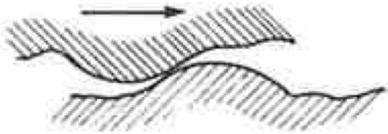
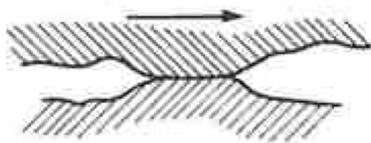


## Adhesive wear process

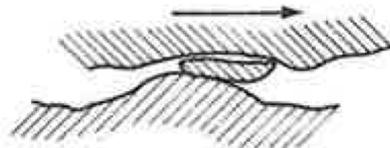
### Assumptions



- Multi-asperity contact



- Plastic or fracture deformations (governed by hardness)



- Real contact area is proportional to the normal load

$$\Delta V = k \frac{L \times s}{H_{soft}}$$

$\Delta V$  is the volume loss due to wear

$L$  is the normal load

$s$  is the sliding distance at constant sliding speed

$H_{soft}$  is the hardness of the softer material

Archard, J. F., "Contact and Rubbing of Flat Surfaces," *Journal of Applied Physics*, Vol. 24, 1953, pp. 981-988.

Holm, R. Reference [3], pp. 242-254.

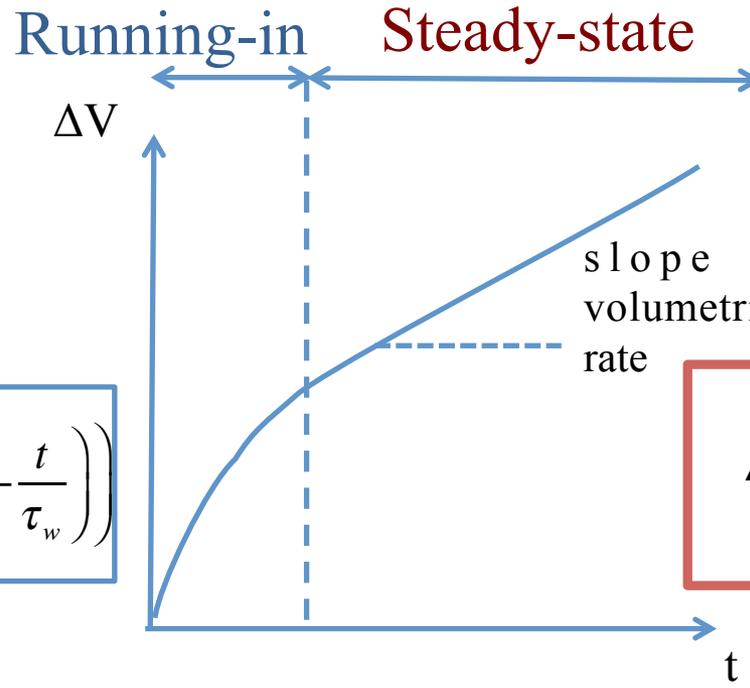
Burwell, J. T., and Strang, C. D., "On the Empirical Law of Adhesive Wear," *Journal of Applied Physics*, Vol. 23, 1953, pp. 18-30.

$\Delta V$  is the wear  
volume

Barwell's law:

$$\Delta V_{\text{running-in}} = w_0 \tau_w \left( 1 - \exp\left(-\frac{t}{\tau_w}\right) \right)$$

F. T. Barwell, Wear 1, 317 (1958).

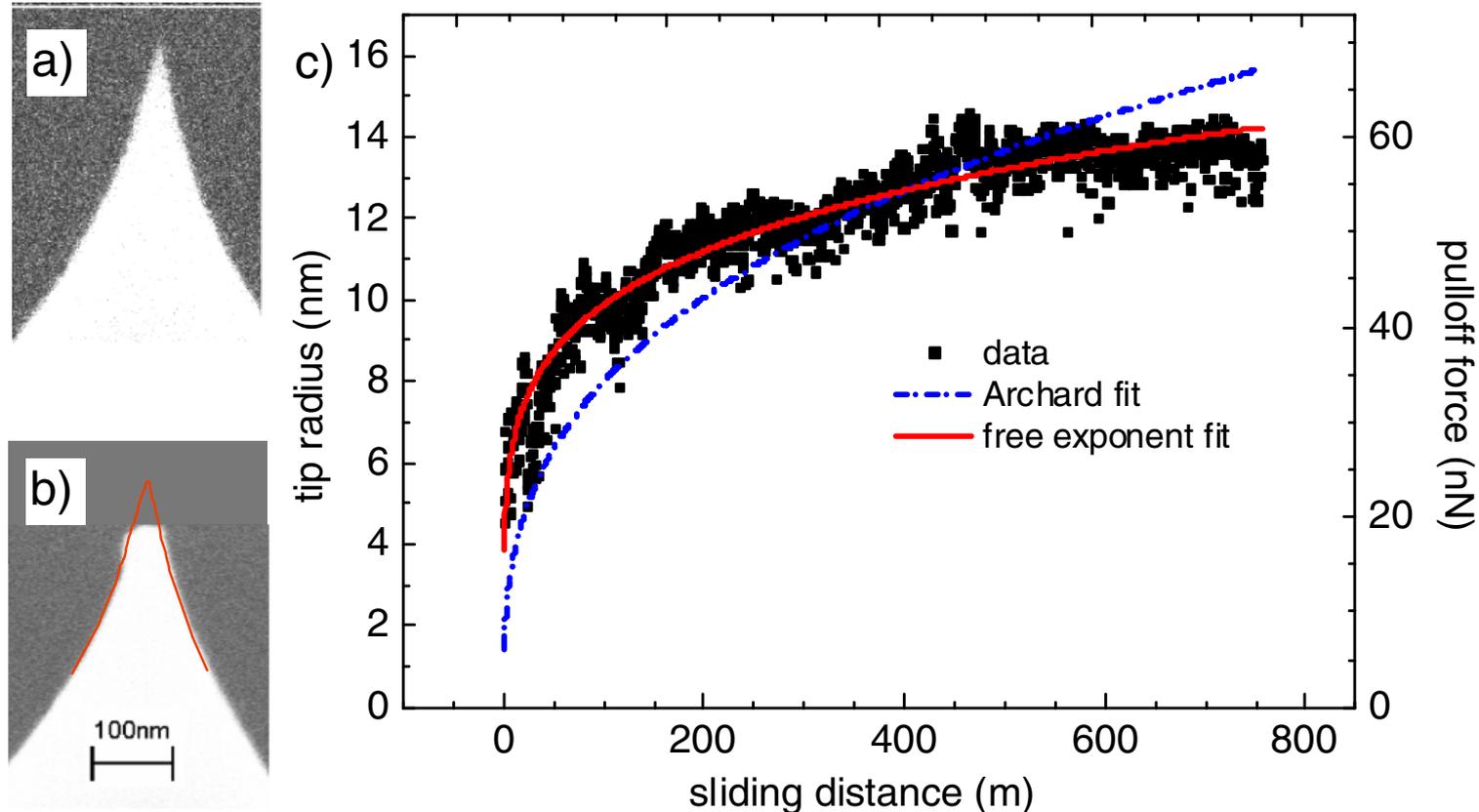


Classical view of  
Archard's law:

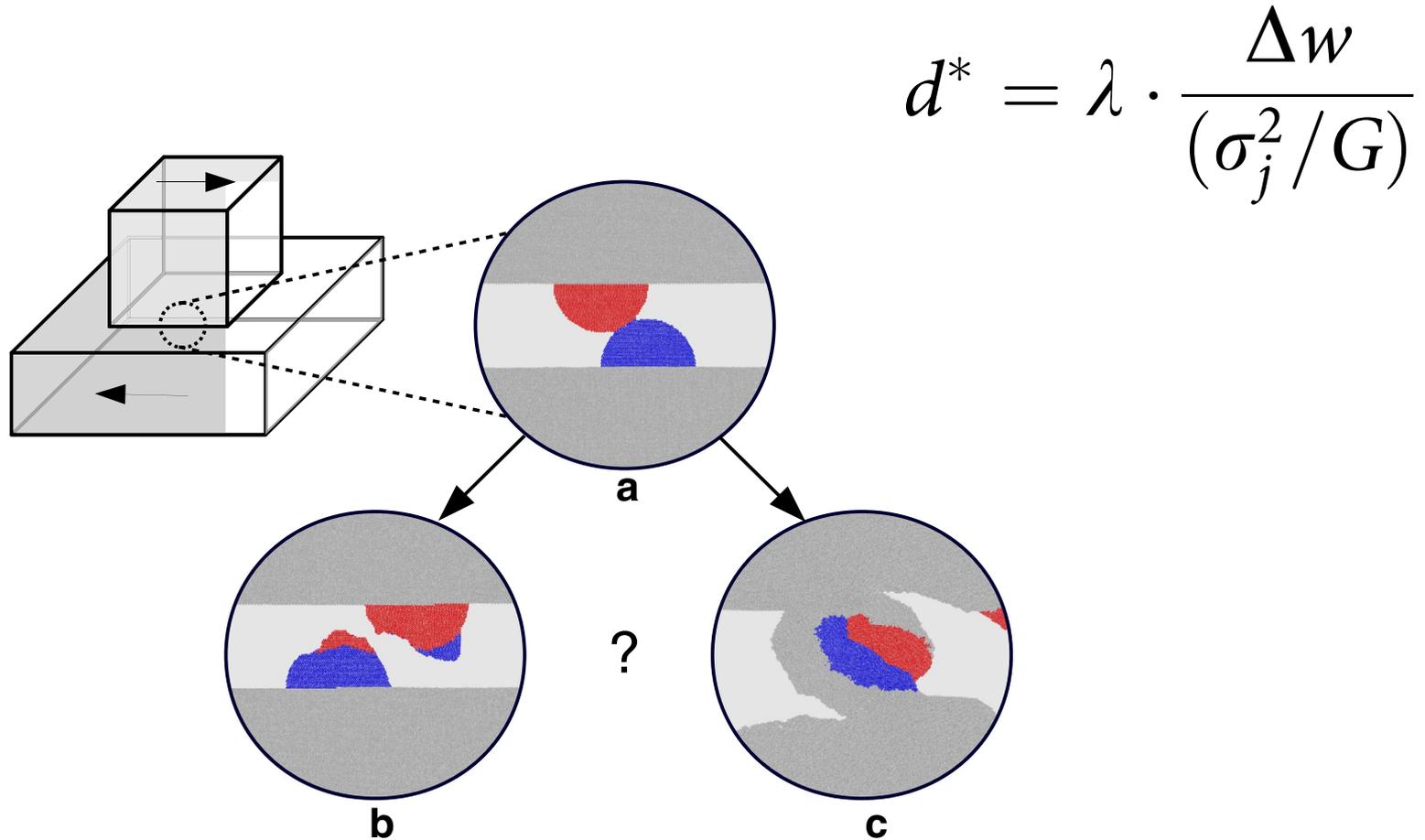
$$\Delta V_{\text{steady-state}} = k \frac{L \times t}{H_{\text{soft}}}$$

In the Archard's law, the wear rate,  $\frac{\Delta V_{\text{steady-state}}}{s}$  is independent of the sliding speed, if the sliding distance,  $s$ , is kept constant.

## Wear of a Silicon *AFM* probe on a polymer surface



“Wear occurs through an atom by atom removal process which implies the breaking of individual bonds”



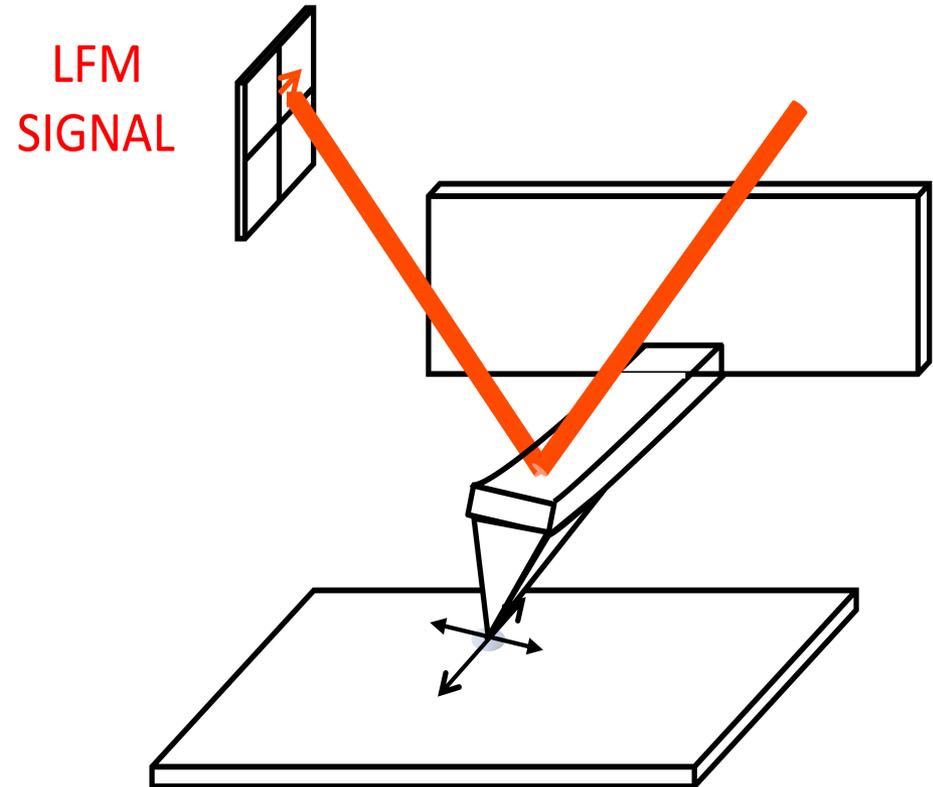
$$d^* = \lambda \cdot \frac{\Delta w}{(\sigma_j^2 / G)}$$

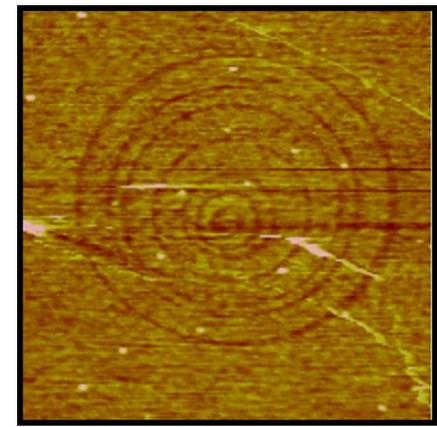
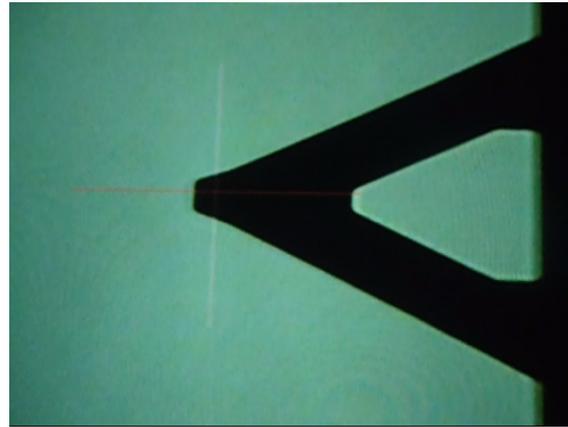
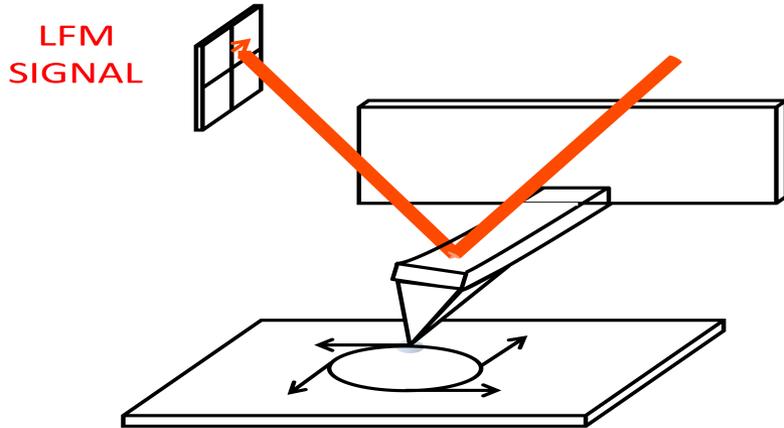
Molinari et al. Nature Communications, 11816, (2016)

- **Main advantage:** - Single asperity contact

- **Limitations:**

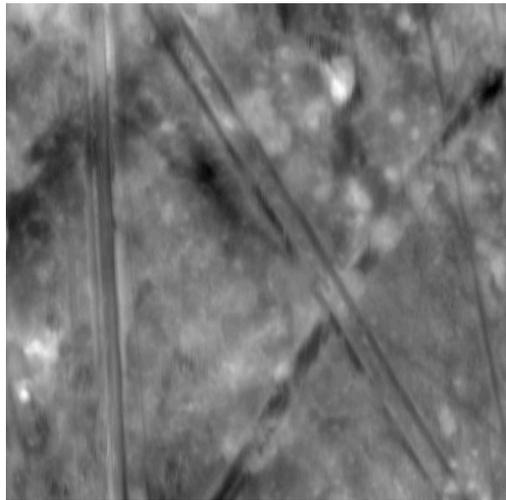
- Non constant and continuous sliding speed
- Low sliding speed (typically max. 100  $\mu\text{m/s}$ )
- Scan drift leads to non well defined wear track



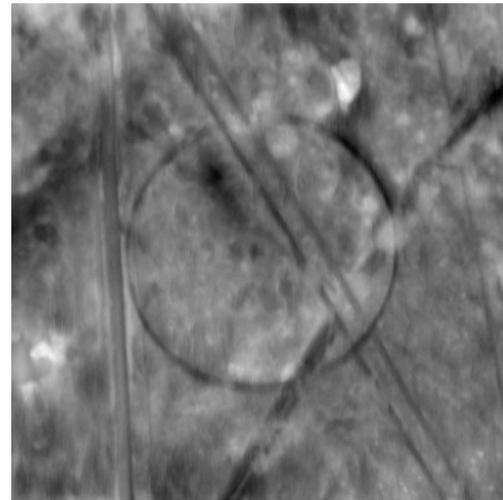


H.Nasrallah, P-E Mazeran, O.Noel. Rev. Sci. Instrum.  
2011, 82, 113703.

	Conventional Mode	CM-AFM
Solicitation velocity	Low scanning or sliding velocity (typically, ranging from 1 $\mu\text{m/s}$ to 100 $\mu\text{m/s}$ )	High sliding velocity (> 6 mm/s)
Advantages / Drawbacks	<i>High scanner drift; Low wear; high shear force when the scan changes its direction</i>	Limiting scanner drift; high wear in a limiting time; well-defined wear track; isotropic wear of the probe if any; anisotropic wear revealed if any; local probing



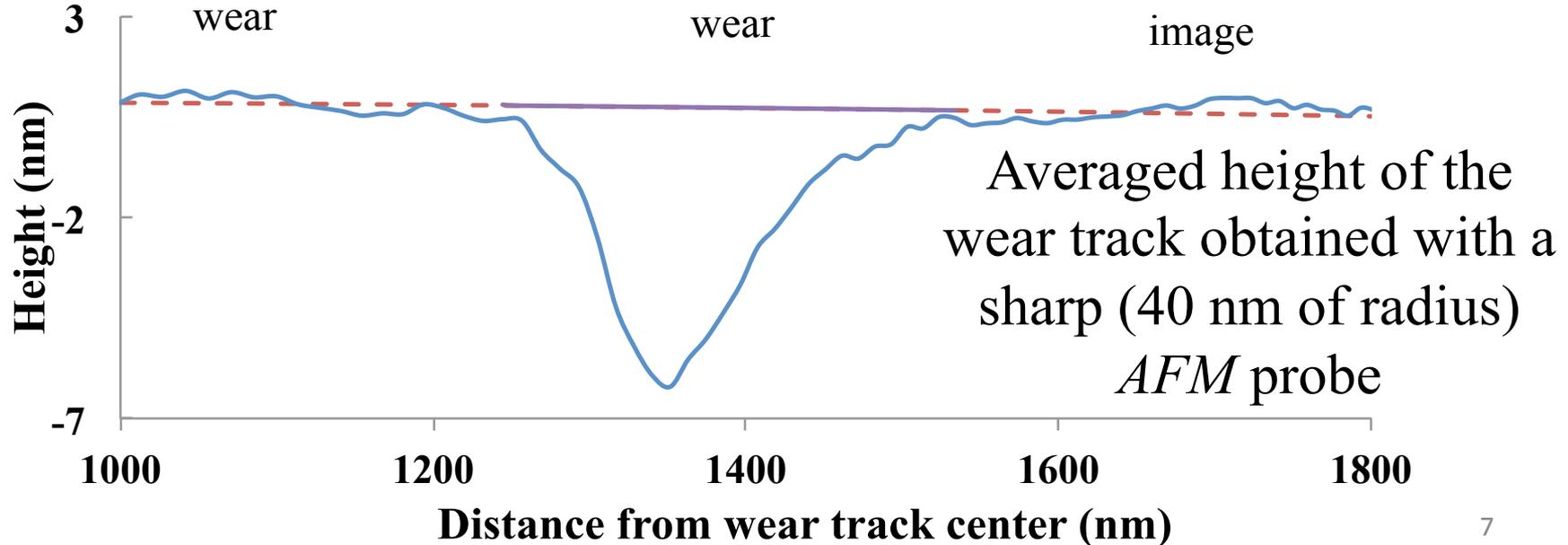
Topography before  
wear



Topography after  
wear



Difference wear  
image



# Comparative analysis of Macro and Nano wear of copper based composite

Trends in  
Nanotribology 2017

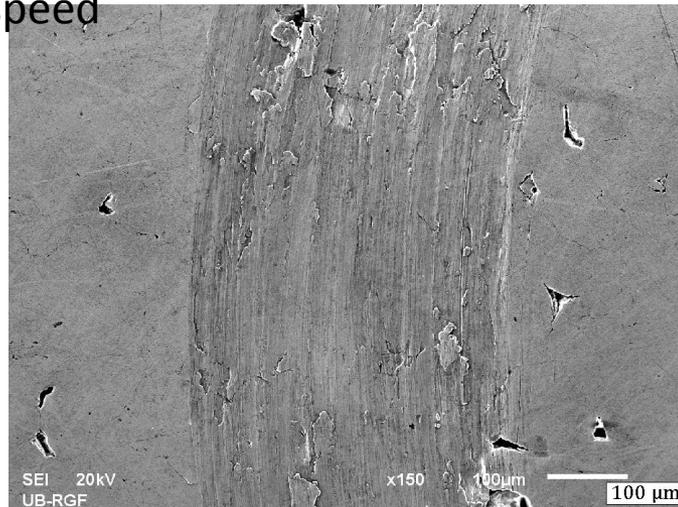
Processing Method: Powder Metallurgy followed by internal oxidation

Designation	Average size particles	Sample roughness Rq	Micro Hardness V <sub>50</sub>
Nano-composite	Less than 100 nm	4.02 nm <i>AFM</i> image 5 μm X 5 μm	224

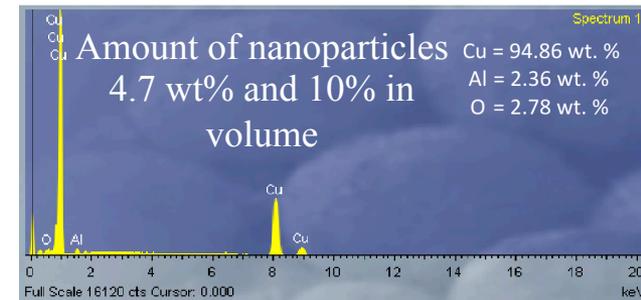
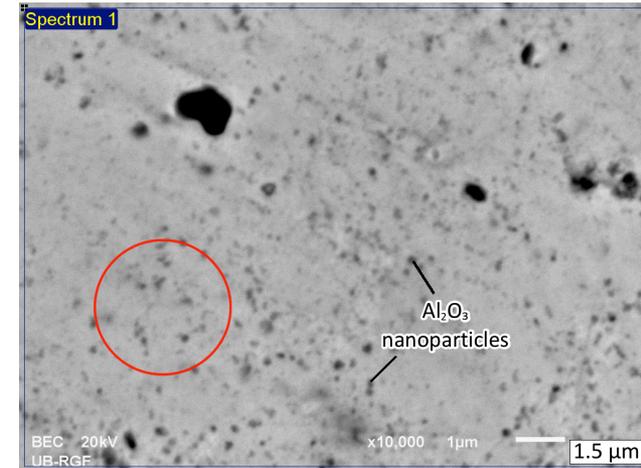
Friction coefficient with steel is 0.13 in the steady-state and is independent of the sliding speed

*SEM* image of wear track after the macro tests (1 N; 8 mm/s)

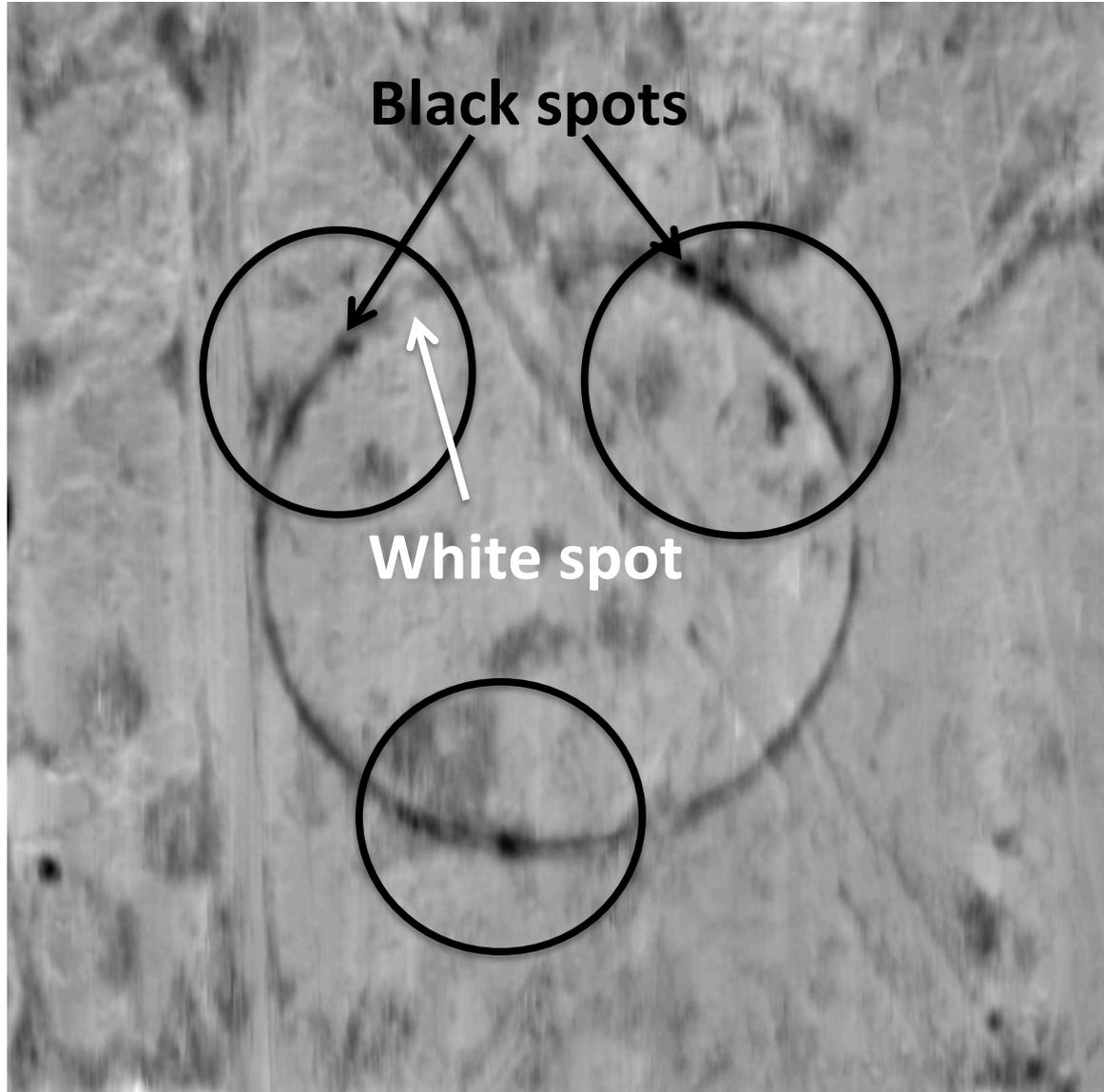
Mostly adhesive and light abrasive wear



*SEM* and *EDX* images



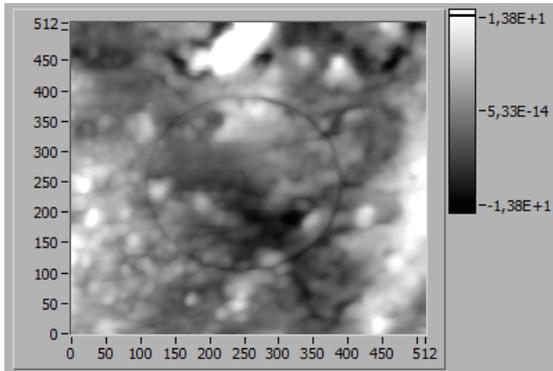
At the macro-scale, wear of the nano-composite follows Archard wear laws <sup>8</sup>



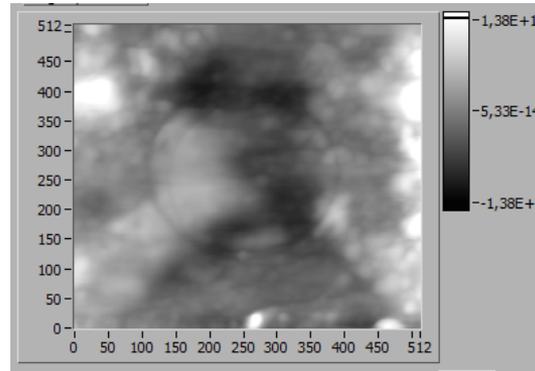
# Wear Volume vs. Sliding Distance (or wear duration)

Trends in  
Nanotribology 2017

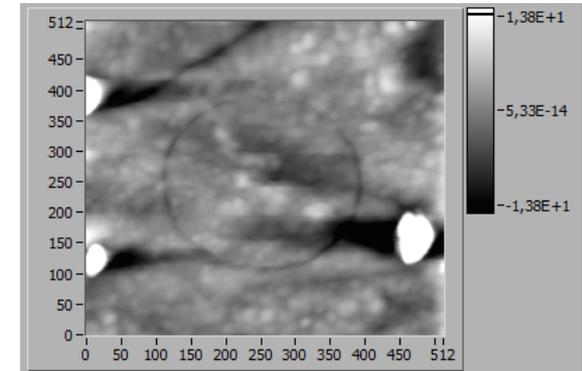
Sliding speed of 0.88 mm/s; Normal load =  $3\mu\text{N}$ ; Diamond Probe



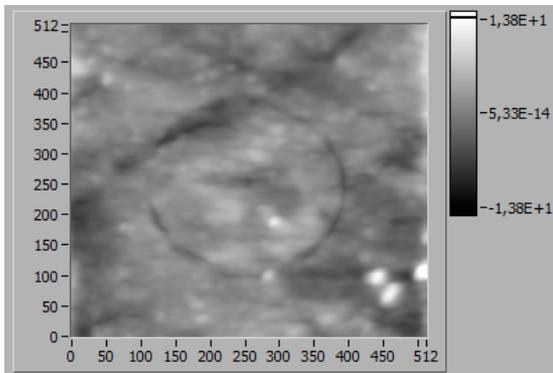
$t = 1$  min.



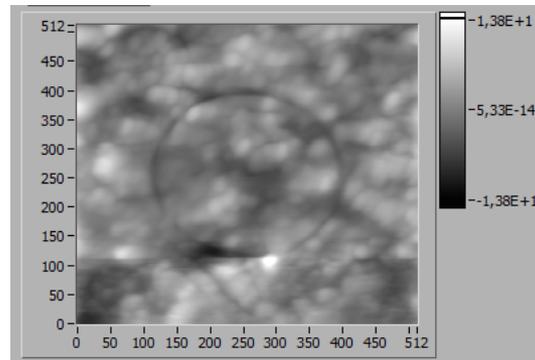
$t = 2$  min.



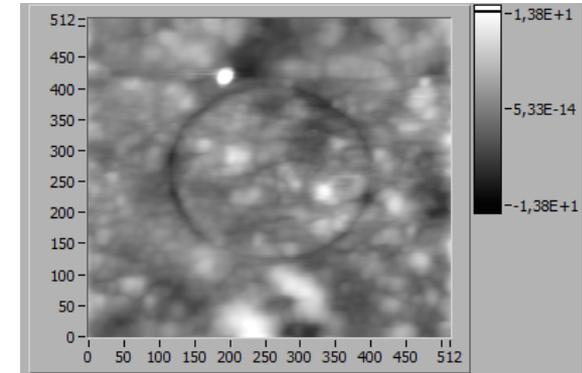
$t = 4$  min.



$t = 8$  min.

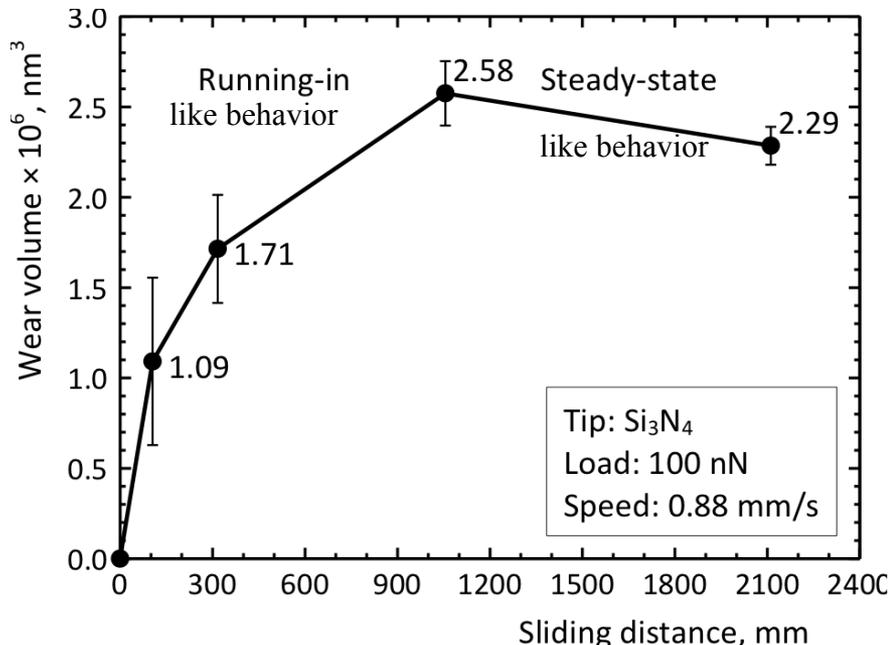


$t = 16$  min.

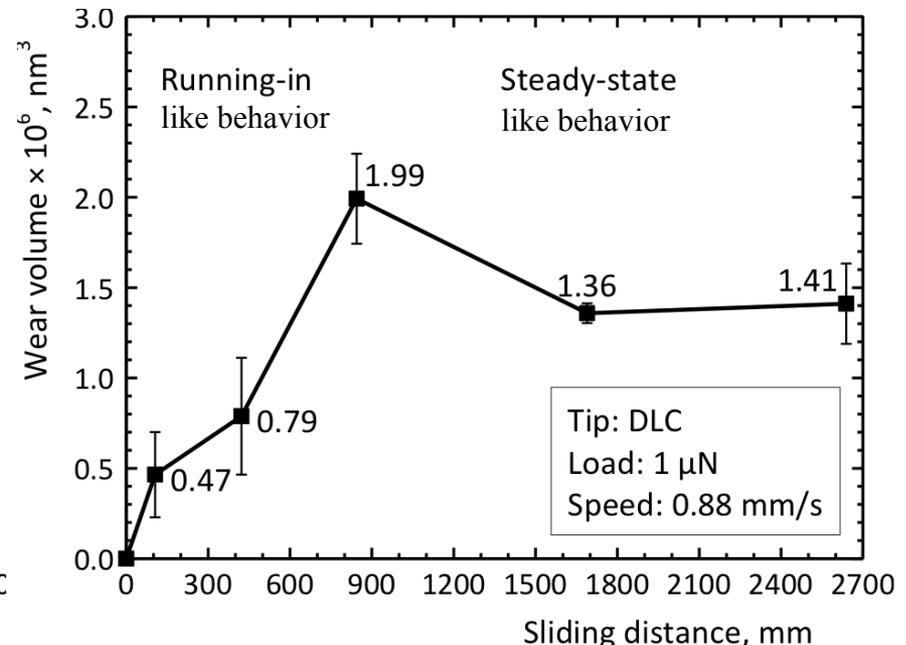


$t = 32$  min.

$\text{Si}_3\text{N}_4$  Probe radius: 100 nm



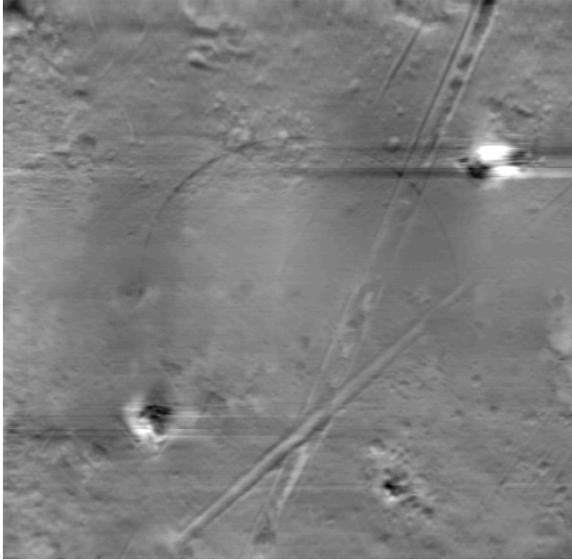
DLC Probe radius: 200 nm



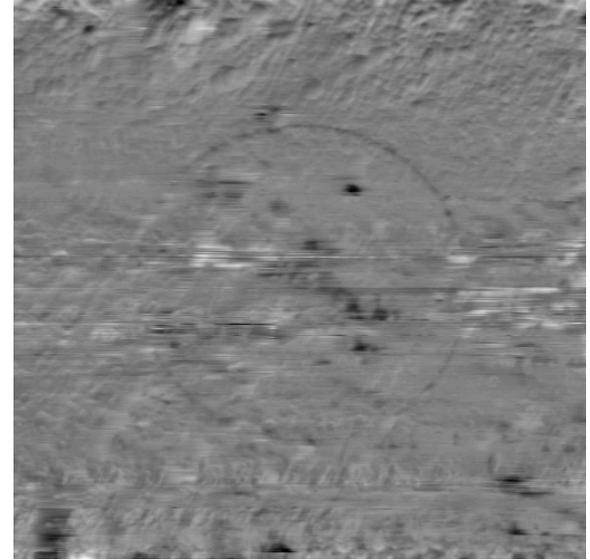
- *SEM* images do not evidence wear of the probes (counter body).
- In both cases, we have an asymptotic steady-state

# Wear volume vs. Normal Load

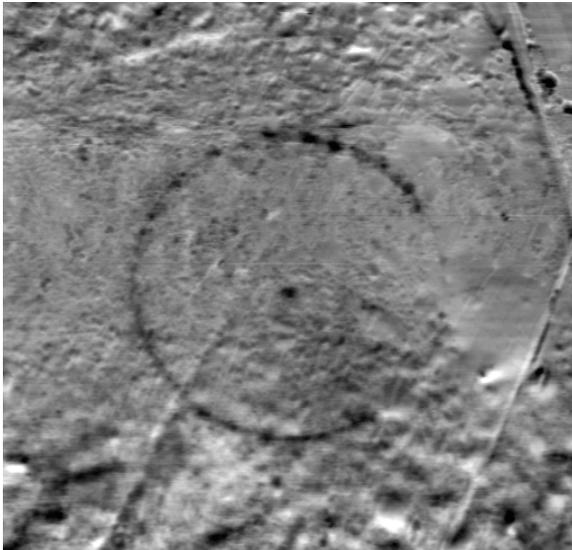
70 nN



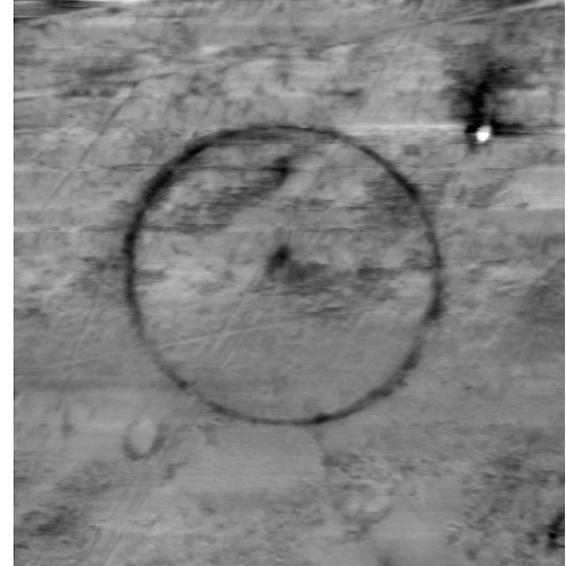
100 nN



140 nN

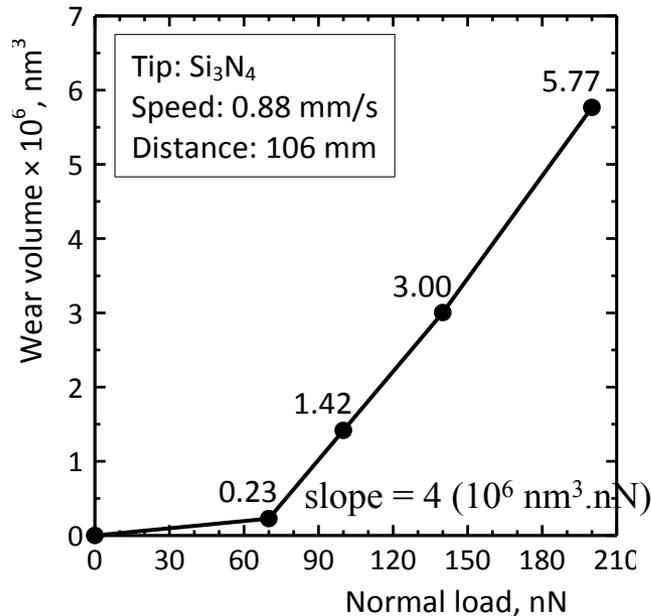


200 nN

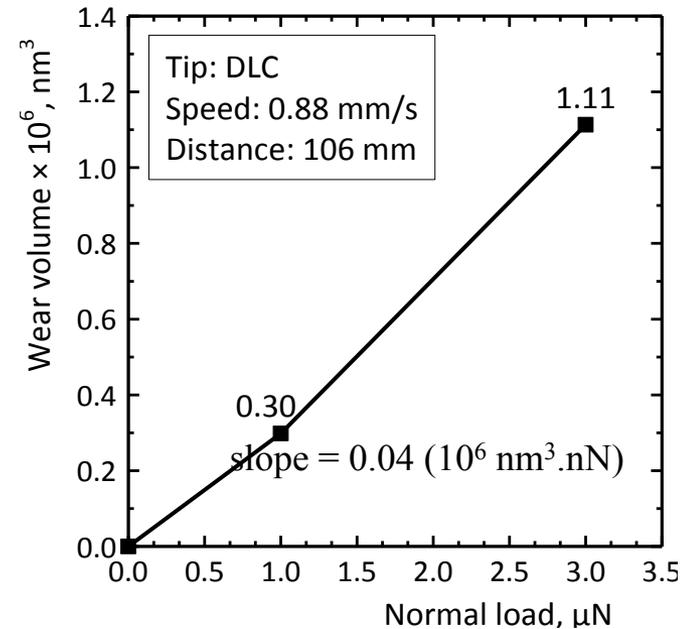


Experiments performed in the **running-in-like regime** if we refer to a macroscopic view of wear

$\text{Si}_3\text{N}_4$  probe radius: 100 nm



*DLC* probe radius: 200 nm



- Archard-like wear law is obtained.
- Wear depends on the nature of the counter-body.
- For  $\text{Si}_3\text{N}_4$  there is a critical threshold load (about 60 nN) from which wear loss is significant.
- If we consider a single asperity contact, this latter behavior is governed by the lateral force which is proportional to the normal load. Eder et al., PRL, 115, 025502 (2015)

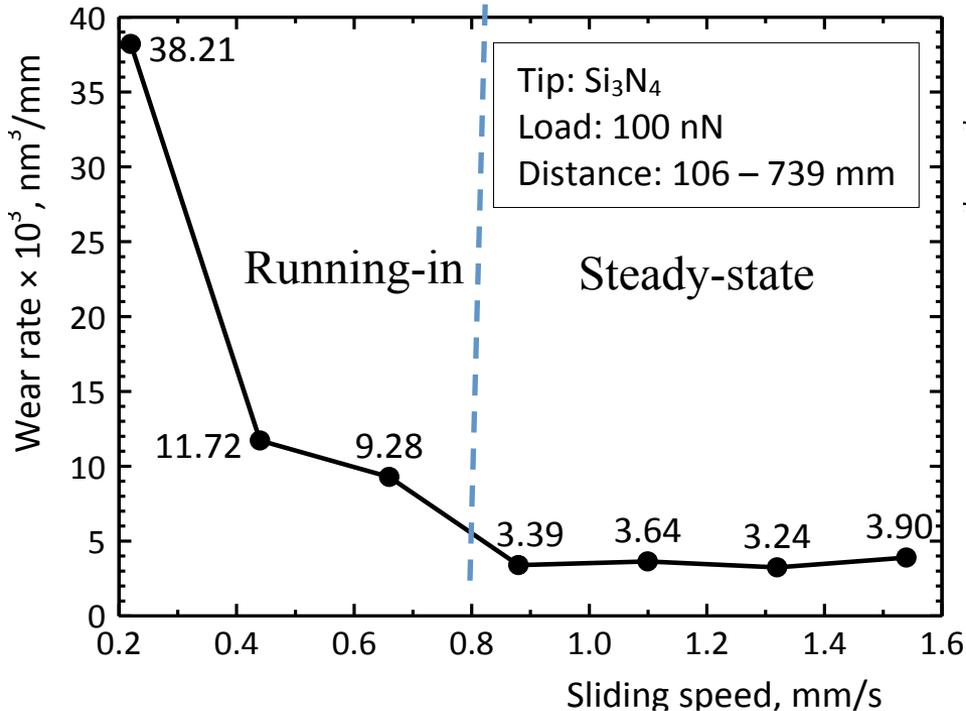
- For a probe radius,  $R = 100$  nm, and a normal load,  $L = 60$  nN (threshold value for SiN probe), the contact radius (Hertz model),  $a$ , is:

$$a = 4 \text{ nm}$$

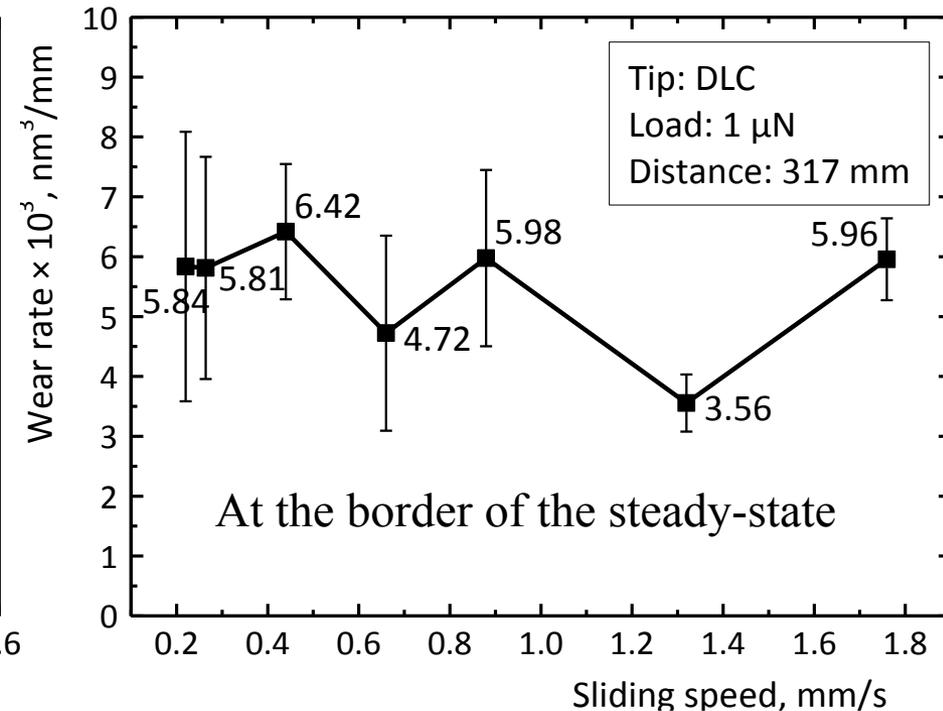
and the contact pressure is  $1.20 \text{ GPa} < H$  of sample  $2.45 \text{ GPa}$  (Hardness of copper oxide is  $4\text{-}5 \text{ GPa}$ ).

- According to the Hertz theory, the shear stress is maximum at a depth of  $0.78 a = 3$  nm. This depth corresponds to the thickness of oxide copper growths in ambient conditions.
- Therefore,  $60$  nN corresponds exactly to the normal load that generates a maximum shear stress at a depth of  $3$  nm.
- The threshold value may correspond to the minimum load to apply to shear the interface of the oxide/metal interface.

$\text{Si}_3\text{N}_4$  Probe radius: 100 nm



DLC Probe radius: 200 nm



- Wear rate is independent of the sliding speed (for a given sliding distance et a given normal load) in the steady-state (from the macroscopic view) regime.

- The methodology based on the CM-AFM gives well-defined wear tracks as the drift of the scanner is limited and the wear loss is significant.
- Well defined wear tracks allows measuring quantitative values.
- Nano-wear heterogeneity is revealed.

## Nano-wear of nano-composite,

- Archard-like wear laws are revealed at the nanoscale but it does not mean we have the same mechanisms involved as for the macroscale
- Wear process may be not governed by the hardness but by the lateral force (or shear stress) and by the physico-chemical interactions in the contact (depending on the nature of the counter-body)
- Can we still think in the same way as for the macroscopic view (running-in, steady-state...)?

