

# Message Passing Programming with MPI

# What is MPI?

- ❑ First message-passing interface standard.
- ❑ Sixty people from forty different organisations.
- ❑ Users and vendors represented, from the US and Europe.
- ❑ Two-year process of proposals, meetings and review.
- ❑ *Message Passing Interface* document produced.

- ❑ MPI's prime goals are:

  - To provide source-code portability.

  - To allow efficient implementation.

- ❑ It also offers:

  - A great deal of functionality.

  - Support for heterogeneous parallel architectures.

- ❑ C:  
`#include <mpi.h>`
- ❑ Fortran:  
`include 'mpif.h'`

□ C:

```
error = MPI_Xxxxx(parameter, ...);
```

```
MPI_Xxxxx(parameter, ...);
```

□ Fortran:

```
CALL MPI_XXXXX(parameter, ..., IERROR)
```

- ❑ MPI controls its own internal data structures.
- ❑ MPI releases `handles' to allow programmers to refer to these.
- ❑ C handles are of defined **typedefs**.
- ❑ Fortran handles are **INTEGERS**.

- C:

```
int MPI_Init(int *argc, char ***argv)
```

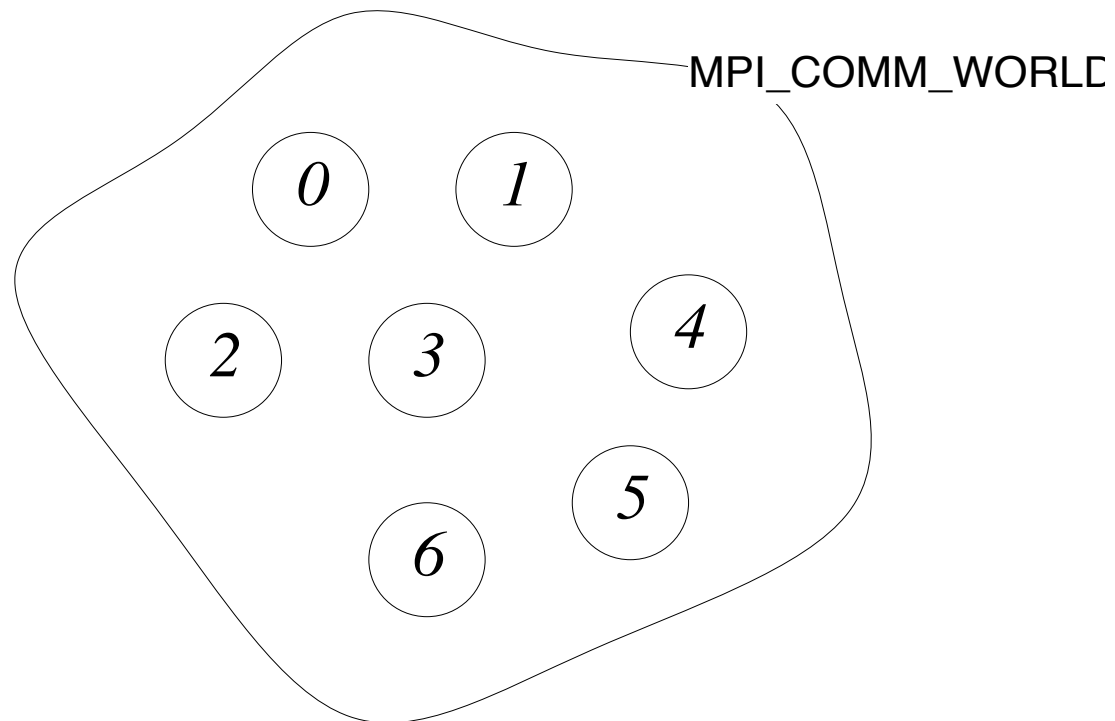
- Fortran:

```
MPI_INIT(IERROR)  
INTEGER IERROR
```

- Must be the first MPI procedure called.



## Communicators



- ❑ How do you identify different processes in a communicator?

```
MPI_Comm_rank(MPI_Comm comm, int *rank)
```

```
MPI_COMM_RANK(COMM, RANK, IERROR)  
INTEGER COMM, RANK, IERROR
```

- ❑ The rank is not the PE number.

- How many processes are contained within a communicator?

```
MPI_Comm_size(MPI_Comm comm, int *size)
```

```
MPI_COMM_SIZE(COMM, SIZE, IERROR)  
INTEGER COMM, SIZE, IERROR
```

- C:

```
int MPI_Finalize()
```

- Fortran:

```
MPI_FINALIZE(IERROR)  
INTEGER IERROR
```

- Must be the last MPI procedure called.

# Messages

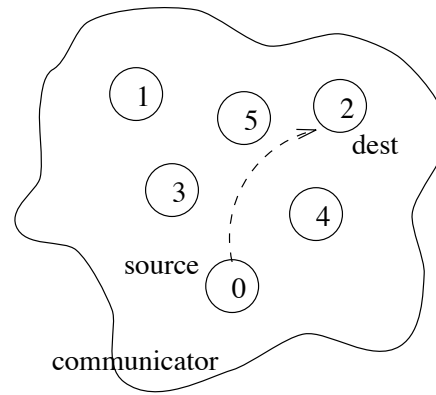
- ❑ A message contains a number of elements of some particular datatype.
- ❑ MPI datatypes:
  - Basic types.
  - Derived types.
- ❑ Derived types can be built up from basic types.
- ❑ C types are different from Fortran types.

MPI Datatype	C datatype
<code>MPI_CHAR</code>	<code>signed char</code>
<code>MPI_SHORT</code>	<code>signed short int</code>
<code>MPI_INT</code>	<code>signed int</code>
<code>MPI_LONG</code>	<code>signed long int</code>
<code>MPI_UNSIGNED_CHAR</code>	<code>unsigned char</code>
<code>MPI_UNSIGNED_SHORT</code>	<code>unsigned short int</code>
<code>MPI_UNSIGNED</code>	<code>unsigned int</code>
<code>MPI_UNSIGNED_LONG</code>	<code>unsigned long int</code>
<code>MPI_FLOAT</code>	<code>float</code>
<code>MPI_DOUBLE</code>	<code>double</code>
<code>MPI_LONG_DOUBLE</code>	<code>long double</code>
<code>MPI_BYTE</code>	
<code>MPI_PACKED</code>	

<b>MPI Datatype</b>	<b>Fortran Datatype</b>
<b>MPI_INTEGER</b>	<b>INTEGER</b>
<b>MPI_REAL</b>	<b>REAL</b>
<b>MPI_DOUBLE_PRECISION</b>	<b>DOUBLE PRECISION</b>
<b>MPI_COMPLEX</b>	<b>COMPLEX</b>
<b>MPI_LOGICAL</b>	<b>LOGICAL</b>
<b>MPI_CHARACTER</b>	<b>CHARACTER(1)</b>
<b>MPI_BYTE</b>	
<b>MPI_PACKED</b>	



# Point-to-Point Communication



- ❑ Communication between two processes.
- ❑ Source process sends message to destination process.
- ❑ Communication takes place within a communicator.
- ❑ Destination process is identified by its rank in the communicator.

## □ C:

```
int MPI_Send(void *buf, int count,  
             MPI_Datatype datatype,  
             int dest, int tag,  
             MPI_Comm comm)
```

## □ Fortran:

```
MPI_SEND(BUF, COUNT, DATATYPE, DEST,  
         TAG, COMM, IERROR)  
<type> BUF(*)  
INTEGER COUNT, DATATYPE, DEST, TAG  
INTEGER COMM, IERROR
```

## □ C:

```
int MPI_Recv(void *buf, int count,  
            MPI_Datatype datatype,  
            int source, int tag,  
            MPI_Comm comm, MPI_Status *status)
```

## □ Fortran:

```
MPI_RECV(BUF, COUNT, DATATYPE, SOURCE,  
         TAG, COMM, STATUS, IERROR)  
<type> BUF(*)  
INTEGER COUNT, DATATYPE, SOURCE, TAG, COMM,  
         STATUS(MPI_STATUS_SIZE), IERROR
```

- ❑ Processes synchronise.
- ❑ Sender process specifies the synchronous mode.
- ❑ Blocking – both processes wait until the transaction has completed.

- Sender must specify a valid destination rank.
- Receiver must specify a valid source rank.
- The communicator must be the same.
- Tags must match.
- Message types must match.
- Receiver's buffer must be large enough.

- ❑ Receiver can wildcard.
- ❑ To receive from any source – **MPI\_ANY\_SOURCE**
- ❑ To receive with any tag – **MPI\_ANY\_TAG**
- ❑ Actual source and tag are returned in the receiver's **status** parameter.

- ❑ Envelope information is returned from **MPI\_RECV** as **status**
- ❑ Information includes:

**Source:** `status.MPI_SOURCE` or  
`status(MPI_SOURCE)`

**Tag:** `status.MPI_TAG` or `status(MPI_TAG)`

**Count:** `MPI_Get_count` or `MPI_GET_COUNT`

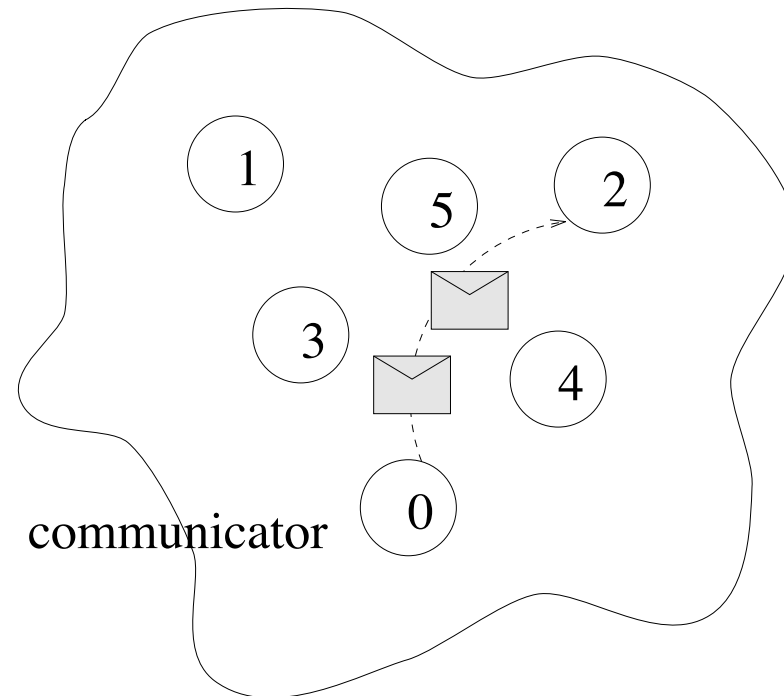


## □ C:

```
int MPI_Get_count(MPI_Status *status,  
                 MPI_Datatype datatype,  
                 int *count)
```

## □ Fortran:

```
MPI_GET_COUNT(STATUS, DATATYPE, COUNT,  
              IERROR)  
INTEGER STATUS(MPI_STATUS_SIZE), DATATYPE,  
          COUNT, IERROR
```



- ❑ Messages do not overtake each other.
- ❑ This is true even for non-synchronous sends.

- ❑ C:

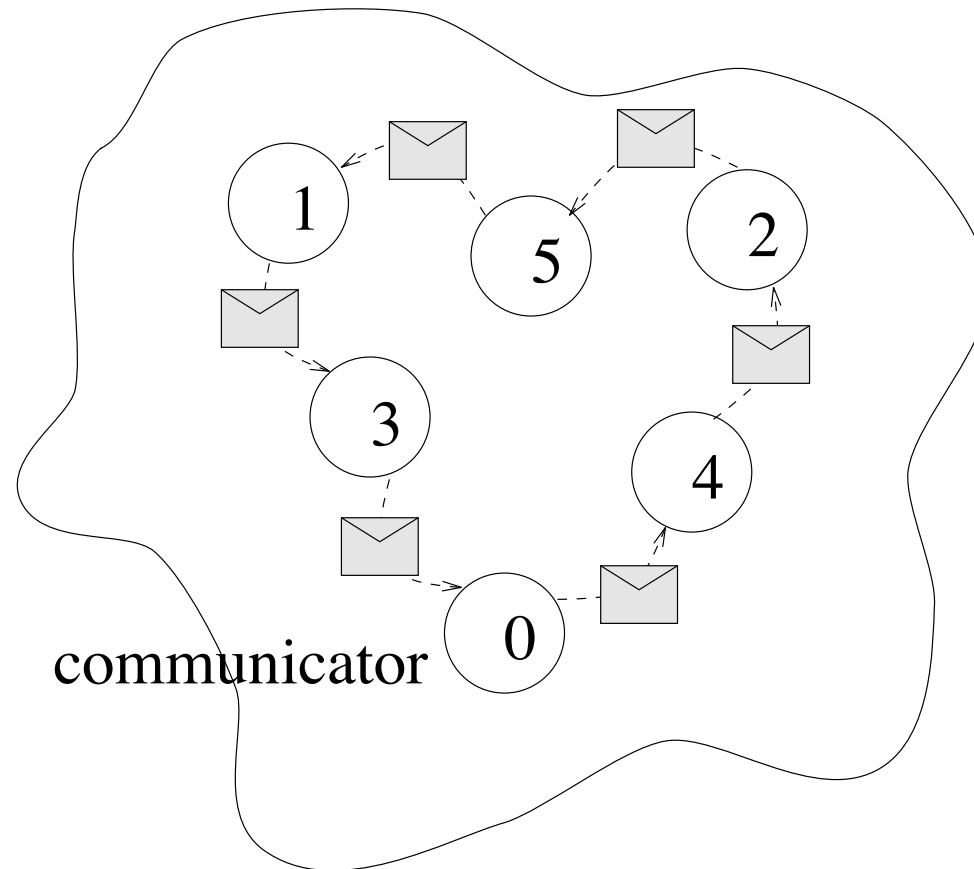
```
double MPI_Wtime(void);
```

- ❑ Fortran:

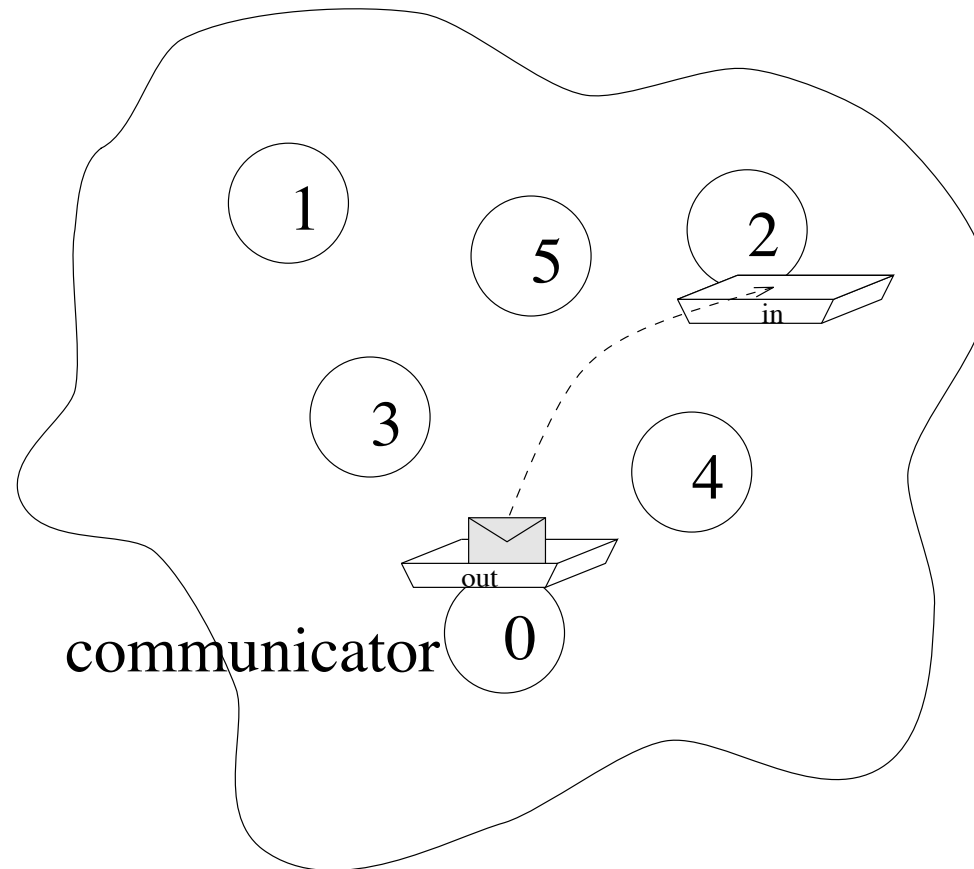
```
DOUBLE PRECISION MPI_WTIME()
```

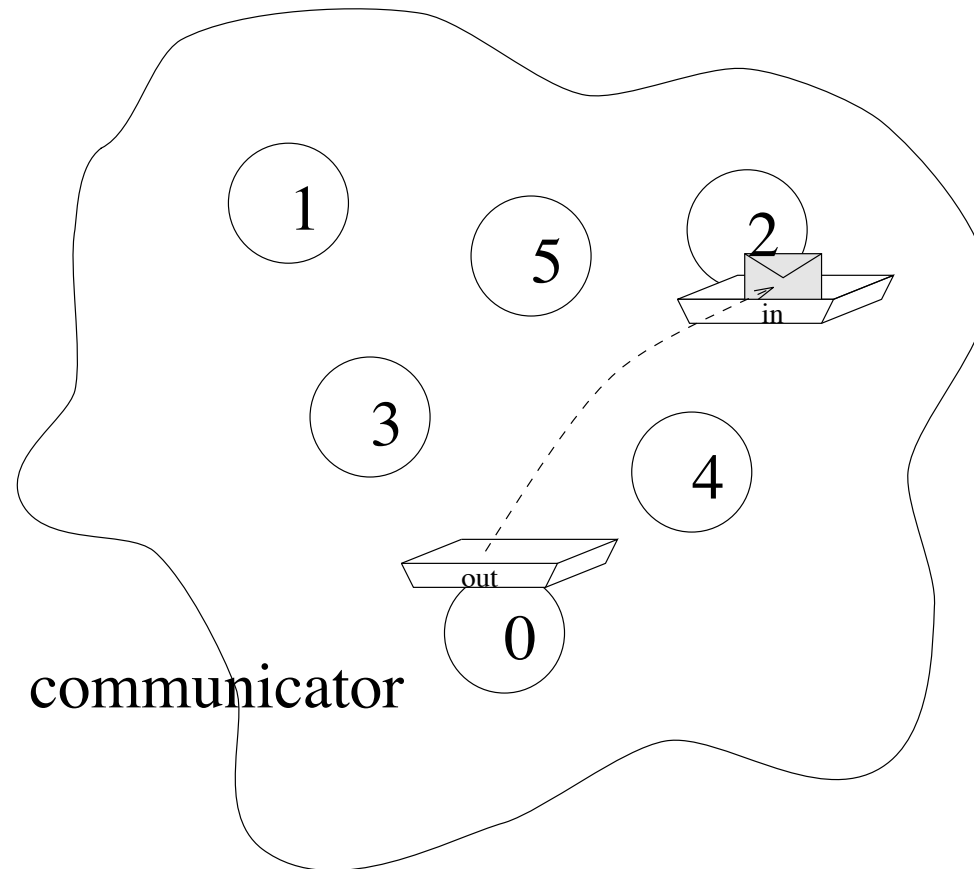
- ❑ Time is measured in seconds.
- ❑ Time to perform a task is measured by consulting the timer before and after.
- ❑ Modify your program to measure its execution time and print it out.

# Non-Blocking Communications



- ❑ Separate communication into three phases:
- ❑ Initiate non-blocking communication.
- ❑ Do some work (perhaps involving other communications?)
- ❑ Wait for non-blocking communication to complete.







- ❑ datatype – same as for blocking (**MPI\_Datatype** or **INTEGER**).
- ❑ communicator – same as for blocking (**MPI\_Comm** or **INTEGER**).
- ❑ request – **MPI\_Request** or **INTEGER**.
- ❑ *A request handle* is allocated when a communication is initiated.

## □ C:

```
int MPI_Isend(void* buf, int count,  
             MPI_Datatype datatype, int dest,  
             int tag, MPI_Comm comm,  
             MPI_Request *request)
```

```
int MPI_Wait(MPI_Request *request,  
            MPI_Status *status)
```

## □ Fortran:

```
MPI_ISEND(buf, count, datatype, dest,  
         tag, comm, request, ierror)
```

```
MPI_WAIT(request, status, ierror)
```

## □ C:

```
int MPI_Irecv(void* buf, int count,  
             MPI_Datatype datatype, int src,  
             int tag, MPI_Comm comm,  
             MPI_Request *request)
```

```
int MPI_Wait(MPI_Request *request,  
            MPI_Status *status)
```

## □ Fortran:

```
MPI_IRecv(buf, count, datatype, src,  
         tag, comm, request, ierror)
```

```
MPI_WAIT(request, status, ierror)
```

- ❑ Send and receive can be blocking or non-blocking.
- ❑ A blocking send can be used with a non-blocking receive, and vice-versa.
- ❑ Non-blocking sends can use any mode - synchronous, buffered, standard, or ready.
- ❑ Synchronous mode affects completion, not initiation.

- ❑ Waiting versus Testing.

- ❑ C:

```
int MPI_Wait(MPI_Request *request,  
             MPI_Status *status)  
int MPI_Test(MPI_Request *request,  
             int *flag,  
             MPI_Status *status)
```

- ❑ Fortran:

```
MPI_WAIT(handle, status, ierror)  
  
MPI_TEST(handle, flag, status, ierror)
```

- Test or wait for completion of one message.
- Test or wait for completion of all messages.
- Test or wait for completion of as many messages as possible.

- Basic types
- Derived types
  - vectors
  - structs
  - others

basic datatype 0	displacement of datatype 0
basic datatype 1	displacement of datatype 1
...	...
basic datatype n-1	displacement of datatype n-1



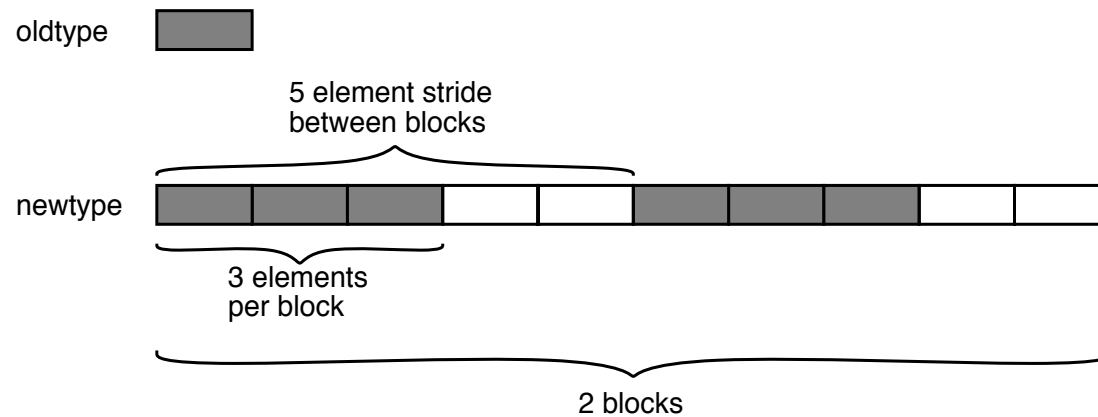
- ❑ The simplest derived datatype consists of a number of contiguous items of the same datatype.
- ❑ C:

```
int MPI_Type_contiguous(int count,  
MPI_Datatype oldtype, MPI_Datatype *newtype)
```

- ❑ Fortran:

```
MPI_TYPE_CONTIGUOUS(COUNT, OLDTYPE, NEWTYPE,  
IERROR)  
INTEGER COUNT, OLDTYPE, NEWTYPE, IERROR
```

## A 3X2 block of a 5X5 Fortran array



- ❑ `count = 2`
- ❑ `stride = 5`
- ❑ `blocklength = 3`

## □ C:

```
int MPI_Type_vector (int count,  
                    int blocklength, int stride,  
                    MPI_Datatype oldtype,  
                    MPI_Datatype *newtype)
```

## □ Fortran:

```
MPI_TYPE_VECTOR (COUNT, BLOCKLENGTH,  
                STRIDE, OLDTYPE, NEWTYPE, IERROR)
```

## □ C:

```
int MPI_Type_extent (MPI_Datatype datatype,  
                    MPI_Aint *extent)
```

## □ Fortran:

```
MPI_TYPE_EXTENT( DATATYPE, EXTENT,  
                IERROR)  
INTEGER DATATYPE, EXTENT, IERROR
```

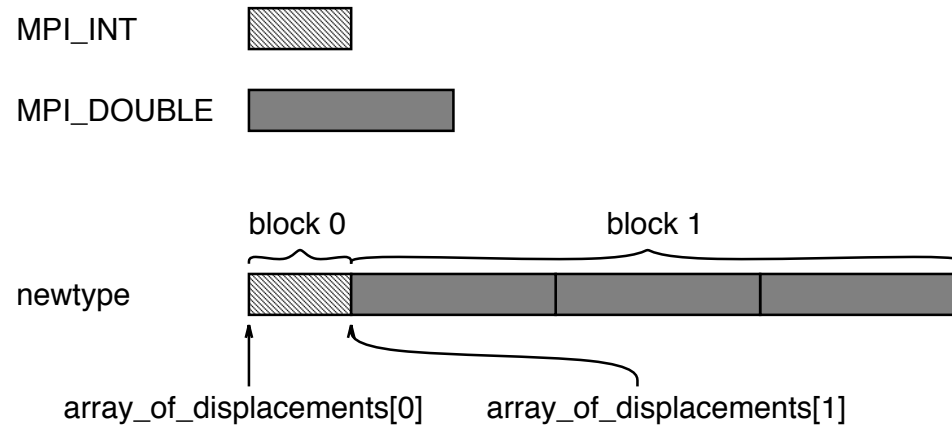
- C:

```
int MPI_Address (void *location, MPI_Aint
                *address)
```

- Fortran:

```
MPI_ADDRESS( LOCATION, ADDRESS, IERROR)
```

```
<type> LOCATION (*)
INTEGER ADDRESS, IERROR
```



- ❑ **count = 2**
- ❑ **array\_of\_blocklengths[0] = 1**
- ❑ **array\_of\_types[0] = MPI\_INT**
- ❑ **array\_of\_blocklengths[1] = 3**
- ❑ **array\_of\_types[1] = MPI\_DOUBLE**

## □ C:

```
int MPI_Type_struct (int count,  
                    int *array_of_blocklengths,  
                    MPI_Aint *array_of_displacements,  
                    MPI_Datatype *array_of_types,  
                    MPI_Datatype *newtype)
```

## □ Fortran:

```
MPI_TYPE_STRUCT (COUNT,  
                ARRAY_OF_BLOCKLENGTHS,  
                ARRAY_OF_DISPLACEMENTS,  
                ARRAY_OF_TYPES, NEWTYPE, IERROR)
```

- ❑ Once a datatype has been constructed, it needs to be committed before it is used.
- ❑ This is done using **MPI\_TYPE\_COMMIT**

- ❑ C:

```
int MPI_Type_commit (MPI_Datatype *datatype)
```

- ❑ Fortran:

```
MPI_TYPE_COMMIT (DATATYPE, IERROR)  
INTEGER DATATYPE, IERROR
```

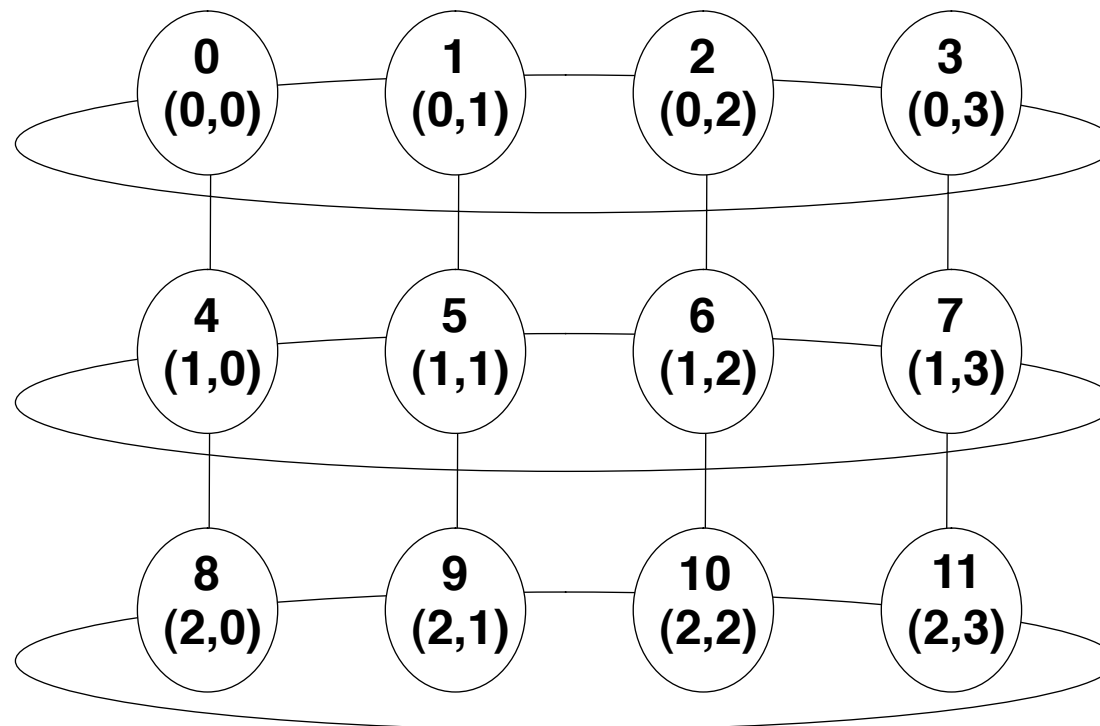


# Virtual Topologies

- ❑ Convenient process naming.
- ❑ Naming scheme to fit the communication pattern.
- ❑ Simplifies writing of code.
- ❑ Can allow MPI to optimise communications.

- ❑ Creating a topology produces a new communicator.
- ❑ MPI provides “mapping functions”.
- ❑ Mapping functions compute processor ranks, based on the topology naming scheme.

## A 2-dimensional Cylinder



- Cartesian topologies

  - each process is “connected” to its neighbours in a virtual grid.

  - boundaries can be cyclic, or not.

  - processes are identified by cartesian coordinates.

- Graph topologies

  - general graphs

  - not covered here

## □ C:

```
int MPI_Cart_create(MPI_Comm comm_old,  
                   int ndims, int *dims, int *periods,  
                   int reorder, MPI_Comm *comm_cart)
```

## □ Fortran:

```
MPI_CART_CREATE(COMM_OLD, NDIMS, DIMS,  
                PERIODS, REORDER, COMM_CART, IERROR)  
  
INTEGER COMM_OLD, NDIMS, DIMS(*), COMM_CART,  
        IERROR  
LOGICAL PERIODS(*), REORDER
```

## □ C:

```
int MPI_Dims_create(int nnodes, int ndims,  
                   int *dims)
```

## □ Fortran:

```
MPI_DIMS_CREATE(NNODES, NDIMS, DIMS, IERROR)  
  
INTEGER NNODES, NDIMS, DIMS(*), IERROR
```

- Call tries to set dimensions as close to each other as possible.

dims before the call	function call	dims on return
(0, 0)	MPI_DIMS_CREATE( 6, 2, dims)	(3, 2)
(0, 0)	MPI_DIMS_CREATE( 7, 2, dims)	(7, 1)
(0, 3, 0)	MPI_DIMS_CREATE( 6, 3, dims)	(2, 3, 1)
(0, 3, 0)	MPI_DIMS_CREATE( 7, 3, dims)	erroneous call

- Non zero values in dims sets the number of processors required in that direction.

**WARNING:- make sure dims is set to 0 before the call!**



## Mapping process grid coordinates to ranks

## □ C:

```
int MPI_Cart_rank(MPI_Comm comm,  
                  int *coords, int *rank)
```

## □ Fortran:

```
MPI_CART_RANK (COMM, COORDS, RANK, IERROR)
```

```
INTEGER COMM, COORDS(*), RANK, IERROR
```

## Mapping ranks to process grid coordinates

## □ C:

```
int MPI_Cart_coords(MPI_Comm comm, int rank,  
                   int maxdims, int *coords)
```

## □ Fortran:

```
MPI_CART_COORDS(COMM, RANK, MAXDIMS,  
                COORDS, IERROR)
```

```
INTEGER COMM, RANK, MAXDIMS, COORDS(*),  
        IERROR
```

## Computing ranks of neighbouring processes

□ C:

```
int MPI_Cart_shift(MPI_Comm comm,  
                  int direction, int disp,  
                  int *rank_source, int *rank_dest)
```

□ Fortran:

```
MPI_CART_SHIFT(COMM, DIRECTION, DISP,  
              RANK_SOURCE, RANK_DEST, IERROR)
```

```
INTEGER COMM, DIRECTION, DISP, RANK_SOURCE,  
        RANK_DEST, IERROR
```

# Collective Communications

# epcc | Collective Communication

- ❑ Communications involving a group of processes.
- ❑ Called by all processes in a communicator.
- ❑ Examples:
  - Barrier synchronisation.
  - Broadcast, scatter, gather.
  - Global sum, global maximum, etc.

- ❑ Collective action over a communicator.
- ❑ All processes must communicate.
- ❑ Synchronisation may or may not occur.
- ❑ All collective operations are blocking.
- ❑ No tags.
- ❑ Receive buffers must be exactly the right size.

□ C:

```
int MPI_Barrier (MPI_Comm comm)
```

□ Fortran:

```
MPI_BARRIER (COMM, IERROR)  
INTEGER COMM, IERROR
```

## □ C:

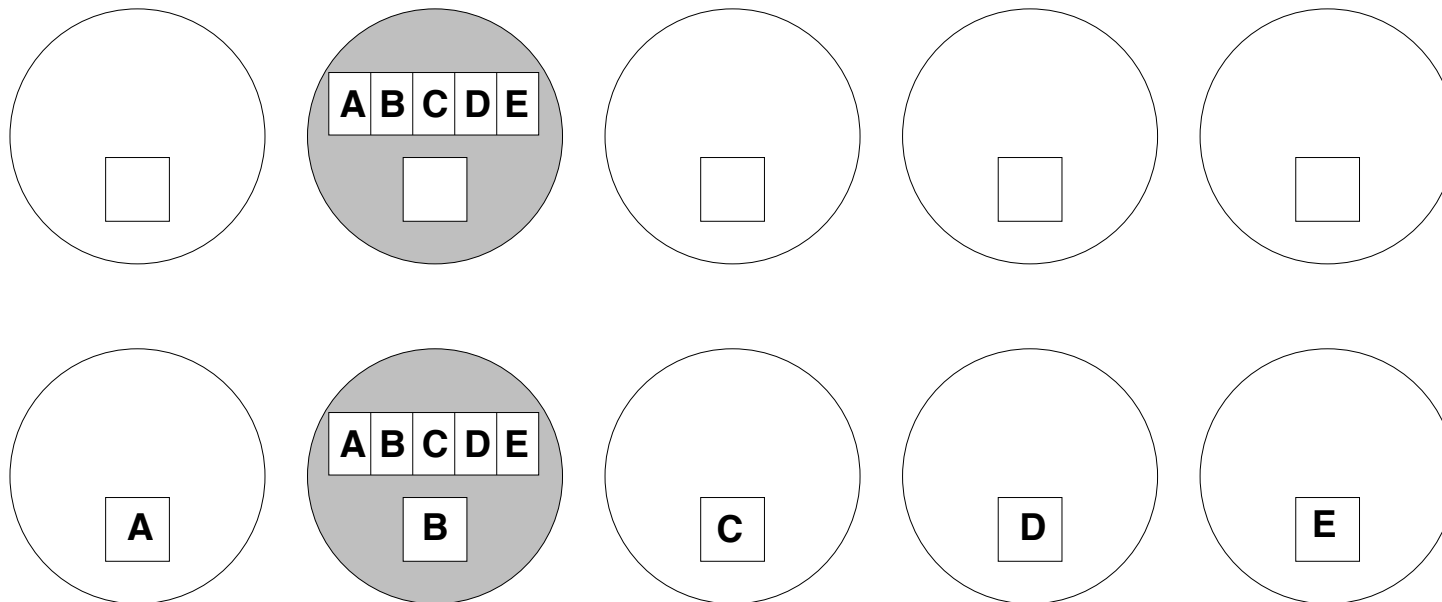
```
int MPI_Bcast (void *buffer, int count,  
              MPI_Datatype datatype, int root,  
              MPI_Comm comm)
```

## □ Fortran:

```
MPI_BCAST (BUFFER, COUNT, DATATYPE, ROOT,  
          COMM, IERROR)
```

```
<type> BUFFER(*)  
INTEGER COUNT, DATATYPE, ROOT, COMM, IERROR
```



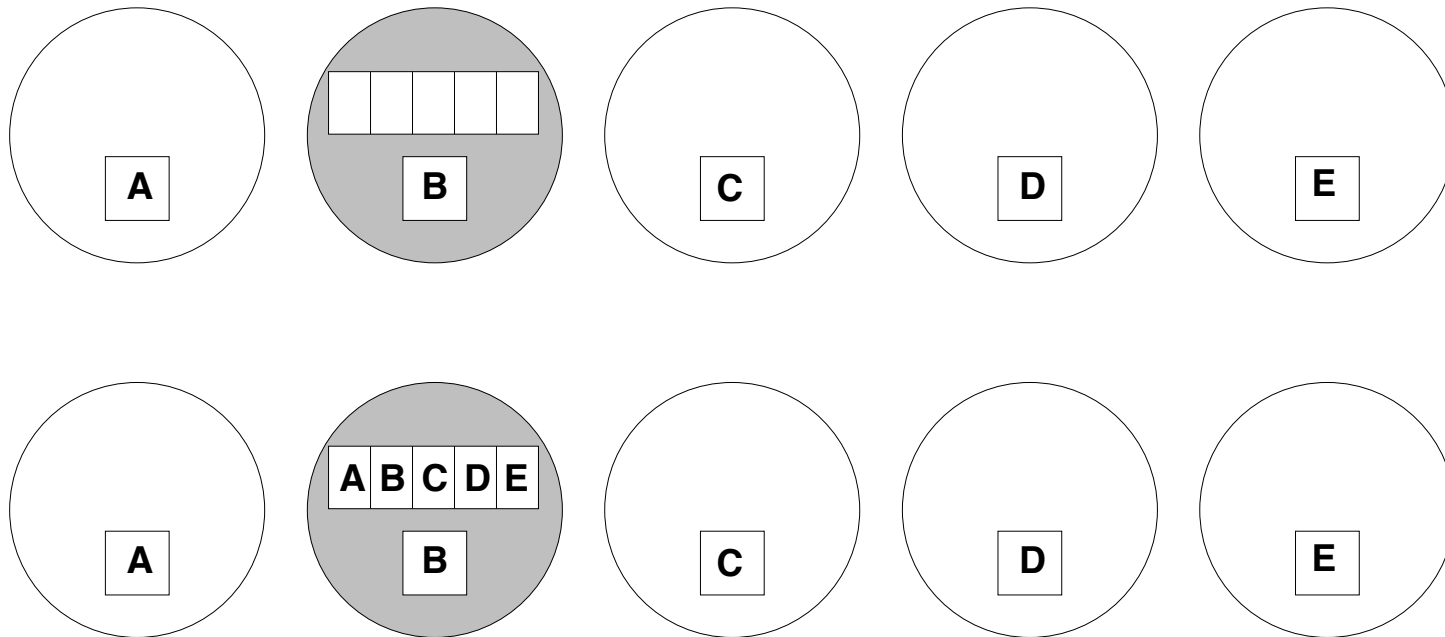


## □ C:

```
int MPI_Scatter(void *sendbuf,  
               int sendcount, MPI_Datatype sendtype,  
               void *recvbuf, int recvcount,  
               MPI_Datatype recvtype, int root,  
               MPI_Comm comm)
```

## □ Fortran:

```
MPI_SCATTER(SENDBUF, SENDCOUNT, SENDTYPE,  
            RECVBUF, RECVCOUNT, RECVTYPE,  
            ROOT, COMM, IERROR)  
  
<type> SENDBUF, RECVBUF  
INTEGER SENDCOUNT, SENDTYPE, RECVCOUNT  
INTEGER RECVTYPE, ROOT, COMM, IERROR
```





C:

```
int MPI_Gather(void *sendbuf, int sendcount,  
              MPI_Datatype sendtype, void *recvbuf,  
              int recvcount, MPI_Datatype recvtype,  
              int root, MPI_Comm comm)
```



Fortran:

```
MPI_GATHER(SENDBUF, SENDCOUNT, SENDTYPE,  
          RECVBUF, RECVCOUNT, RECVTYPE,  
          ROOT, COMM, IERROR)  
<type> SENDBUF, RECVBUF  
INTEGER SENDCOUNT, SENDTYPE, RECVCOUNT  
INTEGER RECVTYPE, ROOT, COMM, IERROR
```

- ❑ Used to compute a result involving data distributed over a group of processes.
- ❑ Examples:
  - global sum or product
  - global maximum or minimum
  - global user-defined operation

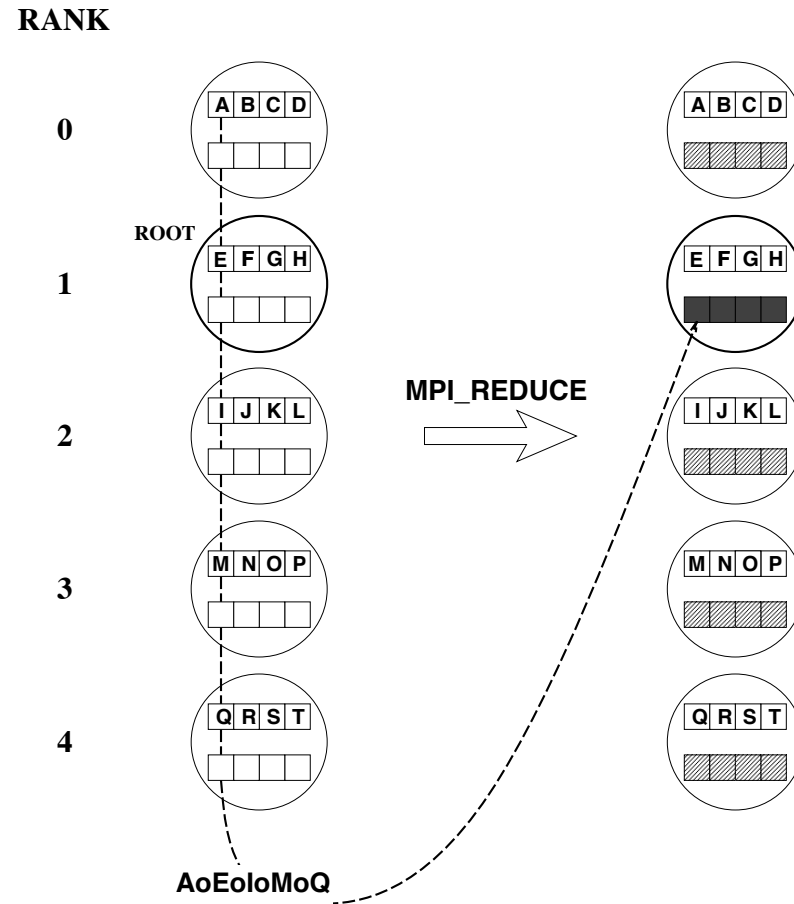
MPI Name	Function
MPI_MAX	Maximum
MPI_MIN	Minimum
MPI_SUM	Sum
MPI_PROD	Product
MPI_LAND	Logical AND
MPI_BAND	Bitwise AND
MPI_LOR	Logical OR
MPI_BOR	Bitwise OR
MPI_LXOR	Logical exclusive OR
MPI_BXOR	Bitwise exclusive OR
MPI_MAXLOC	Maximum and location
MPI_MINLOC	Minimum and location

## □ C:

```
int MPI_Reduce(void *sendbuf,  
              void *recvbuf, int count,  
              MPI_Datatype datatype, MPI_Op op,  
              int root, MPI_Comm comm)
```

## □ Fortran:

```
MPI_REDUCE(SENDBUF, RECVBUF, COUNT,  
          DATATYPE, OP, ROOT, COMM, IERROR)  
<type> SENDBUF, RECVBUF  
INTEGER SENDCOUNT, SENDTYPE, RECVCOUNT  
INTEGER RECVMODE, ROOT, COMM, IERROR
```





## Integer global sum

- C:

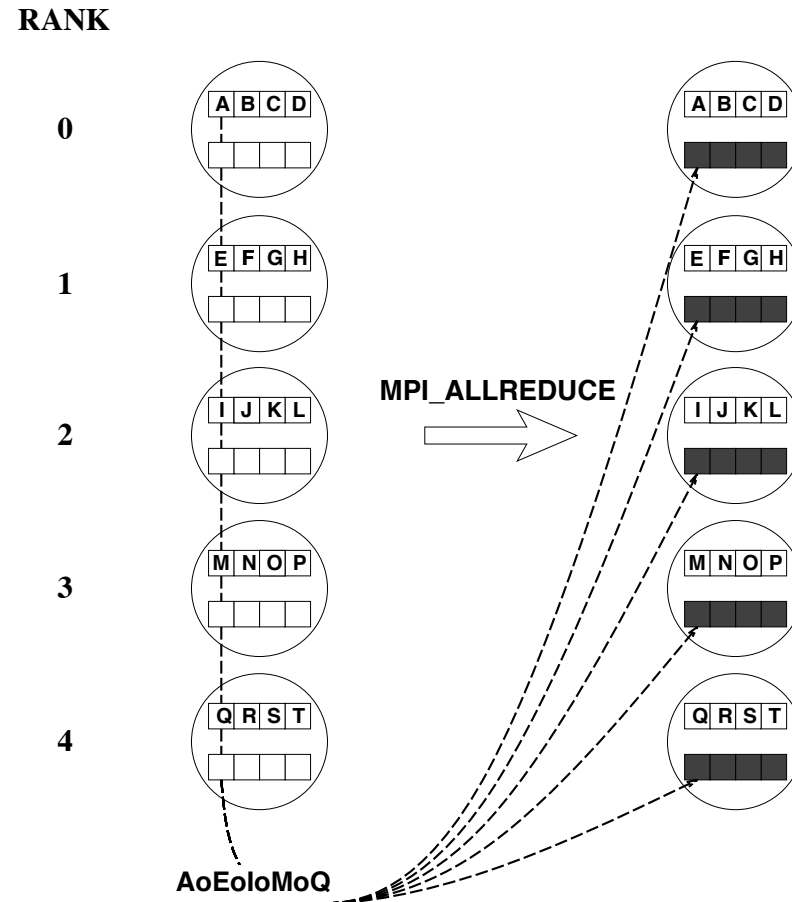
```
MPI_Reduce(&x, &result, 1, MPI_INT, MPI_SUM,  
           0, MPI_COMM_WORLD)
```

- Fortran:

```
CALL MPI_REDUCE(x, result, 1, MPI_INTEGER,  
               MPI_SUM, 0, MPI_COMM_WORLD, IERROR)
```

- Sum of all the **x** values is placed in **result**.
- The result is only placed there on processor 0.

- ❑ **MPI\_ALLREDUCE** – no root process
- ❑ **MPI\_REDUCE\_SCATTER** – result is scattered
- ❑ **MPI\_SCAN** – “parallel prefix”



## Integer global sum

## □ C:

```
int MPI_Allreduce(void* sendbuf,  
                 void* recvbuf, int count,  
                 MPI_Datatype datatype,  
                 MPI_Op op, MPI_Comm comm)
```

## □ Fortran:

```
MPI_ALLREDUCE(SENDBUF, RECVBUF, COUNT,  
              DATATYPE, OP, COMM, IERROR)
```