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# Symmetries + ... (3)

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# Symmetries: Yesterday and today

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Yesterday:

- How to built invariants
- $\mathcal{L}$  has to be invariant
- For  $U(1)$  we explain what is a charge
- For  $SU(N)$  we explain what is a representation

Today:

- Different kind of symmetries
  - Imposed vs accidental
  - Lorentz vs internal
  - Global vs local

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# More on symmetries

# Accidental symmetries

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A symmetry that is an output, and only due to the truncation

- Example: The symmetry that makes the period independent of the amplitude
- Example:  $U(1)$  with  $X(q = 1)$  and  $Y(q = -4)$

$$V(XX^*, YY^*) \Rightarrow U(1)_X \times U(1)_Y$$

- $X^4Y$  breaks this symmetry

# Lorentz invariants

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Unlike symmetries in the internal space of the field, Lorentz is the symmetry of space-time

- We always impose it
- The representations we care about are
  - Singlet: Spin zero (scalars, denote by  $\phi$ )
  - LH and RH fields: Spin half (fermions,  $\psi_L, \psi_R$ )
  - Vector: Spin one (gauge boson, denote by  $A_\mu$ )
- Fermions are more complicated than scalars

# Fermions

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- Under Lorentz, the basic fields are left-handed and right-handed
- We define the complex conjugation as  $\bar{\psi}$
- The kinetic term is different, only one derivative

$$\mathcal{L}_{\text{kin}} \sim \bar{\psi}_L \partial_\mu \gamma^\mu \psi_L$$

- The mass term is also different, it involves LH and RH field

$$\mathcal{L}_m \sim \bar{\psi}_L \psi_R$$

- Why it is?
- We can also have Majorana mass
- What are the conditions to have a mass term?

# Dimension

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- In mechanics we count with  $\dim[x] = 1$
- Here it is a bit more complicated. We use  $\hbar = c = 1$  and  $\dim[E] = 1$  that implies  $\dim[x] = -1$
- What are the dim of
  - $S$
  - $L$
  - $\phi$
  - $\psi$

# $C, P, CP, CPT$

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There are also discrete transformation on space-time

$$C \quad P \quad T$$

- All Lorentz invariant QFT have CPT
- $C$  and  $P$  take you from LH to RH fermion
  - They are “easy” to break
- $CP$  is the difference between matter and anti-matter. Breaking arises from phases in  $\mathcal{L}$



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# Local symmetries

# Local symmetry

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Basic idea: rotations depend on  $x$  and  $t$

$$\phi(x_\mu) \rightarrow e^{iq\theta} \phi(x_\mu) \xrightarrow{\text{local}} \phi(x_\mu) \rightarrow e^{iq\theta(x_\mu)} \phi(x_\mu)$$

- It is kind of logical and we think that all imposed symmetries in Nature are local
- The kinetic term  $|\partial_\mu \phi|^2$  is not invariant
- We want a kinetic term (why?)
- We can save the kinetic term if we add a field that is
  - Massless
  - Spin 1
  - Adjoint representation:  $q = 0$  for  $U(1)$ , triplet for  $SU(2)$ , and octet for  $SU(3)$

# Gauge boson kinetic term

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- Generalization of that of a scalar
- We know how it is in classical  $E\&M$

$$\mathcal{L} \propto F_{\mu\nu} F^{\mu\nu} \quad F_{\mu\nu} = \partial_\mu A_\nu - \partial_\nu A_\mu$$

- For non-Abelian there is a modification. For  $SU(2)$

$$F_{\mu\nu}^a = \partial_\mu G_\nu^a - \partial_\nu G_\mu^a - ig\epsilon_{abc} G^b G^c$$

- We get gauge boson self interaction

$$F_{\mu\nu}^a F_a^{\mu\nu} \sim g G^3 + g^2 G^4$$

# Gauge symmetry

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New field  $A_\mu$ . How we couple it?

- Recall classical electromagnetism

$$H = \frac{p^2}{2m} \Rightarrow H = \frac{(p - qA_i)^2}{2m}$$

- In QFT, for a local  $U(1)$  symmetry and a field with charge  $q$

$$\partial_\mu \rightarrow D_\mu \quad D_\mu = \partial_\mu + iqA_\mu$$

- We get interaction from the kinetic term

$$\bar{\psi} \not{D} \psi \sim \bar{\psi} (\partial_\mu + iqA_\mu) \gamma^\mu \psi \rightarrow q \bar{\psi} \gamma^\mu \psi A_\mu$$

- The interaction  $\propto q$  (for  $SU(N)$  to matrices)

# The two aspects of symmetries

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Thinking about E&M

- Charge conservation
- The force proportional to the charge

Q: Which of these come from the “global” aspect and which from the “local” aspect of the symmetry?

# More on masses

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To summarize masses

- There is no symmetry that forbids generic scalar masses
- Chiral symmetry forbid fermion Dirac masses
- Gauge symmetry forbid gauge boson masses

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# SSB

# Breaking a symmetry

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# SSB

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- A situation that we have when the Ground state is degenerate
- By choosing a ground state we break the symmetry
- We choose to expand around a point that does not respect the symmetry
- PT only works when we expand around a minimum

What is the difference between a broken symmetry and no symmetry?

SSB implies relations between parameters

# SSB

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Symmetry is  $x \rightarrow -x$  and we keep up to  $x^4$

$$f(x) = a^2 x^4 - 2b^2 x^2 \quad x_{\min} = \pm b/a$$

We choose to expand around  $+b/a$  and use  $u \rightarrow x - b/a$

$$f(x) = 4b^2 u^2 + 4ba u^3 + a^2 u^4$$

- No  $u \rightarrow -u$  symmetry
- The  $x \rightarrow -x$  symmetry is hidden
- A general function has 3 parameters  $c_2 u^2 + c_3 u^3 + c_4 u^4$
- SSB implies a relation between them

$$c_3^2 = 4c_2 c_4$$

# Partial SSB

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Think about a vector in 3d. What symmetry is broken by it?

# SSB in QFT

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- When we expand the field around a minimum that is not invariant under a symmetry

$$\phi(x_\mu) \rightarrow v + h(x_\mu)$$

- It breaks the symmetries that  $\phi$  is not a singlet under
- Then we can get masses that were protected by the broken symmetry
  - Fermions

$$y\phi\bar{\psi}_L\psi_R \rightarrow y(v + h)\bar{\psi}_L\psi_R, \quad m_\psi = yv$$

- Gauge fields of the broken symmetries

$$|D_\mu\phi|^2 = |\partial_\mu\phi + iqA_\mu\phi|^2 \ni A^2\phi^2 \rightarrow v^2A^2$$

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# Model buildings

# Building Lagrangians

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- Choosing the generalized coordinates (fields)
- Imposing symmetries and how fields transform (input)
- The Lagrangian is the most general one that obeys the symmetries
- We truncate it at some order, usually fourth

# The general $\mathcal{L}$

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We write

$$\mathcal{L} = \mathcal{L}_{\text{kin}} + \mathcal{L}_{\psi} + \mathcal{L}_{\text{Yuk}} + \mathcal{L}_{\phi}$$

- Always have a kinetic term
- The task is to find the other terms and see what they lead to