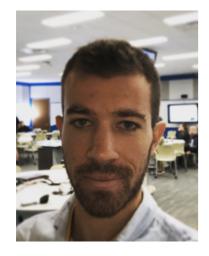
javier aaron brayden romain







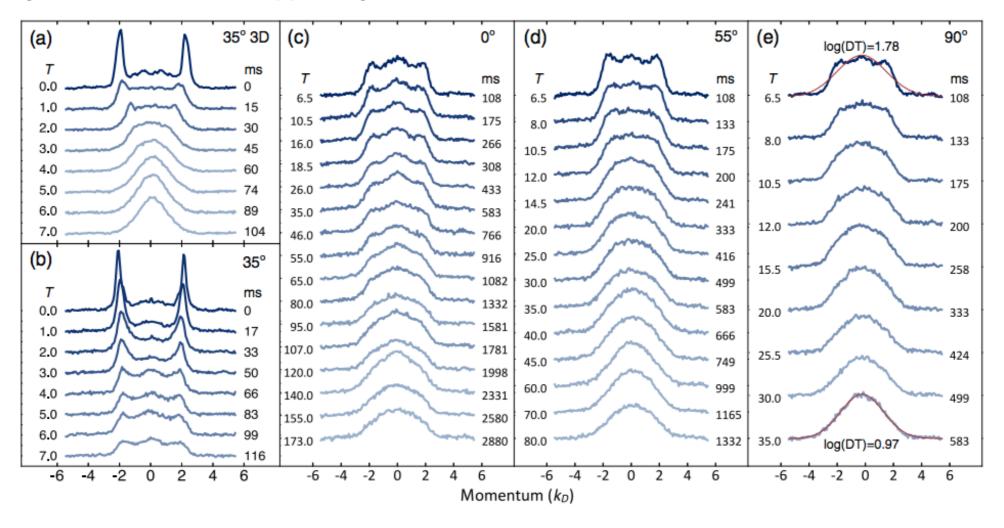


integrability breaking

AJ Friedman, SG, R Vasseur, *Phys. Rev. B* **101**, 180302(R) J Lopez-Piqueres, B Ware, SG, R Vasseur, arXiv:2005.13546

why is this problem interesting?

Experimental systems are not perfectly integrable; need to understand rates
 [Tang, Kao, Li, Seo, Mallayya, Rigol, SG, Lev, PRX (2018); cf. Moller, Dubail talks]



Theoretically unclear what happens in many cases of interest
 [cf. De Nardis talk, also "prethermalization" generally (Abanin, De Roeck, Huveneers)]

why is this problem hard?

Why not just write down an rhs for GHD/Bethe-Boltzmann equation?

$$\partial_t n_{\lambda}(x,t) + v^{\text{eff}}[\{n\}] \partial_x n_{\lambda}(x,t) = I[\{n\}]$$

- Two questions
 - Hard problem

What is the collision integral? (Involves matrix elements between many-body states) Collision integral generally lies outside GHD: e.g., umklapp scattering

Relatively easy problem

How do we extract transport coefficients for the remaining conserved quantities?

(relatively) easy problem

An integrable system has infinitely many conserved quantities

$$\partial_t Q_i = I(\{Q_j\})$$
gradient
expansion

(relatively) easy problem

An integrable system has infinitely many conserved quantities

$$\partial_t Q_i = I(\{Q_j\})$$
gradient expansion

• Linearize:
$$\partial_t \delta Q_i = \frac{\partial I}{\partial Q_j} \delta Q_j \equiv -\Gamma_{ij} \delta Q_j$$
 specified by residual charges

Residual conserved charges are zero modes of Gamma

$$\partial_t \delta Q_i = -\Gamma_{ij} \delta Q_j$$

Continuity equation for residual charges

$$\partial_t q_\alpha + \partial_x \dot{j}_\alpha = 0$$
Greek indices for residual charges

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Greek indices for residual charges

• Drude response in integrable systems comes from overlap of current with conserved charges ("hydrodynamic projections")

$$J_{lpha}=A_{lpha i}Q_{i}+\ldots$$
 stuff that decays

Kubo formula:

$$\sigma_{\alpha\beta}^{\rm d.c.} \propto \int dt \langle J_{\alpha}(t) J_{\beta}(0) \rangle = A_{\alpha i} A_{\beta} \int dt \langle Q_{i}(t) Q_{j}(0) \rangle + \dots$$
diverges in integrable limit

$$\sigma_{\alpha\beta}^{\text{d.c.}} \propto \int dt \langle J_{\alpha}(t) J_{\beta}(0) \rangle = A_{\alpha i} A_{\beta j} \int dt \langle Q_{i}(t) Q_{j}(0) \rangle + \dots$$

• Integrable: $T\sigma_{\alpha\beta}(\omega) = A_{\alpha i}C_{mn}(A^T)_{j\beta}\delta(\omega) + \dots$

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- Integrable: $T\sigma_{\alpha\beta}(\omega) = A_{\alpha i}C_{mn}(A^T)_{j\beta}\delta(\omega) + \dots$
- For sufficiently weak integrability breaking:

$$\langle \delta Q_i(t) \delta Q_j(0) \rangle = [e^{-\Gamma t}]_{ik} \langle \delta Q_k \delta Q_j \rangle$$

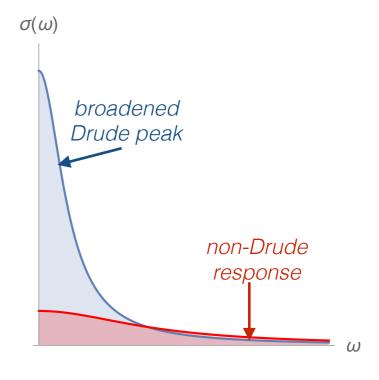
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• Final expression ("broadened Drude peak"):

$$T\sigma_{\alpha\beta}^{\mathrm{d.c.}} = \left(\mathbf{A}\mathbf{I}^{-1}\mathbf{C}\mathbf{A}^T\right)_{\alpha\beta}$$
inverse restricted to fast subspace



ullet By Einstein relation, related to diffusion matrix $D_{lphaeta}=ig({f A}{f \Gamma}^{-1}{f A}ig)_{lphaeta}$

hydrodynamics and noise

- Continuity equations for the residual charges: $\partial_t q_\alpha + \partial_x (A_{\alpha n} q_n) = 0$
- Decay of other charges:

$$\partial_t q_n + \partial_x (A_{n\alpha} q_\alpha) = -\Gamma_{nm} q_m + \xi \Rightarrow q_m = (\Gamma^{-1})_{mn} \left[\partial_x (A_{n\alpha} q_\alpha) + \xi \right]$$

- Stationarity of C_{mn} fixes the noise strength (a la fluctuating hydro)
- Combines to give a noisy diffusion equation with $D_{\alpha\beta}=\left(\mathbf{A}\mathbf{\Gamma}^{-1}\mathbf{A}\right)_{\alpha\beta}$
- In principle this can be extended to a nonlinear diffusion equation where the matrices are nontrivial functions of space

hard problem: what is Gamma?

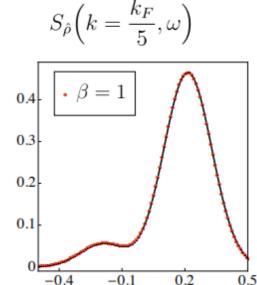
$$\hat{H} = \hat{H}_0 + h_i(x)\hat{q}_i(x) + J_{ij}(x)\hat{q}_i(x)\hat{q}_j(x) + \dots$$

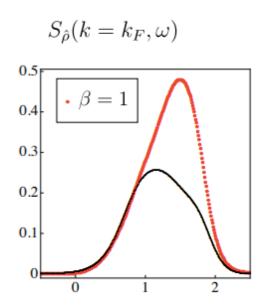
 In general: depends on matrix elements to rearrange many particles with (in principle) large momentum transfer

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$$\hat{H} = \hat{H}_0 + h_i(x)\hat{q}_i(x) + J_{ij}(x)\hat{q}_i(x)\hat{q}_j(x) + \dots$$

- In general: depends on matrix elements to rearrange many particles with (in principle) large momentum transfer
- Hydrodynamic limit:
 - Smoothly varying potentials and/or long-range interactions
 - Dominated by small-momentum scattering,
 which rearranges few quasiparticles
 [De Nardis and Panfil; De Nardis, Bernard, Doyon]





• Matrix elements depend on hydrodynamic data, e.g.: $\langle \psi | \hat{q}_{lpha} | \psi ; heta o heta'
angle = q^{
m dr}(heta)$

$$\langle \psi | \hat{q}_{\alpha} | \psi; \theta \to \theta' \rangle = q^{\mathrm{dr}}(\theta)$$

slowly fluctuating noise

Suffices to work with 1ph excitations

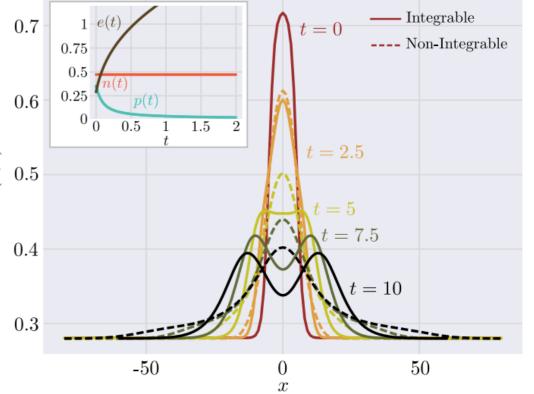
$$\partial_{t} n_{\lambda}(x,t) + v^{\text{eff}}[\{n\}] \partial_{x} n_{\lambda}(x,t) = I[\{n\}]$$

$$\mathcal{I}_{\lambda} = \rho_{\lambda}^{\text{tot}} \int d\varphi |\tilde{V}(k_{\lambda+\varphi} - k_{\lambda})|^{2} |\tilde{\eta}(\varepsilon_{\lambda+\varphi} - \varepsilon_{\lambda})|^{2} \rho_{\lambda+\varphi}^{\text{tot}} h_{0}^{\text{dr}}(\lambda)$$

$$\times h_{0}^{\text{dr}}(\lambda + \varphi) [n_{\lambda+\varphi}(1 - n_{\lambda}) - n_{\lambda}(1 - n_{\lambda+\varphi})],$$

$$(1: \frac{\widehat{\varphi}}{\widehat{\varphi}}) 0.5$$

- Noise causes "rapidity diffusion"
- Noise strength is proportional to dressed charge of quasiparticles



 Can also do slow static potentials, interactions, cases with no Eulerscale hydro (gapped XXZ)

Friedman, SG, Vasseur, PRB (2020) cf. Bastianello, De Nardis, De Luca arXiv:2003.01702; Durnin, Bhaseen, Doyon, arXiv:2004.11030 Bouchoule, Doyon, Dubail, arXiv:2006.03583

generalized relaxation time approximation

- GHD assumes that the system is locally in a generalized Gibbs ensemble
 - GGE in 1-1 correspondence with quasiparticle distribution functions
- Impose local equilibration at some rate:

$$\hat{\rho}_{\text{GGE}}(t + \Delta t) = (1 - \gamma \Delta t)\hat{\rho}_{\text{GGE}}(t) + \gamma \Delta t\hat{\rho}_{\text{Gibbs}} [\hat{\rho}_{\text{GGE}}(t)]$$

generalized relaxation time approximation

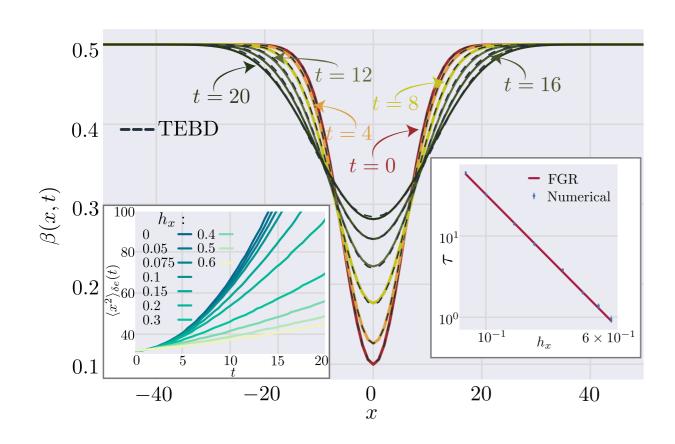
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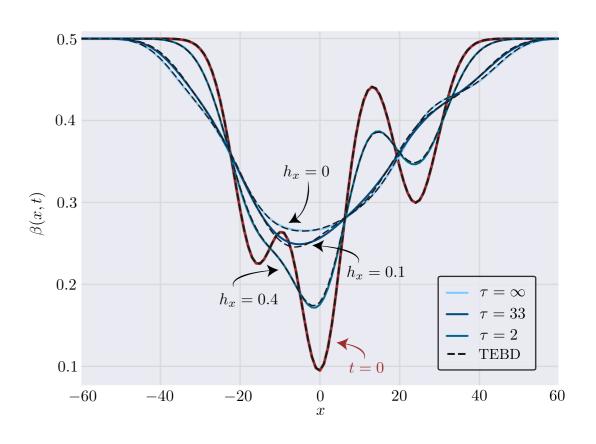
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- Faithful treatment of nonlinearities
- Algorithm: evaluate residual charges in the instantaneous GGE, find Gibbs state that matches these residual charges
- In principle can also let relaxation rate be a function of residual charges

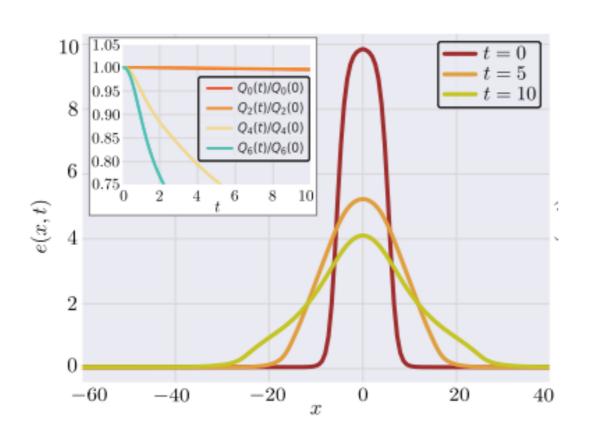
does it work?

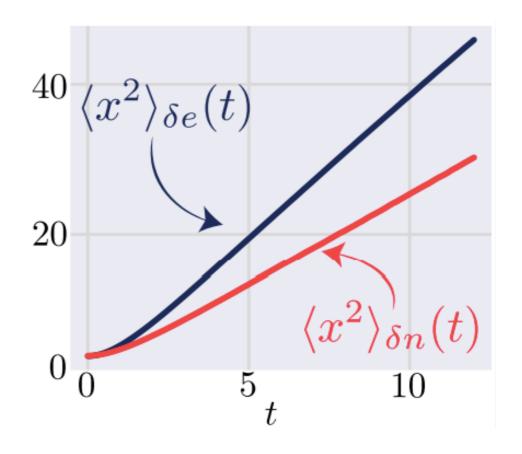
- Energy transport in easy-axis XXZ $\hat{H} = \sum_{i} (\hat{S}_{i}^{x} \hat{S}_{i+1}^{x} + \hat{S}_{i}^{y} \hat{S}_{i+1}^{y} + \Delta \hat{S}_{i}^{z} \hat{S}_{i+1}^{z}) + h_{x}(-1)^{i} \hat{S}_{i}^{x}$,
- Extract relaxation time vs h_x by evolving a gaussian initial state
- Same relaxation time works for essentially all initial states





1d bose gases





- Captures non-Gaussianity of profiles
- Captures distinct transport coefficients for distinct charges

outlook

- Integrability breaking is a hard problem because it depends on matrix elements that are fundamentally outside GHD
 - Except when the perturbations are slowly varying in space and time
- We care about *qualitative* phenomena
 - Crossovers from ballistic to diffusive transport, "dressing" effects
 - Generalized relaxation time approximation captures all the physics essential to hydro
 - Need to extend GRTA to include noise (KPZ?)
 - Key question: integrability-breaking effects in cases with anomalous integrable dynamics