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**INTERNATIONAL WORKSHOP ON PROTEOMICS:
PROTEIN STRUCTURE, FUNCTION AND INTERACTIONS**
(5 - 16 May 2003)

"Solvent effects on simple protein models"

presented by:

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Solvent Effects on Simple Protein Models

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Can we bridge the gap between explicit and implicit solvent models?

Implicit solvent: simple and fast, but... how reliable?

↑
Anything here?
↓

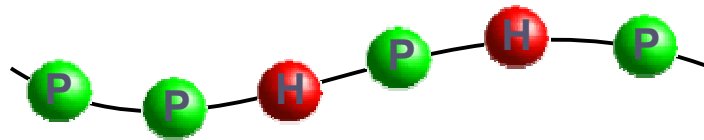
Explicit solvent: detailed and reliable, but... too slow

Outline

- **A simple implicit solvent models: the HP model**
- **The semi-explicit solvent: the Müller-Lee-Graziano model**
- **A simple semi-explicit solvent model: the HPW model**
- **Can we *learn* effective pairwise interactions?**

Implicit solvent: The HP model (K. Dill, 1989)

Amino-acid alphabet: **H** (hydrophobic), **P** (polar)



Proteins: **self-avoiding walks (SAW)** on a **2D lattice**

The hydrophobic effect is expressed by an **effective interaction between nearest neighbors H amino-acids.**

$$\varepsilon_{HH} < \varepsilon_{HP} (= \varepsilon_{PH}) \leq \varepsilon_{PP}$$

Mathematical Formulation

Hamiltonian

$$H = \sum_{i < j} \varepsilon_{p_i p_j} \Delta(r_i, r_j)$$

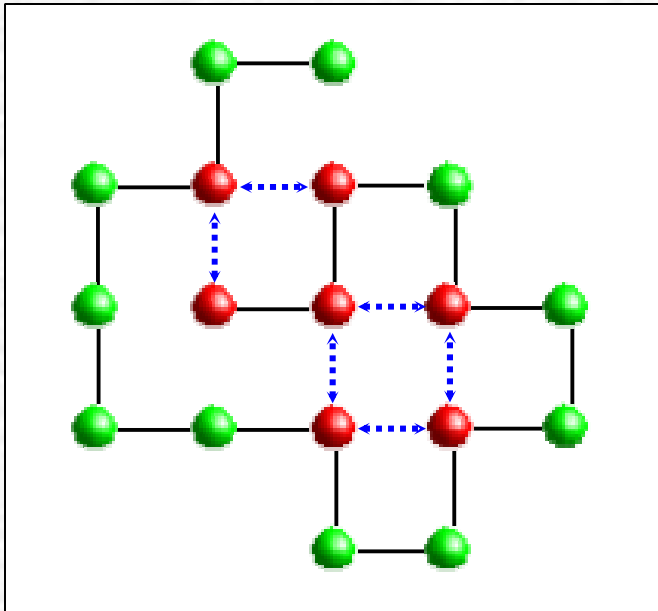
with:

ε_{XY} : interaction values

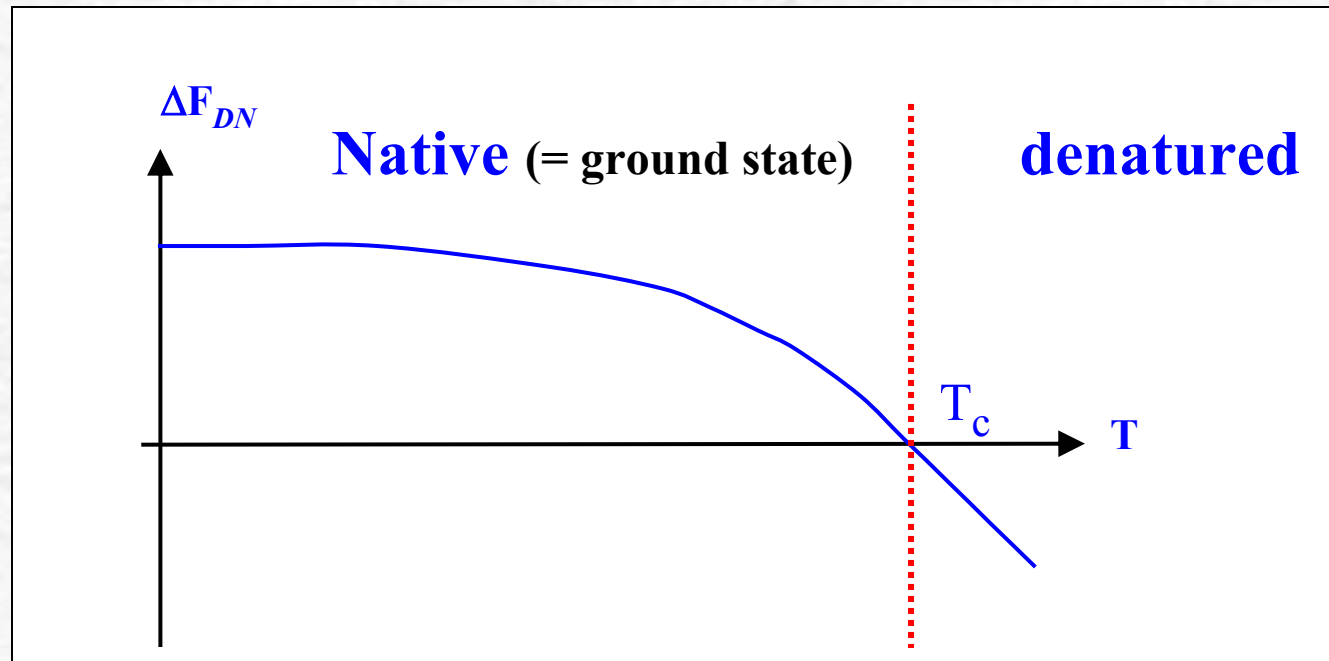
p_i : **H** or **P**

$$\Delta(r_i, r_j) = \begin{cases} 1 & \text{if } i, j \text{ are } n.n. \\ 0 & \text{otherwise} \end{cases}$$

$$\varepsilon_{HH} = -1 \quad \varepsilon_{HP} = \varepsilon_{PH} = \varepsilon_{PP} = 0$$

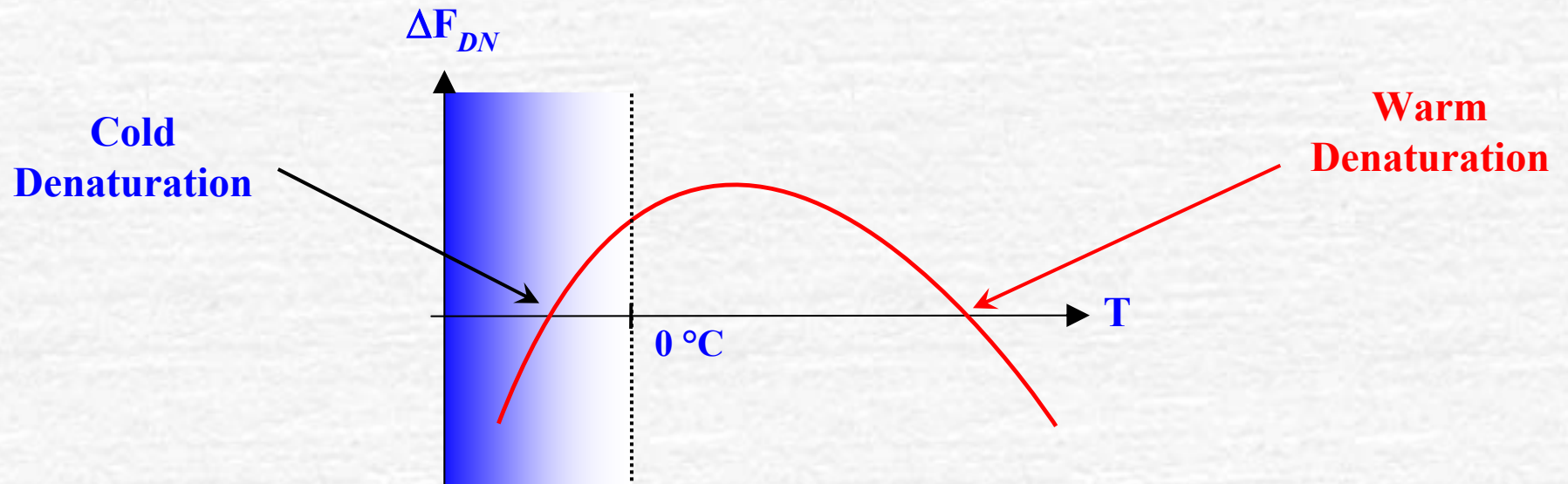


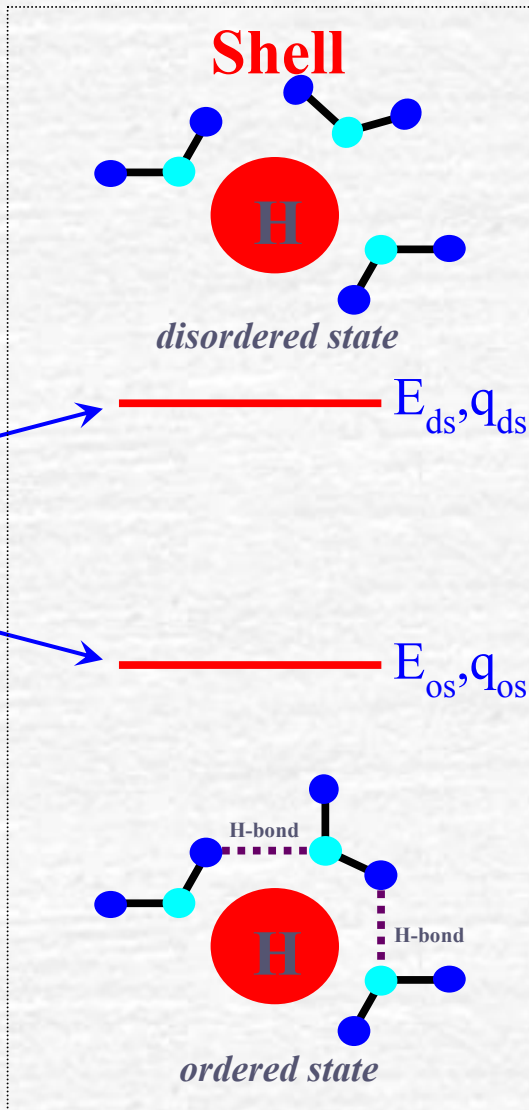
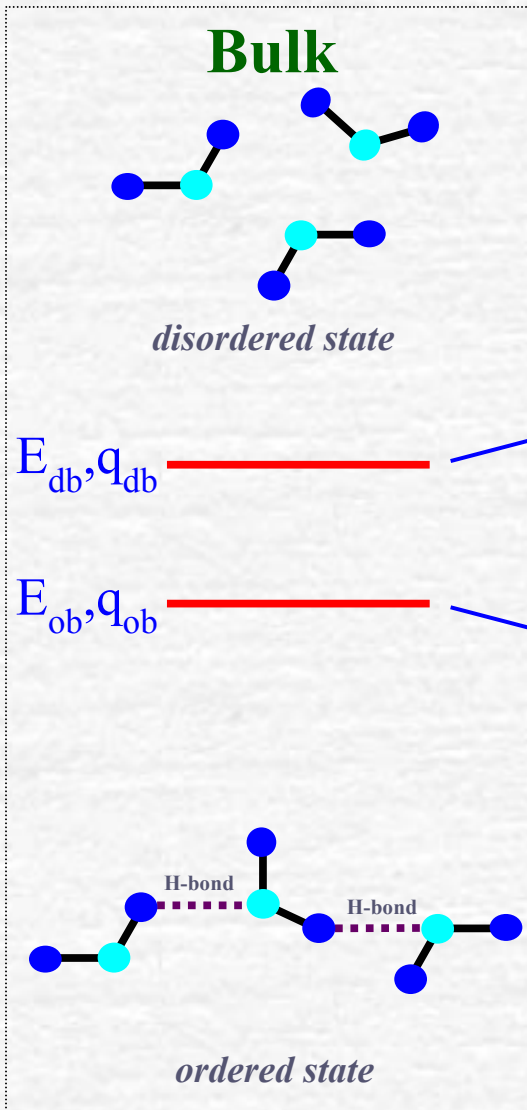
Given a good sequence (= with a non-degenerate native state)



**Only a subset of all sequences are good sequences,
and have a native state with a hydrophobic core**

Folding free energy difference for real proteins





**Müller-Lee-Graziano
(1996)**

Energy ↑

Experiments and simulations suggest

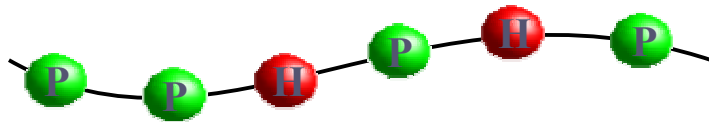
$$E_{ds} > E_{db} > E_{ob} > E_{os}$$

$$q_{ds} > q_{db} > q_{ob} > q_{os}$$

Explicit solvent: The HPW model

P. De Los Rios & G. Caldarelli, Phys. Rev. E **62**, 8449 (2000)

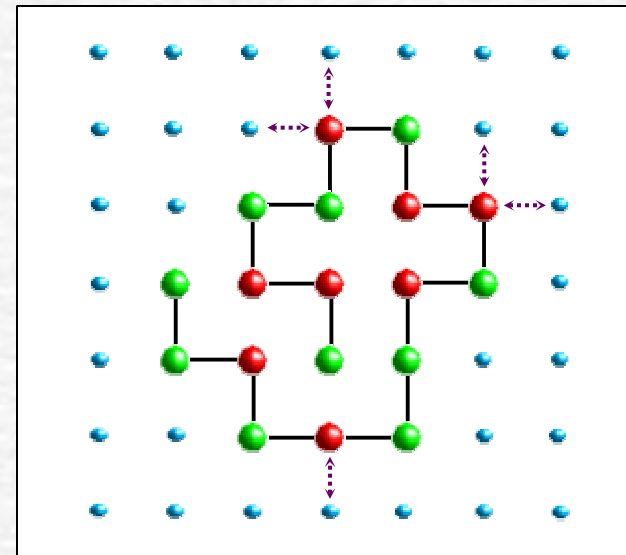
Amino-acids alphabet: **H** (hydrophobic), **P** (polar)



The solvent is (semi)explicitly taken into account. Sites not occupied by a.a. are occupied by *groups of water molecules*.

Proteins:
self-avoiding walks (SAW)
on a 2D lattice

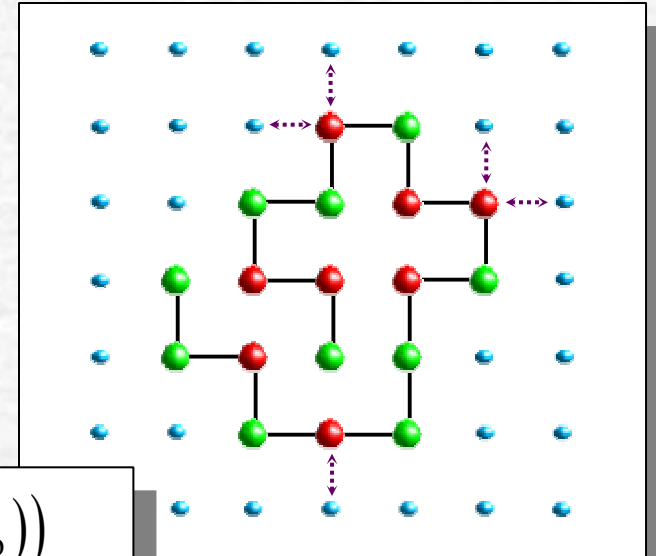
The water behavior is described
by the **MLG** model.



The system: protein + solvent

Energy

$$E = \sum_{\langle i,H \rangle} (E_{os} \delta_{i,os} + E_{ds} (1 - \delta_{i,os})) + \sum_{(i,H)} (E_{ob} \delta_{i,ob} + E_{db} (1 - \delta_{i,ob}))$$

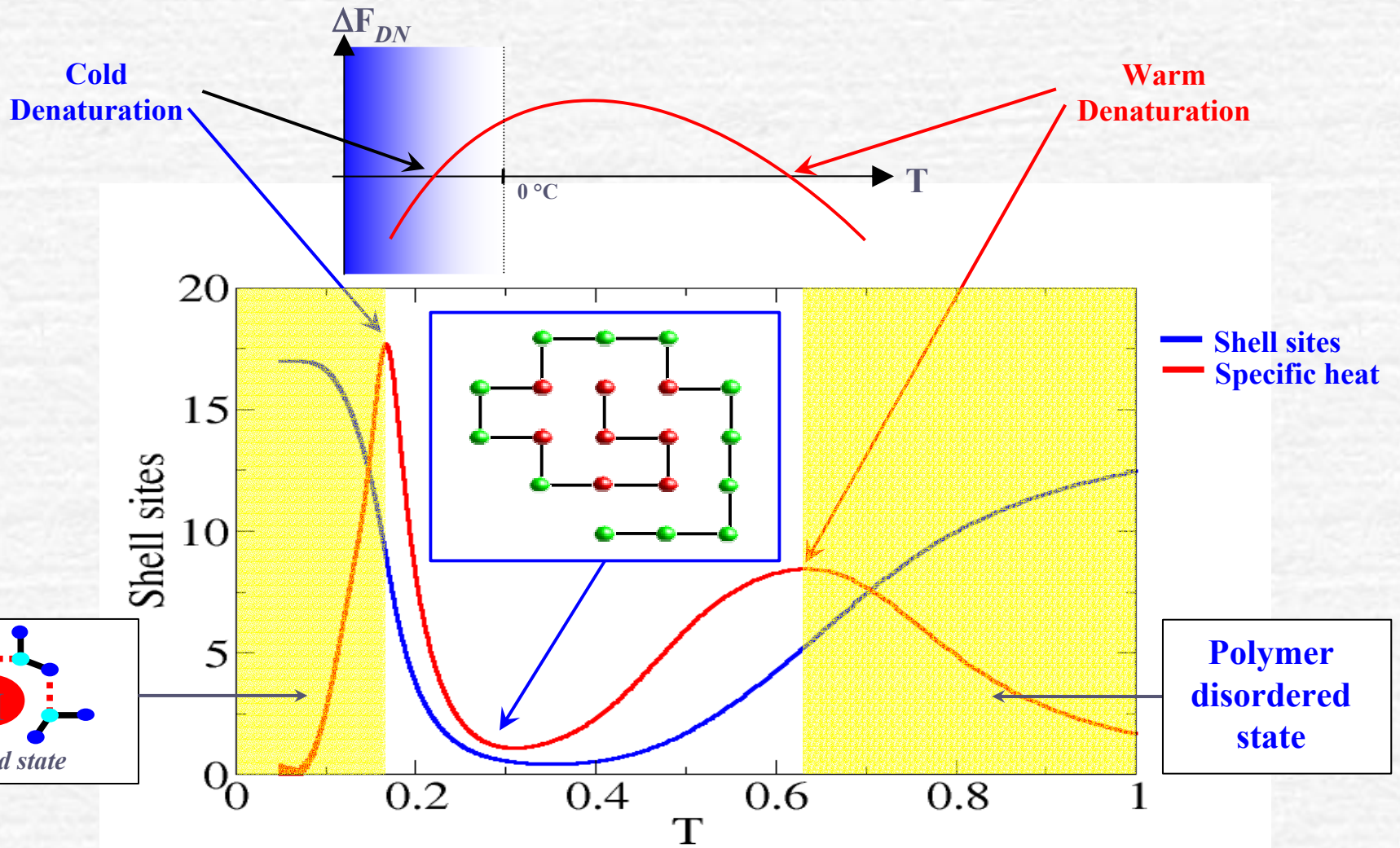


Conformation Partition function

$$Z(S, \Gamma) = \left(q_{ob} e^{-\beta E_{ob}} + q_{db} e^{-\beta E_{db}} \right)^{n_b(\Gamma)} \left(q_{os} e^{-\beta E_{os}} + q_{ds} e^{-\beta E_{ds}} \right)^{n_s(\Gamma)}$$

Γ = conformation
 S = sequence

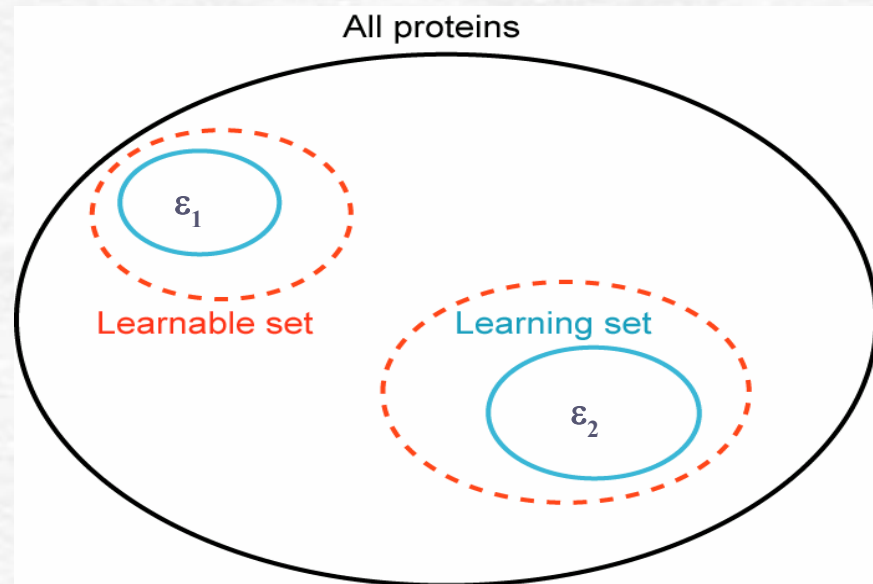
Native state and denaturations



Learning effective potentials

Inference of potentials from known native structures
(from the **Protein Data Bank**)

Problem: no potentials
able to stabilize all
native states



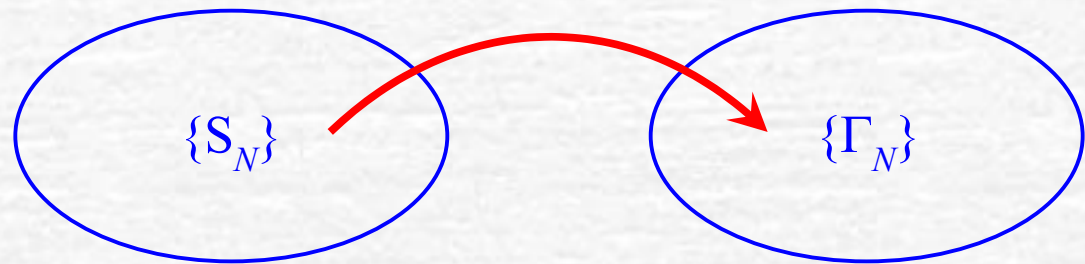
We need to create our own “virtual” **PDB** for simple models

↓
Protein design

Cost function

Partial free energy

$$F(S, \Gamma) = -k_B T \cdot \ln(Z(S, \Gamma) / Z(S))$$



↓ **Exact Enumeration**

Good sequences: those with a unique conformation with the lowest cost function value



e.g. $L = 20$:

$$\begin{aligned} \# \{S_{20}\} &= 2^{20} \cong 10^6 \\ \# \{S'_{20}\} &< 40.000 \end{aligned}$$

Effective a.a. interaction Hamiltonian

$$H = \sum_{i < j} \varepsilon_{pp, \Delta}(\Gamma_i, \Gamma_j)$$

$$H(S, \Gamma) - H(S, \Gamma_R) > 0 \quad \forall \Gamma \neq \Gamma_R, \forall S$$

$$H = \sum_i \varepsilon_i C_i(S, \Gamma)$$

$$\rightarrow \sum_i \varepsilon_i C_i(S, \Gamma) - \sum_i \varepsilon_i C_i(S, \Gamma_R) = \vec{\varepsilon} \cdot \vec{C}^{\Delta}(S, \Gamma, \Gamma_R) > 0$$

$$\text{with: } C_i^{\Delta}(S, \Gamma, \Gamma_R) = C_i(S, \Gamma) - C_i(S, \Gamma_R)$$

$$\vec{\varepsilon} = (\varepsilon_{\text{III}}, \varepsilon_{\text{IV}}, \dots) = ?$$

The perceptron

Trial vector ε_n

- Calculate *all* Scalar Products $C_i^{\Delta} \cdot \varepsilon_n$
- **Worst** Scalar Product $C_w^{\Delta} \cdot \varepsilon_n$
- $\varepsilon_{n+1} = \varepsilon_n + \eta C_w^{\Delta}$
- Iterate the process



$\vec{\varepsilon}_n$ converges to $\vec{\varepsilon}$

Decoys from Protein Design

Sequence 1	$\Gamma_n(S_1)$	15 $\Gamma(S_1)$	15 $C^{\Delta}(S_1)$
Sequence N	$\Gamma_n(S_N)$	15 $\Gamma(S_N)$	15 $C^{\Delta}(S_N)$

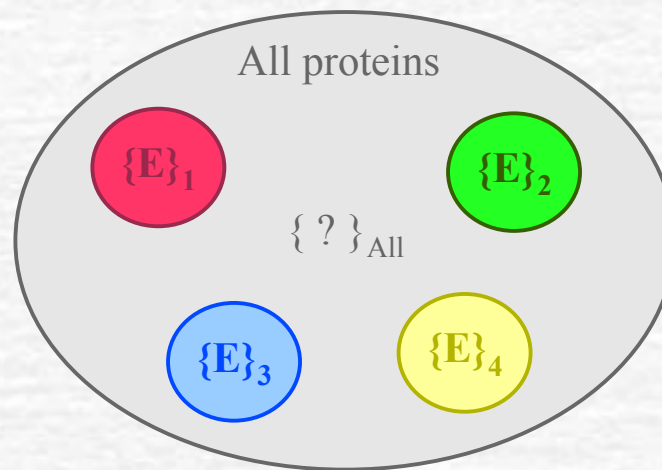
HP Model results

- The perceptron converges to the initial interactions values.

$$\varepsilon_{ij}^{\text{perc}} \cong \varepsilon_{ij} \quad i, j = H, P$$

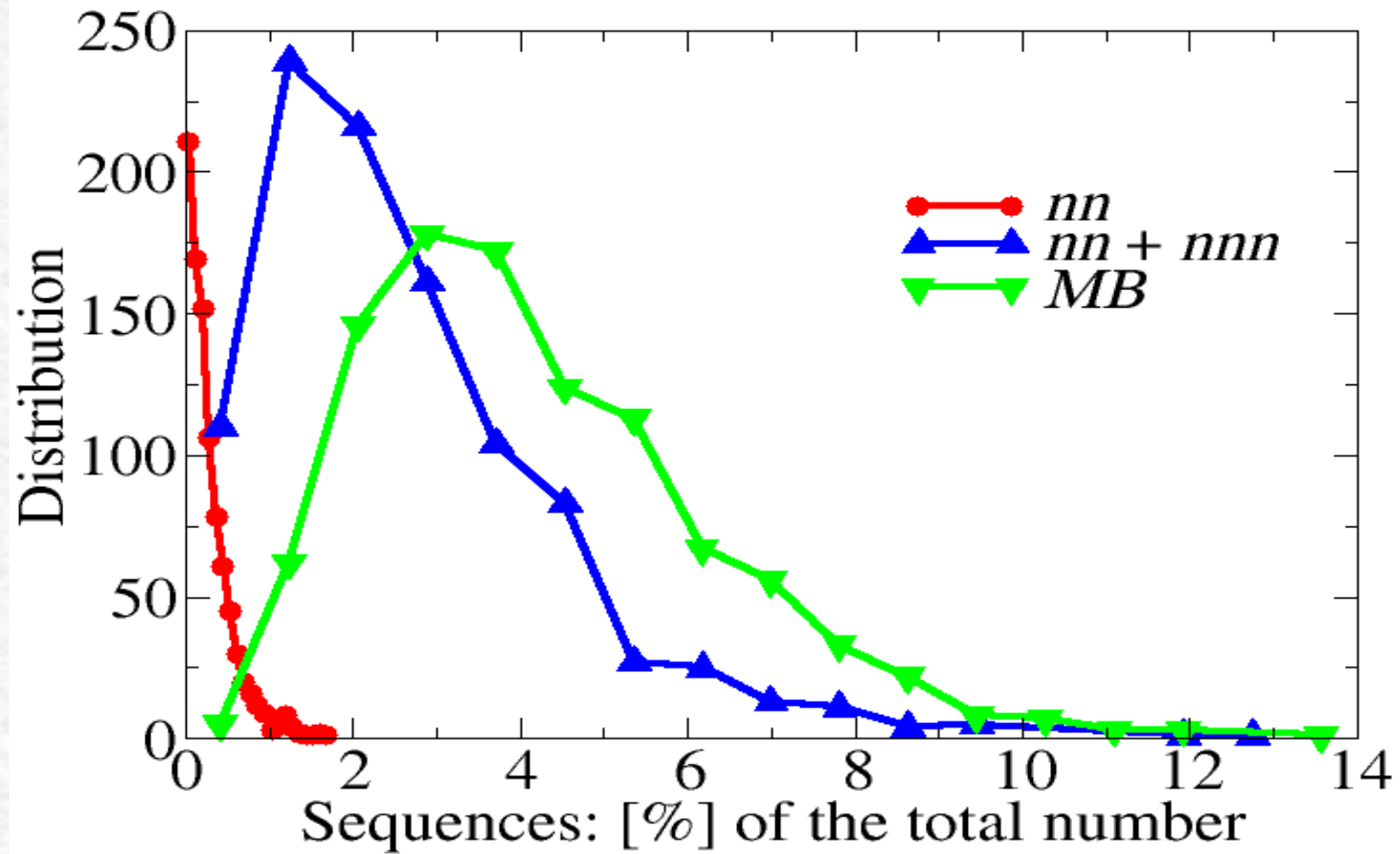
- Only a **small** set is needed to reach the original values.

HPW Model results

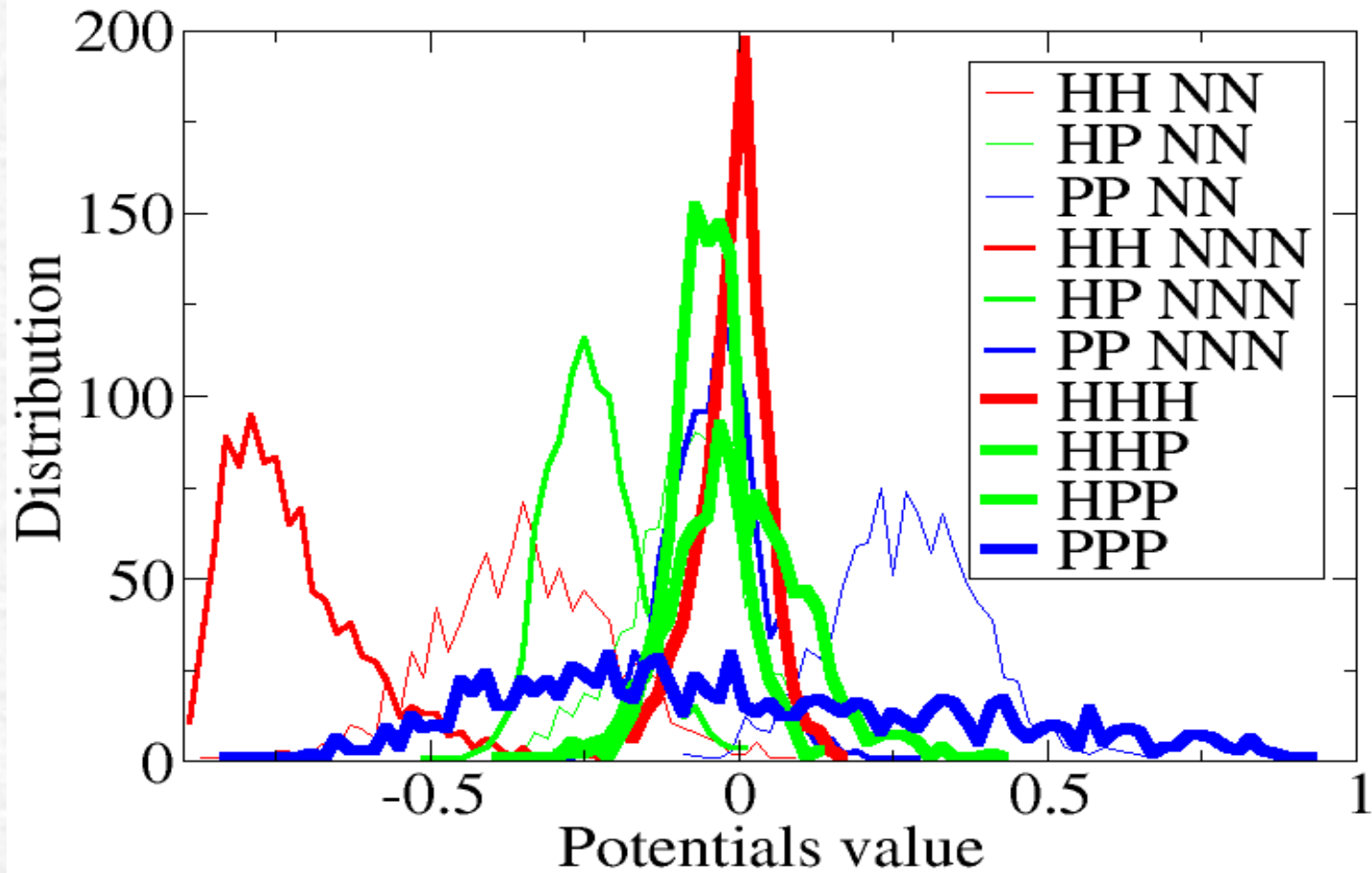


Same problem as for **real** proteins !

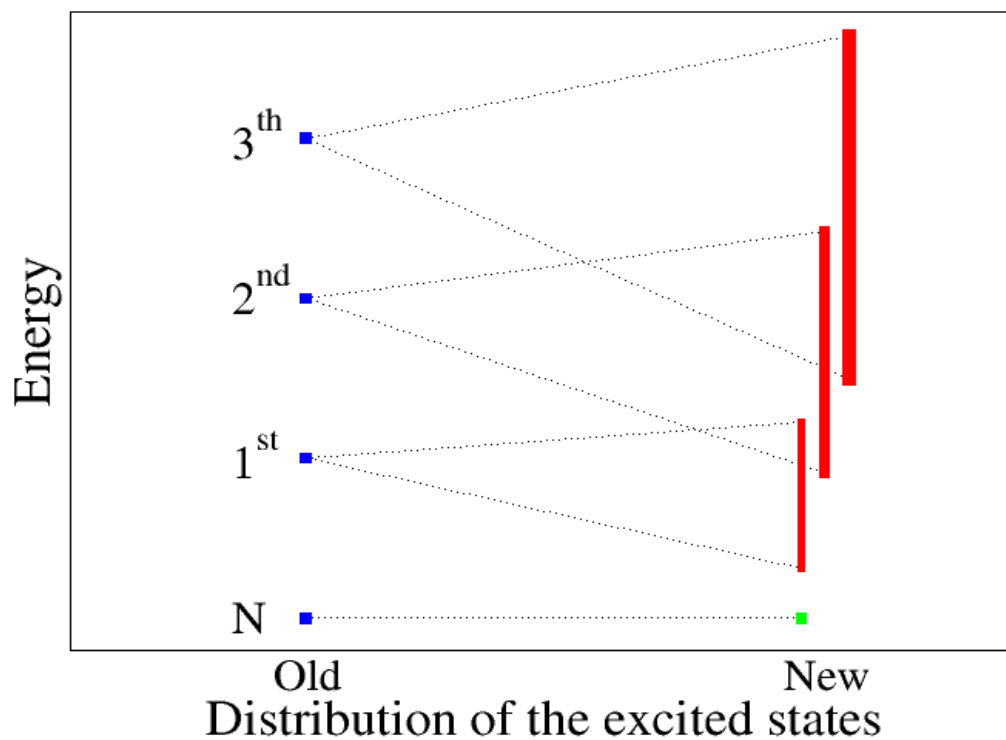
Learnable sequences



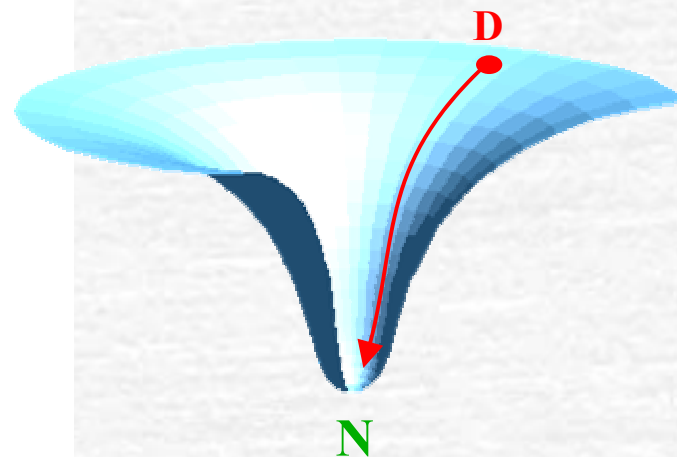
Interaction values



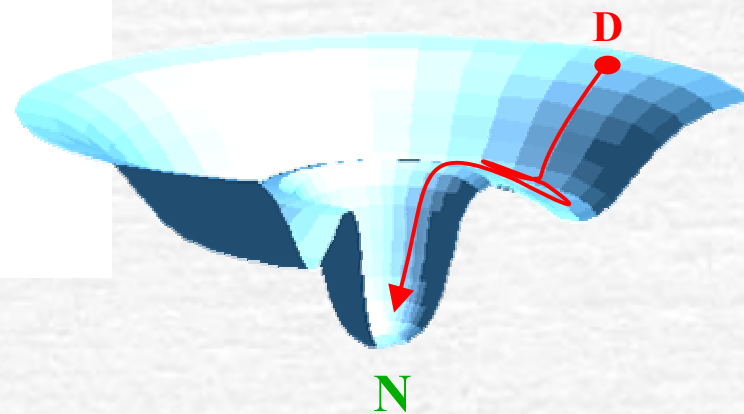
Energy landscapes



Explicit solvent



Effective interactions



Conclusions

- **The thermodynamics of proteins can be reproduced over a broad range of temperatures by means of a semi-explicit solvent (cold and warm denaturation within the same framework)**
- **The solvent effects can not be reproduced by effective residues interactions.**
- **The energy landscape changes : the dynamical folding process may change too. Some care should be taken when studying dynamics.**

Bibliography

- **P. De Los Rios & G. Caldarelli, Phys. Rev. E 62, 8449 (2000)**
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Perceptron Main algorithm

