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School on Nonlinear Differential Equations | (smr 1777)

Friday 27 October 2006

**Subriemannian techniques in Robotics, the Motion Planning Problem - III - Main Building
Main Lecture Hall (11:00-12:00)**

time	title	presenter
11:00	Subriemannian techniques in Robotics, the Motion Planning Problem - III	J-P. GAUTHIER