



2458-13

Workshop on GNSS Data Application to Low Latitude Ionospheric Research

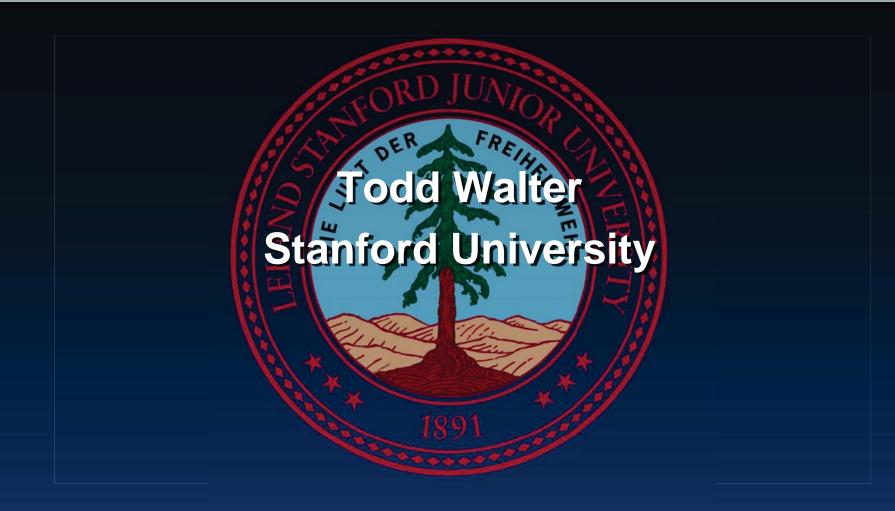
6 - 17 May 2013

Satellite Navigation for Guidance of Aircraft (Part 2)

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#### Satellite Navigation for Guidance of Aircraft



http://waas.stanford.edu





#### Honospheric Modeling

Ionospheric Threats
Next Generation Satellite Navigation
Future Signals
Conclusions



How Are Measurements Correlated Over Distance?

- Translate Our Measurements of the lonosphere Into User Corrections
- How Does the Ionosphere Behave Spatially?
  - What is the underlying structure?
  - What does one measurement tell us about the nearby ionosphere?
  - How should we combine multiple samples?
  - What confidence can we have in our prediction?
- We Need to Determine the Ionospheric Decorrelation Function



#### "Supertruth" Data

Raw Data Collected From Each WRS → 3 independent receivers per WRS Postprocessed to Create "Supertruth" Carrier tracks "leveled" to reduce multipath Interfrequency biases estimated and removed for satellites and receivers Comparisons made between co-located receivers (voting to remove artifacts) Multipath and Bias Residuals are ~50 cm +Without Voting, Receiver Artifacts Cloud **Results and Make It Impossible to See** Tails of the Distribution



#### **Decorrelation Estimation**

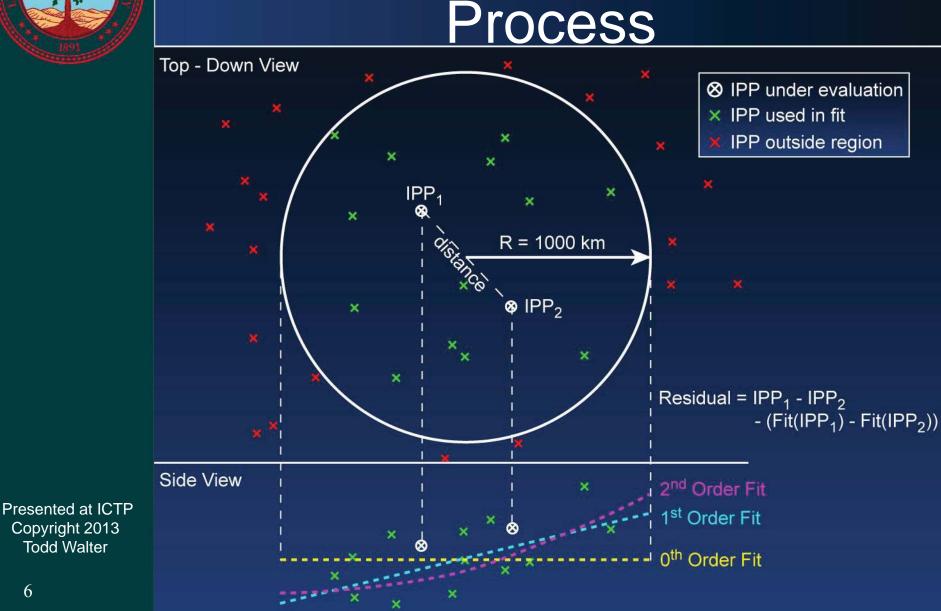
- Every Supertruth IPP Is Compared to All Others
- The Great Circle Distance Between the IPPs Is Calculated
- The Difference in Vertical Ionosphere Is Calculated
- A Two-dimensional Histogram Is Formed: Each Bin Corresponds to a Distance Range and a Vertical Difference Range

Presented at ICTP Copyright 2013 Todd Walter Histogram Contains the Counts for Each Time an IPP Pair Fell in a Particular Bin



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#### **Correlation Estimation**





#### Ionospheric Decorrelation (0<sup>th</sup> Order)

Vertical Ionosphere Correlation, 0th Order (CONUS, 2nd July 2000) 8 **10**<sup>4</sup> 6 d Number of Points per Pixel 5  $\Delta I_{v}$  (m) 3 2 **10**<sup>0</sup> 0 1000 2000 3000 4000 Distance (m)

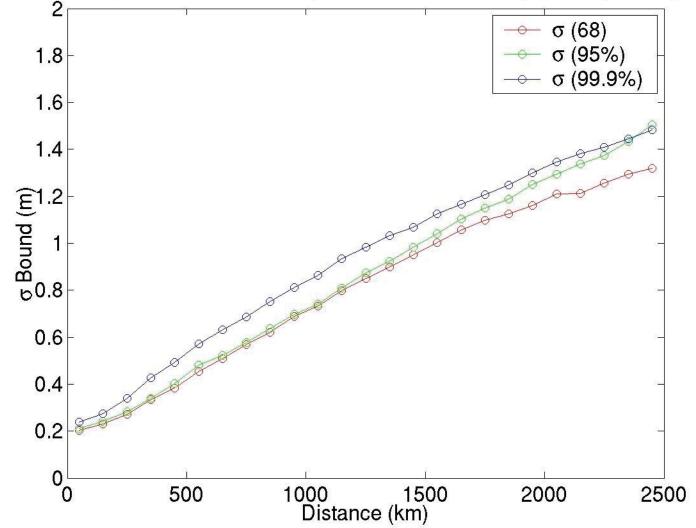
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## Ionospheric Decorrelation Function (0<sup>th</sup> Order)

Vertical lonosphere Containment σ, 0<sup>th</sup> Order Correlation (CONUS,2<sup>nd</sup> July 2000)





#### Preliminary Decorrelation Findings

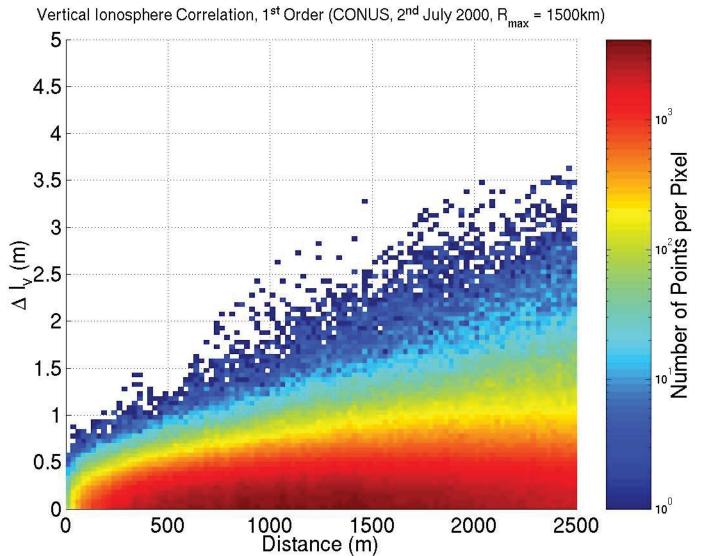
- Nominal Ionosphere is Relatively Smooth
  - Nearby IPPs Well Correlated
- Confidence About a Single Measurement Can Be Described As:
  - $\sigma^2 = \sigma_m^2 + (0.3 \, m + d * 0.5 \, m / 1000 \, km)^2$
- There Appears to Be a Deterministic Component

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Next Try Removing a Planar Fit



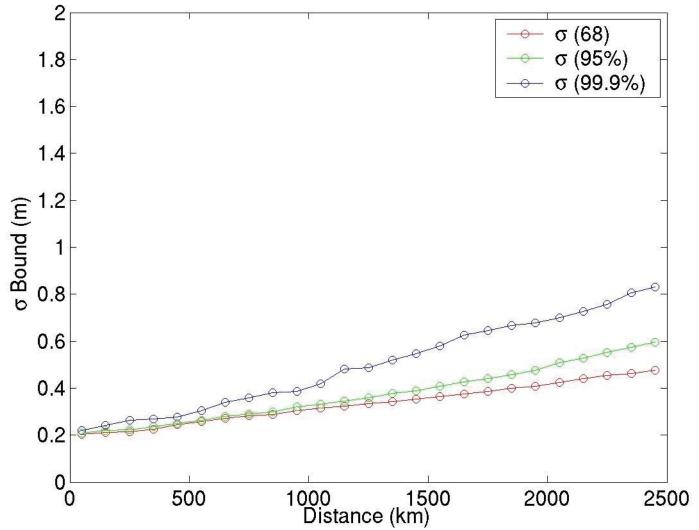
#### Ionospheric Decorrelation About a Planar Fit (1<sup>st</sup> Order)





## Ionospheric Decorrelation Function (1<sup>st</sup> Order)

Vertical lonosphere Containment o, 1st Order Correlation (CONUS, 2nd July 2000



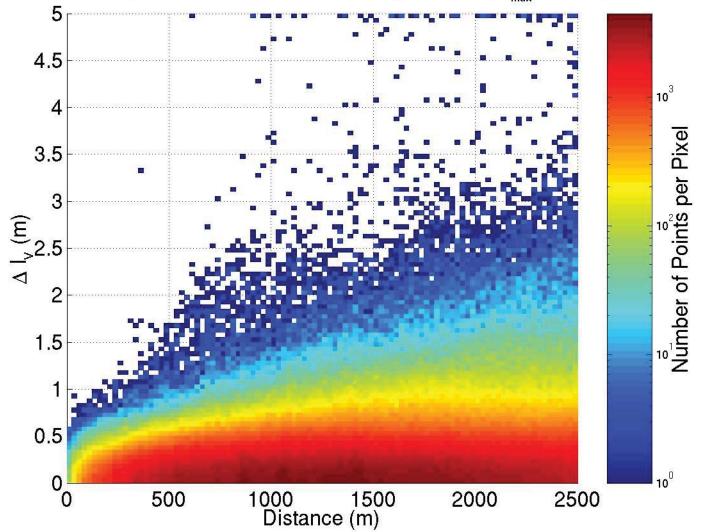
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## Ionospheric Decorrelation About a Quadratic Fit

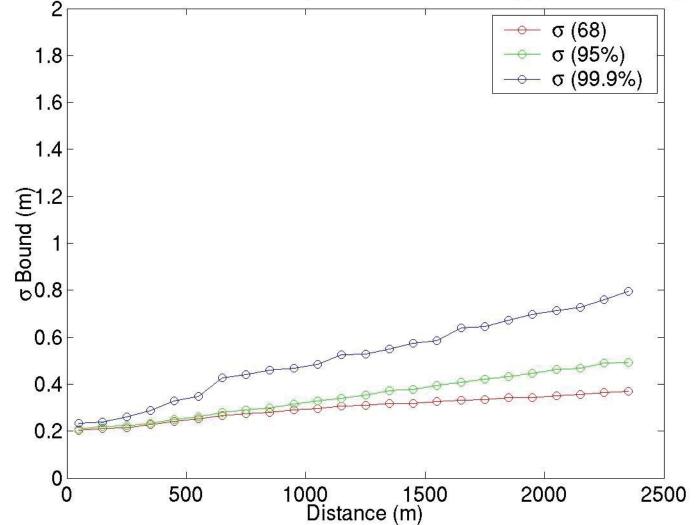
Vertical Ionosphere Correlation, 2<sup>nd</sup> Order (CONUS, 2<sup>nd</sup> July 2000, R<sub>max</sub> = 1500km)





### Ionospheric Decorrelation Function (2<sup>nd</sup> Order)

Vertical lonosphere Containment  $\sigma$ , 2<sup>nd</sup> Order Correlation, (CONUS 2<sup>nd</sup> July 2000

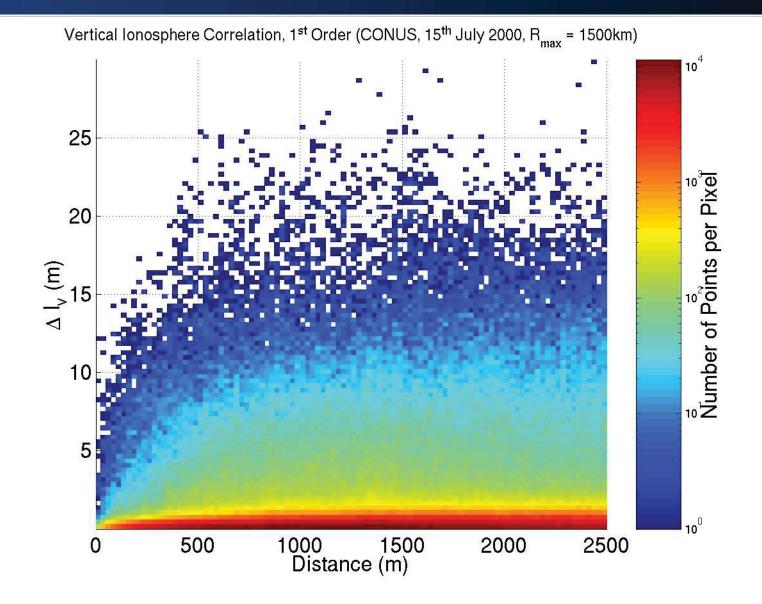


#### **Initial Decorrelation Summary**

Planar Fit Appears to Remove Nearly All Deterministic Elements No Decorrelation Variation With Elevation Angle or vs Day/Night Decorrelation appears to result from residual error in supertruth data →35 cm Valid for Mid-Latitude Nominal Decorrelation (R < ~1000 km) Decorrelation at Lower Latitudes Is Likely Different (larger, more orders?)



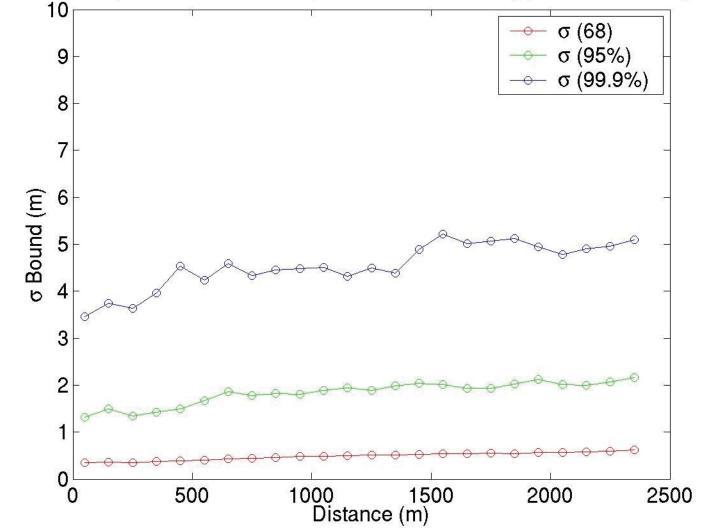
#### **Disturbed Ionosphere**





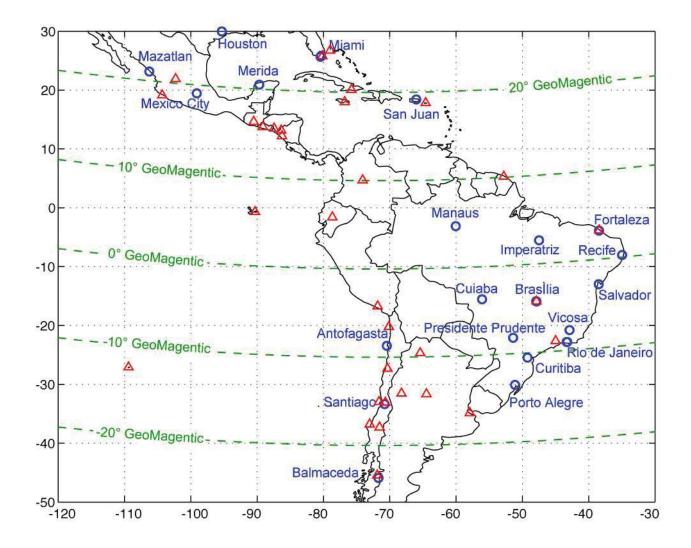
#### **Disturbed Ionosphere**

Vertical lonosphere Containment o, 1st Order Correlation, (CONUS 15th July 2000





#### Map of South American Stations





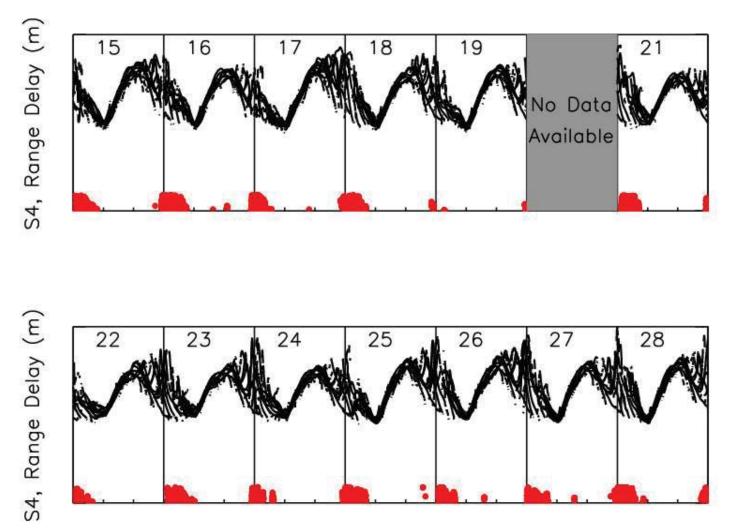
#### **Determination of Quiet Days**

First wish to identify "undisturbed" days to use as basis for "nominal" model

Want a day free of depletions and scintillation



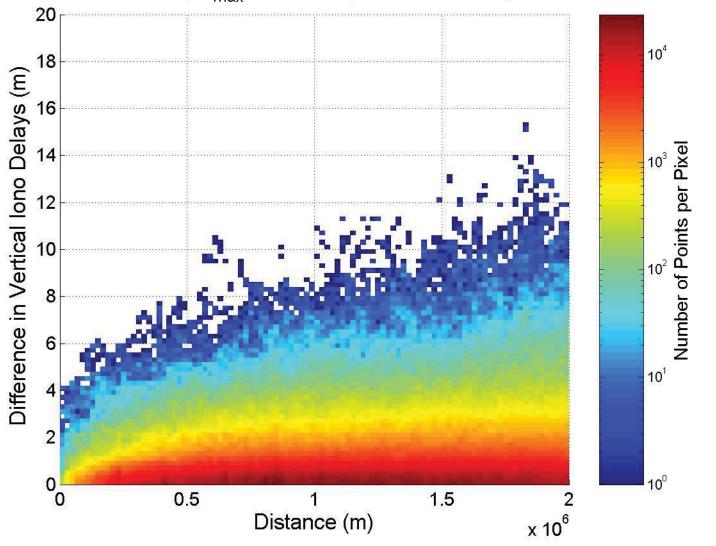
#### Daily Observations of TEC and S4





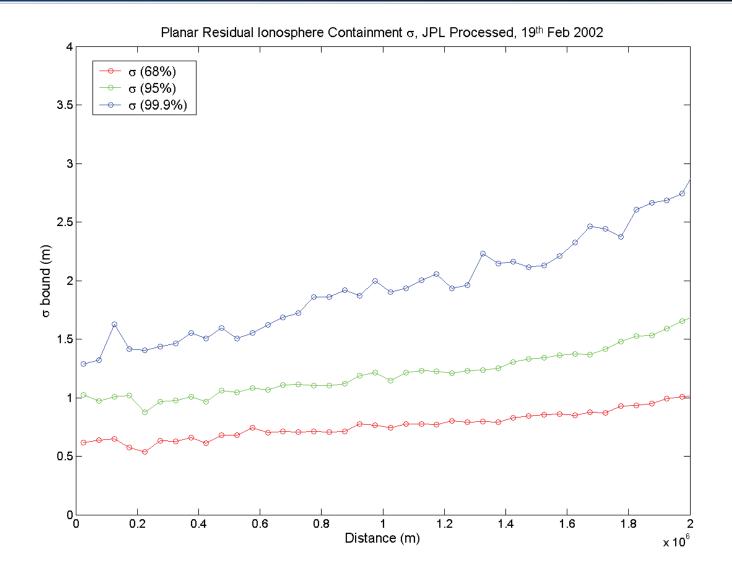
#### Two-D Histogram 1<sup>st</sup> Order

Residues of Planar Fit, R<sub>max</sub> = 1000 km, JPL Processed, 19<sup>th</sup> Feb 2002



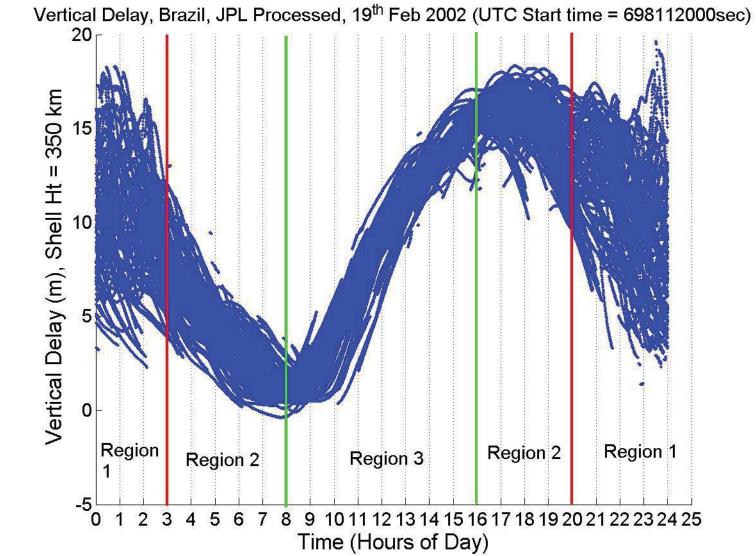


#### Sigma Estimate 1<sup>st</sup> Order



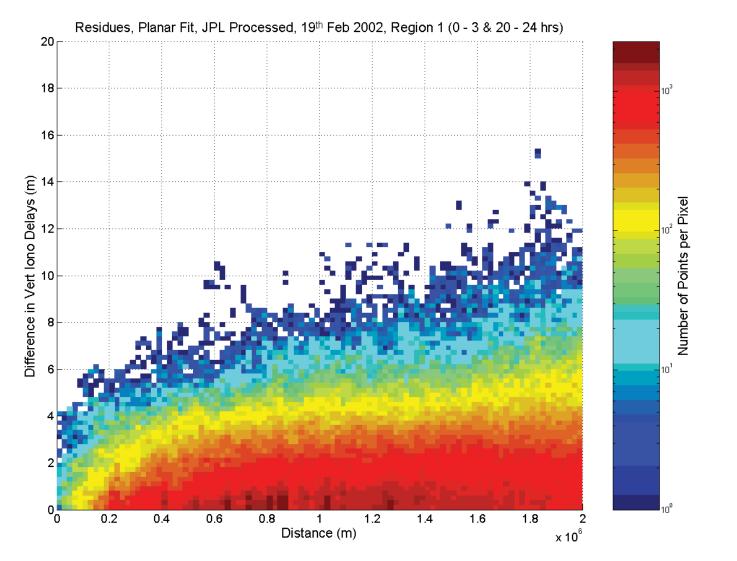


#### Vertical TEC



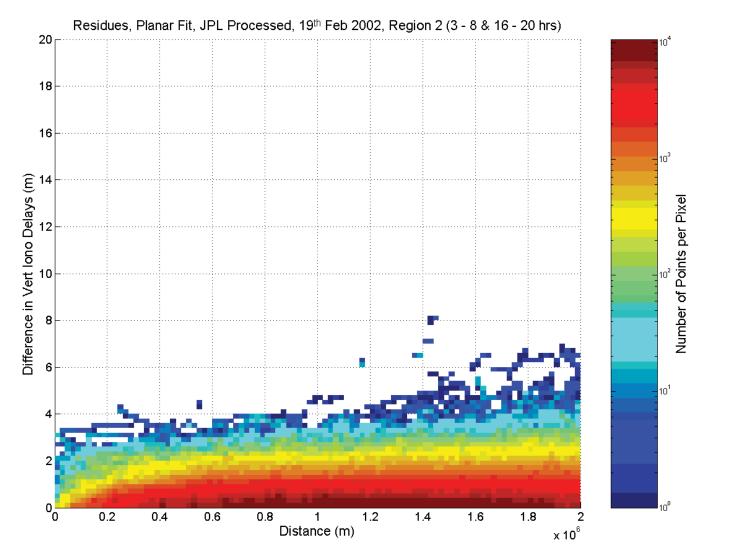


#### Two-D Histogram 1<sup>st</sup> Order (Region 1)



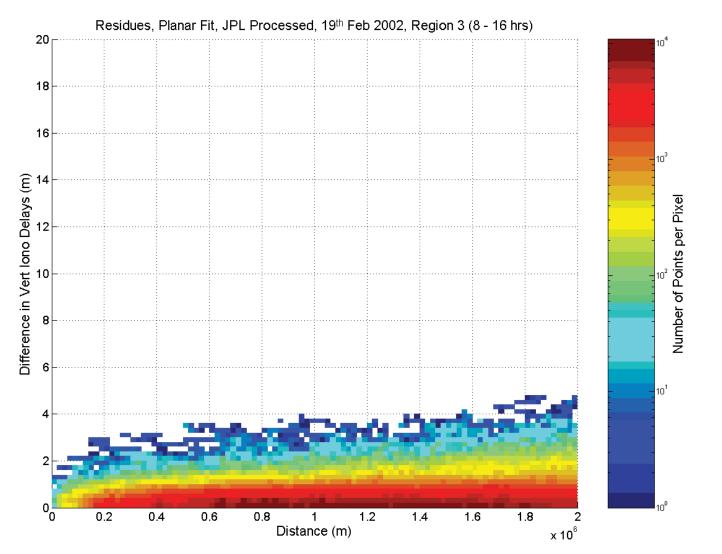


#### Two-D Histogram 1<sup>st</sup> Order (Region 2)



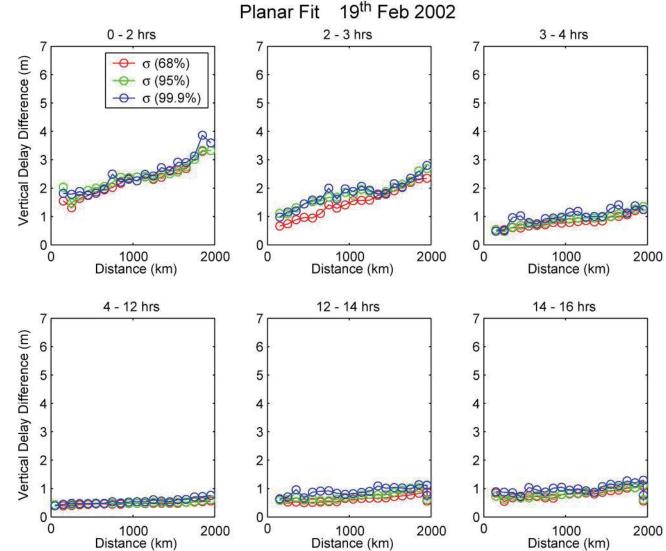


#### Two-D Histogram 1<sup>st</sup> Order (Region 3)



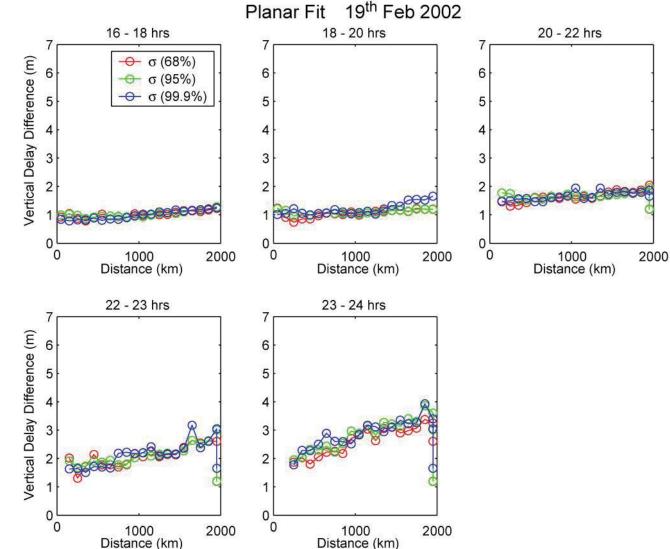


## Sigma Estimate 1<sup>st</sup> Order (Sliced by Time)





## Sigma Estimate 1<sup>st</sup> Order (Sliced by Time)



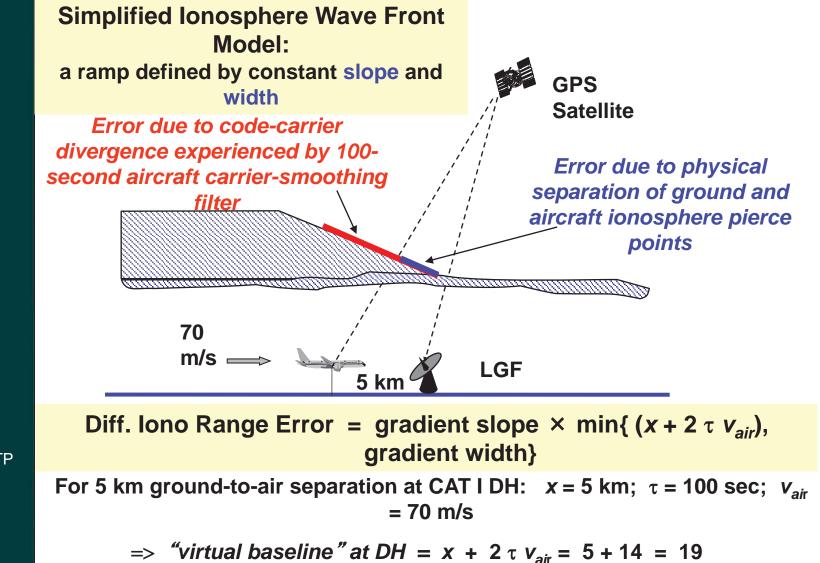


#### **Correlation Observations**

Clear temporal dependencies in the variogram ( $\sigma_{decorr}$  term) + Evening into nighttime is worst Daytime more easily modeled Clear spatial trends in the data → 1<sup>st</sup> and 2<sup>nd</sup> order model the trend about equally well, both better than O<sup>th</sup> order Random Component significantly larger than mid-latitude Gaussian over short times



## Contributors to Differential Ionosphere Error



#### Courtesy: Sam Pullen



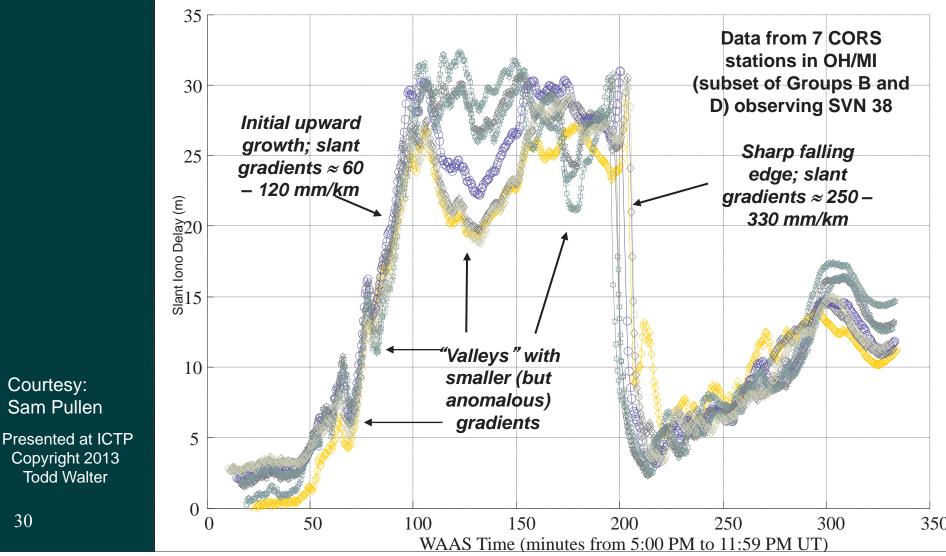
Courtesy:

Sam Pullen

Todd Walter

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#### **Ionosphere Delay Gradients** 20 Nov. 2003



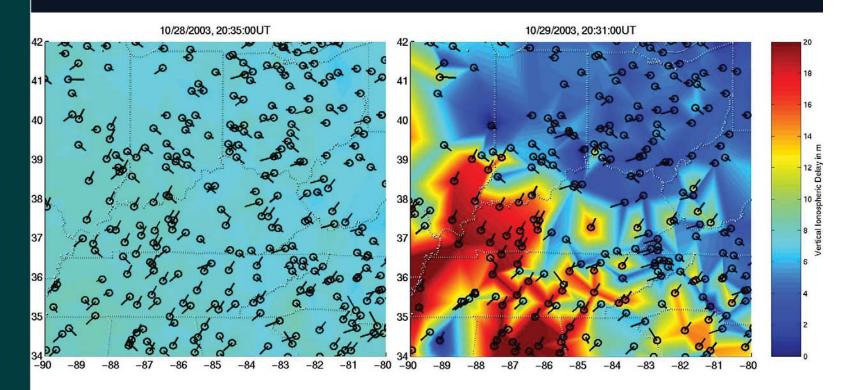


#### **SBAS** Ionospheric Threats

WAAS Was Commissioned on 10 **July 2003** → Availability > 99% for first 3 months October 29-31 Two Large **Disturbances Each Cause the Storm Detectors to Trip for Hours**  $\rightarrow$  Protection factor set to ~15 m 1-sigma November 20-21 Another Large **Disturbance Limits Vertical Guidance** for Several Hours



#### Failure of Thin Shell Model



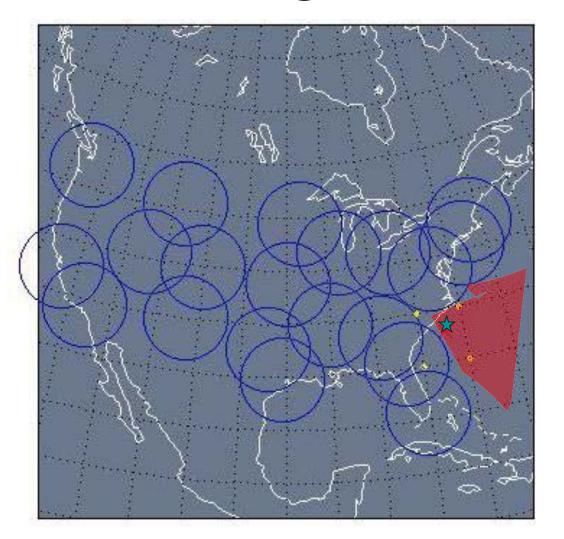
Disturbed Day

Quiet Day



#### Threats at the Edge of Coverage



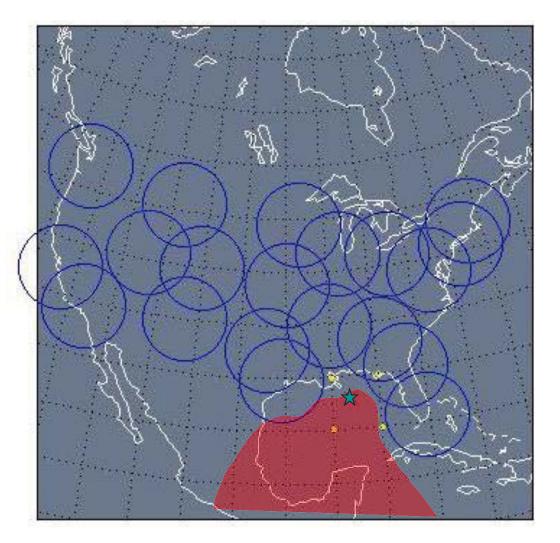


Courtesy: Seebany Datta-Barua



Edge of Coverage 2



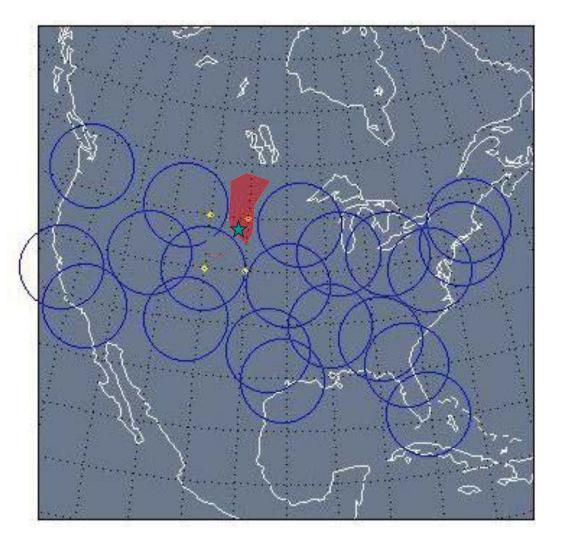


Courtesy: Seebany Datta-Barua



# Undersampling Within CONUS

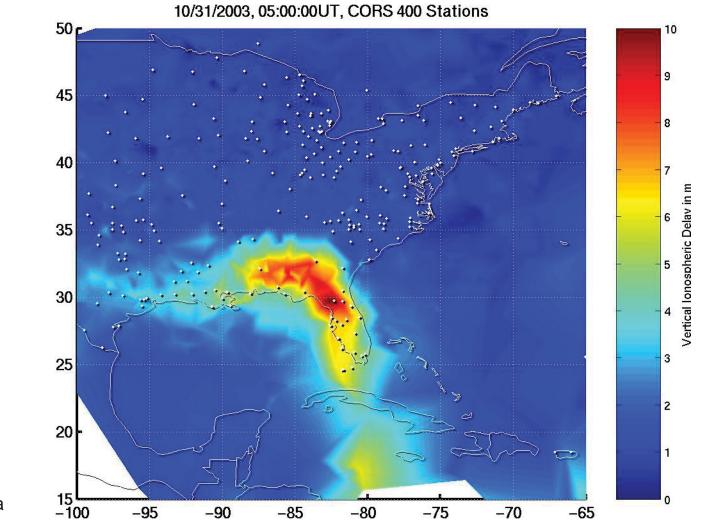




Courtesy: Seebany Datta-Barua



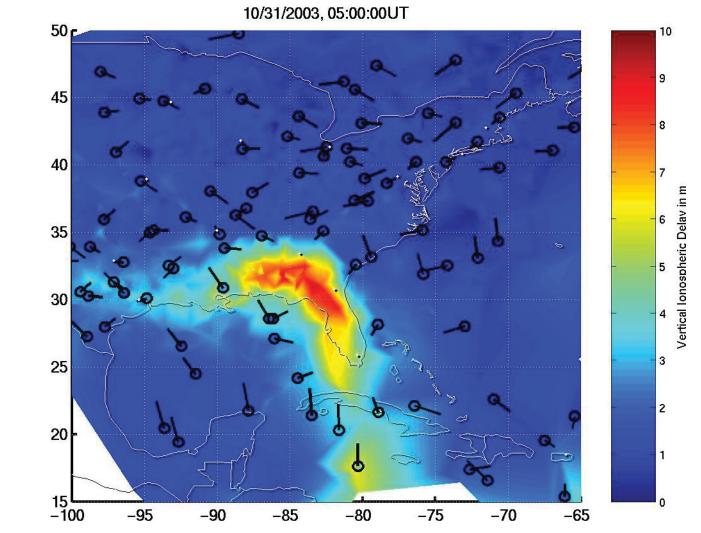






#### Artificial Undersampled Scenario

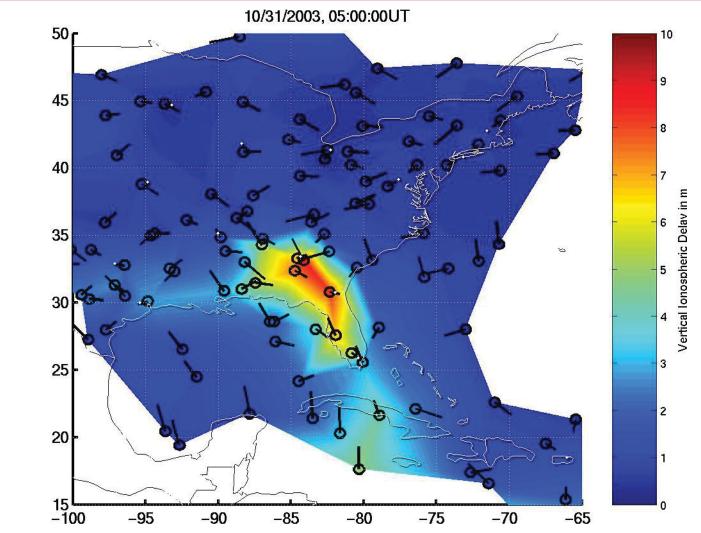






#### WAAS Measurements

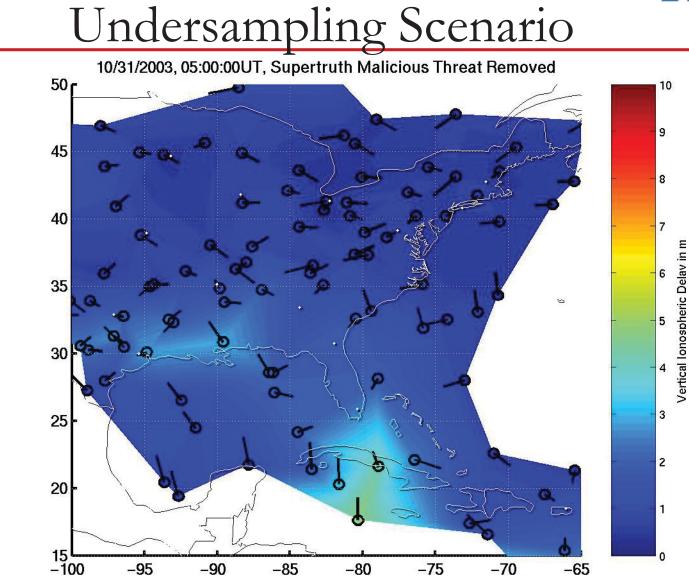






# Artificial WAAS

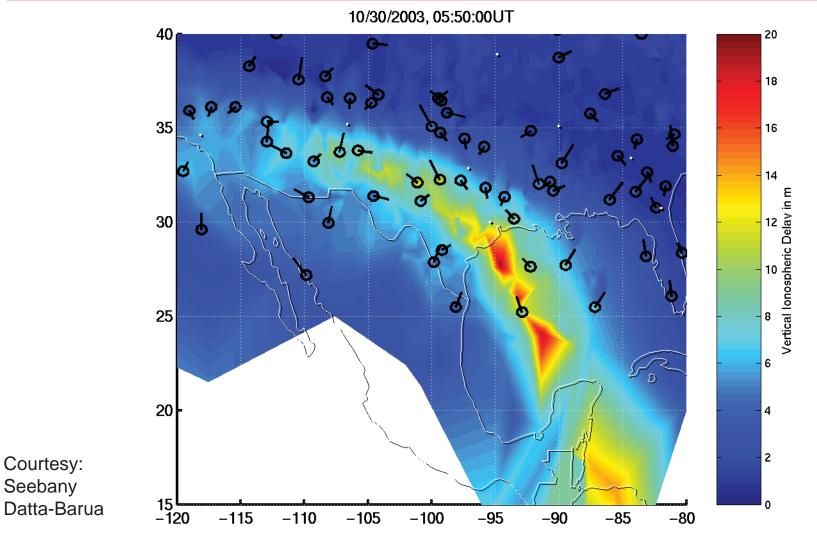






## Real Undersampled Condition

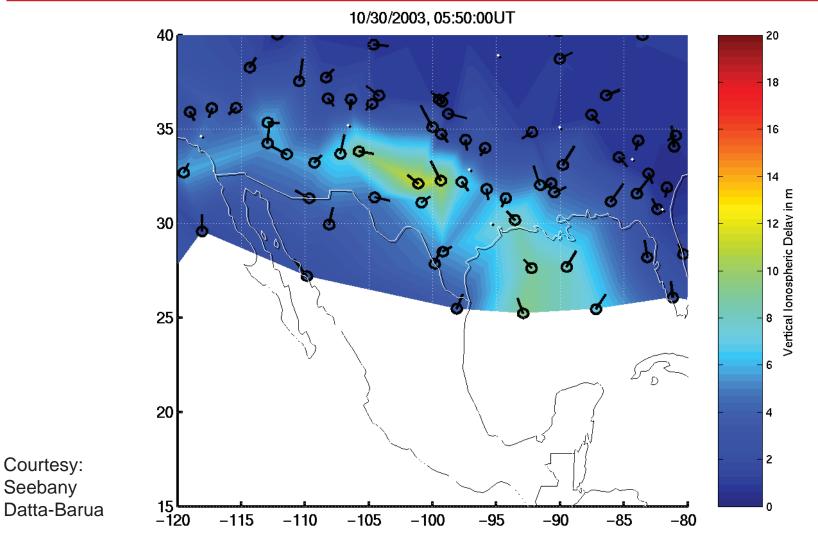




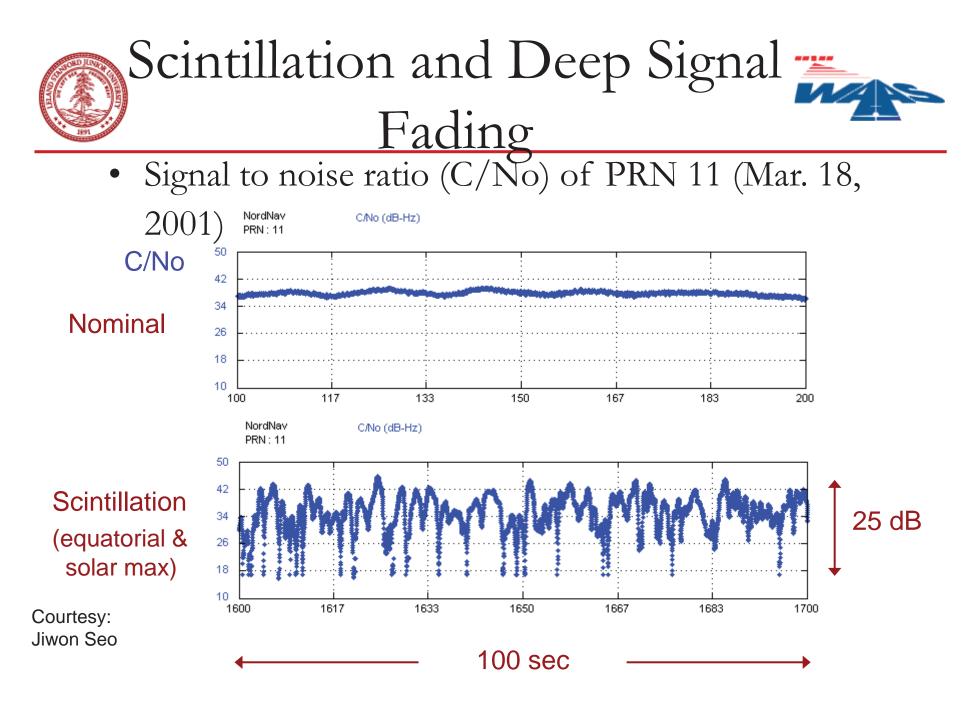


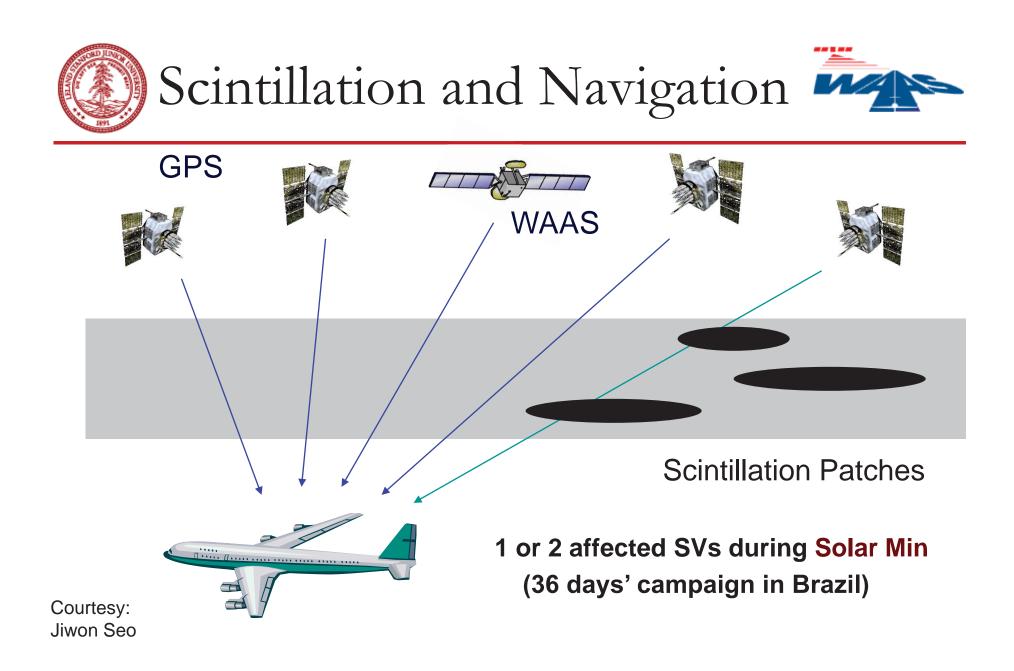
#### WAAS Measurements

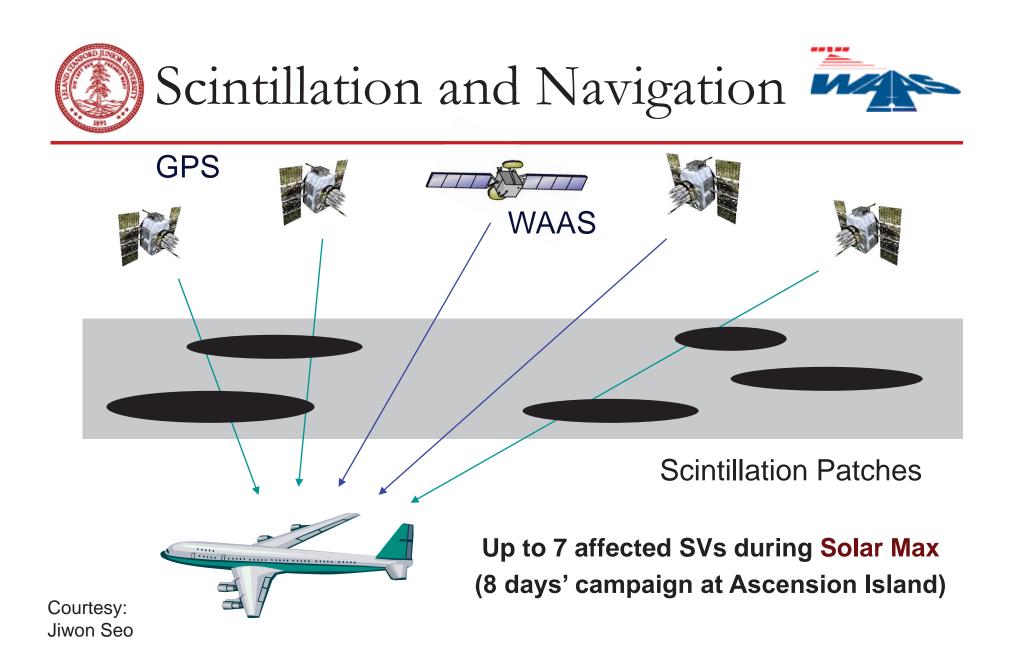




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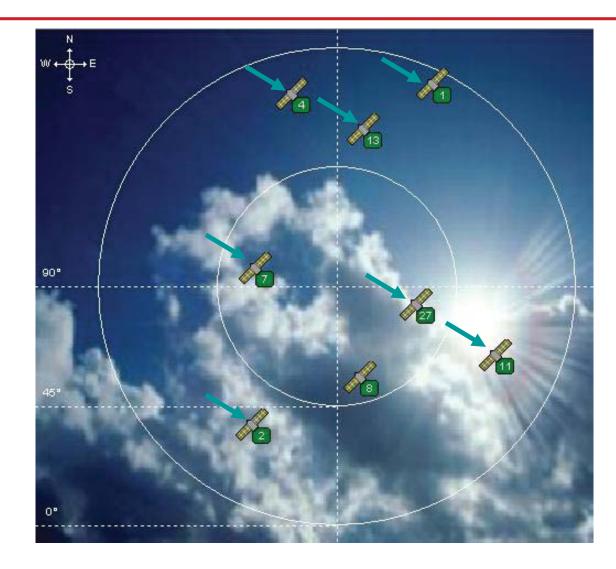








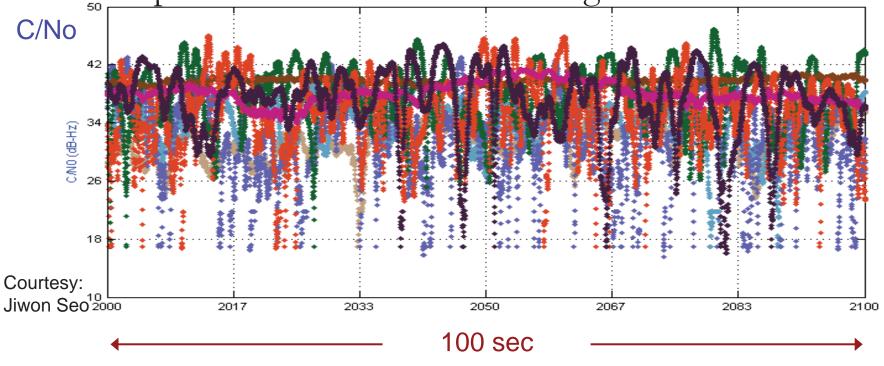
Solar Max (worst 45 min in 8 days)



Courtesy: Jiwon Seo



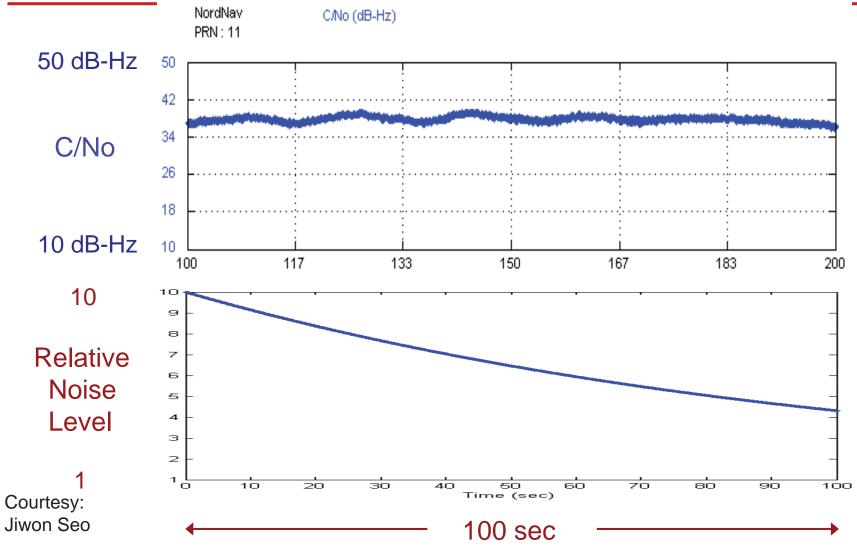
- 50 Hz C/No outputs of all 8 satellites on sky (100 sec out of 45 min data as an example)
- Number of simultaneous loss of satellites is more





#### Hatch Filter Model

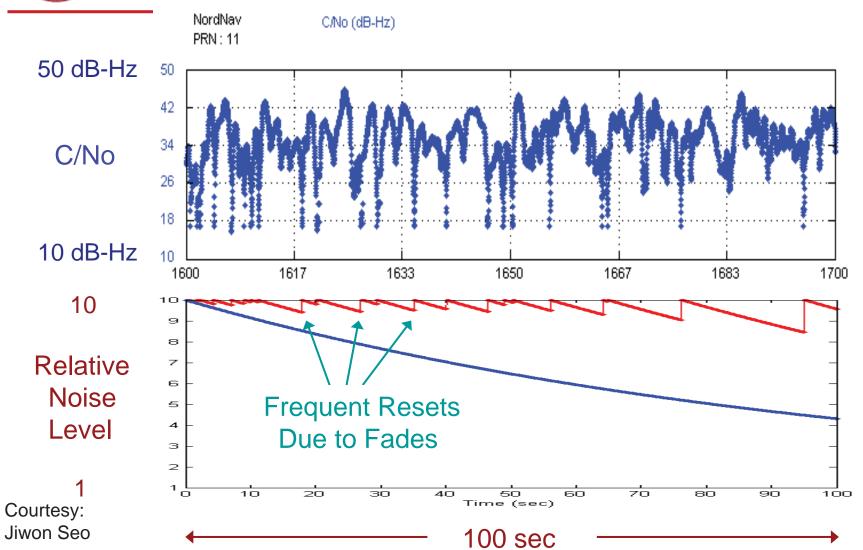






#### Hatch Filter Model







#### **Regions with Scintillation**

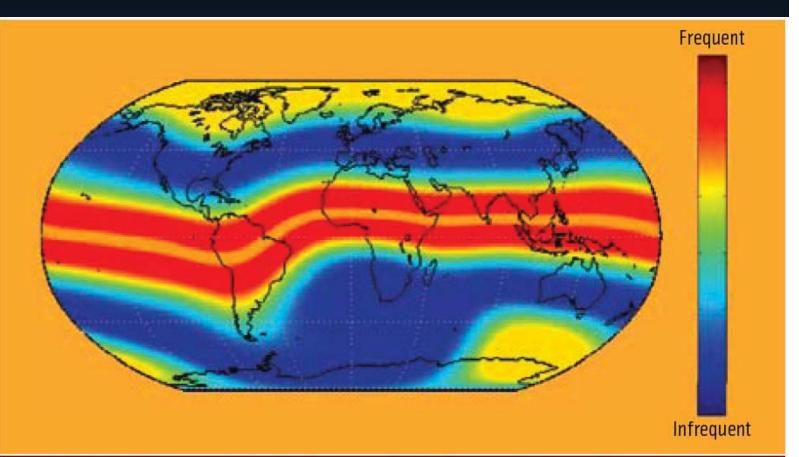


FIGURE 1 Scintillation map showing the frequency of disturbances at solar maximum. Scintillation is most intense and most frequent in two bands surrounding the magnetic equator, up to 100 days per year. At poleward latitudes, it is less frequent and it is least frequent at mid-latitude, a few to ten days per year.

Courtesy: Paul Kintner



#### Outline

 Ionospheric Modeling
 Ionospheric Threats
 Next Generation Satellite Navigation
 Future Signals
 Conclusions



#### Looking Ahead

Next generation of satellite navigation will exploit new signals and new systems

→ GPS is being modernized

Other nations developing SatNav

It is time to plan ahead

What new capabilities can we provide?

Are there more efficient ways to provide them?



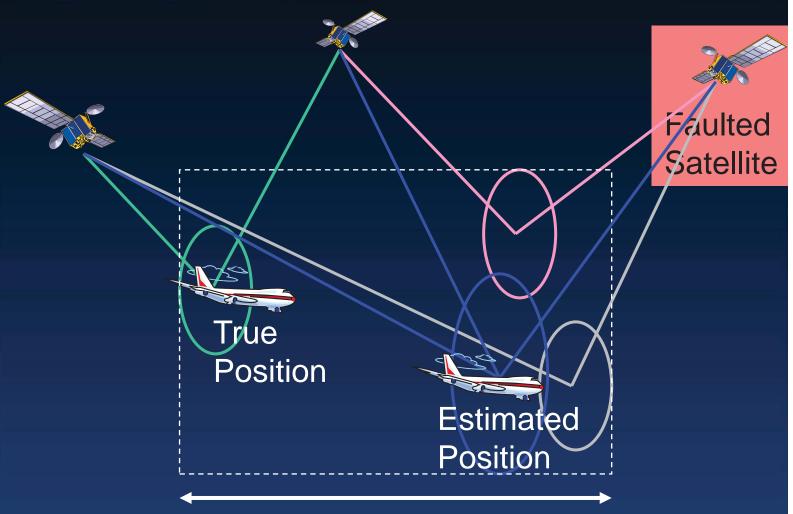
#### **RAIM Protection**

Horizontal Error Bound

Courtesy: Juan Blanch



#### **RAIM Protection**



Horizontal Error Bound

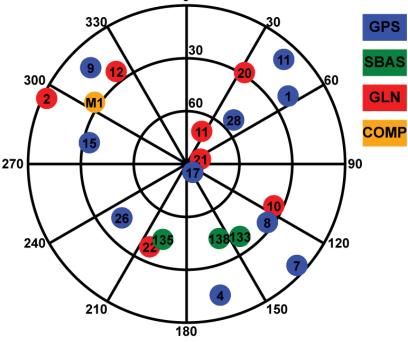
Courtesy: Juan Blanch



#### **New GNSS Constellations**

A solution to constellation weakness
Many more ranging sources
Fills in gaps
Provides extra redundancy

Averages down uncertainty





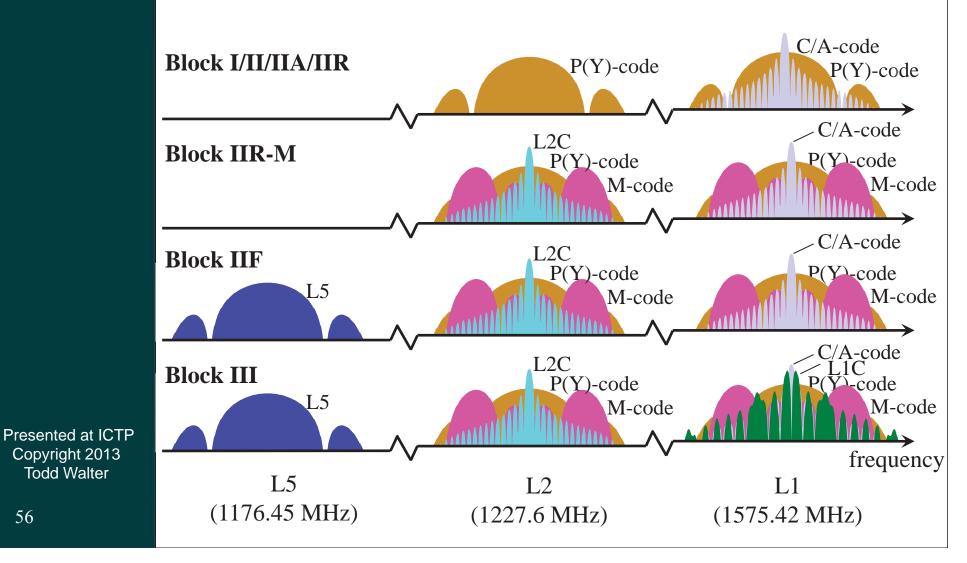
#### Advanced RAIM (ARAIM)

Dual Frequency - Multi-constellation Eliminates multiple SV iono threat → Strong geometries Support for vertical guidance + Requires a more stringent level of certification than RAIM for lateral May require ground monitoring by approving agency Potential for near global coverage Modest infrastructure requirements



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#### **GPS** Signals

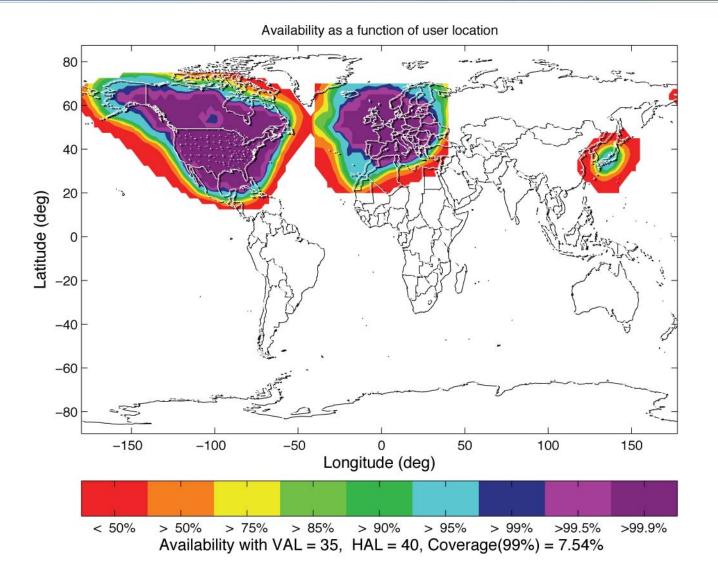




## WAAS EGNOS MSAS

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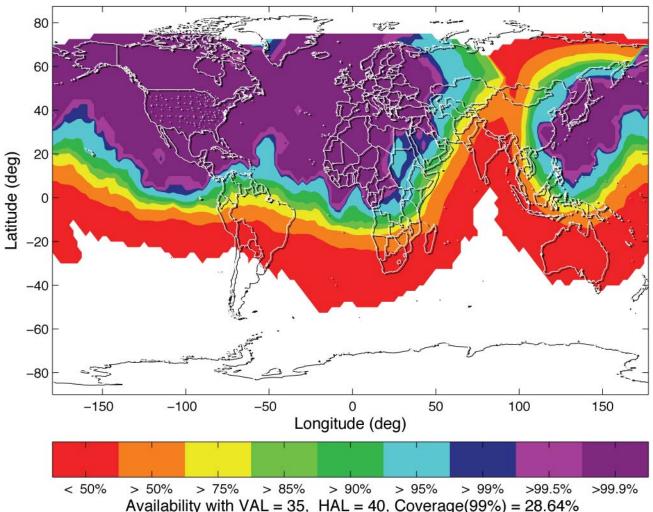
#### Current SBAS Coverage





## Dual Frequency Coverage (WAAS, EGNOS, MSAS)

Availability as a function of user location

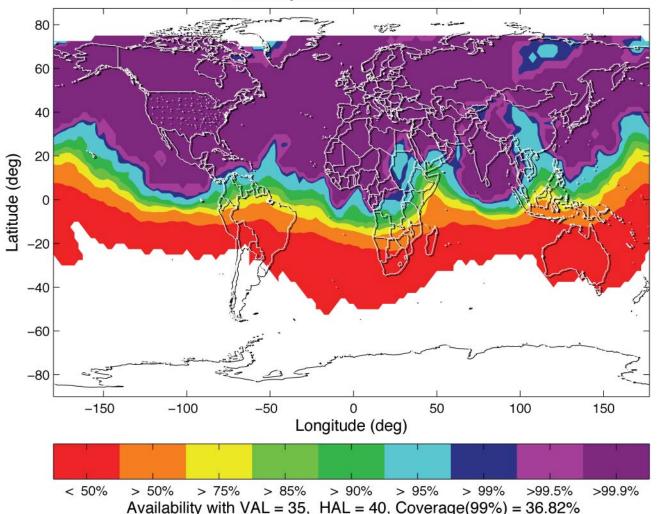


WAAS EGNOS MSAS



## Dual Frequency Coverage (with GAGAN + Russia)

Availability as a function of user location

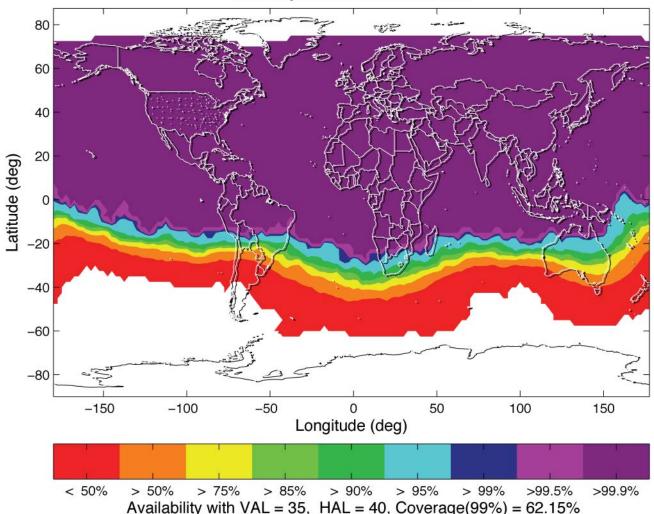


WAAS EGNOS MSAS GAGAN SDCM



## Dual Frequency + Second Constellation (Galileo)

Availability as a function of user location

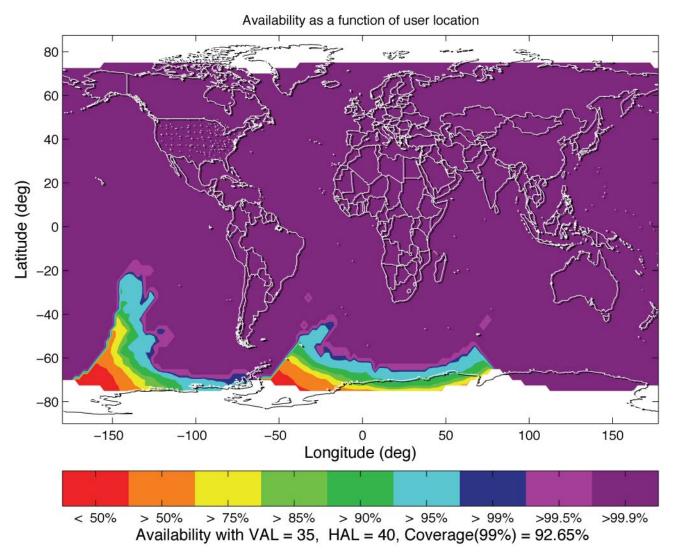


WAAS EGNOS MSAS GAGAN SDCM



## Dual Frequency, Dual GNSS, Expanded Networks

WAAS EGNOS MSAS GAGAN SDCM





Conclusions

→GNSS can be used to provide aircraft navigation for all levels of service Integrity is a key concern Important to understand what can go wrong and how to protect users Observation and data collection are key to understanding behavior A long history of careful and consistent data monitoring are required Practical experience leads to trust and acceptance



#### Outline

Ionospheric Modeling →Ionospheric Threats Other Integrity Threats Integrity Methodology Next Generation Satellite Navigation Future Signals Conclusions



## Integrity

Monitor network or signal redundancy identifies observable threats
 Protection against satellite failures
 Ephemeris errors
 Clock errors
 Signal errors
 Protection against ionospheric errors

Presented at ICTP Copyright 2013 Todd Walter Design assumes worst credible values for all unobservable threats

#### Satellite Ephemeris Anomaly **Observed GPS SPS 3-D Position Errors on** April 10, 2007 Source: FAATC GPS SPS PAN Report #58, 31 July 2007. SPS 3D Position Error During PRN18 Anomaly: 10 April 2007 600 PRN18 Range Error (at Honolulu) Satellite Health × Billings Honolulu 8 500 Los Angeles 400 Error (Meters) PRN18 Marked Unhealthy at 234240 300 200 Presented at ICTP 100 Copyright 2013 Todd Walter 0 65 228000 230000 232000 234000 236000 238000 240000

GPS Time of Week (Seconds)



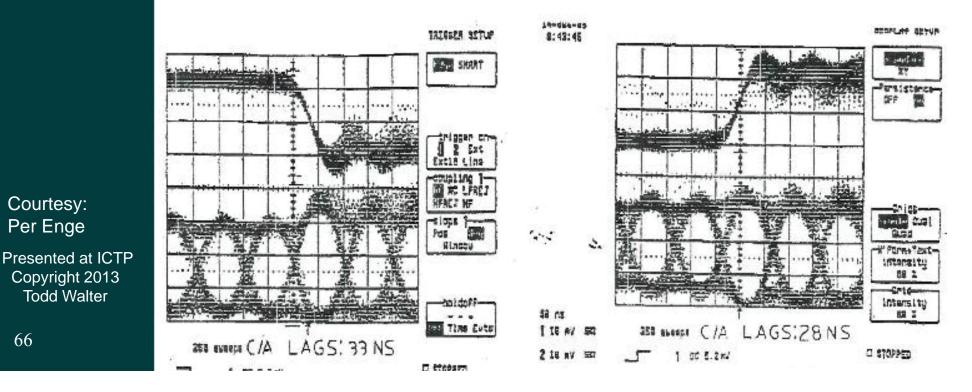
66

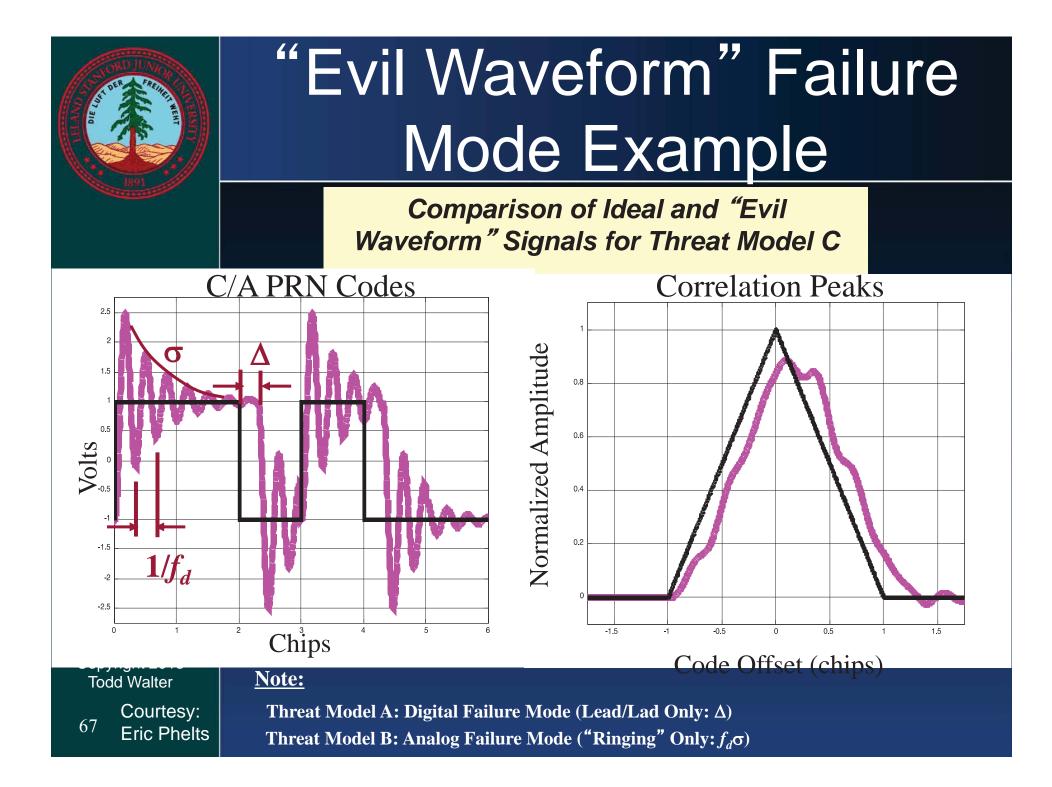
#### Satellite Signal Anomaly

#### L1 C/A Lags L1 P Code Falling Edge or Leading Edge

Oct 13, 1993, 23:45











Ionospheric Modeling →Ionospheric Threats Other Integrity Threats Integrity Methodology Next Generation Satellite Navigation Future Signals Conclusions



#### **Overall Integrity Approach**

Conventional Differential GPS Systems Rely on Lack of Disproof "I've been using it for N years and I've never had a problem" →10<sup>-7</sup> Integrity Requires Active Proof Analysis, Simulation, and Data Must Each Support Each Other None sufficient by themselves Clear Documentation of Safety Rationale is Essential



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of HMI < 10<sup>-7</sup> Per Approach" Possible Interpretations Ensemble Average of All Approaches **Over Space and Time** Ensemble Average of All Approaches Over Time for the Worst Location Previous Plus No Discernable Pattern (Rare & No Correlation With User Behavior)

Interpretation of "Probability

Worst Time and Location



## Probability of Integrity Failure

#### Average Risk



#### Specific Risk

*P*(*fault* | *condition*)

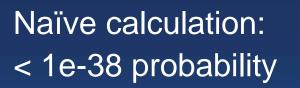


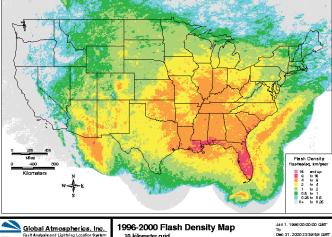
## Probability of Being Struck by Lightning

From the Lightning Safety Institute
USA population = 280,000,000
1000 lightning victims/year/average
Odds = 1 : 280,000 of being struck by lightning

Not everyone has the same risk

One person struck 7 times







#### WAAS Interpretation

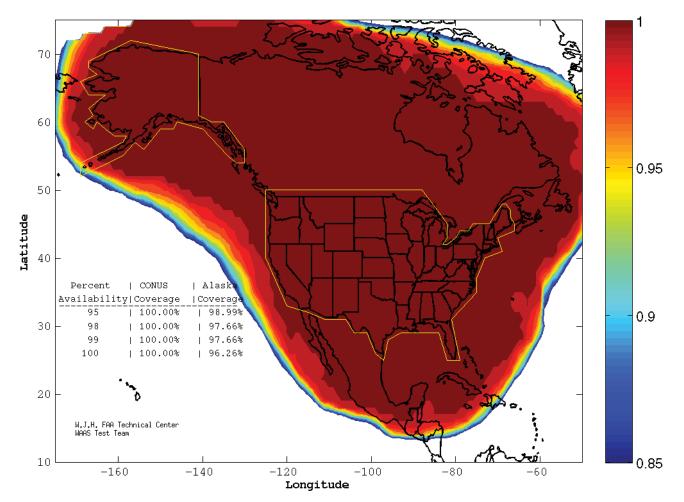
Events handled case by case  $\rightarrow$  Events that are rare and random may take advantage of an *a priori* Deterministic events must be monitored or treated as worst-case Events that are observable must be detected (if risk >  $10^{-7}$ ) Must account for worst-case undetected events



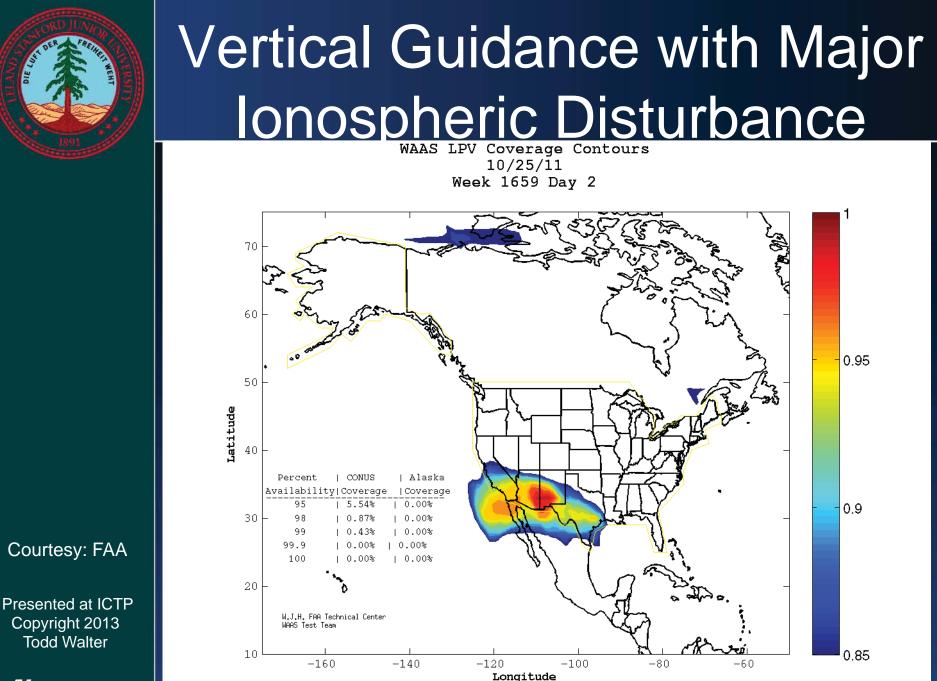
#### Nominal WAAS Vertical

## Guidance Performance

04/22/11 Week 1632 Day 5



Courtesy: FAA

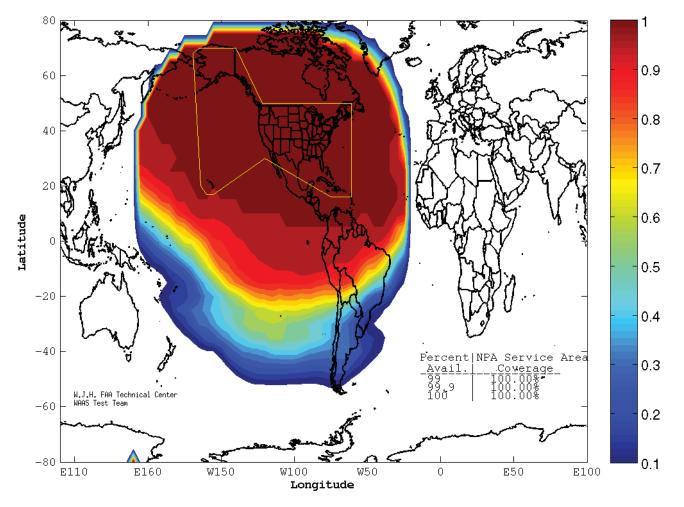




## Nominal WAAS Horizontal

#### Guidance Performance

04/22/11 Week 1632 Day 5



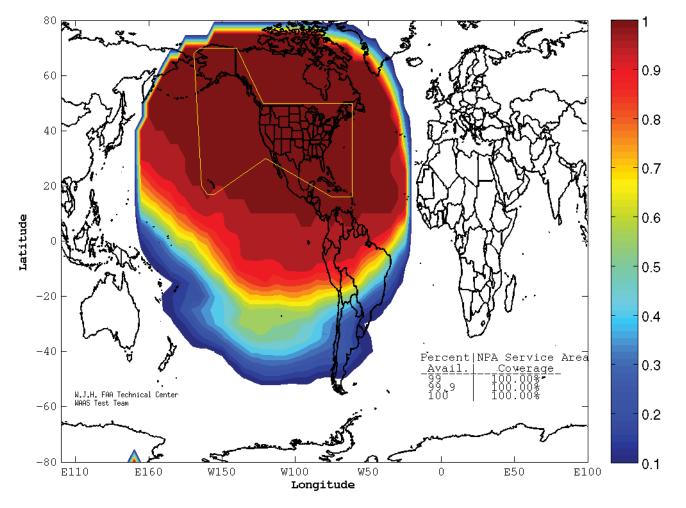
Courtesy: FAA



# Horizontal Guidance in Major

## Ionospheric Disturbance

10/25/11 Week 1659 Day 2



Courtesy: FAA