

Benefits of GNSS software receivers for scientific applications



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DI TORINO**

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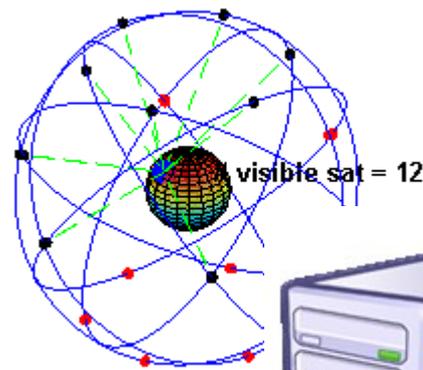
Department of Electronics and Telecommunications (DET)

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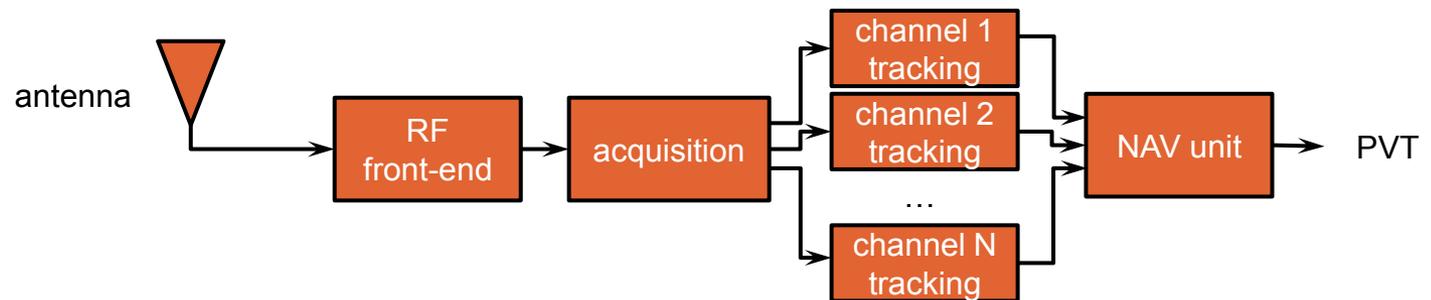
- The concept of software receivers
- An example: N-GENE GNSS software receiver
 - Advantages
 - Case studies
- Scientific applications of GNSS software receivers
 - Remote sensing and reflectometry
 - Ionospheric scintillation monitoring
 - Vietnam
 - Antarctica



Navigation satellite systems and software receivers



- GNSSs are communication systems
- Each GNSS receiver is a suboptimal implementation of a maximum likelihood estimator of the **propagation delay** of the signal
- It exploits GNSS signals characteristics:
 - CDMA code delay
 - Carrier Doppler frequency



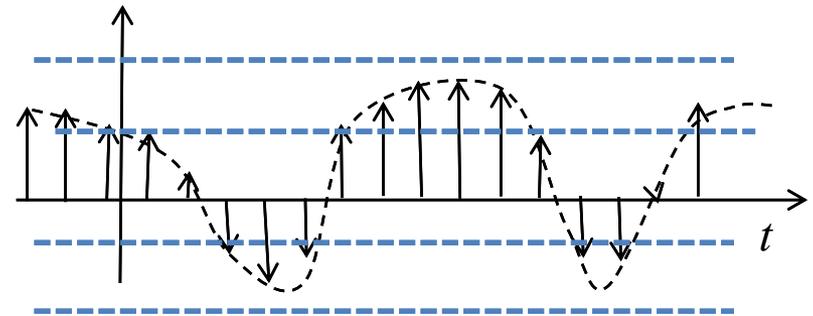
- Traditionally **hardware** receivers

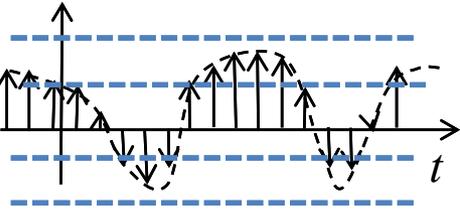
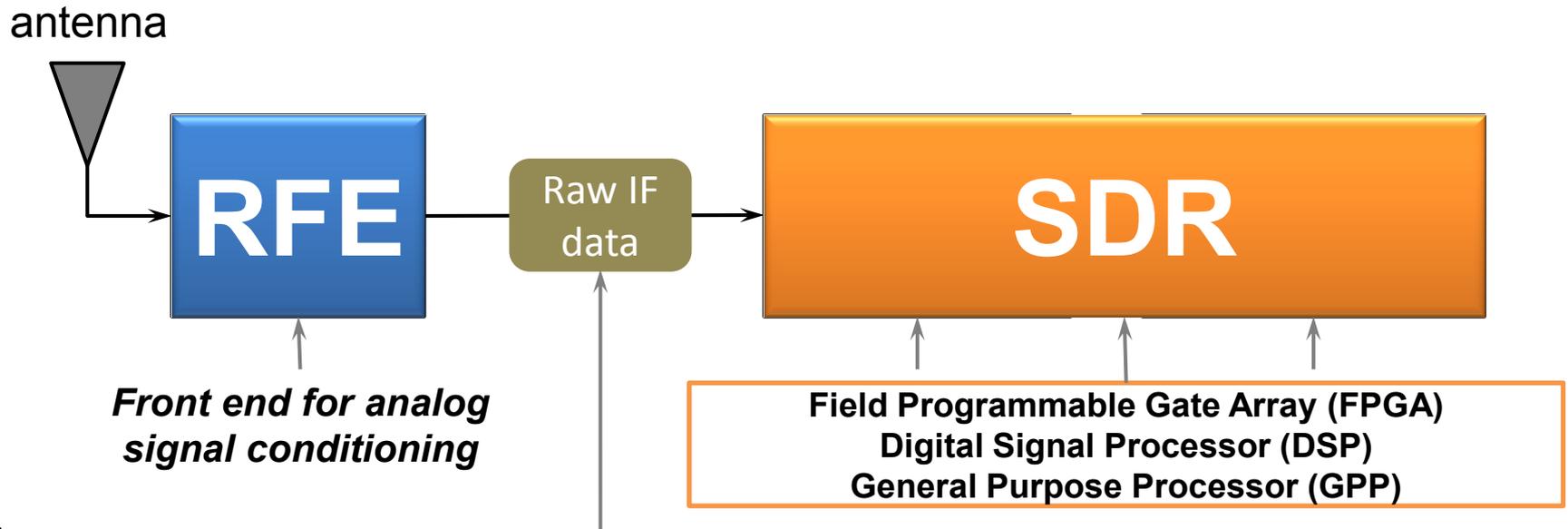
Software Defined Radio (SDR) receivers

- Ensemble of hardware and software technologies enabling reconfigurable communication architectures
- First theoretical concept: 1984
- Growing attractiveness in R&D sectors:

SDR	Hardware
Lower development costs	More efficient
Shorter development time	High volume markets
Easier maintainability	Strict size and power requirements
Upgradability, flexibility, re-configurability potentialities	

- SDR has naturally entered the field of navigation receivers
 - GNSS popularity
 - GNSS signals characteristics
 - Small bandwidth
 - Receiver only system
 - Low data rates
 - Possibilities offered by digital domain analysis





GBs of data!

- Down-converted at IF
- Analog to digital converted (ADC)
- Sampled at a certain f_s
- Quantized
- Stored in memory as binary file

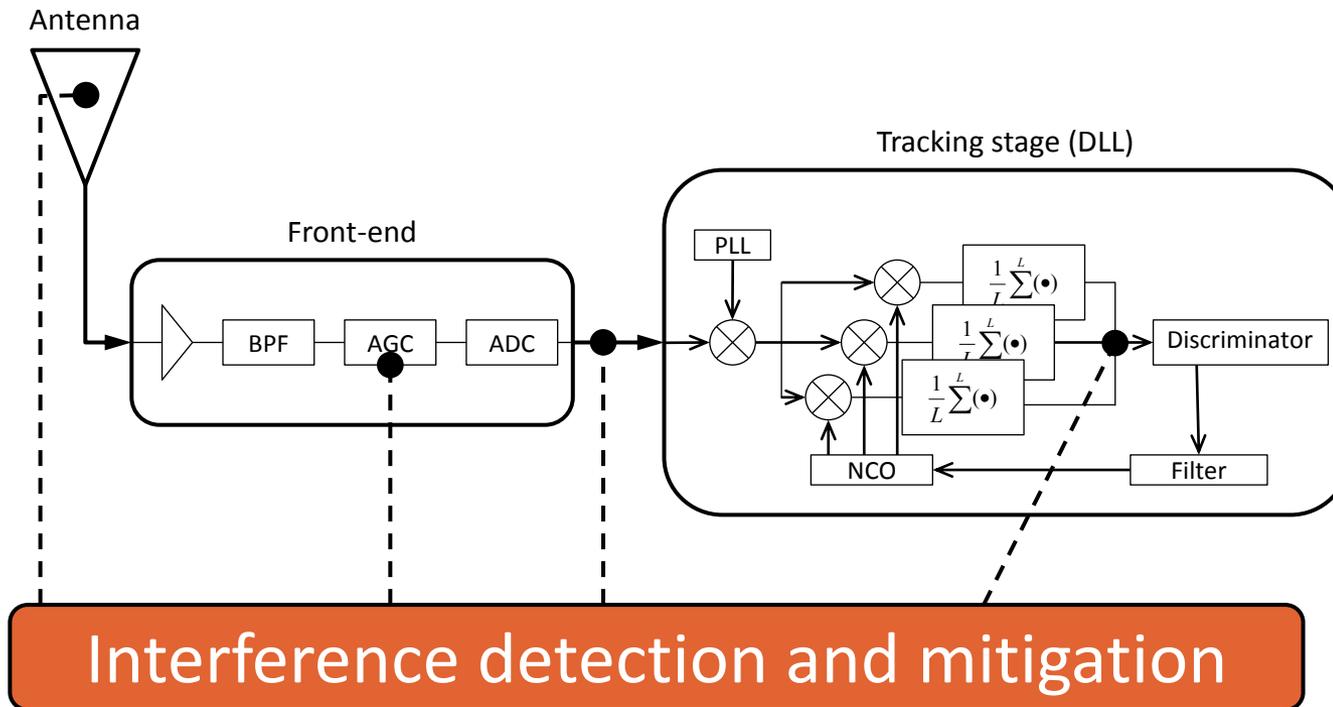
- 1. Classic:**
FPGA + DSP + PC
- 2. Fully software:**
GPP

ACCESSIBILITY

CONFIGURABILITY

MODULARITY

- Low level processing stages, unconventional outputs



ACCESSIBILITY

CONFIGURABILITY

MODULARITY

- Galileo first acquisition and tracking
- Galileo-only first PVT
- Galileo 5 and 6



First Acquisition and Tracking

Europe's GNSS program – Galileo – entered a new phase of development with the recent launch of two in-orbit validation satellites, which comprise the first elements of the system's fully operational constellation. In this article, a team of Italian researchers present the initial results of their analysis of the Galileo signals.

NAVIGATION, SIGNAL ANALYSIS AND SIMULATION (NAVSA) GROUP
POLITECNICO DI TORINO/ISTITUTO SUPERIORE MARIO BOELLA

On December 12, 2012, the two Galileo in-orbit validation (IOV) satellites were launched on October 21 — the first Galileo satellite started transmitting its payload on the E1 band over Europe.

That same day NavSAS researchers were able to acquire and track the Galileo Code Number

esa

GALILEO IOV

The European Space Agency wishes to thank
NavSAS research group
Via Pier Carlo Boggio 61
Torino, Italy

for the successful Galileo position fix made
on 12 March 2013 from 10:49 to 11:00 UTC
Lat.: 45° 03' N
Long.: 7° 39' E
Alt.: 311.96 m

This award is granted to the first 50 users of the Galileo system.

Didier Faivre
Director of the Galileo Programme
and navigation-related activities

Didier Faivre

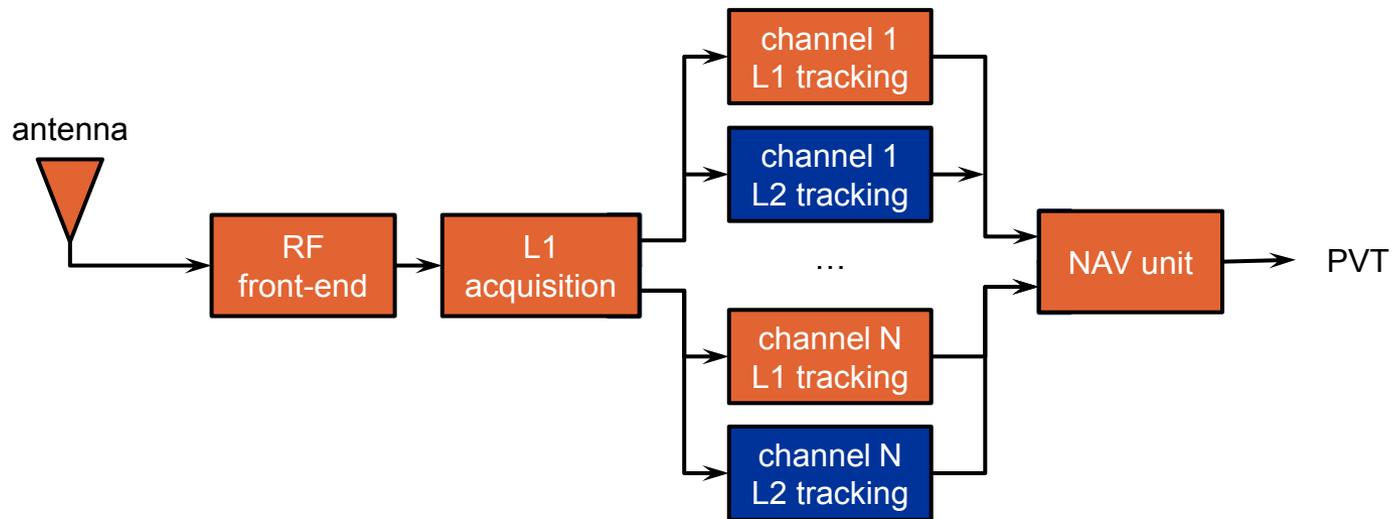
European Space Agency

ACCESSIBILITY

CONFIGURABILITY

MODULARITY

- Block structure: possibility to add new techniques
 - P(Y) codeless tracking
 - **Multiconstellation**





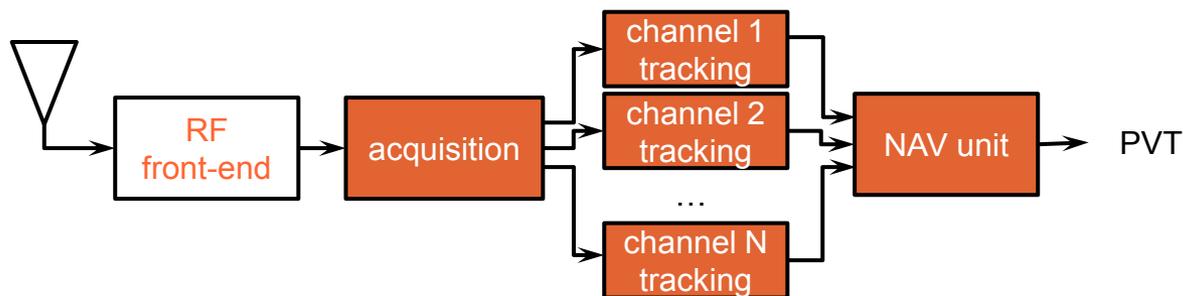
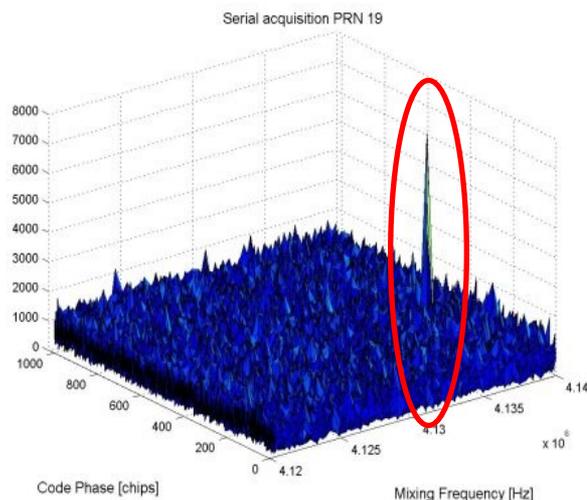
N-GENE



N-GENE fully software receiver



- Real time
- GPS L1 C/A, Galileo E1 OS, EGNOS
- Code measurements + carrier smoothing
- Standard PC Intel x86 processor, with Linux OS
- Process the output of a RFE through USB



Navigation display output



Menu

General Channels Terminal IF Spectrum IF Histogram C/N0 Last Estimate Satellites Map

General

PVT is valid
 LGNOS is not used

Time

GPS Time: 11:15:0 GPS Week Number: 1517
 Galileo Time: 0:0:0 Time of Week: 472500
 UTC Time: 11:14:46

Geodetic Position

	Latitude	Longitude	Altitude
Current	+45°03'54.96"	+7°39'32.13"	308.537
Minimum	+45°03'54.90"	+7°39'31.88"	282.168
Maximum	+45°03'55.29"	+7°39'32.33"	340.736
Average	+45°03'55.11"	+7°39'32.12"	317.472
Std Dev	+0°00'0.09"	+0°00'0.10"	11.51
Variance	+0°00'0.00"	+0°00'0.00"	132.484

Velocity

	Latitude
Current	0.014
Minimum	0.014
Maximum	0.014
Average	0.014
Std Dev	0.014
Variance	0.014

Satellites

Tracked Not Tracked

ECEF Position

	X
Current	4,472,418

Dilution of Precision

	GDOP
Current	3.073
Minimum	0
Maximum	240.052
Average	28.473
Std Dev	68.641
Variance	4,711.523

C/N0 Last Estimate

C/N0 Last Estimate

Channel	db-Hz
GPS6	40
G...	40
GPS3	40
G...	40
GPS1	35

Application Status: ACQUIRING

System Status: READY

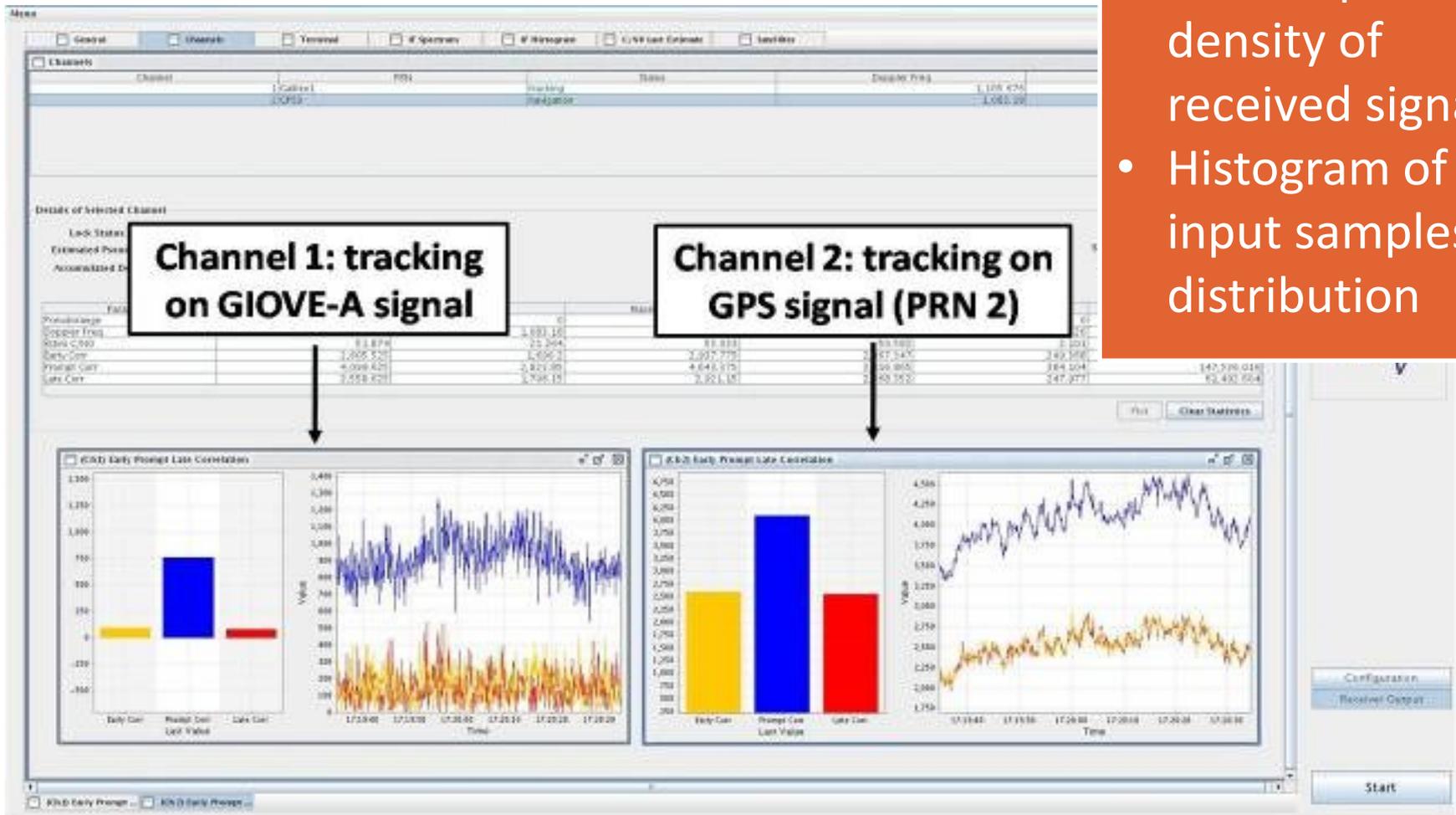
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Configuration
 Receiver Output

Stop

Unconventional outputs

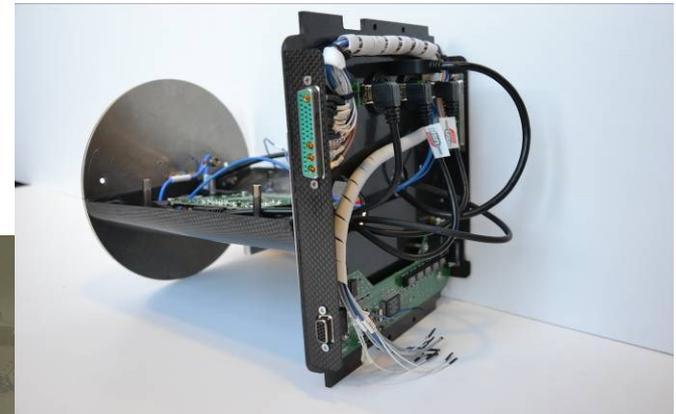
- Power spectral density of received signal
- Histogram of input samples distribution



- Real time processing of GNSS data from antenna
 - Requirements on sampling frequency
- Post-processing of stored raw samples
 - Repeatability, comparison
 - Useful for testing and prototyping
 - Working tool



Scientific applications: remote sensing and reflectometry

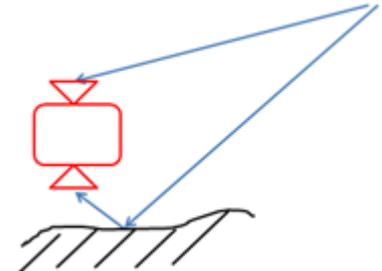


Remote sensing and reflectometry

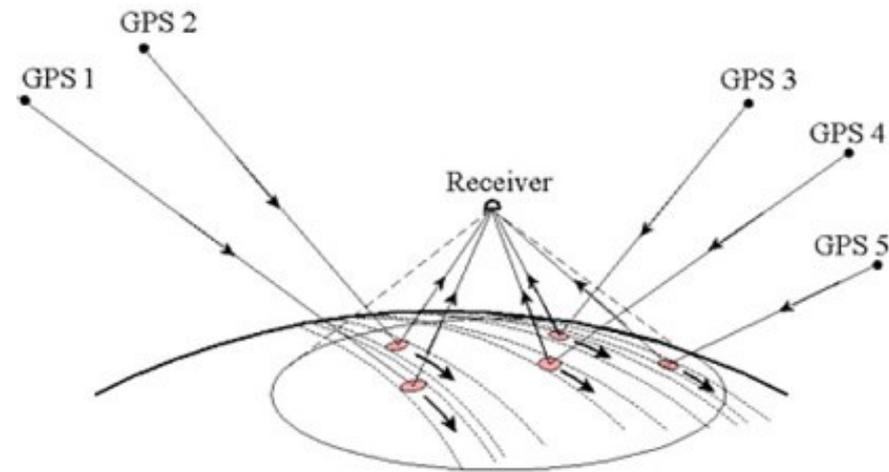
- Earth surface monitoring
- **Ocean** remote sensing:
 - sea-water monitoring (altimetry, wind detection)
 - sea-ice monitoring (topography and thickness)
- **Land** remote sensing:
 - water bacins detection
 - soil moisture measurements
 - snow monitoring



- GNSS signals reflected from Earth's surface
 - A spacecraft in low earth orbit or an Unmanned Aerial Vehicle (UAV) can simultaneously collect **direct** and **reflected** signal transmitted from the visible satellites



- GNSS bistatic radar, ASIS/FPGA custom receiver
 - too heavy and bulky for UAVs
- GPS scatterometer
 - light and compact
 - SDR approach

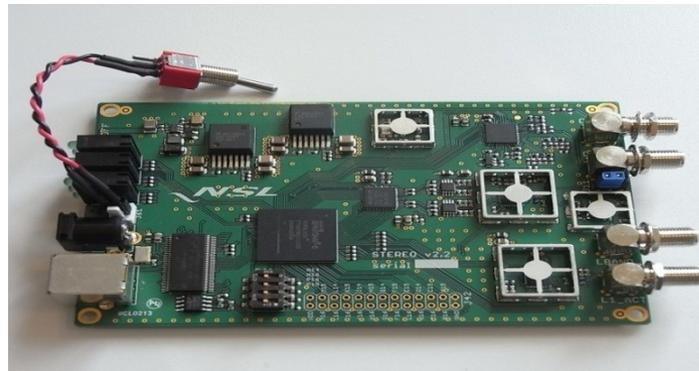


The SMAT project



“Development of a system for territory monitoring, based on sensors on board UAVs, for preventing and controlling a wide range of events (floods, fires, landslides, traffic, urban situations, pollution and crops)”

- Monitoring of the **presence of water** by using GNSS signals



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SMATF2

**Remote Sensing Experiment using
Backscattered GPS Signals**

**Sensitivity to field
boundaries**

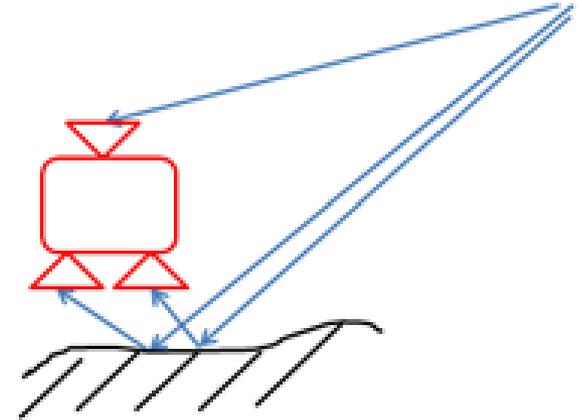
**Viverone, Piedmont - Italy
05/05/2011**

**Istituto Superiore Mario Boela
NavSAS**

Raul Hung 08/2011

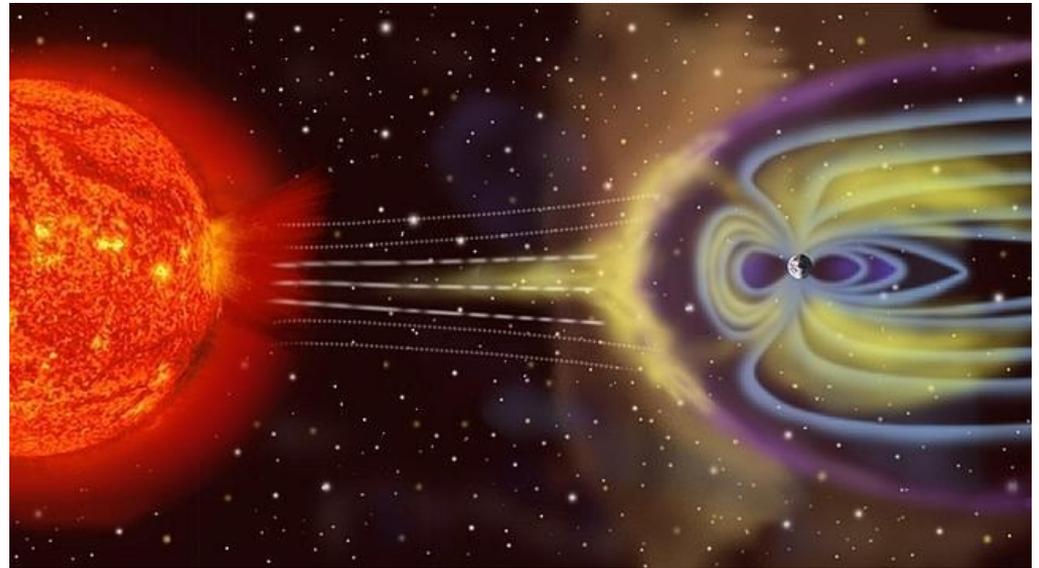
Advanced monitoring: soil moisture retrieval

- 1 up-looking antenna: direct signal
- 2 down-looking antennas: dual polarization RHCP/LHCP
- 2 possibilities:
 - Storing of raw IF data for post-processing
 - Real time processing and storing of correlation results



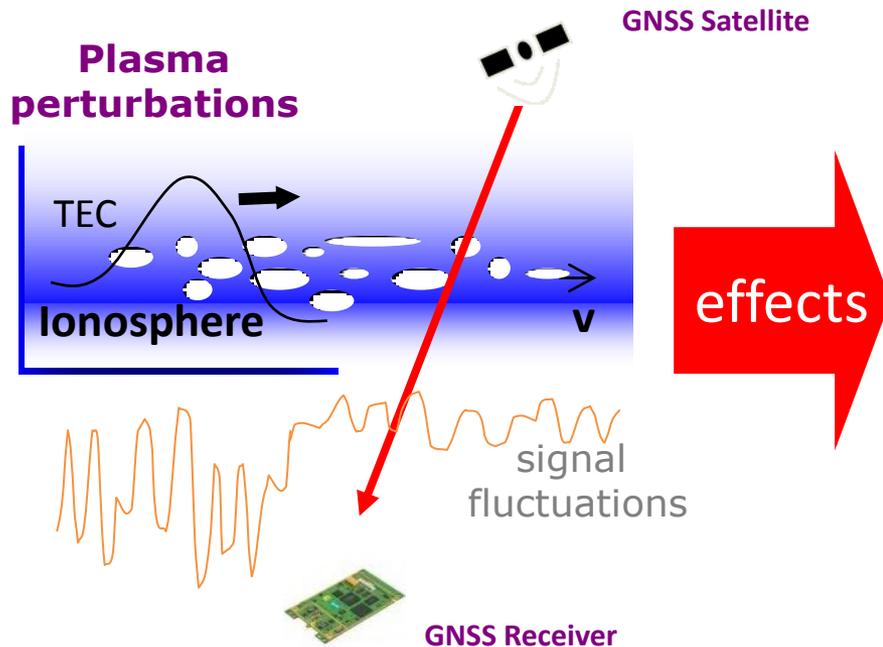
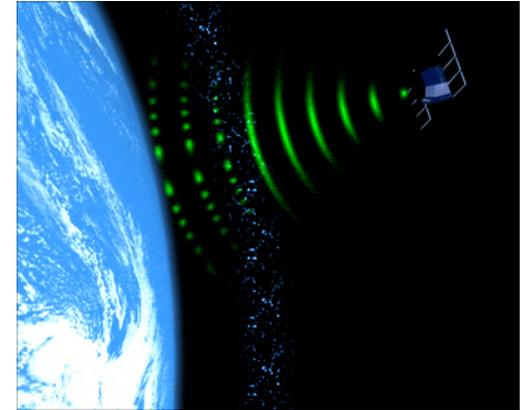


***Scientific applications:
ionospheric
scintillation
monitoring***



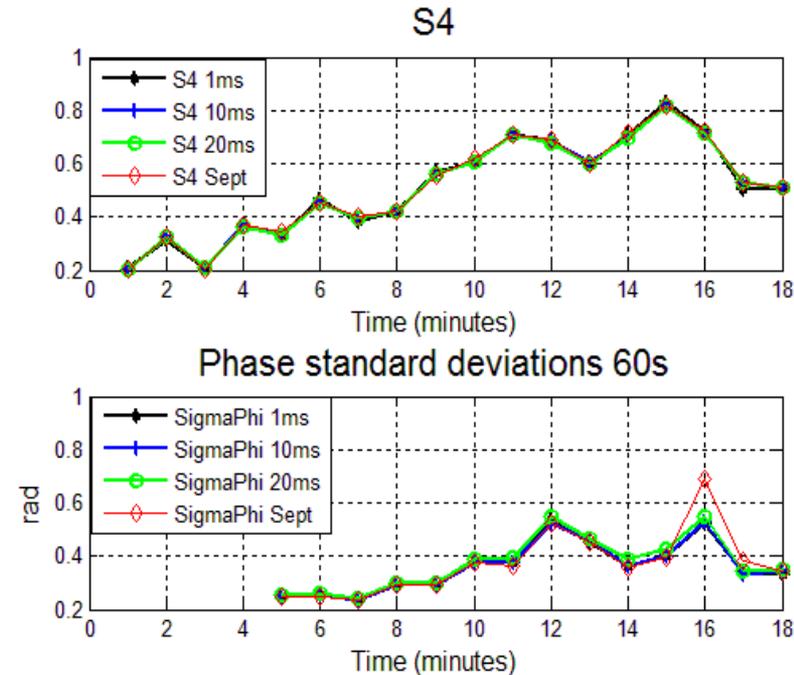
Ionospheric Scintillations

- Rapid fluctuations in the received signal amplitude and phase, originating from a scattering effect in the ionosphere due to irregular electron concentration
- Intensity depends on solar and geomagnetic activity, seasons, time, signal frequency and latitude



- C/N_0 degradation
- Pseudorange and carrier phase measurement noise increases
- Cycle slips
- Loss of lock
- Degradation of positioning accuracy
- Loss of positioning availability

- SDR receivers allow to have access to **pre-correlation** sections and **unconventional** outputs
 - effects of scintillation along the whole processing chain
 - computation of scintillation indices
- **Configurability** and modularity:
 - test with different configurations and architectures
 - dynamic adjustments of the receiver parameters to mitigate the scintillation effect
 - easy implementation of advanced signal processing algorithms on raw signal samples



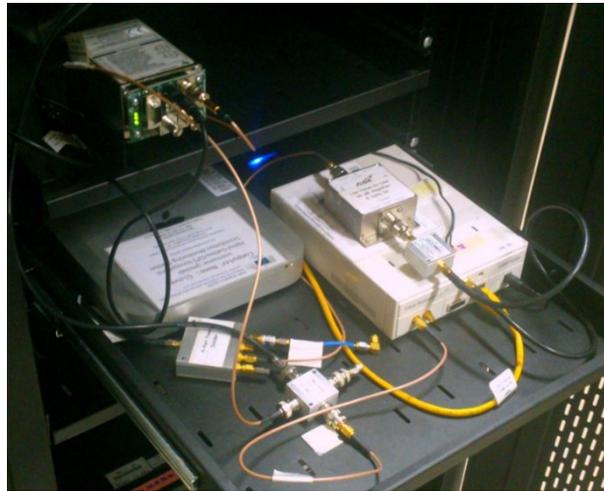
Vietnam: NAVIS center



- International collaboration center
- Monitoring station set-up in cooperation with ESA and EC-JRC

- Single frequency (L1)
- Samples collected after sunset on a daily basis
- Raw data storage (1 day of data = 178 GB)
- Professional receiver used for benchmarking

NAVIS Centre
Hanoi University of Science and Technology



Antarctica



“DemoGRAPE is a demonstrator, to provide on selected case studies an empirical assessment of the delay and of the corruption induced by the ionosphere on satellite signals in the Antarctic regions”



INGV
terremoti
vulcani
ambiente

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DI GEOFISICA E VULCANOLOGIA

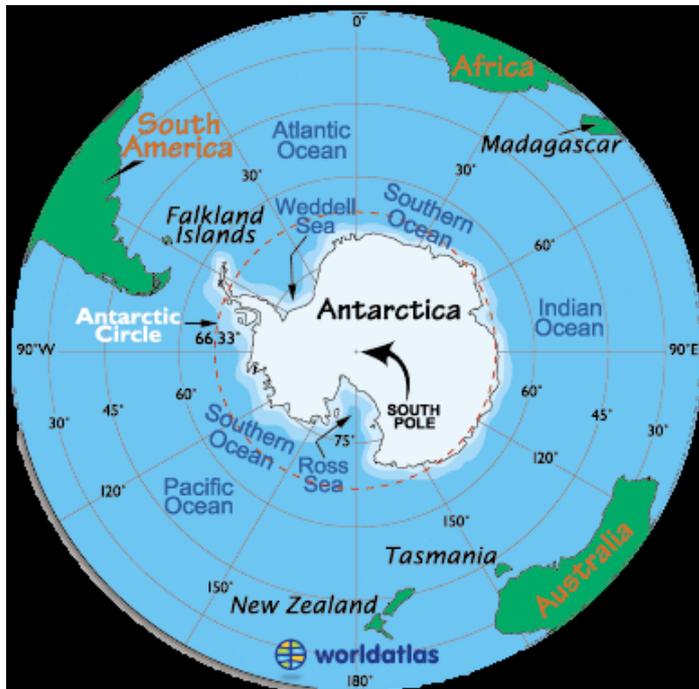


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demoGRAPE



- Dual band (L1+L2, E1+E5) fully software receiver (dynamic switching)
- Configurability: 2 bytes quantization to better represent the signal
- Accessibility: unconventional outputs

2 installations

- Sanae-IV
(SANSA, South Africa)
- EACF (INPE, Brazil)



<http://www.demogrape.net>

- Advantages of SDR receivers vs hardware dedicated platforms
 - modularity, flexibility, re-configurability, accessibility, ...
- Advantages of fully software receivers in GNSS
 - Engineering applications
 - Signal quality monitoring
 - Scientific applications
 - Remote sensing and reflectometry
 - Ionospheric monitoring



Visit: www.navsas.eu
www.polito.it
www.ismb.it



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