

Uncertainty propagation with AGS

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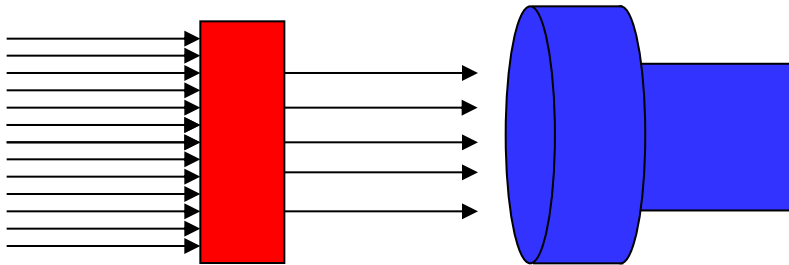
Standards for Nuclear Safety, Security and Safeguards (SN3S)

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- **Uncertainty propagation with AGS (Analysis of Geel Spectra)**
- **Examples**
- **Reporting of TOF-cross section data in EXFOR**

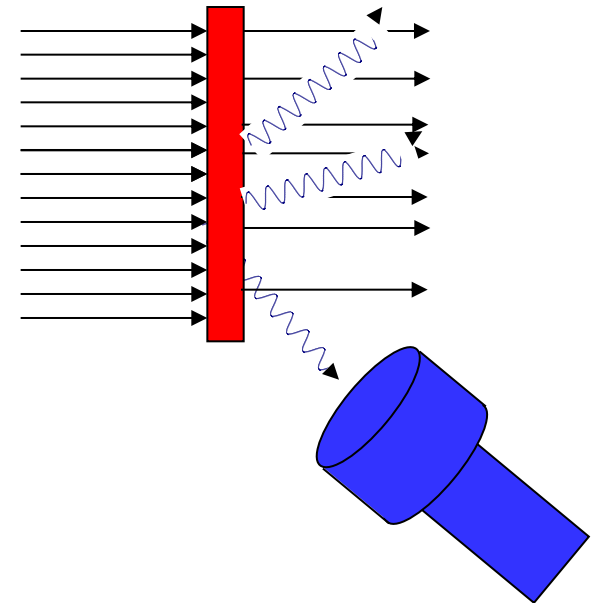
Transmission

$$T_{\text{exp}} = N \frac{C'_{\text{in}} - B'_{\text{in}}}{C'_{\text{out}} - B'_{\text{out}}}$$

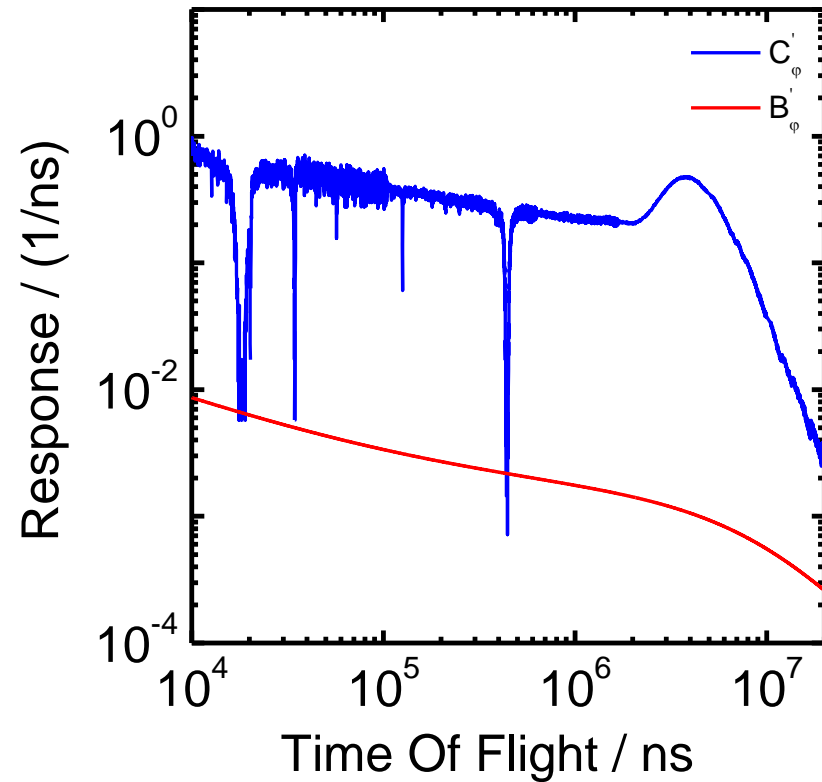


Reaction

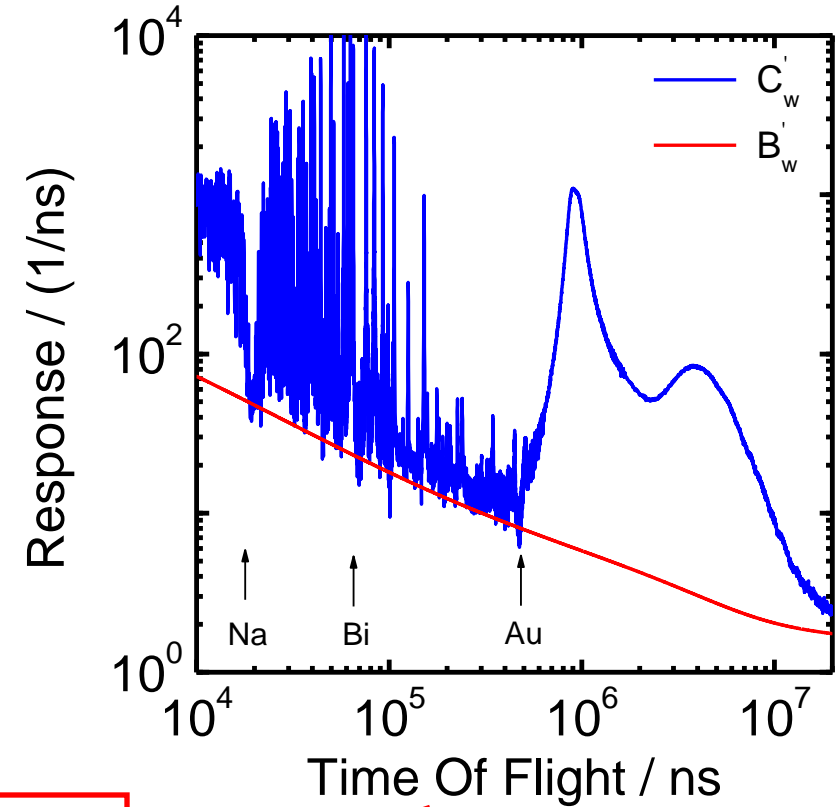
$$Y_{\text{exp}} = N \frac{C'_r - B'_r}{C'_\phi - B'_\phi} Y_\phi$$



Flux measurement



Capture measurement

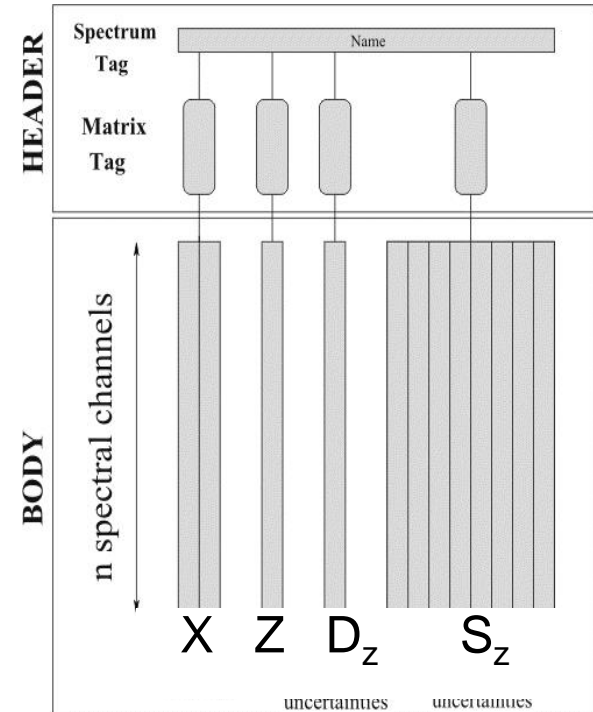


$$Y_{\text{exp}} = N \frac{C_r' - B_r'}{C_\phi' - B_\phi'} Y_\phi$$

Analysis of Geel Spectra (AGS)

- Transforms count rate spectra into observables (transmission, yields)
- Full uncertainty propagation starting from counting statistics
- Output: complete covariance matrix
- Special format for covariance matrix
 - Reduce space for data storage (EXFOR)
 - Document the sources of uncertainties due to each step in the data reduction process
 - Verify the contribution of each quantity introducing a correlated uncertainty component!

C. Bastian, Int. Soc. Optical Eng. 2867 (1997) 611



D_Z : uncorrelated part
n values

S_Z : correlated part
dim. (n x k)

Requires

- Understanding of the measurement process (scientific background)
 - experimental observables
 - measurement model
- Well documented experimental observables, including
 - all experimental details (input parameters, systematic effects)
 - all uncertainty components (correlated and uncorrelated)

⇒ Propagation of uncertainties (uncorrelated & correlated) not complicated

$$\text{GLUP: } \underline{V}_Z = \underline{G}_X \underline{V}_X \underline{G}_X^T$$

$$\text{GLSQ: } (\vec{q} - \vec{q}') = \underline{V}_{\vec{q}'} \underline{G}_{\vec{q}'}^T \underline{V}_Z^{-1} (\vec{z} - h(\vec{q}'))$$

$$\underline{V}_{\vec{q}} = (\underline{G}_{\vec{q}'}^T \underline{V}_Z^{-1} \underline{G}_{\vec{q}'})^{-1}$$

Note : GLUP & GLSQ based on normal probability distributions

⇒ AGS-formalism (concept)

$(\vec{Y}, \underline{V}_{\vec{Y}})$ TOF – spectrum(counts) dim.n

$$\Rightarrow \vec{Z} = f(\vec{a}, \vec{Y})$$

$(\vec{a}, \underline{V}_{\vec{a}})$ $\vec{a} = (a_1, \dots, a_k)$ parameter vector

$$\underline{V}_{\vec{Z}} = \underline{G}_{\vec{a}} \underline{V}_{\vec{a}} \underline{G}_{\vec{a}}^T + \underline{G}_{\vec{Y}} \underline{V}_{\vec{Y}} \underline{G}_{\vec{Y}}^T$$

$$\underline{G}_{\vec{a}} : g_{a,ik} = \frac{\partial f_i}{\partial a_k}$$

$$\underline{G}_{\vec{Y}} : g_{Y,ik} = \frac{\partial f_i}{\partial y_k}$$

- 1) $\underline{V}_{\vec{Y}} = \underline{D}_{\vec{Y}}$ diagonalelements $\sigma_{y_i}^2$
- 2) f only channel–channel operations
- 3) $\underline{V}_{\vec{a}}$: symmetric and positive definite

$$\underline{V}_{\vec{a}} = \underline{L}_{\vec{a}} \underline{L}_{\vec{a}}^T$$

Cholesky transformation

$(\vec{Y}, \underline{D}_{\vec{Y}})$ TOF – spectrum(counts) dim.n $\Rightarrow \vec{Z} = f(\vec{a}, \vec{Y})$
 $(\vec{a}, \underline{V}_{\vec{a}})$ $\vec{a} = (a_1, \dots, a_k)$ parameter vector

$$\underline{V}_{\vec{Z}} = \underline{G}_{\vec{a}} \underline{V}_{\vec{a}} \underline{G}_{\vec{a}}^T + \underline{G}_{\vec{Y}} \underline{D}_{\vec{Y}} \underline{G}_{\vec{Y}}^T$$

dim (k,k) $\underline{V}_{\vec{a}} = \underline{L}_{\vec{a}} \underline{L}_{\vec{a}}^T$

dim (n,k) $\underline{G}_{\vec{a}}$

$\underline{V}_{\vec{Y}} = \underline{D}_{\vec{Y}}$ diagonal
 f only channel–channel
 $\underline{G}_{\vec{Y}}$: diagonal

$$\underline{S}_{\vec{Z}} = \underline{G}_{\vec{a}} \underline{L}_{\vec{a}}$$

dim (n,k)

$$\underline{V}_{\vec{Z}} = \underline{S}_{\vec{Z}} \underline{S}_{\vec{Z}}^T + \underline{D}_{\vec{Z}}$$

$$\underline{D}_{\vec{Z}} = \underline{G}_{\vec{Y}} \underline{D}_{\vec{Y}} \underline{G}_{\vec{Y}}^T$$

$\underline{D}_{\vec{Z}}$ diagonal, n - values

$(\vec{Y}, \underline{D}_{\vec{Y}})$ TOF - spectrum(counts) dim. n $\Rightarrow \vec{Z} = f(\vec{a}, \vec{Y})$
 $(\vec{a}, \underline{V}_{\vec{a}})$ $\vec{a} = (a_1, \dots, a_k)$ parameter vector

$$\underline{V}_{\vec{Z}} = \underline{G}_{\vec{a}} \underline{V}_{\vec{a}} \underline{G}_{\vec{a}}^T + \underline{G}_{\vec{Y}} \underline{D}_{\vec{Y}} \underline{G}_{\vec{Y}}^T$$

$$\underline{V}_{\vec{a}} = \underline{L}_{\vec{a}} \underline{L}_{\vec{a}}^T$$

$$\underline{S}_{\vec{Z}} = \underline{G}_{\vec{a}} \underline{L}_{\vec{a}}$$

$$\underline{D}_{\vec{Z}} = \underline{G}_{\vec{Y}} \underline{D}_{\vec{Y}} \underline{G}_{\vec{Y}}^T$$

$$\underline{V}_{\vec{Z}} = \underline{S}_{\vec{Z}} \underline{S}_{\vec{Z}}^T + \underline{D}_{\vec{Z}}$$

dim (n,k)

AGS - format

$\underline{D}_{\vec{Z}}$ diagonal, n - values

\Rightarrow number of values to be stored dim. (n, k+1)

k = total number of correlated uncertainty components

$(\vec{Y}, \underline{D}_{\vec{Y}})$ TOF – spectrum(counts) dim. n $\Rightarrow \vec{Z} = f(\vec{a}, \vec{Y})$
 $(\vec{a}, \underline{V}_{\vec{a}})$ $\vec{a} = (a_1, \dots, a_k)$ parameter vector

$$\underline{V}_{\vec{Z}} = \underline{G}_{\vec{a}} \underline{V}_{\vec{a}} \underline{G}_{\vec{a}}^T + \underline{G}_{\vec{Y}} \underline{D}_{\vec{Y}} \underline{G}_{\vec{Y}}^T$$

\swarrow \searrow

$$\underline{V}_{\vec{a}} = \underline{L}_{\vec{a}} \underline{L}_{\vec{a}}^T$$

$$\underline{S}_{\vec{Z}} = \underline{G}_{\vec{a}} \underline{L}_{\vec{a}}$$

$$\underline{D}_{\vec{Z}} = \underline{G}_{\vec{Y}} \underline{D}_{\vec{Y}} \underline{G}_{\vec{Y}}^T$$

$\underline{S}_{\vec{Z}}$ – correlated components

$$\underline{V}_{\vec{Z}} = \underline{S}_{\vec{Z}} \underline{S}_{\vec{Z}}^T + \underline{D}_{\vec{Z}}$$

$\underline{D}_{\vec{Z}}$ – uncorrelated components

AGS - format

\Rightarrow number of values to be stored dim. (n, k+1)

k = total number of correlated uncertainty components

$(\vec{Y}, \underline{D}_{\vec{Y}})$ TOF - spectrum(counts) dim.n
 $(a, V_a = \sigma_a^2)$ $\vec{a} = (a_1)$ parameter vector dim.1
 $\Rightarrow \vec{Z} = f(\vec{a}, \vec{Y}) = a \vec{Y}$

$$\underline{V}_{\vec{Z}} = \underline{G}_{\vec{a}} \sigma_a^2 \underline{G}_{\vec{a}}^T + \underline{G}_{\vec{Y}} \underline{D}_{\vec{Y}} \underline{G}_{\vec{Y}}^T$$

$$\underline{L}_a = \sigma_a = \sigma_a^T$$

$$\underline{V}_{\vec{a}} = \underline{L}_a \underline{L}_a^T$$

$\underline{V}_{\vec{Y}} = \underline{D}_{\vec{Y}}$ diagonal
 f only channel-channel

$$\underline{G}_{\vec{a}} = \vec{Y} \quad g_{a,i} = \frac{\partial f_i}{\partial a} = y_i$$

$$\underline{G}_{\vec{Y}} : g_{Y,ii} = \frac{\partial f_i}{\partial y_i} = a$$

$$\underline{S}_{\vec{Z}} = \underline{Y} \sigma_a$$

dim (n,1)

$$\underline{D}_{\vec{Z}} = a^2 \underline{D}_{\vec{Y}}$$

\underline{D}_Z diagonal

$$\underline{V}_{\vec{Z}} = (\underline{Y} \sigma_a)(\underline{Y} \sigma_a)^T + a^2 \underline{D}_{\vec{Y}}$$

$$\vec{Z} = g(\vec{b}, \vec{Z}_1, \vec{Z}_2)$$

b, Z_1 and Z_2 not correlated

Input

$$(\vec{b}, \underline{V}_{\vec{b}}) \quad \text{dim. } \vec{b} = k_b$$

$$\underline{V}_{\vec{b}} = \underline{L}_{\vec{b}} \underline{L}_{\vec{b}}^T$$

$$(\vec{Z}_1, \underline{V}_{\vec{Z}_1}) \quad \vec{Z}_1 = f_1(\vec{a}_1, \vec{Y}_1) \quad \text{dim. } \vec{a}_1 = k_1$$

$$\underline{V}_{\vec{Z}_1} = \underline{S}_{\vec{Z}_1} \underline{S}_{\vec{Z}_1}^T + \underline{D}_{\vec{Z}_1}$$

$$(\vec{Z}_2, \underline{V}_{\vec{Z}_2}) \quad \vec{Z}_2 = f_2(\vec{a}_2, \vec{Y}_2) \quad \text{dim. } \vec{a}_2 = k_2$$

$$\underline{V}_{\vec{Z}_2} = \underline{S}_{\vec{Z}_2} \underline{S}_{\vec{Z}_2}^T + \underline{D}_{\vec{Z}_2}$$

Output

$$\Rightarrow \vec{Z} = f(\vec{b}, \vec{Z}_1, \vec{Z}_2)$$

$$\underline{V}_{\vec{Z}} = \underline{S}_{\vec{Z}} \underline{S}_{\vec{Z}}^T + \underline{D}_{\vec{Z}}$$

$\underline{D}_{\vec{Z}}$ – uncorrelated components

$\underline{S}_{\vec{Z}}$ – correlated components

$$\underline{V}_{\vec{b}} = \underline{L}_{\vec{b}} \underline{L}_{\vec{b}}^T$$

$$\dim \vec{b} = k_b$$

$$\underline{V}_{\vec{Z}_1} = \underline{S}_{\vec{Z}_1} \underline{S}_{\vec{Z}_1}^T + \underline{D}_{\vec{Z}_1}$$

$$\dim \underline{S}_{\vec{Z}_1} = (n, k_1)$$

$$\underline{V}_{\vec{Z}_2} = \underline{S}_{\vec{Z}_2} \underline{S}_{\vec{Z}_2}^T + \underline{D}_{\vec{Z}_2}$$

$$\dim \underline{S}_{\vec{Z}_2} = (n, k_2)$$

$$\underline{V}_{\vec{Z}} = \underline{G}_{\vec{b}} \underline{V}_{\vec{b}} \underline{G}_{\vec{b}}^T + \underline{G}_{\vec{Z}_1} \underline{V}_{\vec{Z}_1} \underline{G}_{\vec{Z}_1}^T + \underline{G}_{\vec{Z}_2} \underline{V}_{\vec{Z}_2} \underline{G}_{\vec{Z}_2}^T$$

$$\underline{V}_{\vec{Z}} = \underline{G}_{\vec{b}} \underline{L}_{\vec{b}} \underline{L}_{\vec{b}}^T \underline{G}_{\vec{b}}^T + \underline{G}_{\vec{Z}_1} \underline{S}_{\vec{Z}_1} \underline{S}_{\vec{Z}_1}^T \underline{G}_{\vec{Z}_1}^T + \underline{G}_{\vec{Z}_1} \underline{D}_{\vec{Z}_1} \underline{G}_{\vec{Z}_1}^T + \underline{G}_{\vec{Z}_2} \underline{S}_{\vec{Z}_2} \underline{S}_{\vec{Z}_2}^T \underline{G}_{\vec{Z}_2}^T + \underline{G}_{\vec{Z}_2} \underline{D}_{\vec{Z}_2} \underline{G}_{\vec{Z}_2}^T$$

$$\underline{V}_{\vec{b}} = \underline{L}_{\vec{b}} \underline{L}_{\vec{b}}^T$$

$$\dim \vec{b} = k_b$$

$$\underline{V}_{\vec{Z}_1} = \underline{S}_{\vec{Z}_1} \underline{S}_{\vec{Z}_1}^T + \underline{D}_{\vec{Z}_1}$$

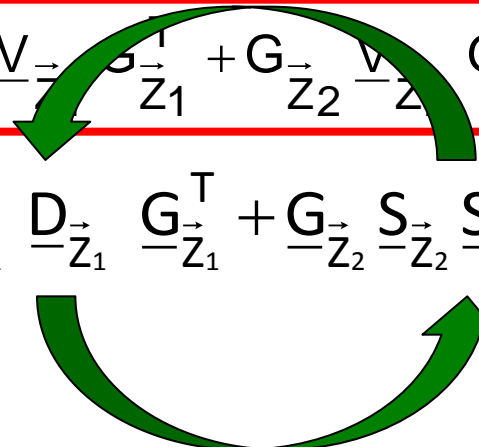
$$\dim \underline{S}_{\vec{Z}_1} = (n, k_1)$$

$$\underline{V}_{\vec{Z}_2} = \underline{S}_{\vec{Z}_2} \underline{S}_{\vec{Z}_2}^T + \underline{D}_{\vec{Z}_2}$$

$$\dim \underline{S}_{\vec{Z}_2} = (n, k_2)$$

$$\underline{V}_{\vec{Z}} = \underline{G}_{\vec{b}} \underline{V}_{\vec{b}} \underline{G}_{\vec{b}}^T + \underline{G}_{\vec{Z}_1} \underline{V}_{\vec{Z}_1} \underline{G}_{\vec{Z}_1}^T + \underline{G}_{\vec{Z}_2} \underline{V}_{\vec{Z}_2} \underline{G}_{\vec{Z}_2}^T$$

$$\underline{V}_{\vec{Z}} = \underline{G}_{\vec{b}} \underline{L}_{\vec{b}} \underline{L}_{\vec{b}}^T \underline{G}_{\vec{b}}^T + \underline{G}_{\vec{Z}_1} \underline{S}_{\vec{Z}_1} \underline{S}_{\vec{Z}_1}^T \underline{G}_{\vec{Z}_1}^T + \underline{G}_{\vec{Z}_1} \underline{D}_{\vec{Z}_1} \underline{G}_{\vec{Z}_1}^T + \underline{G}_{\vec{Z}_2} \underline{S}_{\vec{Z}_2} \underline{S}_{\vec{Z}_2}^T \underline{G}_{\vec{Z}_2}^T + \underline{G}_{\vec{Z}_2} \underline{D}_{\vec{Z}_2} \underline{G}_{\vec{Z}_2}^T$$



$$\underline{V}_{\vec{b}} = \underline{L}_{\vec{b}} \underline{L}_{\vec{b}}^T$$

$$\dim \vec{b} = k_b$$

$$\underline{V}_{\vec{Z}_1} = \underline{S}_{\vec{Z}_1} \underline{S}_{\vec{Z}_1}^T + \underline{D}_{\vec{Z}_1}$$

$$\dim \underline{S}_{\vec{Z}_1} = (n, k_1)$$

$$\underline{V}_{\vec{Z}_2} = \underline{S}_{\vec{Z}_2} \underline{S}_{\vec{Z}_2}^T + \underline{D}_{\vec{Z}_2}$$

$$\dim \underline{S}_{\vec{Z}_2} = (n, k_2)$$

$$\underline{V}_{\vec{Z}} = \underline{G}_{\vec{b}} \underline{V}_{\vec{b}} \underline{G}_{\vec{b}}^T + \underline{G}_{\vec{Z}_1} \underline{V}_{\vec{Z}_1} \underline{G}_{\vec{Z}_1}^T + \underline{G}_{\vec{Z}_2} \underline{V}_{\vec{Z}_2} \underline{G}_{\vec{Z}_2}^T$$

$$\underline{V}_{\vec{Z}} = \underbrace{\underline{G}_{\vec{b}} \underline{L}_{\vec{b}} \underline{L}_{\vec{b}}^T \underline{G}_{\vec{b}}^T + \underline{G}_{\vec{Z}_1} \underline{S}_{\vec{Z}_1} \underline{S}_{\vec{Z}_1}^T \underline{G}_{\vec{Z}_1}^T + \underline{G}_{\vec{Z}_2} \underline{S}_{\vec{Z}_2} \underline{S}_{\vec{Z}_2}^T \underline{G}_{\vec{Z}_2}^T}_{\text{correlated components}} + \underbrace{\underline{G}_{\vec{Z}_1} \underline{D}_{\vec{Z}_1} \underline{G}_{\vec{Z}_1}^T + \underline{G}_{\vec{Z}_2} \underline{D}_{\vec{Z}_2} \underline{G}_{\vec{Z}_2}^T}_{\text{uncorrelated components}}$$

$$\underline{S}_{\vec{Z}} = \begin{bmatrix} \underline{G}_{\vec{b}} \underline{L}_{\vec{b}} & \underline{G}_{\vec{Z}_1} \underline{S}_{\vec{Z}_1} & \underline{G}_{\vec{Z}_2} \underline{S}_{\vec{Z}_2} \end{bmatrix}$$

$$\dim (n, k) \quad (n, k_b) \quad (n, k_1) \quad (n, k_2)$$

$$(k = k_b + k_1 + k_2)$$

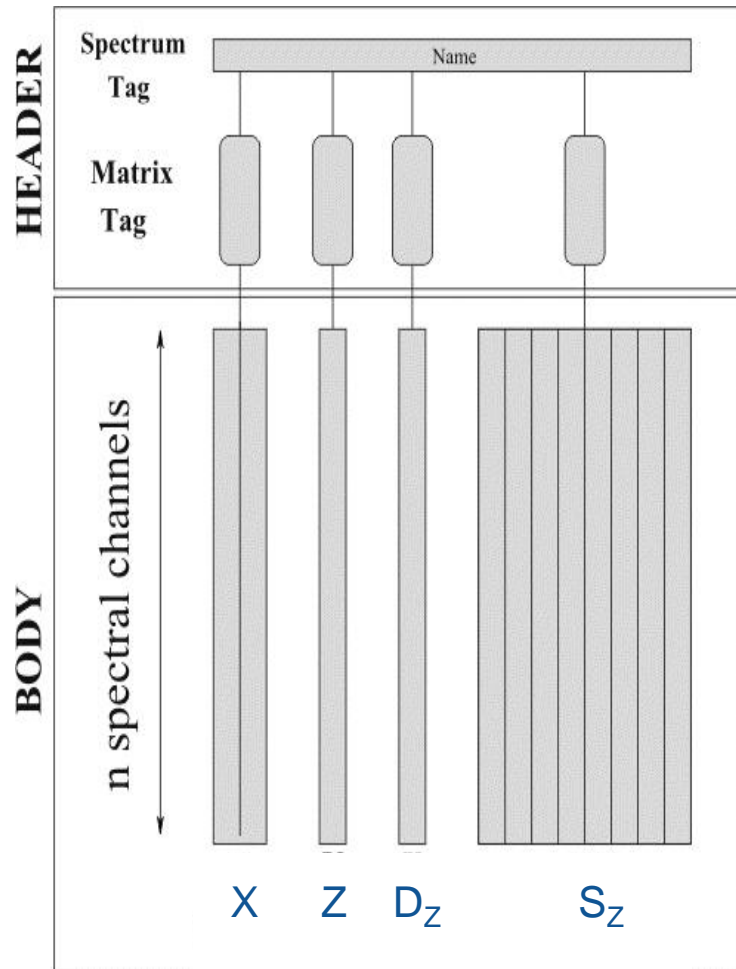
$\underline{S}_{\vec{Z}}$ - correlated components

$$\underline{D}_{\vec{Z}} = \underline{G}_{\vec{Z}_1} \underline{D}_{\vec{Z}_1} \underline{G}_{\vec{Z}_1}^T + \underline{G}_{\vec{Z}_2} \underline{D}_{\vec{Z}_2} \underline{G}_{\vec{Z}_2}^T$$

$\dim n$

$\underline{D}_{\vec{Z}}$ - uncorrelated components

$$\underline{V}_{\vec{Z}} = \underline{S}_{\vec{Z}} \underline{S}_{\vec{Z}}^T + \underline{D}_{\vec{Z}}$$



Observable Z (dimension n) with k sources of correlated uncertainties

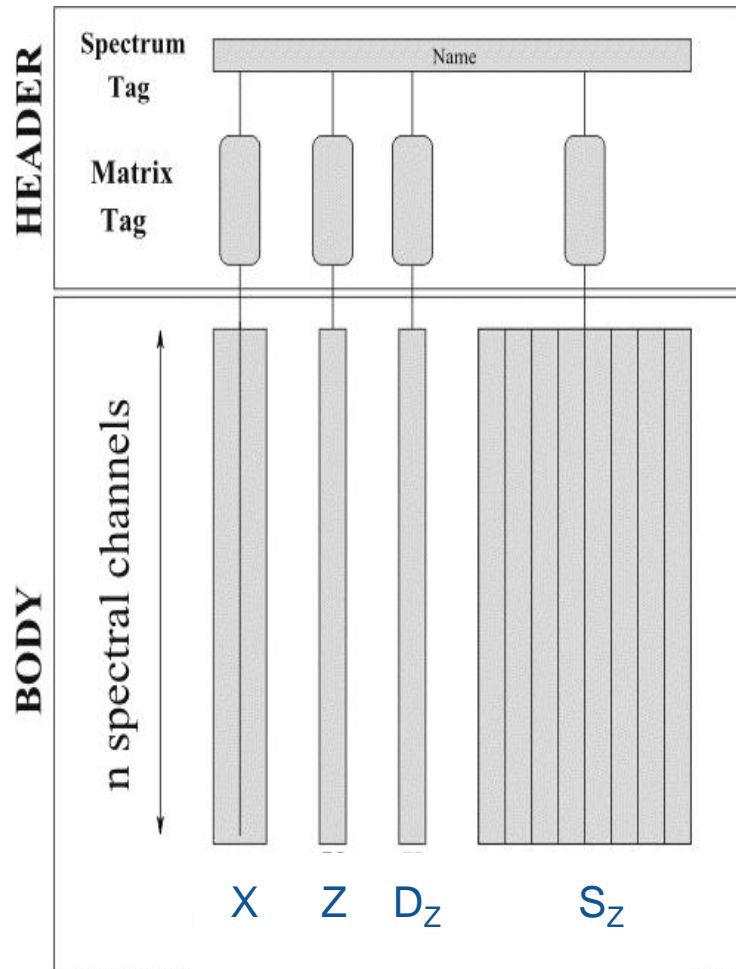
$$\underline{V}_Z = \underline{S}_Z \underline{S}_Z^T + \underline{D}_Z$$

n : number of data points (TOF)

k : number of quantities introducing correlated uncertainty components

D_Z : uncorrelated part (n values)

S_Z : matrix dimension (n x k)
contains the contribution of each quantity creating a correlated uncertainty component



Observable Z (dimension n) with k sources of correlated uncertainties

$$\underline{V}_{\underline{Z}} = \underline{S}_{\underline{Z}} \underline{S}_{\underline{Z}}^T + \underline{D}_{\underline{Z}}$$

Storage space

Covariance matrix

n^2 elements (e.g. 32k x 8 bytes) → 8 Gb)

AGS representation

$n(k+1)$ elements (32k, 20 corr.) → 5 Mb)

Information

Covariance matrix

no separation between components

AGS representation

separates uncorrelated and correlated components (avoid PPP)

verify impact of each individual component

Creation of AGS library file and data import

<i>ags_getA</i>	Import a spectrum from an AGS archive file
<i>ags_getE</i>	Import cross section data from an ENDF formatted file (file 3) in energy
<i>ags_getET</i>	Import cross section data from an ENDF formatted file (file 3) in TOF
<i>ags_getH</i>	Import a histogram (integers)
<i>ags_getW</i>	Import a weighted histogram
<i>ags_getXY</i>	Import a spectrum
<i>ags_getY</i>	Import a histogram
<i>ags_mpty</i>	Creation of an empty AGS archive file

Basic channel-to-channel, arithmetic operations

<i>ags_addval</i>	Add a constant to a spectrum
<i>ags_divval</i>	Division of a spectrum by a constant
<i>ags_multval</i>	Multiplication of a spectrum with a constant
<i>ags_subval</i>	Subtraction of a constant from a spectrum

Channel-to-channel, spectrum operations

<i>ags_avrg</i>	Division of spectrum by bin widths
<i>ags_divi</i>	Division of two spectra
<i>ags_dtco</i>	Dead time correction
<i>ags_ener</i>	Conversion of bin boundaries from TOF to energy
<i>ags_exp</i>	Exponential of a spectrum
<i>ags_fit</i>	Fitting a spectrum
<i>ags_fpa</i>	Flight path adjustment
<i>ags_func</i>	Generate spectrum using a function
<i>ags_fxyp</i>	Special spectrum operation
<i>ags_inv</i>	Inverse a spectrum
<i>ags_lico</i>	Linear combination of spectra
<i>ags_lift</i>	Interpolate spectrum on different grid
<i>ags_log</i>	Natural logarithm of a spectrum
<i>ags_mult</i>	Multiplication of two spectra
<i>ags_shift</i>	Shift grid boundaries
<i>ags_tof</i>	Conversion of bin boundaries from energy to TOF
<i>ags_unav</i>	Multiply spectrum with bin widths

Output operations

<i>ags_putCM</i>	Print covariance matrix
<i>ags_putX</i>	Print spectra and uncertainty components
<i>ags_scan</i>	Print content of AGS archive file
<i>ags_title</i>	Print title of AGS archive file

```
# create ags-file
ags_mpty TRFAK

# read sample out
scaler=TOout,CMout
ags_getXY TRFAK /SCALER=$scaler /FROM=spout.his /ALIAS=SOUT

# read sample in
scaler=TOin,CMin
ags_getXY TRFAK /SCALER=$scaler /FROM=spin.his /ALIAS=SIN /LIKE=A01SOUT

# dead time correction
dtcoef=DTCOEF
ags_idtc TRFAK,A01SOUT /DTIME=$dtcoef /LPSC=1
ags_idtc TRFAK,B01SIN /DTIME=$dtcoef /LPSC=1

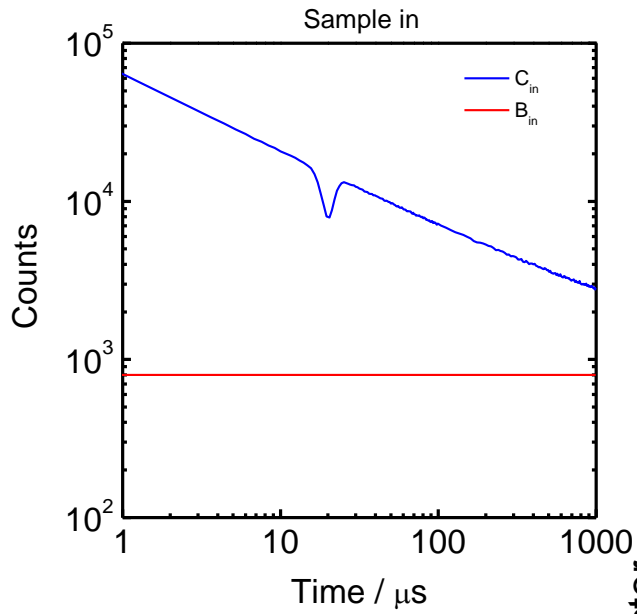
# normalize to central monitor and divide by bin width
ags_avgr TRFAK,C01SOUT /CMSC=2
ags_avgr TRFAK,D01SIN /CMSC=2

#calculate background contribution
ags_func TRFAK /FUN=f01 /PARFILE=PAROUT /ALIAS=SBOUT /LIKE=A01SOUT
ags_func TRFAK /FUN=f01 /PARFILE=PARIN /ALIAS=SBIN /LIKE=A01SOUT

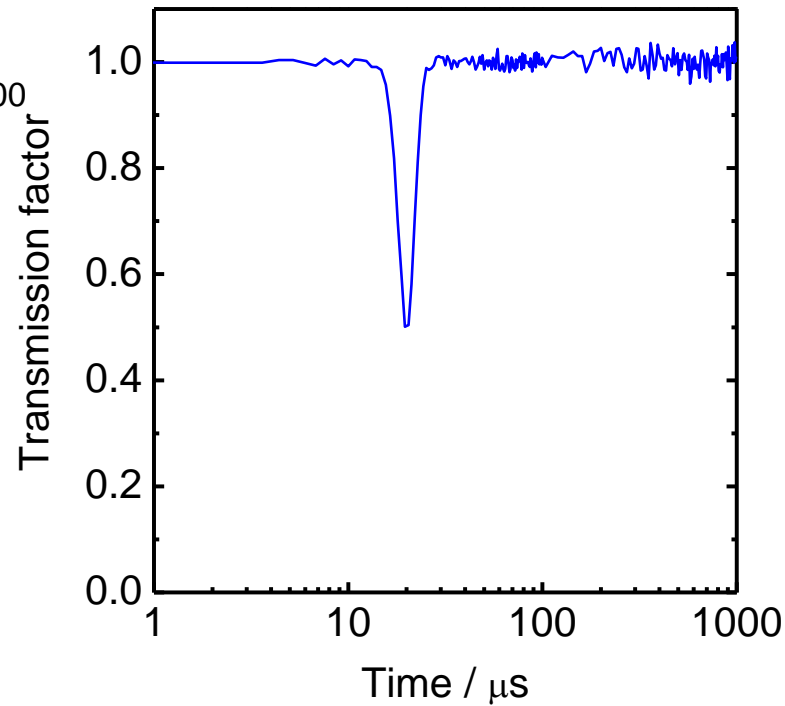
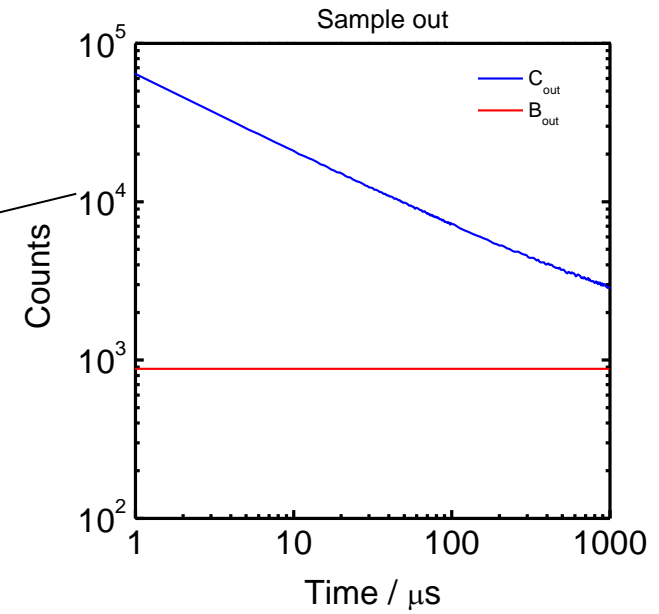
#subtract background
ags_lico TRFAK,E01SOUT,G01SBOUT /ALIAS=SOUTNET /PAR=1.0,-1.0
ags_lico TRFAK,F01SIN,H01SBIN /ALIAS=SINNET /PAR=1.0,-1.0

#create transmission factor
ags divi TRFAK,I01SOUTNET,J01SINNET /ALIAS=TRFAK
```

$$T = N \frac{C'_{in} - B'_{in}}{C'_{out} - B'_{out}}$$

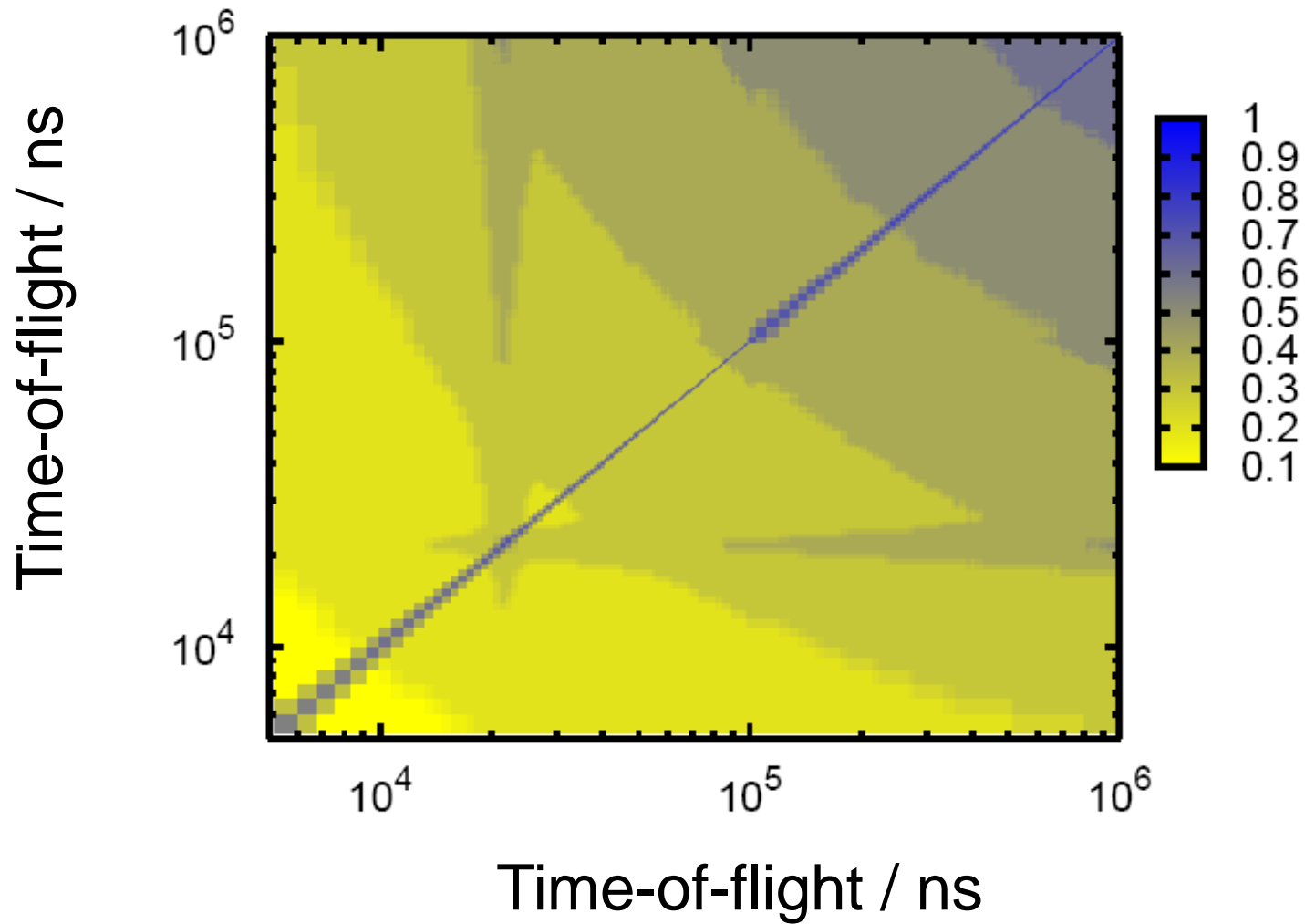


$$T_{\text{exp}} = N \frac{C'_{in} - B'_{in}}{C'_{out} - B'_{out}}$$



X _L	X _H	Z	δZ	δZ _u	V _Z = D _Z + S S ^T			
					D _Z	S		
						δZ _u ²	B _{in}	B _{out}
800	1600	0.999	0.79E-2	0.59E-2	0.35E-4	0.14E-2	-0.08E-2	0.50E-2
1600	2400	0.999	0.86E-2	0.67E-2	0.45E-4	0.18E-2	-0.10E-2	0.50E-2
2400	3200	0.999	0.92E-2	0.73E-2	0.54E-4	0.21E-2	-0.12E-2	0.50E-2
3200	4000	0.999	0.97E-2	0.78E-2	0.61E-4	0.24E-2	-0.13E-2	0.50E-2
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.
.
16000	16800	0.899	1.30E-2	1.07E-2	1.15E-4	0.51E-2	-0.25E-2	0.45E-2
16800	17600	0.818	1.24E-2	1.02E-2	1.04E-4	0.53E-2	-0.24E-2	0.41E-2
17600	18400	0.701	1.15E-2	0.93E-2	0.86E-4	0.54E-2	-0.21E-2	0.35E-2
18400	19200	0.594	1.06E-2	0.84E-2	0.71E-4	0.55E-2	-0.18E-2	0.30E-2
19200	20000	0.501	0.98E-2	0.76E-2	0.57E-4	0.56E-2	-0.15E-2	0.25E-2
20000	20800	0.504	1.00E-2	0.77E-2	0.59E-4	0.57E-2	-0.16E-2	0.25E-2
20800	21600	0.581	1.09E-2	0.85E-2	0.73E-4	0.58E-2	-0.19E-2	0.29E-2
21600	22400	0.707	1.22E-2	0.98E-2	0.97E-4	0.60E-2	-0.23E-2	0.35E-2
.
.
.
964000	972000	0.999	5.91E-2	3.75E-2	14.06E-4	3.98E-2	-2.18E-2	0.50E-2
972000	980000	1.037	6.09E-2	3.89E-2	15.13E-4	4.04E-2	-2.31E-2	0.52E-2
980000	988000	1.001	6.01E-2	3.80E-2	14.46E-4	4.05E-2	-2.23E-2	0.50E-2
988000	996000	1.010	5.92E-2	3.77E-2	14.23E-4	3.96E-2	-2.20E-2	0.50E-2

$\delta B_{in} / B_{in} : 10.0 \%$
 $\delta B_{out} / B_{out} : 5.0 \%$
 $\delta N / N : 0.5 \%$



Requirements:

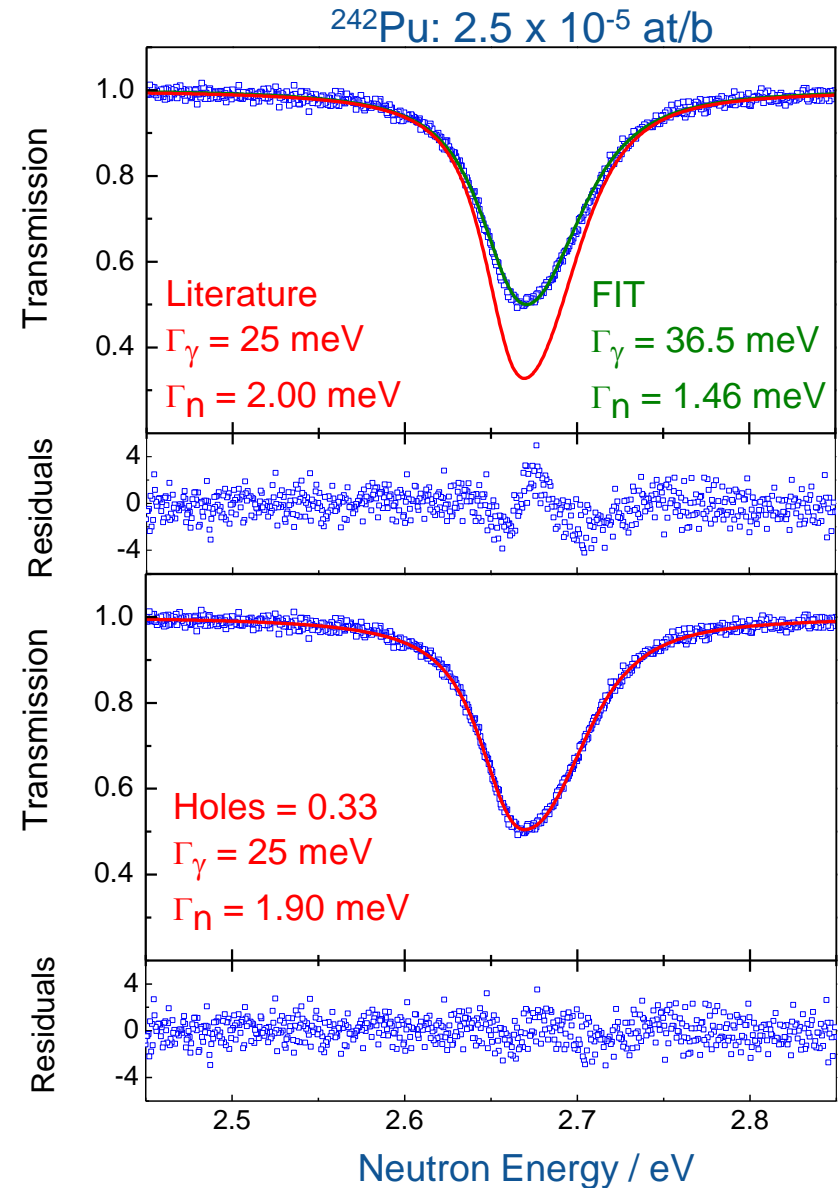
Well documented experimental observables in EXFOR

Including:

- experimental details (T_D , n , N , ...)
- all uncertainty components (correlated and uncorrelated, AGS-format)
- response function of TOF-spectrometers

⇒ Recommendation IAEA / IRMM based on the AGS – system

- Powder/metal sample
- Areal density + uncertainty
- Grain size of powder sample
- Homogeneity



Specify how data reduction was done and use a proper reference

1) Weighting function

- **with threshold** e.g. Borella et al., NIM A577 (2007) 626
- **without threshold** e.g. Abbondanno et al. NIM A521 (2004) 454

2) Correction for γ -ray attenuation

3) Normalization

- **internal/external**
- **saturated resonance**
- **neutron flux monitor**

4) Background

- **fixed background filters**

Main Reference
Facility
Neutron production

Primary neutron production target
 Time resolution primary beam (ns)
 Moderator material
 Surface Dimensions
 (mm x mm or diameter in mm)
 Thickness (mm)

Experimental details

Measurement type
 Flight path length (m)
 (moderator – target (detector): face to face distance)
 Angle
 (with respect to normal of moderator)
 Beam dimensions
 (mm x mm or diameter in mm)

Sample

Type (metal, powder)
 Chemical composition
 Atomic abundance of main element
 Weight per unit area (g/cm^2)
 Geometry
 Surface dimensions
 (mm x mm or diameter in mm)
 Thickness of main element (at/b)
 Backing
 Containment description
 Temperature

GELINA

Uranium
 4 ns
 H_2O
 2 containers 100 x 100 mm
 40 mm

Fission
 (8.218 +/- 0.006) m
 18 deg
 Diameter 55 mm

Electrodeposition
 UO_2
 99.9732 at% ^{236}U
 (209.9 +/- 1.3) $\text{U}\mu\text{g}/\text{cm}^2$
 Diameter (50.0 +/- 0.1) mm
 $5.354 \cdot 10^{-6}$ at/b ^{236}U
 20 μm aluminium
 No container
 25 meV

1
 2,3
 4

Recommendation
 IRMM & NDS - IAEA

[1] NSE 160 (2008) 200 - 206
 [2] NIM A 179 (1981), 13
 [3] NIM A 228 (1985), 217
 [4] NIM A 531 (2004), 392

Detector

Type Frisch gridded ionisation chamber
 Material CH₄ (100%)
 Gas pressure Gas flow at 1 atm
 Geometry 2π

Flux normalization

Reaction ¹⁰B(n,α)
 Cross section from ENDF/B-VI.8
 Atomic abundance of main element 93.0 at% ¹⁰B
 Target thickness (8.05 +/- 0.10) ¹⁰B μg/cm²
 Surface dimensions Diameter (50.0 +/- 0.1) mm
 (²³⁶U- ¹⁰B : back to back)

Normalization uncertainty (TOF-independent)

1.5 %

Data

Time-of-flight of first channel 3000 ns
 Time-of-flight bin width / ns Column 1
 Energy (relativistic formula, L = 8.238 m) eV Column 2
 Yield in barn/at Column 3

Uncertainties (at 1 sigma level)

Total (normalization not included) Column 4
 Uncorrelated contribution (variance) Column 5
 Other sources creating correlated uncertainty components
 Dead time ¹⁰B [col 6]
 Background ¹⁰B [col.7, 8,9]
 Dead time ²³⁶U [col. 10]
 Background ²³⁶U [col.11,12,13]

Description of
 AGS
 Output



INDC(NDS)-0647
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INDC International Nuclear Data Committee

Summary Report of the Consultants' Meeting on

EXFOR Data in Resonance Region and Spectrometer Response Function

IAEA Headquarters, Vienna, Austria

8 – 10 October 2013

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