











Analyzing the ability to identify convective organization by indices

Giulio Mandorli, Claudia Stubenrauch

No definition of organization

Retsch et al. (2020)

ges to convective organization have been linked to
. Yet there is no unanimously agreed upon definition of ous way to objectively define it. In this work, we set used on the size and proximity of convectively active

Bläckberg and Singh (2022)

Convective aggregation may loosely be described as the "coming together" however, it does not currently have a strict quantifiable definition (Retsch et theless, it is generally agreed that the degree of convective aggregation incr

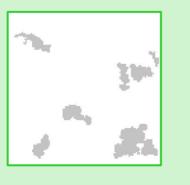
Many indices have been developed Biagioli and Tompkins (2023)

Objects-based (direct)

Based on the disposition of convective objects:

- Iorg
- COP
- SCAI

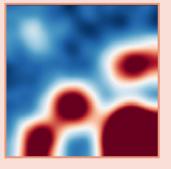
-



Indirect

Based on continuous atmospheric properties. Can be of various kind:

- σ (Column-RH)
- mean OLR
- WVP interquartile
-

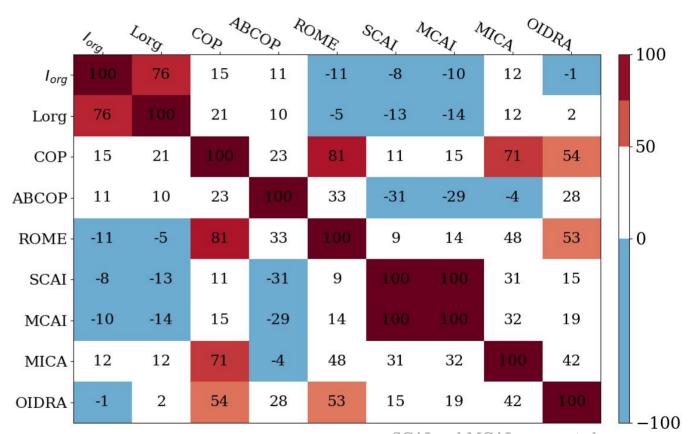


Correlations

Correlated indices

Uncorrelated/Opposite

 \rightarrow similar analyses produce unrelated results



SCAI and MCAI are negated

Need for an evaluation:

Which index quantifies well organization?

Problem:

Challenging! Because there is **no definition**

Solution:

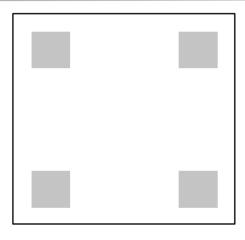
Evaluation of the indices via their behavior

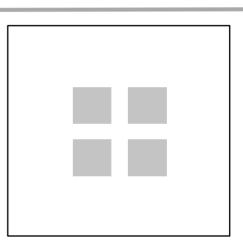
Condition: proximity

low organization





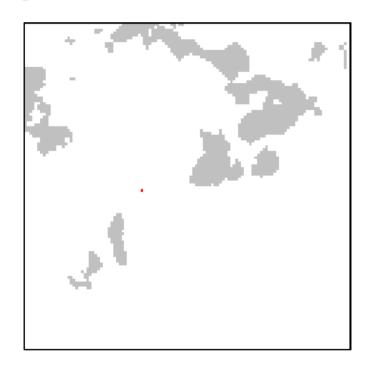




Condition

Organization strength increases with the proximity of the objects.

Condition: noise-safeness



Original + 1 point

- does **not change** significantly the **disposition of convection**
- does **not change** significantly the **strenght of organization**

Condition

Organization strength does **not change** significantly when one random grid box is set to convective.

Evaluation of the indices

Any metric of organization has to satisfy:

- 1) noise-safeness
- 2) increasing with proximity

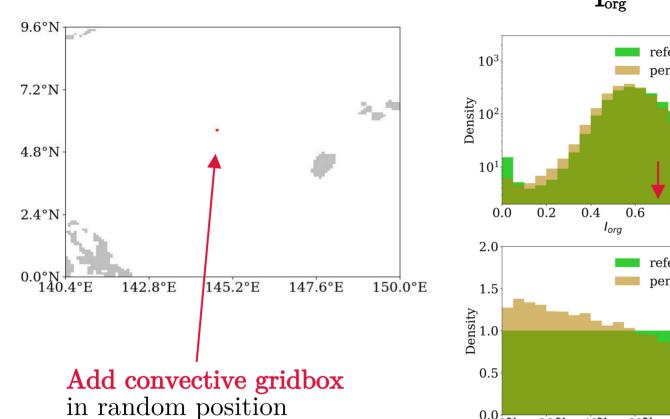
What metric satisfy the conditions?

- Iorg ?
- COP ?
- SCAI ?

condition

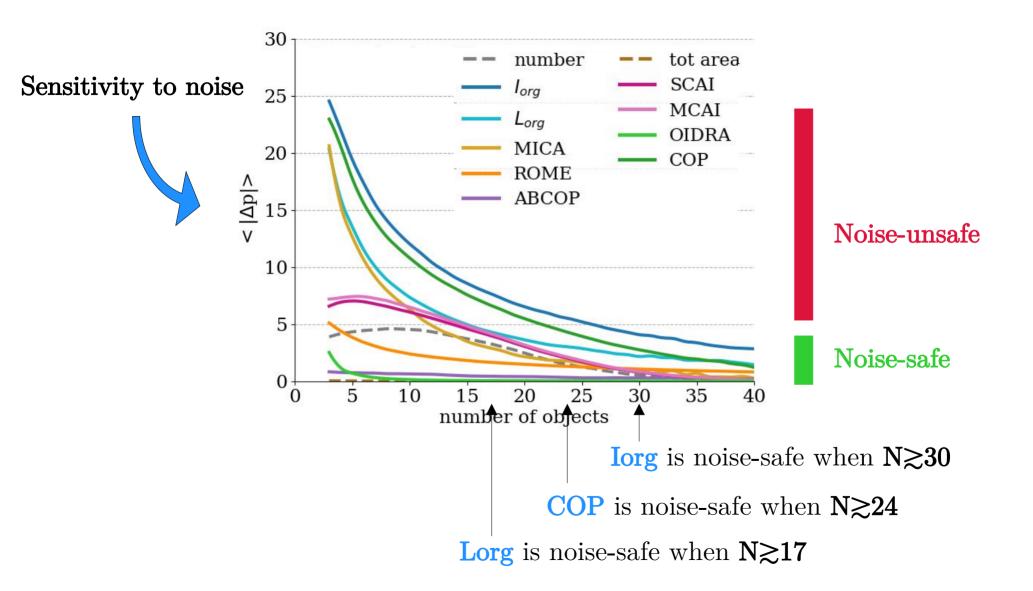
evaluation

condition 1 noise-safeness



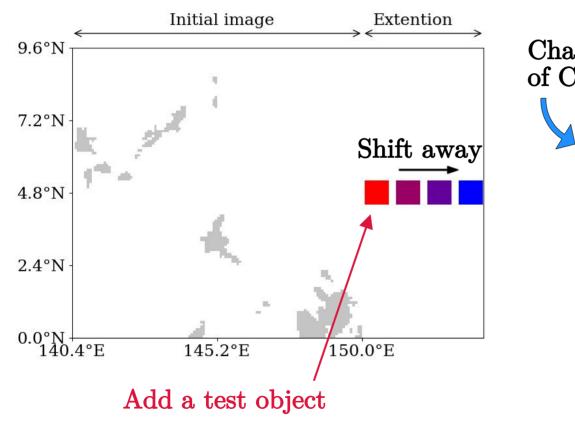
COP 10^{3} reference reference perturbed perturbed Density 101 10^{-1} 8.0 2 4 COP 6 2.0 reference reference perturbed perturbed 1.5 Density 0.1 0.5 0.0 0.0 60% 80% 100% 20% 40% 60% 80% 100% 20% 40% $p(I_{org})$ p(COP)

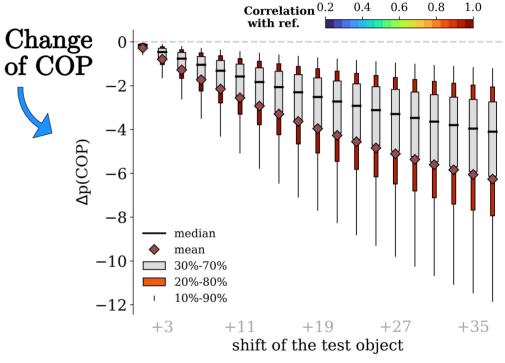
 $\Delta p \sim 10\%$ for both



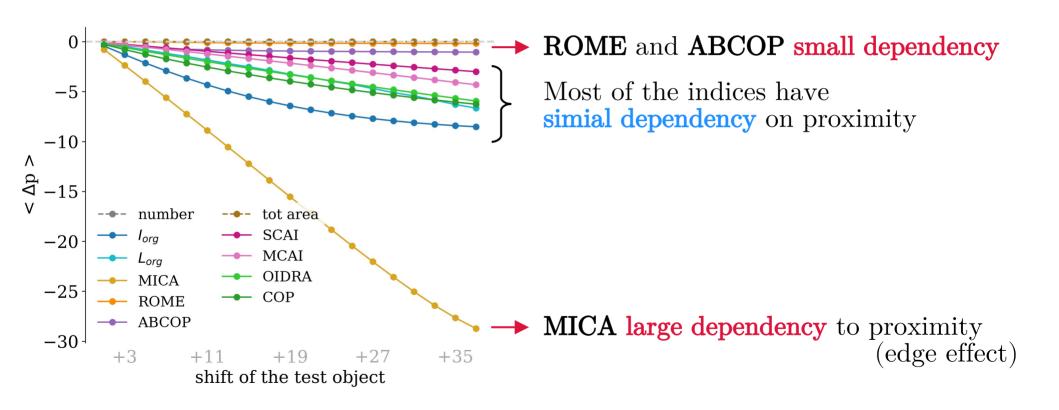
condition 2 sensitivity to proximity

Organization increases with the proximity?





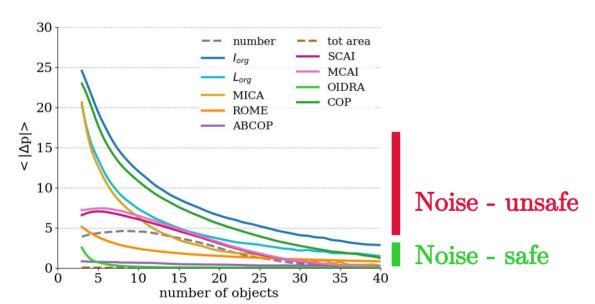
Organization increases with the proximity?



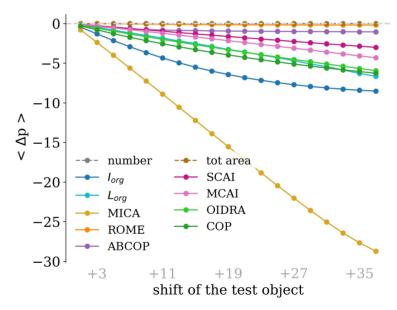
Take home message

Evaluation of the indices via their behavior

Noise – safeness for large number of objects



different sensitivities to **proximity**



Evaluation of the indices via their behavior

Noise-safeness

- 1º. do not change when one pixel is added
- 2°. do not change when two objects are merged by one single pixel

Intrinsic behavior

- 3°. slowing decreasing when objects are moving apart
- 4° . increase when one object is increasing

Compare across diverse datasets

- 5°. do not change with different resolutions
- 6°. do not change after a small time
- 7º. do not change in similar spatial regions

Submitted to GMD

- End -