GNSS lonosphere: How and Why (brief visual discovery)

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Eastern Africa Capacity Building Workshop on Space Weather and Low-latitude, Ionosphere Malindi, Kenya, 03 October 2023 to 12 October 2023







What is this?



UQRG-GIM Global VTEC maps 20231006.279.00000

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What is this?

Movie of the vertically integrated electron number density (AKA Vertical Total Electron Content, VTEC) of the partially ionized part of the Earth atmosphere (ionosphere) obtained from worldwide Global Navigation Satellite System (GNSS) multifrequency measurements

Do you wish to check the present global VTEC, from RT UPC-IonSAT GIMs? If yes:

UQRG-GIM Global VTEC maps 20231006.279.00000



http://chapman.upc.es/tomion/real-time/quick/last_results.uadg/RT-DAILY-VTEC-MOVIE.gif

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Why there are free electrons within the Earth atmosphere?





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Why there are free electrons within the Earth atmosphere?

The chemical reactions on the Earth atmosphere of dissociation of different molecules at different heights by solar photons (mostly in EUV and X-ray bands).





How can the VTEC distribution be explained?









How can the VTEC distribution be explained?



- In principle, taking into account with different solar irradiance in function of the latitude
- (And the Earth rotation!) UNIVERSITAT POLITÈCNICA DE CATALUNYA BARCELONATECH





Anything else to be explained? What about the double VTE® peak (equatorial anomaly)?









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ExB drift, generates the fountain effect, and then, the equatorial anomaly and double peak, with a central role of the magnetic field, the magnetic equator in particular, in the distribution of the free electrons of the Earth ionosphere.





And this? How can it be explained?



RO GPS PRN17 from COSMIC1-06 LEO (150E,50°S) on 01h30m,18Sep2011





And this? How can it be explained?

800

- The electron number density (hereinafter electron density) vs height(*).

- The intermediate electron density peak height can be understood as the optimal height of production of free electrons, a compromise between enough number of target molecules and enough ionizing solar radiation, specially in EUV.

(*) Estimated thanks to GNSS receivers flying on a Low Earth Orbiting satellite -in this case FORMOSAT-3/COSMICmeasuring multifrequency GNSS signals from transmitters below the LEO local horizon (radio-occultation scenario).



RO GPS PRN17 from COSMIC1-06 LEO (150E,50°S) on 01h30m,18Sep2011





And what about this? Any guess?







And what about this? Any guess?



Yes, these are four Global Positioning System (GPS) transmitter providing pseudodistance signals to a receiver on board an airplane (this an "artistic" composition NOT following the real distance scale).





And now, who can explain these layouts?







And now, who can explain these layouts?



Yes, it illustrates the trilateration concept, foundation of GNSS for positioning: knowing the position of the center of at least three(*) spheres in different directions -GNSS transmitters on MEOs- and the radius of such spheres -from the pseudorange measurements-, we get the receiver position X,Y,Z -intersection-).

But we need to get pseudoranges, right?





But we need to get pseudoranges, right? - "Pseudoranges" are computed from the apparent traveling time from GNSS transmitter to GNSS receiver.

- The pseudo-random noise transmitted signal, function of the atomic transmitter clock, is correlated at the receiver with its replica, generated from its typically quartz clock.

- Several "error" sources quickly arises, not only the transmitter and receiver clock errors, but also the atmospheric ones, including the ionospheric delay, all under the "pseudo" part of the observable pseudorange name. UNIVERSITAT POLITÈCNICA **DE CATALUNYA**





But we need to get pseudorange measuremens, right?





But we need to get pseudorange measuremens, right?

1. Code or pseudorange: This measurement is given by the apparent travel time τ of the EM signal propagated from GPS transmitter to receiver, scaled by the speed of light in the vacuum, *c*. This value can be partially considered as a range, i.e., a pseudorange $\tilde{\rho}$:

$$P \equiv c\tau = \tilde{\rho}$$







And we have a second "invited" type of measurement to the ²⁰ "GNSS party", very interesting, very precise: the carrier phase





And we have a second "invited" type of measurement to the ²¹ "GNSS party", very interesting, very precise: the carrier phase

2. Carrier phase: This measurement is computed in the receiver by continuously integrating the frequency Doppler shift, primarily due to the relative velocity, clocks, and tropospheric and ionospheric drifts. This value is scaled in unit lengths in such a way that it represents the pseudorange $\tilde{\rho}$ and basically refers to the last time the carrier phase was locked by the receiver t_L (i.e., the pseudorange change since the last "cycle-slip" or the first acquisition epoch).





And we have a second "invited" type of measurement to the ²² "GNSS party", very interesting, very precise: the carrier phase

$$\int_{t_{\rm L}}^{t} \dot{\tilde{\rho}} \,\mathrm{d}t = -\frac{c}{f} \int_{t_{\rm L}}^{t} \delta f \cdot \mathrm{d}t. \tag{5}$$

Thus, the carrier phase is finally defined as:

$$L \equiv -\lambda \int_{t_{\rm L}}^{t} \delta f \cdot dt = \tilde{\rho}(t) - \tilde{\rho}(t_{\rm L}) = \tilde{\rho} + B_f, \qquad (6)$$

where B_f is the carrier phase ambiguity for frequency f and $\lambda = c/f$ is the corresponding carrier wavelength.

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Now, any guess or comment about this plot?



lonospheric combination (meters, PRN01





Now, any guess or comment about this plot?

onospheric combination (meters, PRN01)

-We can see how the code (i.e. pseudorange) and phase measurements ("ionospheric combination") of a given GPS transmitter ("PRN01") from a given receiver, complement each other very well:

-The code measurements are accurate (pseudorange) but not precise (measurement noise and multipath >~1 m).

-Thecarrierphasemeasurements are not accurate(unknownambiguitypseudorange at phase lock) butveryprecise(measurementnoise and multipath < 1cm).</td>







Finally, the electron content is inside GNSS measurements!²⁵

rT

$$P_{m} = \rho + c(dt - dt') \left\{ + \frac{40.309}{f_{m}^{2}}S \right\} + T + D_{m} + D'_{m} \quad (15)$$

and
$$L_{m} = \rho + c(dt - dt') \left\{ - \frac{40.309}{f_{m}^{2}}S \right\} + T + B_{m} + \frac{c}{f_{m}}\phi \quad (16)$$
$$S = \int_{0}^{r_{R}} N_{e} dl \quad (14)$$





Finally, the electron content is inside GNSS measurements!²⁶

-The first-order approximation of the ionospheric delay term, deduced from the Appleton-Hartree equations of EM propogation, accounts for P99.9% of the the ionospheric delay of GNSS signals (L-band).

- It is positive (delay) for the ar pseudorange and negative (advance) for the carrier phase. L_n BTW: Is this an issue vs the relativity principle of "maximum velocity" the light speed in the vaccum?.

- The ionospheric delay term is proportional to the Slant Total $S = \int N_e dl$ Electron Content (Slant TEC, STEC) and inverserly proportional to the signal frequency.

$$P_m = \rho + c(dt - dt') + \frac{40.309}{f_m^2}S + T + D_m + D'_m \quad (15)$$
nd

$$a_m = \rho + c(dt - dt') - \frac{40.309}{f_m^2}S + T + B_m + \frac{c}{f_m}\phi$$
 (16)





Finally, the electron content is inside GNSS measurements! ²⁷

$$L_I \equiv L_1 - L_2 = \alpha \cdot S - \beta \cdot \phi + B_I, \tag{17}$$

$$P_I \equiv P_2 - P_1 = \alpha \cdot S + D_I + D'_I + \epsilon_M + \epsilon_T, \qquad (18)$$

where $\alpha = 40.309 \left(\frac{1}{f_2^2} - \frac{1}{f_1^2} \right) = 1.05 \cdot 10^{-17} \, m^3, \, \beta =$ $c\left(\frac{1}{f_2}-\frac{1}{f_1}\right) = 0.054 \,\mathrm{m}, B_I = B_1 - B_2, D_I = D_2 - D_1$ and $D'_{I} = D'_{2} - D'_{1}^{2}$. In this case, we also made explicit the two main components of the measurement error, both corresponding to the code: the multipath code error $\epsilon_{\rm M}$ and the thermal noise measurement error $\epsilon_{\rm T}$. Typically, the windup term $\beta \cdot \phi$ is a centimeter-level term. For the permanent receivers, this term can be corrected very accurately from their coordinates and orbital information, and it is not discussed explicitly herein.





Finally, the electron content is inside GNSS measurements!²⁸

highly -Then the variable ionospheric magnitude, STEC, is combination of dual-frequency carrier phases and pseudoranges as plasma bubble detection).

-Other additional terms, are either constant at scales of hours (ambiguity BI, Differential Code Biases, DI, DI') or are small and can be very well modelled (wind-up term $\beta * \phi$).



$$P_I \equiv P_2 - P_1 = \alpha \cdot S + D_I + D'_I + \epsilon_M + \epsilon_T, \qquad (18)$$

(L₁ & P₁): This is the main input data source for GNSS lonosphere! where $\alpha = 40.309 \left(\frac{1}{f_2^2} - \frac{1}{f_1^2}\right) = 1.05 \cdot 10^{-17} m^3$, $\beta =$ (among the good performance of $c\left(\frac{1}{f_2} - \frac{1}{f_1}\right) = 0.054 \text{ m}, B_I = B_1 - B_2, D_I = D_2 - D_1$ single-frequency measurements recently shown for certain and $D'_I = D'_2 - D'_1^2$. In this case, we also made explicit ionospheric viewing problems such the two main components of the measurement error, both corresponding to the code: the multipath code error $\epsilon_{\rm M}$ and the thermal noise measurement error $\epsilon_{\rm T}$. Typically, the windup term $\beta \cdot \phi$ is a centimeter-level term. For the permanent receivers, this term can be corrected very accurately from their coordinates and orbital information, and it is not discussed explicitly herein.



Conclusion: GNSS Ionosphere is well data-supported



~ 100 GNSS trans. & +1000 24/7 static GNSS rec. (+100 in RT)



Worldwide scanner of the lonosphere, an excellent input to generate Global lonospheric Maps (GIMs) of VTEC maps (summarizing Big GNSS data), among many other ways of modelling / studying the ionosphere



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Conclusion: GNSS Ionosphere is well data-supported

GNSS Ionosphere:

"Effects and computation of the distribution of free electrons, located at the partially ionized part of the atmosphere above 50 km height, from the Global Navigation Satellite Systems (GNSS) measurements, usually multi-frequency, crossing it; and its applications, such as Space Weather monitoring, precise realtime positioning and, in general, precise geodetic modelling among others"



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Use Case 10: Access to UPC-IonSAT Global Ionospheric Maps registrations (AKA global VTEC maps every 15 minutes since end of 1996, i.e. ~1 million global VTEC maps & 5x10^9 VTECs computed so far)

Manuel Hernández-Pajares, Victoria Graffigna, Alberto García-Rigo & Germán Olivares-Pulido on behalf of the UPC-IonSAT team



PITHIA-NRF TPW#5, Univ. Westminster, 12-13 September 2023





GNSS lonosphere

GNSS lonosphere¹: Effects and computation of the distribution of free electrons, located at the partially ionized part of the atmosphere above 50 km height, from the Global Navigation Satellite Systems (GNSS) multi-frequency measurements crossing it; and its applications, such as Space Weather monitoring, precise real-time positioning and, among others.







The ionosphere in brief seen by GNSS

 The ionosphere is typically distributed from around 50 km to 1000 km height, where some predominant air molecules, such as O₂ and NO at the very bottom and mostly O above, are partially ionized respectively by the x-ray and specially Extreme Ultraviolet (EUV) solar flux (see for instance²).

VTEC / TECUs 01h30m,18Sep2011 (source: UQRG GIMs from UPC-IonSAT)





²Peter Teunissen and Oliver Montenbruck. Springer handbook of global navigation satellite systems. Springer, 2017, 1327, DOI: 10.1007/978–3–319–42928–1.





Global Electron Content (GEC)

As consequence of its main origin, the total number of ionosphere free electrons (GEC) follows closely the solar activity, specially in normal (undisturbed) conditions: see the GEC time series obtained from the UQRG GIMs, computed every 15 minutes since end of 1996. The origin of features, like the semiannual and annual anomalies, are still under discussion (³).



GPS time / years (from 15-Nov-1996 to 03-May-2023)

³Francisco Azpilicueta and Claudio Brunini. "A new concept regarding the cause of ionosphere semiannual and annual anomalies". In: Journal of Geophysical Research: Space Physics 116.A1 (2011).




Introduction to TOMION model (2 of 3)



UPC Quarter-of-an-hour time resolution Rapid GIM (UQRG)

 It incorporates a Kalman filter and a kriging-based interpolation for the vertically integrated electron density (the vertical total electron content, VTEC, see⁶,⁷,⁸). HORIZON 2020

⁶M Hernandez-Pajares, JM Juan, and J Sanz. "Neural network modeling of the ionospheric electron content at global scale using GPS data". In: *Radio Science* 32.3 (1997), pp. 1081–1089.

⁷M Hernández-Pajares, JM Juan, and J Sanz. "New approaches in global ionospheric determination using ground GPS data". In: *Journal of Atmospheric and Solar-Terrestrial Physics* 61.16 (1999), pp. 1237–1247.

⁸R Orús et al. "Improvement of global ionospheric VTEC maps by using kriging interpolation technique". In: *Journal of Atmospheric and* Solar-Terrestrial Physics 67.16 (2005), pp. 1598–1609.





Introduction to TOMION model (3 of 3)

- TOMION is the software used in the generation of UPC-IonSAT GIMs of VTEC for the International GNSS Service (IGS), such as the UQRG one, one of the best behaving GIMs in IGS (⁹,¹⁰,¹¹).
- The tomography performed by TOMION is able to combine different data and geometries (¹²), in agreement with independent measurements and models (¹³,¹⁴), also in the polar regions (¹⁵).

⁹M Hernández-Pajares et al. "The IGS VTEC maps: a reliable source of ionospheric information since 1998". In: *Journal of Geodesy* 83.3-4 (2009), pp. 263–275.

¹⁰Manuel Hernández-Pajares et al. "Methodology and consistency of slant and vertical assessments for ionospheric electron content models". In: *Journal of Geodesy* 91.doi:10.1007/s00190-017-1032-z (2017), pp. 1405–1414.

¹¹David Roma-Dollase et al. "Consistency of seven different GNSS global ionospheric mapping techniques during one solar cycle". In: *Journal of Geodesy* 92.6 (2018), pp. 691–706.

¹²Manuel Hernández-Pajares et al. "A new way of improving global ionospheric maps by ionospheric tomography: consistent combination of multi-GNSS and multi-space geodetic dual-frequency measurements gathered from vessel-, LEO-and ground-based receivers". In: *Journal of Geodesy* 94.8 (2020), pp. 1–16.

¹³DV Kotov et al. "Coincident observations by the Kharkiv IS radar and ionosonde, DMSP and Arase (ERG) satellites, and FLIP model simulations: Implications for the NRLMSISE-00 hydrogen density, plasmasphere, and ionosphere". In: *Geophysical Research Letters* 45.16 (2018), pp. 8062–8071.

¹⁴DV Kotov et al. "Weak magnetic storms can modulate ionosphere-plasmasphere interaction significantly: Mechanisms and manifestations at mid-latitudes". In: *Journal of Geophysical Research: Space Physics* 124.11 (2019), pp. 9665–9675.

¹⁵Manuel Hernández-Pajares et al. "Polar Electron Content From GPS Data-Based Global Ionospheric Maps: Assessment, Case Studies, and Climatology". In: Journal of Geophysical Research: Space Physics 125.6 (2020), e2019JA027677.



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	EIS foF2 Long Term Prediction Maps	
	EIS foF2 Nowcast Maps	
	EIS hmF2 Nowcast Maps	
- All	EIS Ionospheric Alerts	
	EIS Near Real-Time TEC Maps	
	EPB_detectionTool	
	eSWua: lonograms database, autoscaled records	
	eSWua: lonograms database, manually scaled records	
	eSWua: Scintillation Indices and Total Electron Content (TEC) database	
	EUHFORIA: EUropean Heliospheric FORecasting Information Asset	
	GIM: Global Ionosphere Maps	
	hmF2_qModel	
	IAP-P Doppler sounder spectrograms	
	IPIM : Ionosphere-Plasmasphere IRAP Model	
	IRI: International Reference Ionosphere version 2001	
	IRTAM 3D global real-time assimilative model of ionospheric electron density	
	NOA Athens Digisonde (AT138) Data	
	RayTRIX-CQP: Oblique ionogram synthesizer with E, F1, F2 layer echo traces and MUFs, driven by IRTAM ionospheric nowcast	
	ROB-IONO Near-Real Time European Ionospheric Maps	
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GIM: Global Ionosphere Maps

Global Vertical Total Electron Content 2D map computed using UPC Rapid Network of GPS receivers

Interact

Interaction Method	Description	Data Format	Link
Direct Link to Data Collection	The GIM landing page has the list of data the 15-minutes maps.	text/html (click the link to show information on this ontology term)	<u>Open GIM Landing</u> <u>Page in new tab</u> ♂

Properties

Property	Value
Туре (1/2)	Receiver of GNSS signals (click the link to show information on this ontology term)
Туре (2/2)	Assimilative Model (click the link to show information on this ontology term)
Project	GIM: Global lonospheric Maps (click the link to show information on this metadata registration)
Data Level	Level 3 (click the link to show information on this ontology term)
Result	Not used
Permission	Creative Commons Attribution-NonCommercial-ShareAlike (click the link to show information on this ontology term)
	Property Type (1/2) Type (2/2) Project Data Level Result Permission

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Identifier Properties

Local ID	DataCollection_UPC- RapidNetwork_GIM
Namespace	pithia
Version	1
Created	Tuesday 20th Dec. 2022, 09:30:00
Last Modified	Tuesday 20th Dec. 2022, 09:30:00





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HIA-N P	Role (from Related Party (1/2) > Responsible Party Info)	Point of contact (click the link to show information on this ontology term)	
th Infrastruct	Party (from Related Party (1/2) > Responsible Party Info)	Manuel Hernandez-Pajares (click the link to show information on this metadata registration)	
X	Role (from Related Party (2/2) > Responsible Party Info)	Data Provider (click the link to show information on this ontology term)	
	Party (from Related Party (2/2) > Responsible Party Info)	UPC-IonSAT (click the link to show information on this metadata registration)	
	Result Time	Not used	
	Name (from Collection Results > Source > Online Resource)	GIM Landing Page	
	URL (from Collection Results > Source > Online Resource > Linkage)	http://cabrera.upc.es/upc_ionex_GPSonly-RINEXv3 ^亿	
	Protocol (from Collection Results > Source > Online Resource)	НТТР	
	Data Format (from Collection Results > Source > Online Resource)	text/html (click the link to show information on this ontology term)	
UNIVERSITAT POLITÈCNIC DE CATALUNYA BARCELONATECH	Description (from Collection Results > Source > Online	The GIM landing page has the list of the 15-minutes ionex files.	



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Ionospheric scales derived from UPC-IonSAT Global Ionospheric Maps 3rd URSI Atlantic / Asia-Pacific Radio Science Meeting

29 May - 3 June 2022

by

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0. Motivation

In this work we summarize the approach, results and answer to the question that we did ourselves almost two years ago:

Can the high temporal resolution <u>VTEC Global Ionospheric Maps</u> (GIM, such as UQRG generated by UPC-IonSAT since end 1996) directly provide **reliable estimation** of the spatial and temporal components of the **VTEC gradients**, and of a sensitive **Ionospheric storm scale index**, with **comparable results** to the corresponding indices proposed and generated by other colleagues from <u>raw GNSS data</u> (respectively Jakowski & Hoque 2019, and Nishioka et al. 2017)?

Jakowski, N., & Hoque, M. M. (2019). Estimation of spatial gradients and temporal variations of the total electron content using ground-based GNSS measurements. Space Weather, 17, 339–356. https://doi.org/10.1029/2018SW002119.

Nishioka, M., T. Tsugawa, H. Jin, and M. Ishii (2017), A new ionospheric storm scale based on TEC and f o F 2 statistics, Space Weather, 15, 228–239, doi:10.1002/2016SW001536.





1. Context: GNSS-based UQRG Global Ionospheric Map (GIM)

LOS Carrier phases in length units: **L1-L2** (measurement, corrected from windup)

Associated L1-L2 ambiguity, **BI** (unknown)

Electron density of LOS illuminated voxels: **Ne** (unknowns)

Straight line LOS length within given voxel: **I_{j,k,l}**



Two-Layer voxel tomographic estimation without ionospheric background model and with dualfrequency carrier phase input data only. with in-house TOMION software.

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Kriging interpolation which preserves the details

Resolution: 15min x 5° x 2.5° in time x lon.xlat



1. Context: TOMION software

- TOMION is a data driven ionospheric model originally developed by the second authors of this presentation during the latest 25 years
- It allows a tomographic estimation of the density of free ionospheric electrons from GNSS carrier phase dual-frequency data only, without any background model.
- It incorporates a Kalman filter and a kriging-based interpolation for the vertically integrated electron density (the vertical total electron content, VTEC, see Hernández-Pajares et al. 1997, 1999, Orús et al. 2005).
- TOMION is the software used in the generation of UPC-IonSAT global ionospheric maps (GIMs) of VTEC for the International GNSS Service (IGS), such as the UQRG one, one of the outperforming GIMs, or even the best behaving GIM in IGS (Hernández-Pajares et al. 2009,2017, Roma-Dollase et al. 2018).
- UQRG GIM produced by TOMION is, for instance, able to detect realistic features of the polar ionosphere as well (Hernández-Pajares et al. 2020a) and to provide a realistic and sensitive storm index (Qi et al. 2021).
- The tomography performed by TOMION is able to ingest different geometries and types of input measurements (Hernández-Pajares et al. 2020b), in agreement with independent measurements and models (Kotov et al. 2018, 2019).





2. Defining the components of VTEC gradient from the GIM



DE CATALUNYA BARCELONATECH The spatial and temporal components of VTEC gradient at grid points of UQRG GIM on a global scale are introduced.

The VTEC gradient derived from UQRG GIMs (VgUG, Liu et al. 2022), **allows** to obtain full (non-relative) values of TEC spatial gradients and temporal variations **separately at any worldwide grid point**, considering the distances on the corresponding parallels and meridians at the ionospheric efective height, Δ DLON & Δ DLAT, separated 5° & 2.5° respectively, and the time difference between GIMs Δ t (30 minutes, centered, 15 minutes, uncentered).

 $\nabla V_{x,i,j} = (VTEC_{i,j} - VTEC_{i-1,j}) / \Delta DLON$

 $\nabla V_{y,i,j} = (VTEC_{i,j} - VTEC_{i,j-1})/\Delta DLAT$

 $\nabla V_{i,j} = \sqrt{\nabla V_{x,i,j}^2 + \nabla V_{y,i,j}^2}$ $\vec{\nabla V} = (\nabla V_{x,i,j}, \nabla V_{y,i,j})$

$$\dot{V}_{i,j} = \Delta VTEC_{i,j} / \Delta t = (VTEC_{i,j,t} - VTEC_{i,j,t-1}) / \Delta t$$

55

2.1 Example of global distribution of VTEC spatial gradient

Compared with the quiet ionospheric state, the VTEC spatial and temporal gradient directly derived from the GIM are able to capture the extraordinary VTEC variations during the disturbed ionospheric state, spltted in north, east and time components.

St. Patrick's Day 2015 Geomagnetic Storm



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3. Definition of regional indices from the VTEC gradient

Indeed the **Regional VTEC spatial Gradient indices**, based on UQRG (*RVGU*) and the temporal one, the **Regional Ionospheric Disturbance index** based on UQRG (*RIDU*), are proposed to estimate the regional ionospheric perturbation degree over selected regions. And they allow us **to compare them with similar indices computed previously and independently with different approaches** by other research groups.

$$\begin{cases} \overline{\nabla V} = \sum_{i=1}^{N} \sum_{j=1}^{M} \nabla V_{i,j} / N_{S} \\ \sigma_{\nabla V} = \sqrt{\left(\sum_{i=1}^{N} \sum_{j=1}^{M} \nabla V_{i,j}^{2}\right) / N_{S} - \overline{\nabla V}^{2}} \\ \nabla V_{P_{95}} = P_{95}(\nabla V_{i,j}) \end{cases}$$

$$\begin{cases} \overline{\nabla V_x} = \sum_{i=1}^{N} \sum_{j=1}^{M} \nabla V_{x,i,j} / N_S \\ \nabla V_{x,P_{95+}} = P_{95}(\nabla V_{x,i,j,p}) \\ \nabla V_{x,P_{95-}} = -P_{95}(|\nabla V_{x,i,j,n}|) \\ \overline{\nabla V_y} = \sum_{i=1}^{N} \sum_{j=1}^{M} \nabla V_{y,i,j} / N_S \\ \nabla V_{y,P_{95+}} = P_{95}(\nabla V_{y,i,j,p}) \\ \nabla V_{y,P_{95-}} = -P_{95}(|\nabla V_{y,i,j,n}|) \end{cases}$$

$$RIDU = \sum_{i=1}^{n} \sum_{j=1}^{m} \dot{V}_{i,j} / N_S$$





3.1 Example of comparison of GIM- vs raw-GNSS data- base³ regional spatial indices over Europe: Quiet conditions (20-25 May

2015)

Spatial

norm

Latitudinal gradient component

UPC



From raw GNSS data (Jakowski & Hoque (2017)



3.1 Example of comparison of GIM- vs raw-GNSS data- base⁵d regional spatial indices over Europe: Quiet conditions (20-25 May 2015) -Continued- From UQRG GIM (VgUG) From raw GNSS data





60

40

20 0

-20

-40 -60

Input receivers / IPPs used in the region

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3.2 Example of comparison of GIM- vs raw-GNSS data- base⁶d regional spatial indices over Europe: St. Patricks Day ionospheric storm (16-20 March 2015) -Continued-









3.3 Example of comparison of GIM- vs raw-GNSS data- base³d regional **spatial** indices over Europe: Halloween storm (28 Oct -1 Nov 2003) -Continued-



Both regional indices based on the VTEC gradient norm and on the VTEC gradient latitudinal components provide results very comparable when GIM-based and raw-GNSS-based results are considered. The longitudinal component of the VTEC gradient appear correlated but smaller when they are computed from GIMs.

B.



3.3 Example of comparison of GIM- vs raw-GNSS data- based regional temporal indices over Europe: Solar flare X17.0 class preceding Halloween storm (28 Oct 2003)

Sudden Ionospheric Disturbance indeX (SIDX)

From **UQRG GIM (VgUG),** Regional Ionospheric Disturbance index (Liu et al. 2022)

 $RIDU = \sum_{i=1}^{n} \sum_{j=1}^{m} \dot{V}_{i,j} / N_S$



The **GIM-based** temporal component of the VTEC gradient is only sensitive to very strong flares, and it appears smoothed, as it might be expected from the GIM interpolation procedure in space and time. For detecting and measuring the solar EUV flux rate during flares (two products provided by UPC-IonSAT to the Space Weather community in RT), the global raw GNSS measurements in the daylight hemisphere, perform in an excellent way (Hernández-

S.

Pajares et al. 2012).

4. Extending the definition of the lonospheric storm scale index to GIMs (IsUG)

We propose the Ionospheric Storm Scale Index Based on UQRG (IsUG) as a direct extension of the I-scale index proposed at regional level (Japan) and from raw GNSS data by Nishioka et al. (2017):

$$P_{TEC} = \frac{100 \times (O_{TEC} - R_{TEC})}{R_{TEC}} \qquad \qquad \hat{P}_{TEC} = \frac{P_{TEC} - \mu}{\sigma}$$

It is defined as the standardized Ptec, P_{TEC} , where Ptec is the percentage deviation of VTEC, Otec is the hourly median VTEC derived at grid points of GIM. The hourly median VTEC is the median of the five VTEC values during 1-h interval, under the GIM VTEC temporal resolution of 15 min. The hourly median VTEC is calculated every hour (for example, 0, 1, 2 UT). Rtec is the reference median value at the same local time and geographic location in the past 27 days.

IsUG	Description	Definition	Probability on a global scale (%
IP3	Severe positive storm	$5 < \hat{P}$	0.17
IP2	Strong positive storm	$3 < \hat{P} \le 5$	0.72
IP1	Moderate positive storm	$1 < \hat{P} \leq 3$	12.43
10	Quiet	$-1 < \hat{P} \leq 1$	73.96
IN1	Moderate negative storm	$-2 < \hat{P} \leq -1$	11.72
IN2	Strong negative storm	$-3 < \hat{P} \leq -2$	0.95
IN3	Severe negative storm	$\hat{P} < -3$	0.06

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4.1 Comparing Ptec from GIM with Ptec from raw GNSS data over Japan since 1997 to 2014 (3 months of seasonal data per year)



UPC

4.2 Comparing \hat{P}_{TEC} from GIM \hat{P}_{TEC} from raw GNSS data over Japan since 1997 to 2014 (3 months of seasonal data per year)





4.3 Summary of Ptec and \hat{P}_{TEC} comparison from GIM vs. from raw GNSS data over Japan since 1997 to 2014 (3 months of seasonal data per year)

Table 1

Comparison of P_{TEC} Distribution Parameters During 1997–2014 Between the Values Derived From UQRG (Input for IsUG Index) and the Values Derived in Nishioka et al. (2017) as Input to I-Scale

				$P_{TEC}(UQRQ-GIM)$			<i>P_{TEC}</i> (raw-GNSS-data)		
					(this work	()	(Nisł	nioka et al.,	, 2017)
Season	LT	Long.	Lat.	σ	μ	per. 20%	σ	μ	per. 20%
March Equi.	20 h	130°E	30°N	0.28	0.150	60.0	0.33	0.19	54.3
June Equi.	20 h	130°E	30°N	0.19	-0.001	71.4	0.20	-0.02	69.7
March Equi.	12 h	130°E	30°N	0.22	0.098	66.1	0.26	0.08	62.1
March Equi.	20 h	140°E	40°N	0.23	0.178	56.9	0.27	0.22	50.2

Table 2

Comparison of the Percentiles for $|\hat{P}_{TEC}| \leq 1$ During 1997–2014 Between the Values Derived From UQRG (Input for IsUG Index) and the Values Derived in Nishioka et al. (2017) as Input to I-Scale

 $\hat{P}_{TEC}(UQRQ-GIM)$

 \hat{P}_{TEC} (raw-GNSS-data)

^	
D	
1	TEC

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Ptec

				(this work)	(Nishioka et al., 2017)
Season	LT	Long.	Lat.	perc. $ \hat{P}_{TEC} \leq 1$	perc. $ \hat{P}_{TEC} \leq 1$
March Equi.	20 h	130°E	30°N	77.7	77.5
June Equi.	20 h	130°E	30°N	69.7	72.9
March Equi.	12 h	130°E	30°N	72.5	72.6
March Equi.	20 h	140°E	40°N	71.7	72.3

4.5 Snapshots of IsUG maps of November 7 2004 (severe geomagnetic storm⁶⁹)



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4.5 Snapshots of IsUG maps during November 7-November 8 2004 (severe ⁷⁰ geomagnetic storm) -Continued-(a) 2004-11-07 22:00 (b) 2004-11-07 23:00



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4.6 Animation of IsUG maps during a quiet period

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4.6 Animation of IsUG maps during a ionospheric storm period

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000 UPC 2004-11-07 (doy: 312) 00:00:00




5. Conclusions

- The regional gradient indices based on UQRG open a new way to estimate the ionospheric perturbation degree at selected regions, consistent in a large extent with direct raw-GNSS based approaches. And the spatial and temporal VTEC gradient at each grid point of UQRG allow the representation of ionospheric perturbations on a global scale.
- The new ionospheric storm scale, IsUG, has a great potential for characterization of ionospheric state and the scientific study of ionospheric storms from a global perspective, being consistent with the raw-GNSS based original implementation in Japan during one and half solar cycles (1997-2014).
- \checkmark More details can be found at:

Liu, Q., Hernández-Pajares, M., Lyu, H., Nishioka, M., Yang, H., Monte-Moreno, E., ... & Orús-Pérez, R. (2021). Ionospheric Storm Scale Index Based on High Time Resolution UPC-IonSAT Global Ionospheric Maps (IsUG). Space Weather, 19(11), e2021SW002853.

Liu, Q., Hernández-Pajares, M., Yang, H., Monte-Moreno, E., García-Rigo, A., Lyu, H., ... & Orús-Pérez, R. (2022). A New Way of Estimating the Spatial and Temporal Components of the Vertical Total Electron Content Gradient Based on UPC-IonSAT Global Ionosphere Maps. Space Weather, 20(2), e2021SW002926.





Space Weather RESEARCH ARTICLE

10.1029/2021SW002853

Key Points:

- The new ionospheric storm scale, IsUG, is presented
- The IsUG is based on the high resolution and rapid UPC-IonSAT Global Ionosphere Maps (UQRG) Statistical analysis is carried out
- on a global scale from 1997 to 2014 comparing well with the available raw GNSS data based I-scale index

Supporting Information: Supporting Information may be found ماه تغییر مانداد کر میرونسین میزانید. مراد مراد

Ionospheric Storm Scale Index Based on High Time Resolution UPC-IonSAT Global Ionospheric Maps (IsUG)

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Thanks for your attention!

Space Weather

RESEARCH ARTICLE 10.1029/2021SW002926

Key Points:

- A new ionospheric temporal and spatial gradient index based on UPC-IonSAT Global Ionosphere Maps (UQRG) are presented at the selected
- The new ionospheric spatial gradients indices at grid points of UQRG are presented
- The derived ionospheric spatial gradients and temporal variations indices are analyzed during quiet and

disturbed ionosphere states

A New Way of Estimating the Spatial and Temporal **Components of the Vertical Total Electron Content Gradient Based on UPC-IonSAT Global Ionosphere Maps** Qi Liu¹ ⁽⁶⁾, Manuel Hernández-Pajares^{1,2} ⁽⁶⁾, Heng Yang^{1,3} ⁽⁶⁾, Enric Monte-Moreno⁴ ⁽⁶⁾, Alberto García-Rigo^{1,2}, Haixia Lyu^{1,5}, Germán Olivares-Pulido¹, and Raül Orús-Pérez⁶

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Backup Slides





Abstract

The ionospheric response to high geomagnetic activity, the ionospheric storm, can enlarge GNSS positioning errors by the increase of ionospheric electron density and disable high-frequency communications by the decrease of the ionospheric electron density. In addition, the ionospheric perturbations with high spatial and temporal components of VTEC gradient might also enlarge GNSS positioning errors and even incapacitate Satellite-Based Augmentation System (SBAS) and Ground-Based Augmentation System (GBAS) services[1][2]. UPC Quarter-of-an-hour time resolution Rapid GIM (UQRG) is derived from GNSS carrier phase measurements assuming a two-layer tomographic TEC model and interpolated by Kriging technique with a spatial resolution of 5° and 2.5° in longitude and latitude, respectively[3]. The characteristics and performance of UQRG GIMs[4][5] have allowed us to define two new GIM-derived ionospheric scales:

(1) The Ionospheric storm scale derived from UQRG GIMs (IsUG[6]) is defined as the percentage deviations of hourly median VTEC extracted at each grid point of historical UQRG (from 1997 to 2014), and it is normalized (subtract the mean and divide by the corresponding standard deviation) in order to remove the dependence of VTEC variations on season, local time and geographical location. The level of ionospheric storm from the proposed ionospheric storm scale is consistent with previous studies.

(2) The VTEC gradient derived from UQRG GIMs (VgUG[7]), which allow to obtain full (non-relative) values of TEC spatial gradients and temporal variations separately. Indeed the Regional VTEC spatial Gradient indices, based on UQRG (RVGU) and the Regional Ionospheric Disturbance index based on UQRG (RIDU), are proposed to estimate the regional ionospheric perturbation degree over selected regions. In addition, the spatial and temporal components of VTEC at grid points of UQRG on a global scale are also introduced. Compared with quiet ionospheric state, the VTEC spatial and temporal gradient indices are able to capture the variations of VTEC spatial and temporal gradient during the disturbed ionospheric state.

Acknowledgements:

The work has been performed within the context of MoNEWIC ESA and PITHIA-NRF European Commission activities.

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1. Context

Total Electron Content (TEC) extraction based on GNSS



- Ionospheric error of GNSS observations is proportional to TEC and inversely proportional to signal frequency => combination of GNSS observations for extracting TEC
- Global GNSS network => Global ionospheric sounding and modeling
 вакселоматесн



1. Motivation

Irregular Ionosphere variation





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Figure from Grebowsky and Aikin, 2009

1. Motivation

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Space weather impacts









Solar Geomagnetic coordinates

Z-axis: Boreal Magnetic Pole (from dipolar model), unity vector $\mathbf{k} = \mathbf{R}_{\mathbf{R}}$ Y-axis: unity vector $j = R_{B} \times R_{C}$ Sun pointing vector: unity vector/R X-axis: unity vector i = j x k

From the projection of the unity vector pointing to the ionospheric pierce point, **R**, on the new axis, **i**,**j**,**k**, we can retrieve the Solar-Magnetic Local Time (SMLT) and Magnetic Latitude, MLAT:

 $\mathbf{R}\cdot\mathbf{k} = \sin(\mathbf{MLAT})$ $\mathbf{R} \cdot \mathbf{j} = \cos(\mathsf{MLAT}) * \sin(\mathsf{SMLT})$ $\mathbf{R} \cdot \mathbf{i} = \cos(\mathbf{MLAT}) * \cos(\mathbf{SMLT})$



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Tomographic implementation



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How?: RT-TOMION computing global VTEC maps based on GNSS data





2.1 Spatial and temporal components of VTEC gradient

Evolution of Regional VTEC spatial Gradient indices



2.1 Spatial and temporal components of VTEC gradient

Evolution of Regional VTEC spatial Gradient indices



2.1 Spatial and temporal components of VTEC gradient

boxplot of VTEC spatial gradient









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Ionospheric storm

Joule Heating Penetration Electric Field

Thermospheric Wind

Increase in electron density

Fountain Effect

Positive Storm

Joule HeatingCarry air with
large [N2]/[O]Ion Loss larger
compared with
ion productionDecrease in
electron
density

Negative Storm





Figure from https://swc.nict.go.jp/en/knowledge/ionosphere.html

Users know the receiver-satellites geometry and can compute bounds on the horizontal and vertical position errors.

These bounds are called Protection Levels (HPL and VPL). They provide good confidence (10^{-7} /hour probability) that the true position is within a the corresponding cylinder/ellipsoid around the computed position.



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