



Accurate Wireless LoRa Path Loss Prediction with Machine Learning for Airborne Internet of Things Networks (AIN) in Rural Tropics

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## *Workshop on Communication in Extreme Environments for Science and Sustainable Development*

Haider A.H. Alobaidy, Rosdiadee Nordin, J. S. Mandeep, Nor Fadzilah Abdullah, Azril Haniz, Kentaro Ishizu, Takeshi Matsumura, Fumihide Kojima, and Nordin Ramli, "Low Altitude Platform-based Airborne IoT Network (LAP-AIN) for Water Quality Monitoring in Harsh Tropical Environment", *IEEE Internet of Things Journal*, 9(20): 20034-20054



### Focus



Design and Implementation of AIN Path Loss Prediction with Machine Learning Lesson Learned from AIN Rekindle Interest Towards Non-Terrestrial Network





- Seven (7) stations to monitor the water quality across the Chini Lake
- Measuring various water quality parameters; pH, turbidity, dissolved oxygen, etc.

Pusat Penyelidikan Tasik Chini (PPTC) is Tasik Chini Research Centre Martin and an annual inclusion

Gumum Station

Lake Chini Resort

Kura-Kura Station

lemberau Station

Jerangking Station

ai Station

Chini Station

### Critical Challenges Facing Water Quality Monitoring at Chini Lake



## AIN Deployment















# LoRa Propagation Characterization using Hybrid Machine Learning: Reliability, Coverage, and PL Limits

- Area types: Urban, rural, suburban (at UKM campus) and rural (at Lake Chini and surrounding)
- LoRa performance metrics: (1) <u>communication reliability</u>, (2) <u>coverage</u>, and
   (3) <u>path loss limits</u> via DT (car drive test), BDT (boat drive test)





Measured PL vs. predicted PL plots from FSPL (baseline), LNSPL, and Cloud-RF<sup>®</sup>-based models



Modified Cloud-RF<sup>®</sup> based models performance. (a) Actual vs. predicted PL correlation. (b) Residuals vs. actual PL scatter plot

- None of the well-known PL models are suitable for PL prediction in the study area under consideration
- Indicated the need for additional research to address this issue and propose new models that fit well in such harsh tropical areas

#### Accuracy evaluation in terms of different metrics

Model	MSE	RMSE	MAE	MAAPE	R	R <sup>2</sup>
FSPL	1458	38.18	36	28.04	0.54	-5.36
LNSPL	189.74	13.78	10.994	8.84	0.54	0.17
ITM	743.97	27.27	24.31	19.47	0.58	-2.25
Cost 231-Hata	888.55	29.81	27.03	21.38	0.62	-2.88
ECC-33	386.94	19.67	16.404	12.79	0.63	-0.69
Modified ITM	279.37	16.71	12.28	9.65	0.58	-0.22
Modified Cost 231- Hata	160.47	12.67	10.07	8.18	0.62	0.299
Modified ECC-33	141.23	11.88	9.62	7.82	0.63	0.383

#### **Still performing poorly**

#### Propagation Characterization using Hybrid Machine Learning



- The proposed model comprises of three stacked models.
- Compared to the popular LNSPL model, the proposed model can be represented as follows:

 $PL_{Proposed}[dB] = PL_{FS}(f, d_0 = 1m) + PL_{StWi}[dB] + X_{Ens}[dB]$ 



Flowchart of the raytracing simulation for LOS/NLOS analysis and geographical features extraction.

#### Propagation Characterization using Hybrid Machine Learning



Measured vs. predicted PL from FSPL (baseline), LNSPL, and the proposed model for training, testing, and overall dataset



**Uniformly distributed** 

Proposed PL model performance. (a) Actual vs. predicted PL correlation scatter plots. (b) Residuals vs. actual PL scatter plot with a 2D histogram, showing the density of the residuals spread across the range of actual PL.

## Propagation Characterization using Hybrid Machine Learning

<u>The proposed model outperforms other conventional PL models</u> as it is more flexible and provides the highest prediction accuracy, especially in rural and suburban areas.

	Set	MSE	RMSE	MAE	MAAPE	R	R <sup>2</sup>	<b>91.8%</b>			
	Training	19.13	4.37	3.38	2.79	0.958	0.918	00.20/			
	Testing	21.76	4.67	3.87	3.24	0.945	0.892	69.2%			
	Urban training	21.32	4.62	3.64	2.82	0.918	0.834	•			
	Urban testing	22.15	4.71	3.84	3.01	0.885	0.779				
	Suburban training	17.16	4.14	3.18	2.69	0.96	0.92				
	Suburban testing	22.07	4.7	3.91	3.3	0.938	0.879				
	Rural campus training	22.9	4.79	3.73	3.11	0.935	0.871				
	Rural campus testing	21.81	4.67	3.84	3.25	0.921	0.847				
	Rural forest (Chini) training	26.56	5.15	4.15	3.07	0.939	0.877				
N N	Rural forest (Chini) testing	22.74	4.77	3.97	2.97	0.937	0.869				
	Rural lake (Chini) training	19.69	4.44	3.44	2.71	0.973	0.947				
се	Rural lake (Chini) testing	19.5	4.42	3.68	2.97	0.971	0.941	04 50/			
	Rural training	22.37	4.73	3.69	2.98	0.957	0.915	91.5%			
	Rural testing	21.16	4.6	3.8	3.12	0.955	0.911	,			
	Rural all	22.19	4.71	3.71	3.01	0.957	0.914				
	All	19.51	4.42	3.45	2.86	0.957	0.915	13			
		Low error across all metrics									

Highest prediction accuracy

94%

```
Best
performance
91.8% ~
```

## Lesson Learned & Opportunities

- Limited availability & accessibility of helium gas with high operation cost in remote areas
- Alternative solutions that do not heavily rely on helium or explore more sustainable lifting gases
- Helikite balloon may be further stabilized remotely by using an RC gondola
- Increase the helium retention period by coating the balloon surface with nanomaterials or use other materials, such as aerogel
- Expanding the LAP system usage by adapting other sensors onboard



## LAP Communications in Rural & Underserved Area





(a) NTFPs, satellites, and tower masts.

B. E. Y. Belmekki and M. -S. Alouini, "Unleashing the Potential of Networked Tethered Flying Platforms: Prospects, Challenges, and Applications," in *IEEE Open Journal of Vehicular Technology*, vol. 3, pp. 278-320, 2022

## Key Takeways

The challenge to push wireless connectivity in tropical setting based on rural lake forest and tough climate in Malaysia via AIN, a form of LAP-IoT

Explore opportunity to introduce a path loss model for LPWAN communications, based on combination of empirical and deterministic using Machine Learning

The implementation of AIN in rural area encountered with several challenges, such as technical, practical and cost

With the surging interest on NTN in 6G, will there be an opportunity to rekindle interest of LAP for rural or sustainable development?

## **Thank You!**



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