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MAGNETIC Confinement

Force on a charged particle:

$$\vec{F} = q(\vec{v} \times \vec{B} + \vec{E})$$

Simplest case:

$$\vec{B} = B \hat{z} \quad \text{constant} \quad \vec{E} = \emptyset$$

$$m \dot{\vec{v}} = q(\vec{v} \times B \hat{z}) \quad \vec{v} \equiv v_x \hat{x} + v_y \hat{y} + v_z \hat{z}$$

$$\dot{v}_z \hat{z} = \frac{q}{m} (\vec{v} \times B \hat{z}) \cdot \hat{z} \hat{z} = \emptyset$$

$$\dot{v}_z = \emptyset \rightarrow \boxed{v_z = ct}$$

$$\dot{v}_x = \frac{q}{m} (\vec{v} \times B \hat{z})_{ix} = \frac{qB}{m} v_y$$

$$\dot{v}_y = \frac{q}{m} (\vec{v} \times B \hat{z})_{iy} = -\frac{qB}{m} v_x$$

coupled

$$\ddot{v}_x = \omega_c \dot{v}_y = -\omega_c^2 v_x$$

$$\ddot{v}_y = -\omega_c \dot{v}_x = -\omega_c^2 v_y$$

Where

$$\boxed{\omega_c \equiv \frac{qB}{m}}$$

The general solution is

$$V_x = v_{\perp} \cos(\omega_c t + \phi)$$

$$\dot{V}_x = -\omega_c v_{\perp} \sin(\omega_c t + \phi) = \omega_c V_y$$

$$V_y = -\frac{q}{|q|} v_{\perp} \sin(\omega_c t + \phi)$$

$\frac{q}{|q|}$ is just the sign of the charge, so:

$$\begin{aligned} V_y &= \mp v_{\perp} \sin(\omega_c t + \phi) \\ \text{for } V_x &= v_{\perp} \cos(\omega_c t + \phi) \end{aligned}$$

integrating:

$$\begin{aligned} X &= X_0 + \frac{v_{\perp}}{\omega_c} \sin(\omega_c t + \phi) \\ Y &= Y_0 \pm \frac{v_{\perp}}{\omega_c} \cos(\omega_c t + \phi) \end{aligned}$$

So particles gyrate around a point (X_0, Y_0) with a frequency $\boxed{\omega_c = \frac{|q|B}{m}}$

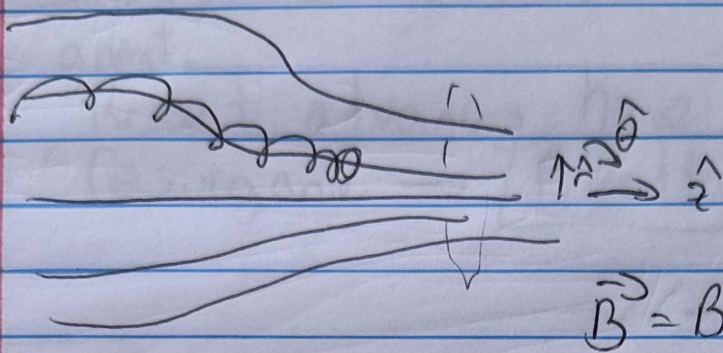
and a radius: $\boxed{r = \frac{v_{\perp}}{\omega_c} = \frac{mv_{\perp}}{|q|B}}$

For ITER, $i = \text{Deuterium}$, $T_i \approx 10 \text{ KeV}$, $B \approx 5 \text{ T}$

$$\left(\begin{array}{l} v_{T_i} = \sqrt{\frac{kT_i}{m}} \approx 700 \text{ km/s} \\) \quad \left(\begin{array}{l} r_i \approx 3 \text{ mm} \\ \text{for } T_e = T_i \rightarrow r_e = 0.05 \text{ mm} \end{array} \right.$$

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First Magnetron Configuration: Mirror



B_r causes $m \frac{dV_z}{dt} = -qV_\perp B_r$

Results in a net force $m \frac{dz}{dt}$

$$F_z = - \frac{mV_\perp^2}{2B} \frac{\partial B_z}{\partial z} = - \mu \frac{\partial B_z}{\partial z}$$

where $\mu \equiv \frac{mV_\perp^2}{2B}$ = ~~ad~~ magnetic moment
adiabatic invariant

as B increases V_\perp increases

Power = $\vec{v} \cdot \vec{F} = \vec{v} \cdot (\vec{v} \times \vec{B}) = 0 \Rightarrow$ Conservation of energy

so $\frac{1}{2} m V_\perp^2 + \frac{1}{2} m V_z^2 = \text{const}$

As particles flow towards \hat{z} , B increases, V_\perp increases, V_z decreases. Sometimes

$V_z = 0$ and reflects \Rightarrow mirror

While this approach is simple to build, the losses have been too great.

Recent advances have led to a resurgence \rightarrow [Realta]

Lets add an $\vec{E} = \vec{E}_\perp + \vec{E}_\parallel$ $\vec{B} = \vec{B}_\parallel$

$$F = m \frac{d\vec{v}}{dt} = q (\vec{v} \times \vec{B} + \vec{E})$$

$$\dot{v}_\parallel = \frac{q}{m} E_\parallel \rightarrow \boxed{v_\parallel = v_{\parallel 0} + \frac{q E_\parallel}{m} t}$$

constant acceleration

$$\dot{\vec{v}}_\perp = \frac{q}{m} (\vec{v} \times \vec{B} + \vec{E}_\perp)$$

For simplicity, assume $\vec{B} = B \hat{z}$, $\vec{E} = E \hat{x}$

$$\dot{v}_x = \frac{q}{m} (v_y B + E)$$

$$\dot{v}_y = -\frac{q}{m} (v_x B)$$

$$v_y' \equiv v_y + E/B \rightarrow \dot{v}_y' = \dot{v}_y$$

$$\dot{v}_x = \frac{q}{m} (v_y' B) \rightarrow \ddot{v}_x = -\omega_c^2 v_x$$

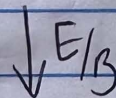
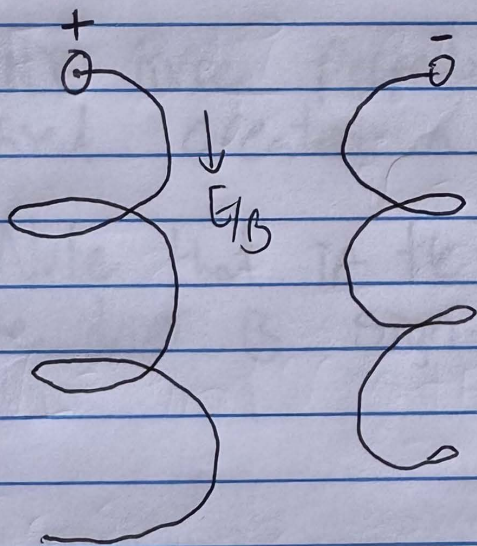
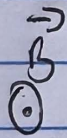
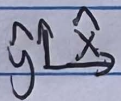
$$\ddot{v}_y' = -\omega_c^2 (v_y')$$

the solutions are similar to the $E=0$ solutions:

$$V_x = V_{\perp} \cos(\omega_c t + \phi)$$

$$V_y = \mp V_{\perp} \sin(\omega_c t + \phi)$$

$$V_y = \mp V_{\perp} \sin(\omega_c t + \phi) - \frac{E}{B} \leftarrow V_{Ex/B}$$



Same direction
for both
charges

Generalized

$$\frac{E \times B}{B^2} = V_{Ex/B}$$

We can generalize to any external force perpendicular to \vec{B} : \vec{F}_{\perp}

$$m \frac{d\vec{v}}{dt} = q \vec{v} \times \vec{B} + \vec{F}_{\perp}$$

$$\vec{v}_{\perp} = \frac{q}{m} \vec{v}_{\perp} \times \vec{B} + \frac{\vec{F}_{\perp}}{m} \Rightarrow \vec{v}_{\perp} = \vec{v}_{\perp} - \frac{\vec{F}_{\perp} \times \vec{B}}{q m B^2}$$

$$+ [-\vec{F}_{E\perp}(\vec{B}\cdot\vec{B}) + \vec{B}(\vec{F}_{E\perp}\cdot\vec{B})]$$

$$\vec{v}_\perp \times \vec{B} = \vec{v}_\perp \times \vec{B} - \frac{(\vec{F}_{E\perp} \times \vec{B}) \times \vec{B}}{qB^2}$$

$$\vec{v}_\perp \times \vec{B} = \vec{v}_\perp \times \vec{B} + \frac{\vec{F}_{E\perp}}{q}$$

$$\text{So } \dot{\vec{v}}_\perp = \frac{q}{m} \vec{v}_\perp \times \vec{B} \Rightarrow \text{Gyro motion}$$

$$\text{So } \vec{v}_\perp \text{ has a drift} = \boxed{\vec{v}_D = \frac{\vec{F}_{E\perp} \times \vec{B}}{qB^2}}$$

ANY force perpendicular to the magnetic field creates a drift perp. to both

Note that if the force is indep. of q , the drift is sign-dependent.

We move to the obvious question:
How about a magnetic field that
bites its own tail?

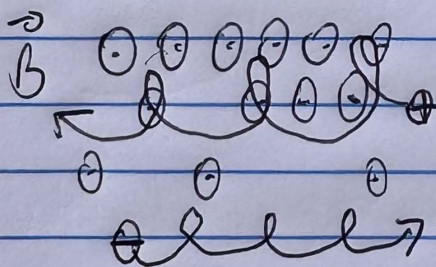
Curvature Drift arises as an effect
of the centrifugal force in the
plasma frame:

$$F_{CF} = \frac{m v_{||}^2}{R_c} \hat{r}$$

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$$V_R = \frac{m v_{||}^2}{q B^2} \frac{\vec{R}_c \times \vec{B}}{R_c^2}$$

∇B Drift arises due to varying
mag. fields perp. to \vec{B} :



$$V_{\nabla B} = \frac{m v_{\perp}^2}{2 q B} \frac{\vec{B} \times \nabla B}{B^2}$$

These add to make purely toroidal
fields untenable (refer to slides)