

Workshop on Fully Programmable Systems-on-Chip for Scientific Applications

VHDL Fo thesis

ICTP 1964-2024

Cristian Sisterna

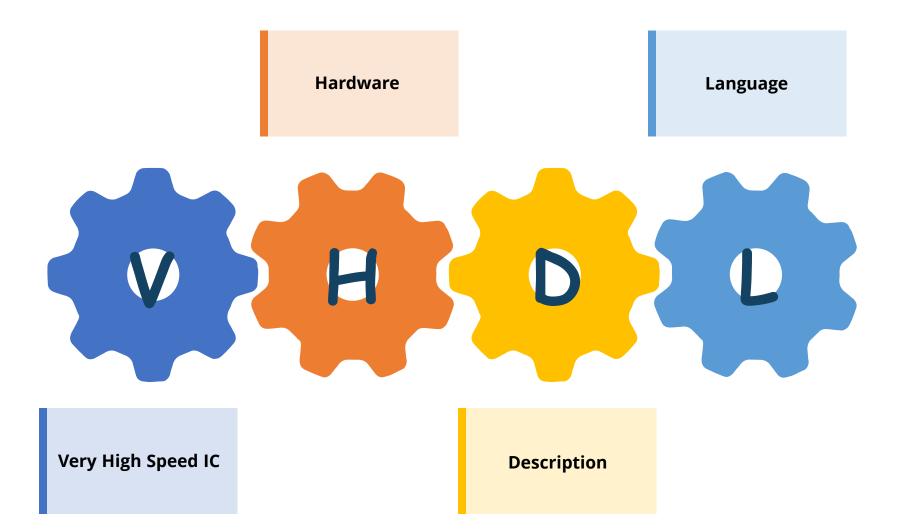
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Introduction



Hardware Description Language

High level of abstraction

```
if(reset='1') then
    count <= 0;
elsif(rising_edge(clk)) then
    count <= count+1;
end if;</pre>
```

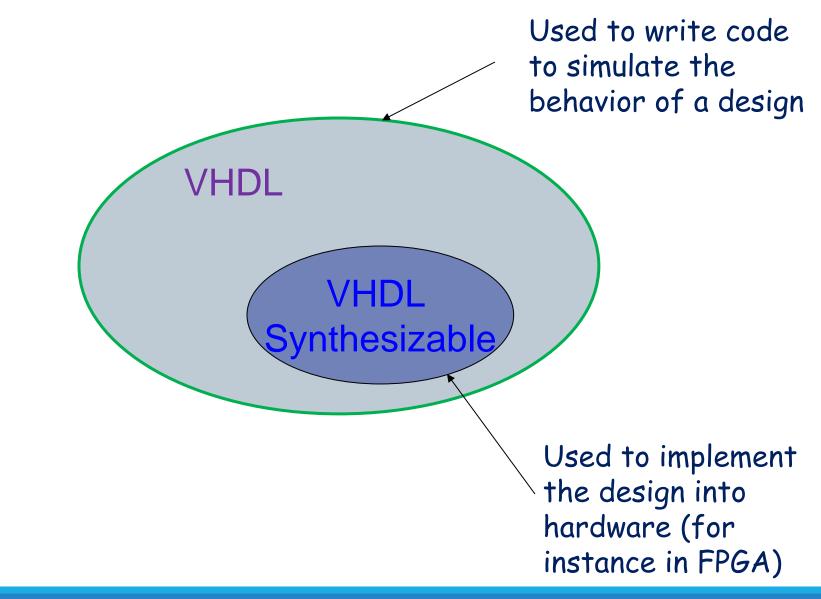
Easy to debug

Parameterized designs

Re-uso

IP Cores (free) available

HDL Synthesis Sub-Set



HDL Synthesis Sub-Set

✓ VHDL is used to DESCRIBE the behavior and/or structure of a Digital System

Be careful ! -> you are *describing Hardware*

Concurrent Code -> Executed in Paralell

✓ With HDL it is possible to describe from a simple combinational circuit to a whole i7 processor

VHDL Describing Digital System

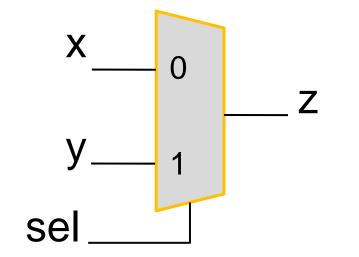
- The operations in real systems are executed concurrently.
- The VHDL language describes real systems as a set of components (statements) that operate concurrently.
 - Each of these components is described with concurrent statements.
- The complexity of each component may vary from a simple logic gate to a processor

Synthesis versus Simulation

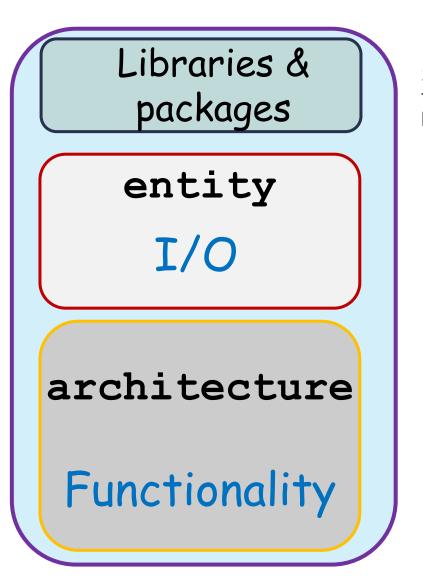
Extremely important to understand that VHLD is both, a *Synthesis* language and a *Simulation* language.

- Small subset of the language is '*synthesizable*', meaning that it can be translated into logic gates, flip-flops, and other 'hardware' components
 - Every line of VHDL code must have a direct translation into hardware.
- Another subset of the language include many features for '*simulation*' or '*verification*', features that have NO meaning in hardware

VHDL 'Description' Examples



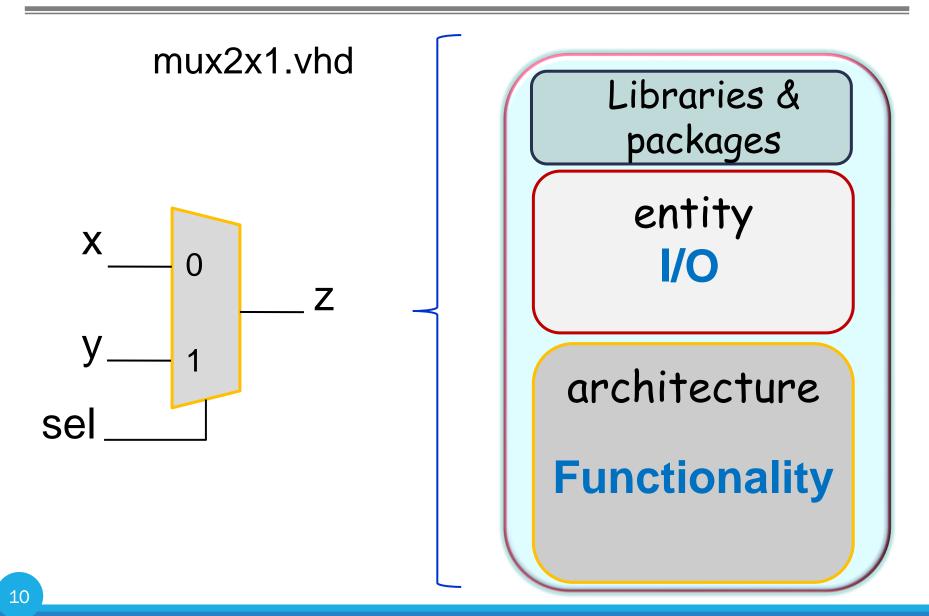
z <= y when sel='1' else x;

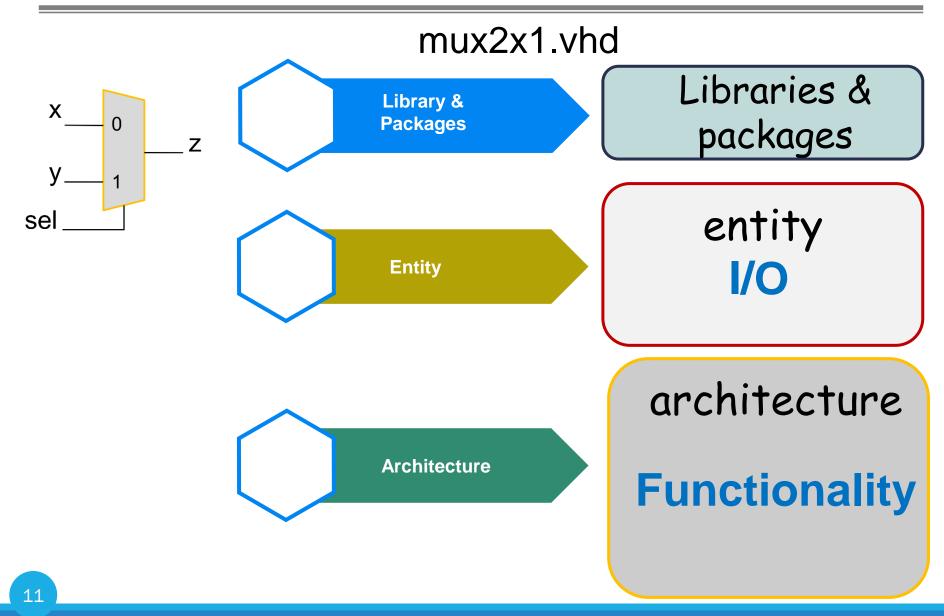


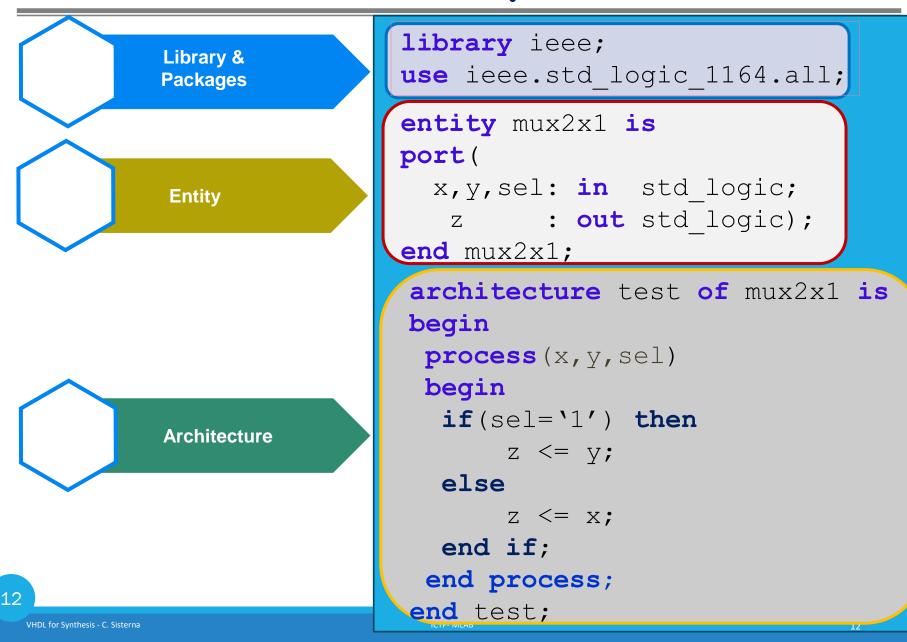
Libraries and packages provides the incorporation of external functions, data types and components to the component to be described

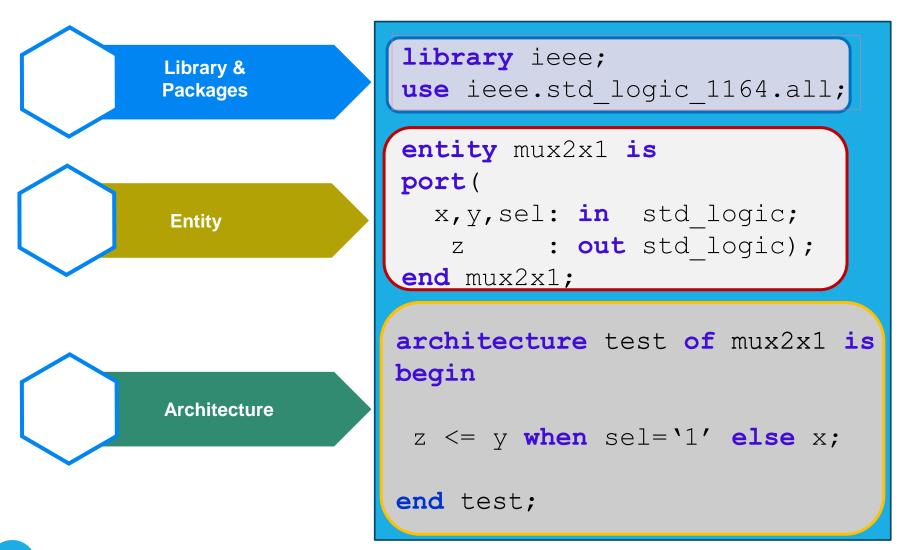
Defines the I/O ports as well as the name of the component. Some times a constant(s) is defined (generic) to write parameterized VHDL code

It's where the hardware **behavior** and/or **structure** is described. It can have from 1 to thousands lines of code… ALL CONCURRENTs !

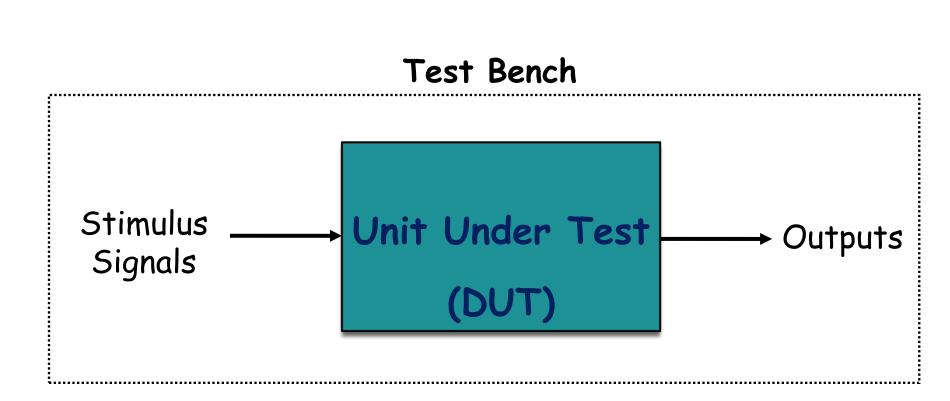


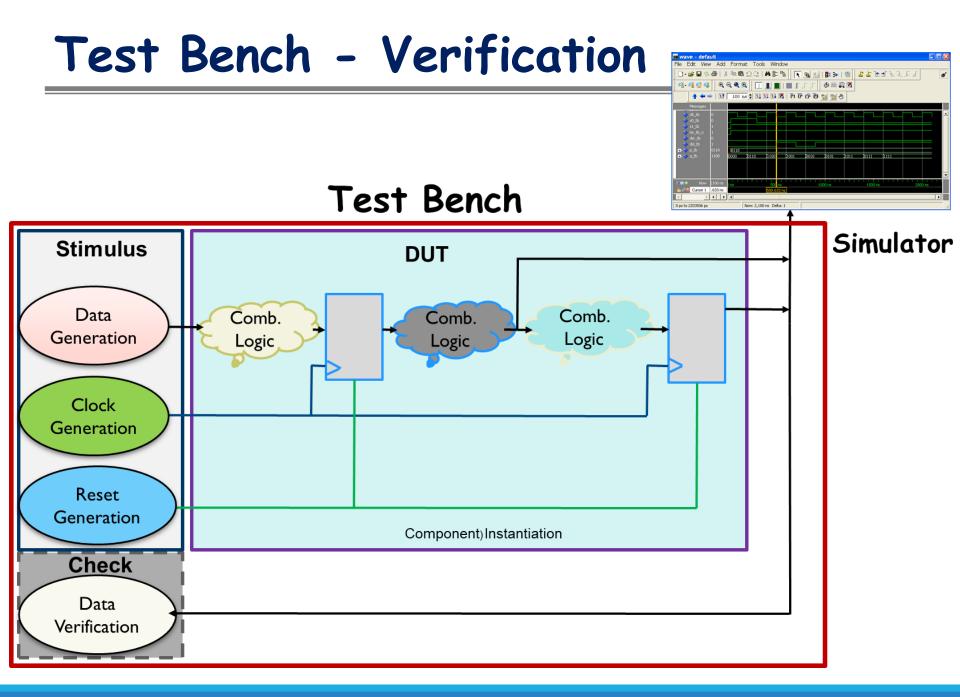






VHDL Code - Is it really Works?

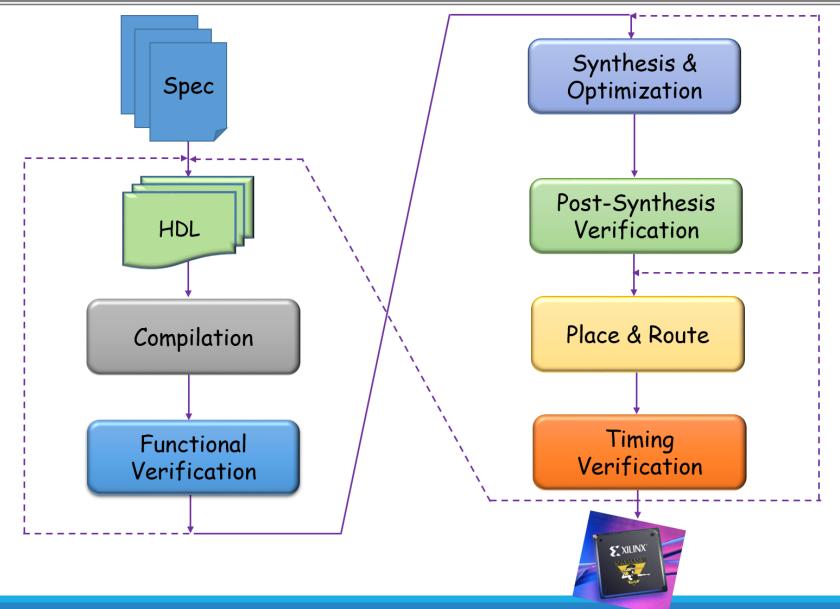




VHDL - Simulation / Verification

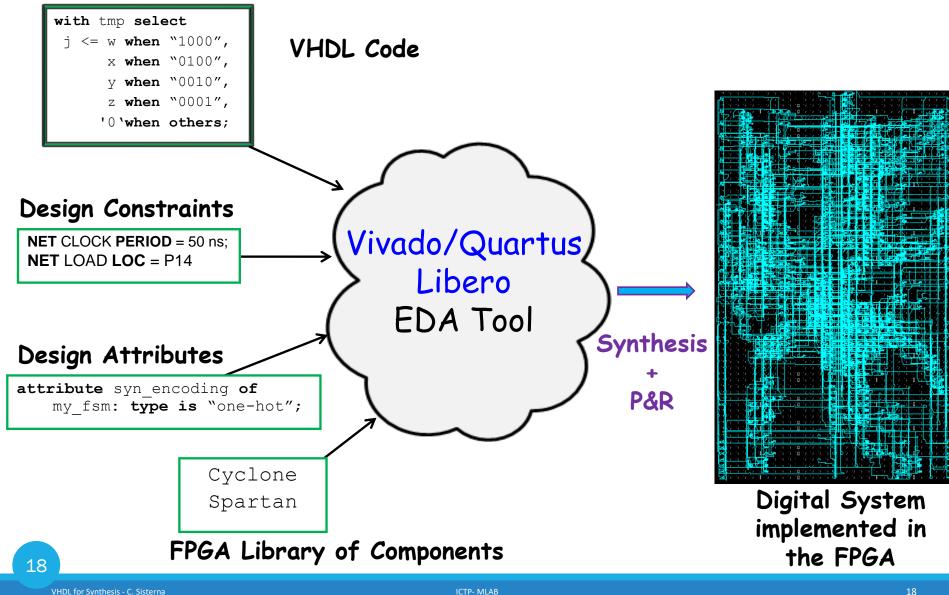
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VHDL - FPGA Design Flow



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VHDL - FPGA: Synthesis + P&R



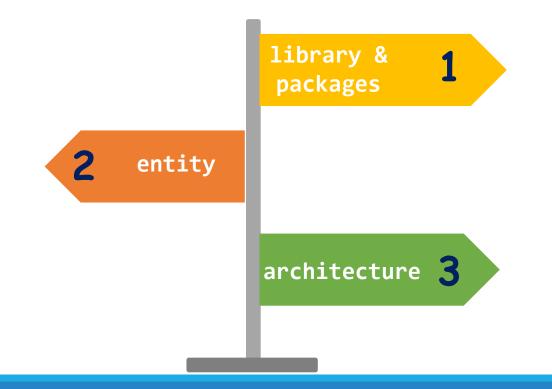
VHDL for Synthesis - C. Sisterna

VHDL Simple Example

Simple Example - VHDL

Design a BCD up-down counter. The count should be displayed in a 7-segment display.

The system has a high frequency clock and system reset as inputs.



Libraries & Packages



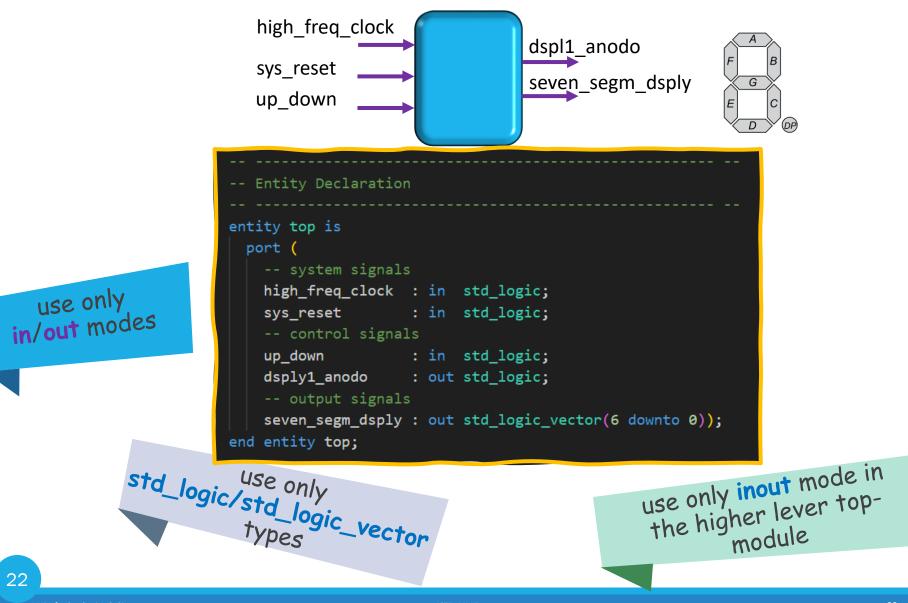
library ieee; use ieee.std_logic_1164.all;

Must be present to use std_logic type. That is, for ALL synthesisable designs.

-- Synopsys non-standard packages
-- use ieee.std logic_arith.all;
-- use ieee.std_logic_signed.all;
-- use ieee.std_logic_unsigned.all;
DO NOT USE these

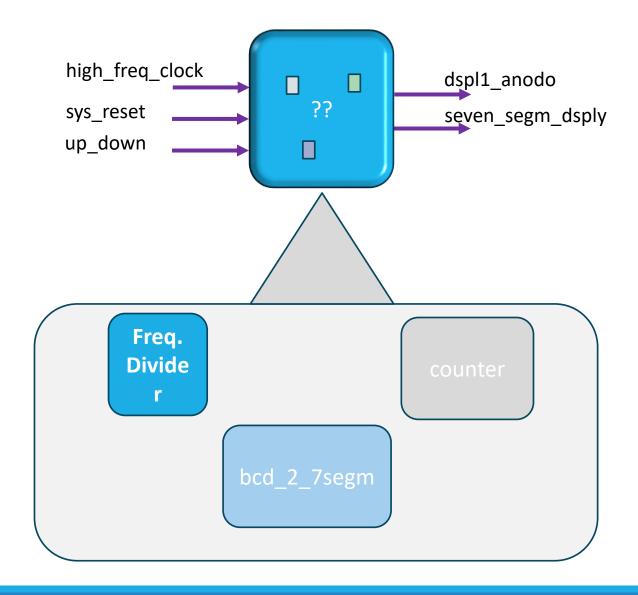
packages. There do not belong to the VHDL IEEE standard.

Signal/Port Declarations in the Entity

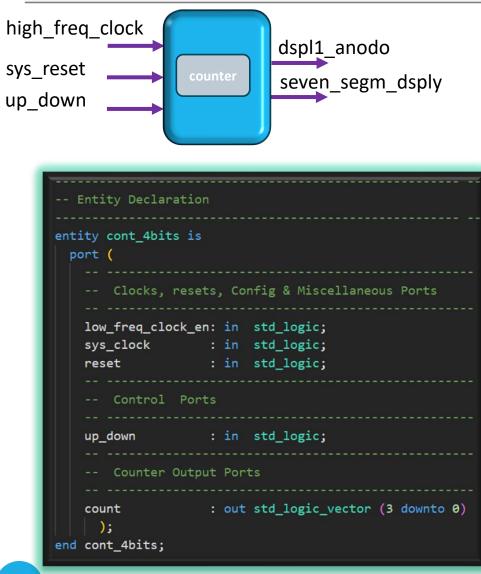


ICTP- MLAB

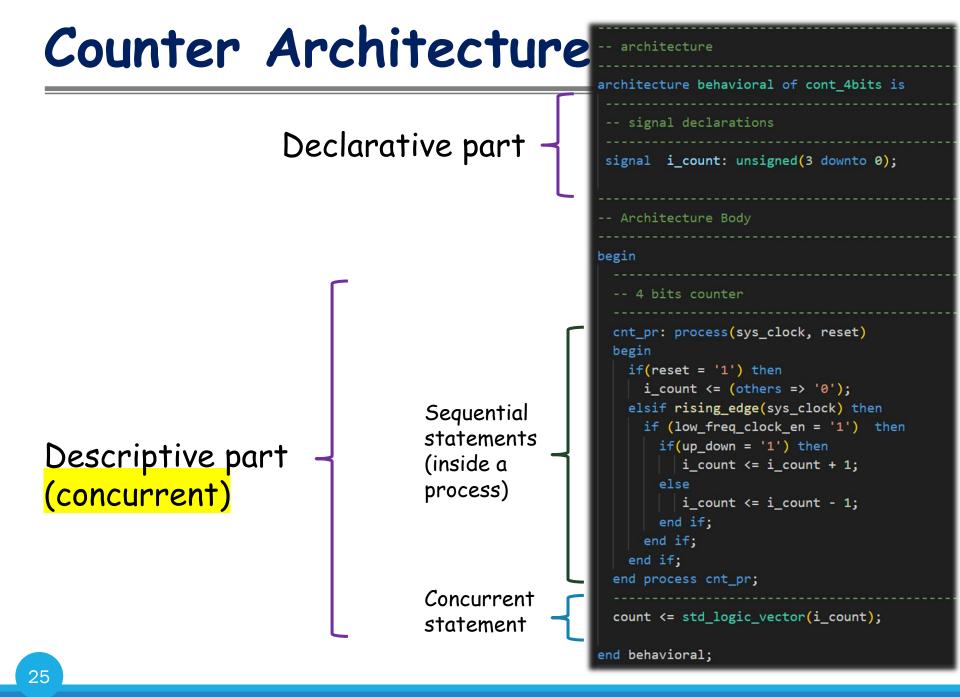
Architecture (top)



Counter entity/arch.



architecture
architecture behavioral of cont_4bits is
signal declarations
<pre>signal i_count: unsigned(3 downto 0);</pre>
Architecture Body
begin
4 bits counter
<pre>cnt_pr: process(sys_clock, reset) begin</pre>
<pre>if(reset = '1') then i_count <= (others => '0'); elsif rising_edge(sys_clock) then if (low_freq_clock_en = '1') then if(up_down = '1') then i_count <= i_count + 1; else i_count <= i_count + 1; else i_count <= i_count - 1; end if; end if; end if; end process cnt_pr;</pre>
<pre>count <= std_logic_vector(i_count);</pre>
end behavioral;



Understanding Concurrency

architecture example of entity_ex is

-- architecture declarative part

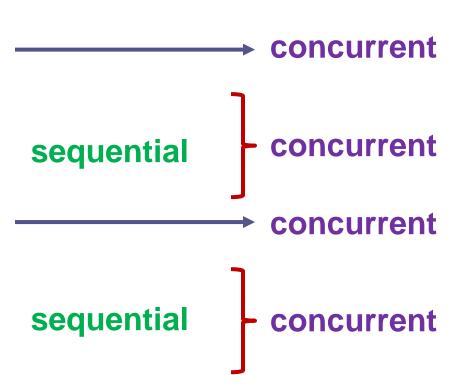
begin

-- architecture descriptive part

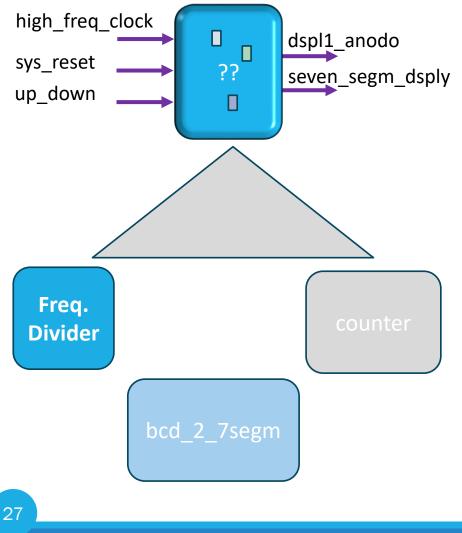
signal assignment concurrent statement; signal assignment concurrent statement; process concurrent statement;

begin

signal assignment sequential statement; signal assignment sequential statement; end process; signal assignment concurrent statement; process concurrent statement; begin signal assignment sequential statement; signal assignment sequential statement; end process; end example;



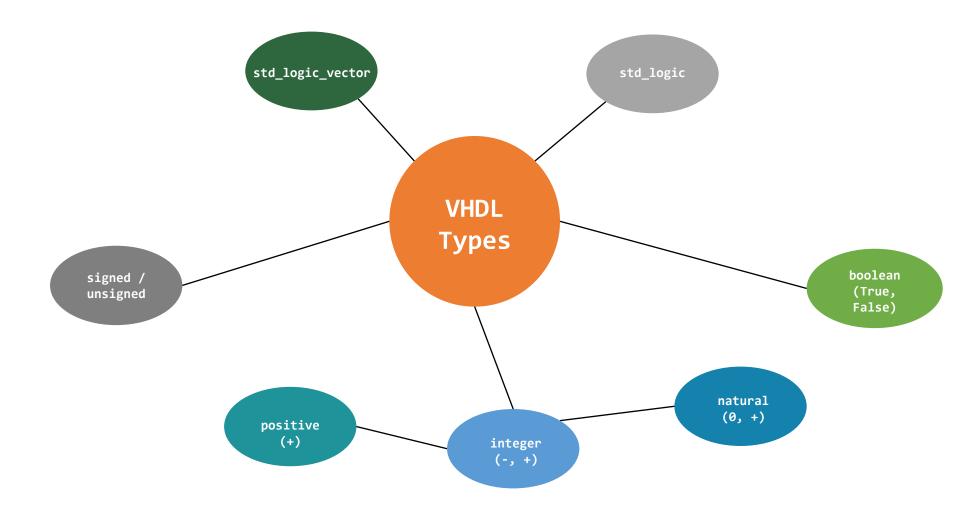
Architecture (top)



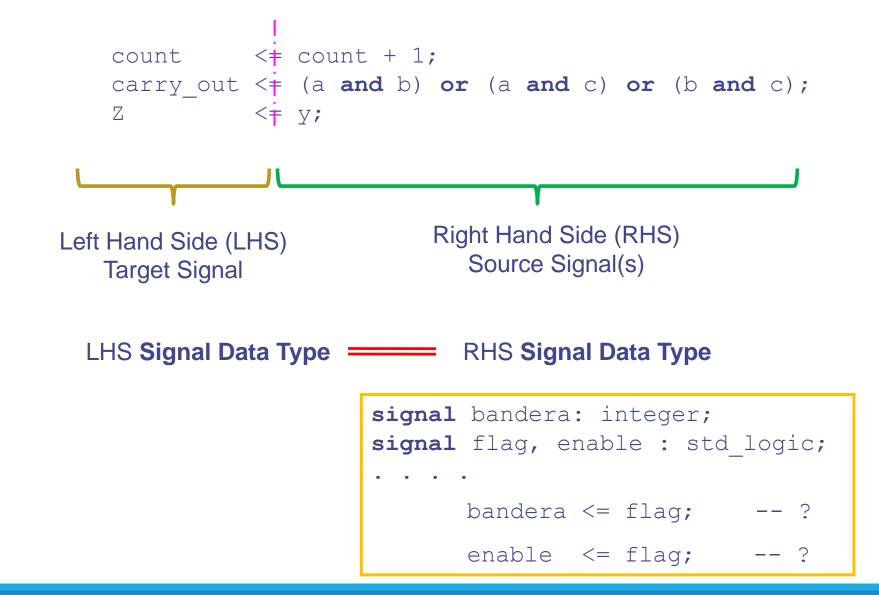
architecture
architecture structural of top is
internal signal declarations
signal count_i : std_logic_vector(3 downto 0); signal low_freq_clock_en_i : std_logic;
architecture body
begin
component instantiations
·····
bdc-7seg decoder bcd_7seg_1: entity work.bcd_7seg port map (
<pre>bcd_in => count_i,</pre>
<pre>segs_out => seven_segm_dsply, enable => '1',</pre>
<pre>dot_out => open);</pre>
divisor de frecuencia (50MHz-> ~ 1 seg)
<pre>freq_div_1: entity work.freq_div port map (</pre>
<pre>sys_rst => sys_reset,</pre>
<pre>sys_clock_50 => high_freq_clock,</pre>
<pre>low_freq_clock_en => low_freq_clock_en_i);</pre>
contador de 4 bits con reloj de baja frecuencia
<pre>cont_4bits_1: entity work.cont_4bits</pre>
port map (
<pre>low_freq_clock_en => low_freq_clock_en_i,</pre>
<pre>sys_clock => high_freq_clock,</pre>
reset => sys_reset,
<pre>up_down => up_down, count => count_i);</pre>
count => count_1);

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VHDL Data Types

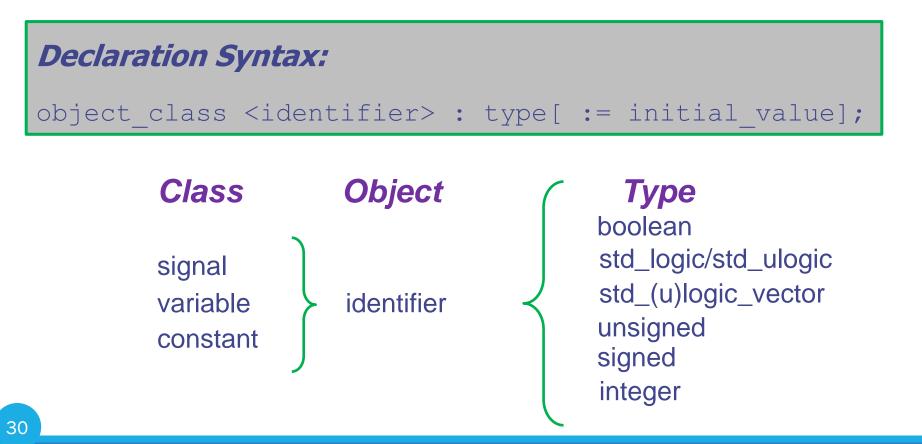


Signal Assignment - strongly typed

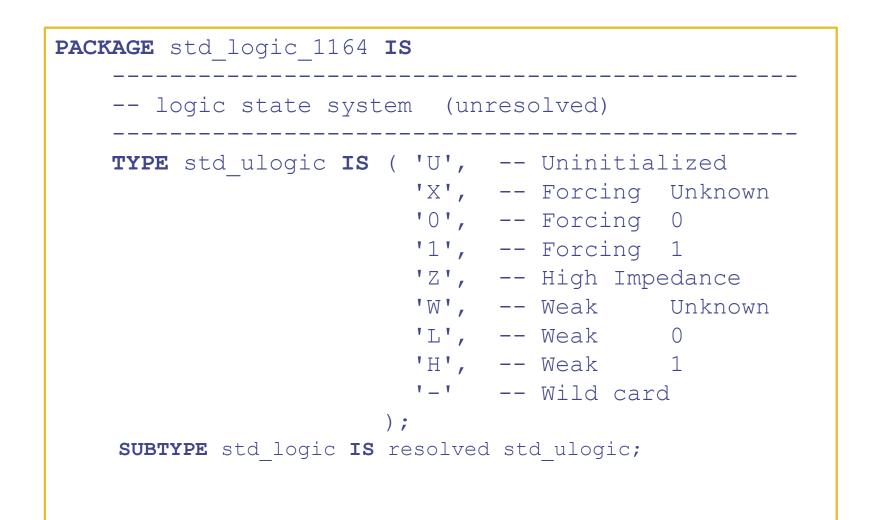


VHDL Object

An **object** holds a value of some specified **type** and can be one of the three **classes**: **signal**, **variable**, **constant**



std_logic Type



Type Conversion - Casting

VHDL does allow restricted type of <u>CASTING</u>, that is converting values between related types

```
datatype <= type(data_object);</pre>
```

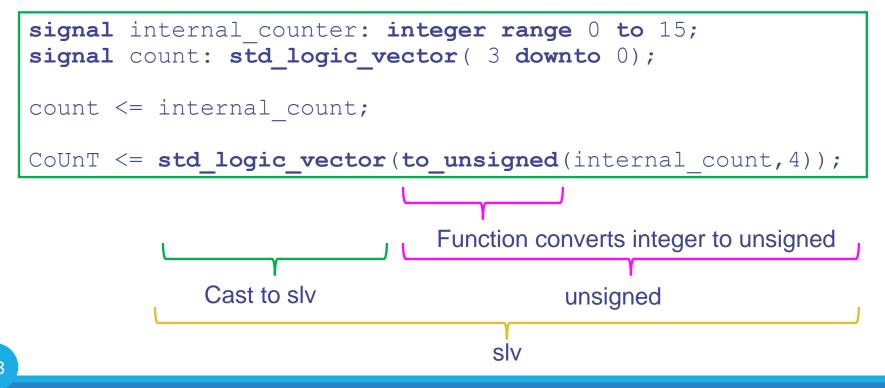
```
signal max_rem: unsigned (7 downto 0);
signal more_t: std_logic_vector( 7 downto 0);
max_rem <= more_t;
max_rem <= unsigned(more_t);</pre>
```

unsigned and std_logic_vector are both vectors of the same element type, therefore it's possible a direct conversion by casting. When there is not type relationship a conversion function is used.

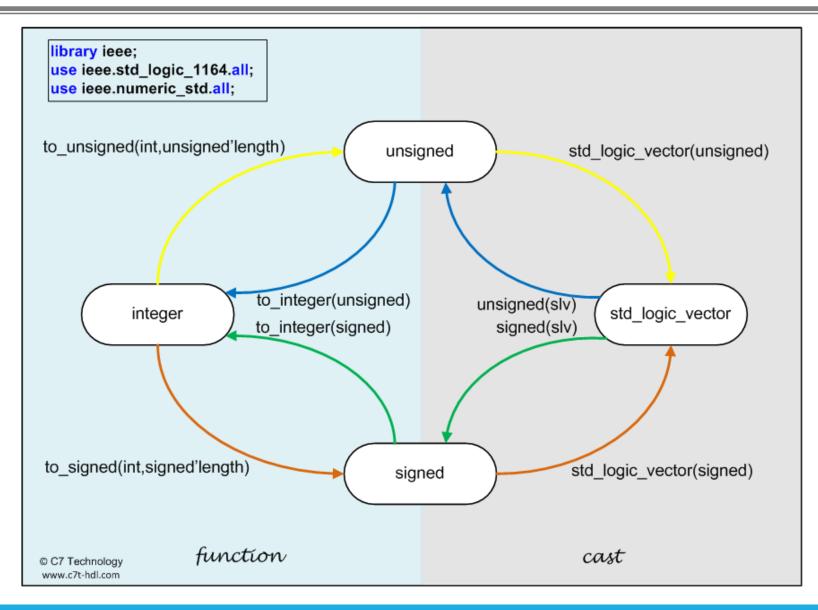
Type Conversion - Functions

VHDL does have some built-in functions to convert some different data types (not all the types allow conversions)

datatype <= to_type(data_object);</pre>



Type Conversion - Cast / Function

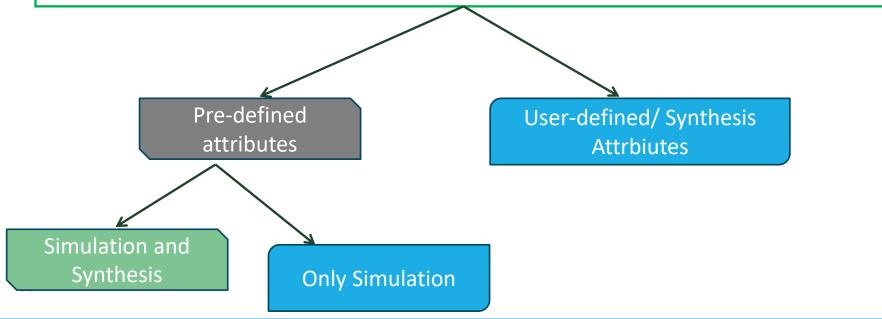


VHDL Operators

Operator	Description	Data type of a	Data type of b	Data type of result		
a ** b	exponentiation	integer				
abs a	absolute value	integer				
not a	negation	boolean, bit, bit_vector				
a * b, a / b, a mod b, a rem b	multiplication, division, modulo, remainder	integer				
+a, -a	identity, negation	integer		integer		
a + b, a - b	addition, subtraction,	integer				
a & b	concatenation	1D array, element				
a sll b, a srl b, a sla b, a sra b, a rol b, a ror b	shift-left (right) logical, shift-left (right) arithmetic, rotate left (right)	bit_vector	integer	bit_vector		
a = b, a /= b,		any	same as a	boolean		
a < b, a <= b, a > b, a >= b		scalar or 1D array	same as a	boolean		
a and b, a or b, a xor b, a nand b, a nor b, a xnor b		boolean, bit, bit_vector	same as a	same as a		

VHDL Attributes

- It's way of extracting information from a type, from the values of a type or it might define new implicit signals from explicitly declared signals
- It's also a way to allow to assign additional information to objects in your design description (such as data related to synthesis)



Array Attributes

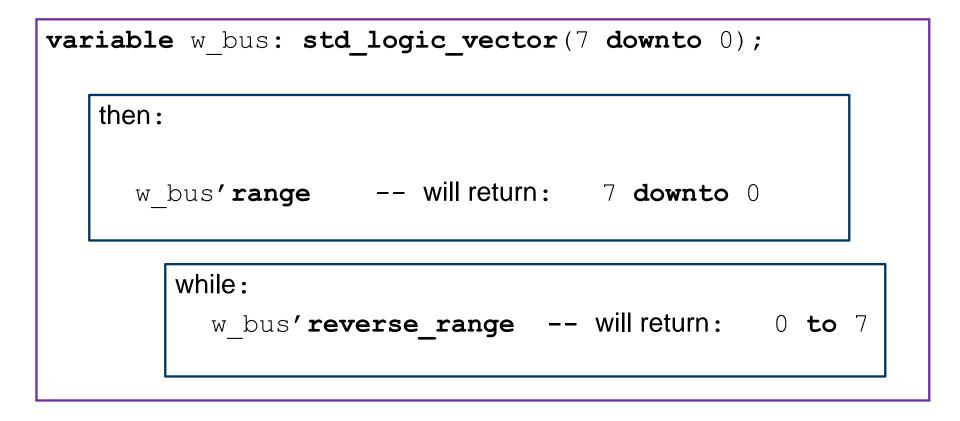
Array attributes are used to obtain information on the size, range and indexing of an array

It's good practice to use attributes to refer to the size or range of an array. So, if the size of the array is change, the VHDL statement using attributes will automatically adjust to the change

Array Attributes – Range Related	
A'range	Returns the range value of a constrained array
A'reverse_range	Returns the reverse value of a constrained array

Array Attributes

Use of the attributes *range* and *reverse_range*



User-defined/Synthesis Attributes

VHDL provides designers/vendors with a way of adding additional information to the system to be synthesized

- Synthesis tools use this features to add timing, placement, pin assignment, hints for resource locations, type of encoding for state machines and several others physical design information
- The bad side of synthesis attributes is that the VHDL code becomes synthesis tools/FPGA dependent, NO TRANSPORTABLE

User-defined/Synthesis Attributes

Syntax

attribute attr_name: type;

attribute attr_name of data_object: ObjectType is AttributeValue;

Example

attribute syn preserve: boolean;

attribute syn_preserve of ff_data: signal is true;

type my fsm state is (reset, load, count, hold);

attribute syn encoding: string;

attribute syn_encoding of my_fsm_state: type is "gray";

User-defined/Synthesis Attributes

Example:

VHDL Statements

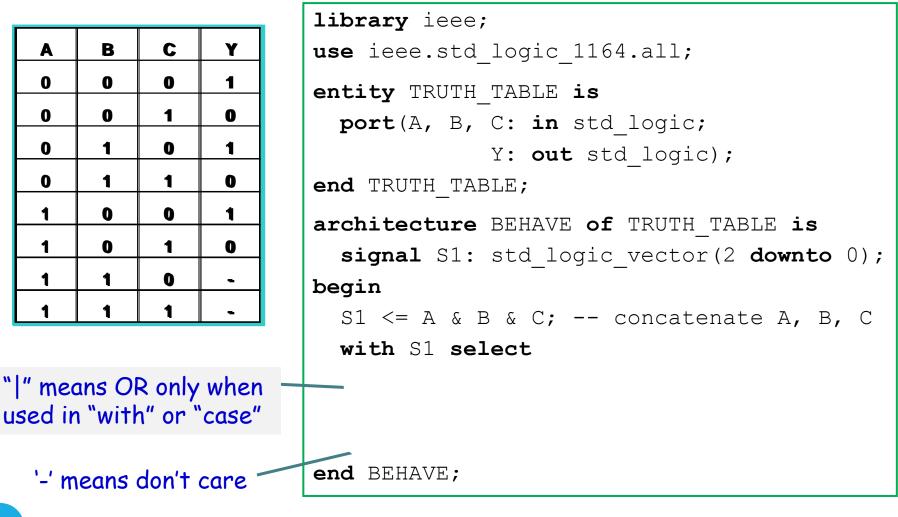
Selective Signal Assignment Statement

Syntax

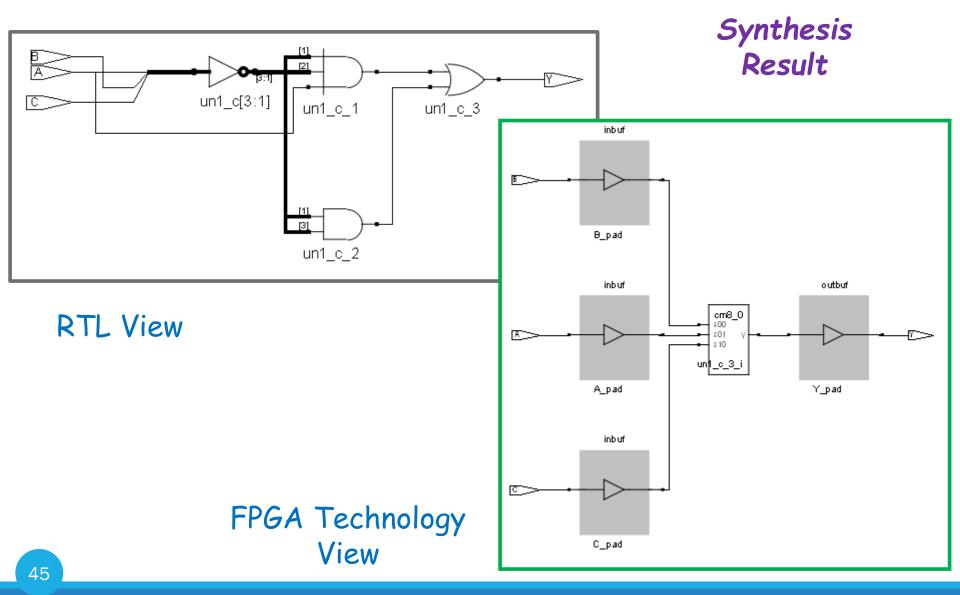
A selective signal assignment describes logic based on mutually exclusive combinations of values of the selection signal

Selective Signal Assignment Statement

Example: Truth Table



Selective Signal Assignment Statement



Conditional Signal Assignment

Syntax

```
target_signal <=
  <expression> when <boolean_condition> else
  <expression> when <boolean_condition> else
  ....
  <expression> when <boolean_condition>[else
      <expression>];
```

A conditional signal assignment describes logic based on unrelated boolean_conditions, the first condition that is true the value of expression is assigned to the target_signal

Conditional Signal Assignment

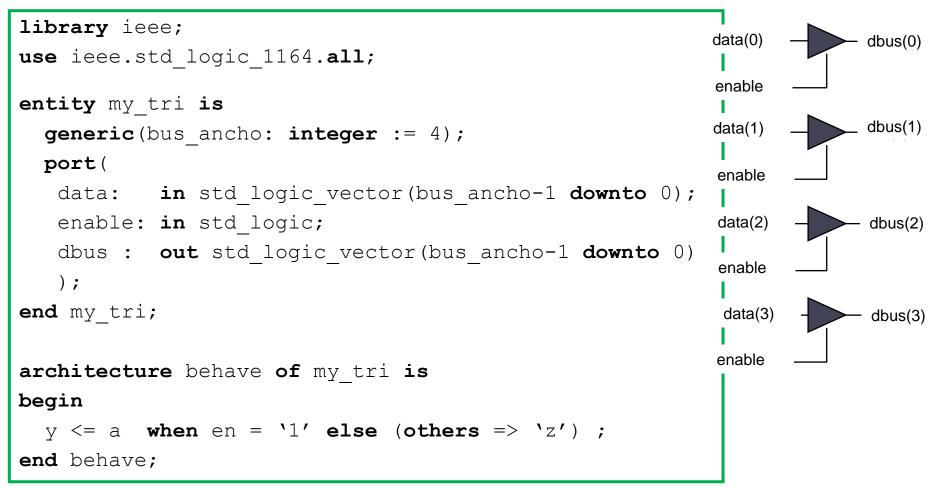
Main usage

dbus <= data when enable = '1' else 'Z';

dbus <= data when enable = '1' else (others=>'Z');

Conditional Signal Assignment

Example



process Statement

A process is a concurrent statement, but it is the primary mode of introducing sequential statements

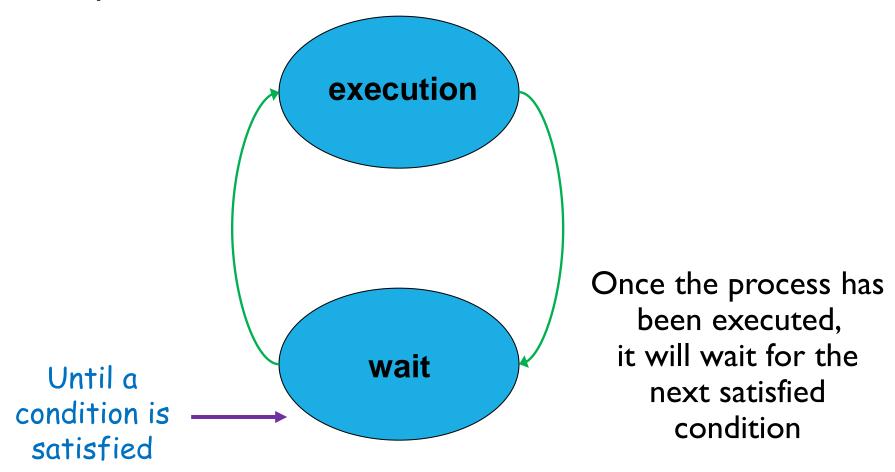
�A process, with all the sequential
statements, is a simple concurrent
statement.

*From the traditional programming view, it
is an infinite loop

Multiple processes can be executed in
parallel

Process Statement

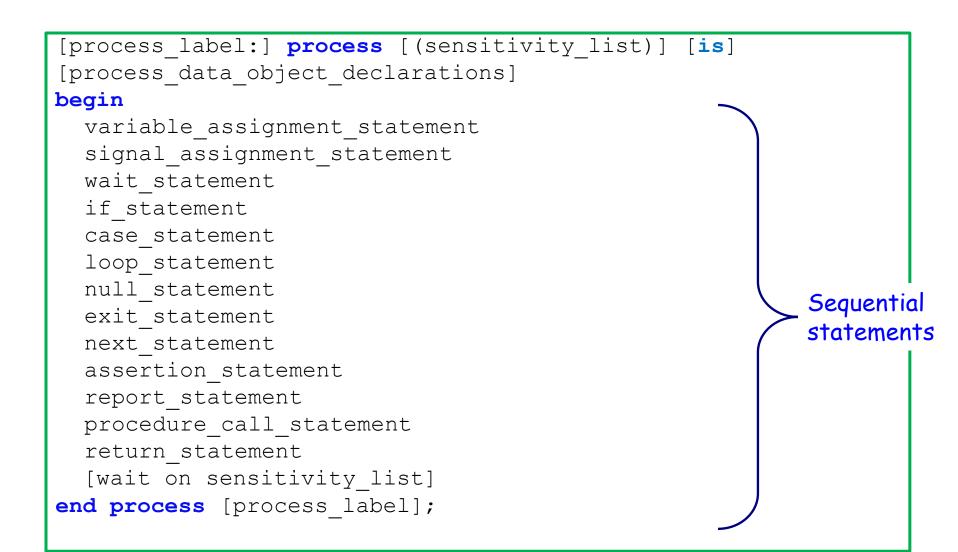
A process has two states: execution and wait



Process Statement

- Processes are composed of sequential statements, but process declarations are concurrent statements.
- The main features of a process are the following:
 - It is executed in parallel with other processes;
 - It defines a region of the architecture where statements are executed sequentially
 - It must contain an explicit sensitivity list or a wait statement
 - It allows functional descriptions, similar to the programming languages;

Process Statement



Parts of the process statement

sensitivity_list

• List of all the signals that are able to trigger the process

- Simulation tools monitor events on these signals
- Any event on any signal in the sensitivity list will cause to execute the process at least once

declarations

- Declarative part. Types, functions, procedures and variables can be declared in this part
- Each declaration is local to the process

sequential_statements

All the sequential statements that will be executed each time that the process is activated

Signal Behaviour in a process

While a process is running ALL the SIGNALS in the system
remain unchanged -> Signals are in effect CONSTANTS during
process execution, EVEN after a signal assignment, the
 signal will NOT take a new value

SIGNALS are updated at the end of a process

Signals are a mean of communication between processes -> VHDL can be seen as a network of processes intercommunicating via signals

Variable Behavior in a process

While a process is running ALL the Variables

in the system are updates **IMMEDIATELY** by a

variable assignment statement

Combinational Process

- In a combinational process all the input signals must be contained in the sensitivity list
- If a signal is omitted from the sensitivity list, the VHDL simulation and the synthesized hardware will behave differently
- All the output signals from the process must be assigned a value each time the process is executed. If this condition is not satisfied, the signal will retain its value (latch !)

Combinational Process

```
a_process: process (a_in, b_in)
begin
c_out <= not(a_in and b_in);
d_out <= not b_in;
end process a process;</pre>
```

```
architecture rtl of com_ex is
begin
ex_c: process (a,b)
begin
z <= a and b;
end process ex_c;
end rtl;</pre>
```

if-elsif-end if Statement

Syntax

```
if <boolean_expression> then
        <sequential_statement(s)>
[elsif <boolean_expression> then
        <sequential_statement(s)>]
        . .
[else
            <sequential_statement(s)>]
end if;
```

if Statement - 3 to 8 Decoder

a(2:0) ??

```
entity if decoder example is
b(7:0)
       port(
       a: in std logic vector(2 downto 0);
       z: out std logic vector(7 downto 0);
     end entity;
     architecture rtl of if decoder example is
     begin
     if dec ex: process (a)
      begin
      end process if dec ex;
     end rtl;
```

if Statement

Most common mistakes for describing combinatorial logic

```
entity example3 is
  port ( a, b, c: in std logic;
             z, y: out std logic);
end example3;
architecture beh of example3 is
begin
process (a, b)
 begin
   if c='1' then
         z <= a;
   else
         y <= b;
   end if;
end process;
end beh;
```

case Statement

```
[case label:]case <selector expression> is
  when <choice 1> =>
      <sequential statements> -- branch #1
  when <choice 2> =>
     <sequential statements> -- branch #2
   [when <choice n to/downto choice m > =>
     <sequential statements>] -- branch #n
     . . . .
   [when <choice x | choice y | . . .> =>
      <sequential statements>] -- branch #...
   [when others =>
      <sequential statements>]-- last branch
end case [case label];
```

case Statement

```
entity mux4 is
 port ( sel : in std ulogic vector(1 downto 0);
        d0, d1, d2, d3 : in std ulogic;
                       : out std ulogic );
         Z
end entity mux4;
architecture demo of mux4 is
begin
out select : process (sel, d0, d1, d2, d3) is
begin
  case sel is
        when "00" =>
                 z <= d0;
        when "01" =>
                 z <= d1;
        when "10" =>
                 z <= d2;
        when others =>
                 z <= d3;
    end case;
 end process out select;
end architecture demo;
```

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case Statement with if Statement

```
mux mem bus :process
   (cont_out, I_P0, I_P1, I_A0, I_A1, Q_P0, Q_P1, Q_A0, Q_A1)
begin
 mux out <= I P0;</pre>
 case (cont out) is
  when "00" =>
      if(iq bus = '0') then
         mux out <= I P0;--I A0;</pre>
      else
        mux out <= Q P0;--Q A0;</pre>
      end if;
  when "01" =>
      if(iq bus = '0') then
        mux out <= I A0;--I P0;</pre>
      else
        mux out <= Q A0;--Q P0;</pre>
           end if;
```

.

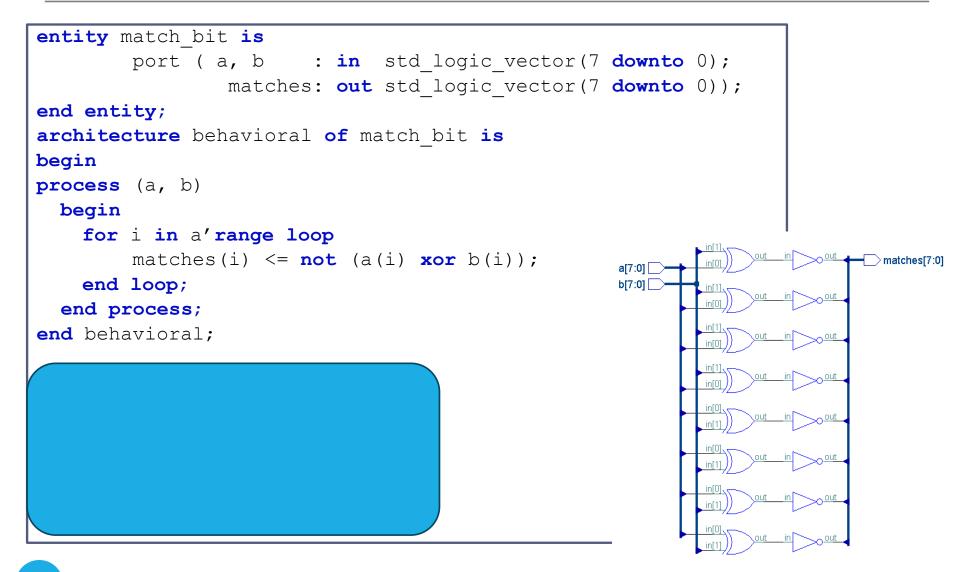
for loop-end loop Statement

[loop_label]: for <identifier> in discrete_range loop
 <sequential_statements>
 end loop [loop_label];

<identifier>

- The identifier is called loop parameter, and for each iteration of the loop, it takes on successive values of the discrete range, starting from the left element
- It is not necessary to declare the identifier
- By default the type is integer
- Only exists when the loop is executing

for-loop Statement



for-loop Statement

```
library ieee;
use ieee.std logic 1164.all;
use ieee.numeric std.all;
entity count ??? is
       port(vec: in std logic vector(15 downto 0);
           count: out std logic vector (3 downto 0))
end count ones;
architecture behavior of count ???? is
begin
 cnt ones proc: process(vec)
   variable result: unsigned(3 downto 0);
 begin
     result:= (others =>'0');
     for i in vec'range loop
       if vec(i)='1' then
          result := result + 1;
       end if:
     end loop;
   count <= std logic vector(result);</pre>
 end process cnt ones proc;
end behavior;
```

The Role of Componentes in VHDL

Hierarchy in VHDL

4 Divide & Conquer

Each subcomponent can be designed and completely tested

4 Create library of components (technology independent if possible)

4Third-party available components



Component Instantiation

Component instantiation is a concurrent statement that is used to connect a component I/Os to the internal signals or to the I/Os of the higher lever component

component_label: entity work.component_name

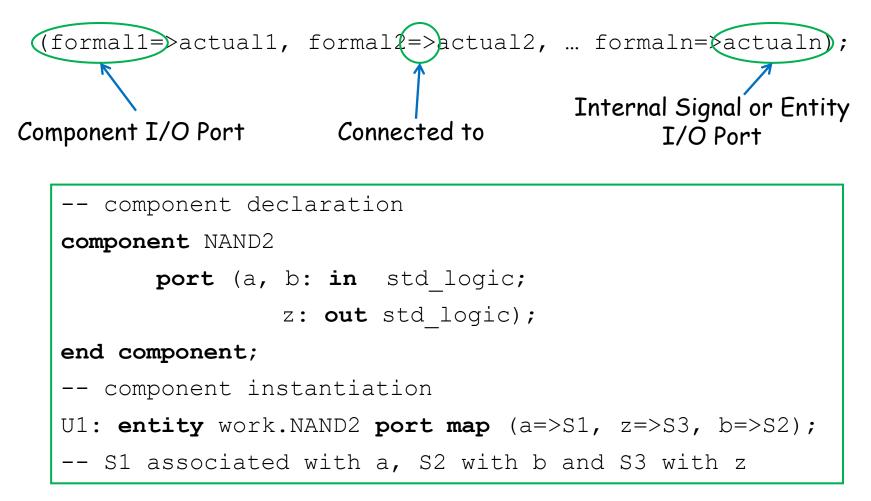
[generic map (generic assocation list)]

port map (port_association_list);

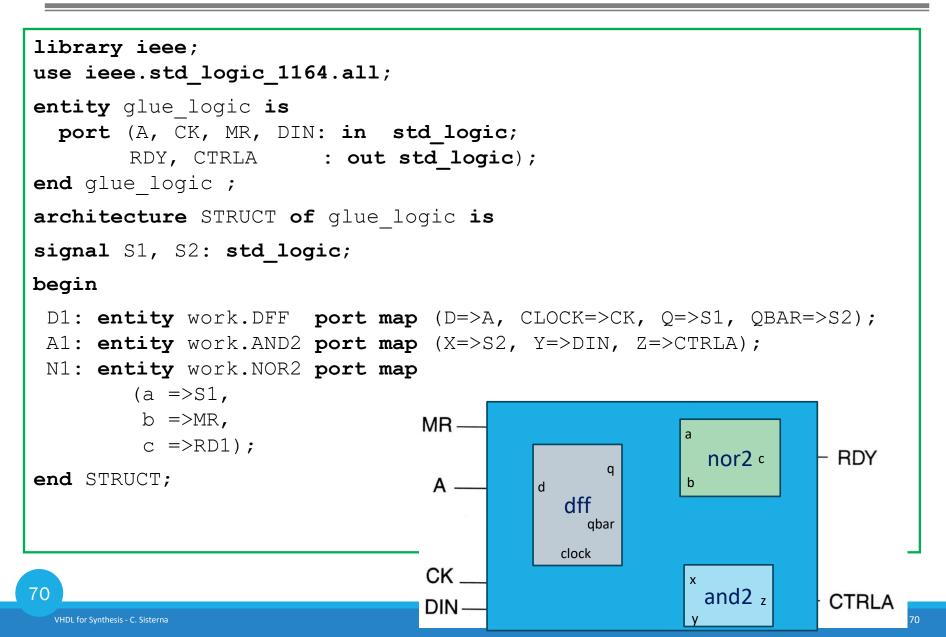
- component_label it labels the instance by giving a name to the instanced
- generic_assocation_list assign new values to the default generic values (given in the entity declaration)
- port_association_list associate the signals in the top entity/architecture with the ports of the component. There are two ways of specifying the port map:
 - Positional Association / Name Association

Association By Name

In named association, an association list is of the form

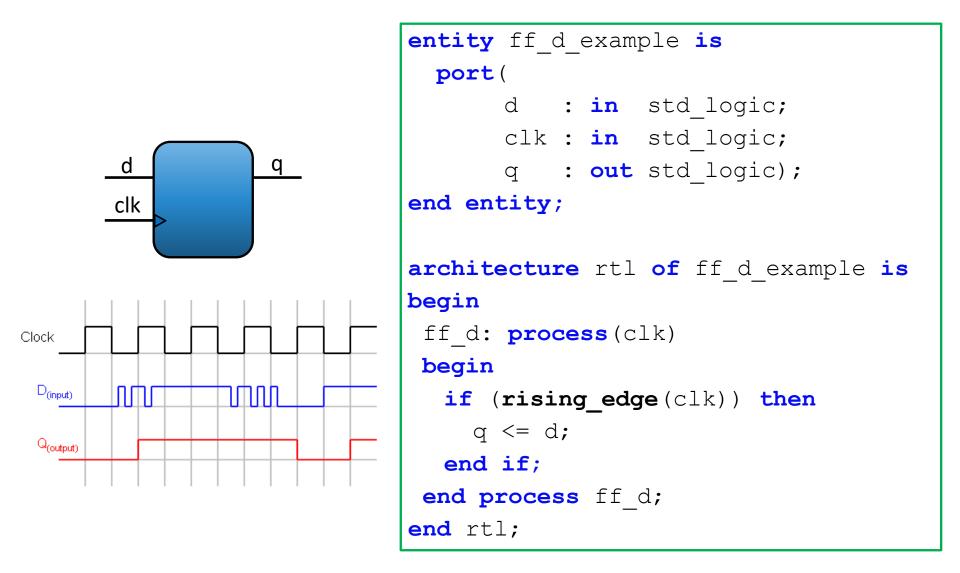


Component Instantiation Example

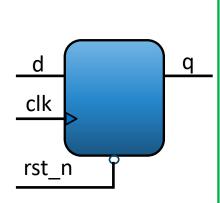


VHLD for Sequential Logic Design

D Flip-Flop - VHDL

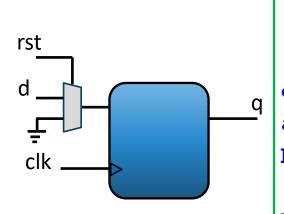


D-ff with asynchronous reset



entity ff example is port(d, clk, rst n: in std logic; q: out std logic); end entity; architecture rtl of ff example is begin ff d rst: process (clk, rst n) end process ff d rst; end rtl;

D-ff with synchronous reset

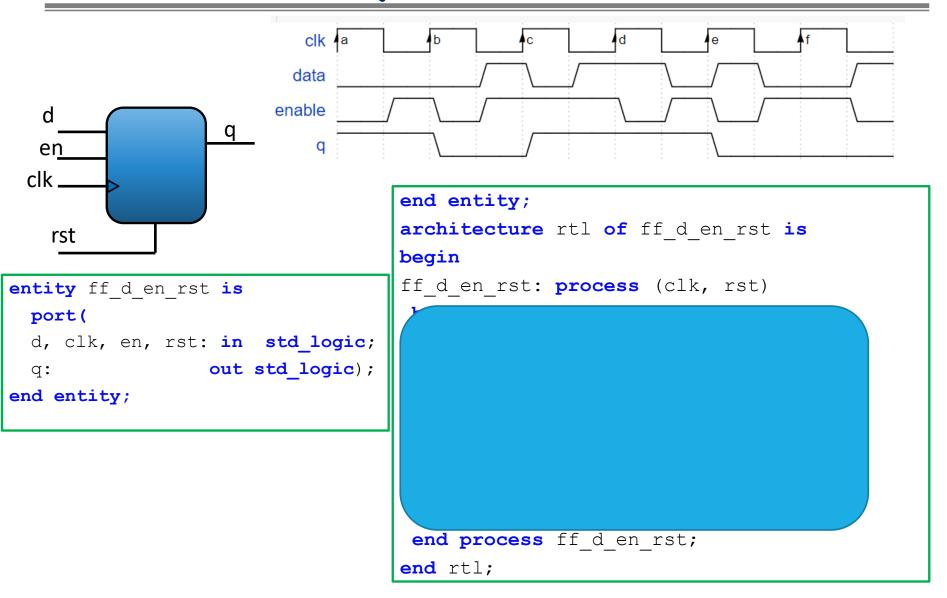


entity ff d srst is port(d, clk, rst: in std logic; q: out std logic); end entity; architecture rtl of ff d srst is begin ff d srst: process (clk) begin

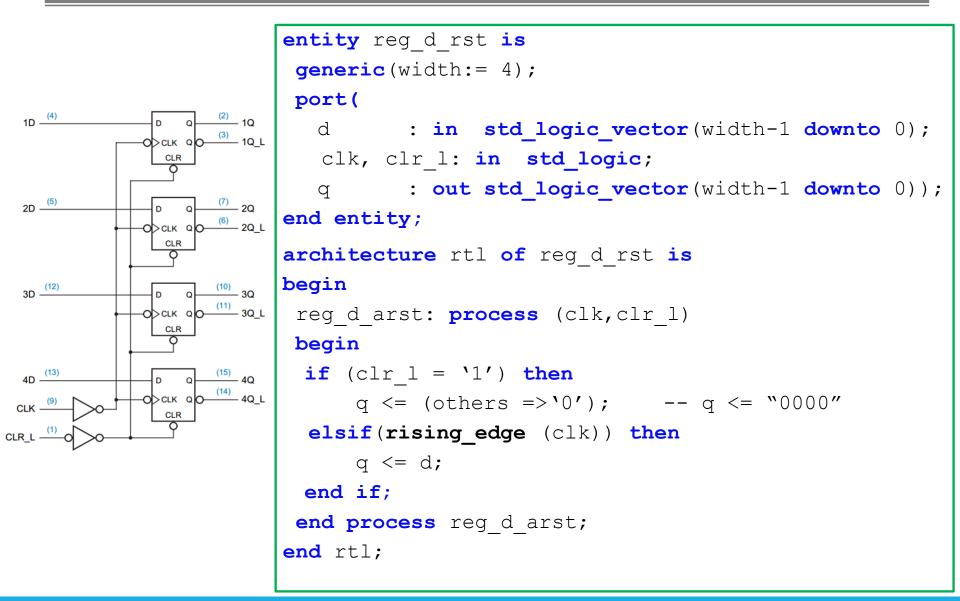
end process ff_d_srst;

end rtl;

D-ff with async. reset and enable



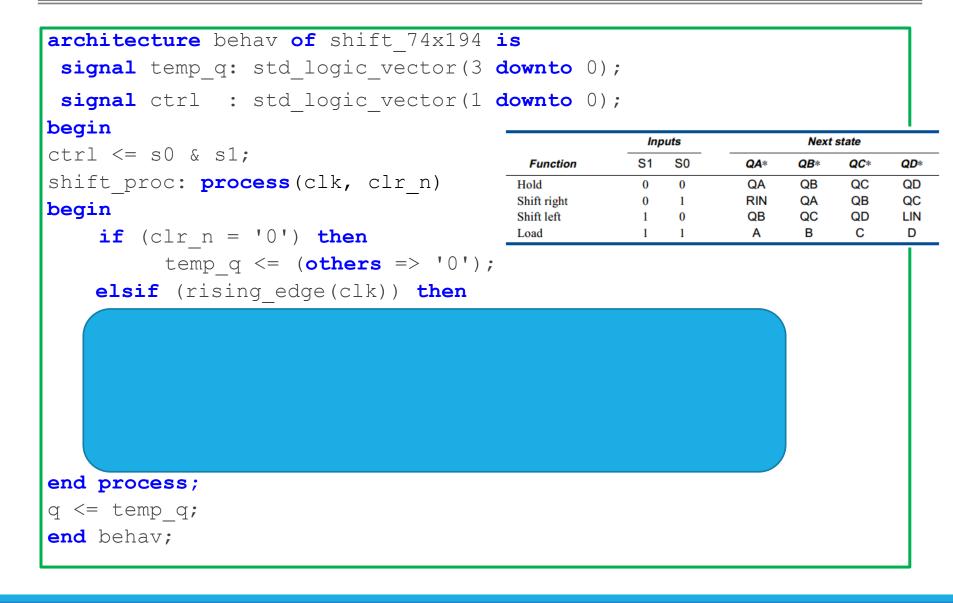
Registers



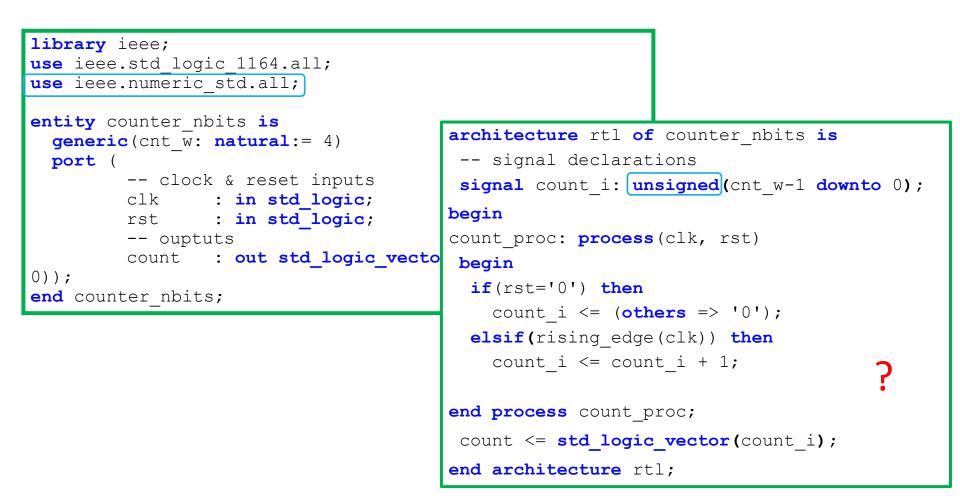
What is the implementation result??

```
library ieee;
use ieee.std logic 1164.all;
entity shift pi po x8 is
  port(
        clk, clr : in std logic;
        serial in : in std logic;
        data out : out std logic vector(7 downto 0);
end shift pi po x8;
architecture behav of shift si so x4 is
 signal data out temp: std logic vector(3 downto 0);
begin
shift proc: process(clk, clr)
begin
    if (clr = '0') then
       data out temp <= others(=>'0');
    elsif (rising edge(clk)) then
       data out temp <= serial in & data out temp(3 downto 1);</pre>
    end if;
end process shift proc;
data out <= data out temp;</pre>
end behave;
```

Shift Register : 74x194



Counter



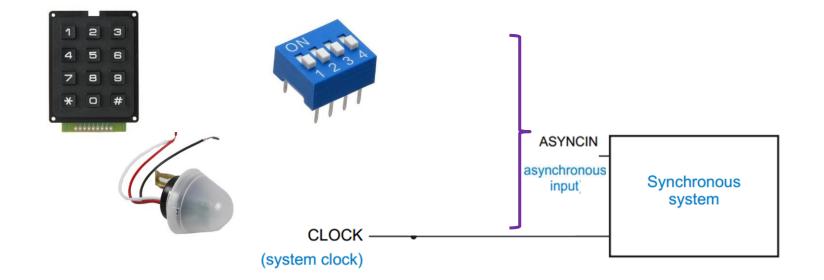
Up/Down Counter

```
architecture rtl of counter ud is
                                          -- signal declarations
library ieee;
                                          signal count i: unsigned(cnt w-1 downto 0);
use ieee.std logic 1164.all;
use ieee.numeric std.all;
                                          begin
                                           count proc: process(clk, rst)
entity counter ud is
                                           begin
  generic(cnt w: natural:= 4)
                                            if(rst='0') then
  port (
                                               count i <= (others => '0');
         -- clock & reset inputs
                                            elsif(rising edge(clk)) then
         clk : in std logic;
                                               if(up dw = '1') then -- up
         rst : in std logic;
                                                  count i <= count i + 1;</pre>
         -- control input signals
                                              else
                                                                    -- down
         up dw : in std logic;
                                                  count i <= count i - 1;</pre>
         -- ouptuts
                                              end if:
         count : out std logic vector (
                                             end if;
0));
                                           end process count proc;
end counter ud;
                                           count <= std logic vector(count i);</pre>
                                          end architecture rtl;
```

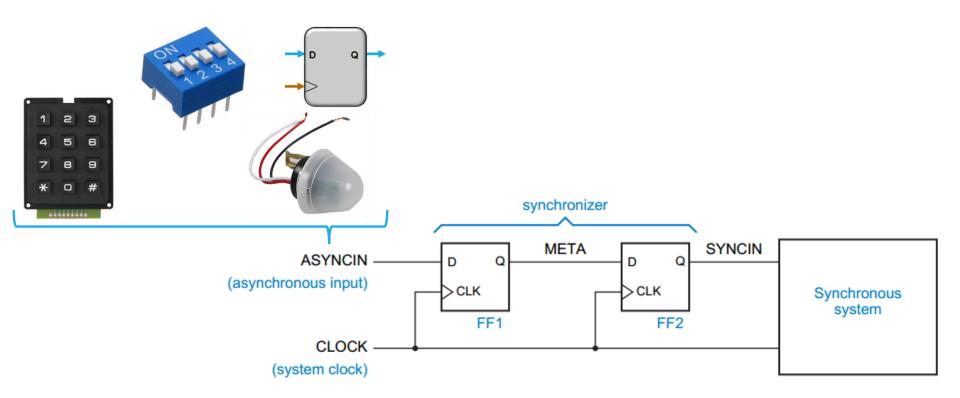
Up/Down Counter - Integers

```
architecture rtl of counter ud i is
begin
 count proc: process(clk, rst)
    variable count i: integer range 0 to 255;
begin
  if(rst n = '0') then
     count i := 0;
  elsif(rising edge(clk)) then
    if (count i = 255) then
       count i := 0;
    else
       count i := count i + 1;
    end if:
   end if;
 end process count proc;
 count <= std logic vector(to unsigned(count i, 8));</pre>
end architecture rtl;
```

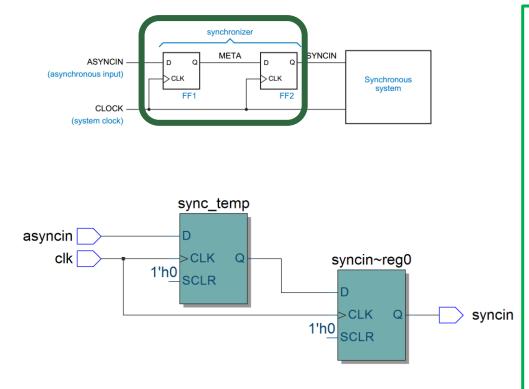
Asynchronous Inputs



Synchronizer



Synchronizer

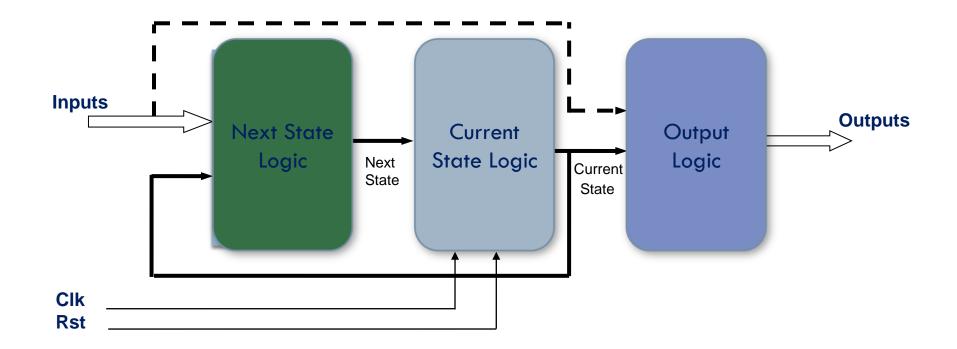


```
library ieee;
use ieee.std logic 1164.all;
entity synchronizer is
  port(
           : in std logic;
       clk
       asyncin : in std logic;
       syncin : out std logic);
end synchronizer;
architecture behave of synchronizer is
 signal sync temp: std logic;
begin
sync proc: process(clk)
begin
    if (rising edge(clk)) then
        sync temp <= asyncin;</pre>
        syncin <= sync temp;</pre>
    end if;
 end process;
end behave;
```

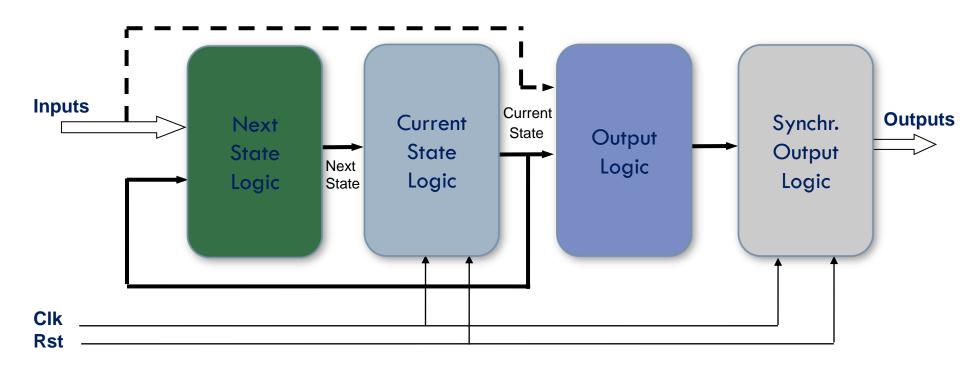
FINITE STATE MACHINES (FSM) DESCRIPTION IN VHDL



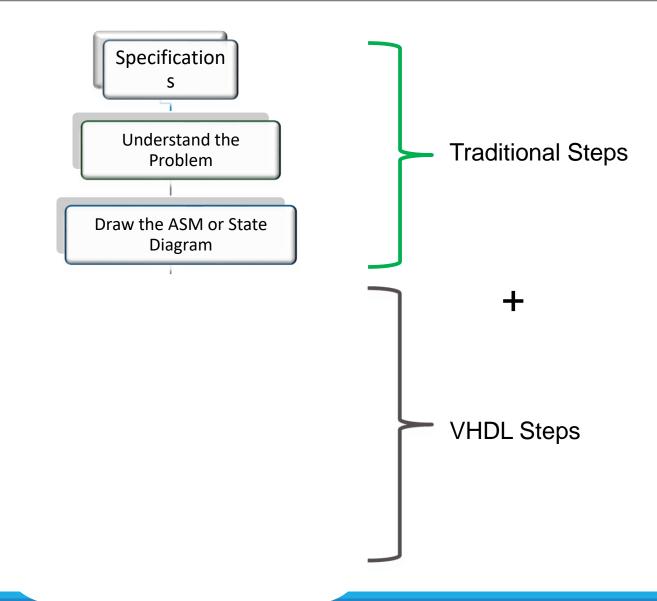
State Machine General Scheme 1



State Machine General Scheme 2



FSM VHDL General Design Flow

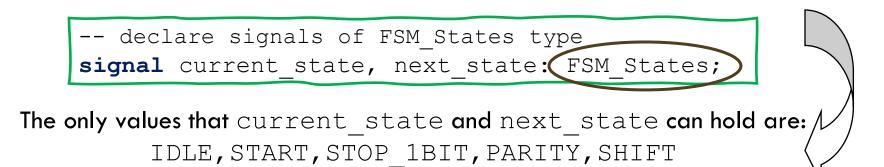


FSM Enumerated Type Declaration

Declare an enumerated data type with values (names) that symbolize the states of the state machine Symbolic State



Declare the signals for the next state and current state of the state machine as signal of the enumerated data type already defined for the state machine



FSM Encoding Techniques

State Assignment

During synthesis each symbolic state name has to be mapped to a unique binary representation

type FSM_States is(IDLE, START, STOP_1BIT, PARITY, SHIFT);
signal current_state, next_state: FSM_States;

A good state assignment can *reduce* the circuit *size* and *increase* the *clock rate* (by reducing propagation delays)

The hardware needed for the implementation of the next state logic and the output logic is *directly related* to the state assignment selected

FSM Encoding Schemes

An FSM with n symbolic states requires at least $[\log_2 n]$ bits to encode all the possible symbolic values

Commonly used state assignment schemes:

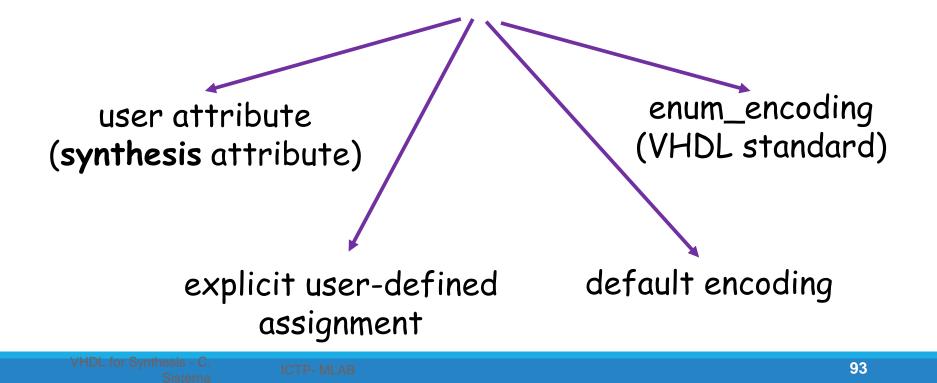
- Binary: assign states according to a binary sequence
- **Gray:** use the Gray code sequence for assigning states
- One-hot: assigns one 'hot' bit for each state
- Almost one-hot: similar to one-hot but add the all zeros code (initial state)

FSM Encoding Schemes

	Binary	Gray	One-Hot	Almost One-hot						
idle	000	000	00001	0000						
start	001	001	00010	0001						
stop_1 bit	010	011	00100	0010						
parity	011	010	01000	0100						
shift	100	110	10000	1000						

Encoding Schemes in VHDL

During synthesis each symbolic state name has to be mapped to a unique binary representation



syn_encoding-Quartus & Synplify

- syn_encoding is the synthesis <u>user-attribute</u> of Quartus (Synplify) that specifies encoding for the states modeled by an enumeration type
- To use the syn_encoding attribute, it must first be declared as string type. Then, assign a value to it, referencing the current state signal.

```
-- declare the (state-machine) enumerated type
type my_fms_states is (IDLE,START,STOP_1BIT,PARITY,SHIFT);
-- declare signals as my_fsm_states type
signal nxt_state, current_state: my_fsm_states;
-- set the style encoding
attribute syn_encoding: string;
attribute syn_encoding of my_fms_states : type is "one-hot";
```

Results for Different Encoding Schemes

Simple, 5 states, state machine

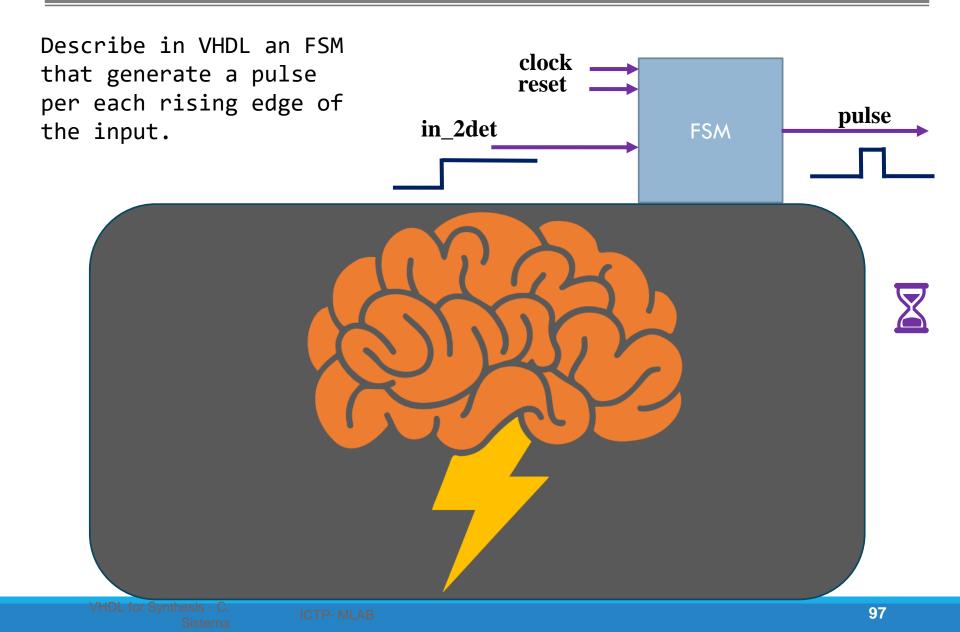
	One-hot safe	One-hot	Gray	Gray-Safe	Binary	Johnson
Total combination al functions	76	66	66	68	66	68
Dedicated logic registers	45	45	43	43	43	43
Max. frq.	352.24	340.95	331.02	335.01	338.34	311.72

Results for Different Encoding Schemes

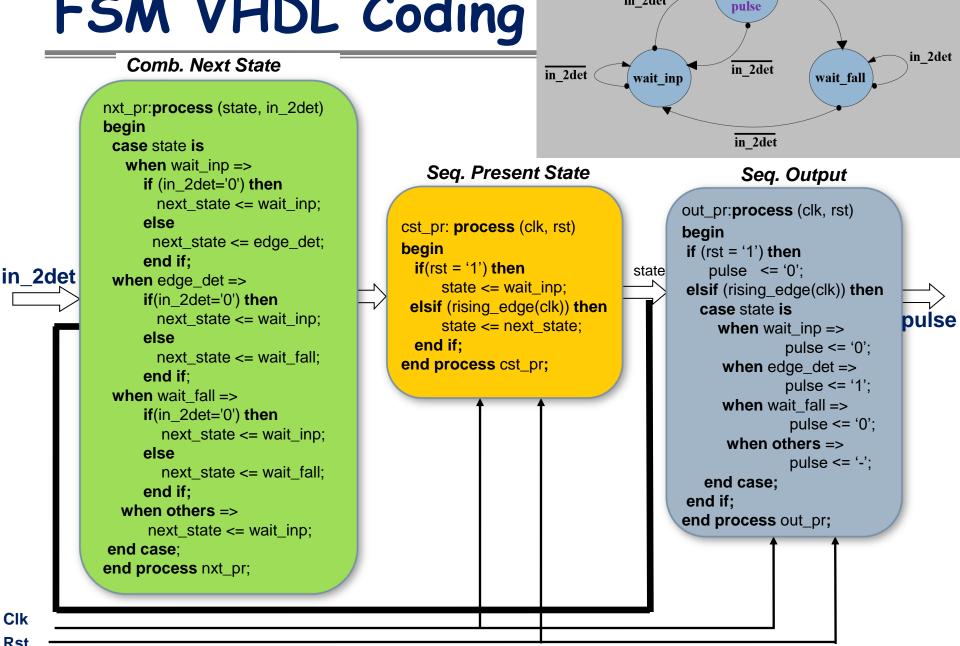
19 states, state machine

	One-hot safe	One-hot	Gray	Gray-Safe	Binary	Johnson
Total combinational functions	556	523	569	566	561	573
Dedicated logic registers	215	215	201	201	201	206
Max. frq.	187.3	175.22	186.39	180.6	197.63	186.22

State Machine VHDL Coding - Example



FSM VHDL Coding

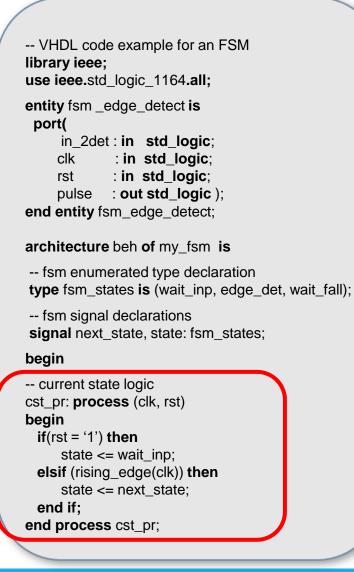


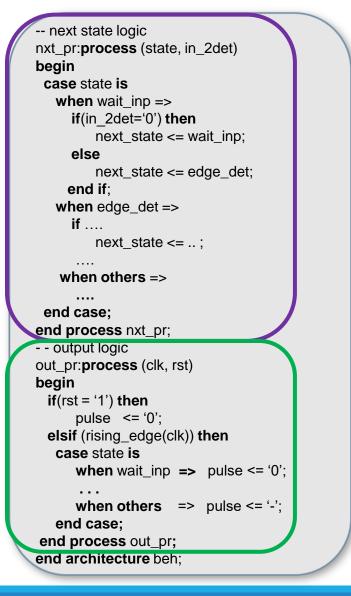
Clk Rst edge det

in 2det

in 2det

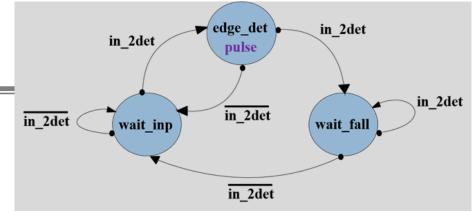
State Machine VHDL Coding (complete)





ICTP- MLAE

FSM Simulation



Wave

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state	wait_inp	wait in	0					edge de	et	wait inp				edge de	t	wait f	fall					
nxt_state	edge_det						X	wait_fal		(wait_inp	X		let	wait_fall								
																						Z
	0000 ps	ps				20000)0 ps			4000	00 ps	0.2		6000	00 ps				8	00000) ps	
Cursor 1	5983 ps										4359	83 ps										
0 ps to 840 ns			Output P	ulse																		

Another Ex.: Memory Controller FSM

Let's try to obtain an state diagram of a hypothetical memory controller FSM that has the following specifications:

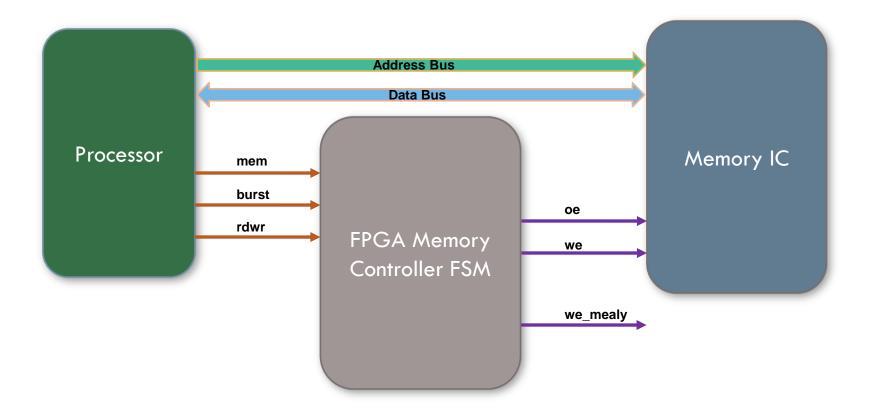
The controller is between a processor and a memory chip, interpreting commands from the processor and then generating a control sequence accordingly. The commands, *mem*, *rw* and **burst**, from the processor constitute the input signals of the FSM. The **mem** signal is asserted to high when a memory access is required. The *rdwr* signal indicates the type of memory access, and its value can be either '1' or '0', for memory read and memory write respectively. The burst signal is for a special mode of a memory read operation. If it is asserted, four consecutive read operations will be performed. The memory chip has two control signals, oe (for output enable) and we (for write enable), which need to be asserted during the memory read and memory write respectively. The two output signals of the FSM, oe and we, are connected to the memory chip's control signals. For comparison purpose, let also add an artificial Mealy output signal, we_mealy, to the state diagram. Initially, the FSM is in the idle state, waiting for the mem command from the processor. Once *mem* is asserted, the FSM examines the value of *rdwr* and moves to either the *read1* or the *write* state. The input conditions can be formalized to logic expressions, as shown below:

• *mem'* : represents that *n*o memory operation is required (mem='0')

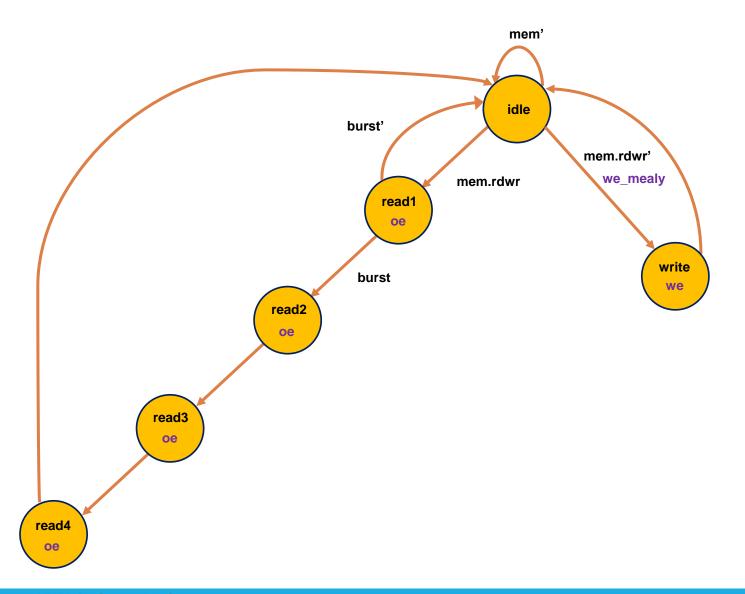
- *mem.rdwr*: represents that a memory *read* operation is required (mem=rdwr='1').
- *mem.rdwr*': represents that a memory *write* operation is required (mem='1'; rdwr='0')

Based on an example from the "RTL Hardware Design Using VHDL" book, By Pong Chu

Memory Controller FSM



Memory Controller FSM

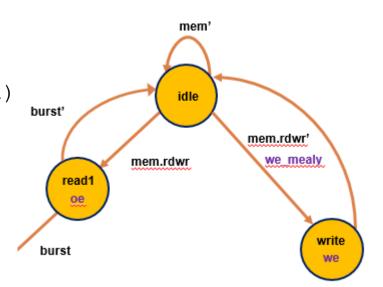


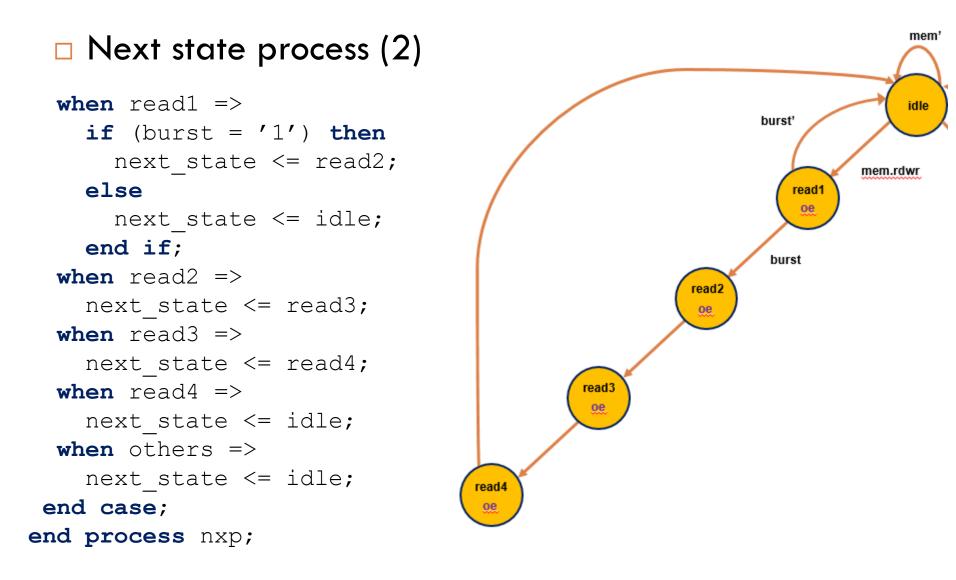
```
library ieee ;
use ieee.std logic 1164.all;
entity mem ctrl is
port (
      clk, reset : in std logic;
      mem, rdwr, burst: in std logic;
      oe, we, we mealy: out std logic
      );
end mem ctrl ;
architecture mult seg arch of mem ctrl is
type fsm states type is
       (idle, read1, read2, read3, read4, write);
 signal crrnt state, next state: fsm states type;
begin
```

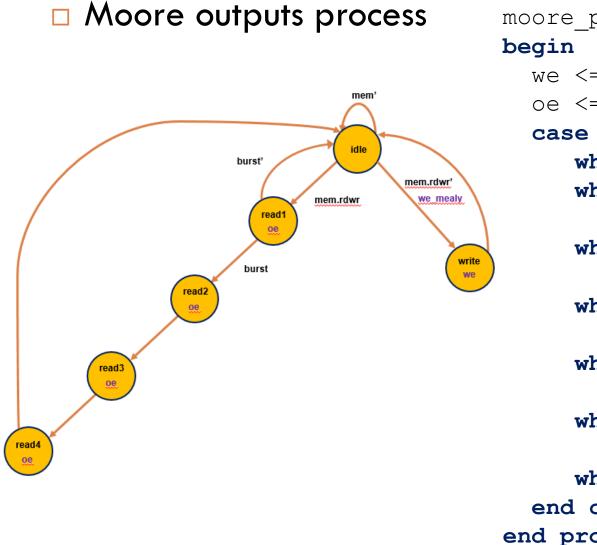
```
-- current state process
cs_pr: process (clk, reset)
begin
if(reset = '1') then
    crrnt_state <= idle ;
elsif(rising_edge(clk))then
    crrnt_state <= next_state;
end if;
end process cs_pr;</pre>
```

Next state process (1)

```
-- next-state logic
nxp:process(crrnt state,mem,rdwr,burst)
begin
 case crrnt state is
   when idle =>
     if mem = '1 ' then
        if rdwr = '1' then
          next state <= read1;</pre>
        else
         next state <= write;</pre>
        end if;
     else
        next state <= idle;</pre>
     end if;
   when write =>
     next state <= idle;</pre>
```







-- Moore output logic moore_pr: process (crrnt_state) begin

we $\leq 10'$; -- default value $oe \leq '0'; -- default value$ case crrnt state is when idle => null; when write => we <= '1'; **when** read1 => oe <= '1'; when read2 => oe <= '1'; **when** read3 => oe <= '1'; **when** read4 => oe <= '1'; when others => null; end case ; end process moore pr;



