

Workshop on Fully Programmable Systems-on-Chip for Scientific Applications



Independent University, Bangladesh



FPGA for Accelerating Machine Learning (ML) Algorithms

Romina Soledad Molina

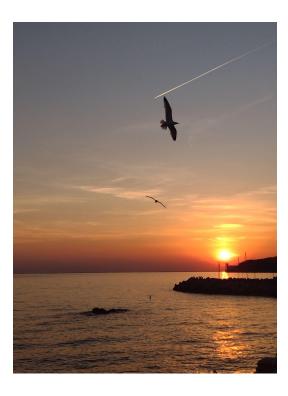
MLab/STI Unit - ICTP

Doha, Qatar 2024



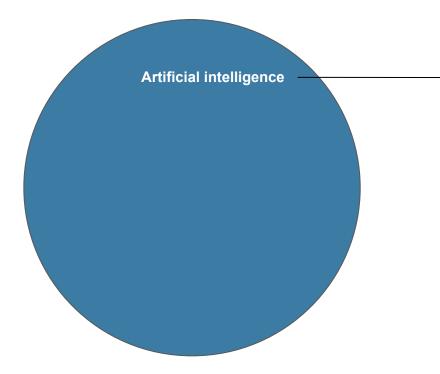
Outline

- Introduction.
- Remarks from SOTA.
- ML and model compression techniques.
- An end-to-end workflow to compress and deploy DNN on FPGA.
 - DNN training and compression.
 - Integration with a hardware synthesis tool for ML.
 - Hardware assessment framework.
- Applications.
- Final remarks.



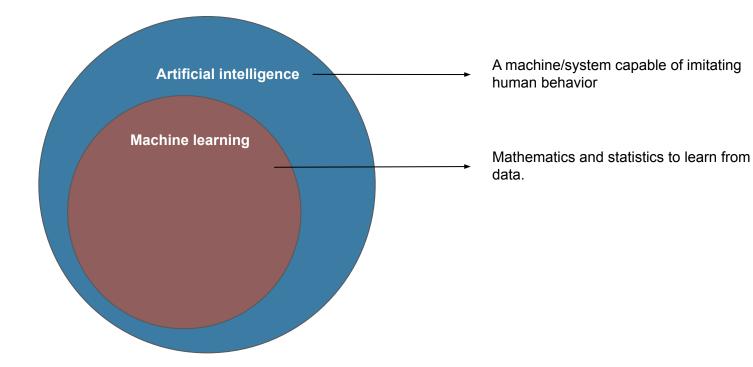




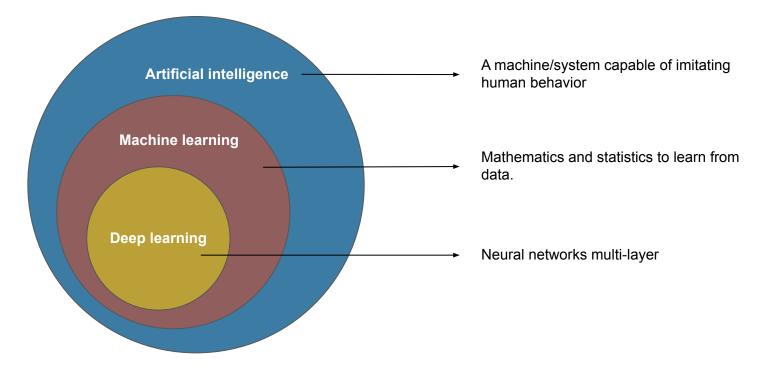


A machine/system capable of imitating human behavior









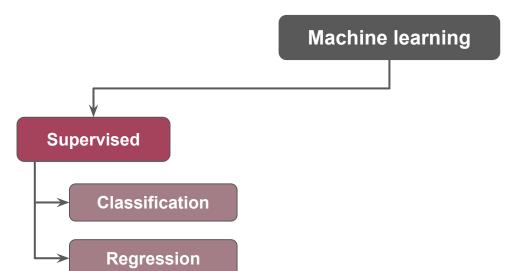


Classification

Machine learning

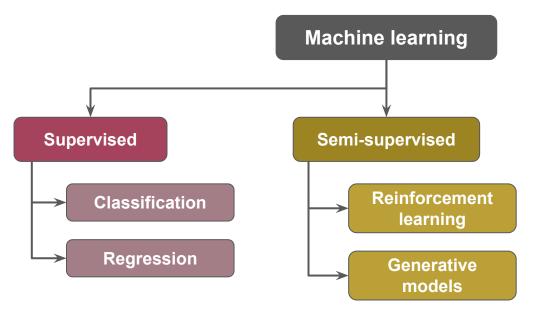


Classification



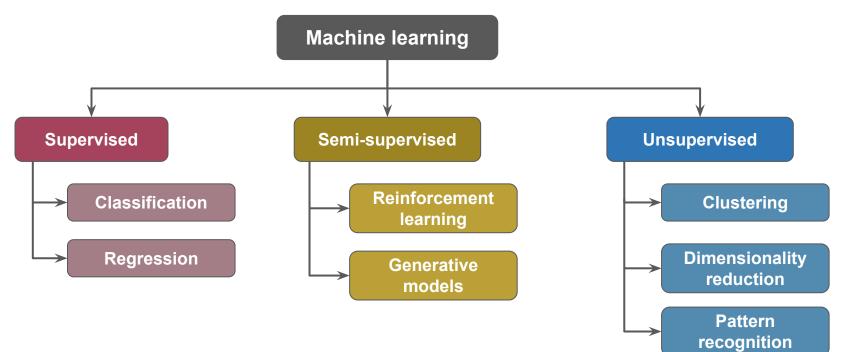


Classification

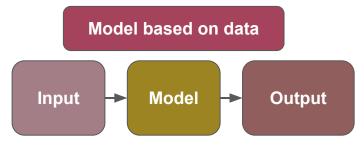




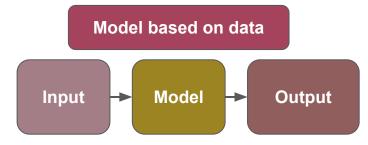
Classification

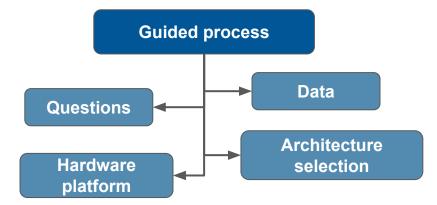




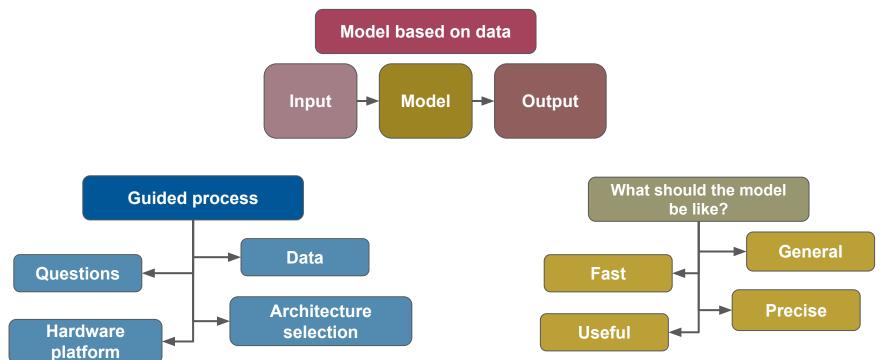












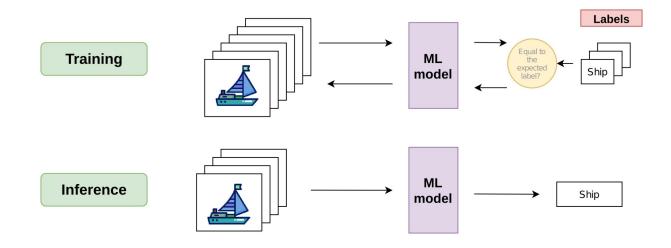


Generalization

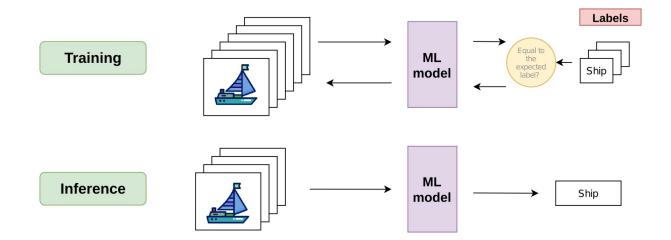


Image from Togootogtokh, E., & Amartuvshin, A. (2018). Deep Learning Approach for Very Similar Objects Recognition Application on Chihuahua and Muffin Problem. ArXiv, abs/1801.09573.









- In a classifier, an input is mapped to a specific class.
- Supervised training phase: the network compares its current output with the desired output. The difference between these two values is corrected using backpropagation.



A classifier as example





A classifier as example

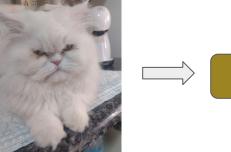






A classifier as example









A classifier as example

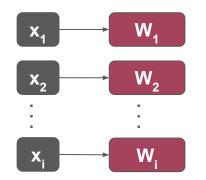




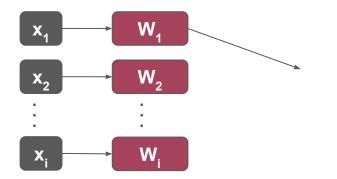




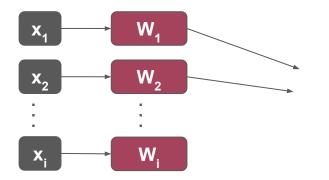




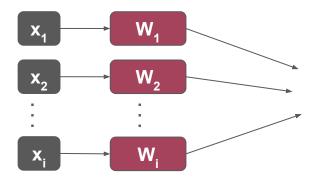




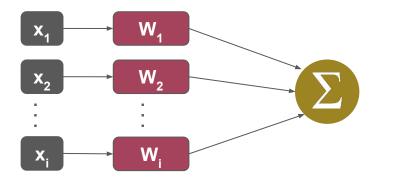




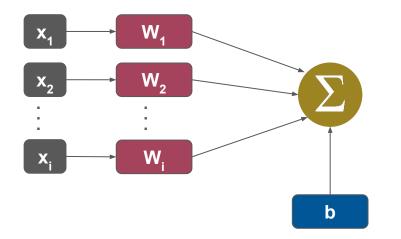




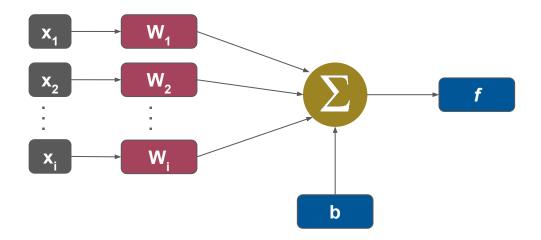




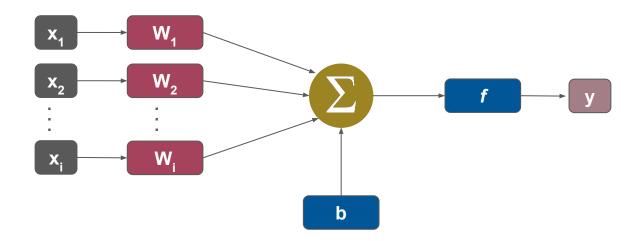






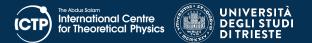




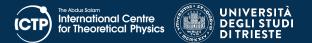




Introduction: ML and SoC

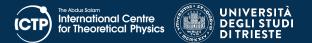






Low latency

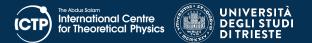




Low latency

Low power consumption

SoC-based FPGA

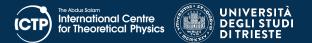


Low latency

Low power consumption

High parallelism





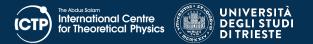
Low latency

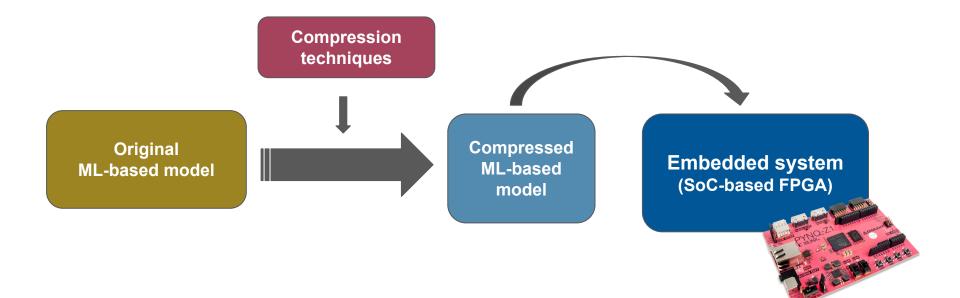
Low power consumption

High parallelism

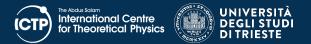
Resource-constrained devices

SoC-based FPGA

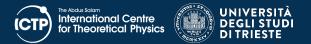




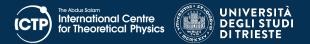




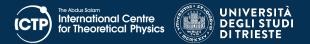
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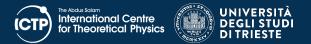
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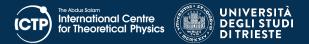
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Memory footprint and latency

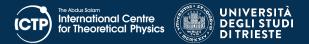
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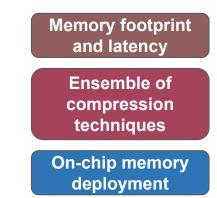
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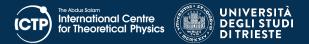
Memory footprint and latency Ensemble of compression

techniques



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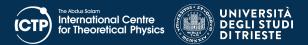


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tion. opment cycle.	Ensemble of compression techniques
	On-chip memory deployment
Productivity	End-to-end workflow



ML and model compression techniques



ML and model compression techniques for reconfigurable hardware accelerators

Ensemble of compression techniques - Exploration of the interplay between:

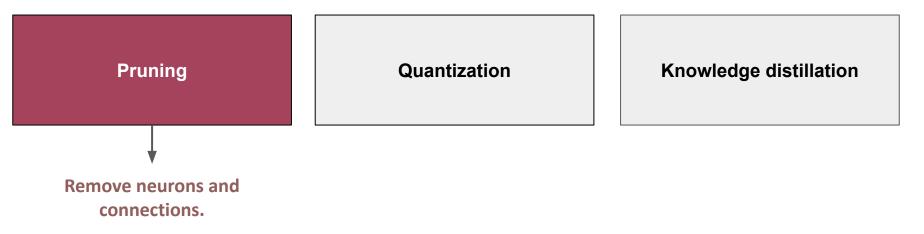


ML and model compression techniques for reconfigurable hardware accelerators

Pruning	Quantization	Knowledge distillation

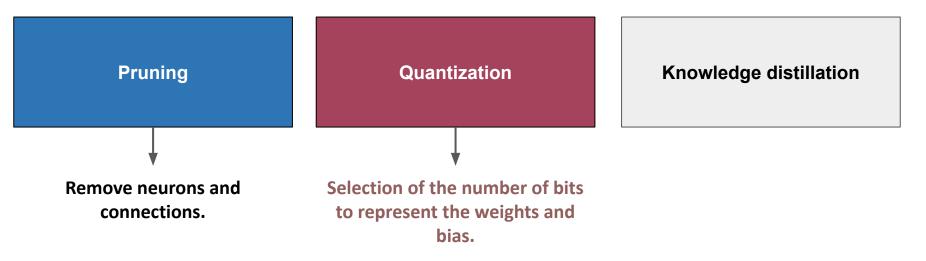


ML and model compression techniques for reconfigurable hardware accelerators



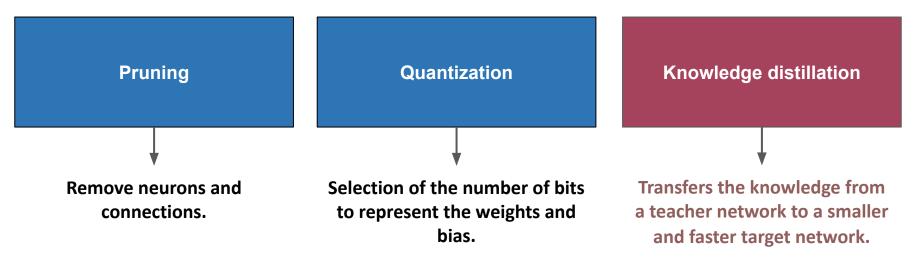


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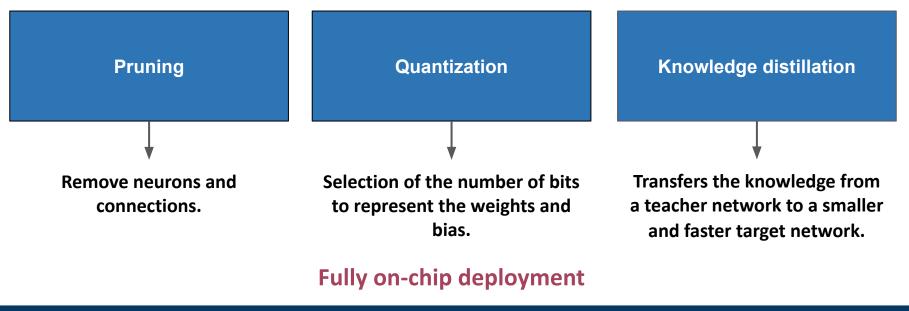
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Ensemble of compression techniques - Exploration of the interplay between:





An end-to-end workflow to efficiently compress and deploy DNN on SoC/FPGA



End-to-end workflow

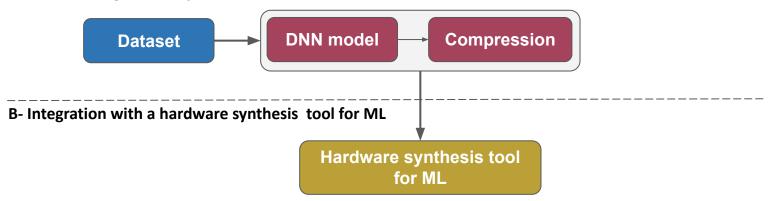
A- DNN training and compression





End-to-end workflow

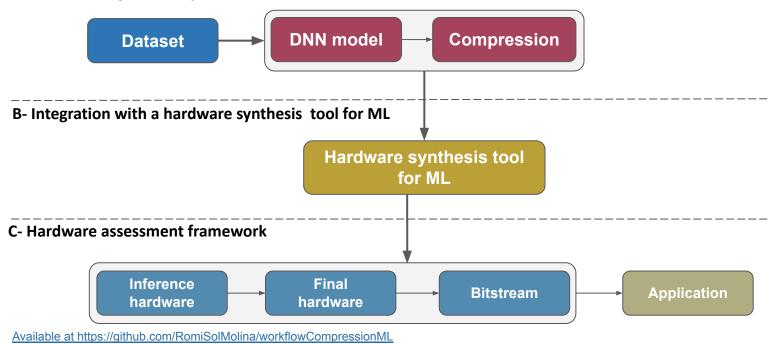
A- DNN training and compression





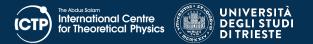
End-to-end workflow

A- DNN training and compression

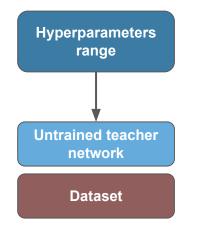


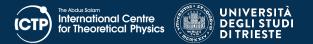


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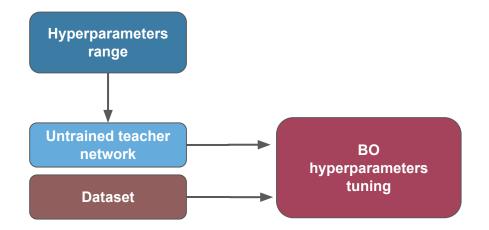


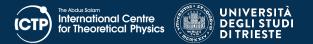
DNN training and compression Stage 1 - Teacher training



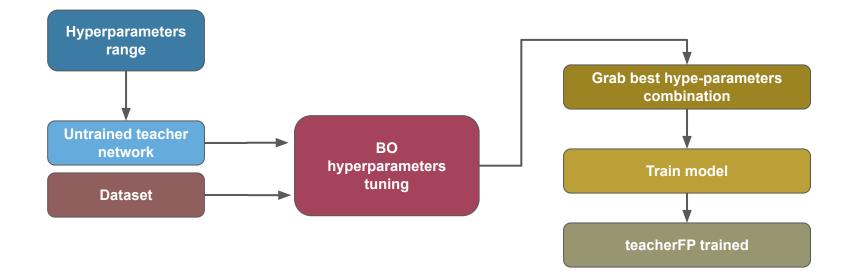


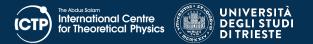
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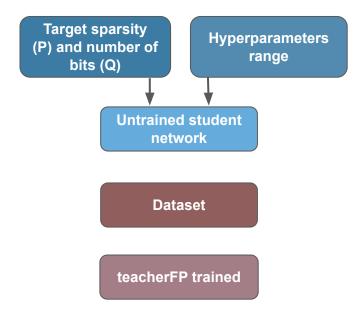


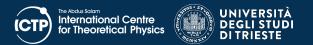
DNN training and compression Stage 1 - Teacher training



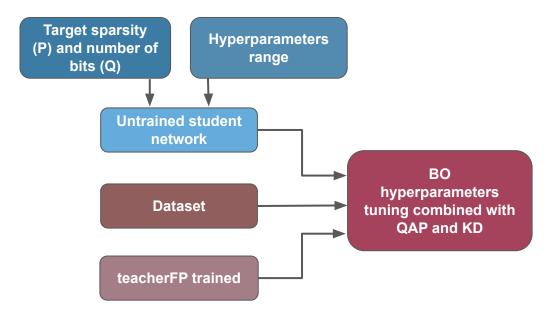


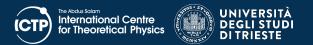
DNN training and compression Stage 2 - Student training



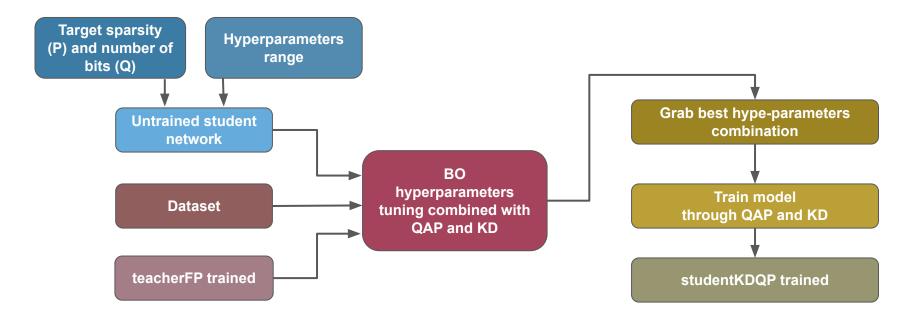


DNN training and compression Stage 2 - Student training

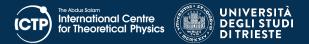




DNN training and compression Stage 2 - Student training





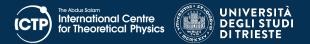


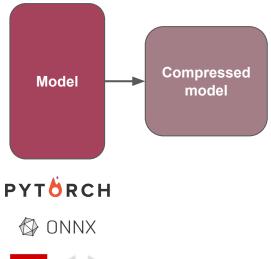




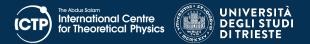
🚱 ONNX

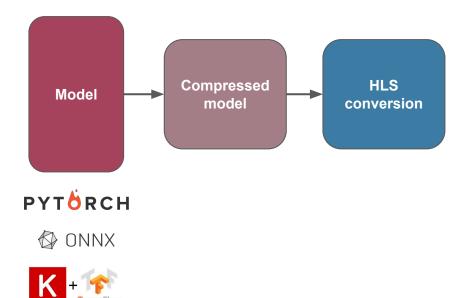


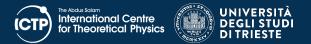


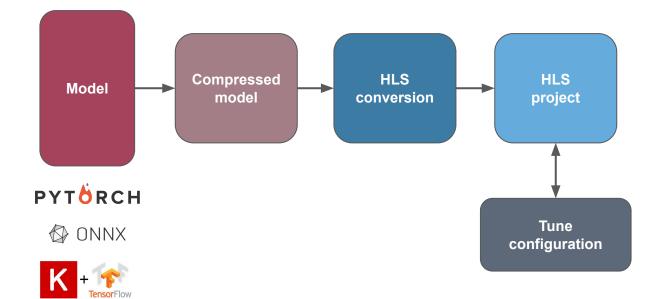


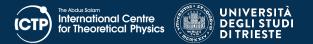


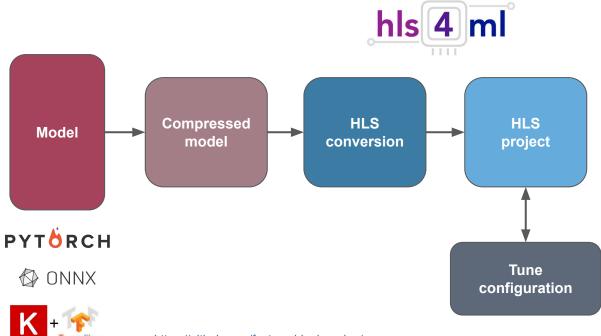




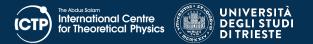


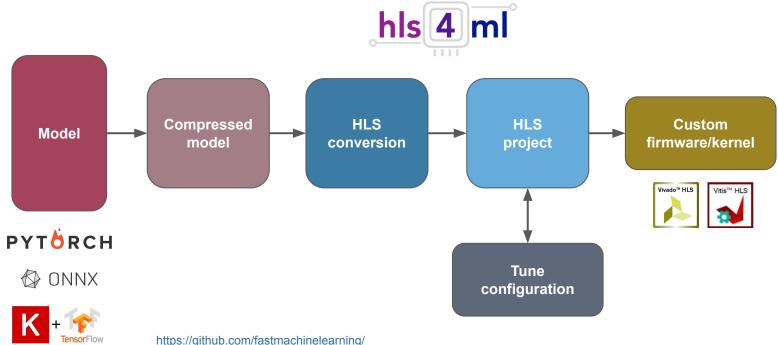




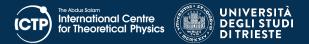


https://github.com/fastmachinelearning/





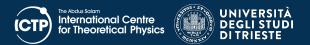
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ML framework support:

- (Q)Keras
- **PyTorch** (limited)
- (Q)ONNX (in development)



Integration with a hardware synthesis tool for ML

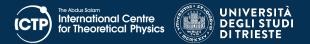


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Neural networks architectures:

- Fully Connected NN
- Convolutional NN
- Recurrent NN
- Graph NN



Integration with a hardware synthesis tool for ML



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HLS backends:

- Vivado HLS
- Intel HLS
- Vitis HLS (experimental)

https://fastmachinelearning.org/hls4ml/



Python integration

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1 from tensorflow.keras.models import load_model 2 from sklearn.metrics import accuracy_score 3 model = load_model('model_keras_MLP.h5') 4 model.summary()

Model: "sequential"

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Layer (type)	Output Shape	Param #
fc1 (Dense)	(None, 60)	3900
relu1 (Activation)	(None, 60)	Θ
fc0 (Dense)	(None, 40)	2440
relu0 (Activation)	(None, 40)	Θ
fc2 (Dense)	(None, 30)	1230
relu2 (Activation)	(None, 30)	0
fal (Danca)	(Nana 10)	210



Python integration

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Python integration

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```
import hls4ml
import plotting
hls4ml.model.optimizer.OutputRoundingSaturationMode.layers = ['Activation']
hls4ml.model.optimizer.OutputRoundingSaturationMode.rounding mode = 'AP RND'
hls4ml.model.optimizer.OutputRoundingSaturationMode.saturation mode = 'AP SAT'
config = hls4ml.utils.config from keras model(model, granularity='name')
config['Model'] = {'Precision' : 'ap fixed<17,16>', 'ReuseFactor' : 1, 'Strategy' : 'Latency'}
config['LayerName']['fc1']['Precision']['weight'] = 'ap fixed<9, 1>'
config['LayerName']['softmax']['Precision'] = 'ap fixed<32,15>'
print("-----
                        ----")
plotting.print dict(config)
print("-----
hls model = hls4ml.converters.convert from keras model(model,
                                                    hls confia=confia.
                                                    output dir='model 3/MLP student smr3765'
hls model.compile()
```



QKeras for quantization-aware training

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```
# MLP architecture
# Create the student OKERAS
studentQ MLP = keras.Seguential(
        Input(shape=(30,)),
        QDense(20, name='fcl',
                 kernel guantizer=guantized bits(9,1,alpha=1), bias guantizer=guantized bits(23,15,alpha=1)),
        QActivation(activation=quantized relu(16,15), name='relu1'),
        ODense(10, name='fc2'.
                 kernel quantizer=quantized bits(9,1,alpha=1), bias quantizer=quantized bits(23,15,alpha=1)),
        OActivation(activation=quantized relu(16.15), name='relu2').
        QDense(10, name='fc6',
                 kernel quantizer=quantized bits(9,1,alpha=1), bias quantizer=quantized bits(23,15,alpha=1)),
        QActivation(activation=quantized relu(16,15), name='relu3'),
        ODense(4, name='output',
                 kernel quantizer=quantized bits(32,15,alpha=1), bias quantizer=quantized bits(32,15,alpha=1)),
        Activation(activation='softmax', name='softmax')
    ],
    name="student".
print gstats(studentQ MLP)
```



hls

High-level synthesis project generated through hls4ml

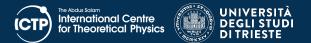
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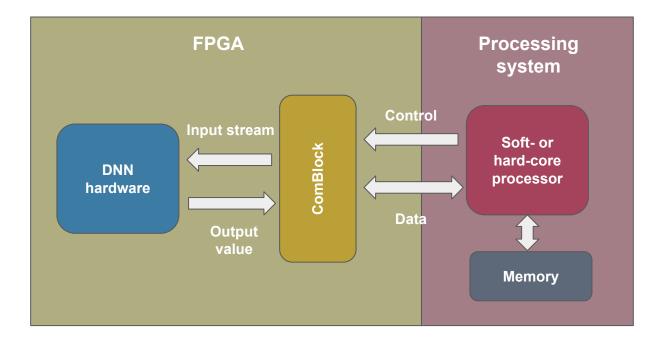
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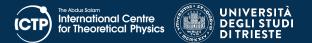
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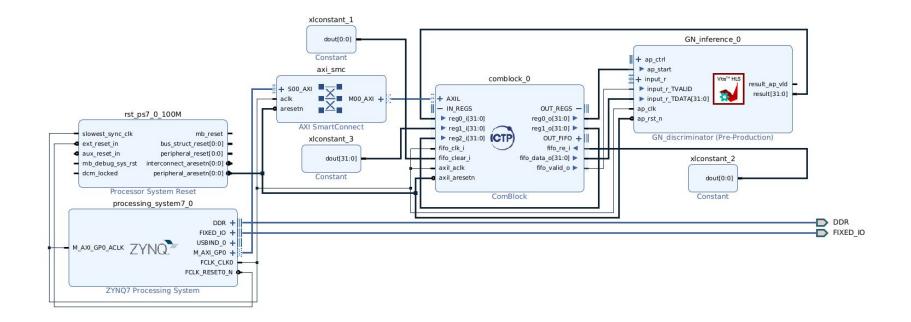
```
esis Summary(solution1)
                        myproject.cpp ×
 Layers t layer8 out[N LAYER 8];
 #pragma HLS ARRAY PARTITION variable=layer8 out complete dim=0
 nnet::dense<layer6 t, layer8 t, config8>(layer6 out, layer8 out, w8, b8); // fc3
 Layer9_t layer9 out[N LAYER 8];
 #pragma HLS ARRAY PARTITION variable=layer9 out complete dim=0
 nnet::linear<layer8 t, layer9 t, linear config9>(layer8 out, layer9 out); // fc3 linear
 layer11 t layer11 out[N LAYER 11];
 #pragma HLS ARRAY PARTITION variable=layer11 out complete dim=0
 nnet::dense<layer9 t, layer11 t, config11>(layer9 out, layer11 out, w11, b11); // fc4
 layer12_t layer12 out[N LAYER 11];
 #pragma HLS ARRAY PARTITION variable=layer12 out complete dim=0
 nnet::linear<layer11 t, layer12 t, linear config12>(layer11 out, layer12 out); // fc4 linear
```



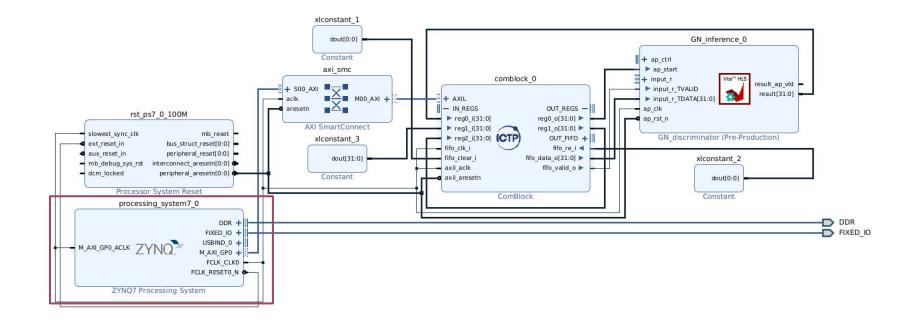




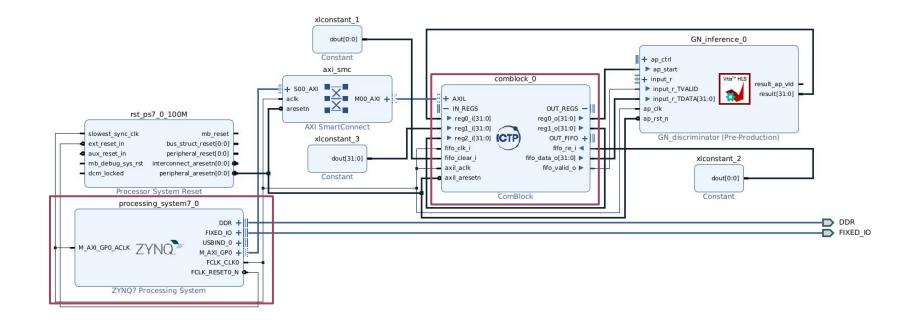




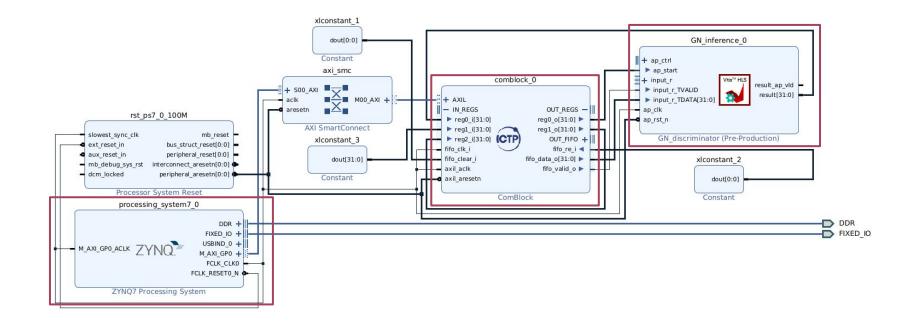








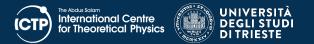








Applications



- Gamma/Neutron discrimination [submitted TNS].
- Pest classification in fruit crops [9, 11].
- Pulse shape discriminator for cosmic rays studies [8, 11].
- Volcanic seismic event detection [12].
- Object detection for adverse weather conditions, particularly haze and fog [India on-going].
- Water quality monitoring applied to Dunav river [Serbia Remarkable / on-going].





Gamma/Neutron discrimination



Gamma/neutron discrimination

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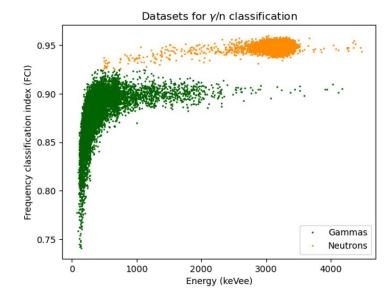


- Tagged dataset of gamma and neutron events from Deuterium-Deuterium
 (DD) and Deuterium-Tritium (DT) generators.
- The dataset was recorded at the Neutron Science Facility (NSF) of the Nuclear Science and Instrumentation Laboratory (NSIL), IAEA.
- The detector is based on a small **CLYC** (Cs2LiYCl6:Ce) crystal (0.5 in diameter by 30 mm length) coupled to a 4-element SiPM array.
- The data were **sampled at 4 GSPS with 10-bits resolution** using a CAEN DT5761 digitizer.
- The total gamma and neutron events in this dataset are 10,913 and 27,696, respectively.



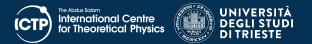
Gamma/neutron discrimination





Morales, I. R., Crespo, M. L., Bogovac, M., Cicuttin, A., Kanaki, K., & Carrato, S. (2023). Gamma/neutron classification with SiPM CLYC detectors using frequency-domain analysis for embedded real-time applications. Nuclear Engineering and Technology.

Dataset from https://doi.org/10.5281/zenodo.8037059



Gamma/neutron discrimination





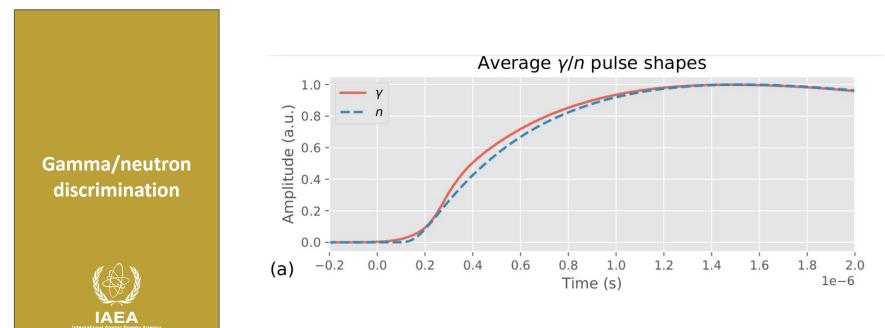


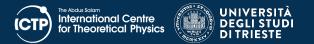


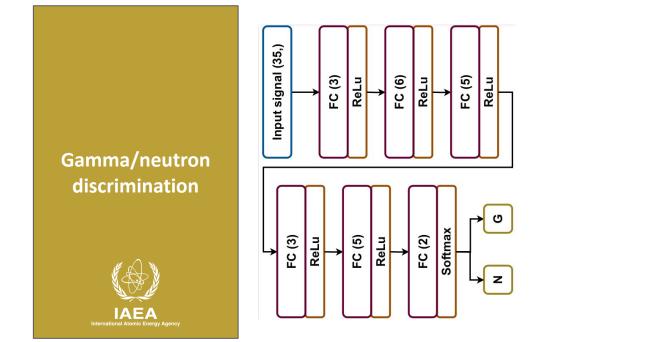
'he Abdus Salam

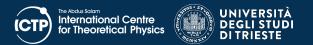
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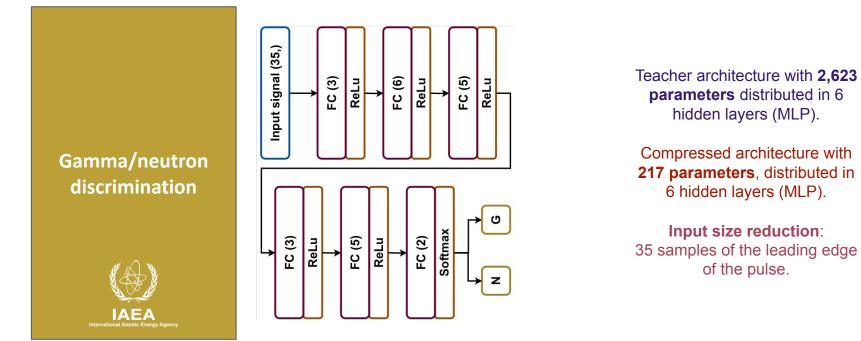
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Overall accuracy

- Teacher architecture (original): **99.00%**
- Student architecture (compressed): 98.20%

Gamma/neutron discrimination





Overall accuracy

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- Teacher architecture (original): **99.00%**
- Student architecture (compressed): **98.20%**
- SoC memory footprint in terms of resource utilization @200MHz
 - Artix-7 platform: **below 35%**

Gamma/neutron discrimination

International Centre for Theoretical Physics





- Overall accuracy
 - Teacher architecture (original): **99.00%**
 - Student architecture (compressed): **98.20%**
- SoC memory footprint in terms of resource utilization @200MHz
 - Artix-7 platform: below 35%

- SoC latency
 - Zedboard platform: 45 clk cycles (@200MHz)

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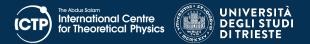
Gamma/neutron discrimination



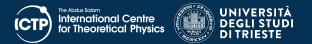


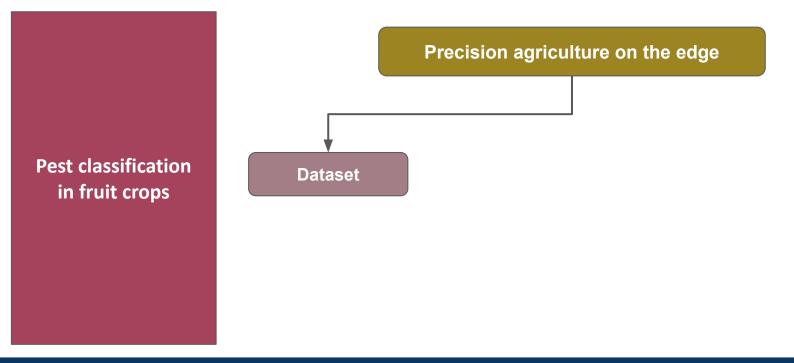


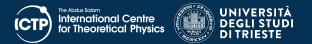
Image classification based on CNN

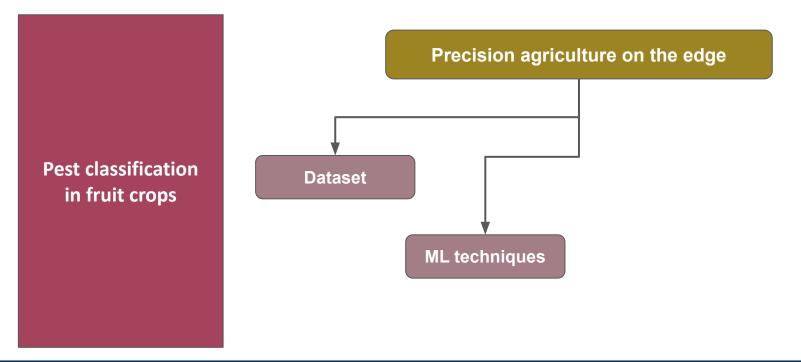


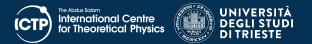
Pest classification in fruit crops Precision agriculture on the edge

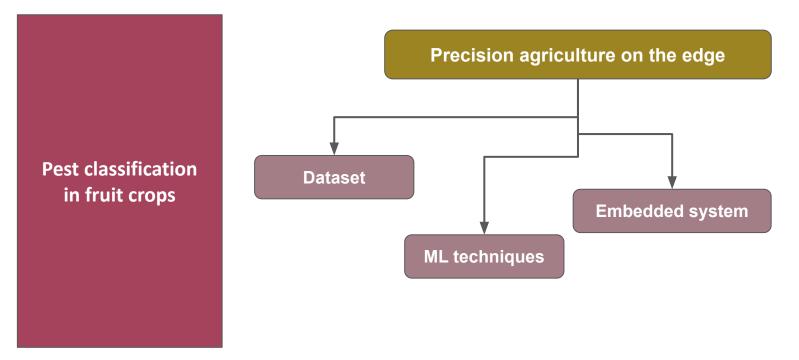


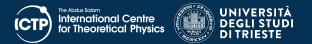


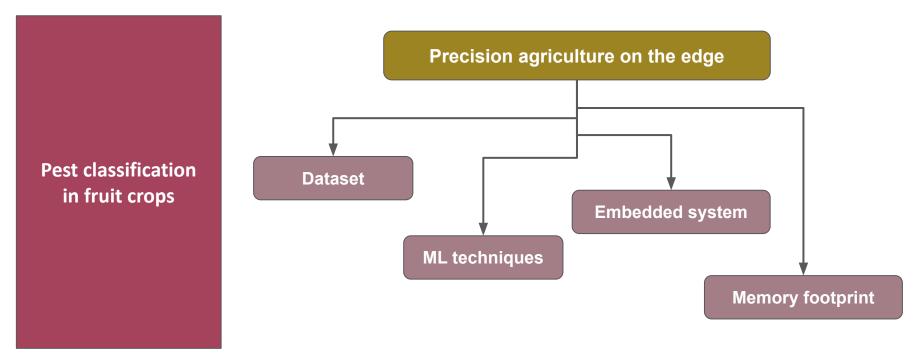


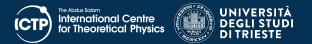




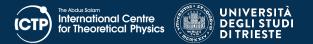


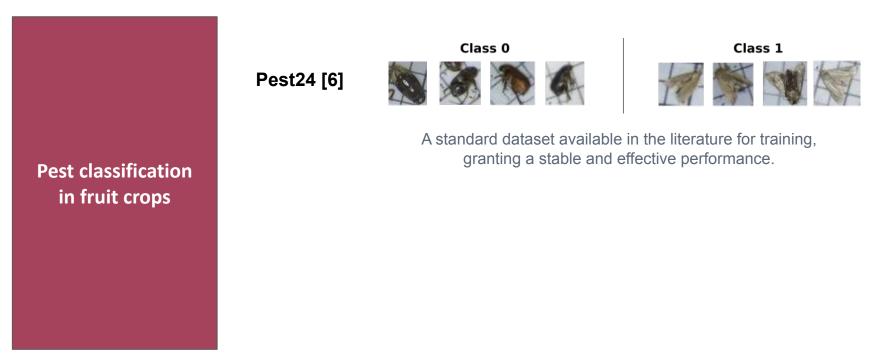


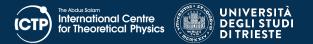


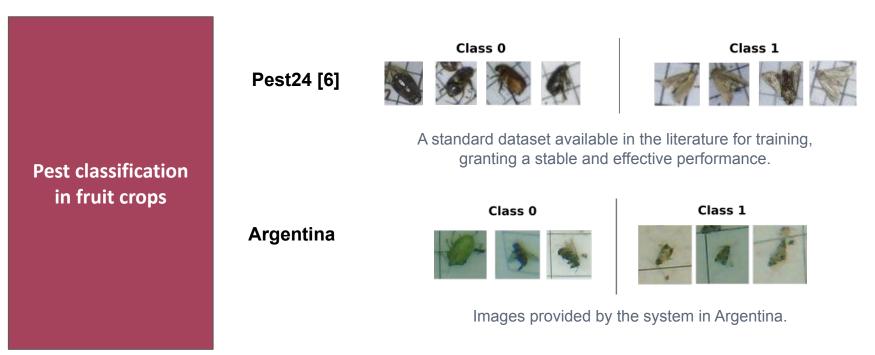


Precision agriculture on the edge Nectras IoT trap Captured image Other insects Pest classification in fruit crops Lobesia botrana

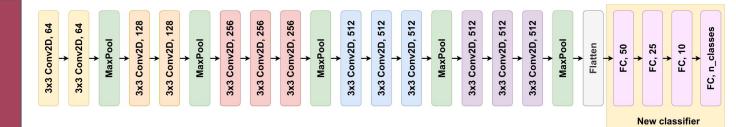






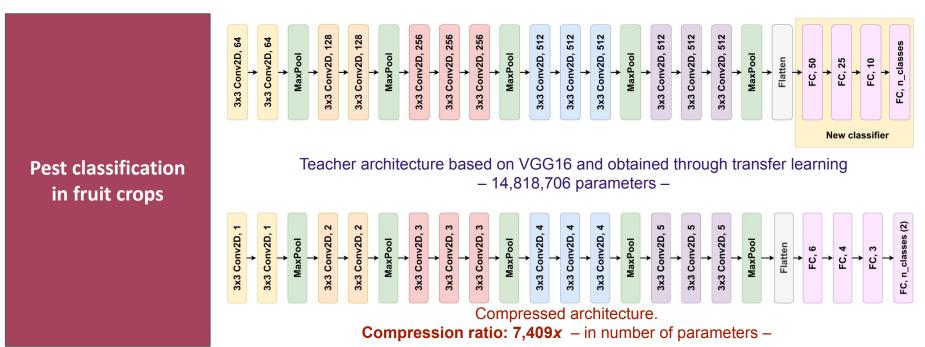






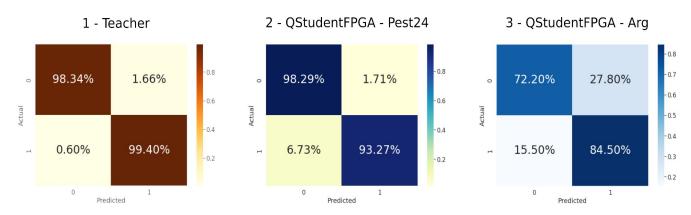
Pest classification in fruit crops Teacher architecture based on VGG16 and obtained through transfer learning - 14,818,706 parameters -











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• Overall accuracy

- Teacher architecture: 98.87%
- Student architecture: **95.78%**

Pest classification in fruit crops

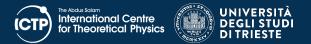


Pest classification

in fruit crops

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- Overall accuracy
 - Teacher architecture: **98.87%**
 - Student architecture: 95.78%
- SoC memory footprint in terms of resource utilization @200MHz
 - KRIA platform: **below 21%**
 - PYNQ-Z1 platform: below 63%

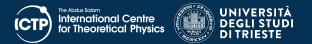


Object detection [work in progress]



Image from Cityscapes dataset.

Cordts, M., Omran, M., Ramos, S., Rehfeld, T., Enzweiler, M., Benenson, R., ... & Schiele, B. (2016). The cityscapes dataset for semantic urban scene understanding. In *Proceedings of the IEEE conference on computer vision and pattern recognition* (pp. 3213-3223).



Object detection [work in progress]



Image from Cityscapes dataset.

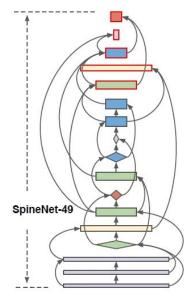
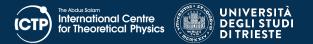


Image from Du, X., Lin, T. Y., Jin, P., Ghiasi, G., Tan, M., Cui, Y., ... & Song, X. (2020). Spinenet: Learning scale-permuted backbone for recognition and localization. In Proceedings of the IEEE/CVF conference on computer vision and pattern recognition (pp. 11592-11601).



Final remarks

- The proposed workflow successfully generates compressed models, leading to a **fully on-chip memory-mapped implementation** on the FPGA.
- The **integration of KD** into the ensemble of compression techniques contributes to achieving a balanced student model in terms of size, computational efficiency, and accuracy.
- The workflow addresses the entire development cycle: from the ML-based architecture training to the hardware deployment, overcoming the limitations outlined in previous works.
- Addition of FPGA metric estimation in the training stage to adapt the ML-based model to the hardware architecture.



Workshop on Fully Programmable Systems-on-Chip for Scientific Applications







Thank you!!

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Back up slides

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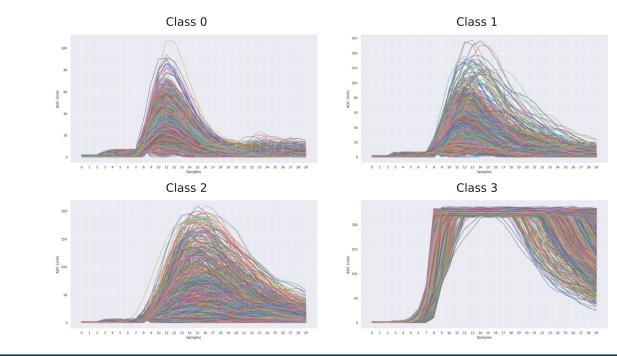


Pulse shape discriminator for cosmic rays studies

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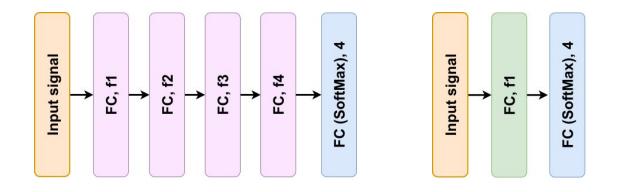
Pulse shape discriminator for cosmic rays studies



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Pulse shape discriminator for cosmic rays studies



Left. Teacher architecture based on MLP - 16,352 parameters.

Right: Distilled architecture - **529** parameters Compression ratio: 30.91*x*.



Pulse shape discriminator for cosmic rays studies

- Overall accuracy
 - Teacher architecture: 99.70%
 - Student architecture: 98.96%
 - 8-bit fixed point
 - Target sparsity: 20%



Pulse shape discriminator for cosmic rays studies

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• Overall accuracy

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- Teacher architecture: 99.70%
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 - 8-bit fixed point
 - Target sparsity: 20%
- SoC memory footprint in terms of resource utilization @200MHz
 - Artix-7: below 27%



Pulse shape discriminator for cosmic rays studies

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• Overall accuracy

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- Teacher architecture: **99.70%**
- Student architecture: **98.96%**
 - 8-bit fixed point
 - Target sparsity: 20%
- SoC memory footprint in terms of resource utilization @200MHz
 - Artix-7: **below 27%**
- SoC latency @200MHz
 - Artix-7: 10 clock cycles

ML and model compression techniques for SoC/FPGA Applications - Connections example

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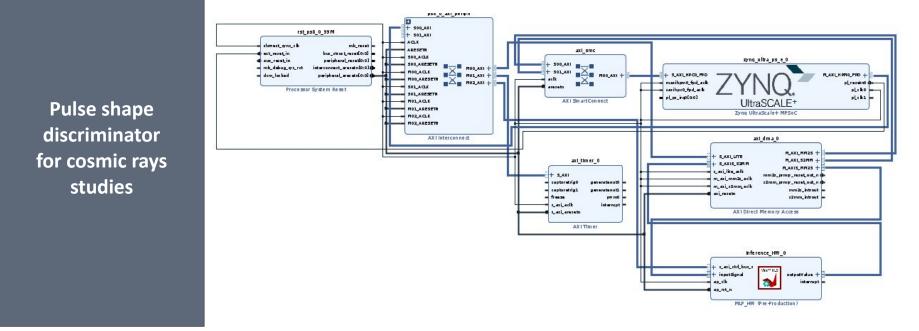
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Pulse shape discriminator for cosmic rays

In []: from pyng import Overlay

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In []:	<pre>ol = Overlay("hw/inference_PYNO.bit")</pre>
In []:	ol.ip_dict
In []:	dma = ol.axi_dma_0 dma_send = ol.axi_dma_0.sendchannel dma_recv = ol.axi_dma_0.recvchannel
In []:	<pre>from pynq import allocate import numpy as np data_size = 30 input_buffer = allocate(shape=(data_size,), dtype=np.uint32)</pre>
In []:	<pre>x3 = [0, 2, 0, 0, 0, 0, 2, 14, 60, 231, 232, 232, 232, 230, 232, 231, 233, 232, 231, 231, 232, 232, 231, 230, 232, 231, 232, 231, 230] for i in range(0, data_size): input_buffer[i] = x3[i]</pre>
In []:	<pre>import matplotlib.pyplot as plt plt.figure(figsize=(15,7)) plt.xlabel('Samples', fontsize=11) plt.ylabel('Amplitude', fontsize=11) plt.grid(True, alpha=1.0) plt.plot(x3, 'o', label="Signal 1", color='navy', markersize=7, lw=1)</pre>







Pulse shape discriminator for cosmic rays studies JNIVERSITÀ

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hls_ip = ol.inference_HW_0
hls_ip.register_map
<pre># Initialize HLS IP core CONTROL_REGISTER = 0x0 hls_ip.write(CONTROL_REGISTER, 0x81) # 0x81 will set bit 0</pre>
hls_ip.register_map
<pre># Start the DMA transfer dma_send.transfer(input_buffer)</pre>
<pre>output_buffer = allocate(shape=(4,), dtype=np.uint32)</pre>
<pre>dma_recv.transfer(output_buffer)</pre>
<pre>for i in range(4): print((output_buffer[i]))</pre>



