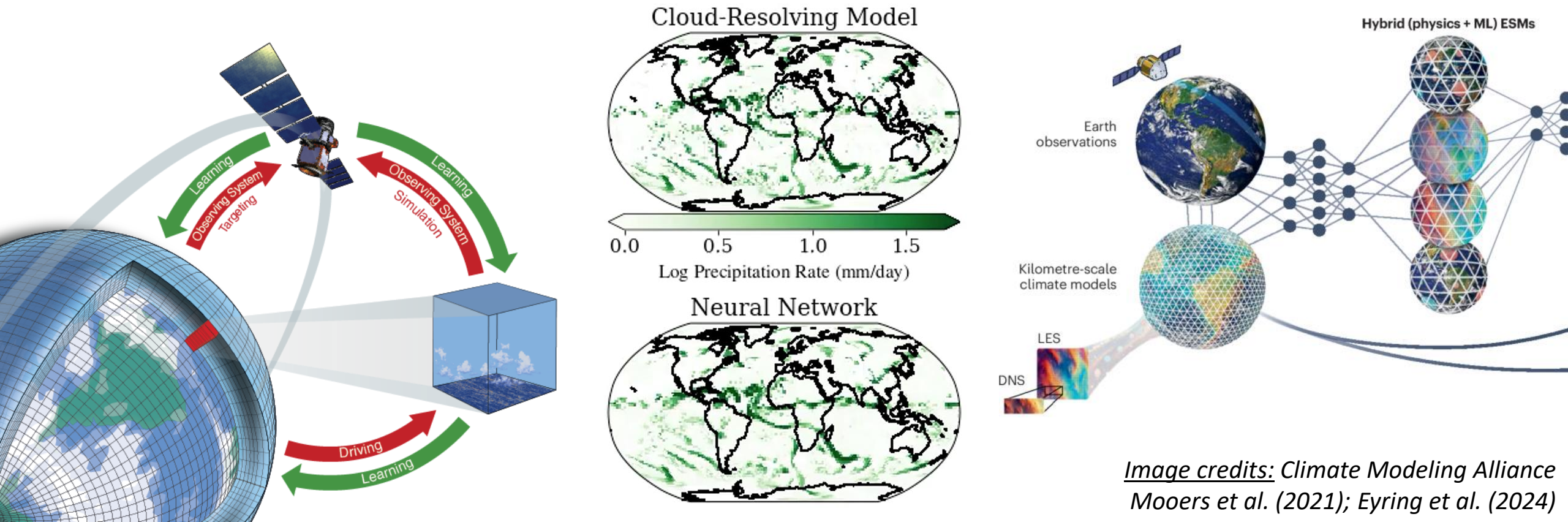


# Towards Reliable Hybrid AI-Climate Modeling



*Image credits: Climate Modeling Alliance  
Mooers et al. (2021); Eyring et al. (2024)*



# Atmospheric Physics + AI

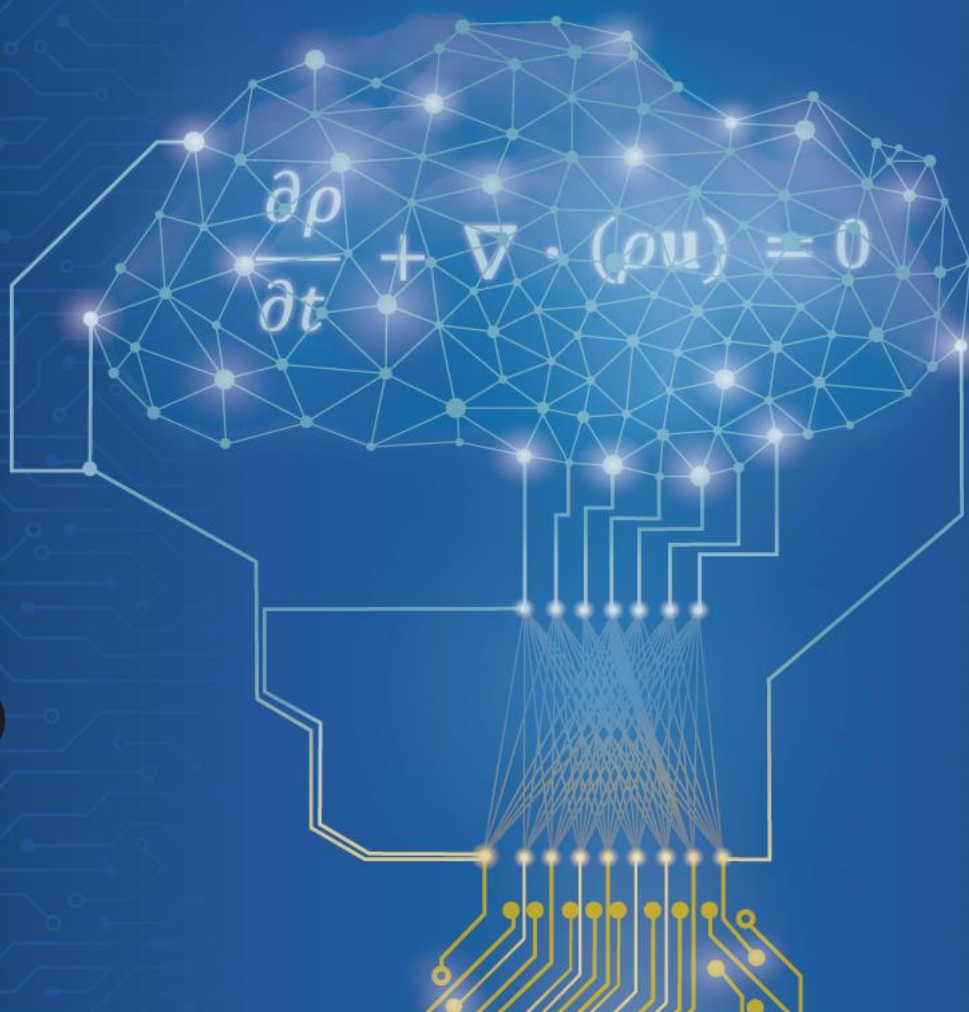
$$\frac{D\vec{v}}{Dt} + 2\vec{\Omega} \times \vec{v} = -\frac{\vec{\nabla} p}{\rho} - \vec{\nabla} \Phi$$

$$\mu \frac{dI}{dT} = I - B$$

$$\frac{de^*}{dT} = \frac{L_v e^*}{R_v T^2}$$

Physics-Guided ML

Data-Driven Discovery



Earth System Modeling  
(Parameterization)

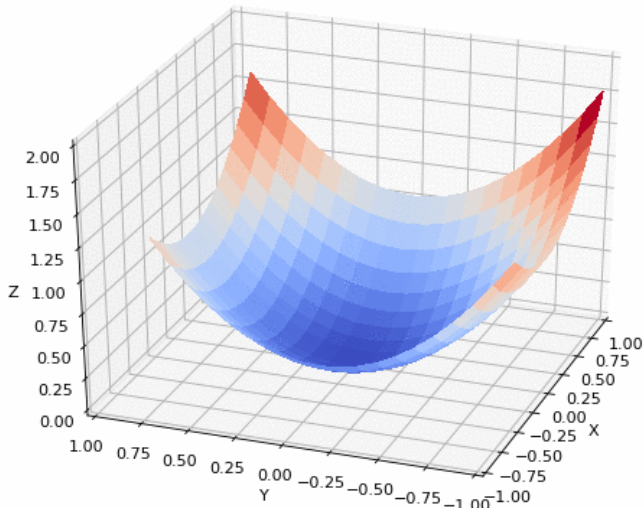
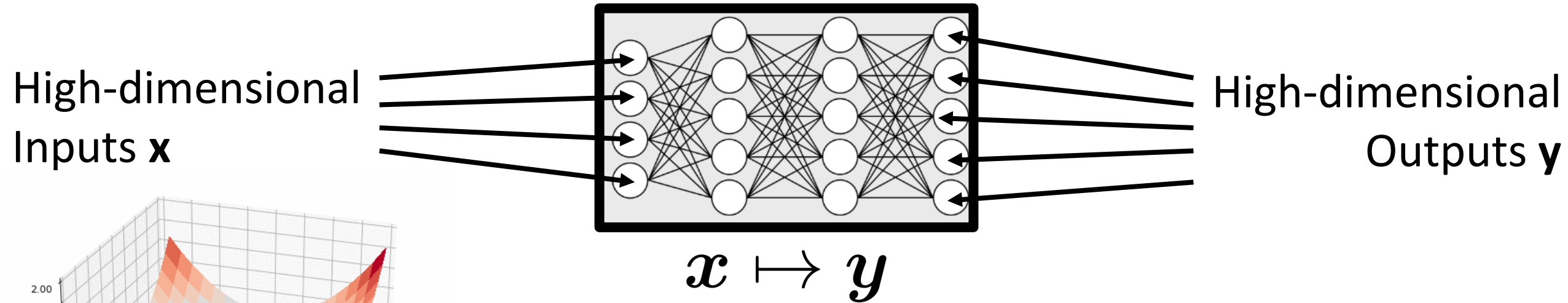
Extreme Weather Events  
Forecasting,  
Post-Processing,  
Downscaling

Environmental  
Data Science



Machine Learning = Learning task from data without being explicitly programmed for task

Neural Network = Non-linear regression tool



min Loss function ( $\mathbf{y}_{\text{Predicted}}, \mathbf{y}_{\text{Truth}}$ )



Lots of data

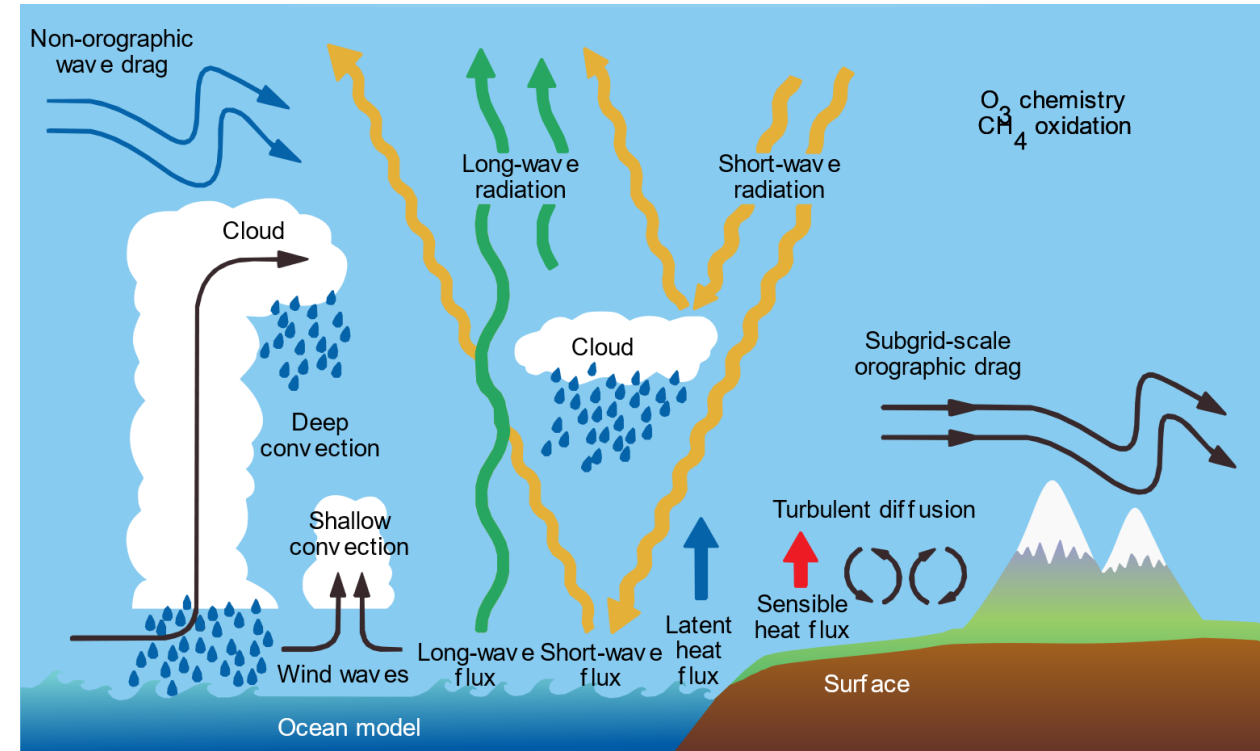
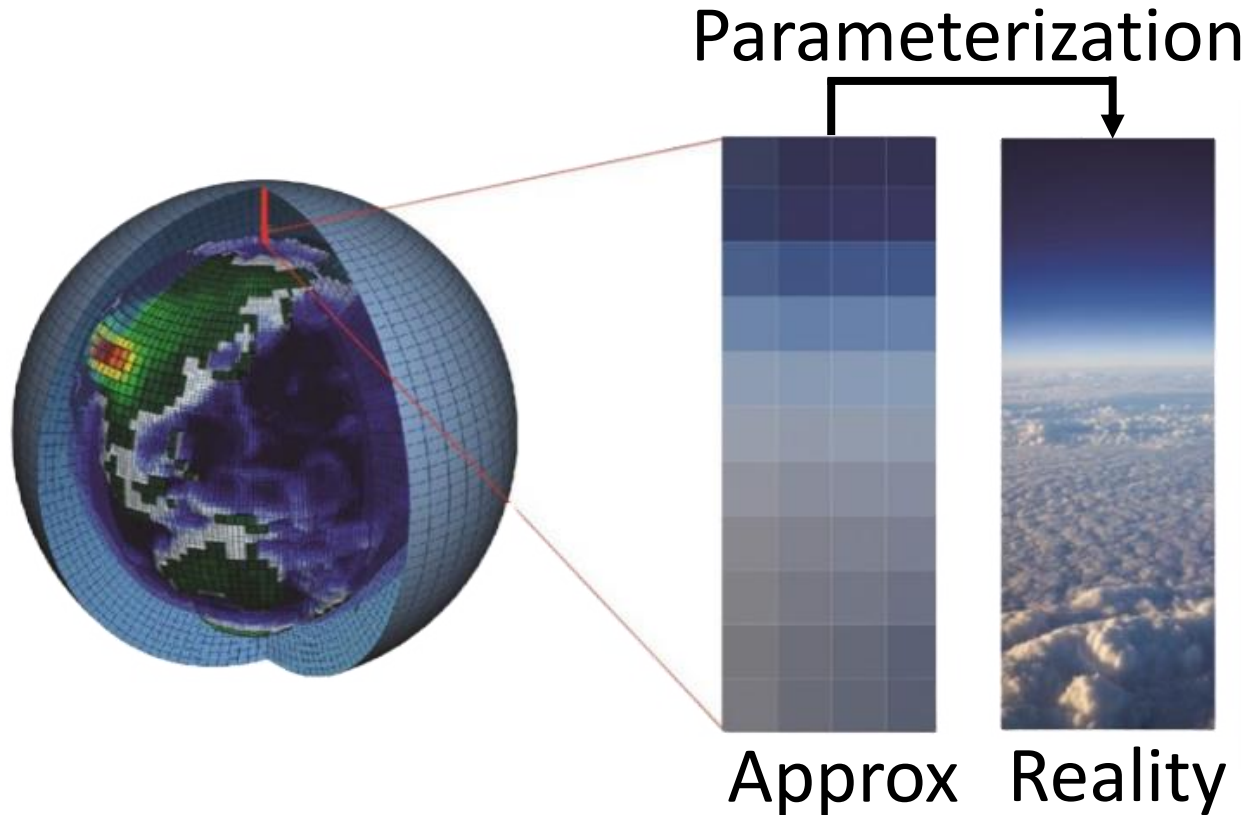


Largest uncertainties in long-term atmospheric  
projections linked to subgrid cloud processes





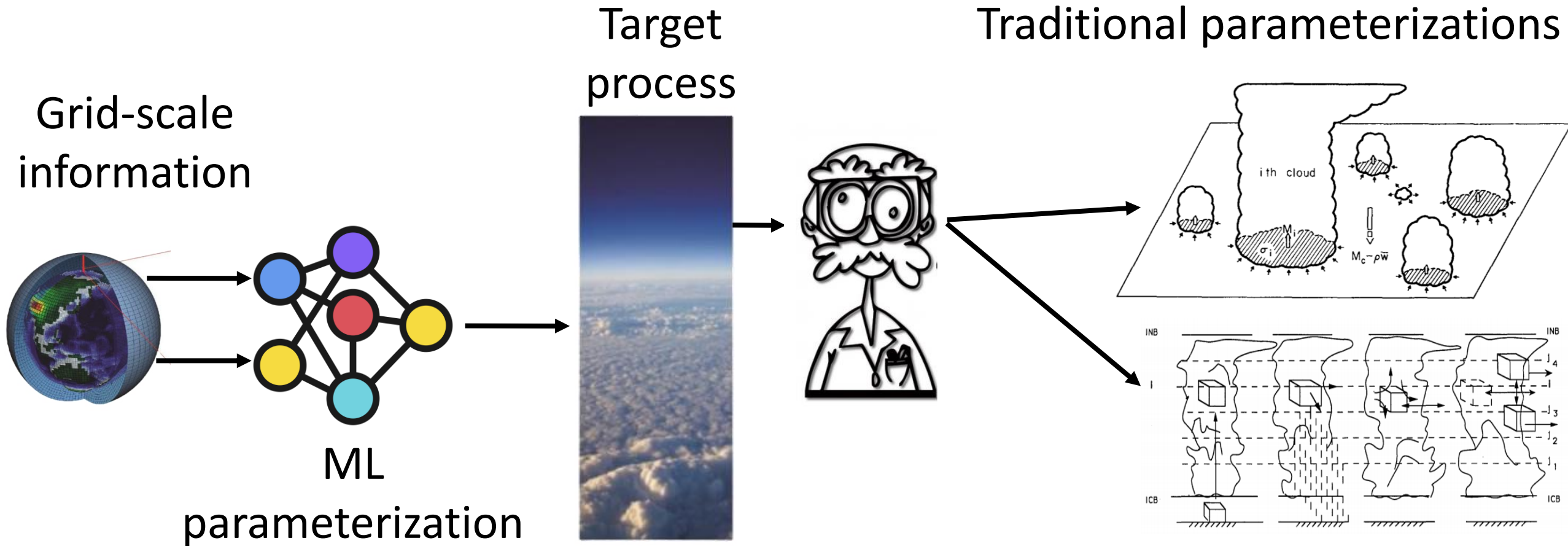
# Processes that are not explicitly resolved by Earth System models must be **parameterized**



Schematic source: ECMWF

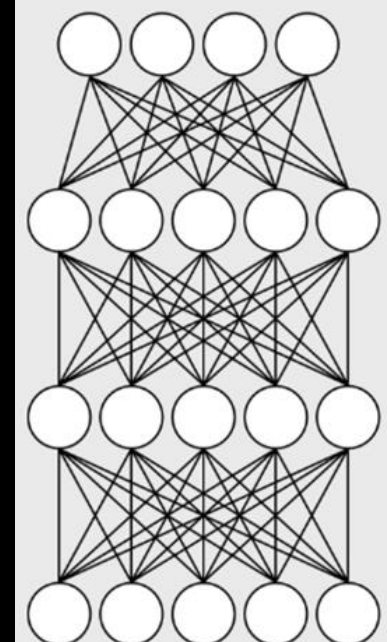
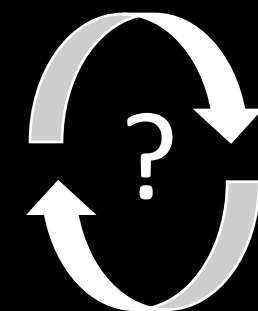
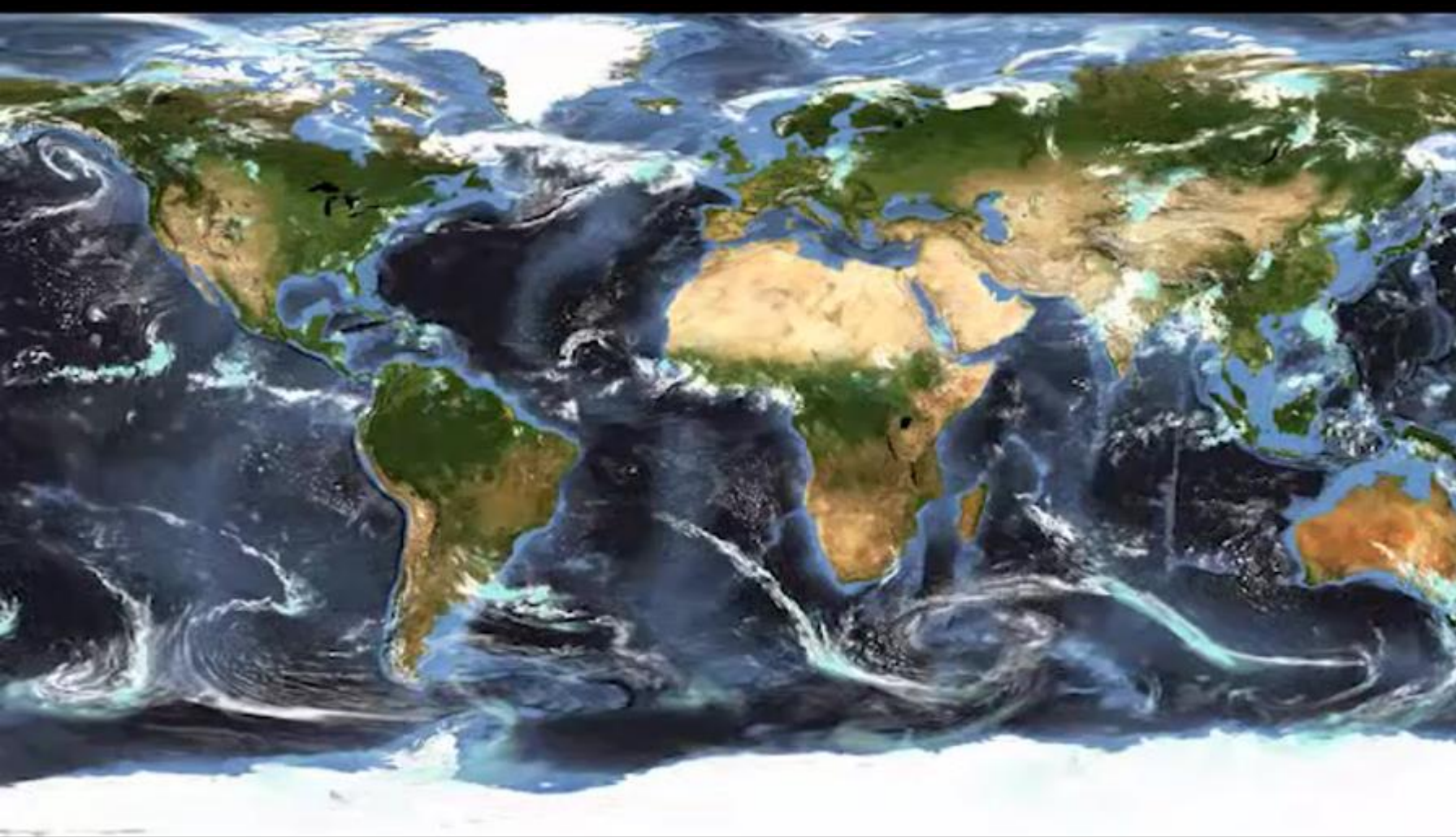
References: Humphrey et al. (2008), Mass et al. (2002), Zelinka et al. (2020), Boucher et al. (2014), Sherwood et al. (2014), Gentine et al. (2020)

# We can machine learn a **parameterization** from data → **emulation** of observations and/or models



References: Gentine et al. (2020), Bretherton (schematic), Arakawa & Schubert (1974), Emanuel (1999)

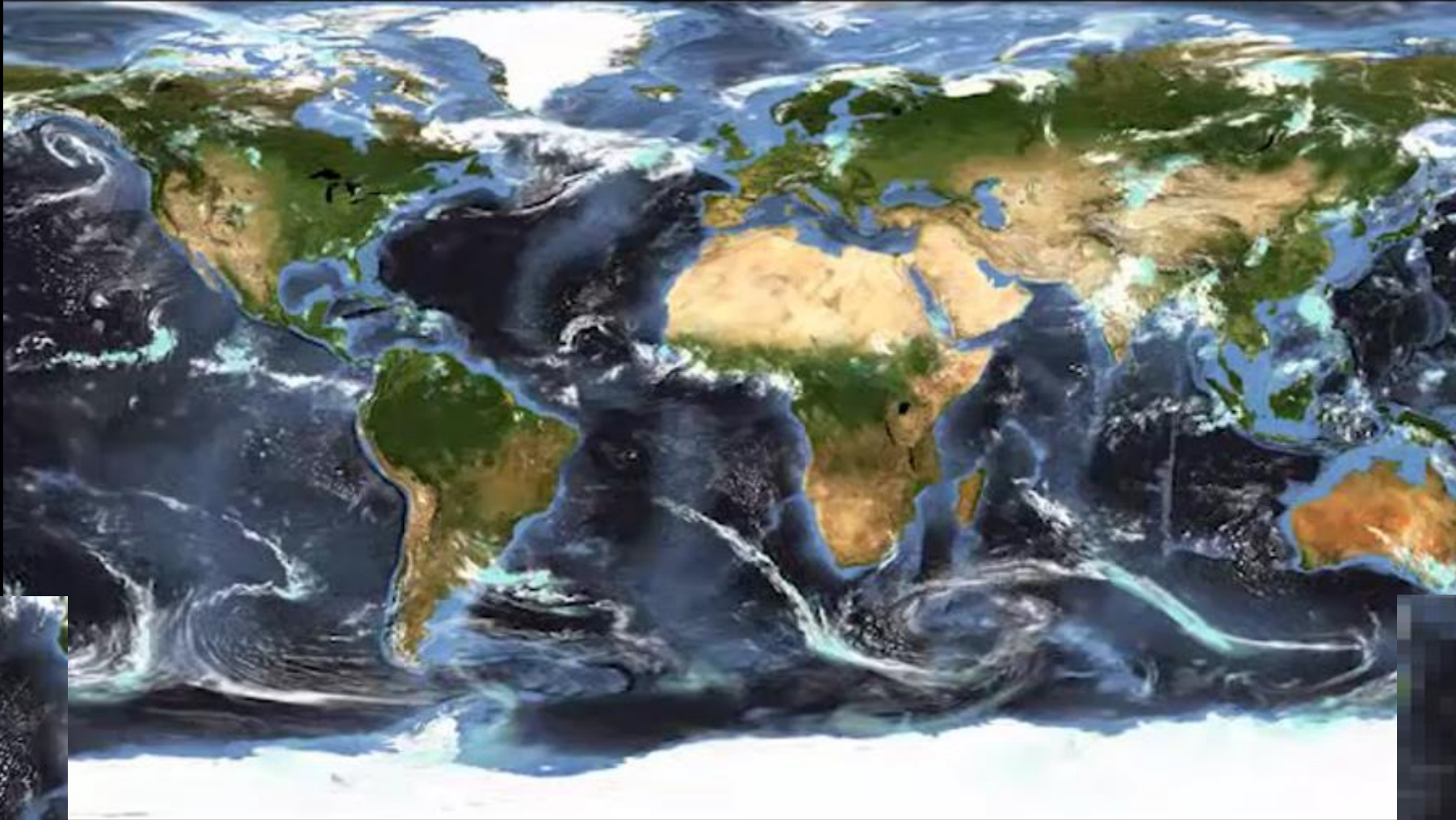




Video source: Global Storm-Resolving and Large-Domain Large-Eddy Simulations with ICON LEM. Deutsches Klimarechenzentrum  
Image source: Pierre Gentine (LEAP)



Coarse graining enables learning the aggregate effects of subgrid clouds and turbulence, too costly to simulate in routine climate projections



Video source:  
*P. Gentine (LEAP)*

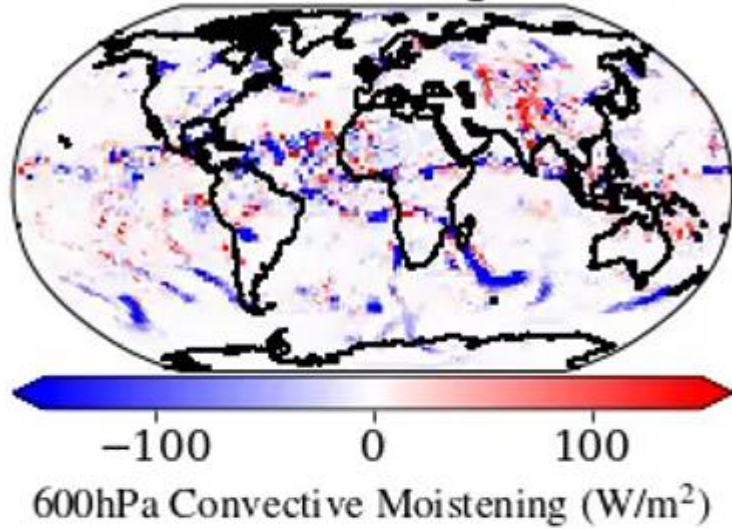
Coarse-Graining



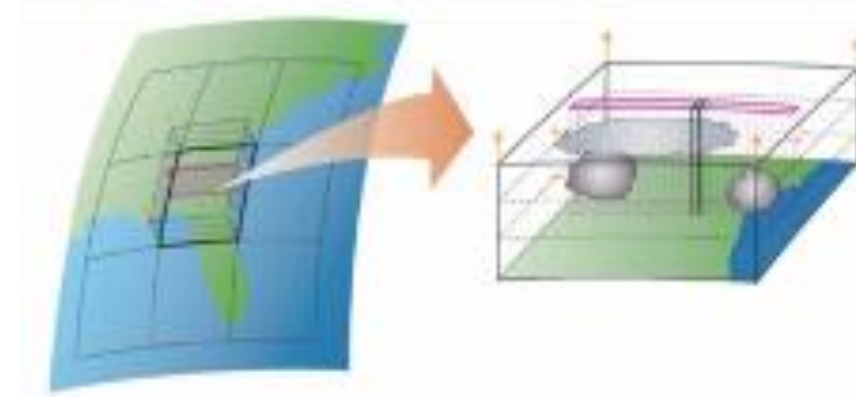
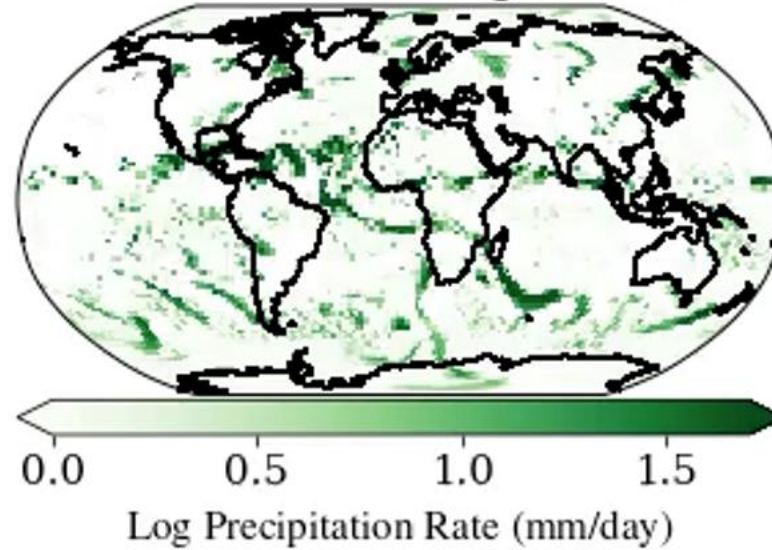


# Neural Networks can emulate subgrid tendencies with high accuracy in realistic geography configurations

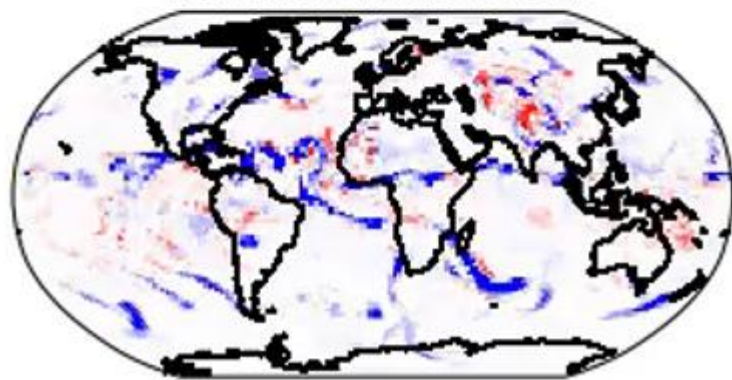
Cloud-Resolving Model



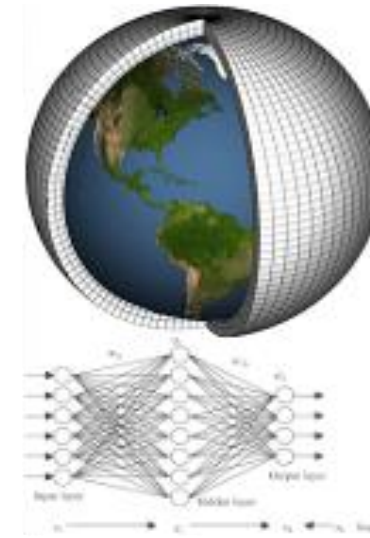
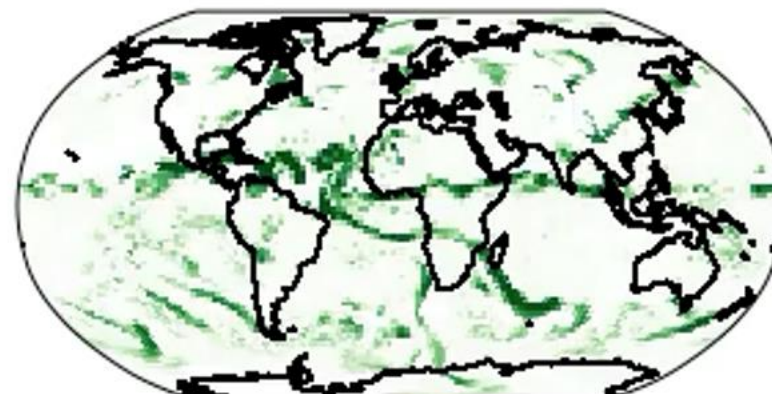
Cloud-Resolving Model



Neural Network



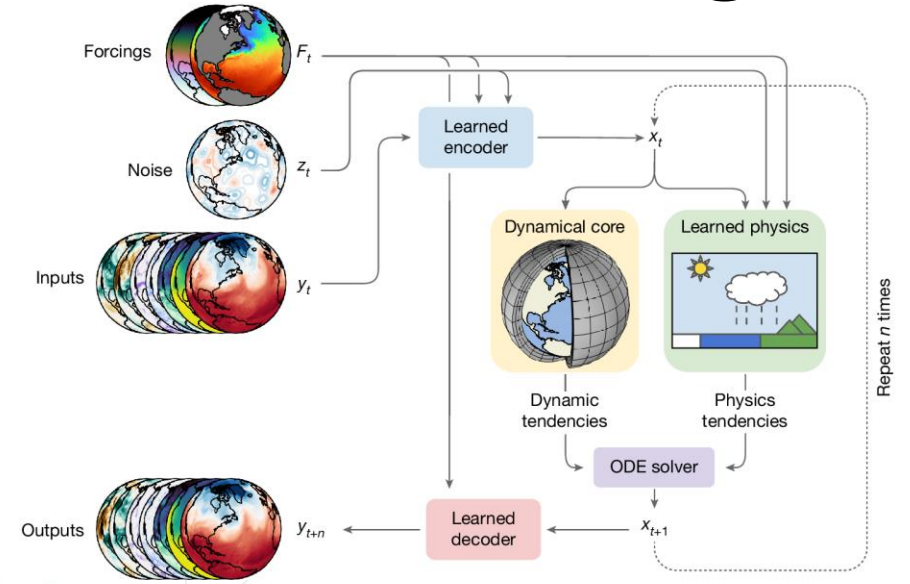
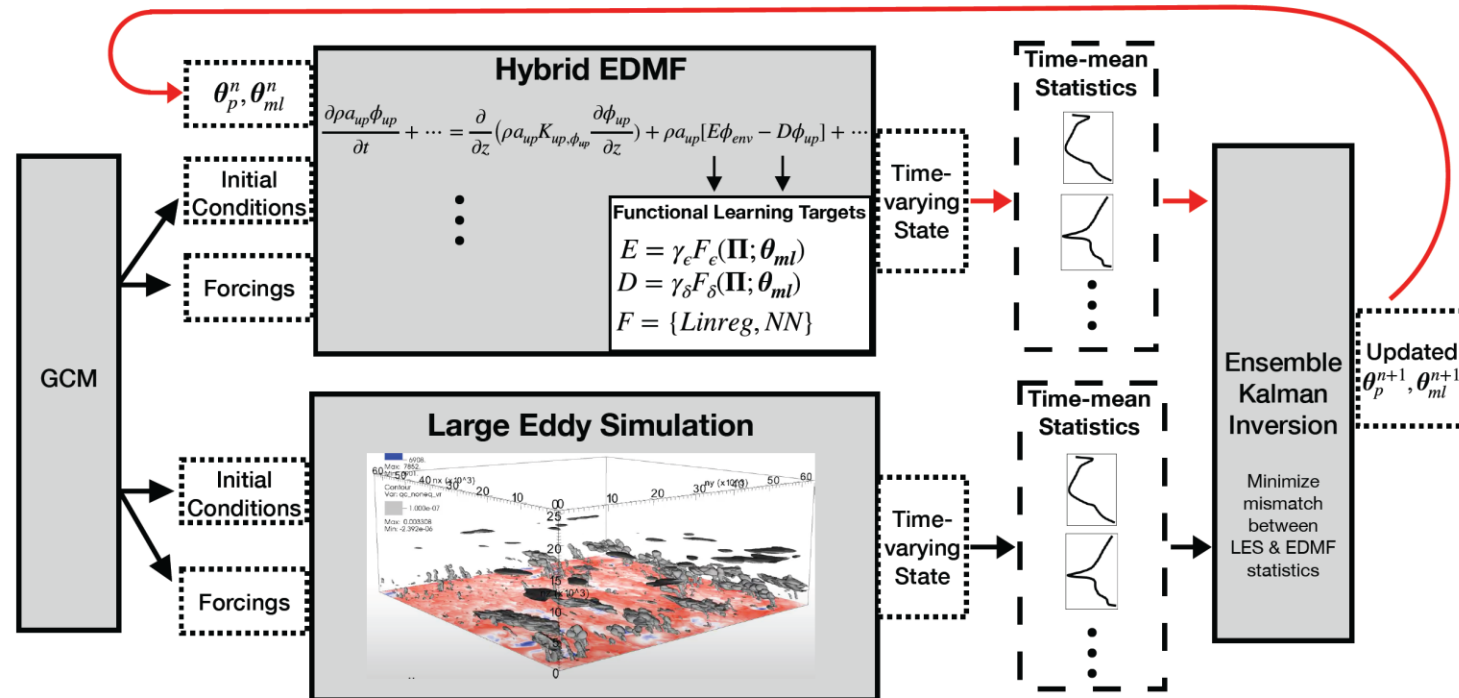
Neural Network



*Video source:*  
Griffin Mooers (MIT)  
*Article:*  
Mooers et al. (2021)

# Data-Driven Parameterizations are flourishing...

## Online Function Learning with Ensemble Kalman Inversion



kaggle

Create

Home

Competitions

Datasets

Models

Code

Discussions

Learn

More

Your Work

VIEWED

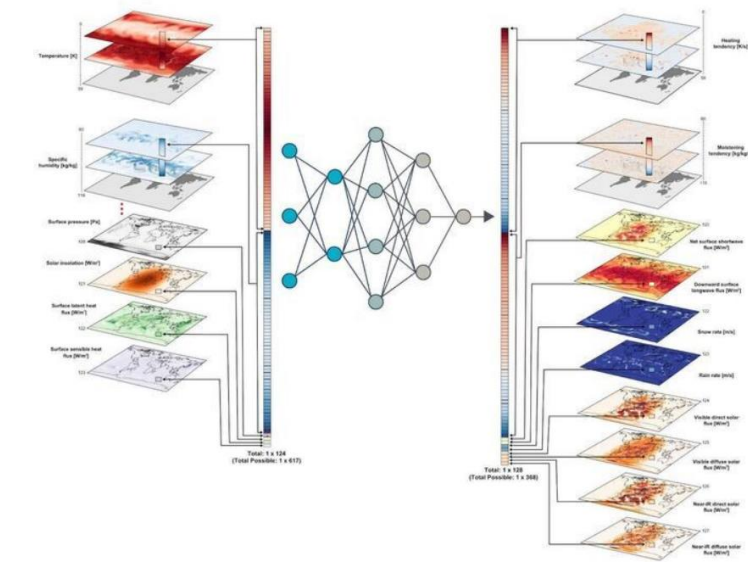
LEAP - Atmospheric...

LEAP: Training 1

LEAP: model preds ...

### LEAP - Atmospheric Physics using AI (ClimSim)

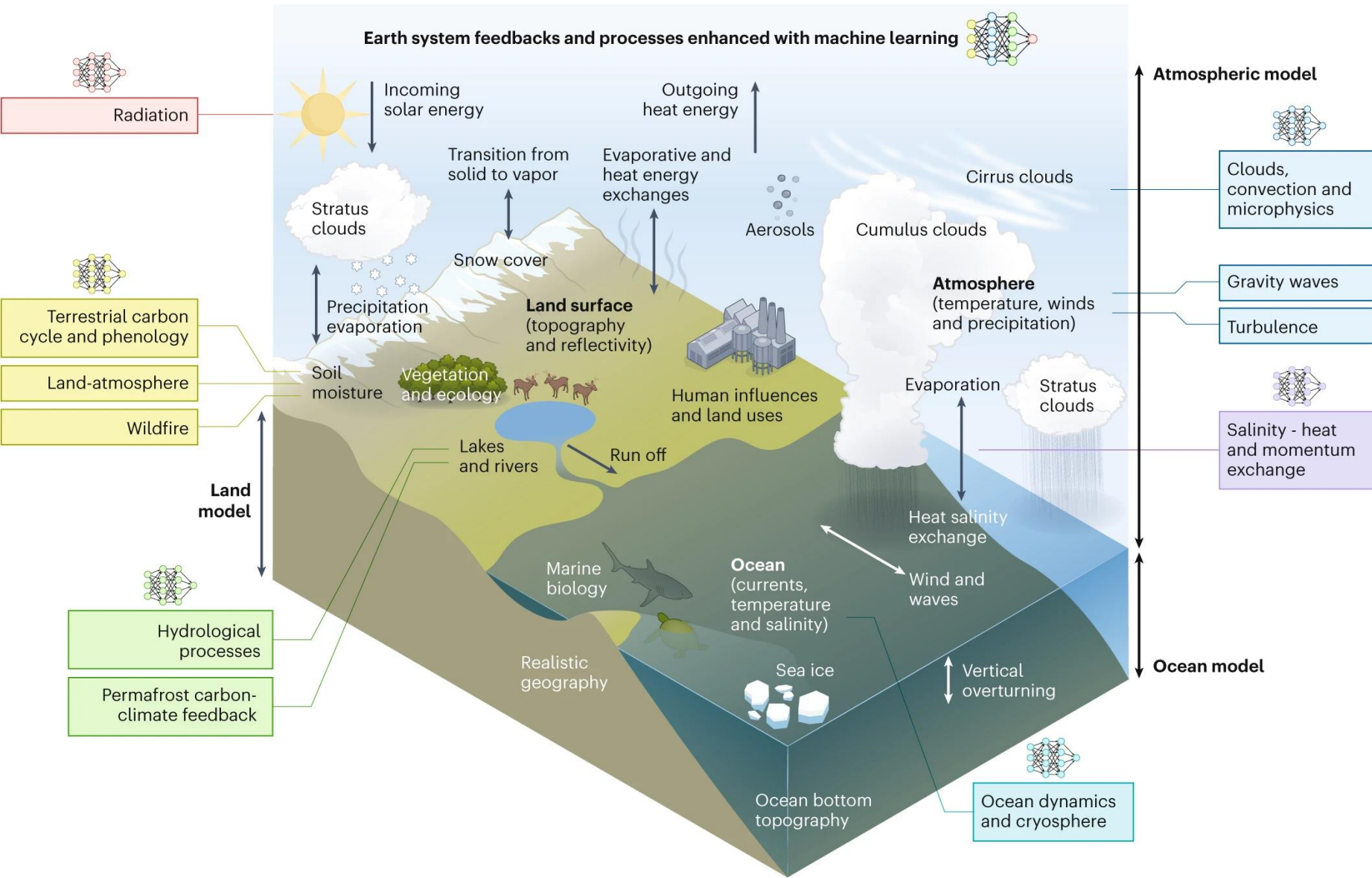
Overview Data Code Models Discussion Leaderboard Rules



See: Christopoulos et al. (2024), Kochkov et al. (2024), Yu et al. (2023, 2024)



# Data-Driven Parameterizations are flourishing and **Hybrid AI-climate modeling** is within grasp...



Question:

Why are hybrid  
AI-climate models  
not routine  
by now?

*See: Eyring et al. (2024)*



# ...but remain under-used in climate science

$$C_{\text{frac}} = \text{ML} (p, q_v, q_l, q_i, T)$$

Cloud Fraction  
Parameterization  
(Grundner et al., 2024)

Subgrid-Scale Thermodynamics  
Parameterization  
(Beucler et al., 2024)

$$\begin{pmatrix} \dot{T} \\ \dot{q} \end{pmatrix} = \text{ML} (p, q_v, T, \text{LHF}, \text{SHF}, S_0)$$

IS ML  
RELIABLE  
FOR  
CLIMATE  
PROJECTIONS?

HAVE WE  
LEARNED  
ANYTHING NEW  
USING ML?



$$\frac{D\vec{v}}{Dt} + 2\vec{\Omega} \times \vec{v} = -\frac{\vec{\nabla} p}{\rho} - \vec{\nabla} \Phi$$

$$\mu \frac{dI}{dT} = I - B$$

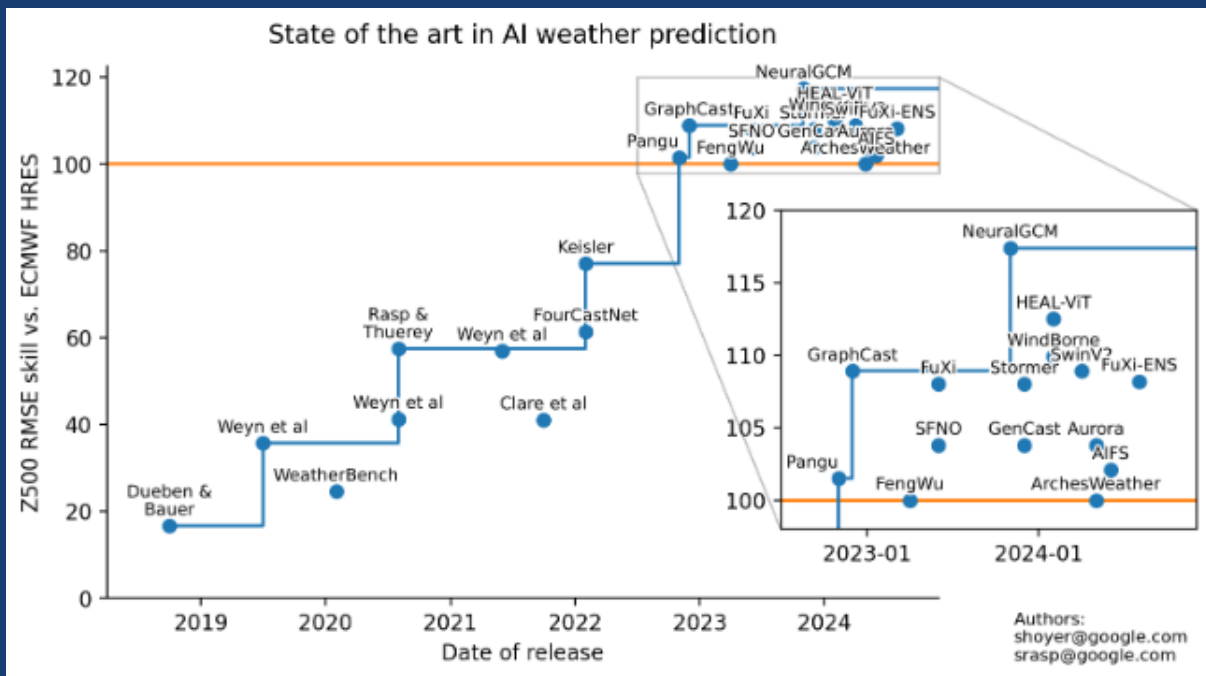
$$\frac{de^*}{dT} = \frac{\mathcal{L}_v e^*}{R_v T^2}$$

$$\int$$

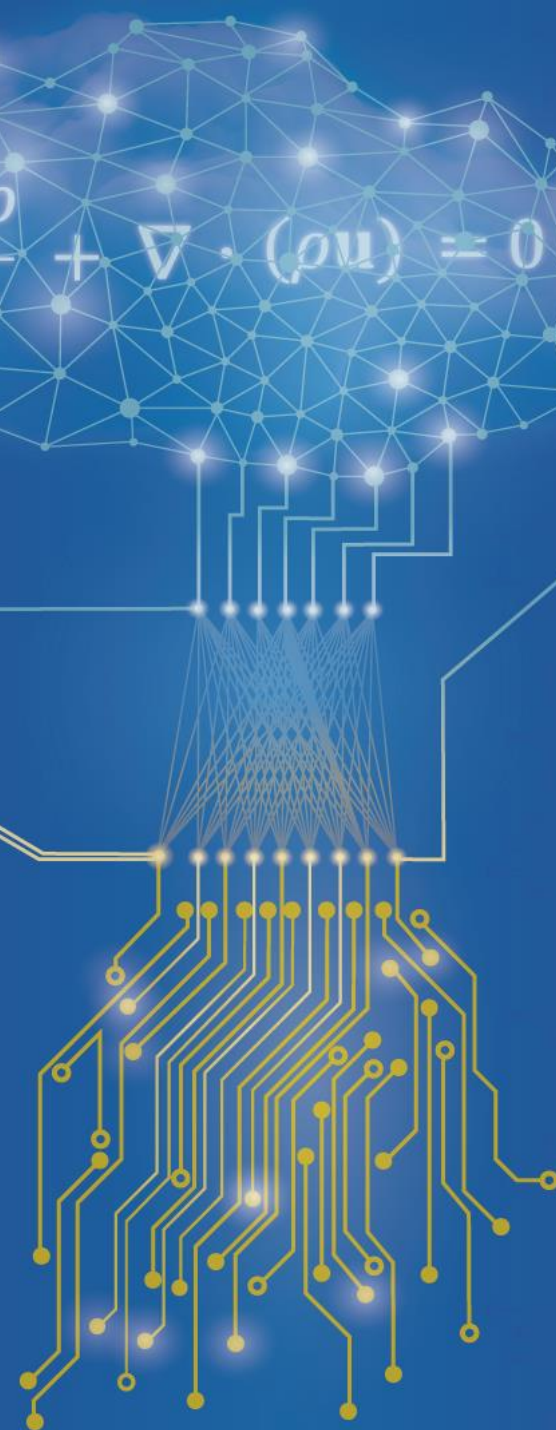
←  
Data-Driven Discovery



Added value of ML measurable...



...but often challenging to explain



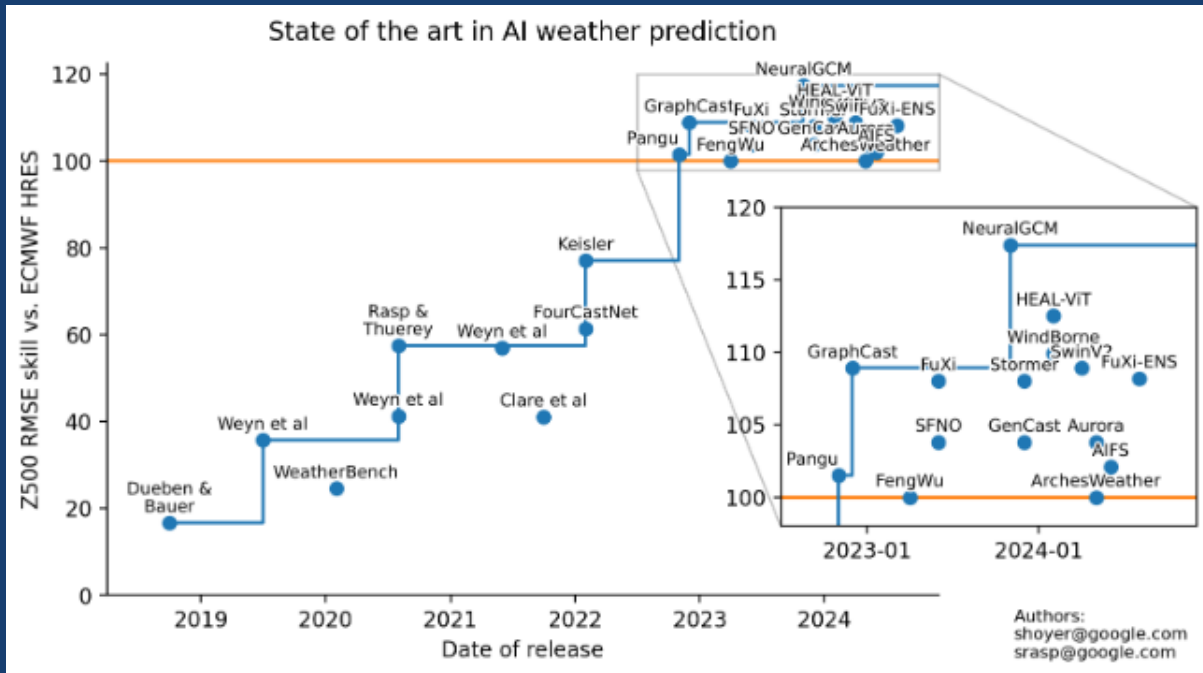
$$\frac{D\vec{v}}{Dt} + 2\vec{\Omega} \times \vec{v} = -\frac{\vec{\nabla}p}{\rho} - \vec{\nabla}\Phi$$

$$\mu \frac{dI}{dT} = I - B$$

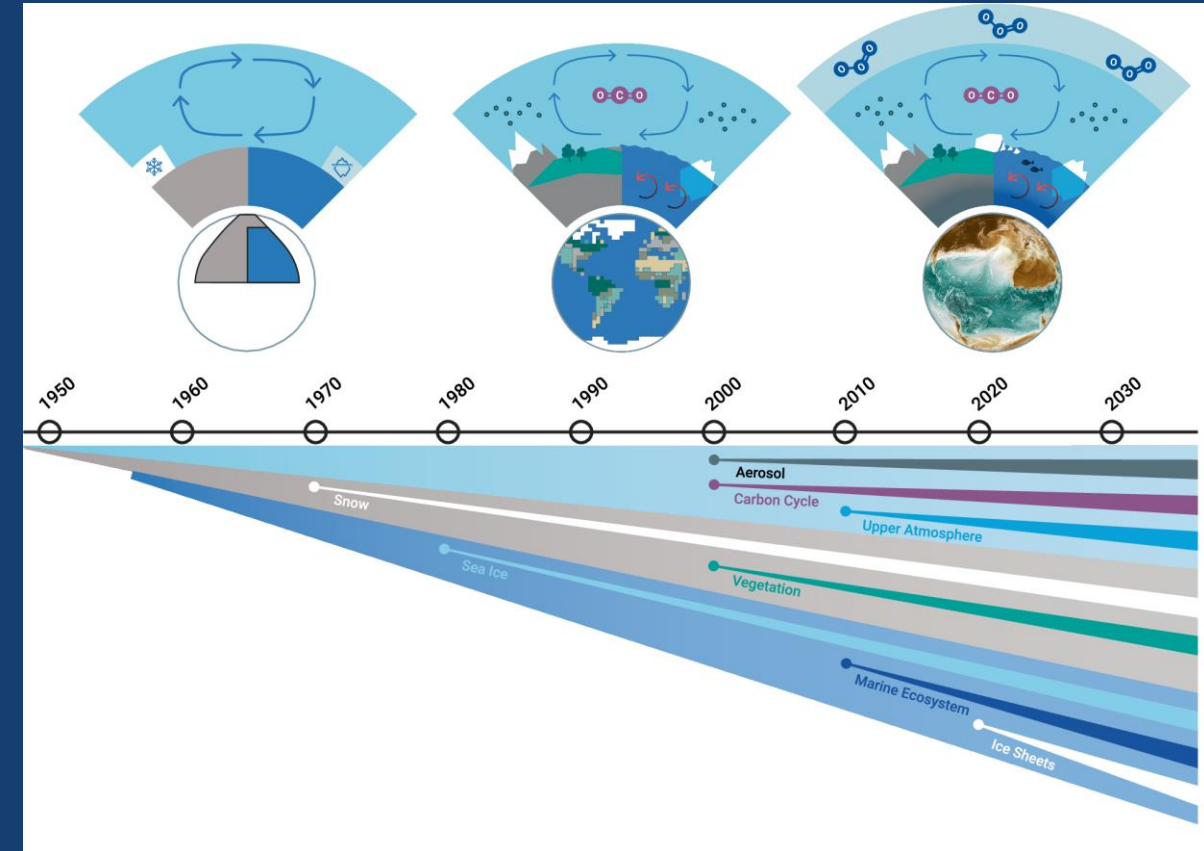
$$\frac{de^*}{dT} = \frac{\mathcal{L}_v e^*}{R_v T^2}$$



Added value of ML measurable...



...but often challenging to explain



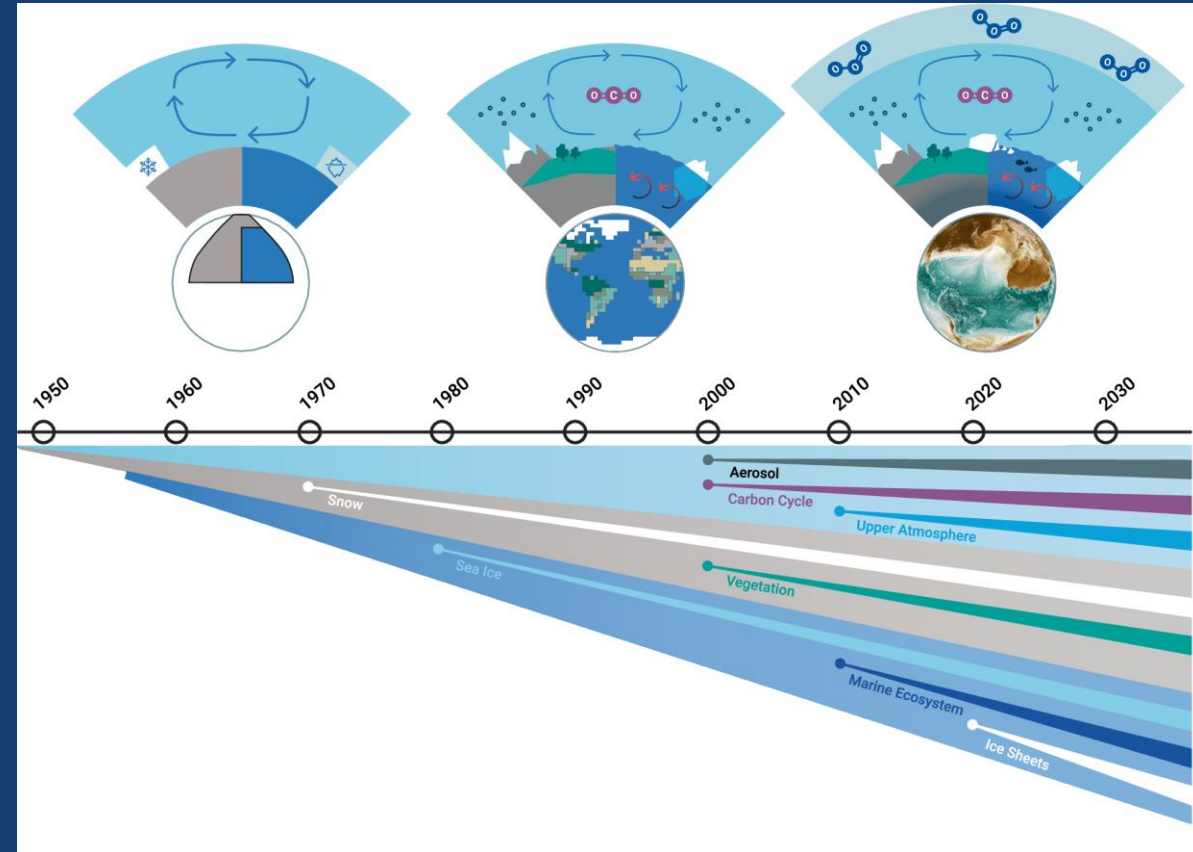
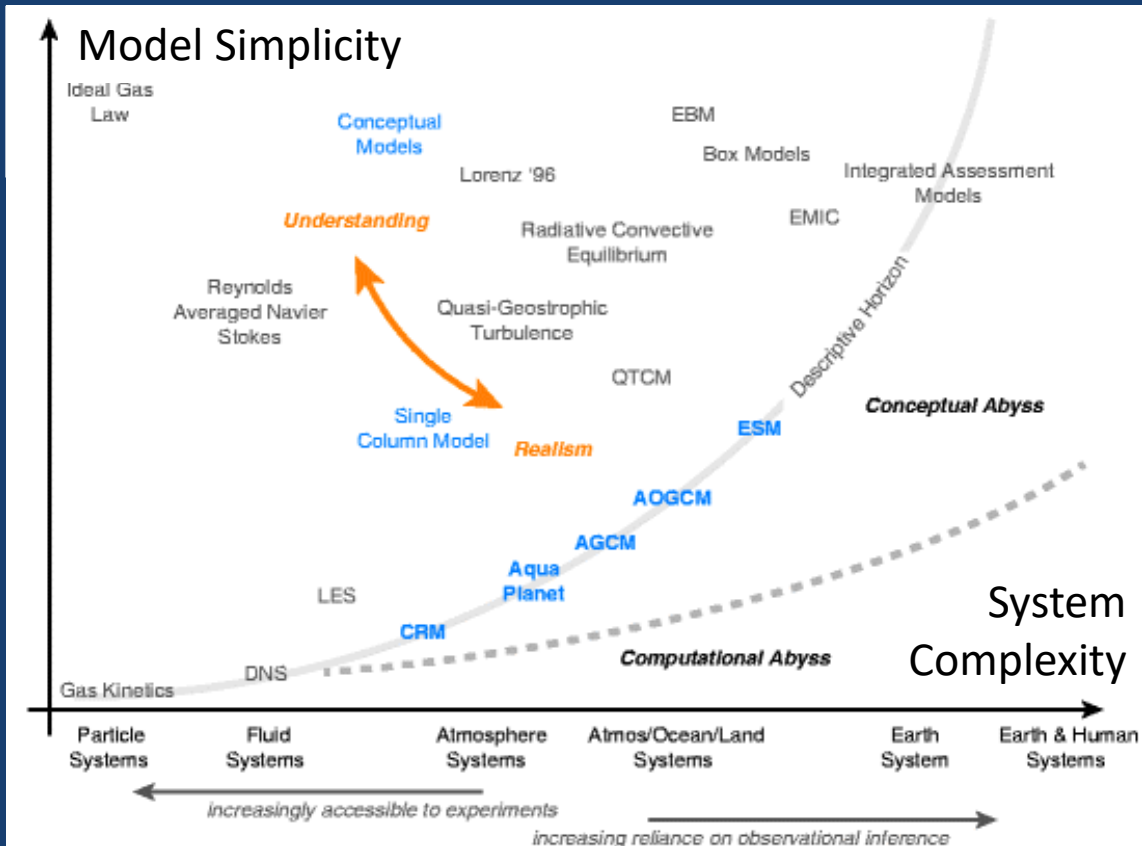
Source: Bordoni et al. (2025), Bony et al. (2013);  
See: Jeevanjee et al. (2017), Balaji (2022), ORNL (C. Jones, 2018)



$$\frac{D\vec{v}}{Dt} + 2\vec{\Omega} \times \vec{v} = -\frac{\vec{\nabla} p}{\rho} - \vec{\nabla}\Phi$$

$$M \frac{dI}{dt} = I - B$$

$$\frac{de^*}{dT} = \frac{\mathcal{L}_v e^*}{R_v T^2}$$



...but often challenging to explain

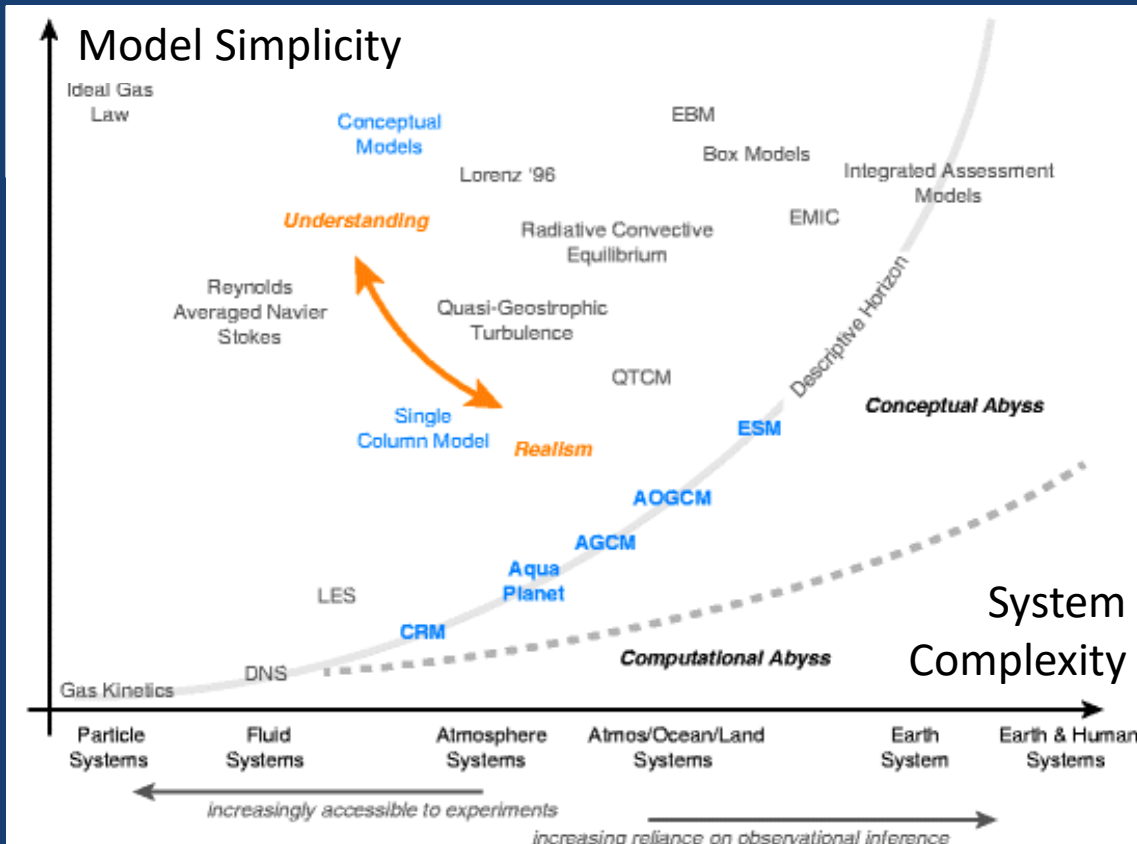
Source: Bordoni et al. (2025), Bony et al. (2013);  
See: Jeevanjee et al. (2017), Balaji (2022), ORNL (C. Jones, 2018)

$$\frac{D\vec{v}}{Dt} + 2\vec{\Omega} \times \vec{v} = -\frac{\vec{\nabla} p}{\rho} - \vec{\nabla}\Phi$$

$$\mu \frac{dI}{dT} = I - B$$

$$\frac{de^*}{dT} = \frac{\mathcal{L}_v e^*}{R_v T^2}$$

$$\int$$



1. Pareto-optimal model hierarchies
2. Knowledge distillation
3. Challenges

Source: Bony et al. (2013); See: Jeevanjee et al. (2017), Balaji (2022), ORNL (C. Jones, 2018)





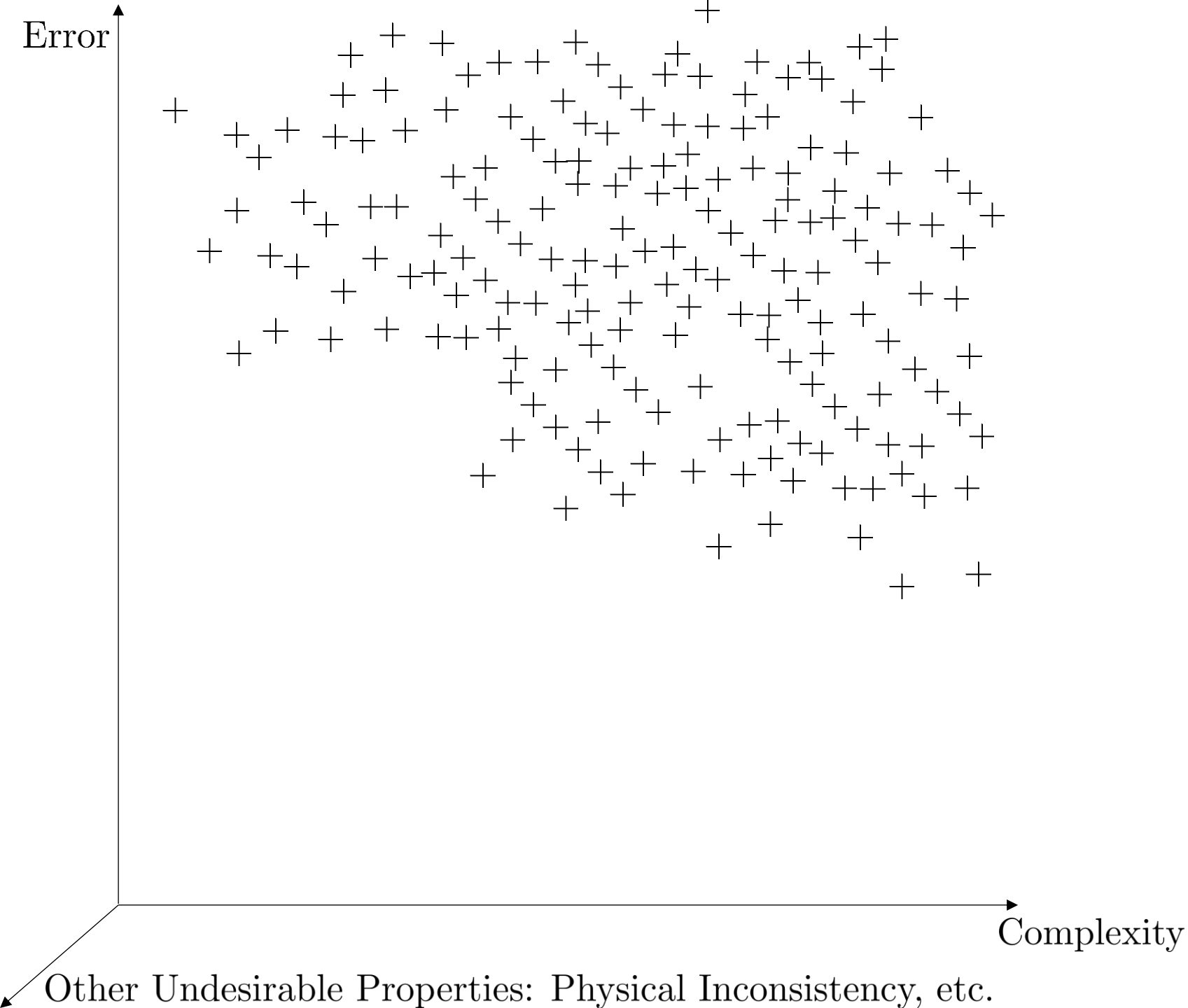
Idea: Work in a well-defined error-complexity plane



Model  
Error



Model Complexity



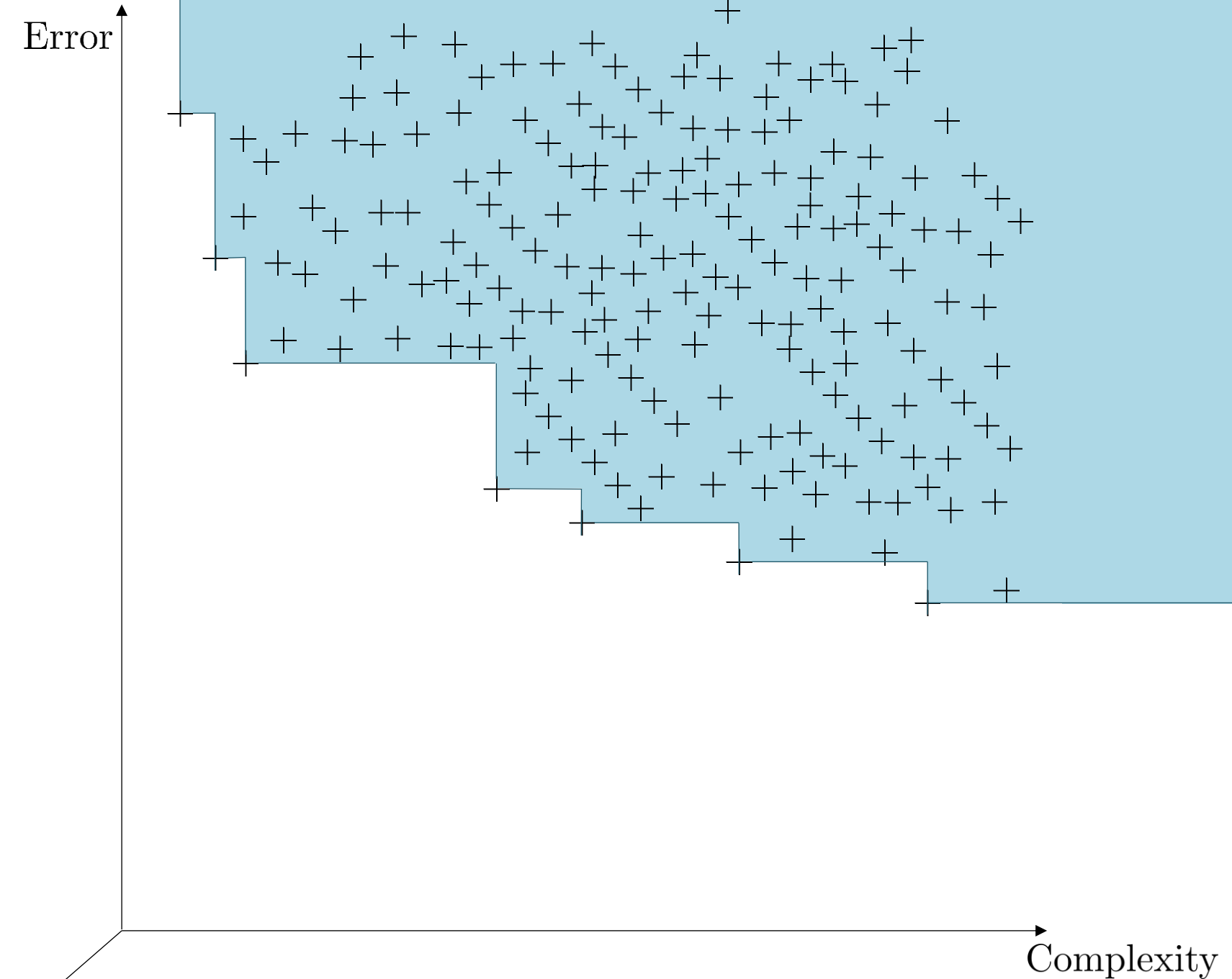
## Pareto Front:

“When selecting a model from the Pareto front, switching to a different model means sacrificing the quality of at least one evaluation metric.”

$$\text{PF}_{\mathcal{E}} = \left\{ M_{\text{opt}} \mid \nexists M \text{ s.t. } \begin{cases} \forall i \mathcal{E}_i(M) \leq \mathcal{E}_i(M_{\text{opt}}) \\ \exists j \mathcal{E}_j(M) < \mathcal{E}_j(M_{\text{opt}}) \end{cases} \right\}$$

*See: Censor (1977), Miettinen (1999)*





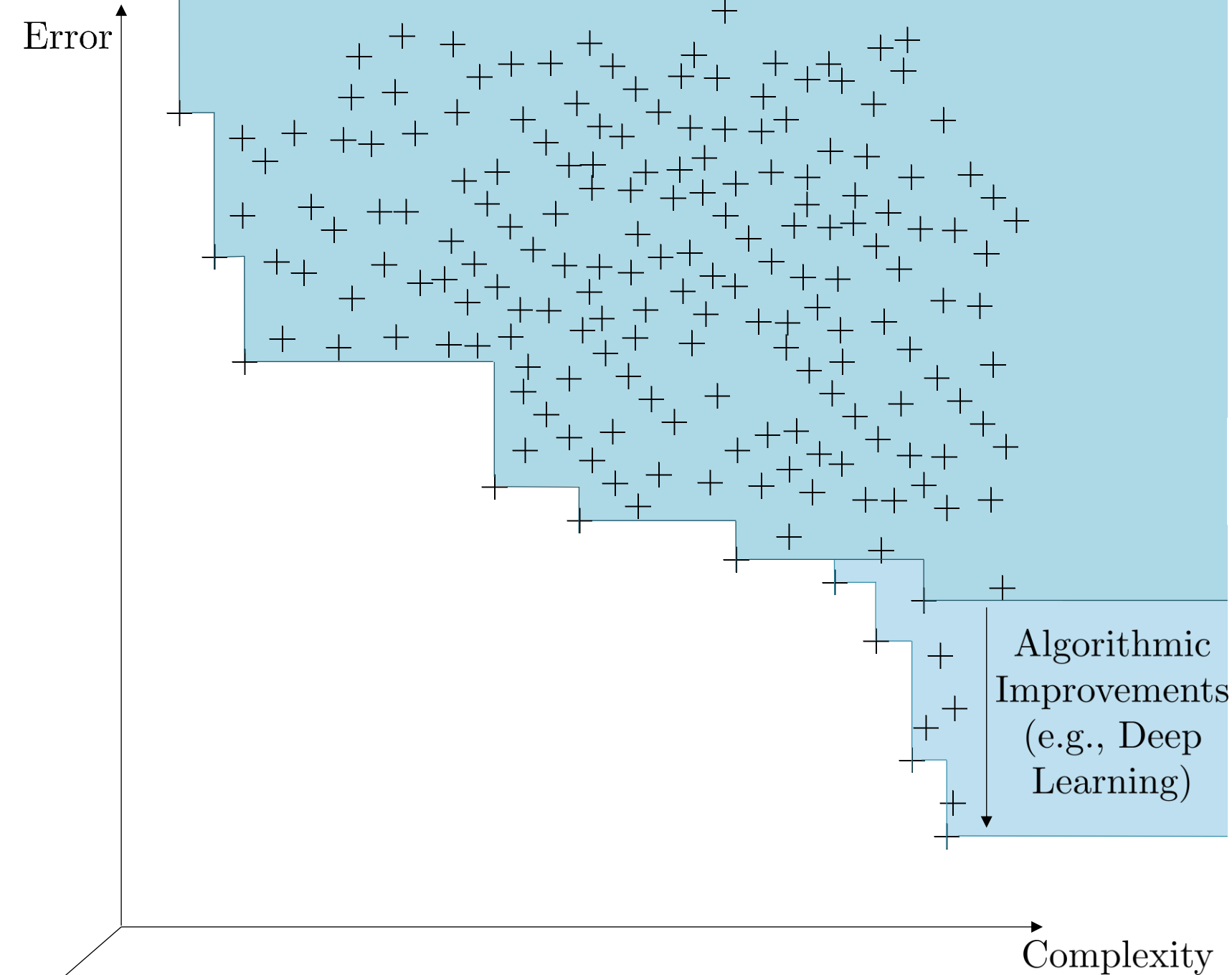
## Pareto Front:

“When selecting a model from the Pareto front, switching to a different model means sacrificing the quality of at least one evaluation metric.”

$$\text{PF}_{\mathcal{E}} = \left\{ M_{\text{opt}} \mid \nexists M \text{ s.t. } \begin{cases} \forall i \mathcal{E}_i(M) \leq \mathcal{E}_i(M_{\text{opt}}) \\ \exists j \mathcal{E}_j(M) < \mathcal{E}_j(M_{\text{opt}}) \end{cases} \right\}$$

Other Undesirable Properties: Physical Inconsistency, etc.

*See: Censor (1977), Miettinen (1999)*



## Pareto Front:

“When selecting a model from the Pareto front, switching to a different model means sacrificing the quality of at least one evaluation metric.”

$$\text{PF}_{\mathcal{E}} = \left\{ M_{\text{opt}} \mid \nexists M \text{ s.t. } \begin{cases} \forall i \mathcal{E}_i(M) \leq \mathcal{E}_i(M_{\text{opt}}) \\ \exists j \mathcal{E}_j(M) < \mathcal{E}_j(M_{\text{opt}}) \end{cases} \right\}$$

*See: Censor (1977), Miettinen (1999)*



$$\frac{D\vec{v}}{Dt} + 2\vec{\Omega} \times \vec{v} = -\frac{\vec{\nabla} p}{\rho} - \vec{\nabla} \Phi$$

$$\mu \frac{dI}{d\tau} = I - B$$

$$\frac{de^*}{dT} = \frac{\mathcal{L}_v e^*}{R_v T^2}$$

$$\int$$



$$Y = M \left[ X_{\vec{x}, t} \right]$$

$$\frac{D\vec{v}}{Dt} + 2\vec{\Omega} \times \vec{v} = -\frac{\vec{\nabla} p}{\rho} - \vec{\nabla} \Phi$$

$$\mu \frac{dI}{d\tau} = I - B$$

$$\frac{de^*}{dT} = \frac{\mathcal{L}_v e^*}{R_v T^2}$$

$$\int$$

←  
Data-Driven Discovery

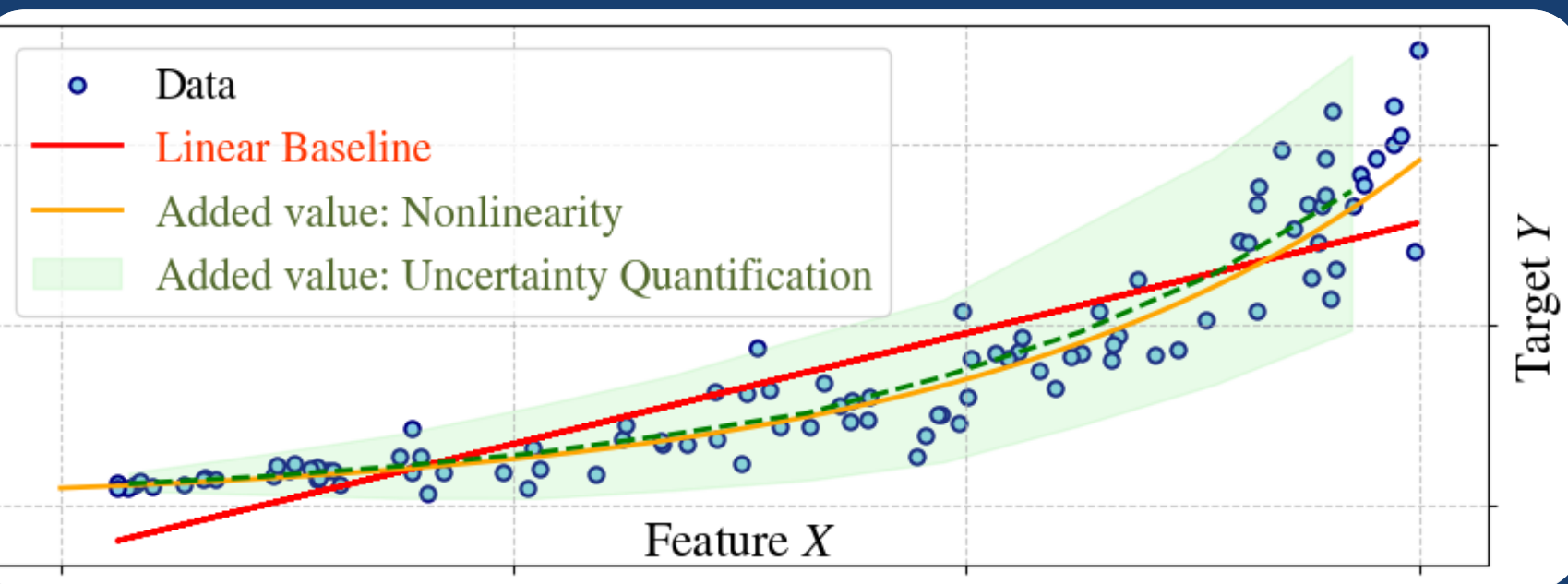


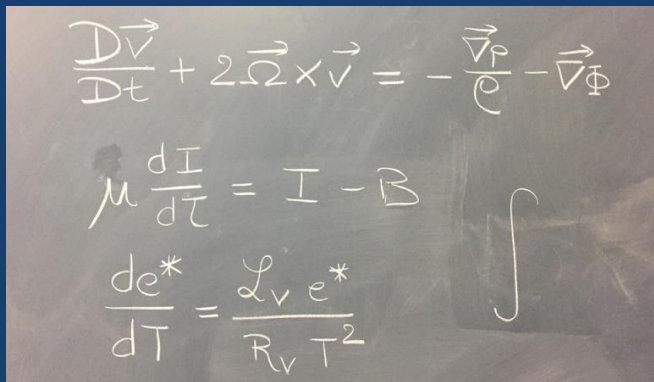
Distillable value:

1) Functional representation

$$Y = M \left[ X_{\vec{x}, t} \right]$$

↑





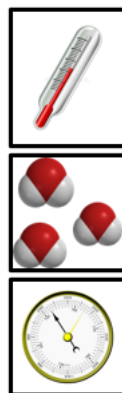
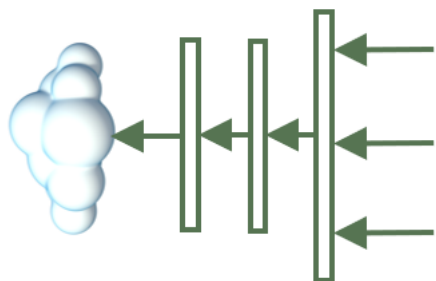
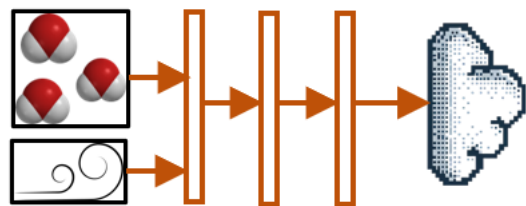
Distillable value:

1) Functional representation

2) Feature assimilation

$$Y = M \left[ X_{\vec{x}, t} \right]$$

Baseline  
Set of  
Features



Added Value:  
Improved Model  
via a  
New Feature Set



$$\frac{D\vec{v}}{Dt} + 2\vec{\Omega} \times \vec{v} = -\frac{\vec{\nabla} p}{\rho} - \vec{\nabla} \Phi$$

$$\mu \frac{dI}{dT} = I - B$$

$$\frac{de^*}{dT} = \frac{\mathcal{L}_v e^*}{R_v T^2}$$

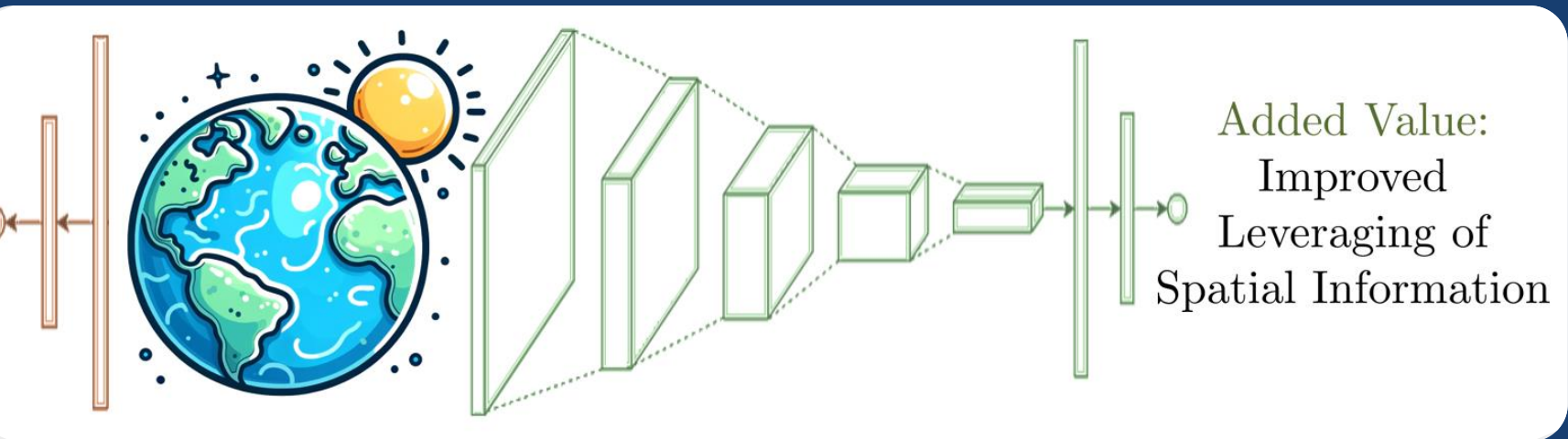
$$\int$$



Distillable value:

- 1) Functional representation
- 2) Feature assimilation
- 3) Spatial connectivity

$$Y = M \left[ X_{\vec{x}, t} \right]$$



$$\frac{D\vec{v}}{Dt} + 2\vec{\Omega} \times \vec{v} = -\frac{\vec{\nabla} p}{\rho} - \vec{\nabla} \Phi$$

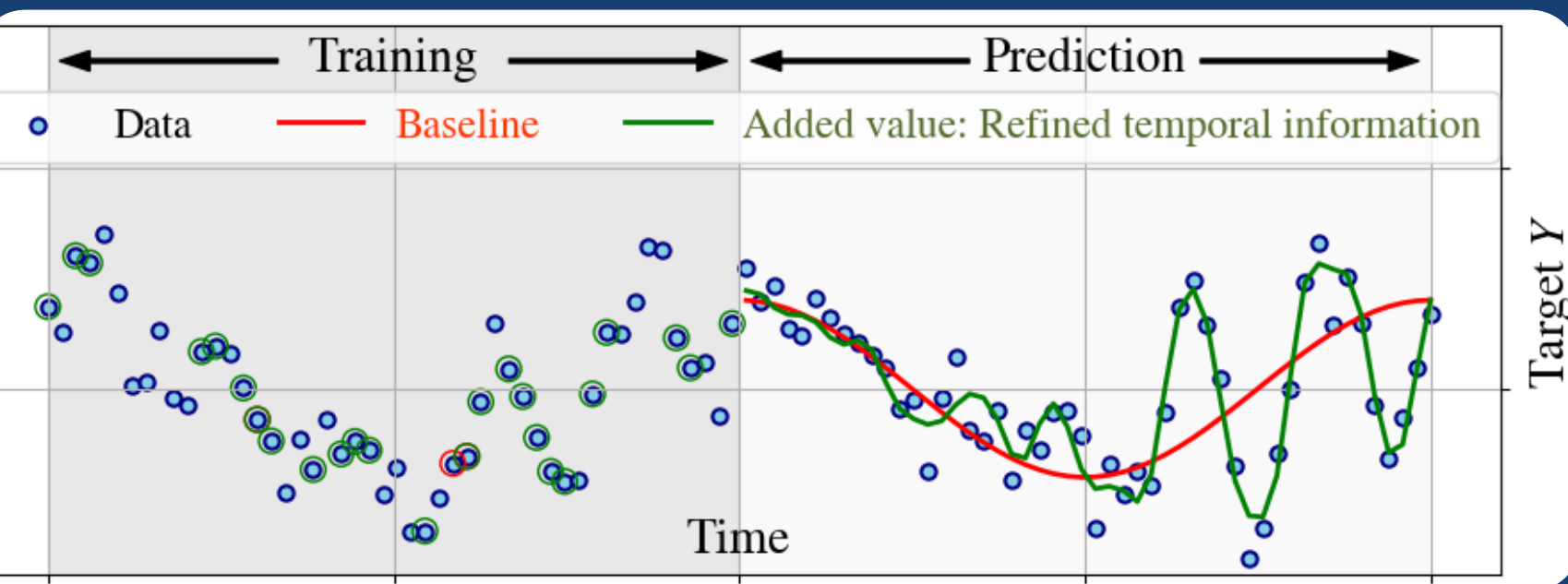
$$\mu \frac{dI}{dT} = I - B$$

$$\frac{de^*}{dT} = \frac{\mathcal{L}_v e^*}{R_v T^2}$$

$$\int$$

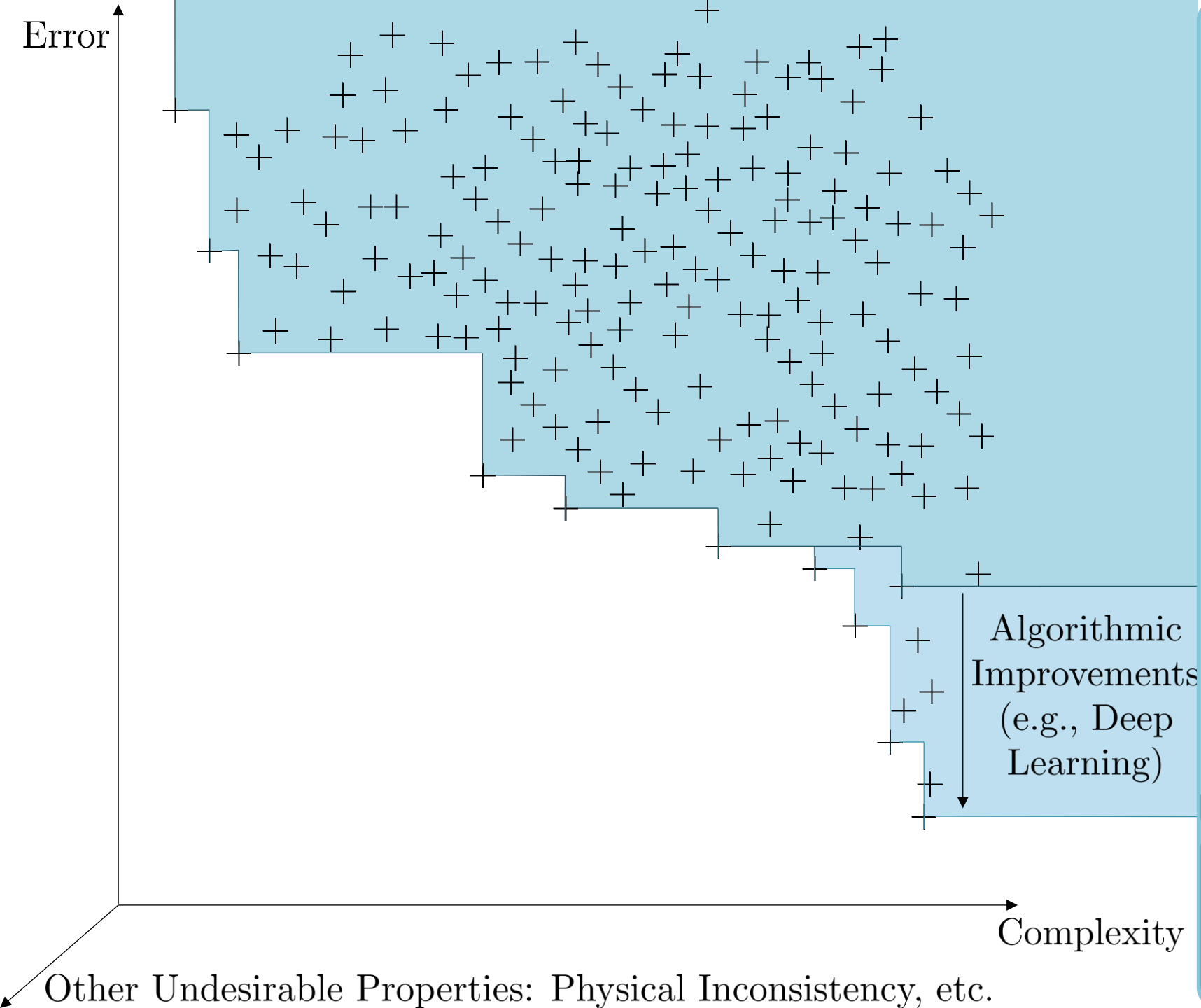


$$Y = M \left[ X_{\vec{x}, t} \right]$$



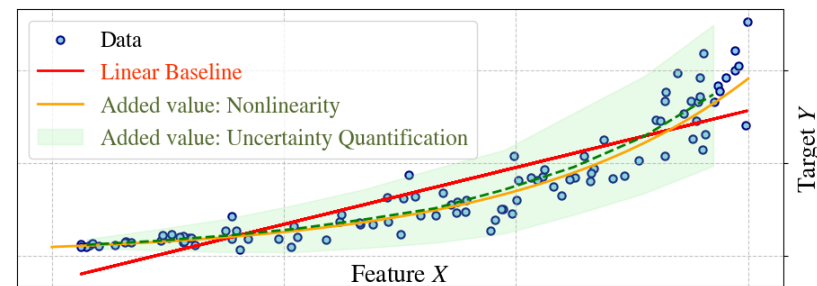
Distillable value:

- 1) Functional representation
- 2) Feature assimilation
- 3) Spatial connectivity
- 4) Temporal connectivity

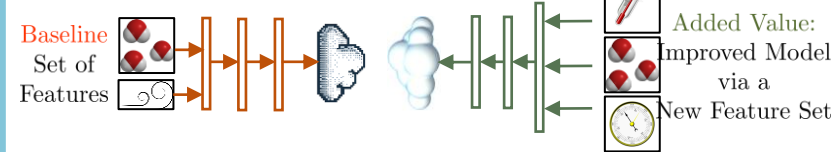


Distillable value:

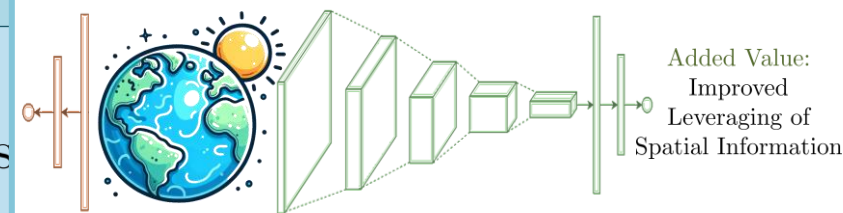
## 1) Functional Representation



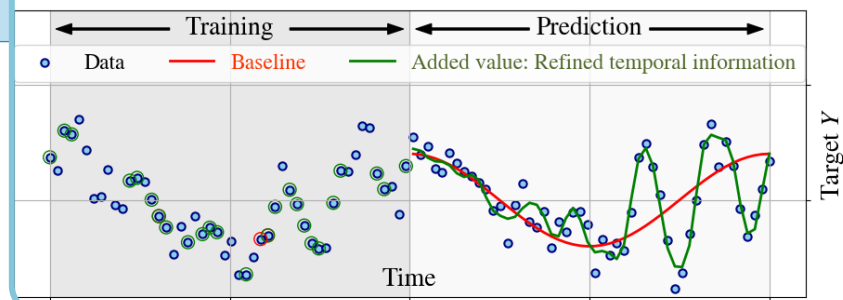
## 2) Feature Assimilation



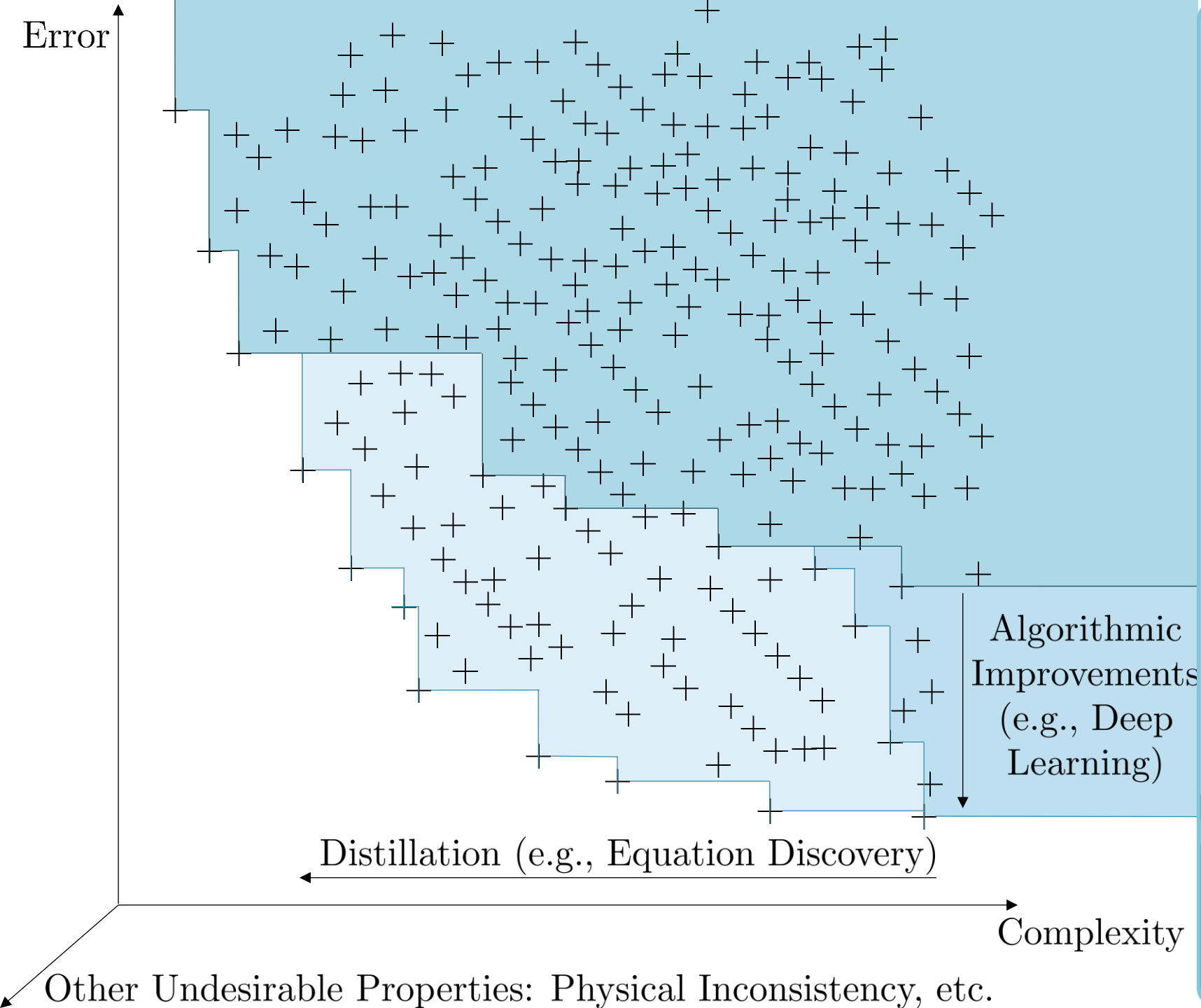
## 3) Spatial Connectivity



## 4) Temporal Connectivity

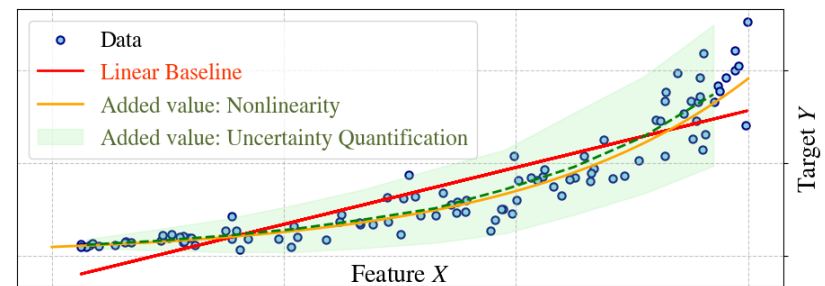




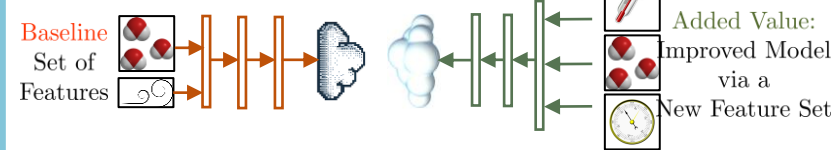


Distillable value:

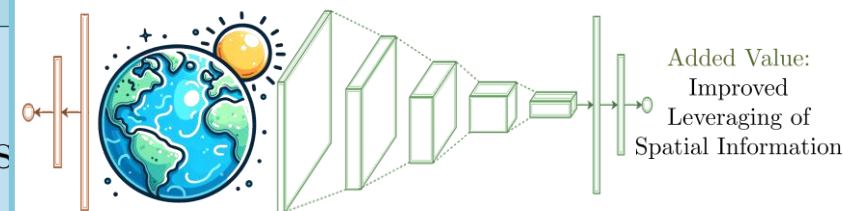
## 1) Functional Representation



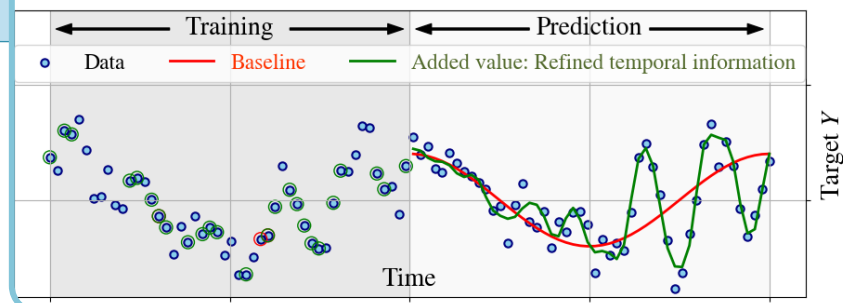
## 2) Feature Assimilation



## 3) Spatial Connectivity



## 4) Temporal Connectivity



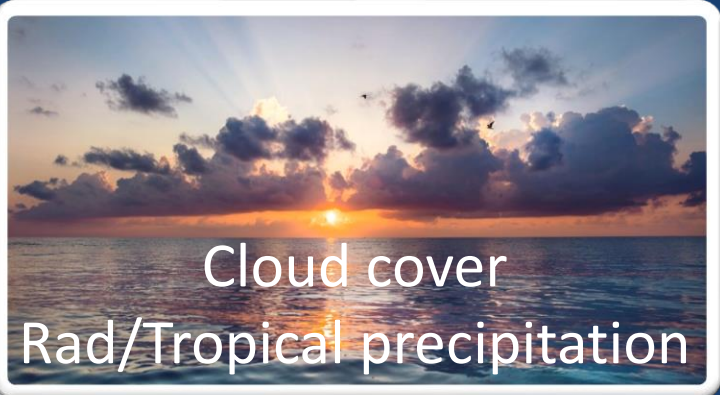
$$\frac{D\vec{v}}{Dt} + 2\vec{\Omega} \times \vec{v} = -\frac{\vec{\nabla} p}{\rho} - \vec{\nabla} \Phi$$

$$\mu \frac{dI}{dT} = I - B$$

$$\frac{de^*}{dT} = \frac{\mathcal{L}_v e^*}{R_v T^2}$$



1. Pareto-optimal model hierarchies
2. Knowledge distillation
3. Challenges



### Distillable value:

- 1) Functional Representation
- 2) Feature Assimilation
 

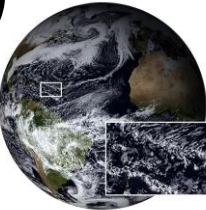
Added Value: Improved Model via a New Feature Set
- 3) Spatial Connectivity
 

Added Value: Improved Leveraging of Spatial Information
- 4) Temporal Connectivity

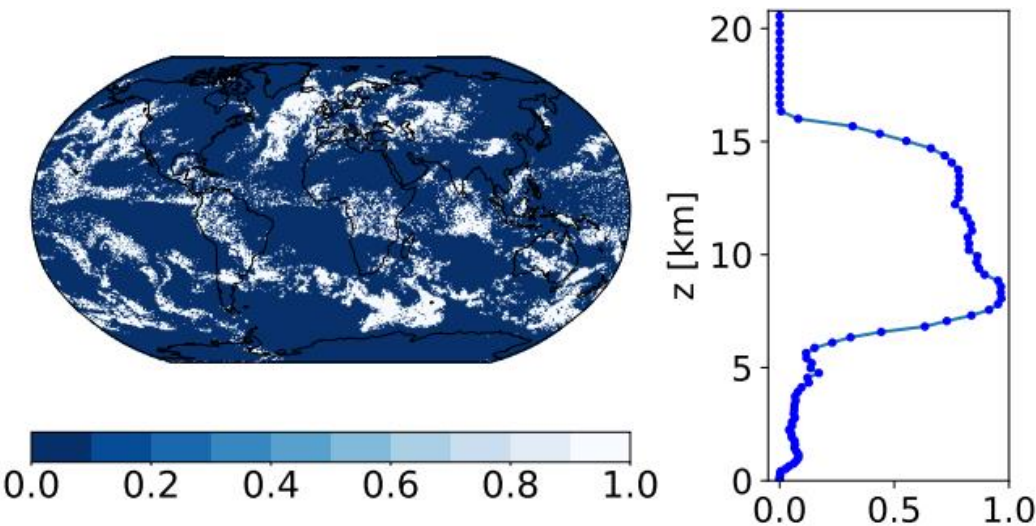
# Cloud cover parameterization maps the grid-scale environment to the fraction occupied by clouds

Motivation: Reducing cloud-related biases via storm-resolving simulations

Data: 2.5km-res, 59-layer, global storm-resolving ICON runs (DYAMOND)



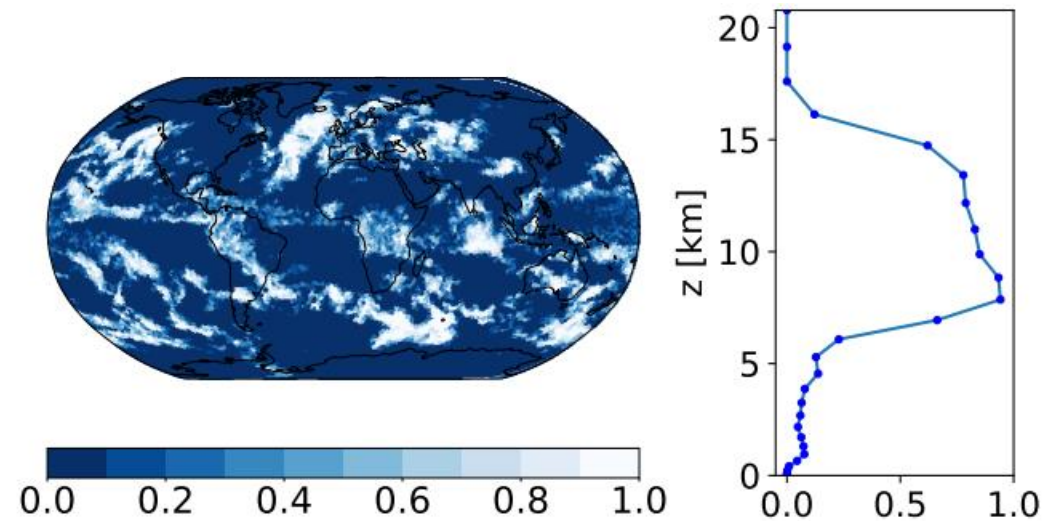
Original Cloud Cover



Coarse  
Graining



80km-res “High-fidelity” Cl. Cov.

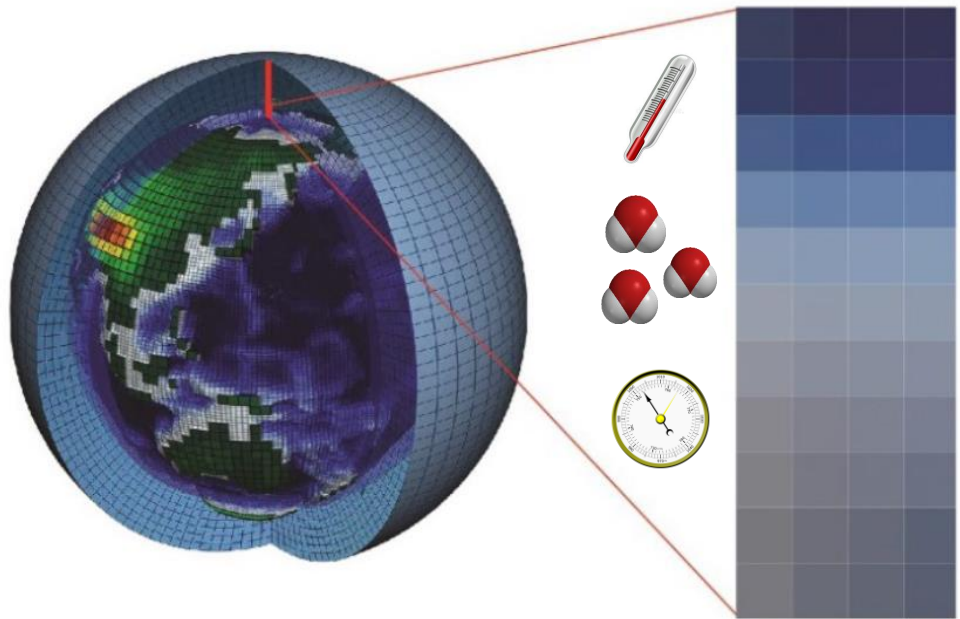


Source: Grundner, Beucler et al. (2022), Giorgetta et al. (2022), Stevens et al. (2019)



# Cloud cover parameterization maps the grid-scale environment to the fraction occupied by clouds

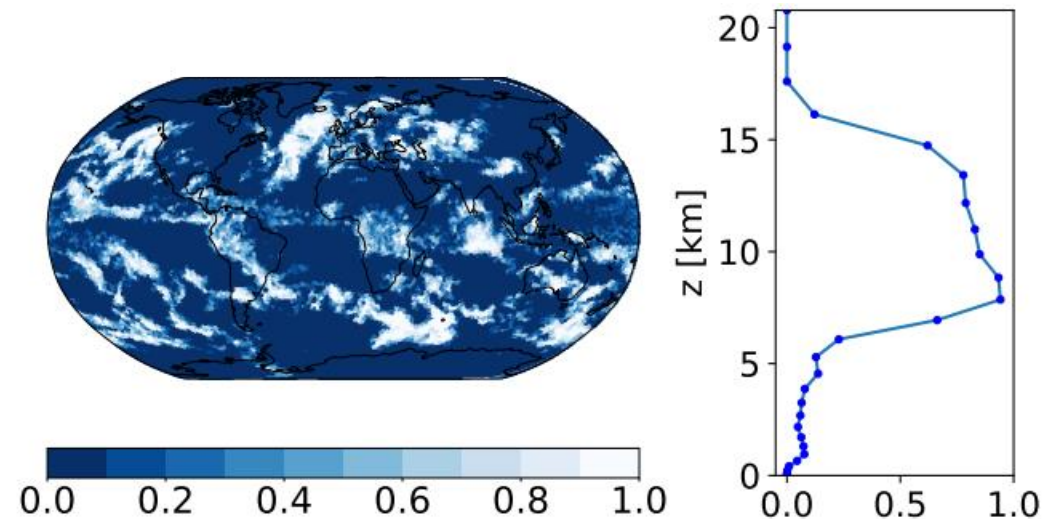
80km-res Coarse Environment



Goal

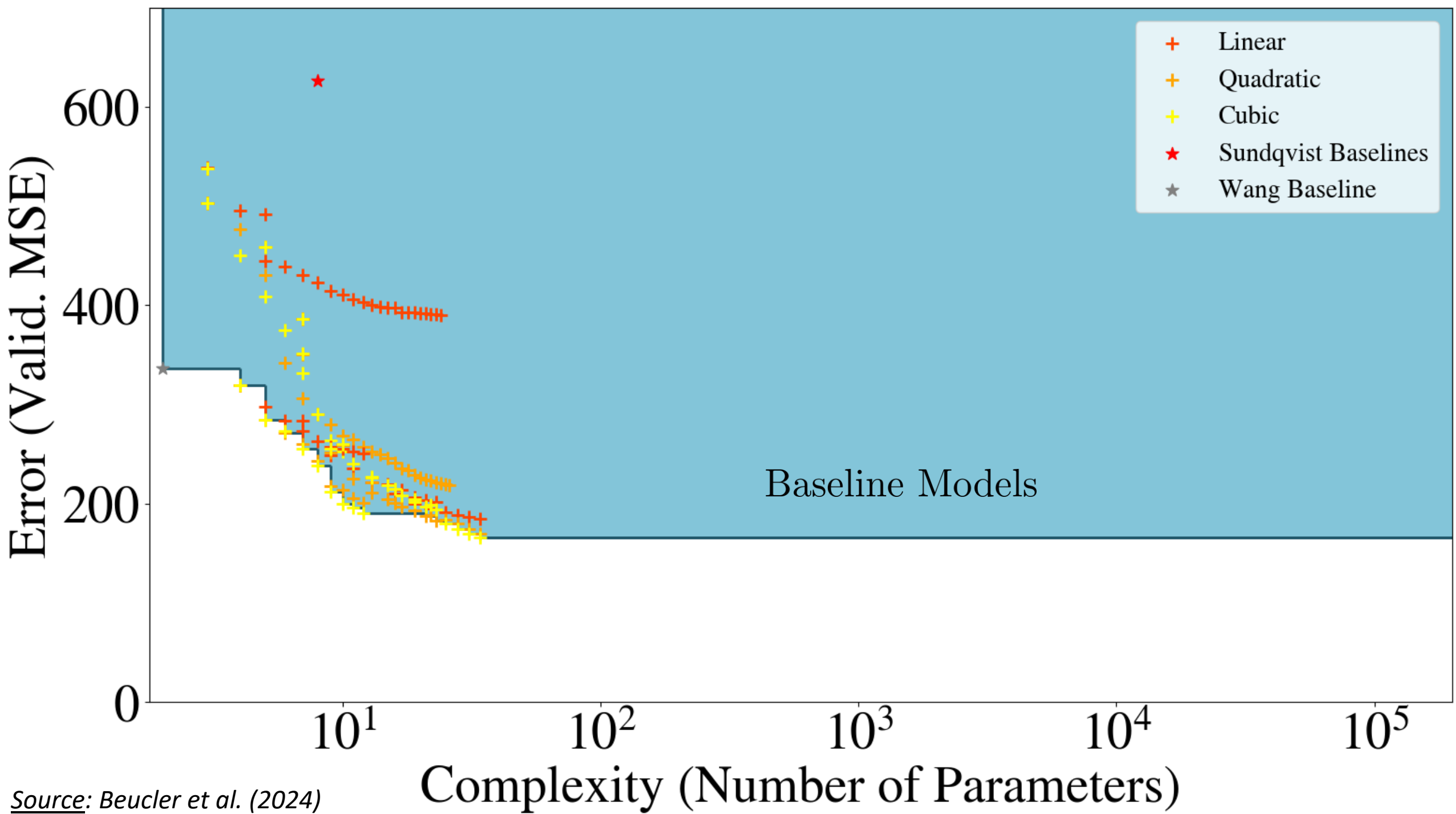


80km-res “High-fidelity” Cl. Cov.





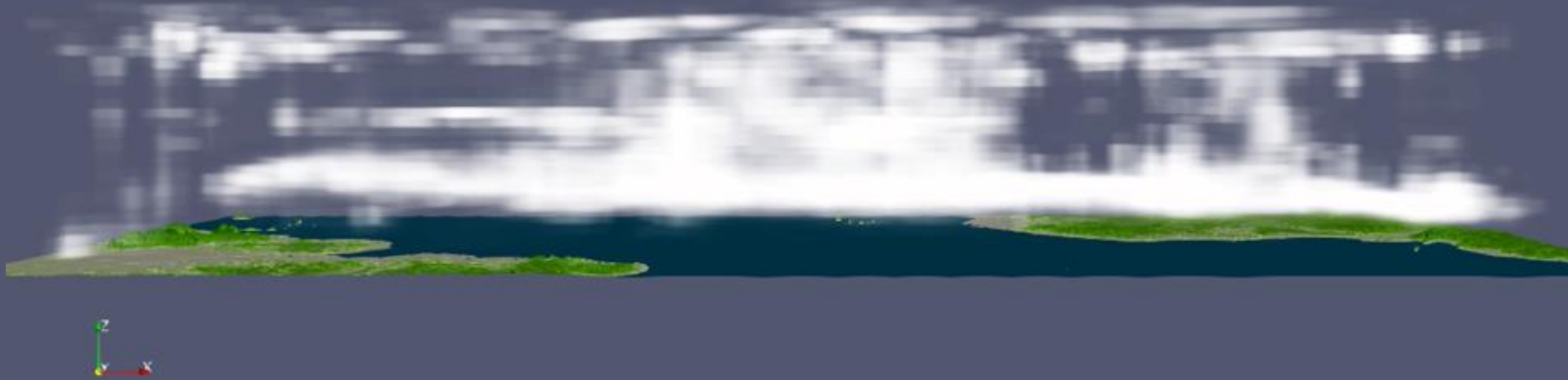
Movie from: Monsoon IV (Olbinski, 2017)





# Neural Nets achieve root-mean squared errors $< 7\%$

Neural Network  
Estimate



Reference  
(Coarse-Grained  
High-resolution  
simulation)



*Source: Grundner, Beucler et al. (2022)*



# And guide the discovery of new equations for cloud cover

## Example of **transparent machine learning**...

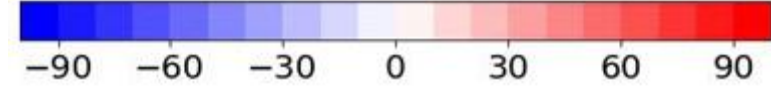
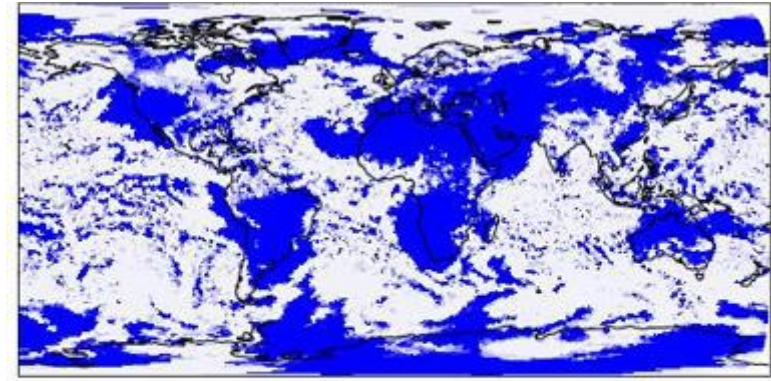
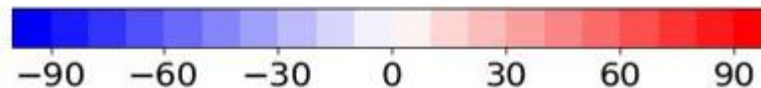
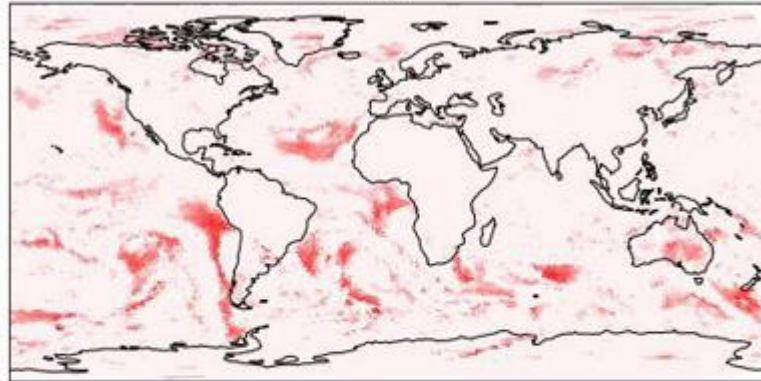
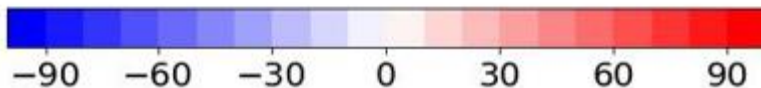
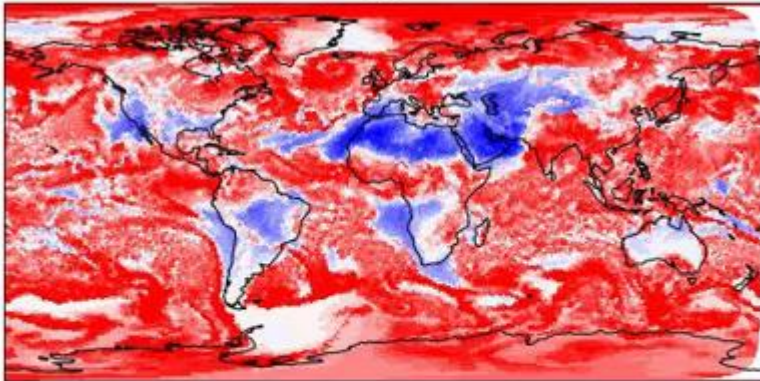


$$C_{\text{PySR}} = \underbrace{\mathcal{I}_1(\text{RH}, T)}_{\text{Humidity/Temperature}} + \underbrace{\mathcal{I}_2\left(\frac{d\text{RH}}{dz}\right)}_{\text{Inversion}} + \underbrace{\mathcal{I}_3(q_\ell, q_i)}_{\text{Condensates}}$$

$$\begin{aligned} \mathcal{I}_1 = & \bar{C} + \left(\frac{\partial C}{\partial \text{RH}}\right)_{\bar{\text{RH}}, \bar{T}} (\text{RH} - \bar{\text{RH}}) - \left(\frac{\partial C}{\partial T}\right)_{\bar{\text{RH}}, \bar{T}} (T - \bar{T}) \\ & + \frac{1}{2} \left(\frac{\partial^2 C}{\partial \text{RH}^2}\right)_{\bar{\text{RH}}, \bar{T}} (\text{RH} - \bar{\text{RH}})^2 \\ & + \frac{1}{2} \left(\frac{\partial C}{\partial \text{RH} \partial T^2}\right)_{\bar{\text{RH}}, \bar{T}} (T - \bar{T})^2 (\text{RH} - \bar{\text{RH}}). \end{aligned}$$

$$\mathcal{I}_2 = H_{\text{PySR}}^3 \left[ \frac{d\text{RH}}{dz} + \frac{3}{2} \left( \frac{d\text{RH}}{dz} \right)_{\max C} \right] \left( \frac{d\text{RH}}{dz} \right)^2$$

$$\mathcal{I}_3 = -\frac{1}{\epsilon_{\text{PySR}}} \times \frac{1}{1 + 2\epsilon_{\text{PySR}} (\lambda_\ell q_\ell + \lambda_i q_i)}$$

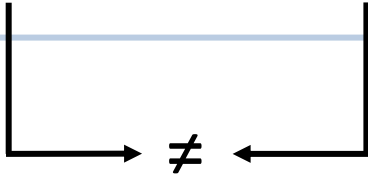


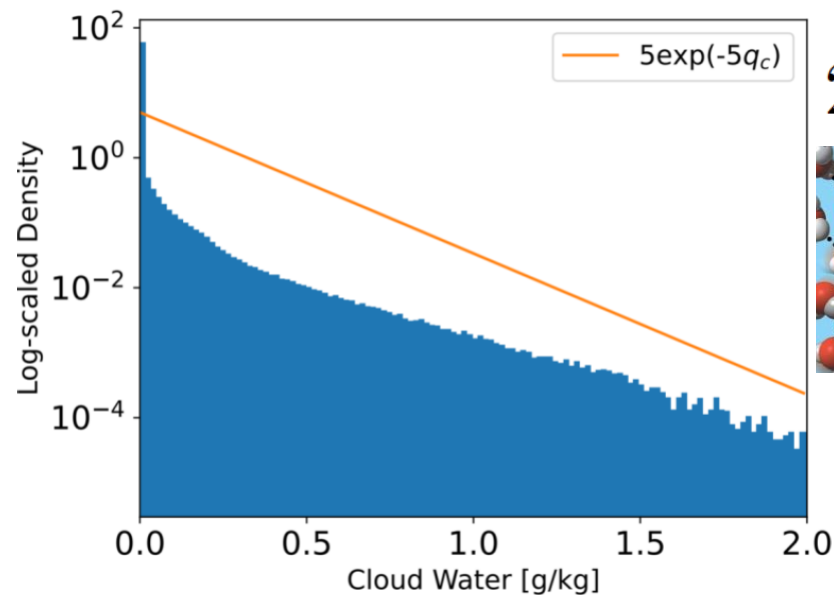
Source: Grundner, Beucler et al. (2024); Video source: PySR (2025)



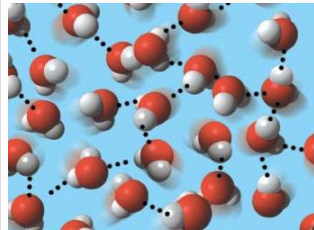
Unexpected discovery: The faster the subgrid distribution tends  $\rightarrow 0$ ,  
the more sensitive cloud cover is to cloud water concentration

$$I_3(q_c, q_i) \stackrel{\text{def}}{=} \frac{-1}{q_c/a_8 + q_i/a_9 + \epsilon}$$

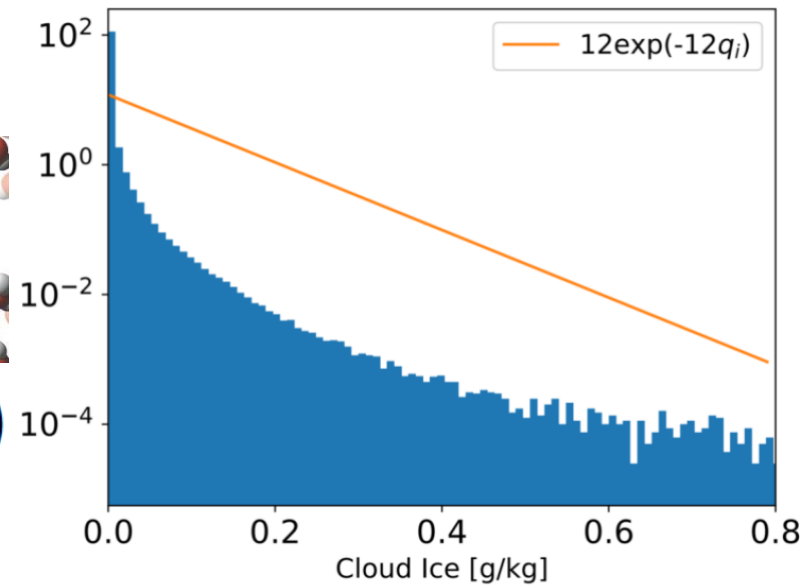
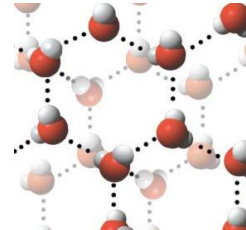




$$2\lambda_l \approx 1/(a_8\epsilon^2)$$



$$2\lambda_i \approx 1/(a_9\epsilon^2)$$



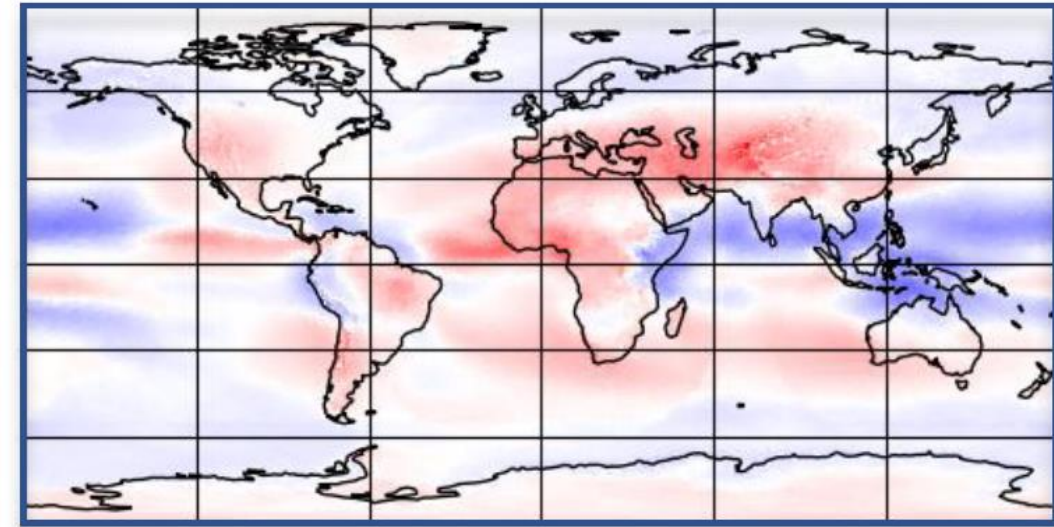
Source: Grundner et al. (2024), 2013 Pearson Ed.



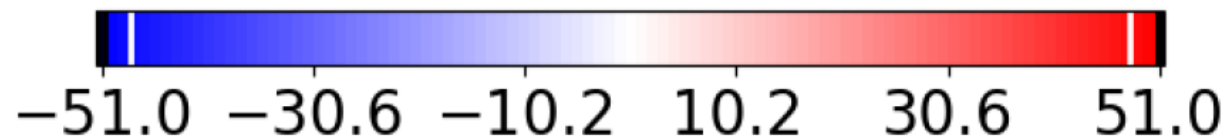
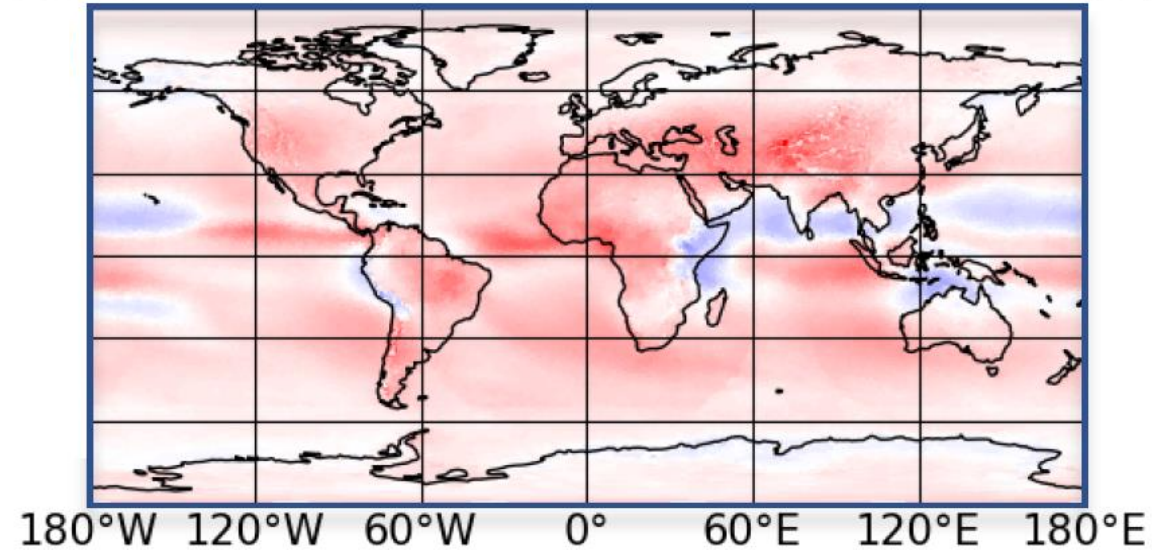
# Example of **transparent ML** that reduces biases of the resulting atmospheric simulation (below: outgoing TOA LW fluxes)

$$C_{\text{PySR}} = \underbrace{\mathcal{I}_1(\text{RH}, T)}_{\text{Humidity/Temperature}} + \underbrace{\mathcal{I}_2\left(\frac{d\text{RH}}{dz}\right)}_{\text{Inversion}} + \underbrace{\mathcal{I}_3(q_\ell, q_i)}_{\text{Condensates}}$$

ICON-ML - OBS (RMSE = 8.37 W/m<sup>2</sup>)

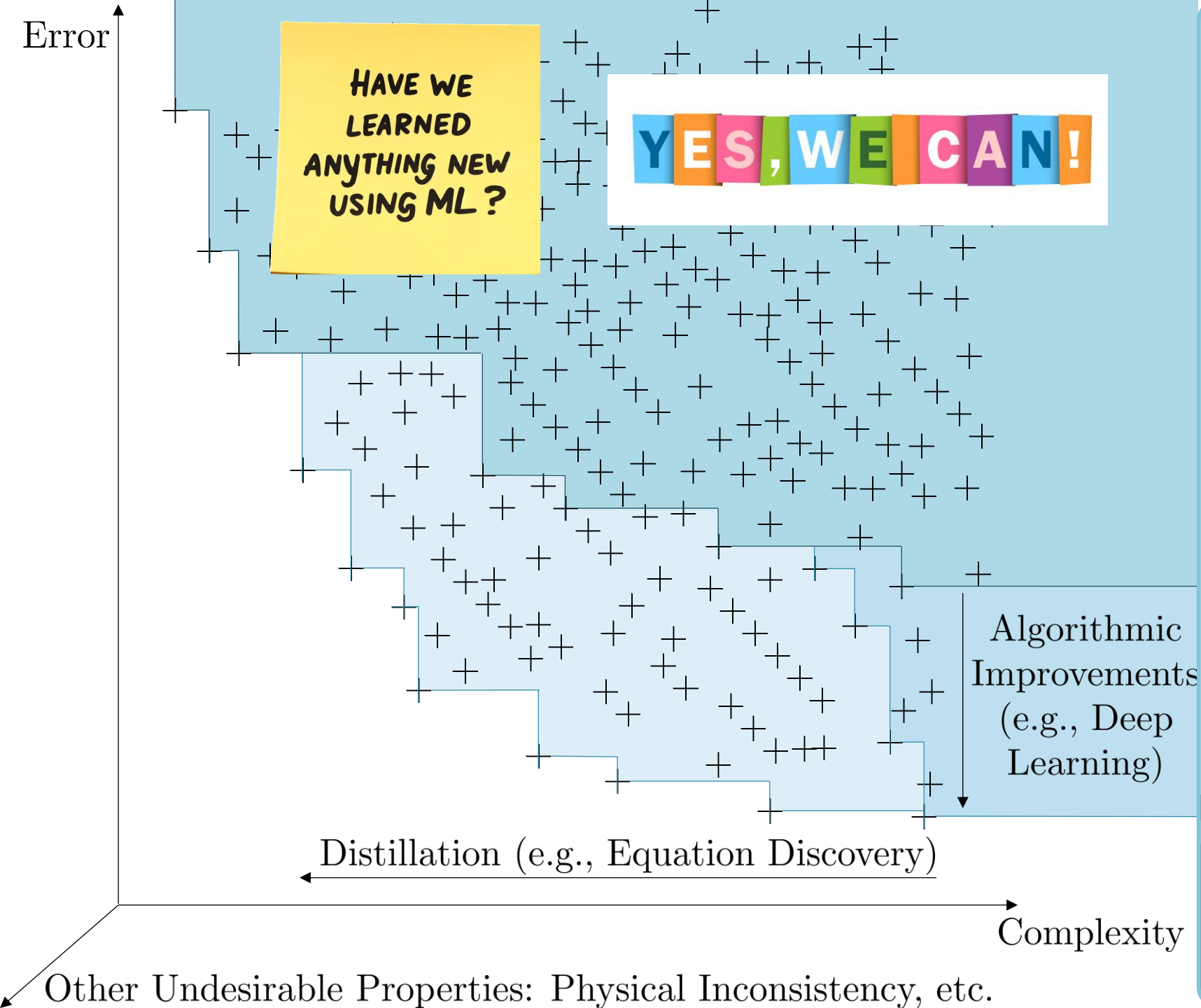


ICON-A (mt.) - OBS (RMSE = 10.03 W/m<sup>2</sup>)



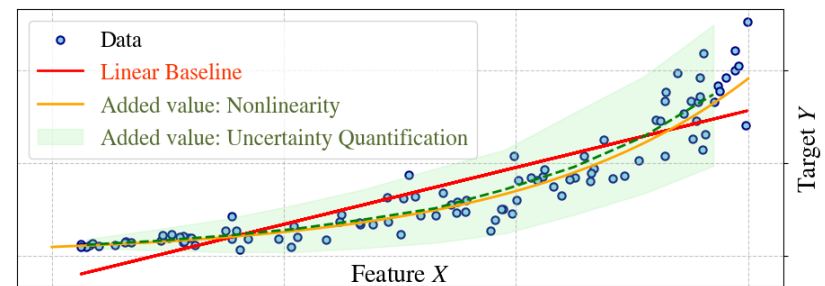
*Source: Grundner, Beucler, ... & Eyring (Submitted, Preprint coming soon)*



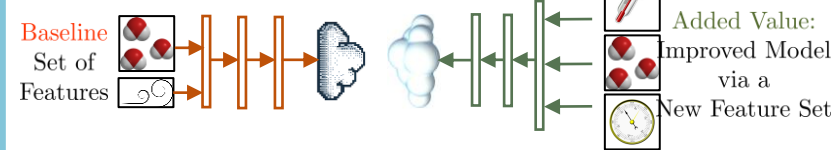


Distillable value:

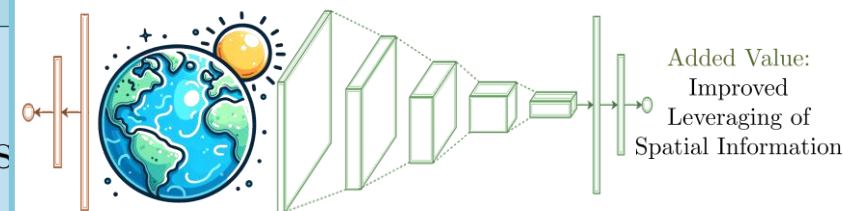
## 1) Functional Representation



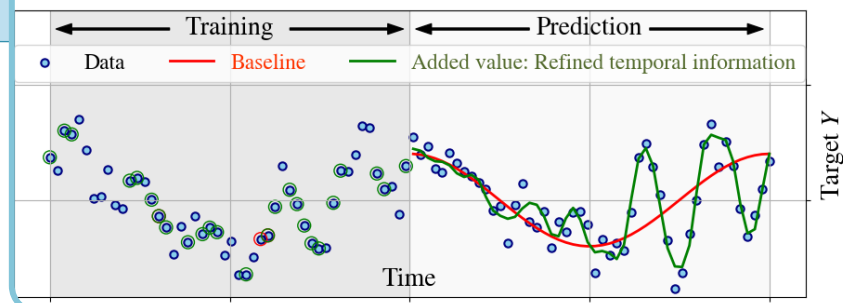
## 2) Feature Assimilation



## 3) Spatial Connectivity




## 4) Temporal Connectivity



## Group activity:

- 1) Form groups of approximately 5 people.
  - 2) For 15 minutes, discuss and propose equations or conceptual solutions to:
    - How can we make hybrid climate–AI models more reliable for climate change projections? Think of the key outcomes we ultimately care about?
    - How can AI help advance our understanding of the climate system?
- Next 15 min: Each group presents a 1-minute summary of their ideas on the board.

A photograph of a sunset over the ocean. The sun is low on the horizon, creating a bright orange glow and reflecting on the water. The sky is filled with dark, dramatic clouds. Two yellow sticky notes are overlaid on the image, one on the left and one on the right.

**IS ML  
RELIABLE  
FOR  
CLIMATE  
PROJECTIONS?**

**HAVE WE  
LEARNED  
ANYTHING NEW  
USING ML?**



# ...but remain under-used in climate science

$$C_{\text{frac}} = \text{ML} (p, q_v, q_l, q_i, T)$$

Cloud Fraction  
Parameterization  
(Grundner et al., 2024)

Subgrid-Scale Thermodynamics  
Parameterization  
(Beucler et al., 2024)

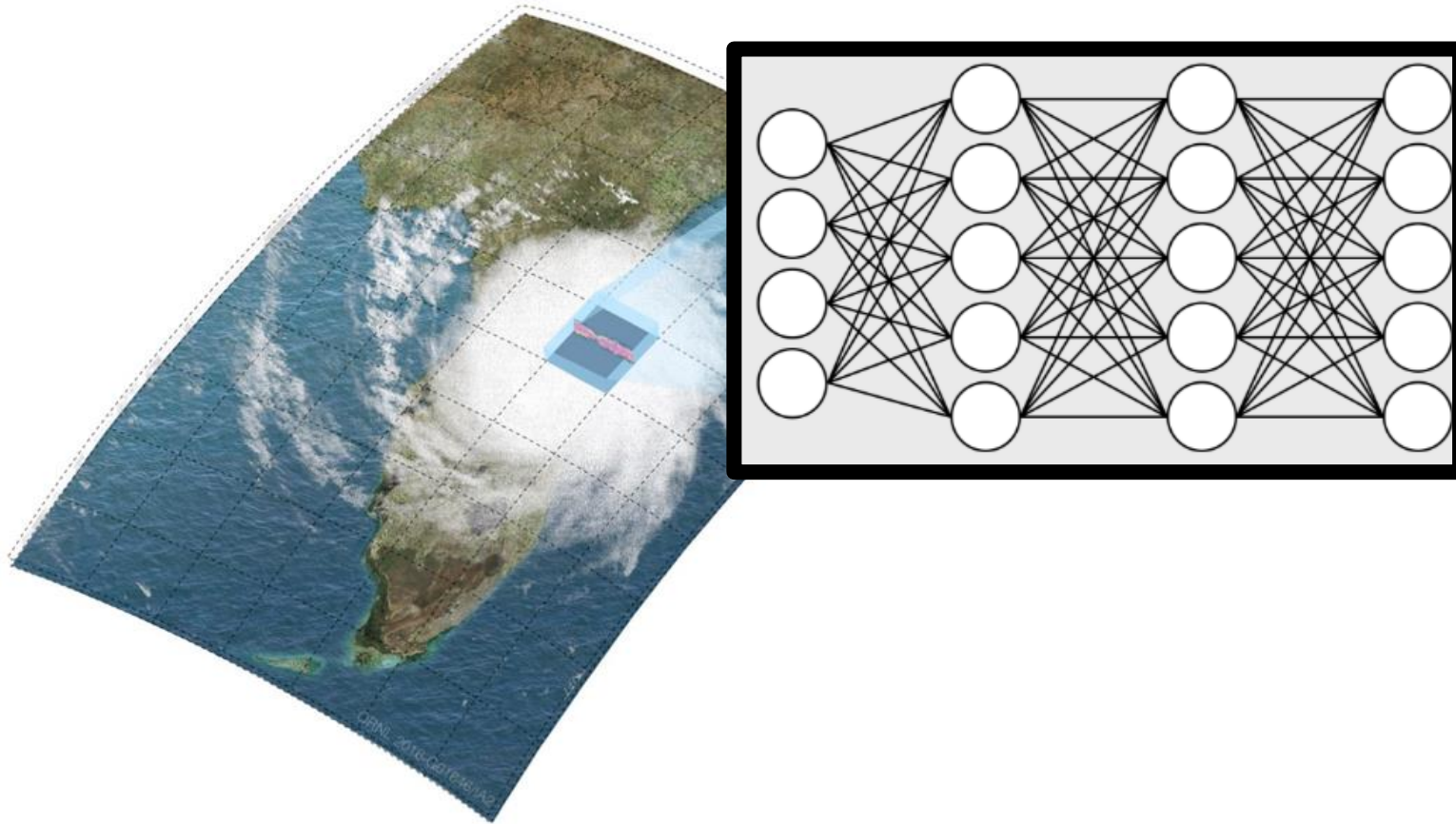
$$\begin{pmatrix} \dot{T} \\ \dot{q} \end{pmatrix} = \text{ML} (p, q_v, T, \text{LHF}, \text{SHF}, S_0)$$

IS ML  
RELIABLE  
FOR  
CLIMATE  
PROJECTIONS?

HAVE WE  
LEARNED  
ANYTHING NEW  
USING ML?



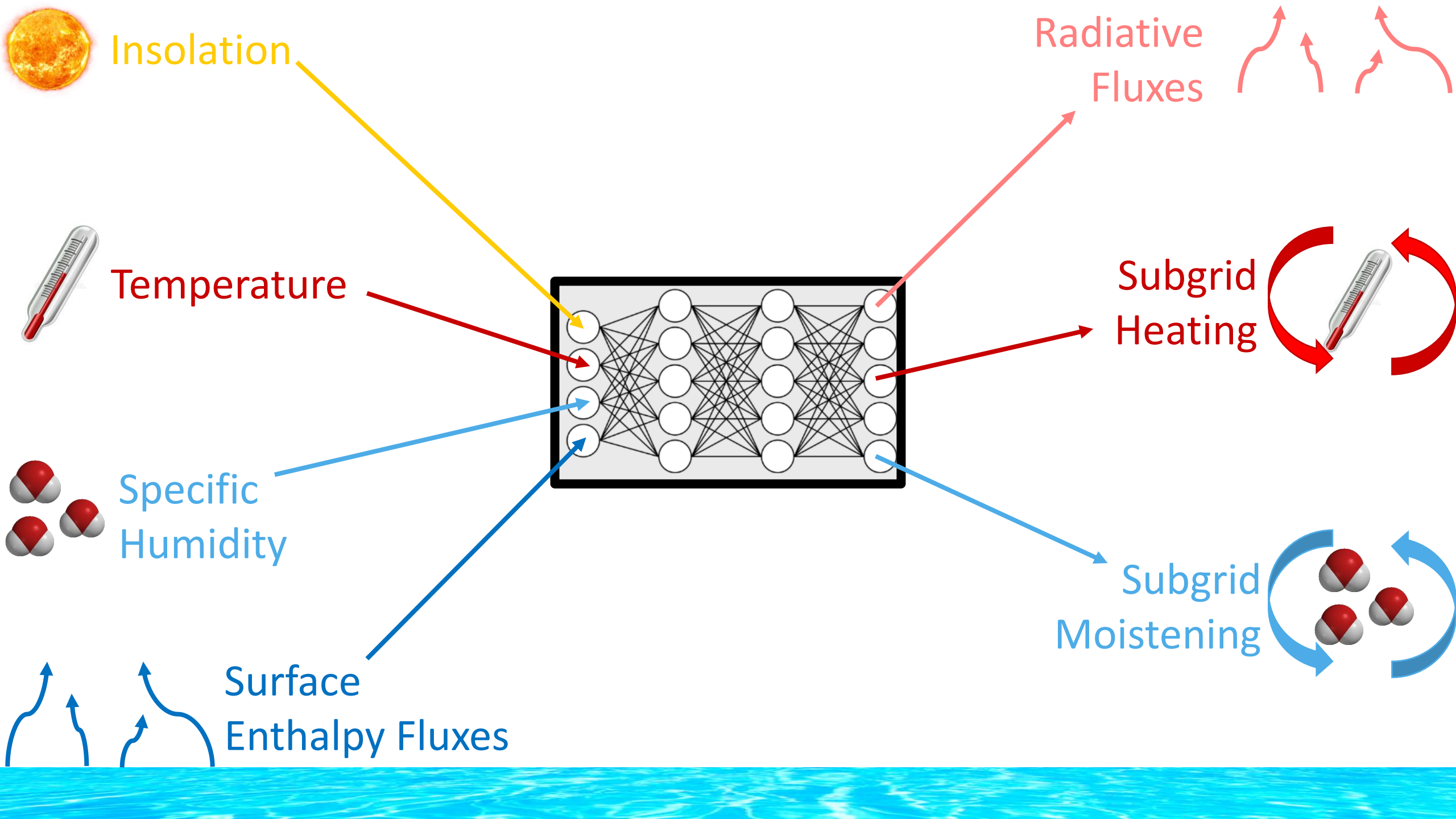
# Improving the representation of subgrid-scale thermodynamics in CAM



Once trained, neural networks accelerate the simulation 20x

Setup: Super-Parameterized Community Atmosphere Model v3.0

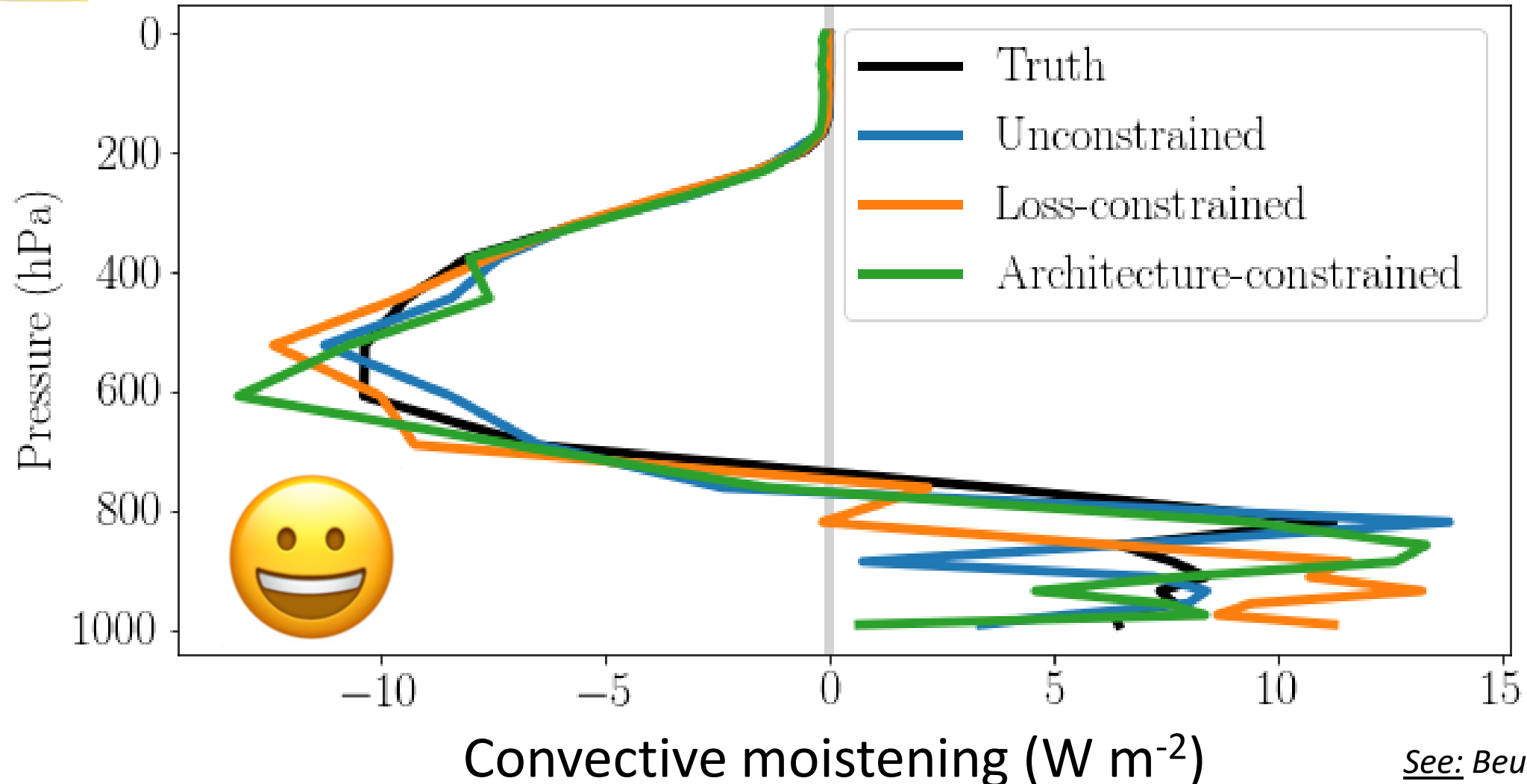
*Image source: [e3sm.org](http://e3sm.org), Model source: Khairoutdinov et al. (2004)*



# Problem: Neural Nets often fail to generalize out-of-distribution

IS ML  
RELIABLE  
FOR  
CLIMATE  
PROJECTIONS?

## Daily-mean Tropical prediction in reference climate



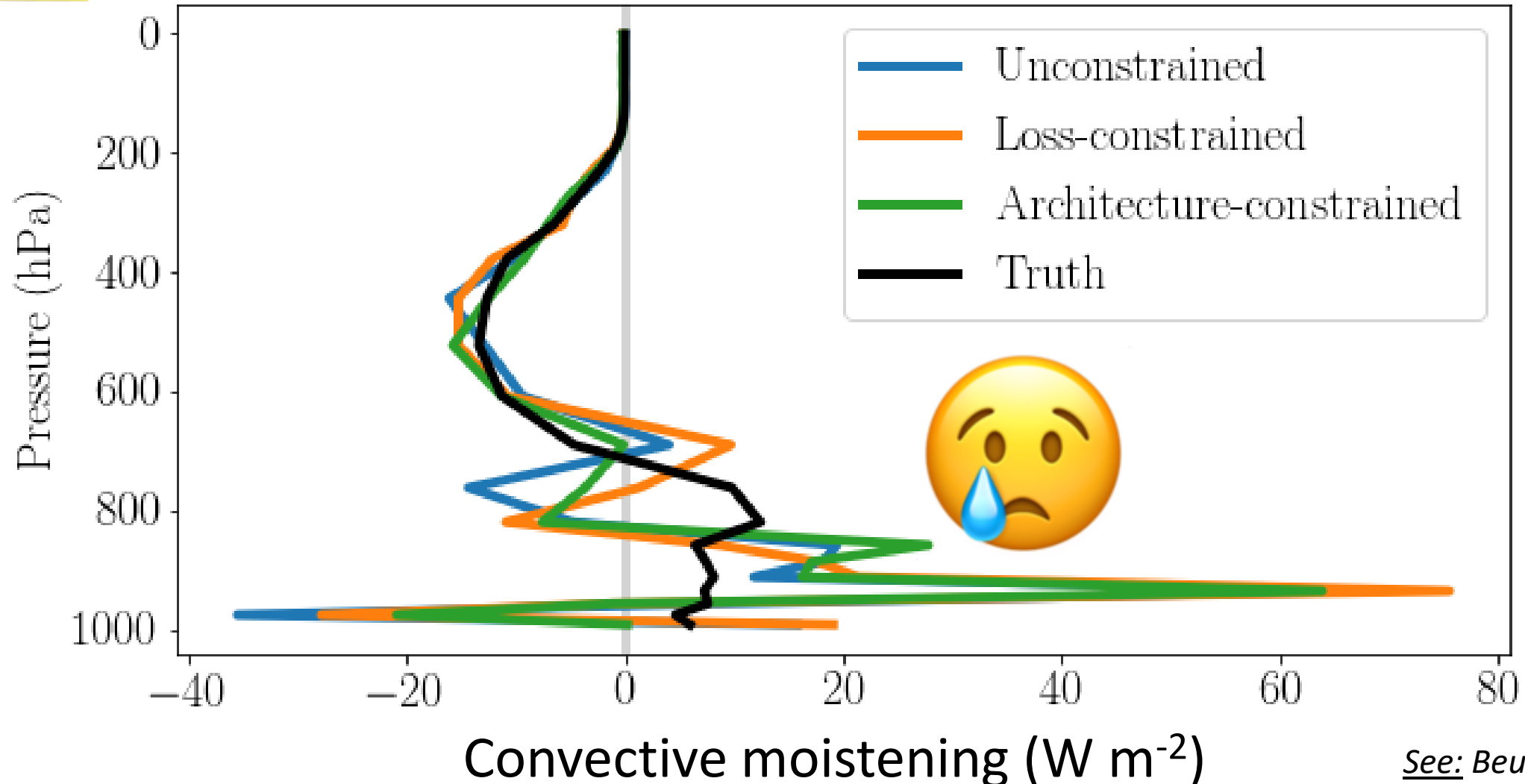
See: Beucler et al. (2020)



# Problem: Neural Nets often fail to generalize out-of-distribution

IS ML  
RELIABLE  
FOR  
CLIMATE  
PROJECTIONS?

## Daily-mean Tropical prediction in (+4K) warming experiment





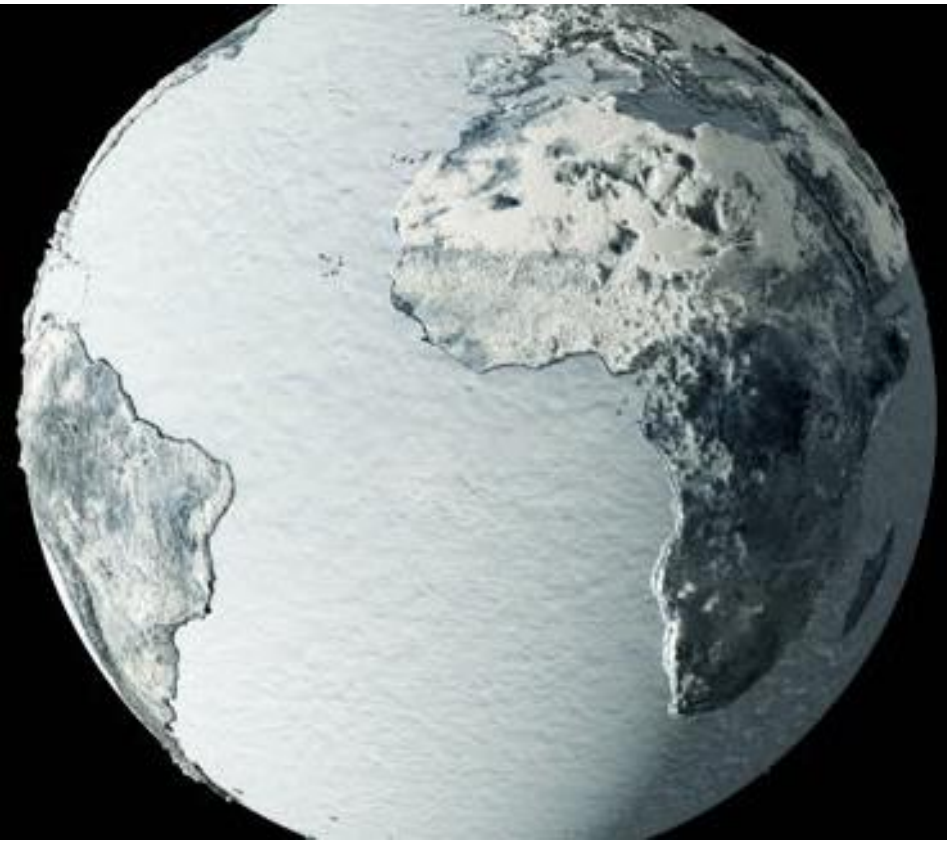
# Idea: Break the model even more!



Image source: IT Biz Advisor

# Generalization Experiment: +8K surface warming

Training and Validation on  
cold simulations



+8K



Test on warm simulations

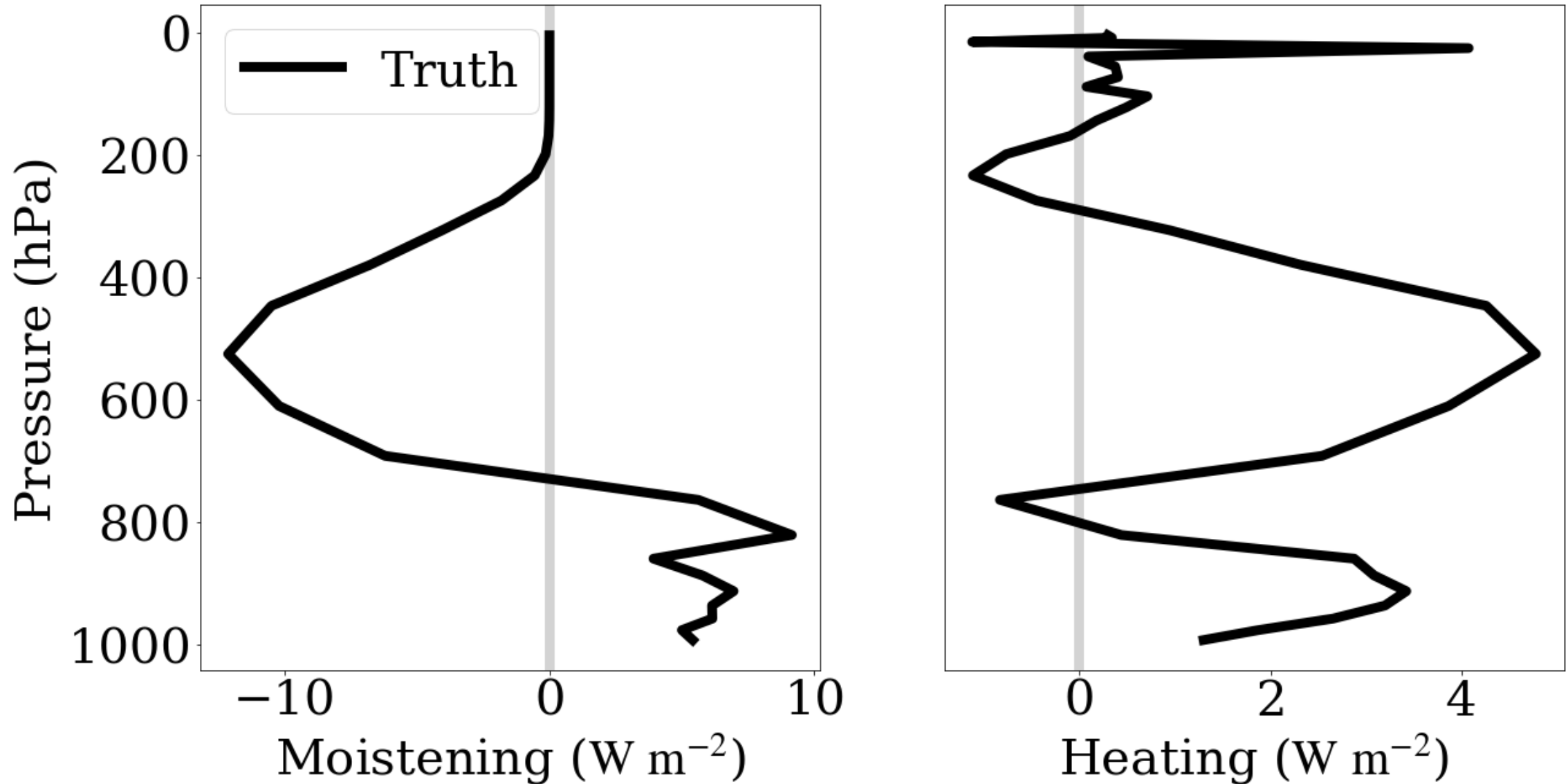


*Images: Rashevskiy Viacheslav, Sebastien Decoret*



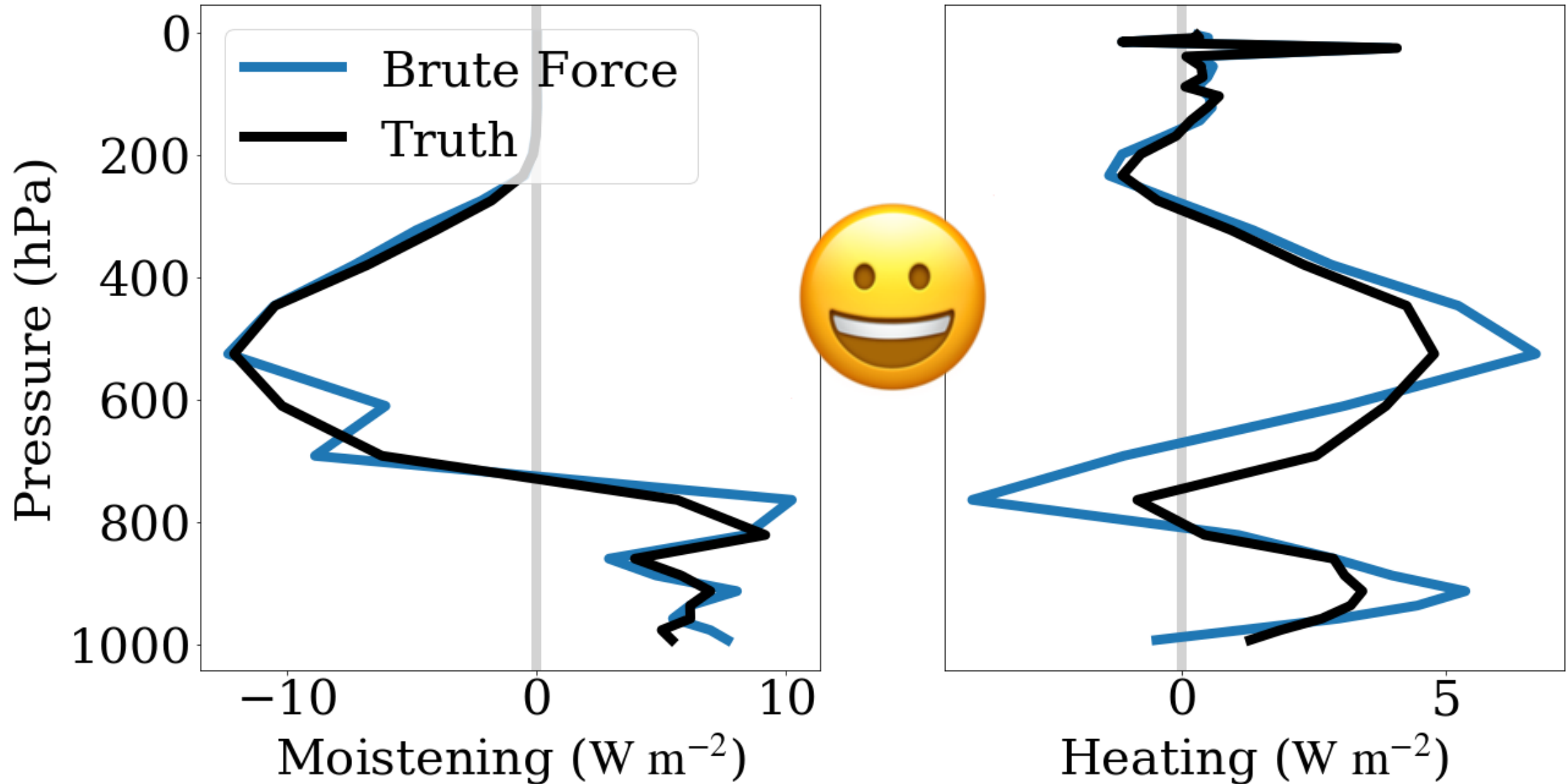
# Problem: NNs fail to generalize to unseen climates

## Daily-mean Tropical prediction in cold climate

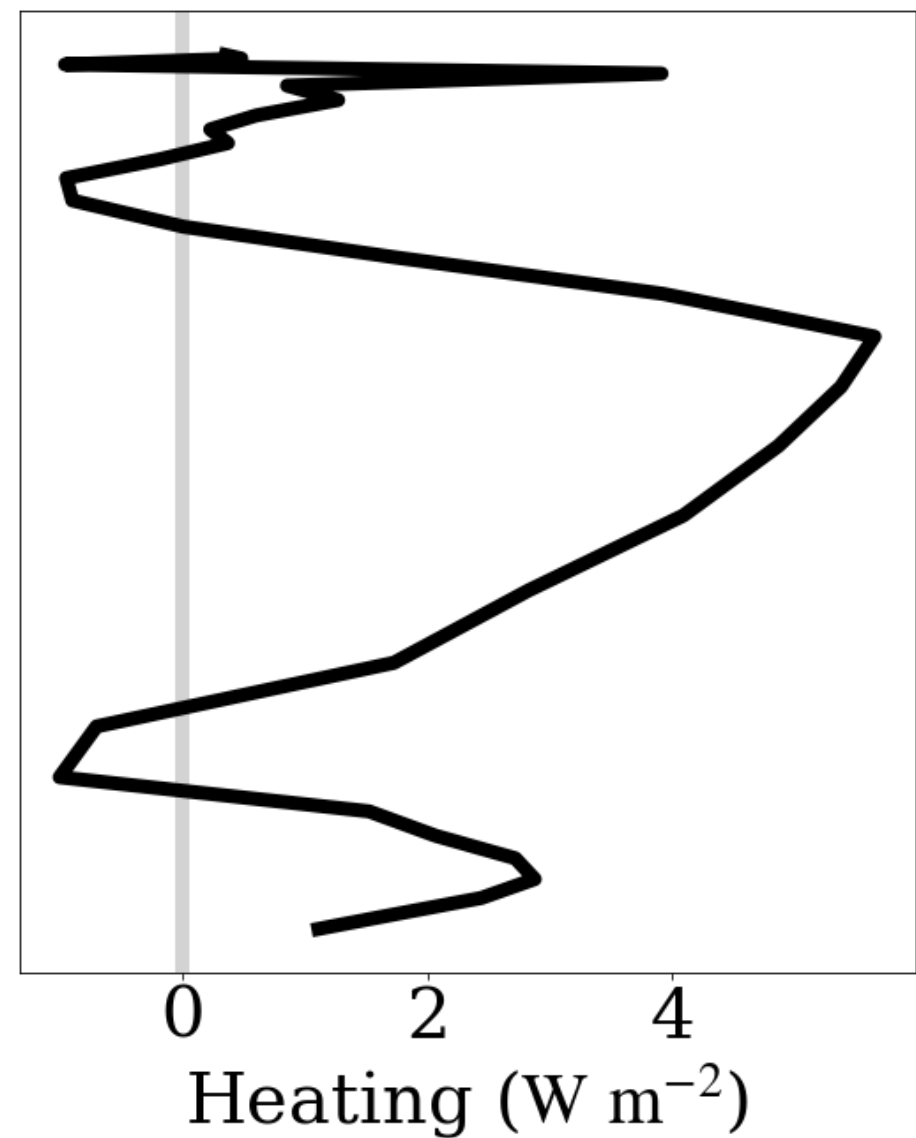
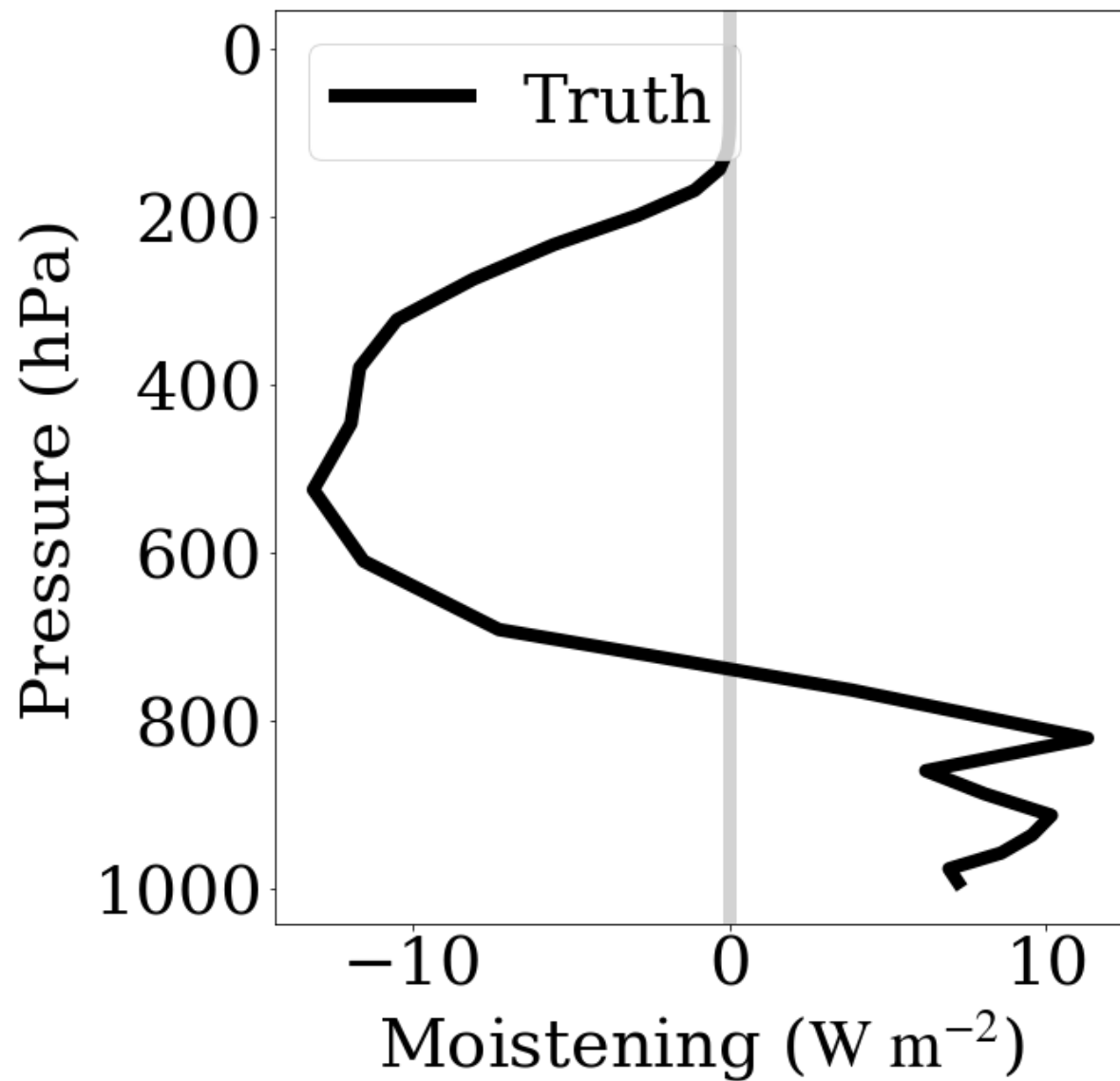


# Problem: NNs fail to generalize to unseen climates

## Daily-mean Tropical prediction in cold climate

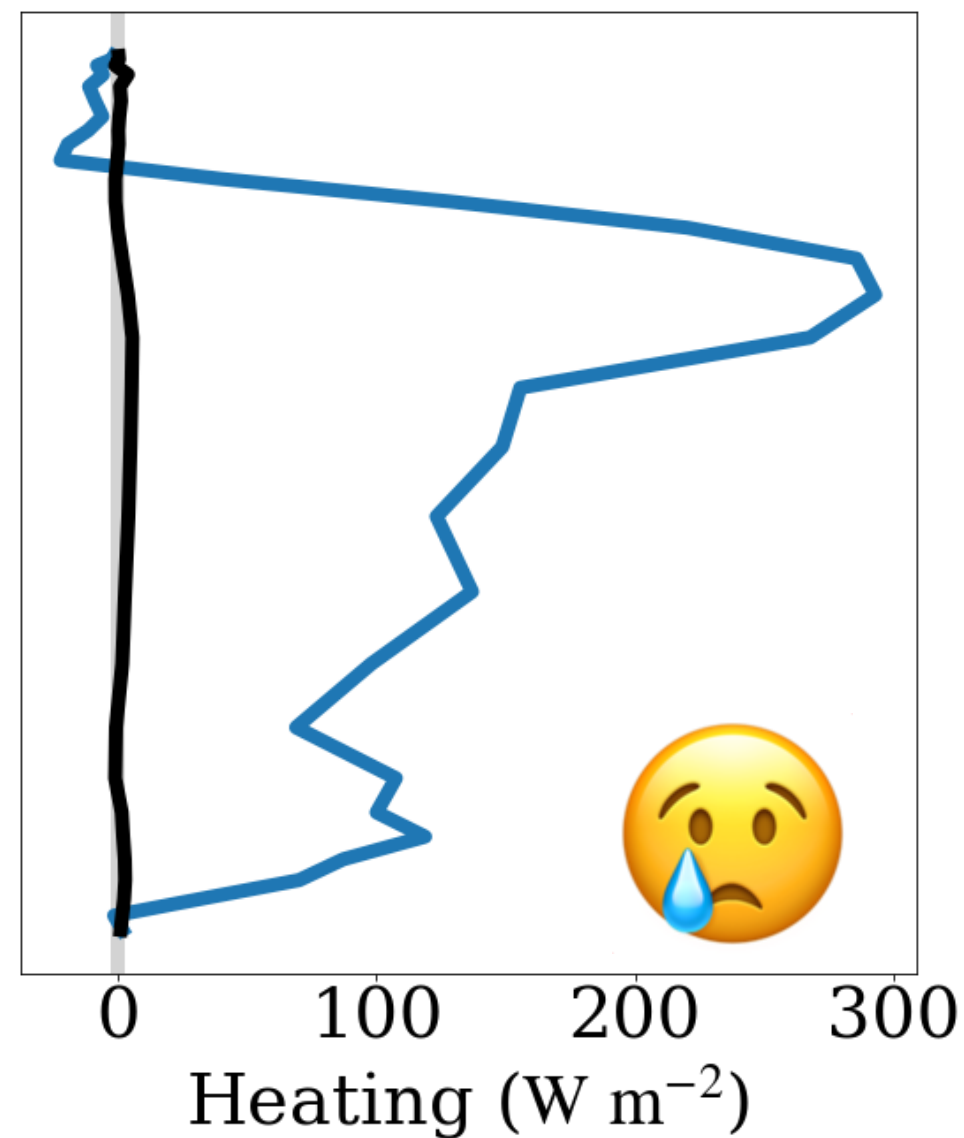
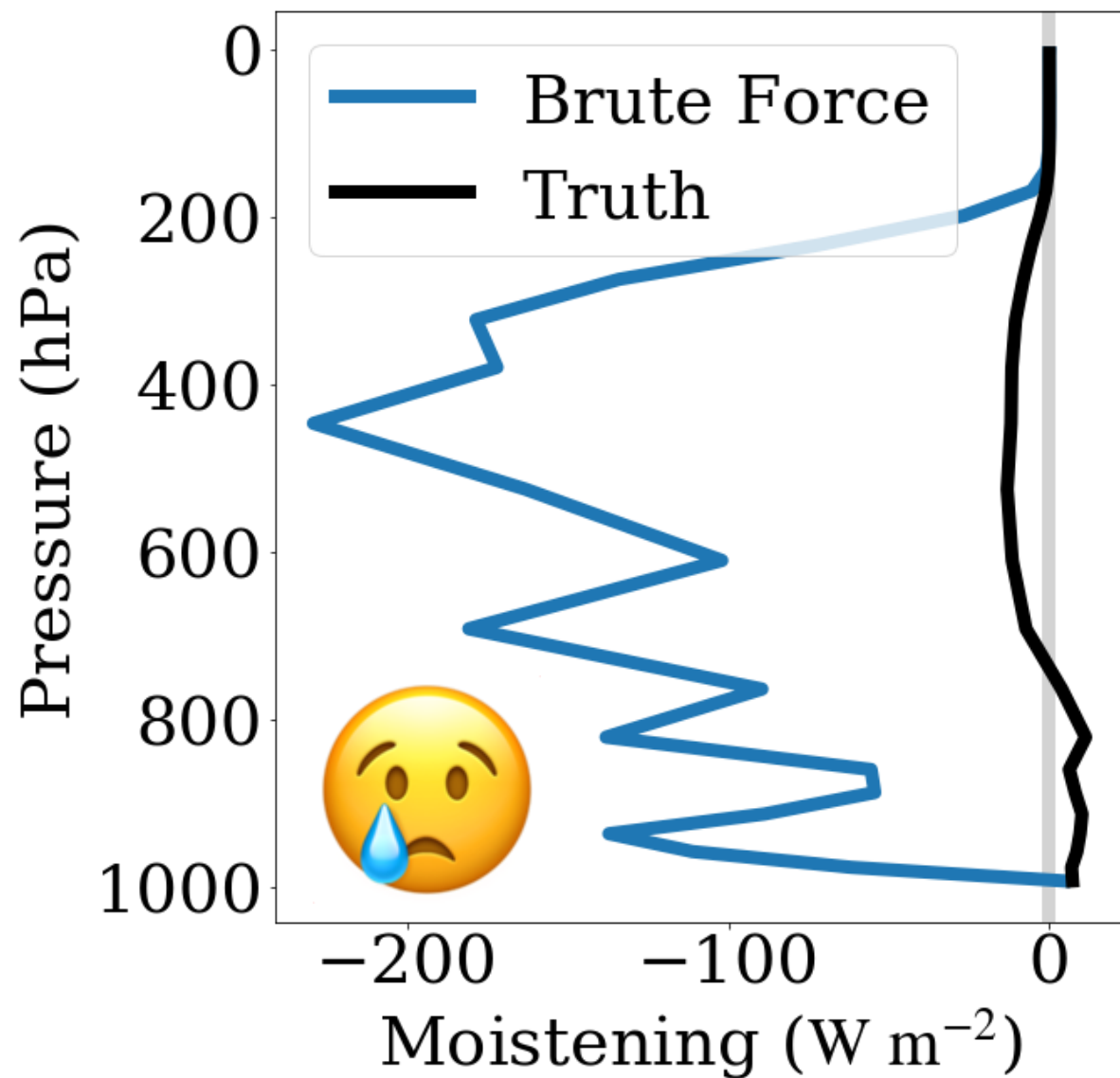


## Daily-mean Tropical prediction in warm climate





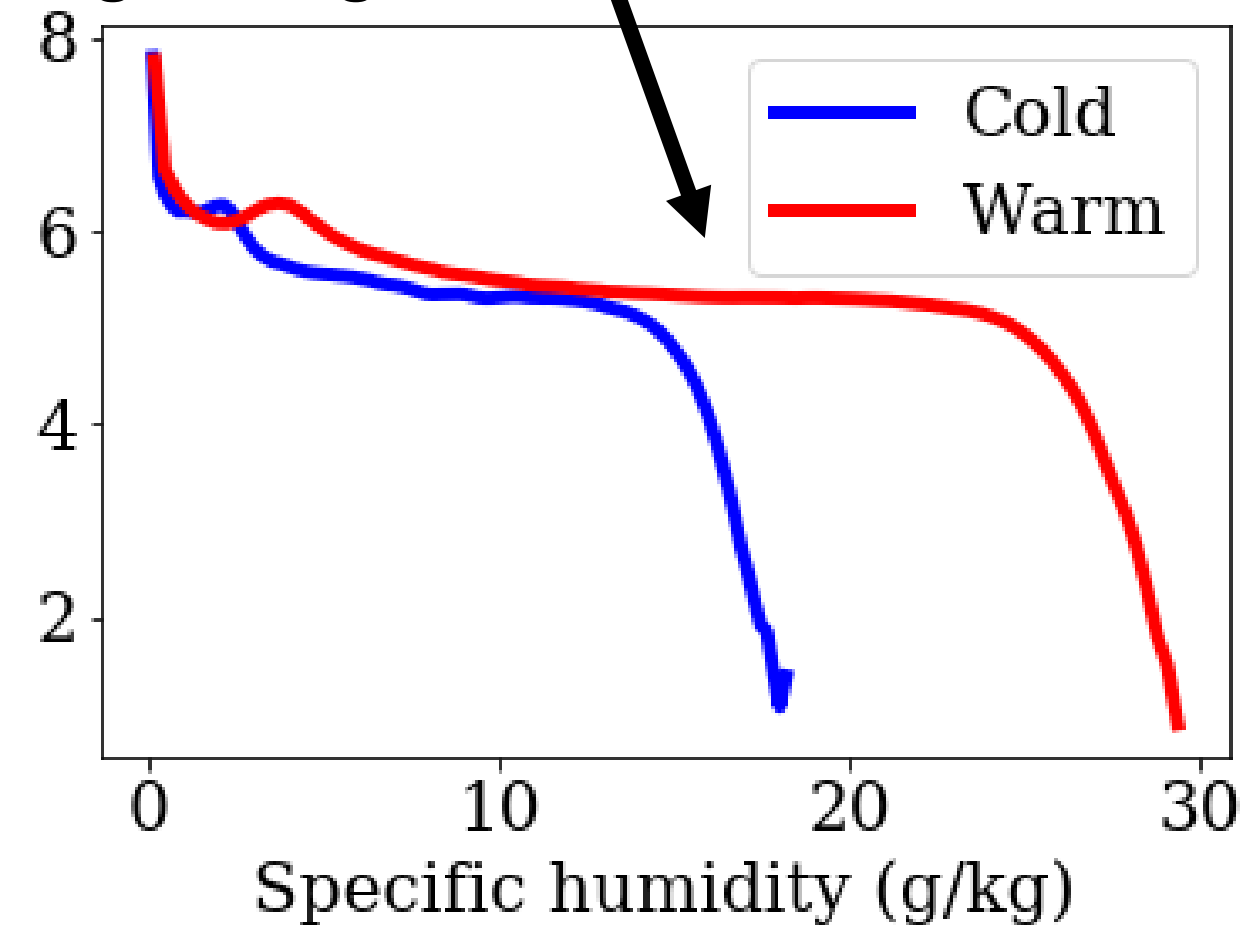
## Daily-mean Tropical prediction in warm climate



Specific humidity ( $z$ )

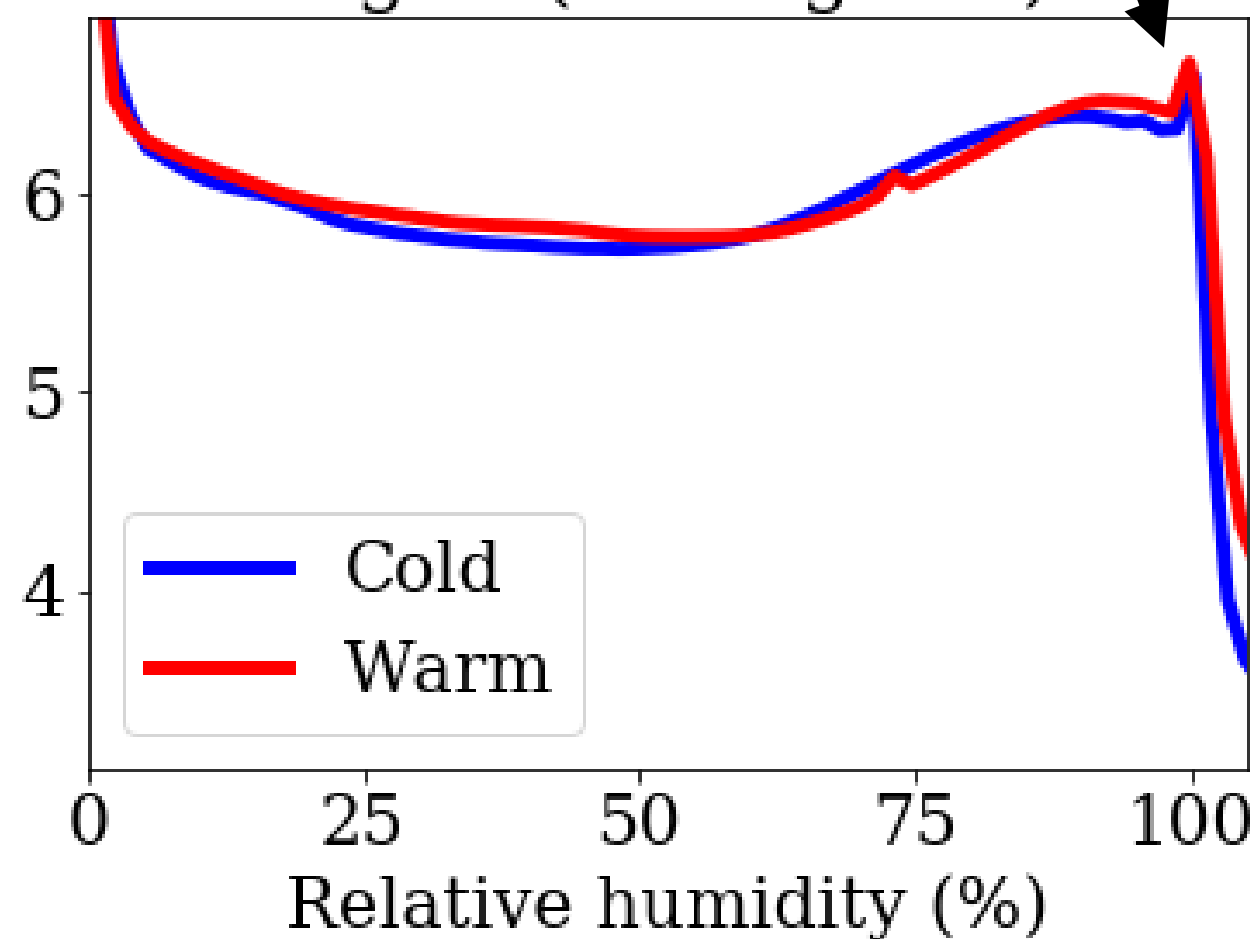
Extrapolation

Log. Histogram



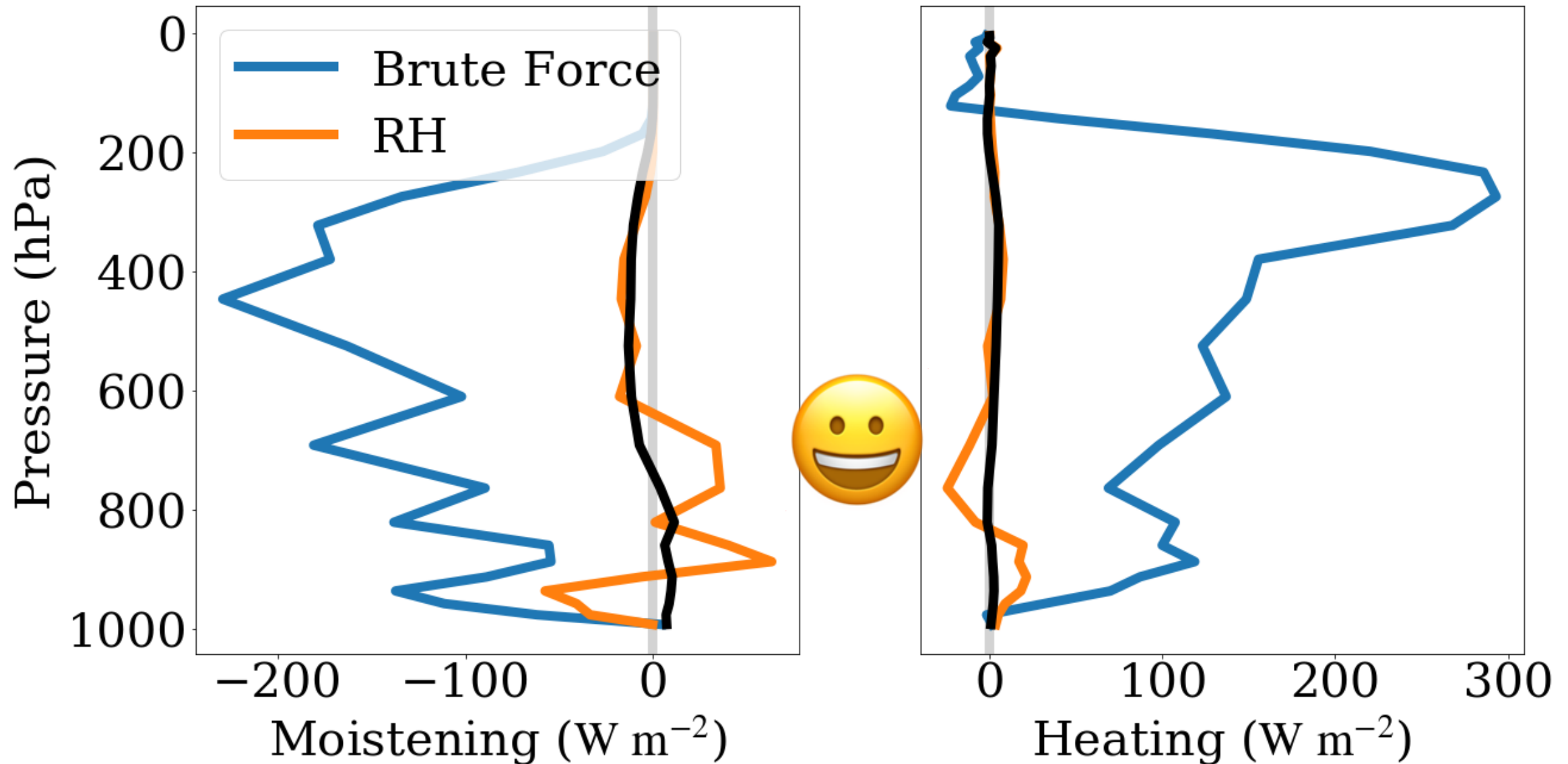
Interpolation

log10 (Histogram)



Specific humidity ( $z$ )  $\rightarrow$  Relative humidity ( $z$ )

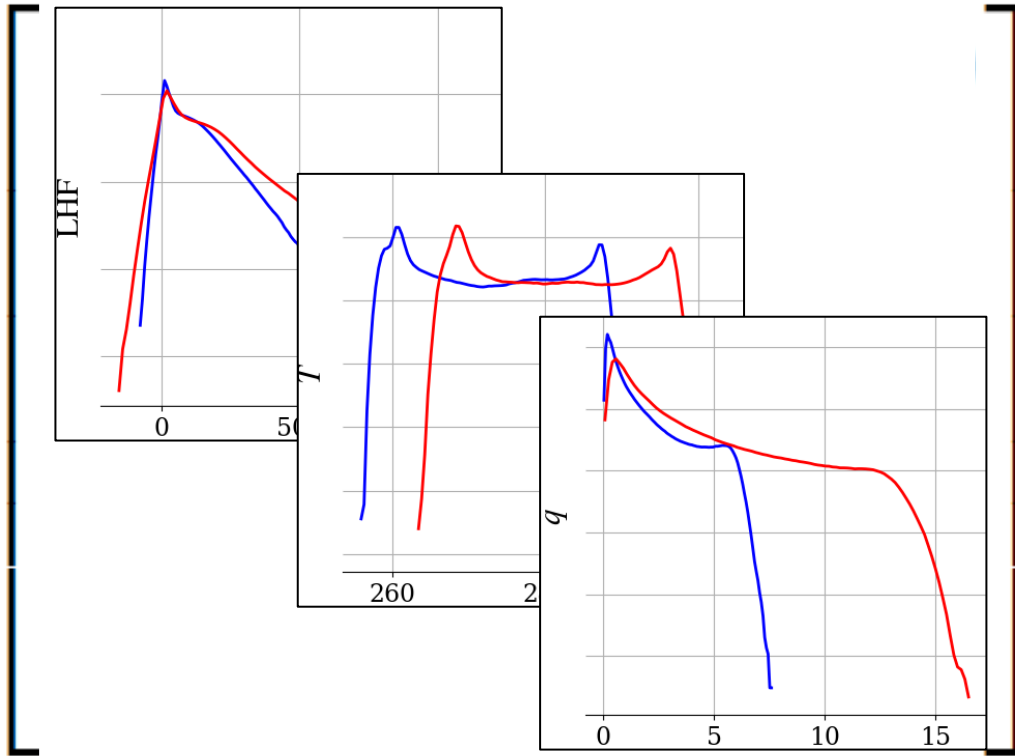
Generalization improves dramatically!



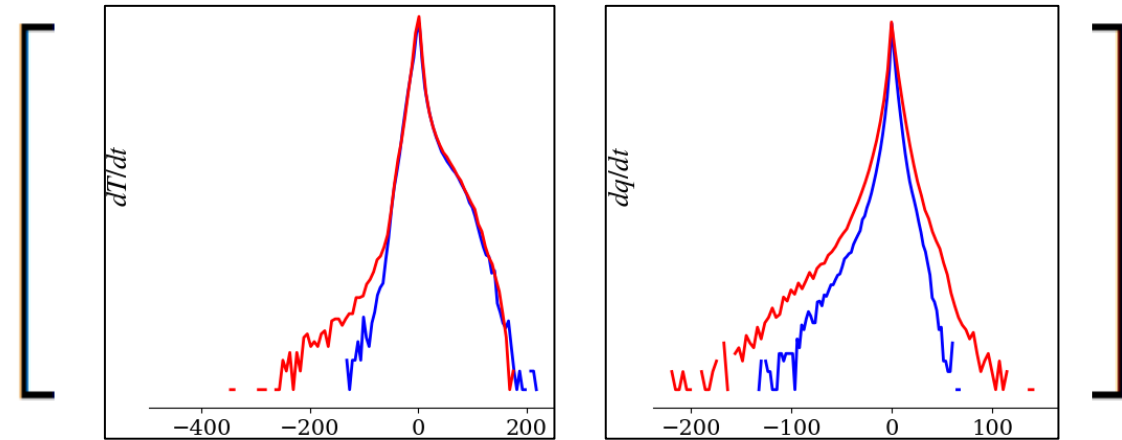




# Physically transform the data to convert extrapolation into interpolation



NN



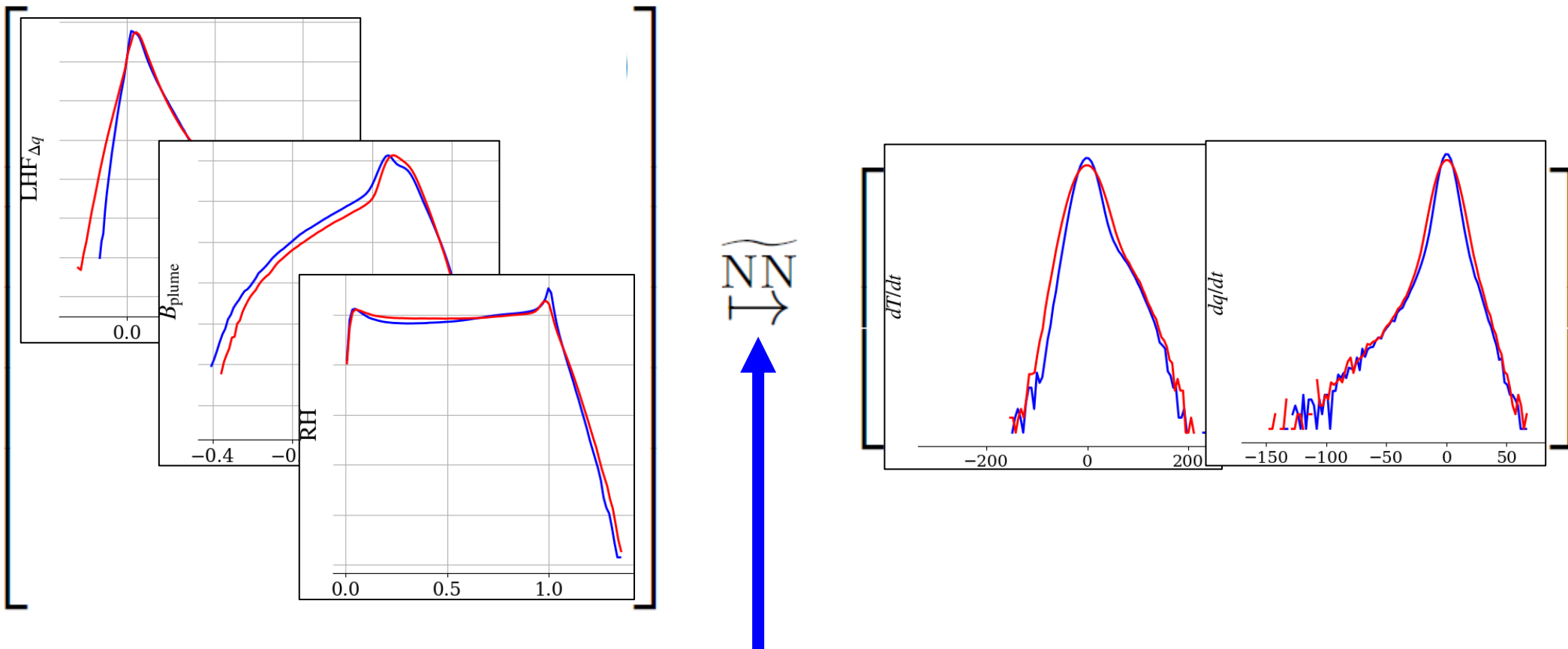
**Raw Data: Not Climate-Invariant**



# Physically transform the data to convert extrapolation into interpolation



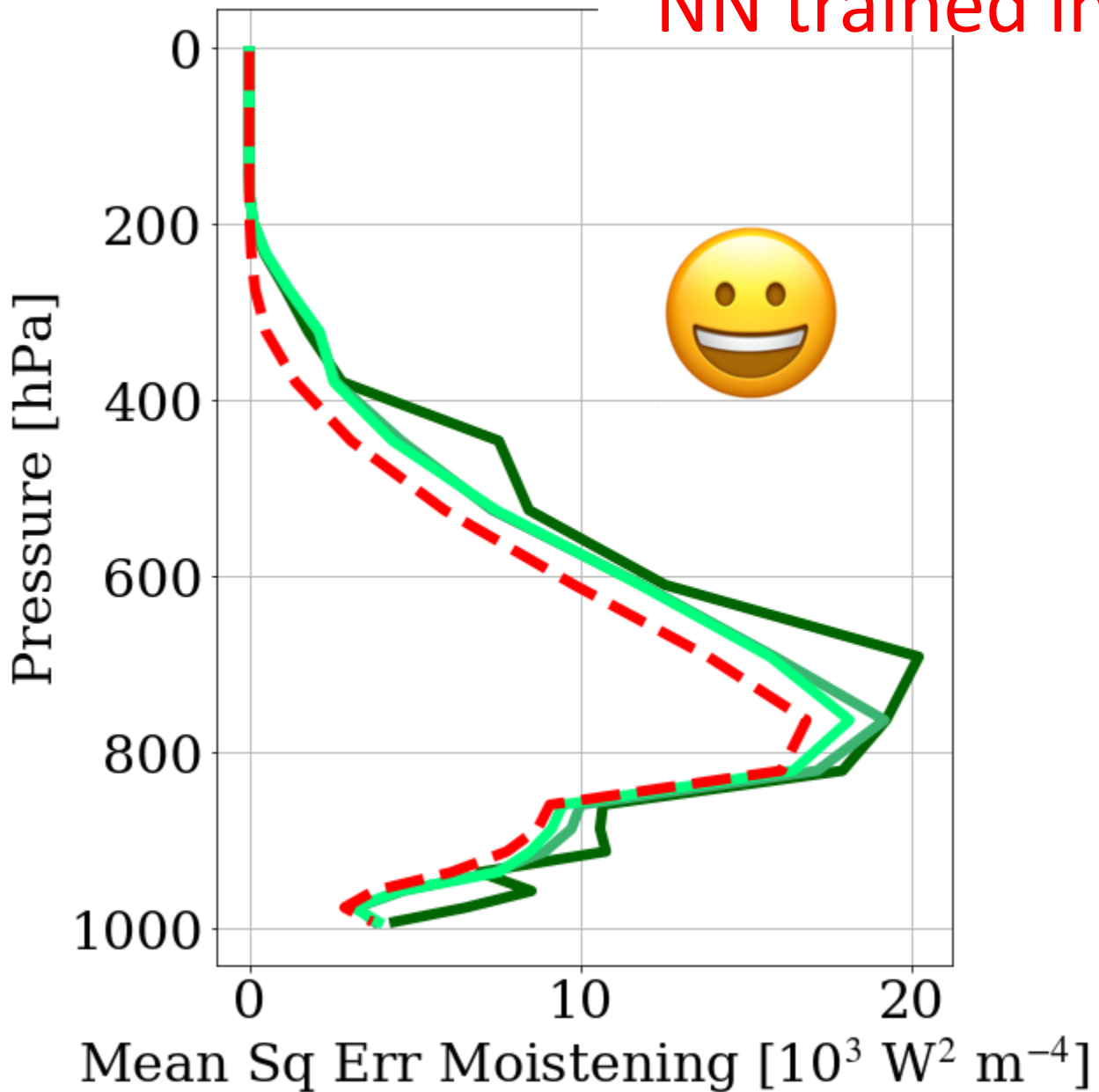
Idea: Uncover **climate-invariant** mapping from climate to convection



Physically-transformed data: Climate-Invariant

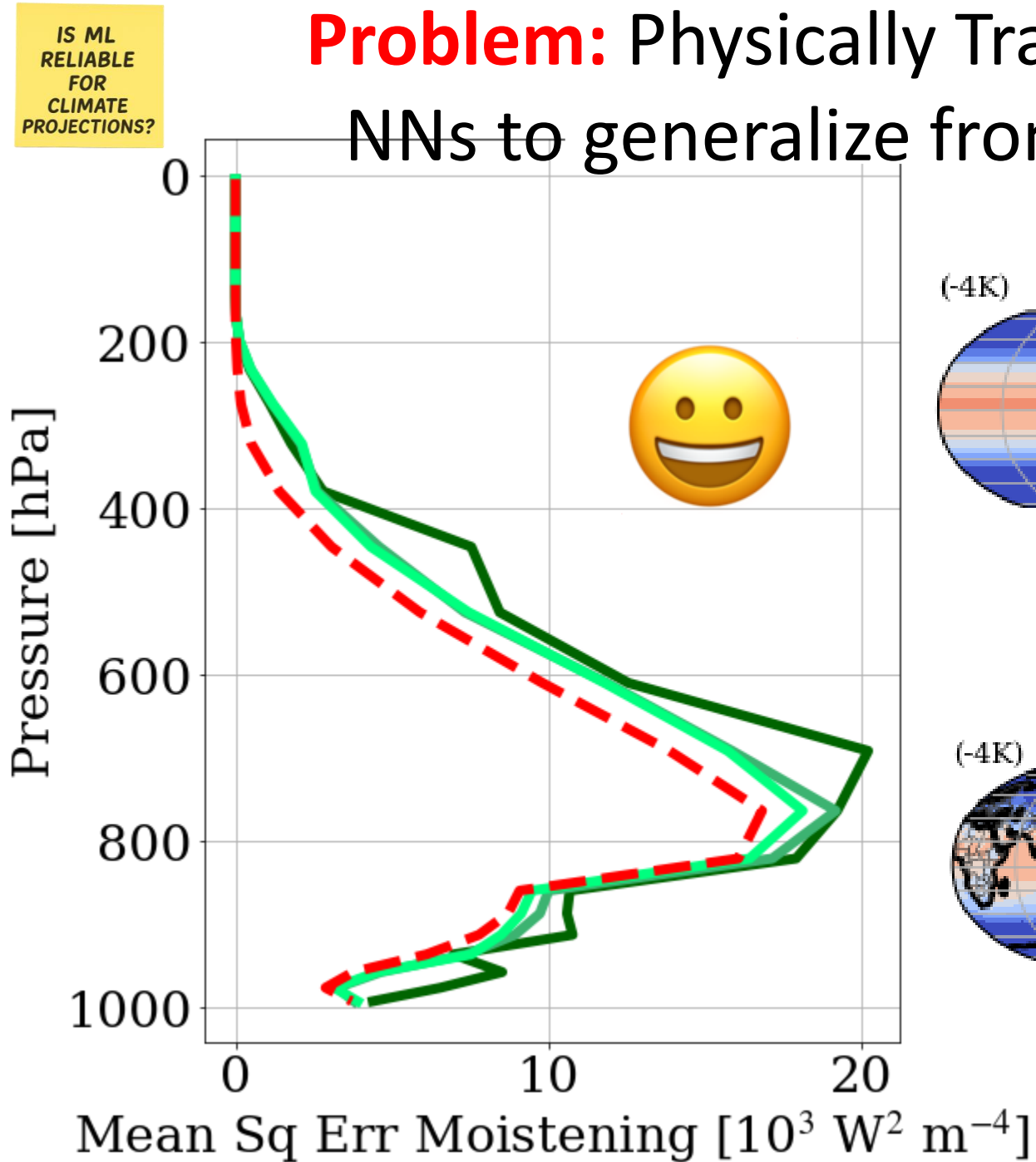
Climate-Invariant NNs generalization error close to

NN trained in warm climate

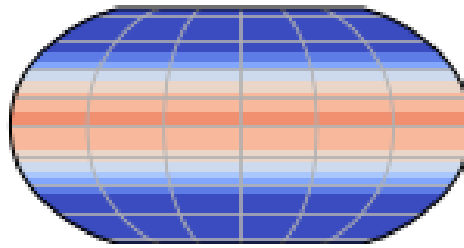




# Problem: Physically Transforming Inputs allows NNs to generalize from cold to warm climate

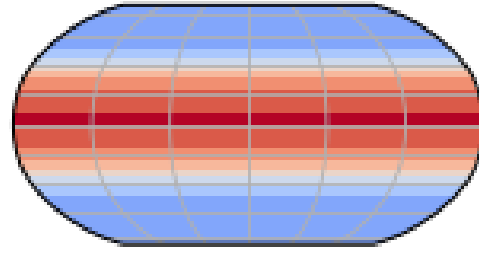


(-4K)

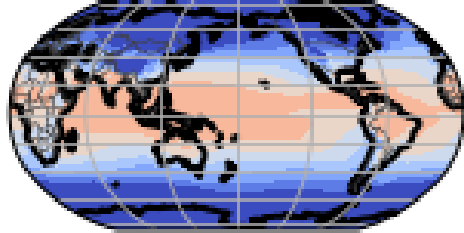


+8K

(+4K)

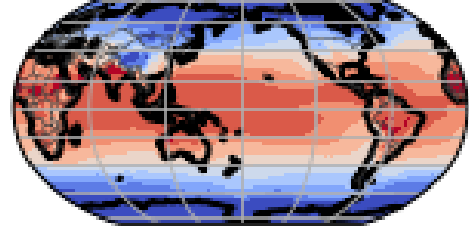


(-4K)



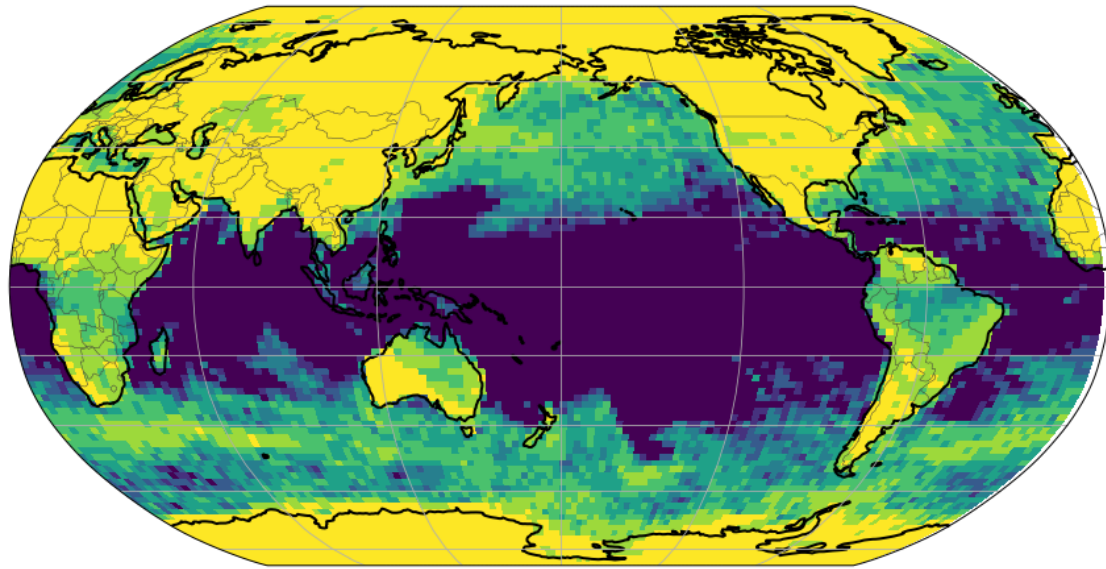
+8K

(+4K)

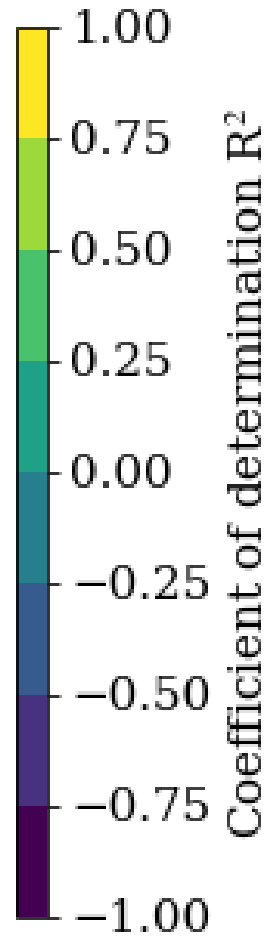
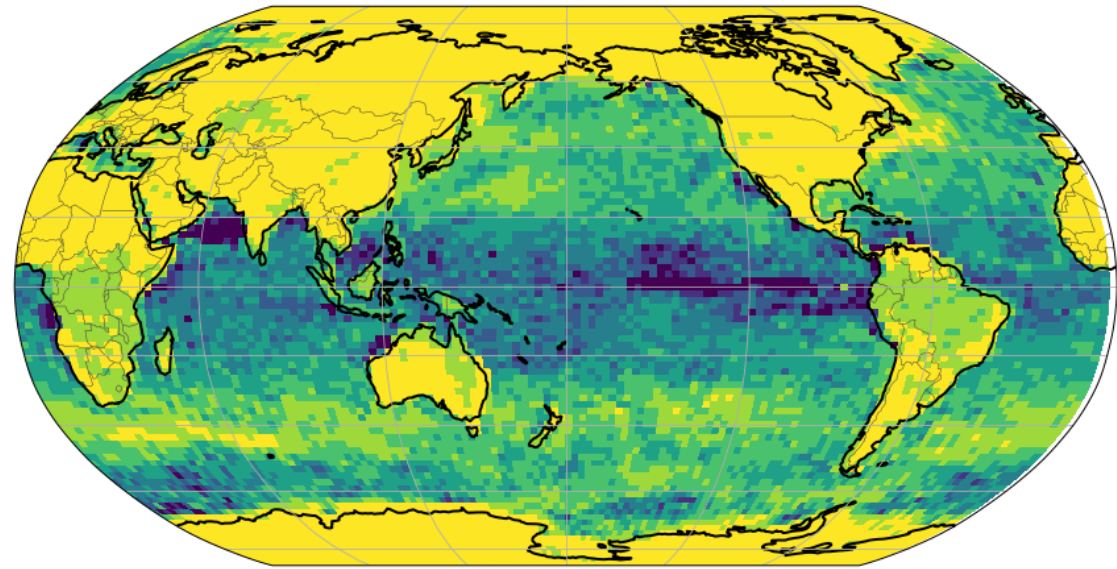


# Physically-Informed Neural Networks Generalize Better Across Climates **in Earth-like configurations**

Without Rescaling



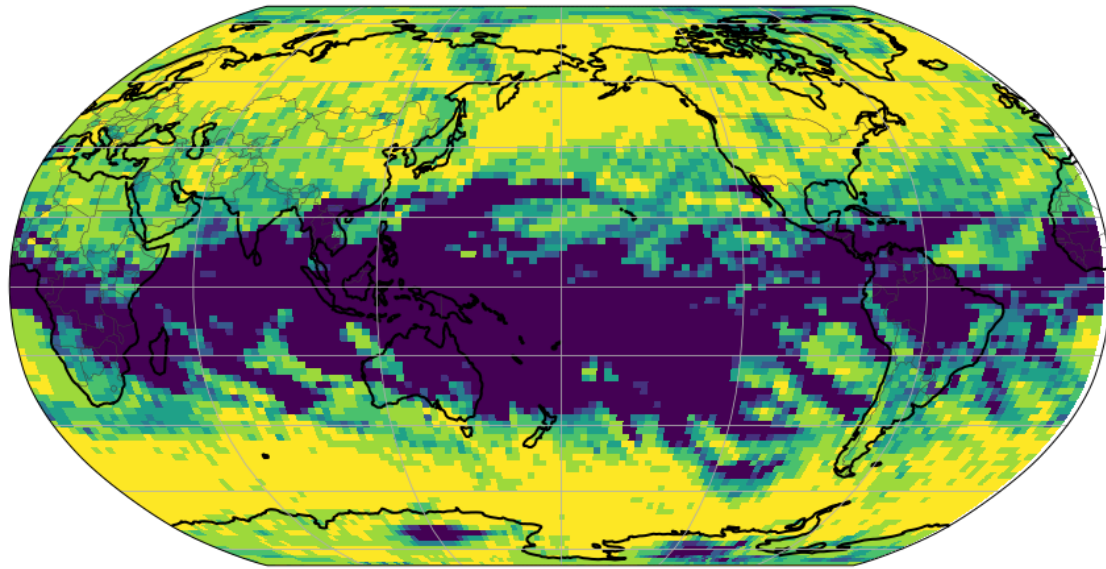
With Physical Rescaling



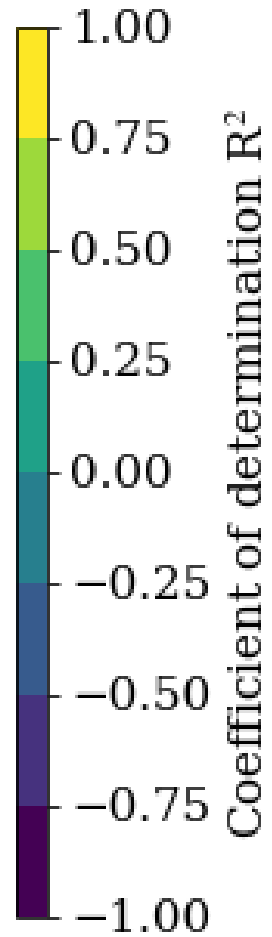
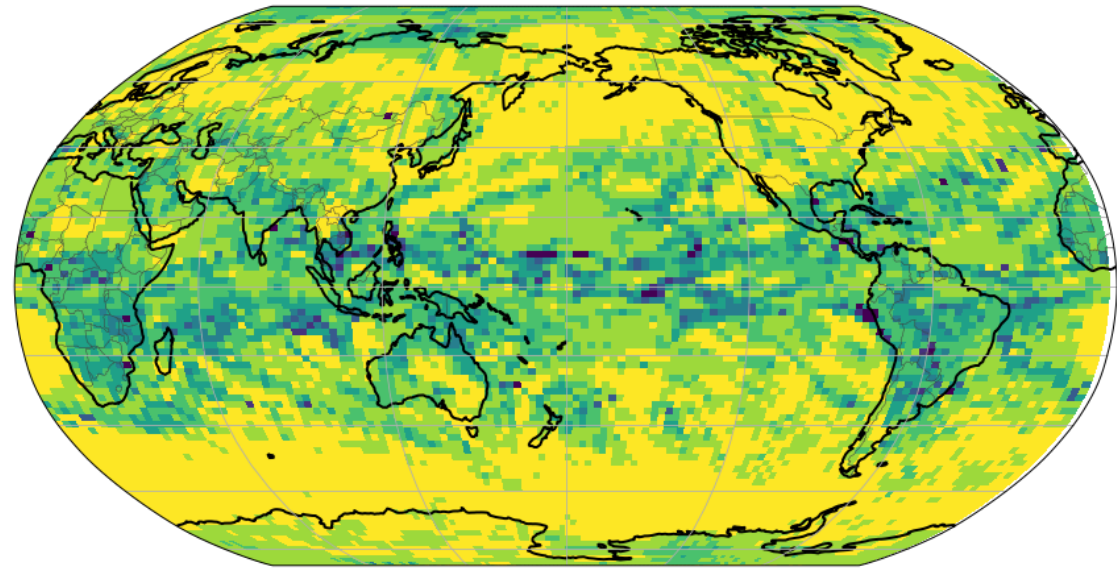
**Near-Surface Subgrid Heating**

# Physically-Informed Neural Networks Generalize Better Across Climates **in Earth-like configurations**

Without Rescaling



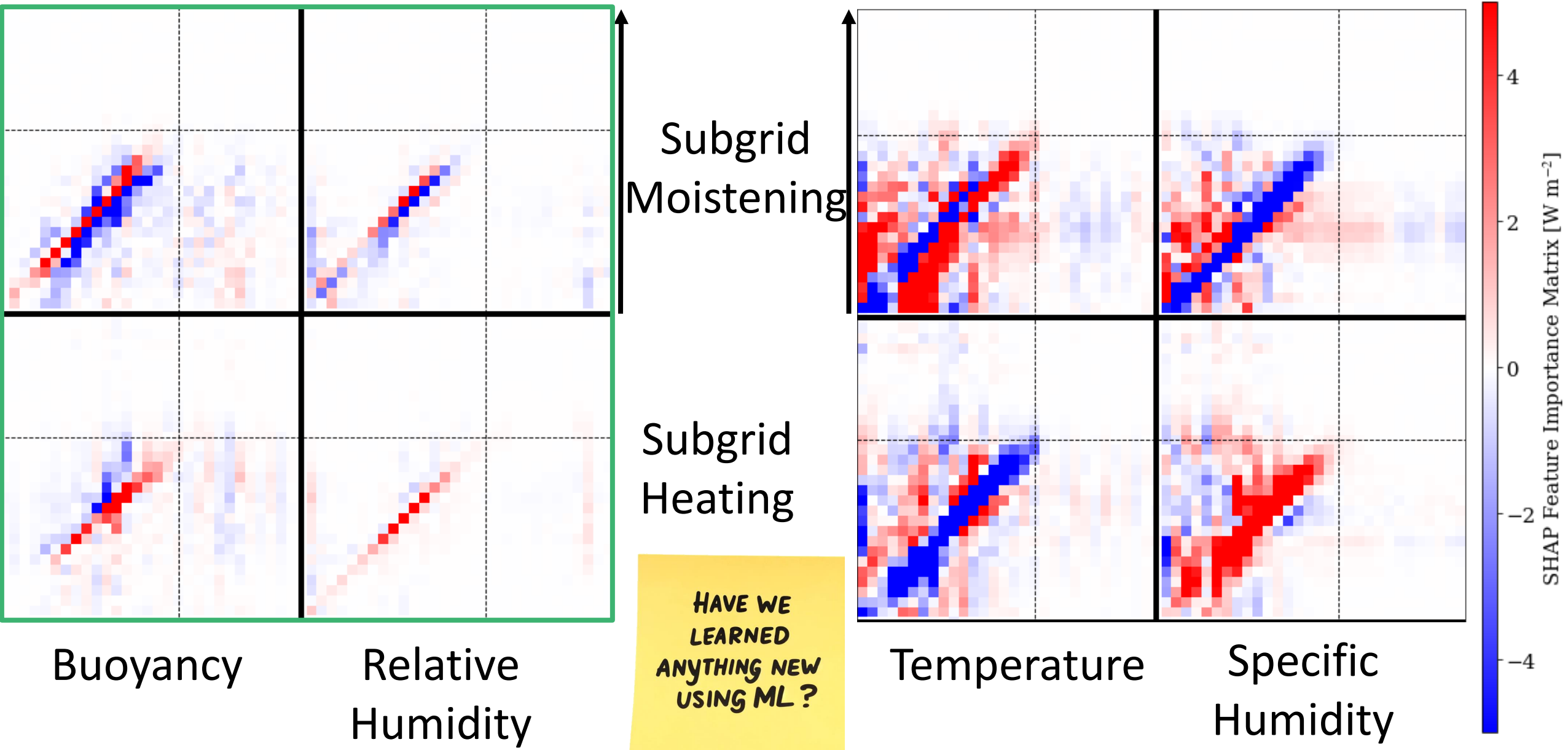
With Physical Rescaling



**Mid-Tropospheric Subgrid Heating**



Unexpected discovery: **Climate-invariant NNs** more local than Brute-Force NNs



- 1) Data-driven parameterizations may not only accelerate, but also **improve** Earth System Models
- 2) They may lead to unexpected discoveries
- 3) They benefit from domain knowledge
- 4) Many challenges remain unsolved...

#### 4) Many challenges remain unsolved:

1. Stability, extrapolation behavior, and recalibration of the host model





# Journal of the Atmospheric Sciences

≡ Volume 77: Issue 12 ▼

▼ Sections

Editorial Type: Article

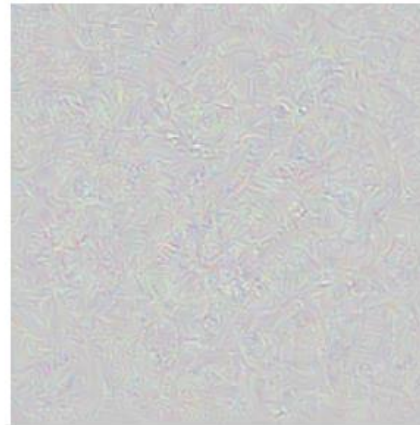
Article Type: Research Article

## Interpreting and Stabilizing Machine-Learning Parametrizations of Convection

Noah D. Brenowitz, Tom Beucler, Michael Pritchard, and  
Christopher S. Bretherton

- ### 4) Many challenges remain unsolved:
1. **Stability**, extrapolation behavior, and recalibration of the host model

# Why bother with XAI?



**Article:** Super Bowl 50

**Paragraph:** "Peython Manning became the first quarterback ever to lead two different teams to multiple Super Bowls. He is also the oldest quarterback ever to play in a Super Bowl at age 39. The past record was held by John Elway, who led the Broncos to victory in Super Bowl XXXIII at age 38 and is currently Denver's Executive Vice President of Football Operations and General Manager. Quarterback Jeff Dean had a jersey number 37 in Champ Bowl XXXIV."

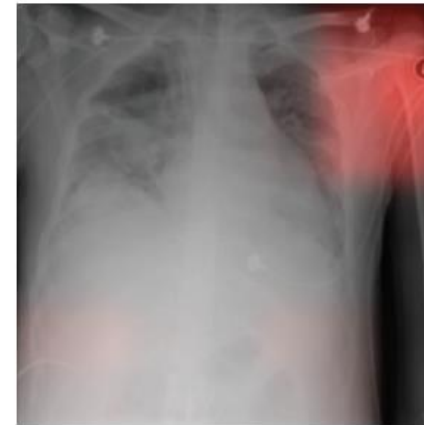
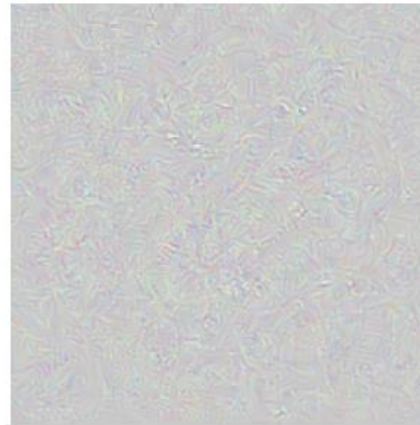
**Question:** "What is the name of the quarterback who was 38 in Super Bowl XXXIII?"

**Original Prediction:** John Elway

**Prediction under adversary:** Jeff Dean

Task for DNN	Caption image	Recognise object	Recognise pneumonia	Answer question
<b>Problem</b>	Describes green hillside as grazing sheep	Hallucinates teapot if certain patterns are present	Fails on scans from new hospitals	Changes answer if irrelevant information is added

# Why bother with XAI? Because NNs take shortcuts!



Article: Super Bowl 50

Paragraph: "Peython Manning became the first quarterback ever to lead two different teams to multiple Super Bowls. He is also the oldest quarterback ever to play in a Super Bowl at age 39. The past record was held by John Elway, who led the Broncos to victory in Super Bowl XXXIII at age 38 and is currently Denver's Executive Vice President of Football Operations and General Manager. Quarterback Jeff Dean had a jersey number 37 in Champ Bowl XXXIV."

Question: "What is the name of the quarterback who was 38 in Super Bowl XXXIII?"

Original Prediction: John Elway

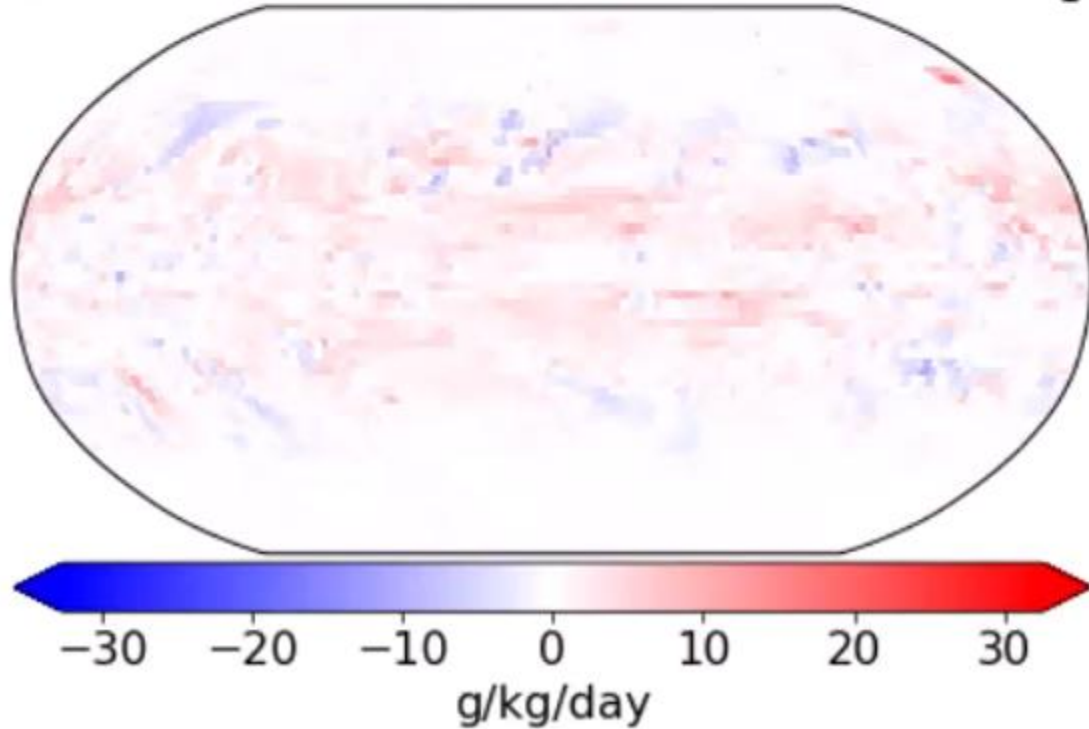
Prediction under adversary: Jeff Dean

Task for DNN	Caption image	Recognise object	Recognise pneumonia	Answer question
<b>Problem</b>	Describes green hillside as grazing sheep	Hallucinates teapot if certain patterns are present	Fails on scans from new hospitals	Changes answer if irrelevant information is added
<b>Shortcut</b>	Uses background to recognise primary object	Uses features irrerecognisable to humans	Looks at hospital token, not lung	Only looks at last sentence and ignores context

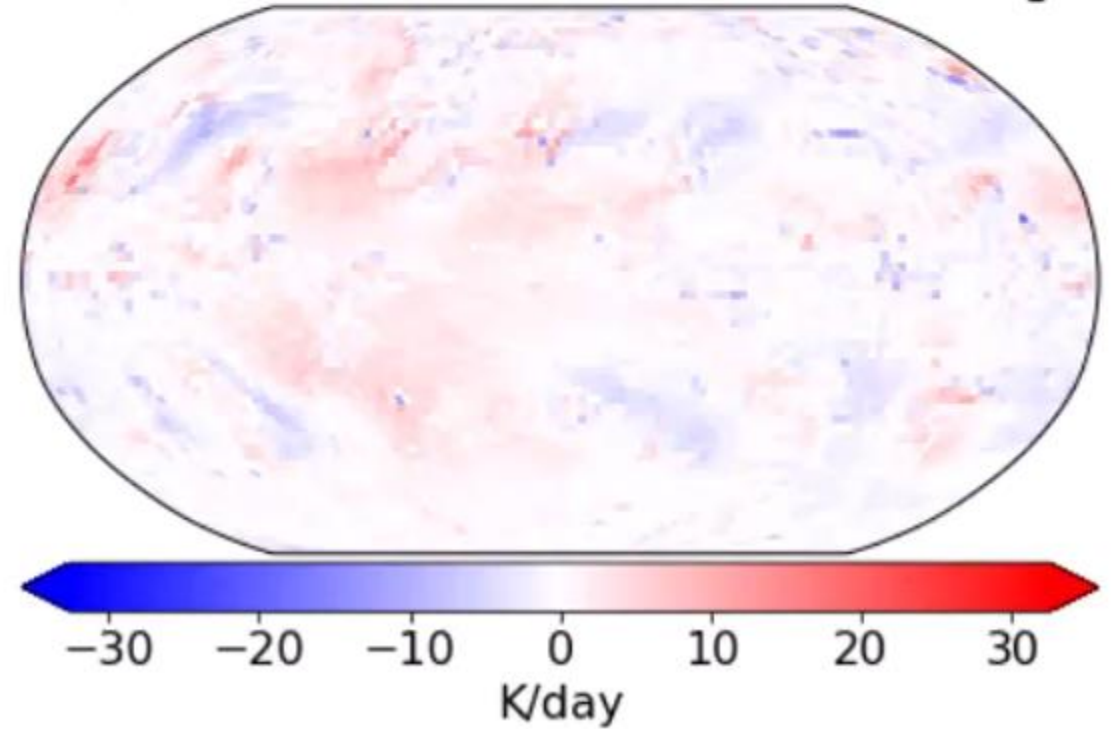
# Should you blindly trust hybrid AI-climate models?

Time to Crash: 1.2day

(a) Near-surface Convective Moistening



(b) Near-surface Convective Heating



*See: Brenowitz, Beucler et al. (2020)*





# Tailor NN interpretability techniques to parametrization task



## Saliency Map

Squared Jacobian of the emulated mapping

Deep learning libraries efficiently calculate Jacobian via automatic differentiation

$$\mathbf{J} \stackrel{\text{def}}{=} \left( \frac{\partial \mathbf{Output}}{\partial \mathbf{Input}} \right)_{\mathbf{Input}_0}$$

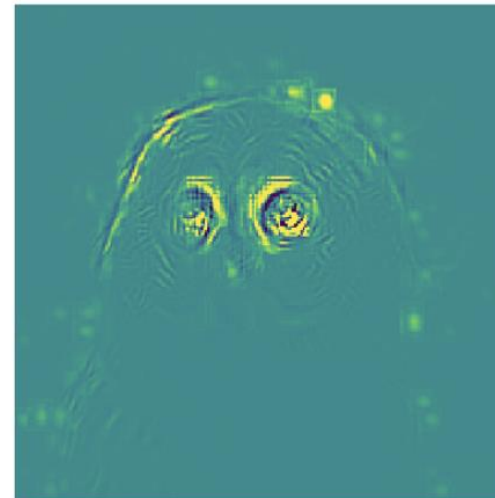
Input image



Gradients across RGB channels



Max gradients

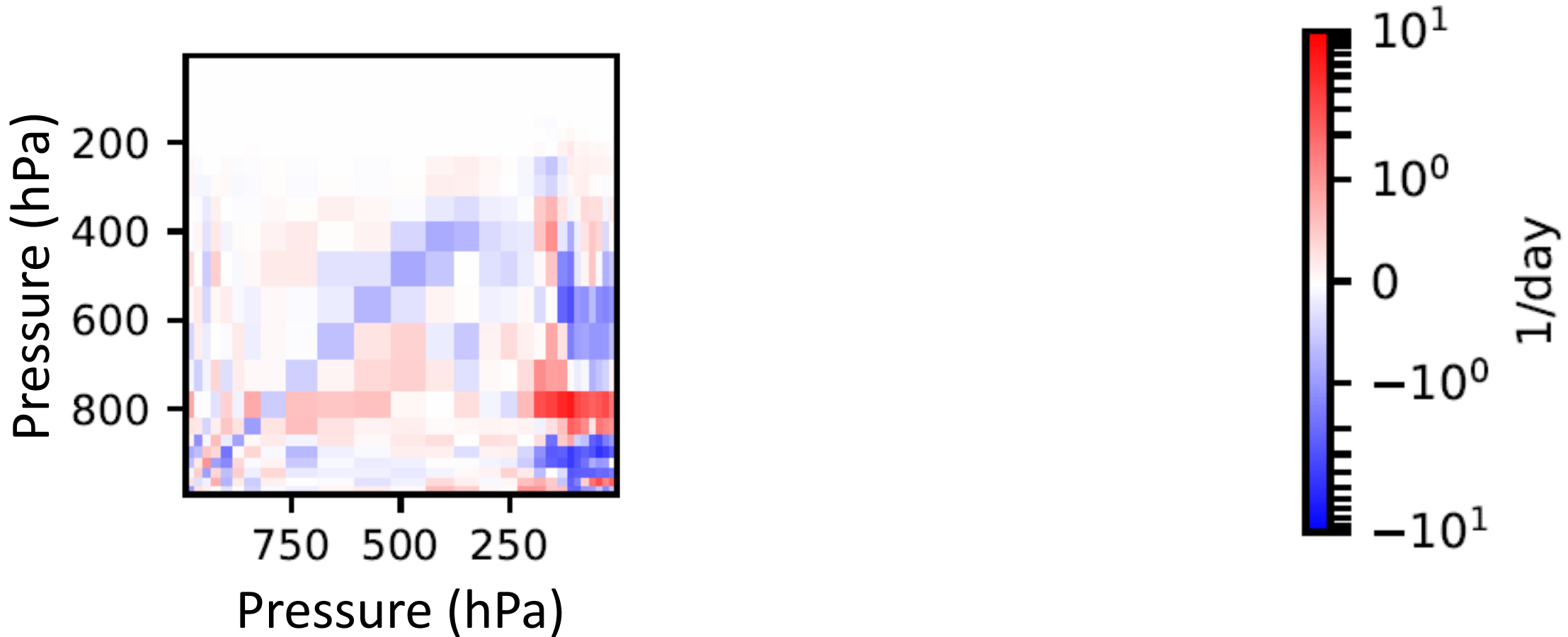


Overlay



# Jacobian reveals linear response of convection

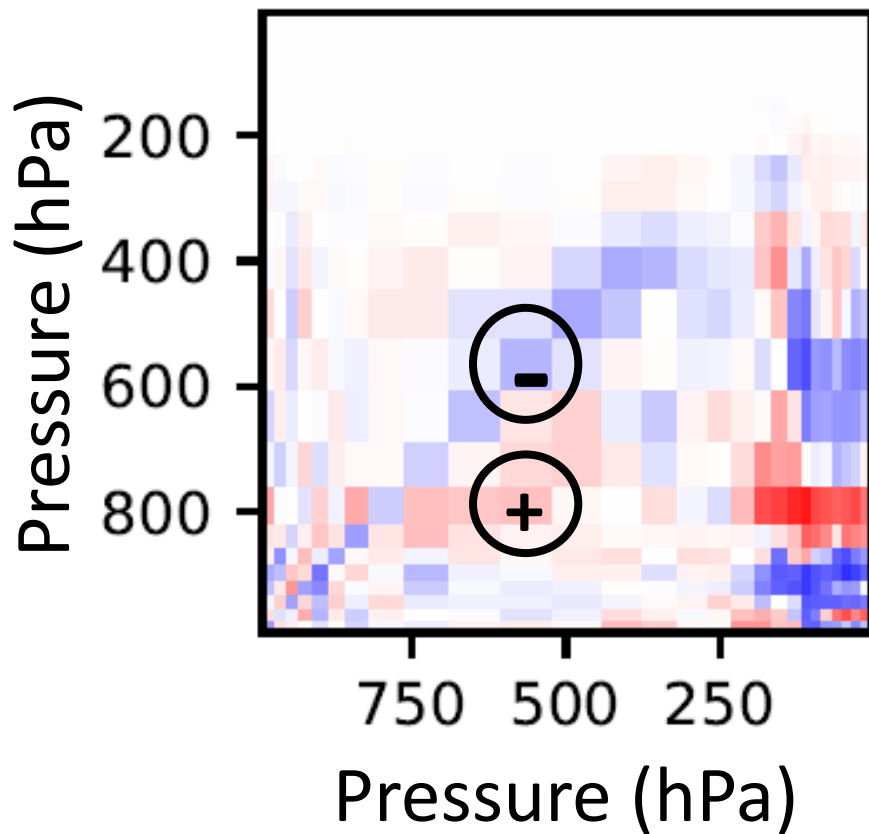
$$\left( \frac{\partial \mathbf{Output}}{\partial \mathbf{Input}} \right) = \frac{\partial (\text{Convective Moistening})}{\partial (\text{Moisture})} \quad [1/\text{day}]$$



*See: Kuang (2018, 2007), Herman and Kuang (2013), Beucler et al. (2018)*

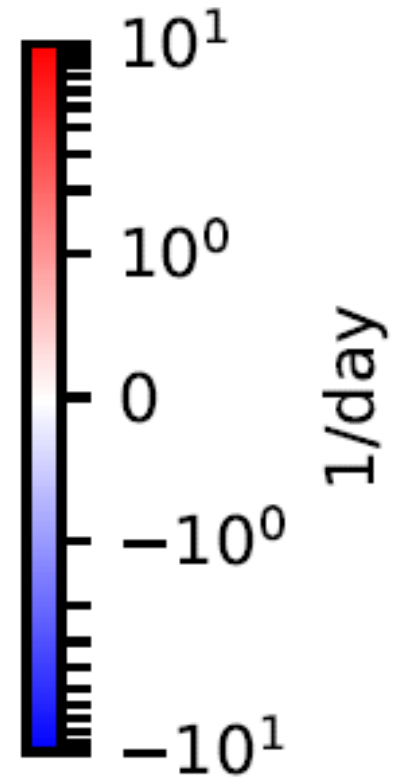
# Jacobian reveals linear response of convection

$$\left( \frac{\partial \mathbf{Output}}{\partial \mathbf{Input}} \right) = \frac{\partial (\text{Convective Moistening})}{\partial (\text{Moisture})} \quad [1/\text{day}]$$

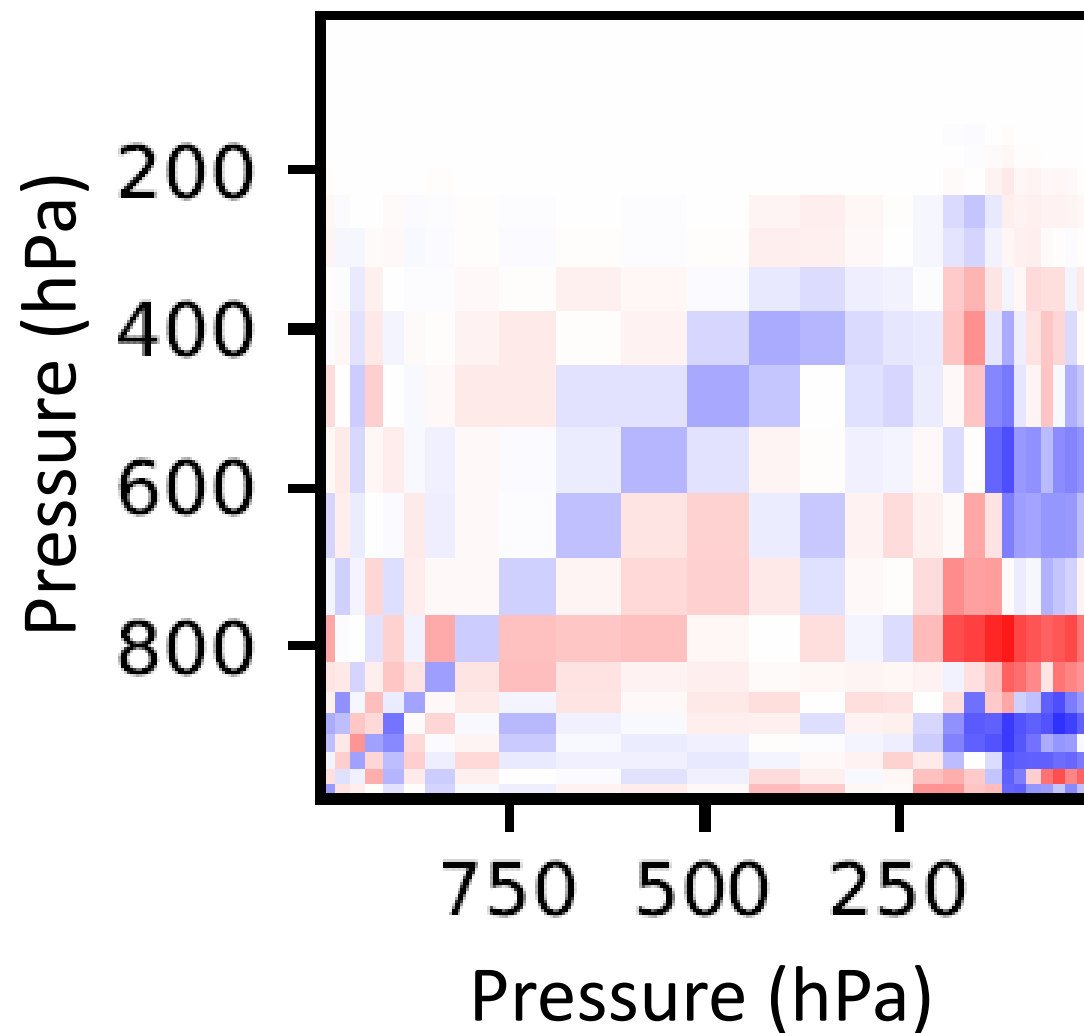


Local anomalies  
are removed

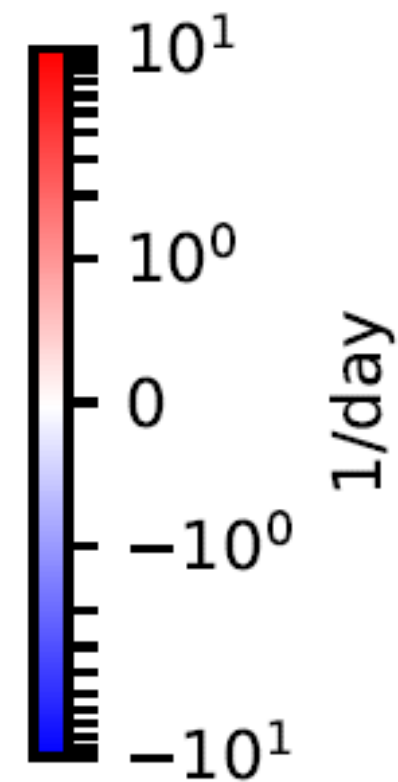
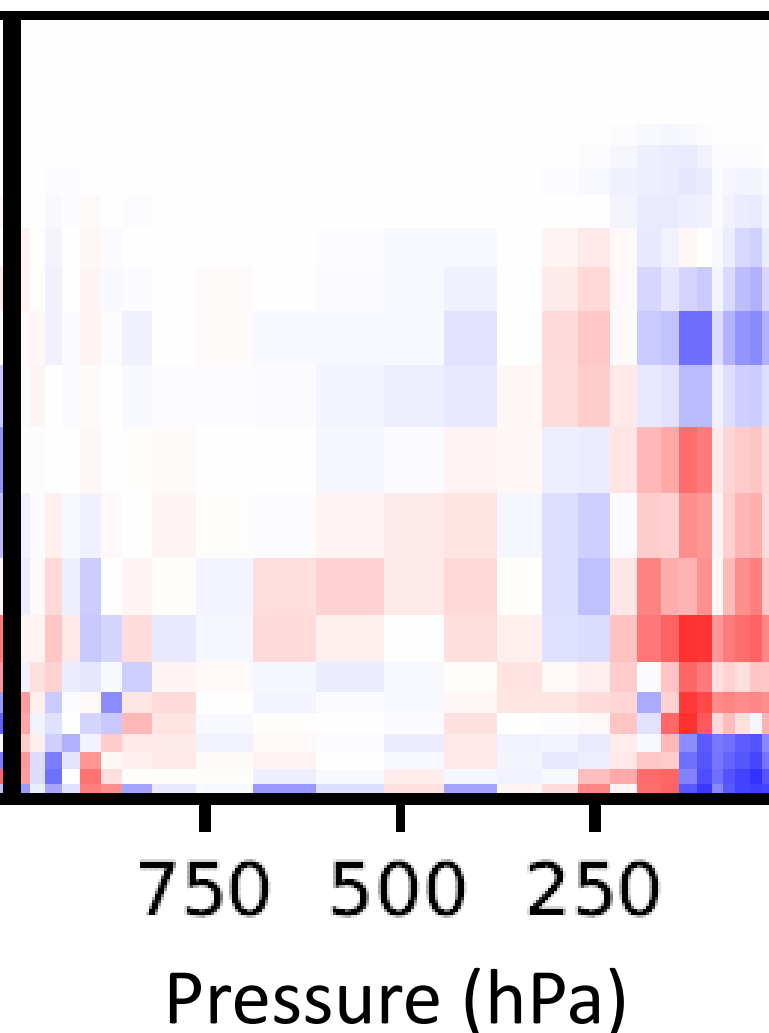
And redistributed  
in lower  
atmosphere



# Tuned NN



# Standard NN



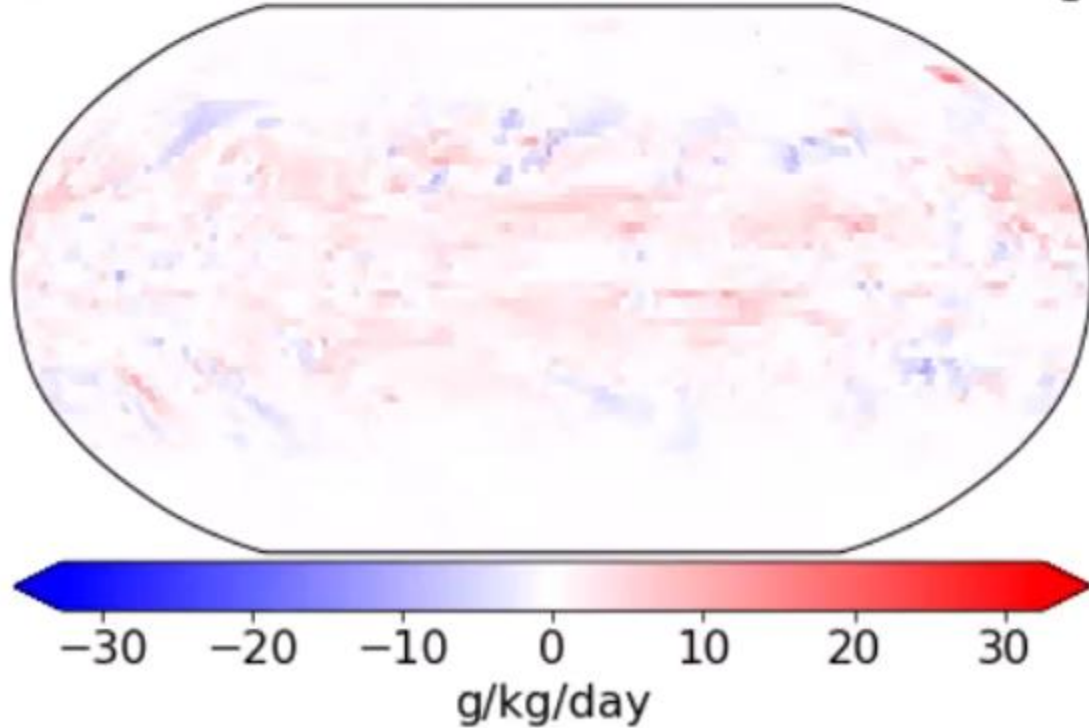
*See: Kuang (2018, 2007), Herman and Kuang (2013), Beucler et al. (2018)*



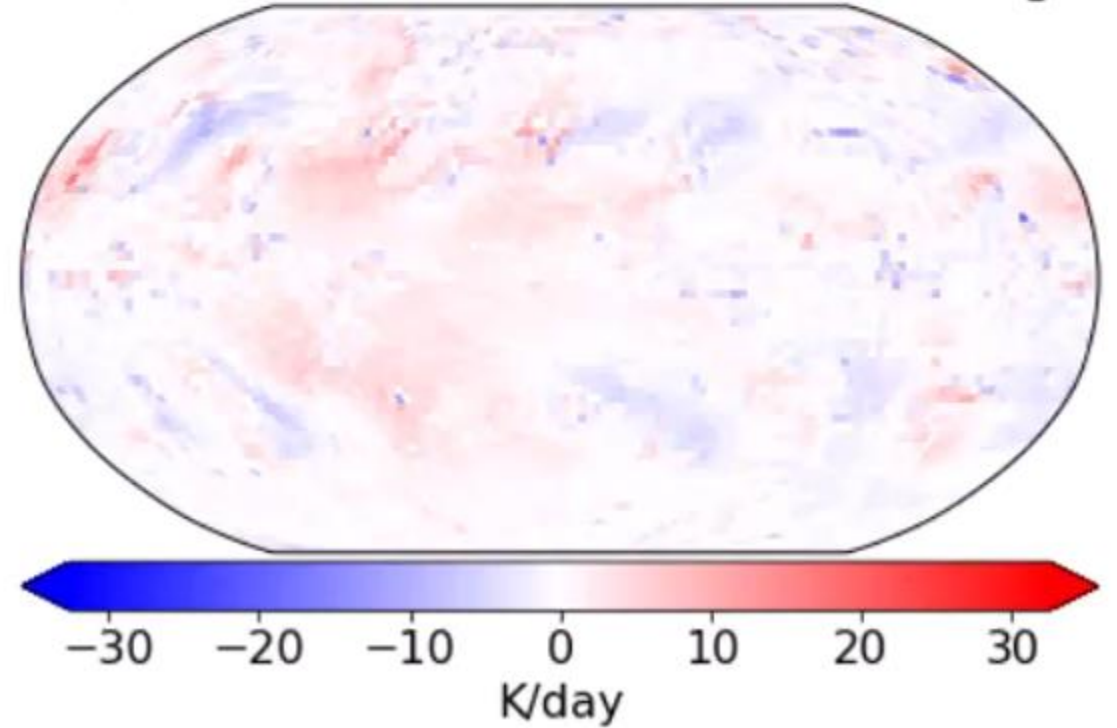
# Challenge: Offline & online objectives often misaligned in hybrid ESMs

Time to Crash: 1.2day

(a) Near-surface Convective Moistening



(b) Near-surface Convective Heating



*See: Brenowitz, Beucler et al. (2020)*

# Derivations in Brenowitz et al. (2020, JAS)

the authors upon request.

## APPENDIX

### Derivation of 2D Anelastic Wave Dynamics

#### a. Continuous equations

The linearized hydrostatic anelastic equations in the horizontal direction  $x$  and height  $z$  are given by

$$q_t + \bar{q}_z w = Q'_2,$$

$$s_t + \bar{s}_z w = Q'_1, \quad \text{and}$$

$$u_t + \phi_x = -du.$$

The prognostic variables are humidity  $q$ , dry static energy  $s = T + (g/c_p)z$ , horizontal velocity  $u$ , and vertical velocity  $w$ . These are assumed to be perturbations from a large-scale state denoted by an overbar. The anelastic geopotential term is given by  $\phi = p'/\rho_0$ , where  $\rho_0(z)$  is a reference density profile specified for the full nonlinear model.

These prognostic equations are completed by assuming hydrostatic balance and mass conservation. Hydrostatic balance is given by

$$(Aw)_k = a_k w_{k-1} + b_k w_k + c_k w_{k+1}, \quad \text{where}$$

$$a_k = \frac{\rho_{k-1}}{(z_k - z_{k-1})(z_{k+1/2} - z_{k-1/2})\rho_{k-1/2}},$$

$$b_k = -\frac{\rho_k}{(z_{k+1/2} - z_{k-1/2})} \times \left[ \frac{1}{(z_{k+1} - z_k)\rho_{k+1/2}} + \frac{1}{(z_k - z_{k-1})\rho_{k-1/2}} \right], \quad \text{and}$$

$$c_k = \frac{\rho_{k+1}}{(z_{k+1} - z_k)(z_{k+1/2} - z_{k-1/2})\rho_{k+1/2}}.$$

The index  $k$  ranges from 1 to  $N$ , the number of vertical grid cells, and  $z$  is the height.

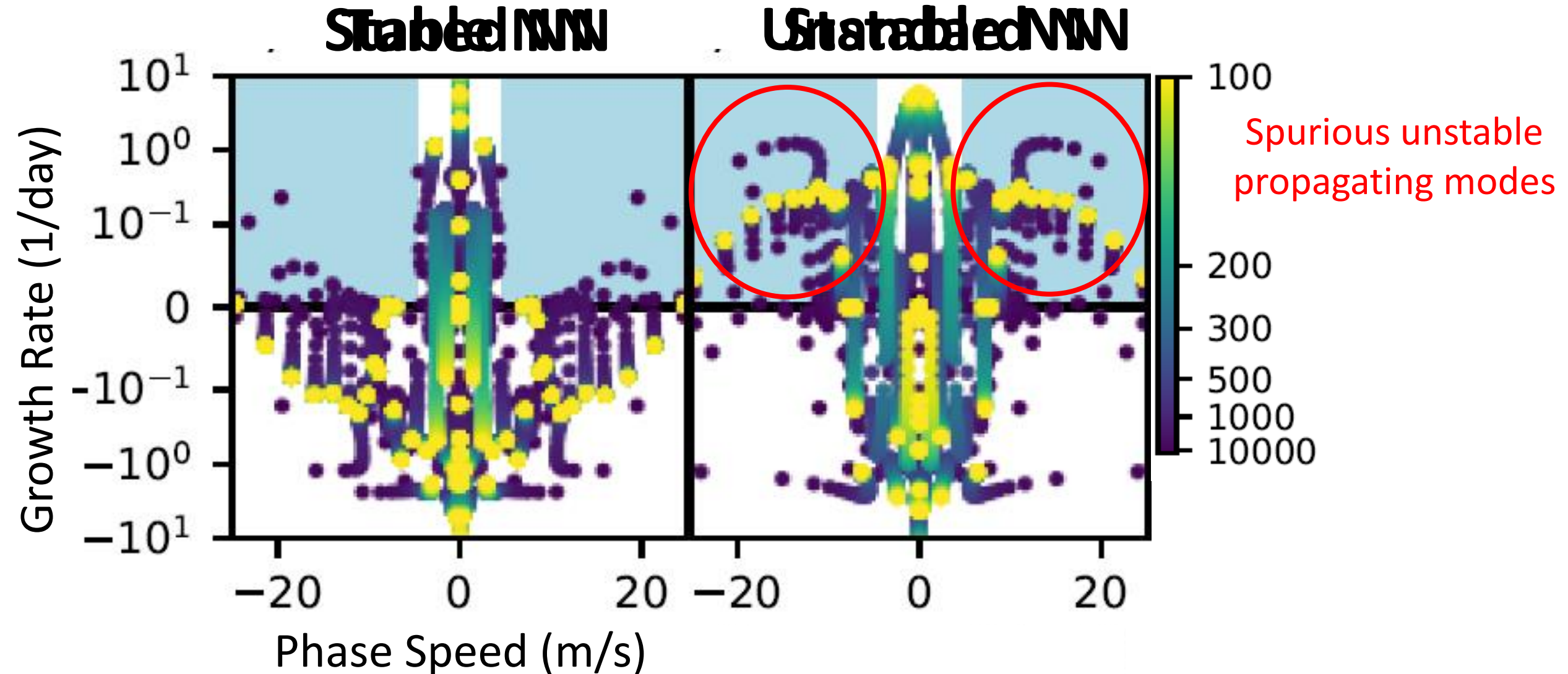
The rigid-lid boundary conditions are satisfied by:  $w_0 = -w_1$  and  $w_{n+1} = -w_n$ . It is not simply  $w_0$  because the vertical velocity should be located at the cell center. These boundary conditions can be implemented by modifying the matrix representation of  $A$  to satisfy

$$(Aw)_1 = -a_1 w_1 + b_1 w_1 + c_1 w_2,$$

$$(Aw)_n = a_n w_{n-1} + b_n w_n - c_n w_n$$

at the lower and upper boundaries.

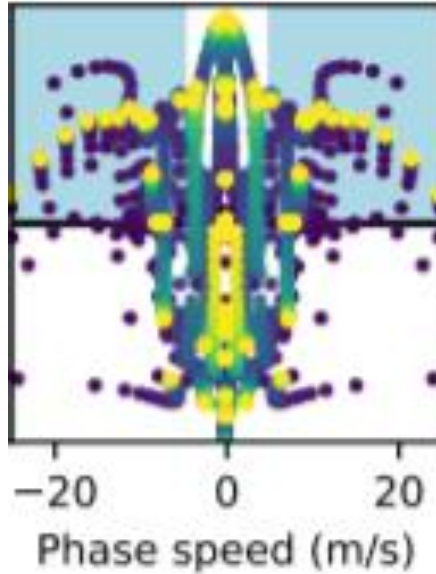
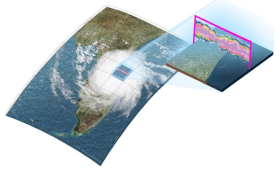
# Coupling Linear Response Function to Gravity Waves reveals the unstable NN **offline**



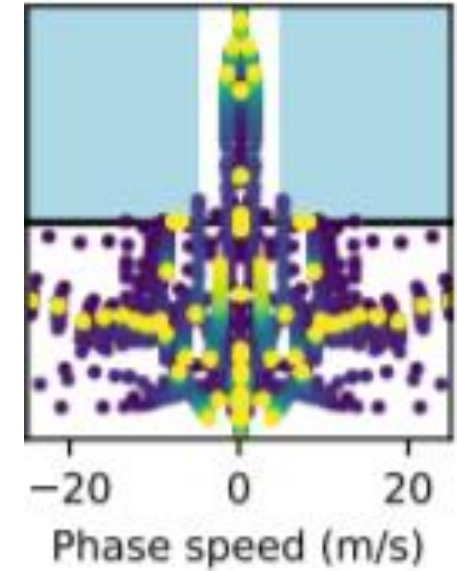
*See: Kuang (2018), Brenowitz, Beucier et al. (2020)*

# Stability diagram helped stabilize NNs **offline**

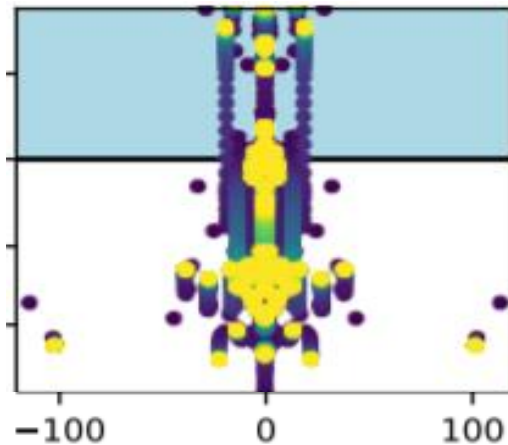
Super  
Parametrized



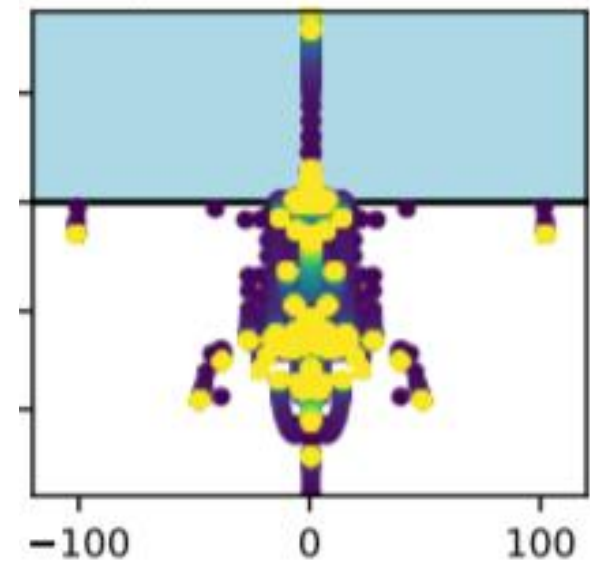
“Regularize” Inputs  
by adding  
Gaussian noise



Global  
Cloud-  
Resolving



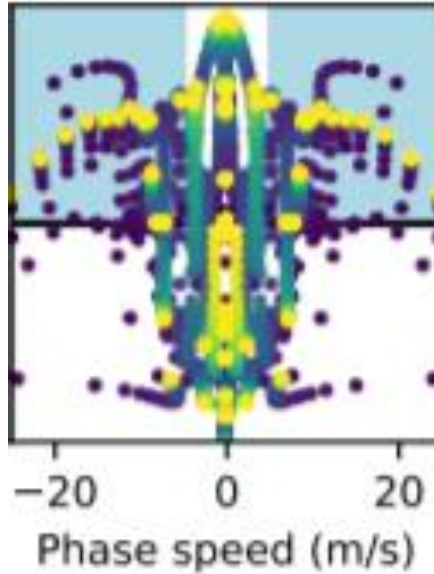
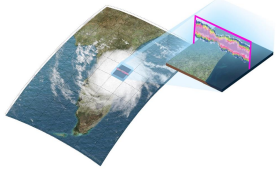
Remove  
upper-atmospheric  
Inputs



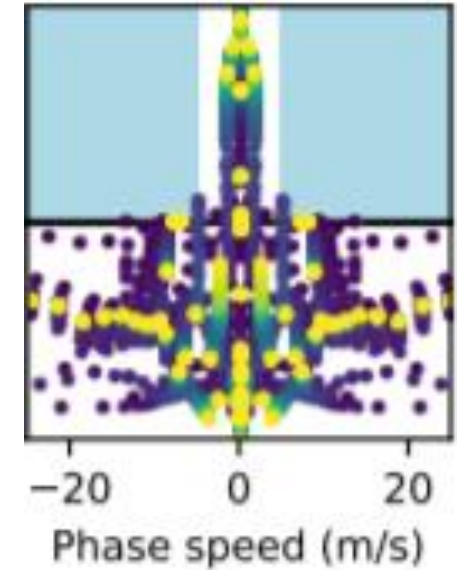


Both stabilized NN ran without crashing for **1month+**  
when coupled to climate models

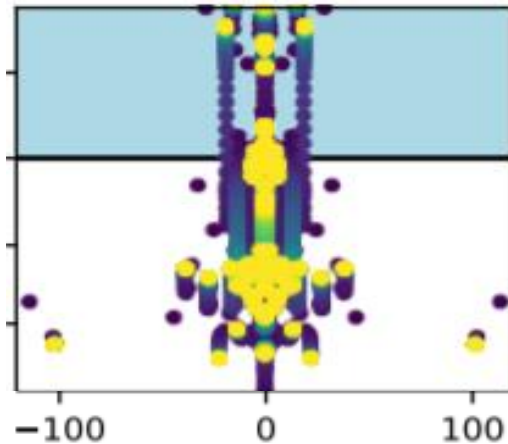
Super  
Parametrized



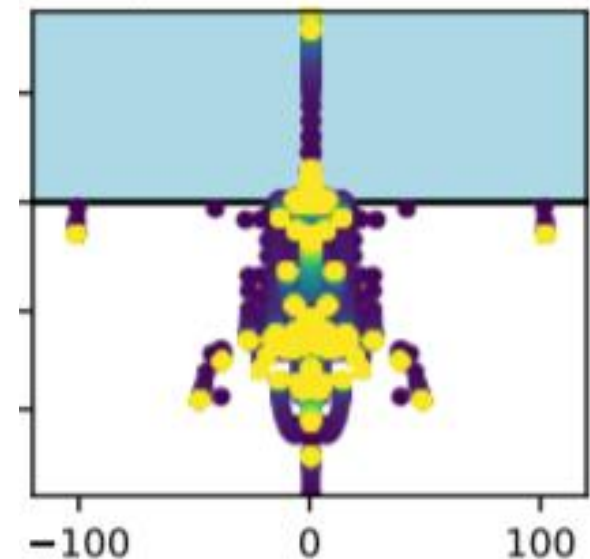
“Regularize” Inputs  
by adding  
Gaussian noise



Global  
Cloud-  
Resolving



Remove  
upper-atmospheric  
Inputs



# Engression: extrapolation through the lens of distributional regression

Xinwei Shen and Nicolai Meinshausen

Seminar für Statistik, Department of Mathematics, ETH Zürich, Zürich, Switzerland

Address for correspondence: Xinwei Shen, Seminar für Statistik, Department of Mathematics, ETH Zürich, Rämistrasse 101, 8092 Zürich, Switzerland. Email: [xinwei.shen@stat.math.ethz.ch](mailto:xinwei.shen@stat.math.ethz.ch)

## Progression: an extrapolation principle for regression

Gloria Buriticá

Université Paris-Saclay, AgroParisTech, INRAE, UMR MIA Paris-Saclay, 22 place de l'Agronomie  
91123 Palaiseau, France

Sebastian Engelke

Research Institute for Statistics and Information Science, University of Geneva, Boulevard du  
d'Arve 40, 1205 Geneva, Switzerland.

Journal of Advances in Modeling Earth Systems / Volume 14, Issue 9 / e2022MS003219

Research Article | [Open Access](#) |  

## Correcting a 200 km Resolution Climate Model in Multiple Climates by Machine Learning From 25 km Resolution Simulations

Spencer K. Clark , Noah D. Brenowitz, Brian Henn, Anna Kwa, Jeremy McGibbon, W. Andre Perkin,  
Oliver Watt-Meyer, Christopher S. Bretherton, Lucas M. Harris

First published: 02 September 2022

<https://doi.org/10.1029/2022MS003219>

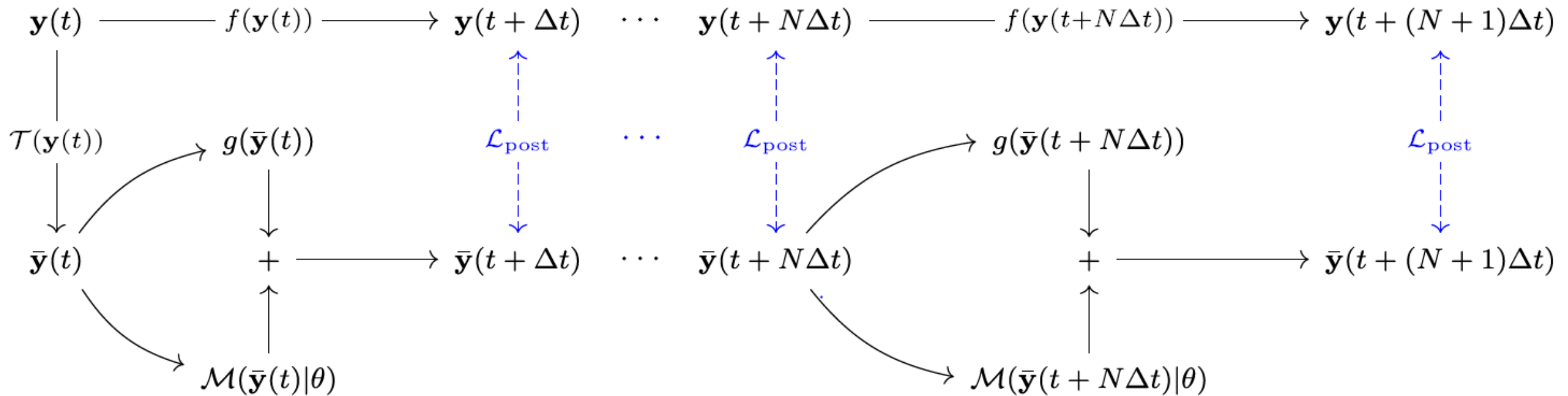
## 4) Many challenges remain unsolved:

1. Stability, extrapolation behavior, and recalibration of the host model

4) Many challenges remain unsolved:

1. Stability, extrapolation behavior, and **recalibration of the host model**

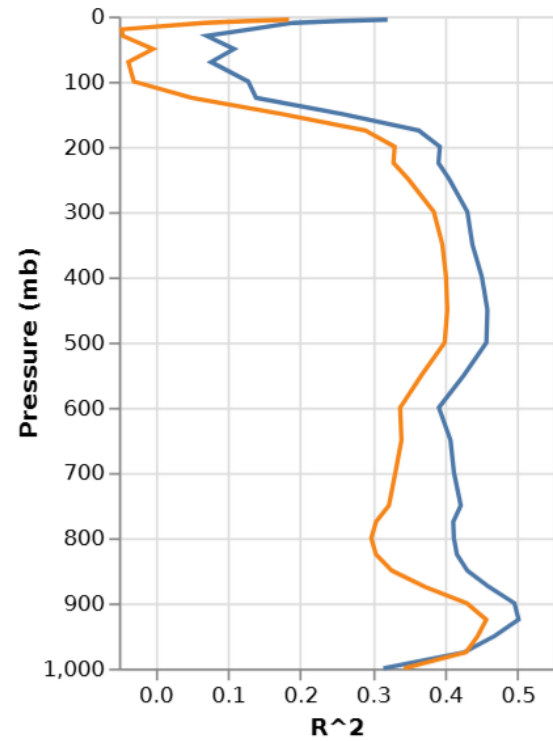
Offline Learning = Best fit given the collected data  
 Online Learning = Integrating dynamical model during training



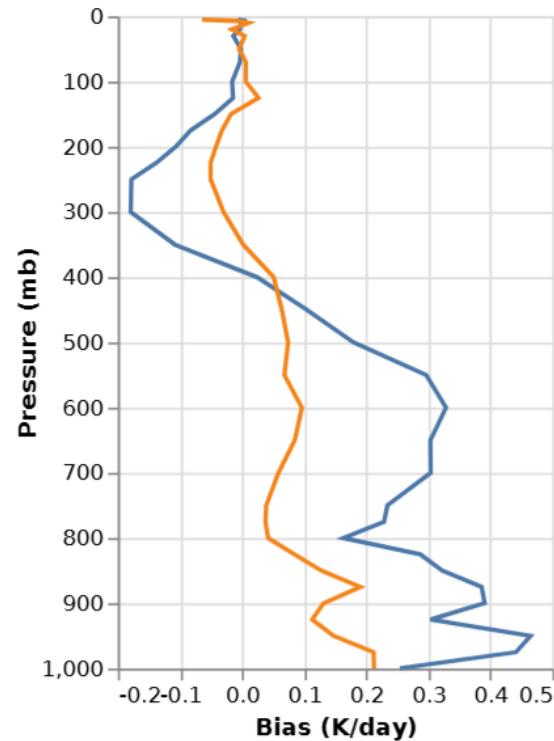


# Challenge: Offline & online objectives often misaligned in hybrid ESMs

a) Heating accuracy



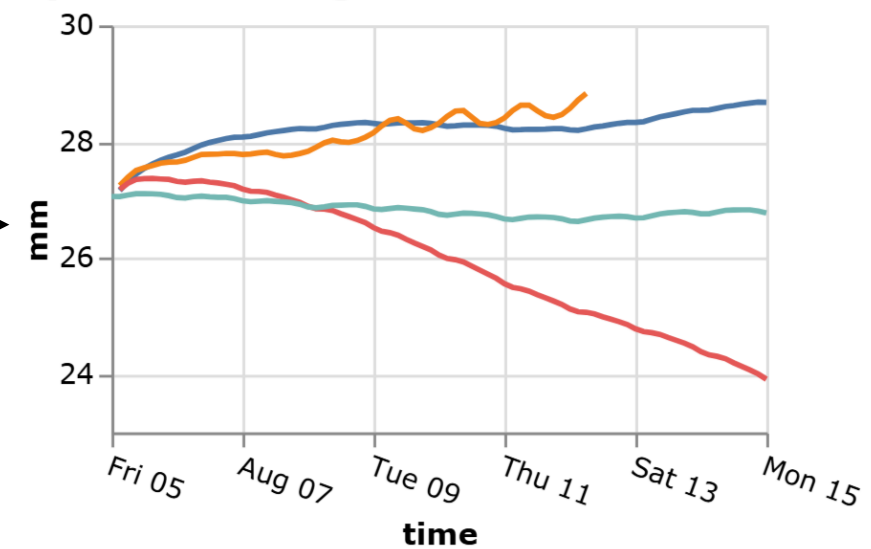
b) Heating Bias



model  
— NN  
— RF

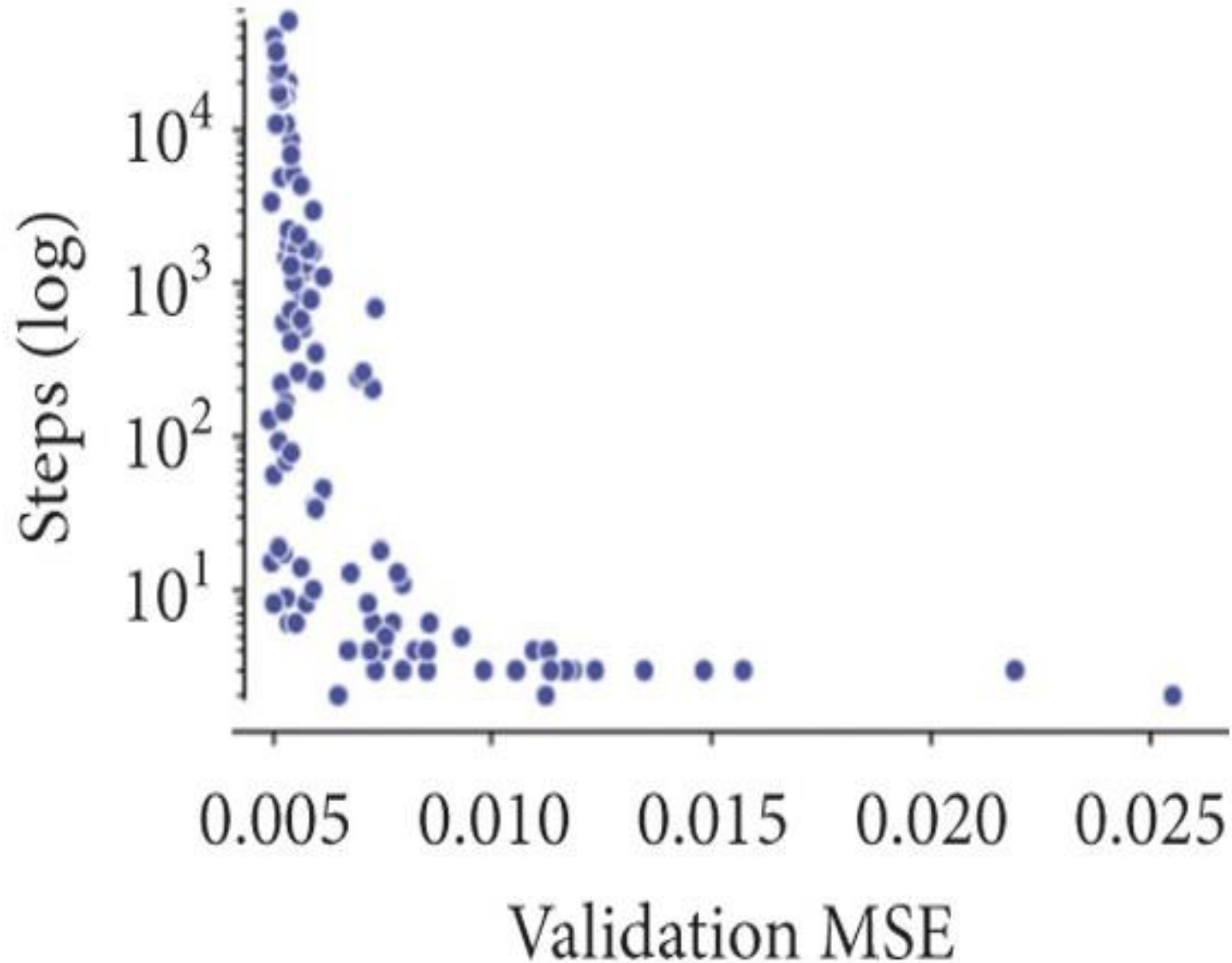


b) Global Average PW

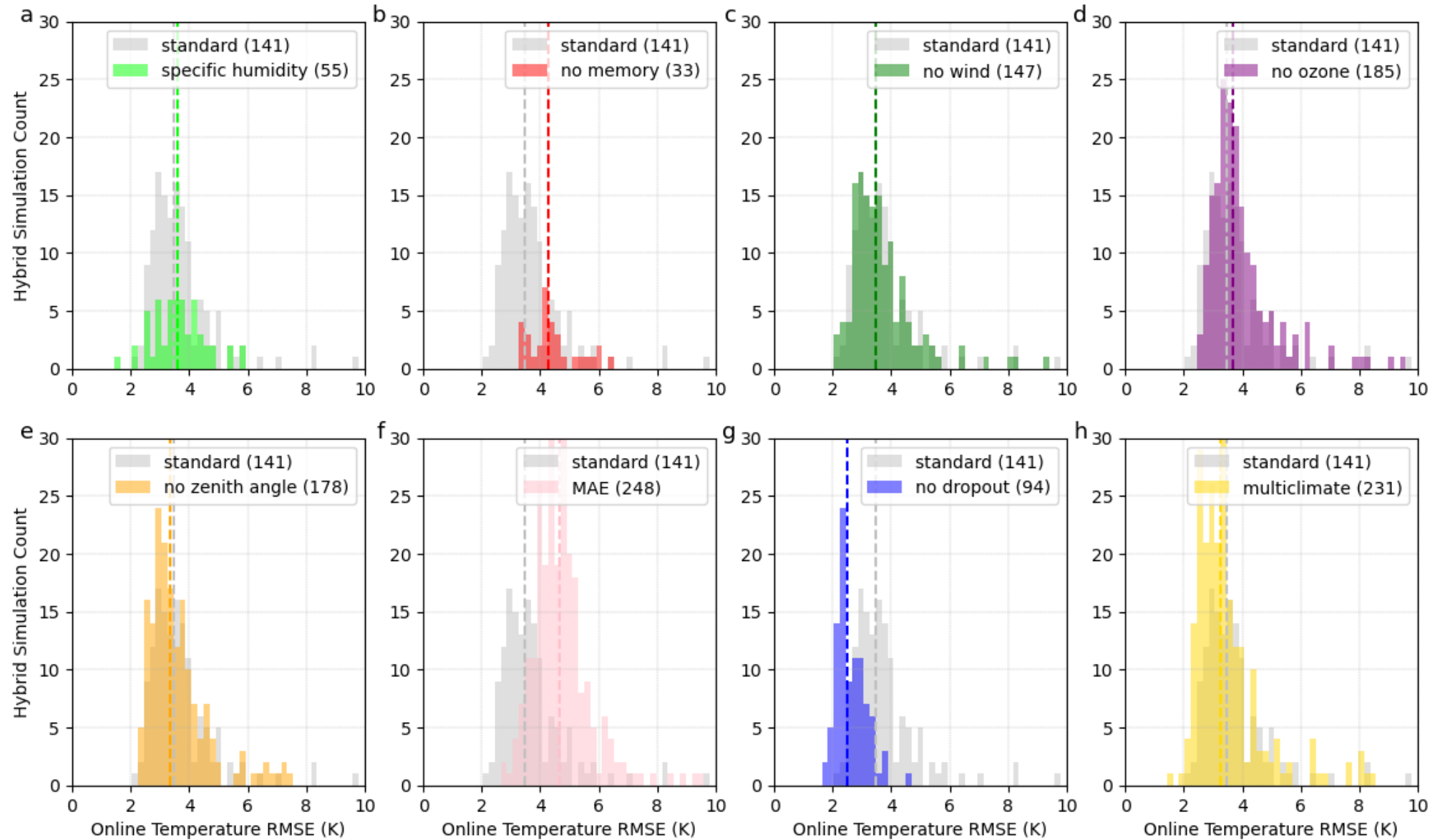


model  
— Baseline  
— NN  
— RF  
— Verification


## Challenge: Offline & online objectives often misaligned in hybrid ESMs



# Challenge: Offline & online objectives often misaligned in hybrid ESMs



## Online Learning of Entrainment Closures in a Hybrid Machine Learning Parameterization

Costa Christopoulos , Ignacio Lopez-Gomez, Tom Beucler, Yair Cohen, Charles Kawczynski, Oliver R. A. Dunbar, Tapio Schneider

First published: 14 November 2024

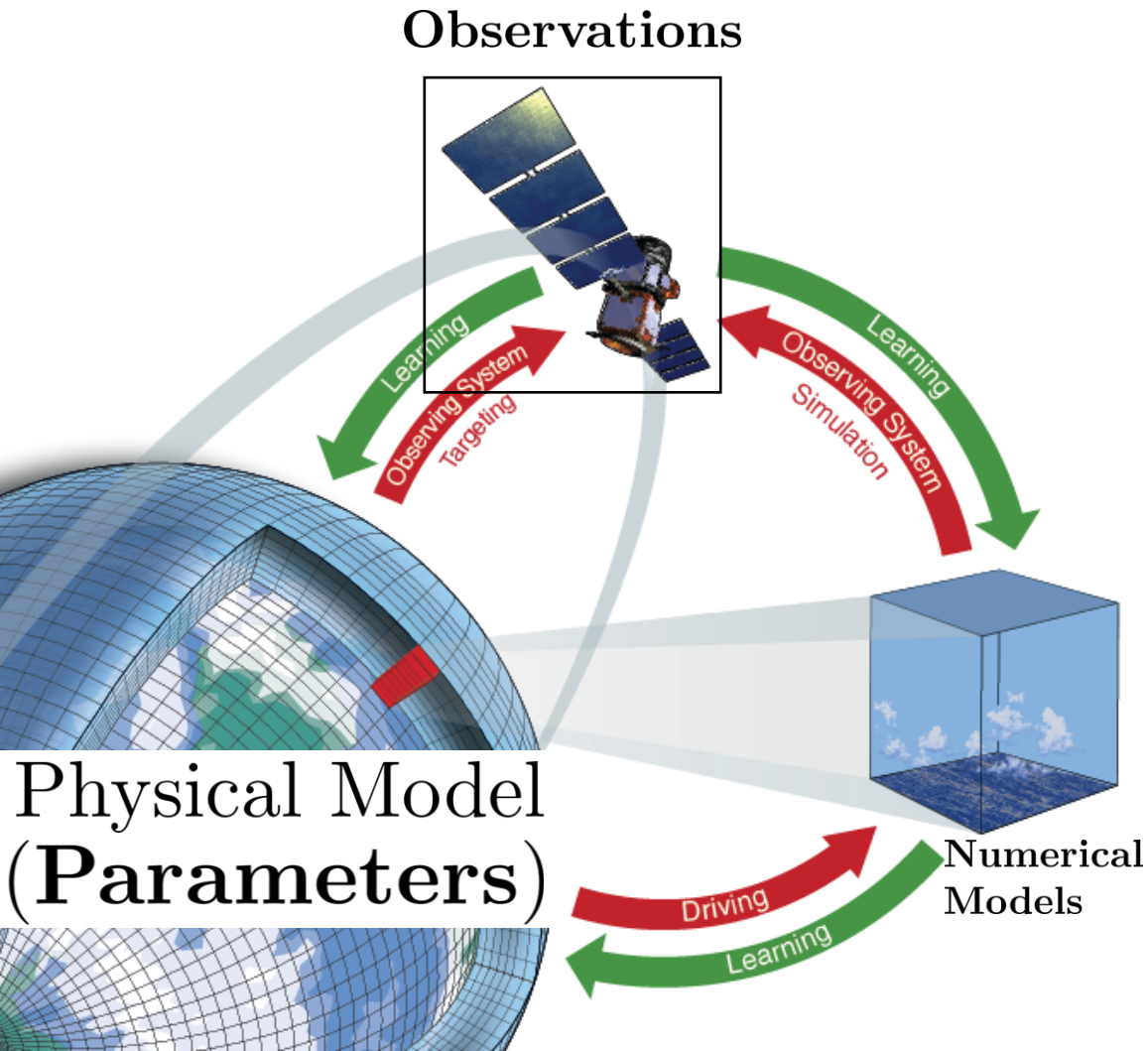
<https://doi.org/10.1029/2024MS004485>

# 4) Many challenges remain unsolved:

1. Stability, extrapolation behavior, and **recalibration of the host model**



# Strategy: Machine Learn Parameters of Physical Models



## Parameter estimation/calibration problem

Subfield of data assimilation = Optimal state estimation given real-time data

*See ECMWF resources on 4D-Var*

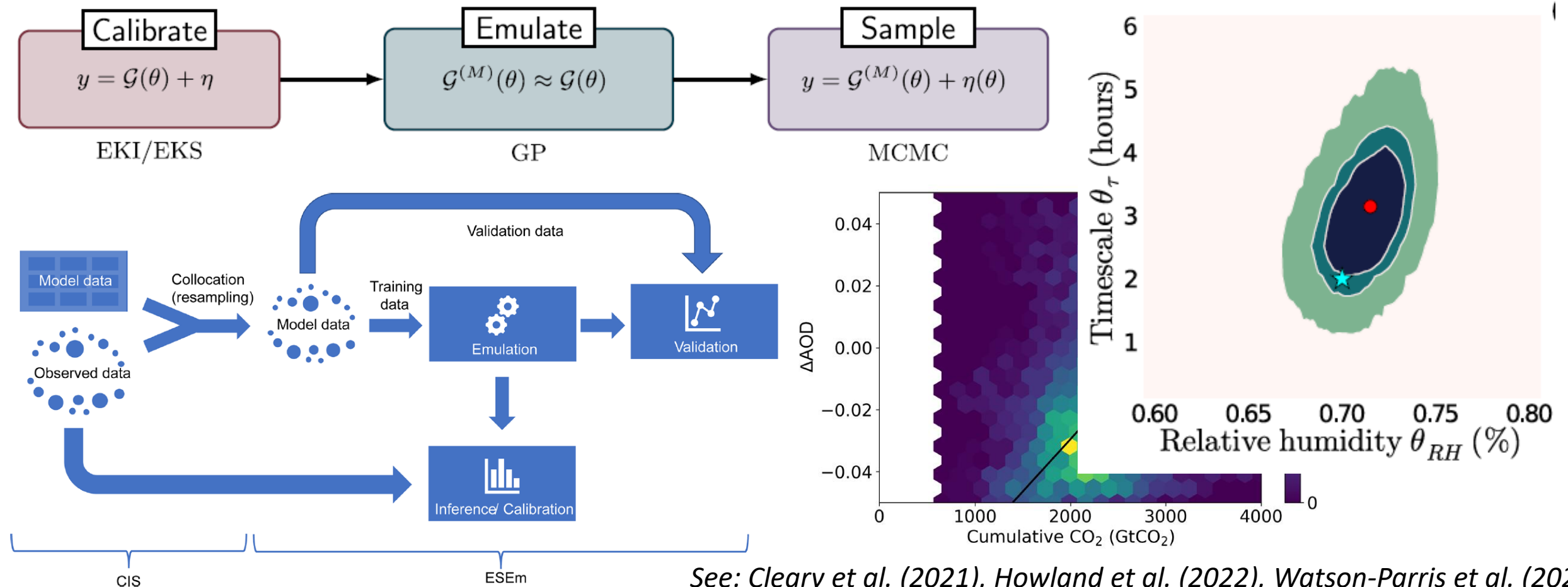
$p(\text{Parameters}|\text{Obs})$

ML helps maximize the likelihood

*See: Brajard et al. (2021), ECMWF Fact sheets; Image Source: CliMA*

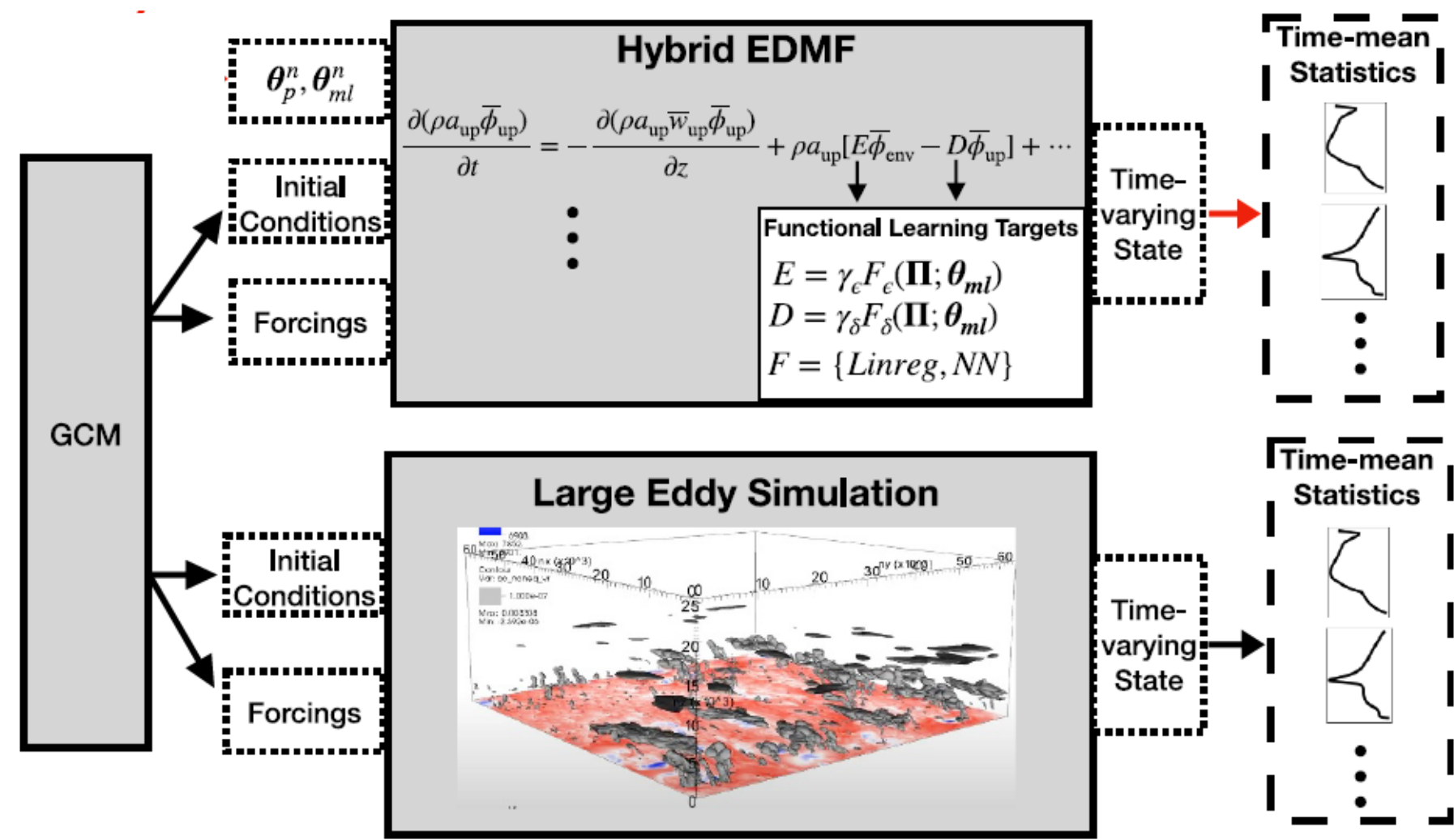
# Learn Parameters of Physical Models

## ML-based frameworks: CES & ESEm



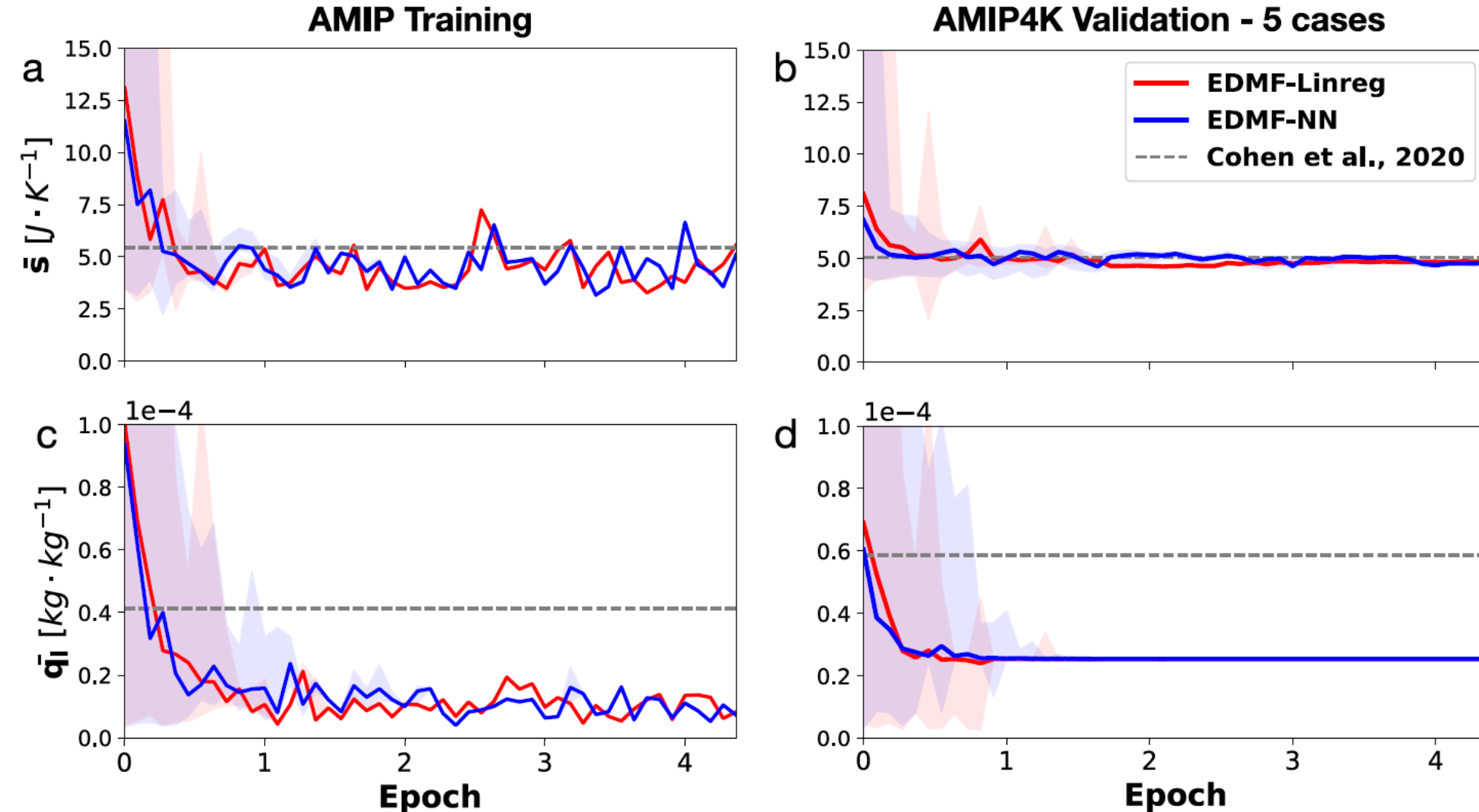
# Ensemble Kalman Inversion = Gradient-free, data-assimilation technique

Inverse problem framing: Direct learning from climate statistics



See: Christopoulos et al. (2024); Lopez-Gomez et al. (2022)

Advantages: Guaranteed stability once trained, +4K generalization  
Challenges: Cost, instability and host model issues during training




*See: Christopoulos et al. (2024)*





## Causally-Informed Deep Learning to Improve Climate Models and Projections

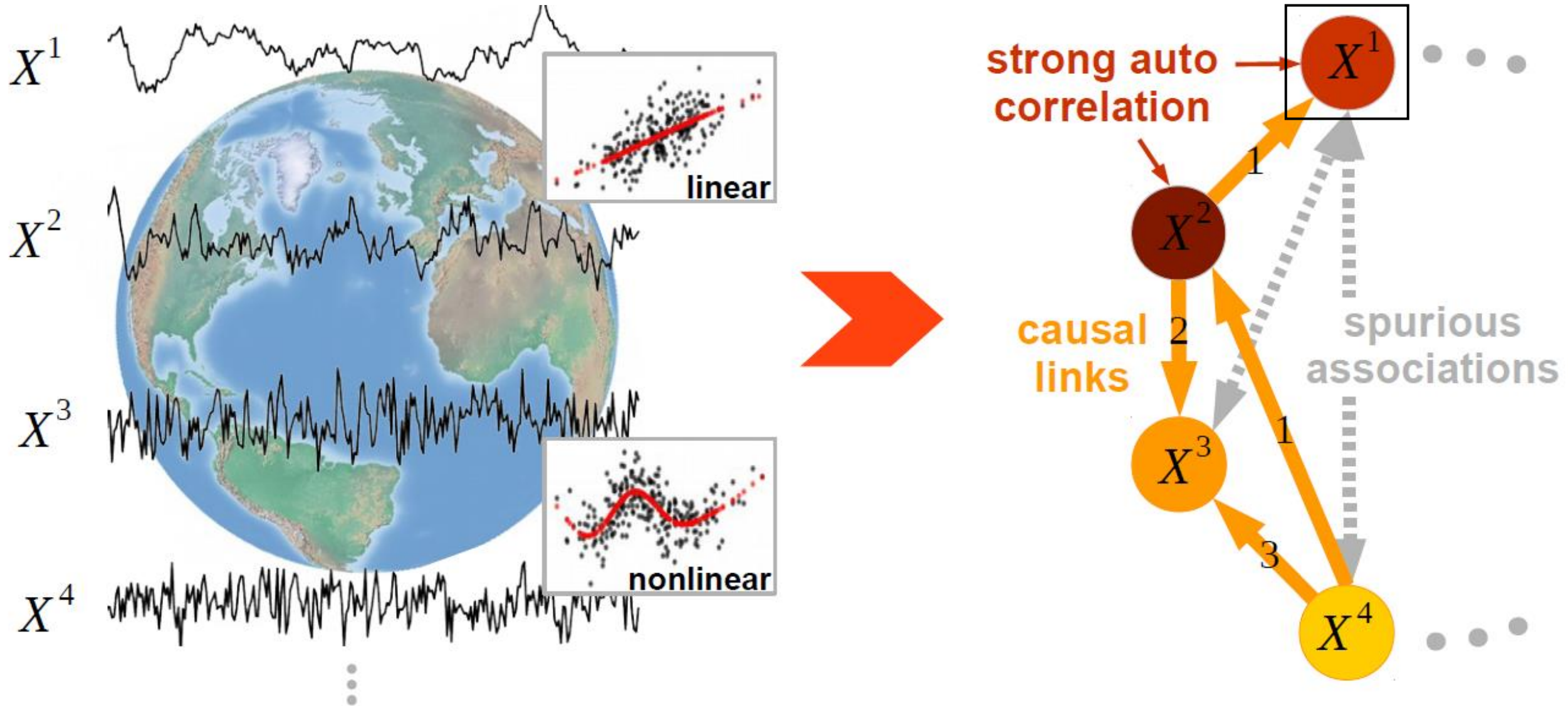
Fernando Iglesias-Suarez , Pierre Gentine, Breixo Solino-Fernandez, Tom Beucler, Michael Pritchard, Jakob Runge, Veronika Eyring

First published: 19 February 2024 | <https://doi.org/10.1029/2023JD039202> | Citations: 10

### 4) Many challenges remain unsolved:

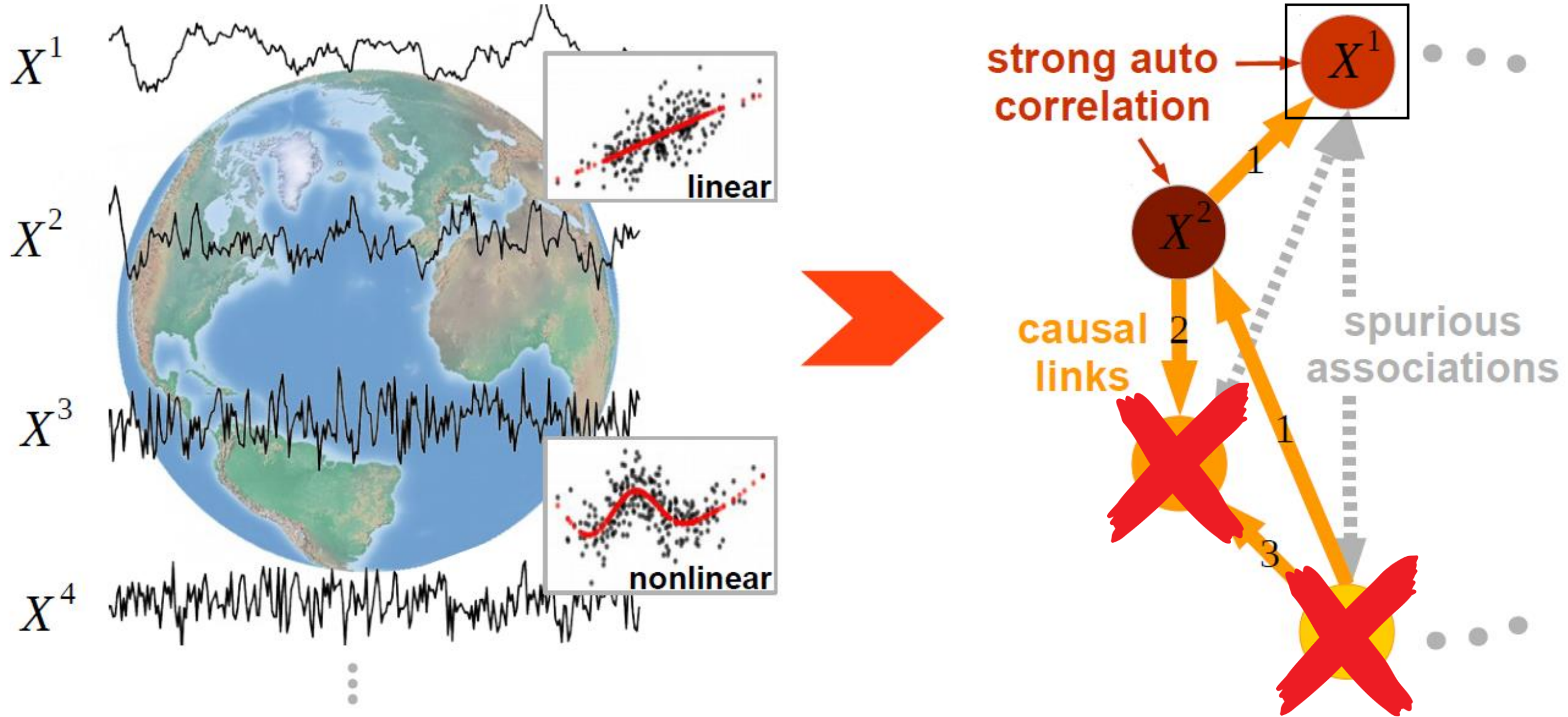
1. Stability, extrapolation behavior, and recalibration of the host model
2. Best way to incorporate causality?

# Can Causal Discovery Improve Parameterizations?



Source: Runge et al. (2019), See: Kretschmer et al. (2016), Runge et al. (2019), Spirtes & Glymour (1991)

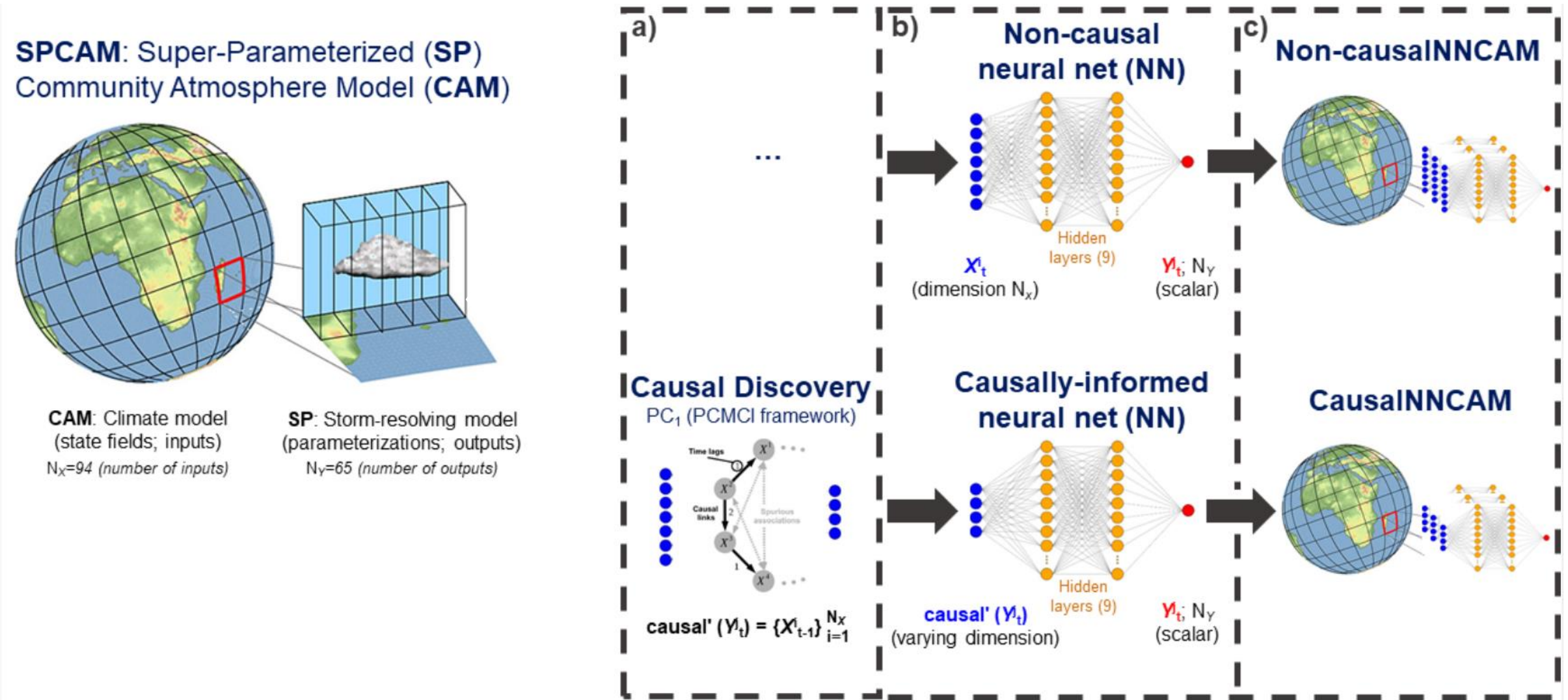
# Causal feature selection = Eliminating non-causal predictors



*See: Geiger et al. (1990), Pena et al. (2007), Gao and Ji (2017); Image source: Res*



# Causal feature selection improves the robustness & stability of hybrid climate-AI simulations





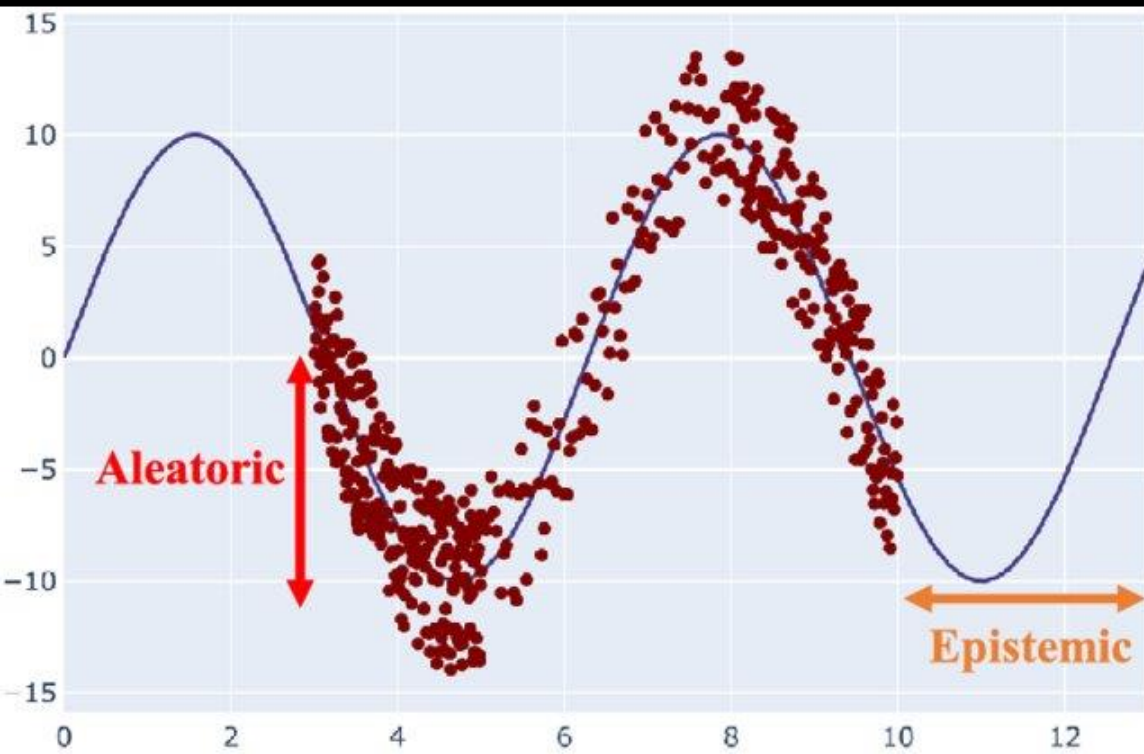
#### 4) Many challenges remain unsolved:

1. Stability, extrapolation behavior, and recalibration of the host model
2. Best way to incorporate causality?
3. Best way to incorporate and evaluate stochasticity?

When given an input, **generative** models predict **distributions** of outputs rather than a single output vector

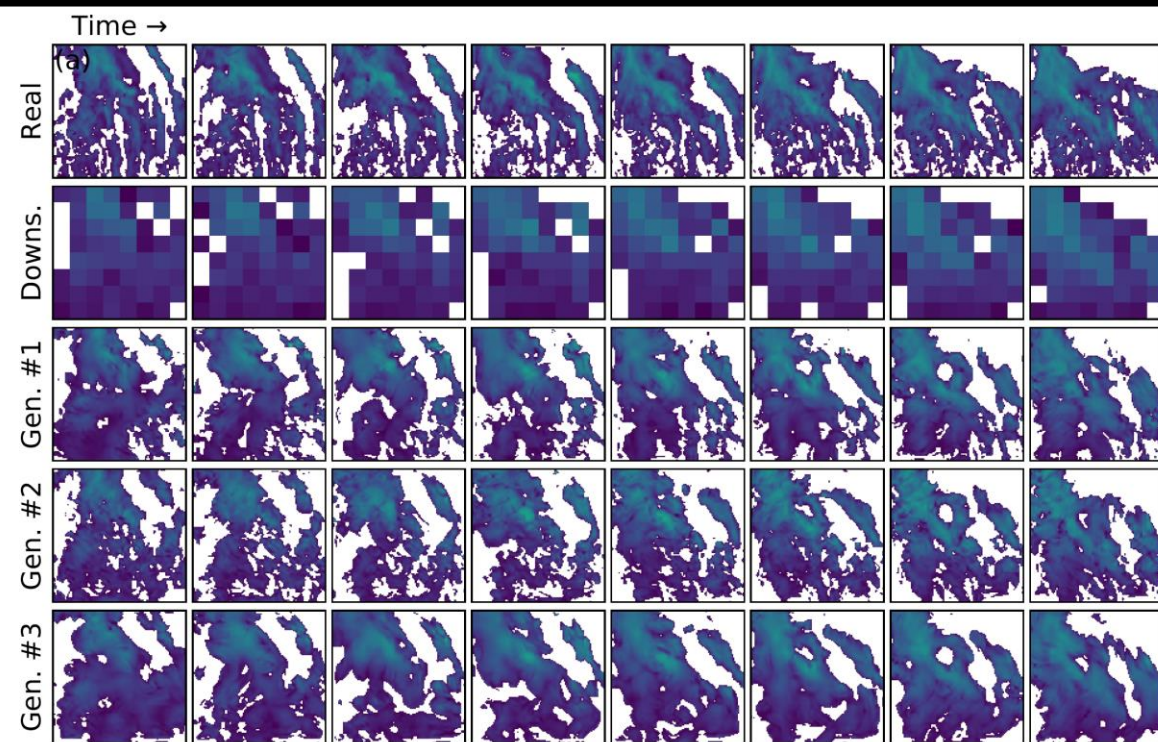
A **generative model** is a **statistical model** of the **joint probability distribution**  $P(X, Y)$  on given **observable variable**  $X$  and **target variable**  $Y$ ;[1]

## Uncertainty Quantification



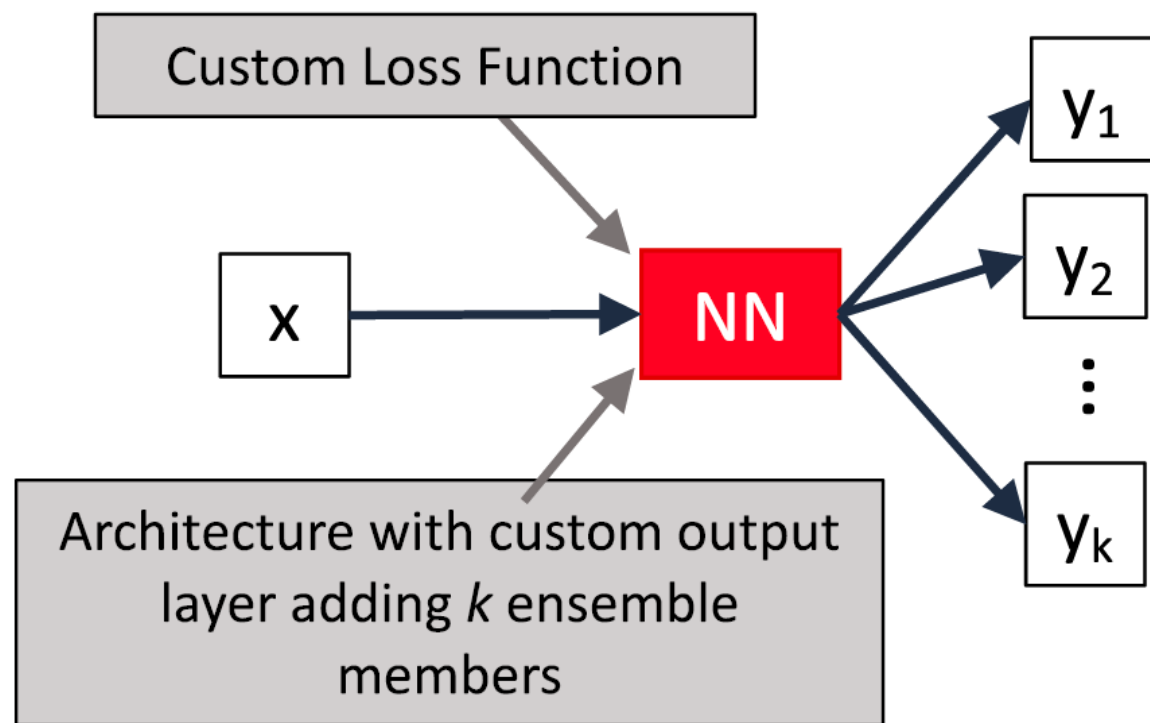
Abdar et al. (2021)

## Stochastic Modeling

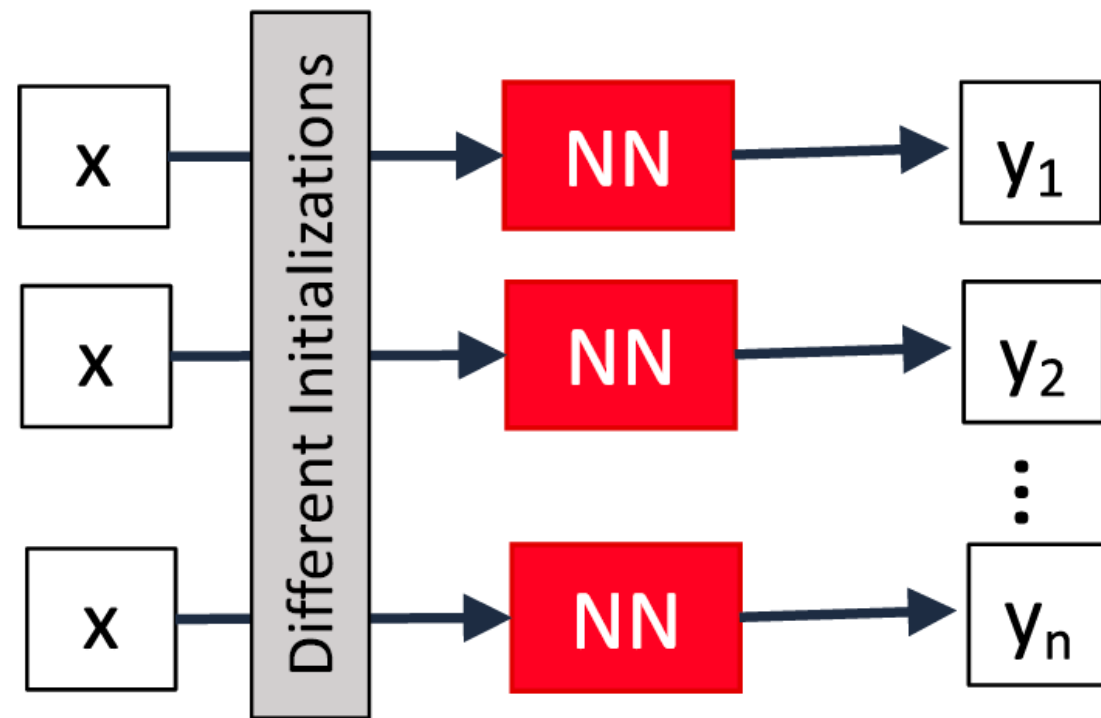


# In practice, there are many ways of adding UQ!

## Ensemble Prediction (EP)

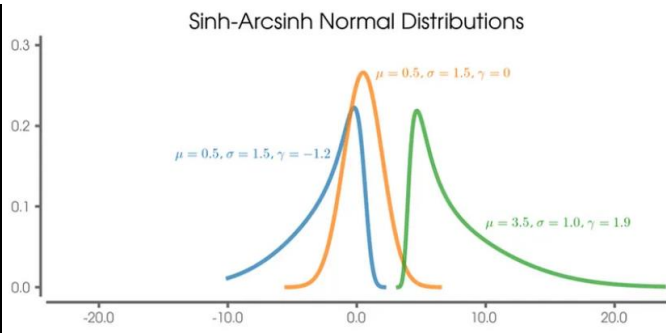
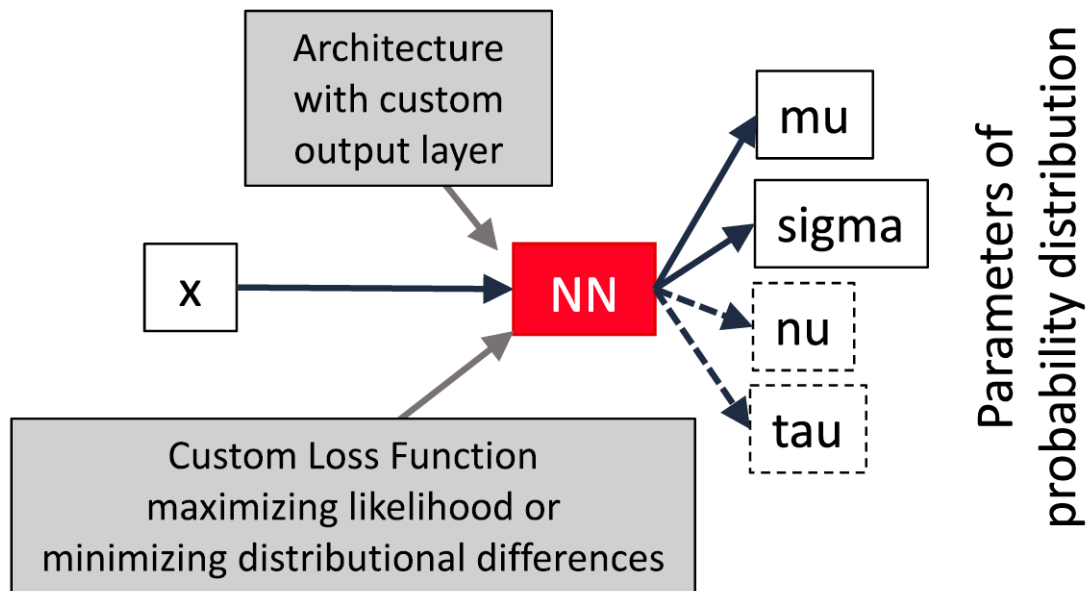


## Multi-Model (MM)

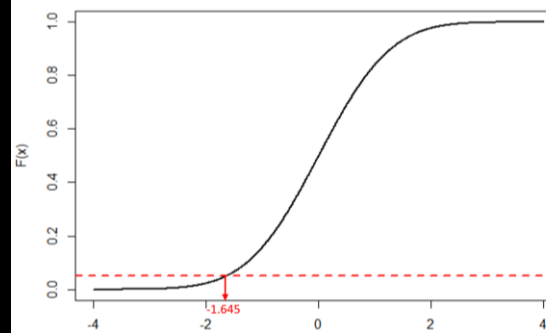
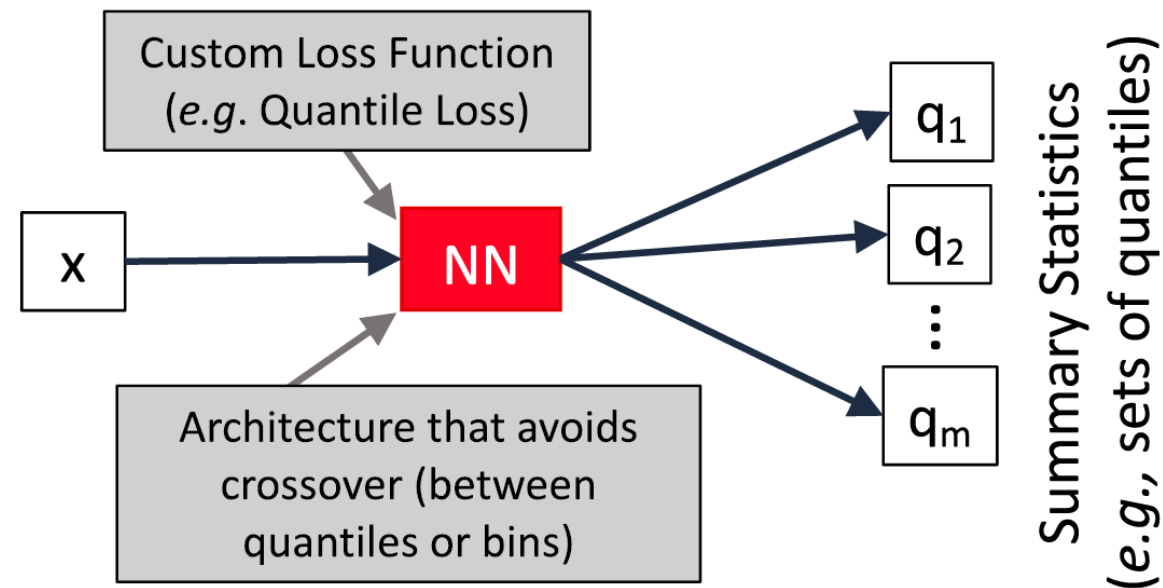


# In practice, there are many ways of adding UQ!

## Parametric Distributional Prediction (PDP)



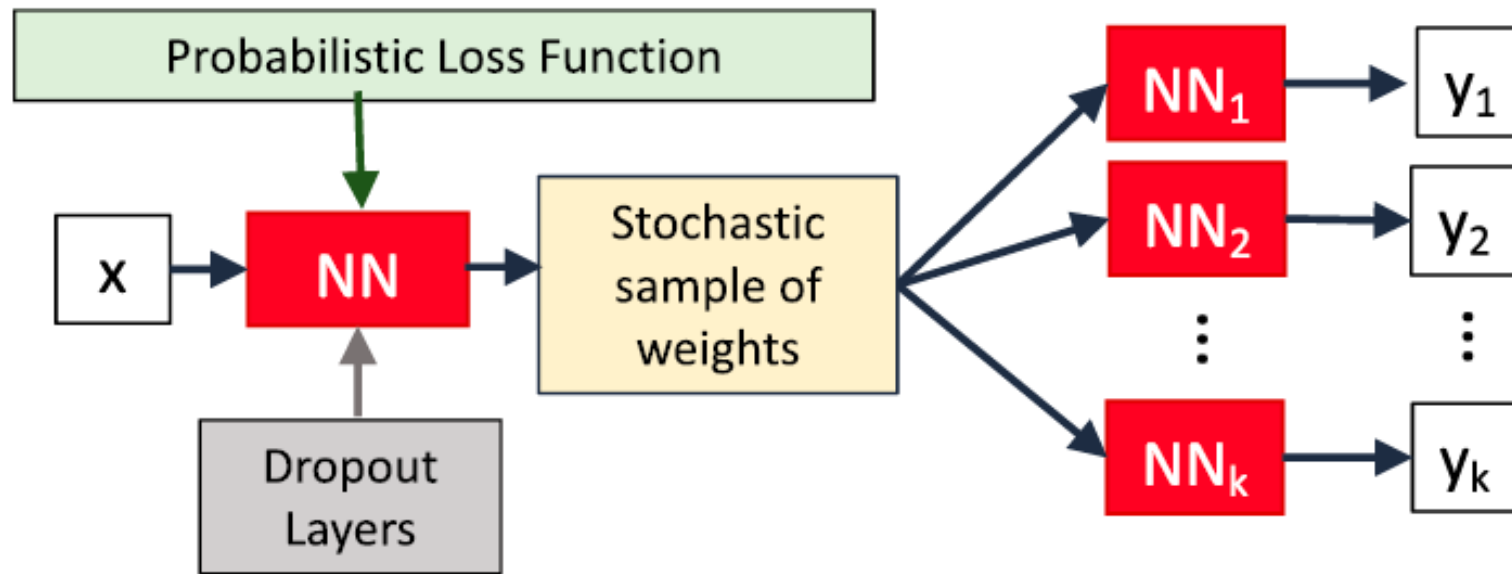
## Non-Parametric Distributional Prediction (NPDP)





# MC-Dropout randomly drops neural connections (Training) Regularization & (Test time) UQ

## Monte Carlo (MC) Dropout

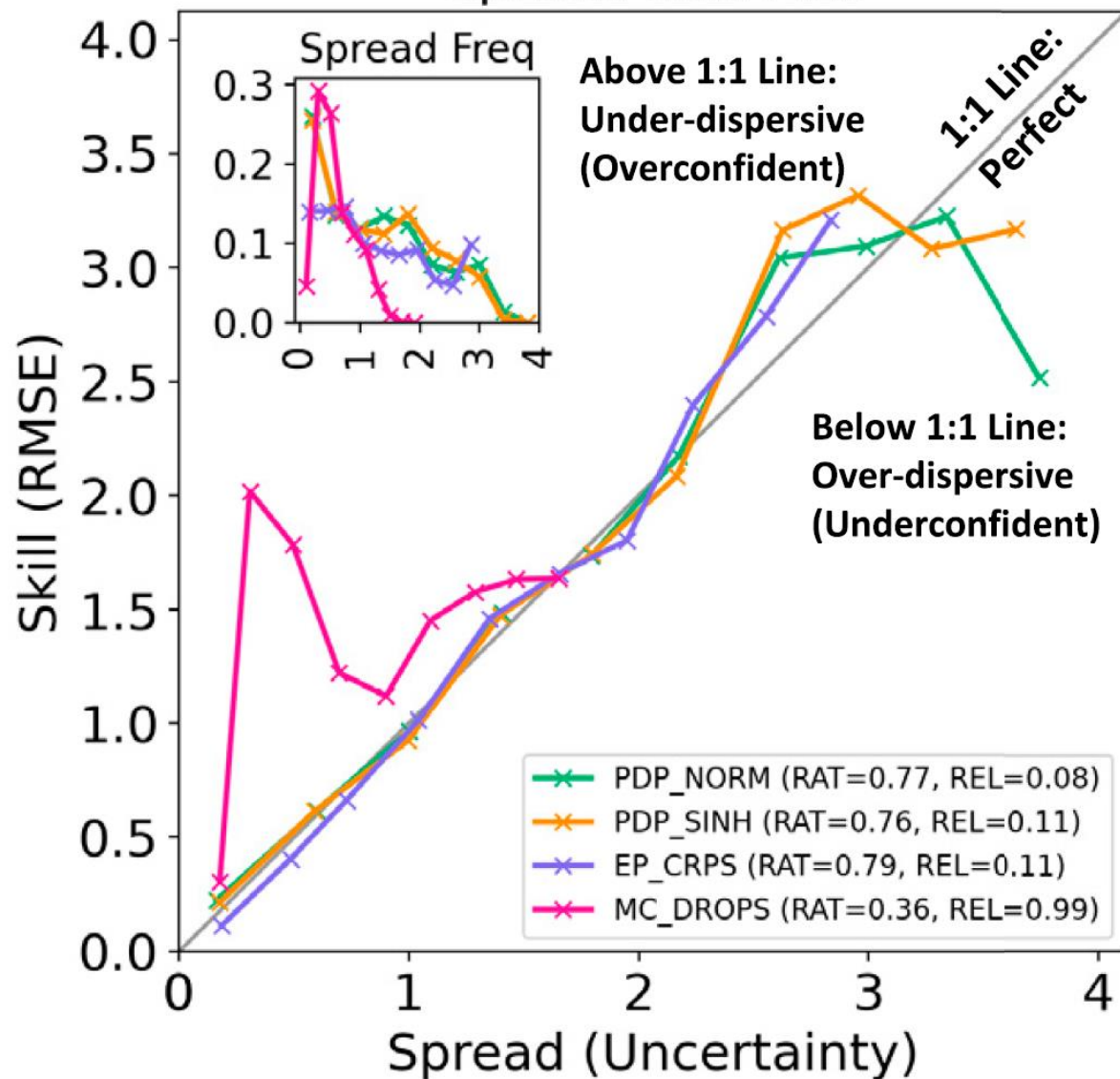


Ensemble of deterministic  
predictions  
[probabilistic predictions]

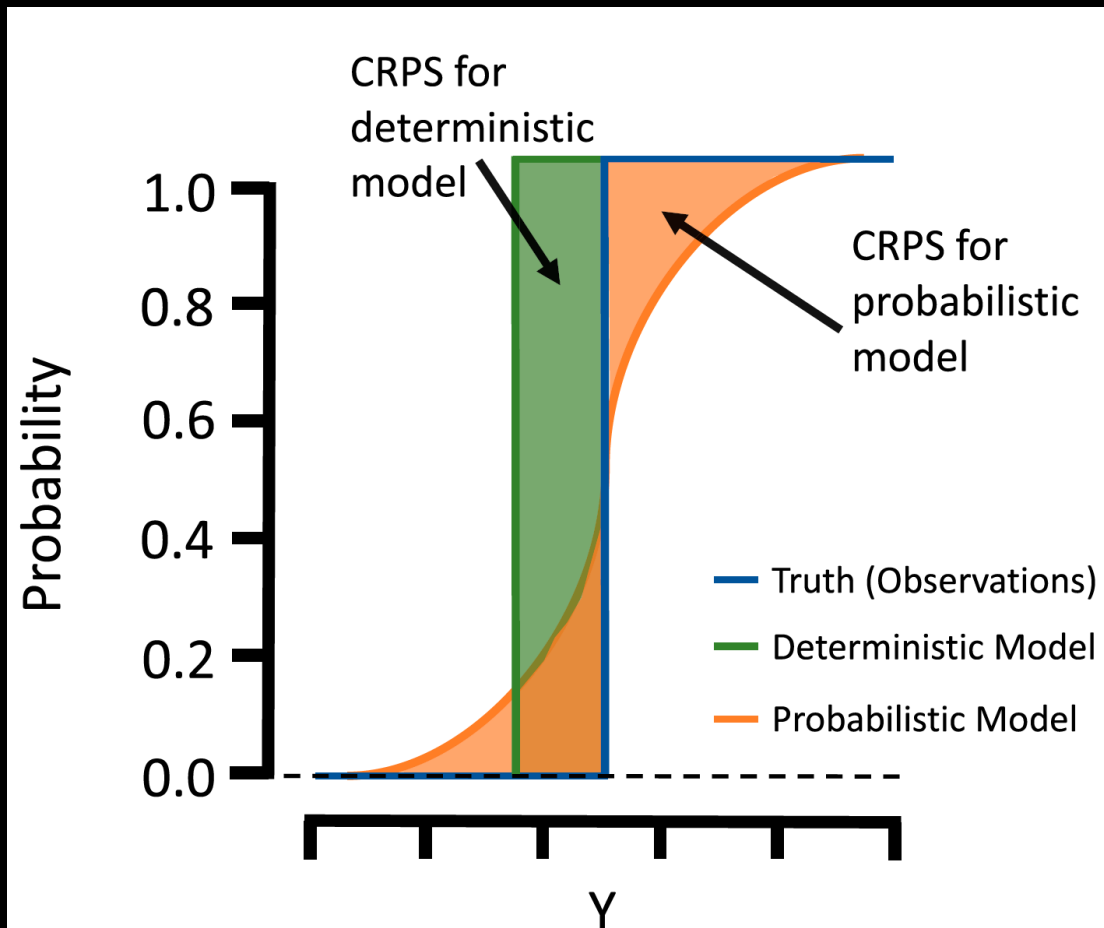
This block contains three screenshots of documentation for the Dropout layer in different deep learning frameworks:

- Keras:** Shows the 'Dropout layer' documentation, including the `Dropout` class and the `keras.layers.Dropout` function signature.
- PyTorch:** Shows the 'DROPOUT' documentation, including the `torch.nn.Dropout` class and the `torch.nn.Dropout(p=0.5, inplace=False)` function signature.
- TensorFlow:** Shows the 'Dropout' documentation, including the `tf.keras.layers.Dropout` class and the `tf.keras.layers.Dropout` function signature.

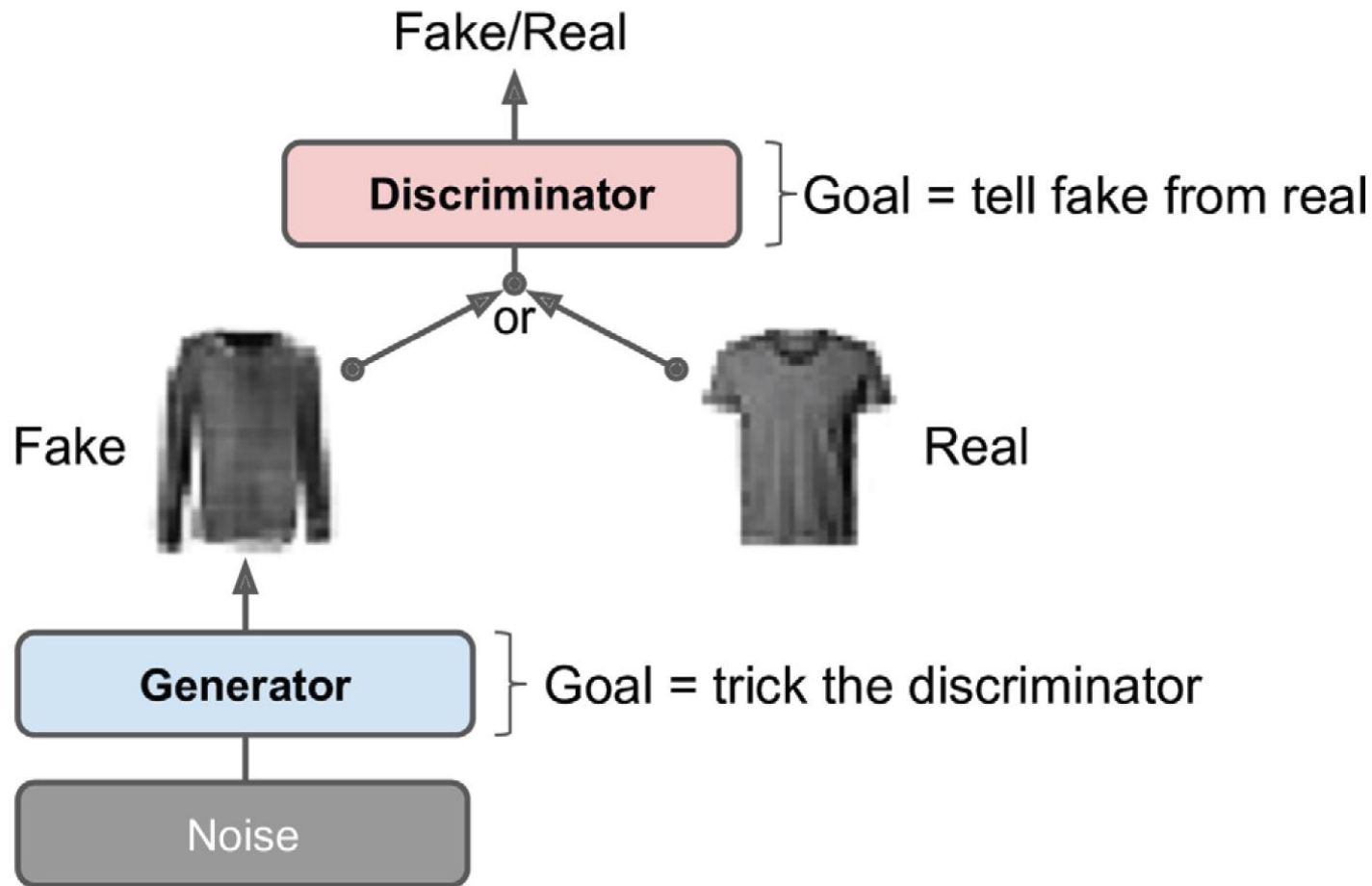
Spread-Skill Plot



Spread-Skill Plot and CRPS\*  
evaluate the generated distribution  
\*(Continuous Ranked Prob. Score)



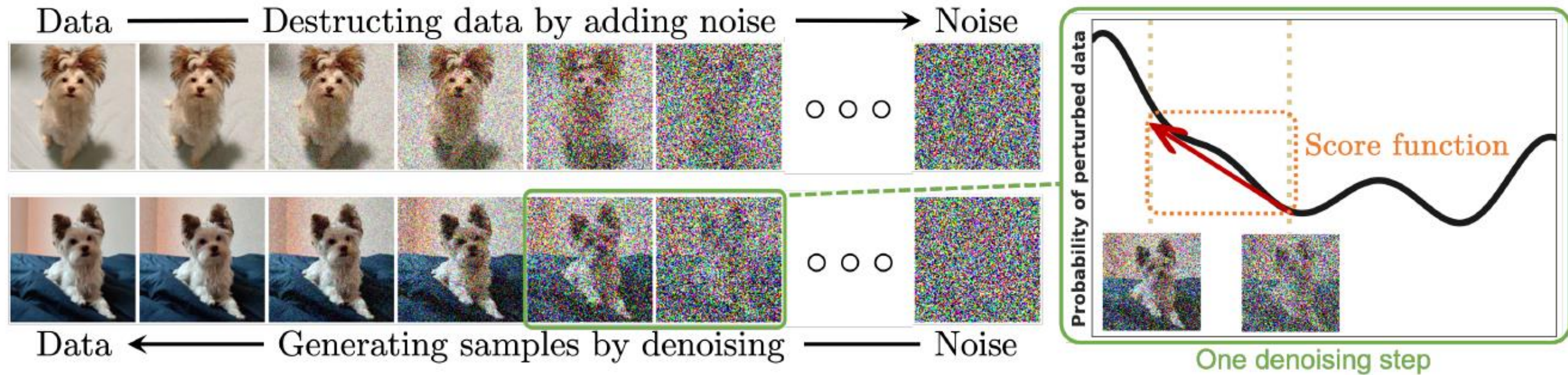
# 1) Generative Adversarial Nets pit a generator (fed noise) against a discriminator (fed the fake or real images)



*Géron textbook, Wikipedia (GAN),  
Bodla et al. (2018)*



2) Diffusion Probabilistic Models smoothly perturb data by adding noise, then reverse this process to generate new data from noise.



**Keras**

Star 57,559

About Keras

Getting started

Developer guides

Keras API reference

Code examples

Search Keras documentation...

» Code examples / Generative Deep Learning / Denoising Diffusion Implicit Models

## Denoising Diffusion Implicit Models

Author: András Béres

Date created: 2022/06/24

Last modified: 2022/06/24

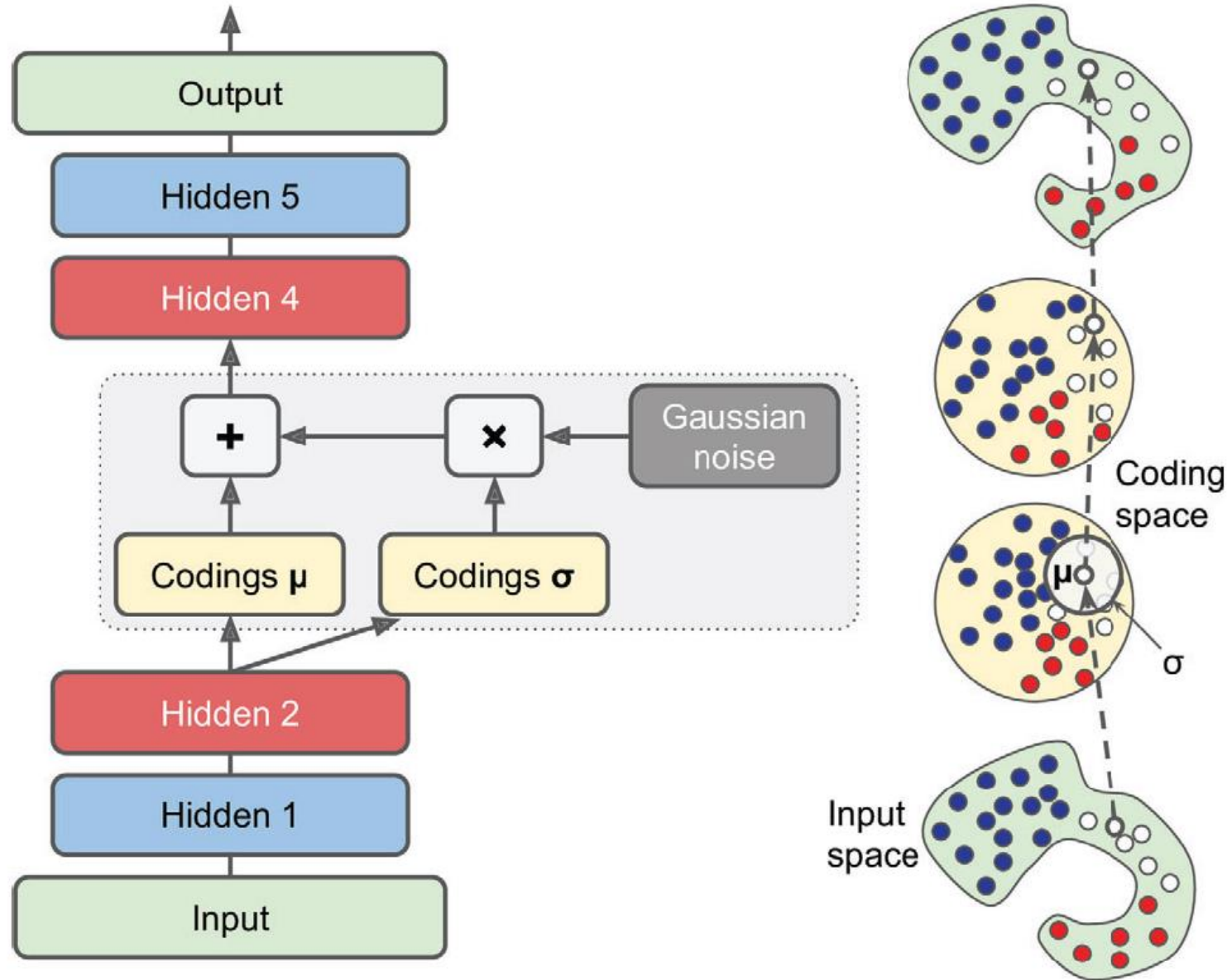
Description: Generating images of flowers with denoising diffusion implicit models.

View in Colab · GitHub source

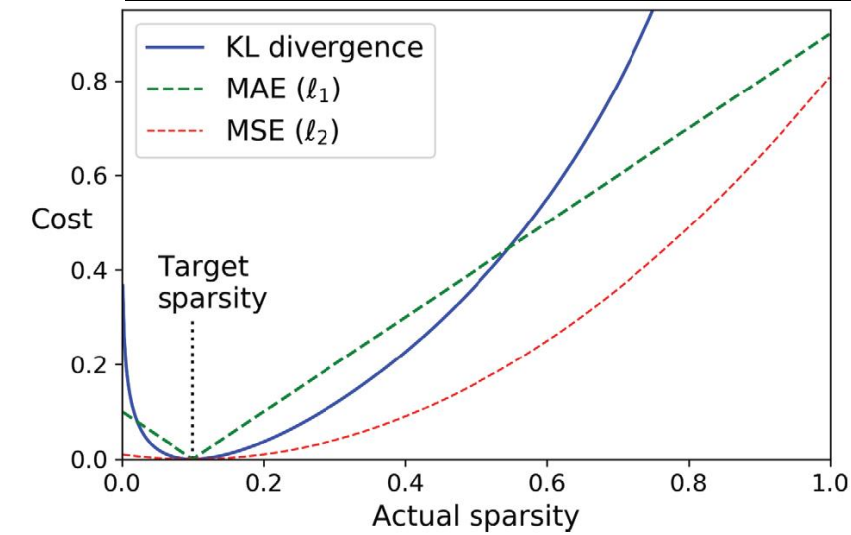
**Difusers**

license Apache-2.0 release v0.14.0 Contributor Covenant 2.0

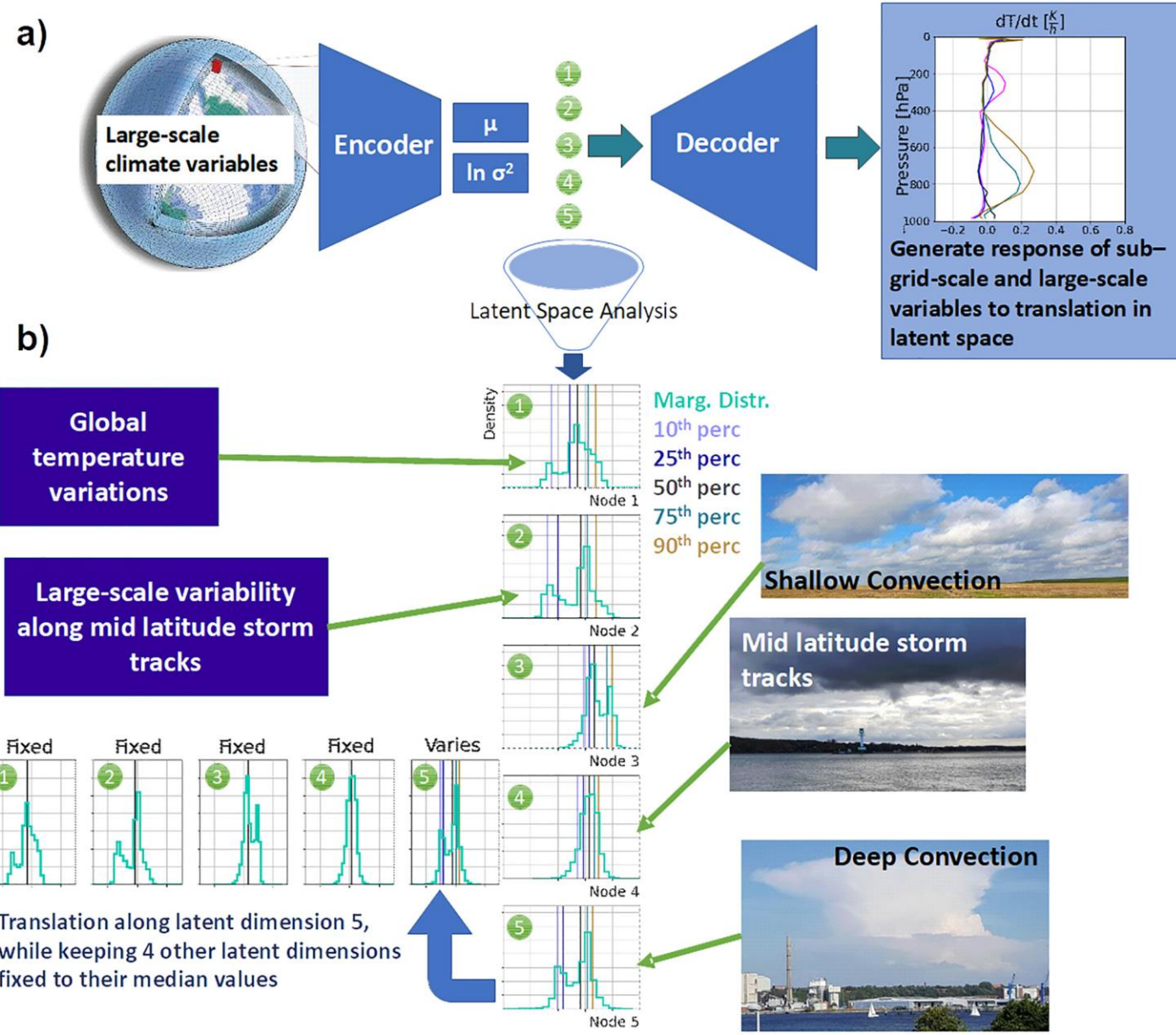
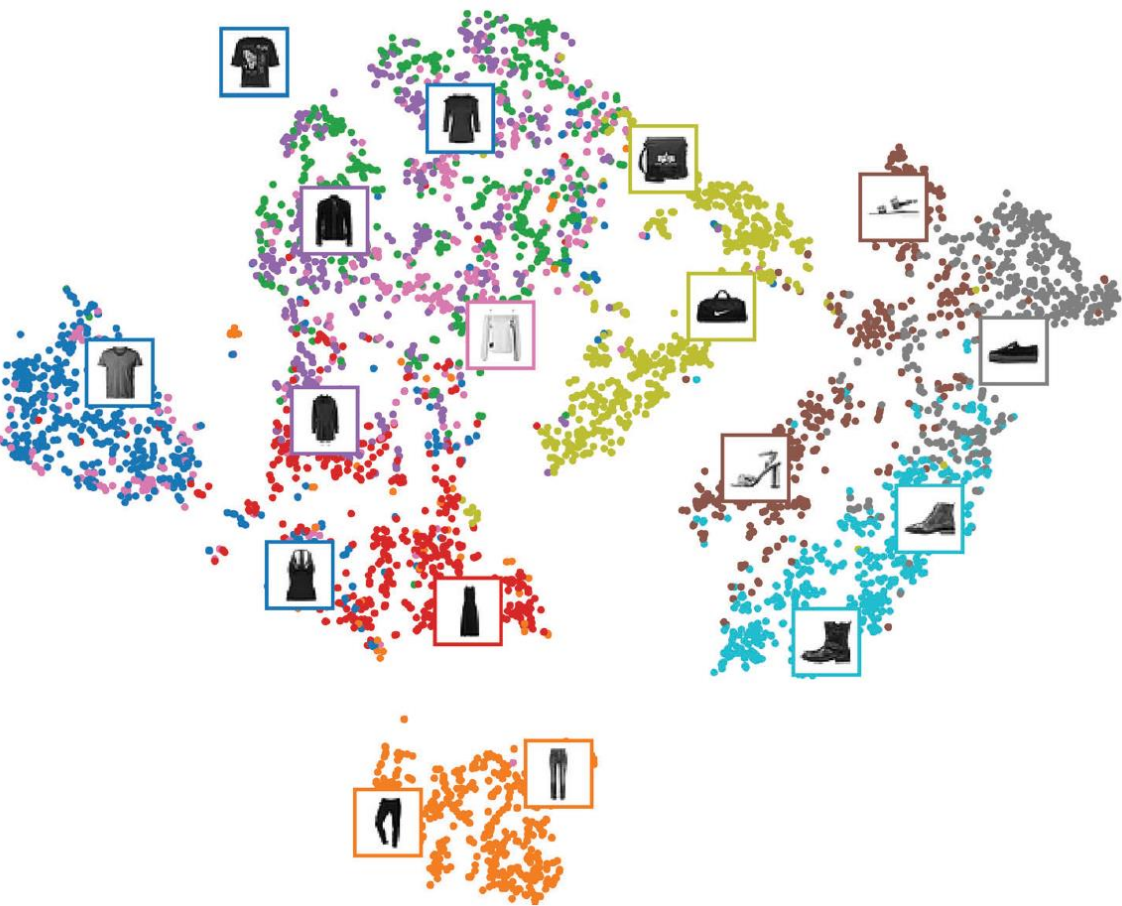




3) Variational Autoencoders probabilistically encode/decode data from *latent representations*

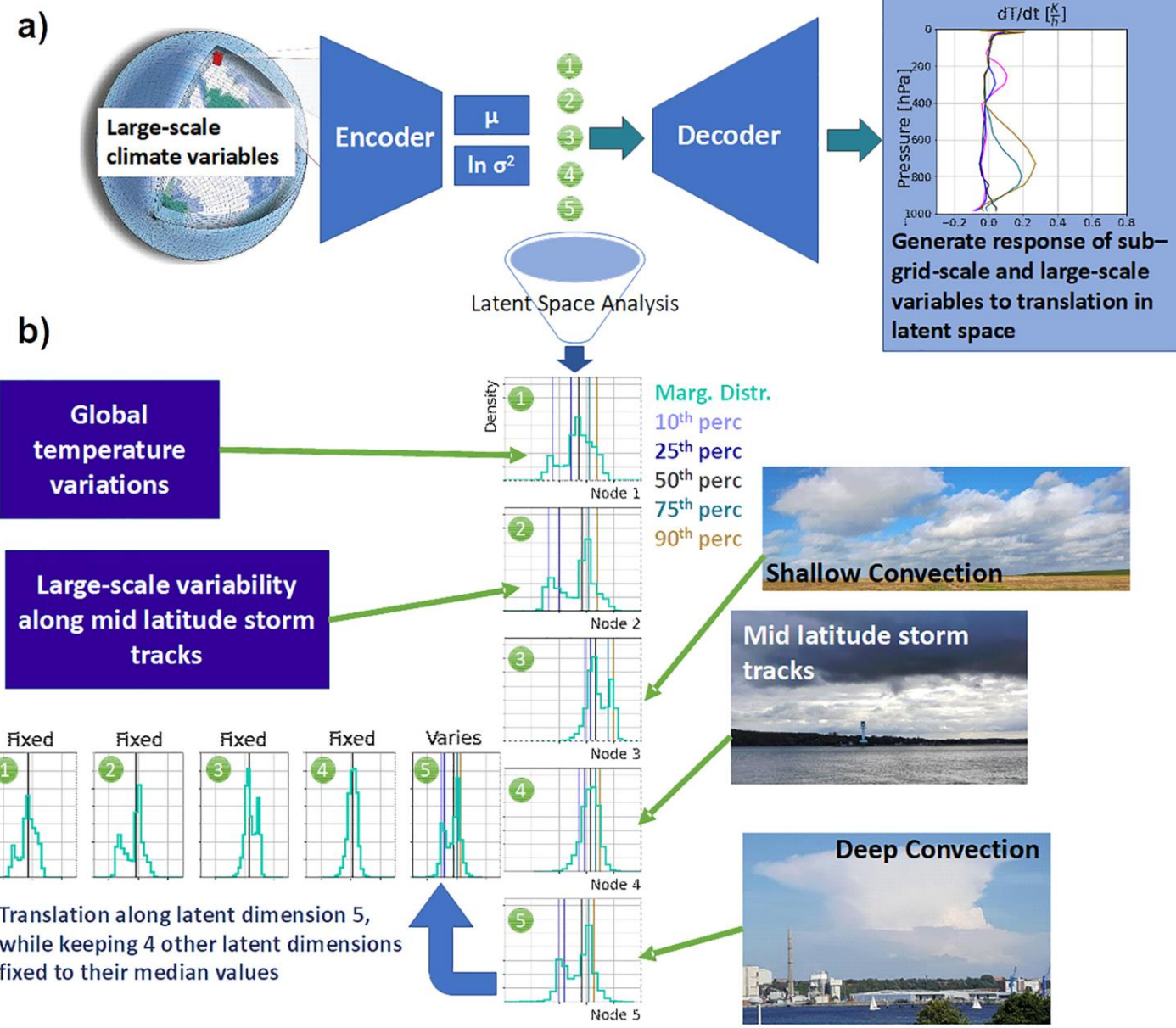
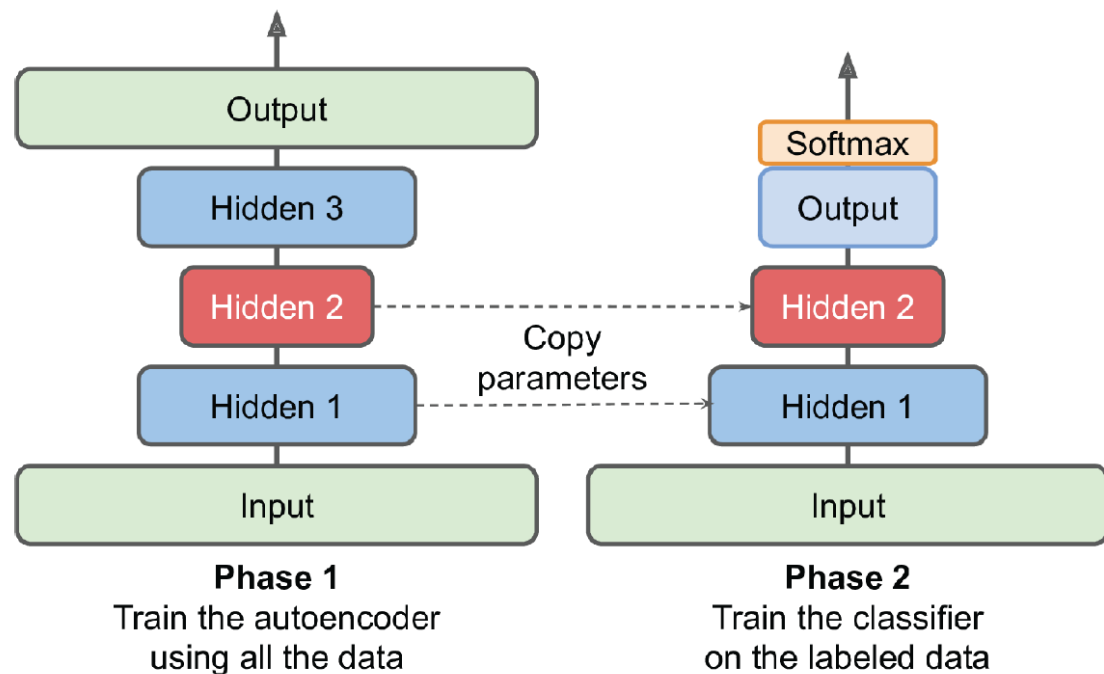


# Latent manifold or “Latent space”






Latent manifolds can be used for e.g.,  
scientific analysis and  
semi-supervised learning



Research Article |  **Open Access** |  

# Simulating Atmospheric Processes in Earth System Models and Quantifying Uncertainties With Deep Learning Multi-Member and Stochastic Parameterizations

Gunnar Behrens , Tom Beucler, Fernando Iglesias-Suarez, Sungduk Yu, Pierre Gentine, Michael Pritchard, Mierk Schwabe, Veronika Eyring

First published: 13 April 2025

<https://doi.org/10.1029/2024MS004272>

## 4) Many challenges remain unsolved:

1. Stability, extrapolation behavior, and recalibration of the host model
2. Best way to incorporate causality?
3. Best way to incorporate and evaluate stochasticity?



## ICTP25: Hybrid AI-Climate Modeling

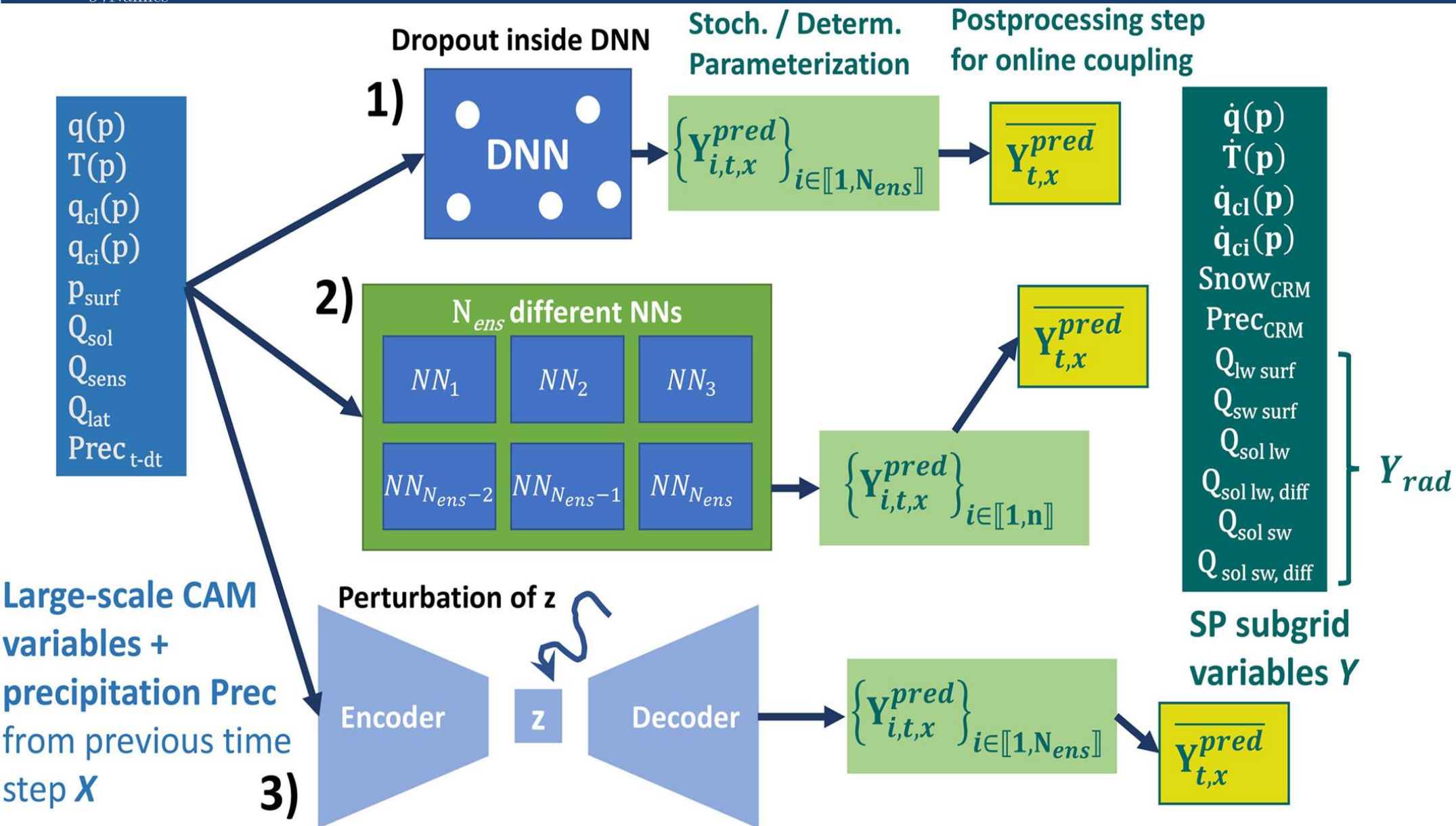
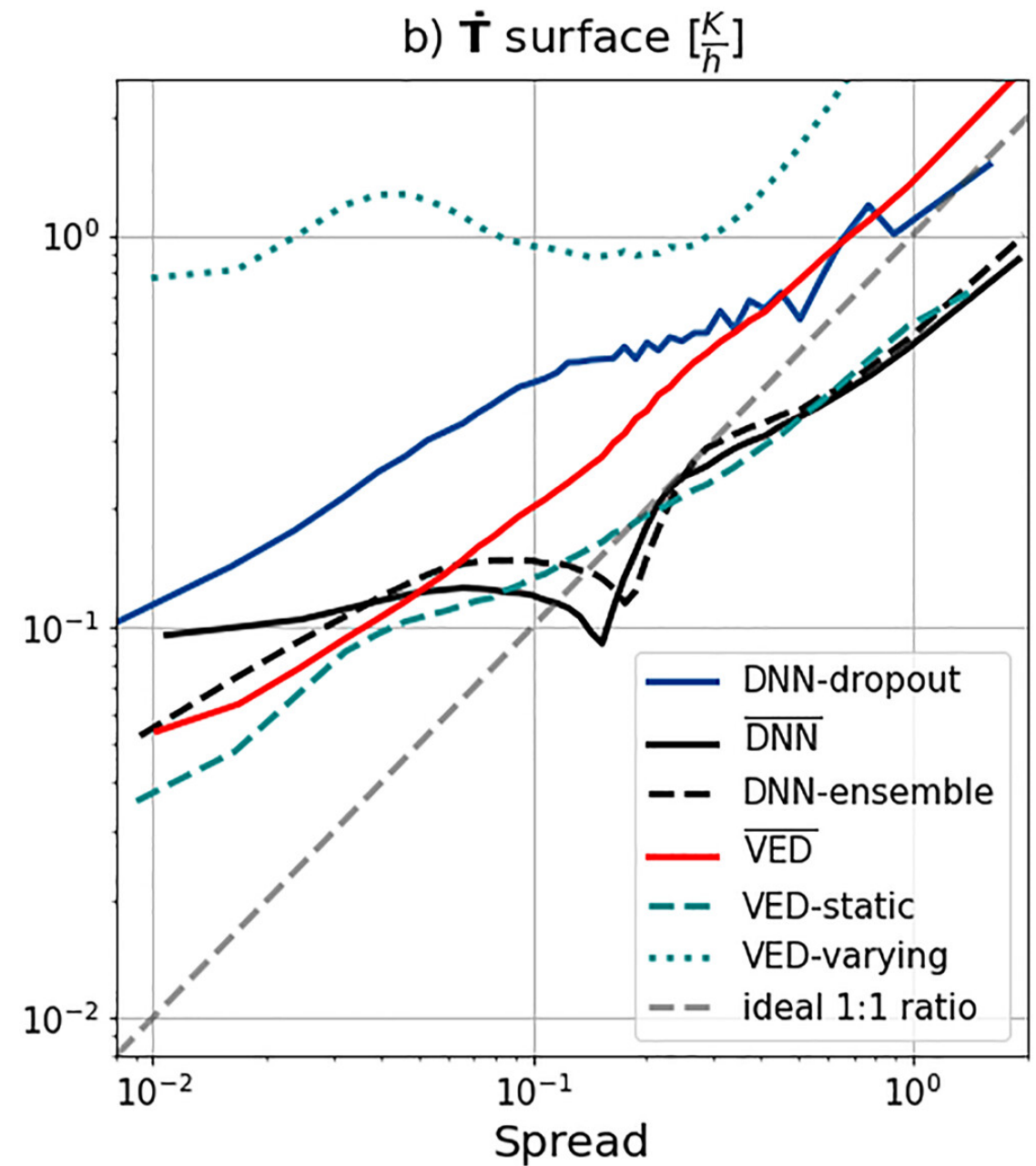


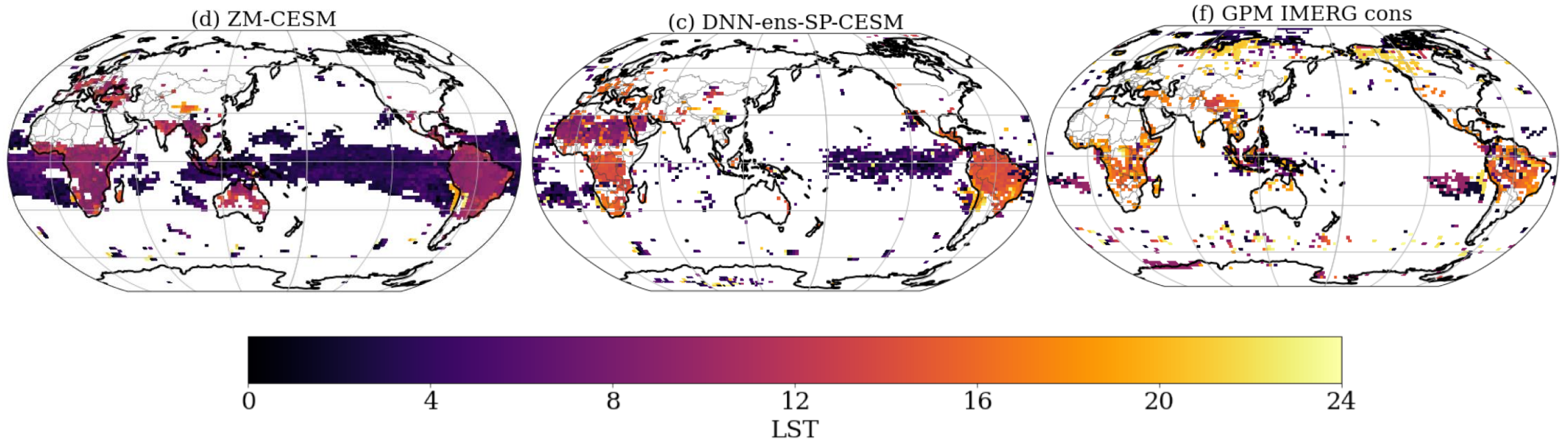
Figure: Behrens  
et al. (2025)

ANN ensembles and latent space perturbations lead to well-calibrated uncertainty **offline**

RMSE



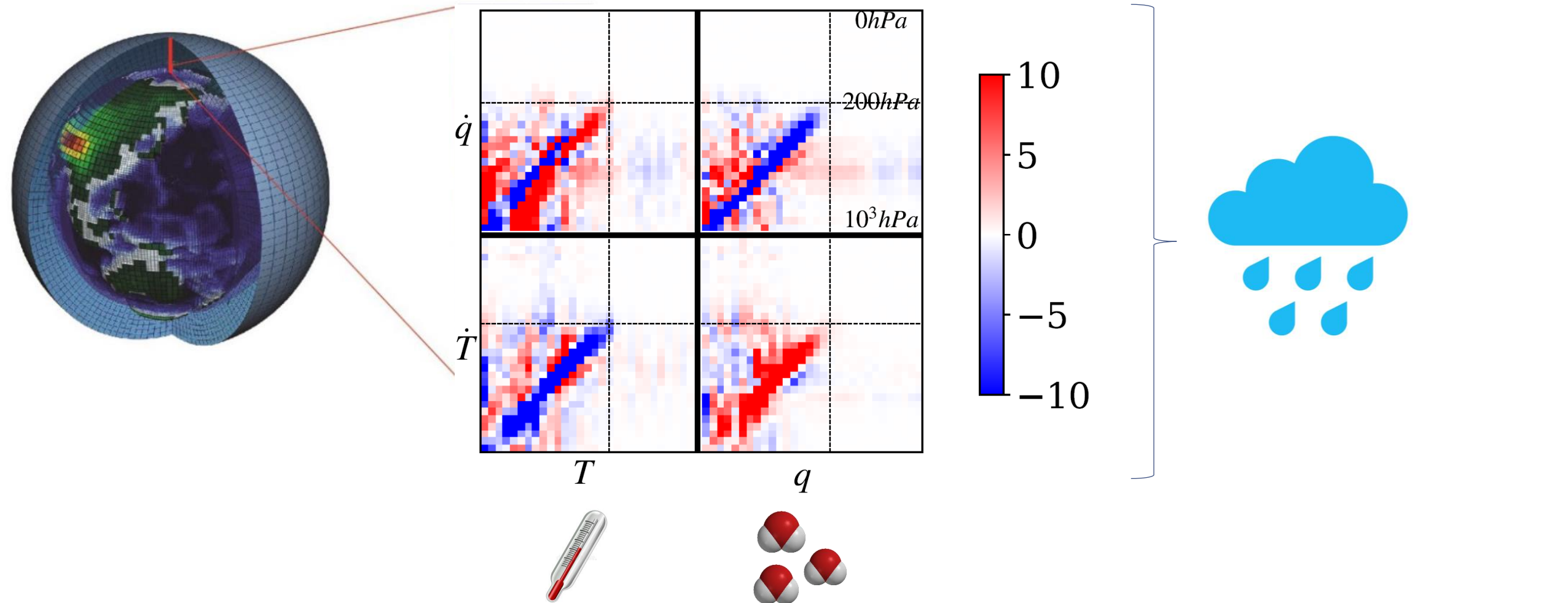
*Fig. source: Behrens et al. (2025), See also: Guillaumin & Zanna (2021), Mansfield & Sheshadri (2024), Schneider et al. (2021)*



#### 4) Many challenges remain unsolved:

1. Stability, extrapolation behavior, and recalibration of the host model
2. Best way to incorporate causality?
3. Best way to incorporate and evaluate stochasticity?
4. Grid-independence? Scale awareness? Transferability?

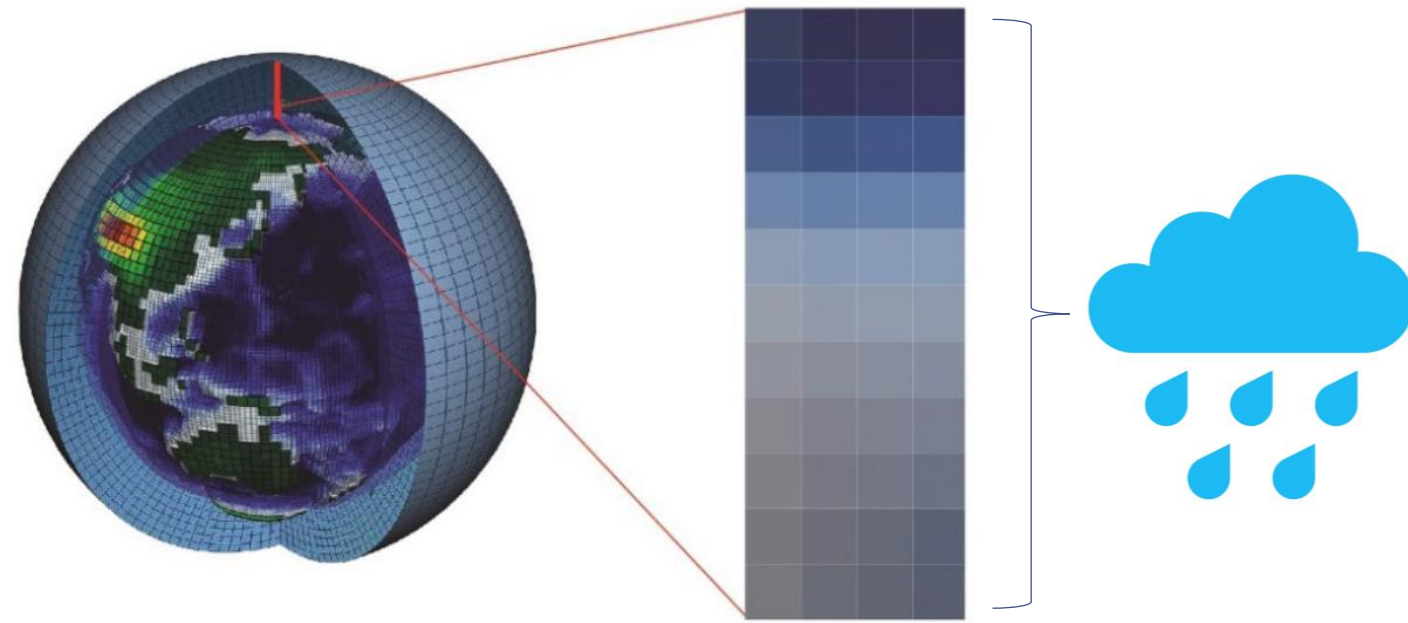
# At hourly timescales, convection is non-local! How can we keep our equation simple?



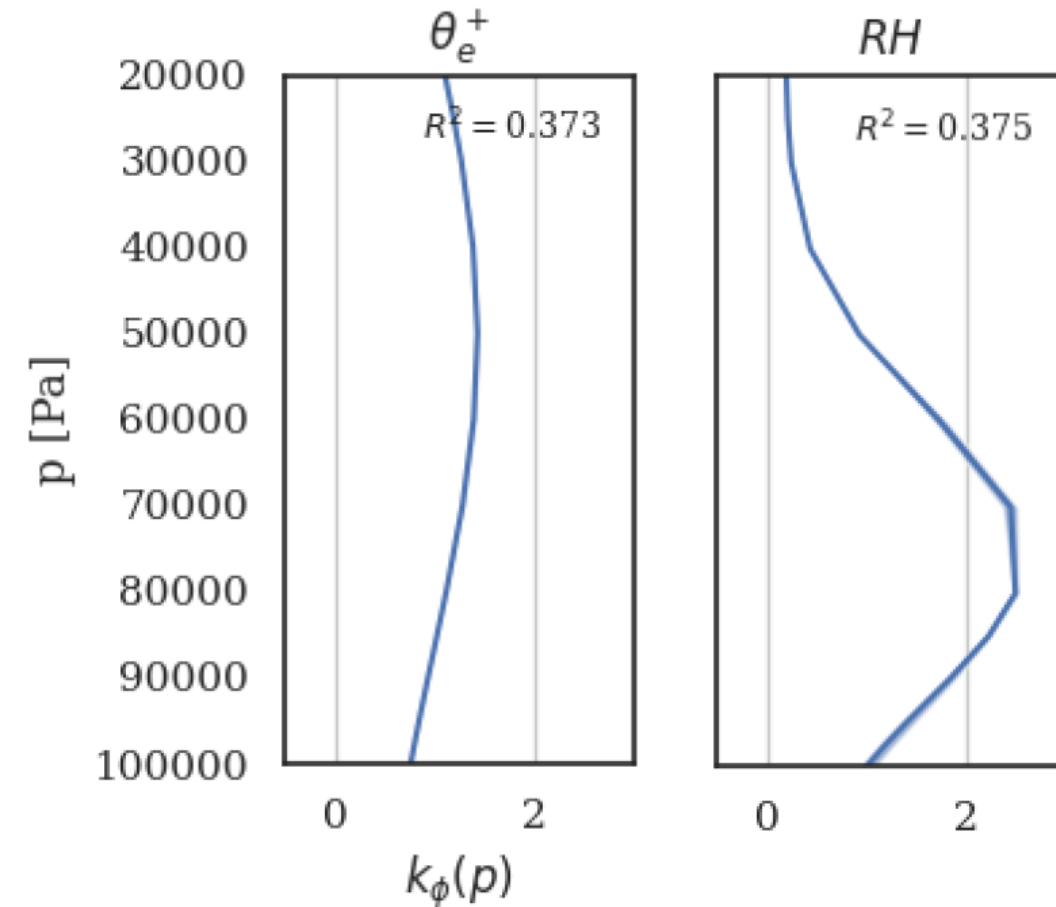
*Image source: Gentine, Eyring & Beucler (2020); Figure source: Beucler et al. (2024)*



- Idea: 1. Learn a vertical integration kernel from data  
2. Parameterize this integration kernel analytically



$$y = f[\mathbf{X}(\mathbf{p})] \approx f \left[ \int_0^{p_s} \frac{dp}{g} \underbrace{k(p)}_{\text{Learned}} \mathbf{X}(p) \right]$$



See: Beucler et al. (2024, AMS Tropical Meteorology)

# Learning kernels shares analogy with neural operators

 NeuralOperator Install User Guide API Examples Developer's Guide

Installing NeuralOperator

User Guide

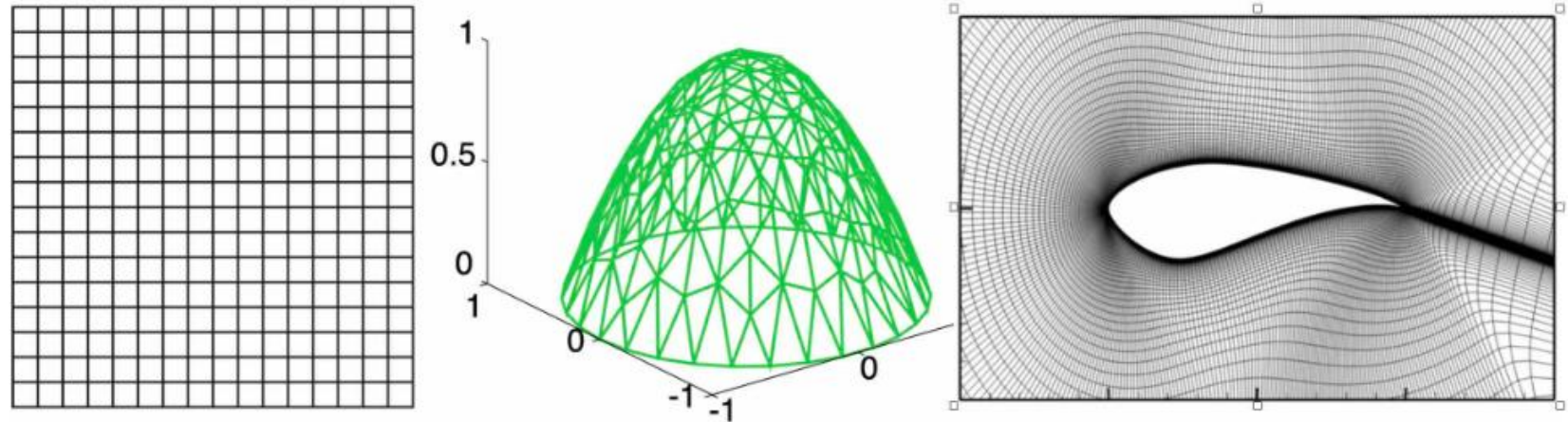
API reference

Examples

NeuralOperator Developer's Guide

## Limitation of Fixed Discretization

PDEs are, unfortunately, hard. Instead of learning the operator, people usually discretize the physical domain and cast the problem in finite-dimensional Euclidean space. Indeed, hundred years of effort has been made to develop numerical solvers such as the finite element method and finite difference method.



Source: <https://neuraloperator.github.io/>

# ACE2 is a SOA climate model emulator based on Spherical Fourier Neural Operators

**ACE2-SOM: Coupling an ML atmospheric emulator to a slab ocean and learning the sensitivity of climate to changed CO<sub>2</sub>**

Spencer K. Clark<sup>1,2</sup>, Oliver Watt-Meyer<sup>1</sup>, Anna Kwa<sup>1</sup>, Jeremy McGibbon<sup>1</sup>,  
Brian Henn<sup>1</sup>, W. Andre Perkins<sup>1</sup>, Elynn Wu<sup>1</sup>, Lucas M. Harris<sup>2</sup>, and  
Christopher S. Bretherton<sup>1</sup>

<sup>1</sup>Allen Institute for Artificial Intelligence, Seattle, WA, USA

<sup>2</sup>NOAA/Geophysical Fluid Dynamics Laboratory, Princeton, NJ, USA

## Key Points:

- The Ai2 Climate Emulator coupled to a slab ocean accurately emulates temperature and precipitation CO<sub>2</sub> sensitivity in a physics-based model
- Inference in an out-of-sample scenario with gradually increasing CO<sub>2</sub> is also accurate except for regime shifts in its stratosphere
- Abrupt 4xCO<sub>2</sub> inference reaches the correct equilibrium climate but the atmosphere warms too fast due to energy non-conservation

# Group activity

## 4) Many challenges remain unsolved:

1. Stability, extrapolation behavior, and recalibration of the host model
2. Best way to incorporate causality?
3. Best way to incorporate and evaluate stochasticity?
4. Grid-independence? Scale awareness? Transferability?
5. **Questioning the entire climate model formulation** 🤖



# 🔗 Towards Hybrid Earth System Modeling: A Living Review

This page reviews and organizes emerging hybrid Earth System Models (ESMs), which combine Machine Learning (ML) and physics-based components, alphabetically. Hybrid ESMs retain essential components for physical consistency (e.g., the dynamical core) while using ML to enhance parameterizations for small-scale processes (e.g., clouds). These models hold promise for improving long-term projections of Earth's physical climate and biogeochemical cycles.


If you notice any errors, omissions, or outdated information, please feel free to submit a pull request.

Author: Tom Beucler (UNIL); written in the context of [AI4PEX](#).

## Table of Contents

- [ACE](#)
- [CAMulator](#)
- [CBRAIN](#)
- [CliMA](#)
- [ClimSim](#)
- [Corrective ML](#)
- [DLESyM](#)
- [Hybrid ARP-GEM](#)
- [Hybrid CAM](#)
- [Hybrid LSM](#)
- [Hybrid SAM](#)

<https://github.com/tbeucler/HybridESM>

 Activity

☆ 20 stars

👁 1 watching

🍴 1 fork

### Releases

No releases published

[Create a new release](#)

### Packages

No packages published

[Publish your first package](#)

If you want to learn more: Lit. reviews are listed at  
[https://github.com/tbeucler/ML for Environmental Science](https://github.com/tbeucler/ML_for_Environmental_Science)

README MIT license

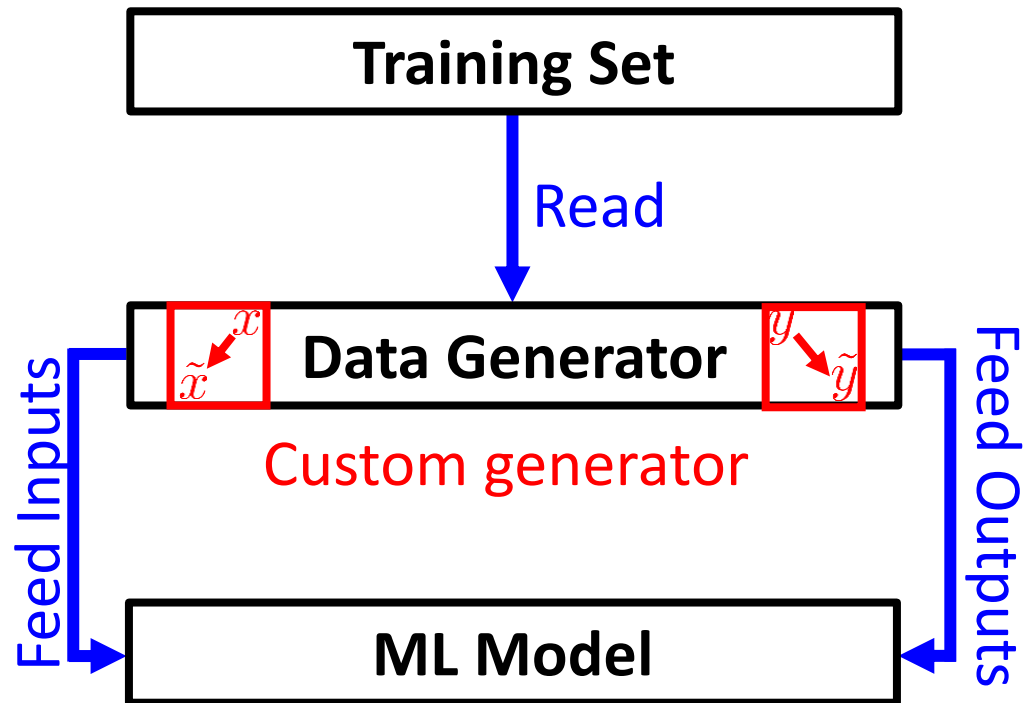


## Literature Reviews on Machine Learning for Environmental Science

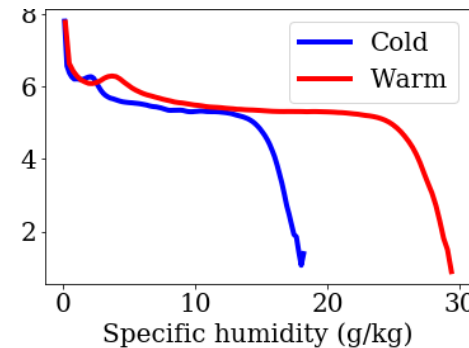
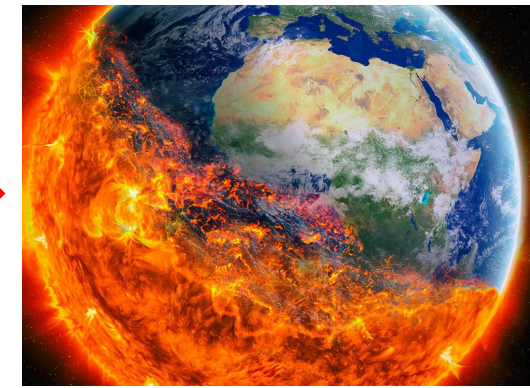
- [Stephan Rasp \(Living Review\)](#): State-of-the-art in AI-based weather forecasting.
- [Tom Beucler \(Living Review\)](#): State-of-the-art in hybrid Earth system modeling.
- [Eyring et al. \(2024\)](#): Pushing the frontiers in climate modeling and analysis with machine learning.
- [Beucler et al. \(2021\)](#): Machine Learning for Clouds and Climate.
- [Ullrich et al. \(2025\)](#): Recommendations for comprehensive and independent evaluation of machine learning-based Earth system models.
- [Reichstein et al. \(2019\)](#): Deep Learning and Process Understanding for Data-Driven Earth System Science.
- [Lai et al. \(2025\)](#): Machine Learning for Climate Physics and Simulations.
- [Zhu et al. \(2023\)](#): Machine Learning in Environmental Research: Common Pitfalls and Best Practices.
- [Reichstein et al. \(2025\)](#): Early warning of complex climate risk with integrated artificial intelligence.
- [Bergen et al. \(2019\)](#): Machine Learning for Data-Driven Discovery in Solid Earth Geoscience.
- [Rampal et al. \(2024\)](#): Enhancing Regional Climate Downscaling through Advances in Machine Learning.
- [Beucler et al. \(2024\)](#): Next-Generation Earth System Models: Towards Reliable Hybrid Models for Weather and Climate Applications.
- [Camps-Valls et al. \(2025\)](#): Artificial intelligence for modeling and understanding extreme weather and climate events.
- [Bracco et al. \(2024\)](#): Machine learning for the physics of climate.
- [Eyring et al. \(2024\)](#): AI-empowered next-generation multiscale climate modelling for mitigation and adaptation.
- [Rolnick et al. \(2019\)](#): Tackling Climate Change with Machine Learning.
- [Willard et al. \(2020\)](#): Integrating Physics-Based Modeling with Machine Learning: A Survey.
- [Sonnewald et al. \(2021\)](#): Bridging observations, theory and numerical simulation of the ocean using machine learning.

## Hands-on exercises:

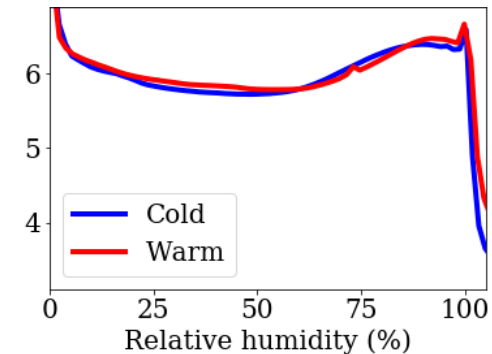
<https://wp.unil.ch/dawn/teaching/>



**+8K**



**Rescaling**



*See: Beucler et al. (2021)*