

Oscillators: frequency stability and noise analysis

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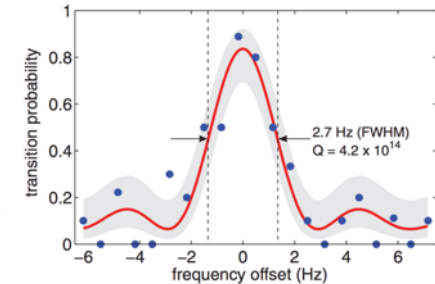
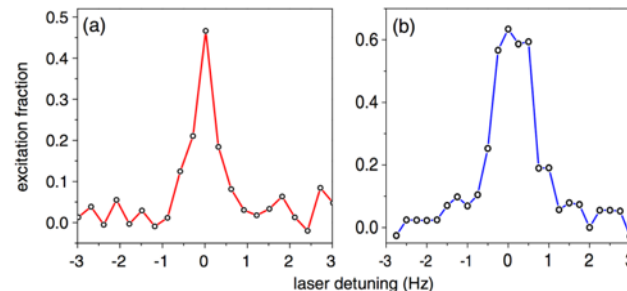
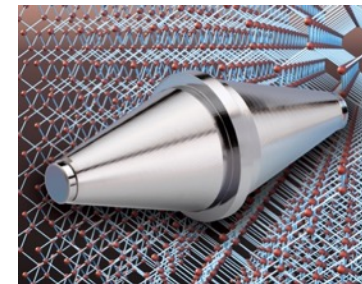
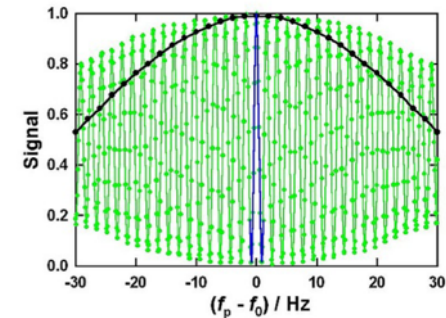
Winter College on Optics

Optical Frequency Combs: from multispecies gas sensing to high precision interrogation of atomic and molecular targets

15 – 26 February 2016



1. Frequency/Phase stability
2. Frequency domain characterization
3. Time domain characterization
4. Frequency stabilization principles



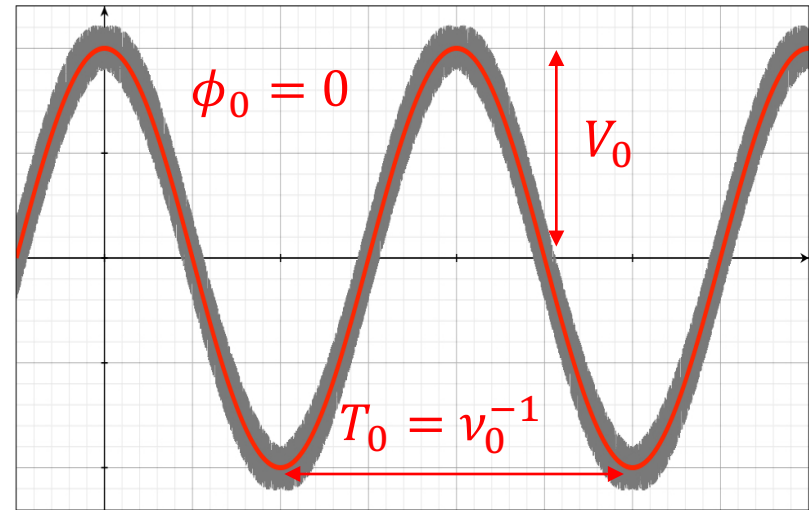
1. Clock signal – Noisy sine-wave
2. Fourier frequency domain stability
3. Time domain stability
4. Spectrum of a noisy sine-wave

$$v_{ideal}(t) = V_0 \cos(2\pi\nu_0 t + \phi_0)$$

V_0 is the amplitude [V]

ν_0 is the frequency [Hz= s^{-1}]

ϕ_0 is a constant phase [rad]



Oscillator output signal

$$v(t) = [V_0 + \varepsilon(t)] \cos[2\pi\nu_0 t + \varphi(t)]$$

$\varepsilon(t)$ is the amplitude noise [V] $\overline{\varepsilon(t)} = 0$; $|\alpha(t)| = \frac{|\varepsilon(t)|}{V_0} \ll 1$

$\varphi(t)$ is the phase noise [rad]

$$\overline{\varphi(t)} = 0; |x(t)| = \frac{|\varphi(t)|}{2\pi\nu_0} \ll 1$$

Not always fulfilled

$$v(t) = V_0 [1 + \alpha(t)] \cos[2\pi\nu_0 t + \varphi(t)] \text{ polar representation}$$

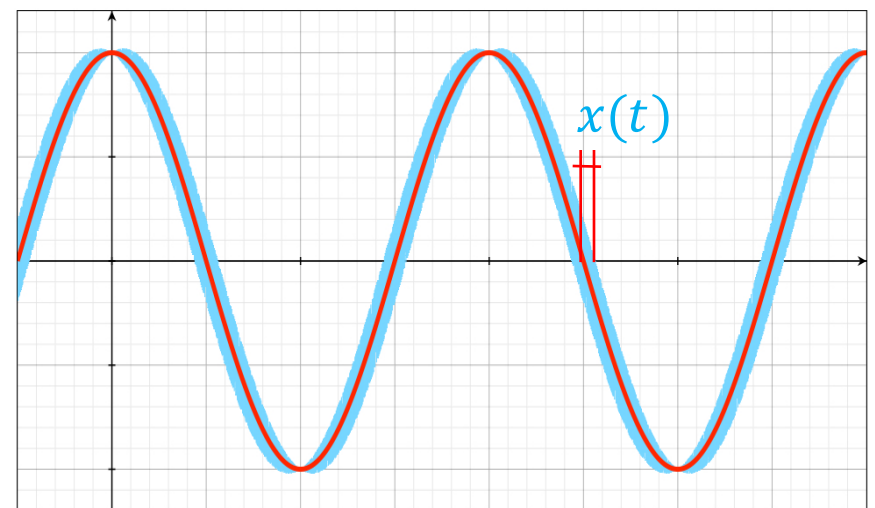
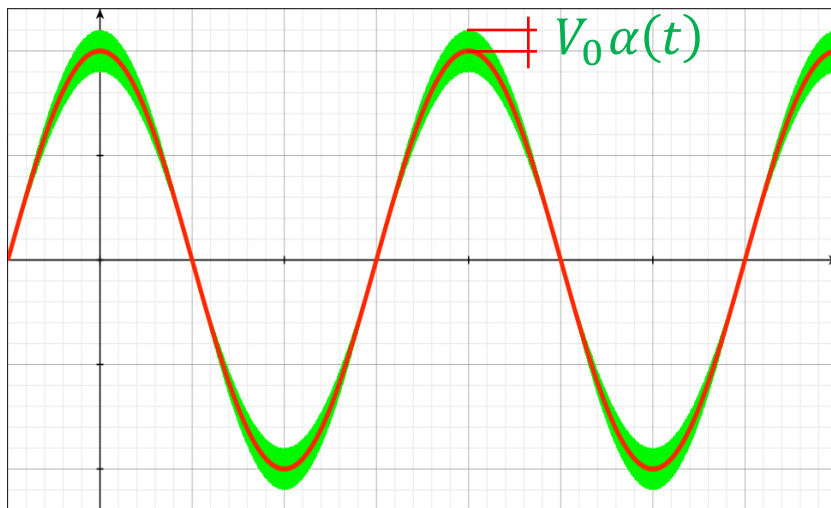
$$v(t) = V_0[1 + \alpha(t)] \cos[2\pi\nu_0 t + \varphi(t)] \quad \cos(a + b) = \cos a \cos b - \sin a \sin b$$

$$v(t) = V_0 \cos(2\pi\nu_0 t) + v_P(t) \cos(2\pi\nu_0 t) - v_Q(t) \sin(2\pi\nu_0 t)$$

$$v_P(t) = V_0[\cos \varphi (1 + \alpha) - 1] \quad v_Q(t) = V_0(1 + \alpha) \sin \varphi$$

If $|\alpha(t)| \ll 1$ and $|\varphi(t)| \ll 1$ **LOW NOISE SIGNAL**

$$v(t) \cong V_0 \cos(2\pi\nu_0 t) + V_0\alpha(t) \cos(2\pi\nu_0 t) - V_0\varphi(t) \sin(2\pi\nu_0 t)$$

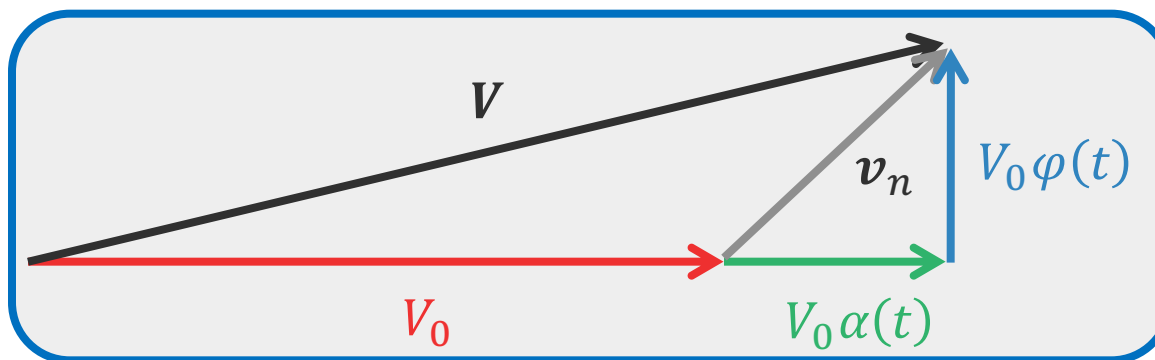


$$v(t) = V_0 \cos(2\pi\nu_0 t) + V_0\alpha(t) \cos(2\pi\nu_0 t) - V_0\varphi(t) \sin(2\pi\nu_0 t)$$

$$v(t) = \Re\{V_0 e^{i(2\pi\nu_0 t)} + V_0\alpha(t) e^{i(2\pi\nu_0 t)} + iV_0\varphi(t) e^{i(2\pi\nu_0 t)}\}$$

$$v(t) = \Re\{[V_0 + V_0\alpha(t) + iV_0\varphi(t)] e^{i(2\pi\nu_0 t)}\}$$

$$V(t) = V_0 + V_0\alpha(t) + iV_0\varphi(t) = V_0 + v_n$$



$$v(t) = V_0[1 + \alpha(t)] \cos[2\pi\nu_0 t + \varphi(t)]$$

$$\dot{v}(t) = \frac{1}{2\pi} \frac{d}{dt} [2\pi\nu_0 t + \varphi(t)] = \nu_0 + \frac{1}{2\pi} \frac{d\varphi(t)}{dt} = \nu_0 + \frac{\dot{\varphi}(t)}{2\pi}$$

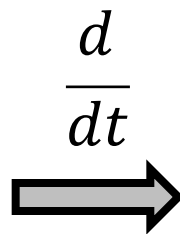
Frequency fluctuation/noise

$$\Delta\nu(t) = \nu(t) - \nu_0 = \frac{\dot{\varphi}(t)}{2\pi} \text{ [Hz]} \quad \overline{\Delta\nu(t)} = 0; \quad \overline{\dot{\varphi}(t)} = 0; \quad |\dot{\varphi}(t)| \ll 1$$

Normalized quantities

$$x(t) = \frac{\varphi(t)}{2\pi\nu_0} \text{ [s]}$$

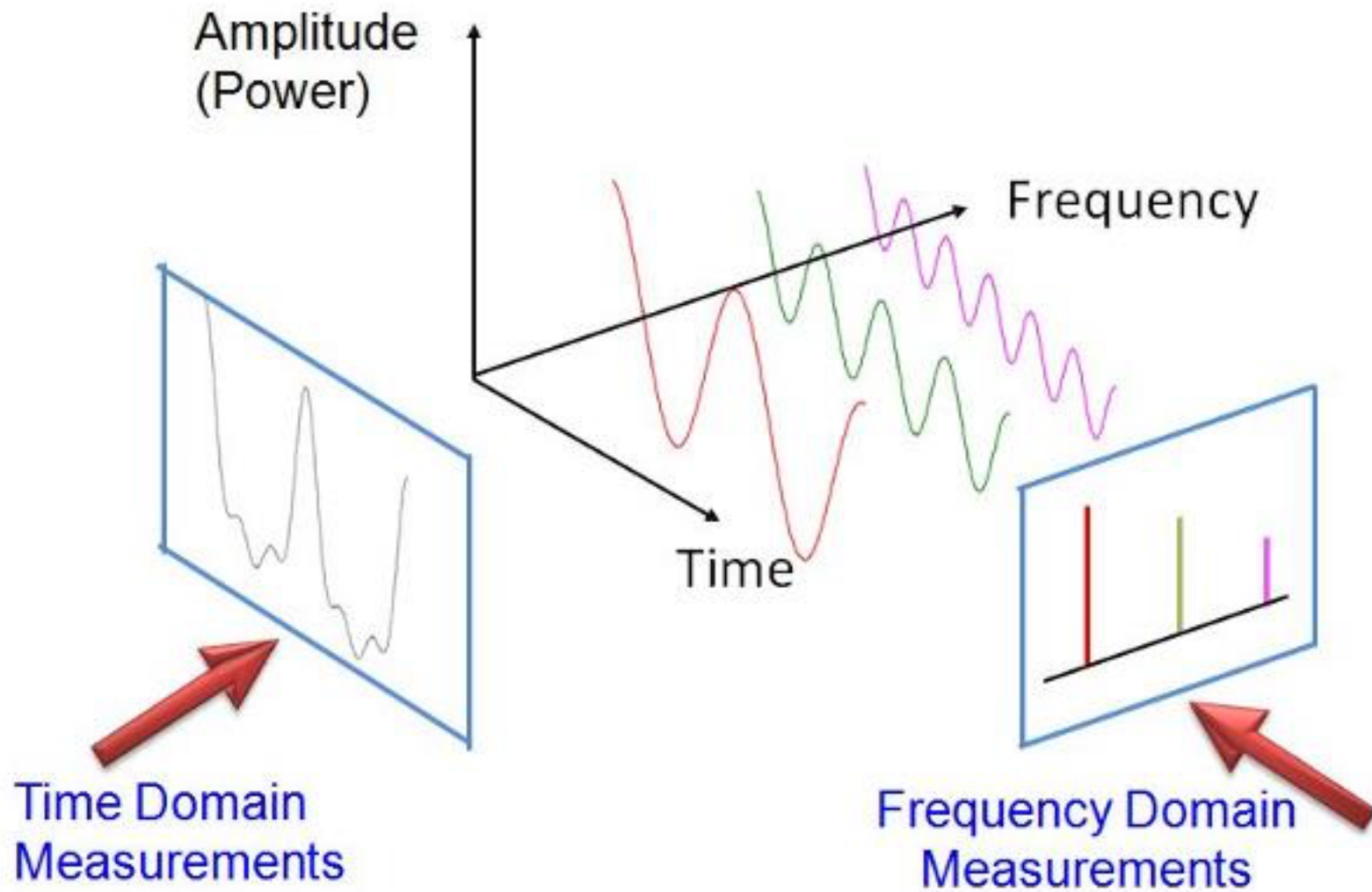
Phase time Noise



$$y(t) = \frac{\Delta\nu(t)}{\nu_0} = \frac{\dot{\varphi}(t)}{2\pi\nu_0} = \dot{x}(t) [1]$$

Fractional frequency noise

Invariant for phase/frequency multiplication/division



Power spectral density (PSD) of a **stationary** random signal $z(t)$

$$S_Z^{TS}(f) = \int_{-\infty}^{+\infty} R_Z(\tau) e^{-i2\pi f\tau} d\tau = \mathbb{F}\{R_Z(\tau)\} \quad \mathbb{F}\{\cdot\} \text{ Fourier transform}$$

$$R_Z(\tau) = \mathbb{E}\{z(t)z(t + \tau)\} = \iint_{-\infty}^{+\infty} z(t)z(t + \tau)w(z, t; z, t + \tau) (dz)^2$$

$\mathbb{E}\{\cdot\}$ Expectation value $w\{\cdot;\cdot\}$ conjunted probability density

Assuming $z(t)$ **ergotic** (ensemble average equal to time average)

$$R_Z(\tau) = \int_{-\infty}^{+\infty} S_Z^{SS}(f) e^{+i2\pi f\tau} df = \lim_{T \rightarrow \infty} \frac{1}{T} \int_{-T/2}^{+T/2} z(t)z(t + \tau) dt$$

$$R_Z(\tau = 0) = \int_{-\infty}^{+\infty} S_Z^{SS}(f) df = \lim_{T \rightarrow \infty} \frac{1}{T} \int_{-T/2}^{+T/2} z^2(t) dt = \overline{z^2}$$

The direct measurement of $R_z(\tau)$ and $S_z^{TS}(f)$ needs infinite time...

A more convenient way is:

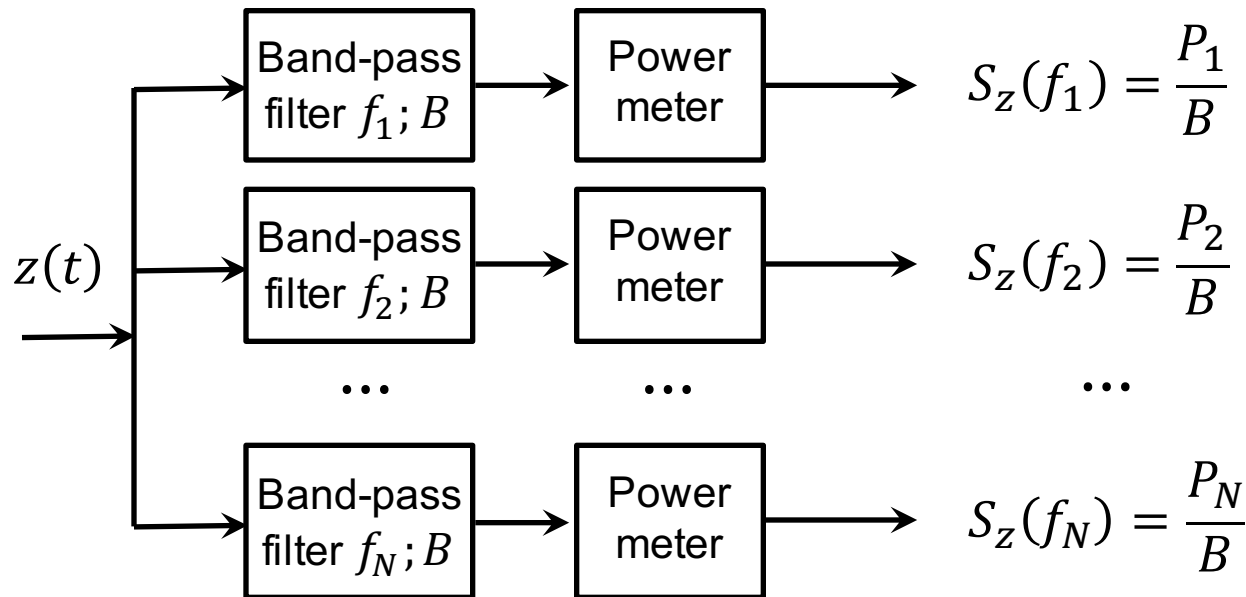
$$S_z^{TS}(f) = \lim_{T \rightarrow \infty} \frac{1}{T} |Z_T(f)|^2; \quad Z_T(f) = \int_{-T/2}^{+T/2} z(t) e^{-i2\pi f t} dt$$

Actual waveforms $z(t)$ are real signals and $S_z^{TS}(f) = S_z^{TS}(-f)$

$$S_z^{SS}(f) = S_z(f) = \begin{cases} 2S_z^{TS}(f) & \text{for } f \geq 0 \\ 0 & \text{for } f < 0 \end{cases}$$

$$R_z(\tau = 0) = \int_0^{+\infty} S_z(f) df = \overline{z^2}$$

$$\int_{f_0}^{f_0+B} S_z(f) df = P(B) = S_z(f_0)B \quad S_z(f_0) = \frac{P(B)}{B} \left[\frac{\text{power}}{\text{Hz}} \right]$$



The PSD extends the concept of root-mean-square value to the frequency domain

$$S_{\varphi}(f) = \lim_{T \rightarrow \infty} \frac{2}{T} |\varphi_T(f)|^2 \quad \left[\frac{\text{rad}^2}{\text{Hz}} \right]$$

$$S_x(f) = \frac{1}{(2\pi\nu_0)^2} S_{\varphi}(f) \quad \left[\frac{\text{s}^2}{\text{Hz}} \right]$$

$$x(t) = \frac{\varphi(t)}{2\pi\nu_0} \quad [\text{s}]$$

$$\mathcal{L}(f) = \frac{1}{2} S_{\varphi}(f) \quad \left[\frac{\text{rad}^2}{\text{Hz}} \right] \quad \mathcal{L}(f) = 10 \log_{10} \left[\frac{1}{2} S_{\varphi}(f) \right] \quad \left[\frac{\text{dB}_c}{\text{Hz}} \right]$$

$$\varphi_{rms} = \sqrt{\overline{\varphi^2}} = \sqrt{\int_{f_L}^{f_H} S_{\varphi}(f) df} \quad [\text{rad}] \quad x_{rms} = \sqrt{\overline{x^2}} = \frac{1}{2\pi\nu_0} \sqrt{\int_{f_L}^{f_H} S_{\varphi}(f) df} \quad [\text{s}]$$

$$S_{\Delta\nu}(f) = S_{\frac{\dot{\varphi}}{2\pi}}(f) = \frac{|i2\pi f|^2}{(2\pi)^2} S_{\varphi}(f) = f^2 S_{\varphi}(f) \left[\frac{\text{Hz}^2}{\text{Hz}} \right]$$

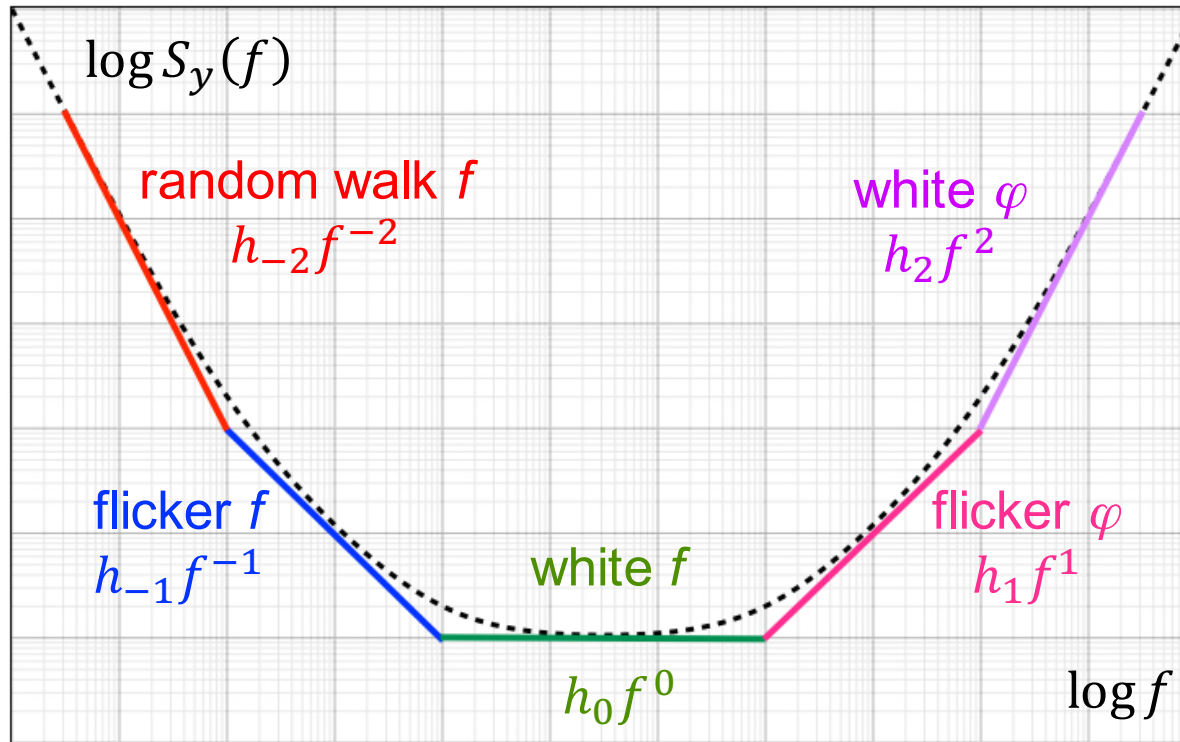
$$y(t) = \frac{\Delta\nu(t)}{\nu_0} = \dot{x}(t) \quad [1]$$

$$S_y(f) = \frac{1}{\nu_0^2} S_{\Delta\nu}(f) = \frac{f^2}{\nu_0^2} S_{\varphi}(f) = |i2\pi f|^2 S_x(f) \left[\frac{1}{\text{Hz}} \right]$$

$$y_{rms} = \sqrt{y^2} = \sqrt{\int_{f_L}^{f_H} S_y(f) df} \quad [1]$$

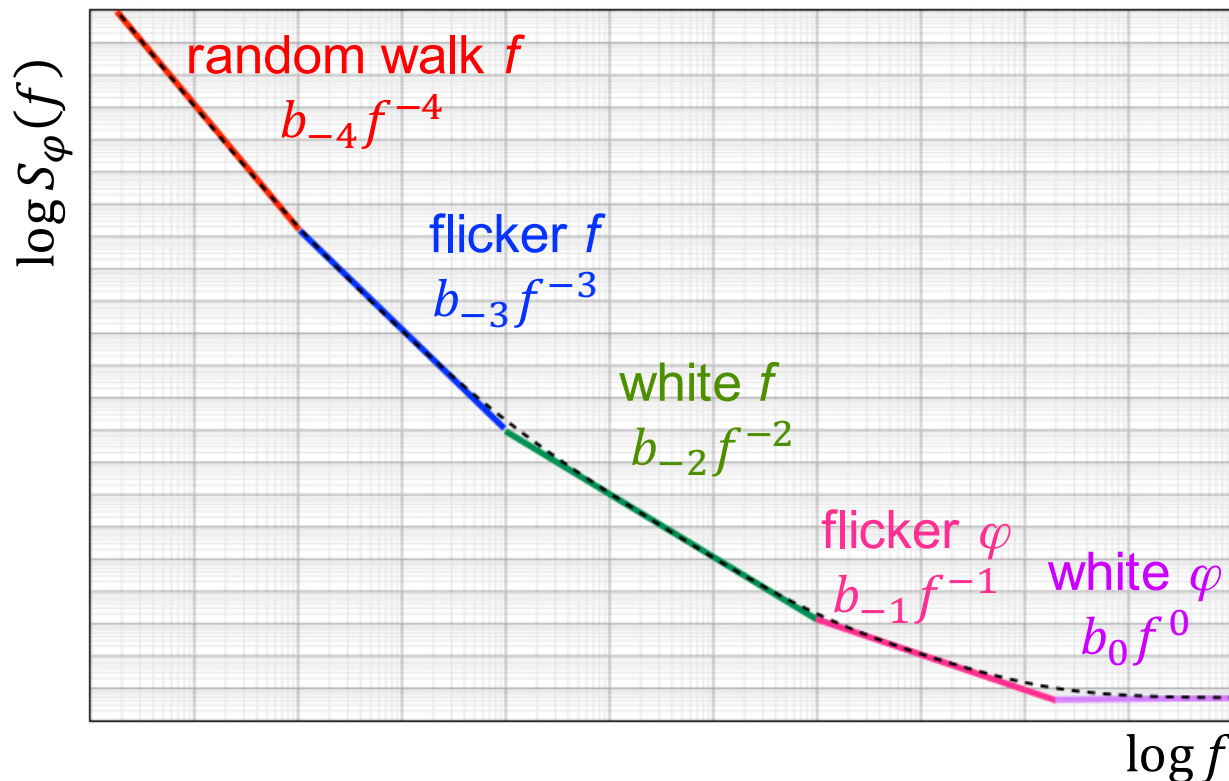
Experimental evidence shows

$$S_y(f) = \begin{cases} \sum_{\alpha=-2}^{+2} h_{\alpha} f^{\alpha} & 0 \leq f < f_H \\ 0 & f > f_H \end{cases}$$



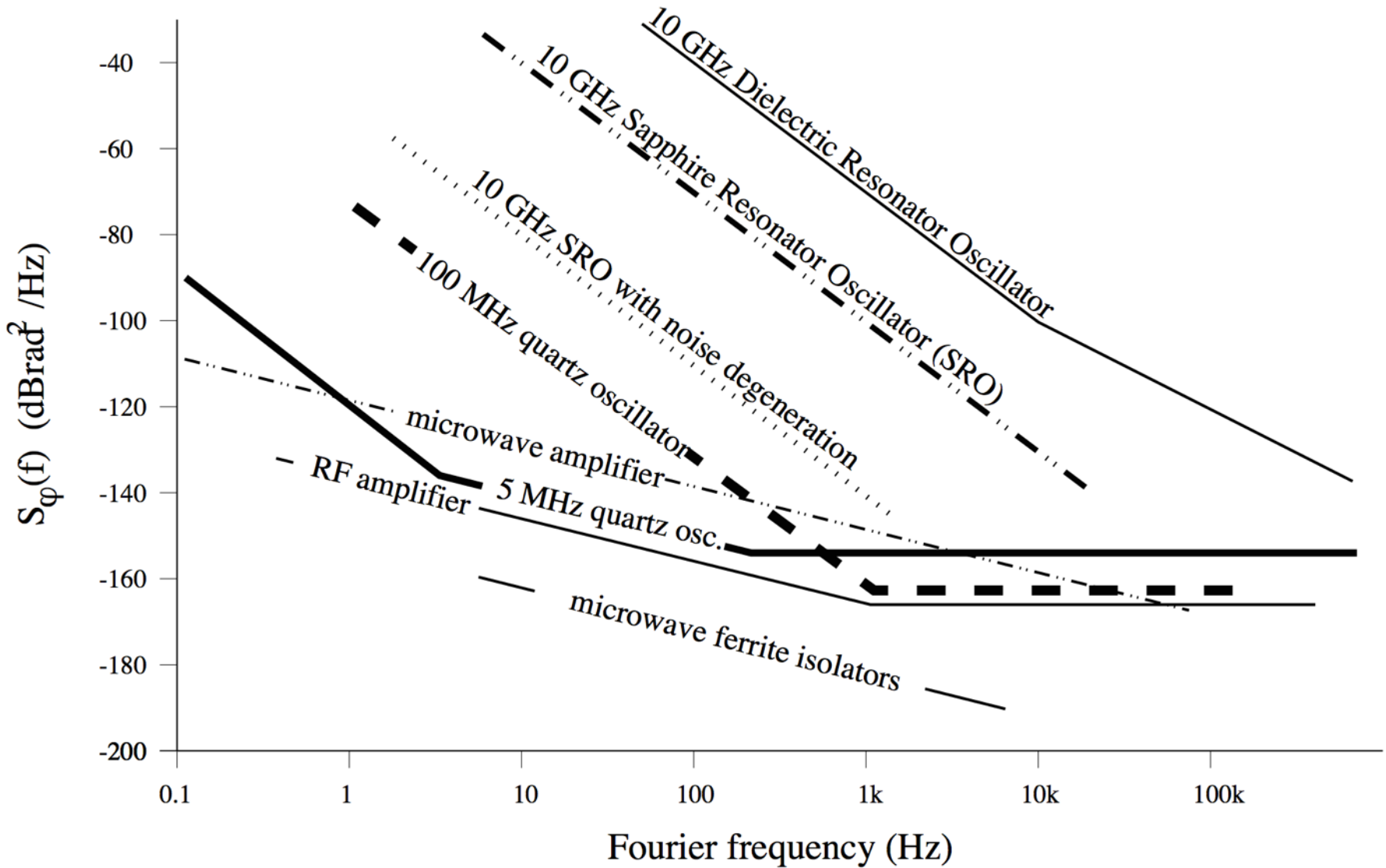
$$S_{\varphi}(f) = \frac{v_0^2}{f^2} \sum_{\alpha=-2}^{+2} h_{\alpha} f^{\alpha} = \sum_{\alpha=-2}^{+2} v_0^2 h_{\alpha} f^{\alpha-2} = \sum_{i=-4}^0 b_i f^i$$

$$b_i = v_0^2 h_{i+2}$$



$S_y(f)$ [Hz ² /Hz]	Type of noise	Main contribution	Relation
$h_{-2}f^{-2}$	Random walk (RW) of frequency	Different unknown origin	-
$h_{-1}f^{-1}$	Flicker of frequency	Leeson effect supplied by flicker phase/resonator thermal noise	-
h_0	White frequency/ RW of phase	Resonator in band /quantum/thermal noise (Leeson effect)	$h_0 = \begin{cases} FkT/PQ^2 \\ Fh\nu_0/PQ^2 \end{cases}$
h_1f	Flicker of phase	Up-conversion of the amplifier flicker noise by amplifier non-linearity	-
h_2f^2	White phase	Thermal/quantum/electronics noise in amplifiers	$h_2 = \begin{cases} FkT/P\nu_0^2 \\ Fh\nu_0/P\nu_0^2 \end{cases}$

$$S_\varphi(f) = \sum_{i=-4}^0 b_i f^i; \quad b_i = \nu_0^2 h_{i+2}$$



By means of an electronic counter, the average frequency (number of counts, i.e. number of cycles) can be measured over a time interval τ

$$\overline{\nu}_k(\tau) = \frac{N_k}{\tau} = \frac{1}{\tau} \int_{t_k}^{t_k+\tau} \nu(t) dt = \nu_0 + \frac{1}{\tau} \int_{t_k}^{t_k+\tau} \Delta\nu(t) dt$$

$$y(t) = \frac{\Delta\nu(t)}{\nu_0} = \dot{x}(t) \qquad x(t) = \frac{\varphi(t)}{2\pi\nu_0}$$

$$\overline{y}_k(\tau) = \frac{1}{\tau} \int_{t_k}^{t_k+\tau} y(t) dt = \frac{\varphi(t_k + \tau) - \varphi(t_k)}{2\pi\nu_0\tau}$$

Frequency instability is defined as:

$$I^2(\tau) = \sigma^2[\overline{y}_k(\tau)] = \mathbb{E}[\overline{y}_k^2]$$

A possible determination/definition of frequency instability is represented by the N-sample variance:

$$\sigma_y^2(N, T, \tau) = \mathbb{E} \left[\frac{1}{N-1} \sum_{i=1}^N \left(\bar{y}_i - \frac{1}{N} \sum_{j=1}^N \bar{y}_j \right)^2 \right]$$

Drawbacks: dependence from N and it diverges for flicker and random walk noises for $\tau \rightarrow \infty$

Allan Variance (zero dead-time two-sample variance)

<http://www.allanstime.com/AllanVariance/>

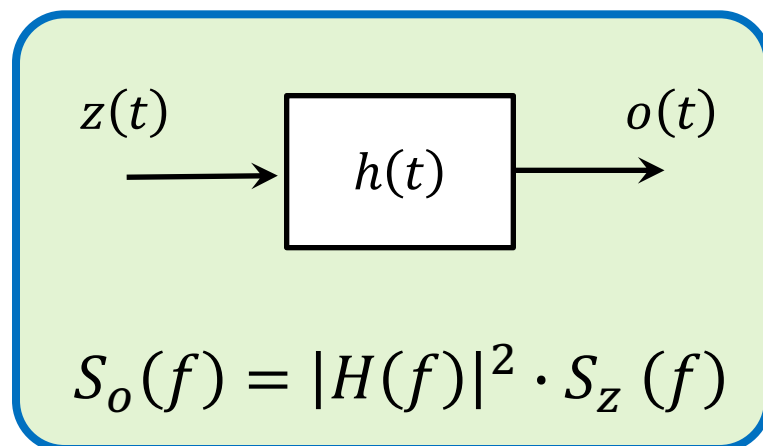
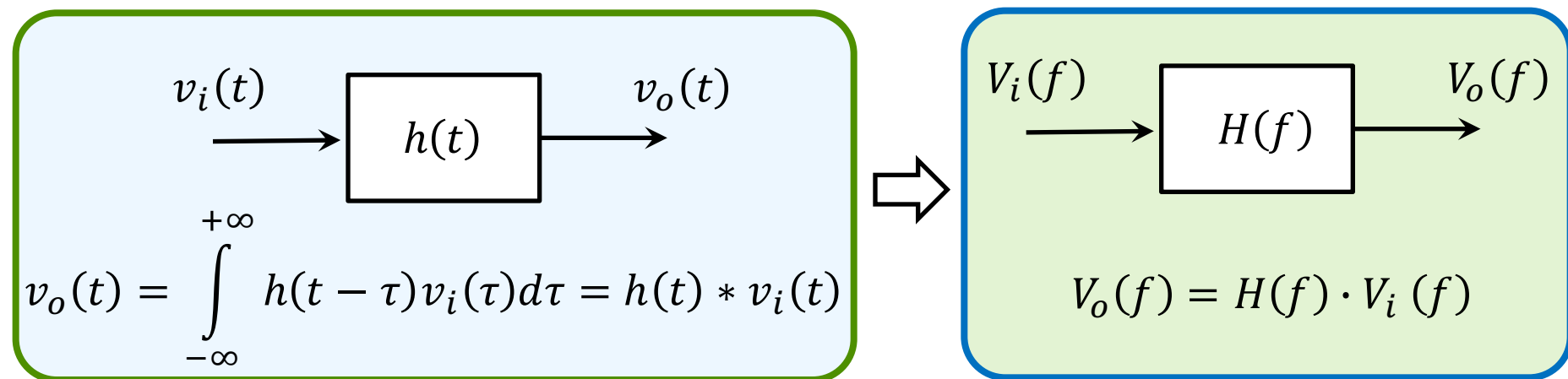
$$\sigma_y^2(\tau) = \mathbb{E} \left[\sum_{i=1}^2 \left(\bar{y}_i - \frac{1}{2} \sum_{j=1}^2 \bar{y}_j \right)^2 \right] = \frac{1}{2} \mathbb{E}[(\bar{y}_2 - \bar{y}_1)^2]$$

$$\langle \sigma_y^2(\tau) \rangle_m = \frac{1}{2(m-1)} \sum_{i=1}^m (\bar{y}_{i+1} - \bar{y}_i)^2$$

It converges for flicker and random walk noises for $\tau \rightarrow \infty$

Connection between time and Fourier frequency domains

Linear and time-invariant systems (LTI)



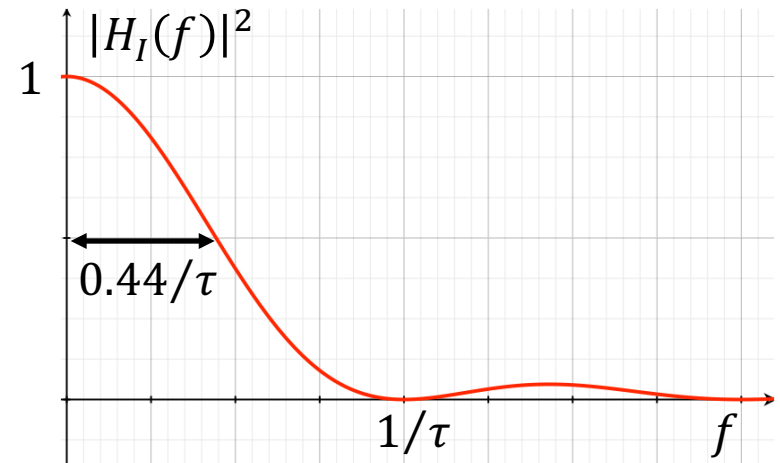
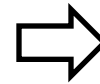
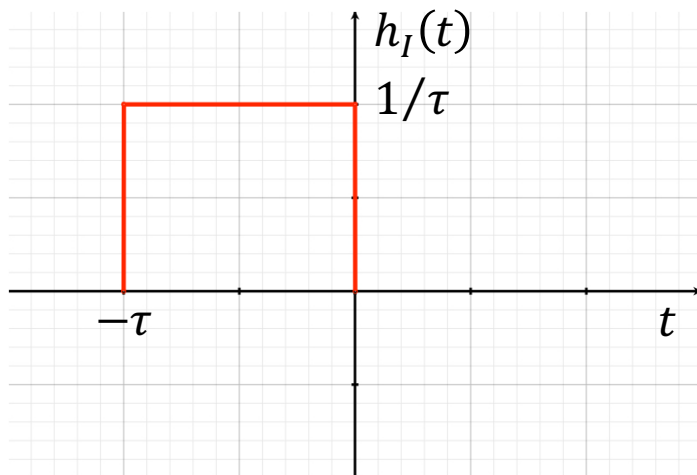
convolution

$$I^2(\tau) = \sigma^2(\overline{y_k}) = \mathbb{E}[\overline{y_k}^2] = \mathbb{E}\left\{\left[\frac{1}{\tau} \int_{t_k}^{t_k+\tau} y(t) dt\right]^2\right\} = \mathbb{E}\left\{\left[\int_{-\infty}^{+\infty} h_I(t_k - t) y(t) dt\right]^2\right\}$$

$$h_I(t) = \begin{cases} 0 & \text{elsewhere} \\ 1/\tau & t_k < t < t_k + \tau \end{cases}$$



$$H_I(f) = \frac{\sin(\pi f \tau)}{\pi f \tau}$$



$$I^2(\tau) = \sigma^2(\overline{y_k}) = \int_0^{+\infty} |H_I(f)|^2 S_y(f) df = \int_0^{+\infty} \left| \frac{\sin(\pi f \tau)}{\pi f \tau} \right|^2 S_y(f) df$$

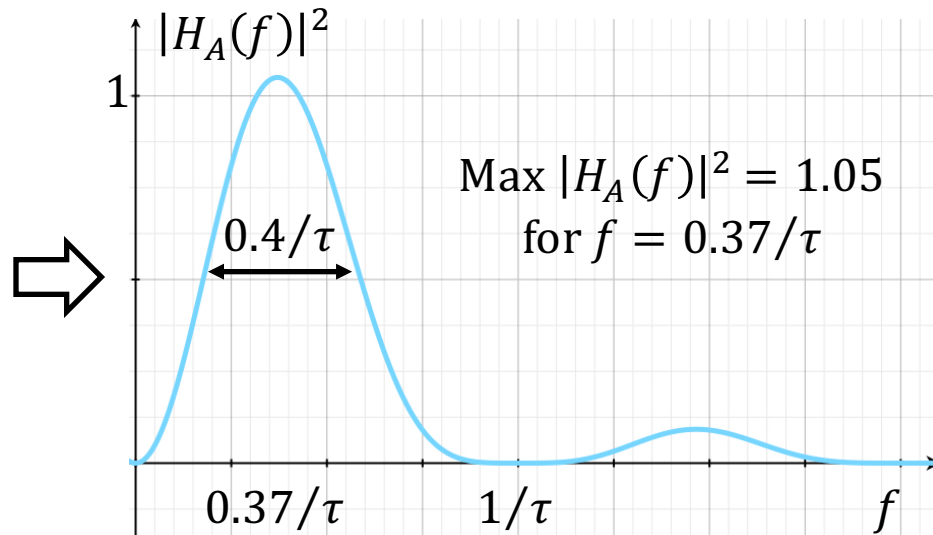
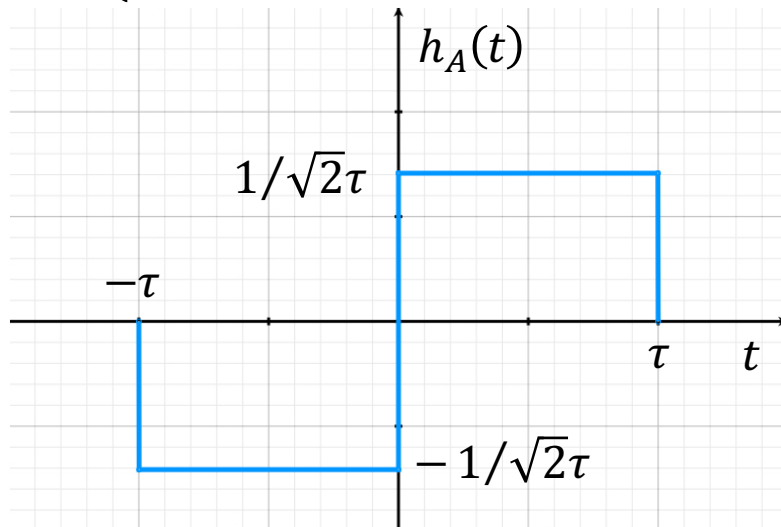
It diverges for flicker and random walk noises for $f \rightarrow 0$ ($\tau \rightarrow \infty$)

$$\sigma_y^2(\tau) = \frac{1}{2} \mathbb{E}[(\bar{y}_2 - \bar{y}_1)^2] = \mathbb{E} \left\{ \left[\frac{1}{\sqrt{2}\tau} \int_{t_k+\tau}^{t_k+2\tau} y(t) dt - \frac{1}{\sqrt{2}\tau} \int_{t_k}^{t_k+\tau} y(t) dt \right]^2 \right\}$$

$$\sigma_y^2(\tau) = \mathbb{E} \left\{ \left[\int_{-\infty}^{+\infty} h_A(t_k - t) y(t) dt \right]^2 \right\}$$

$$h_A(t) = \begin{cases} -1/\sqrt{2}\tau & t_k < t < t_k + \tau \\ 1/\sqrt{2}\tau & t_k + \tau < t < t_k + 2\tau \\ 0 & \text{elsewhere} \end{cases}$$

$$\Rightarrow H_A(f) = \sqrt{2} \frac{[\sin(\pi f \tau)]^2}{\pi f \tau}$$



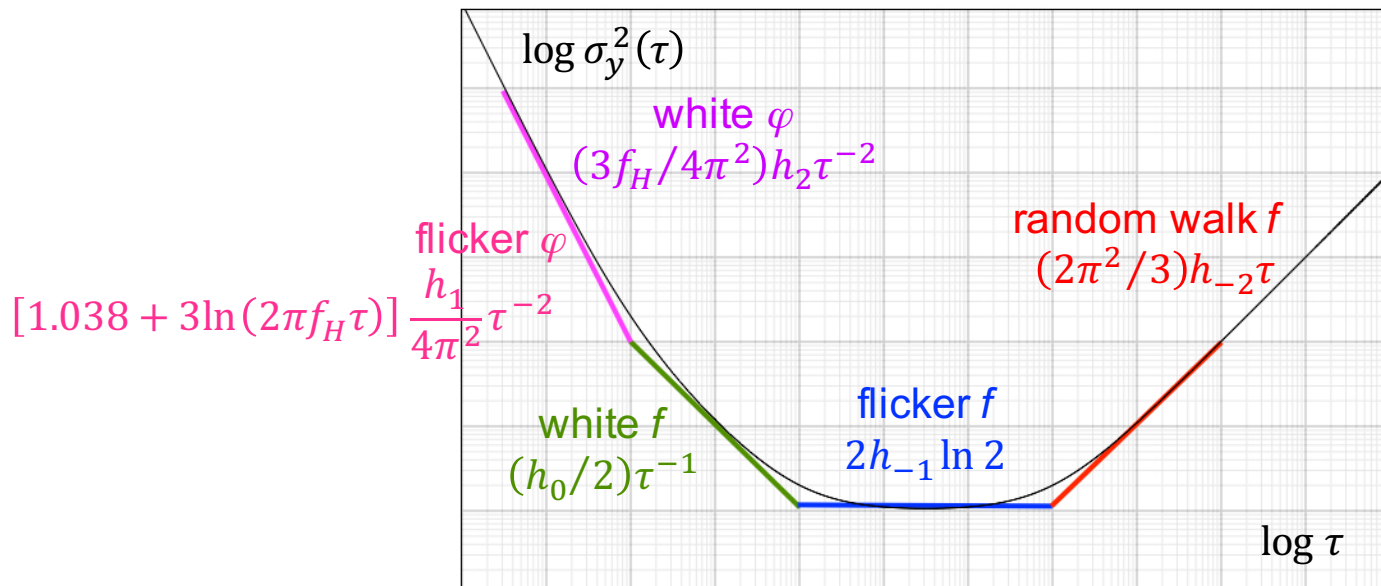
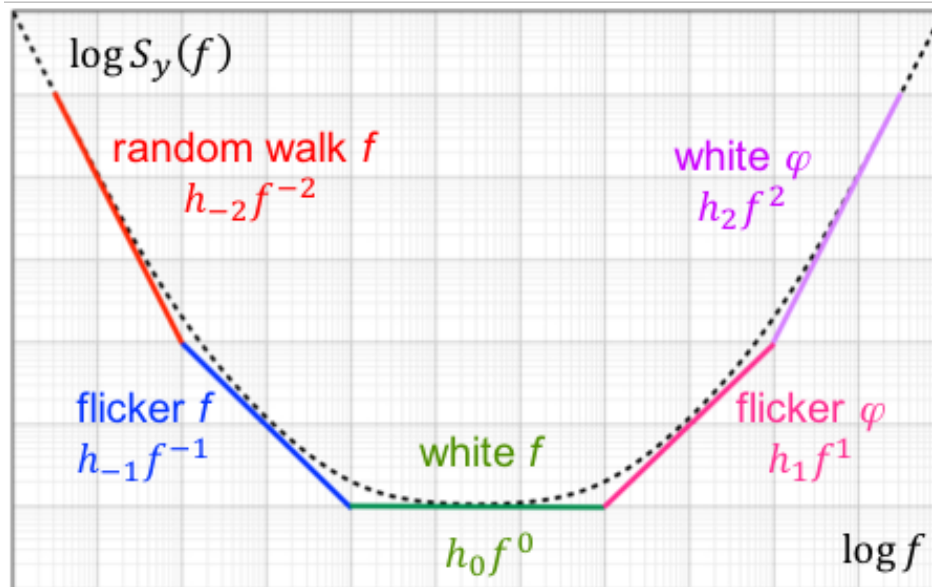
$$\sigma_y^2(\tau) = \int_0^{+\infty} |H_A(f)|^2 S_y(f) df = \int_0^{+\infty} 2 \frac{[\sin(\pi f \tau)]^4}{(\pi f \tau)^2} S_y(f) df$$

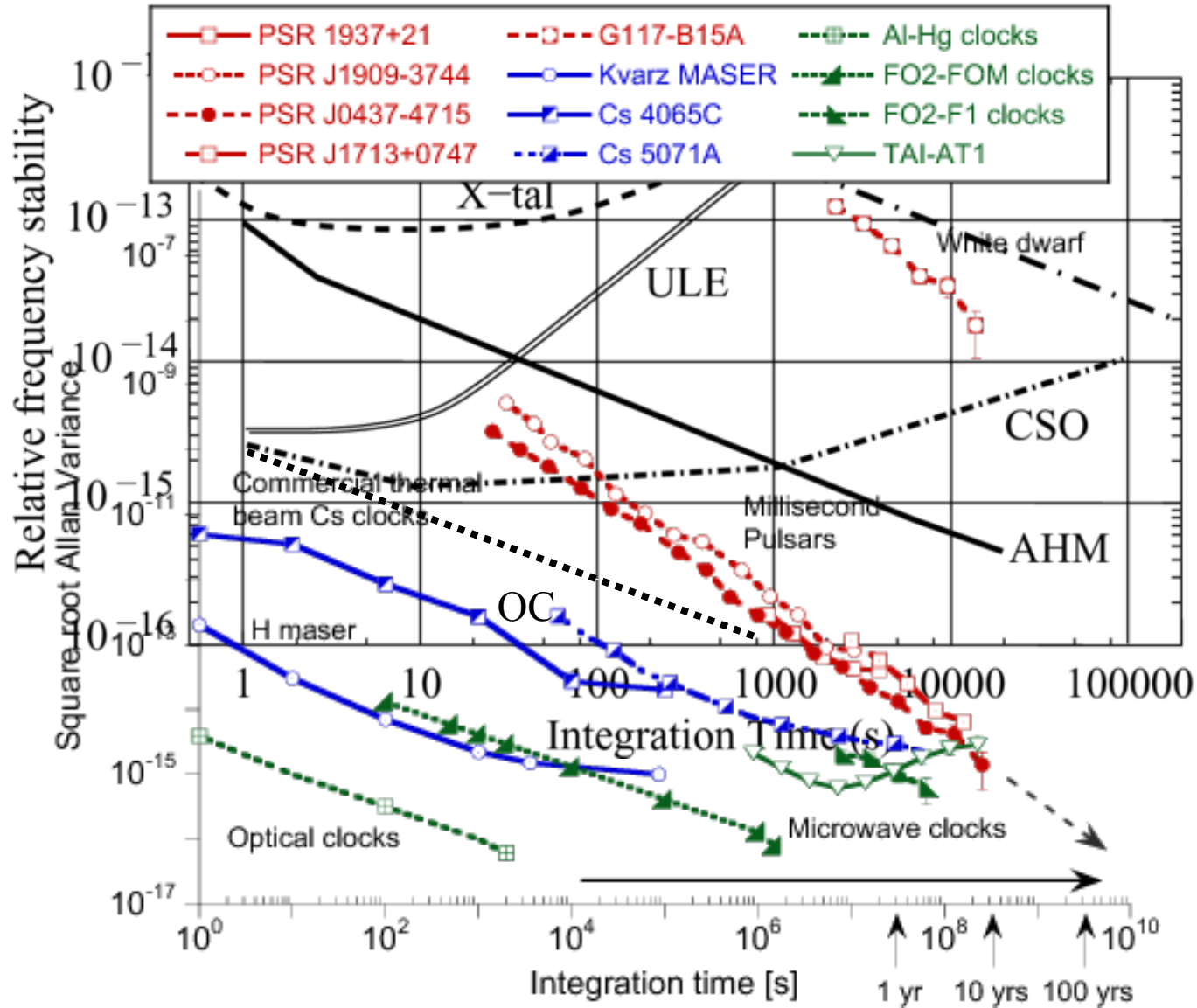
$S_y(f)$ [Hz ² /Hz]	Type of noise	$\sigma_y^2(\tau)$
$h_{-2} f^{-2}$	Random walk FM	$(2\pi^2/3)h_{-2}\tau$
$h_{-1} f^{-1}$	Flicker FM	$2h_{-1} \ln 2$
h_0	White FM	$(h_0/2)\tau^{-1}$
$h_1 f$	Flicker PM	$[1.038 + 3\ln(2\pi f_H \tau)] \frac{h_1}{4\pi^2} \tau^{-2} *$
$h_2 f^2$	White PM	$(3f_H/4\pi^2)h_2\tau^{-2} *$

$$\sigma_y^2(\tau) \propto \tau^\mu$$

$$\mu = \begin{cases} -\alpha - 1; & -2 \leq \alpha < 1 \\ -2; & \alpha \geq 1 \end{cases}$$

* f_H is a high cutoff frequency, needed for the noise power to be finite
 ($2 \pi f_H \tau \gg 1$)



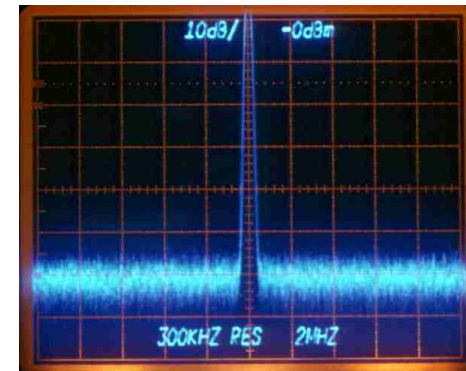


$$v(t) = V_0 [1 + \alpha(t)] \cos[2\pi\nu_0 t + \varphi(t)]$$

$$\overline{v^2(t)} = V_0^2 [1 + 2\alpha(t)]$$

Noise broadens the spectrum in a complex way but the random phase does not contribute to the signal power!!!

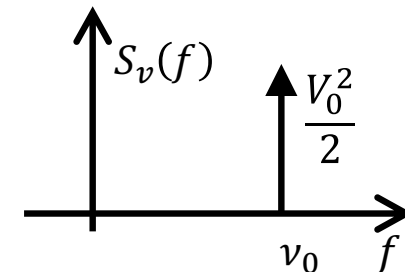
$$S_v(f, t) = \mathbb{F}\{R_v(\tau, t)\}$$



Noise-free ideal signal

$$R_v(\tau) = V_0^2 \mathbb{E}\{\cos(2\pi\nu_0 t) \cos[2\pi\nu_0(t + \tau)]\} = \frac{V_0^2}{2} \cos(2\pi\nu_0 \tau)$$

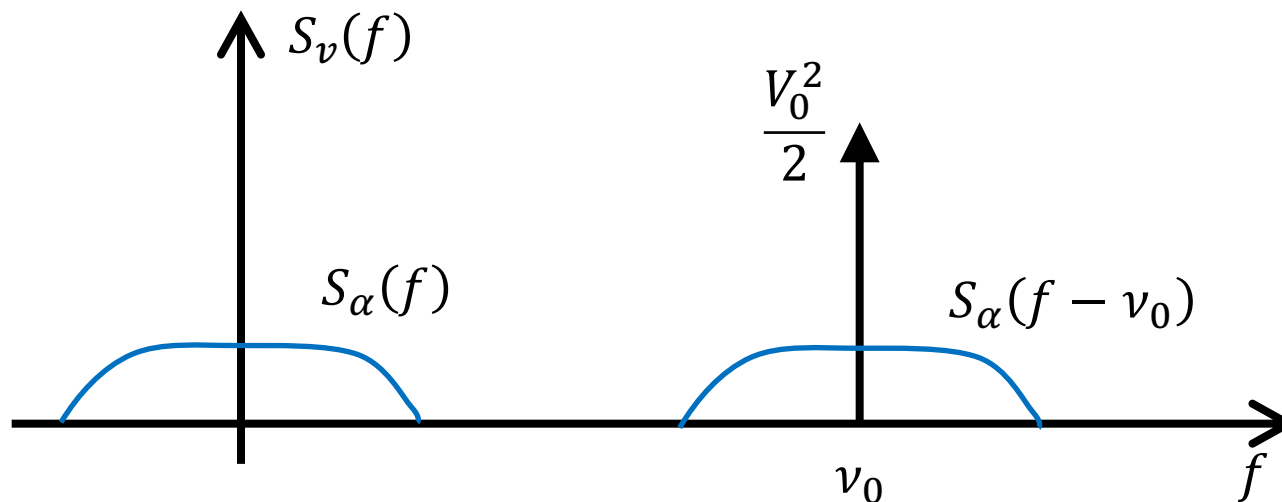
$$S_v(f) = \frac{V_0^2}{2} \delta(f - \nu_0)$$



Pure AM noise signal

$$R_v(\tau) = \frac{V_0^2}{2} \cos(2\pi\nu_0\tau)[1 + R_\alpha(\tau)]$$

$$S_v(f) = \frac{V_0^2}{2} \delta(f - \nu_0) * [\delta(f) + S_\alpha(f)] = \frac{V_0^2}{2} [\delta(f - \nu_0) + S_\alpha(f - \nu_0)]$$



Pure PM noise signal

$$R_v(\tau) = \frac{V_0^2}{2} \cos(2\pi\nu_0\tau) \exp\left\{\frac{1}{2} [R_\varphi(0) - R_\varphi(\tau)]\right\}$$

$$R_v(\tau) = \frac{V_0^2}{2} \cos(2\pi\nu_0\tau) \exp\left[-2 \int_0^\infty \left|\frac{\sin(2\pi f\tau)}{f}\right|^2 S_{\Delta\nu}(f) df\right]$$

$$S_v(f) = \mathbb{F}\{R_v(\tau)\}$$

White frequency noise ($S_{\Delta\nu} = \nu_0^2 h_0$)

Complex integral!!

$$S_v(f) = \frac{V_0^2}{2} \frac{(\pi\Delta f_L)^{-1}}{1 + \left[2 \frac{(f - \nu_0)}{\Delta f_L}\right]^2}$$

$$\Delta f_L = \text{FWHM} = \pi\nu_0^2 h_0$$

PM and AM noise

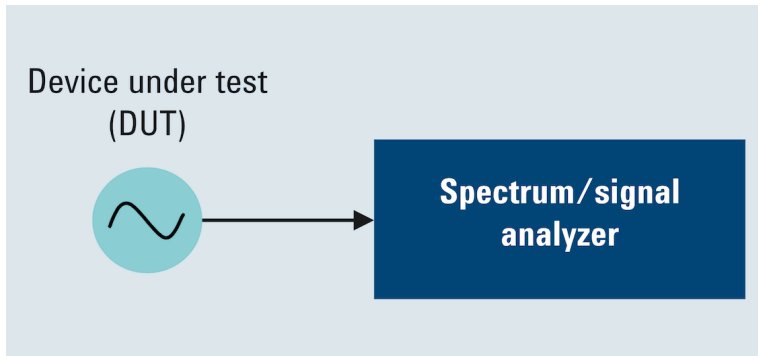
$$R_v(\tau) = R_{v_{\Delta v}}(\tau)[1 + R_\alpha(\tau)]$$

$$S_v(f) = \mathbb{F}\{R_v(\tau)\} = S_{v_{\Delta v}}(f) + S_{v_{\Delta v}}(f) * S_\alpha(f)$$

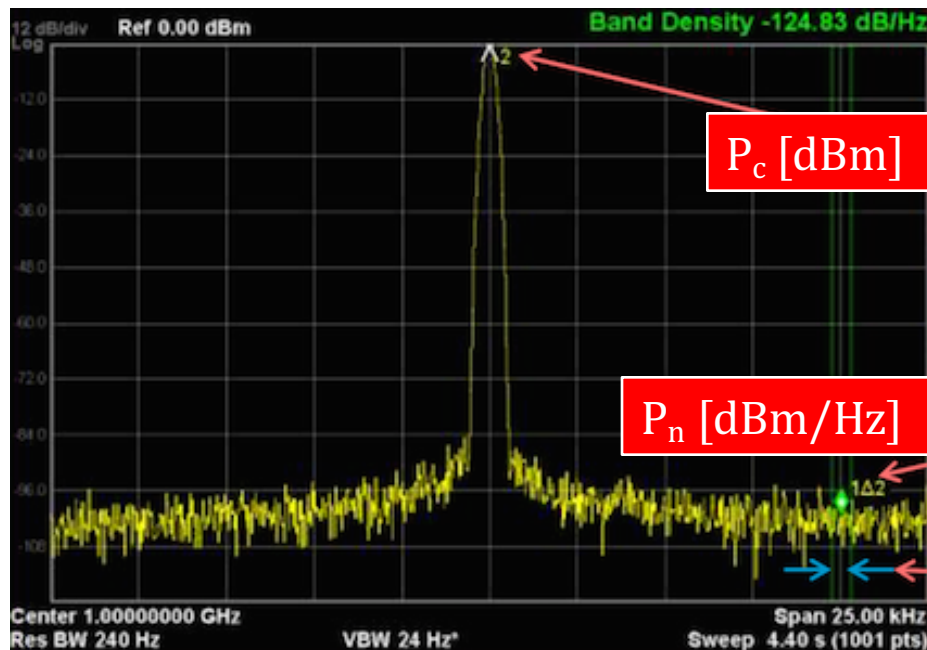
Very Complex integral!! Numerical integration is performed

1. Direct measurement
2. Frequency discriminator
3. Phase discriminator

Is the simplest and oldest method for the measurement of the phase noise power spectral density



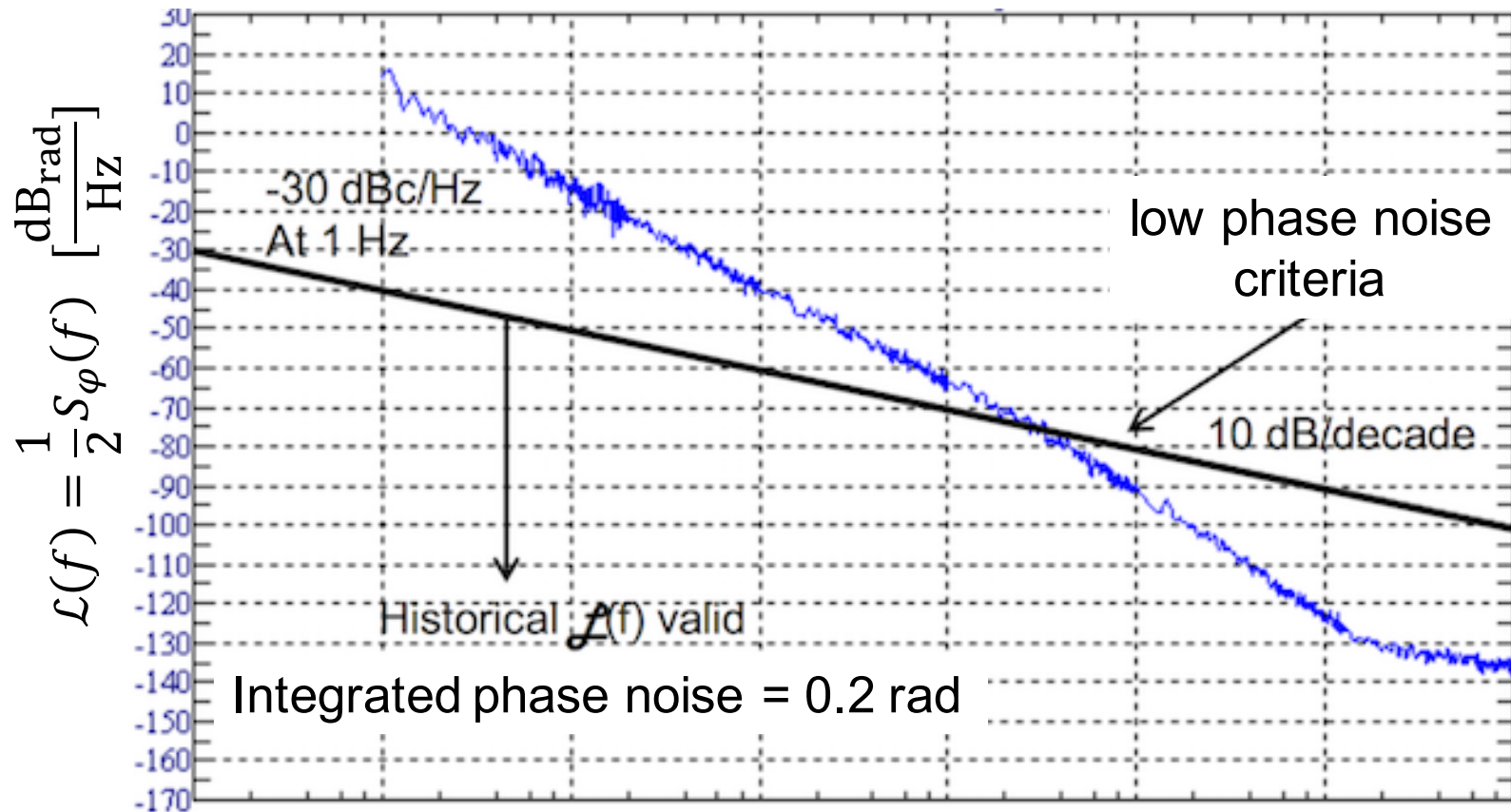
$$\mathcal{L}(f) = \frac{\text{power in the SSB in 1 Hz}}{\text{power in the carrier}}$$



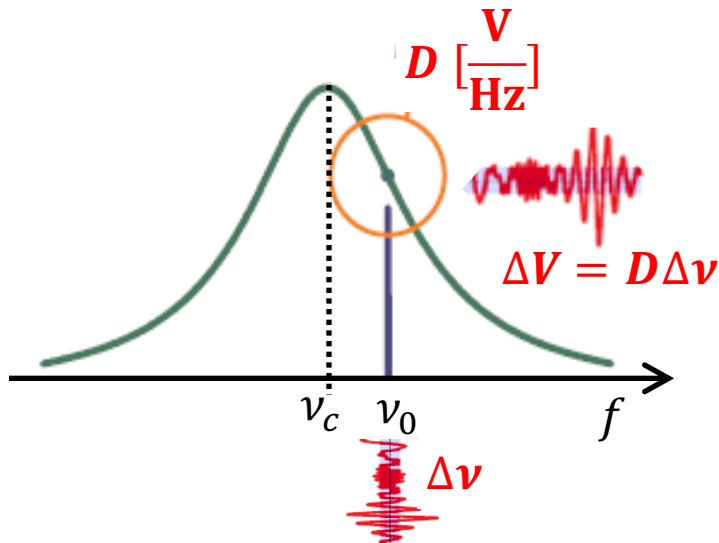
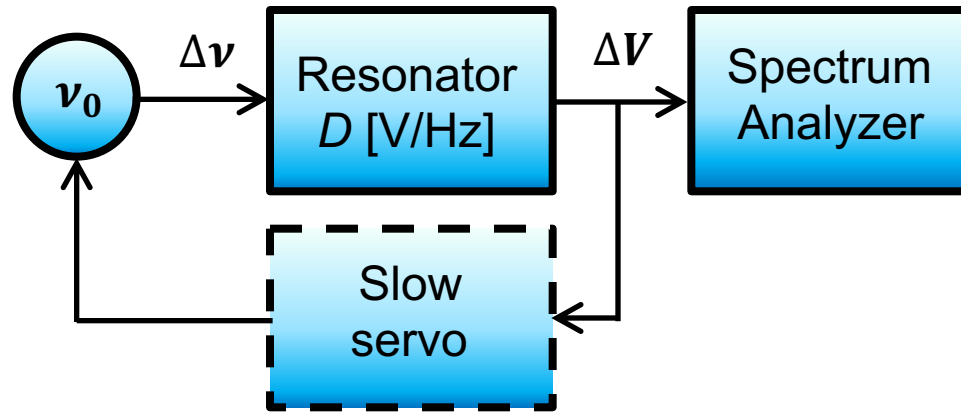
$$\mathcal{L}(f) \left[\frac{\text{dB}_c}{\text{Hz}} \right] = P_n \left[\frac{\text{dB}_m}{\text{Hz}} \right] - P_c [\text{dB}_m]$$

The problems with this measurement are (ambiguous results):

- it does not divide AM noise from PM noise
- improper value for phase noise larger than 1 rad!!



A resonator (band pass filter) converts the frequency fluctuations into intensity/voltage

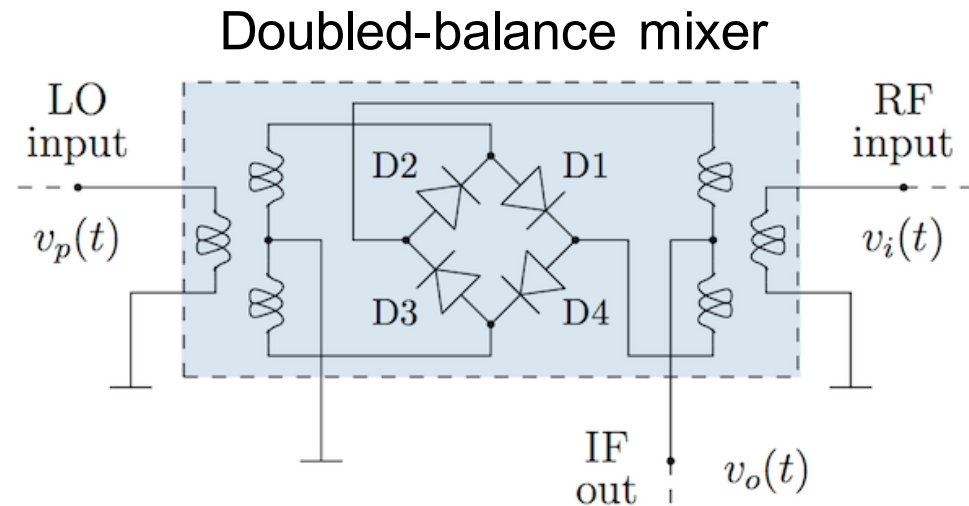
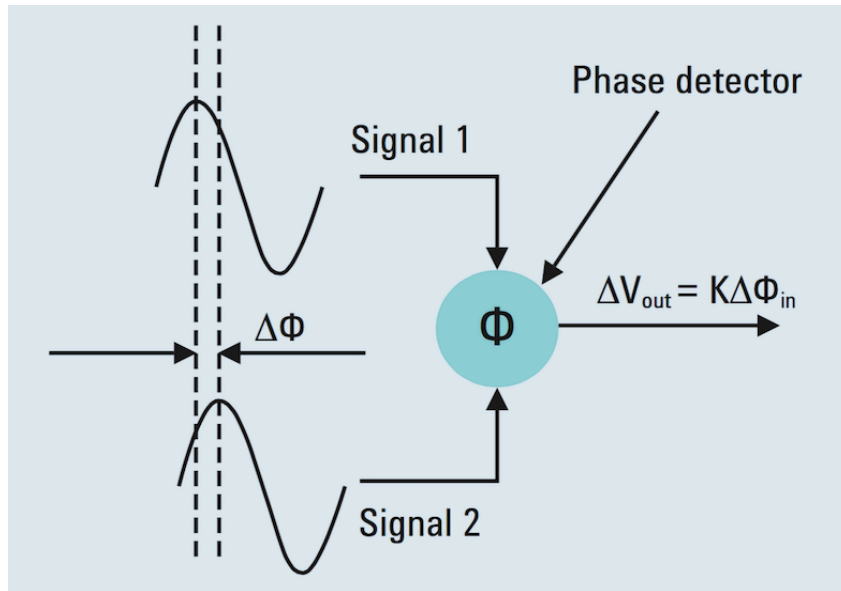


$$S_{\Delta V}(f) = D^2 S_{\Delta \nu}(f)$$

$$S_{\Delta \nu}(f) = \frac{S_{\Delta V}(f)}{D^2}$$

$$S_{\phi}(f) = f^2 \frac{S_{\Delta V}(f)}{D^2}$$

The phase detector converts the phase difference of the two input signals into a voltage at the output of the detector

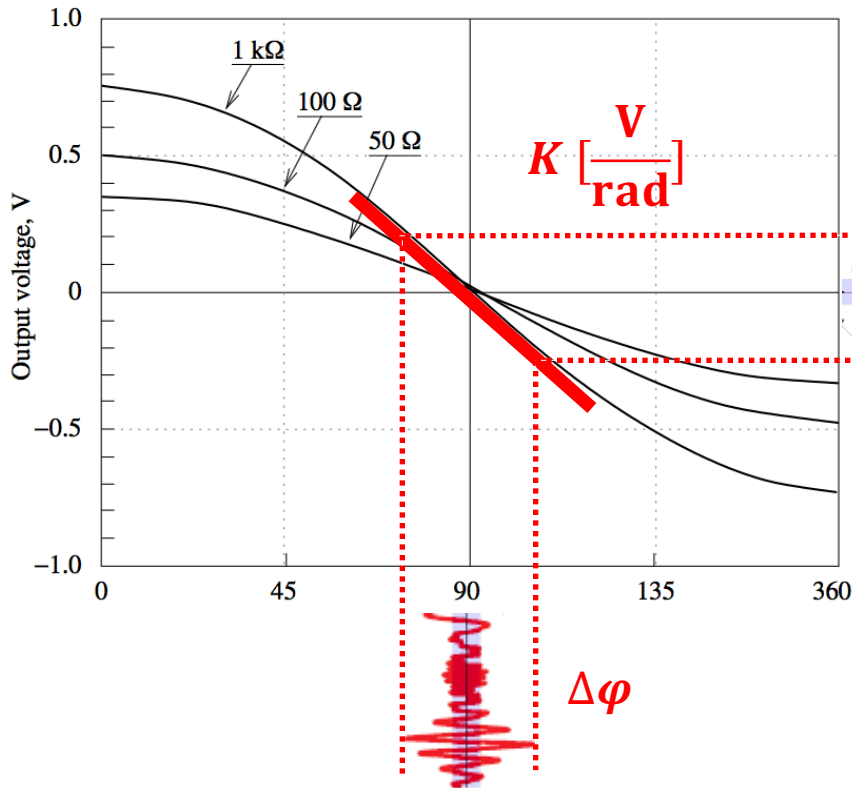
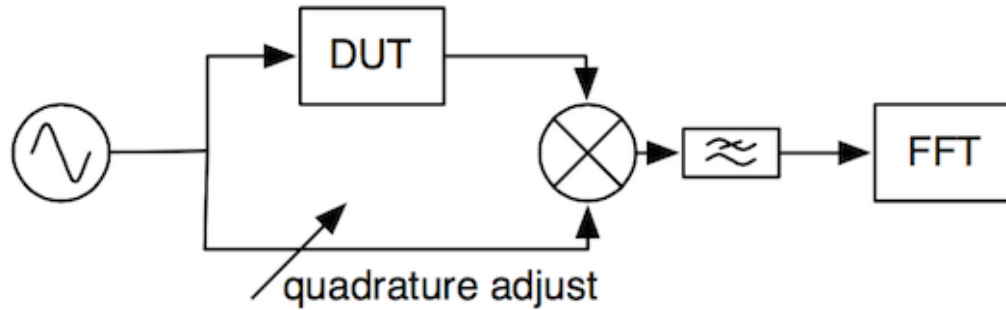


$$v_o(t) = kv_1(t)v_2(t) = kV_1V_2 \cos(2\pi\nu_0t + \varphi_1) \cos(2\pi\nu_0t + \varphi_2 + \Phi)$$

$$v_o(t) \Big|_{DC} = \frac{k}{2} V_1 V_2 [\cos(\varphi_1 - \varphi_2 + \Phi)]$$

$$v_o(t) \Big|_{\Phi=\frac{\pi}{2}} = \frac{k}{2} V_1 V_2 (\varphi_1 - \varphi_2) = K\Delta\varphi$$

Phase discriminator: measurement of a two port device



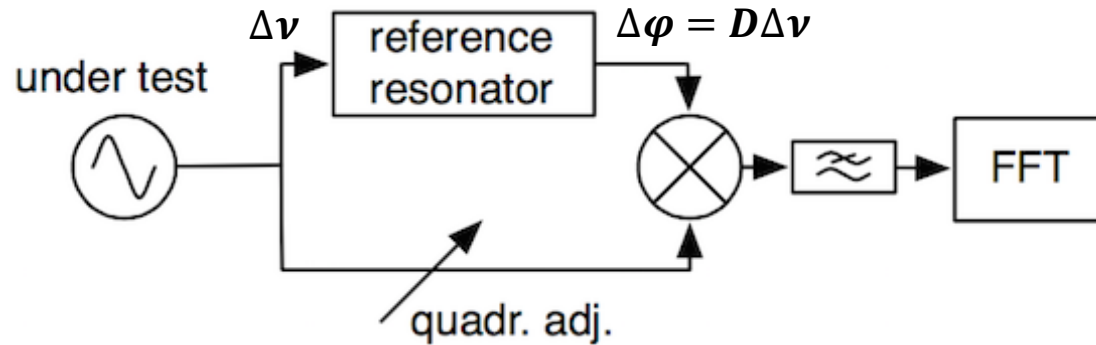
$$\Delta V = K \Delta \varphi$$

$$S_{\Delta V}(f) = K^2 S_{\Delta \varphi}(f)$$

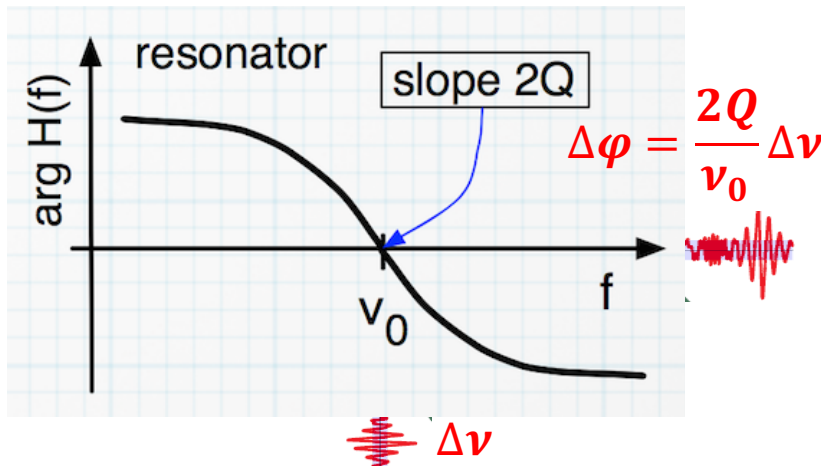
$$S_{\Delta \varphi}(f) = \frac{S_{\Delta V}(f)}{K^2}$$

Phase discriminator: combining a frequency discriminator

A frequency discriminator, a resonator/filter or a delay line, can be used to measure the oscillator phase noise



A resonator, the imaginary part of the complex transfer function, turns a slow frequency fluctuation into a phase fluctuation



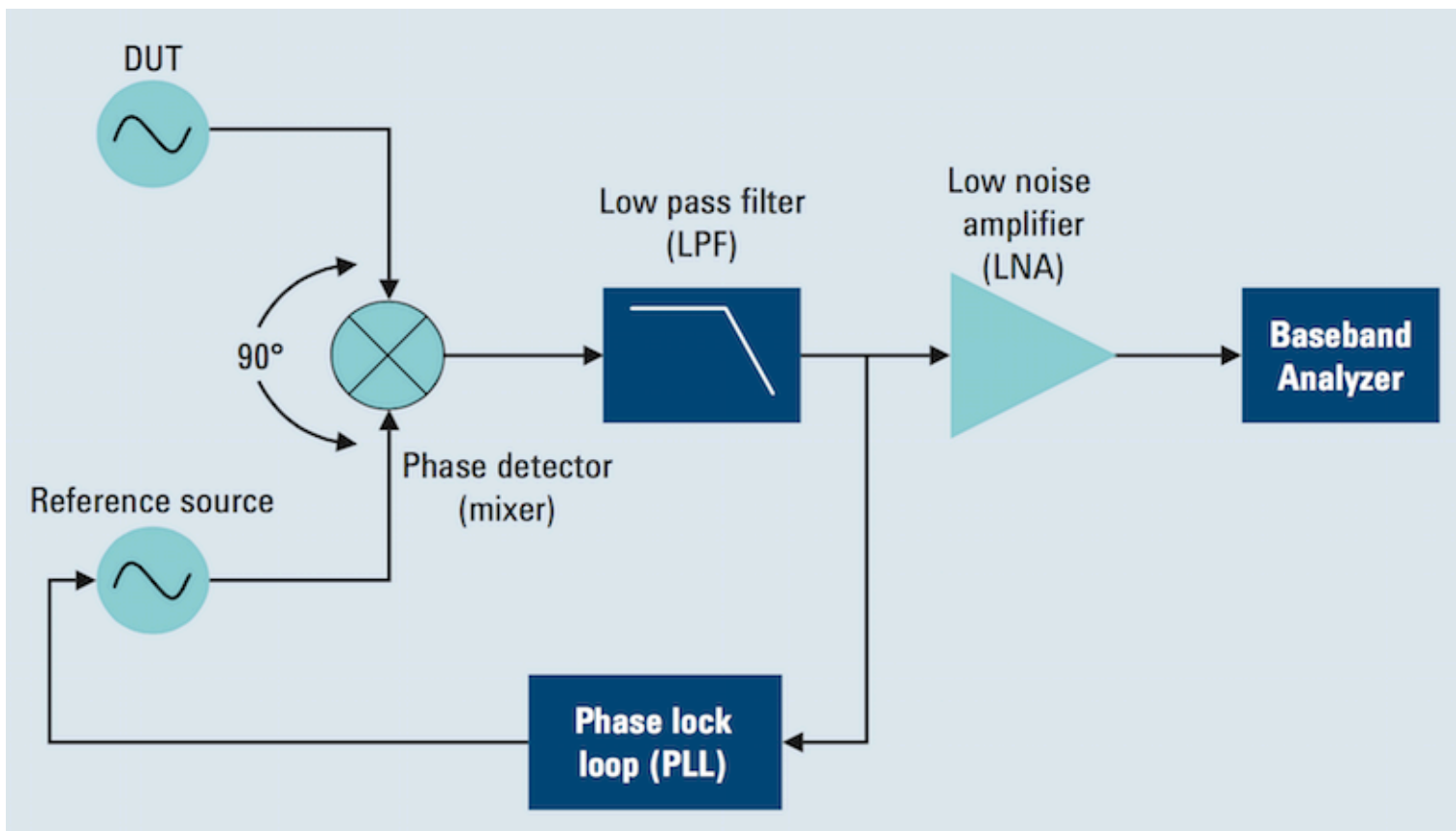
$$S_{\Delta V}(f) = K^2 S_{\Delta \phi}(f) = 4Q^2 K^2 S_y(f)$$

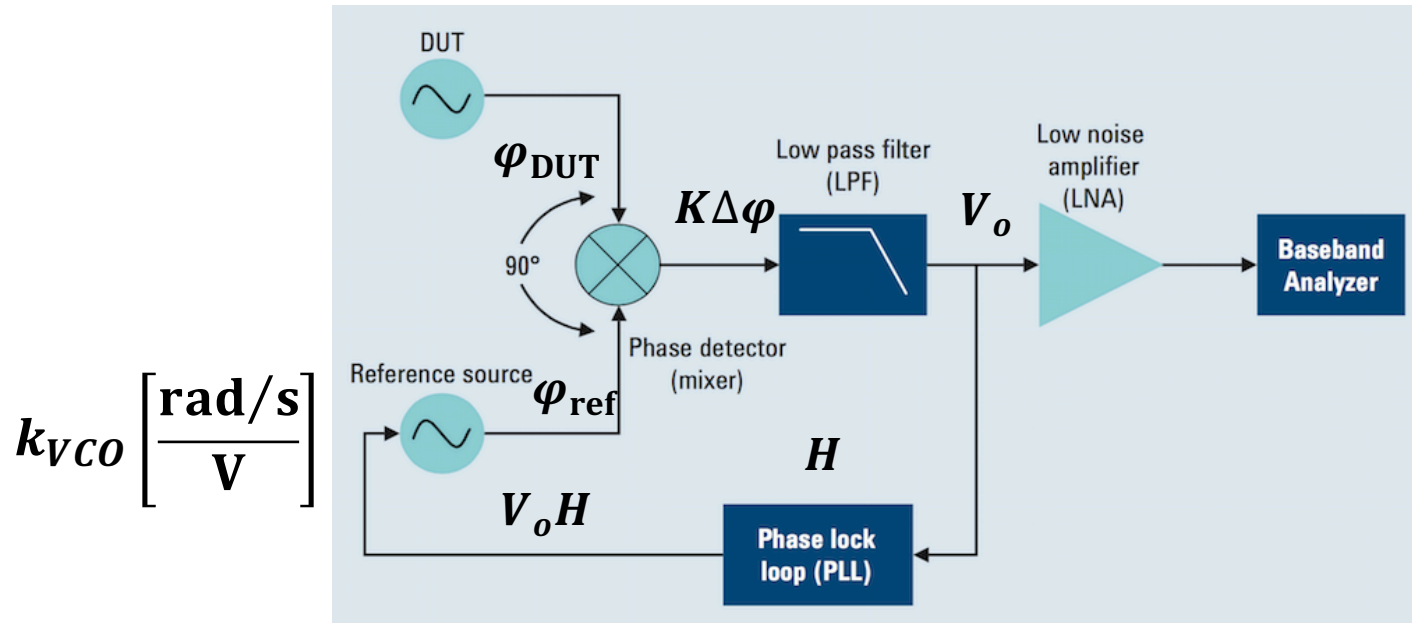
$$S_y(f) = \frac{S_{\Delta V}(f)}{4Q^2 K^2}$$

$$S_{\phi}(f) = \frac{S_{\Delta V}(f) f^2}{4Q^2 K^2 \nu_0^2}$$

Phase discriminator: measurement of oscillator phase noise using PLL

The reference source/PLL (phase-locked-loop) is one of the most widely used methods

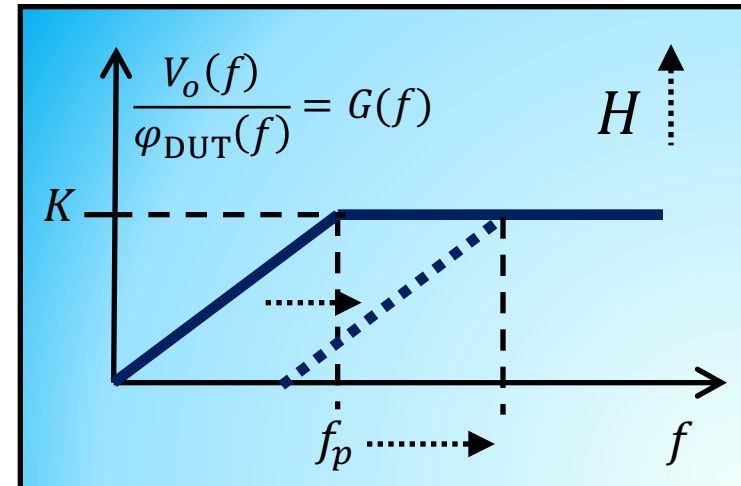




$$\varphi_{\text{ref}}(f) = \frac{k_{VCO} V_o H}{j2\pi f}$$

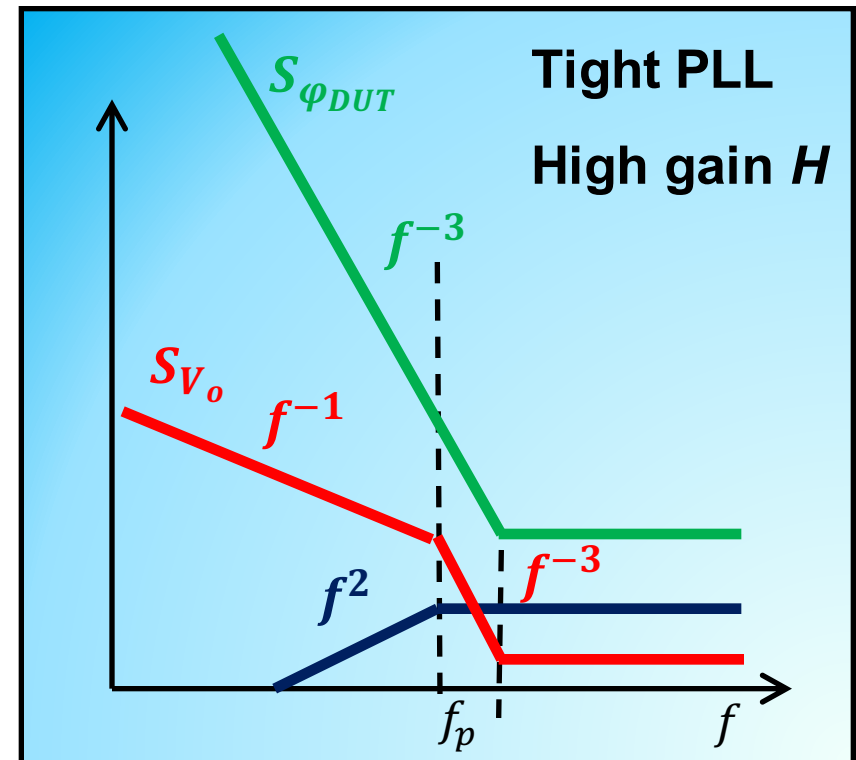
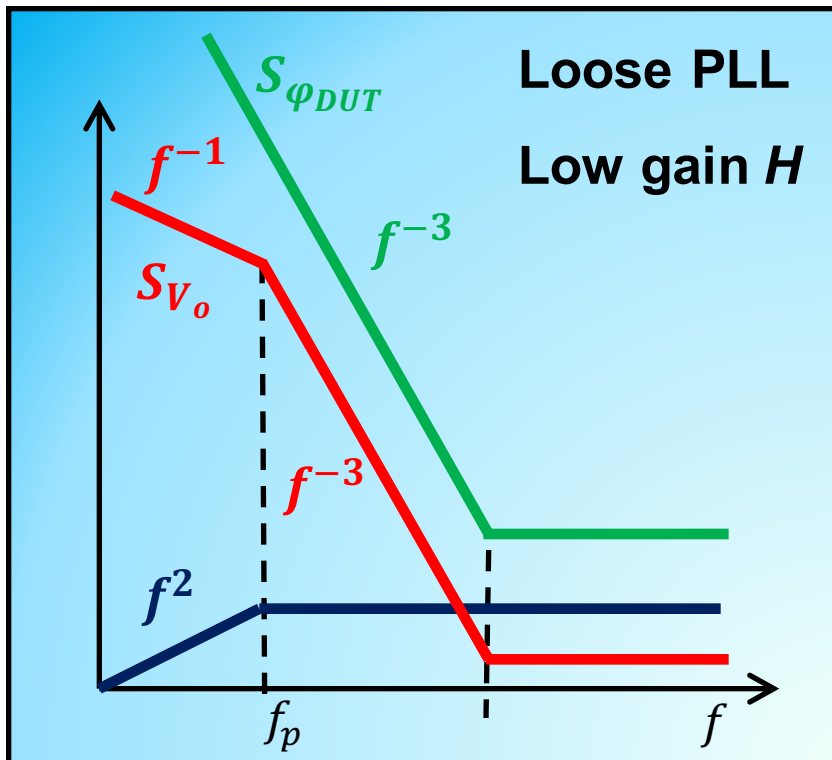
$$\frac{V_o(f)}{\varphi_{\text{DUT}}(f)} = \frac{j2\pi f K}{j2\pi f + k_{VCO} K H} = \frac{j \frac{f}{f_z}}{1 + j \frac{f}{f_p}} = G(f)$$

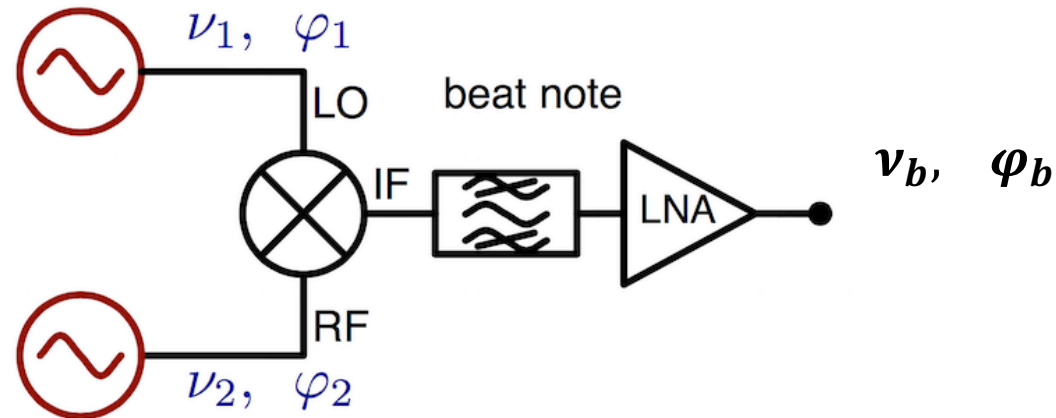
$$f_z = \frac{k_{VCO} H}{2\pi}; \quad f_p = \frac{k_{VCO} K H}{2\pi}$$



$$S_{V_o}(f) = |G(f)|^2 S_{\varphi_{DUT}}(f) = \frac{(2\pi f K)^2}{(2\pi f)^2 + (k_{VCO} K H)^2} S_{\varphi_{DUT}}(f)$$

$$S_{\varphi_{DUT}}(f) = \frac{S_{V_o}(f)}{|G(f)|^2} = \frac{(2\pi f)^2 + (k_{VCO} K H)^2}{(2\pi f K)^2} S_{V_o}(f)$$





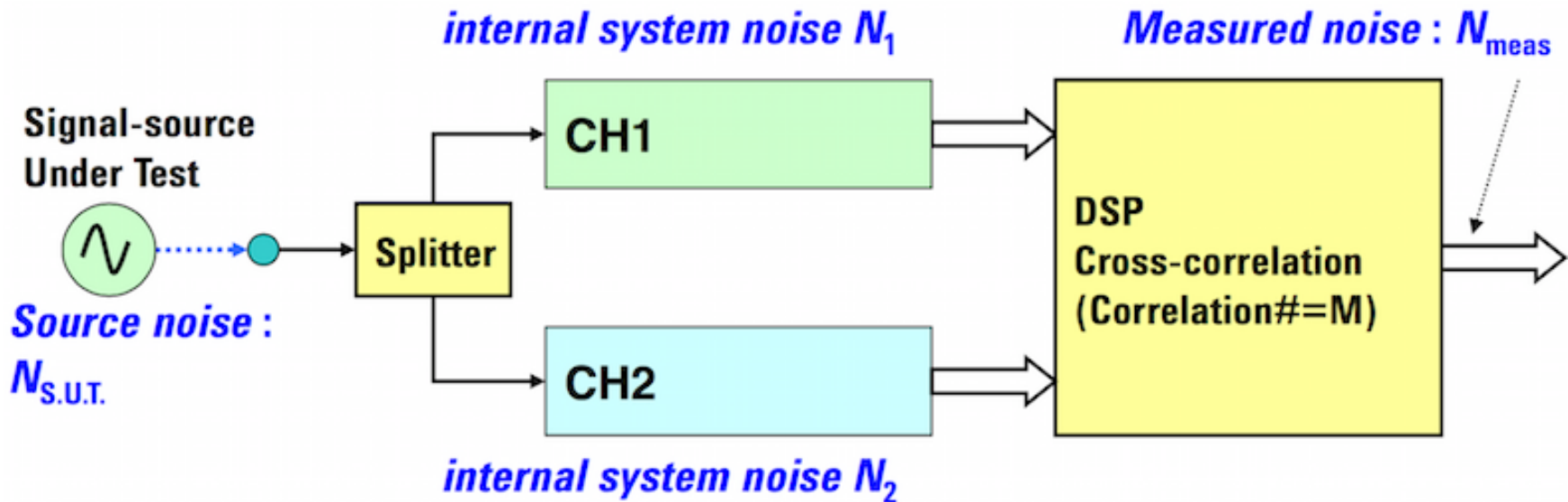
$$v_b(t) = k v_1(t) v_2(t) = k V_1 V_2 \cos(2\pi\nu_1 t + \varphi_1) \cos(2\pi\nu_2 t + \varphi_2)$$

$$v_b(t) \Big|_{\text{LF}} = \frac{k}{2} V_1 V_2 \cos[2\pi(\nu_1 - \nu_2)t + (\varphi_1 - \varphi_2)] = V_b \cos(2\pi\nu_b t + \varphi_b)$$

$$S_{\varphi_b}(f) = S_{\varphi_1}(f) + S_{\varphi_2}(f) = \frac{\nu_1^2}{f^2} S_{y_1}(f) + \frac{\nu_2^2}{f^2} S_{y_2}(f)$$

$$S_{y_b}(f) = \frac{f^2}{\nu_b^2} S_{\varphi_b}(f) = \frac{\nu_1^2}{\nu_b^2} S_{y_1}(f) + \frac{\nu_2^2}{\nu_b^2} S_{y_2}(f)$$

The two-channel cross-correlation technique combines two duplicate single-channel reference sources/PLL systems and performs cross-correlation operations between the outputs of each channel



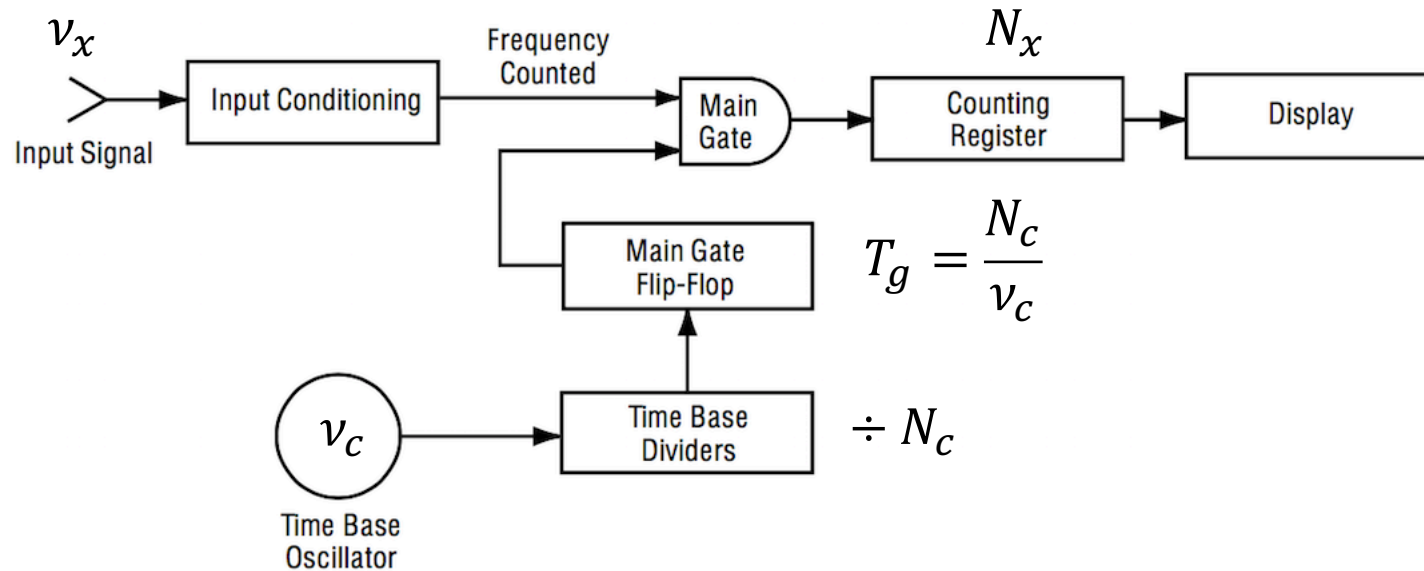
$$N_{meas} = N_{SUT} + \frac{(N_1 + N_2)}{\sqrt{M}}$$

Number of correlation M	Noise floor reduction
10^2	10 dB
10^4	20 dB

1. Classical counter (old)
2. Reciprocal counter
3. Interpolation methods



Enrico Rubiola,
FEMTO-ST Institute, CNRS and Université Franche Comté
<http://www.rubiola.org/> (also <http://rubiola.net>)

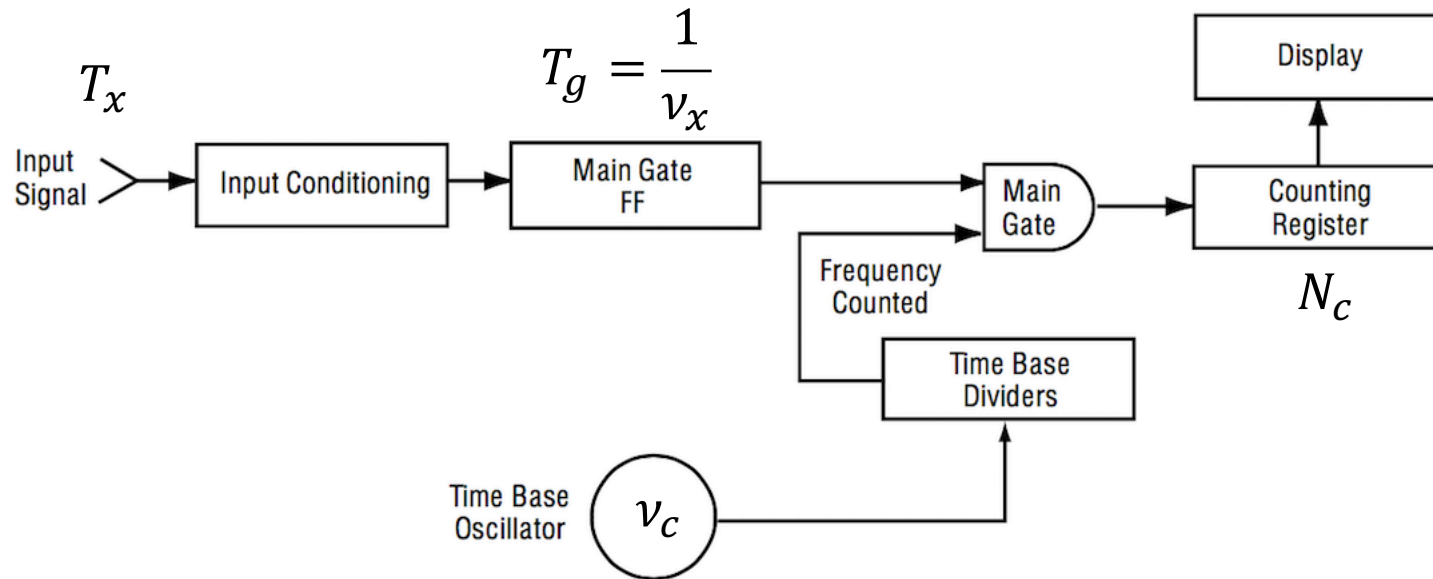


$$\nu_x = \frac{N_x}{T_g} = N_x \frac{\nu_c}{N_c}$$

$$\frac{\Delta \nu_x}{\nu_x} = \frac{1}{T_g \nu_x}$$

The resolution is set by input period which can be significantly lower than reference clock

Example: $\nu_x = 100$ Hz; $\nu_c = 10$ MHz; $T_g = 1$ s RES = 10^{-2}

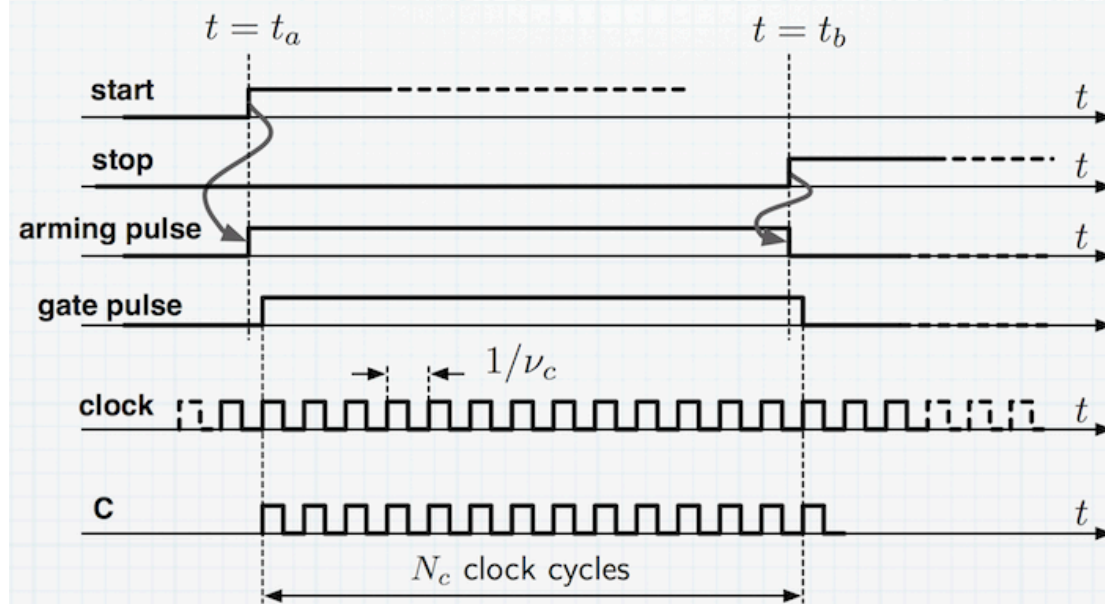
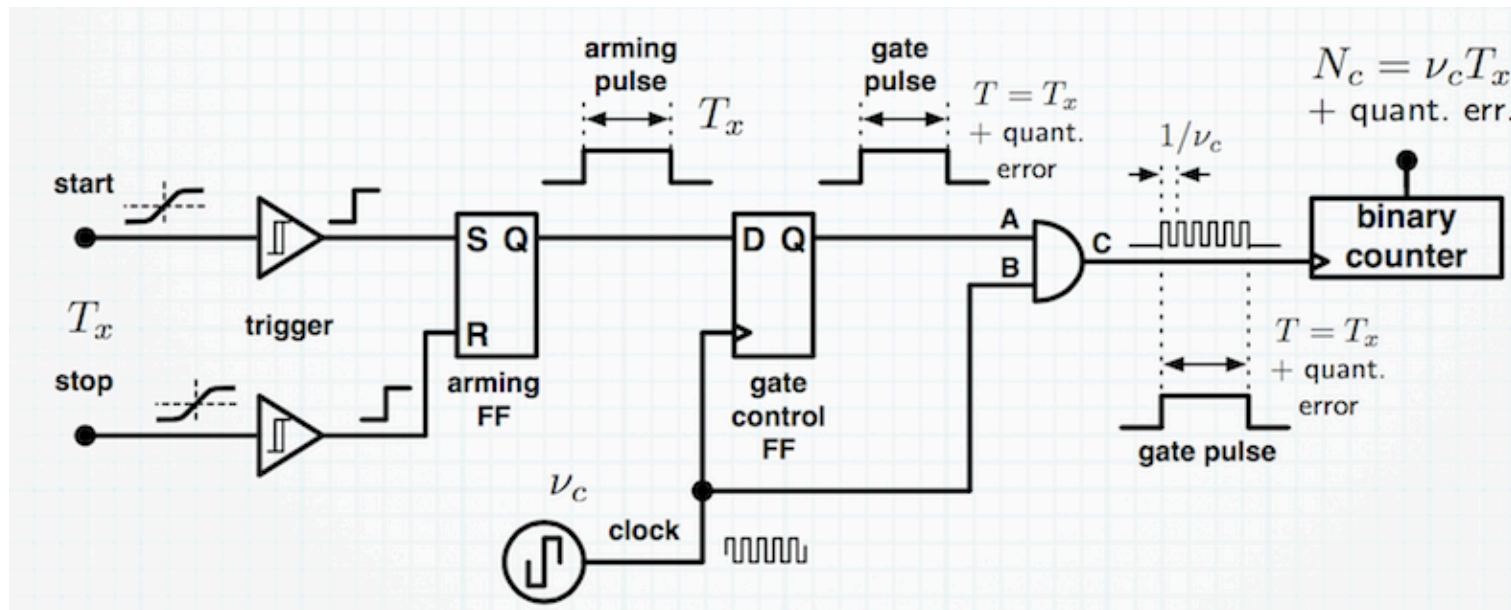


$$T_x = \frac{1}{\nu_x} = N_c T_c$$

$$\frac{\Delta T_x}{T_x} = \frac{1}{T_g \nu_c}$$

The resolution is set by reference period

Example: $\nu_x = 100$ Hz; $\nu_c = 10$ MHz; $T_g = 1$ s RES = 10^{-5}

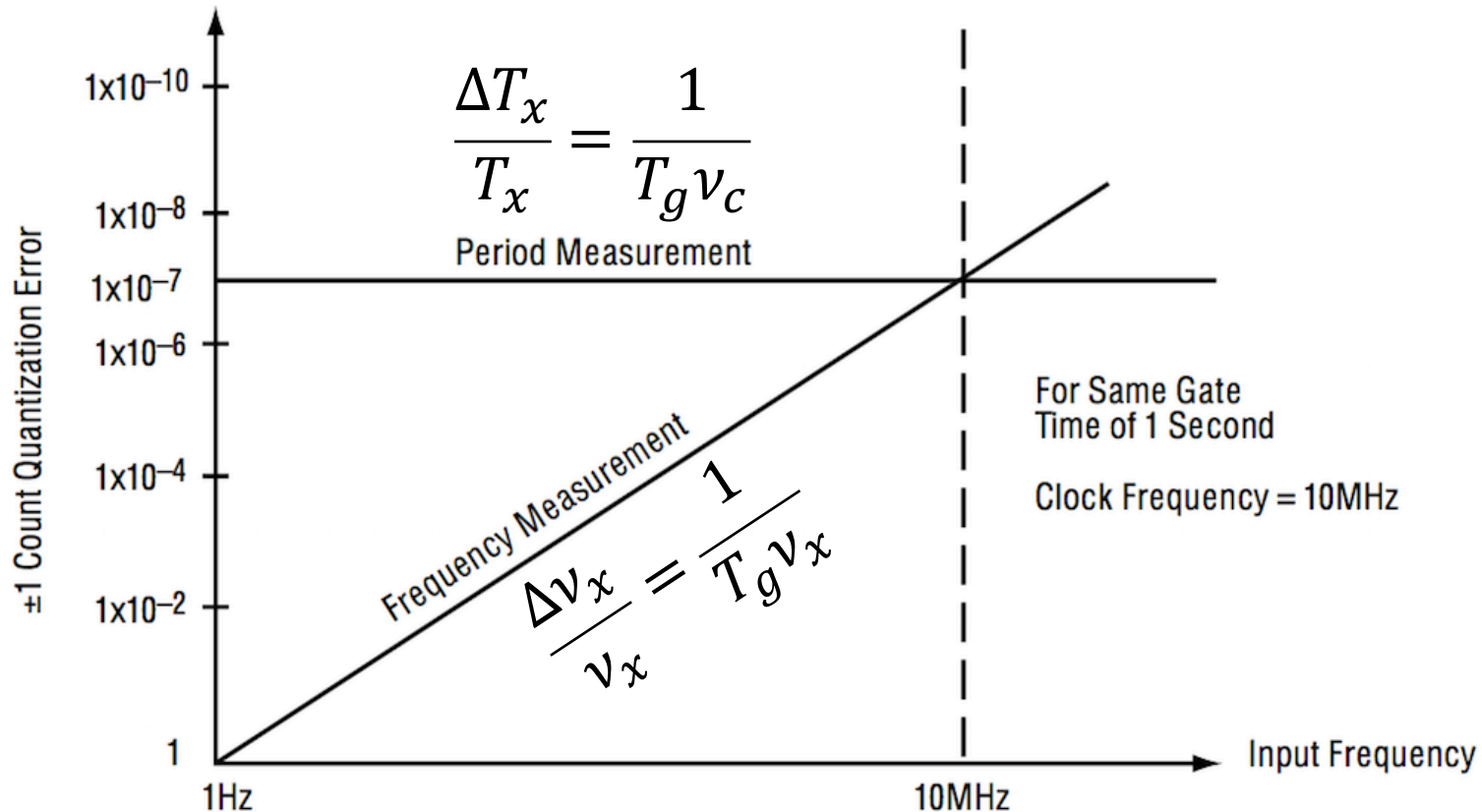


$$T_x = N_c T_c = \frac{N_c}{\nu_c}$$

$$\Delta T_x = T_c = \frac{1}{\nu_c}$$

Set by clock reference

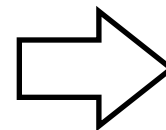
Comparison between frequency and period resolution



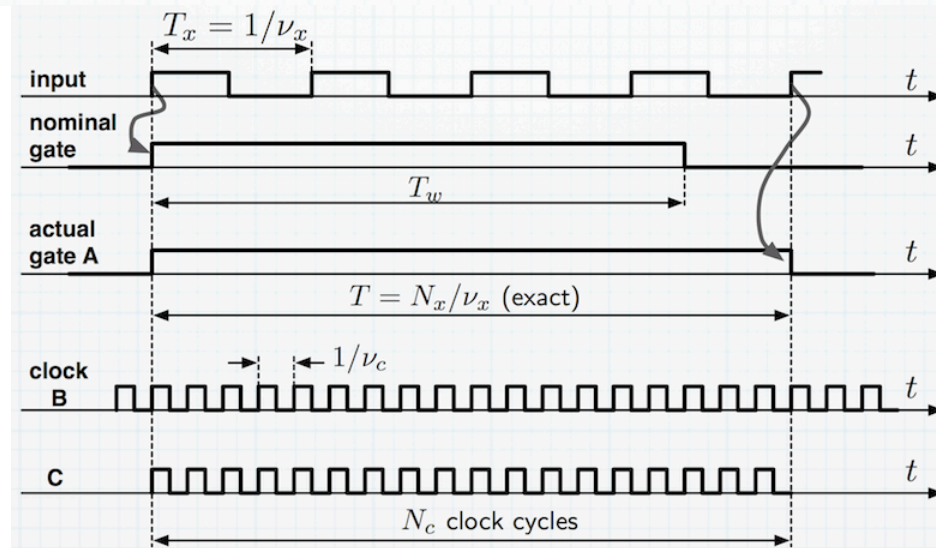
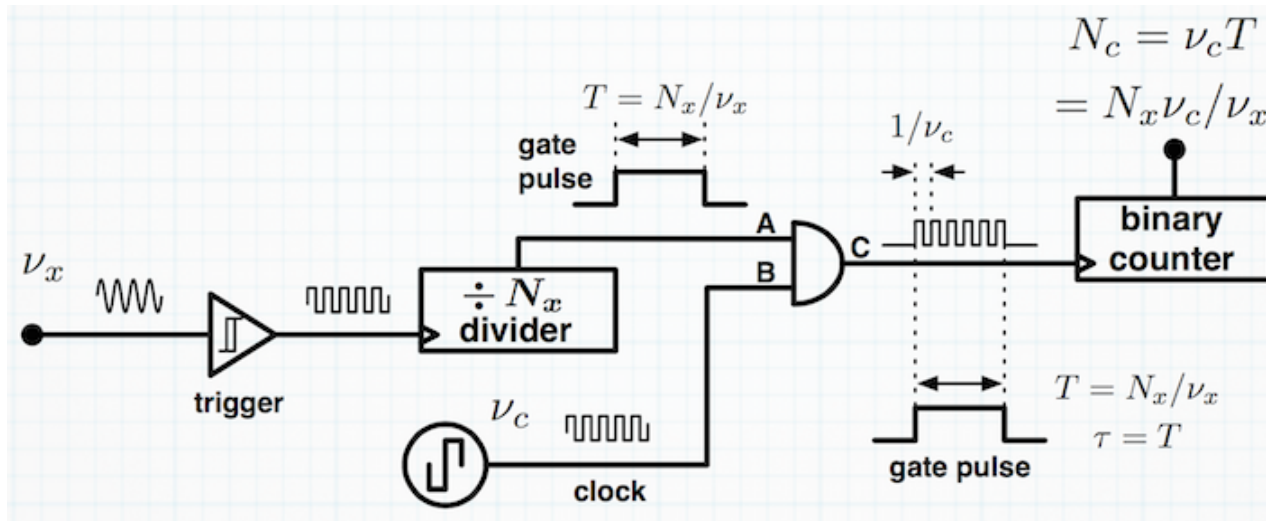
Measurement strategy

$\nu_x < \nu_c$ period measurement

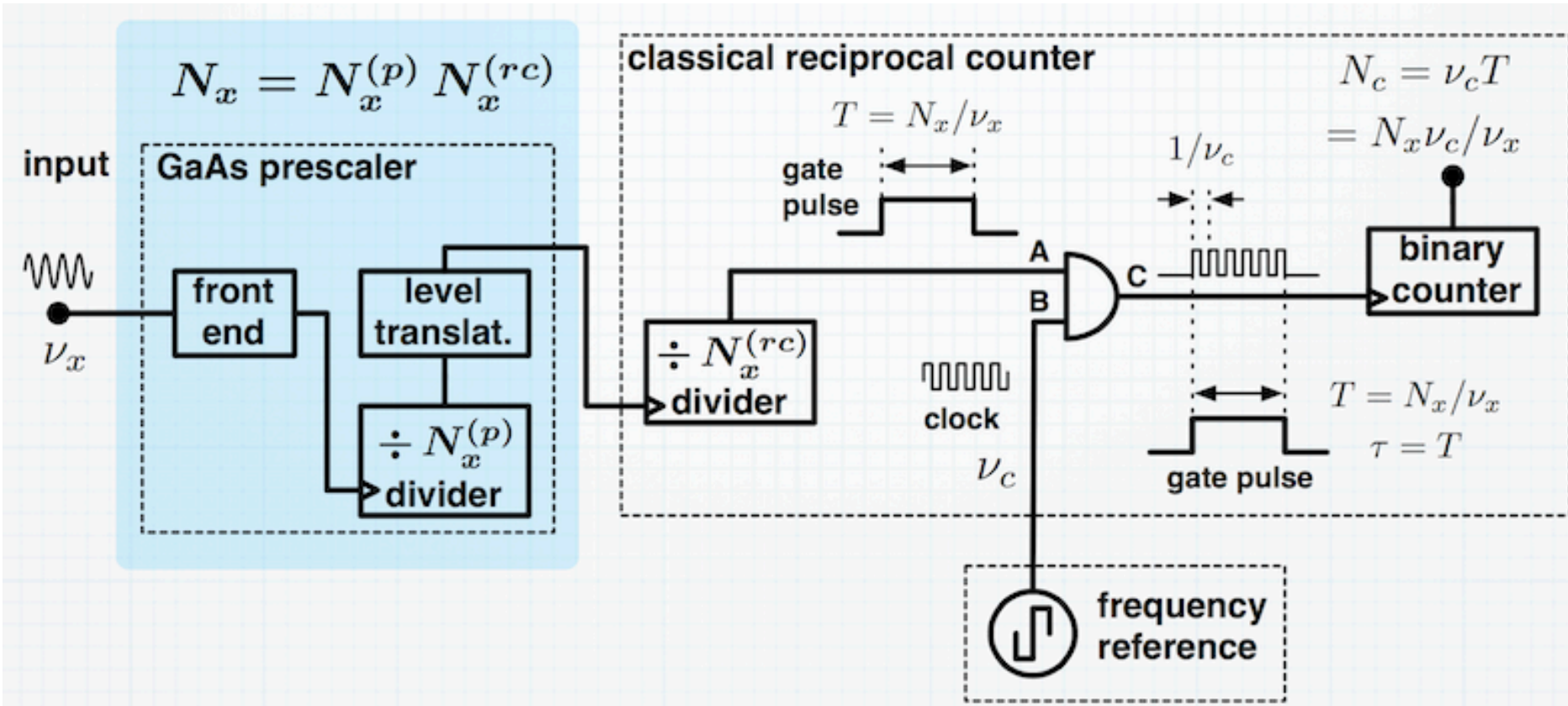
$\nu_x > \nu_c$ frequency measurement



RECIPROCAL COUNTER



- Use the highest clock frequency permitted by the hardware
- The measurement time is a multiple of the input period

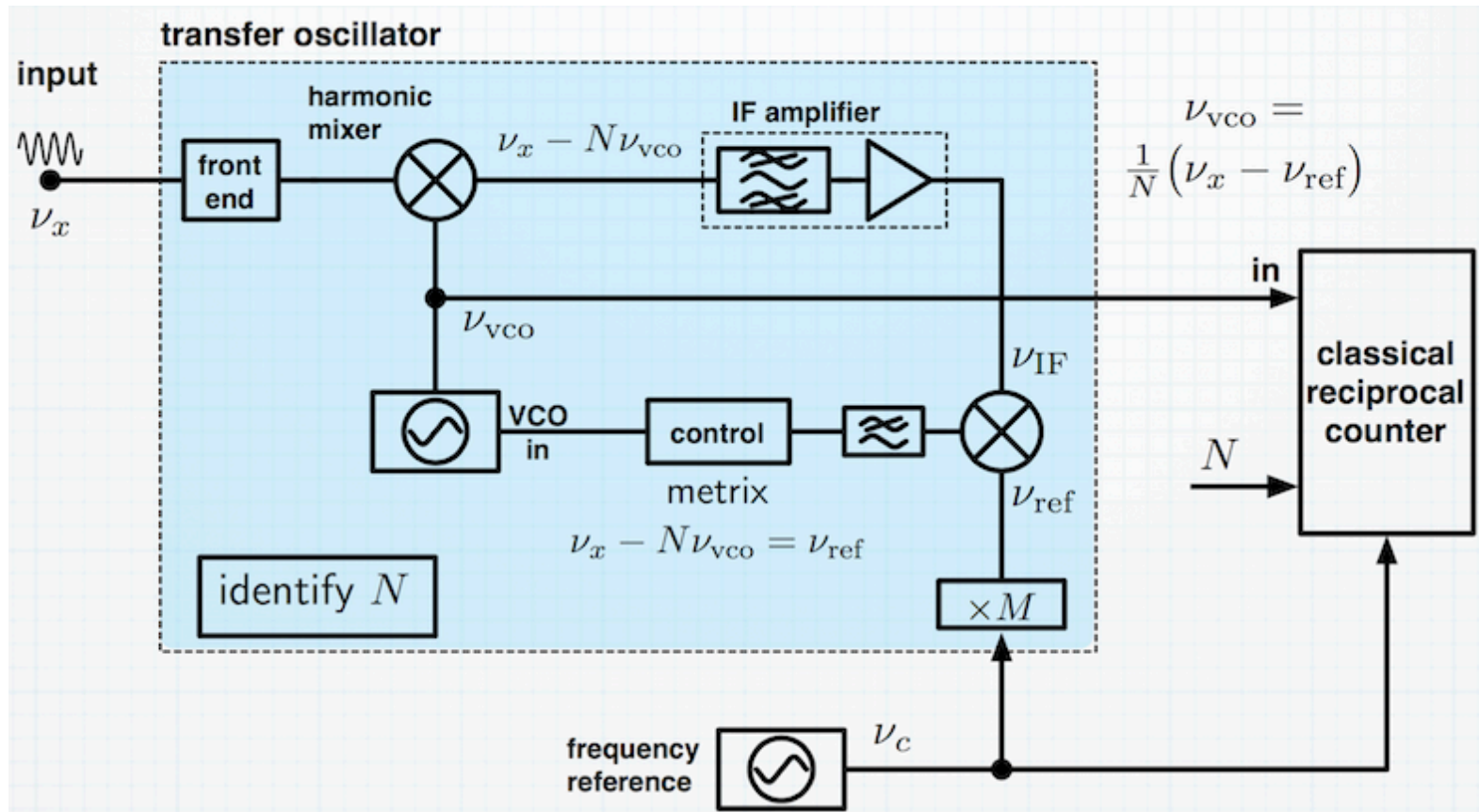


The prescaler is a n-bit binary divider $\div N_x^{(p)} = 2^n$

GaAs fast prescaler works up to 20-50 GHz

Most microwave counters use fast prescalers

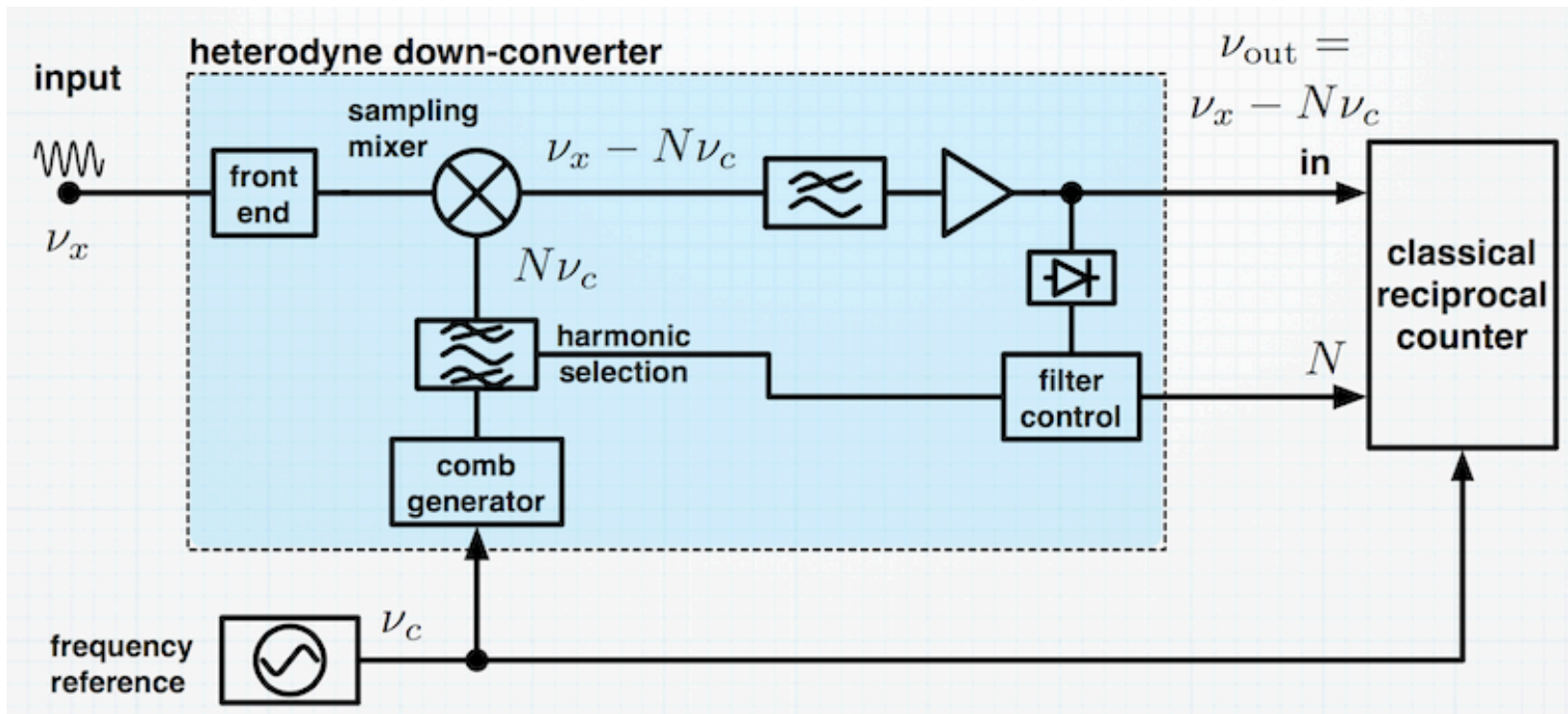
High-frequency measurement: Transfer oscillator



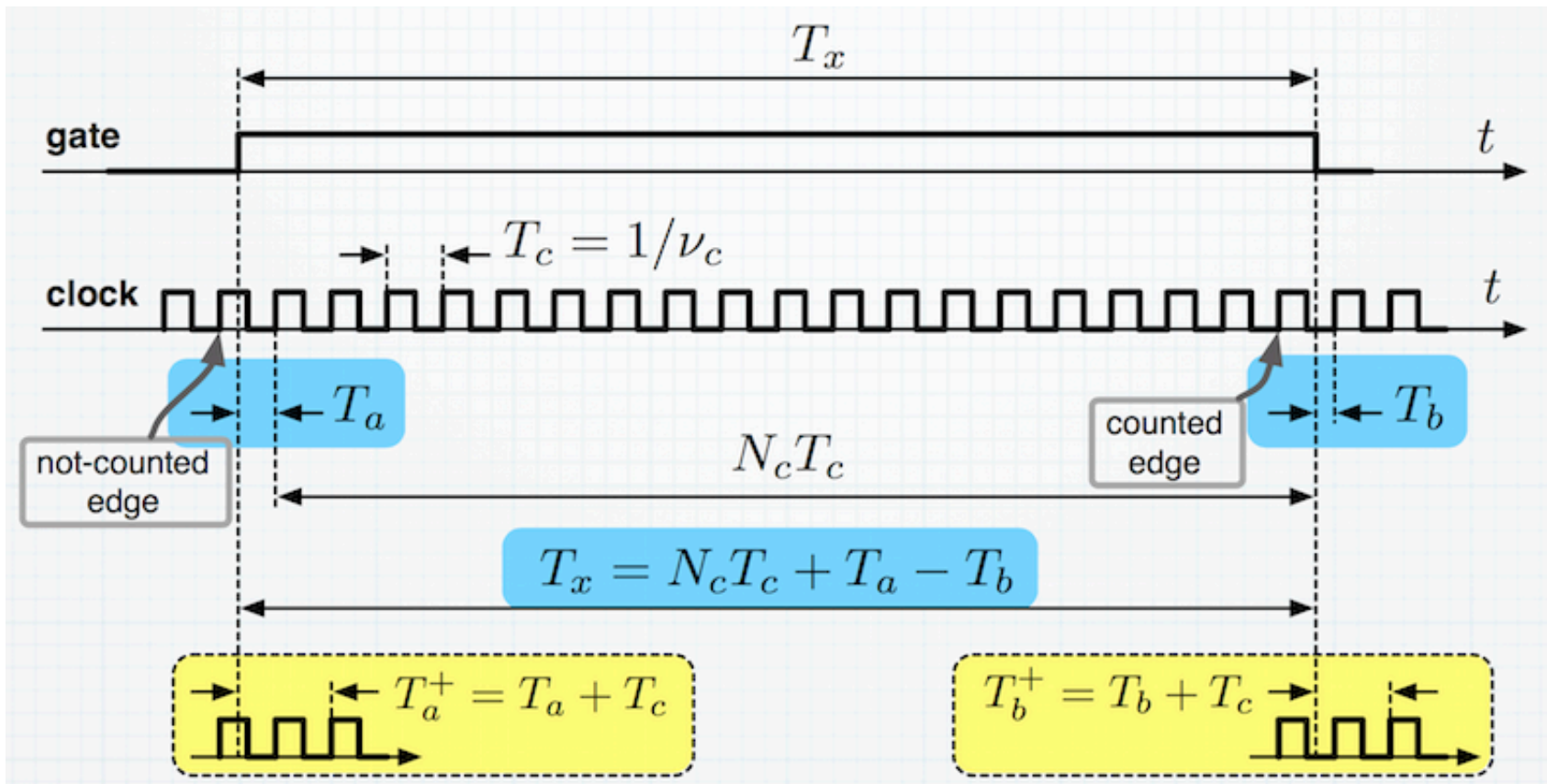
The transfer oscillator is a PLL

The counter measures the VCO frequency

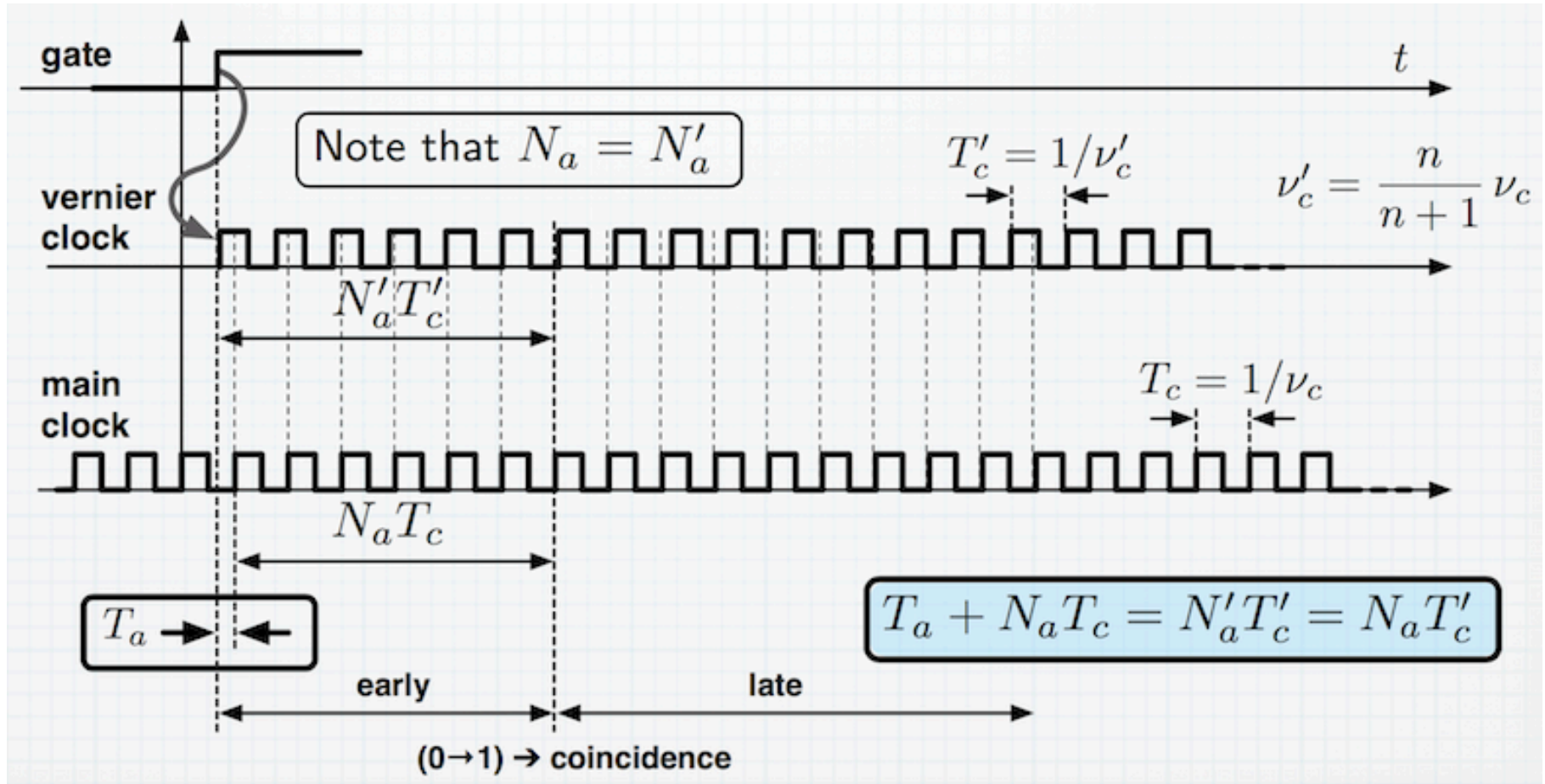
The harmonic N has to be measured (modulation frequency)

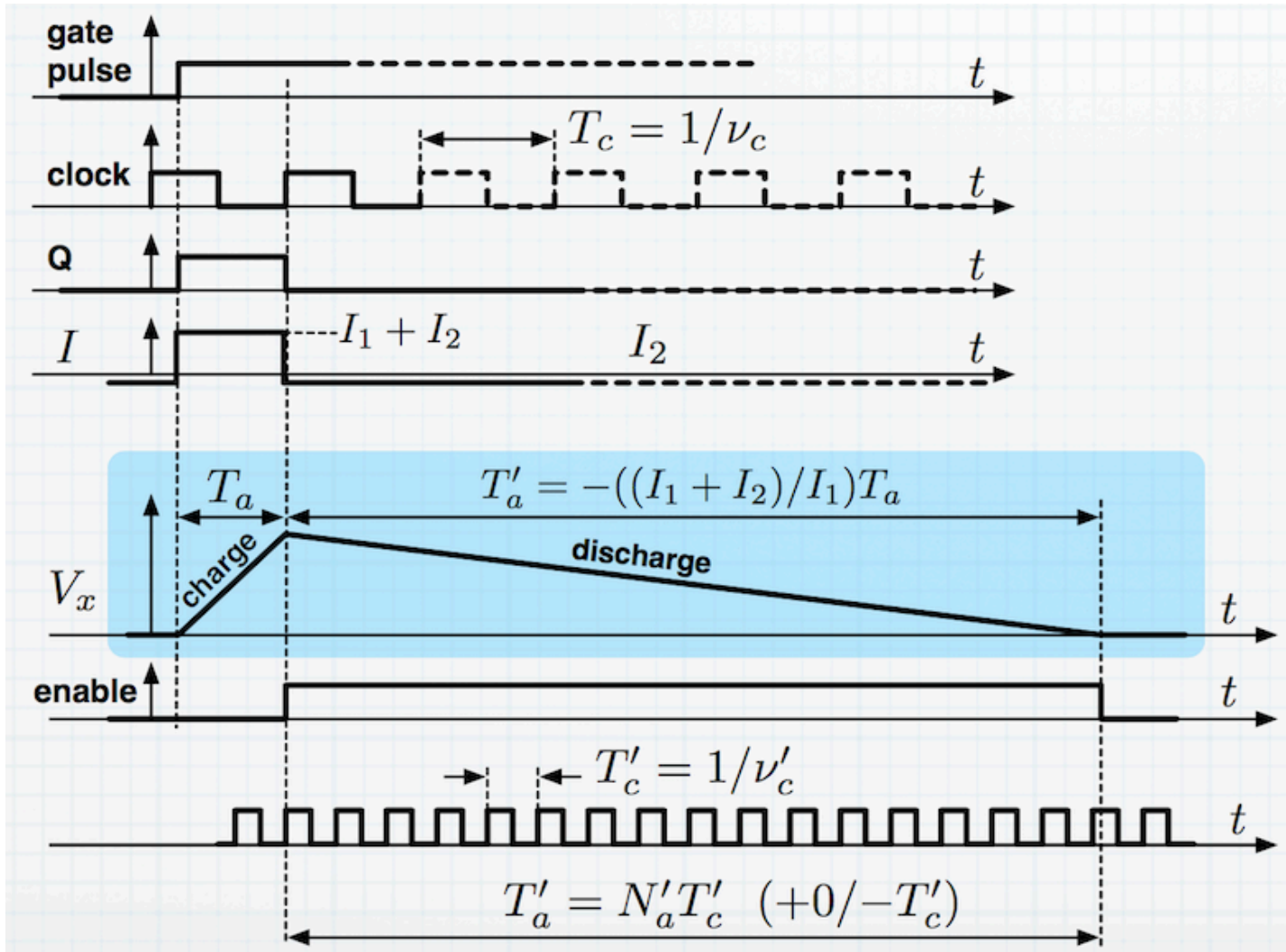


The beat frequency is in the range of the classic counters
100-200 MHz

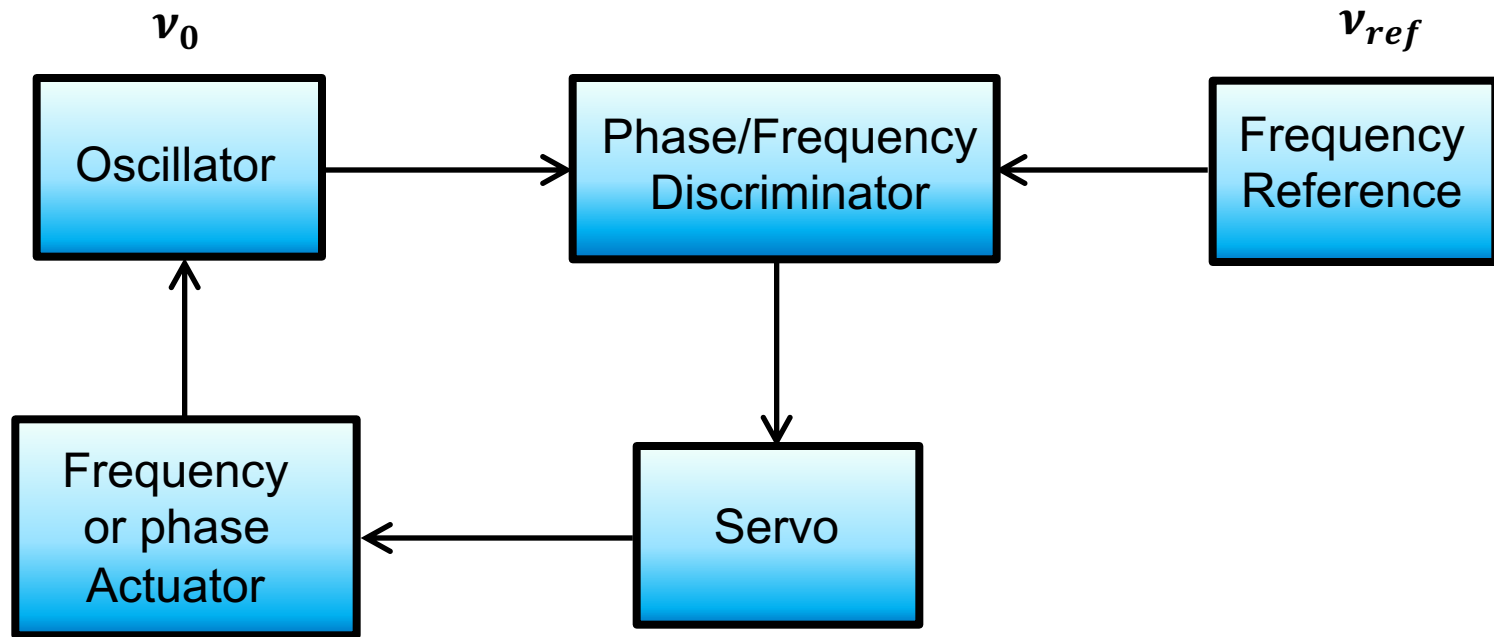


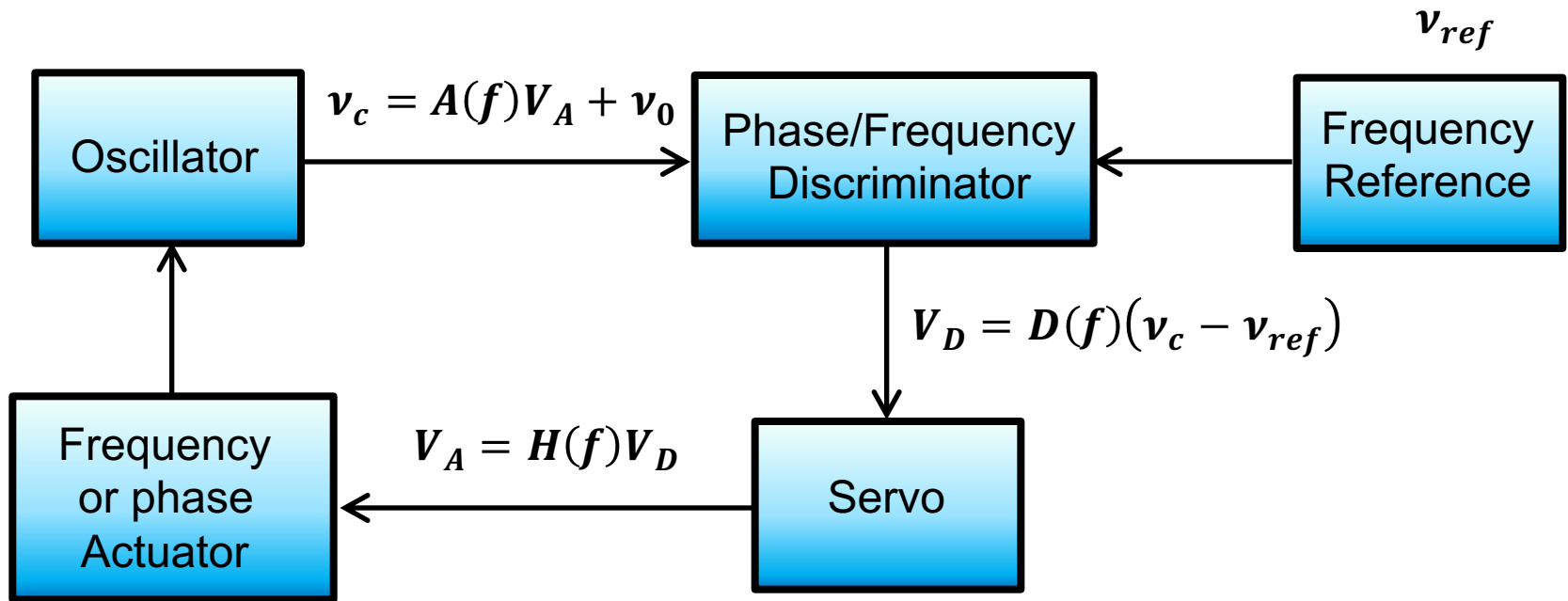
The interpolation is based on the high-stability and accuracy reference clock





1. General scheme
2. Stability performance
3. Some examples





$$v_c(f) = \frac{v_0(f) - v_{ref}(f)D(f)H(f)A(f)}{1 + D(f)H(f)A(f)} = \frac{v_0(f) - G_{loop}(f)v_{ref}(f)}{1 + G_{loop}(f)}$$

$$S_{v_c}(f) = \frac{S_{v_0}(f)}{|1 + G_{loop}(f)|^2} + \frac{S_{v_{ref}}(f)|G_{loop}(f)|^2}{|1 + G_{loop}(f)|^2}$$

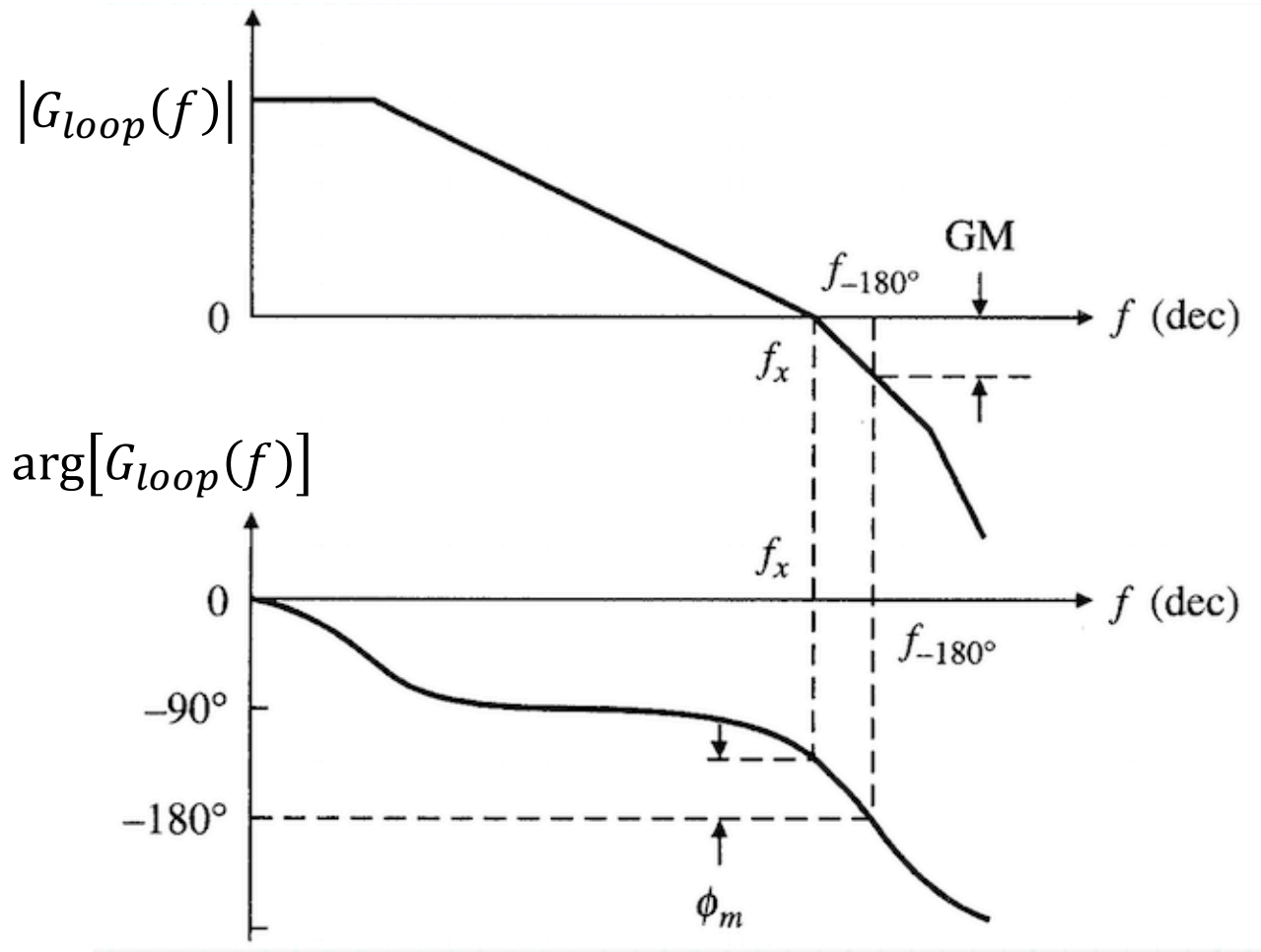
$$S_{v_c}(f) = \frac{S_{v_0}(f)}{|1 + G_{loop}(f)|^2} + \frac{S_{v_{ref}}(f) |G_{loop}(f)|^2}{|1 + G_{loop}(f)|^2}$$

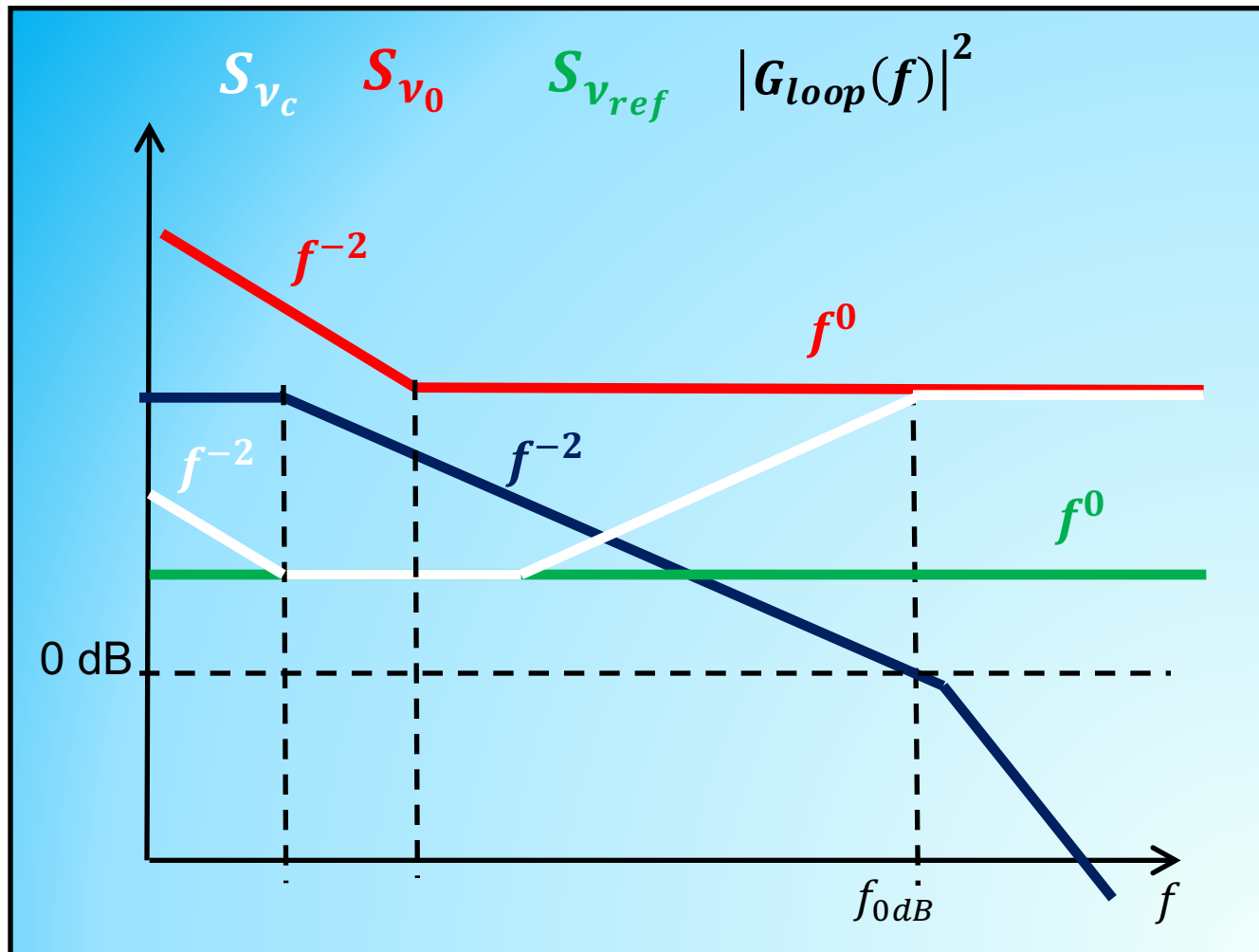
For $|G_{loop}(f)| \gg 1$

$$S_{v_c}(f) = \frac{S_{v_0}(f)}{|G_{loop}(f)|^2} + S_{v_{ref}}(f) \cong S_{v_{ref}}(f)$$

For $|G_{loop}(f)| \ll 1$

$$S_{v_c}(f) = S_{v_0}(f) + S_{v_{ref}}(f) |G_{loop}(f)|^2 \cong S_{v_0}(f)$$

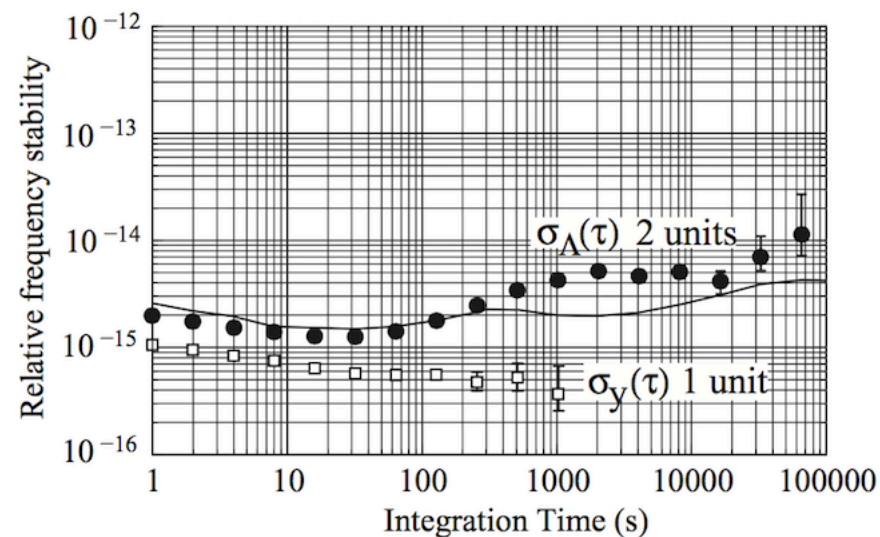
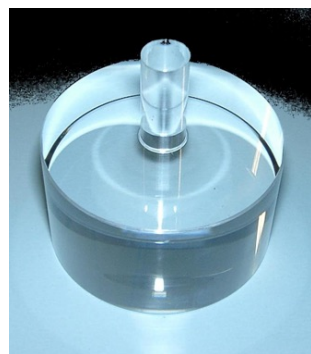
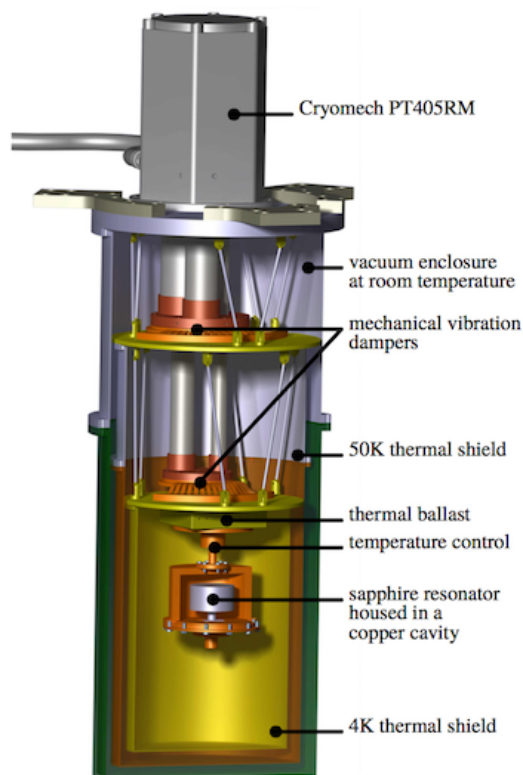




AIP | Review of Scientific Instruments

New-generation of cryogenic sapphire microwave oscillators for space, metrology, and scientific applications

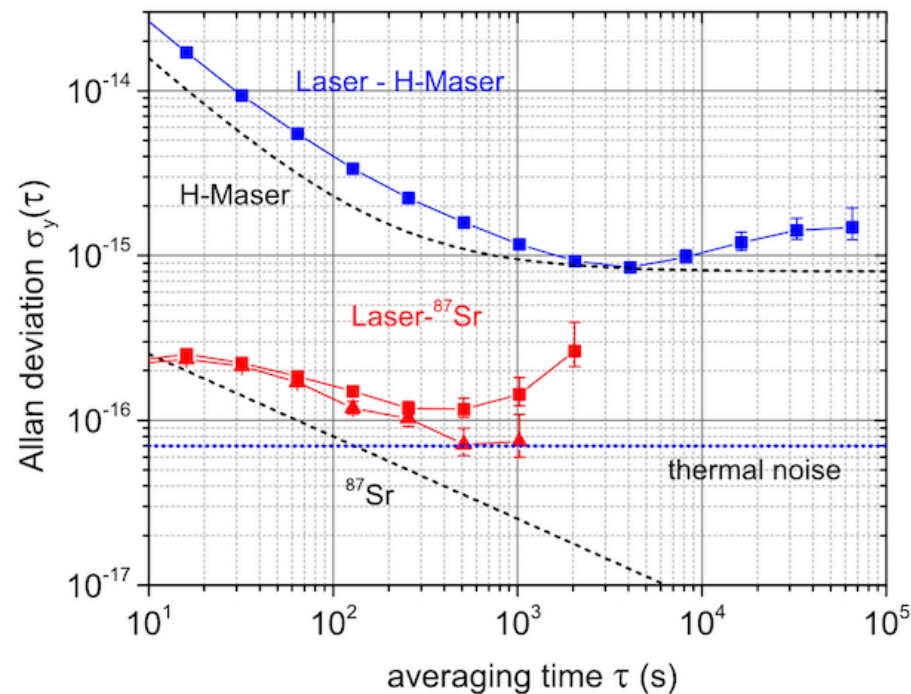
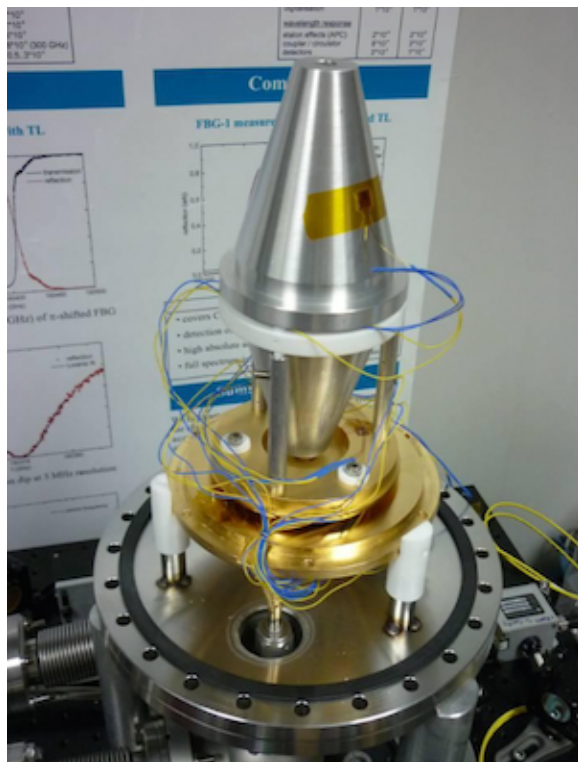
Vincent Giordano, Serge Grop, Benoît Dubois, Pierre-Yves Bourgeois, Yann Kersalé et al.



OPTICS LETTERS / Vol. 39, No. 17 / September 1, 2014

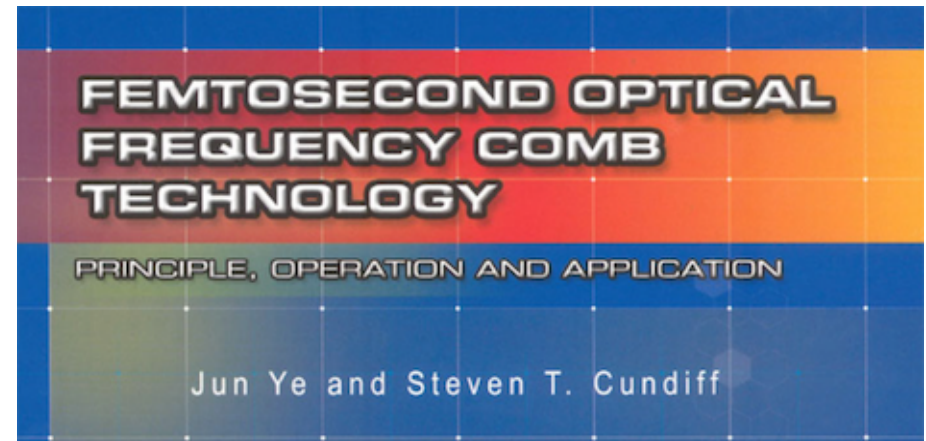
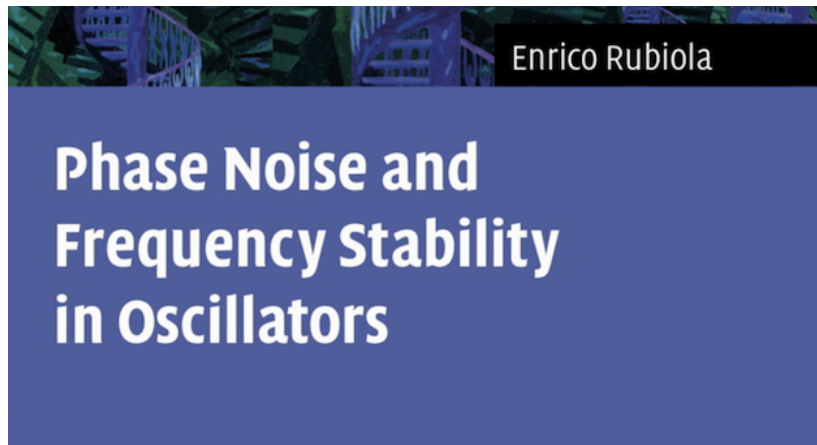
Ultrastable laser with average fractional frequency drift rate below $5 \times 10^{-19}/s$

Christian Hagemann,¹ Christian Grebing,¹ Christian Lisdat,¹ Stephan Falke,¹ Thomas Legero,¹ Uwe Sterr,^{1,*} Fritz Riehle,¹ Michael J. Martin,² and Jun Ye²



Agilent Application Notes on Phase Measurements, Electronic Counters, Electrical spectrum analyzer, Quartz Oscillators

Agilent's Phase Noise Measurement Solutions Finding the Best Fit for Your Test Requirements, Selection Guide



Thank you for attention

...a special thank to Elio



Washington DC, July 1998