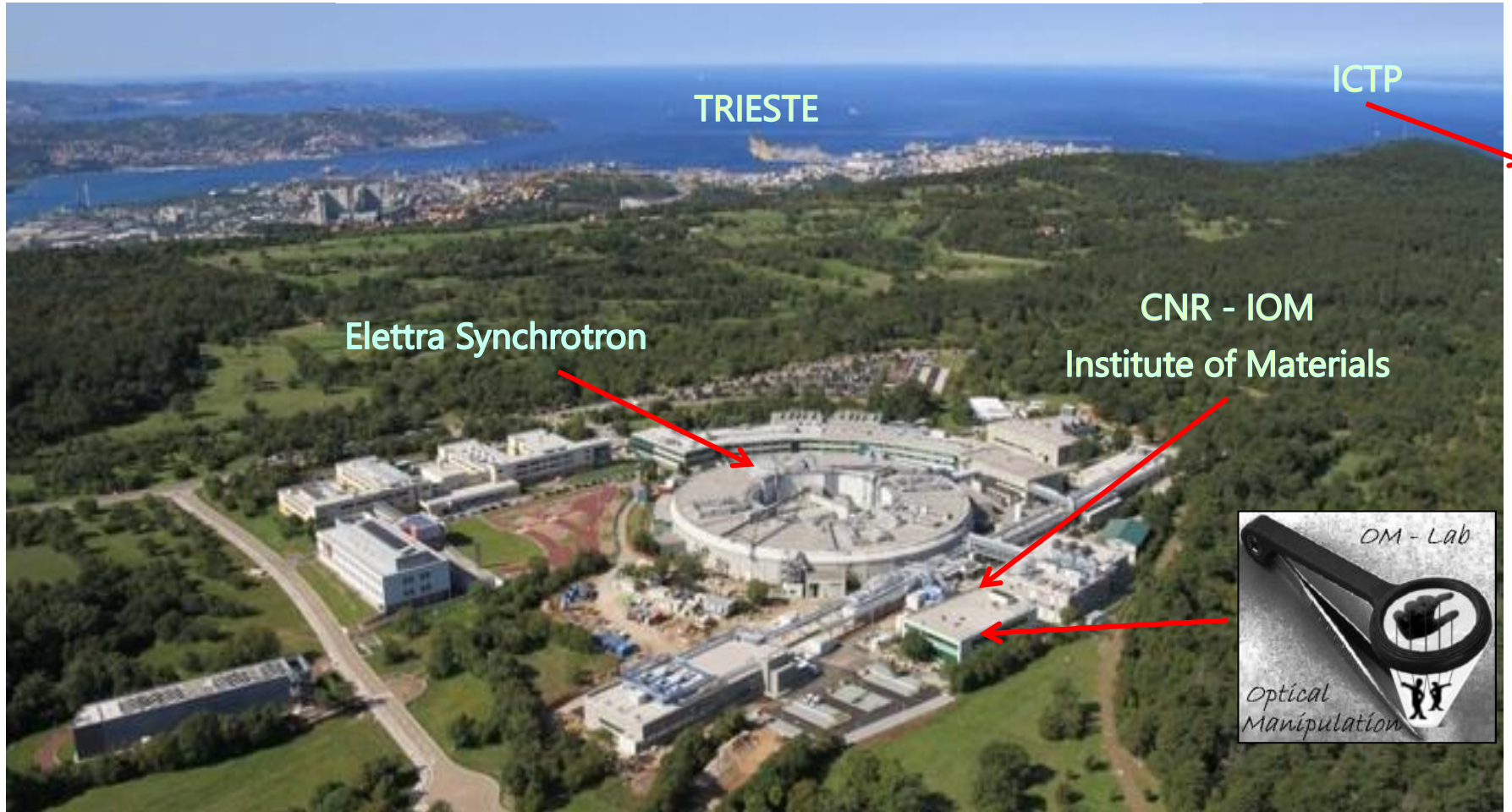


Optical Tweezers: basics and applications

Dan COJOC



National Research Council of Italy



Winter College on Optics: Advanced Optical Techniques for Bio-imaging
13 - 24 Feb 2017, ICTP - Trieste

OUTLINE

- **Optical Tweezers (OT) - single-beam gradient force 3D optical trap: how this works, optical manipulation of microparticles**
- **Measuring piconewton forces with OT: direct and indirect methods**
- **Applications of OT in living cell studies:**
 - **probing forces expressed by developing neurons**
 - **probing the stiffness of cancer cells**
 - **mechanotransduction - conversion of the mechanical stimulus into a biochemical signal by the cell**
 - **biochemical local cell stimulation using optically manipulated vectors (coated beads, biodegradable micro-sources, liposomes)**

A photon has the energy: $E = h \nu$ and carries momentum : $p = E / c$

- Momentum can be transferred to an object by interaction (e.g. reflection)
- **Radiation pressure:** the pressure exerted by light on the object surface

- For a light wave beam, carrying a momentum flux:
$$d\left(\frac{d\vec{P}}{dt}\right) = \vec{S} dS$$

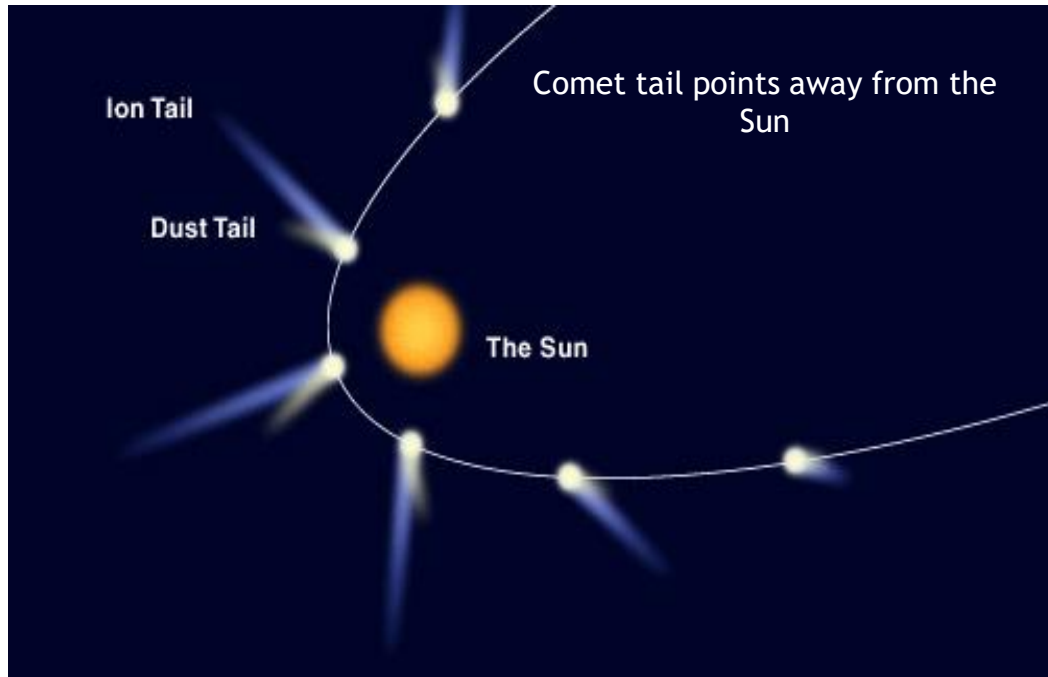
\vec{S} - the Poynting vector, dS - element of area normal to \vec{S}

the radiation pressure is: $P_R = \langle S \rangle / c$ measured in [N/m²]

Radiation Pressure = The momentum transferred per second per unit area =
= Energy deposited per second per unit area / c

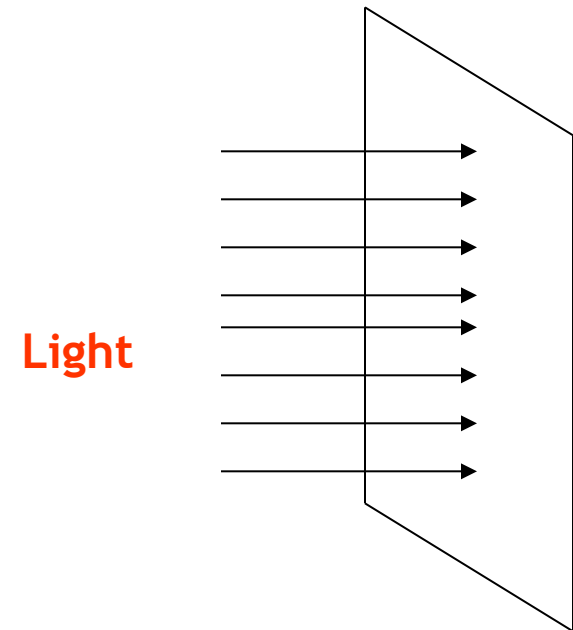
- Forces generated by radiation pressure of light are in general very small and hence difficult to be detected --> use of laser light (LASER) which is able to generate high optical intensities and high optical intensity gradients.

Radiation Pressure of Light



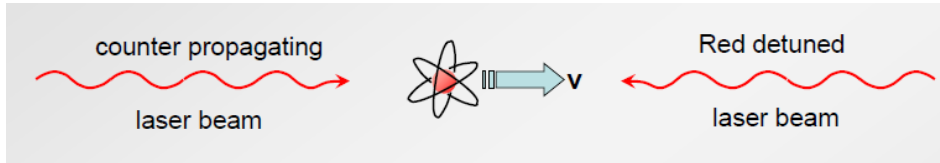
The comet tail is always pointing away from the Sun due to radiation pressure

Kepler 1619

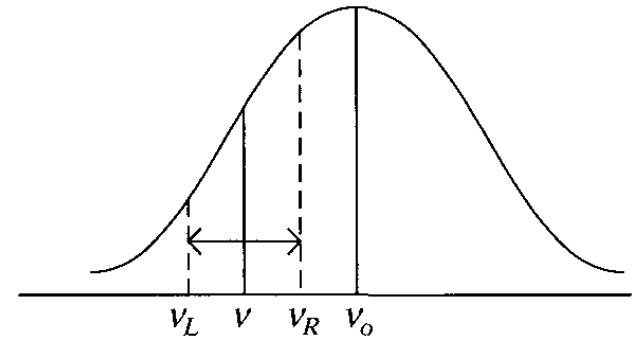


Radiation pressure of Sunlight on the Earth is in average 4.6 [μPa]

Doppler cooling/damping atomic motion -- > optical molasses



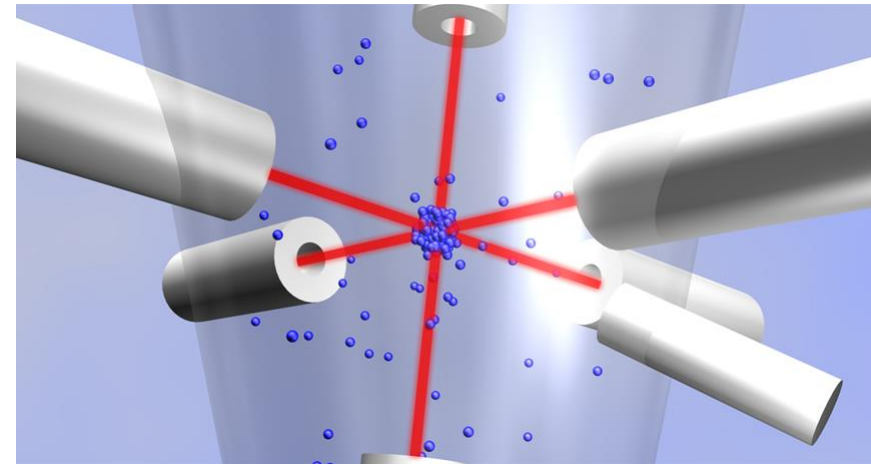
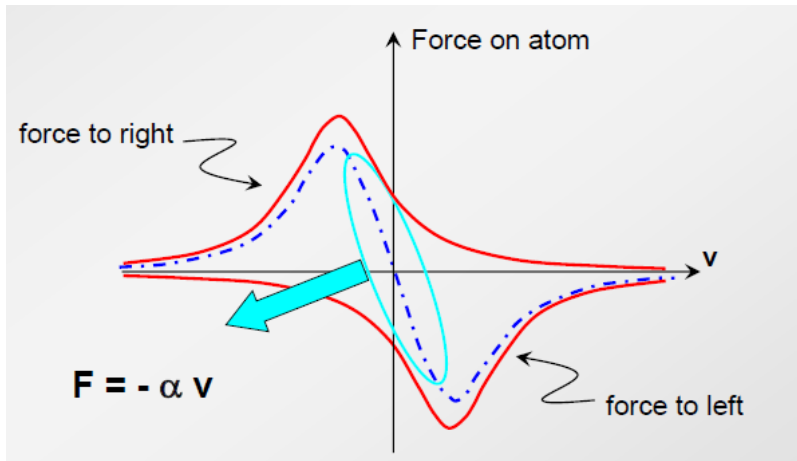
- laser beams tuned slightly below resonance
- atoms will absorb more photons if they move towards the light source, due to the Doppler effect



$$\nu < \nu_0$$

$$F = -\gamma v$$

in three dimensions \longrightarrow optical molasses



How big is the force exerted by a ray of light on a microbead ?

Geometrical optics approximation --> light rays

- (bead diam) $d > \lambda$ (light wavelength)
- reflection coefficient $R = 1$
- $d = 2 \text{ } [\mu\text{m}]$, $\lambda = 0.5 \text{ } [\mu\text{m}]$

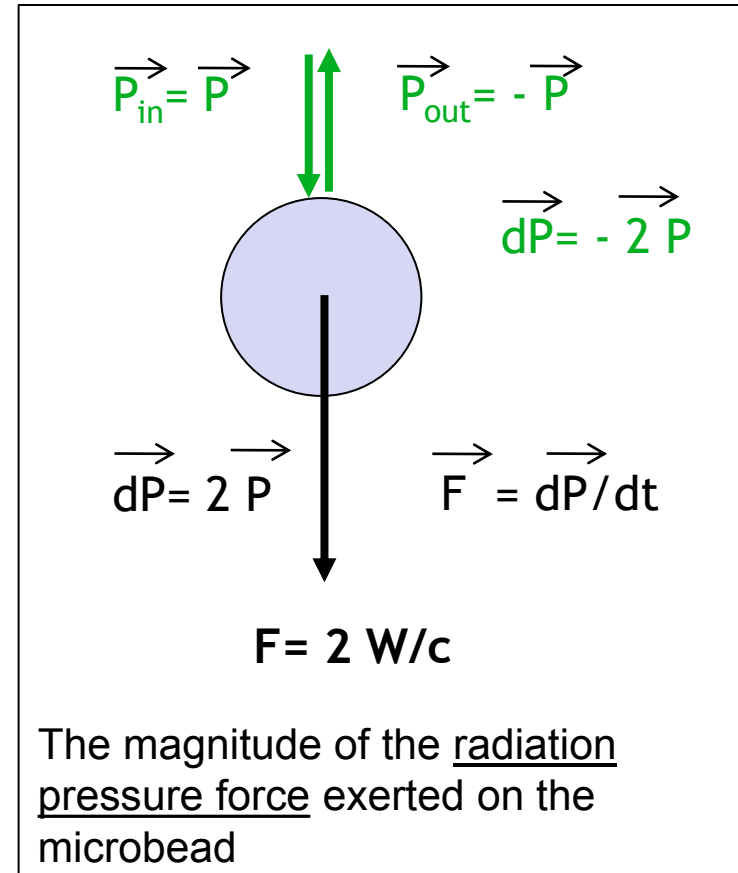
The magnitude of the momentum associated to the ray of light:

$$P = E / c ; E = N h \nu$$

P - momentum; E - energy;

c - light velocity in vacuum ; h - Plank constant;

ν - light frequency; W - power of the light ray $W = dE/dt$



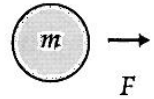
$N = 1$ photon, $\rightarrow E \approx 2.5 \text{ eV}$, $W \approx 4 \times 10^{-19} \text{ W}$ $\rightarrow F \approx 2.7 \times 10^{-27} \text{ N}$ - very small

$N = 10^{15}$ photons, $W \approx 0.4 \text{ mW}$, $F \approx 2.7 \times 10^{-12} \text{ N} = \mathbf{2.7 \text{ pN}}$ - **SMALL**

Is the magnitude of this force significant ?

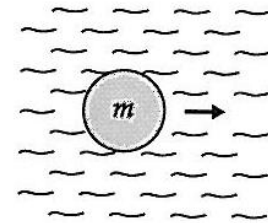
Microbead in free space (vacuum)):

$F \approx 2.7 \times 10^{-12} \text{ N} = 2.7 \text{ pN}$ - SMALL , but also the mass of the microbead is small,
 $m \approx 8 \text{ pg}$ --> acceleration $\mathbf{a} \approx F/m = 3.4 \times 10^2 \text{ [m/s}^2\text{]} = \mathbf{34 \text{ g}}$, which is very **BIG !**



Microbead in water:

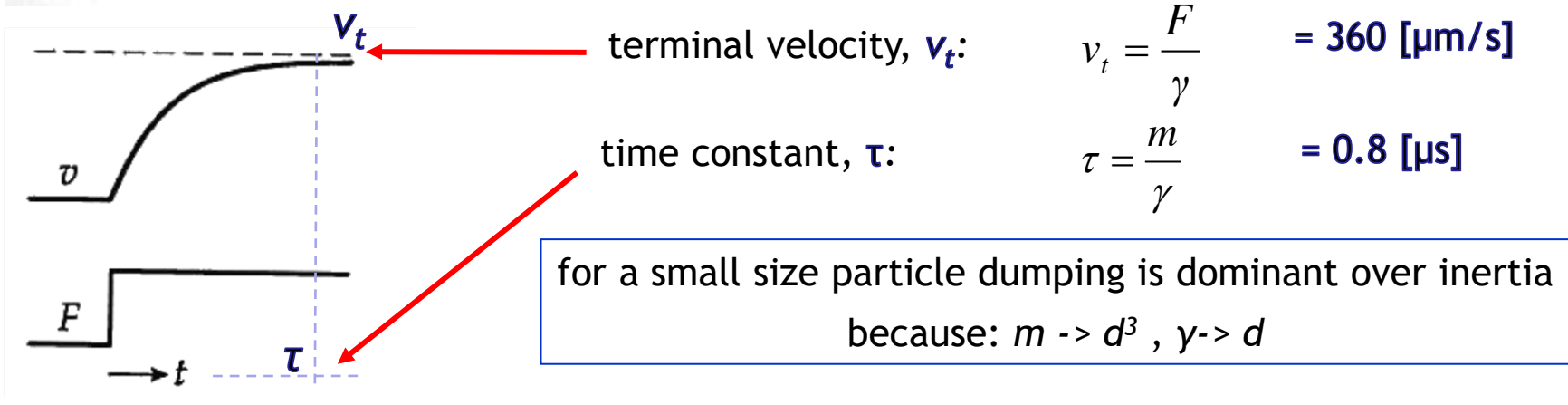
refractive index : $n_m = 1.33$; drag coefficient : $\gamma = 10 \text{ nN s/m}$;
 force by light : $F = 2 n_m W/c$; $\mathbf{F \approx 3.6 \text{ pN}}$



mass + dashpot model

$$m \frac{dv}{dt} = F - \gamma v$$

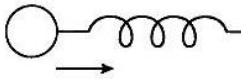
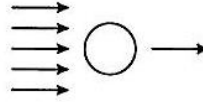
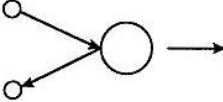
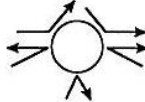
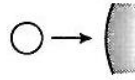
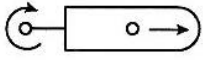
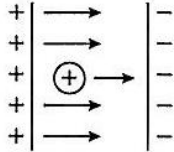
$$v(t) = \frac{F}{\gamma} \left[1 - \exp\left(-\frac{t}{\tau}\right) \right]$$



An example from biology: the movement of a bacterium in water. The bacterial motor must be able to generate force $> 0.5 \text{ pN}$ to swim through water and stops immediately when motor stops.

Physical forces and their magnitudes at the single molecule level

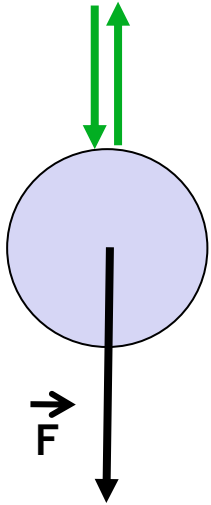
Table 2.1 Examples of forces acting on molecules

Type of force	Diagram	Approximate magnitude
Elastic		1–100 pN
Covalent		10,000 pN
Viscous		1–1000 pN
Collisional		10^{-12} to 10^{-9} pN for 1 collision/s
Thermal		100–1000 pN
Gravity		10^{-9} pN
Centrifugal		$< 10^{-3}$ pN
Electrostatic and van der Waals		1–1000 pN
Magnetic		$\ll 10^{-6}$ pN

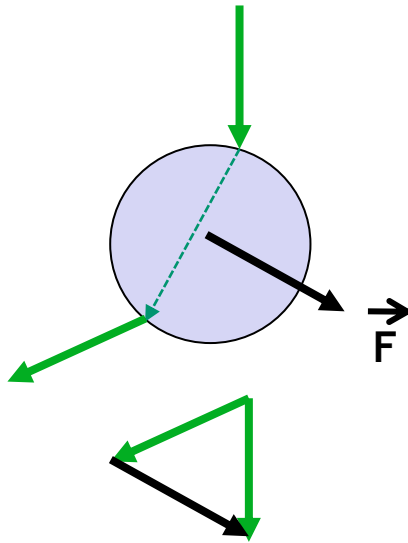
pN

Force induced by a ray of light by refraction on a bead in water

reflection only
 $R=1$



refraction only,
 $R=0; n_b > n_m$



The magnitude of the force:

$$F = Q n_m W_{in} / c$$

the incident momentum /s
of a ray of power W_{in}

Q - dimensionless factor, $Q \leq 2$

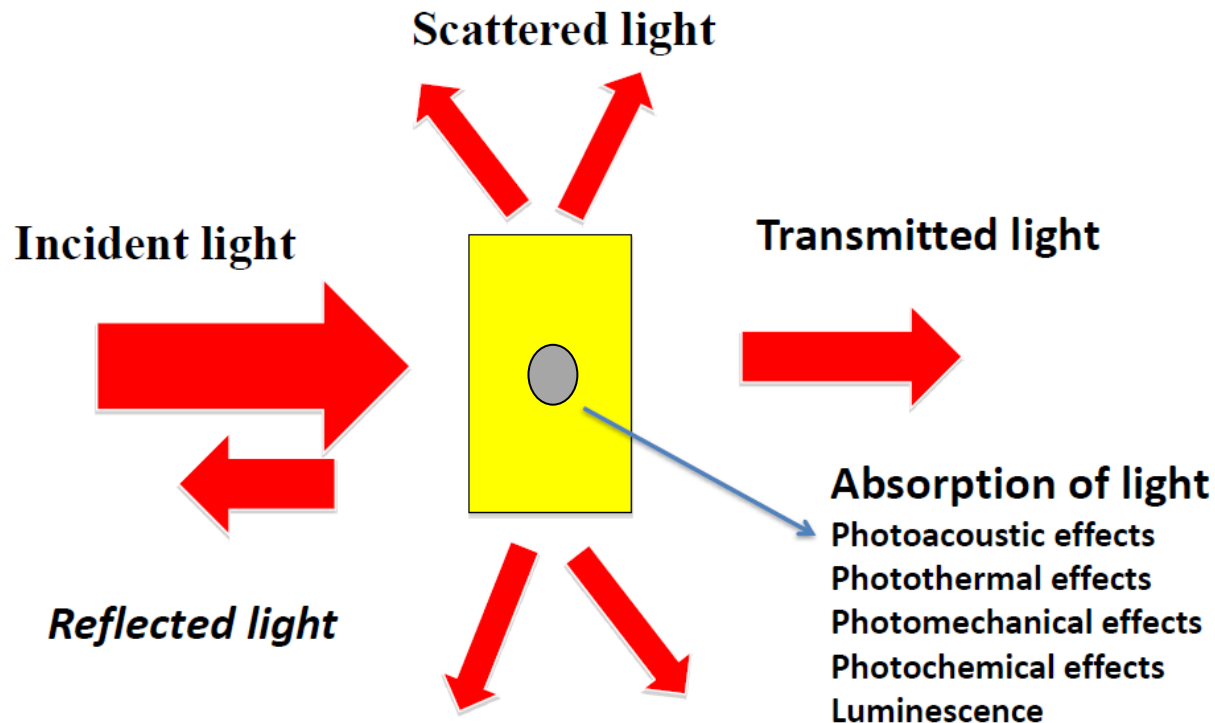
Q - function of shape, material

The total force on a particle interacting with an incident light beam (reflection, scattering, refraction, absorption, emission) is given by the difference between the momentum flux entering the object and the one leaving it:

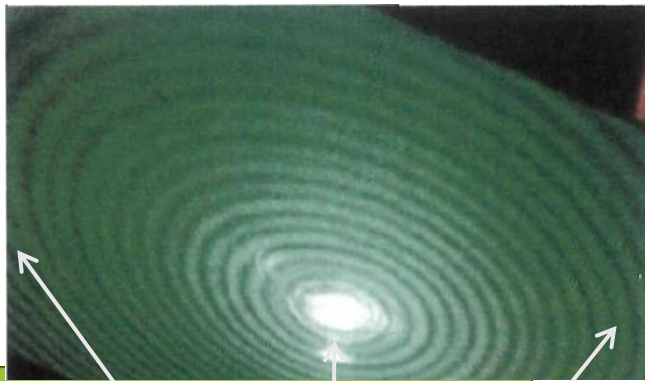
$$\vec{F} = \frac{n_m}{c} \int_S (\vec{S}_{in} - \vec{S}_{out}) dS$$

In principle it is possible to directly calculate / measure the force on a particle using the light momentum flux through it.

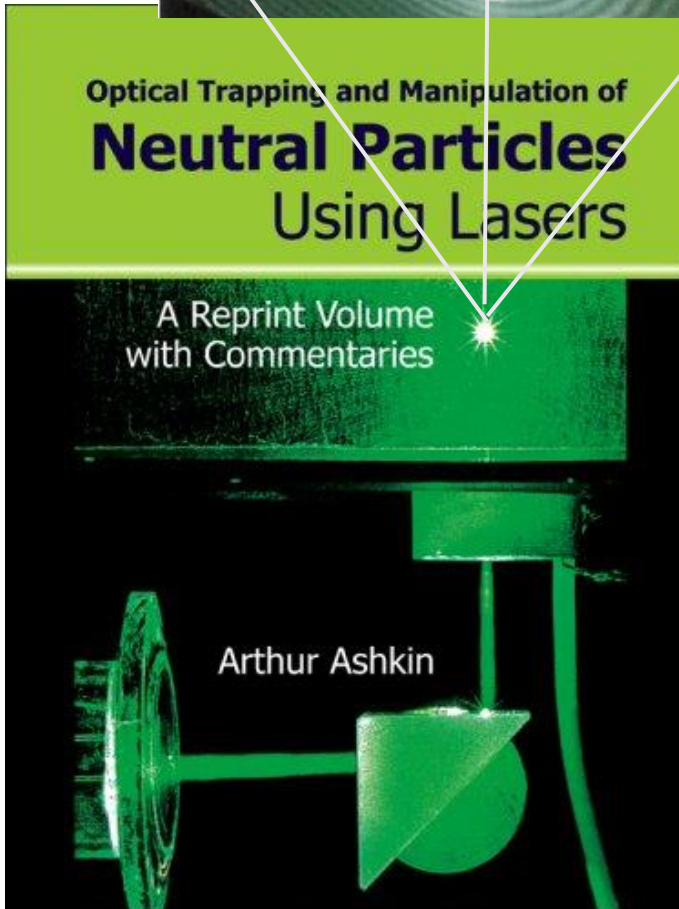
Sample interacting with light --> effects
Energy conservation, momentum conservation



adapted from slide of the lecture on PhotoThermal Lens by Prof. Aristides Marcano

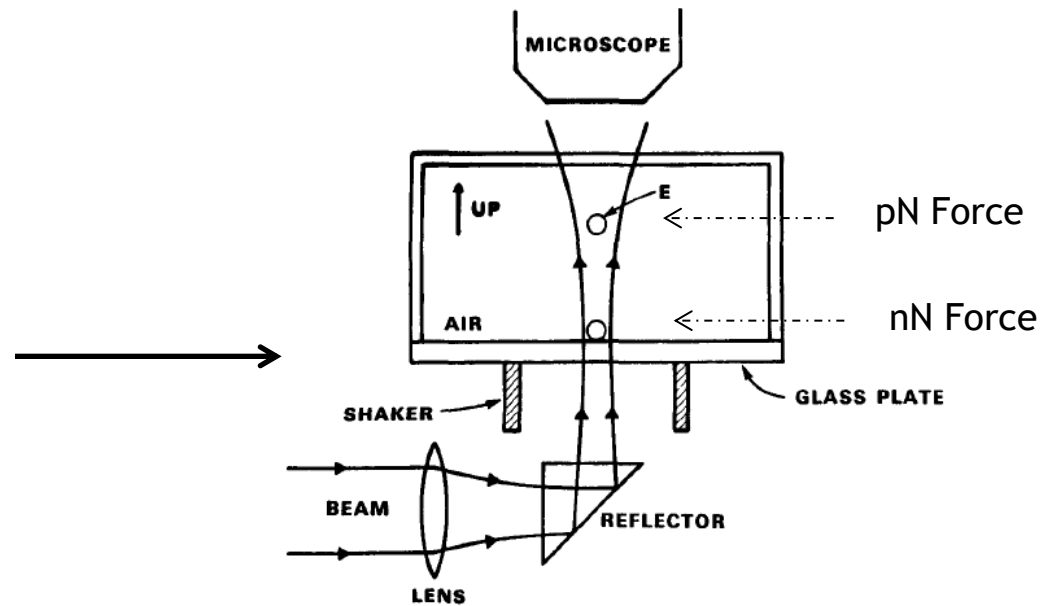


Mie scattering pattern



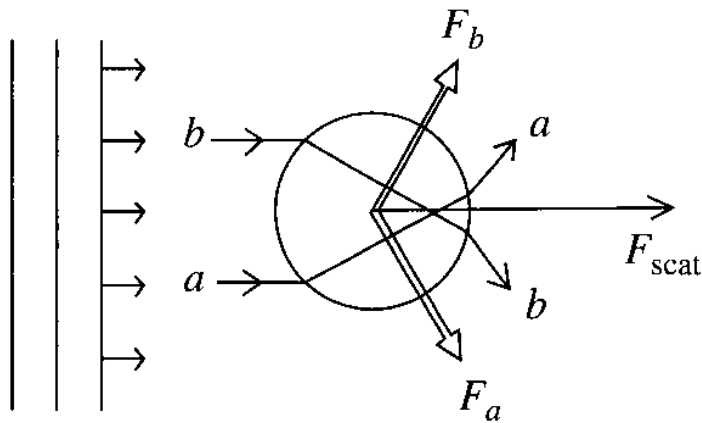
Warmly recommended book

Arthur Ashkin - Scientific Publishing 2006



Optical levitation of microparticles in air (hollow, diam 50-75 μm)

Simplified ray optics diagrams of the scattering force and gradient force components of the radiation force on a dielectric Mie particle ($d > \lambda$)



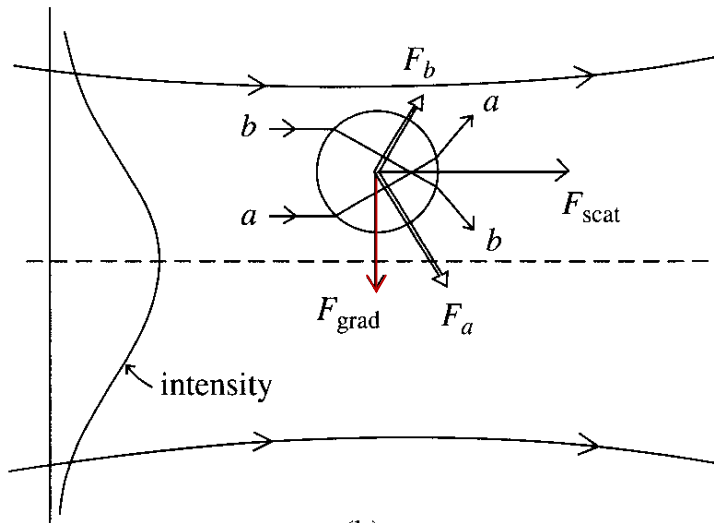
Plane wave

high index particle $n_p > n_m$

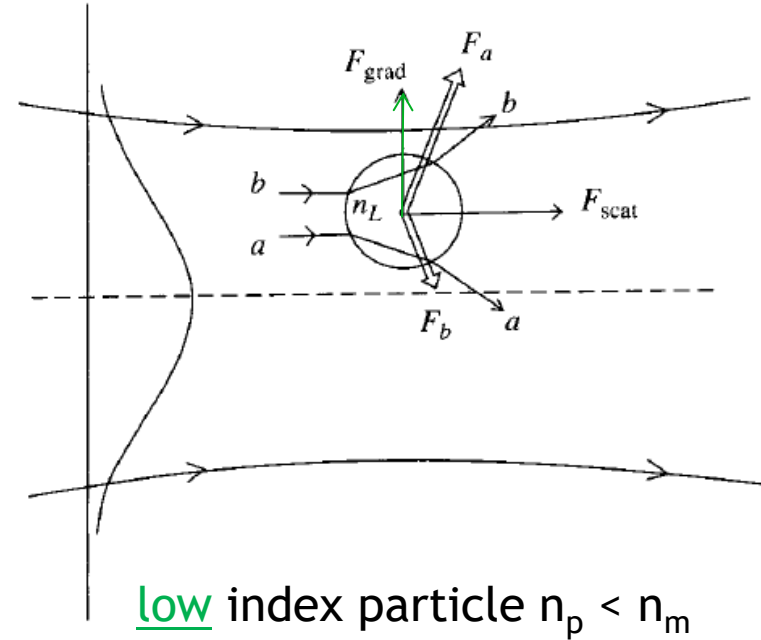
Origin of the scattering force - \mathbf{F}_{scat}

in the direction of the intensity of the incident plane wave beam

Scattering and gradient forces



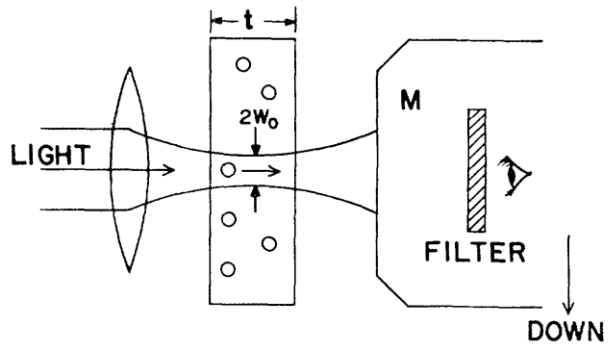
high index particle $n_p > n_m$



low index particle $n_p < n_m$

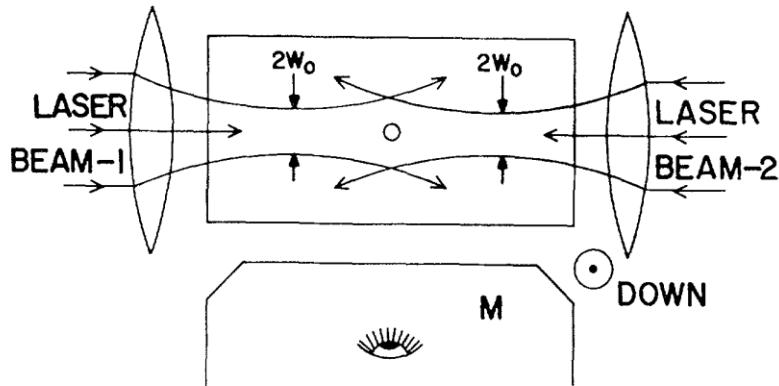
mildly focused Gaussian wave beam

Origin of the transverse gradient force component - \mathbf{F}_{grad}
for a particle located off-axis



2D trapping

Single laser beam focused through a lens with low NA



3D trapping

Counter propagating laser beams

Experimental results: dielectric microparticles in water and water droplets in air

It is hypothesized that similar acceleration and trapping are possible with atoms and molecules using light tuned to specific transitions.

Forces on submicrometric Rayleigh particles:

Gradient Force $F_{grad} = (\mathbf{P} \cdot \nabla) \cdot \mathbf{E} = \frac{1}{2} \alpha \nabla E^2$

$F_{grad} = -\frac{n_b}{2} \alpha \nabla E^2 = -\frac{n_b^3 r^3}{2} \left(\frac{m^2 - 1}{m^2 + 2} \right) \nabla E^2$

P - polarization vector,
 α - polarizability
 E - optical electric field

Scattering Force $F_{scat} = P_{scat}/c$

$F_{scat} = \frac{I_0}{c} \frac{128\pi^5 r^6}{3\lambda^4} \left(\frac{m^2 - 1}{m^2 + 2} \right)^2 n_b$

I_0 – incident beam intensity
 r – particle radius

Conditions for trapping stability

axial stability $R = \frac{F_{grad}}{F_{scat}} = \frac{3\sqrt{3}}{64\pi^5} \frac{n_b^2}{\left(\frac{m^2 - 1}{m^2 + 2} \right)} \frac{\lambda^5}{r^3 \omega_0^2} \geq 1$

transverse stability $\exp(-U/kT) \ll 1 \leftrightarrow U > 10kT,$

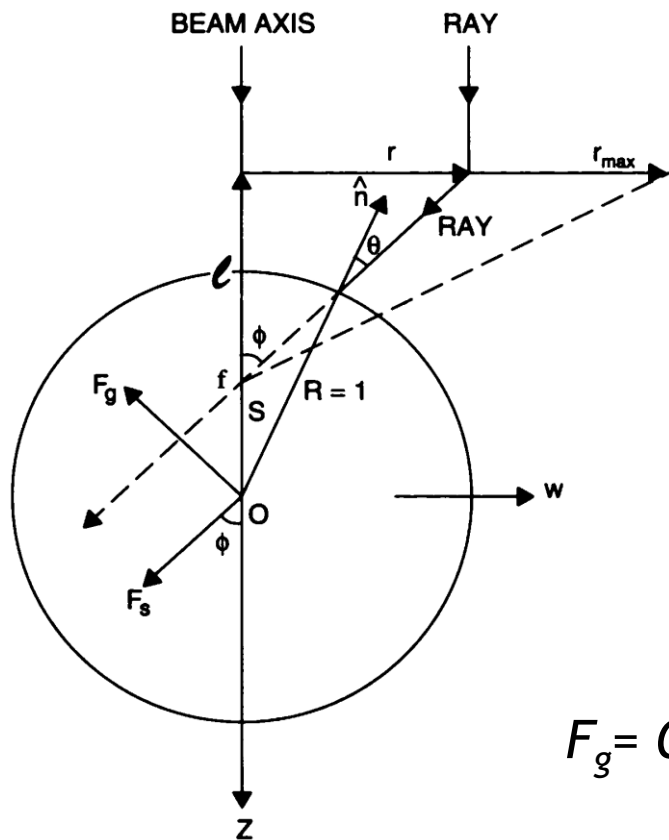
Size that can be trapped (polystyrene latex):
 14 nm (theory)
 25 nm (experimental)

where $U = n_b \alpha E^2 / 2$ is the potential of the gradient force

the time to pull a particle into the trap should be less than

the time for the particle to diffuse out of the trap by Brownian motion

Geometry of an incident ray giving rise to gradient and scattering force contributions F_g and F_s



$$F_s = \frac{n_1 P}{c} \times \left\{ 1 + R \cos 2\theta - \frac{T^2 [\cos(2\theta - 2r) + R \cos 2\theta]}{1 + R^2 + 2R \cos 2r} \right\}$$

Q_s

$$F_g = \frac{n_1 P}{c} \times \left\{ R \sin 2\theta - \frac{T^2 [\sin(2\theta - 2r) + R \sin 2\theta]}{1 + R^2 + 2R \cos 2r} \right\}$$

Q_g

$$F_g = Q_g n_1 P / c$$

$$F_s = Q_s n_1 P / c$$

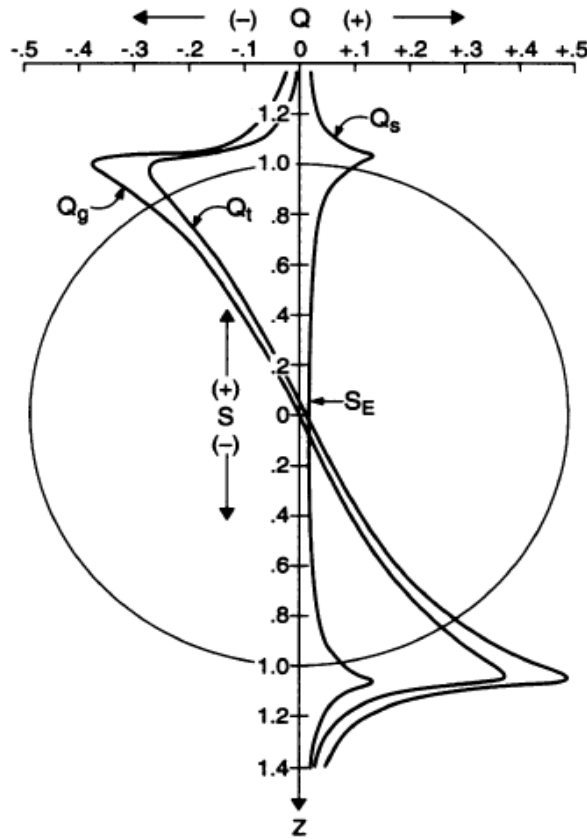
$$F = F_s + F_g = Q n_1 P / c$$

$$Q = \sqrt{(Q_g^2 + Q_s^2)}$$

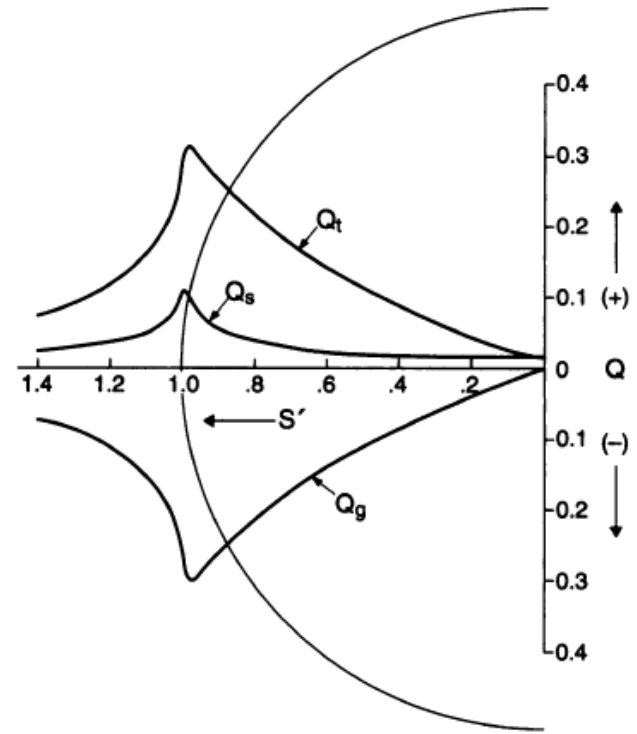
A. Ashkin, *Biophys. J.* 611, 569 (1992)

Forces of a single-beam gradient laser trap on a dielectric sphere in the ray optics regime

Which is the magnitude of the forces experienced by a particle close to the trap ? ¹⁸



axial



transverse

A. Ashkin, *Biophys. J.* 611, 569 (1992)

Forces of a single-beam gradient laser trap on a dielectric sphere in the ray optics regime

Ashkin's dream was to trap atoms

A. Ashkin, Trapping of atoms by resonance radiation pressure Phys. Rev. Lett. 40, 729 (1978)

A method of stably trapping, cooling, and manipulating atoms on a continuous-wave basis is proposed using resonance radiation pressure forces. Use of highly focused laser beams and atomic beam injection should give a very deep trap for confining single atoms or gases at temperatures $\sim 10^{-6}$ °K. An analysis of the saturation properties of radiation pressure forces is given.

Steven Chu, J. E. Bjorkholm, A. Ashkin, and A. Cable Experimental Observation of Optically Trapped Atoms Phys. Rev. Lett. 57, 314 , (1986)

We report the first observation of optically trapped atoms. Sodium atoms cooled below 10^{-3} K in “optical molasses” are captured by a dipole-force optical trap created by a single, strongly focused, Gaussian laser beam tuned several hundred gigahertz below the D_1 resonance transition. We estimate that about 500 atoms are confined in a volume of about $10^3 \mu\text{m}^3$ at a density of 10^{11} – 10^{12} cm^{-3} . Trap lifetimes are limited by background pressure to several seconds. The observed trapping behavior is in good quantitative agreement with theoretical expectations.

Optical trapping contributed to:

1997 Nobel Prize in Physics

Steven Chu, Claude Cohen-Tannoudji and William D. Phillips

"for development of methods to cool and trap atoms with laser light"

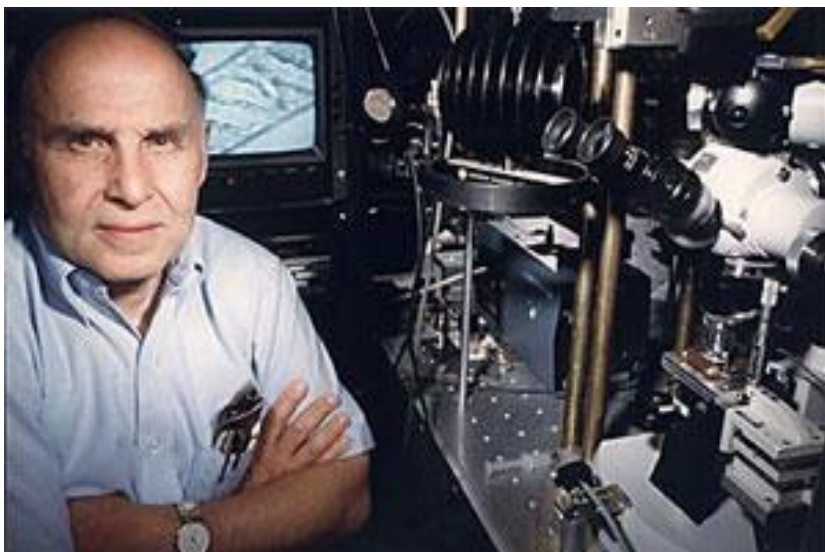
2001 Nobel Prize in Physics

Eric A. Cornell, Wolfgang Ketterle and Carl E. Wieman

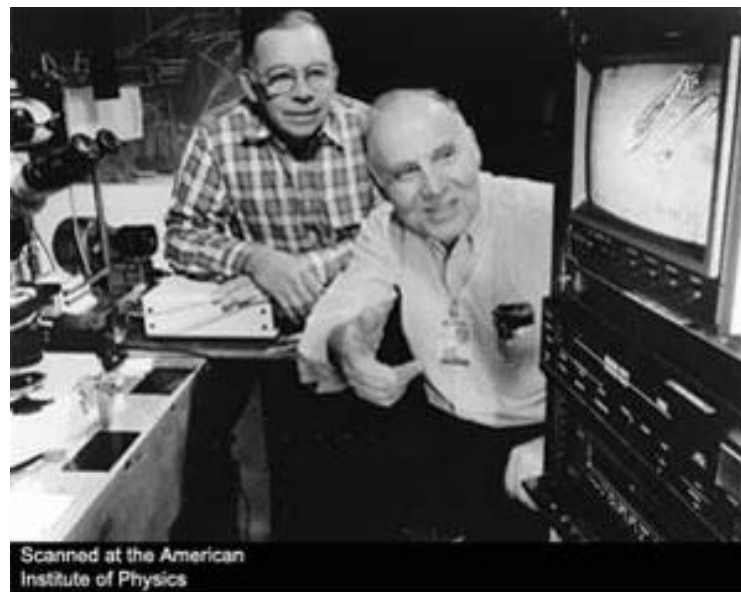
"for the achievement of Bose-Einstein condensation in dilute gases of alkali atoms, and for early fundamental studies of the properties of the condensates"

Ashkin, meanwhile, focused on using optical tweezers to trap and study various living things, including the tobacco mosaic virus, various bacteria, red blood cells, and algae, without damaging them. He went on to probe the internal cell structure, using his tweezers to manipulate the cell's cytoplasm and organelles in what he describes as "a form of internal cell surgery."

Arthur Ashkin at Bell Labs (1986)



Ashkin and Dziedzic



<http://laserfest.org/lasers/pioneers/ashkin.cfm>

Types of particle:

- **Material:** Dielectric (polystyrene, silica); Metallic (gold, silver, copper), Biological (cells, macro-molecules, intracellular structures, DNA filaments), Low index (ultrasound agent contrast); crystal or amorphous material.
- **Size:** 20 nm - 20 μm
- **Shape:** spherical, cylindrical, arbitrary

Types of laser beam:

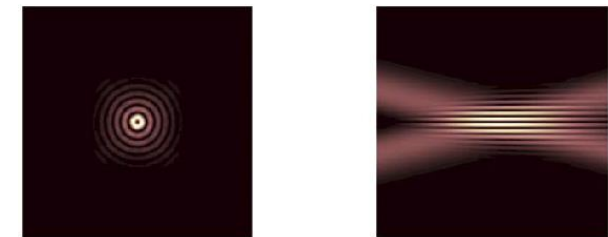
- Gaussian



- Laguerre-Gaussian

LG carries also orbital angular momentum that can be transferred to the trapped particles and make move on the ring and spin around their axis.

- Bessel
(non diffracting beam)



x-y beam intensity z

Particles can be trapped in a bottle since the beam reconstructs itself

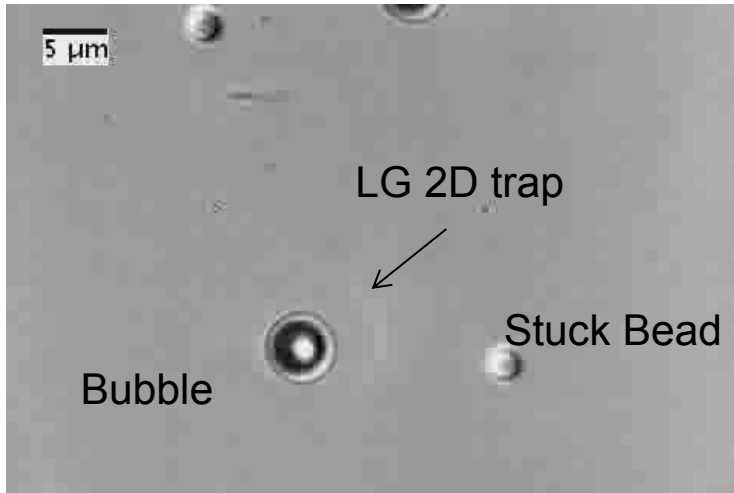
Range of forces that can be applied and measured : 0.1 - 300 pN

Reviews: Svoboda and Block, Annu. Rev. Biophys. 1992; Neuman and Block, Rev. Sci. Instr. 2004;

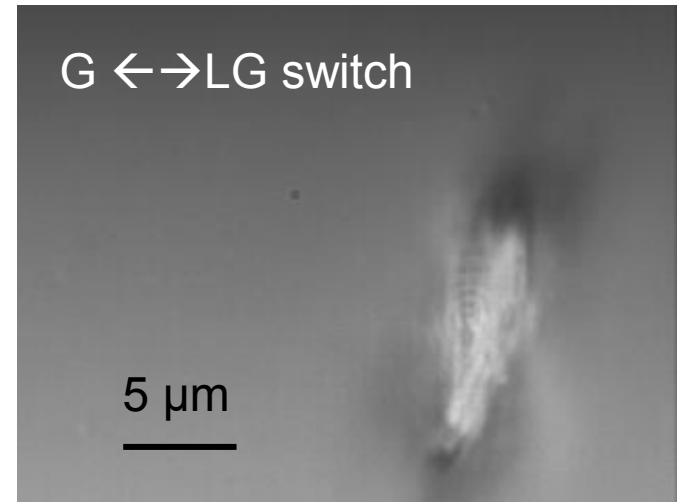
Grier, Nature 2003; Moffit, Chemla, Smith and Bustamante, Annu. Rev. Biochem. 2008; Neuman and Nagy, Nat. Meth. 2008; Bendix, Jauffred, Norregaard and Oddershede,

IEFF I Sel. Topics in Quantum Electronics, 2014

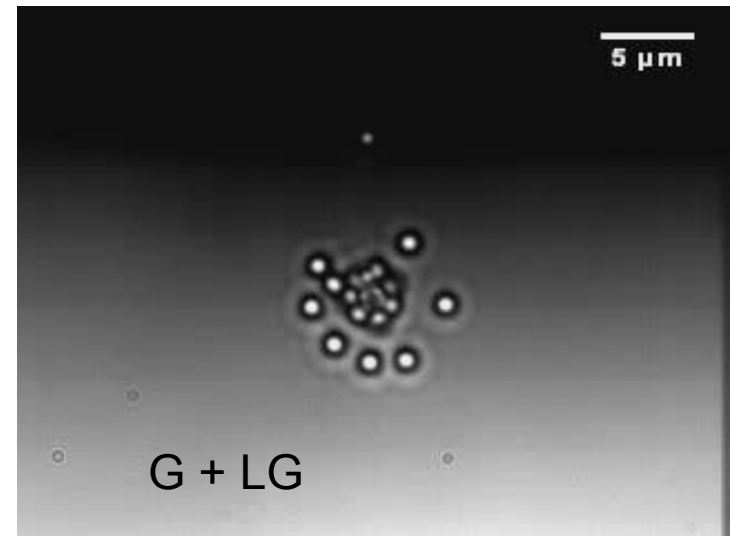
Ultrasound Contrast Bubble – LG 2D trap



Very simple rotor - piece of glass



LG OAM transfer to silica bead



OAM = Optical Angular Momentum

Garbin et al New J Phys 2009

Garbin et al, Appl Phys Lett 2007

Cojoc et al Microel. Eng. 2005

Optical trapping and manipulation of bioparticles / living cells

Are there sensitive issues when using optical tweezers to trap biological particles ?

1. The intensity at the trapping position (focal plane) is very high !
Absorption of light by different components of a biological sample is wavelength dependent !

Is the laser beam damaging the sample ?

If yes, which is the level of damage ?

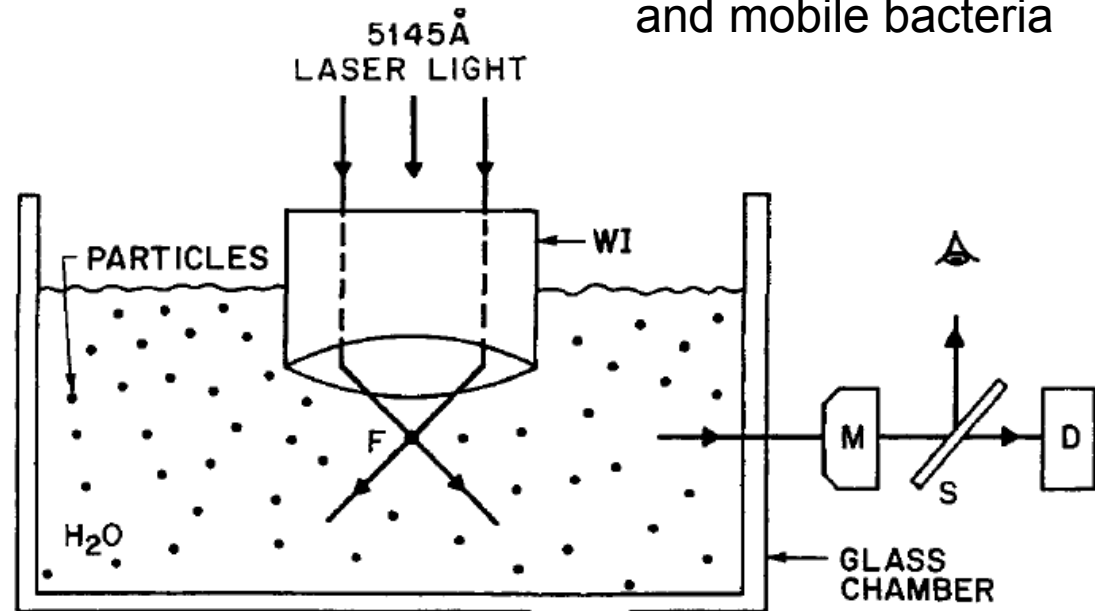
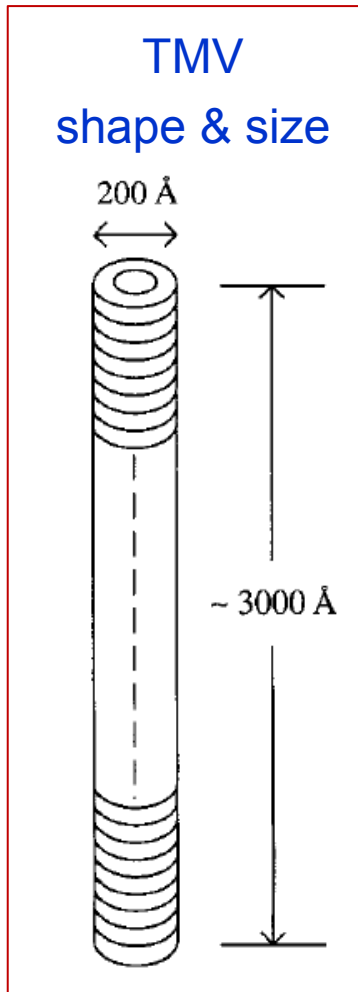
2. Biological samples (e.g. viruses, bacteria, cells) have arbitrary shapes while the laser beam is symmetric.

Does this mismatch prevent trapping ?

First optical trapping of a biological sample

Tobacco Mosaic Virus (TMV)

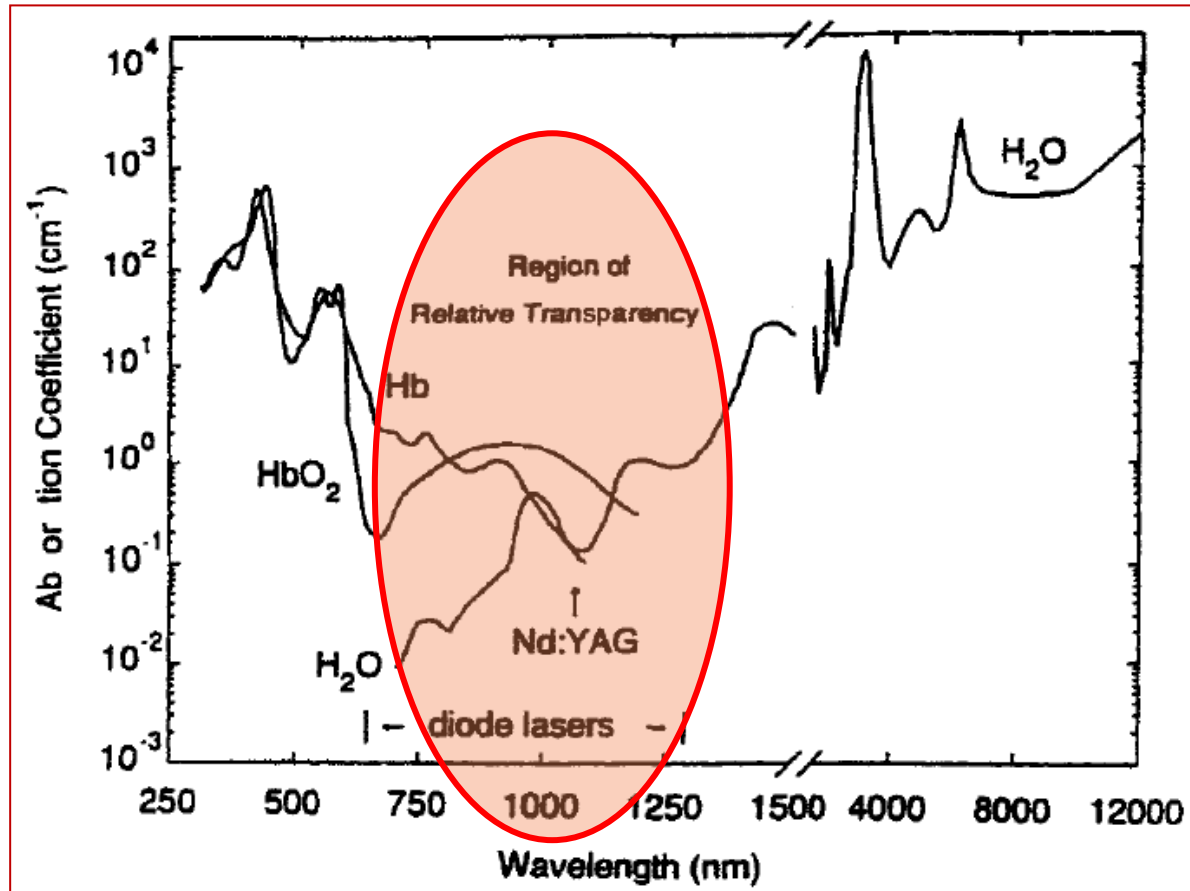
Apparatus used for optical trapping of TMV particles and mobile bacteria



- Laser light scattering → detect the particles and their orientation with respect to the optical field orientation
- Laser power modulation + scattering → study damaging

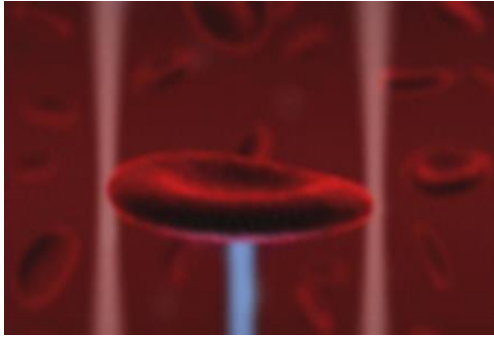
A. Ashkin and J.M. Dziedzic, "Optical trapping and manipulation of viruses and bacteria", *Science* 235, 1517 (1987)

Damaging free OTM of living cells → Infrared Laser

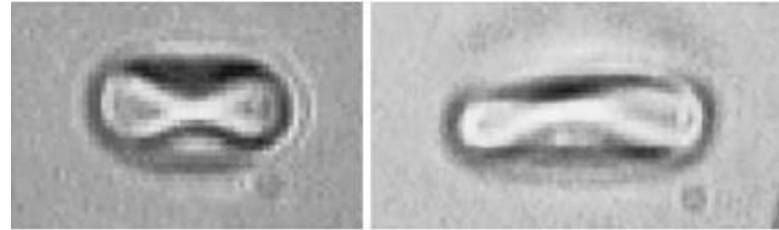


Plot of the optical absorption coefficients of hemoglobin (Hb), oxyhemoglobin (HbO₂) and water versus the wavelength.

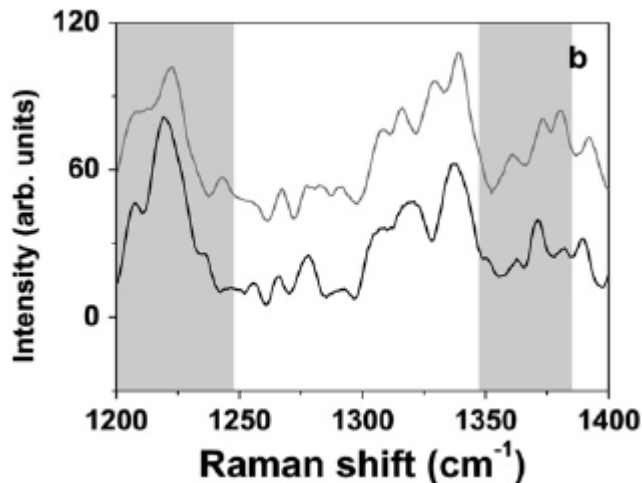
Example: Red Blood Cell (RBC) + OTM stretching + micro Raman



Cover



RBC trapped by two beams in the equilibrium (left) and stretched (right) conditions.



equilibrium (top)

stretched (bottom spectra)

The overall result reveals a bidirectional relationship between chemical binding and mechanical force in the oxygenation cycle of the Hb structure.

RBC with a significant oxygen concentration were pushed to a deoxy state when stretched with optical tweezers

How can we get multiple optical traps / tweezers?

1. **time-sharing a single beam among several different locations**

using galvano mirrors (GM), acousto-optic deflectors (AOD)

- Allow to obtain: 2D arrays of dynamic traps; modulate the strength of the traps individually
- GM are relatively cheap but have a lower frequency (kHz) and hence only few traps can be generated; AOD are more expensive but have a high frequency (MHz) and hence even tens of traps can be generated and controlled.

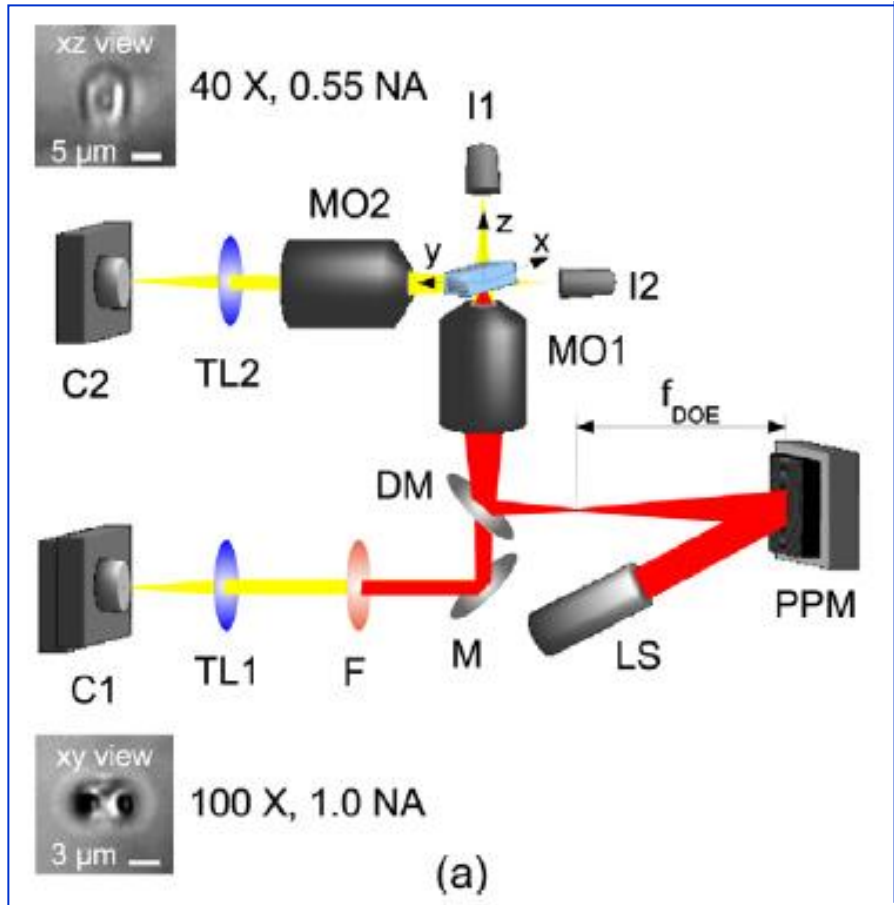
2. **split the beam into multiple beams**

using beam-splitter (BS) or spatial light modulators (SLM)

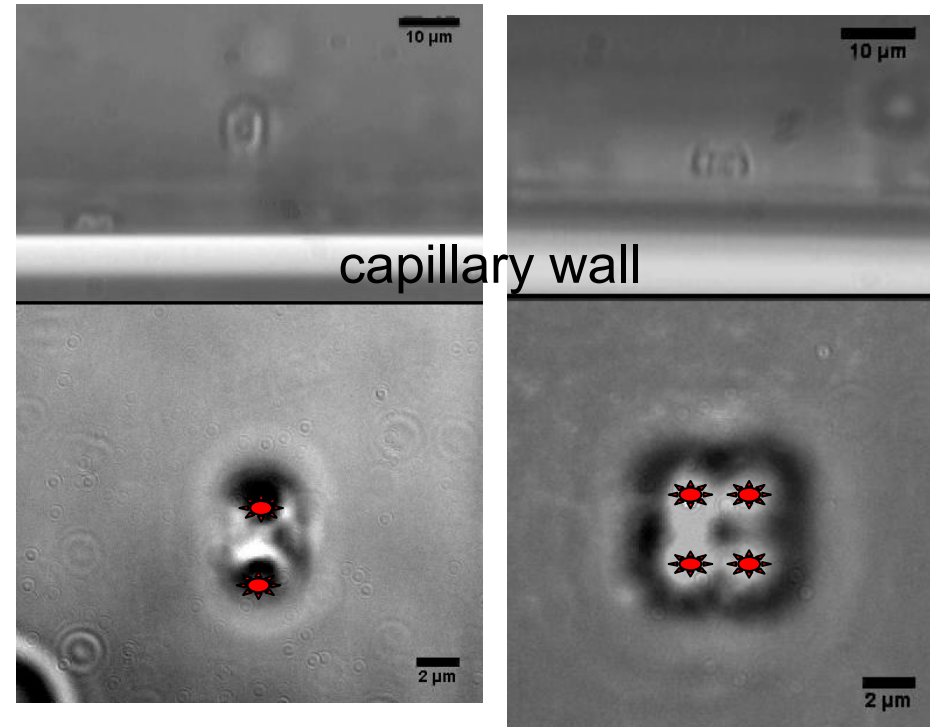
- BS allow to obtain 2 fixed traps with fixed strengths;
- SLM allows to obtain: 2D and 3D arrays of dynamic traps; modulate the strength of each trap individually; convert Gaussian beams to Laguerre-Gauss beams (to get helical-vortex beams) or Bessel beams

Single RBC - multiple traps – multiple view imaging

Optical setup



40X lateral view



100X axial view

OUTLINE

- Optical Tweezers (OT) - single-beam gradient force 3D optical trap: how this works, optical manipulation of microparticles
- **Measuring piconewton forces with OT : direct and indirect methods**
- Applications of OT in living cell studies:
 - probing forces expressed by developing neurons
 - probing the stiffness of cancer cells
 - mechanotransduction - conversion of the mechanical stimulus into a biochemical signal by the cell
 - biochemical local cell stimulation using optically manipulated vectors (coated beads, biodegradable micro-sources, liposomes)

Measuring picoNewton forces with OT : direct and indirect methods

Direct methods:

the force is measured by detecting light momentum changes

$$F = \alpha S$$

- α - conversion factor [N/V]

- S - electrical signal [V] $S_x = \psi \iint \frac{x}{R_D} I(x, y) dx dy$, I - radiant power

Indirect methods:

the force is measured by detecting bead position changes

$$F = k \cdot x$$

- k - trap stiffness [N/m]

- x - displacement of the bead in the trap [m]

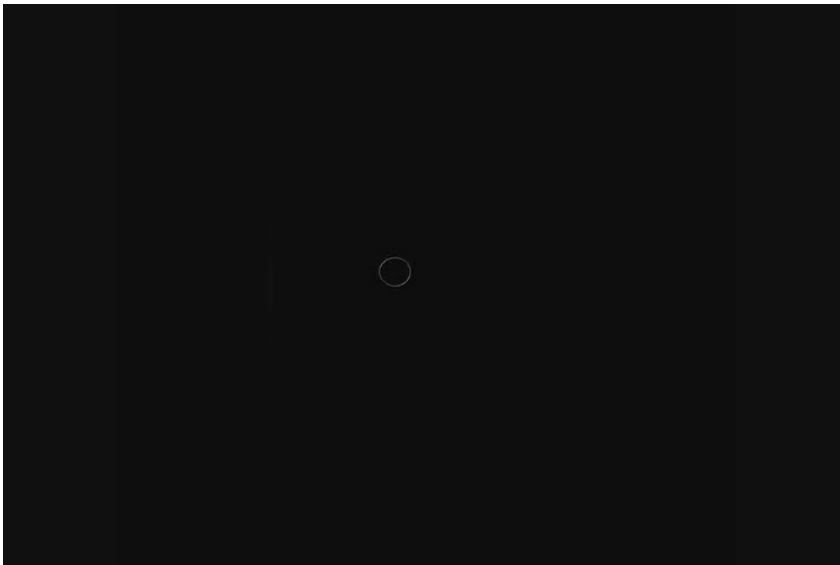
Direct method: the total force on the particle in the trap is given by the difference between the momentum flux entering the object (*in*) and the one leaving it (*out*):

$$\vec{F} = \frac{d\vec{P}_{in}}{dt} - \frac{d\vec{P}_{out}}{dt} = \frac{n_m}{c} \int_S (\vec{S}_{in} - \vec{S}_{out}) dS$$

It requires to detect all the light before and after interaction with the particle.

Measuring all the back and forward scattered light after interaction is unfeasible.

Backward scattered light is a small fraction of the emitted light.



Light scattered by a bead in trap

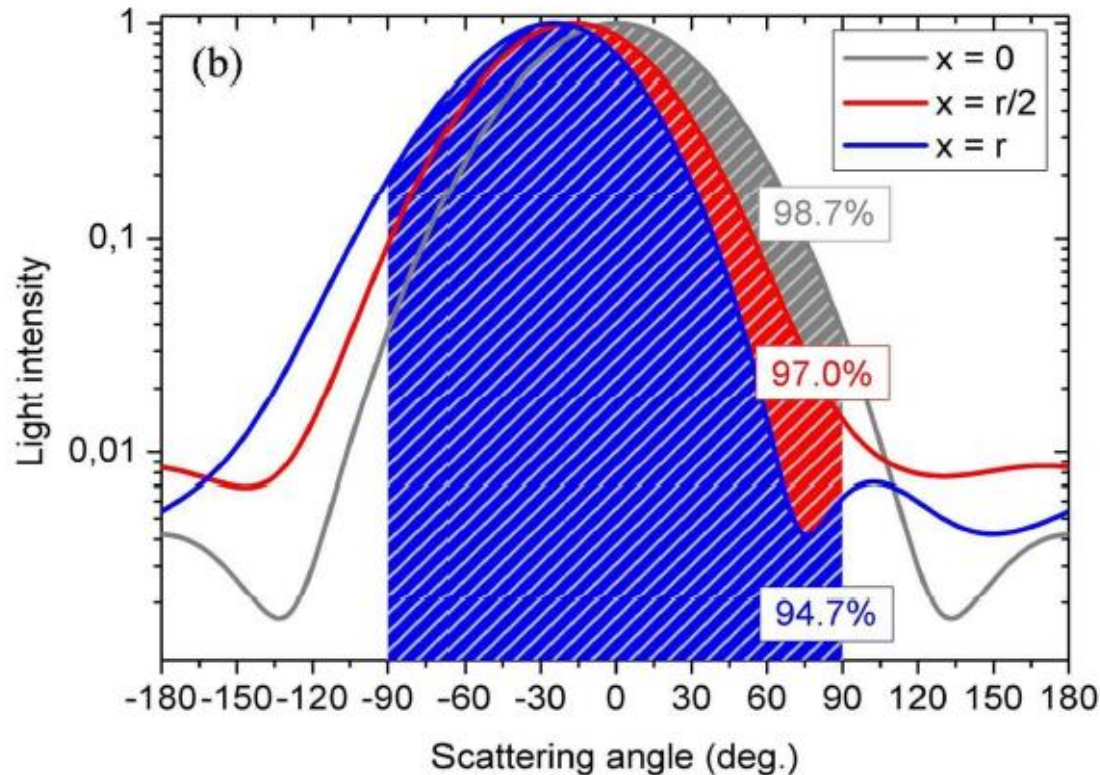
1 μm polystyrene bead in water;

$\lambda = 1064 \text{ nm}$; focusing lens NA= 1.3 ;

Simulation for the E_x component of the electric field.

Most of the light is scattered forward

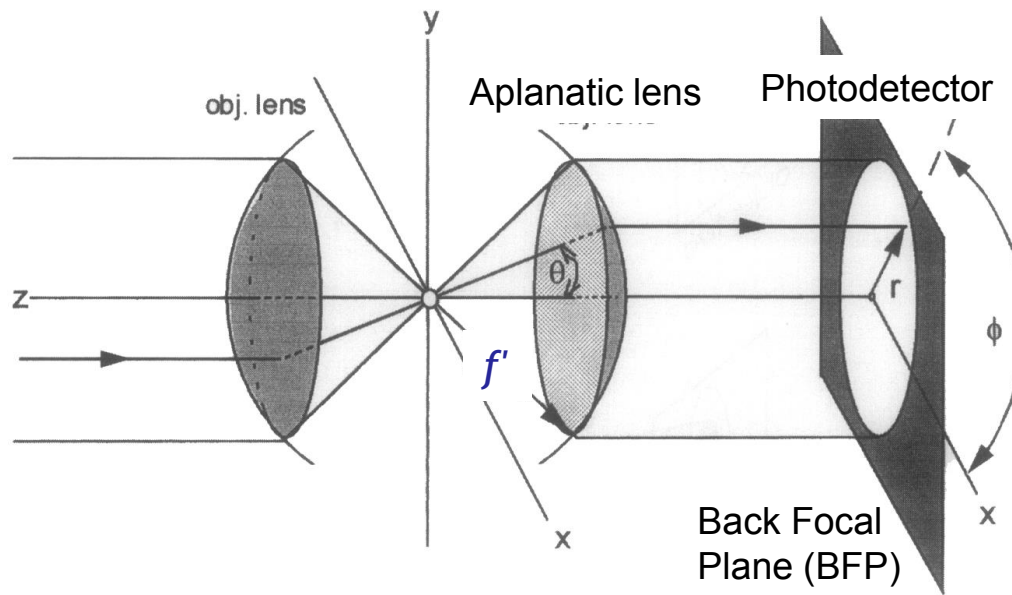
Forward-scattered light is dominant



Angular intensity distribution of the light scattered by the bead.

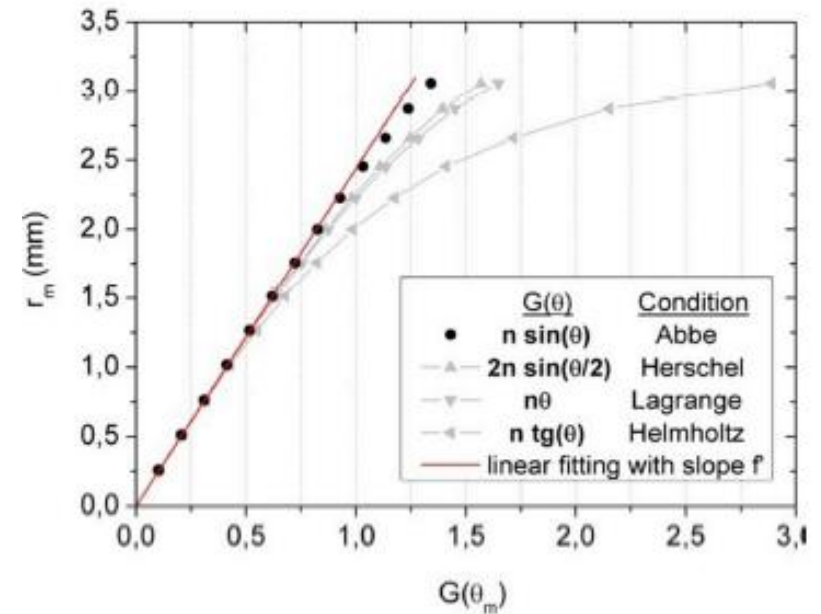
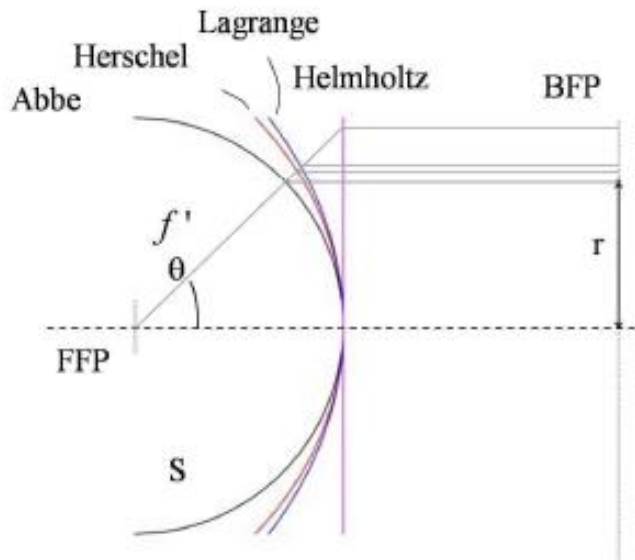
The amount of forward-scattered light contained between $[-90^\circ : 90^\circ]$ is $> 95\%$.

To collect this light one needs a lens with high NA, which fulfills the Abbe sine condition and a photodetector placed in a plane conjugated with the back focal plane of the lens.



Abbe's sine condition:

$$\frac{r}{n_1 \sin \theta_1} = \text{const} = f'$$



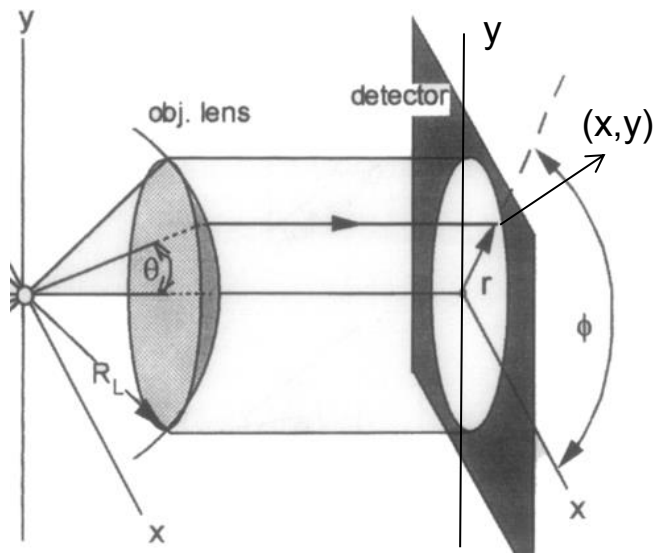
Smith et al, Methods in Enzymology, vol 361, 134 (2003)

Farré and Montes-Usategui, Opt. Express 18, 11955 (2010); Sheppard and Gu, J. Mod. Opt. 40, 1631-1651 (1993)

Condition for the photodetector position: in Back Focal Plane (BFP) of the lens³⁶

Why: the intensity pattern in the BFP does not depend on position of the focus, which means the signal on the photodetector does not change with the position of the trapped bead.

BFP can be seen as the Fourier plane of the lens, and hence the shift invariance of the Fourier transform applies.



The plane wave with momentum p_r

$$p_r = p_0 n_1 \sin \theta_1$$

focuses in BFP at r :

$$r = f' n_1 \sin \theta_1 = f' \frac{p_r}{p_0} = f' \frac{k_r}{k_0}$$

coordinates represent the transverse components of light momenta in a proper scale

where: p_0 - light momentum in vacuum

The intensity pattern $I(x,y)$ projected onto the PSD which produces an electric signal:

$$S_x = \psi \iint_{R_D} \frac{x}{R_D} I(x, y) dx dy$$

$I(x,y)$ is the radiant power at point (x,y) , proportional to the number of photons per time having momentum (p_x, p_y) ; R_D and ψ are the size and the efficiency of the detector.

The x component of the force F_x

$$F_x = \frac{1}{f'c} \iint x I(x, y) dx dy = \frac{R_D}{\psi f'c} S_x = \alpha S_x$$

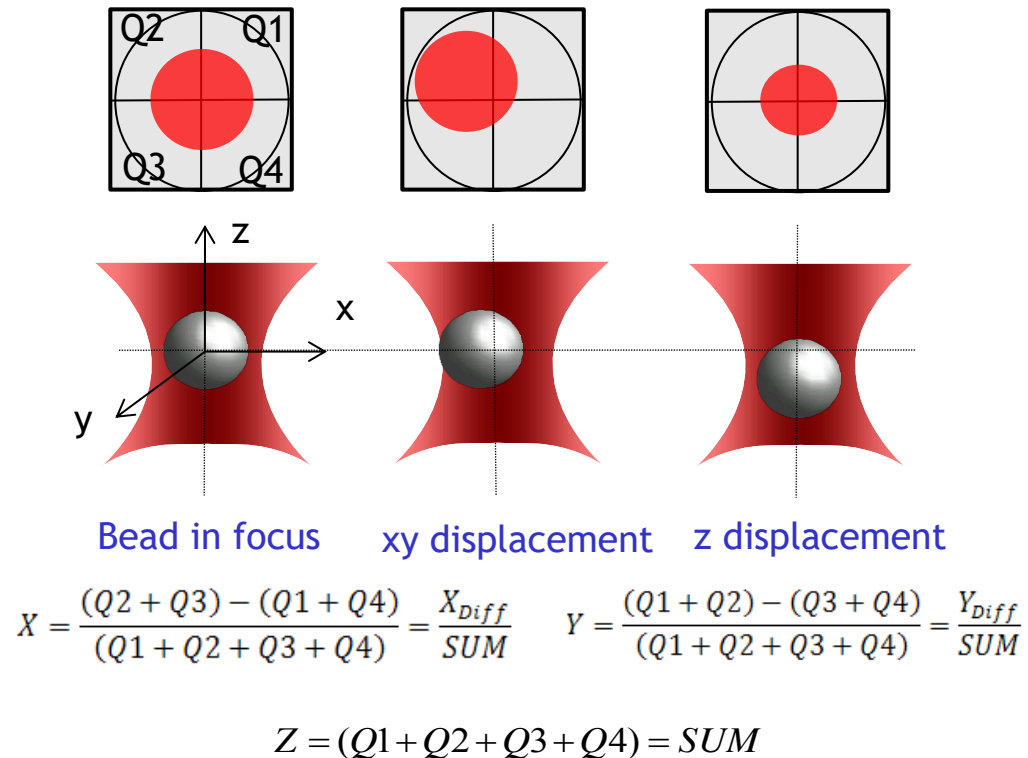
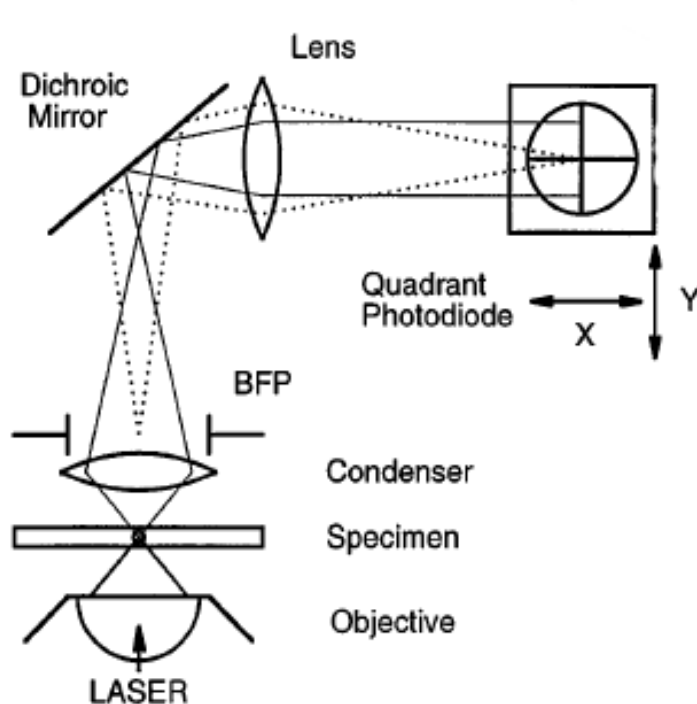
- the direct method is independent of the shape, size and refractive index of the particle
- this method is also insensitive to changes to the trap shape
- this method requires a high NA (1.4) condenser lens --> low WD (2-300 μm) and hence small height for the sample chamber limiting some applications

For positions close to the center of the trap the force is linear with the position:

$$F_x = \alpha S_x = k x$$

Back Focal Plane (BFP) interferometry

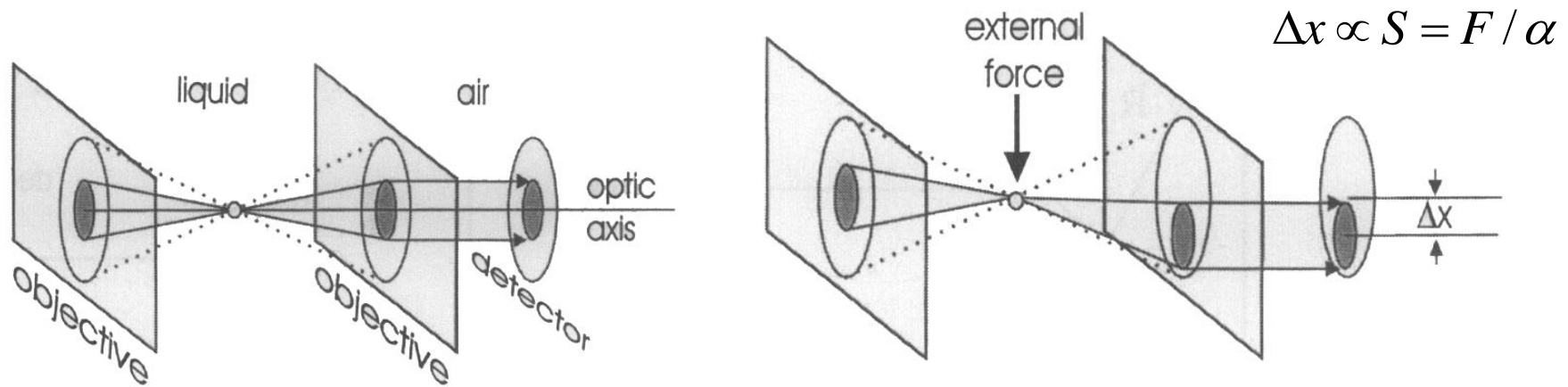
Intensity shifts were identified as first-order far-field interference between the outgoing laser beam and scattered light from the trapped particle. This interference also reflects momentum transfer to the particle, giving the spring constant of the trap.



The intensity shift is determined with a Quadrant Photo Diode (QPD) or a Position Sensing Detector (PSD). For small displacements of the bead:

$$F_x = k x = \alpha S_x$$

Light momentum force transducer with low NA lenses

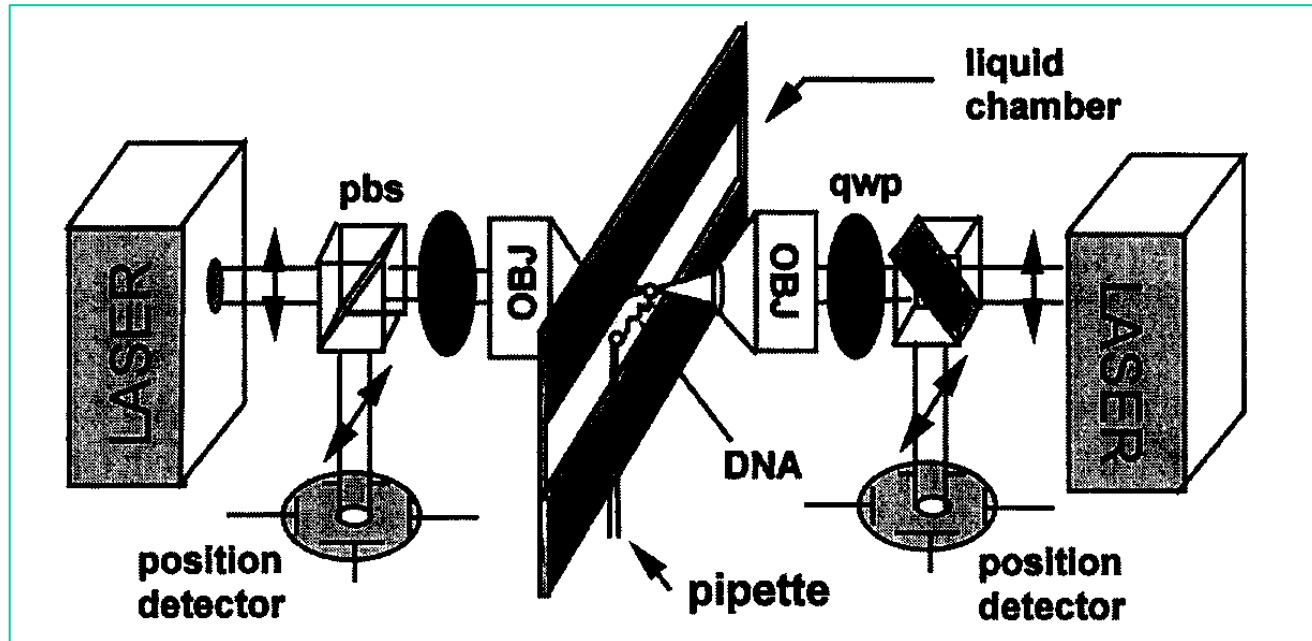


The second objective should collect all the forward scattered light

If the diameter of the incident laser beam is small and the first lens has a relatively low NA then also the collecting lens can have a relatively low NA.

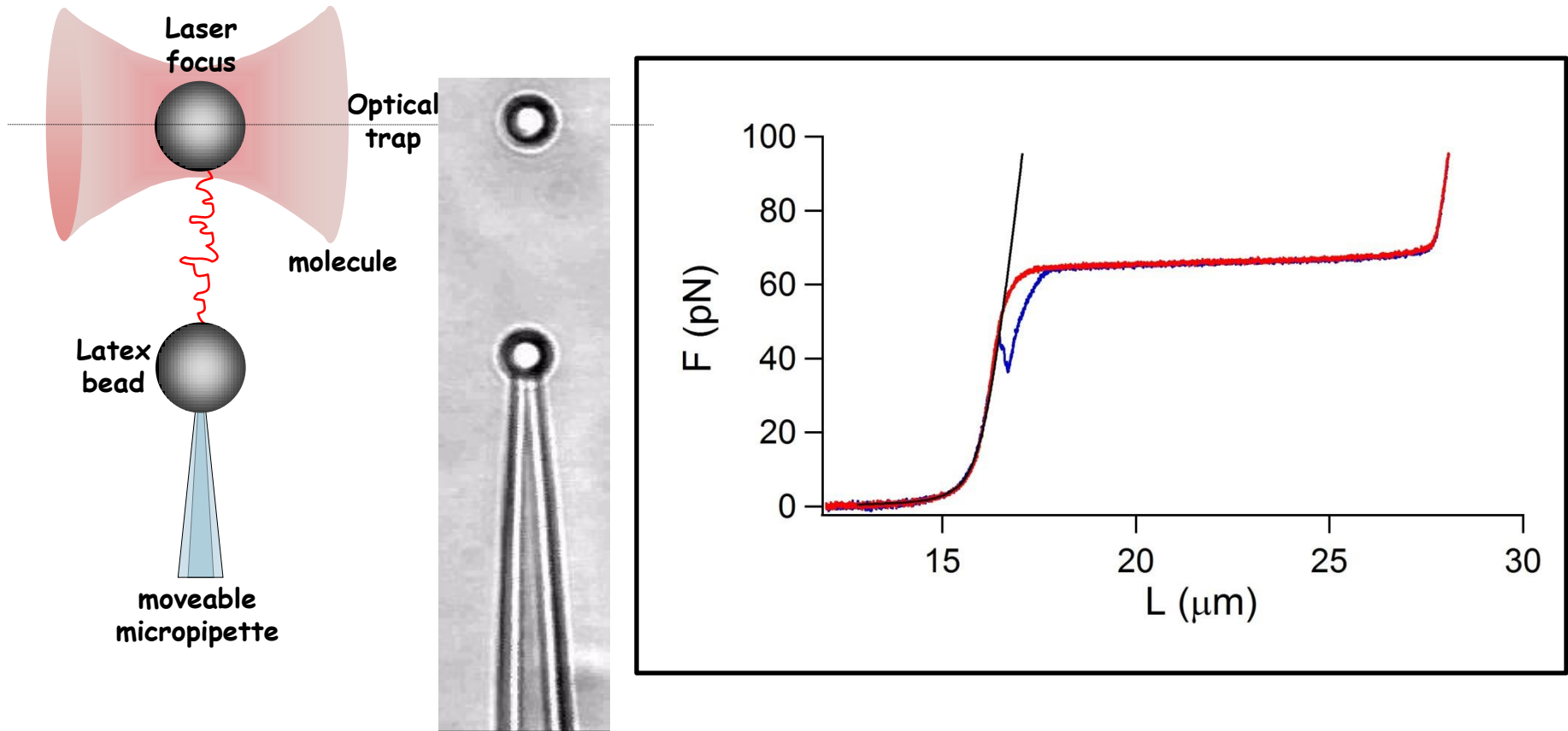
Note: Dashed lines define the lens NA

Dual Beam Laser Tweezers (DBLT) + light momentum force transducer



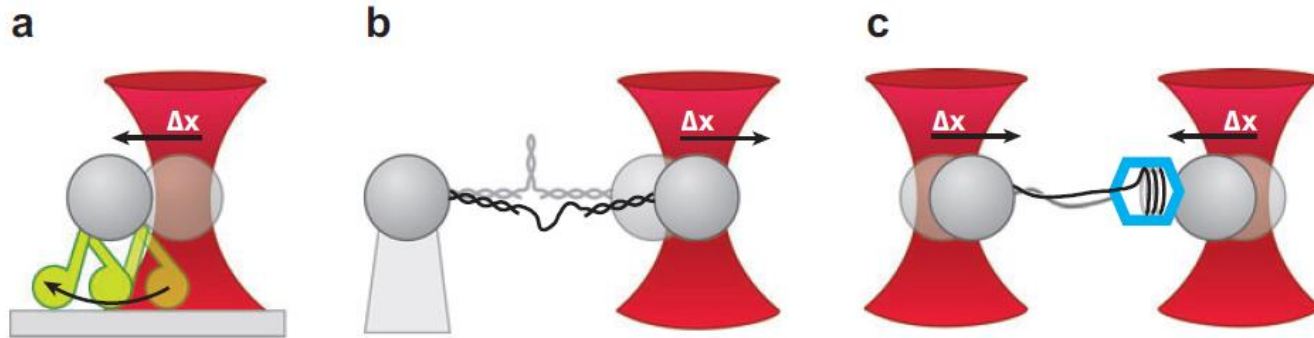
Why a DBLT (counter propagating beams) tweezers has been chosen and not a single beam optical tweezers?

Example:
Force and length range tested by recording
the overstretching transition in λ -phage DNA



The molecule undergoes a highly cooperative structural change at ~ 65 pN that implies 70% elongation and is likely involved in the modulation of the access to genetic information

Different experimental geometries for single molecule optical tweezers force experiments



(a) Processive cytoskeletal motors, such as kinesin, the motor is typically attached directly to a polystyrene bead held in an optical trap, and the filament is attached to the surface of a sample chamber. Motions of the motor are revealed by motions of the trapped bead.

(b) It is also possible to attach one end of the biological system to a second polystyrene bead suctioned onto the end of a micropipette. The motion of the biological system, such as the unfolding of a RNA hairpin, is again revealed in the motion of the trapped bead.

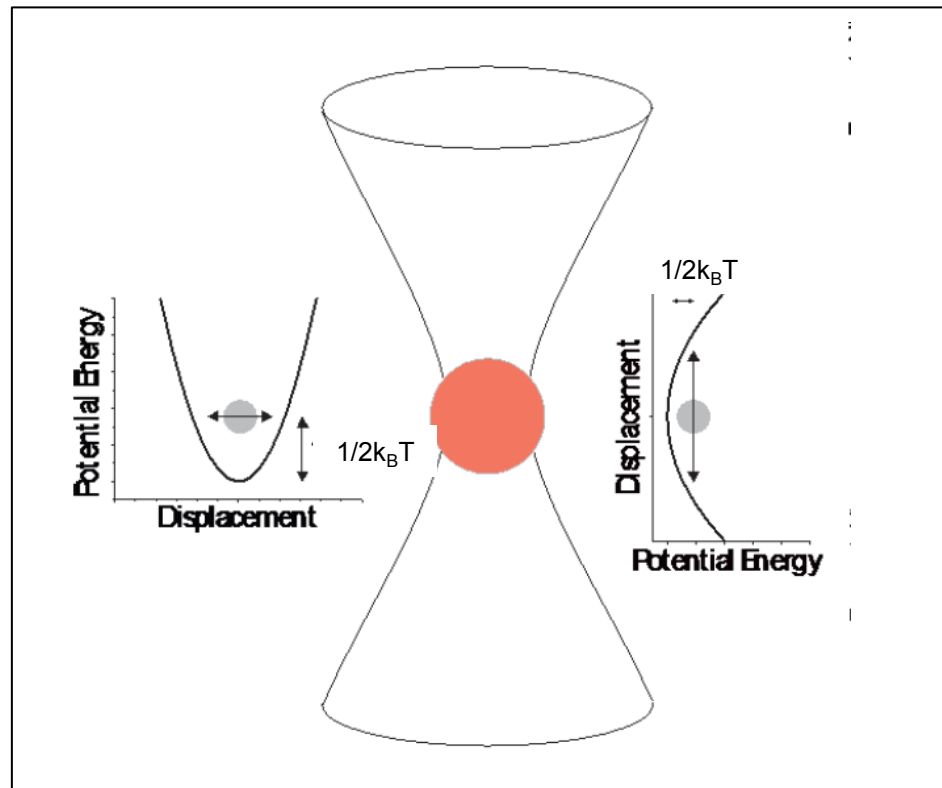
(c) The second bead can also be held in a second optical trap. In this case, changes in the length of the tethered DNA by the action of a bacteriophage portal motor are revealed in the motions of both beads. The relative motion of each bead depends on the relative stiffness of the two optical traps.

Indirect method :

the force is measured by detecting bead position changes

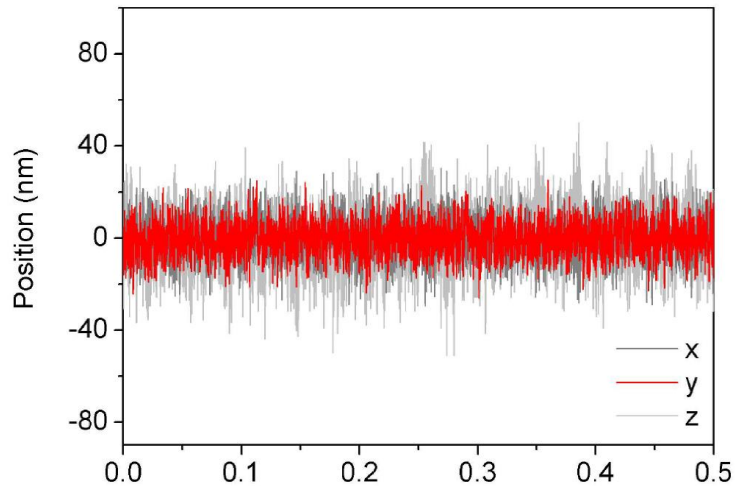
- k - trap stiffness [N/m]
- x - displacement of the bead in the trap [m]

$$F = k \cdot x$$



The trap stiffness k should be determined first

Tracking the displacement of the bead in the optical trap with high sampling frequency (> 5 kHz)

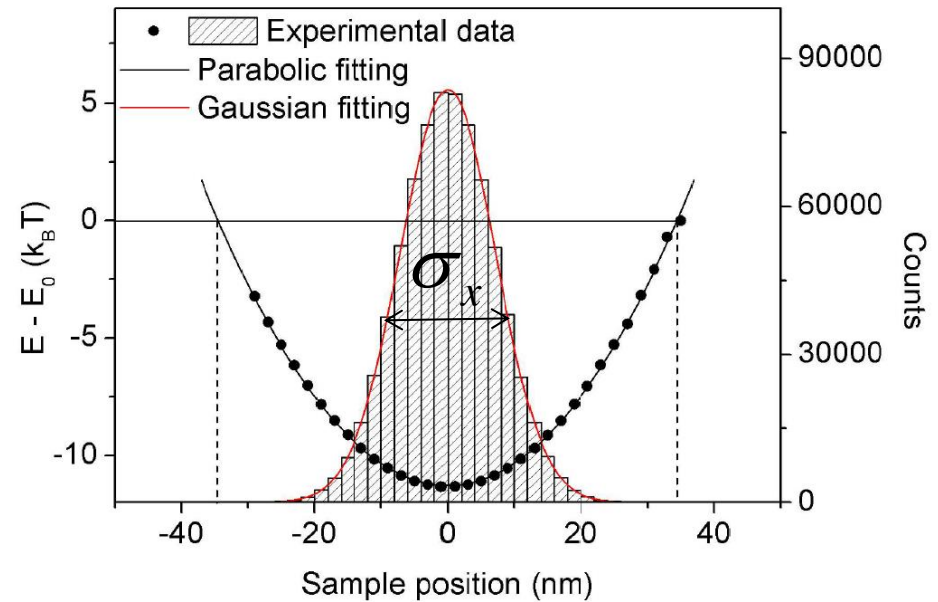


X, Y, Z - bead in trap

Probability density of the bead position
(Boltzmann statistics)

$$\rho(x, y) = C e^{\frac{-k_x x^2}{2 k_B T}} e^{\frac{-k_y y^2}{2 k_B T}}$$

Position histogram, potential energy



$$\rho(x, y) = C \exp\left(\frac{-U(x, y)}{k_B T}\right)$$

$$k_x = \frac{k_B T}{\sigma_x^2} \quad k_y = \frac{k_B T}{\sigma_y^2}$$

Problem with gaussian noise --> underestimated trap stiffness

Power Spectrum Analysis

The power spectrum $S_v(f)$ of the signal $sv(x)$ is:

$$S_v(f) = |F(s)|^2$$

F- Fourier transform

$S_v(f)$ - measured power spectrum

$S(f)$ - density Lorentzian fit

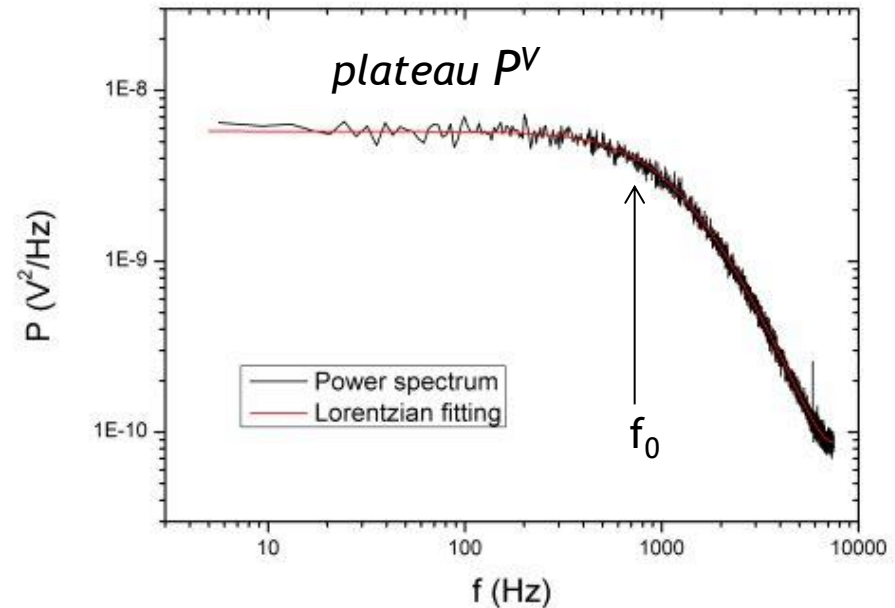
$$S(f) = \frac{S_0 f_0^2}{f_0^2 + f^2},$$

f_0 - corner frequency

$$f_0 = \kappa / 2\pi\gamma$$

k - trap stiffness

γ - Stokes drag coefficient

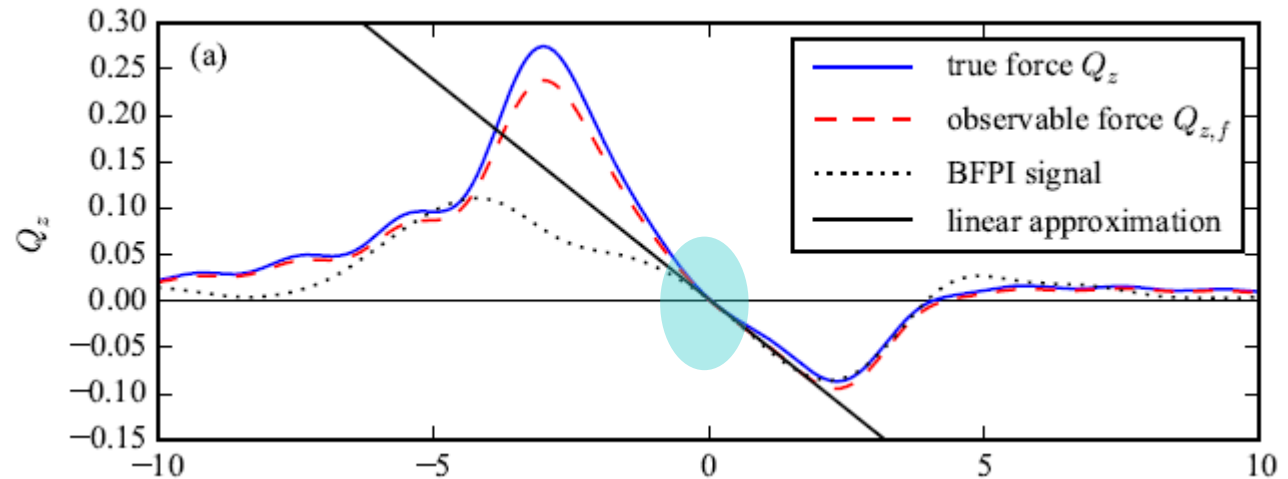


The power spectrum (black) of a trapped 1 μm silica bead acquired at 10 KHz and fitted to a Lorentzian (red).

Axial force - comparison between simulation and measurement

$$F = \alpha S = k x$$

$$F = Q n_1 P / c$$



Thalhammer *et al* Optics Express 23, 6112 (2015)

Fig. 3. Calculated axial force profile for a 3 μm diameter polystyrene bead. (a) True axial force Q_z (solid blue line) and estimate $Q_{z,f}$ from forward scattered light only (red dashed line). Also shown (black dotted line) is the axial BFPI signal (for a condenser with $\text{NA} = 0.8$), scaled and shifted such that value and slope coincides with the true force at the zero crossing. (b) Difference ΔQ of the estimated and the true force (red dashed line), and

Typical values for **OT** : $K_{\text{OT}} = 0.001 - 10 \text{ pN/nm}$

Typical values for **AFM**: $K_{\text{AFM}} = 10 - 1000 \text{ pN/nm}$

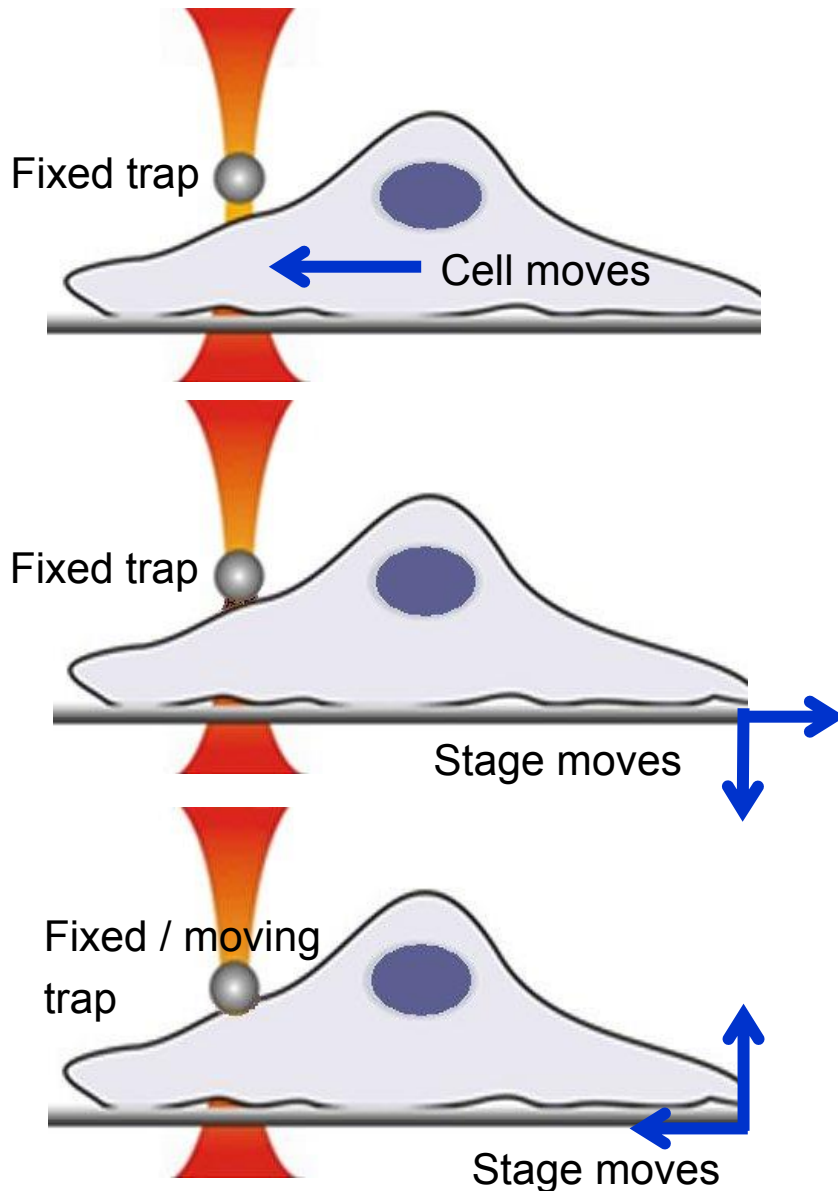
**OT and AFM
are complementary
Techniques**

OUTLINE

- Optical Tweezers (OT) - single-beam gradient force 3D optical trap: how this works, optical manipulation of microparticles
- Measuring picoNewton forces with OT : direct and indirect methods
- **Applications of OT in living cell studies:**
 - **probing forces expressed by developing neurons**
 - **probing the stiffness of cancer cells**
 - **mechanotransduction - conversion of the mechanical stimulus into a biochemical signal by the cell**
 - **biochemical local cell stimulation using optically manipulated vectors (coated beads, biodegradable micro-sources, liposomes)**

OT local probing living cells

(touch - pull - push approaches)



Touch / intercept

Measure forces when full cell or part of the cell move

Pull (Coated beads)

Local adhesion / binding

Local viscoelasticity (tether membrane)

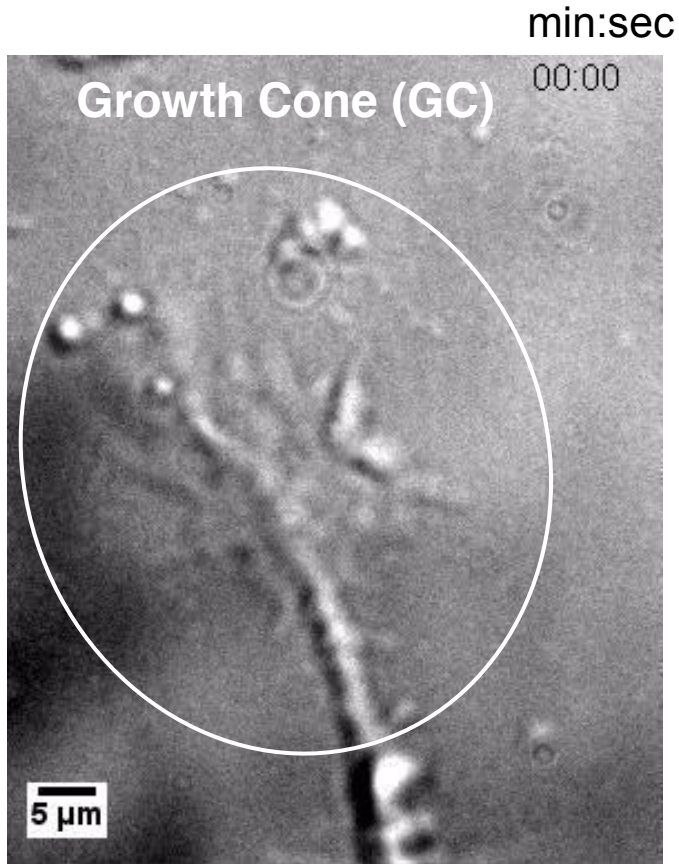
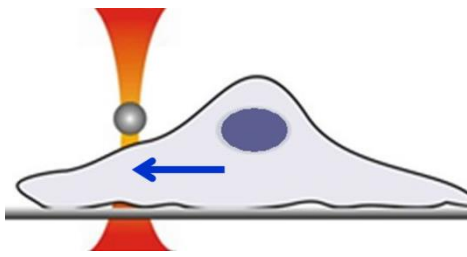
Push

Local viscoelastic properties

Local cell stressing

TOUCH Example:

measuring the forces expressed by lamellipodia and filopodia of the Growth Cone

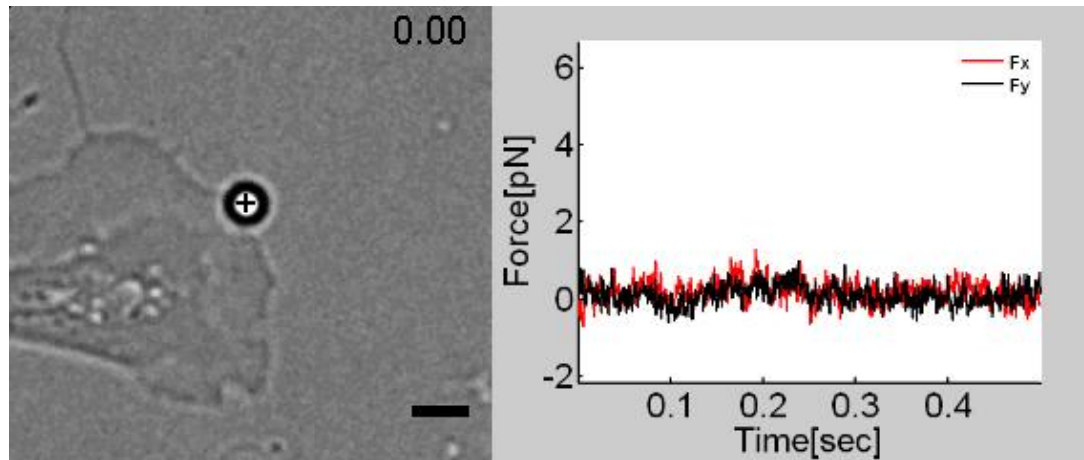


2 DIV hippocampal neuron from mouse
stimulated with BDNF at $t = 5$ min.

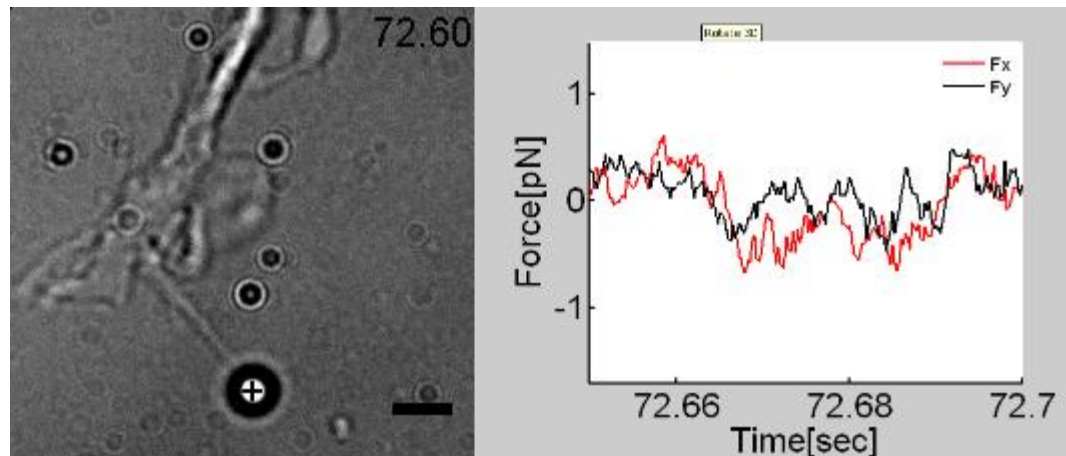
Cojoc, D, ... & Torre, V, PLoS One 2 (10), e1072 (2007)

Difato, F, Pinato, G & Cojoc, D, *Int. J. Mol. Sci.* **14**, 8963 (2013) - REVIEW

Force exerted by Lamellipodia

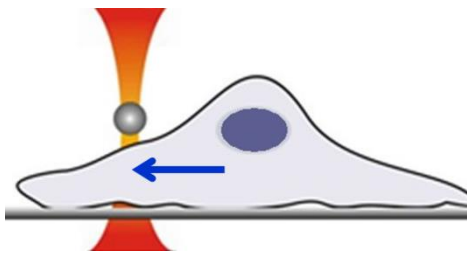


Force exerted by Filopodia - Protrusion



Acquisition rate: 20Hz; Scale Bar = 2 μ m; Time in seconds

Acquisition rate : 4KHz, Subsampled at : 2KHz

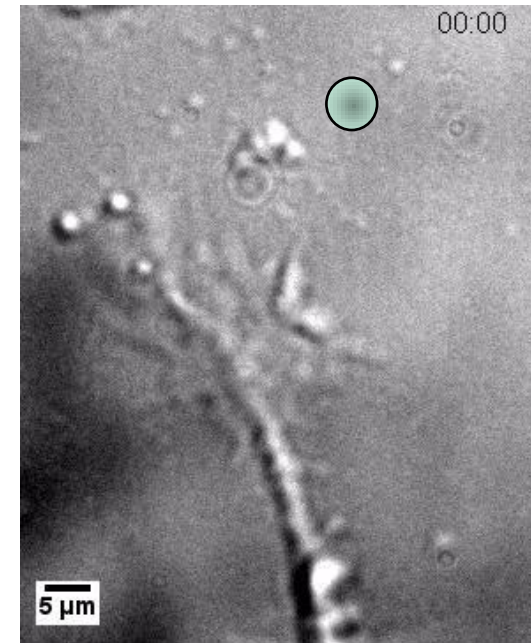


TOUCH Example:

measuring the forces expressed by lamellipodia and filopodia of the Growth Cone

We found that:

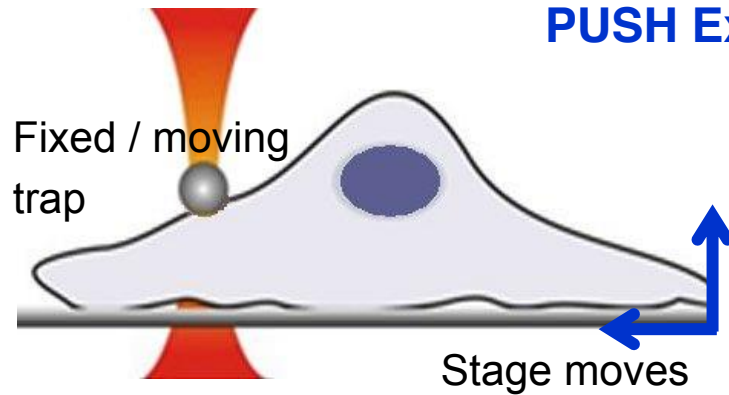
- **Forces exerted** by filopodia were ≤ 3 pN and by lamellipodia were < 20 pN
- **Forces** were discontinue (max frequency about 200 Hz)
- **Inhibitors** of **myosin** light chain kinase (ML-7) or of **microtubule** polymerization drastically reduced the force exerted by lamellipodia, while filopodia continued to exert forces up to 3 pN.
- **Inhibitor** of **actin** polymerization blocked the GC from expressing any force



Cojoc, D, ... & Torre, V, PLoS One 2 (10), e1072 (2007)

Difato, F, Pinato, G & Cojoc, D, *Int. J. Mol. Sci.* **14**, 8963 (2013) - REVIEW

PUSH Example



Cell membrane indentation by OT to measure cells elasticity

(same type of experiment as with AFM, but with much smaller loading rate)

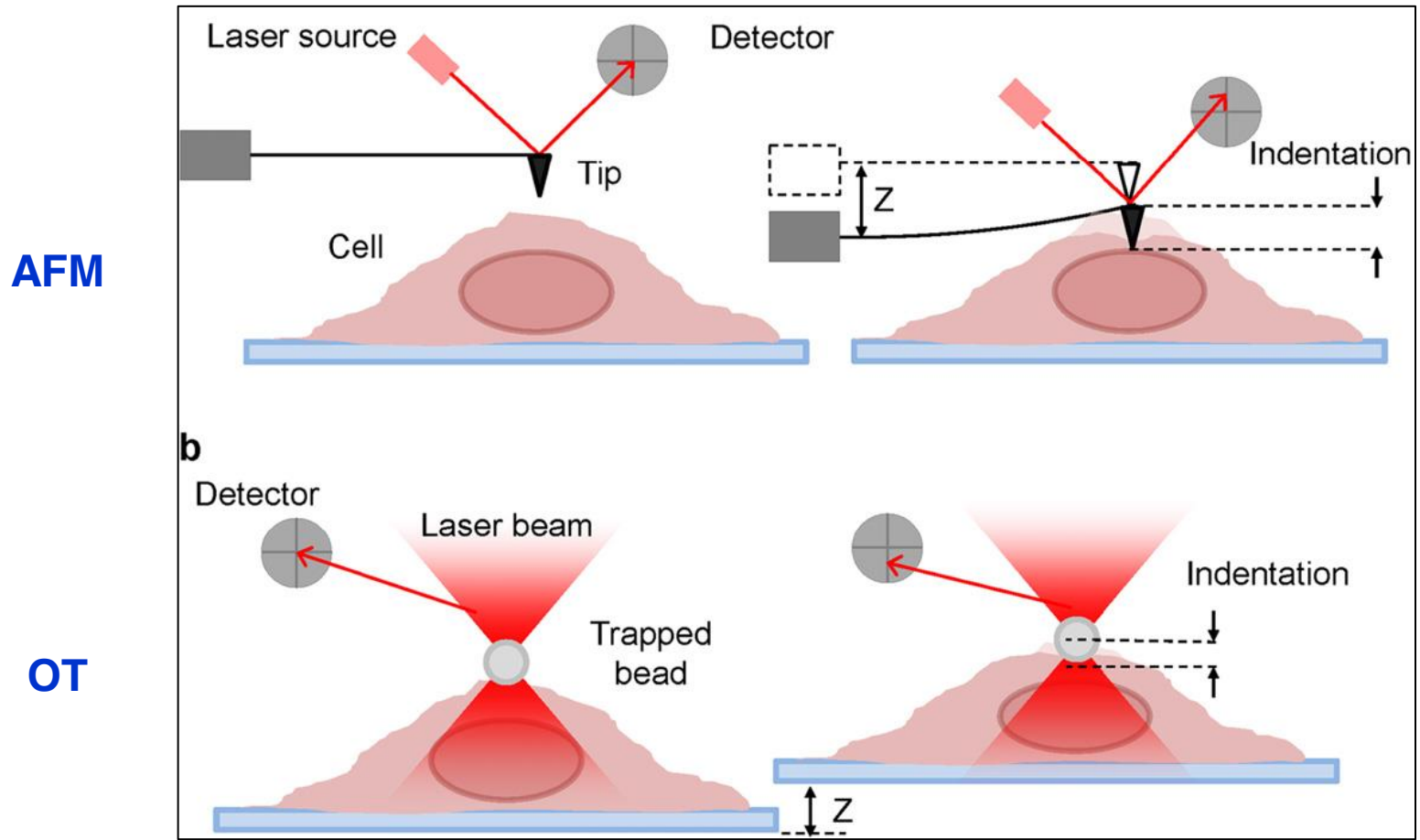
Why measuring the elasticity of cancer cells ?

- Different cells have different mechanical properties
- Cancer cells change their mechanical properties during their cancer journey
- Elasticity might be a label free bio-marker
- Investigating cell mechanics helps to understand cell alterations

It is generally accepted that cancer cells are softer than the non-neoplastic cells.

Is it always true ?

Cell vertical indentation: AFM vs OT



	AFM	OT
Force	$10 - 10^3$ pN	$10^{-1} - 10^2$ pN
Stiffness	> 10 pN/nm	< 10 pN/nm

Yousafzai et. al. 2015, *Opt. Lasers Eng.*

Coceano et. al. 2016, *Nanotechnology*

Comparing cell stiffness of cells from 3 human breast cancer cell lines

Normal myoepithelial

Luminal breast cancer

Basal breast cancer cells

Non neoplastic

Low metastatic potential

High metastatic potential

HBL-100

MCF-7

MDA-MB-231

by using 2 complementary techniques

OT: $k = 0.015 \text{ pN/nm}$, $A = 1 \mu\text{m}$, $f = 0.2 \text{ Hz}$, $F = 10 \text{ pN}$

AFM: $k = 150 \text{ pN/nm}$, $A_{\text{PF}} = 1 \mu\text{m}$, $f_{\text{PF}} = 200 \text{ Hz}$, $F_{\text{SP}} = 1 \text{ nN}$

Some questions:

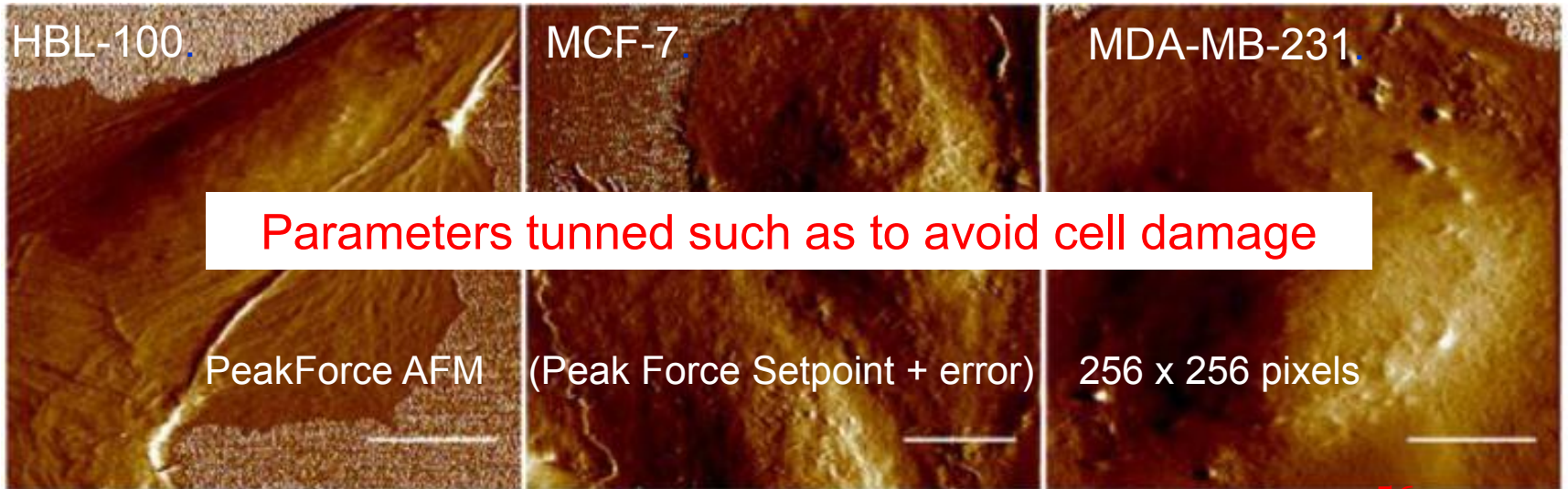
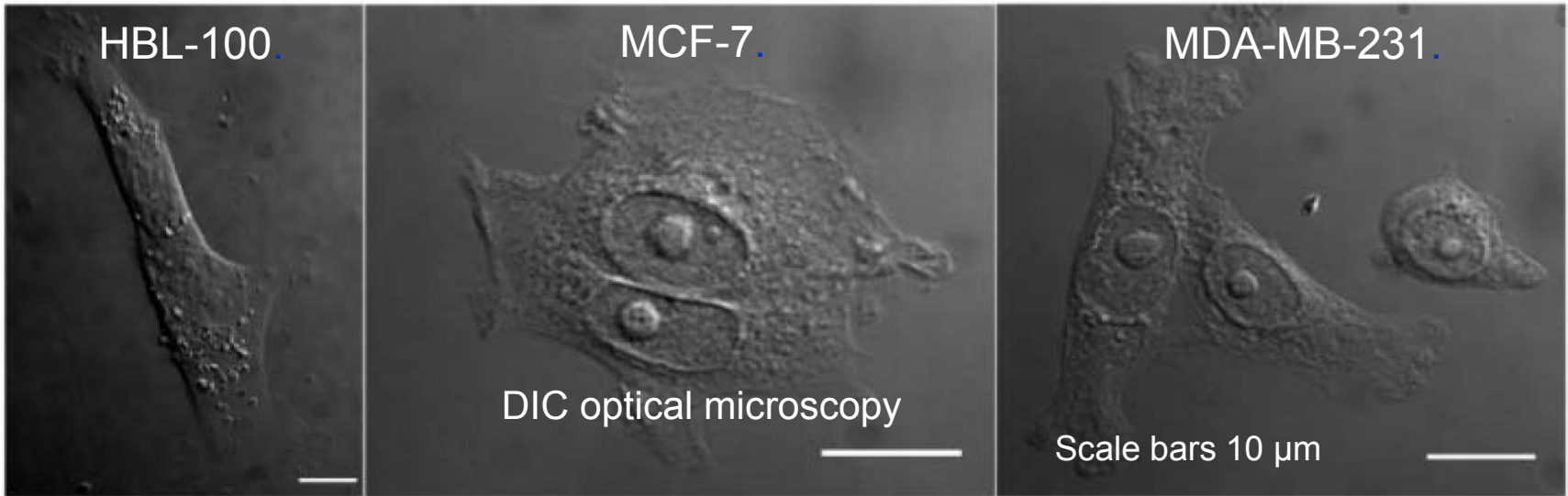
- do we damage the cells by laser radiation (OT) or mechanical interaction (AFM) ?
- where should we measure ? on top of the nuclear region, near the leading edge ?
- are the results obtained for cell stiffness by using OT and AFM comparable ?

Cell morphology – DIC optical microscopy + AFM

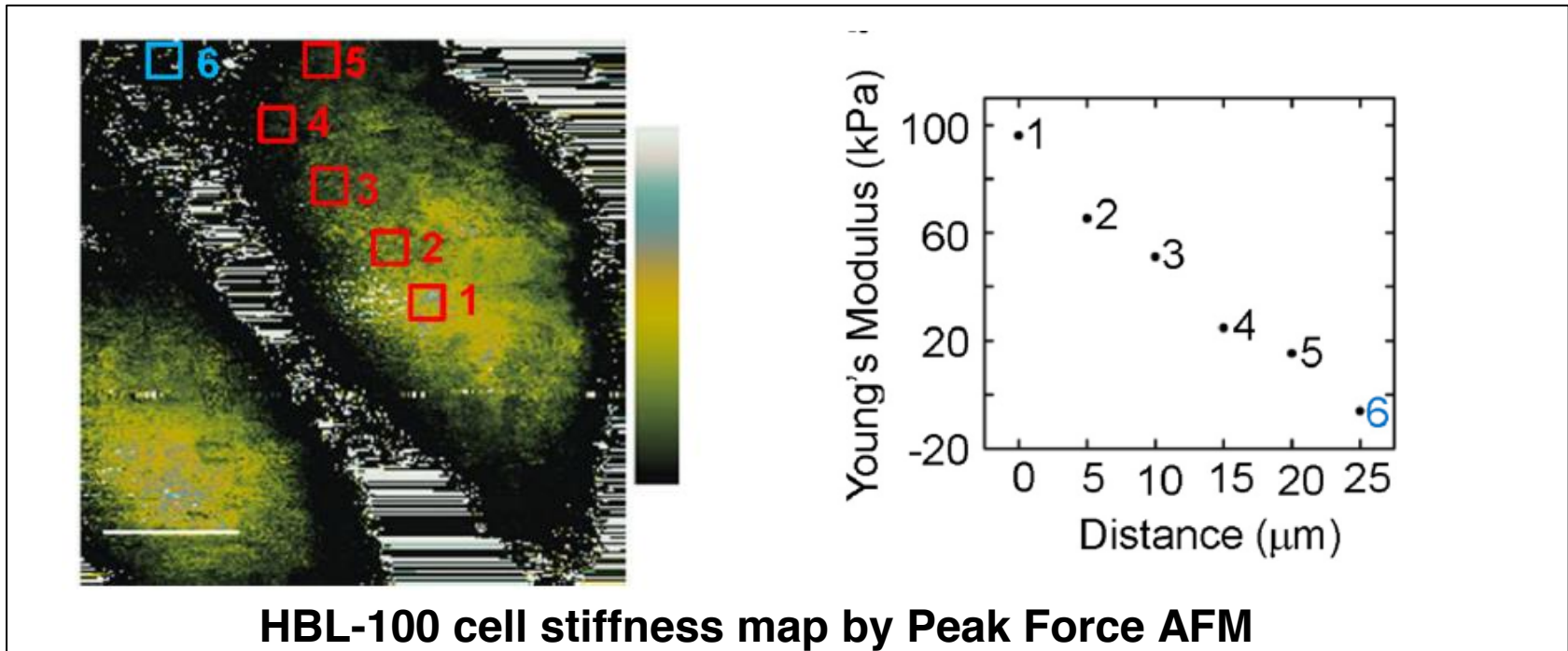
Normal myoepithelial
Non neoplastic

Luminal breast cancer
Low metastatic potential

Basal breast cancer cells
High metastatic potential

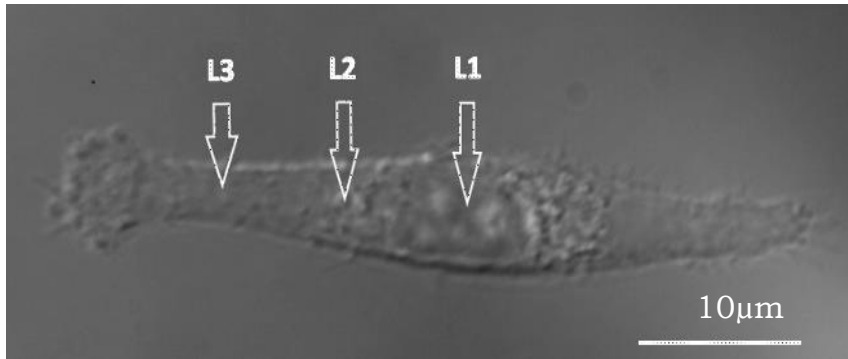


Where to measure ?

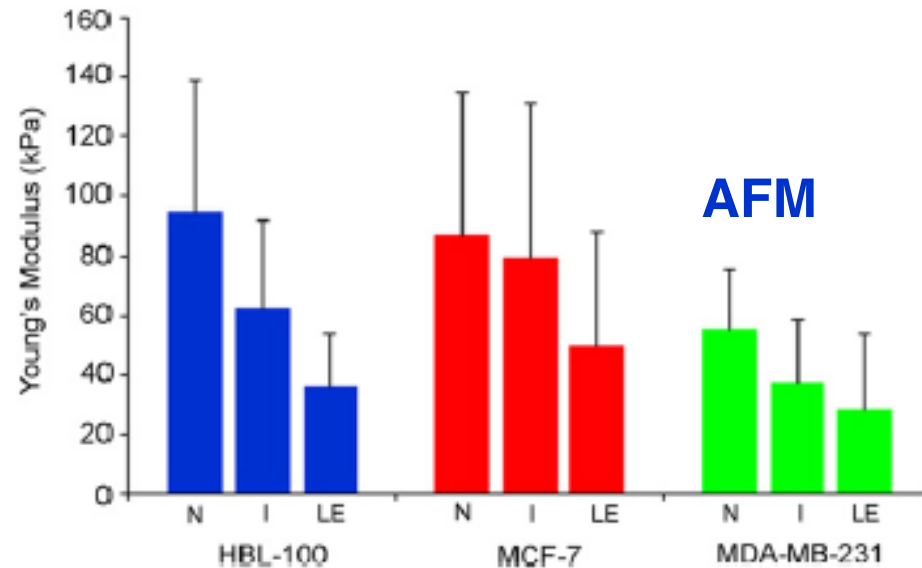
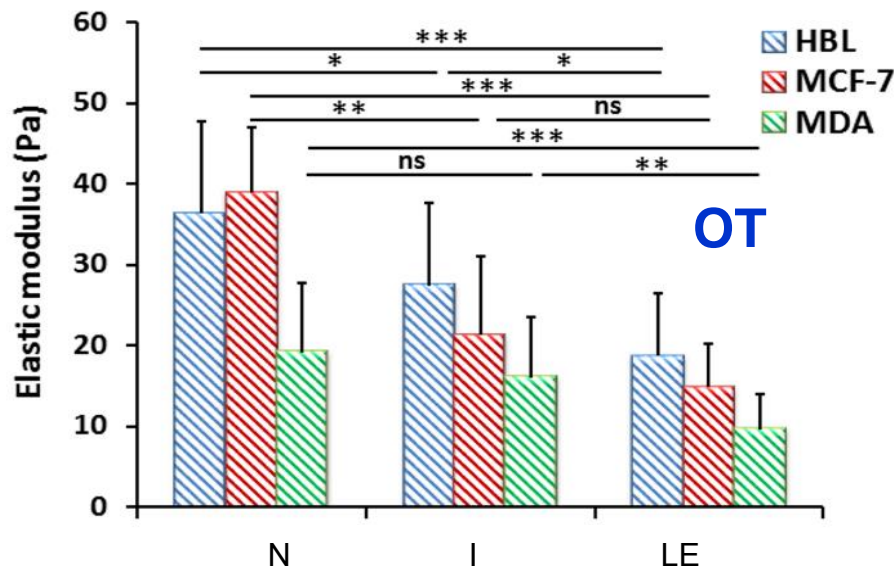


Local cell stiffness is calculated averaging the values inside a 2.5 x 2.5 μm square. 6 squares, positioned at different distances from the nuclear region 1 are considered. The nuclear region 1 is chosen from topography of the cell as the highest feature in the height channel. Square 6 (blue) is on the substrate and hence the value is irrelevant. Scale bar 10 μm. Color bar : 0- 300 kPa

- Cell stiffness decreases from the nuclear region (centre) to the leading edge
- The nuclear region is the most reliable region to measure since it is well defined by topography.

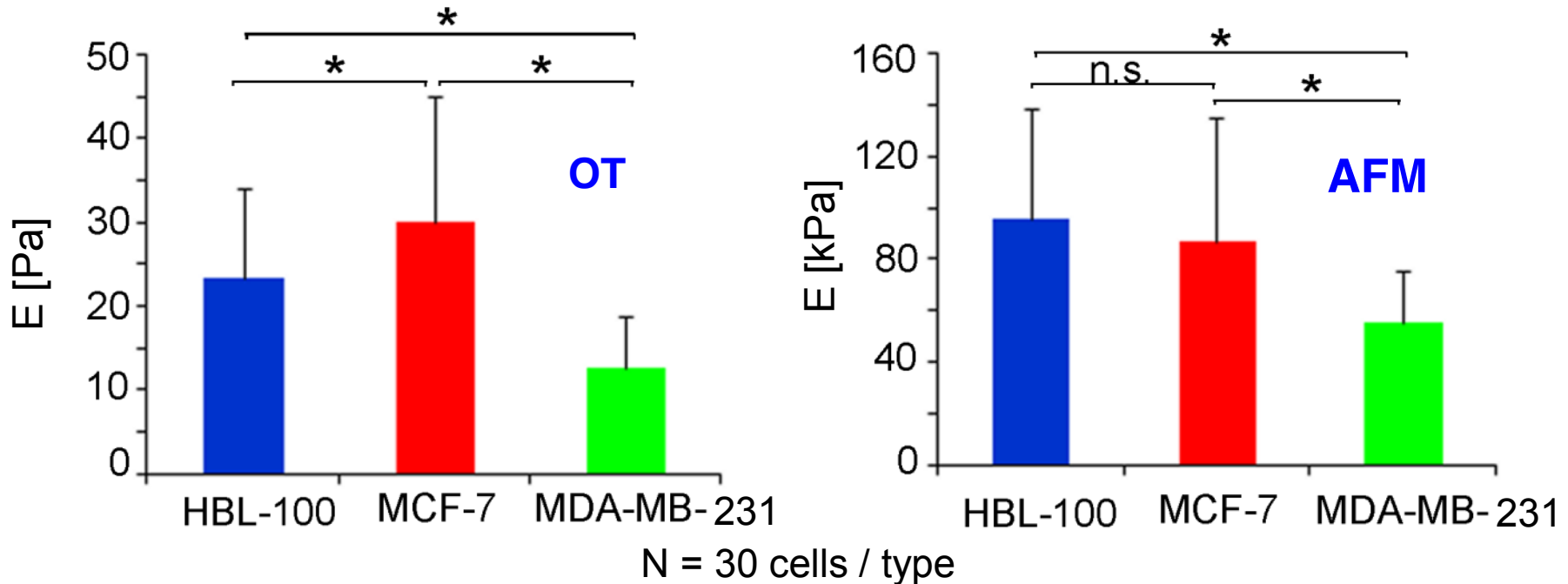


OT: Each cell was indented at three different locations:
 N – Nuclear region
 I - Intermediate
 LE -Leading Cedge



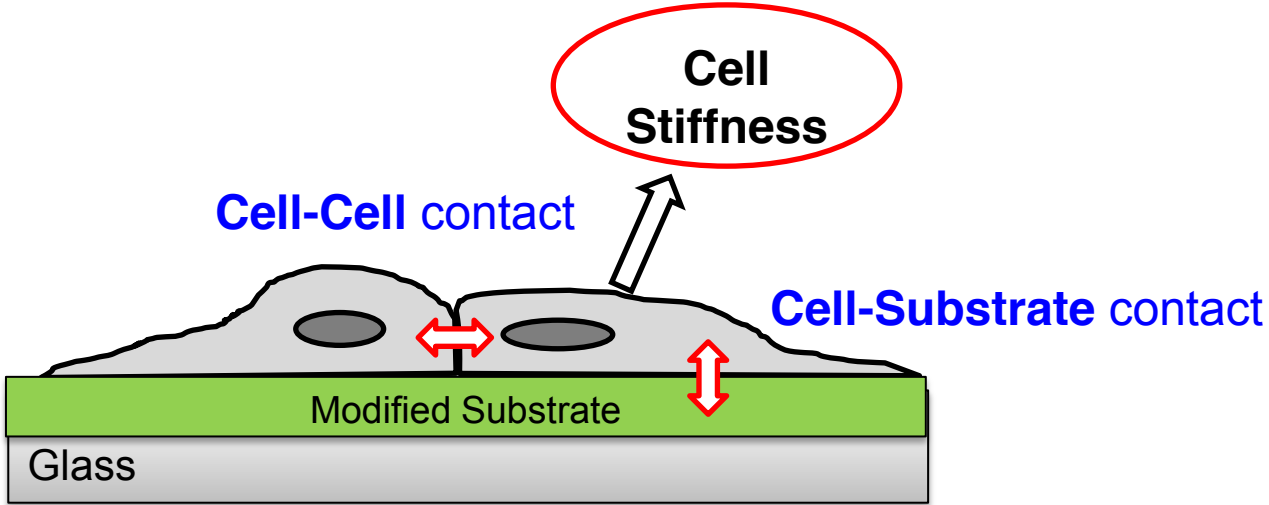
- Cells are stiffer at the center (for all the cell lines).
- The trend was confirmed by both OT and AFM measurements.

Cell stiffness measured above the nuclear region

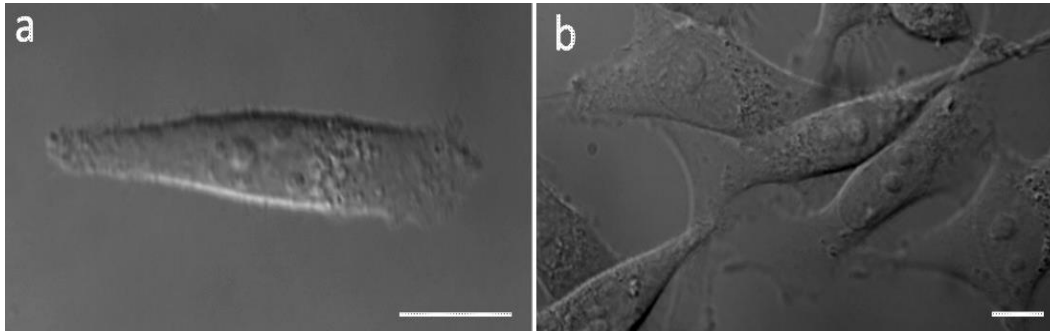


- MDA – MB- 231 cells (**high metastatic potential**) are significantly **softer** than the other two cell types
- this **result is confirmed both by OT and AFM** techniques
- the absolute values obtained for E are different because the force range and the loading rate are different for OT and AFM
- OT reveals a significant difference between HBL and MCF cells

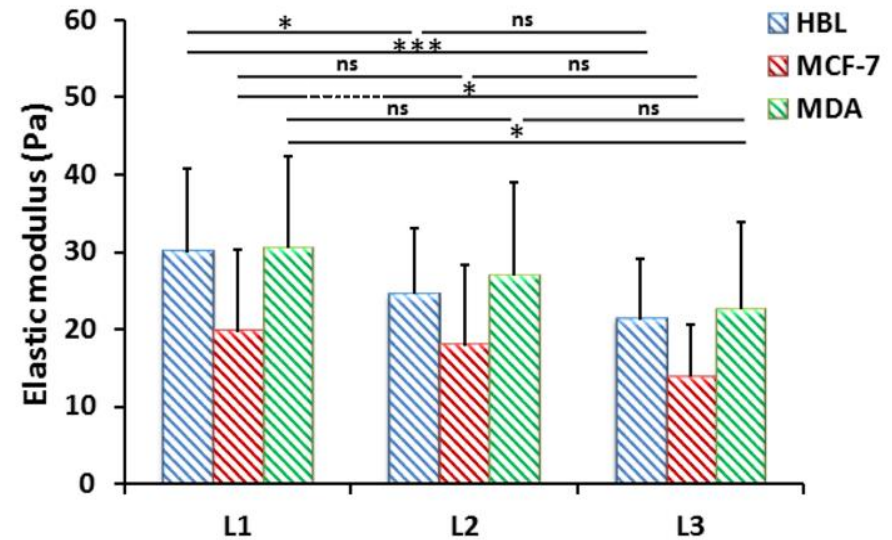
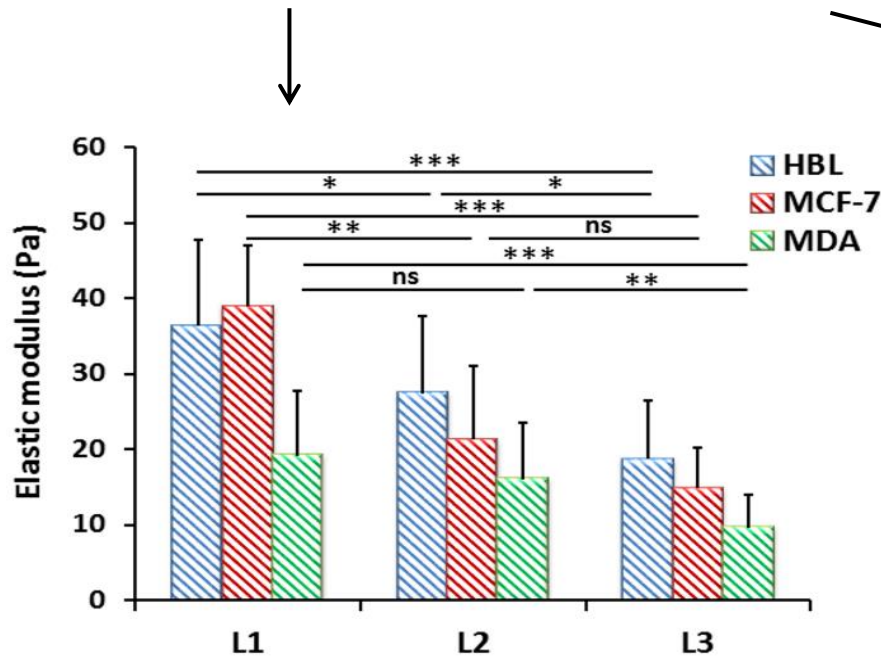
Is the cell stiffness influenced by cell's microenvironment ?



OT only: Cell –Cell contact



Each cell was indented at three different locations:
 L1 - Center (nucleus)
 L2 - Nucleus edge
 L3 -Leading edge

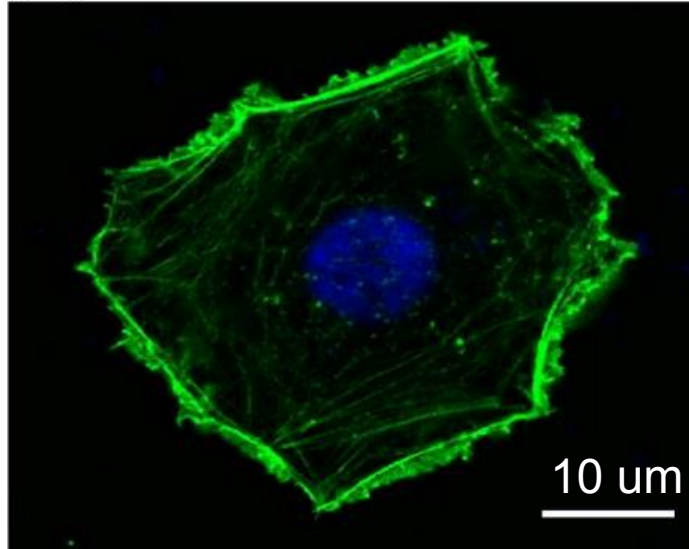


- **MDA cells get stiffer when in contact, being similar to HBL and MCF**
- MCF and HBL become softer.

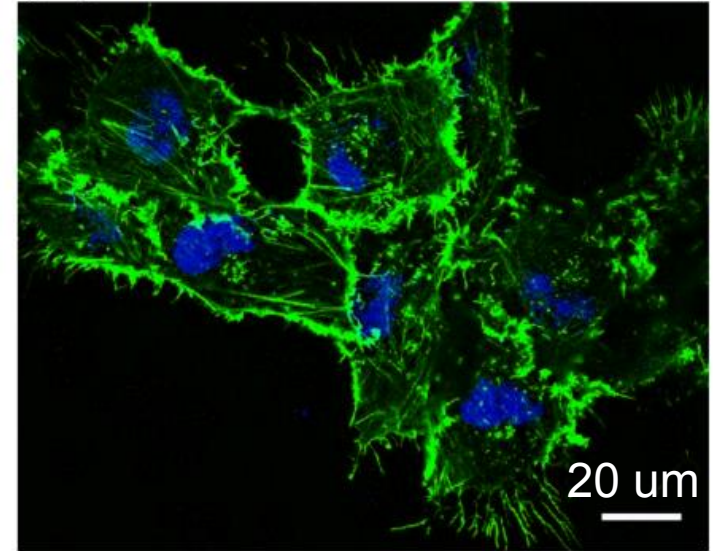
Confocal Images of actin (green) + nucleus DAPI (blue)

HBL – 100

(a)

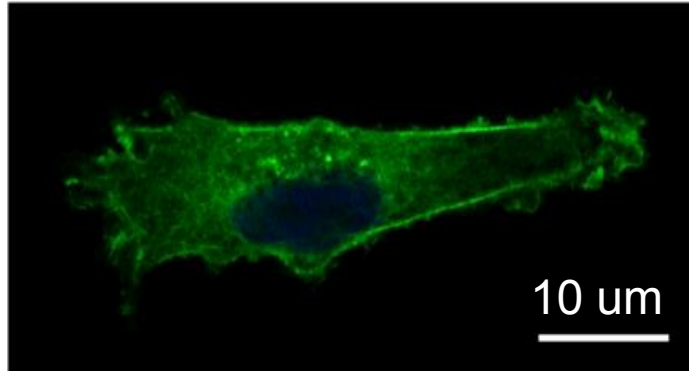


(b)

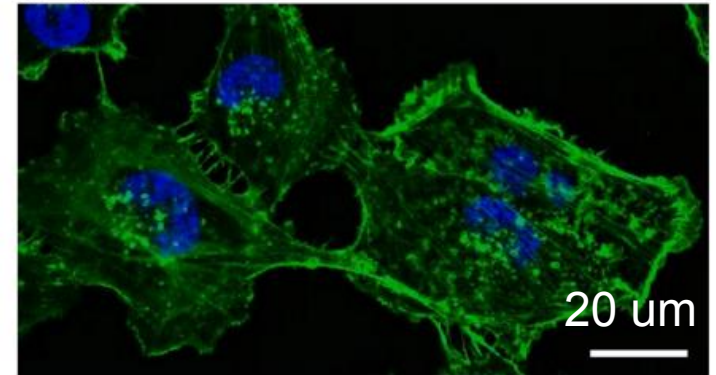


MDA-MB-231

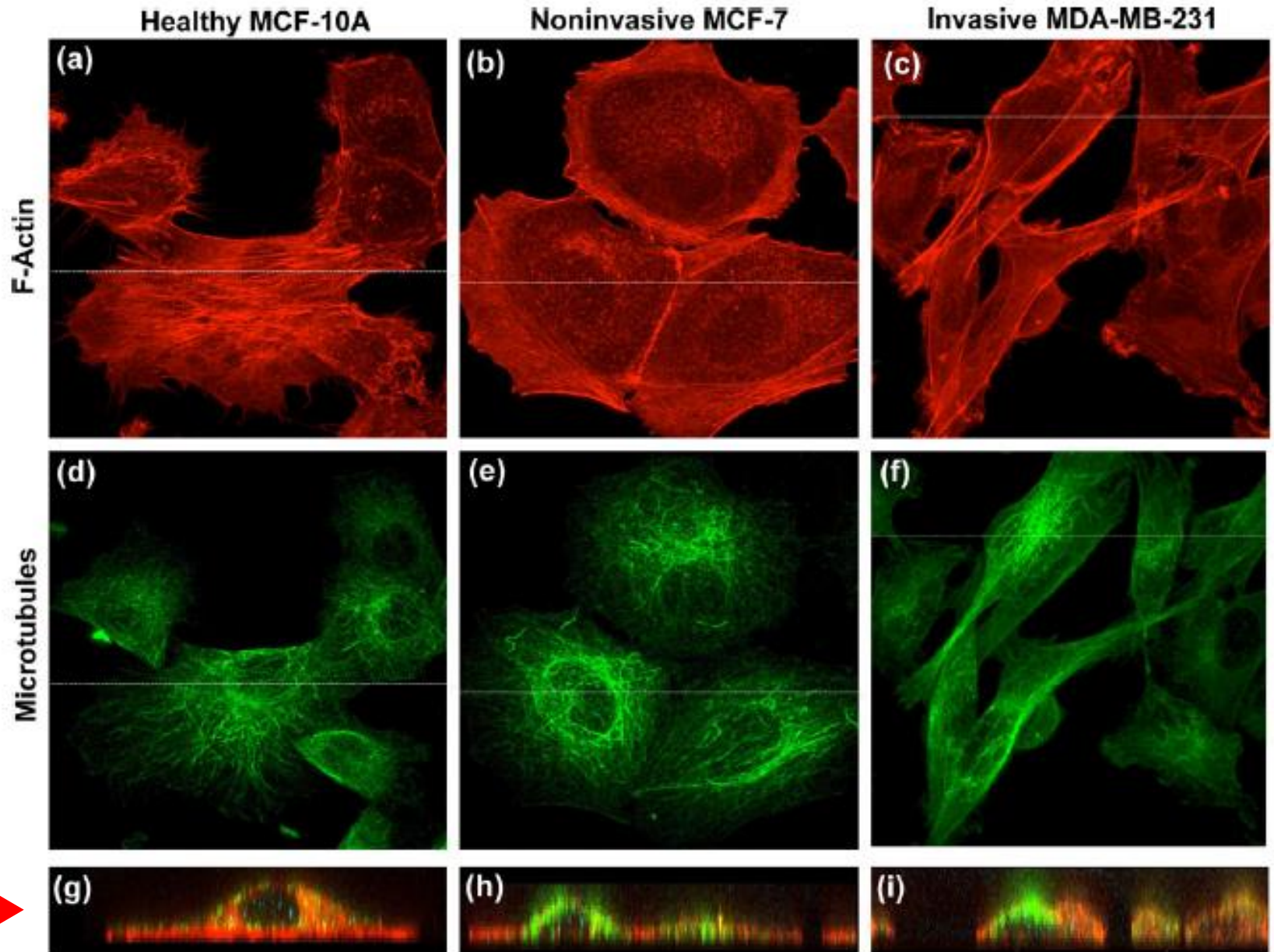
(c)



(d)



Confocal Images of actin (red) + microtubules (green)



OUTLINE

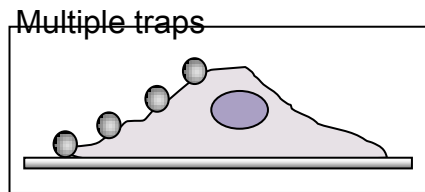
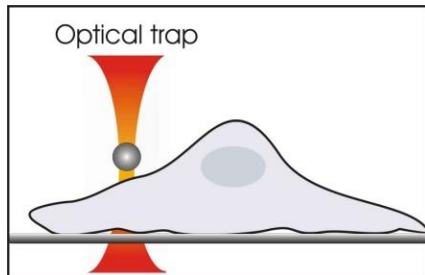
- Optical Tweezers (OT) - single-beam gradient force 3D optical trap: how this works, optical manipulation of microparticles
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Focal Mechanical Stimulation (Examples)

Mechanical stimulation is induced by trapped beads, moving either the beads or the cell.

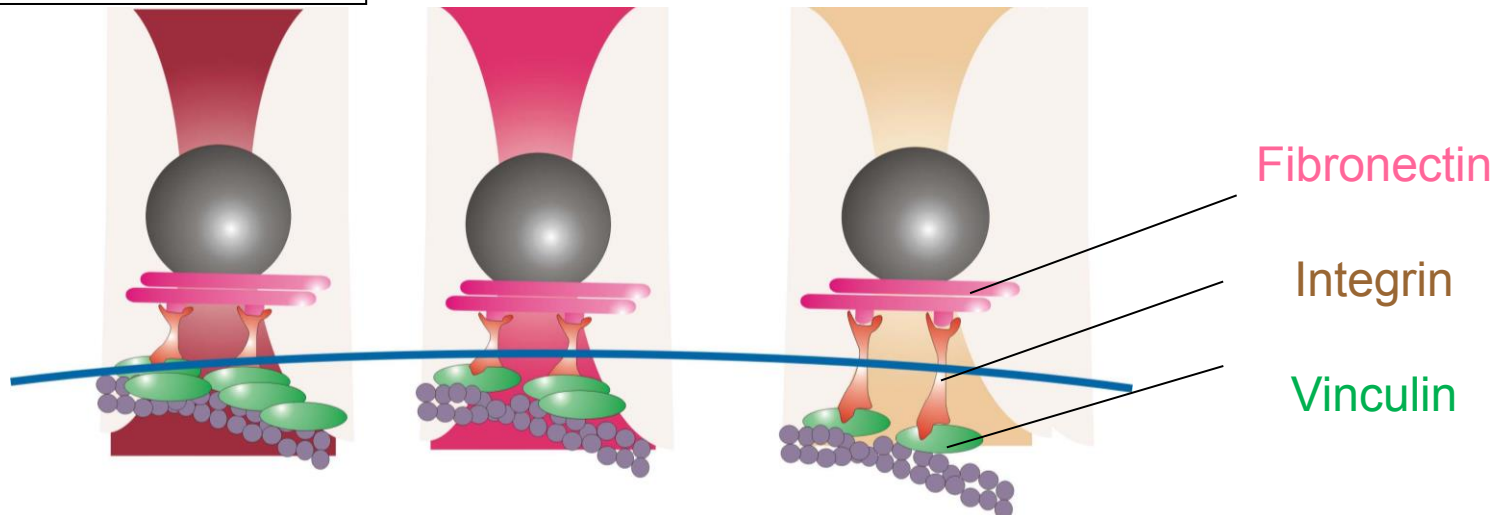
The effect of the mechanical force applied by the beads on the cell is monitored by optical microscopy techniques on the same platform.

Example 1: Cell mechanical stimulation at multiple adhesion sites, with force modulation



Multiple optical trapping is combined with epi-fluorescence to monitor vinculin recruitment as a function of the trap strength.

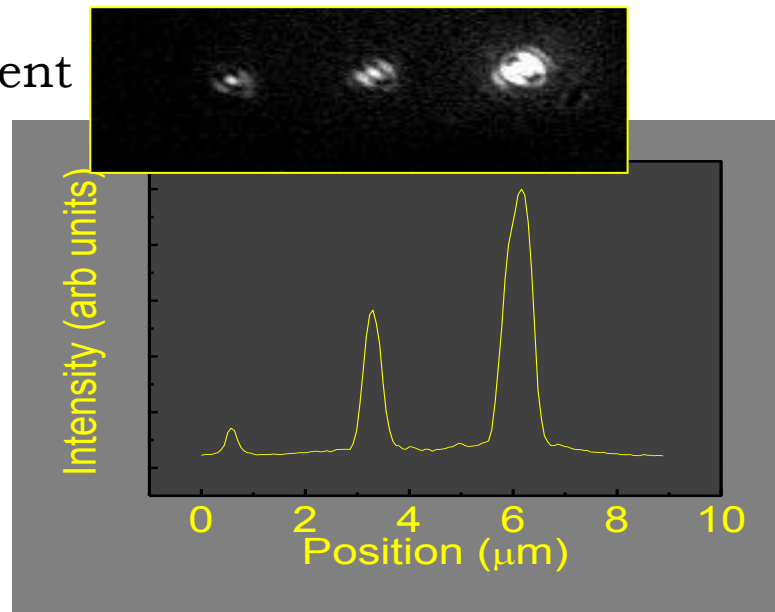
Fn coated beads are manipulated on the dorsal surface of Vin-GFP transfected HeLa cell.



Vinculin recruitment

**The strength of
the traps is
modulated
in 3 steps**

changing
the power of the laser



**Vinculin recruitment
increases with the
strength of the trap,
Showing a selective
response of the cell to
the mechanical stimulus.**

DIC

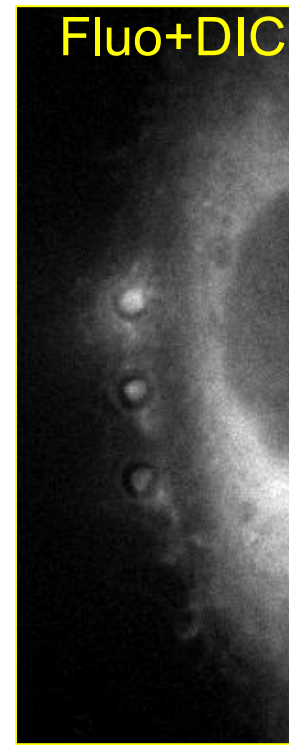
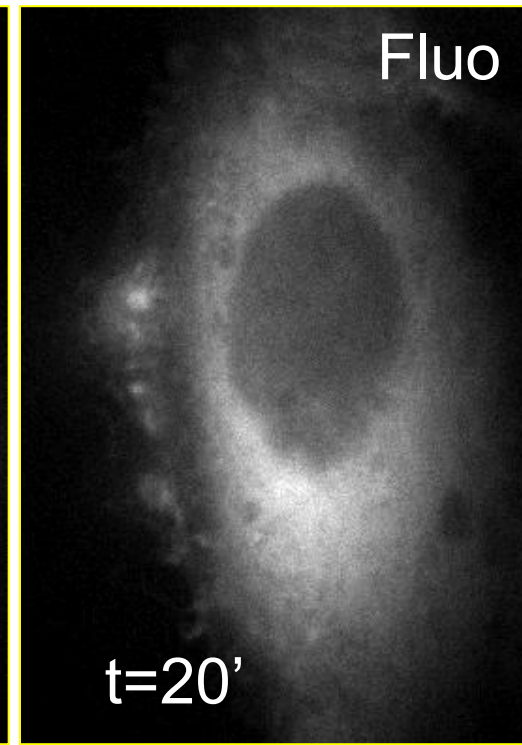
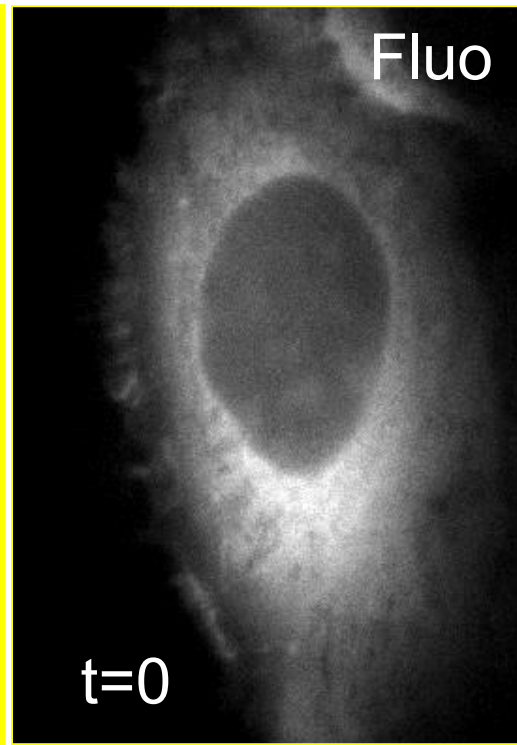
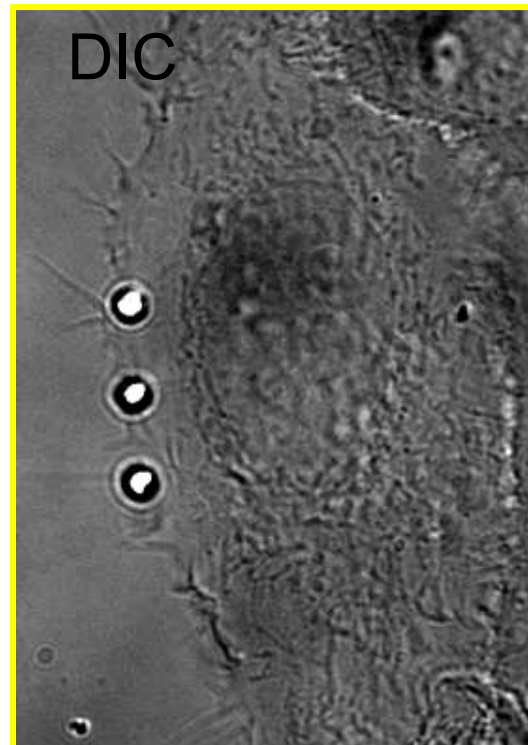
Fluo

Fluo

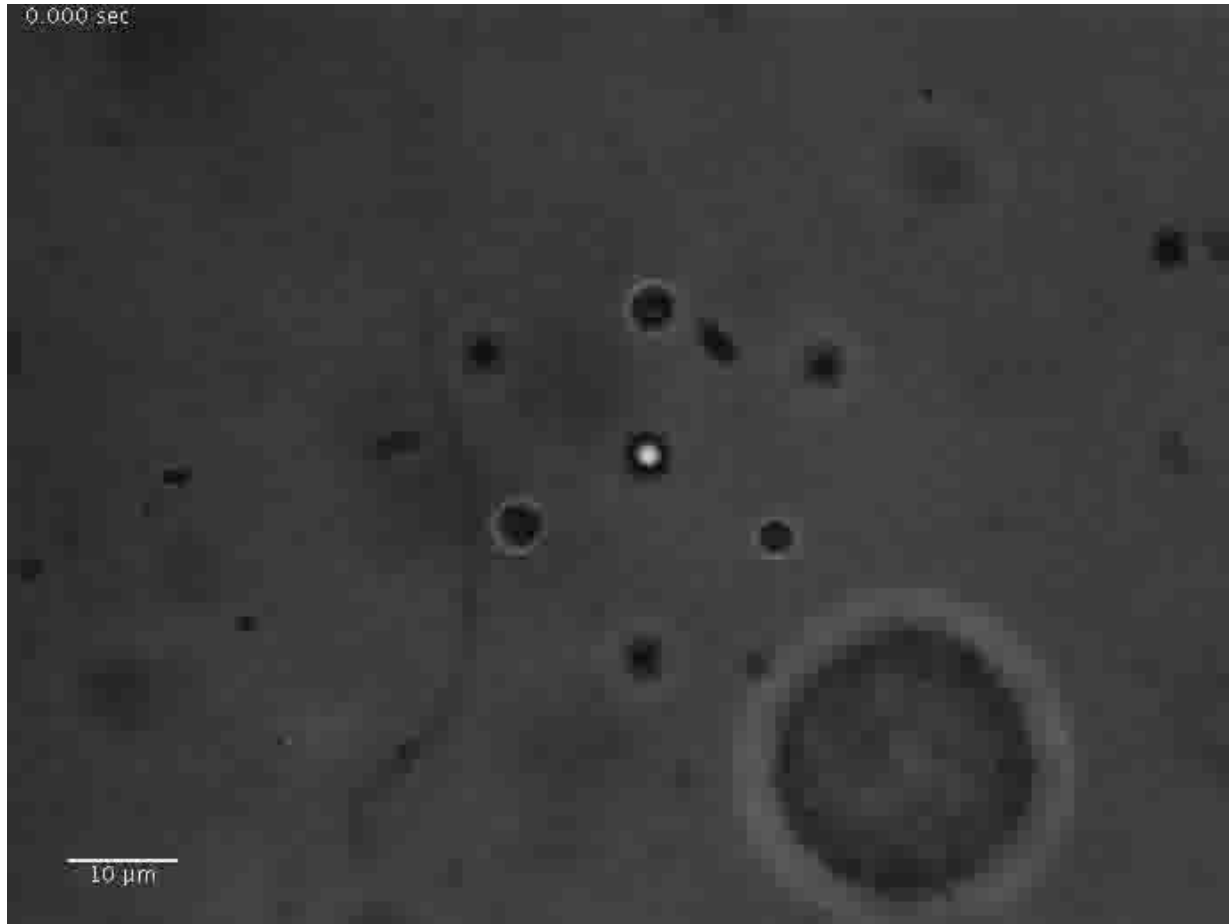
Fluo+DIC

t=0

t=20'



Using multiple OT to stimulate the cell

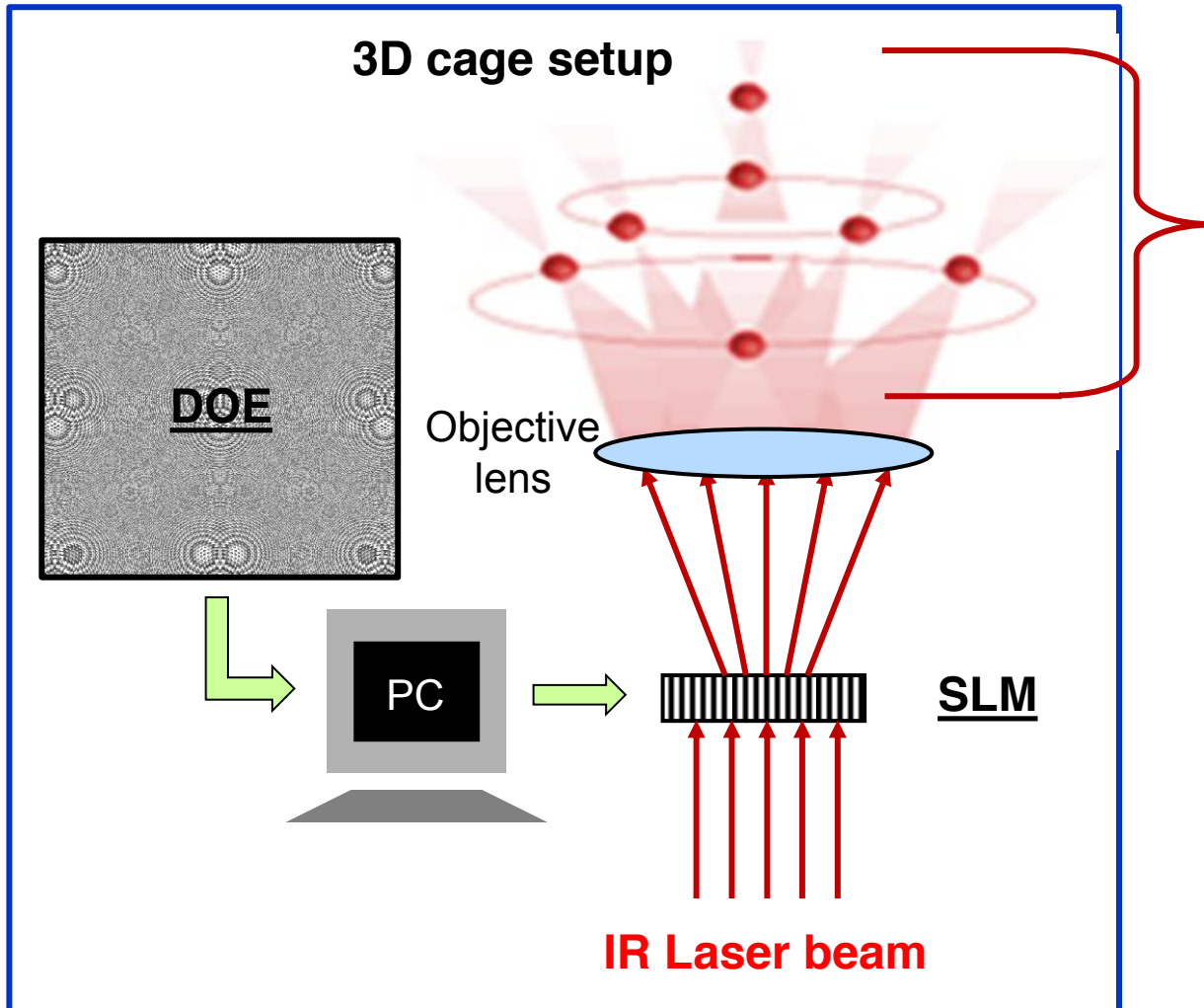


HeLa cell goes under the cage (configured by OT)

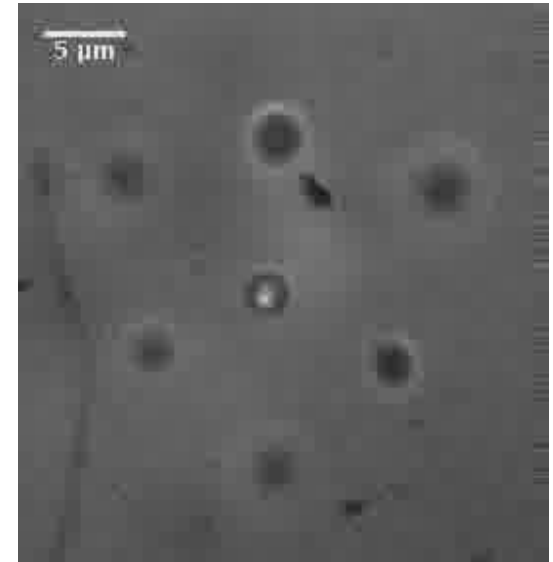
2004-2006, E. Ferrari OM-Lab collaboration with Dr. V. Emiliani
from Pierre and Marie Curie University (Paris VI)

Building the cage

by means of Diffractive Optical Elements implemented on a Spatial Light Modulator



3D cage (top view)



D. Cojoc *et al* 2004-2006

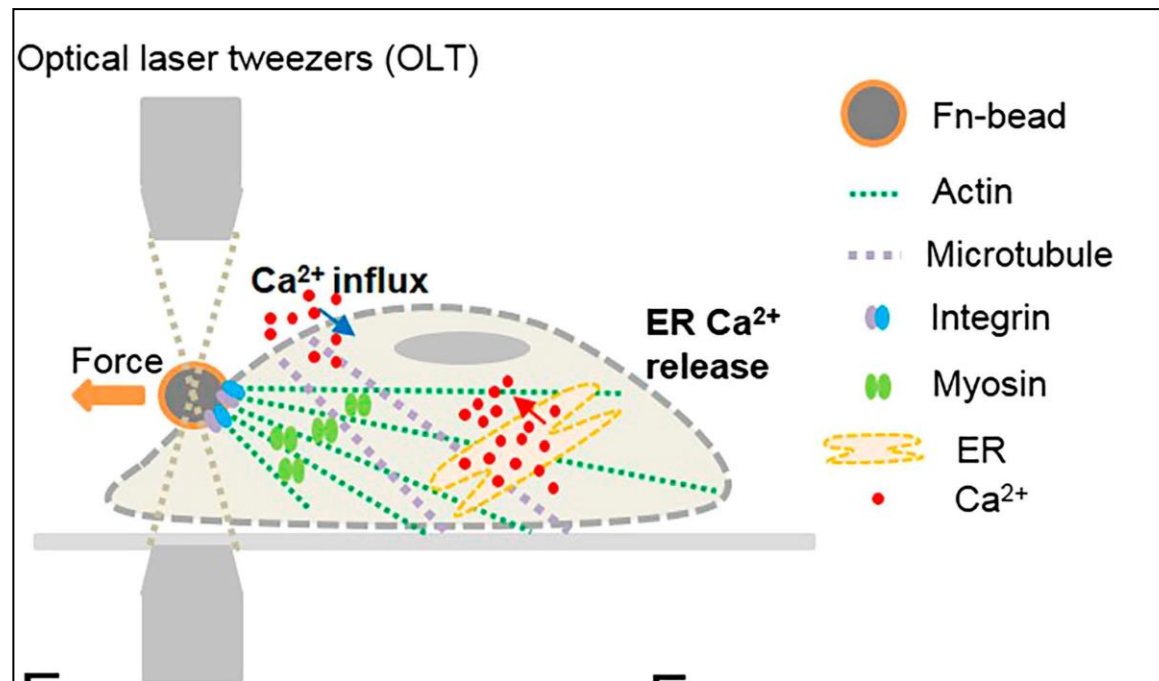
OM-Lab

Distinct mechanisms regulating mechanical force-induced Ca^{2+} signals at the plasma membrane and the ER in human MSCs

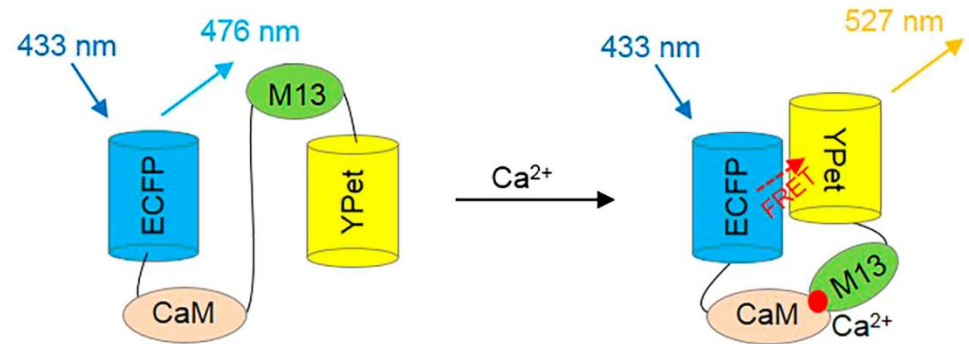
Tae-Jin Kim *et al*, eLife 2015;4:e04876.

DOI: 10.7554/eLife.04876

Investigate how mechanical forces are transmitted in a human mesenchymal stem cell using optical tweezers for mechanical stimulation and a FRET probe for Ca^{2+} to CaM protein binding measurement.



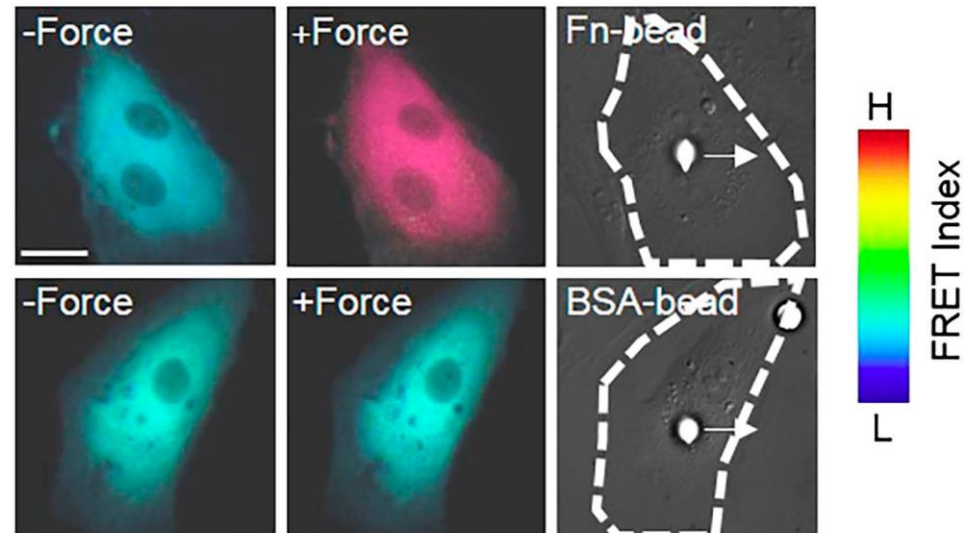
Schematic drawing of the activation mechanism of the Ca²⁺ FRET biosensor.

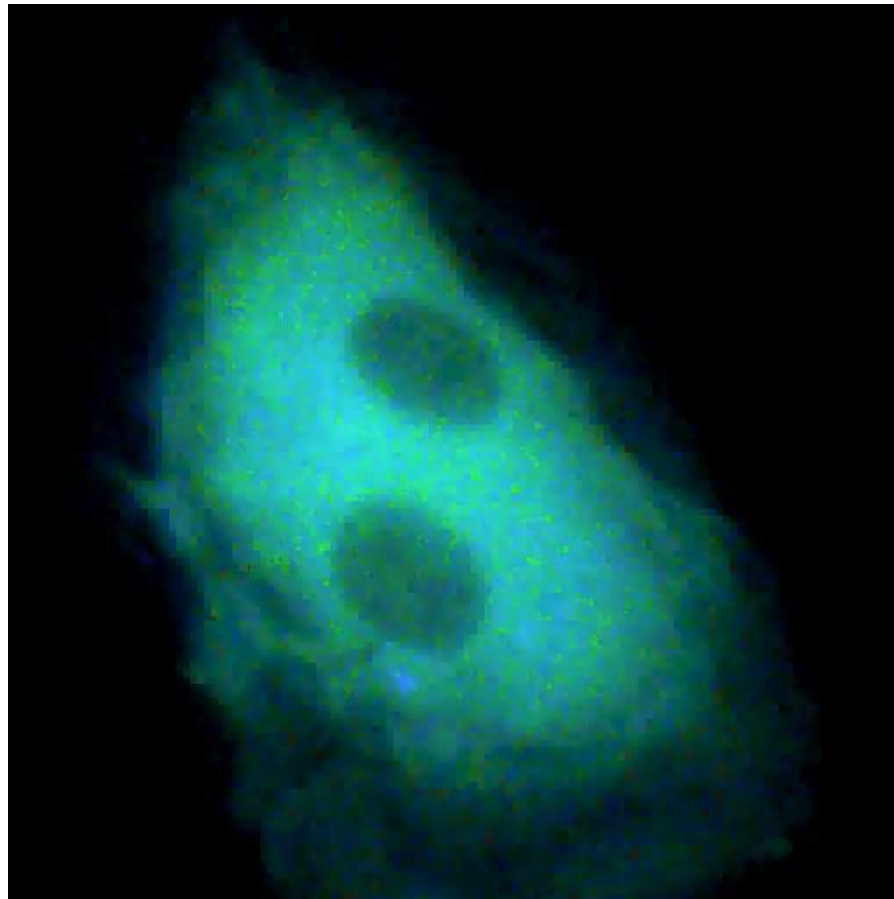


Color images represent the YPet/ECFP emission ratio of the cytoplasmic Ca²⁺ biosensor.

The color scale bars represent the range of emission ratio, with cold and hot colors indicating low and high levels of Ca²⁺ concentration, respectively.

Notice the high ratio when the force is applied by the Fn bead.





A HMSC transfected with cytosolic Ca²⁺ biosensors before and after mechanical force application by optical laser tweezers on a Fn-coated bead attached to the cell (Duration of Video: 2700 s).

Biochemical Stimulation

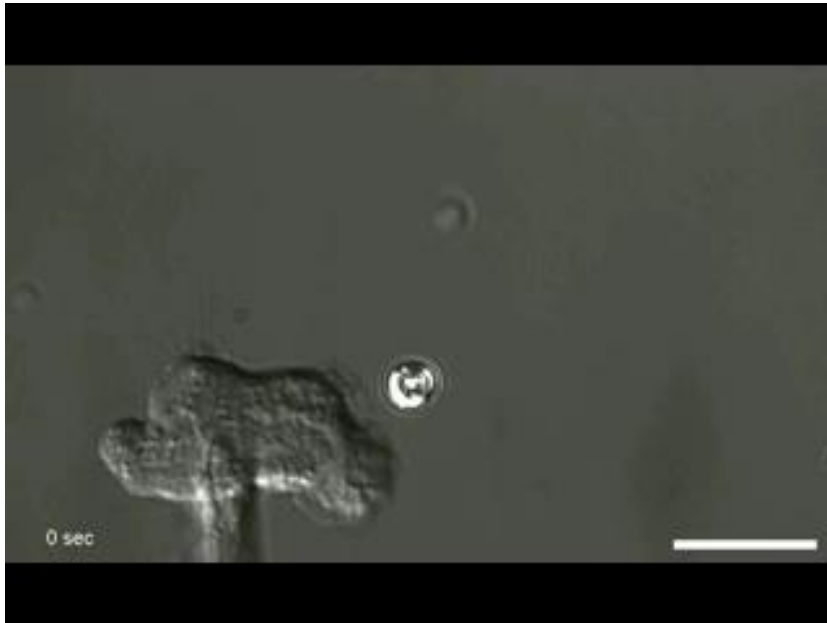
Biomechanical stimulation is induced by coated beads
optically manipulated in contact to the cell

or

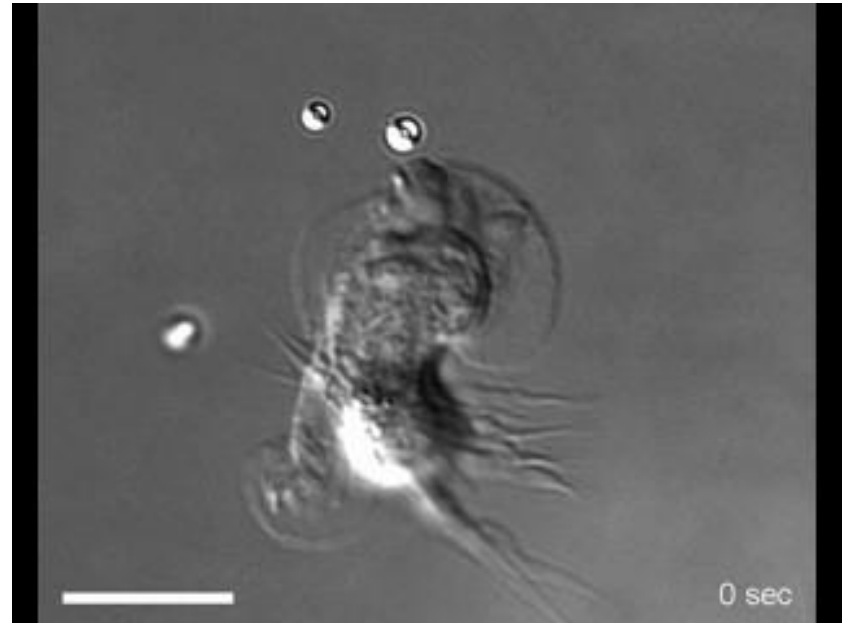
filled liposomes optically manipulated
in the vicinity of the cell and photolysed

The effect on the cell is observed by
optical microscopy techniques on the same platform

Cell stimulation with biodegradable micro sources



Chemoattractant

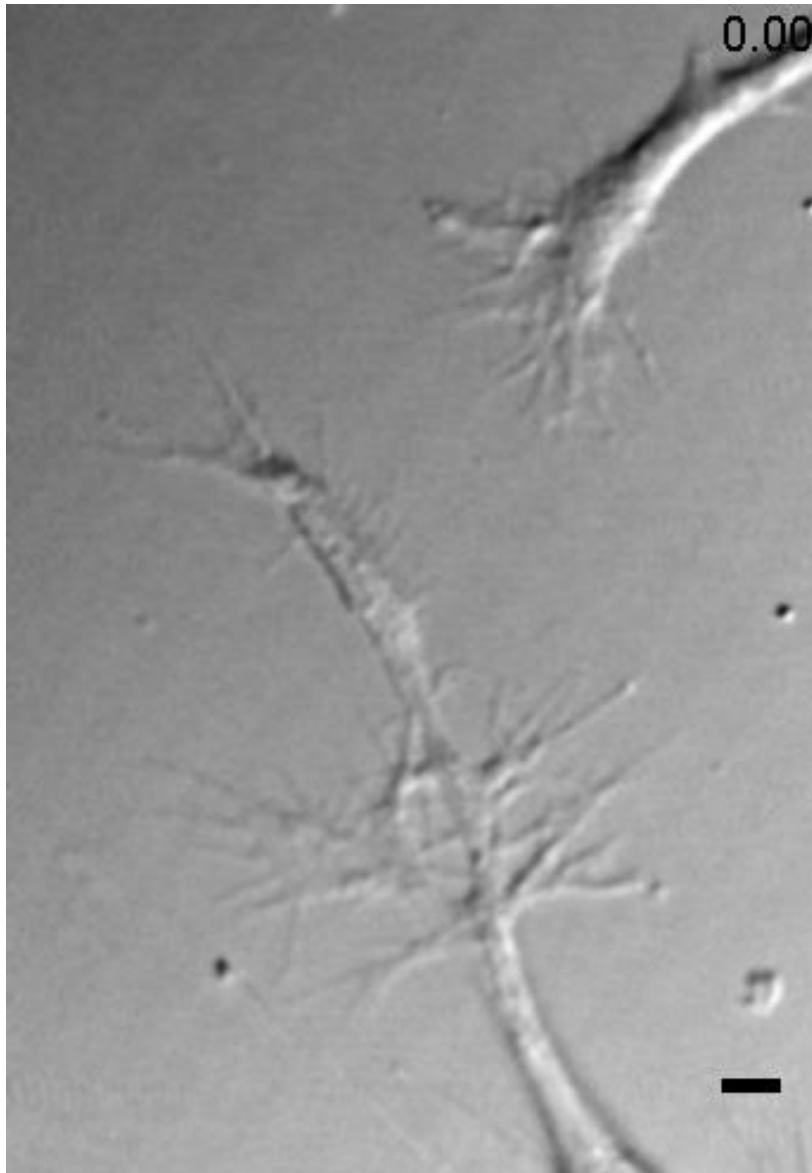


Chemorepellent

Human Neutrophil Cells, scale bar 10 μ m

Neuronal development

min :sec



Neurons release biochemical cues which are intercepted and interpreted by their nearby neurons.

➤ The **Growth Cone (GC)** searches and detects molecular signposts that are displayed by the nearby developing neuron and the environment.

➤ **GC** responds to these signs by advancing, pausing and turning until it reaches its proper destination

Scale Bar = 2 μm

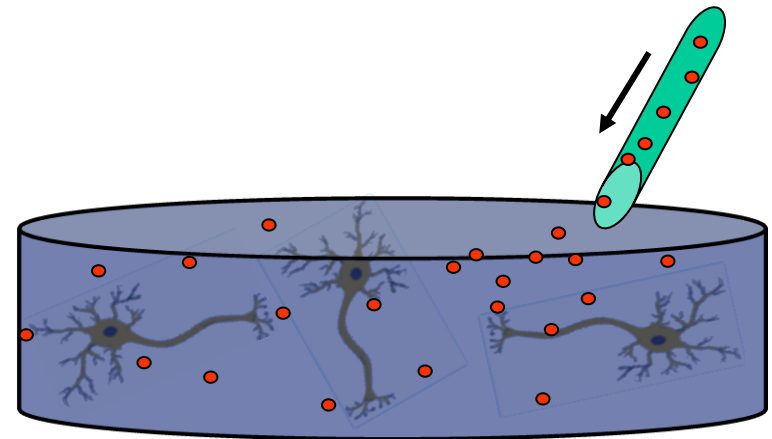
Acquisition freq= 1 frame every 5 s

GOAL:

Create physiological inspired experimental conditions !

E.g. **mimic one of the two neurons in the previous example by using functionalized microvectors carrying the stimuli and manipulate them to stimulate the neuron at specific sites !**

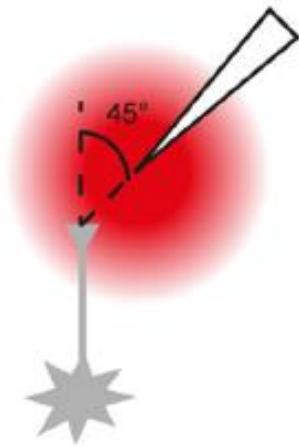
Classical bath administration of molecules rarely reflects the physiological conditions in which molecules are locally released at low concentrations, creating spatial and temporal gradients.



Assays for Localized Sources of Guidance Cues

I. Dupin *et al* (2013) J. Neurosci., 33: 17647

Micro-pipette based assay

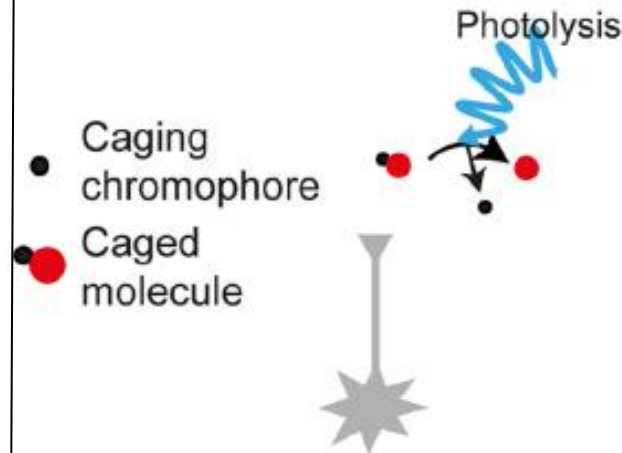


Pujic Z *et al*, (2008)

J Neurosci Methods 170:220

Gundersen RW, Barrett JN
(1979) Science 206:1079

Optical uncaging of caged molecule

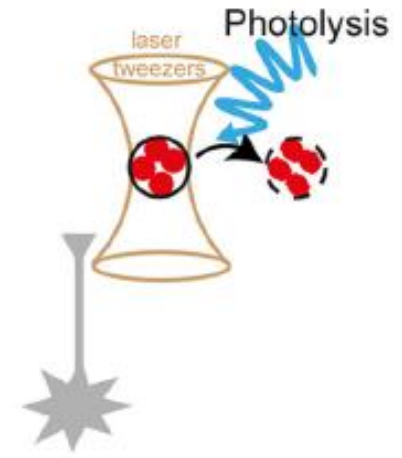


Ellis-Davies GC (2007)

Nat Methods 4:619

Gomez TM, Spitzer NC
(1999) Nature 397:350

Photorelease of encapsulated molecules



Pinato G *et al*, (2012)

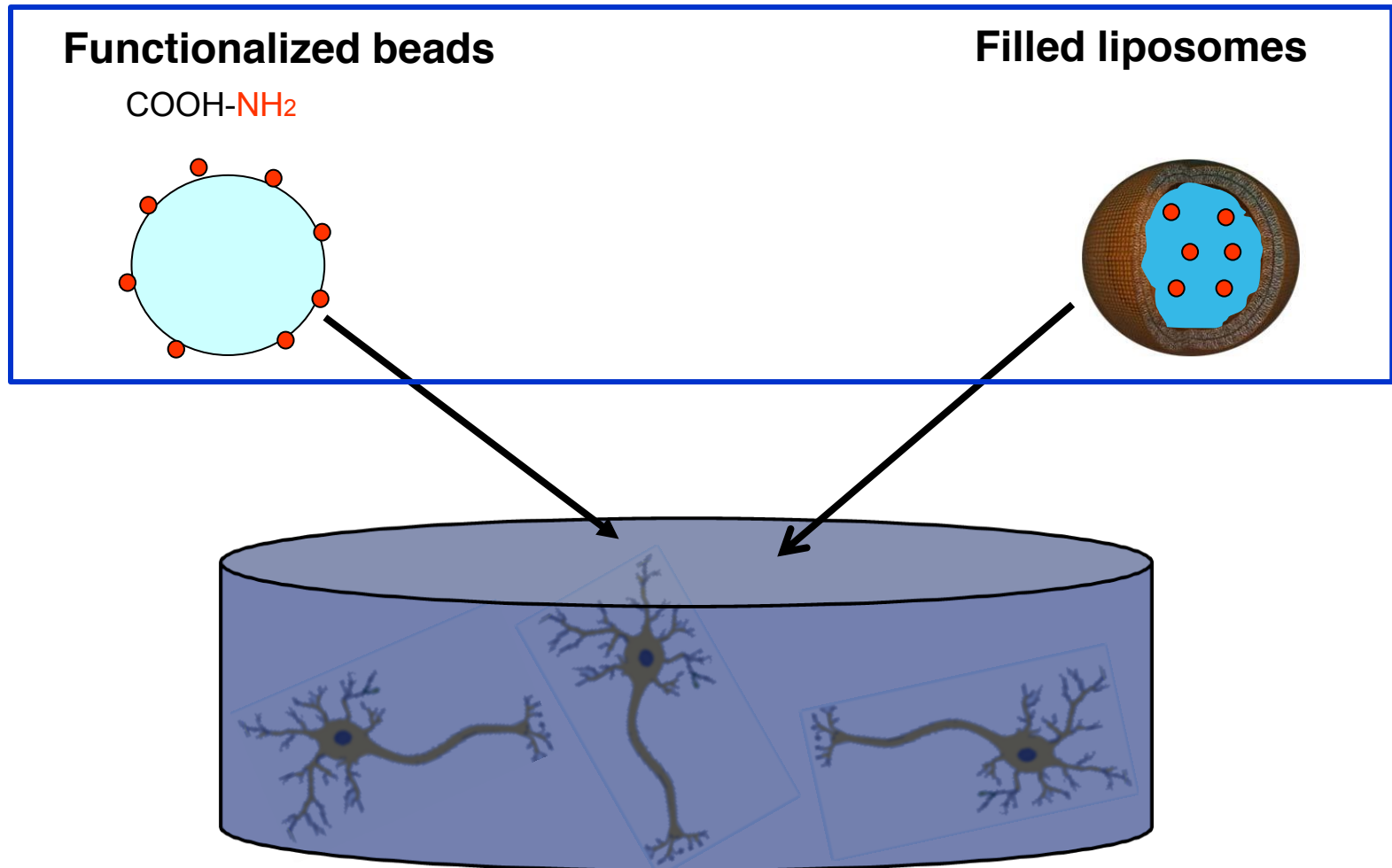
Sci Rep 2:675

Pinato G *et al*, (2011)
J Biomed Opt 16:095001

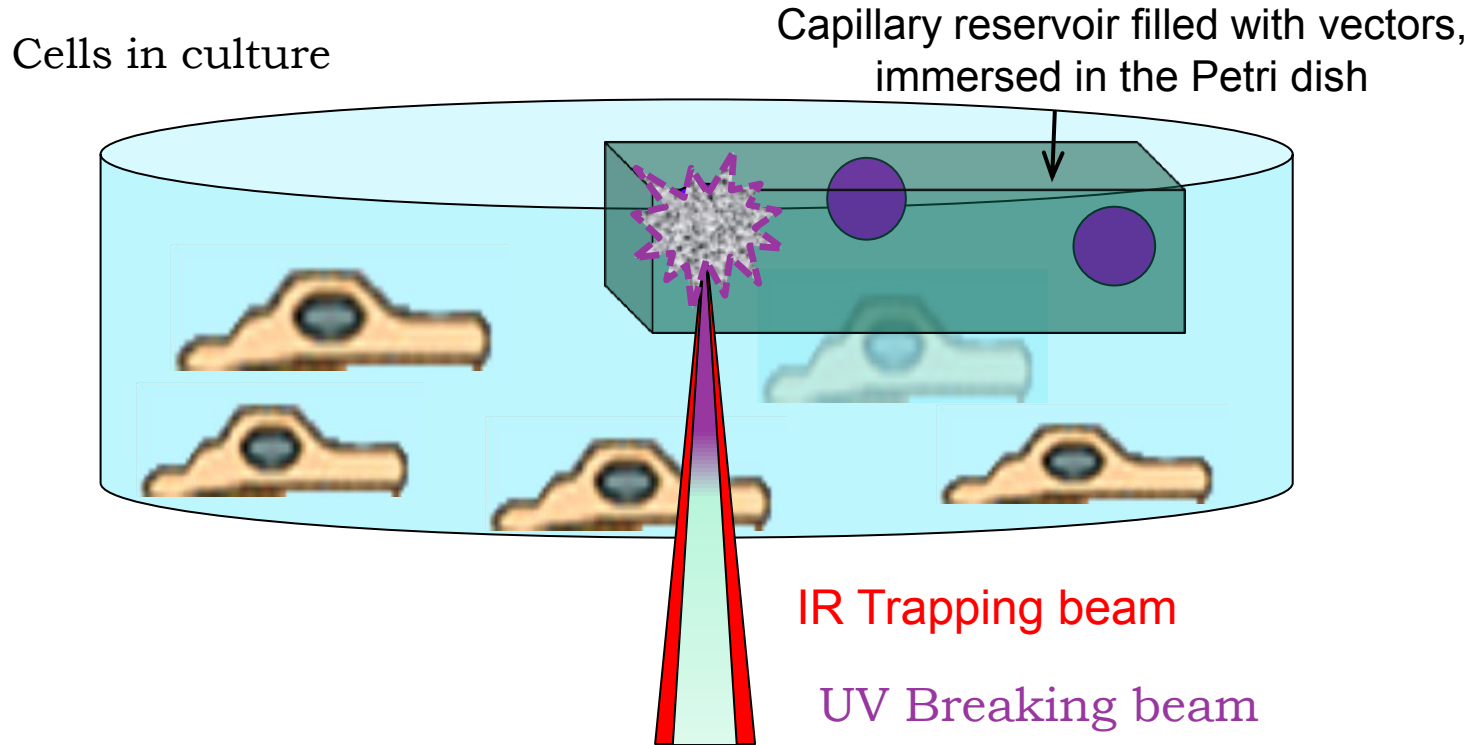
Sun B, Chiu DT (2003)
J Am Chem Soc 125:3702

Local stimulation using micro/nano vectors

Active molecules (e.g. guidance cues) are cross-linked to the surface of **microbeads** or encapsulated in **liposomes** (lipid vesicles)



Vector - Cell Positioning by Optical Manipulation



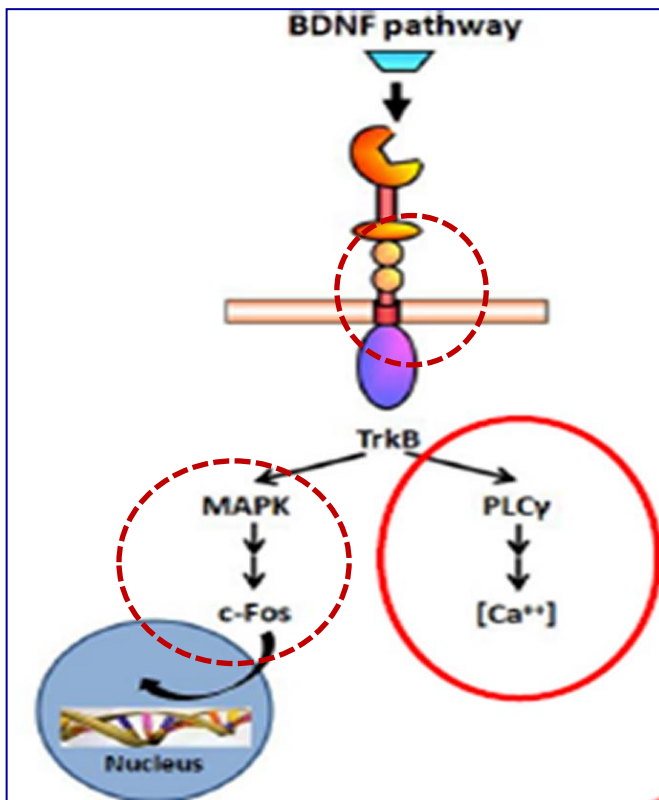
and delivered by:

- contact (beads or microspheres) – D'Este *et al* Integrative Biology (2011)
- photolysis of liposomes Sun B, Chiu DT, JACS (2003)

Example 1

Focal stimulation of specific neuronal compartments by optically manipulated microbeads coated with BDNF

Silica beads functionalized with COOH allow cross-linking of any type of proteins on bead surface (beads and kit are commercially available)



A single microbead positioned at about 30 μm from the cell body is enough to:

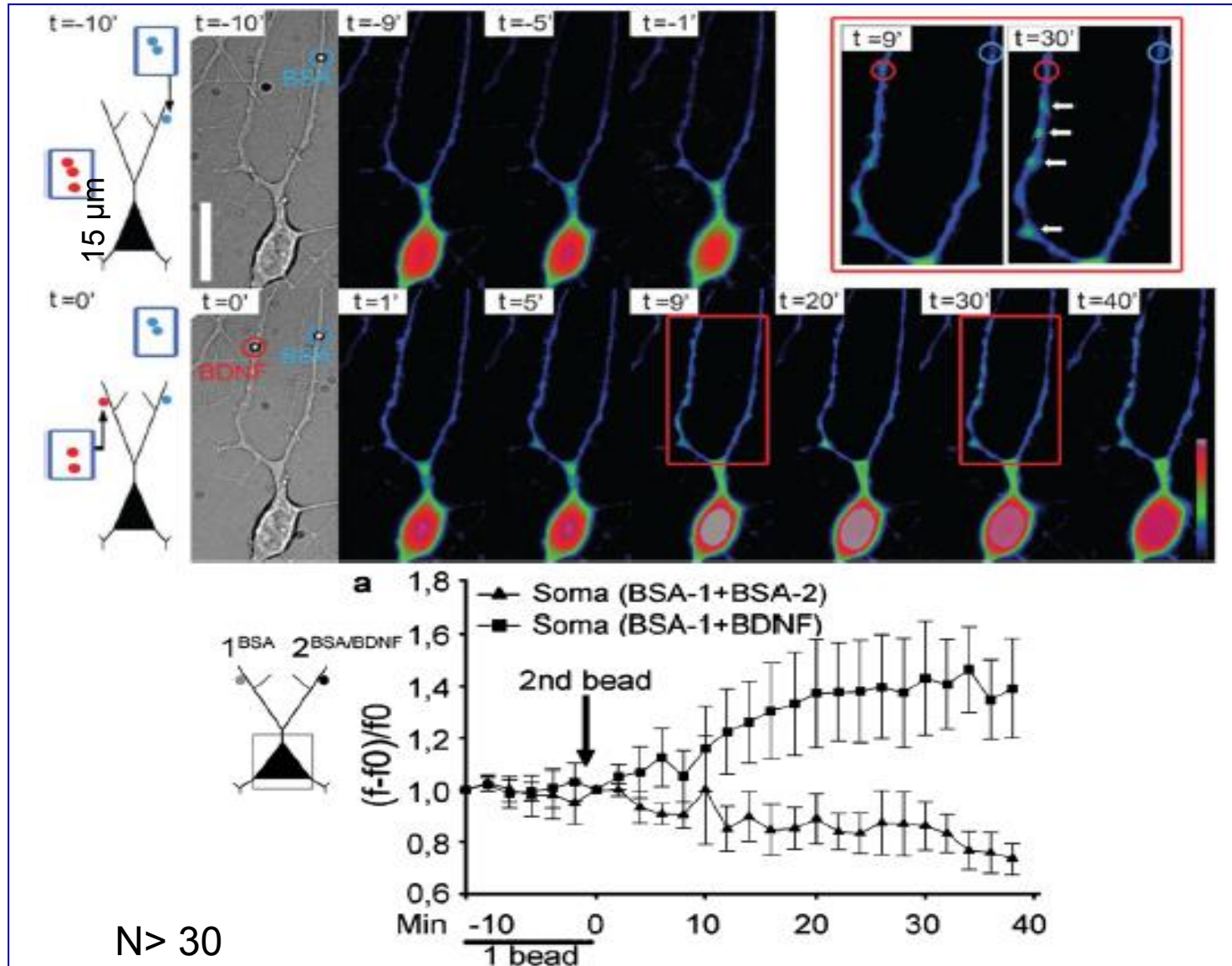
- increase Ca^{++} in the cell body and stimulated dendrite
- activate the BDNF receptor TrkB
- Induce c-Fos translocation in nucleus
- increase neurite motility

BDNF = Brain Derived Neurotrophic Factor

collaboration with the group of prof. **Enrico Tongiorgi**

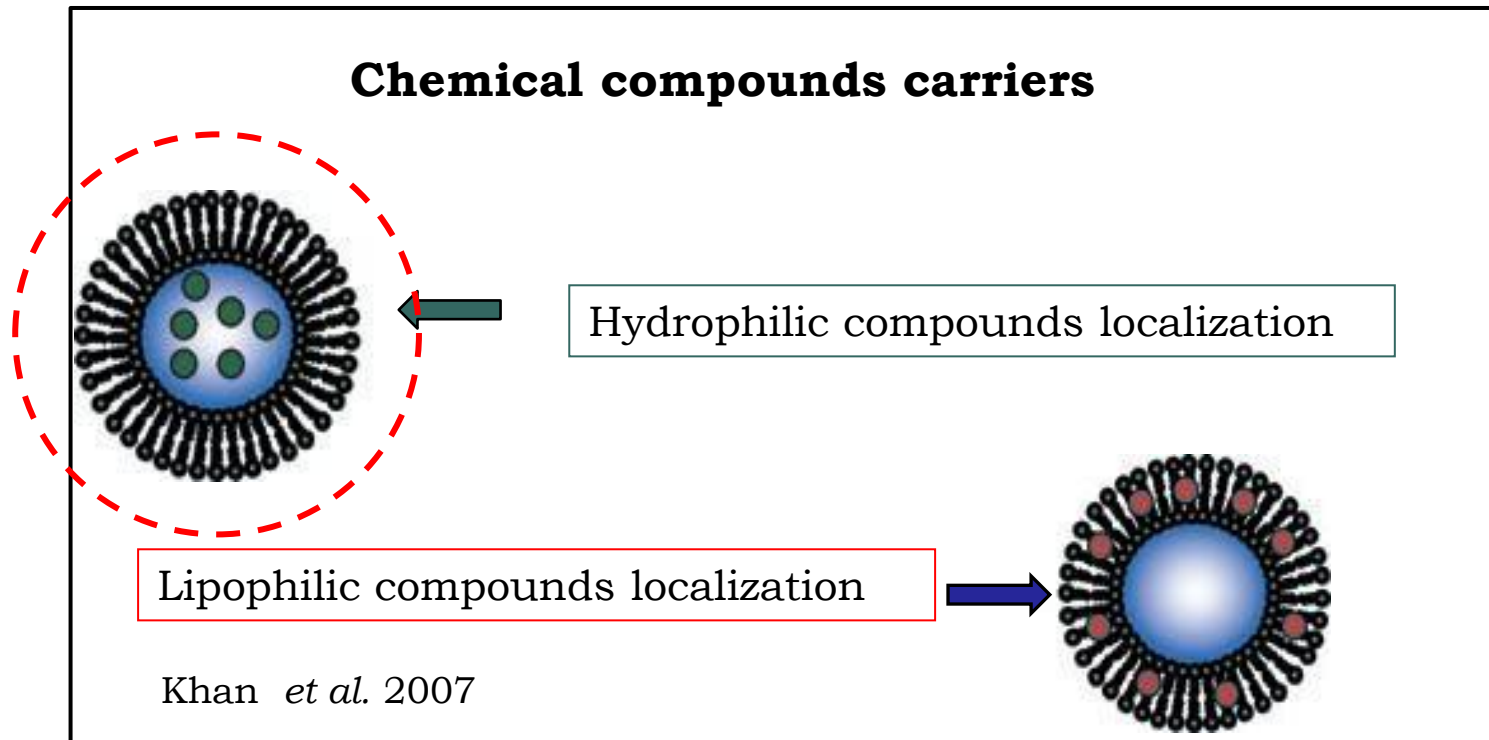
BRAIN Centre, University of Trieste

<http://www2.units.it/brain/>



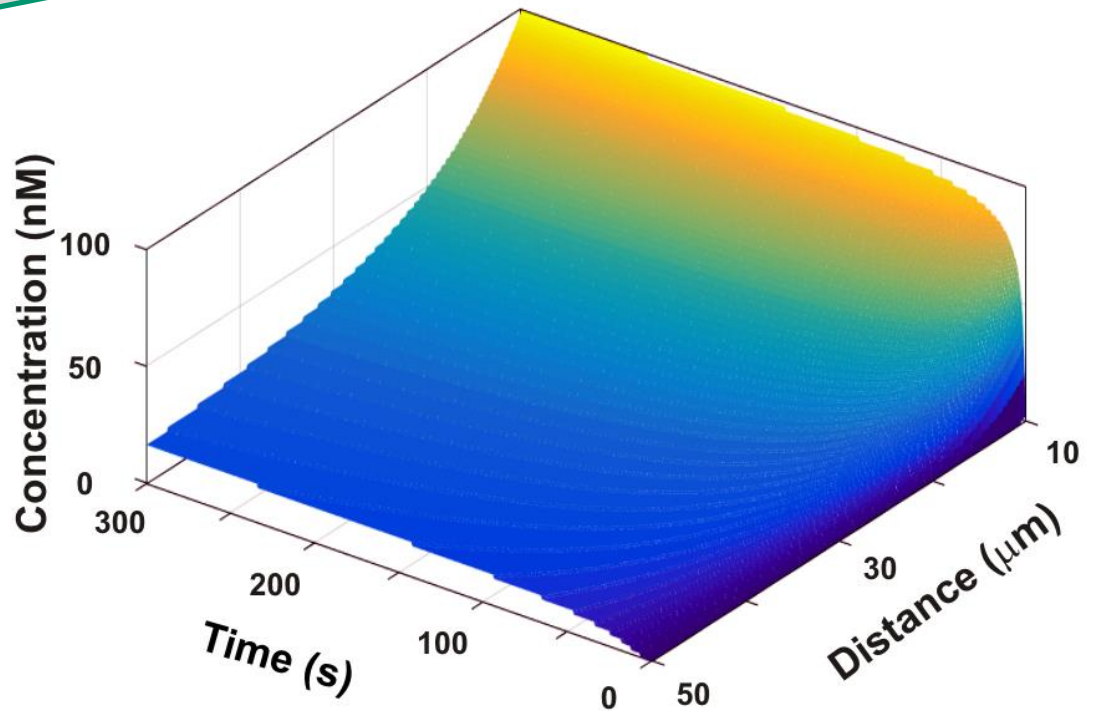
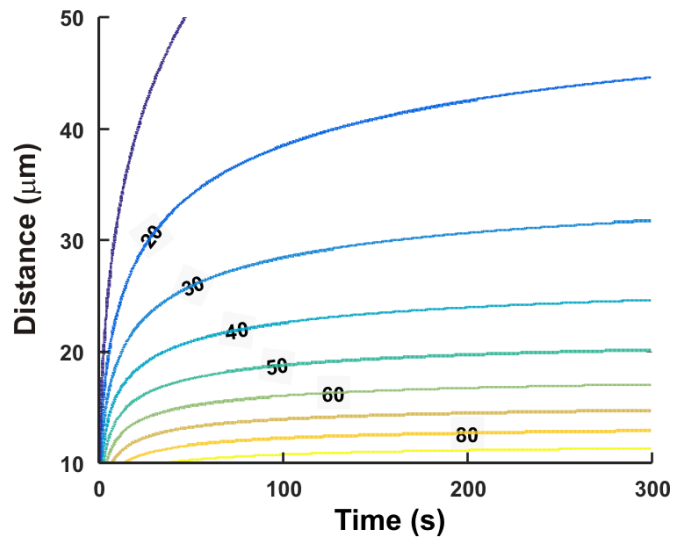
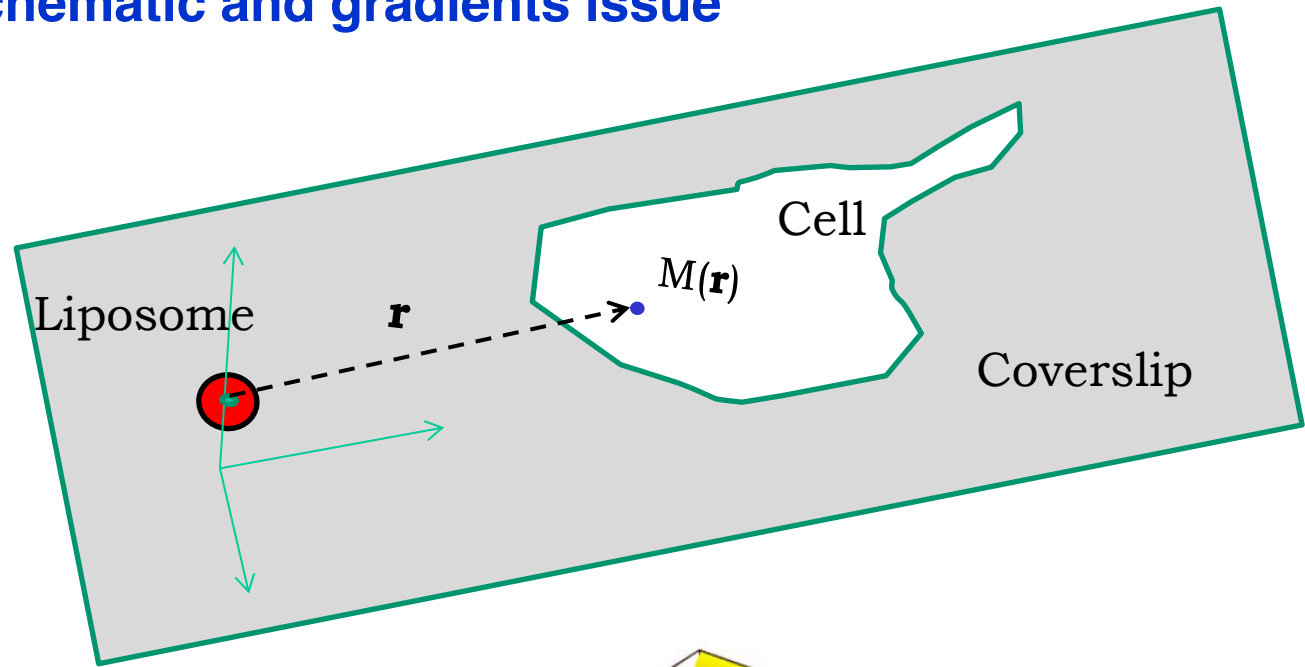
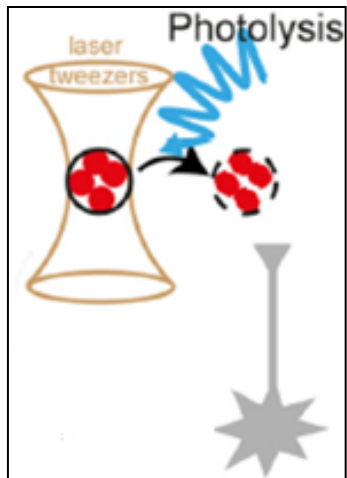
Using Liposomes as Vectors carrying active molecules

- ✓ Spherical vesicles from 50 nm to 50 μm
- ✓ Phospholipid bilayer membrane
- ✓ Aqueous core



A liposome of 1 μm diameter, filled with 1 nM solution contains 1 MOLECULE (mean value) !!!!!!!!!

Release Schematic and gradients issue



Example 2

Focal stimulation of hippocampal neurons by PrP^C

The **cellular prion protein (PrP^C)** is present in all cells, particularly in neurons. PrP^C has been associated with many cellular processes, including the **regulation of ion transport, neuritogenesis, cell survival, cell-to-cell interactions, cell signaling and synaptic transmission** (Linden *et al.* 2008).

Characterization of prion protein function by focal neurite stimulation

Ladan Amin¹, Xuan T. A. Nguyen¹, Irene Giulia Rolle¹, Elisa D'Este², Gabriele Giachin^{1,*}, Thanh Hoa Tran¹, Vladka Čurin Šerbec³, Dan Cojoc^{4,‡} and Giuseppe Legname^{1,‡}

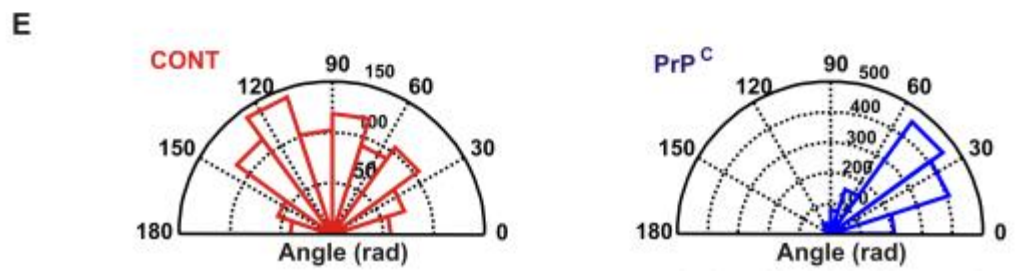
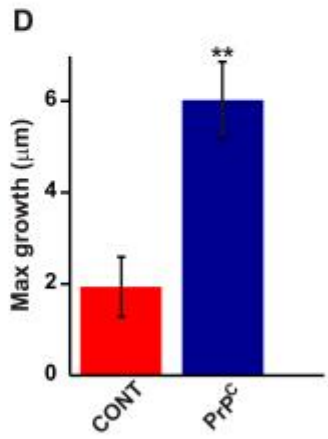
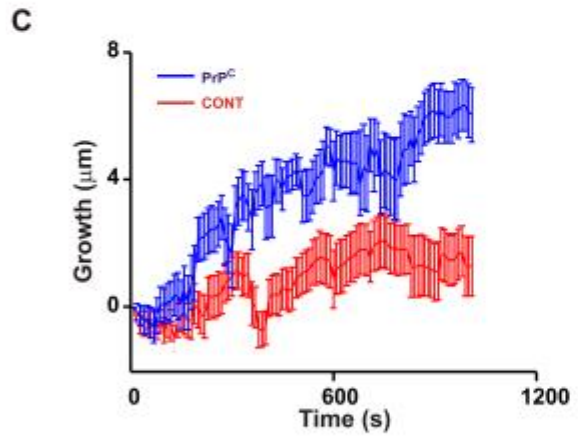
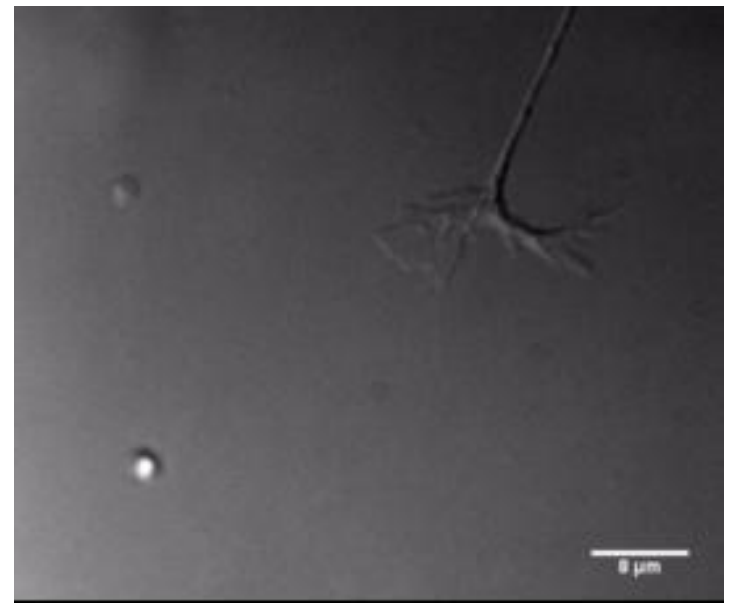
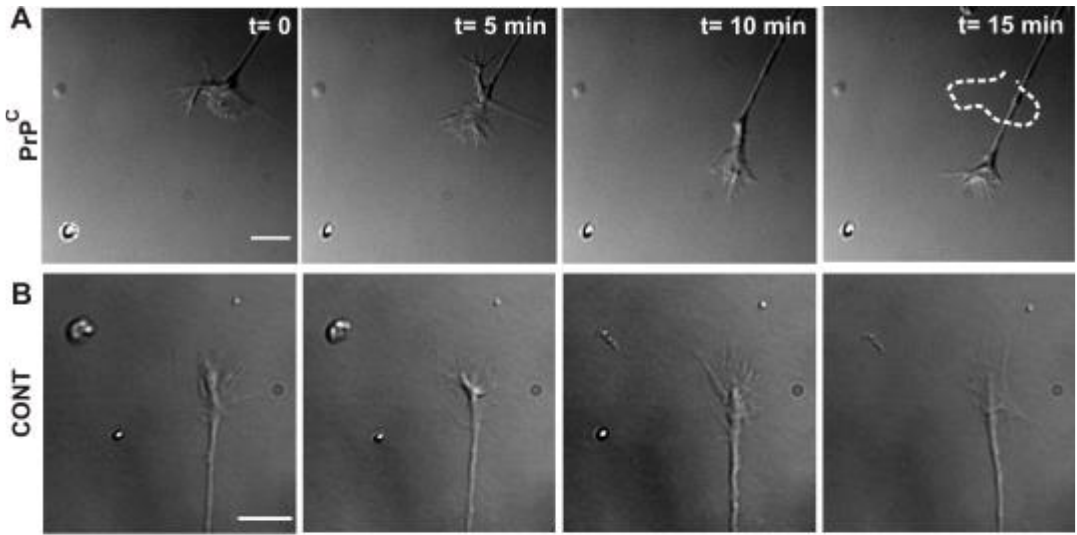
Journal of Cell Science (2016) 129, 3878-3891 doi:10.1242/jcs.183137

PrP^C encapsulated in lipid microvesicles or cross-linked to the surface of microbeads

We found:

- **recPrP^C works as a guidance molecule**
- membrane PrP^C is required for the extracellular PrP^C to bind (PrP^C might be the receptor of itself)
- full length PrP^C is required to have the guidance function
- concentration modulates the GC growth

Local delivery of controlled amount of MoPrP^C to neurons



Neurite growth is observed in 15 min after local stimulation.

Stimulation by bath administration induced this effect **after 24 h** incubation. (Kanaani 2005).

Control liposomes (BSA) do not induce growth or turning. .

PrpC KO neurons do not respond to the stimulation with PrPc

Example 3

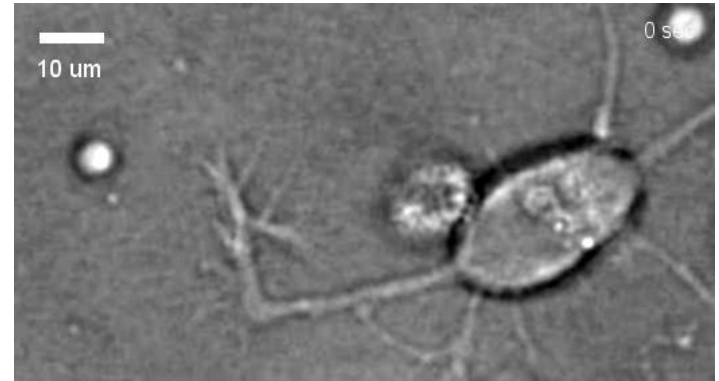
Focal stimulation of hippocampal neurons by guidance cues encapsulated in liposomes

Netrin-1

Growth Cone (GC) growing + turning

Proof of concept

Pinato G, *et al* J. Eur. Opt. Soc. –
Rap. Comm. 6, 11042, (2011)

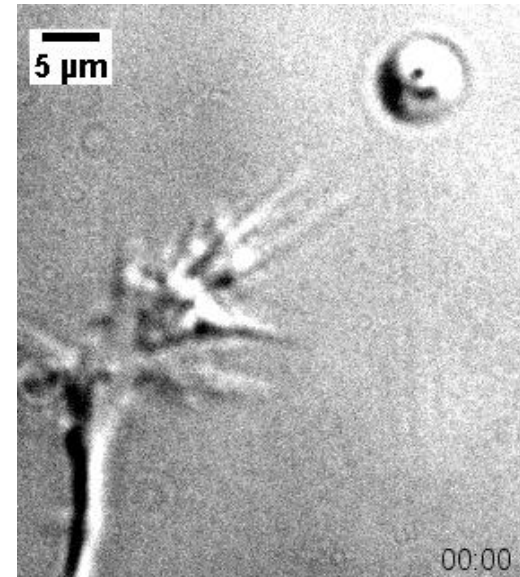


Sema3 – GC repelling and collapse

A more quantitative study:

Less than 5 Netrin-1 molecules initiate attraction but 200 Sema3A molecules are necessary for repulsion

Pinato G *et al* Sci. Rep. 2, 675 (2012)



Example 4

Signal transduction dynamics

Local stimulation + FRET microscopy

Stimulating the GC with coated beads and liposomes filled with **Sem3A**.

- Signal transduction is a very complex mechanism, regulated by many “players” among which the GTPases: Rac1, RhoA and Cdc42, which act together to control cytoskeleton dynamics. [Machacek, M, ...& Danuser, G, Nature 461, 99 (2009)].
- **Goal:** visualize the RhoA and Cdc42 activation and their dynamics upon local stimulation with Sem3A
- **Study case:** Ng 108-15 neuroblastoma cells

Project in collaboration with the group of prof. **Vincent Torre**
Neurobiology Sector, **SISSA, Trieste**

Sem3A = Semaphorin 3A

is a guidance (repellant) molecule released by neurons during their differentiation

GTPase = hydrolyse enzymes that can bind and hydrolyze guanosine triphosphate (GTP)

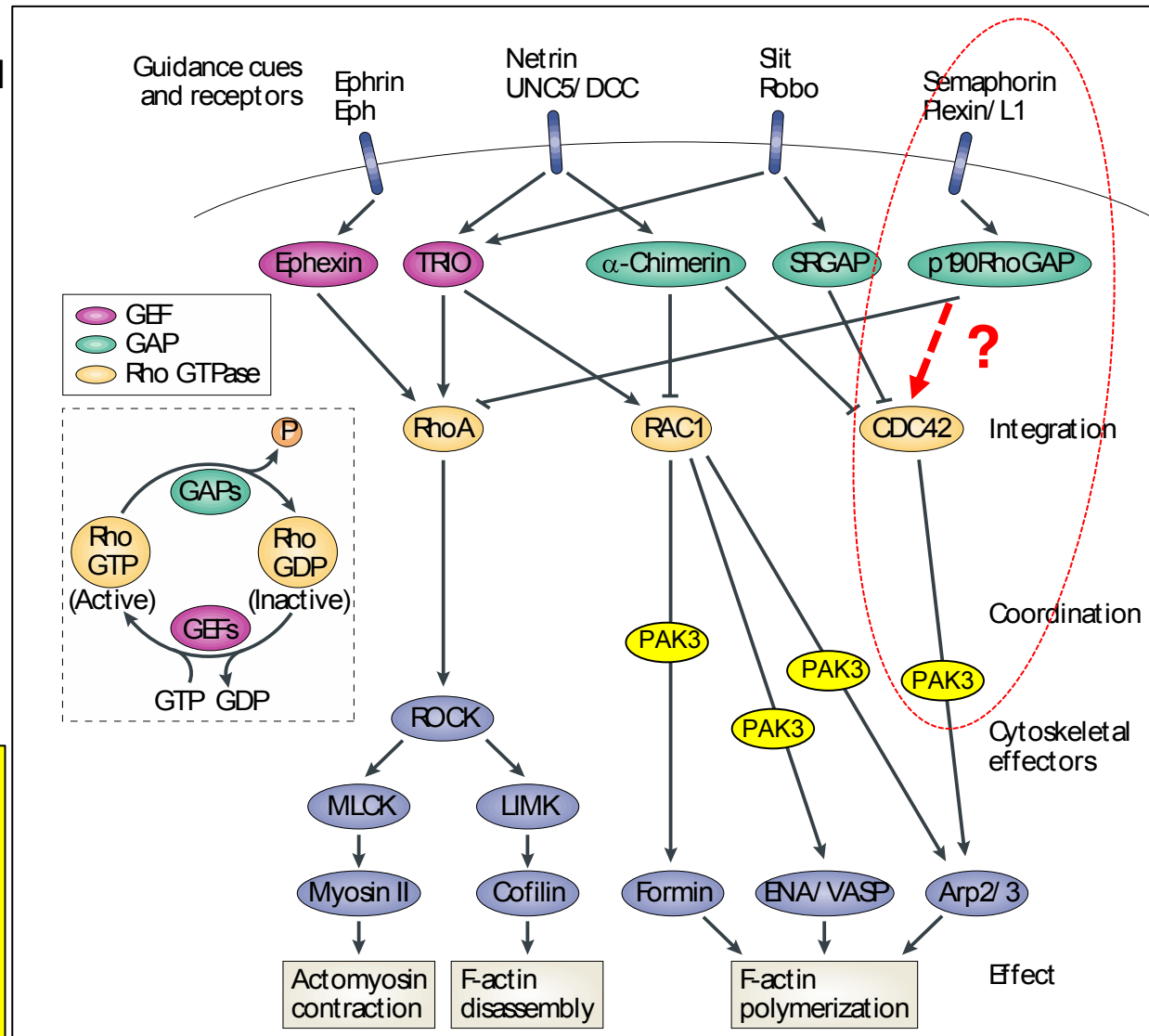
Guidance cues signaling pathways

RhoGTPases are signalling nodes that couple upstream directional cues and downstream cytoskeletal rearrangements to either enhance actin polymerization for protrusion or promote disassembly and actomyosin contraction for retraction.

GTPases are a large family of hydrolase enzymes that can bind and hydrolyze guanosine triphosphate (GTP).

PAK proteins are critical effectors that link Rho GTPases to cytoskeleton reorganization and nuclear signaling.

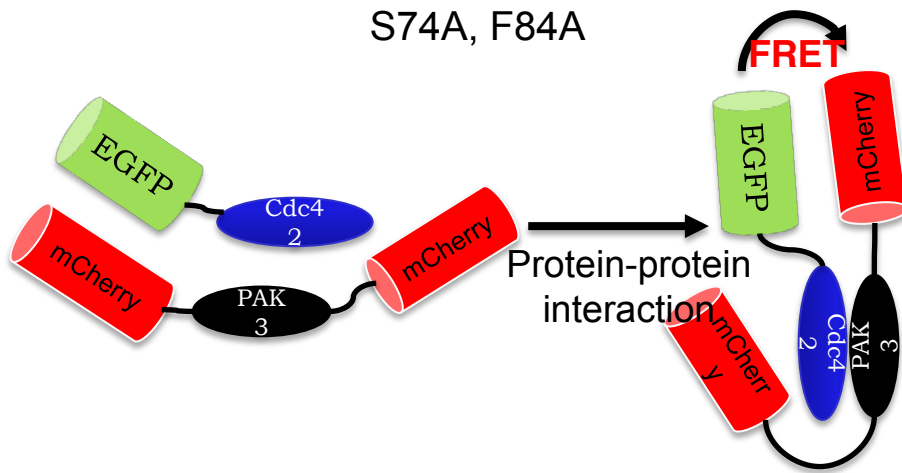
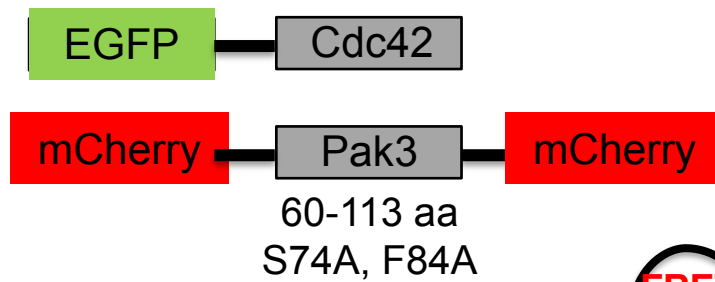
They serve as targets for the small GTP binding proteins Cdc42 and RAC



FRET probes

Inter - Molecular

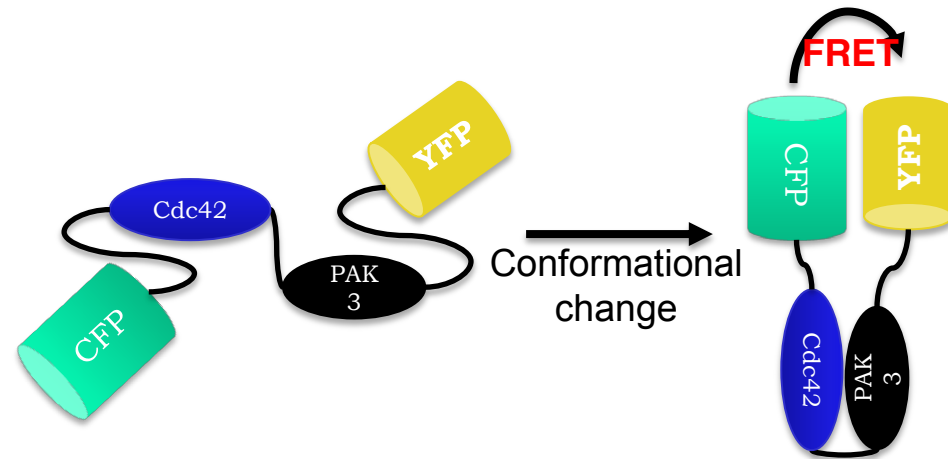
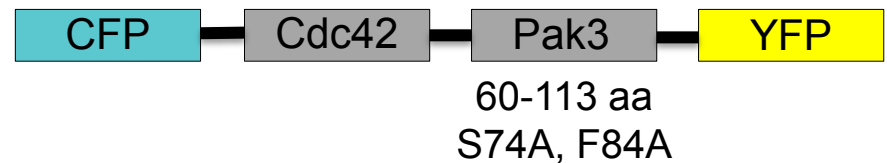
Cdc42 FRET sensor



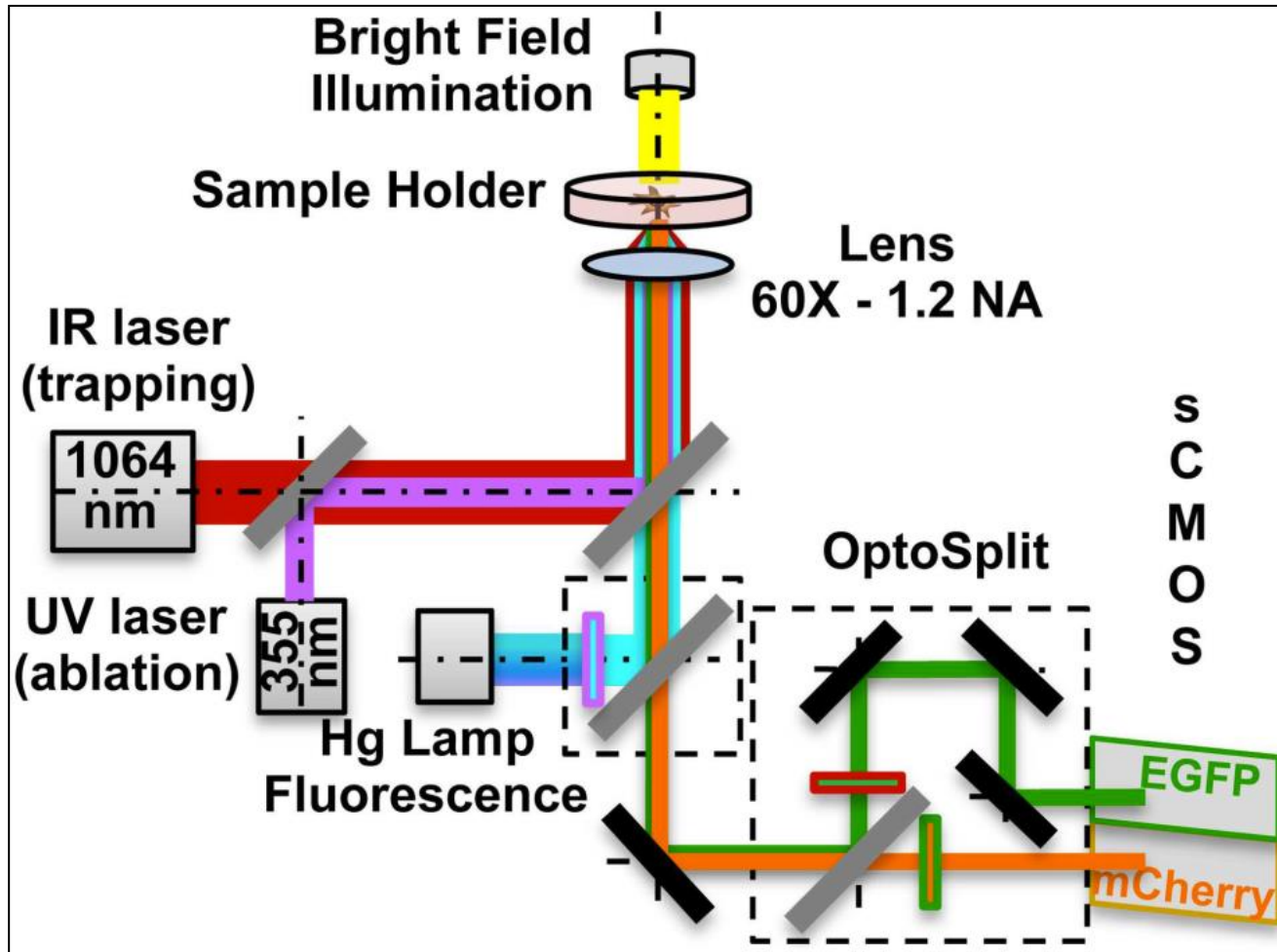
- Suitable for Protein-Protein interaction studies;
- Fluorophore Stoichiometry uncertain.
- Sensitized FRET.

Intra - Molecular

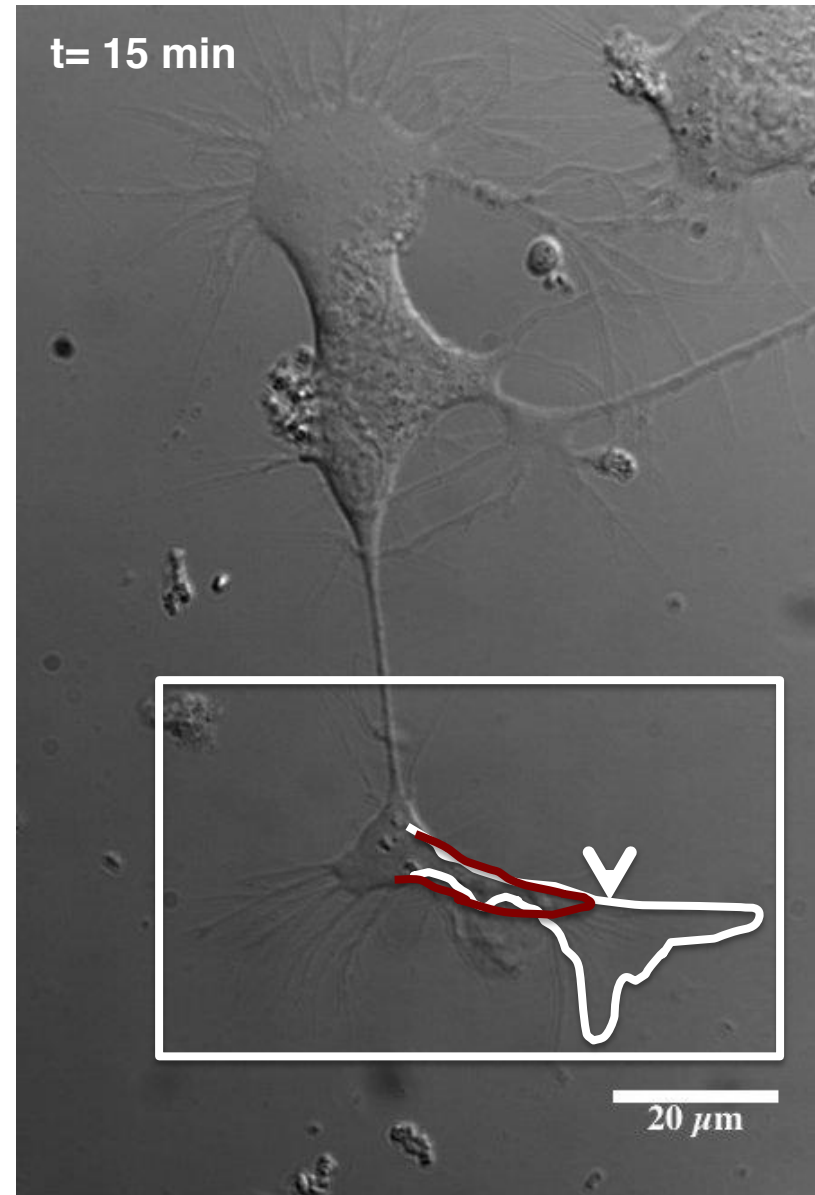
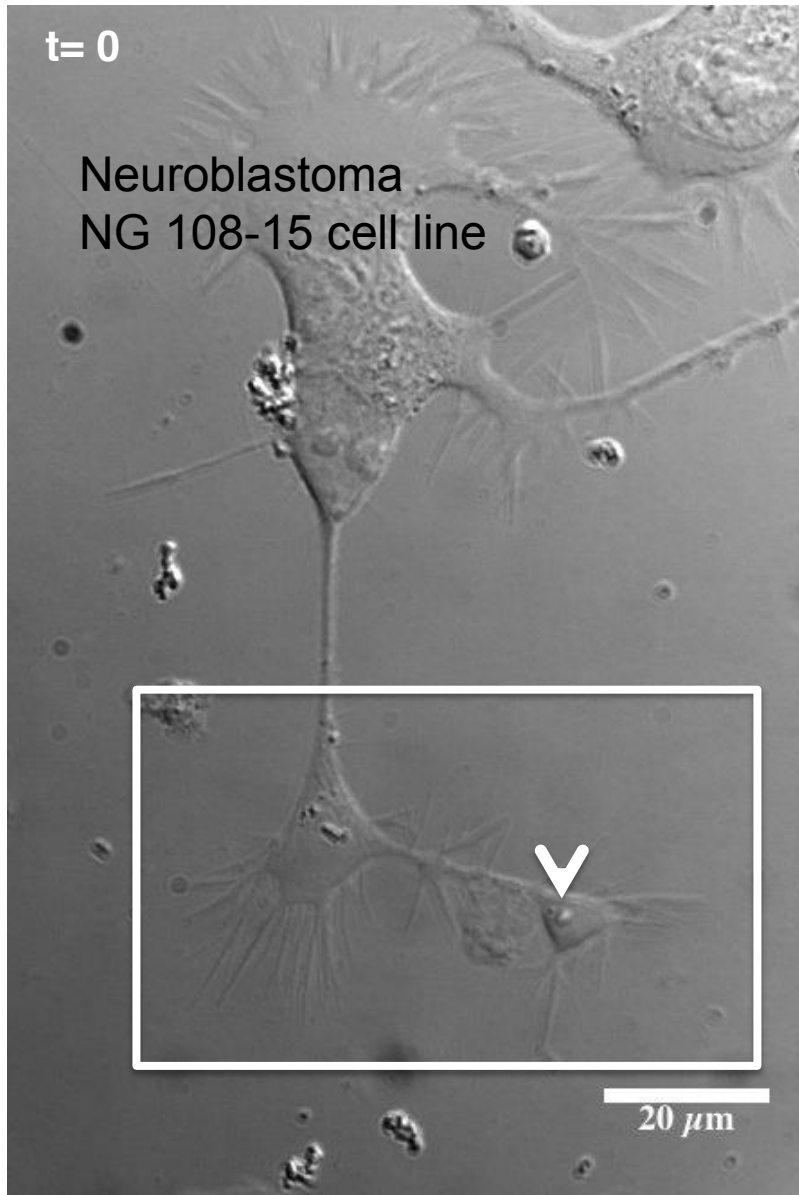
“Raichu” Cdc42 FRET sensor



- Suitable for Protein activation studies;
- Fluorophore Stoichiometry 1:1;
- Ratiometric FRET



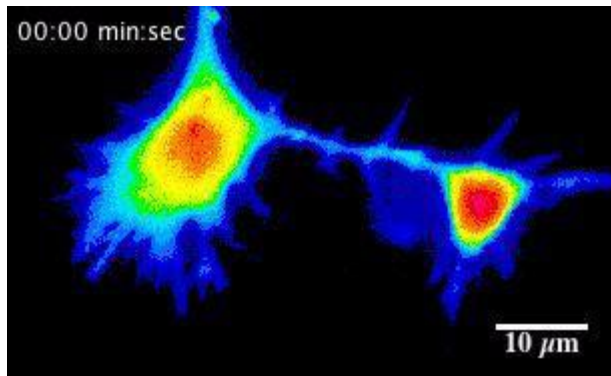
Local stimulation: SemA3 bead positioned on the GC and kept in contact for 30⁰¹s



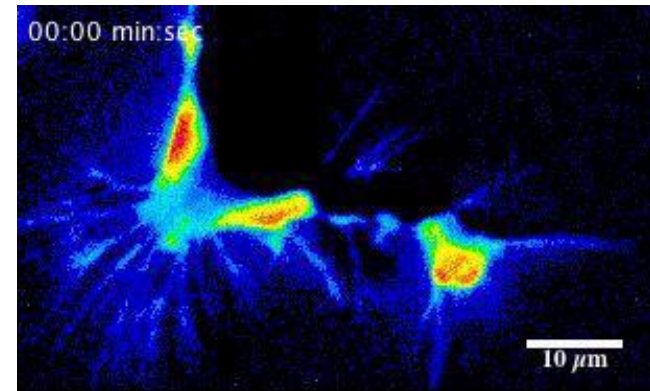
After 30 s the trap is switched off and the bead released.
The GC retracts about 15 μm after t= 15 min

Dynamics of the Cdc42 activation

using a Cdc42 FRET probe based on mEGFP and mCherry

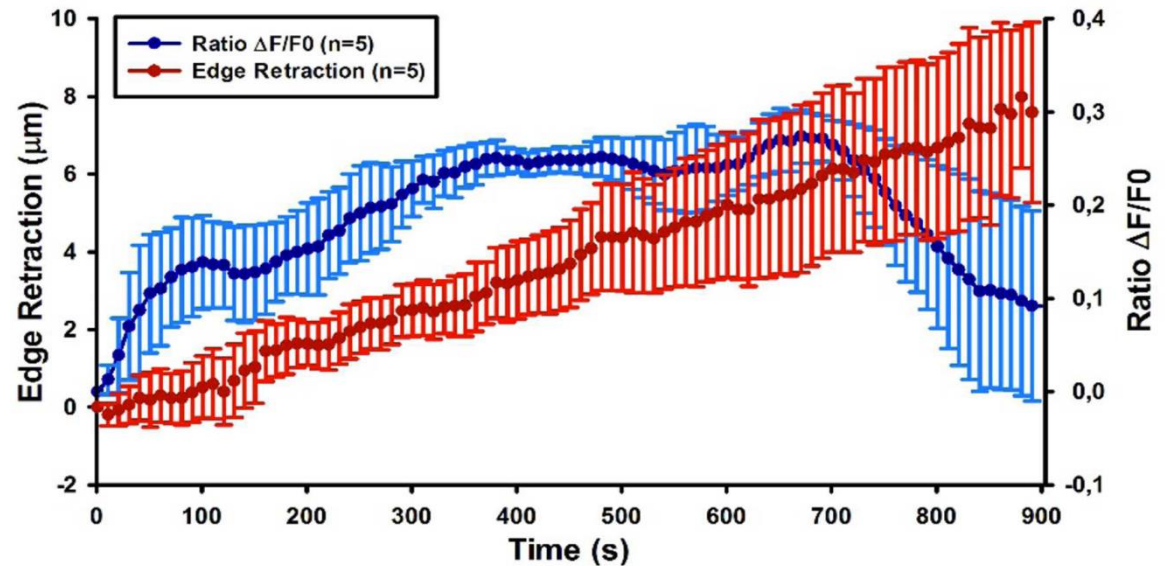
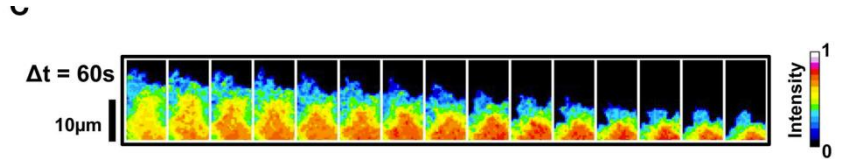
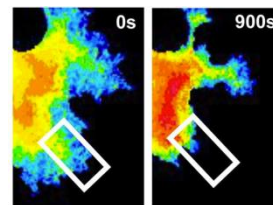
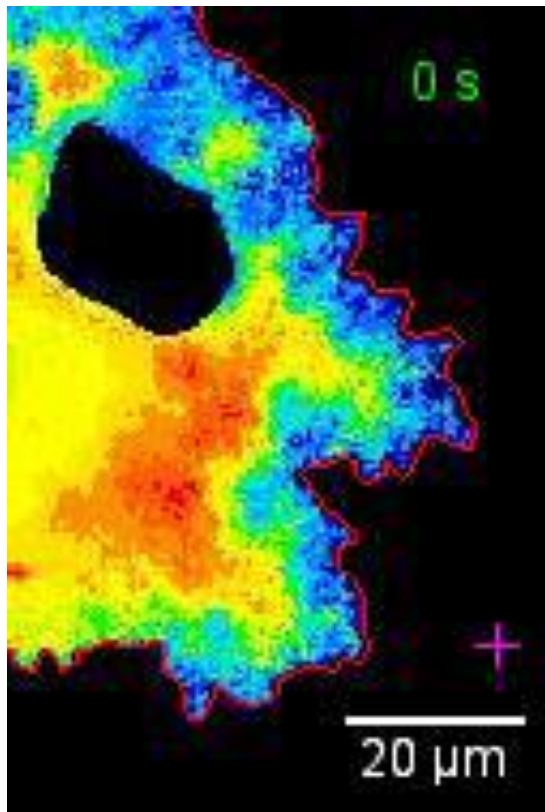
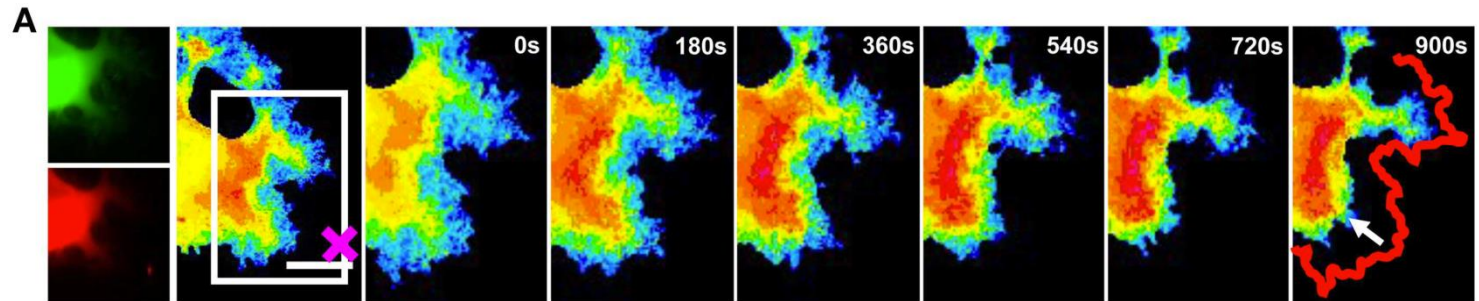


Spontaneous FRET
before stimulation
(Control)

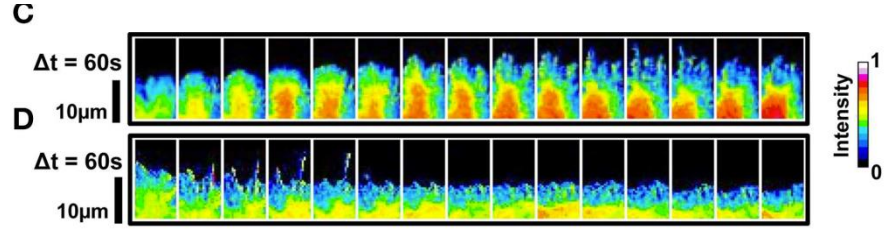
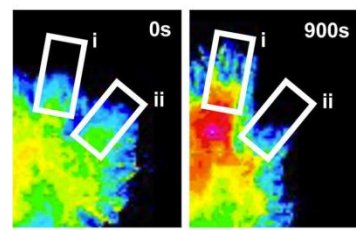
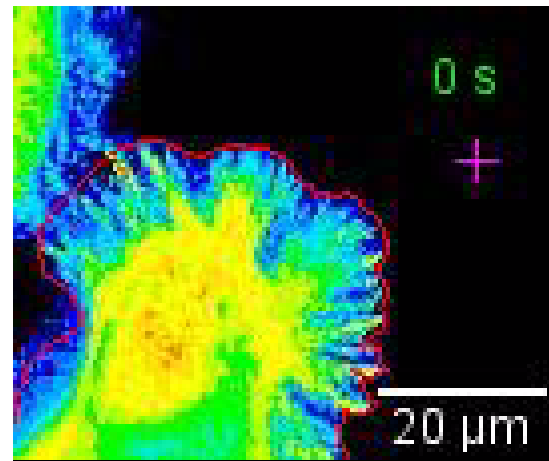
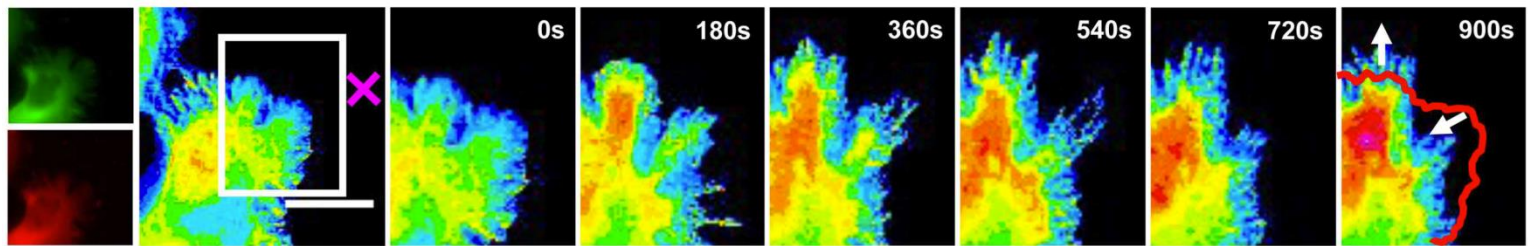


FRET after
stimulation with
SemA3 bead

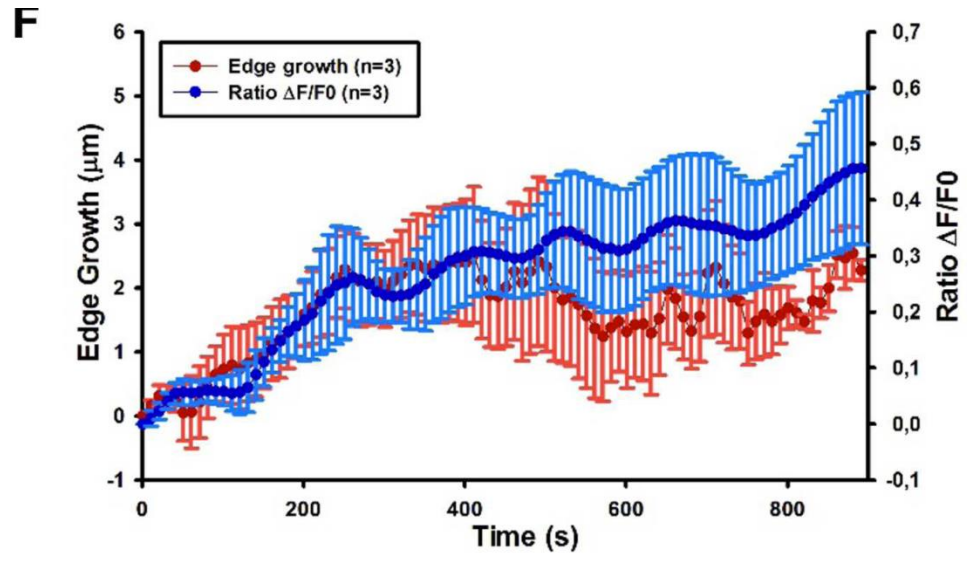
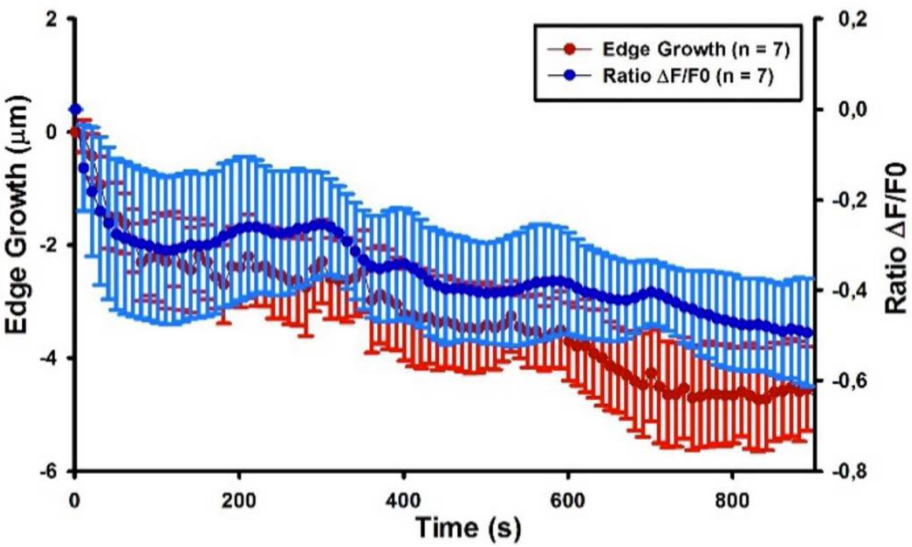
RhoA dynamics upon local delivery of Sema3A from liposome



CdC42 dynamics upon local delivery of Sema3A from liposome



Iseppon F *et al* Frontiers Cell. Neuroscience, 2015





EV from microglial cells
on a microglia cell.

- EV are circular membrane structures released by most cells which represent highly conserved mediators of intercellular communication.
- EV carry proteins, lipids and genetic materials and transfer these cellular components between cells by different mechanisms, such as endocytosis, macropinocytosis or fusion.
- Temporal and spatial dynamics of vesicle-cell interaction still remain largely unexplored

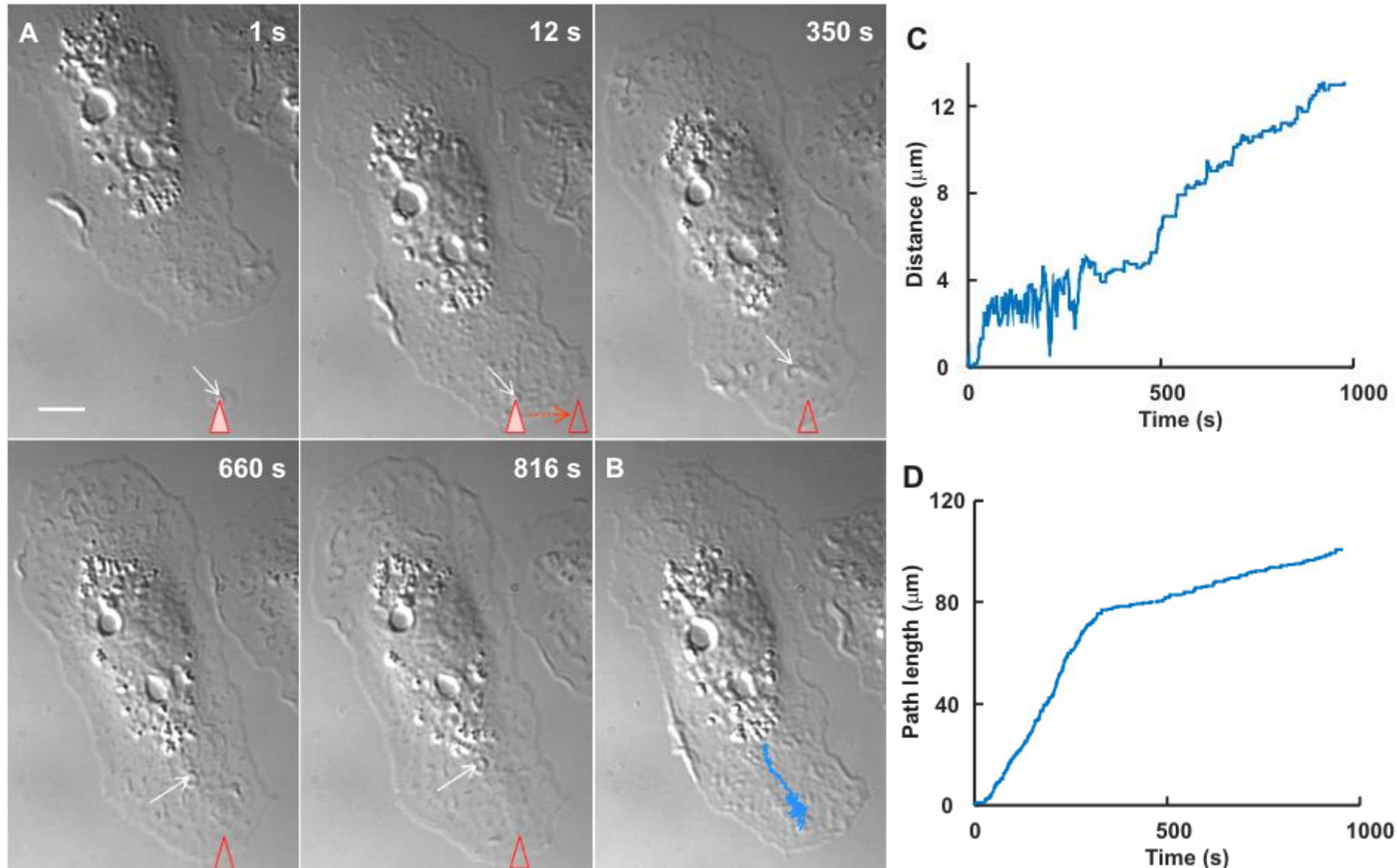
Collaboration:

Claudia Verderio - CNR-Institute of Neuroscience Milan

Roberto Furlan – San Raffaele, Milan

Giuseppe Legname – SISSA, Trieste

Interaction between single microglial EVs and microglia: adhesion and transport



Optical Tweezers Manipulation (OTM) technology allows to :

- **measure forces exerted by cells**
- **apply forces to cells and measure stiffness**
- **handle vectors carrying active molecules to stimulate locally cells**
 - local stimulation by OM coated beads is simple and extremely flexible; any type of protein can be cross-linked on surface
 - filled liposomes are flexible as well and the released molecules can interact freely with the cell

OMT is compatible with Optical microscopy imaging –

See what you manipulate and manipulate what you see !

F. Difato, G. Pinato, D. Cojoc, "Cell signaling experiments driven by optical manipulation",
Int. J. Mol. Sci. 14, 8963 (2013) Review

Acknowledgments

OM - Lab CNR - IOM

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Leonardo Venturelli
Fatou Ndoeye (ICTP)
Elisa D'Este
Enrico Ferrari
Valeria Garbin

SISSA

Vincent Torre
Giuseppe Legname
Luisa Napoletano
Gabriele Giachin
Jelena Ban
Francesco Difato
Lin Thuy Lien

ICTP

Joseph Niemela

University of Trieste

Serena Bonin
Enrico Tongiorgi
Gabriele Baj

CNR – IN Milano

Claudia Verderio
Ilaria Prada

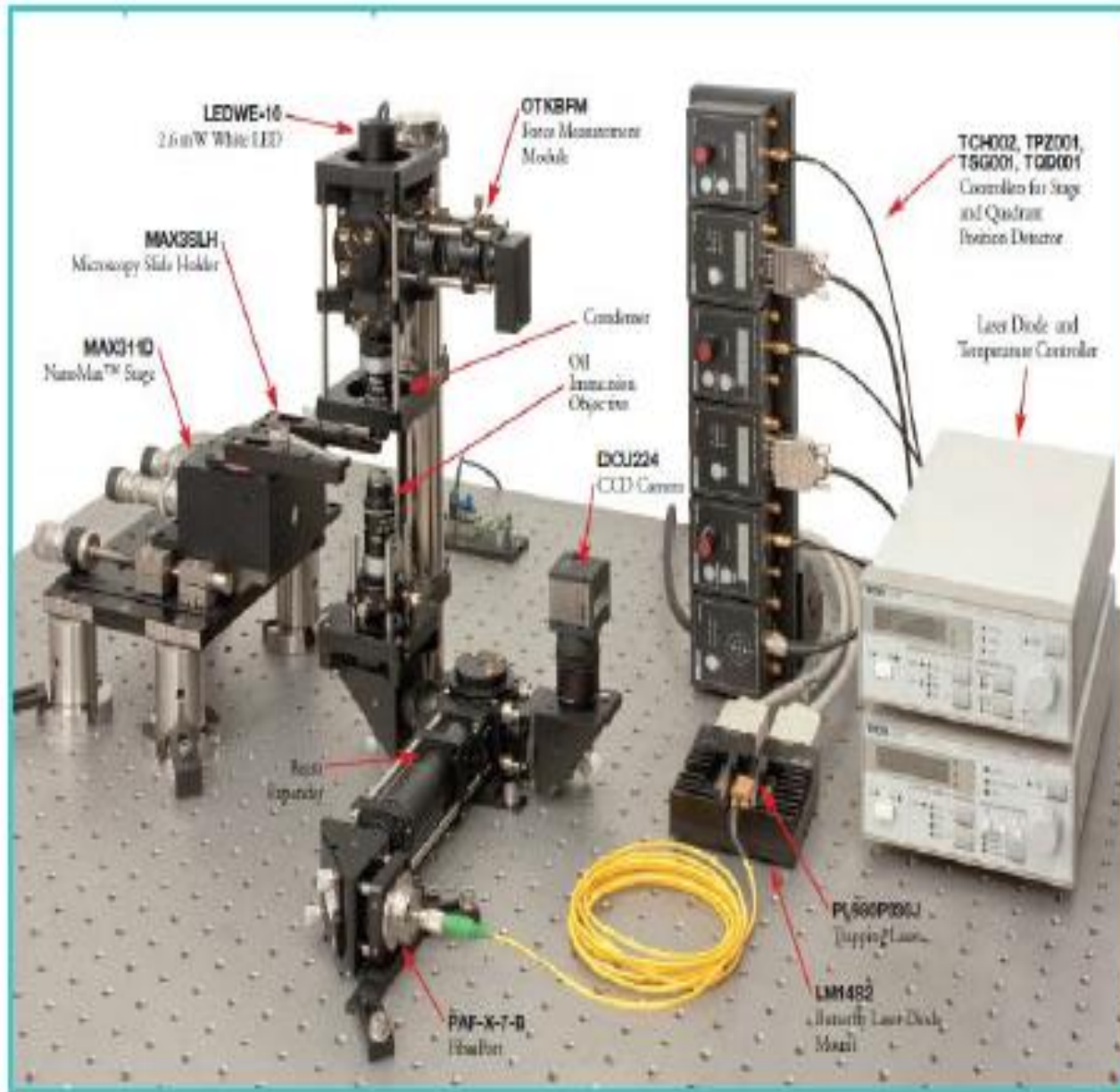
FR San Raffaele Milano

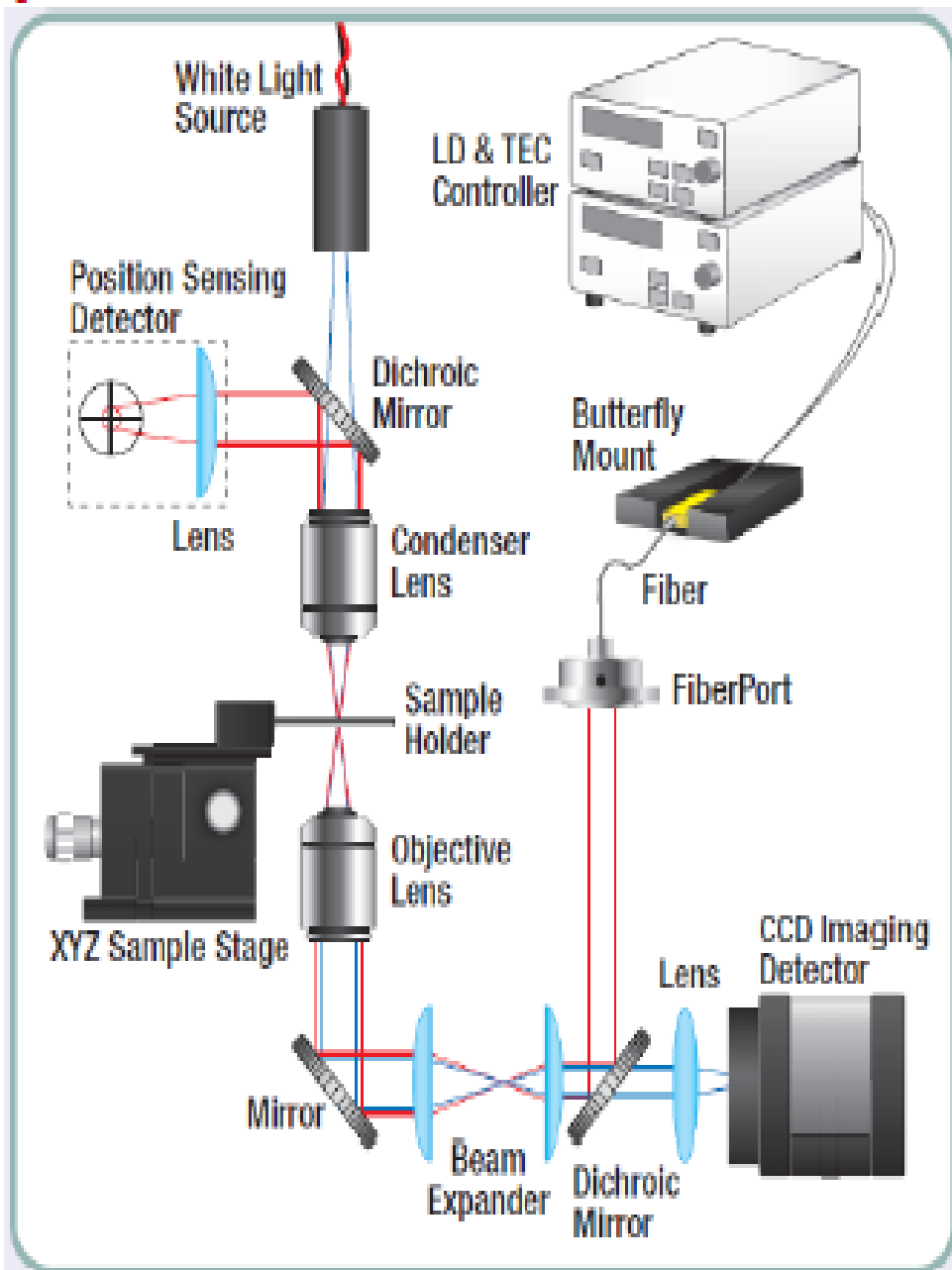
Roberto Furlan

www.iom.cnr.it/optical-manipulation-laboratory
dancojoc.wix.com/om-lab

“Progress in science depends on new techniques, new discoveries,
and new ideas, probably in that order”, Sydney Brenner
(Nobel Prize in Physiology or Medicine 2002)

Experiments Optical Tweezers Hands on - modular setup Thorlabs [1]





two modules:

1. trapping and manipulation module
2. position detection and force measurement module

Important feature of this kit : modular design --> implement easily additional modules as fluorescence imaging, Raman spectroscopy, laser dissection, and laser beam steering.

This system is a result of the design and development work of the prof. M. Lang group at the Massachusetts Institute of Technology (MIT), Boston/USA. A more detailed description of the setup and experiments that can be performed with it can be found in reference [2].

[2] Appleyard et al, "Optical tweezers for undergraduates", Am. J. of Physics (2007), [http://www.vanderbilt.edu/langlab/Publications/Appleyard-etal\(2007\).pdf](http://www.vanderbilt.edu/langlab/Publications/Appleyard-etal(2007).pdf)

Trapping module:

- 975 nm trapping laser source (stabilized single mode laser diode), 330 mW Power (Max), power at optical trap is about 40 % of Fiber Output
- trapping objective Nikon 100 X, Numerical Aperture NA 1.25, oil immersion, depth of focus 1 μm , spot size 0.6 μm (min), Working Distance WD 0.23 mm, transmission 380-1100 nm, recommended cover glass thickness 0.17 mm
- condenser objective Nikon 10X, NA 0.25, WD 7 mm, transmission 380 – 1100 nm - XYZ sample stage: 4 mm of manual travel in combination with 20 μm of piezo actuation and a resolution of 20 nm; using the internal strain gauges for positional feedback, 5 nm resolution can be achieved; the stage is mounted on a single-axis, long-travel translation stage, which allows scanning over a range of 50 mm, facilitating loading/uploading of the sample cel.

Position detection and force measurement module:

- position detection based on interference pattern in the back focal plane of the condenser, interference formed by trapping laser beam scattered by the trapped bead (probe); Quadrant Position Detector (QPD) detects the pattern displacement sampling it at high frequency rate (100 kHz) - position calibration capability with 5 nm resolution; trap stiffness calibration using different methods as: Power Spectral Density (PSD), Stokes drag and Equipartition theorem (for details of these methods see for instance references [2], [3]); determining the trap stiffness and knowing that the bead probe near the equilibrium position of the trap, behaves as in a Hooke potential well (linear spring with stiffness k), force measurement of the probe interacting with a sample (e.g. cell) can be calculated measuring the displacement x of the bead: $F=kx$; the trap stiffness depends of the power of the trapping laser and of the material and geometry of the trapped probe; the stiffness range is 10^{-4} –1 pN/nm, which allows to measure forces in pN range with resolution of tens of fN; the stiffness is 2-3 order of magnitudes smaller than that of the cantilever stiffness in AFM
- MATLAB-based graphical user interface (GUI) – open access code available from Thorlabs-MIT.

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Some hystorical notes

2003 - OT lab at INFM-Synchrotron Trieste, ICTP-STEP PhD program

2005- many requests to visist and work with the only OT setup we had

2009 - with Joe Niemela we planned to build a simple setup transportable for demo

2010 - Francesco Difato - IIT Genova - OT tweezers in a box --> workshop Ghana

2012 - thanks to ICTP and SPIE --> OT Thorlabs setup

2013 - two demos: ICTP Trieste, Univ. N. Gorica Vipava Slovenia

2013 - PhD students, master, visitors worked on it, mainly within ICTP programs

Fatou NDOYE, Senegal (ICTP- STEP program, defended 2017)

Muhammad Sulaiman YUSAFZAI, Pakistan (Univ Trieste PhD Nanoechnology, ICTP - TRIL 2016-2017)

Jose J. SUAREZ-VARGAS, Venezuela (ICTP- associate)

Humberto CABRERA, Venezuela (ICTP- associate)

Ali Reza MORADI , Iran (ICTP associate)

and of course Joe Niemela