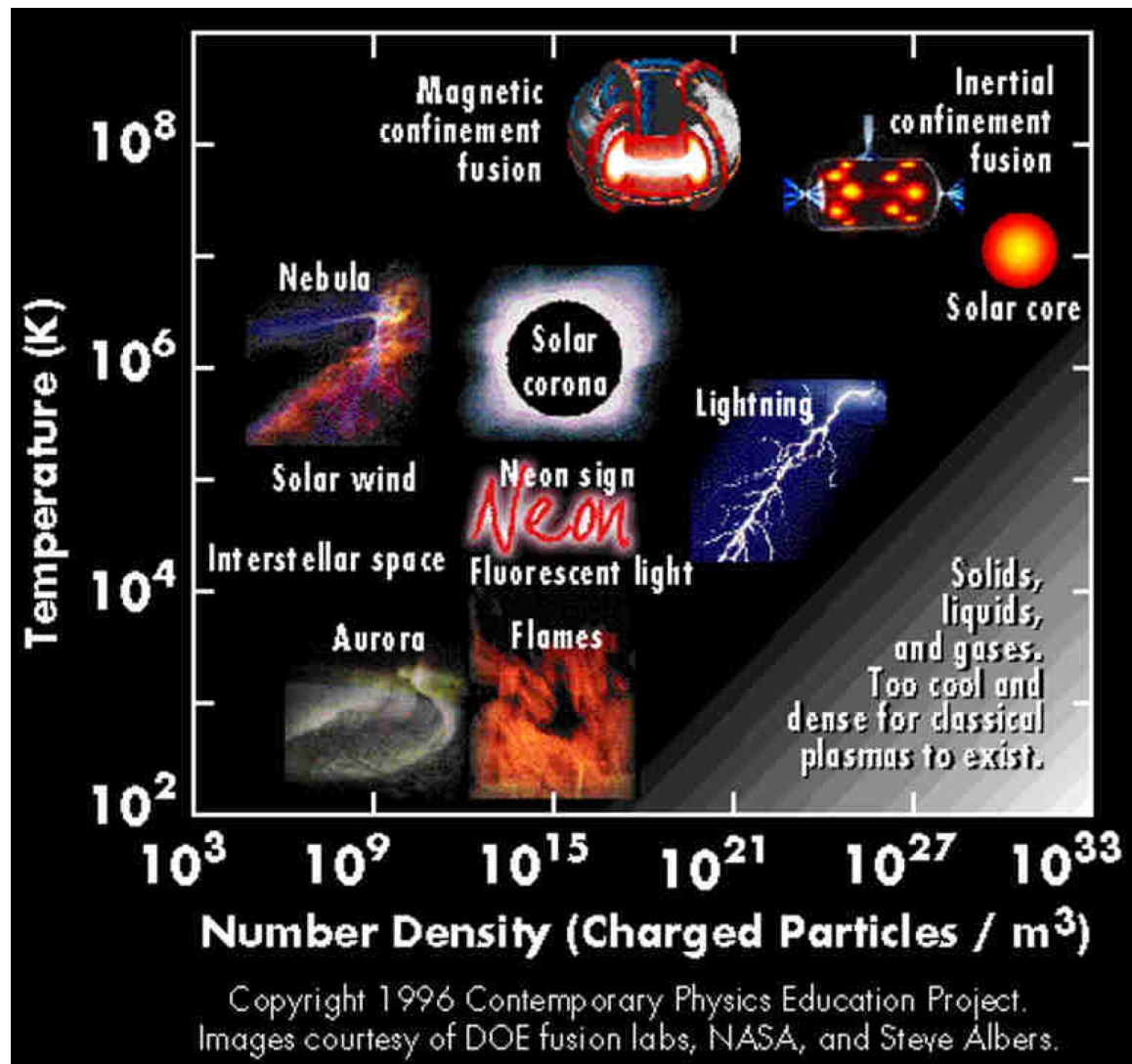


# Intro to Fusion and Gyrokinetics

D. R. Hatch

ICTP Oct 29, 2018

# Most Matter is Turbulent *Plasma*



# Outline of Talks (Hatch + Citrin)

- Lecture 1 Intro to Fusion and Gyrokinetics
- Lecture 2 Intro to Plasma Turbulence and How to Model It
- Lecture 3 High Confinement Fusion Regimes
- Lecture 4 + 5: Experimental observations of turbulence, nature of turbulent transport, saturation mechanisms, validation (comparison of simulations and experiment), overview of instabilities, reduced modeling, etc.

# Brief Intro to Magnetic Confinement Fusion



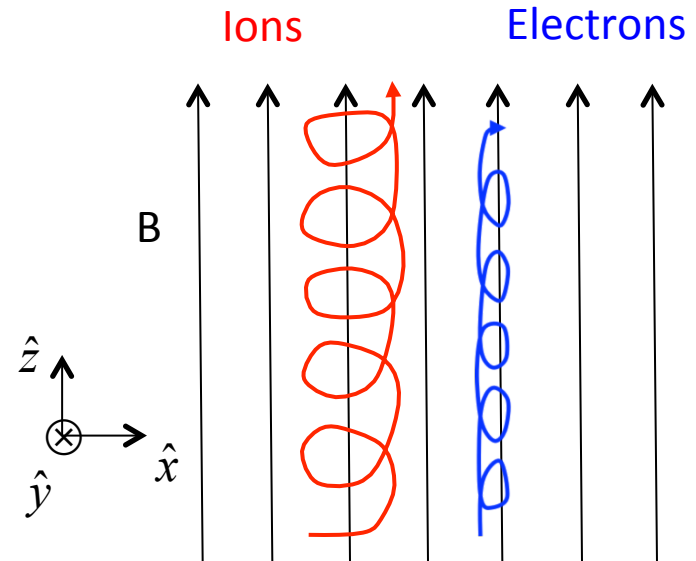
# Plasma physics basics – Particle motion in a Magnetic Field

$$m_s \frac{dw}{dt} = q_s w \times B \quad \mathbf{B} = B_0 \hat{z}$$

$$w_{||} = w_{||0}$$

$$w_x = w_{\perp} \cos \Omega t \quad x = \frac{w_{\perp}}{\Omega} \sin(\Omega t) + x_0$$

$$w_y = -w_{\perp} \sin \Omega t \quad y = \frac{w_{\perp}}{\Omega} \cos(\Omega t) + y_0$$



gyro-frequency:  

$$\Omega_s = q_s B / m_s$$

gyro-radius:  

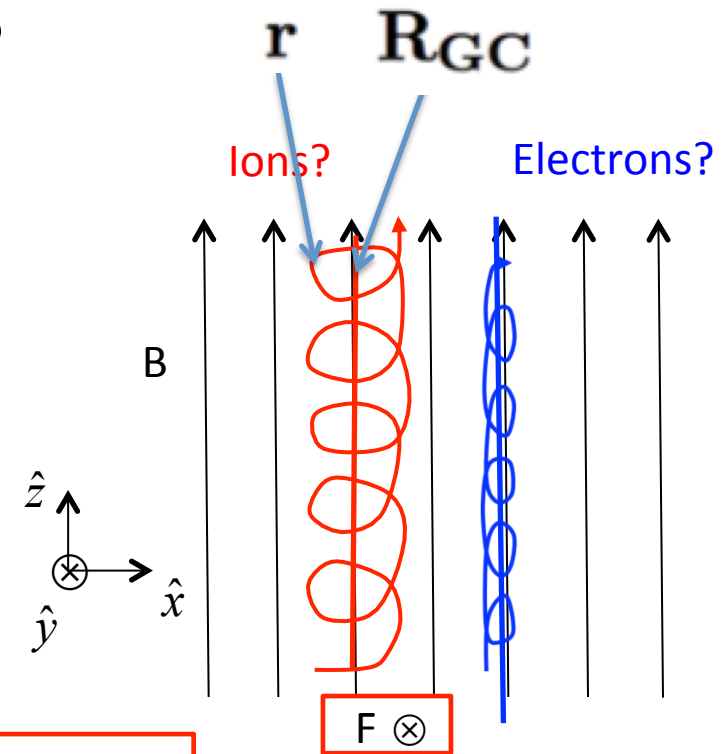
$$\rho_s = w_{\perp} / \Omega_s$$

# What Happens if We Add an Additional Force?

$$m \frac{dv}{dt} = F + qv \times B$$

Assume small gyroradius  
and slowly evolving fields  
--i.e. a magnetized plasma

$$\mathbf{r} = \mathbf{R}_{GC} + \rho_L$$



$$m \frac{d}{dt} [v_{GC} + w_L] = F + q[v_{GC} + w_L] \times B$$

This is  
small

We know this solution already

$$w_x = w_{\perp} \cos \Omega t \quad w_y = -w_{\perp} \sin \Omega t$$

# What Happens if We Add an Additional Force?

$$m \frac{dv}{dt} = F + qv \times B$$

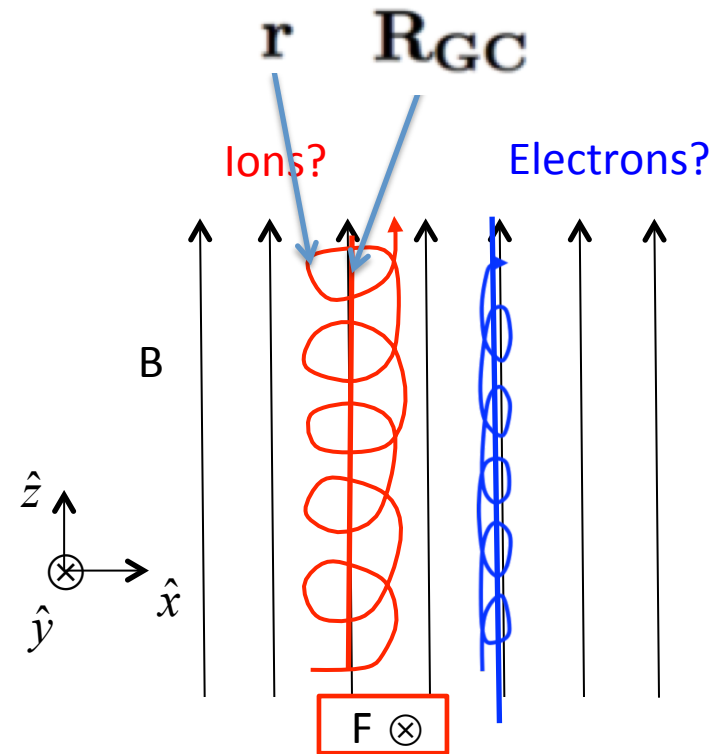
Assume small gyroradius  
and slowly evolving fields  
--i.e. a magnetized plasma

$$\mathbf{r} = \mathbf{R}_{GC} + \rho_L$$

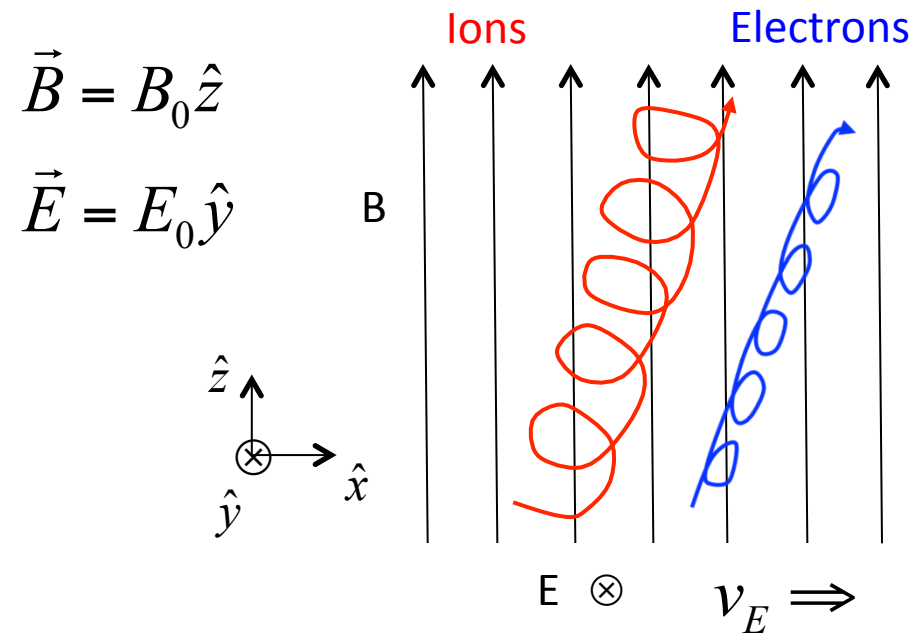
What's left?

$$F + qv_{GC} \times B = 0$$

$$\longrightarrow v_{\perp, GC} = \frac{F_{\perp} \times B}{qB^2}$$



# Plasma physics basics – Magnetic Field Plus Electric Field



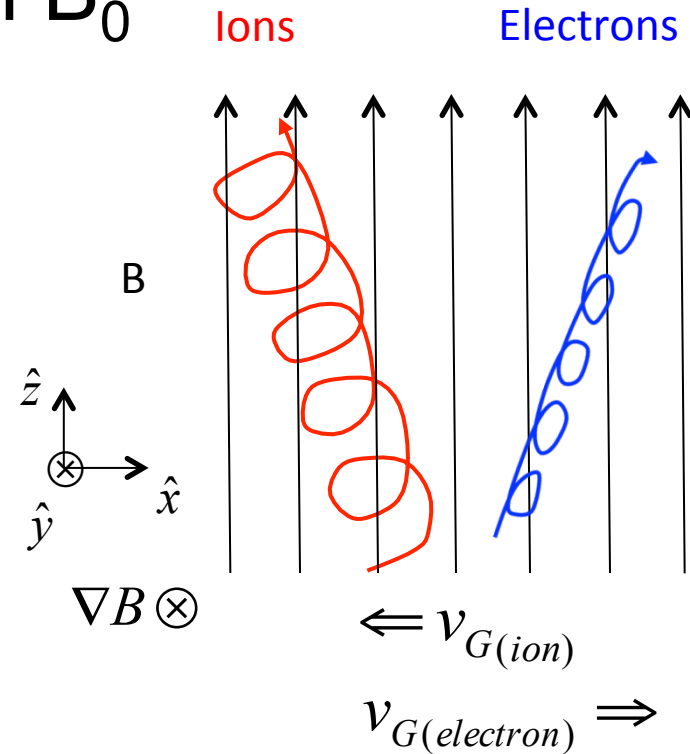
ExB drift:

$$v_{\perp, GC} = v_E = \frac{E \times B}{B^2}$$

(Note: same direction for ions and electrons)

# Plasma physics basics – Gradient in $B_0$

$$\vec{B} = B(y)\hat{z} \quad (\text{Only small variations on gyroradius scale})$$



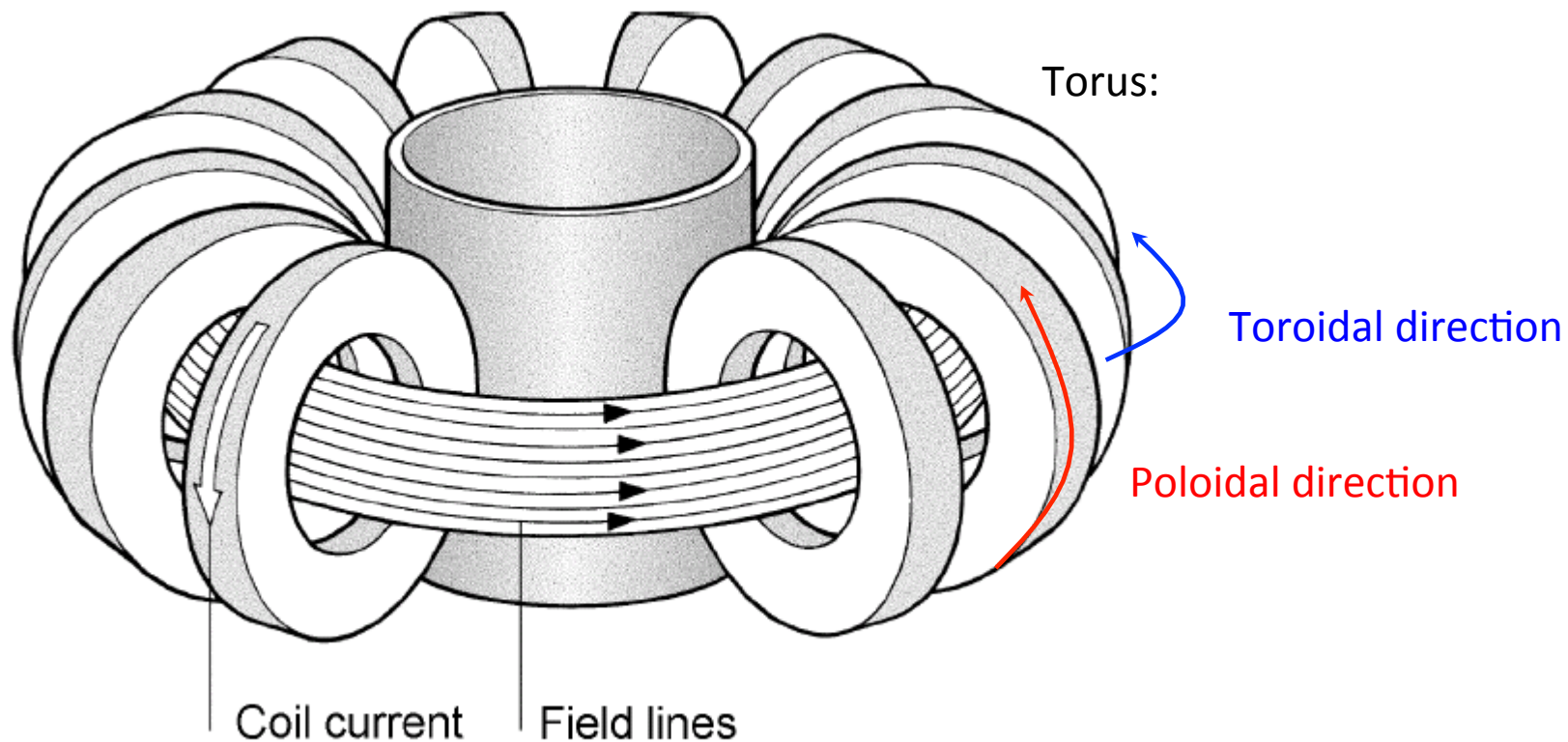
Grad B drift:

$$v_{\perp, GC} = v_{\nabla B} = m_j w_{\perp}^2 \frac{B \times \nabla B}{2q_j B^2}$$

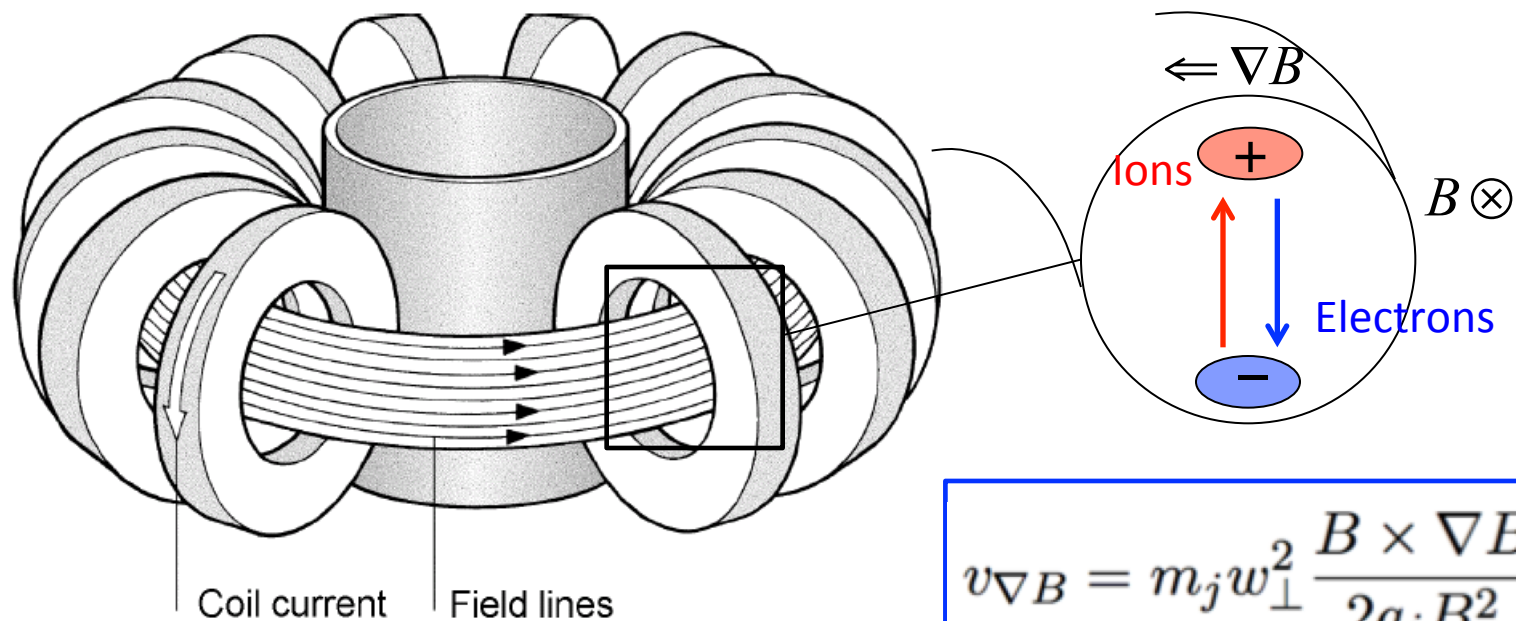
(Note: this drift depends on the charge, so it is in opposite direction for ions and electrons)

# Toroidal Magnetic Confinement

- Strong toroidal magnetic field:
- Particles move freely around the torus
- Particles are confined perpendicular to the magnetic field

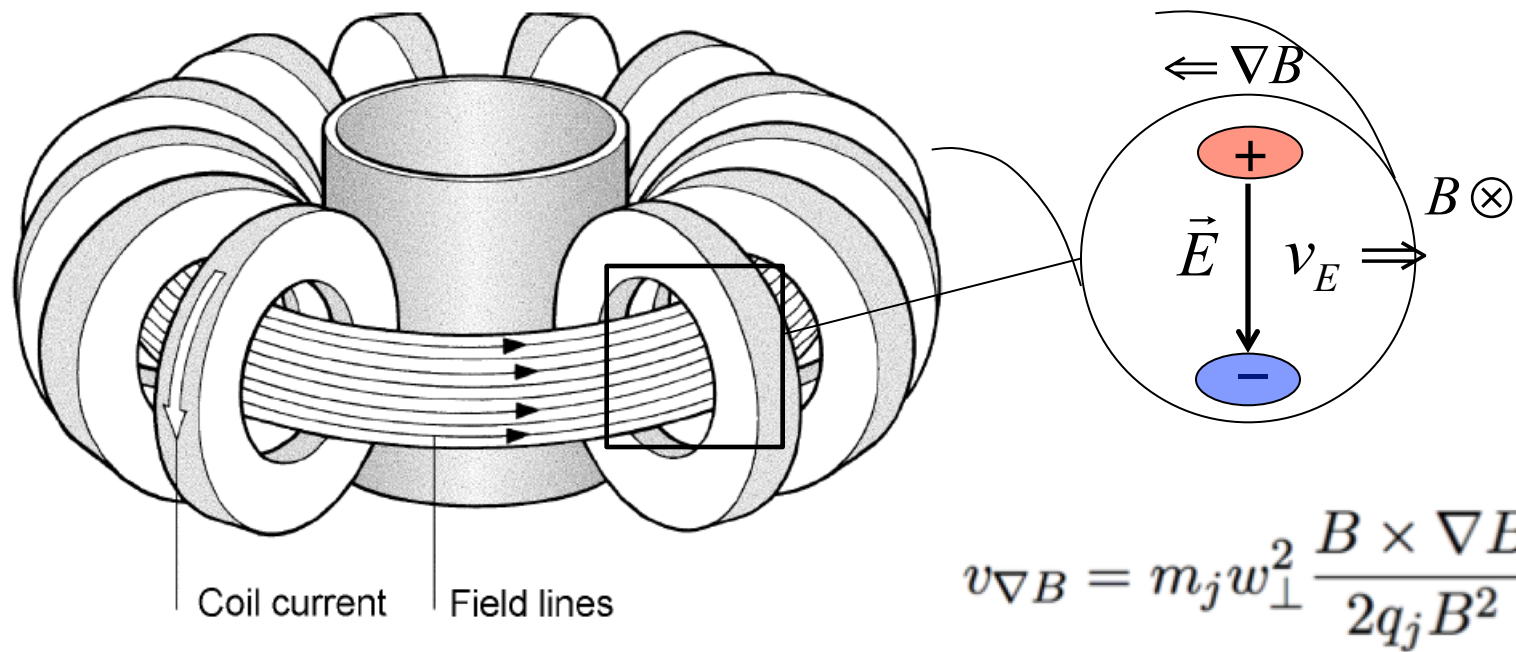


# Toroidal Magnetic Confinement



$$v_{\nabla B} = m_j w_{\perp}^2 \frac{B \times \nabla B}{2q_j B^2}$$

# Toroidal Magnetic Confinement

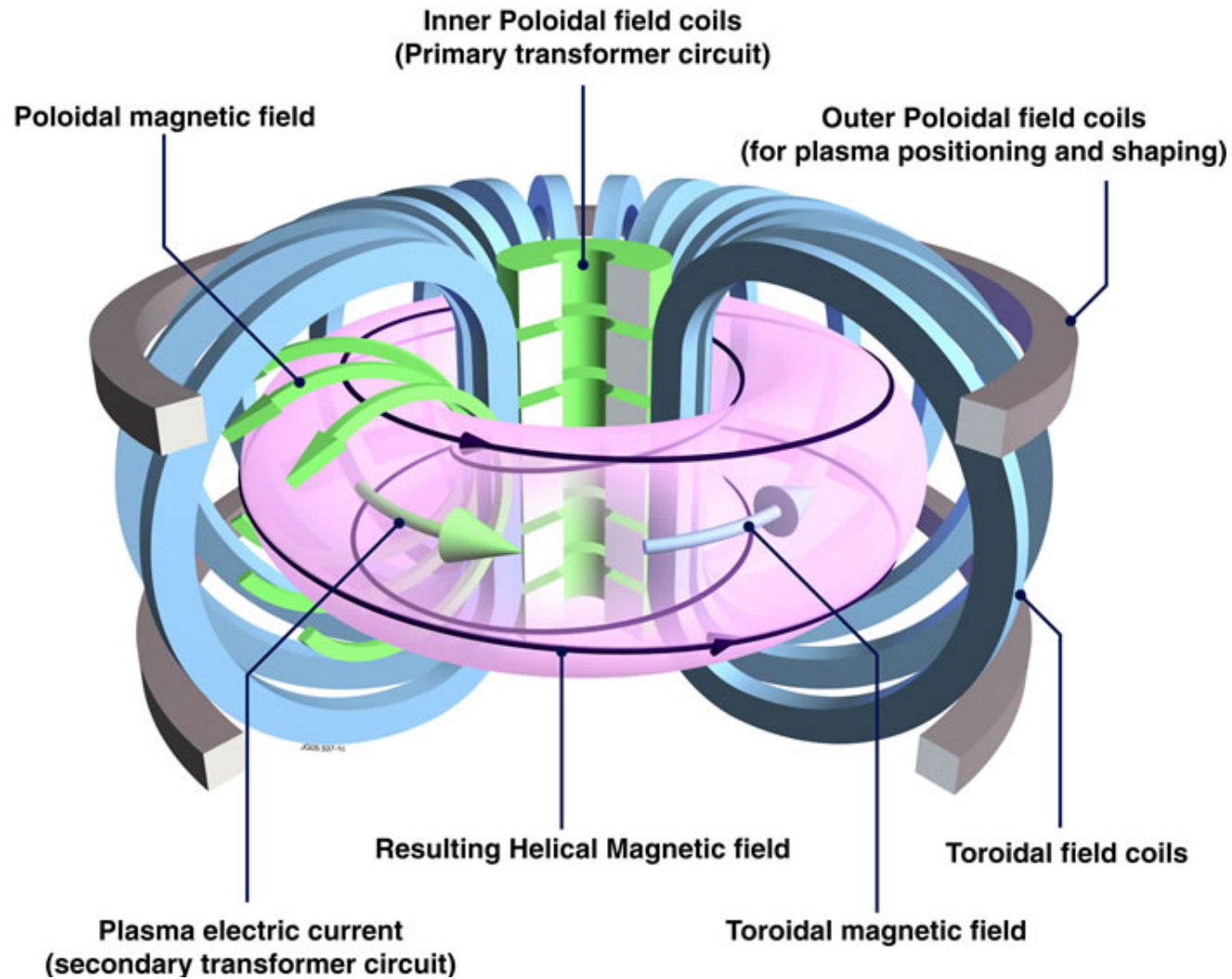


$$v_{\nabla B} = m_j w_{\perp}^2 \frac{B \times \nabla B}{2q_j B^2}$$

$$v_E = \frac{E \times B}{B^2}$$

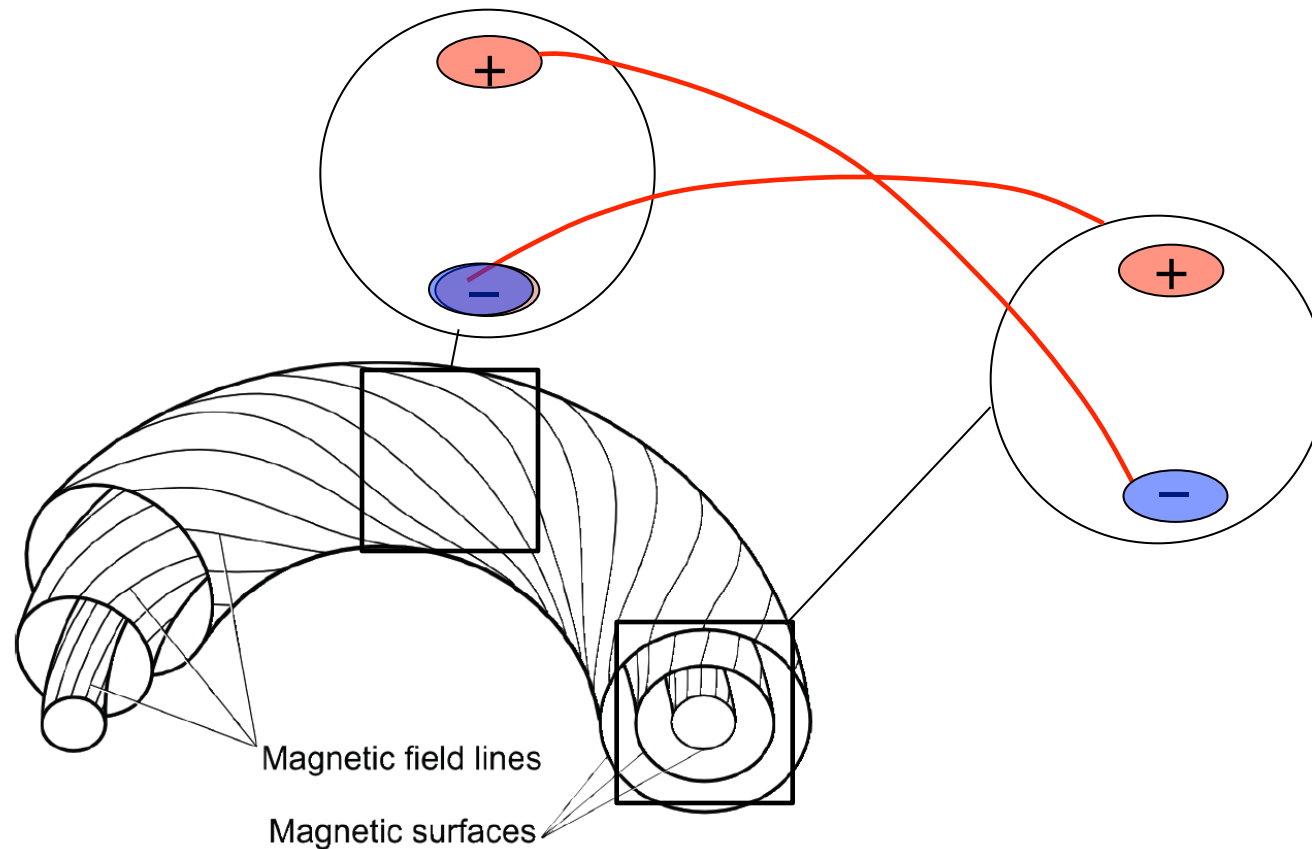


# Tokamak



# Toroidal Magnetic Confinement

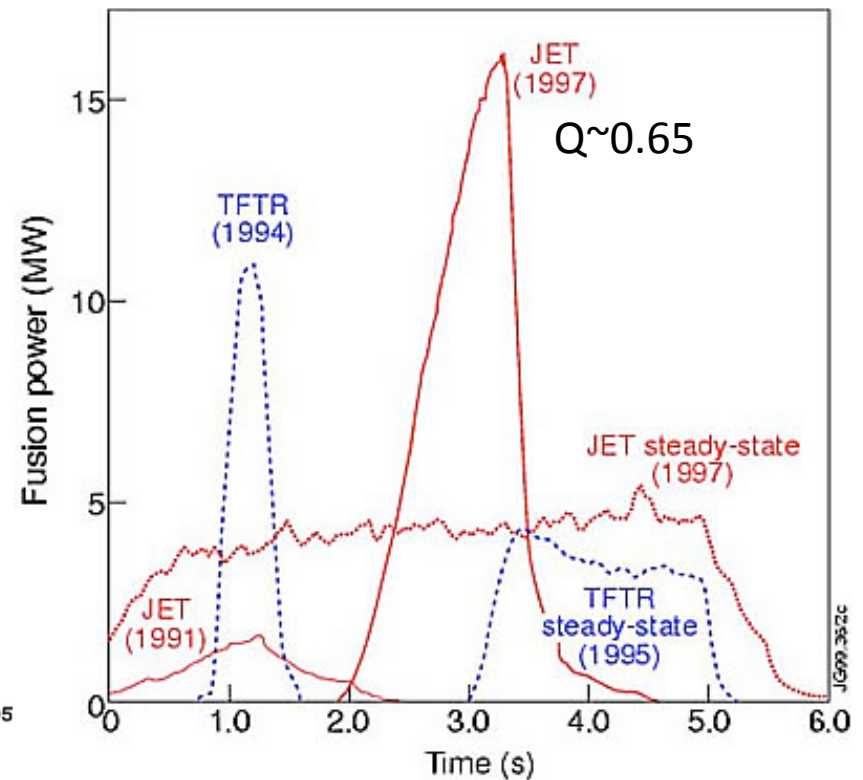
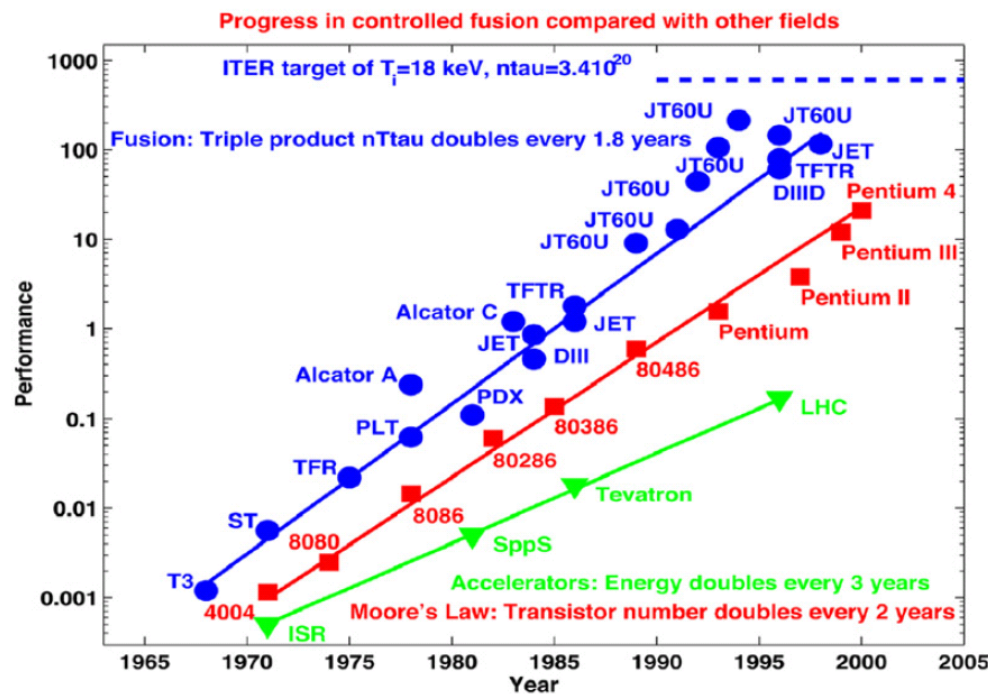
- Vertical drift: Need helical field



# Progress in Magnetic Confinement Fusion

Fusion Triple Product:

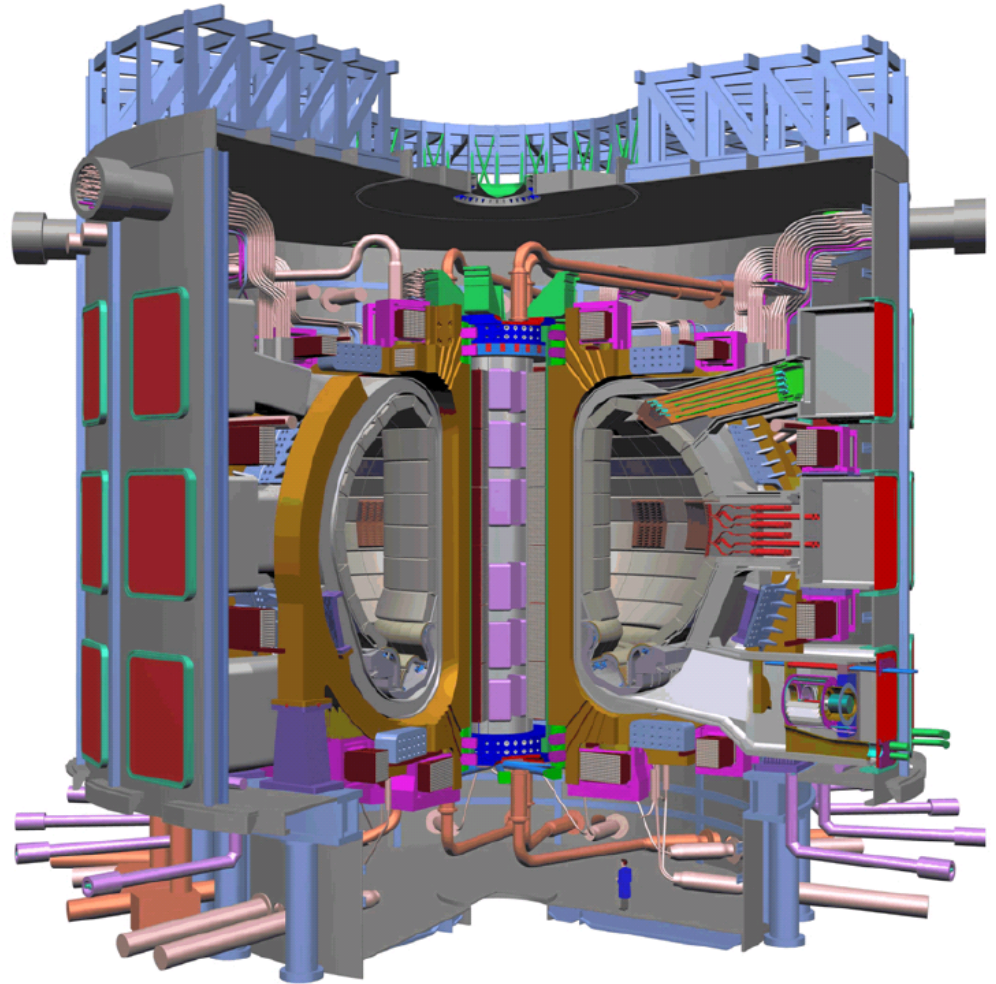
$$nT\tau_E \geq 5 \times 10^{21} m^{-3} keVs$$



Burning Question: What sets confinement time?  
Turbulent transport—the topic of these lectures.

# ITER—Demonstrate Large Net Energy

- ITER International Collaboration
  - Demonstrate large fusion gain ( $Q=5-10$ )
  - Fusion Power 500 MW
  - Duration ½ hour
  - Major radius: 6 m

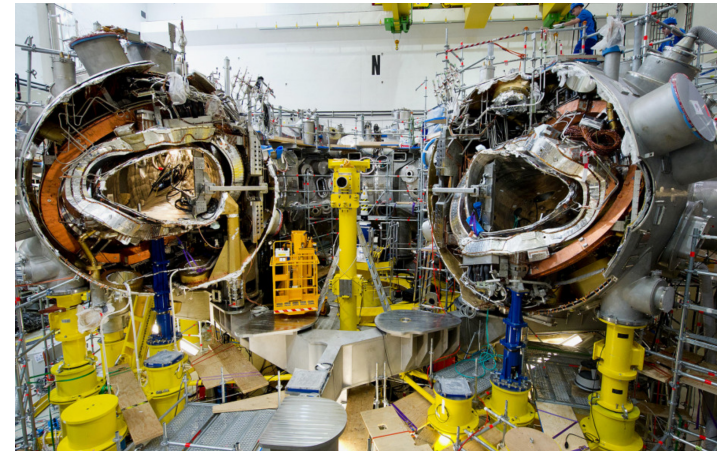
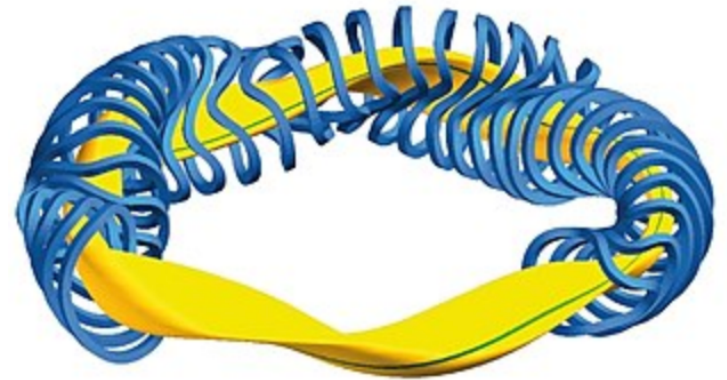




# Tokamak is the Leader, but there Exist Other Promising Fusion Designs

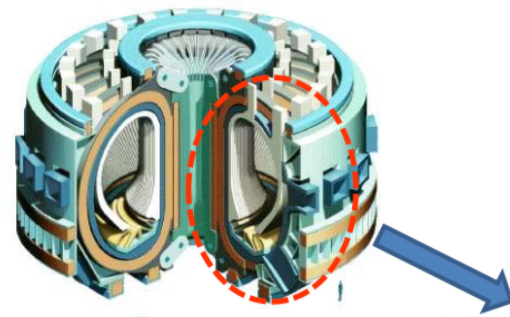
W7X (Greifswald, Germany)

- Spherical Tokamak (fatter donut—NSTX-U and MAST)
- Stellarator
  - Exploits third dimension (no toroidal symmetry) to confine plasma without externally driven current
  - Enormous room for theory-based optimization
- Other 'alternative' confinement configurations
  - Spheromak
  - Reverse Field Pinch
  - Field Reverse configuration

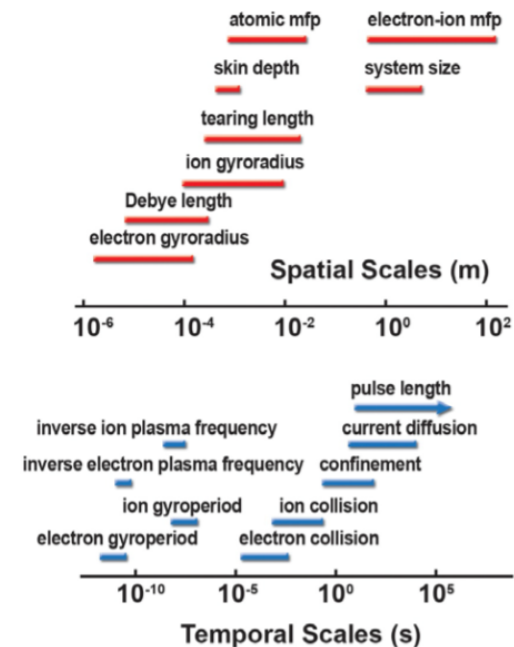
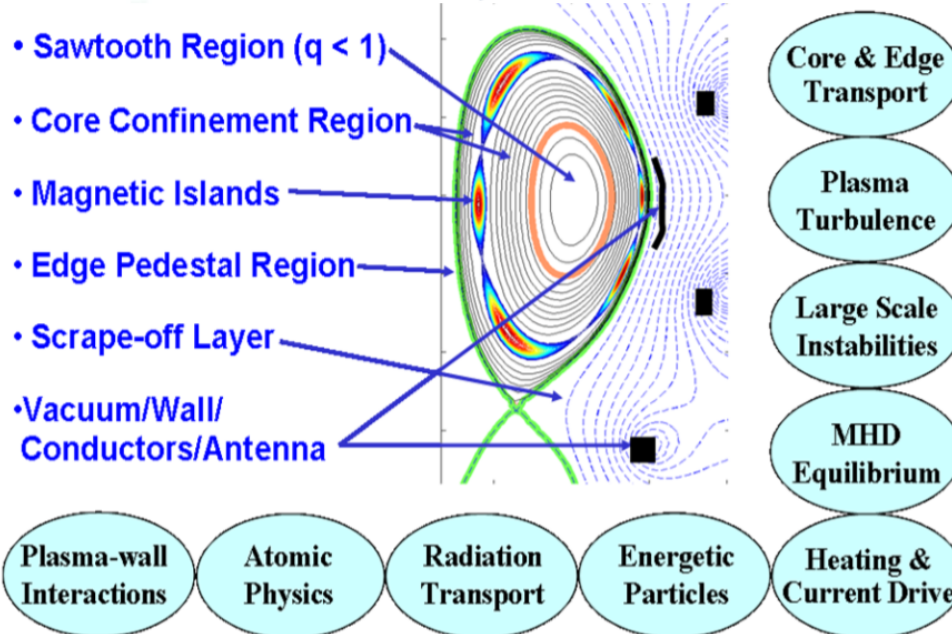


# How to Model Fusion Plasmas

# The Multiple Scales and Processes of a Fusion Reactor



- Fusion devices encompass:
  - Multiple physical processes
  - Large range of scales in time and space



# Can Describe All the Plasma Dynamics with the Distribution Function

$$f_{\sigma}(\mathbf{x}, \mathbf{v}, t)$$



# Moments of Distribution Function

$$f_{\sigma}(\mathbf{x}, \mathbf{v}, t)$$

$$n_{\sigma}(\mathbf{x}, t) = \int f_{\sigma}(\mathbf{x}, \mathbf{v}, t) d\mathbf{v}$$

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$$\mathbf{u}_{\sigma}(\mathbf{x}, t) = \frac{1}{n_{\sigma}} \int \mathbf{v} f_{\sigma}(\mathbf{x}, \mathbf{v}, t) d\mathbf{v}$$

# Moments of Distribution Function

$$f_{\sigma}(\mathbf{x}, \mathbf{v}, t)$$

$$n_{\sigma}(\mathbf{x}, t) = \int f_{\sigma}(\mathbf{x}, \mathbf{v}, t) d\mathbf{v} \longrightarrow \rho = \sum_{\sigma} q_{\sigma} n_{\sigma}$$

$$\mathbf{u}_{\sigma}(\mathbf{x}, t) = \frac{1}{n_{\sigma}} \int \mathbf{v} f_{\sigma}(\mathbf{x}, \mathbf{v}, t) d\mathbf{v} \longrightarrow J = \sum_{\sigma} q_{\sigma} n_{\sigma} \mathbf{u}_{\sigma}$$

# Moments of Distribution Function

$$f_{\sigma}(\mathbf{x}, \mathbf{v}, t)$$

$$n_{\sigma}(\mathbf{x}, t) = \int f_{\sigma}(\mathbf{x}, \mathbf{v}, t) d\mathbf{v} \longrightarrow \rho = \sum_{\sigma} q_{\sigma} n_{\sigma}$$

$$\mathbf{u}_{\sigma}(\mathbf{x}, t) = \frac{1}{n_{\sigma}} \int \mathbf{v} f_{\sigma}(\mathbf{x}, \mathbf{v}, t) d\mathbf{v} \longrightarrow J = \sum_{\sigma} q_{\sigma} n_{\sigma} \mathbf{u}_{\sigma}$$

Can feed into Maxwell's equations and describe the entire system

# How To Solve for Distribution Function?

$$\frac{Df_{\sigma}}{Dt} = 0$$

# How To Solve for Distribution Function?

$$\frac{\partial f_{\sigma}}{\partial t} + \overset{\dot{\mathbf{x}}}{\downarrow} \mathbf{v} \cdot \nabla f + \frac{q_{\sigma}}{m_{\sigma}} \overset{\dot{\mathbf{v}}}{\underbrace{(\mathbf{E} + \mathbf{v} \times \mathbf{B})}} \cdot \nabla_{\mathbf{v}} f_{\sigma} = 0$$

+

Maxwell's Equations

# Fokker-Planck: Theory of (almost) Everything for Fusion Plasma

$$\frac{\partial f_{\sigma}}{\partial t} + \mathbf{v} \cdot \nabla f + \frac{q_{\sigma}}{m_{\sigma}} (\mathbf{E} + \mathbf{v} \times \mathbf{B}) \cdot \nabla_{\mathbf{v}} f_{\sigma} = C_{\sigma\alpha}(f_{\sigma})$$

+

- Also need collision operator

## Maxwell's Equations

- LHS: interaction of particles with fields produced collectively by particles
  - ➔ conservation of particles in phase space
- RHS: collision operator representing short-scale one on one particle interaction
- This equation is capable of describing all relevant dynamics over all space and time scales
  - (Exception—plasma material interaction at the boundary)
- Consequently it is too complex to be of much practical use
- But it's the best starting point for formulating other models that optimize rigor and tractability

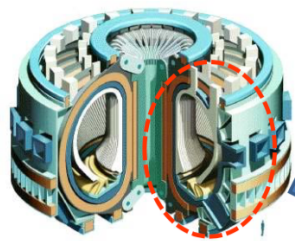


# Fokker-Planck: Theory of (almost) Everything for Fusion Plasma

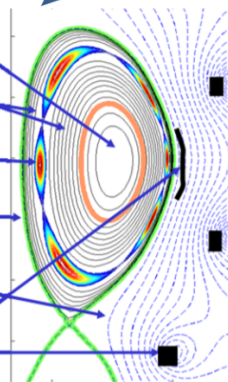
$$\frac{\partial f_{\sigma}}{\partial t} + \mathbf{v} \cdot \nabla f + \frac{q_{\sigma}}{m_{\sigma}} (\mathbf{E} + \mathbf{v} \times \mathbf{B}) \cdot \nabla_{\mathbf{v}} f_{\sigma} = C_{\sigma\alpha}(f_{\sigma})$$

+

## Maxwell's Equations



- Sawtooth Region ( $q < 1$ )
- Core Confinement Region
- Magnetic Islands
- Edge Pedestal Region
- Scrape-off Layer
- Vacuum/Wall/Conductors/Antenna



Core & Edge Transport

Plasma Turbulence

Large Scale Instabilities

MHD Equilibrium

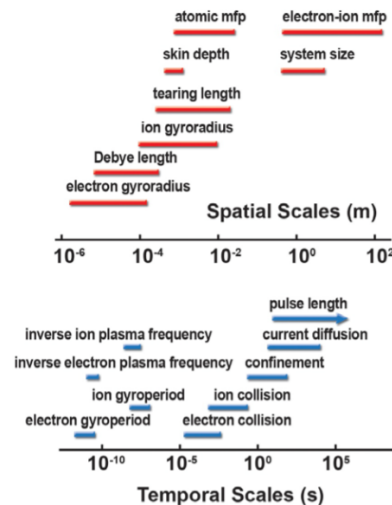
Plasma-wall Interactions

Atomic Physics

Radiation Transport

Energetic Particles

Heating & Current Drive



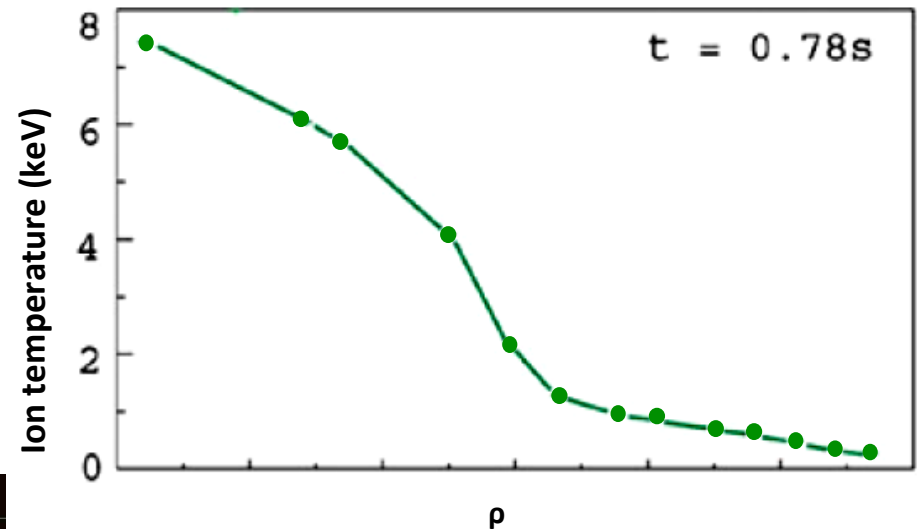
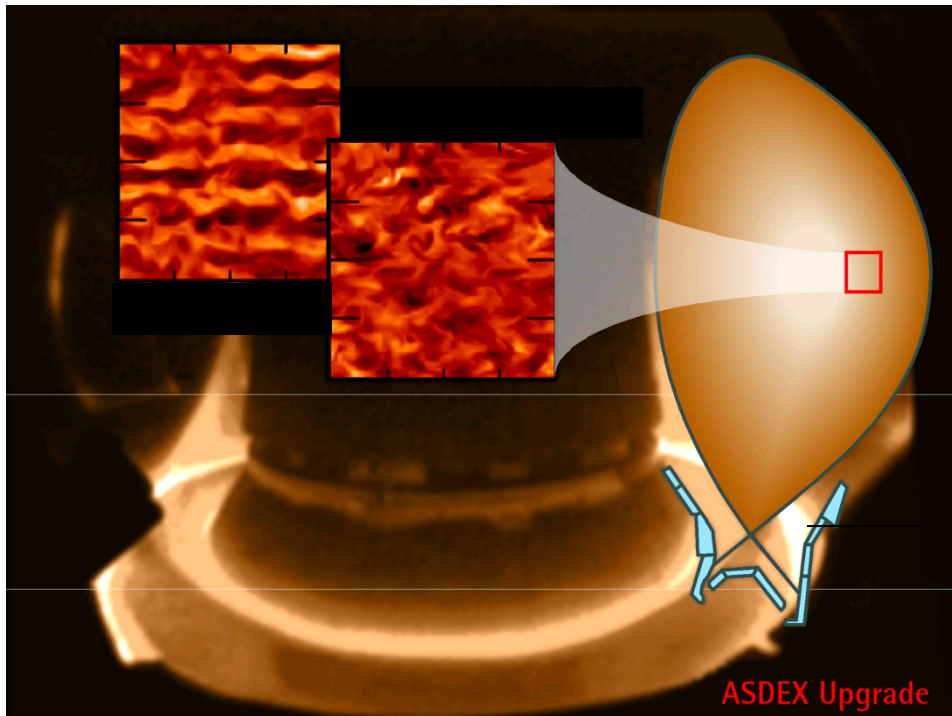
# How to Model a Fusion Reactor?

- Seek to find optimal balance of rigor and tractability
- Today's lecture: gyrokinetics
  - How the main models describing a fusion plasma can be derived from first principles (Fokker-Planck) based on a well-defined, rigorously justified ordering scheme.
  - The orderings and assumptions may seem arbitrary to you
  - But they are actually very well justified based on basic theory, extensive experience, and experimental observations of the systems we are trying to describe
  - *This remains very close to first principles*
  - References:
    - Multiscale Gyrokinetics: Abel et al Reports on Progress in Physics 2013
    - Plasma Confinement: Hazeltine and Meiss
    - GENE dissertations (Merz, Told, Goerler)

## Sneak Peak: What We Will Do

- Establish a rigorous ordering system—i.e. define a small parameter in terms of the relevant space and time scales, etc
- Transform into a natural coordinate system for a magnetized plasma—drift coordinates
- Split distribution function into
  - Background, slow time scale, large spatial scale part
  - Fluctuating, ‘fast’ time scale, small spatial scale part
- Expand kinetic equation with these orderings and solve order by order

# Sneak Peak: What We Will Achieve



Equations for:


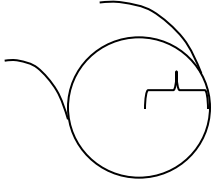
1. Macroscopic equilibrium (**Grad-Shafranov**):

$$\text{Grad } P = J \times B$$

Without this there would be no confinement

2. Small amplitude, small scale, fast time scale fluctuations (**Gyrokinetics**)
3. Large scale, slow time scale transport and flows (**Drift-Kinetic** → **Neoclassical**)
4. Slowly evolving background temperature and density (**Transport Equations**)

# Examples: Scales of a Fusion Plasma

Quantity	Typical Value	$\rho_*$
<p>Gyroradius: <math>\rho_j = \frac{m_j v_{Tj}}{q_j B}</math> </p> <p>Minor radius: a  a=minor radius:</p> <p>Gyrofrequency: <math>\Omega_j = \frac{q_j B}{m_j}</math></p> <p>Drift frequency: <math>\omega_* = \frac{v_{Tj}}{a}</math></p>	<p>ions ~ a few mm electrons ~0.1 mm</p> <p>~1 m</p> <p>ion~10<sup>9</sup> Hz electron~10<sup>12</sup> Hz</p> <p>ion~10<sup>6</sup> Hz electron~10<sup>8</sup> Hz</p>	<p><math>\frac{\rho_i}{a} \equiv \rho_{*i} \approx 10^{-3}</math></p> <p><math>\frac{\rho_e}{a} \equiv \rho_{*e} \approx 10^{-5}</math></p> <p><math>\frac{\omega_{*i}}{\Omega_i} \equiv \rho_{*i}</math></p> <p><math>\frac{\omega_{*e}}{\Omega_e} \equiv \rho_{*e}</math></p>
<p>Collision frequency <math>\nu \propto nT^{-3/2}</math></p>	<p>~5x10<sup>4</sup> Hz</p>	

# Starting Point: Fokker-Planck + Maxwell

- Fokker-Planck

$$\frac{df_s}{dt} = \frac{\partial f_s}{\partial t} + \mathbf{v} \cdot \nabla f_s + \frac{Z_s e}{m_s} \left( \tilde{\mathbf{E}} + \frac{1}{c} \mathbf{v} \times \tilde{\mathbf{B}} \right) \cdot \frac{\partial f_s}{\partial \mathbf{v}} = C[f_s] + S_s,$$

- Maxwell's Equations

$$\nabla \cdot \tilde{\mathbf{E}} = 4\pi \tilde{\rho},$$

$$\nabla \cdot \tilde{\mathbf{B}} = 0,$$

$$\frac{\partial \tilde{\mathbf{B}}}{\partial t} = -c \nabla \times \tilde{\mathbf{E}},$$

$$\nabla \times \tilde{\mathbf{B}} = \frac{4\pi}{c} \tilde{\mathbf{j}} + \frac{1}{c} \frac{\partial \tilde{\mathbf{E}}}{\partial t},$$

Note: using equations largely from Abel et al 2013 for convenience (some changes in notation from earlier slides—e.g. now Gaussian units)

# Gyrokinetic Ordering: Exploit Known Time and Length Scales of Turbulence

Global Gyrokinetic Simulation of  
Turbulence in  
**ASDEX Upgrade**



`gene.rzg.mpg.de`

- Well-established scale separation between turbulence time and length scales and those of background
- Multi-scale processes: challenge and opportunity
  - Challenge if you try brute force
  - Opportunity if you exploit it (which is what we do in this talk)

# Simplified Maxwell's Equations

- Small Debye length and non-relativistic  $k_{\perp}^2 \lambda_{\text{De}}^2 \ll 1$   $\frac{v_{\text{th}_s}^2}{c^2} \ll 1$

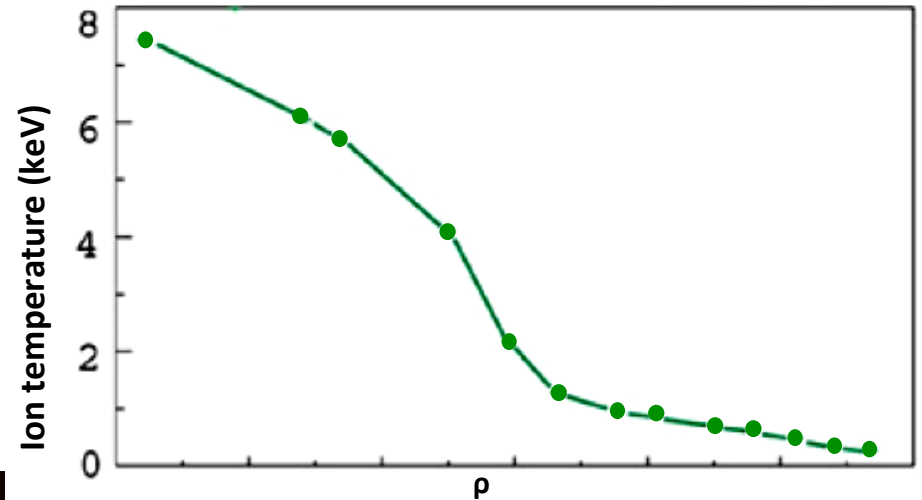
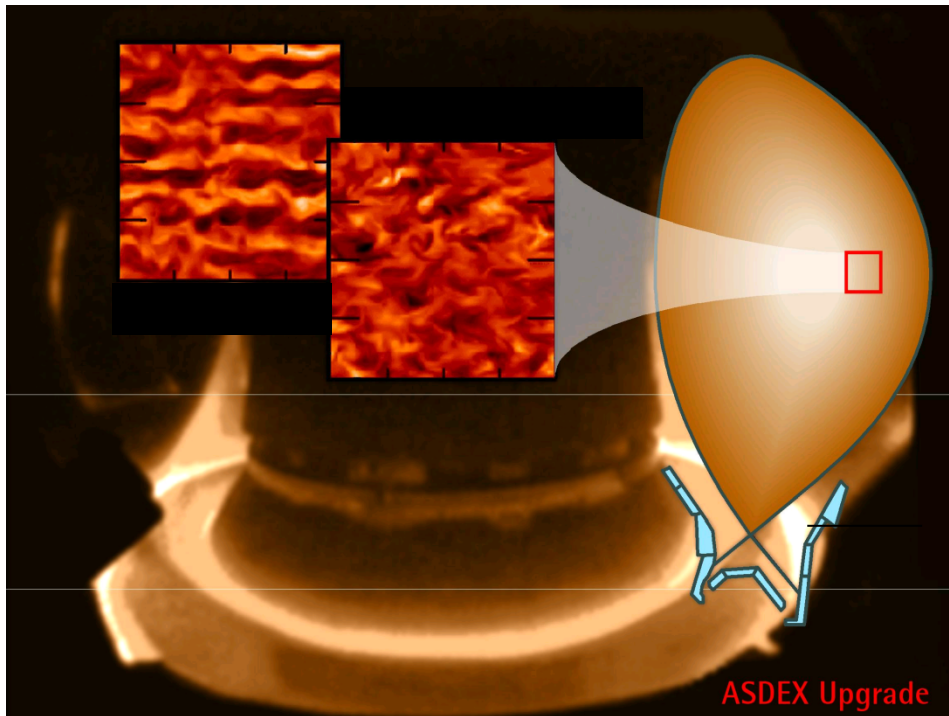
$$\left. \begin{aligned}
 \nabla \cdot \tilde{\mathbf{E}} &= 4\pi \tilde{\rho}, \\
 \nabla \cdot \tilde{\mathbf{B}} &= 0, \\
 \frac{\partial \tilde{\mathbf{B}}}{\partial t} &= -c \nabla \times \tilde{\mathbf{E}}, \\
 \nabla \times \tilde{\mathbf{B}} &= \frac{4\pi}{c} \tilde{\mathbf{j}} + \frac{1}{c} \frac{\partial \tilde{\mathbf{E}}}{\partial t},
 \end{aligned} \right\} \longrightarrow \begin{aligned}
 \tilde{\rho} &= 0, \\
 \tilde{\mathbf{E}} &= -\nabla \tilde{\varphi} - \frac{1}{c} \frac{\partial \tilde{\mathbf{A}}}{\partial t}, \\
 \tilde{\mathbf{B}} &= \nabla \times \tilde{\mathbf{A}}, \\
 \nabla \times \tilde{\mathbf{B}} &= \frac{4\pi}{c} \tilde{\mathbf{j}}.
 \end{aligned}$$

$$\tilde{\rho} = \sum_s Z_s e \int d^3 v f_s,$$

$$\tilde{\mathbf{j}} = \sum_s Z_s e \int d^3 v \mathbf{v} f_s.$$

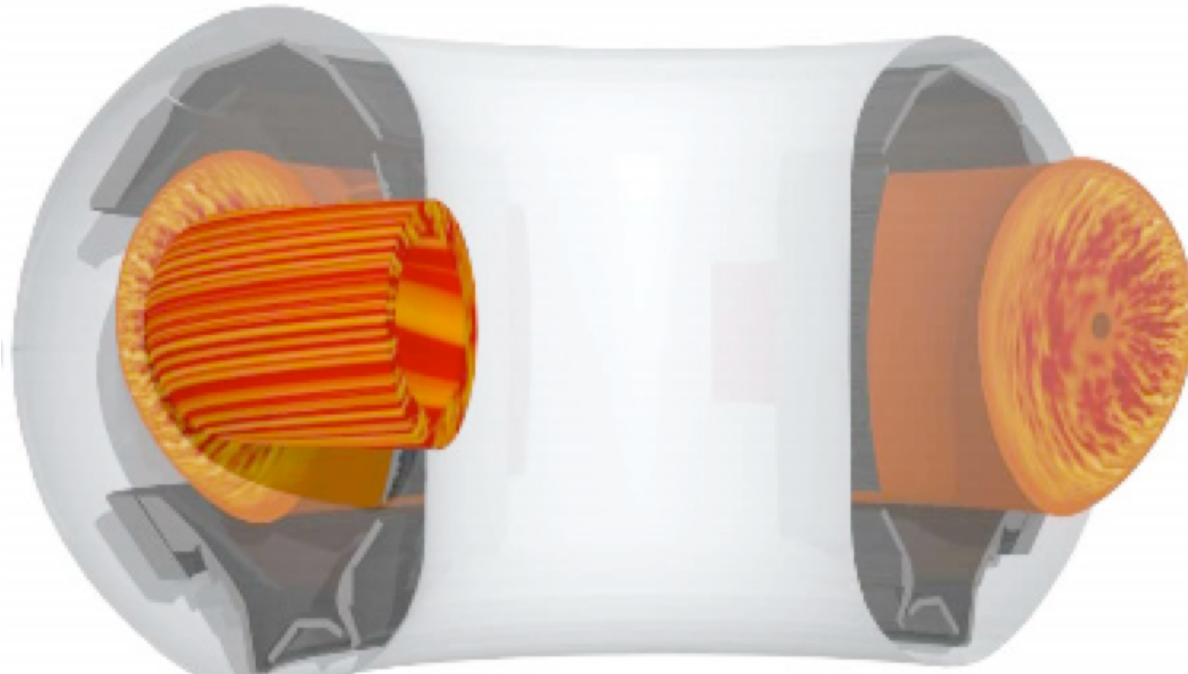


# Gyrokinetic Ordering: Small Amplitude Fluctuations



- Fluctuations are small compared to background  $\frac{|\delta \mathbf{B}|}{|\mathbf{B}|} \sim \frac{|\delta \mathbf{E}|}{|\mathbf{E}|} \sim \frac{\delta f_s}{f_s} \sim \epsilon.$

# Gyrokinetic Ordering: Small Spatial Scales

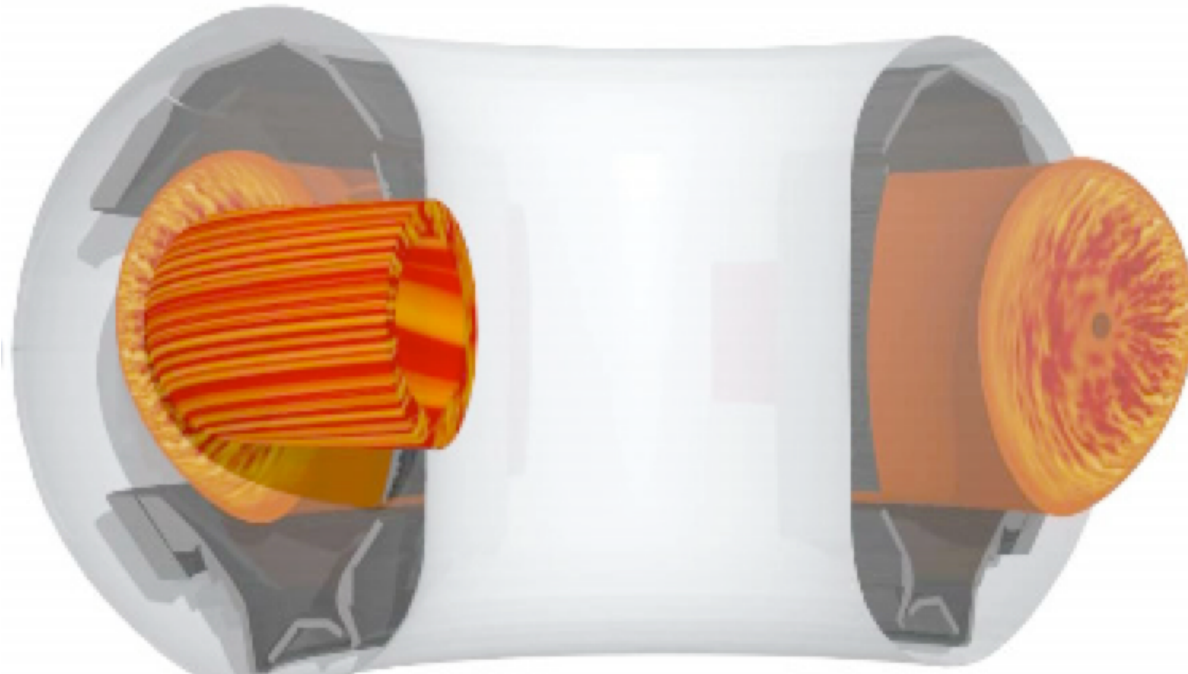


- Fluctuations have scales comparable to gyroradius
- Gyroradius is small compared to, e.g., machine size
- Use this as small parameter to do multi-scale expansion
- Note: this is a condition for a 'strongly magnetized' plasma

$$k_{\perp} \sim 1/\rho_s$$

$$\frac{\rho_s}{a} = \epsilon.$$

# Gyrokinetic Ordering: Time Scales

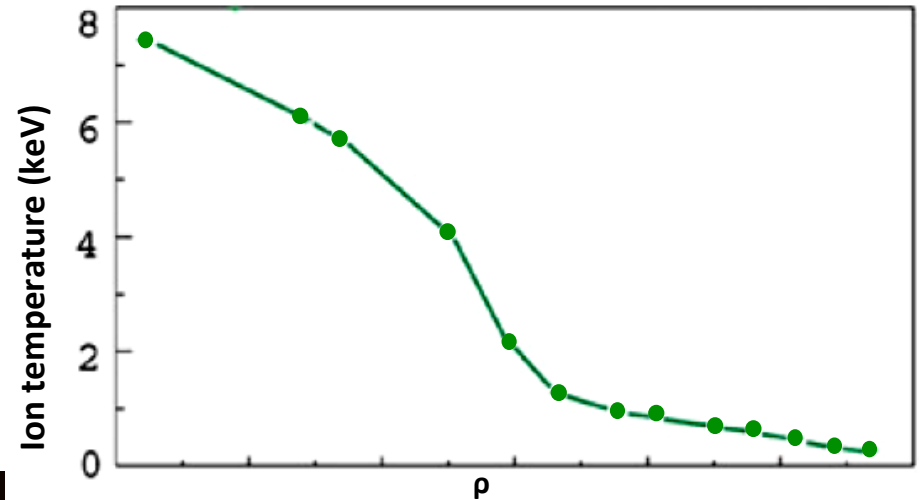
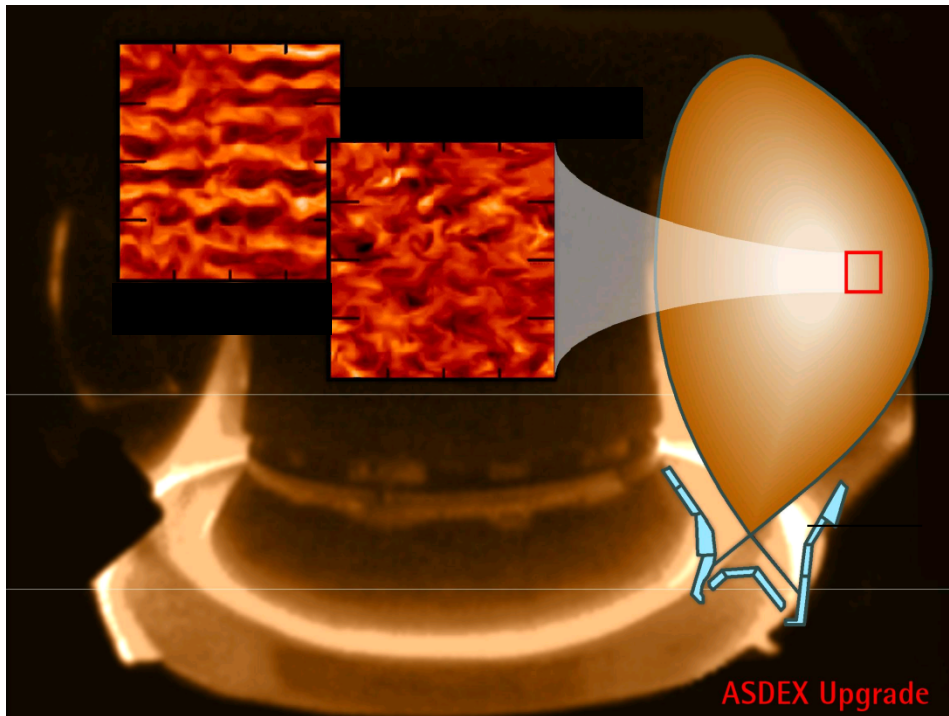


- Fluctuation time scales are large compared to gyrofrequency
- Fluctuation time scales are small compared to confinement time
  - i.e. time scale of background evolution
- Note: this is also a condition for a 'strongly magnetized' plasma

$$\omega \sim c_s/a$$

$$\frac{\omega}{\Omega} \sim \epsilon$$

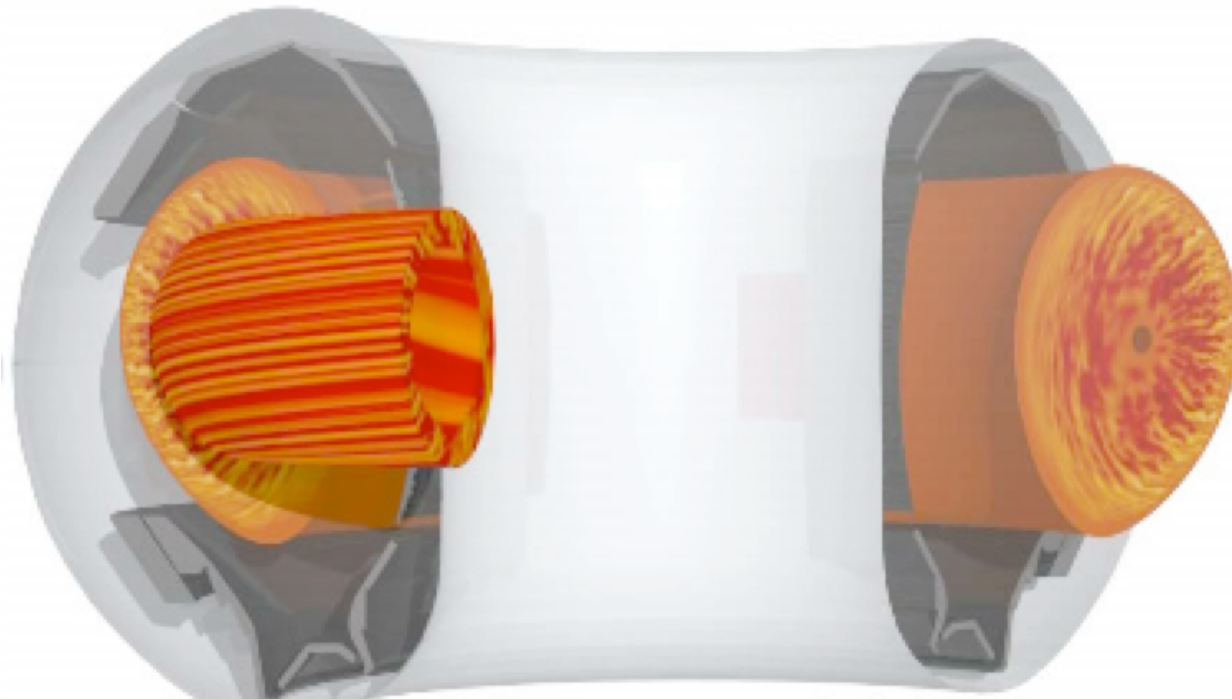
# Gyrokinetic Ordering: Small Amplitude Fluctuations



- Background evolves much slower than fluctuations (gyroBohm scaling)

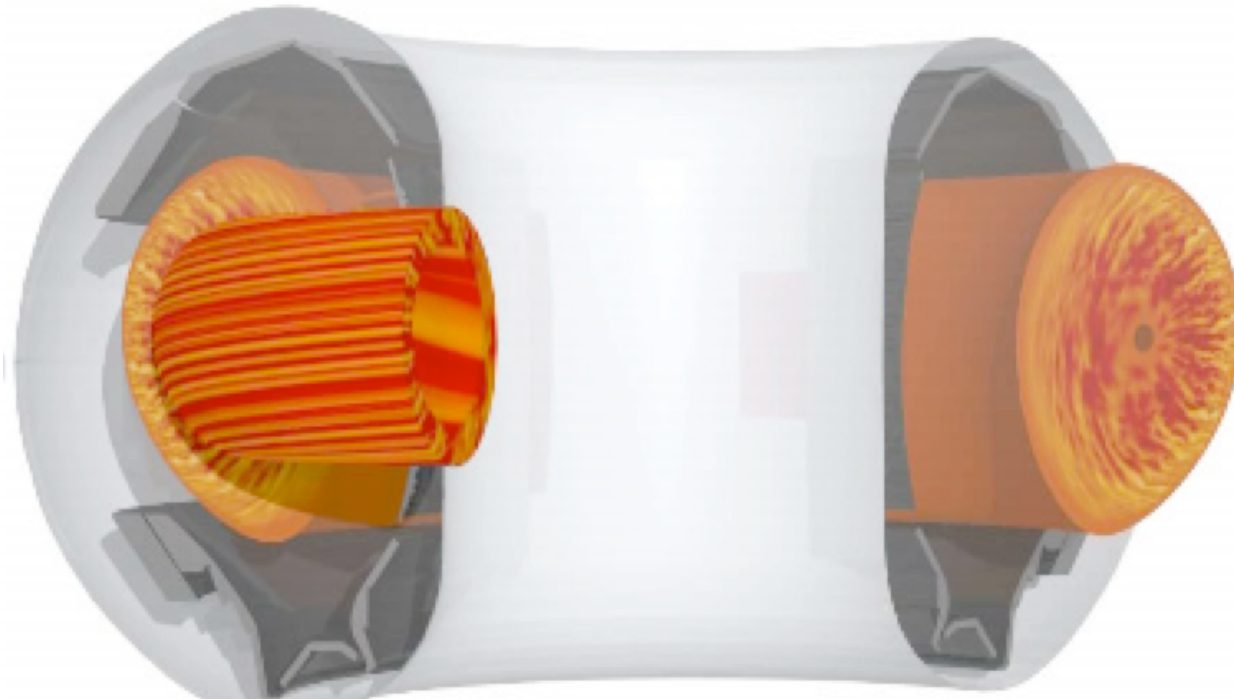
$$\frac{1}{\tau_E} \sim \frac{\chi_T}{a^2} \sim \frac{\omega}{\Omega_s} \left( \frac{\rho_s}{a} \right)^2 \Omega_s \sim \epsilon^3 \Omega_s$$

# Gyrokinetic Ordering: Parallel vs Perpendicular Scales



- Perpendicular scales are much smaller than parallel  $\frac{k_{\parallel}}{k_{\perp}} \sim \epsilon$ .

# Gyrokinetic Ordering: Summary



$$\frac{|\delta \mathbf{B}|}{|\mathbf{B}|} \sim \frac{|\delta \mathbf{E}|}{|\mathbf{E}|} \sim \frac{\delta f_s}{f_s} \sim \frac{k_{\parallel}}{k_{\perp}} \sim \frac{\omega}{\Omega_s} \sim \frac{\rho_s}{a} = \epsilon.$$

$$\frac{1}{\tau_E} \sim \frac{\chi_T}{a^2} \sim \frac{\omega}{\Omega_s} \left( \frac{\rho_s}{a} \right)^2 \Omega_s \sim \epsilon^3 \Omega_s.$$

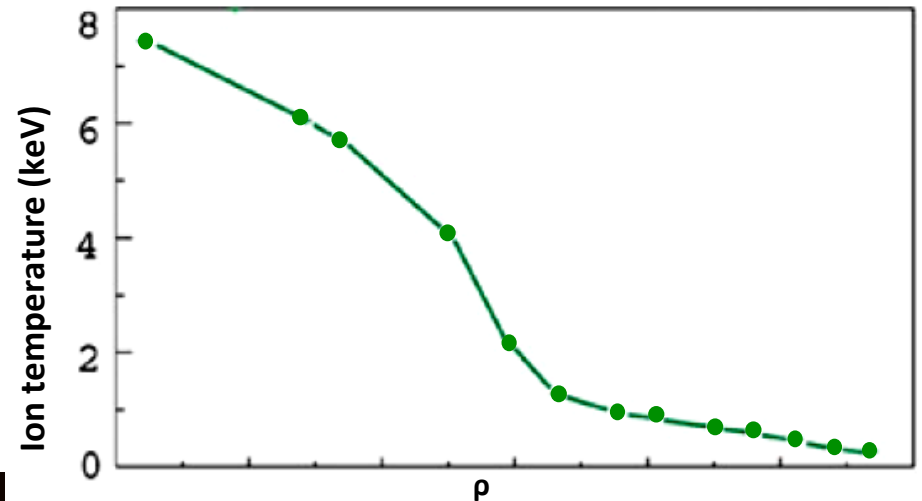
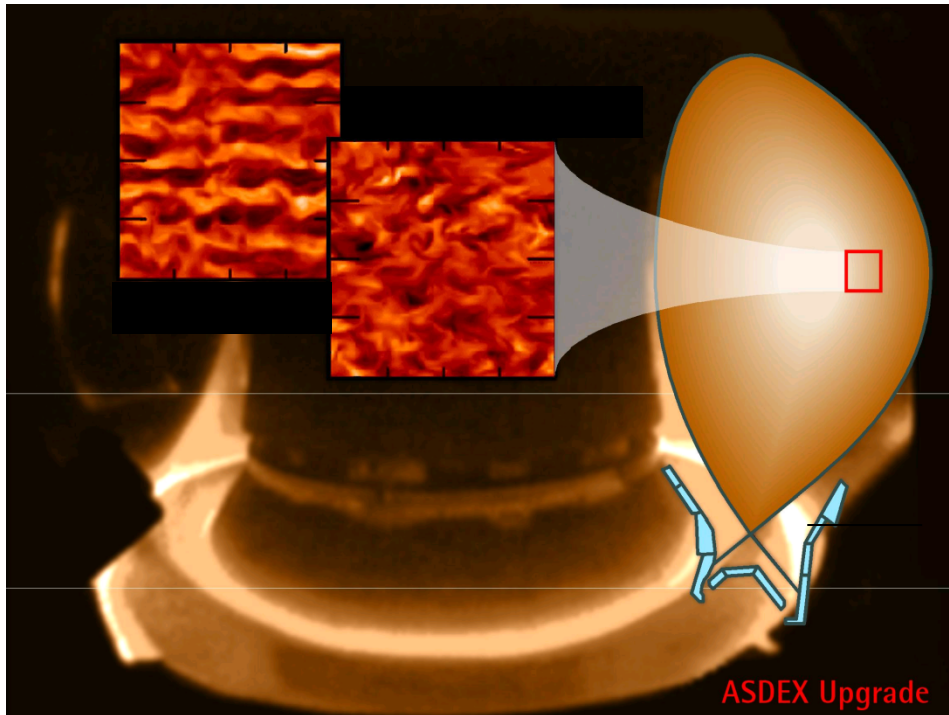
# Average Over 'Intermediate' Scales to Separate Fluctuations from Background

$$\begin{array}{l}
 \text{Space} \left\{ \begin{array}{lll}
 a \gg \lambda \gg \rho_s & f_s = F_s + \delta f_s, & F_s = \langle f_s \rangle_{\text{turb}}, \\
 \langle g(\mathbf{r}, \mathbf{v}, t) \rangle_{\perp} = \int_{\lambda_{\perp}^2} d^2 \mathbf{r}'_{\perp} g(\mathbf{r}'_{\perp}, l, \mathbf{v}, t) / \int_{\lambda_{\perp}^2} d^2 \mathbf{r}_{\perp}, & \tilde{\mathbf{E}} = \mathbf{E} + \delta \mathbf{E}, & \mathbf{E} = \langle \tilde{\mathbf{E}} \rangle_{\text{turb}}, \\
 & \tilde{\mathbf{B}} = \mathbf{B} + \delta \mathbf{B}, & \mathbf{B} = \langle \tilde{\mathbf{B}} \rangle_{\text{turb}}, \\
 \\ 
 \text{Time} \left\{ \begin{array}{lll}
 \tau_E \gg T \gg \omega^{-1} & \tilde{\mathbf{A}} = \mathbf{A} + \delta \mathbf{A}, & \mathbf{A} = \langle \tilde{\mathbf{A}} \rangle_{\text{turb}}, \\
 \langle g(\mathbf{r}, \mathbf{v}, t) \rangle_T = \frac{1}{T} \int_{t-T/2}^{t+T/2} dt' g(\mathbf{r}, \mathbf{v}, t'), & \tilde{\varphi} = \varphi + \delta \varphi, & \varphi = \langle \tilde{\varphi} \rangle_{\text{turb}}.
 \end{array} \right.
 \end{array}$$

$$\langle g(\mathbf{r}, \mathbf{v}, t) \rangle_{\text{turb}} = \langle \langle g \rangle_{\perp} \rangle_T.$$



# First Step: Separating Background, Macroscopic, Slowly Evolving Quantities from Fluctuating Quantities



$$f_s = F_s + \delta f_s, \quad F_s = \langle f_s \rangle_{\text{turb}},$$

$$\tilde{E} = E + \delta E, \quad E = \langle \tilde{E} \rangle_{\text{turb}},$$

$$\tilde{B} = B + \delta B, \quad B = \langle \tilde{B} \rangle_{\text{turb}},$$

$$\tilde{A} = A + \delta A, \quad A = \langle \tilde{A} \rangle_{\text{turb}},$$

$$\tilde{\varphi} = \varphi + \delta \varphi, \quad \varphi = \langle \tilde{\varphi} \rangle_{\text{turb}}.$$



Next Step: Convert into 'Drift Coordinates'

# Gyrokinetic Variables

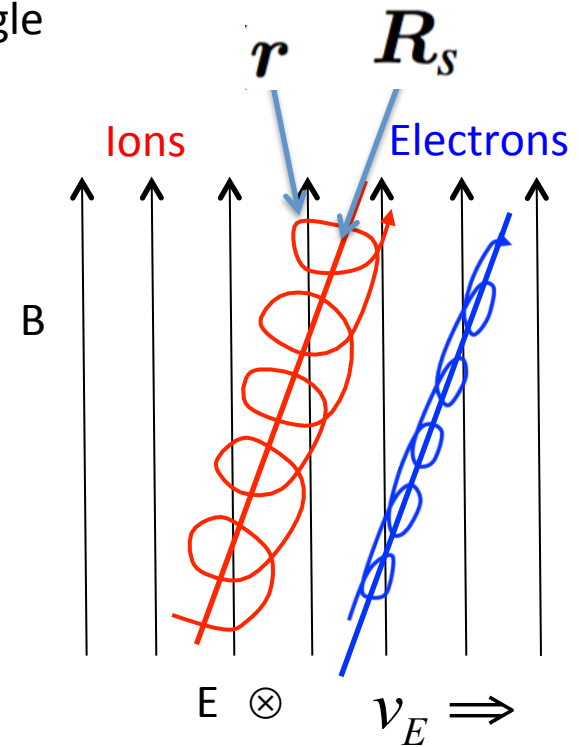
$$\mathbf{w} = w_{\parallel} \mathbf{b} + w_{\perp} (\cos \vartheta \mathbf{e}_2 - \sin \vartheta \mathbf{e}_1),$$

$(\Omega t)$  gyrophase angle

Particle location      Location of guiding center

$$(\mathbf{r}, \mathbf{w}) \rightarrow (\mathbf{R}_s, \varepsilon_s, \mu_s, \vartheta, \sigma)$$

$$\mathbf{R}_s = \mathbf{r} - \frac{\mathbf{b} \times \mathbf{w}}{\Omega_s},$$



## Useful Velocity Space Variables

$$(r, w) \rightarrow (\mathbf{R}_s, \varepsilon_s, \mu_s, \vartheta, \sigma)$$

$$\varepsilon_s = \frac{1}{2} m_s w^2 \quad \mu_s = \frac{m_s w_{\perp}^2}{2B}, \quad \sigma = \frac{w_{\parallel}}{|w_{\parallel}|},$$

Alternatively (GENE uses these):

$$w_{\parallel} \quad \text{and} \quad \mu_s = \frac{m_s w_{\perp}^2}{2B},$$

## Convert Entire Kinetic Equation into Gyrokinetic Variables

$$\frac{df_s}{dt} = \frac{\partial f_s}{\partial t} + w \cdot \nabla f_s + \frac{Z_s e}{m_s} \left( \tilde{\mathbf{E}} + \frac{1}{c} w \times \tilde{\mathbf{B}} \right) \cdot \frac{\partial f_s}{\partial \mathbf{v}} = C[f_s] + S_s,$$

$$(r, w) \rightarrow (\mathbf{R}_s, \varepsilon_s, \mu_s, \vartheta, \sigma)$$

$$\frac{df_s}{dt} = \frac{\partial f_s}{\partial t} + \dot{\mathbf{R}}_s \cdot \frac{\partial f_s}{\partial \mathbf{R}_s} + \dot{\mu}_s \frac{\partial f_s}{\partial \mu_s} + \dot{\varepsilon}_s \frac{\partial f_s}{\partial \varepsilon_s} + \dot{\vartheta} \frac{\partial f_s}{\partial \vartheta} = C[f_s] + S_s,$$

We now have a kinetic equation in its ‘natural’ coordinates for a strongly magnetized plasma.

Now we have, instead of a distribution of particles, a distribution of guiding centers

# Convert Entire Kinetic Equation into Gyrokinetic Variables

$$\frac{df_s}{dt} = \frac{\partial f_s}{\partial t} + w \cdot \nabla f_s + \frac{Z_s e}{m_s} \left( \tilde{\mathbf{E}} + \frac{1}{c} w \times \tilde{\mathbf{B}} \right) \cdot \frac{\partial f_s}{\partial \mathbf{v}} = C[f_s] + S_s,$$

$$(r, w) \rightarrow (\mathbf{R}_s, \varepsilon_s, \mu_s, \vartheta, \sigma)$$

$$\frac{df_s}{dt} = \frac{\partial f_s}{\partial t} + \dot{\mathbf{R}}_s \cdot \frac{\partial f_s}{\partial \mathbf{R}_s} + \dot{\mu}_s \frac{\partial f_s}{\partial \mu_s} + \dot{\varepsilon}_s \frac{\partial f_s}{\partial \varepsilon_s} + \dot{\vartheta} \frac{\partial f_s}{\partial \vartheta} = C[f_s] + S_s,$$

What is this?

# Convert Entire Kinetic Equation into Gyrokinetic Variables

$$\frac{df_s}{dt} = \frac{\partial f_s}{\partial t} + w \cdot \nabla f_s + \frac{Z_s e}{m_s} \left( \tilde{\mathbf{E}} + \frac{1}{c} w \times \tilde{\mathbf{B}} \right) \cdot \frac{\partial f_s}{\partial \mathbf{v}} = C[f_s] + S_s,$$

$$(r, w) \rightarrow (\mathbf{R}_s, \varepsilon_s, \mu_s, \vartheta, \sigma)$$

$$\frac{df_s}{dt} = \frac{\partial f_s}{\partial t} + \boxed{\dot{\mathbf{R}}_s} \cdot \frac{\partial f_s}{\partial \mathbf{R}_s} + \dot{\mu}_s \frac{\partial f_s}{\partial \mu_s} + \dot{\varepsilon}_s \frac{\partial f_s}{\partial \varepsilon_s} + \dot{\vartheta} \frac{\partial f_s}{\partial \vartheta} = C[f_s] + S_s,$$

What is this?

This encompasses the drift velocities  
etc

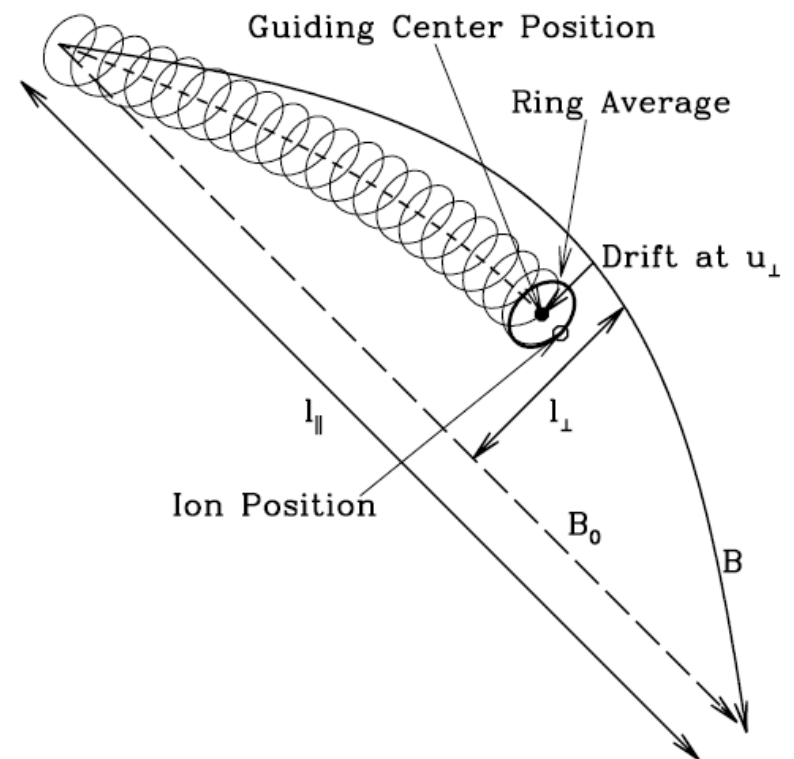
$$v_E = \frac{E \times B}{B^2}$$

$$v_{\nabla B} = m_j w_{\perp}^2 \frac{B \times \nabla B}{2q_j B^2}$$

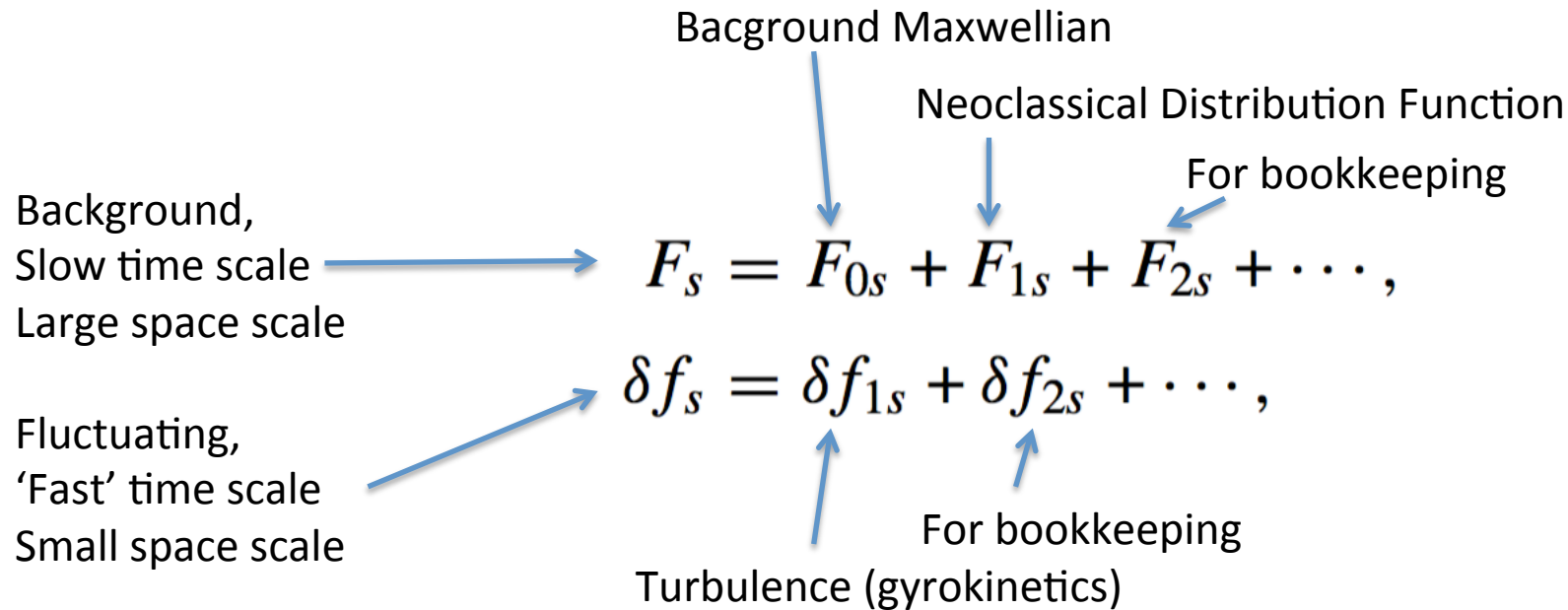
## Necessary Tool: Gyro-average

$$\langle g \rangle_R = \frac{1}{2\pi} \oint d\vartheta g(\mathbf{R}_s, \varepsilon_s, \mu_s, \vartheta, \sigma),$$

Averaging out the gyrophase angle eliminates this extremely fast time scale  
--very useful!



# Split the Distribution Function



$$F_{0s} \sim f_s, F_{1s} \sim \delta f_{1s} \sim \epsilon f_s, F_{2s} \sim \delta f_{2s} \sim \epsilon^2 f_s, \text{ etc.}$$



Now Expand in Terms of Our Ordering Scheme

$$\frac{df_s}{dt} = \frac{\partial f_s}{\partial t} + \dot{\mathbf{R}}_s \cdot \frac{\partial f_s}{\partial \mathbf{R}_s} + \dot{\mu}_s \frac{\partial f_s}{\partial \mu_s} + \dot{\epsilon}_s \frac{\partial f_s}{\partial \epsilon_s} + \dot{\vartheta} \frac{\partial f_s}{\partial \vartheta} = C[f_s] + S_s,$$




$$\frac{|\delta \mathbf{B}|}{|\mathbf{B}|} \sim \frac{|\delta \mathbf{E}|}{|\mathbf{E}|} \sim \frac{\delta f_s}{f_s} \sim \frac{k_{\parallel}}{k_{\perp}} \sim \frac{\omega}{\Omega_s} \sim \frac{\rho_s}{a} = \epsilon.$$

$$\frac{1}{\tau_E} \sim \frac{\chi_T}{a^2} \sim \frac{\omega}{\Omega_s} \left( \frac{\rho_s}{a} \right)^2 \Omega_s \sim \epsilon^3 \Omega_s$$

Solve order by order

## Some examples

$$\frac{df_s}{dt} = \frac{\partial f_s}{\partial t} + \dot{\mathbf{R}}_s \cdot \frac{\partial f_s}{\partial \mathbf{R}_s} + \dot{\mu}_s \frac{\partial f_s}{\partial \mu_s} + \dot{\varepsilon}_s \frac{\partial f_s}{\partial \varepsilon_s} + \dot{\vartheta} \frac{\partial f_s}{\partial \vartheta} = C[f_s] + S_s,$$




$$\frac{\partial f}{\partial t} = \frac{\partial F_0}{\partial t} + \frac{\partial F_1}{\partial t} + \frac{\partial \delta f_1}{\partial t} + \dots$$


Ordering in terms of  $\Omega F_0$ ?

## Some examples


$$\frac{df_s}{dt} = \frac{\partial f_s}{\partial t} + \dot{\mathbf{R}}_s \cdot \frac{\partial f_s}{\partial \mathbf{R}_s} + \dot{\mu}_s \frac{\partial f_s}{\partial \mu_s} + \dot{\epsilon}_s \frac{\partial f_s}{\partial \epsilon_s} + \dot{\vartheta} \frac{\partial f_s}{\partial \vartheta} = C[f_s] + S_s,$$




$$\frac{\partial f}{\partial t} = \frac{\partial F_0}{\partial t} + \frac{\partial F_1}{\partial t} + \frac{\partial \delta f_1}{\partial t} + \dots$$



$$\epsilon^3 \Omega F_0$$



$$\epsilon^4 \Omega F_0$$



$$\epsilon^2 \Omega F_0$$

## Some examples

$$\frac{df_s}{dt} = \frac{\partial f_s}{\partial t} + \dot{\mathbf{R}}_s \cdot \frac{\partial f_s}{\partial \mathbf{R}_s} + \dot{\mu}_s \frac{\partial f_s}{\partial \mu_s} + \dot{\epsilon}_s \frac{\partial f_s}{\partial \epsilon_s} + \dot{\vartheta} \frac{\partial f_s}{\partial \vartheta} = C[f_s] + S_s,$$

$$v_E \cdot \nabla f = v_E \cdot \nabla (F_0 + F_1 + \delta f_1 + \dots)$$

Note:

$v_E$  is perp to B

$$v_E \sim \epsilon v_{th}$$

$$v_E \cdot \nabla F_0 \rightarrow \epsilon v_{th} (1/a) F_0 \sim \epsilon^2 \Omega F_0$$

$$v_E \cdot \nabla F_1 \rightarrow \epsilon v_{th} (1/a) F_1 \sim \epsilon^3 \Omega F_0$$

$$v_E \cdot \nabla \delta f_1 \rightarrow \epsilon v_{th} (1/\rho) \delta f_1 \sim \epsilon^2 \Omega F_0$$

# Summary of Equations Order by Order

- In the following: lots of averaging, use of several identities, Boltzmann H-theorem, etc.
- 0<sup>th</sup> order: Background distribution function is independent of gyro-phase

$$\Omega_s \left. \frac{\partial F_{0s}}{\partial \vartheta} \right|_{\mathbf{R}_s, \mu_s, \varepsilon_s} = 0.$$

- First order: Background is a Maxwellian with density and temperature ‘flux functions’

$$F_{0s} = N_s(\psi(\mathbf{R}_s)) \left[ \frac{m_s}{2\pi T_s(\psi(\mathbf{R}_s))} \right]^{3/2} e^{-\varepsilon_s / T_s(\psi(\mathbf{R}_s))}.$$

- First order: fluctuating distribution function is made of two parts—Boltzmann response and a part that is gyro-phase independent (→ no fast time dependence in h!)

$$\delta f_{1s} = -\frac{Z_s e \delta \varphi'(\mathbf{r})}{T_s} F_{0s} + h_s(\mathbf{R}_s, \mu_s, \varepsilon_s, \sigma, t),$$



# Summary of Equations Order by Order

- Second order:

$$\frac{\partial h_s}{\partial t} + \left( \dot{\mathbf{R}}_s \cdot \frac{\partial}{\partial \mathbf{R}_s} + \dot{\mu}_s \frac{\partial}{\partial \mu_s} + \dot{\varepsilon}_s \frac{\partial}{\partial \varepsilon_s} \right) (F_{0s} + F_{1s} + h_s) = -\Omega_s \frac{\partial}{\partial \vartheta} (F_{2s} + \delta f_{2s}) + \frac{d}{dt} \left( \frac{Z_s e \delta \varphi'}{T_s} F_{0s} \right) + C[F_{0s} + F_{1s} + h_s],$$

- Gyro-averaging eliminates higher order distribution functions
- Average over fluctuations → drift-kinetic equation (neoclassical)
- Ampere's law with  $F_0$ ,  $F_1$  (e.g., bootstrap current): Grad-Shafranov

$$j = \frac{c}{4\pi} \nabla \times B, \quad j = \sum_s Z_s e \int d^3w w F_s,$$


 $\frac{1}{c} j \times B = \sum_s \nabla p_s$ 

 Macroscopic Equilibrium

# Gyrokinetic Equation:

## Describes the Time Evolution of **Guiding Centers**

### 5D instead of 6D

### No fast gyro-frequency time scales

- Second order:

$$\frac{\partial h_s}{\partial t} + \left( \dot{\mathbf{R}}_s \cdot \frac{\partial}{\partial \mathbf{R}_s} + \dot{\mu}_s \frac{\partial}{\partial \mu_s} + \dot{\varepsilon}_s \frac{\partial}{\partial \varepsilon_s} \right) (F_{0s} + F_{1s} + h_s) = -\Omega_s \frac{\partial}{\partial \vartheta} (F_{2s} + \delta f_{2s}) + \frac{d}{dt} \left( \frac{Z_s e \delta \varphi'}{T_s} F_{0s} \right) + C[F_{0s} + F_{1s} + h_s],$$

- Keep fluctuating part: gyrokinetic equation and again gyroaverage to eliminate  $f_2$  terms (note, I have simplified the following equation w.r.t. Abel 2013)

$$\frac{\partial}{\partial t} \left( h_s - \frac{Z_s e F_{0s}}{T_s} \langle \delta \phi \rangle_R \right) + (w_{||} \hat{b} + v_{Ds} + \langle v_E \rangle_R) \cdot \frac{\partial h_s}{\partial \mathbf{R}_s} + \langle v_E \rangle_R \cdot \nabla F_0 = \langle C_l[h_s] \rangle_R$$

Gyrokinetic Equation:  
Describes the Time Evolution of **Guiding Centers**  
5D instead of 6D  
No fast gyro-frequency time scales

$$\frac{\partial}{\partial t} \left( h_s - \frac{Z_s e F_{0s}}{T_s} \langle \delta \phi \rangle_R \right) + (w_{\parallel} \hat{b} + v_{Ds} + \langle v_E \rangle_R) \cdot \frac{\partial h_s}{\partial R_s} + \langle v_E \rangle_R \cdot \nabla F_0 = \langle C_l[h_s] \rangle_R$$

(electrostatic, no background flow)

$$\langle v_E \rangle_R = \frac{c}{B} \hat{b} \times \frac{\partial \delta \phi}{\partial R} \quad (\text{gyro-averaged ExB drift})$$

$$\mathbf{V}_{Ds} = \frac{\mathbf{b}}{\Omega_s} \times \left[ w_{\parallel}^2 \mathbf{b} \cdot \nabla \mathbf{b} + \frac{1}{2} w_{\perp}^2 \nabla \ln B \right]$$

Curvature drift

(Grad B drift)

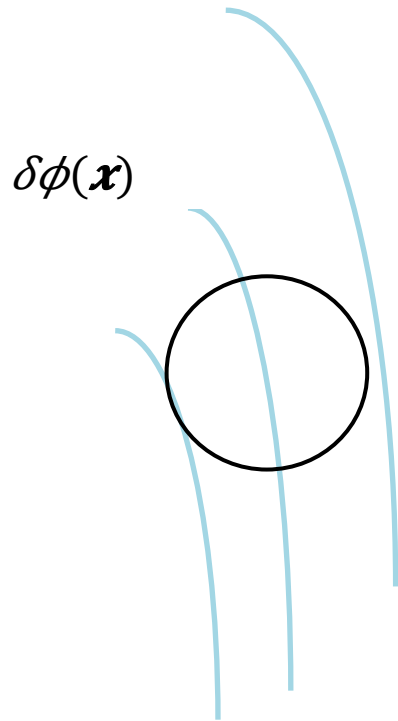
What's the meaning of the gyroaverages?



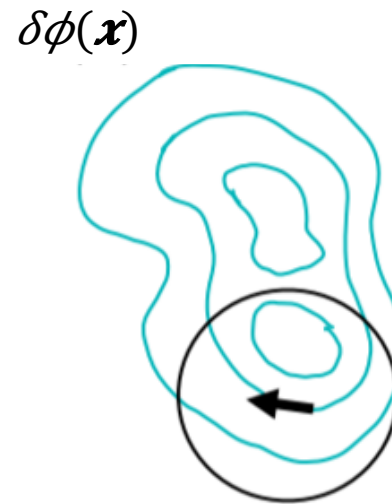
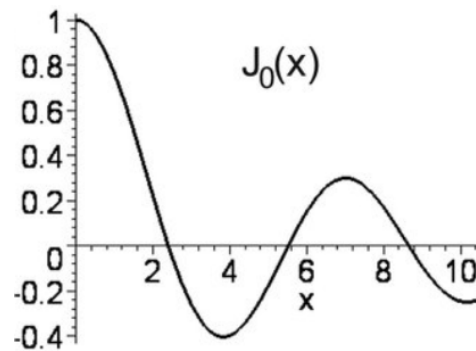
# Consequences of Gyroaveraging

In Fourier space ( $k$ ), gyroaverage operator  
Can be expressed as  $J_0(k \rho)$  (Bessel function)

$$\langle \delta\phi(R) \rangle_R \rightarrow J_0(k_\perp \rho) \delta\phi_k$$



Large scales:  $J_0(k \rho) \sim 1$




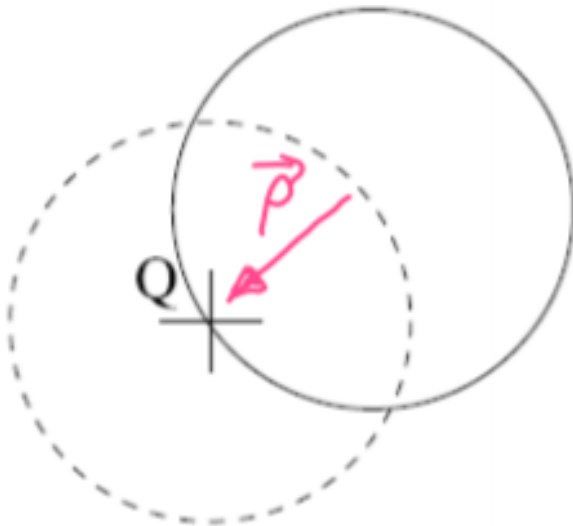
Small scales ( $k \rho \sim 1$ ):  $J_0(k \rho) \rightarrow 0$

→ Instabilities suppressed at scales much smaller than gyroradius

# GK Poisson Equation: Need Distribution Function for Particles (not gyro-centers) for Poisson Eqn.

For fields: need particle (not gyro center) distribution function  
→ Get particle distribution function

$$\sum_s \frac{Z_s^2 e^2 n_s \delta\varphi}{T_s} = \sum_s Z_s e \int d^3 w \langle h_s \rangle_r,$$




Gyroaverage at constant  
particle position  $r$

Get contribution of each gyrocenter  
with particles at location 'Q'

# What We Have Achieved with Gyrokinetics

- Extracted a rigorous equation for the fluctuations / turbulence
- This equation describes the guiding center distribution function
  - Gyro-average: removes fast gyro-frequency time scale
  - Exploits the anisotropy of the fluctuations (parallel vs perpendicular)
  - Big savings!
- Captures *all* the important micro-instabilities for a fusion plasma (ITG, TEM, ETG, MTM, KBM, RBM, drift Alfvén...)
  - (But this means some transparency is lost—may require some more work to understand physics)
- What's left out
  - Some MHD behavior (current-driven MHD instabilities, low  $n$  modes?)
  - Some fast particle instabilities
  - Anything with time scales faster than the gyro-frequency
    - Not much in a fusion plasma
    - But some space / astro waves (whistlers, fast Alfvén wave)
- Later discussion: in the edge 'transport barrier' some of these orderings are not as robust as they are in the main plasma (we'll talk about this later)

# Major Theoretical Speedups G.Hammett

relative to original Vlasov/Maxwell system on a naive grid, for ITER  $\rho_* = \rho/a \sim 1/1000$

- ❑ Nonlinear gyrokinetic equations
  - eliminate plasma frequency:  $\omega_{pe}/\Omega_i \sim m_i/m_e$   $\times 10^3$
  - eliminate Debye length scale:  $(\rho_i/\lambda_{De})^3 \sim (m_i/m_e)^{3/2}$   $\times 10^5$
  - average over fast ion gyration:  $\Omega_i/\omega \sim 1/\rho_*$   $\times 10^3$
  
- ❑ Field-aligned coordinates
  - adapt to elongated structure of turbulent eddies:  $\Delta_{||}/\Delta_{\perp} \sim 1/\rho_*$   $\times 10^3$
  
- ❑ Reduced simulation volume
  - ❑ reduce toroidal mode numbers (i.e., 1/15 of toroidal direction)  $\times 15$
  - ❑  $L_r \sim a/6 \sim 160 r \sim 10$  correlation lengths  $\times 6$
  
- ❑ Total speedup  $\times 10^{16}$
  
- ❑ For comparison: Massively parallel computers (1984-2009)  $\times 10^7$

# You'll Find Varying Notation for GK Equation; This is a Standard for GENE (in k space)

$$\frac{\partial g}{\partial t} = Z + \mathcal{L}[g] + \mathcal{N}[g], \quad \text{This notation puts all time derivatives on } g$$

$$\begin{aligned} \mathcal{L}[g] = & - \left( \omega_n + (v_{\parallel}^2 + \mu B_0 - \frac{3}{2}) \omega_{Tj} \right) F_{0j} i k_y \chi + \frac{\beta T_{0j}}{q_j B_0^2} v_{\parallel}^2 \omega_p \Gamma_{jy} - \frac{v_{Tj}}{J B_0} v_{\parallel} \Gamma_{jz} \\ & - \frac{T_{0j} (2v_{\parallel}^2 + \mu B_0)}{q_j B_0} (K_y \Gamma_{jy} + K_x \Gamma_{jx}) + \frac{v_{Tj}}{2 J B_0} \mu \partial_z B_0 \frac{\partial f_j}{\partial v_{\parallel}} + \langle C_j(f) \rangle, \end{aligned}$$

$$N[g] = \sum_{\vec{k}'_{\perp}} (k'_x k_y - k_x k'_y) \chi(\vec{k}'_{\perp}) g_j(\vec{k}_{\perp} - \vec{k}'_{\perp}),$$

$$\chi_j = \bar{\phi}_j - v_{Tj} v_{\parallel} \bar{A}_{1\parallel j}$$

$$f_j = g_j - \frac{2q_j}{m_j v_{Tj}} v_{\parallel} \bar{A}_{1\parallel} F_{0j}$$

$$\Gamma_{x,y} = i k_{x,y} g + \frac{q_j}{T_{0j}} F_0 i k_{x,y} \chi$$



Gamma is h from earlier slides

## Third Order: Transport Equations

- Third order: transport equation describing slow evolution of background

$$\frac{\partial F_s}{\partial t} + (\mathbf{u} + \mathbf{w}) \cdot \nabla F_s + \left[ \mathbf{a}_s - \frac{\partial \mathbf{u}}{\partial t} - (\mathbf{u} + \mathbf{w}) \cdot \nabla \mathbf{u} \right] \cdot \frac{\partial F_s}{\partial \mathbf{w}} + \left\langle \delta \mathbf{a}_s \cdot \frac{\partial \delta f_s}{\partial \mathbf{w}} \right\rangle_{\text{turb}} = C[F_s] + S_s,$$

$$\frac{\partial n_s}{\partial t} + \frac{1}{V'} \frac{\partial}{\partial \psi} (V' \langle \Gamma_s \rangle) = \langle S_n \rangle,$$

$$\Gamma \equiv \nabla \psi \cdot \int d^3 \mathbf{v} (\mathbf{v}_\chi \delta f_1 + \mathbf{v}_B \langle F_1 \rangle + \boldsymbol{\rho} C[\boldsymbol{\rho} \cdot \nabla f_0]),$$

$$\begin{aligned} \frac{\partial \bar{L}}{\partial t} + \sum_s \frac{1}{V'} \frac{\partial}{\partial \psi} (V' \langle \pi_s \rangle) \\ = \frac{1}{4\pi} \overline{\nabla \cdot \langle \delta \mathbf{B} \delta \mathbf{B} \cdot \nabla \phi R^2 \rangle} + \sum_s \langle S_{L_s} \rangle, \end{aligned}$$

$$Q \equiv \nabla \psi \cdot \int d^3 \mathbf{v} \frac{mv^2}{2} (\mathbf{v}_\chi \delta f_1 + \mathbf{v}_B \langle F_1 \rangle + \boldsymbol{\rho} C[\boldsymbol{\rho} \cdot \nabla f_0]),$$

$$\begin{aligned} \frac{3}{2} \frac{\partial p_s}{\partial t} + \frac{1}{V'} \frac{\partial}{\partial \psi} (V' \langle Q_s \rangle) \\ = -\langle H_s \rangle + \frac{3}{2} n_s \sum_u \nu_{su}^\varepsilon (T_u - T_s) + \langle S_p \rangle, \end{aligned}$$

$$\pi \equiv \nabla \psi \cdot \int d^3 \mathbf{v} (m R^2 \mathbf{v} \cdot \nabla \phi) \mathbf{v}_\chi \delta f_1,$$

## Example: Heat Flux

$$Q \equiv \nabla \psi \cdot \int d^3\mathbf{v} \frac{mv^2}{2} (\mathbf{v}_\chi \delta f_1 + \mathbf{v}_B \langle F_1 \rangle + \rho C[\rho \cdot \nabla f_0]),$$

- Classical collisional heat flux
- Most obvious / basic transport mechanism
- Step size = gyroradius
- Step time = inverse collision frequency
- Very high confinement time

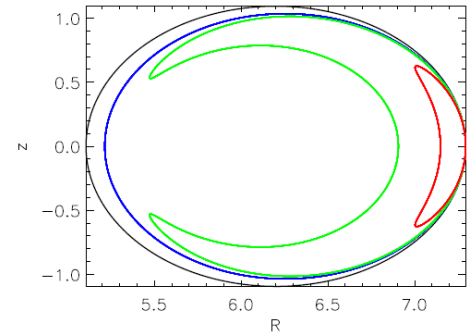
$$D = \rho_e^2 \nu_c \approx 10^{-3} m^2 s^{-1}$$

$$\text{Classical} \rightarrow \tau_E \approx 1000s$$

# Example: Heat Flux

$$Q \equiv \nabla \psi \cdot \int d^3\mathbf{v} \frac{mv^2}{2} (\mathbf{v}_\chi \delta f_1 + \boxed{\mathbf{v}_B \langle F_1 \rangle} + \rho C[\rho \cdot \nabla f_0]),$$

- **Neoclassical** collisional heat flux
- Classical (linear, not turbulent)
- Accounts for broad particle orbits, etc.
- Relevant in some parameter regimes
- Still very high confinement time



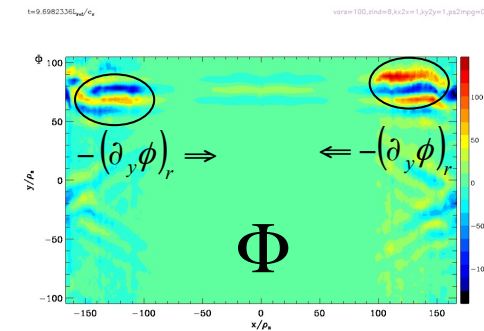
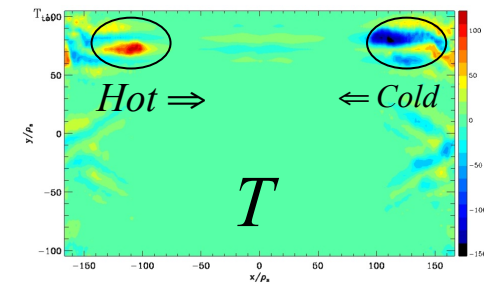
$$\tau_{E(neo)} \approx \frac{\tau_{E(classical)}}{100} \approx 10s$$



# Example: Heat Flux

$$Q \equiv \nabla \psi \cdot \int d^3\mathbf{v} \frac{m\mathbf{v}^2}{2} (\mathbf{v}_\chi \delta f_1 + \mathbf{v}_B \langle f_1 \rangle + \rho C [\rho \cdot \nabla f_0]), \Rightarrow$$

- **Turbulent** transport
- Advection of temperature fluctuations by velocity fluctuations
- Dominant transport mechanism in fusion devices
- Lower confinement time
  - ➔ Understanding and controlling plasma turbulence is a major part of fusion research



$x = \text{radial}$

Typical Fusion Parameters ➔

$$\tau_E \approx 0.1 - 1.0s$$

## End Result

- Starting from first principles kinetic equation
- Exploiting scale separation
- Arriving at a set of four equations that is still extremely close to first principles (in the core):
  - Grad-Shafranov for background equilibrium
  - Drift-kinetic for neoclassical (second order macroscopic distribution)
  - Gyro-kinetic for fluctuations (turbulence)
  - Transport equation for slow evolution of background profiles