

Medical Physics Dept., Veneto Institute of Oncology IOV – IRCCS, Padova

Automation in Planning A. Scaggion, PhD

School on Medical Physics for Radiation Therapy: Dosimetry and Treatment Planning for Basic and Advanced Applications

25 March – 5 April 2019 Trieste, Italy

Further information: Activity URL: http://indico.ictp.it/event/8651/ smr3278@ictp.it



Recent review articles with an extensive collection of literature

- M. Hussein et al, "Automation in intensity-modulated radiotherapy treatment planning - a review of recent innovations." *The British Journal of Radiology*, 20180270. (2018) <u>https://doi.org/10.1259/bjr.20180270</u>
- S. Breedveld et al, "Multi-criteria optimization and decision-making in radiotherapy", European Journal of Operational Research, 277(1): 1-19 (2019) <u>https://doi.org/10.1016/j.ejor.2018.08.019</u>
- P. Meyer et al, "Survey on deep learning for radiotherapy", Computers in Biology and Medicine, 98:126-146 (2018) <u>https://doi.org/10.1016/j.compbiomed.2018.05.018</u>
- A.M. Kalet et al, "Quality assurance tasks and tools: The many roles of machine learning." to be published in *Medical Physics*, <u>https://doi.org/10.1002/mp.13445</u>



RT planning is a complex non convex problem with a nonunique solution which is always been tackled with a trial-anderror approach



RT planning is a complex non convex problem with a nonunique solution which is always been tackled with a trial-anderror approach



Save time and money

EFFICACY

Achieve better quality (within center and across centers)

RUBUSTNESS

Reduce variability (standardization)

EDUCATION

Share knowledge



Outline

- Why we talk about quality and variability?
- Variability in Radiotherapy
 - does it really matter? reported negative outcomes
 - where does it come from? main causes and actors
 - how to tackle the problem? some general examples
- Variability in Treatment Planning
 - where does it come from? a closer look
 - automation can help with variability? some reported examples
- A clinical experience from Padova
 - Reduce inter- and intra-planner variability with a commercial knowledge-based planning solution
- Automation pitfalls and personal advices
- Conclusion

05/04/2019



Why we talk about quality and variability?

«In radiotherapy, and medicine in general, there is not a "gold" standard for the best treatment.»



ensure (and assess) quality of cancer care to each and every patient without distinction.



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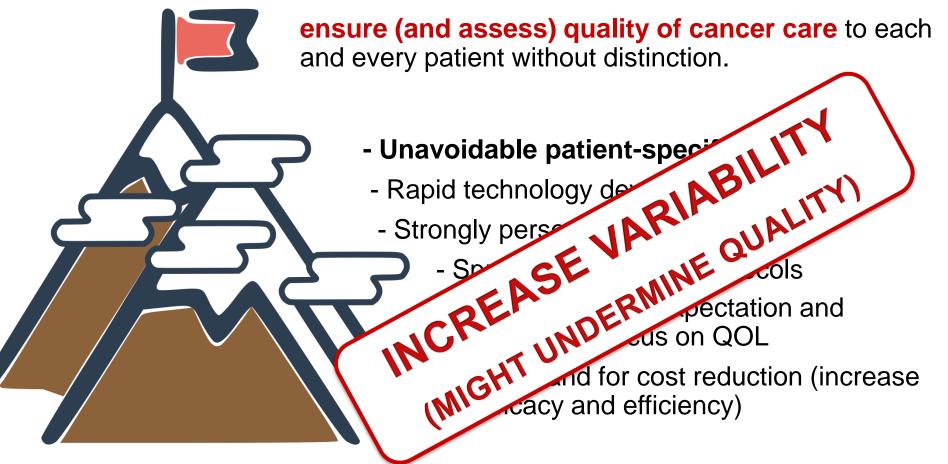
- Unavoidable patient-specific variability

- Rapid technology developments
- Strongly personalized treatments
 - Spread of treatment protocols
 - Increased life expectation and increased focus on QOL
 - Demand for cost reduction (increase efficacy and efficiency)



Why we talk about quality and variability?

«In radiotherapy, and medicine in general, there is not a "gold" standard for the best treatment.»





(TROG 02.02) «The impact of poor radiotherapy can greatly exceed the anticipated benefit of concurrent chemotherapy. [...]»

L.J. Peters, 2010 https://doi.org/10.1200/jco.2009.27.4498

(RTOG 9704) «Failure to adhere to specified RT guidelines was associated with reduced survival [...]»

R.A. Abrams, 2012 https://doi.org/10.1016/j.ijrobp.2010.11.039

«protocol-compliant RT may decrease failure rates and increase overall survival[...] » A. Fairchild, 2013 https://doi.org/10.1016/j.ijrobp.2013.03.036

«In clinical trials, RT protocol deviations are associated with increased risks of treatment failure and overall mortality. »

N. Ohri, 2013 https://doi.org/10.1093/jnci/djt001

«Plan quality deficiencies in RTOG 0126 exposed patients to substantial

excess risk for rectal complications.»

K.L. Moore, 2015 http://dx.doi.org/10.1016/j.ijrobp.2015.01.046

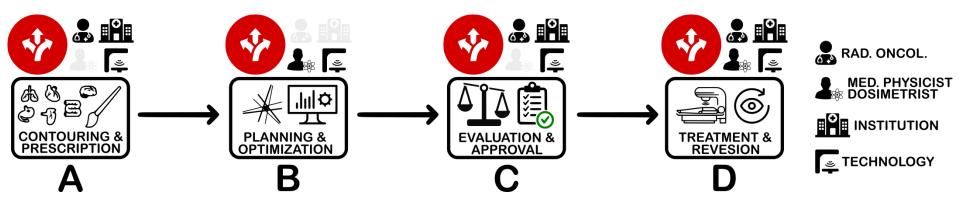
«Individualized QA indicated that OAR sparing could frequently be improved in EORTC-1219-DAHANCA-29 study plans, even though they met the trial's generic plan criteria.»

J.P. Tol, 2018 https://doi.org/10.1016/j.radonc.2018.10.005

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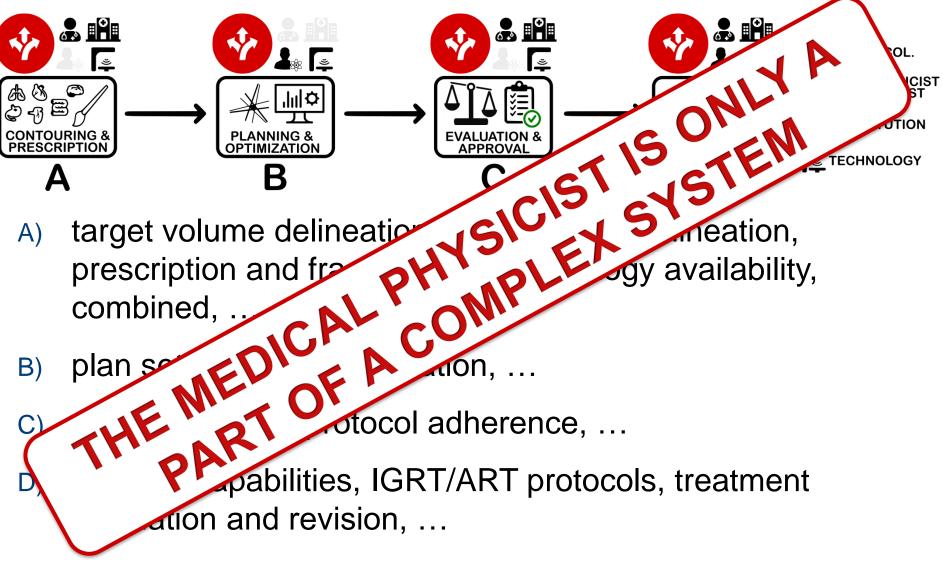
Causes and actors of RT variability



- A) target volume delineation, organ-at-risk delineation, prescription and fractionation, technology availability, combined, ...
- B) plan set-up, plan optimization, ...
- C) plan evaluation, protocol adherence, ...
- D) Imaging capabilities, IGRT/ART protocols, treatment evaluation and revision, ...



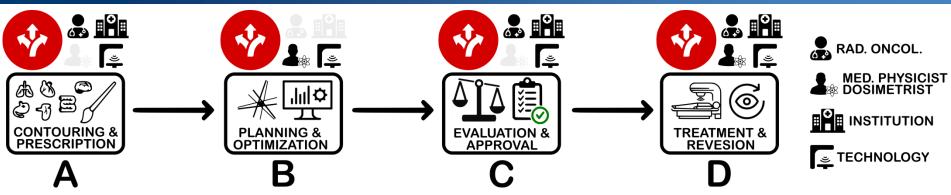
Causes and actors of RT variability



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Some examples of variability tackling



 A) draw local protocols, adherence to national/international standards, participation in Quality Assurance programmes, use of automatic or semiautomatic contouring solution, technological update, ...

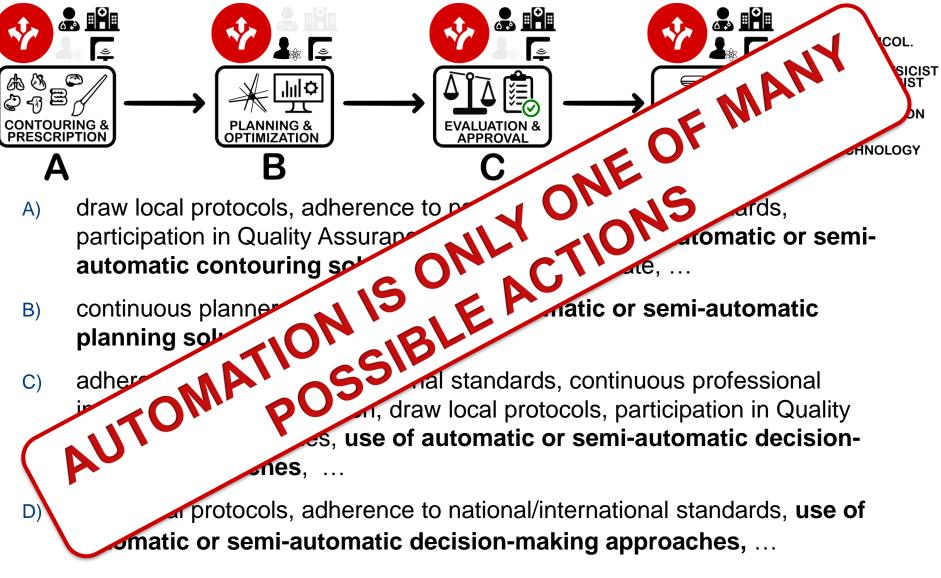
- B) continuous planners education, **use of automatic or semi-automatic planning solution**, ...
- C) adherence to national/international standards, continuous professional interaction and collaboration, draw local protocols, participation in Quality Assurance programmes, **use of automatic or semi-automatic decision-making approaches**, ...
- D) draw local protocols, adherence to national/international standards, **use of** automatic or semi-automatic decision-making approaches, ...

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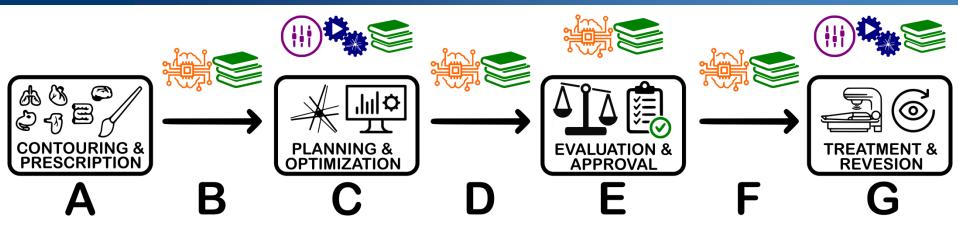
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Some examples of variability tackling





Can automation tailor variability in RT?



- A) OAR contouring (tumor contouring) and treatment definition
- B) spot possible unavoidable tradeoffs and tailor prescription to dose constraints
- C) drive optimization
- **D)** comparison to historical standards (within center QA)
- E) comparison to general standards (across center QA, automatic peer-revision)
- F) evaluate need for/benefit of replanning
- G) online/offline replanning



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Main causes of treatment planning variability







- Center experience and subspecialization (yearly patients income)
- Available technology
- Planner's expertise and planning skills

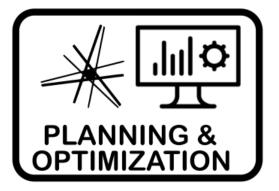
Mainly related to

- Differences in treatment set-up (technique and geometry)
- Difficulty to a priori asses the attainable tradeoff between the PTV coverage and OAR sparing
- Differences in planning priorities during optimization (different choices for OAR sparing)
- Clinical workload (time for planning and pressure on planner)

Whatever the strategy, planning automated solutions aim at:

- Reply a predefined scheme of actions or a result similar to prior ones (might not be the best path but at least reduces the possible paths followed in search for a solution)
- Tend to the better solution they know (might not be the best one but is at least the better)
- Reduce the time spent tackling single challenges (system set-up might be time demanding, but reduces time when you might be in a hurry)



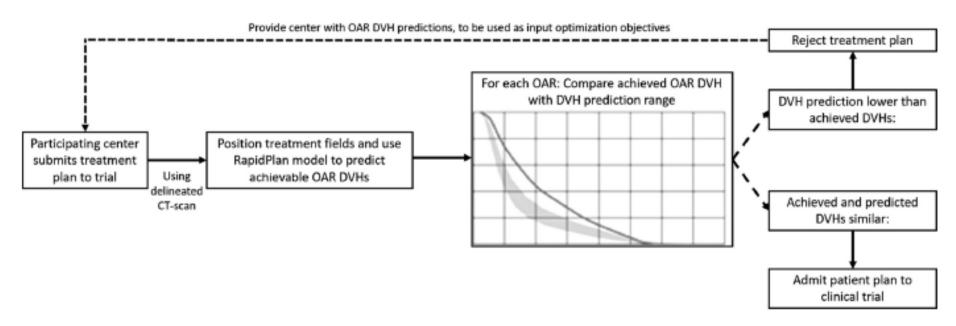


Single strategies might also:

- give you a bunch of possible good solutions (a posteriori MCO)
- be educational for the user (a posteriori MCO, KBP)
- be educational for others (KBP)
- be fairly automatic (PBAIO, a priori MCO),



- KBP model generated from a single well-trained institution
- KBP model used to predict and plan treatment for patients included in a previous clinical trial (EORTC-1219-DAHANCA-29)
- Proposal of an automated patient-specific QA workflow



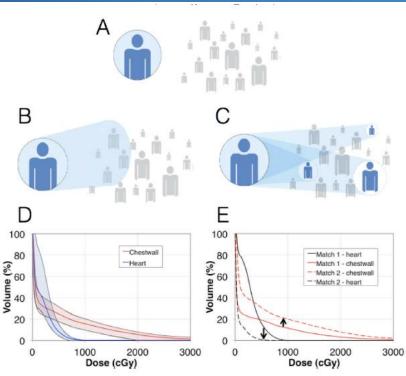
Such steps also have the potential to be largely automated.

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EX 2. Machine Learning for decision support G.Valdes et al Radiotherapy and Oncology 125(3), 392-397 (2017)

- The first artificial-intelligence based clinical decision support system (CDS) in radiation oncology
- CDS connects current assessments (patients) to past decisions (discrete treatment plans already treated)
- Past cases are collected and classified through: anatomical information, medical records, treatment intent, radiation transport
- A machine-learning algorithm is fed with these data
- For any new patient the "closer" and "more diverse" solution are proposed
- Clinicians can be informed of dose tradeoffs between critical structures early in the treatment process



- A) Standard treatment planning
- B) Knowledge-based planning
- c) Treatment plan outcome decision support enabled using treatment plan classification.
- D) DVH prediction provided by KBP
- E) DVH illustrating distinct tradeoffs provided by a classification technique.

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- Database of fully automated generated Pareto-optimal treatment plans with consistent priorities (a single wishlist).
- Plans used to train existing OVH model.
- OVH model applied to predict DVH as a QA tool.
- Database of Pareto-optimal treatment plans generated with fully automatic multi-criterial treatment planning variyng the priority list (N patients x M priority lists → NxM treatment plans)
- This dataset contains intrinsically effect of inter-organ dependency and dataset inconsistency.
- This database can be used to validate and characterize KBP prediction models (available upon request).



Ideal workflow:

- 1. Select and specify the model goal (site/disease, fractionation scheme, treatment technique, ...)
- 2. Gather all information (patients data, dicom data, ...)
- **3.** Populate the KBP database
- 4. Train and set-up the KBP model
- 5. Validate the KBP predictions
- 6. Use the KBP into the clinical environment



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6. Use KBP into the clinical environment

Our experience with prostate:

SYSTEM: Varian RapidPlan v13.5, initially then upgraded to v15.5

GOAL: Radical prostate only – 78Gy/39fx or 70Gy/28fx, only VMAT

PATIENT SAMPLE: in total ~120 patients

- ~100 used for model training (initially 60 then further collection) treated between 2014 and 2016
- after database cleaning only 82 used (because of deviations)
- 20 patients reserved for closed-loop validation

MODEL POPULATION: CTV, PTV, rectum, bladder, femoral head left and right separately (after a major revision penile bulb was added and femurs were merged)



MODEL TRAINING AND REFINEMENT:

1st APPROACH: After every training we:

- 1. Removed geometric outliers
- 2. Visually checked every other outlier and every single OAR largely over prediction
- 3. Re-planned under-optimized plans
- 4. Re-train the model and begin again,

Where/when should we stop?

How to cope with trade-offs? (KBP model is composed by as many models as OARs which do not take directly into account inter-organ dependencies) See Y. Wang et al *Phys. Med. Biol.* 61 4268–4282 (2016) and Y. Wang et al *Med. Phys.* 46 934-943 (2018) for a deeper perspective

How to thoroughly compare to competitive plans?



- PQM% (Plan Quality Metric) is a user-defined metric intended to quantify and compare plan quality
- PQM can be adjusted making use of a "feasibility" analysis built upon first principles to become APQM%

BE Nelms, Pract. Radiat. Oncol. 2:296-305 (2012)

S Ahmed, Med. Phys. 44:5486-5497 (2017)

It allows to rank plans (pertaining to same patient or different patients) following the user clinical practice and taking into account patient specific challenges

Raw PQM / Max PQM PQM (S	APGM (%) Pass/Fail	Settings			0.04	Distribution(s)	 Soft 	- 11 Je
125.03 / 150.00 83.4%	87,4%	Grace	100 🗧	% MORE	龋	跳湖	A ADDAN	att.
Plan Quality Metric Etimponent	Objective(s)	Result	Ra	w Score	Max Score	Performance	Planiq	Adjusted Performance
(PTV_5603) V[33.26y] (%)	× 90 [≥ 95]	99.8049	Q.	20.00	20	HOLO	S+ 100.	0%
(PTV_5600] V[53.2Gy] (%)	> 98 [2 100]	99.8049	Q,	11.61	12	96.7		N
(PTV_5600] V[58.8Gy] (%)	< 10 [s 0]	0.0000	Q,	5.00	5	100.0/	N 100	0%
(PTV_5600) D(0.03cc) (Gy)	< 61.6 (± 57)	58,1770	Q,	3.09	5	73.8	1 73.8	7 .
(CTV_5600) V[56.0Gy] (%)	> 94 [≥ 99]	100.0000	0,	12.00	12	100.0	> 100	0%
(PTV5040) Conformation Number (47.896y)	> 0.5 [2 1]	0.7546	Q.	5.02	4	75.5	1 -+ 75.0	% [Adjusted] [To Beseline: 3.99] [Planic Score]
(CTV_5040) v(50.4Gy] (%)	> 94 [2 99]	\$5.7737	9	5.91	12	49.3	s + 42.3	\$ *******
PTV5040-PTV5600[V[50.4Gy] (%)	> 90 [≥ 95]	94,1350	a,	19.14	20	95.7	N> 95.7	5
PTV5040-PTV5600[V[47.88Gy] (%)	> 98 ≥ 100]	99.2537	Q.	10.51	12	87.6	87.5	and the second sec
PTV3040-PTV5600] V[52.92Gy] (%)	< 50 [\$ 15]	17,4753	9	9.29	10	92.56	N 92.9	10 March 10
RECTUM_] V[50.4Gy] (%)	< 20 (≤ 0)	21.9355	Q.	0.00	6	0.0	100.	Dis [Adjusted] [To Baseline: 0.005 [Plank] Score]
RECTURAL VIALOGA (%)	< 60 (< 40)	29.07%7	0	1.09	6	1.1.4	a www.unu	The Ladjuster of Charlenne Applications and
[BOWEL_TOTAL] V[50.4Gy] (cc)	< 250 (s 160)	205.9657	Q,	2.94	6	48.9	5> 48.9	94
(8LADDER_] V(50.5Gy] (cc)	< 80 [≤ 50]	53.1413	0	3.58	4	69.5	N 89.5	S
(8LADDER_) V(40.0Gy) (%)	< 60 [5 40]	33.7554	9	4.00	4	100.0/	N 100	0%
[8M-PTV5040] V[20.0Gy] (%)	< 90 [≤ 75]	79.4550	Q.	2.11	3	70.1	N+ 713	\$
(PERIPHERAL_RING) V(40.0Gy) (cc)	< 100 (s 10)	16.0560	Q,	2.80	3	43.1	• 93.T	8
Global Max Location (ROI)	CTV_5600; PTV_5600 [CTV_5600]	PTV_3600	0.	2.00	3	66.7	N	x
[RECTUM_] Serial Slice Evaluation (28.0Gy]	PASS [PASS]	Pacc	0,	0.00	0	100,07	the	0%
(PTVS040) Volume of Regret (50.4Gy) (cc)	< 500 [≤ 100]	187,4030	0,	2.34	3	78.1	1 11 78.1	and the second second second second
Total [20 Metrics]		1		125.03	150.00	83.4	5> 87.A	% [Adjusted] [To Baseline 143.09]

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MODEL TRAINING AND REFINEMENT:

- 2nd APPROACH: Firstly we ranked all plans through a quantitative quality score (APQM%). After every training we:
 - 1. Removed geometric outliers (only if law-quality plans)
 - 2. Visually checked every other outlier and every single OAR largely over prediction
 - 3. Re-planned under-optimized plans (of lower-half of the rank) and re-ranked them
 - 4. Re-train the model and begin again

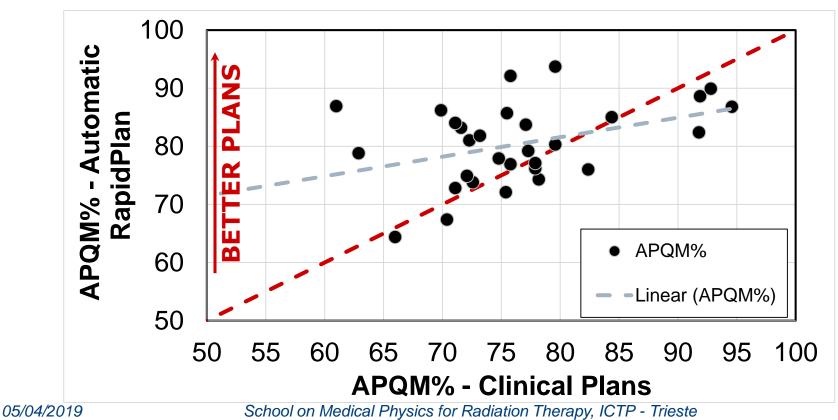
We stopped when there where no more plans lower than the initial first quartile

How to cope with trade-offs? PQM%

How to thoroughly compare to competitive plans? PQM%

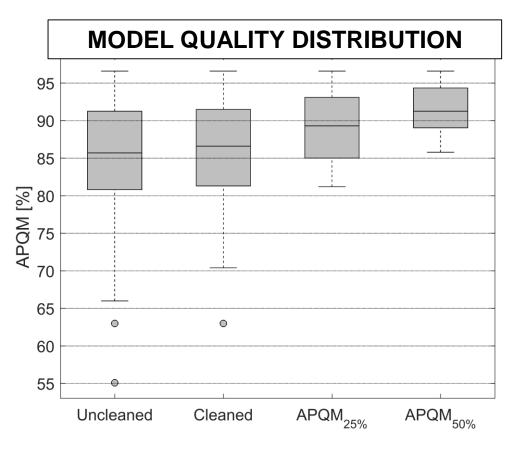


- To validate the model we automatically re-planned (without human interaction):
 - 20 randomly chosen patients within the model (closed-loop)
 - 20 patients outside the model (open-loop)



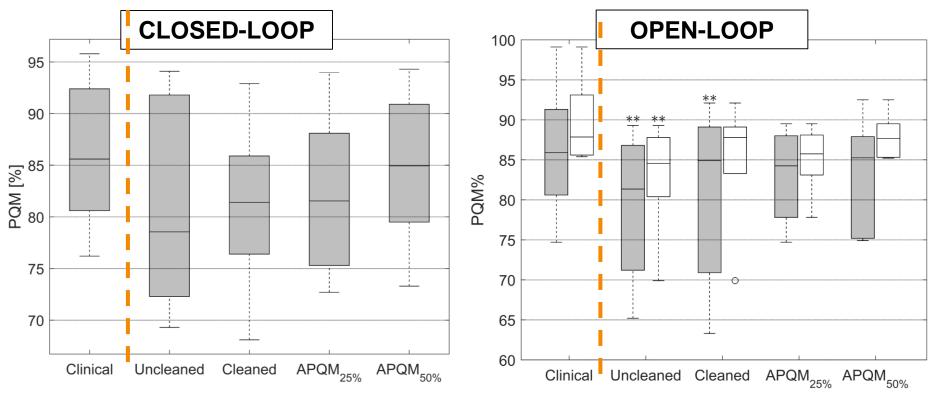


- APQM% scoring have been proposed as a tool to help a feed forward population, train and validation of a KBP model
- 4 KBP models compared:
 - Uncleaned: 80 patients no other refinement
 - Cleaned: outliers removed to lead 69 patients
 - APQM25%: 60 patients removed the lower quartile of APQM% ranking
 - APQM50%: 40 patients removed the lower half of APQM% ranking





- Open- and closed-loop validation of automatically optimized plans compared through PQM%
- RESULT: "Better plans in, better plans out", but pay attention to the width of the population



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PD experience - clinical impact of KBP (I) A. Scaggion et al. *Phys. Med.* **53**:86-93 (2018)

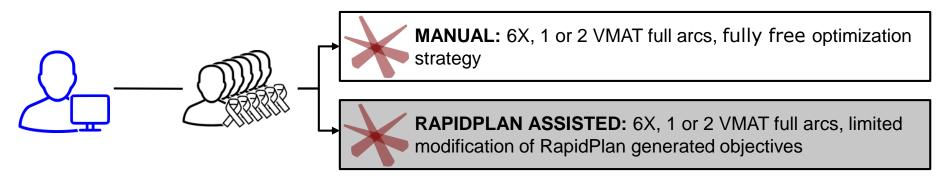
Varian RapidPlan v13.5 prostate model: 70 patients - prostate only - VMAT, validated through open-loop and closed-loop tests



15 patients used for prospective planning

7 planners: 6 resident operators + 1 internship student

Each operator planned twice the same 15 patients with and without RapidPlan assistance





PD experience - clinical impact of KBP (II) A. Scaggion et al. *Phys. Med.* **53**:86-93 (2018)

- The overall increase in plan quality is accompanied by a general reduction in its variability
- 11 out of 15 patients (73%) showed an increased mean quality (PQM%) and a reduced variability



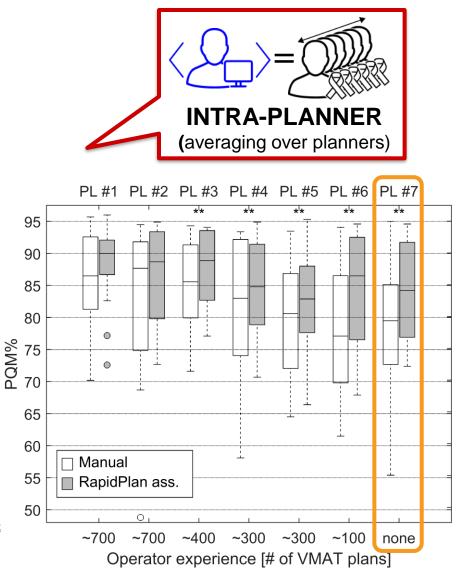
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IVIE	etric	Manual	RapidPlan	# of cases	p-value	90			0		HI				, Č					H	0
	V _{40Gy} [%]	11.69±3.71	6.45±3.34	14 (93%)	<0.001*	00		Å			Ļ		н					÷	-		-
Rectum	V _{60Gy} [%]	4.26±2.77	2.17±1.02	13 (86%)	0.002*	85	╶──└┛┊	Ť		Ц ¦									Ĥ	-	<u>_</u>
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	<d> [Gy]</d>	6.57±1.90	3.82±1.89	15 (100%)	<0.001*		0	Н		-	0	0					Ļ				.
	V _{40Gy} [%]	4.62±3.75	3.54±2.93	11 (73%)	0.107	% 75		<u>L</u> Ţ				Π÷			ļ		-				-
Bladder	V _{65Gy} [%]	1.42±1.19	1.14±0.89	10 (66%)	0.389	WOd 70	_	Ĺ				H			±			Ļ			
Bladdel	V _{75Gy} [cc]	1.26±0.69	1.12 ± 0.67	9 (60%)	0.330	Ш /0								\square		Н		÷ o	0		L I
	<d> [Gy]</d>	2.35±1.65	1.95±1.45	10 (66%)	0.277	65		0						H							
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Femur L	D _{1cc} [Gy]	5.66±2.33	2.76±1.57	13 (86%)	0.001*	55				n a	66										
	<d> [Gy]</d>	3.02±1.05	1.56±0.97	14 (93%)	0.001*		RapidPlan ass.													ľ	
PQM%		8.32±4.19	4.73±3.79	12 (80%)	0.046*	50											1		1		
							1	2	3	4	5	6	7 Pa	8 atier	9 nts	10	11	12	13	14	15



PD experience - clinical impact of KBP (III) A. Scaggion et al. *Phys. Med.* **53**:86-93 (2018)

- Significant increase of overall quality for 5 out of 7 planners
- Internship student raised to the level of a medium experienced planner
- Intra-planner variability shows a reduction for all planners but #6
- The overall reduction is statistically significant (p-value=0.033).
- Similar results have been found by Wang in 2017 for left-side breast cancer

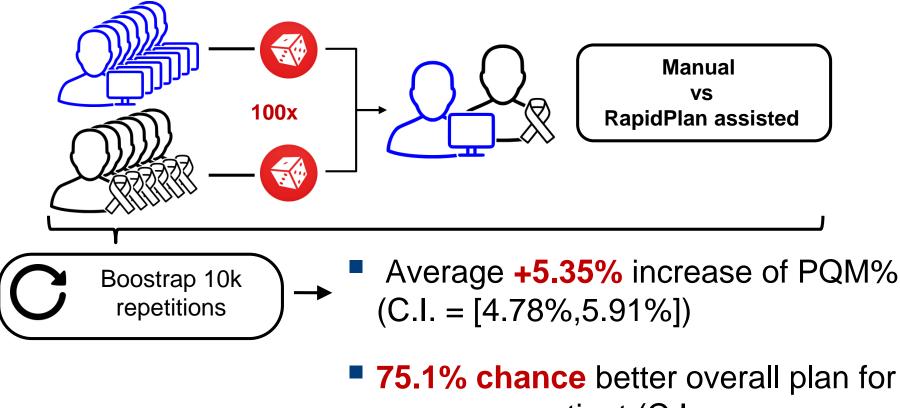
J Wang, 2017 https://doi.org/10.1186/s13014-017-0822-z





PD experience - clinical impact of KBP (IV) A. Scaggion et al. *Phys. Med.* **53**:86-93 (2018)

Clinical impact simulation based on bootstrap technique



every new patient (C.I. = [72.3%,77.8%]).



- The automated system you will have tomorrow will be based on the knowledge you have today! Start today to collect data as methodically and tidy as you can and to reduce variability as much as you can!
- Every automated process is the outcome of a lengthy and demanding effort to build it. The effort you save tomorrow is worth the effort you spend today.
- At the moment most of the automated planning solution still require a certain degree of human interaction. Some room for variability still remains.
- An automated planning solution leaves you more room to improve not more time to pursue your own business (disengaging is dangerous)
- Solutions based on prior knowledge require to gather large amount of cases. A lot of tasks that single centers can not undertake alone (pediatrics, rare disease, ultra-specific treatments, ...) and, in my opinion, should not undertake alone.

05/04/2019



Conclusion

- Automation in planning is accomplished through different strategies but all of them has the intrinsic capability to improve quality and limit variability.
- SMALL SCALE: Automation narrows the space for human failure (planner interaction).
- LARGE SCALE: Automation opens the possibility to global improvement through large collaboration (multi-center shared libraries, patient-specific QA, …)
- In Padova we need approximately 18 months to set-up the first RapidPlan model. Most of them spent to deeply understand the tool.
 - hands-on experience is beneficial and crucial
 - set-up is a trial-error process based on human interaction (pay attention to your own decision)
 - KBP useful to increase quality and train new human resources





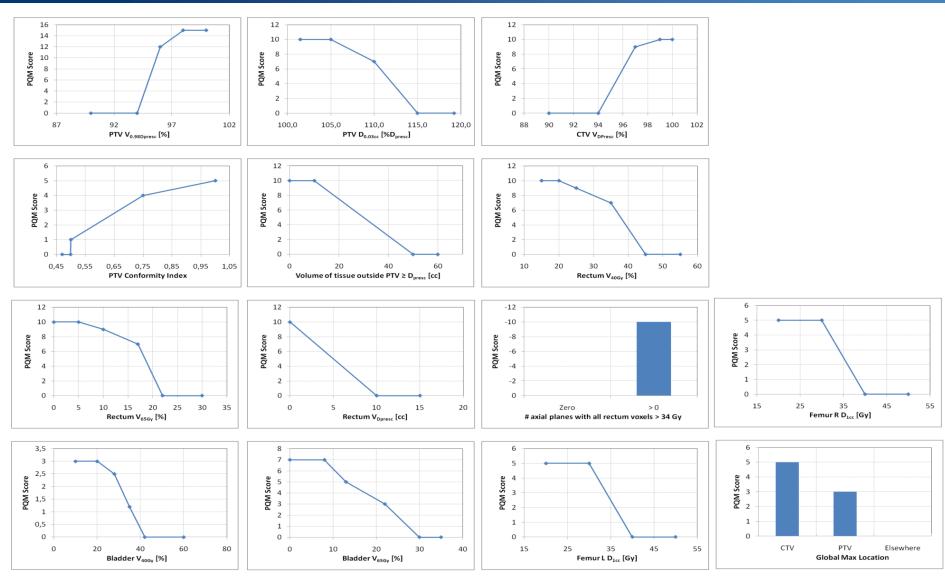


PD experience - Plan Quality Metric (I)

Churchten	Matria	Metric Definition						
Structure	Metric	Definition	Min	Max				
PTV	V _{0.98Dpresc} [%]	Percent of PTV volume ≥ 98% of the prescription dose	0	15				
PTV	D _{0.03 cc} [Gy]	Dose [Gy] covering highest 0.03 cc of PTV	0	10				
CTV	V _{Dpresc} [%]	Percent of CTV volume ≥ prescription dose	0	10				
PTV	Conformity index	(PTV V _{95%} [cc]) ² / (PTV total volume [cc] * 0.98D _{presc} isosurface volume [cc])	0	5				
Body - PTV	V _{Dpresc} [%]	Volume [cc] of tissue outside PTV ≥ D _{presc}	0	10				
Rectum	V _{40Gy} [%]	Percent of rectum volume ≥ 40 Gy	0	10				
Rectum	V _{65Gy} [%]	Percent of rectum volume ≥ 65 Gy	0	10				
Rectum	V _{Dpresc} [cc]	Volume [cc] of rectum \geq Dpresc	0	10				
Rectum	Serial rectum	Number of axial planes with all rectum voxels exceeding 34 Gy	-10	0				
Bladder	V _{40Gy} [%]	Percent of bladder volume ≥ 40 Gy	0	3				
Bladder	V _{65Gy} [%]	Percent of bladder volume ≥ 65 Gy	0	7				
Femur R	D _{1 cc} [Gy]	Dose [Gy] covering highest 1 cc of right femour	0	5				
Femur L	D _{1 cc} [Gy]	Dose [Gy] covering highest 1 cc of left femour	0	5				
	Global maximum location	Anatomic location of global maximum: CTV, PTV or elsewhere	0	5				
Total			-10	105				
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PD experience - Plan Quality Metric (II)



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46% plans unequivocal better sparing, 11% plans unequivocal worse sparing

Metric			Man	iual	RapidPla			
IWE	uic	Endpoint	mean ± std	[min;max]	mean ± std	[min;max]		p-value
	D _{98%}		98.5 ± 0.3	[97.5;98.9]	98.6 ± 0.3	[96.9;99.3]	::	0.441
ΡΤΥ	D _{2%}		105.6 ± 0.9	[103.7;109.4]	105.8 ± 1.0	[103.6;109.6]	<u></u>	0.618
	HI		7.12 ± 1.16	[5.03;11.80]	7.21 ± 1.25	[4.46;12.68]	<u> </u>	0.837
	CI		1.00 ± 0.02	[0.97; 1.10]	0.99 ± 0.02	[0.97;1.06]	—	0.089
	V _{40Gy} [%]	<= 45	30.43 ± 10.13	[11.39;58.07]	26.38 ± 8.60	[9.42;50.12]	÷	<0.001*
Rectum	V _{60Gy} [%]	<= 25	13.94 ± 6.33	[3.13;34.43]	11.31 ± 4.98	[3.42;25.69]	$\overline{\ominus}$	<0.001*
	V_{75Gy} [cc]	<=10	2.38 ± 1.84	[0.03;10.09]	2.24 ± 1.62	[0.04;7.80]		0.059
	<d> [Gy]</d>		31.03±6.35	[18.90;46.07]	29.16±5.38	[19.18;41.29]	÷	<0.001*
	V _{40Gy} [%]	<=40	24.17 ± 10.38	[7.38;52.22]	23.41 ± 9.69	[7.49;44.23]	:	0.091
Bladder	V _{65Gy} [%]	<=25	10.75 ± 5.19	[3.75;23.50]	10.37 ± 4.92	[3.65;22.19]	:	0.118
	V_{75Gy} [cc]	<=10	13.19 ± 6.01	[4.55;32.99]	12.83 ± 5.80	[4.78;33.99]	<u></u>	0.136
	<d> [Gy]</d>		24.43±8.50	[8.35;41.59]	24.04±8.32	[8.99;39.24]	:	0.149
Femur R	D _{1cc} [Gy]	<=45	29.67±8.50	[20.41;43.59]	26.68±3.35	[8.99;39.24]	÷	<0.001*
	<d> [Gy]</d>		14.00±4.68	[7.28;21.12]	13.01±2.57	[8.17;18.62]	$\overline{\ominus}$	<0.001*
Femur L	D_{1cc} [Gy]	<=45	30.29±5.23	[18.79;45.18]	27.95±3.68	[18.29;37.03]	÷	<0.001*
	<d> [Gy]</d>		14.58±3.14	[6.70;23.24]	13.68±2.68	[7.06;21.36]	÷	<0.001*