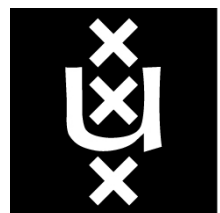


Strong Gravitational Lensing Systems with Machine Learning: first results on Dark Matter substructures

Marco Chianese

Advanced Workshop on Accelerating the Search
for Dark Matter with Machine Learning

8-12 April 2019, Trieste



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Dark Matter substructures

In Λ CDM model, structures are formed hierarchically from the collapse of small-scale fluctuations. Their formation depends on the **coldness of dark matter** that provides a halo mass cut-off:

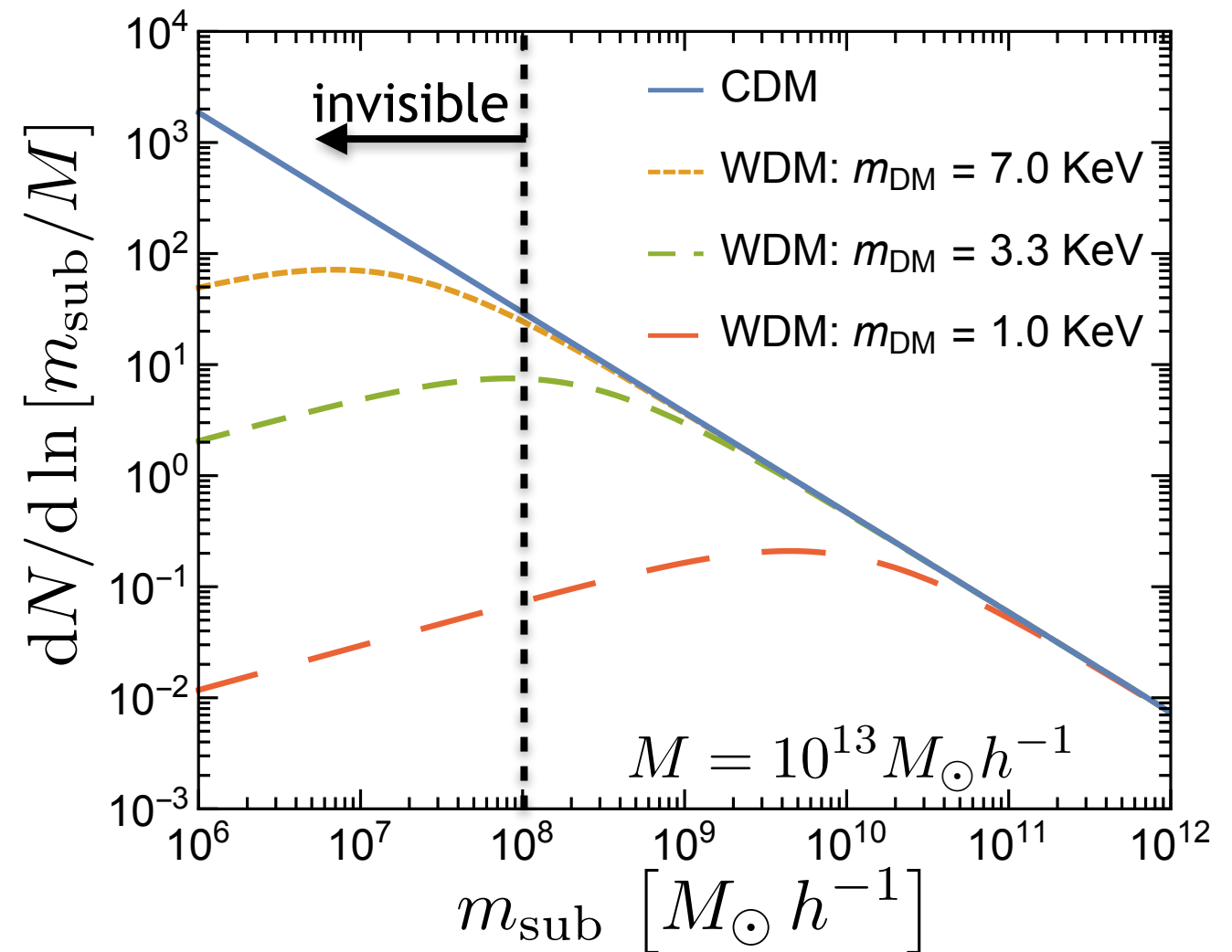
$$M_{\text{cut}} = 10^{10} \left(\frac{m_{\text{MD}}}{1 \text{ KeV}} \right)^{-3.33} M_{\odot} h^{-1}$$

A key quantity is the subhalo mass function:

$$\frac{dN}{d \ln \xi} = (1+z)^{1/2} A_M \xi^{\alpha} \exp(-\beta \xi^3) \left(1 + \frac{M_{\text{cut}}}{M} \xi \right)^{\gamma} \quad \text{where } \xi = m_{\text{sub}}/M$$

Cold DM

Warm DM



Gao et al., MNRAS 455 (2004)
 Giocoli et al., MNRAS 404 (2010)
 Gao et al., MNRAS 410 (2011)

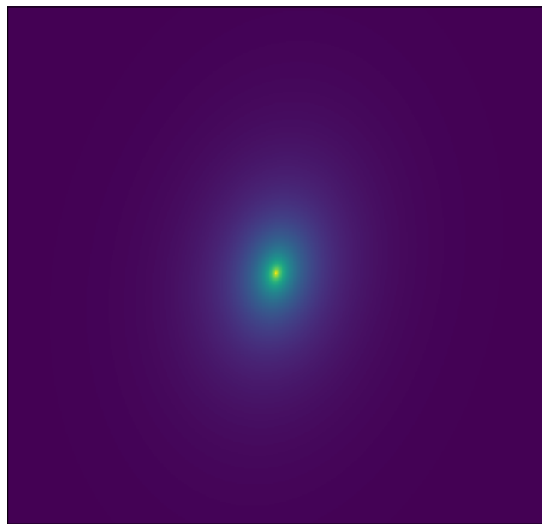
Schneider et al., MNRAS 424 (2012)
 Lovell et al., MNRAS 439 (2014)
 Han et al., MNRAS 457 (2016)

Despali and Vegetti, MNRAS 469 (2017)
 Gilman et al., arXiv:1901.11031
 Ando et al., arXiv:1903.11427

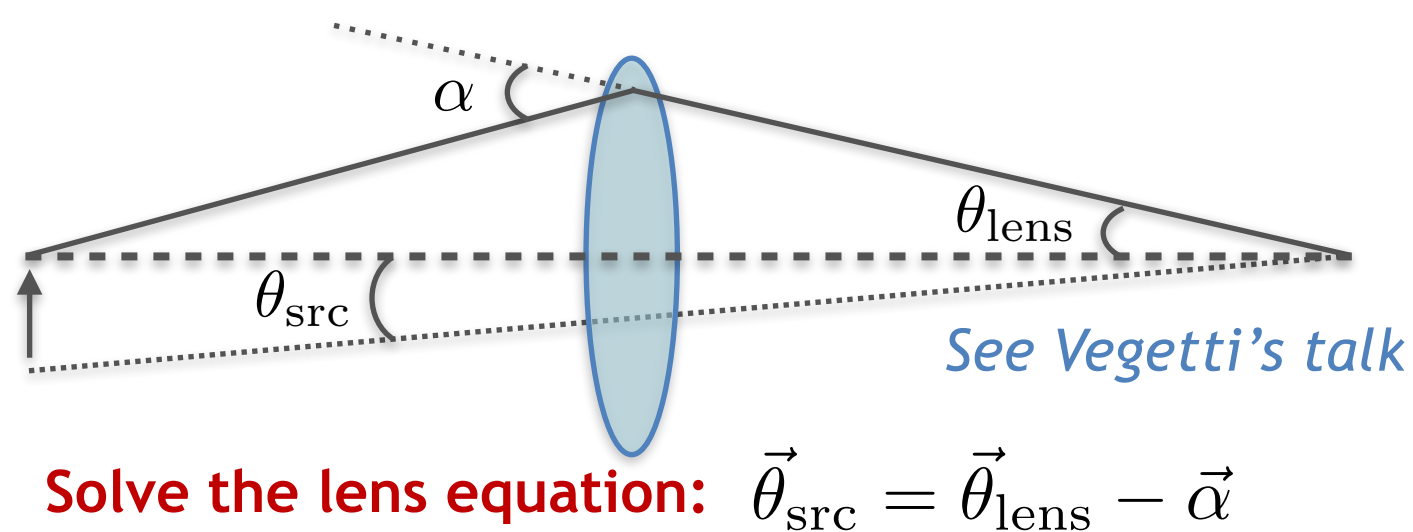
Strong Gravitational Lensing

We want to infer at the same time the structure of the background source galaxy and the total mass distribution (gravitational potential) of the foreground lens galaxy.

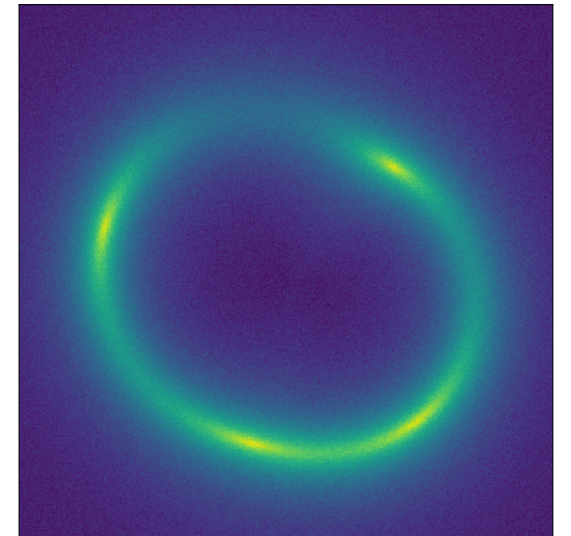
Source



Main Lens

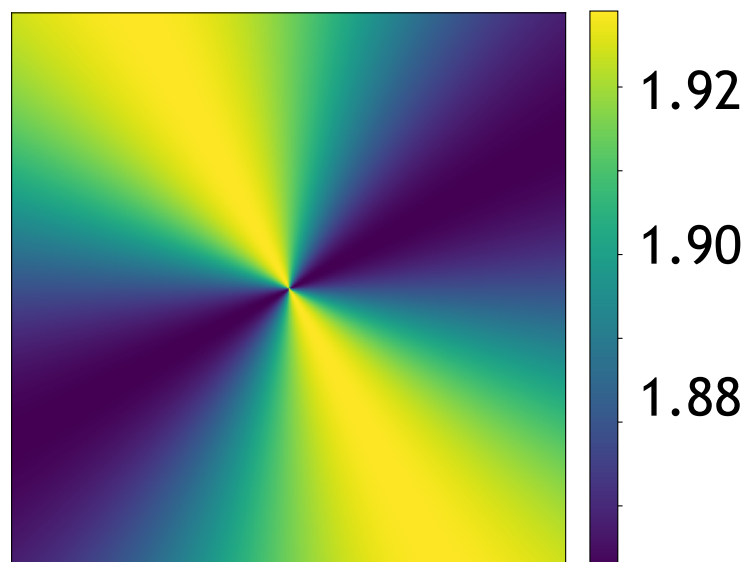


What we observe

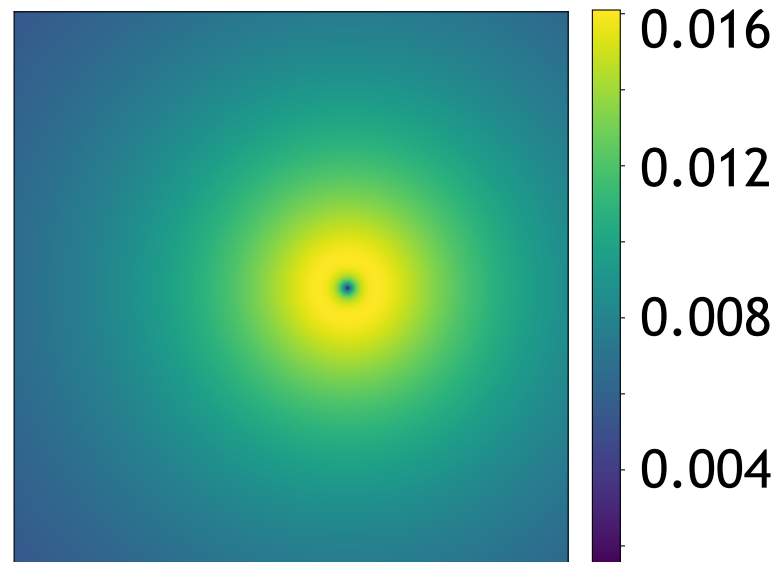


The effect of dark matter subhaloes is subdominant and localized w.r.t. the main halo.

Deflection due to main halo



Deflection due to subhalo



$$m_{\text{sub}} = 10^{10} M_{\odot}$$



$$\Delta\alpha \sim 0.9\%$$

Analysis pipeline



Two methods have been exploited so far:

Parametric models

- **Pros:** analytical models that depend on a set of parameters (Sersic profile).
- **Cons:** oversimplified models that do not cover all the realistic galaxies with complex morphology (bulge, disk, ...).

Non-parametric models

- **Pros:** more freedom due to image reconstruction pixel by pixel.
- **Cons:** no *a priori* information from real galaxies and regularization according to some criteria (like smoothness).

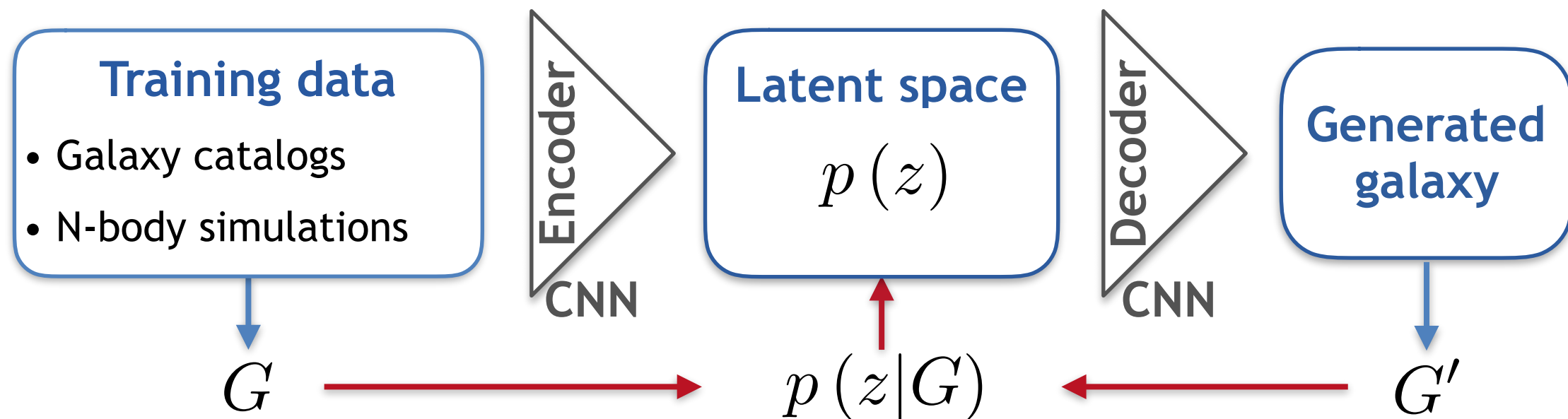
Koopmans, MNRAS 363 (2005)
Vegetti and Koopmans, MNRAS 392 (2009)

Analysis pipeline



We adopt **generative models** as **Variational AutoEncoder** to model the surface brightness of the source galaxy.

See Coogan's talk!



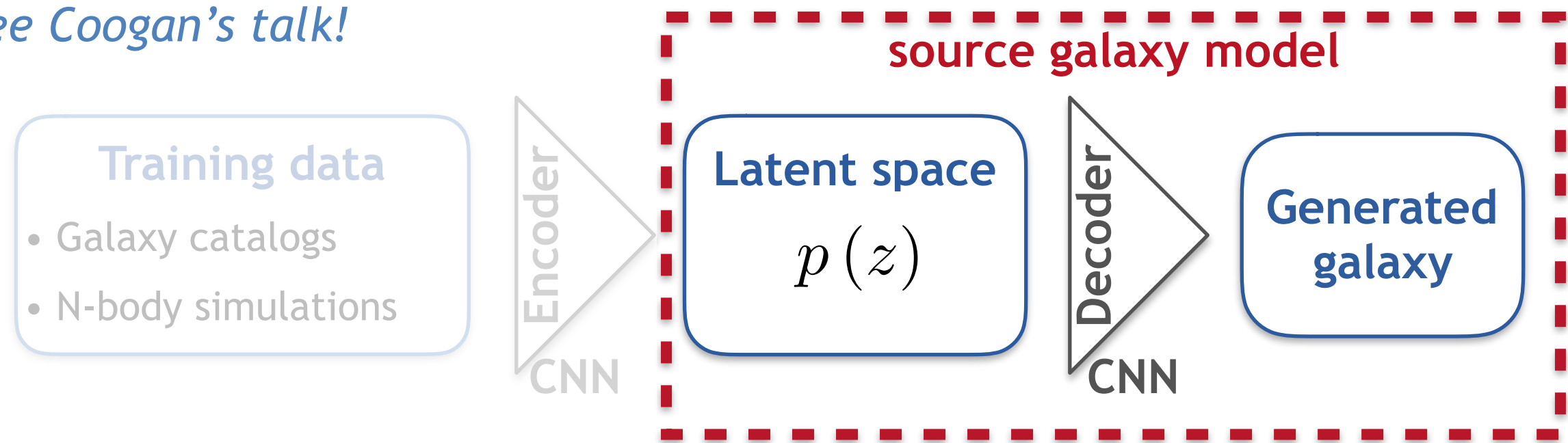
See also Hendriks' talk!

Analysis pipeline



We adopt **generative models** as **Variational AutoEncoder** to model the surface brightness of the source galaxy.

See Coogan's talk!



See also Hendriks' talk!

Analysis pipeline



① Define a pixel grid according to the observed image

② Compute the total projected mass (main lens + subhaloes)

$$\kappa_{ij} = \kappa_{\text{ml}}(\theta_{ij}^x, \theta_{ij}^y) + \kappa_{\text{sub}}(\theta_{ij}^x, \theta_{ij}^y) + \dots$$

③ Compute the displacement field via a 2-dimensional convolution

$$\alpha(\vec{\theta}) = \int \kappa(\vec{\theta}') F(\vec{\theta} - \vec{\theta}') d^2\vec{\theta}'$$

with $F(\vec{\theta} - \vec{\theta}') = \frac{1}{\pi} \frac{\vec{\theta} - \vec{\theta}'}{|\vec{\theta} - \vec{\theta}'|^2}$

Discrete convolution $\alpha_{ij} = \sum_{i'j'} F[i - i', j - j'] \kappa[i', j']$

④ Add the external shear contribution

$$\alpha_{ij}^x = \alpha_{ij} + \alpha_{ij}^{\text{ext}}$$

$$\alpha_{ij}^y = \alpha_{ij} + \alpha_{ij}^{\text{ext}}$$



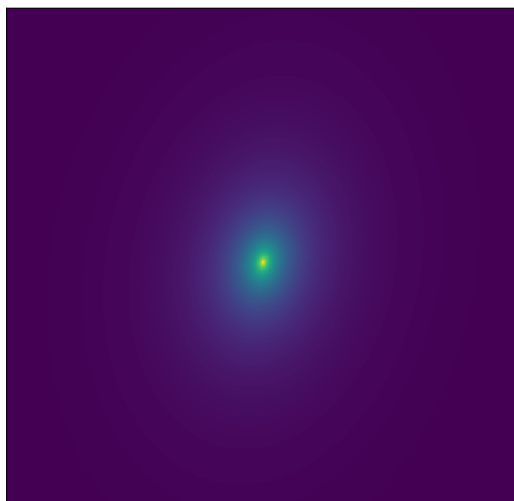
Total displacement field

Analysis pipeline

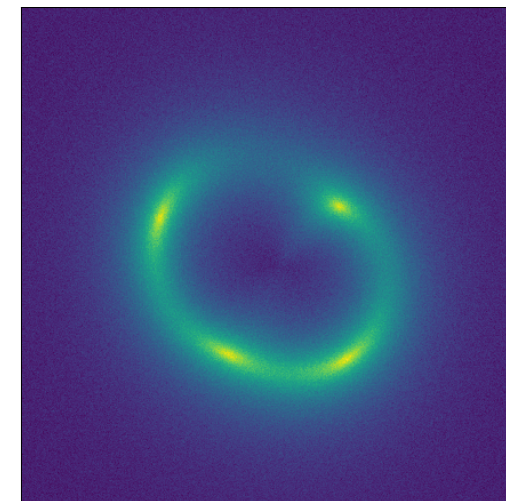


- ① Compute the brightness in the lens plane

$$f_{\text{src}}(\tilde{\theta}_{ij}^x, \tilde{\theta}_{ij}^y)$$



$$f_{\text{src}}(\theta_{ij}^x - \alpha_{ij}^x, \theta_{ij}^y - \alpha_{ij}^y)$$



Lens
equation →

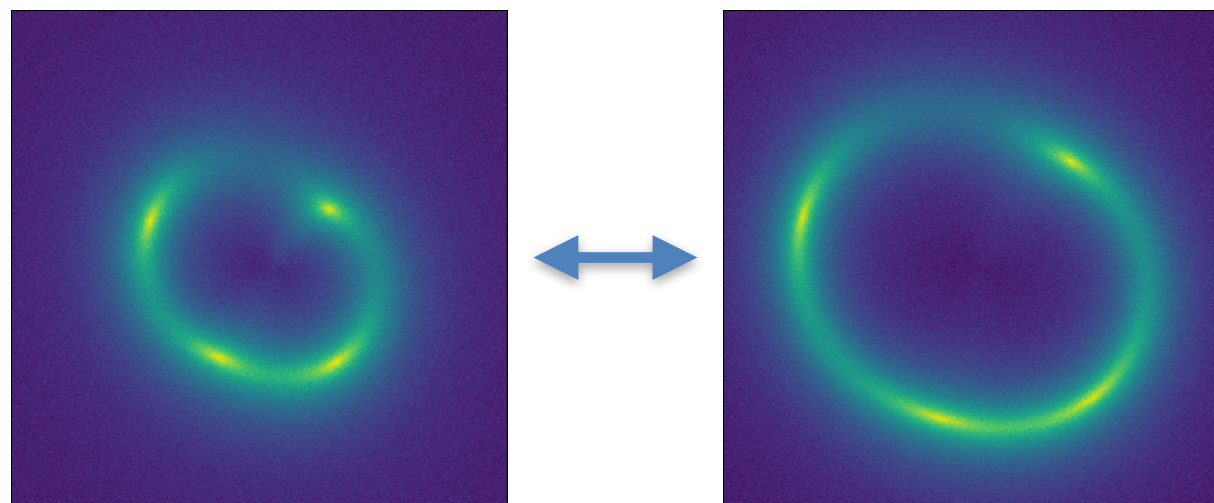
- ② Apply Point Spread Function (PSF)

- ③ Add Gaussian noise

Analysis pipeline



Loss/Score



(model)

(data)

Posteriors

$$p(x|D) \sim p(D|x) p(x)$$

Priors: $p(x) = p(x_{\text{src}}) p(x_{\text{lens}})$

Sampling techniques with gradient descent

- Hamiltonian Monte Carlo (HMC)
- Stochastic Variational Inference (SVI)

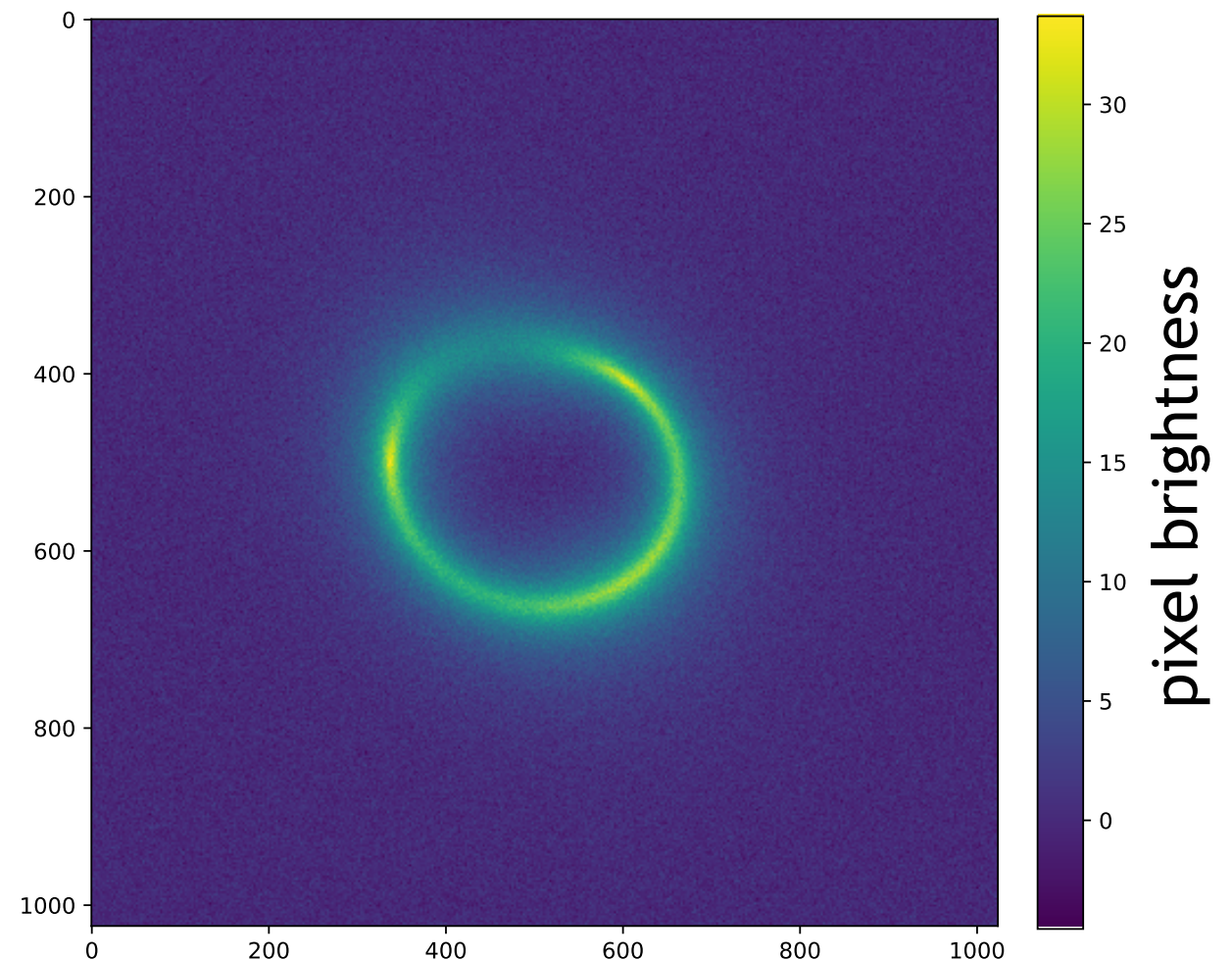
PYTORCH + 

See Thomas and Weniger's talks

Pipeline test

In order to test our Bayesian inference pipeline, we generate and analyze mock data.

- **Optical image:** area of 10×10 arcsec² with 1024×1024 pixels.
- **Source:** analytical Sersic profile.
- **Main lens:** Singular Power-Law Ellipsoid plus external shear.
- **Subhaloes:** 1 truncated NFW.
- **Total number of parameters:**
 $13 + 4$ (subhalo) = 17



Due to the presence of several local minima in the 17-dimensional space, we perform:

- **Optimization:** find the best initial values for the parameters by means of SVI with guide

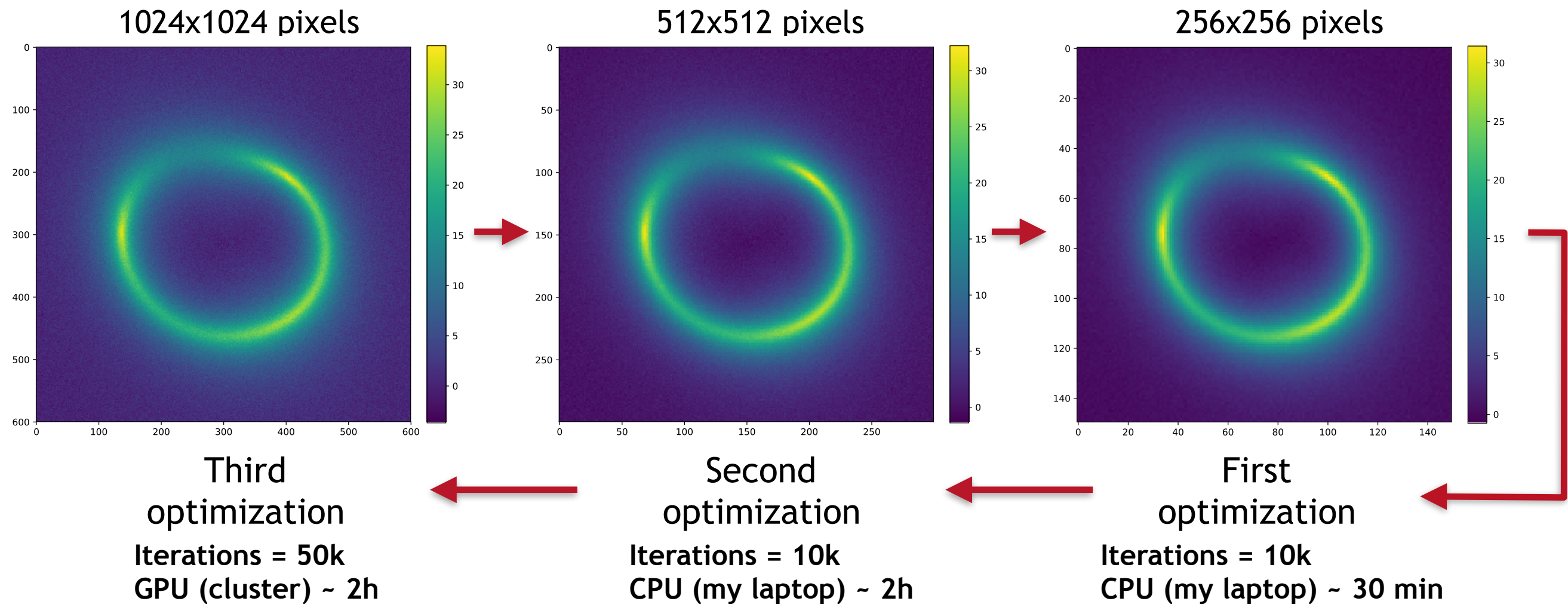
$$q_{\theta}(x) = \delta(x - \theta)$$

- **Bayesian inference:** obtain the parameters' posteriors by means of HMC

Optimization

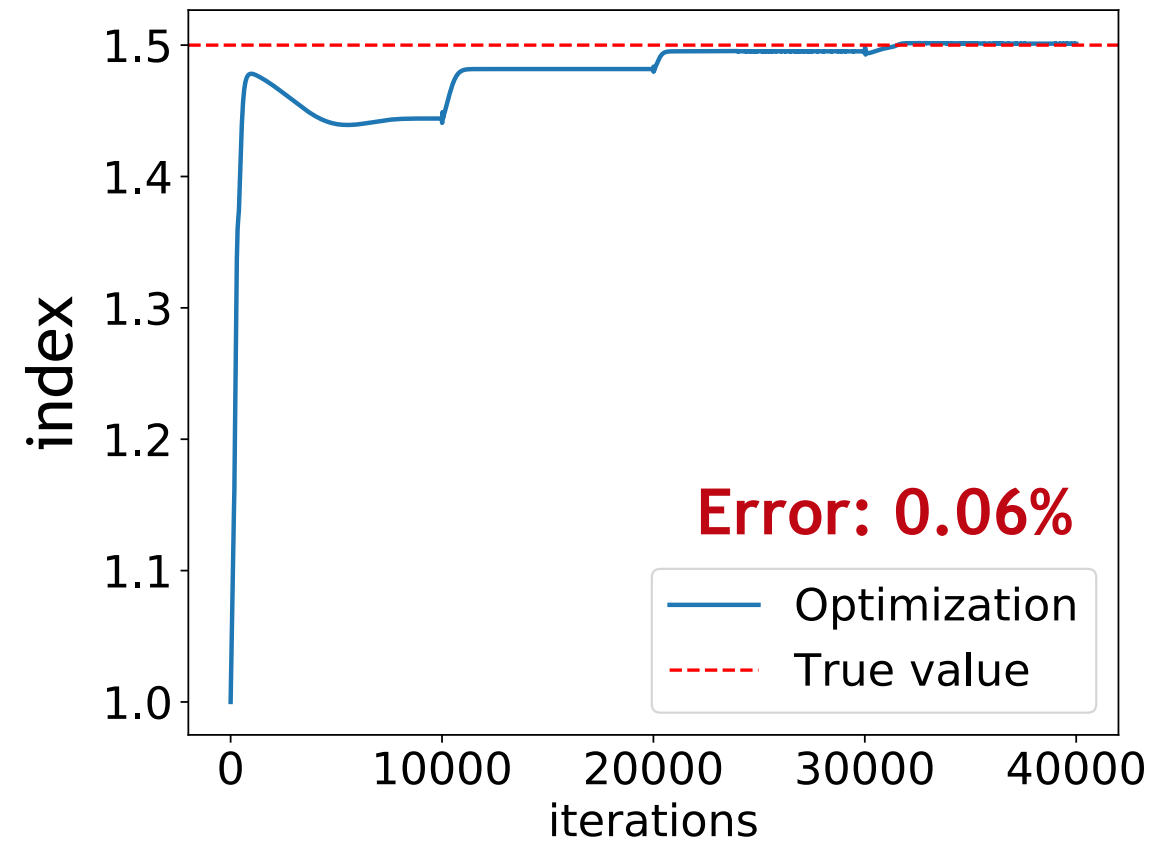
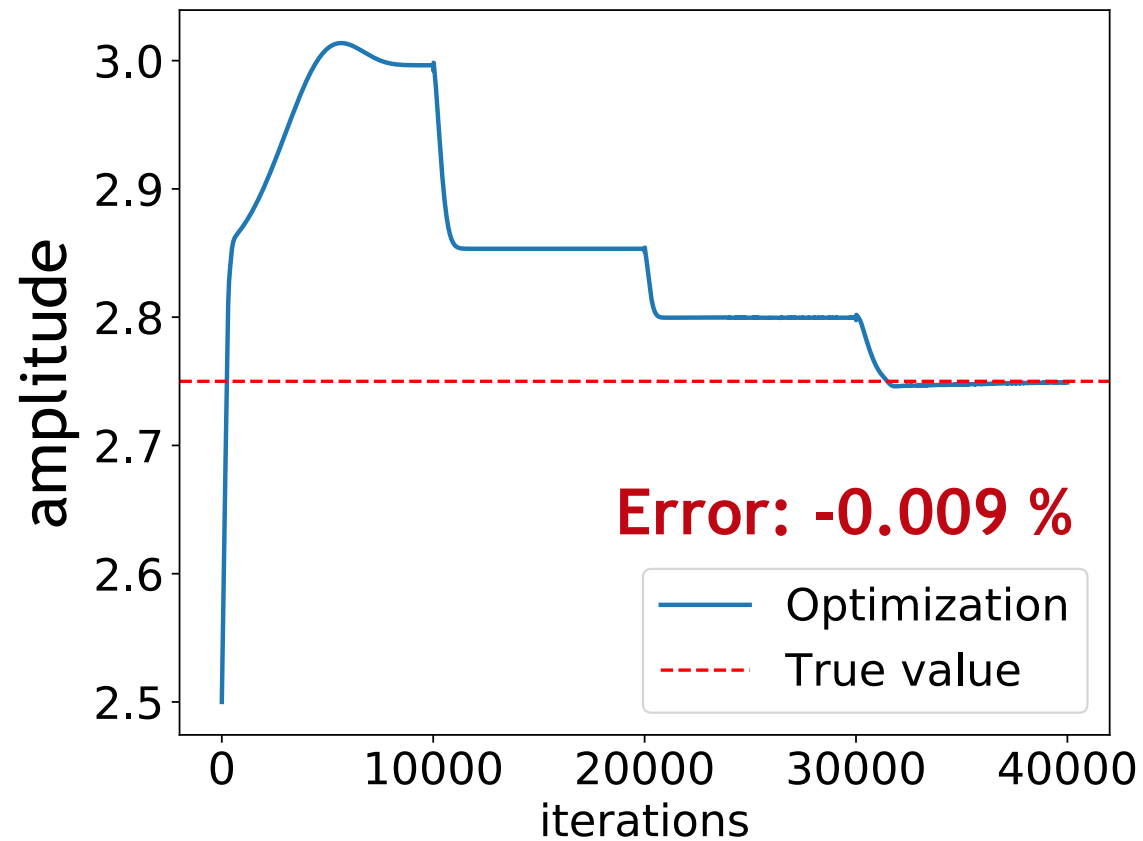
The optimization is based on the following steps:

1. **Hierarchical modeling**: start with a lensing model without including the substructure.
2. **Down-sampling**: consider a smaller image.

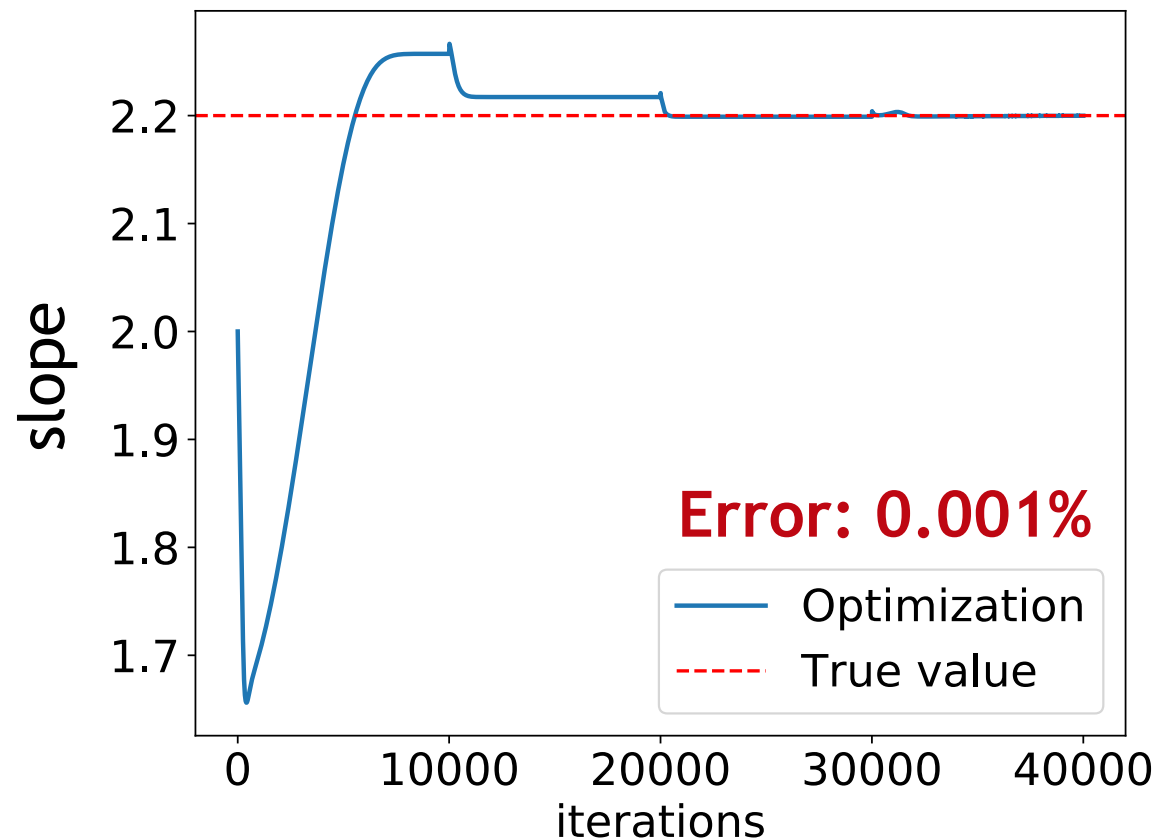
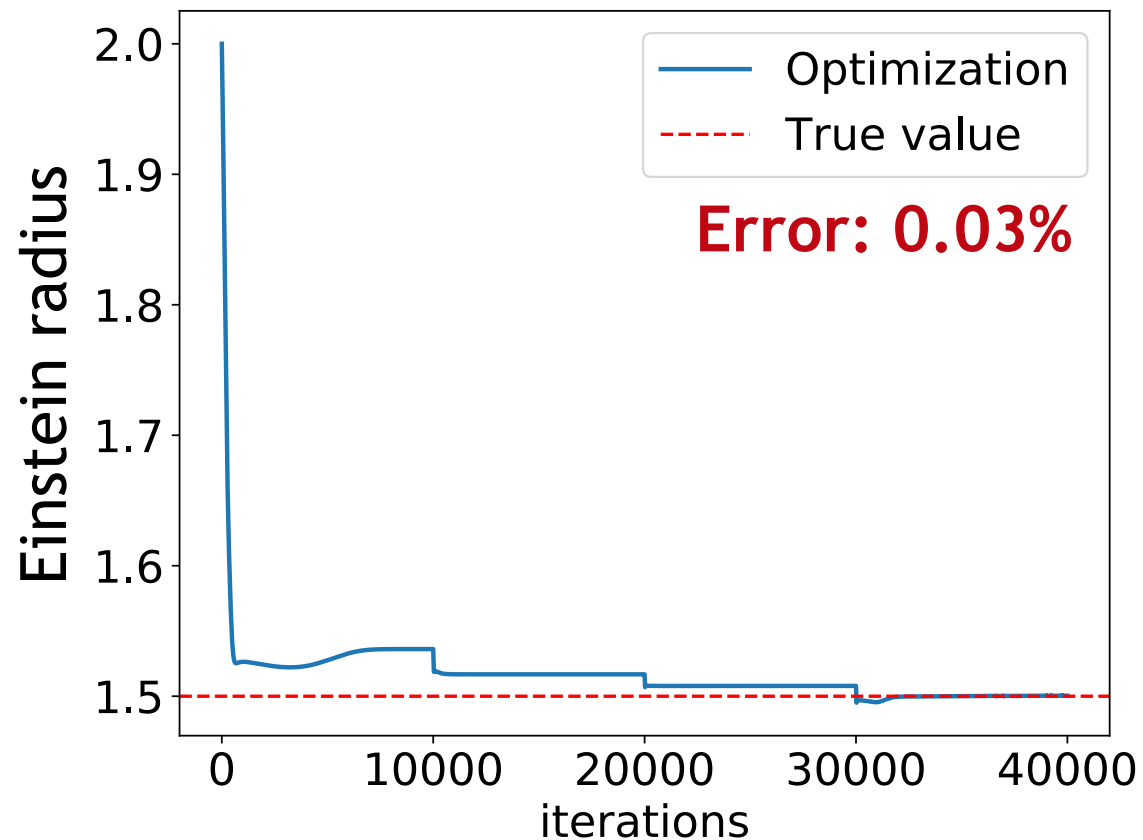


3. **Including the substructure**: perform the last optimization with the substructure.

Optimization: results

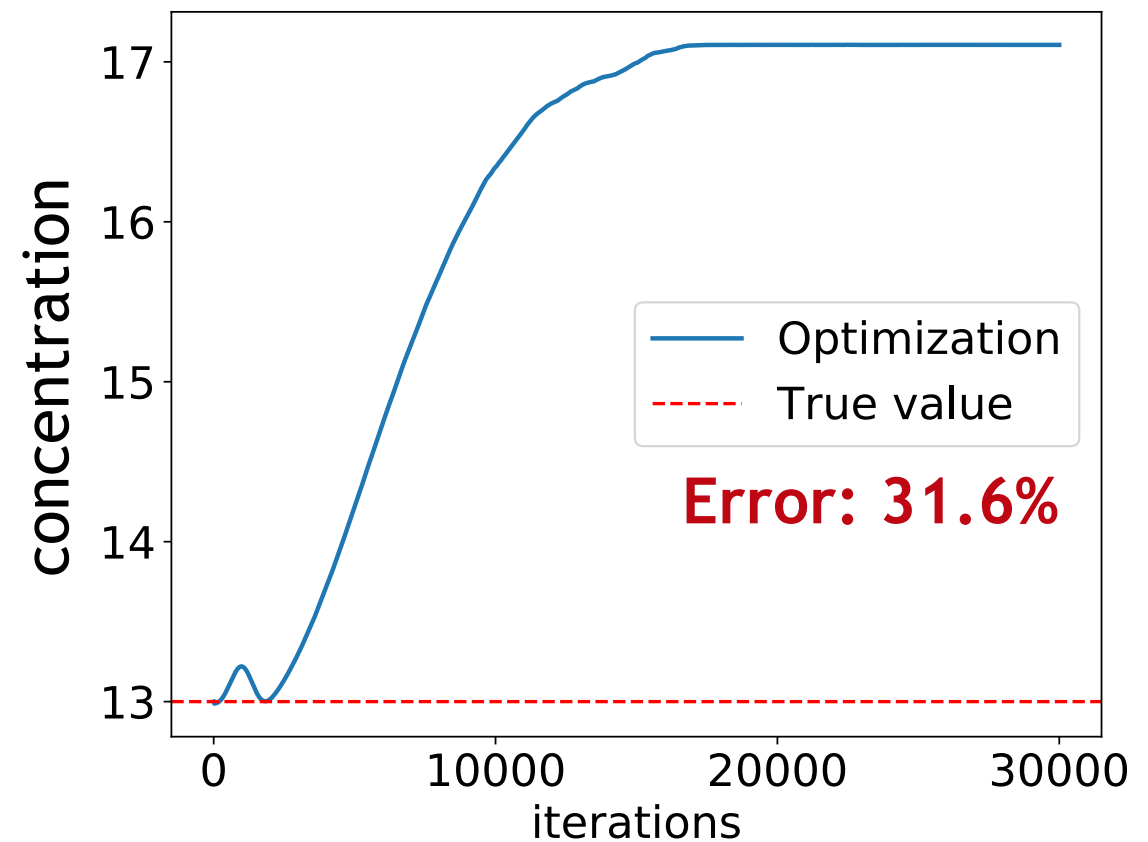
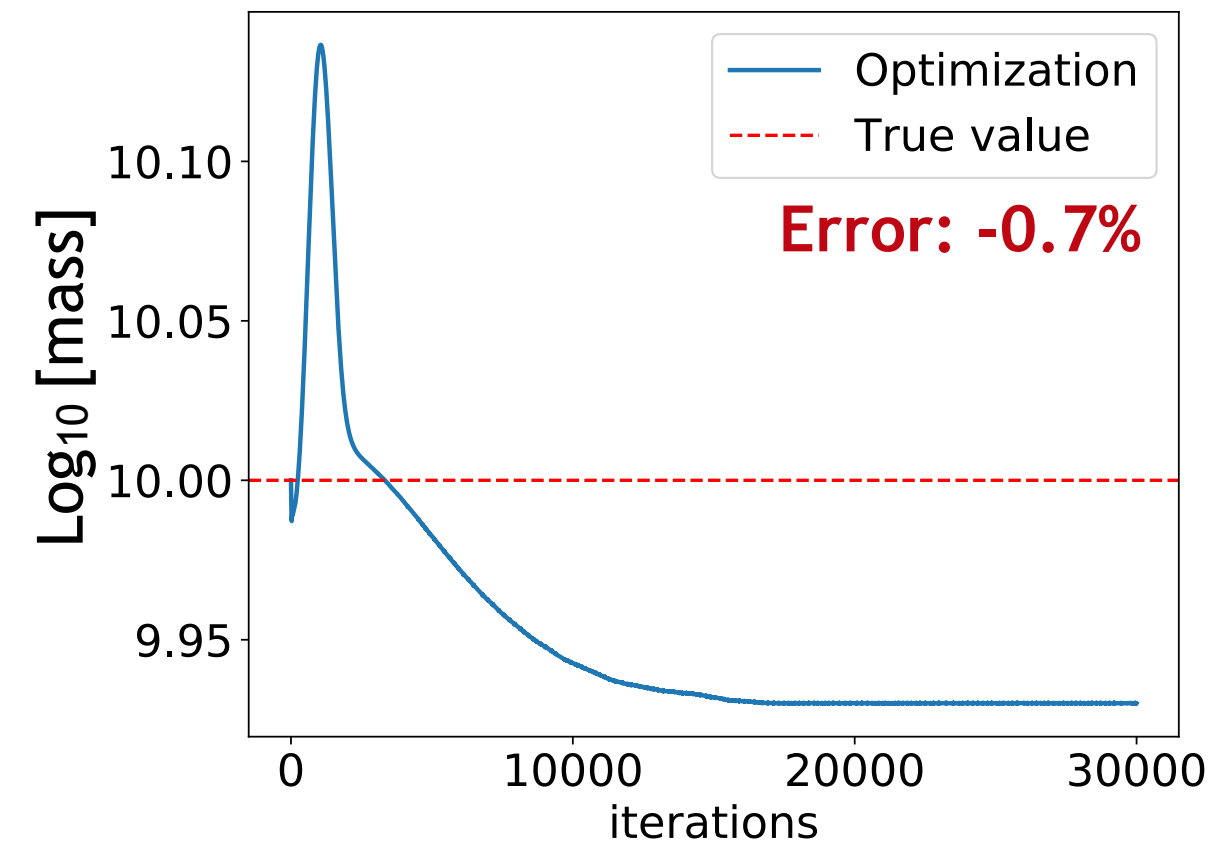
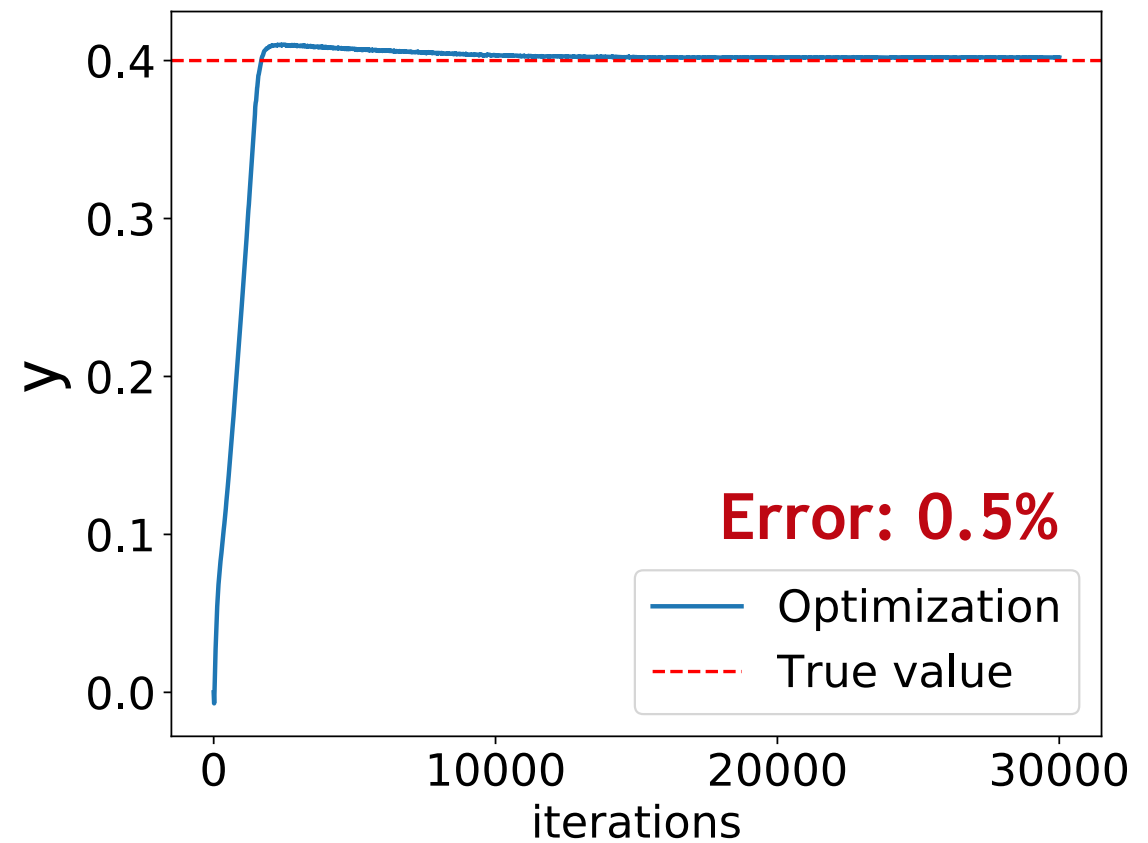
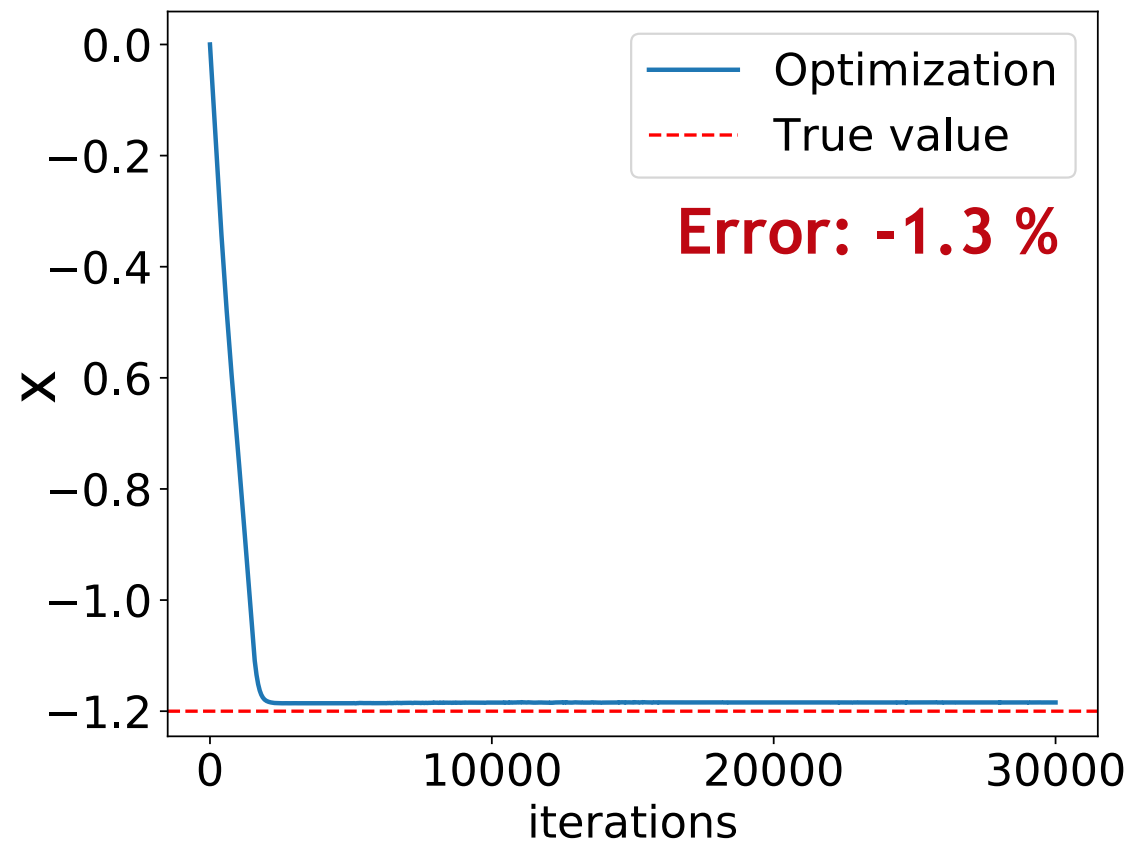


Source



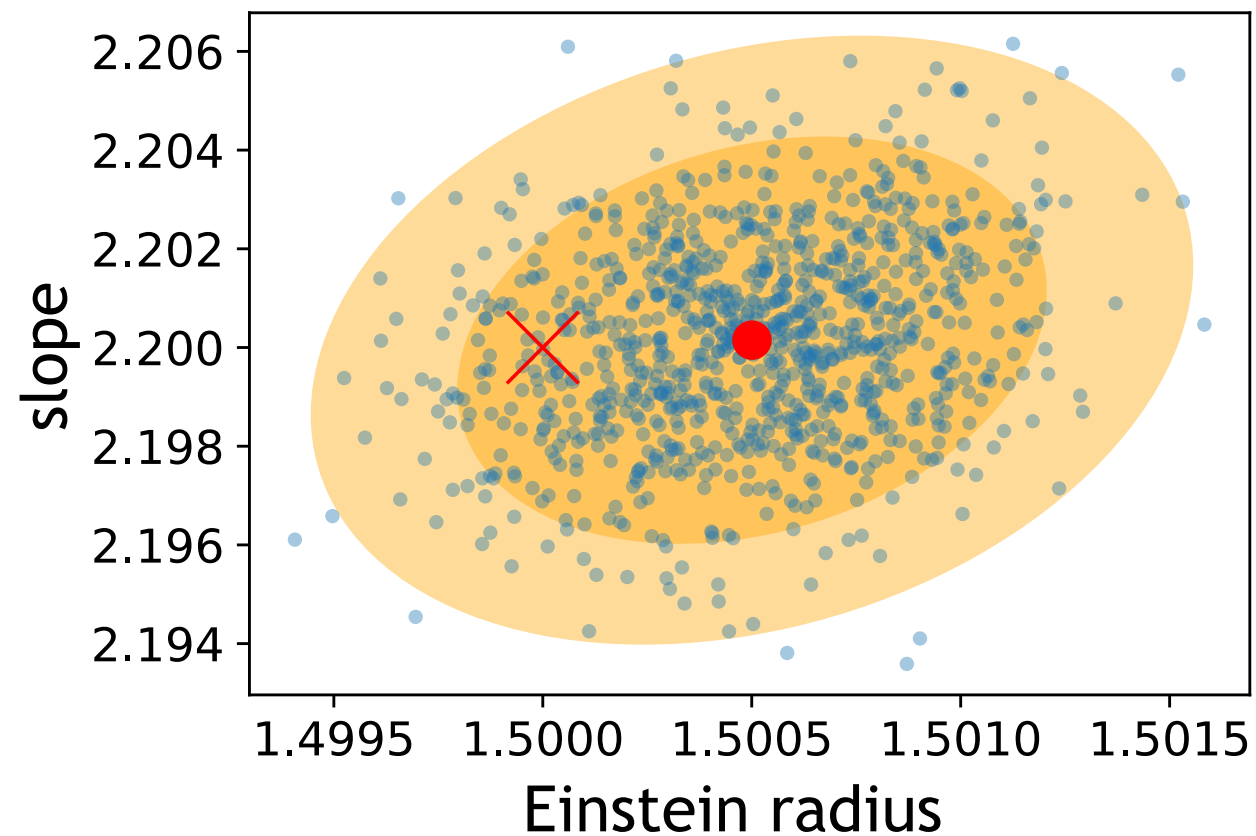
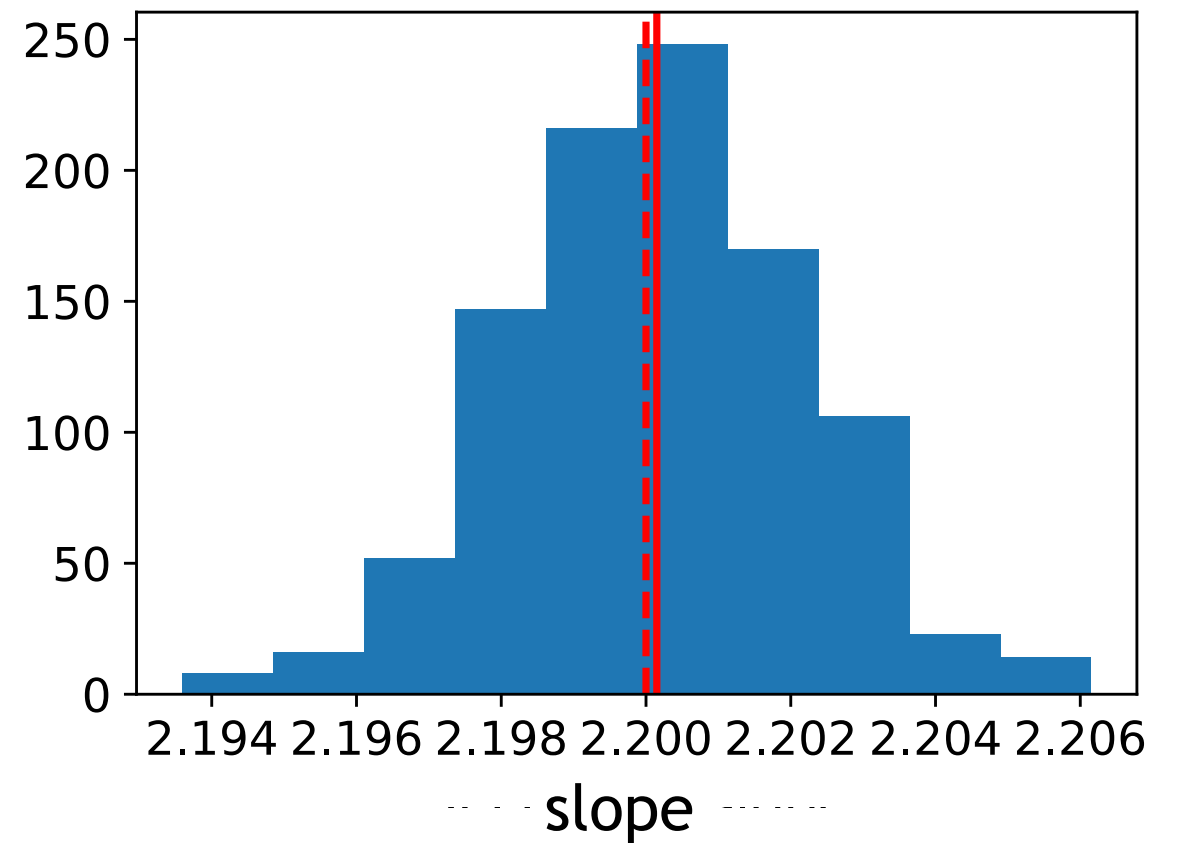
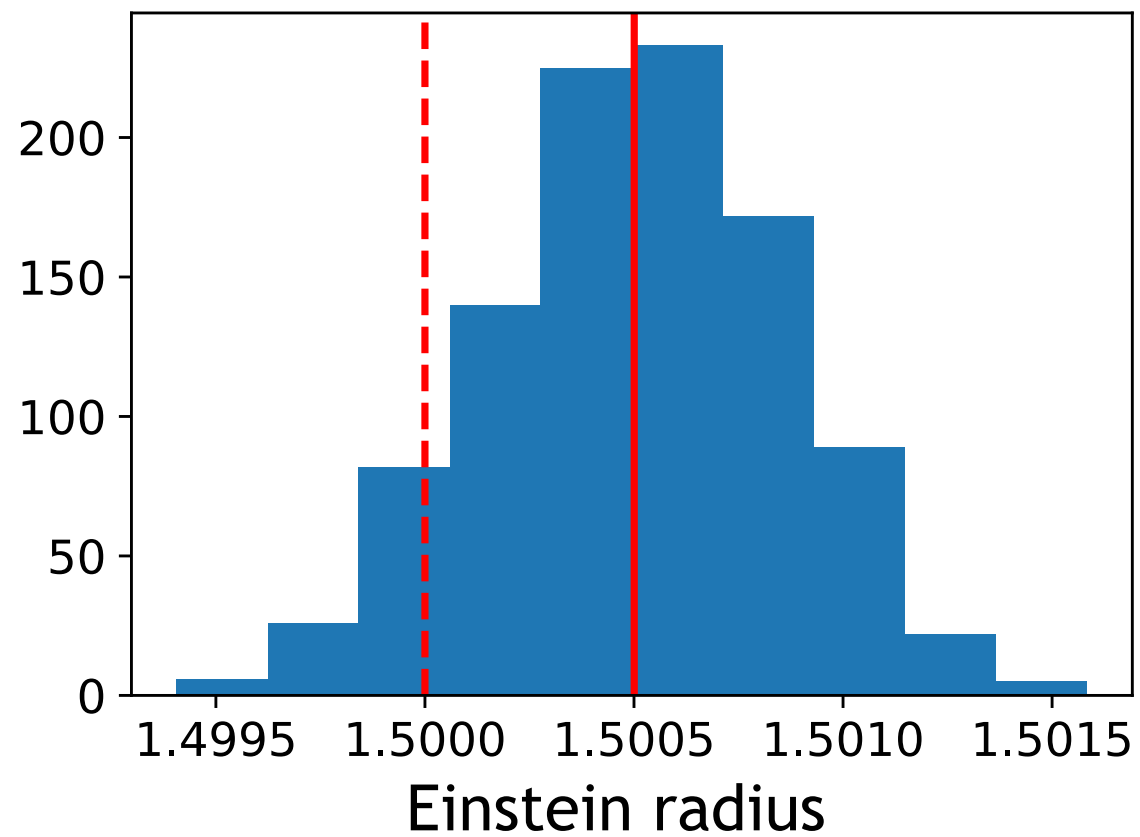
Main Lens

Optimization: subhalo

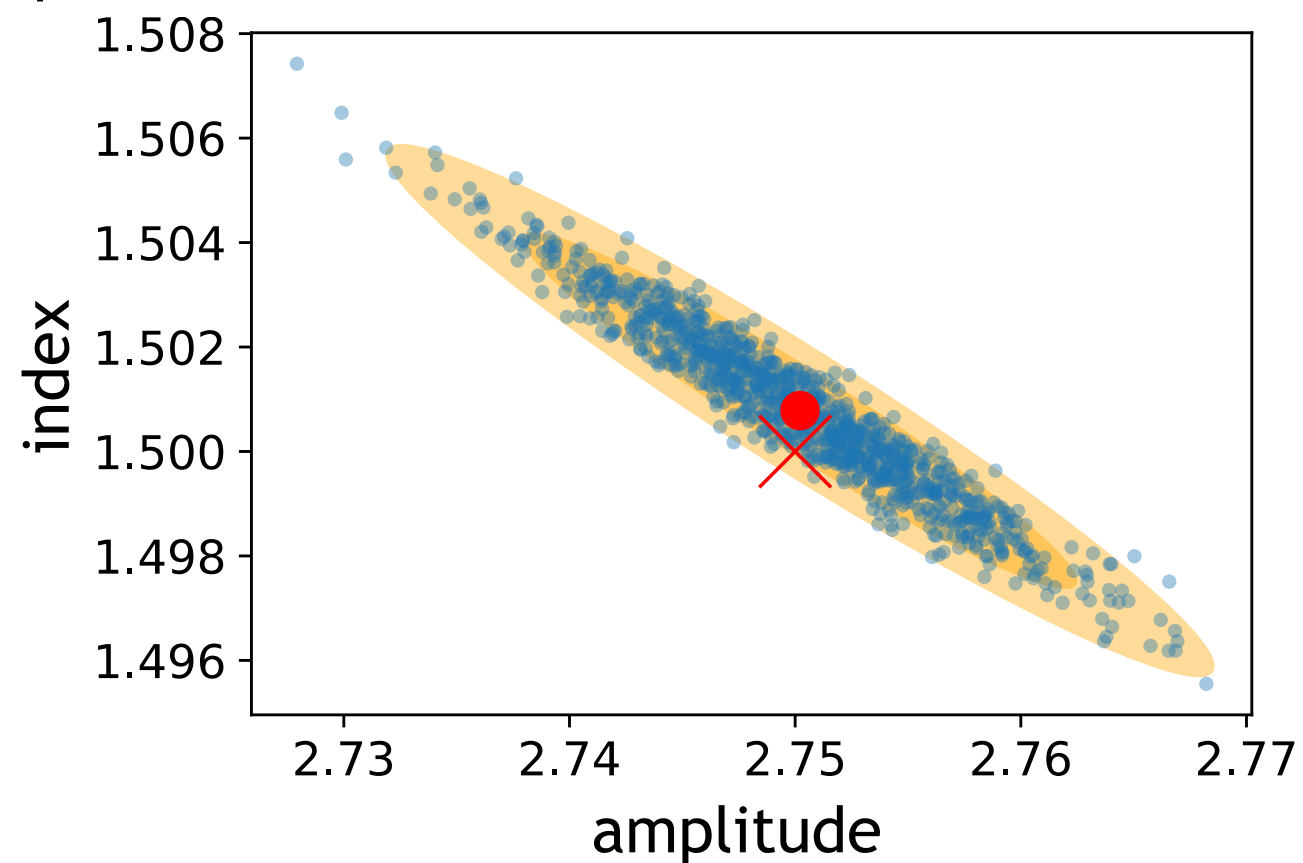
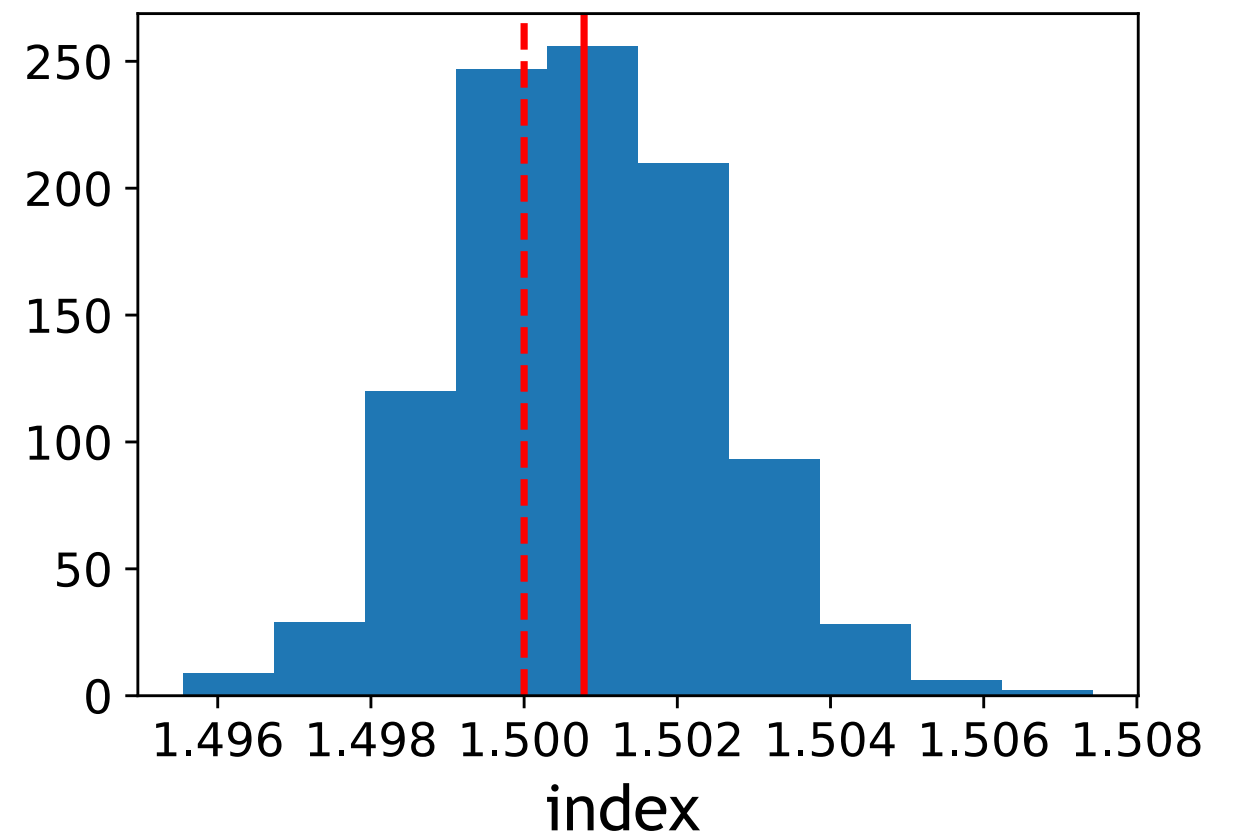
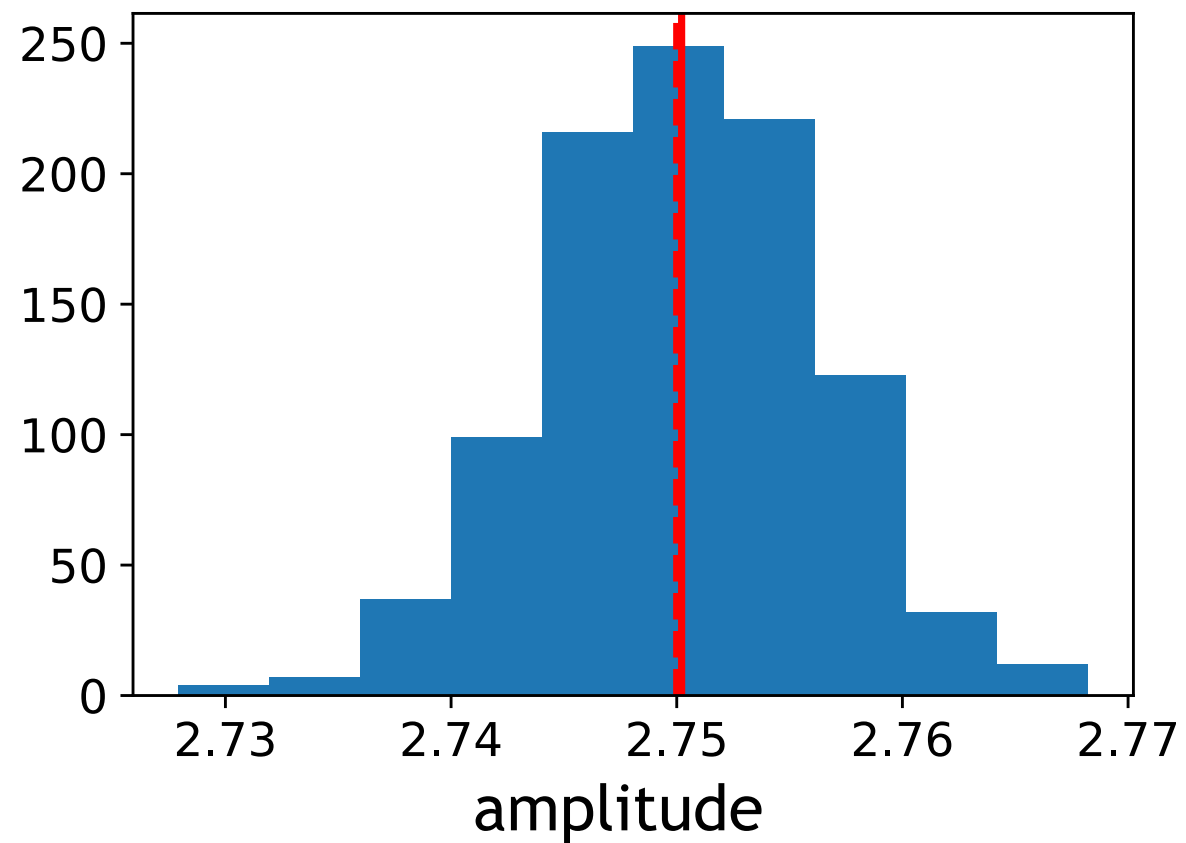


truncated NFW subhalo

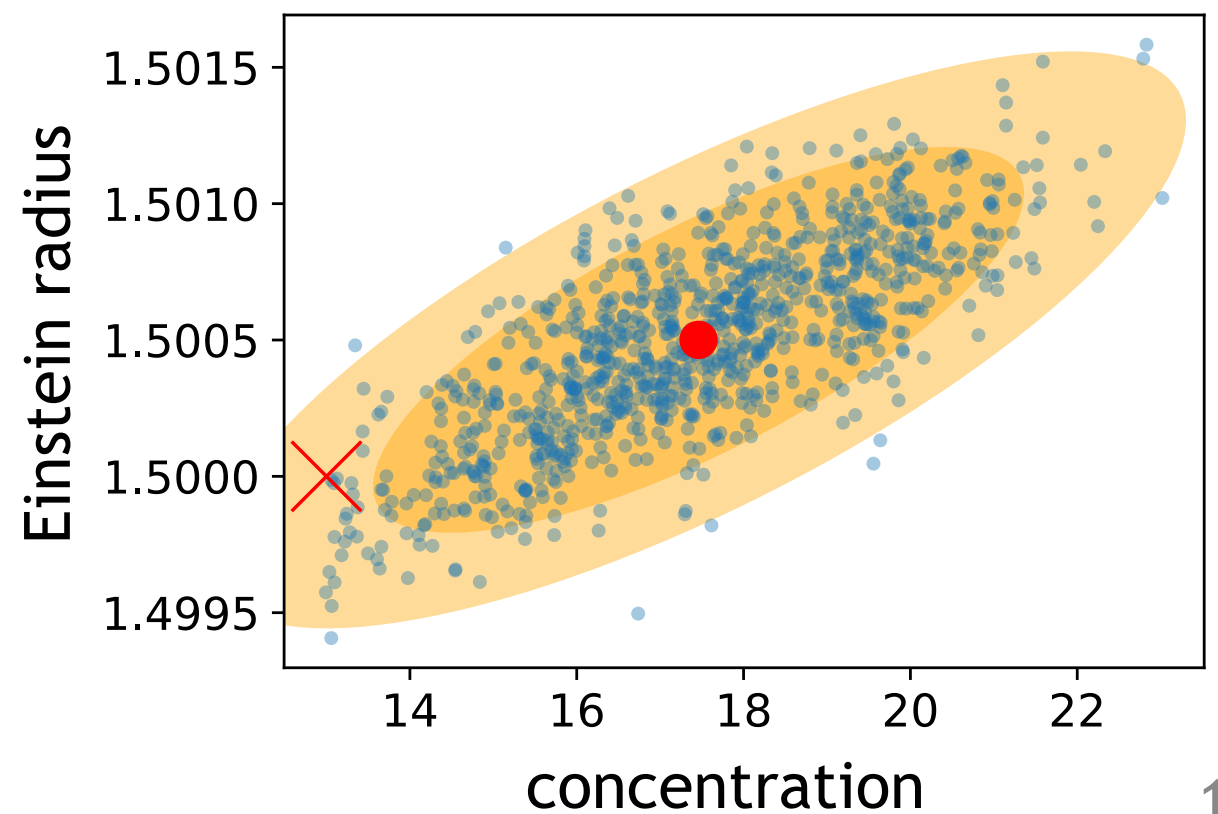
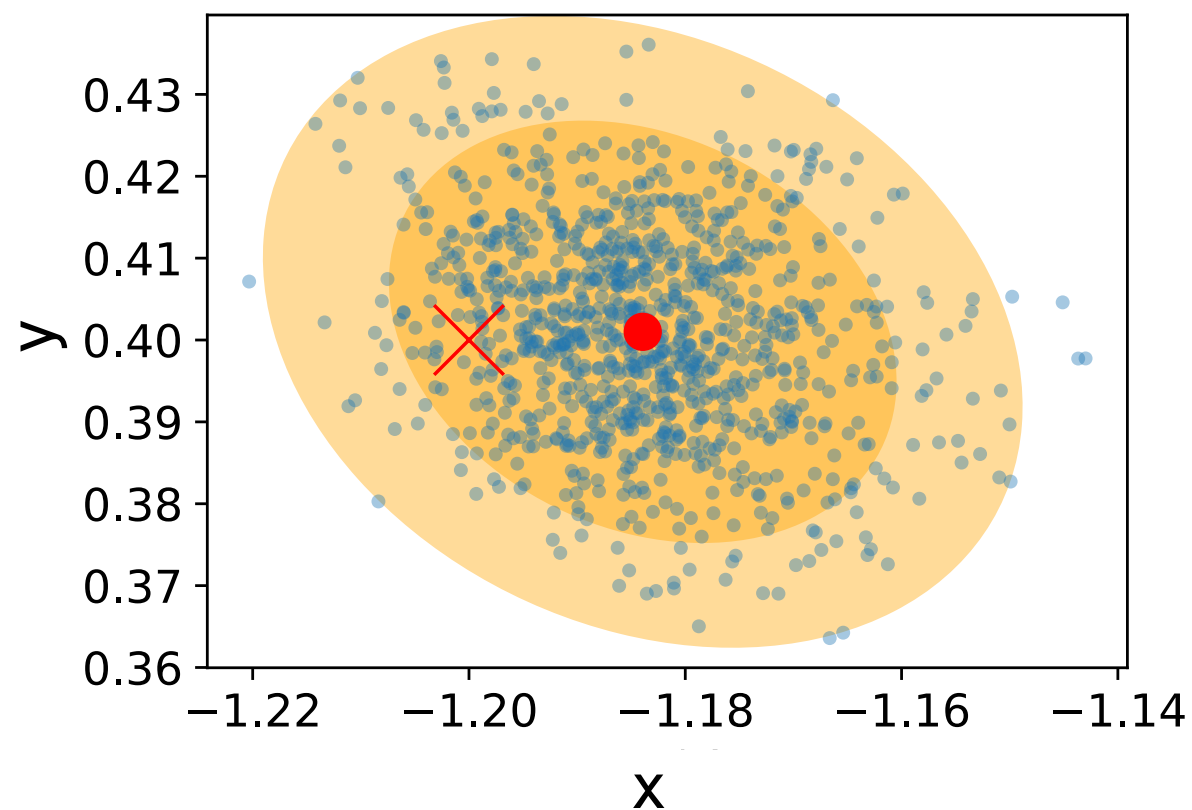
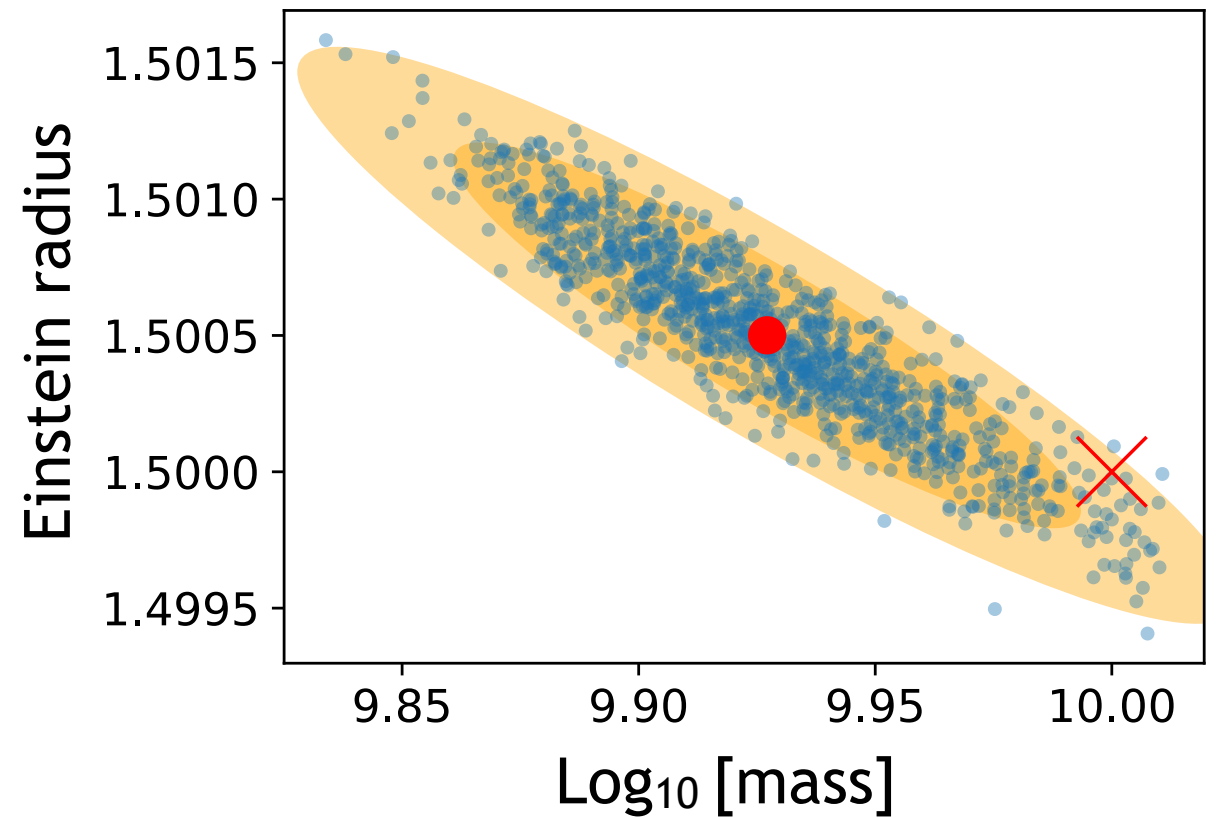
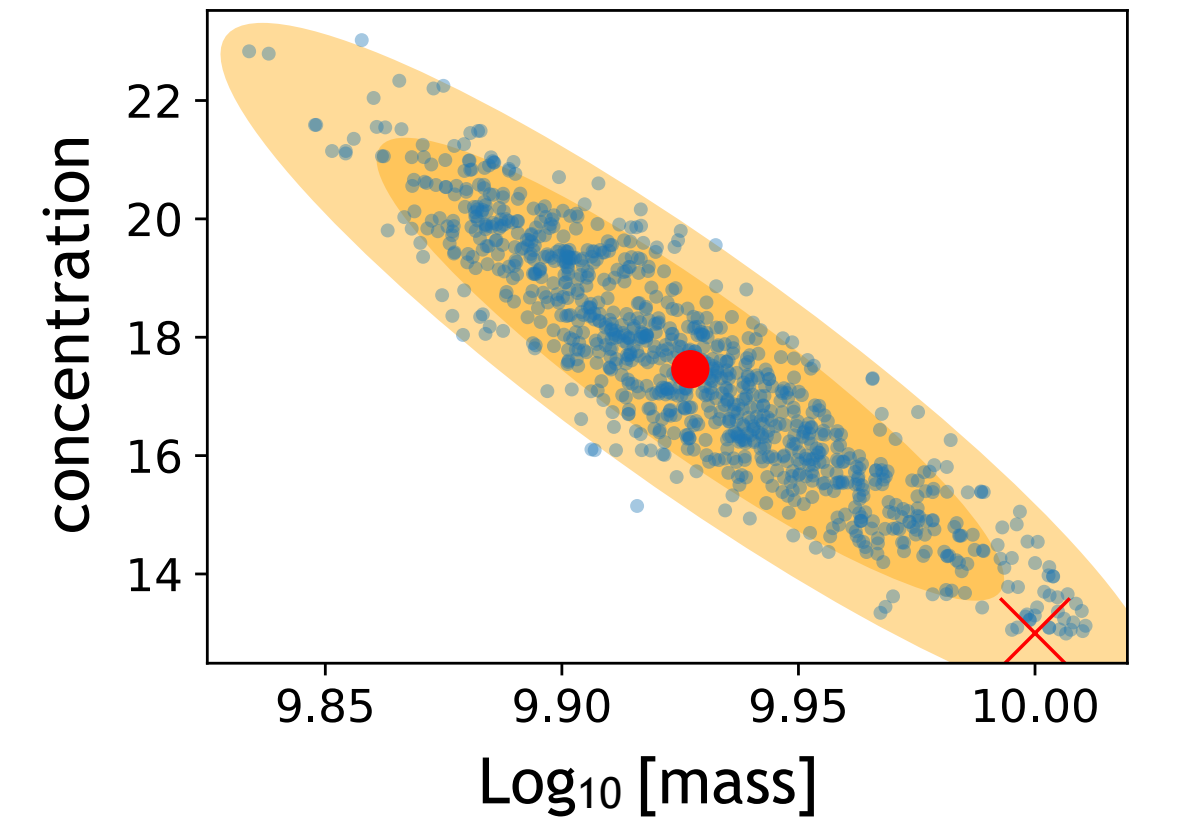
HMC: lens



HMC: source

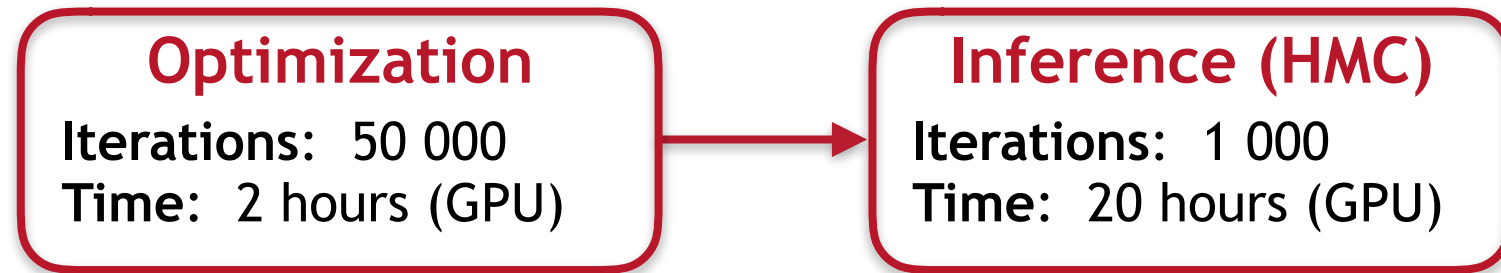


HMC: subhalo



Conclusions

We have developed a fast **Bayesian analysis pipeline** for strong lensing data in a **deep probabilistic programming** framework.



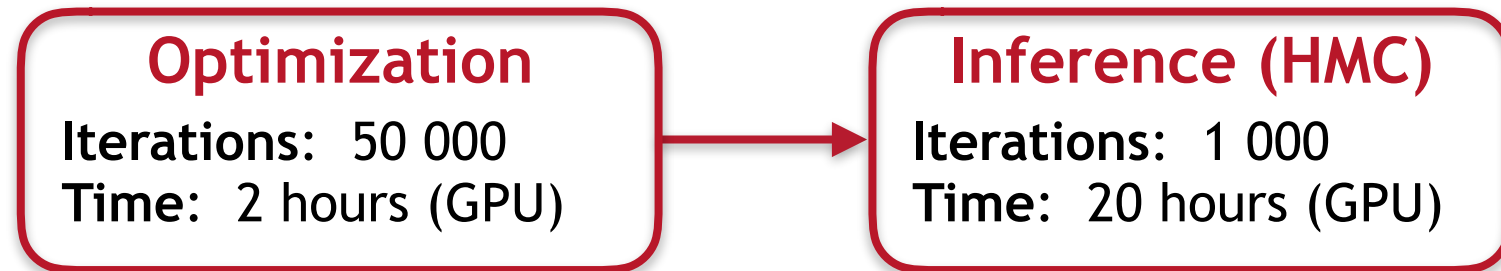
We have studied the **feasibility of inference techniques with gradient descent** (HMC and SVI) for systems with high-dimensional parameters space.

The next steps are:

- Systematic study of the sensitivity to substructures
- Inference on real strong lensing data
- Estimation of the Bayesian evidence (models discrimination)
- Couple to **generative models** for the background source galaxy *See Coogan's talk!*

Conclusions

We have developed a fast **Bayesian analysis pipeline** for strong lensing data in a **deep probabilistic programming** framework.



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Thank you for your attention

Backup slides

Pytorch and Pyro

PYTORCH

In **Pytorch**, the key features are:

- automatic *differentiation*

```
M = model(x, ...) with x = torch.Tensor(..., requires_grad=True)
```

`M.backward()` $\longleftrightarrow$ $\partial M / \partial x$

- simple implementation on GPU with: `M.cuda()`

In **Pyro**, the basic units are primitive stochastic functions:

- double role as *probability distribution* and *random number generator*

```
x = pyro.sample("param", dist.Normal(mean, sigma))  
image = pyro.sample("image", dist.Normal(M, noise))
```

- can be conditioned on data

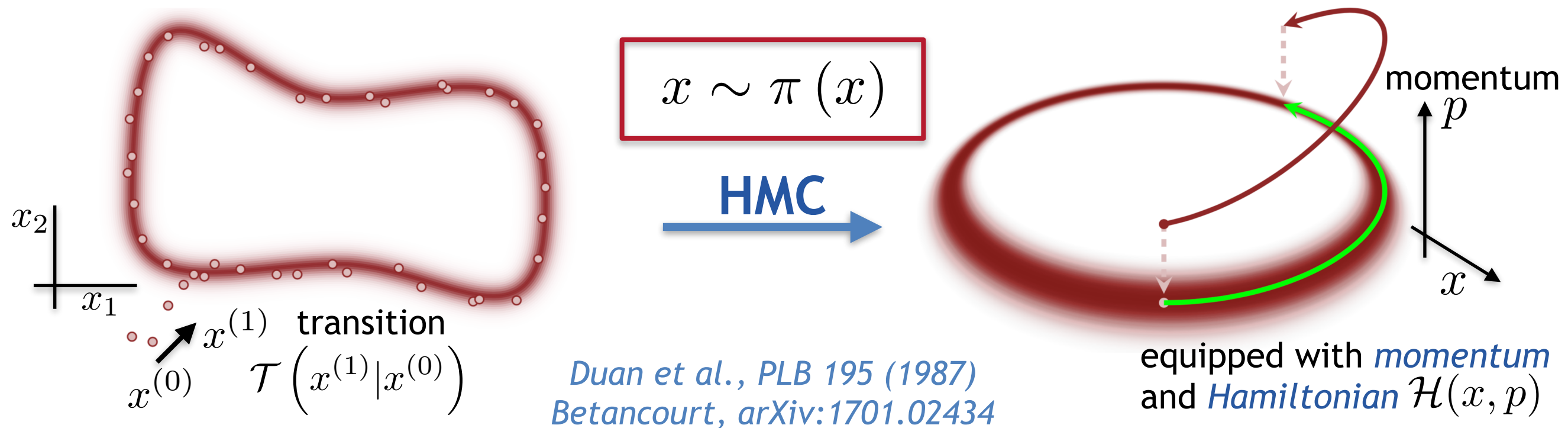
```
conditioned_image = pyro.condition(image, data={"obs": obs_image})
```

- used in *universal inference algorithms* (e.g. HMC, SVI)



HMC vs SVI

The **Hamiltonian Monte Carlo** (HMC) is a MCMC that exploits gradient information.



The **Stochastic Variational Inference** (SVI) is a fast method for approximately posteriors.

- **Guide:** $q_{\theta}(x)$ $\longrightarrow$ find θ so that $q_{\theta}(x) \sim p(x|D)$
- Maximize the **Evidence Lower BOund**

$$\text{ELBO} \equiv \log p(D) - \text{KL}(q_{\theta}(x), p(x|D))$$

$\log p(D)$ $\longrightarrow$ Bayesian evidence

$\text{KL}(q_{\theta}(x), p(x|D))$ $\longrightarrow$ Kullback-Leibler divergence (measure of approximation error)

Wingate and Weber, arXiv:1301.1299

Ranganath, Gerrish and Blei, arXiv:1401.0118