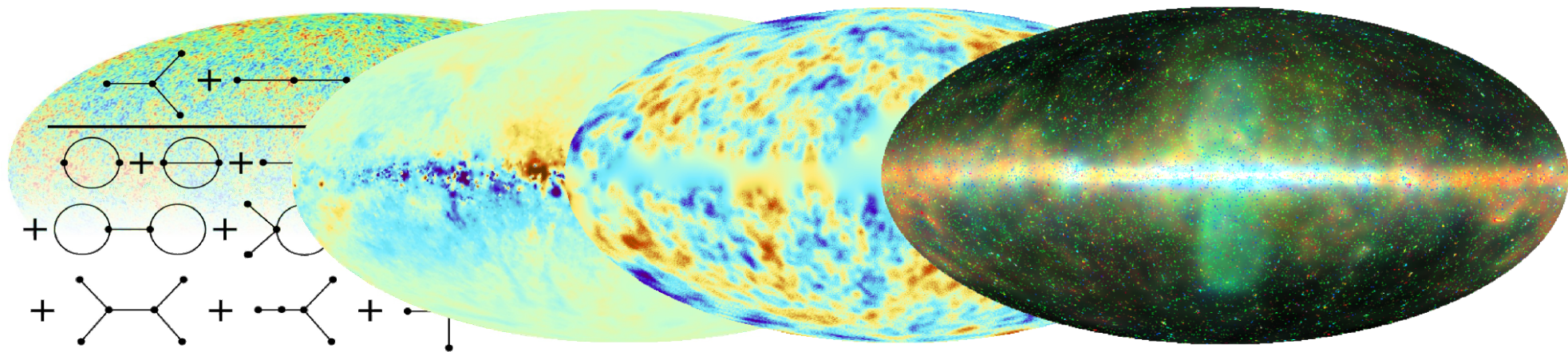
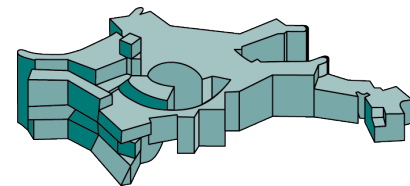




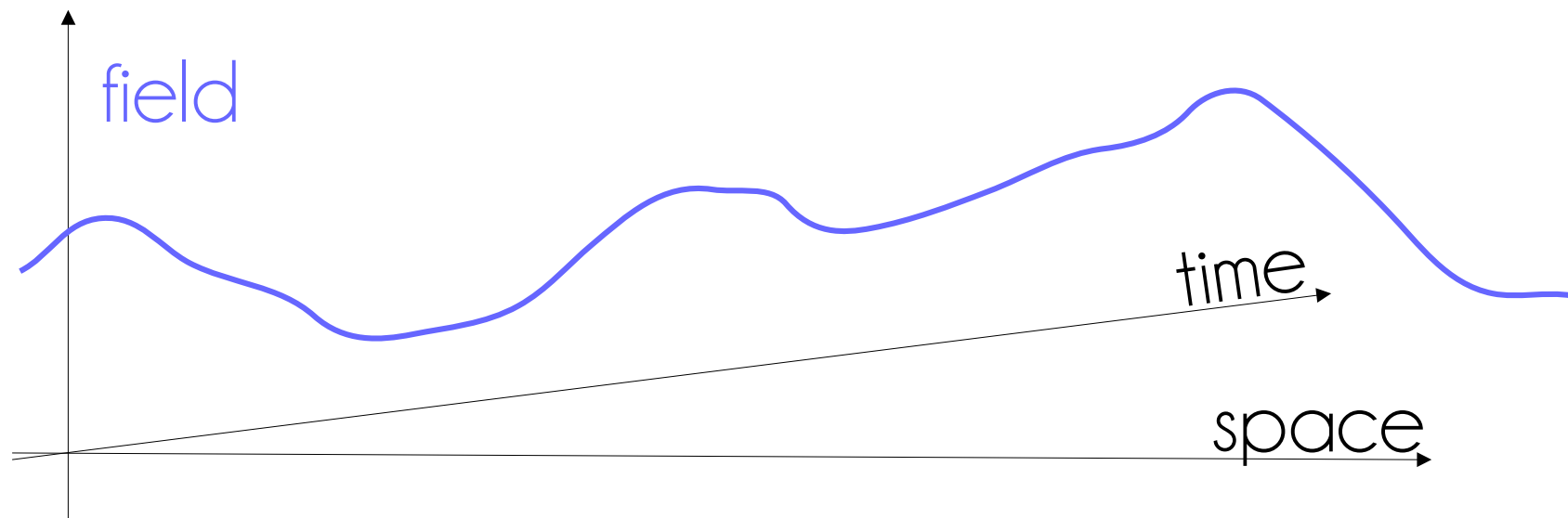
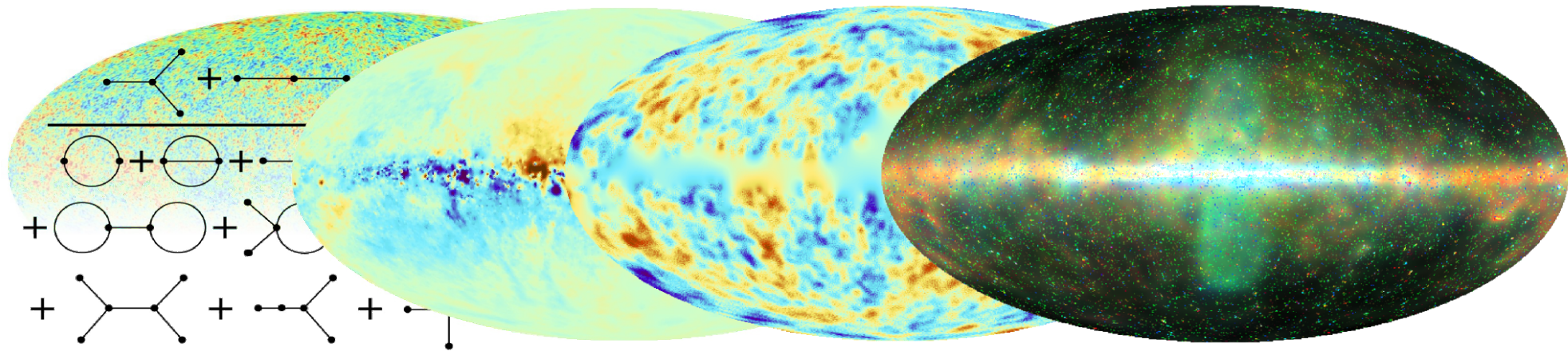
Information field theory

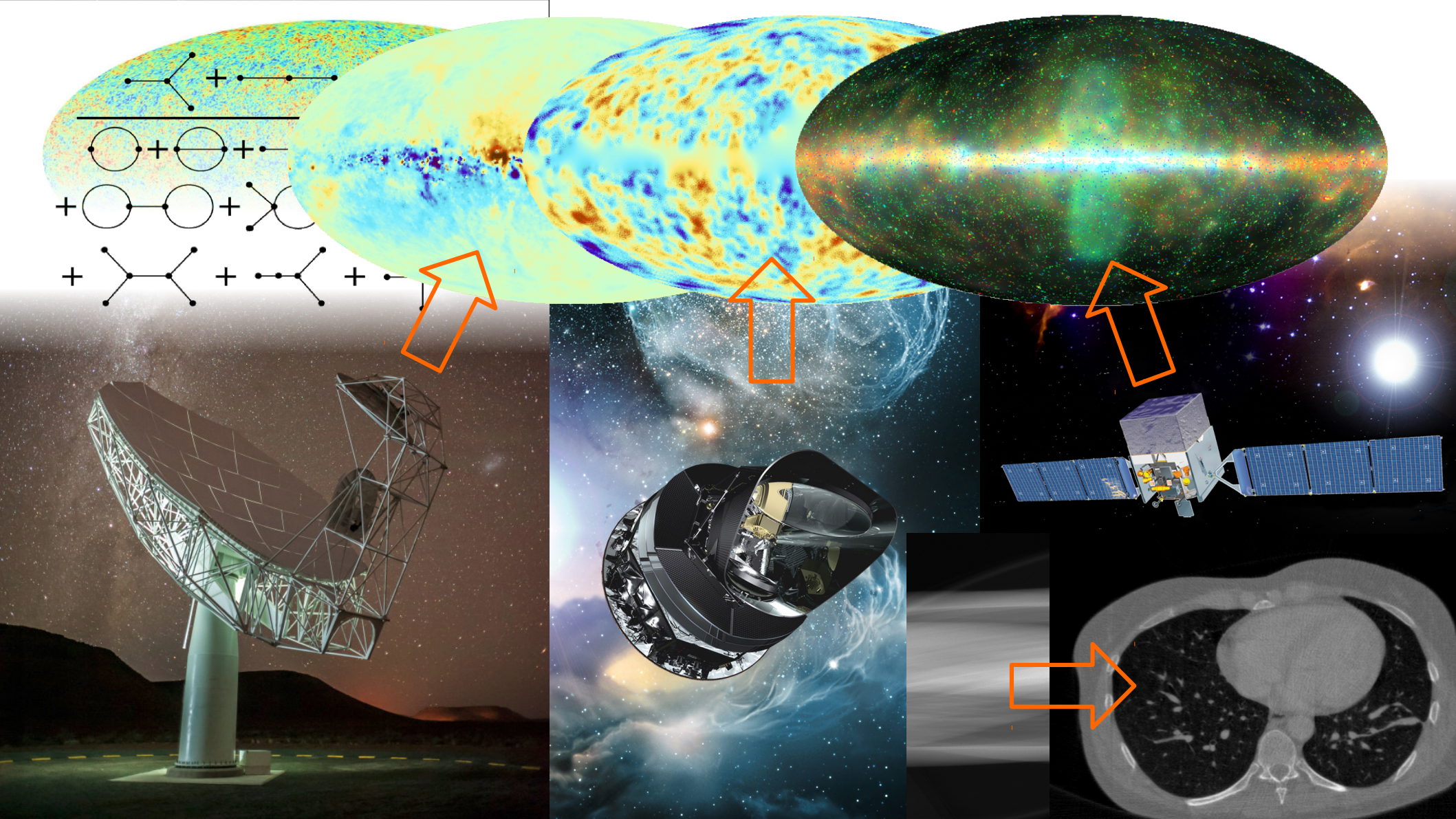


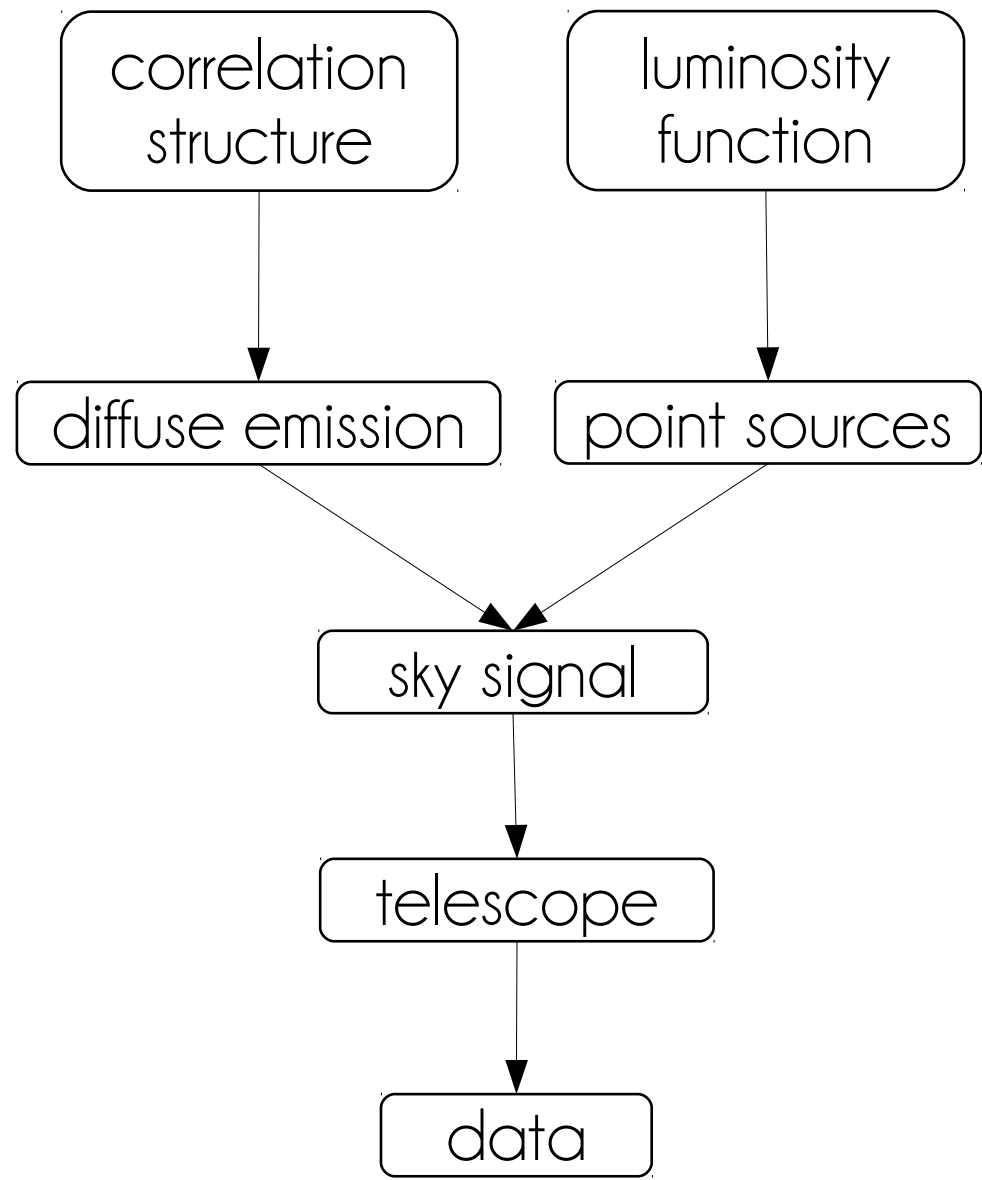
Torsten Enßlin
MPI for Astrophysics
Ludwig Maximilian University Munich

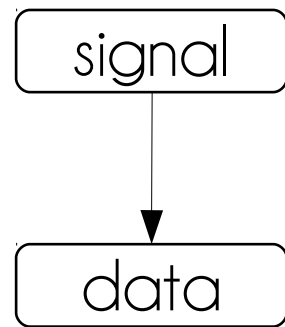
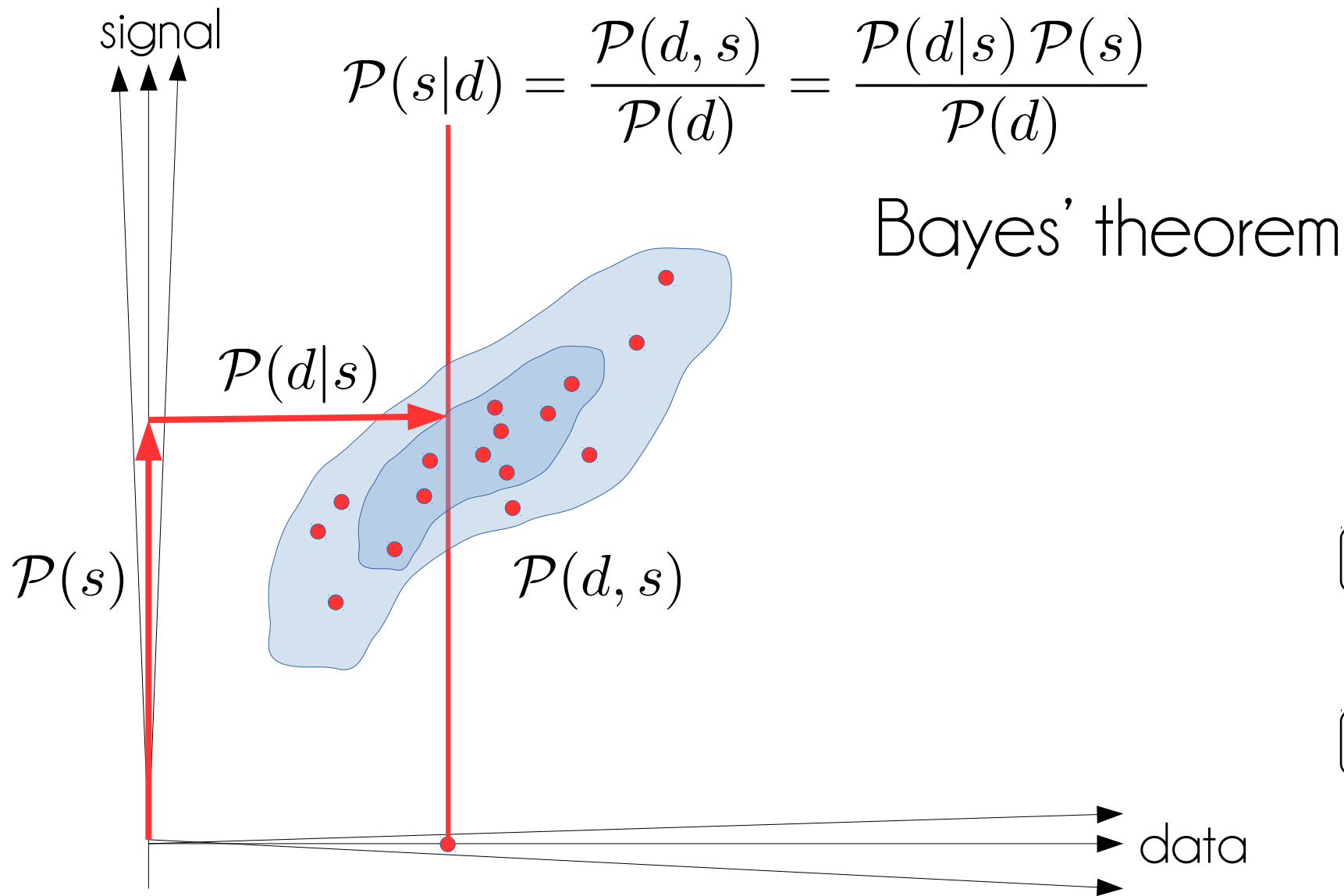


IFT Team: Philipp Arras, Michael Bell, Vanessa Böhm, Sebastian Dorn, Martin Dupont, Mona Frommert, Philipp Frank, Mahsa Ghaempanah, Maksim Greiner, Sebastian Hutschenreuter, Henrik Junklewitz, Francisco-Shu Kitaura, Jakob Knollmüller, Christoph Lienhard, Reimar Leike, Marco Selig, Theo Steininger, Johannes Oberpriller, Niels Oppermann, Natalia Porqueres, Daniel Pumpe, Tiago Ramalho, Martin Reinecke, Julia Stadler, Valentina Vacca, Cornelius Weig, Margret Westerkamp, & many more









Information theory

$$\mathcal{P}(s|d) = \frac{\mathcal{P}(d, s)}{\mathcal{P}(d)} = \frac{e^{-\mathcal{H}(d, s)}}{\mathcal{Z}(d)}$$

$$\mathcal{H}(d, s) = -\log \mathcal{P}(d, s)$$

Information

$$\mathcal{Z}(d) = \mathcal{P}(d)$$

$$= \int \mathcal{D}s \mathcal{P}(d, s)$$

$$\mathcal{P}(d, s) = \mathcal{P}(d|s) \mathcal{P}(s)$$

$$\mathcal{H}(d, s) = \mathcal{H}(d|s) + \mathcal{H}(s)$$

is additive

Probability & Information

$$\mathcal{P}(s) = \frac{1}{\sqrt{2\pi\sigma^2}} e^{-\frac{s^2}{2\sigma^2}}$$

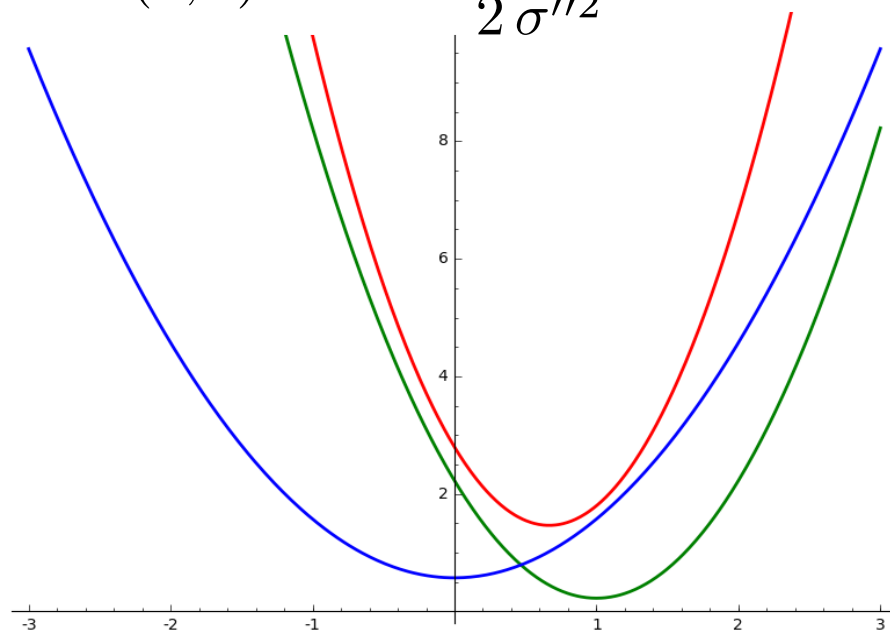
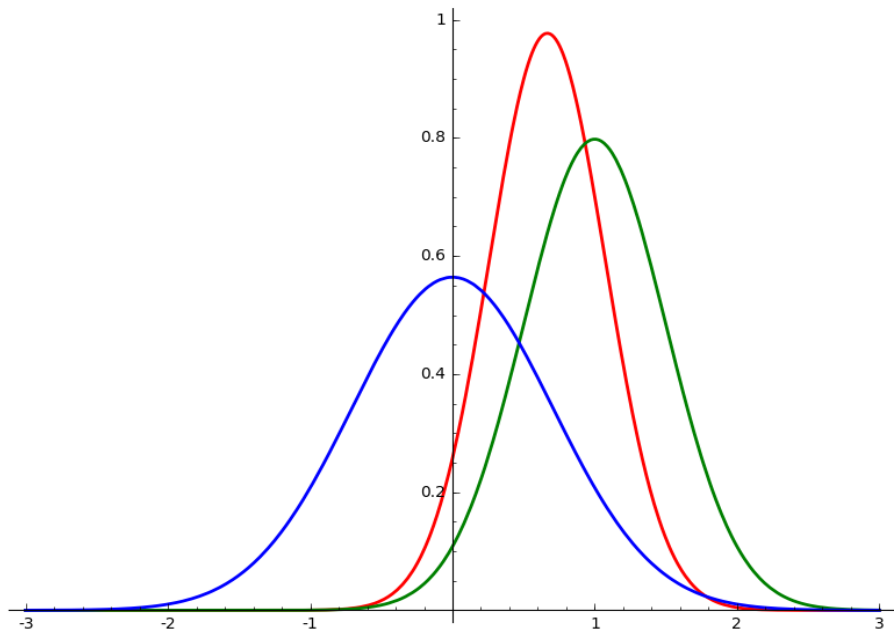
$$\mathcal{P}(d|s) \propto e^{-\frac{(s-d)^2}{2\sigma'^2}}$$

$$\mathcal{P}(s|d) \propto e^{-\frac{(s-m)^2}{2\sigma''^2}}$$

$$\mathcal{H}(s) \hat{=} \frac{s^2}{2\sigma^2}$$

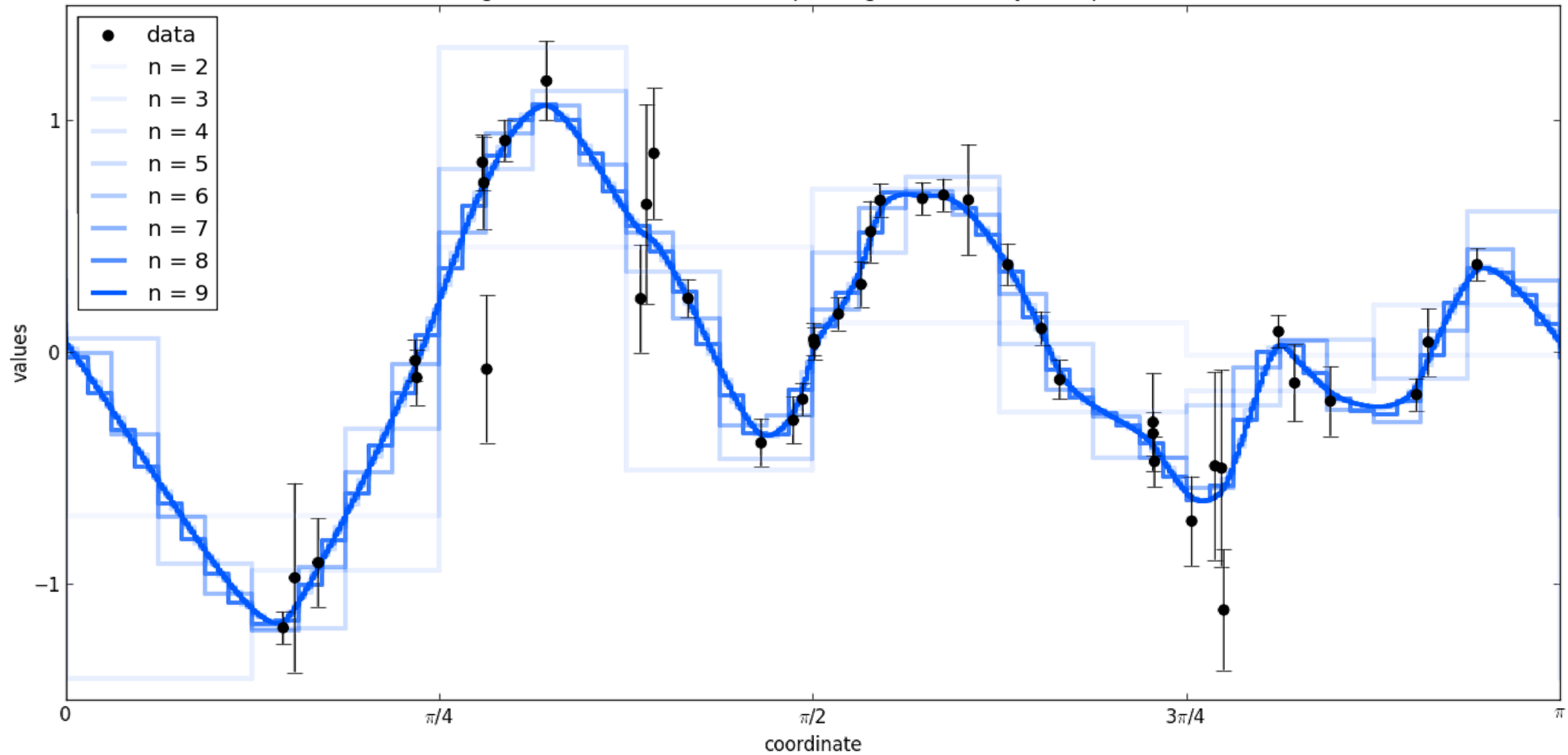
$$\mathcal{H}(d|s) \hat{=} \frac{(s-d)^2}{2\sigma'^2 \sigma^2}$$

$$\mathcal{H}(d, s) \hat{=} \frac{(s-m)^2}{2\sigma''^2}$$





signal reconstruction with 2^n pixels given 42 noisy data points



NIFTy

5.0

Search docs

IFT – Information Field Theory
Discretization and Volume in NIFTy
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NIFTy-related publications
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NIFTy – Numerical Information Field Theory

NIFTy ^[1], ^[2], "Numerical Information Field Theory" is a versatile library designed to enable the development of signal inference algorithms that are independent of the underlying grids (spatial, spectral, temporal, ...) and their resolutions. Its object-oriented framework is written in Python, although it accesses libraries written in C++ and C for efficiency.

NIFTy offers a toolkit that abstracts discretized representations of continuous spaces, fields in these spaces, and operators acting on these fields into classes. This allows for an abstract formulation and programming of inference algorithms, including those derived within information field theory. NIFTy's interface is designed to resemble IFT formulae in the sense that the user implements algorithms in NIFTy independent of the topology of the underlying spaces and the discretization scheme. Thus, the user can develop algorithms on subsets of problems and on spaces where the detailed performance of the algorithm can be properly evaluated and then easily generalize them to other, more complex spaces and the full problem, respectively.

The set of spaces on which NIFTy operates comprises point sets, n -dimensional regular grids, spherical spaces, their harmonic counterparts, and product spaces constructed as combinations of those. NIFTy takes care of numerical subtleties like the normalization of operations on fields and the numerical representation of model components, allowing the user to focus on formulating the abstract inference procedures and process-specific model properties.

References

- [1] Selig et al., "NIFTy - Numerical Information Field Theory. A versatile PYTHON library for signal inference ", 2013, Astronomy and Astrophysics 554, 26; [DOI], [arXiv:1301.4499]
- [2] Steininger et al., "NIFTy 3 - Numerical Information Field Theory - A Python framework for multicomponent signal inference on HPC clusters", 2017, accepted by Annalen der Physik; [arXiv:1708.01073]

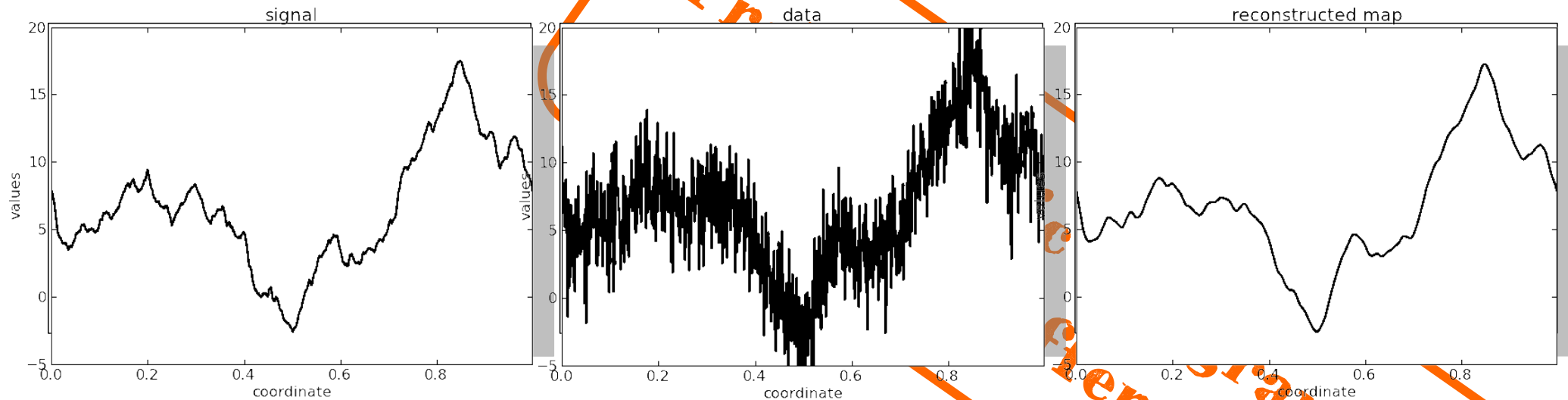
Contents

- IFT – Information Field Theory
 - Theoretical Background
 - Free Theory & Implicit Operators
 - Generative Models
 - Maximum a Posteriori
 - Variational Inference
- Discretization and Volume in NIFTy
 - Setup

With Probabilistic auto-differentiation

NIFTy – Numerical Information Field Theory

NIFTy [1], [2], "Numerical Information Field Theory" is a versatile library designed to enable the development of signal inference algorithms that are independent of the underlying grids (spatial, spectral, temporal, ...) and their resolutions. Its object-oriented framework is written in Python.



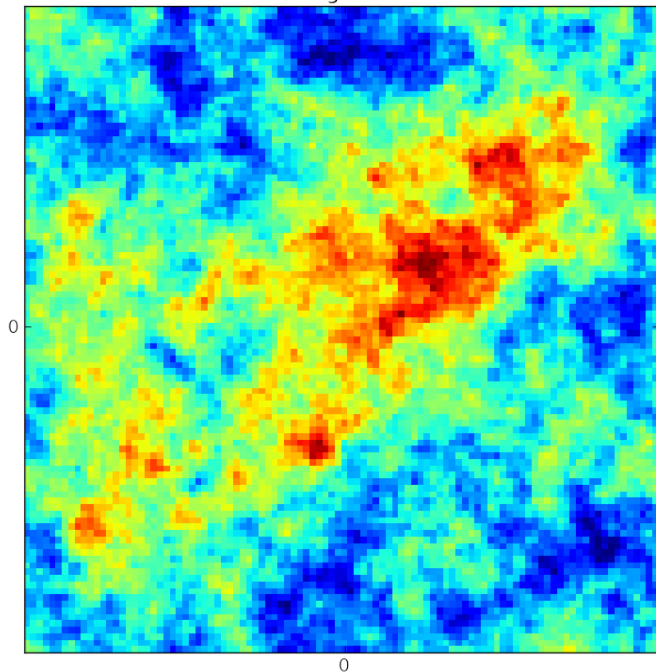
```
import nifty5 as ift
s_space = ift.RGSpace([N])
```



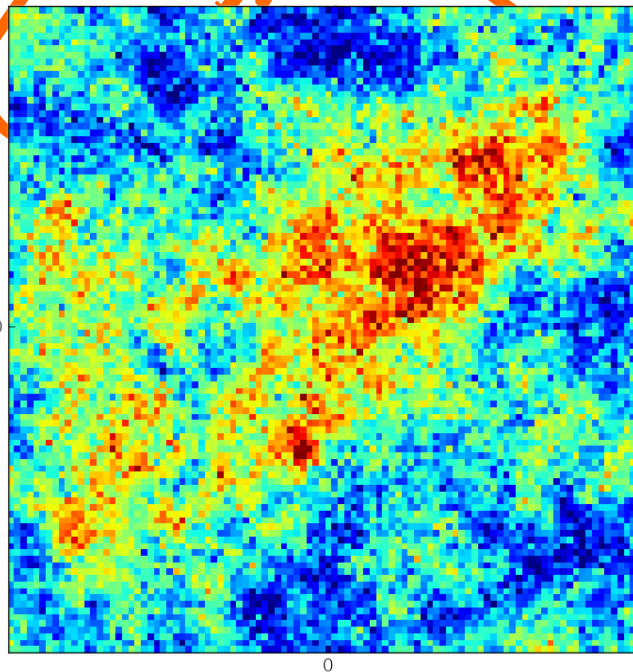
NIFTy – Numerical Information Field Theory

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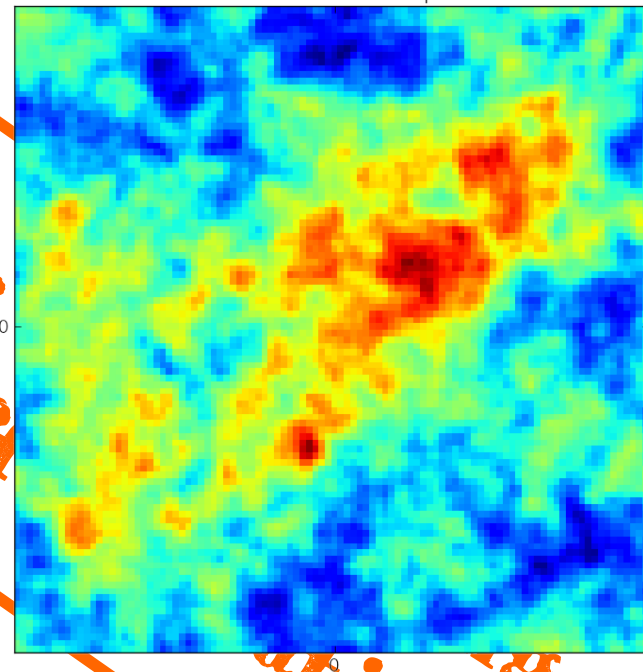
signal



data



reconstructed map

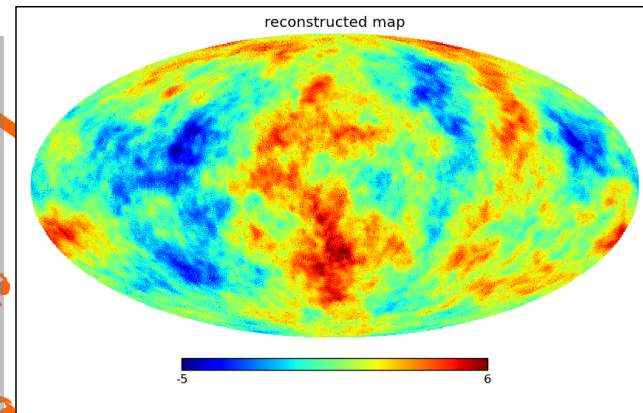
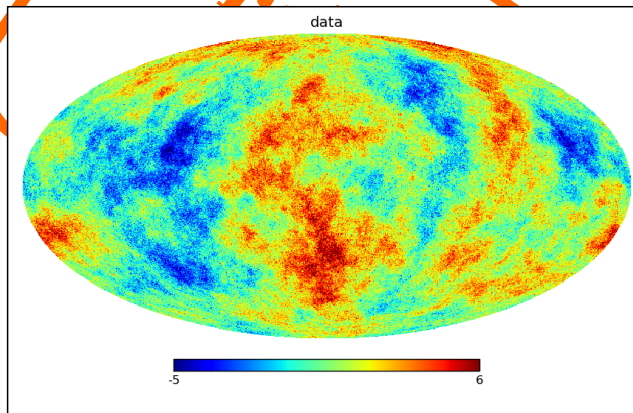
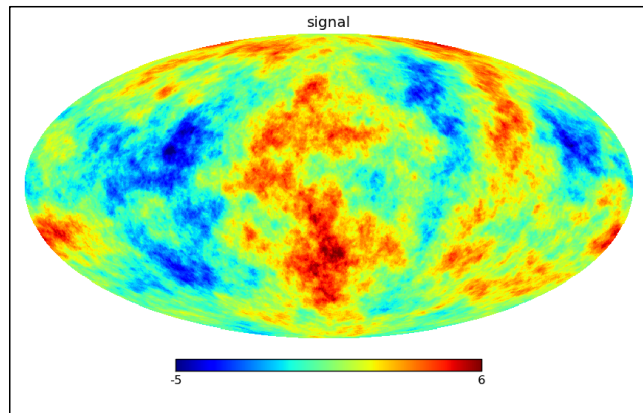


```
import nifty5 as ift  
s_space = ift.RGSpace([N,N])
```




NIFTy – Numerical Information Field Theory

NIFTy ^[1], ^[2], "Numerical Information Field Theory" is a versatile library designed to enable the development of signal inference algorithms that are independent of the underlying grids (spatial, spectral, temporal, ...) and their resolutions. Its object-oriented framework is written in Python.

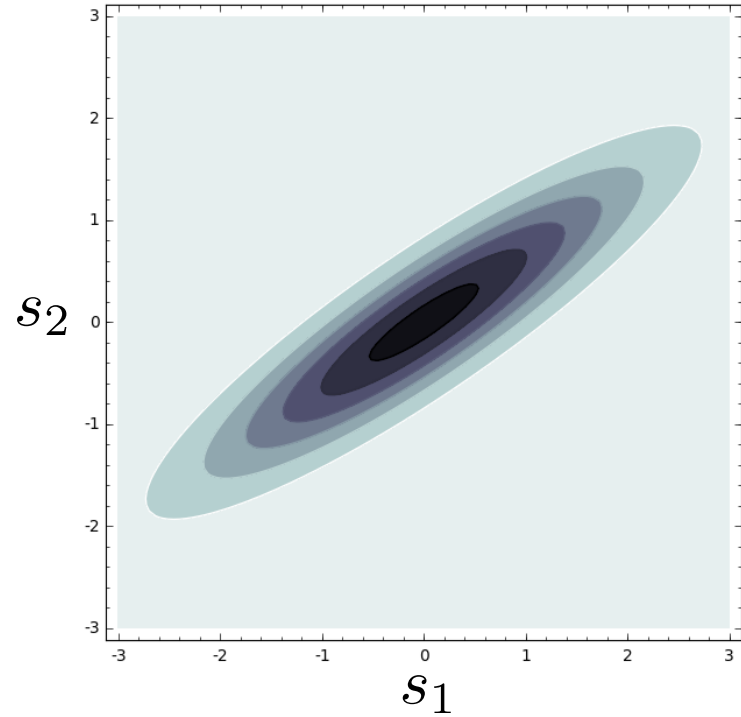


```
import nifty5 as ift  
s_space = ift.HPSpace(NSide)
```

Correlations

$$\mathcal{P}(s)$$

$$s = \begin{pmatrix} s_1 \\ s_2 \end{pmatrix}$$



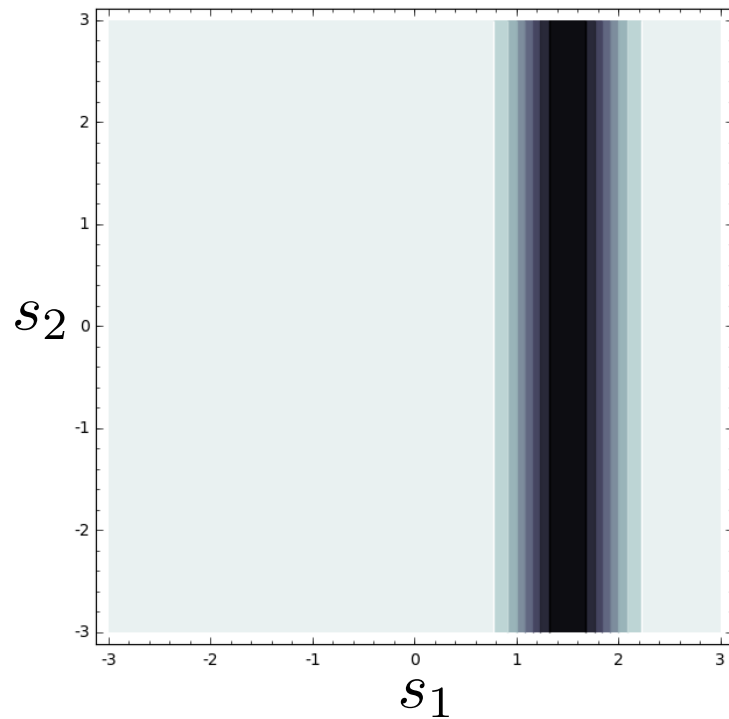
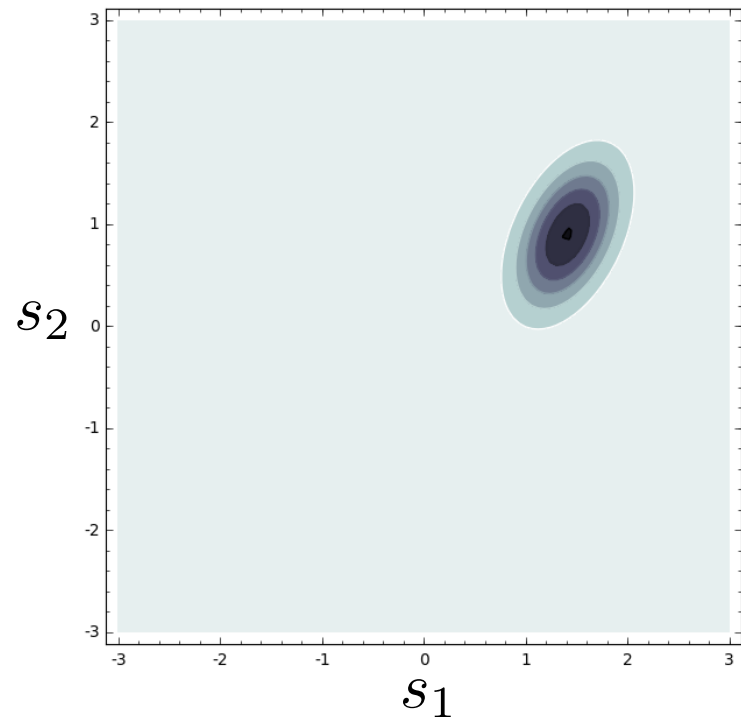
Correlations

$$\mathcal{P}(s|d)$$

$$s = \begin{pmatrix} s_1 \\ s_2 \end{pmatrix}$$

$$\mathcal{P}(d|s)$$

$$d = s_1 + n$$



Correlations

$$\mathcal{P}(s)$$

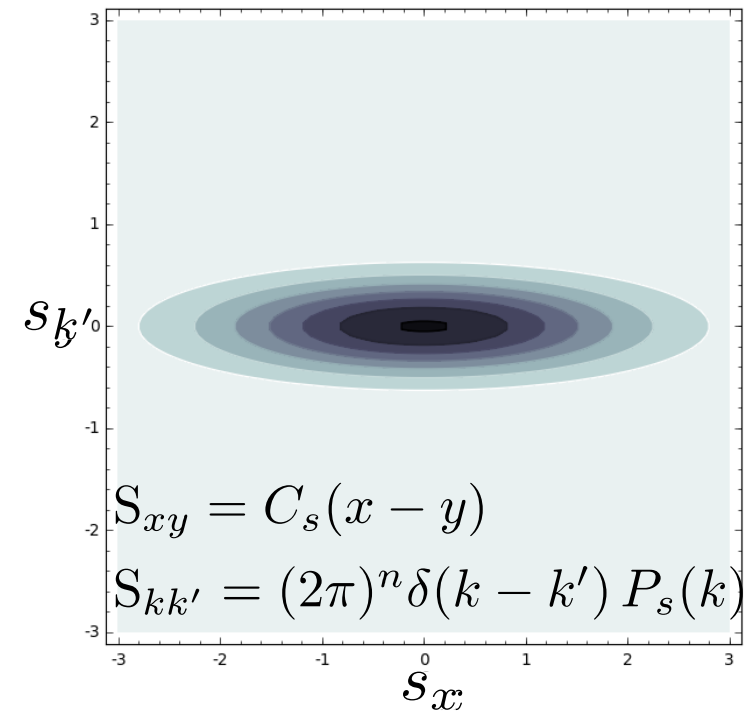
$$s = \begin{pmatrix} s_1 \\ s_2 \end{pmatrix}$$

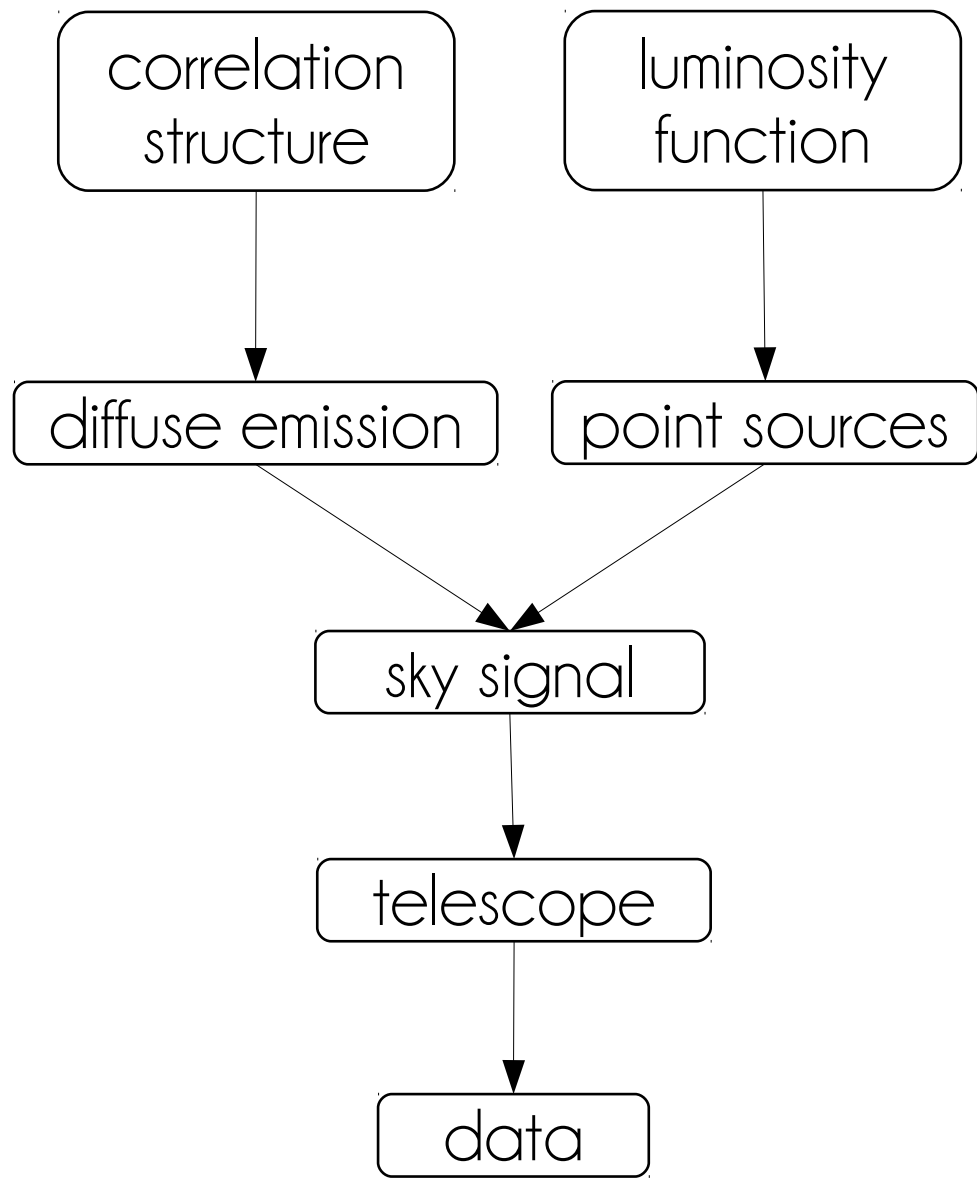
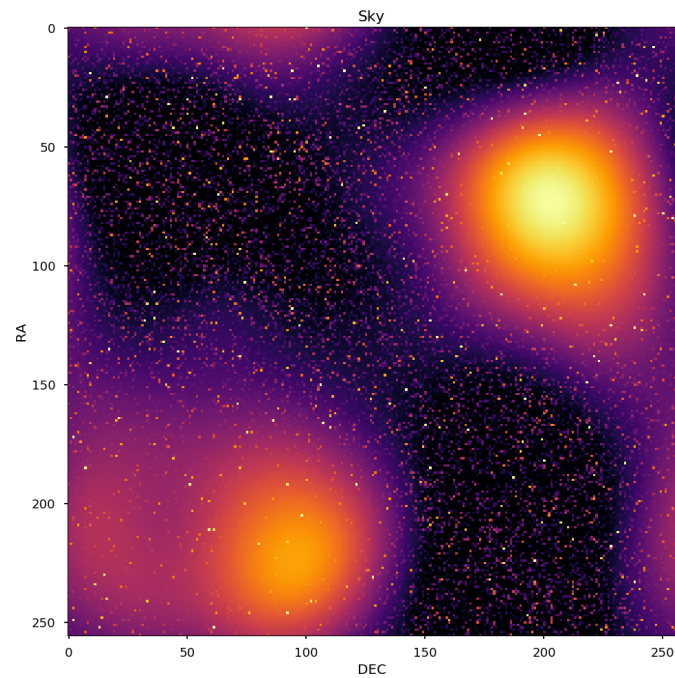
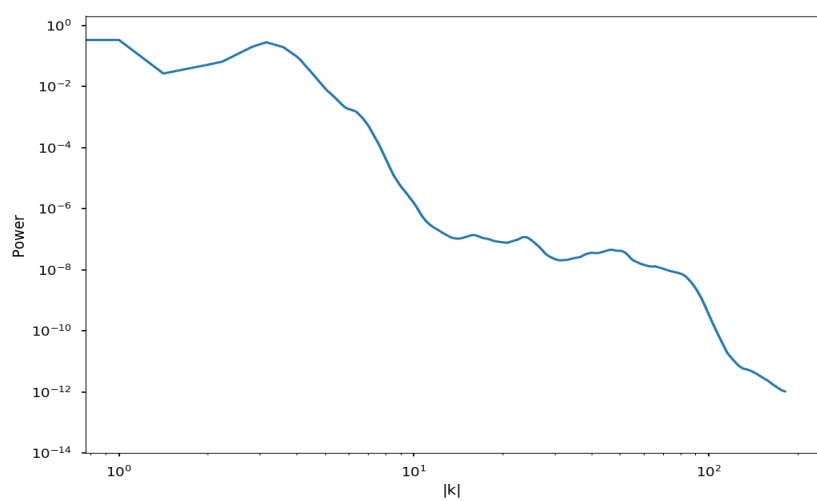
$$\begin{aligned} \mathcal{P}(s) &= \mathcal{G}(s, S) \\ &= \frac{1}{\sqrt{|2\pi S|}} \exp\left(-\frac{1}{2} s^\dagger S^{-1} s\right) \end{aligned}$$

$$S = \begin{pmatrix} \langle s_1 s_1 \rangle & \langle s_1 s_2 \rangle \\ \langle s_2 s_1 \rangle & \langle s_2 s_2 \rangle \end{pmatrix} \quad \text{2-dim.}$$

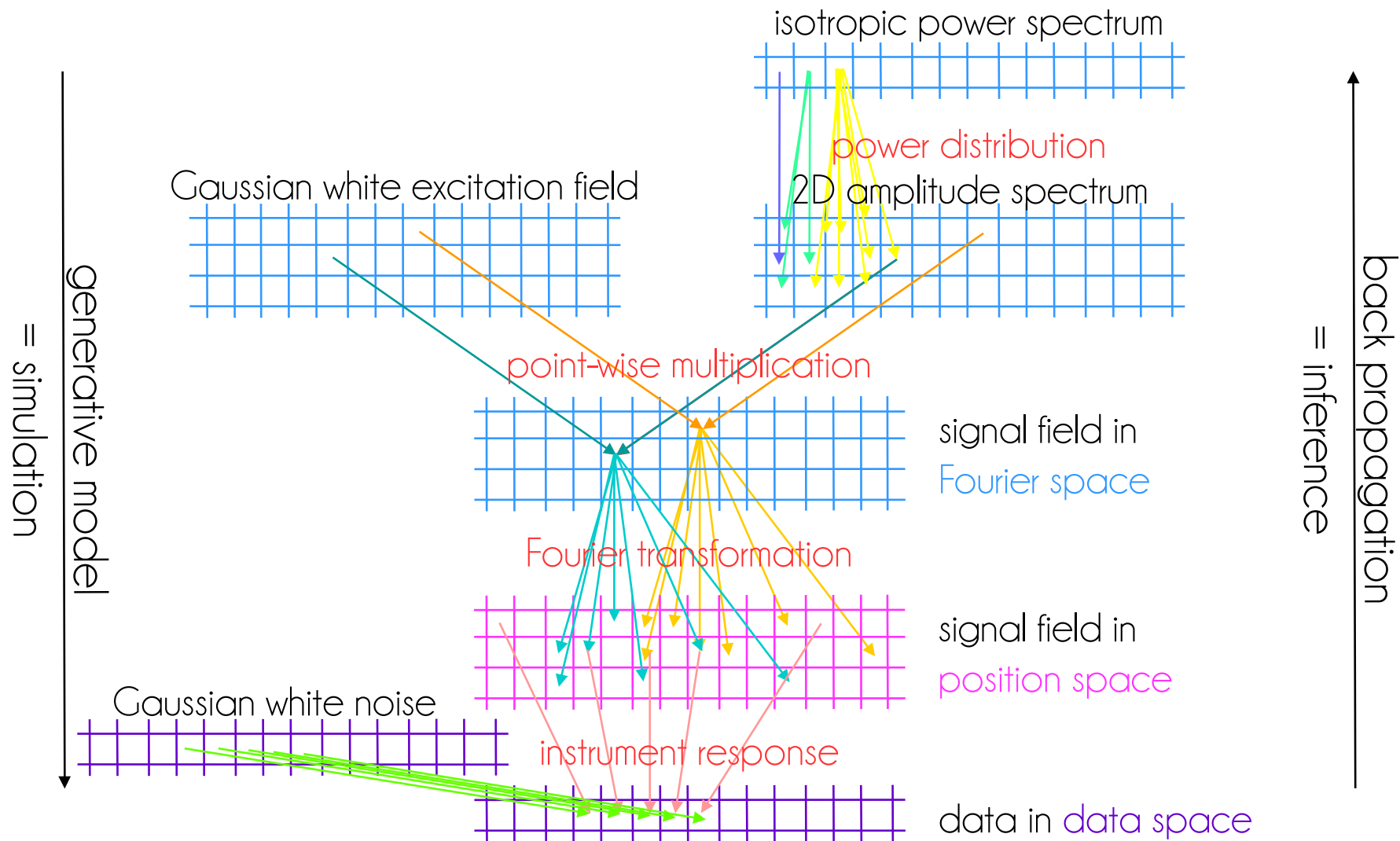
$$S_{ij} = \langle s_i s_j \rangle \quad n\text{-dim.}$$

$$S_{xy} = \langle s_x s_y \rangle, \quad x \in \mathbb{R}^n \quad \infty\text{-dim.}$$





IFT as neural network



Data model

known $\longrightarrow d = R e^{\textcolor{red}{s}} + \textcolor{red}{n}$

known response

$\textcolor{red}{\lambda} = R e^{\textcolor{red}{s}}$
 $\textcolor{red}{\text{unknown}}$

$$\mathcal{P}(s) = \mathcal{G}(s, \textcolor{red}{S}) \quad \textcolor{red}{\text{unknown}}$$

$$\mathcal{P}(d|\lambda) = \prod_i \frac{\lambda_i^{d_i}}{d_i!} e^{-\lambda_i}$$



Information

$$\begin{aligned}\mathcal{H}(\mathbf{d}, \mathbf{s}, \boldsymbol{\tau}) &= -\log \mathcal{P}(\mathbf{d}, \mathbf{s}, \boldsymbol{\tau}) \\ &= 1^\dagger [\log(d!) + \mathbf{R} (\mathbf{e}^{\mathbf{s}} + \mathbf{e}^{\mathbf{u}})] - \mathbf{d}^\dagger \log [\mathbf{R} (\mathbf{e}^{\mathbf{s}} + \mathbf{e}^{\mathbf{u}})] \\ &\quad + \frac{1}{2} \mathbf{s}^\dagger \mathbf{S}^{-1} \mathbf{s} + \frac{1}{2} \log (\det [\mathbf{S}])\end{aligned}$$

$$+ (\boldsymbol{\alpha} - \mathbf{1})^\dagger$$

$$+ (\boldsymbol{\beta} - \mathbf{1})^\dagger$$

- Convert into **generative model**
- Compress information into Gaussian via **Metric Gaussian Variational Inference**

$$\mathbf{S} = \sum_k \mathbf{e}^{\tau_k} \mathbf{S}_k$$

Variational Bayes

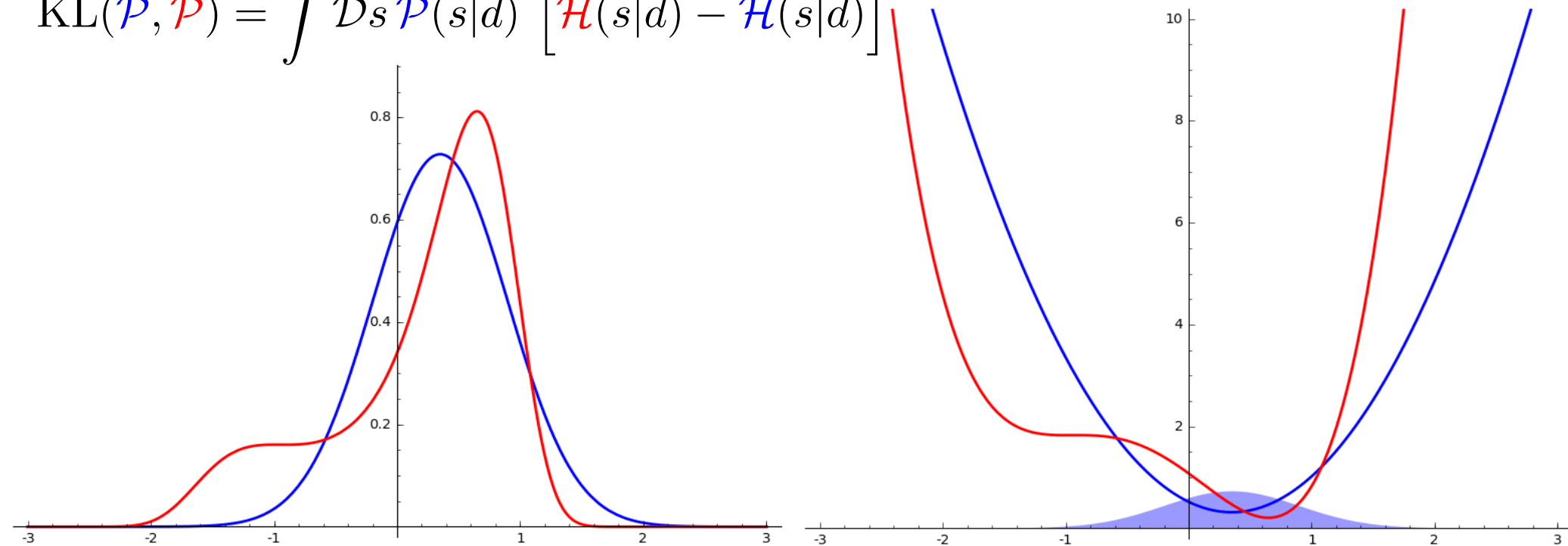
$$\mathcal{P}(s|d)$$

$$\tilde{\mathcal{P}}(s|d) = \mathcal{G}(s - m, D)$$

$$\mathcal{H}(s|d)$$

$$\tilde{\mathcal{H}}(s|d) \hat{=} \frac{1}{2}(s - m)^\dagger D^{-1}(s - m)$$

$$\text{KL}(\tilde{\mathcal{P}}, \mathcal{P}) = \int \mathcal{D}s \tilde{\mathcal{P}}(s|d) \left[\mathcal{H}(s|d) - \tilde{\mathcal{H}}(s|d) \right]$$



Metric Gaussian Variational Bayes

$$\mathcal{P}(s|d)$$

$$\tilde{\mathcal{P}}(s|d) = \mathcal{G}(s - m, D)$$

$$\mathcal{H}(s|d)$$

$$\tilde{\mathcal{H}}(s|d) \hat{=} \frac{1}{2} (s - m)^\dagger D^{-1} (s - m)$$

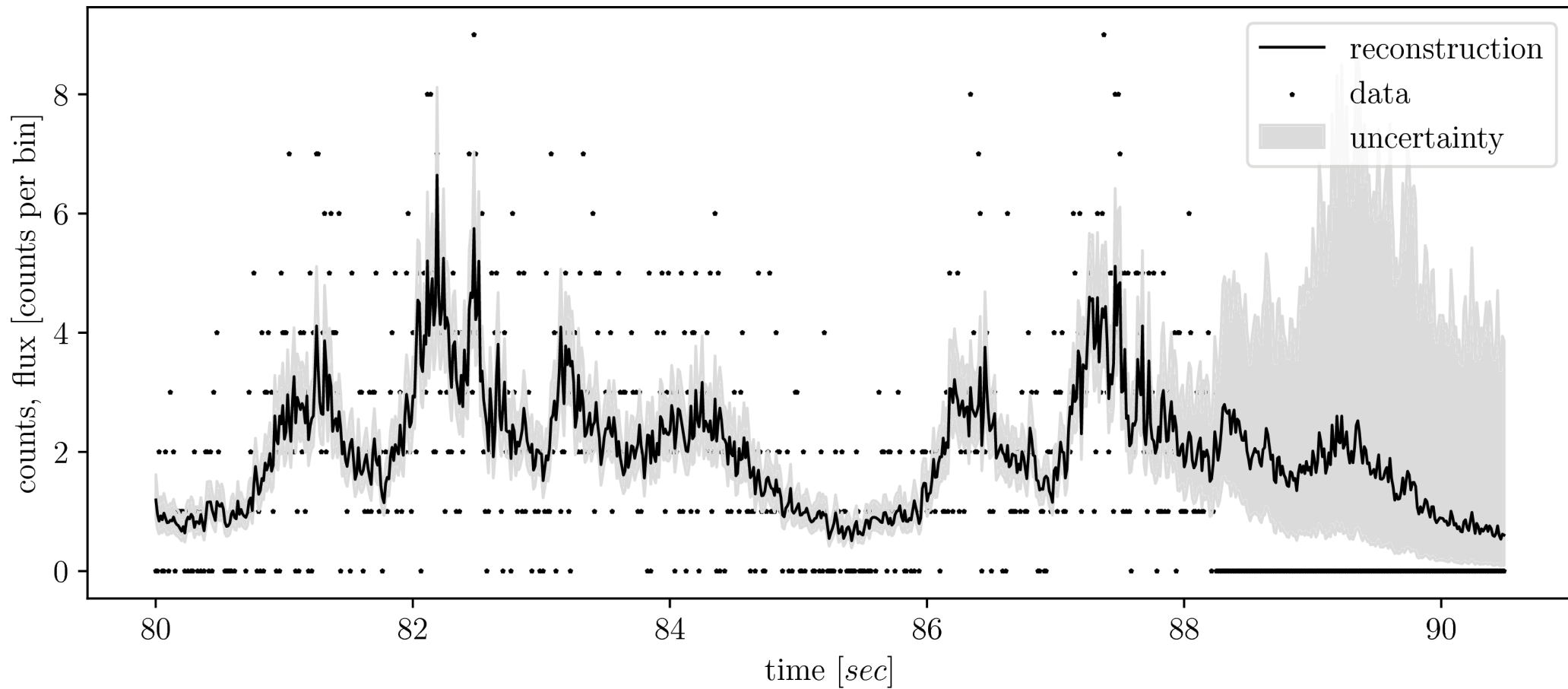
Knollmüller & Enßlin (2019)

$$\text{KL}(\tilde{\mathcal{P}}, \mathcal{P}) = \int \mathcal{D}s \tilde{\mathcal{P}}(s|d) \left[\mathcal{H}(s|d) - \tilde{\mathcal{H}}(s|d) \right]$$

$$D \approx \left\langle \frac{\partial \mathcal{H}(d, s)}{\partial s} \frac{\partial \mathcal{H}(d, s)}{\partial s}^\dagger \right\rangle_{(d|s=m)}^{-1}$$

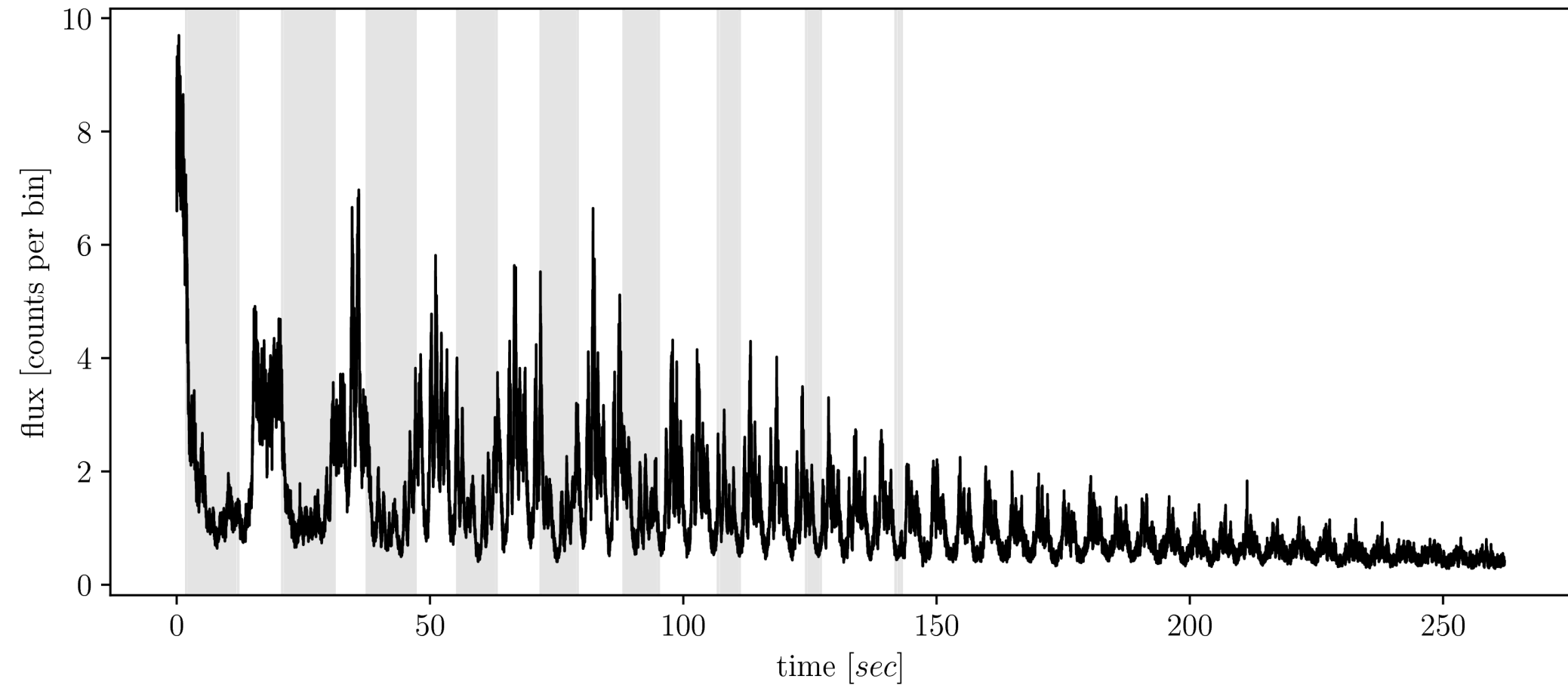
Magnetar flare SGR 1900+14

Pumpe et al. (2018)



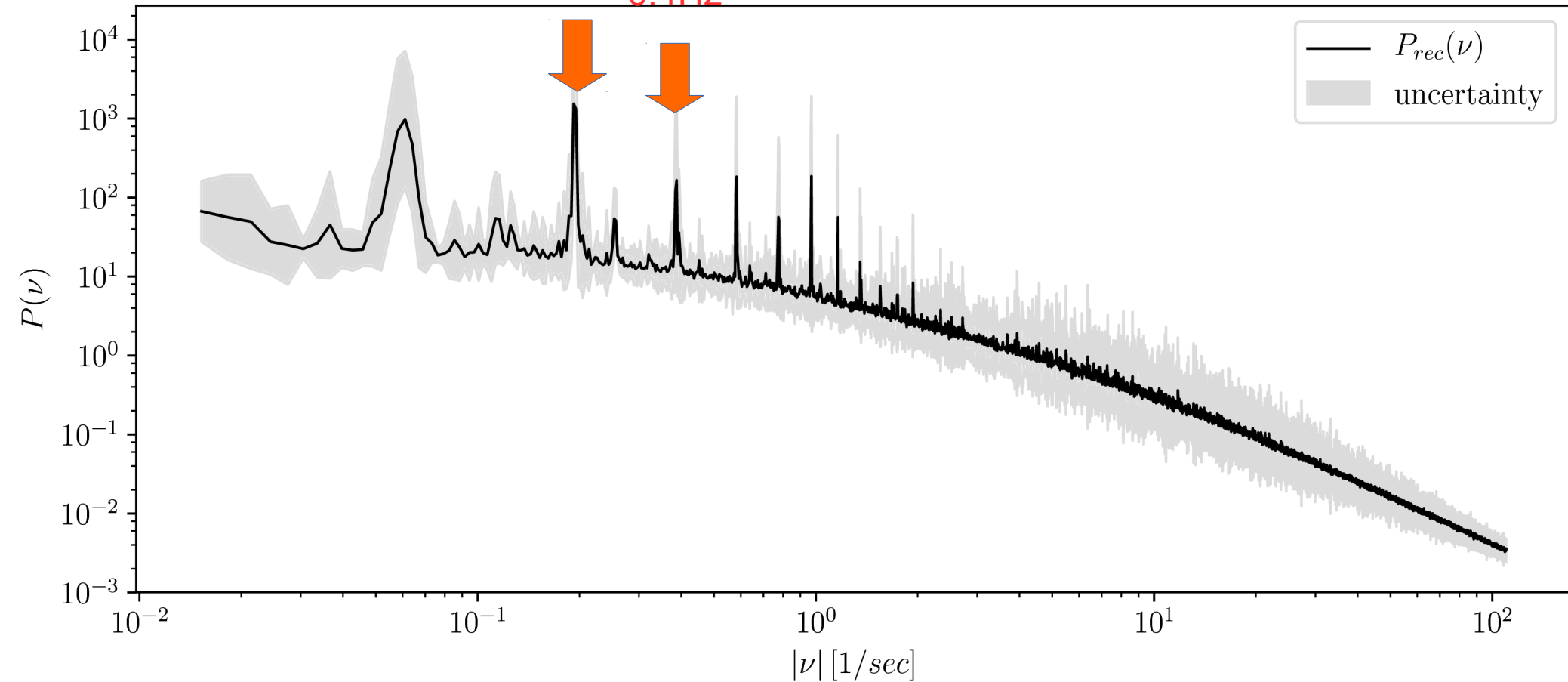
Magnetar flare SGR 1900+14

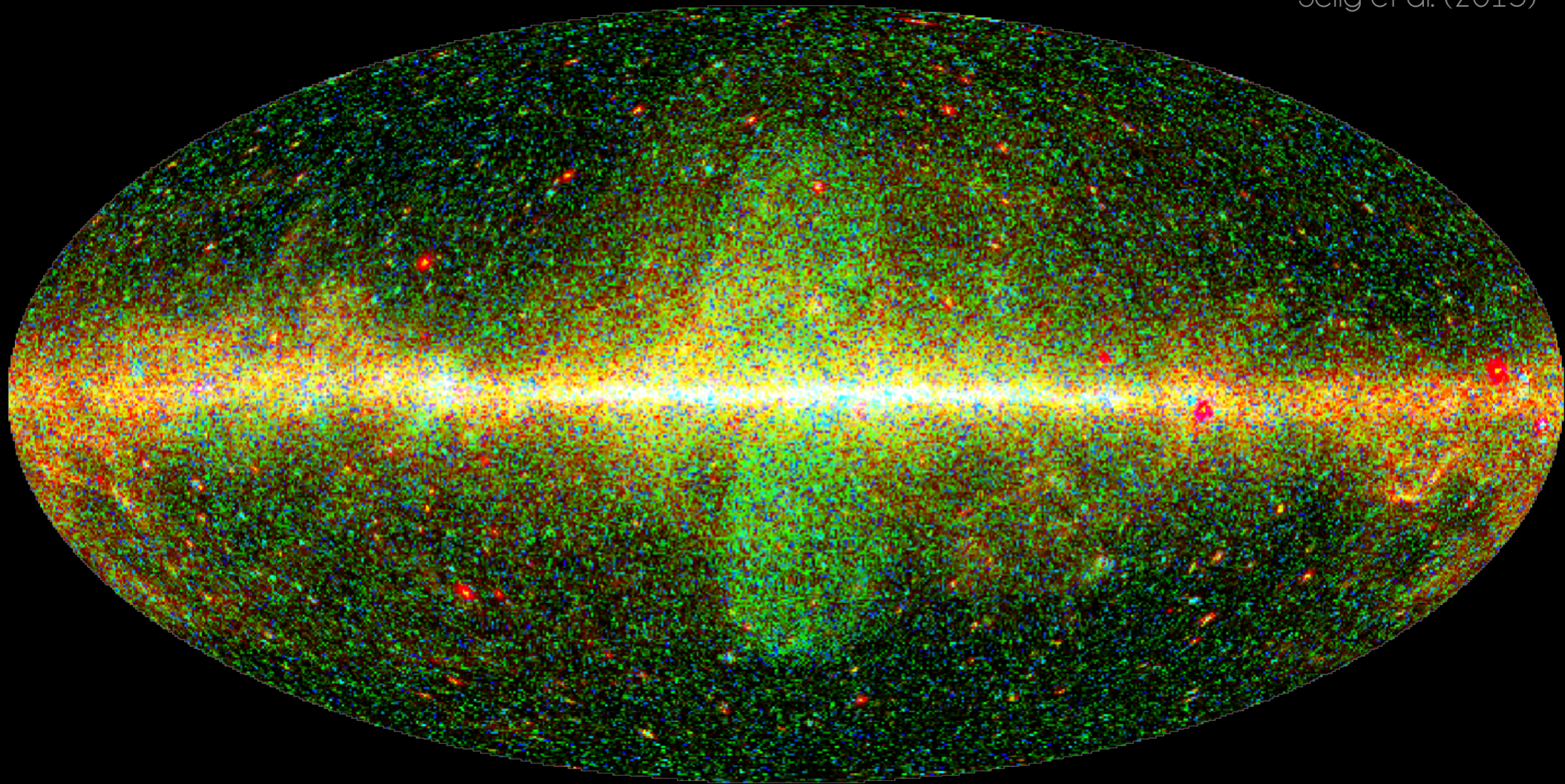
Pumpe et al. (2018)

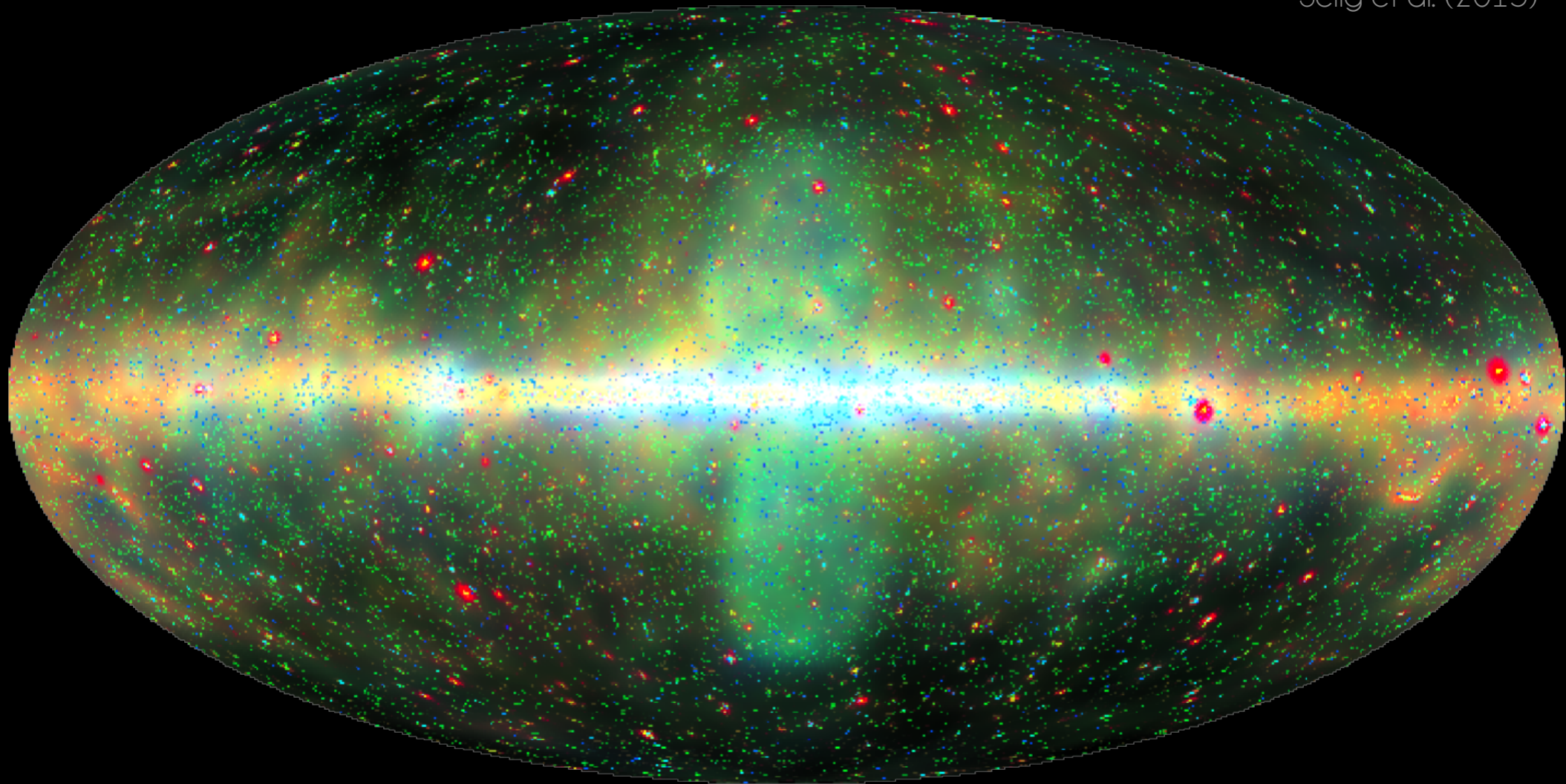


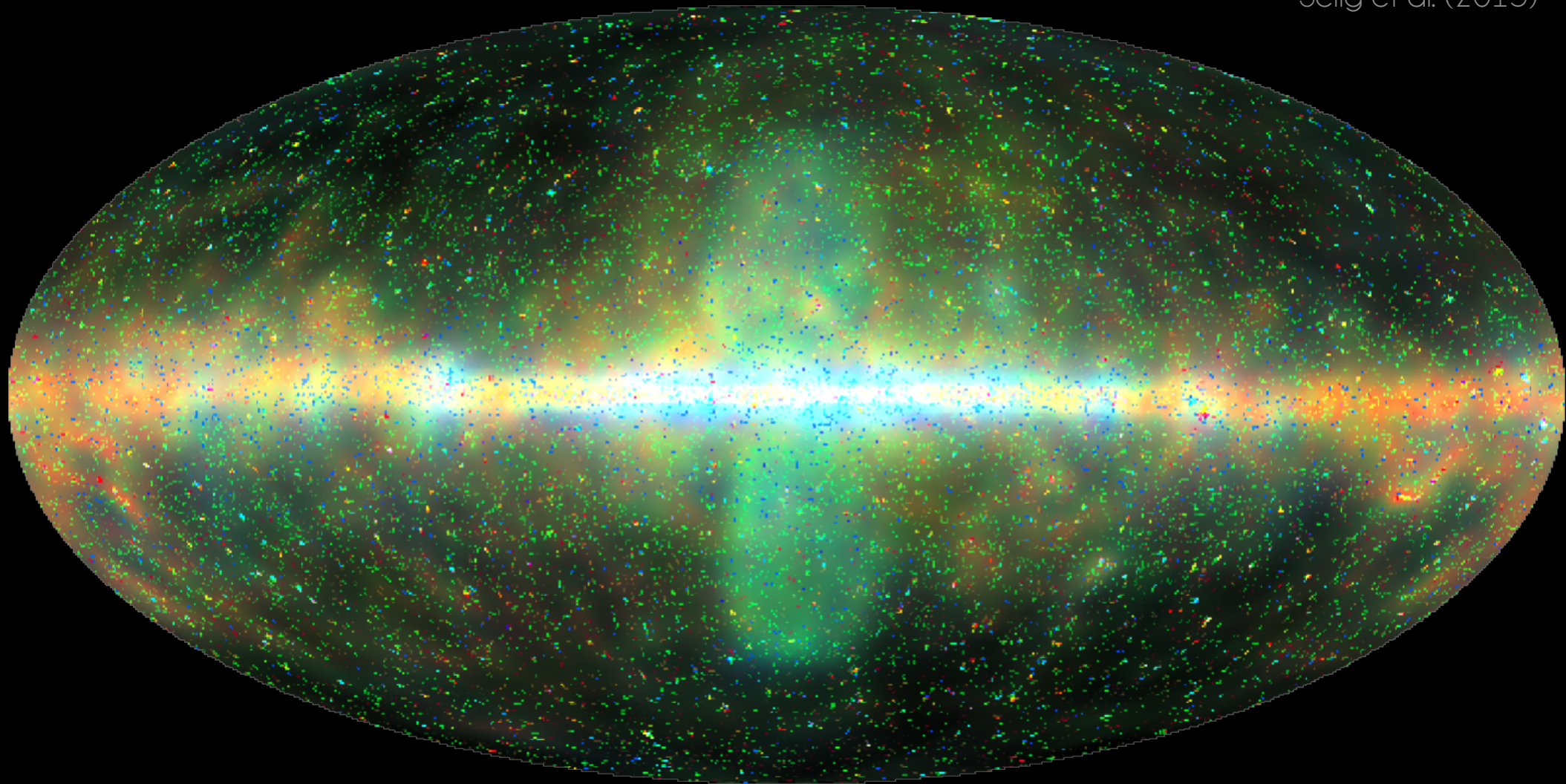
Magnetar flare SGR 1900+14

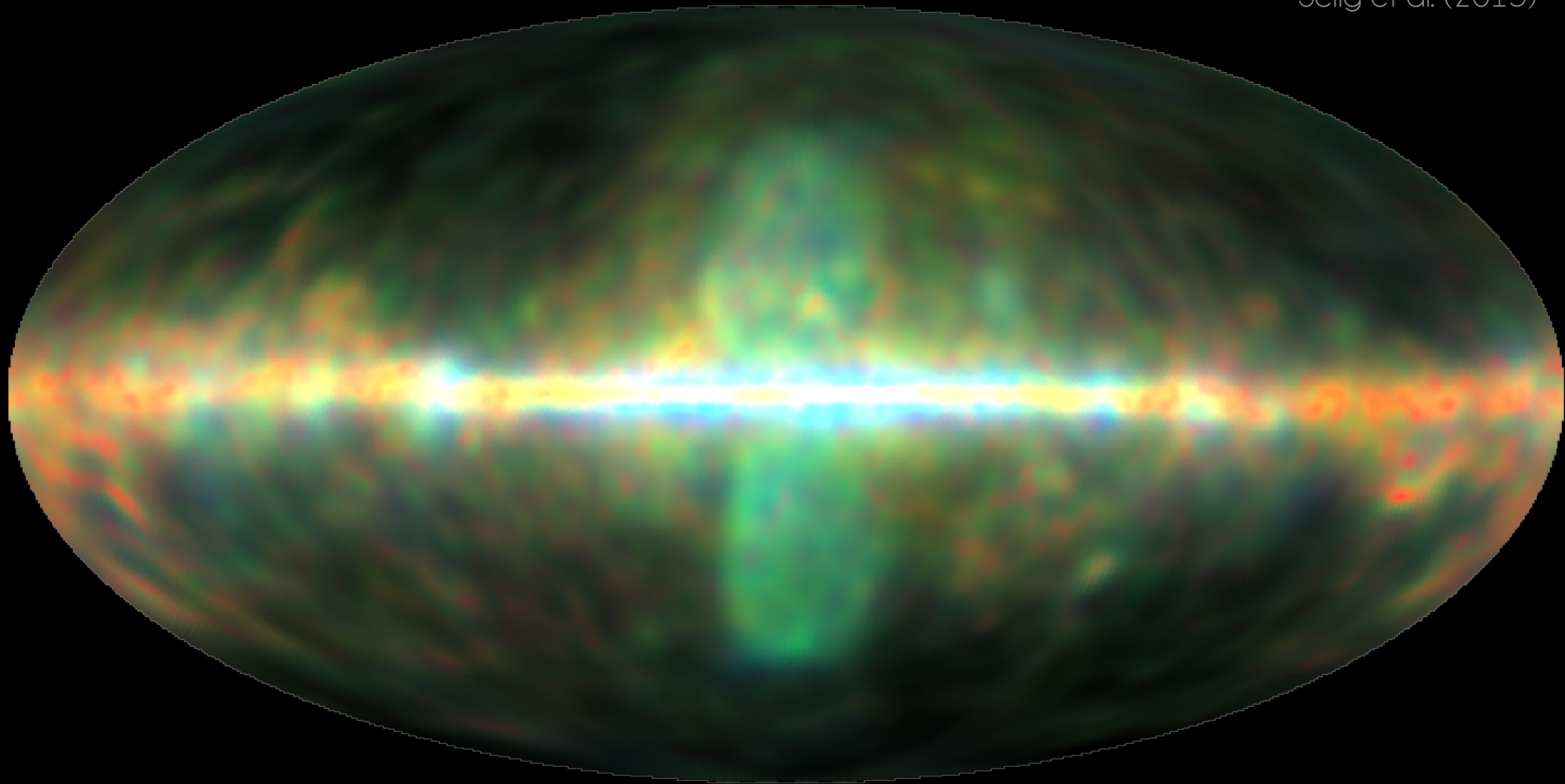
0.2Hz ^{Pumpe et al. (2018)}
0.4Hz

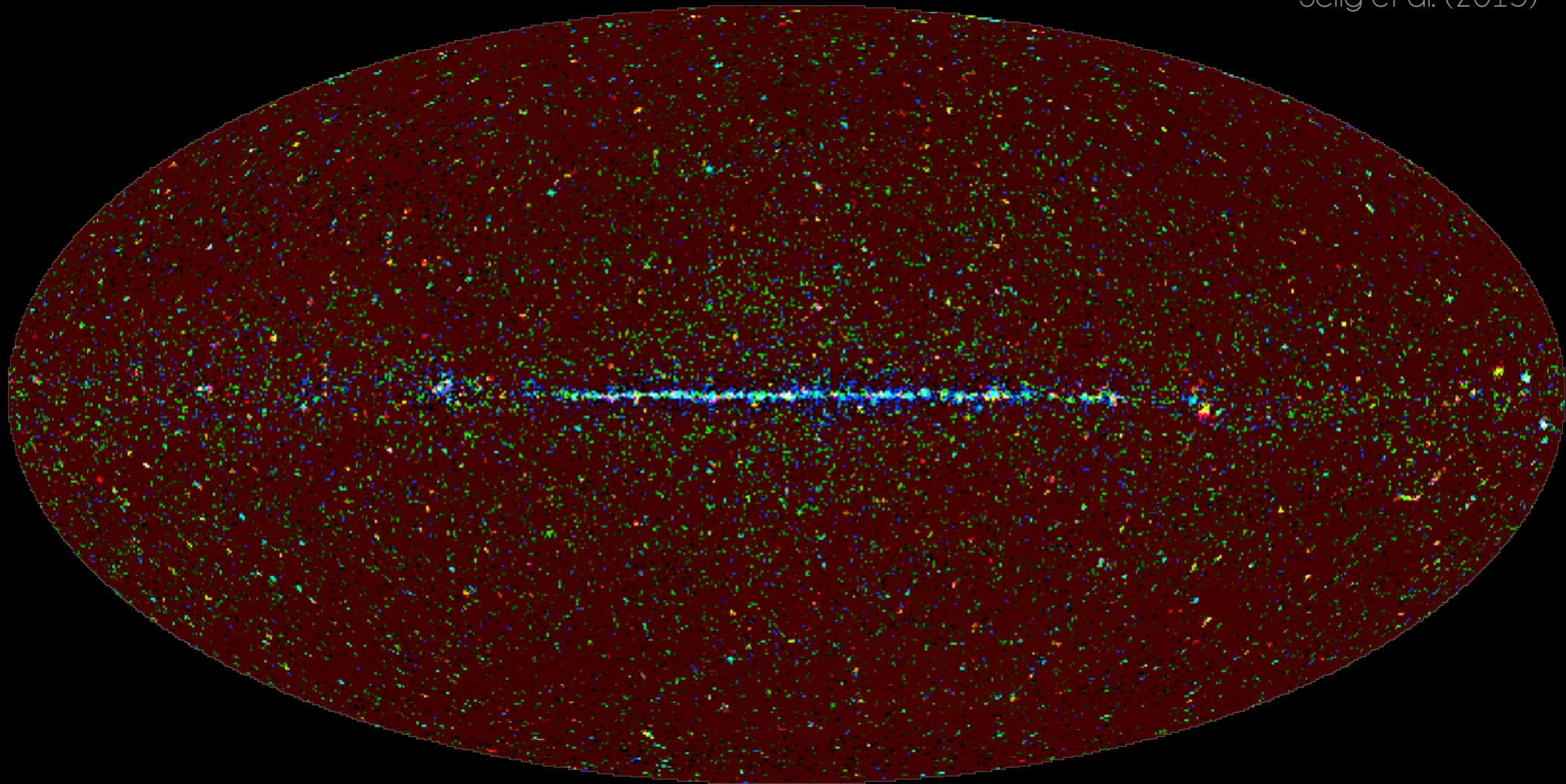


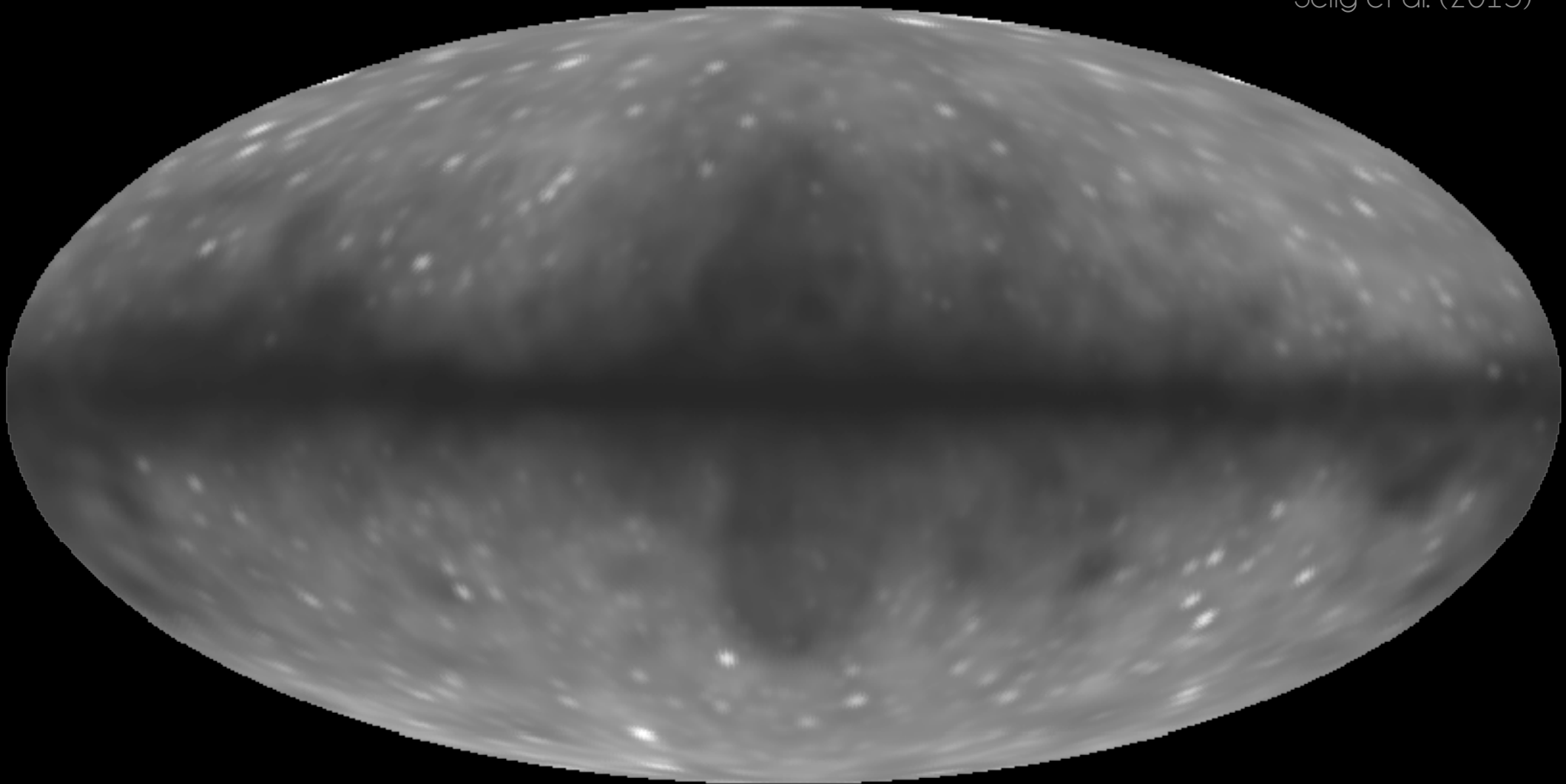


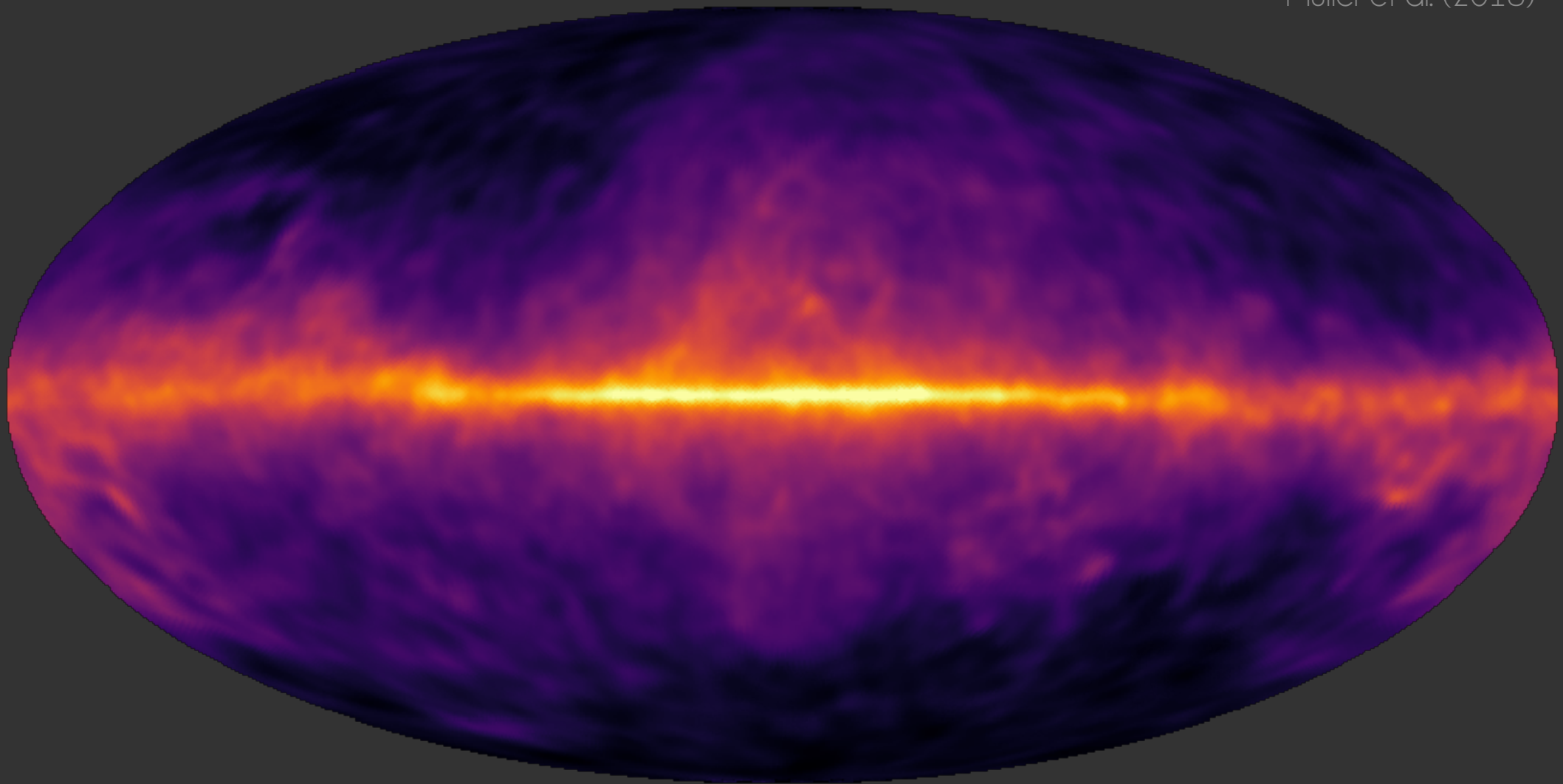




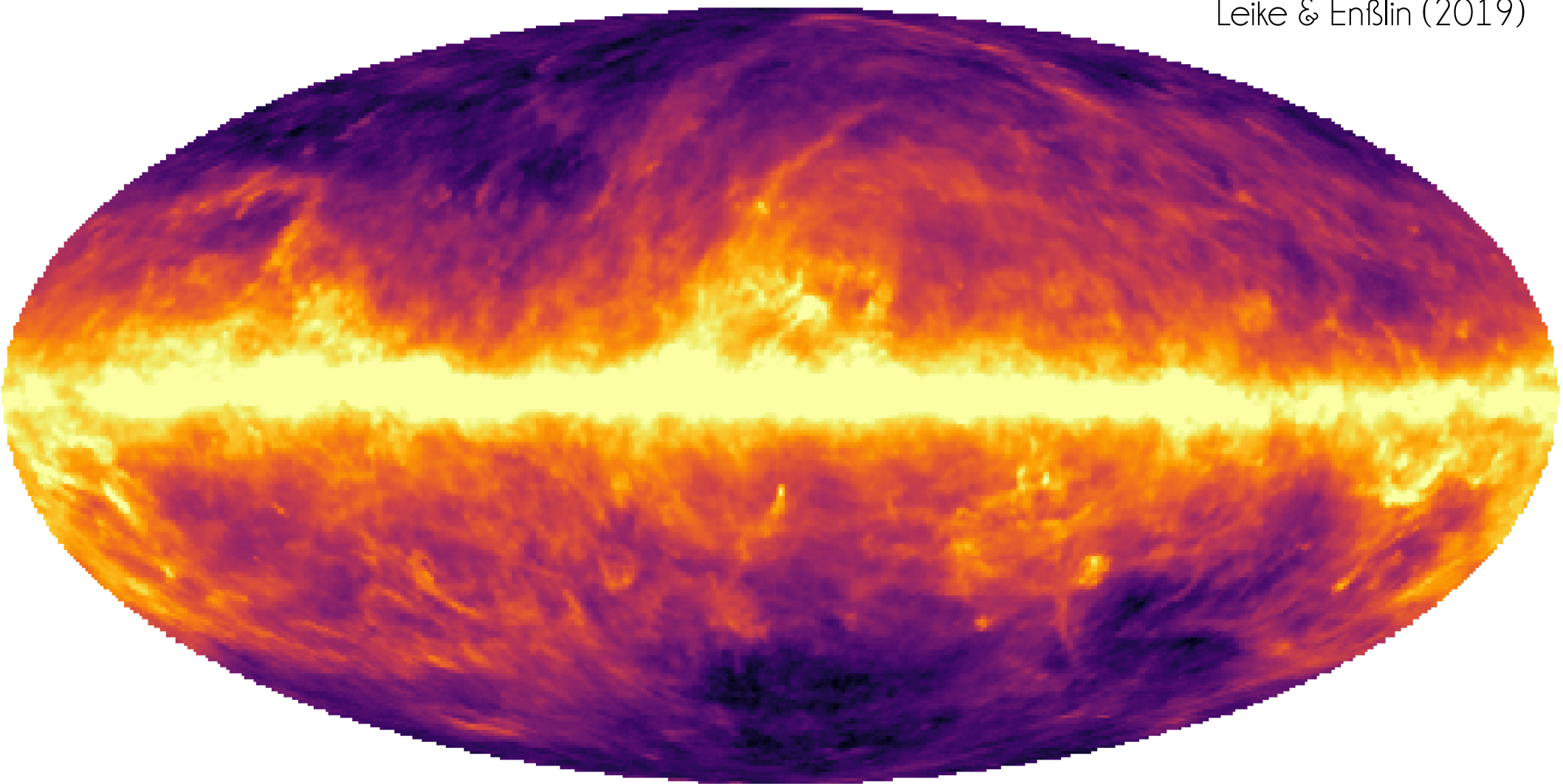




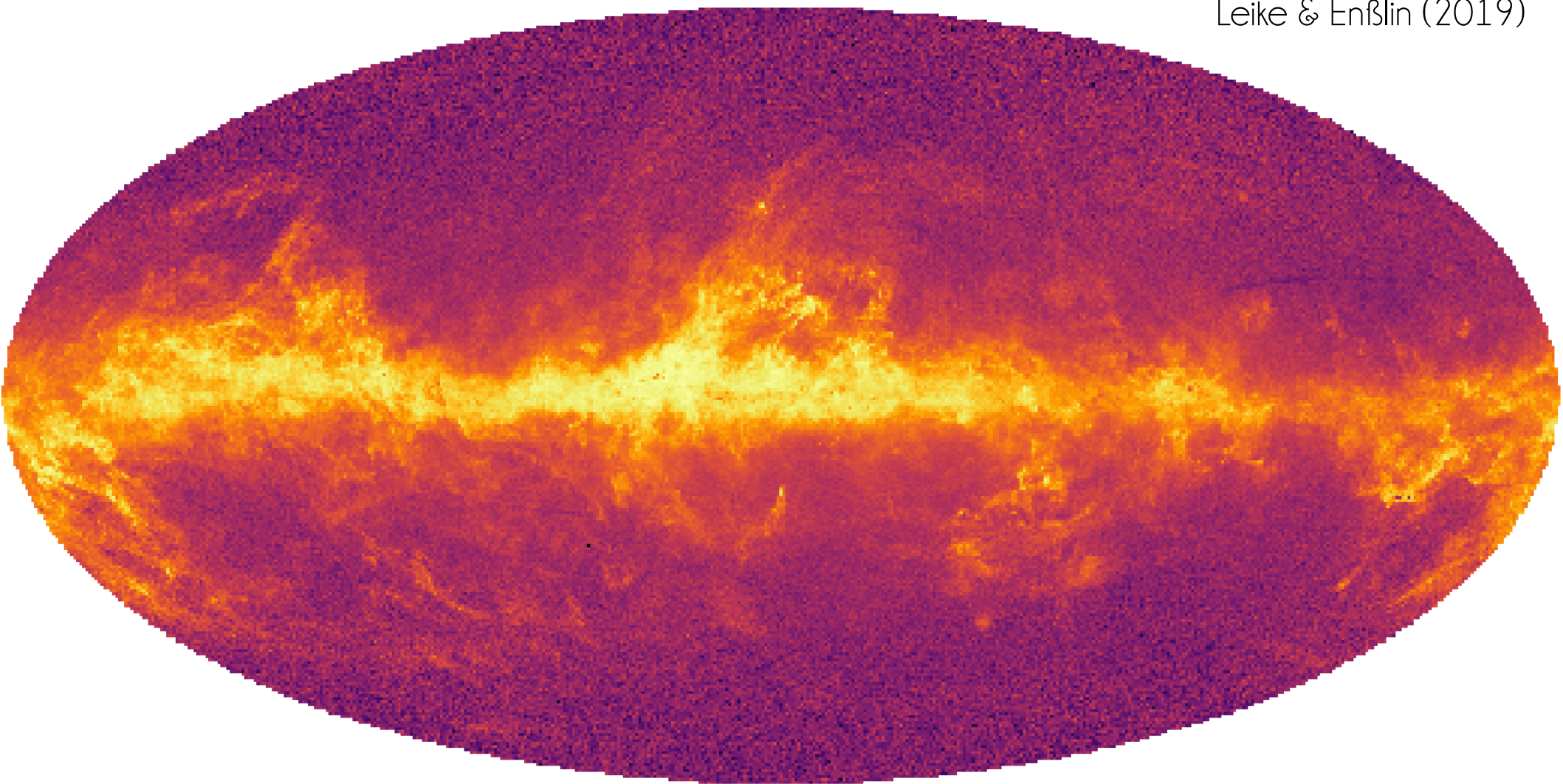




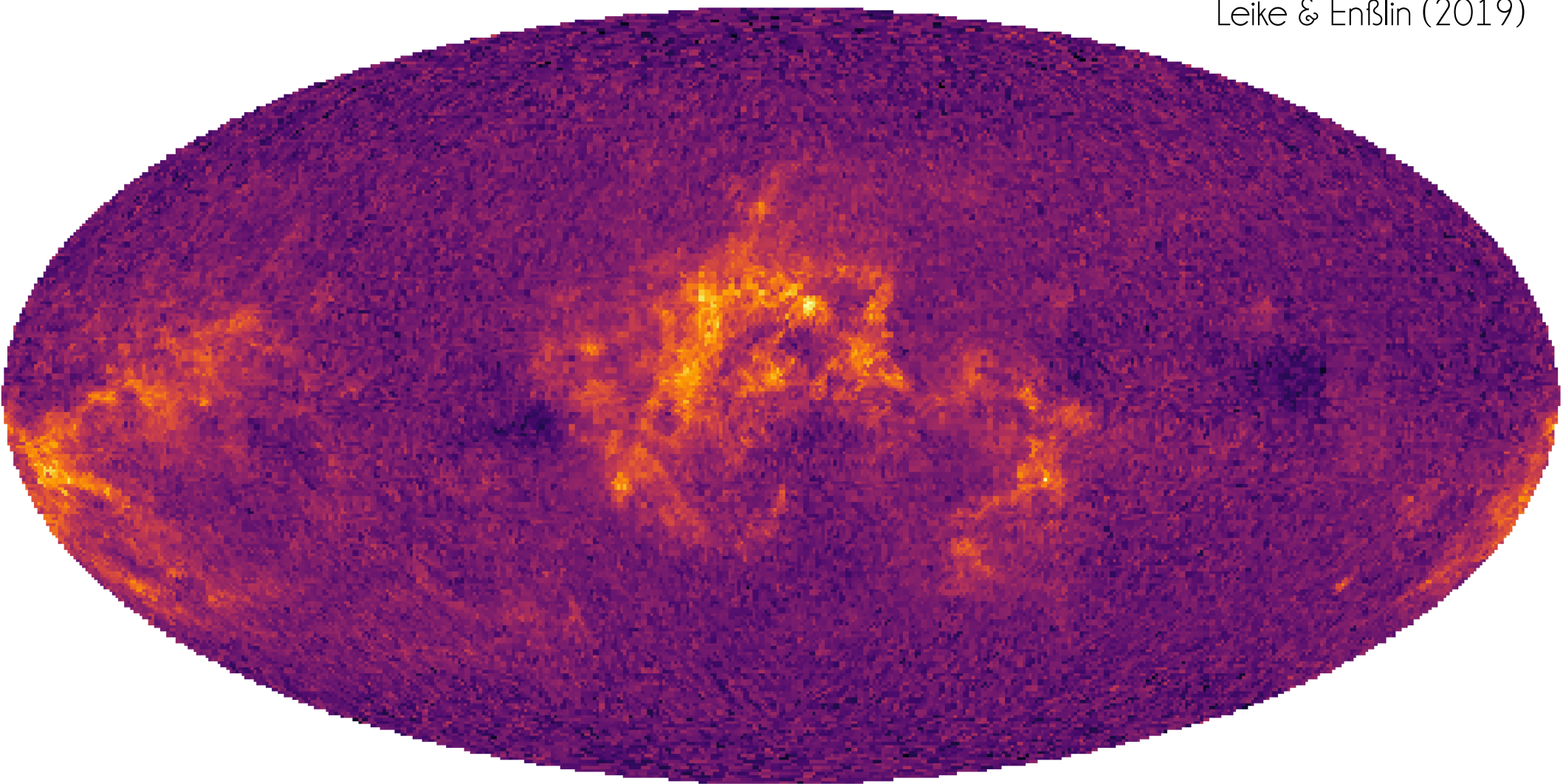
Galactic dust by Planck
Leike & Enßlin (2019)



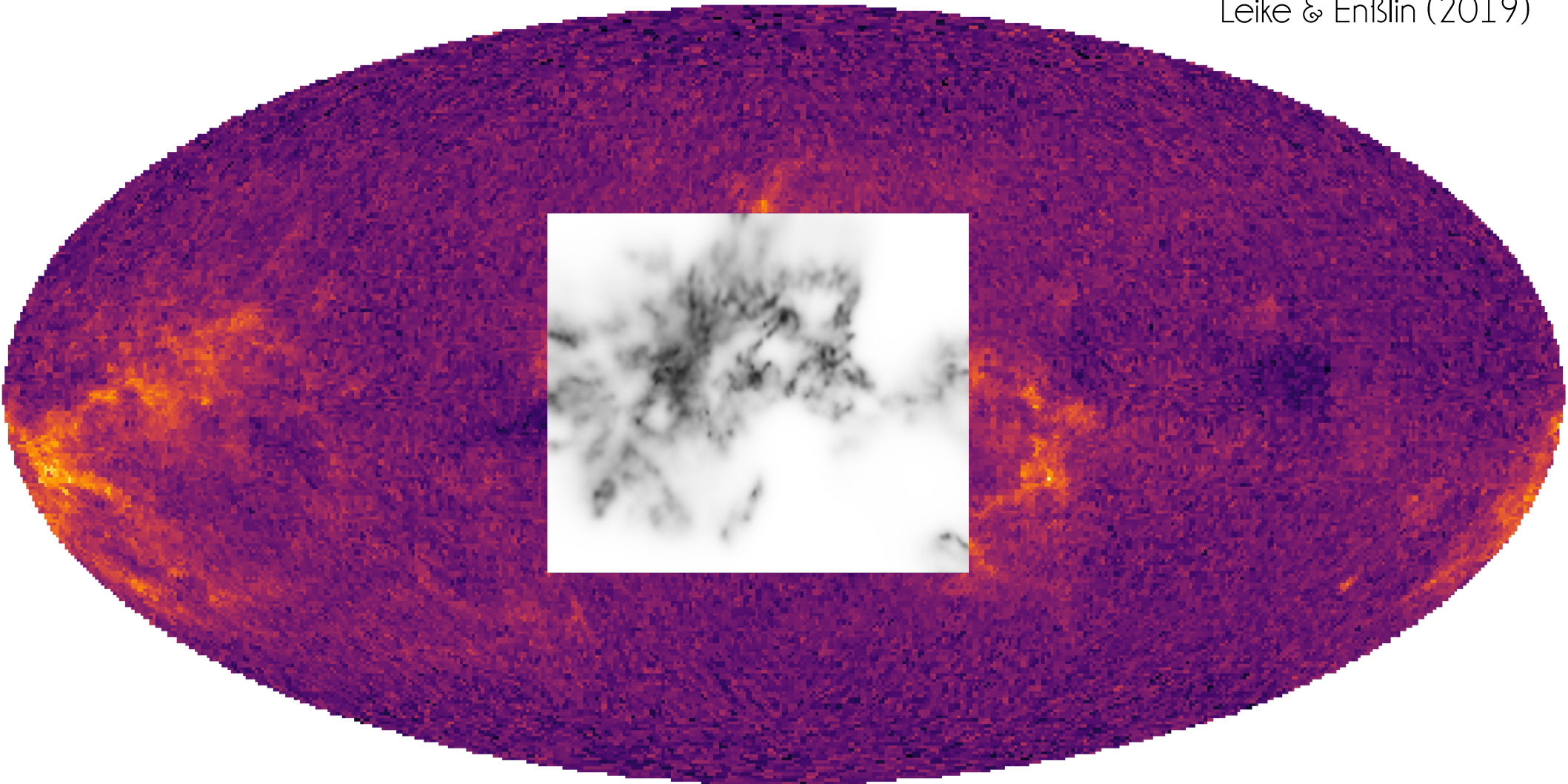
Galactic dust by Gaia
Leike & Enßlin (2019)



Galactic dust by Gaia
Leike & Enßlin (2019)

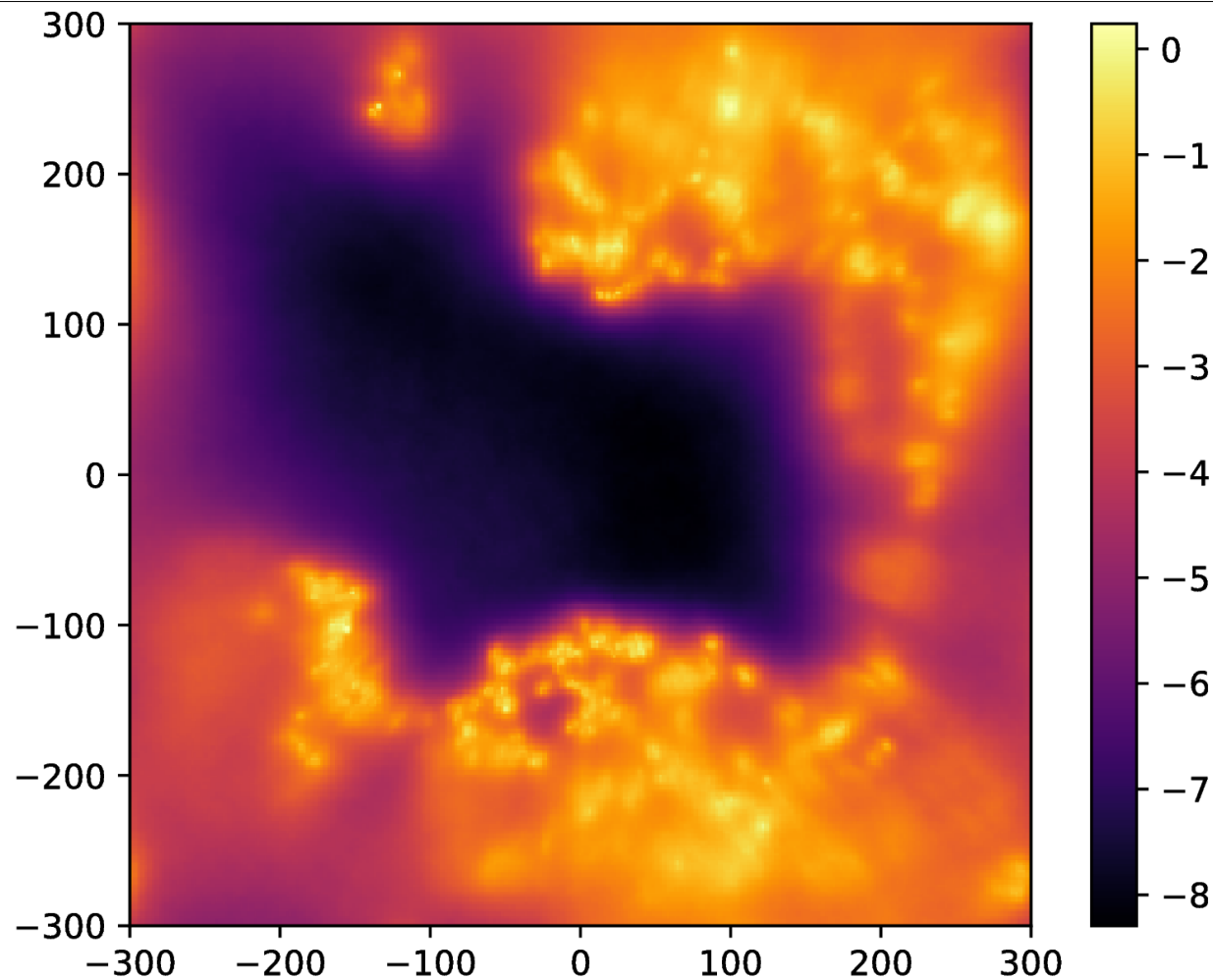


Galactic dust by Gaia
Leike & Enßlin (2019)



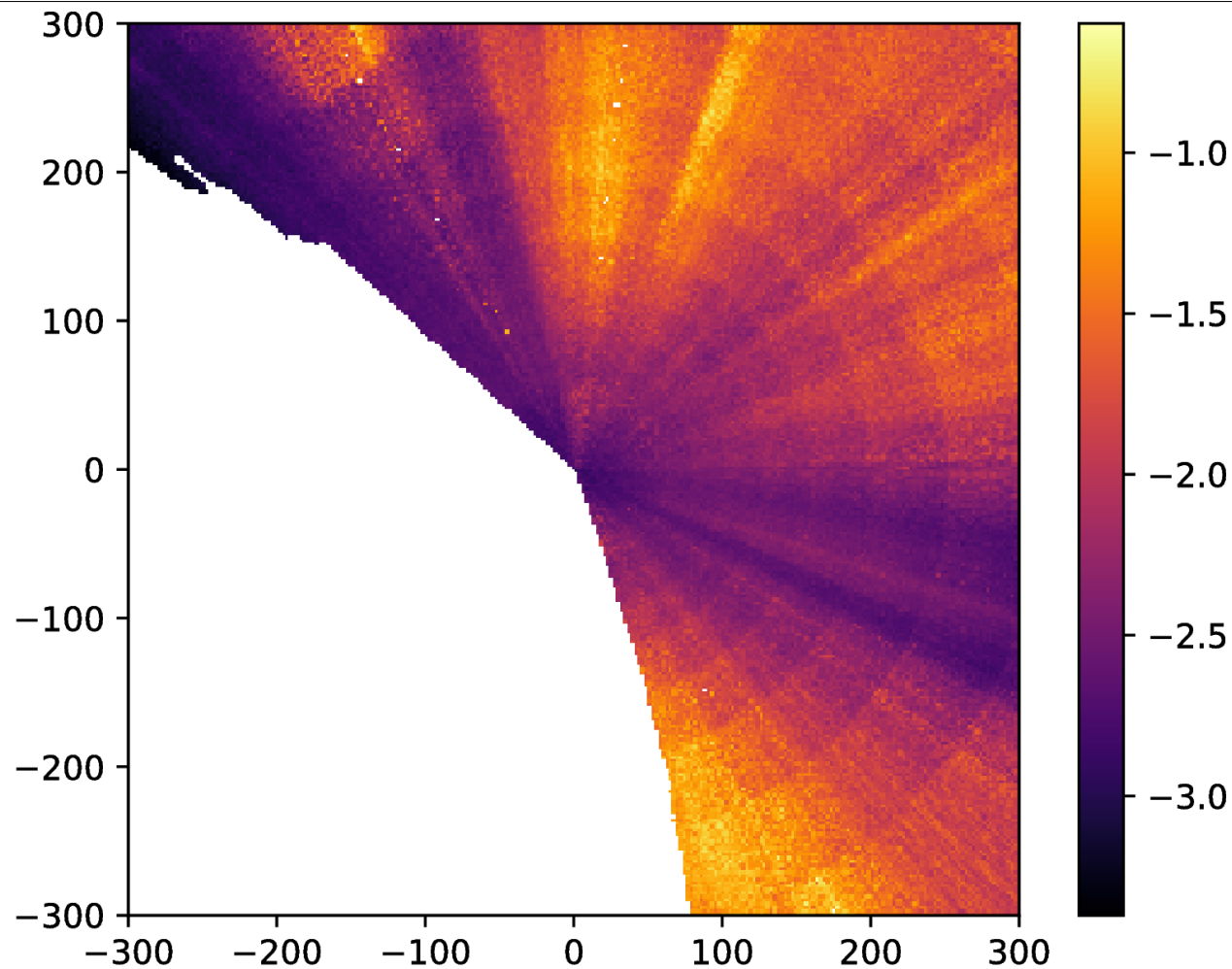
log dust density

Reimar Leike et al. (2019)



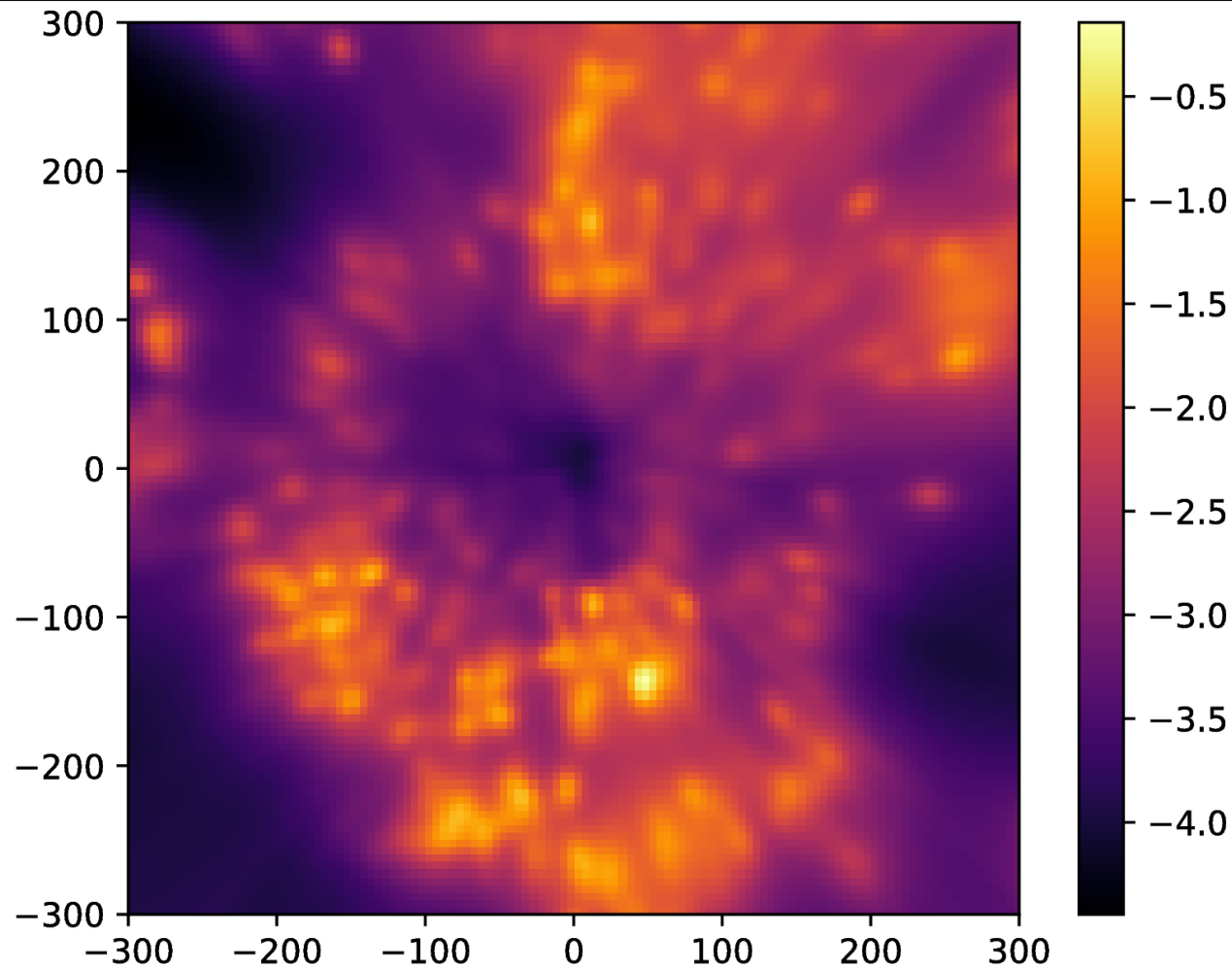
log dust density

Green et al. (2018.)



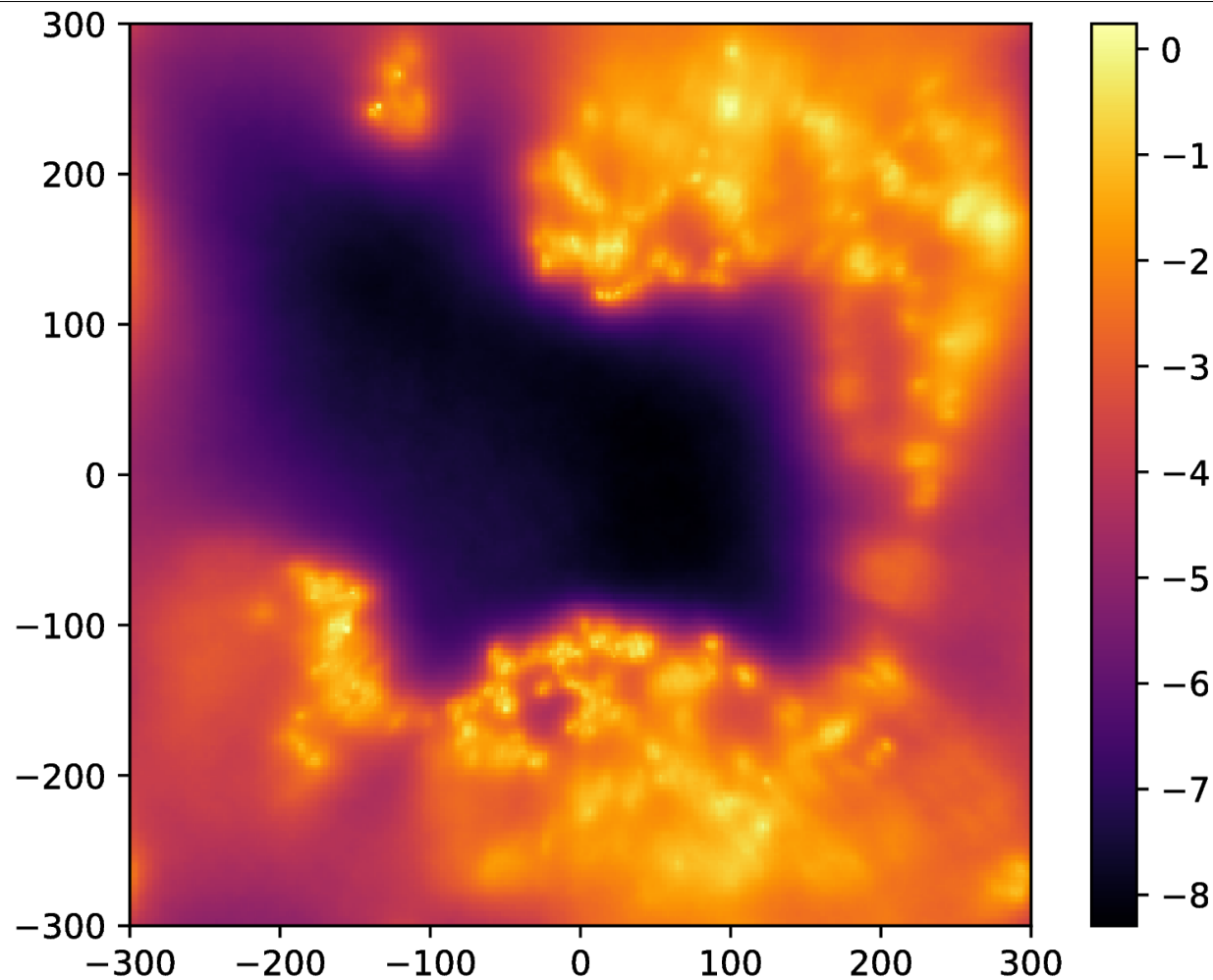
log dust density

Lallement et al. (2018)

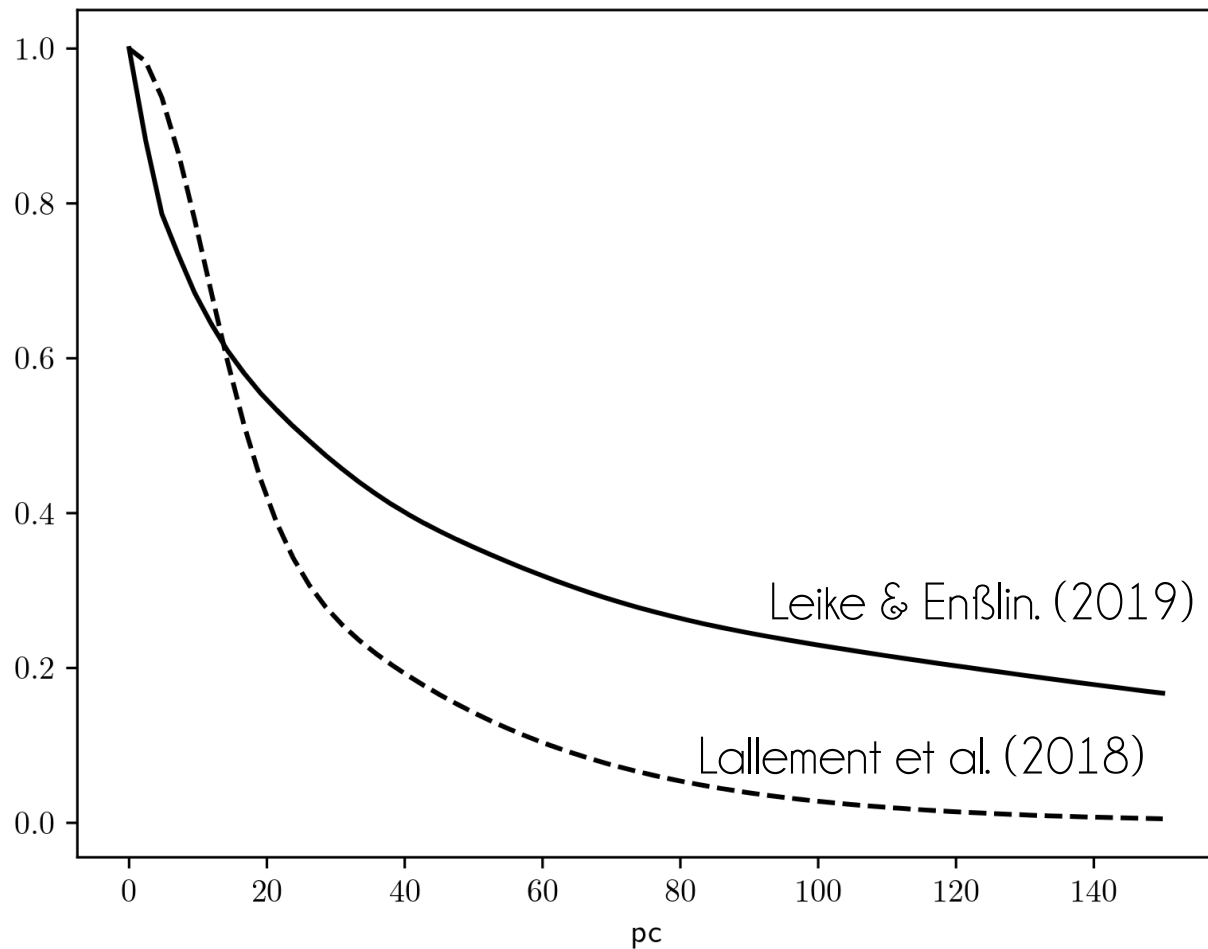


log dust density

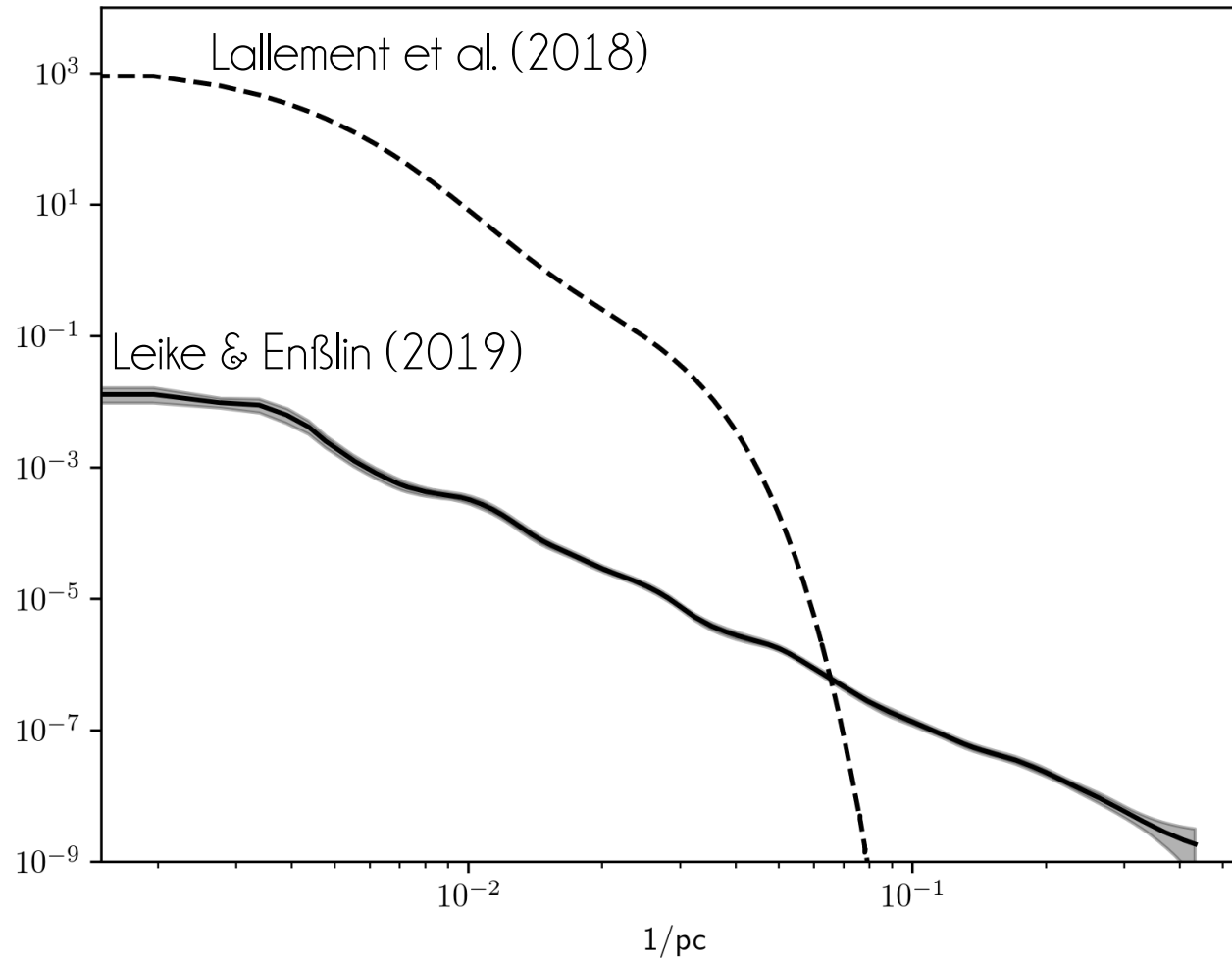
Reimar Leike et al. (2019)



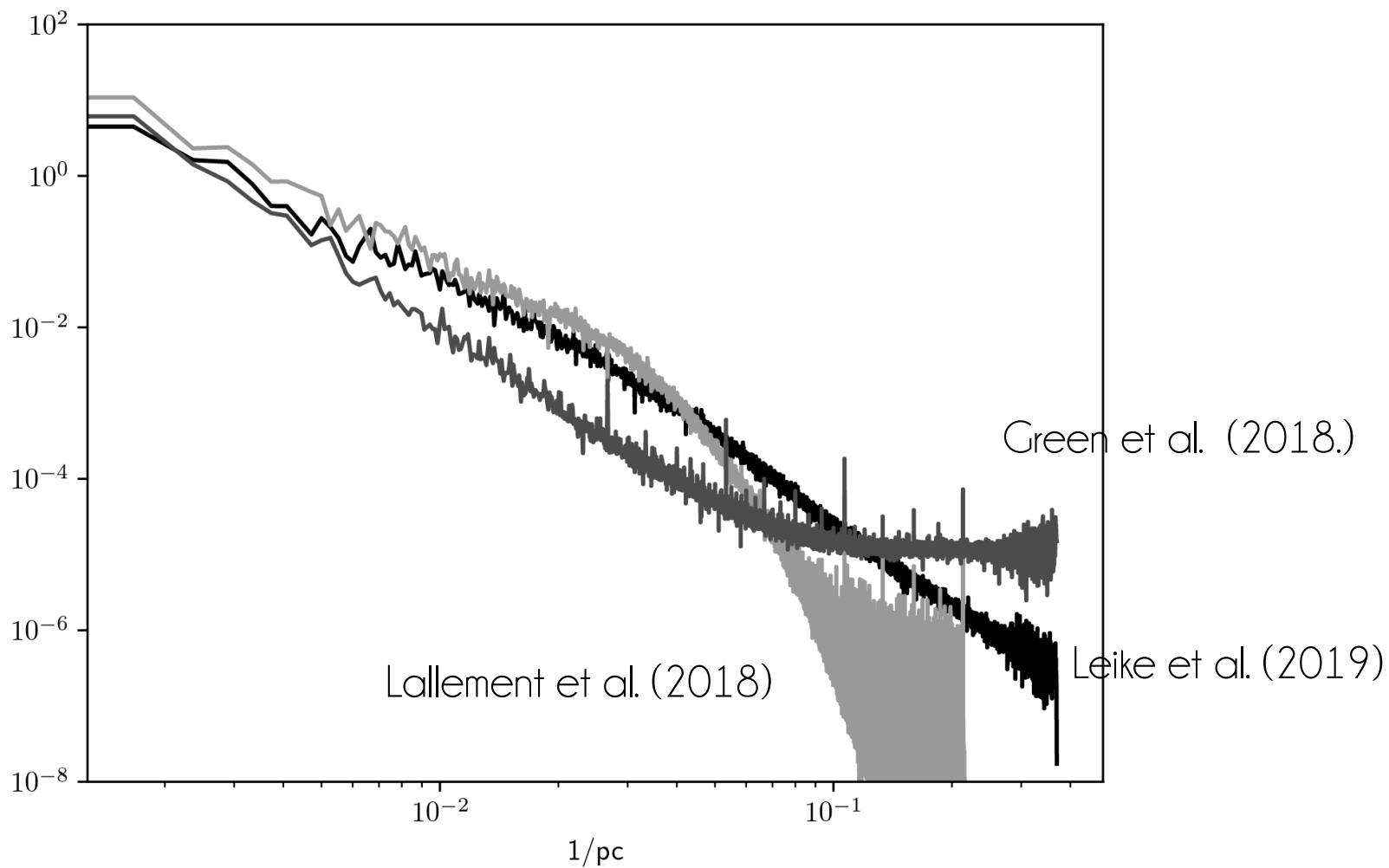
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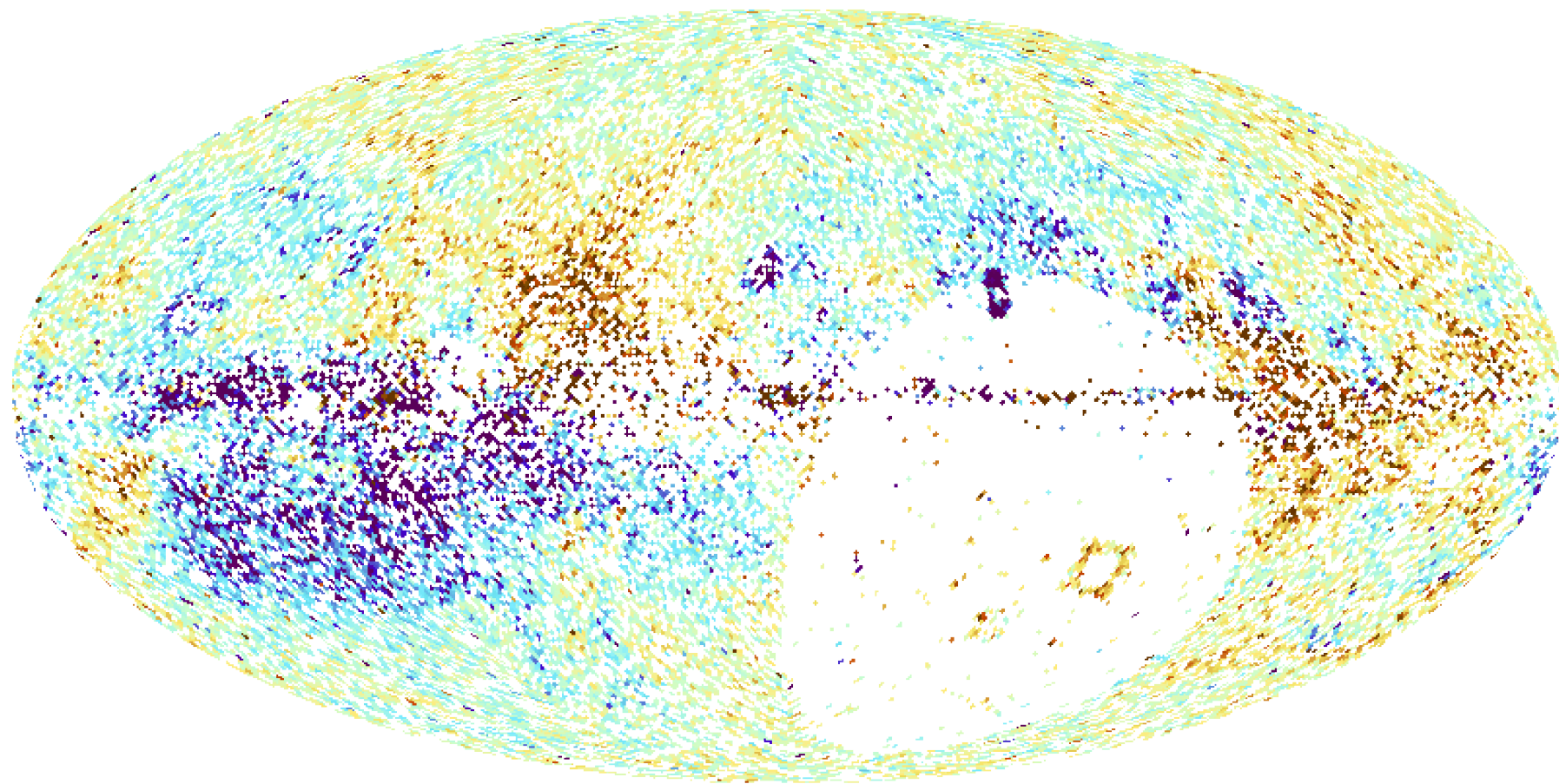


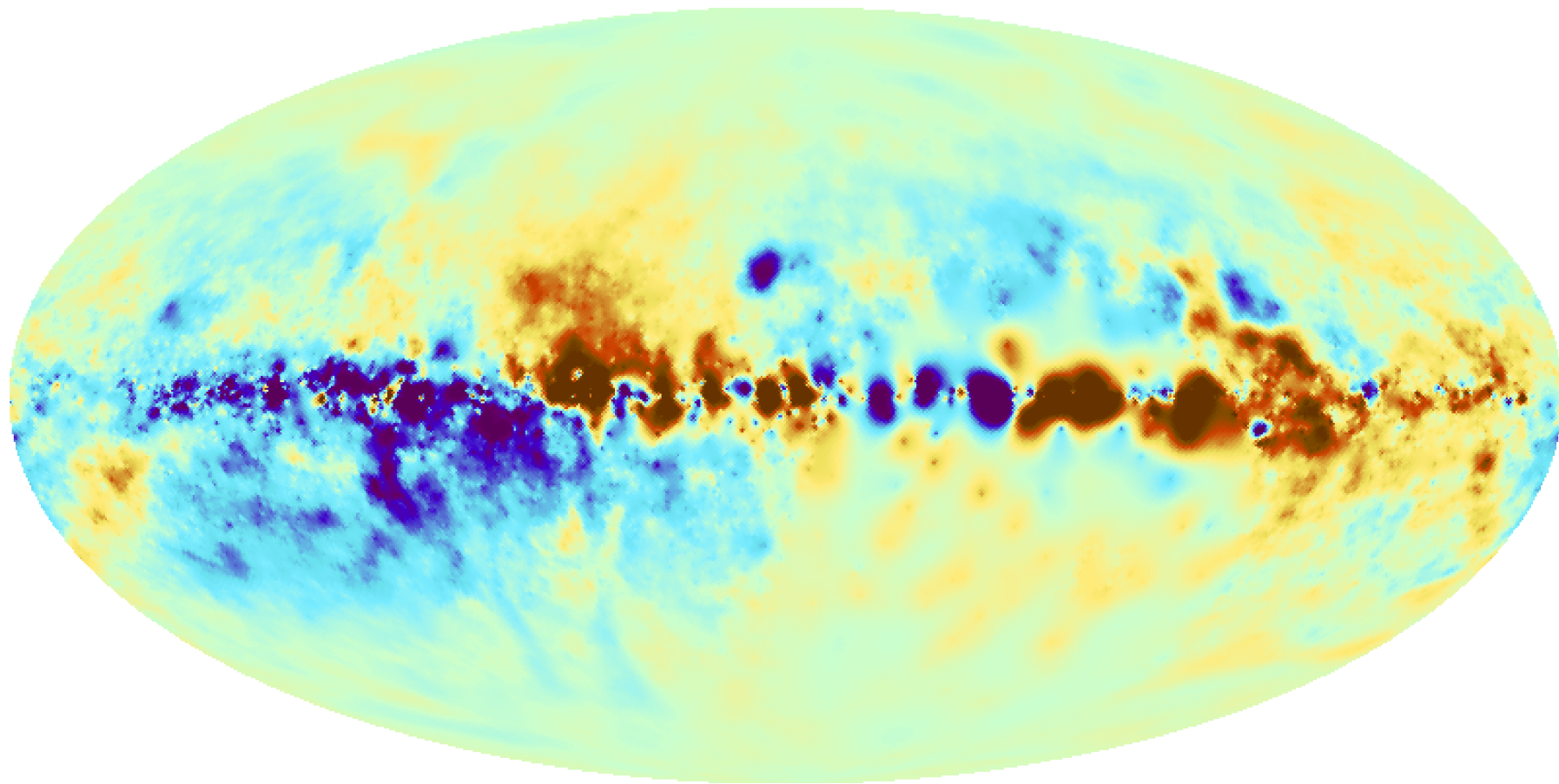
assumed power spectra

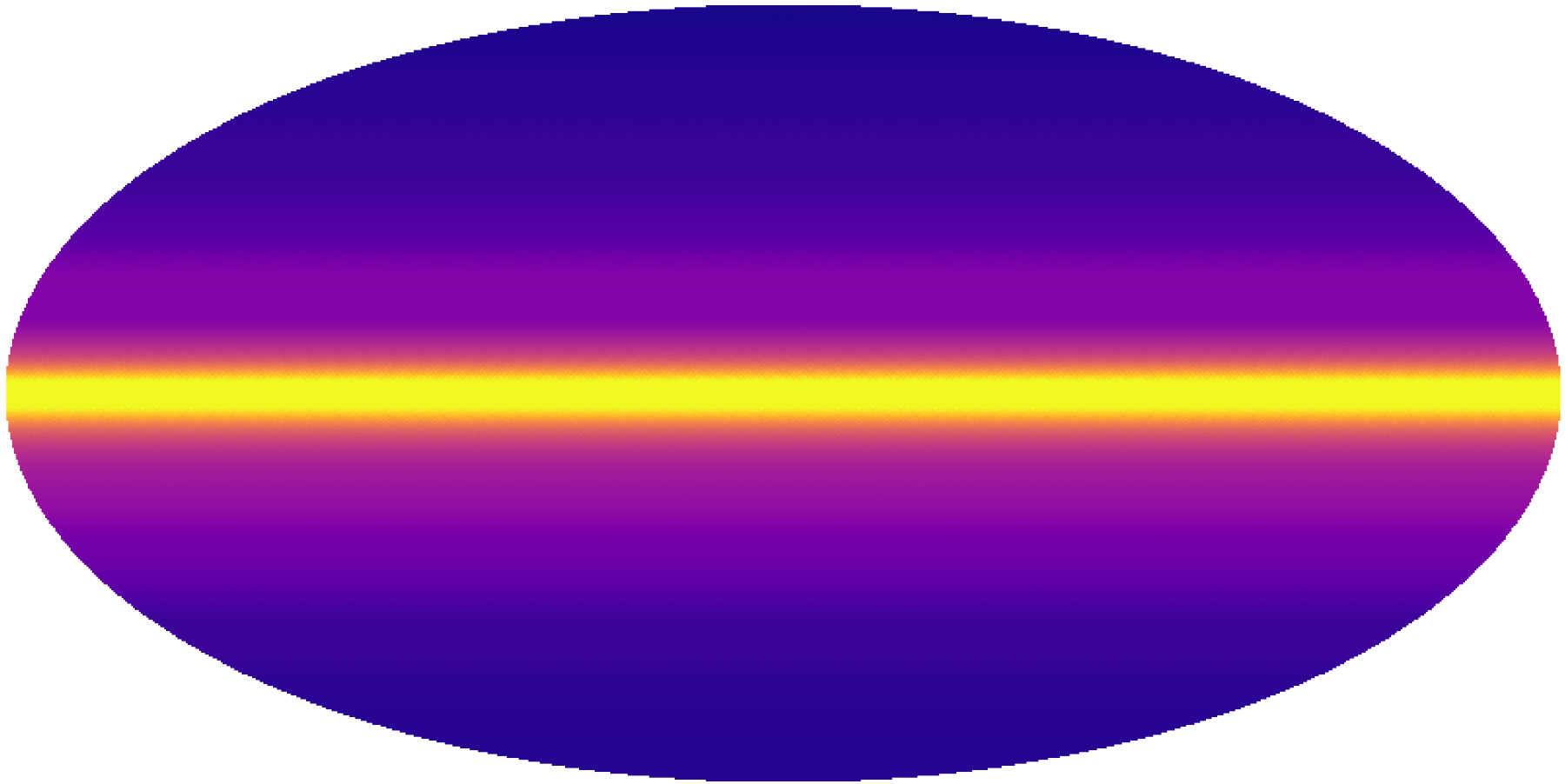


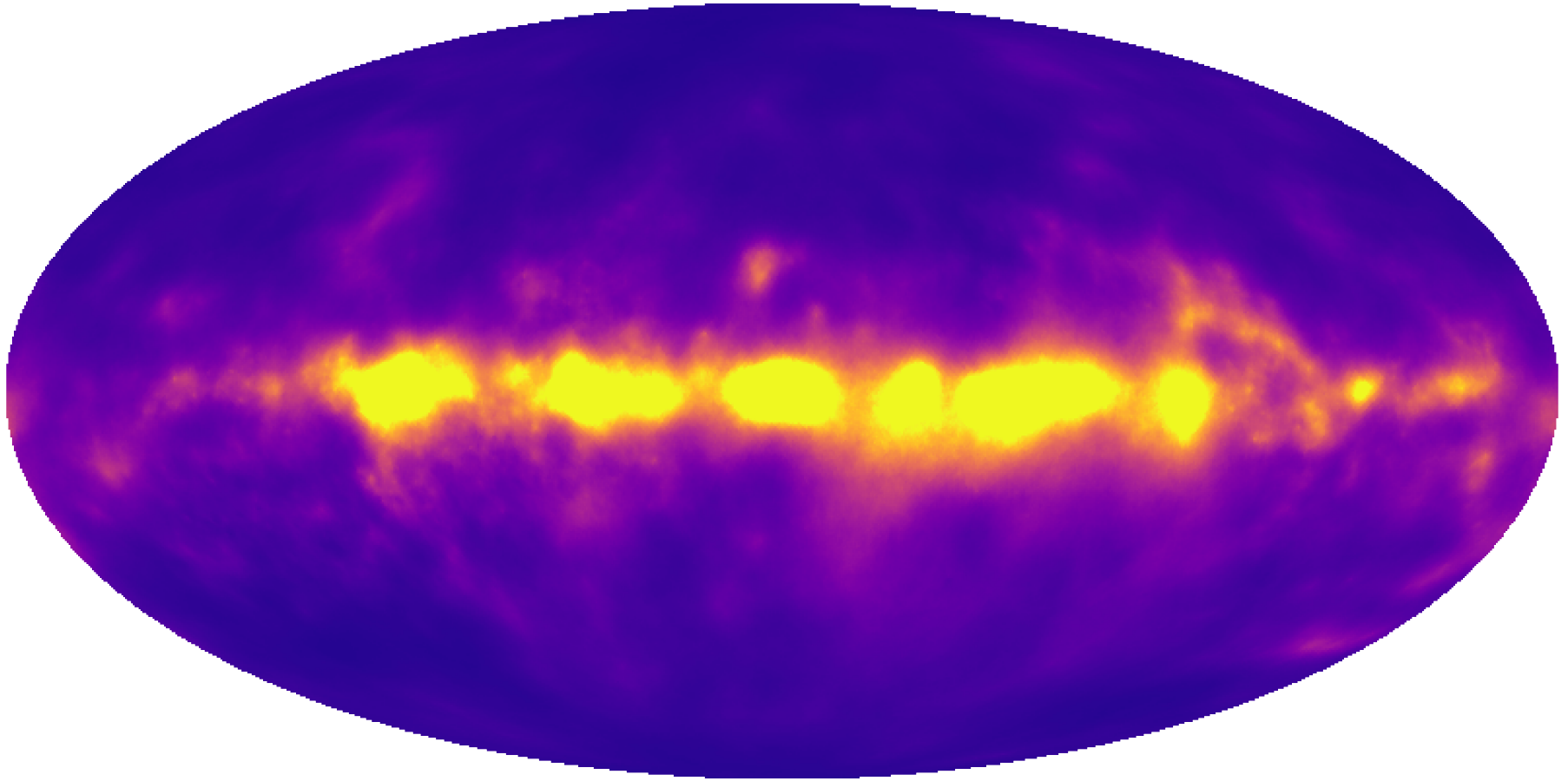
observed power spectra

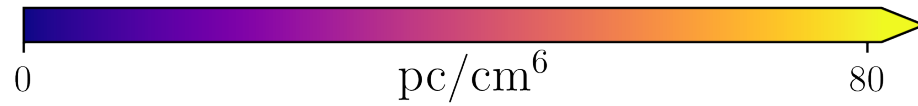
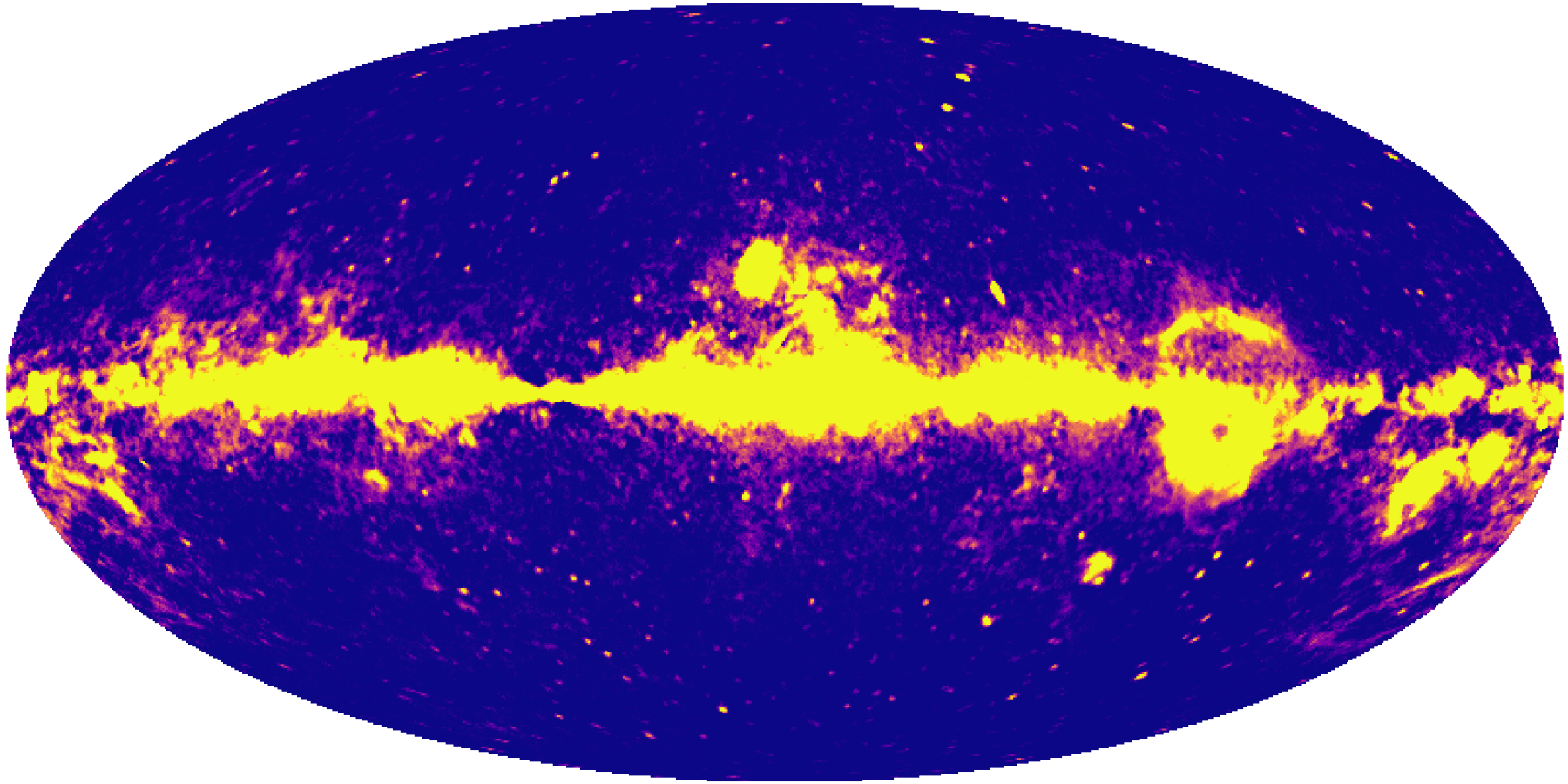


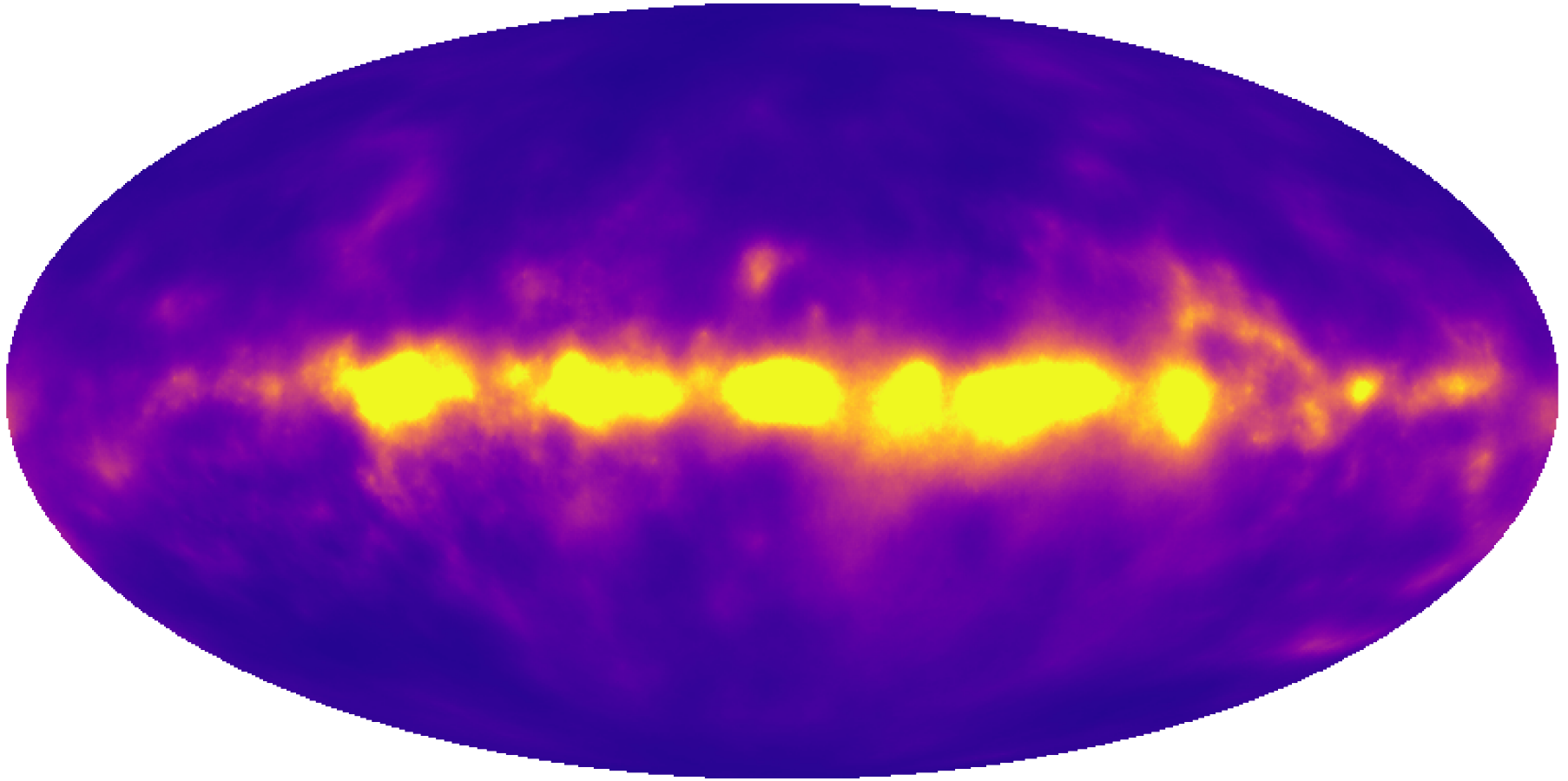


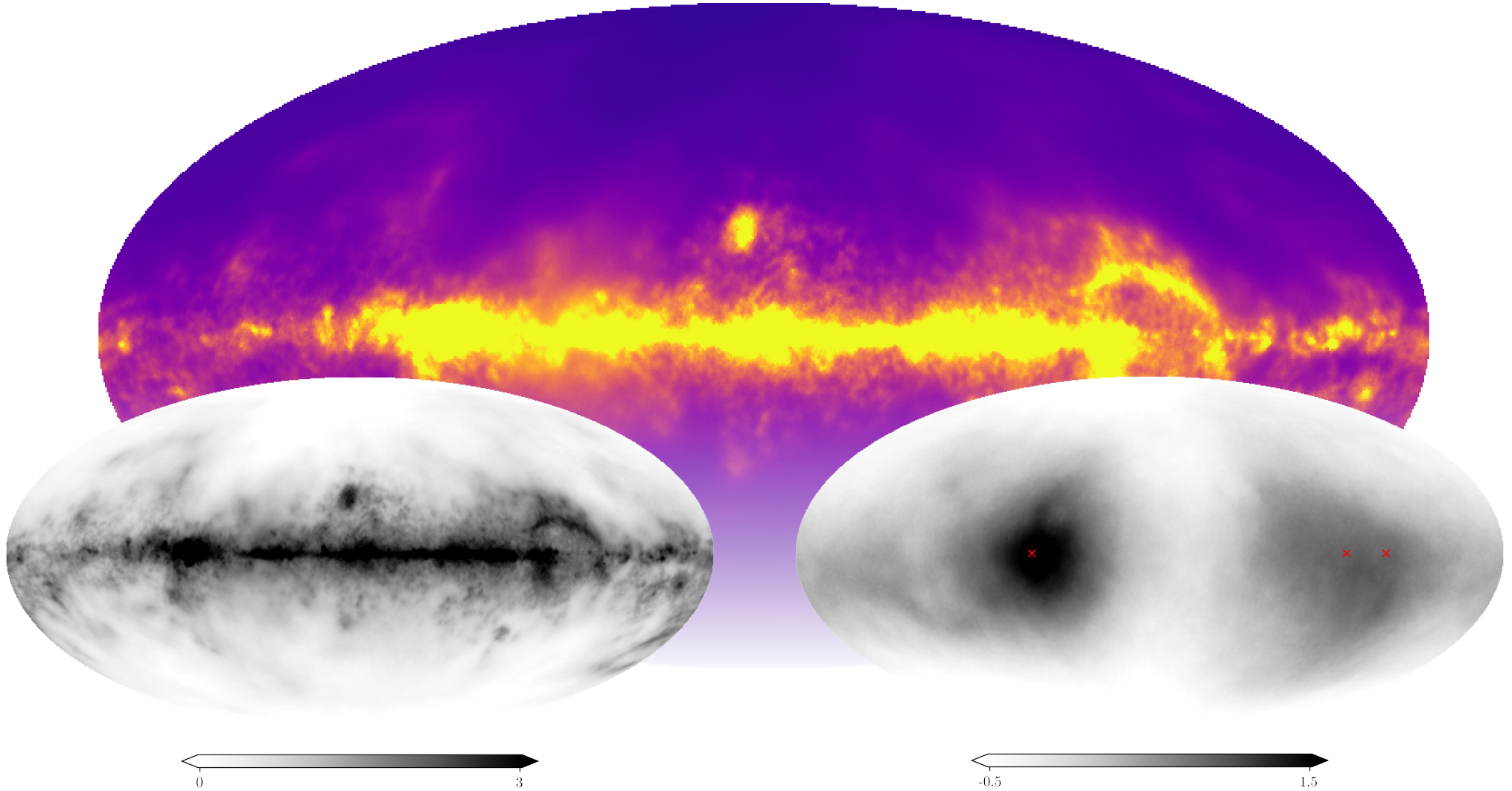


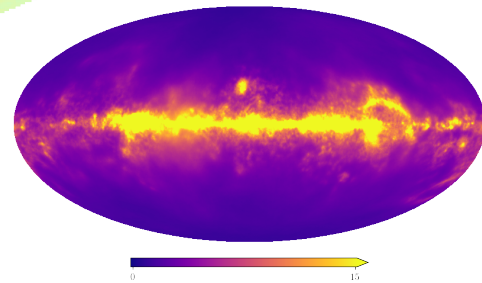
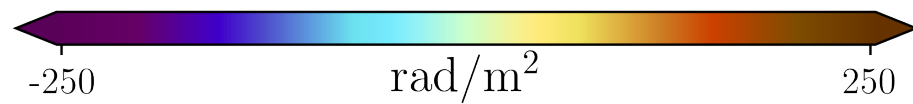
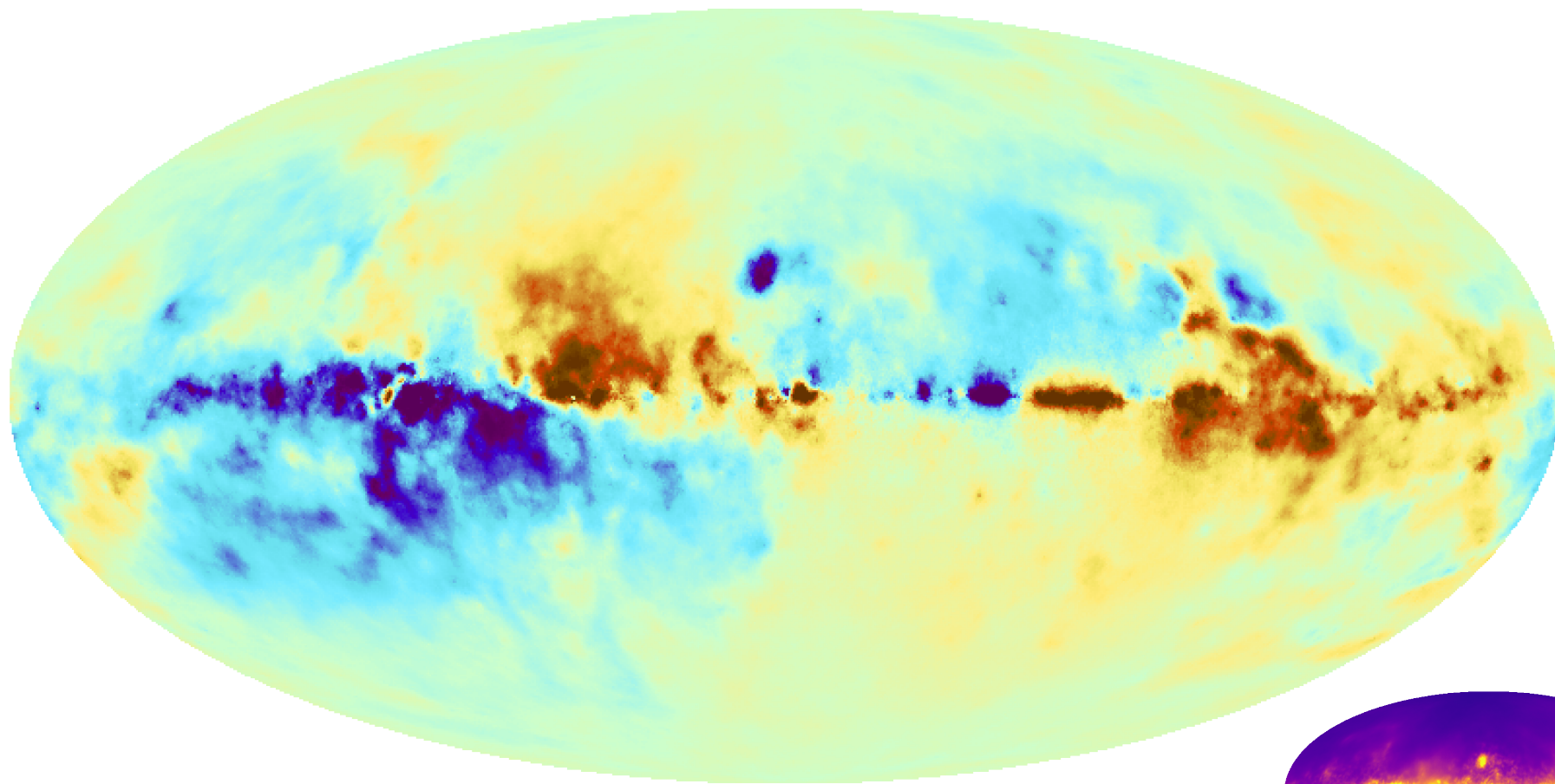


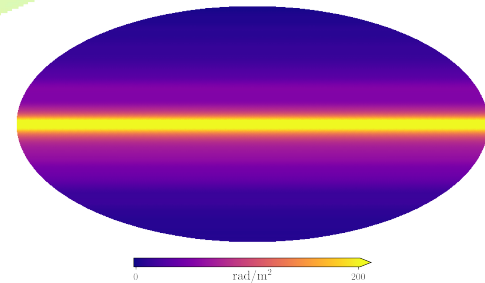
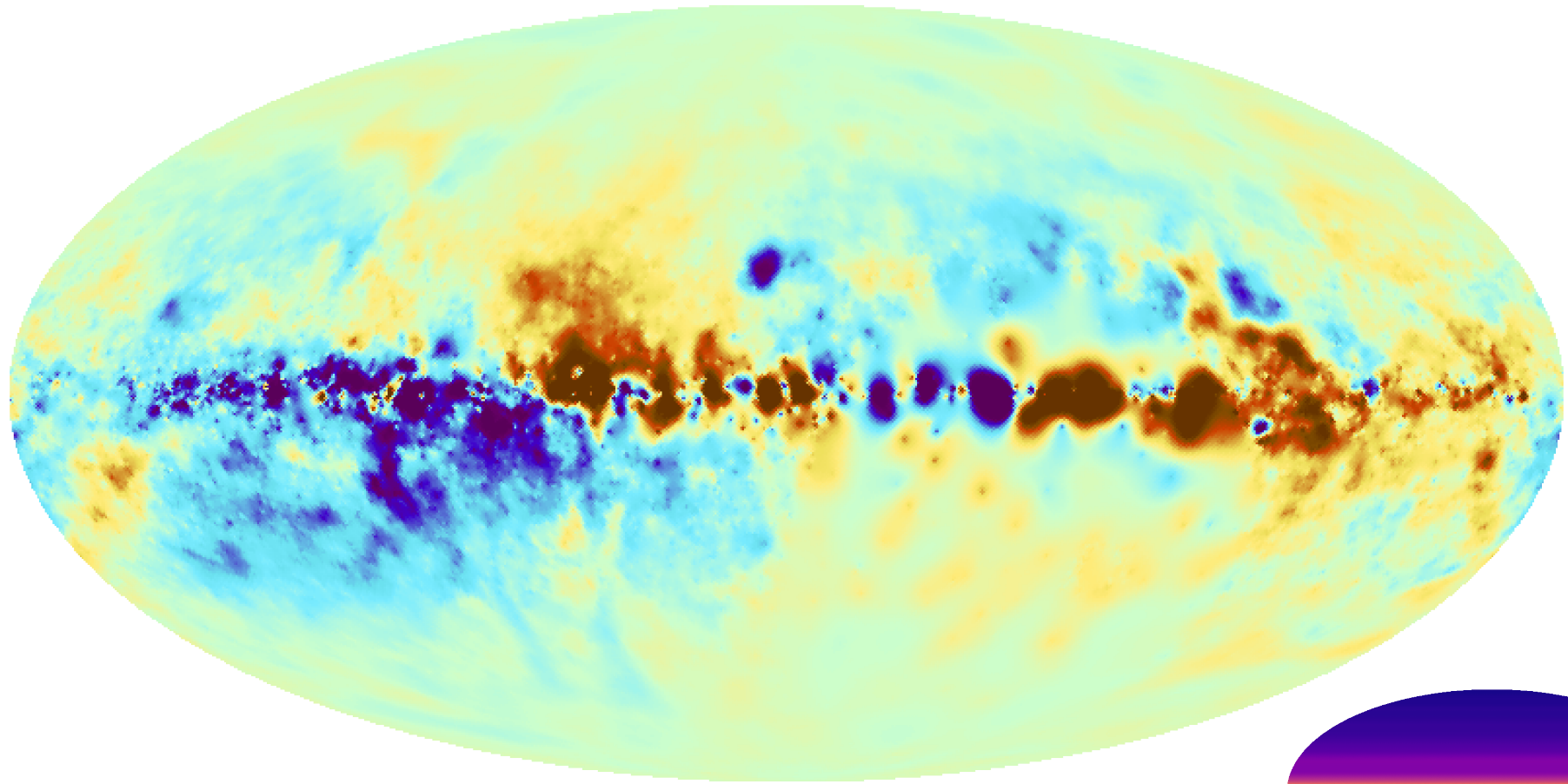




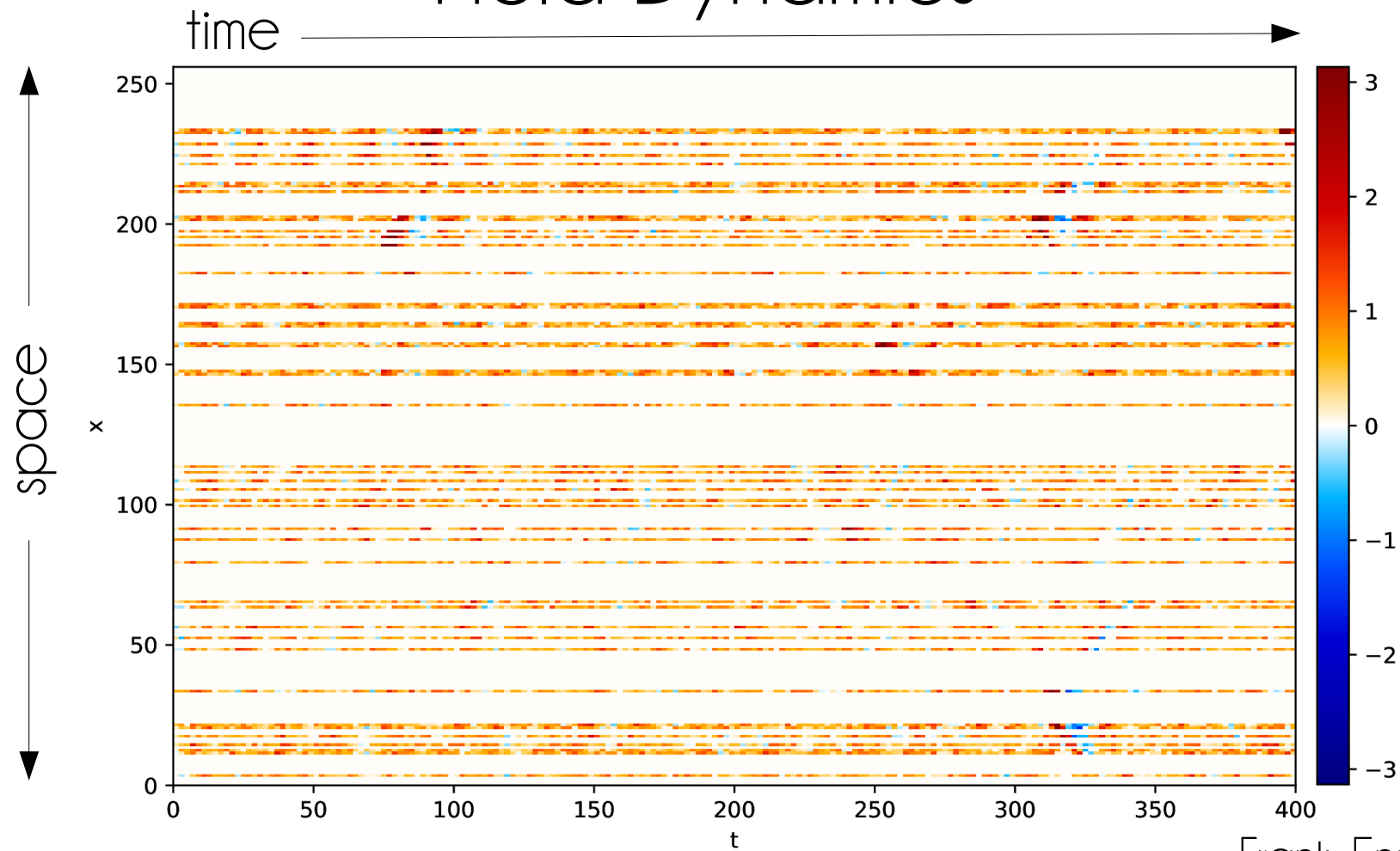






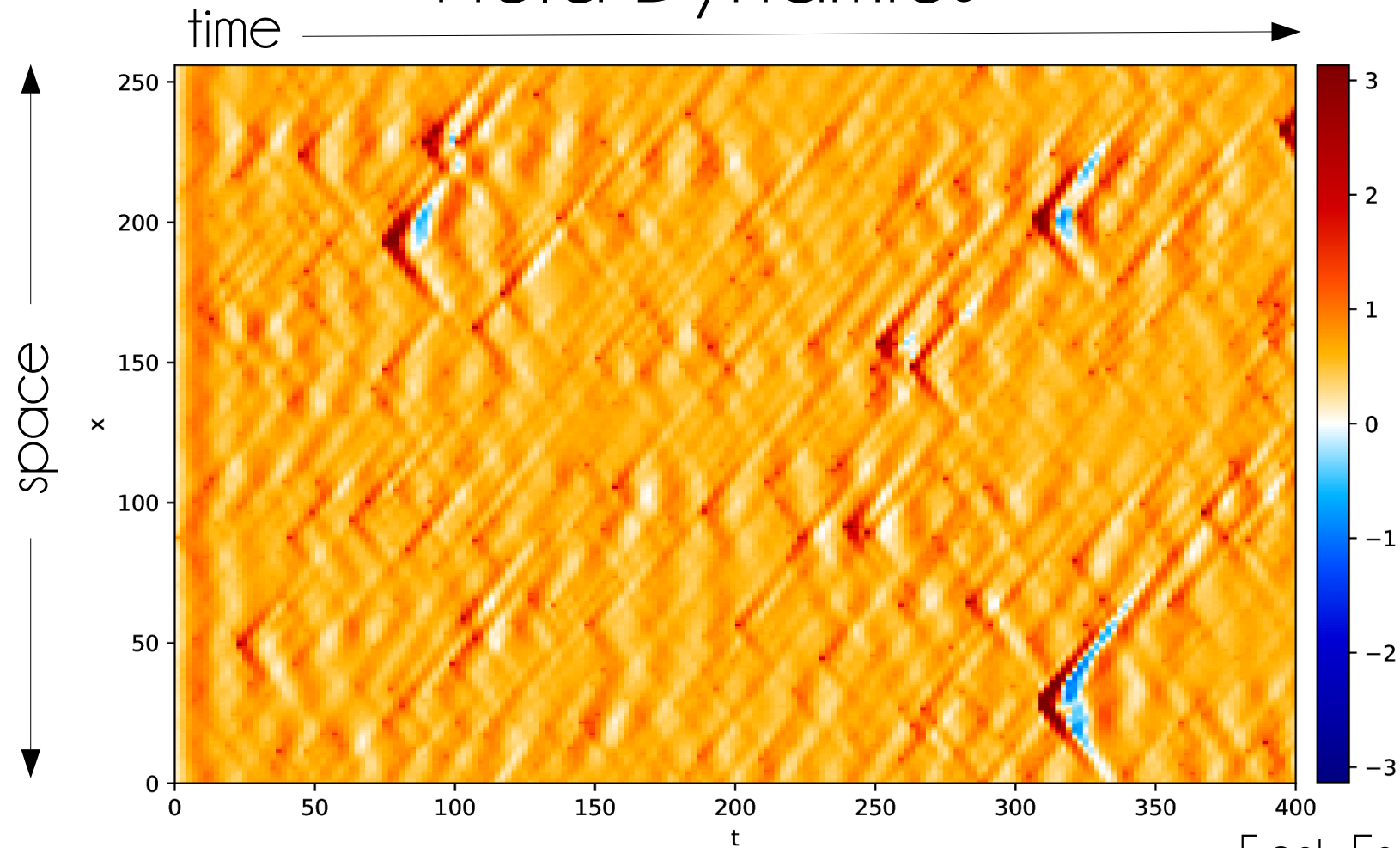


Field Dynamics



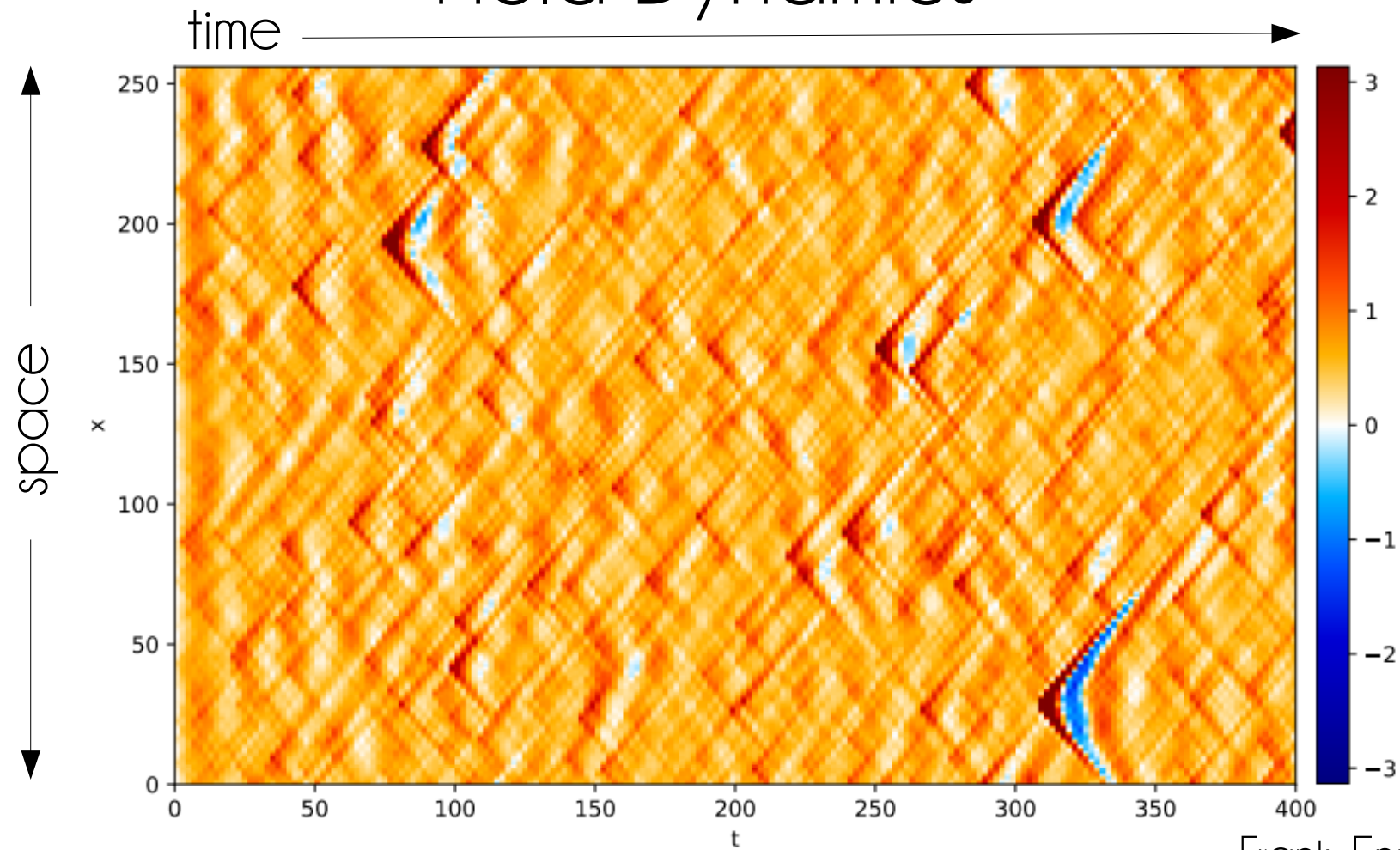
Frank, Enßlin (2019)

Field Dynamics



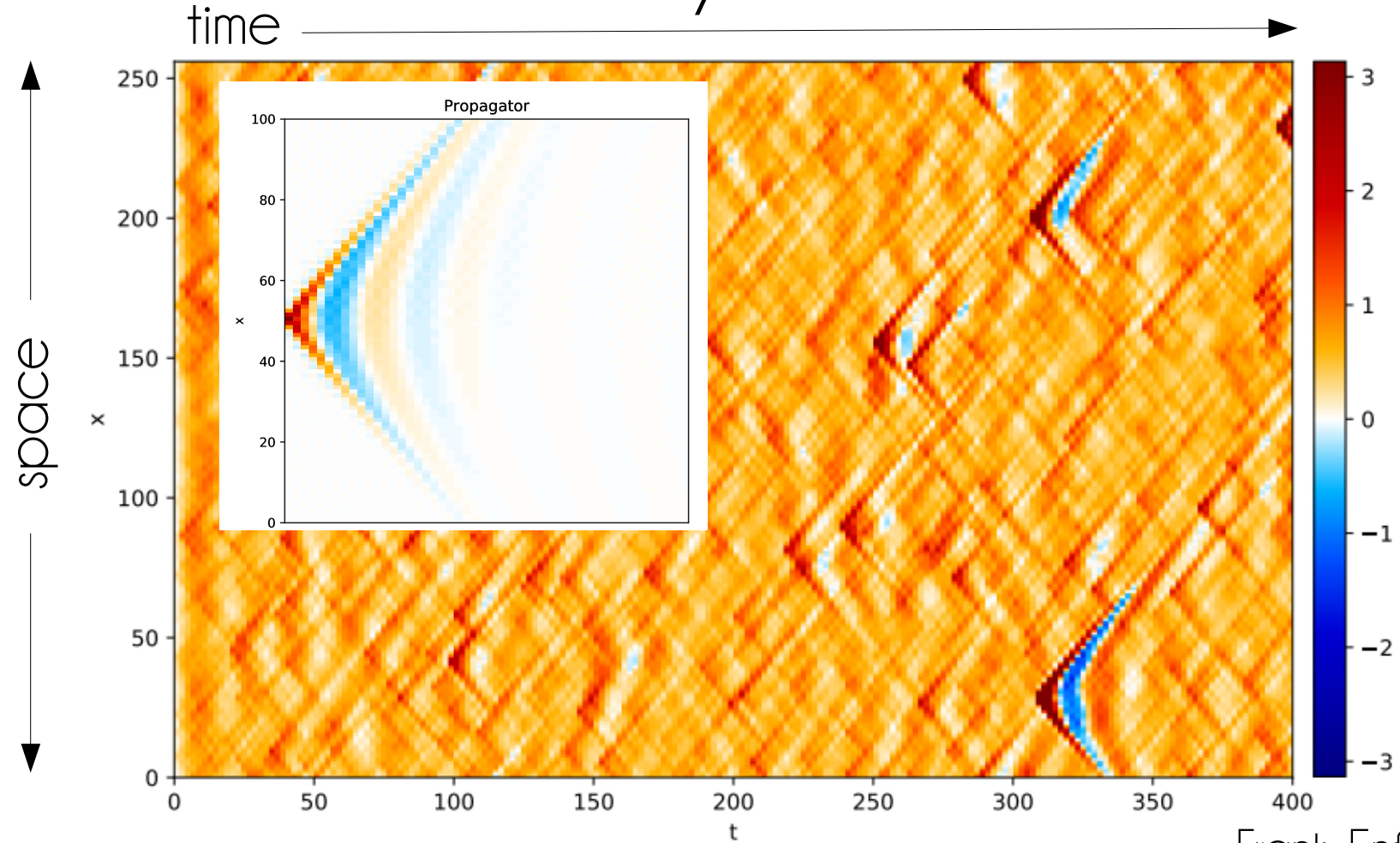
Frank, Enßlin (2019)

Field Dynamics

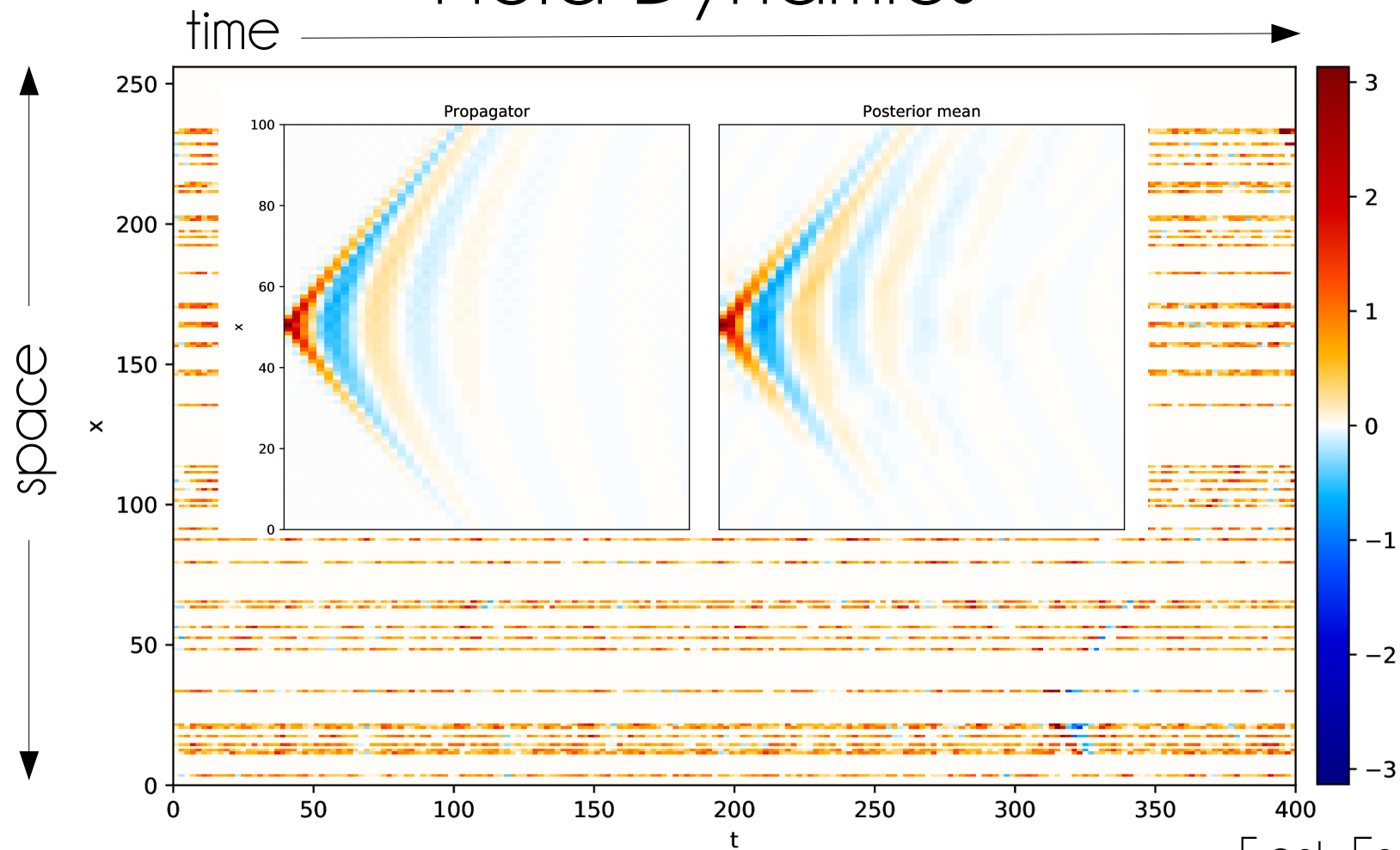


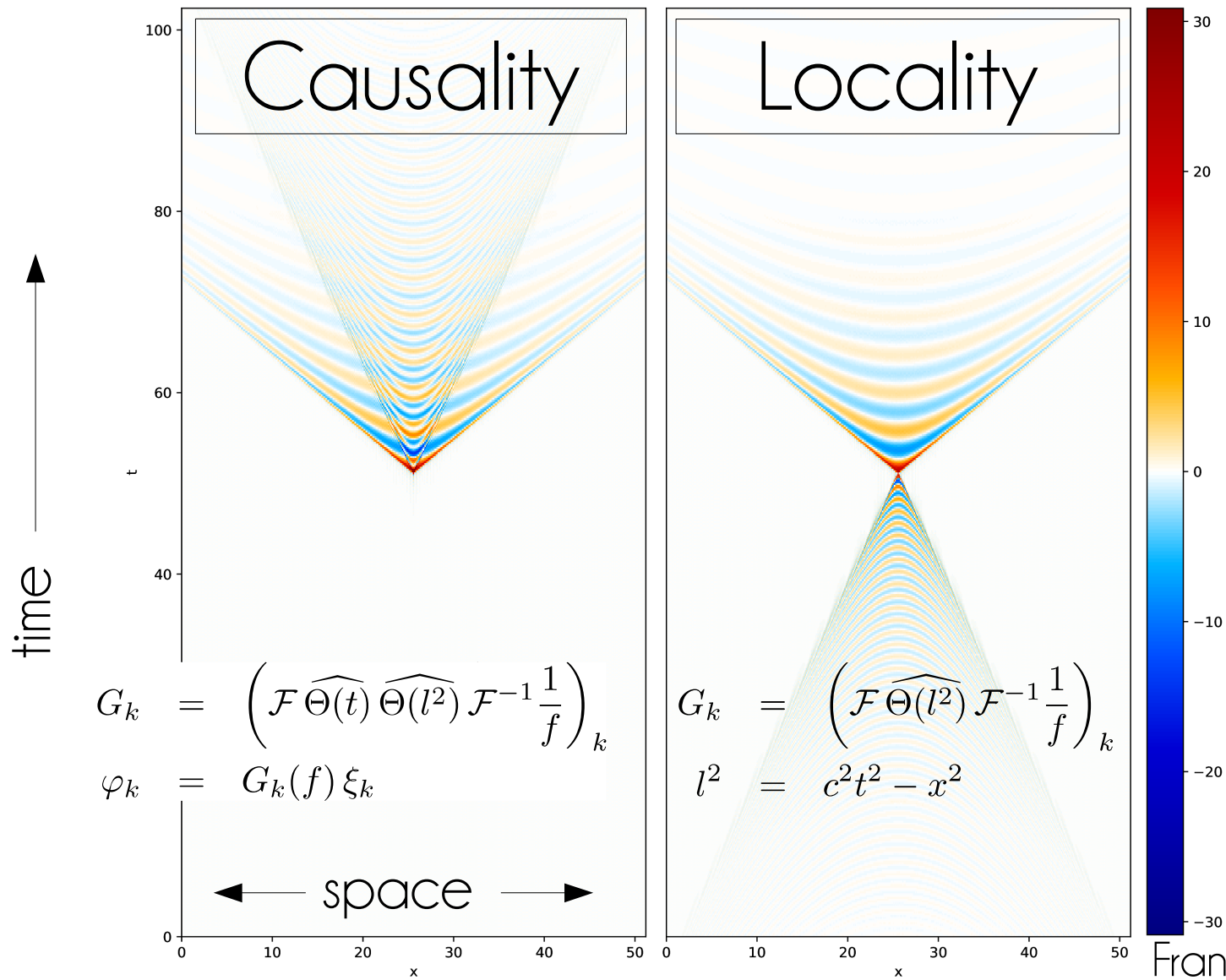
Frank, Enßlin (2019)

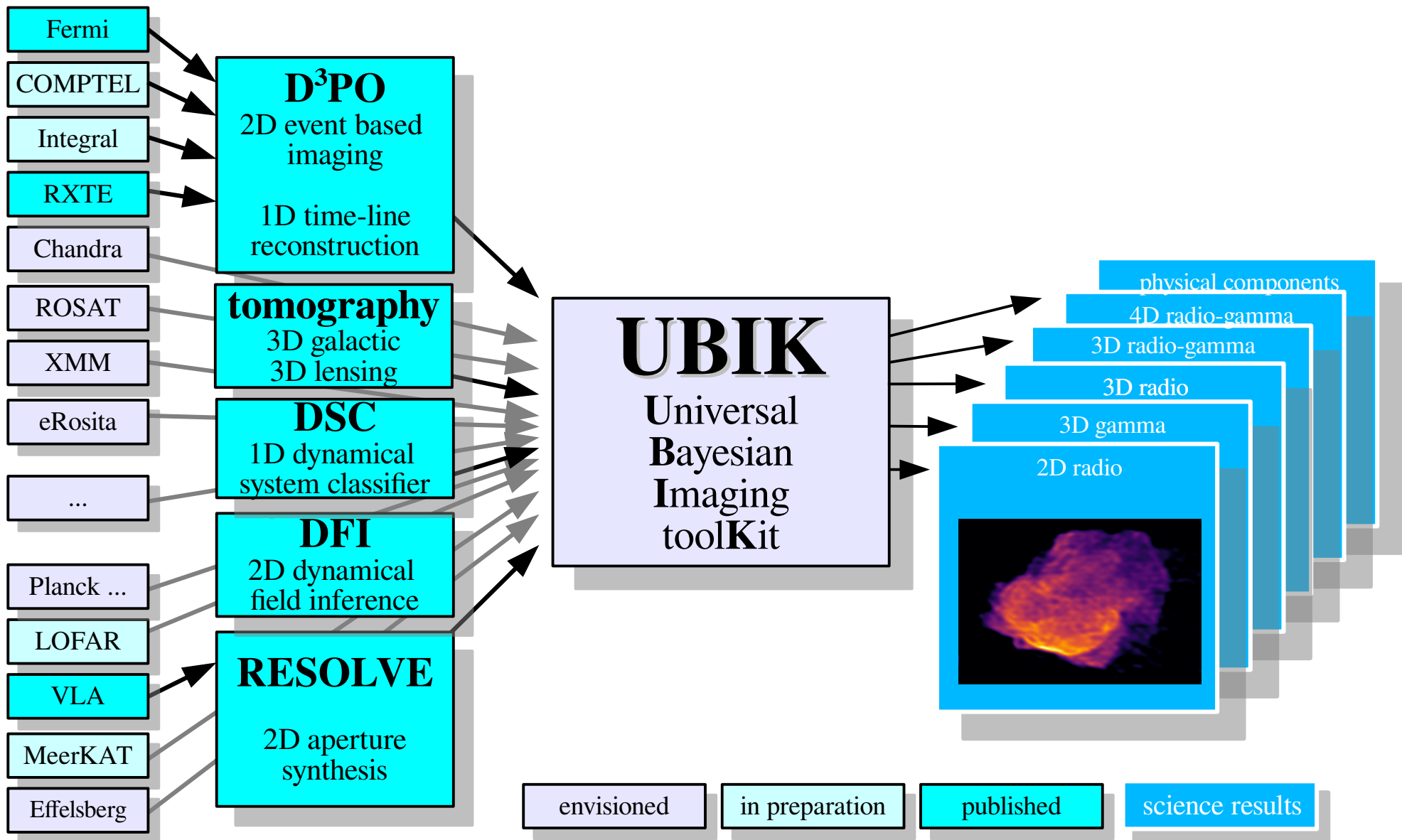
Field Dynamics

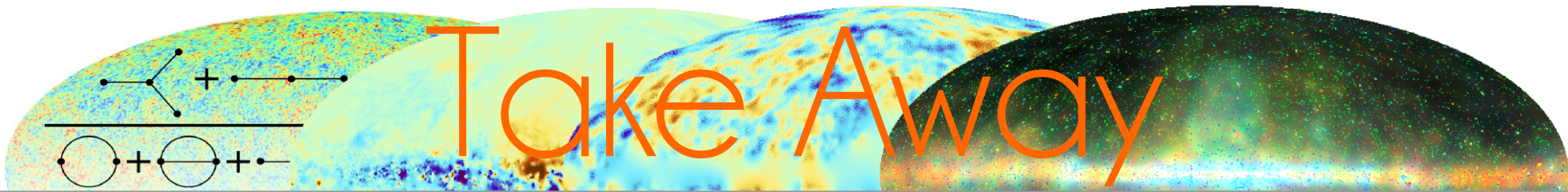


Field Dynamics





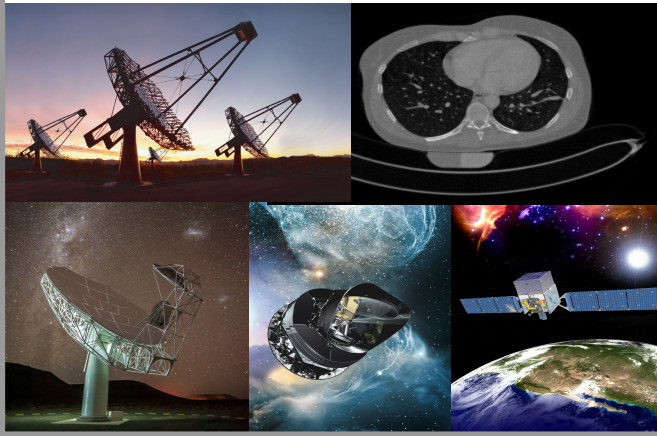




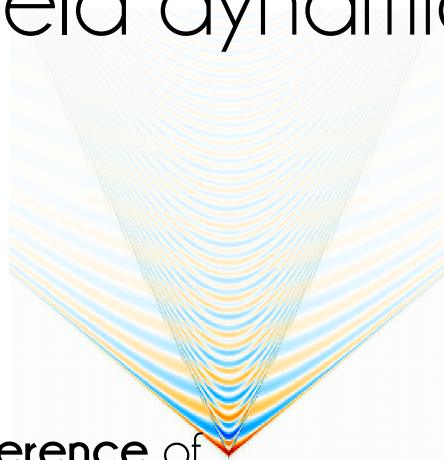
IFT = Information field theory

NIFTy = Numerical Information Field Theory

Unified imaging
UBIK



Field dynamics



Inference of

- dynamical fields
- & their dynamics

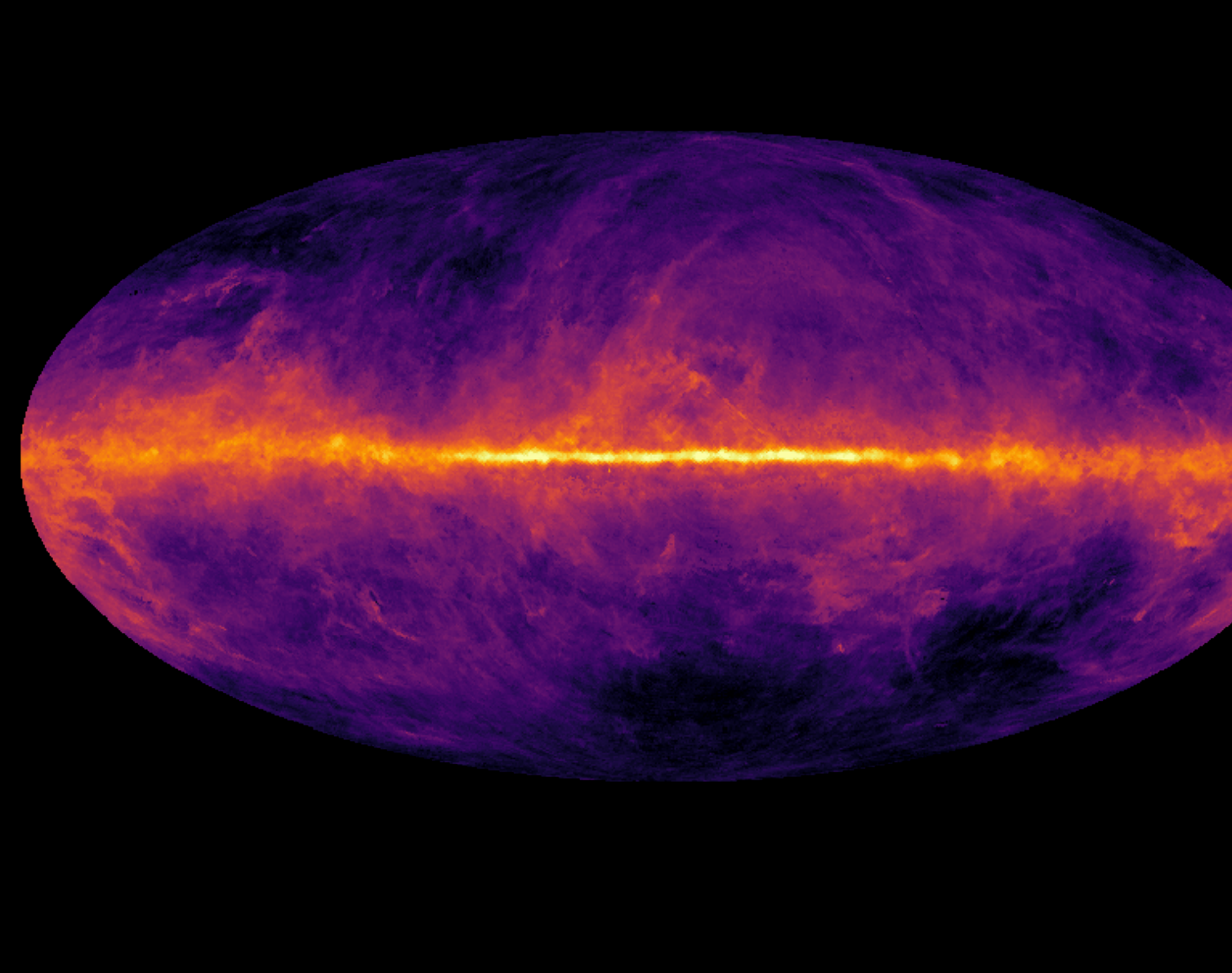
Use it!

IFT:

- Theory papers
- Application papers

NIFTy:

- Python
- freely available
- documented
- tutorials
- demos
- codes



Thank you!