

Maxwell's Equations

- Set of four equations
- Describes the behavior of both the electric and Magnetic fields as well as their interaction with.

Maxwell's four eq's express.

→ How electric charges produce electric field → Gauss's law.

→ The absence of magnetic monopoles.
(Some books call it Gauss's law in magnetism)

→ How currents and changing electric fields produces magnetic fields ⇒
Ampere's law with Maxwell's correction

→ How changing magnetic fields produce electric fields (Faraday's law of induction)

Electrodynamics before Maxwell's Correction.

i) $\vec{\nabla} \cdot \vec{E} = \frac{\rho}{\epsilon_0}$ — Gauss's law

(ii) $\vec{\nabla} \cdot \vec{B} = 0$

iii) $\vec{\nabla} \times \vec{E} = -\frac{\partial \vec{B}}{\partial t}$ Faraday's Law

(iv) $\vec{\nabla} \times \vec{B} = \mu_0 \vec{J}$ Ampere's law.

Both Fields in terms of scalar potential V and vector potential \vec{A}

$$\vec{E} = -\vec{\nabla} V - \frac{\partial \vec{A}}{\partial t}$$

$$\vec{B} = \vec{\nabla} \times \vec{A}$$

Apply divergence to eqn iii,

$$\nabla \cdot (\nabla \times \vec{E}) = \nabla \cdot \left(-\frac{\partial \vec{B}}{\partial t} \right) = -\frac{\partial}{\partial t} (\nabla \cdot \vec{B}) \quad \text{v,}$$

LHS is zero \because divergence of a curl is zero.

RHS is zero $\because \nabla \cdot \vec{B} = 0$

Now apply divergence to eqn iv,

$$\nabla \cdot (\nabla \times \vec{B}) = \mu_0 (\nabla \cdot \vec{J}) \quad \text{(vi)}$$

zero

$$\nabla \cdot \vec{J} = 0$$

for magnetostatic
i.e. for steady current

\Rightarrow Beyond magnetostatic Ampere's law cannot be right
In electrodynamics from equation
of continuity (conservation of charge)

$$\Rightarrow \nabla \cdot \vec{J} = -\frac{\partial \rho}{\partial t} \quad \text{vii,}$$

\Rightarrow Eqn iv, is not valid for non-steady currents as in electrodynamics.

Maxwell's correction to Ampere's law.

From Gauss's law

$$\vec{\nabla} \cdot \epsilon_0 \vec{E} = \rho$$

Take time derivative

$$\frac{\partial}{\partial t} (\vec{\nabla} \cdot \epsilon_0 \vec{E}) = \frac{\partial \rho}{\partial t}$$

$$\Rightarrow \frac{\partial \rho}{\partial t} = \vec{\nabla} \cdot \epsilon_0 \frac{\partial \vec{E}}{\partial t}$$

using this in equation we get.

$$\vec{\nabla} \cdot (\vec{\nabla} \times \vec{B}) = \mu_0 (\vec{\nabla} \cdot \vec{J}) + \mu_0 \epsilon_0 \vec{\nabla} \cdot \left(\frac{\partial \vec{E}}{\partial t} \right)$$

$$= \mu_0 \left(-\frac{\partial \rho}{\partial t} \right) + \mu_0 \epsilon_0 \vec{\nabla} \cdot \left(\frac{\partial \vec{E}}{\partial t} \right)$$

$$= \mu_0 \left(-\frac{\partial \rho}{\partial t} \right) + \mu_0 \left(\frac{\partial \rho}{\partial t} \right)$$

$$0 = 0$$

\Rightarrow Ampere's law and the conservation of charge eqn. suggest that there are actually two sources of magnetic field.

⇒ The current density and displacement current

$$\frac{\partial D}{\partial t} = \frac{\partial (\epsilon_0 E)}{\partial t} \rightarrow \text{Displacement Current}$$

⇒ Ampere's law with Maxwell's correction.

$$\nabla \times \vec{B} = \mu_0 \vec{J} + \mu_0 \epsilon_0 \frac{\partial \vec{E}}{\partial t}$$

⇒ Maxwell's fixed Ampere's law on pure theoretical arguments

⇒ In Maxwell's time there was no experiment reason to doubt that Ampere's law was of wider validity.

→ Maxwell's called extra term as the displacement current.

$$\vec{J}_d \equiv \epsilon_0 \frac{\partial \vec{E}}{\partial t}$$

it has nothing to do with current except that it adds to \vec{J} in Amp. law

Paradox of charging Capacitor.

→ If the capacitor plates are very close together — the Electric field between them is

$$E = \frac{\sigma}{\epsilon_0} = \frac{1}{\epsilon_0} \frac{Q}{A}$$

Q — charge on the plate

A — is plate's area.

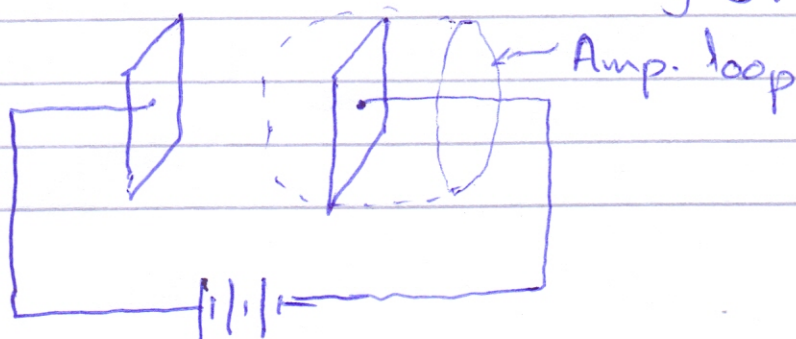
$$\Rightarrow \frac{\partial E}{\partial t} = \frac{1}{\epsilon_0 A} \frac{dQ}{dt} = \frac{1}{\epsilon_0 A} I$$

From $\nabla \times \vec{B}$.

$$\nabla \times \vec{B} = \mu_0 \vec{J}_{enc} + \mu_0 \epsilon_0 \frac{\partial \vec{E}}{\partial t}$$

in integral form.

$$\oint \vec{B} \cdot d\vec{l} = \mu_0 I_{enc} + \mu_0 \epsilon_0 \int \frac{\partial \vec{E}}{\partial t} \cdot d\vec{a}$$



For flat surface $E=0$ and $I_{enc}=I$

For balloon-shaped surface $\rightarrow I_{enc}=0$

but
$$\int \frac{\partial E}{\partial t} \cdot da = \frac{I}{\epsilon_0}$$

we get same answer in both cases
or for either surface.

\rightarrow In first case it comes from the genuine current and ~~it~~ in the second from the displacement current.

②

General Form of Maxwell's Equations

Differential Form

Integral Form

i, $\vec{\nabla} \cdot \vec{E} = \frac{\rho}{\epsilon_0}$ Divergence theorem

$$\oint \vec{E} \cdot d\vec{a} = \frac{1}{\epsilon_0} \int_V \rho d\tau$$

ii, $\vec{\nabla} \cdot \vec{B} = 0$ "

$$\oint \vec{B} \cdot d\vec{a} = 0$$

iii, $\vec{\nabla} \times \vec{E} = -\frac{\partial \vec{B}}{\partial t}$ Stokes's theorem

$$\oint \vec{E} \cdot d\vec{l} = -\frac{d}{dt} \int_S \vec{B} \cdot d\vec{a}$$

iv, $\vec{\nabla} \times \vec{B} = \mu_0 \vec{J} + \mu_0 \epsilon_0 \frac{\partial \vec{E}}{\partial t}$

$$\oint \vec{B} \cdot d\vec{l} = \mu_0 I_{enc} + \mu_0 \epsilon_0 \frac{d}{dt} \int \vec{E} \cdot d\vec{a}$$

Together with the Force law.

$$\vec{F} = q\vec{E} + q(\vec{v} \times \vec{B}) \quad \text{Lorentz force}$$

⇒ It tells how fields affect charges.
and Equation of Continuity.

$$\vec{\nabla} \cdot \vec{J} = -\frac{\partial \rho}{\partial t}$$

Summarize the entire theoretical content of classical electrodynamics

Maxwell's Equations:

- Eqs. i, ii, 2.iii, in this form reinforce the notion that
- ⇒ Electric fields can be produced either by charges (ρ), or by changing M.F ($\frac{\partial B}{\partial t}$)
- And
- ⇒ Magnetic fields can be produced either by currents (J) or by changing E.F ($\frac{\partial E}{\partial t}$)
- ⇒ This is misleading because $\left(\frac{\partial E}{\partial t}\right)$ & $\left(\frac{\partial B}{\partial t}\right)$ are themselves due to charges and currents

Logical approach can be

$$\vec{\nabla} \cdot \vec{E} = \frac{\rho}{\epsilon_0}$$

$$\vec{\nabla} \cdot \vec{B} = 0$$

$$\vec{\nabla} \times \vec{E} + \frac{\partial \vec{B}}{\partial t} = 0$$

$$\vec{\nabla} \times \vec{B} - \mu_0 \epsilon_0 \frac{\partial \vec{E}}{\partial t} = \mu_0 \vec{J}$$

- ⇒ All EM. fields are ultimately attributable to charges and currents

Maxwell's Equations in Vacuum.

No free charge & Current i.e. ($\rho = J = 0$)

i. $\nabla \cdot \vec{E} = 0$

ii. $\nabla \cdot \vec{B} = 0$

iii. $\nabla \times \vec{E} = -\frac{\partial \vec{B}}{\partial t}$

iv. $\nabla \times \vec{B} = \mu_0 \epsilon_0 \frac{\partial \vec{E}}{\partial t}$

Vacuum is a linear, homogeneous, ~~med~~ isotropic and dispersionless medium.

Linear

Homogeneous medium: has the same properties at every point \Rightarrow uniform without irregularities.

Isotropic: Having identical values of a property in all directions.

Dispersionless medium.

In which all frequencies travel with same velocity. Vacuum is dispersionless for EM waves.

11

From Gauss's law in dielectric

$$\vec{\nabla} \cdot \vec{E} = \frac{\rho_t}{\epsilon_0} = \frac{1}{\epsilon_0} (\rho_f + \rho_b)$$

where $\rho_f \rightarrow$ Free charges
 $\rho_b \rightarrow$ bound volume charges.

$$\vec{\nabla} \cdot \vec{E} = \frac{1}{\epsilon_0} (\rho_f - \vec{\nabla} \cdot \vec{P})$$

where $\rho_b = -\vec{\nabla} \cdot \vec{P}$
 and $\sigma_b = \vec{P} \cdot \hat{n} \rightarrow$ Surface bound charges.

$$\vec{\nabla} \cdot \epsilon_0 \vec{E} + \vec{\nabla} \cdot \vec{P} = \frac{\rho_f}{\epsilon_0}$$

$$\vec{\nabla} \cdot (\epsilon_0 \vec{E} + \vec{P}) = \frac{\rho_f}{\epsilon_0}$$

Define $\vec{D} \equiv \epsilon_0 \vec{E} + \vec{P}$

Electric displacement vector.

$$\Rightarrow \vec{\nabla} \cdot \vec{D} = \rho_f$$

$$\oint \vec{D} \cdot d\vec{a} = Q_{fenc}$$

Using $\vec{P} = \epsilon_0 \chi_e \vec{E}$

$$\Rightarrow \vec{D} = \epsilon_0 \vec{E} + \epsilon_0 \chi_e \vec{E} \\ = \epsilon_0 (1 + \chi_e) \vec{E}$$

Ampere's law in Magnetized Materials.

$$\nabla \times \vec{B} = \mu_0 \vec{J}$$

The effect of magnetization is to establish bound currents

and $\vec{J}_b = \nabla \times \vec{M}$ within the material
 $\vec{K}_b = \vec{M} \times \hat{n}$ on the surface.

$$\Rightarrow \vec{J} = \vec{J}_f + \vec{J}_b$$

free current is due to wire connected to a battery

The bound current is there because of magnetization.

$$\frac{1}{\mu_0} (\nabla \times \vec{B}) = \vec{J} = \vec{J}_f + \vec{J}_b = \vec{J}_f + (\nabla \times \vec{M})$$

$$\nabla \times \left(\frac{\vec{B}}{\mu_0} - \vec{M} \right) = \vec{J}_f \quad ; \quad \vec{H} \equiv \frac{1}{\mu_0} \vec{B} - \vec{M}$$

$$\nabla \times \vec{H} = \vec{J}_f \quad ; \quad \oint \vec{H} \cdot d\vec{l} = I_{fenc}$$

As $\vec{M} = \chi_m \vec{H}$

$$\Rightarrow \vec{B} = \mu_0 \vec{H} + \mu_0 \chi_m \vec{H} = \mu_0 (1 + \chi_m) \vec{H} = \mu \vec{H}$$

Maxwell's Equations inside Matter.

⇒ Eqs. are modified for polarized and magnetized materials.

For linear materials

$$\vec{P} = \epsilon_0 \chi_e \vec{E}$$

$$\vec{M} = \chi_m \vec{H}$$

The fields \vec{E} & \vec{B} are related with \vec{D} & \vec{H} by.

$$\vec{D} = \epsilon_0 \vec{E} + \vec{P} \Rightarrow (1 + \chi_e) \epsilon_0 \vec{E} = \epsilon \vec{E}$$

where $\frac{\epsilon}{\epsilon_0} = \epsilon_r = (1 + \chi_e) \rightarrow$ Dielectric Constant.

and

$$\vec{B} = \mu_0 (\vec{H} + \vec{M}) = (1 + \chi_m) \mu_0 \vec{H} = \mu \vec{H}$$

$\chi_e \rightarrow$ electric susceptibility of material
 $\chi_m \rightarrow$ magnetic " " " "

In electrodynamics any change in the electric polarization involves a flow of bound charges resulting in polarization current, J_p .

$$\vec{J}_p = \frac{\partial \vec{P}}{\partial t}$$

Polarization current density is due to linear motion of charge when the Electric polarization changes.

⇒ Total charge density is

$$\rho_t = \rho_f + \rho_b$$

Total current density is

$$J_t = J_f + J_b + J_p$$

and

$$J_b = \epsilon_0 \frac{\partial E}{\partial t}$$

Maxwell's Equations Inside MatH.

$$i) \quad \vec{\nabla} \cdot \vec{E} = \frac{\rho}{\epsilon_0} \rightarrow \vec{\nabla} \cdot \vec{D} = \rho_f \quad \text{where } \vec{D} = \epsilon_0 \vec{E} + \vec{P} \\ \text{or } \vec{D} = \epsilon \vec{E}$$

$$ii) \quad \vec{\nabla} \cdot \vec{B} = 0$$

$$iii) \quad \vec{\nabla} \times \vec{E} = -\frac{\partial \vec{B}}{\partial t}$$

$$(iv) \quad \vec{\nabla} \times \vec{B} = \mu_0 \vec{J}_f + \mu_0 \vec{J}_b + \mu_0 \vec{J}_p + \mu_0 \epsilon_0 \frac{\partial \vec{E}}{\partial t}$$

$$\vec{\nabla} \times \frac{\vec{B}}{\mu_0} = \vec{J}_f + \vec{\nabla} \times \vec{M} + \frac{\partial \vec{P}}{\partial t} + \epsilon_0 \frac{\partial \vec{E}}{\partial t}$$

$$\vec{\nabla} \times \frac{\vec{B}}{\mu_0} = \vec{J}_f + \vec{\nabla} \times \vec{M} + \frac{\partial}{\partial t} (\epsilon_0 \vec{E} + \vec{P})$$

$$\vec{\nabla} \times \left(\frac{\vec{B}}{\mu_0} - \vec{M} \right) = \vec{J}_f + \frac{\partial \vec{D}}{\partial t}$$

$$\vec{\nabla} \times \vec{H} = \vec{J}_f + \frac{\partial \vec{D}}{\partial t}$$

$$\begin{aligned} \vec{H} &= \frac{\vec{B}}{\mu_0} - \vec{M} \\ \text{or } \vec{B} &= \mu_0 \vec{H} \end{aligned}$$

In non-dispersive, isotropic media ϵ & μ are time independent scalars and space independent.

$$\begin{aligned} \vec{\nabla} \cdot \epsilon \vec{E} &= \rho \\ \vec{\nabla} \cdot \mu \vec{H} &= 0 \end{aligned}$$

$$\vec{\nabla} \times \vec{E} = -\mu \frac{\partial \vec{H}}{\partial t}$$

$$\vec{\nabla} \times \vec{H} = \vec{J} + \epsilon \frac{\partial \vec{E}}{\partial t}$$

(6)

Electromagnetic Waves in Vacuum.

⇒ In region of free space (i.e. the vacuum)

→ where no electric charges, no electric currents and no matter of any are present

→ Maxwell's equations are.

$$1, \quad \vec{\nabla} \cdot \vec{E}(\vec{r}, t) = 0$$

$$2, \quad \vec{\nabla} \cdot \vec{B}(\vec{r}, t) = 0$$

$$3, \quad \vec{\nabla} \times \vec{E}(\vec{r}, t) = -\frac{\partial \vec{B}(\vec{r}, t)}{\partial t}$$

$$4, \quad \vec{\nabla} \times \vec{B}(\vec{r}, t) = \mu_0 \epsilon_0 \frac{\partial \vec{E}(\vec{r}, t)}{\partial t}$$

$$= \frac{1}{c^2} \frac{\partial \vec{E}}{\partial t}$$

$$\text{where } c^2 = \frac{1}{\mu_0 \epsilon_0}$$

These eqns. are set of coupled first-order partial equations

→ Can be decoupled by applying curl operator to eqns (3) & (4)

⑦

$$\nabla \times (\nabla \times \mathbf{E}) = \nabla \times \left(-\frac{\partial \mathbf{B}}{\partial t} \right) \quad \nabla \times (\nabla \times \mathbf{B}) = \nabla \times \left(\frac{1}{c^2} \frac{\partial \mathbf{E}}{\partial t} \right)$$

using vector identity

$$\nabla \times (\nabla \times \mathbf{A}) = \nabla (\nabla \cdot \mathbf{A}) - \nabla^2 \mathbf{A}$$

$$\Rightarrow \nabla (\nabla \cdot \mathbf{E}) - \nabla^2 \mathbf{E} = -\frac{\partial}{\partial t} (\nabla \times \mathbf{B})$$

$$-\nabla^2 \mathbf{E} = -\frac{\partial}{\partial t} \left(\frac{1}{c^2} \frac{\partial \mathbf{E}}{\partial t} \right)$$

$$\Rightarrow \nabla^2 \mathbf{E} = \frac{1}{c^2} \frac{\partial^2 \mathbf{E}}{\partial t^2} \quad \left. \begin{array}{l} \text{Similarly } \nabla^2 \mathbf{B} = \frac{1}{c^2} \frac{\partial^2 \mathbf{B}}{\partial t^2} \end{array} \right\} \text{3D-de-coupled wave equations}$$

→ Have exactly the same structure

→ Both are linear, homogenous, 2nd order differential equations.

Both eqn's have explicit dependence on space and time

$$\nabla^2 \bar{\mathbf{E}}(\bar{\mathbf{r}}, t) - \frac{1}{c^2} \frac{\partial^2 \bar{\mathbf{E}}(\bar{\mathbf{r}}, t)}{\partial t^2} = 0$$

$$\nabla^2 \bar{\mathbf{B}}(\bar{\mathbf{r}}, t) - \frac{1}{c^2} \frac{\partial^2 \bar{\mathbf{B}}(\bar{\mathbf{r}}, t)}{\partial t^2} = 0$$

⇒ Maxwell's equations implies that empty space - the vacuum - support the propagation of electromagnetic waves - at the speed of light

$$c = \frac{1}{\sqrt{\mu_0 \epsilon_0}} = 3 \times 10^8 \text{ m/sec}$$

Monochromatic EM Plane waves

- A plane wave is a constant freq. $\nu(\lambda)$ wave whose
 - wavefronts are infinite parallel planes.
 - Have constant amplitude normal (\perp) to the phase velocity vector.
- Propagates with speed of light in vacuum.

$$c = \nu \lambda = \frac{\omega}{k}$$

Mathematical form

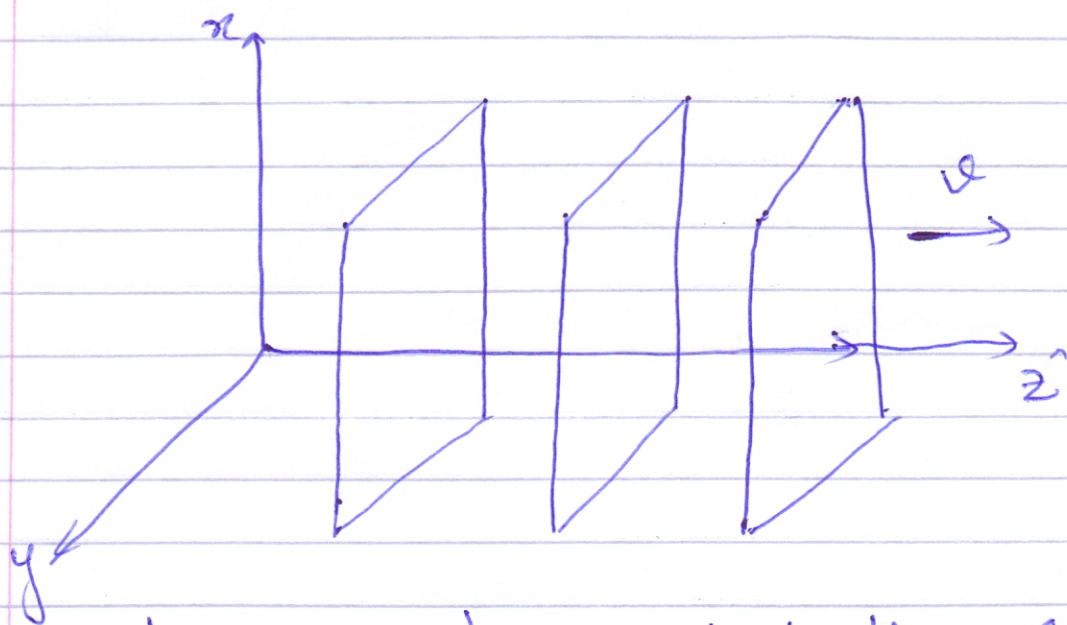
is

$$\vec{F}(\vec{r}, t) = \vec{F}_0 e^{i(\vec{k} \cdot \vec{r} - \omega t)}$$

Uniform plane wave

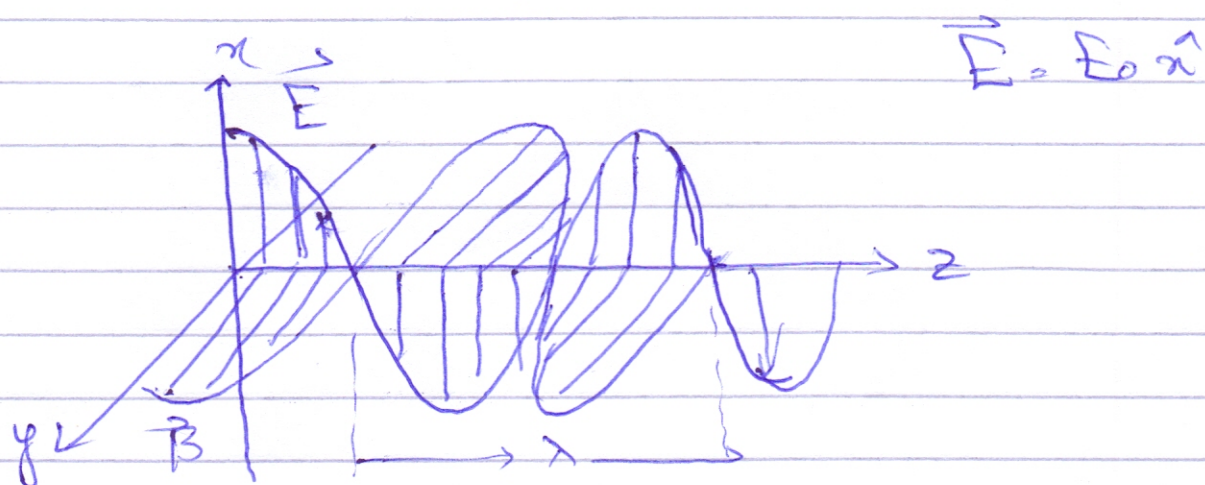
Generally have uniform or constant properties in plane \perp to their direction of propagation.

- \Rightarrow The magnitude of the electric and magnetic fields are the same at all points in the direction of propagation.
- \Rightarrow The Electric & Magnetic fields are orthogonal to the direction of propagation.
- \Rightarrow EM wave that propagates in z -direction



Lie in plane \perp to the \hat{z} -axis.
 \vec{E} & \vec{B} are function of (z, t)

- \Rightarrow The direction of propagation is taken to be along z -axis.
- \Rightarrow The direction of propagation is normal to the plane formed by the electric & magnetic field vectors.
- \Rightarrow The phase of these fields is independent of x & y .
- \Rightarrow no phase variation exist over the planar surfaces orthogonal to the direction of the propagation.

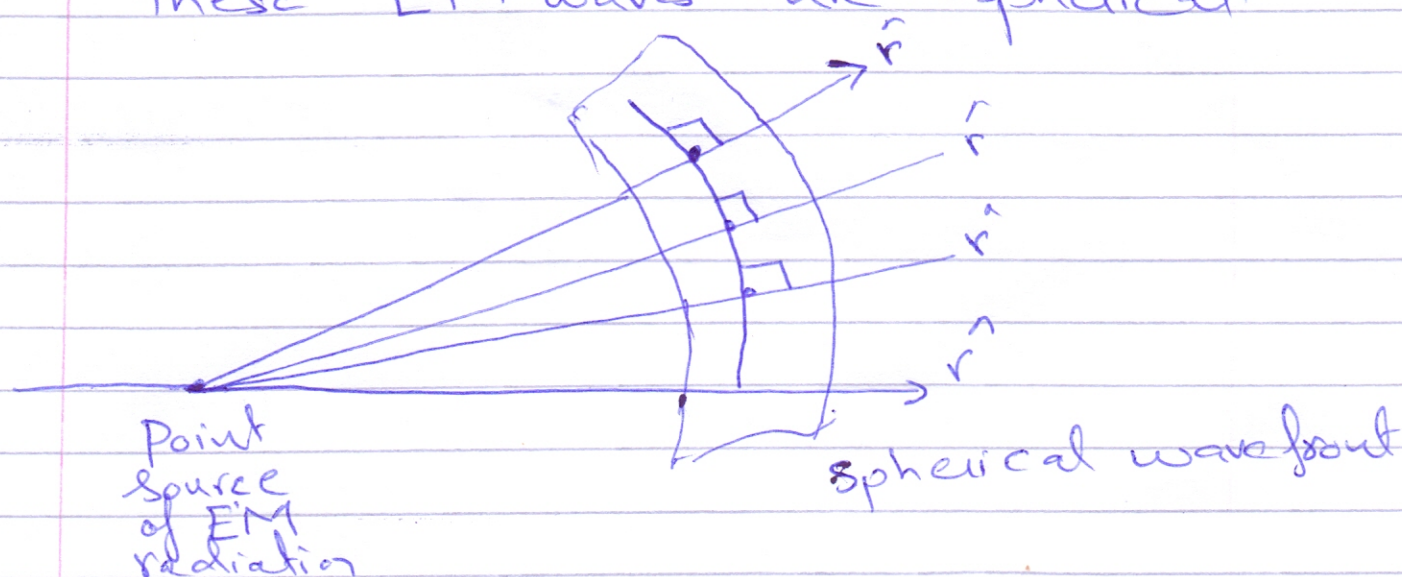


Important properties of waves are Amp, phase or frequency which allows the waves to carry information from source to destination.

\vec{E} is function of (\vec{r}, t) and independent of y & z .

Electromagnetic Spherical waves

- Another possible solution of wave equation can be spherical EM waves — emitted from a point source
- Wave-fronts associated with these EM waves are spherical.



Mathematical form

$$\vec{F}(r,t) = \frac{\vec{F}_0}{r} e^{i(k \cdot r - \omega t)}$$

r — radial distance from the point source to a given pt on wave front.

$\frac{\vec{F}_0}{r}$ — amplitude

→ If point source is infinitely far

away from field point (observer)

→ A spherical wave → plane wave in this limit ($R_c \rightarrow \infty$)

Criterion for a plane wave

$$\lambda \ll R_c$$

Monochromatic Plane waves associated with $\vec{E} \text{ and } \vec{B}$

Using complex notation i.e.

$$e^{i\omega t} = \cos \omega t + i \sin \omega t \quad \text{Euler's eqn.}$$

$$\Rightarrow \vec{E}(\vec{r}, t) = \vec{E}_0 (e^{i(k \cdot \vec{r} - \omega t)})$$

$$\text{and } \vec{B}(\vec{r}, t) = \vec{B}_0 (e^{i(k \cdot \vec{r} - \omega t)})$$

For wave propagating in z -direction

$$\begin{aligned} \vec{k} \cdot \vec{r} &= (k_x \hat{x} + k_y \hat{y} + k_z \hat{z}) \cdot (x \hat{x} + y \hat{y} + z \hat{z}) \\ &= k_z z \end{aligned}$$

Monochromatic EM Plane Waves

$$\vec{E}(z, t) = \vec{E}_0 e^{i(kz - \omega t)}$$

propagating in +z direct.

complex vectors

Similarly for M. field

$$\vec{B}(z, t) = \vec{B}_0 e^{i(kz - \omega t)}$$

with $\vec{E}_0 = E_0 e^{i\delta_x} \hat{x} = E_0 e^{i\delta_x} \hat{n}$

$$\vec{B}_0 = B_0 e^{i\delta_y} \hat{y}$$

⇒ The real, physical (instantaneous) fields are.

$$\vec{E}(\vec{r}, t) \equiv \text{Re}(\vec{E}(\vec{r}, t))$$

$$\vec{B}(\vec{r}, t) \equiv \text{Re}(\vec{B}(\vec{r}, t))$$

⇒ Maxwell's equations impose additional constraints on \vec{E}_0 & \vec{B}_0

$$\text{As } \vec{\nabla} \cdot \vec{E} = 0 \quad \& \quad \vec{\nabla} \cdot \vec{B} = 0$$

$$\text{Re}(\vec{\nabla} \cdot \vec{E}) = 0$$

$$\text{Re}(\vec{\nabla} \cdot \vec{B}) = 0$$

only satisfied if.

(24)

if $\vec{\nabla} \cdot \vec{E} = 0$ for all \vec{r}, t

and $\vec{\nabla} \cdot \vec{B} = 0 \quad \forall (\vec{r}, t)$

In Cartesian Co-ordinates.

$$\vec{\nabla} = \frac{\partial}{\partial x} \hat{x} + \frac{\partial}{\partial y} \hat{y} + \frac{\partial}{\partial z} \hat{z}$$

$$\vec{\nabla} \cdot \vec{E} = 0 \quad ; \quad \vec{\nabla} \cdot \vec{B} = 0$$

$$\left(\frac{\partial}{\partial x} \hat{x} + \frac{\partial}{\partial y} \hat{y} + \frac{\partial}{\partial z} \hat{z} \right) \cdot \left(\vec{E}_0 e^{i(kz - \omega t)} \right) = 0$$

If we allow all polarization direction

$$\Rightarrow \vec{E}_0 = (E_{0x} \hat{x} + E_{0y} \hat{y} + E_{0z} \hat{z}) e^{i\delta} \equiv \vec{E}_0 e^{i\delta}$$

$$\vec{\nabla} \cdot \vec{E} = 0$$

$$\Rightarrow \left(\frac{\partial}{\partial x} \hat{x} + \frac{\partial}{\partial y} \hat{y} + \frac{\partial}{\partial z} \hat{z} \right) \cdot (E_{0x} \hat{x} + E_{0y} \hat{y} + E_{0z} \hat{z}) e^{i\delta} e^{i(kz - \omega t)} = 0$$

E_{0x}, E_{0y} & $E_{0z} \Rightarrow$ Amplitudes of the E-F

Components in x, y, z directions

(25)

$$\Rightarrow \frac{\partial}{\partial x} \hat{x} \cdot E_{0x} \hat{x} e^{i(kz - \omega t)} e = 0$$

$$\frac{\partial}{\partial y} \hat{y} \cdot E_{0y} \hat{y} e^{i(kz - \omega t)} e = 0$$

$$\frac{\partial}{\partial z} \hat{z} \cdot E_{0z} \hat{z} e^{i(kz - \omega t)} e = ik E_{0z} e^{i(kz - \omega t)} e$$

This will = zero if and only if

$$E_{0z} = 0$$

Similarly $B_{0z} = 0$ iff r

\Rightarrow Maxwell's eqns impose the restriction

that an electromagnetic plane wave cannot have any component of \vec{E} or \vec{B} ~~parallel~~ parallel and/or anti-parallel to the propagation direction.

\Rightarrow EM wave is a transverse wave (at least for propagation in free space)

→ Maxwell's eqns. impose another restriction on the allowed form of \vec{E} and \vec{B} for an EM wave.

$$\vec{\nabla} \times \vec{E} = -\frac{\partial \vec{B}}{\partial t} \quad \text{or} \quad \vec{\nabla} \times \vec{B} = \frac{1}{c^2} \frac{\partial \vec{E}}{\partial t}$$

$$= \text{Re}(\vec{\nabla} \times \vec{E}) = \text{Re}\left(-\frac{\partial \vec{B}}{\partial t}\right)$$

It can only be satisfied if and only if.

$$\vec{\nabla} \times \vec{E} = -\frac{\partial \vec{B}}{\partial t} \quad \text{or} \quad \vec{\nabla} \times \vec{B} = \frac{1}{c^2} \frac{\partial \vec{E}}{\partial t}$$

$$\vec{\nabla} \times \vec{E} = \left(\frac{\partial \tilde{E}_z}{\partial y} - \frac{\partial \tilde{E}_y}{\partial z}\right) \hat{x} + \left(\frac{\partial \tilde{E}_x}{\partial z} - \frac{\partial \tilde{E}_z}{\partial x}\right) \hat{y} + \left(\frac{\partial \tilde{E}_y}{\partial x} - \frac{\partial \tilde{E}_x}{\partial y}\right) \hat{z}$$

$$= -\frac{\partial \tilde{B}_x}{\partial t} \hat{x} - \frac{\partial \tilde{B}_y}{\partial t} \hat{y} - \frac{\partial \tilde{B}_z}{\partial t} \hat{z}$$

zero: no x, y dependence in \tilde{E}_x & \tilde{E}_y

As $E_z \neq B_z = 0$

$$\vec{\nabla} \times \vec{E} = -\frac{\partial \tilde{E}_y}{\partial z} \hat{x} + \frac{\partial \tilde{E}_x}{\partial z} \hat{y} = -\frac{\partial \tilde{B}_x}{\partial t} \hat{x} - \frac{\partial \tilde{B}_y}{\partial t} \hat{y}$$

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Complex Electric field vector \vec{E} is given by

(27)

$$\begin{aligned}\vec{\tilde{E}} &= \tilde{E}_x \hat{x} + \tilde{E}_y \hat{y} + \cancel{\tilde{E}_z \hat{z}} \\ &= (E_{0x} \hat{x} + E_{0y} \hat{y}) e^{i(kz - \omega t)} e^{is} \quad \left| \begin{array}{l} \tilde{E}_x = E_{0x} e^{is} \\ \quad \quad \quad \times e^{i(kz - \omega t)} \end{array} \right.\end{aligned}$$

Similarly,

$$\vec{\tilde{B}} = \tilde{B}_x \hat{x} + \tilde{B}_y \hat{y} = (B_{0x} \hat{x} + B_{0y} \hat{y}) e^{i(kz - \omega t)} e^{is}$$

$$\vec{\nabla} \times \vec{\tilde{E}} = -\frac{\partial \tilde{E}_y}{\partial z} \hat{x} + \frac{\partial \tilde{E}_x}{\partial z} \hat{y} = -\frac{\partial \tilde{B}_x}{\partial t} \hat{x} - \frac{\partial \tilde{B}_y}{\partial t} \hat{y} \quad (1)$$

$$\vec{\nabla} \times \vec{\tilde{B}} = -\frac{\partial \tilde{B}_y}{\partial t} \hat{x} + \frac{\partial \tilde{B}_x}{\partial t} \hat{y} = \frac{1}{c^2} \frac{\partial \tilde{E}_x}{\partial t} \hat{x} + \frac{1}{c^2} \frac{\partial \tilde{E}_y}{\partial t} \hat{y} \quad (2)$$

Comparing same components
x-component

$$\vec{\nabla} \times \vec{\tilde{E}} \Rightarrow \boxed{-\frac{\partial \tilde{E}_y}{\partial z} \hat{x} = -\frac{\partial \tilde{B}_x}{\partial t} \hat{x}}$$

$$\Rightarrow \frac{\partial \tilde{E}_y}{\partial z} = \frac{\partial \tilde{B}_x}{\partial t} \Rightarrow ik E_{0y} e^{i(kz - \omega t)} e^{is} = -i\omega B_{0x} e^{i(kz - \omega t)} e^{is}$$

$$\Rightarrow ik E_{0y} = -i\omega B_{0x} \quad (3)$$

For y-component,

$$\frac{\partial \tilde{E}_x}{\partial z} \hat{y} = -\frac{\partial \tilde{B}_y}{\partial t} \hat{y} \Rightarrow ik E_{0x} = i\omega B_{0y} \quad (4)$$

For $\nabla \times \vec{B} = \mu_0 \epsilon_0 \frac{\partial \vec{E}}{\partial t}$

$$\nabla \times \vec{B}: \left[\frac{-\partial \tilde{B}_y}{\partial z} \hat{i} = \frac{1}{c^2} \frac{\partial \tilde{E}_x}{\partial t} \hat{i} \right] \Rightarrow -ik B_{oy} = \frac{1}{c^2} i\omega E_{ox} \quad (5)$$

2

$$+\frac{\partial \tilde{B}_x}{\partial z} \hat{j} = \frac{1}{c^2} \frac{\partial \tilde{E}_y}{\partial t} \hat{j} \Rightarrow ik B_{ox} = -\frac{1}{c^2} i\omega E_{oy} \quad (6)$$

From eqn 3, 4, 5 & 6 we have

$$ik E_{oy} = -i\omega B_{ox} \Rightarrow E_{oy} = -\left(\frac{\omega}{k}\right) B_{ox} \quad (7)$$

$$ik E_{ox} = i\omega B_{oy} \Rightarrow E_{ox} = \left(\frac{\omega}{k}\right) B_{oy} \quad (8)$$

$$-ik B_{oy} = -\frac{1}{c^2} i\omega E_{ox} \Rightarrow B_{oy} = \frac{1}{c^2} \left(\frac{\omega}{k}\right) E_{ox} \quad (9)$$

$$ik B_{ox} = -\frac{1}{c^2} i\omega E_{oy} \Rightarrow B_{ox} = -\frac{1}{c^2} \left(\frac{\omega}{k}\right) E_{oy} \quad (10)$$

$$\text{As } c = f\lambda \text{ or } c = v\lambda = (2\pi f)\left(\frac{\lambda}{2\pi}\right) = \frac{\omega}{k}$$

$$\frac{1}{c} = \frac{k}{\omega} \text{ and } k = \frac{2\pi}{\lambda}$$

$$\text{eqn (7) in terms of } B_{ox} = -\left(\frac{k}{\omega}\right) E_{oy}$$

$$\text{" (8) " " of } B_{oy} = \frac{1}{k} \left(\frac{\omega}{k}\right) E_{ox}$$

$$\begin{array}{lcl}
 \vec{\nabla} \times \vec{E} : & B_{ox} = -\frac{1}{c} E_{oy} & \uparrow \\
 & B_{oy} = \frac{1}{c} E_{ox} & \uparrow \\
 \vec{\nabla} \times \vec{B} : & B_{oy} = \frac{1}{c} E_{ox} & \downarrow \\
 & B_{ox} = -\frac{1}{c} E_{oy} & \downarrow
 \end{array}$$

Redundancy of relations.

Two independent relations are

$$B_{ox} = -\frac{1}{c} E_{oy} \Rightarrow -\hat{x} = \hat{z} \times \hat{y}$$

$$B_{oy} = \frac{1}{c} E_{ox} \Rightarrow \hat{y} = \hat{z} \times \hat{x}$$

In compact form.

$$\vec{B}_0 = \frac{1}{c} (\hat{z} \times \vec{E}_0)$$

Physically this relation states that \vec{E} & \vec{B} are

\Rightarrow In phase with each other.

\Rightarrow Mutually \perp to each other - $(\vec{E} \perp \vec{B}) \perp \hat{z}$

The real amplitudes of \vec{E} & \vec{B} are related to each other.

$$B_0 = \frac{1}{c} E_0$$

$$\text{where } B_0 = \sqrt{B_{0x}^2 + B_{0y}^2} \\ \approx E_0 = \sqrt{E_{0x}^2 + E_{0y}^2}$$

Instantaneous Poynting's vector associated with an EM wave is

$$\vec{S}(\vec{r}, t) = \frac{1}{\mu_0} \vec{E}(\vec{r}, t) \times \vec{B}(\vec{r}, t) = \frac{\text{Watt}}{\text{m}^2} \\ \Rightarrow \vec{S}(z, t) = \frac{1}{\mu_0} \vec{E}(z, t) \times \vec{B}(z, t) \\ = \frac{1}{\mu_0} \text{Re}\{\vec{E}(z, t)\} \times \text{Re}\{\vec{B}(z, t)\}$$

It represents the energy that is instantaneously flowing out of boundary surface.

\Rightarrow The energy transported by \vec{E} & \vec{B}

Also called energy flux density.

For linearly polarized plane wave

propagating in z-direction

$$\vec{S}(z,t) = c \epsilon_0 E_0^2 \cos^2(kz - \omega t + \delta)$$

Energy density stored in E & B

$$= \frac{1}{2} \left(\epsilon_0 E^2 + \frac{1}{\mu_0} B^2 \right)$$

for free space propagation

Instantaneous EM field energy contained in volume V is

$U_E = U_M$ i.e.	energy stored in Electric field is equal to that stored in M.F
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$$U_{EM}(t) = \int U_{EM}(\vec{r}, t) d\tau \quad (\text{Joules})$$

EM linear momentum density.

$$\vec{p}_{EM}(\vec{r}, t) \equiv \epsilon_0 \mu_0 \vec{S} = \frac{1}{c^2} \vec{S}(\vec{r}, t)$$

$$= \epsilon_0 (\vec{E}(\vec{r}, t) \times \vec{B}(\vec{r}, t)) \quad \text{kg/m}^2\text{-sec}$$

$$P_{EM}(t) \equiv \int \vec{p}_{EM}(\vec{r}, t) d\tau$$

EM angular momentum Density

$$\vec{l}_{EM}(\vec{r}, t) \equiv \vec{r} \times \vec{p}_{EM}$$

$$= \epsilon_0 \mu_0 \vec{r} \times \vec{S}(\vec{r}, t) = \frac{1}{c^2} \vec{r} \times \vec{S}(\vec{r}, t)$$

$$\vec{L}_{EM}(t) \equiv \int_V \vec{l}_{EM}(\vec{r}, t) d\tau$$

$$= \epsilon_0 \int_V \left[\vec{r} \times [\vec{E}(\vec{r}, t) \times \vec{B}(\vec{r}, t)] \right] d\tau$$

Intensity of EM field is

$$I(\vec{r}) \equiv \left\langle |\vec{S}(\vec{r}, t)| \right\rangle = c \left\langle u_{EM}(\vec{r}, t) \right\rangle$$

$$= \frac{1}{2} c \epsilon_0 E_0^2(\vec{r})$$

time averaged
Poynting vector