

OPTIMIZATION OF MEAN-FIELD SPIN GLASSES

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Joint work /



&



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The Ising mixed p-spin Hamiltonian

$(H_N(\sigma))_{\sigma \in \Sigma_N}$ centered Gaussian process with covariance

$$\mathbb{E}[H_N(\sigma)H_N(\sigma')] = N\xi(\langle\sigma, \sigma'\rangle/N)$$

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2-spin (SK)

$$H_N(\sigma) = \frac{1}{\sqrt{N}} \sum_{i < j}^N J_{ij} \sigma_i \sigma_j$$

$$\xi(x) = x^2$$

3-spin

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$$\text{maximize} \quad H_N(\sigma) \quad \text{s.t.} \quad \sigma \in \Sigma_N = \{-1, +1\}^N$$

(Ground state)

Optimization

$$\text{maximize} \quad H_N(\sigma) \quad \text{s.t.} \quad \sigma \in \Sigma_N = \{-1, +1\}^N$$

- Can we **efficiently** find an (approximate) ground state?
- **Input:** Gradient oracle for H_N . Tolerance $\epsilon > 0$.
- **Output:** $\sigma^{\text{alg}} = \sigma^{\text{alg}}(\text{queries}) \in \{\pm 1\}^N$ such that

$$H_N(\sigma^{\text{alg}}) \geq (1 - \epsilon) \max_{\sigma \in \Sigma_N} H_N(\sigma) \quad \text{w.h.p.}$$

- **Runtime:** #queries = $\text{Poly}(N, 1/\epsilon)$.

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Worst case: Already NP-hard for quadratics and for $1 - \epsilon \geq 1/(\log N)^c$

[Arora et al. 2005]

What is known

Convex relaxations: (Pure k-spin spherical model)

Level k Sum of Square relaxation: $SOS_N(k) \gtrsim N^{(k-2)/4} \cdot \text{OPT}_N$

[Bhattacharjee, Guruswami, Lee 2016]

Langevin/Glauber dynamics: Rich literature. Slow dynamics. Gets stuck at **threshold energy**.

[Cugliandolo, Kurchan 92] [Bouchaud et al. 98] [Ben Arous, Guionnet 95]
[Ben Arous, Dembo, Guionnet 2001]...

“Dual” algorithms: Spherical model [Subag 2018]

Ising SK ($p=2$) model [Montanari 2018]

→ Both achieve approximate global optimum under **no overlap gap assumption**.

Gamarnik & coauthors: Impossibility results if **overlap gap**; (Subhabrata’s talk)

Asymptotic value: Zero temperature Parisi formula

$$\mathcal{U} \equiv \left\{ \gamma : [0, 1) \rightarrow \mathbb{R}_{\geq 0} \text{ non-decreasing, } \int_0^1 \gamma(t) dt < \infty \right\}$$

$$\partial_t \Phi_\gamma(t, x) + \frac{\xi''(t)}{2} \left(\gamma(t) (\partial_x \Phi_\gamma(t, x))^2 + \partial_x^2 \Phi_\gamma(t, x) \right) = 0 \quad (\textbf{Parisi PDE})$$

$$(t, x) \in [0, 1] \times \mathbb{R} \quad \Phi_\gamma(1, x) = |x|$$

$$\mathsf{P}(\gamma) \equiv \Phi_\gamma(0, 0) - \frac{1}{2} \int_0^1 t \xi''(t) \gamma(t) dt \quad (\textbf{Parisi functional})$$

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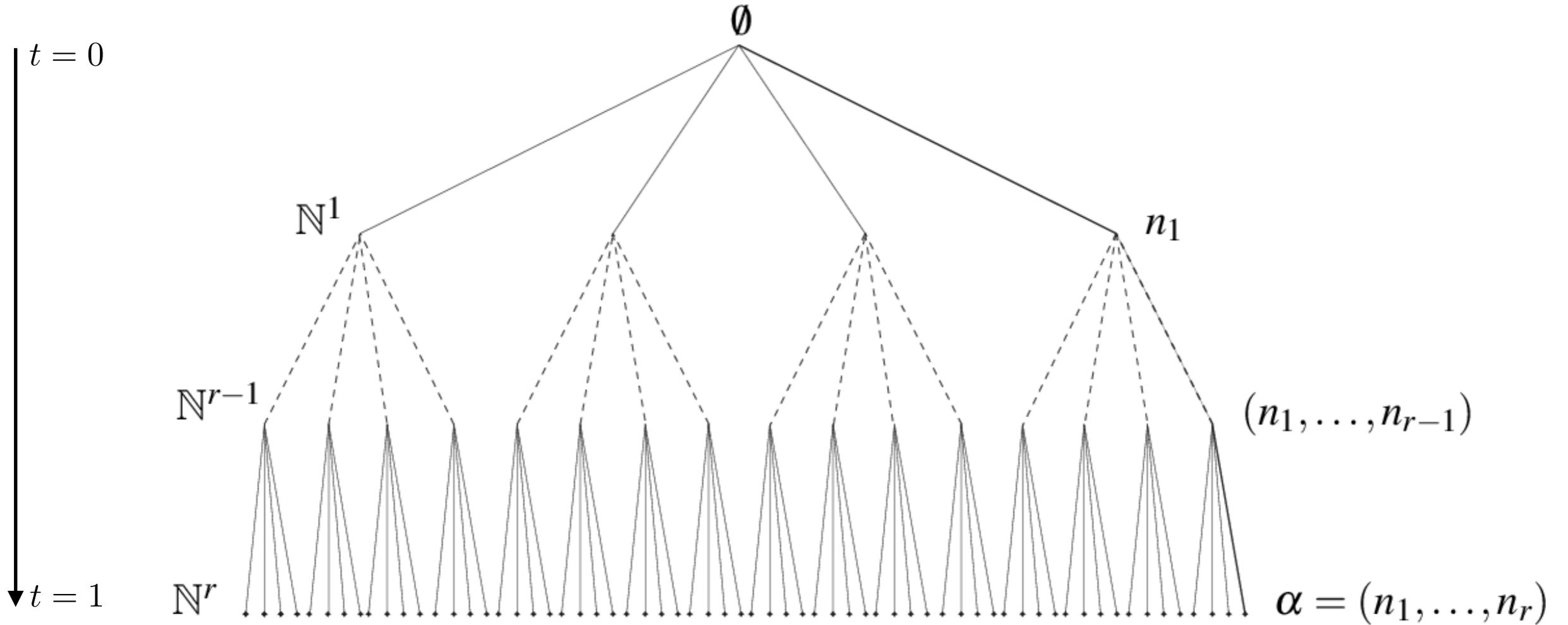
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Theorem [Auffinger, Chen 17]:

$$\frac{1}{N} \max_{\sigma \in \Sigma_N} H_N(\sigma) \xrightarrow[N \rightarrow \infty]{p} \inf_{\gamma \in \mathcal{U}} P(\gamma) \quad (\textbf{GS Energy})$$

Ultrametric structure

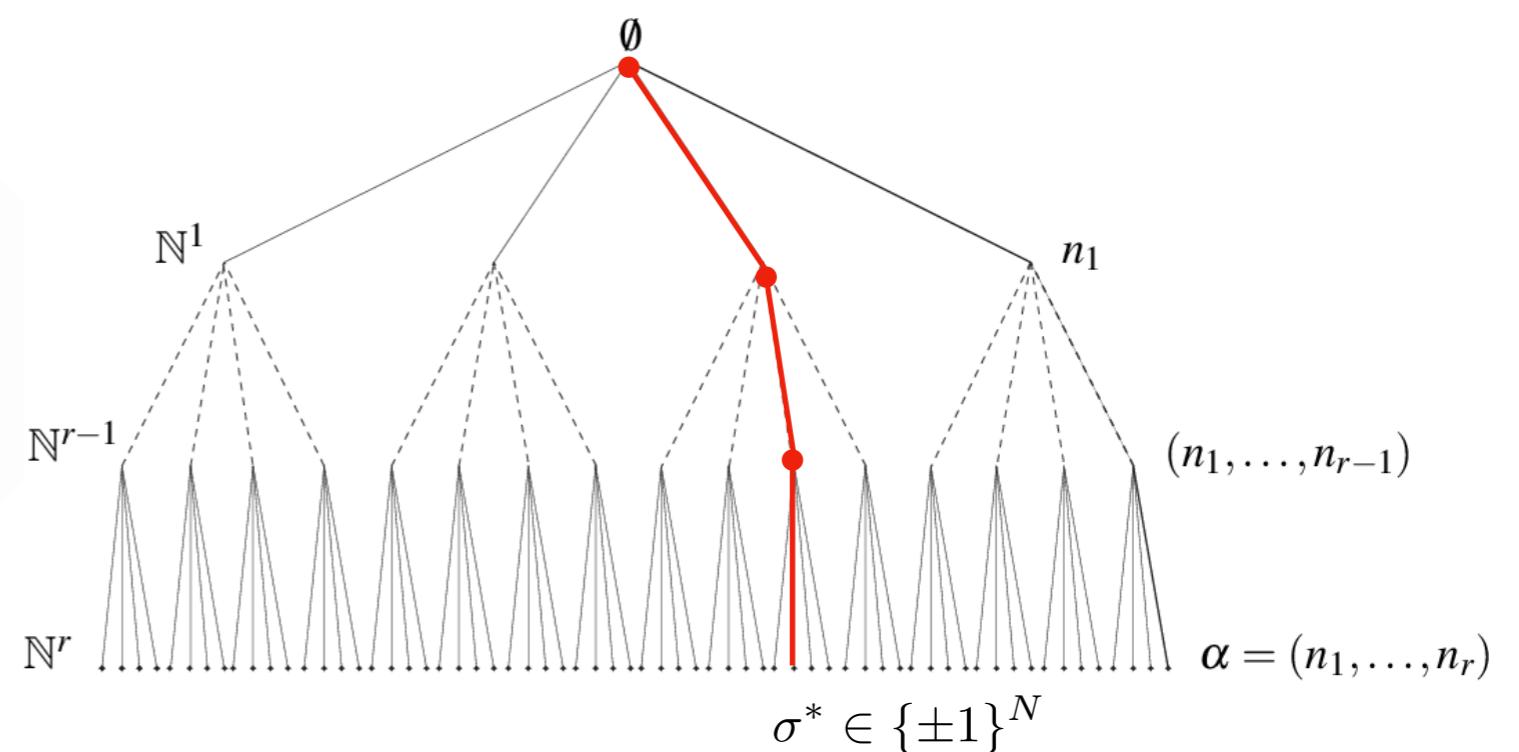
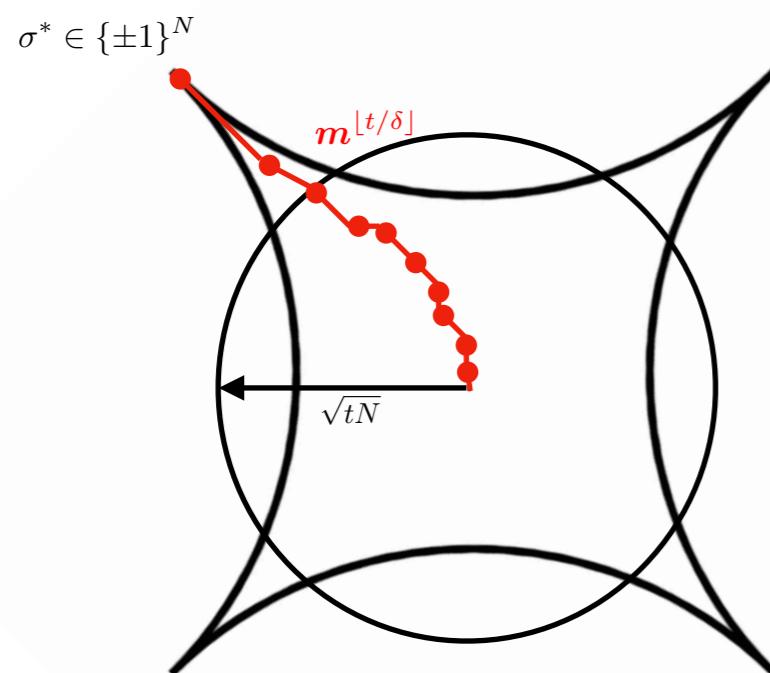


1. Clusters of near-optima in $\{\pm 1\}^N$ are represented by *leaves* of an infinitary tree
2. Internal (ancestor) nodes of the tree are associated to points $m \in [-1, 1]^N$
At level t : $\frac{1}{N} \|m\|_2^2 \simeq t$
3. Euclidean distance btw clusters is reflected by the tree distance btw nodes

[Mezard, Parisi, Toulouse, Virasoro 84] [Panchenko 13] [Chen, Panchenko, Subag 19]

Main algorithmic idea:

Start at the root and explore a random path in the tree



Main result

Extended Parisi formula

[EA, Montanari, Sellke 2020]

There exist **ALG** which outputs $\sigma^{\text{alg}} \in \{-1, +1\}^N$ in $C(\epsilon)$ iterations such that

$$H_N(\sigma^{\text{alg}}) \geq (1 - \epsilon) \inf_{\gamma \in \mathcal{L}} P(\gamma)$$

$\mathcal{U} \subset \mathcal{L}$ contains non-monotone functions.

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In particular, if $\inf_{\gamma \in \mathcal{U}} P(\gamma)$ is achieved at a strictly increasing function

→ **No overlap gap, continuous/full replica symmetry breaking**

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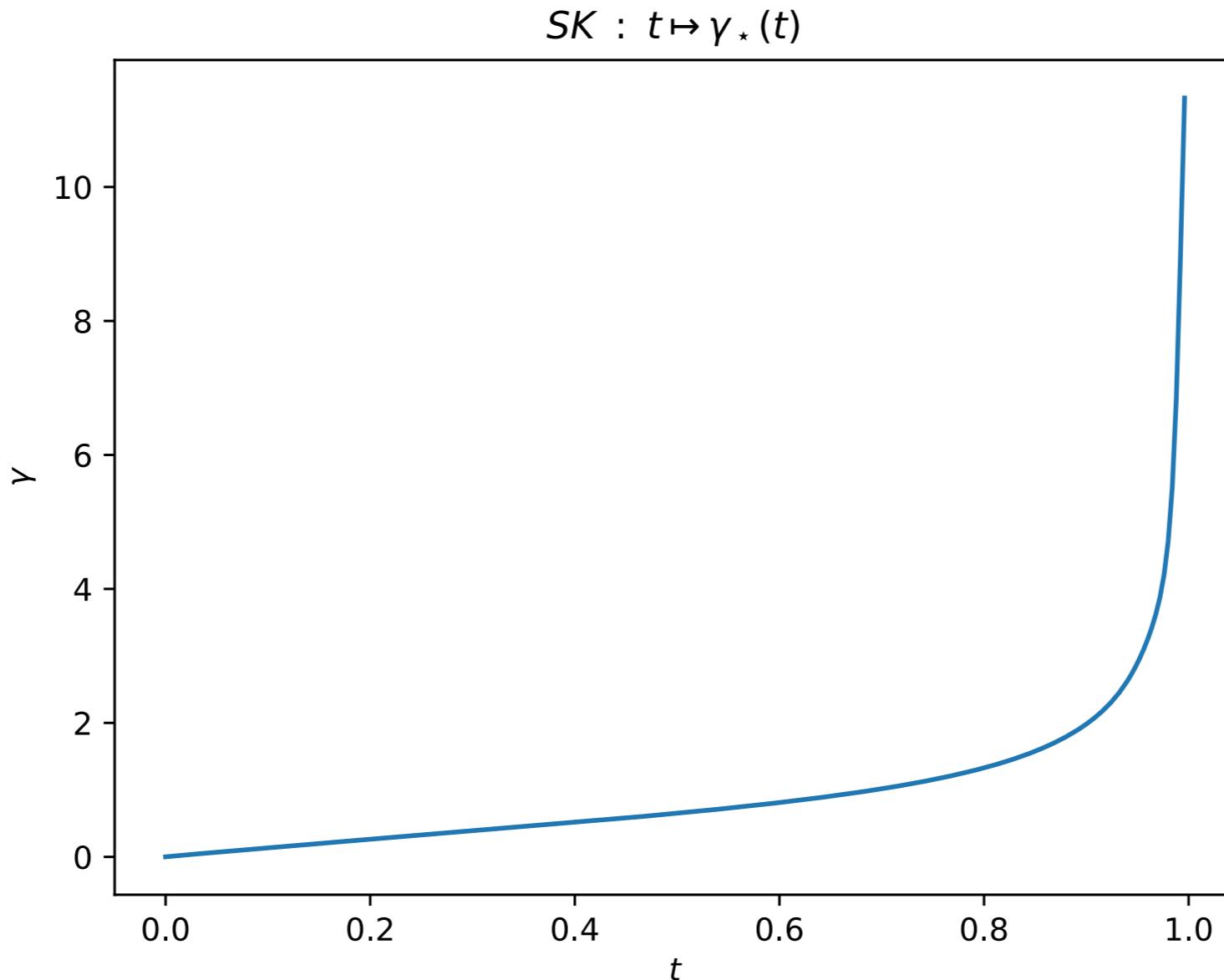
Best value algorithmically possible:

NO **AMP** algorithm can achieve a value larger than $\inf_{\gamma \in \mathcal{L}} P(\gamma)$

—————> An **algorithmic threshold** for optimization in spin glasses

2-spin/SK

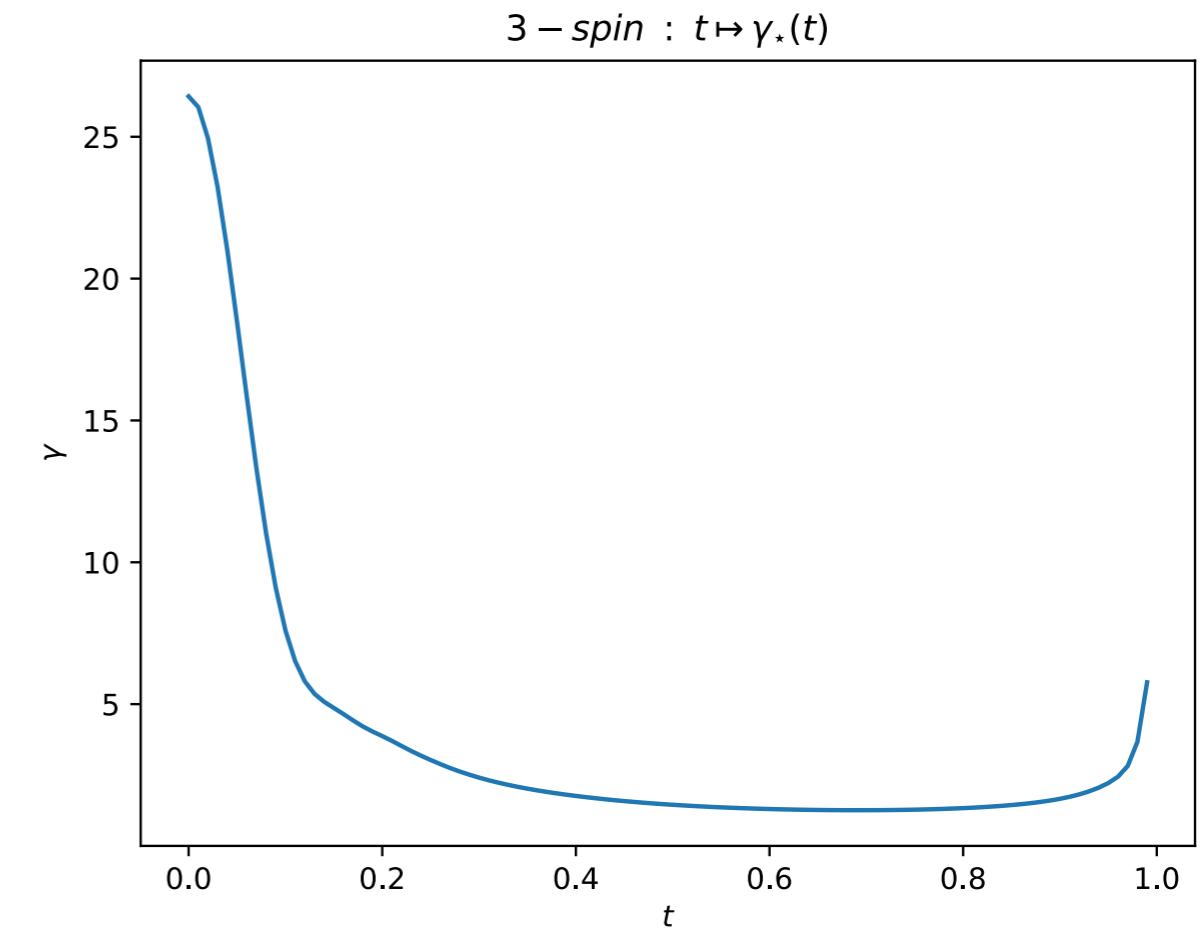
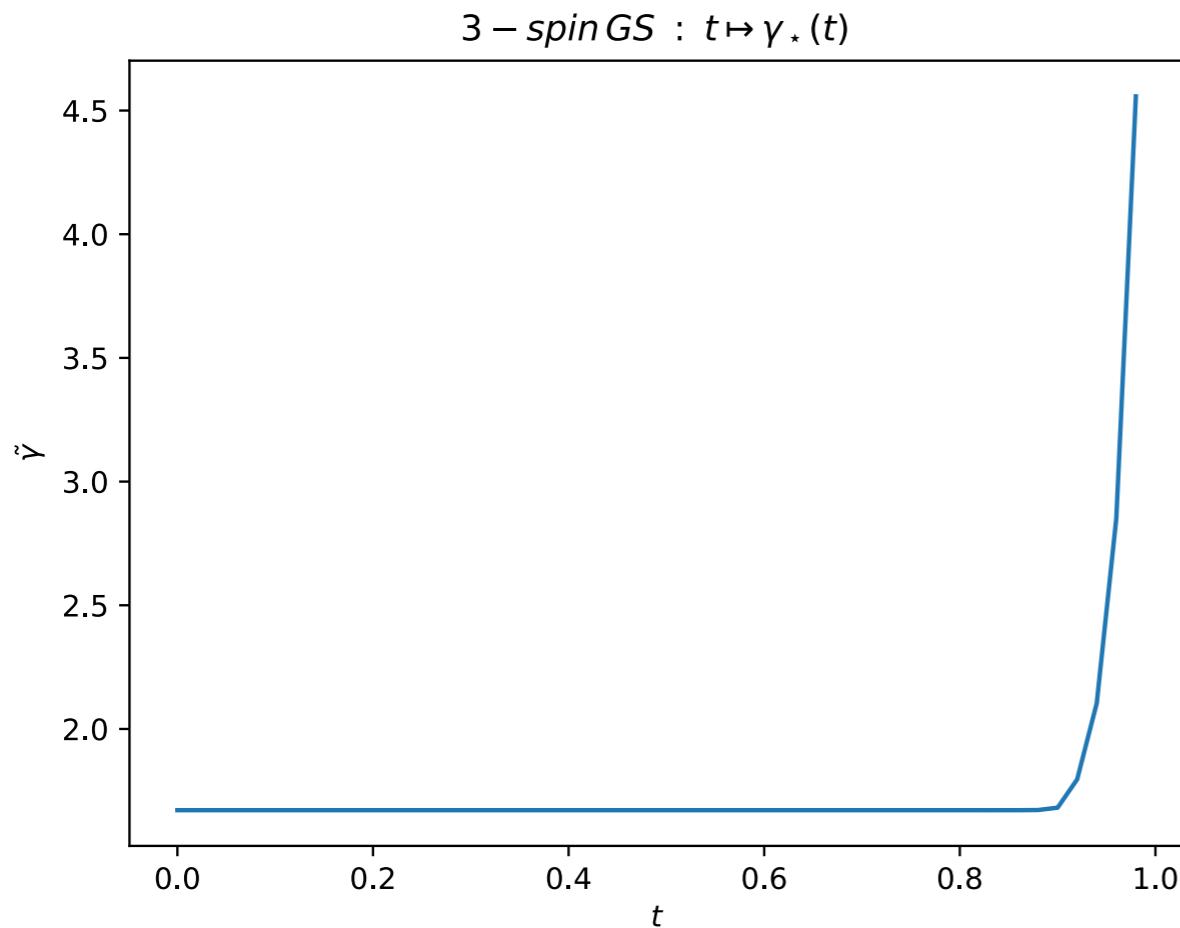
$$H_N(\sigma) = \frac{1}{\sqrt{N}} \sum_{i < j}^N J_{ij} \sigma_i \sigma_j$$



$$E_{\text{GS}} = E_{\text{ALG}} = \mathsf{P}(\gamma_*) \simeq .76316$$

3-spin

$$H_N(\sigma) = \frac{1}{N} \sum_{i < j < k} J_{ijk} \sigma_i \sigma_j \sigma_k$$



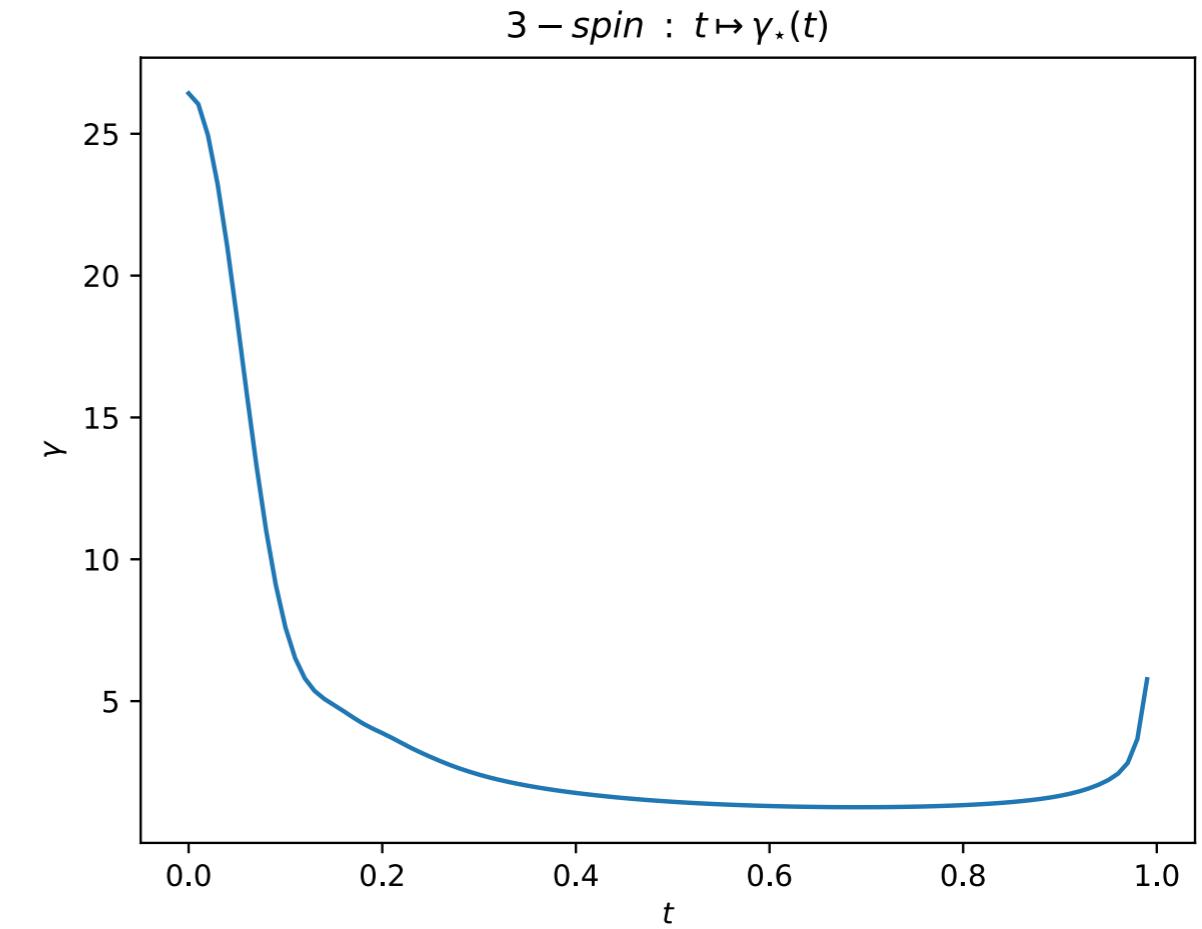
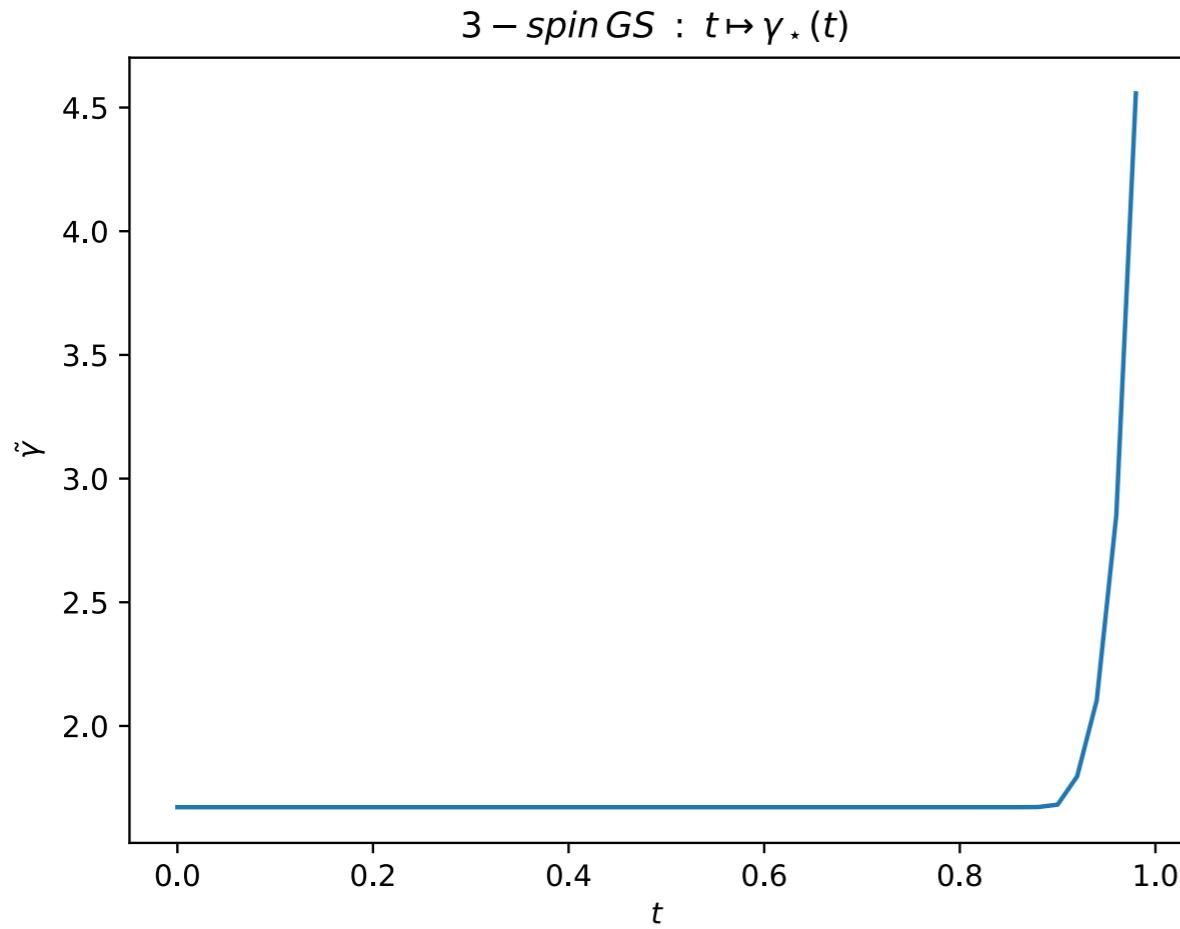
$$E_{\text{GS}} = \inf_{\gamma \in \mathcal{U}} \mathbb{P}(\gamma) \simeq .8134$$

$$E_{\text{ALG}} = \inf_{\gamma \in \mathcal{L}} \mathbb{P}(\gamma) \simeq .8006$$

$$E_{\text{ALG}} < E_{\text{GS}}$$

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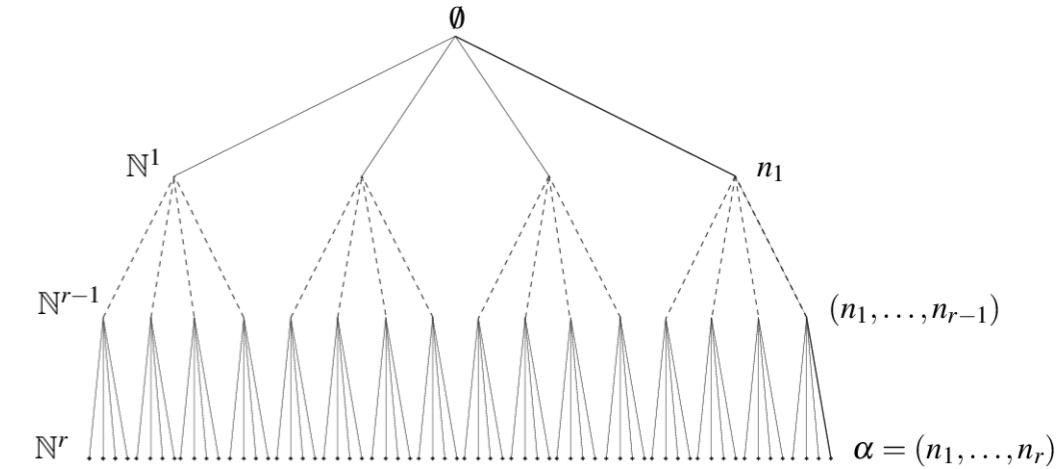
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$$.7882 \simeq E_{\text{thr}} < E_{\text{ALG}} < E_{\text{GS}}$$

[Rizzo 2013]

Stochastic formulation

$$(2\text{-spin}) \quad H_N(\sigma) = \frac{1}{\sqrt{N}} \sum_{i < j}^N J_{ij} \sigma_i \sigma_j$$



Effective (cavity) field: $dX_t = \gamma(t) \partial_x \Phi_\gamma(t, X_t) dt + dB_t \quad X_0 = 0$

Effective magnetization: $M_t = \partial_x \Phi_\gamma(t, X_t) = \int_0^t \partial_x^2 \Phi_\gamma(s, X_s) dB_s$

RS: $X_q \sim N(0, q), \quad M_q = \tanh(\beta X_q + h)$

Discretize SDE with driving noise coming from $\mathbf{J} = (J_{i,j})$ in the “right” way.

AMP

Incremental Approximate Message Passing

$$\begin{aligned} \mathbf{z}^0 &= 0 \\ t \in \{0, \delta, 2\delta, \dots, \ell\delta, \dots, 1\} \quad \mathbf{m}^\ell &= f_\ell(\mathbf{z}^0, \dots, \mathbf{z}^\ell) \\ \mathbf{z}^{\ell+1} &= \frac{1}{\sqrt{N}} \mathbf{J} \mathbf{m}^\ell - \sum_{j=0}^{\ell} d_{\ell,j} \mathbf{m}^{j-1} \end{aligned}$$

State Evolution: $\mathbf{z}^0, \dots, \mathbf{z}^\ell$ converge to a centered Gaussian vector with cov.

$$\mathbb{E}[Z^{\ell+1} Z^{\ell'+1}] = \mathbb{E}[f_\ell(Z^0, \dots, Z^\ell) f_{\ell'}(Z^0, \dots, Z^{\ell'})].$$

Choice of non-linearities: $f_\ell : (\mathbf{z}^0, \dots, \mathbf{z}^\ell) \mapsto \mathbf{m}^\ell$

$$\begin{aligned} \mathbf{x}^0 &= 0 \\ \mathbf{x}^{j+1} - \mathbf{x}^j &= v(\delta j, \mathbf{x}^j) \delta + (\mathbf{z}^{j+1} - \mathbf{z}^j) \quad \text{for } 0 \leq j \leq \ell \\ \mathbf{m}^\ell &= \sum_{j=0}^{\ell-1} u(\delta j, \mathbf{x}^j) (\mathbf{z}^{j+1} - \mathbf{z}^j) \end{aligned}$$

Self-consistency condition

Assume Z^0, \dots, Z^ℓ has independent increments with $\mathbb{E}[(Z^{j+1} - Z^j)^2] = \delta \quad \forall j \leq \ell - 1$

Show $\mathbb{E}[(Z^{\ell+1} - Z^\ell)Z^j] = 0 \quad \forall j \leq \ell$ and $\mathbb{E}[(Z^{\ell+1} - Z^\ell)^2] = \delta$

Necessary condition: $\mathbb{E}[u(\delta\ell, X^\ell)^2] = 1 \quad \forall \ell$

$$\implies \mathbb{E}[u(t, X_t)^2] = 1 \quad \forall t \in [0, 1]$$

An algorithm design question

Energy achieved:

$$N^{-1} H_N(\mathbf{m}^{\lfloor \delta^{-1} \rfloor}) \xrightarrow[N \rightarrow \infty]{\delta \rightarrow 0} \int_0^1 \mathbb{E}[u(t, X_t)] dt$$

Necessary condition:

$$\mathbb{E}[u(t, X_t)^2] = 1 \quad \forall t \in [0, 1]$$

Ising spins:

$$M_1 = \int_0^1 u(s, X_s) dB_s \in (-1, +1) \text{ a.s.}$$

An algorithm design question

$$\max_{u,v} \int_0^1 \mathbb{E}[u(t, X_t)] dt$$

$$\mathbb{E}[u(t, X_t)^2] = 1 \quad \forall t \in [0, 1]$$

subj. to

$$M_1 = \int_0^1 u(s, X_s) dB_s \in (-1, +1) \text{ a.s.}$$

An algorithm design question

$$\mathcal{E}_\star = \max_{u \in D[0,1]} \int_0^1 \mathbb{E}[u_t] dt$$

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Relaxed stochastic control problem

$$\mathcal{E}_\star \leq \text{REL}$$

$$\text{REL} \equiv \sup_{u \in D[0,1]} \mathbb{E} \left[\int_0^t u_s ds + \frac{1}{2} \int_0^1 \nu(s) (u_s^2 - 1) ds \right]$$

$$\nu(t) = \int_t^1 \gamma(s) ds \quad \text{s.t.} \quad \int_0^1 u_s dB_s \in (-1, 1) \text{ a.s.}$$

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Theorem: $\text{REL} = P(\gamma)$ and $\mathcal{E}_\star = \inf_{\gamma \in \mathcal{L}} P(\gamma)$!!

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Theorem: $\text{REL} = \mathsf{P}(\gamma)$ and $\mathcal{E}_\star = \inf_{\gamma \in \mathcal{L}} \mathsf{P}(\gamma)$!!

Optimal control: $u_t^* = \partial_x^2 \Phi_\gamma(t, X_t)$ $v(t, x) = \gamma(t) \partial_x \Phi_\gamma(t, x)$
 $dX_t = \gamma(t) \partial_x \Phi_\gamma(t, X_t) dt + dB_t$

Main message

Duality

Stochastic control problem

$$\begin{aligned} & \sup_{u \in D[0,1]} \mathbb{E} \left[\int_0^1 u_s ds \right] \\ \text{s.t. } & \mathbb{E}[u_t^2] = 1 \quad \forall t \in [0, 1], \\ & \int_0^1 u_s dB_s \in (-1, 1) \text{ a.s.} \end{aligned}$$

Parisi formula



$$\inf_{\gamma \in \mathcal{L}} P(\gamma)$$

Some interesting directions

- Physical interpretation of Extended Parisi Principle
- Explore the duality property.
- Other models: Perceptron, k-SAT, bipartite, Hopfield,...
- Sampling from the Gibbs measure
- Sparse models (MIN-BIS, MAX-CUT on random regular graph)

Thanks!