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Introduction to Nonlinear Gyrokinetic Equation

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These are preliminary lecture notes, intended only for distribution to participants.

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Trieste

Intro to Nonlinear

Gyrokinetic Equation

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I. Microminstabilities + MHD instabilities

often driven by "bad curvature" + ∇p .

⇒ intuitive picture of this

II. Properties of the Gyrokinetic Eq.

+ GK ordering

compare with Kulsrud's Collisionless MHD

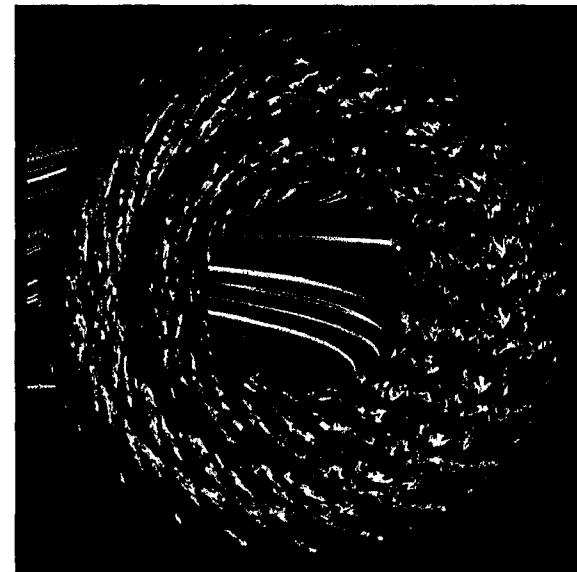
+ drift-kinetic ordering.

THEORY-BASED MODELS OF TURBULENCE AND ANOMALOUS TRANSPORT IN FUSION PLASMAS

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APS Centennial, Atlanta, March, 1999

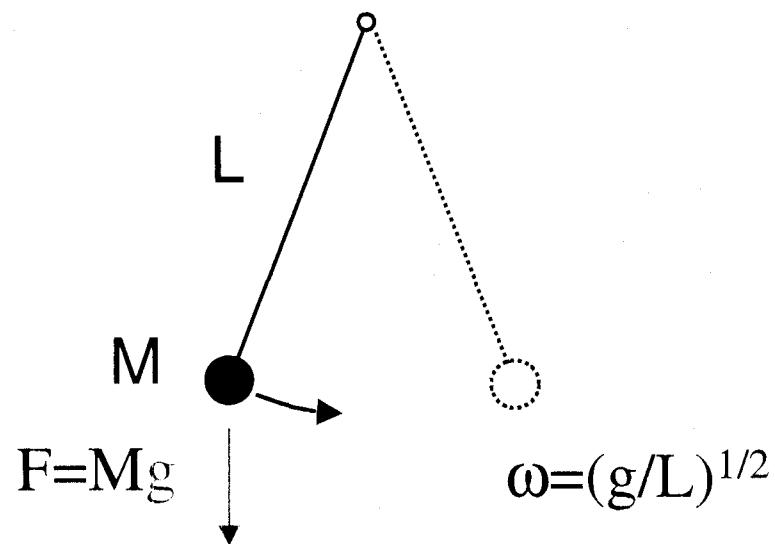
**Close collaboration with M.A. Beer (PPPL),
W. Dorland (Univ. of Maryland), M. Kotschenreuther
(Univ. of Texas), R.E. Waltz (General Atomics).**

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T.S. Hahm, Z. Lin, P.B. Snyder (PPPL),
S.E. Parker (U. Colorado), and many others.**



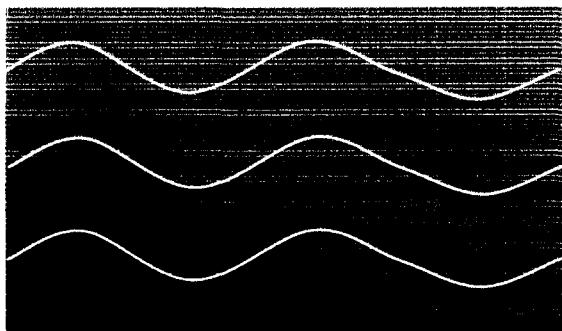
**Supported at PPPL by DOE contract DE-AC02-76CH03073, computational resources at NERSC and the LANL ACL,
part of the Numerical Tokamak Turbulence Project national collaboration, a DOE HPCCI Grand Challenge.**

Stable Pendulum



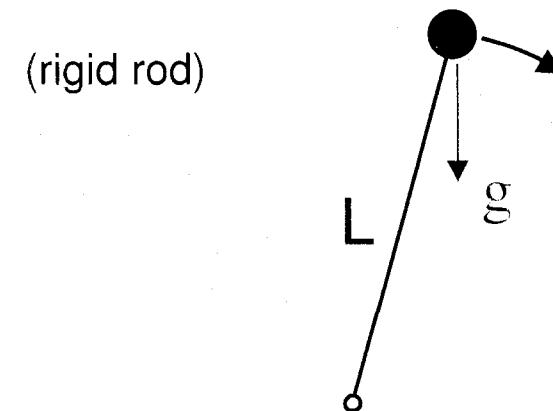
Density-stratified Fluid

$$\rho = \exp(-y/L)$$



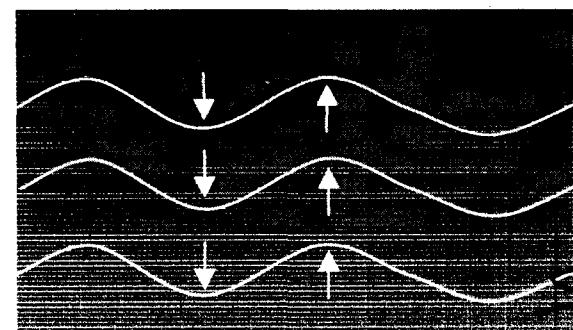
stable $\omega = (g/L)^{1/2}$

Unstable Inverted Pendulum



↑ Instability

Inverted-density fluid
⇒ Rayleigh-Taylor Instability
 $\rho = \exp(y/L)$

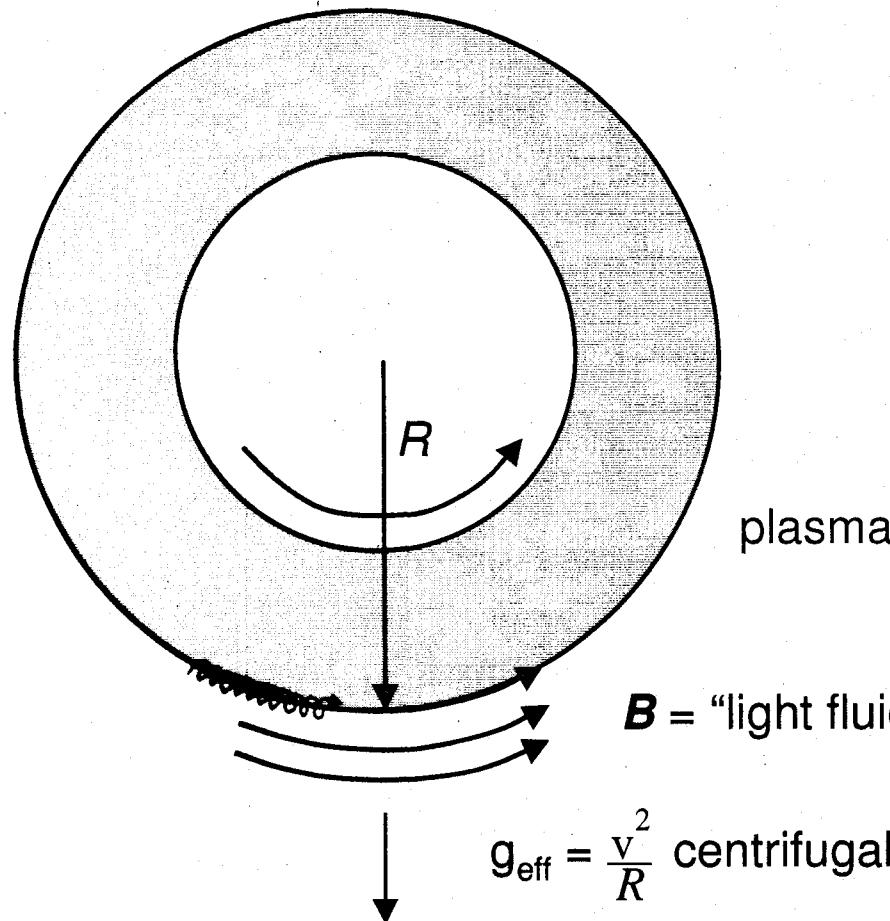


Max growth rate $\gamma = (g/L)^{1/2}$

“Bad Curvature” instability in plasmas

≈ Inverted Pendulum / Rayleigh-Taylor Instability

Top view of toroidal plasma:



Growth rate:

$$\gamma = \sqrt{\frac{g_{eff}}{L}} = \sqrt{\frac{V_t^2}{RL}} = \frac{V_t}{\sqrt{RL}}$$

Similar instability mechanism
in MHD & drift/microinstabilities

$1/L = \nabla p/p$ in MHD,
≈ combination of ∇n & ∇T
in microinstabilities.

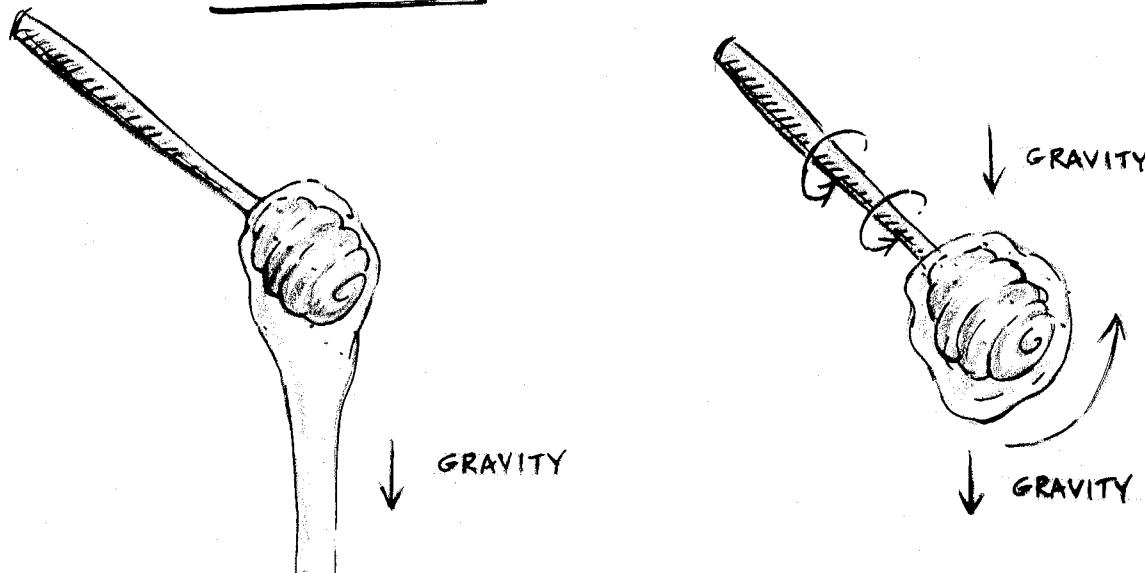
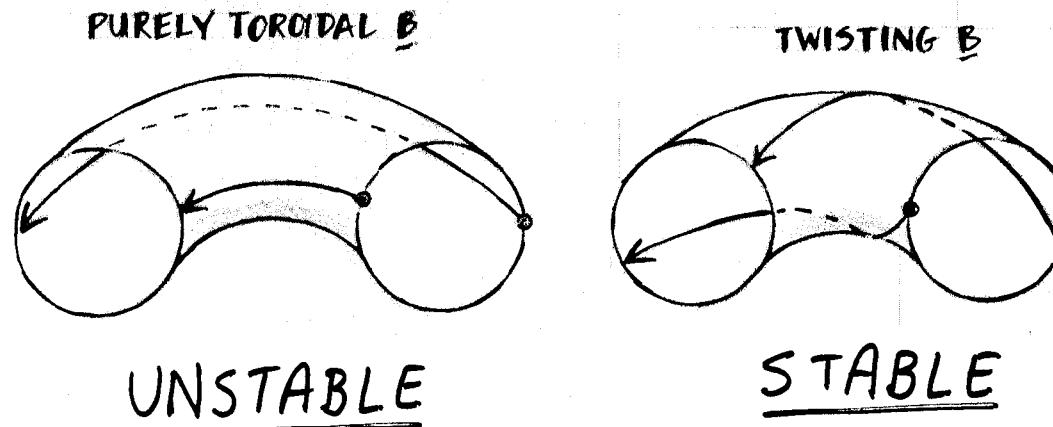
plasma = heavy fluid

B = “light fluid”

$$g_{eff} = \frac{v^2}{R} \text{ centrifugal force}$$

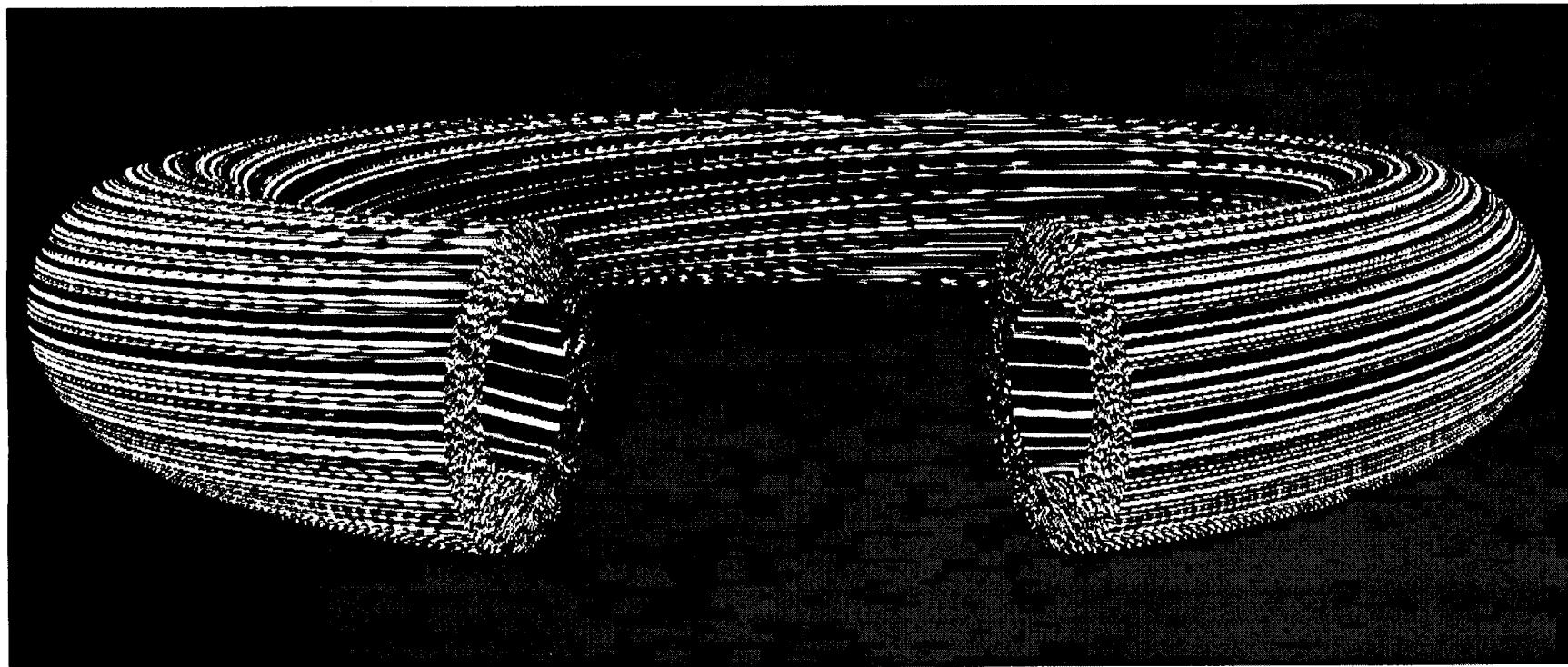
The Secret for Stabilizing Bad-Curvature Instabilities

Twist in \underline{B} carries plasma from bad curvature region to good curvature region.



Similar to how a twirling honey dipper can prevent honey from dripping.

Cut-away view of tokamak turbulence simulation



Waltz (General Atomics), Kerbel (LLNL), et.al., gyrofluid simulations. Similar pictures from gyrokinetic particle simulations.

Lots more pictures at www.acl.lanl.gov/GrandChal/Tok/gallery.html.

The Simplest Drift Wave

(oversimplified...)

Classic drift wave ordering:

$$V_{ti} \ll \frac{\omega}{k_{\parallel}} \ll V_{te}$$

Fluid ions
(ions don't move much along field line)

Wave phase speed

Kinetic electrons
⇒ adiabatic (Boltzmann) response

+ $i\delta$ small non-adiabatic part (collisions, trapped particles can't flow along field line...)

$$\frac{\partial n_i}{\partial t} + \nabla \cdot (n_i \underline{v}_E) = 0$$

+

Quasineutrality

$$\tilde{n}_i = \tilde{n}_e = n_{e0} \frac{e\tilde{\Phi}}{T_e} (1+i\delta)$$

$$\underline{v}_E = \frac{c}{B^2} \underline{E} \times \underline{B} = \frac{c}{B} \hat{b} \times \nabla \tilde{\Phi}$$

$$n_i = n_0 + \tilde{n}_i$$

$$\frac{\partial \tilde{n}_i}{\partial t} + \underline{v}_E \cdot \nabla (n_0 + \tilde{n}_i) + (n_0 + \tilde{n}_i) \underbrace{\nabla \cdot \underline{v}_E}_{=0} = 0$$

$$\frac{c}{B} \nabla \cdot [\hat{b} \times \nabla \tilde{\Phi}] = 0 \quad \text{in slab} \quad (\hat{b} = \hat{z})$$

$$\underline{v}_E \cdot \nabla n_0 = \frac{c}{B} \hat{b} \times \nabla \tilde{\Phi} \cdot (-\hat{x} \frac{n_0}{L_n})$$

$$= i \frac{c T_e k_B}{e B} \frac{1}{L_n} \frac{e \tilde{\Phi}}{T_e} n_0$$

$\omega_{fe} \equiv$

$$-i\omega(1+i\delta) \frac{e\tilde{\Phi}}{T_e} + i\omega_{xe} \frac{e\tilde{\Phi}}{T_e} + \underline{v}_E \cdot \nabla \left[\frac{e\tilde{\Phi}}{T_e} (1+i\delta) \right] = 0$$

Linear $\omega = \frac{\omega_{xe}}{1+i\delta} \approx \omega_{xe}(1-i\delta)$

Unstable if $\omega_{xe}\delta < 0$

$\delta = \delta_0 k_y$ in some models.

$\omega_{xe}\delta \propto k_y^2$ independent of $\text{Sign}(k_y)$.

Stability depends on $\text{Sign}(\delta_0)$.

$\gamma \propto k_y^2 \Rightarrow$ Fastest growing mode at highest k_y (Usually cut off by FLR at $k_y p \sim 1$)

Nonlinear term:

$$\underline{v}_E \cdot \nabla \left[(1+i\delta) \frac{e\tilde{\Phi}}{T_e} \right]$$

$$= \underline{v}_E \cdot \nabla \left[\left(1 + \delta_0 \frac{\partial}{\partial y} \right) \frac{e\tilde{\Phi}}{T_e} \right]$$

$$= \frac{c}{B} \hat{b} \times \nabla \tilde{\Phi} \cdot \nabla \left[\frac{e\tilde{\Phi}}{T_e} + \delta_0 \frac{\partial}{\partial y} \frac{e\tilde{\Phi}}{T_e} \right]$$

$\underbrace{\qquad\qquad}_{=0}$

Only surviving nonlinearity
is from $i\delta$, unless FLR
corrections kept...

Gyrokinetic Ordering for Nonlinear Plasma Turbulence

Frieman & Chen
Phys. Fluids 25, 502 (1982)

$$\frac{\omega}{\Omega} \sim \frac{f_L}{\Omega} \sim \frac{k_{\parallel} v_t}{\Omega} \sim \frac{\tilde{F}_1}{F_0} \sim \frac{e\tilde{\Phi}}{T} \sim \frac{|SB|}{B} \sim \epsilon \ll 1$$

$k_{\perp} \rho \sim 1$ "Maximal ordering" (small $k_{\perp} \rho$ sometimes)
FLR effects important

$L \rightarrow$ equilibrium scale length, $\omega, k_{\parallel}, k_{\perp} \rightarrow$ time & space scales of perturbations

If perturbations are small, how can there be nonlinearities?

$$\frac{\partial F}{\partial t} + (\hat{v}_{\parallel} \hat{b} + \underline{v}_{\perp}) \cdot \nabla F + \frac{e}{m} E_{\parallel} \frac{\partial F}{\partial v_{\parallel}} = 0$$

$$F = F_0(\underline{x}, \underline{v}) + \tilde{F}_1(\underline{x}, \underline{v}, t)$$

equilibrium + perturbation

$$\underline{v}_{\perp} = \frac{c}{B} (\underline{E} \times \hat{b})$$

$$\frac{\partial F_0}{\partial t} = 0 \quad \hat{b} \cdot \nabla F_0 = 0$$

$$\frac{\partial \tilde{F}_1}{\partial t} + \hat{v}_{\parallel} \hat{b} \cdot \nabla \tilde{F}_1 + \underline{v}_{\perp} \cdot \nabla (F_0 + \tilde{F}_1) + \frac{e}{m} E_{\parallel} \frac{\partial}{\partial v_{\parallel}} (F_0 + \tilde{F}_1) = 0$$

$$\begin{aligned} \sim \omega F_1 & \sim k_{\parallel} v_t F_1 \\ & \sim \omega F_1 \end{aligned}$$

Nonlinear
Can we ignore this \tilde{F}_1 compared to F_0 ?

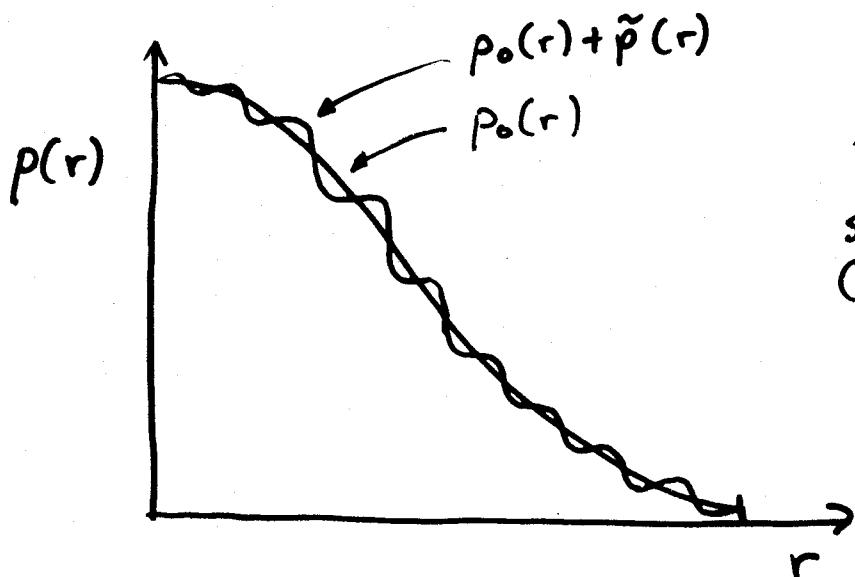
(No...) —

Aside: The ordering above simplifies equations (fluid &/or kinetic) for many types of plasma turbulence. Not just used to derive the Gyrokinetic Eq. Ordering motivated by experiments & years of theoretical analysis of various instabilities.

Though $\frac{F_1}{F_0} \sim \epsilon \ll 1$

$$\frac{\nabla F_1}{\nabla F_0} \sim \frac{k_{\perp} F_1}{\frac{1}{L} F_0} \sim k_{\perp} L \frac{F_1}{F_0} \sim k_{\perp} \rho \frac{L}{\rho} \frac{F_1}{F_0} \sim 1$$

$\downarrow \quad \downarrow \quad \downarrow$
 $\sim 1 \quad \sim \frac{1}{\epsilon} \quad \sim \epsilon$



Perturbations have
small amplitude, but
short wavelength
(sharp gradients).

$E \times B$ nonlinearity is the same order as linear terms.

$$\nabla_{\perp} F_1 \sim \nabla_{\perp} F_0$$

linear $E \times B$ term: $\underline{v}_E \cdot \nabla F_0 \sim \frac{c}{B} E_{\perp} \frac{F_0}{L_n} \sim \frac{c\Phi}{B} \frac{k_{\perp}}{L_n} F_0$

$$\sim \frac{e\Phi}{T} \frac{cT}{eB} \frac{k_{\perp}}{L_n} F_0 \sim \epsilon \omega_* F_0 \\ \sim \omega_* F_0$$

$$(\Rightarrow \omega \sim \omega_*)$$

"Parallel" nonlinearity usually ignored assuming $\frac{\partial \tilde{F}_1}{\partial V_{||}} \ll \frac{\partial \tilde{F}_0}{\partial V_{||}}$

Here " \sim " doesn't mean "close", but merely the same order in an ϵ expansion. I.e., $10 \epsilon \sim \frac{1}{2} \epsilon$

Large $k_{\perp}L \gg 1$ also means magnetic nonlinearities are included in the gyrokinetic ordering:

$$\hat{\underline{b}} = \frac{\underline{B}}{|\underline{B}|} = \frac{\underline{B}_0 + \delta\underline{B}_{\perp}}{|\underline{B}|} \quad |\hat{\underline{b}}_1| \sim \epsilon$$

$$= \hat{\underline{b}}_0 + \hat{\underline{b}}_1$$

$$v_{\parallel} \hat{\underline{b}}_1 \cdot \nabla \tilde{F}_i \sim v_{\parallel} \epsilon k_{\perp} \tilde{F}_i \sim v_{\parallel} k_{\parallel} \tilde{F}_i \sim \omega \tilde{F}_i$$

(other magnetic nonlinearities also...)

The gyrokinetic ordering includes the "Reduced MHD" ordering (MHD minus the fast compressional Alfvén wave, while retaining the shear Alfvén wave).

$\omega \sim k_{\parallel} v_A$ Shear Alfvén

$$\frac{\omega}{\Omega} \sim \frac{k_{\parallel} v_A}{\Omega} \sim \frac{k_{\parallel} v_{ci}}{\Omega} \frac{v_A}{v_{ci}}$$

homework
⇒

$$\sim \epsilon \frac{1}{\sqrt{\beta_i/2}}$$

Satisfies gyrokinetics
(β isn't necessarily an expansion parameter...)

$\omega \sim |k_{\parallel}| v_A$ Compressional Alfvén

$$\frac{\omega}{\Omega} \sim \frac{k_{\parallel} v_A}{\Omega} \sim 1 \quad \left(\frac{k_{\parallel}}{k_{\parallel}} \sim \frac{1}{\epsilon} \right)$$

A modified form of gyrokinetics might be able to keep long wavelength $k_{\parallel} \rho \ll 1$ compressional Alfvén waves while still allowing $k_{\parallel} \rho \sim 1$ for drift-like modes?

Compare with MHD / drift Orderings:

$$\frac{\omega}{\Omega} \sim \frac{f}{L} \sim \rho h \sim \mathcal{O}(\epsilon)$$

$$\frac{F_1}{F_0} \sim \frac{V_{EXB}}{V_t} \sim \frac{\delta B}{B} \sim \mathcal{O}(1)$$

$$\frac{\partial F}{\partial t} \sim \omega F \quad \nabla F \sim \frac{F}{L}$$

But this ordering misses drift waves!

$$\frac{\omega_*}{\Omega} \sim \frac{cT}{eB} \frac{k_y}{L} \sim \frac{V_t^2}{\Omega^2} \frac{1}{L^2} \sim \frac{f^2}{L^2} \sim \mathcal{O}(\epsilon^2)$$

Would have to work to higher order in ϵ
(but could only get FLR $k_\perp^2 \rho^2$ effects perturbatively)

MHD waves okay (of course):

$$\frac{\omega}{\Omega} \sim \frac{k_\perp V_A}{\Omega} \sim \frac{k_\perp V_t}{\Omega \sqrt{\beta}} \sim \frac{k_\perp \rho}{\sqrt{\beta}} \sim \mathcal{O}(\epsilon)$$

Collisionless MHD + Drift Kinetic Eq.
 Ref #2 & 3
 Varenna '63

Kulsrud's Collisionless MHD
 f

Summary

In this ordering, the Vlasov equation reduces to a condition on the zeroth-order parallel (relative to the magnetic field) electric field $E_{\parallel 0} = 0$, and the following kinetic equation for the zeroth-order distribution function of each species $f_{0,s}(v_{\parallel}, \mu, \mathbf{r}, t)$:

$$\frac{\partial f_{0,s}}{\partial t} + (v_{\parallel} \hat{\mathbf{b}} + \mathbf{v}_E) \cdot \nabla f_{0,s} + \left(-\hat{\mathbf{b}} \cdot \frac{D \mathbf{v}_E}{Dt} - \mu \hat{\mathbf{b}} \cdot \nabla B + \frac{e_s}{m_s} E_{\parallel} \right) f_{0,s} = 0, \quad (1)$$

where e_s is the charge on species s , $\hat{\mathbf{b}}$ is a unit vector in the magnetic field direction $\hat{\mathbf{b}} = \mathbf{B}/B$, $\mathbf{v}_E = c(\mathbf{E} \times \mathbf{B})/B^2$, $\mu = v_{\perp}^2/2B$, and $D/Dt = \partial/\partial t + (v_{\parallel} \hat{\mathbf{b}} + \mathbf{v}_E) \cdot \nabla$.

Combining moments of this kinetic equation with Maxwell's equations and taking the usual low Alfvén speed limit $v_A^2 \ll c^2$ yields Kulsrud's set of collisionless MHD equations:

$$\frac{\partial \rho}{\partial t} + \nabla \cdot (\rho \mathbf{U}) = 0, \quad (2)$$

$$\rho \left(\frac{\partial \mathbf{U}}{\partial t} + \mathbf{U} \cdot \nabla \mathbf{U} \right) = \frac{(\nabla \times \mathbf{B}) \times \mathbf{B}}{4\pi} - \nabla \cdot \mathbf{P}, \quad (3)$$

$$\frac{\partial \mathbf{B}}{\partial t} = \nabla \times (\mathbf{U} \times \mathbf{B}), \quad (4)$$

$$\mathbf{P} = p_{\perp} \mathbf{I} + (p_{\parallel} - p_{\perp}) \hat{\mathbf{b}} \hat{\mathbf{b}}, \quad (5)$$

$$p_{\perp} = \sum_s \frac{m_s}{2} \int f_{0,s} v_{\perp}^2 d^3 v, \quad (6)$$

$$p_{\parallel} = \sum_s m_s \int f_{0,s} (v_{\parallel} - \mathbf{U} \cdot \hat{\mathbf{b}})^2 d^3 v, \quad (7)$$

$$\sum_s e_s \int f_{0,s} d^3 v = 0, \quad (8)$$

where ρ is the total mass density, $\mathbf{U} = \mathbf{v}_E + u_{\parallel} \hat{\mathbf{b}}$ is the fluid velocity, and \mathbf{P} is the pressure tensor.

The above set of equations is exact to zeroth order in the expansion parameter, but the kinetic equation itself, Eq. (1), must be used to evaluate p_{\parallel} and p_{\perp} to close the system. Because Eq. (1) is difficult to solve directly, this system is rarely employed without further simplification.

lem, it is necessary to introduce an additional ordering which removes the compressional Alfvén time scale.

Another complication is the evaluation of the $|k_{\parallel}|/k_{\parallel}$ terms found in the Landau closures. As pointed out by Finn and Gerwin,¹⁸ the Landau damping must be evaluated along perturbed field lines. Hence, for nonlinear calculations, transforming the closure to real space requires an integral along the perturbed field line. The numerical evaluation of these nonlinear closures may be burdensome in some cases, as discussed in Sec. VII.

It is anticipated that the model will be useful for nonlinear numerical simulations. Some of the caveats involved in using Landau closures in nonlinear simulations have been extensively discussed in the gyrofluid literature,^{11,12,23,24,26-30} but these caveats are an area of ongoing research. There are some regimes where certain nonlinear kinetic effects are not well modeled by Landau-fluid closures.³⁰ But we generally believe^{12,24,27,28} these closures will be adequate for stronger turbulence regimes where rapid decorrelation is occurring and the velocity space details of the distribution function are not critically important.

It is hoped that the model will prove useful for simulating both laboratory and astrophysical plasmas in the collisionless MHD regime. The model should be able to predict the onset and structure of instabilities, as well as the heat and particle transport caused by the instabilities.

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by the Numerical Tokamak Turbulence Project, part of the DoE High Performance Computing and Communications Initiative.

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Kulsrud Refs.

Caution: Gyrokinetic ordering may break down
(or may need extension) near the plasma
edge where

$$\frac{e\tilde{\Phi}}{T} \sim 1$$

$$\frac{\rho}{L} \sim \rho \frac{\nabla n}{n} \sim 1$$

(Perhaps can include $\frac{e\tilde{\Phi}}{T} \sim 1$ as long as $k_{\perp}p \ll 1$?)

i.e., $\underline{V}\underline{E} \propto \nabla_{\perp}\tilde{\Phi}$ is the relevant quantity...)

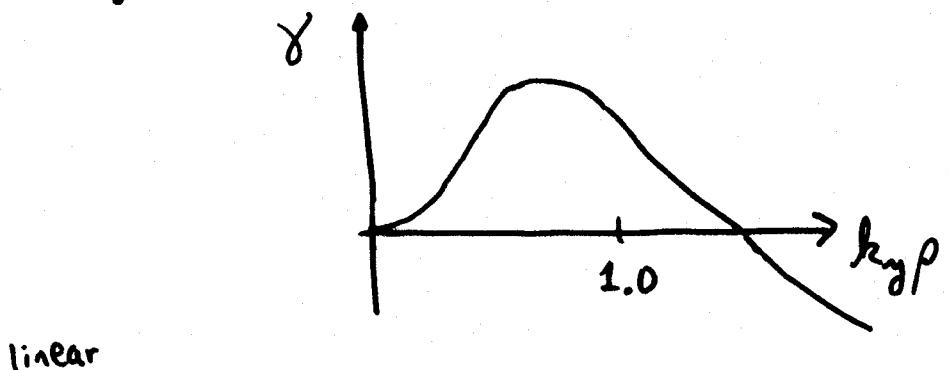
FLR effects

FLR = Finite Larmor (gyro) Radius $\Rightarrow k_{\perp p} > 0$

* \Rightarrow Popular Forms...

$$\omega \sim \omega_{*e} = \frac{cT_e}{eB} \frac{k_y}{L_n} \sim \frac{m_i c}{eB} \frac{T_e}{m_i} \frac{k_y}{L_n} \sim \frac{c_s}{L_n} k_y \rho_s$$

Often, $\gamma \propto \omega_{*e}$, so the fastest growing mode has the largest k_y . FLR provides cutoff.



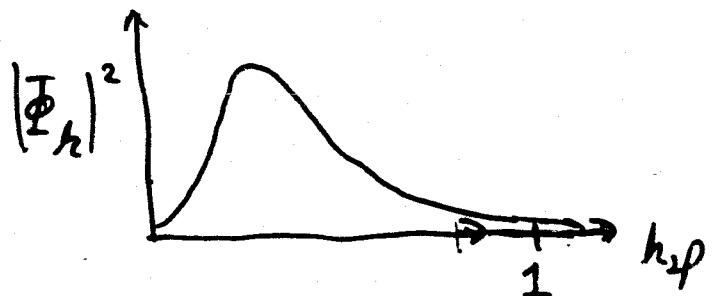
linear

- * Fastest growing mode is not necessarily going to dominate in the nonlinear state.
- * Indeed, BES + p-wave scattering on TFTR indicate $k_{\perp p} \sim .1 - .3 \ll 1$

Speculations::

- * Even at $k_{\perp p} \ll 1$, residual FLR plays important roles in driving instabilities + nonlinearities.
- * Also, damped modes at $k_{\perp p} > 1$ may be an important sink of energy in nonlinear simulations, even if not dominant in the spectrum?

(Actually, lots of ion Landau damping at high $k_{\parallel i}$, ($k_{\parallel i} v_i > \omega_*$), not just high $k_{\perp i}$)



The Gyrokinetic Eq.

(Not as mysterious as you might think...)

$$\frac{\partial F_{gc}}{\partial t} + \nabla \cdot [F_{gc}(\mathbf{v}_{\parallel} \hat{\mathbf{b}} + \langle \mathbf{v}_E \rangle)] - \frac{\partial}{\partial v_{\parallel}} \left[F_{gc} \frac{e}{m} \hat{\mathbf{b}} \cdot \nabla \langle \Phi \rangle \right] = 0$$

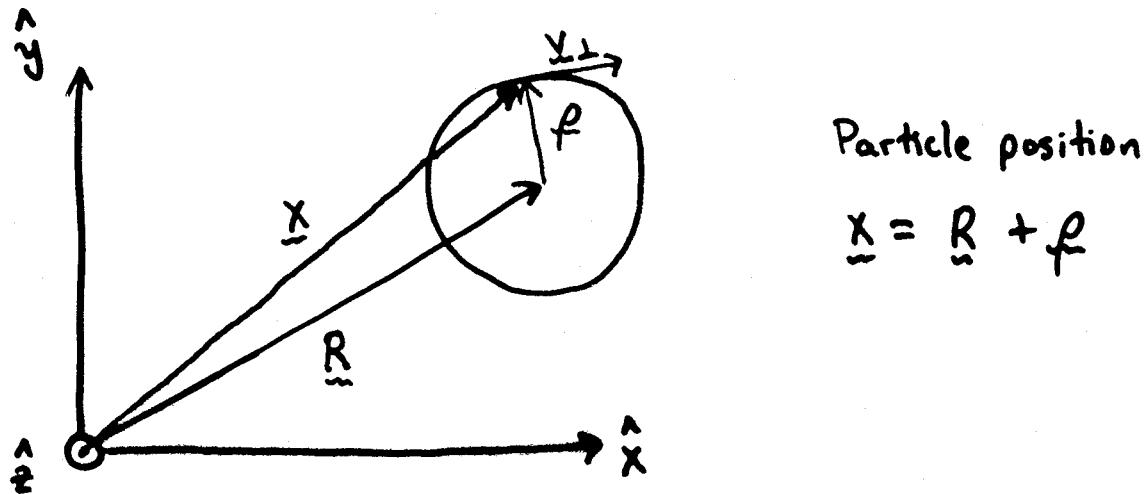
Parallel
flow

$\underline{E} \times \underline{B}$
(Gyroaveraged)

Parallel
Acceleration
(Gyro averaged)

Conservation Eq. for $F_{gc}(\underline{R}, v_{\parallel}, v_{\perp}, t)$,
the density of particles with guiding centers
at position \underline{R} , with velocities v_{\parallel} & v_{\perp} .

$$n_{gc}(\underline{R}) = \int d^3v F_{gc} \neq \text{particle density } n$$



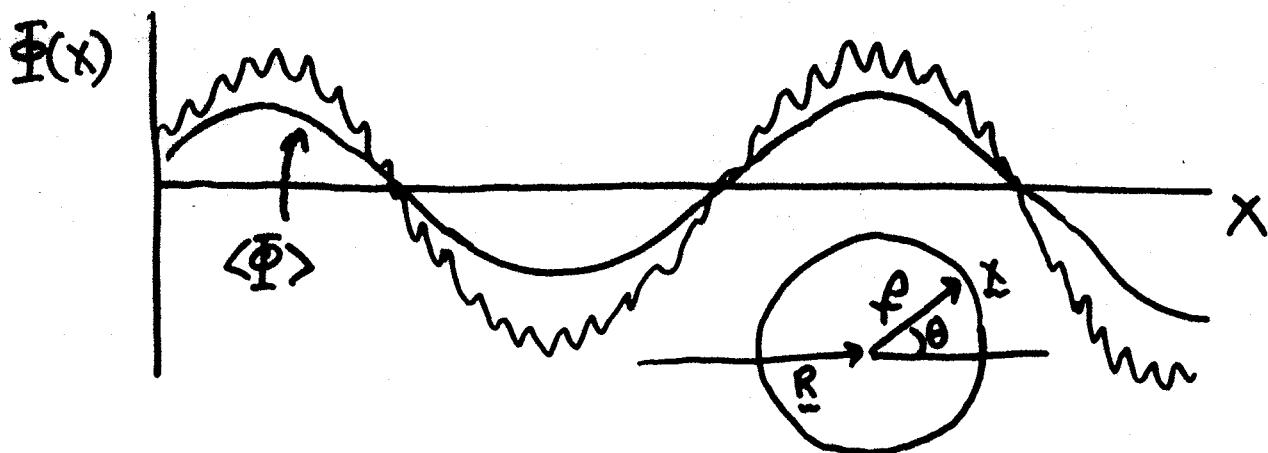
The above GKE is for slab geometry (\underline{B} straight, may be sheared) for electrostatic perturbations only. General geometry + $S\underline{B}_{\perp}$ GKE exists. Tomorrow: + toroidal ITG...

Gyro averaging

Particles respond to the gyro-orbit-averaged

$$\langle \underline{v}_E \rangle = \frac{e}{B} \hat{b} \times \nabla \langle \Phi \rangle.$$

⇒ Smooths out high $k_{\perp} p$ components:



$$\Phi(\underline{x}) = \sum_k \Phi_k e^{i \underline{k} \cdot \underline{x}} \quad \underline{x} = \underline{R} + \underline{r}(\theta)$$

$$\text{Gyro-average: } \langle \Phi \rangle = \frac{1}{2\pi} \int d\theta \Phi(\underline{R} + \underline{r}(\theta))$$

$$= \sum_k \Phi_k \frac{1}{2\pi} \int d\theta e^{i \underline{k} \cdot (\underline{R} + \underline{r}(\theta))}$$

$$= \underbrace{\sum_k \Phi_k e^{i \underline{k} \cdot \underline{R}}}_{= \Phi(\underline{R})} \underbrace{\frac{1}{2\pi} \int d\theta e^{i k_{\perp} p \cos\theta}}_{\equiv J_0(k_{\perp} p)}$$

Bessel Function

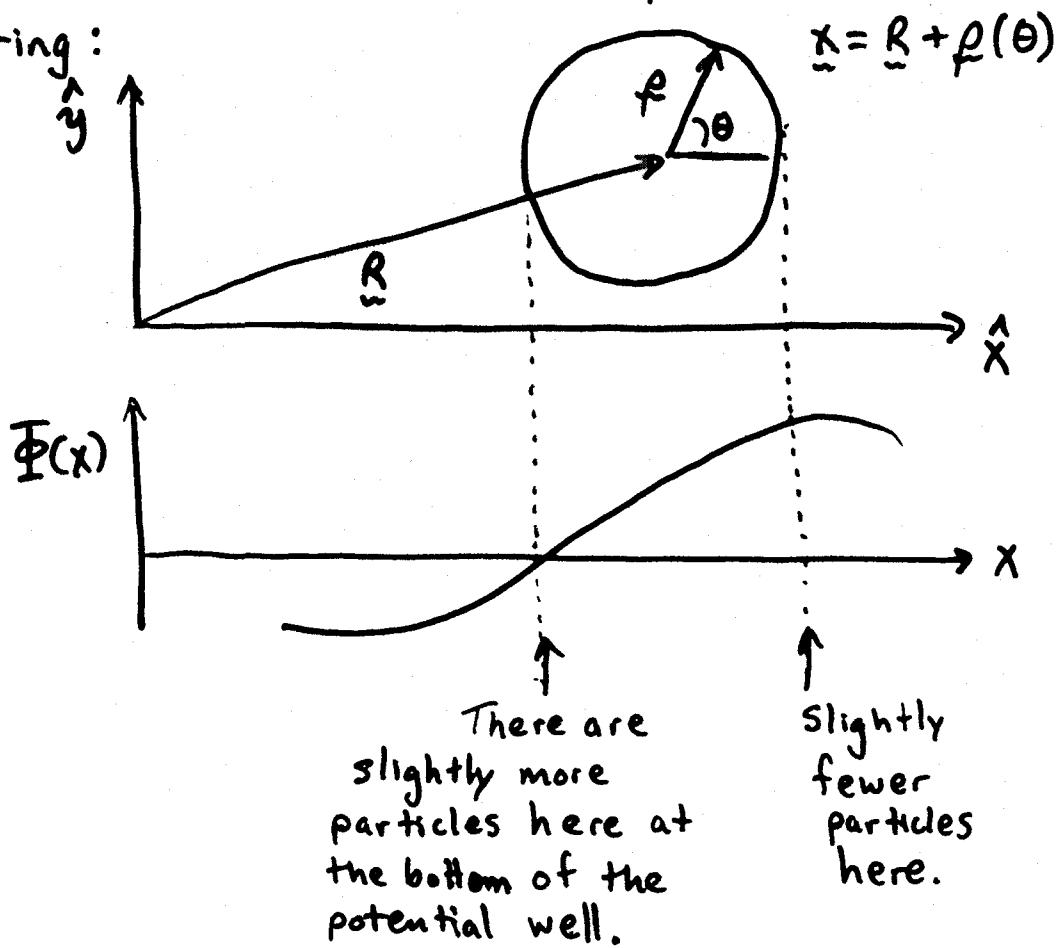
$$\begin{aligned}
 J_0(k_1\rho) &= \frac{1}{2\pi} \int d\theta e^{ik_1\rho \cos\theta} \\
 &\approx \frac{1}{2\pi} \int d\theta \left[1 + ik_1\rho \cos\theta - \frac{k_1^2\rho^2}{2} \cos^2\theta + \dots \right] \\
 &= 1 + 0 - \frac{k_1^2\rho^2}{4} \\
 &\Rightarrow 1 + \frac{\rho^2}{4} \nabla_{\perp}^2
 \end{aligned}$$

$$\begin{aligned}
 \langle \Phi \rangle &\approx \left(1 + \frac{\rho^2}{4} \nabla_{\perp}^2 \right) \Phi \\
 &\approx \left(1 - \frac{\rho^2}{4} k_{\perp}^2 \right) \Phi \\
 &\equiv J_0 \Phi
 \end{aligned}$$

Think of J_0 as an operator, like in quantum mechanics, which happens to have a simple form in k space.

Surprise: Particles are not uniformly distributed around the gyro-orbit.

There is a correction due to the variation of Φ around the orbit. Since $\omega \ll \Omega$, the particles set up an adiabatic (Boltzmann) response around the gyro-ring:



$$F_{\text{TOT}}(R, v_u, v_\perp, \theta, t) = F_{\text{gc}}(R, v_u, v_\perp, t)$$

$$-F_0(R, v_u, v_\perp) \left[\frac{e\Phi}{T} - \frac{e\langle\Phi\rangle}{T} \right]$$

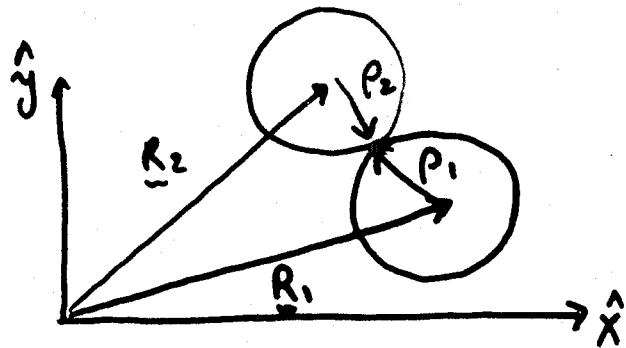
Evaluate at
 $x = R + \rho(\theta)$

Averaged over
 θ at fixed R .

Guiding-center density \neq Particle density.

$$\underline{x} = \underline{R} + \underline{f}(\theta)$$

$$\underline{R} = \underline{x} - \underline{f}(\theta)$$



Two particles at the same \underline{x} ,
but different \underline{R} .

$f(\underline{x}, \underline{v})$ = particle distribution function

$$= F_{\text{TOT}} \left(\underbrace{\underline{x} - \underline{f}(\theta)}_{\underline{R}}, v_{||}, v_{\perp}, \theta \right)$$

$$= F_{\text{gc}}(\underline{x} - \underline{f}(\theta), v_{||}, v_{\perp}) - F_0(\underline{x} - \underline{f}(\theta), v_{||}, v_{\perp}) \left[\frac{e\Phi(\underline{x})}{T} - \frac{e\langle\Phi\rangle}{T} \right]$$

↑
evaluate
at $\underline{R} = \underline{x} - \underline{f}$

$$n(\underline{x}) = \int d^3v \Big|_{\underline{x}} f = \bar{n} + n_{\text{pol}}$$

$$\bar{n} = \int dv_{||} \int dv_{\perp} v_{\perp} \int d\theta \sum_k F_{\text{gc}, k}(\underline{v}_{||}, \underline{v}_{\perp}) e^{i \underline{k} \cdot (\underline{x} - \underline{f}(\theta))}$$

$$= \underbrace{\int dv_{||} \int dv_{\perp} v_{\perp} 2\pi}_{d^3v} \sum_k F_{\text{gc}, k}(\underline{v}_{||}, \underline{v}_{\perp}) e^{i \underline{k} \cdot \underline{x}} \underbrace{\frac{1}{2\pi} \int d\theta e^{-i \underline{k} \cdot \underline{f}(\theta)}}_{= J_0(k_{\perp} \rho)}!$$

$$\bar{n} = \int d^3v J_0 F_{gc}(\underline{x}, v_u, v_\perp) \approx \int d^3v (1 + \frac{e^2}{4} \nabla_\perp^2) F_{gc}$$

$$n_{pol} = - \int d^3v F_0(\underline{x} - \rho(\theta), v_u, v_\perp) \left[\frac{e\Phi(\underline{x})}{T} - \frac{e\langle\Phi\rangle}{T} \right] \Big|_{R=\underline{x}-\rho}$$

(brace under the previous equation)

$$\approx F_0(\underline{x}, v_u, v_\perp) - \rho \cdot \frac{\partial F_0}{\partial \underline{x}} \quad \begin{matrix} \uparrow \\ \sim \frac{\rho}{k_B T} F_0 \end{matrix} \quad \begin{matrix} \text{ignore} \\ \langle \Phi \rangle \end{matrix}$$

$$\langle \Phi \rangle \Big|_{R=\underline{x}-\rho} = \sum_k \Phi_{\frac{k}{\lambda}} e^{i \frac{k}{\lambda} \cdot (\underline{x} - \rho(\theta))} J_0(k \lambda \rho)$$

$$n_{pol} = -n_0 \frac{e\Phi(\underline{x})}{T} + \sum_k \Phi_{\frac{k}{\lambda}} e^{i \frac{k}{\lambda} \cdot \underline{x}} \underbrace{\int d^3v F_0 e^{-i \frac{k}{\lambda} \cdot \rho(\theta)} J_0(k \lambda \rho)}$$

1 Bessel Function from
 $\Phi(\underline{x}) \rightarrow \langle \Phi \rangle(R)$

$$\int d^3v F_0 J_0 \frac{1}{2\pi} \int d\theta e^{-ik \lambda \rho \cos\theta}$$

$$\int d^3v F_0 J_0^2$$

$$n_0 \Gamma_0(k \lambda \rho^2)$$

*1 Bessel Function from
 $F(R) \rightarrow \langle F \rangle(\underline{x})$

$$n = \text{particle density}$$

$$= \bar{n} + n_{\text{pol}}$$

$$n = \int d^3v J_0 F_{gc} - n_0 (1 - \Gamma_0) \frac{e\Phi}{T}$$

Useful I.Q.'s: $b = k_L^2 \rho_t^2 = k_L^2 \frac{T_i}{m_i \Omega_{ci}^2}$

$$\Gamma_0(b) = e^{-b} I_0(b) = e^{-b} J_0(ib)$$

$$\approx 1 - b \approx 1 - k_L^2 \rho_t^2 = 1 + \rho_t^2 \nabla_L^2$$

Ion particle density in the cold ion limit ($T_i \rightarrow 0, k_L^2 \rho_i^2 \rightarrow 0$):

$$n_i = \int d^3v F_{gc} - n_0 [1 - (1 - k_L^2 \rho_i^2)] \frac{e\Phi}{T_i}$$

$$= n_{gc} - n_0 k_L^2 \rho_i^2 \underbrace{\frac{e\Phi}{T_i}}$$

independent of T_i !
Survives the $T_i \rightarrow 0$ limit.

$$n_i = n_{gc} - n_0 k_L^2 \rho_s^2 \frac{e\Phi}{T_e}$$

$$\rho_s^2 = \frac{C_S^2}{\Omega_{ci}^2} = \frac{T_e/m_i}{\Omega_{ci}^2}$$

Combine with adiabatic electron response
in quasineutrality condition :

$$\tilde{n}_e = \tilde{n}_i$$

$$n_{eo} \frac{e\tilde{\Phi}}{T_e} (1+i\delta) = \tilde{n}_{gc} - n_0 k_\perp^2 \rho_s^2 \frac{e\tilde{\Phi}}{T_e}$$

$$\frac{e\tilde{\Phi}}{T_e} = \frac{\tilde{n}_{gc}/n_0}{1+i\delta + k_\perp^2 \rho_s^2}$$

Provides "filtering" at
high $k_\perp^2 \rho_s^2$, even with $k_\perp^2 \rho_i^2 \rightarrow 0$.

(Most tokamaks have $T_i \sim T_e$, so
 $k_\perp^2 \rho_i^2$ effects similar in size to
 $k_\perp^2 \rho_s^2$. Supershots & hot ion modes
have $T_i/T_e \sim 3-4$.)

The Toroidal Gyrokinetic Eq.

$$\frac{\partial}{\partial t} (FB) + \nabla \cdot [FB(v_{||}\hat{b} + J_0 \underline{v}_E + \underline{v}_d)]$$

parallel flow: Gyro-avg. E \times B: ∇B \times Curvature Drifts:

$$+ \frac{\partial}{\partial v_{||}} \left[FB \left(-\frac{e}{m} \hat{b} \cdot \nabla J_0 \Phi - \nu \hat{b} \cdot \nabla B + v_{||} (\hat{b} \cdot \nabla \hat{b}) \cdot J_0 \underline{v}_E \right) \right]$$

$E_{||}$ force
(properly gyro-avg.)

Magnetic
Mirroring
Force

Acceleration to
conserve toroidal
angular momentum

$$= 0$$

($m v_{||} R = \text{constant}$
during toroidal adiabatic compression)

$$J_0 \underline{v}_E \approx \frac{c}{8} \hat{b} \times \nabla J_0 \Phi$$

$$\underline{v}_d \approx \frac{\hat{b} \times \nabla B}{B} \frac{\frac{1}{2} v_{\perp}^2 + v_{||}^2}{\Omega}$$

$$F = F_{gc}(R, v_{||}, \nu, t)$$

$$\nu = \frac{1}{2} \frac{v_{\perp}^2}{B}$$

$$n_{gc} = \int d^3v F_{gc} = 2\pi \int dv_{||} \int dp \ B F_{gc}$$

$$F_{TOT} = F_{gc} + F_{pol}$$

Quasineutrality condition: $\tilde{n}_e \approx \tilde{n}_i$

$$\tilde{n}_i = \int d^3v J_0 F_{gc} + n_o (\Gamma_o - 1) \frac{e \tilde{\Phi}}{T_i}$$

$$J_0 \approx 1 - \frac{h_{\perp}^2 \rho^2}{4}$$

$$\Gamma_o \approx 1 - h_{\perp}^2 \rho_{ti}^2 \approx \frac{1}{1 + h_{\perp}^2 \rho_{ci}^2} \text{ (better)}$$

n_{pol}

From component of F_{TOT} which has an adiabatic variation around the gyro-orbit

Nonlinear Gyrokinetic Eq. Refs.

Frieman & Chen, Phys. Fluids 25, 502 (1982)

First Nonlinear GK Eq. It's all there,
but somewhat complicated.

Others:

W. W. Lee, Phys. Fluids 26, 556 (1983)
" " , J. Comput. Phys. 72, 243 (1987)

Dubin, Krommes, et. al. Phys. Fluids 26, 3524 (1983).

More modern Approach:

Littlejohn, "Variational principles of guiding center motion", J. Plasma Physics 29, 111 (1983)

T. S. Hahm, Phys. Fluids 31, 2620 (1988)

^{1989 -}
1990's papers by Hahm, Brizard, + by Hong Qin.

Note: some of 1980's papers went to higher order
in ϵ expansion than needed.