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***ICTP-UNU-Microprocessor Laboratory
Fifth Course on Basic VLSI Design Techniques***

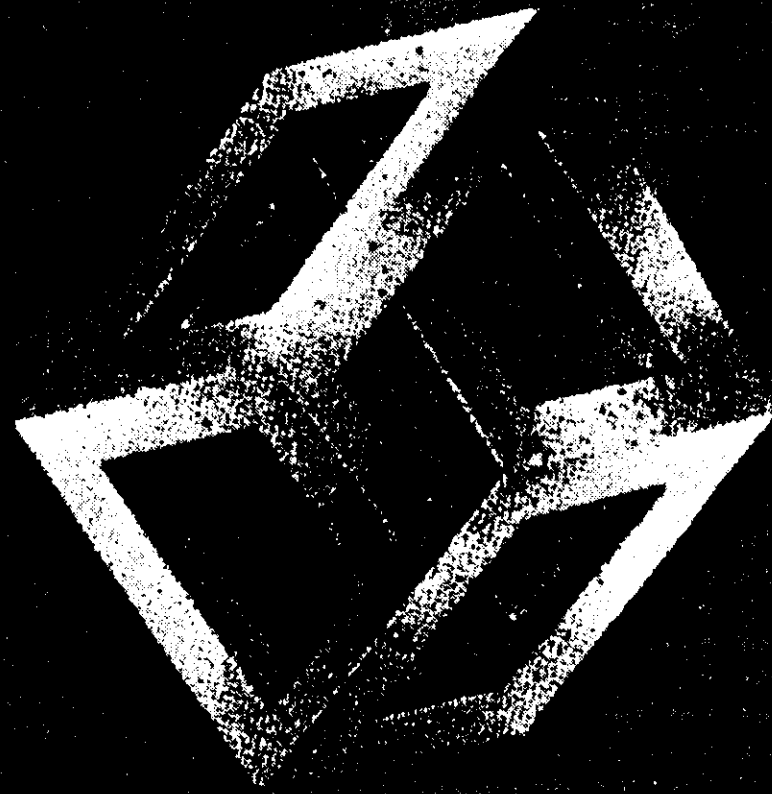
9 November - 4 December 1998

VHDL, ALLIANCE

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These are preliminary lecture notes intended only for distribution to participants

The ALLVANCE System



PAIC/IASI

1994

INTRODUCTION



ICTP/UNESCO

Trieste

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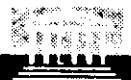
 : **Nizar.Abdallah@masi.ibp.fr**

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Paris

INTRODUCTION



ICTP-UNESCO
Tribes

OUTLINE

I - INTRODUCTION

II - DESIGN METHODOLOGY: AN OVERVIEW

III - ABSTRACTION LEVELS IN ALLIANCE

IV - VHDL: A HARDWARE DESCRIPTION LANGUAGE

V - VHDL: THE ALLIANCE SUBSET

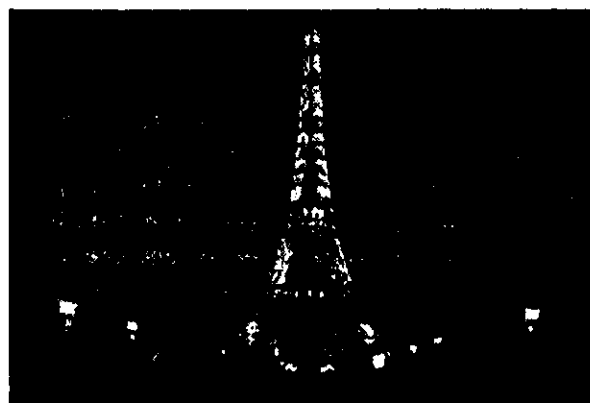
VI - ALLIANCE: A COMPLETE DESIGN SYSTEM

VII - TODAY'S CHALLENGES IN CAD TOOLS



THE MASI LABORATORY

UNIVERSITY PIERRE ET MARIE CURIE
NATIONAL CENTRE OF SCIENTIFIC RESEARCH



168 RESEARCHERS

ARCHITECTURE	59	NETWORKS & PERFORMANCES	30
DISTRIBUTED SYSTEMS	36	PARALLEL ALGORITHMS	17



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SLIDE 3

THE ARCHITECTURE GROUP

CAD FOR VLSI		ARCHITECTURE	
PORTABLE LIBRARIES	9	SUPERSCALAR PROCESSOR	5
VERIFICATION	7	RCUBE ROUTER	8
LOGIC SYNTHESIS	5	RAPID COPROCESSOR	6
ARCHITECTURE SYNTHESIS	4		
TEST	5		



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SLIDE 4

EDUCATION TARGET

- UNDERGRADUATE STUDENTS: (≈ 80 STUDENTS AND 72 HOURS)
 - ♦ ELECTRICAL ENGINEERING
 - ♦ COMPUTER SCIENCE
- POSTGRADUATE STUDENTS (≈ 60 STUDENTS AND 300 HOURS)
 - ♦ DEA MEMI
 - ♦ DESS CIMI



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SLIDE 5

THE ALLIANCE SYSTEM

- A COMPLETE SET OF CAD TOOLS FOR DIGITAL CMOS VLSI DESIGN.
- PROPOSES A DESIGN METHODOLOGY.
- PORTABLE, COMPACT AND EASY TO LEARN.
- ALLIANCE IS TOTALLY FREE.



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SLIDE 6

OUTLINE

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II - DESIGN METHODOLOGY: AN OVERVIEW.

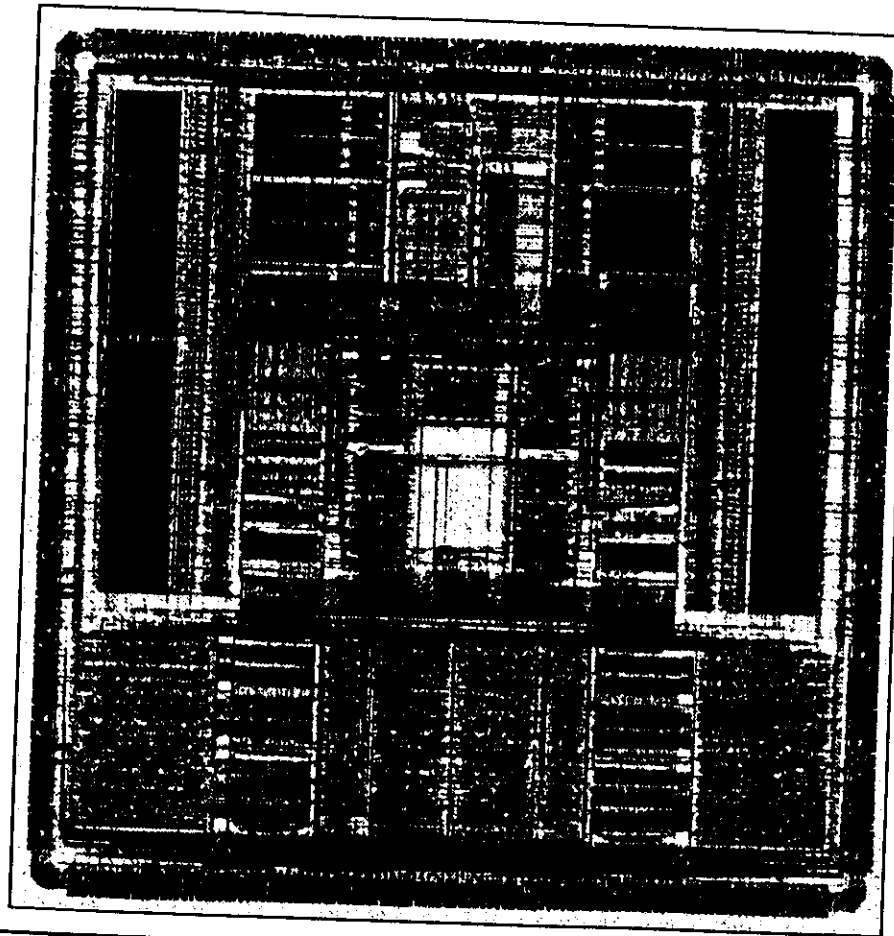
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VI - ALLIANCE: A COMPLETE DESIGN SYSTEM.



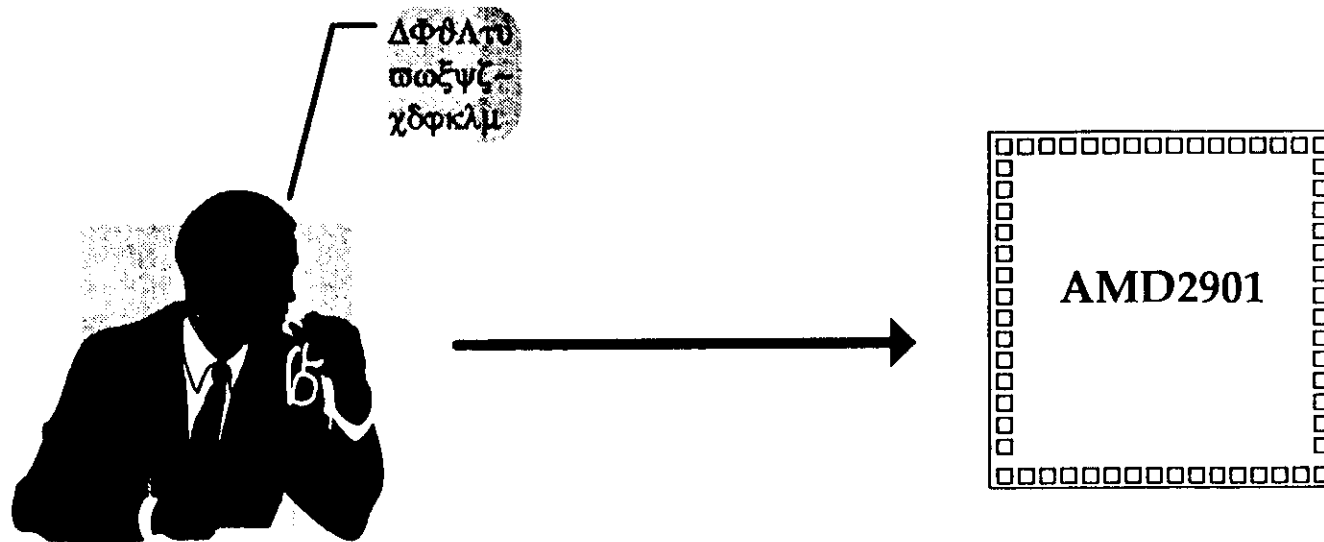


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SLIDE 2

DESIGNER'S DREAM

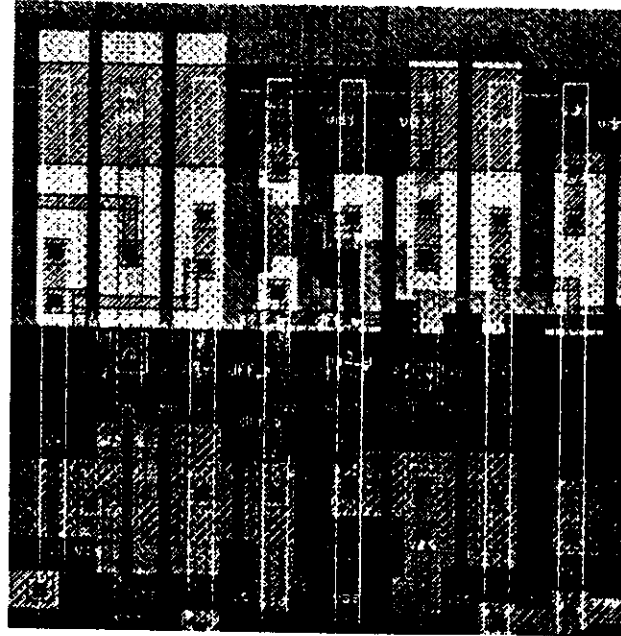


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SLIDE 3

MILLIONS OF SEGMENTS PUT TOGETHER.



HOW TO DEAL WITH SUCH COMPLEXITY ?

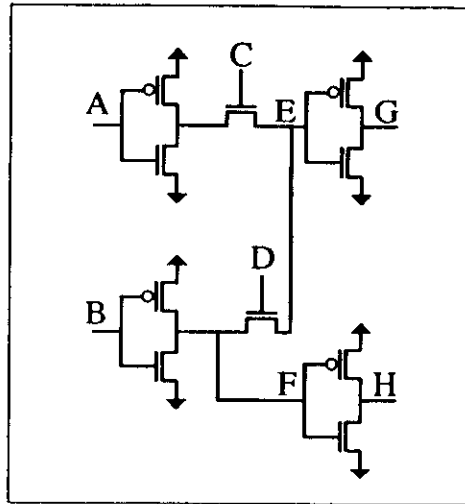


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SLIDE 4

ONE MILLION OF TRANSISTORS CONNECTED TOGETHER.



β **STILL TOO COMPLEX.....!!!**



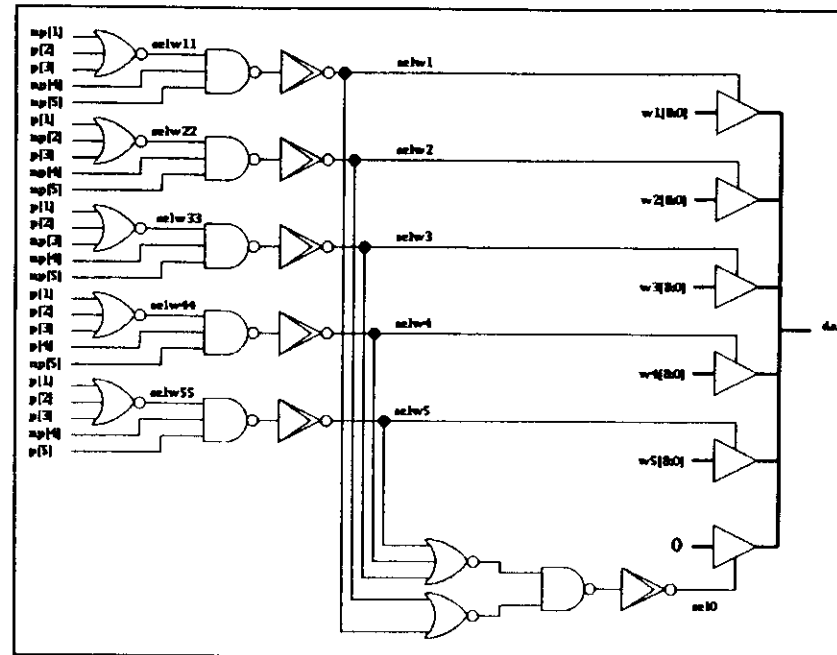
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SLIDE 5



HUNDRED THOUSAND OF CELLS CONNECTED TOGETHER.



x STILL TOO COMPLEX.....!!!



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SLIDE 6

DOZEN OF FUNCTIONAL BLOCKS THAT COMMUNICATE
TOGETHER.

✓ I UNDERSTAND (OUF !!!)



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SLIDE 7

A SET OF EQUATIONS THAT REFLECT THE WHOLE
FUNCTIONALITY OF THE CIRCUIT.

```
entity adder is
port (
    a, b: Bit;
    c, d : bit
);

architecture adder is

a <= b or c
d <= b and c;
end;
```

✓ I UNDERSTAND WHAT THIS CIRCUIT IS SUPPOSED TO DO.



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SLIDE 8

SO,

HOW TO DEAL WITH SUCH COMPLEXITY ?

✓ **ABSTRACTION**

✓ **HIERARCHY**



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SLIDE 9



LEVELS OF ABSTRACTION

TO GO ACROSS THESE DIFFERENT LEVELS OF ABSTRACTION

I NEED

A DESIGN METHODOLOGY



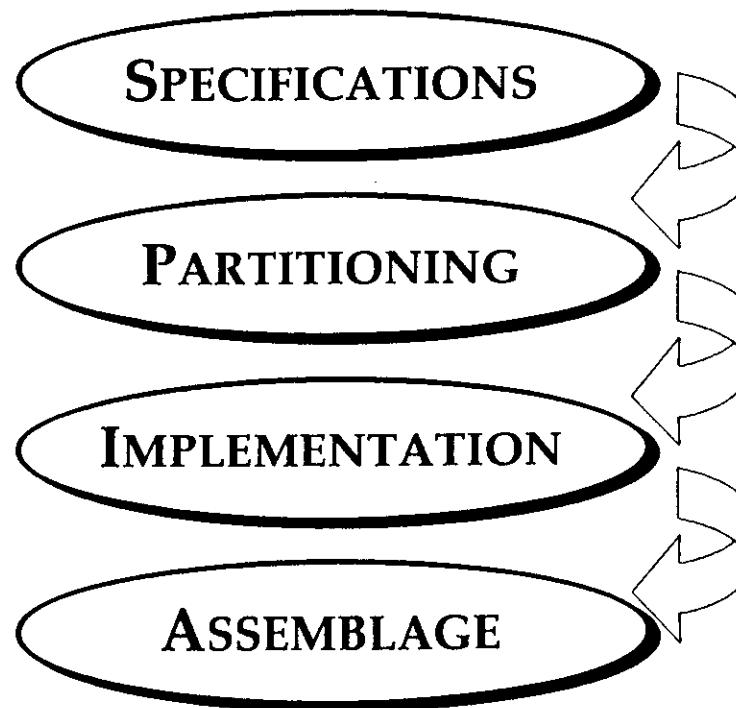
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SLIDE 10

DESIGN METHODOLOGY

TOP-DOWN METHODOLOGY



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SLIDE 11

STEP 1: SPECIFICATIONS (1)

PUT DOWN THE CIRCUIT CONCEPT.

TWO REASONS:

- TO BE ABLE TO CHECK IT BEFORE MANUFACTURING.
- TO HAVE A REFERENCE MANUAL FOR COMMUNICATION.



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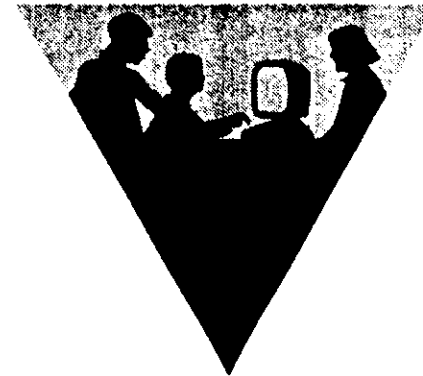
SLIDE 12

STEP 1: SPECIFICATIONS (2)

COMMUNICATION LANGUAGE.

BETWEEN DIFFERENT PEOPLE ON THE PROJECT AND BETWEEN PEOPLE AND COMPUTERS.

- ✗ NO ORDINARY LANGUAGE.
- ✓ ACCURATE LANGUAGE.
- ✓ A LANGUAGE THAT CAN BE SIMULATED.



STEP 2: HOW TO ?(1)

VERY DIFFICULT STEP: RELAYS ON THE KNOW-HOW OF THE DESIGNER.

MAIN IDEA: TO SPLIT INTO SEVERAL SMALL PARTS.

DIVIDE AND CONQUER STRATEGY.

HIERARCHY.



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SLIDE 14



STEP 2: HOW TO ? (2)

THE CUTTING IS GUIDED BY:

1. REGULARITY OR NOT.

- IDENTIFY REGULAR BLOCKS.
- IDENTIFY RANDOM LOGIC BLOCKS.



STEP 2: HOW TO ? (3)

THE CUTTING IS GUIDED BY:

2. TIMING ASPECTS.

- COARSE ESTIMATION OF TIMING.
- LOOKING FOR A GOOD BALANCE.



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STEP 2: HOW TO ? (4)

THE CUTTING IS GUIDED BY:

3. TOPOLOGY.

- ALREADY IN MIND THE CIRCUIT FORM.
- AN IDEA ABOUT THE SIZE OF EACH PART.
- AN IDEA ABOUT THE ROUTING.
- OPTIMIZING SILICON AREA USAGE.



STEP 2: HOW TO ? (5)

THE CUTTING IS GUIDED BY:

4. TECHNOLOGY.

- USING GAAS OR CMOS ?
- USING PALS OR STANDARD CELLS ?



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SLIDE 18

STEP 2: HOW TO ? (6)

THE CUTTING IS GUIDED BY:

5. CAD TOOLS.

- WHAT TOOLS DO I HAVE TO MAKE MY CIRCUIT ?

EX: NO SYNTHESIS TOOLS SO I TRY TO REDUCE THE RANDOM LOGIC PART.



STEP 3: IMPLEMENTATION

EACH PART WILL BE IMPLEMENTED USING A PARTICULAR METHOD. WHEN I SPLIT MY CIRCUIT, I HAVE ALREADY DECIDED WHICH ONE.



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SLIDE 20



STEP 4: ASSEMBLAGE

THE ASSEMBLAGE IS DONE IN A HIERARCHICAL WAY, STARTING FROM THE LOWEST LEVEL.



CONCLUSION (1)

AT EACH STEP, THE INFORMATION IS ENHANCED:

1. FROM THE IDEA DOWN TO THE SPECIFICATIONS.
2. WHEN STRUCTURING THE MODEL IN AN OTHER WAY.
3.

⇒ AT EACH STEP, A VERIFICATION IS TO BE DONE.



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CONCLUSION (2)

ALL ALONG THE METHODOLOGY, WE HANDLED DIFFERENT VIEWS:

1. EQUATIONS.
2. NETLISTS.
3. LAYOUT.



CONCLUSION (3)

T H E R E I S A M E T H O D.



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OUTLINE

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3 DIFFERENT VIEWS

ALL ALONG THE METHODOLOGY, WE HANDLED DIFFERENT VIEWS:

1. BEHAVIORAL VIEW (EQUATIONS).
2. STRUCTURAL VIEW (NETLISTS).
3. LAYOUT VIEW.



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SLIDE 2

BEHAVIORAL VIEW (1)

LOGICAL EQUATIONS

- DESCRIPTION FORMALISM.

A SET OF LOGICAL EQUATIONS (BOOLEAN) REPRESENTING
BOOLEAN FUNCTIONS.

EXAMPLE: $U = A.(A+B)$ $V = C.D$ $T = D \oplus E$

$X = U.V$ $Y = V + T + X$ $Z = T.E$



BEHAVIORAL VIEW (2)

LOGICAL EQUATIONS

- REPRESENTATION.

A DIRECTED ACYCLIC GRAPH INCLUDING THREE KINDS OF NODES: INPUT, INTERMEDIARY, OUTPUT.

EACH INTERMEDIARY OR OUTPUT NODE IS ASSOCIATED TO A LOGICAL EXPRESSION.

EACH NODE IS ASSOCIATED TO A VARIABLE NAME.



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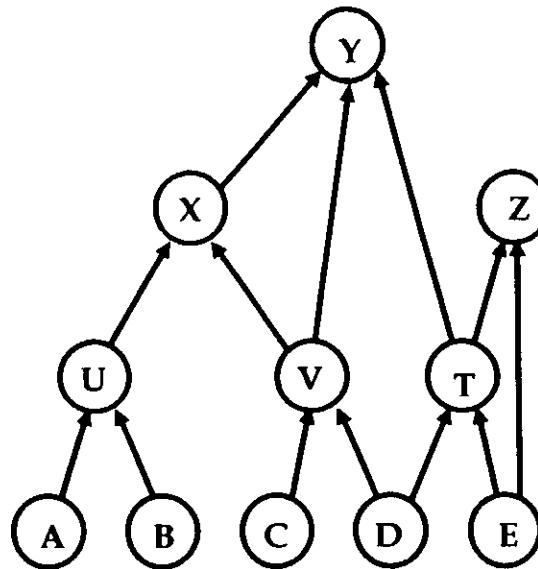
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SLIDE 4

BEHAVIORAL VIEW (3)

BOOLEAN NETWORK

- REPRESENTATION.



STRUCTURAL VIEW (1)

FOR ALL THESE VIEWS, WE ARE LOOKING FOR BASIC CONCEPTS:
COMPLETELY INDEPENDENT FROM A GIVEN LANGUAGE.

IN THE STRUCTURAL VIEW:

- CONNECTORS: ID, DIRECTION, ETC....
- SIGNALS: ID, TYPE (EXTERNAL OR NOT), ETC....
- INSTANCE: ID, MODEL NAME, PORTS, ETC....



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SLIDE 6

LAYOUT VIEW (1)

SYMBOLIC LAYOUT: PRINCIPLES

- PORTABILITY
- SIMPLICITY
- ROBUSTNESS



LAYOUT VIEW (2)

SYMBOLIC LAYOUT: OUR APPROACH

THIN FIXED GRID, SYMBOLIC LAYOUT.

DISTANCES FORM CENTER TO CENTER \Rightarrow GOOD DENSITIES.

SPECIAL SYMBOLIC LAYOUT EDITOR.

AUTOMATIC TRANSLATION FROM SYMBOLIC TO PHYSICAL.

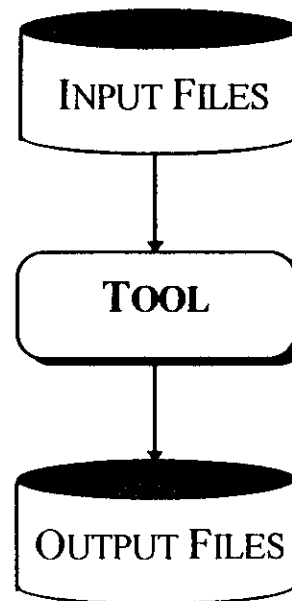


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SLIDE 8

HOW TO DEAL WITH THESE VIEWS ? (1)



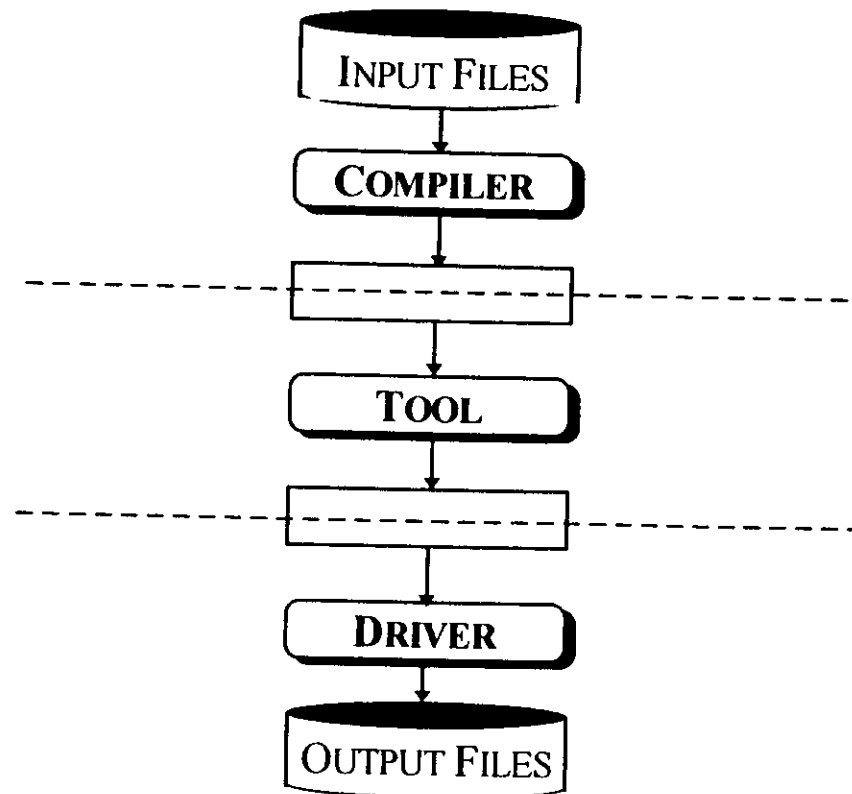
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SLIDE 9



HOW TO DEAL WITH THESE VIEWS ? (2)



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SLIDE 10

INDEPENDENCE (1)

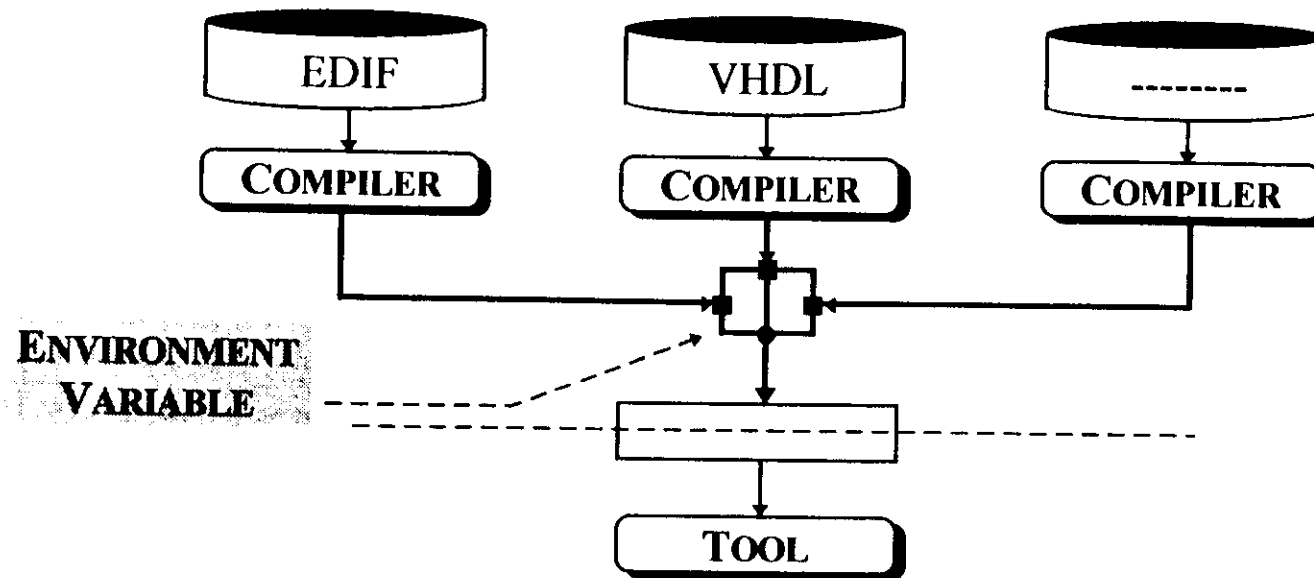
A MAJOR IDEA IN ALLIANCE IS ITS INDEPENDENCE FROM ANY GIVEN LANGUAGE.

IDENTIFY THE CONCEPTS THAT:

- ✗ DO NOT DEPEND ON A LANGUAGE.
- ✓ DEPENDS ON THE ABSTRACTION LEVEL.



INDEPENDENCE (2)



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SLIDE 12

OUTLINE

I - INTRODUCTION

II - DESIGN METHODOLOGY: AN OVERVIEW

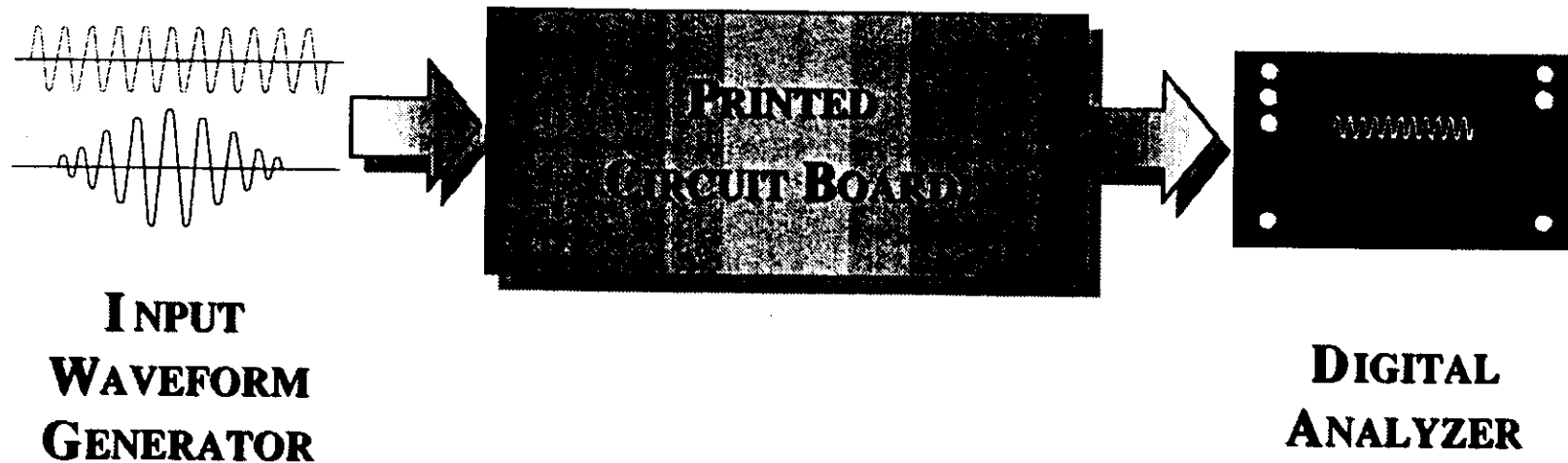
III - ABSTRACTION LEVELS IN ALLIANCE

IV - VHDL: A HARDWARE DESCRIPTION LANGUAGE



Why an HDL ?? (1)

✗ Hardware Solutions Limits



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VHDL: A HARDWARE DESCRIPTION LANGUAGE



IEEE COMPUTER SOCIETY

Why an HDL ? (2)

- ✗ Increasing Complexity
- ✗ Increasing Cost in Time & Investment
- ✗ Increasing Knowledge Requirement

A Software Solution is Needed



Why an HDL ? (3)

✗ Programming Language not Suited

A Special Purpose Language : HDL



DSME/ANSI

VHDL: A HARDWARE DESCRIPTION LANGUAGE



IEEE/ANSI

Why VHDL ? (1)

**Circuit Manufacturers
Fully Satisfied with their
Proprietary HDLs...**



Why VHDL ? (2)

Problems for system manufacturers

- ✗ Different vendors ➡ different incompatible HDLs
- ✗ Impossible to verify a whole mixed-system



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VHDL: A HARDWARE DESCRIPTION LANGUAGE

Why VHDL ? (3)

- ✗ Vendor dependency
- ✗ Design documentation exchange

**A Standard HDL from the System
Manufacturer's Point of View: V H D L**



VHDL

Very High Speed Integrated Circuits (VHSIC)

Hardware

Description

Language



PAIC VLSI

VHDL: A HARDWARE DESCRIPTION LANGUAGE



IEEE PRESS

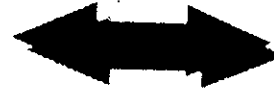
History

- 1981: an Extensive Public Review (DOD)
- 1983: a Request for Proposal
(Intermetrics, IBM, and Texas Instruments)
- 1986: VHDL in the Public Domain
- 1987: a Standard Language VHDL'87 (IEEE-1076)
- 1992: a New Standard VHDL'92



Advantages & Drawbacks

Standard



Open language

- ✓ Vendor independent
- ✓ User definable
- ✓ Wide capabilities

- ✗ Complex tools
- ✗ Slow tools



IEEE
COMPUTER SOCIETY

VHDL: A HARDWARE DESCRIPTION LANGUAGE



IEEE
COMPUTER SOCIETY

Abstraction Levels (1)

Algorithmic Level

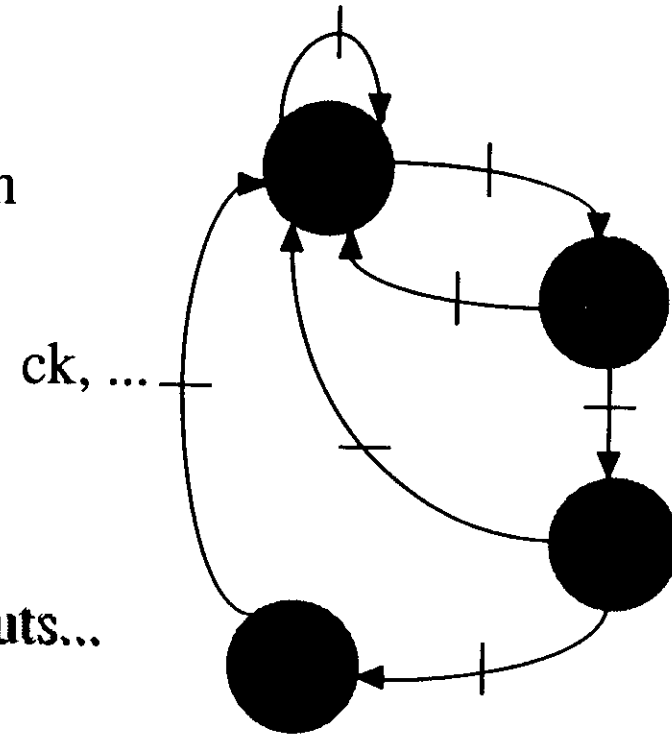
- Very High Abstraction Level
- Functional Interpretation of a Discrete System
- No Implementation Details
- Sequential Program-Like Description
- Programmer's Point of View



Abstraction Levels (2)

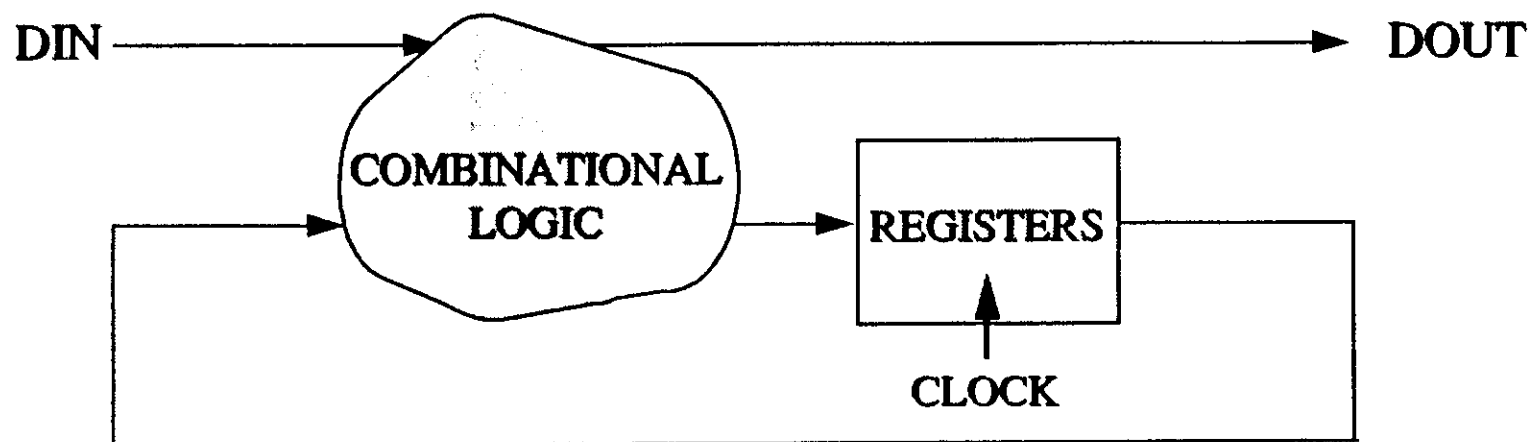
Finite State Machine Level

- Controller Part of a Digital Design
- Internal States
- State Changement Driven by:
 - ✧ Status Information
 - ✧ Clock and other External Inputs...



Abstraction Levels (3)

Register Transfer Level

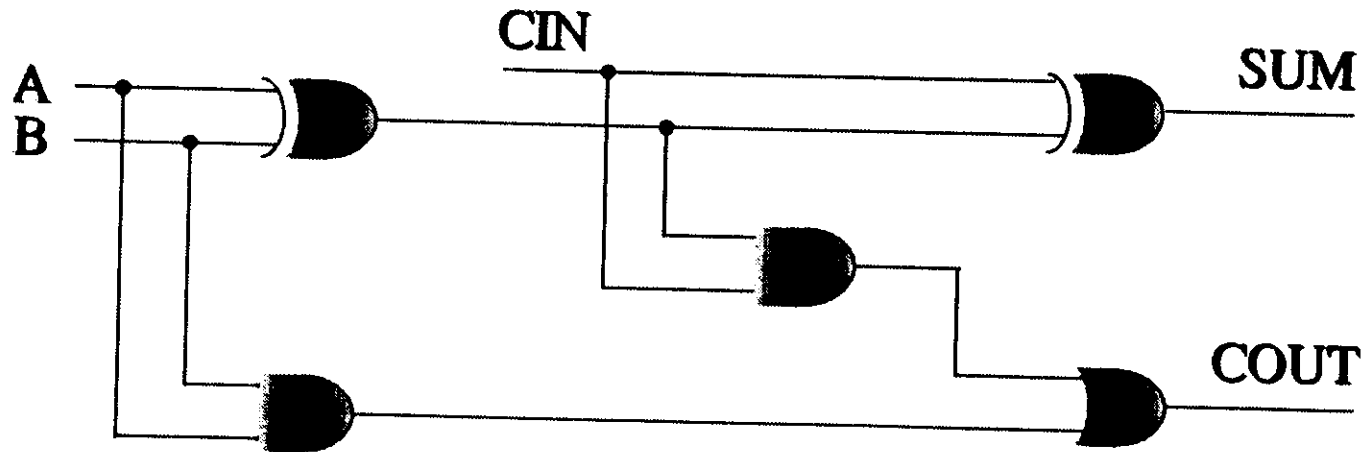


- Registers Connected by Combinational Logic
- Very Close to the Hardware



Abstraction Levels (4)

Gate Level



- A Gate Net-List Describing Instantiation of Models



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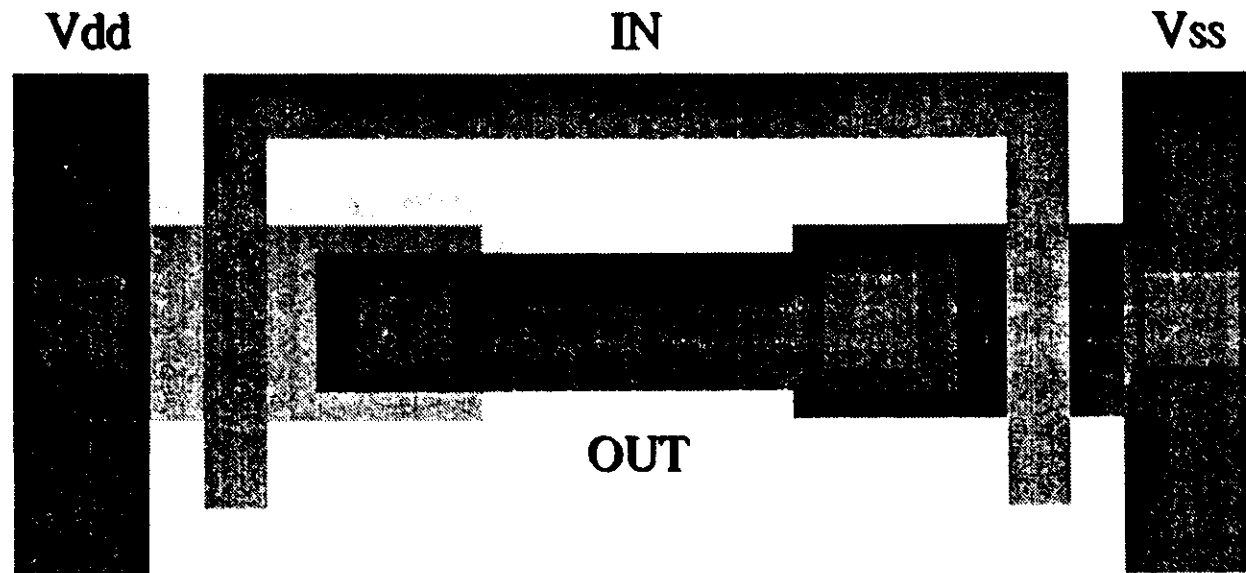
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Abstraction Levels (5)

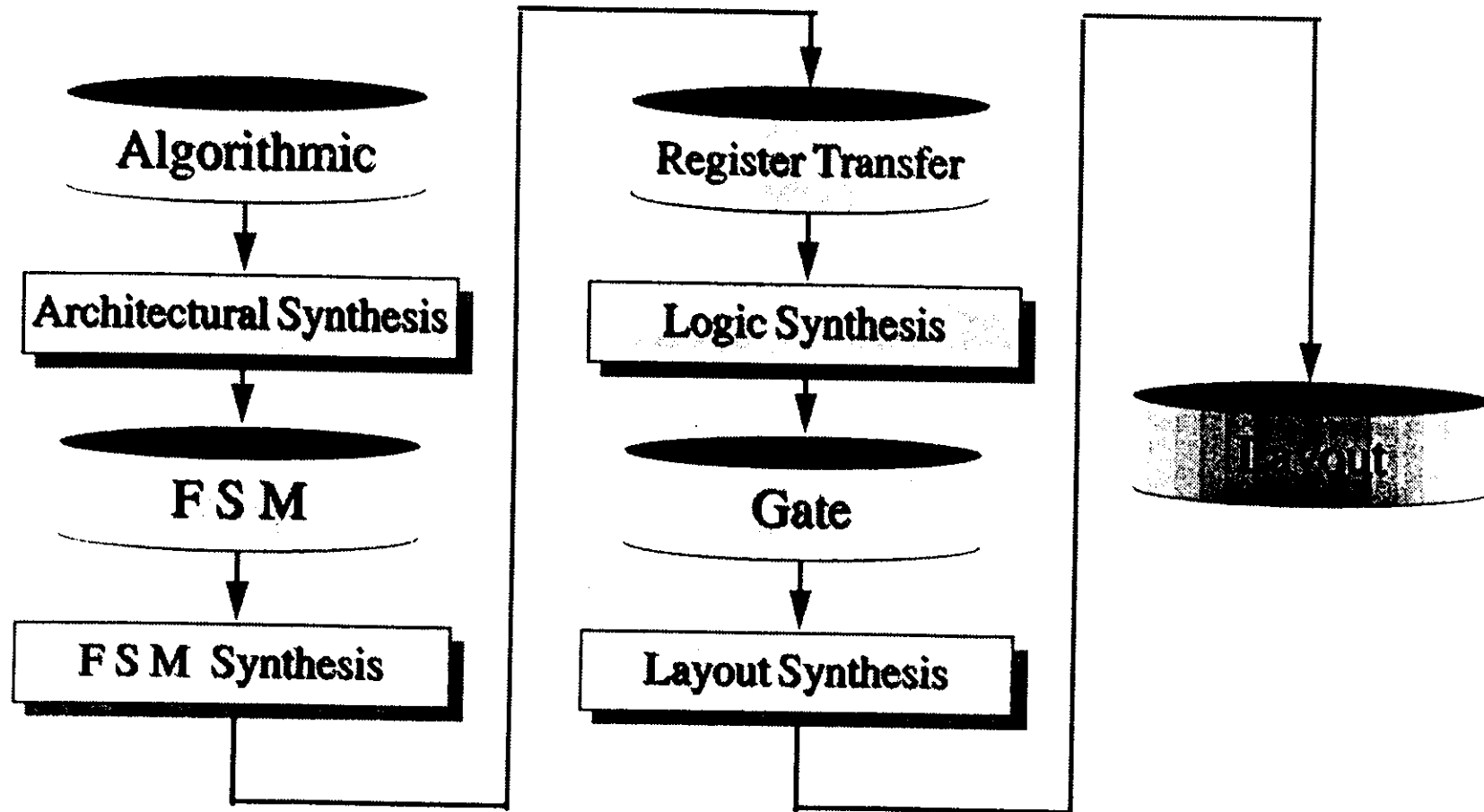
Layout Level



- A Set of Segments and Layers



Synthesis Flow



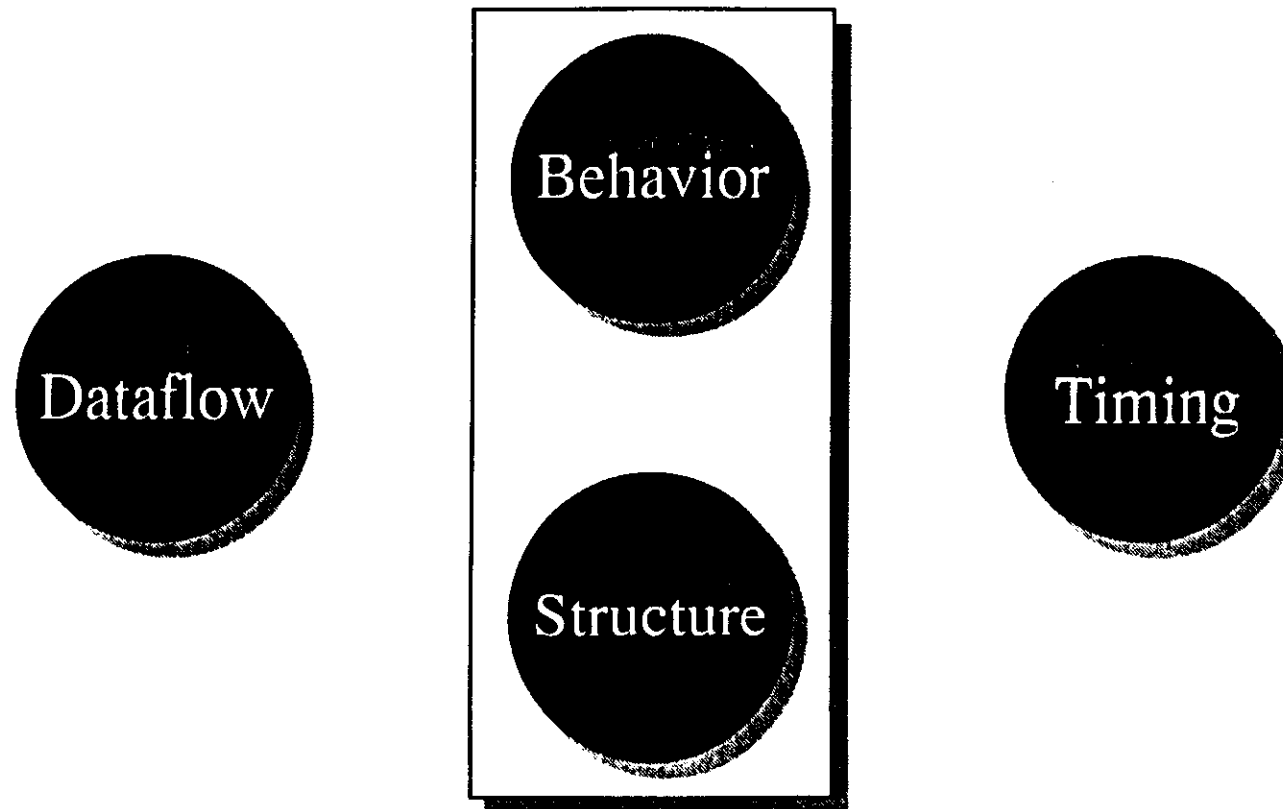
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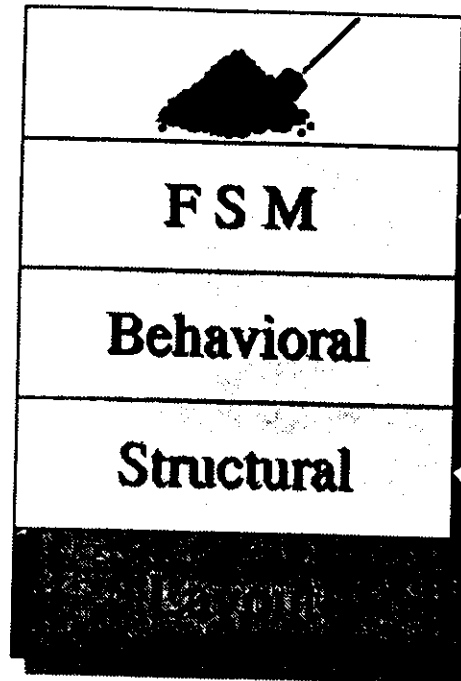
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VHDL Main Features

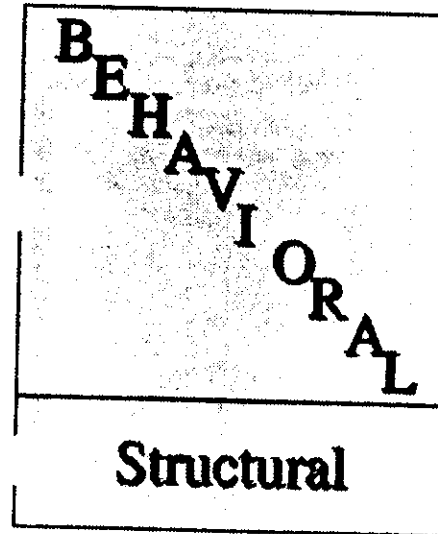


VHDL Architectures

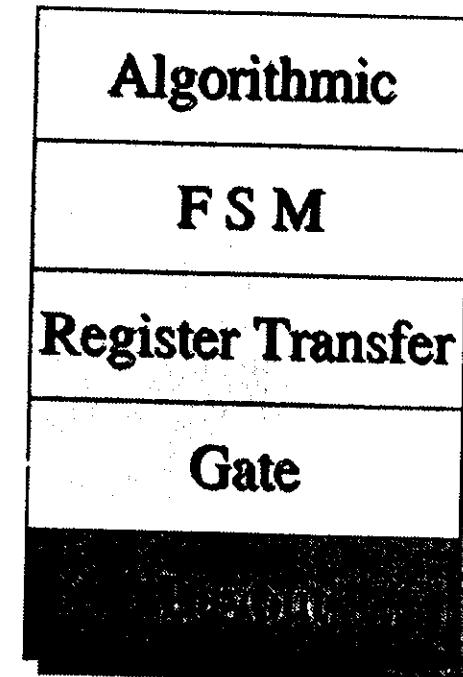
ALLIANCE VIEWS



VHDL ARCHITECTURES



DESIGN LEVELS



A Dataflow Language (1)

CONTROLFLOW



DATAFLOW

EX: C language assignment

X = A & B;

X is computed out of A and B ONLY each time this assignment is executed

EX: VHDL signal assignment

X <= A and B;

A PERMANENT link is created between A, B, and X

X is computed out of A and B WHENEVER A or B change



A Dataflow Language (2)

CONTROLFLOW



DATAFLOW

EX: C language assignment

$X = A \& B;$

$X = C \& D;$

✓ YES

EX: VHDL assignment

~~$X \leq A \text{ and } B;$~~

~~-----~~

~~$X \leq C \text{ and } D;$~~

✗ NO



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VHDL: A HARDWARE DESCRIPTION LANGUAGE



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Basic Structures

Basic Building Blocks

- Entity
- Architecture
- Configuration
- Package
- Library



Entity Declaration (1)

The External Aspect of a Design Unit

```
entity entity_name is
    [generic_declaration]
    [port_clause]
    {entity_declarative_item}
[begin
    entity_statement_part]
end [entity_name];
```

What is visible



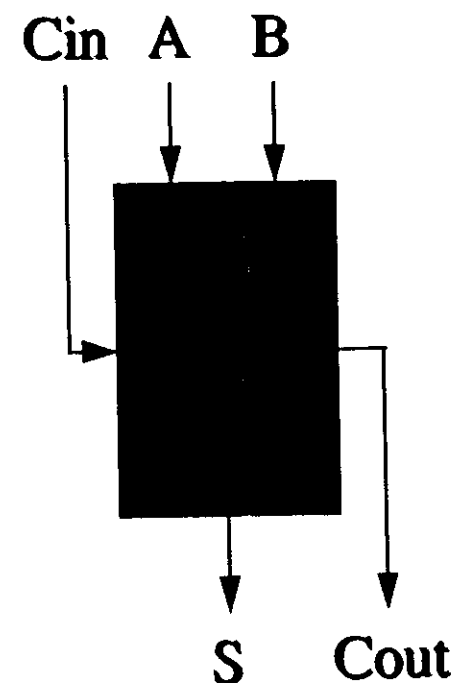
Entity Declaration (2)

Example

```
entity FULL_ADDER is
  port (A, B, Cin : in BIT;
        S, Cout : out BIT);
end FULL_ADDER;
```

MODE: in, out, inout...

DATATYPE



Architectures (1)

The Internal Aspect of a Design Unit

```
architecture architecture_name of entity_name is
    {architecture_declarative_part}
begin
    {architecture_descriptive_part}
end [architecture_name];
```

how it works

- Collection of CONCURRENT Statements Executed in PARALLEL
- Concurrent Statements Communicate through SIGNALS



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VHDL: A HARDWARE DESCRIPTION LANGUAGE



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Architectures (2)

A Behavioral Style

```

entity FULL_ADDER is
  port (A, B, Cin : in  BIT;
        S, Cout  : out BIT);
end FULL_ADDER;
architecture DATAFLOW of FULL_ADDER is
  signal X : BIT;
begin
    X    <= A xor B;
    S    <= S xor Cin after 10 ns;
    Cout <= (A and B) or (X and Cin) after 5 ns;
end DATAFLOW;
  
```



Architectures (3)

A Structural Style

architecture STRUCTURE of FULL_ADDER is
component HALF_ADDER

port (I1, I2 : in BIT;
Carry, S : out BIT);

end component;

component OR_GATE

port (I1, I2 : in BIT;
O : out BIT);

end component;

signal X1, X2, X3 : BIT;

**DECLARATIVE
PART**



Architectures (4)

A Structural Style

begin

HA1 : HALF_ADDER port map (

I1 => A, I2 => B, Carry => X1, S => X2);

HA2 : HALF_ADDER port map (

I1 => X2, I2 => Cin, Carry => X3, S => S);

OR1 : OR_GATE port map (

I1 => X1, I2 => X3, O => Cout);

end STRUCTURE;

**DESCRIPTIVE
PART**



UNICAMP

VHDL: A HARDWARE DESCRIPTION LANGUAGE

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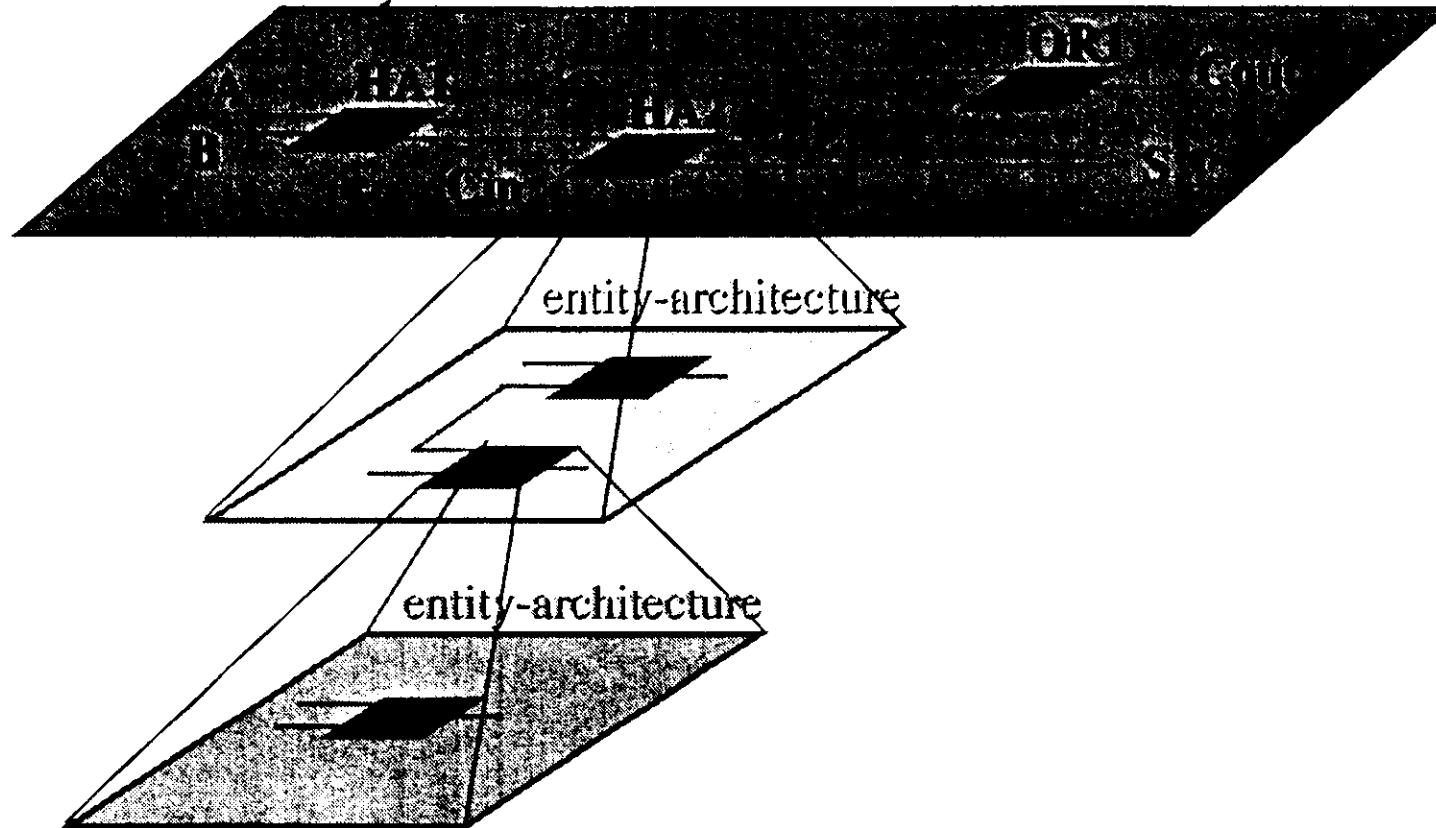
ICTP-UNESCO

Trieste

Architectures (5)

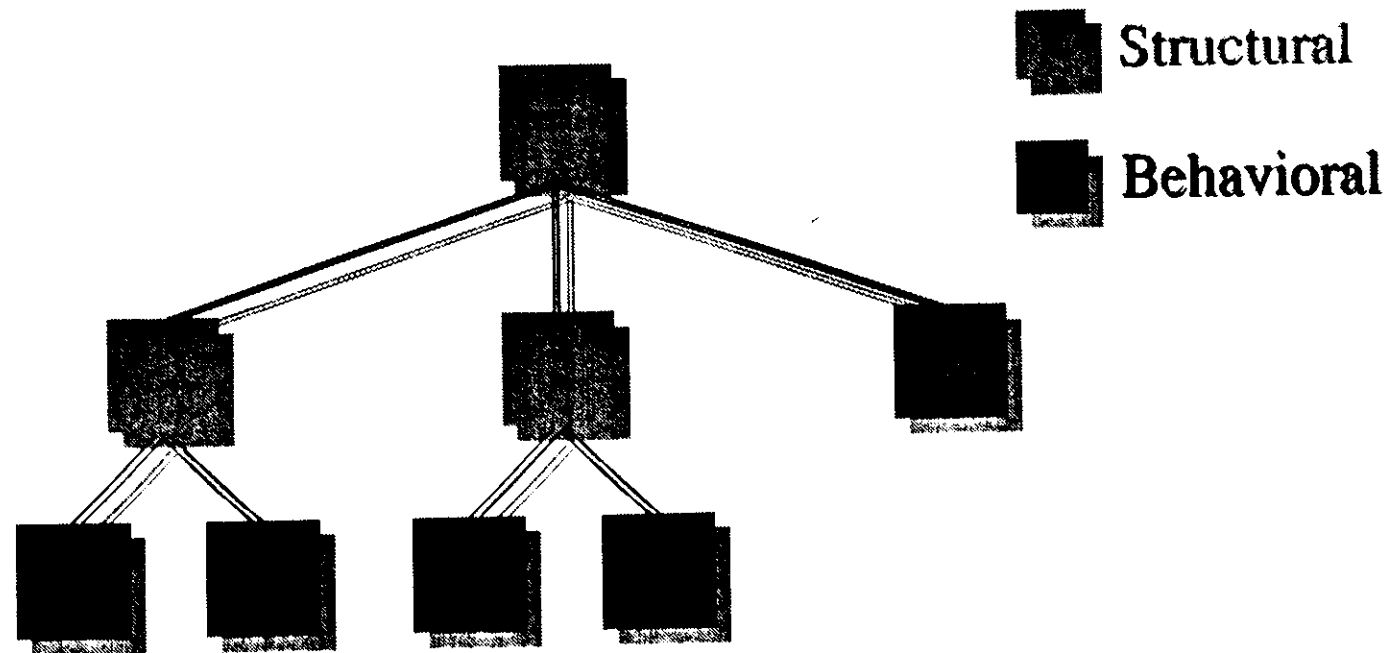
Structural Style to represent Hierarchy

entity-architecture



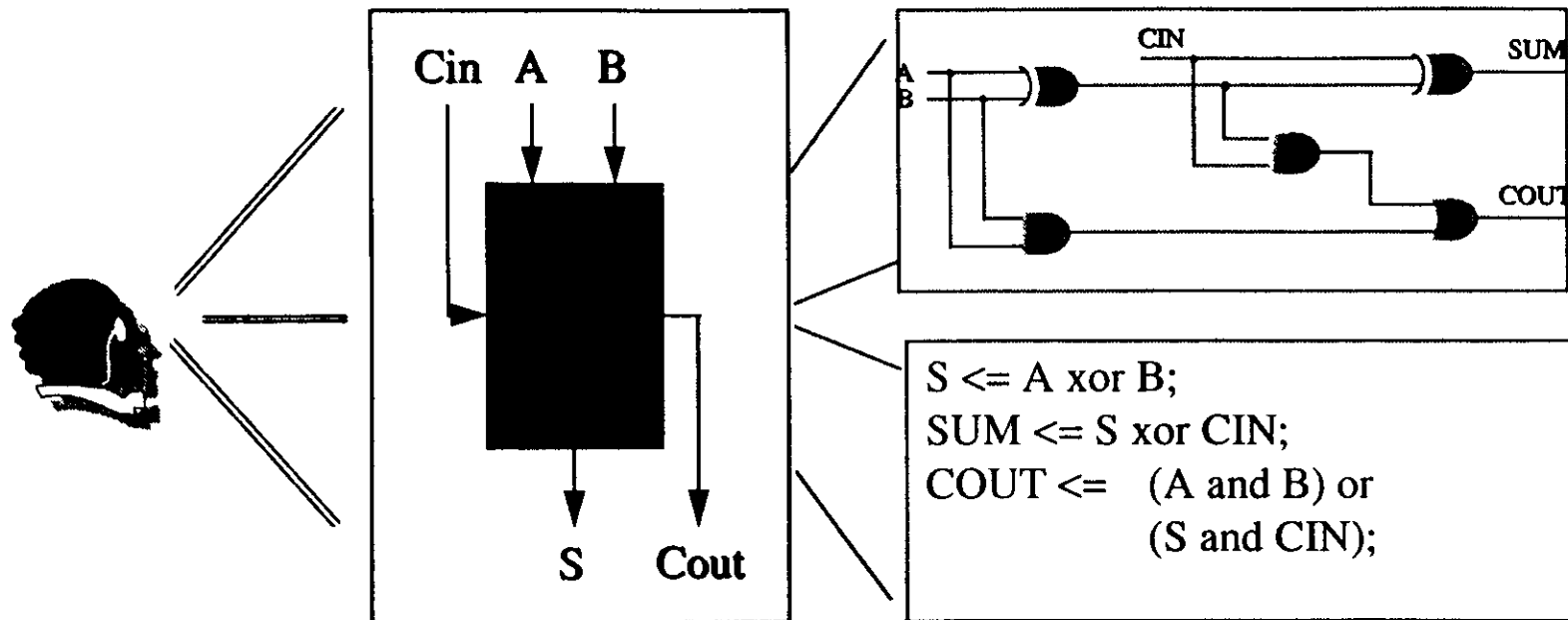
Architectures (6)

Structural & Behavioral in a Design Tree



Architectures (77)

entity/architecture: a One to Many Relationship



PMCMASL
12.04.2014

VHDL: A *HARDWARE DESCRIPTION LANGUAGE*



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Configurations (1)

Specification Inside the Architecture Body

for instantiation_list: component_name use binding_indication;



use library_name.entity_name [(architecture_name)];

- **Binding a couple "entity/architecture" to each instance**



Configurations (2)

Declaration as a Separate Design Unit

```
configuration configuration_name of entity_name is  
    for { architecture | component } binding_indication;  
end [configuration_name];
```

- Can be compiled separately and stored in a library
- It defines a configuration for a particular entity



Packages

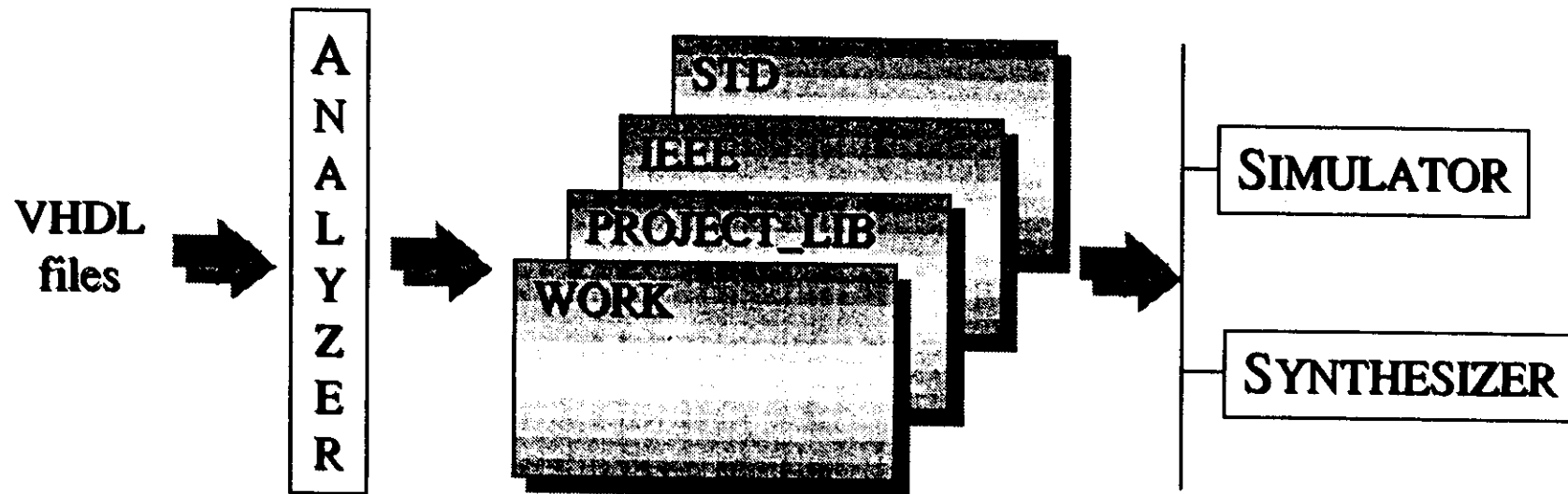
Global Design Unit

```
package package_name is
    {package_declarative_item}
end [package_name];
package body package_name is
    {package_body_declarative_item}
end [package_name];
```

- Same declarations visible by a number of design entities
- May contain subprograms, components, signals, ...



Design Libraries



```
library library_name ;  
use library_name.package_name.all;
```

- May contain: packages, entities, architectures, configurations



IPME/IASI
1994

VHDL: A HARDWARE DESCRIPTION LANGUAGE



IPME/UNESCO
1994

Data Objects (1)

Three Classes

➤ Constants

- ✧ Initialized to a specific value and never modified

constant MSB : INTEGER := 5;

➤ Variables

- ✧ Used to hold temporary data
- ✧ Only used within processes & subprograms

variable DELAY : INTEGER range 0 to 15 := 0;



Data Objects (2)

Three Classes

➤ Signals

- ✧ Used to communicate between processes
- ✧ When declared in a package : Global Signals
- ✧ Also declared within entities, blocks, architectures
- ✧ Can be used but not defined in processes and subprograms

signal CLK : BIT;



Data Types (1)

Enumeration Types

- **The first identifier is the default value**
type COLOR is (RED, ORANGE, YELLOW);
type TERNARY is ('1', '0', 'X');
variable X : COLOR;
signal Y : TERNARY;



Data Types (2)

Integer Types

- The range must be specified
- No logical operations on integer
type **MEMORY_SIZE** is range 1 to 2048;



Data Types (3)

Predefined VHDL Data Types IEEE 1076-1987 Standard Package

- **BOOLEAN** : (false , true)
- **BIT** : ('0', '1')
- **CHARACTER**
- **INTEGER** : range -2 147 483 647 to +2 147 483 647
- **NATURAL** : Subtype of INTEGER (Non Negative)
- **POSITIVE** : Subtype of INTEGER (positive)
- **BIT_VECTOR** : array of BIT values
- **STRING** : array of CHARACTERS
- **REAL** : range -1.0E+38 to +1.0E+38
- **TIME** : Physical type used for simulation



Data Types (4)

Array Types

➤ Constrained Array

```
type VEC_64 is array (0 to 63) of INTEGER;  
variable S : VEC_64;  
variable S1 : INTEGER;  
S1 := S (1);
```

➤ Unconstrained Array

```
type BIT_VECTOR is array (POSITIVE range <>) of BIT;  
signal S : BIT_VECTOR (4 downto 0);
```

➤ Multiple Dimentional Arrays

```
type TWO_D is array (0 to 7, 0 to 3) of INTEGER;
```



Data Types (5)

Record Types

**type DATE is
 record**

YEAR : INTEGER range 1900 to 1999 ;

MONTH : INTEGER range 1 to 12 ;

DAY : INTEGER range 1 to 31 ;

end record ;

signal S : DATE;

variable Y : INTEGER range 1900 to 1999 ;

Y := S.YEAR ;



Data Types (6)

STD_LOGIC Data Types

IEEE 1164-1993 Standard Logic Package

type STD_ULOGIC is (

'U'	--	Uninitialized
'X'	--	Forcing Unknown
'0'	--	Forcing Low
'1'	--	Forcing High
'Z'	--	High Impedance
'W'	--	Weak Unknown
'L'	--	Weak Low
'H'	--	Weak High
'-'	--	Don't Care



Unresolved
Data Type

Used in Synthesis



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Data Types (77)

STD_LOGIC Data Types IEEE 1164-1993 Standard Logic Package

- **STD_LOGIC : Resolved (Resolution Function provided)**
- **STD_LOGIC_VECTOR**
- **STD_ULOGIC_VECTOR**



Data Types (77)

Also,

- **FILE : Useful for RAM Values or Stimuli Files**
- **ACCESS : Like "pointers" in High Level Languages**
- **TEXT : FILE of STRING (TEXTIO package)**
- **LINE : access STRING (TEXTIO package)**



Subtypes

Subsets of Other Types

- To Insure Valid Assignments
- Inherit All Operators and Subprograms from the Parent Type

subtype DIGIT is INTEGER range 0 to 9;



Operators

Six Classes

LOGIC OPERATOR	and , or , nand , nor , xor
RELATIONAL OPERATOR	= , /= , < , <= , > , >=
ADDING OPERATOR	+ , - , &
SIGN	+ , -
MULTIPLYING OPERATOR	* , / , mod , rem
MISCELLANEOUS OPERATOR	** , abs , not



PRECEDENCE ORDER



Operands (1)

- **Literals : 'x' , "1100" , 752 , B"11001" , O"277" , X"4C"**
 - ✧ **numeric, character, enumeration, or string**
- **Identifiers :**
 - ✧ **starts with (a-z) followed by letters, '_', or digits**
 - ✧ **Not case-sensitive**
 - ✧ **Some are reserved words**
- **Indexed Names : S (3) , DATA (ADDR)**



Operands (2)

- **Slice Names : variable ORG : BIT_VECTOR (7 downto 0)**
 - ✧ **Sequence of elements of an array object**
- **Aliases : alias MSB : BIT is ORG (7)**
 - ✧ **New name for a part of a range of an array**
- **Aggregates**
- **Qualified Expressions**
- **Function Calls**
- **Type Conversions**



Operands (3)

Attributes Names

A Data Attached to VHDL Objects

- **S'LEFT** : Index of the leftmost element of the data type
- **S'RIGHT** : Index of the rightmost element of the data type
- **S'HIGH** : Index of the highest element of the data type
- **S'LOW** : Index of the lowest element of the data type
- **S'RANGE** : Index range of the data type
- **S'REVERSE_RANGE** : Reverse index range
- **S'LENGTH** : Number of elements of an array



Operands (4)

Attributes Names

A Data Attached to VHDL Signals

- **S'EVENT** : A change value at the current simulation time
- **S'STABLE** : No change value at the current simulation time
if (CK = 0 and not CK'STABLE)
-



Concurrent Statement

Natural Concept for Describing Hardware

- Concurrent Signal Assignment
- Conditional Signal Assignment
- Selected Signal Assignment
- Block Statement
- Concurrent Assertion Statement
- Process Statement



Concurrent Signal Assignment

Represent an Equivalent Process Statement

target <= expression [after time_expression] ;

- Signals are associated with Time
- With "after", the assignment is scheduled to a future simulation time
- Without "after", the assignment is scheduled at a Delta Time after the current simulation time



Selected Signal Assignment

Only One Target

with choice_expression select

target <= { expression [after time_exp] when choices , }
expression [after time_exp] when choices ;

- "when others" is used when all the cases were not treated



Block Statement (1)

A Set of Concurrent Statements

```
label : block  
      { block_declarative_part }  
begin  
      { concurrent_statements }  
end block [ label ] ;
```

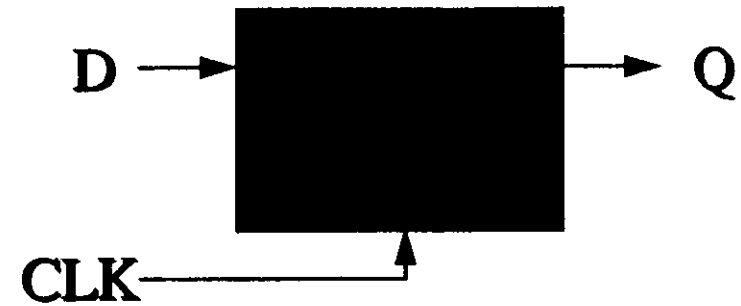
- Used to organize a set of concurrent statements hierarchically



Block Statement (2)

In Synchronous Descriptions

```
latch : block ( CLK = '1' )
begin
    Q <= GUARDED D ;
end block latch ;
```



Assertion Statement

Only One Target

assert condition

[report error_message]

[severity severity_level] ;

- **If the condition is false, it reports a diagnostic message**
- **Useful for detecting condition violation during simulation**
- **Not used in synthesis**



Process Statement (1)

A Set of Sequential Statements

```
[ label : ] process [ ( sensitivity_list ) ]  
    { process_declarative_part }  
begin  
    { sequential_statements }  
end process [ label ] ;
```

- All processes in a design executes **CONCURRENTLY**
- At a given time, **ONLY ONE** sequential statement executed within each process
- Communicates with the rest of a design through signals



Process Statement (2)

A Pseudo-Infinite Loop

```
process
begin
    sequential_statement_1 ;
    sequential_statement_2 ;
    -----
    sequential_statement_n ;
end process;
```

- A Synchronization Mechanism is Needed



Process Statement (3)

Synchronization Mechanism

wait

```
[ on signal_name { signal_name } ]  
[ until boolean_expression ]  
[ for time_expression ] ;
```

- Objects being waited upon should be SIGNALS



Process Statement (4)

The Sensitivity List

```
process [ ( sensitivity_list ) ]  
begin  
    { sequential_statements }  
end process ;
```

- Equivalent to a "wait" statement as the last statement
wait on sensitivity_list ;



Sequential Statement

Insight Into Statements within Processes

- Variable Assignment
- Signal Assignment
- If
- Case
- Null
- Assertion
- Loop
- Next
- Exit
- Wait
- Procedure Calls
- Return



Variable Assignment Statement

Immediate Assignment

target_variable := expression ;

- Always executed in **ZERO SIMULATION TIME**
- Used as temporary storages
- Can not be seen by other concurrent statements



Signal Assignment Statement (1)

Defines a **DRIVER** of the Signal

target_signal <= [transport] expression [after time_expression] ;

- Within a process, **ONLY ONE** driver for each signal
- When assigned in multiple processes, it has **MULTIPLE DRIVERS**. A **RESOLUTION FUNCTION** should be defined



CONCLUSION (1)

VHDL IS AN OPEN LANGUAGE WITH MANY FEATURES.

WITH VHDL, ANY DISCRETE SYSTEM CAN BE MODELED.



CONCLUSION (2)

EACH USER HAS ITS OWN NEEDS DEPENDING ON:

- HIS BACKGROUND.
- HIS ENVIRONMENT.

WE DEFINED A SUBSET OF VHDL.



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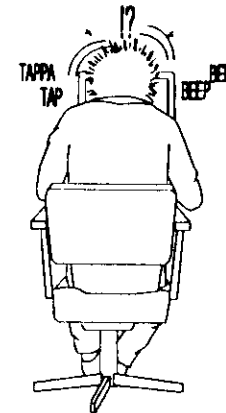
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SLIDE 21



CONCLUSION (3)

WHY ?



COMPLEX LANGUAGE \Rightarrow DEVELOPING A COMPILER IS HARD
AND TIME CONSUMING.



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CONCLUSION (4)

WHY ?

EDUCATIONAL NEEDS:

- UNDERSTANDING TIME.
- UNIVOCAL (ONE WAY FOR DESCRIBING A REGISTER).



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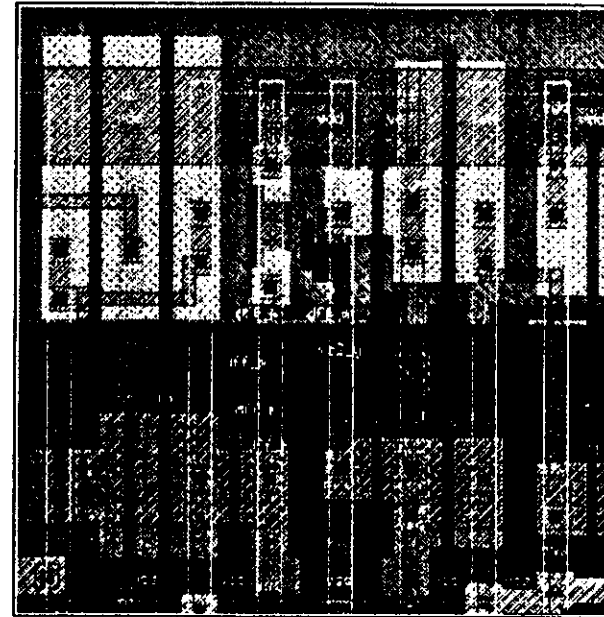
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CONCLUSION (5)

WHY ?

OUR ENVIRONMENT: VLSI.



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OUTLINE

I - INTRODUCTION.

II - DESIGN METHODOLOGY: AN OVERVIEW.

III - ABSTRACTION LEVELS IN ALLIANCE.

IV - VHDL: AN OVERVIEW.

V - VHDL: THE ALLIANCE SUBSET.

VI - ALLIANCE: A COMPLETE DESIGN SYSTEM.



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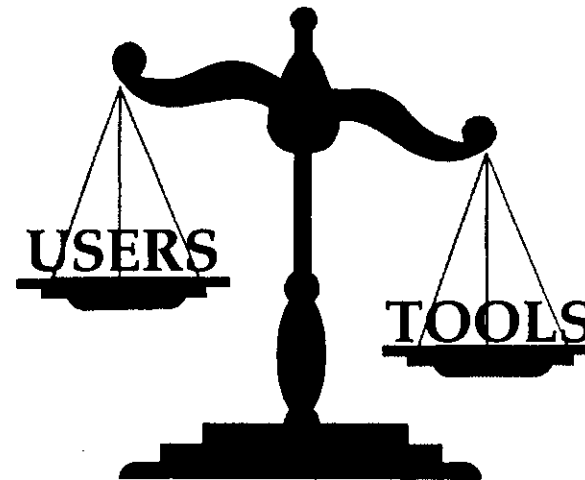
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WHY AND HOW ?

WHY ?

- DEVELOPMENT TIME.
- EDUCATION CONSTRAINTS.
- THE CURRENT ENVIRONMENT.

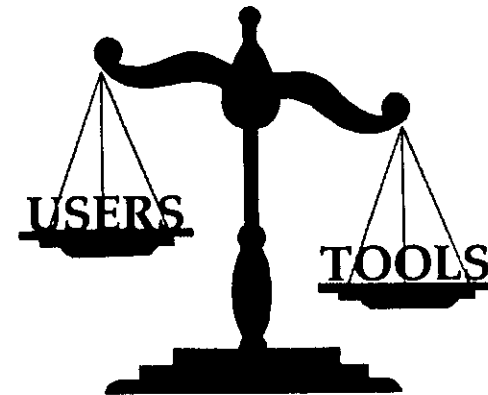
CRITERIONS FOR THE SUBSET DEFINITION.



TOOLS REQUIREMENTS (1)

WHICH TOOLS USE VHDL ?

- SYNTHESIS.
- FORMAL PROOVER.
- PLACER & ROUTER.
- SIMULATOR.
- FUNCTIONAL ABTRACTOR.



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SLIDE 3

TOOLS REQUIREMENTS (2)

SYNTHESIS TOOLS.

- ✗ A REGISTER MUST BE IDENTIFIED IN A SYNTACTICAL WAY.
- ✗ A BUS MUST BE IDENTIFIED IN A SYNTACTICAL WAY.
- ✗ SIGNALS MUST HAVE THE **BIT** TYPE ('0' , '1').
- ✗ NO TIMING.

FORMAL PROOVER.

- ✗ A REGISTER MUST BE IDENTIFIED IN A SYNTACTICAL WAY.
- ✗ A BUS MUST BE IDENTIFIED IN A SYNTACTICAL WAY.



TOOLS REQUIREMENTS (3)

FUNCTIONAL ABTRACTOR.

- ✗ THE VHDL SUBSET MUST BE AS CLOSE AS POSSIBLE TO THE HARDWARE.

PLACER & ROUTER.

- ✗ NO MIXING BETWEEN STRUCTURAL AND BEHAVIORAL VIEWS.

SIMULATOR.

- ✗ NO ABSTRACT TYPES.
- ✗ NO TIMING.



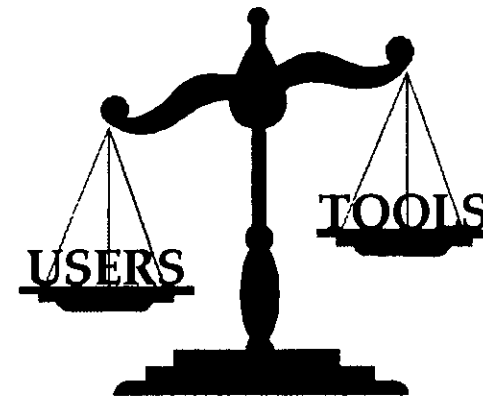
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SLIDE 5

USERS REQUIREMENTS

LOOKING FOR THE LARGEST SUBSET.



THE GOOD VHDL SUBSET:

- ✓ LETS THE USER DESCRIBE HIS CIRCUIT EASILY.
- ✓ DO NOT DETERIORATE THE TOOL WITH A COMPLEX LANGUAGE.



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SLIDE 6

THE EXTERNAL ASPECT

IN VHDL A CIRCUIT (DESIGN UNIT) HAS TWO ASPECTS:

1. THE EXTERNAL ASPECT: (EXTERNAL VISIBILITY)

ALLIANCE

What is visible

✓ NAME

✓ INTERFACE (PORT)

✗ COLOR

✗ TEMPERATURE

✗ -----



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SLIDE 7

THE INTERNAL ASPECT (1)

IN VHDL A CIRCUIT (DESIGN UNIT) HAS TWO ASPECTS:

2. THE INTERNAL ASPECT: (FUNCTIONALITY)

how it works

ALLIANCE

✓ STRUCTURAL
✓ DATA FLOW



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SLIDE 8

THE INTERNAL ASPECT (2)

IN THE STRUCTURAL INTERNAL ASPECT, WE DESCRIBE THE CIRCUIT AS A NETWORK OF SMALLER CIRCUITS.

THE FOLLOWING OBJECTS ARE USED:

- SIGNAL.
- COMPONENT (MODEL).
- INSTANCE.



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EXTERNAL ASPECT: EXAMPLE (1)

```
ENTITY PARITY IS
  PORT (
    A: IN BIT ;
    B : IN BIT;
    C : IN BIT ;
    D : IN BIT;
    P : OUT BIT
  )
END PARITY;
```

Circuit Name

Port Name

Input/output mode

Type



EXTERNAL ASPECT: EXAMPLE (2)

ENTITY ADDER_32 IS

PORT (

A : IN BIT_VECTOR (31 DOWNT0 0);

B : IN BIT_VECTOR (31 DOWNT0 0);

CIN : IN BIT;

SUM : OUT BIT_VECTOR (31 DOWNT0 0);

COUT : OUT BIT

)

END;



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INTERNAL STRUCTURAL EXAMPLE (1)

ARCHITECTURE PSTRUCT OF PARITY IS
COMPONENT XOR_Y

PORT (

I0 : IN BIT ;

I1 : IN BIT;

T : OUT BIT

);

END COMPONENT;

SIGNAL PARITY_AB : BIT;

SIGNAL PARITY_CD : BIT;

DECLARATIVE
PART



INTERNAL STRUCTURAL EXAMPLE (2)

BEGIN

 INSTANCE_AB : XOR_Y

 PORT MAP (

 I0 => A,

 I1 => B,

 T => PARITY_AB

);

 INSTANCE_CD : XOR_Y

 PORT MAP (

 I0 => C,

 I1 => D,

 T => PARITY_CD

);

DESCRIPTION
PART



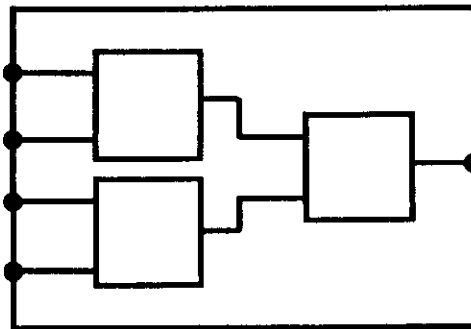
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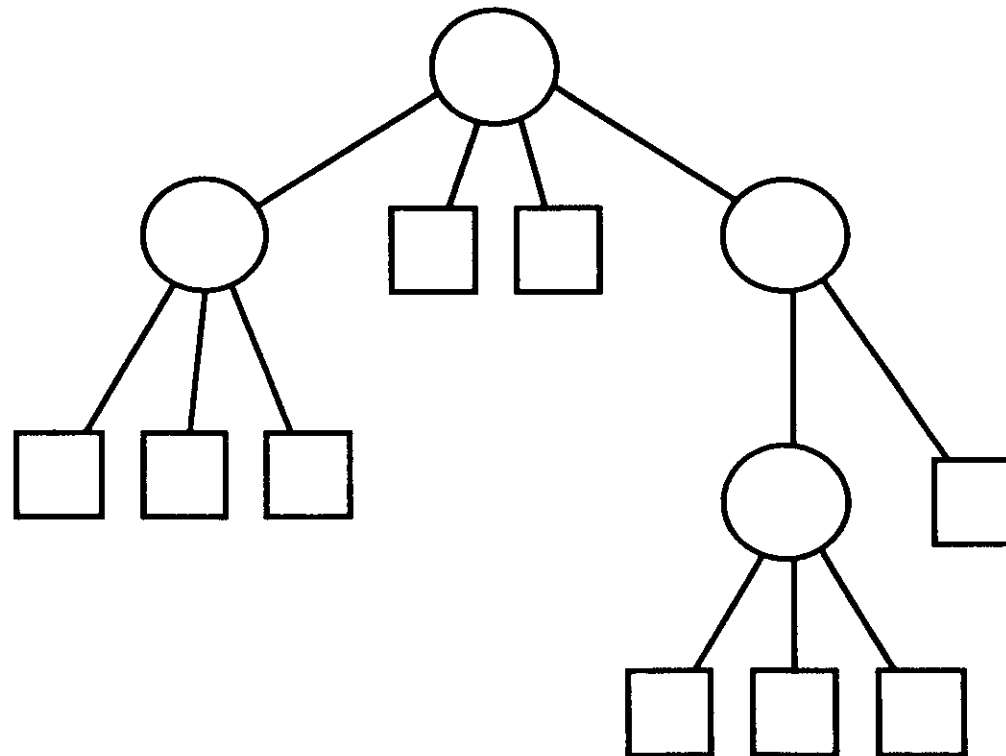
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INTERNAL STRUCTURAL EXAMPLE (3)

```
INSTANCE_ABCD : XOR_Y  
  PORT MAP (  
    I0 => PARITY_AB,  
    I1 => PARITY_CD,  
    T => P  
  );  
  
END;
```



STRUCTURAL & HIERARCHICAL



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SLIDE 15

INTERNAL BEHAVIORAL ASPECT (1)

DESCRIBING EQUATIONS BETWEEN INPUTS AND OUTPUTS.

- BOOLEAN FUNCTIONS:

- ◆ AND

- ◆ OR

- ◆ XOR

- ◆ NAND

- ◆ NOR

- ◆ NOT

ALWAYS USE BRACKETS.



INTERNAL BEHAVIORAL ASPECT (2)

DESCRIBING EQUATIONS BETWEEN INPUTS AND OUTPUTS.

- ASSERT (CONDITION)
REPORT "MESSAGE"
SEVERITY LEVEL;

VERY USEFUL IN LARGE-SCALE DESIGN.

- ◆ ALLOWS ENCODING SPECIFIC CONSTRAINTS AND ERROR CONDITIONS
- ◆ PROVIDE USEFUL MESSAGES.
- ◆ STOP THE SIMULATION WHEN CONSTRAINTS ARE NOT MET.



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SLIDE 17

INTERNAL BEHAVIORAL ASPECT (3)

- THREE KINDS OF ASSIGNMENTS:

SIMPLE ASSIGNMENT:

$S \leq A \text{ AND } B;$

CONDITIONAL ASSIGNMENT:

$S \leq A \text{ AND } B \text{ WHEN } (C = '0') \text{ ELSE}$
 $D \text{ OR } E;$

Always



INTERNAL BEHAVIORAL ASPECT (4)

SELECTIVE ASSIGNMENT:

WITH ADDRESS(3 DOWNT0 0) SELECT

OUT <= "000100" WHEN "0000",

"000101" WHEN "0001",

"000000" WHEN OTHERS;



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INTERNAL BEHAVIORAL ASPECT (5)

- REGISTERS:

SIGNAL MYREGISTER : REG_BIT REGISTER;

```
STORE : BLOCK ( CK = '0' AND NOT CK'STABLE )  
BEGIN  
MYREGISTER <= GUARDED I0;  
END BLOCK STORE;
```



INTERNAL BEHAVIORAL ASPECT (6)

- BUS:

SIGNAL MY_BUS1 : MUX_BIT BUS;
ONLY ONE DRIVER ACTIVE AT THE SAME TIME.

SIGNAL MY_BUS2 : WOR_BIT BUS;
MANY DRIVERS DRIVE THE SAME VALUE.



INTERNAL BEHAVIORAL EXAMPLE

ARCHITECTURE DATA_FLOW OF PARITY IS

SIGNAL PARITY_AB : BIT;

SIGNAL PARITY_CD : BIT;

BEGIN

PARITY_AB <= A XOR B;

PARITY_CD <= C XOR D;

P <= PARITY_AB XOR PARITY_CD;

End;



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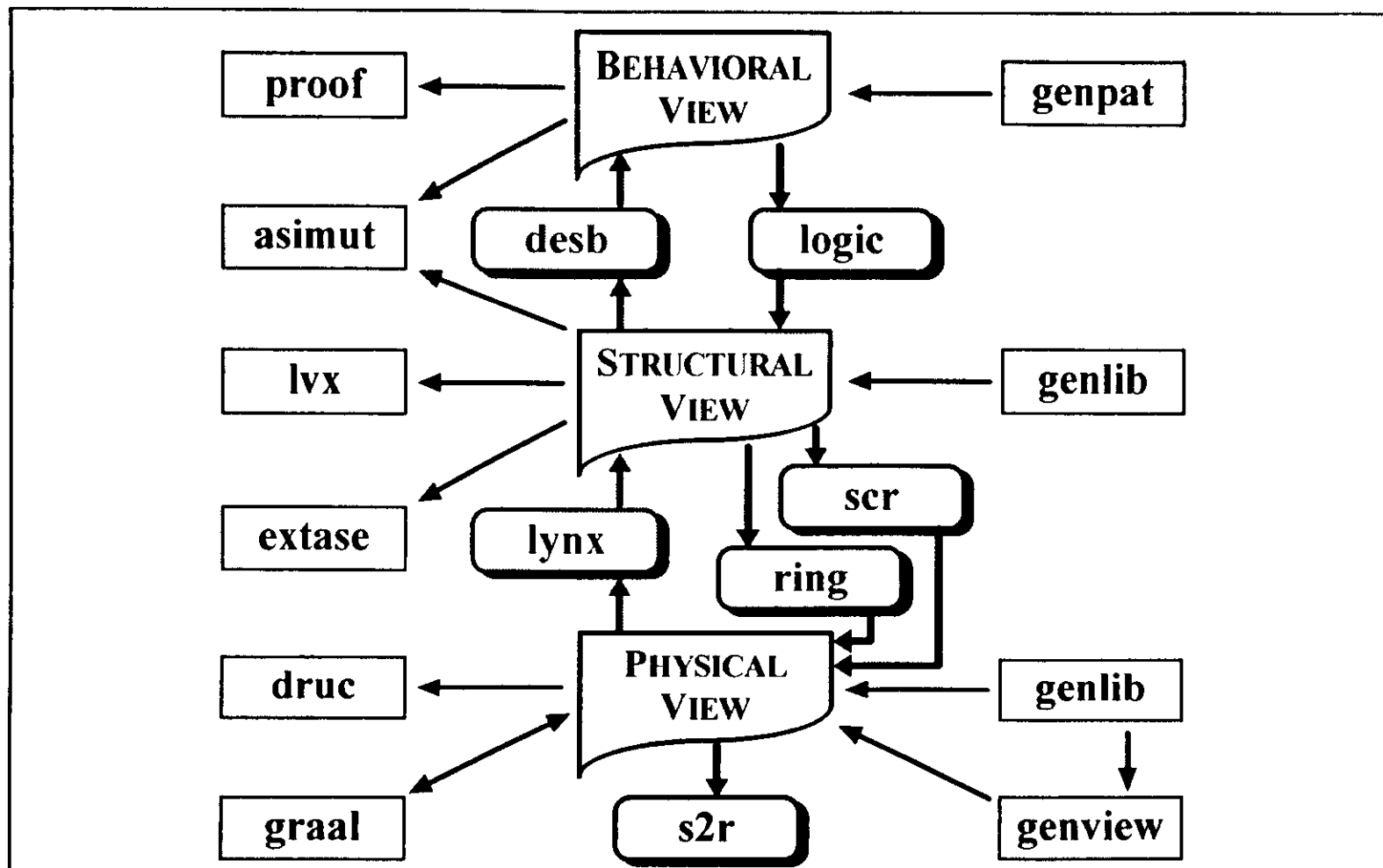
VI - ALLIANCE: A COMPLETE DESIGN SYSTEM.



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SLIDE 1



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SLIDE 2

SYNTHESIS LEVELS

- ARCHITECTURAL
- FINITE STATE MACHINE
- LOGIC
- LAYOUT



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SLIDE 3

SYNTHESIS AREA

- CONTROL LOGIC

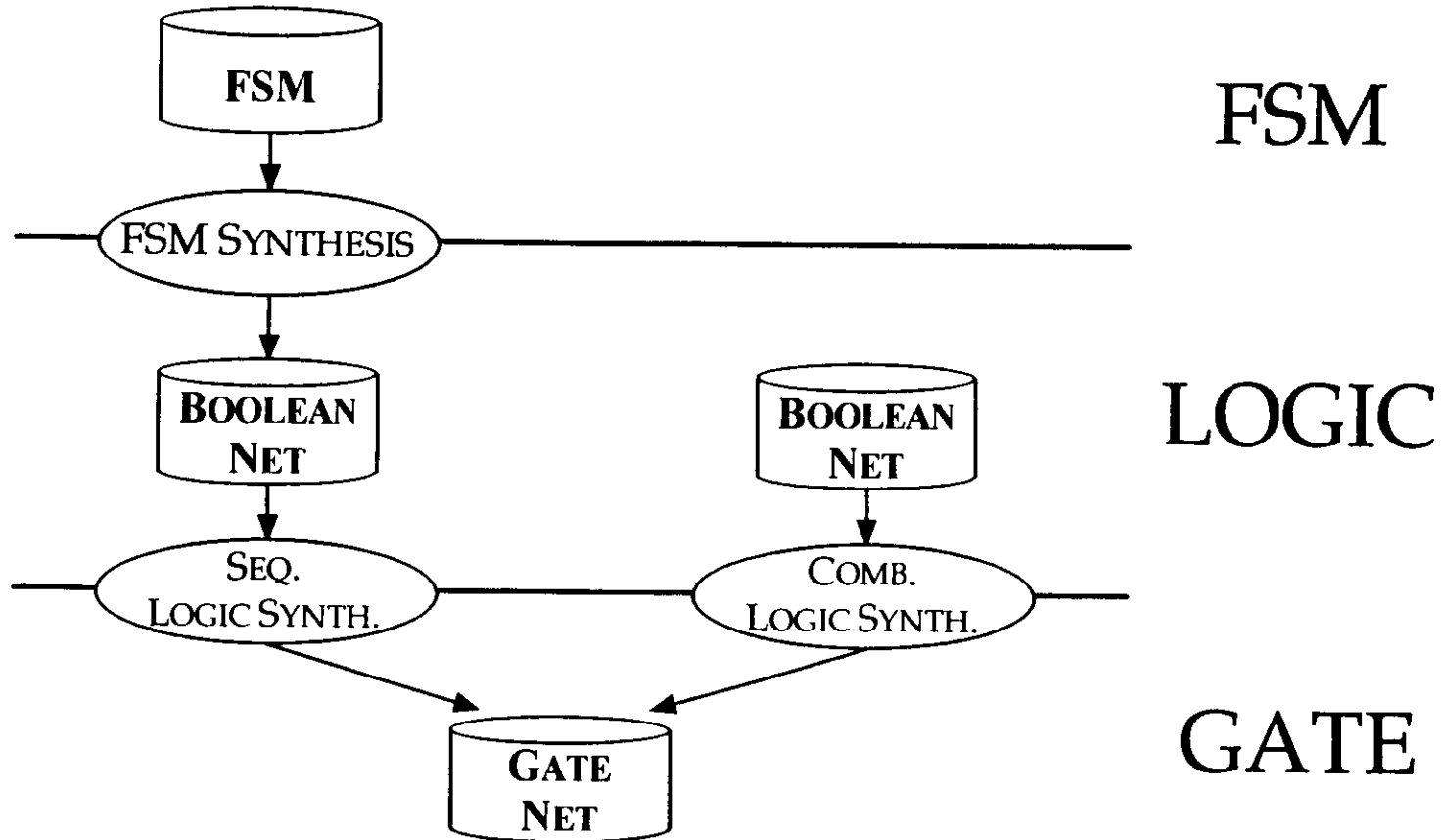
EVERY CIRCUIT THAT MAY BE DESCRIBED AS FSM
(NB STATES < 1000).

- RANDOM LOGIC

EVERY CIRCUIT THAT MAY NOT BE DESCRIBED WITH REGULAR
LOGIC.



SYNTHESIS ARCHITECTURE

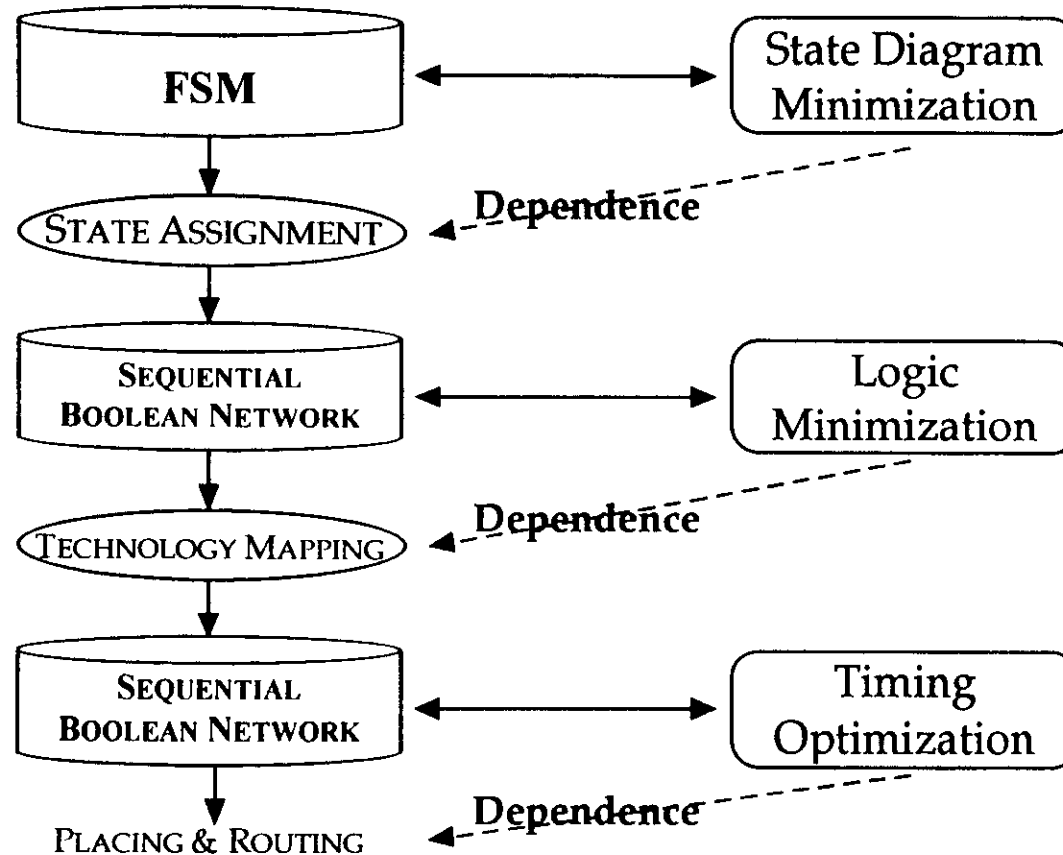


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OPTIMIZATION AND SYNTHESIS FLOW



LOGIC SYNTHESIS

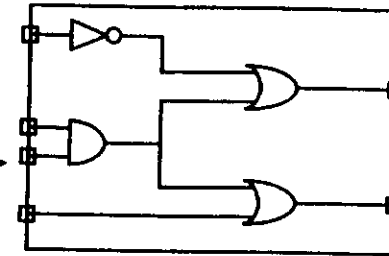
• COMBINATIONAL LOGIC SYNTHESIS

```
ENTITY dec2to4 is
PORT(A,B,enable:in BIT;
      vdd,vss,vdde,vsse:in BIT;
      Y:out bit_vector(0 to 3));
end dec2to4;

architecture dflow of dec2to4 is
signal a_bar,b_bar:bit;
signal a1,a2,a3,a4:bit;

begin
  a_bar <= not a;
  b_bar <= not b;
```

Combinational
Logic Synthesis



Gate Netlist =
Gate Level
Structural Description

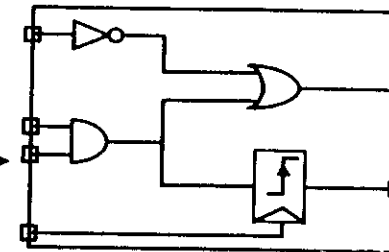
• SEQUENTIAL LOGIC SYNTHESIS

```
ENTITY adder is
PORT(A,B,enable:in BIT;
      vdd,vss,vdde,vsse:in BIT;
      ck:in bit;
      Y:out bit_vector(0 to 3));
end adder;

architecture dflow of adder is
signal registr:reg_vector(0 to 3)
register;
signal a1,a2,a3,a4:bit;

begin
```

Sequential
Logic Synthesis



Gate Netlist =
Gate Level
Structural Description



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OPTIMIZATION

- ✓ IMPROVE DESCRIPTION AT EQUIVALENT LEVEL.

$$\begin{cases} X = A + \bar{A}.C.D \\ Y = C.D \end{cases} \Rightarrow \begin{cases} X = A + Y \\ Y = C.D \end{cases}$$



REPRESENTATION (1)

LOGICAL EQUATIONS

A DIRECTED ACYCLIC GRAPH INCLUDING THREE KINDS OF NODES: INPUT, INTERMEDIARY, OUTPUT.

EACH INTERMEDIARY OR OUTPUT NODE IS ASSOCIATED TO A LOGICAL EXPRESSION.

EACH NODE IS ASSOCIATED TO A VARIABLE NAME.



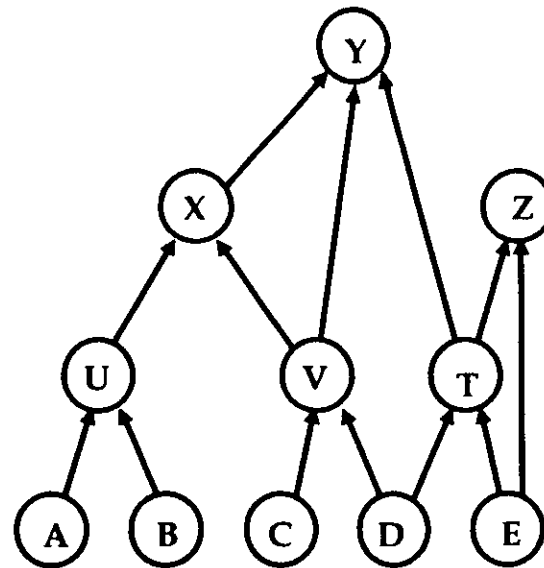
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REPRESENTATION (2)

BOOLEAN NETWORK



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BDD (BINARY DECISION DIAGRAM) (1)

BASED ON THE SHANNON THEOREM:

$$F(X_1, X_2, \dots, X_n) = \overline{X_1} \cdot F(0, X_2, \dots, X_n) + X_1 \cdot F(1, X_2, \dots, X_n)$$

✓ CANONICAL REPRESENTATION OF A BOOLEAN EQUATION.



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BDD (BINARY DECISION DIAGRAM) (2)


EX: $F(a, b) = a + b$

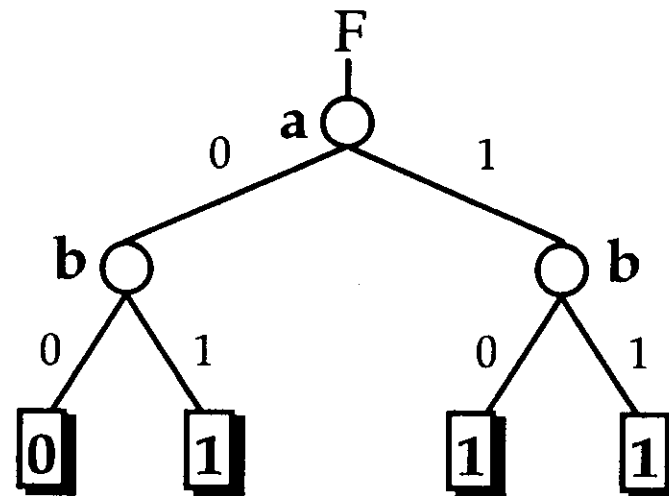
$$\begin{aligned} F &= \bar{a}.F(0, b) + a.F(1, b) \\ &= \bar{a}.(0 + b) + a.(1 + b) \\ &= \bar{a}.(b) + a.(1) \\ &= \bar{a}.(b.(0) + b.(1)) + a.(b.(1) + b.(1)) \end{aligned}$$



BDD (BINARY DECISION DIAGRAM) (3)

So...

$$F = \bar{a} \cdot (\bar{b} \cdot (0) + b \cdot (1)) + a \cdot (\bar{b} \cdot (1) + b \cdot (1))$$




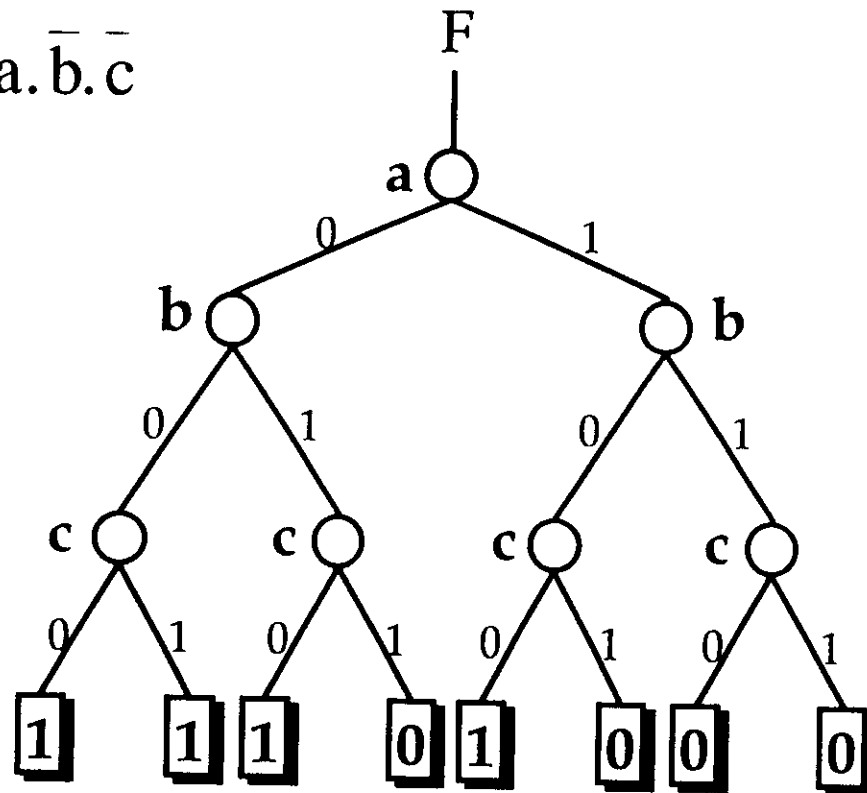
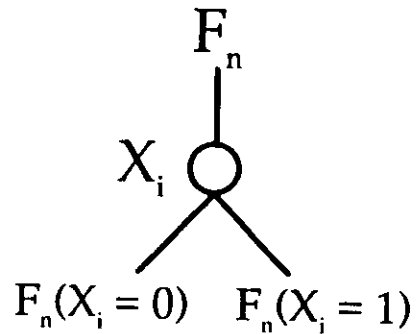
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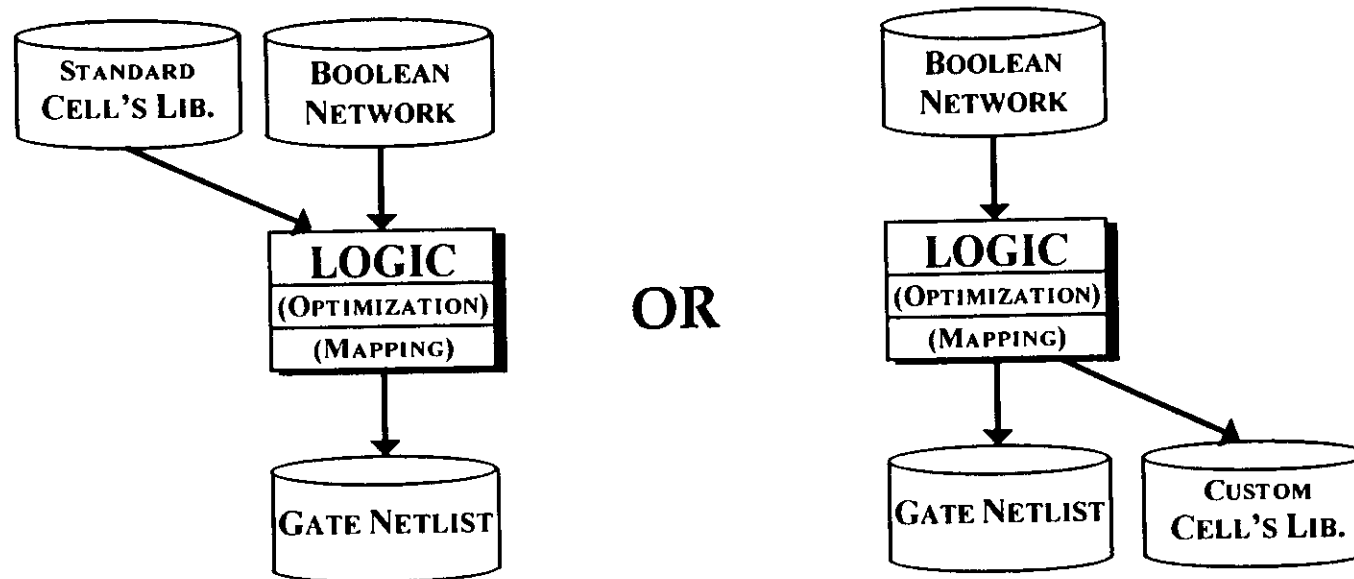
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BDD (BINARY DECISION DIAGRAM) (4)

EX: $F = \bar{a}.\bar{b} + \bar{a}.b.\bar{c} + a.\bar{b}.\bar{c}$



LOGIC: LOGIC SYNTHESIZER



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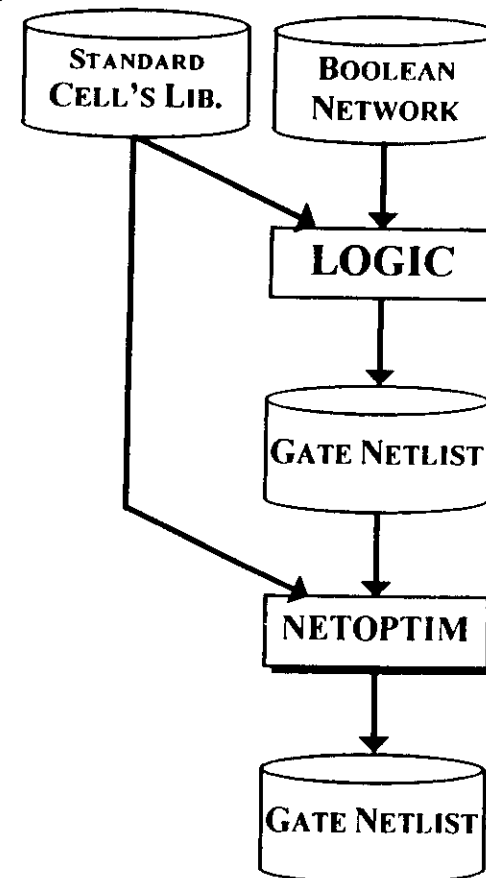
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NETOPTIM: TIMING OPTIMIZER

- ✓ TIMING OPTIMIZATION WITH LIMITED SURFACE LOSS.

TWO OPTIMIZATION OPTIONS:

- FANOUT OPTIMIZATION (LOCAL VIEW).
- DELAY OPTIMIZATION WITH TIMING ANALYSIS (GLOBAL VIEW).



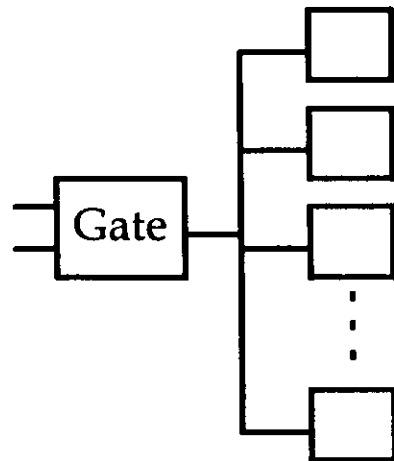
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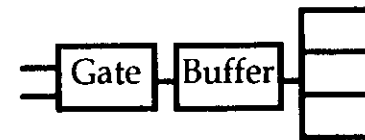
NETOPTIM: FANOUT OPTIMIZATION (LOCAL)

THREE METHODS:

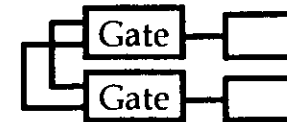


- REPOWER.

- BUFFER INSERTION.



- GATE DUPLICATION.



✓ FAST TECHNIQUES.

✗ NOT SHARP ENOUGH.



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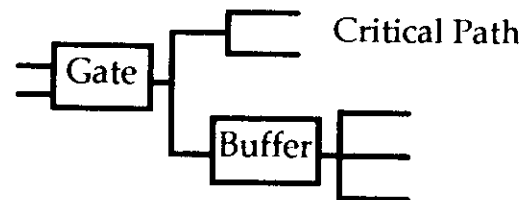
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NETOPTIM: DELAY OPTIMIZATION (GLOBAL)

THE TIMING ANALYSIS COMPUTES THE CRITICAL PATH OF THE CIRCUIT.

TWO METHODS TO OPTIMIZE THE CRITICAL PATH:

- REPOWER.
- BUFFER INSERTION.



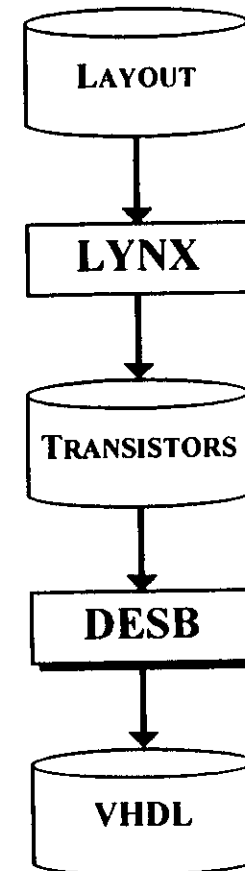
✓ GOOD RESULTS.

✗ FALSE PATH PROBLEM



DESB: FUNCTIONAL ABTRACTOR (1)

- ✓ GENERATES BEHAVIORAL DATA FLOW VHDL.
- ✓ PROVIDES FUNCTIONAL VERIFICATIONS.
- ✓ DOES NOT USE ANY CELL LIBRARY.
- ✓ ACCEPTS STANDARD TRANSISTOR NETLIST FORMAT (VTI, SPICE).

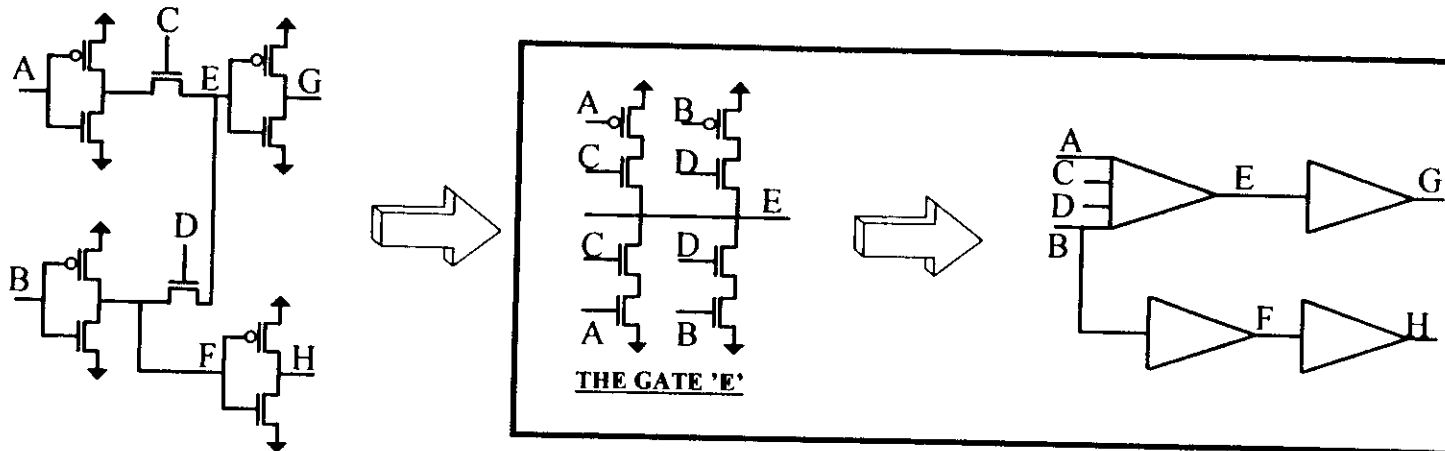


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DESB: FUNCTIONAL ABTRACTOR (2)



$E \leq (\text{NOT } A \text{ AND } C) \text{ OR } (\text{NOT } B \text{ AND } D);$
 $H \leq \text{NOT } F;$
 $G \leq \text{NOT } E;$
 $F \leq \text{NOT } B;$



FSM (FINITE STATE MACHINE) (1)

- MODELS SEQUENTIAL CIRCUITS.
- TWO KINDS OF FSM.
- GRAPH REPRESENTATION.
- DEFINITION:

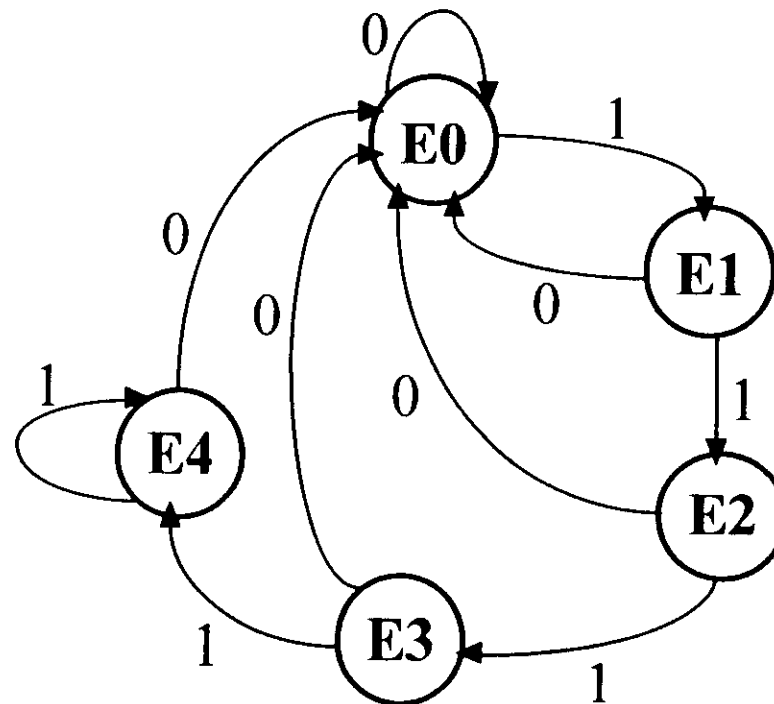
$$\text{STATE}(T+1) \leq F(I_1, \dots, I_n, \text{STATE}(T))$$

$$\text{OUTPUT}_i \leq F(I_1, \dots, I_n, \text{STATE}(T))$$



FSM (FINITE STATE MACHINE) (2)

EXAMPLE: FOUR CONSECUTIVE ONE'S COUNTER



FSM: THE DESCRIPTION LANGUAGE

- STANDARD.
- VHDL SUBSET.
- THE STATES ARE ENUMERATED TYPE.
- TWO SPECIAL SIGNALS.
- TWO PROCESSES.



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--

Entity counter is port (ck, I, reset: in bit; O: out bit);
End counter;

Architecture automate of counter is

type STATE_TYPE is (E0, E1, E2, E3, E4);
signal CURRENT_STATE, NEXT_STATE: STATE_TYPE;
-- pragma CUR_STATE CURRENT_STATE;
-- pragma NEX_STATE NEXT_STATE;
-- pragma CLOCK ck;

begin

 Process(CURRENT_STATE, I, reset)

 begin

 if (reset = '1') then

 NEXT_STATE <= E0;

 O <= '0';

 else



```
case CURRENT_STATE is
  WHEN E0 =>
    if (I='1') then
      NEXT_STATE <= E1;
    else
      NEXT_STATE <= E0;
    end if;
    O<= '0';
```

```
  WHEN E1 =>
    if (I='1') then
      NEXT_STATE <= E2;
    else
      NEXT_STATE <= E0;
    end if;
    O<= '0';
```



```
WHEN E2 =>  
  if (I='1') then  
    NEXT_STATE <= E3;  
  else  
    NEXT_STATE <= E0;  
  end if;  
  O<= '0';
```

```
WHEN E3 =>  
  if (I='1') then  
    NEXT_STATE <= E4;  
  else  
    NEXT_STATE <= E0;  
  end if;  
  O<= '0';
```



```

        WHEN E4 =>
            if (I='1') then
                NEXT_STATE <= E4;
            else
                NEXT_STATE <= E0;
            end if;
            O<= '1';

        WHEN others =>
            assert('1')
            report "Illegal State";

    end case;
end if;
end process;

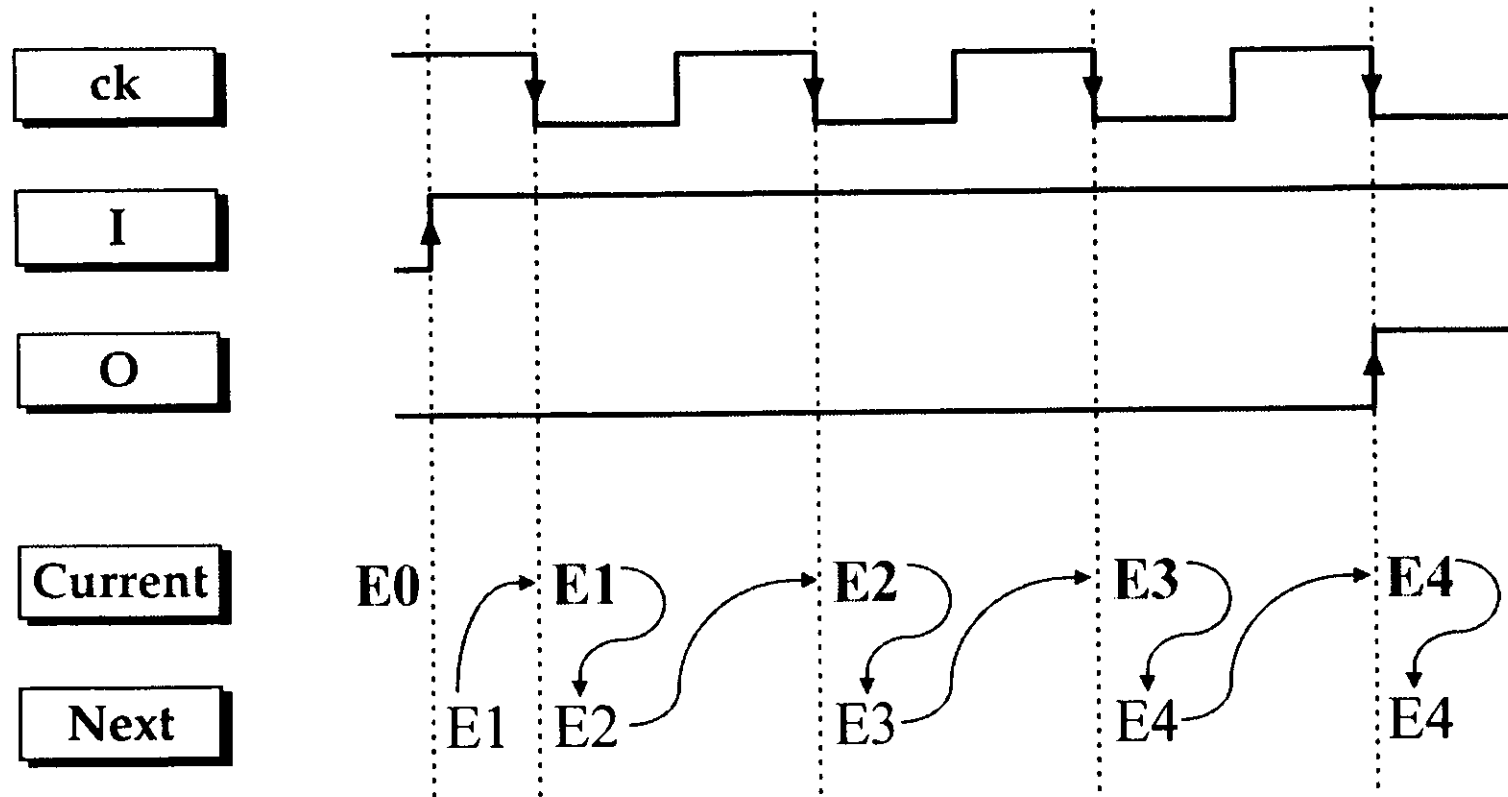
```



```
Process(ck)
begin
    if (ck = '0' and not ck'stable) then
        CURRENT_STATE <= NEXT_STATE;
    end if;
end process;
end counter;
```



FSM: THE FOUR CONSECUTIVE ONE'S COUNTER

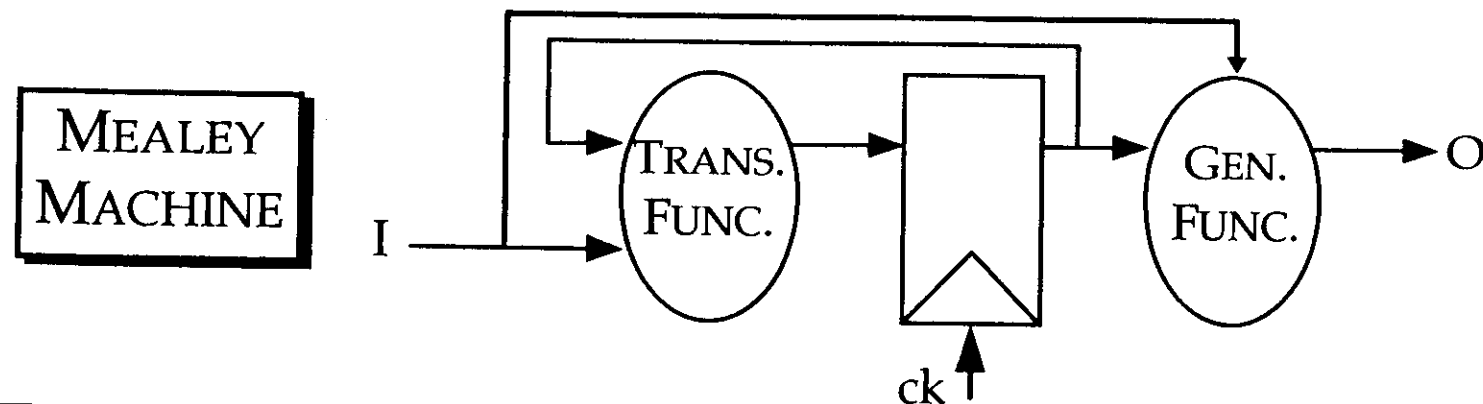
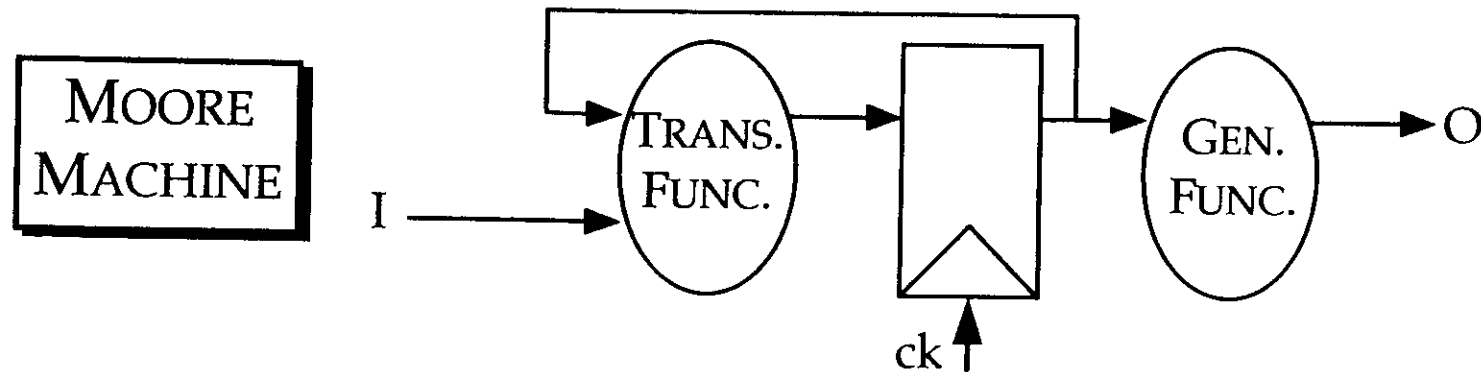


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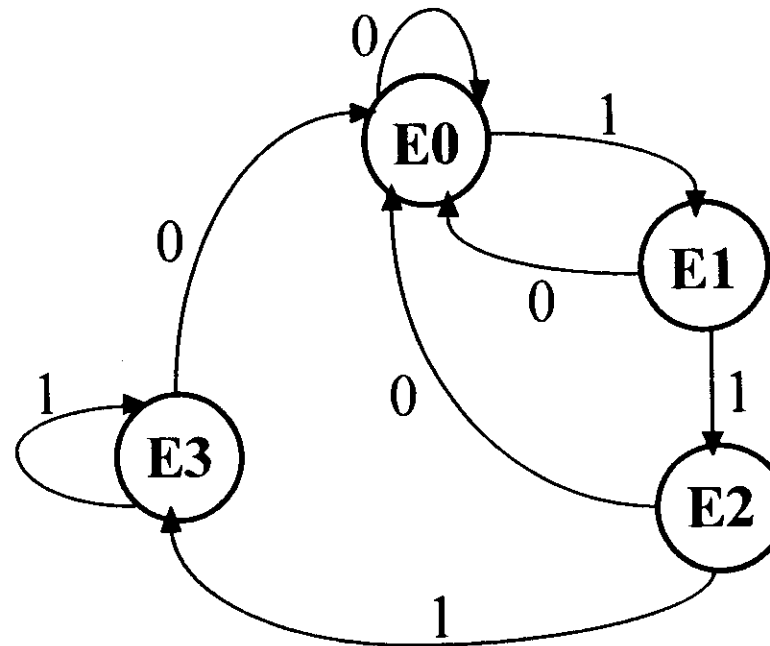
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FSM: DIFFERENT MACHINE'S TYPE



FSM: THE COUNTER WITH THE MEALEY MACHINE



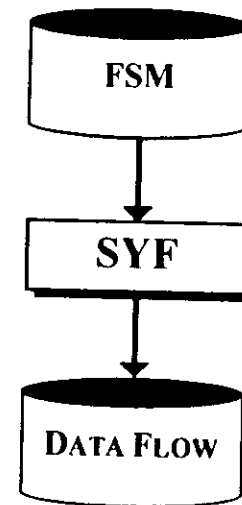
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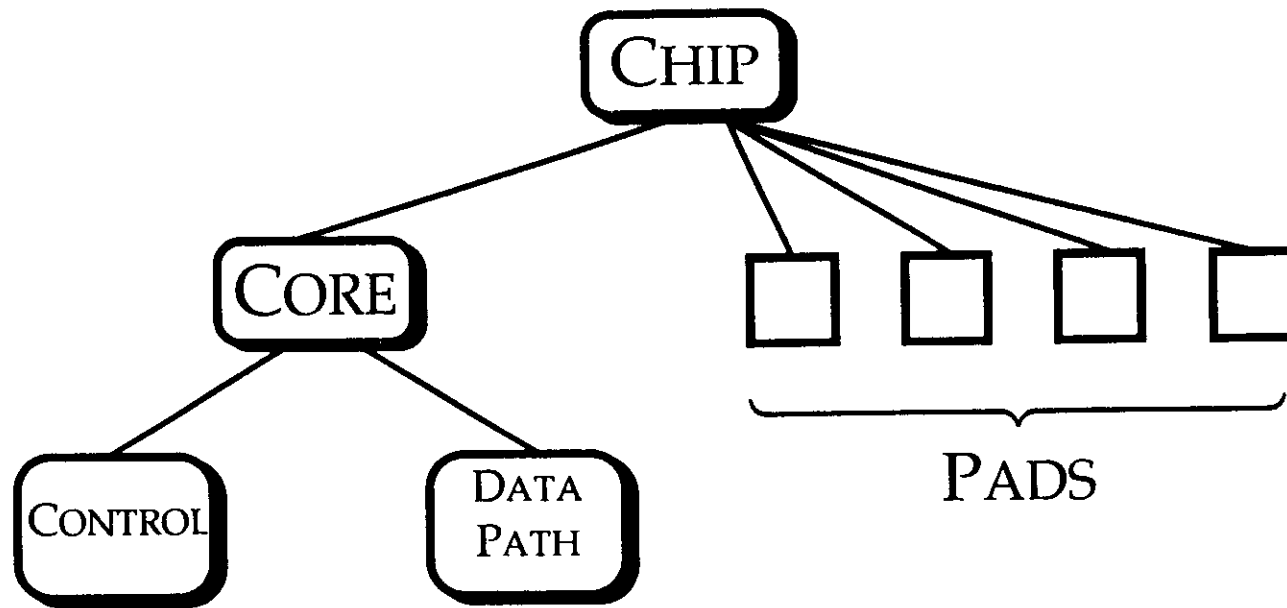
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SYF: AN FSM SYNTHESIZER

- VERIFICATION.
- ENCODING.
- OPTIMIZATION.
- DRIVING DATA FLOW DESCRIPTION.

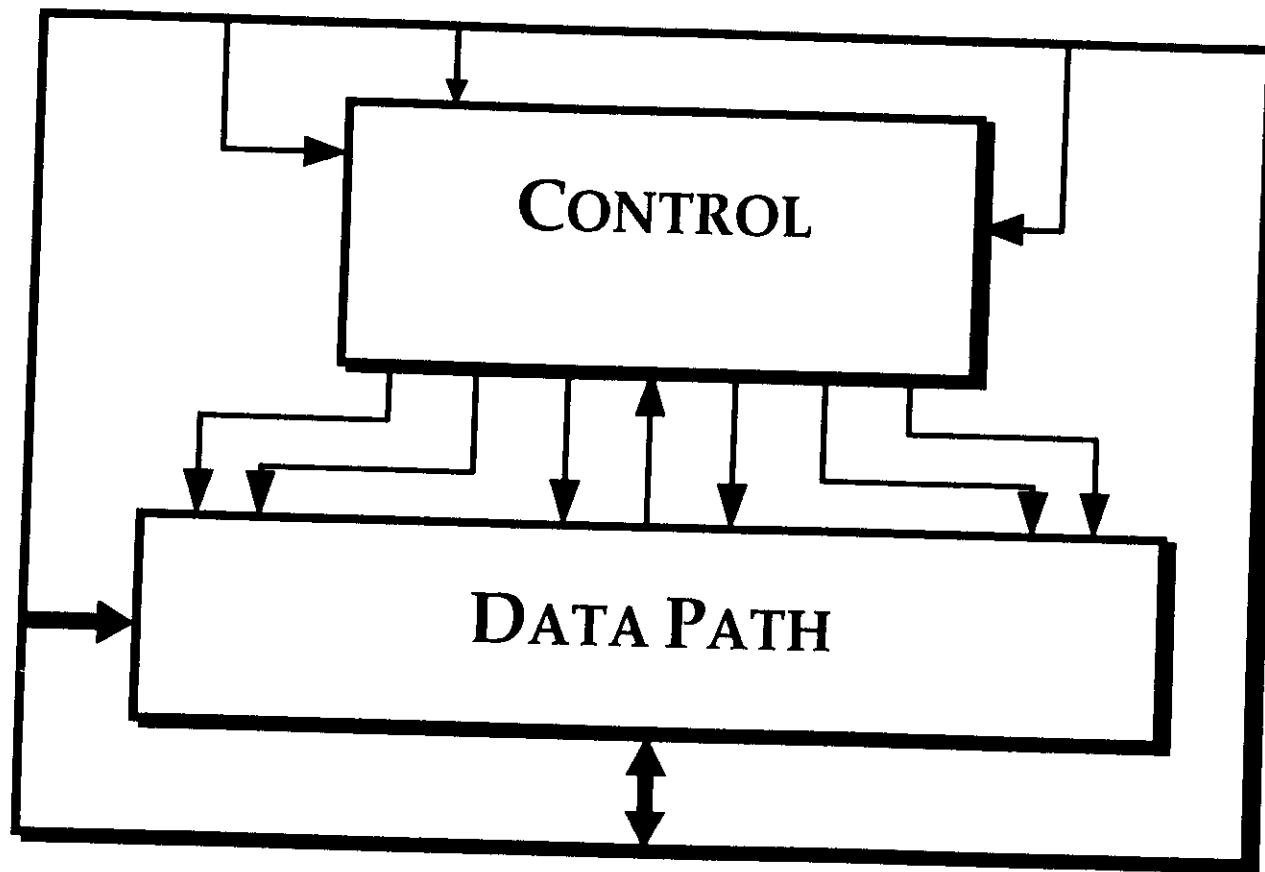




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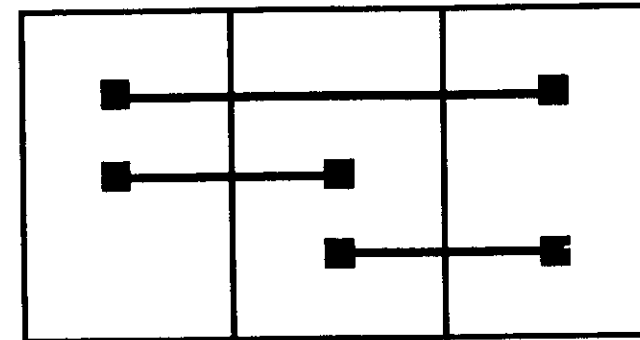
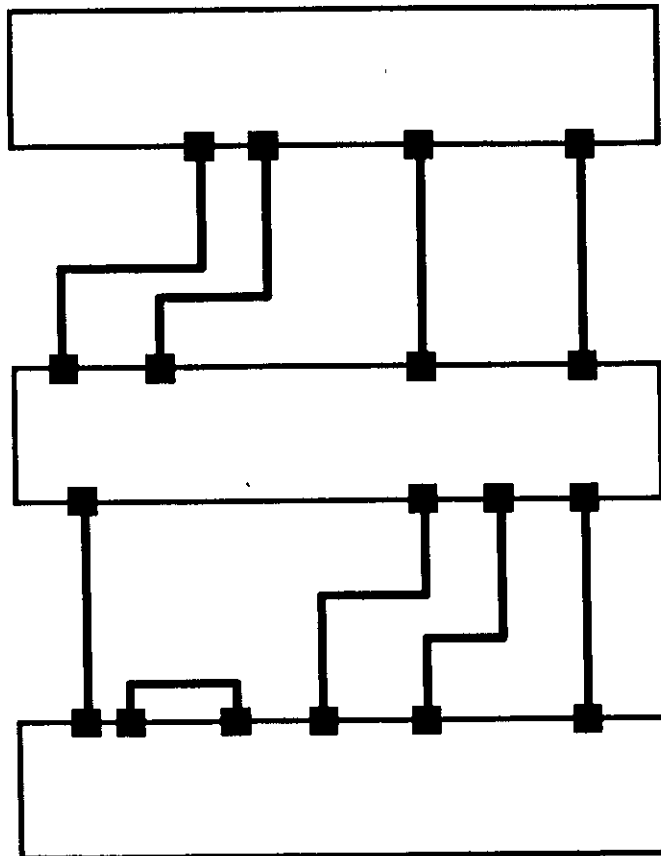
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STANDARD CELLS ROUTER VERSUS DATA PATH ROUTER

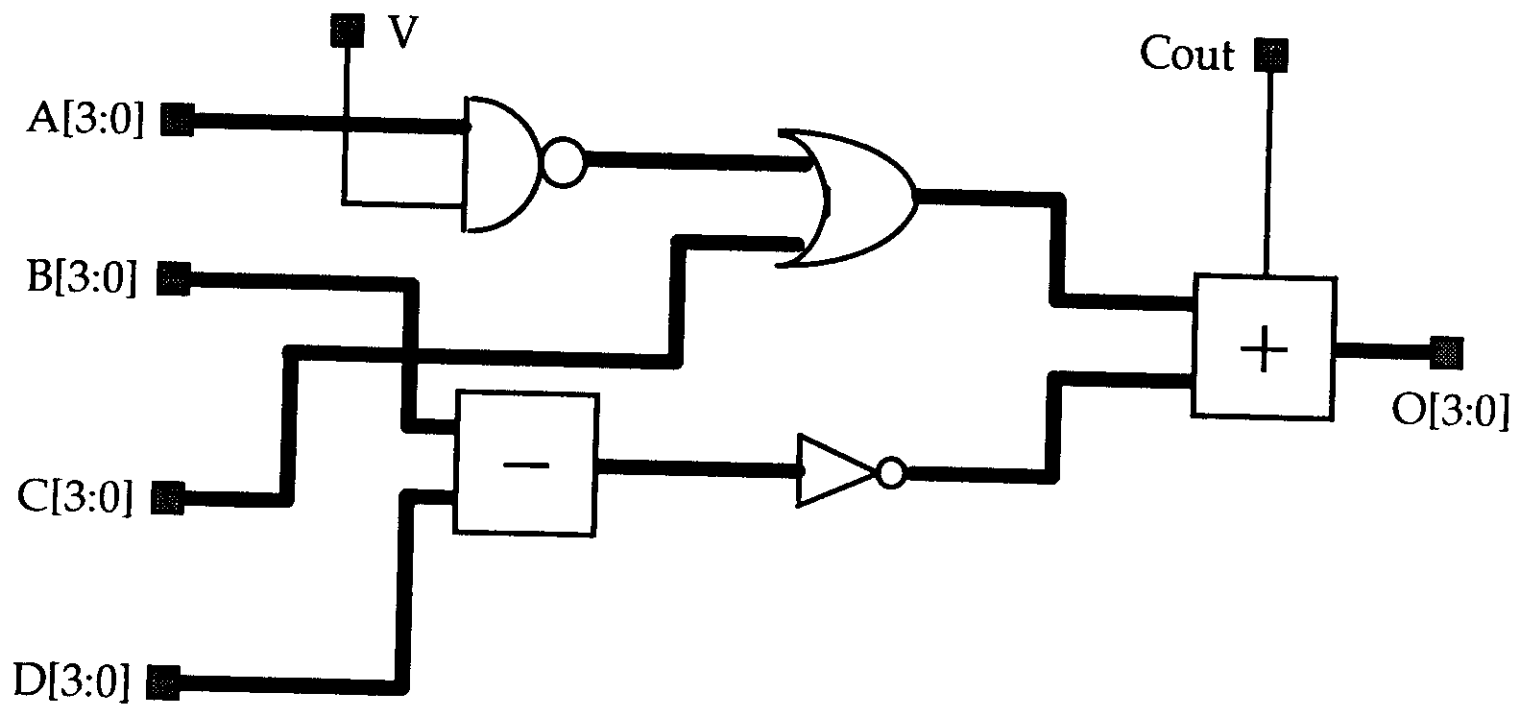


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DATA PATH: AN EXAMPLE (1)

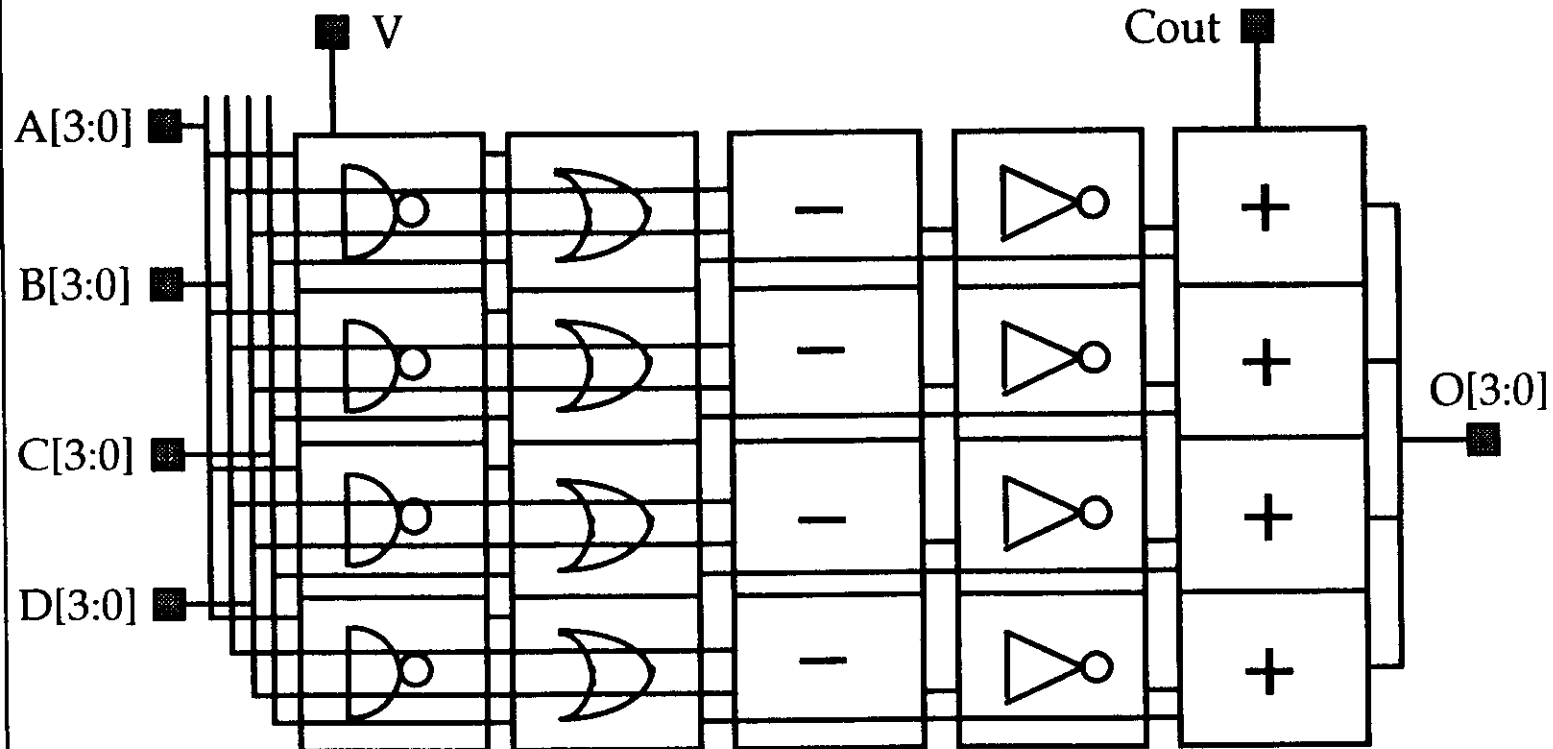


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DATA PATH: AN EXAMPLE (2)



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TIMING VERIFICATION

◆ SIMULATORS

- CIRCUIT-LEVEL.
- TIMING.
- SWITCH-LEVEL.
- LOGIC-LEVEL.

◆ VERIFIERS (PATTERN INDEPENDENT)

- TIMING.



It was a real pleasure working with you. I hope that our ALLIANCE tools will help you in teaching VLSI once back home and I look forward to your feedback.

Very truly yours...

Nizar



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