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UNITED NATIONS EDUCATIONAL SCIENTIFIC AND CULTURAL ORGANIZATION



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AUTUMN COLLEGE  
ON  
THE TROPOSPHERE, STRATOSPHERE AND MESOSPHERE  
10 September - 19 October 1984

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MICROWAVE DUCT PROPAGATION OVER THE SEA

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# INTRODUCTION

Radio waves propagating close to the earth's surface are strongly affected by atmospheric conditions giving rise to evaporation, advection and subsidence ducts. Models are given for evaporation and advection ducts but subsidence ducts are only described qualitatively. Field strength calculations involve geometrical optics, waveguide mode and parabolic equation methods. Finite difference mode methods are being developed for elevated ducts and parabolic equation methods for horizontally varying media. Waveguide mode calculations in the evaporation duct over a rough sea are presented and are in qualitative agreement with data.

# EVAPORATION DUCTS

These are shallow overwater surface ducts of order 5-15 m thick. At the sea surface the air is saturated but not usually at higher levels. This gives an approximately logarithmic decrease of water vapour pressure with height and is the primary cause of the evaporation duct. Close to the sea surface the modified and potential refractive indices  $n$  and  $n_p$  are related by

$$n = n_p + \frac{z}{Ka} \quad (1)$$

where  $z$  is height,  $a$  is the earth's radius and  $K = 1.205$  at the sea surface. Over small height intervals

$$n_p - n_{p0} = c(e_p - e_{p0}) + f(e - e_0) \quad (2)$$

$$c = \frac{.373}{T^2}, \quad f = -7.76 \times 10^{-5} \frac{P}{T^2} - .746 \frac{e}{T^3} \quad (3)$$

where  $e_p$  is the potential vapour pressure,  $e$  is the potential temperature,  $T$  is temperature,  $e$  is vapour pressure,  $P$  is pressure, and  $n_{p0}$ ,  $e_{p0}$  and  $e_0$  are the surface values. The theory of the constant flux surface layer is given by the Monin-Obukhov similarity theory (1). If  $s$  is  $e_p$  or horizontal wind speed  $u$ , then

$$s - s_0 = \frac{s_*}{\kappa s_0} \int_0^z \frac{dz_0}{z + z_0} \quad (4)$$

$$= \frac{s_*}{\kappa s_0} \left[ \ln \left( \frac{z+z_0}{z_0} \right) + \psi_s(z/L) \right]$$

$$s_* u_* = - \langle s'w' \rangle, \quad \frac{1}{L} = \frac{g(\theta_* + .38T_e/P)}{u_*^2} \quad (5)$$

in which  $L$  is the Monin-Obukhov stability length,  $s_0$  is the surface value of  $s$ ,  $s_*$  is a scale for  $s, s'$  and  $w'$  are the fluctuations in  $s$  and  $w$ , and  $w$  is the vertical wind speed.

If  $c$  and  $f$  are treated as constants, eqns. (2) and (4) show that  $s$  can stand for  $n_p$  with  $n_* = c s_* + f \theta_*$ . From measurements made by Businger et al (2)

$$* = .35, \quad \alpha_u = 1, \quad \alpha_\theta = \alpha_e = \alpha_n = 1.35 \quad (6)$$

$$\psi_u(x < 0) = (1-15x)^{-1/4}, \quad \psi_u(x > 0) = 1 + 4.7x \quad (7)$$

$$\psi_\theta(x < 0) = (1-9x)^{-1/4}, \quad \psi_\theta(x > 0) = 1 + 6.5x \quad (8)$$

$$\psi_\theta(x) = \psi_e(x) = \psi_n(x) \quad (9)$$

The  $\psi_s$  forms are found from eqn. (4). The  $z_s$  are related to neutral drag coefficients by  $C_s^{1/2} = \kappa s_0 / \ln(z/z_0)$ . For  $z = 10$  m, Kondo (3) gives  $C_s = C_e = C_n = 1.3 \times 10^{-3}$  whilst  $C_u \times 10^3$  is .96, 1.2, 1.4 and 1.8 when  $u = 2.2, 5, 8$  and  $25$  m/s. Combining eqns. (1), (2) and (4) gives for the  $m$ -profile

$$m - m_0 = \frac{1}{Ka} \left[ z - \frac{d}{\psi_n(d/L)} \int_0^z \frac{dz_0 \psi_n(z_0/L)}{z + z_0} \right] \quad (10)$$

$$d = - \frac{n_*}{\kappa a} \frac{Ka \psi_n(d/L)}{n} \quad (11)$$

where  $d$  is the duct thickness. The  $m$ -profile depends upon the two parameters  $d$  and  $L$ . Figure 1 shows it as a single family of curves with  $10^6(m-m_0)/d$  plotted against  $z/d$  for various values of  $d/L$ , where  $m_d = m(d)$ . One can determine  $d$  and  $L$  from simple measurements of  $u, \theta$  and  $e_p$  at height  $z$  and surface temperature  $\theta_0$ , with  $e_{p0}$  the saturation vapour pressure at  $\theta_0$  and  $u_0 = 0$ . With  $\xi = z/L$ ,  $L$  is found from

$$\xi_0 = \frac{\kappa g z}{c u} \left[ \theta - \theta_0 + .38T(e_p - e_{p0})/P \right] \quad (12)$$

$$\xi = \xi_0 \frac{[1 + \psi_u(\xi)/\ln(z/z_0)]^2}{[1 + \psi_\theta(\xi)/\ln(z/z_0)]} \quad (13)$$

$\xi_0$  is found from the measurements and  $\xi$ , and hence  $L$ , is then found by inverting eqn. (13) either graphically or by a simple algorithm. The scales  $s_*$ , including  $n_*$ , are found from eqn. (4) using the measured  $s-s_0$  and calculated  $L$ . The duct thickness  $d$  is then found by inverting eqn. (11). This method is sensitive to experimental errors. Wet and dry bulb, or equivalent, measurements must be made to  $\pm 0.1^\circ\text{C}$  and this is difficult in a marine environment. Similarity theory breaks down in strongly stable conditions and this increases sensitivity to errors. The theory is useless for

$d/L > .07$ . Information exists on evaporation duct statistics. Figure 2 shows mean values in metres for European waters. Monthly means of  $d(m)$  are strongly correlated with  $\theta_0(^\circ\text{C})$  with  $d = 1 + .4 \theta_0$ .

# ADVECTION DUCTS

The passage of warm well mixed air from land over a cooler sea leads to a modified layer near the surface within which humidity decreases while temperature increases with height forming an advection duct. In a model given by Mulhearn (4),  $\theta, e_p, n_p$  and  $u$  assume constant values  $\theta_1, e_{p1}, n_{p1}$  and  $u_1$  in the well mixed air mass over the land, and  $\theta_0, e_{p0}, n_{p0}$  and  $0$  at the sea surface. Over the sea a modified layer of height  $z_m$  grows with wind fetch  $x$  with the empirical form

$$\frac{z_m}{L_m} = .014 \left( \frac{x}{L_m} \right)^{.55} \quad (14)$$

$$\frac{1}{L_m} = \frac{g}{u_1^2} \left[ \frac{\theta_1 - \theta_0}{\theta_1} + \frac{.38(e_{p1} - e_{p0})}{P} \right] \quad (15)$$

where  $L_m$  is a bulk stability parameter. Within the modified layer  $\theta, e_p$  and  $n_p$  vary like  $z^{1/4}$  so the  $m$ -profile and duct thickness  $d$  are

$$m - m_0 = \frac{2}{Ka} + (n_{p1} - n_{p0}) \left[ H(z - z_m) + H(z_m - z) \left( \frac{z}{z_m} \right)^{1/4} \right] \quad (16)$$

$$d = z_m \min \left[ 1, \left\{ \frac{(n_{p0} - n_{p1}) \frac{Ka}{4z_m}}{1} \right\}^{4/3} \right] \quad (17)$$

where  $H(\cdot)$  is the unit step function. Figure 3(a) shows experimental  $M$ -profiles given by Unwin (5) whilst figure 3(b) shows  $M-M_0 = 10^6(m-m_0)$  from eqn. (16) with  $10^6(n_{p0} - n_{p1}) = 30$  and  $L_m = 1000$  m. A more elaborate model has been given by Gossard (6) when the air mass over land is stably stratified.

# SUBSIDENCE INVERSIONS

In a high pressure system the frictional outflow of air near the surface is accompanied by a slow subsidence of air from a high level towards the high pressure centre. The surface friction layer forms a base for the subsidence at which marked gradients occur. Temperature increases whilst humidity usually decreases through the inversion because the air from higher levels is very dry. This often causes an elevated duct. Some interesting examples have been given by Flavell (7) and data is given by Dougherty and Hart (8).

# CALCULATION OF FIELD STRENGTH

## Geometrical Optics

At short distances geometrical optics may be used. For a plane stratified medium Snell's law gives  $m(z) \sin \theta = S$  where  $S$  is a constant for each ray and  $\theta$  is the angle to the vertical. Ray tracing methods follow from simple geometry. Figure 4 is an example given by Davies and Evans (9). The ray equations often have multiple solutions giving caustics and cusps where ray theory breaks down. Uniform approximations can be used in these cases but the results are complex. For a transmitter in a surface duct, two kinds of

caustics meet in cusps and are designated interior and exterior by Hartree (10), as shown in figure 5.

# Waveguide Mode Theory.

Formulation. As shown by Budden (11), the field at greater distances is given by an infinite sum of independently propagating waveguide modes proportional to

$$\frac{1}{D^2} \sum_n e^{-ik_0 S D} \frac{g(z_n, S) g(z_p, S)}{g(0, S) g(D, S)} \left[ \frac{\partial g}{\partial S}(0, S) \right]^{-1} \quad (18)$$

where  $D$  is range,  $k_0$  is the free space wave-number,  $z_t$  and  $z_p$  are the terminal heights, and  $g(z, S)$  is the height-gain function, the outgoing wave solution of

$$\frac{d^2 g(z, S)}{dz^2} = -k_0^2 q^2(z, S) g(z, S) \quad (19)$$

$$= -k_0^2 [m^2(z) - S^2] g(z, S)$$

The wave impedance  $\psi(z, S) = \partial \ln g(z, S) / \partial z$  satisfies the boundary condition  $\psi(0, S) = ik_0 \zeta$  where  $\zeta = (n_e^2 - 1)^{1/2}$  for horizontal and  $\zeta = (n_e^2 - 1)^{1/2} / n_e^2$  for vertical polarisation with  $n_e$  the refractive index of the earth. The solutions are the complex values  $S = S_n (n = 1, 2, \dots)$  which are usually ordered by increasing attenuation.

# Phase integral and comparison equation methods.

For simple problems such as surface ducts, phase integral (WKB) methods may be used. These often give useful analytic approximations. Higher order approximations using the comparison equation method are given by Rotherham (12).

Initial value methods. An iterative initial value method (11) employs the Riccati equation satisfied by the impedance  $\psi(z, S)$  or reflection coefficient  $R(z, S) = (ik_0 q + \psi)/(ik_0 q - \psi)$ . This satisfies the boundary condition

$$R_0(S) R(0, S) = 1 \quad (20)$$

where  $R_0(S) = [q(0, S) - \zeta]/[q(0, S) + \zeta]$ . A value of  $S$  is chosen,  $R(z, S)$  is calculated at great heights using the WKB approximation, the Riccati equation is integrated to the surface to give  $R(0, S)$ , and Newton's method is used to recalculate  $S$  from eqn. (20).

Continuation method. Solving eqn. (20) can be quite tricky. It is easy to miss eigenvalues and the initial value of  $S$  must be close to  $S_n$ . A better method is to define a complex wavenumber  $v(S)$  such that  $v(S_n) = n$ . One such mapping is

$$R_0(S) R(0, S) = e^{-2i\pi v(S)} \quad (21)$$

Solving eqn. (20) amounts to finding  $S(v)$ , the inverse of  $v(S)$ . One technique is to turn eqn. (21) into a differential equation. A value of  $S$  is chosen,  $v$  is found from eqn. (21) and the differential equation is integrated numerically to  $v = 1, 2, \dots$  to find  $S(1), S(2)$  etc. If  $R_0(S)$  or  $R(0, S)$  have poles or zeros, the  $v$ - $S$  mapping is not single valued. This

is discussed by Budden (13) in the context of mode degeneracy. Surface duct propagation over a rough surface is an example.

**Finite difference methods.** Because of these problems a finite difference method is being developed. The infinite height range is transformed to a finite interval by, for example,  $x = \exp(-z/z_0)$  where  $z_0$  is a suitable scale height. The differential equation and boundary conditions are replaced by finite difference approximations giving a matrix eigenvalue problem. About 10N points must be used to give N accurate eigenvalues for simple m-profiles.

**2-dimensional refractive index problems.** For the 2 or 3-D problem, coupled mode methods are given by Wait (14) but these are rather complicated. Non-mode methods involving the parabolic wave equation have been used by Tappert (15) in underwater acoustics and these are being studied for radio problems such as the advection duct.

**Evaporation duct results.** An evaporation duct program has been written using a combination of phase integral, comparison equation, shooting and continuation methods. A rough sea is included by replacing  $R_0(S)$  by  $R_0(S)\exp[-2k_0^2 \sigma^2 q(0,S)^2]$  where  $\sigma$  is the r.m.s. roughness.

**Attenuation.** This is  $\mu_n = .0086 k_0 \text{ Im } S_n$  dB/km for mode number n. Figure 6 shows  $(d/10)^{1/2} \mu_1$  plotted against  $(d/10)^{3/2} f$  for a series of values of  $\sigma/d$ , with  $f(\text{GHz})$  the frequency and  $d(\text{m})$  the duct thickness and neutral stability ( $1/L=0$ ). As  $f$  increases,  $\mu_1$  decreases as the mode becomes more trapped, but eventually increases because of surface roughness. It tends to a value of about .5 though with an overshoot that for  $\sigma/d < .04$  involves an interchange with higher modes, an example of degeneracy (13). For large  $f$  the reflected wave is destroyed and the mode structure is as if the earth had been removed.

**Height-gain.** Figure 7(a) shows  $g(S_1, z)/g(S_1, d)$  for neutral stability ( $1/L=0$ ) and a smooth sea ( $\sigma=0$ ) and values of  $(d/10)^{3/2} f$  GHz. As this increases the mode becomes trapped and energy concentrates in the duct. Figure 7(b) is for  $(d/10)^{3/2} f = 15$  GHz. and roughnesses  $\sigma/d = 0, .05$  and .1 showing how the roughness destroys the trapped mode.

**Comparison with experiment.** Figure 8 shows measurements in the Baltic made by Hamburg University compared with theoretical predictions for neutral stability and various roughnesses. The qualitative features of the data are well predicted.

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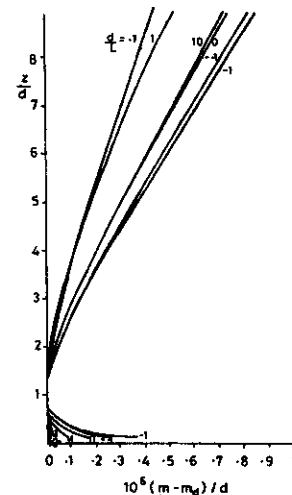


Figure 1 Variation of modified refractive index m with height z, duct thickness d and stability L.

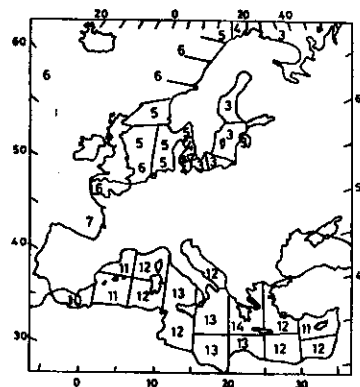


Figure 2 Mean evaporation duct thickness  $d(\text{m})$  in European waters.

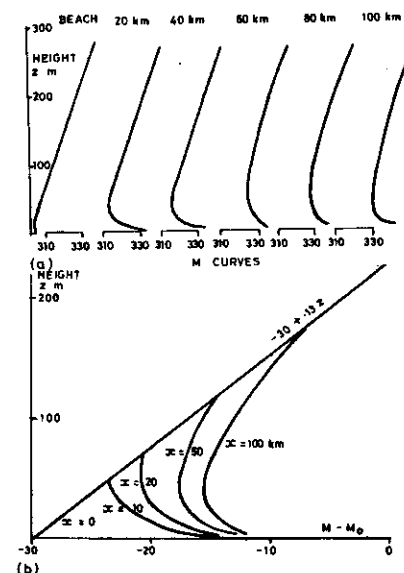


Figure 3 Experimental (a) and theoretical (b) profiles of modified refractivity M.

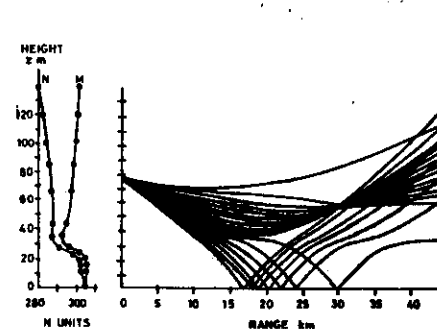


Figure 4 Ray paths in an elevated duct.

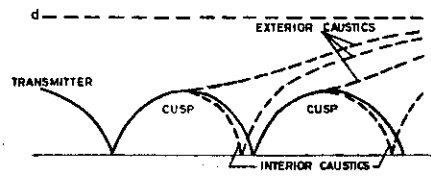


Figure 5 Formation of a set of caustics and cusps in a surface duct.

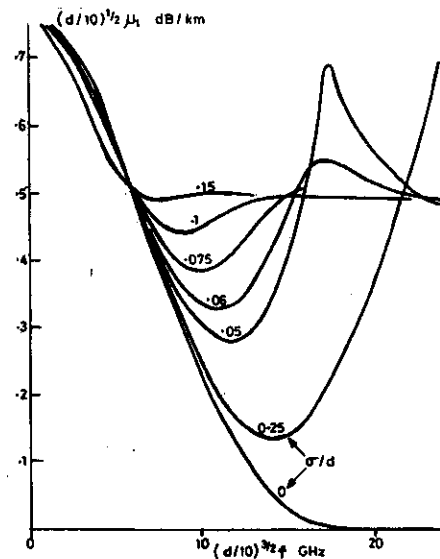


Figure 6 First mode attenuation  $\mu_1$  (dB/km) as a function of  $f$  (GHz),  $d$  (m) and  $\sigma$  (m) Neutral stability ( $1/L=0$ ).

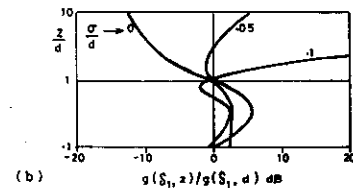
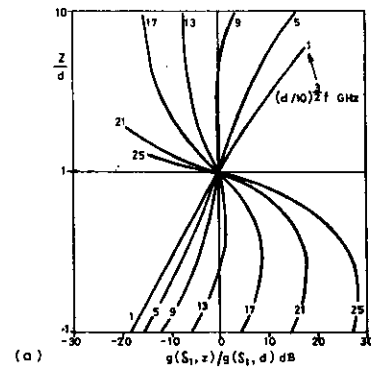


Figure 7 Height-gain functions. Variations with (a)  $d$  (m) &  $f$  (GHz) for  $1/L=0$  &  $\sigma=0$ . (b)  $\sigma$  for  $(d/10)^{3/2} f = 15$  GHz.

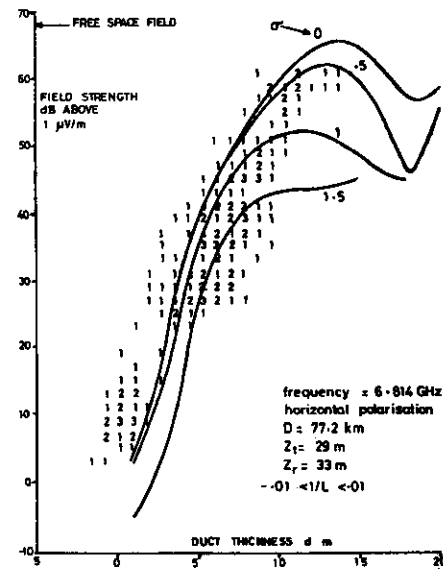


Figure 8 Theoretical and experimental field strength-duct thickness relations for near-neutral stability.