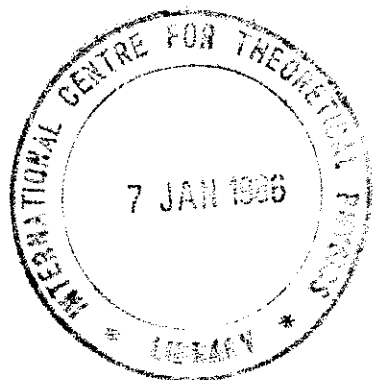




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COLLEGE ON
REPRESENTATION THEORY OF LIE GROUPS
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Supplement to "HARMONIC ANALYSIS ON COMPACT LIE GROUPS"

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These are preliminary lecture notes, intended only for distribution to participants.

G linear.

$$\begin{aligned} \text{Ad } g \zeta &= d\text{ad}_g(\zeta) = \left. \frac{d}{dt} \text{ad}_g(\exp t\zeta) \right|_{t=0} \\ &= \left. \frac{d}{dt} g \exp t\zeta g^{-1} \right|_{t=0} \\ &= \left. \frac{d}{dt} \exp t\zeta g^{-1} \right|_{t=0} \\ &= \zeta g^{-1}, \quad g \in G \end{aligned}$$

M connected. If M is orientable, can partition the n -forms without zeros into 2 classes i.e. if β, γ are non-zero n -forms $\gamma = f\beta$ for a function f . Say that $\beta \sim \gamma$ if $f > 0$, ~~or~~ ~~either~~ ~~or~~ if not then $\beta \sim -\gamma$ i.e. there are two equivalence classes. Choosing one of these classes is called an orientation of M . The forms in this class are called oriented forms.

A chart (U, ϕ) at x is called oriented if $dx^1 \wedge \dots \wedge dx^n$ is oriented i.e. if β is an oriented n -form on M and $\beta|_U = g dx^1 \wedge \dots \wedge dx^n$, then $g > 0$ on U . Now if (V, ψ) is another chart at x one has under change of coordinates

$$dy^1 \wedge \dots \wedge dy^n = \det \left(\frac{\partial y^i}{\partial x^j} \right) dx^1 \wedge \dots \wedge dx^n$$

so if this chart is also oriented we have $\det \left(\frac{\partial y^i}{\partial x^j} \right) > 0$.
Lebesgue measure on $\mathbb{R}^n$ transforms

$$dy^1 \wedge \dots \wedge dy^n = \left| \det \frac{\partial y^i}{\partial x^j} \right| dx^1 \wedge \dots \wedge dx^n \quad \text{on change of}$$

coordinates. These two formulae agree on oriented charts.

Suppose $\beta \in \Lambda^n(M)$ with $\text{supp } \beta \subseteq U$, (U, ϕ) oriented so $\beta|_U = f dx^1 \wedge \dots \wedge dx^n$ on U with $\text{supp } f \subseteq U$
 $\text{supp } f = \{x; f(x) \neq 0\}$. Can regard $f \circ \phi^{-1}$ as a compactly supported function on $\mathbb{R}^n$. Define

$$\int_M \beta = \int_{\mathbb{R}^n} f \circ \phi^{-1} dx^1 \wedge \dots \wedge dx^n \quad \text{rhs independent of oriented chart.}$$

For any β cover M with oriented charts and use partition of unity argument.

Finite dimensional representation

$$\pi: G \longrightarrow GL(V) \quad \text{with differential}$$

$$\pi_*: \mathfrak{g} \longrightarrow \mathfrak{gl}(V)$$

$$\pi_*(\xi) = \left. \frac{d}{dt} \pi(\exp t\xi) \right|_{t=0} \quad \text{is the infinitesimal generator}$$

of the 1-parameter subgroup; and $\pi_* \in \mathfrak{g}^* \otimes \mathfrak{gl}(V)$.

Now w.r.t a basis of V each matrix element of π may be differentiated by the exterior derivative d to get a 1-form on G i.e. $d\pi$ is a $\mathfrak{gl}(V)$ valued 1-form on G i.e.

$$d\pi \in \mathcal{L}'(G) \otimes \mathfrak{gl}(V). \quad \text{The left invariant 1-forms } \mathcal{L}'_2(G)$$

may be identified with $\mathfrak{g}^*$, by ω left invariant 1-form

$$\omega(\xi) = \omega(e) \xi(e), \quad e \text{ the identity element of } G \text{ and}$$

$$\mathcal{L}'_2(G) \text{ may be identified with } \mathcal{X}(G) \longrightarrow C^\infty(G) \text{ by}$$

$$\omega \text{ a 1-form, } \omega(\xi)(g) = \omega(g) \xi(g) \quad \xi \text{ a vector field on } G.$$

If $f \in C^\infty(G)$,
we have $d f(\xi)(g) = \xi f(g) = \left. \frac{d}{dt} f(g \exp t\xi) \right|_{t=0}, \quad \xi \in \mathfrak{g}$

$$\text{Thus } d\pi(\xi)(e) = \pi_*(\xi), \quad \xi \in \mathfrak{g} \text{ and more generally}$$

$$d\pi(\xi)(g) = \pi(g) \pi_*(\xi), \quad g \in G$$

$$\text{Matrix group } G. \quad G \xrightarrow{X} GL(n, \mathbb{C})$$

Let $\Omega = X^{-1} dX$. Regard Ω as a $\mathfrak{gl}(n, \mathbb{C})$ valued 1-form i.e. $\Omega \in \mathcal{L}'(G) \otimes \mathfrak{gl}(n, \mathbb{C})$.

Lemma

Under left translations, $l_g^* \Omega = \Omega$, $g \in G$
i.e. Ω is a matrix of left invariant 1-forms.

Proof

$$\begin{aligned} (l_g^* \Omega)(g_1) \xi(g_1) &= \Omega(gg_1) l_{g*} \xi(g_1) = \Omega(gg_1) \xi(gg_1) \\ &= X(g_1)^{-1} X(g)^{-1} dX(gg_1) \xi(gg_1) \end{aligned}$$

$$\text{Now } dX(gg_1) \xi(gg_1) = X(g) dX(g_1) \xi(g_1), \quad g \in G, \xi \in \mathfrak{g} \quad \square$$

$\mathbb{R}$ addition left invariant 1-form is $c dx$

$\mathbb{R}^{\times}$ multiplication $l_a: x \mapsto ax \quad \frac{dx}{x} \mapsto \frac{a dx}{ax} = \frac{dx}{x}$

affine group of $\mathbb{R} \quad x \mapsto ax+b$

$$l_{(g,h)}(a,b)(x) = g(ax+b) + h = gax + gb + h$$

1-forms $g(a,b) da + g(b) db$

left invariant 1-forms have basis $\frac{da}{a}, \frac{db}{b}$

left invariant 2-form $\frac{da \wedge db}{a^2}$

$$SL(2, \mathbb{R}) \quad X = \begin{pmatrix} w & x \\ y & z \end{pmatrix}, \quad X^{-1} = \begin{pmatrix} z & -x \\ -y & w \end{pmatrix}$$

$$dX = \begin{pmatrix} dw & dx \\ dy & dz \end{pmatrix} \quad \Omega = \begin{pmatrix} z dw - x dy & z dx - x dz \\ -y dw + w dy & -y dx + w dz \end{pmatrix}$$

$$\det X = 1 \quad wz - xy = 1$$

$$z dw + w dz - x dy - y dx = 0 \text{ is } \text{tr } \Omega = 0$$

basis for left invariant 1-forms is

$$\omega_1 = z dw - x dy, \quad \omega_2 = z dx - x dz, \quad \omega_3 = -y dw + w dy$$

left invariant 2-forms have basis $\omega_1 \wedge \omega_2, \omega_1 \wedge \omega_3, \omega_2 \wedge \omega_3$

left invariant 3-form is $\omega_1 \wedge \omega_2 \wedge \omega_3$

$$= z dw \wedge dx \wedge dy + x dw \wedge dy \wedge dz$$

$$SU(2) \quad X = \begin{pmatrix} x & y \\ -\bar{y} & \bar{x} \end{pmatrix} \quad |x|^2 + |y|^2 = 1, \quad X^{-1} = \begin{pmatrix} \bar{x} & -y \\ \bar{y} & x \end{pmatrix}$$

$$dX = \begin{pmatrix} dx & dy \\ -d\bar{y} & d\bar{x} \end{pmatrix}, \quad \Omega = \begin{pmatrix} x dx + y d\bar{y} & x dy - y d\bar{x} \\ \bar{y} dx - x d\bar{y} & \bar{y} dy + x d\bar{x} \end{pmatrix}$$

$$x\bar{x} + y\bar{y} = 1 \text{ is } x d\bar{x} + \bar{x} dx + \bar{y} dy + y d\bar{y} = 0, \text{ so } \text{tr } \Omega = 0;$$

$$\text{also } \Omega + \bar{\Omega}^T = 0.$$

$$SL(n, \mathbb{R}) \quad X = (x_{ij}), \quad (\text{adj } X)_{ij} = X_{ji}; \quad \det X = 1 = \sum_j x_{jj} X_{jj} = d_{jj}$$

$$c = d(\det X) = \sum_{i,j} dx_{ij} X_{ji} = \text{tr}(X^{-1} dX)$$

left invariant 1-forms spanned by those in Ω with $\text{tr } \Omega = 0$.

$$SO(n) \quad X^T X = I, \quad (dX)^T X + X^T dX = 0 \text{ is } \Omega + \Omega^T = 0$$

$$U(n) \quad \Omega + \bar{\Omega}^T = 0$$

$$SP(n) \quad \Omega J + J \Omega^T = 0$$

Maurer-Cartan equations $d\Omega = -\Omega \wedge \Omega$

Proof

$$0 = d(XX^{-1}) = dX X^{-1} + X dX^{-1} \quad \text{and} \quad dX^{-1} = -X^{-1} dX X^{-1}$$

$$d(X^{-1} dX) = dX^{-1} \wedge dX = -X^{-1} dX \wedge X^{-1} dX$$

affine group of $\mathbb{R}$ $X = \begin{pmatrix} a & b \\ 0 & 1 \end{pmatrix}$

$$dX = \begin{pmatrix} da & db \\ 0 & 0 \end{pmatrix}, \quad X^{-1} = \begin{pmatrix} a^{-1} & -a^{-1}b \\ 0 & 1 \end{pmatrix}$$

$$\Omega_L = X^{-1} dX = \begin{pmatrix} a^{-1} da & a^{-1} db \\ 0 & 0 \end{pmatrix}$$

$$\Omega_R = \frac{dX dX^{-1}}{dX X^{-1}} = \begin{pmatrix} a^{-1} da & -a^{-1} b da + db \\ 0 & 0 \end{pmatrix}$$

left invariant 1-forms have basis $\frac{da}{a}, \frac{db}{a}$

2-form $\frac{da \wedge db}{a^2}$

right invariant 1-forms have basis $\frac{da}{a}, \frac{b da}{a} - db$

2-form $\frac{da \wedge db}{a}$ not unimodular

$$\Omega_R X = -\Omega_L X^{-1}$$

Proof

$$\Omega_L X^{-1} = X dX^{-1} = -X X^{-1} dX X^{-1} = -\Omega_R X$$

Poincaré group $X = \begin{pmatrix} A & x \\ 0 & 1 \end{pmatrix}, \quad A \in SO(3)$

$$X^{-1} = \begin{pmatrix} A^{-1} & -A^{-1}x \\ 0 & 1 \end{pmatrix}, \quad dX = \begin{pmatrix} dA & dx \\ 0 & 0 \end{pmatrix}$$

$$\Omega_L = \begin{pmatrix} A^{-1} dA & A^{-1} dx \\ 0 & 0 \end{pmatrix}, \quad \Omega_R = \begin{pmatrix} dA A^{-1} & -dA A^{-1} x + dx \\ 0 & 0 \end{pmatrix}$$

