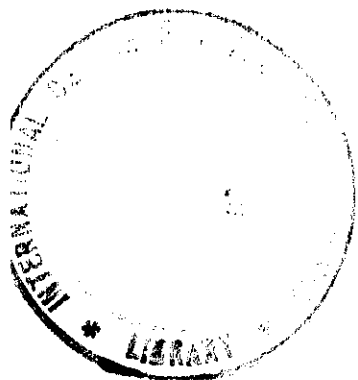




INTERNATIONAL ATOMIC ENERGY AGENCY
UNITED NATIONS EDUCATIONAL, SCIENTIFIC AND CULTURAL ORGANIZATION



INTERNATIONAL CENTRE FOR THEORETICAL PHYSICS
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SMR/208 - 12

SPRING COLLEGE IN MATERIALS SCIENCE

ON

"METALLIC MATERIALS"

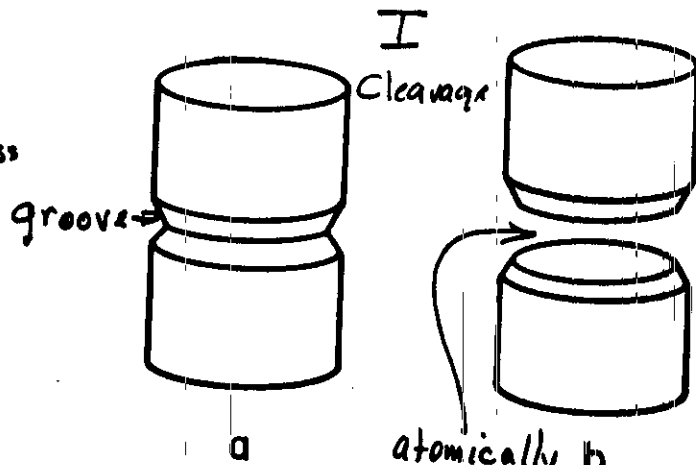
(11 May - 19 June 1987)

PHYSICAL UNDERSTANDING OF FRACTURE

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National Bureau of Standards
Gaithersburg, Maryland 20899
U.S.A.

These are preliminary lecture notes, intended only for distribution to participants.

mica
SiO₂ glass
Si
Diamond
etc.

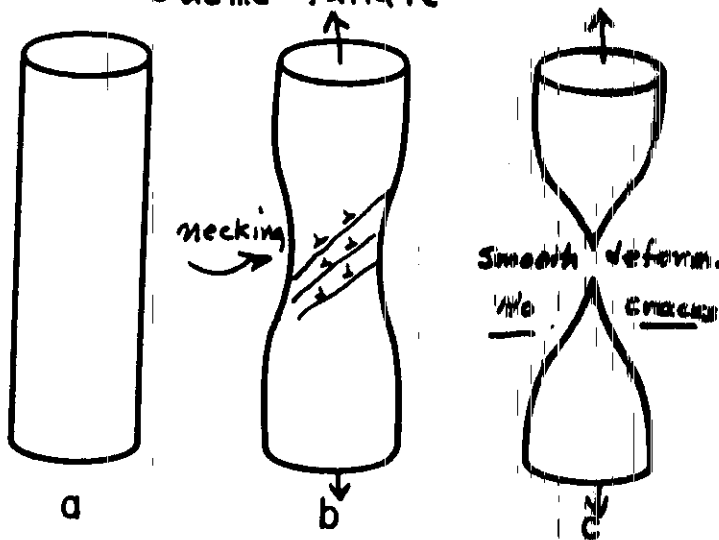


atomically smooth cleavage
(No dislocations or other defect formation)

Failure Bipolarity

II Ductile failure

"butter"
pure Cu, Al,
etc.



Bipolarity

Brittle
High Strength

St, C, mica
etc.

Ductile
High Toughness

pure Cu, Au,
Al, etc.

technological
materials balanced
between high
strength + toughness

Balance shifts with:

Strain rate
Temperature
chemical environment
microstructure

Yield-Deformation

Fundamental Problem:

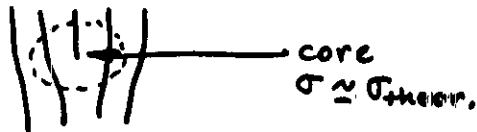
- Why do crystals yield at average stresses much less than bond strength?

Dislocations exist in crystal.

$\sigma \sim \sigma_{\text{theor.}}$ in core

translation carries core across entire
xtal

translation requires very small σ .



Fracture

Fundamental Problem

- Why do materials crack when average stress is less than bond strength?

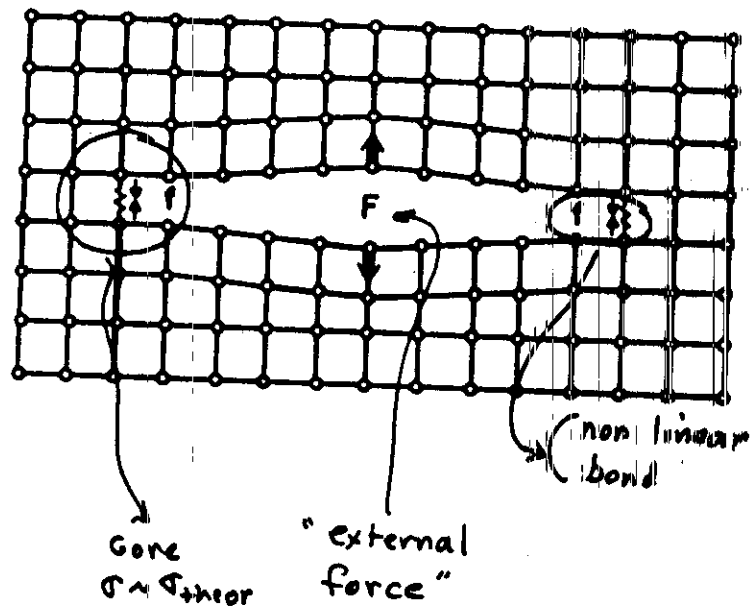
Cracks exist

$\sigma \sim \sigma_{\text{theor}}$ in core

translation carries core across
crystal with small external
force. result is bifurcation!

Dislocations and cracks are "dual" lattice defects (i.e. fundamental lattice defects!) which together determine the ultimate questions of strength and failure of all materials. <what about amorphous mats ??>

Schematic Model of a Crack



Note: a crack can only exist when an "external" force holds open its cleavage surfaces! (unlike dislocation)

Theoretical Strength of Solids

("Strong Solids")

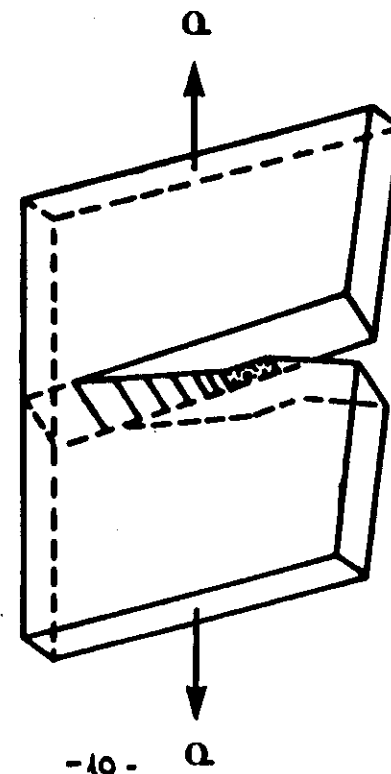
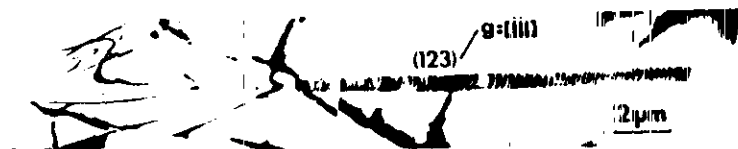
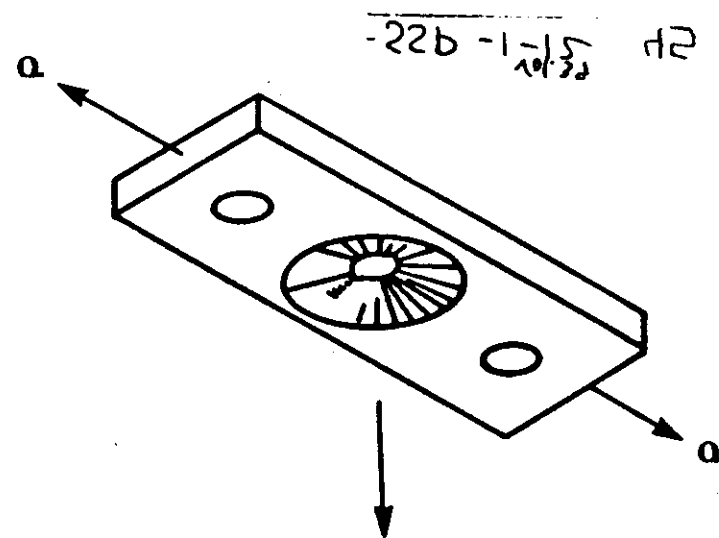
by
A. Kelly)

	μ	σ_m (shear)	E	σ_m (tension)
C	50	12	121	20.8
Al ₂ O ₃	15	1.7	46	4.6
Si	6	1.4	1.0	0.14
NaCl	2	.3	4.4	0.43
Cu	3	.13	[19.2	3.9] <101>
Ag	2	.07	6.7	2.5] <100>
Al	2	.09	12.1	2.4
Zn	4	.2	—	—
Fe	6	.66	26.0	4.6 <111>
			13.2	3.0 <100>

$$\frac{\sigma_{shear}}{\mu} = \begin{matrix} 0.04 & \text{Ag} \\ 0.24 & \text{C} \end{matrix} \}$$

$$\frac{\sigma_{tension}}{E} = \begin{matrix} 0.2 & \text{Ag} \\ 0.2 & \text{C} \end{matrix}$$



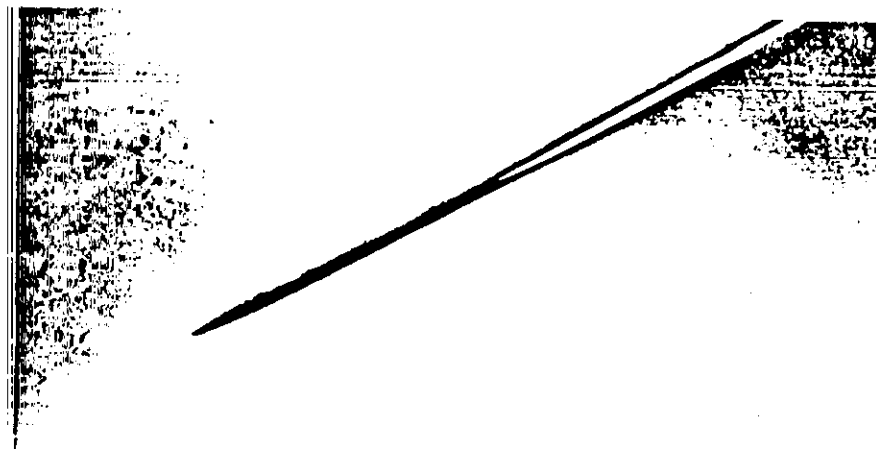




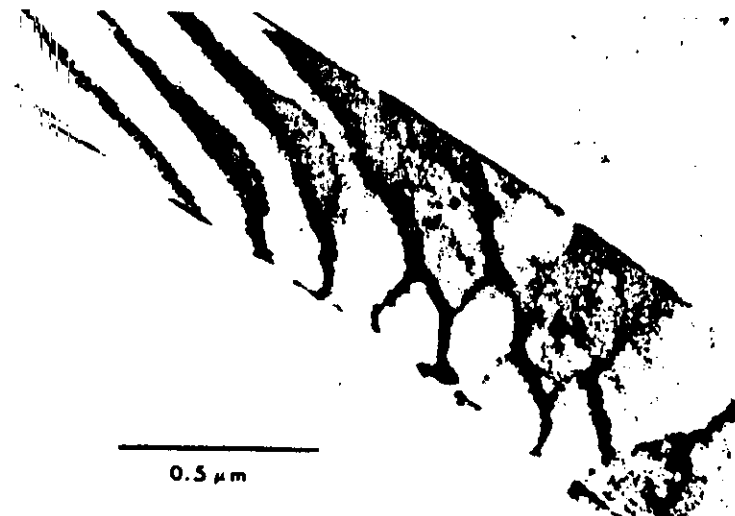
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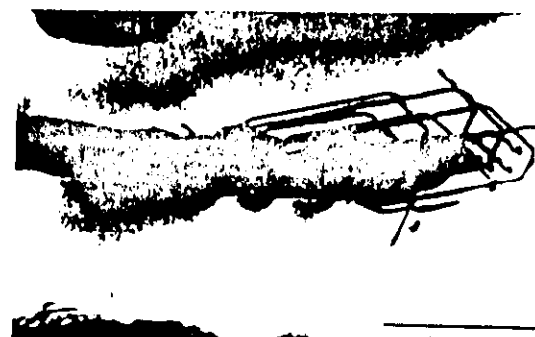
-11-



100 nm



0.5 μ m



-12-

Experimental Background

1. Real failure is very complicated!
2. Modelling done on basis of
 - a) 2-D
 - b) elasticity (isotropic)
 - c) simple atomic lattices
3. Basic Concepts.
 - Interplay between cracks + dislocations
 - Chemical effects on structure of tip
 - Structure of tip determines the ultimate matl. behavior

Morphology/Mechanism Relationship

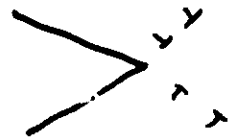
Cleavage

- Bond breaking at Tip
(Cleavage Criterion required)
- Dynamic mobility
Low toughness
- Shielded by Xlocs.



Wedge

- advances by Xloc emission
(emission criterion required)
- shielded by Xlocs.
- Hi toughness



Notch

- Blunts - does not advance (Hi Tough)
- No singularity at tip
No emission
No cleavage
No shielding
- Absorbs Xlocs from sources
- Fracture by plastic hole growth.

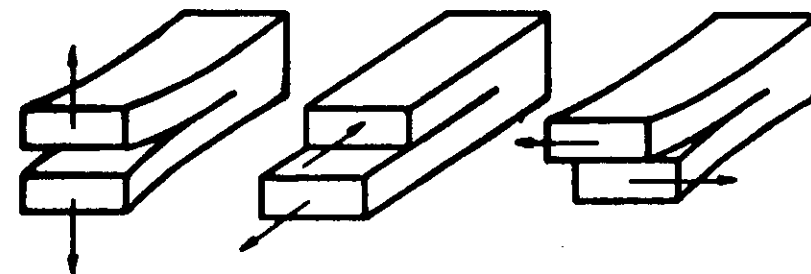


Hints for Theory

1. Interplay between Cracks + Disl. at root of toughness.
2. A role for chemical interactions with bonds at crack tip.
3. Atomic morphology (structure) of crack crucial. !!
4. Fracture is very complicated
Simplest modelling is by 2D line defect analysis - (isotropic !)

The Three Primordial Crack "Modes"

(Isotropic medium)



MODE I

MODE II

MODE III

Plane strain
(Edge $\times$ loc)
(Long. sound waves)

Anti Plane strain
(screw $\times$ loc)
(shear waves)

2D Elasticity

$$\left[\frac{\partial}{\partial x_i} = 0 \right]$$

See Muskhelishvili
Hirth & Lothe
Rice (Fract. Vol 2)

Stress



force (f) transmitted by $\oplus \rightarrow \ominus$

$$f_i = \sigma_{ij} n_j \quad \sigma_{ij} = \sigma_{ji} \quad (\text{no torque})$$

For equilibrium,

$$\sigma_{ij,j} = f_i$$

Linear Response

$$\text{Strain} \Rightarrow \epsilon_{ij} = \frac{1}{2} \left(\frac{\partial u_i}{\partial x_j} + \frac{\partial u_j}{\partial x_i} \right)$$

$$\text{Rotation} \Rightarrow \omega_{ij} = \frac{1}{2} (u_{i,j} - u_{j,i})$$

$$\sigma_{ij} = C_{ijmn} \epsilon_{mn}$$

Isotropic

$$\sigma_{ij} = \lambda u_{k,k} \delta_{ij} + \mu (u_{i,j} + u_{j,i})$$

Surface B.C.

o Free surf.

$$\sigma_{ij} n_j = F_i \quad \text{External Force}$$

2D Elasticity

Anti plane Strain

$$u = \begin{Bmatrix} 0 \\ 0 \\ u_z \end{Bmatrix} \quad \sigma = \begin{pmatrix} 0 & 0 & \sigma_{13} \\ 0 & 0 & \sigma_{23} \\ \sigma_{31} & \sigma_{32} & 0 \end{pmatrix} \quad \frac{\partial}{\partial z} = 0$$

Equilibrium (no body force)

$$\nabla^2 u = 0 \Rightarrow \text{Invoke complex variable} \quad (z = x + iy)$$

$$\text{Im}(\eta(z)) = \frac{\mu}{2} u$$

$$\text{Hookes Law: } \sigma(z) = \sigma_{32} + i \sigma_{31} = z \eta'(z)$$

Functions of class

$$\eta(z) = z^n \quad n = \left(\frac{1}{2}, \frac{3}{2}, \dots \right) \quad \sigma_{32} = 0 \text{ [B.C.]}$$

$n = + \rightarrow$ singular at ∞ .

$n < \frac{1}{2} \rightarrow$ Singular energy in tip region.

$$\eta' = \frac{K}{\sqrt{2\pi r}} \quad \leftarrow \text{stress intensity factor.}$$

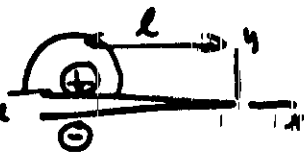
$$\left[\text{NB. } \eta' = \frac{b}{r} \rightarrow \begin{array}{l} \text{Dislocation } b \text{ real} \\ \text{Line force } b \text{ imag} \end{array} \right]$$

CRACK GREEN'S F_N

elegant method — see Appendix SSP.

Heuristic:

Limit $z \rightarrow c$ must be unit force



$$\lim_{z \rightarrow c} \int g(z, l) \eta_j dl = -1 \hat{e}$$

$$= \frac{1}{2\pi i} \int_0^\pi r [g_{31} \cos \theta + g_{32} \sin \theta] d\theta = -1$$

Thus $g \rightarrow \frac{1}{z-l}$ at l ($f_3 = \oint g d\pi$)

Also, must have $1/\sqrt{z}$ at $z \rightarrow 0$ to satisfy B.C. on crack surface

Trial: $g = \frac{A}{(z-l)\sqrt{z}}$

Substitution gives

$$\eta'(z) = g(z) = g_{32} + i g_{31}$$

$$g = \frac{1}{2\pi i} \frac{1}{(t-z)} \sqrt{\frac{t}{z}} \quad (t < 0)$$

Master Eqn:

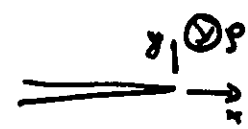
$$\eta'(z) = \int_0^\infty p(t) g(z, t) dt$$

p is (Dipole) force distribution on crack surface

Dislocations

Importance of crack,

must add stress (potential) which cancels σ_{32} on crack surface:



$$\eta' = \eta'_0 + \eta'_i$$

$$\eta'_0 = \frac{\mu b}{4\pi(z-s)}$$

$$\eta'_i = -\frac{1}{2\pi i \sqrt{z}} \int_{-\infty}^0 \frac{\sqrt{t} \operatorname{Re} \{2\eta'_0(t)\}}{t-z} dt$$

$$2\eta' = \sigma = \frac{\mu}{4\pi \sqrt{z}} \left(\frac{b}{\sqrt{z}-\sqrt{s}} - \frac{b}{\sqrt{z}+\sqrt{s}} \right) + \underbrace{\frac{K}{\sqrt{2\pi z}}}_{\text{Crack}}$$

↑
Image!

Many Dislocations: Do summation.

Dislocation Shielding

From Definition of K :

Let $k = \text{Local } k$:

$$k = \lim_{z \rightarrow 0} 2\sqrt{2\pi z} \eta'$$

From previous page:

$$k = K - \underbrace{\frac{\mu}{2} \sum b_j \left[\frac{1}{\sqrt{2\pi z}} + \frac{1}{\sqrt{2\pi r}} \right]}_{\text{Dislocation Shielding}}$$

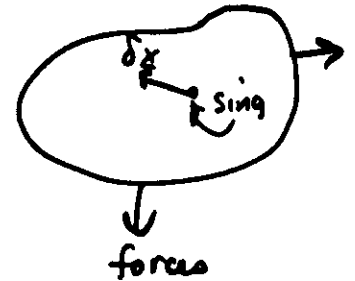
↑
external
Loading

(or anti-shielding! : $b < 0$)

[PRESENCE OF DISLOCATIONS
MODIFIES LOCAL CRACK
STRENGTH]

Eshelby Theorem: Elastic Forces

1. Assume a loaded body containing a singular source of stress.



2. Displace the source δx

Energy density:

$$W = \frac{1}{2} \sigma_{ij} u_{ij} = W(x)$$

3. Stage 1: calculate change due to translation δx :

$$W^{(1)} = W(x) - \underbrace{\frac{\partial W}{\partial x_k} \delta x_k}_{\text{(note - : due to observer - medium difference)}} \quad (\text{Taylor's Th})$$

$$\delta U^{(1)} = - \int \frac{\partial W}{\partial x_k} \delta x_k dV = - \oint W dS_k \delta x_k$$

4. Stage 2:

New stresses on body do not satisfy the B.C.!

Eshelby Theorem (cont)

New stresses are generated at body to ensure body cond are satisfied — likewise new displacements also generated, Δu

$$\Delta u_i = u_i^{\text{final}} - \left(u_i^{(0)} - \frac{\partial u_i^{(0)}}{\partial x_j} \delta x_j \right)$$

↑
from stage I.

The work done by the stresses working thru these added displacements is:

$$\begin{aligned} \delta U^{(2)} &= \int (\sigma_{ij} + \Delta \sigma_{ij}) \Delta u_j dS_j \approx \int \sigma_{ij} \Delta u_j dS_j \\ &= \int \sigma_{ij}^0 \left(u_i^{\text{final}} - u_i^{(0)} + \frac{\partial u_i^{(0)}}{\partial x_k} \delta x_k \right) dS_j \end{aligned}$$

Stage II: Work Done by external forces:

$$\delta U^{(3)} = - \int \sigma_{ij}^{(0)} (u_i^{\text{final}} - u_i^{(0)}) dS_j$$

Adding:

$$f_k = - \frac{\partial U^{\text{total}}}{\partial x_k} = \oint (W \delta_{ij} - \sigma_{ij} u_{i,k}) dS_j$$

Residue Theorem

In 2-D, replace contour integral by Cauchy theorem:

Mode II $\bar{f} = f_1 + i f_2 = \frac{\pi}{\mu} \sum \text{Res}(\sigma^*)$

Check for Dislocation:

$$\sigma = \sigma_0 + \frac{\mu b}{2\pi z}$$

$$\bar{f} = \sigma_0 b \leftarrow \text{Peach-Koehler}$$

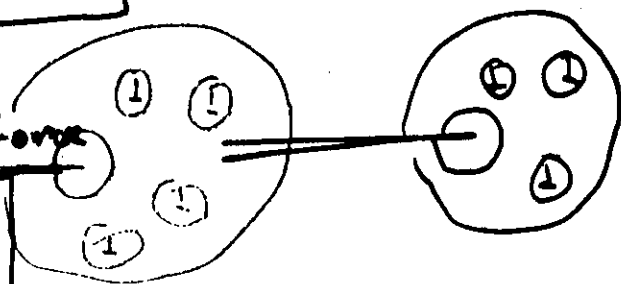
For Crack:

$$f_1 = \frac{K^2}{2\mu}$$

Note (Local stress intensity!)

$F = \Sigma f = \text{total force}$

$$F = \frac{K^2}{2\mu}$$



J- Integral

$$J) f_k = \int (W \delta_{ik} - \sigma_{ij} u_{i,j}) ds = \frac{2\pi^2 i}{\mu} \int \sigma^2 dz$$

Independent of
path by Cauchy
theorem

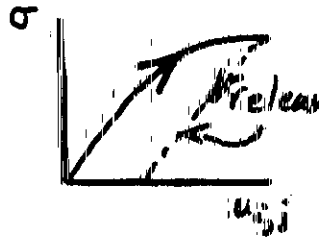


Different Interpretation:

Instead of Hooke's Law,

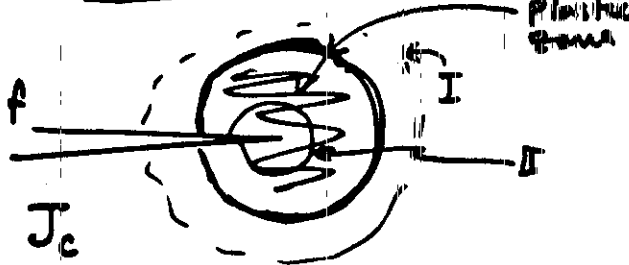
$$\text{Let } \sigma = \sigma(u_{i,j})$$

(nonlinear)



Then $\boxed{f = J}$ - still independent of path

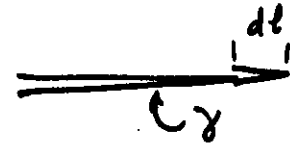
Then J indep. of
path, & is a
"matl. const". J_c



- characterizes toughness —
- Can Matl "call bluff"?
- great practical use — even fatigue

GRIFFITH RELATION

$$f_{el} = \frac{k^2}{2\mu}$$



$$f_{\text{surface}} = 2\gamma$$

tension

Balance of forces (Conservation of Energy)

$$\boxed{\frac{k^2}{2\mu} = 2\gamma}$$

Based on energy conservation, hence
very powerful:

- No disl. activity
- Self similar motion of crack
(cleavage)

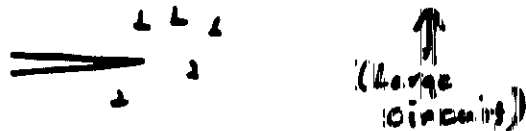
But γ is a thermodynamic quantity - valid
in presence of external chemical
environment. So Griffith is a thermo
statement, valid under chem. equil.
Also limit of kinetics for v.o.

Elastic Overview

1. Cracks + Disl. are singularities in E field
2. $\sigma \approx K / \sqrt{2\pi r}$ crack
 $\sigma \approx b / 2\pi r$ Disl.

3. Dislocations shield (anti shield) cracks.
 k is local field } Note both crack-
 K is external field } fix.!

4. Have developed a formalism for calculating many body equilibrium:

$$F_{\text{tot}} = \sum f_{\text{Disl}} + \sum f_{\text{cracks}} = \frac{K^2}{2\pi\mu}$$


5. Each singularity:

$$f = 0 = f_{\text{elastic}} - f_{\text{matl.}}$$

↑ for crack
 • friction stress for X loc.

6. K gives overall toughness - like J - but contains Xloc. effects.
 (meas. by Narita, et al, Barnes, et al)

-2-

7. Local Crack equil. given by Griffith - hints at chemical effects.

Limitations

1. Where do Disl. come from?
2. What is shape of crack?
3. Kinetics - (chemical effects) at crack tip?

Overall picture: Toughness is result of dislocation shielding (+ other interplay) with crack.

Toughness is K_c at equilibrium.

III ATOMIC AND DISCRETE THEORIES

Atomic treatments do not just remove unsatisfactory singularity -

Required for

Stability of crack in lattice -
(sharp or blunt)

Chemical Effects at tip -
(enhanced reactivity at tip)

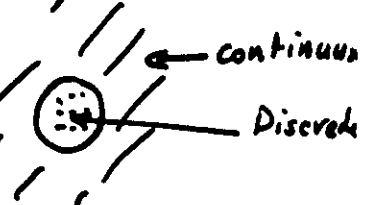
Kinetics of crack motion -
(lattice trapping effects)

Types of Discrete theories

I Classical

1. Inner core with Boundary.

Long history. but flawed by problems on Bndy. 2-D.



[Markworth (Fe, etc.), Mullins,
de Cellis, Argon, Yip, (Fe, Cu)
early
Kanninen et al., Fe
Sinclair Si]

2. Pure simulation - Molecular Dynamics

Finite sample, problems of bndy interacting with crack.

Can do dynamic simulations

2-D - so far

Dienes, Paskin, Sieradsky, et al.
(Lennard-Jones)

Doyama

Simmons - ceramics

3. Green's Fns.

∞ Solid, rigorous theoretical base,
puts in nonlinearity ad hoc. 3D

II Quantum Theories

All classical theories limited by inadequate force laws.

For metals - used empirical ^{n-body} fits to spline fns. (Johnson Potential)
Inadequate for problems where surfaces are present.

For covalents - used empirical 3 body forces (Sinclair: Si)

Ionic Xtals not treated because of long range of force.

Recent progress very dramatic - High promise for powerful theories of detailed crack phenomena:

1. Embedded Atom Method (metals)

Semiempirical method based on embedding potential—metal systems. Used in connection with Molecular dynamics calculations — Fe/H₂ — 3D, still limited to small systems — ~ hours on CRAY. Calculations of surface, interfaces, dislocations, cracks, crack/dislocation. (Kinetics, but not Dynamics)

Daw, Baskes

2. Green's Fns

Small molecular Cluster embedded in a Classical matrix.

Insulators. (Si:O)

3-D.

3. Clusters

molecular calculations of configurations thought to be important in fracture — Interface bonding. (Not a full crack calculations)

Reaction Paths for Crack Motion

Prospect:

First Principle, ^{total energy} techniques now being applied to surface structure not applied (yet?) to crack.

Crack very complicated, ^{extended} defect — Prospect is for techniques based on valid first principle concepts to be most successful. Embedded atom good example.

Experimentally (ceramics)

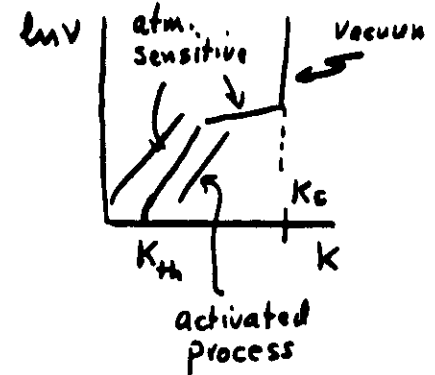
1. In presence of atm., get slow crack growth. growth is activated

2. Occurs in SiO_2 , Al_2O_3 , MgO , etc.

(H_2O , etc.)

(Michalske, Bunker

J. Appl. Phys. 56 2696 (1994))



Implication

Some kind of stress induced molecular reaction. Must study local fluctuations (SD) in crack config. induced by chemical reactions at local site.

a) Small molecules: Reaction at tip bond.

b) Large molecule: Penetration into crack mouth restricted.

- What is criterion for penetration?

- What mechanisms exist for growth for no penetration?

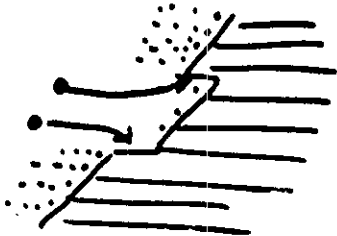
Plan of Attack

1. Small molecules: penetration assured.

Assume molecule attacks crack tip bond.



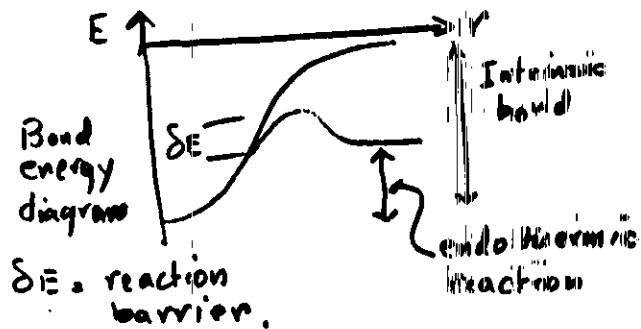
After reaction, surface is covered $\gamma_0 \rightarrow \gamma_1$ in Griffith relation



Crack growth is by nucleation & growth of kink pairs on crack tip.

How do barriers arise??

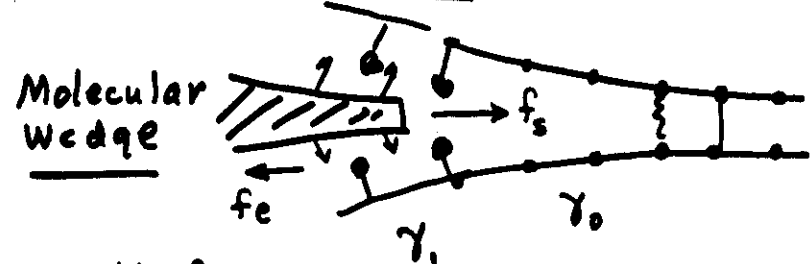
1. Atomicity: Lattice ~~impeding~~
2. chemical reaction barrier



Plan of Attack (cont)

2. Large Molecules.

Penetration criterion



Elastic force on wedge tip = $f_e(R)$
due to crack surfaces "squirting" molecules out of crack mouth

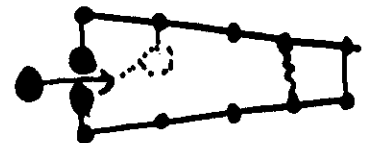
Surface tension force on wedge tip = f_s
 $f_s = 2(\gamma_0 - \gamma_1)$

$$f_e = f_s \text{ at equilibrium}$$

Penetration condition - depends on R, x .

Mechanism for Crack Growth

Diffusion of molecules in constricted region



Reaction Paths for Small Molecules

(In both cases) Atomic structure of crack is crucial.

Thus require general theory of crack structure required:

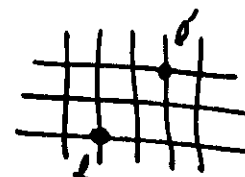
Paradigm

1. Develop a Green's fn. formalism for linear cracked lattice.
2. Put in non linear bonds.
3. Calculate reaction path, + $E_{act.}$ (kinked crack)
4. Include external chemical species
5. Entire procedure assumes knowledge of force laws.

Green's Fns Analysis

static Eqn:

$$\sum_{j,l} \phi_{ij}(l, l') u_j(l') = F_i(l)$$



$$\Phi \underline{u} = \underline{F}$$

See Tewary,
Adv. Phys. 47 486 (1976)

G defined by

$$G = \Phi^{-1}$$

$$u = GF \quad (\text{"Master" Eqn})$$

If lattice is defective, then,

$$\Phi^* = \Phi - \delta\Phi ; u = G^* F$$



If

$$G^* = (\Phi^*)^{-1} \quad \text{i.e.} \quad G^* \Phi^* u = 1$$

$$G [\Phi - \delta\Phi] u = G \cdot 1 ; u = G^* \cdot 1$$

$$\boxed{G^* = G + G \delta\Phi G^*} \quad \text{Dyson Eqn.}$$

Formal soln of crack
problem. (Note G^* on right)

Assumptions

$$u = u_y$$

$$f(l) = A (\Delta_x^2 + \Delta_y^2) u(l) + B (\Delta_y^2 u(l))$$

(nearest neighbor forces)

Then Fourier analyze f , and $G(q)$ is simple:

$$G(q) = \frac{1}{4(A \sin^2 q_x/2 + A \sin^2 q_y/2 + B \sin^2 q_y/2)}$$

Ultimately, (see notes) Dyson eqn. becomes:

$$\sum_{\text{crack plane}} (S_{\vec{l}, \vec{n}} - \alpha(\vec{l} - \vec{n})) G^*(\vec{n}; \vec{m}) = \frac{1}{2B} \alpha(\vec{l} - \vec{m})$$

$$\alpha(\vec{l} - \vec{n}) = -\frac{iB}{8\pi^2 L_z} \sum_{\vec{q}} \int_{-\pi}^{\pi} d\vec{q} \frac{e^{i\vec{q}(\vec{l} - \vec{n})} e^{i\vec{q} \cdot \vec{y}_y} \sin q_y/2}{A(\sin^2 q_x/2 + \sin^2 q_y/2) + B \sin^2 q_y/2}$$

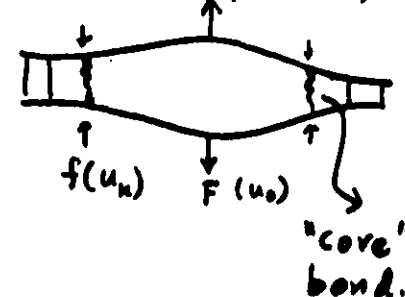
only integrations is analytic.

Structure of Egn:

1. set of algebraic eqns.
rank of matrix = N = no. atoms on crack basic cell.
2. If $u = (u_x, u_y, u_0)$, and forces are longer range,
rank = $3qN$ q : range of force.

Non Linear Bonding Paradigm

(Esterling, 1976)



Green's fn. Master Egn:

$$u_0 = g_{00} F - \sum g_{0k} f$$

$$\approx g_{00} F - p g_{0k} f$$

$$u_k = g_{k0} F - \sum g_{kk'} f$$

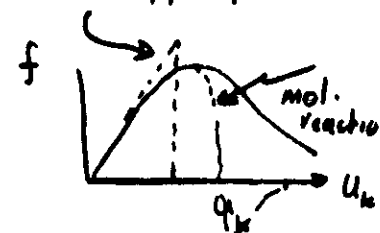
$$= g_{k0} F - g_{kT} f$$

$$(u_{k+1} = g_{k+1,0} F - \sum g_{k+1,k'} f)$$

In the Green's fn. eqn., f is considered an External force.

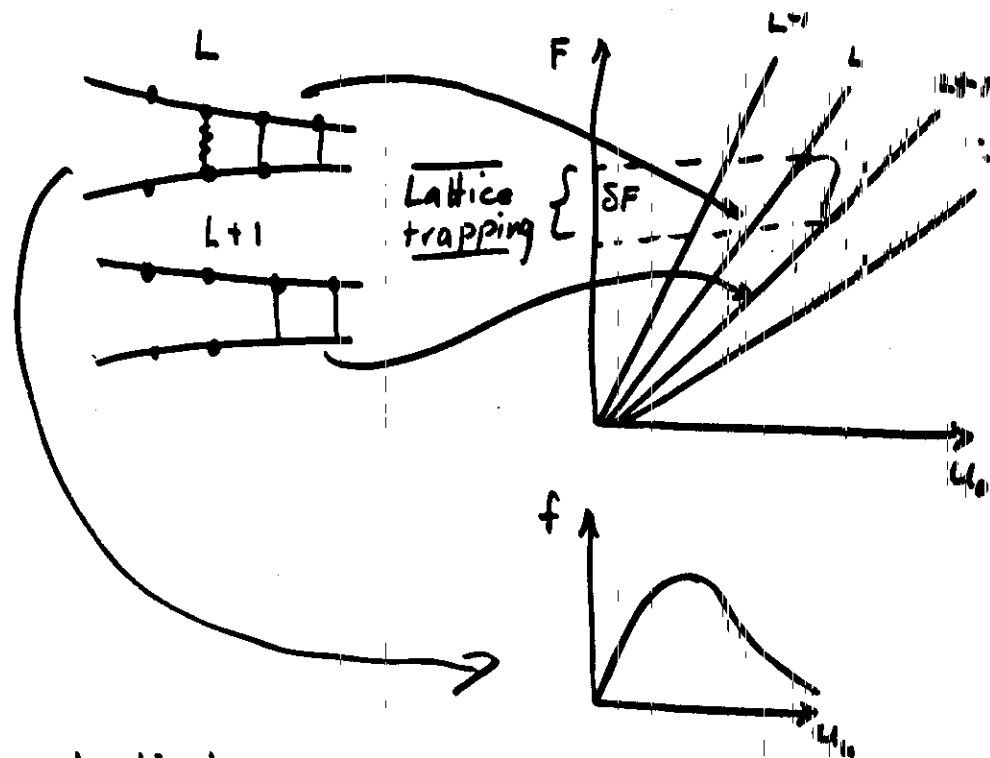
Actually

$$f = f(u_k)$$



Thus, the actual crack structure problem is ~~more~~ represented by a Small set of non linear coupled equations where $N = (\text{no. nonlinear bonds}) + 1$
This represents the real power of Green's fn. Analysis!

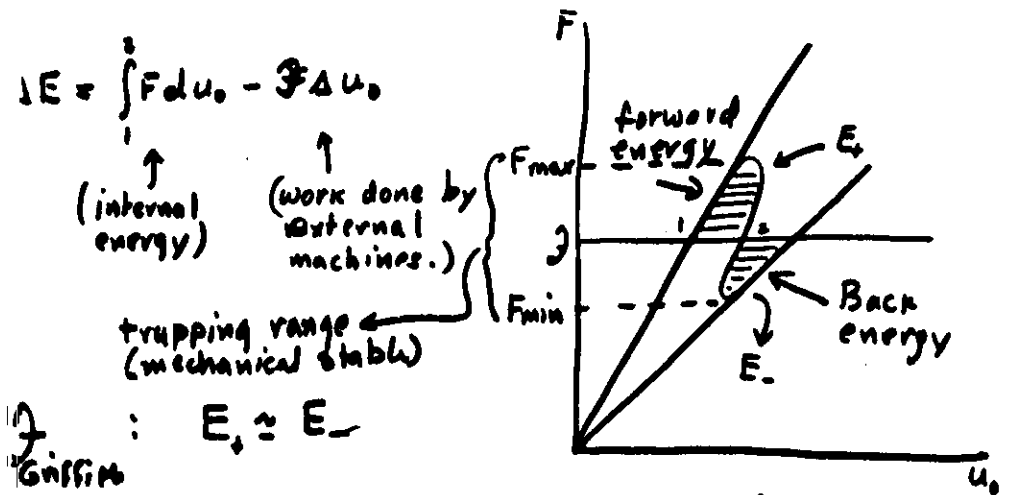
CRACK RESPONSE FNS + GRAPHICAL ANALYSIS



As tip bond goes nonlinear & breaks, response fn. goes from $L \rightarrow L+1$, with nonlinear excursion between $F(u_0)$ lines.

Over lattice trapping range, crack does not change length. This results in energy barriers.

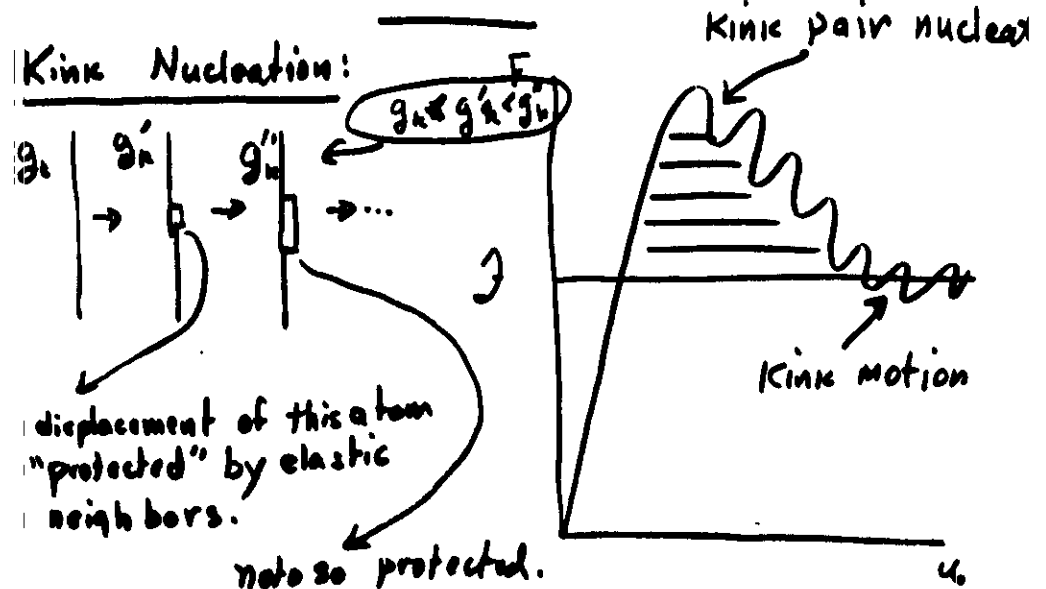
Energy Barriers



$$\Delta E \approx E_+ \approx E_-$$

valid for kink motion energy, or for 2D crack motion.

Kink Nucleation:



- cont -

1). $E(f(u))$ (very sensitive)

2) Master Egn $\rightarrow F(u) \rightarrow E$

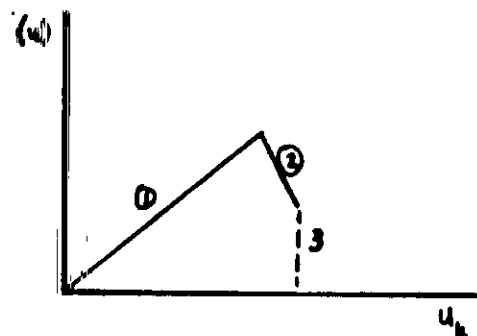
3) $E \rightarrow 0$ as core size increases.

[as atomic "size" decreases,
uniform elasticity takes over.
 $\therefore E \rightarrow 0$]

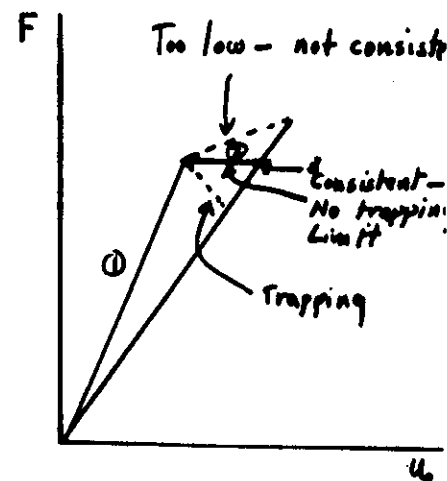
"One Atom" core has most pronounced barriers.

In this case, Master Egn. degenerates
to just 2 eqns.

One Atom Core Criterion



Self consistent force
Law for limiting response
function.



Limiting response curves
for zero trapping and
self consistent 1 atom
core.

From, Green's func Master Egn.

$$du_h = g_{ho} dF - g_{hr} dF \quad (dF \neq 0)$$

$$\left[\frac{dF}{du_h} \right]_{\text{same side}} < -\frac{1}{g_{hr}} = -\frac{B}{h_{hr}}$$

← elastic modulus
← number (dimensionless)

For trapping to be observable, force law must
be almost snapping. Thus, no trapping for
intrinsic fracture, external atm. required - special reaction

Green's Fns Summary

- Excellent method for exploring barriers to crack growth with external chemical environment
- Important to develop criterion for penetration
- Crack growth by chemical reaction at tip only possible for reaction paths of "snapping" character.
- Kink formation energies in SiO_2 at room motion energy $\sim 0.1 \text{ eV}$.
- Qm calculations of forces for "insulating" matls relevant & needed.
- Diffusion mechanism for barriers still not worked out.

DISLOCATION EMISSION

Issue here is Ductile/Brittle dichotomy.

Criterion explored first in elastic cut-off:

2D

In Mode I, (in L+T, Eq 36)

$$f_g = \frac{k_b}{\sqrt{2\pi r}} f(\theta) - \frac{\mu b^2}{4\pi r(1-\nu)}$$

$\uparrow$ K-field $\uparrow$ Image

When $r = r_{\text{core}}$, then emission just possible. Thus:

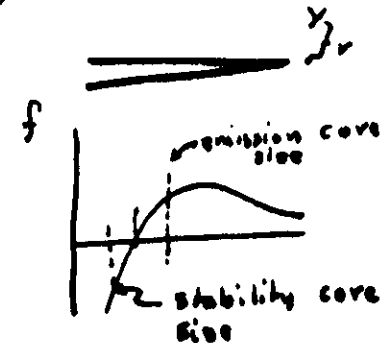
$$k_c = \frac{\mu b}{2\sqrt{2\pi r_{\text{core}}(1-\nu)}} \frac{1}{f(\theta)}$$

But cleavage will occur when

$$k_c = 2\sqrt{\mu\gamma(1-\nu)}$$

Thus

$k_c < k_e$	$\longrightarrow$	cleaving Crack
$k_c > k_e$	$\longrightarrow$	emitting Crack



- cont -

A curious parameter:

$$\frac{k_b}{k_c} = \sqrt{\frac{\mu_b}{\gamma}} \approx \text{const.}$$

Thus

$\frac{\mu_b}{\gamma}$ is a figure of merit (rough)

$\frac{\mu_b}{\gamma} > 10$ - brittle

$\frac{\mu_b}{\gamma} < 10$ - ductile

Roughly the fcc metals are ductile, ionic +
some brittle. Fe borderline!

But this criterion contains r_0 and τ - which are
force law parameters.

The real conclusion is that ductile/brittle
solid depends sensitively on the force
laws of solid!

Hence the true emission/cleavage criterion should
be done from fundamental theory!

- cont -

Simulation work -

1. Dienes et al.: cut-off
confirmed that criterion is
valid for Lennard-Jones 6/12.

2. ~~de~~ de Cellis, Argon, Yip.
Comp. sim. calc using empirical
"Johnson" type force laws. suggest
Cu ductile + Fe brittle. - not
based on adequate force laws.

3. Daw + Baskes
confirm Fe is borderline -
curious result that H
enhances xloc. emission!?

Effect of Mixed Modes

Emission Criterion

Same as before: calculate elastic force on dislocation:

$$f_e = b_s k_{III} f_s(0) + b_a \left[k_I f_i(0) + k_{II} f_{II}(0) \right]$$

compl. fn. of θ . (su L+T)

$$- \frac{\mu}{2\sqrt{2\pi r_0}} \left(b_s^2 + \frac{b_a^2}{1-\nu} \right) = 0 \text{ for critical pt.}$$

Cleavage Criterion

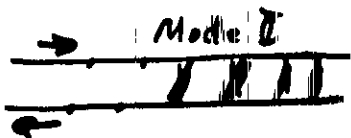
cut.

①



stress

②



release bonds

③

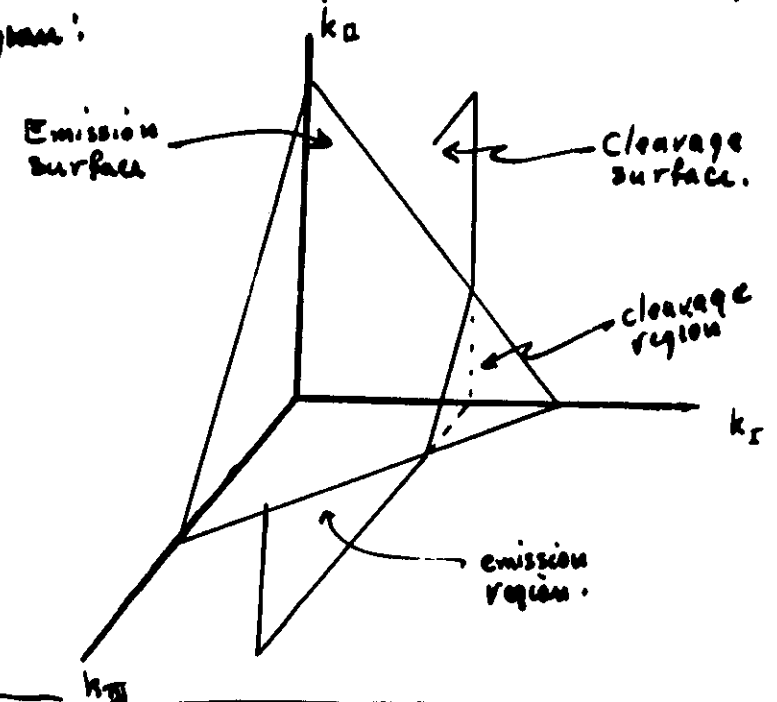


Result is a dislocation! Must have sufficient Mode I to open crack on back side of disl. core so crack does not reclose.

-Cont-

I estimate the modification of Griffith relation by Modes II & III to depend somewhat on type of bonding (i.e. metal vs. semicond.) but normally to be a negligible effect.

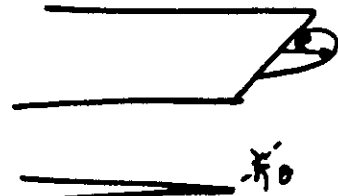
Combine Emission Cleavage Criterion on a single diagram:



Ductile/Brittle depends on loading mode as well as bonding type.

3-D

2D establishes Genl.
mechanical stability.



But dislocations can be thermally activated out
of crack tip, even when crack is stable
against emission!

Activation barrier is set by critical loop of
dislocation.

original estimate in Rice + Thomson.

Update: Thesis by Peter Anderson.
Harvard Univ. (1986)

See also Argon, Acta Met, 35 185 (1987)

General

1. Dislocation self energy (includes ~~strain~~)
2. strain energy release.

- Cont -

From Hirth + Lothe.

$$U_{\text{self}} = +\mu b^2 r \frac{2-\nu}{2(1-\nu)} \ln \frac{8r}{e^2 r_0} \propto r$$

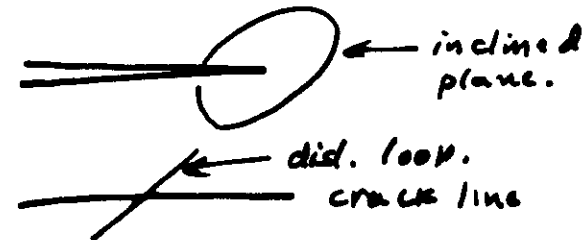
$$U_r = -\frac{2}{3} \frac{\mu b^2}{1-\nu} \sqrt{\frac{\gamma}{\mu b}} f(\theta, \delta) (r^{3/2} - r_0^{3/2}) \propto r^{3/2}$$

$$U_{\text{image}} = (\text{small term})$$

Energy of act. is maximum in $U = U_{\text{self}} + U_r + U_{\text{image}}$.

Original estimates on basis of whole b, and
circular loop gave very large energies
except for Fe. Experimentally, disl.
are easier to produce.

So there is a different slip system in
general: (Non-Blunting)



Seen first by Burns + Webb, but ~~more~~ a genl.
phenomenon - quantitative results by Michot
on Si. Submitted to J. Math. Sci.

- Cont.

This whole question being revisited -

See upcoming work, with Lin & Argon.

role of alternate slip plane.

role of high stress regions on
core size

role of partial b (w/o low energy
stacking fault.)

role of non circular shape.

Can this problem be done properly (i.e.
at atomic level) in 3-D ??

TOUGHNESS & SHIELDING

GEN'L IDEA

UNDERLYING CRACK: Local & DETERMINES

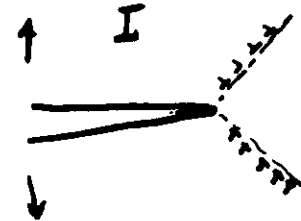
TOTAL O/A BEHAVIOR

for emission - k_e

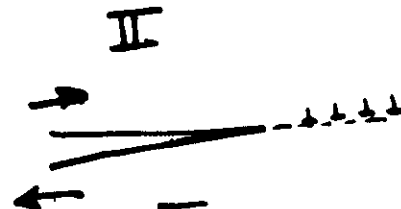
for cleavage - k_c .

General Shielding Theorems

① "Natural" Dislocation Config.:



Dislocations
for
maximum
Emission
criteria



- cont -

Theorem on Shielding orthogonality (mixed mode).

Mode I dislocations only shield mode I loading - (no shielding of I + III.)

etc

Exception -

In mode I, asymmetric dislocation emission induces (shields) mode II. (not mode III) (first noticed by Sinclair. Finnis - can be important effect for mixed mode problems. (e.g. serrated fracture found by Ohr)

A solvable many body problem (B.C.S) (Dugdale)

Assume Mode III -

Assume force on



dislocations is in balance:

$$F_d = \frac{Kb}{\sqrt{2\pi x}} - \frac{\mu b^2}{4\pi x} + \sum' \frac{\mu b b'}{2\pi} \frac{1}{x-x'} \sqrt{\frac{x'}{x}} = \sigma_f b$$

Assume continuum approx:

$$db = \beta(x) dx$$

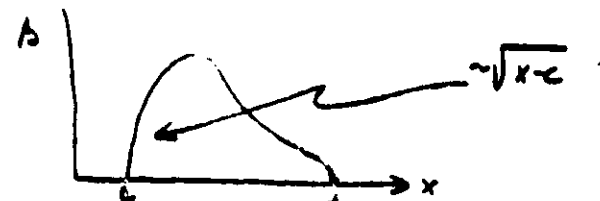
$$\sigma_f = \frac{K}{\sqrt{2\pi x}} - \frac{\mu \beta dx}{4\pi x} + \frac{\mu}{2\pi \sqrt{x}} \int_c^d \frac{\sqrt{x'} \beta(x')}{x-x'} dx'$$

$$\frac{\mu}{2\pi} \left[\sigma_f \sqrt{x} - \frac{K}{\sqrt{2\pi x}} \right] = \int_c^d \frac{\sqrt{x'} \beta(x')}{x-x'} dx'$$

Hilbert Xform - see Muskhelishvili (details in SSP - Appendix)

$$\beta(x) = - \frac{2}{\mu \pi} \sqrt{\frac{(x-c)(d-x)}{x}} \int_c^d \frac{(\sqrt{x'} \sigma_f + K/\sqrt{2\pi}) \sqrt{x'}}{(x'-x) \sqrt{(x'-c)(d-x')}} dx'$$

This is an elliptic integral - Interested in asymptotic range ccd:



- cont -

For $c \ll d$

$$k = \frac{3}{\pi} \left(\frac{2}{\pi} \right)^{1/2} \sigma_f \sqrt{c} \left(\ln \frac{4d}{c} + \frac{4}{3} \right)$$

$$k = K - \mu \int \frac{\beta(x')}{\sqrt{2\pi r'}} dx' = \text{local } k.$$

$$\left. \begin{aligned} K &= 2 \sigma_f \sqrt{\pi/2d} \\ K &= \mu B \sqrt{\pi/2d} \end{aligned} \right\} \begin{array}{l} \text{Not dependent on } c - \\ \text{comes from original} \\ \text{Bilby-Cottrell-Smith} \\ \text{treatment.} \end{array}$$

Rice Paradox

Let $c \rightarrow 0$. Then

$$k = 0$$

Eliminate d from last 2 eqns:

$$\frac{K^2}{2\mu} = \sigma_f B$$

The force to move crack + Disl.
is just the force to move the
dislocations! When $c \rightarrow 0$, this is
a rigorous result.

- cont -

This is a paradox because all the energy
goes into moving the dislocations, and NONE
into creating the broken bonds at the crack
tip. This result is because the dislocations
cancel the local k at the crack tip. In order
for there to be a finite energy absorption at
the crack tip, ~~the~~ $c > 0$ is required. (Originally
proved by Rice in a different way - see
Rice Sendai Conf. on Fract.)

But is this a subtle point, or a crucial one?

The previous eqns can be written

$$k \sim \sigma_f \sqrt{c} \leftarrow \begin{array}{l} \text{Set by cleavage} \\ \text{or emission} \\ \text{condition at tip} \end{array}$$

$$\frac{K^2}{2\mu} = \sigma_f B \leftarrow \text{shielding relation}$$

Connection is thru σ_f

- Cont -

What is c or Disl. Free Zone?

(there is controversy on this point - (Birnbaum))

- Clearest in experiments by Ohr.

- Fundamentally:

It connects the atomic bonding conditions at crack tip with the shielding zone.

(It must exist — otherwise $K \rightarrow \infty$!)

and provides the bridge between macroscopic and microscopic + atomic properties.

- Physically it arises:

Finite distance between sources for Dislocations near the tip.
(Frank-Read sources — (Birnbaum))

Distance required for a dislocation to move from a tip before another can be emitted.

- See recent work by ~~Li +~~ Li + co-workers for simulation of DFZ.

- Cont -

The problem is - what determines the B ? Suppose the B s are created at external sources due to σ exceeding the local yield stress. Then, we need a yield - dislocation density relation - (a constitutive relation - work hardening)

Suppose $B = B_0 \sigma_f^n$

Then

$$K^2 = 2\mu B_0 \left(\frac{k}{\sqrt{c}}\right)^{n+1} \left[l_c = \sqrt{\frac{k}{2\mu\gamma}} \right]$$

So the overall toughness of the material follows from:

- ① Strength of bonds (γ)
- ② Dislocation response to stress.
- ③ Elastic constants.
- ④ Disl. Free zone

TOUGHNESS PERSPECTIVE

Intrinsic Ductility/Brittleness

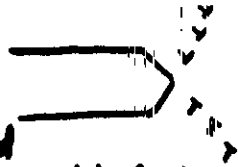
1. Crack Emits

Shape Change -

Dislocation dominated
phenomenology. - Plastic failure

* Crack doesn't go anywhere!

Inherently high toughness +
 k_i shielding



2. Crack Cleaves

* Crack is highly mobile -- determined
by local k_e . - i.e. state is unstable

Shielding can occur by external
dislocations - not too effective

-cont-

Extrinsic Ductility

Crucial Issue:

Can a brittle crack induce such large
amounts of external plasticity that
overall ductile failure occurs

This means:

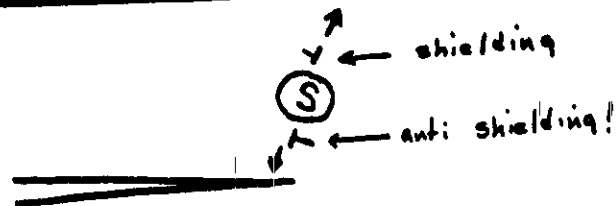
Local k never rises to k_c because
there always exists a source nearby
which produces shielding disl.

? ? ?

[This mechanism is proposed by
Ashby + Embury as a serious
mechanism for ductile Xtion
(Stripta Met)]

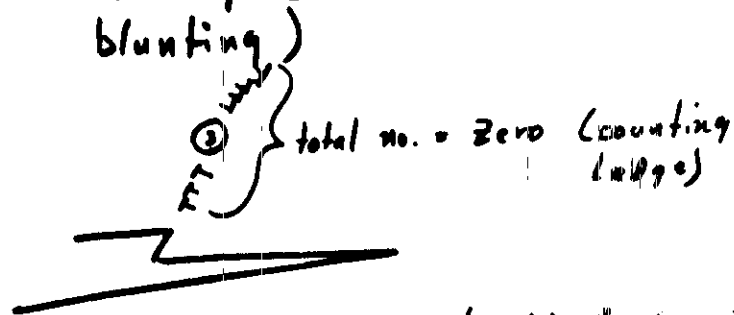
-cont-

Some qualitative thoughts:



1) Thus, the initial action is anti-shielding
This means that externally generated dislocations are always less effective in shielding than intrinsically produced dislocations!

2) Then antishielding dislocations are absorbed, + net effect is shielding (and some non local blunting)

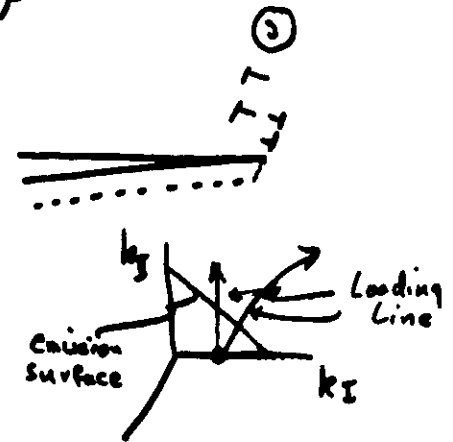


Note: probability to blunt tip is low!

-cont-

3) Anti shielding dislocations change emission condition at tip

$[k_{II} \text{ generated}]$



emission creates a dipole configuration near tip — ~~shifts~~ cancelling k_{II} and anti shielding. Then overall effect is shielding, + k_{II} goes negative, stabilising cleavage crack

4) As k increases, crack again cleaves (even tho blunted!) and cycle is repeated

5) This process is highly rate sensitive!
conclusion The question is still open

-cont-

Mixed Cases

It now appears that a brittle ceramic has a low energy of activation for dislocation nucleation (??)

Thus as T increases, dislocation emission becomes significant, and ductility ensues. Si is such a case (Fe may be) - now being worked out.

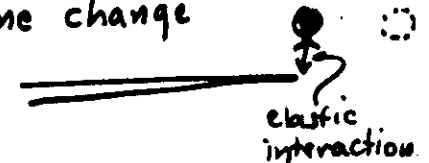
-65-

MECHANISMS FOR SHIELDING LOCAL CRACK TIP IN CERAMICS

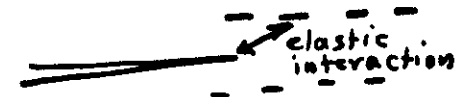
1. Dislocations

Sources external $\rightarrow$ (some anti shielding)
Source is crack $\rightarrow$ much more effective.

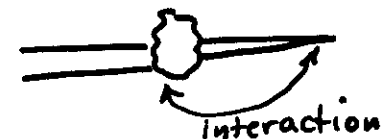
2. Transformation of Second Phase Stress induced volume change



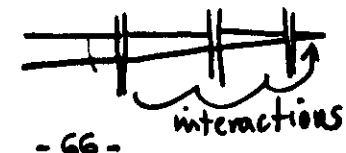
3. Microcracking in polycrystals



4. Encapsulated Particle or Grain



5. Fiber "Reinforcement"



$K_{\text{I}} \rightarrow \infty!$

-66-

Concluding Summary

Emerging Possibility: Materials Design

- T
H
E
O
R
Y
- 1) Enhanced modeling of crack structure because force laws now tractible.
 - 2) Enhanced computation capability for more realistic crack-dislocation cloud simulation
 - 3) Tailoring of materials thru enhanced processing controls (i.e. composites, quenched phases, etc.)

