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BOUNDARY VALUE PROBLEMS FOR PERIODIC HETEROGENEOUS
MEDIA AND APPLICATIONS TO COMPOSITE MATERIALS

"Compléments"

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These are preliminary lecture notes intended for participants only.
Copies are available outside the Publications Office (T-floor) or from
room 112.

Boundary value problems for periodic heterogeneous medium. Complements

The first part of the lecture notes concerning this subject being the exact copy of a document relative to an Enimtech. acc. rather descriptive. This second part which seems to repeat some pages of the preceding one, gives the details of the proofs.

Complement 1: Precisions about the introduction of the representative cell P

Taking the same notations than in p. 3, it is clear that a point M of the ~~the~~ composite body is characterized by

i) its position $\underline{x}$ in Ω .

ii) its position in the cell $\mathcal{C}_{\underline{k}}$ to which it belongs

($\underline{k} = k_1, k_2, \dots, k_N$; this index indicates that this cell occupies the number of order k_i in the x_i direction).

This last position being itself characterized by this of the corresponding $\underline{y}$ in the representative cell P .

So, let recapitulate changing slightly the notations:

- The physical coefficients are periodic, of periods ε_i in the x_i direction.

$$C(\underline{x} + \underline{k}\varepsilon) = C(\underline{x})$$

$$M = \max_{i=1 \dots N} \varepsilon_i \quad ; \quad y'_i = \frac{x_i}{\varepsilon_i} \quad ; \quad p_i = \frac{\varepsilon_i}{\varepsilon}$$

So, the homothetism $H_\varepsilon = (0, \frac{1}{\varepsilon})$ associates at

$$\underline{x} \in \mathcal{C}_{\underline{k}} \quad \text{the element} \quad \underline{y}' \in P'_{\underline{k}} = H_\varepsilon(\mathcal{C}_{\underline{k}})$$

Then we carry $P'_{\underline{k}}$ to the origine by the translation.

$$T_{\underline{k}} = -(\underline{k}-1)\underline{p} = [-(k_1-1)p_1, \dots, -(k_N-1)p_N]$$

So this translation associates at

$$\underline{y}' \in P'_{\underline{k}} \quad \text{the point} \quad \underline{y} = \underline{y}' - (\underline{k}-1)\underline{p} \in P.$$

$$\text{and now } C(\underline{x}) = C(\varepsilon \underline{y}) = a(\underline{y}') = a(\underline{y})$$

Complement 2 : Details about the multiple scale method

a) Formal working.

If we consider one particle of the periodic heterogeneous body, two things will be important to characterize it:

- its position $\underline{x}$ in Ω .
- its position in the basic cell to which it belongs; this one can be represented by the corresponding $\underline{y}$ in P .

In the other hand, we are interested in the eventual limit of u_ε , solution of (3)(4)(5), when ε goes to 0 keeping P fixed.

The two preceding remarks leads us to look for u_ε under the form of an asymptotic expansion of the type:

$$(30) \quad u_\varepsilon(\underline{x}) = w_0(\underline{x}, \underline{y}) + \varepsilon w_1(\underline{x}, \underline{y}) + \varepsilon^2 w_2(\underline{x}, \underline{y}) + o(\varepsilon^2)$$

where $\underline{y}_i = \frac{x_i}{\varepsilon} + \text{constant}$; $\underline{x}, \underline{y} \in \Omega \times P$:

The w_i being "P-periodic" in $\underline{y}$

If we set generally $\varphi(\underline{x}, \underline{y}) = \varphi^*(\underline{x})$, we have:

$$\frac{\partial \varphi^*}{\partial x_i} = \frac{\partial \varphi}{\partial x_i} + \frac{1}{\varepsilon} \frac{\partial \varphi}{\partial y_i} \quad \text{and then}$$

$$A^\varepsilon u_\varepsilon = - \frac{\partial}{\partial x_i} \left\{ a_{ij}(\underline{y}) \frac{\partial}{\partial x_j} (w_0^*(\underline{x}) + \varepsilon w_1^*(\underline{x}) + \varepsilon^2 w_2^*(\underline{x}) + o(\varepsilon^2)) \right\} = f(\underline{x})$$

can be written

$$(31) \quad (\varepsilon^{-2} A_1 + \varepsilon^{-1} A_2 + A_3) (w_0 + \varepsilon w_1 + \varepsilon^2 w_2 + \dots) = f.$$

with:

$$A_1 \varphi = - a_{ij} \frac{\partial^2 \varphi}{\partial y_i \partial y_j} - \frac{\partial a_{ij}}{\partial y_i} \frac{\partial \varphi}{\partial y_j} = - \frac{\partial}{\partial y_i} \left(a_{ij} \frac{\partial \varphi}{\partial y_j} \right)$$

$$A_2 \varphi = - a_{ij} \left[\frac{\partial^2 \varphi}{\partial x_i \partial y_j} + \frac{\partial^2 \varphi}{\partial x_j \partial y_i} \right] - \frac{\partial a_{ij}}{\partial y_i} \frac{\partial \varphi}{\partial x_j}$$

$$= - \frac{\partial}{\partial y_i} \left[a_{ij} \frac{\partial \varphi}{\partial x_j} \right] - a_{ij} \frac{\partial^2 \varphi}{\partial x_i \partial y_j}$$

$$A_3 \varphi = \dots \frac{\partial^2 \varphi}{\partial x_i \partial x_j}$$

By identification in (31) for the different orders on ε , we obtain, respectively

$$(32) \quad \varepsilon^{-2}: \quad A_1 w_0 = 0$$

$$(33) \quad \varepsilon^{-1}: \quad A_1 w_1 + A_2 w_0 = 0$$

$$(34) \quad \varepsilon^0: \quad A_1 w_2 + A_2 w_1 + A_3 w_0 = f$$

Let explicit (32)

$$-\frac{\partial}{\partial y_i} \left[a_{ij}(y) \frac{\partial w_0}{\partial y_j} \right] = 0$$

if we multiply by w_0 and integrate by parts over P , we obtain, thanks to the "P-periodicity" of a_{ij} and w_0 in y : (*)

$$0 = \int_P \frac{\partial}{\partial y_i} \left[a_{ij} \frac{\partial w_0}{\partial y_j} \right] w_0 dy = - \int_P a_{ij} \frac{\partial w_0}{\partial y_j} \frac{\partial w_0}{\partial y_i} dy \leq -\beta \int_P |\text{grad } w_0|^2 dy$$

that implies

$$\frac{\partial w_0}{\partial y_i} = 0 \quad \text{almost everywhere in } P.$$

and then

$$(35) \quad \boxed{w_0(x, y) = u(x)}$$

u is still unknown.

Let explicit (33)

$$(36) \quad -\frac{\partial}{\partial y_i} \left(a_{ij} \frac{\partial w_1}{\partial y_j} \right) = -A_2 w_0^* = \frac{\partial a_{ij}}{\partial y_i} \frac{\partial u}{\partial y_j}$$

Let introduce the space

$$W = \{ \varphi \mid \varphi \in H^1(P), \text{ P-periodic} \}$$

$$\dot{W} = \frac{W}{R} \quad \text{where } R \text{ is the equivalence relation defined by}$$

$$\varphi R \psi \Leftrightarrow \varphi - \psi = \text{constant}$$

fact $\int_P a_{ij} \frac{\partial w_0}{\partial y_j} w_0 m_i dx = 0$ because $a_{ij}, w_0, \frac{\partial w_0}{\partial y_i}$ take

then $(\int_p |\text{grad } \psi|^2 dy)^{1/2}$ can be chosen as a norm on $\dot{W}$

$\frac{\partial u}{\partial \alpha_j}$ depending exclusively of $\underline{x}$ we can introduce $\underline{x}$ by

$$w_1(\underline{x}, \underline{y}) = -x^j(\underline{y}) \frac{\partial u}{\partial \alpha_j}$$

in a such a way that x^j be "P-periodic" and satisfies.

$$(37) \quad \begin{cases} A_1 x^j = -\frac{\partial a_{ij}}{\partial y_i} \\ x^j \in W \end{cases}$$

A_1 is coercive on $\dot{W}$; in fact:

$$\int_p (A_1 \varphi) \varphi dy = \int_p a_{ij} \varphi_{,j} \varphi_{,i} dy \geq \beta \|\varphi\|_{\dot{W}}^2$$

then we can apply the Lax-Milgram theorem and conclude at the existence of x^j at a constant (that is to say at a function of $\underline{x}$) in W . Hence the form of $w_1(\underline{x}, \underline{y})$

$$(38) \quad \boxed{w_1(\underline{x}, \underline{y}) = -\left(x^j(\underline{y}) \frac{\partial u}{\partial \alpha_j} + \tilde{w}_1(\underline{x})\right)}$$

At this point, we have still to determine u and $\tilde{w}_1$.

Let explicit (34)

$$A_1 w_2 = f - A_2 w_1 - A_3 w_0$$

is an equation of the type.

$$\begin{cases} A_1 \phi = F \\ \phi \text{ "P-periodic" in } y \end{cases}$$

or in its weak formulation.

$$(39) \quad a_p(\phi, \psi) = (F, \psi) \quad \forall \psi \in \dot{W}$$

with the definition:

which is a bilinear form on W .

Then (39) admits one unique solution on W if and only if

$$(41) \quad \int_P F(y) dy = 0.$$

because the set of constant (or function of z) is the neutral element of W .

$$(41) \text{ is exactly } \int_P [f(z) - A_2 w_1(z, y) - A_3 u(z)] dy = 0.$$

that is to say, in denoting by $V(P)$ the volume of P .

$$V(P) f = \int_P (A_2 w_1 + A_3 u) dy.$$

Let remark again that.

$$\int_P A_2 \varphi dy = - \int_P a_{ij} \frac{\partial^2 \varphi}{\partial x_i \partial y_j} dy$$

$\forall \varphi(x, y)$ "P. periodic" in y .

Then, taking account of (35) and (38) we obtain.

$$\begin{aligned} V(P) f &= \int_P \left\{ a_{ij} \frac{\partial x^k}{\partial y_j} \frac{\partial^2 u}{\partial x_k \partial x_i} - a_{ij} \frac{\partial^2 u}{\partial x_i \partial x_j} \right\} dy \\ &= \int_P a_{ij} \left(\frac{\partial x^k}{\partial y_j} - \delta_{kj} \right) \frac{\partial^2 u}{\partial x_k \partial x_i} dy. \end{aligned}$$

from where.

$$f = - q_{ik} \frac{\partial^2 u}{\partial x_k \partial x_i} \quad \text{if we define } q_{ik} \text{ by.}$$

$$(42) \quad \boxed{q_{ik} = \frac{1}{V(P)} \int_P a_{ij} \frac{\partial}{\partial y_j} (y_k - x^k) dy.}$$

in conclusion, the q_{ij} being determined by (37) and (42), it is

$$(43) \quad -q_{ij} \frac{\partial^2 u}{\partial x_i \partial x_j} = f \quad \text{on } \Omega; \quad u \in H_0^1(\Omega).$$

because for $\varepsilon = 0$, u has to satisfy the same boundary conditions as u_ε .

Remark 9: It is time now to realize what we got:

By the preceding formal workings, we obtained:

$$u_\varepsilon(\underline{x}) = u(\underline{x}) - \varepsilon \left[\chi^j(\underline{y}) \frac{\partial u}{\partial x_j} + \tilde{w}_1(\underline{x}) \right] + \varepsilon^2 w_2(\underline{x}, \underline{y}) + o(\varepsilon')$$

where χ^j and u are determined by the surmised solutions of (37) (42) and (43), $\tilde{w}_1(\underline{x})$ and $w_2(\underline{x}, \underline{y})$ by the following identifications of (31)

We can then expect for a first step, that u is a good approximation of u_ε when ε is small and wonder if that is interesting on a numerical point of view as well as of a study of the global behaviour of the solution u_ε . To answer these questions, it is necessary

- to study "existence and uniqueness" for (43).
- to study the converging of u_ε toward u when $\varepsilon \rightarrow 0$.
- to evaluate, if possible, the error $v_\varepsilon = u_\varepsilon - u$.
- to have a look at the nature of the preliminary computing (37) and (42)

b) Study of the homogenized problem (43)

Lemma 1:
$$q_{ij} = \frac{1}{V(P)} a_p(\chi^j - y_j, \chi^i - y_i) \quad (44)$$

This lemma is useful to obtain q_{ij} on a more symmetric form and to be then able to study more easily the coercivity of the operator

To obtain this form of q_{ij} , we have first to modify slightly the definition (42) in fact:

$$\begin{aligned} q_{ij} &= \frac{1}{V(P)} \int_P a_{ke}(\underline{y}) \frac{\partial}{\partial y_e} (y_j - x^j) \delta_{ki} dy \\ &= \frac{1}{V(P)} \int_P a_{ke}(\underline{y}) \frac{\partial}{\partial y_e} (y_j - x^j) \frac{\partial y_i}{\partial y_e} dy \\ &= \frac{1}{V(P)} a_p(y_j - x^j, y_i). \end{aligned}$$

In an other hand, if we multiply (37) by $\psi \in W$ and integrate by parts over P , we obtain.

$$\begin{aligned} \int_P a_{ie} x^j_e \psi_{,i} dy &= \int_P a_{ij} \psi_{,i} dy \\ &= \int_P a_{ie} \psi_{,i} \delta_{ej} dy. \end{aligned}$$

(app the integrals on the boundary being zero because the hypothesis of P-Periodicity of $\underline{a}$ and $\underline{x}$, ψ)

That gives us a kind of weak form for the problem (37).

$$(45) \quad \boxed{a_p(x^j, \psi) = a_p(y_j, \psi) \quad \forall \psi \in W}$$

That implies in particular $a_p(x^j - y_j, x^i) = 0$.

hence the announced form for the coefficients q_{ij} and also the following lemma.

Lemma 2. The problem (43) is elliptic (on convex)

$$\begin{aligned} \text{in fact: } q_{ij} \xi_i \xi_j &= \frac{1}{V(P)} a_p[\xi_j(x^j - y_j), \xi_i(x^i - y_i)] \\ &= \frac{1}{V(P)} \int_P a_{elm} \xi_j(x^j - y_j)_{,m} \xi_i(x^i - y_i)_{,e} dy. \end{aligned}$$

and we obtain:

$$q_{ij} \xi_i \xi_j \geq \frac{\alpha}{V(P)} \int_P |\text{grad } v|^2 dy \geq 0 \quad \forall \xi \in \mathbb{R}^N$$

Let show now that this inequality is strict. Let suppose then that for a $\xi \neq 0$, $q_{ij} \xi_i \xi_j = 0$ that implies

$\text{grad } v = 0$ almost everywhere on P . that is to say.

$$v = \xi_i [X^i(y) - y] = \text{constant} \quad \text{a. e. on } P.$$

Let $\vec{e}_i$ a new orthonormal basis such as $\vec{\xi} = \vec{e}_1$; in this new basis, the preceding equality can be written

$$X^1(y) = \text{constant} + y_1 \quad \text{a. e. on } P.$$

and that is impossible because X^1 is "periodic" and y_1 is not. Whence:

$$q_{ij} \xi_i \xi_j > 0 \quad \forall \xi \neq 0.$$

Let then introduce

$$\beta = \inf_{|\xi|=1} q_{ij} \xi_i \xi_j$$

this inf is reach, thanks to the compactness of the sphere $|\xi|=1$ in $\mathbb{R}^N$, and therefore $\beta > 0$ implies

$$q_{ij} \xi_i \xi_j \geq \beta |\xi|^2 \quad \forall \xi \in \mathbb{R}^N. \quad \text{q. e. d.}$$

We can now by the Lax-Milgram theorem to the existence and uniqueness of the solution of (43)

c) Study of the convergence of u_ε when $\varepsilon \rightarrow 0$ and estimate of the error

It is time now to express precisely the complete results that we are going to obtain in this way

cf following page.

Theorem 1: We suppose that the coefficient a_{ij} are $C^\infty(\bar{\Omega})$ (that is obviously superabundant, but the regularity asked by the method is anyway too great for the application)

Let A^ε be the differential operator defined by (3) and satisfying the hypothesis of concavity (4)

Let $\mathcal{A}$ be the operator defined by

$$\mathcal{A} = -q_{ij} \frac{\partial^2}{\partial x_j \partial x_i}, \quad q_{ij} \text{ defined themselves by (44).}$$

Let consider now the 2 homogeneous Dirichlet problems

$$(P_\varepsilon): \quad A^\varepsilon u_\varepsilon = f \quad \text{in } \Omega; \quad u_\varepsilon = 0 \quad \text{on } \partial\Omega.$$

$$(P): \quad \mathcal{A}u = f \quad \text{in } \Omega; \quad u = 0 \quad \text{on } \partial\Omega.$$

Then u_ε converges toward u , uniformly in $C^0(\bar{\Omega})$ and.

$$(46) \quad |u_\varepsilon(x) - u(x)| \leq C\varepsilon \quad \forall x \in \Omega.$$

Proof: let introduce.

$$v_\varepsilon(x) = u_\varepsilon(x) - u(x) - \varepsilon w_1(x, y) - \varepsilon^2 w_2(x, \frac{x}{\varepsilon})$$

$$A^\varepsilon v_\varepsilon = f + (\varepsilon^{-2} A_1 + \varepsilon^{-1} A_2 + A_3) (-u - \varepsilon w_1 - \varepsilon^2 w_2)$$

$$\text{but } u \text{ satisfies } A_1 u = 0. \quad \text{cf (32) and (35)}$$

$$\text{and also } A_2 u + A_1 w_1 = 0. \quad \text{cf (33)}$$

$$f - A_3 u - A_2 w_1 - A_1 w_2 = 0 \quad \text{cf (34).}$$

therefore

$$A^\varepsilon v_\varepsilon = -\varepsilon (A_3 w_1 + A_2 w_2) - \varepsilon^2 A_3 w_2.$$

the regularity of the coefficients guarantees this of w_1 and w_2 which are therefore bounded on $\bar{\Omega}$. whence.

$$\begin{cases} A^\varepsilon v_\varepsilon = o(\varepsilon) & \text{on } \Omega \\ v_\varepsilon = o(\varepsilon) & \text{on } \partial\Omega. \end{cases}$$

It seems that the estimate (46) comes from there? (good)

Complement 6: Details about the energy method

a) Hypothesis - weak formulation - statement

We assume $a_{ij} \in L^\infty(\mathbb{R}^N)$ as a function of $y' \quad \forall i \text{ and } j$.

We consider a more general problem, that is to say a mixed problem.

$$(47) \quad \begin{cases} -\frac{\partial}{\partial \alpha_i} \left[a_{ij} \left(\frac{x}{\varepsilon} \right) \frac{\partial u_\varepsilon}{\partial \alpha_j} \right] = f & \text{in } \Omega \\ u_\varepsilon = 0 & \text{on } \Gamma_0 \subset \partial\Omega, \Gamma_0 \text{ being of non zero measure.} \\ \frac{\partial u_\varepsilon}{\partial \nu_{A_\varepsilon}} = 0 & \text{on } \Gamma_1 \subset \partial\Omega \end{cases}$$

with $\Gamma_0 \cap \Gamma_1 = \emptyset$; $\Gamma_0 \cup \Gamma_1 = \partial\Omega$

$$(48) \quad \text{and} \quad \frac{\partial u_\varepsilon}{\partial \nu_{A_\varepsilon}} = a_{ij} \left(\frac{x}{\varepsilon} \right) \frac{\partial u_\varepsilon}{\partial \alpha_j} n_i \quad \text{on } \Gamma.$$

a_{ij} being still "P-periodic" and concif (property (4))

We consider then the elastic functional space (cf L.N 23/8 p 31)

$$(49) \quad V = \{ v / v \in H^1(\Omega), v = 0 \text{ on } \Gamma_0 \}.$$

We have: $H_0^1(\Omega) \subset V \subset H^1(\Omega)$.

Whence the weak formulation of (47)

$$(48) \quad \begin{cases} a_\varepsilon(u_\varepsilon, v) = (f, v) & \forall v \in V \\ u_\varepsilon \in V \end{cases}$$

With :

$$(49) \quad a_\varepsilon(u, v) = \int_\Omega a_{ij} \left(\frac{x}{\varepsilon} \right) \frac{\partial u}{\partial \alpha_j} \frac{\partial v}{\partial \alpha_i} dx \quad \text{and}$$

$$(50) \quad (f, v) = \int_\Omega f(x) v(x) dx.$$

We can now establish the following statement

Theorem 3 : u_ε converges toward u in V weak; u being solution of

$$(51) \quad \begin{cases} \mathcal{A}(u, v) = (f, v) & \forall v \in V \\ u \in V \end{cases}$$

$\mathcal{A}$ being defined by.

$$(52) \quad \mathcal{A}(\varphi, \psi) = \int_{\Omega} q_{ij} \frac{\partial \varphi}{\partial x_j} \frac{\partial \psi}{\partial x_i} dx.$$

with the same constant coefficients q_{ij} as above.

b) Proof : we shall show successively

i) the existence of a subsequence, still called u_ε , such as

$$u_\varepsilon \xrightarrow{\varepsilon \rightarrow 0} u \quad \text{in } V \text{ weak.}$$

and :

$$\xi_i^\varepsilon = a_{ij} \left(\frac{x}{\varepsilon} \right) \frac{\partial u_\varepsilon}{\partial x_j} \xrightarrow{\varepsilon \rightarrow 0} \xi_i \quad \text{in } L^2(\Omega) \text{ weak.}$$

ii) $\xi_i = \bar{q}_{ij} \frac{\partial u}{\partial x_j}$; $\bar{q}_{ij}$ being constant coefficients

$$\text{iv) } \bar{q}_{ij} = q_{ij}.$$

i) Existence of a subsequence weakly converging.

Let denote by $\| \cdot \|$ the norm in $H^1(\Omega)$ and $| \cdot |$ this of $L^2(\Omega)$.

$$\|v\|^2 = |v|^2 + |\text{grad } v|^2 \quad \text{then.}$$

Taking account of the concavity (4) and of the equivalence in V

$$\|v\|_0 = |\operatorname{grad} v|,$$

We obtain from (48).

$$m\beta \|u_\varepsilon\|^2 \leq \beta \|u_\varepsilon\|_0^2 \leq a_\varepsilon(u_\varepsilon, u_\varepsilon) \leq |f| \|u_\varepsilon\| \leq |f| \|u_\varepsilon\|$$

hence
$$\|u_\varepsilon\| \leq \frac{1}{m\beta} |f|$$

and then the existence of a subsequence u_{ε_k} such that.

$$(53) \quad u_{\varepsilon_k} \xrightarrow{\varepsilon \rightarrow 0} u \quad \text{in } V \text{ weak.}$$

Because a_{ij} is bounded.

$$(54) \quad a_{ij} \left(\frac{x}{\varepsilon} \right) \frac{\partial u_{\varepsilon_k}}{\partial x_j} \xrightarrow{\varepsilon \rightarrow 0} \xi_i \quad \text{in } L^2(\Omega) \text{ weak.}$$

in consequence.

$$a_\varepsilon(u_{\varepsilon_k}, v) = \left(\xi_i^{\varepsilon_k}, \frac{\partial v}{\partial x_i} \right) \xrightarrow{\varepsilon \rightarrow 0} \left(\xi_i, \frac{\partial v}{\partial x_i} \right) = (f, v) \quad \forall v \in V.$$

and therefore $\forall v \in \mathcal{D}(\Omega)$ whence.

$$(55) \quad f = - \frac{\partial \xi_i}{\partial x_i}$$

ii) identification of ξ_i

The idea of the following reasoning consists in choosing, in (48) a special v related to the solution of the transformed problem in order to get rid of terms for which the nature of the convergence is unknown.

The spaces W and $\tilde{W}$ being the same as above (cf. p.37) let introduce then the transformed operator A^* of A defined by.

$$(56) \quad A^* = - \frac{\partial}{\partial y_i} \left[a_{ij}(y) \frac{\partial}{\partial y_j} \right]$$

Let π be a homogeneous polynomial of degree $\pm$ which will be.

Then the following problem

$$(57) \begin{cases} w \in H^1(P) ; & A^* w = 0 \text{ in } P \\ w - \pi \in \dot{W} \end{cases}$$

has a unique solution because it is reduced to look for $\theta = w - \pi$ such that

$$(58) \begin{cases} a_p^*(\theta, \psi) = -a_p^*(\pi, \psi) \quad \forall \psi \in \dot{W} \\ \theta \in \dot{W} \end{cases}$$

with, as above for a_p ; $a_p^*(\varphi, \varphi) \geq \beta \|\varphi\|_{\dot{W}}^2$

$$w(y) = \pi(y) + \theta(y)$$

is defined almost everywhere on P and also outside of P by a periodic extension of θ . Thanks to the homogeneity of π we have

$$w\left(\frac{x}{\varepsilon}\right) = \frac{1}{\varepsilon} \pi(x) + \theta\left(\frac{x}{\varepsilon}\right).$$

Let introduce now:

$$(59) \quad w^\varepsilon(x) = \varepsilon w\left(\frac{x}{\varepsilon}\right) = \pi(x) + \varepsilon \theta\left(\frac{x}{\varepsilon}\right) \quad \text{which is solution of}$$

$$(60) \quad (A^\varepsilon)^* w^\varepsilon - \frac{\partial}{\partial x_j} \left[a_{ij}\left(\frac{x}{\varepsilon}\right) \frac{\partial w^\varepsilon}{\partial x_i} \right] = \frac{1}{\varepsilon} A^* w = 0. \quad \text{with } w^\varepsilon \in H^1(\Omega)$$

of which the weak formulation is

$$(61) \quad a_\varepsilon^*(w^\varepsilon, \psi) = 0 \quad \forall \psi \in H_0^1(\Omega) ;$$

Remark 9: this construction, rather artificial for everyone who has not invented it, allowed us to introduce this element w_ε

identifying ξ_i :

Let then $\varphi \in \mathcal{D}(\Omega)$, we are going to choose

$$v = \varphi w_\varepsilon \text{ in (48)}$$

$$\psi = \varphi u_\varepsilon \text{ in (61)}$$

in a such a way that subtracting the two equations we obtain:

$$\begin{aligned} (62) \quad a_\varepsilon(u_\varepsilon, \varphi w_\varepsilon) - a_\varepsilon^*(w_\varepsilon, \varphi u_\varepsilon) &= \int_\Omega \xi_i^\varepsilon \frac{\partial \varphi}{\partial x_i} w_\varepsilon dx - \int_\Omega a_{ij} \frac{\partial \varphi}{\partial x_j} u_\varepsilon \frac{\partial w_\varepsilon}{\partial x_i} dx \\ &= (f, \varphi w_\varepsilon) \quad \forall \varphi \in \mathcal{D}(\Omega) \end{aligned}$$

thanks to the disappearing of the term $\int_\Omega \varphi a_{ij} \frac{\partial u^\varepsilon}{\partial x_j} \frac{\partial w_\varepsilon}{\partial x_i} dx$.

We can now obtain the passage to the limit in (62), taking account of:

- The weak converging of ξ_i^ε in $L^2(\Omega)$ already mentioned.
- The strong convergence of w_ε in $L^2(\Omega)$; in fact

$$\int_\Omega (w_\varepsilon - \pi)^2 dx = \varepsilon^2 \int_\Omega \theta'(\frac{x}{\varepsilon}) dx \xrightarrow{\varepsilon \rightarrow 0} 0 \text{ thanks to the}$$

periodicity of θ .

- The strong convergence of u_ε toward u in $L^2(\Omega)$; in fact, $u_\varepsilon \rightarrow u$ in $H^1(\Omega)$ weak and the injection of $H_1(\Omega)$ in $L^2(\Omega)$ is compact

- The fact that $\frac{\partial w^\varepsilon}{\partial x_i} = \frac{\partial \pi}{\partial x_i} + \frac{\partial \theta}{\partial x_i} = c_i + \frac{\partial \theta}{\partial x_i}$ is P -periodic as well as:

$$\hat{\chi}_i(\frac{x}{\varepsilon}) = a_{ij}(\frac{x}{\varepsilon}) \frac{\partial w^\varepsilon}{\partial x_j}$$

The next is "classical" result saying that:

if g is P periodic, $g(\frac{x}{\varepsilon}) \xrightarrow{\varepsilon \rightarrow 0} m_P(g)$ in $L^2(\Omega)$ weak.

with:

$$m_P(g) = \frac{1}{|P|} \int_P g(u) du$$

So at the limit, (52) becomes.

$$\int_{\Omega} \xi_i \frac{\partial \varphi}{\partial x_i} \pi \, d\alpha - m_p \left(a_{ij} \frac{\partial w}{\partial y_i} \right) \int_{\Omega} \frac{\partial \varphi}{\partial x_j} u \, d\alpha = (f, \varphi \pi) \quad \forall \varphi \in \mathcal{D}(\Omega)$$

And then, taking account of (55) we obtain.

$$\begin{aligned} (f, \varphi \pi) &= \left(-\frac{\partial \xi_i}{\partial x_i}, \varphi \pi \right) = \left(\xi_i, \frac{\partial \varphi}{\partial x_i} \pi \right) + \left(\xi_i, \varphi \frac{\partial \pi}{\partial x_i} \right) \\ &= \left(\xi_i, \frac{\partial \varphi}{\partial x_i} \pi \right) + m_p \left(a_{ij} \frac{\partial w}{\partial y_i} \right) \int \varphi \frac{\partial u}{\partial x_j} \, d\alpha. \\ &\quad \forall \varphi \in \mathcal{D}(\Omega). \end{aligned}$$

Whence

$$(64) \quad \xi_i \frac{\partial \pi}{\partial x_i} = m_p \left(a_{ij} \frac{\partial w}{\partial y_i} \right) \frac{\partial u}{\partial x_j}.$$

But we have still the choice of π and because we are interested by ξ_i , it is natural to choose simply $\pi(x) = x_e$. Let denote by w_e the corresponding solution of (57) and then.

$$(65) \quad \xi_e = m_p \left(a_{ij} \frac{\partial w_e}{\partial y_i} \right) \frac{\partial u}{\partial x_j} = \hat{q}_{ej} \frac{\partial u}{\partial x_j} \quad \text{q. e. d.}$$

iii) comparison of $\hat{q}_{ej}$ with q_{ej} obtained by the first method.

$$\hat{q}_{ej} = \frac{1}{V(P)} \int_P a_{ij}(y) \frac{\partial w_e}{\partial y_i} \, dy = \frac{1}{V(P)} \int_P a_{ij}(y) \frac{\partial}{\partial y_i} [y_e + \theta_e(y)] \, dy.$$

$$= \frac{1}{V(P)} a_p^* (\theta_e + y_e, y_j)$$

$$\text{So : } V(P) \hat{q}_{ej} = a_p^* (\theta_e, y_j) + a_p^* (y_e, y_j).$$

Proceedingly, we founded (cf p 6)

$$V(P) q_{ej} = -a_p(x^j, y_e) + a_p(y_j, y_e)$$

but on the one hand:

and on the other hand:

$$a_p^*(\theta_e, y_j) = a_p(y_j, \theta_e) = a_p(x^j, \theta_e) \quad \text{from (45) taking } \psi = \theta_e$$

$$- a_p(x^j, y_e) = - a_p^*(y_e, x^j) = a_p^*(\theta_e, x^j) = a_p(x^j, \theta_e) \\ \text{from (58) taking } \psi = x^j.$$

Whence the conclusion:

$$q_{ej} = q_{ej}^1.$$

So, taking account of (65) and (55)

$$- q_{ij} \frac{\partial^2 u}{\partial x_i \partial x_j} = f.$$

That is exactly the equation (51) because $u \in V$.

Remark 10: The results of the theorems 1 and 2 are consistent since the "homogenized solution" is the same. That insures the uniqueness of the set of the coefficients q_{ij} . The strong of the convergence depending of the regularity of the a_{ij} .
