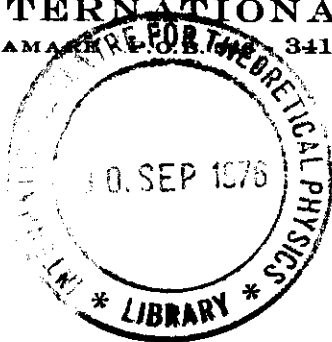




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SMR/26 - 2

AUTUMN WEEK ON

GEOMETRY OF THE LAPLACE OPERATOR

27 September - 3 October 1976

BASIC FACTS ON HARMONIC MAPS

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BASIC FACTS ON HARMONIC MAPS

J.C. Wood

①

Introduction We formulate harmonic maps in the real and complex cases and discuss some elementary properties and examples. No mention of existence problems is made. For full proofs see cited references.

References are numbered according to "BIBLIOGRAPHY FOR HARMONIC MAPS —(1976) "

Preliminary lecture notes for Autumn Week on "Geometry of the Laplace Operator".

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1 PRELIMINARIES ON RIEMANNIAN GEOMETRY

①

(A) Tensors and Forms

Let M be a manifold of class C^∞ and TM its tangent bundle. Let T_pM denote the fibre of TM over $p \in M$, a member of T_pM is called a tangent vector at p . A smooth section of TM is called a vector field.

Let T^*M denote the dual bundle of TM , we can form the bundle $\underbrace{TM \otimes \dots \otimes TM}_{r \text{ times}} \otimes \underbrace{T^*M \otimes \dots \otimes T^*M}_{s \text{ times}}$; a smooth section

of this is called a tensor field (r times contravariant, s times covariant). We shall denote the space of smooth sections of any bundle E over M by $C^\infty(E)$, $C^\infty(M)$ will denote the ring of smooth functions $M \rightarrow \mathbb{R}$. If $r=0$, a tensor field F gives an s -linear map on each tangent space T_pM , if this map is alternating we call F an s -form.

More generally, let E be any vector bundle over M . A smooth section of $\underbrace{TM \otimes \dots \otimes TM}_{r \text{ times}} \otimes \underbrace{T^*M \otimes \dots \otimes T^*M}_{s \text{ times}} \otimes E$ is called

an E -valued tensor (r times contravariant, s times covariant). If $r=0$ we can interpret such a tensor as an s -linear bundle map from TM to E . If this map is alternating on each tangent space we call the tensor an E -valued s -form.

Example Let $f: M \rightarrow N$ be a smooth map between smooth manifolds. Let $E =$ the pull-back bundle $f^{-1}TN$. Then the derivative df of f can be considered to be a smooth section of $T^*M \otimes E$.

Local coordinates If (x^1, \dots, x^m) are local coordinates for M , the vector fields $\frac{\partial}{\partial x^1}, \dots, \frac{\partial}{\partial x^m}$ give ^(local) a basis for TM and their duals

dx^1, \dots, dx^m give a basis for T^*M . All possible tensor products give bases for $TM \otimes \dots \otimes TM \otimes T^*M \otimes \dots \otimes T^*M$. In the example, a basis for $E = f^{-1}TN$ is given by pulling back a basis for TN ; if (u^1, \dots, u^n) are local coordinates for N , then $\{ dx^i \otimes \frac{\partial}{\partial u^j} \}$ gives a

② (B) Metric A ^{Riemannian} metric on a bundle E over M is a smooth section g of $E^* \otimes E^*$ (where E^* denotes the dual bundle of E) such that for each $p \in M$ g gives a pairing $\langle \cdot, \cdot \rangle_p: E_p \times E_p \rightarrow \mathbb{R}$ (here E_p denotes the fibre of E over p) with the properties:

- (1) $\langle X, Y \rangle_p = \langle Y, X \rangle_p \quad \forall X, Y \in E_p$ (symmetry)
- (2) $\langle X+Y, Z \rangle_p = \langle X, Z \rangle_p + \langle Y, Z \rangle_p \quad \forall X, Y, Z \in E_p$ (bilinearity)
- (3) $\langle aX, Y \rangle_p = a \langle X, Y \rangle_p \quad \forall X, Y \in E_p \quad \forall a \in \mathbb{R}$ ("")
- (4) $\langle X, X \rangle_p > 0 \quad \forall X \in E_p, X \neq 0$ (positive definiteness)

A metric on TM is called a Riemannian metric on M ; M together with a chosen Riemannian metric is called a Riemannian manifold.

If M is a ^{compact} Riemannian manifold and E a bundle over M with a Riemannian metric, all the bundles $TM \otimes \dots \otimes TM \otimes T^*M \otimes \dots \otimes T^*M \otimes E$ "inherit" metrics in a canonical way from the metrics on TM and E , using this metric the "global inner product" of two E -valued tensors ~~is def~~ F_1, F_2 is defined as the integral

$$\langle F_1, F_2 \rangle = \int_M \langle F_1, F_2 \rangle_p \omega_M \quad \text{where}$$

ω_M is the volume form of M

Local coordinates If (x^1, \dots, x^m) are local coordinates for M then $\{dx^i \otimes dx^j\}$ is a basis for $T^*M \otimes T^*M$. Thus a metric g on M can be written locally as

$$g = g_{ij} dx^i \otimes dx^j \quad (\text{double summation convention})$$

where $g_{ij} = g_{ji}$. The tensor product sign may be omitted.

Example Recall a basis for $T^*M \otimes E$ is given by $\{dx^i \otimes \frac{\partial}{\partial x^a}\}$ in the case $E = f^{-1}TN$, and thus the derivative df of f can be written as $f_i^\alpha dx^i \otimes \frac{\partial}{\partial x^\alpha}$. Then

$$\langle df, df \rangle_p = g^{ij} h_{\alpha\beta} f_i^\alpha f_j^\beta \quad \text{where}$$

$h_{\alpha\beta} du^\alpha \otimes du^\beta$ is the metric on N and $g^{ij} = (g_{ij})^{-1}$ (inverse matrix).

(3)

(C) Connections on Manifolds and Bundles Let M be a ~~Riemannian~~ smooth manifold. A connection or covariant differentiation D on M is a real-linear map $D: C^\infty(TM) \otimes C^\infty(TM) \rightarrow C^\infty(TM)$

$$(Z, X) \longmapsto D_Z X$$

- satisfying:
- (1) $D_{fZ}(X) = f D_Z X \quad \forall f \in C^\infty(M)$
 - (2) $D_Z(gY) = g D_Z(Y) + (\nabla_Z g) Y \quad \forall g \in C^\infty(M)$

Here $\nabla_Z g$ denotes the directional derivative of g in direction Z which may be defined as $dg(Z)$ where $dg: TM \rightarrow \mathbb{R}$ is the derivative of g .

~~The connection~~ If M is a Riemannian manifold, the connection D is s.t.b. Riemannian if $\forall X, Y, Z \in C^\infty(TM)$

$$(3) \nabla_Z \langle X, Y \rangle = \langle D_Z X, Y \rangle + \langle X, D_Z Y \rangle$$

$$(4) D_Z X - D_X Z = [X, Z] \quad (\text{where } [\ , \] \text{ is the bracket of two vector fields})$$

i.e. D is "torsion free". There exists a unique torsion free Riemannian connection on a Riemannian manifold called the Levi-Civita connection.

Let (X_1, \dots, X_m) be a local basis of vector fields. A connection may be specified by giving a matrix of connection 1-forms (Φ_i^k) $i, k=1, \dots, m$ defined by $D_Z X_i = \Phi_i^k(Z) X_k$.

The Christoffel symbols of the connection are the numbers $\Gamma_{ij}^k = \Phi_i^k(X_j)$

Now let E be a vector bundle over M . A connection on E is defined as a real-linear map $D': C^\infty(TM) \times C^\infty(E) \rightarrow C^\infty(E)$
 $(Z, X) \longmapsto D'_Z X$

satisfying (1) and (2) above. If E has a metric $\langle \ , \ \rangle$, D' is s.t.b. a Riemannian connection and E is s.t.b. Riemannian connected if (3) and (4) above hold. Again, a connection on E

can be specified by a matrix of connection 1-forms w.r.t. a basis for ~~the~~ E . Note D' can be considered as a real-linear map $D': C^\infty(E) \rightarrow C^\infty(TM^* \otimes E)$

We shall now show how to define a sequence of covariant differentiations

$$C^\infty(E) \xrightarrow{\tilde{D} = D'} C^\infty(TM^* \otimes E) \xrightarrow{\tilde{D}} C^\infty(TM^* \otimes TM^* \otimes E) \xrightarrow{\tilde{D}} \dots$$

④

Firstly the Levi-Civita connection on M can be used to define covariant differentiations $D_Z : C^\infty(TM \otimes \dots \otimes TM \otimes T^*M \otimes \dots \otimes T^*M) \rightarrow C^\infty(TM \otimes \dots \otimes TM \otimes T^*M \otimes \dots \otimes T^*M)$ by insisting that the "product rule" holds viz:

$D_Z(X \otimes Y) = D_Z X \otimes Y + X \otimes D_Z Y$ for any tensor fields X, Y , for all $Z \in C^\infty(TM)$. In particular

$D_Z : C^\infty(T^*M) \rightarrow C^\infty(T^*M)$ is found by solving

$D_Z(W(Y)) = (D_Z W)(Y) + W(D_Z Y) \quad \forall W \in C^\infty(T^*M)$
 $\forall Y, Z \in C^\infty(TM)$. It follows that if D has connection 1-forms Φ_i^k w.r.t. a basis $\{x^1, \dots, x^m\}$ and if $\{x^1, \dots, x^m\}$ is the dual basis of 1-forms, $D_Z : C^\infty(T^*M) \rightarrow C^\infty(T^*M)$ is given by $D_Z X^k = -\Phi_i^k(Z) X^i$.

To define $\tilde{D} : C^\infty(T^*M \otimes E) \rightarrow C^\infty(T^*M \otimes T^*M \otimes E)$ we again require that the "product law" holds viz, if $W \in C^\infty(T^*M)$ $e \in C^\infty(E)$:

$$\tilde{D}(W \otimes e) = \tilde{D}(W) \otimes e + W \otimes \tilde{D}(e)$$

or equivalently:

$$\tilde{D}_Z(W \otimes e) = \tilde{D}_Z(W) \otimes e + W \otimes \tilde{D}_Z(e) \quad \forall Z \in C^\infty(TM)$$

Note that $\tilde{D}(W)$ ~~can~~ be defined as $D(W)$ and $\tilde{D}(e)$ as $D'(e)$ so we have, as the definition of our \tilde{D} :

$$\tilde{D}_Z(W \otimes e) = D_Z(W) \otimes e + W \otimes D'_Z(e)$$

Another useful formula for \tilde{D}_Z is, for $W \in C^\infty(T^*M \otimes E)$:

$$(\tilde{D}_Z, W)(Z_2) = D'_{Z_1}\{W(Z_2)\} - W\{D_{Z_1} Z_2\}$$

$(Z_1, Z_2 \in C^\infty(TM))$ so that $W(Z_2) \in C^\infty(E)$

Divergence Define the (generalised) divergence $\tilde{\delta}$:

$C^\infty(T^*M \otimes E) \rightarrow C^\infty(E)$ as the composition:

$$C^\infty(T^*M \otimes E) \xrightarrow{\tilde{D}} C^\infty(T^*M \otimes T^*M \otimes E) \xrightarrow{\text{Tr}} C^\infty(E)$$

⑤ where if $\beta \in C^\infty(T^*M \otimes T^*M \otimes E)$, $\text{Tr} \beta$ may be defined as $\text{Tr} \beta = \sum_i \beta(x_i, x_i)$ where x_i is an orthonormal basis.

Proposition ~~is~~ $-\tilde{D}$ is the adjoint of $\tilde{D}: C^\infty(E) \rightarrow C^\infty(T^*M \otimes E)$ i.e.

$$\int_M \langle \tilde{D}\alpha, \beta \rangle = - \int_M \langle \alpha, \tilde{D}\beta \rangle$$

if $\alpha \in C^\infty(E)$, $\beta \in C^\infty(T^*M \otimes E)$ where $\langle \rangle$ denotes the metric on $T^*M \otimes E$ (l.h. side), E (r.h. side).

Proof see [16], [34].

Case when $E = f^{-1}TN$

Let $f: M \rightarrow N$ be a smooth map between Riemannian manifolds. Let $E = f^{-1}TN$. Then E inherits a metric from that of TN and can also be given a connection by pulling back the Levi-Civita connection on TN . Specifically, if e_1, \dots, e_n is a local basis for TN which is pulled back to a local basis (which we still denote by e_1, \dots, e_n) for E define the connection 1-form of E w.r.t. this basis by:

$$\Theta_\alpha^\gamma(z) = (\nabla_z f) (\Phi_\alpha^\gamma(df(z))) \quad z \in C^\infty(TM)$$

where Φ_α^γ are the connection 1-forms for N

$$= (\nabla_z f^\beta) L_{\alpha\beta}^\gamma$$

where $L_{\alpha\beta}^\gamma$ are the Christoffel symbols for N .

Note that since TN is Riemannian connected it easily follows that E is.

The following formulae follow from the product rule:

(a) If $e \in C^\infty(E)$, $z \in C^\infty(TM)$; if e has components $\{e^1, \dots, e^n\}$ w.r.t. some local basis for E ;

$$\{\tilde{D}_z e\}^\gamma = \nabla_z(e^\gamma) + \Theta_\alpha^\delta(z) e^\alpha$$

⑥ (b) If $W \in C^\infty(T^*M \otimes E)$, $Z \in C^\infty(TM)$ and W has components W_j^α w.r.t. basis $\{dx^j \otimes \frac{\partial}{\partial u^\alpha}\}$ for

$T^*M \otimes E$ which is obtained from local coordinates (x^1, \dots, x^m) on M , (u^1, \dots, u^n) on N , then

$$\{\tilde{D}_{Z_i}(W)\}_j^\alpha = \nabla_{Z_i}(W_j^\alpha) - \Gamma_{ji}^k W_k^\alpha + (\nabla_{Z_i} f^\beta) L_{\alpha\beta}^\delta W_j^\alpha$$

where Γ_{ij}^k $L_{\alpha\beta}^\delta$ are the Christoffel symbols for M, N respectively and f^β denotes the β^{th} component of f w.r.t. the coordinates on N .

Notes This brief description may be supplemented by
 [H:3] [KN:13] basic differential geometry
 [11] [16] pull-back bundles etc.

2 THE CONCEPT OF A HARMONIC MAP

(A) Energy Let M, N be connected C^∞ Riemannian manifolds of dimensions m, n respectively and let $f: M \rightarrow N$ be a C^∞ map. Form the pull-back bundle $E = f^{-1}TN$ over M . This bundle together with the bundles $T^*M \otimes E$, $TM \otimes T^*M \otimes E$, etc. inherit metrics from those of M & N as described earlier. In particular the for derivative $df \in C^\infty(T^*M \otimes E)$, we have the inner product at each point $p \in M$

$$\langle df, df \rangle_p = \sum_i \langle df(x_i), df(x_i) \rangle_{E_p} \quad \text{where}$$

$\{x_i\}$ is an orthonormal basis for T_pM ; the number $e(f)(p) = \frac{1}{2} \langle df, df \rangle_p$ is called the energy density of f at p ; the ~~total~~ if M is compact, the number

$$E(f) = \int_M e(f) \nu_M \quad \text{is called the energy of } f$$

Intuitively, the energy density measures how much the map "stretches" at a point p , and the energy is a measure of the total amount of "stretching" of the map.

Local coordinates if (x^1, \dots, x^m) , (u^1, \dots, u^n) are local coordinates for M, N respectively, then $df = f_i^\alpha dx^i \otimes \frac{\partial}{\partial u^\alpha}$

where $f_i^\alpha = \frac{\partial u^\alpha}{\partial x^i}$. Write

$g_{ij} dx^i dx^j$, $h_{\alpha\beta} du^\alpha du^\beta$ for the metrics on M, N respectively then

$$e(f)(p) = \frac{1}{2} g^{ij} f_i^\alpha f_j^\beta h_{\alpha\beta} \quad g^{ij} = (g_{ij})^{-1} \quad \text{(inverse matrix)}$$

Definition If M is compact $f: M \rightarrow N$ is harmonic if ~~f~~ is a stationary point for the energy functional E . ~~with~~ ^{w.r.t.} all small variations of f .

Note If M is not compact, we can define the energy $E(f, D) = \int_D e(f) \nu_M$

of f over any compact region D we say f is harmonic if it renders

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all energy functionals $E(\cdot, D)$ stationary wrt all smooth variations of f that are fixed on ∂D .

(B) Tension Given M, N, f as above we define the tension field of f as follows. Recall that using the ~~connections~~ Levi-Civita connections on M, N we can define covariant differentiations:

$TM^* = T^*M!$

$$\tilde{D}: C^\infty(E) \rightarrow C^\infty(TM^* \otimes E)$$

$$\tilde{D}: C^\infty(TM^* \otimes E) \rightarrow C^\infty(TM^* \otimes TM^* \otimes E)$$

In particular $\tilde{D}df \in C^\infty(TM \otimes T^*M \otimes E)$ is called the second fundamental form of f and $\text{Tr}(\tilde{D}df) \in C^\infty(E)$ is called the tension field of f denoted $\tau(f)$. Note the following formulae which follow from §1.

$$\tau(f) = \text{Tr} \tilde{D}df = \sum_i \tilde{D}df(x_i, x_i) \quad \text{where } \{x_i\} \text{ is an orthonormal basis for } TM$$

$$\tilde{D}df(x_i, x_j) = \mathcal{D}'_{x_j}(df(x_i)) - df\{D_{x_j}x_i\}$$

where \mathcal{D}' is the connection on E of D is the connection on TM .

$$\text{hence } \tau(f) = \sum_i \mathcal{D}'_{x_i}(df(x_i)) - \sum_i df\{D_{x_i}x_i\}$$

where $\{x_i\}$ is an orthonormal basis for TM

In local coordinates (same notation as ~~last~~ section A) $\tilde{D}df$ has components

$$f_{ij}{}^\gamma = f_{ij}{}^\gamma - \Gamma_{ij}^k f_k{}^\gamma + L_{\alpha\beta}{}^\gamma f_j{}^\alpha f_i{}^\beta$$

~~where~~ where

$$f_{ij}{}^\gamma = \frac{\partial^2 f^\gamma}{\partial x^i \partial x^j} \quad \& \quad \Gamma_{ij}^k, L_{\alpha\beta}{}^\gamma \text{ are Christoffel symbols for } M, N$$

$\tau(f)$ has components

$$\tau(f)^\gamma = g^{ij} f_{ij}{}^\gamma - \dots - \Gamma_{ij}^k \Gamma_{\alpha\beta}{}^\gamma + \dots$$

⑨ (c) Tie-up - First Variation of the Energy Let $f_t: M \times I \rightarrow N$
 be a C^∞ with $f_0 = f$ We calculate

$$\left. \frac{dE(f_t)}{dt} \right|_{t=0} = \frac{1}{2} \int_M \sum_i \langle df(x_i), df(x_i) \rangle_E \quad \{x_i\} \text{ orthonormal basis for } TM$$

$$= \int_M \sum_i \langle \frac{D'}{dt} df(x_i), df(x_i) \rangle_E$$

since E is Riemannian connected and \langle, \rangle is symmetric ~~with $\frac{D'}{dt}$~~

$$= \int_M \langle D'_{x_i} \frac{\partial f}{\partial t}, df(x_i) \rangle_E \quad \text{since } \frac{\partial}{\partial t} \text{ and } e_i$$

clearly have zero bracket on $M \times (-\epsilon, \epsilon)$

$$= \int_M \langle \tilde{D}w, df \rangle_{TM \otimes E}$$

where $w = \frac{\partial f}{\partial t}|_{t=0}$

$$= - \int_M \langle w, \tau(f) \rangle \quad \text{since adjoint of } \tilde{D} \text{ is } -\text{Tr } \tilde{D}$$

Thus E is stationary for all small variations $\Leftrightarrow \tau(f) \equiv 0$ We thus now adopt the definition

Definition $f: M \rightarrow N$ is harmonic if $\tau(f) \equiv 0$.

Notes For a better explanation of above calculation see [173], [15][16][17], for the second variation of the energy see [34][49].

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(D) Interpretation of the condition $\tau(f) = 0$ [187]

Definitions: By a (parametrised) curve c in N through $q \in N$ we mean a smooth map

$c: (-\epsilon, \epsilon) \rightarrow N$ with $c(0) = q$. The acceleration vector of c at q is the vector $\left. \frac{D'}{dt} \frac{\partial c}{\partial t} \right|_{t=0}$. This is a tangent vector at q .

c is a geodesic if its acceleration vector at each point is zero, more generally if the parameter t measures arc length (i.e. c is an isometry) the acceleration vector of c at q is merely the geodesic curvature of c at q .

Now let $f: M \rightarrow N$ be a smooth map, let $p \in M$ and let $\{X_1, \dots, X_m\}$ be an orthonormal basis of tangent vectors at p . Let γ_i be the unique geodesic of M through p tangent to X_i .

Claim:

$\tau(f)(p) = \sum \text{sum of acceleration vectors of the parametrised curves } f \circ \gamma_i$ at $q = f(p)$.

NSZ Here, and elsewhere, rather than considering $\tau(f)$ as a section of the bundle $f^{-1}TN$, it is convenient to consider $\tau(f)$ as a smooth map $\tau(f): M \rightarrow TN$ with $\tau(f)(p) \in T_{f(p)}N$. Such a map is called a vector field along f .

Proof of Claim From the formulae in §B

$$\tau(f) = \sum D'_{X_i} (df(X_i)) - \sum df\{D_{X_i} X_i\}$$

~~The second term is zero at p .~~ Choose normal coordinates (x_1, \dots, x_m) for M centred on p and choose the basis X_1, \dots, X_m by $X_i = \frac{\partial}{\partial x_i}$. Then since the "axes" through p are geodesics, $D_{X_i} X_i = 0$ and the second term vanishes. The first term can be written

$$\sum \frac{D'}{dx_i} \frac{df}{dx_i} \quad \text{and the claim follows.} \quad \text{Thus:}$$

Proposition A smooth map $f: M \rightarrow N$ is harmonic (\Leftrightarrow) at all points $p \in M$ and for all sets of geodesics $\{\gamma_1, \dots, \gamma_m\}$ of M through p whose tangents at p form an orthonormal set, the sum of the acceleration vectors of the curves $f \circ \gamma_i$ is zero.

Thus a harmonic map is one that maps geodesics into "a set of curves"

(11) 3 SPECIAL TYPES OF HARMONIC MAPS

(A) Totally geodesic maps [11] Defn $f: M \rightarrow N$ is s.t. b. totally geodesic if its second fundamental form $\tilde{D}df$ is identically zero. Lemma: f is totally geodesic \Leftrightarrow it maps geodesics to geodesics linearly.

Proof In normal coordinates ~~(x^1, \dots, x^m)~~ centred on a point $p \in M$ and normal coordinates (u^1, \dots, u^n) centred on $f(p) \in N$ ~~we have~~ we have the simple expressions for the components of $\tilde{D}df$
 ~~$\tilde{D}df(x^i, x^j) = \frac{\partial^2 f^\alpha}{\partial x^i \partial x^j} dx^\alpha$~~ $f_{;ij}^\gamma = \frac{\partial^2 f^\gamma}{\partial x^i \partial x^j}$ The

lemma follows.

Clearly, a totally geodesic map is harmonic.

(B) Geodesics [11] If M is 1-dimensional, to be specific, suppose $M =$ open subset of \mathbb{R} we have, (as before):

$\tau(f) =$ acceleration vector of $f: M \rightarrow N$. Hence

f is harmonic $\Leftrightarrow f$ is a geodesic.

This is a special case of (A).

(C) Harmonic Functions [11] If N is 1-dimensional, to be specific, suppose $N = \mathbb{R}$ then:

$\tau(f) = \Delta f =$ the Laplacian of the function $f: M \rightarrow \mathbb{R}$

This can be seen from the expression in §2B for $\tau(f)$ in local coordinates: which reduces to

$$\tau(f) = g^{ij} f_{;ij} - g^{ij} \Gamma_{ij}^k f_k$$

which is a well-known expression for the Laplacian of f .

Note The Laplacian of f may be defined as:

$$\Delta f = \delta df \quad \text{where } \delta = \text{Tr} \circ D$$

Hence $f: M \rightarrow \mathbb{R}$ is a harmonic map $\Leftrightarrow f$ is a harmonic function

Thus the concept of harmonic map is a generalisation of the concept of harmonic function.

(D) Minimal Immersions [11] $f: M \rightarrow N$ is called a Riemannian immersion if df is an isometry on each tangent space. The mean normal curvature field H of such a map may be defined as follows: ~~choose~~ given $p \in M$, choose geodesics γ_i in M through p such that the tangent vectors of the γ_i form an orthonormal basis for the tangent space at p , then $H(p) = \sum_i$ acceleration vectors of $f \circ \gamma_i$ at $f(p)$. Then clearly we have (by 52D):

Lemma For a Riemannian immersion: $\tau(f) = H$

Note also:

Lemma For a Riemannian immersion $\tau(f)(p)$ is perpendicular to $T_p M$

This can be proved in local coordinates [11] but is also obvious from the interpretation of $\tau(f)(p) = H(p)$ as the sum of acceleration vectors.

We call a Riemannian immersion minimal if its mean normal curvature field = 0.

Proposition [11] A Riemannian immersion is harmonic \Leftrightarrow it is minimal.

(E) ~~Harmonic Maps~~ The Gauss Map of a Minimal Immersion [44]

Given a Riemannian immersion $i: M \rightarrow \mathbb{R}^{m+r}$ (M m -dimensional) we define its Gauss map $g: M \rightarrow G(m,r)$ = Grassmann manifold of m planes in \mathbb{R}^{m+r} by $g(p) =$ tangent plane $i_* T_p M$. Now we may form the mean normal curvature vector field H of i , which by the second Lemma of 5D is a cross-section of $N(M)$, the normal bundle of M . Using the covariant derivative on M we may form the covariant derivative ∇H of H in $N(M)$, $\nabla H \in C^\infty(T^*M \otimes NM)$. Ruh & Vilms [44] show that the bundle $T^*M \otimes NM$ may be identified with the bundle $g^{-1}TG(m,r)$ and

Lemma Under this identification $\nabla H = \tau(g)$. Hence:

Theorem [44] If $i: M \rightarrow \mathbb{R}^{m+r}$ is a Riemannian immersion with ~~parallel~~ mean normal curvature vector parallel in the normal bundle, its Gauss map is harmonic.

Corollary The Gauss-map of a minimal submanifold of Euclidean space is harmonic.

Corollary The Gauss-map of a surface M in \mathbb{R}^3 with constant ^{scalar} mean normal curvature is harmonic. Note since $N(M)$ is 1-dimensional the mean normal curvature field H has only one component.

(13)

(F) Harmonic Fibre Maps [11] [173] For any smooth map $f: M \rightarrow N$ we may write $TM = V \oplus H$ where $V_p = \{X \in T_p M : df(X) = 0\}$ and H_p is its orthogonal complement. Vectors in V are called vertical, vectors in H horizontal. f is called a Riemannian fibration if $df|_{H_p}$ is an isometry $\forall p \in M$. Such a map is a locally trivial fibre map [108]

Lemma $\tau(f)(p) = -df \circ \tau(i)(p)$ where i is the inclusion of the fibre containing p into M .

Proof Choose coordinates (x^1, \dots, x^m) for M centred on p such that:

(1) the vectors $X_i = \frac{\partial}{\partial x^i}$ form an orthonormal base for $T_p M$ with X_{n+1}, \dots, X_m vertical and X_1, \dots, X_n horizontal, (2) the axes x^1, \dots, x^n are the horizontal lifts of geodesics in N through $f(p)$ - by [108] they must also be geodesics. Then by the composition law

(see §5)

$$\tau(f \circ i) = df \circ \tau(i) + \sum_{i=n+1}^m \tilde{D} df(di(X_i), di(X_i))$$

But $f \circ i$ is constant so $\tau(f \circ i) = 0$. Also the last term

$$= \sum_{i=n+1}^m \tilde{D} df(X_i, X_i) = \sum_{i=1}^n \tilde{D} df(X_i, X_i) = \tau(f) \quad \text{since}$$

$$\tilde{D} df(X_i, X_i) = 0 \quad i=1, \dots, n \quad \text{by choice of coordinates.}$$

Proposition A Riemannian fibration is harmonic \Leftrightarrow all the fibres are minimal submanifolds

Proof By lemma, recalling $\tau(i) \in H$ (see §5D) and $\tau(i)$ = mean normal curvature of fibre in M , and remembering df is an isometry on H .

(G) Isomorphic Maps [11] Isomorphic and antiisomorphic maps between Kähler manifolds are harmonic - see §4.

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(H) Mappings of Spheres [173] [47] [48] [188]

(1) $S^2 \rightarrow S^2$ Treating S^2 as the Riemann sphere, the maps $z \mapsto z^k$ $k=0, \pm 1, \pm 2, \dots$ provide harmonic maps of each ^(topological) degree k .

(2) Spherical Harmonics [173] A spherical harmonic f of degree k on \mathbb{R}^m is a homogeneous harmonic polynomial of degree k on \mathbb{R}^m . We examine $f|_{S^{m-1}}$. By an easy computation

$$\begin{aligned} \Delta_{S^{m-1}} f|_{S^{m-1}} &= \Delta_{\mathbb{R}^m} f|_{S^{m-1}} - \frac{\partial^2 f}{\partial r^2} - (m-1) \frac{\partial f}{\partial r} \\ &= -k(k+m-2) f|_{S^{m-1}} \end{aligned}$$

(Thus $f|_{S^{m-1}}$ is an eigenfunction of $\Delta_{S^{m-1}}$. All eigenfunctions of $\Delta_{S^{m-1}}$ arise in this way [B&M])

Note The definition of $\Delta_{S^{m-1}}$ $\Delta_{\mathbb{R}^m}$ may differ ~~by a~~ in sign from the one we have adopted. This will not trouble us.

Lemma Suppose $f: S^{m-1} \rightarrow S^{n-1}$ is the restriction of a homogeneous harmonic polynomial map $\mathbb{R}^m \rightarrow \mathbb{R}^n$, each polynomial $\mathbb{R}^m \rightarrow \mathbb{R}$ being of degree k . Then f is a harmonic map.

Proof By SJ (last prop): $\tau(f) = \text{proj}_{S^{n-1}} \{ \Delta_{S^{m-1}} f \}$ where f is considered as map $S^{m-1} \rightarrow \mathbb{R}^n$. But by computation above $\Delta_{S^{m-1}} f$ is normal to S^{m-1} .

Harmonic maps of this type may be constructed from

(3) Orthogonal Multiplications An orthogonal multiplication $F: \mathbb{R}^m \times \mathbb{R}^{m'} \rightarrow \mathbb{R}^n$ is a bilinear map s.t. $|F(x,y)| = |x||y| \quad \forall x \in \mathbb{R}^m, y \in \mathbb{R}^{m'}$. Given an orthogonal multiplication it is easily seen that the following maps are harmonic:

(1) the restriction $F: S^{m-1} \times S^{m'-1} \rightarrow S^{n-1}$

(2) if $m=m'$ the map $H: S^{2m-1} \rightarrow S^{n-1}$ given by $H(x,y) = (|x|^2 - |y|^2, 2F(x,y))$ where (x,y) are Euclidean coords for $\mathbb{R}^{2m} = \mathbb{R}^m \times \mathbb{R}^m$ ("Hopf construction")

(3) given two second order degree harmonic polynomial maps $f: S^{m-1} \rightarrow S^{q-1}$, $g: S^{m'-1} \rightarrow S^{q'-1}$ the map $h: S^{m+m'-1} \rightarrow S^{q+q'+n-1}$

$$h(x,y) = (f(x), g(y), \sqrt{2} F(x,y)) \rightarrow S^{q+q'+n-1}$$

where (x,y) are Euclidean coordinates for $\mathbb{R}^{m+m'} = \mathbb{R}^m \times \mathbb{R}^{m'}$.

(1) Examples (1) $F: \mathbb{R}^m \times \mathbb{R}^m \rightarrow \mathbb{R}^m$ $m=2, 4, 8$, given by multiplication of complex numbers, quaternions, Cayley numbers give the Hopf fibrations $S^3 \rightarrow S^2$, $S^7 \rightarrow S^4$, $S^{15} \rightarrow S^8$ when the "Hopf construction" above is applied. These maps are all harmonic.

(2) Real tensor product is an orthogonal multiplication $F: \mathbb{R}^m \times \mathbb{R}^m \rightarrow \mathbb{R}^{m^2}$ yielding harmonic maps $S^{2m-1} \rightarrow S^{m^2-1}$.

Many other examples are given in [173]

(4) Eikonals [188] Let $P: \mathbb{R}^m \rightarrow \mathbb{R}$ be a spherical harmonic of degree $k+1$. If

$$\left(\frac{\partial P}{\partial x_1}\right)^2 + \dots + \left(\frac{\partial P}{\partial x_m}\right)^2 = (x_1^2 + \dots + x_m^2)^k \quad (*)$$

then the gradient of P , $\left(\frac{\partial P}{\partial x_1}, \dots, \frac{\partial P}{\partial x_m}\right): \mathbb{R}^m \rightarrow \mathbb{R}^m$

restricts to $S^{m-1} \rightarrow S^{m-1}$ and is of course harmonic.

(*) is called the Eikonal equation of geometric optics and was studied by Cartan. The most general solution for $k=1$ is $P = \frac{1}{2}(x_1^2 + \dots + x_r^2 - x_{r+1}^2 - \dots - x_m^2)$ which is harmonic $\Leftrightarrow r=s$. This ~~is~~ resulting ~~is~~ harmonic maps $\left(\frac{\partial P}{\partial x_1}, \dots, \frac{\partial P}{\partial x_m}\right): S^{m-1} \rightarrow S^{m-1}$ are isometries.

Much more interesting are the solutions for larger k . R. Ward shows that we get: ($k=2$) harmonic maps $S^4 \rightarrow S^4$ $S^8 \rightarrow S^8$ $S^{13} \rightarrow S^{13}$ $S^{25} \rightarrow S^{25}$ of degree 2, ($k=3$) harmonic maps $S^5 \rightarrow S^5$ degree 1 $S^9 \rightarrow S^9$ degree 1.

(5) Joining Polynomial Maps of Spheres R.T. Smith [47] shows that two homogeneous harmonic polynomial maps $f: S^{m-1} \rightarrow S^{n-1}$ $g: S^{m'-1} \rightarrow S^{n'-1}$ of degree l and k may be "joined" to give a harmonic map $F: S^{m+m'-1} \rightarrow S^{n+n'-1}$ of the form $F(u, v) = \begin{pmatrix} \frac{g(v)}{|v|^k} \cos \alpha(t), \\ \frac{f(u)}{|u|^l} \sin \alpha(t) \end{pmatrix}$

where $\alpha: \mathbb{R} \rightarrow [0, \frac{\pi}{2}]$ is a smooth monotone function with $\alpha(t) \rightarrow 0$ as $t \rightarrow -\infty$ $\alpha(t) \rightarrow \frac{\pi}{2}$ as $t \rightarrow \infty$ and $t = \ln(|u|/|v|)$, provided

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Examples (1) Suspending a map is achieved by joining it with the ~~identity~~ ^{identity} map $S^0 \rightarrow S^0$. Suspending $S^2 \rightarrow S^2$ $z \mapsto z^k$ gives harmonic maps of degree k $S^n \rightarrow S^n$ for $n=2, \dots, 7$ (for larger n conditions for joining are no longer satisfied)

(2) Suspending the Hopf maps $S^3 \rightarrow S^2$ $S^7 \rightarrow S^4$ yields essential harmonic ~~representatives~~ maps $S^{n+1} \rightarrow S^n$ $n=3, \dots, 8$, $S^{n+3} \rightarrow S^n$ $n=5, \dots, 10$.

(I) Maps into S^1 and Tori [11] [32] [187] Let M be a connected compact oriented Riemannian manifold. Given any harmonic 1-form σ on M with integral periods, i.e. such that $\int_c \sigma$ is integral for all small closed curves c , choose a base point p_0 and set

$$f(p) = \int_{p_0}^p \sigma$$

This defines a ^{harmonic} map into $M/\mathbb{Z} = S^1$

(Note A harmonic 1-form may be defined as a 1-form which is locally of the form dg for some harmonic function g defined on part of M)

Harmonic maps in every homotopy class $M \rightarrow S^1$ may be constructed in this way, for the set of homotopy classes $[M, S^1]$ is canonically isomorphic to $H^1(M, \mathbb{Z})$, and any cohomology class in $H^1(M, \mathbb{Z})$ can be canonically represented by a harmonic 1-form on M with integral periods.

For ^{flat} tori $T = \mathbb{R}^n / \Gamma$ where Γ is a lattice generated by a_1, \dots, a_n , say, for any n harmonic 1-forms $\sigma_1, \dots, \sigma_n$:

$f: M \rightarrow \mathbb{R}^n / \Gamma = T$ defined by

$$p \mapsto a_1 \int_{p_0}^p \sigma_1 + \dots + a_n \int_{p_0}^p \sigma_n$$

provides a harmonic map in any desired homotopy class

Maps from a surface into tori are studied in [187].

(3) Compositions

Let $f: M \rightarrow N$ and $k: N \rightarrow P$ be smooth maps between connected Riemannian manifolds. If f and k are harmonic, it does not necessarily follow that $k \circ f$ is harmonic. In fact note the following formulae for the second fundamental form and tension field of $k \circ f$

(J1) $\tilde{D}d(k \circ f)(X, Y) = dk\{\tilde{D}df(X, Y)\} + \tilde{D}dk(df(X), df(Y))$

where $X, Y \in TM$, or in local coordinates:

(S2) $(k \circ f)_{;ij}{}^a = f_{;ij}{}^\alpha k_{\gamma}{}^a + k_{;\alpha\beta}{}^a f_i{}^\alpha f_j{}^\beta$

(S3) $\tau(k \circ f) = dk \circ \tau(f) + \sum \tilde{D}dk(df(x_i), df(x_i))$
 where $\{x_i\}$ is orthonormal basis in TM

or in local coordinates:

(S4) $\tau(k \circ f)^a = \tau(f)^\gamma k_\gamma{}^a + k_{;\alpha\beta}{}^a g^{ij} f_i{}^\alpha f_j{}^\beta$

where g_{ij} is metric on M .

From these formulae we deduce:

(a) Proposition [11] If f is harmonic and k is totally geodesic, then $k \circ f$ is harmonic.

(b) Proposition [18] If f is a weakly conformal map between surfaces and k is harmonic then $k \circ f$ is harmonic.

(c) Proposition [173] If f is a Riemannian fibration with fibres minimal submanifolds and k is harmonic then $k \circ f$ is harmonic.

Proofs (a) $\tilde{D}dk \equiv 0 \dots$ (b) A weakly conformal map f is one such that df is conformal or trivial on each tangent space. Such a map must be holomorphic or antiholomorphic and \therefore harmonic by GJC.

Further, ~~$\tilde{D}dk(df(x_i), df(x_i)) = \lambda^2 \tau(k)$~~

if we write $df(x_i) = \lambda Y_i$ where Y_i are unit vectors in TN then ~~$\tilde{D}dk(df(x_i), df(x_i))$~~ the Y_i must be an orthonormal basis whence $\sum \tilde{D}dk(df(x_i), df(x_i)) = \lambda^2 \sum \tilde{D}dk(Y_i, Y_i)$

$= \lambda^2 \tau(k) = 0 \dots$

(c) Similar proof. (see [173]).

(18)

Note also the useful

Proposition [11] If k is a Riemannian immersion, $\tau(f) = \text{proj}^?$ of $\tau(k \circ f)$ onto TN .

Proof The formula (J3) gives a decomposition of $\tau(k \circ f)$ into components in tangent bundle of N and normal bundle of N .

(k) Compositions with Convex Functions [21] [187] and [53]

A function $k: U \rightarrow \mathbb{R}$ defined on an open subset of N is s.t.b. convex (resp. strictly convex) if its second fundamental form $\mathfrak{D}^2 k$ is positive ~~semi-definite~~ (resp. positive definite).

Propn If $f: M \rightarrow N$ is harmonic and $k: U \rightarrow \mathbb{R}$ is convex where $U \supseteq f(M)$, then $k \circ f$ is subharmonic i.e. $\Delta(k \circ f) \geq 0$.

Proof By (J3) $\tau(k \circ f) = \Delta(k \circ f) = \sum_i \mathfrak{D}^2 k (df(x_i), df(x_i))$

(x_i orthonormal basis for TM) ...

Corollary (1) If M is compact $k \circ f$ must be constant

(2) If ^{further,} k is strictly convex then f must be constant

Proof (1) By maximum principle for subharmonic functions. (2) $\Delta(k \circ f) = \sum_i \mathfrak{D}^2 k (df(x_i), df(x_i)) = 0 \Rightarrow df(x_i) = 0 \forall x_i \Rightarrow df \equiv 0$.

These corollaries tell us much about the image of a harmonic map [21] [187] [53] for example: (1) every point ^{of N} has a neighborhood on which there may be defined a strictly convex function. Then no harmonic map can have its image in this neighborhood unless it is constant [21].

(2) Sampson's Maximum Principle [45] Let S denote a submanifold of N of codimension 1 passing through a point $q = f(p)$. Suppose S has definite fundamental form at q . Then if $f: M \rightarrow N$ is harmonic, no neighborhood of p is mapped entirely ~~to~~ the ^{concave} ~~convex~~ side of S .

This is proved by constructing [187] a ^{strictly} convex function k which changes sign when crossing S and then using the maximum principle for the subharmonic function $\Delta(k \circ f)$. It can be used to show [53] that for a non-constant harmonic map $f: M \rightarrow N$ M, N compact connected C^∞ Riemannian mds N oriented:

(19) 4 FORMULATION OF HARMONICITY FOR MAPS BETWEEN COMPLEX MANIFOLDS

(A) Preliminaries on Complex Manifolds (1) Let M be a differentiable manifold of even dimension $2m$. An almost complex structure on M is a tensor field $J \in C^\infty(T^*M \otimes TM)$ such that for each $p \in M$ $J: T_p M \rightarrow T_p M$ is an endomorphism satisfying $J^2 = -I$. A manifold with a given almost complex structure is called an almost complex manifold. For example \mathbb{R}^{2m} has standard almost complex structure J given on its trivial tangent bundle by $J(x_1, y_1, \dots, x_m, y_m) = (-y_1, x_1, \dots, -y_m, x_m)$.

A mapping $f: M \rightarrow N$ between two almost complex manifolds is called holomorphic if $df \circ J = J' \circ df$ and antiholomorphic if $df \circ J = -J' \circ df$ where J' denotes the almost complex structure on N . If there exists ^{on atlas of} charts $c_\alpha: U_\alpha \rightarrow \mathbb{R}^{2m}$ which are biholomorphic (i.e. c_α and c_α^{-1} are holomorphic) we say the complex structure is integrable and the manifold is called a complex manifold.

Such charts define local complex coordinates. Conversely, given any complex manifold M we may define an almost complex structure $J: T_p M \rightarrow T_p M$ by choosing a chart $c: U \rightarrow \mathbb{R}^{2m}$ and defining $J = \{dc(p)\}^{-1} \circ J_{\mathbb{R}^{2m}} \circ dc(p)$ where $J_{\mathbb{R}^{2m}}$ is the standard complex structure on \mathbb{R}^{2m} .

(2) A Hermitian metric g on an almost complex manifold M is a Riemannian metric which is invariant by the almost complex structure J i.e. $g(JX, JY) = g(X, Y) \quad \forall X, Y \in T_p M \quad \forall p \in M$. An (almost) complex manifold equipped with a Hermitian metric is called an (almost) Hermitian manifold.

Let $M = (M, g, J)$ be an almost Hermitian manifold and let D be the Levi-Civita connection on M . We say that g is a Kähler metric and M is a Kähler manifold if $D_X(JY) = J D_X Y \quad \forall X, Y \in C^\infty(TM)$

It can be shown (Newlander & Nirenberg) - that a Kähler manifold is always integrable and that a 1-complex dimensional almost Hermitian manifold is always Kähler.

On a Kähler manifold curvature tensors and Ricci tensors ~~have~~ commute with J see [KN27]

(20)

(3) Now let M be an ^{almost} complex manifold. It is useful to complexify the tangent bundle to give a bundle $T^{\mathbb{C}}M = TM \otimes_{\mathbb{R}} \mathbb{C}$.

We then identify $v \in TM$ with $v \otimes 1$ and write $v \otimes i$ as iv or iv . We extend J to $T^{\mathbb{C}}M$ by requiring it to be linear over \mathbb{C} . Now the complexified tangent bundle $T^{\mathbb{C}}M$

can be written as a direct sum of complex bundles

$$T^{\mathbb{C}}M = T^{1,0}M \oplus T^{0,1}M \quad \text{where}$$

$$T^{1,0}M = \{Z \in T^{\mathbb{C}}M : JZ = iZ\} = \{X - iJX : X \in TM\}$$

$$T^{0,1}M = \{Z \in T^{\mathbb{C}}M : JZ = -iZ\} = \{X + iJX : X \in TM\}$$

Conjugation $-: T^{\mathbb{C}}M \rightarrow T^{\mathbb{C}}M$ defined by $X + iY \mapsto X - iY$

$X, Y \in TM$ gives a real-linear isomorphism between $T^{1,0}M$ and $T^{0,1}M$.

We define similarly $T_{\mathbb{C}}^*M = T^*M \otimes_{\mathbb{R}} \mathbb{C}$, this is the dual of $T^{\mathbb{C}}M$, we then define $T_{1,0}^*M$ $T_{0,1}^*M$ similarly to the above - note that

$$T_{1,0}^*M = \{w \in T_{\mathbb{C}}^*M : w(X) = 0 \quad \forall X \in T^{0,1}M\}$$

$$T_{0,1}^*M = \{w \in T_{\mathbb{C}}^*M : w(X) = 0 \quad \forall X \in T^{1,0}M\}$$

The tensor product $T^{\mathbb{C}}M \otimes \dots \otimes T^{\mathbb{C}}M \otimes T_{\mathbb{C}}^*M \otimes \dots \otimes T_{\mathbb{C}}^*M$

can be decomposed similarly e.g.

$$T^{\mathbb{C}}M \otimes T^{\mathbb{C}}M = T^{2,0}M \oplus T^{1,1}M \oplus T^{0,2}M$$

where $T^{2,0}M = T^{1,0}M \otimes T^{1,0}M$, $T^{0,2}M = T^{0,1}M \otimes T^{0,1}M$

$$T^{1,1}M = T^{1,0}M \otimes T^{0,1}M \oplus T^{0,1}M \otimes T^{1,0}M$$

(4) Now let M be an almost Hermitian manifold with metric defined by g

We extend g to $T^{\mathbb{C}}M$ by insisting it be bilinear over \mathbb{C} .

Then g satisfies:

$$g(Z, iW) = g(iZ, W) = ig(Z, W)$$

$$g(Z, JW) = -g(JZ, W)$$

$$g(\bar{Z}, \bar{W}) = \overline{g(Z, W)}$$

Writing $Z = X + iY$
 $X, Y \in TM$ $g(Z, \bar{Z}) = g(X, X) + g(Y, Y) \geq 0$

BASES

(5) Let Z_1, \dots, Z_m be a ^(real) basis for $T^{1,0}M$, then

$\bar{Z}_1, \dots, \bar{Z}_m$ is a basis for $T^{0,1}M$, and together they form a basis for $T^{\mathbb{C}}M$

(6) It is convenient to denote \bar{z}_k by $z_{\bar{k}}$ and adopt the convention that small letters such as k, α may range over the indices $1, 2, \dots$ whereas large letters may range over $1, 2, \dots, \bar{1}, \bar{2}, \dots$. It is easily seen that

$$g_{j\bar{k}} = g(z_j, z_{\bar{k}}) = \overline{g_{k\bar{j}}}$$

$$g_{jk} = g(z_j, z_k) = 0$$

(6) COORDINATES Suppose now M is a complex manifold.

Let (z^1, \dots, z^m) be local complex coordinates for M , where

$z^i = x^i + iy^i$. Setting

$$z_i = \frac{\partial}{\partial z^i} = \frac{1}{2} \left(\frac{\partial}{\partial x^i} - i \frac{\partial}{\partial y^i} \right) \quad z_{\bar{i}} = \frac{\partial}{\partial z^{\bar{i}}} = \frac{1}{2} \left(\frac{\partial}{\partial x^i} + i \frac{\partial}{\partial y^i} \right)$$

gives a basis for $T^{1,0}M \oplus T^{0,1}M = T^cM$. The dual basis for T_c^*M is easily seen to be

$$dz^i = dx^i + i dy^i \quad d\bar{z}^i = dx^i - i dy^i$$

Now suppose $M = (M, g, J)$ is Kähler. Then w.r.t. the above basis the Christoffel symbols $\Gamma_{I\bar{J}}^K$ of M have only pure components $\Gamma_{i\bar{j}}^k, \Gamma_{\bar{i}j}^{\bar{k}}$, other components being zero. (Proof: use cond: $D_X JY = JD_X Y$)

NOTE It should first be mentioned that, as always, we extend the connection $D_X: C^\infty(TM) \rightarrow C^\infty(TM)$ to the complexified tangent bundle by requiring $D_X Y$ to be linear in X and Y over \mathbb{C} and then $\Gamma_{I\bar{J}}^K = k$ 'th component of $D_{z_I} z_{\bar{J}}$.

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(B) Harmonic Maps From a Complex Manifold

Let M, N be

Riemannian manifolds. Recall that, for a smooth map, $f: M \rightarrow N$, $\tau(f)$ is defined as $\text{Tr } \tilde{D}df$:

$$C^\infty(M, N) \xrightarrow{d} C^\infty(T^*M \otimes E) \xrightarrow{\tilde{D}} C^\infty(T^*M \otimes T^*M \otimes E) \xrightarrow{\text{Tr}} C^\infty(E)$$

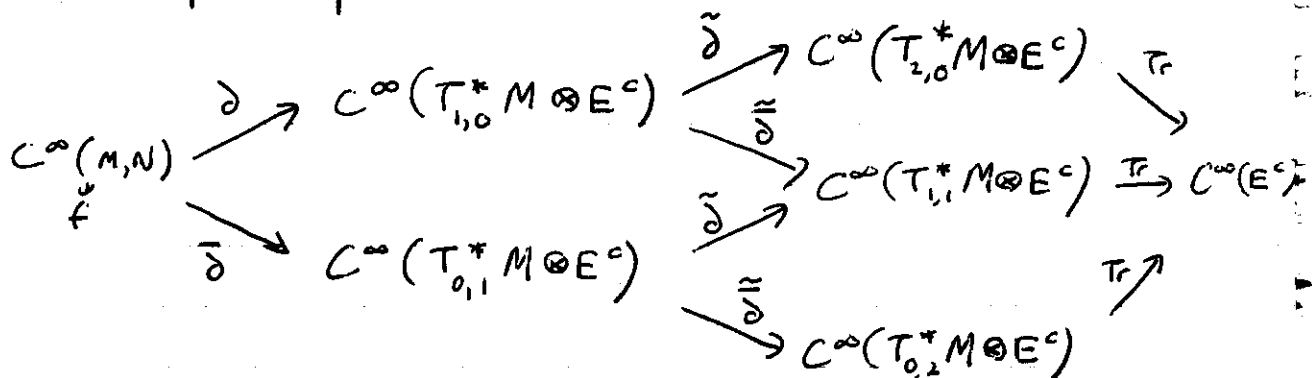
where $E = f^{-1}TN$. We can evidently replace each bundle by its complexification and extend the definitions of df, \tilde{D}, Tr by requiring them to be linear over \mathbb{C} :

$$C^\infty(M, N) \xrightarrow{d^c} C^\infty(T_c^*M \otimes E^c) \xrightarrow{\tilde{D}^c} C^\infty(T_c^*M \otimes T_c^*M \otimes E^c)$$

$$\downarrow \text{Tr}$$

$$C^\infty(E^c)$$

Now suppose M has an almost complex structure. Then we can decompose $T_c^*M = T_{1,0}^*M \oplus T_{0,1}^*M$, ~~and the maps decompose:~~ and the maps decompose:



and $\tau(f)$ is obtained by summing over the four routes.

But now suppose that M is almost hermitian. Then $g(Z, W) = 0$ if $Z, W \in T^{1,0}M$, it follows that the top and bottom Trace maps are the zero maps. Also $\tilde{\partial} \circ \partial = \tilde{\bar{\partial}} \circ \bar{\partial}$ (basically since $\bar{\partial}f = \overline{\partial f}$ etc.) Thus

$$\tau(f) = 2\text{Tr } \tilde{\partial} \circ \partial f = 2\text{Tr } \tilde{\bar{\partial}} \circ \bar{\partial} f$$

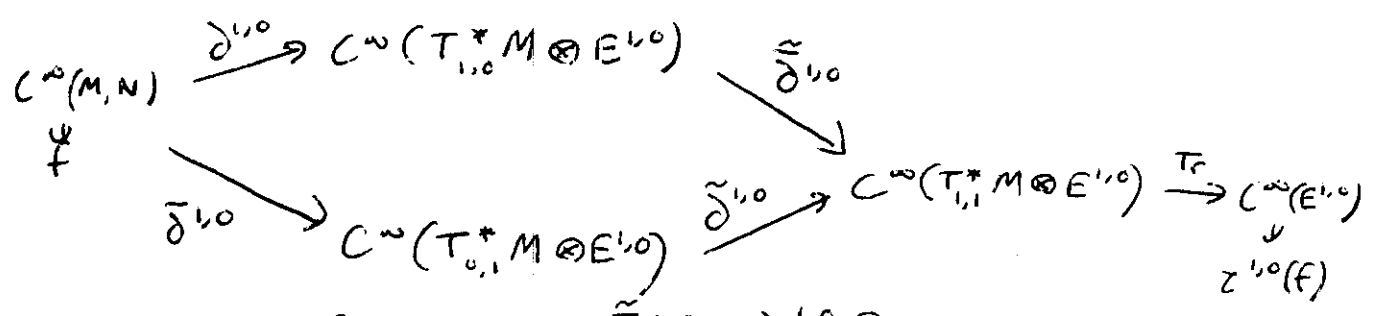
In local coordinates x , with complex coordinates on M

$$\tau(f)^r = 2g^{i\bar{j}} \left(f_{i\bar{j}}^r - \Gamma_{j\bar{i}}^k f_k^r + L_{\alpha\beta}^r f_j^\alpha f_i^\beta \right)$$

Further, if M is Kähler $\Gamma_{j\bar{i}}^k = 0$ and we thus see that harmonicity $M \rightarrow N$ depends only on the conformal equivalence class of the metric ~~g~~ g .

(23)

(c) Harmonic Maps Between Complex Manifolds Let M, N be Kähler manifolds. We can now split $E^c = E^{1,0} \oplus E^{0,1}$ and write $\partial = \partial^{1,0} + \partial^{0,1}$. We have a commutative diagram, for ~~F~~ the $(1,0)$ case:



We have $\tau^{1,0}(f) = 2 \text{Tr} \tilde{\partial}^{1,0} \circ \partial^{1,0} f$
 $= 2 \text{Tr} \tilde{\partial}^{1,0} \circ \bar{\partial}^{1,0} f$
 and $\tau^{0,1}(f) = \overline{\tau^{1,0}(f)}$

In local complex coordinates on M, N $\tau^{1,0} f$ is given by
 $\tau(f)^\gamma = 2 g^{\bar{\alpha}\beta} (f_{i\bar{j}}^\gamma + L_{\alpha\beta}^\gamma f_j^\alpha f_i^\beta)$
 remembering only the pure Christoffel symbols of M if it is non-zero

Note that f is holomorphic $\Leftrightarrow \bar{\partial}^{1,0} f = 0$
 f is antiholomorphic $\Leftrightarrow \partial^{1,0} f = 0$

hence from expression for $\tau^{1,0}(f)$ we very easily see that a holomorphic or antiholomorphic map between Kähler manifolds is harmonic

Note ~~A more general type of~~ See [33] for improvement of this result.

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