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REGULARITY AND UNIQUENESS OF HARMONIC MAPS INTO AN ELLIPSOID

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REGULARITY AND UNIQUENESS
OF HARMONIC MAPS INTO AN ELLIPSOID.

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This paper concerns harmonic maps from an open set Ω of \mathbb{R}^N into an n -dimensional ellipsoid

$$N = \{(u_I, u_{II}) \in \mathbb{R}^n \times \mathbb{R} / u_I^2 + \frac{u_{II}^2}{a} = 1\} \text{ where } a \in [0, 1].$$

First one shows that any harmonic map whose image lies in a compact subset of the open upper hemisphere of the ellipsoid N_+ is smooth. Then one proves the uniqueness of any harmonic map whose image lies in a compact subset of N_+ , and whose boundary data are prescribed. Using these results, one computes the minimizing map from a ball of dimension n into N whose boundary data are the equator map $\frac{x}{|x|}$.

Let $N = \{(u_I, u_{II}) \in \mathbb{R}^n \times \mathbb{R} / u_I^2 + \frac{u_{II}^2}{a} = 1\}$ be a n -dimensional ellipsoid, where $n \geq 1$ and $a > 0$.

$N_+ = \{u = (u_I, u_{II}) \in \mathbb{R}^n \times \mathbb{R} / u_{II} > 0\}$ is the upper hemi-

phère.

Let Ω be a bounded open set with regular boundary $\partial\Omega$ of \mathbb{R}^N where $N \geq 1$.

We consider the space $H^1(\Omega, N)$ of functions u of $H^1(\Omega, \mathbb{R}^{n+1})$ which verifies a.e. $u(x) \in N$. $H_0^1(\Omega, \mathbb{R}^{n+1})$ will be the closure of $C_c^\infty(\Omega, \mathbb{R}^{n+1})$ in $H^1(\Omega, \mathbb{R}^{n+1})$.

We define on $H^1(\Omega, N)$ the energy fonctionnal E by :

$$E(u) = \frac{1}{2} \int_{\Omega} |\nabla u(x)|^2 dx = \frac{1}{2} \int_{\Omega} \sum_{\alpha=1}^N \sum_{i=1}^{n+1} \left(\frac{\partial u_i}{\partial x_\alpha} \right)^2.$$

We will study the critical points of E , i.e. the weakly harmonic maps. They satisfy in the sense of distributions the following equations :

$$(0.1) \quad \begin{cases} \Delta u_I + \lambda u_I = 0 & (a) \\ \Delta u_{II} + \lambda \frac{u_{II}}{a} = 0 & (b) \end{cases}$$

where $\lambda = \left[|\nabla u_I|^2 + \frac{|\nabla u_{II}|^2}{a^2} \right] \frac{a^4}{a^4 u_I^2 + u_{II}^2}$, see e.g. A. Baldes [B].

We will only consider the case of a flattened ellipsoid, i.e. we will assume that $a \in (0, 1]$.

The first result is a regularity theorem. We will show that if $N \geq 3$, every harmonic map u whose image belongs to a compact subset of N_+ is smooth inside of Ω . This theorem is a variant of a result of S. Hildebrandt, H. Kaul and K-O. Widman who have proved in [HKW] the same result with a geodesic ball of radius M of a Riemannian manifold M instead of N_+ , with the condition that

$M < \frac{\pi}{2\sqrt{K}}$ where K is an upper bound of the sectionnal curvature of M . The two results coincide when $a = 1$, but the result of this paper is new in the case $a \in (0, 1)$. However the following proof is a variant of [HKW].

The second result is a uniqueness principle. If $N \geq 1$ we show that for every φ in $H^1(\Omega, N)$ such that $\varphi(x)$ lies in a compact subset of N_+ for a.e. x in $\partial\Omega$, there exists a unique smooth harmonic map whose image belongs to N_+ and which agrees with φ on $\partial\Omega$. This theorem is a variant of a result of W. Jäger and H. Kaul who have obtained the same result in [JK1] with a geodesic ball whose radius is strictly bounded by $\frac{\pi}{2\sqrt{K}}$. The two results coincide only when $a = 1$ but the proof here uses the same ideas of [JK1].

In the third part, we will use these two first results to study the following problem :

Let us suppose $n = N \geq 3$ and $\Omega = B^n = \{x \in \mathbb{R}^n / |x| < 1\}$, we consider the equator map $u_*(x) = (\frac{x}{|x|}, 0)$ of $H^1(B^n, N)$, and we want to find minimizing maps u of $H^1(B^n, N)$ which agree with the equator map on ∂B^n , i.e. a map u in $H^1(B^n, N)$ with the boundary condition $u|_{\partial B^n} = u_*|_{\partial B^n}$, and such that $E(u) \leq E(v)$ for any v in $H^1(B^n, N)$ such that $v|_{\partial B^n} = u_*|_{\partial B^n}$.

By a calculation of the hessian $\delta^2 E(u_*)$ of the energy fonctionnal E on u_* , A. Baldes showed in [B] that u_* cannot be a minimizing map if $a^2 < \frac{4(n-1)}{(n-2)^2}$, and that

$\Delta^2 E(u_*)(v, v) > 0$ for any v in $H_0^1(B^n, \mathbb{R}^{n+1}) \cap L^\infty(B^n, \mathbb{R}^{n+1})$ such that $v(x) \in T_{u_*(x)} N$ a.e. and $v \neq 0$ provided that $a^2 > \frac{4(n-1)}{(n-2)^2}$. Note that this does not imply that u_* is local minimizing. He proved also that if u_* is minimizing, then u_* is the unique minimizer. Here we will show that :

- if $a^2 < \frac{4(n-1)}{(n-2)^2}$, there is a smooth minimizing map.
- if $a^2 > \frac{4(n-1)}{(n-2)^2}$, u_* is the unique minimizer.

The proof here uses the movement of a point on a cycloid and is a variant of the method of W. Jäger and H. Kaul in [JK2] who solved this problem in the case of a sphere, i.e. when $a = 1$, using the movement of a pendulum.

I want to express my gratitude to J.M. Coron for his helpful advice.

1 - REGULARITY.

Let us formulate our first result.

Theorem 1. Suppose that $N \geq 3$, assume that $u \in H^1(\Omega, N)$, that the image of u belongs to a compact subset of N_+ , and that u verifies weakly (0.1).

Then u is smooth on Ω .

Remark. If $N = 1$, the regularity is trivial, if $N = 2$ Morrey showed in [M] regularity for minimizing maps.

Notations. In all the paper, we will note by the dot the

scalar product in \mathbb{R}^{n+1} , and by the bracket the scalar product in the dual space of \mathbb{R}^N , so that :

$$\text{If } \varphi \in H^1(\Omega, \mathbb{R}^{n+1}), \beta \in H^1(\Omega, \mathbb{R}), \langle \nabla \beta, \nabla \varphi \rangle = \sum_{\alpha=1}^N \frac{\partial \beta}{\partial x^\alpha} \frac{\partial \varphi}{\partial x^\alpha}$$

$$\text{If } \varphi, \psi \in H^1(\Omega, \mathbb{R}^{n+1}), \nabla \varphi \cdot \psi = \sum_{i=1}^{n+1} (\nabla \varphi^i) \psi^i.$$

Proof of theorem 1. We will prove only continuity. Smoothness then follows from [LU]. See also [BG] or [S].

Let us consider a weak harmonic map u whose image belongs to a compact subset of N_+ . So there exists $\alpha_0 > 0$ with :

$$(1.1) \quad u_{II} \geq \alpha_0 \text{ a.e. on } \Omega.$$

We consider the equation for f in $H^1(\Omega, \mathbb{R})$:

$$(1.2) \quad \begin{cases} -\Delta \zeta = f \\ \zeta \in H_0^1(\Omega, \mathbb{R}). \end{cases}$$

There is an associate Green function G which gives the solution of (1.2) by

$$(1.3) \quad \forall y \in \Omega, \zeta(y) = \int_{\Omega} f(x) G(x, y) dx.$$

For every point y of Ω , there exists σ_0 such that

$$B_{\sigma_0}(y) = \{z \in \mathbb{R}^N / |z-y| < \sigma_0\} \subset \Omega.$$

Then for $\sigma \in]0, \sigma_0]$, let us consider

$$(1.4) \quad G^\sigma(x, y) = \frac{1}{\text{mes}(B_\sigma(y))} \int_{B_\sigma(y)} G(x, z) dz = \int_{B_\sigma(y)} G(x, z) dz.$$

From (1.3) we deduce

$$(1.5) \quad \int_{\Omega} f(x) G^{\sigma}(x, y) dy = \int_{B_{\sigma}(y)} \zeta(z) dz.$$

We use too the following properties which are in [LSW] or in [HKW] : there exists strictly positive constants K_1, K_2, K_3 such that

$$(1.6) \quad 0 \leq G(x, y) \leq K_1 |x-y|^{2-N}$$

$$(1.7) \quad G(x, y) \geq K_2 |x-y|^{2-N}, \text{ if } |x-y| \leq \frac{3}{4} d(y, \partial\Omega)$$

$$(1.8) \quad |\nabla_x G(x, y)| \leq K_3 |x-y|^{1-N}$$

$$(1.9) \quad G^{\sigma}(x, y) \leq 2^{N-2} K_1 |x-y|^{2-N}, \text{ if } \sigma < \frac{1}{2} |x-y|.$$

$$(1.10) \text{ if } d(y, \partial\Omega) > \sigma, [x \mapsto G^{\sigma}(x, y)] \in H_0^1(\Omega, \mathbb{R}) \cap L^{\infty}(\Omega, \mathbb{R}).$$

where x and y are in Ω .

We take an arbitrary point of Ω and show that u is continuous on this point. It is always possible using translation in \mathbb{R}^N to assume that this point is 0. By (1.10) we may use the map

$[x \mapsto (0, G^{\sigma}(x, 0))]$ as a test function in (0.1), for σ small enough. This gives

$$(1.11) \quad \int_{\Omega} [\Delta u_{II}(x) G^{\sigma}(x, 0) + \lambda \frac{u_{II}(x)}{a^2} G^{\sigma}(x, 0)] dx = 0.$$

Let w in $H_0^1(\Omega, \mathbb{R})$ be the solution of the equation

$$\begin{cases} -\Delta w = 0 \\ w|_{\partial\Omega} = u_{II}|_{\partial\Omega} \end{cases}.$$

So $u_{II} - w \in H_0^1(\Omega, \mathbb{R})$ and by (1.5)

$$\begin{aligned} \int_{\Omega} \Delta u_{II}(x) G^{\sigma}(x, y) dx &= \int_{\Omega} \Delta (u_{II} - w) G^{\sigma}(x, y) dx = \\ &= - \int_{B_{\sigma}(0)} (u_{II} - w)(z) dz. \end{aligned}$$

Replacing this in (1.11),

$$\int_{\Omega} \lambda \frac{u_{II}}{a^2} G^{\sigma}(x, 0) dx = \int_{B_{\sigma}(0)} (u_{II} - w)(z) dz \leq a.$$

Using (1.1)

$$\int_{\Omega} \lambda G^{\sigma}(x, 0) dx \leq \frac{a^3}{a_0}.$$

Obviously $\lambda \geq a^2 |\nabla u|^2$ and so

$$(1.12) \quad \int_{\Omega} |\nabla u|^2 G^{\sigma}(x, 0) dx \leq \frac{a}{a_0}.$$

Now, using Fatou's lemma and passing to the limit in (1.12) when $\sigma \rightarrow 0$, we obtain

$$(1.13) \quad \int_{\Omega} |\nabla u(x)|^2 G(x, 0) dx \leq \frac{a}{a_0}.$$

Using (1.7), for ϵ_0 sufficiently small :

$$\int_{B_{\epsilon_0}(0)} |\nabla u(x)|^2 |x|^{2-N} \leq \frac{a}{a_0 K_2}.$$

Hence, by Lebesgue's theorem, if $\epsilon \rightarrow 0$

$$(1.14) \quad \int_{B_{\epsilon}(0)} |\nabla u(x)|^2 |x|^{2-N} \rightarrow 0.$$

And it follows that

$$(1.14) \text{ bis } \frac{1}{\epsilon^{N-2}} \int_{B_{\epsilon}(0)} |\nabla u(x)|^2 dx \rightarrow 0.$$

Let us remark, using the results of R. Schoen and K.

Uhlenbeck in [SU], that if u would be a minimizing map,

then (1.14)bis would be enough to prove regularity.

Now, for $R < \frac{\sigma}{2}$ let us define :

$$T_{2R} = \{x \in \Omega / R < |x| < 2R\}.$$

$$B_{2R} = \{x \in \Omega / |x| < 2R\}.$$

We note for $\alpha > 0$ $N_\alpha = N \cap \{u/u_{II} > \alpha\}$. So (1.1) implies that $u(x) \in N_{\alpha_0}$ a.e. .

We consider the point u_R of N_{α_0} which is defined by :

$$\begin{cases} u_{RI} = \int_{T_{2R}} u_I(x) dx \in \mathbb{R}^n \\ u_{RII} = a \sqrt{1 - (u_{RI})^2} \end{cases}$$

So we have the following inequality using Poincaré's inequality

$$\begin{aligned} (1.15) \quad \|u - u_R\|_{L^2(T_{2R})} &\leq K_{\alpha_0} \|u_I - u_{RI}\|_{L^2(T_{2R})} \\ &\leq K_{\text{Poincaré}} K_{\alpha_0} R \|\nabla u_I\|_{L^2(T_{2R})} \\ &\leq K_4 R \|\nabla u\|_{L^2(T_{2R})}. \end{aligned}$$

We consider the constant speed parametrag of the unique geodesic in N_{α_0} the extremities of which are u_R and the north pole $P = (0, a)$,

$$[0, 1] \ni t \mapsto u_{R,t}, \text{ with } u_{R,0} = P, u_{R,1} = u_R.$$

For the sake of commodity we note $v = u_{R,t}$.

We define the linear mapping $A : \mathbb{R}^{n+1} \rightarrow \mathbb{R}^{n+1}$,

$(u_I, u_{II}) \mapsto (u_I, \frac{u_{II}}{a})$ and we use the following test function

$$A[u(x) - v] G^\sigma(x, y) \eta(x)$$

where $y \in B_R$, $\sigma < \frac{R}{2} - |y|$, $\eta \in C_c^\infty(B_{2R}, \mathbb{R})$, $\eta = 1$ on B_R and

$|\nabla \eta| \leq K_5 R^{-1}$. This gives :

$$\int_{B_{2R}} \{-\langle \nabla(u-v), \nabla A(u-v) \rangle G^\sigma \eta - \langle \nabla(u-v), \nabla \eta \rangle \cdot A(u-v) G^\sigma\}$$

$$- \langle \nabla(u-v), \nabla G^\sigma \rangle \cdot A(u-v) \eta + \lambda A(u) \cdot A(u-v) G^\sigma \eta \rangle dx = 0$$

$$\bullet (1.16) \quad - \int_{B_{2R}} \langle \nabla[(u-v) \cdot A(u-v) \eta], \nabla G^\sigma \rangle dx$$

$$+ \int_{B_{2R}} \langle \nabla \eta, \nabla G^\sigma \rangle (u-v) \cdot A(u-v) dx$$

$$- 2 \int_{B_{2R}} \langle \nabla(u-v), \nabla \eta \rangle \cdot A(u-v) G^\sigma dx$$

$$+ 2 \int_{B_{2R}} [\lambda A(u) \cdot A(u-v) - \langle \nabla u, \nabla[A(u)] \rangle] G^\sigma \eta dx = 0$$

. Since $\sigma < \frac{R}{2} - |y|$, the first integral is equal to

$$- \int_{B_0(y)} (u(z) - v) \cdot A[u(z) - v] dz.$$

. In the second integral we make the decomposition

$$(u-v) \cdot A(v-u) = (v-u_R) \cdot A(v-u_R)$$

$$+ [(u-v) \cdot A(u-v) - (v-u_R) \cdot A(v-u_R)]$$

$$\text{and } |(u-v) \cdot A(u-v) - (v-u_R) \cdot A(v-u_R)| \leq K_6 |u-v| |v-u_R|$$

$$\leq K_6 |u - u_R|.$$

hence

$$| \int_{B_{2R}} \langle \nabla \eta, \nabla G^\sigma \rangle [(u-v) \cdot A(u-v) - (v-u_R) \cdot A(v-u_R)] dx |$$

$$\leq K_6 \int_{T_{2R}} |\langle \nabla \eta, \nabla G^\sigma(x-y) \rangle| |u - u_R| dx$$

$$\leq K_5 K_6 2^{n-2} K_3 R^{-N} \int_{T_{2R}} |u - u_R| dx.$$

$$\leq K_3 K_4 K_5 K_6 2^{n-2} [R^{2-N} \int_{T_{2R}} |\nabla u|^2 dx]^{\frac{1}{2}}$$

$$\leq K_7 [\int_{B_{2R}} |\nabla u(x)|^2 R^{2-N} dx]^{\frac{1}{2}}$$

using (1.8) and (1.15). So the second integral is equal to

$$(v-u_R) \cdot A(v-u_R) + O([\int_{B_{2R}} |\nabla u(x)|^2 R^{2-N} dx]^{\frac{1}{2}}).$$

. In the third integral, we use the Cauchy-Schwarz inequality

$$|-2 \int_{B_{2R}} \langle \nabla(u-v), \nabla \eta \rangle \cdot A(u-v) G^\sigma dx|$$

$$\leq 4 \sqrt{\frac{1}{a^2} + 1} [\int_{T_{2R}} |\nabla u|^2 G^\sigma(x, y) dx]^{\frac{1}{2}} [\int_{T_{2R}} |\nabla \eta|^2 G^\sigma(x, y) dx]^{\frac{1}{2}}$$

$$\leq 4 \sqrt{\frac{1}{a^2} + 1} [\int_{T_{2R}} K_1 |\nabla u|^2 (\frac{R}{2})^{2-N} dx]^{\frac{1}{2}} 2^{N-2} (K_1)^{\frac{1}{2}} K_5 \text{mes}(T_2)$$

$$\leq K_8 [\int_{B_{2R}} |\nabla u|^2 R^{2-N} dx]^{\frac{1}{2}}.$$

. In the fourth integral, we remark that $\lambda = \frac{\langle \nabla u, \nabla[A(u)] \rangle}{|A(u)|^2}$,

so $\lambda A(u) \cdot A(u-v) = \langle \nabla u, \nabla[A(u)] \rangle = -A(u) \cdot A(v) \lambda$.

Hence (1.16) becomes

$$(1.17) \int_{B_\sigma(y)} (u(z)-v) \cdot A(u(z)-v) dz \leq (v-u_R) \cdot A(v-u_R) +$$

$$K_9 [\int_{B_{2R}} |\nabla u|^2 R^{2-N} dx]^{\frac{1}{2}} - 2 \int_{B_{2R}} \lambda A(u) \cdot A(v) G^\sigma dx.$$

Now, let $\sigma \rightarrow 0$ and use $\lambda \leq \frac{|\nabla u(x)|^2}{a^2}$, (1.9), (1.14) and

Lebesgue's theorem. We find for a.e. $y \in B_{\frac{R}{2}}$

$$(1.18) (u(y)-v) \cdot A(u(y)-v) \leq (v-u_R) \cdot A(v-u_R) +$$

$$+ K_9 [\int_{B_{2R}} |\nabla u|^2 R^{2-N} dx]^{\frac{1}{2}} - 2 \int_{B_{2R}} \lambda A(u) \cdot A(v) G(x, y) \eta(x) dx.$$

Now, we take $\rho < \frac{R}{2}$ and $y \in B_\rho$, and we write

$$\int_{B_{2R}} \lambda A(u) \cdot A(v) G(x, y) \eta(x) dx$$

$$\geq - \int_{B_{2R} \setminus B_{2\rho}} a^2 |\nabla u|^2 G(x, y) \eta(x) dx + \inf_{B_{2\rho}} [A(u) \cdot A(v)] \int_{B_{2\rho}} a^2 |\nabla u|^2 G(x, y) \eta(x) dx.$$

And since $2(x-y) \gg |x-y| + \rho \gg (x-y) + (y) \gg (x)$, and from (1.6),

$$|\int_{B_{2R} \setminus B_{2\rho}} a^2 |\nabla u|^2 G(x, y) \eta(x) dx| \leq K_{10} \int_{B_{2R} \setminus B_{2\rho}} |\nabla u|^2 |x|^{2-N} dx \leq K_{10} \int_{B_{2R}} |\nabla u|^2 |x|^{2-N} dx.$$

So (1.18) becomes

$$(1.19) (u(y)-v) \cdot A(u(y)-v) \leq (v-u_R) \cdot A(v-u_R) +$$

$$+ K_{11} [\int_{B_{2R}} |\nabla u|^2 R^{2-N} dx]^{\frac{1}{2}}$$

$$- 2 \inf_{B_{2\rho}} [A(u) \cdot A(v)] \int_{B_{2\rho}} a^2 |\nabla u|^2 G(x, y) \eta(x) dx.$$

Now, we define $h : [0, 1] \rightarrow \mathbb{R} +$ by

$$h(t) = \limsup_{R \rightarrow 0} [\limsup_{\rho \rightarrow 0} \sup_{B_\rho} (u(y)-v) \cdot A[u(y)-v]].$$

Let us remember that $v = u_{R,t}$. It is standard that h is continuous.

Furthermore, $h(0) \leq 2(1 - \frac{\alpha_0}{a})$. In fact we have for every t in $[0,1]$, $h(t) \leq 2(1 - \frac{\alpha_0}{a})$. Let us suppose that it is false, then, there exists t_0 in $]0,1[$ such that $h(t_0) = 2(1 - \frac{\alpha_0}{a}) + \epsilon$ for ϵ sufficiently small, such that $2(1 - \frac{\alpha_0}{a}) + \epsilon < 2$.

It follows that for small enough R and $\rho < \rho_0(R)$, we have :

for a.e. $y \in B_{2\rho}$, $(u(y) - u_{R,t_0}) \cdot A(u(y) - u_{R,t_0}) < 2$.

or for a.e. $y \in B_{2\rho}$, $A(u(y)) \cdot u_{R,t_0} > 0$

which implies that for a.e. $y \in B_{2\rho}$, $A(u(y)) \cdot A(u_{R,t_0}) > 0$.

Now, we use (1.19), and find for a.e. $y \in B_2$,

$$(u(y) - u_{R,t_0}) \cdot A(u(y) - u_{R,t_0}) \leq (u_{R,t_0} - u_R) \cdot A(u_{R,t_0} - u_R) + K_{11} \left[\int_{B_{2R}} |\nabla u|^2 |x|^{N-2} dx \right]^{\frac{1}{2}}.$$

And this implies

$$h(t_0) \leq (u_{R,t_0} - u_R) \cdot A(u_{R,t_0} - u_R) \leq 2(1 - \frac{\alpha_0}{a})$$

which gives us a contradiction with $h(t_0) = 2(1 - \frac{\alpha_0}{a}) + \epsilon$.

Hence we conclude that $\forall t \in [0,1]$, $h(t) \leq 2$, and so for small enough R and $\rho < \rho_0(R)$, we have $A(u(y)) \cdot A(u_{R,t}) \geq 0$,

for a.e. $y \in B_{2R}$. We apply this in (1.19) with $t=1$, this gives

$$(u(y) - u_R) \cdot A(u(y) - u_R) \leq K_{11} \left[\int_{B_{2R}} |\nabla u|^2 |x|^{2-N} dx \right]^{\frac{1}{2}} \\ \Rightarrow (1.20) \quad |u(y) - u_R|^2 \leq K_{12} \left[\int_{B_{2R}} |\nabla u|^2 |x|^{2-N} dx \right]^{\frac{1}{2}},$$

for almost everywhere y sufficiently small, and R sufficiently small. And using (1.14) the continuity of u

on y is proved.

II. UNIQUENESS.

We want to solve the following Dirichlet problem : Let φ be a function of $H^1(\Omega, N)$ whose values on $\partial\Omega$ lies on a compact subset of N_+ , let us find a harmonic map u which agrees with φ on $\partial\Omega$ and whose values are in N_+ . The existence is standard by finding a minimizing map. We will show that this solution is unique using theorem 1 and the following result :

Theorem 2. If $u^1, u^2 \in C^\infty(\Omega, N_+) \cap H^1(\Omega, N_+)$ are harmonic, and if $u^1(\partial\Omega)$ and $u^2(\partial\Omega)$ belong to a compact subset of N_+ , then the function :

$$\theta = \frac{1}{2} \frac{|u^1 - u^2|^2}{u_{II}^1 u_{II}^2} \text{ checks the maximum principle :}$$

Proof. For $r = 1, 2$, since $u^i(\partial\Omega)$ is contained in a compact subset of N_+ , there exists $\alpha_0 > 0$ with $u_{II}^i(x) > \alpha$ if $x \in \partial\Omega$.

Using (0.1) (b), we have

$$-\Delta u_{II}^i(x) = \lambda^i \frac{u_{II}^i(x)}{a^2} > 0.$$

And so by the maximum principle

$$(2.1) \quad u_{II}^i(x) > \alpha \text{ on } \Omega.$$

The function $\phi = -\log(u_{II}^1) - \log(u_{II}^2)$ is smooth and bounded on Ω . We will construct the elliptic operator \mathcal{L} with ϕ by : $\forall f \in H^1(\Omega, \mathbb{R})$, $\mathcal{L}(f) = \operatorname{div}[e^{-\phi} \operatorname{grad} f]$.

We will show that $f(\theta) \geq 0$, which assures the result.

Noting $\psi = \frac{1}{2}|u^1 - u^2|^2$ so that $\theta = e^\psi$ and :

$f(\theta) = \Delta\psi + \psi\Delta\psi + \langle \nabla\psi, \nabla\psi \rangle$, we have

$$\nabla\psi = -\frac{\nabla u_{II}^1}{u_{II}^1} - \frac{\nabla u_{II}^2}{u_{II}^2}$$

$$\Delta\psi = -\frac{\Delta u_{II}^1}{u_{II}^1} - \frac{\Delta u_{II}^2}{u_{II}^2} + \left| \frac{\nabla u_{II}^1}{u_{II}^1} \right|^2 + \left| \frac{\nabla u_{II}^2}{u_{II}^2} \right|^2.$$

Hence

$$(2.1) f(\theta) = \Delta\psi + \psi \left[-\frac{\Delta u_{II}^1}{u_{II}^1} - \frac{\Delta u_{II}^2}{u_{II}^2} + \left| \frac{\nabla u_{II}^1}{u_{II}^1} \right|^2 + \left| \frac{\nabla u_{II}^2}{u_{II}^2} \right|^2 \right]$$

$$- \left\langle \frac{\nabla u_{II}^1}{u_{II}^1} + \frac{\nabla u_{II}^2}{u_{II}^2}, \nabla\psi \right\rangle.$$

Using Young's inequality

$$- \left\langle \frac{\nabla u_{II}^i}{u_{II}^i}, \nabla\psi \right\rangle \geq - \psi \left| \frac{\nabla u_{II}^i}{u_{II}^i} \right|^2 - \frac{|\nabla\psi|^2}{\psi}, \quad i = 1, 2.$$

We obtain :

$$(3.2) f(\theta) \geq \Delta\psi - \frac{|\nabla\psi|^2}{2\psi} - \psi \left[\frac{\Delta u_{II}^1}{u_{II}^1} + \frac{\Delta u_{II}^2}{u_{II}^2} \right],$$

and by the Cauchy-Schwarz's inequality

$$\frac{|\nabla\psi|^2}{2\psi} = \frac{\langle (u^1 - u^2), \nabla(u^1 - u^2) \rangle \cdot \langle (u^1 - u^2), \nabla(u^1 - u^2) \rangle}{(u^1 - u^2) \cdot (u^1 - u^2)} \leq |\nabla(u^1 - u^2)|^2.$$

Inequality (3.2) gives

$$(3.3) f(\theta) \geq \Delta\psi - \psi \left[\frac{\Delta u_{II}^1}{u_{II}^1} + \frac{\Delta u_{II}^2}{u_{II}^2} \right] - |\nabla(u^1 - u^2)|^2.$$

Now, $\Delta\psi = |\nabla(u^1 - u^2)|^2 + (u^1 - u^2) \cdot \Delta(u^1 - u^2)$ implies using (0.1)

$$\Delta\psi = |\nabla(u^1 - u^2)|^2 - (u^1 - u^2) \cdot [\lambda_1 A(u^1) - \lambda_2 A(u^2)]$$

$$= |\nabla(u^1 - u^2)|^2 - (\lambda_1 + \lambda_2) [1 - u^1 \cdot A(u^2)].$$

$$\text{Furthermore, } \frac{-\Delta u_{II}^1}{u_{II}^1} = \frac{\lambda_1}{a^2}, \quad \frac{-\Delta u_{II}^2}{u_{II}^2} = \frac{\lambda_2}{a^2}.$$

$$\text{So, } f(\theta) \geq |\nabla(u^1 - u^2)|^2 - (\lambda_1 + \lambda_2) [1 - u^1 \cdot A(u^2)] +$$

$$+ \frac{|u^1 - u^2|^2}{2} \frac{\lambda_1 + \lambda_2}{a^2} - |\nabla(u^1 - u^2)|^2$$

$$\text{or } f(\theta) \geq \frac{\lambda_1 + \lambda_2}{a^2} \left[\frac{|u^1 - u^2|^2}{2} - a^2 + a^2 u^1 \cdot A(u^2) \right]$$

$$\text{or } f(\theta) \geq \frac{\lambda_1 + \lambda_2}{2a^2} (1 - a^2) |u^1 - u^2|^2 > 0.$$

This terminates the proof.

III. THE PROBLEM WITH THE EQUATOR MAP.

Now we choose $n = N \geq 3$, $B^n = \{x \in \mathbb{R}^n / |x| < 1\}$.

$u_*(x) = \frac{x}{|x|}$. We show the following result.

Theorem 3. u_* is the unique minimizing map if and only if $a^2 > \frac{4(n-1)}{(n-2)^2}$. If $a^2 < \frac{4(n-1)}{(n-2)^2}$, there is a smooth and

radially symmetric minimizing map.

Proof. We will only prove that u_* is minimizing when

$a^2 > \frac{4(n-1)}{(n-2)^2}$. Unicity is then a consequence of theorem 5 of A. Baldes in [B].

We begin to look for the solution of the following Dirichlet problem: let be $r \in (0,1)$ and u_r a map of $H^1(B^n, N_+)$ which verifies: $\forall x \in \partial B^n$, $u_r(x) = (x \sin(\tau \frac{\pi}{2}), a \cos(\tau \frac{\pi}{2}))$, and which minimizes the energy functionnal among the functions of $H^1(B^n, N_+)$ which agree with u_r on ∂B^n .

It follows from theorems 1 and 2 that u_r will be smooth harmonic and unique. Because of the uniqueness of u_r and because of the symmetry of the problem, u_r must be rotationally symmetric, i.e.

$$\begin{cases} u_r(x) = (\frac{x}{r} \sin \theta_r(r), a \cos \theta_r(r)), & \text{where } r = |x|. \\ \theta_r \in C^\infty([0,1], [0, \frac{\pi}{2}]) \\ \theta_r(0) = 0, \theta_r(1) = \tau \frac{\pi}{2}. \end{cases}$$

Let us calculate the equation verified by u_r :

$$E(u_r) = |S^{n-1}| \int_0^1 [(\theta_r')^2 (\cos^2 \theta_r + a^2 \sin^2 \theta_r) + \frac{n-1}{r^2} \sin^2 \theta_r] r^{n-1} dr$$

Let us introduce the diffeomorphism $\ell \in C^\infty([0, \frac{\pi}{2}], [0, \sigma])$ with

$$\begin{cases} \forall \theta \in [0, \frac{\pi}{2}] , \ell(\theta) = \int_s^\theta \sqrt{\cos^2 q + a^2 \sin^2 q} dq \\ \sigma = \int_s^{\frac{\pi}{2}} \sqrt{\cos^2 q + a^2 \sin^2 q} dq. \end{cases}$$

$\ell(\theta)$ is the arc-length of the arc $[0, \theta] \rightarrow \mathbb{R}^2$, $q \mapsto (\sin q, a \cos q)$.

Let us note $S \in C^\infty([0, \sigma], [0, 1])$ defined by

$$\forall \theta \in [0, \frac{\pi}{2}] , S[\ell(\theta)] = \sin \theta.$$

(Note that if $a = 1$, S is the sinus function).

We make the change of variables $\lambda_r(t) = \ell[\theta_r(e^t)]$

$$E(u_r) = |S^{n-1}| \int_{-\infty}^0 [(\dot{\lambda}_r)^2 + (n-1)S(\lambda_r)^2] e^{(n-2)t} dt.$$

Hence, we obtain the equation which express that u_r is harmonic

$$(3.1) \quad \ddot{\lambda}_r + (n-2)\dot{\lambda}_r - (n-1)S(\lambda_r)S'(\lambda_r) = 0$$

with the boundary conditions $\lambda_r(-\infty) = 0$, $\lambda_r(0) = \ell(\frac{\pi}{2})$.

Now, let us introduce the cycloid

$$\begin{cases} z = \frac{-(1+a)}{4} \cos 2\theta \\ y = \frac{(1-a)}{2} \theta + \frac{(1+a)}{2} \sin 2\theta \end{cases} \quad \theta \in (0, +\infty).$$

$$\begin{cases} \frac{dz}{d\theta} = \frac{1+a}{2} \sin 2\theta \\ \frac{dy}{d\theta} = \frac{1-a}{2} + \frac{1+a}{2} \cos 2\theta. \end{cases}$$

The sinus of the slope of the cycloid with the direction z is

$$p = \frac{\frac{dz}{d\theta}}{\sqrt{\left(\frac{dz}{d\theta}\right)^2 + \left(\frac{dy}{d\theta}\right)^2}}$$

$$\frac{\frac{(1+a)}{2} \sin 2\theta}{\sqrt{\left[\frac{(1+a)\sin 2\theta}{2}\right]^2 + \left[\frac{(1-a)}{2}\right]^2 + \left[\frac{(1+a)\cos 2\theta}{2}\right]^2 + \frac{1-a^2}{2} \cos 2\theta}}$$

$$p = \frac{(1+a)\sin\theta\cos\theta}{\sqrt{\cos^2\theta + a^2\sin^2\theta}}$$

And $S(\ell(\theta)) = \sin\theta$ implies

$$S'[\ell(\theta)]\ell'(\theta) = S'[\ell(\theta)]\sqrt{\cos^2\theta + a^2\sin^2\theta} = \cos\theta.$$

$$\text{So } S[\ell(\theta)] S'[\ell(\theta)] = \frac{\sin\theta\cos\theta}{\sqrt{\cos^2\theta + a^2\sin^2\theta}} = \frac{p}{1+a}.$$

The curvilinear arc-length on the cycloid is

$$\int_0^\theta \sqrt{\cos^2 q + a^2 \sin^2 q} dq = \ell(\theta).$$

Now take $\beta \in \mathbb{R}$, and consider the movement of a point M on the cycloid whose curvilinear absciss is defined by

$$s(t) = \ell[\theta_\tau(t-\beta)] = \lambda_\tau(t-\beta).$$

Equation (3.1) becomes

$$(3.2) \quad \ddot{s} + (n-2)\dot{s} - \frac{(n-1)p}{1+a} = 0,$$

with the boundary conditions $s(-\infty) = 0$, $s(\beta) = \ell(\tau\frac{\pi}{2})$.

This equation is the equation of the damped movement

of a point which is forced to slide along the cycloid and which is subjected to a constant acceleration field

$$\frac{(n-1)}{1+a} p \frac{\partial}{\partial z}.$$

The problem is : does this point reach the arc-length σ in a finite time ? To see this, we linearize (3.2) in a neighbourhood of $s = \sigma$ (or $\theta = \frac{\pi}{2}$), this gives

$$(3.3) \quad \ddot{(s-\sigma)} + (n-2) \dot{(s-\sigma)} + \frac{n-1}{a} (s-\sigma) = 0.$$

The characteristic equation is then

$$\mu^2 + (n-2)\mu + \frac{n-1}{a} = 0,$$

$$\text{with discriminant } \Delta = \frac{(n-2)^2}{a^2} [a^2 - \frac{4(n-1)}{(n-2)^2}].$$

. If $\Delta < 0 \Leftrightarrow a^2 < \frac{4(n-1)}{(n-2)^2}$, we have small oscillations. So there exists $t_1 \in \mathbb{R}$ with $s(t_1) = \sigma$ and

$$\begin{cases} \forall t \in (-\infty, t_1), s(t) \in (0, \sigma). \\ \forall \tau \in (0, 1), \exists ! t_\tau \in (-\infty, t_1), s(t_\tau) = \ell(\tau\frac{\pi}{2}) \end{cases}$$

By a translation on t , we suppose that $s(0) = \sigma$. Taking $\beta = t_\tau$ i.e. $\lambda_\tau(t) = s(t+t_\tau)$, we find that λ_τ satisfies (3.1) with good boundary conditions for every $\tau \in (0, 1]$.

Equivalently : $\theta_\tau(r) = \ell^{-1}[\lambda_\tau[\text{Log}(e^{\frac{t}{\tau}} r)]]$, so that $\forall \tau \in (0, 1], \theta_\tau(r) = \theta_1(e^{\frac{t}{\tau}} r)$.

. If $\Delta > 0 \Leftrightarrow a^2 > \frac{4(n-1)}{(n-2)^2}$, the roots are real and non

positive, the point M will never reach the absciss σ .

Indeed, let us suppose the contrary. Then there exists a real \bar{t} such that

$$\begin{cases} \forall t \in (-\infty, \bar{t}), s(t) \in (0, \sigma), \dot{s}(t) > 0 \\ s(\bar{t}) = \sigma. \end{cases}$$

Let μ be a root of the characteristic equation of (3.3), μ is strictly negative, we pose

$$\forall t \in (-\infty, \bar{t}), x(t) = \mu(\sigma - s(t)) + \dot{s}(t).$$

Then we have

$$\begin{aligned} \dot{x} &= \ddot{s} - \mu \dot{s} = -[(n-2) + \mu] \dot{s} + \frac{n-1}{1+a} p(s). \\ \dot{x} &= \frac{n-1}{2} \left[\dot{s} + \frac{a^2}{1+a} \mu p(s) \right] \\ \dot{x} &= \frac{n-1}{2} x + (n-1) \left[\frac{\sin \theta \cos \theta}{\sqrt{\cos^2 \theta + a^2 \sin^2 \theta}} - \int_0^{\frac{\pi}{2}} \frac{\sqrt{\cos^2 q + a^2 \sin^2 q}}{a^2} dq \right]. \end{aligned}$$

And it follows that $\dot{x} < \frac{n-1}{2} x$ because if

$$H(\theta) = \frac{\sin \theta \cos \theta}{\sqrt{\cos^2 \theta + a^2 \sin^2 \theta}} - \int_0^{\frac{\pi}{2}} \frac{\sqrt{\cos^2 q + a^2 \sin^2 q}}{a^2} dq$$

H is negative on $[0, \frac{\pi}{2}]$ since $H(\frac{\pi}{2}) = 0$ and

$$H'(\theta) = \frac{[(a^2+1)\cos^2 \theta + 2a^2 \sin^2 \theta]}{(\cos^2 \theta + a^2 \sin^2 \theta)^{3/2}} > 0.$$

Then since $\lim_{t \rightarrow \infty} x(t)$ is strictly negative, we obtain that $x(\bar{t})$ is

strictly negative, which is impossible because

$$x(\bar{t}) = \mu(\sigma - s(\bar{t})) + \dot{s}(\bar{t}) = \dot{s}(\bar{t}) > 0.$$

Hence we conclude

$$\begin{cases} \forall t \in \mathbb{R}, \lambda(t) \in (0, \sigma), \\ \lim_{t \rightarrow +\infty} \lambda(t) = \frac{II}{2} \\ \forall t \in (0, 1), \exists! \tau_t \in \mathbb{R}, s(\tau_t) = \lambda(\tau_t \frac{II}{2}) \end{cases}$$

By a translation on t , we suppose that $s(0) = \lambda(\frac{II}{4})$.

Hence we will only obtain λ_t for $t \in (0, 1)$ by taking

$\beta = \tau_t - \frac{t}{2}$ i.e. $\lambda_t(t) = s(t + \tau_t - \frac{t}{2})$, or equivalently

tely

$$\theta_t(r) = \lambda^{-1} [\lambda_t \text{Log}(e^{\frac{t - \tau_t}{2} r})].$$

Conclusion. Let v be in $H^1(B^n, \bar{N}_+)$ which verifies

$v|_{\partial B^n} = u_*|_{\partial B^n}$. It is easy to find a sequence τ_k and a

sequence v_k which verifies

$$\begin{cases} \tau_k \in (0, 1), \tau_k \rightarrow 1 \\ \forall x \in \partial B^n, v_k(x) = (x \sin(\tau_k \frac{II}{2}), a \cos(\tau_k \frac{II}{2})) \\ v_k \rightarrow v \text{ in } H^1(B^n, \mathbb{R}^{n+1}) \end{cases}$$

Using the following result, we have

$$(3.5) \quad E(u_{\tau_k}) \leq E(v_k)$$

We now pass to the limit :

. If $a^2 < \frac{4(n-1)}{(n-2)^2}$, obviously, $u_{\tau_k} \rightarrow u_1$ in $H^1(B^n, \mathbb{R}^{n+1})$ where

$$u_1(x) = (\frac{x}{r} \sin \theta_1(r), a \cos \theta_1(r)).$$

So $E(u_1) < E(v)$ and u_1 is a smooth and radially symmetric minimizing map.

. If $a^2 > \frac{4(n-1)}{(n-2)^2}$, obviously $u_{T_k} \rightarrow u_+ \in H^1(B^n, \mathbb{R}^{n+1})$, and by

lower semicontinuity : $E(u_+) \leq E(v)$.

And it is not difficult to see that these functions are minimizing in $H^1(B^n, N)$ instead of $H^1(B^n, \bar{N}_+)$, because for every map $u \in H^1(B^n, N)$, if $u_+ = (u_I, |u_{II}|)$, then $E(u_+) = E(u)$, and $u_+ \in H^1(B^n, \bar{N}_+)$.

This completes the proof of theorem 3.

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