



INTERNATIONAL ATOMIC ENERGY AGENCY  
UNITED NATIONS EDUCATIONAL, SCIENTIFIC AND CULTURAL ORGANIZATION



INTERNATIONAL CENTRE FOR THEORETICAL PHYSICS  
34100 TRIESTE (ITALY) - P.O.B. 500 - MIRAMARE - STRADA COSTIERA 11 - TELEPHONE: 2260-1  
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SECOND SCHOOL ON ADVANCED TECHNIQUES  
IN COMPUTATIONAL PHYSICS  
(18 January - 12 February 1988)

SMR.282/31

ACCELERATOR PHYSICS

A.Wrulich  
Area di Ricerca Sincrotrone, Trieste, Italy

# COMPUTING IN ACCELERATOR PHYSICS

A. Wielich  
SINCRONTE TRIESTE

COMPUTING →

Accelerator Design

Accelerator Operation

## 1. Lesson:

Accelerators, an introduction

Basic equations for transverse motion

Computation of linear optics

Basic equations for longitudinal motion

Nonlinear transverse motion

Resonance effects in circular accelerators

Simulation of particle motion, tracking

## 3. Lesson:

Chaotic trajectories of transverse motion

Collective effects

Beam-beam effect

Beam-environment interaction

Numerical field calculations

## ACCELERATORS (introduction)

used for  $\rightarrow$

Elementary particle physics,  
colliders

Light sources

Health service

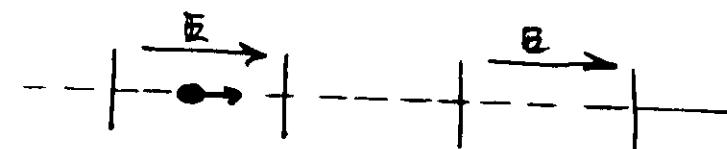
Industry (compact sources)

### types of accelerators $\rightarrow$

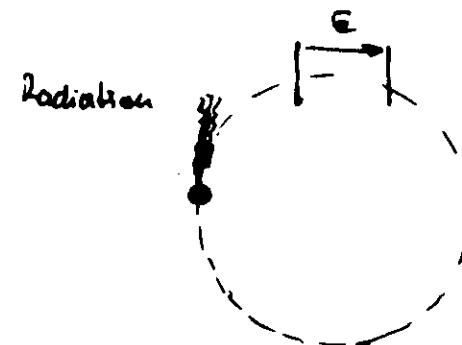
Linear

Circular (synchrotron, storage ring,  
cyclotron, microtron, --)

### Linear accelerator:



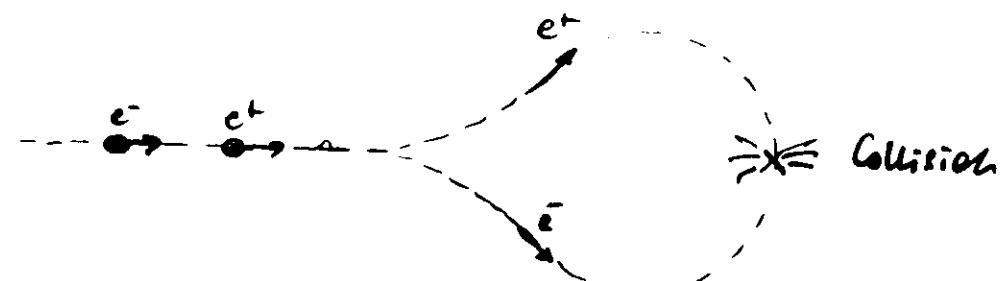
### Circular Accelerator:



Storage rings  
Synchrotrons

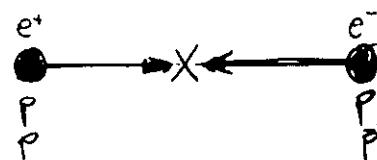
Radiation: ( $e^+e^-$ )  
Synchrotron Radiation  
Beam-beam effect  
(p) Large bending  
fields

### SLC (Stanford):

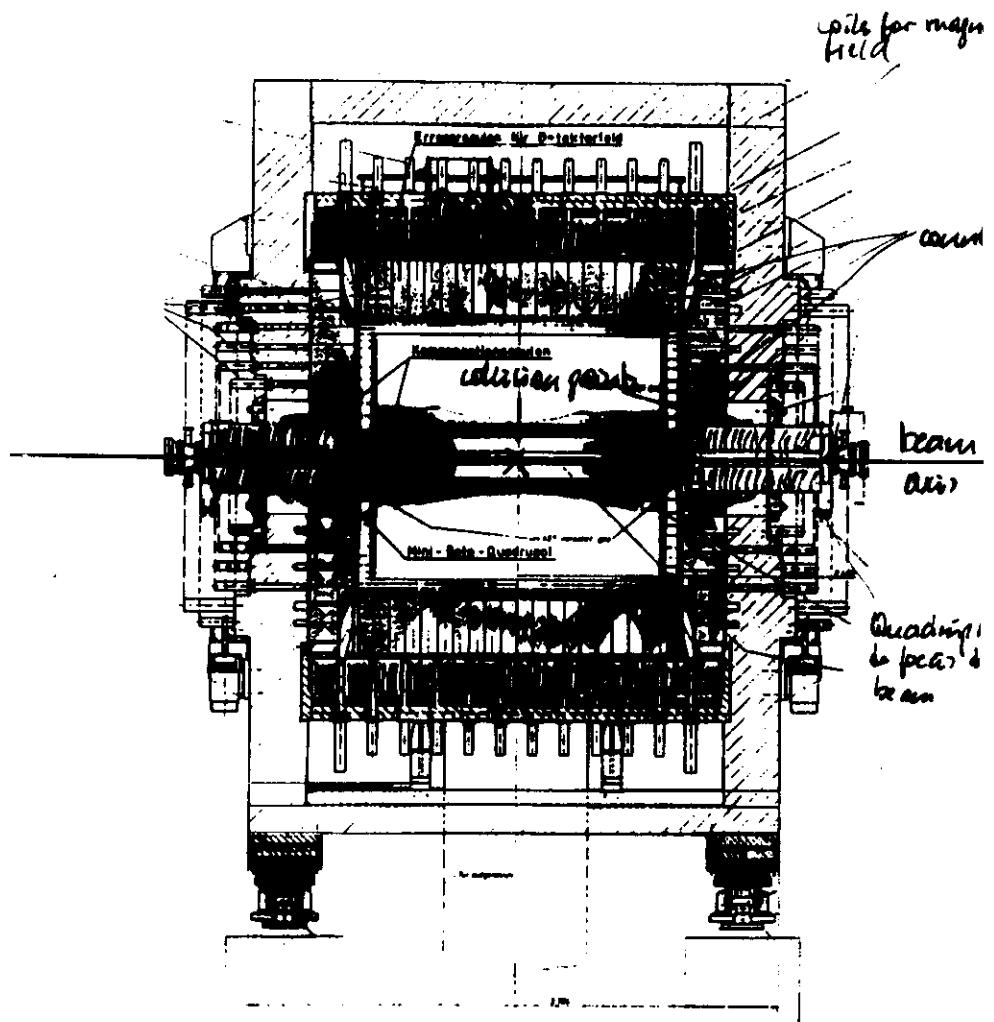


## Accelerators for High Energy Physics

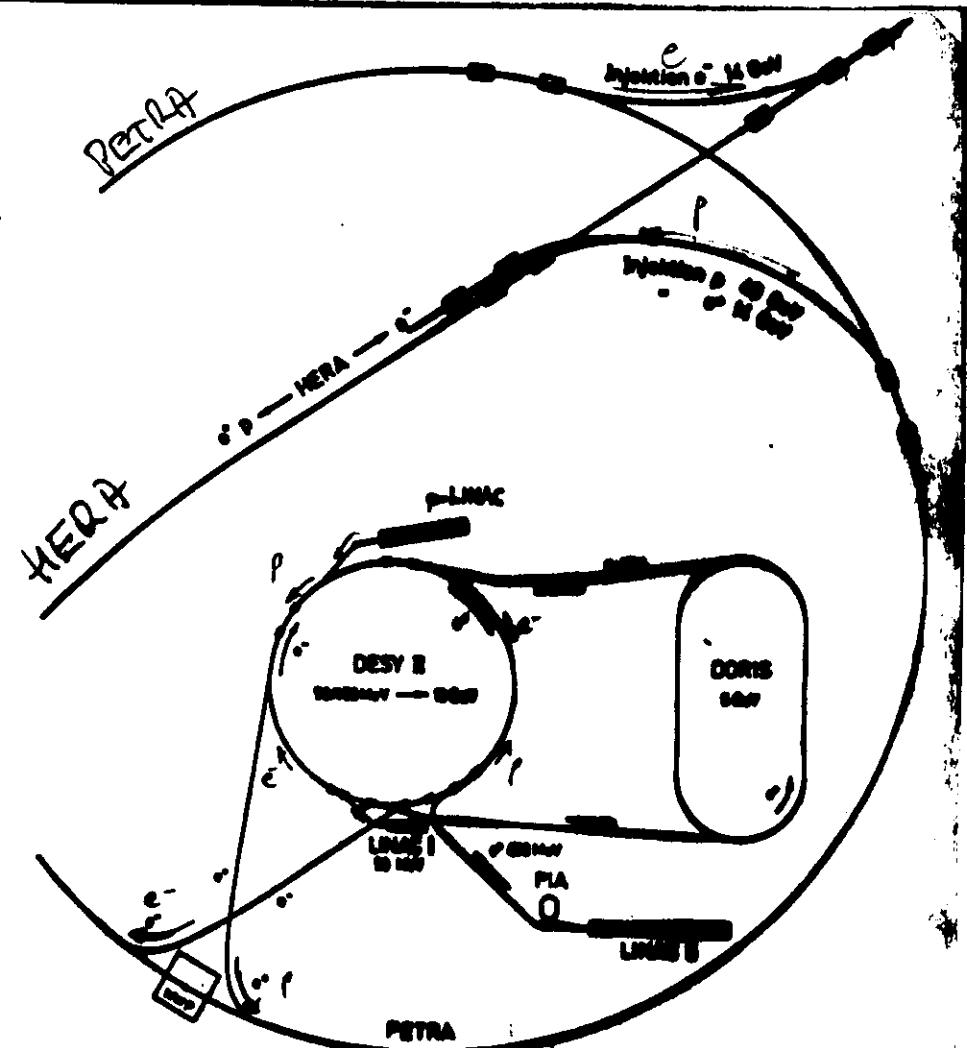
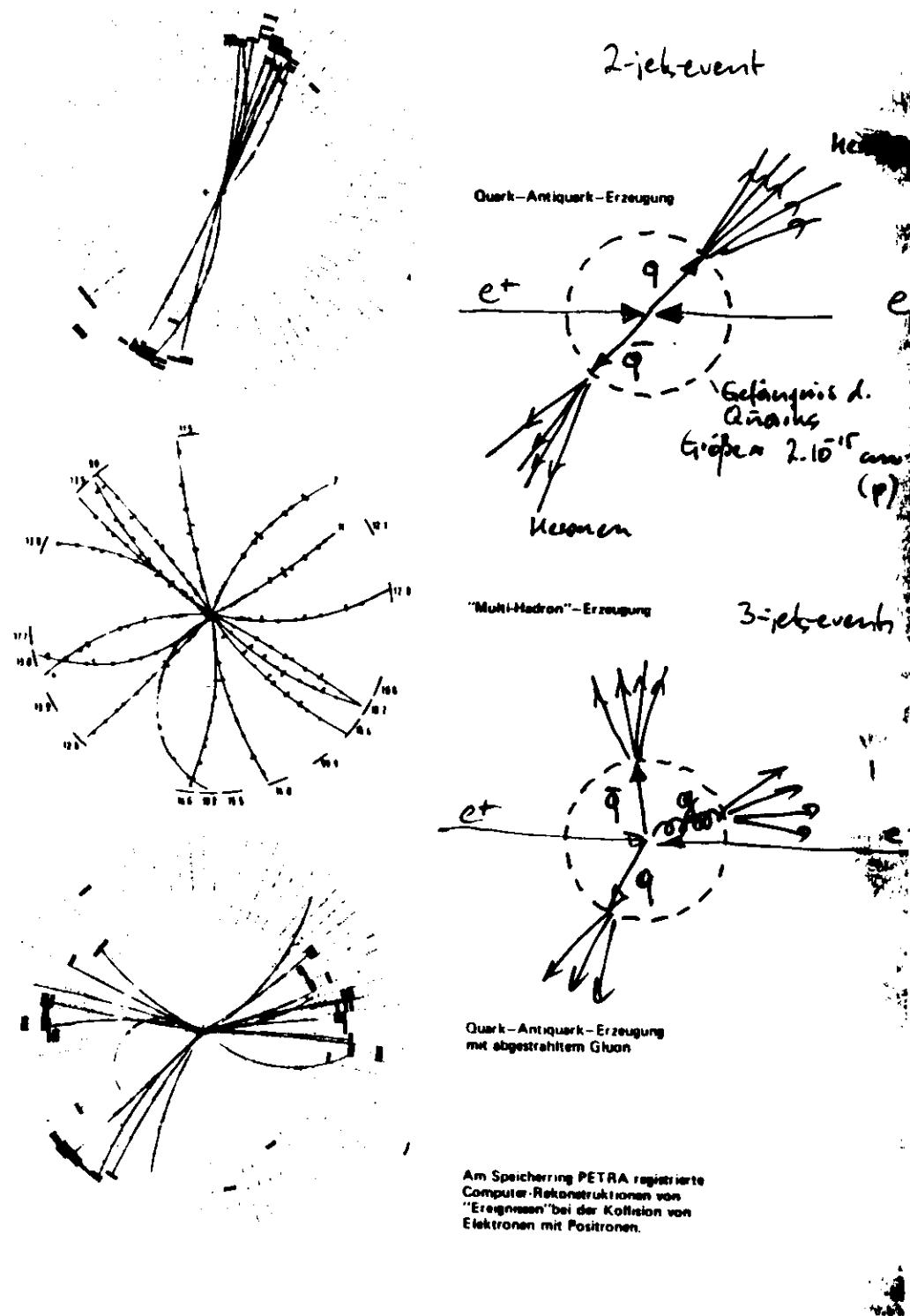
Energy of colliding particles



is used to create showers of new particles. Their traces are detected by large apparatuses (DETECTORS) and evaluated by computers.

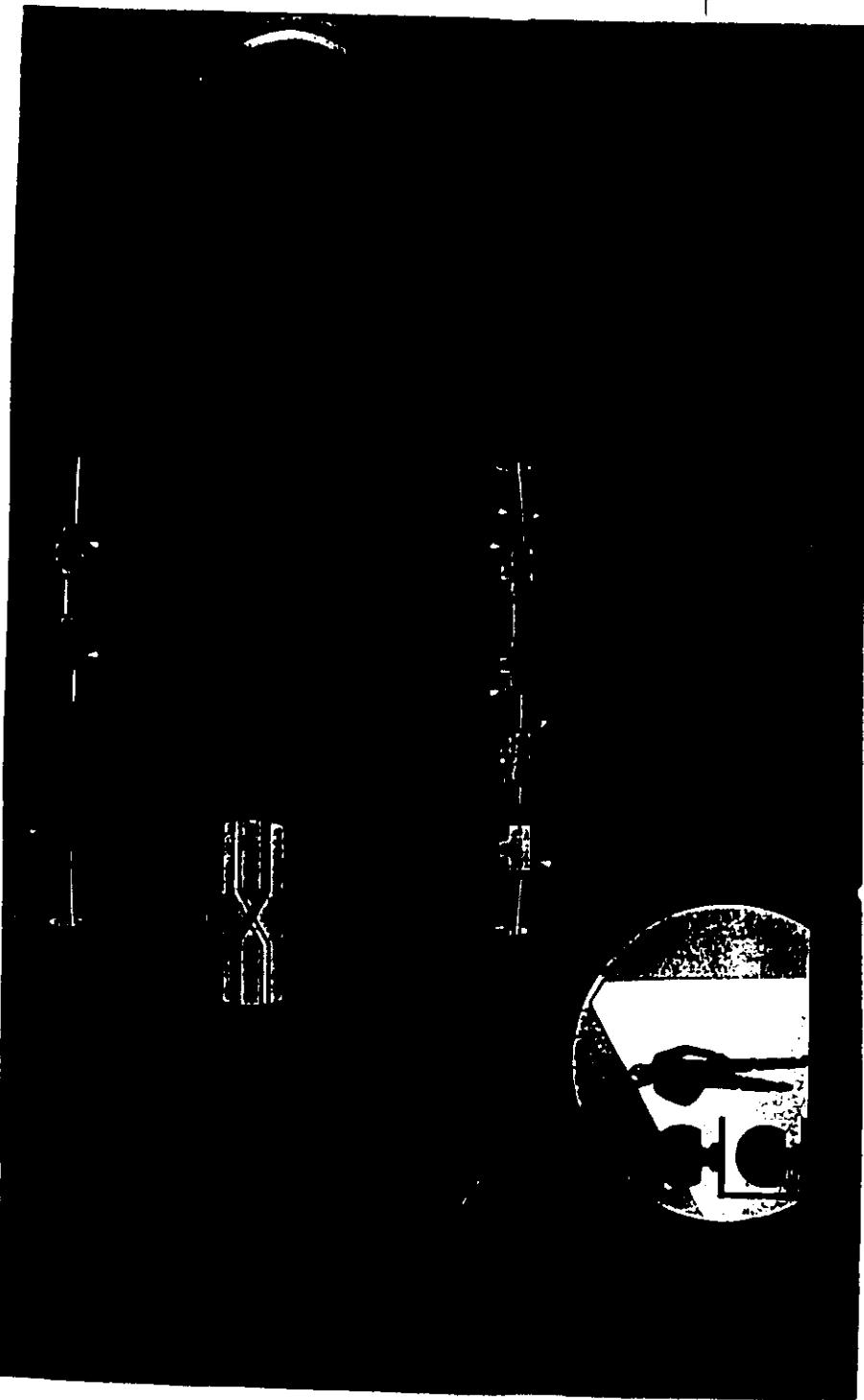


AEGIS at DORIS II (DESY)

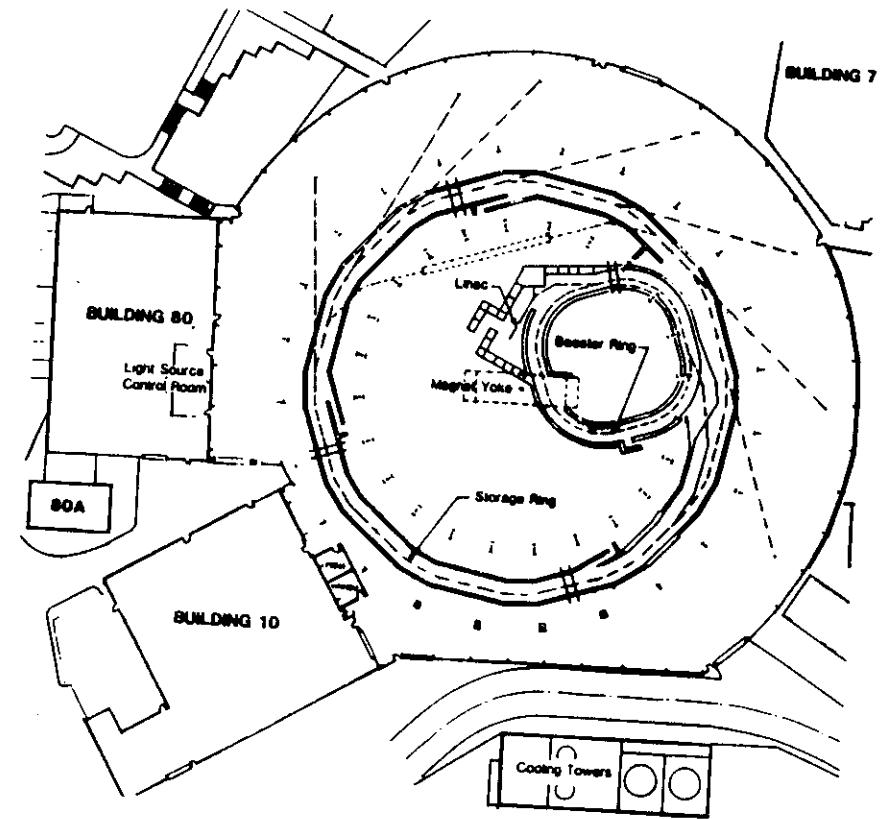


DESY - accelerators

Am Speicherring PETRA registrierte  
 Computer-Rekonstruktionen von  
 "Ergebnissen" bei der Kollision von  
 Elektronen mit Positronen.



Radiation Sources:

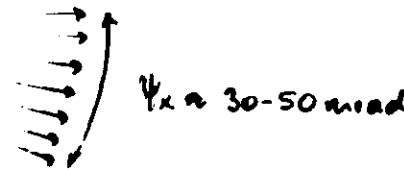
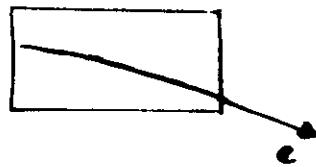


Berkeley 1.5 GeV Light Source

## RADIATION

Basic principle: Radiation is emitted by relativistic charged particles circulating in a magnetic field.

## I. BENDING MAGNETS:



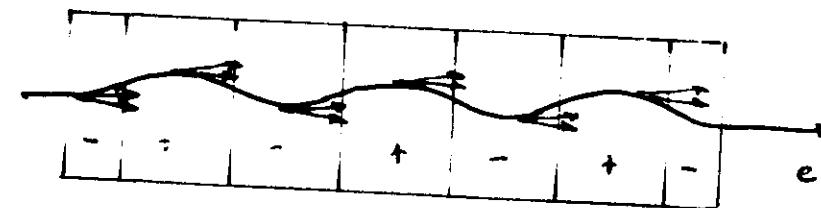
SR is emitted with →

$$\text{Horizontal divergence: } \Phi_x \approx 30 - 50 \text{ mrad}$$

$$\text{Vertical divergence: } \Phi_z = \pm \frac{1330}{g} \left( \frac{\lambda}{\lambda_0} \right)^{0.43} \approx \pm \frac{1}{g}$$

$$E = 2 \text{ GeV} (\gamma = 4000) \Rightarrow \Phi_x = \pm 0.33 \text{ mrad}$$

## II. WIGGLER



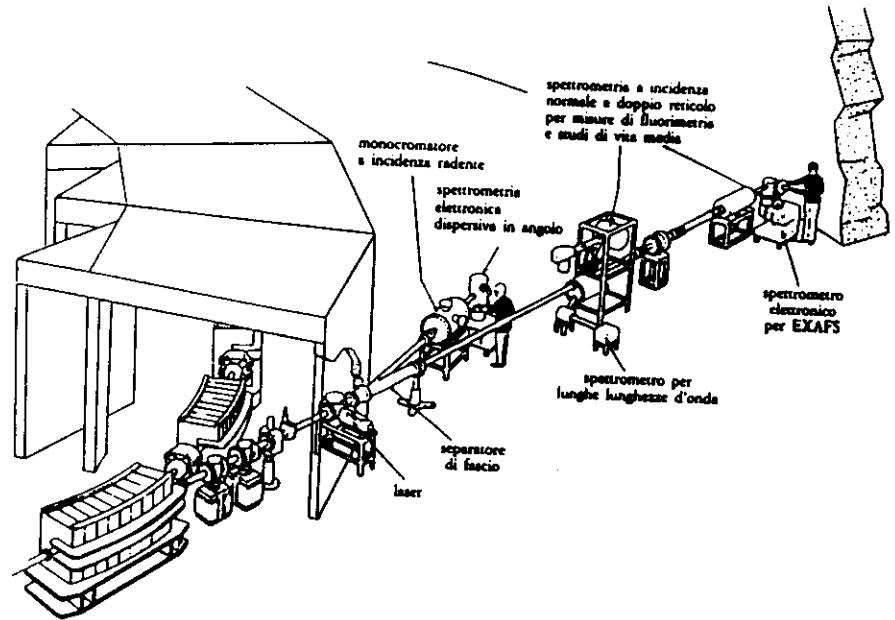
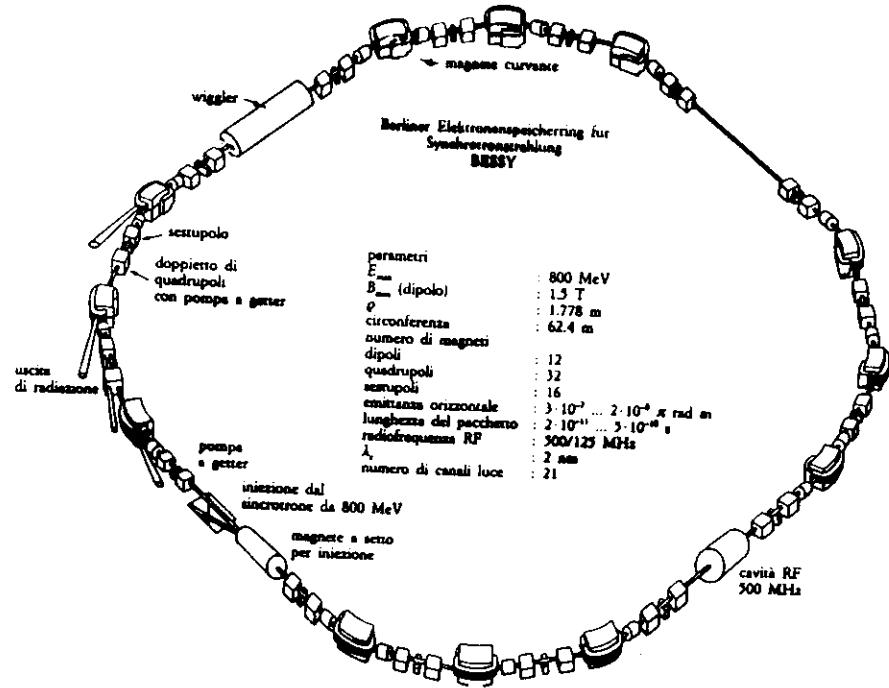
$$\epsilon_c [\text{keV}] = 0.665 \cdot E^2 [\text{Gev}] \cdot B [\text{T}]$$

↑  
can be chosen independent  
of storage ring energy

FLUX is increased due to superposition

inductance T Henry:

$$\left. \begin{array}{l} E = 2 \text{ GeV} \\ B = 1.2 \text{ T} \end{array} \right\} \rightarrow \epsilon_c = 3.2 \text{ keV}$$



Beam line of radiation source

BESSY - Radiation Source

## EQUATIONS OF MOTION

Principle: Charged particles moving in a (constant) magnetic field are bend on a circular orbit

LORENTZ FORCE  $\rightarrow$

$$\vec{F} = e [\vec{v} \times \vec{B}]$$

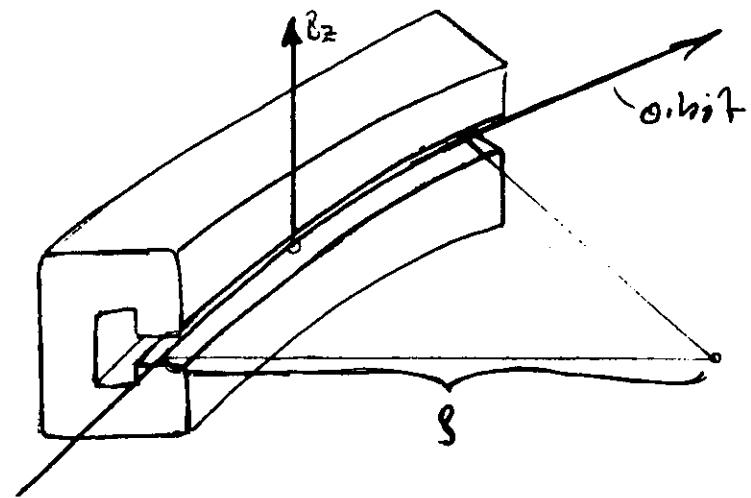
Basic magnetic elements of an accelerator  $\rightarrow$

## BENDING MAGNETS

Quadrupoles

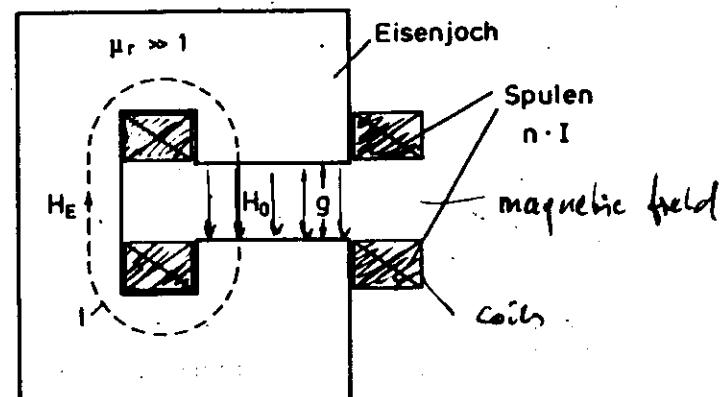
Sextupoles

## BENDING MAGNET $\rightarrow$ Guiding Field



$$\vec{v} \perp \vec{B}: F = e [\vec{v} \times \vec{B}] = \frac{mv^2}{r} \Rightarrow$$

$$\frac{e}{m} B_z = \frac{1}{r}$$

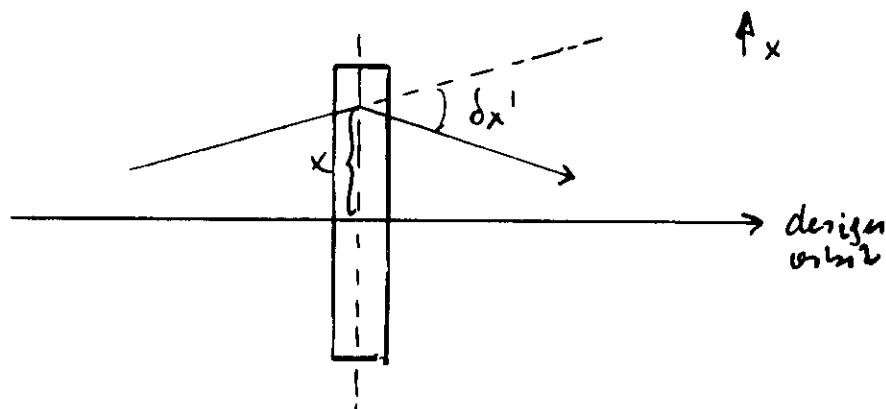


guiding field only is not sufficient!

→ Original deviations of the particle from the design orbit would lead to a loss after several turns.

THERMOPORSE →

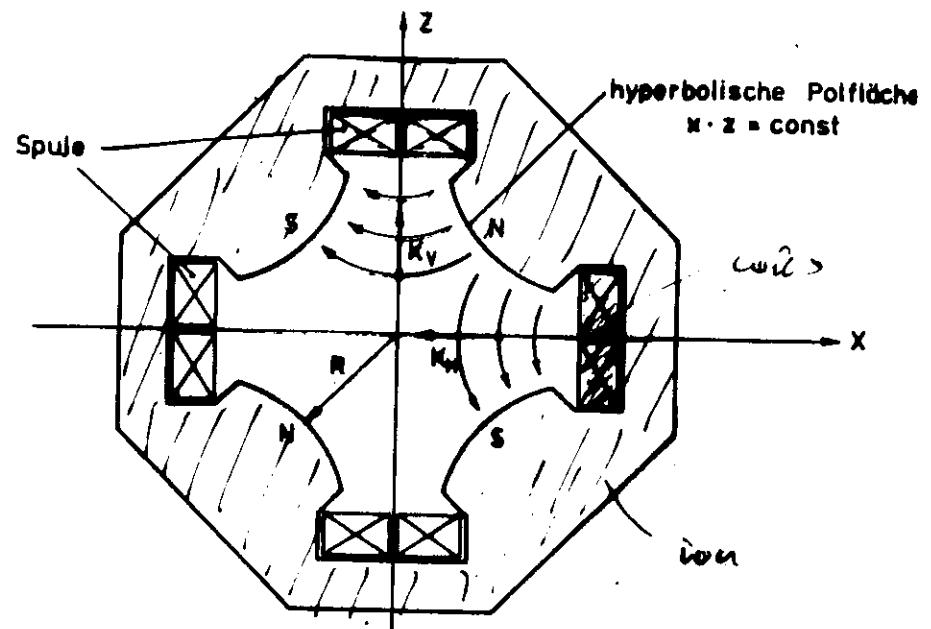
Force is needed to bend the particle back to the design orbit, with strength proportional to the deviation from the design orbit:



FOCUSING:

$$\delta x' = -g \cdot x$$

QUADRUPOLE → Focusing



Potential:  $V = -g \cdot x \cdot z$

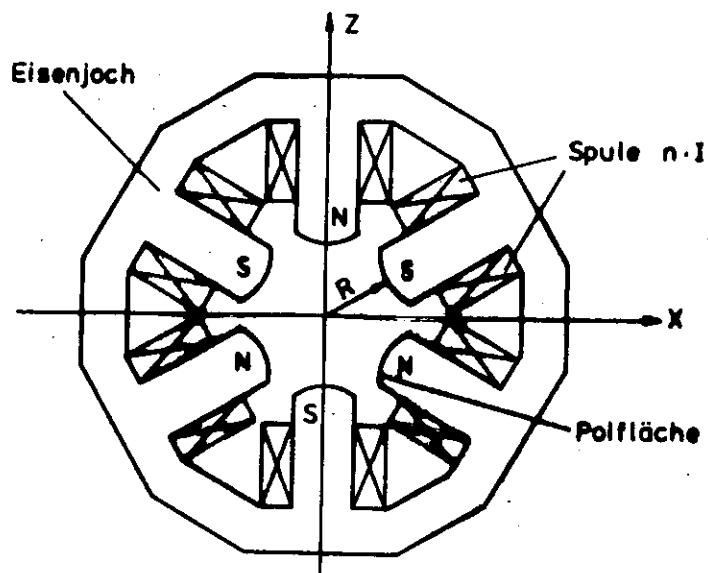
$$\frac{dV}{dx} = -gx = -\frac{\epsilon B_z}{L_x} \cdot x$$

REFLECTION:

$$\delta x' = -\frac{\epsilon}{\rho_0} \frac{\partial B_z}{\partial x} L_x \cdot x$$

EXTUPOLAS → for chromatic corrections

to avoid TIME LAG  
HEAD TAIL INT.



$$\delta x' = m \cdot x^2 + \left( \frac{1}{2} \frac{e}{p} \frac{\partial^2 B_0}{\partial x^2} L_s \right) \cdot x^2$$

$$\frac{\delta p}{p} \rightarrow \text{orbit deviation } x_0 = \frac{q^2 D}{p} \quad D \dots \text{dispersion}$$

$$q \rightarrow s/(1+\beta)$$

$$\delta x' = m(x - x_0)^2 = mx^2 - (2mx_0)x + mx_0^2$$

↓  
quadrupole

If in addition field errors are taken into account, the general expression for the field can be expanded in a Taylor series (for small deviations from the design orbit) →

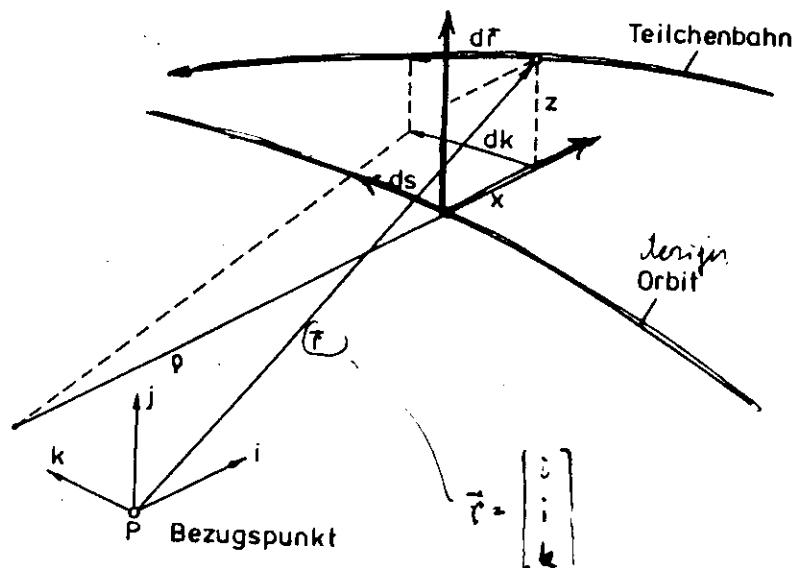
ONE PLANE:

$$\frac{1}{p} = \frac{e}{p} B_z(x) = \underbrace{\frac{e}{p} B_{z0} + \left( \frac{e}{p} \frac{\partial B_z}{\partial x} \right) x + \left( \frac{1}{2} \frac{e}{p} \frac{\partial^2 B_z}{\partial x^2} \right) x^2}_{\text{Regular elements of}} + \dots$$

circular accelerators

Equation of Motion:

$$\dot{\vec{p}} = e [\dot{\vec{r}} \times \vec{B}]$$



→ transformation to reference system moving with the particle

⇒

After changing the independent variable from

$$t \rightarrow s$$

we find after a straight forward evaluation of the equations of motion in the new reference frame →

$$\vec{r}'' = \frac{e}{p} \left( 1 + \frac{x}{p} \right) \begin{bmatrix} -B_z \\ B_x \\ x' B_z - z' B_x \end{bmatrix}$$

- for transverse magnetic fields only!

For a linear machine, i.e.

$$\begin{aligned} \frac{e}{p} B_z &= \frac{1}{p} + (b) x && \text{focusing} \\ \frac{e}{p} B_x &= -(b) x \end{aligned}$$

bending magnet deflection

→ Equations of motion:

$$X'' + (b + \frac{1}{\rho^2})X = 0$$

$$Z'' - b \cdot Z = 0$$

General:

$$\frac{d^2x}{ds^2} + K(s) \cdot x = 0$$

HILL's differential equation

Solution of any second order differential equation →

$$x(s) = C(s, s_0)x(s_0) + S(s, s_0)x'(s_0)$$

In matrix form, including the derivatives →

$$\begin{bmatrix} X \\ X' \end{bmatrix}_s, \begin{bmatrix} C & S \\ C' & S' \end{bmatrix} \begin{bmatrix} X \\ X' \end{bmatrix}_{s_0}$$

To solve the equation, we follow the historical way:

Substitute in the differential equation:

$$U = \frac{X}{\beta} \rightarrow \phi^1 = \frac{1}{\beta} \quad \text{Floquet transformation}$$

$$\frac{d^2x}{ds^2} + K(s)x = 0 \rightarrow \frac{d^2u}{dq^2} + u = 0$$

Harmonic oscillator with angular frequency  $\omega$

$\beta^1$  - beatfunction is defined by

$$\frac{d^2}{ds^2}(\beta^{11}) + K(s)(\beta^{11}) - \frac{1}{\beta^{31}} = 0$$

Solution of the harmonic oscillator:

$$u(\phi) = A \cos \phi + B \sin \phi$$

Develop the constants by defining the initial conditions  $\rightarrow \phi=0 \rightarrow u_0, u_{0\phi}$

$$u = \frac{x}{\beta} \Rightarrow A = u_0$$

$$\frac{x}{\beta})' = u' = \frac{1}{\beta} (x^1 + \lambda \frac{x}{\beta}) \rightarrow B = u_0' \beta \quad \lambda = -\frac{1}{2} \beta^2$$

$$\begin{bmatrix} u \\ u' \end{bmatrix} = \begin{bmatrix} \cos \phi & \beta \sin \phi \\ -\frac{1}{2} \sin \phi & \cos \phi \end{bmatrix} \begin{bmatrix} u \\ u' \end{bmatrix},$$

starting vector

$\rightarrow$  back transformation  $(u, u') \rightarrow (x, x')$

$$\begin{bmatrix} x \\ x' \end{bmatrix} = \begin{bmatrix} \sqrt{\beta} (\cos \phi + \lambda \sin \phi) & \sqrt{\beta} \sin \phi \\ -\frac{1}{2} \sqrt{\beta} ((1-\lambda)\cos \phi + (1+\lambda)\sin \phi) & \sqrt{\beta} (\cos \phi - \lambda \sin \phi) \end{bmatrix} \begin{bmatrix} x_0 \\ x'_0 \end{bmatrix}$$

$\lambda, \beta$  ... Constant Snyder parameters

By using the trigonometric identity

$$\cos^2 \phi + \sin^2 \phi = 1$$

we can derive the

Constant Snyder invariant

$$I = \frac{x^2 + (x^2 + x^1 \beta)^2}{\beta} = \frac{x_0^2 + (x_{00} + x_0' \beta_0)^2}{\beta_0^2}$$

- Equation of ellipse with area

$$E = \pi \cdot I$$

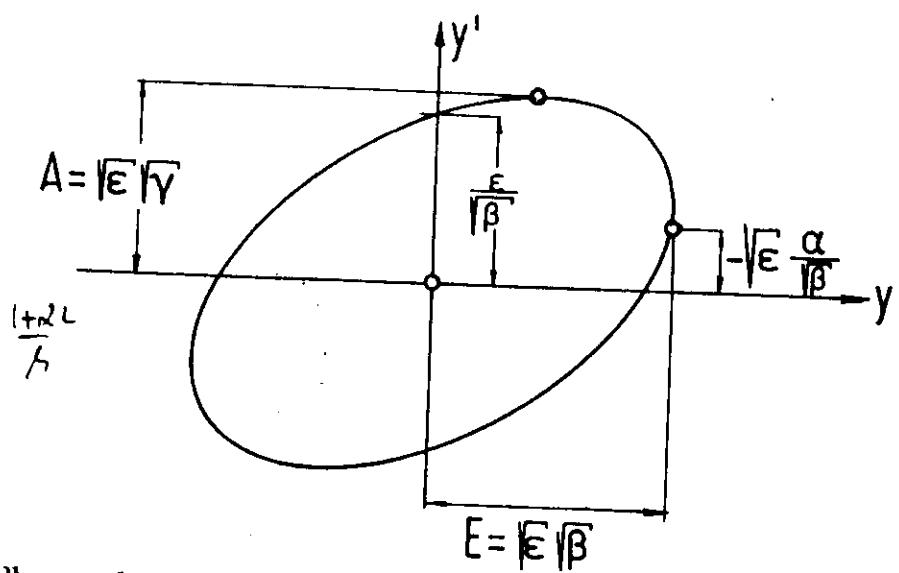
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Emittance

If we substitute  $x = A \cos(\phi + \delta)$   
we find

$$A = \sqrt{E \beta}$$

amplitude of  
rotation oscillations



Phase plane ellipse

Since the area of the phase-plane ellipse given the maximum amplitude of beta function oscillation  $E$  becomes smaller when  $\beta$  (larger).

$\beta$  = measure of beam cross section

### Periodic structures.

$$\left. \begin{array}{l} \beta = \beta_0 \\ d = d_0 \\ \phi = 2\pi Q - \mu \end{array} \right\}$$

$$\left. \begin{array}{l} \beta_0, d_0, \phi_0 \\ S_0 \end{array} \right\}$$

$$\phi - \phi_0 = 2\pi Q - \mu$$

$d .. \text{time}$

$$\begin{bmatrix} x \\ x' \end{bmatrix} = \begin{bmatrix} \cos \mu + d \sin \mu & \beta \sin \mu \\ -\frac{1+d^2}{\beta} \sin \mu & \cos \mu - d \sin \mu \end{bmatrix} \begin{bmatrix} x \\ x' \end{bmatrix},$$

$$\vec{x}_n = [\mathbb{I} \sin \mu + \mathbb{J} \cos \mu] \vec{x}_0$$

$$\mathbb{I} = \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix}, \quad \mathbb{J} = \begin{bmatrix} d & \beta \\ -r & -d \end{bmatrix}$$

$$\boxed{\vec{x}_n = \mathbb{M}^n \vec{x}_0}$$

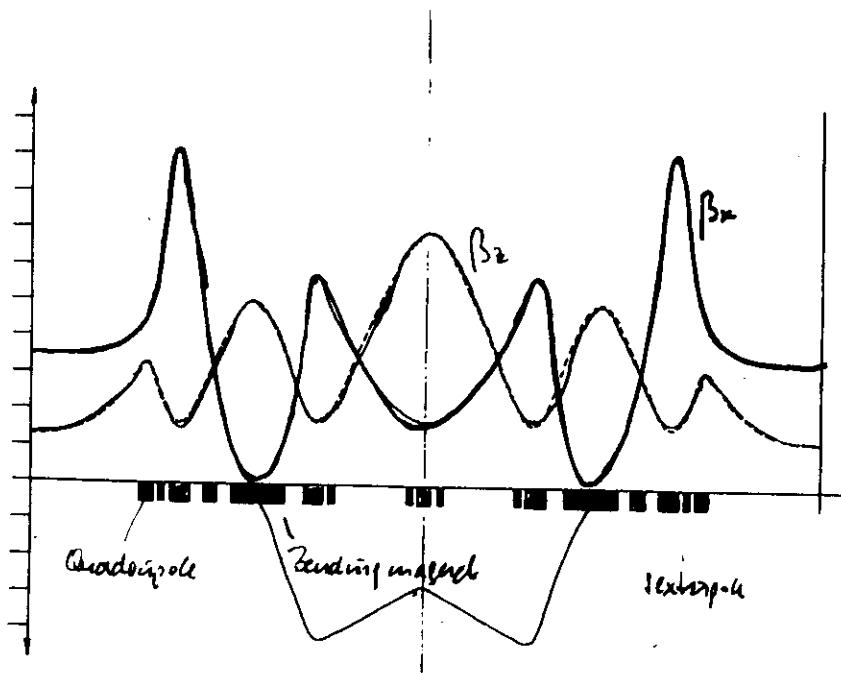
$$= [\mathbb{I} \sin \mu + \mathbb{J} \cos \mu] \vec{x}_0$$

$$r = \frac{1+d^2}{\beta}$$

... initial vector  $\vec{x}_0$  transformed over  $n$  turns in a circular accelerator!

## SINCHROTRONE TRIESTE

- lattice functions



The constant-frequency parameters are the characteristic of a magnet lattice!

How to calculate the structure functions  $\beta$  and  $\gamma$ ?

Phase-plane ellipse in parameter form:

$$\text{So: } \vec{x}(s) = \sqrt{\epsilon} [ \vec{x}_1(s_0) \cos \delta + \vec{x}_2(s_0) \sin \delta ] \\ 0 \leq \delta \leq 2\pi$$

Ellipse defined by linear independent vectors

$$\vec{x}_1 = \begin{bmatrix} x_1 \\ x_2 \end{bmatrix} \text{ and } \vec{x}_2 = \begin{bmatrix} x_1 \\ x_2 \end{bmatrix}$$

To get the phase plane area  $\epsilon$ , they must be normalized to give

$$\vec{x}_2 \begin{pmatrix} 0 & -1 \\ 1 & 0 \end{pmatrix} \vec{x}_1 = 1$$

i.e. Wronski-determinante = 1

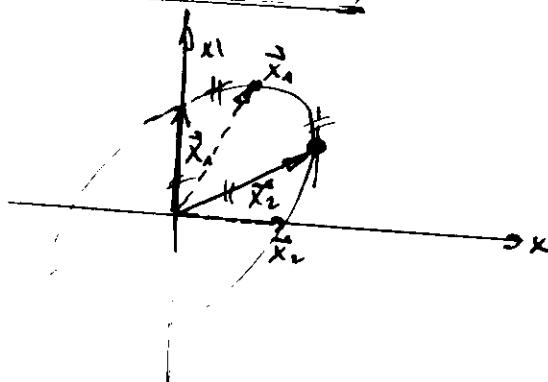
a particle is moving through  
magnet structure, the form  
of ellipse is changed

$$\vec{r} = \bar{r} E [\vec{x}_1(s) \cos \vartheta + \vec{x}_2(s) \sin \vartheta]$$

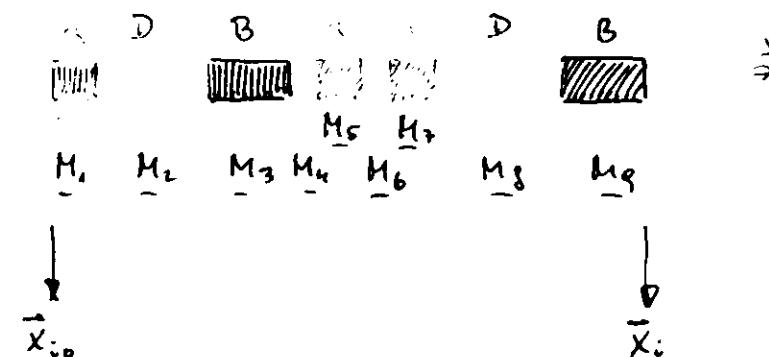
$$\vec{x}_i(s) = M(s) s_i \vec{x}_{i0}$$

evaluated numerically  
by transforming current  
by element

$$\frac{x_1^2 + x_2^2}{-(x_1 x_{1'} + x_2 x_{2'})}$$



To calculate the motion function, the conjugated vector are transformed through H.c. structure  $\rightarrow$



$$\vec{x}_i = M_9 M_8 M_7 M_6 M_5 M_4 M_3 M_2 M_1 \vec{x}_{i0}$$

To get the transformation matrices the  
differential equation is solved piecewise

$$x'' + K(s) x = 0$$

$$K(s) = b \dots \text{Quadrupoles}$$

$$\frac{1}{s^2} \dots \text{Bending magnets}$$

$$c \dots \text{Drift spaces}$$

Transformation matrix  $\underline{M} \rightarrow$

$$\begin{bmatrix} 1 & s \\ 0 & 1 \end{bmatrix}$$

DRIFT

$$\begin{bmatrix} \cos \frac{s}{\rho} & s \sin \frac{s}{\rho} \\ -\frac{1}{\rho} \sin \frac{s}{\rho} & \omega \frac{s}{\rho} \end{bmatrix}$$

BENDING MAGNET

$$\begin{bmatrix} \cos \sqrt{k_1} t & \frac{1}{\sqrt{k_1}} \sin \sqrt{k_1} t \\ -\sqrt{k_1} \sin \sqrt{k_1} t & \cos \sqrt{k_1} t \end{bmatrix}$$

QUADRUPOLE  
(FOC)

How to get the initial values  
of the conjugated vectors?

Linear machines  $\rightarrow \bar{x}_1, \bar{x}_2$  is given by  
the initial beam condition

Circular machine  $\rightarrow$  Phase plane ellipse  
must transform into the  
after 1 turn

Resonance parameter form of phase plane motion:

$$\begin{aligned} \bar{x}(s_0) &= \bar{t} \bar{e} \left\{ \bar{x}_1(s_0) \cos \delta + \bar{x}_2(s_0) \sin \delta \right\} \\ &= \frac{\bar{t} \bar{e}}{2} \left\{ [x_1(s_0) - i \bar{x}_2(s_0)] e^{i \delta} + [x_1(s_0) + i \bar{x}_2(s_0)] e^{-i \delta} \right\} \end{aligned}$$

We have shown before that the transformation  
of a vector over one closed turn changes  
only the phase, i.e.  $\rightarrow$

$\leftrightarrow$   $i\delta = \cos \delta + i \sin \delta$

$$\underline{M}(s_0 + t, s_0) [\bar{x}_x(s_0) - i \bar{x}_v(s_0)] = e^{-i 2\pi Q} [x_x(s_0) - i x_v(s_0)]$$

Eigenwert-equation of revolution matrix  $\underline{M}$

$$|\underline{M} \vec{q} = A \vec{q}|$$

The motion is stable, if  $|\lambda| = |e^{i 2\pi Q}| = 1$ ,  
i.e.  $Q = \text{real}$ !

### Achieving stability:

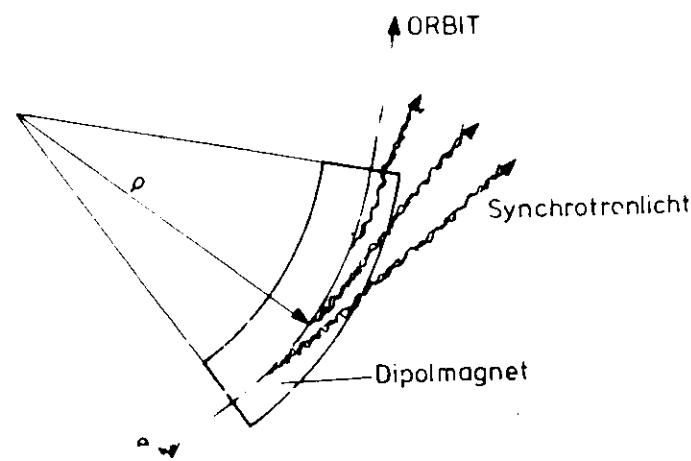
to find the initial conjugate vectors,  
solve the Eigenwert-equation of  
revolution matrix.

Transform from beam through the  
structure to calculate the structure  
function ( $f$ )

→ define required magnet operation!

### LONGITUDINAL MOTION:

Emission of Synchrotron Light  $\rightarrow$



Radiated power:

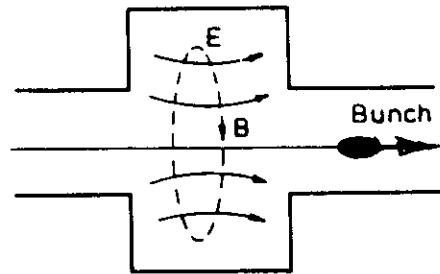
$$P_F = \frac{2e^2 c^2 r_0}{3(m_0 c^2)^3} \cdot E^2 B^2$$

With

$$\beta = \frac{e c B}{E} \Rightarrow$$

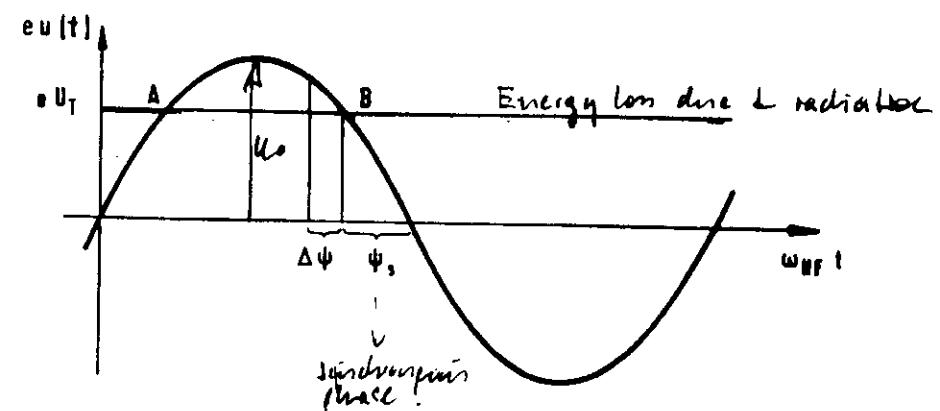
$$P_F = 88.5 \frac{E^4 [\text{GeV}]}{\beta [\text{m}]}$$

Energy lost by synchrotron radiation must be compensated in 'accelerating sections' (cavities)



→ cavity with oscillating field  
(350 MHz, 800 MHz, 1-3 GHz)

Accelerating voltage in the cavities →



$eU_T$  ... necessary to compensate the radiation losses

Energy gain by accelerating voltage:

$$E = e U_0 \sin(\varphi_s + \Delta\varphi) \quad \Delta\varphi \text{... phase deviation}$$

$$\underline{E_0 = e U_0 \sin \varphi_s} \quad \text{exact phase!}$$

$$\frac{E - E_0}{T_0} \approx \frac{d\Delta E}{dt} = e U_0 f_0 [\sin(\varphi_s + \Delta\varphi) - \sin \varphi_s]$$

Period of synchrotron oscillation  $\Rightarrow$  revolution period!

Phase deviation for particles with wrong revolution time, i.e.

$$T = T_0 + \Delta T$$

⇒

$$\Delta\gamma = -\omega_{RF} \cdot \Delta T$$

$$\frac{d\Delta\gamma}{dt} = -\omega_{RF} \frac{\Delta T}{T} = -\omega_{RF} \frac{\Delta L}{L}$$

$$\frac{\Delta L}{L} \approx d_c \frac{\Delta E}{E}$$

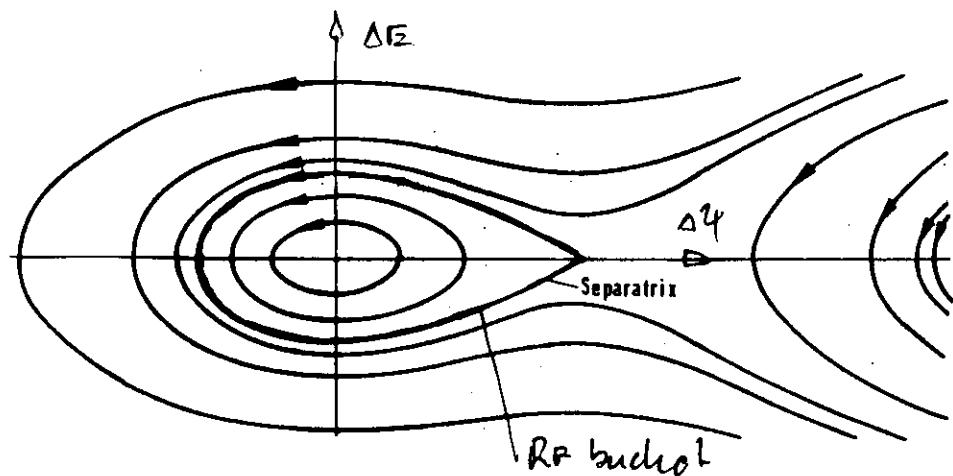
$d_c$  .. momentum compaction

$$\boxed{\frac{d\Delta\gamma}{dt} = -\omega_{RF} d_c \frac{\Delta E}{E}}$$

$\Delta E$  substituted from previous equation gives →

$$\boxed{\frac{d^2\Delta\gamma}{dt^2} + \omega_0 \omega_{RF} \frac{d_c e U_0}{2\pi E_0} [\sin(\gamma_s + \Delta\gamma) - \sin\gamma_s] = 0}$$

Phase-plane of longitudinal motion →



For small amplitudes  $\Delta\gamma \rightarrow$   
Harmonic oscillation

$$\sin(\gamma_s + \Delta\gamma) - \sin\gamma_s \approx (\omega \gamma_s) \Delta\gamma$$

$$\boxed{\frac{d^2\Delta\gamma}{dt^2} + \Omega^2 \Delta\gamma = 0}$$

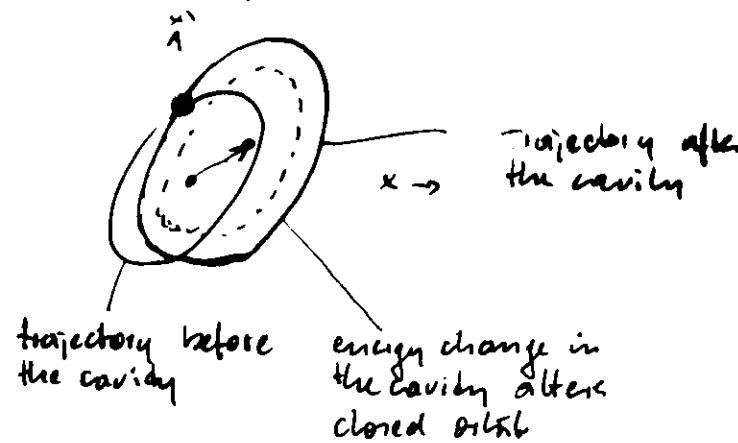
$$\Omega^2 = \omega_0 \omega_{RF} \frac{d_c e U_0 \cos\gamma_s}{2\pi E_0}$$

Coupling between transverse (betatron) motion and longitudinal (synchrotron) motion:

Sources: uncompensated chromaticity fields in accelerating structures  
beam-beam interaction (crossing angle)  
dispersion in the cavity  
⋮

EXAMPLE: Dispersion in the cavity  
i.e. orbit displacement in the cavity varies with the momentum of the particle.

Transverse phase space:



Must be numerically evaluated:

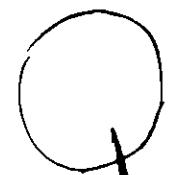
CAVITY - transformation:

$$\bar{E}_{n+1} = E_n + eV [\sin(\varphi_0 + \varphi_n) - \sin \varphi_0]$$

$$\varphi_{n+1} = \varphi_n$$

$$x_{n+1} = x_n - D \frac{\bar{E}_{n+1} - E_n}{E_0}$$

$$x'_{n+1} = x'_n - D' -$$



cavity

MAGNET STRUCTURES - transformation:

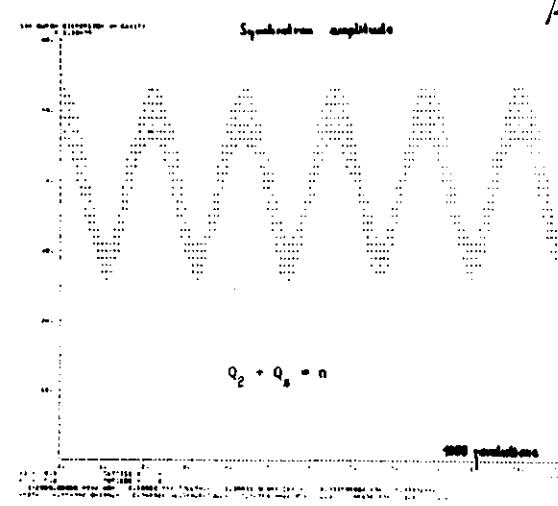
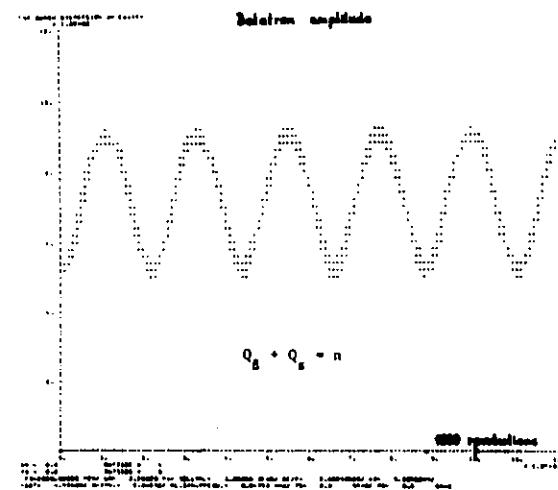
$$E_{n+2} = \bar{E}_{n+1}$$

$$\varphi_{n+2} = \varphi_{n+1} - 2\pi f \left[ \ln \frac{\bar{E}_{n+1} - E_0}{E_0} + \underbrace{\{(x_{n+1}, x'_{n+1}, D)\}}_{=0 \text{ for } D \ll 1} \right]$$

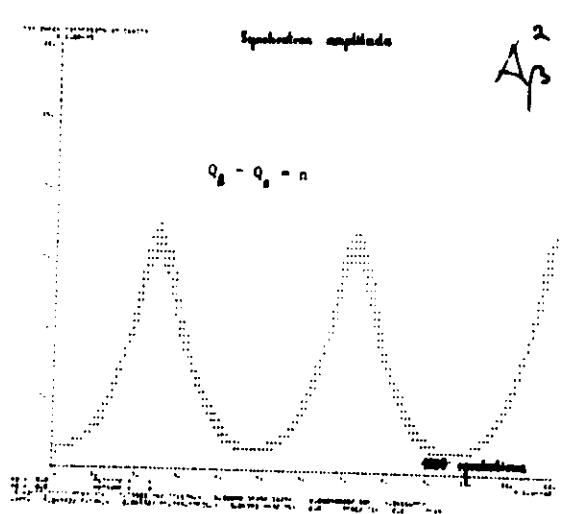
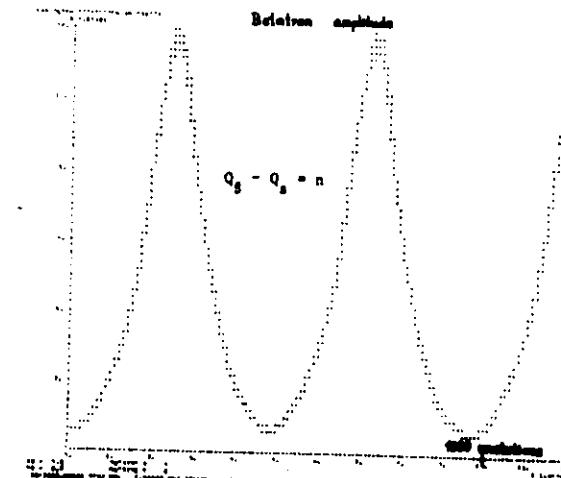
$$x_{n+2} = x_{n+1} \cos \varphi + x'_{n+1} \sin \varphi$$

$$x'_{n+2} = -\frac{x_{n+1}}{T} \sin \varphi + x'_{n+1} \cos \varphi$$

? OSCILLATION AMPLITUDE IS INCREASED!



$$A_\beta^2 + q A_{3\mu\nu}^2 = \text{const}$$



$$A_\beta^2 = q A_s^2 = \text{const}$$

Exchange of energy only!

both amplitudes increase!

## NONLINEAR MOTION (transverse)

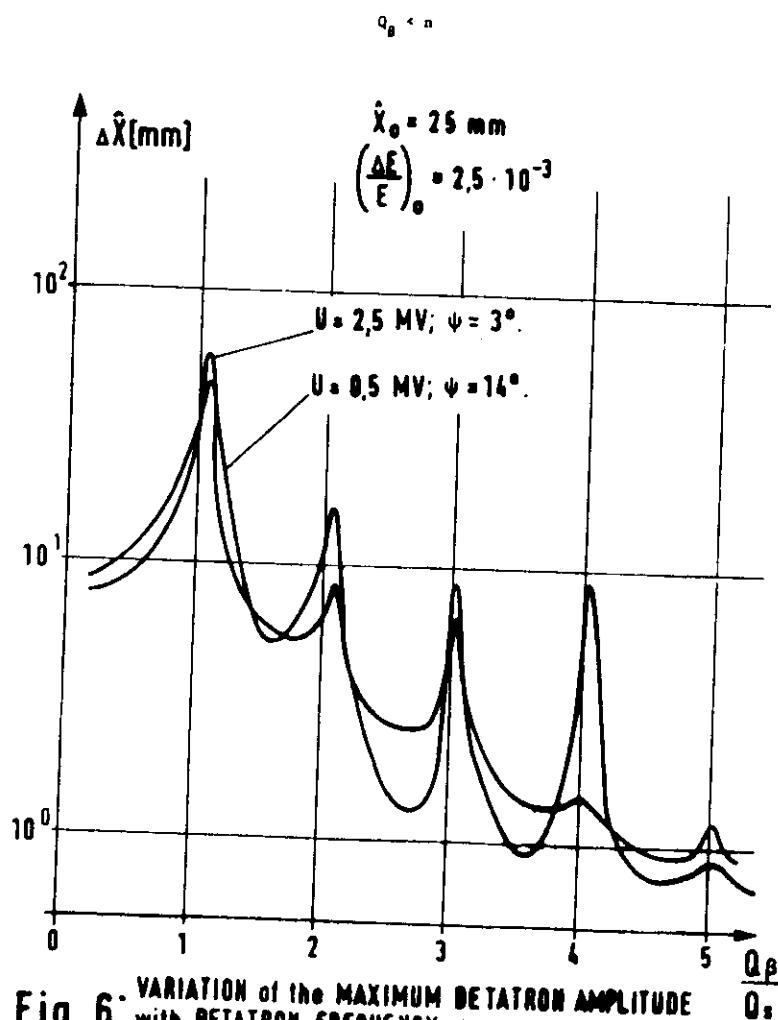
→ due to sextupoles  
or field errors

Equations of motion:

$$\frac{d^l X}{ds^l} + k(s) X = \frac{e}{p_0} \sum_{n=0} b_n(s) X^n$$

$$b_n = \frac{1}{n!} \frac{\partial^n B}{\partial x^n}$$

- b<sub>0</sub> ... dipole
- b<sub>1</sub> ... quadrupole
- b<sub>2</sub> ... sextupole
- ⋮



In superconducting magnets the still relevant maximum orders are 24-poles (usually !)

Transformation do normalized coordinates (as before in the linear case)  $\rightarrow$  Floquet transform.

$$u = \frac{x}{\sqrt{\beta}}, \quad \phi = \int \frac{ds}{\beta}$$

$\Rightarrow$

$$\boxed{\frac{d^2 u}{d\phi^2} + u = \frac{e}{\rho} \sum_n b_n(\phi) \beta^{\frac{n+3}{2}}(\phi) u^n}$$

Periodic function  $\rightarrow$

$$\frac{e}{\rho} b_n(\phi) \beta^{\frac{n+3}{2}}(\phi) = \sum_k f_{nk} \cos 2\pi k \cdot \frac{\phi}{2\pi Q}$$

$\mu = 2\pi Q$

represented by Fourier series with period  $\underline{2\pi Q}$

(Assumption here: even function with zero mean)

Fourier coefficient:

$$f_{nk} = \frac{1}{\pi Q} \int_0^{2\pi Q} \left[ \frac{e}{\rho} b_n(\phi) \beta^{\frac{n+3}{2}}(\phi) \right] \cos \frac{k}{Q} \phi \, d\phi$$

For small distortions we can substitute the homogeneous solution for  $u$  at the right hand side of the differential equation:

$$u = u_0 \cos \phi + \underbrace{u_1 \sin \phi}_{=0}$$

$$\frac{d^2 u}{d\phi^2} + u = \sum_n u^n \sum_k f_{nk} \cos \frac{k}{Q} \phi$$

$$u^n = u_0^n (\cos \phi)^n = \frac{u_0^n}{2^{n-1}} \sum_{p=0}^{n-1} \binom{n}{p} \cos (n-2p)\phi$$

$$\frac{d^2 u}{d\phi^2} + u = \sum_n \frac{U_0^n}{2^{n-1}} \sum_{p=0}^{\frac{n}{2}} \binom{n}{p} \cos(n-2p)\phi \sum_k f_{nk} \cos \frac{k}{Q}\phi$$

i.e. beat note amplitude increases,  
if  
 $(\frac{k}{Q} - n) = 1$  or

$$(n+1)Q = k$$

Resonance condition for 1-dimensional resonance

e.g.  $n=2 \rightarrow$  Sextipole  $\rightarrow (\frac{1}{2} \frac{\partial^4 U}{\partial x^2})$

$$3Q = k$$

In the general 2-dimensional case we have the resonances  $\rightarrow$

$$\left[ \begin{array}{l} 3Q_x \\ 2Q_x \pm Q_z \\ Q_x \pm 2Q_z \\ 3Q_z \end{array} \right] = \text{integer!}$$

$$\boxed{U_x Q_x + U_z Q_z = p}$$

Resonances in the presence of sextipole fields!

$$N = |u_x| + |u_z| \sim \text{order of resonance}$$

take one term only  $\rightarrow$

$$\frac{d^2 u}{d\phi^2} + u = \underbrace{\frac{U_0^n}{2^{n-1}} f_{nk} \cos n\phi \cos \frac{k}{Q}\phi}_{(p=0)}$$

$$\frac{1}{2} [\cos(n - \frac{k}{Q})\phi + \cos(n + \frac{k}{Q})\phi]$$

only  $\rightarrow$

$$\boxed{\frac{d^2 u}{d\phi^2} + u = A \cos(n - \frac{k}{Q})\phi}$$

$$A = \frac{U_0^n}{2^n} f_{nk}$$

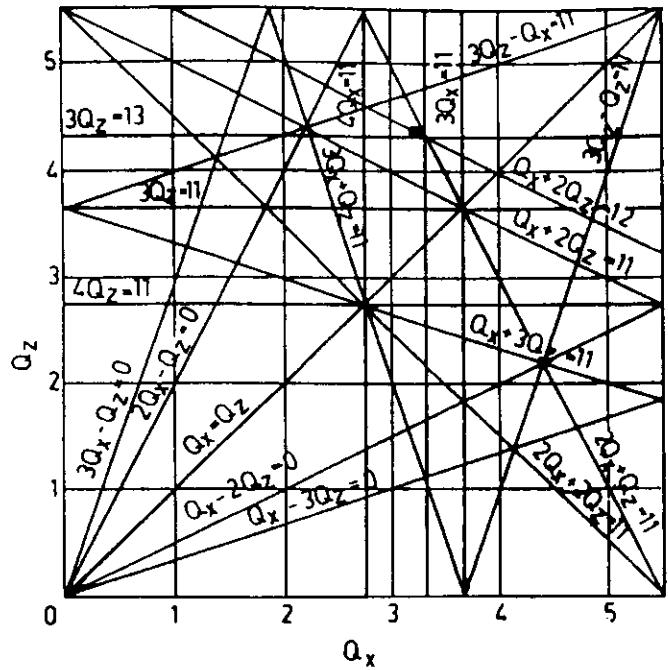
Solution:

$$u = u_n + u_p$$

$$u_n = A_n \cos \phi$$

$$u_p = \underbrace{\frac{A}{1 - (\frac{k}{Q} - n)^2}}_{\text{Resonance!}} \cos(n - \frac{k}{Q})\phi +$$

Resonance term!



Resonance lines in 2-dimensional  
time diagram  
(up to 4<sup>th</sup> order)

$$n_x Q_x + n_z Q_z = p \quad N = |n_x| + |n_z| \dots \text{order of resonance!}$$

Maximum stable betatron amplitude  
can be calculated analytical for  
one isolated resonance.

For a realistic pattern of magnet  
field errors one has to simulate the  
motion with a computer  $\Rightarrow$

### TRACING

### Tracking codes:

PATRICIA  
MAD  
RIGETRACH  
DIAMAT  
TRANSPORT  
:  
:

# NICK COOKES

Principle structure of these cookes:

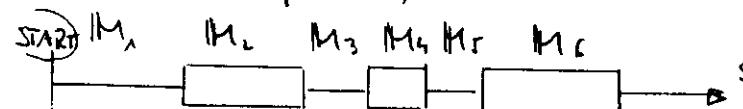
## INPUT:

Magnet structure  
Magnet strengths  
Field energ.

Tracking parameters:  
# of turns  
# of particles  
initial amplitude

## Find Revolution Matrix:

(Linear optics)



$$M = \prod_{n=1}^N M_n$$

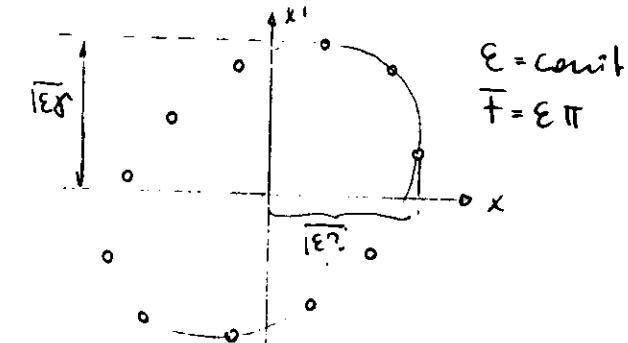
$M_n$  - single element transformation  
(6x6)

Calculate optical parameters at the starting point,

by solving the Eigenval. equation of the revolution matrix

$$\begin{aligned} f &= \frac{1+d^2}{\beta} \\ d &= \frac{1}{2} \frac{\alpha \beta}{d \beta} \end{aligned}$$

## Initial coordinates:



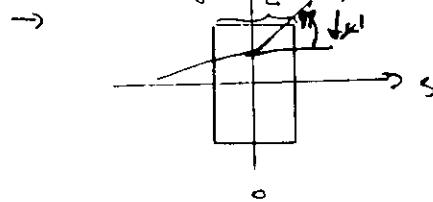
Tracking of particle ensemble through the structure:

① Linear element:  $\vec{x}_f = M \vec{x}_i$

## ② Nonlinear element:

$$\frac{d^2x}{ds^2} = \frac{e}{p_0} \sum_{n=0} b_n(s_i) X_i^n$$

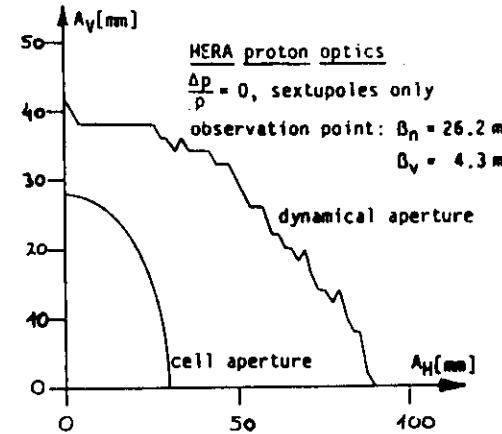
thin magnet approximation



Kick:

$$\frac{dx}{ds} = f_x = \sum_n (b_n L_n) X_i^n$$

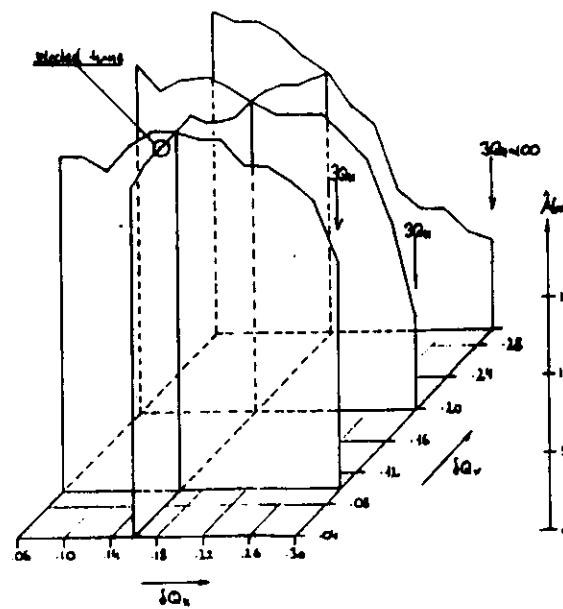
Find maximum stable  
betatron amplitude by  
varying the initial value

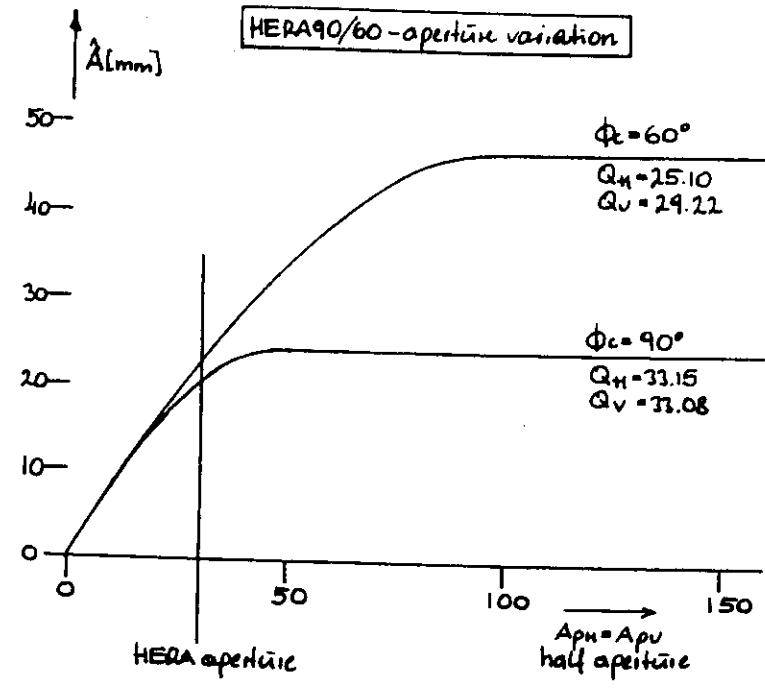
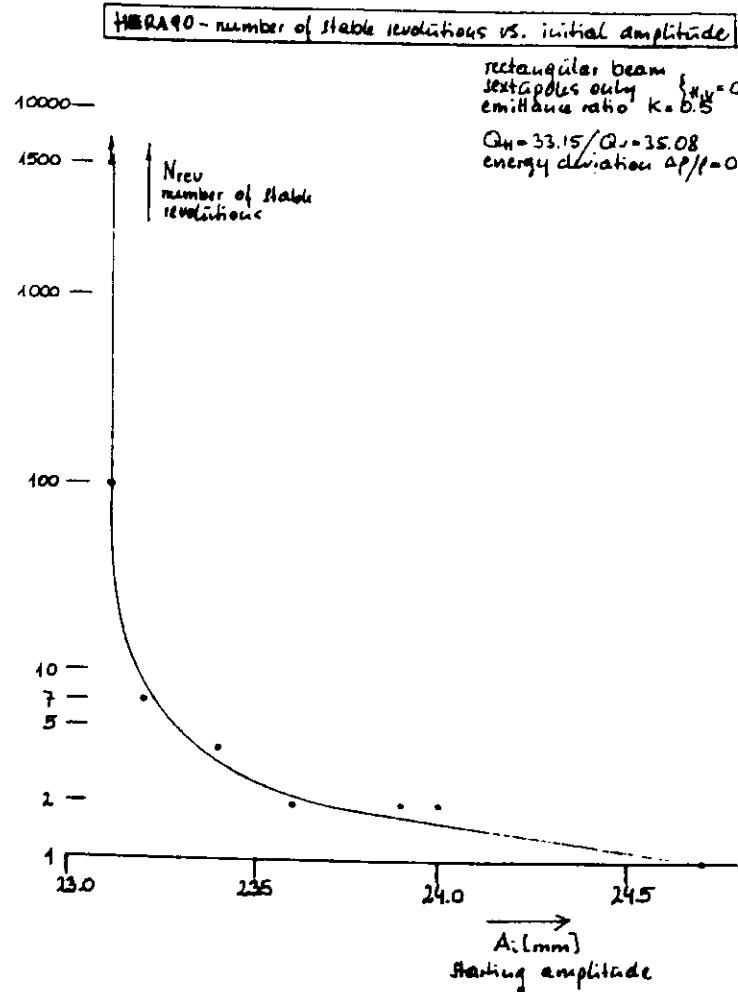


### HERA90 - tune variation

Maximum stable initial  
amplitude vs. tune

rectangular beam  
 sextupoles only  $\beta_{u,v} = 0$   
 emittance ratio  $K = 0.5$   
 energy deviation  $\delta p/p = 0$   
 $\alpha_u = 33 + d\alpha_u / \alpha_u = 15 + d\alpha_u$   
 $N_{uv} = 100$

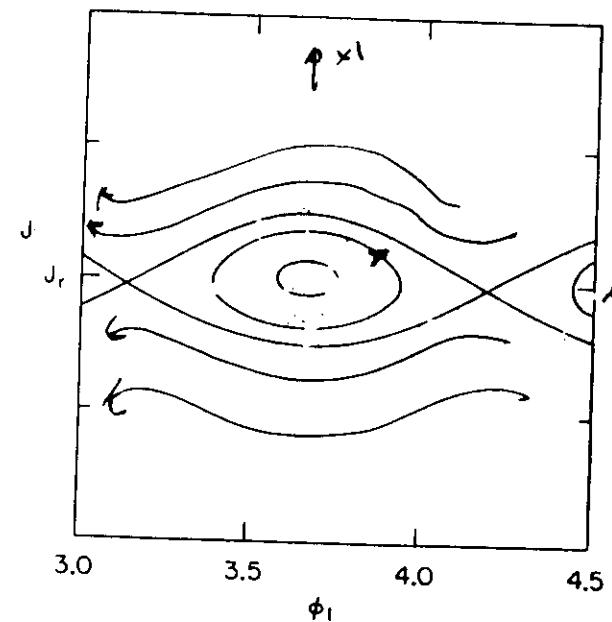




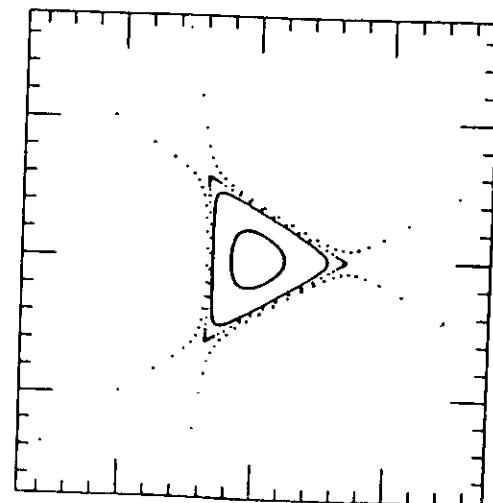
rectangular beam  
sextupoles only  
emittance ratio  $K = 1.0$   
no energy deviation  
Nrev = 30 !

## Phase space motion:

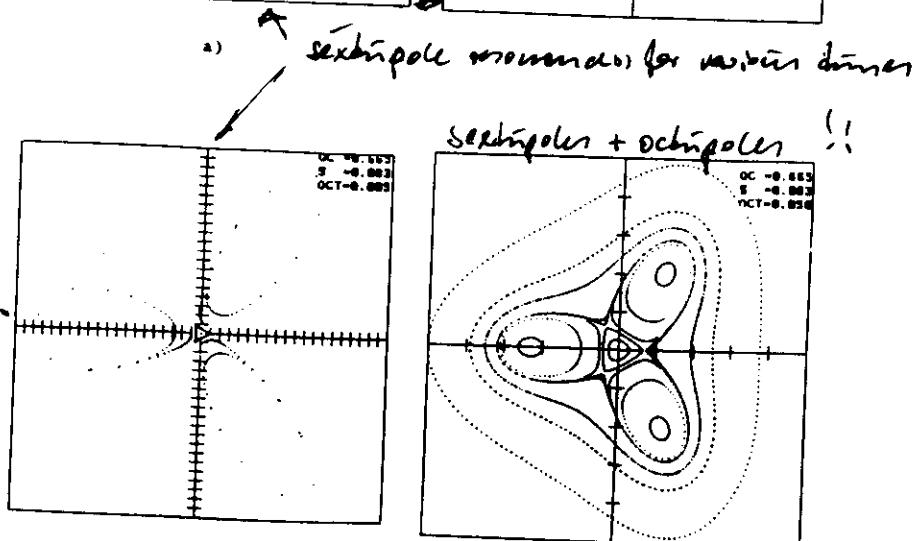
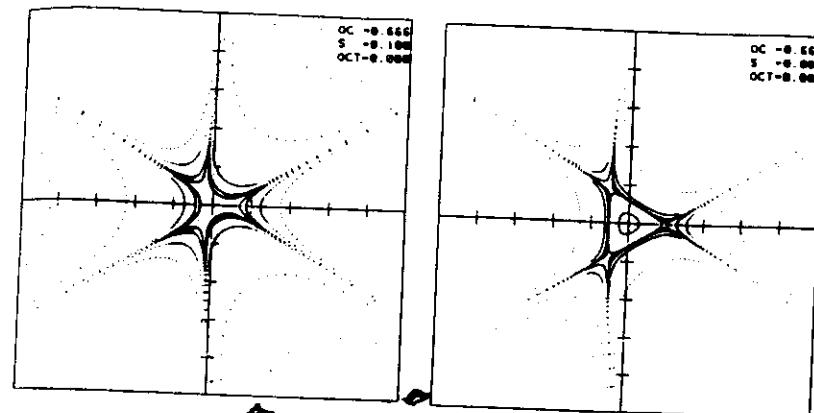
Pendulum



Motion near a third integer resonance in a circular accelerator:



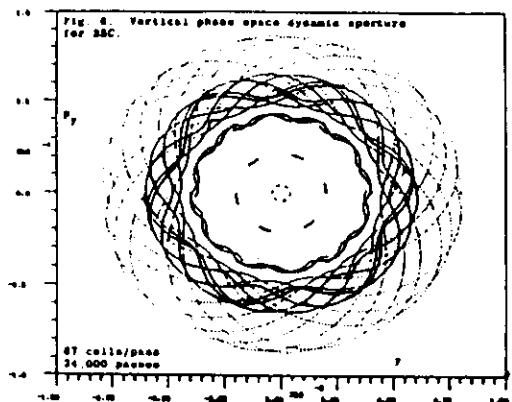
Unstable motion due to sextupole nonlinearities, stabilized by octopoles  $\rightarrow$



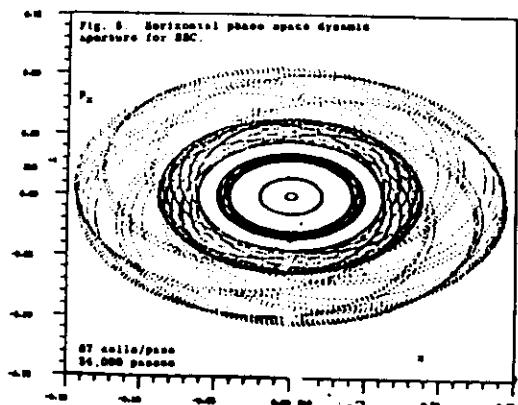
Landau damping due to octopoles !)

Turn variation with amplitude  $\rightarrow$  particle falls out of the resonance !

Perm: MARYLI

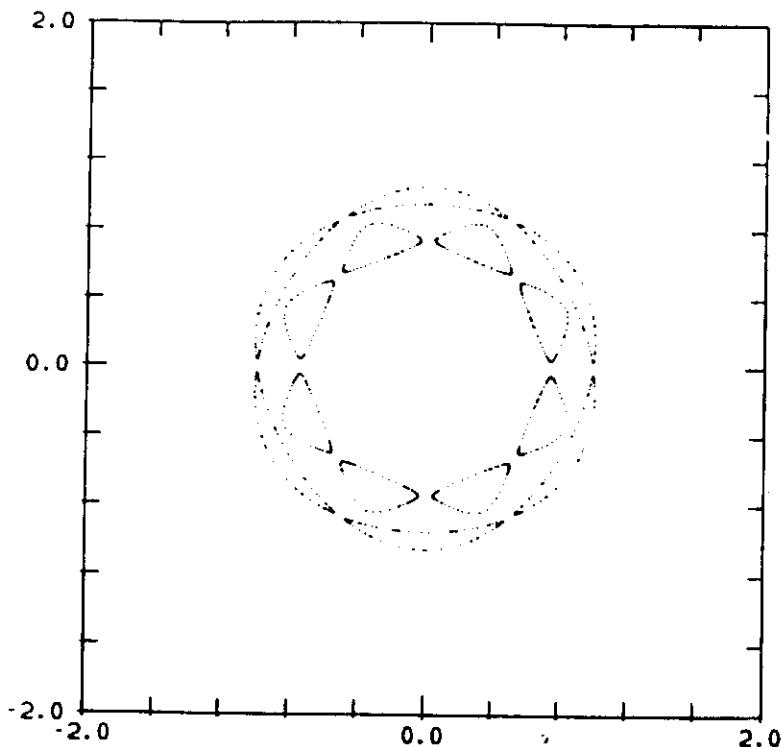


Vertical



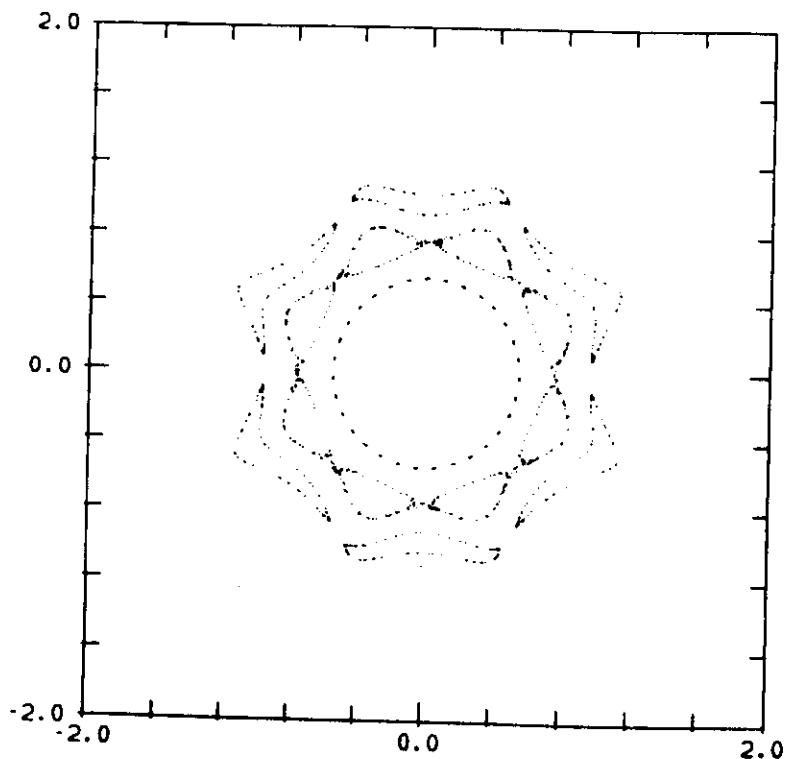
Horizontal

Isolated resonances plotted together  $\rightarrow$

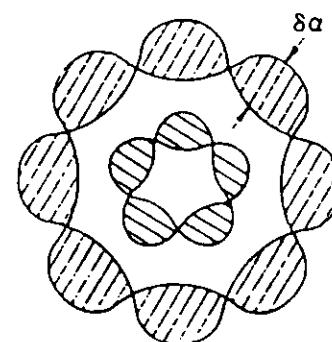


Situation becomes complicated if the particle motion is influenced by more than one resonance!

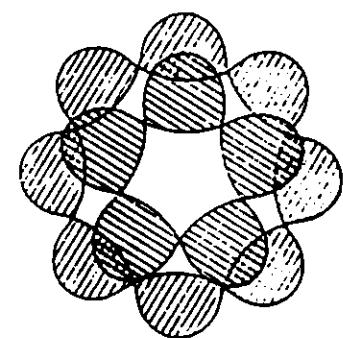
Actual phase space for these resonances  $\rightarrow$



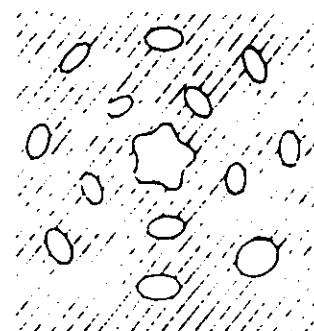
If the resonances start to overlap, the particle can easily become chaotic  $\rightarrow$



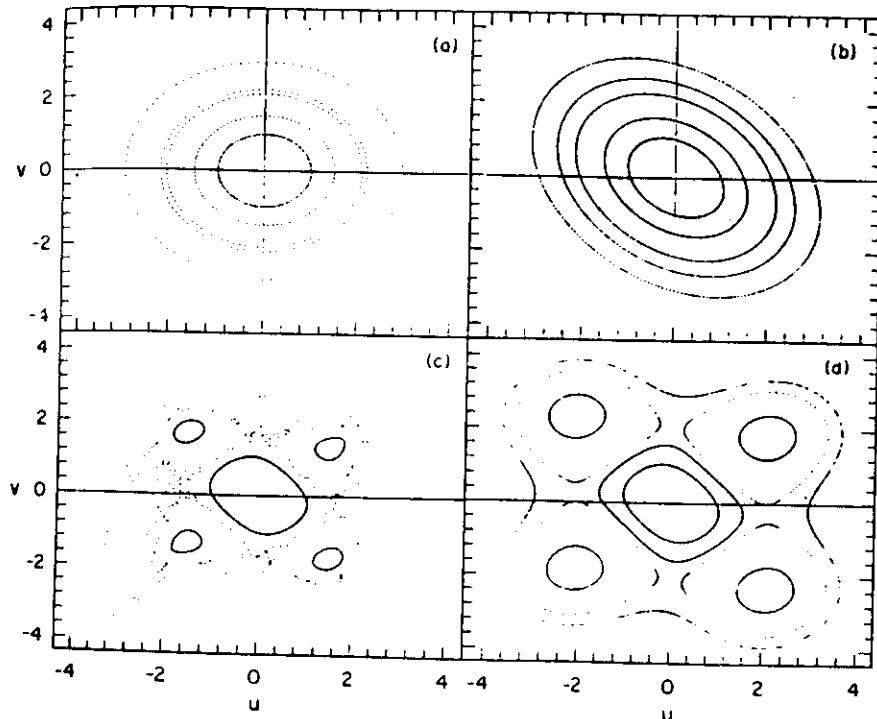
Single Resonances



Overlapping Resonances



Actual phase space

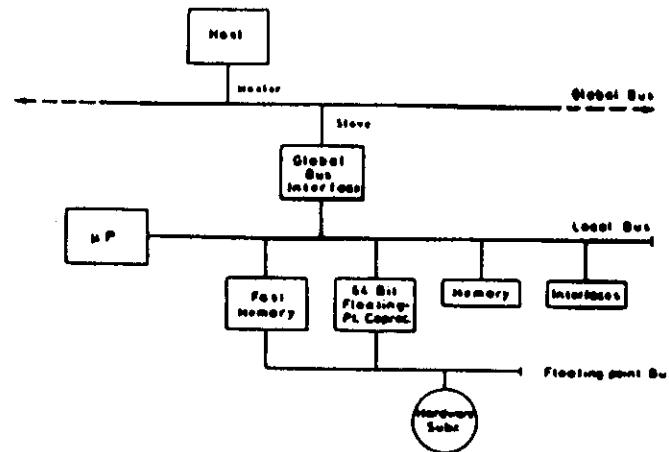


Regular motion  $\rightarrow$  concentric curves  
or islands

Chaotic motion  $\rightarrow$  'randomly' distributed orbits

To perform long time tracking, a dedicated computer has been developed  $\rightarrow$   
parallel microprocessors (one for each particle)

Conceptual design  $\rightarrow$



Host computer - programs compiled and linked  
then can directly run on the μP  
μP - connected with global bus interface to local bus to other interface

μP: MC 68000  
double precision floating point unit controller  
memory with 128 kBytes

## long-term stability

Even though particles may be chaotic, they may nevertheless survive for the limited number of revolutions normally accessible

To distinguish regular from chaotic motion use concept of characteristic Lyapunov exponent →

$$\lambda = \lim_{\substack{d_0 \rightarrow 0 \\ N \rightarrow \infty}} (\ln \left| \frac{d_N}{d_0} \right|)$$

d.. separation in phase space

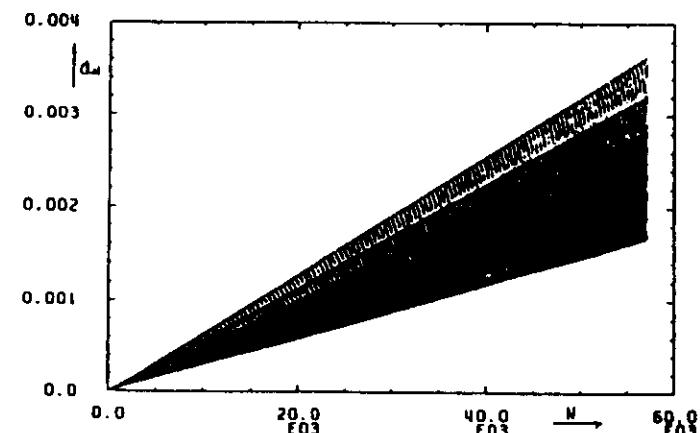
N.. revolution number

For chaotic motion the distance in phase space of two neighbouring trajectories increases exponentially with the Lyapunov exponent.

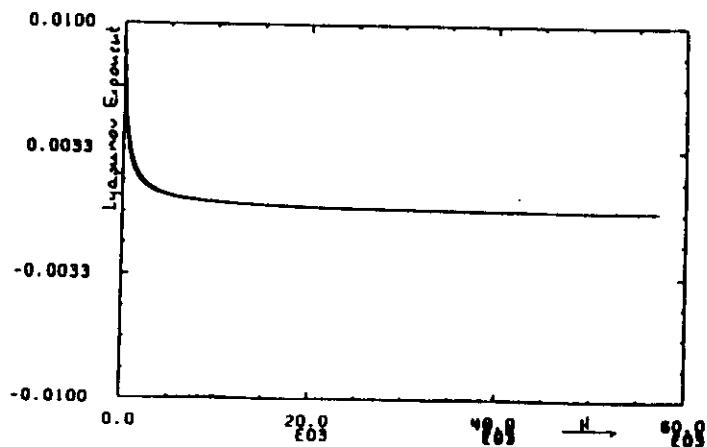
→ BREAK OF STRONG CAUSALITY!

## Regular motion

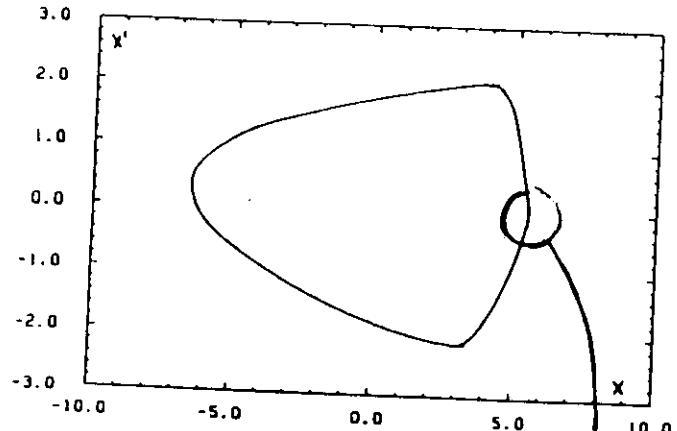
- distance in phase space increases linearly
- Lyapunov exponent = 0



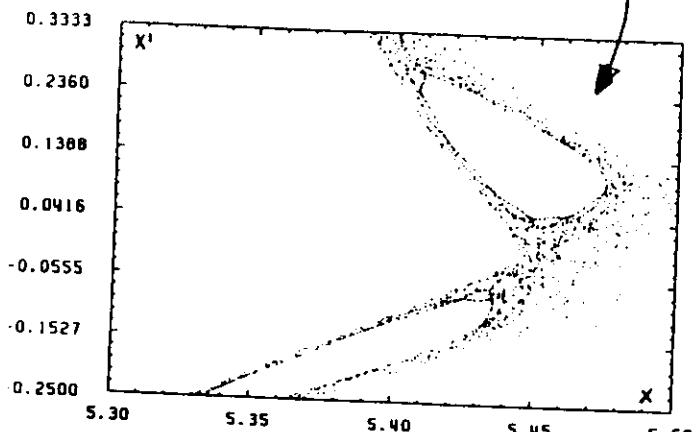
Trajectory separation for regular motion.



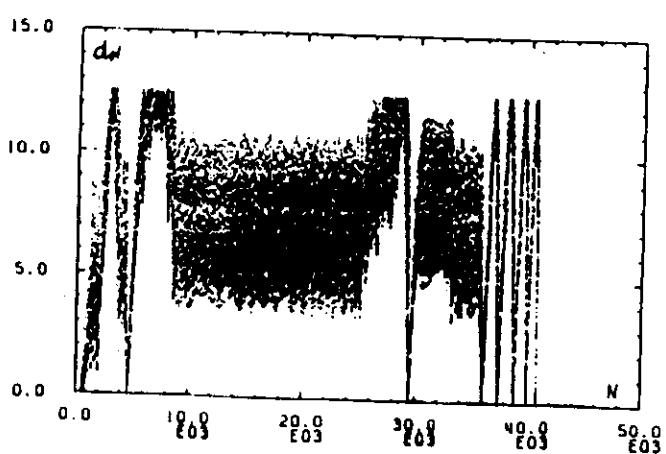
Lyapunov exponent for regular motion.



Trajectory  
close to the  
dynamic  
limit

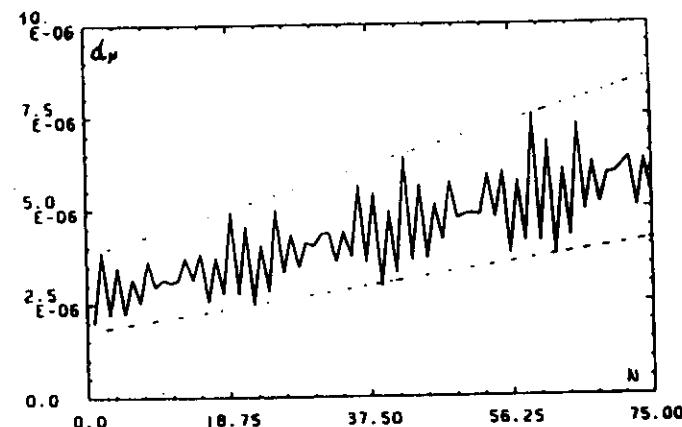


Chaos

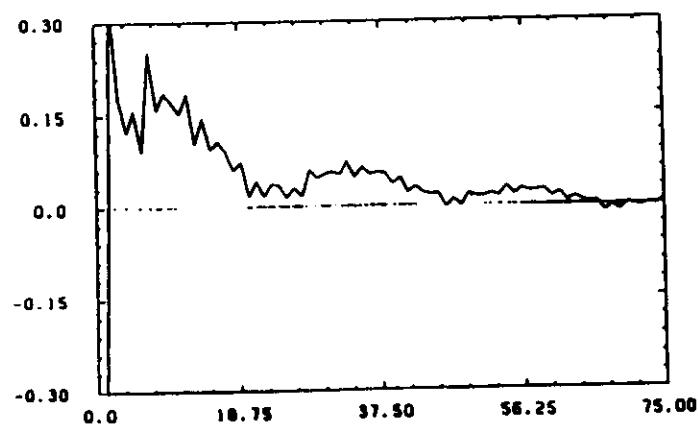


Distance in phase  
space!  
Lyapunov-  
Exponent

## Regular motion

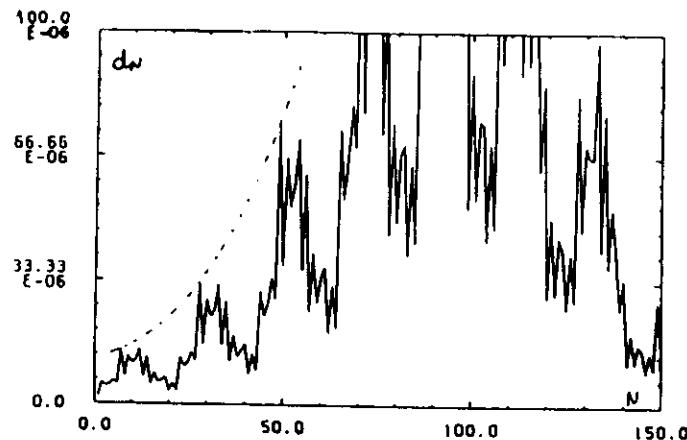


Distance of trajectories in phase space for regular motion

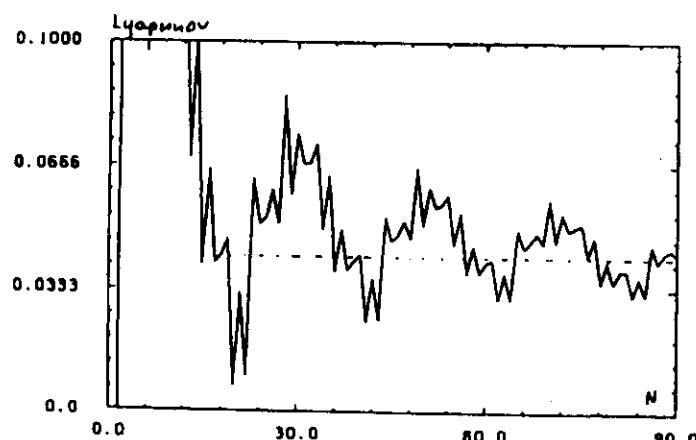


Lyapunov exponent for regular motion.

## Chaotic motion

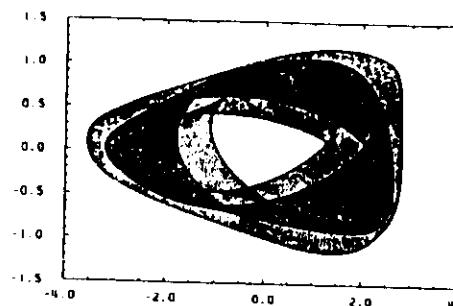


Distance of trajectories in phase for chaotic motion

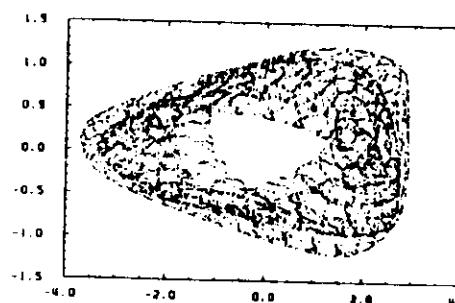


Lyapunov exponent to chaotic motion.

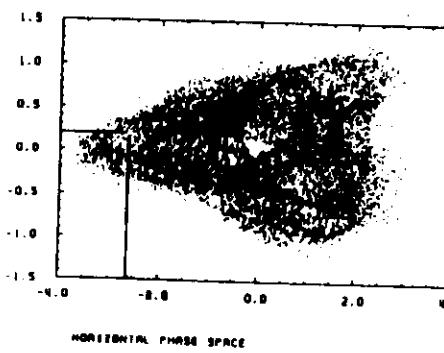
## 4-dimensional phase space



Projection onto  
the horizontal  
plane



increasing  
nonlinearities



→ Chaos

For systems with  $N > 2$ , degrees of freedom  
the stochastic layers are connected together  
and form the ARNOLD WEB

For an initial condition within the  
WEB, the chaotic motion on the  
WEB can carry the particle to  
large amplitudes

⇒ ARNOLD DIFFUSION

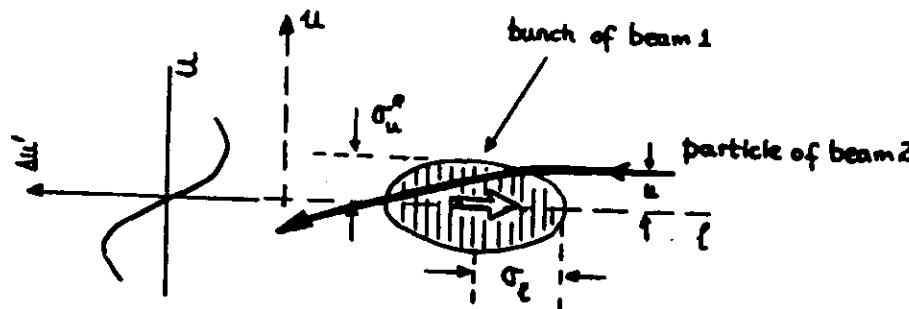
(Some) Collective Effects

So far → only single particle  
dynamics has been  
considered

BUT! Particle ensemble (bunch)  
as a whole acts via the environment  
(vacuum chamber) or directly  
on particles of the same bunch  
or particles in other bunches in  
the ring.

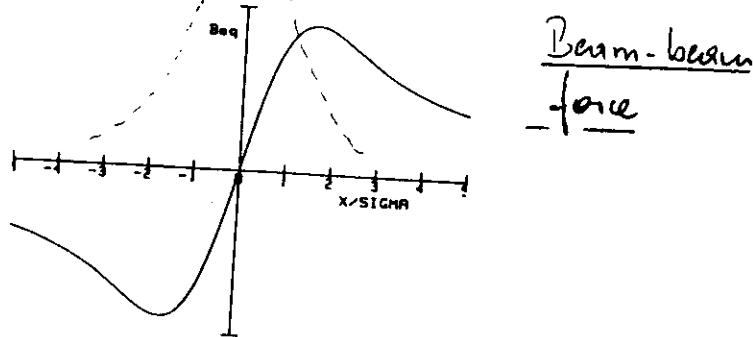
FORCE  $\sim$  Intensity, i.e. number  
of particles in the bunch

# ① Beam-beam effect in colliders



Particles experience a transverse deflecting force due to the charge of the colliding bunch  $\rightarrow$

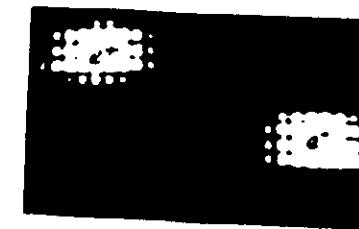
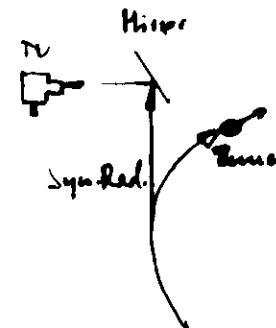
gaussian particle distribution!



For high intensities (number of particles per bunch) the beams blow up transversely  $\rightarrow$



beams separated



colliding beams

i.e. the Luminosity is decreased!

$$\text{Events/sec} \frac{dN}{dt} = L \cdot \sigma$$

Luminosity cross section

Low beta optics for high luminosity

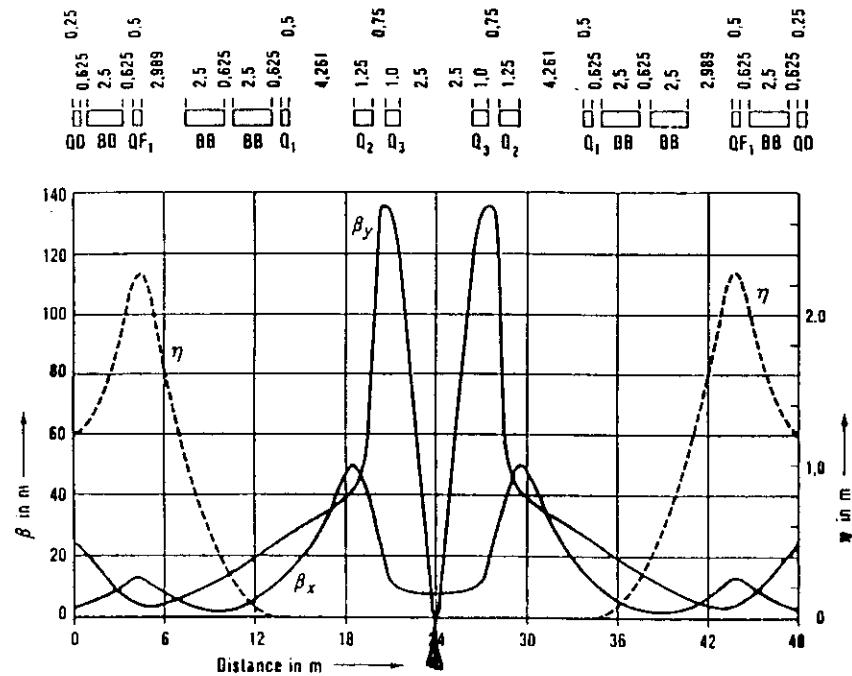


Fig. 3: Betatron functions  $\beta_x$ ,  $\beta_y$  (left scale) and momentum function  $\eta$



Interaction  
point

Luminosity is inversely proportional to beam cross section  $\rightarrow$

$$L = \frac{1}{4\pi e^2 f_0} \cdot \frac{I^+ I^-}{\sigma_x \sigma_z}$$

const.

needed:  
high current  
small beam size

Deflection kick due to the beam-beam force:

In  $e^-$ -ring, the unperturbed charge distribution is gaussian  $\rightarrow$

$$f(x, z, s) = \frac{N_B e}{2\pi^{3/2} \sigma_x \sigma_z \sigma_s} \exp \left\{ -\frac{x^2}{2\sigma_x^2} - \frac{z^2}{2\sigma_z^2} - \frac{s^2}{2\sigma_s^2} \right\}$$

$\sigma_x, \sigma_z, \sigma_s$  ... rms beam dimensions  
 $N_B$  ... particles per bunch

Electric potential:

$$V(x, z, s) = \frac{Ne}{4\pi^2 \epsilon_0} \int_0^\infty \frac{\exp \left\{ -\frac{x^2}{(2a^2+q)} - \frac{z^2}{(2b^2+q)} - \frac{s^2}{(2c^2+q)} \right\}}{\{(2a^2+q)(2b^2+q)(2c^2+q)\}^{1/2}} dq$$

Integrated transverse deflection  $\rightarrow$

$$\Delta \left( \frac{dz}{ds} \right) = \frac{e}{m_{oc} c^2} \int_{-\infty}^{+\infty} E_z ds = - \frac{e}{m_{oc} c^2} \int_{-\infty}^{+\infty} \frac{\partial V}{\partial z} ds$$

$\rightarrow$

$$\Delta z' = \frac{2N_r e}{\gamma} \frac{z}{\sqrt{\gamma}} \int_{-\infty}^{\infty} \int_0^\pi \frac{\exp \left\{ -\frac{x^2}{(2a^2+q)} - \frac{z^2}{(2b^2+q)} - \frac{s^2}{(2c^2+q)} \right\}}{(2a^2+q)^{1/2} (2b^2+q)^{1/2} (2c^2+q)^{1/2}} d\theta dq$$

↓ (Eckermann, Baschnib)

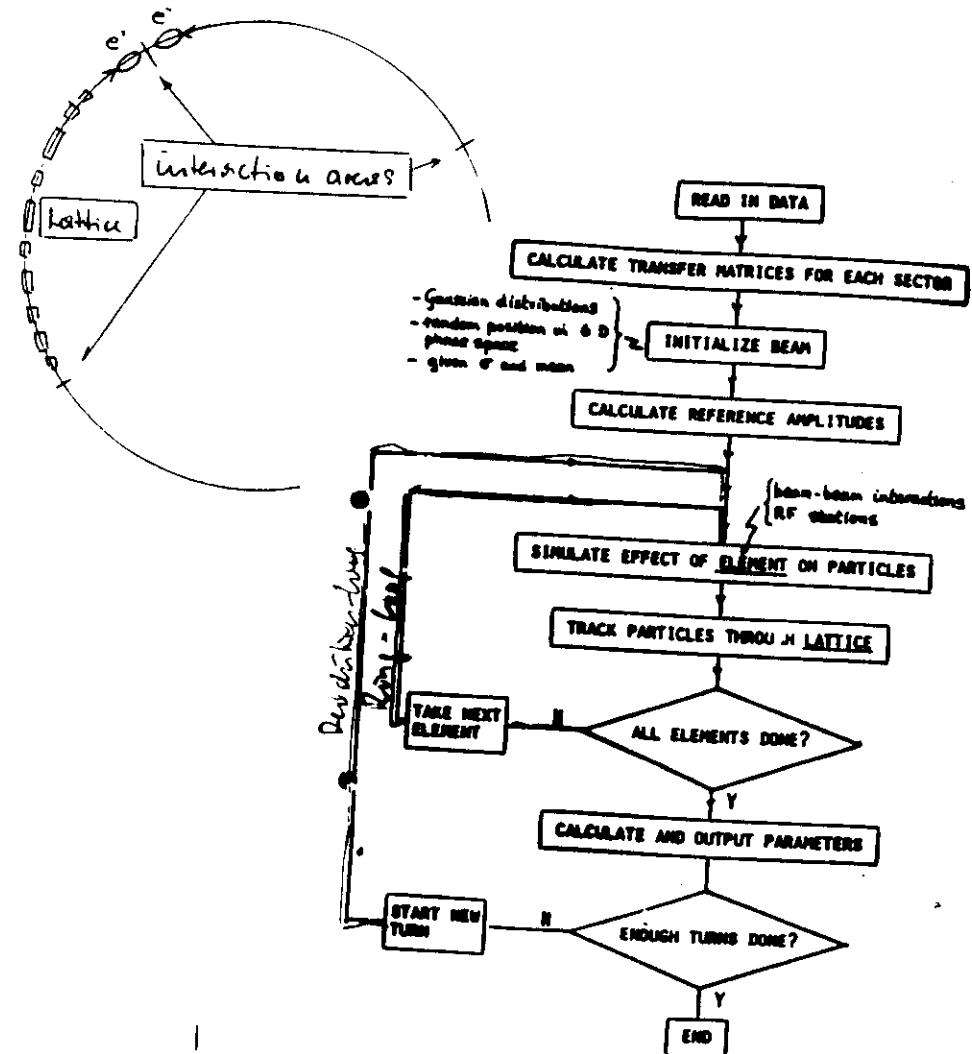
$$\boxed{a z' = \frac{N r_e}{\gamma} \sqrt{\frac{2\pi}{a^2-b^2}} R \left[ w \left( \frac{x+iz}{\sqrt{2(a^2-b^2)}} \right) - \exp \left\{ -\frac{x^2}{2a^2} - \frac{z^2}{2b^2} \right\} \right].}$$

$$w = \left( \frac{x \frac{b}{a} + iz \frac{a}{b}}{\sqrt{2(a^2-b^2)}} \right)$$

W... complex error function!

Brem - brems effect must be simulated, usually several hundred of particles are tracked over several thousands of turns.

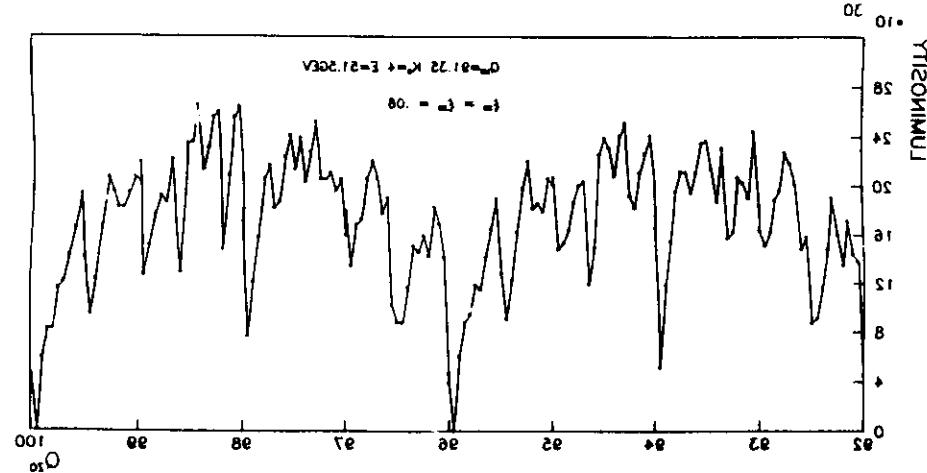
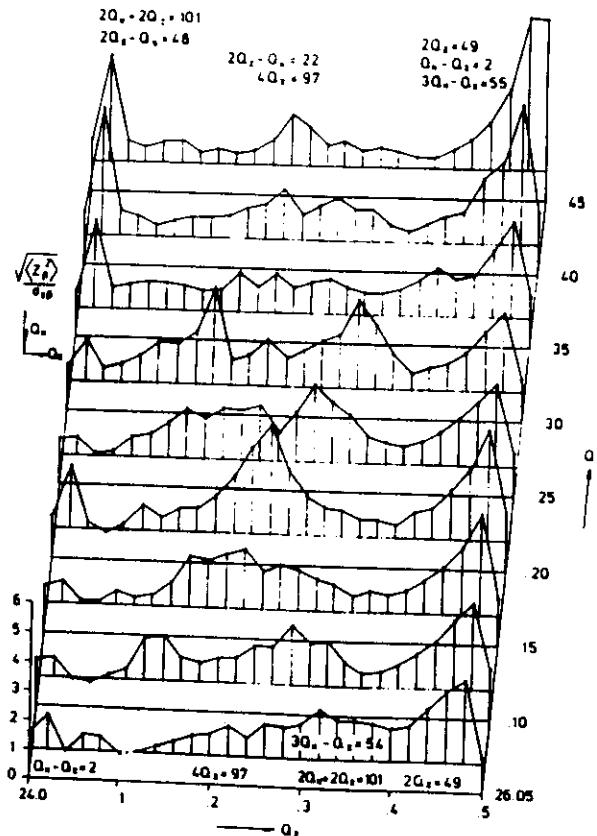
Principle of simulation:



Purpose of simulation  $\rightarrow$

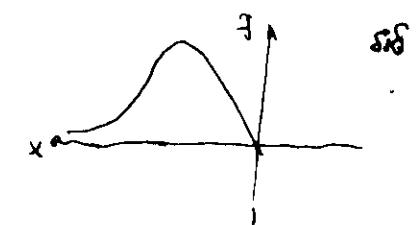
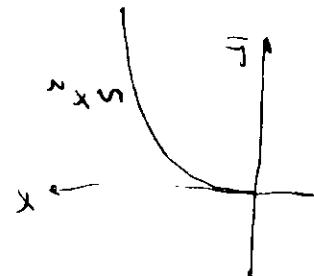
prediction of suitable working parameter  
for minimum beam-beam blow up:

simulations  $\rightarrow$  optimisation

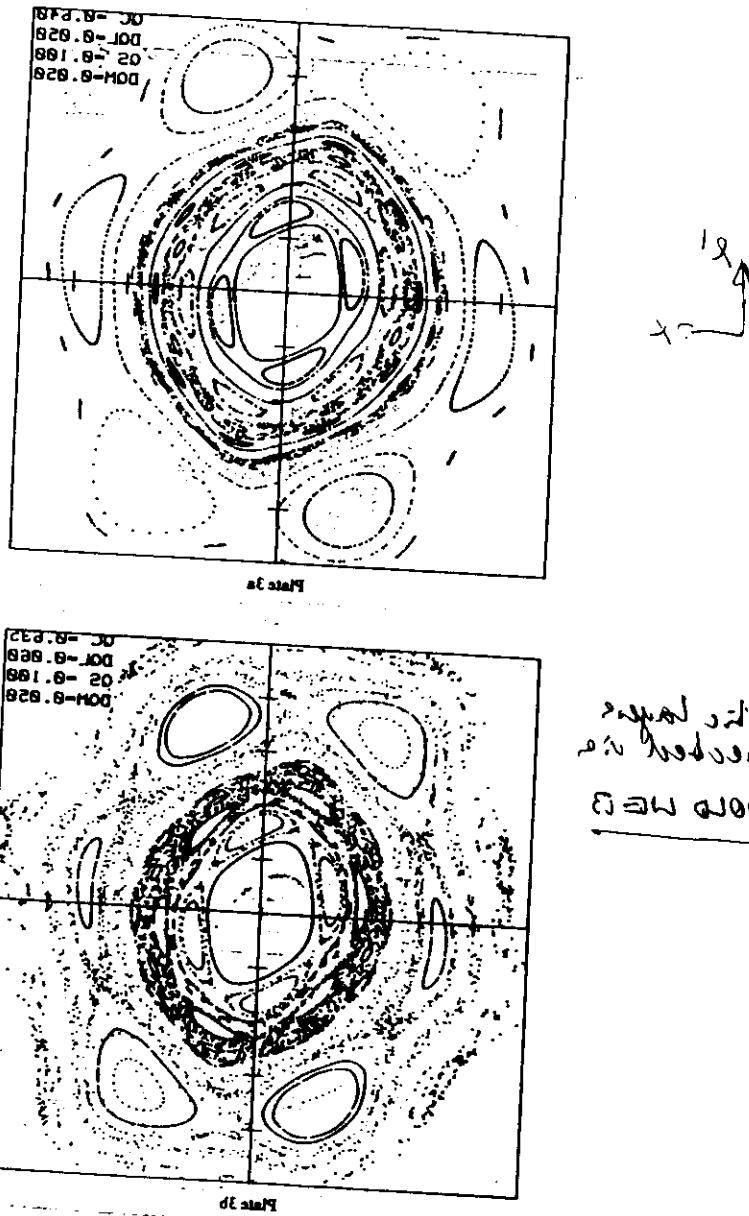


$\alpha \leftarrow x$  ref  $0 \leftarrow \bar{T}$  : refined search

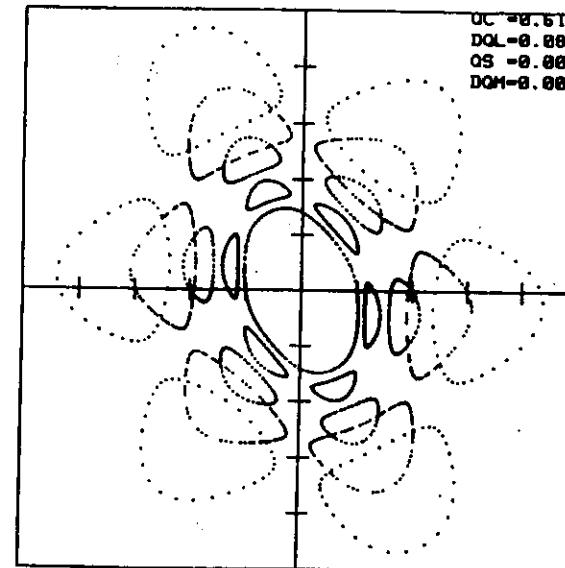
$\alpha \leftarrow x$  ref  $\alpha \leftarrow \bar{T}$  : new minimum found



: 0010001111111111

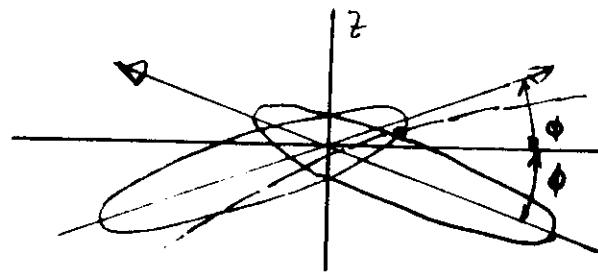


Phase space topology near a 6<sup>th</sup> order beam-beam resonance as the tune is changed:

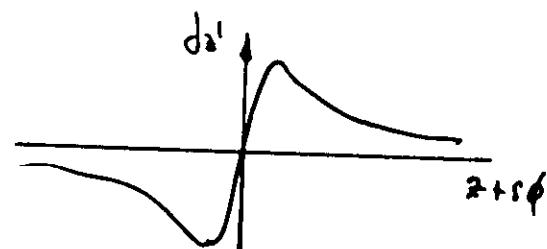


regular island disappears  
as tune approaches 6/3

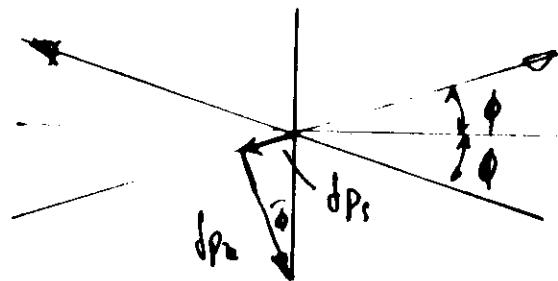
## Beam-beam interaction at crossing angle



Deflection :  $\frac{dz'}{ds} = f(z + s\phi)$



Energy change:



$$dp_z = \phi dp_{z_0}$$

$$\left[ \frac{dE}{E} \approx \frac{dp}{p} = \phi \frac{dp_z}{p_0} = \phi dz' = \phi f(z + s\phi) \right]$$

## COMPUTER SIMULATION

→ only with strong  
interactions Rutherford +  
+ Coulomb + Kicked

At the interaction point:

$$z_{n+1} = z_n$$

$$z'_{n+1} = z'_n + f(z_n + \phi s_n)$$

$$(\frac{dE}{E})_{n+1} = (\frac{dE}{E})_n + \phi f(z_n + \phi s_n)$$

$$s_{n+1} = s_n$$

Between interaction points:

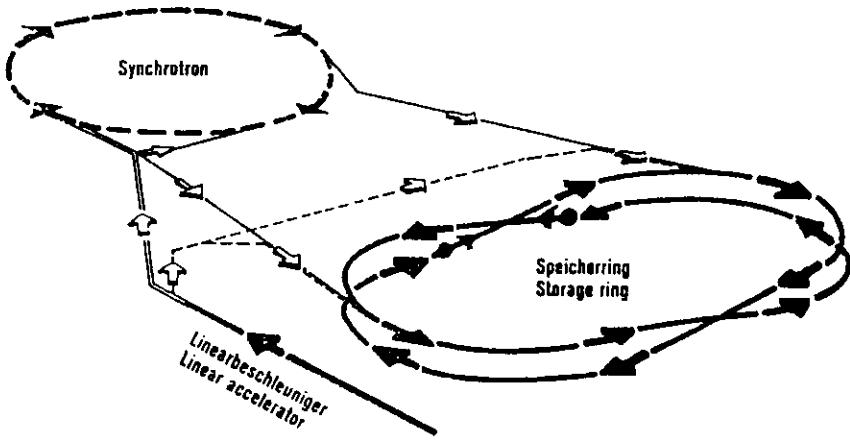
$$z_{n+2} = z_{n+1} \cos \phi + z'_n \sin \phi$$

$$z'_{n+2} = z_{n+1} \frac{\sin \phi}{\cos \phi} + z'_{n+1} \cos \phi$$

$$(\frac{dE}{E})_{n+2} = (\frac{dE}{E})_{n+1} + \frac{eU}{E} \left[ \sin(\psi_s + \frac{2\pi}{\lambda_{pp}} s_{n+1}) - \sin(\psi_s) \right]$$

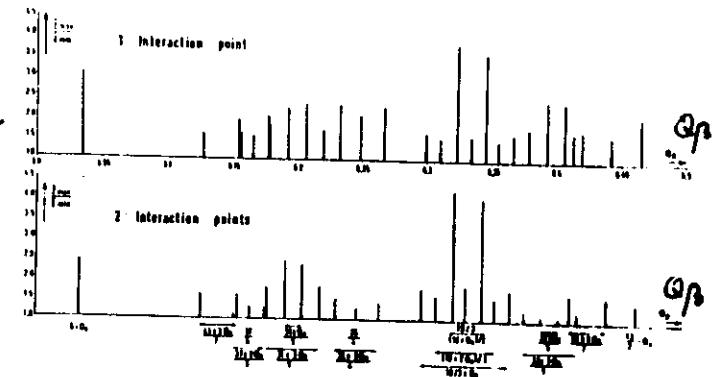
$$s_{n+2} = s_{n+1} - L_c \cdot C_0 (\frac{dE}{E})_{n+1}$$

## DOUBLE RING STORAGE



Resonances due to collision with crossing angle

interaction point

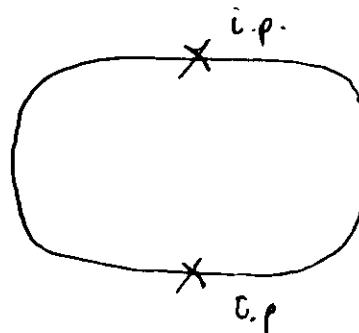


DORIS I:  $\alpha = 30 \text{ mrad}$  ... crossing angle

$\Rightarrow$  CURRENT LIMITING EFFECT

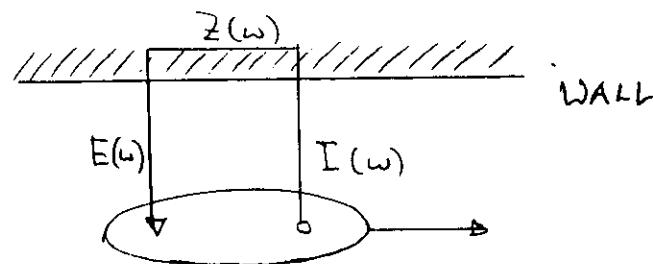
WITH COLLIDING BEAMS

SLC: 2 p-rings have also a small crossing angle



becomes separated during injection and ramping!

② Interaction of beam with environment



$$E_{\parallel} \sim Z_{\parallel} \cdot I_{\text{beam}} \rightarrow \text{takes energy out of the beam}$$

$$F_{\perp} \sim Z_{\perp} d_{\text{beam}} \rightarrow \text{deflects the beam}$$

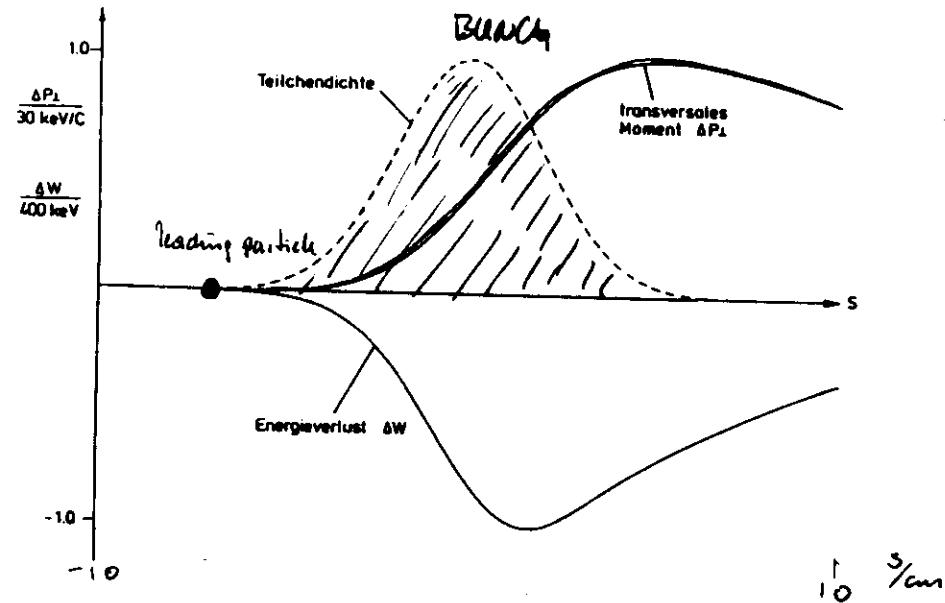
To evaluate the effect of the beam via the environment on itself  $\rightarrow$

Maxwell's equations must be solved with boundaries as given by the beam environment

Numerical solution of Maxwell's equation leads to

→ WAKE Potentials

→ inside a Gaussian bunch ( $\rho = 1 \mu\text{C}$ ,  $\sigma = 2 \text{ cm}$ ) after passage of a single cell 500 MHz cavity, 0.5 cm off axis

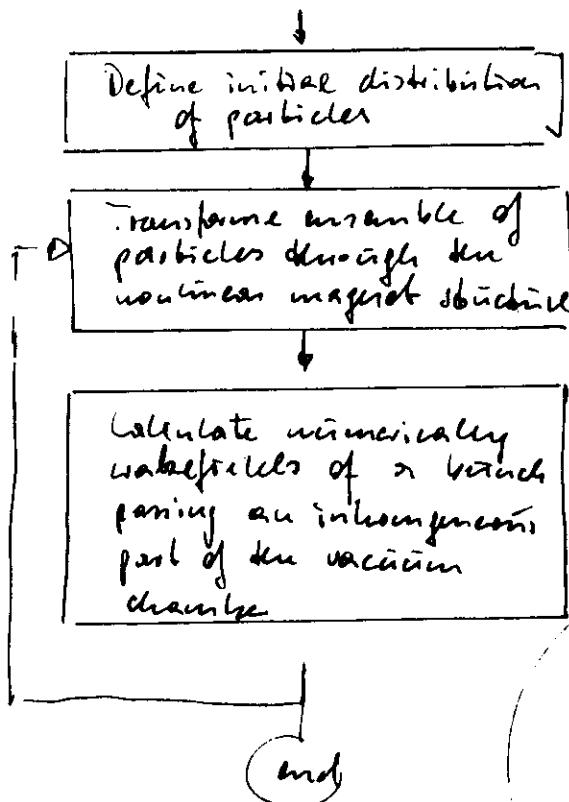


(ΔW → energy loss due to axis-symmetric (monopole fields))

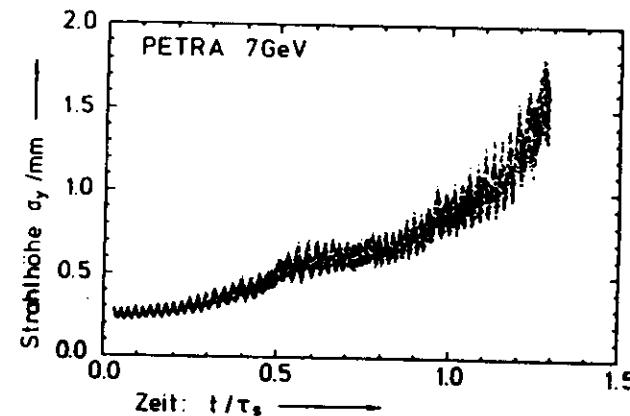
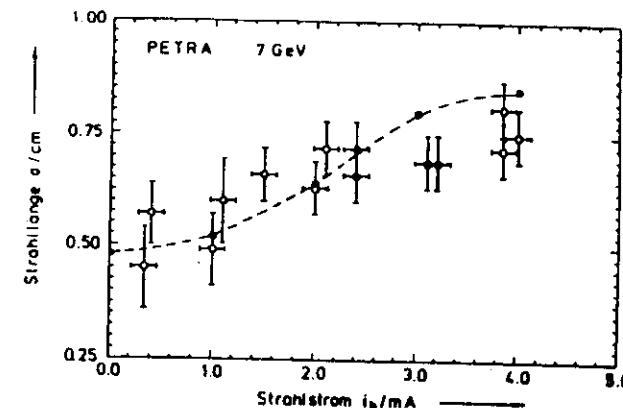
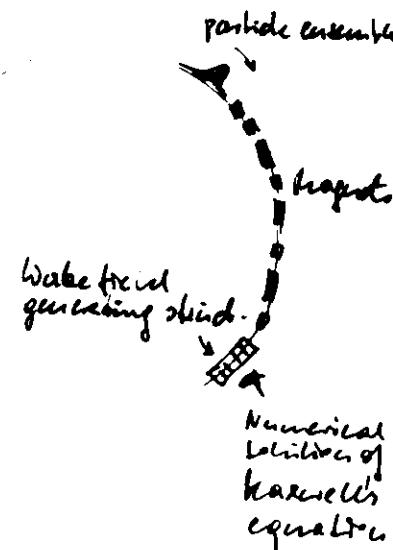
(w<sub>1</sub> → transverse change in momentum due to dipole fields)

Simulations have been made to include  
UHEZ fields in tracking codes: to  
simulate the FAST TRANSVERSE BLOCK UP

Principle of Simulation:



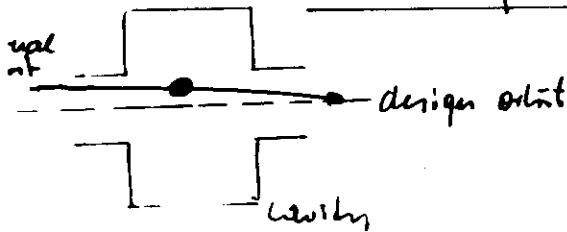
CIRCULAR ACCELERATOR.



SIMULATION OF FAST TRANSVERSE BLOCK UP !

Collective effect generating satellite resonance:

- needs a transverse field with a longitudinal gradient, which is produced by the BUNCH CURRENT in the accelerating structure due to displacement of the beam in the cavity



Transverse kick ( $\vec{z}$ ):

$$\delta z^1 = \frac{e}{\rho} \int (\bar{E}_z + v \bar{B}_x) dt$$

$$\delta z^1 = s \cdot \frac{e}{\rho} \int \left( \frac{\partial \bar{E}_z}{\partial t} + v \frac{\partial \bar{B}_x}{\partial t} \right) dt$$

$$\underline{\delta z^1 = A \cdot s}$$

linear in  $s$

Energy gain:

$$\frac{\delta E}{E} = \frac{e}{E} \int \bar{E}_z v dt$$

$$= 2 \frac{e}{E} \int \frac{\partial \bar{E}_z}{\partial t} v dt$$

$$\underline{\frac{\delta E}{E} = A \cdot s}$$

$$\nabla \times \vec{B} \cdot \frac{\partial \vec{B}}{\partial t}$$

! unequal!

In general the solution can only be found numerically →

### NUMERICAL SOLUTION OF MAXWELL'S EQUATION

$$\text{curl } \vec{E} = - \frac{\partial \vec{B}}{\partial t}$$

$$\text{curl } \vec{H} = \vec{j} + \frac{\partial \vec{D}}{\partial t} + \rho \vec{v}$$

$$\text{div } \vec{D} = \rho$$

$$\text{div } \vec{B} = 0$$

T. WEILAND

rewrite in integral representation →

$\vec{E}, \vec{H}$  ... fields  
 $\vec{D}, \vec{B}$  ... flux densities

$$\oint \vec{E} ds = - \iint_A \frac{\partial \vec{B}}{\partial t} d\vec{A}$$

(A)

$$\oint \vec{H} ds = \iint_A \left( \vec{j} + \frac{\partial \vec{D}}{\partial t} + \rho \vec{v} \right) d\vec{A}$$

(A)

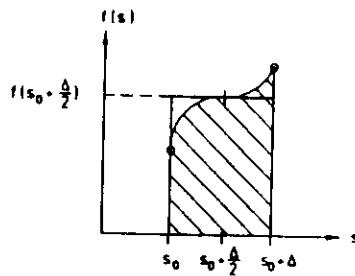
$$\iint_A \vec{B} d\vec{A} = 0$$

(V)

$$\iint_A \left( \frac{\partial \vec{D}}{\partial t} + \vec{j} \right) d\vec{A} = 0$$

(V)

Integral approximation in lowest order:

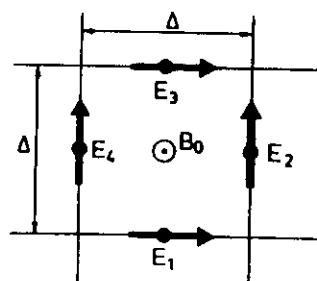


$$\int_{s_0}^{s_0 + \Delta} f(s) ds = \Delta \cdot f\left(s_0 + \frac{\Delta}{2}\right) + O(\Delta^2)$$

gives for e.g.  $\rightarrow$

$$\int_A \vec{E} ds = - \int_A \frac{\partial \vec{B}}{\partial t} d\vec{A} \Rightarrow$$

$$\Delta(E_1 + E_2 - E_3 - E_4) = \dot{B}_0 \cdot \Delta^2$$



2nd Maxwell equation  $\rightarrow$

$$\oint \vec{f} ds = \iint_A (\frac{\partial D}{\partial t} + \vec{j} \cdot \vec{v}) d\vec{A}$$

$\rightarrow$

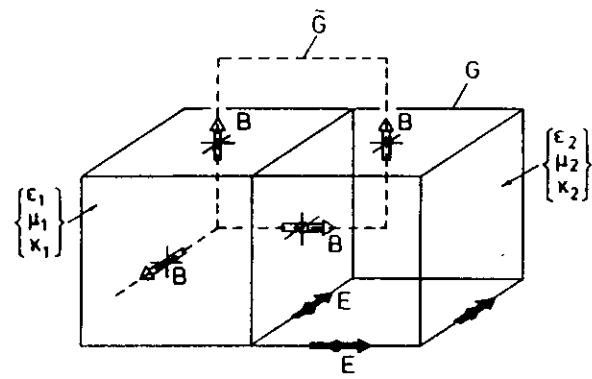
$$\frac{1}{\mu} (B_1 + B_2 + B_3 + B_4) = \Delta^2 (\epsilon E_0 + \gamma E_0 + V_0 \beta)$$

$$\begin{array}{ll} \vec{D} = \epsilon \vec{E} & \epsilon \text{ permittivity} \\ \vec{B} = \mu \vec{H} & \mu \text{ permeability} \\ \vec{j} = \gamma \vec{E} & \gamma \text{ conductivity} \end{array}$$

(here  $\epsilon, \mu, \gamma = \text{constant!}$ )

The choice of a DUAL GRID implicitly satisfy Maxwell's Equation 3 and 4.

DUAL MESH  $\rightarrow$

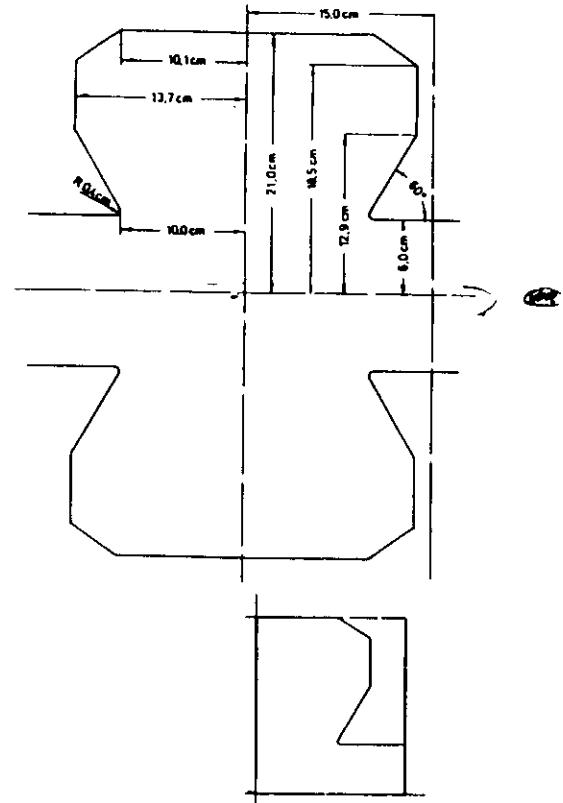


With time discretization we get for  
the traxsects equations in the  
mesh  $\rightarrow$

$$B_o(t=T + \frac{\Delta t}{2}) - B_o(t=T - \frac{\Delta t}{2}) = \frac{\Delta t}{\mu_e} (\bar{E}_1 + \bar{E}_2 - \bar{E}_3 - \bar{E}_4) (t=T)$$

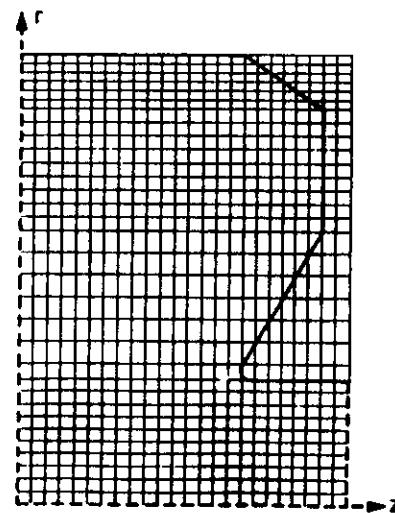
$$\bar{E}_o(t=T + \Delta t) - \bar{E}_o(t=T) + \frac{1}{\mu_e} \frac{\Delta t}{\Delta} (B_1 + B_2 - B_3 - B_4) (t=T + \frac{\Delta t}{2})$$

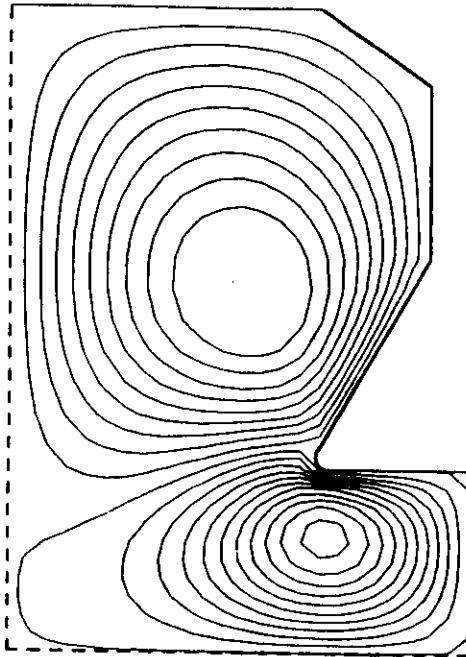
(here  $\bar{r}, \bar{s} = 0$ )



Mesh generation!

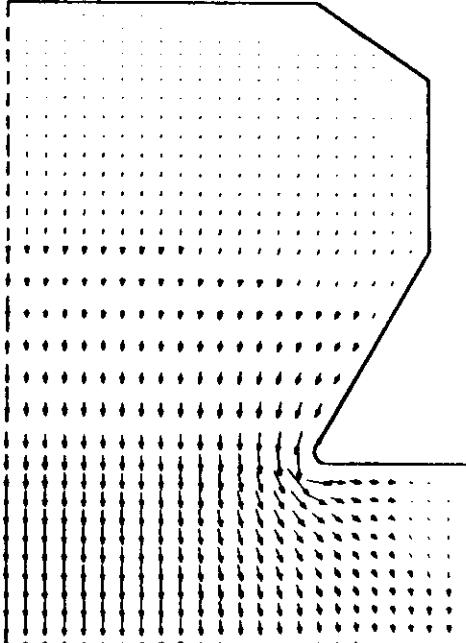
Dynamic Mesh  
for cavity





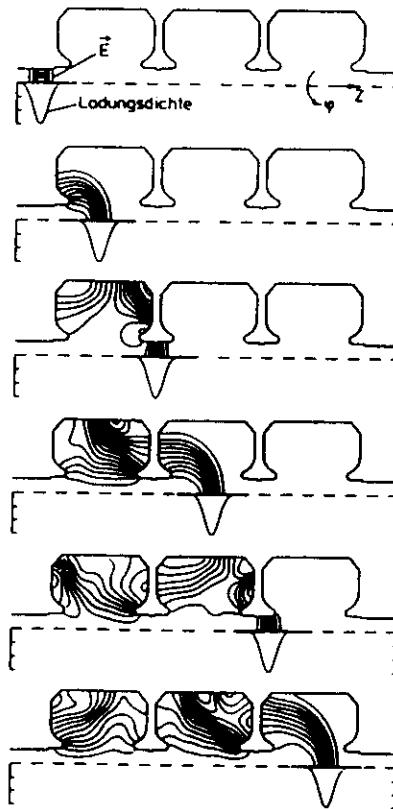
Contours plot  
 $rE_y$  (at  $\theta = 90^\circ$ )

- for the lowest dipole mode in a 500 MHz PETRA cavity



Magnetic field (at  $\theta = 90^\circ$ )  
of the lowest dipole mode in a 500 MHz PETRA cavity

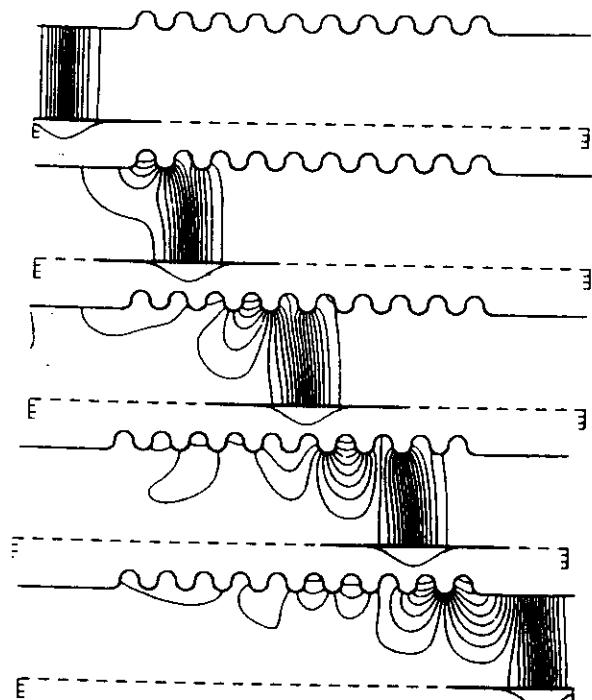
## WAVEFIELDS DUE TO MOVING CHARGES



Bunch passing  
a 3-cell  
accelerating structure

T. WEILAND

A  
leads to coupled bunch instabilities  
→ dangerous for Radiation Sources !!



Electromagnetic field of a Gaussian bunch of charged particles traversing a baffle.

→ they must be shielded!

To find the modes of a cavity,  
Maxwell's equations can be solved  
in frequency domain:

$$\frac{d}{dt} \rightarrow i\omega$$

(SUPERFISH)

$$\nabla \times \vec{H} = k \vec{E} \quad \nabla \times \vec{E} = -k \vec{H} \quad \left. \right\} \rightarrow \boxed{\nabla \times (\nabla \times \vec{H}) = k^2 \vec{H}}$$

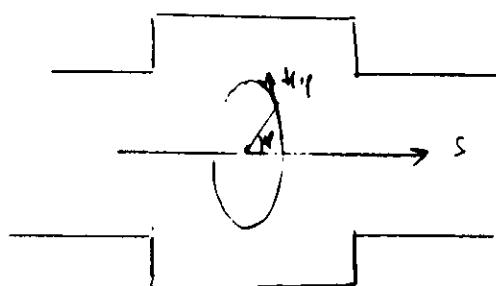
$$k = \frac{\omega}{c}$$

Difference equations

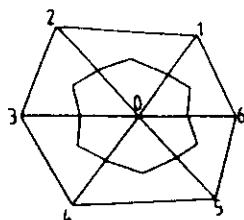
$$\int \nabla \times (\nabla \times \vec{H}) d\vec{A} = k^2 \int \vec{H} d\vec{A}$$

For objects with cylindrical symmetry  
the only nonvanishing component is

$$d(\phi)$$



## Triangular MESH:



## 3-dimensional field calculation ( MAFIA )

Mesh generator  
for Torus →

Assuming:  $H_q$  = linear inside each triangle  $\Rightarrow$

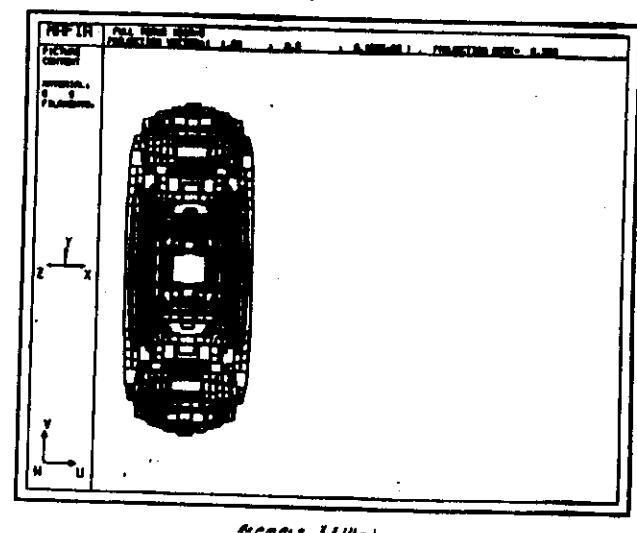
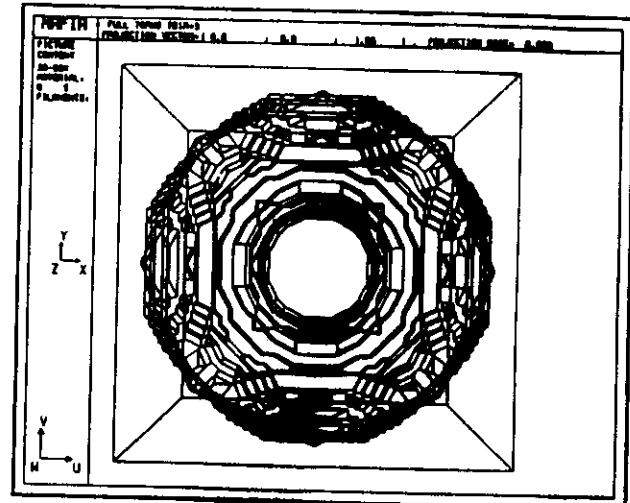
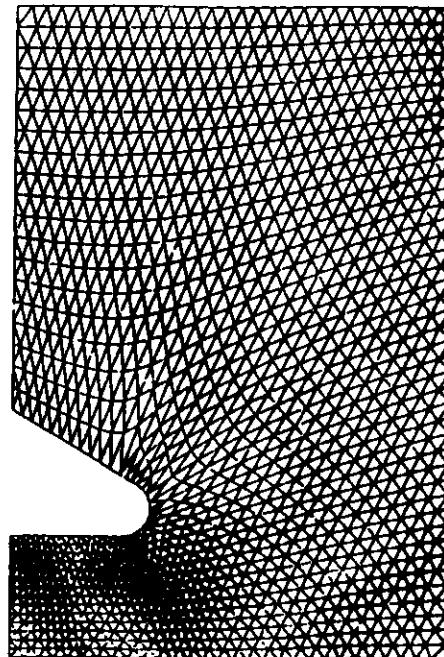
$H_q$  is uniquely determined everywhere in the triangle by its values at the corners.

Equation for each  
interior mesh point:

$$\sum_{u=0}^6 H_{qn} (a_u + b_u^2 b_n) = 0$$

$a_n, b_n \dots$  depend on meshpoint  
coordinates only

triangular mesh for  
cavity →

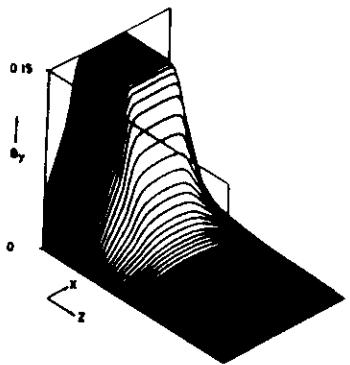
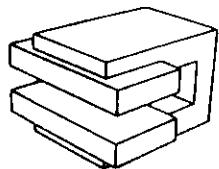


Conduction dipole magnet field (vertical)  
in the midplane

(Pgm. PROF1)

W.R. NOVENDORF

W.R. NOVENDORF



Median plane field!

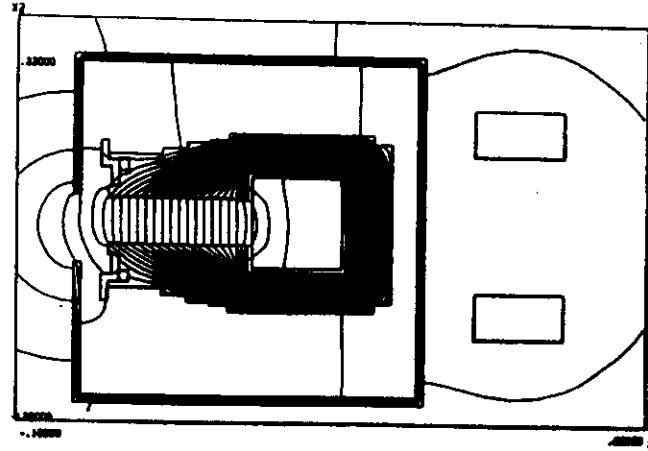


Fig. 3.6. HERA  $e^-$  arc bending magnet

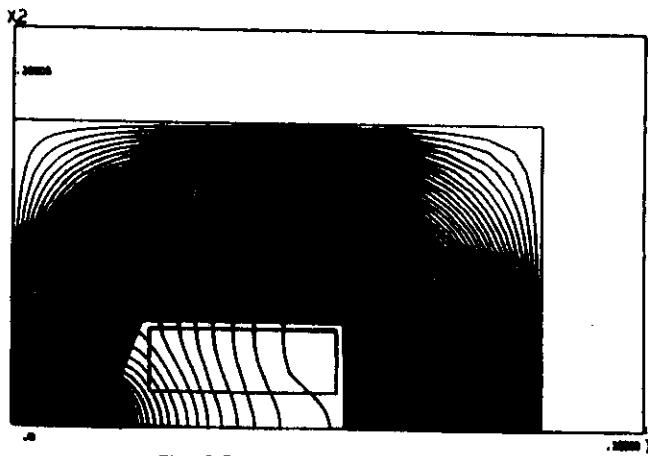


Fig. 3.7. HERA injection magnet