



## THE PALAIS-SMALE CONDITION VERSUS COERCIVITY

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### The Palais-Smale Condition Versus Coercivity

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### 1. Introduction

Given a functional  $\varphi : X \rightarrow \mathbb{R}$  on a Banach space  $X$ ,  $\varphi$  is said to be coercive if  $\varphi(u) \rightarrow +\infty$  as  $\|u\| \rightarrow \infty$ . This is equivalent to saying that, for every  $d \in \mathbb{R}$ , the set

$$\varphi^d = \{u \in X \mid \varphi(u) \leq d\}$$

is bounded. On the other hand, a (Fréchet) differentiable functional  $\varphi : X \rightarrow \mathbb{R}$  is said to satisfy the Palais-Smale condition at the level  $d \in \mathbb{R}$ ,  $(PS)_d$ , if any sequence  $\{u_n\} \subset X$  such that

$$\begin{cases} \varphi(u_n) \rightarrow d \\ \|\varphi'(u_n)\|_{X^*} \rightarrow 0 \end{cases}$$

possesses a convergent subsequence; and  $\varphi$  is said to satisfy  $(PS)$  if it satisfies  $(PS)_d$  for every  $d \in \mathbb{R}$ .

Recently, among other results in critical point theory, Shujie [11] showed that if a  $C^1$  functional  $\varphi : X \rightarrow \mathbb{R}$  is bounded from below and satisfies the condition  $(PS)$  then  $\varphi$  is coercive. Shujie's proof uses a "gradient flow" approach, through the so-called "deformation theorem" (cf. [3,10]) and, for that, he needs the notion of a pseudo-gradient vector field  $v$  associated with the functional  $\varphi$  (whose existence is guaranteed for  $C^1$  functionals by Palais [8]).

In this note we present some new results which relate the Palais-Smale condition and the notion of coercivity, and are all based on the well-known Variational Principle due to Ekeland

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[5,6]. In particular, a new proof of the above mentioned result of Shujie is given. It should be pointed out that, throughout the paper, the given functional  $\varphi$  could be assumed to be only Gateaux differentiable, rather than  $C^1$ . And, in addition to being conceptually simpler, this approach could be used in more general situations where the functional is not even differentiable (cf. [4]). The strong form of Ekeland's Variational Principle, to be repeatedly used in the sequel, is the following

**Theorem 0.** Let  $M$  be a complete metric space and  $\theta : M \rightarrow \mathbb{R} \cup \{+\infty\}$ ,  $\theta \not\equiv +\infty$ , a lower semicontinuous function which is bounded from below, say  $a = \inf_M \theta$ . Let  $\varepsilon > 0$  be given and  $\tilde{u} \in M$  be such that

$$\theta(\tilde{u}) \leq a + \varepsilon.$$

Then, for any  $\lambda > 0$ , there exists  $u_\lambda \in M$  such that

- (i)  $\theta(u_\lambda) \leq \theta(\tilde{u})$
- (ii)  $\theta(u_\lambda) < \theta(u) + \frac{\varepsilon}{\lambda} d(u, u_\lambda) \quad \forall u \neq u_\lambda$
- (iii)  $d(u_\lambda, \tilde{u}) \leq \lambda$

**Remark.** Note that the special choice  $\lambda = \sqrt{\varepsilon}$  gives  $d(u_\lambda, \tilde{u}) \leq \sqrt{\varepsilon}$  and  $\theta(u_\lambda) < \theta(u) + \sqrt{\varepsilon} d(u, u_\lambda) \quad \forall u \neq u_\lambda$ . Also note that, when  $M = X$  is a Banach space and  $\theta : X \rightarrow \mathbb{R}$  is Gateaux differentiable, by taking  $u = u_\lambda + th$ ,  $h \in X$ , in (ii) and letting  $t \rightarrow 0$ , one obtains  $\|\theta'(u_\lambda)\|_{X^*} \leq \varepsilon/\lambda$ .

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## 2. Main Results

We start with a preliminary result which, although not directly needed for the main the-

orem, it typically illustrates our approach and shows how Ekeland's Principle comes naturally into scene.

**Proposition 1.** Let  $\varphi \in C^1(X, \mathbb{R})$  be bounded from below, say  $a = \inf_X \varphi$ . If  $\varphi$  satisfies  $(PS)_a$  then the set  $\varphi^{a+\alpha}$  is bounded, for some  $\alpha > 0$ .

**Proof.** Suppose, by contradiction, that  $\varphi^{a+\alpha}$  is unbounded for all  $\alpha > 0$ . Then, there exist  $\{\tilde{u}_n\} \subset X$  such that

$$\begin{cases} a \leq \varphi(\tilde{u}_n) \leq a + \frac{1}{n} \\ \|\tilde{u}_n\| \geq n, \end{cases}$$

and Theorem 0 (with  $\varepsilon = 1/n$ ,  $\lambda = 1/\sqrt{n}$ ) implies the existence of  $\{u_n\} \subset X$  satisfying

- (i)  $a \leq \varphi(u_n) \leq \varphi(\tilde{u}_n) \leq a + \frac{1}{n}$
- (ii)  $\varphi(u_n) \leq \varphi(u) + \frac{1}{\sqrt{n}} \|u - u_n\| \quad \forall u \in X$
- (iii)  $\|u_n - \tilde{u}_n\| \leq \frac{1}{\sqrt{n}}$ .

We reach a contradiction with  $(PS)_a$ , since (1)(i)-(iii) give, respectively,

$$\begin{cases} \varphi(u_n) \rightarrow a \\ \|\varphi'(u_n)\|_{X^*} \leq \frac{1}{\sqrt{n}} \rightarrow 0 \\ \|u_n\| \geq n - \frac{1}{\sqrt{n}} \rightarrow \infty. \quad \blacksquare \end{cases}$$

A similar result, which is slightly more general is the following.

**Proposition 2.** Let  $\varphi \in C^1(X, \mathbb{R})$  and  $c \in \mathbb{R}$  be such that  $\varphi^d$  is unbounded for  $d > c$  and  $\varphi^d$  is bounded for  $d < c$ . Then, there exists  $\{u_n\} \subset X$  such that

- (i)  $\varphi(u_n) \rightarrow c$
- (ii)  $\|\varphi'(u_n)\|_{X^*} \rightarrow 0$
- (iii)  $\|u_n\| \rightarrow \infty$ .

**Proof.** In view of the hypotheses, for any given  $n \in \mathbb{N}$ , there exists  $R_n \geq n$  such that

$$(3) \quad \varphi^{c-\frac{1}{n}} \subset B_{R_n}(0).$$

Define  $M_n = X \setminus B_{R_n}$ ,  $\theta_n = \varphi|_{M_n} : M_n \rightarrow \mathbb{R}$  and note that

$$(4) \quad c_n \equiv \inf_{M_n} \theta_n \geq c - \frac{1}{n}$$

in view of (3). Now, from the unboundedness of  $\varphi^{c+\frac{1}{n}}$ , we can pick  $\hat{u}_n \in X$  satisfying

$$(5) \quad \varphi(\hat{u}_n) \leq c + \frac{1}{n},$$

$$(6) \quad \|\hat{u}_n\| \geq R_n + 1 + \frac{1}{\sqrt{n}},$$

so that, in fact, we have  $\hat{u}_n \in M_n$  and, from (4), (5),

$$(7) \quad \varphi(\hat{u}_n) \leq c + \frac{1}{n} \leq c_n + \frac{2}{n}.$$

Now, applying Theorem 0 (with  $\varepsilon = 2/n$ ,  $\lambda = 1/\sqrt{n}$ ) we obtain  $u_n \in M_n$  satisfying

$$(8) \quad \begin{aligned} & \text{(i) } c - \frac{1}{n} \leq c_n \leq \varphi(u_n) \leq \varphi(\hat{u}_n) \leq c + \frac{1}{n} \leq c_n + \frac{2}{n} \\ & \text{(ii) } \varphi(u_n) \leq \varphi(u) + \frac{2}{\sqrt{n}} \|u - u_n\| \forall u \in M_n \\ & \text{(iii) } \|u_n - \hat{u}_n\| \leq \frac{1}{\sqrt{n}} \end{aligned}$$

In particular, (6) and (8) (iii) imply

$$(9) \quad \|u_n\| \geq R_n + 1,$$

so that  $u_n$  belongs to the interior of  $M_n$  and (8) (ii) gives

$$(10) \quad \|\varphi'(u_n)\|_{X^*} \leq \frac{2}{\sqrt{n}}$$

Therefore, (8)(i), (10) and (9) provide (2)(i), (ii) and (iii) respectively. The proof is complete. ■

**Corollary 3.** Let  $\varphi \in C^1(X, \mathbb{R})$  satisfy  $(PS)_c$ . If  $\varphi^d$  is bounded for every  $d < c$  then  $\varphi^{c+\gamma}$  is also bounded, for some  $\gamma > 0$ .

**Remarks 1)** In particular, it follows from Corollary 3 that  $\varphi^c$  is bounded.

2) The conclusion of Corollary 3 holds whenever  $\varphi^c$  is bounded.

3) Notice that the above Corollary generalizes Proposition 1. Also, it is clear from Proposition 2 that this Corollary holds for  $\varphi$  satisfying a condition weaker than  $(PS)_c$ , namely  $(\widehat{PS})_c$ : whenever  $\{u_n\} \subset X$  is a sequence verifying (2)(i), (ii), then  $\{u_n\}$  must have a bounded subsequence

As another consequence of Proposition 2 we have the following.

**Theorem 4.** Let  $\varphi \in C^1(X, \mathbb{R})$  be bounded from below. If  $\varphi$  is not coercive then  $\varphi$  does not satisfy  $(PS)_{c_0}$ , where

$$c_0 = \sup\{d \in \mathbb{R} \mid \varphi^d \text{ is bounded}\}.$$

**Proof.** Let  $C = \{d \in \mathbb{R} \mid \varphi^d \text{ is bounded}\}$ . Since  $\varphi$  is bounded from below, we have  $C \supset (-\infty, a)$  where  $a = \inf_X \varphi$ , hence  $C$  is nonempty. If we define

$$c_0 = \sup C$$

then  $c_0 < +\infty$  since  $\varphi$  is not coercive. And, by definition, it follows that  $\varphi^d$  is unbounded for  $d > c_0$ . So, Proposition 2 implies the result. ■

**Corollary 5.** [11] If  $\varphi \in C^1(X, \mathbb{R})$  is bounded from below and satisfies  $(PS)$  (that is,  $(PS)_c$  for every  $c \in \mathbb{R}$ ) then  $\varphi$  is coercive.

**Remarks 4)** Notice that we could also characterize  $c_0 = \sup C$  defined above as

$$c_0 = \inf \{d \in \mathbb{R} \mid \varphi^d \text{ is unbounded}\}.$$

5) In general, for any functional  $\varphi : X \rightarrow \mathbb{R}$ , the set  $C = \{d \in \mathbb{R} \mid \varphi^d \text{ is bounded}\}$  is a (left) half-line, either open or closed, and we may have  $C = \emptyset$  or  $C = \mathbb{R}$  the latter case occurring if and only if  $\varphi$  is coercive. And the assumption of  $\varphi$  being bounded from below in Theorem 4 was used only to show that  $C \neq \emptyset$ . Therefore, in that theorem (cf. also next section), one could assume more generally that  $\varphi^d$  is bounded, for some  $d \in \mathbb{R}$ . Of course, for typical situations in differential equations, where  $\varphi$  takes bounded sets into bounded sets, the assumption  $C \neq \emptyset$  is equivalent to  $\varphi$  being bounded from below.

6) Suppose that the set  $D = \{d \in \mathbb{R} \mid \varphi \text{ satisfies } (PS)_d\}$  is nonempty. Unlike the set  $C$ , it is easy to see that  $D$  is not necessarily a half-line, even in the case that  $\varphi$  is bounded from below, for which  $D \supset (-\infty, \inf_X \varphi)$ . However, if  $X$  is a reflexive Banach space,  $X^*$  is strictly convex and  $\varphi \in C^1(X, \mathbb{R})$  is such that  $\varphi' = J - K$ , with  $J : X \rightarrow X^*$  the duality mapping and  $K : X \rightarrow X^*$  a compact mapping, then it is not hard to show that  $c_0 = \sup C$  coincides with the number

$$\begin{aligned} \hat{c}_0 &= \sup \{d \in \mathbb{R} \mid \varphi \text{ satisfies } (PS)_c \text{ for every } c \leq d\} \\ &= \inf \{d \in \mathbb{R} \mid \varphi \text{ does not satisfy } (PS)_d\} \end{aligned}$$

The following example of a  $\varphi \in C^1(\mathbb{R}, \mathbb{R})$  is illustrative, where  $C = (-\infty, 0) = \{d \in \mathbb{R} \mid \varphi \text{ satisfies } (PS)_c \forall c \leq d\}$ ,  $\{d \in \mathbb{R} \mid \varphi \text{ does not satisfy } (PS)_d\} = \{0, \frac{1}{2}\}$  and  $c_0 = \hat{c}_0 = 0$ :

$$\varphi(t) = \begin{cases} \sin t, & -\frac{\pi}{2} \leq t \leq \frac{\pi}{2} \\ \frac{1}{2} \left[ 1 + e^{-(t-\frac{\pi}{2})^2} \right], & t \geq \frac{\pi}{2} \\ -e^{-(t+\frac{\pi}{2})^2}, & t \leq -\frac{\pi}{2} \end{cases}$$

7) Finally, it should be remarked that, in fact, Proposition 2 suggests the weaker Palais-Smale type condition  $(\widehat{PS})_c$  defined in Remark 3) as the natural one to relate to

coercivity, in the sense that a converse to Corollary 3 also holds (trivially) true. More precisely, let  $\varphi \in C^1(X, \mathbb{R})$  be such that  $\varphi^d$  is bounded for every  $d < c$ . Then,  $\varphi$  satisfies  $(\widehat{PS})_c$  if and only if  $\varphi^{c+\gamma}$  is bounded, for some  $\gamma > 0$ .

In particular, considering the set  $\hat{D} = \{d \in \mathbb{R} \mid \varphi \text{ satisfies } (\widehat{PS})_d\}$ , it is easy to see that:

(i)  $C = \mathbb{R} \implies \hat{D} = \mathbb{R}$ ; (ii)  $C = (-\infty, c_0)$  or  $C = (-\infty, c_0] \implies \hat{D} = (-\infty, c_0) \cup \hat{D}$ , where  $(-\infty, c_0)$  is a component of  $\hat{D}$  (that is,  $\varphi$  does not satisfy  $(\widehat{PS})_{c_0}$ )

### 3. Some Extensions and a Resonant Problem

Given a vector  $e \in \partial B_1(0)$  and a decomposition  $X = \langle e \rangle \oplus W$ , we shall hereafter write  $u \in X$  as  $u = te + w$ , where  $w \in W$ . And a set  $S \subset X$  will be said to be  $e$ -bounded if

$$S \subset \{u = te + w \mid t < R, w \in W\} \equiv H_R$$

for some  $R \in \mathbb{R}$ . Also, a functional  $\varphi : X \rightarrow \mathbb{R}$  will be called  $e$ -coercive if

$$\varphi(te + w) \rightarrow +\infty \quad \text{as} \quad t \rightarrow +\infty,$$

uniformly for  $w \in W$ . And  $\varphi$  will be called  $e$ -bounded from below if there exists  $a \in \mathbb{R}$  such that  $\varphi^a$  is  $e$ -bounded.

In this section we shall extend our previous results to include situations where  $\varphi$  is not necessarily bounded from below. In fact, it is not hard to check that results which are similar to Proposition 1 through Corollary 5 hold true in this more general setting, with the words "bounded", "bounded from below" and "coercive" being replaced by " $e$ -bounded", " $e$ -bounded from below" and " $e$ -coercive", respectively. As illustrations, we shall state the analogues of Proposition 2 and Corollary 5 and prove the former.

**Proposition 2e.** Let  $\varphi \in C^1(X, \mathbb{R})$  and  $c \in \mathbb{R}$  be such that  $\varphi^d$  is not  $e$ -bounded for  $d > c$  and  $\varphi^d$  is  $e$ -bounded for  $d < c$ . Then, there exists  $\{u_n\} = \{t_n e + w_n\} \subset X$  such that

$$(11) \quad \begin{aligned} & \text{(i)} \quad \varphi(u_n) \longrightarrow c \\ & \text{(ii)} \quad \|\varphi'(u_n)\|_{X^*} \longrightarrow 0 \\ & \text{(iii)} \quad t_n \longrightarrow +\infty. \end{aligned}$$

**Corollary 5e.** If  $\varphi \in C^1(X, \mathbb{R})$  is  $\epsilon$ -bounded from below and satisfies (PS) then  $\varphi$  is  $\epsilon$ -coercive.

**Proof of Proposition 2e.** By the hypotheses, given  $n \in \mathbb{N}$ , there exists  $R_n \geq n$  such that

$$(12) \quad \varphi^{c-\frac{1}{n}} \subset H_{R_n} = \{u = te + w \mid t < R_n, w \in W\}.$$

Define  $M_n = X \setminus H_{R_n}$ ,  $\theta_n = \varphi|_{M_n}$  and note that (12) implies

$$(13) \quad c_n \equiv \inf_{M_n} \theta_n \geq c - \frac{1}{n}.$$

Since  $\varphi^{c+\frac{1}{n}}$  is not  $\epsilon$ -bounded, there exists  $\hat{u}_n = \hat{t}_n e + \hat{w}_n$  such that

$$(14) \quad \varphi(\hat{u}_n) \leq c + \frac{1}{n}$$

$$(15) \quad \hat{t}_n \geq R_n + 1 + \frac{1}{\sqrt{n}},$$

hence  $\hat{u}_n \in M_n$  and, from (13), (14), we obtain

$$(16) \quad \varphi(\hat{u}_n) \leq c + \frac{1}{n} \leq c_n + \frac{2}{n}.$$

Now, Theorem 0 (with  $\epsilon = 2/n$ ,  $\lambda = 1/\sqrt{n}$ ) gives  $u_n = t_n e + w_n \in M_n$  satisfying

$$(17) \quad \begin{aligned} & \text{(i)} \quad c - \frac{1}{n} \leq c_n \leq \varphi(u_n) \leq \varphi(\hat{u}_n) \leq c + \frac{1}{n} \leq c_n + \frac{2}{n} \\ & \text{(ii)} \quad \varphi'(u_n) \leq \varphi'(u) + \frac{2}{\sqrt{n}} \|u - u_n\| \quad \forall u \in M_n \\ & \text{(iii)} \quad \|u_n - \hat{u}_n\| \leq \frac{1}{\sqrt{n}}. \end{aligned}$$

From the continuity of the projection  $P : X \rightarrow \langle e \rangle$  along  $W$  (say  $\|P\| = 1$  without loss of generality), we obtain  $|t_n - \hat{t}_n| \leq 1/\sqrt{n}$  and then, in view of (15),

$$(18) \quad t_n \geq R_n + 1.$$

This shows that  $u_n = t_n e + w_n$  belongs to the interior of  $M_n$ , hence

$$(19) \quad \|\varphi'(u_n)\|_{X^*} \leq \frac{2}{\sqrt{n}}$$

in view of (17)(ii). The proof is complete since (17)(i), (19), (18) imply (11)(i), (ii), (iii), respectively. ■

We now present an example of a resonant problem whose corresponding functional  $\varphi$  is  $\epsilon$ -bounded from below but is not bounded. Moreover,  $\varphi$  will be shown to satisfy the hypotheses of Proposition 2e with  $c = 1$  so that, in particular, it will not satisfy (PS)<sub>1</sub> in view of (11). Consider the Dirichlet problem

$$(*) \quad \begin{aligned} -\Delta u &= \lambda_1 u + g(u) \quad \text{in } \Omega \\ u &= 0 \quad \text{on } \partial\Omega, \end{aligned}$$

where  $\Omega \subset \mathbb{R}^N$  is a bounded smooth domain,  $\lambda_1$  is the first eigenvalue of  $-\Delta$  with zero Dirichlet boundary condition, and  $g : \mathbb{R} \rightarrow \mathbb{R}$  is a continuous function satisfying the following conditions:

$$\begin{aligned} (g_1) \quad & g \text{ is bounded on } \mathbb{R}, \text{ say } |g(s)| \leq M \text{ for every } s \in \mathbb{R} \text{ (and some } M > 0); \\ (g_2) \quad & \lim_{s \rightarrow +\infty} G(s) = -\frac{1}{|\Omega|} \text{ (where } G(s) = \int_0^s g(\sigma) d\sigma); \\ (g_3) \quad & \lim_{s \rightarrow -\infty} G(s) = +\infty. \end{aligned}$$

From (g<sub>1</sub>) the corresponding functional

$$\varphi(u) = \int_{\Omega} \frac{1}{2} (|\nabla u|^2 - \lambda_1 u^2) dx - \int_{\Omega} G(u) dx = q(u) - \psi(u)$$

is well-defined and of class  $C^1$  on the Sobolev space  $X = H_0^1(\Omega)$ , which we decompose as  $X = \langle e \rangle \oplus W$ , with  $e = \phi_1 > 0$  being the first (normalized) eigenfunction of  $-\Delta$  on  $H_0^1(\Omega)$  and  $W = \langle \phi_1 \rangle^{\perp}$ .

**Lemma 6.** (i) There exists  $R_0 > 0$  such that  $\varphi(t\phi_1 + w) \geq -\psi(t\phi_1)$  for all  $\|w\| \geq R_0$  and  $t \in \mathbb{R}$ .

(ii) For any  $R > 0$ , we have  $\lim_{t \rightarrow +\infty} \varphi(t\phi_1 + w) = q(w) + 1$  uniformly for  $\|w\| \leq R$ .

**Proof.** (i) By  $(g_1)$  and the mean value theorem applied to  $G(t\phi_1 + w) - G(t\phi_1)$ , we have

$$(20) \quad |\psi(t\phi_1 + w) - \psi(t\phi_1)| = \left| \int_{\Omega} g(t\phi_1 + xw)w \, dx \right| \leq M_0 \|w\|$$

for some  $M_0 > 0$ . Therefore, we obtain

$$\varphi(t\phi_1 + w) = q(w) - \psi(t\phi_1 + w) \geq q(w) - M_0 \|w\| - \psi(t\phi_1),$$

and it is enough to take  $R_0 > 0$  such that  $q(w) - M_0 \|w\| \geq 0$  for all  $\|w\| \geq R_0$ .

In order to prove (ii), we only need to show that

$$(21) \quad \lim_{t \rightarrow +\infty} \psi(t\phi_1 + w) = -1,$$

uniformly for  $\|w\| \leq R$ . Indeed, if we suppose that (21) does not hold, then we can find  $t_n \rightarrow +\infty$  and  $w_n \in W$ ,  $\|w_n\| \leq R$ , such that

$$(22) \quad \psi(t_n\phi_1 + w_n) \not\rightarrow -1, \quad \text{as } n \rightarrow \infty.$$

Without loss of generality, we may assume that there exist  $\tilde{w} \in H_0^1(\Omega)$  and  $h \in L^1(\Omega)$  such that

$$(23) \quad \begin{aligned} & \text{(i) } w_n \rightharpoonup \tilde{w} \text{ weakly in } H_0^1 \\ & \text{(ii) } w_n \rightarrow \tilde{w} \text{ strongly in } L^p, 1 \leq p < \frac{2N}{N-2} \text{ if } N \geq 3 \text{ } [1 \leq p < \infty \text{ if } N = 1, 2] \\ & \text{(iii) } w_n(x) \rightarrow \tilde{w}(x) \text{ a.e. in } \Omega \\ & \text{(iv) } |w_n(x)| \leq h(x) \text{ a.e. in } \Omega. \end{aligned}$$

For each  $n \in \mathbb{N}$ , consider the set

$$A_n = \{x \in \Omega | t_n\phi_1(x) + w_n(x) < 0\}$$

and the function

$$f_n = G(t_n\phi_1 + w_n)\chi_{A_n}$$

in  $\Omega$ , where  $\chi_{A_n} = \chi_{A_n}$  is the characteristic function of  $A_n$ . From (23)(iii) we obtain that  $f_n(x) \rightarrow 0$  a. e. in  $\Omega$ . And, from  $(g_1)$ , the mean value theorem and (23)(iv), we get that

$$|f_n(x)| \leq M |t_n\phi_1(x) + w_n(x)| \chi_{A_n}(x) \leq M |w_n(x)| \chi_{A_n}(x) \leq M h(x) \text{ a.e. in } \Omega.$$

Therefore, by Lebesgue's Dominated Convergence Theorem,

$$(24) \quad \int_{A_n} G(t_n\phi_1 + w_n) dx \rightarrow 0, \text{ as } n \rightarrow \infty.$$

On the other hand, from  $(g_2)$ , (23) and the fact that  $G(s)$  is bounded on  $\mathbb{R}^+ = \{s \in \mathbb{R} | s \geq 0\}$ , we obtain that

$$(25) \quad \int_{\Omega \setminus A_n} G(t_n\phi_1 + w_n) dx \rightarrow -1, \text{ as } n \rightarrow \infty.$$

Hence, (24) and (25) give  $\psi(t_n\phi_1 + w_n) \rightarrow -1$ , which contradicts (22) and thus concludes the proof of Lemma 6. ■

Now, it follows from Lemma 6 that

$$\lim_{t \rightarrow +\infty} \varphi(t\phi_1) = 1,$$

$$\lim_{t \rightarrow +\infty} \inf_{w \in W} \varphi(t\phi_1 + w) \geq 1,$$

from which we obtain, respectively, that  $\varphi^d$  is not  $\phi_1$ -bounded for  $d > 1$  and is  $\phi_1$ -bounded for  $d < 1$ . In particular, the functional  $\varphi$  is  $\phi_1$ -bounded from below. However,  $\varphi$  is not bounded from below since  $(g_3)$  implies

$$(26) \quad \lim_{t \rightarrow -\infty} \varphi(t\phi_1) = -\lim_{t \rightarrow -\infty} \psi(t\phi_1) = -\infty.$$

Applying Proposition 2 e to the functional  $\varphi$  with  $c = 1$ , we conclude that there exists a sequence  $\{u_n\} = \{t_n \phi_1 + \omega_n\} \subset H_0^1(\Omega)$  such that

$$\begin{cases} \varphi(u_n) \longrightarrow 1 \\ \|\varphi'(u_n)\|_{H^{-1}} \longrightarrow 0 \\ t_n \longrightarrow +\infty. \end{cases}$$

In particular,  $\varphi$  does not satisfy  $(PS)_1$ .

Note that there may exist  $d \neq 1$  such that  $\varphi$  does not satisfy  $(PS)_d$ . However, this is not the case if we assume

$$(g_4) \quad \lim_{s \rightarrow +\infty} g(s) = 0,$$

as the following lemma shows.

**Lemma 7.** If  $(g_1) - (g_4)$  hold, then

$$D = \{d \in \mathbb{R} \mid \varphi \text{ satisfies } (PS)_d\} = \mathbb{R} \setminus \{1\}.$$

**Proof.** Suppose that  $\varphi$  does not satisfy  $(PS)_d$ . Then, there exists  $u_n = t_n \phi_1 + \omega_n \in H_0^1$  such that

$$(27) \quad \varphi(u_n) \longrightarrow d,$$

$$(28) \quad \|\varphi'(u_n)\|_{H^{-1}} \longrightarrow 0,$$

but  $\{u_n\}$  does not possess a convergent subsequence. From (28) we obtain

$$(29) \quad |\varphi'(u_n), \omega_n| = \|\omega_n\|^2 - \lambda_1 \|\omega_n\|_{L^2}^2 - \int_{\Omega} g(t_n \phi_1 + \omega_n) \omega_n dx \leq \varepsilon_n \|\omega_n\|,$$

where  $\varepsilon_n = \|\varphi'(u_n)\|_{H^{-1}} \longrightarrow 0$ , so that

$$\|\omega_n\|^2 - \lambda_1 \|\omega_n\|_{L^2}^2 \leq (M_0 + \varepsilon_n) \|\omega_n\|$$

in view of  $(g_1)$  and, hence,  $\|\omega_n\| \leq R$  for some  $R > 0$ . Since  $u_n = t_n \phi_1 + \omega_n$  and  $\nabla \varphi(u_n) = u_n - K(u_n)$  with  $K : H_0^1 \longrightarrow H_0^1$  a compact operator, it must be the case that  $|t_n| \longrightarrow \infty$ . In fact,  $t_n \longrightarrow +\infty$  necessarily in view of (20), (26) and (27). Now, arguing as in Lemma 6 and using  $(g_4)$ , we obtain that

$$\lim_{n \rightarrow \infty} \int_{\Omega} g(t_n \phi_1 + \omega_n) \omega_n dx = 0,$$

and, hence, that  $\|\omega_n\| \longrightarrow 0$  in view of (29). But then Lemma 6 (ii) yields

$$\lim_{n \rightarrow \infty} \varphi(t_n \phi_1 + \omega_n) = \lim_{n \rightarrow \infty} [q(\omega_n) + 1] = 1,$$

so that  $d = 1$  necessarily. ■

Finally, we should observe that, if we assumed

$$(g_3) \quad \lim_{s \rightarrow -\infty} G(s) = -\frac{a}{|\Omega|},$$

instead of  $(g_3)$  then by the same argument used above with  $c = -\phi_1$ , we would conclude that  $\varphi$  does not satisfy  $(PS)_a$ . On the other hand, for results concerning existence of solutions for problem (\*) under hypotheses on  $G$  of the type  $(g_2) - (g_3)$  we refer the reader to e.g. [1], [2], [7], [9], [12], [13] and references there in.

#### 4. Final Remarks and Comments

A close look at the proof of Proposition 2e shows that, in fact, a more general result is true. In order to state it, we need the following definition: given a functional  $F : X \longrightarrow \mathbb{R}$ , a set  $X$  will be said to be  $F$ -bounded if  $S \subset F^r$  for some  $r \in \mathbb{R}$ .

**Proposition 2F.** Let  $\varphi : X \rightarrow \mathbb{R}$  be of class  $C^1$ ,  $F : X \rightarrow \mathbb{R}$  be uniformly continuous and  $c \in \mathbb{R}$  be such that  $\varphi^d$  is not  $F$ -bounded for  $d > c$  and  $\varphi^d$  is  $F$ -bounded for  $d < c$ . Then, there exists  $\{u_n\} \subset X$  such that

$$\begin{cases} \varphi(u_n) \rightarrow c \\ \|\varphi'(u_n)\|_{X^*} \rightarrow 0 \\ F(u_n) \rightarrow +\infty. \end{cases}$$

Of course, if we give the other suitable (and natural) definitions, all the corresponding results of section 2 will also hold true in this new framework. Also note that Proposition 2 and Proposition 2e correspond to the choices  $F(u) = \|u\|$  and  $F(te + \omega) = t$ , respectively, in Proposition 2F above. Another interesting choice, which may prove to be useful in situations where  $\varphi$  is an indefinite functional, is  $F(v + \omega) = \|v\| - \|\omega\|$  for a suitable decomposition  $X = V \oplus W$ .

Finally, we mention a further related result which extends Corollary 5 in another direction, namely that of the underlying space  $X$ .

**Corollary 5.** Let  $\varphi \in C^1(X, \mathbb{R})$  satisfy (PS) and be such that  $X \setminus \varphi^a$  is not bounded for some  $a \in \mathbb{R}$ . If either

- (i)  $\varphi^{-1}(a) = \{u \in X \mid \varphi(u) = a\}$  or
- (ii)  $\varphi^{-1}(a, b) = \{u \in X \mid a < \varphi(u) \leq b\}$  for some  $b > a$

is a bounded set, then  $\varphi$  is coercive on  $X \setminus \varphi^a$ , that is,  $\varphi(u) \rightarrow +\infty$  as  $\|u\| \rightarrow \infty$ ,  $u \in X \setminus \varphi^a$ .

Corollary 5 follows from a corresponding Proposition 2, whose statement we presently omit. Details and proofs of these and other results will appear elsewhere.

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