



INTERNATIONAL ATOMIC ENERGY AGENCY
UNITED NATIONS EDUCATIONAL, SCIENTIFIC AND CULTURAL ORGANIZATION
INTERNATIONAL CENTRE FOR THEORETICAL PHYSICS
I.C.T.P., P.O. BOX 586, 34100 TRIESTE, ITALY, CABLE: CENTRATOM TRIESTE



SMR/534-15

ICTP/WMO WORKSHOP ON EXTRA-TROPICAL AND TROPICAL
LIMITED AREA MODELLING
22 October - 3 November 1990

"The Finite-Element Method for the Horizontal
& Vertical Discretization of Atmospheric Models"

THE FINITE-ELEMENT METHOD FOR THE HORIZONTAL AND VERTICAL DISCRETIZATION OF ATMOSPHERIC MODELS

Andrew Staniforth

Recherche en prévision numérique
Environment Canada

OUTLINE

- 1) Introduction to FE method.
- 2) Formulation considerations.
- 3) Some recent results (hot off the press!). *Friday, Nov 2* → deferred to
- 4) Conclusions.

A. STANIFORTH
Service de L'Environnement Atmosphérique
Recherche en Prévision Numérique
Dorval, Quebec
Canada

ICTP-FE.5

FE REVIEW PAPERS

A.N.Staniforth: The application of the finite-element method to meteorological simulations - a review.

Int. J. Num. Meth. Fluids, 4, 1-12. 1984

A.N.Staniforth: Review: formulating efficient finite-element codes for flows in regular domains.

Int. J. Num. Meth. Fluids, 7, 1-16. 1987

FE

- Galerkin (like spectral)
- local (like FD's)

FD/FE issues

- staggered vs unstaggered grids
- primitive vs differentiated form of equations
- 2nd vs 4th order
- conservation properties
- uniform vs variable resolution

Galerkin FE method

SPACE DISCRETIZATION

Choices

- FD
- FE
- spectral } Galerkin

Spectral (for limited area)

- similar to spherical application
(half-wave Fourier series instead of spherical harmonics)
- aperiodicity requires special measures
(e.g. add special basis functions)
- more efficient than spherical spectral
(cheaper transforms)
- good phase speeds
(but restrictive CFL)
- Ibc's delicate

- (1) Expand dependent variables in terms of basis functions
 - Fourier series or spherical harmonics for spectral discretization
 - piecewise polynomials for FE discretization.
- (2) Insert in governing equations.
- (3) Orthogonalize error to basis
 - multiply by arbitrary basis function
 - integrate over domain.

GALERKIN METHOD

Governing equation: $Q[u(\underline{x}, t)] = 0$

- 1) Expand dependent variables

$$u(\underline{x}, t) = \sum_{n=1}^{\infty} u_n(t) f_n(\underline{x})$$

- 2) Insert into governing equations

$$Q\left(\sum_{n=1}^{\infty} u_n(t) f_n(\underline{x})\right) = E(\underline{x}, t)$$

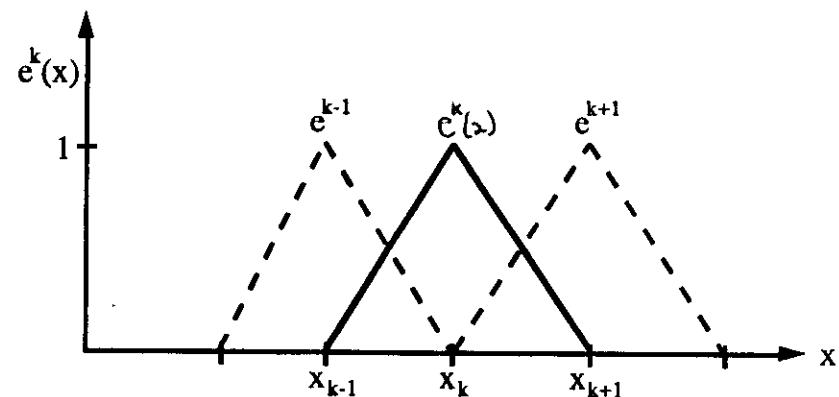
- 3) Orthogonalize error to basis

$$\int_D Q\left(\sum_{n=1}^{\infty} u_n(t) f_n(\underline{x})\right) f_k(\underline{x}) d\underline{x} = 0$$

EXAMPLE: 1st derivative

Governing equation: $v = \frac{du}{dx}$

LINEAR ELEMENT IN 1-D



1) Expand dependent variables

$$u = \sum_{i=1}^N u_i e^i(x)$$

$$v = \sum_{i=1}^N v_i e^i(x)$$

FD vs FE for 1st derivatives

FD

$$v_k = \frac{u_{k+1} - u_{k-1}}{2h} + O(h^2)$$

2) Insert in governing equations

$$E(x) = \sum_{i=1}^N [v_i e^i(x) - u_i e_x^i(x)]$$

FE

$$\frac{1}{6} (v_{k-1} + 4v_k + v_{k+1}) = \frac{u_{k+1} - u_{k-1}}{2h} + O(h^4)$$

3) Orthogonalize error to basis

$$\int_{x_1}^{x_N} E(x) e^k(x) dx = 0$$

"super-convergence at nodes" for FE result

$$= \int_{x_1}^{x_N} \sum_{i=1}^N [v_i e^i(x) - u_i e_x^i(x)] e^k(x) dx$$

for $k=1, 2, \dots, N$

EXAMPLE: product in 1-d

Governing equation: $w = u v$

1) Expand dependent variables

$$w = \sum_{i=1}^N w_i e^i(x)$$

... etc.

2) Insert in governing equation

$$\sum_{i=1}^N w_i e^i(x) - \sum_{i=1}^N u_i e^i(x) \sum_{j=1}^N v_j e^j(x) = E(x)$$

3) Orthogonalize error to basis

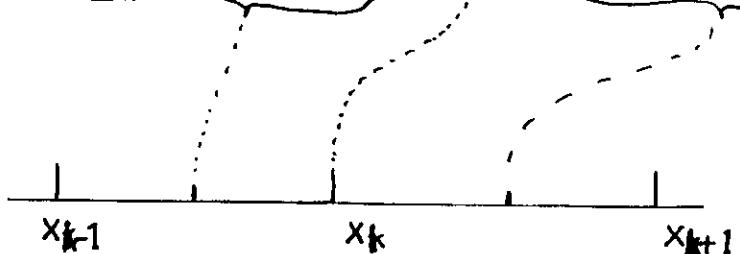
$$\int_{x_1}^{x_k} E(x) e^k(x) dx = 0 \quad \text{for } k = 1, 2, \dots, N$$

Result:

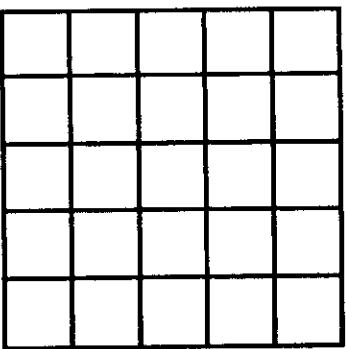
$$\frac{1}{6}(w_{k-1} + 4w_k + w_{k+1})$$

$$= \frac{1}{12}[(u_{k-1}+u_k)(v_{k-1}+v_k) + 4u_kv_k + (u_k+u_{k+1})(v_k+v_{k+1})]$$

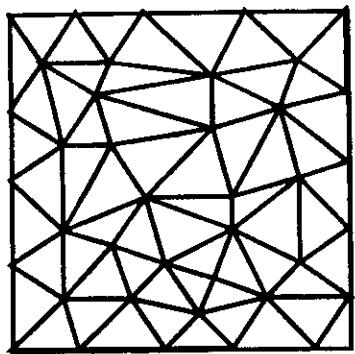
$$= \frac{1}{3} \left[\underbrace{\left(\frac{u_{k-1}+u_k}{2} \right) \left(\frac{v_{k-1}+v_k}{2} \right)}_{\text{Term 1}} + \underbrace{u_kv_k}_{\text{Term 2}} + \underbrace{\left(\frac{u_k+u_{k+1}}{2} \right) \left(\frac{v_k+v_{k+1}}{2} \right)}_{\text{Term 3}} \right]$$



KEY ISSUE - ELEMENT CHOICE



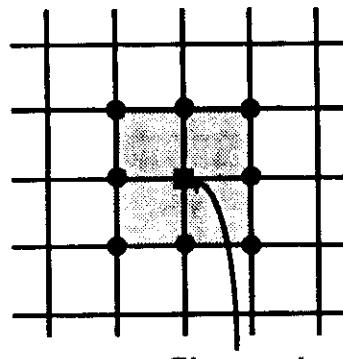
RECTANGLES



TRIANGLES

- Q? Can we afford **generality** of triangles?
- Q? Is it **computationally competitive** with FD's?

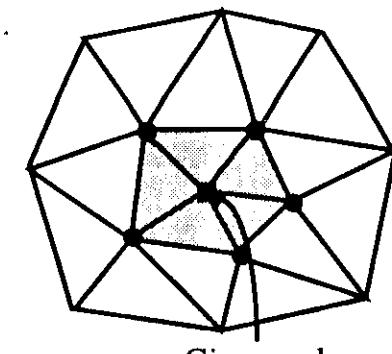
LINEAR ELEMENTS



Given node

Rectangles

$$(a+bx)(c+dy)$$



Triangles

$$(a+bx+cy)$$

Definition: $e^i(x,y) = 1$ at given node (■),
 $= 0$ at neighbouring nodes (●),
 $= 0$ outside shaded areas,
varies linearly over shaded areas.

MASS-MATRIX PROBLEM

Both $v = u_x$ and $v = uw$ lead to

$$P\underline{v} = \underline{r}$$

where \underline{r} is known,

and P is **large and sparse**.

COST ?????

RECTANGULAR ELEMENTS

Can exploit structure of P .

Decompose P as

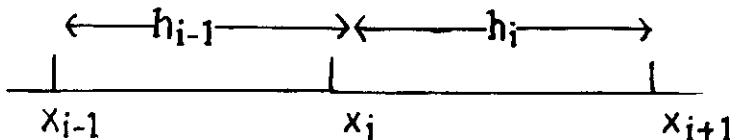
$$P = P^x \ P^y$$

$$\text{where } P^x \sim \left[\frac{h_{k-1}}{6}, \frac{2(h_{k-1}+h_k)}{6}, \frac{h_k}{6}, \right]$$

Operational count: $O(1)$ per node

Memory: $O(1)$ per node

Generalizes to : 3d



TRIANGULAR ELEMENTS

Can exploit *bandwidth* of P,

but several orders of magnitude more costly.

Less accurate than rectangular elements

(no super-convergence at nodes)

TRICK FOR O(h⁴) APPROXIMATION

(on uniform- resolution sub-domain)

$$\text{TO: } r = \nabla^2 f$$

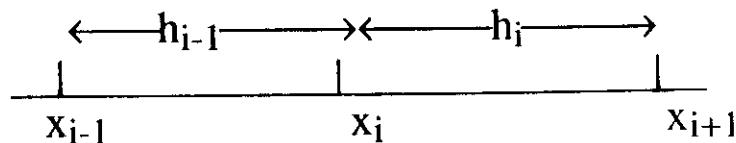
Example (in 1-d): $r = f_{xx}$

Usual: - $O(h^2)$

$$\frac{h_{i-1}}{6} (r_{i-1} + 2r_i + r_{i+1}) + \frac{h_i}{6} (2r_i + r_{i+1}) = \frac{1}{h_i} (f_{i+1} - f_i) - \frac{1}{h_{i-1}} (f_i - f_{i-1})$$

Modified: - $O(h^4)$

$$\frac{h_{i-1}}{12} (r_{i-1} + 5r_i + r_{i+1}) + \frac{h_i}{12} (5r_i + r_{i+1}) = \frac{1}{h_i} (f_{i+1} - f_i) - \frac{1}{h_{i-1}} (f_i - f_{i-1})$$



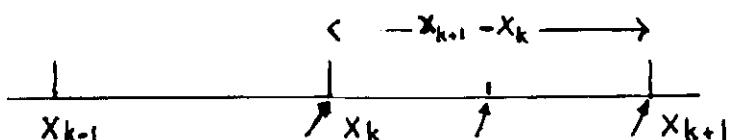
NUMERICAL QUADRATURE FOR PRODUCTS

Example in 1-d:- $w = u v$

$$\int_{x_{k-1}}^{x_{k+1}} u v e^k(x) dx = \int_{x_{k-1}}^{x_k} u v e^k(x) dx + \int_{x_k}^{x_{k+1}} u v e^k(x) dx$$

Use Simpson's rule on each interval (exact for cubics):

$$\text{e.g. } I_k = \int_{x_k}^{x_{k+1}} u v e^k(x) dx = \int_{x_k}^{x_{k+1}} F dx \\ = \left(\frac{x_{k+1} - x_k}{6} \right) (F_k + 4F_{k+\frac{1}{2}} + F_{k+1}) + h^5 f^{(iv)}(\xi)$$



where:

$$F_k = [u v e^k(x)]|_{x_k} = u_k \cdot v_k \cdot (1) = u_k v_k$$

$$F_{k+\frac{1}{2}} = [u v e^k(x)]|_{x_{k+\frac{1}{2}}} = u_{k+\frac{1}{2}} \cdot v_{k+\frac{1}{2}} \cdot \left(\frac{1}{2} \right) \\ = \frac{1}{8} (u_k + u_{k+1})(v_k + v_{k+1})$$

$$F_{k+1} = u_{k+1} \cdot v_{k+1} \cdot (0) = 0$$

Thus

$$I_k = \frac{(x_{k+1} - x_k)}{3} \left[2u_k v_k + \frac{(u_k + u_{k+1})}{2} \frac{(v_k + v_{k+1})}{2} \right]$$

Note: - method generalizes to 2- and 3-d
- yields algorithm that is more efficient than evaluating integrals analytically.

SPATIAL EVOLUTIONARY ERROR

Cullen & Morton considered two ways of approximating $w = u \frac{\partial v}{\partial x}$ (using linear elements)

in context of time-dependent problem.

$$1) \text{ One-shot } w = u \frac{\partial v}{\partial x}$$

$$2) \text{ Two shots } r = \frac{\partial v}{\partial x}$$

$$w = u \cdot r$$

Both methods give $O(h^4)$ estimate for spatial evolutionary error, but "two shots" more accurate and permits code modularity.

ALIASING

e.g. 2-d incompressible flow using linear elements (Jespersen)

$$\Rightarrow \frac{\partial}{\partial t} (P \zeta) = J(\psi, \zeta) = \psi_x \zeta_y - \psi_y \zeta_x$$

$$\text{where } P \sim \frac{1}{36} \begin{bmatrix} 1 & 4 & 1 \\ 4 & 16 & 4 \\ 1 & 4 & 1 \end{bmatrix}$$

and $J(\psi, \zeta) = \text{Arakawa's Jacobian}$.

Thus if $P \rightarrow I$ ("mass lumping") we have Arakawa's scheme.

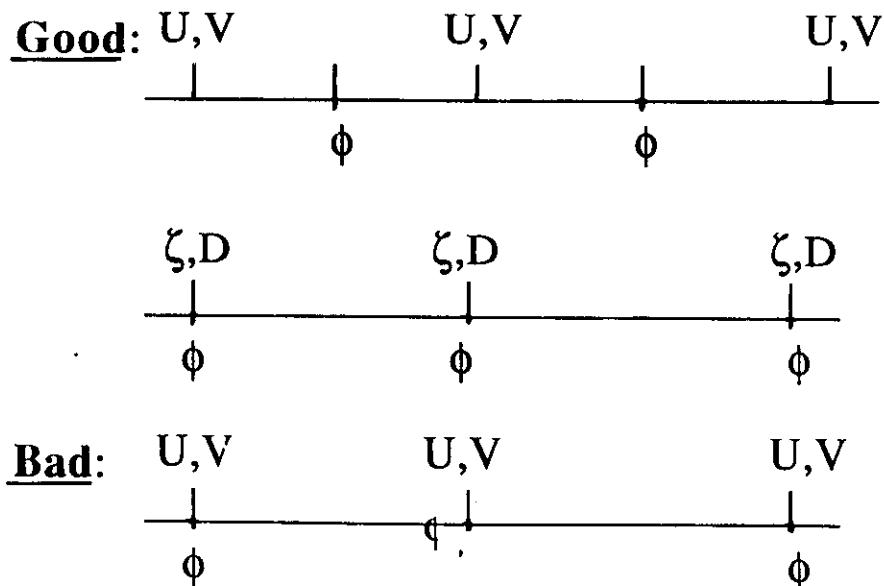
Note: - $J(\psi, \zeta)$ controls aliasing.

- P 'sharpens response', improves accuracy.

HORIZONTAL ISSUES

- 1) Staggered vs unstaggered meshes
- 2) Primitive vs differentiated form of equations

Analysis of linearised shallow-water equations shows (Williams) that FE considerations similar to FD ones.



But:

Pseudo staggering good in SL applications

Example: $v = \frac{du}{dx}$

$$\Rightarrow \frac{1}{2} (v_k + v_{k+1}) = \frac{u_{k+1} - u_k}{h_k}$$

Note: This is a one-interval approximation to a 1st derivative, rather than the usual two-interval one.

It is obtained by orthogonalizing the error to a different set of basis functions (piecewise-constant instead of piecewise linear).

It has certain advantages for some variable-res applications.

VERTICAL DISCRETIZATIONS

Several schemes exist using piecewise-linear and piecewise-constant elements.

Some have interesting conservation properties- e.g Yakimiw & Girard and Steppeler & Burridge.

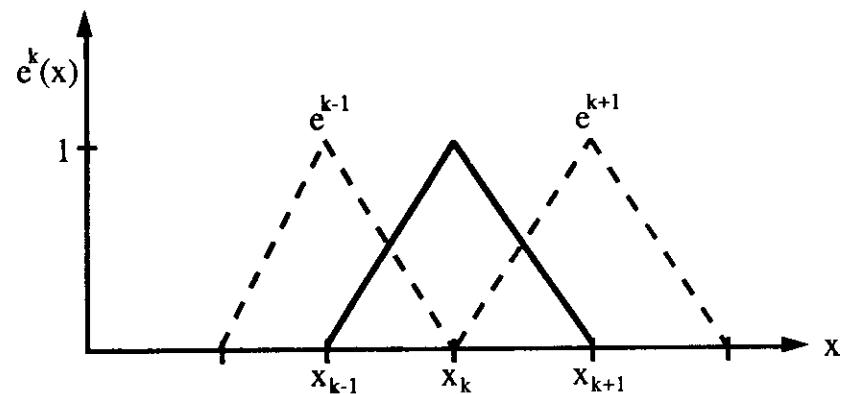
Yakimiw & Girard show how to obtain several well-known *FD* schemes using *FE*'s!

Beaudoin & Staniforth and Steppeler & Burridge found sensitivity to application of top b.c.

ELEMENT CHOICE FOR OPERATIONAL CANADIAN REGIONAL FE MODEL

- tri-linear elements on a variable-res Cartesian mesh

$$f_{ijk} (x,y) = e^i(x) e^j(y) e^k(\sigma)$$

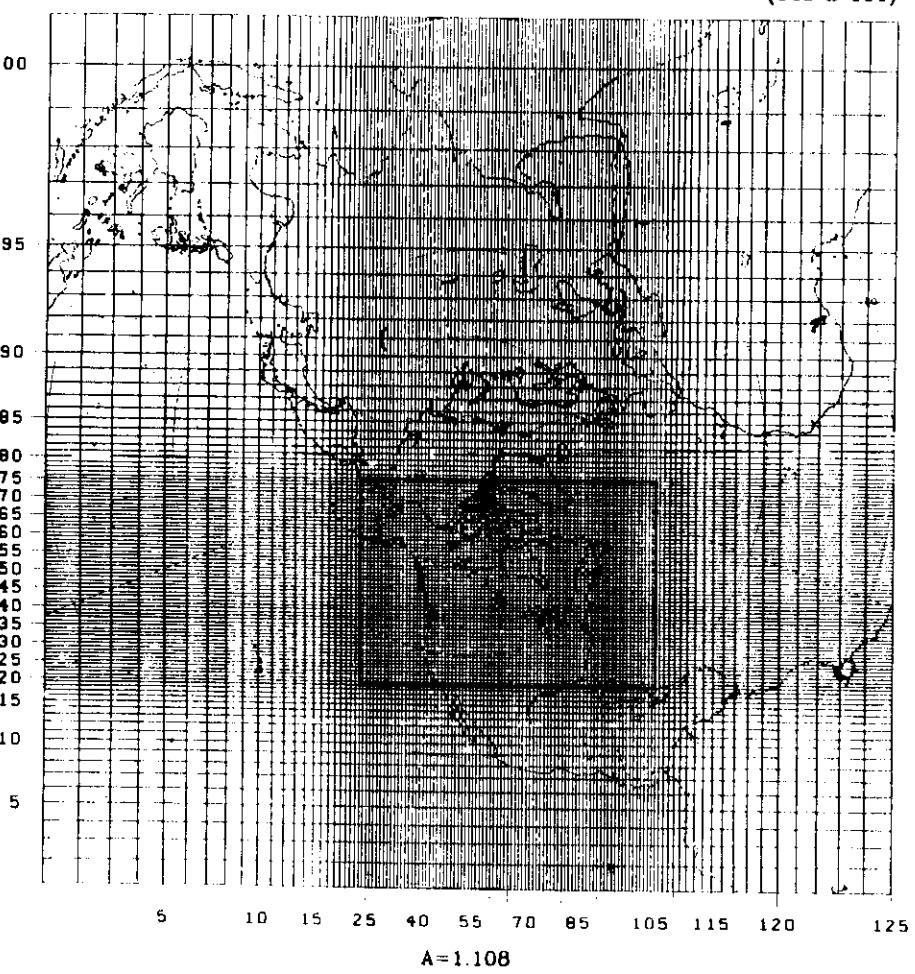


OPERATIONAL GRID

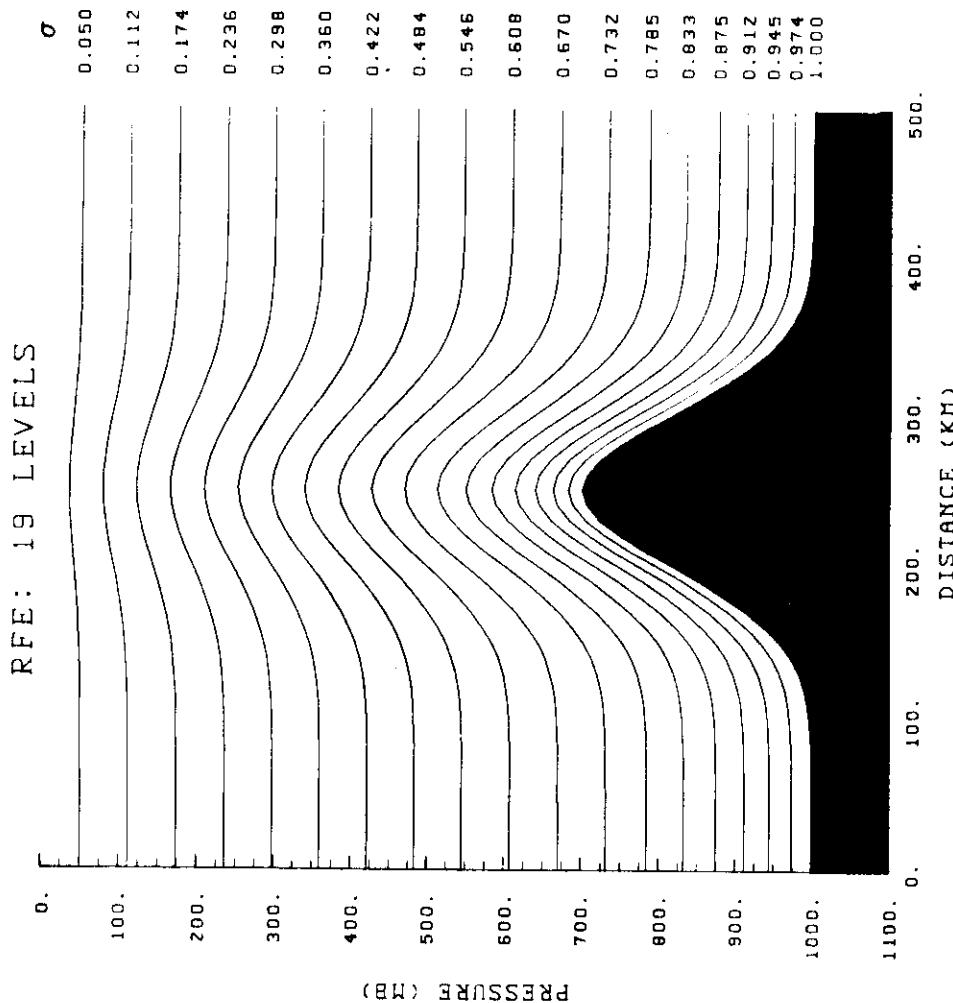
100 km

$A=1.109$

(125 x 101)



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REASONS

- Simplicity
- Flexibility of variable resolution
- Accuracy (particularly when coupled with semi-Lagrangian advection)
- Separable basis gives efficiency
 - vectorized algorithms
 - code modularity
- Low-order elements reduce # of computational modes
- Ease of incorporating b.c.'s

SURPRISING FACT

Semi-Lagrangian advection with cubic-spline interpolation is a finite-element method (using linear basis functions)

FINITE-ELEMENT REGIONAL MODEL

PARAMETERIZATIONS

DYNAMICS

Tanguay,Simard & Staniforth, MWR,89

- hydrostatic primitive equations
- variable-resolution 125x101 horizontal grid
- uniform 100 km res over N/A
- 19 levels (top at sigma = 0.05)
- trilinear finite elements
- semi-implicit semi-Lagrangian time scheme
- orography

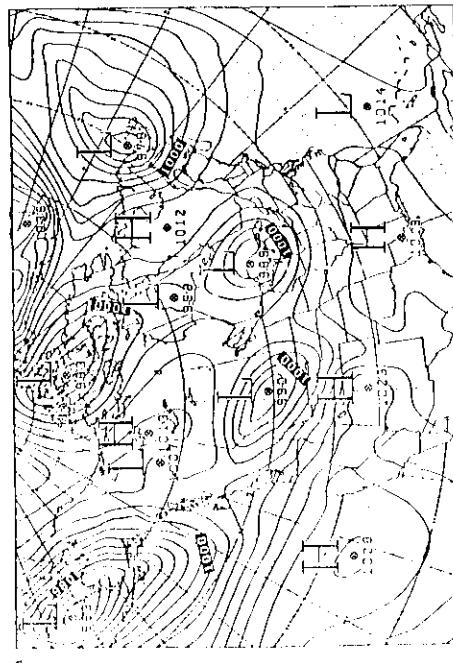
Benoit , Côté & Mailhot , MWR,89

- turbulent fluxes of momentum, heat & moisture based on turbulent KE
- prediction of temperature & moisture over land
- diurnal cycle based on surface energy budget
- solar & infrared radiation interactive with clouds
- moist convection and precipitation

3-d regional finite-element model 48-hour mean-sea-level forecasts

Eulerian

$dt = 400$ secs



- 5) FE's viable for vertical discretization of both
regional and global models.
- 6) Linear FE's competitive with FD's for regional
modelling.
- 7) Semi-Lagrangian advection is a FE method.
- 8) Particularly advantageous to associate variable-
res FE's with semi-Lagrangian advection (in both
regional and global models).
- 9) FE's with semi-Lagrangian advection now offers
promise of being more efficient than spectral
method for global modelling.