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INTERNATIONAL ATOMIC ENERGY AGENCY
INTERNATIONAL CENTRE FOR THEORETICAL PHYSICS
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SMR.998a - 17

Research Workshop on Condensed Matter Physics
30 June - 22 August 1997
MINIWORKSHOP ON
QUANTUM MONTE CARLO SIMULATIONS OF LIQUIDS AND SOLIDS
30 JUNE - 11 JULY 1997
and
CONFERENCE ON
QUANTUM SOLIDS AND POLARIZED SYSTEMS
3 - 5 JULY 1997

"Learning about melting with solid helium"

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These are preliminary lecture notes, intended only for distribution to participants.

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LEARNING ABOUT MELTING WITH SOLID HÉLIUM

EMIL POLTURAK

INON BERENT

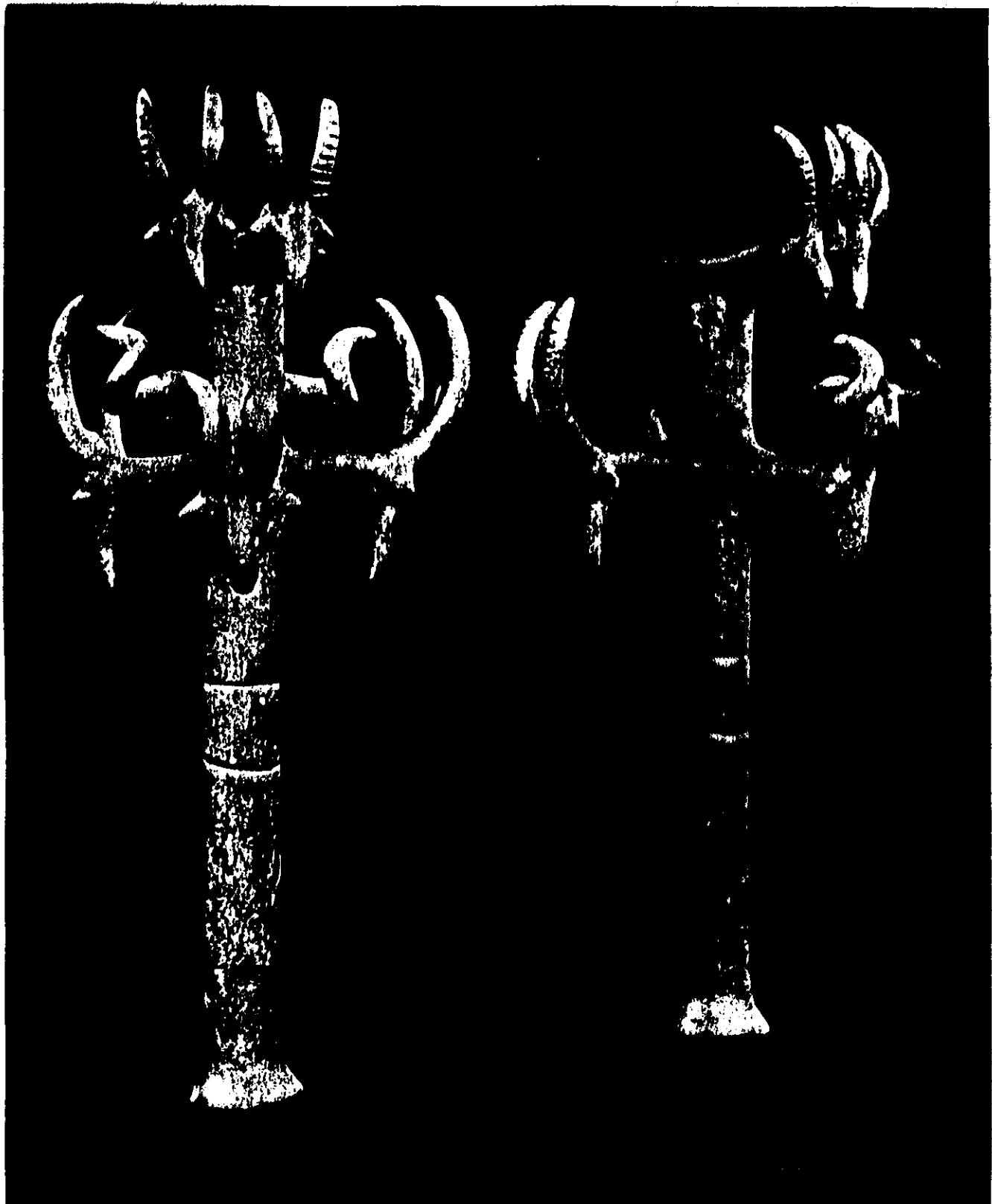
TUVY MARKOWITZ

ISRAEL SCHUSTER

STEVEN LIPSON

TECHNION PHYSICS DEPARTMENT

MELTING - A WELL KNOWN PHASE TRANSITION

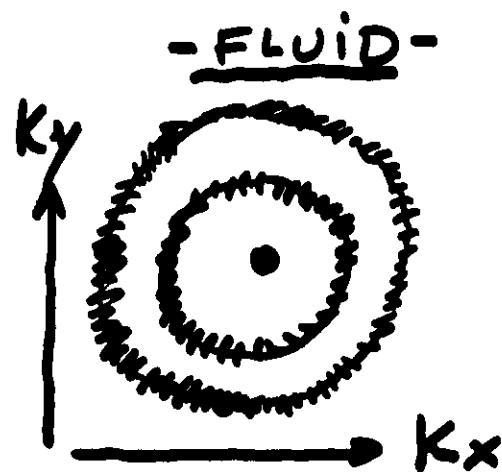
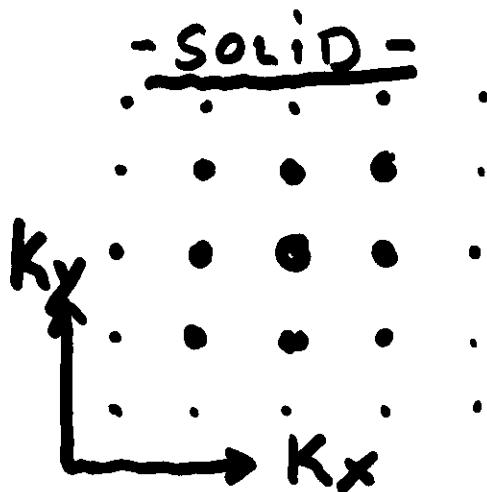
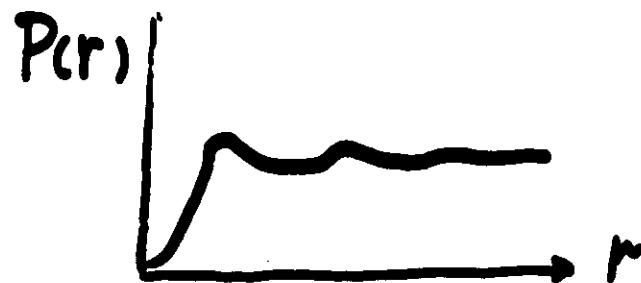
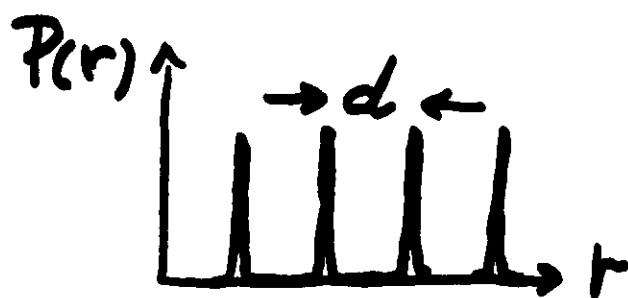


"COPPER , 3400 B.C.

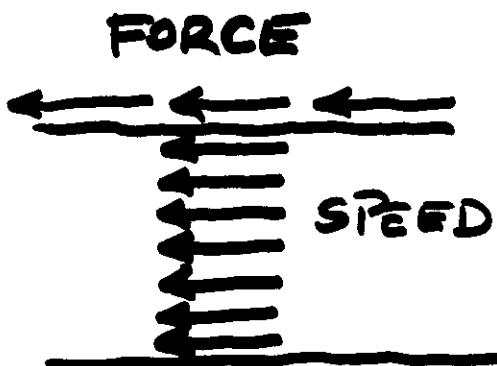
JUDEAN DESERT.

WHAT DOES ONE MEAN BY "MELTING"

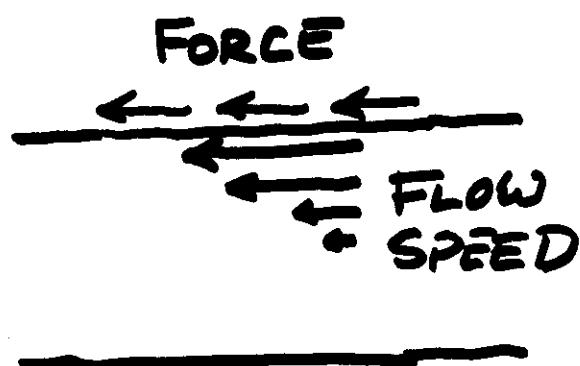
LOSS OF LONG RANGE ORDER.



b) LOSS OF RESISTANCE TO SHEAR (10^{15})



SOLID



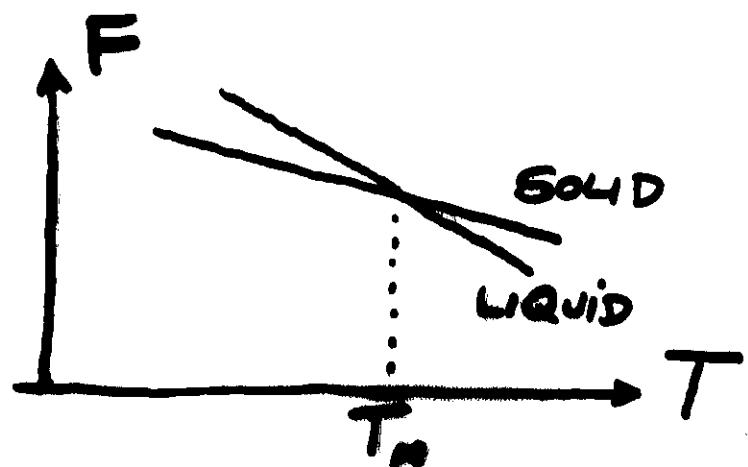
FLUID

$$F_s = \eta \frac{du}{dx}$$

THEORIES OF 3-D MELTING.

THERMODYNAMICS:

HARD!



SINGLE PHASE THEORIES:

LOOK FOR STRUCTURAL DEFECTS OR EXCITATIONS WHICH WILL DISINTEGRATE THE SOLID :

LINDEMANN (1910) - PHONONS

BORN (1939) - SHEAR INSTABILITY (phonons)

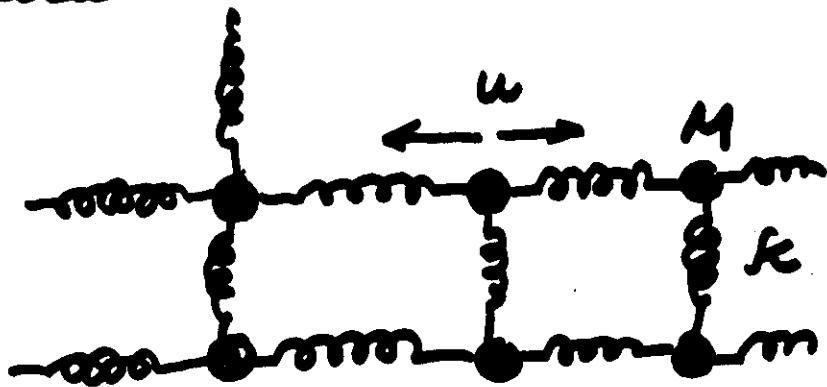
FRENDL (1965) - VACANCIES

MUSINA (1960) - DISLOCATIONS

GRANATO (1992) - INTERSTITIALS

:

LINDEMANN'S MODEL



ASSUME : FOR $u > u_c$, SOLID BREAKS UP

$$\text{USE : } \frac{3}{2} k u_c^2 = \frac{3}{2} k_B T_M$$

$$k_B \Theta_D = \hbar \omega_D = 2\pi \sqrt{k/M}$$

GET :

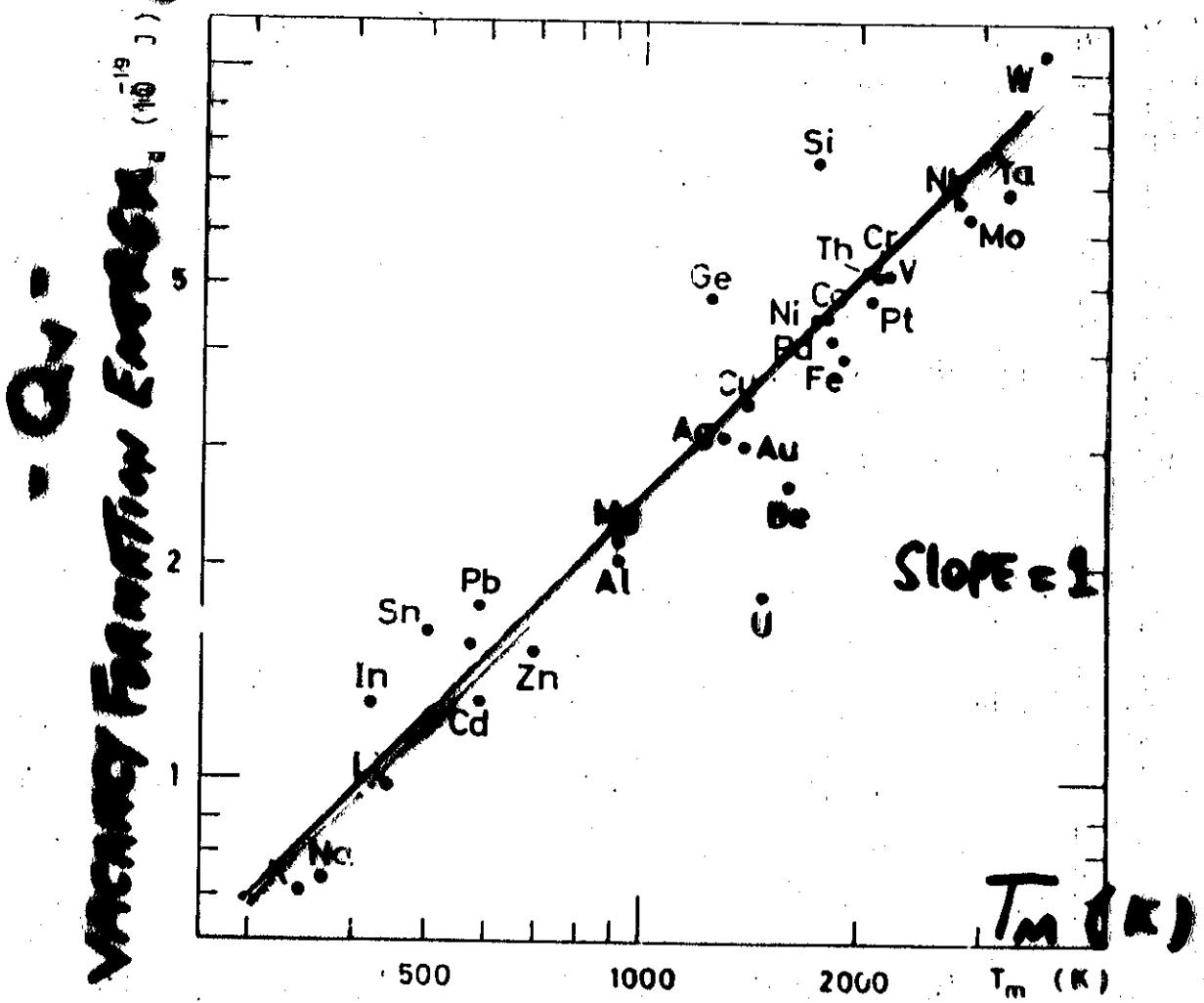
$$\boxed{\text{CONST} = \sqrt{\frac{k_B T_M}{M \Theta_D^2}} \sqrt[3]{2/3}}$$

WORKS FOR SOLID HELIUM! (Dugdale & Dorn)

DOES NOT WORK FOR OTHER MATERIALS.

MELTING - 3D - VACANCIES

1.5. Correlation and estimation of thermophysical parameters



$$\overline{T_m} = \text{const.} \times Q_v$$

Van Liermp (1938) - EMPIRICAL RULE

FRENKEL (1955) - THEORY

NUMBER AT $T_m \sim 10^{-3}$ (SMALL)

$$N_v = e^{-\frac{Q_v}{kT}}$$

Thermodynamics of Crystals and Melting

MAX BORN

Tait Professor of Natural Philosophy, University of Edinburgh, Edinburgh, Scotland

(Received May 25, 1939)

The Helmholtz free energy, A , of a rigid body is a function of temperature, and of the six homogeneous strain components. If the crystal is to be rigid, three inequalities must be satisfied for the derivatives of A with respect to the six strain components, for a regular (cubic) lattice. This enables one to limit the pressure-temperature range for which the crystal is stable. The violation of the condition $c_{44} > 0$, that the crystal resist shearing, is interpreted as leading to melting. From a knowledge of the forces

between the molecules the phase integral, and therefore the free energy, may be calculated as a function of T , V , and the six strain components. The numerical calculations are carried out for a body-centered cubic lattice. The product of all the frequencies is calculated directly, so that the assumption that the Debye equation for the frequency distribution, holds, is not necessary. The melting curve, pressure against temperature, is then determined.

$C_{44} \leq 0 \Rightarrow \text{INSTABILITY!}$

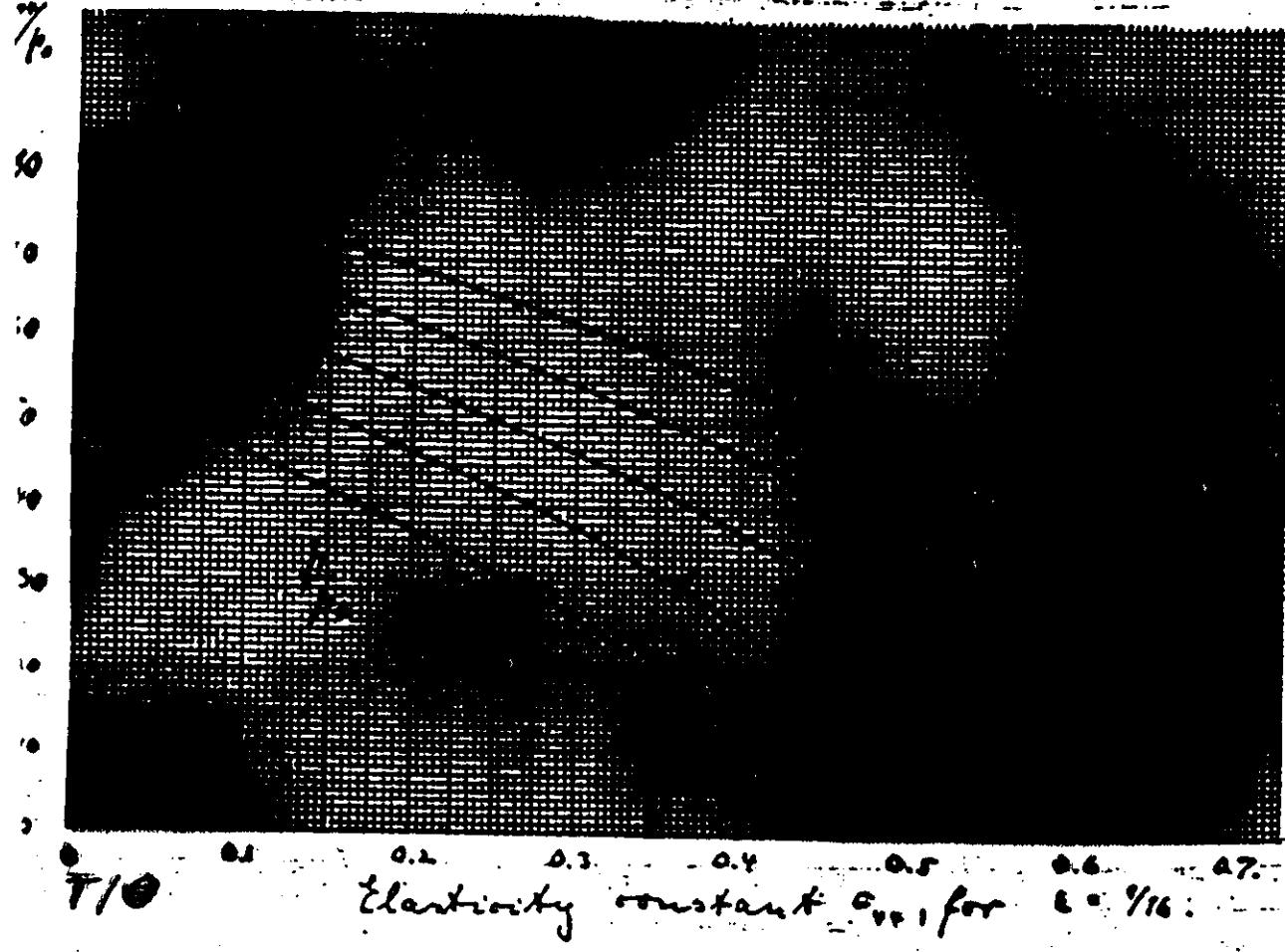
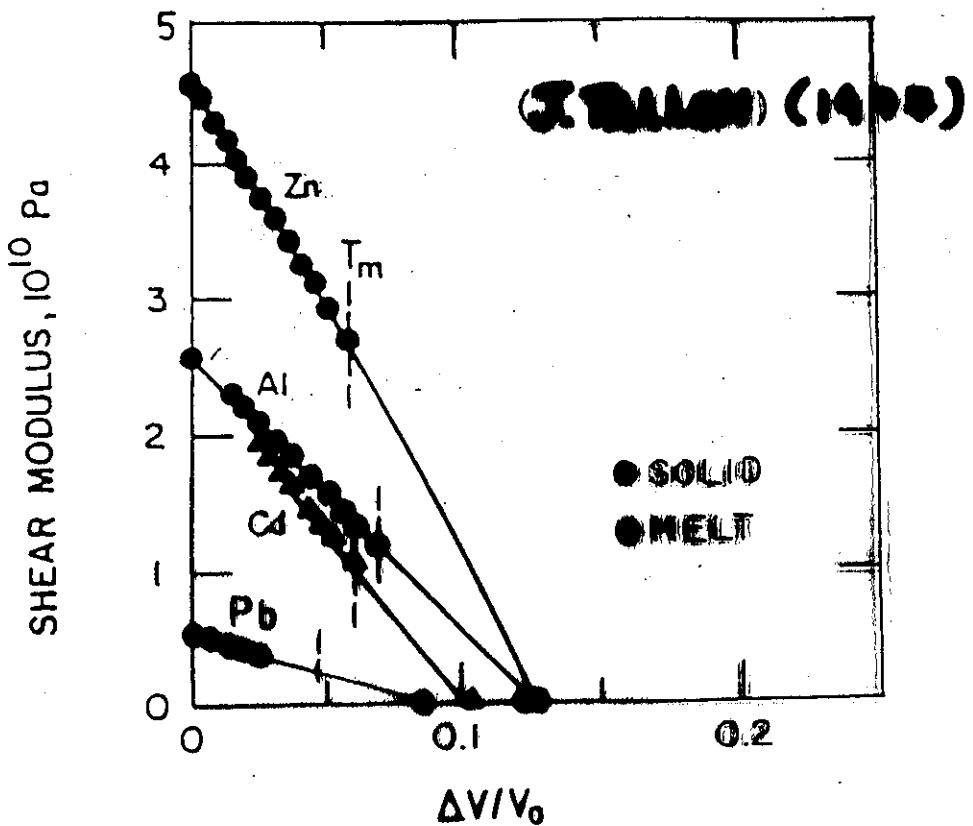


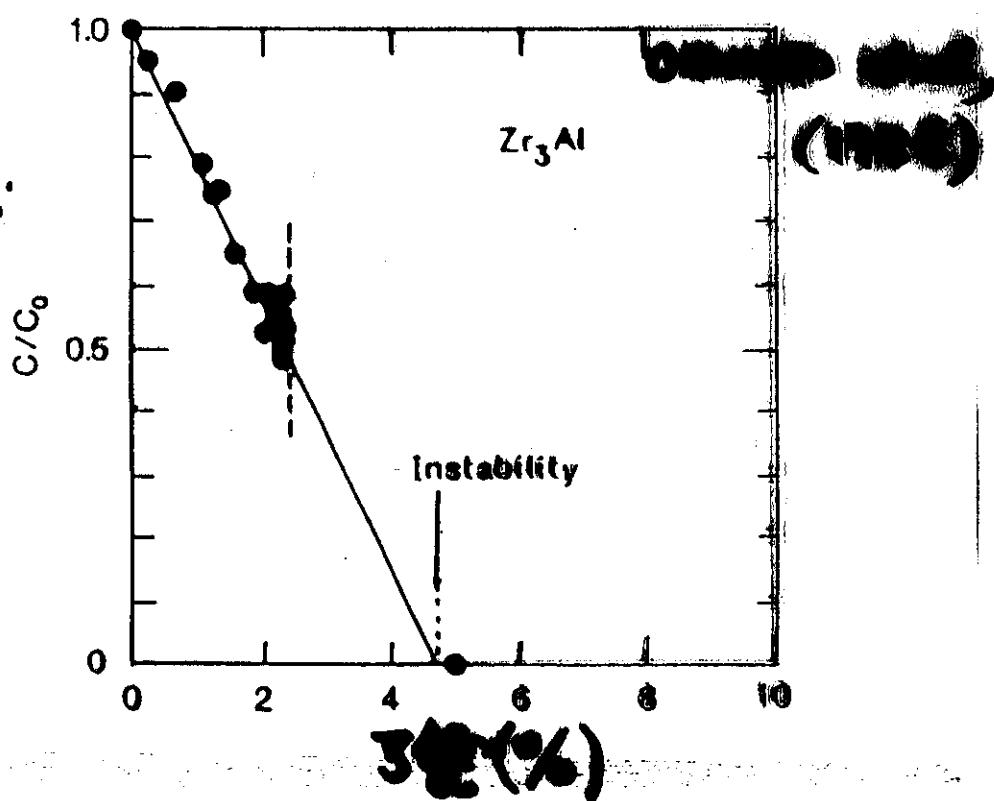
FIG. 6

C_{44} INSTABILITY : RESULT OF THERMAL EXPANSION

MELTING:



MORPHIZATION:



AMORPHIZATION - LOSS OF LONG RANGE ORDER

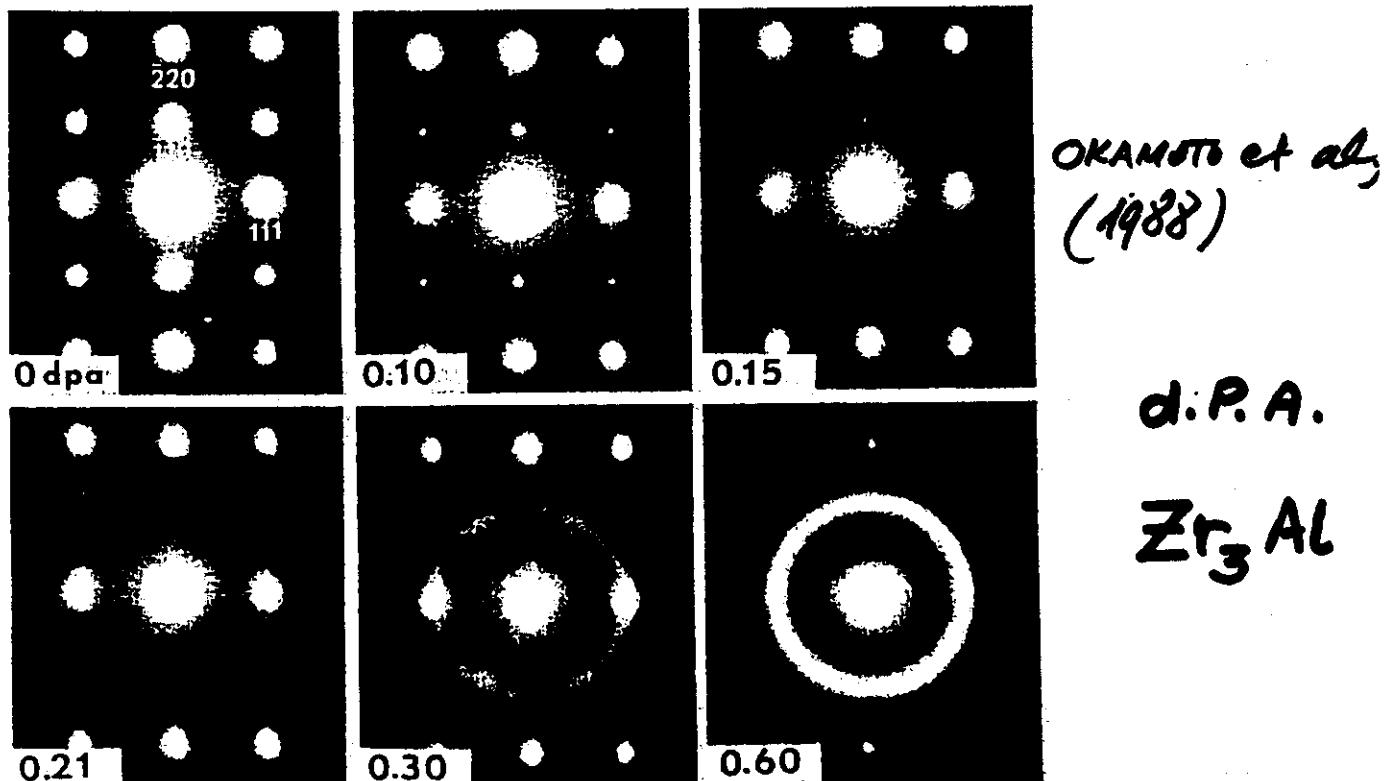
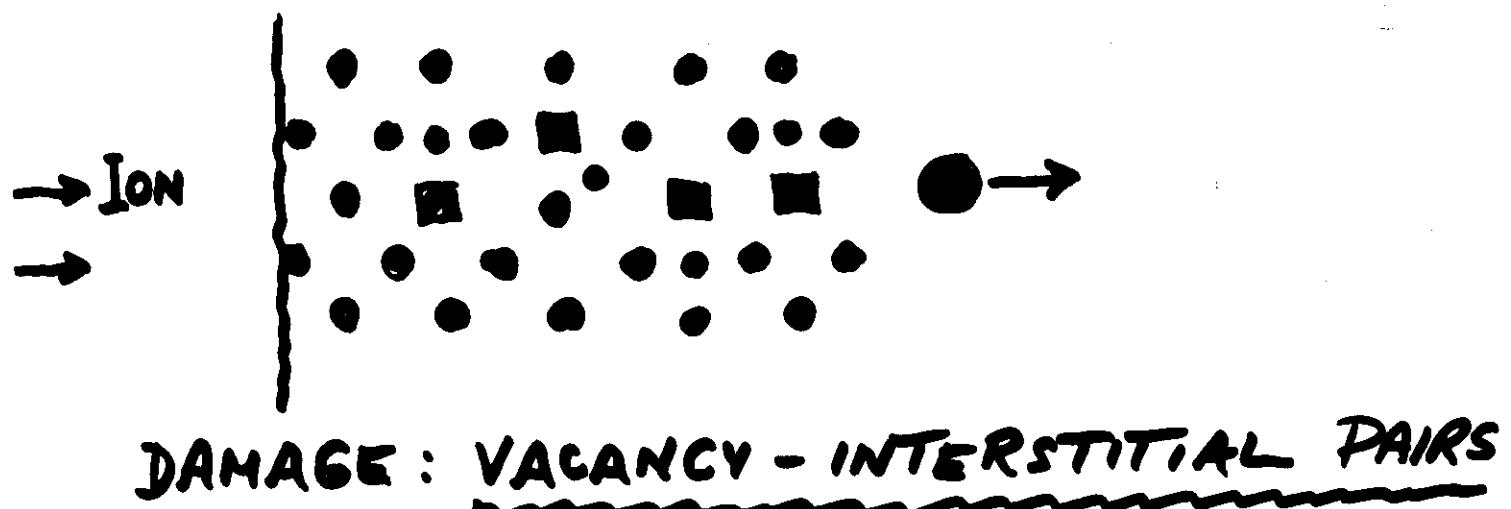
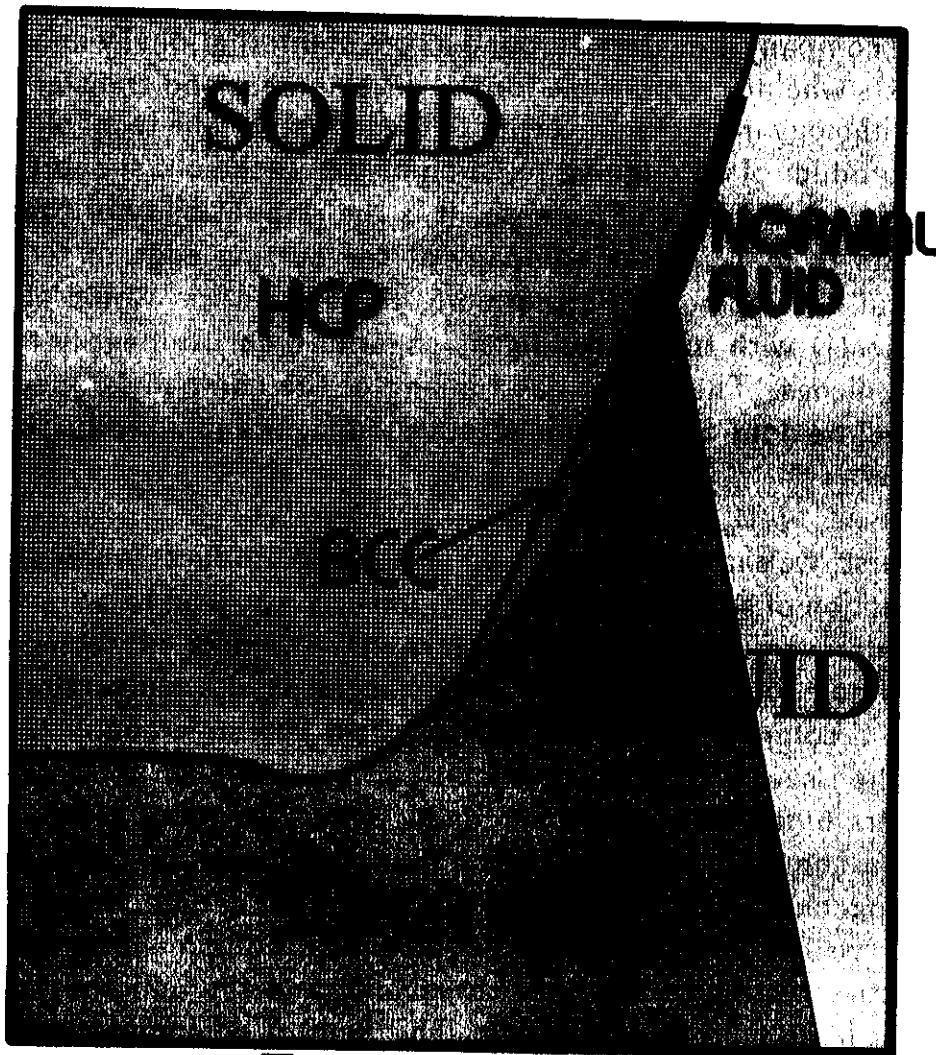


Fig. 3. Sequence of [112] zone-axis diffraction patterns of Zr₃Al showing the disappearance of superlattice reflections, and the formation of diffuse rings during *in situ* irradiation at room temperature with 1.0 MeV Kr⁺; doses are in d.p.a.



^4He PHASE Diagram

Pressure

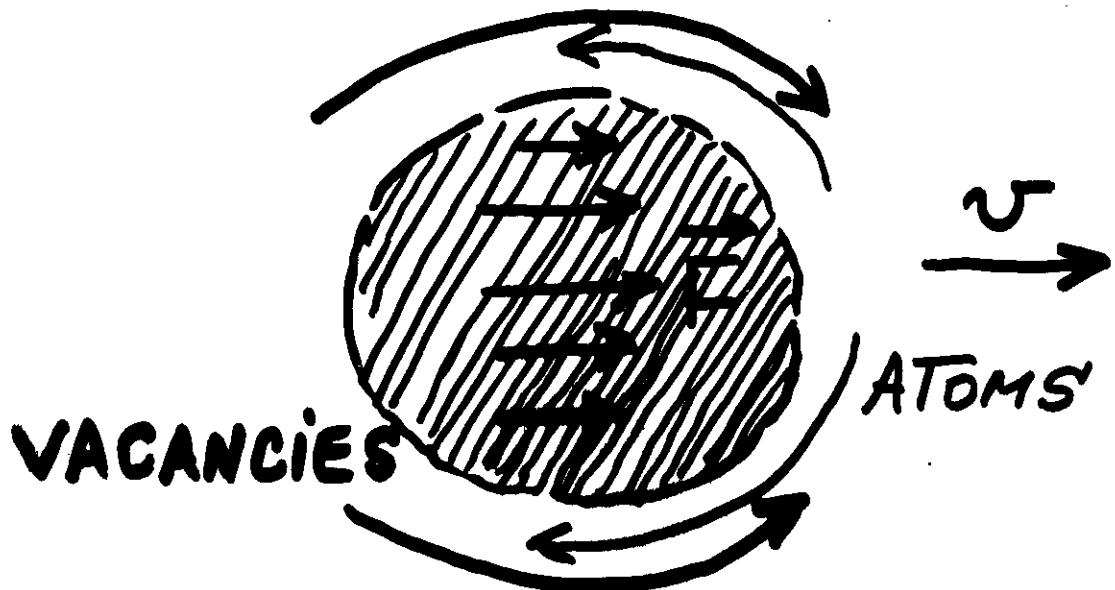


Temperature

Experiments were carried on the melting curve, along the purple line.

MOVING WIRE EXPERIMENT

(PURE ^4He , bcc, MEETING CURVE)



DIFFUSION COEFFICIENT:

$$D \cong \frac{kT \bar{v} \rho R}{F}$$

PREVIOUS EXPTS.

BLOMIN, et al..

SUZUKI

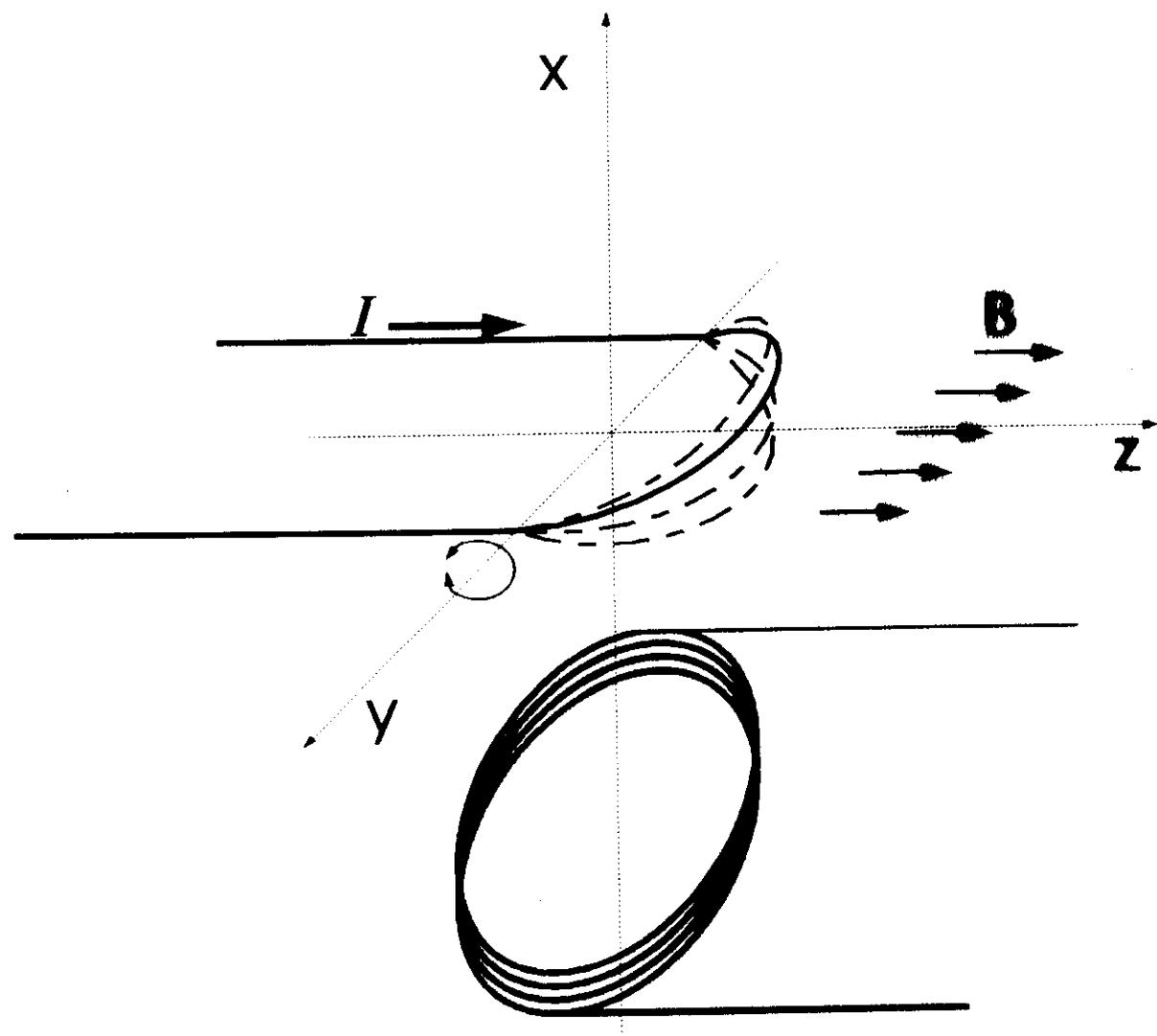
ELBAMW, et al.,

TECHNIQUE

A. GUENAUT

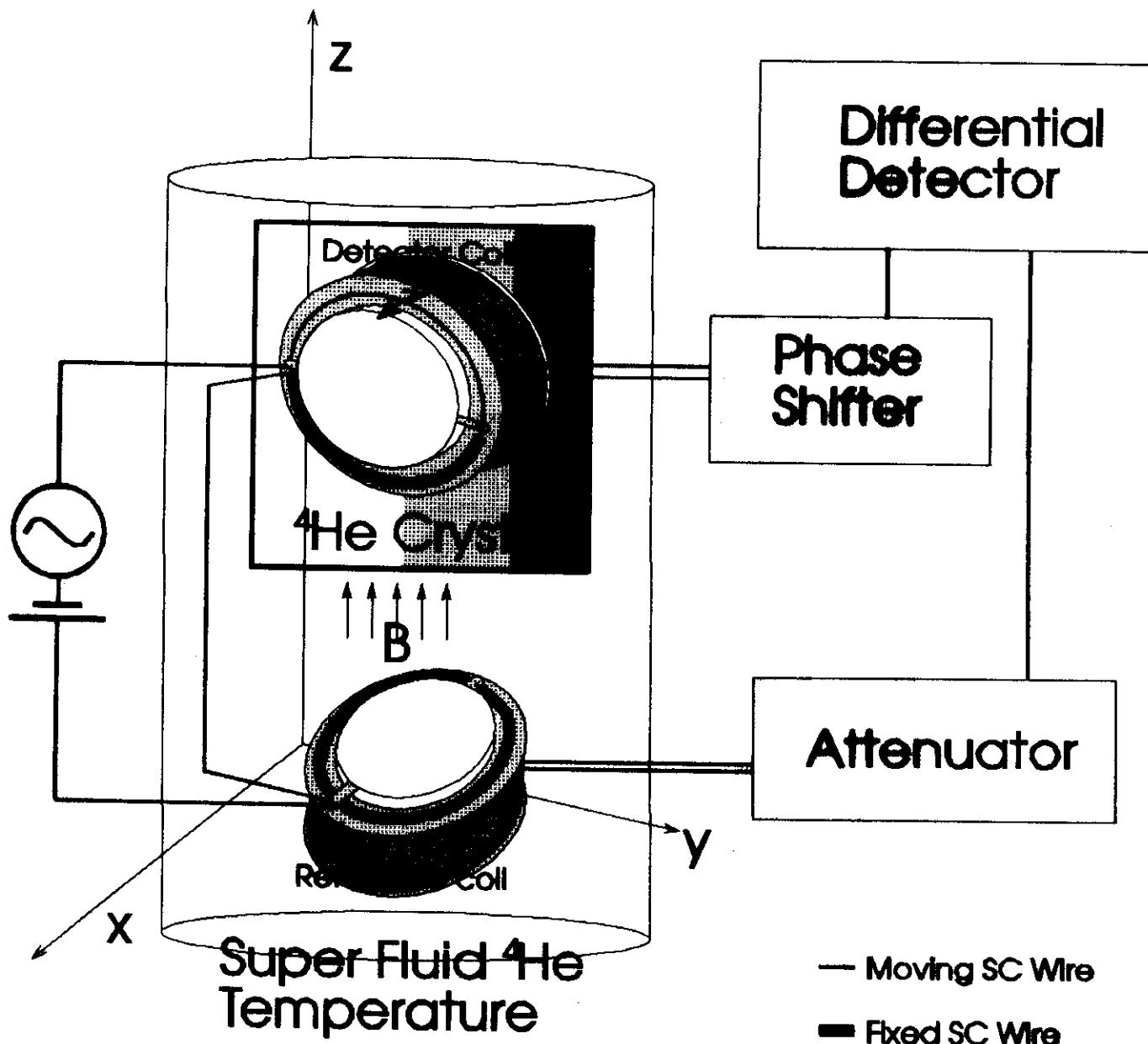
!

Measurement principle



The wire rotates around the y axis, with the DC current.
The induced voltage in the coil changes with the wire position.

Experimental setup



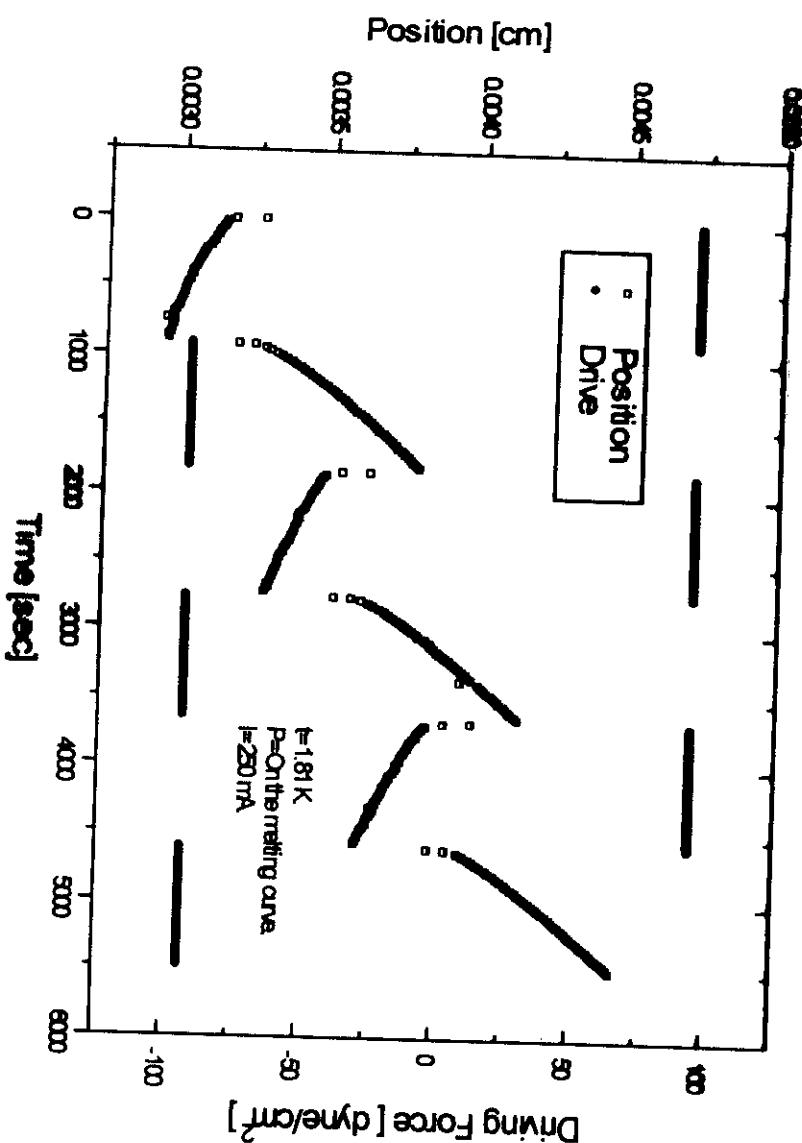
A DC, and a low amplitude, 7 KHz, AC current flows through the superconducting wire (— & —).

The Lorentz force, on the wire (—), drive it through the He crystal (■).

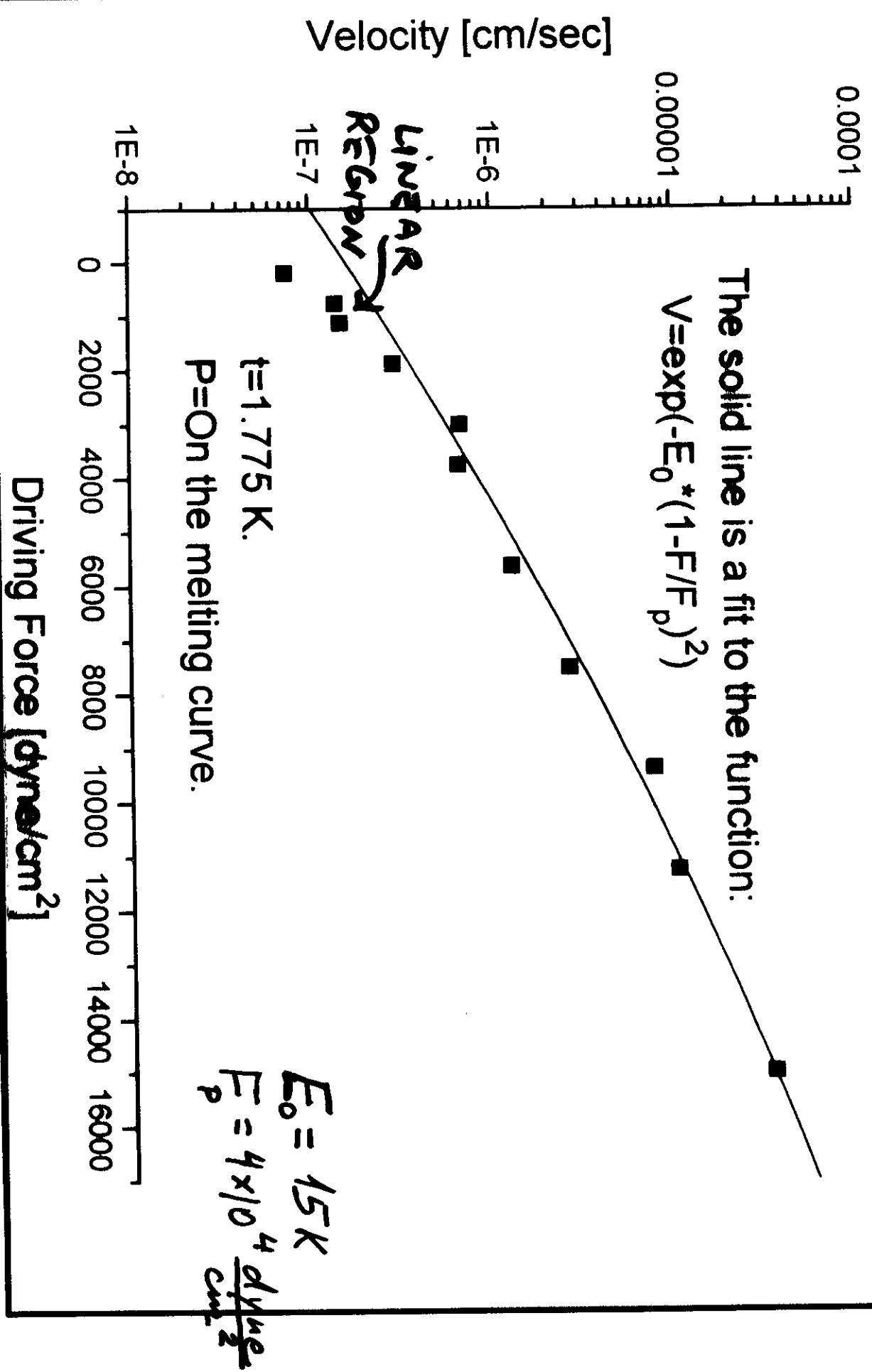
The wire position is found from the induced voltage difference between the coils.

Typical Measurement Results

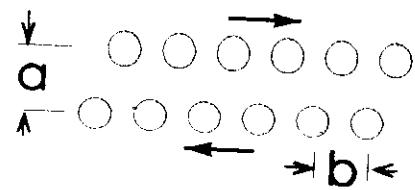
A DC current was applied to the superconducting wire. The wire, submerged in the helium crystal, moved. The difference in the induced voltage, between the cell and the reference coils is plotted here, calibrated to distance units. The current direction was periodically changed so that the drift could be subtracted.



The Velocity Dependence on the Applied Force



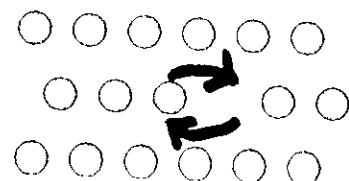
How can one move through the crystal?
Glide of one plane other the over??



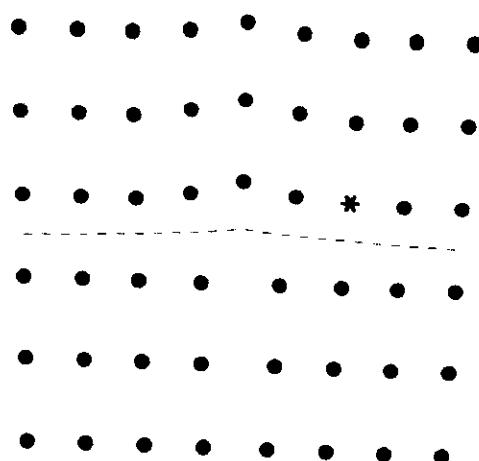
NO! - The stress needed is too high.

$$\sigma_m = \frac{b \mu}{a 2\pi}$$

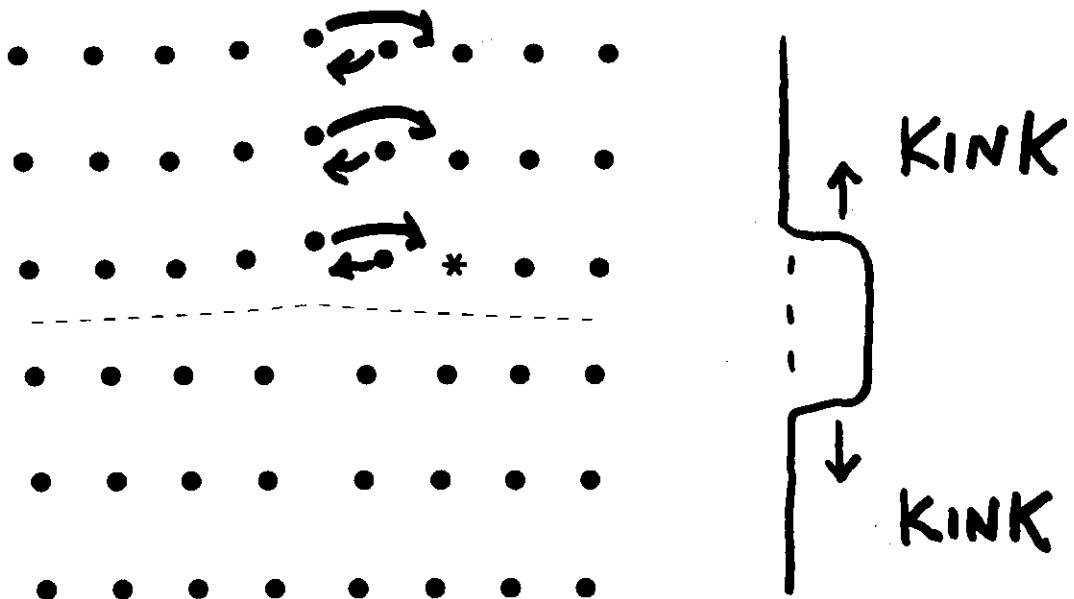
Instead of the whole plane, move a single atom-*Vacancies* mechanism. This leads to strain rate linear in the stress.



Or move a row of atoms- *Dislocation* mechanism.

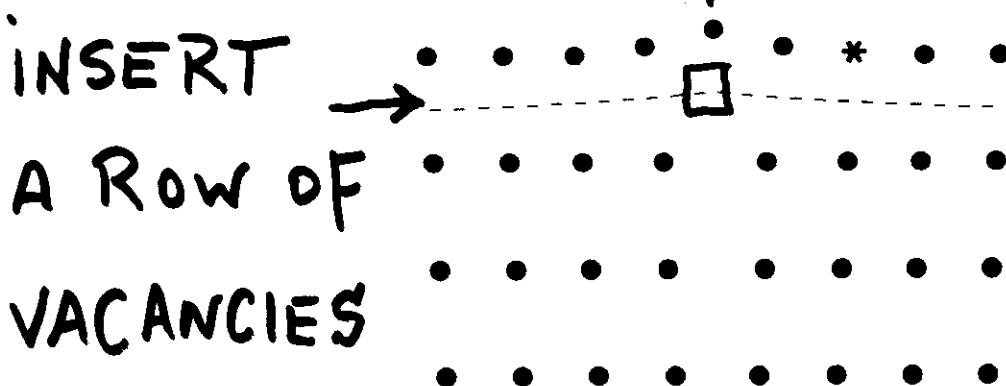


GLIDE - V is EXPONENTIAL in FORCE



CLIMB - V is SOME POWER LAW

OF FORCE



BOTH MECHANISMS HAVE AN ACTIVATION ENERGY

LINEAR DEPENDENCE (VACANCIES)

$$\vec{v} = \frac{D}{\rho R kT} \vec{F}$$

(STOKES LAW)

EXPONENTIAL DEPENDENCE (DISLOCATION GLIDE)

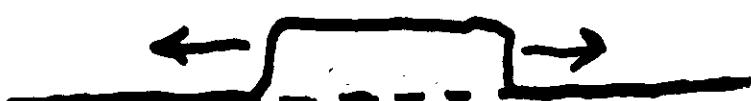
$$\vec{v} \propto \exp(-U_0(1 - \frac{F}{F_p})^2/kT)$$

(SORT OF ANDERSON-KIM CREEP MODEL)

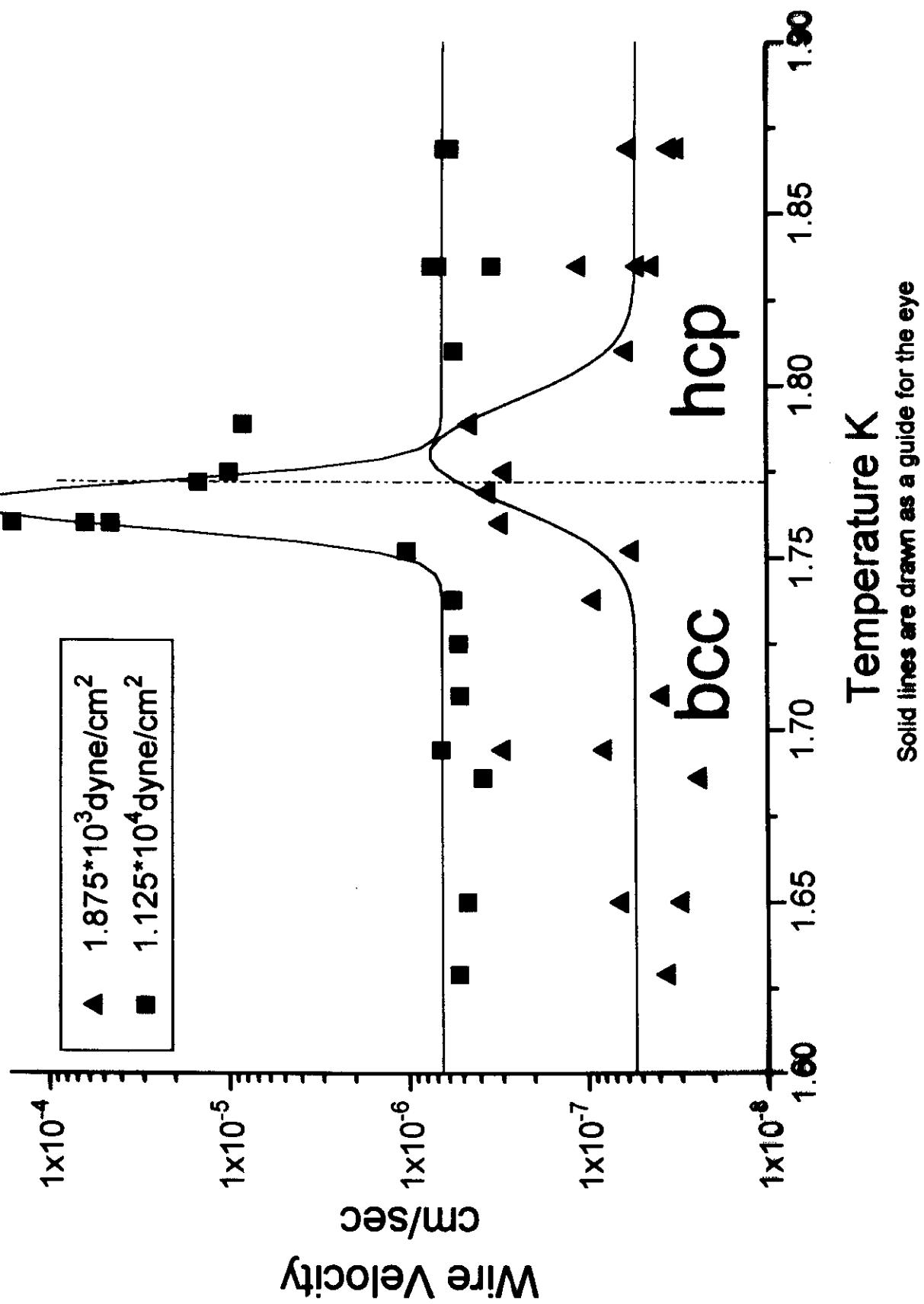


F_p - PEIERLS (PINNING) FORCE

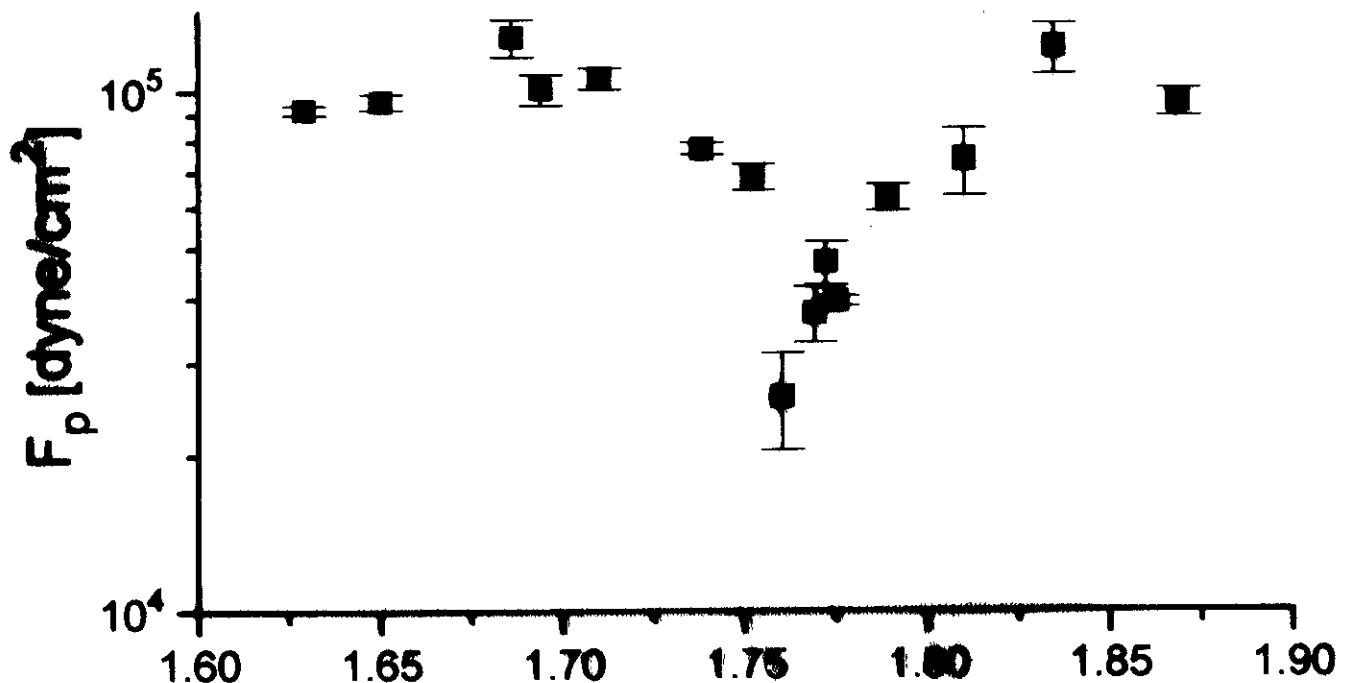
U_0 - ACTIVATION ENERGY OF A PAIR OF KINKS



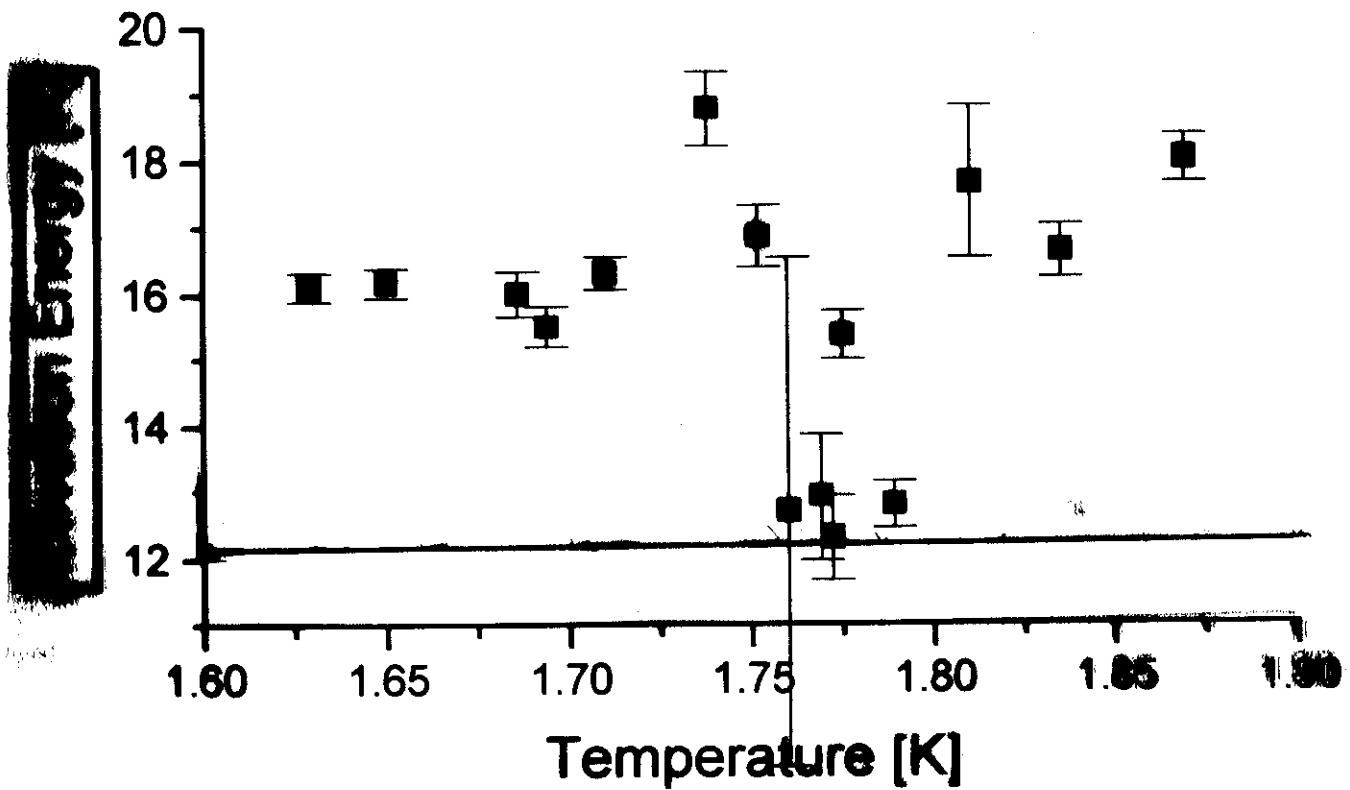
Wire Velocity at different Temperatures



Peierls Force vs Temperature



Activation Energy vs Temperature



CONCLUSIONS

1. PLASTIC PROPERTIES CAN EXHIBIT SOMETHING RESEMBLING "Critical Behaviour" NEAR A 1ST ORDER PHASE TRANSITION.
2. MORE THAN ONE TYPE OF DEFECT is RESPONSIBLE FOR THIS BEHAVIOUR.
3. THE NATURE OF THE NON-LINEAR BEHAVIOUR (VS. TEMPERATURE) REMAINS A PUZZLE.