FAMILIES OF INITIAL DATA FOR BINARY BLACK HOLES



Philippe Grandclément

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PART I : INTRODUCTION AND TOPOLOGIES

3+1 DECOMPOSITION

Decomposition of space-time into space **AND** time.

Metric is given by :

$$\mathrm{d}s^2 = -\left(N^2 - N^i N_j\right) \mathrm{d}t^2 + 2N_i \mathrm{d}t \mathrm{d}x^i + \gamma_{ij} \mathrm{d}x^i \mathrm{d}x^j$$

- Lapse N: choice of time coordinate.
- Shift \vec{N} : choice of spatial coordinates.
- Spatial projection of the metric γ_{ij} .

Second fundamental form **extrinsic curvature tensor** :

$$K_{ij} = -\frac{1}{2}\mathcal{L}_{\mathbf{n}}\gamma_{ij}$$

EINSTEIN'S EQUATIONS IN 3+1 (vacuum case)

| Туре | Einstein | Maxwell |
|-------------|---|--|
| | Hamiltonian $R + K^2 - K_{ij}K^{ij} = 0$ | $ abla \cdot \vec{E} = 0$ |
| Constraints | | |
| | Momentum : $D_j K^{ij} - D^i K = 0$ | $ abla \cdot ec B = 0$ |
| | $\frac{\partial \gamma_{ij}}{\partial t} - \mathcal{L}_{\vec{N}} \gamma_{ij} = -2NK_{ij}$ | $\frac{\partial \vec{E}}{\partial t} = \frac{1}{\varepsilon_0 \mu_0} \left(\vec{\nabla} \times \vec{B} \right)$ |
| Evolution | | |
| | $\frac{\partial K_{ij}}{\partial t} - \mathcal{L}_{\vec{N}} K_{ij} = -D_i D_j N) +$ | $rac{\partial ec{B}}{\partial t} = -ec{ abla} 	imes ec{E}$ |
| | $N\left(R_{ij} - 2K_{ik}K_j^k + KK_{ij}\right)$ | |

 R_{ij} Ricci tensor associated with γ_{ij} .

 D_i is covariant derivative with respect to γ_{ij} .

INITIAL DATA PROBLEM

Solving the initial value problem is as hard as doing the evolution.

One has to give γ_{ij} (t = 0) and K_{ij} (t = 0) verifying :

 $R - K^{ij}K_{ij} + K^2 = 0$

$$D_j \left[K^{ij} - K\gamma^{ij} \right] = 0$$

But ...

- There exist a lot of solutions.
- How can we precise the physical content of such solutions ?

CONFORMALLY FLAT SOLUTIONS

$$\gamma_{ij} = \Psi^4 f_{ij}$$

Properties :

- exact at 1 PN.
- small deviation for binary neutron stars (2%).
- false for extreme Kerr.

With maximum slicing (K = 0):

$$\Delta \Psi = -\frac{1}{8} \Psi^{-7} \hat{K}_{ij} \hat{K}^{ij}$$

$$\bar{D}_i \hat{K}^{ij} = 0$$

where $K_{ij} = \Psi^{-2} \hat{K}_{ij}$ and $K^{ij} = \Psi^{10} \hat{K}^{ij}$.

INITIALLY STATIC SOLUTIONS

Solutions with $\hat{K}_{ij} = 0$

Only has to solve for the Hamiltonian constraint : $\Delta \Psi = 0$ Additional conditions :

- Signature of $g_{\mu\nu}$ implies that $\Psi > 0$.
- Asymptotical flatness : $\Psi \to 1$ when $r \to \infty$

Several solutions, even for two black holes...

BRILL-LINDQUIST TOPOLOGY

D.R. Brill and R.W. Lindquist, *Phys. Rev.* **131**, 471 (1963).

 Ψ singular function at two points :

$$\Psi = 1 + \frac{\alpha_1}{||\vec{r} - \vec{c_1}||} + \frac{\alpha_2}{||\vec{r} - \vec{c_2}||}$$

Three asymptotically flat regions : • mass $m = 2(\alpha_1 + \alpha_2)$ when $r \to \infty$. • mass $m_1 = 2\alpha_1 \left(1 + \frac{\alpha_2}{c_{12}}\right)$ when $\vec{r} \to \vec{c_1}$. • mass $m_2 = 2\alpha_1 \left(1 + \frac{\alpha_1}{c_{12}}\right)$ when $\vec{r} \to \vec{c_2}$. with $c_{12} = ||\vec{c_1} - \vec{c_2}||$. The masses are defined by $\Psi \to 1 + \frac{m}{2r}$.



INVERSION-SYMMETRIC SOLUTION

Define two spheres centered on $\vec{c_i}$ of radii a_i .

Inversion with respect to a sphere is define by :

$$M\left(r_{i}, \theta_{i}, \varphi_{i}\right) \rightarrow J\left(M\right)\left(\frac{a_{i}^{2}}{r_{i}}, \theta_{i}, \varphi_{i}\right)$$



Choice of topology : the three metric is isometric with respect to both J_i . It is equivalent to imposing the following boundary condition on the spheres :

$$\frac{\partial \Psi}{\partial r_i} + \frac{1}{2a_i} \Psi \bigg|_{r_i = a_1} = 0$$

MISNER-LINDQUIST SOLUTION

C.W. Misner, Ann. Phys. 24, 102 (1963).

R.W. Lindquist, J. Math. Phys. 4, 938 (1963).

The isometric Ψ is given by :

$$\Psi = 1 + \sum_{n=1}^{\infty} c_n \left(\frac{1}{\left| \left| \vec{r} - \vec{d_n} \right| \right|} + \frac{1}{\left| \left| \vec{r} + \vec{d_n} \right| \right|} \right)$$

where c_n and d_n depends explicitly on $\vec{c_i}$ and a_i .

Two asymptotically flat regions :

- mass $m = 4 \sum_{n=1}^{\infty} c_n$ when $r \to \infty$.
- regions $\vec{r} \to \vec{c_1}$ and $\vec{r} \to \vec{c_2}$ coincides (because of the inversion) and have also the mass m



PART II : CONFORMAL TT DECOMPOSITIONS

"FREELY" SPECIFIABLE VARIABLES

The 3-metric and the extrinsic curvature tensor are written as :

$$\gamma_{ij} = \Psi^4 \tilde{\gamma}_{ij}$$

$$K^{ij} = \Psi^{10} \hat{K}^{ij} = \Psi^{-10} \left[\tilde{A}^{ij}_{\rm TT} + (LX)^{ij} \right] + \frac{1}{3} \gamma^{ij} K$$

where $(LX)^{ij} = D^i X^j + D^j X^i - \frac{2}{3} \gamma^{ij} D_k X^k$

One can pick any choice for :

- the conformal metric $\tilde{\gamma}_{ij}$.
- the trace K.
- the transverse traceless part \tilde{A}_{TT}^{ij}

The constraints give elliptic equations for Ψ and \vec{X} .

BOWEN-YORK EXTRINSIC CURVATURE TENSOR

Assumptions :

- conformal flatness : $\tilde{\gamma}_{ij} = f_{ij}$.
- maximum slicing : K = 0.
- purely longitudinal K_{ij} : $\tilde{A}_{TT}^{ij} = 0$.

Existence of analytical solution for K_{ij} :

$$\hat{K}_{ij}\left(\vec{P}\right) = \frac{3}{2r^2} \left[P_i n_j + P_j n_i - (f_{ij} - n_i n_j) P^k n_k \right] \Longrightarrow \text{global impulsion } \vec{P}$$

and

$$\hat{K}_{ij}\left(\vec{S}\right) = \frac{3}{r^3} \left[\epsilon_{kil} S^l n^k n_j + \epsilon_{kjl} S^l n^k n_i\right] \Longrightarrow \text{global momentum } \vec{S}$$

 \vec{n} is a radial unit vector field.

J.M. Bowen, Gen. Relativ. Gravit. **11**, 227 (1979); J.M. Bowen and J.W. York, Phys. Rev. D **21**, 2047 (1980); A.D. Kulkarni, L.C. Shepley and J.M. York, Phys. Lett. A **96**, 228 (1983).

TWO BLACK HOLES

For two black holes, one can use a sum of the form :

$$\hat{K}_{ij} = \hat{K}_{1ij} \left(\vec{P}_1 \right) + \hat{K}_{2ij} \left(\vec{P}_2 \right) + \hat{K}_{1ij} \left(\vec{S}_1 \right) + \hat{K}_{2ij} \left(\vec{S}_2 \right)$$

recall that $\overline{D}_i \hat{K}^{ij} = 0$ is linear.

As we are interested in circular orbits, we will choose $\vec{P}_1 + \vec{P}_2 = \vec{0}$.

THE PUNCTURE METHOD

Extension of **Brill-Lindquist** topology :

- Use directly the previous sum centered on two points.
- Impose singularities at those two points by imposing :

$$\Psi = \left[\frac{\alpha_1}{||\vec{r} - \vec{c}_1||} + \frac{\alpha_2}{||\vec{r} - \vec{c}_2||}\right]^{-1} + u$$

• then solve the Hamiltonian constraint for u, which is regular everywhere.

T.W. Baumgarte, *Phys. Rev. D* **62**, 024018 (2000).

S. Brandt and B. Brügmann, *Phys. Rev. Lett.* 78, 3606 (1997).

CONFORMAL IMAGING APPROACH

Extension of the **Misner-Lindquist** topology :

- Use a symmetric version of the extrinsic curvature tensor.
- Solve the Hamiltonian constrain by imposing boundary conditions on the two spheres.
- In this case the spheres are apparent horizons.

G.B. Cook, *Phys. Rev. D* **50**, 5025 (1994).

H.P. Pfeiffer, S.A. Teukolsky and G.B. Cook, *Phys. Rev. D* 62, 104018 (2000).

EFFECTIVE POTENTIAL METHOD

Remaining question : What value of \vec{P} should be used to get circular orbits ? Define a potential (binding energy) $V = \frac{M_{ADM} - m}{\mu}$. Bare mass m is **NOT** well define in GR.

Utilization of Christodoulou formula :

$$m_i = M_{\rm ir} + \frac{S_i}{4M_{\rm ir}}$$

where $M_{\rm ir}$ is the irreducible mass :

$$M_{\rm ir} = \sqrt{\frac{A}{16\pi}}$$

A being the area of the *apparent* horizon of the holes.

 \vec{P} is chosen so that $\frac{\partial V}{\partial P} = 0.$

First law of BH thermodynamics, along a sequence

 $\delta M = \Omega \delta J$



doing the evolution...

THE SUSPECTS

Several questionable steps :

- conformal flatness
 - certainly an issue.
 - has long been held responsible.
- choice of the extrinsic curvature tensor : Bowen-York ansatz.
 - likely to be the most important difference.
- Use of effective potential method
 - ambiguous definition of the individual masses.
 - use of Christodoulou formula
 - unlikely because also used by PN.
 - validity tested on some simple analytic cases.

KERR-SCHILD INITIAL DATA

In Kerr-Schild coordinates it is easy to apply a Lorentz boost to the BH.

Idea : use a superposition of two boosted Kerr-Schild black holes for the freely specifiable variables.

For example :

$\tilde{\gamma_{ij}} = f_{ij} + 2B_1H_1l_{1i}l_{1j} + 2B_2H_2l_{12i}l_{2j}$

where H_i and \vec{l}_i are given by the Kerr-Schild coordinates, for one BH.

The functions B_i are attenuation functions, that ensures that, near the holes the geometry is identical to a single Kerr BH.

Solve for Ψ and \vec{X} (conformal TT decomposition) to obtain a solution of the constraints.

P. Marronetti, M.F. Huq, P. Laguna, L. Lehnerm, R.A. Matzner and D.
Shoemaker, *Phys. Rev. D* 62, 024017 (2000); P. Marronetti and R.A. Matzner, *Phys. Rev. Lett.* 85, 5500 (2000); R.A. Matzner, M.F. Huq and D. Shoemaker, *Phys. Rev. D* 59, 024015 (1999).



Not conformally flat and used in some evolutionary codes but no sequences published and no circular orbits found

"PN-BASED" INITIAL DATA

- Choose the "freely" specifiable variables by using their post-Newtonian expressions (not conformally flat).
- Use a version of the conformal TT decomposition to solve the constraints.

In general, the agreement with PN, at the end of the procedure is bad.



PART III: AN HELICAL KILLING VECTOR APPROACH a.k.a. THE THIN-SANDWICH DECOMPOSITION a.k.a THE MEUDON INITIAL DATA

E. Gourgoulhon, P. Grandclément and S. Bonazolla, *Phys. Rev. D* **65**, 044020 (2002).

P. Grandclément, E. Gourgoulhon and S. Bonazolla, *Phys. Rev. D* **65**, 044021 (2002).



HELICAL KILLING VECTOR

Circular orbits \implies Helical Killing vector \vec{l} .

Advance δt in time \iff Rotation of $\delta \varphi = \Omega \delta t$.

Inertial coordinates :

$$l^{\alpha} = \left(\frac{\partial}{\partial t}\right)^{\alpha} + \Omega \left(\frac{\partial}{\partial \varphi}\right)^{\alpha}$$

Corotating coordinates :

- such as $l^{\alpha} = \left(\frac{\partial}{\partial t}\right)^{\alpha}$.
- coordinate t is ignorable.
- corotating shift $\beta^i = N^i + \Omega \left(\frac{\partial}{\partial \varphi}\right)^i$.
- functions N and γ_{ij} are the same.



ELLIPTIC EQUATIONS

Additional hypothesis : K = 0 and $\tilde{\gamma}_{ij} = f_{ij}$.

We solve 5 of the 10 Einstein's equations :

- Hamiltonian constraint : $\Delta \Psi = -\frac{\Psi^5}{8} \hat{A}_{ij} \hat{A}^{ij}$
- Momentum constraints : $\Delta \beta^i + \frac{1}{3} \bar{D}^i \bar{D}_j \beta^j = 2 \hat{A}^{ij} \left(\bar{D}_j N 6N \bar{D}_j \ln \Psi \right)$
- Trace of $\frac{\partial K_{ij}}{\partial t}$: $\Delta N = N\Psi^4 \hat{A}_{ij} \hat{A}^{ij} 2\bar{D}_j \ln \Psi \bar{D}^j N$

with $\hat{A}_{ij} = \Psi^{-4} K_{ij}$ and $\hat{A}^{ij} = \Psi^4 K^{ij}$.

Definition of $\mathbf{K} \Longrightarrow \hat{A}^{ij} = \frac{1}{2N} \left(L\beta \right)^{ij}$

 $(L\beta)^{ij}$ is the conformal Killing operator : $(L\beta)^{ij} = \bar{D}^i\beta^j + \bar{D}^j\beta^i - \frac{2}{3}\bar{D}_k\beta^k f^{ij}$

Set of 5 non-linear, highly-coupled, elliptic equations.

THE THIN-SANDWICH FORMULATION

Decomposition **different** from the conformal TT.

$$\gamma_{ij} = \Psi^4 \tilde{\gamma}_{ij}$$

$$K^{ij} = \Psi^{-4} \left[\frac{\left(L\beta\right)^{ij} - \tilde{u}^{ij}}{2N} \right] - \frac{1}{3}\gamma^{ij}K$$

"Freely" specifiable variables : $K, \dot{K}, \tilde{u}^{ij}$ and $\tilde{\gamma}^{ij}$.

- Maximum slicing K = 0.
- If we evolve the initial data with lapse N and shift $\vec{\beta}$, then : $-\partial_t \gamma^{\tilde{i}j} = \tilde{u}^{ij} \Longrightarrow \tilde{u}^{ij} = 0.$
 - $-\partial_t K = 0 \Longrightarrow$ same equation for N.
- Conformal flatness : $\tilde{\gamma}_{ij} = f_{ij}$.

The solve for Ψ and $\vec{\beta}$ to verify the constraints \implies same equations than before.

COMPARING THE TWO DECOMPOSITIONS

- Conformal TT : choose the momentum via $\tilde{A}_{TT}^{ij} \Longrightarrow$ Hamiltonian representation.
- Thin sandwich : choose velocity $\partial_t \tilde{\gamma}_{ij} \Longrightarrow$ Lagrangian representation.

The thin-sandwich formulation is better suited for quasi-equilibrium data. H.P. Pfeiffer and J.W. York, *Phys. Rev. D* 67, 044022 (2003).

CHOICE OF TOPOLOGY

Extension of Misner-Lindquist.

Boundary condition on the throats (isometry conditions) :

• Lapse : antisymmetric choice

 $N|_S = 0$

• Conformal factor

$$\left(\frac{\partial\Psi}{\partial r} + \frac{\Psi}{2r}\right)\Big|_{S} = 0$$

• **shift vector** : COROTATION (rigidity theorem)

$$\left. \vec{\beta} \right|_S = 0$$

The throats are Killing \mathbf{AND} apparent horizons.

ASYMPTOTIC FLATNESS

At infinity we recover Minkowski space-time :

 $N \to 1$ when $r \to \infty$

 $\Psi \rightarrow 1$ when $r \rightarrow \infty$

$$ec{eta}
ightarrow \Omega rac{\partial}{\partial arphi} \quad ext{when} \quad r
ightarrow \infty$$

ISOMETRY AND REGULARITY

To have a regular \mathbf{K} :

$$\begin{array}{ccc} \hat{A}^{ij} & = & \displaystyle \frac{(L\beta)^{ij}}{2N} \\ N|_{S_i} & = & \displaystyle 0 \end{array} \end{array} \right\} \Longrightarrow (L\beta)^{ij} \Big|_{S_i} = 0.$$

One can show that to have **RIGIDITY**, **REGULARITY** and **ISOMETRY** one must have :

$$\left. egin{array}{ccc} ec{eta} & = & 0 \\ \partial_r ec{eta} & = & 0 \end{array}
ight. \ = & 0 \end{array}$$

REGULARIZATION OF THE SHIFT

One solves for $\vec{\beta}$, using Dirichlet-type boundary condition :

 $\left. \vec{\beta} \right|_{S_i} = 0$

At each iteration one modifies the shift vector by :

$$\vec{eta}_{
m new} = \vec{eta} + \vec{eta}_{
m cor}$$

 $\vec{\beta}_{cor}$ is chosen so that :

$$\begin{array}{ccc} \vec{\beta}_{\mathrm{new}} \Big|_{S_i} &= & 0 \\ \partial_r \vec{\beta}_{\mathrm{new}} \Big|_{S_i} &= & 0. \end{array}$$

At the end of a calculation :

- if $\vec{\beta}_{cor} \to 0$: exact solution.
- if $\vec{\beta}_{cor}$ is small : approximate solution.
- else not a solution !

DETERMINATION OF Ω

 Ω only present in the boundary condition for $\vec{\beta}$.

One can solve for ANY value of Ω (example : $\Omega = 0 \implies$ Misner-Lindquist).

SUPPLEMENTARY CONDITION : the $O(r^{-1})$ part of the metric when $(r \to \infty)$ is identical to Schwarzschild.

A priori : $\Psi \sim 1 + \frac{M_{\text{ADM}}}{2r}$ and $N \sim 1 - \frac{M_{\text{K}}}{r}$

One chooses the **ONLY** Ω such that : $M_{\rm K} = M_{\rm ADM} \iff \Psi^2 N \sim 1 + \frac{\alpha}{r^2}$ Justifications :

- exact stationary asymptotical space-times.
- Newtonian limit \implies virial theorem.
- True for binary neutron stars.





PART IV: WHAT IS NEXT ?



NEW BOUNDARY CONDITIONS ON THE HOLES

Cook proposed to relax the symmetry boundary conditions and to replace them by demanding that :

- the throats are apparent horizons $\implies \tilde{s}^k \tilde{\nabla}_k \ln \Psi \Big|_S = -\frac{1}{4} \left(\tilde{h}^{ij} \tilde{\nabla}_i \tilde{s}_j \Psi^2 J \right) \Big|_S$
- the remain apparent horizons (Killing vector tangent to the surfaces) $\Longrightarrow \beta^i |_S = N \Psi^{-2} \tilde{s}^i |_S$ (corotation).

No condition for the lapse.

If we choose spheres and $N|_S = 0$ then we obtained the same equations than the one used by the Meudon group.

The "new" boundary conditions are just more general and would admit $N|_S \neq 0$ \implies no regularity problem.

G.B. Cook, *Phys. Rev. D* **65**, 084003 (2002)



RELAXING THE EFFECTIVE POTENTIAL METHOD

Proposition :

- Apply the standard puncture method with the conformal TT decomposition of K_{ij} .
- Determine a lapse by solving $\partial_t K = 0$.
- Determine a shift by solving $\partial_t \gamma_{ij} = 0$.
- Determination of Ω and puncture parameters via criterium similar to $M_{\rm ADM} = M_{\rm K}.$

Good test of the validity of the effective potential method to determine Ω .

W. Tichy, B. Brügmann and P. Laguna, gr-qc/0306020.

W. Tichy and B. Brügmann, gr-qc/0307627.



REVISITING THE PUNCTURE

In order to combine the puncture method and the thin-sandwich formulation one would need :

- quasi-stationary coordinates (stationary slicing).
- asymptotically flat regions near the puncture.
- Positive lapse everywhere N > 0.

Hannam *et al.* have shown that those conditions can **NOT** be verified, even for a single Schwarzschild black hole.

The puncture method seems to lose its appeal in the thin-sandwich frame-work.

M.D. Hannam, C.R. Evans, G.B. Cook and T.W. Baumgarte, gr-qc/0306028.

CONCLUDING REMARKS

Conclusions :

- The main difference between initial data is the choice of extrinsic curvature tensor.
- The thin-sandwich formulation is better suited for quasi-equilibrium sequences.
- First good agreement between PN and numerical results.

Still to be done :

- Use apparent horizon boundary conditions.
- Remove conformal flatness, possibly making use of the other Einstein's equations.
- Assess the quality of the initial data by evolving them.