
General Relativistic Numerical Simulation on Coalescing Binary Neutron Stars

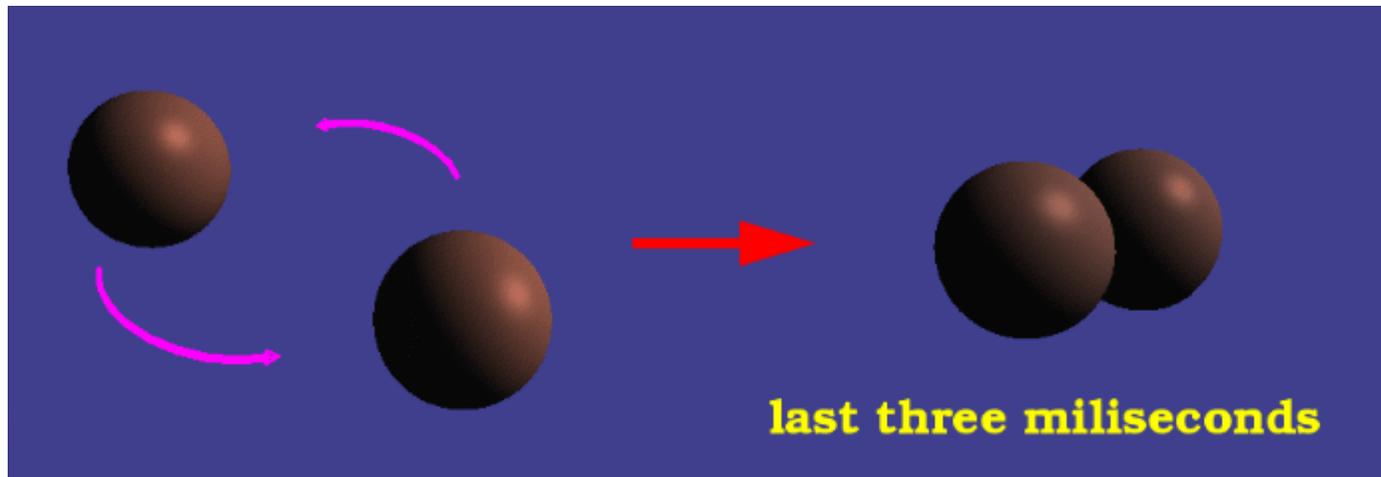
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Introduction

- We are construction computer codes on 3D numerical relativity.
- The main target is to study the evolution of coalescing binary neutron stars and the radiation of gravitational waves from the merger.



Basic Equations

- We write the 4D metric as

$$ds^2 = -\alpha^2 dt^2 + \gamma_{ij}(\mathbf{dx}^i + \beta^i dt)(\mathbf{dx}^j + \beta^j dt)$$

α : the lapse function

β^i : the shift vector

γ_{ij} : the intrinsic metric of 3-space

- Hamiltonian constraint

$$R + K^2 - K_{ij}K^{ij} = 16\pi\rho_H$$

- Momentum constraint

$$D_j(K^j_i - \delta^j_i K) = 8\pi J_i$$

■ The evolution equations

$$\partial_t \gamma_{ij} = -2\alpha \mathbf{K}_{ij} + D_i \beta_j + D_j \beta_i$$

$$\begin{aligned} \partial_t \mathbf{K}_{ij} = & \alpha \left[\mathbf{R}_{ij} - 8\pi \left\{ \mathbf{S}_{ij} + \frac{1}{2} (\rho_H - \mathbf{S}^k_k) \right\} \right] - D_i D_j \alpha \\ & + \alpha (\mathbf{K} \mathbf{K}_{ij} - 2 \mathbf{K}_{ik} \mathbf{K}^k_j) + \mathbf{K}_{ik} D_j \beta^k + \mathbf{K}_{jk} D_i \beta^k + \beta^k D_k \mathbf{K}_{ij} \end{aligned}$$

\mathbf{R}_{ij} : the 3-D Ricci tensor, $\mathbf{R} = \gamma^{ij} \mathbf{R}_{ij}$

\mathbf{K}_{ij} : the extrinsic curvature $\mathbf{K} = \gamma^{ij} \mathbf{K}_{ij}$

ρ_H : the energy density

\mathbf{J}_i : the momentum density

\mathbf{S}_{ij} : the stress tensor

measured by the observer moving along the line
normal to the spacelike hypersurface of $t = \text{const.}$

General Relativistic Hydrodynamics Equations

- We assume that the matter is the perfect fluid,

$$T_{\mu\nu} = (\rho + \rho\varepsilon + P)u_\mu u_\nu + Pg_{\mu\nu}$$

where

ρ : the energy density

ε : the specific internal energy (per unit mass)

P : the pressure

measured by the observer moving with the fluid

u_μ : the 4-velocity of the fluid

$$\rho_H = n^\mu n^\nu T_{\mu\nu}, \quad J_i = -h_i^\mu n^\nu T_{\mu\nu}, \quad S_{ij} = h_i^\mu h_j^\nu T_{\mu\nu}$$

where n_μ is the unit timelike normal vector

and $h_{\mu\nu} = g_{\mu\nu} + n_\mu n_\nu$

GR Hydrodynamics Equations (2)

- The relativistic hydrodynamics equations are obtained from $\nabla_{\mu}(\rho \mathbf{u}^{\mu}) = 0$ and $\nabla_{\mu} T^{\mu\nu} = 0$.

- $$\rho_N = \sqrt{\gamma} \alpha \mathbf{u}^0 \rho, \quad \mathbf{u}_i^N = \frac{\mathbf{J}_i}{\alpha \mathbf{u}^0 \rho}, \quad V^i = \frac{\mathbf{u}^i}{\mathbf{u}^0} = \frac{\alpha \mathbf{J}^i}{\mathbf{P} + \rho_H} - \beta^i$$

- ★
$$\partial_t \rho_N + \partial_I(\rho_N V^I) = 0$$

- ★
$$\begin{aligned} \partial_t(\rho_N \mathbf{u}_i^N) + \partial_I(\rho_N \mathbf{u}_i^N V^I) = & -\sqrt{\gamma} \alpha \partial_i \mathbf{P} - \sqrt{\gamma} (\mathbf{P} + \rho_H) \partial_i \alpha \\ & + \frac{\sqrt{\gamma} \alpha \mathbf{J}^k \mathbf{J}^l}{2(\mathbf{P} + \rho_H)} \partial_i \gamma_{kl} + \sqrt{\gamma} \mathbf{J}_I \partial_i \beta^I \end{aligned}$$

- ★
$$\partial_t(\rho_N \varepsilon) + \partial_I(\rho_N \varepsilon V^I) = -\mathbf{P} \partial_{\mu}(\sqrt{\gamma} \alpha \mathbf{u}^{\mu})$$

Evolution Equations of the Metric

- To solve the evolution of the metric tensor, we define the following variables:

$$\phi = \gamma^{\frac{1}{12}}$$

$$\tilde{\gamma}_{ij} = \phi^{-4} \gamma_{ij}$$

$$\tilde{F}^i = \tilde{\gamma}^{ij}{}_{,j}$$

$$\widehat{K}_{ij} = \phi^{-4} (\mathbf{K}_{ij})^{\text{STF}}$$

$$\mathbf{K} = \gamma^{ij} \mathbf{K}_{ij}$$

$$\text{where } (\mathbf{K}_{ij})^{\text{STF}} = \frac{1}{2} \left(\mathbf{K}_{ij} + \mathbf{K}_{ji} - \frac{2}{3} \tilde{\gamma}_{ij} \tilde{\gamma}^{kl} \mathbf{K}_{kl} \right)$$

- $\partial_t \phi - \beta^l \partial_l \phi = -\frac{\phi}{6} (\alpha \mathbf{K} - \partial_l \beta^l)$
- $\partial_t \tilde{\gamma}_{ij} - \beta^l \partial_l \tilde{\gamma}_{ij} = -2 \left[\alpha \widehat{\mathbf{K}}_{ij} - (\tilde{\gamma}_{il} \partial_j \beta^l)^{\text{STF}} \right]$
- $\partial_t \tilde{\mathbf{F}}^i - \beta^l \partial_l \tilde{\mathbf{F}}^i = 2 \partial_j (\alpha \widehat{\mathbf{K}}^{ij}) - \tilde{\gamma}^{jk} \partial_j \partial_k \beta^i - \frac{1}{3} \tilde{\gamma}^{ij} \partial_j \partial_k \beta^k$
- $\partial_t \widehat{\mathbf{K}}_{ij} - \beta^l \partial_l \widehat{\mathbf{K}}_{ij} = \phi^{-4} \left[\alpha (\mathbf{R}_{ij}^{\text{STF}} - 8\pi \mathbf{S}_{ij}^{\text{STF}}) - (\mathbf{D}_i \mathbf{D}_j \alpha)^{\text{STF}} \right]$
 $+ \alpha (\mathbf{K} \widehat{\mathbf{K}}_{ij} - 2 \widehat{\mathbf{K}}_{il} \widehat{\mathbf{K}}^l_j) + \widehat{\mathbf{K}}_{il} \partial_j \beta^l + \widehat{\mathbf{K}}_{jl} \partial_i \beta^l - \frac{2}{3} \widehat{\mathbf{K}}_{ij} \partial_l \beta^l$
- $\partial_t \mathbf{K} - \beta^l \partial_l \mathbf{K} = \alpha \left[\widehat{\mathbf{K}}_{ij} \widehat{\mathbf{K}}^{ij} + \frac{1}{3} \mathbf{K}^2 + 4\pi (\rho_H + \mathbf{S}^i_i) \right] - \mathbf{D}^i \mathbf{D}_i \alpha$

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- Several kinds of the reformulation of the Einstein equation in numerical relativity have been proposed.
 - Our formulation is the simplest one.
 - The motivation to use the formulation is that we encountered numerical instability and suppose that numerical errors in **the second derivatives** of the metric tensor needed to calculate the **Ricci tensor** are likely to cause the instability.
 - We decided to compute \tilde{F}^i as an independent variable and calculate Ricci tensor using it.

Coordinate Conditions

- The choice of the shift β^i and the lapse function α is important because
 - the stability of the code depends on themand
 - it is intimately related to the extraction of physically relevant information such as gravitational radiation.
- The condition

$$\tilde{D}_j(\partial_t \tilde{\gamma}^{ij}) = 0$$

produces the minimal distortion shift vector, but gives an equation too complicated to be solved numerically.

Shift Vector

- Instead we use the *pseudo-minimal distortion condition*;

$$\partial_j(\partial_t \tilde{\gamma}^{ij}) = (\partial_t \tilde{F}^i) = 0$$

- The shift vector β^i obeys

$$\nabla^2 \beta^i + \frac{1}{3} \partial_i \partial_j \beta^j = 2 \partial_j (\alpha \hat{K}^{ij}) - h^{jk} \partial_j \partial_k \beta^i - \frac{1}{3} h^{ij} \partial_j \partial_k \beta^k$$

where $h^{ij} = \tilde{\gamma}^{ij} - \delta^{ij}$

- In this condition, we can simply set

$$\tilde{F}^i = 0 \text{ since } \partial_t \tilde{F}^i = \tilde{F}^i(t=0) = 0.$$

Lapse Function

- As for the slicing condition, we choose the maximal slicing, $K = 0$, which yields

$$D^i D_i \alpha = \alpha \left[\widehat{K}_{ij} \widehat{K}^{ij} + 4\pi(\rho_H + S^i_i) \right]$$

The Conformal Factor ϕ

- The evolution of ϕ is given by

$$\partial_t \phi - \beta^I \partial_I \phi = -\frac{\phi}{6} (\alpha \mathbf{K} - \partial_I \beta^I)$$

- From the Hamiltonian constraint, it obeys

$$\tilde{\Delta} \phi = -\frac{\phi^5}{8} (16\pi\rho_H + \widehat{\mathbf{K}}_{ij} \widehat{\mathbf{K}}^{ij} - \phi^{-4} \tilde{\mathbf{R}})$$

- We first make ϕ evolve using the former equation, then calculate the right-hand side of the latter one and solve it.

The Ricci Tensor

- We must take special care to calculate the Ricci tensor.

$$\mathbf{R}_{ij} = \tilde{\mathbf{R}}_{ij} + \mathbf{R}_{ij}^\phi$$

$$\mathbf{R}_{ij}^\phi = -2\phi^{-1}(\tilde{\mathbf{D}}_j \tilde{\mathbf{D}}_i \phi + \tilde{\gamma}_{ij} \tilde{\Delta} \phi) + 2\phi^{-2} \left[3(\tilde{\mathbf{D}}_i \phi)(\tilde{\mathbf{D}}_j \phi) - \tilde{\gamma}_{ij}(\tilde{\mathbf{D}}_k \phi)(\tilde{\mathbf{D}}^k \phi) \right]$$

$$\tilde{\mathbf{R}}_{ij} = \frac{1}{2} \left[\tilde{\gamma}^{kl} (\tilde{\gamma}_{li,jk} + \tilde{\gamma}_{lj,ik} - \tilde{\gamma}_{ij,kl}) + \tilde{\gamma}^{kl}{}_{,l} (\tilde{\gamma}_{ki,j} + \tilde{\gamma}_{kj,i} - \tilde{\gamma}_{ij,k}) \right] - \tilde{\Gamma}_{li}{}^k \tilde{\Gamma}{}^l{}_{jk}$$

$$= \frac{1}{2} (\tilde{\mathbf{F}}_{i,j} + \tilde{\mathbf{F}}_{j,i} - \tilde{\gamma}^{kl}{}_{,j} \tilde{\gamma}_{il,k} - \tilde{\gamma}^{kl}{}_{,i} \tilde{\gamma}_{jl,k} - \tilde{\gamma}^{kl} \tilde{\gamma}_{ij,kl})$$

$$+ \tilde{\mathbf{F}}^k (\tilde{\gamma}_{ki,j} + \tilde{\gamma}_{kj,i} - \tilde{\gamma}_{ij,k}) - \tilde{\Gamma}_{li}{}^k \tilde{\Gamma}{}^l{}_{jk}$$

$$= -\frac{1}{2} (\tilde{\gamma}^{kl}{}_{,j} \tilde{\gamma}_{il,k} + \tilde{\gamma}^{kl}{}_{,i} \tilde{\gamma}_{jl,k} + \tilde{\gamma}^{kl} \tilde{\gamma}_{ij,kl}) - \tilde{\Gamma}_{li}{}^k \tilde{\Gamma}{}^l{}_{jk} \quad \text{if } \tilde{\mathbf{F}}^i = 0$$

The Ricci Tensor (2)

- $\tilde{\gamma}^{kl} \tilde{\gamma}_{li,jk}$ includes terms such as $\frac{\partial^2 h_{xx}}{\partial x \partial y}$ ($h_{kl} = \tilde{\gamma}_{kl} - \delta_{kl}$)

whose accuracy in numerical calculation is not so good.

- The term $\tilde{\gamma}^{kl} \tilde{\gamma}_{ij,kl} = \frac{\partial^2 h_{ij}}{\partial x^2} + \frac{\partial^2 h_{ij}}{\partial y^2} + \frac{\partial^2 h_{ij}}{\partial z^2} + h^{kl} \frac{\partial^2 h_{ij}}{\partial x^k \partial x^l}$

includes the second derivatives, but inaccuracies in $h^{kl} h_{ij,kl}$ is not so serious, if both h^{kl} and $h_{ij,kl}$ are small.

Boundary Conditions on the Metric

- We apply outgoing conditions for $\tilde{\gamma}_{ij}$ and \widehat{K}_{ij} ;

$$Q(t, \mathbf{x}^i) = \frac{H(\alpha t - \phi^2 r)}{r}, \quad r^2 = \mathbf{x}^2 + \mathbf{y}^2 + \mathbf{z}^2$$

$$\partial_t H + c^i \partial_i H = 0, \quad c^i = \frac{\alpha \mathbf{x}^i}{r \phi^2}$$

$$\partial_t Q + c^i \partial_i Q = -\frac{\alpha}{r \phi^2} Q$$

Numerical Methods

- We solve the hydrodynamics equations using van Leer's scheme with the minmod limiter.
- The evolution equations of the metric are solved using the CIP (Cubic-Interpolated Propagation) method.
- To achieve second-order accuracy both in time as well as in space, we use a two-step predictor-corrector scheme.

$$\partial_t Q = F$$

$$Q(t + \frac{1}{2} \Delta t) = Q(t) + \frac{1}{2} \Delta t \cdot F(t)$$

$$Q(t + \Delta t) = Q(t) + \Delta t \cdot F(t + \frac{1}{2} \Delta t)$$

Elliptic Equations

- $\nabla^2 \phi = \mathbf{S}_\phi$
- $\nabla^2 \alpha = \mathbf{S}_\alpha$
- $\nabla^2 \beta^i + \frac{1}{3} \partial_i \partial_k \beta^k = \mathbf{S}_\beta^i$

They are solved with a pre-conditioned conjugate gradient method.

The most CPU hours are consumed for solving these equations.

- 50% for β
- ~10% for each of α and ϕ

Code Tests (Oscillation of a Spherical Star)

- Put a spherical star of

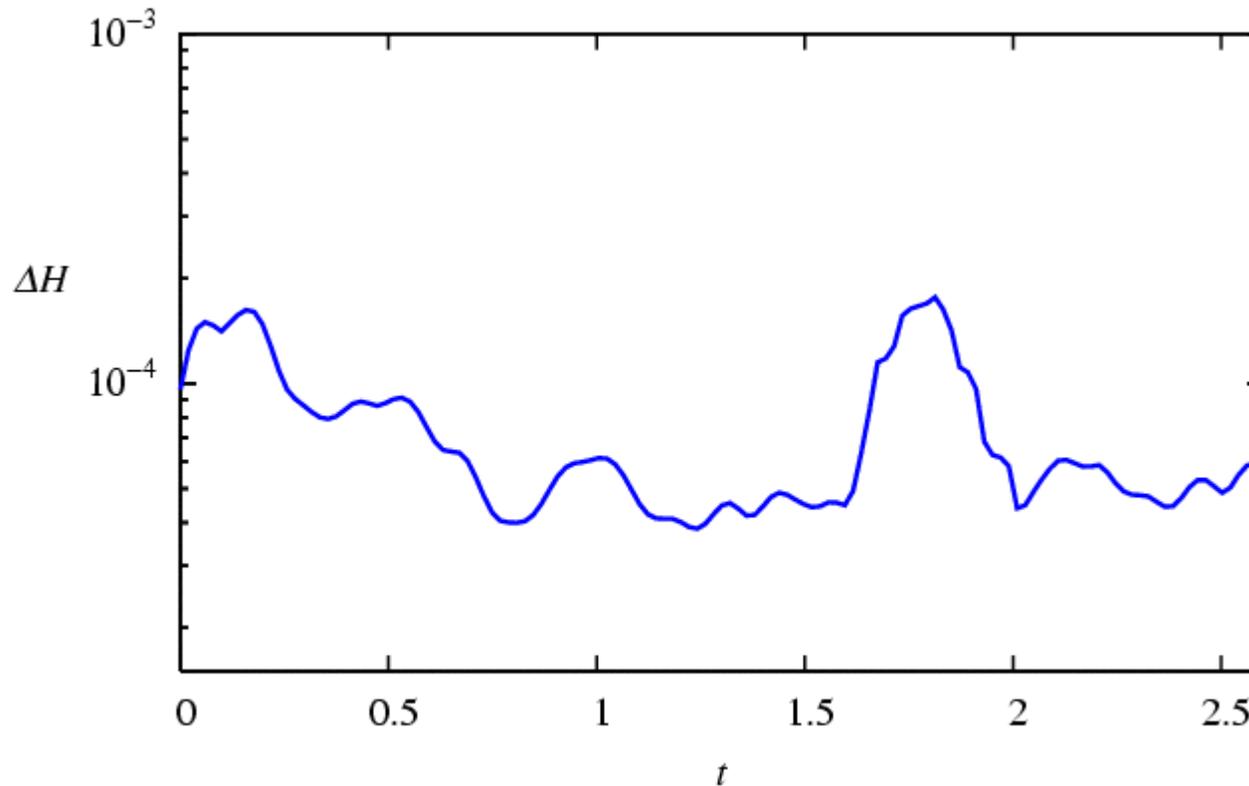
$$M = 1.5 M_{\odot} , \quad R = 7.7 M_{\odot}$$

$$\rho_c = 2.1 \times 10^{-3} M_{\odot}^{-2}$$

$$P = (\Gamma - 1) \rho \varepsilon , \quad \Gamma = 2$$

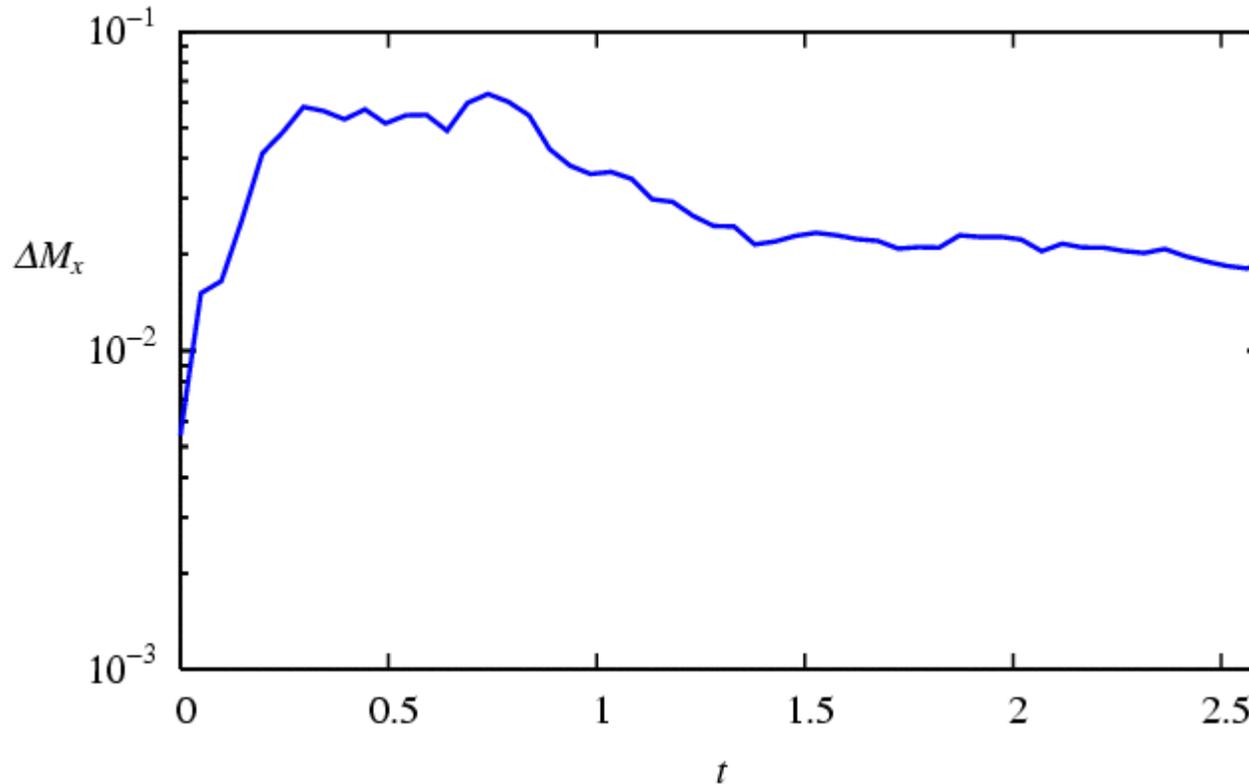
- Reduce the pressure and the star begin to oscillate.

Hamiltonian Constraint



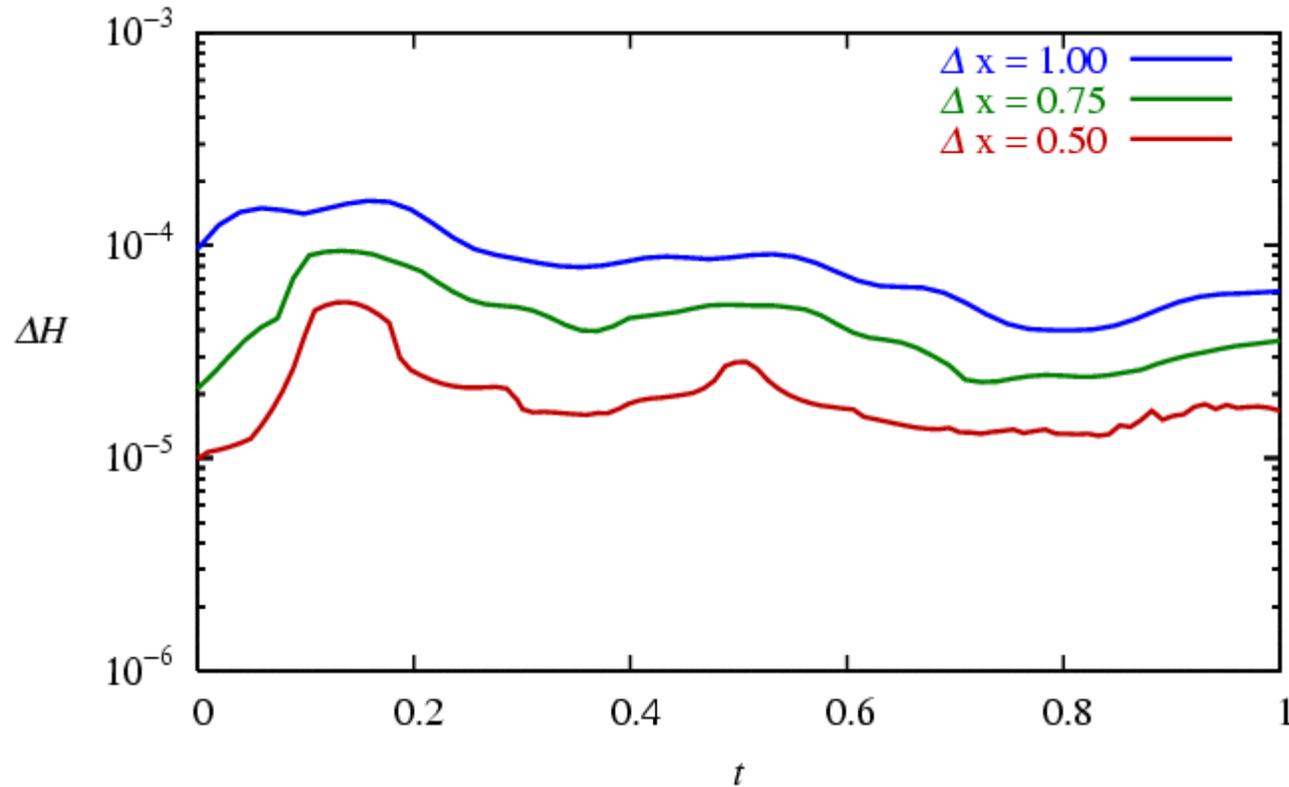
$$\Delta H = \frac{\|R + K^2 - K_{ij}K^{ij} - 16\pi\rho_H\|}{16\pi\|\rho_H\|}$$

Momentum Constraint

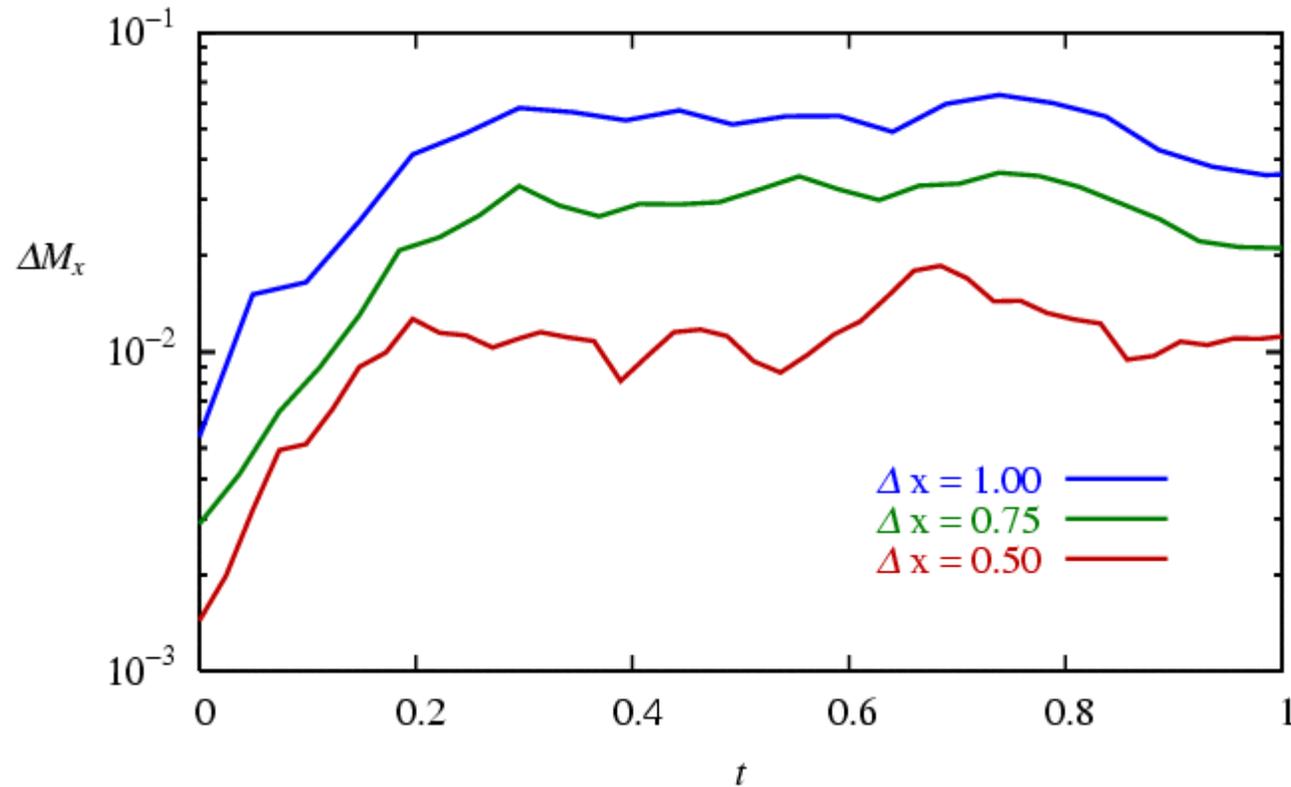


$$\Delta M_i = \frac{\|D_j(K^j_i - \delta^j_i K) - 8\pi J_i\|}{8\pi \sqrt{\|J^2\|}}$$

Convergence Tests (1)

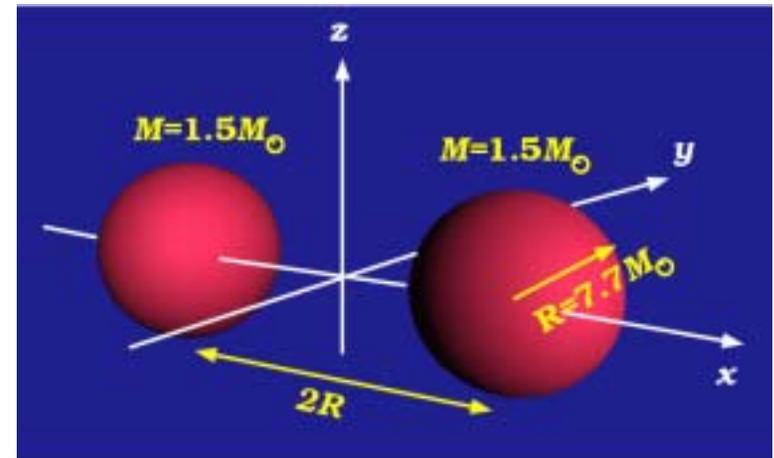


Convergence Tests (2)

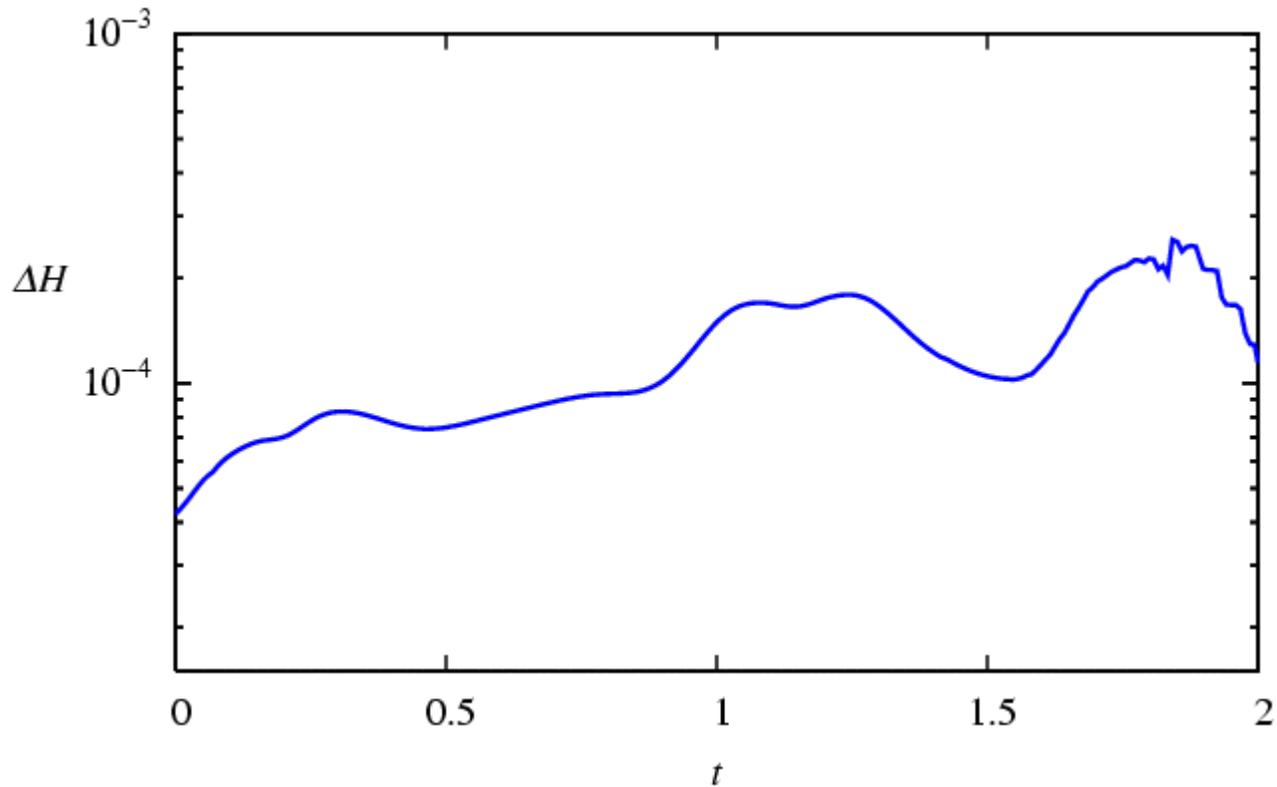


Coalescing Binary Neutron Stars

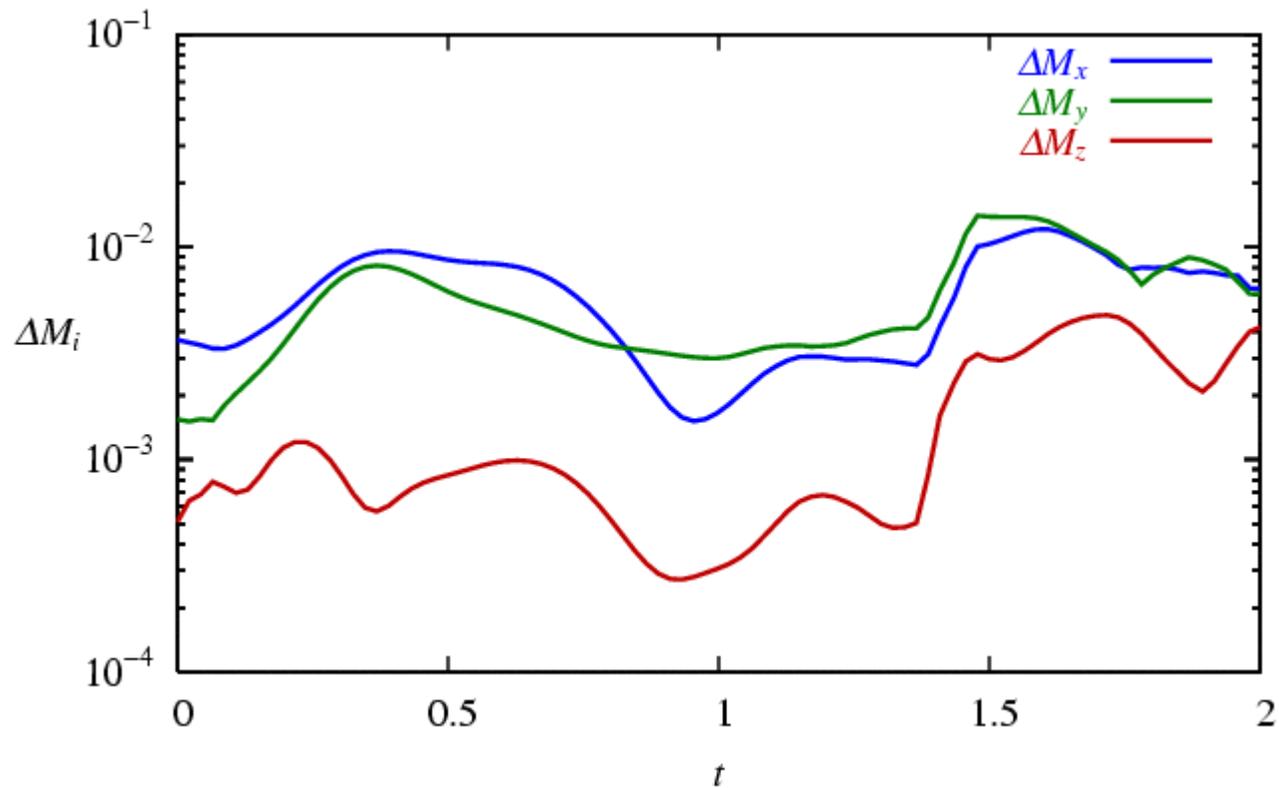
- Grid properties: $475 \times 475 \times 238$, $\Delta x = \Delta y = \Delta z = 1 M_{\odot}$
- We assume the symmetry wrt the equatorial plane.
- Initial data:
 - 2 spherical stars of rest mass $M = 1.5 M_{\odot}$
radius $R = 7.7 G M_{\odot} / c^2 = 11.6 \text{ km}$
located at $x = \pm 2R$, $y = z = 0$
 - The initial rotational velocity is given so that the circulation of the system vanishes.



Hamiltonian Constraint



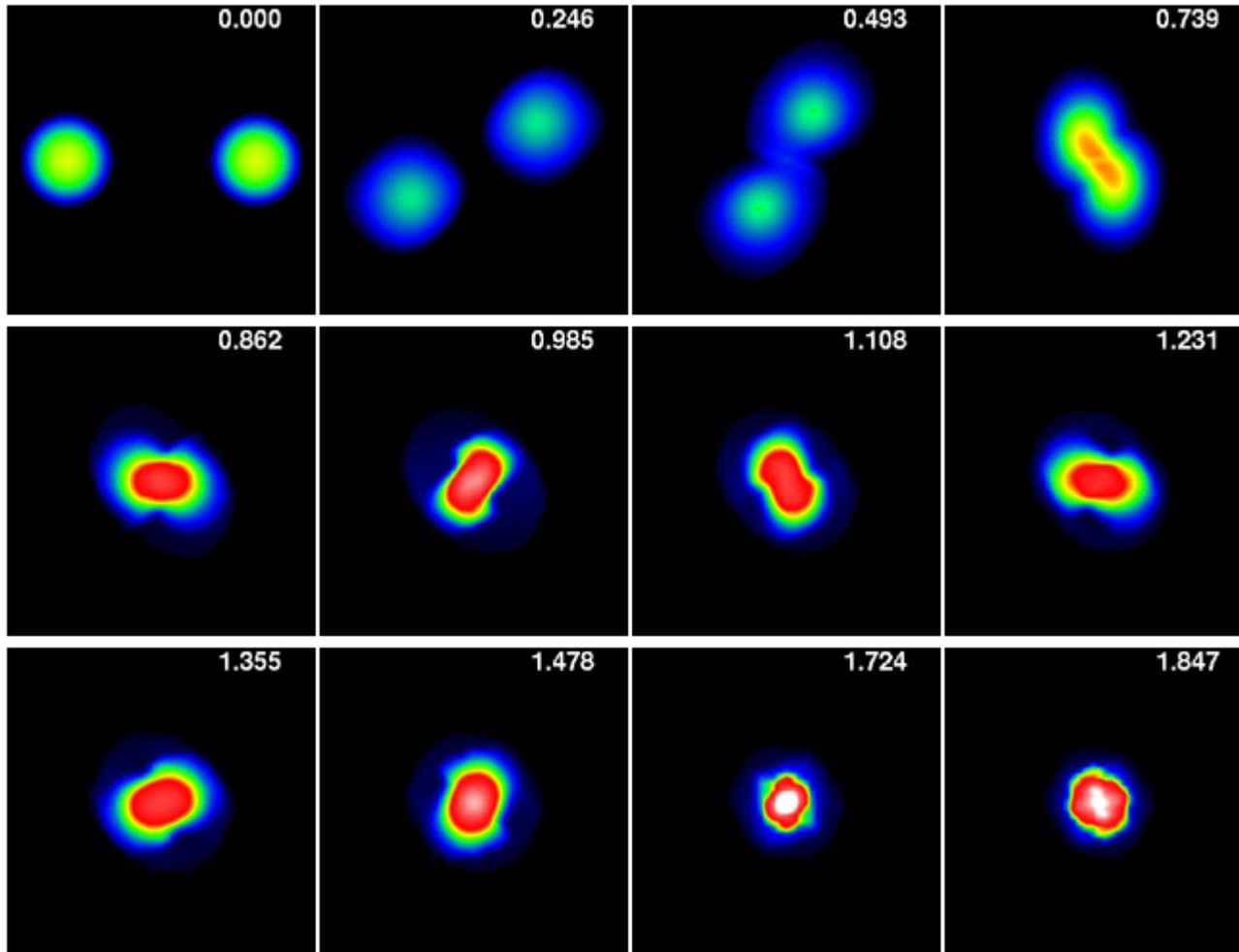
Momentum Constraint



Numerical Precision

- We need not solve for K since we use the maximal slicing, but it is solved to monitor the numerical precision. The value of K is kept as small as 0.1% of the typical value of K_{ij} , but it becomes large from the numerical boundary region in the final stage of simulation. It is due to a small reflection of GW at the numerical boundary.
- Since we use the pseudo-minimal distortion condition, $\tilde{F}^i = \tilde{\gamma}^{ij}{}_{,j}$ must be zero. It is satisfied within a few % of the derivative of γ_{ij} . The error grows in the same way as K in the final stage of simulation.
- The total ADM mass is conserved within 10% error.

Coalescing Binary NS (density ρ)



Gauge-Invariant Wave Form Extraction

- Outside of the star, we consider the total spacetime metric $g_{\mu\nu}$ as a sum of a Schwarzschild metric and non-spherical perturbation parts:

$$g_{\mu\nu} = g_{\mu\nu}^{(B)} + h_{\mu\nu}^{(e)} + h_{\mu\nu}^{(o)}$$

$$g_{\mu\nu}^{(B)} = \begin{pmatrix} -N^2 & 0 & 0 & 0 \\ 0 & A^2 & 0 & 0 \\ 0 & 0 & R^2 & 0 \\ 0 & 0 & 0 & R^2 \sin^2 \theta \end{pmatrix}$$

(in the spherical coordinates)

$$\mathbf{h}_{\mu\nu}^{(e)} = \sum_{l,m} \begin{pmatrix} N^2 H_{0lm} Y_{lm} & H_{1lm} Y_{lm} & h_{0lm}^{(e)} Y_{lm,\theta} & h_{0lm}^{(e)} Y_{lm,\phi} \\ * & A^2 H_{2lm} Y_{lm} & h_{1lm}^{(e)} Y_{lm,\theta} & h_{1lm}^{(e)} Y_{lm,\phi} \\ * & * & r^2 [K_{lm} + G_{lm} \partial_\theta^2] Y_{lm} & r^2 G_{lm} X_{lm} \\ * & * & * & h_{3lm}^{(e)} \end{pmatrix}$$

$$\mathbf{h}_{\mu\nu}^{(o)} = \sum_{l,m} \begin{pmatrix} 0 & 0 & -h_{0lm}^{(o)} Y_{lm,\phi} / \sin \theta & h_{0lm}^{(o)} Y_{lm,\theta} \sin \theta \\ * & 0 & -h_{1lm}^{(o)} Y_{lm,\phi} \sin \theta & h_{1lm}^{(o)} Y_{lm,\theta} \sin \theta \\ * & * & \frac{1}{2} h_{2lm}^{(o)} X_{lm} / \sin \theta & -\frac{1}{2} h_{2lm}^{(o)} W_{lm} \sin \theta \\ * & * & * & -\frac{1}{2} h_{2lm}^{(o)} X_{lm} \sin \theta \end{pmatrix}$$

- From the linearized theory about perturbations of the Schwarzschild spacetime, the gauge invariant quantities are give by

$$\Psi_{lm}^{(o)}(t, r) = \sqrt{2\Lambda(\Lambda - 2)} N^2 \left[\mathbf{h}_{1lm}^{(o)} + \frac{r^2}{2} \frac{\partial}{\partial r} \left(\frac{\mathbf{h}_{2lm}^{(o)}}{r^2} \right) \right]$$

$$\Psi_{lm}^{(e)}(t, r) = -\sqrt{\frac{2(\Lambda - 2)}{\Lambda}} \frac{4rN^2 \mathbf{k}_{2lm} + \Lambda r \mathbf{k}_{1lm}}{(\Lambda + 1 - 3N^2)}$$

$$\Lambda = l(l+1)$$

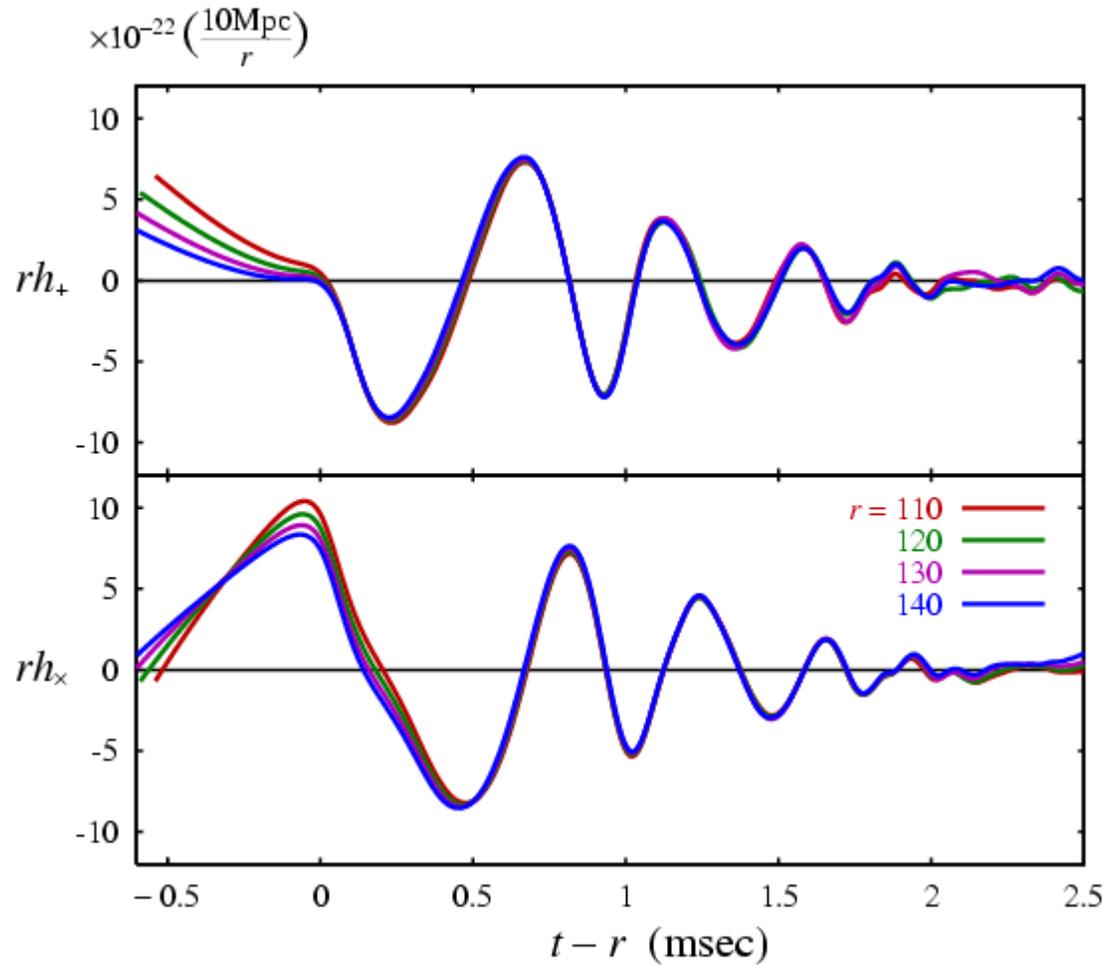
$$\mathbf{k}_{1lm} = \mathbf{K}_{lm} + N^2 r \mathbf{G}_{lm,r} - 2N^2 \mathbf{h}_{1lm}^{(o)} / r$$

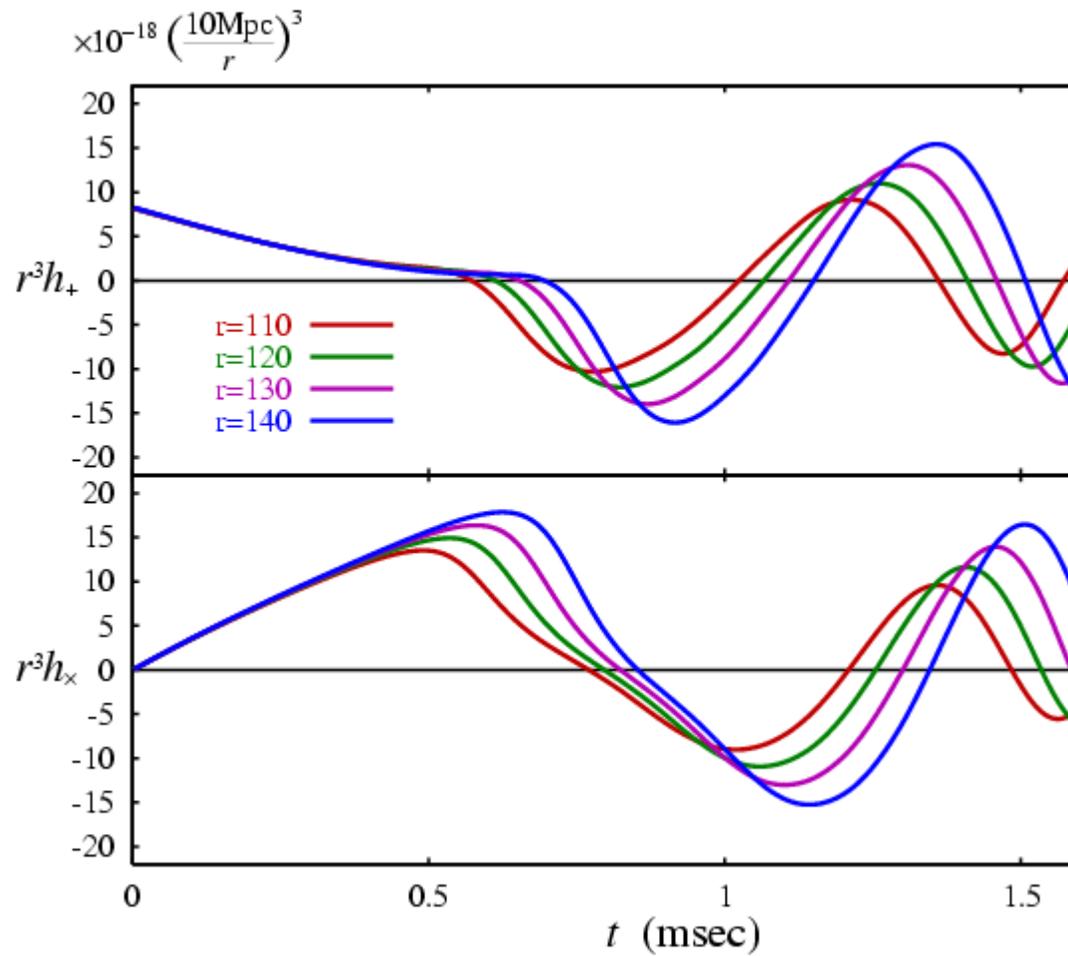
$$\mathbf{k}_{2lm} = \frac{\mathbf{H}_{2lm}}{2N^2} - \frac{1}{\sqrt{N^2}} \frac{\partial}{\partial r} \left(\frac{r}{N^2} \mathbf{K}_{lm} \right)$$

-
- $\Psi_{lm}^{(o)}$ and $\Psi_{lm}^{(e)}$ satisfy the Regge-Wheeler and the Zerilli equations, respectively.
 - Two independent polarizations of the gravitational waves are given by

$$h_+ - ih_\times = \frac{1}{\sqrt{2}r} \sum_{l,m} \left(\Psi_{lm}^{(o)}(t, r) + \Psi_{lm}^{(e)}(t, r) \right) {}_{-2}Y_{lm}$$

Wave Form





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- h includes a non-wave mode proportional to r^{-3} , which corresponds to the quadrupole part in the Newtonian potential.
It decreases fast as the merger of stars proceeds.
 - It becomes small for large r even before the merger.
 - To eliminate the non-wave part,

$$h(t-r) \equiv h_+ - ih_x = \frac{F(t-r)}{r} + \frac{G(t)}{r^3}$$

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- Fourier components of h are written as

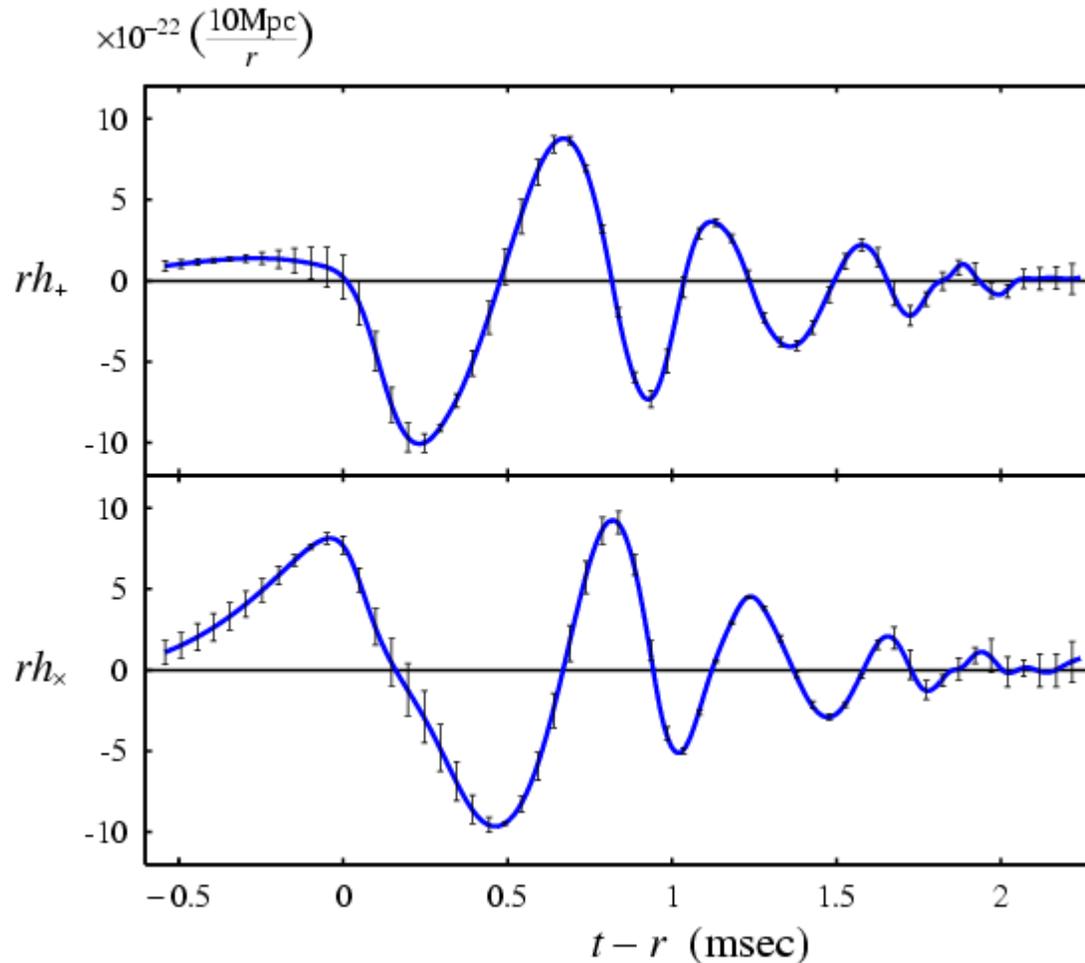
$$\mathbf{h}_\omega(\mathbf{r}) = \frac{\mathbf{e}^{-i\omega\mathbf{r}} \mathbf{F}_\omega(\mathbf{r})}{r} + \frac{\mathbf{G}_\omega(\mathbf{t})}{r^3}$$

$$\mathbf{F}_\omega(\mathbf{r}) = \frac{1}{2\pi} \int \mathbf{F}(t, \mathbf{r}) \mathbf{e}^{-i\omega t} dt, \quad \mathbf{G}_\omega(\mathbf{r}) = \frac{1}{2\pi} \int \mathbf{G}(t, \mathbf{r}) \mathbf{e}^{-i\omega t} dt$$

- From the values $\mathbf{h}_\omega(\mathbf{r})$ in r_1 and r_2 ,

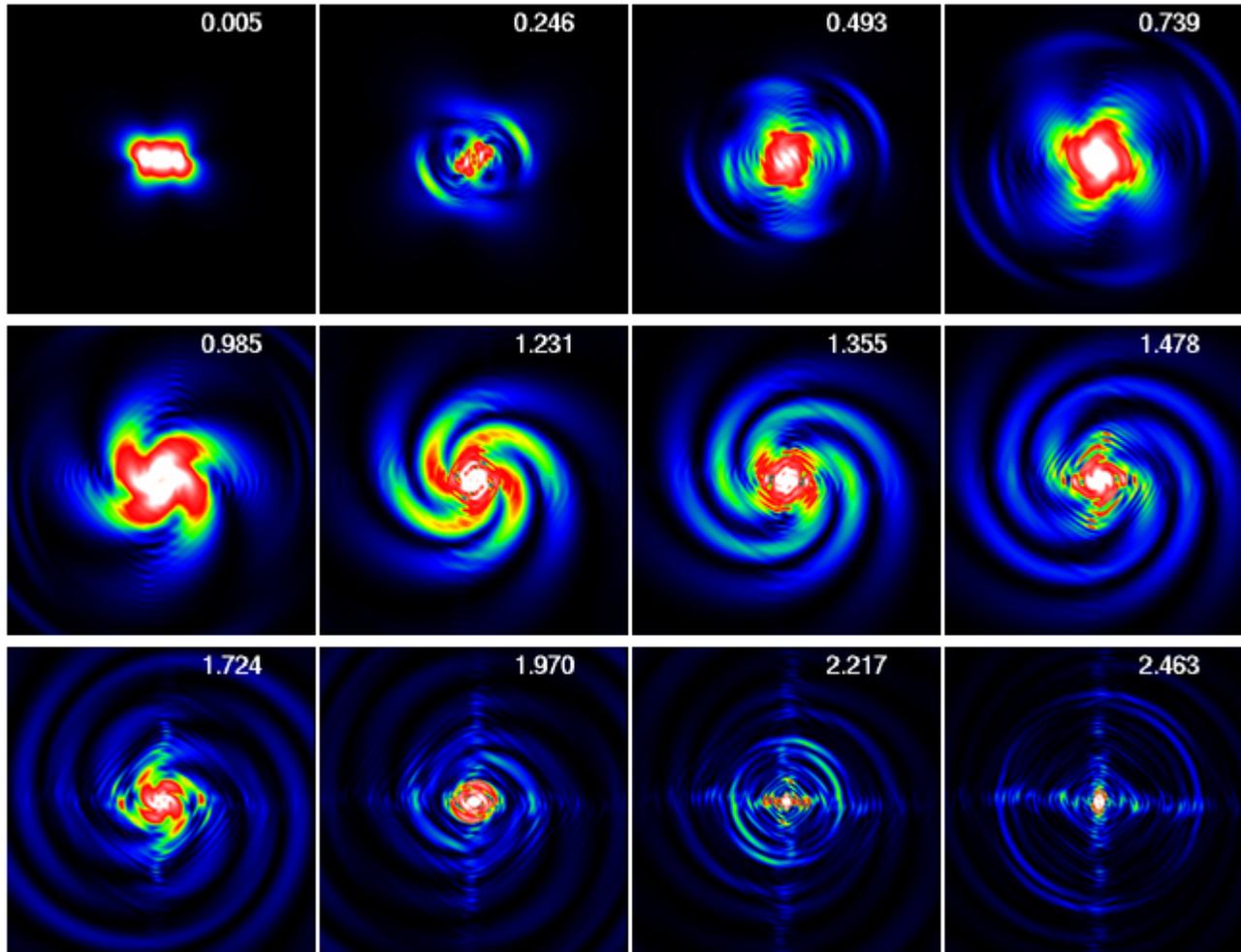
$$\mathbf{F}_\omega(\mathbf{r}) = \frac{r_2^3 \mathbf{h}_\omega(\mathbf{r}_2) - r_1^3 \mathbf{h}_\omega(\mathbf{r}_1)}{r_2^2 \mathbf{e}^{-i\omega r_2} - r_1^2 \mathbf{e}^{-i\omega r_1}}$$

- $\hat{\mathbf{h}}_\omega(\mathbf{r}) = \frac{\mathbf{e}^{-i\omega\mathbf{r}} \mathbf{F}_\omega(\mathbf{r})}{r}, \quad \mathbf{h}(t, \mathbf{r}) = \int \hat{\mathbf{h}}_\omega(\mathbf{r}) \mathbf{e}^{i\omega t} d\omega$



Wave forms along z -axis as a function of $t - r$. The curves are average of rh estimated at $r=110 \sim 200 M_{\odot}$ and error bar denote 2σ .

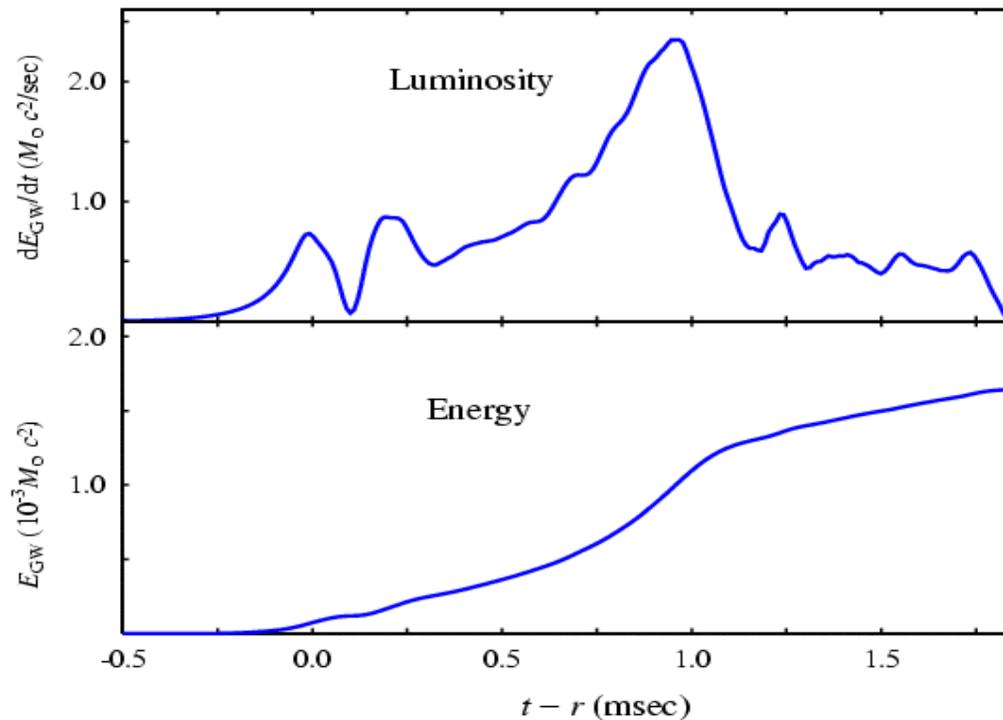
Coalescing Binary NS (energy of GW ρ_{GW})



The 'energy density of grav. waves' $r^2\rho_{GW}$.

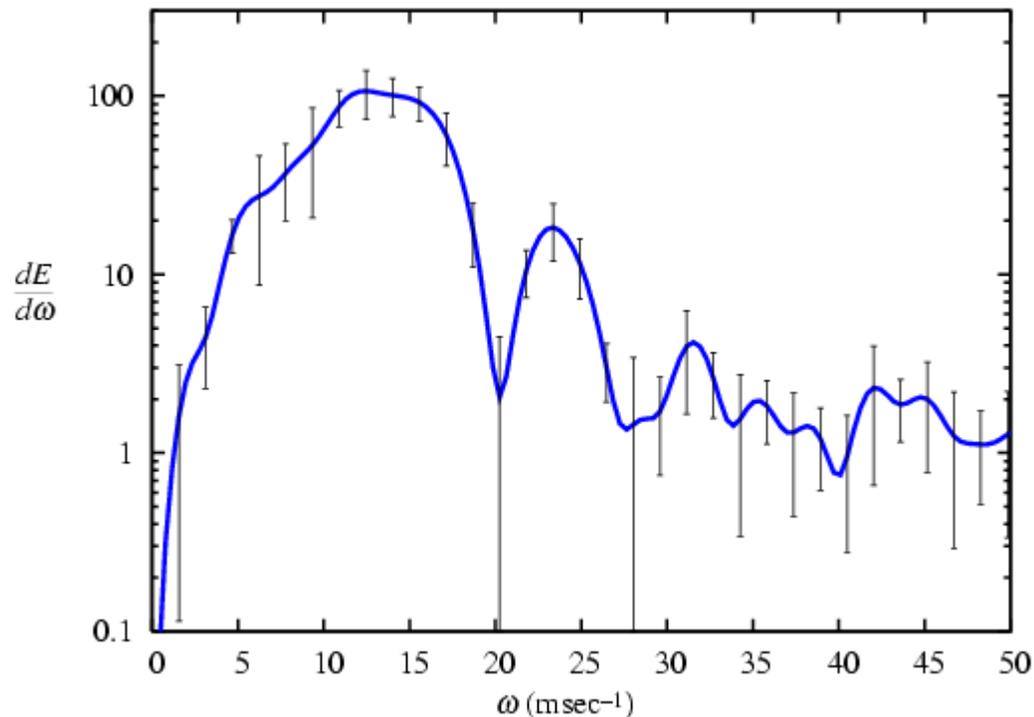
$$\rho_{GW} = \frac{1}{32\pi} \sum_{ij} (\partial_t \tilde{\gamma}_{ij})^2$$

Energy of the Gravitational Waves



$$\frac{dE_{\text{GW}}}{dt} = \frac{1}{32\pi} \sum_{l,m} \left(\left| \partial_t \Psi_{lm}^{(o)} \right|^2 + \left| \partial_t \Psi_{lm}^{(e)} \right|^2 \right)$$

Energy Spectrum of the GW



The curves are average of $dE/d\omega$ estimated at $r=110 \sim 200 M_{\odot}$ and error bar denote 2σ .

$$\frac{dE_{\text{GW}}}{d\omega} = \frac{1}{32\pi} \sum_{l,m} \omega^2 \left(|\Psi_{lm\omega}^{(o)}|^2 + |\Psi_{lm\omega}^{(e)}|^2 \right)$$

Concluding Remarks

- **We obtained a stable 3-D code for coalescing binary neutron stars.**
- **The initial data used here is not realistic, but we are ready to perform scientific simulation for coalescing binary neutron stars.**
- **Shibata and Uryu (2002) has presented results for it using different code. Comparison must be made soon.**