

Local waveform inversion for source parameters

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The questions we would like to address are:

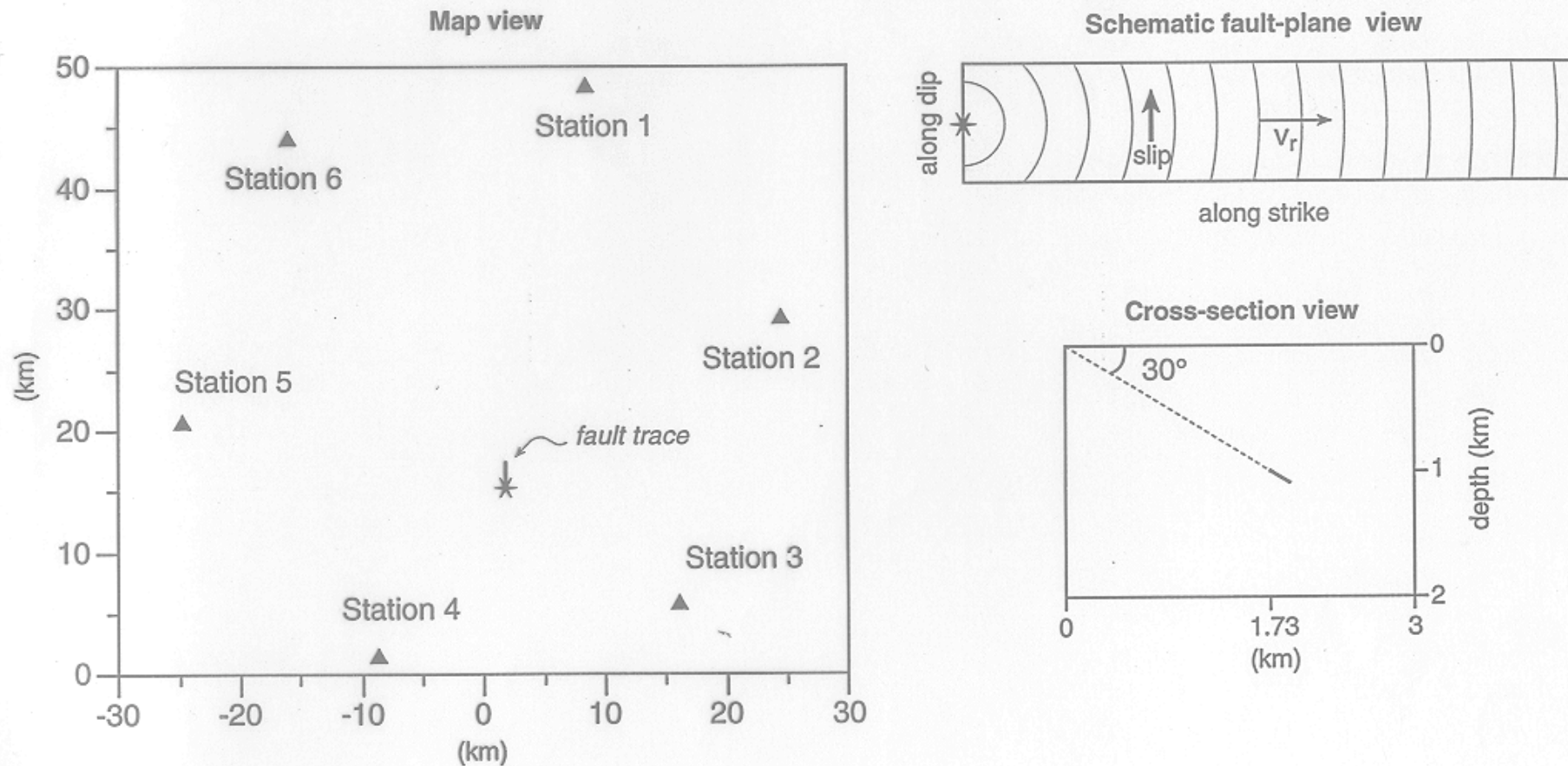
1. How close is the solution of this (unstable) problem to the correct one?
2. How does poor knowledge of crustal structure in the source region affect the estimate of the rupture front location and speed?

3. Since such inversions are non-unique, what methods can one use to choose the “correct” solution from among the multiplicity of solutions?

Since these questions cannot, in fact, be answered when working with real data, we set up a problem using artificial data

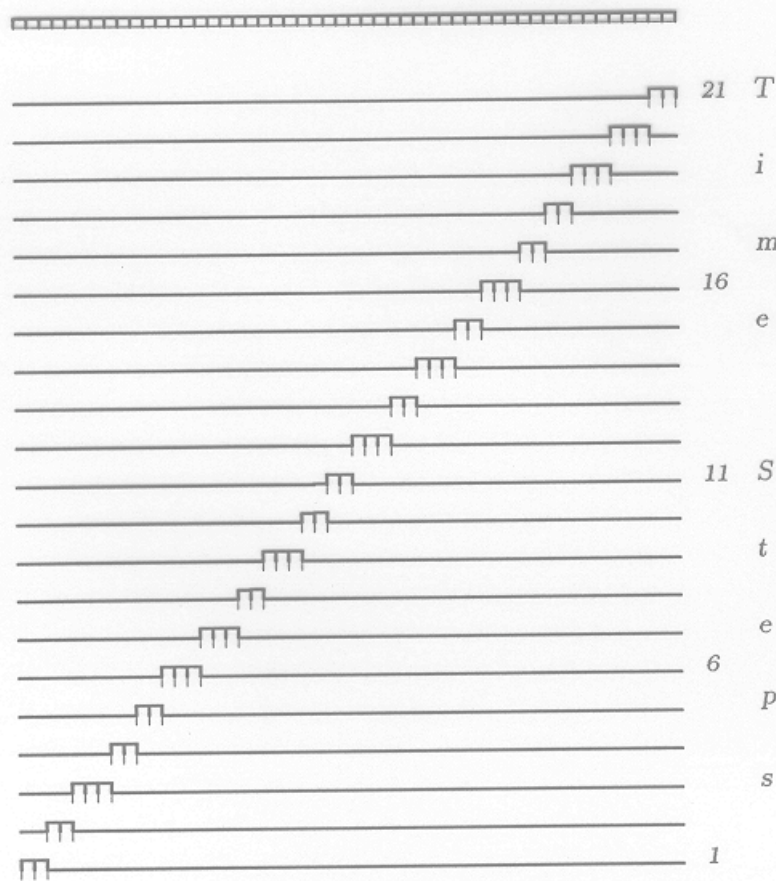
Source model

Fault geometry Shallow dipping fault



FORWARD MODEL

Final Moment



Forward Rupture Model



Length Steps

Forward model

1×10^{11} Nm of moment are released at each grid, which is allowed to slip **only once**
Rupture speed = 0.7β

In the first set of cases, the inverse problem is solved using the SAME spatial and temporal grid sizes as those used to generate the synthetic (noise-free) data

Inversion methods

First approach:

SVD, minimize L2 norm

Constrain moment value

Remove small eigenvalues

Solution with smallest first differences

Second approach:

Linear programming, minimize L1 norm

Use different physical constraints

Smallest second differences

Case 1a - conclusions

Even if we constrain the rupture front in the inversion to the true front, we are unable to reproduce the final constant moment distribution and the source time function, when we use the SVD method: many small, negative values of moment rates are produced

Case 1b - conclusions

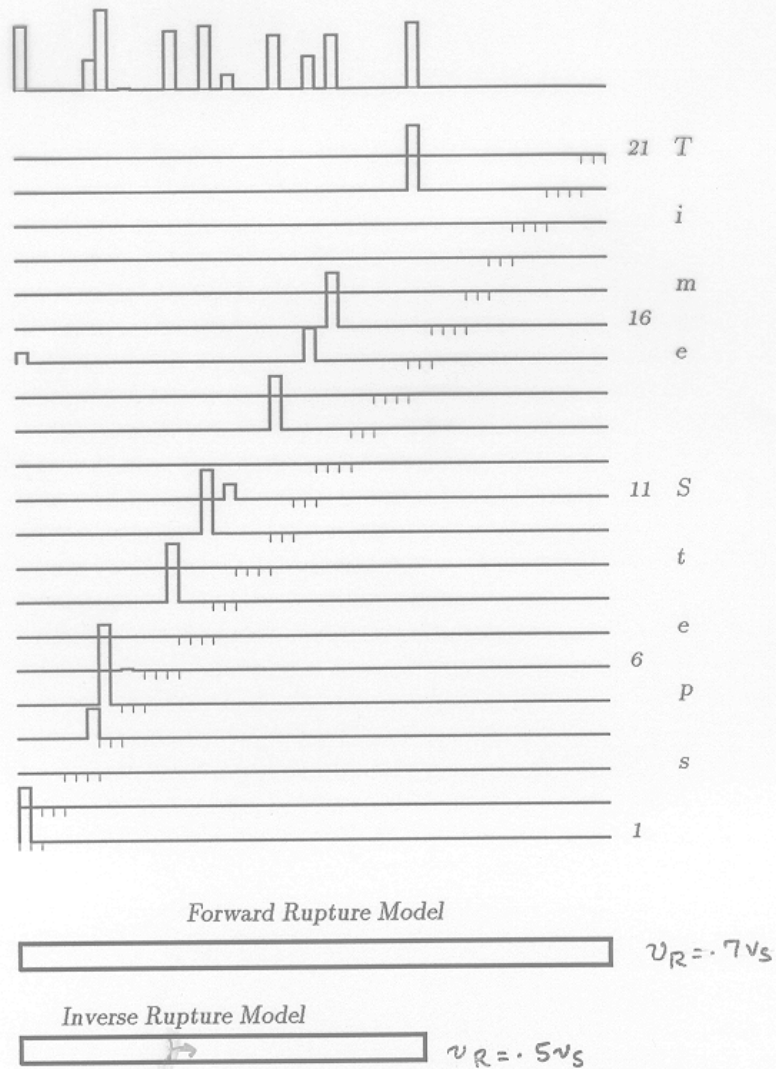
**When we constrain the moment rates to be
POSITIVE (using the linear programming
method) we are able to reproduce the final
constant moment distribution and the source
time function correctly!**

Case 1c - conclusions

When we constrain the rupture front to move **faster** than the true one and also allow all cells behind it to continue to slip, we are able to reproduce the solution (moment-rate history, final moment, source time function) as long as the **POSITIVITY** constraint is used

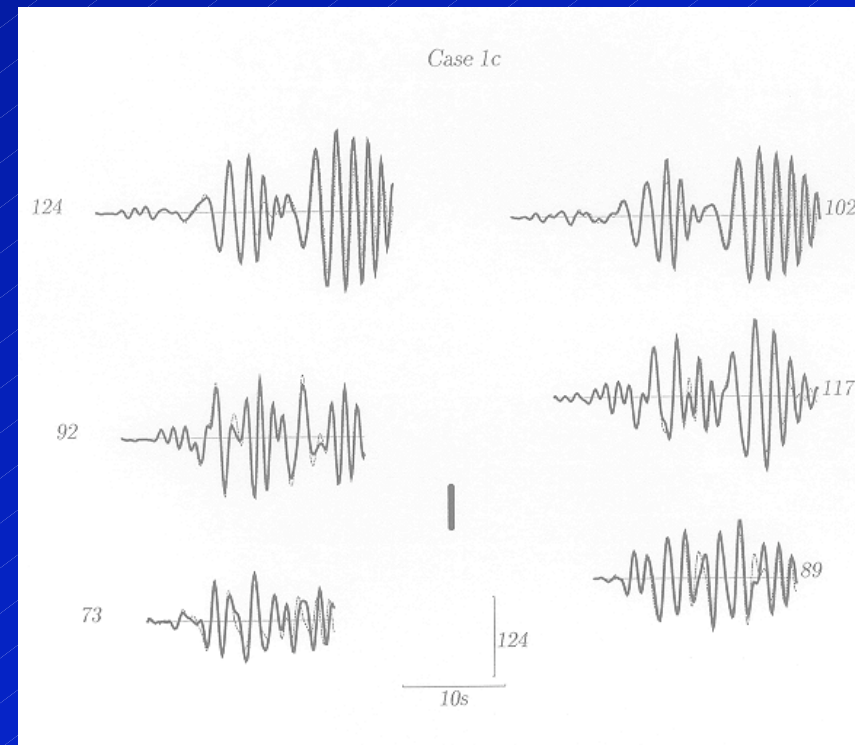
CASE 1c

Final Moment



Case 1c Rupture front

Forward model = 0.7β
Inverse model = 0.5β

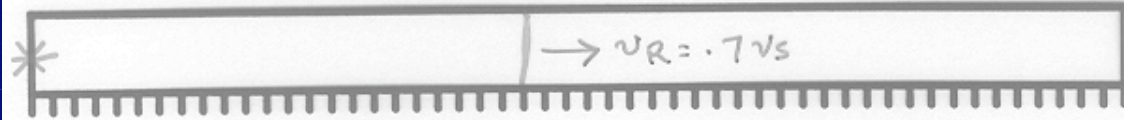


Case 1c - conclusions

If the rupture front is constrained to move **more slowly** than the true one, we are unable to reproduce any aspect of the solution correctly, **even with the positivity constraint**. Constraining the seismic moment to the true one does not improve the solution.

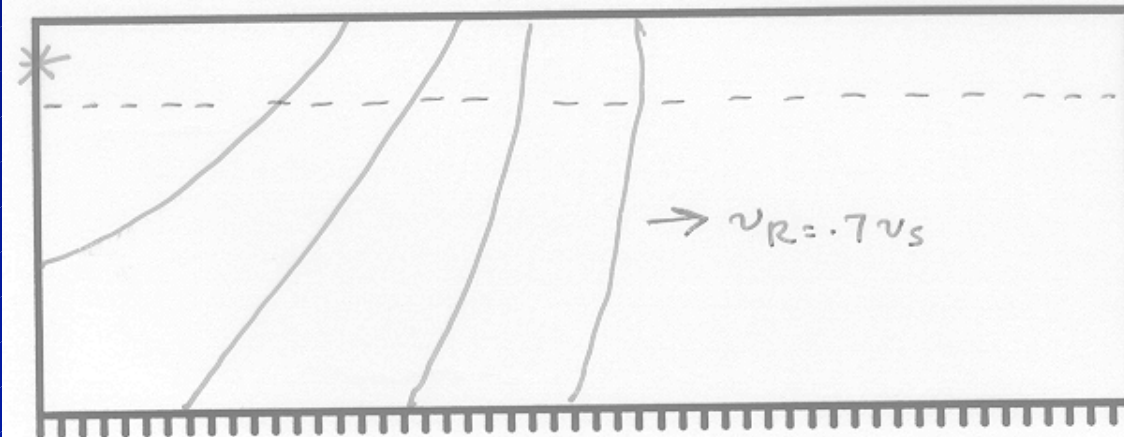
CASE 2a

FORWARD RUPTURE MODEL



Length Steps

INVERSE RUPTURE MODEL



Length Steps

Case 2a
Wider fault

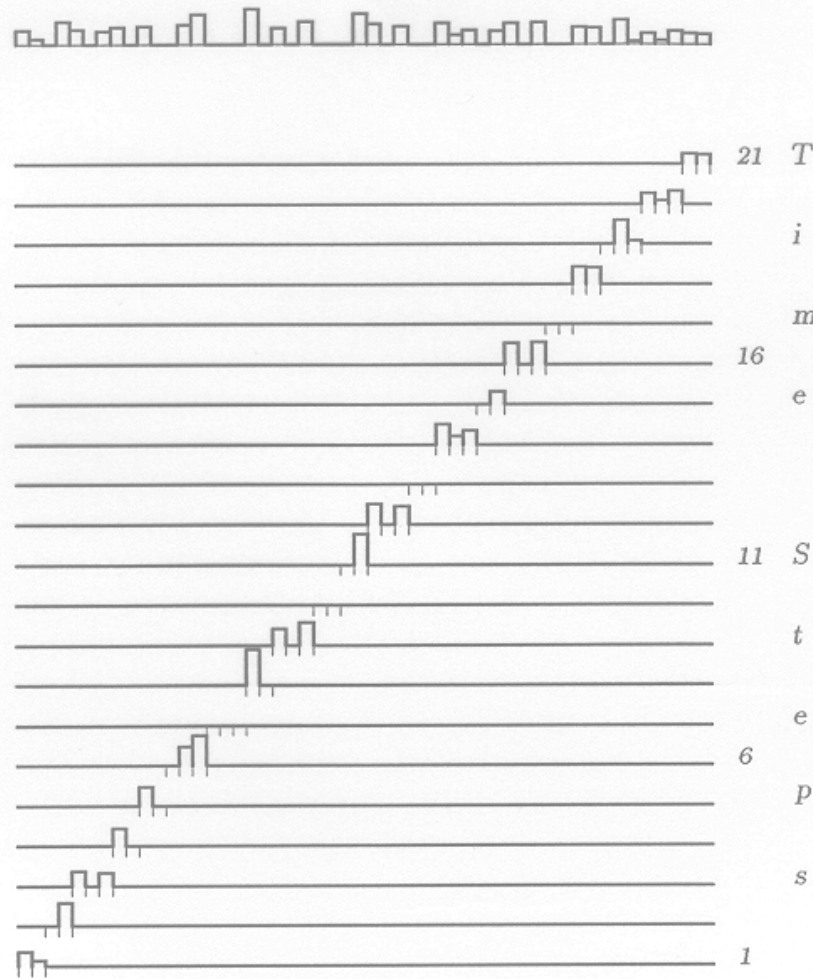
Same rupture speed in forward and inverse model
 0.7β

Case 2a - conclusions

If we use a **wider** fault and the correct rupture speed and allow cells to release moment only once in the inversion, and also impose the positivity constraint, then the moment is only released at the correct depth in the solution, **even though moment release at deeper parts of the fault was permitted**

CASE 2a

Final Moment



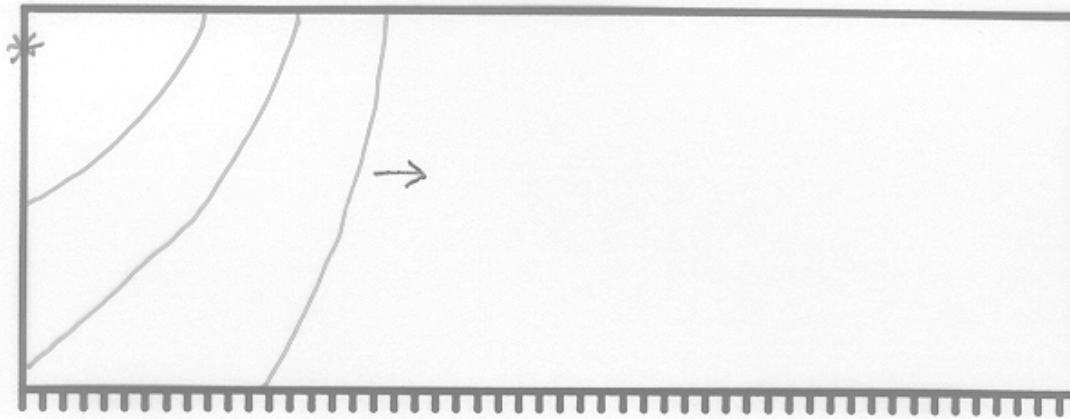
Case 2a Wider fault

Inversion results

The constant
moment
release is
reproduced
approximately

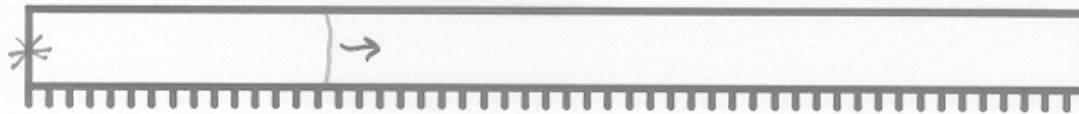
CASE 2b

FORWARD RUPTURE MODEL



Length Steps

INVERSE RUPTURE MODEL



Length Steps

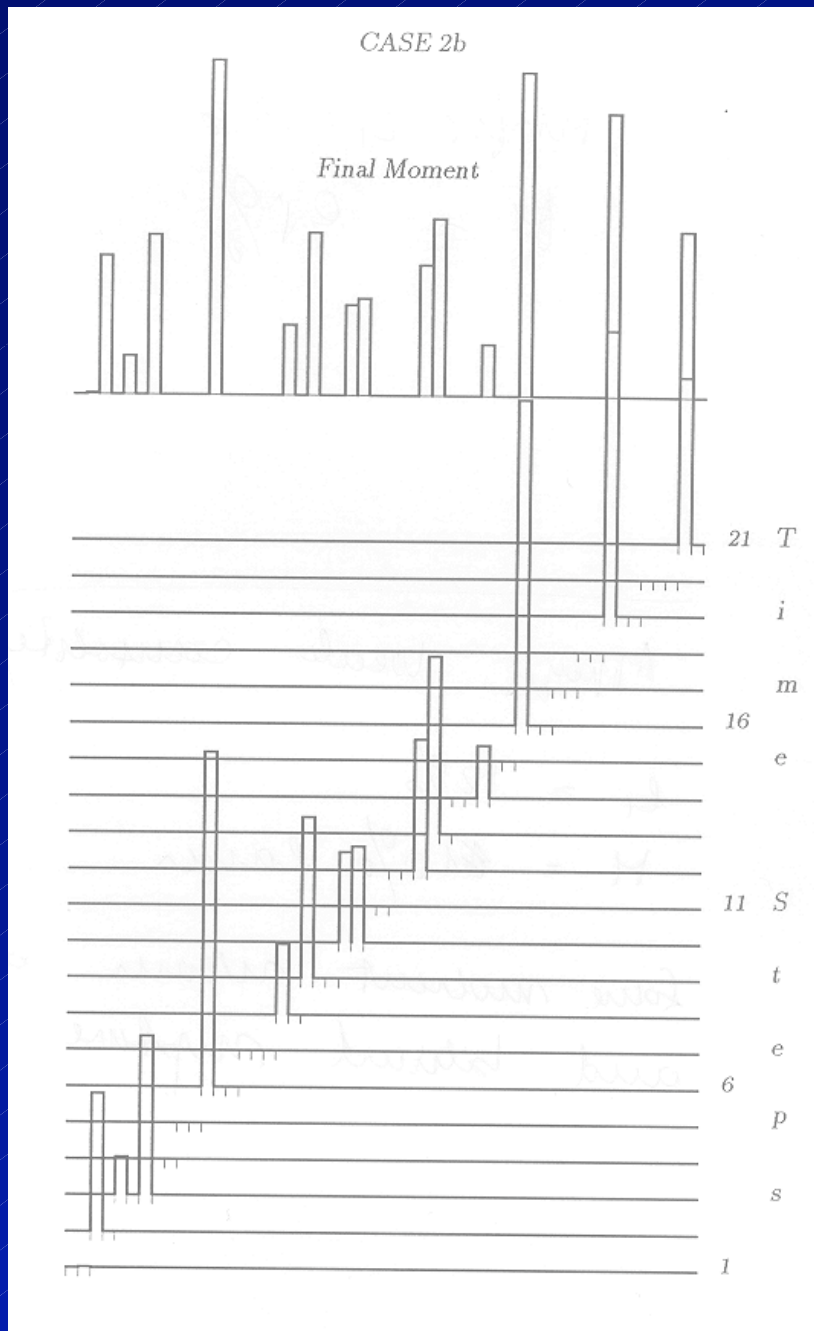
Case 2b Narrower fault

Same rupture
speed 0.7β

Case 2b - conclusions

If we use a **narrower** fault than the true one in the inversion, we obtain the correct moment and centroids, but are unable to reproduce the source time function and the uniform moment release at the rupture front

But we are able to fit the data!



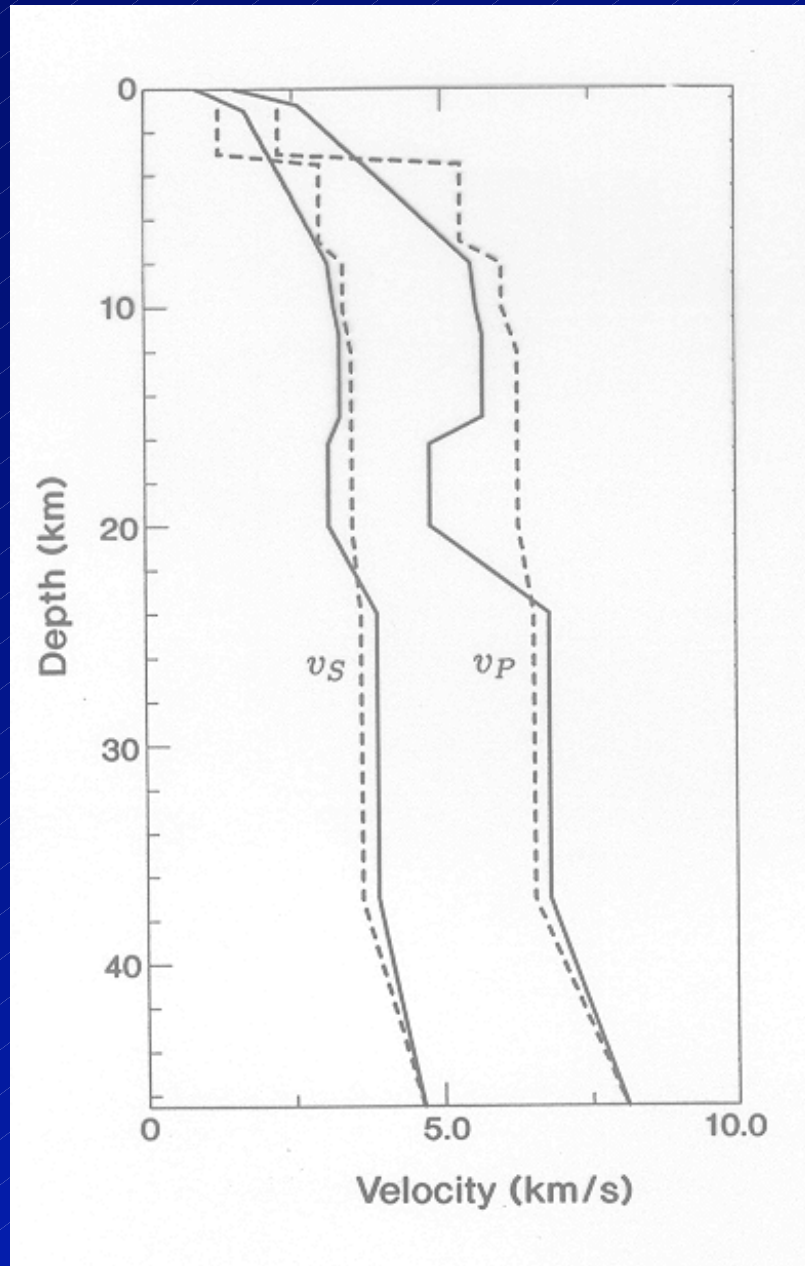
Case 2b

Narrower fault

Strongly non-
uniform moment
distribution
(asperities!)

Case 3a

**Different
medium used
in forward
(M1,
continuous)
and inverse
model
(M2, dashed)**



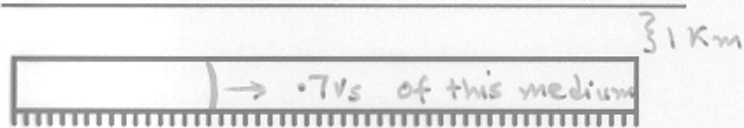
Case 3a

Different medium

CASE 3a

FORWARD RUPTURE MODEL

Earth's surface



Length Steps

Medium M1

INVERSE RUPTURE MODEL

Earth's surface



Length Steps

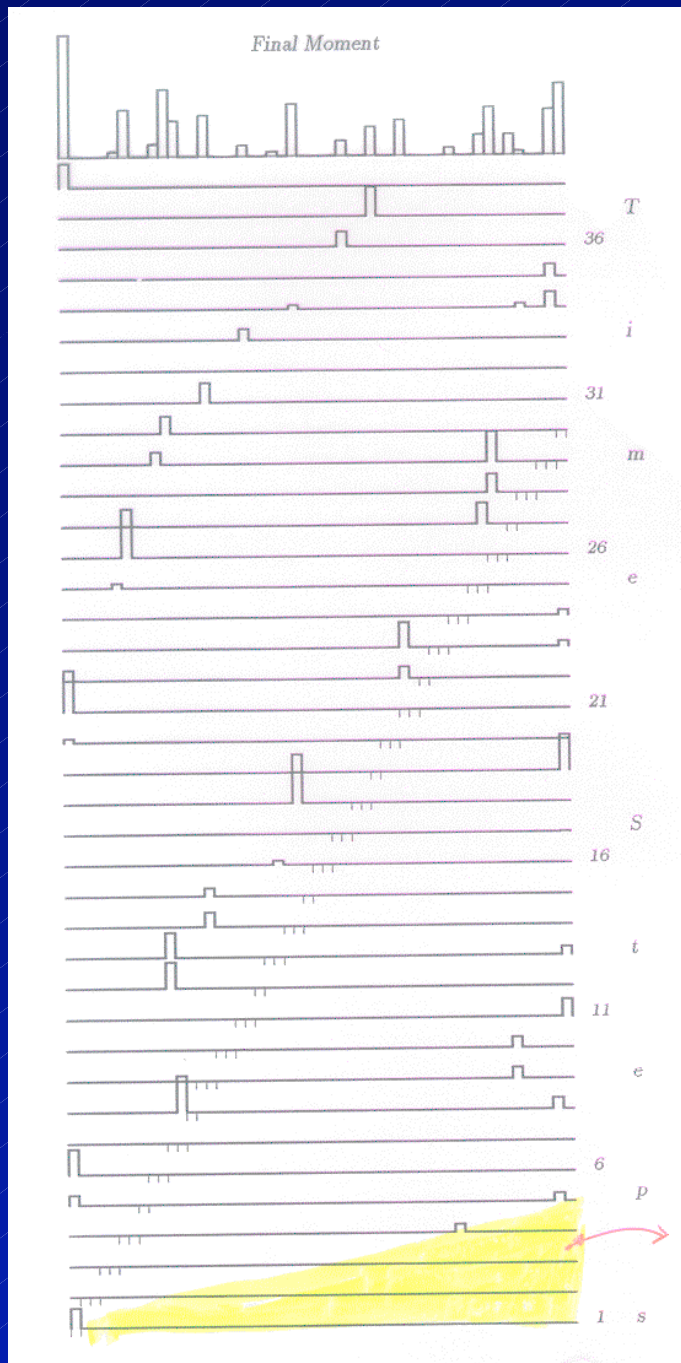
Medium M2

Case 3a - conclusions

Incorrect source structure leads to poor fitting of the data and the solution is not reproduced.

Instead, this incorrect source structure is transformed into **ARTIFACTS** of the solution!

An illustration of the effect of model noise



Case 3a

Incorrect source structure

Appearance of
artifacts:
a **GHOST front**
Behind the main
rupture front

Region excluded by weak causality constraint

CONCLUSIONS

In summary, **if the Earth structure is known**, then we can determine the rupture front location in time, as long as we use a **larger fault area and larger rupture speed** than the true ones.

CONCLUSIONS

All our **negative conclusions**, say the fact that we are unable to reproduce the correct solution without the positivity constraint, will hold for more complex cases

CONCLUSIONS

On the other hand, our **positive conclusions**, say the cases when we can reproduce the rupture front position correctly by using the positivity constraint, is only applicable to the simple forward model studied here

CONCLUSIONS

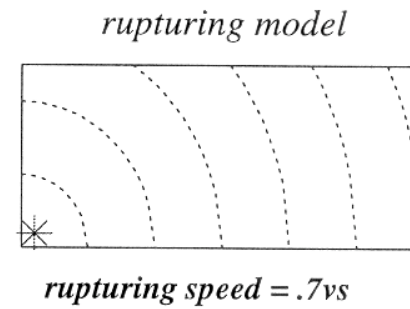
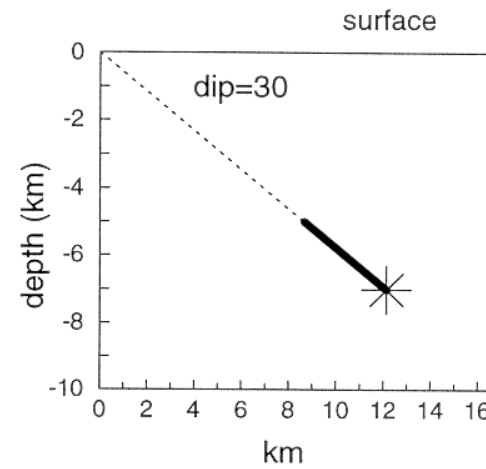
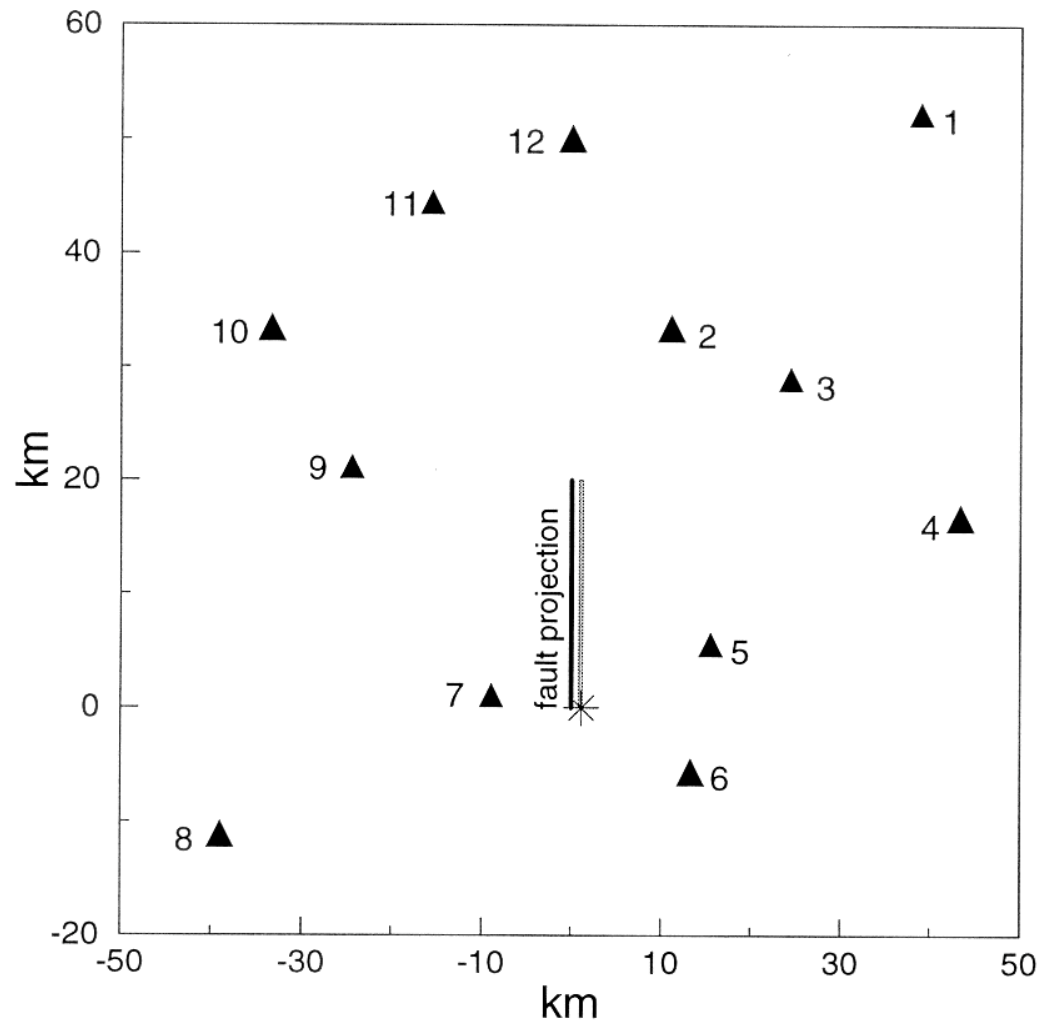
Larger faults (20 km x 5 km), top of the fault located at 5 km depth. We use 8 times **larger spatial** and 4 times **larger temporal steps** in the inversion. Positivity of moment rate enforced. Results compared with forward model **smoothed over the larger grids**. Similar conclusions as before.

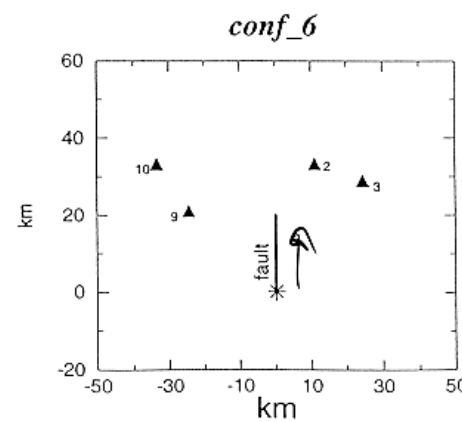
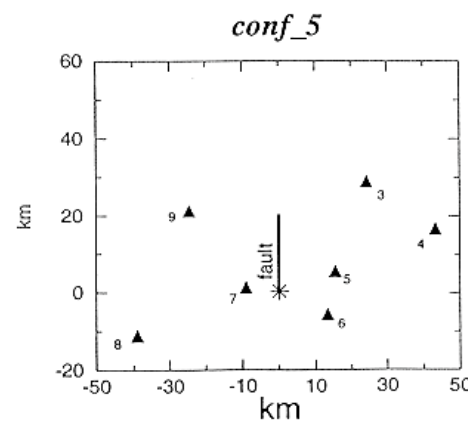
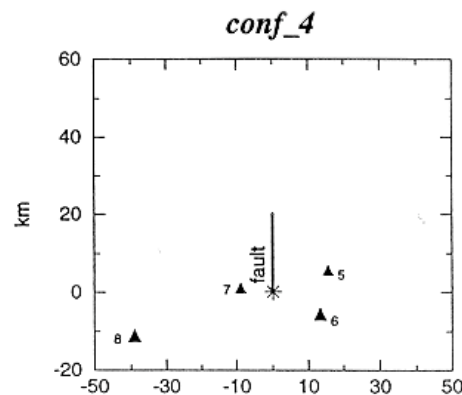
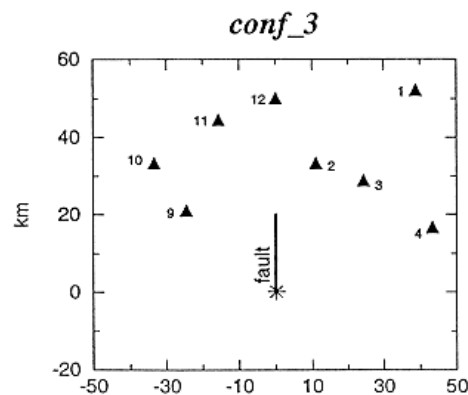
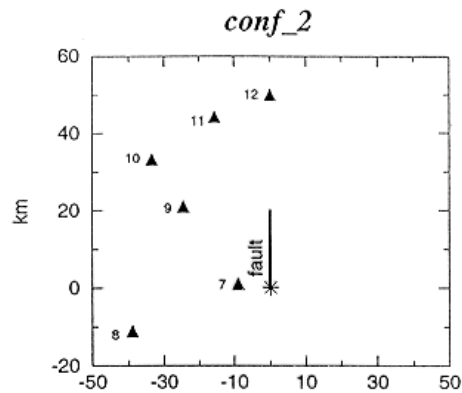
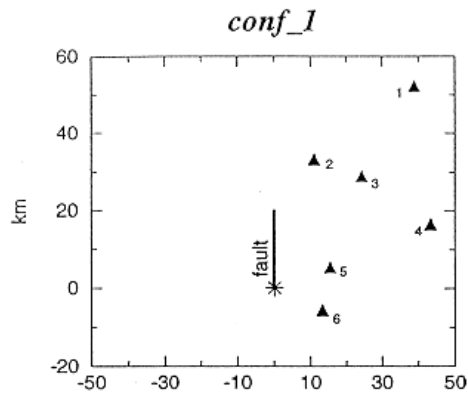
CONCLUSIONS

This study demonstrates the problems we encounter even for the simple case of a Haskell-type faulting model. Clearly more realistic models, like crack models, and models with larger variability of rupture propagation speeds would present even greater difficulties.

Slide

Fault geometry





Conf_1:
Stations on the hanging wall

Conf_2:
Stations on the footwall

Conf_3 & 6:
Stations in the forward rupture propagation direction

Conf_4 & 5:
Stations in the backward rupture propagation

CONCLUSIONS

A distribution of stations on the **hanging wall** and in the **forward rupture propagation direction** allows the source model to be retrieved even in the presence of a small number of stations.

A good **azimuthal distribution** is more important than the number of **stations!**

Inversion of the Bovec 1998 (W Slovenia) event

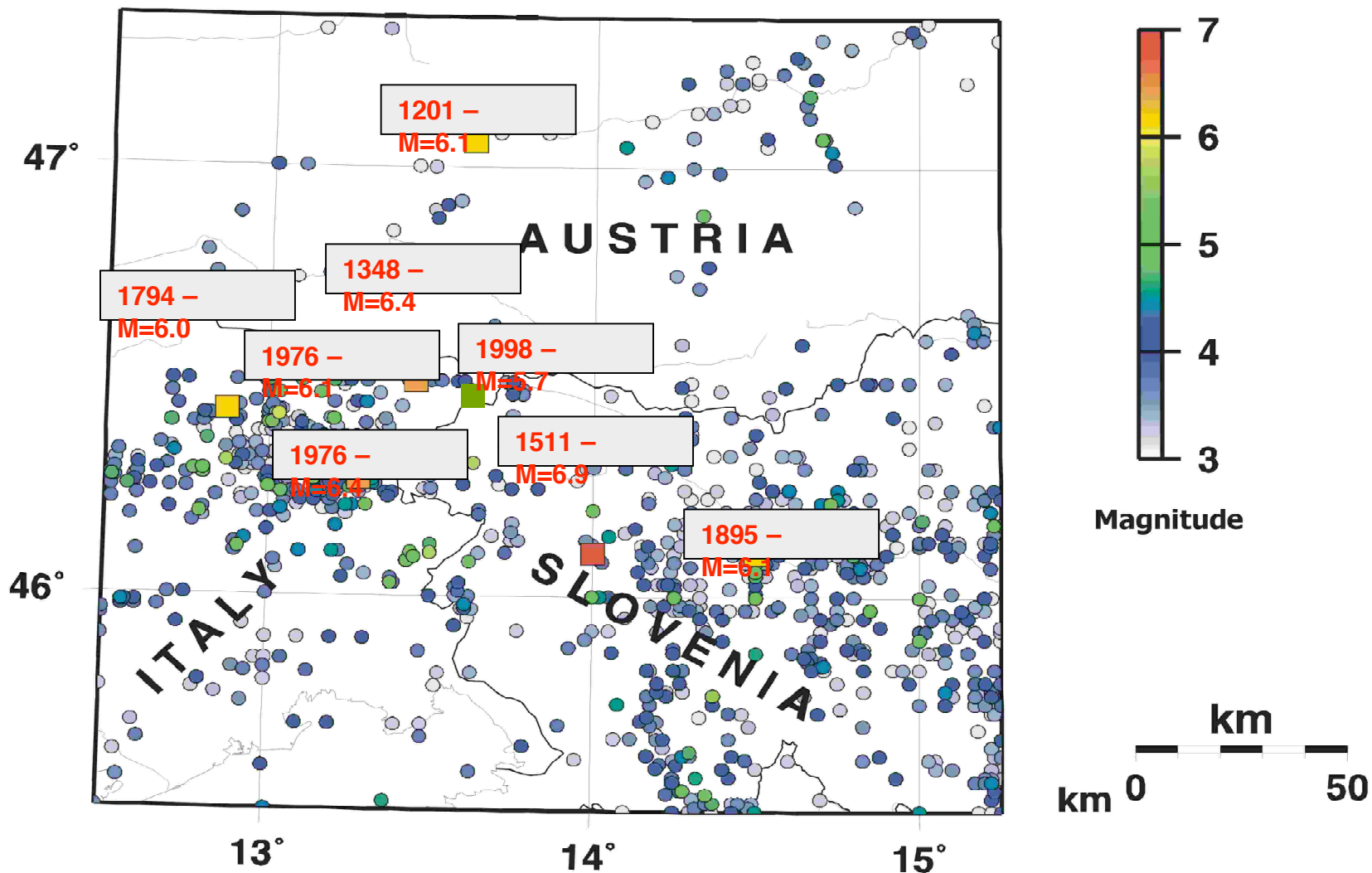
EUROPE





Geodynamic Framework

Historical seismicity



Active deformation and recent seismicity

September 15, 1976

09:21
Ms = 6.1

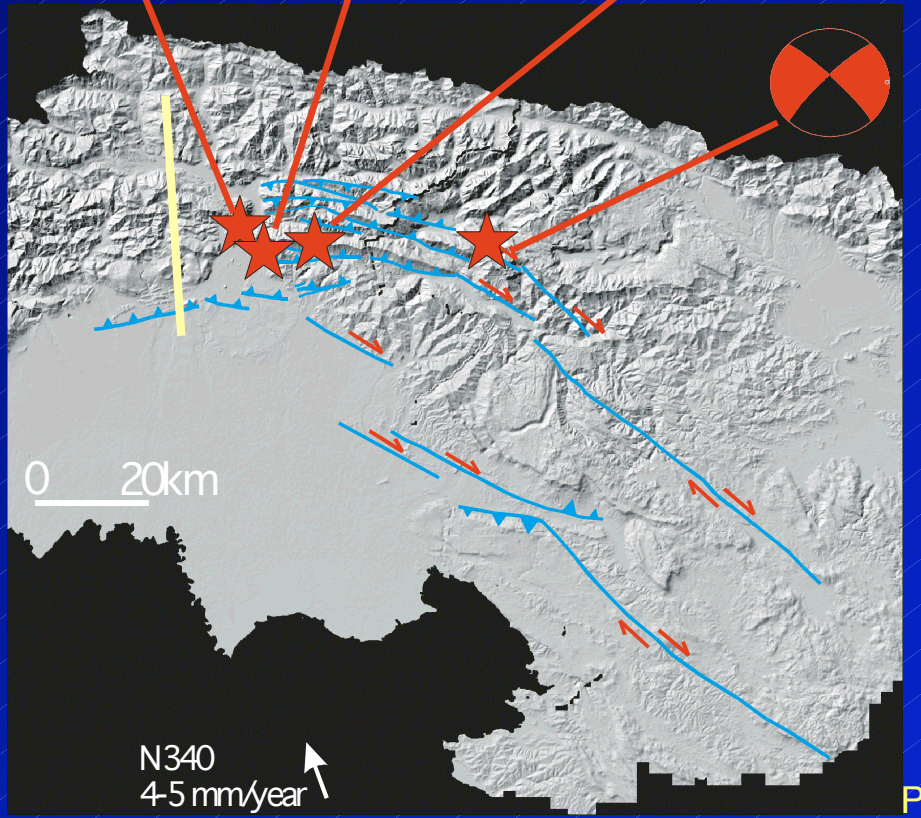
03:15
Ms = 6.0

May 6, 1976

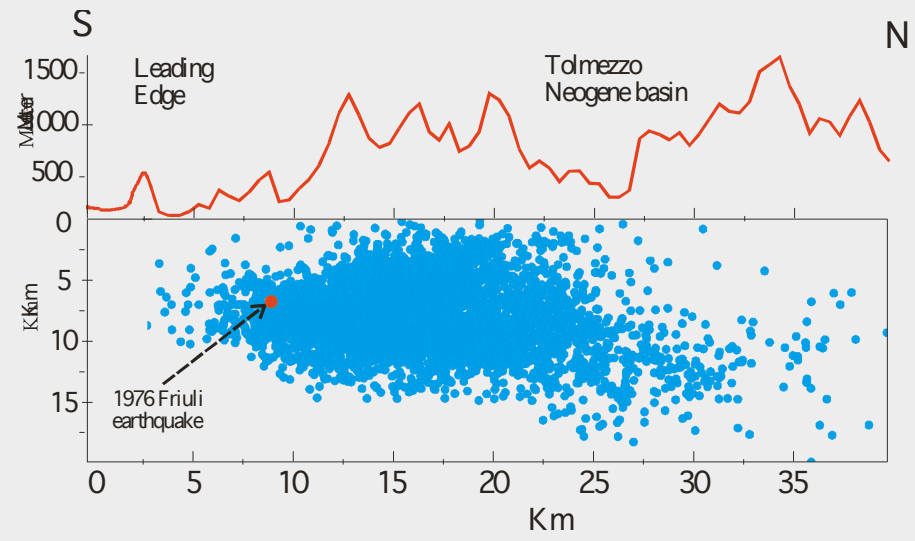
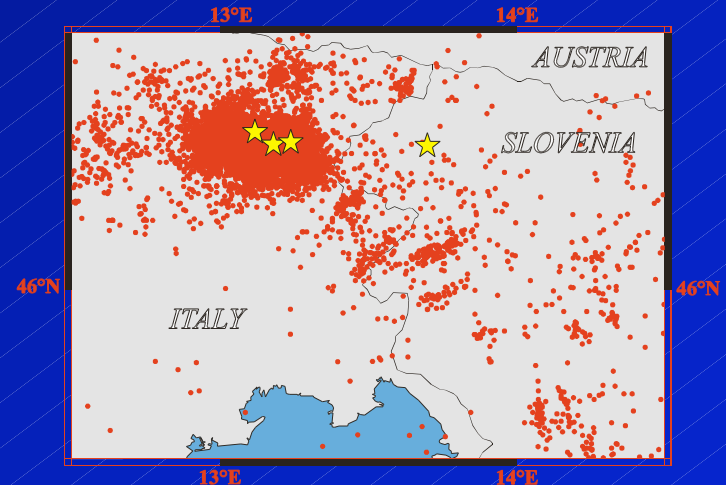
Ms = 6.5

April 12, 1998

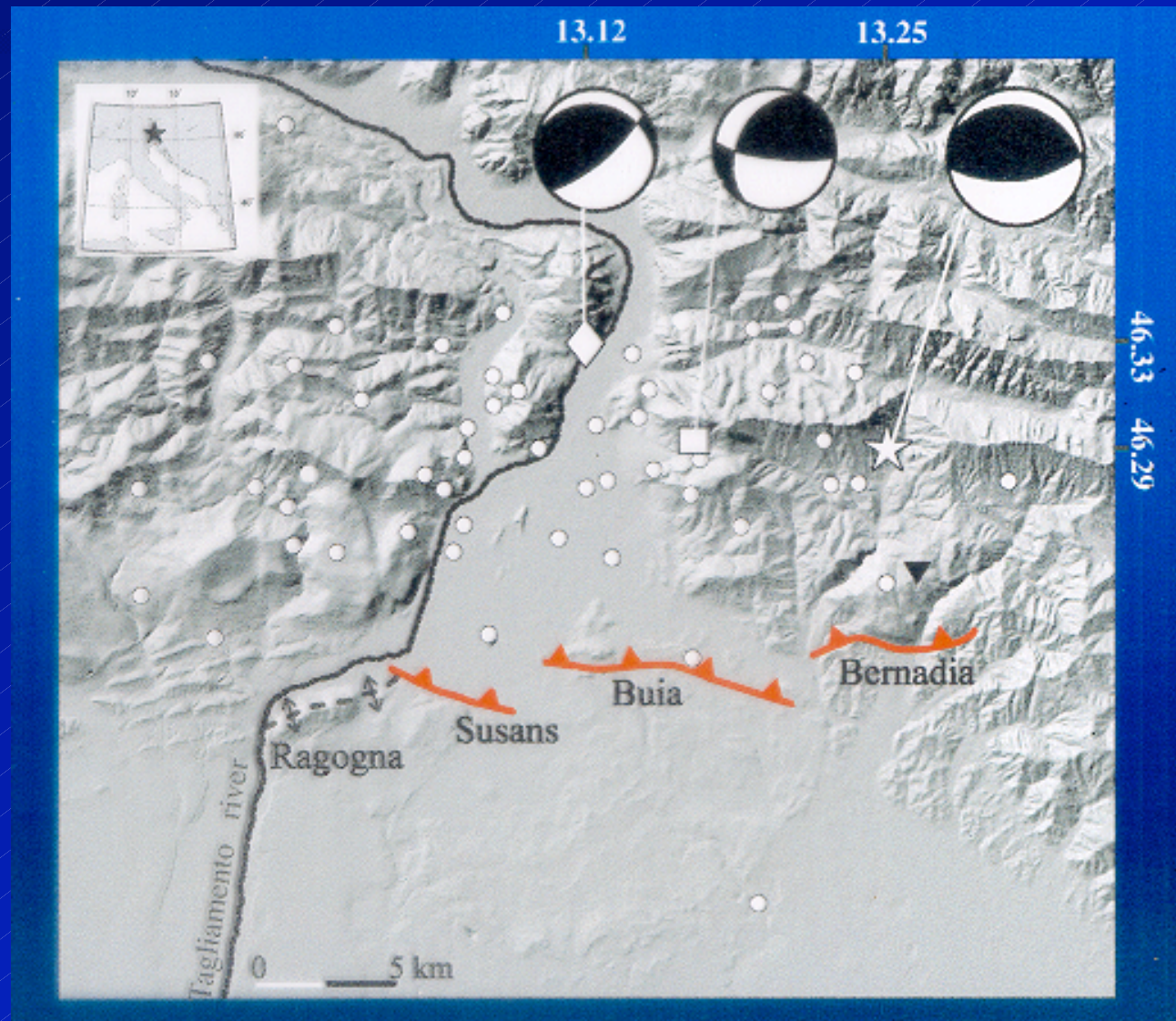
Ms = 5.7
Bovec-Krn



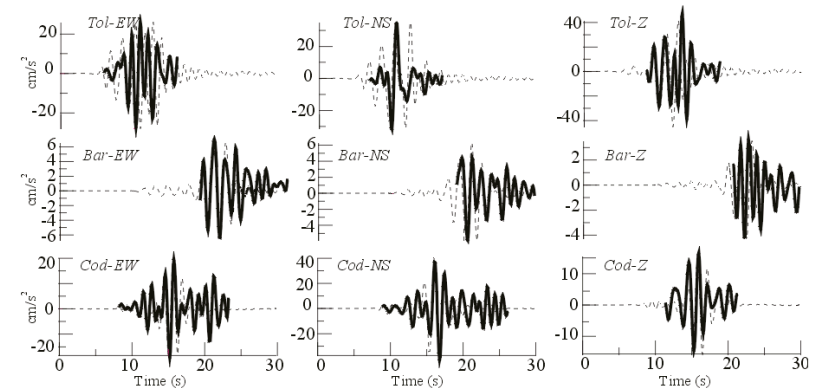
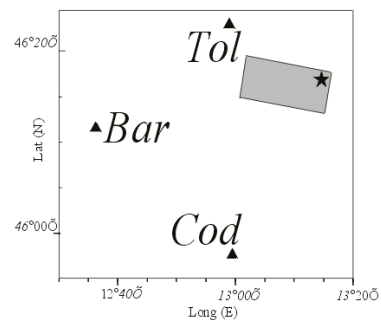
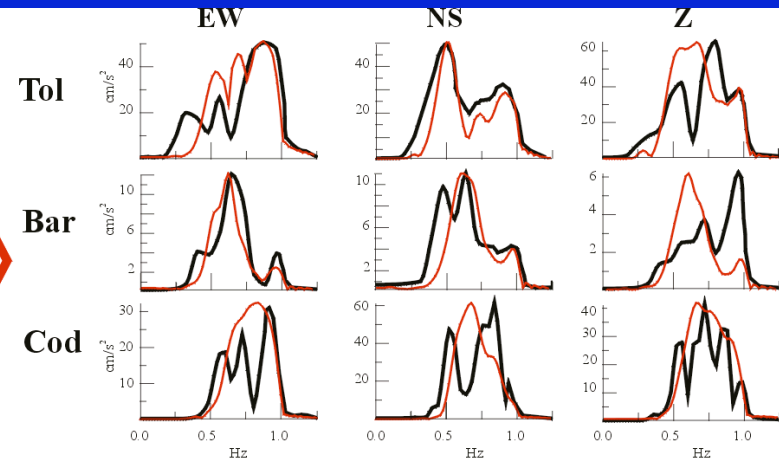
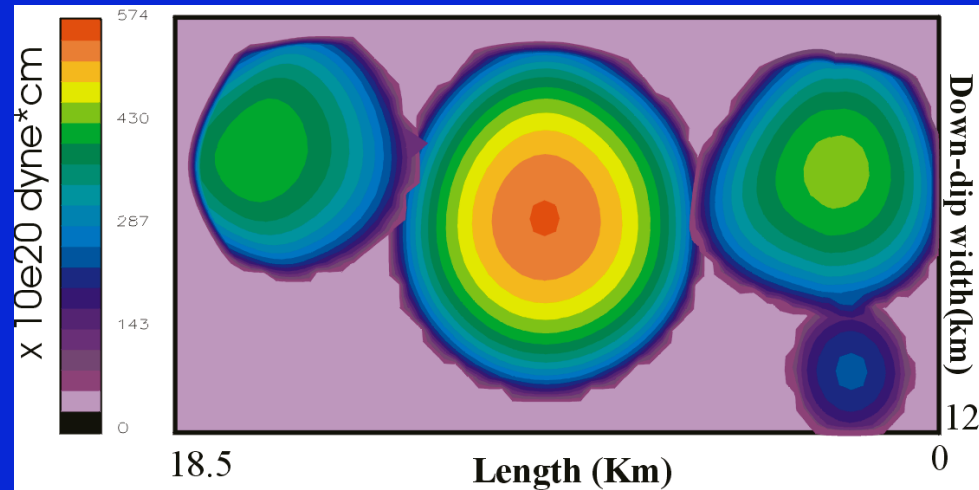
Microseismicity 1977-1987 (Renner, 1995)



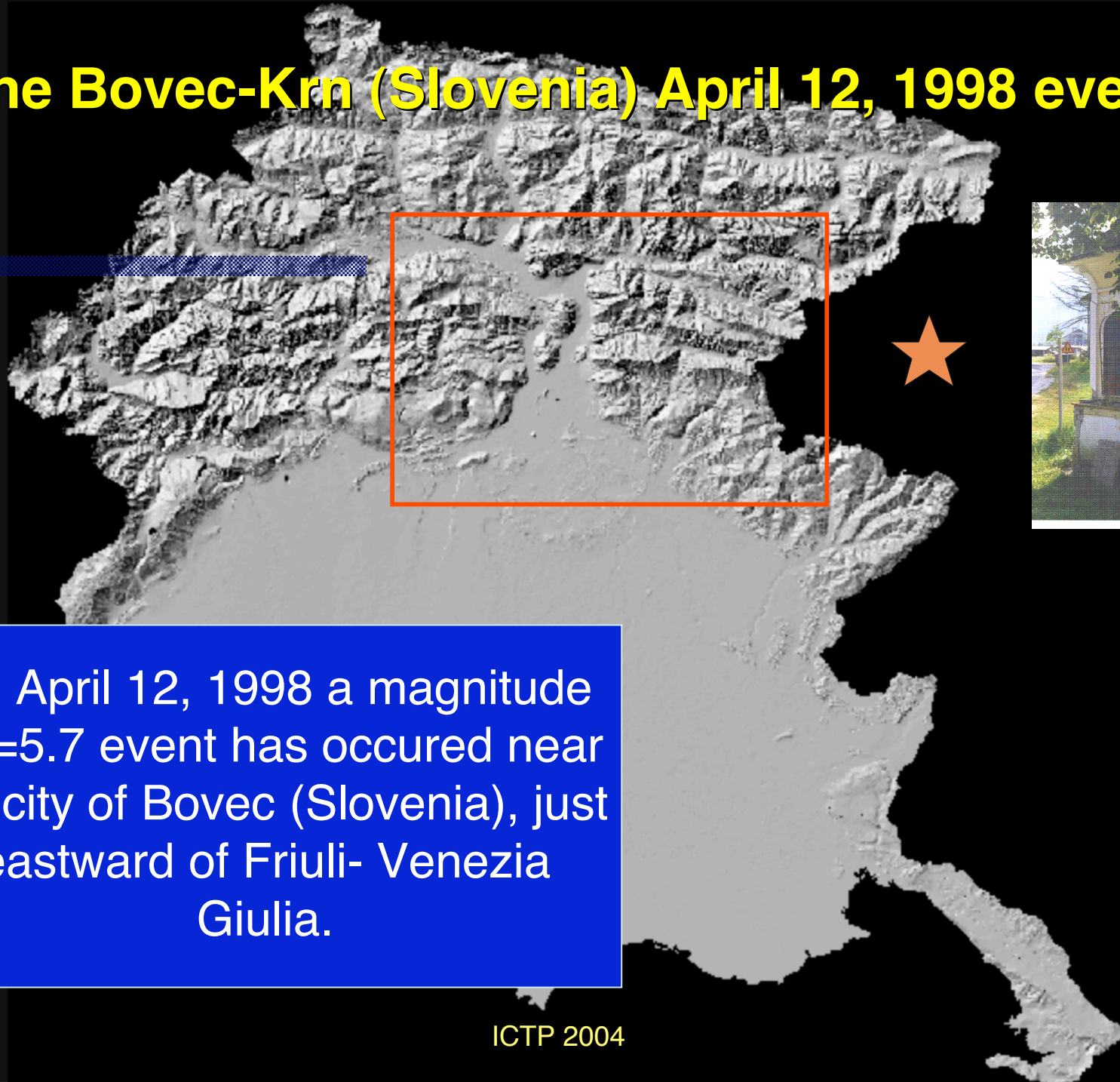
The 1976 Friuli thrust fault and related earthquake sequence



The 1976 Friuli Thrust-faulting Earthquake, Ms 6.5



The Bovec-Krn (Slovenia) April 12, 1998 event

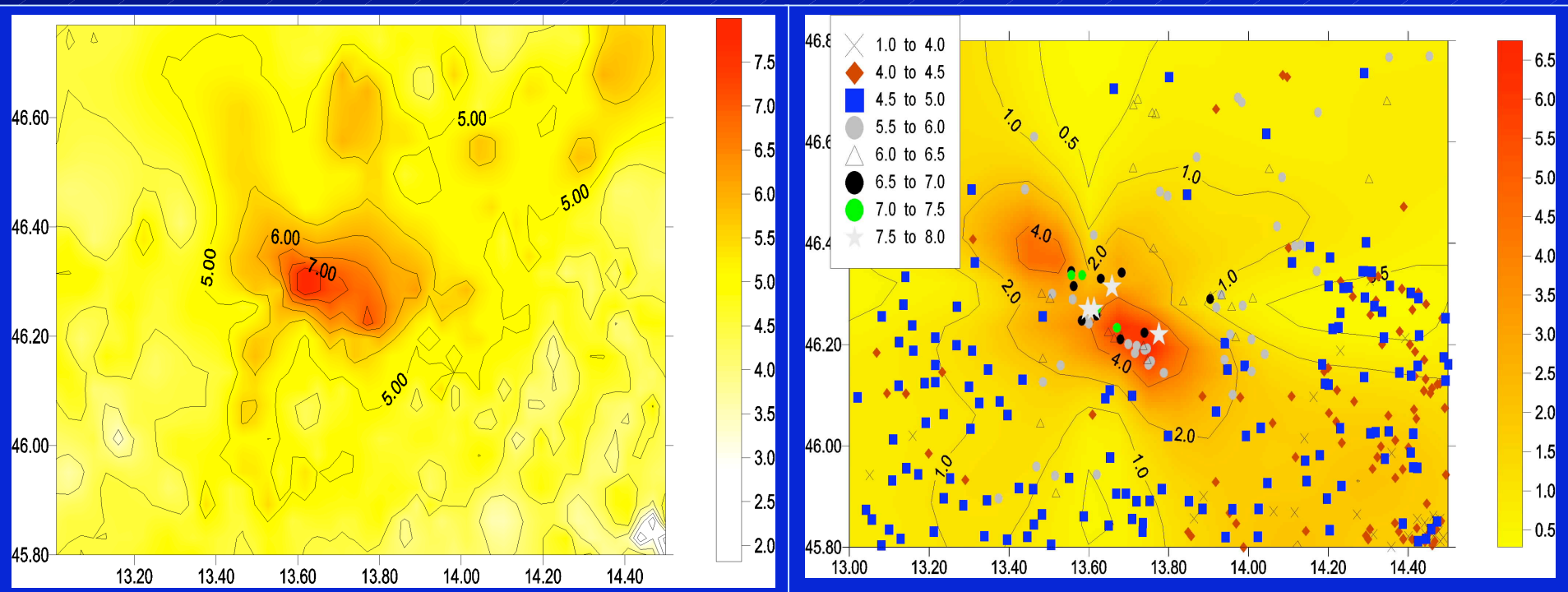


On April 12, 1998 a magnitude $M_s=5.7$ event has occurred near the city of Bovec (Slovenia), just eastward of Friuli- Venezia Giulia.

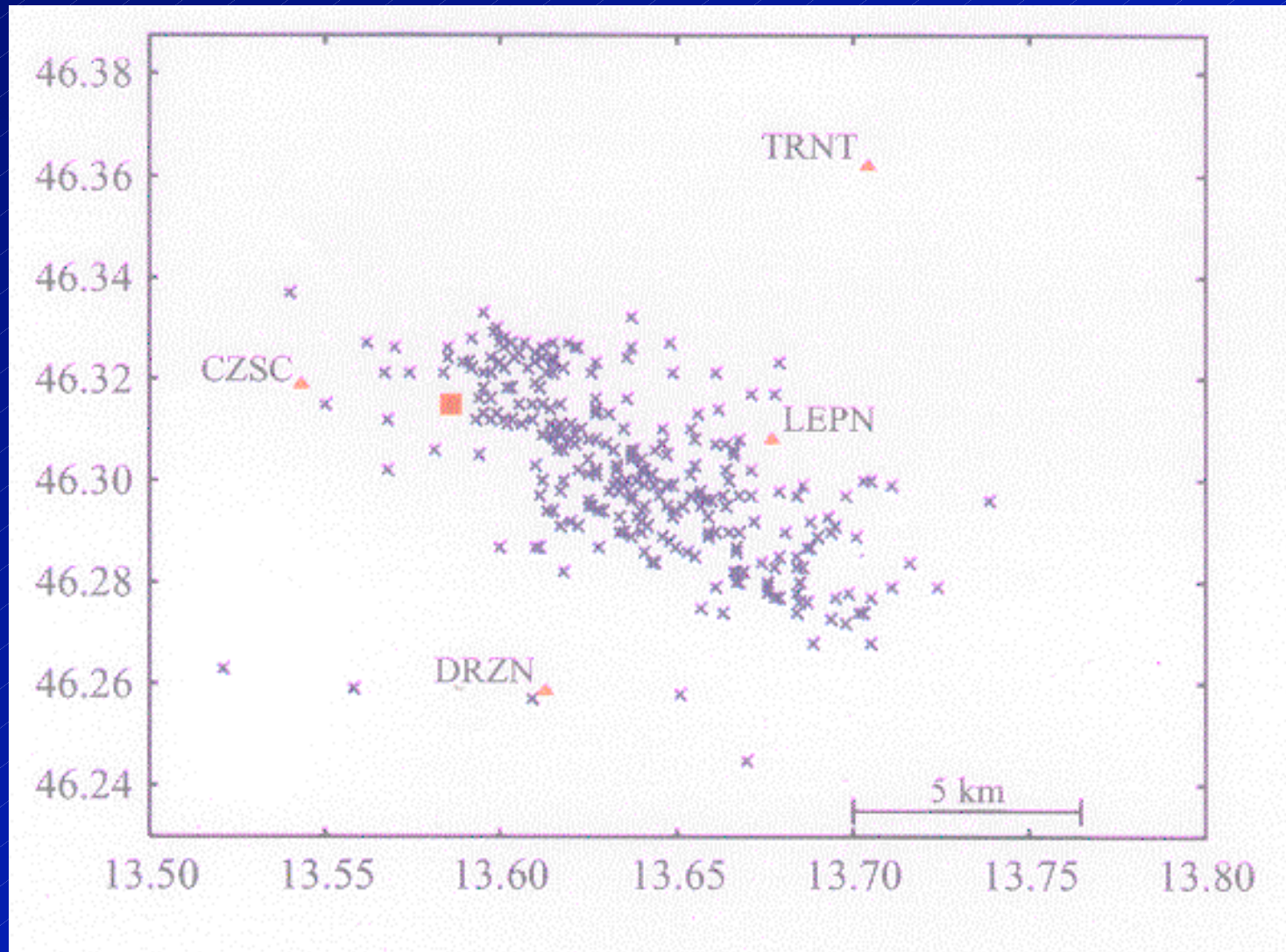
The 1998 Bovec-Krn Strike-Slip Earthquake, Ms 5.7

Observed Intensities
(EMS-98)

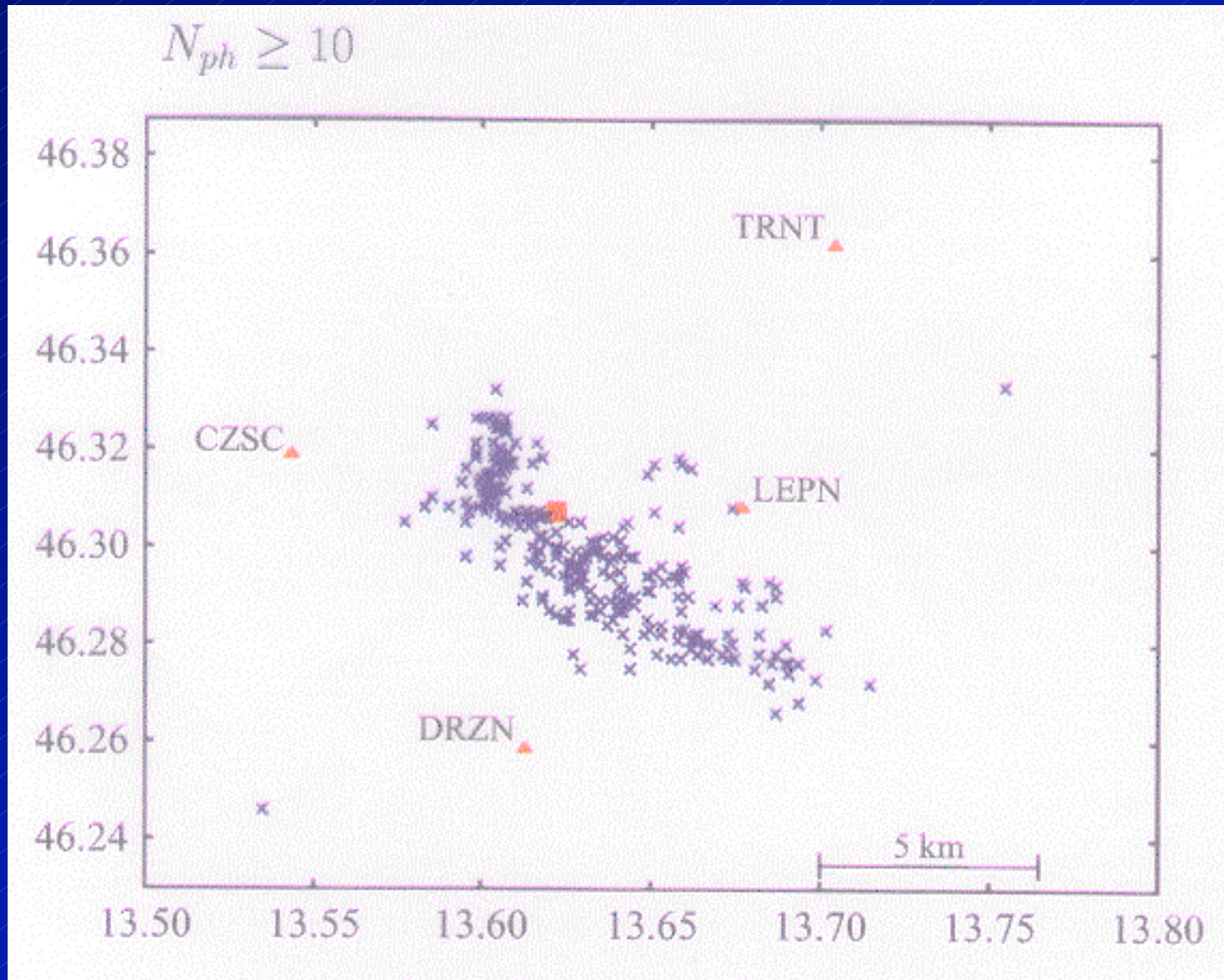
Maximum Horizontal
Velocities (cm/s)



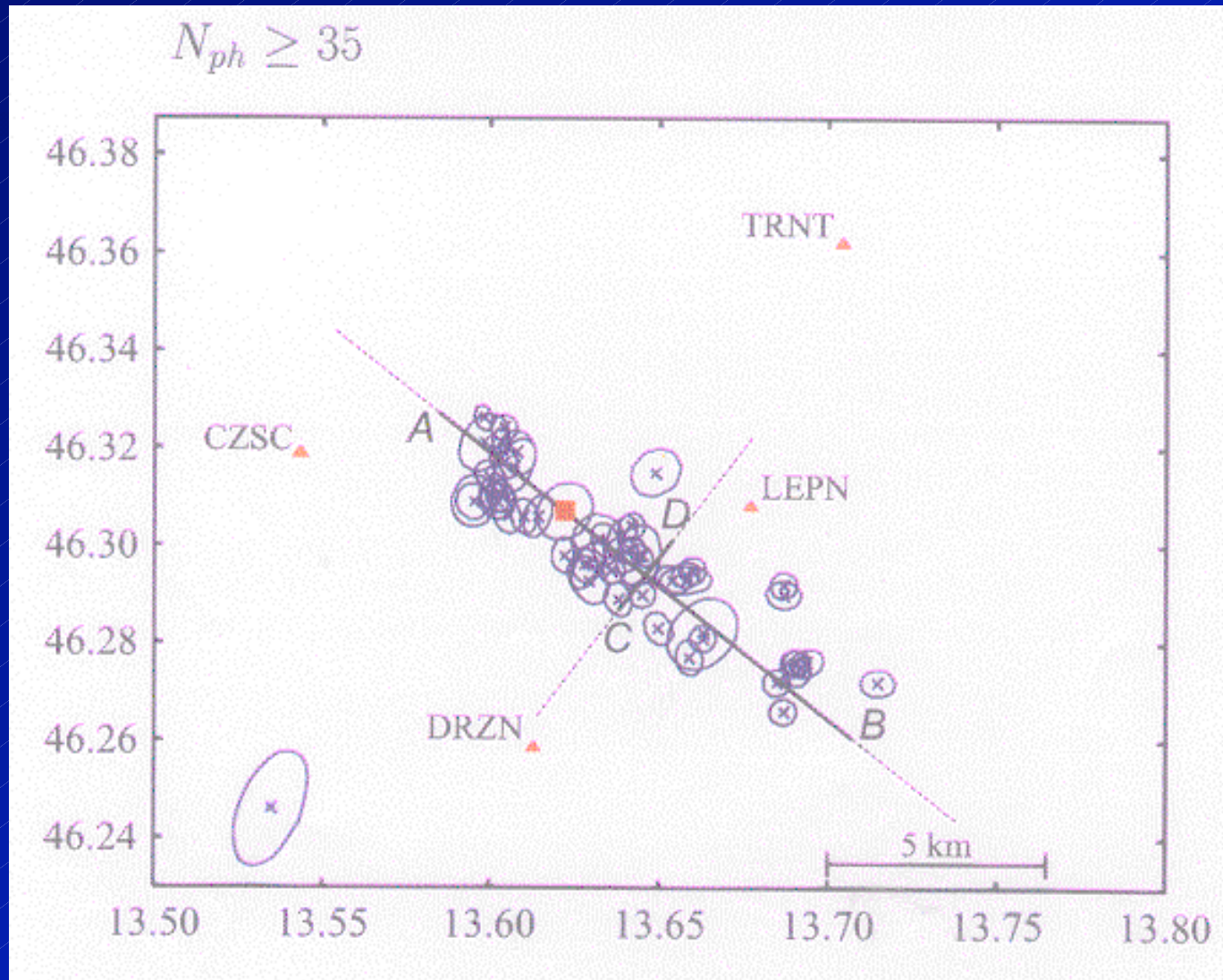
Bovec 1998 - Locations



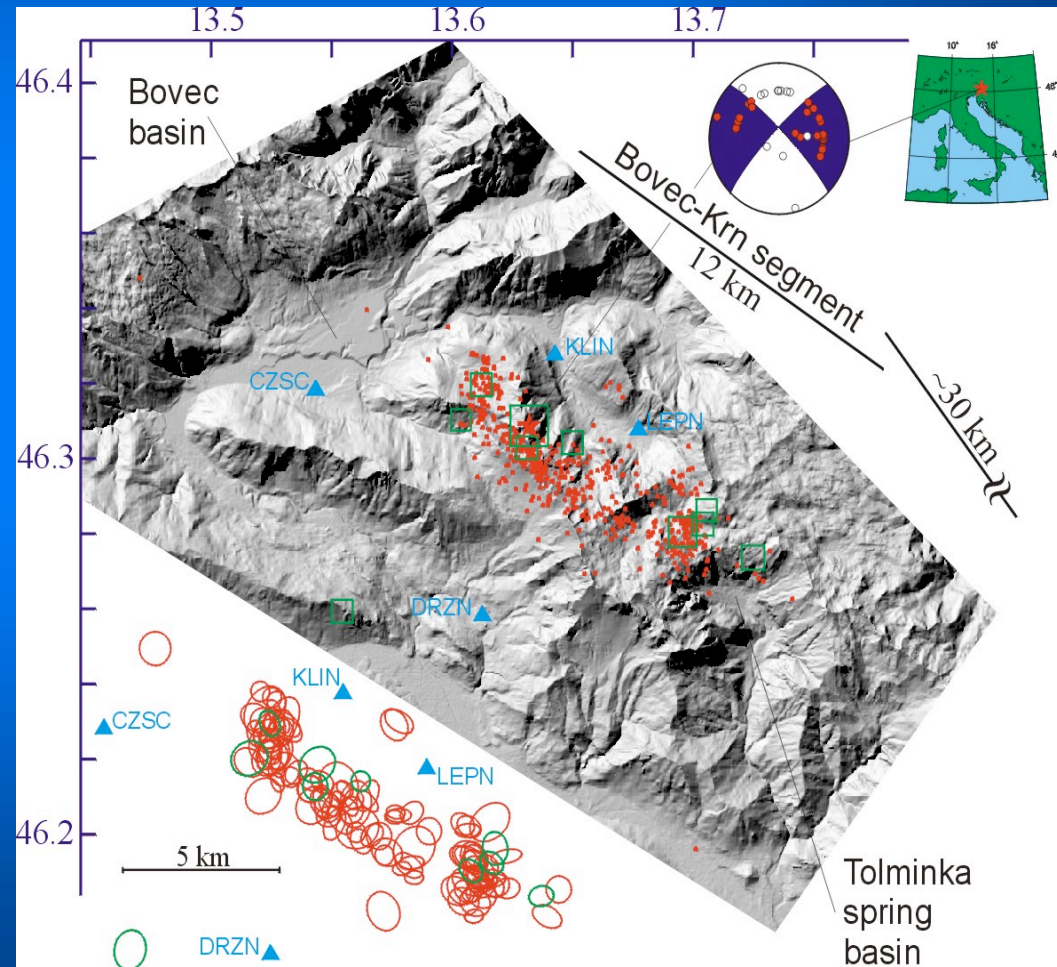
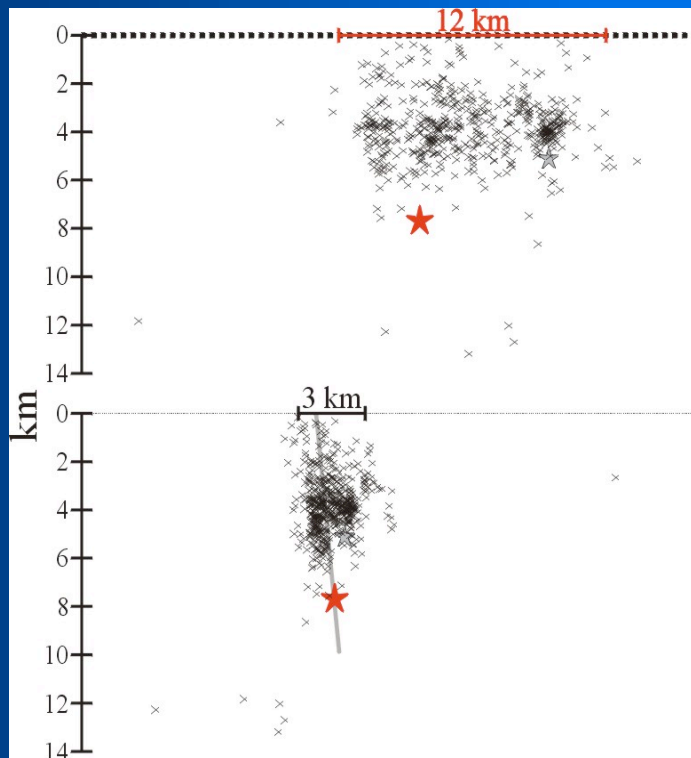
Bovec 1998 - Relocations



Bovec 1998 - Relocation errors

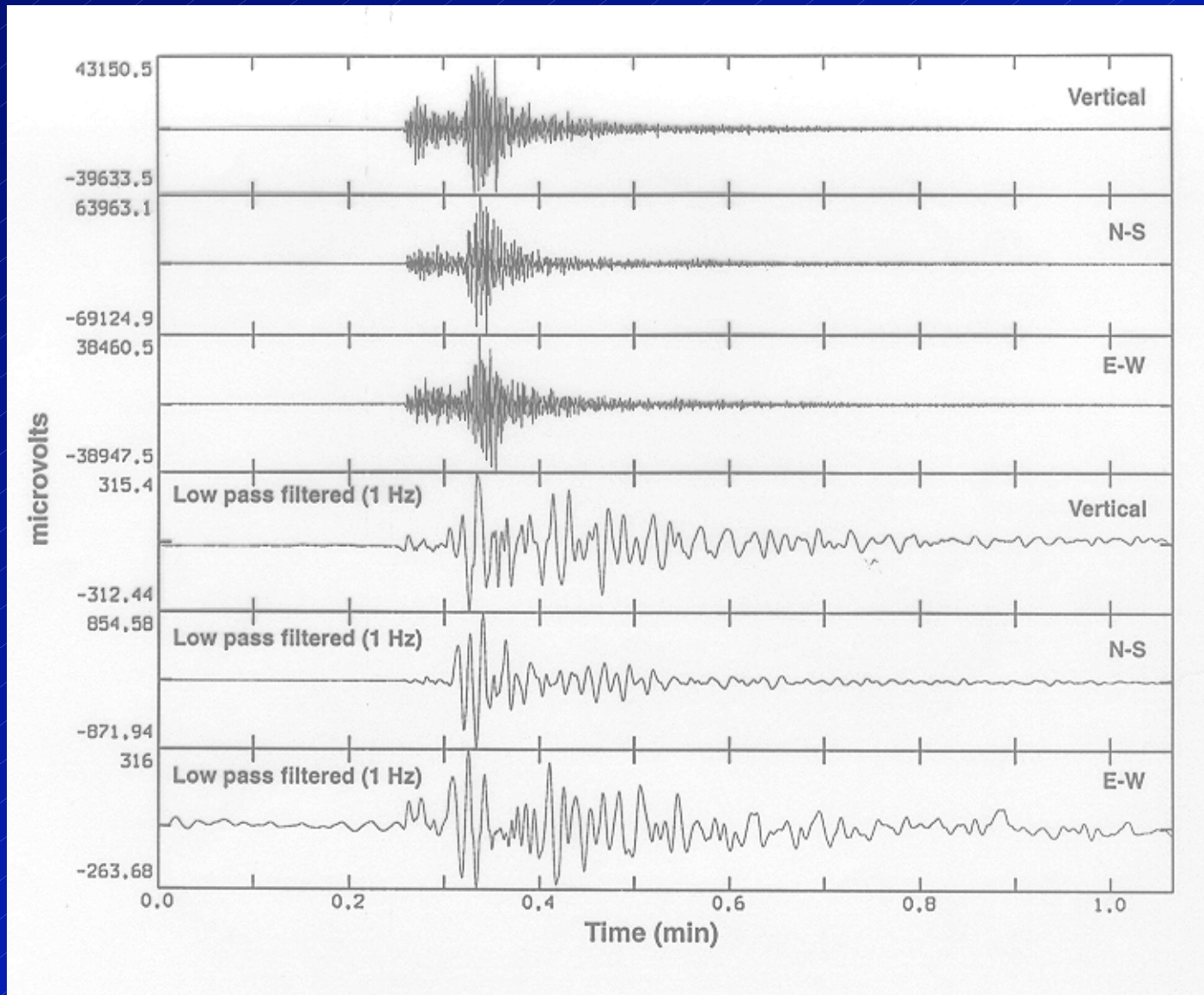


The 1998 Bovec earthquake sequence

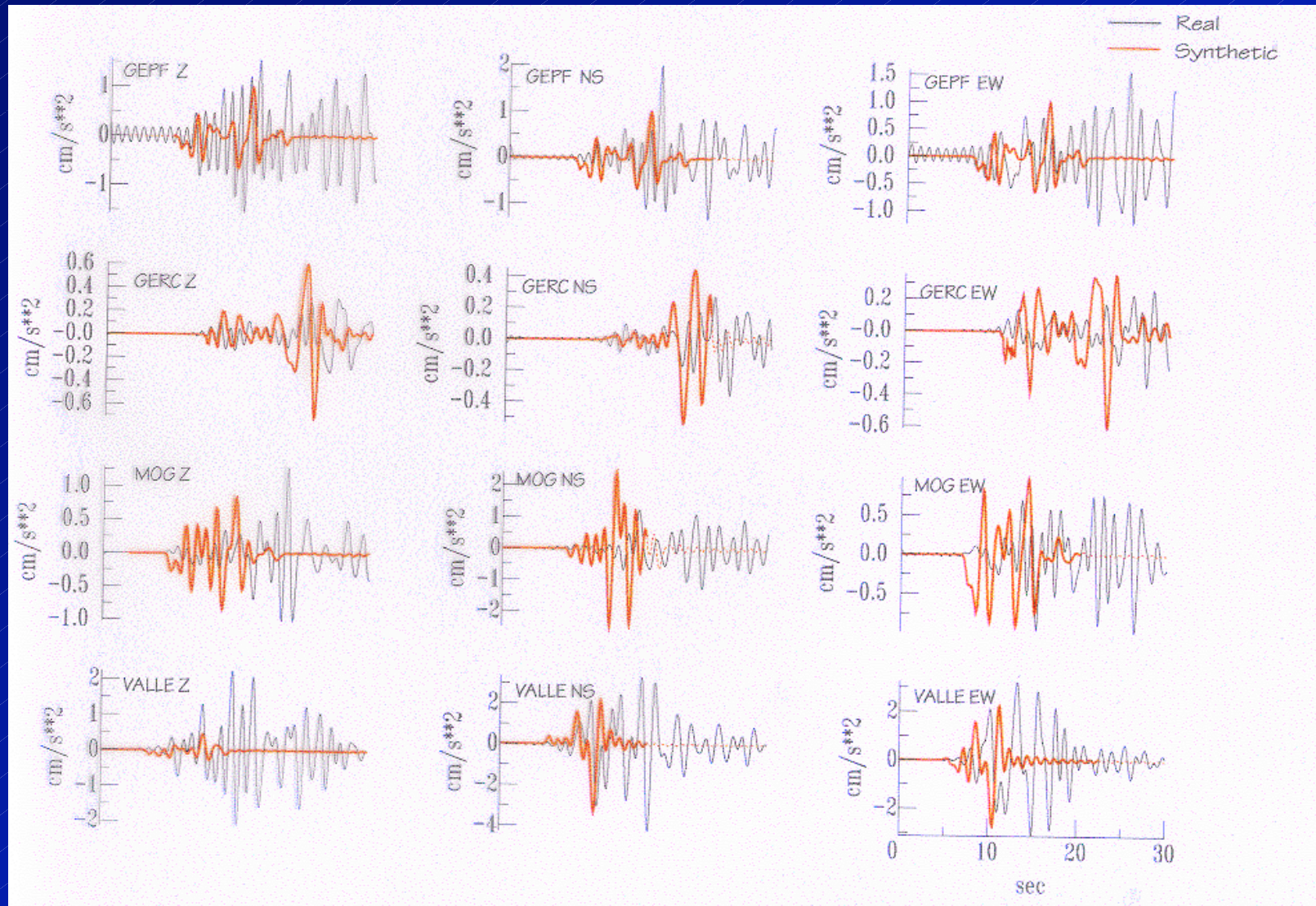


ICTP 2004

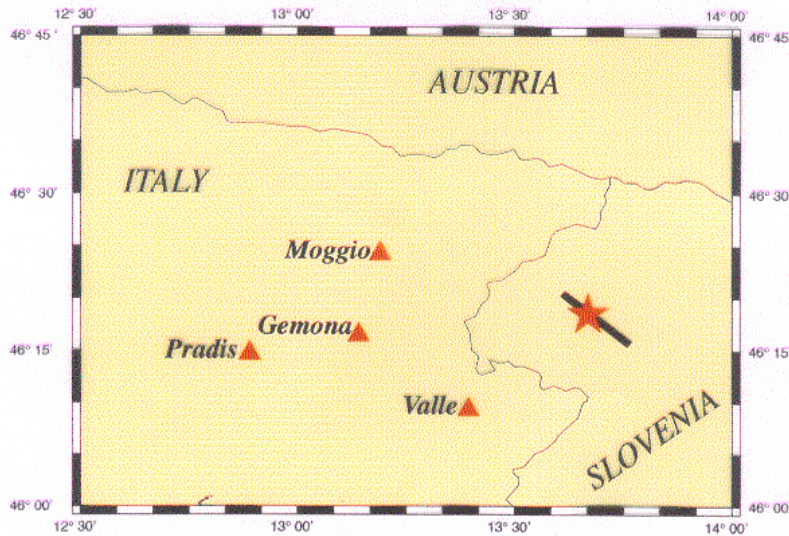
Filtering of data - max freq 1 Hz



Which portion to invert?

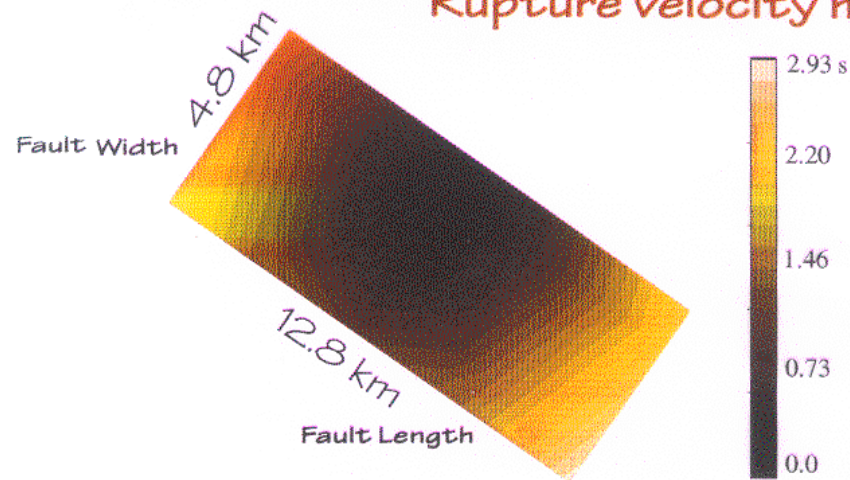


1 - Fault parameters



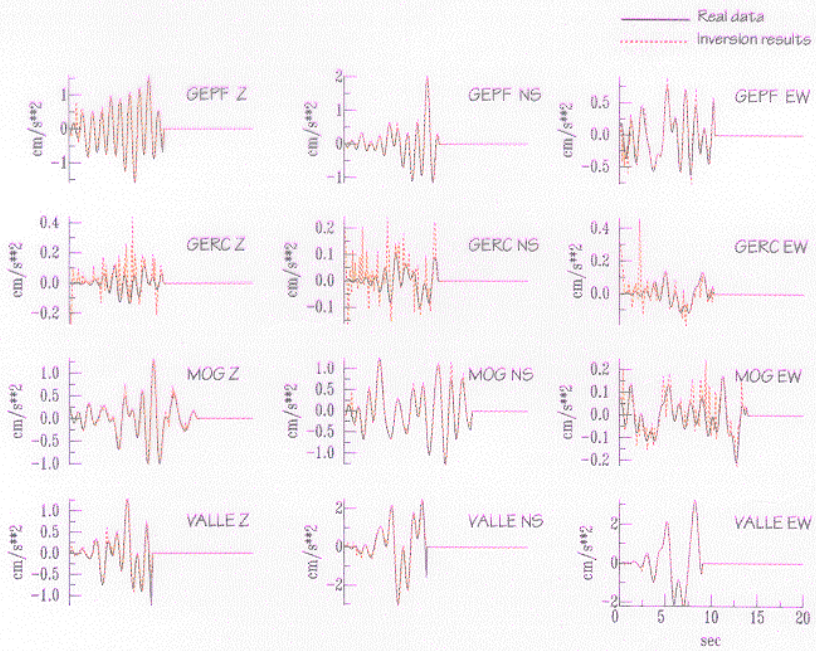
Hypocenter : $46^{\circ}.31 - 13^{\circ}.67$ Depth: 9.0 km
Top of the fault depth: 4.5 km
Strike: 313° Dip: 82° Rake: 178°

Rupture velocity model

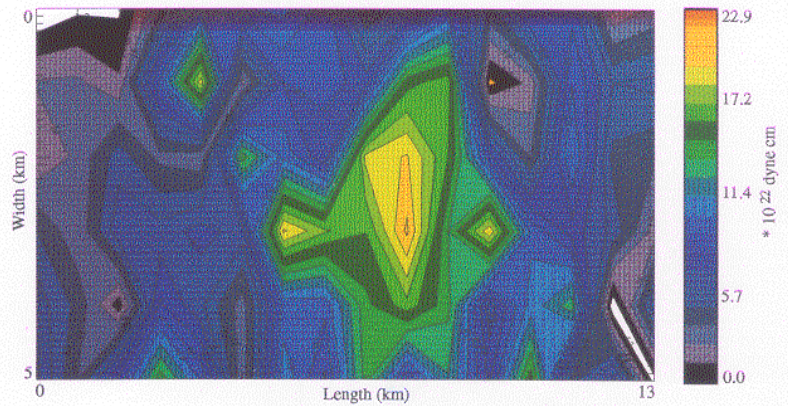


Model 1

1 - INVERSION RESULTS



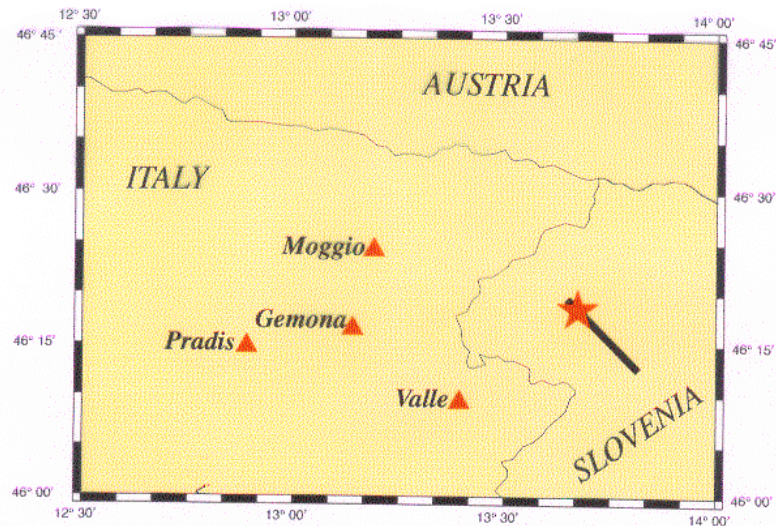
Total moment distribution



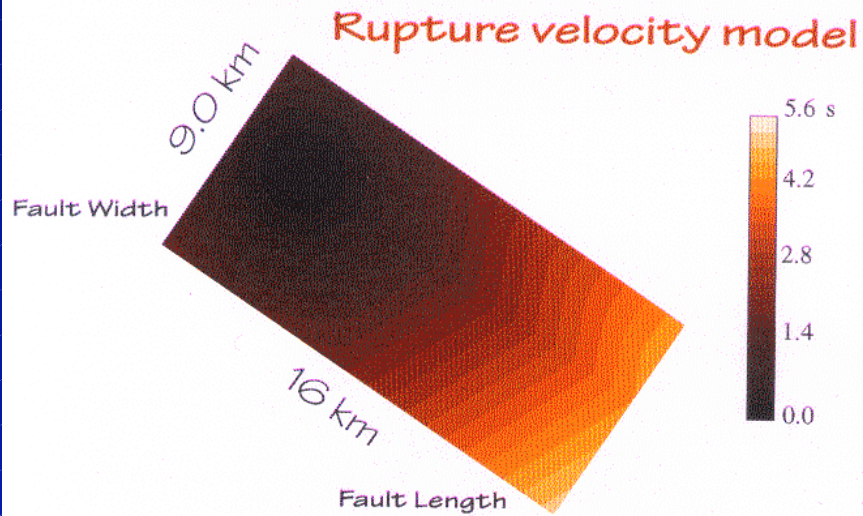
$M_0 = 5.4 \times 10^{24}$ dyne*cm

Model 1

2 - Fault parameters

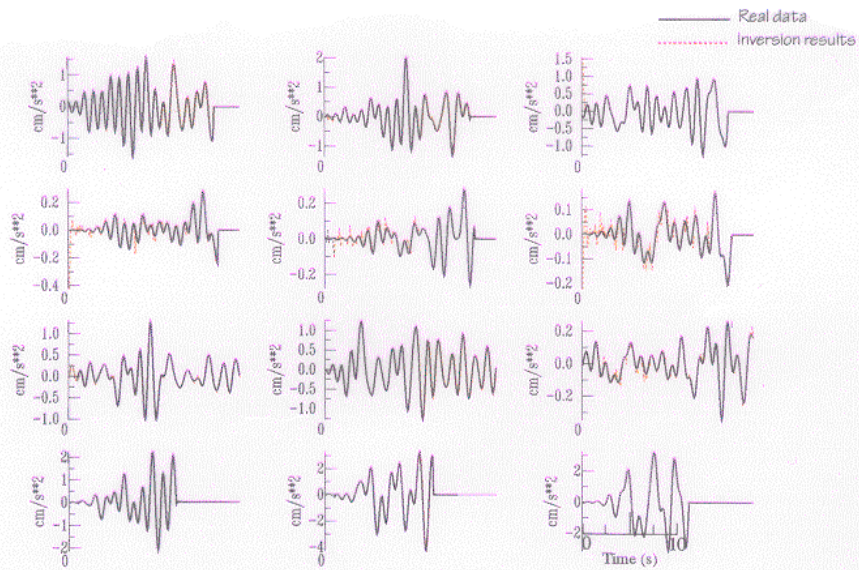


Hypocenter : $46^{\circ}.31 - 13^{\circ}.67$ Depth: 11.0 km
Top of the fault depth: 4.5 km
Strike: 313° Dip: 82° Rake: 178°

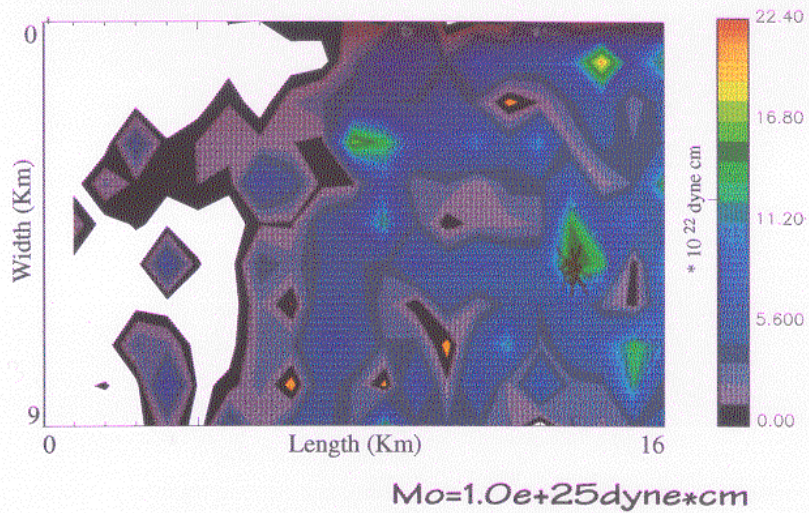


Model 2

2 - INVERSION RESULTS

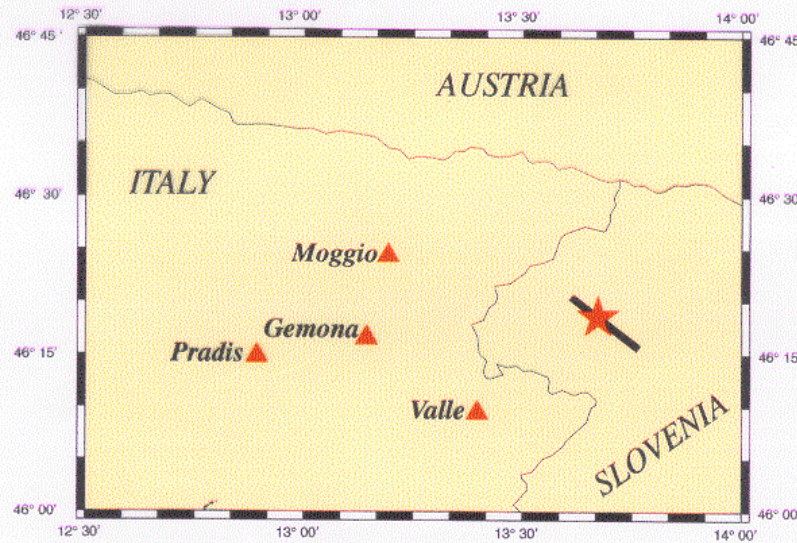


Total moment distribution



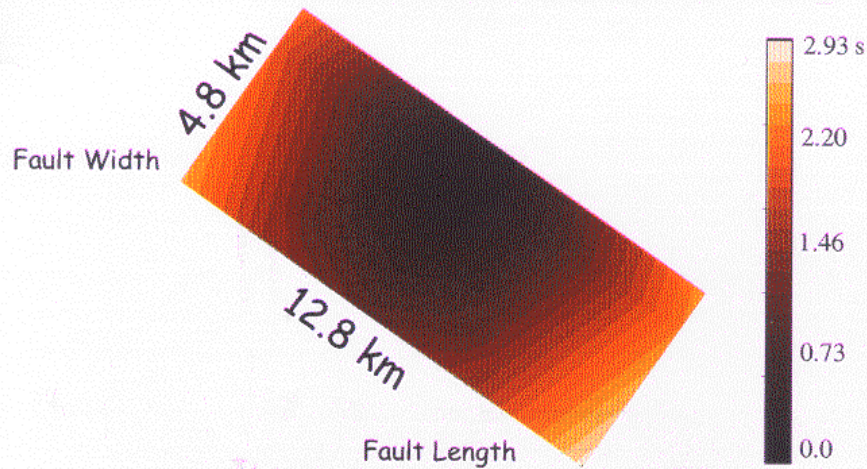
Model 2

3 - Fault parameters



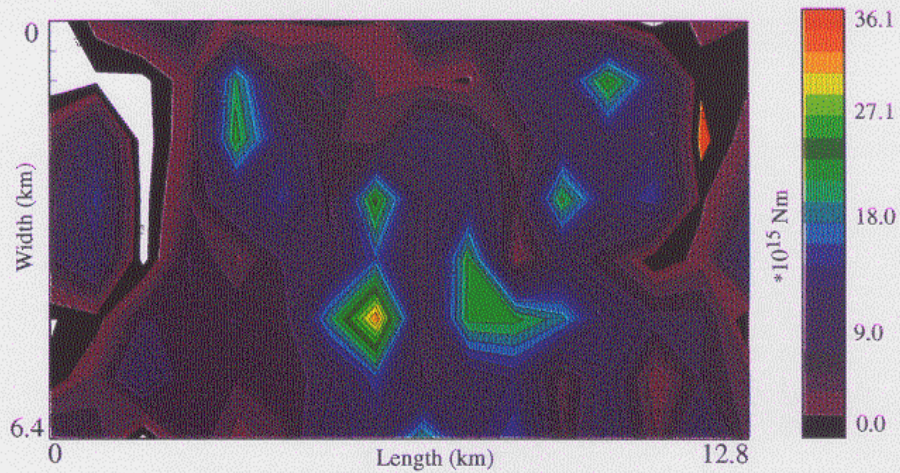
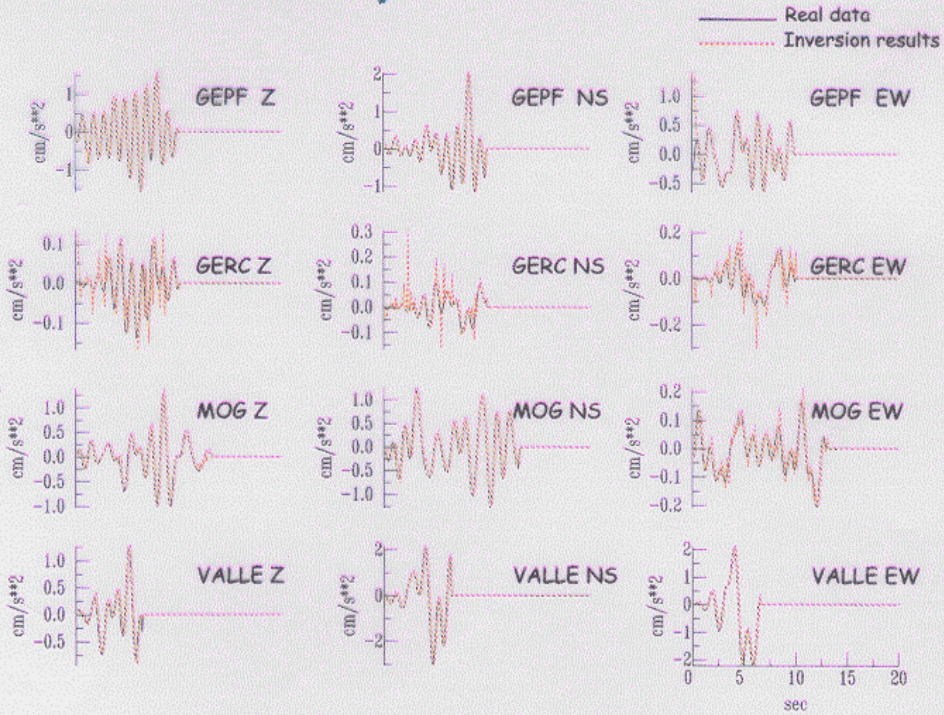
Hypocenter : $46^{\circ}.31 - 13^{\circ}.67$ Depth: 9.0 km
Top of the fault depth: 4.0 km
Strike: 313° Dip: 82° Rake: 178°

Rupture velocity model



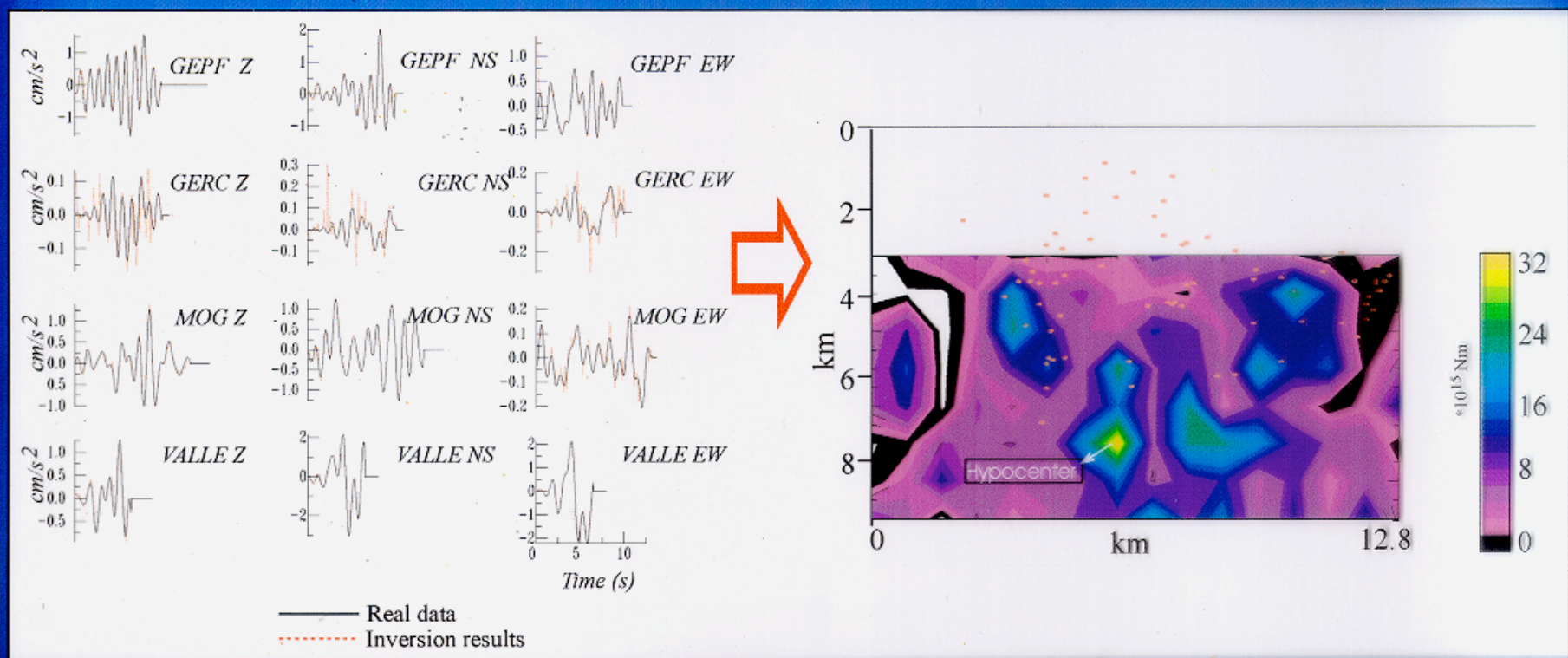
Model 3

3 - Fault parameters

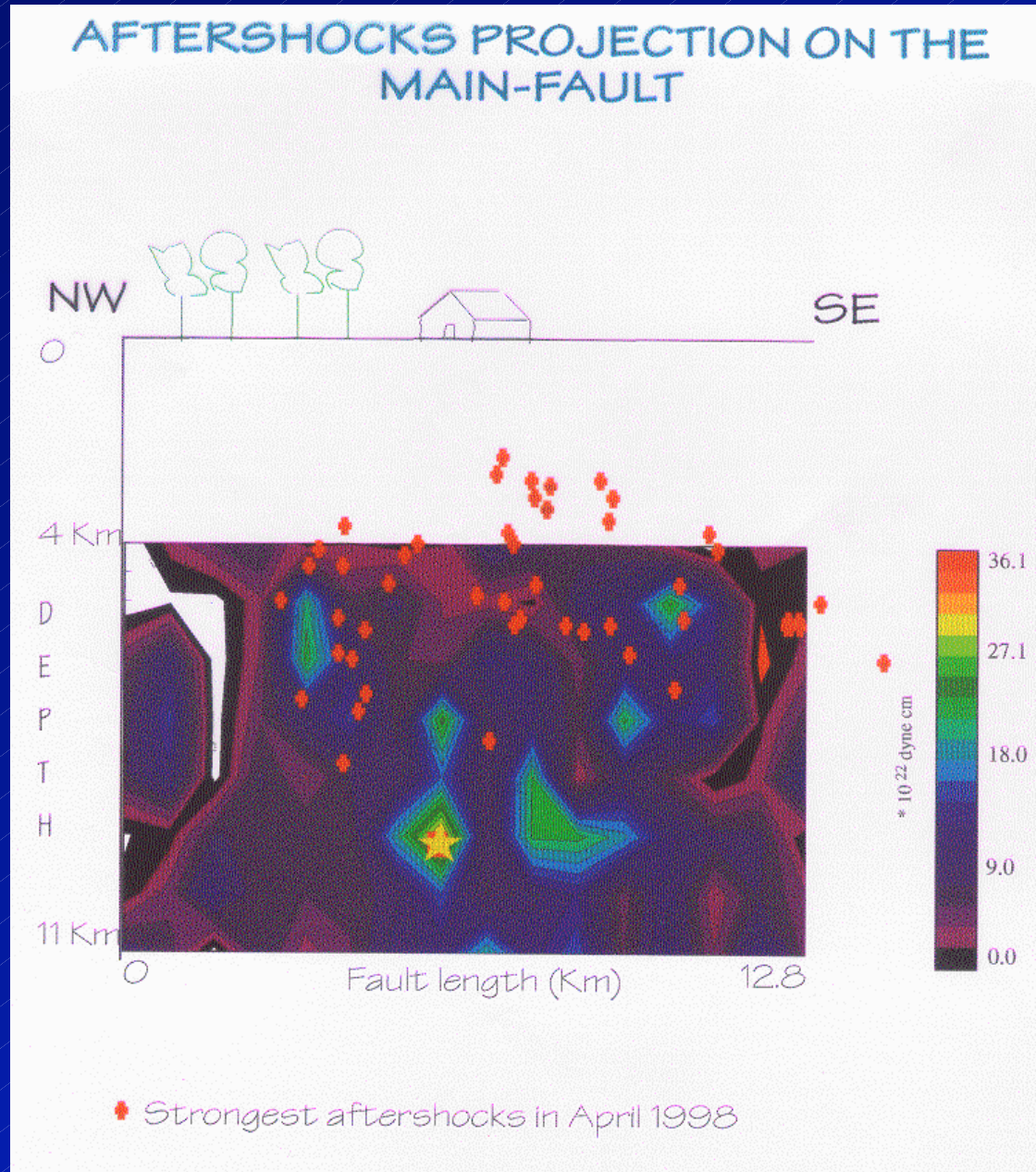


Model 3

Results

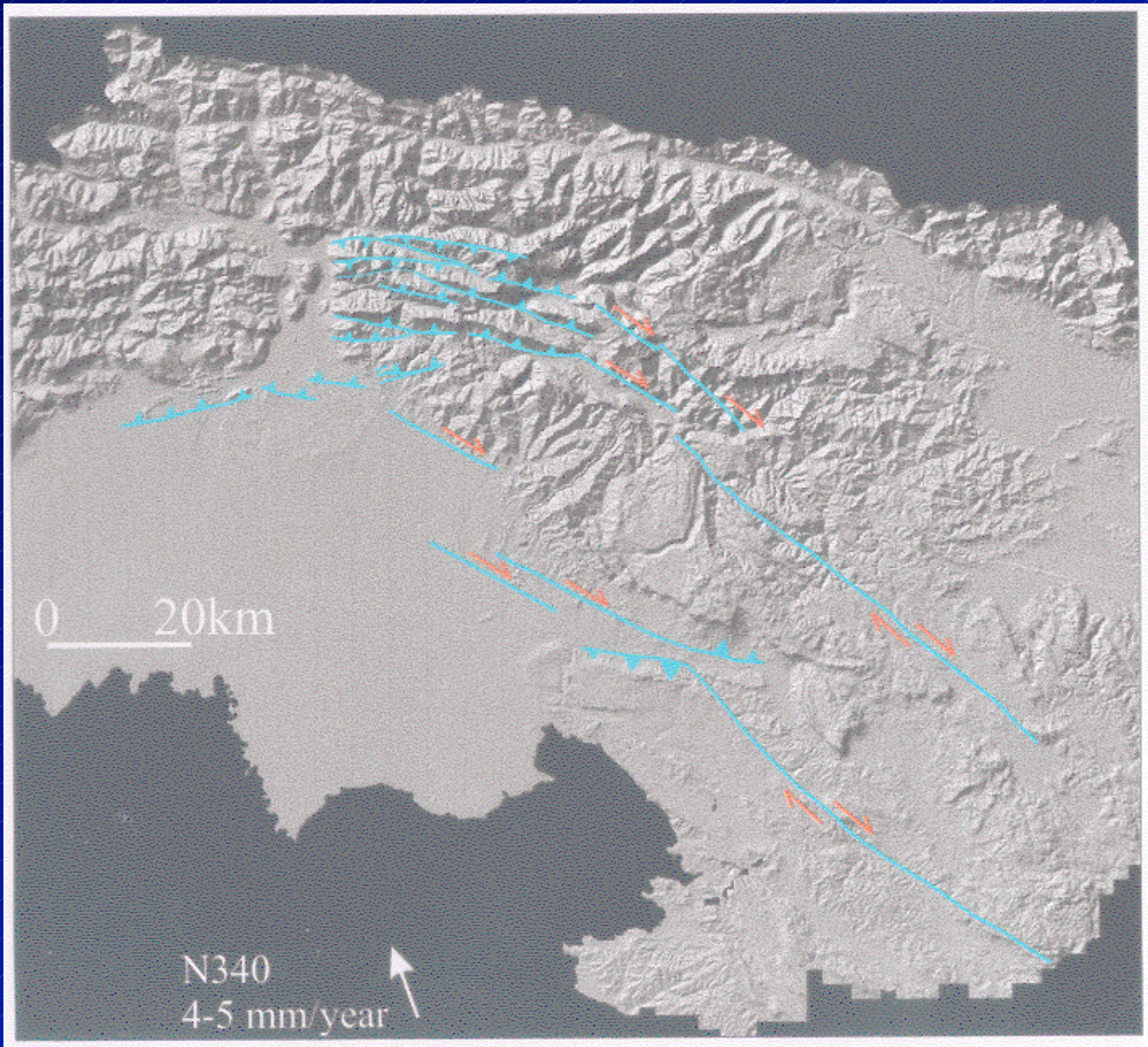


Final

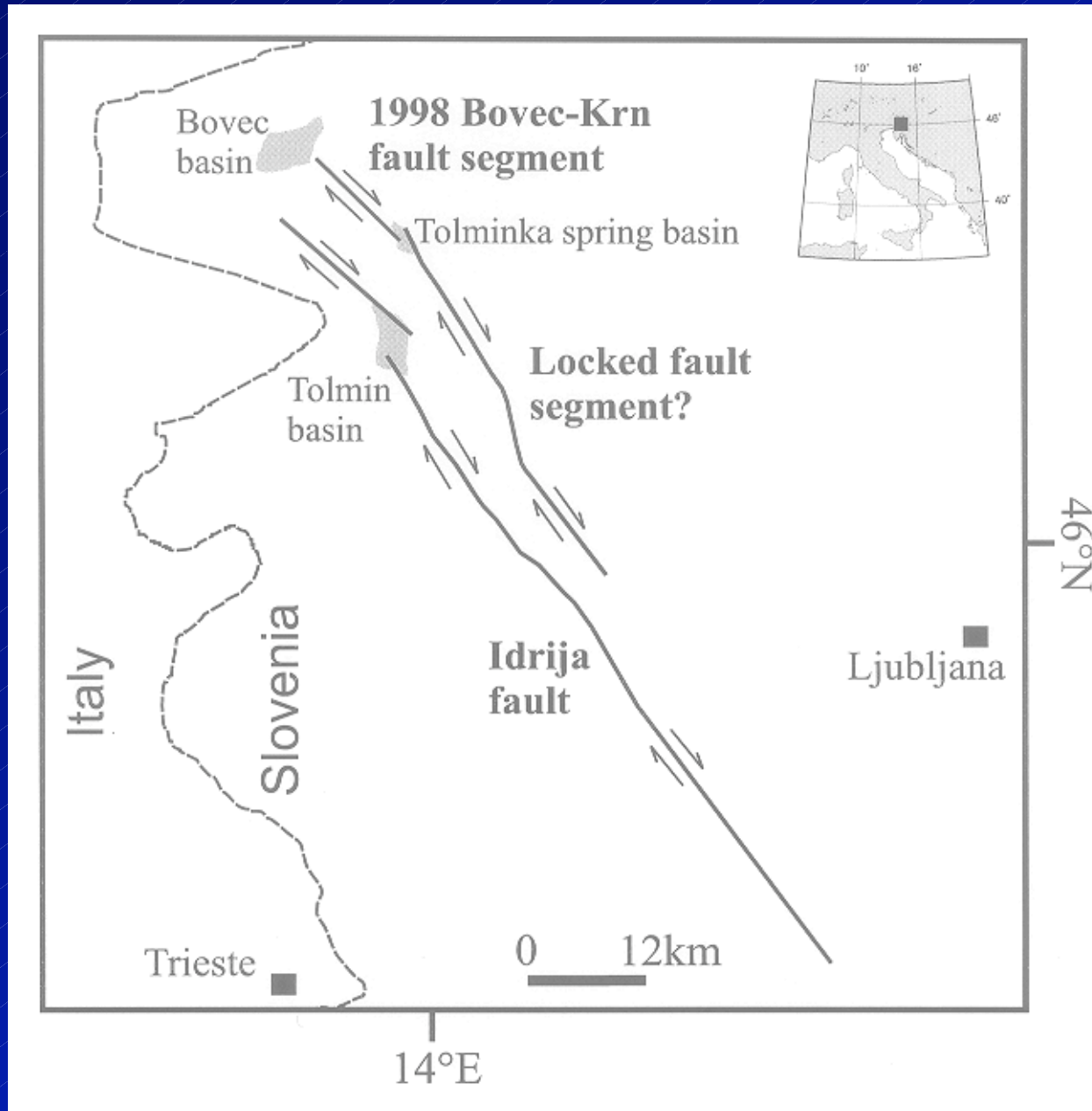


Active faults in NE Italy and W Slovenia

Aoudia(1999)



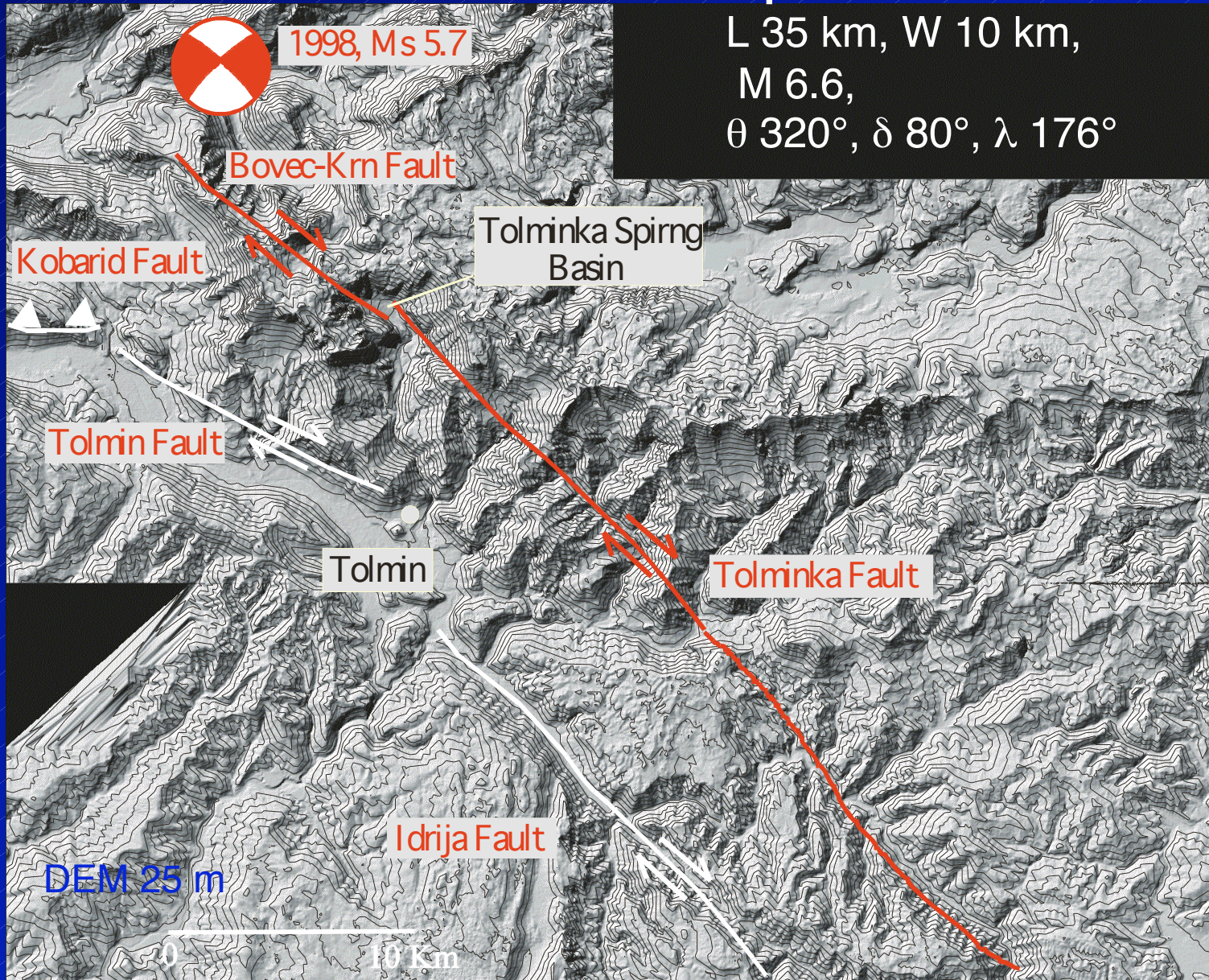
Slide



The Tolminka Fault

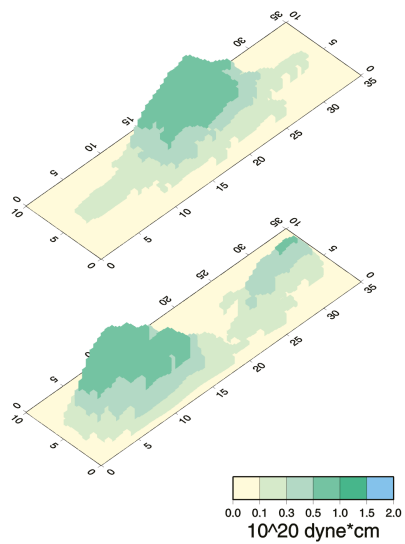
Input Fault Model:

L 35 km, W 10 km,
M 6.6,
 θ 320°, δ 80°, λ 176°

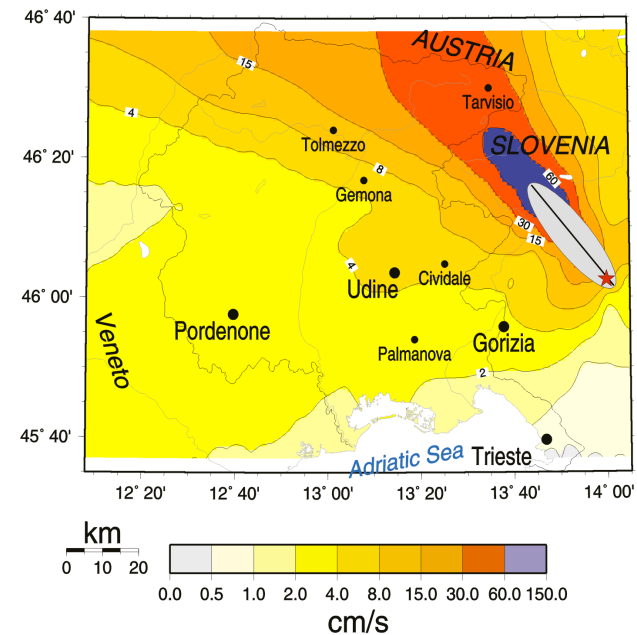
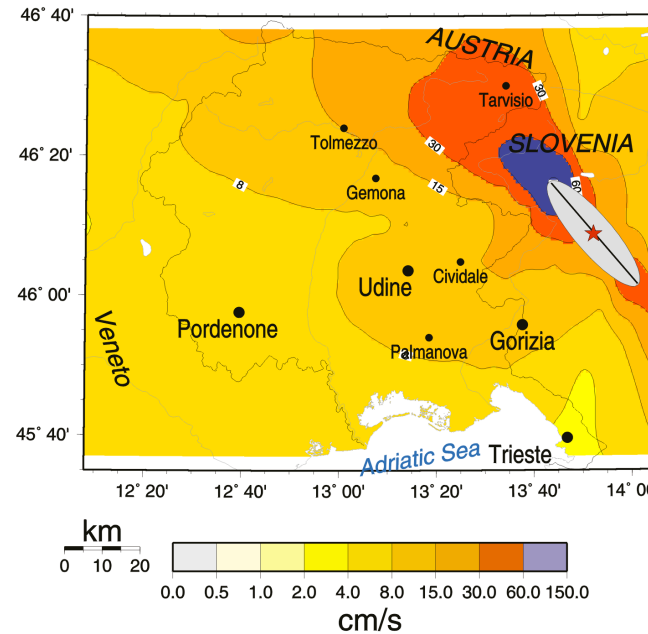
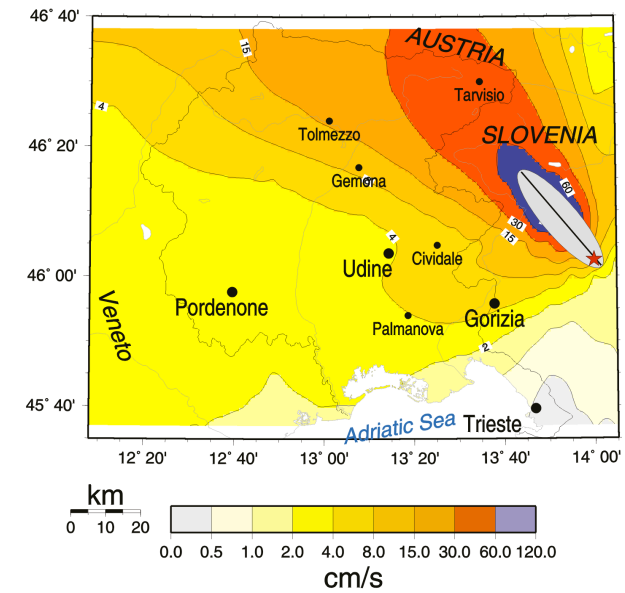
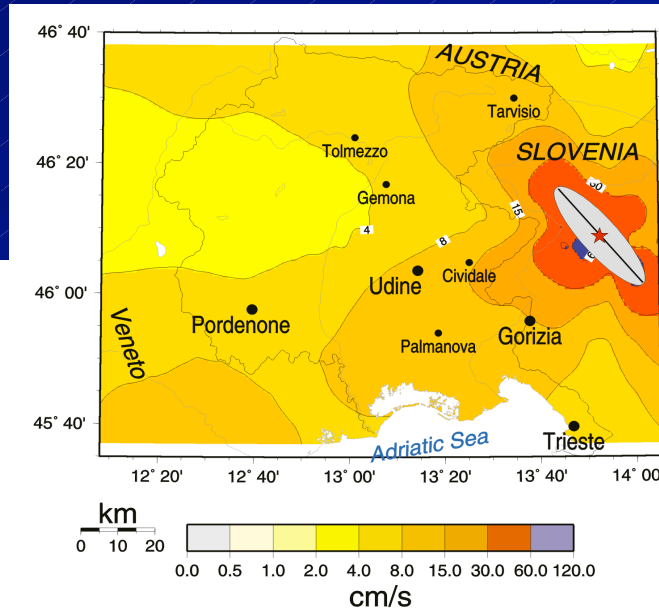


The Tolminka Fault: Results – 1 Hz

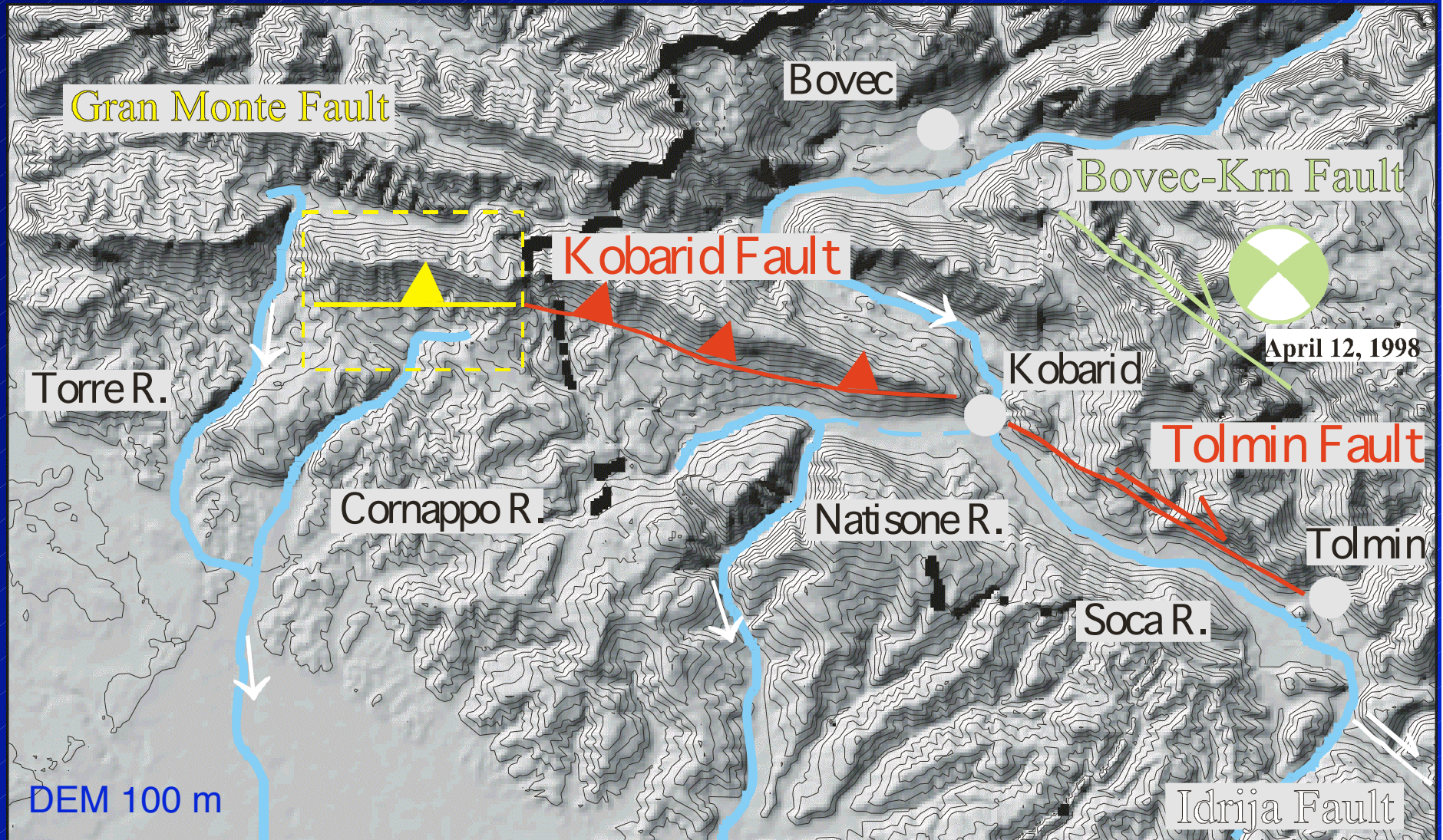
Single
Asperity



Double
Asperity



The Kobarid-Tolmin Fault

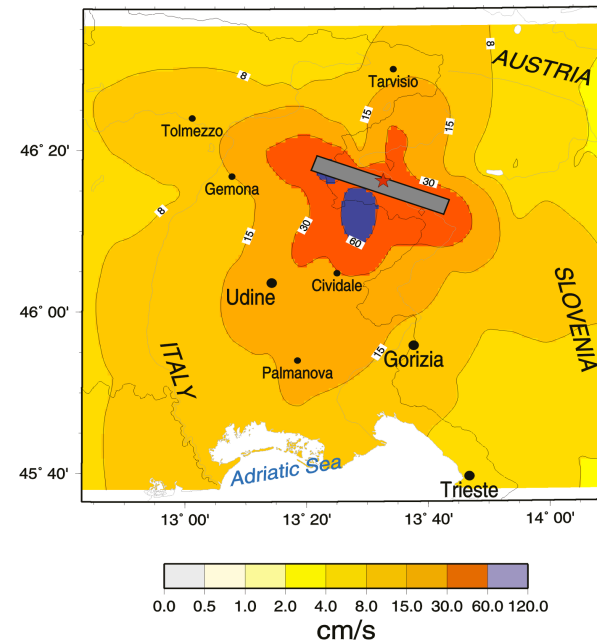
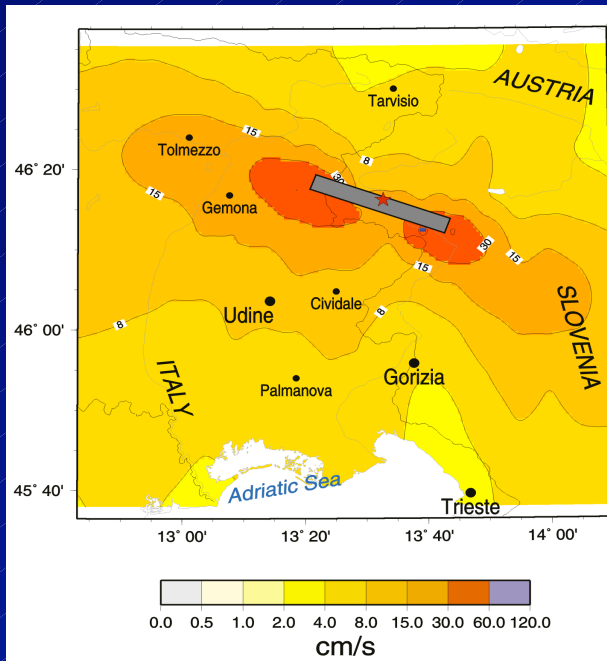
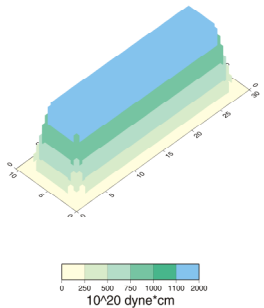


Input Fault Model: L 30 km, W 10.5 km, M 6.6, θ 290°, δ 70°, λ 146°

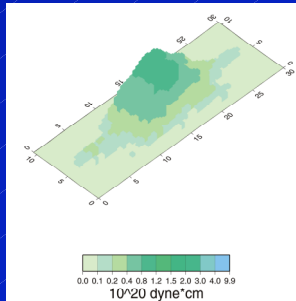
ICTP 2004

The Kobarid-Tolmin Fault (1 Hz): Results

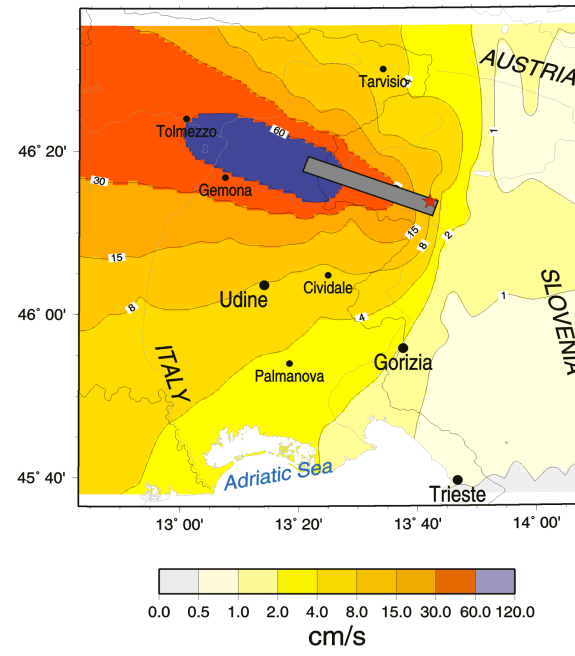
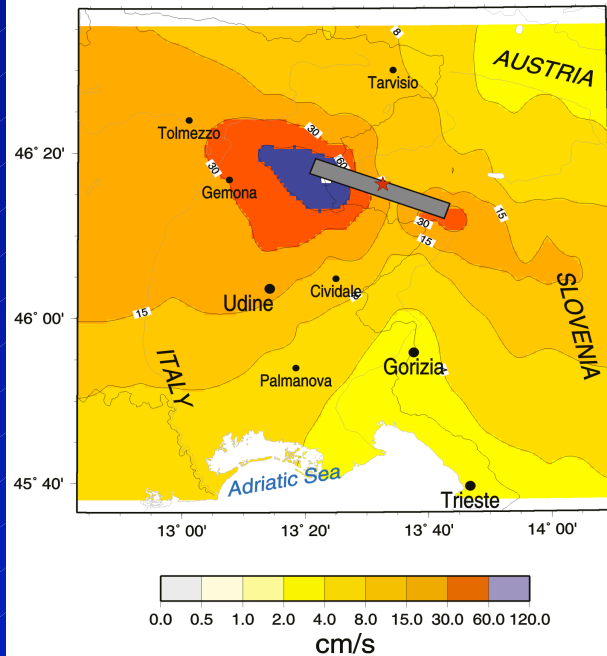
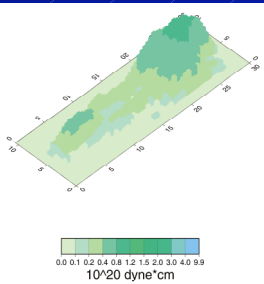
Uniform
Seismic
Moment
Distributio



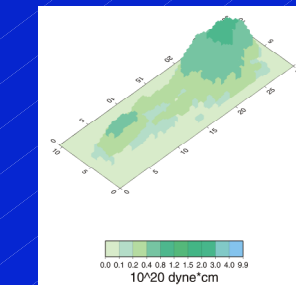
Single
Asperity



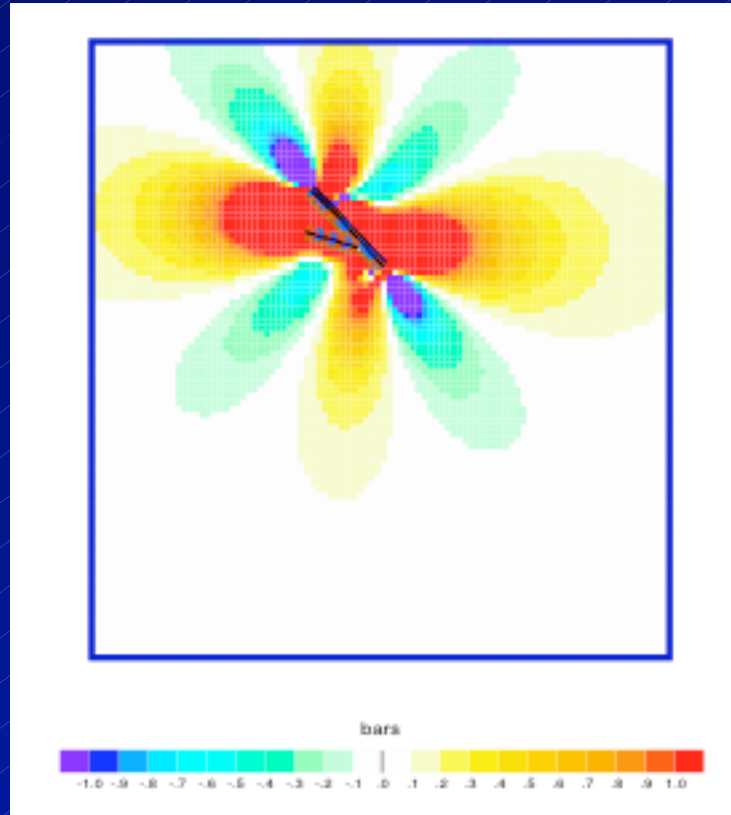
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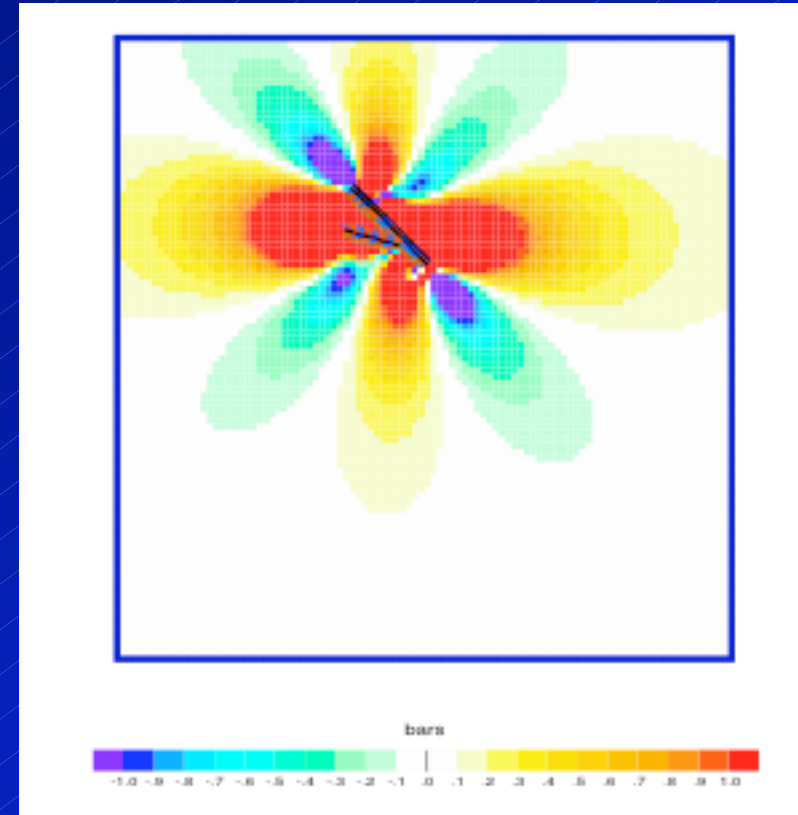
Double
Asperity



Coulomb stress change



After 1998 event modeled with
finite fault model of Bajc et al.
(2002)



After 1998 and 2004 events:
modeled with
finite fault models of Bajc et al.
(2002) and with uniform slip

Which active fault will rupture next?

The Coulomb stress change would thus favour an increased stress on the Kobarid-Tolmin fault and a reduced stress on the Tolminka fault

Which will be the next ruptured fault depends however on the accumulated stress level on the two faults...