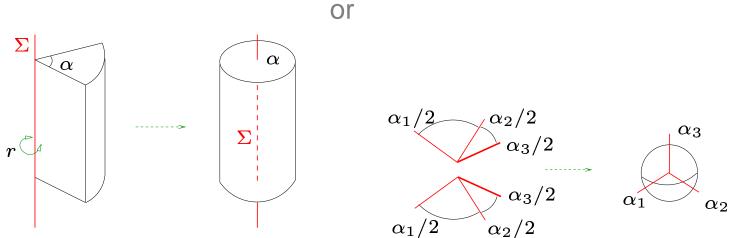
Spherical cone structures on 2-bridge links

Joan Porti (UAB)

ICTP Trieste, June 24, 2005

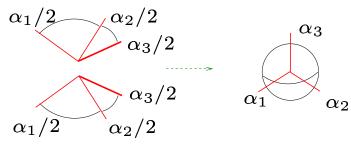
• A Euclidean cone 3-manifold is locally isometric to Euclidean space except at the singular locus Σ . Σ is a graph locally isometric to either



 A Euclidean cone 3-manifold is locally isometic to Euclidean space except at the singular locus Σ . Σ is a graph locally isometric to either or

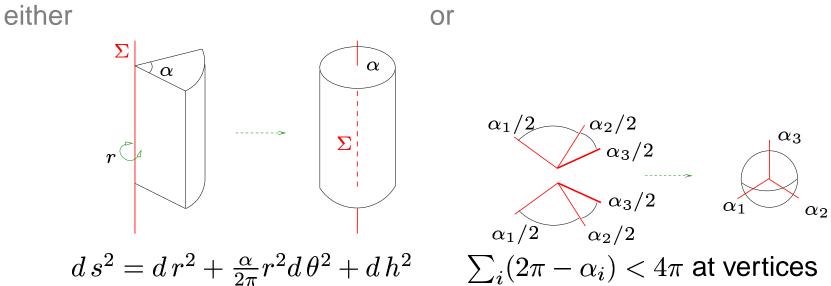
 α

$$d\,s^2=d\,r^2+rac{lpha}{2\pi}r^2d\,\theta^2+d\,h^2$$
 $\sum_i(2\pi-lpha_i)<4\pi$ at vertices



$$\sum_i (2\pi - lpha_i) < 4\pi$$
 at vertices

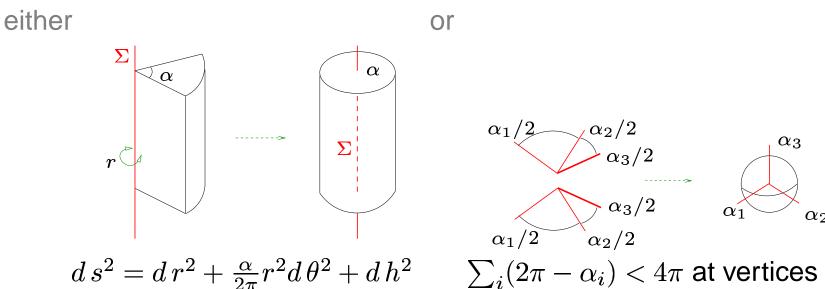
• A Euclidean cone 3-manifold is locally isometric to Euclidean space except at the singular locus Σ . Σ is a graph locally isometric to



Euclidean can be replaced by spherical or hyperbolic.

hyperbolic:
$$ds^2 = dr^2 + \frac{\alpha}{2\pi}\sinh^2(r) d\theta^2 + \cosh^2(r) dh^2$$

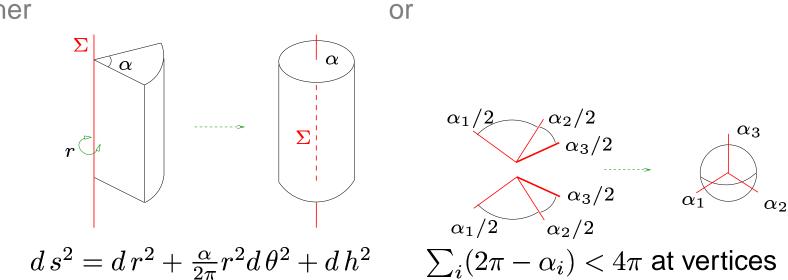
• A Euclidean cone 3-manifold is locally isometric to Euclidean space except at the singular locus Σ . Σ is a graph locally isometric to



Euclidean can be replaced by spherical or hyperbolic.

spherical:
$$d s^2 = d r^2 + \frac{\alpha}{2\pi} \sin^2(r) d \theta^2 + \cos^2(r) d h^2$$

• A Euclidean cone 3-manifold is locally isometric to Euclidean space except at the singular locus Σ . Σ is a graph locally isometric to either



- Euclidean can be replaced by spherical or hyperbolic.
- Locally defined as metric cone on spherical (n-1)- cone manifolds

Motivation and goal

• Cone 3-manifolds are well understood when cone angles are $\leq \pi$ (in the proof of the orbifold theorem)



- e.g. $\sum_{i} (2\pi \alpha_i) < 4\pi$ at vertices implies that
 - for cone angles $< 2\pi/3$ singular vertices do not occur
 - for cone angles $<\pi$ all singular vertices are trivalent and during deformations the singular locus does not cross

Motivation and goal

• Cone 3-manifolds are well understood when cone angles are $\leq \pi$ (in the proof of the orbifold theorem)

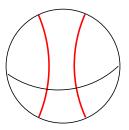


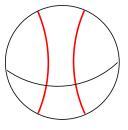
- e.g. $\sum_{i} (2\pi \alpha_i) < 4\pi$ at vertices implies that
 - for cone angles $< 2\pi/3$ singular vertices do not occur
 - for cone angles $<\pi$ all singular vertices are trivalent and during deformations the singular locus does not cross

GOAL: study examples with cone angle $\geq \pi$

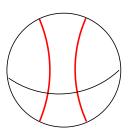
 S^3 with singular locus Σ = two bridge knots and links

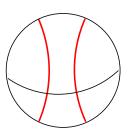
 $\Sigma = L \subset S^3$ is obtained by gluing two trivial 2-tangles:

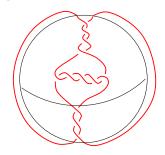




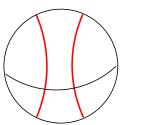
 $\Sigma = L \subset S^3$ is obtained by gluing two trivial 2-tangles:

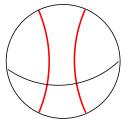


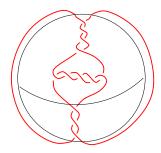




 $\Sigma = L \subset S^3$ is obtained by gluing two trivial 2-tangles:



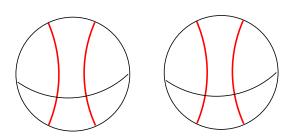


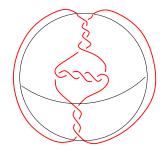


 $L \subset S^3$ has at most two components and it is:

- either hyperbolic ($S^3 L$ complete hyperbolic).
- ullet or a torus link t(2,n) (L is made of fibres of a Seifert fibration of S^3)

 $\Sigma = L \subset S^3$ is obtained by gluing two trivial 2-tangles:

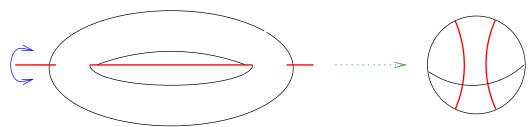




 $L \subset S^3$ has at most two components and it is:

- either hyperbolic ($S^3 L$ complete hyperbolic).
- ullet or a torus link t(2,n) (L is made of fibres of a Seifert fibration of S^3)

The double cover of S^3 branched along L is a (generalized) lens space



 $L \subset S^3$ 2-bridge knot or link

 $C(\alpha)$ = cone structure on S^3 , singular along $\Sigma = L$ and cone angle α .

 $L \subset S^3$ 2-bridge knot or link $C(\alpha) = \text{cone structure on } S^3$, singular along $\Sigma = L$ and cone angle α .

- $C(\pi)$ is spherical (the double branched cover is a lens space).
- If L hyperbolic, then $C(\alpha)$ hyperbolic for $\alpha \in [0, \varepsilon)$. (by W. Thurston's hyperbolic Dehn filling).

 $L \subset S^3$ 2-bridge knot or link $C(\alpha) = \text{cone structure on } S^3$, singular along $\Sigma = L$ and cone angle α .

- $C(\pi)$ is spherical (the double branched cover is a lens space).
- If L hyperbolic, then $\underline{C}(\alpha)$ hyperbolic for $\alpha \in [0, \varepsilon)$. (by W. Thurston's hyperbolic Dehn filling).
- From the proof of the orbifold thm:

If L hyperbolic, then there exists $\frac{2\pi}{3} \leq \alpha_0 < \pi$ such that $C(\alpha_0)$ Euclidean.

(
$$\alpha_0 = \frac{2\pi}{3}$$
 iff $L =$ figure eigth)

 $L \subset S^3$ 2-bridge knot or link $C(\alpha) = \text{cone structure on } S^3$, singular along $\Sigma = L$ and cone angle α .

- $C(\pi)$ is spherical (the double branched cover is a lens space).
- If L hyperbolic, then $C(\alpha)$ hyperbolic for $\alpha \in [0, \varepsilon)$. (by W. Thurston's hyperbolic Dehn filling).
- If L hyperbolic, then there exists $\frac{2\pi}{3} \leq \alpha_0 < \pi$ such that

$$C(\alpha) \text{ is } \begin{cases} \text{ hyperbolic if } \alpha < \alpha_0 \\ \text{ Euclidian if } \alpha = \alpha_0 \\ \text{ spherical if } \alpha_0 < \alpha \leq \pi \end{cases}$$

 $L \subset S^3$ 2-bridge knot or link $C(\alpha) = \text{cone structure on } S^3$, singular along $\Sigma = L$ and cone angle α .

- $C(\pi)$ is spherical (the double branched cover is a lens space).
- If L hyperbolic, then $C(\alpha)$ hyperbolic for $\alpha \in [0, \varepsilon)$. (by W. Thurston's hyperbolic Dehn filling).
- If L hyperbolic, then there exists $\frac{2\pi}{3} \leq \alpha_0 < \pi$ such that

$$C(\alpha) \text{ is } \begin{cases} \text{ hyperbolic if } \alpha < \alpha_0 \\ \text{ Euclidian if } \alpha = \alpha_0 \\ \text{ spherical if } \alpha_0 < \alpha \leq \pi \end{cases}$$

Question: what happens for $\alpha > \pi$?

Theorem

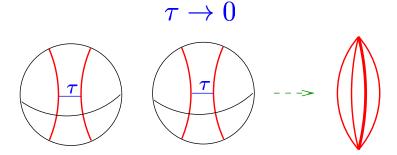
If L is a hyperbolic two bridge link, $C(\alpha_0)$ Euclidean, then $C(\alpha)$ is spherical for $\alpha \in (\alpha_0, 2\pi - \alpha_0)$.

• When $\alpha \to 2\pi - \alpha_0$, $C(\alpha) \to {\rm spherical\ suspension\ of\ }$ sphere with 4 cone points and the tunnels shrink to a point.

Theorem

If L is a hyperbolic two bridge link, $C(\alpha_0)$ Euclidean, then $C(\alpha)$ is spherical for $\alpha \in (\alpha_0, 2\pi - \alpha_0)$.

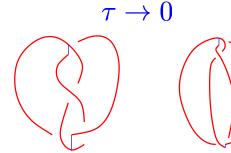
- When $\alpha \to 2\pi \alpha_0$, $C(\alpha) \to {\rm spherical\ suspension\ of\ }$ sphere with 4 cone points and the tunnels shrink to a point.
- When $\alpha \to 2\pi \alpha_0$



Theorem

If L is a hyperbolic two bridge link, $C(\alpha_0)$ Euclidean, then $C(\alpha)$ is spherical for $\alpha \in (\alpha_0, 2\pi - \alpha_0)$.

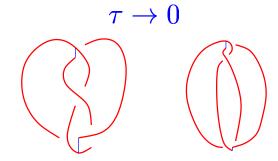
- When $\alpha \to 2\pi \alpha_0$, $C(\alpha) \to {\rm spherical\ suspension\ of\ }$ sphere with 4 cone points and the tunnels shrink to a point.
- When $\alpha \to 2\pi \alpha_0$



Theorem

If L is a hyperbolic two bridge link, $C(\alpha_0)$ Euclidean, then $C(\alpha)$ is spherical for $\alpha \in (\alpha_0, 2\pi - \alpha_0)$.

- When $\alpha \to 2\pi \alpha_0$, $C(\alpha) \to {\rm spherical\ suspension\ of\ }$ sphere with 4 cone points and the tunnels shrink to a point.
- When $\alpha \to 2\pi \alpha_0$



• When $\alpha \to \alpha_0$, rescale $\frac{1}{\sqrt{\alpha - \alpha_0}}C(\alpha) \to C(\alpha_0)$ Euclidean.

A tool for the proof: variety of representations

Want to deform incomplete metrics on S^3-L that complete to $C(\alpha)$

$$egin{aligned} egin{aligned} egin{aligned} Dev \colon & \widetilde{S^3-L}
ightarrow S^3 & \textit{(local isometry)} \ & \textit{hol} \colon & \pi_1(S^3-L)
ightarrow SO(4) & \textit{(representation)} \ & Dev(\gamma \cdot x) = hol(\gamma)(Dev(x)) \end{aligned}$$

- Step 1 Study $hom(\pi_1(S^3 L), SO(4))/SO(4)$
- Step 2 Show that some points in $hom(\pi_1(S^3 L), SO(4))/SO(4)$ give cone structures $C(\alpha)$.

A tool for the proof: variety of representations

Want to deform incomplete metrics on S^3-L that complete to $C(\alpha)$

$$egin{aligned} \emph{Dev} \colon & \widetilde{S^3-L}
ightarrow S^3 & \textit{(local isometry)} \ \emph{hol} \colon & \pi_1(S^3-L)
ightarrow SO(4) & \textit{(representation)} \ & Dev(\gamma \cdot x) = hol(\gamma)(Dev(x)) \end{aligned}$$

- Step 1 Study $hom(\pi_1(S^3 L), SO(4))/SO(4)$
- Step 2 Show that some points in $hom(\pi_1(S^3 L), SO(4))/SO(4)$ give cone structures $C(\alpha)$.

Easier to work with
$$\begin{cases} Spin(4) = \widetilde{SO(4)} \cong S^3 \times S^3 \\ Spin(3) = \widetilde{SO(3)} \cong S^3 \quad \text{(diagonal in } Spin(4)) \end{cases}$$

$$\bullet \ S^3 \cong SU(2)$$

$$(a,b) \in S^3 \subset \mathbf{C}^2 \mapsto \left(\begin{smallmatrix} a & b \\ -\overline{b} & \overline{a} \end{smallmatrix} \right) \in SU(2)$$

$$\bullet \ S^3 \cong SU(2)$$

$$(a,b) \in S^3 \subset \mathbf{C}^2 \mapsto \left(\begin{smallmatrix} a & b \\ -\bar{b} & \bar{a} \end{smallmatrix} \right) \in SU(2)$$

$$\bullet \ SU(2) \times SU(2) \cong Spin(4)$$

$$\begin{array}{ccc} SU(2) & \to & SU(2) \\ x & \mapsto & p \, x \, q^{-1} \end{array} \quad \forall p, q \in SU(2)$$

•
$$\underline{S^3 \cong SU(2)}$$
 $(a,b) \in S^3 \subset \mathbf{C}^2 \mapsto \begin{pmatrix} a_{-\bar{b}} & \bar{b} \\ -\bar{b} & \bar{a} \end{pmatrix} \in SU(2)$
• $\underline{SU(2) \times SU(2) \cong Spin(4)}$ $SU(2) \to SU(2)$ $x \mapsto p x q^{-1}$ $\forall p, q \in SU(2)$

• $Spin(3) \cong SU(2) \subset SU(2) \times SU(2)$ diagonal (preserves Re(a) = 0).

•
$$\underline{S^3 \cong SU(2)}$$
 $(a,b) \in S^3 \subset \mathbf{C}^2 \mapsto \begin{pmatrix} a & b \\ -\bar{b} & \bar{a} \end{pmatrix} \in SU(2)$
• $\underline{SU(2) \times SU(2) \cong Spin(4)}$ $SU(2) \rightarrow SU(2)$ $\times p, q \in SU(2)$ $\times p \times q^{-1}$

- $Spin(3) \cong SU(2) \subset SU(2) \times SU(2)$ diagonal (preserves Re(a) = 0).
- (p,q) is a rotation of angle $\theta \iff tr(p) = tr(q) = \pm 2\cos(\theta/2)$.

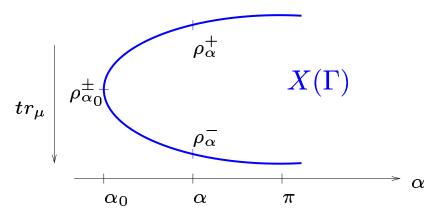
$$\begin{pmatrix} e^{i\alpha} & 0 \\ 0 & e^{-i\alpha} \end{pmatrix} \cdot \begin{pmatrix} a & b \\ -\bar{b} & \bar{a} \end{pmatrix} \cdot \begin{pmatrix} e^{i\beta} & 0 \\ 0 & e^{-i\beta} \end{pmatrix}^{-1} = \begin{pmatrix} e^{i(\alpha-\beta)}a & e^{i(\alpha+\beta)}b \\ -e^{i(-\alpha-\beta)}\bar{b} & e^{i(-\alpha+\beta)}\bar{a} \end{pmatrix}$$

•
$$\underline{S^3 \cong SU(2)}$$
 $(a,b) \in S^3 \subset \mathbf{C}^2 \mapsto \begin{pmatrix} a & b \\ -\bar{b} & \bar{a} \end{pmatrix} \in SU(2)$
• $\underline{SU(2) \times SU(2) \cong Spin(4)}$ $SU(2) \rightarrow SU(2)$ $x \mapsto p x q^{-1}$ $\forall p, q \in SU(2)$

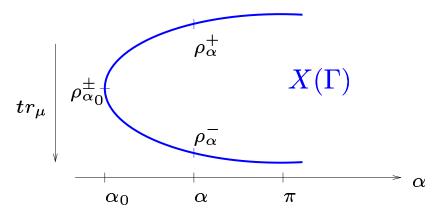
- $Spin(3) \cong SU(2) \subset SU(2) \times SU(2)$ diagonal (preserves Re(a) = 0).
- (p,q) is a rotation of angle $\theta \Longleftrightarrow tr(p) = tr(q) = \pm 2\cos(\theta/2)$.
- $X(\Gamma)= \hom(\Gamma, SU(2))/SU(2)$, $\Gamma=\pi_1(S^3-L)$ Holonomy reps. of $C(\alpha)-L$ viewed in:

$$\{(\rho^+, \rho^-) \in X(\Gamma) \times X(\Gamma) \mid tr(\rho^+(\mu)) = tr(\rho^-(\mu)), \ \mu \text{ meridian}\}$$

$$\begin{split} \bullet \ X(\Gamma) &= \hom(\Gamma, SU(2))/SU(2) \\ \{(\rho^+, \rho^-) \in X(\Gamma) \times X(\Gamma) \mid tr(\rho^+(\mu)) = tr(\rho^-(\mu)), \ \mu \ \text{meridian} \} \end{split}$$

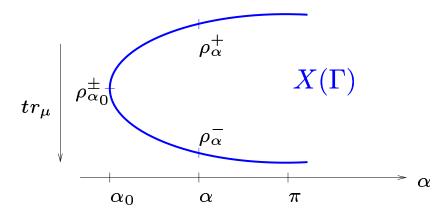


 $\bullet \ X(\Gamma) = \hom(\Gamma, SU(2))/SU(2)$ $\{ (\rho^+, \rho^-) \in X(\Gamma) \times X(\Gamma) \mid tr(\rho^+(\mu)) = tr(\rho^-(\mu)), \ \mu \text{ meridian} \}$



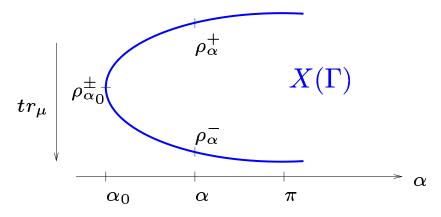
- $X(\Gamma)$ well understood for $\alpha \leq \pi$.
- $C(\alpha_0)$ Euclidean $\Rightarrow \rho_{\alpha_0}^+ = \rho_{\alpha_0}^-$. $(\rho_{\alpha_0}^+, \rho_{\alpha_0}^-)$ diagonal, in Spin(3). $(\rho_{\alpha_0}^+, \rho_{\alpha_0}^-)$ comes from $Isom(\mathbf{R}^3) \to SO(3)$

 $\begin{array}{l} \bullet \; X(\Gamma) = \hom(\Gamma, SU(2))/SU(2) \\ \{(\rho^+, \rho^-) \in X(\Gamma) \times X(\Gamma) \mid tr(\rho^+(\mu)) = tr(\rho^-(\mu)), \; \mu \; \text{meridian} \} \end{array}$



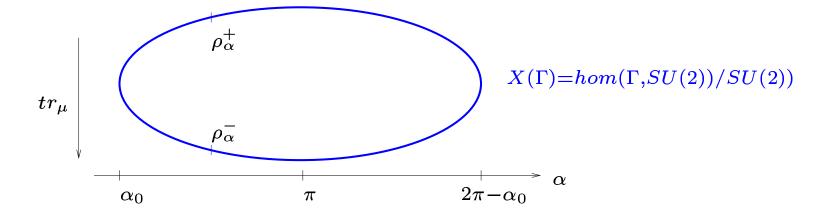
- $C(\alpha_0)$ Euclidean $\Rightarrow \rho_{\alpha_0}^+ = \rho_{\alpha_0}^-$. $(\rho_{\alpha_0}^+, \rho_{\alpha_0}^-)$ diagonal, in Spin(3). $(\rho_{\alpha_0}^+, \rho_{\alpha_0}^-)$ comes from $Isom(\mathbf{R}^3) \to SO(3)$
- How to find reps. in $(\pi, 2\pi \alpha_0)$?

 $\bullet \ X(\Gamma) = \hom(\Gamma, SU(2))/SU(2)$ $\{ (\rho^+, \rho^-) \in X(\Gamma) \times X(\Gamma) \mid tr(\rho^+(\mu)) = tr(\rho^-(\mu)), \ \mu \text{ meridian} \}$

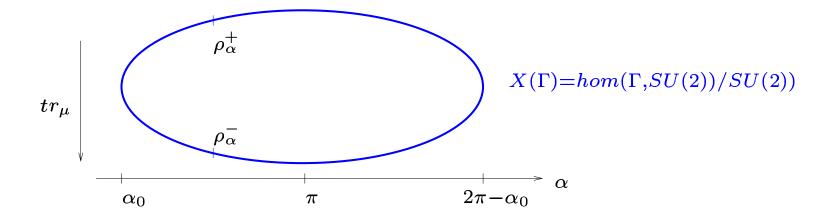


- How to find reps. in $(\pi, 2\pi \alpha_0)$?
 - reach $\alpha = \pi + \varepsilon$ for some $\varepsilon > 0$ (local paramet./rigidity)
 - $(\rho_{\pi+\varepsilon}^+, \rho_{\pi+\varepsilon}^-)$ and $(\rho_{\pi-\varepsilon}^+, \rho_{\pi-\varepsilon}^-)$ project to the same rep. in SO(4).
 - ⇒ Can complete the ellipse symmetrically.

Using the structure of $X(\Gamma)$ when $\alpha \leq \pi$ and the symmetry:



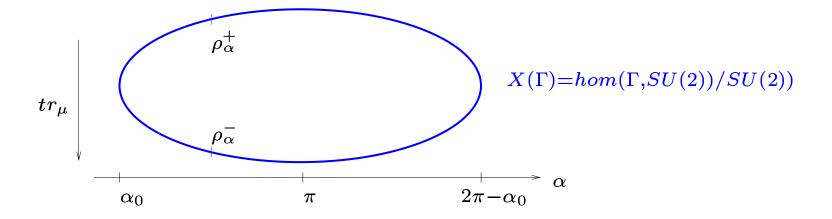
Using the structure of $X(\Gamma)$ when $\alpha \leq \pi$ and the symmetry:



 $\bullet(\rho_{\alpha}^+,\rho_{\alpha}^-) = \pm(\rho_{2\pi-\alpha}^+,\rho_{2\pi-\alpha}^-)$ i.e. $(\rho_{\alpha}^+,\rho_{\alpha}^-)$ and $(\rho_{2\pi-\alpha}^+,\rho_{2\pi-\alpha}^-)$ induce the same rep. in SO(4).

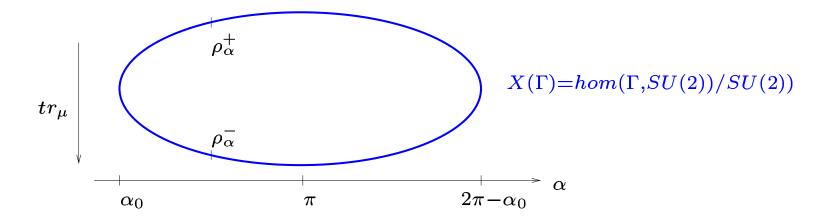
Notice that $\underline{tr(\rho_{\alpha}^{\pm}(\mu))} = \pm 2\cos(\alpha/2)$ local parameter at $\alpha = \pi$. thus the angle $\alpha > \pi$ makes sense.

Using the structure of $X(\Gamma)$ when $\alpha \leq \pi$ and the symmetry:



Next step: why those reps. correspond to spherical structures?

Using the structure of $X(\Gamma)$ when $\alpha \leq \pi$ and the symmetry:



Next step: why those reps. correspond to spherical structures?

- $C(\alpha_0)$ Euclidean: $\rho_{\alpha_0}^+ = \rho_{\alpha_0}^-$ (in Spin(3))
- $\rho_{2\pi-\alpha_0}^+ = \rho_{2\pi-\alpha_0}^-$ (also in Spin(3)). Also want to show:

$$\lim_{\alpha \to 2\pi - \alpha_0} C(\alpha) = \mbox{ spherical suspension of } S^2 \mbox{ with } 4 \mbox{ cone points}$$

Realizing reps. as holonomy of cone manifolds

$$A = \left\{ \alpha \in [\pi, 2\pi - \alpha_0) \middle| \begin{array}{l} (\rho_\alpha^+, \rho_\alpha^-) \in X(\Gamma) \times X(\Gamma) \text{ holonmy of a sph.} \\ \text{metric on } S^3 - L \text{ that completes to } C(\alpha) \end{array} \right\}$$

• A is open (deformations of holonomy \Rightarrow defs. of structure)

Realizing reps. as holonomy of cone manifolds

$$A = \left\{ \alpha \in [\pi, 2\pi - \alpha_0) \middle| \begin{array}{l} (\rho_\alpha^+, \rho_\alpha^-) \in X(\Gamma) \times X(\Gamma) \text{ holonmy of a sph.} \\ \text{metric on } S^3 - L \text{ that completes to } C(\alpha) \end{array} \right\}$$

- A is open (deformations of holonomy \Rightarrow defs. of structure)
- To show A is closed take $\alpha_n \in A$, $\alpha_n \nearrow \alpha_\infty$ and look at $\lim C(\alpha_n) = ?$

Need to bound:

- 1. bound above the diameter of $C(\alpha_n)$
- 2. radius of an embedded metric tube of $\Sigma \subset C(\alpha_n)$ ($\geq r > 0$)
- 3. injectivity radius on $C(\alpha_n) N_r(\Sigma) \ (\geq \varepsilon > 0)$

With those bounds, $\Longrightarrow \lim C(\alpha_n) = C(\alpha_\infty)$ and $\alpha_\infty \in A$.

Finding bounds

 $\alpha_n \in A$, $\alpha_n \nearrow \alpha_\infty$ and look at $\lim C(\alpha_n) = ?$

Finding bounds

 $\alpha_n \in A$, $\alpha_n \nearrow \alpha_\infty$ and look at $\lim C(\alpha_n) = ?$

• $\operatorname{diam}(C(\alpha_n)) \leq \pi$ bc. it is an Alexandrov space with curv. ≥ 1 .

Finding bounds

$$\alpha_n \in A$$
, $\alpha_n \nearrow \alpha_\infty$ and look at $\lim C(\alpha_n) = ?$

- $\operatorname{diam}(C(\alpha_n)) \leq \pi$ bc. it is an Alexandrov space with curv. ≥ 1 .
- $r(\alpha) = \sup\{\delta > 0 \mid N_{\delta}(\Sigma) \subset C(\alpha) \text{ embedded metric tube}\}$

Need to bound $r(\alpha) > 0$ uniformly for $\pi \le \alpha \le c < 2\pi - \alpha_0$ (i.e. the singular locus does not cross with itself before $2\pi - \alpha_0$).

- $\operatorname{vol}(C(\alpha)) \le 2\pi r(\alpha) + 2\pi(\alpha \pi)$
- $\operatorname{vol}(C(\alpha)) = \operatorname{vol}(C(2\pi \alpha)) + 2\pi(\alpha \pi)$

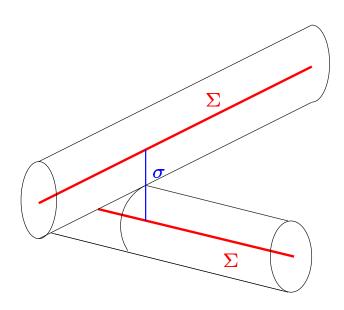
Hence
$$r(\alpha) \geq \frac{1}{2\pi} \operatorname{vol}(C(2\pi - \alpha))$$

Dirichlet domain

ullet Proof of $\operatorname{vol}(C(lpha)) \leq 2\pi r(lpha) + 2\pi (lpha - \pi)$

$$r = r(\alpha) = \sup\{\delta > 0 \mid N_{\delta}(\Sigma) \subset C(\alpha) \text{ embedded metric tube}\}$$

 σ segment of length 2r perpendicular to Σ .



Dirichlet domain

• Proof of
$$\operatorname{vol}(C(\alpha)) \leq 2\pi r(\alpha) + 2\pi(\alpha - \pi)$$

 σ segment of length 2r perpendicular to Σ .

$$D(\sigma) = \{x \in C(\alpha) \mid x \text{ has a unique minimizing segment to } \sigma \}$$

• $D(\sigma)$ not convex but star-shaped!

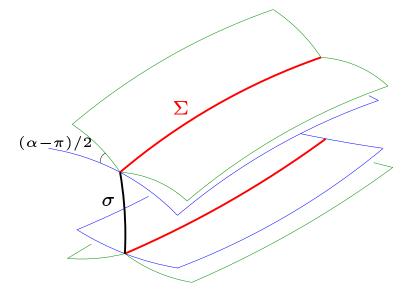
Dirichlet domain

$$ullet$$
 Proof of $\operatorname{vol}(C(lpha)) \leq 2\pi r(lpha) + 2\pi (lpha - \pi)$

 σ segment of length 2r perpendicular to Σ .

$$D(\sigma) = \{x \in C(\alpha) \mid x \text{ has a unique minimizing segment to } \sigma \}$$

• $D(\sigma)\subset {\sf a}$ lens of width 2r and 4 lenses of width $\frac{\alpha-\pi}{2}$ in S^3 .



 $vol(lens) = \pi \cdot width(lens)$

• Proof of
$$\operatorname{vol}(C(\alpha)) = \operatorname{vol}(C(2\pi - \alpha)) + 2\pi(\alpha - \pi)$$
 $\forall \alpha \in [\pi, 2\pi - \alpha_0)$

$$l(\alpha) = \text{total length of } \Sigma \subset C(\alpha)$$

• Schläfli's formula: $d \operatorname{vol} C(\alpha) = \frac{1}{2} l(\alpha) d \alpha$

$$\operatorname{vol} C(\alpha) = \int_{\alpha_0}^{\alpha} \frac{1}{2} l(\theta) d\theta$$

Thus $\operatorname{vol} C(\alpha)$ increases whith α .

• Proof of
$$\operatorname{vol}(C(\alpha)) = \operatorname{vol}(C(2\pi - \alpha)) + 2\pi(\alpha - \pi)$$
 $\forall \alpha \in [\pi, 2\pi - \alpha_0)$

$$l(\alpha) = \text{total length of } \Sigma \subset C(\alpha)$$

• Schläfli's formula: $d \operatorname{vol} C(\alpha) = \frac{1}{2} l(\alpha) d \alpha$

$$\operatorname{vol} C(\alpha) = \int_{\alpha_0}^{\alpha} \frac{1}{2} l(\theta) d\theta$$

• By symmetry: $l(\alpha) = 4\pi - l(2\pi - \alpha)$

• Proof of $\operatorname{vol}(C(\alpha)) = \operatorname{vol}(C(2\pi - \alpha)) + 2\pi(\alpha - \pi)$ $\forall \alpha \in [\pi, 2\pi - \alpha_0)$

$$l(\alpha) = \text{total length of } \Sigma \subset C(\alpha)$$

- Schläfli's formula: $\operatorname{vol} C(\alpha) = \int_{\alpha_0}^{\alpha} \frac{1}{2} l(\theta) d\theta$
- By symmetry: $l(\alpha) = 4\pi l(2\pi \alpha)$

$$\operatorname{vol}(C(\alpha)) = \int_{\alpha_0}^{\pi} \frac{1}{2} l(\theta) d\theta + \int_{\pi}^{\alpha} \frac{1}{2} l(\theta) d\theta$$

• Proof of $\operatorname{vol}(C(\alpha)) = \operatorname{vol}(C(2\pi - \alpha)) + 2\pi(\alpha - \pi)$ $\forall \alpha \in [\pi, 2\pi - \alpha_0)$

$$l(\alpha) = \text{total length of } \Sigma \subset C(\alpha)$$

- Schläfli's formula: $\operatorname{vol} C(\alpha) = \int_{\alpha_0}^{\alpha} \frac{1}{2} l(\theta) d\theta$
- By symmetry: $l(\alpha) = 4\pi l(2\pi \alpha)$

$$\operatorname{vol}(C(\alpha)) = \int_{\alpha_0}^{\pi} \frac{1}{2} l(\theta) d\theta + \int_{\pi}^{\alpha} \frac{1}{2} l(\theta) d\theta$$
$$= \int_{\alpha_0}^{\pi} \frac{1}{2} l(\theta) d\theta + \int_{\pi}^{\alpha} 4\pi \frac{1}{2} d\theta + \int_{\pi}^{2\pi - \alpha} \frac{1}{2} l(\theta) d\theta$$

• Proof of $\operatorname{vol}(C(\alpha)) = \operatorname{vol}(C(2\pi - \alpha)) + 2\pi(\alpha - \pi)$ $\forall \alpha \in [\pi, 2\pi - \alpha_0)$

$$l(\alpha) = \text{total length of } \Sigma \subset C(\alpha)$$

- Schläfli's formula: $\operatorname{vol} C(\alpha) = \int_{\alpha_0}^{\alpha} \frac{1}{2} l(\theta) d\theta$
- By symmetry: $l(\alpha) = 4\pi l(2\pi \alpha)$

$$\operatorname{vol}(C(\alpha)) = \int_{\alpha_0}^{\pi} \frac{1}{2} l(\theta) d\theta + \int_{\pi}^{\alpha} \frac{1}{2} l(\theta) d\theta$$

$$= \int_{\alpha_0}^{\pi} \frac{1}{2} l(\theta) d\theta + \int_{\pi}^{\alpha} 4\pi \frac{1}{2} d\theta + \int_{\pi}^{2\pi - \alpha} \frac{1}{2} l(\theta) d\theta$$

$$= \int_{\alpha_0}^{2\pi - \alpha} \frac{1}{2} l(\theta) d\theta + (\alpha - \pi) 2\pi$$

More bounds (final)

$$\left. \begin{array}{l} \operatorname{vol}(C(\alpha)) \leq 2\pi r(\alpha) + 2\pi(\alpha - \pi) \\ \operatorname{vol}(C(\alpha)) = \operatorname{vol}(C(2\pi - \alpha)) + 2\pi(\alpha - \pi) \end{array} \right\} \Rightarrow r(\alpha) \geq \frac{\operatorname{vol}(C(2\pi - \alpha))}{2\pi} \ .$$

Remarks

- $\operatorname{vol}(C(\alpha_0)) = 0$. Thus $r(2\pi \alpha_0) \ge 0$ trivial bound.
- $2\pi(\alpha \pi) = \text{vol}(\text{spherical suspension of } S^2(\alpha, \alpha, \alpha, \alpha))$ In particular $\text{vol}(C(2\pi - \alpha_0)) = \text{vol. spherical suspension}$

More bounds (final)

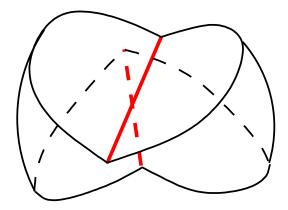
$$\left. \begin{array}{l} \operatorname{vol}(C(\alpha)) \leq 2\pi r(\alpha) + 2\pi(\alpha - \pi) \\ \operatorname{vol}(C(\alpha)) = \operatorname{vol}(C(2\pi - \alpha)) + 2\pi(\alpha - \pi) \end{array} \right\} \Rightarrow r(\alpha) \geq \frac{\operatorname{vol}(C(2\pi - \alpha))}{2\pi} \ .$$

Remarks

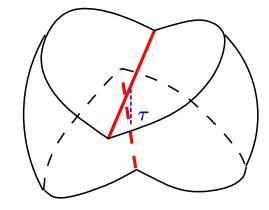
- $\operatorname{vol}(C(\alpha_0)) = 0$. Thus $r(2\pi \alpha_0) \geq 0$ trivial bound.
- $2\pi(\alpha \pi) = \text{vol}(\text{spherical suspension of } S^2(\alpha, \alpha, \alpha, \alpha))$ In particular $\operatorname{vol}(C(2\pi - \alpha_0))$ =vol. spherical suspension
- The injectivity radius in $C(\alpha) N_r(\Sigma)$ is bounded because:
 - $\begin{cases} \bullet \ \operatorname{vol} C(\alpha) \ \operatorname{increases} \ \operatorname{whith} \ \alpha \ (\operatorname{Schl\"{a}fli's}). \\ \bullet \ \operatorname{diam}(C(\alpha)) \leq \pi \ (\operatorname{Alexandrov} \ \operatorname{space}). \end{cases}$

• The length of tunnels $|\tau_i| \to 0$ as $\alpha \to 2\pi - \alpha_0$, by symmetry of the variety of reps.

- The length of tunnels $|\tau_i| \to 0$ as $\alpha \to 2\pi \alpha_0$, by symmetry of the variety of reps.
- We construct the metric on $C(2\pi \alpha_0)$ from the <u>tangles</u> and we deform them decreasing α explicitely.

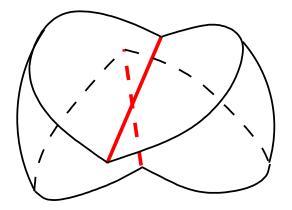


$$\alpha = 2\pi - \alpha_0$$

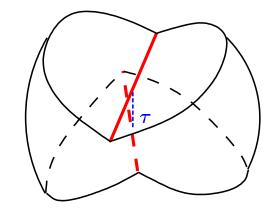


$$\alpha < 2\pi - \alpha_0$$

• We construct the metric on $C(2\pi - \alpha_0)$ from the <u>tangles</u> and we deform them decreasing α explicitely.



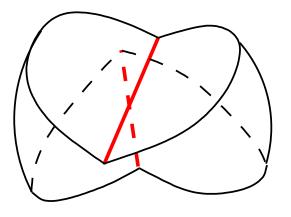
$$\alpha = 2\pi - \alpha_0$$



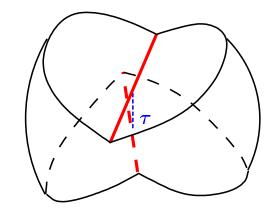
$$\alpha < 2\pi - \alpha_0$$

• At $2\pi - \alpha_0$ angle of crossing is $\neq 0$ (bc. $(\rho_{\alpha_0}^+, \rho_{\alpha_0}^-)$ non abelian)

• We construct the metric on $C(2\pi - \alpha_0)$ from the <u>tangles</u> and we deform them decreasing α explicitely.



$$\alpha = 2\pi - \alpha_0$$



$$\alpha < 2\pi - \alpha_0$$

- At $2\pi \alpha_0$ angle of crossing is $\neq 0$ (bc. $(\rho_{\alpha_0}^+, \rho_{\alpha_0}^-)$ non abelian)
- Why this deformation is the same as the previous one? By the same volume calculations, can decrease α to π and apply de Rham's global rigidity for orbifolds

Torus links

Cone structures described by the basis of the Seifert fibration.

Torus links

Cone structures described by the basis of the Seifert fibration.

$$\begin{array}{ll} L=t(2,n),\, n \text{ odd} \\ \text{(i.e. L a knot).} \end{array} \Rightarrow C(\alpha) \left\{ \begin{array}{ll} PSL_2(\mathbf{R}) & \text{for } \alpha \in (0,\pi-\frac{2\pi}{n}) \\ Nil & \text{for } \alpha=\frac{2\pi}{n} \\ \text{spherical} & \text{for } \alpha \in (\pi-\frac{2\pi}{n},\pi+\frac{2\pi}{n}) \end{array} \right.$$

Torus links

Cone structures described by the basis of the Seifert fibration.

$$\begin{array}{ll} L=t(2,n),\, n \text{ odd} \\ \text{(i.e. L a knot).} \end{array} \Rightarrow C(\alpha) \left\{ \begin{array}{ll} PSL_2(\mathbf{R}) & \text{for } \alpha \in (0,\pi-\frac{2\pi}{n}) \\ Nil & \text{for } \alpha=\frac{2\pi}{n} \\ \text{spherical} & \text{for } \alpha \in (\pi-\frac{2\pi}{n},\pi+\frac{2\pi}{n}) \end{array} \right.$$

When
$$\alpha \to \pi + \frac{2\pi}{n} \Rightarrow \begin{cases} \Sigma \text{ intersectes itself tangentially} \\ \text{and get a round circle with cone angle } \frac{4\pi}{n} \end{cases}$$

• When
$$n=3$$

Addendum

During my talk I forgot to mention that A. Mednykh and A. Rasskazov had obtained the same result for the fi gure eigth knot. Mednykh was attending the talk and complained about my omission.

The referee of my paper let me know about that (so I should have mentioned it), but I was not aware that this paper was available on the web. Google found the preprint in http://cis.paisley.ac.uk/research/reports/tr22.zip

The paper of my talk can be found in http://mat.uab.es/~porti/twobridge040127.pdf and it just appeared in Kobe J. of Math. **21** (2004), 61-70