

Accelerators for Spallation Neutron Sources

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Course description



Level: Introductory; overview

Prerequisites: Physics 101

Duration: 1h 30 min

Topics:

- General concept of accelerator for Spallation Neutron Source
- Fundamentals of accelerators; vocabulary; concepts
- Example: design of the SNS

Exercise session: Questions, discussion, demonstration of beam dynamics simulation codes

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Acknowledgments:

In preparation of this lecture I used materials generously provided by my colleagues from the SNS, in particular by N. Holtkamp, S. Henderson, R. Campisi, M. Plum, J. Stovall, and J. Wei.

Units



SI units will be used with one exception:

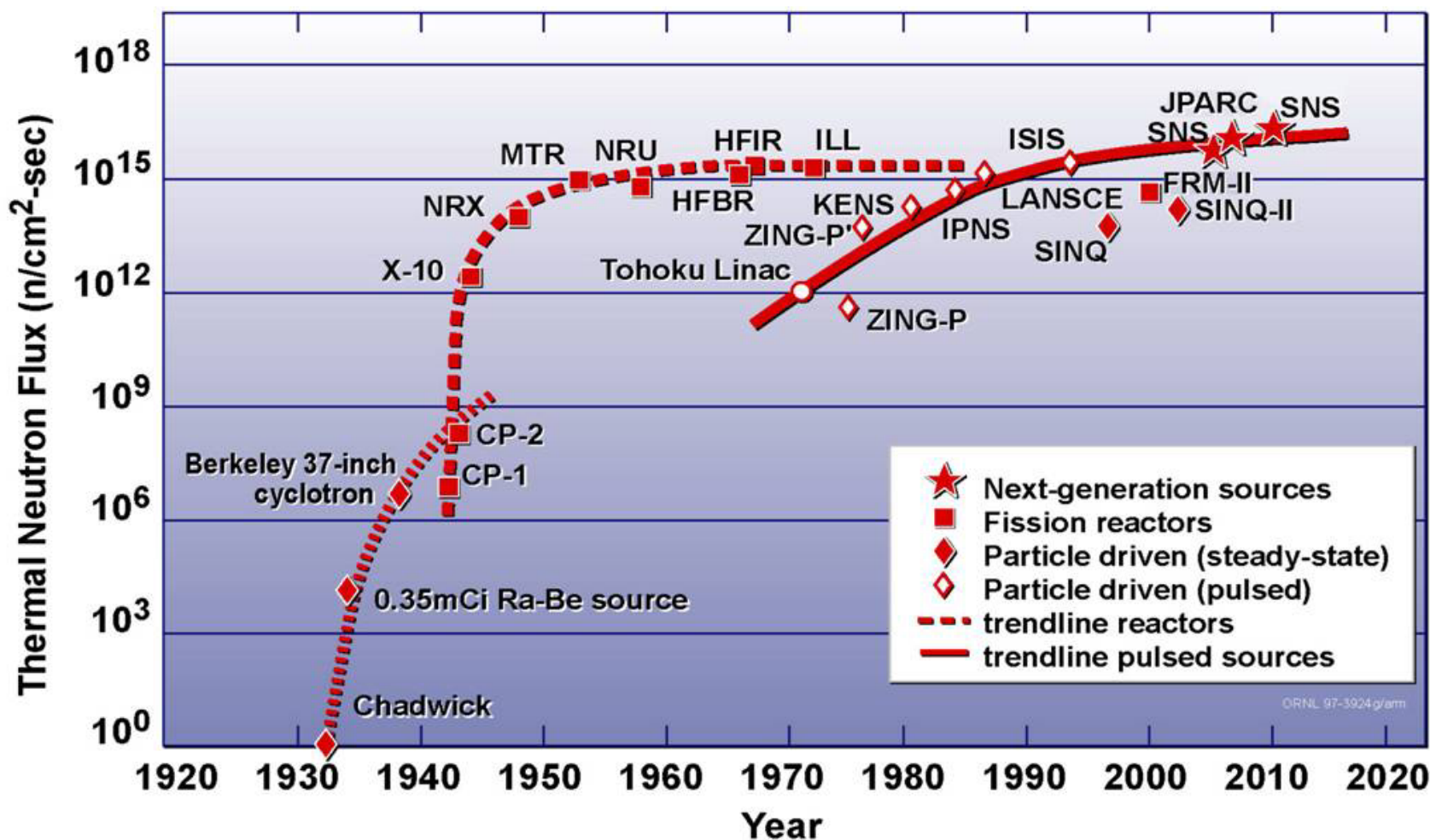
Beam kinetic energy is expressed in electron volt (eV), instead of Joules.

1eV=energy acquired by a particle with electronic charge 1.602×10^{-19} C accelerated through 1 Volt.

$$1\text{MeV} = 10^6 \text{ eV}$$

$$1\text{GeV} = 10^9 \text{ eV}$$

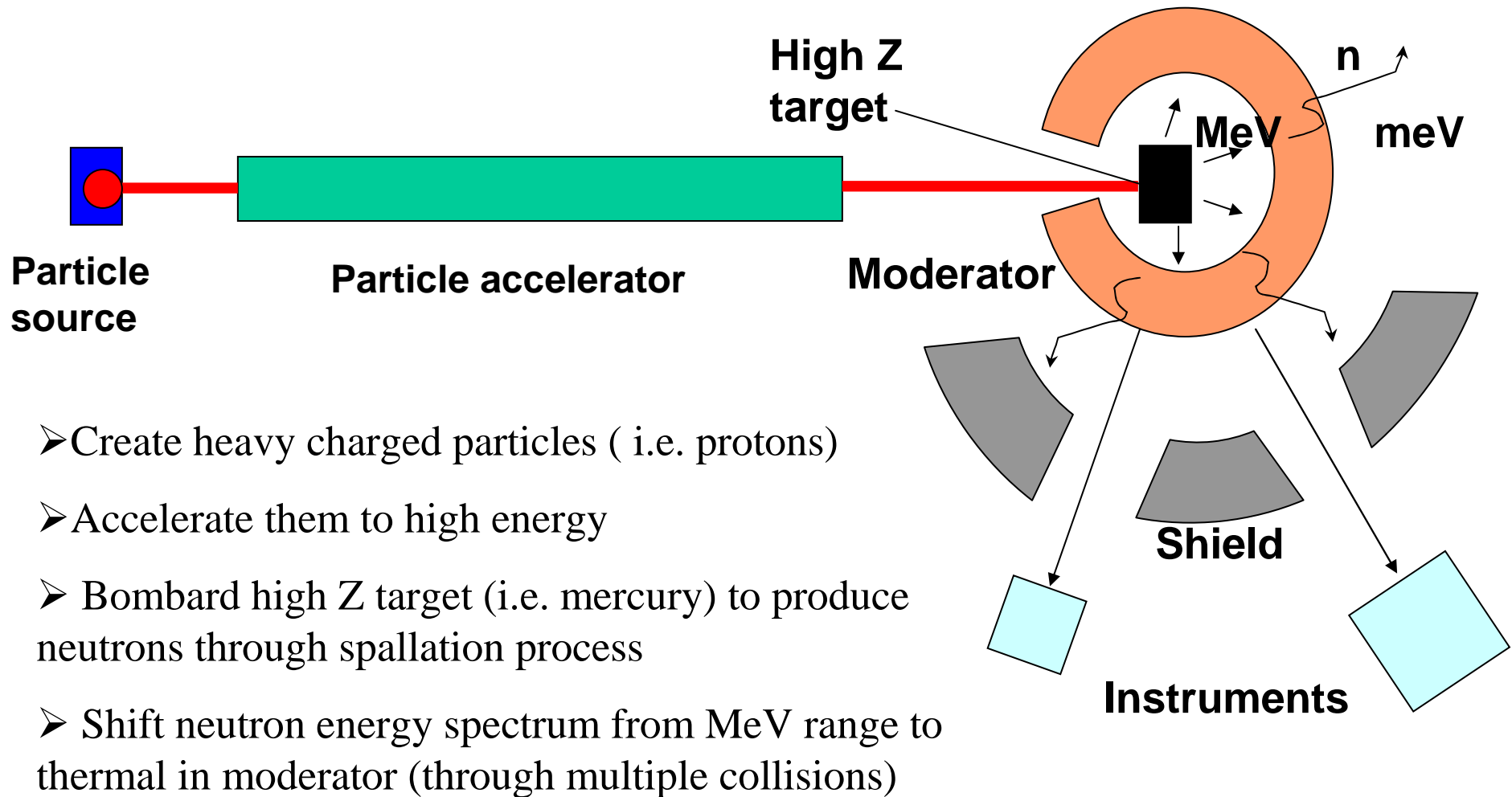
Development of neutron science facilities



(Updated from *Neutron Scattering*, K. Skold and D. L. Price: eds., Academic Press, 1986)

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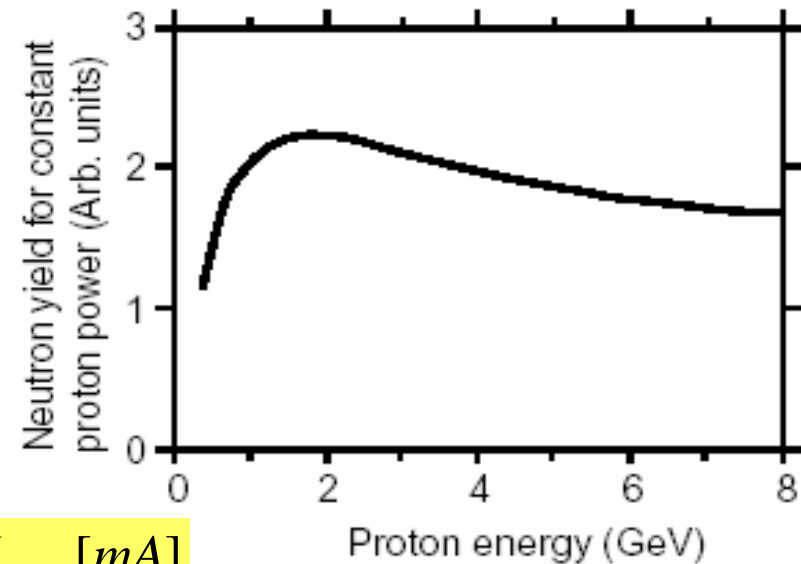
Simplest Spallation Neutron Source layout



Choosing design parameters : beam energy



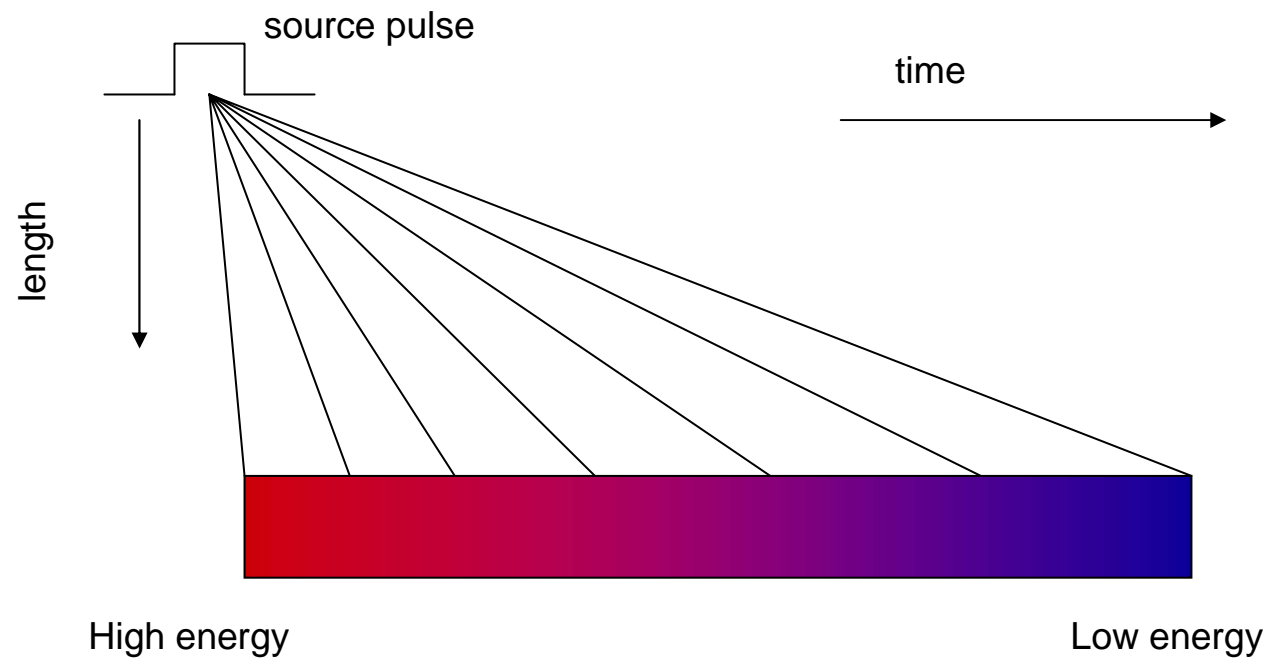
- Neutron yield per 1W of proton beam power is almost independent on beam energy above ~ 1GeV



$$N[\frac{n}{\text{sec}}] = k \cdot P_{\text{beam}} [MW] = k \cdot W_{\text{beam}} [GeV] \cdot I_{\text{beam}} [mA]$$

- Efficient use of beam power requires $W > 1\text{GeV}$
- Approximately same neutron yield will be produced by 1 GeV * 2 mA beam and 2 GeV * 1 mA beam
- Trade off between beam current and energy provides flexibility in choosing type of accelerator (will be discuss later)

Pulsed Neutron Source and Time-of-Flight separation

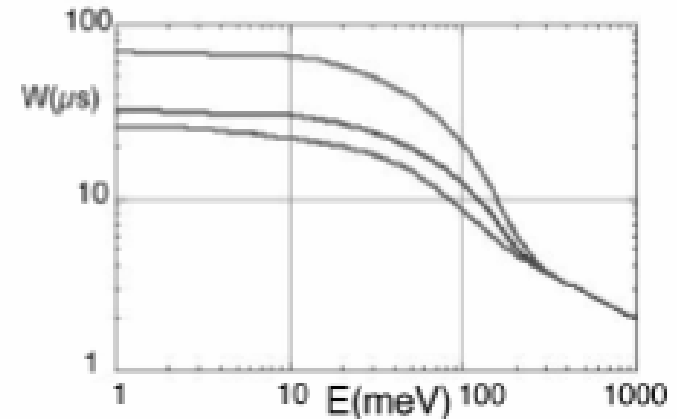


- Pulsed operation allows neutron energy separation by resolving time of arrival to the detector: faster neutrons arrive earlier slower neutrons arrive later

Choosing design parameters : beam pulse time structure



- Beam pulse length τ should be much shorter than neutron pulse widening in the moderator to preserve resolution of Time-of-Flight energy separation. Typically, $\tau < 1 \mu\text{s}$.
- Time between pulses T should be large enough to prevent “frame-overlap” from consecutive pulses. Typically, $T > 10 \text{ ms}$ (or repetition rate $< 100 \text{ Hz}$).



Time widths W (FWHM) of neutrons emerging from a room-temperature water moderator in different regimes.

- Accelerator stability improves if pulse rate is synchronized with AC power line: 60 Hz, 30 Hz, 20 Hz ... in USA (50 Hz, 25 Hz, 10 Hz ... in Europe).
- ! In pulsed systems distinguish peak values of parameters (e.g. current, power) vs. average values.

Choosing design parameters : example

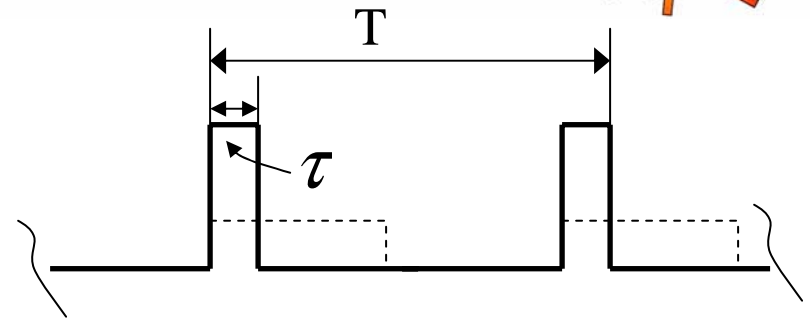


Average beam power: $P = 1.0 \text{ MW}$

Beam kinetic energy: $W = 1.0 \text{ GeV}$

Beam pulse length: $\tau = 1.0 \mu\text{s}$

Repetition rate: $R = 50 \text{ Hz}$



Average beam current: $I_{av} = \frac{P}{W} = \frac{1 \cdot 10^6 \text{ watt}}{1 \cdot 10^9 \text{ eV}} = 1 \cdot 10^{-3} \text{ A} = 1.0 \text{ mA}$

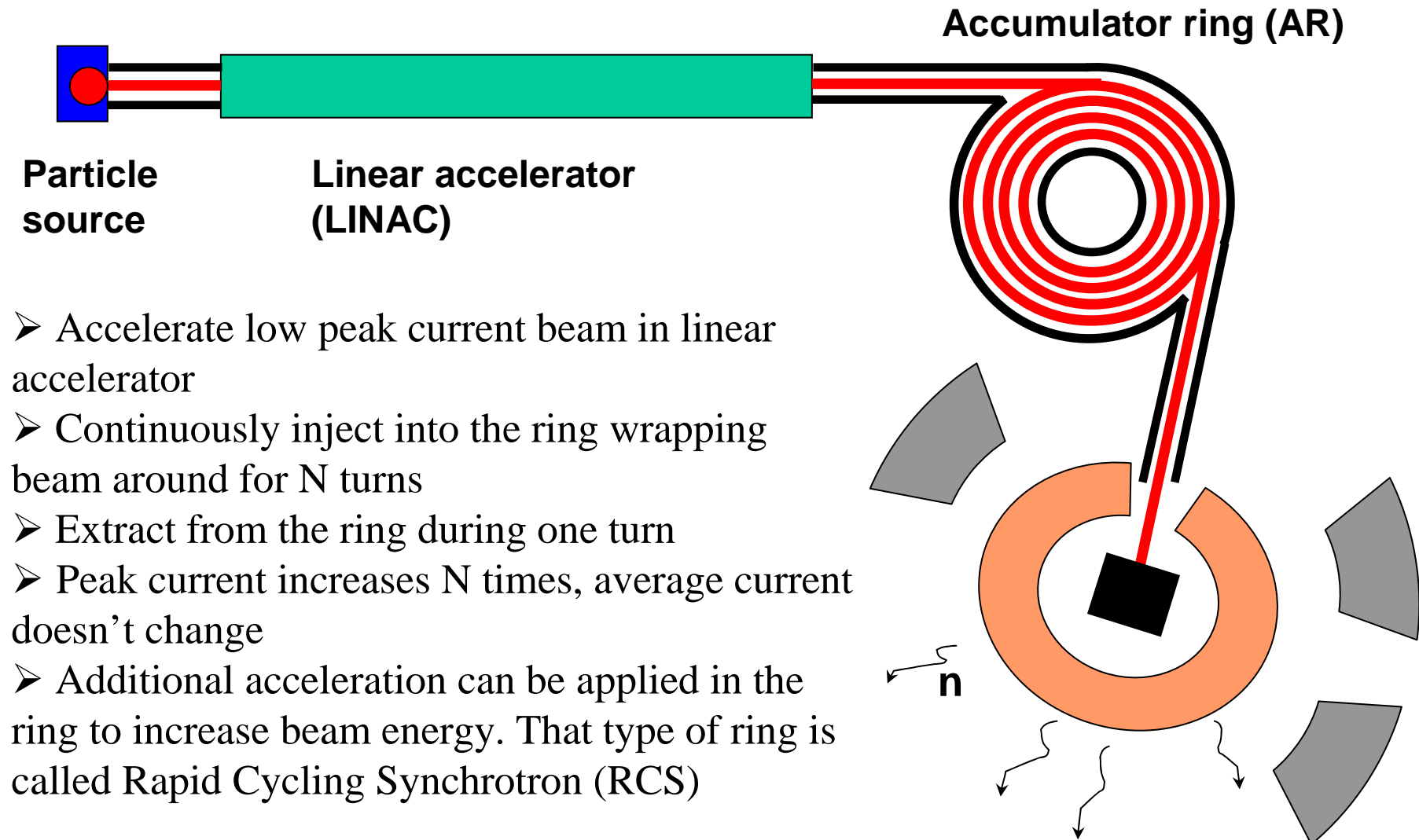
Peak beam current: $I_{pk} = \frac{I_{av} \cdot T}{\tau} = \frac{I_{av}}{\tau \cdot R} = \frac{10^{-3} \text{ A}}{10^{-6} \text{ s} \cdot 50 \text{ Hz}} = 20 \text{ A}$

Maximum peak beam current in modern proton linear accelerator is $\approx 0.1 \text{ A}$

How to resolve discrepancy?

- ~~1. Increase beam energy to 200 GeV. Impractical and cost prohibitive.~~
2. Accelerate 200 μs long beam pulse then compress it to 1 μs .

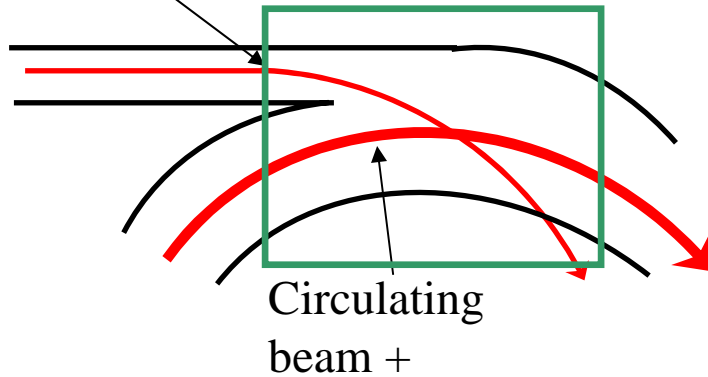
Layout of pulsed SNS with pulse compression



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Multi-turn injection into the ring

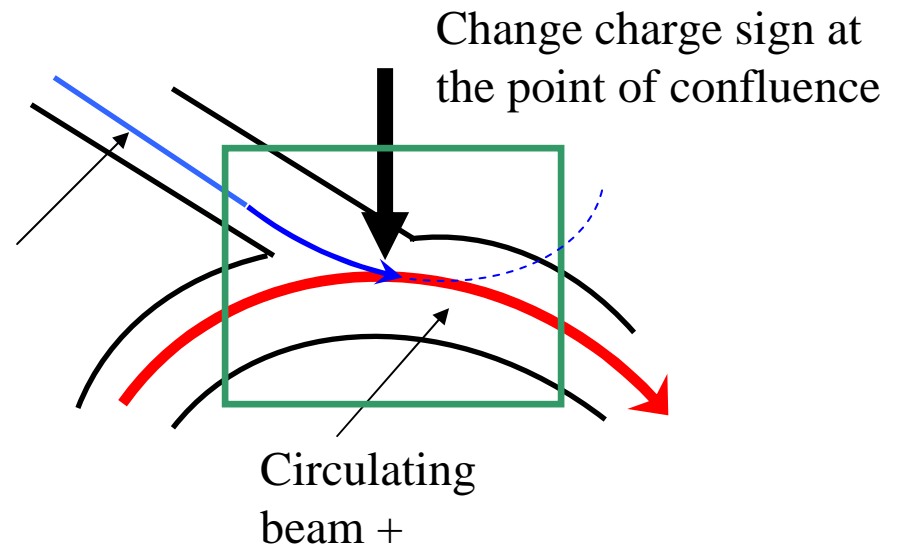
Injected
beam +



Injection without charge exchange
doesn't allow confluence of two
beams

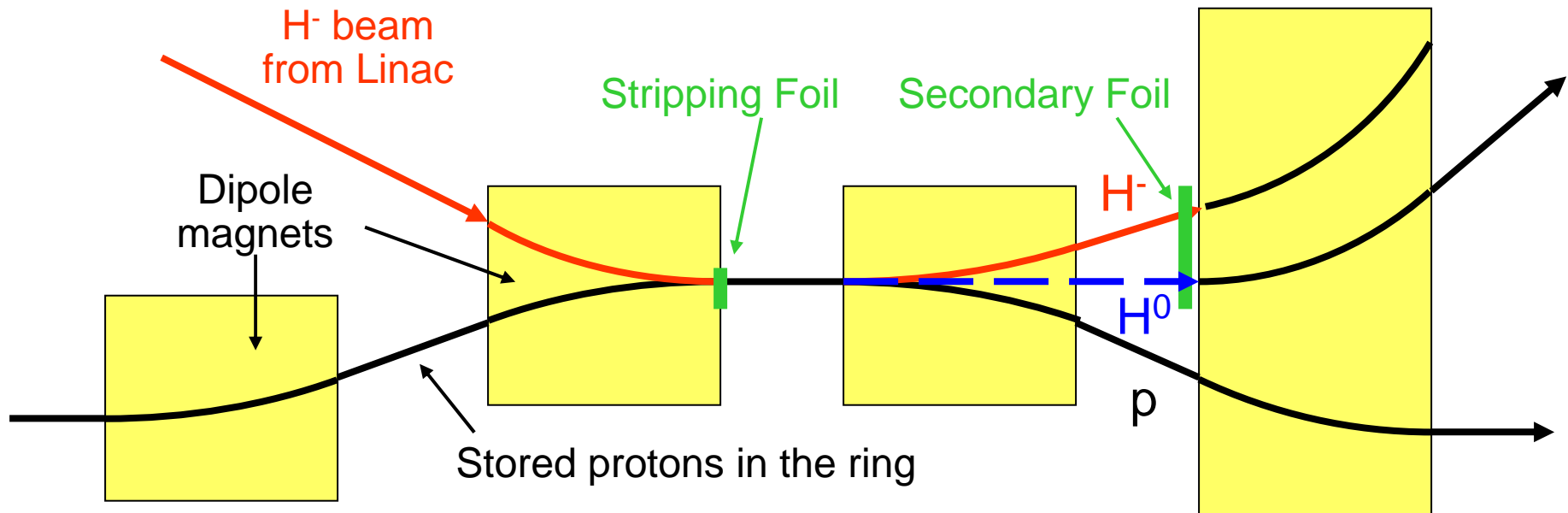
Injection in magnetic field with
charge exchange does allow
confluence of two beams

Injected
beam -



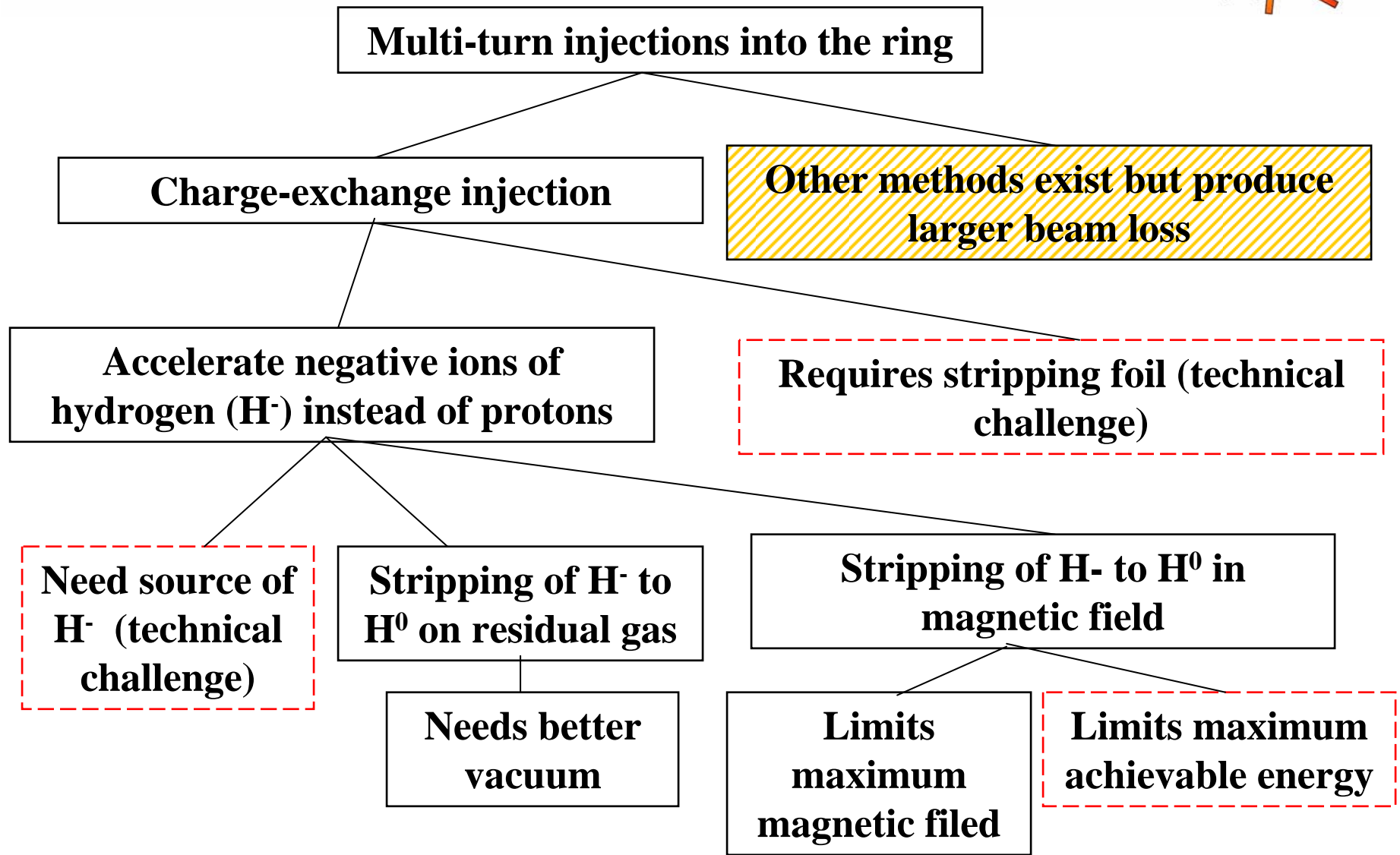
Multi-turn charge-exchange injection in practice

- Negative ions of hydrogen (bound state of proton + 2 electrons) are produced in the source and accelerated
- Two electrons are removed by the stripping foil, injected protons are merged with previously accumulated beam
- The Secondary foil strips the H^- and H^0 which survived the first foil



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Multi-turn charge-exchange injection implications

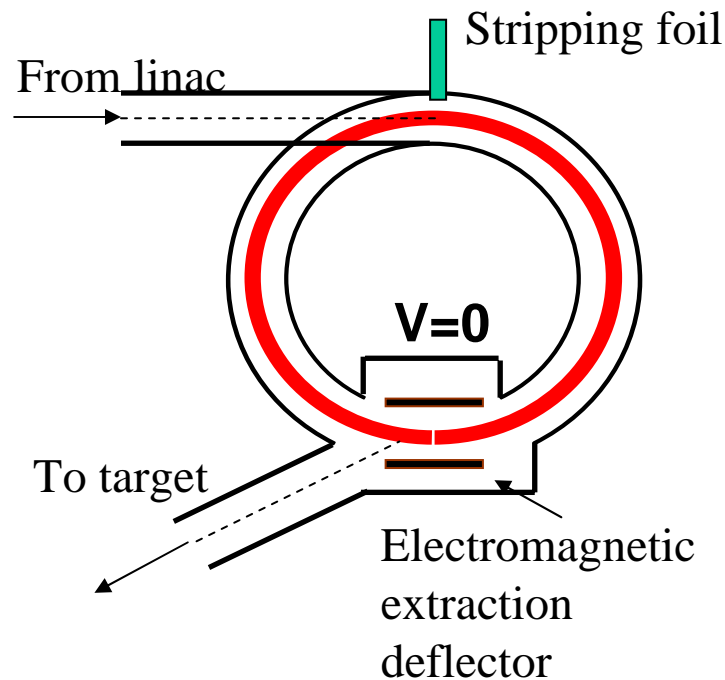


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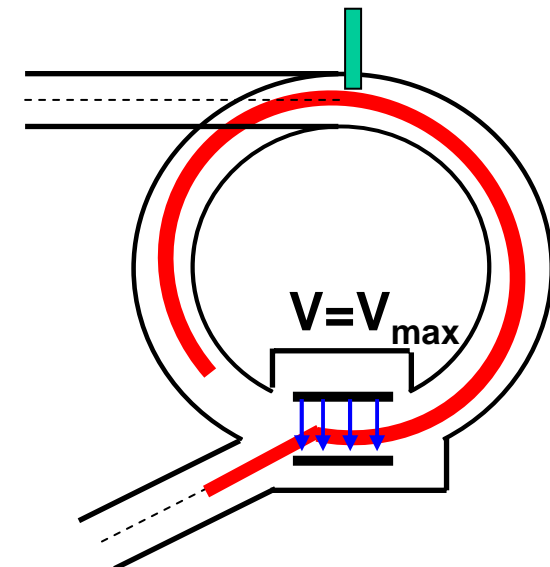
Single-turn extraction from the ring

- Install electro-magnetic deflector in the ring.
- Zero voltage on deflector. No deflection. Beam is circulating.
- Maximum voltage on deflector. Beam is deflected to extraction channel.

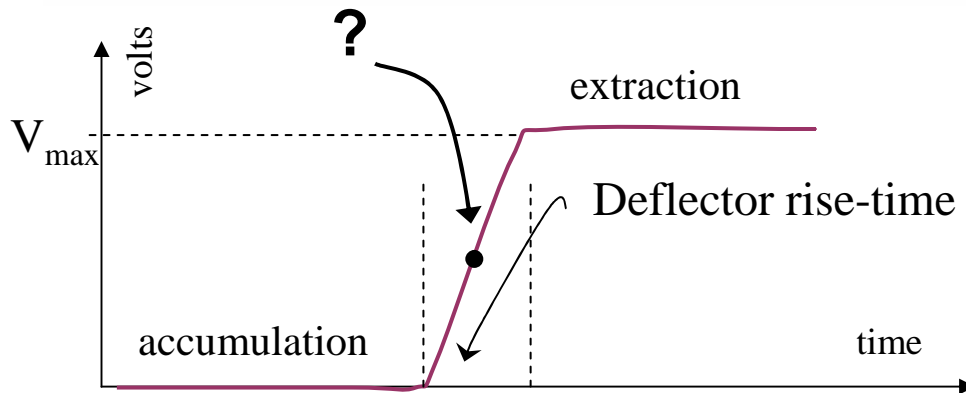
End of accumulation



Extraction



Extraction losses



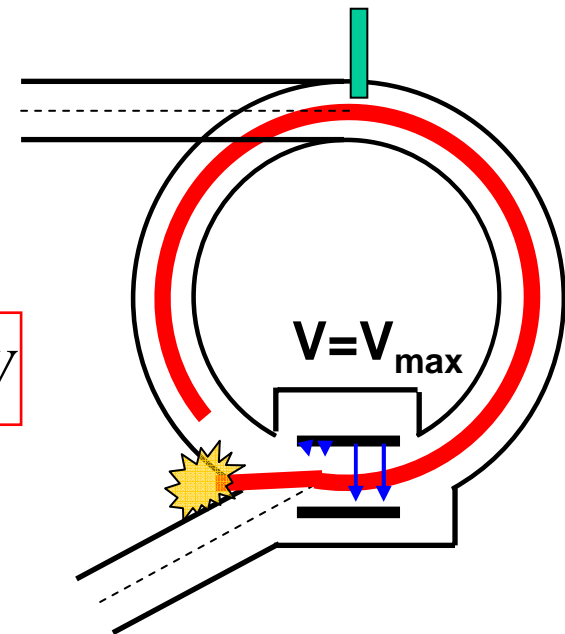
- Deflector can't switch on instantly
- Typical rise-time $\sim 200\text{ns}$
- What happens to partially deflected beam?

➤ Half-deflected beam misses extraction channel and hits the wall

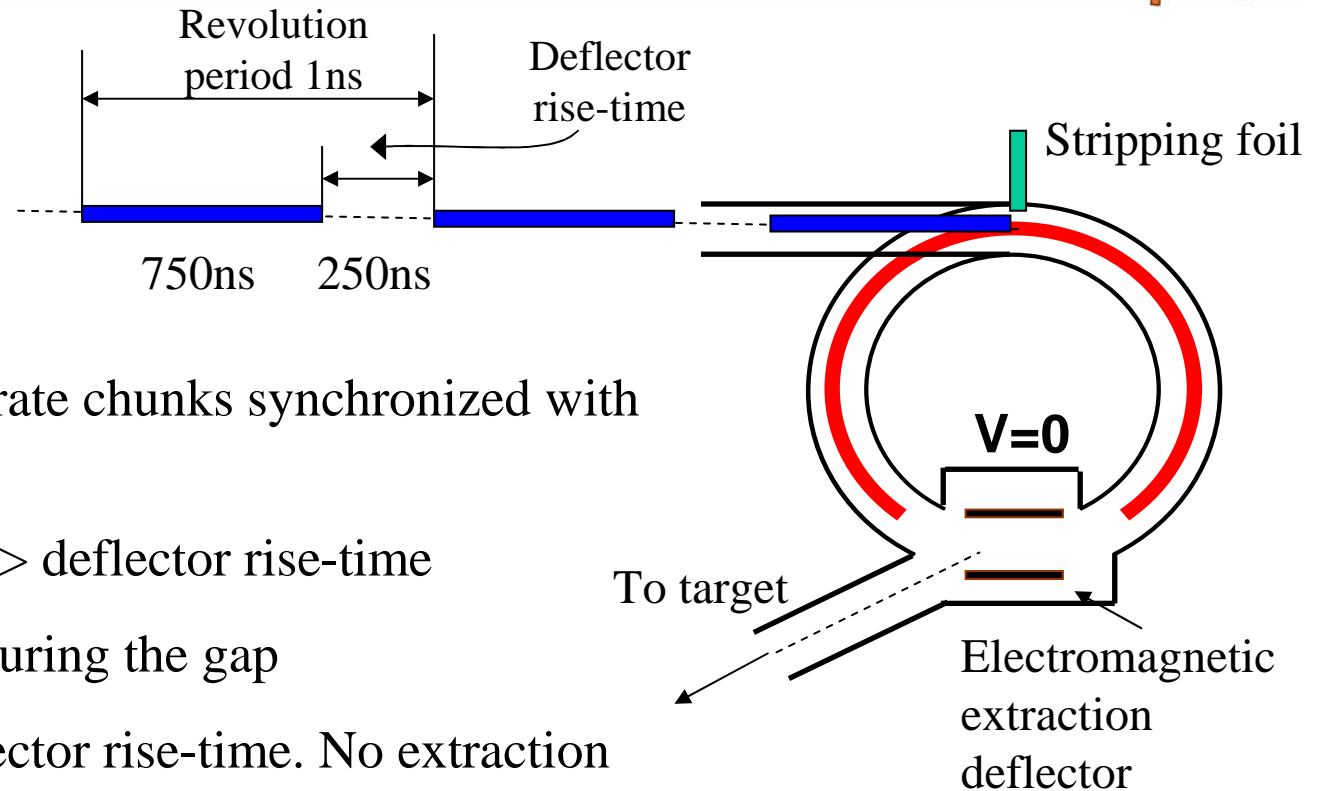
➤ Power of lost beam

$$\approx \frac{\text{deflector rise time}}{\text{revolution period}} \cdot P \approx \frac{0.2\mu\text{s}}{1\mu\text{s}} \cdot 1\text{MW} = 200\text{kW}$$

➤ Unacceptably high. *Higher than power on target for best existing machines!*

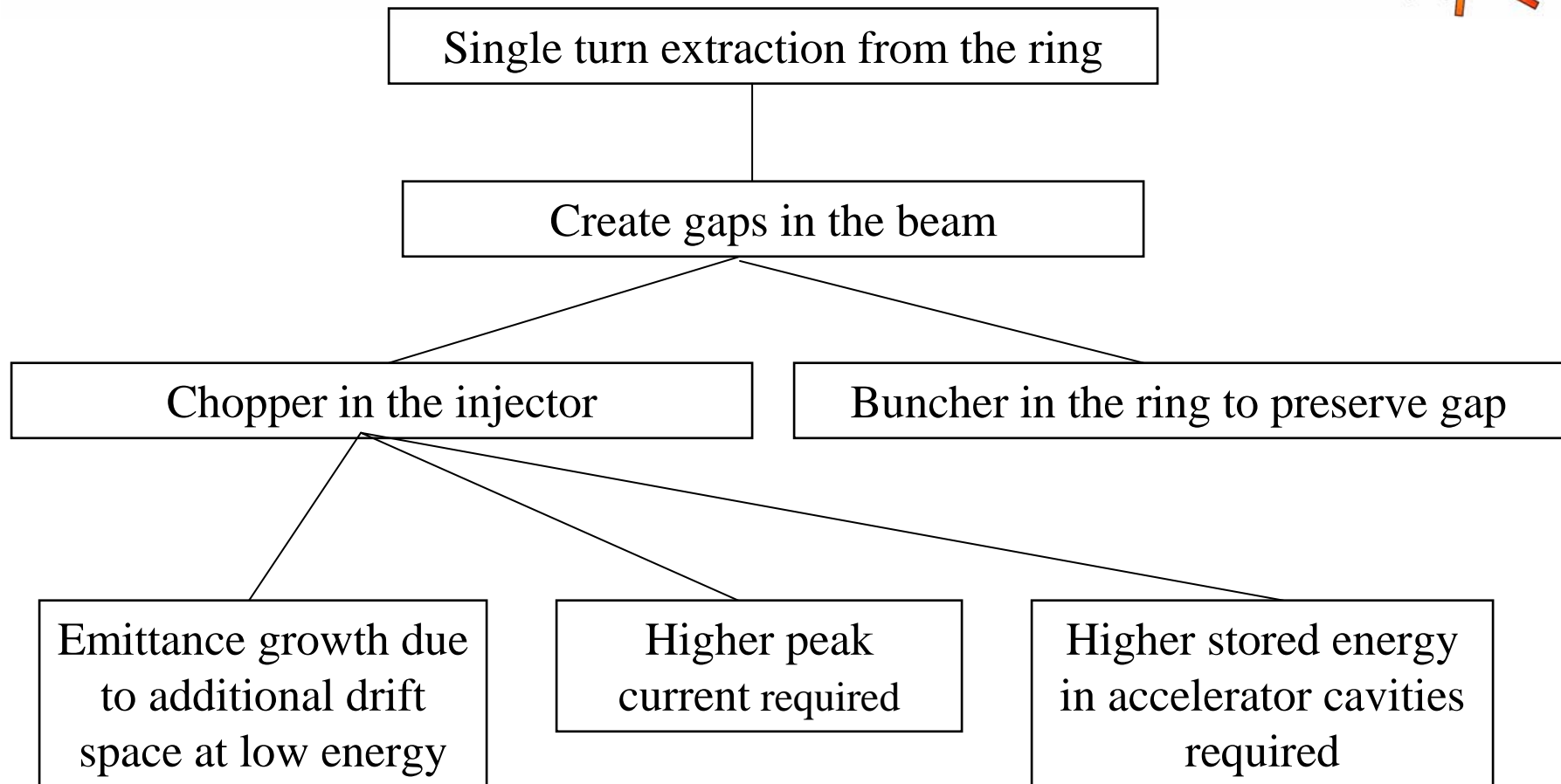


Extraction losses mitigation



- Divide beam on separate chunks synchronized with ring revolution period
- Gap between chunks $>$ deflector rise-time
- Switch on deflector during the gap
- No beam during deflector rise-time. No extraction losses.
- Have to add “chopper” creating gaps in the beam
- Chopper should be placed at as low energy as possible to minimize power of beam removed from the gaps

Single-turn extraction implications



Acceleration



➤ Lorentz force: $\vec{F} = e(\vec{E} + \vec{v} \times \vec{B})$

➤ Total particle energy: $T = mc^2 + W$

➤ Energy change by external force: $\frac{dT}{dt} = \vec{v} \cdot \vec{F} = e\vec{v} \cdot (\vec{E} + \vec{v} \times \vec{B}) = e\vec{v} \cdot \vec{E}$

Only electrical field collinear with particle velocity can change its energy

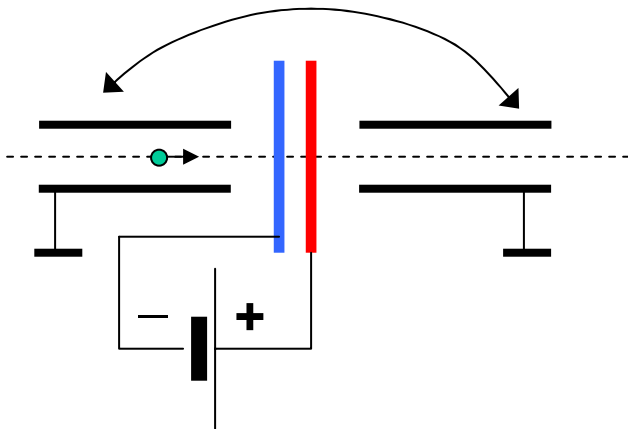
- For velocities $v \approx c$ a moderate magnetic field of 1 Tesla creates transverse force corresponding to a huge electric field of 3000 kV/cm.
- Use magnetic fields to deflect particles at high energy, $v \approx c$
- Use electric field to deflect particles at low energy, $v \ll c$

Radio Frequency Acceleration Principle

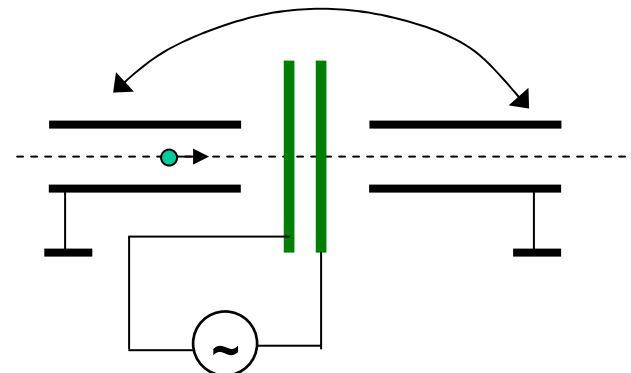


- Need electric field to accelerate particles
- From Maxwell equations: $\vec{E} = -\nabla \phi - \frac{\partial}{\partial t} \vec{A}$; $\vec{B} = \nabla \times \vec{A}$
- Electrostatic field is associated with difference of potentials
- To gain 1 GeV energy particle needs to traverse 1 Giga-Volt potential difference. Absolutely not feasible technically. Maximum energy of DC accelerator ~10 MeV: Van de Graaff, Cockcroft-Walton, Tandem...
- Have to use time-varying field

Same potential \Leftrightarrow no acceleration



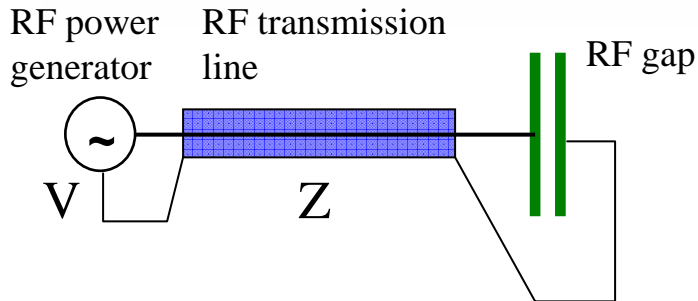
Same potential but can be an acceleration because time varying field is not conservative



Radio-Frequency (RF) acceleration principle

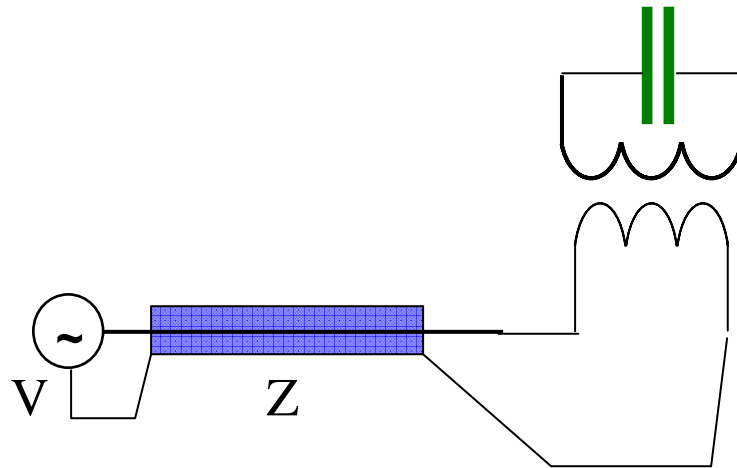
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Inducing voltage in the gap



➤ Rf power required to create 100kV voltage in the gap:

$$P = \frac{V^2}{2Z} = \frac{(10^5 \text{ volt})^2}{2 \cdot 50 \Omega} = 10^8 \text{ Watt}$$

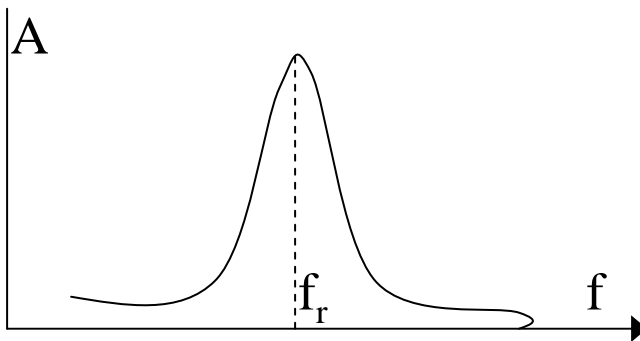


➤ Transformer allows higher voltage without power increase

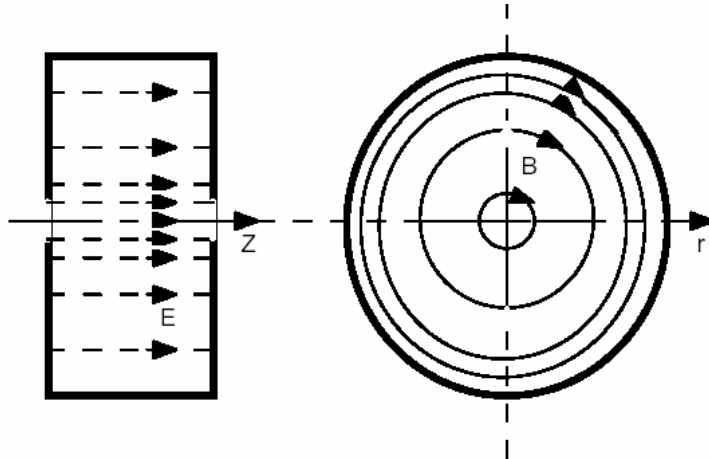
➤ Gap capacitance and transformer inductance form resonant LC circuit

➤ If driven at resonant frequency allows significantly ($10^2 - 10^4$) higher voltage without power increase

➤ At high frequencies ($10^7 - 10^{11}$ Hz) RF cavity is more efficient than ordinary LC circuit



RF cavity



Electric E and magnetic B fields for the lowest mode in a cylindrical (pillbox) cavity resonator.

➤ Solution of Maxwell equations for e/m fields inside a conducting boundary can be represented as an infinite sum of specific field configurations (field eigenvectors or **modes**) oscillating at specific frequencies (eigenvalues or resonant frequencies)

➤ If driven at resonant frequency only the corresponding mode is excited

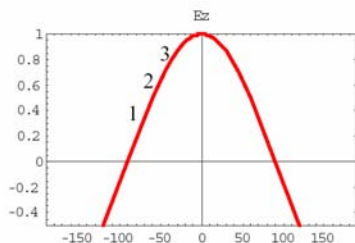
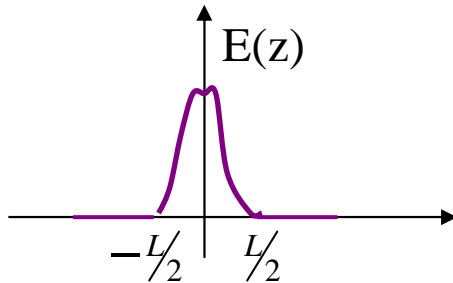
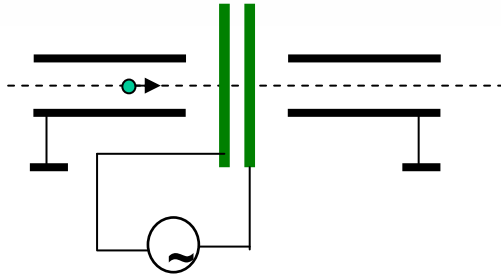
➤ Final conductivity of the cavity walls cause resistive energy losses $P_{loss} \sim E$

➤ Energy of the filed in the cavity is **stored energy** $U \sim E^2$

➤ **Quality factor** is figure of merit for cavity efficiency $Q = \frac{\omega U}{P_{loss}}$

➤ Balance of power $P_{generator} = P_{loss} + P_{beam}$

Energy gain in RF gap



1. Particle enters the gap
2. Particle in the middle
3. Particle exits the gap

$$E(z, t) = E_0(z) \cdot \cos(\omega t + \phi)$$

$$\Delta W = e \int_{-L/2}^{L/2} E(z, t) dz = e \int_{-L/2}^{L/2} E_0(z) \cdot \cos(\omega t + \phi) dz =$$

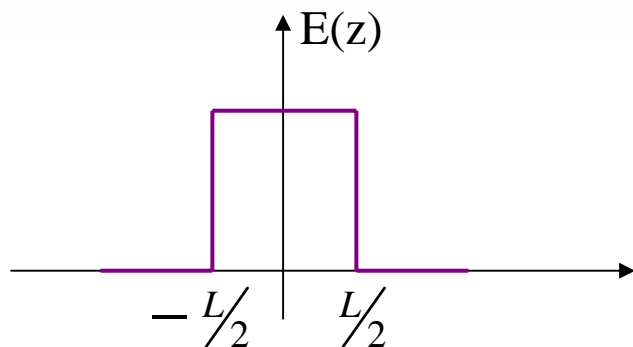
$$= e \int_{-L/2}^{L/2} E_0(z) \cdot [\cos \omega t \cdot \cos \phi - \sin \omega t \cdot \sin \phi] dz =$$

$$= e \cdot V_0 \cdot T \cdot \cos \phi,$$

$$\text{where } V_0 = \int_{-L/2}^{L/2} E_0(z) \cdot dz \quad , \text{ RF voltage.}$$

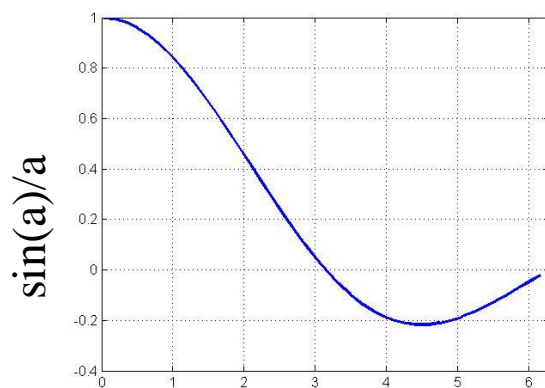
$$T = \frac{\int_{-L/2}^{L/2} E_0(z) \cdot \cos \omega t \cdot dz}{V_0} - \frac{\int_{-L/2}^{L/2} E_0(z) \cdot \sin \omega t \cdot dz}{V_0}$$

Transit-Time Factor



- Assume uniform electric field in the gap
- Assume particle velocity v change in the gap is small

$$T = \frac{\sin \omega L / 2v}{\omega L / 2v}$$



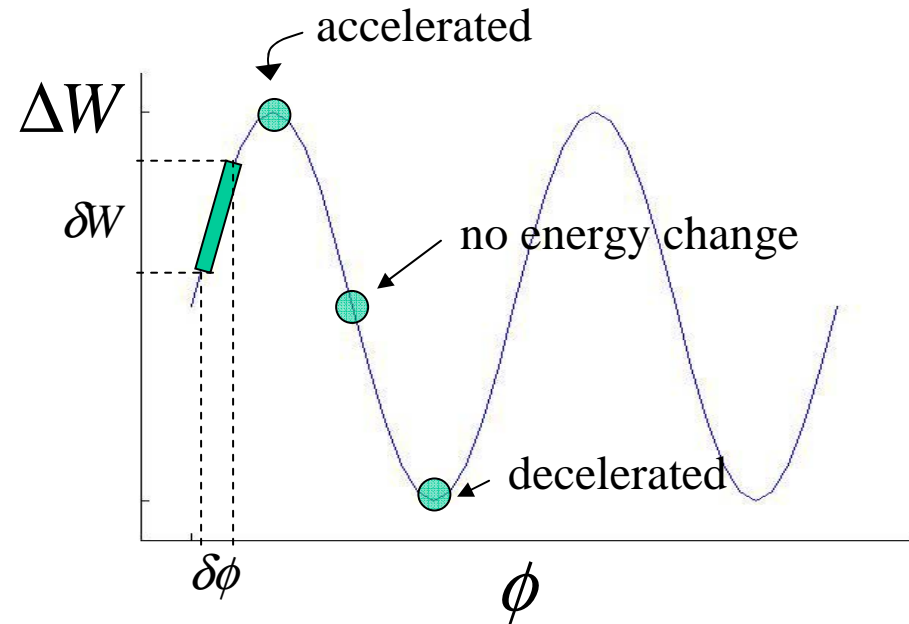
a

- Transit-time factor decreases with gap width
- Transit-time factor increases with particle velocity
- Transit-time factor is “geometrical” factor – depends on gap geometry but doesn’t depend on electrical field strength

Accelerating phase

$$\Delta W = e \cdot V \cdot T \cdot \cos \phi$$

- Energy gain for individual particle depends on arrival phase
- If particles in the beam occupy a finite range of phases $\delta\phi$, the output energy will occupy range of energies – **energy spread** δW
- To obtain accelerated beam with small energy spread requires grouping particles in the narrow range of phases (**bunch**) around the **accelerating phase**



Typical values :

$$\delta W \approx (10^{-3} \div 10^{-2}) \cdot W$$

$$\delta\phi \approx 1^\circ - 10^\circ$$

Gap voltage



$$V_0 = \int_{-L/2}^{L/2} E_0(z) \cdot dz \quad \text{In uniform field: } V_0 = E_0 \cdot L$$

- To increase energy gain:
 - ✓ increase gap length L
 - limited by transit-time factor decrease
 - ✓ increase electrical field strength E
 - limited by electrical breakdown; available RF power

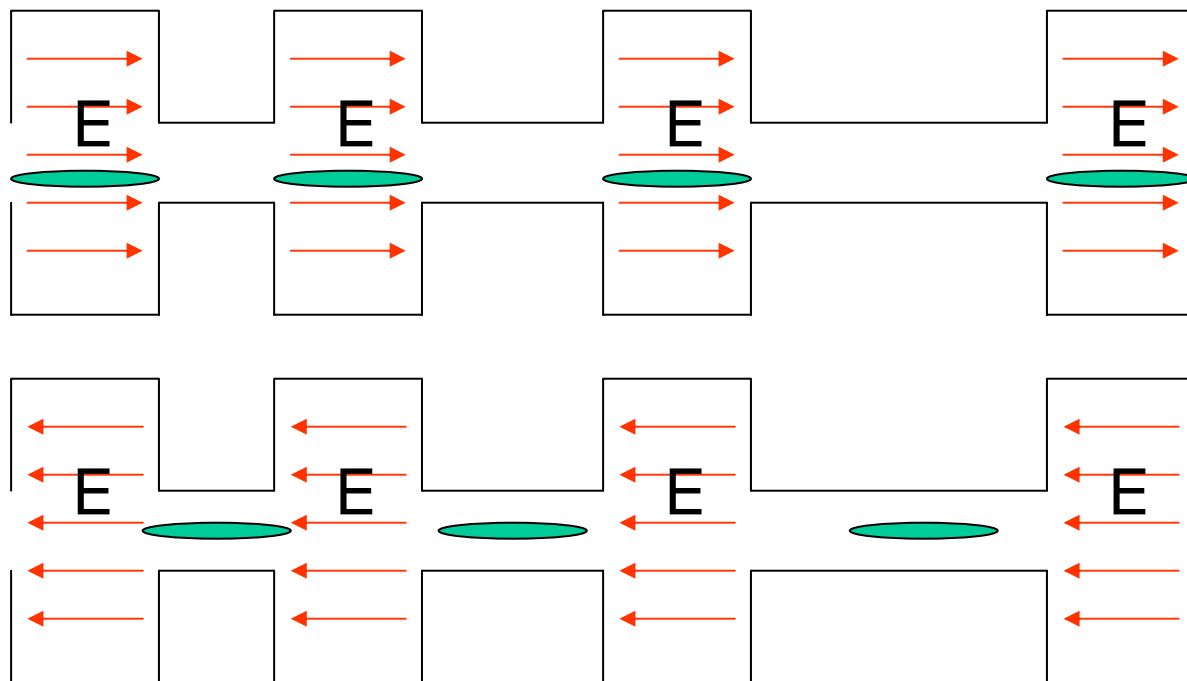
Typical values :

$$E = 3 \div 30 \text{ MV/m} \quad L \approx \frac{\beta\lambda}{4} = .01 \div .1 \text{ m}$$

$$V \approx .03 \div 3 \text{ MV}$$

- Can not reach large acceleration in single gap -> use multiple gaps

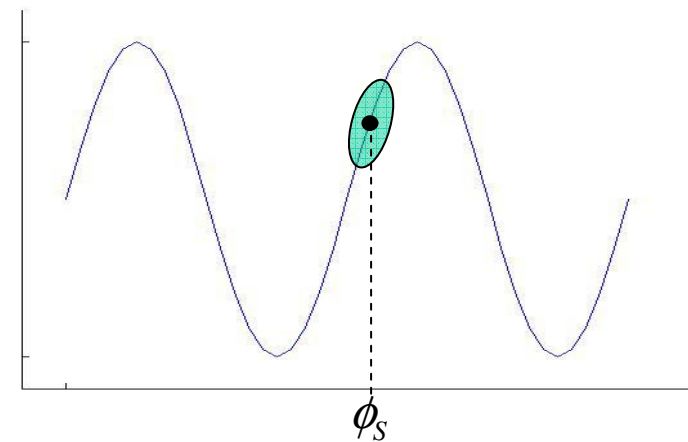
- We can make an accelerator by “stringing” together many individual accelerating cells, one after the next
- Since the particle is accelerated in each cell, we have to space the cells farther apart as the velocity increases



Synchronous Particle and Synchronous Phase

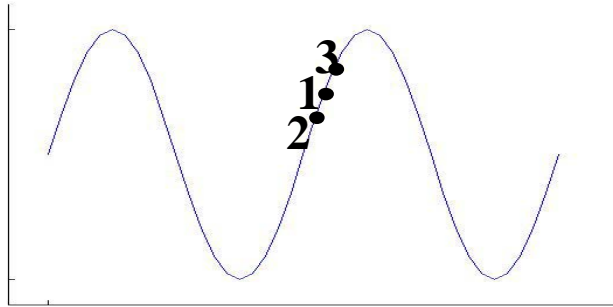


- A **synchronous particle** is one whose velocity is such that particle appears in the center of successive accelerating gaps in step with the RF fields. That is, the particle arrives at each gap center at the **synchronous phase** ϕ_s
- For synchronous particle to exist the accelerator has to be properly designed:
 - Time of flight from one gap center to another is multiple of the RF period
- Synchronous particle has exact phase and energy.
- Other particles in the bunch do not satisfy the synchronicity condition
- How to keep particles in compact bunch around the synchronous phase?



! Autophasing mechanism can provide longitudinal focusing

Autophasing mechanism

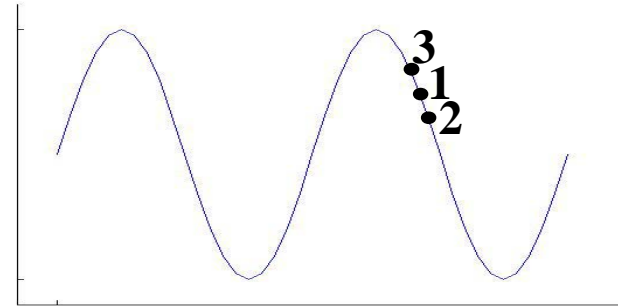


#1 – synchronous particle arrives at synchronous phase; gets design energy increment

#2- fast particle arrives at smaller phase; gets smaller energy increment

#3 - slow particle arrives at larger phase; gets larger energy increment

fast particle decelerates until it becomes slow particle, then accelerates and so on – stable oscillations around the synchronous phase



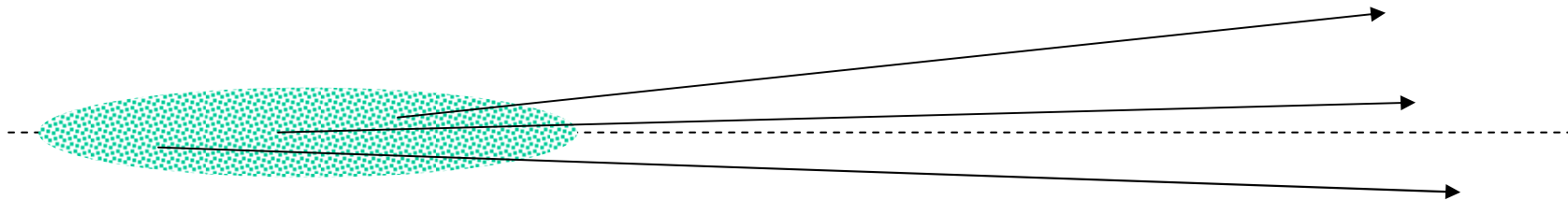
#1 – synchronous particle arrives at synchronous phase; gets design energy increment

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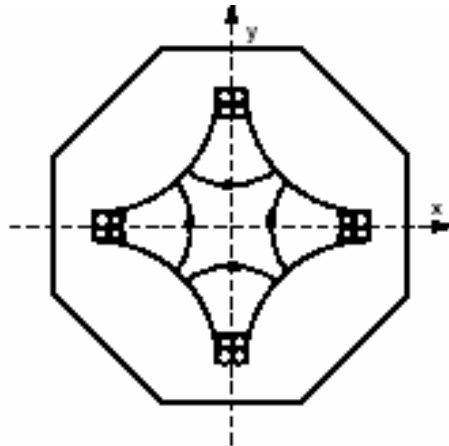
fast particle accelerates, slow particle decelerates – unstable longitudinal motion.

Transverse focusing



- Need many accelerating gaps to achieve high energy thus long particle path
- Particles tend to travel away from the axis because of
 - Spread of initial transverse angles
 - Coulomb repulsion of charged particles
 - Transverse component of RF field in the gaps
 - Stray magnetic field (Earth, cables....)
- Need mechanism to keep particles near the axis of the accelerator (**Transverse focusing**)
 - Electric fields (at low energy) – electrostatic lenses, RFQ
 - Magnetic fields (at high energy) – magnetic lenses

Quadrupole focusing



Quadrupole magnet cross section showing magnetic field pattern

- In an ideal quadrupole field the pole tips have hyperbolic profiles and produce a constant transverse quadrupole gradient:

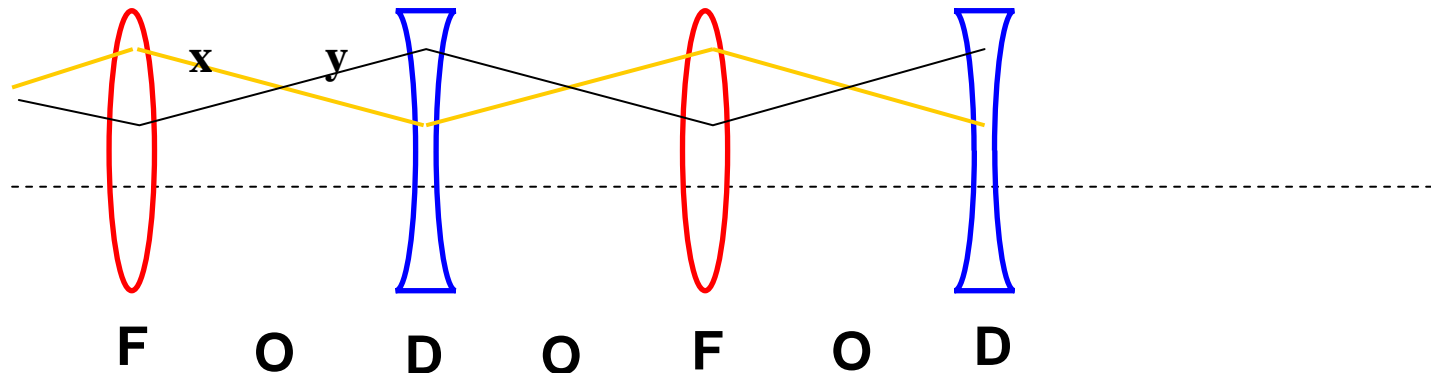
$$G = \frac{\partial B_x}{\partial y} = \frac{\partial B_y}{\partial x}$$

- For a particle moving along the z direction with velocity v and transverse coordinates (x,y), the Lorentz force components are:

$$F_x = -e \cdot v \cdot G \cdot x, \quad F_y = e \cdot v \cdot G \cdot y$$

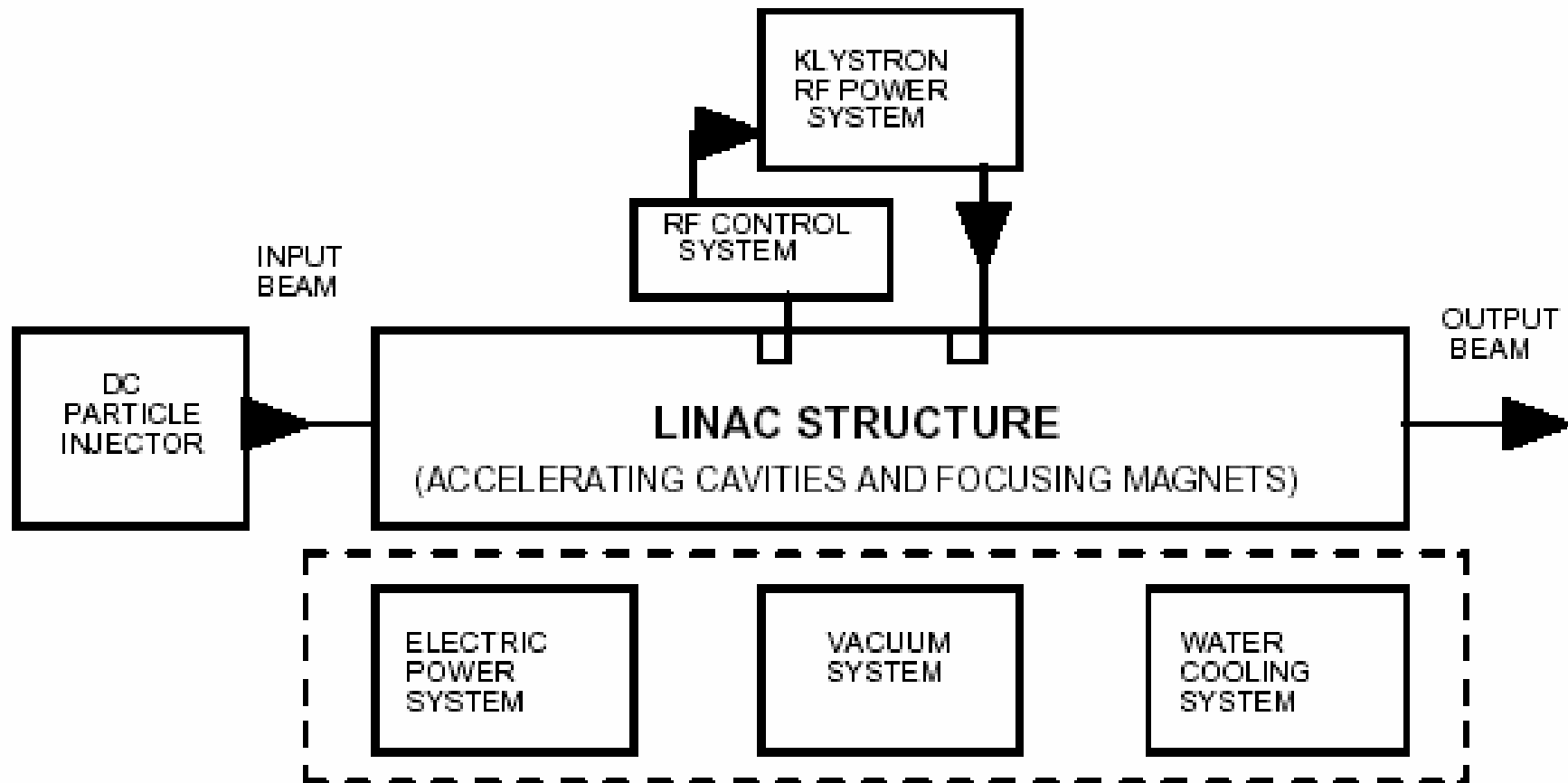
- For a pole tip with radius a and pole-tip field B, the gradient is $G=B/a$
- If $e \cdot G$ is positive, the lens focuses in x and defocuses in y
- Although individual quadrupole lenses focus in only one plane, they can be combined in systems to give overall strong focusing in both transverse plains.

FODO channel



- The FODO lattice periodic structure is the most common focusing structure in accelerators.
- Provides focusing in both transverse planes
- Certain relations between focusing strength of the lenses and distance between them should be satisfied to ensure stability. Well developed mathematical methods exist. Matrix formalism.

Block diagram of an RF linac system



The Spallation Neutron Source (SNS)



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SNS main parameters

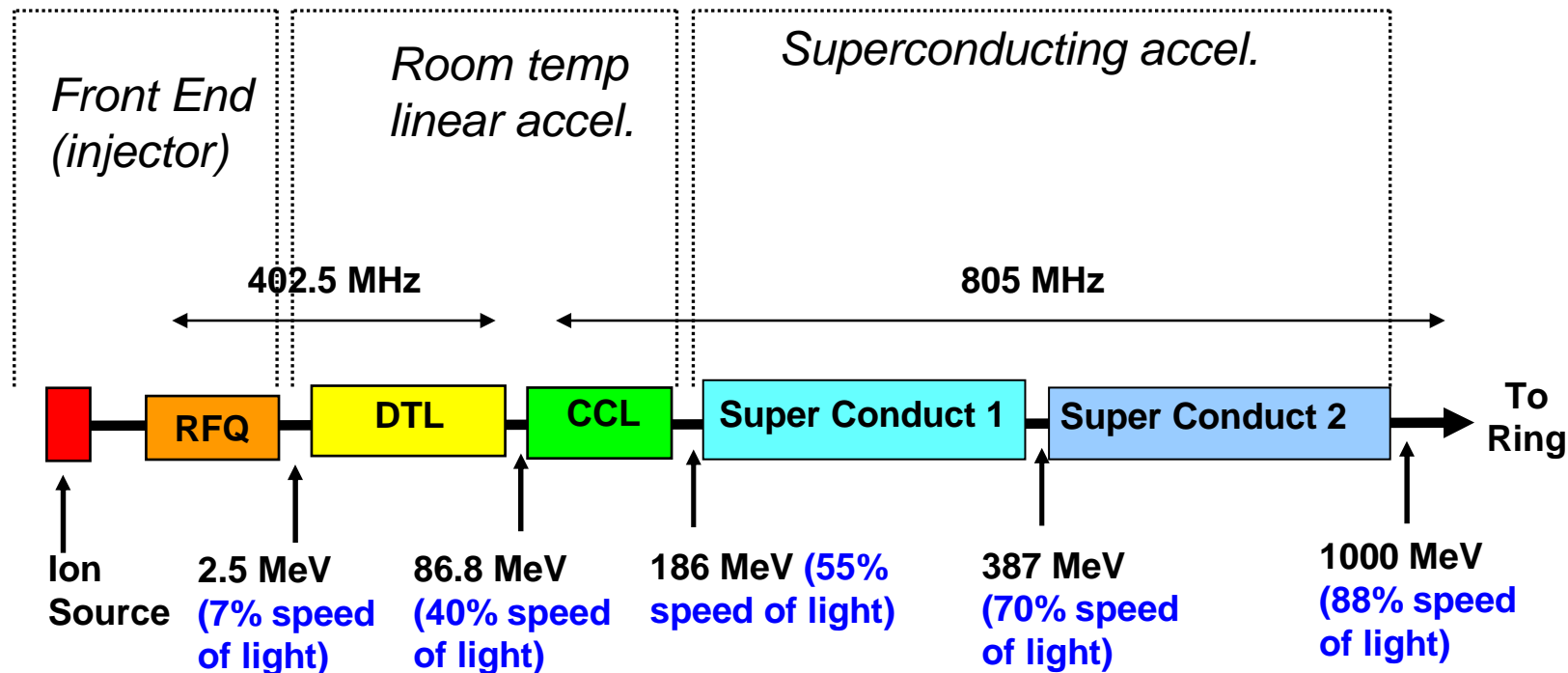


Power on target	1.4	MW
Proton beam energy on target	1.0	GeV
Proton pulse width on target	695	ns
Linac pulse width	1.0	ms
Linac peak current	38	mA
Pulse repetition rate	60	Hz
Linac length	335	m
Accumulator ring circumference	248	m

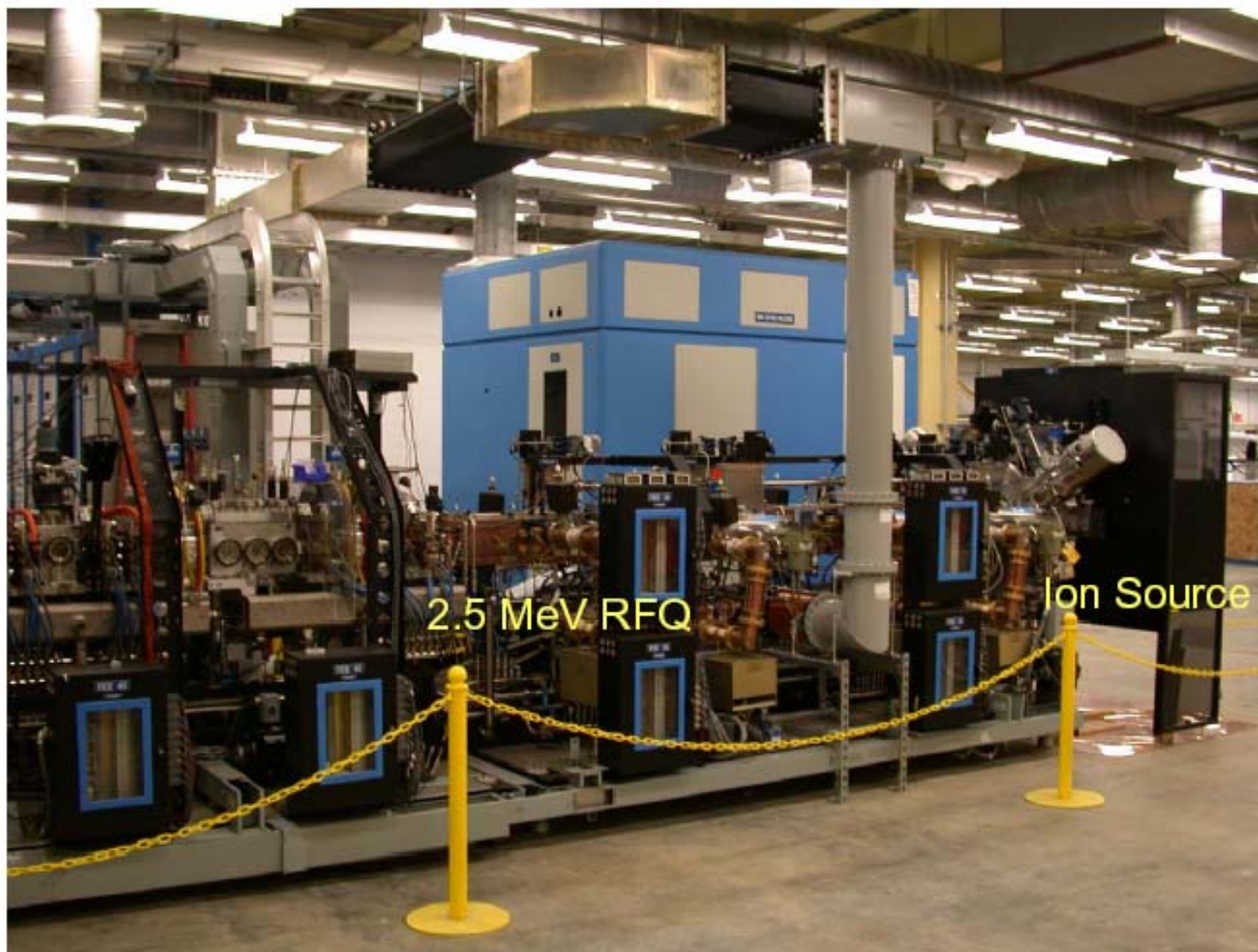
The SNS Linear Accelerator (LINAC)



- The SNS Linac is constructed of 5 different types of accelerating cavities.
- Each is optimized to a certain range of H- beam velocities



The SNS Front End

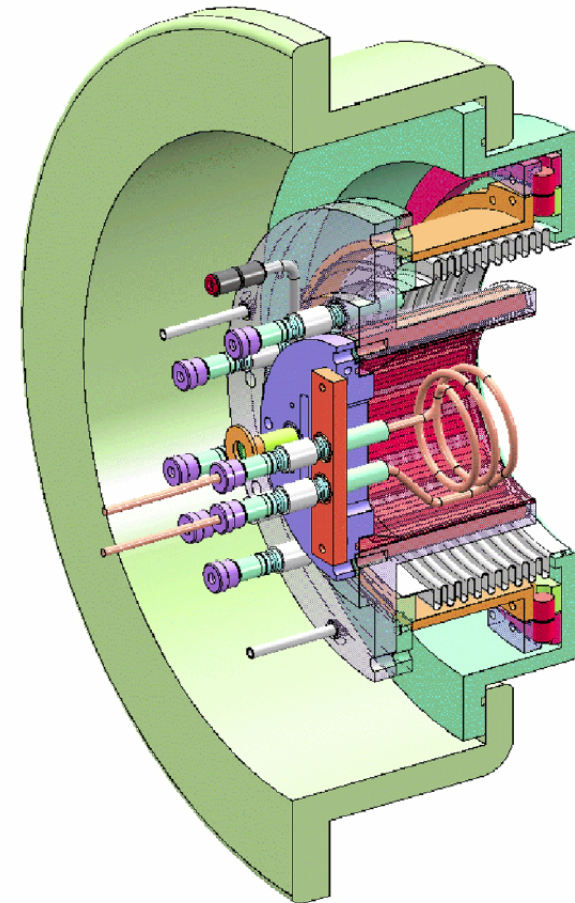


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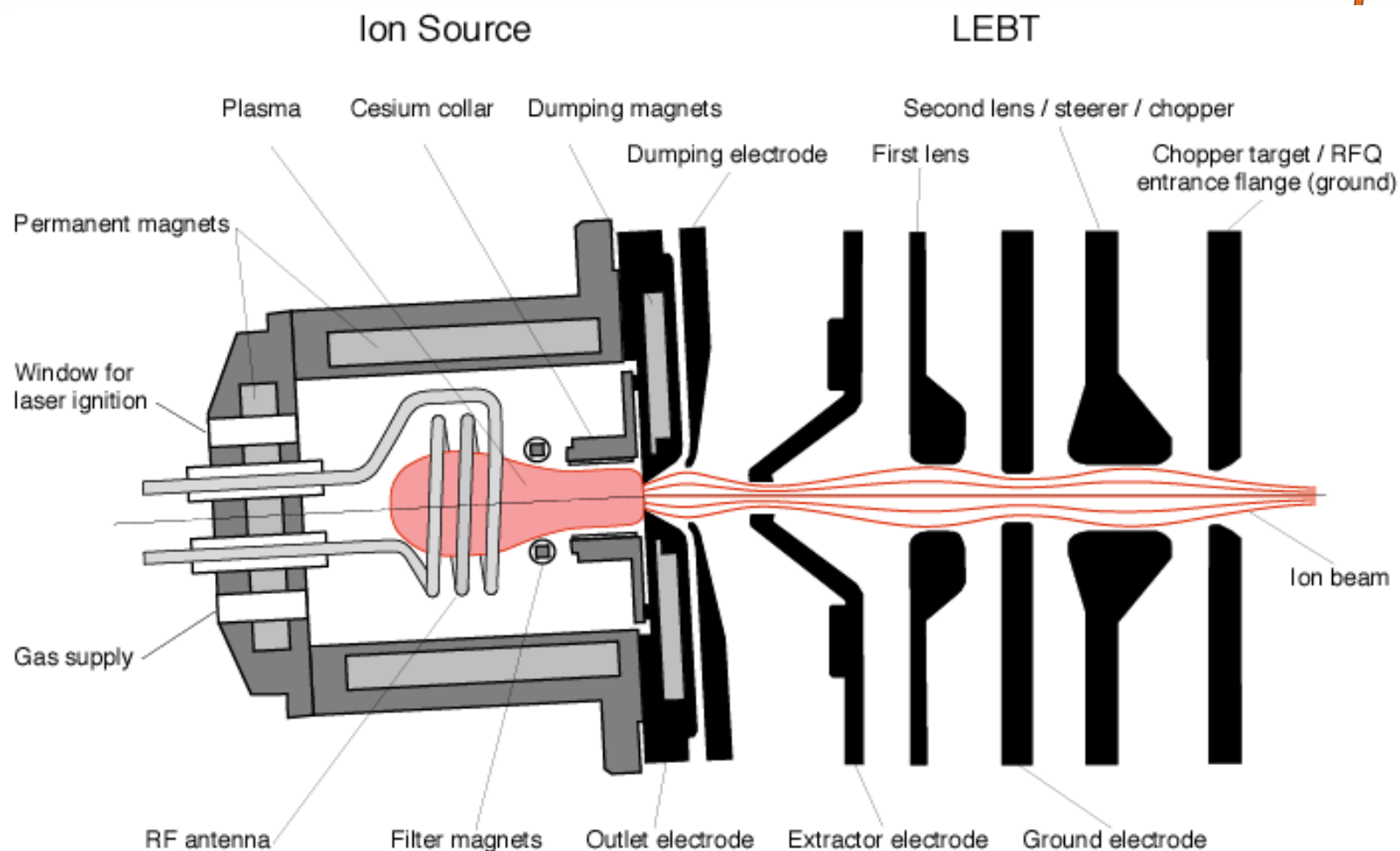
The SNS Ion Source



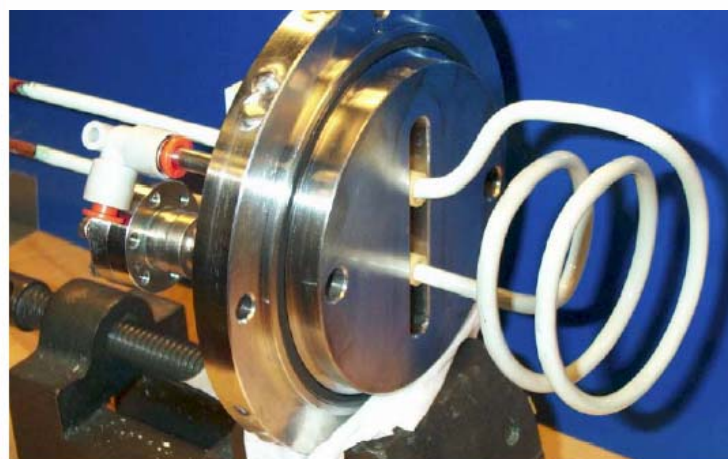
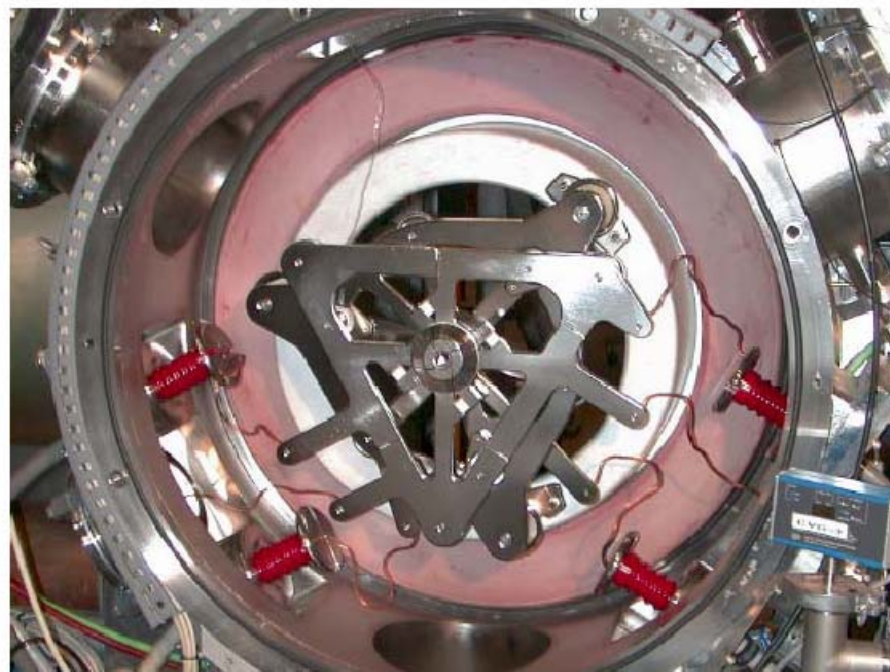
Ion species	H⁻
Extraction Energy (keV)	65
H ⁻ output current (mA)	48
Normalized rms emittance (π mm mrad)	0.2
Pulse length (ms)	1.2
Duty factor	6%
Repetition rate (Hz)	60



The SNS Ion Source and LEBT layout



Some magnet orientations are rotated into the viewing plane of this illustration

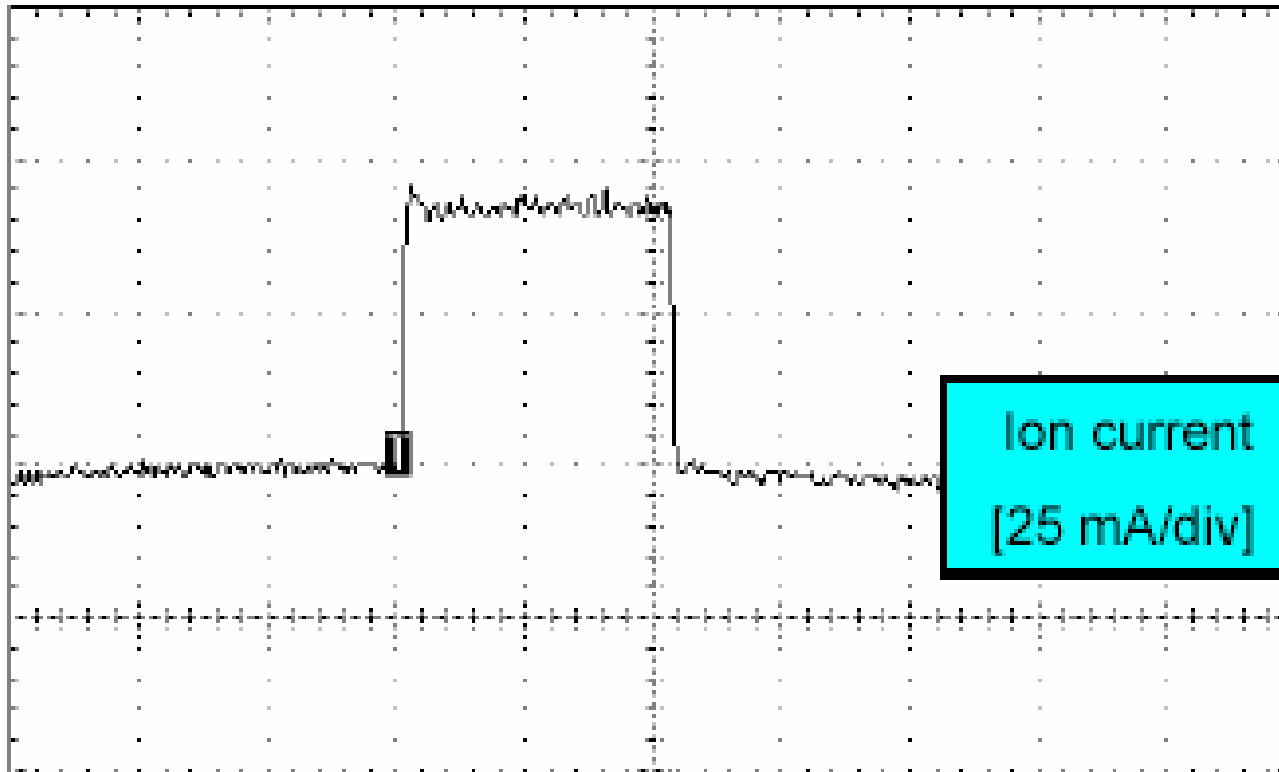


Plasma glow in the RF discharge chamber

Electrodes of the LEBT

2MHz RF antenna

Ion Source Beam Pulse



- Ion source produce pulse of continues current (DC), not divided on bunches.

The SNS Radio Frequency Quadrupole RFQ accelerator

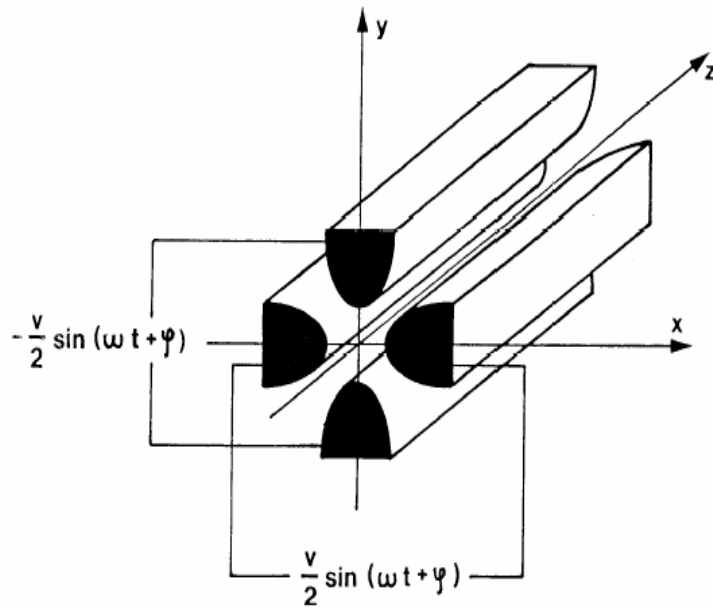


- The invention of the RFQ made major improvement in the current limit for ion RF linacs. *I.M.Kapchinskiy and V.A.Tepliakov, Prib.Tekh.Eksp. 2,19-22(1970)*
- The RFQ RF structure provides rf electric field for bunching (dividing continuous beam on separate bunches), acceleration, and longitudinal and transverse rf focusing.

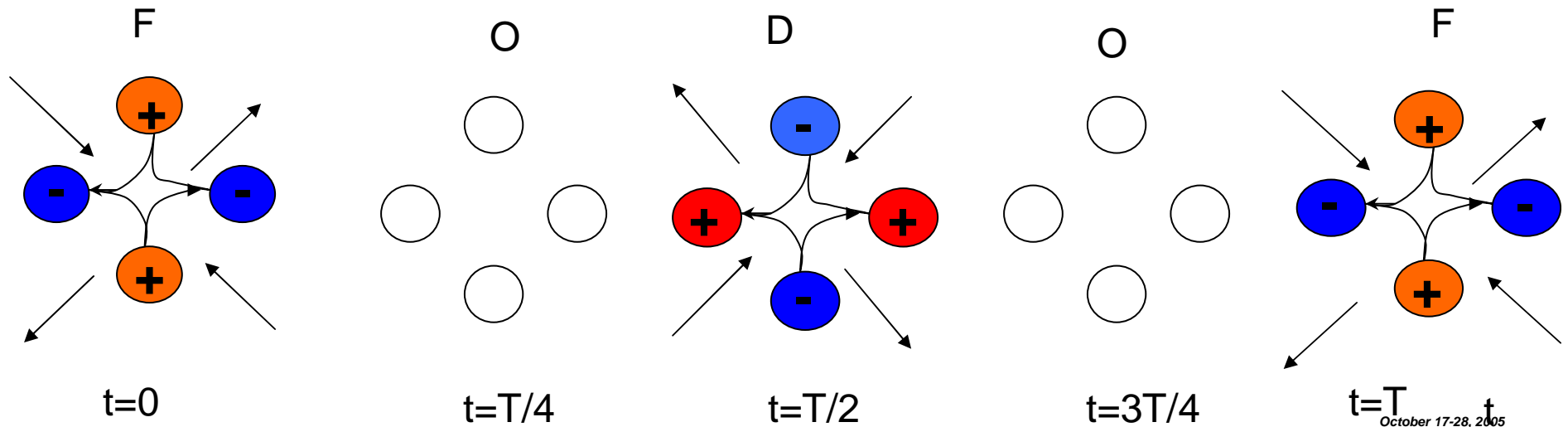
The SNS RFQ Parameters

Input energy	65 kV
Output energy	2.5MeV
Beam current	15-60mA
RF frequency	402.5MHz
Peak RF power	720kW with nominal beam
Average RF power	45kW with nominal beam

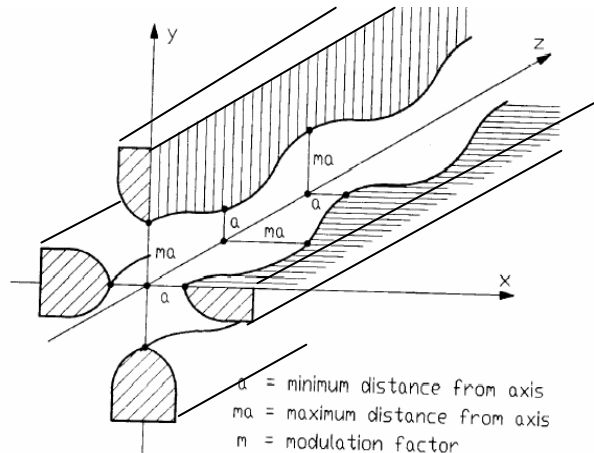
RFQ principle of operation



- Action of RF quadrupole focusing channel is similar to conventional FODO structure
- Quadrupole configuration of electrical field provides transverse focusing/de-focusing
- Focusing strength varies in time not in space (it is the same from particle point of view)
- No acceleration yet!



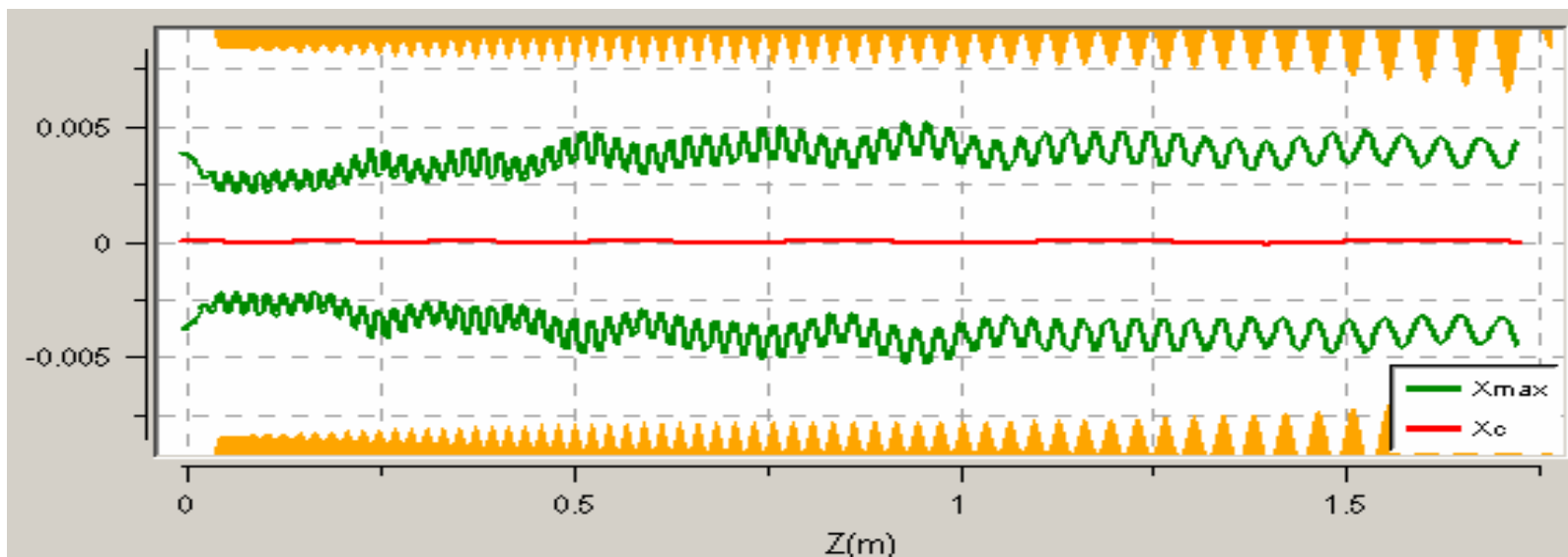
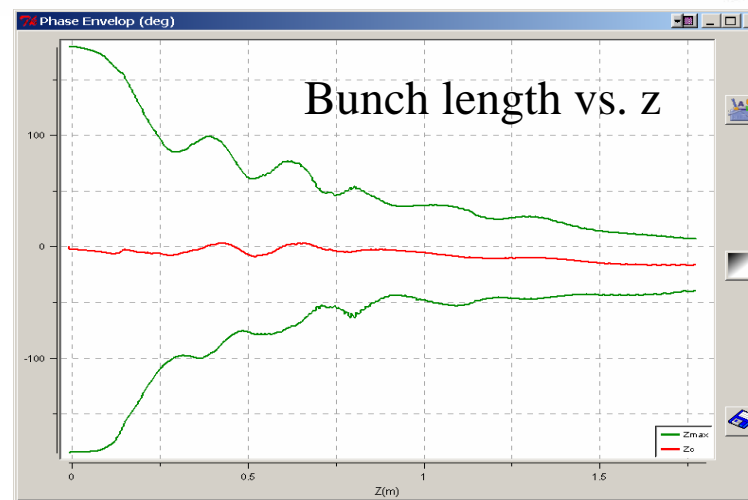
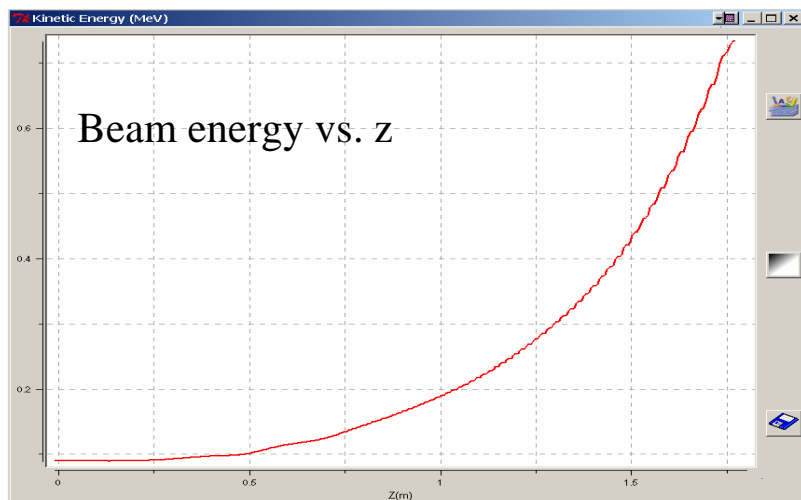
RFQ principle of operation



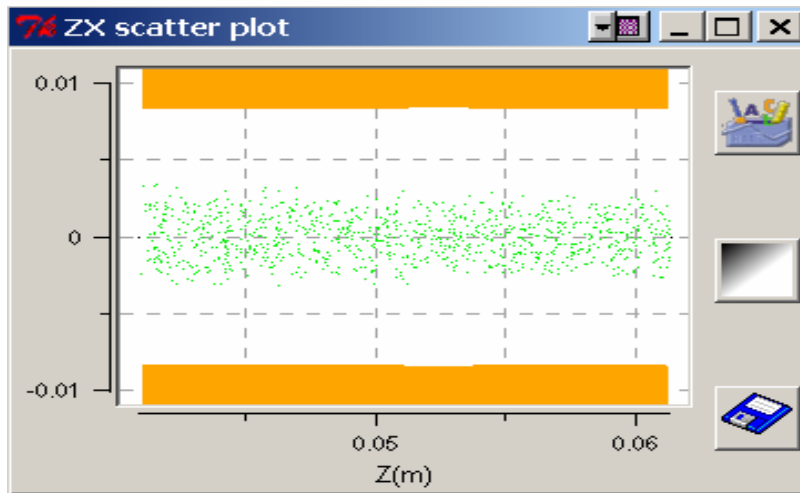
- Longitudinal electric field is created by modulating electrode shape along the longitudinal axis
- When longitudinal RF field is introduced then synchronous phase can be defined. Bunching and acceleration becomes possible

- Configuration and strength of the longitudinal field is defined by geometrical pattern of the modulation, which can be varied along RFQ smoothly and in wide range. That gives powerful control over longitudinal beam dynamics:
- Starting from zero at RFQ entrance and slowly increasing the longitudinal field strength (**controlled by modulation depth**) one can bunch incoming DC beam with high efficiency
- Slowly change synchronous particle phase (**controlled by modulation period**) from bunching to acceleration

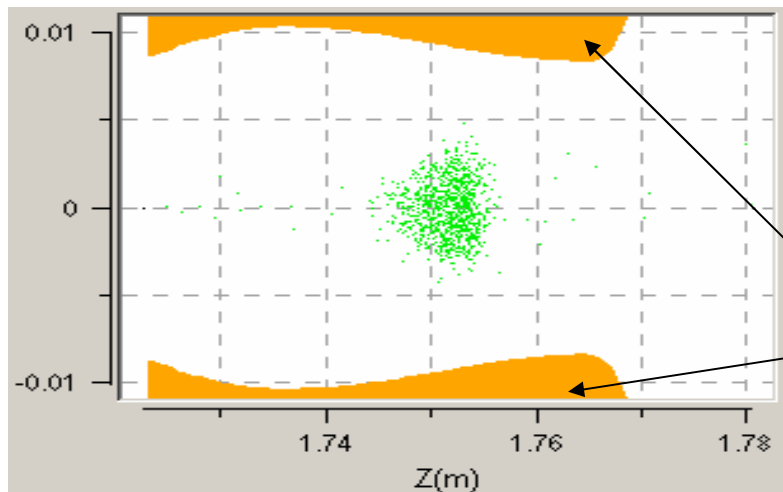
Beam in RFQ: simulation



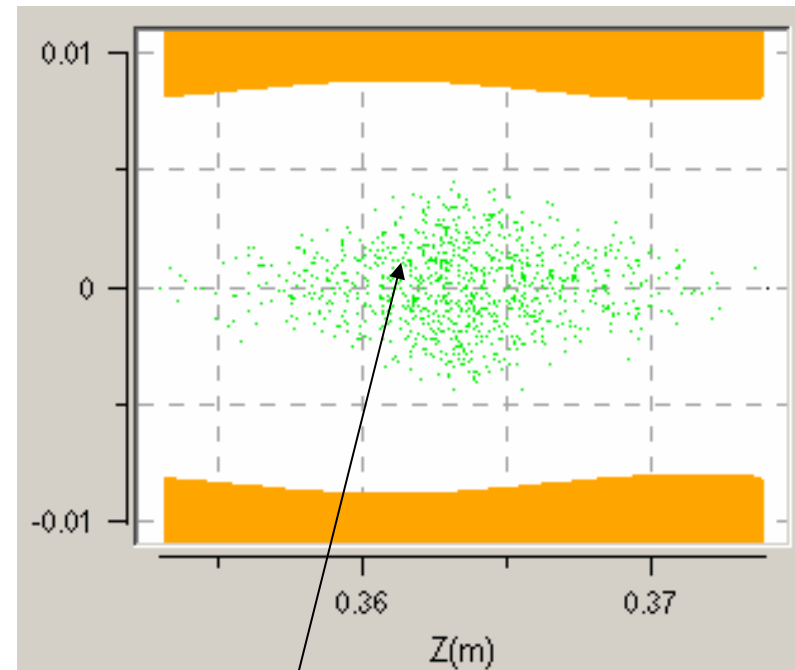
Beam in RFQ: simulation



RFQ entrance. Bunching starts.



Middle of RFQ. Bunching finished, acceleration starts.

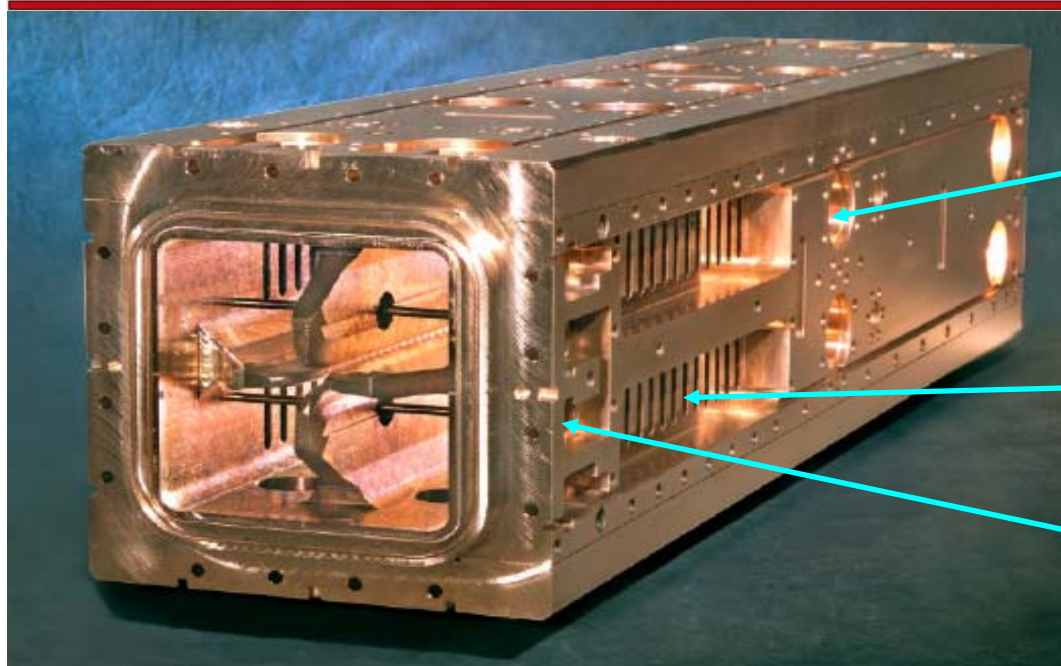


poles

particles

RFQ exit. Acceleration finished

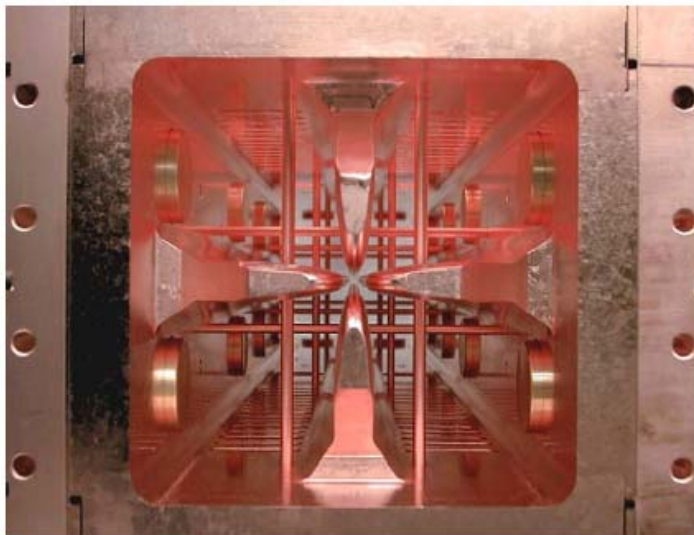
The SNS RFQ cavity



RF drive
loop
penetration

pumping port

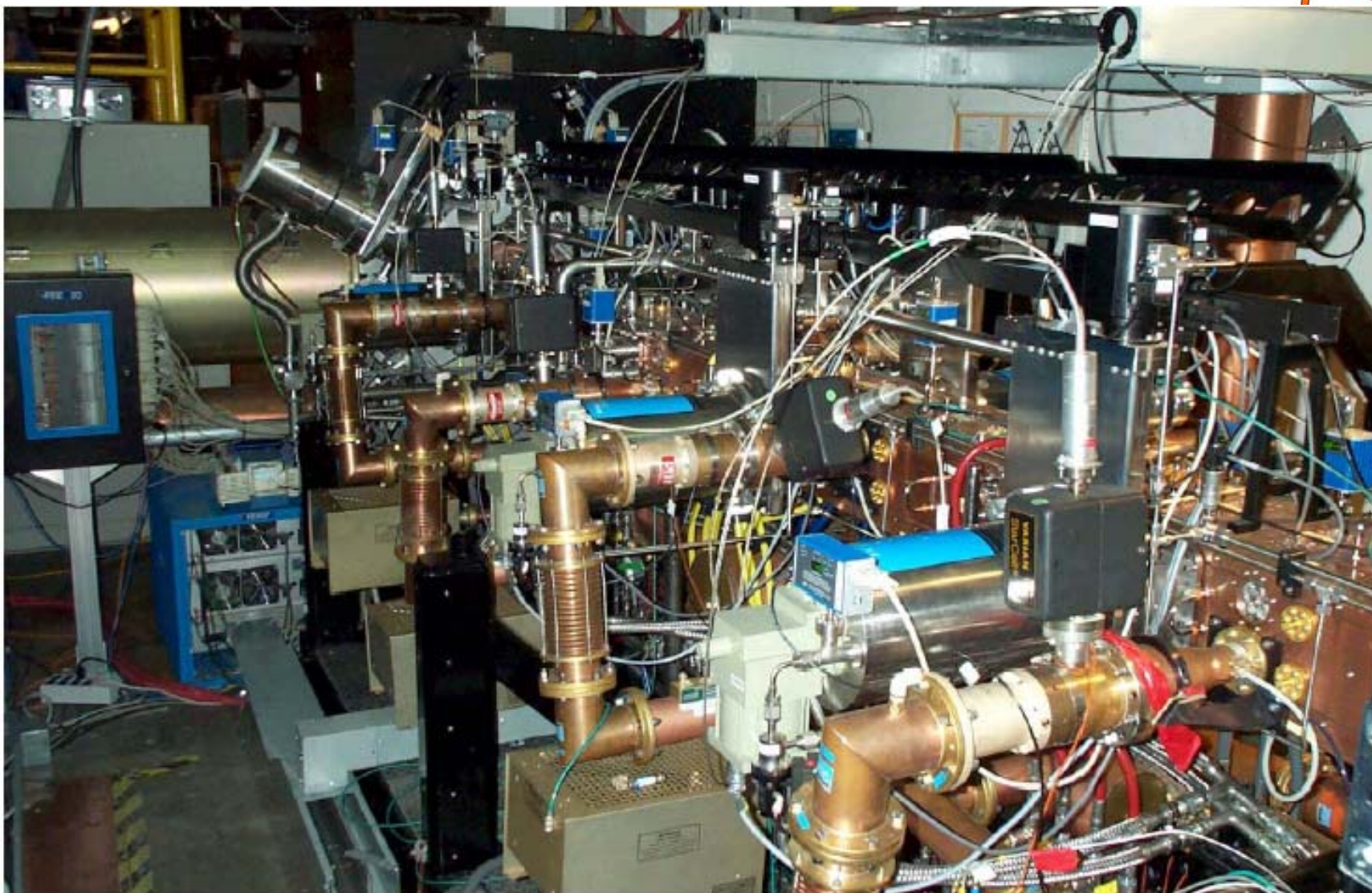
Cooling
channel



➤ To make it work we need to add:

- Vacuum system
- RF power system
- Cooling system to control temperature

The SNS RFQ

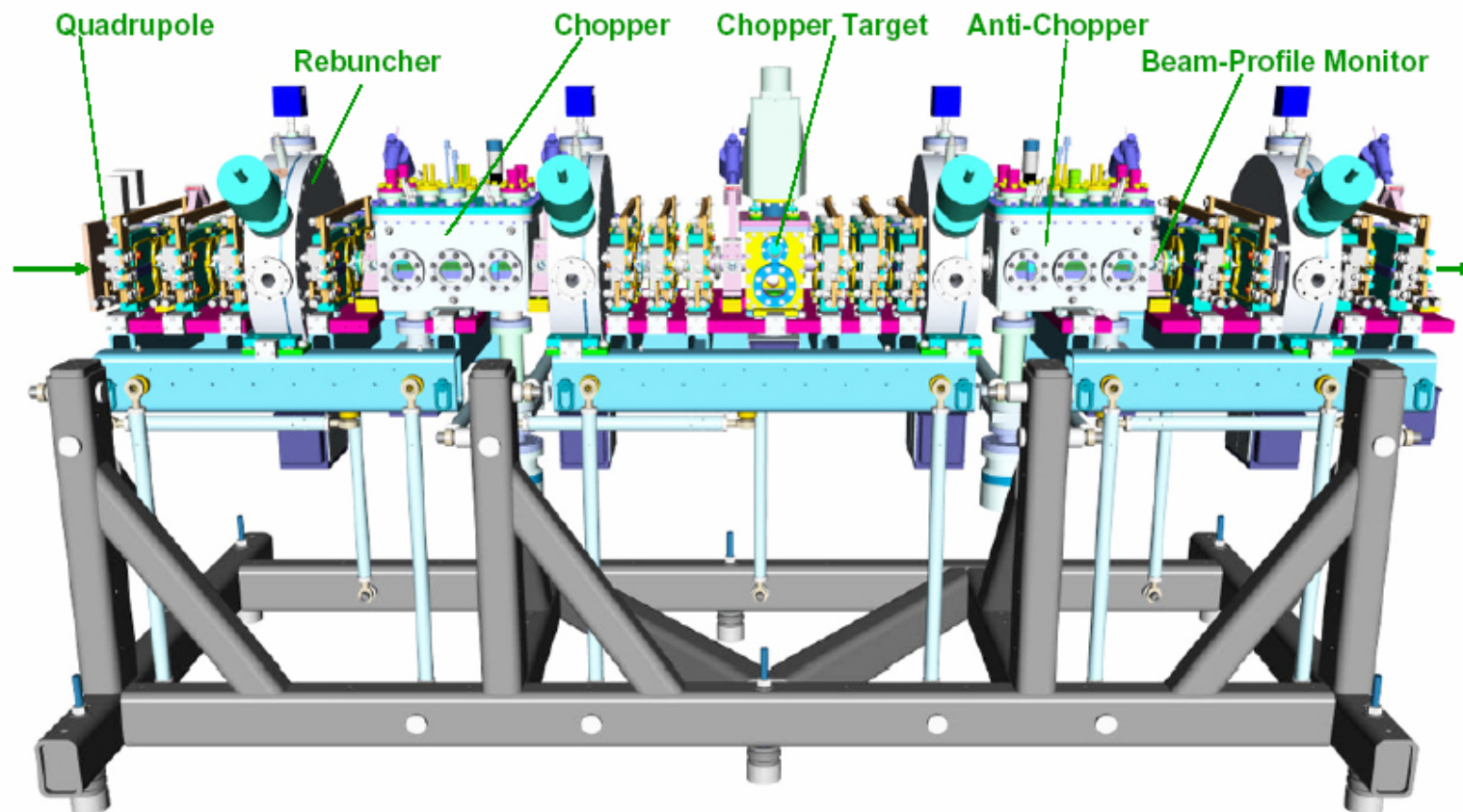


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The SNS Medium Energy Beam Transport line (MEBT)

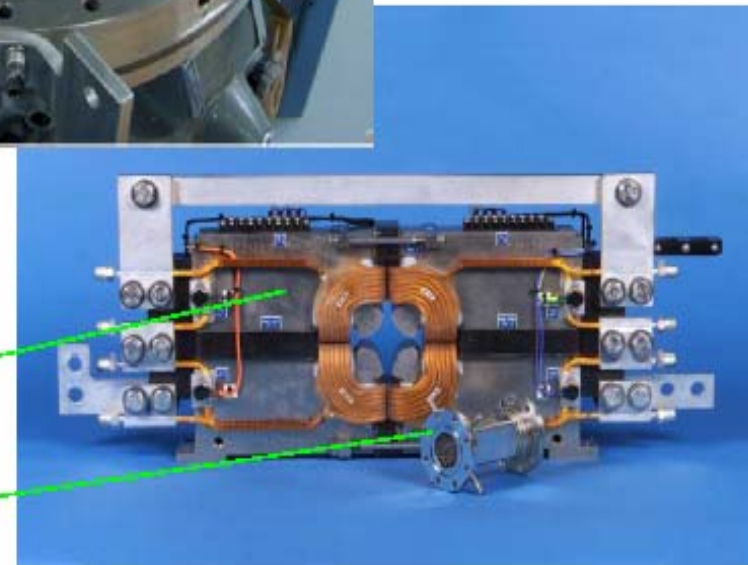
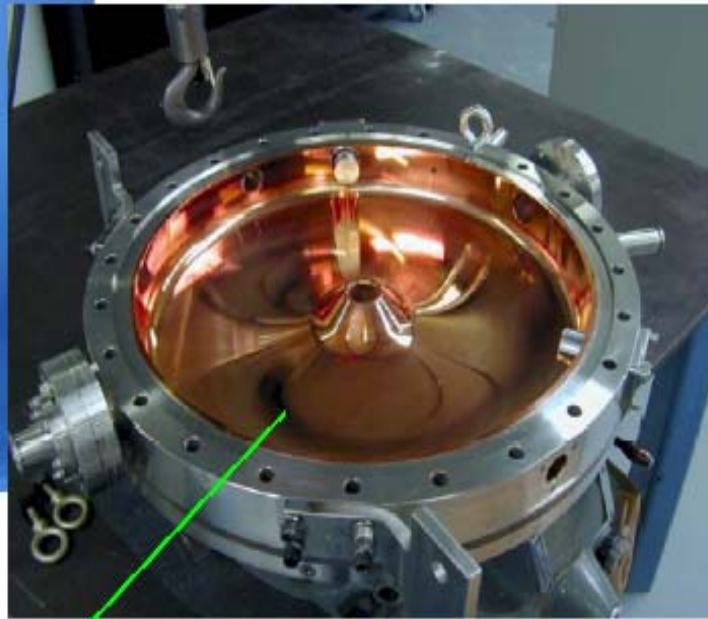
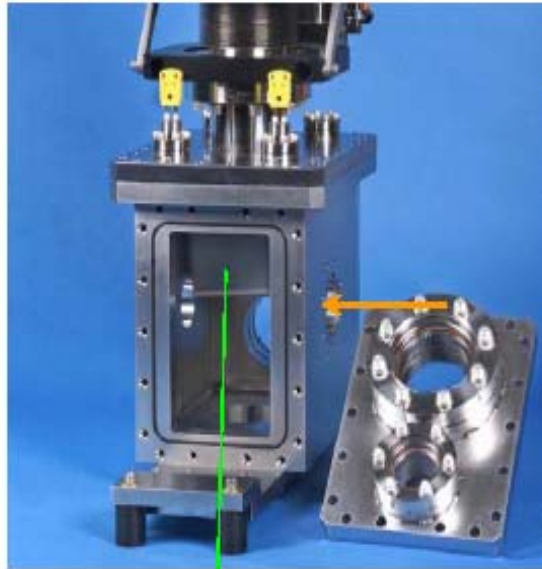


- After the RFQ beam is ready to be injected into the linear accelerator but still has to be chopped for lossless ring extraction
- MEBT provides place for the chopper and various beam diagnostics



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MEBT Components



Chopper Target

Rebuncher Cavity

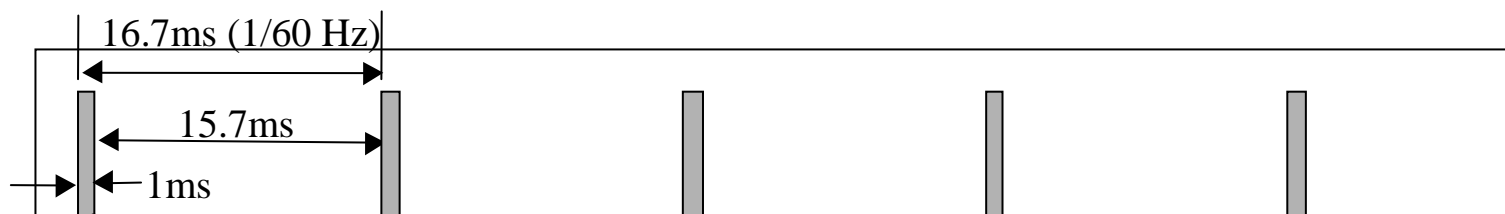
Quadrupole Magnet
with Beam-Position Monitor

Beam pulse structure after the Front End – very complex!



Macro-pulse

Structure
(made by the
Ion Source)



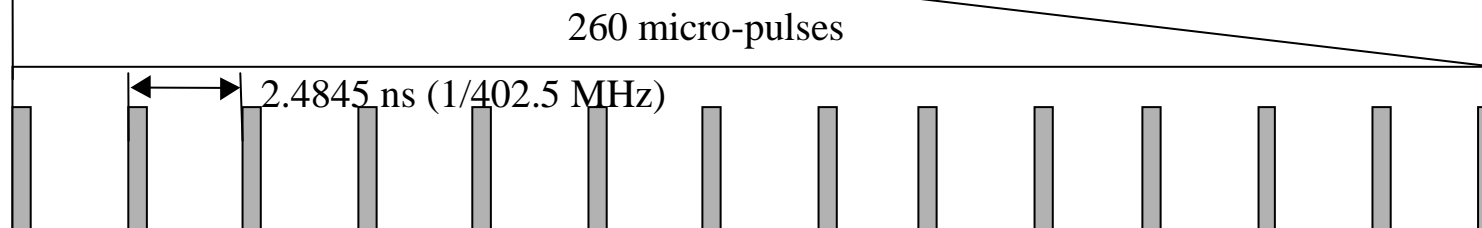
Mini-pulse

Structure
(made by the
choppers)

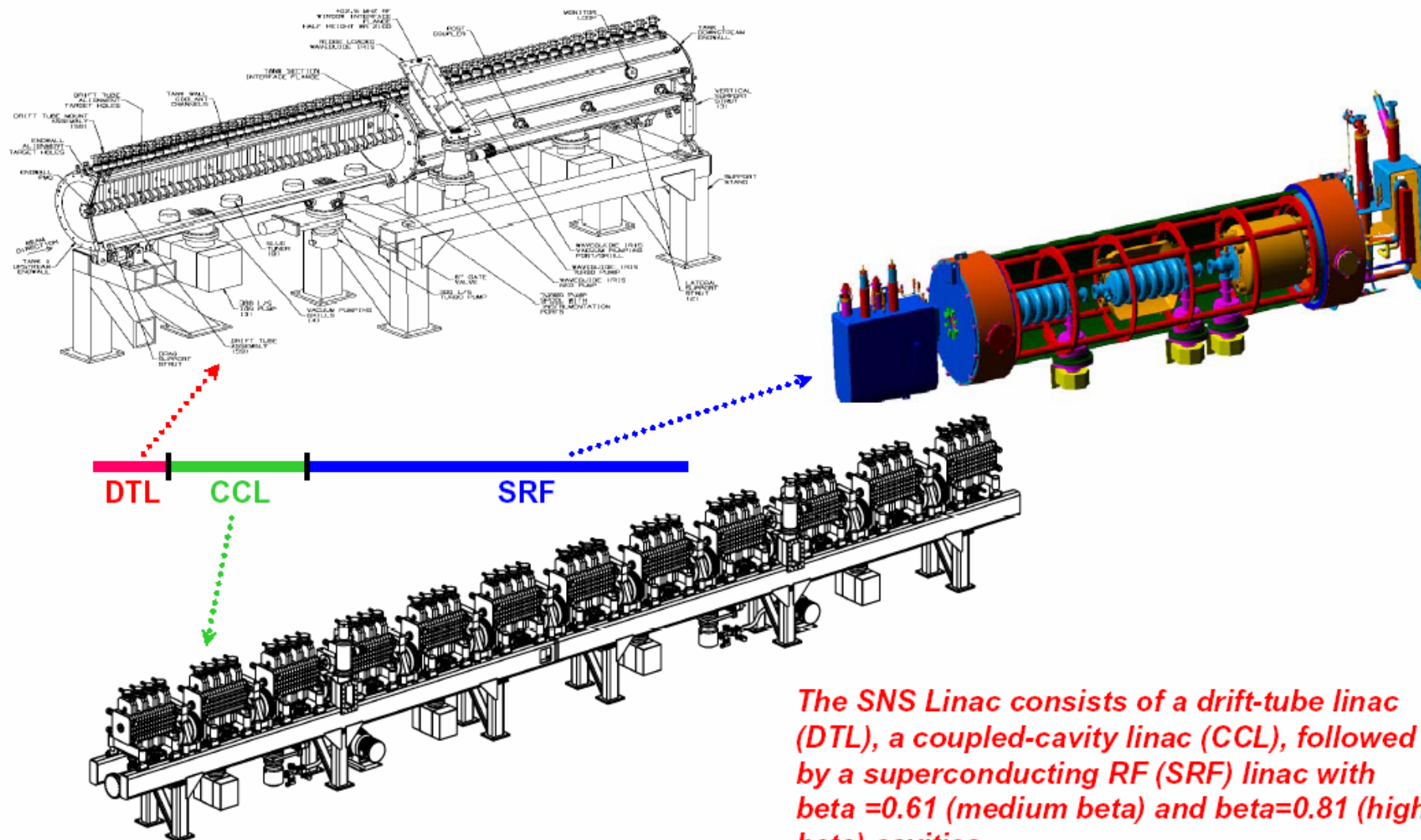


Micro-pulse

structure
(made by the
RFQ)

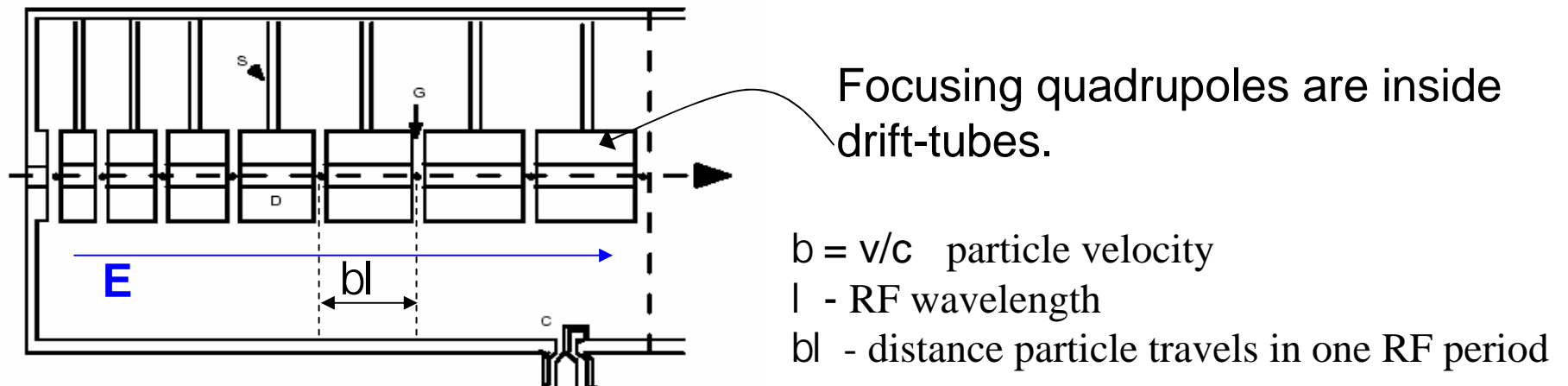


Accelerating structures of the SNS linac

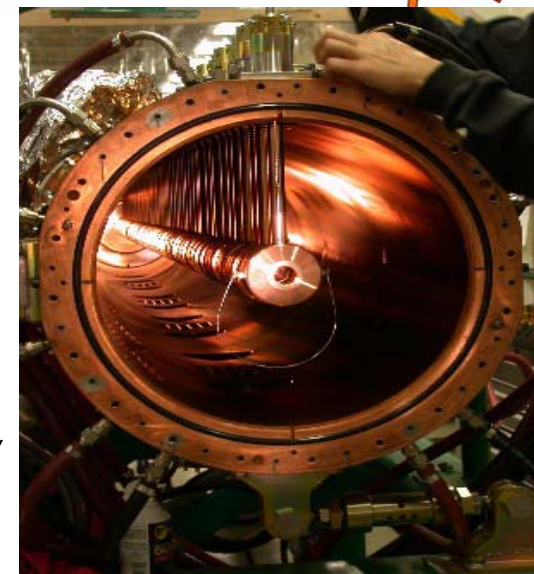
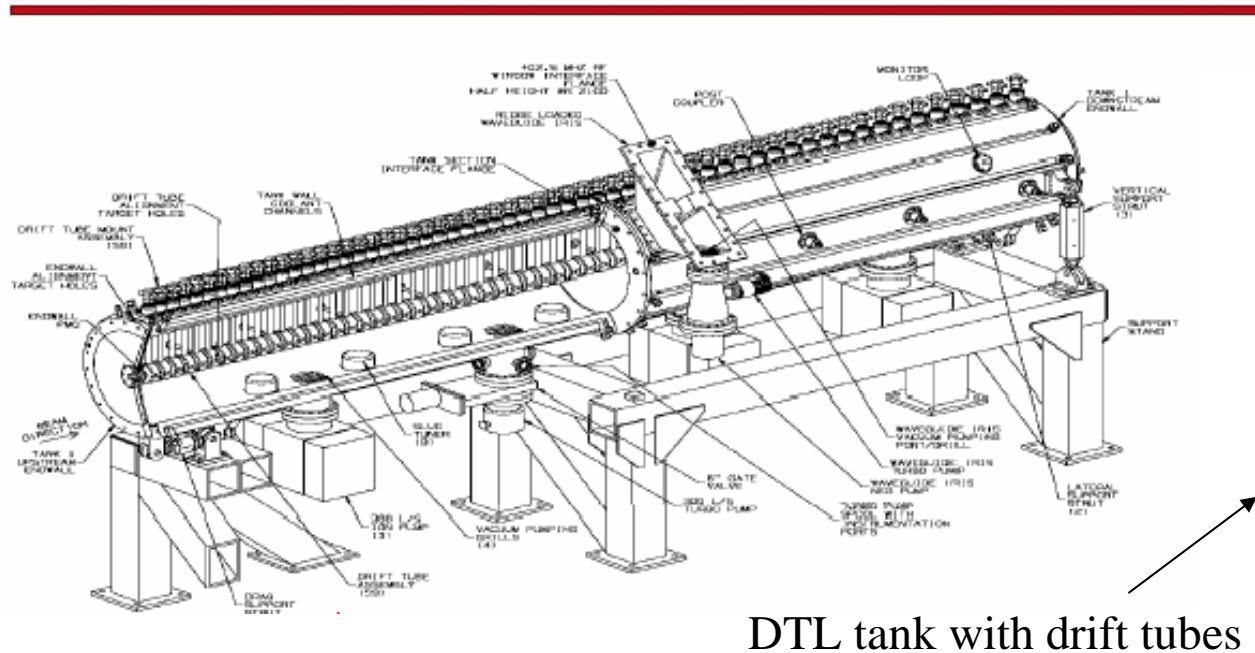


The SNS Linac consists of a drift-tube linac (DTL), a coupled-cavity linac (CCL), followed by a superconducting RF (SRF) linac with $\beta = 0.61$ (medium beta) and $\beta = 0.81$ (high beta) cavities.

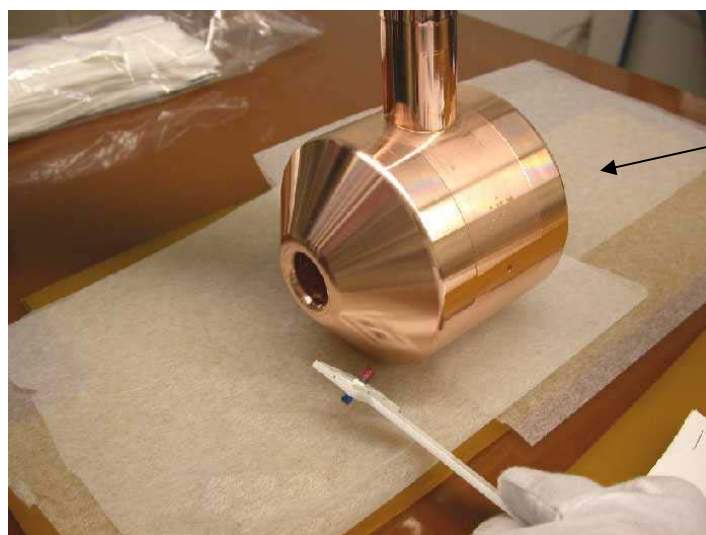
Drift Tube Linac (DTL) Principle of Operation



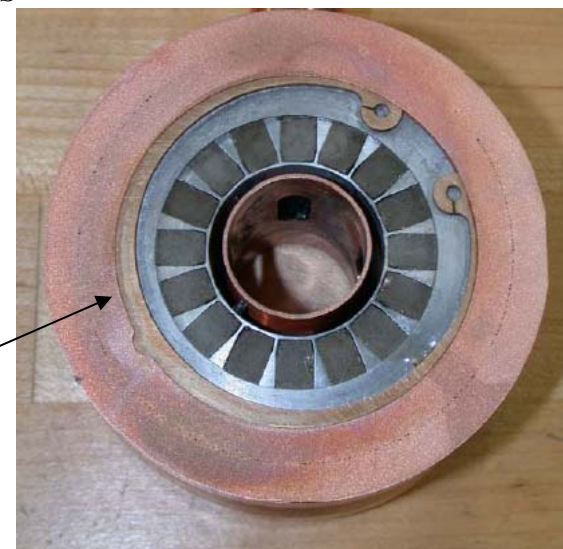
- DTL is a multi-cell cavity obtained by installing drift tubes in a long pillbox cavity operating in a TM₀₁₀ mode.
- Motivation: When pillbox cavity length $> \beta\lambda/2$, acceleration becomes inefficient because Transit-Time factor becomes small.
- The idea is to introduce hollow drift tubes to shield the beam from the decelerating fields, dividing cavity into cells of length $\beta\lambda$. As β increases, cell lengths increase.
- Designed for fixed velocity profile.



DTL tank with drift tubes

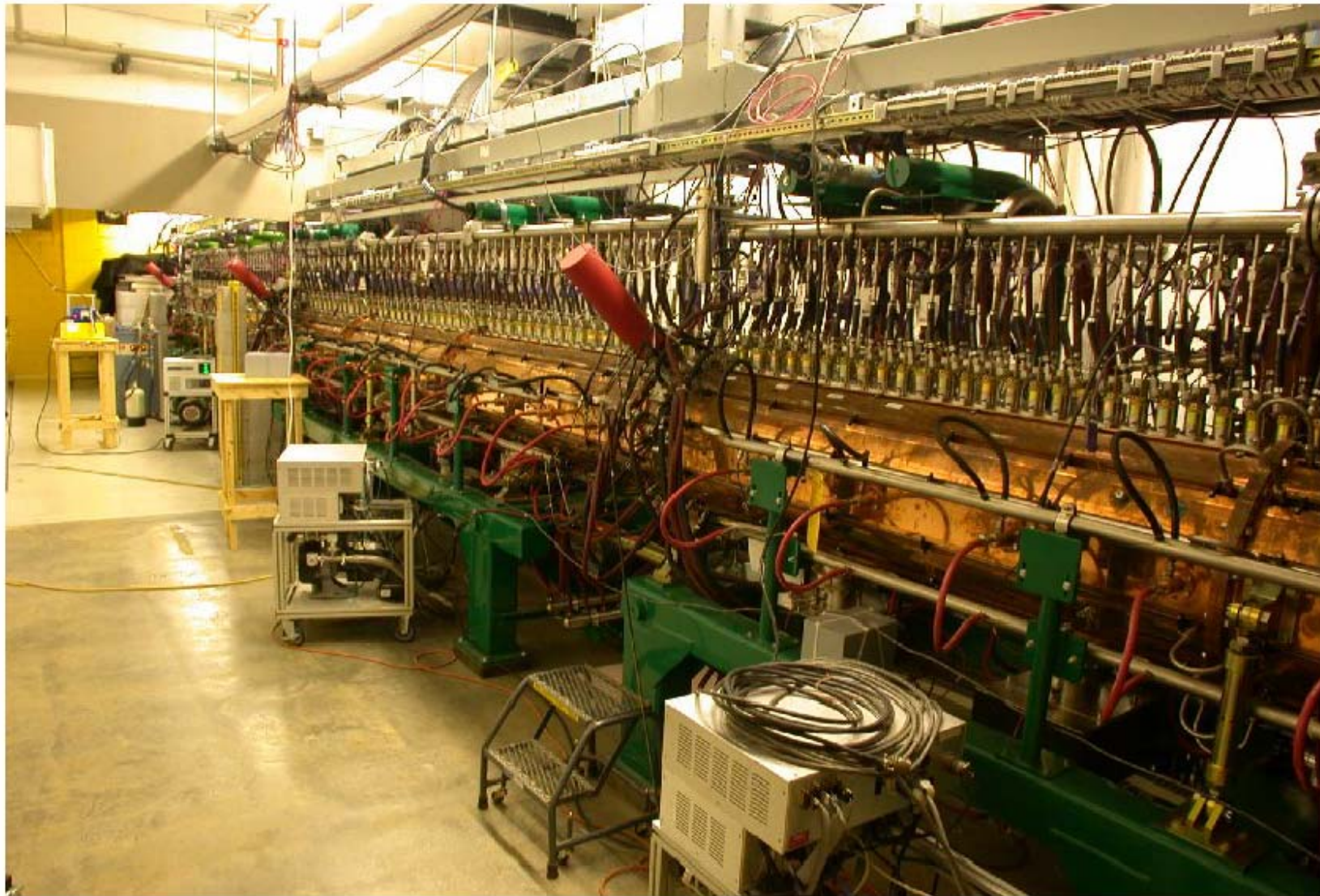


Drift tube



Cross-cut of the
drift tube with
permanent
magnet inside

The SNS DTL in the tunnel



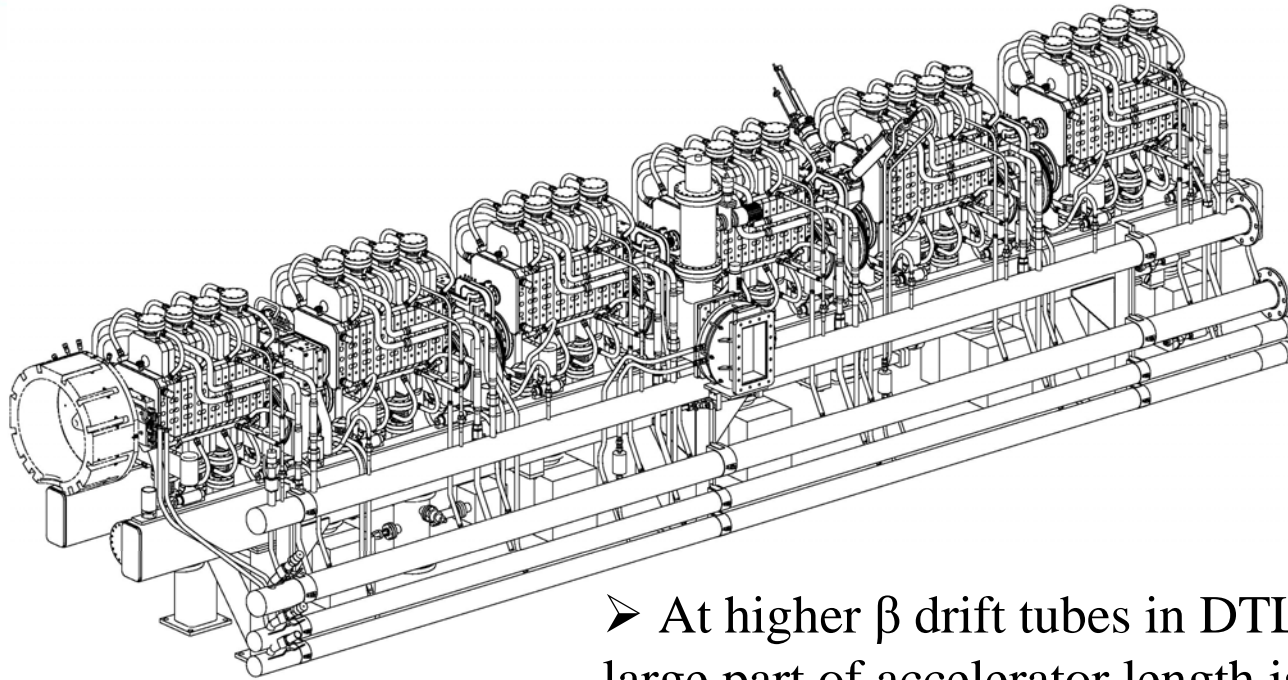
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The SNS DTL parameters



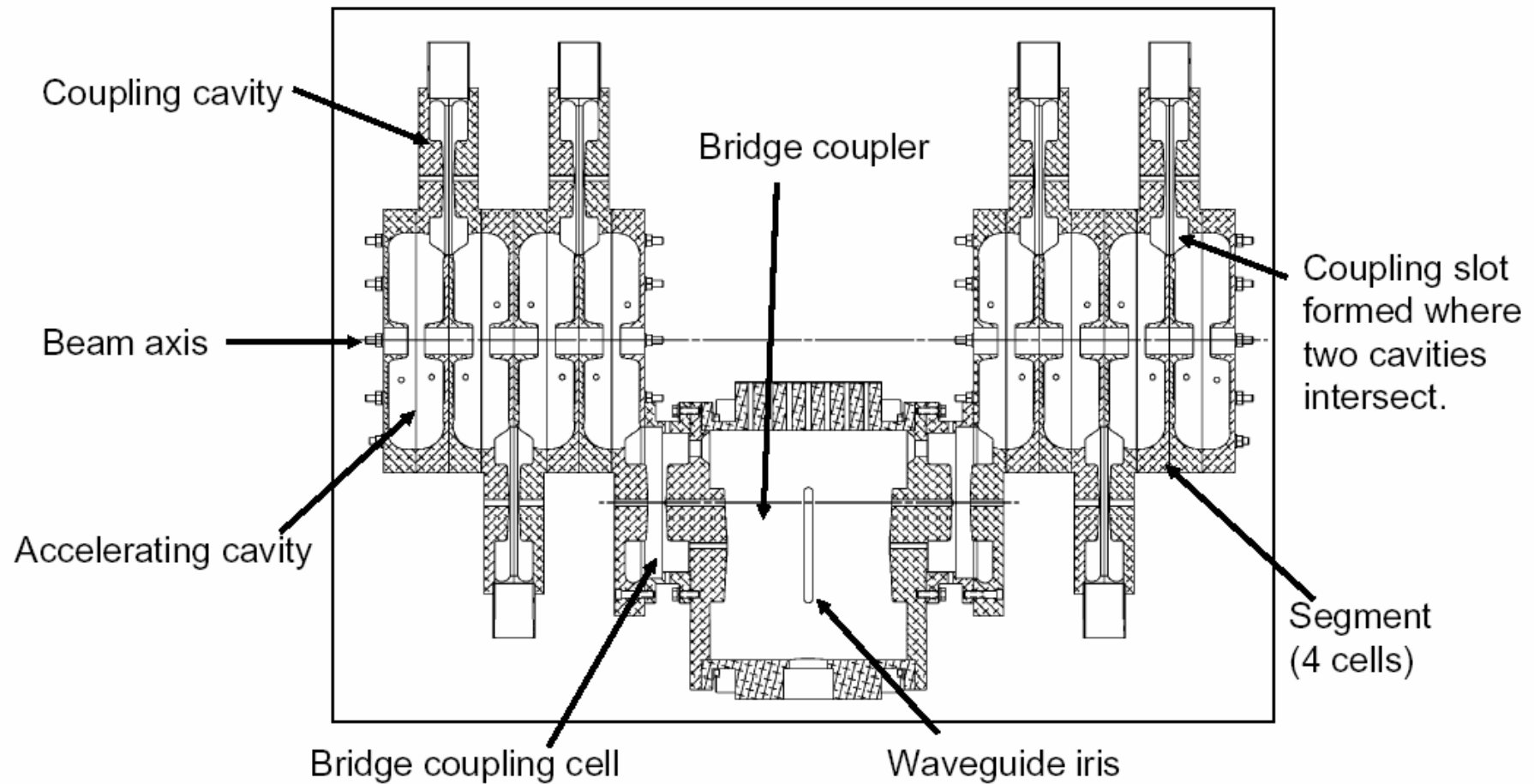
Input energy:	2.5 MeV
Output energy:	86 MeV
Peak current:	38 mA
Number of tanks:	6
Total number of cells:	216
Total length:	36 m
RF frequency:	402.5 MHz
Synchronous phase:	-37° to -26°

Coupled-Cavity Linac (CCL)

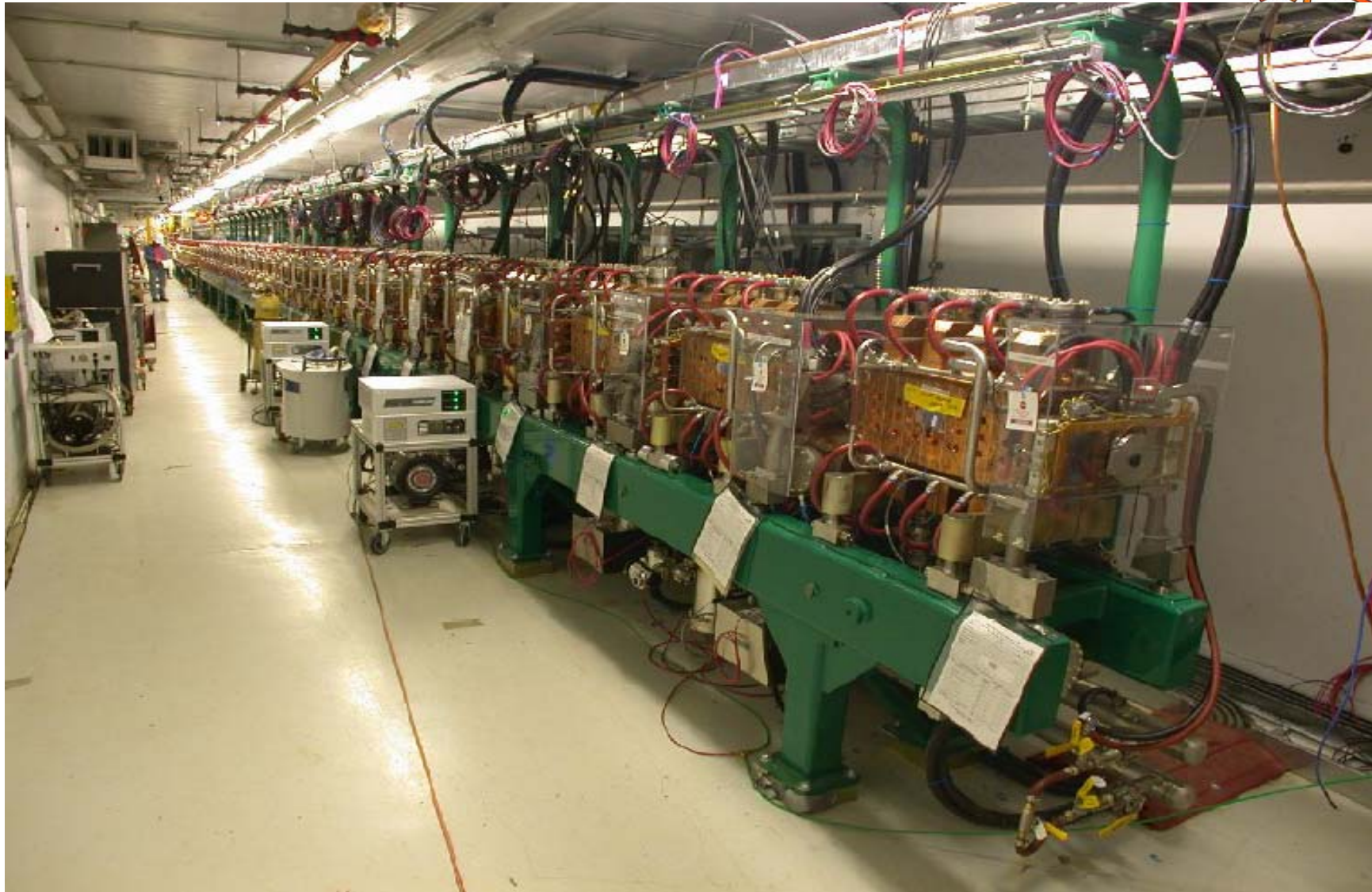


- At higher β drift tubes in DTL become too long and large part of accelerator length is “wasted” for drifting in the tube. Need more efficient structure
- If use separate cavities than field in adjacent cells need not be in phase
- The **coupled-cavity linac** (CCL) consists of an array of single-gap cavities or cells, that are electromagnetically **coupled** together to form a **multi-cell accelerating structure**.
- Main motivation for coupling: we want long multi-cell accelerating structures that can be driven by a single high power generator.

The SNS CCL cells



The SNS CCL in the tunnel



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The SNS CCL parameters



Input energy:	86 MeV
Output energy:	186 MeV
Peak current:	38 mA
Number of tanks:	4
Total number of cells:	386
Total length:	55 m
RF frequency:	805 MHz
Synchronous phase:	-30° to -28°

Super Conducting Linac (SCL)



- CCL accelerating structure is suitable for acceleration up to relativistic energies. Why need another one?
- Disadvantages of copper (normal temperature or warm) linacs:
 - Large rf power dissipation results in
 - 1) High cost of RF system
 - 2) High operating costs for AC power
 - 3) Cooling requirement can limit accelerating gradient
- Example: RF power budget for the SNS CCL module

$$P_{generator} = P_{wall} + P_{beam} = 2.2MW + .52MW$$

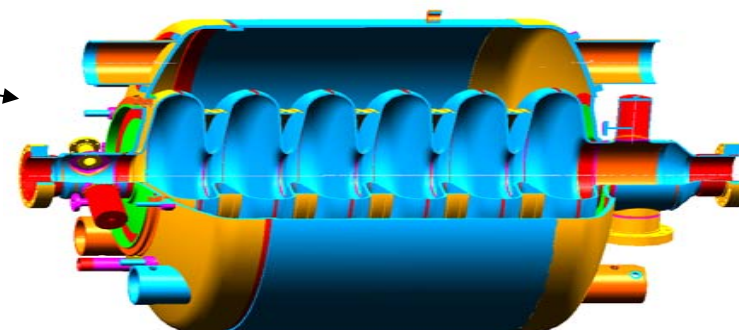
- Significant reduction of resistive losses due to use of superconducting material for cavity walls eliminates warm linac disadvantages.
- There is price to pay:
 - Must operate linac at cryogenic temperature (2-4 K)
 - Must maintain ultra clean environment during cavity manufacture, handling and operation

The SNS superconducting cavity



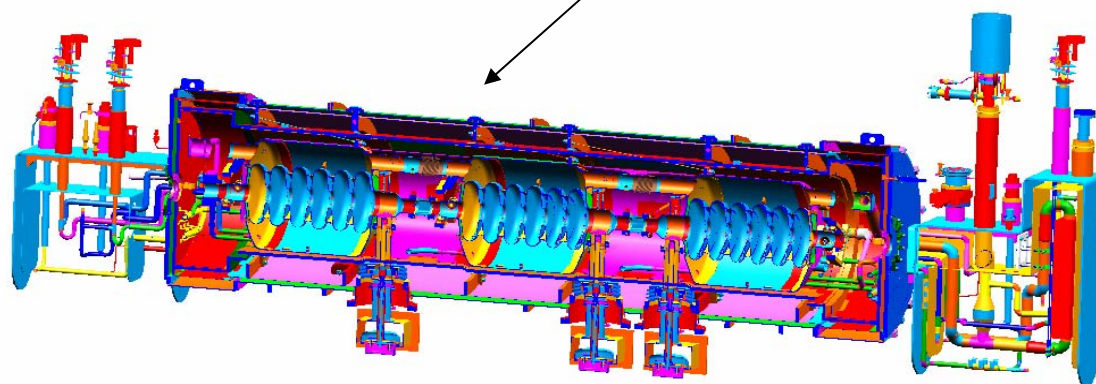
Material:	niobium (NB)
Operating frequency	805MHz
Number of cells per cavity	6
Operating temperature:	2.1K
Number of cavities	33 (b=.61) + 48 (b=.81)
Total length	157 m
Total energy gain	814 MeV

Cavities are contained in a Helium Vessel



Vessels are assembled into a String

String is placed in a cryomodule (11 +12 cryomodes)



The SNS SCL in the tunnel



- Quadrupole magnets for transverse focusing are between the cryomodules (warm sections)
- Beam diagnostics are in the warm sections

Cryogenic plant



➤ All cryomodules are cooled by liquid He from the cryo-plant (huge helium liquefaction station; ~2.4kW at 2.1K)

➤ 1W at 2.1K approximately equivalent to 1kW at 300K



High Power RF Generators



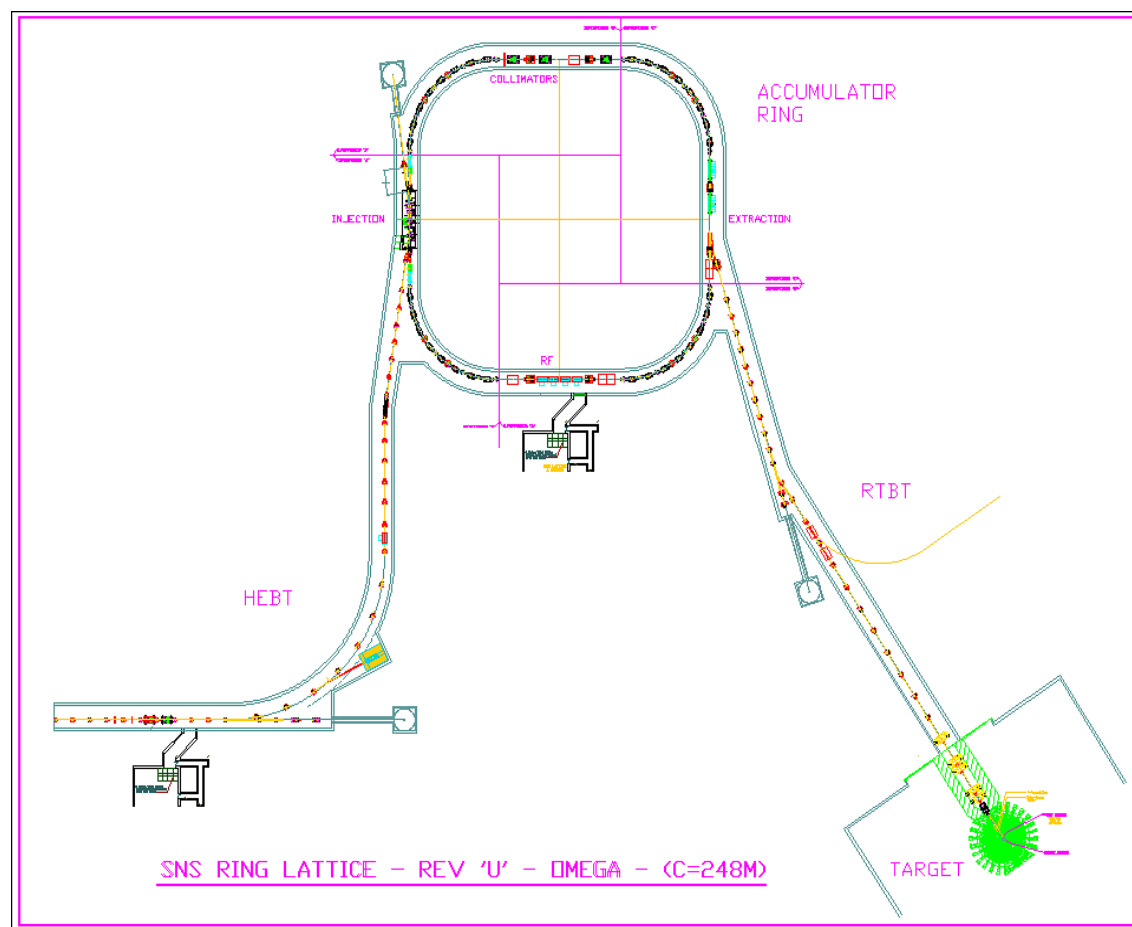
Warm linac: 7 – 2.5MW, 4 – 5MW klystrons

Super Conducting Linac: 81 - .5MW klystrons

The SNS Accumulator Ring

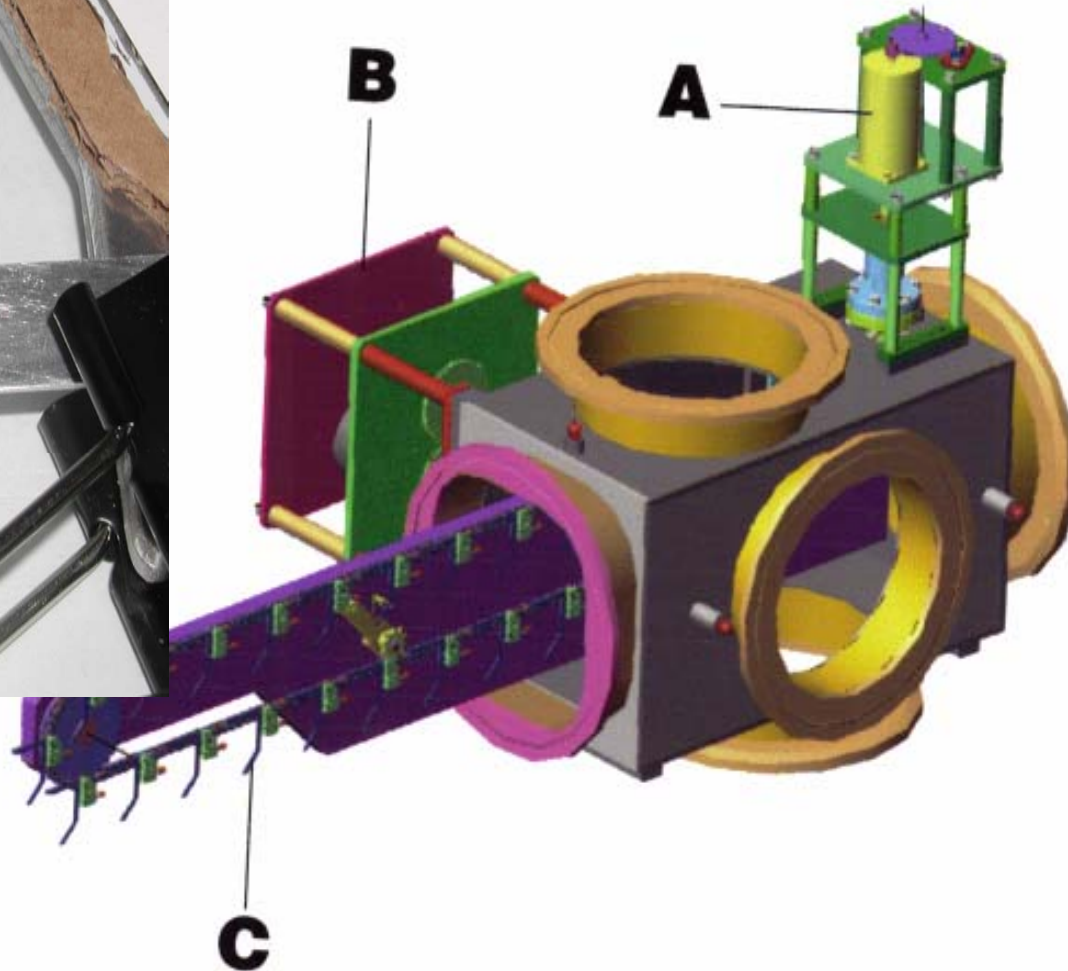


Circumference	248 m
Energy	1 GeV
Revolution period	1 μ s
Number of turns	1060
Final Intensity	1.5×10^{14}
Peak Current	52 A
Number of magnets (bend and focusing)	>300



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Injection foil and exchange mechanism



The SNS Ring in the tunnel



Quadrupole
Magnet (focuses
the beam)

Corrector
magnet (steers
the beam)

Dipole Magnet
(bends the
beam)



Ring to target transfer line and target



Rad hard quadrupole magnets

The SNS mercury target



The SNS cost breakdown



WBS	Description	November 2003 Review Baseline (\$M)	Net Forecast Changes (\$M)	Management EAC (\$M)
	1.2 Project Support	75.6	0.3	75.9
	1.3 Front End Systems	20.8	-	20.8
	1.4 Linac Systems	313.2	1.4	314.6
	1.5 Ring and Transfer Systems	141.2	0.9	142.1
	1.6 Target Systems	106.5	1.6	108.1
	1.7 Instrument Systems	63.3	0.0	63.3
	1.8 Conventional Facilities	367.5	9.4	376.9
	1.9 Integrated Controls	59.6	(0.0)	59.6
BAC		1,147.9	13.5	1,161.4
Total Contingency		44.8		31.3 21.8%*
	TEC	1,192.7		1,192.7
	OPC	219.0		219.0
	TPC	1,411.7		1,411.7

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Challenges of Accelerator for Spallation Source Design



- Accelerator physics
 - To ensure small beam loss during acceleration and transport. Typical requirement is $<1\text{W/m}$ ($<1\text{ppm}$ at 1GeV)
 - To provide required current from the source
 - To provide reliable stripping foil
- Operation
 - To provide personnel protection and accelerator protection in case of an accident
 - To provide high reliability and availability of all systems. Typical requirement is $>95\%$
- Economics
 - To optimize construction and operation cost
- Technical
 - Numerous

The SNS is the first pulsed spallation source of megawatt class and the first pulsed superconducting linac ever build - will provide many lessons to learn