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"8th Workshop on Three-Dimensional Modelling of Seismic Waves Generation, Propagation and their Inversion"

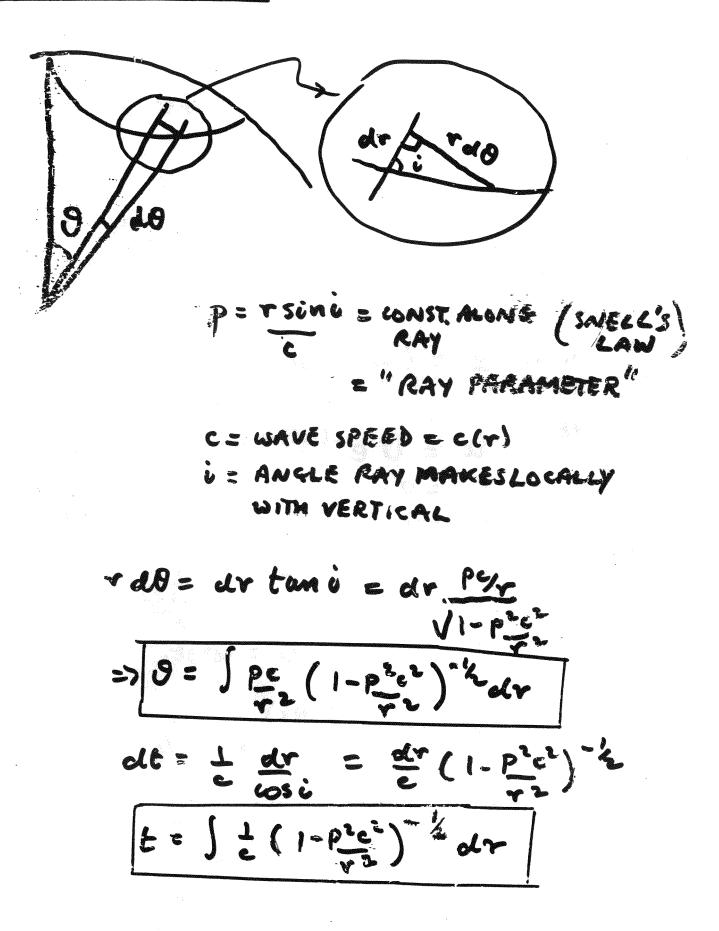
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RAY THEORY (Overheads)

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CLASSEAL RAY THEORY



EQUATION OF MOTION AND PLANE

WAVE SOLUTIONS :

tij = püi tij = STRESS TENSOR

 $t_{ij} = \mu (u_{i,j} + u_{j,i}) + \lambda u_{R,R} S_{ij}$

ISOTROPIC HOOKE'S LAW

PLANE WAVE SOLUTIONS: CONSIDER WAVE TRAVELLING IN X-DIRECTION WRITE U = (U, J, W)

$$\frac{P-\omega_{A}vE}{\omega} = U e^{i(\omega t - kz)}$$

$$\frac{\sigma}{\omega} = 0$$

$$\frac{\omega}{\omega} = 0$$

$$\frac{\omega}{\omega} = \frac{\omega}{\omega}$$

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WHAT IS THE ENERGY FLUX?

WE NEED TO FIND THE RATE OF WORKING
OF ONE SIDE OF A PLANE
$$L^{x}$$
 x-axis on
THE OTHER.
LET $\underline{\Omega}$ be a unit vector in x-direction
 $\underline{\Omega} = (1, 0, 0)$
Traction = $t_{i} = t_{ij} n_{j} ds$
where $ds =$ element of area
Rate of working = $t_{ij} n_{j} ds \dot{u}_{i}$ (force x velocity)
P-wave
 $T_{XX} = (\lambda + 2\mu) ik U e^{i(\omega t - kx)}$
Energy flux = $Re \{(\lambda + 2\mu) ik U e^{i(\omega t - kx)}\}$
 $\times Re \{i \omega U e^{i(\omega t - kx)}\}$
 $\Rightarrow ENERGY FLUX AVERAGED OVER A cycle
 $= \frac{1}{2} |U|^{2} wk (\lambda + 2\mu)$
 $= \frac{1}{2} |U|^{2} w^{2} \rho d$$

UNITS: ENERGY PER UNIT TIME PER UNIT AREA. S-WAVE SIMILARLY $T_{xy} = \mu ik V e^{i(\omega t - kx)}$ Energy flux = $Re \{ \mu ik V e^{i(\omega t - kx)} \}$ $\times Re \{ i \omega V e^{i(\omega t - kx)} \}$ <u>ENERGY FLUX AVERAGED OVER A CYCLE</u> $= \frac{1}{2} |V|^2 \omega k \mu$ $= \frac{1}{2} |V|^2 \omega^2 \rho \beta$

ASYMPTOTIC THEORY

1- DIMENSIONAL CASE

THE BASIC IDEN OF THE ASYMPTOTIC OR RAY THEORIES IS THAT IN MEDIA IN WHICH THE WAVE VELOCITIES AND DENSITY VARY SCOWLY WAVES PROPAGATE IN MUCH THE SAME WAY AS IN HOMOGENEOUS MEDMA.

CONSIDER A P-WAVE PROPAGATING IN THE X-DIRECTION IN A MEDIUM IN WHICH DENSITY AND P-WAVE SPEED ARE ALSO FUNCTIONS OF X. WAVE EQUATION:

$$\frac{\partial}{\partial x} (1+2\mu) \frac{\partial u}{\partial x} = \rho \frac{\partial^2 u}{\partial E^2}$$
ie.
$$\frac{\partial}{\partial x} \left(\rho d^2 \frac{\partial u}{\partial x} \right) = \rho \frac{\partial^2 u}{\partial E^2} \qquad \rho = \rho(x)$$

$$\frac{d}{\partial E^2} \qquad d = d(x)$$
SEEK AN APPROXIMATE SOLUTION OF THE
FORM
$$\frac{u(x,t) = U(x)}{U = U(x)} e^{i\omega(t - \partial(x))}$$

$$\frac{U = U(x)}{U = U(x)}, \quad \partial = \partial(x) \quad \text{To BE DETERMINED}.$$

$$\frac{\omega}{\omega} \text{ is considered to be A LARGE PARAMETER}$$

SUBSTITUTING, WE FIND

 $\frac{\partial u}{\partial x} = \left(-i\omega \frac{\partial \theta}{\partial x} U + \frac{\partial U}{\partial x} \right) e^{i\omega(t-\theta)}$ $\frac{\partial}{\partial x} \left(\rho \alpha^{2} \frac{\partial u}{\partial x} \right) = \left\{ -\omega^{2} \rho \alpha^{2} \frac{U(\partial \theta)^{2}}{\partial x} \right\}$ $-i\omega \frac{\partial \theta}{\partial x} \frac{\partial U}{\partial x} \rho \alpha^{2}$ $-i\omega \frac{\partial}{\partial x} \left(\frac{\partial \theta}{\partial x} U \rho \alpha^{2} \right) + \cdots \right\} e^{i\omega(t-\theta)}$

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where ... indicates terms of lower order in w

THUS, FROM ω^2 terms: $\left(\frac{\partial \theta}{\partial x}\right)^2 = \frac{1}{\alpha^2}$ EQUATION FOR THE PHASE $\partial \omega$ $\left[EIKONAL\right]$ EQUATION

AND FROM WI TERMS

$$\frac{\partial \Theta}{\partial x} \frac{\partial U}{\partial x} p \chi^2 + \frac{\partial}{\partial z} \left(\frac{\partial \Theta}{\partial x} U p \chi^2 \right) = 0$$

ie
$$\frac{\partial}{\partial x} \left(\frac{\partial \theta}{\partial x} \right)^2 \rho \alpha^2 = 0$$

ie $\frac{\partial}{\partial x} \left(\frac{\partial^2 \rho \alpha^2}{\partial x} \right)^2 = 0 = 0$ $\equiv CONSTANT ENERGY$
 $FLUX$

3-D THEORY - WORKS SIMILARLY

(KARAL & KELLER, J. Acoust. Soc. Am., <u>31</u>, 694, 1959) SEEK ASOLUTION OF EQNS. OF MOTION IN FORM $u_i = U_i(z, y, z) e^{i\omega(t - \Theta(x, y, z))}$ substitute into equation of motion, identify leading purers of $\omega(\omega^2)$. DETAILS ARE COMPLEATED.

WE FIND THAT EITHER

$$\Theta_{ji} \Theta_{ji} = \frac{1}{\alpha^2} \qquad \text{with } U_i \parallel \Theta_{ji}$$

$$OR$$

$$\Theta_{ji} \Theta_{ji} = \frac{1}{\beta^2} \qquad \text{with } U_i \perp^r \Theta_{ji}$$

THUS WE GET TWO KINDS OF SOLUTION, CORRESPONDING TO P-WAVES AND TO S-WAVES THUS, IN BOTH CASES WE OBTAIN FOR

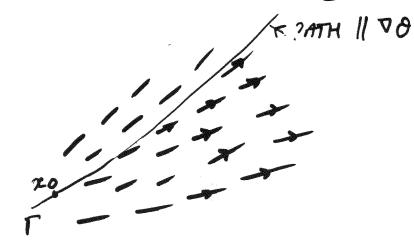
THE "TRAVELTIME" O(=) AN EQUATION

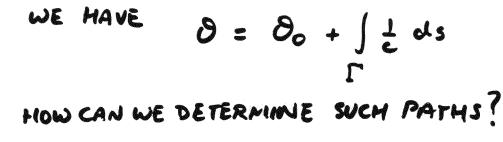
OF THE FORM

$$(\nabla \theta)^2 = \frac{1}{c^2}$$
 EQUATION

WHERE C=& FOR P.WAVES, OR C=B FOR S-WAVES.

IMAYINE A PATH EVERYWHERE 11 TO VO





$$2 \Theta_{i} \Theta_{i} = \frac{\partial}{\partial x_{j}} \begin{pmatrix} 1 \\ c^{2} \end{pmatrix}$$

ie. 2 ∂_{i} , ∂_{j} ; $= \frac{\partial}{\partial x_{j}} \left(\frac{1}{c^{2}} \right)$ but Osi is parallel to 5 ie

$$\Theta_{,i} = \frac{1}{c} \frac{dx_i}{ds} \qquad (A)$$

$$\therefore \quad \frac{2}{c} \frac{d\theta_j}{ds} = \frac{\partial}{\partial x_j} \left(\frac{1}{c^2}\right)$$

$$or \quad \frac{d\theta_j}{ds} = \frac{c}{2} \frac{\partial}{\partial x_j} \left(\frac{1}{c^2}\right) = \frac{\partial}{\partial x_j} \left(\frac{1}{c}\right)$$

$$(B)$$
Thus: FRAM (A) 4(B)

THUS, FROM (A) Q(3)

$dx_i =$	c 8, i	
ds		
d.0,; =	2 (1)	
ds	dri (c)	

RAY-TRACING FOUATIONS

ALTERNAIVELY, WRITING

$$\frac{d}{ds} = \frac{1}{c} \frac{d}{d\theta}$$
$$\frac{d}{d\theta} = \frac{1}{c} \frac{d}{d\theta}$$
$$\frac{d}{d\theta} = \frac{1}{c} \frac{d}{d\theta}$$

WE GET

$$dx_{i} = c^{2}k_{i} = ck_{i}$$

$$dk_{i} = \omega c \frac{\partial}{\partial x_{i}} \left(\frac{1}{c}\right) = -\frac{\omega}{c} \frac{\partial c}{\partial x^{i}} = -k\frac{\partial}{\partial x^{i}}$$

$$\frac{\partial k_{i}}{\partial \theta} = \omega c \frac{\partial}{\partial x_{i}} \left(\frac{1}{c}\right) = -\frac{\omega}{c} \frac{\partial c}{\partial x^{i}} = -k\frac{\partial}{\partial x^{i}}$$

$$\frac{\omega}{\partial x_{i}}$$

$$\frac{\partial k_{i}}{\partial x_{i}} = ck_{i}$$

$$k_{i} = -k\frac{\partial}{\partial x_{i}}$$

THESE REPRESENT THE MOTION OF A "PARTICLE" TRAVELLANG AT THE LOCAL WAVE SPEED C, SUFFERING DEFLECTIONS FROM A STRAIGHT-LINE TRASECTURY DUE TO VELOCITY GRADIENTS THAT ARE NOT 11 TO THE PATH 9

A GENERAL WAY OF UNDERSTANDING THE RAY EQUATIONS IS THROUGH THE CONCEPT OF THE LOCAL DISPERSION RELATION BY WHICH WE SHALL MEAN THE RELATION BETWEEN FREQUENCY W (=2TT/PERIOD) AND WAVE-VECTOR R ($|k| = 2\pi/WAVELENGTH$). THE WAVE VECTOR FOR A WAVE OF THE FORM i(wt - 4(E))U C

CAN BE DEFINED AS $k_i = \frac{\partial 4}{\partial x_i}$

THE LOCAL DISPERSION RELATION IS THEN GIVEN BY A FUNCTION $\omega(k;, x;),$ so the PHASE $\Psi(x)$ satisfies an EQUATION OF THE FORM

$$\omega = \omega(\frac{\partial \Psi}{\partial x_i}, x_i)$$

THE METHOD OF CHARACTERISTICS (ESSENTIALLY

THE METHOD GIVEN ABOVE) THEN LEADS TO HAMILTON'S EQUATION GIVEN A LOCAL DISPERSION RELATION

 $\omega = \omega(\mathbf{k}; \mathbf{z}; \mathbf{z})$

THE RAY EQUATIONS ARE

$$\dot{x}_{i} = \frac{\partial \omega}{\partial k_{i}}$$
$$\dot{k}_{i} = -\frac{\partial \omega}{\partial x_{i}}$$

cf. HAMILTON'S EQNS. FOR A MECHANICAL SYSTEM: GIVEN THE HAMILTONIAN H(Pi, qi)THE EVOLUTION OF THE SYSTEM IS GOVERNED BY $\dot{q}i = \partial H$ ∂Pi $p_i = - \partial H$ ∂q_i $P_i = "GENERALISED$ MOMENTAGE" LET US USE THIS IDEA TO RE-DERIVE THE RAY EQUATIONS. THE LOCAL DISPERSION RELATION IS OF THE SIMPLE FORM $W = c(\underline{z})|\underline{k}|$

FOR BODY WAVES IN AN ISOTROPIC MEDIUM $(c = \alpha \quad or \quad c = \beta)$ ie $w = c(x)(k:k:)^{\frac{1}{2}}$

 $\therefore \text{ HAMILTON'S EQUATIONS GIVE}$ $\dot{x}_{i} = c \underbrace{k_{i}}_{R}$ $\dot{k}_{i} = - \underbrace{k}_{2} \underbrace{dc}_{2}$ $k_{i} = - \underbrace{k}_{2} \underbrace{dc}_{2}$ EARLIER $WITH \underbrace{k}_{i} = (\underbrace{k_{i}}_{i} \underbrace{k_{i}}_{i}) = 1\underbrace{k}_{i}$

LET US WRITE VOWN RAY EQUATIONS FOR AN ANISOTROPIC MEDWM.
WE MAVE
$(c_{ijkl} U_{k,l})_{jj} + \omega^2 u_i = 0$
\Rightarrow -ik; cijks (-ikg) UK + ω^2 Ui:0
ie (Cijke ke kj $-\omega^2 \delta_{ik}$) $u_k = 0$
THUS THE LOCAL DISPERSION RELATION
15 Det (Cijkekek; -w² Sik) = 0
THE DERIVATIVES DW, DW CAN BE DR: DK:
FOUND FROM STANDARD PERNRIATION
THEORY (RAYLEIGH'S PRINCIPLE)
WEFND
WE FIND $R_{m} = -\frac{\partial \omega}{\partial x_{m}} = -\frac{1}{2\omega} \frac{\partial C_{ijkl}}{\partial x_{m}} \forall i \ U_{k} \ k_{l} \ k_{j}$
$\dot{x}_{m} = \frac{\partial \omega}{\partial k_{m}} = \frac{1}{2\omega} \left(\operatorname{Cijkm} k_{j} + \operatorname{Cimke} k_{e} \right) \sigma_{i} \sigma_{k}$
where vi is a (local) unit eigenvector (CORRESPONDING TO THE WAVE OF INTEREST)

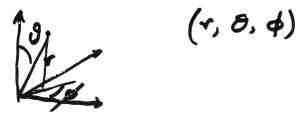
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ANOTHER ELEGANIT PROPERTY OF HAMILTON'S EQUATIONS IS THAT THEY CAN BE WRITTEN DOWN IN ANY COORDINATE SYSTEM

SUPPOSE THAT WE WATNT TO DO 3-D

RAY TRACING IN SPHERICAL CUURDINATES



We have
$$k_r = \frac{\partial 4}{\partial r}$$
, $k_\theta = \frac{\partial 4}{\partial \Theta}$, $k_{\chi} = \frac{\partial 4}{\partial \varphi}$
and $k = \left(k_r^2 + \frac{1}{r^2}k_{\Theta}^2 + \frac{1}{r^2\sin^2\theta}k_{\varphi}^2\right)^{1/2}$

with the usual dispersion relation

$$\omega = c(r, 0, \phi) \mathbf{R}$$

WE OBTAIN RAY-TRACING EQUATIONS:

$$\dot{r} = \frac{krc}{k}$$
$$\dot{\Theta} = \frac{1}{r^2} \frac{k\Theta}{k} \frac{1}{k}$$
$$\dot{\phi} = \frac{1}{r^2 \sin^2 \Theta} \frac{k}{k} \frac{1}{k} \frac{k}{k} \frac{1}{k} \frac{k}{k} \frac{1}{k} \frac{k}{k} \frac{k}{k}$$

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$$\dot{\mathbf{k}}_{\mathbf{r}} = -\frac{\partial c}{\partial \mathbf{r}} \mathbf{k} + \frac{1}{k_{\mathbf{r}}} \left(\frac{1}{r^2} \mathbf{k}_{\mathbf{0}}^2 + \frac{1}{r^3 \sin^2 \mathbf{0}} \mathbf{k}_{\mathbf{1}}^2 \right)$$
$$\dot{\mathbf{k}}_{\mathbf{0}} = -\frac{\partial c}{\partial \mathbf{0}} \mathbf{k} + \frac{\cot \theta}{\mathbf{k} r^2 \sin^2 \theta} \mathbf{k}_{\mathbf{0}}^2$$
$$\dot{\mathbf{k}}_{\mathbf{0}} = -\frac{\partial c}{\partial \mathbf{0}} \mathbf{k} + \frac{\cot \theta}{\mathbf{k} r^2 \sin^2 \theta} \mathbf{k}_{\mathbf{0}}^2$$

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TO MAKE CONTACT WITH CLASSICAL RAY THEORY IN THE SPHERICAL EARTH LET US NOW SIMPLIFY THESE FOR THE CASE C = C(V) TAKE SOURCE AT Q=0, K\$=0

$$\dot{\tau} = \frac{k_{v}c}{k} \qquad \dot{k_{v}} = -\frac{\partial c}{\partial v} k + \frac{1}{k} \frac{k_{0}}{k}$$

$$\dot{\Theta} = \frac{1}{v^{2}} \frac{k_{0}c}{k} \qquad \dot{k_{0}} = 0$$

$$\dot{\phi} = 0 \qquad \dot{k_{1}} = 0$$

$$\omega = c\left(\frac{k_{1}^{2}}{v^{2}} + \frac{1}{v^{2}}\frac{k_{0}^{2}}{v^{2}}\right)^{2} = const$$

$$w_{RITE} \qquad k_{v} = w_{Pv} \qquad k_{0} = w_{P0}$$

$$p_{0} = const \qquad p_{v}^{2} + \frac{1}{v^{2}} p_{0}^{2} = \frac{1}{c^{2}}$$

$$ie \qquad p_{v} = \left(\frac{1}{c^{2}} - \frac{p^{2}}{v^{2}}\right)^{\frac{1}{2}} \qquad (P = p_{0})$$

$$= \frac{u}{RAy}$$

$$\frac{1}{v} = \frac{dt}{dv} = \frac{1}{c} \left(1 - \frac{c^{2}p^{2}}{v^{2}}\right)^{-\frac{1}{2}} \qquad PAFAMETER$$

$$\frac{d\theta}{dv} = \frac{\dot{\Theta}}{v} = \frac{p_{v}}{v^{2}} \left(1 - \frac{c^{2}p^{2}}{v^{2}}\right)^{-\frac{1}{2}}$$

THUS WE OBTAIN THE CLASSICAL RAY INTEGRALS

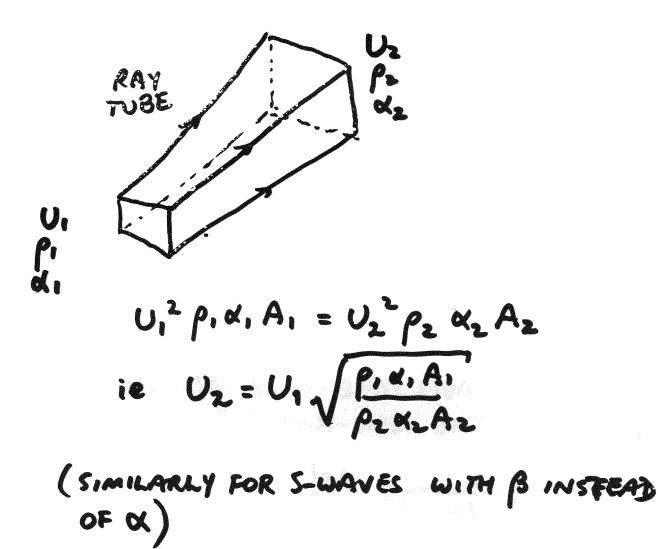
 $t = \int \frac{1}{2} \left(1 - \frac{c^2 p^2}{r^2} \right)^{-\lambda} dr$ $\Theta \left(= 0^{-1} \right)^{-1} = \int \frac{pc}{r^2} \left(1 - \frac{c^2 p^2}{r^2} \right)^{-\lambda} dr$

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AMPLITUDES AND WAVEFORMS

BECAUSE RAY THEORY (FOR BODY WAVES) IS FREQUENCY-INDEPENDENT, IT PREDICTS THAT WAVES PROPAGATE WITHOUT ANY CHANGE TO THE WAVEFORM (JUST AS IN A NOMOGENEOUS MEDIUM) THE ASYMPTOTIC THEORY CAN BE USED TO DERIVE WAVE AMPLITUDES (BY INVESTIGATING THE TERMS & W) THE DERIVATION WILL NOT BE GIVEN HERE (SEE LITERATURE) THE RESULT IS THAT ENERGY FLUX IN A RAY TUBE IS CONSTANT RECALLING THAT ENERGYFLUX of poluz (FOR PWQVES) THIS MEANS THAT RAY AMPLITUDES VARY INVERSELY AS NOW AND ALSO AS 1/VA' WHERE A is the CROSS-SECTIONAL AREA

OF THE RAY TUBE .



TO PERTURBATIONS OF THE PATH

$$E_{i}(s) = NON-RAY$$

$$ds' = RAY$$

$$T' = "TRAVEL TIME CALCULATED ALONG
THE NON-RAY F"
$$= \int \frac{1}{c(x + E)} ds'$$

$$= \int \frac{P(1)}{c(x + E)} ds' + \int \frac{1}{c} \frac{ds'}{ds} ds + O(e^{2})$$

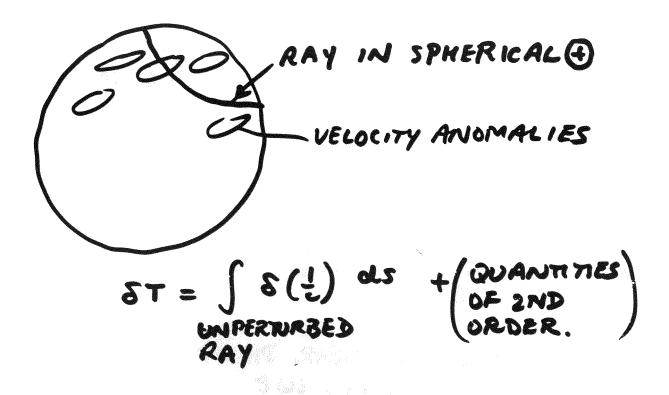
$$But ds' = \int \frac{d}{ds} (x_{i} + E_{i}) \frac{d}{ds} (x_{i} + e_{i}) \int \frac{1}{2} dx$$

$$= 1 + dx \cdot dE$$

$$ds = \int \frac{1}{c} ds + \int \left(\frac{P(1)}{c} \cdot \frac{e}{cs} + \frac{1}{cs} \frac{dx}{ds}\right) ds$$

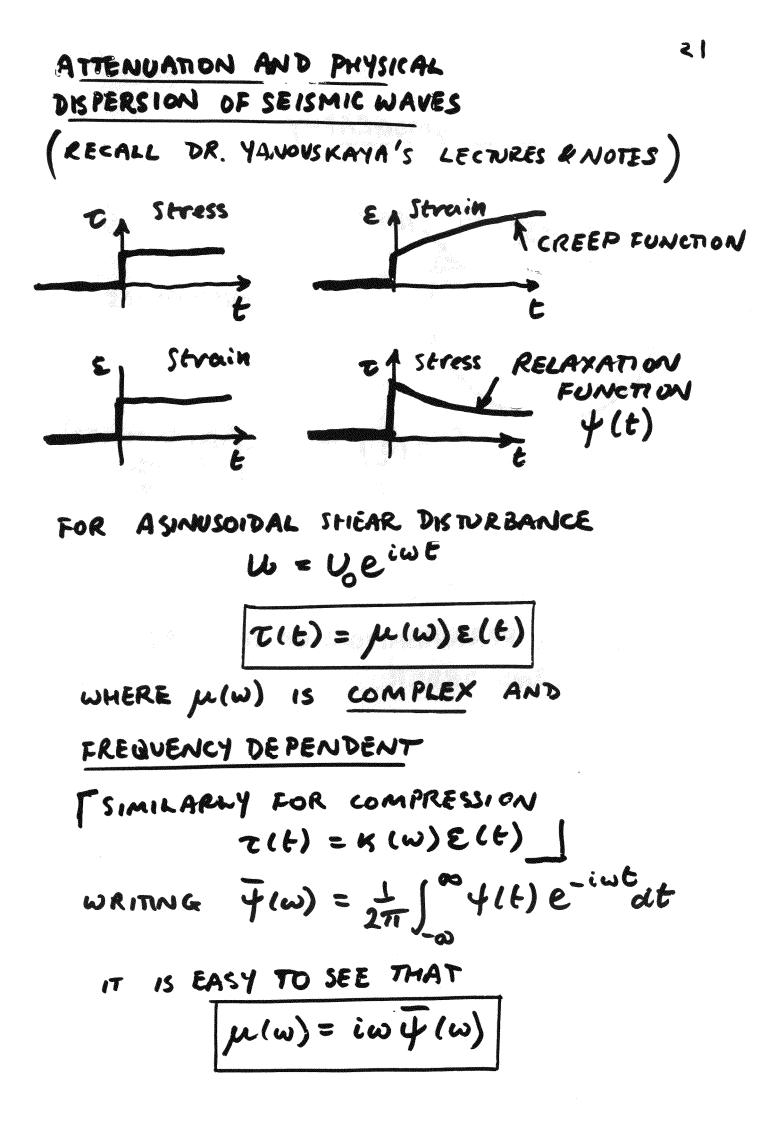
$$= T + \int \left(\frac{P(1)}{c} + \frac{d}{cs} + \frac{1}{cs} \frac{dx}{ds}\right) \cdot e ds$$

$$+ \left[\frac{1}{c} \frac{dx}{ds} \cdot E\right]^{S_{i}} = T + O(e^{2})$$$$



NOTE THAT IT IS NOT TRUE

THAT THE PERTURBATION OF THE RAY PATH IS 2ND ORDER.



IT IS CONVENTIONAL TO DEFINE

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BUT OFTEN MURE CONVENIENT TO USE

$$Q_{\mu}(\omega) \equiv \frac{1}{Q_{\mu}(\omega)} \ll 1$$

Writing

$$\frac{1}{J_{s}} = \sqrt{\frac{1}{\mu(w)}} = s_{1} - is_{2}$$

$$\approx Re(1)(1 - 1)(q_{1})$$

Thus THE EXPRESSION FOR A PLANE
WAVE TRAVELLING IN THE
$$\times - \exists reschown
is of the form
 $u \sim U_0 e^{i\omega(t-x/v_s)}$
 $= U_0 e^{-\omega x s_2} e^{i\omega(t-x s_1)}$
with $s_2 = Re(\frac{1}{s_1}) \cdot \frac{1}{2} q_{\mu}$
 $\exists ECAY IN ONE WAVELENGTH
 $exp\{-\omega \frac{2\pi}{\omega s_1}, \frac{1}{2} q_{\mu} s_1\} = exp(-\pi q_{\mu})$$$$

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AMPLITUDE DECAY FOR S-WAVE $= e^{-\pi/Q_{ph}} PER CYCLE$ $\frac{Q_{ph}}{Q_{ph}} IS ALSO SOMETIMES DENOTED BY$ $\frac{Q_{ph}}{Q_{ph}} (= Q FOR S-WAVES)$

CORRESPONING LY

where
$$Q_{\alpha} \equiv \frac{-2Re(1)\sigma_{\beta}}{Im(1)\sigma_{\beta}}$$

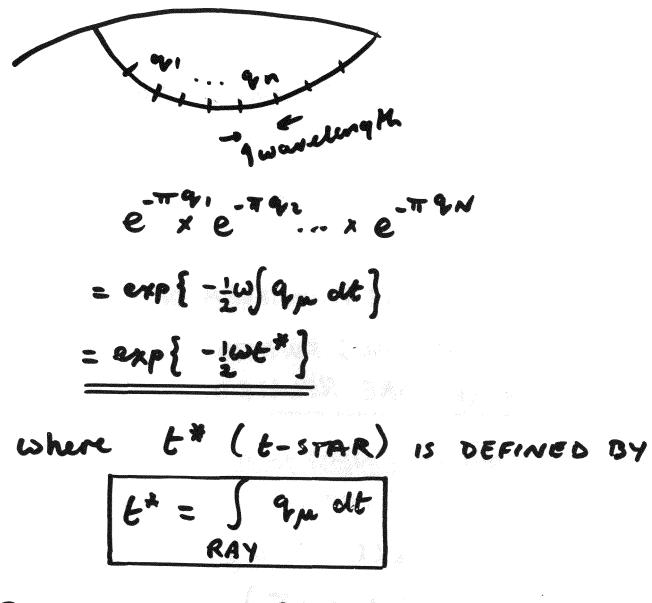
$$K = (ReK)(I + iq_K)$$
 etc.

SO IT IS EASY TO FIND EXPRESSIONS FOR Q_K IN TERMS OF Q_K, Q_M. IN PARTICULAR IF Q_K = 0 (USUALLY A FAIR ASSUMPTION) WE OBTAIN

$$q_{x} = \frac{4}{3} \frac{\sigma_{x}^{2}}{\sigma_{p}^{2}} q_{p}$$

WITHIN RAY THEORY THIS LEADS

TO AN ADDITIONAL AMPLITUDE DECAY



[NOTE STRONG DAMPING OF HIGH FREQUENCY WAVES] PHYSICAL DISPERSION

WE SAW THAT

$$\mu(\omega) = i\omega \overline{\Psi}(\omega)$$

WHERE $\overline{\Psi}(\omega) = F.T.$ OF RELAXATIONS FUNCTION
 $\psi(t)$
WAVE VELOCITY $(\sqrt{5})$ IS RELATED TO
Re(μ) AND DAMPING TO Jm (μ).
BUT SINCE $\mu(\omega)$ IS THE TRANSFORM OF
A SINGLE REAL (CAUSAL) FUNCTION
Re(μ) AND Im (μ) ARE RELATED.

EG. FOR THE STANDARD LINEAR SOLID (SEE "WAVE PROPAGATION" NOTES FROM DR. YANOUSKAYA)

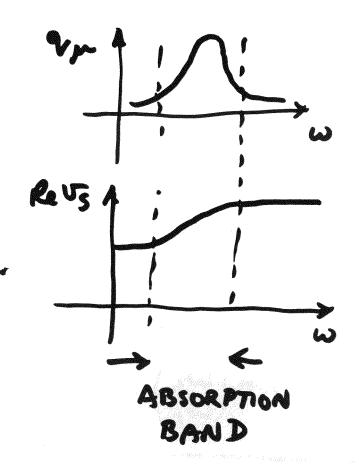
$$\tau + T_{\tau} \dot{\tau} = \mu_{0} (\varepsilon + T_{\varepsilon} \dot{\varepsilon})$$

$$\Rightarrow \quad \mu(\omega) = \mu_{0} (1 + i\omega T_{\varepsilon})$$

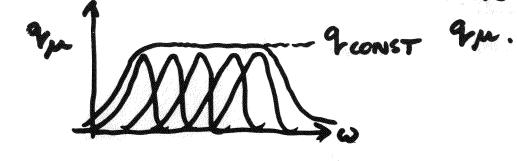
$$\frac{1}{1 + i\omega T_{\tau}}$$

This can be used to find both
$$q_{\mu}(\omega)$$

AND $U_{S}(\omega) = Re \sqrt{\frac{\mu(\omega)}{\rho}}$



THUS VS INCREASES THROUGH THE ABSORPTION BAND. FOR MANY ABSORPTION BANDS US INCREASES THROUGHOUT THE RANGE OF CONSTANT





QUANTITIVELY IT CAN BE SHOWN THAT APPROXIMATELY, AND WITHIN THE BAND OF CONSTANT Q,

d	ln	Us	æ		QUA CONST
d	ln	69		78	

OR (INTEGRATING) FOR WI, WITHIN THE BANG

	Je (wz)			1	CON Q	$\left(\begin{array}{c} \omega_{2} \\ \omega_{2} \\ \omega_{3} \end{array}\right)$	
ln	and the second s	(w,)	*	R	Vµ		(1)

THESE LEAD TO A RELATIONSHIP BETWEEN THE DELAY OF AWAVE OF GIVEN FREQUENCY AND 2T'S DECAY. -THE PHENOMENON IS KNOWN AS PHYSICAL DISPERSION

[SEE LIU, ANDERSON, KANAMORI, GJ. 1976 AND REFERENCES CITED THEREIN] WE CAN ALSO WRITE FOR THE COMPLEX VELOCITY

$$\mathcal{V}(\omega) = \mathcal{V}_0 \left(1 + \frac{\alpha}{\pi} \ln \frac{\omega}{\omega_0} + \frac{1}{2} iq \right)$$

WHERE UTO IS THE (REAL) VELOUTY AT REFERENCE FREQUENCY WO

CONSEQUENTLY THE EFFECT ON THE SIGNAL IS REPRESENTED BY

$$exp\left\{-\frac{1}{2}\omega t^{*}\left(1-\frac{2\omega}{\pi}\ln\frac{\omega}{\omega_{0}}\right)\right\}$$

THIS REPRESENTS (APPROXIMATELY, AND ASSUMING THAT THE ENTIRE SIGNAL IS WITHIN THE CONSTANT Q.M. BAND) THE TOTAL AFFECT OF ATTENUATION ON THE SIGNAL.