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School on Nonlinear Differential Equations | (smr 1777)

Monday 23 October 2006

Subriemannian techniques in Robotics, the Motion Planning Problem - I - Main Building

Main Lecture Hall (14:00-15:00)

time	title	presenter
14:00	Subriemannian techniques in Robotics, the Motion Planning Problem - I	J-P. GAUTHIER