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**Long Memory Processes**

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# Long Memory Processes

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# Outline

1. Brief Introduction
2. Definition of Long Memory Processes
3. Relation between Long Memory and Self-Similar Processes
4. Short overview of the methods to detect long memory
5. An example with real data

# Introduction

A great challenge in modern times is the construction of predictive theories for non-linear dynamical systems for which the evolution equations are barely known, if known at all.

The more dependence there is between  $X_{n+k}$  and the past values  $X_n, X_{n+1}, \dots$  the better  $X_{n+k}$  can be predicted.

Stochastic process may be used to model the behavior of an observed time series in a purely statistical way, without a direct physical interpretation of the parameters.

**Definition** Let  $X_t$  be a stochastic process with finite mean  $\mu = E[X_t]$  and variance  $\sigma^2 = E[(X_t - \mu)^2]$ , the autocorrelation between  $X_i$  and  $X_j$  is defined as

$$\rho(i, j) = \frac{\gamma(i, j)}{\sigma^2} \quad (1)$$

where  $\gamma(i, j)$  is the autocovariance between  $X_i$  and  $X_j$  and is defined as

$$\gamma(i, j) = E[(X_i - \mu)(X_j - \mu)] \quad (2)$$

In the following we will indicate  $\rho(i, i + k)$  as  $\rho(k)$ .

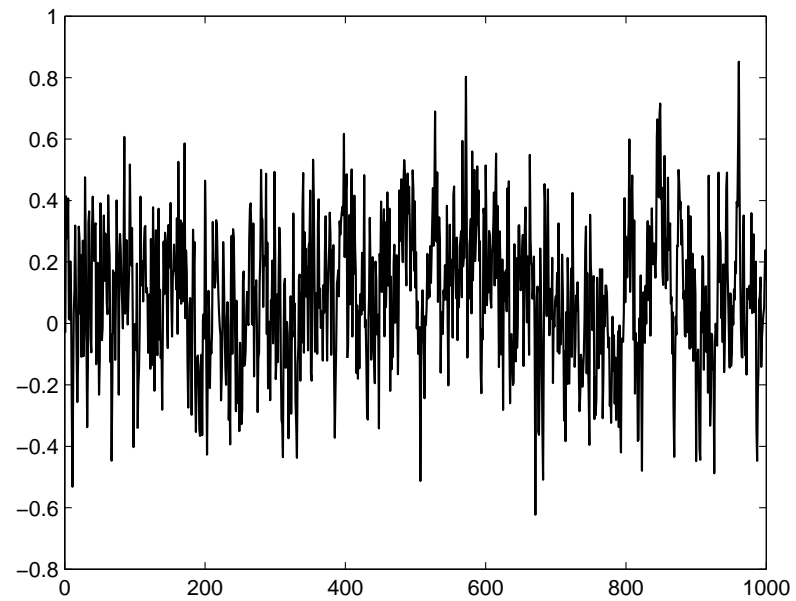
**Definition** The spectral density for the same stochastic process  $X_t$  is defined as

$$f(\lambda) = \frac{\sigma^2}{2\pi} \sum_{k=-\infty}^{\infty} \rho(k) e^{ik\lambda} \quad (3)$$

# Stationary processes with long memory

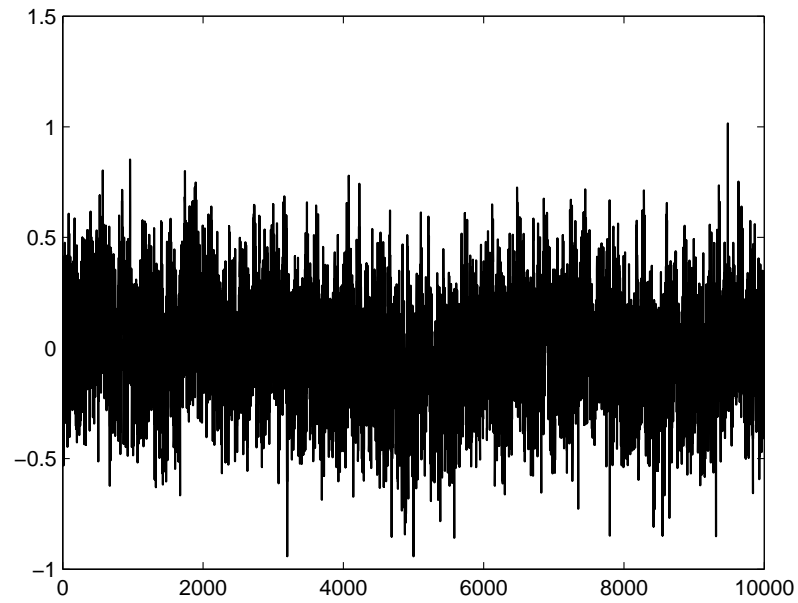
## A. Qualitative features:

1. There are relatively long periods where the observations tend to stay at high (low) level
2. Looking only at short time periods, there seems to be cycles/trends. However, looking at the whole time series, there is no apparent persisting cycles/trend.
3. Overall the series look stationary



A simple example of fractional noise with  $H=0.8$

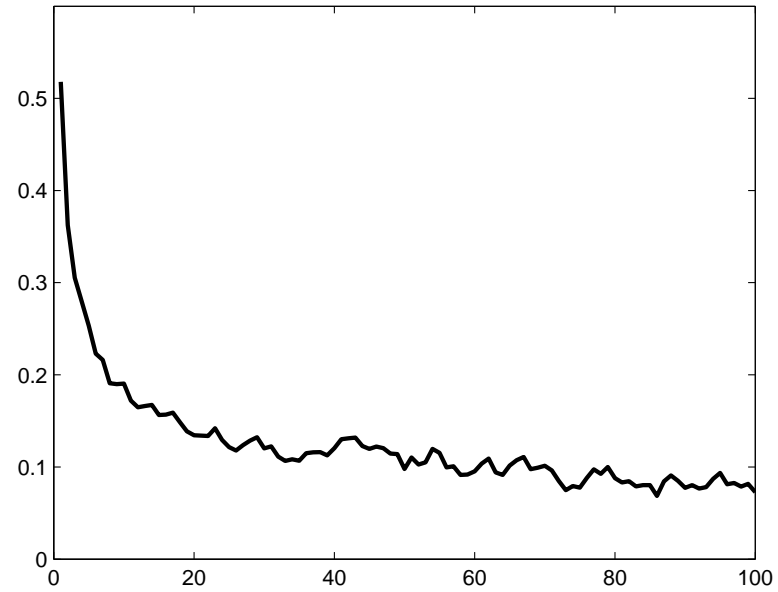




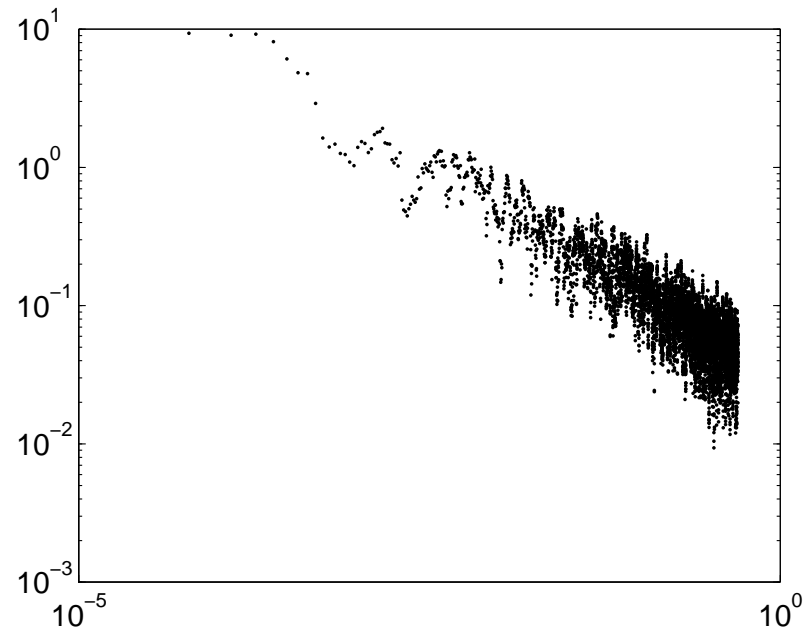
Same as before but for a longer period

## B. Quantitative features

1. The variance of the sample mean seems to decay to zero slower than  $n^{-1}$
2. The sample correlation  $\rho(k) = \gamma(k)/\gamma(0)$  decays to zero at a rate that in good approximation is proportional to  $k^{-\alpha}$  for some  $0 < \alpha < 1$
3. Near the origin the logarithm of the power spectrum  $f(\lambda)$  plotted against the logarithm of the frequency appears to be randomly scattered around a straight line with negative slope.



Correlations for the same process (fractional noise with  $H=0.8$ )



Power Spectrum for the same process (fractional noise with  $H=0.8$ )

Point A.3 implies that at least at first approximation, it is reasonable to assume stationarity. Let us therefore assume that the data are a sample path of a stationary process  $X_t$ .

**Definition:** Let  $X_t$  be a stationary process for which the following holds. There exist a real number  $\alpha \in (0, 1)$  and a constant  $c_\rho$  such that

$$\lim_{k \rightarrow \infty} \rho(k) / [c_\rho k^{-\alpha}] = 1 \quad (4)$$

Then  $X_t$  is called a stationary process with long memory or long range dependence or strong dependence (or long range correlations).

The Hurst exponent is defined as  $H = 1 - \alpha/2$ , in terms of Hurst exponent long memory occurs if  $\frac{1}{2} < H < 1$ .

An equivalent definition of long memory is the following:

**Definition:** Let  $X_t$  be a stationary process for which the following holds: There exists a real number  $\beta \in (0, 1)$  and a constant  $c_f > 0$  such that

$$\lim_{\lambda \rightarrow 0} f(\lambda) / [c_f |\lambda|^{-\beta}] = 1 \quad (5)$$

Then  $X_t$  is called a stationary process with long memory.

These two definitions are equivalent in the following sense:

**Theorem:** (i) Suppose 4 holds with  $0 < \alpha = 2 - 2H < 1$ . Then the spectral density  $f$  exists and

$$\lim_{\lambda \rightarrow 0} f(\lambda) / [c_f(H) |\lambda|^{1-2H}] = 1 \quad (6)$$

where

$$c_f = \sigma^2 \pi^{-1} c_\rho \Gamma(2H - 1) \sin(\pi - \pi H) \quad (7)$$

and  $\sigma^2 = \text{var}(X_t)$

(ii) Suppose 5 holds with  $0 < \beta = 2H - 1 < 1$ . Then

$$\lim_{k \rightarrow \infty} \rho(k) / [c_\rho k^{-2H-2}] = 1 \quad (8)$$

where

$$c_\rho = \frac{c_\gamma}{\sigma^2} \quad (9)$$

and

$$c_\gamma = 2c_f \Gamma(2 - 2H) \sin\left(\pi H - \frac{\pi}{2}\right) \quad (10)$$

It is important to note that the definition of long-range dependence by 4 and 5 is an asymptotic definition.



## To summarize...

For a Long Memory Process

$$\rho(k) \approx k^{-\alpha} \quad (11)$$

$$f(\lambda) \approx |\lambda|^{-\beta} \quad (12)$$

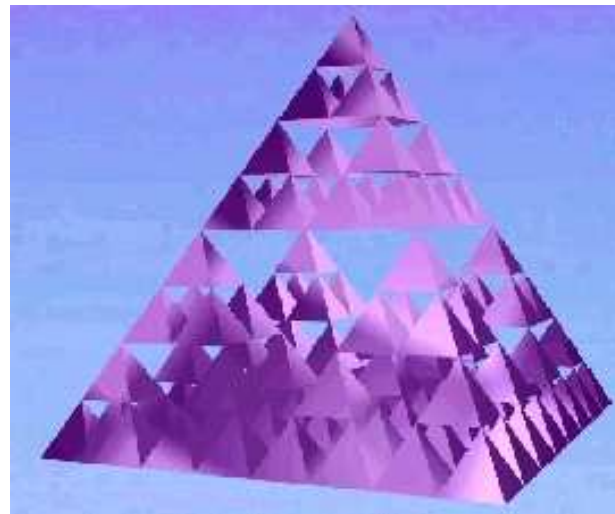
and

$$H = \frac{(2 - \alpha)}{2} = \frac{(1 + \beta)}{2} \quad (13)$$

with  $\frac{1}{2} < H < 1$

## Self Similar Processes

A geometric shape is called self-similar in a deterministic way if the same geometric structures are observed, independently of the distance from which one looks at the shape.



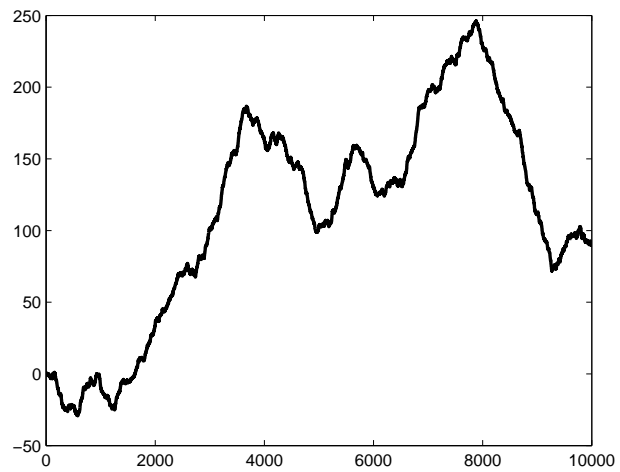
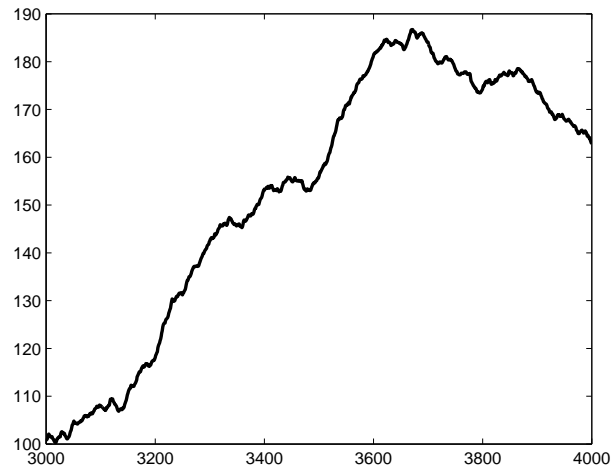
In the context of stochastic processes, self-similarity is defined in terms of the distribution of the process:

**Definition:** Let  $Y_t$  be a stochastic process with continuous time parameter  $t$ .  $Y_t$  is called self-similar with self-similarity parameter  $H$ , if for any positive stretching factor  $c$ , the rescaled process with time scale  $ct$ ,  $ct^{-H}Y_{ct}$ , is equal in distribution to the original process  $Y_t$ .

This means that for any sequences of time  $t_1, \dots, t_k$  and any positive constant  $c$ ,  $c^{-H}(Y_{ct_1}, Y_{ct_2}, \dots, Y_{ct_k})$  has the same distribution of  $(Y_{t_1}, Y_{t_2}, \dots, Y_{t_k})$ .

Thus, typical sample paths of self-similar process look qualitatively the same, irrespective of the distance from which we look at them.

In contrast to deterministic self-similarity, it does not mean that the same picture repeats itself exactly as we go closer. It is rather the general impression that remains the same.



Self-similarity arises in a natural way from limit theorems for sums of random variables.

**Definition:** if for any  $k \geq 1$  and any  $k$  time point  $t_1, \dots, t_k$ , the distribution of  $(Y_{t_1+c} - Y_{t_1+c-1}, \dots, Y_{t_k+c} - Y_{t_k+c-1})$  does not depend on  $c \in \mathbb{R}$ , then we say that  $Y_t$  has stationary increments.

**Theorem:** (i) Suppose that  $Y_t$  is a stochastic process such that  $Y_1 \neq 0$  with positive probability and  $Y_t$  is the limit in distribution of the sequence of normalized partial sums

$$a_n^{-1} S_{nt} = a_n^{-1} \sum_{i=1}^{[nt]} X_i, \quad n = 1, 2, \dots \quad (14)$$

Here  $[nt]$  denotes the integer part of  $nt$ ,  $X_1, X_2, \dots$  is a stationary sequence of random variables, and  $a_1, a_2, \dots$  is a sequence of positive normalizing constants such that  $\log a_s \rightarrow \infty$ . Then there exists an  $H > 0$  such that for any  $u > 0$

$$\lim_{n \rightarrow \infty} \frac{a_{nu}}{a_n} = u^H \quad (15)$$

and  $Y_t$  is self-similar with self-similarity parameter  $H$ , and has stationary increments.

(ii) All self-similar processes with stationary increments and  $H > 0$  can be obtained by partial sums as given in (i).

Part (i) says that whenever a process is the limit of normalized partial sums of random variables, it is necessarily self-similar.

Suppose that  $Y_t$  is a self-similar process with self-similarity parameter  $H$ . The property

$$Y_t =_d t^H Y_1 \quad (t > 0) \quad (16)$$

where  $=_d$  is equality in distribution, implies the following limiting behavior of  $Y_t$  as  $t$  tends to infinity:

1. If  $H < 0$ , then  $Y_t \rightarrow_d 0$
2. If  $H = 0$ , then  $Y_t =_d Y_1$
3. if  $H > 0$  and  $Y_t \neq 0$ , then  $|Y_t| \rightarrow_d \infty$



Analogously, for  $t$  converging to zero, we have:

1. If  $H < 0$  and  $Y_t \neq 0$ , then  $|Y_t| \rightarrow_d \infty$

2. If  $H = 0$ , then  $Y_t =_d Y_1$

3. if  $H > 0$  and  $Y_t \neq 0$ , then  $Y_t \rightarrow_d 0$

If we exclude the trivial case  $Y_t \equiv 0$ , then these properties imply that  $Y_t$  is not stationary unless  $H = 0$ .

For the purpose of modelling data that look stationary, we need only to consider self-similar processes with stationary increments. The range of  $H$  can then be restricted to  $H > 0$ .

The form of the covariance function  $\gamma_y(t, s) = \text{cov}(Y_t, Y_s)$  of a self-similar process  $Y_t$  with stationary increments follows from these two properties. Let us assume that  $E[Y_t] = 0$ .

Let  $s < t$  and denote by  $\sigma^2 = E[(Y_t - Y_{t-1})^2] = E[Y_1^2]$  the variance of the increments process  $X_t = Y_t - Y_{t-1}$ . Then

$$E[(Y_t - Y_s)^2] = E[(Y_{t-s} - Y_0)^2] = \sigma^2(t - s)^{2H} \quad (17)$$

The covariance  $\gamma(k)$  of the increments sequence  $X_i = Y_i - Y_{i-1}$ , between  $X_i$  and  $X_{i+k}$  for  $k > 0$  is

$$\gamma(k) = \frac{1}{2} \{ E[(Y_{k+1} - Y_0)^2] - E[(Y_{k-1} - Y_0)^2] - 2E[(Y_k - Y_0)^2] \} \quad (18)$$

Using self-similarity, we obtain the formula

$$\gamma(k) = \frac{1}{2} \sigma^2 [(k+1)^{2H} - 2k^{2H} + (k-1)^{2H}] \quad (19)$$

The correlations are then given by

$$\rho(k) = \frac{1}{2}[(k+1)^{2H} - 2k^{2H} + (k-1)^{2H}] \quad (20)$$

The asymptotic behavior of  $\rho(k)$  follows from Taylor expansion

$$\frac{\rho(k)}{[H(2H-1)k^{2H-2}]} \rightarrow 1 \quad (21)$$

as  $k \rightarrow \infty$ . For  $1/2 < H < 1$  this means that the correlations decay to zero so slowly that

$$\sum_{k=-\infty}^{\infty} \rho(k) = \infty \quad (22)$$

The process  $X_i$  ( $i = 1, 2, \dots$ ) has long memory.

For  $H = 1/2$ , all correlations at non-zero lags are zero, i.e., the observations  $X_i$  are uncorrelated.

For  $0 < H < 1/2$ , the correlations are summable. In fact a more specific equation holds, namely,

$$\sum_{k=-\infty}^{\infty} \rho(k) = 0 \quad (23)$$

In practice, this case is rarely encountered and the sum is equal to some constant  $c$  different from zero.

We will assume that the variance is always finite and  $\lim_{k \rightarrow \infty} \rho(k) = 0$  and then  $0 < H < 1$ .

Under this assumptions, the spectral density of the increments  $X_i$  can be calculated directly and expanded near the origin giving

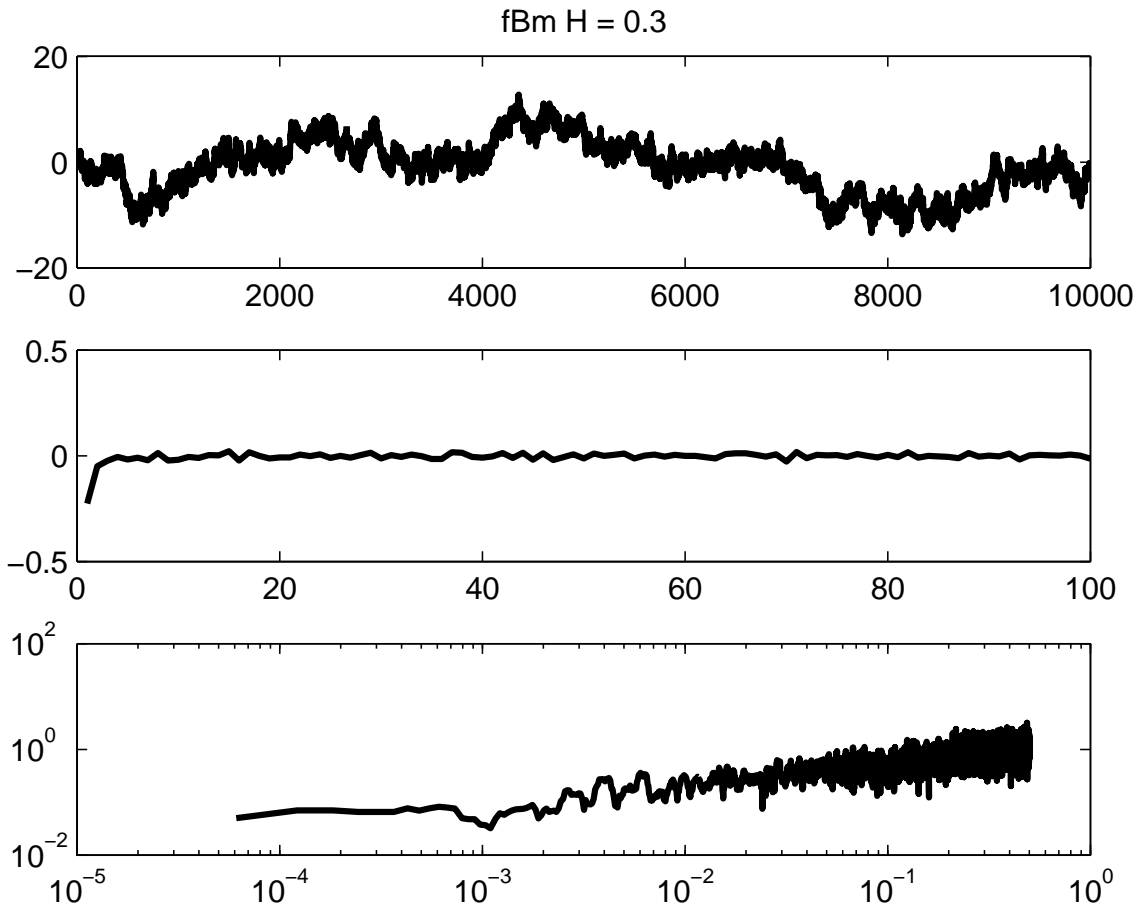
$$f(\lambda) \approx c_f |\lambda|^{1-2H} \quad (24)$$

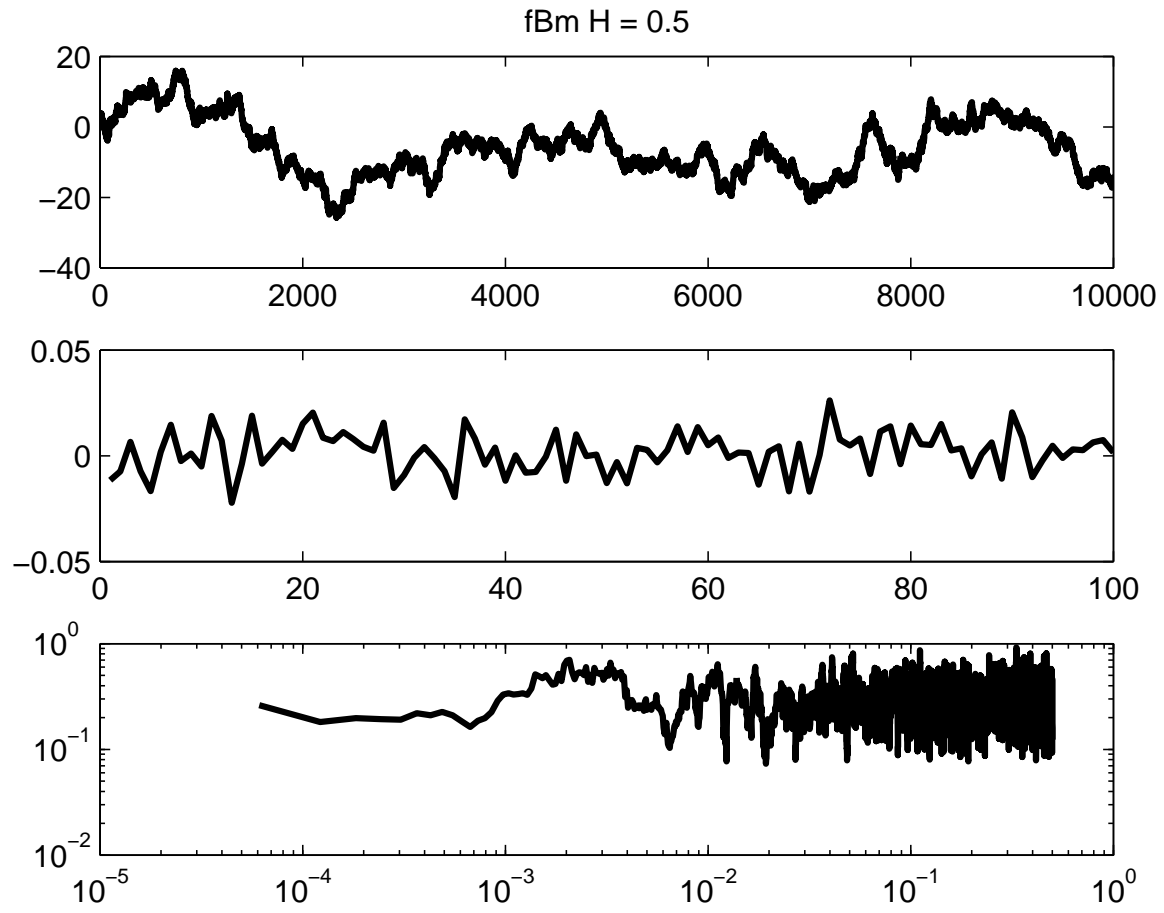
## To summarize... again

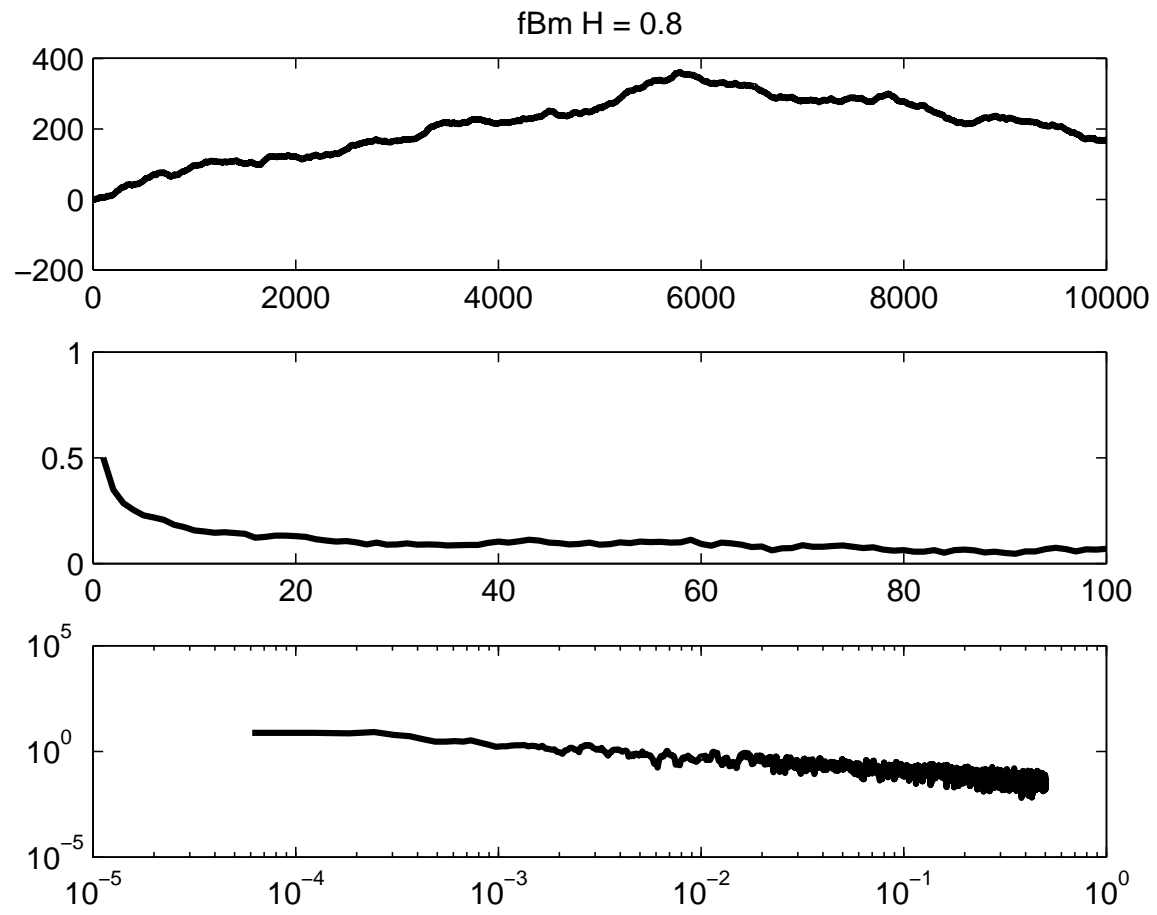
Let  $X_i$  be a stationary stochastic process

- $\frac{1}{2} < H < 1$  or  $0 < \alpha < 1$  or  $0 < \beta < 1$  then  $X_i$  has Long Memory (persistent)
- $H = \frac{1}{2}$  then correlations are zero
- $0 < H < \frac{1}{2}$  correlations are, in fact, negative and the process is anti-persistent









## Fractional Brownian Motion and Gaussian Noise

Suppose that  $Y_t$  is a self-similar process with stationary increments (N.B. we do not request stationarity of the process itself). That the increments  $X_i = Y_i - Y_{i-1}$  have zero mean and that they are Gaussian.

For each value of  $H \in (0, 1)$  there is exactly one Gaussian process  $X_i$  that is the stationary increment of a self similar process  $Y_t$ . This process is called **fractional Gaussian noise**.

The corresponding self-similar process  $Y_t$  is called **fractional Brownian motion** denoted by  $B_H(t)$

In the simple case of  $H = 1/2$ ,  $X_i$  are independent normal variable  $\rightarrow B_{\frac{1}{2}}(t)$  is an ordinary Brownian motion.

**Definition:** Let  $B(t)$  be a stochastic process with continuous sample paths and such that

- $B(t)$  is Gaussian
- $B(0) = 0$  almost surely
- $B(t)$  has independent increments

- $E[B(t) - B(s)] = 0$

- $\text{var}[B(t) - B(s)] = \sigma^2|t - s|$

Then  $B(t)$  is called Brownian motion.

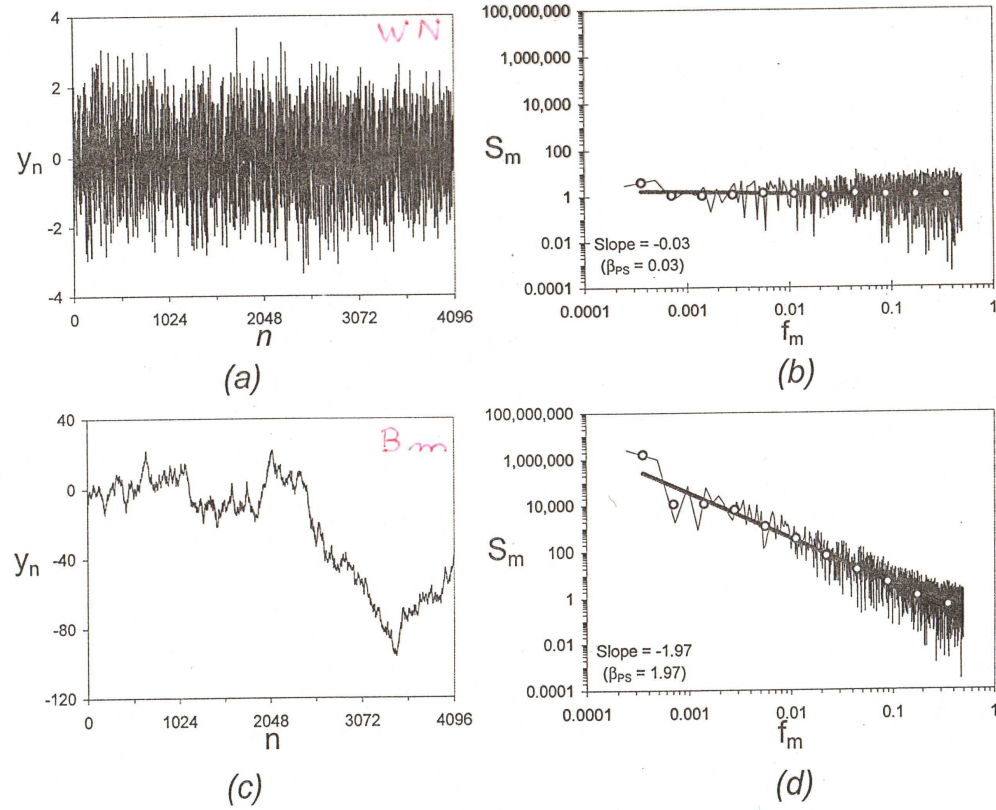
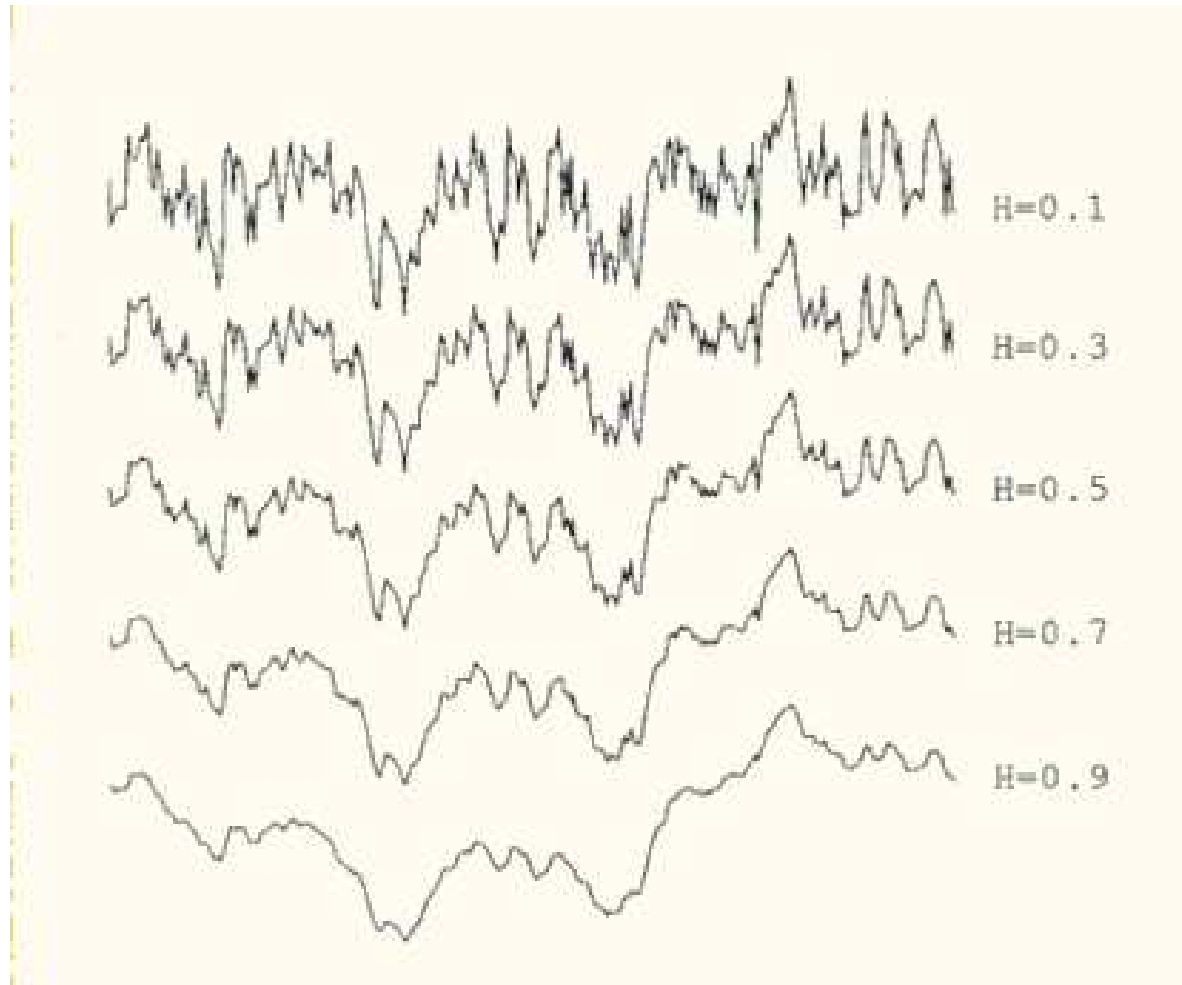


Figure 1, Malamud and Turcotte





# Detection of Long Memory

1. Detrended Fluctuation Analysis
2. Rescaled Range Analysis
3. Spectral Analysis

## Detrended Fluctuation Analysis

The method has been used to identify whether long range correlations exist in many research fields such as e.g. finance, cardiac dynamics, meteorology etc. etc.

- The signal time series  $X(i)$ ,  $i = 1, 2, \dots, N$  is *first integrated*

$$Y(k) = \sum_{i=1}^k [X(i) - \langle X \rangle] \quad (25)$$

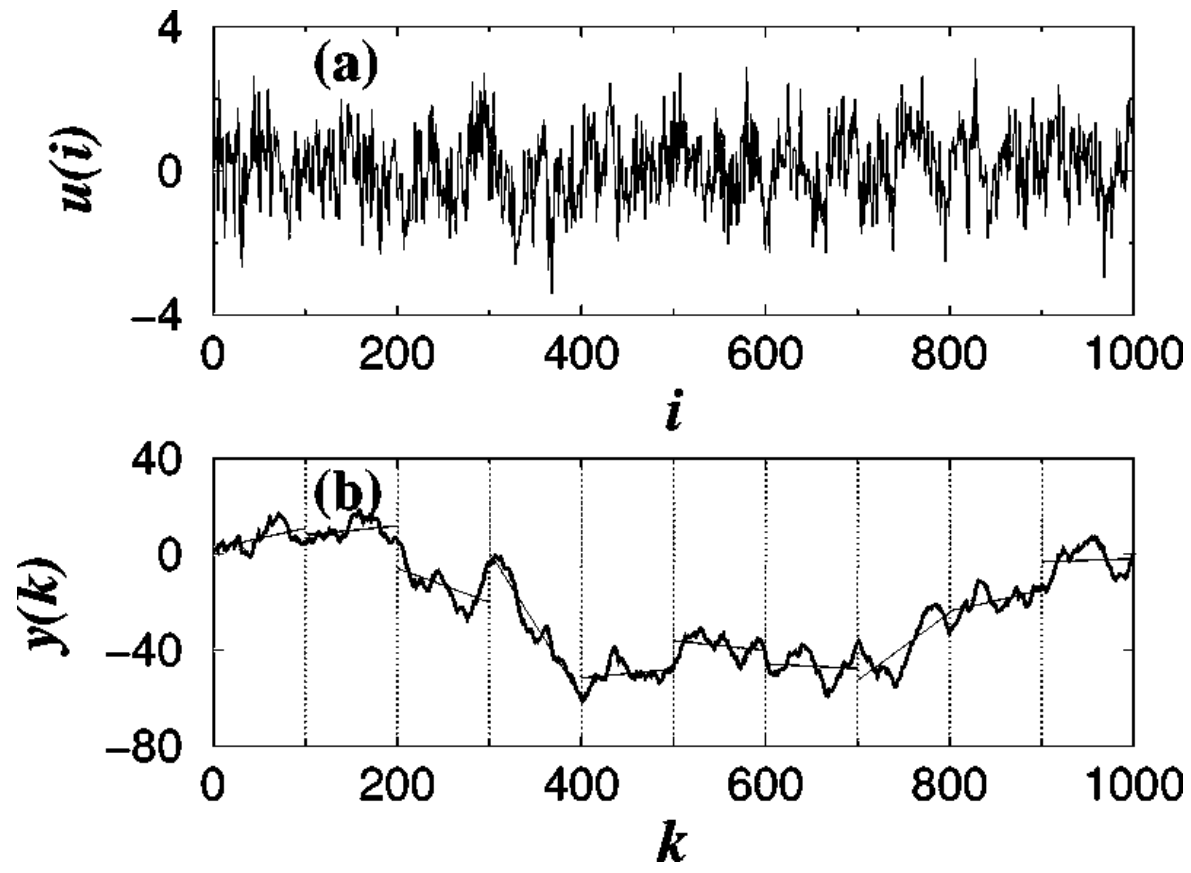
where  $\langle X \rangle$  is the mean;

- The time axis (from 1 to  $N$ ) is next divided into non-overlapping boxes of equal size  $n$ ;
- In each box of length  $n$  one looks thereafter for the best (polynomial, of degree  $m$ ) trend,  $z_{n,m}$ ;
- The integrated signal in each box is detrended by subtracting the local trend;

- For each box size  $n$ , the root mean square deviation of the (integrated) signal is calculated

$$F_m(n) \equiv \sqrt{\frac{1}{N} \sum_{k=1}^N [Y(k) - z_{n,m}(i)]^2} ; \quad (26)$$

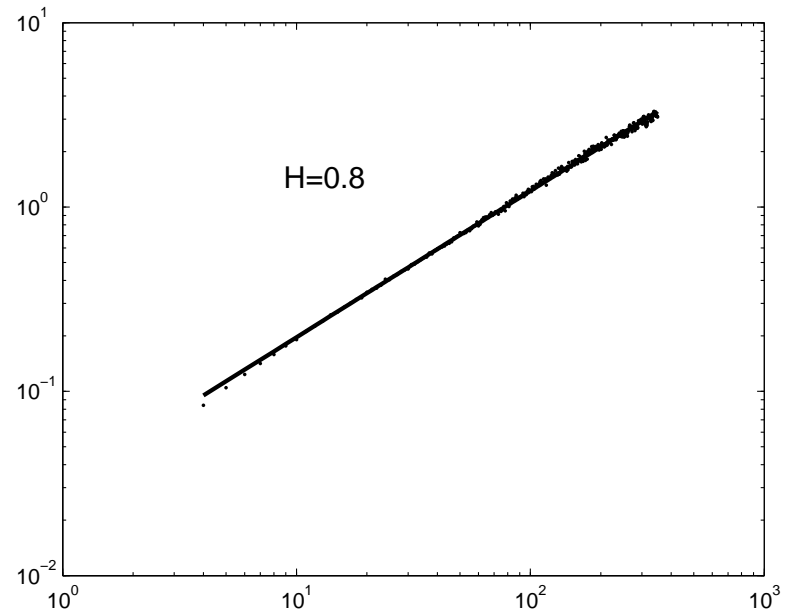
- the above computation is repeated for a broad range of scales (box size  $n$ ) to provide a relationship between the fluctuation function  $F_m(n)$  and the box size  $n$ ;



If the original time series  $X(i)$  is long range correlated (has long memory) the fluctuation function  $F_m(n)$  increases following a power law:

$$F_m(n) \approx n^\gamma \quad (27)$$

and the exponent  $\gamma$  is related to the correlation exponent  $\alpha$ . It turns out that  $\gamma = H$ .



DFA for the same process (fractional noise with  $H=0.8$ )

## Rescaled Range Analysis

- The signal time series  $X(i)$ ,  $i = 1, 2, \dots, N$  is divided into  $l$  boxes of equal size  $n$ ;
- In the  $k^{th}$  box, ( $k = 1, \dots, l$ ), there are  $n$  elements;
- the local fluctuation at point  $j$  in the  $k^{th}$  box is

$$F^{(k)}(n) = X^{(k)}(j) - \langle X \rangle_n^{(k)} \quad (28)$$

where  $\langle \rangle_n$  is the mean in the  $k^{th}$  box;



- Let

$$S^{(k)}(n) = \sqrt{\frac{1}{n} \sum_{j=1}^n (F(n)^{(k)})^2} \quad (29)$$

- The cumulative departure  $Y_m^{(k)}(n)$  up to the  $m^{\text{th}}$  point in the  $k^{\text{th}}$  box (of size  $n$ ) is next calculated

$$Y_m^{(k)}(n) = \sum_{j=1}^m F^{(k)}(n) \quad (30)$$

for  $m = 1, \dots, n$  and in all  $k$  boxes

- look for  $\max_{1 \leq m \leq n} Y_m^{(k)}(n)$  and  $\min_{1 \leq m \leq n} Y_m^{(k)}(n)$

- The rescaled range function is then defined by

$$\frac{R^{(k)}(n)}{S^{(k)}(n)} = \frac{\max_{1 \leq m \leq n} Y_m^{(k)}(n) - \min_{1 \leq m \leq n} Y_m^{(k)}(n)}{\sqrt{\frac{1}{n} \sum_{j=1}^n (F(n)^{(k)})^2}}$$

for  $k = 1, \dots, l$

- The average of the rescaled range function for boxes of size  $n$  is obtained and denoted by  $\langle R/S \rangle_n$
- Everything is repeated for different  $n$
- for Long Memory processes one expects

$$\langle R/S \rangle_n \approx n^H \quad (31)$$

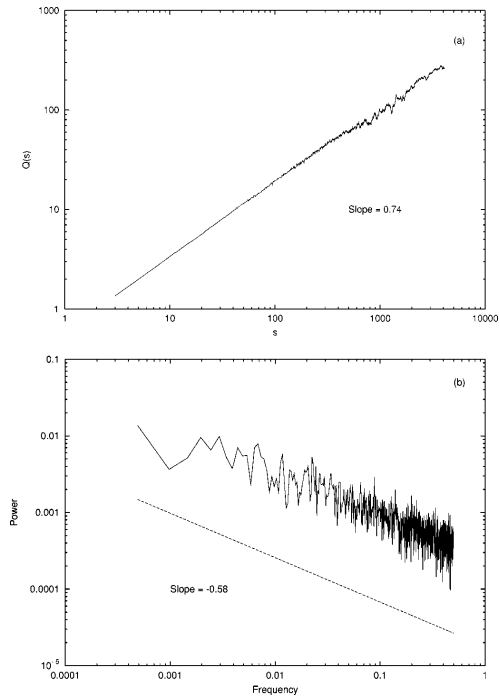


FIG. 1. (a) Log-log plot of the rescaled range statistic  $Q(s)$  against the window size  $s$  for a true long range correlated process with  $\alpha=0.6$ , variance 0.25, and a long data set of 8192 points. (b) Spectral density of the same data.

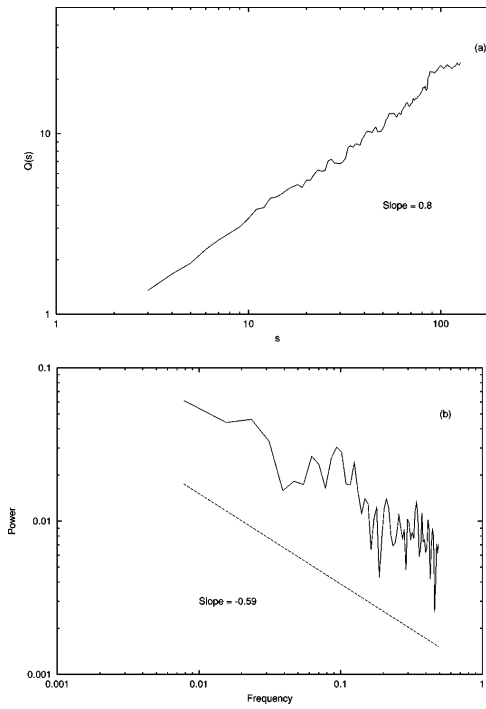


FIG. 2. (a) Log-log plot of the rescaled range statistic  $Q(s)$  against the window size  $s$  for a true long range correlated process with  $\alpha=0.6$ , variance 0.25, and a short data set of 256 points. (b) Spectral density of the same data.

Two examples taken from [2]

## Spectral Analysis

The periodogram (the sample analogon of the spectral density) is defined as

$$I(\lambda_j) = \frac{1}{2\pi n} \left| \sum_{t=1}^n (X_t - \langle X \rangle_n) e^{it\lambda_j} \right|^2 = \frac{1}{2\pi} \sum_{k=-(n-1)}^{n-1} \hat{\gamma}(k) e^{it\lambda_j}$$

where

$$\hat{\gamma}(k) = \frac{1}{n} \sum_{t=1}^{n-|k|} (X_t - \langle X \rangle_n) (X_{t+k} - \langle X \rangle_n)$$

are the sample covariances

It is expected for a long memory process

$$I(\lambda_j) \approx |\lambda|^{1-2H}$$

## References

1. J. Beran, *Statistics for Long-Memory Processes*, Chapman & Hall, New York (1994).
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3. B.D. Malamud and D. L. Turcotte, *J. Stat. Plann. Infer.* 80 (1999) 173-196.