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**Electrodynamics revisited: Basic principles of medical lasers (I)**

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# **ELECTODYNAMICS: REVISITED**

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# LAYOUT

- **Electrostatic : Revisited**
- **Magnetostatic : Revisited**
- **Introduction to Maxwell's equations**
- **Electrodynamics before Maxwell**
- **Maxwell's correction to Ampere's law**
- **General form of Maxwell's equations**
- **Maxwell's equations in vacuum**
- **Maxwell's equations inside matter**
- **The Electromagnetic wave**

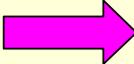
# Nomenclature

- $E$  = Electric field
- $D$  = Electric displacement
- $B$  = Magnetic flux density
- $H$  = Auxiliary field
- $\rho$  = Charge density
- $j$  = Current density
- $\mu_0$  (permeability of free space) =  $4\pi \times 10^{-7} \text{T}\cdot\text{m/A}$
- $\epsilon_0$  (permittivity of free space) =  $8.854 \times 10^{-12} \text{N}\cdot\text{m}^2/\text{C}^2$
- $c$  (speed of light) =  $2.99792458 \times 10^8 \text{ m/s}$

# Introduction

- **Electrostatics**

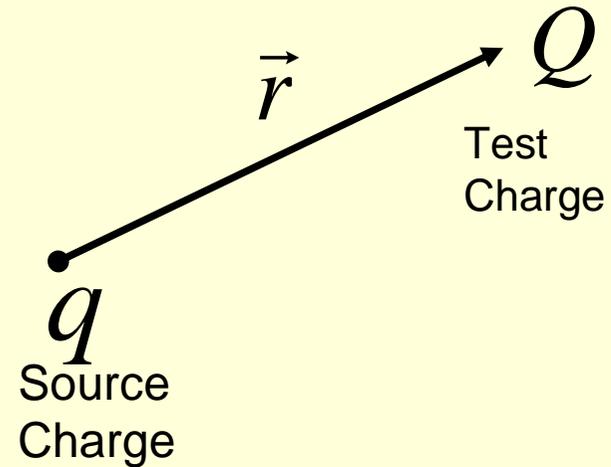
- **Electrostatic field** : Stationary charges produce electric fields that are constant in time. The theory of static charges is called electrostatics.

**Stationary charges**  **Constant Electric field;**

# Electrostatic :Revisited

## Coulombs Law

$$\vec{F} = \frac{1}{4\pi\epsilon_0} \frac{qQ}{r^2} \hat{r}$$



$$\epsilon_0 = 8.85 \times 10^{-12} \frac{C^2}{N \cdot m^2} \text{ Permittivity of free space}$$

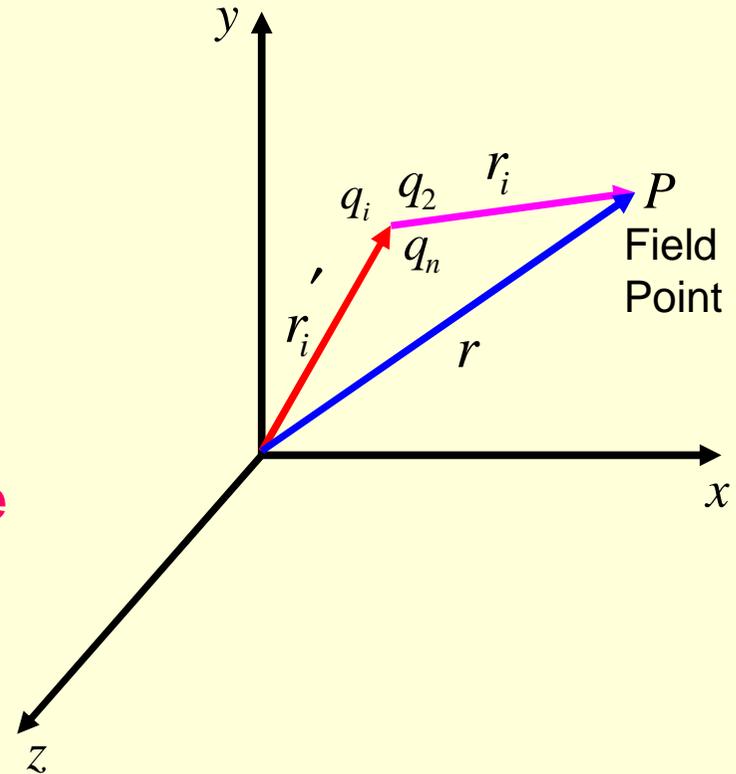
# The Electric Field

$$\vec{F} = Q\vec{E}$$

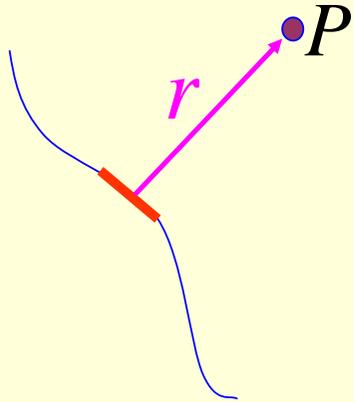
$$\vec{E}(P) = \frac{1}{4\pi\epsilon_0} \sum_{i=1}^n \frac{q_i}{r_i^2} \hat{r}_i$$

$\vec{E}$  - the electric field of the source charges.

Physically  $E(P)$  is force per unit charge exerted on a test charge placed at  $P$ .

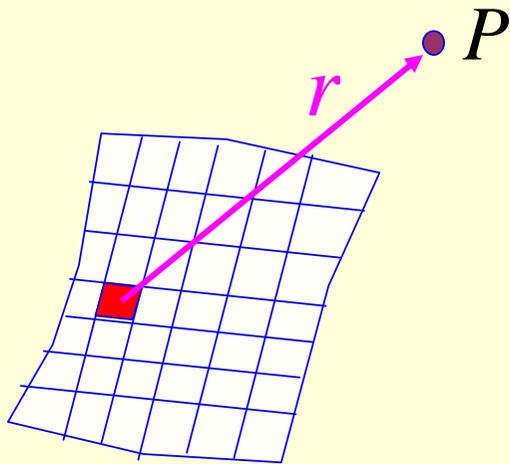


# The Electric Field: cont'd



$$\vec{E}(P) = \frac{1}{4\pi\epsilon_0} \int_{Line} \frac{\hat{r}}{r^2} \lambda dl$$

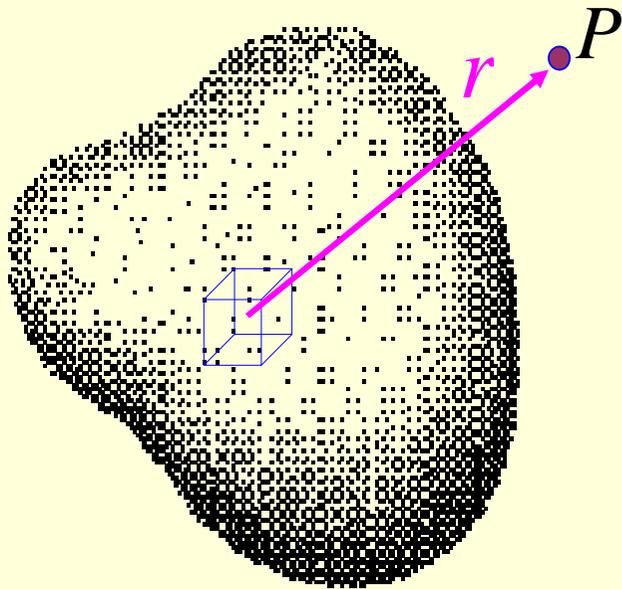
$\lambda$  is the line charge density



$$\vec{E}(P) = \frac{1}{4\pi\epsilon_0} \int_{Surface} \frac{\hat{r}}{r^2} \sigma da$$

$\sigma$  is the surface charge density

# The Electric Field: cont'd



$$\vec{E}(P) = \frac{1}{4\pi\epsilon_0} \int_{\text{Volume}} \frac{\hat{r}}{r^2} \rho d\tau$$

$\rho$  is the volume charge density

# Electric Potential

The work done in moving a test charge  $Q$  in an electric field from point  $P_1$  to  $P_2$  with a constant speed.

$$W = \text{Force} \cdot \text{distance}$$

$$W = - \int_{P_1}^{P_2} Q\vec{E} \cdot d\vec{l}$$

negative sign - work done is against the field.

For any distribution of fixed charges.

$$\oint \vec{E} \cdot d\vec{l} = 0$$

**The electrostatic field is conservative**

# Electric Potential: cont'd

Stokes's Theorem gives

$$\vec{\nabla} \times \vec{E} = 0$$

$$\vec{E} = -\vec{\nabla} V$$

where  $V$  is Scalar Potential

The work done in moving a charge  $Q$  from infinity to a point  $P_2$  where potential is  $V$

$$W = QV$$

$V$  = Work per unit charge

= Volts = joules/Coulomb

# Electric Potential : cont'd

Field due to a single point charge  $q$  at origin

$$V = \int_r^{\infty} \frac{qdr}{4\pi\epsilon_0 r^2} = \frac{q}{4\pi\epsilon_0 r}$$

$$F \propto \frac{1}{r^2}$$

$$E \propto \frac{1}{r^2}$$

$$V \propto \frac{1}{r}$$

**Gauss's Law**  $\oint \vec{E} \cdot d\vec{a} = \frac{1}{\epsilon_0} Q_{enc}$

Differential form of Gauss's Law  $\vec{\nabla} \cdot \vec{E} = \frac{\rho}{\epsilon_0}$

**Poisson's Equation**  $\nabla^2 V = -\frac{\rho}{\epsilon_0}$

**Laplace's Equation**  $\nabla^2 V = 0$

# Electrostatic Fields in Matter

**Matter:** Solids, liquids, gases, metal, wood and glasses - behave differently in electric field.

## Two Large Classes of Matter

(i) Conductors

(ii) Dielectric

**Conductors:** Unlimited supply of free charges.

**Dielectrics:**

- Charges are attached to specific atoms or molecules- No free charges.
- Only possible motion - minute displacement of positive and negative charges in opposite direction.
- Large fields- pull the atom apart completely (ionizing it).

# Polarization

A dielectric with charge displacements or induced dipole moment is said to be polarized.



Induced Dipole Moment  $\mathbf{p} = \alpha \mathbf{E}$

The constant of proportionality  $\alpha$  is called the atomic polarizability

$\mathbf{P} \equiv$  dipole moment per unit volume

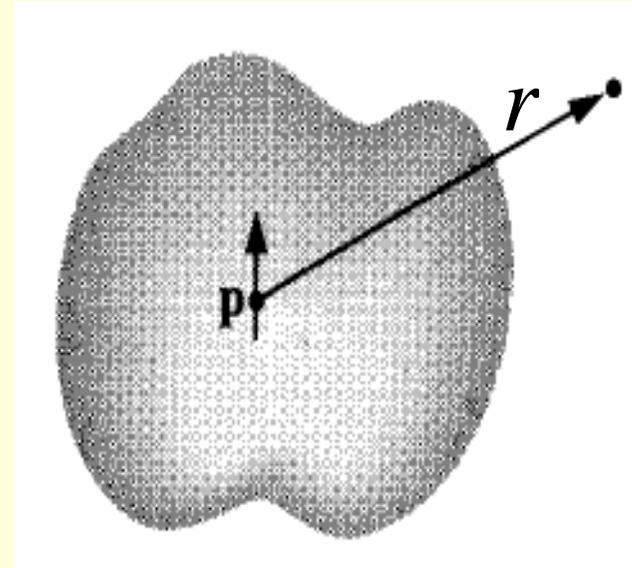
# The Field of a Polarized Object

Potential of single dipole  $\mathbf{p}$  is

$$dV = \frac{1}{4\pi\epsilon_0} \frac{\hat{\mathbf{r}} \cdot \vec{\mathbf{p}}}{r^2}$$

$$V = \frac{1}{4\pi\epsilon_0} \int_{\text{volume}} \frac{\vec{\mathbf{P}} \cdot \hat{\mathbf{r}}}{r^2} d\tau$$

$$V = \frac{1}{4\pi\epsilon_0} \left[ \int_{\text{surface}} \frac{1}{r} \vec{\mathbf{P}} \cdot d\mathbf{a} - \int_{\text{volume}} \frac{1}{r} (\vec{\nabla} \cdot \vec{\mathbf{P}}) d\tau \right]$$



Potential due to dipoles in the dielectric

# The Field of a Polarized Object: cont'd

$$\sigma_b = \vec{P} \cdot \hat{n}$$

Bound charges at surface

$$\rho_b = -\vec{\nabla} \cdot \vec{P}$$

Bound charges in volume

$$V = \frac{1}{4\pi\epsilon_0} \left[ \int_{\text{surface}} \frac{1}{r} \sigma_b da - \int_{\text{volume}} \frac{1}{r} \rho_b d\tau \right]$$

The total field is field due to bound charges plus due to free charges

# Gauss's law in Dielectric

- Effect of polarization is to produce accumulations of bound charges.
- The total charge density

$$\rho = \rho_f + \rho_b$$

$$\int \vec{D} \cdot d\vec{a} = Q_{fenc}$$

From Gauss's law

$Q_{fenc}$  -Free charges enclosed

$$\epsilon_0 \vec{\nabla} \cdot \vec{E} = \rho = \rho_b + \rho_f$$

Displacement vector

$$\vec{\nabla} \cdot \vec{D} = \rho_f$$

$$\vec{D} = \epsilon_0 \vec{E} + \vec{P}$$

# Magnetostatics : Revisited

- **Magnetostatics**
  - **Steady current produce magnetic fields that are constant in time. The theory of constant current is called magnetostatics.**

**Steady currents  
field;**  **Constant Magnetic**

# Magnetic Forces

## Lorentz Force

$$\vec{F} = q[\vec{E} + (\vec{v} \times \vec{B})]$$

- The magnetic force on a segment of current carrying wire is

$$F_{mag} = \int (\vec{I} \times \vec{B}) dl$$

$$F_{mag} = \int I (d\vec{l} \times \vec{B})$$

# Equation of Continuity

The current crossing a surface  $s$  can be written as

$$I = \int \vec{J} \cdot d\vec{a} = \int (\vec{\nabla} \cdot \vec{J}) d\tau$$
$$\int (\vec{\nabla} \cdot \vec{J}) d\tau = -\frac{d}{dt} \int \rho d\tau = -\int \left( \frac{\partial \rho}{\partial t} \right) d\tau$$

Charge is conserved whatever flows out must come at the expense of that remaining inside - outward flow decreases the charge left in  $v$

$$\vec{\nabla} \cdot \vec{J} = -\frac{\partial \rho}{\partial t} \quad \text{This is called equation of continuity}$$

# Equation of Continuity Cont'd

In Magnetostatic steady currents flow in the wire and its magnitude  $I$  must be the same along the line- otherwise charge would be piling up some where and current can not be maintained indefinitely.

$$\frac{\partial \rho}{\partial t} = 0$$

In Magnetostatic and equation of continuity

$$\vec{\nabla} \cdot \vec{J} = 0$$

**Steady Currents: The flow of charges that has been going on forever - never increasing - never decreasing.**

# Magnetostatic and Current Distributions

## Biot and Savart Law

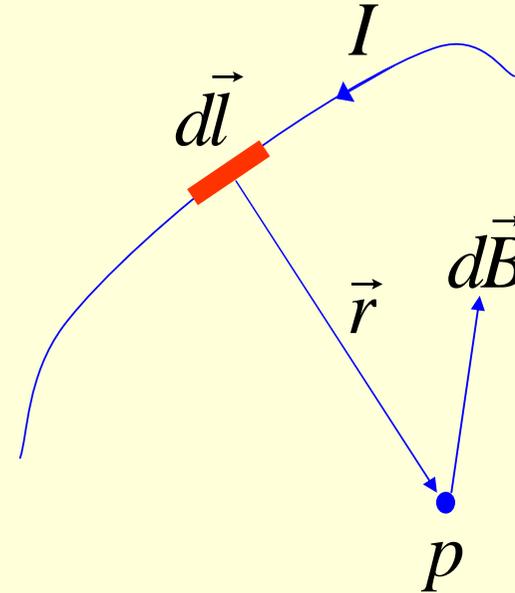
$$\vec{B}(p) = \frac{\mu_0}{4\pi} \int \frac{\vec{I} \times \vec{r}}{|\vec{r}|^3} dl$$

$dl$  is an element of length.

$\vec{r}$  vector from source to point p.

$\mu_0$  Permeability of free space.

Unit of B = N/Am = Tesla (T)



# Biot and Savart Law for Surface and Volume Currents

$$\vec{B} = \frac{\mu_0}{4\pi} \int \frac{\vec{K} \times \vec{r}}{|\vec{r}|^3} da \quad \text{For Surface Currents}$$

$$\vec{B} = \frac{\mu_0}{4\pi} \int \frac{\vec{J} \times \vec{r}}{|\vec{r}|^3} d\tau \quad \text{For Volume Currents}$$

# Force between two parallel wires

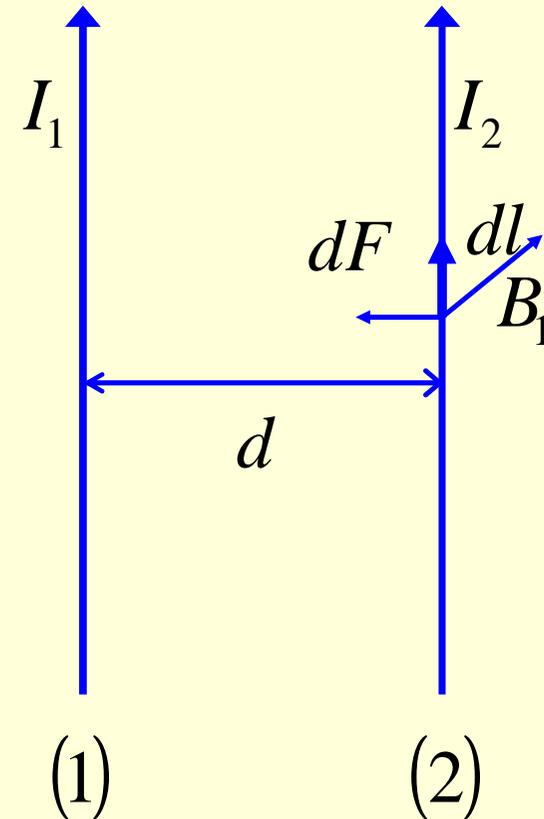
The magnetic field at (2) due to current  $I_1$  is

$$B_1 = \frac{\mu_0 I_1}{2\pi d} \quad \text{Points inside}$$

Magnetic force law

$$dF = \int I_2 (d\vec{l}_2 \times \vec{B}_1)$$

$$dF = \int I_2 \left( d\vec{l}_2 \times \frac{\mu_0 I_1}{2\pi d} \hat{k} \right)$$



# Force between two parallel wires

$$dF = \frac{\mu_0 I_1 I_2}{2\pi d} dl_2$$

The total force is infinite but force per unit length is

$$\frac{dF}{dl_2} = \frac{\mu_0 I_1 I_2}{2\pi d}$$

If currents are anti-parallel the force is repulsive.

# Straight line currents

The integral of  $\vec{B}$  around a circular path of radius  $s$ , centered at the wire is

$$\oint \vec{B} \cdot d\vec{l} = \oint \frac{\mu_0 I}{2\pi s} dl = \mu_0 I$$

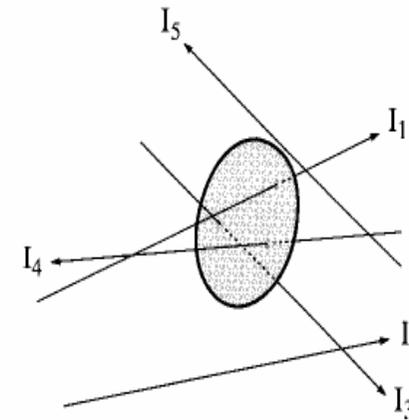
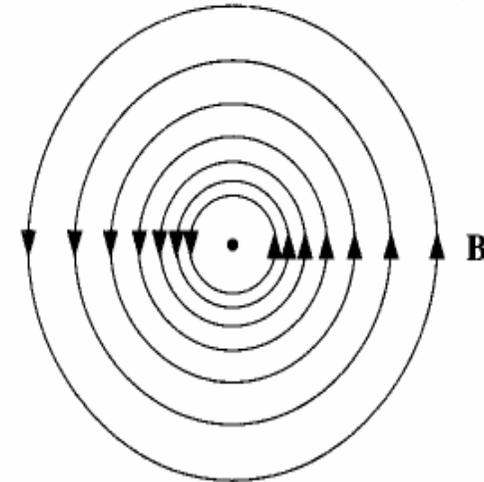
For bundle of straight wires. Wire that passes through loop contributes only.

$$\oint \vec{B} \cdot d\vec{l} = \mu_0 I_{enc}$$

Applying Stokes' theorem

$$\vec{\nabla} \times \vec{B} = \mu_0 \vec{J}$$

The current is out of the page



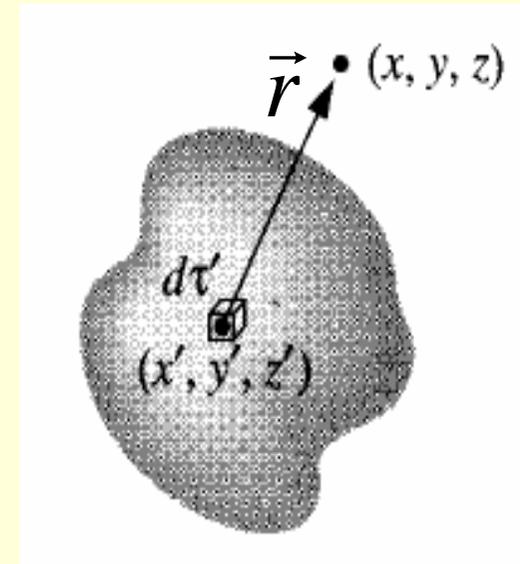
# Divergence and Curl of B

Biot-Savart law for the general case of a volume current reads

$$\vec{B} = \frac{\mu_0}{4\pi} \int \frac{\vec{J}(r') \times \vec{r}}{r^3} d\tau'$$

$\vec{r}$

$$\begin{aligned} \mathbf{B} & \text{ is a function of } (x, y, z), \\ \mathbf{J} & \text{ is a function of } (x', y', z'), \\ & = (x - x') \hat{\mathbf{x}} + (y - y') \hat{\mathbf{y}} + (z - z') \hat{\mathbf{z}}, \\ & d\tau' = dx' dy' dz'. \end{aligned}$$



$$\vec{\nabla} \cdot \vec{B} = 0 \quad \text{and} \quad \vec{\nabla} \times \vec{B} = \mu_0 \vec{J}$$

# Ampere's Law

$$\vec{\nabla} \times \vec{B} = \mu_0 \vec{J} \quad \text{Ampere's law}$$

Integral form of Ampere's law

Using Stokes' theorem

$$\int (\vec{\nabla} \times \vec{B}) \cdot d\vec{a} = \oint \vec{B} \cdot d\vec{l} = \mu_0 \int \vec{J} \cdot d\vec{a}$$

$$\oint \vec{B} \cdot d\vec{l} = \mu_0 I_{enc}$$

# Magnetic Scalar and Vector Potential

The basic differential law of Magnetostatics

$$\vec{\nabla} \times \vec{B} = \mu_0 \vec{J}$$

$$\vec{\nabla} \cdot \vec{B} = 0$$

**B must be curl of some vector field called vector potential  $A(P)$**

$$\vec{B}(P) = \vec{\nabla} \times \vec{A}(P)$$

$$\vec{\nabla} \times (\vec{\nabla} \times \vec{A}) = \mu_0 \vec{J}$$

**Coulomb's gauge**

$$\vec{\nabla} \cdot \vec{A} = 0$$

$$\nabla^2 A = \mu_0 \vec{J}$$

# Magnetostatic Field in Matter

- **Magnetic fields- due to electrical charges in motion.**
- **Examine a magnet on atomic scale we would find tinny currents.**
- **Two reasons for atomic currents.**
  - **Electrons orbiting around nuclei.**
  - **Electrons spinning on their axes.**
- **Current loops form magnetic dipoles - they cancel each other due to random orientation of the atoms.**
- **Under an applied Magnetic field- a net alignment of - magnetic dipole occurs- and medium becomes magnetically polarized or magnetized**

# Magnetization

If  $m$  is the average magnetic dipole moment per unit atom and  $N$  is the number of atoms per unit volume, the magnetization is define as

$$\vec{M} = N\vec{m} \quad \vec{m} = I\vec{a} = Am^2$$

or

$$m = Md\tau \quad M = \frac{Am^2}{m^3} = \frac{A}{m}$$

# Magnetic Materials

## Paramagnetic Materials

The materials having magnetization parallel to  $B$  are called paramagnets.

## Diamagnetic Materials

The elementary moment are not permanent but are induced according to Faraday's law of induction. In these materials magnetization is opposite to  $B$ .

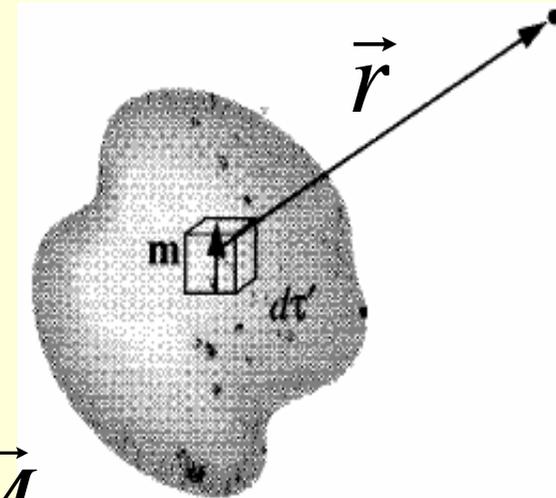
## Ferromagnetic Materials

Have large magnetization due to electron spin. Elementary moments are aligned in form of groups called domain

# The Field of Magnetized Object

Using the vector potential of current loop

$$\vec{A} = \frac{\mu_0}{4\pi} \frac{\vec{m} \times \hat{r}}{r^2}$$



$$\vec{A} = \frac{\mu_0}{4\pi} \int \frac{\vec{M} \times \hat{n}}{r} da + \frac{\mu_0}{4\pi} \int \frac{\vec{\nabla} \times \vec{M}}{r} d\tau$$

$$\vec{K}_b = \vec{M} \times \hat{n}$$

**Bound Surface Current**

$$\vec{J}_b = \vec{\nabla} \times \vec{M}$$

**Bound Volume Current**

# Ampere's Law in Magnetized Material

$$\vec{\nabla} \times \vec{B} = \mu_0 \vec{J}$$

$$\vec{J} = \vec{J}_b + \vec{J}_f$$

$$\frac{1}{\mu_0} (\vec{\nabla} \times \vec{B}) = \vec{J}_b + \vec{J}_f = \vec{J}_f + (\vec{\nabla} \times \vec{M})$$

$$\vec{\nabla} \times \vec{H} = \vec{J}_f$$

where

$$\vec{H} = \frac{\vec{B}}{\mu_0} - \vec{M}$$

Integral form

$$\oint \vec{H} \cdot d\vec{l} = I_{fenc}$$

# Faraday's Law of Induction

- Faraday's Law - a changing -magnetic flux through circuit induces an electromotive force around the circuit.

$$\varepsilon = \oint \vec{E} \cdot d\vec{l} = -\frac{d\phi}{dt} = -\frac{d}{dt} \int \vec{B} \cdot d\vec{a}$$

$\varepsilon$  – Induced emf

$E$  – Induced electric field intensity

Differential form of Faraday's law

$$\vec{\nabla} \times \vec{E} = -\frac{\partial \vec{B}}{\partial t}$$

# Faraday's Law of Induction

Induced Electric field intensity in terms of vector potential

$$\vec{E} = -\frac{\partial \vec{A}}{\partial t} - \vec{\nabla}V$$

For steady currents

$$\vec{E} = -\vec{\nabla}V \quad V - \text{Scalar potential}$$

Induced emf in a system moving in a changing magnetic field

$$\varepsilon = \vec{\nabla} \times \vec{E} = -\frac{\partial \vec{B}}{\partial t} + \vec{\nabla} \times (\vec{v} \times \vec{B})$$

# Maxwell's Equations

# Introduction to Maxwell's Equation

- In electrodynamics Maxwell's equations are a set of four equations, that describes the behavior of both the electric and magnetic fields as well as their interaction with matter
- Maxwell's four equations express
  - How electric charges produce electric field (Gauss's law)
  - The absence of magnetic monopoles
  - How currents and changing electric fields produces magnetic fields (Ampere's law)
  - How changing magnetic fields produces electric fields (Faraday's law of induction)

# Historical Background

- 1864 Maxwell in his paper “A Dynamical Theory of the Electromagnetic Field” collected all four equations
- 1884 Oliver Heaviside and Willard Gibbs gave the modern mathematical formulation using vector calculus.
- The change to vector notation produced a symmetric mathematical representation, that reinforced the perception of physical symmetries between the various fields.

# Electrodynamics Before Maxwell

Gauss's Law

$$(i) \vec{\nabla} \cdot \vec{E} = \frac{\rho}{\epsilon_0}$$

No name

$$(ii) \vec{\nabla} \cdot \vec{B} = 0$$

Faraday's Law

$$(iii) \vec{\nabla} \times \vec{E} = -\frac{\partial \vec{B}}{\partial t}$$

Ampere's Law

$$(iv) \vec{\nabla} \times \vec{B} = \mu_0 \vec{J}$$

$$\vec{E} = -\vec{\nabla} \phi - \frac{\partial \vec{A}}{\partial t}$$
$$\vec{B} = \vec{\nabla} \times \vec{A}$$

# Electrodynamics Before Maxwell (Cont'd)

Apply divergence to (iii)

$$\vec{\nabla} \cdot (\vec{\nabla} \times \vec{E}) = \vec{\nabla} \cdot \left( -\frac{\partial \vec{B}}{\partial t} \right) = -\frac{\partial}{\partial t} (\vec{\nabla} \cdot \vec{B})$$

The left hand side is zero, because divergence of a curl is zero.

The right hand side is zero because  $\vec{\nabla} \cdot \vec{B} = 0$ .

Apply divergence to (iv)

$$\vec{\nabla} \cdot (\vec{\nabla} \times \vec{B}) = \mu_o (\vec{\nabla} \cdot \vec{J})$$

# Electrodynamics Before Maxwell (Cont'd)

- The left hand side is zero, because divergence of a curl is zero.
- The right hand side is zero for steady currents i.e.,

$$\vec{\nabla} \cdot \vec{J} = 0$$

- In electrodynamics from conservation of charge

$$\begin{aligned}\vec{\nabla} \cdot \vec{J} &= - \frac{\partial \rho}{\partial t} \\ \Rightarrow \frac{\partial \rho}{\partial t} &= 0\end{aligned}$$

$\rho$  is constant at any point in space which is wrong.

# Maxwell's Correction to Ampere's Law

Consider Gauss's Law

$$\vec{\nabla} \cdot \epsilon_0 \vec{E} = \rho$$

$$\frac{\partial}{\partial t} (\vec{\nabla} \cdot \epsilon_0 \vec{E}) = \frac{\partial \rho}{\partial t}$$

$$\Rightarrow \frac{\partial \rho}{\partial t} = \vec{\nabla} \cdot \epsilon_0 \frac{\partial \vec{E}}{\partial t}$$

$$\frac{\partial \vec{D}}{\partial t} = \epsilon_0 \frac{\partial \vec{E}}{\partial t}$$

**Displacement current**

This result along with Ampere's law and the conservation of charge equation suggest that there are actually two sources of magnetic field. The current density and displacement current.

# Maxwell's Correction to Ampere's Law (Cont'd)

Ampere's law with Maxwell's correction

$$\vec{\nabla} \times \vec{B} = \mu_0 \vec{J} + \mu_0 \epsilon_0 \frac{\partial \vec{E}}{\partial t}$$

# General Form of Maxwell's Equations

## Differential Form

$$\vec{\nabla} \cdot \vec{E} = \frac{\rho}{\epsilon_0}$$

$$\vec{\nabla} \cdot \vec{B} = 0$$

$$\vec{\nabla} \times \vec{E} = -\frac{\partial \vec{B}}{\partial t}$$

$$\vec{\nabla} \times \vec{B} = \mu_0 \vec{J} + \mu_0 \epsilon_0 \frac{\partial \vec{E}}{\partial t}$$

## Integral Form

$$\oint_S \vec{E} \cdot d\vec{S} = \frac{1}{\epsilon_0} \int_V \rho dV$$

$$\oint_S \vec{B} \cdot d\vec{S} = 0$$

$$\oint_C \vec{E} \cdot d\vec{l} = -\frac{d}{dt} \int_S \vec{B} \cdot d\vec{S}$$

$$\oint_C \vec{B} \cdot d\vec{l} = \mu_0 I_{enc} + \mu_0 \epsilon_0 \frac{d}{dt} \oint_S \vec{E} \cdot d\vec{S}$$

# Maxwell's Equations in vacuum

- The vacuum is a linear, homogeneous, isotropic and dispersion less medium
- Since there is no current or electric charge is present in the vacuum, hence Maxwell's equations reads as
- These equations have a simple solution in terms of traveling sinusoidal waves, with the electric and magnetic fields direction orthogonal to each other and the direction of travel

$$\vec{\nabla} \cdot \vec{E} = 0$$

$$\vec{\nabla} \cdot \vec{B} = 0$$

$$\vec{\nabla} \times \vec{E} = -\frac{\partial \vec{B}}{\partial t}$$

$$\vec{\nabla} \times \vec{B} = \mu_0 \epsilon_0 \frac{\partial \vec{E}}{\partial t}$$

# Maxwell's Equations Inside Matter

Maxwell's equations are modified for polarized and magnetized materials. For linear materials the polarization  $P$  and magnetization  $M$  is given by

$$\vec{P} = \epsilon_0 \chi_e \vec{E}$$

$$\vec{M} = \chi_m \vec{H}$$

And the  $D$  and  $B$  fields are related to  $E$  and  $H$  by

$$\vec{D} = \epsilon_0 \vec{E} + \vec{P} = (1 + \chi_e) \epsilon_0 \vec{E} = \epsilon \vec{E}$$

$$\vec{B} = \mu_0 (\vec{H} + \vec{M}) = (1 + \chi_m) \mu_0 \vec{H} = \mu \vec{H}$$

Where  $\chi_e$  is the electric susceptibility of material,

$\chi_m$  is the magnetic susceptibility of material and .

# Maxwell's Equations Inside Matter (Cont'd)

- For polarized materials we have bound charges in addition to free charges

$$\sigma_b = \vec{P} \cdot \hat{n}$$

$$\rho_b = -\vec{\nabla} \cdot \vec{P}$$

- For magnetized materials we have bound currents

$$\vec{K}_b = \vec{M} \times \hat{n}$$

$$\vec{J}_b = \vec{\nabla} \times \vec{M}$$

# Maxwell's Equations Inside Matter (Cont'd)

- In electrodynamics any change in the electric polarization involves a flow of bound charges resulting in polarization current  $J_p$

$$J_p = \frac{\partial \vec{P}}{\partial t}$$

Polarization current density is due to linear motion of charge when the Electric polarization changes

Total charge density

$$\rho_t = \rho_f + \rho_b$$

Total current density

$$J_t = J_f + J_b + J_p$$

# Maxwell's Equations Inside Matter (Cont'd)

- Maxwell's equations inside matter are written as

$$\vec{\nabla} \cdot \vec{E} = \frac{\rho_t}{\epsilon_0}$$

$$\vec{\nabla} \cdot \vec{B} = 0$$

$$\vec{\nabla} \times \vec{E} = -\frac{\partial \vec{B}}{\partial t}$$

$$\vec{\nabla} \times \vec{B} = \mu_0 \vec{J}_f + \mu_0 \vec{J}_p + \mu_0 \vec{J}_b + \mu_0 \epsilon_0 \frac{\partial \vec{E}}{\partial t}$$

$$\vec{\nabla} \times \frac{\vec{B}}{\mu_0} = \vec{J}_f + \frac{\partial \vec{P}}{\partial t} + \vec{\nabla} \times \vec{M} + \epsilon_0 \frac{\partial \vec{E}}{\partial t}$$

$$\vec{\nabla} \times \left( \frac{\vec{B}}{\mu_0} - \vec{M} \right) = \vec{J}_f + \frac{\partial}{\partial t} (\epsilon_0 \vec{E} + \vec{P})$$

$$\vec{\nabla} \times \vec{H} = \vec{J}_f + \frac{\partial \vec{D}}{\partial t}$$

# Maxwell's Equations Inside Matter (Cont'd)

- In non-dispersive, isotropic media  $\epsilon$  and  $\mu$  are time-independent scalars, and Maxwell's equations reduces to

$$\vec{\nabla} \cdot \epsilon \vec{E} = \rho$$

$$\vec{\nabla} \cdot \mu \vec{H} = 0$$

$$\vec{\nabla} \times \vec{E} = -\mu \frac{\partial \vec{H}}{\partial t}$$

$$\vec{\nabla} \times \vec{H} = \vec{J} + \epsilon \frac{\partial \vec{E}}{\partial t}$$

# Maxwell's Equations Inside Matter (Cont'd)

- In uniform (homogeneous) medium  $\epsilon$  and  $\mu$  are independent of position, hence Maxwell's equations reads as

$$\vec{\nabla} \cdot \vec{D} = \rho_f$$

$$\oint_S \vec{D} \cdot d\vec{S} = Q_{f\ enc}$$

$$\vec{\nabla} \cdot \vec{H} = 0$$

$$\oint_S \vec{H} \cdot d\vec{S} = 0$$

$$\vec{\nabla} \times \vec{E} = -\mu \frac{\partial \vec{H}}{\partial t}$$

$$\oint_C \vec{E} \cdot d\vec{l} = -\mu \frac{d}{dt} \int_S \vec{H} \cdot d\vec{S}$$

$$\vec{\nabla} \times \vec{H} = \vec{J}_f + \epsilon \frac{\partial \vec{E}}{\partial t}$$

$$\oint_C \vec{H} \cdot d\vec{l} = I_{f\ enc} + \frac{d}{dt} \int_S \vec{D} \cdot d\vec{S}$$

Generally,  $\epsilon$  and  $\mu$  can be rank-2 tensor (3X3 matrices) describing birefringent anisotropic materials.

# The Electromagnetic Wave from Maxwell's Equations

Take curl of

$$\vec{\nabla} \times \vec{E} = -\frac{\partial \vec{B}}{\partial t}$$

$$\vec{\nabla} \times \vec{\nabla} \times \vec{E} = \vec{\nabla} \times \left[ -\frac{\partial \vec{B}}{\partial t} \right]$$

Change the order of differentiation on the R.H.S

$$\vec{\nabla} \times \vec{\nabla} \times \vec{E} = -\frac{\partial}{\partial t} [\vec{\nabla} \times \vec{B}]$$

# The Electromagnetic Wave from Maxwell's Equations (cont'd)

As

$$\vec{\nabla} \times \vec{B} = \mu_0 \epsilon_0 \frac{\partial \vec{E}}{\partial t}$$

Substituting for  $\vec{\nabla} \times \vec{B}$  we have

$$\vec{\nabla} \times [\vec{\nabla} \times \vec{E}] = -\frac{\partial \vec{B}}{\partial t} \Rightarrow \vec{\nabla} \times [\vec{\nabla} \times \vec{E}] = -\frac{\partial}{\partial t} \left[ \mu_0 \epsilon_0 \frac{\partial \vec{E}}{\partial t} \right]$$

$$\vec{\nabla} \times [\vec{\nabla} \times \vec{E}] = -\mu_0 \epsilon_0 \frac{\partial^2 \vec{E}}{\partial t^2}$$

•As  $\mu_0$  and  $\epsilon_0$  are constant in time

# The Electromagnetic Wave from Maxwell's Equations (cont'd)

Using the vector identity  $\vec{\nabla} \times \vec{\nabla} \times \vec{E} = -\frac{\partial^2 \vec{E}}{\partial t^2}$

becomes,  $\vec{\nabla}(\vec{\nabla} \cdot \vec{E}) - \nabla^2 \vec{E} = -\mu_o \epsilon_o \frac{\partial^2 \vec{E}}{\partial t^2}$

In free space  $\vec{\nabla} \cdot \vec{E} = 0$

And we are left with the wave equation

$$\nabla^2 \vec{E} - \mu_o \epsilon_o \frac{\partial^2 \vec{E}}{\partial t^2} = 0$$

# The Electromagnetic Wave from Maxwell's Equations (cont'd)

Similarly the wave equation for magnetic field

$$\nabla^2 \vec{B} - \mu_0 \epsilon_0 \frac{\partial^2 \vec{B}}{\partial t^2} = 0$$

where,

$$c = \frac{1}{\sqrt{\mu_0 \epsilon_0}}$$

# Solution of Electromagnetic Waves in Vacuum

The solutions to the wave equations, where there is no source charge is present

$$\nabla^2 \vec{E} - \mu_0 \epsilon_0 \frac{\partial^2 \vec{E}}{\partial t^2} = 0 \quad \nabla^2 \vec{B} - \mu_0 \epsilon_0 \frac{\partial^2 \vec{B}}{\partial t^2} = 0$$

can be plane waves, obtained by method of separation of variables

# Solution of Electromagnetic Waves in Vacuum (Cont'd)

$$\vec{E} = \vec{E}_o e^{i(\vec{k} \cdot \vec{r} - \omega t)}$$

$$\vec{B} = \vec{B}_o e^{i(\vec{k} \cdot \vec{r} - \omega t)}$$

Where  $E_o$  and  $B_o$  are the complex amplitudes of electric and magnetic fields and related to each other by relation

$$\vec{B} = \frac{1}{c} (\hat{k} \times \vec{E})$$

Where  $\hat{k}$  is a propagation vector.

# Electromagnetic Plane waves

- Plane electromagnetic waves can be expressed as

$$\vec{E} = \vec{E}_o e^{i(\vec{k}\cdot\vec{r} - \omega t)} \hat{n}$$

$$\vec{B} = \frac{1}{c} \vec{E}_o e^{i(\vec{k}\cdot\vec{r} - \omega t)} (\hat{k} \times \hat{n}) = \frac{1}{c} (\hat{k} \times \vec{E})$$

Where  $\hat{n}$  is the polarization vector.

# Electromagnetic Plane waves

The real electric and magnetic fields in a monochromatic plane wave with propagation vector  $\hat{k}$  and polarization  $\hat{n}$  are therefore

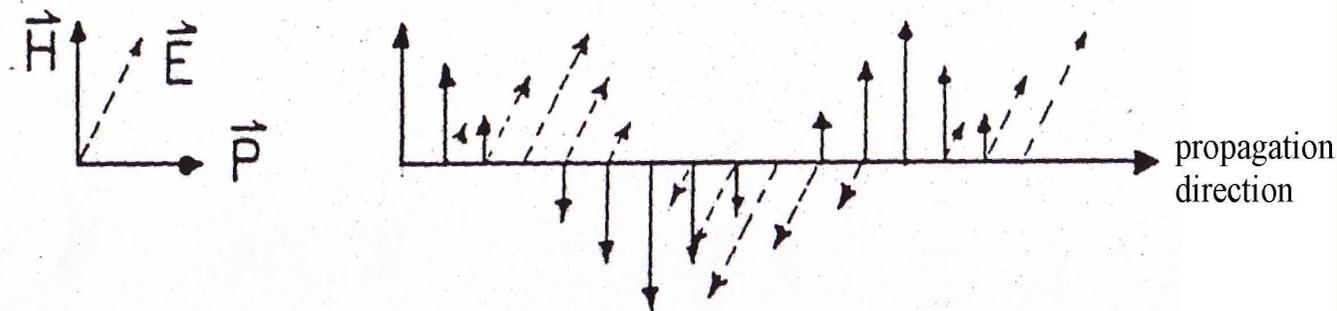
$$\vec{E}(\vec{r}, t) = E_o \cos(\vec{k} \cdot \vec{r} - \omega t) \hat{n}$$

$$\vec{B}(\vec{r}, t) = \frac{1}{c} E_o \cos(\vec{k} \cdot \vec{r} - \omega t) (\vec{k} \times \hat{n})$$

# Polarization

- The polarization is specified by the orientation of the electromagnetic field.
- The plane containing the electric field is called the plane of polarization.

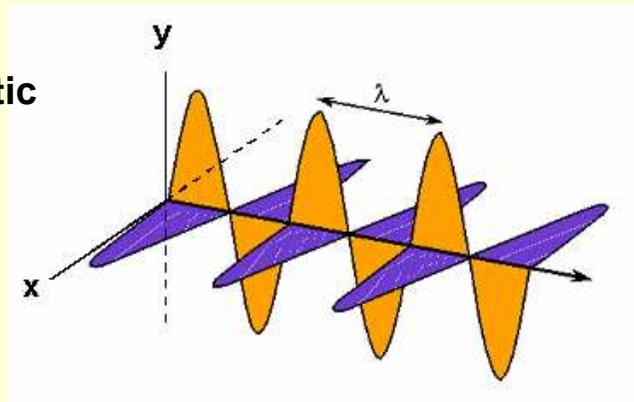
A polarized wave: E field and H field  
each oscillate in a single plane



# Polarization (Cont'd)

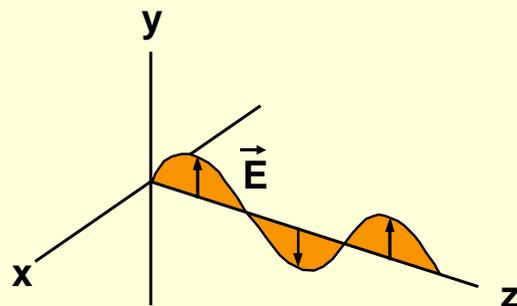
- Can be horizontal, vertical, circular, or elliptical

Electromagnetic Wave

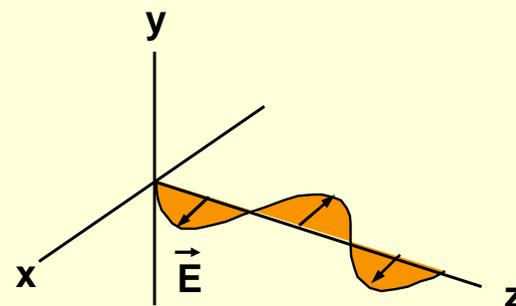


Electric Field  
Magnetic Field

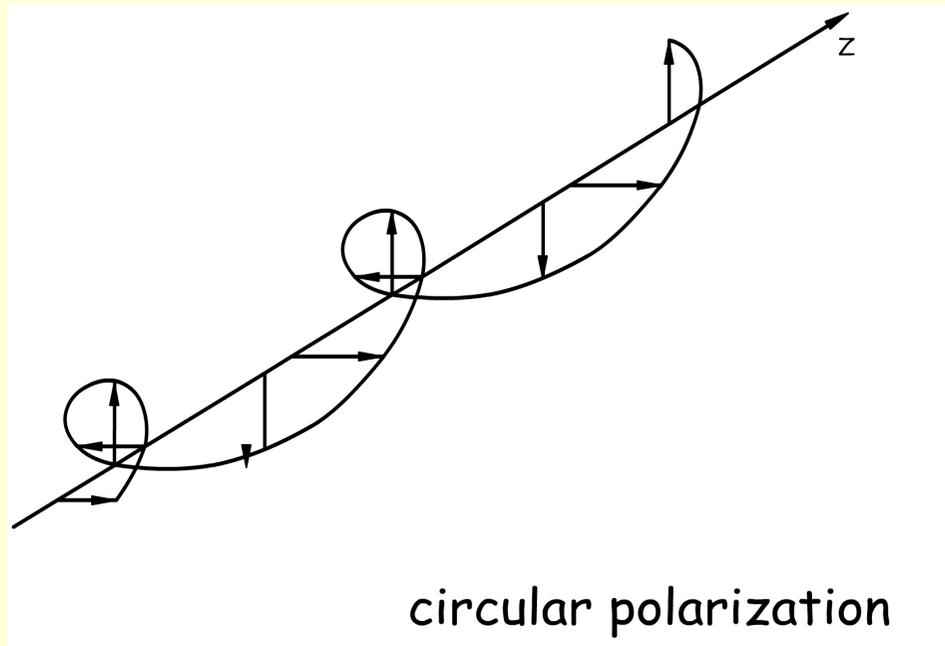
Vertical Polarization



Horizontal Polarization



# Polarization (Cont'd)



# Homogenous Wave Equations Inside Matter

Vacuum

$$\frac{1}{\mu_0 \epsilon_0} \nabla^2 \vec{E} = \frac{\partial^2 \vec{E}}{\partial t^2}$$

$$\frac{1}{\mu_0 \epsilon_0} \nabla^2 \vec{B} = \frac{\partial^2 \vec{B}}{\partial t^2}$$

Matter

$$\frac{1}{\mu \epsilon} \nabla^2 \vec{E} = \frac{\partial^2 \vec{E}}{\partial t^2}$$

$$\frac{1}{\mu \epsilon} \nabla^2 \vec{B} = \frac{\partial^2 \vec{B}}{\partial t^2}$$

# Homogenous Wave Equations Inside Matter (cont..)

Permittivity:  $\epsilon = \epsilon_r \epsilon_0$  ( $\epsilon_r$  is dielectric constant)

Permeability:  $\mu = \mu_r \mu_0$  ( $\mu_r$  is relative permeability  $\approx 1$ )

$$v = \frac{1}{\sqrt{\mu\epsilon}} = \frac{1}{\sqrt{\mu_r \mu_0 \epsilon_r \epsilon_0}} = \frac{1}{\underbrace{\sqrt{\mu_0 \epsilon_0}}_{=c}} \frac{1}{\underbrace{\sqrt{\mu_r \epsilon_r}}_{=n}}$$

$$v = \frac{c}{n}$$

$n$ =Refractive Index

# References

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## 2. INTRODUCTION TO ELECTRODYNAMICS

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**THANK YOU**