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International Centre for Theoretical Physics**



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23 March - 9 April, 2009

Scintillation Impacts on GPS

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Scintillation Impacts on GPS

**Workshop for Sustainable Development in Navigation Studies
and
Technology in Africa**

March 23 – April 9, 2009

K. Groves*, C. Carrano

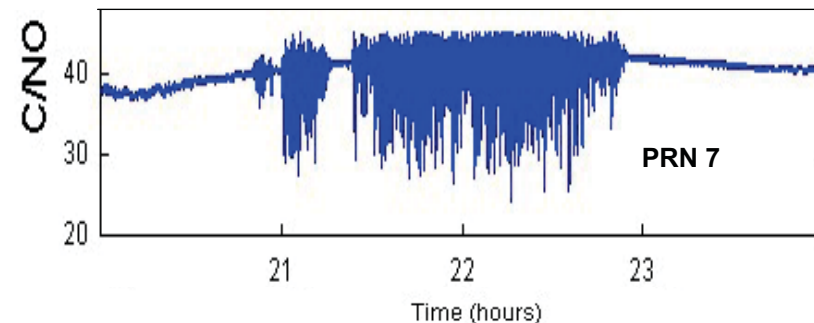
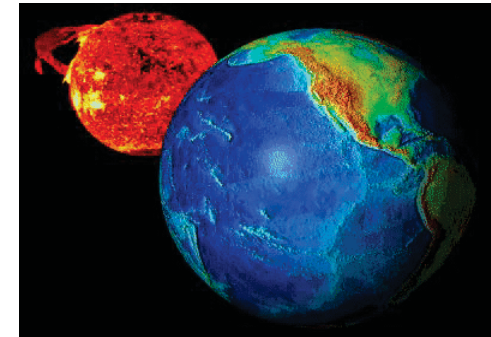
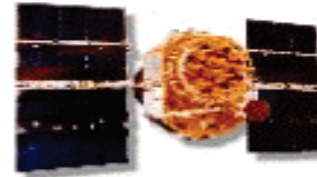
***Space Vehicles Directorate
Air Force Research Laboratory**



OUTLINE



- ~~• Principles of GPS operation~~
- ~~• Ionosphere 101~~
- ~~• Ranging errors: Group delay~~
- Scintillation effects
- Modeling impacts
- Conclusions



Look how far you've come!



A short review of plasma physics



Nominal dielectric permittivity in “smooth” ionosphere

$$\langle \varepsilon \rangle = \left(1 - \frac{f_p^2}{f^2} \right) \varepsilon_o \qquad f_p^2 = \frac{e^2 N}{m_e \varepsilon_o}$$

Linearized description when weak density fluctuations are present

$$\varepsilon = \langle \varepsilon \rangle (1 + \varepsilon_1(r, t)) = \varepsilon_o \left[\left(1 - \frac{f_p^2}{f^2} \right) + \left(\frac{f_p^2}{f^2} \right) \frac{\Delta N}{N} \right]$$

Putting in some numbers:

$$f_p \approx 10 \times 10^6 \text{ Hz}$$

$$f = 1.575 \times 10^9 \text{ Hz}$$

$$\Delta N / N \approx 0.10$$

$$\varepsilon = \varepsilon_o \underbrace{\left[1 - 4 \times 10^{-5} + 4 \times 10^{-6} \right]}_{\approx 1!}$$



Let's look at the integrated effect...



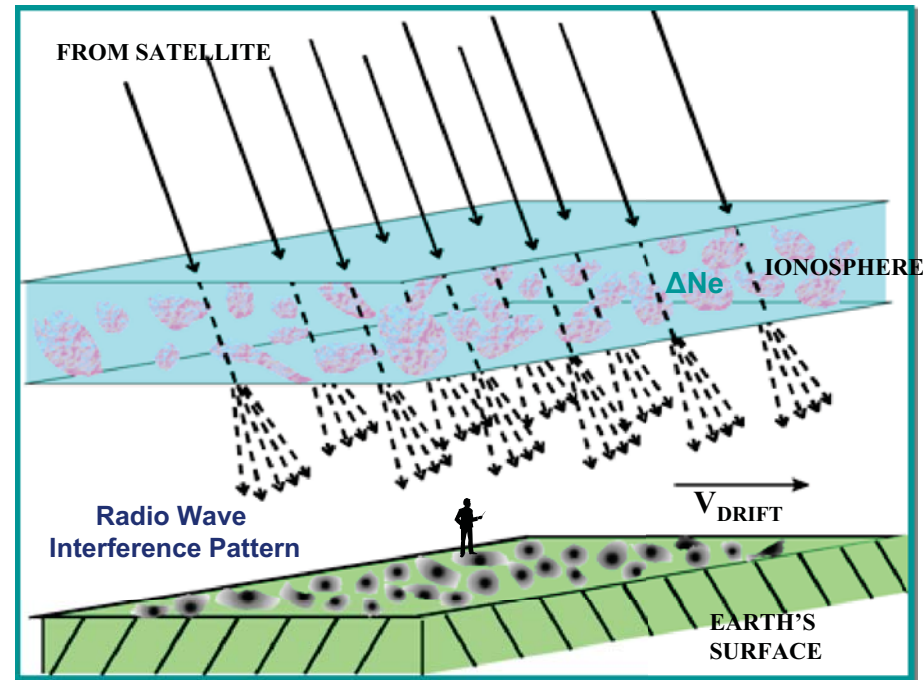
$$\tau_d = R/c + \frac{r_e c}{2\pi} \frac{N_{tot}}{f^2}$$

$$N_{tot} = \int N_e(z) dz$$

$$\varphi = 2\pi f R/c - \underbrace{r_e c \frac{N_{tot}}{f}}_{\delta\varphi}$$

Phase change due
to ionized layer $\delta\varphi$

$$\delta\varphi \approx 5 \times TEC \text{ radians}$$



- Phase variations on wavefront cause diffraction pattern on ground
- A phase changes of $\sim \pi$ radians (i.e., 0.6 TEC units) required for total destructive interference
- But the variations must occur over limited spatial scale (Fresnel zone)



Amplitude Scintillation & the Fresnel Scale



S4 and σ_ϕ can be related to physical parameters through phase screen theory (Rufenach, 1972; Rino, 1979), shown in simplified form below:

$$\sigma_\phi = \frac{K}{f^2} \int \langle \Delta N^2 \rangle GF(k_N, p_N) dk$$

$$S4^2 = \frac{K'}{f^2} \int \langle \Delta N^2 \rangle GF(k_N, p_N) \sin^2(k_r / k_f)^2 dk$$

$$\text{where} \quad k_r^2 = k_x^2 + k_y^2 \quad k_f^2 = 4\pi / \lambda z$$

Intensity scintillation (S4) has vanishing contribution for irregularity scale sizes greater than the so-called Fresnel scale, $F_r = \sqrt{2\lambda z}$

where λ is the radio signal wavelength and z is the distance from the observer to the ionospheric phase screen (~350 km or more).

For GPS L1 frequency, F_r is typically 400-500 meters; density fluctuations larger than this scale size will not cause GPS amplitude scintillations.



Implications for the Ionosphere

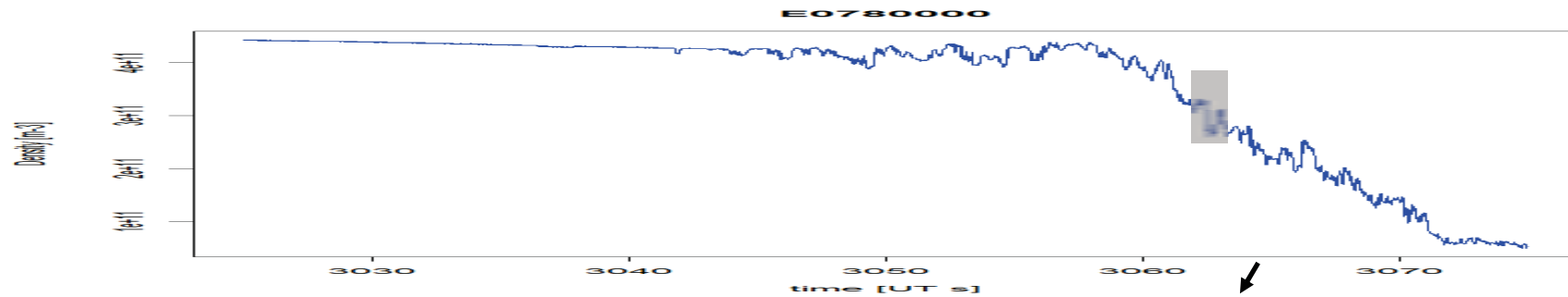


So that means at L1 we need ~0.6 TEC unit variations over spatial scales of a few 100 meters to achieve strong scintillation; lesser variations will cause correspondingly weaker intensity fluctuations

- Solar max TEC ~ 50-100
 - Small relative density fluctuations required
- Solar min TEC ~ 1-5 (nighttime)
 - Large relative density fluctuations required
- Consistent with expectations, GPS scintillations are generally weak during solar minimum
- Scintillation impacts on GPS are limited to solar max periods (3-4 years around peak)



Checking our expectations



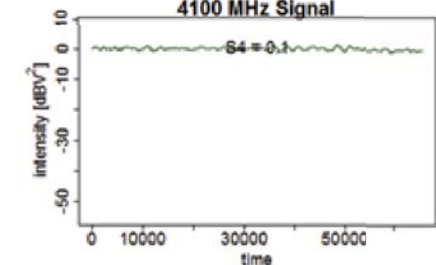
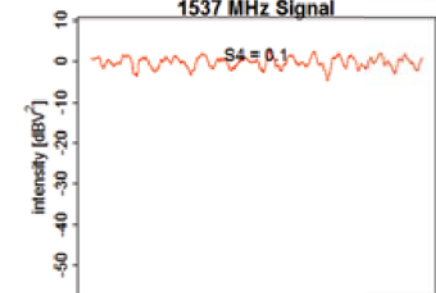
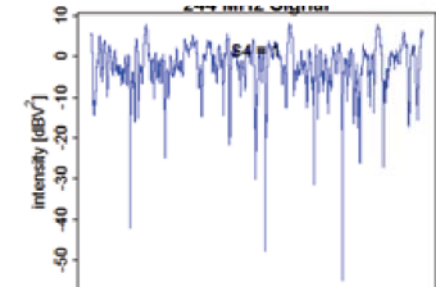
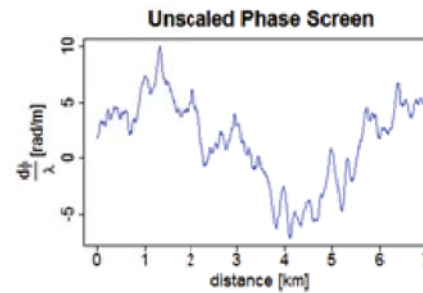
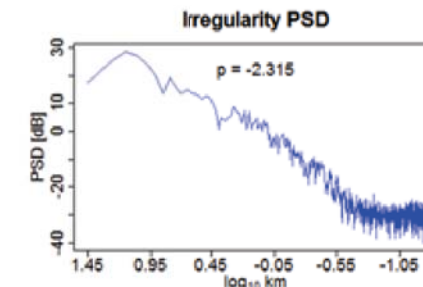
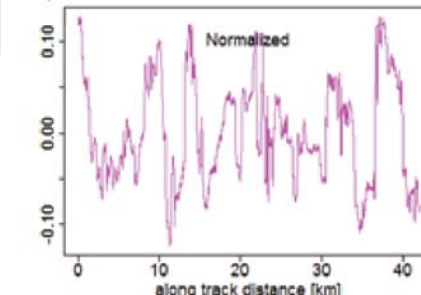
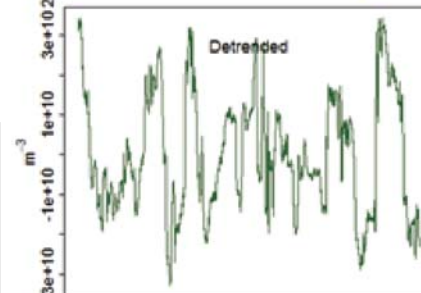
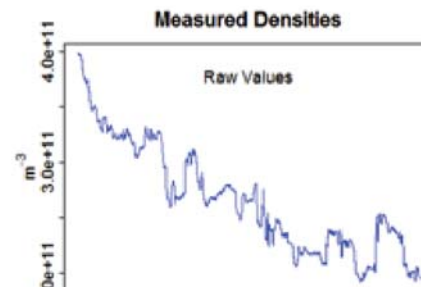
rms $\Delta N/N = 2.1\%$

$S_4(244) = 1.0$

$S_4(1537) = 0.1$

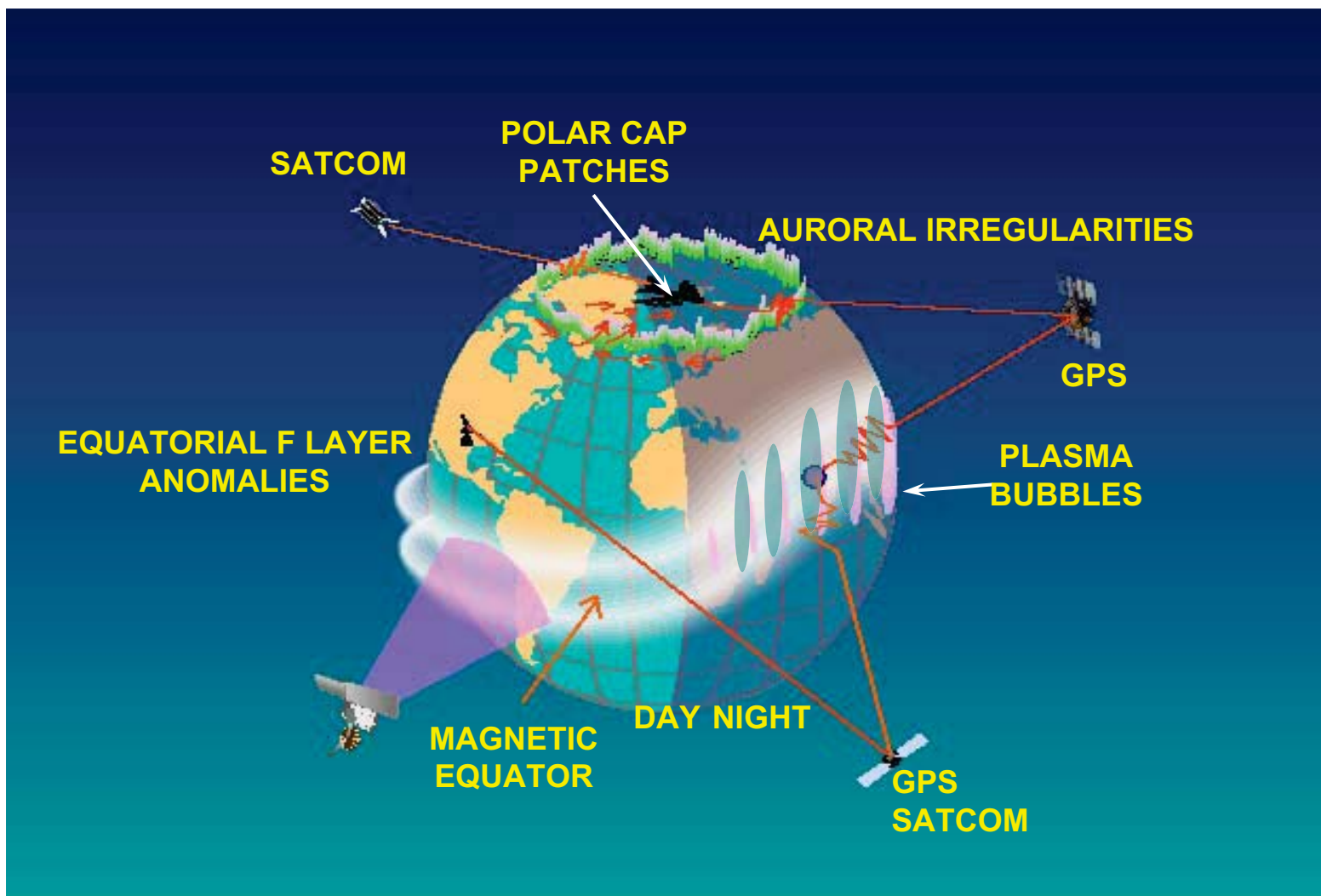
$S_4(4100) = 0.1$

Assuming that ΔN is constant predicts reasonable scintillation values





Disturbed Ionospheric Regions and Systems Affected by Scintillation

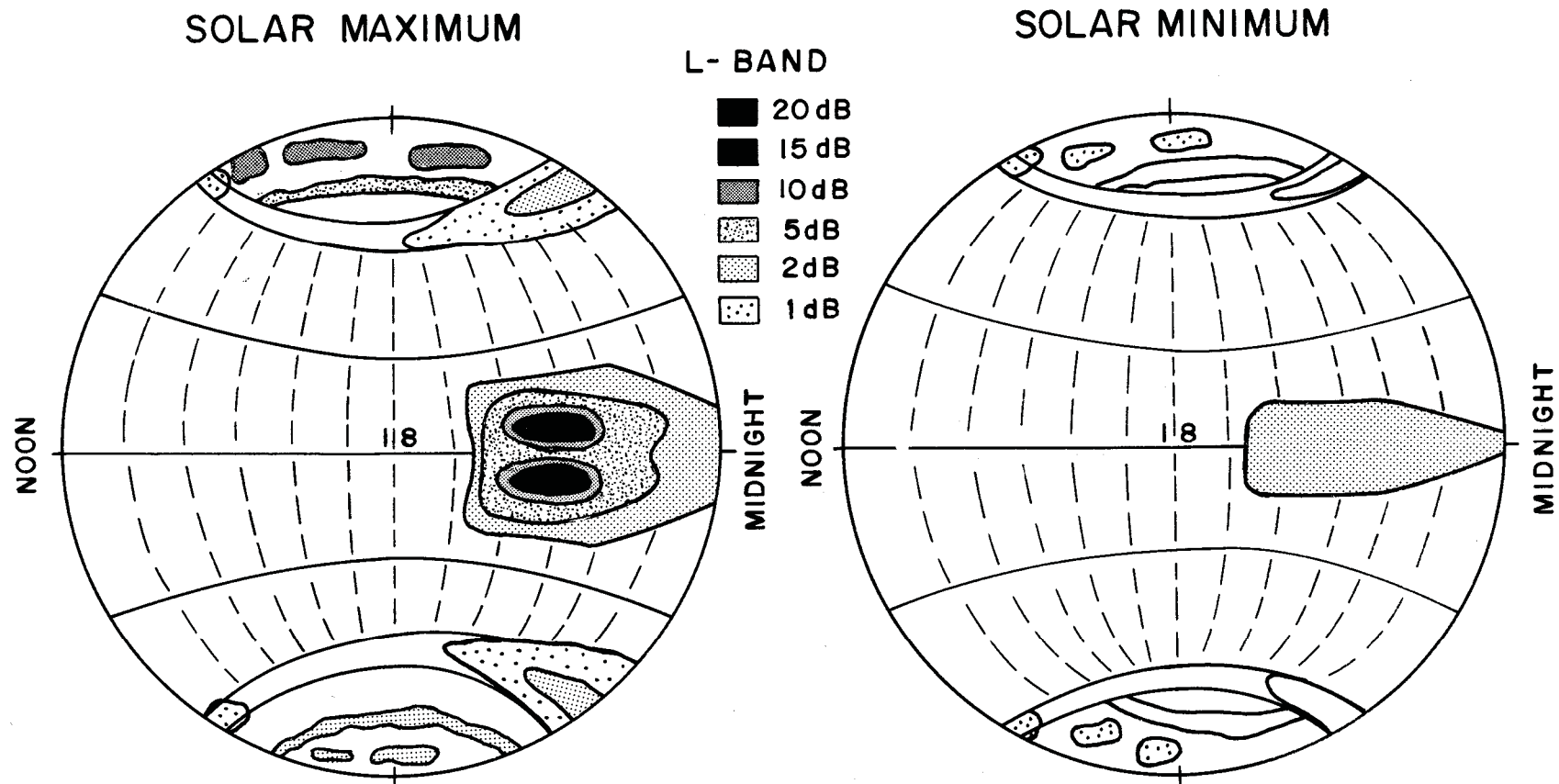




Global Morphology



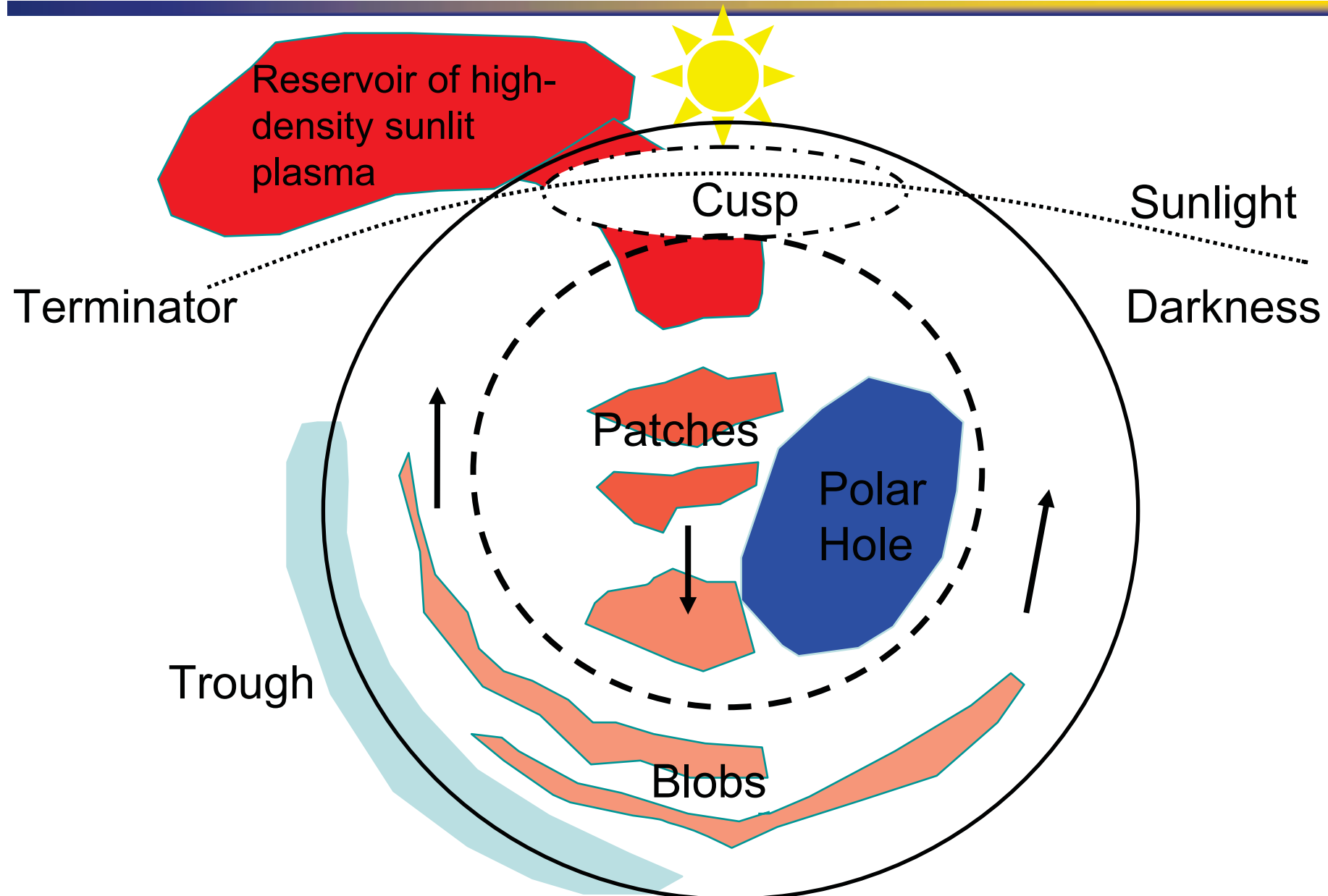
"WORST CASE" FADING DEPTHS AT L-BAND



[After Basu, et al.]

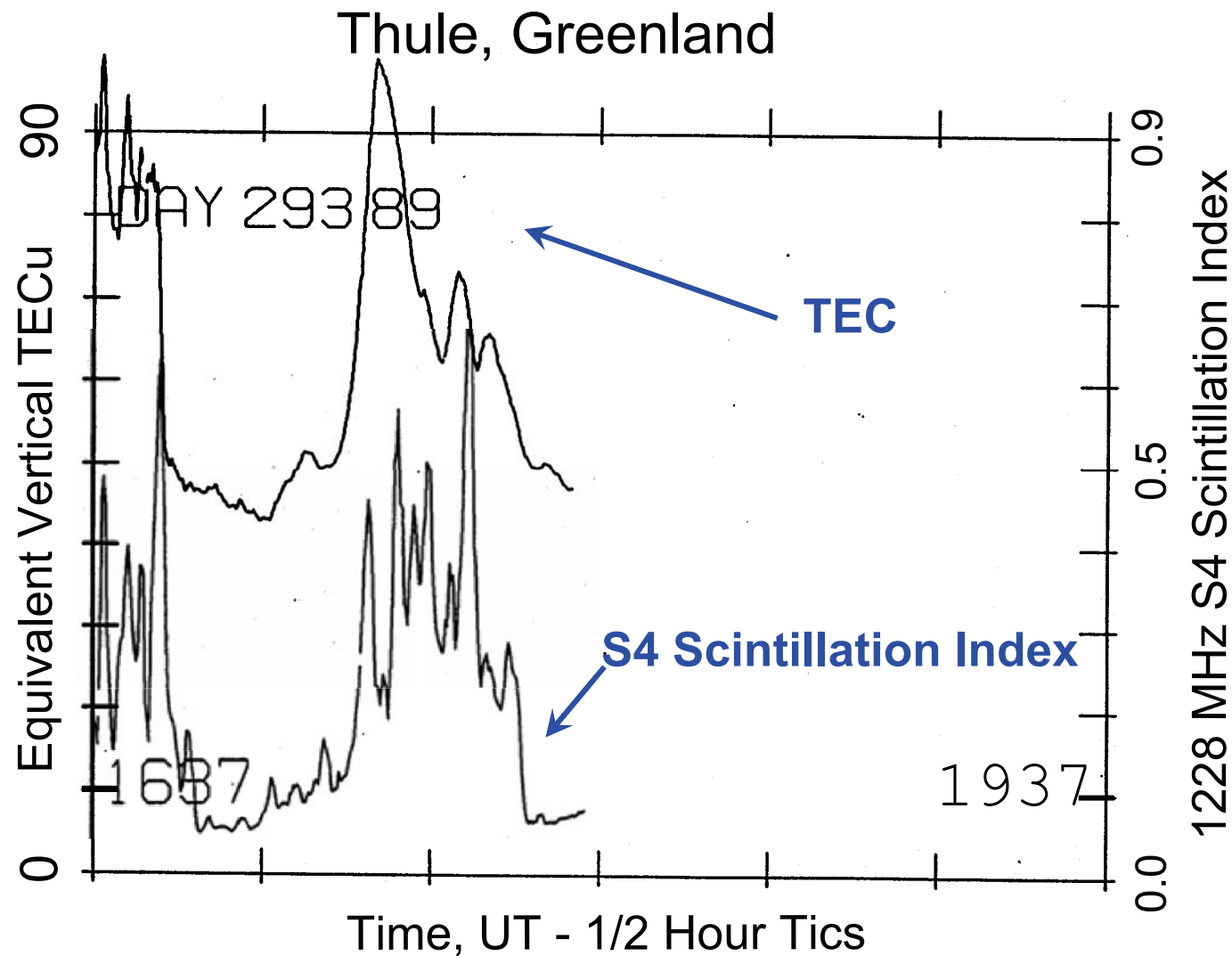


Polar Ionosphere Density Regimes (Winter, $B_z < 0$)





TEC Fluctuations and Scintillation during Patch Events





Equatorial Scintillation vs Polar



EQUATOR

- Well-ordered zonal progression after instability develops
- Modest drift velocities (~ 100 m/sec)
- Macro-scale changes relatively slowly

POLAR

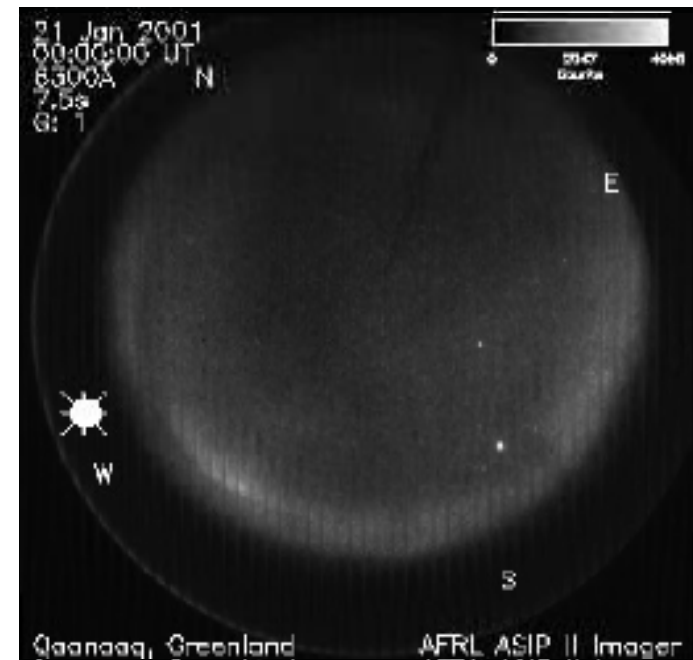
- Chaotic development & evolution
- Large drift velocities ($\sim >1$ km/sec)
 - Much larger spatial scales affect signal raypaths
- Driven by external forcing (magnetosphere) difficult to predict



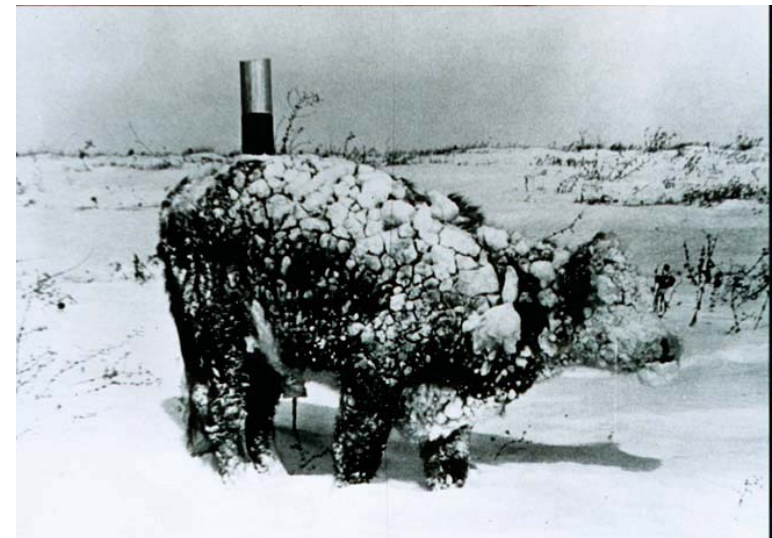
Equatorial Scintillation vs Polar



movie



movie



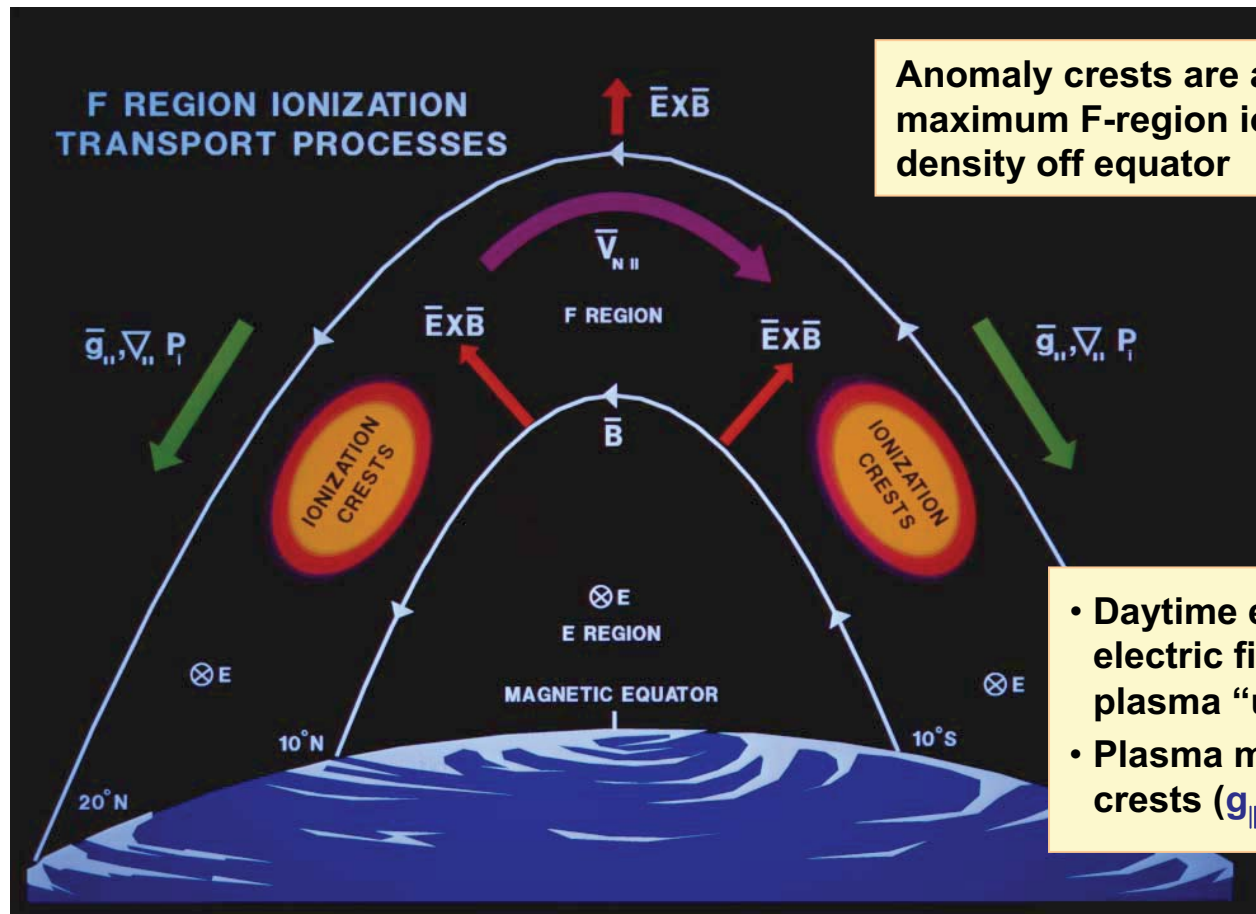


What Are Equatorial Dynamics?

Formation of Anomaly Region



- Presence of anomaly crests strengthens off-equator scintillations
- State of anomaly formation is indicative of equatorial dynamics



Anomaly crests are areas of maximum F-region ionization density off equator

- Daytime eastward electric field (E) drives plasma “up” ($E \times B$)
- Plasma moves toward crests ($g_{\parallel}, \nabla_{\parallel} P_{\parallel}$)

(View looking east)

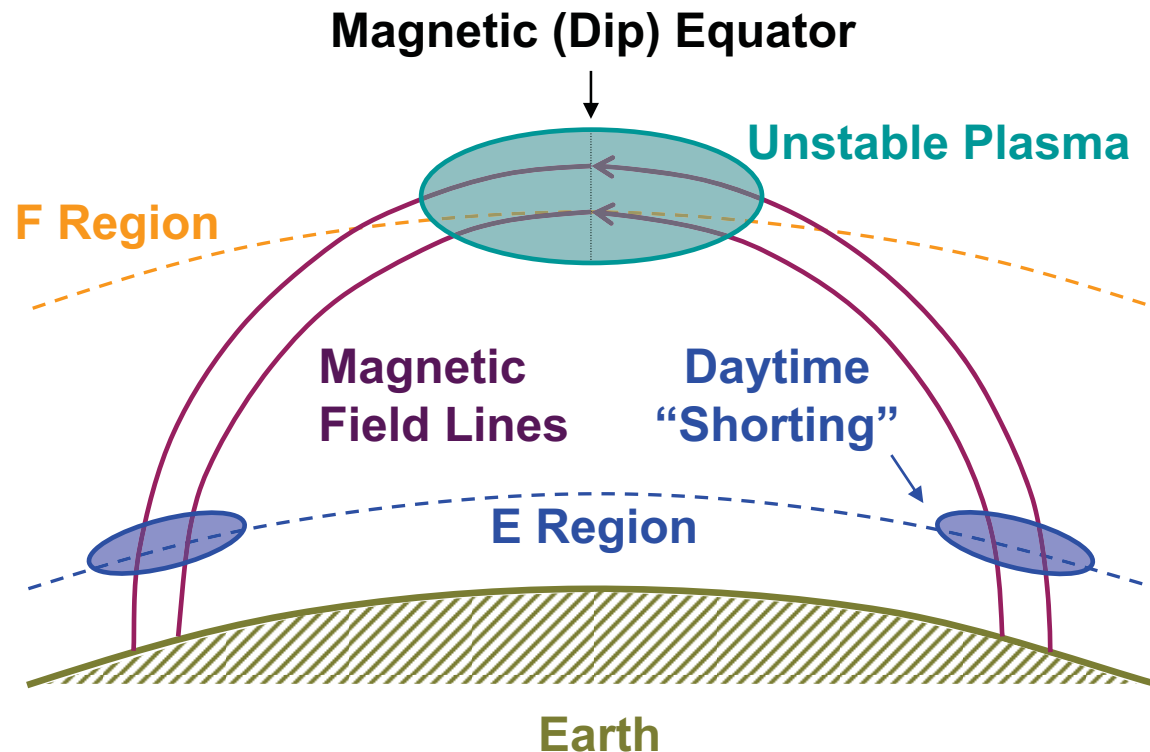


Why Do Disturbances Form?

Unique Equatorial Magnetic Field Geometry

Equatorial scintillation occurs because plasma disturbances readily form with horizontal magnetic field

- Plasma moves easily along **field lines**, which act as conductors
- Horizontal field lines support plasma against gravity—**unstable configuration**
- E-region “**shorts out**” electrodynamic instability during the day



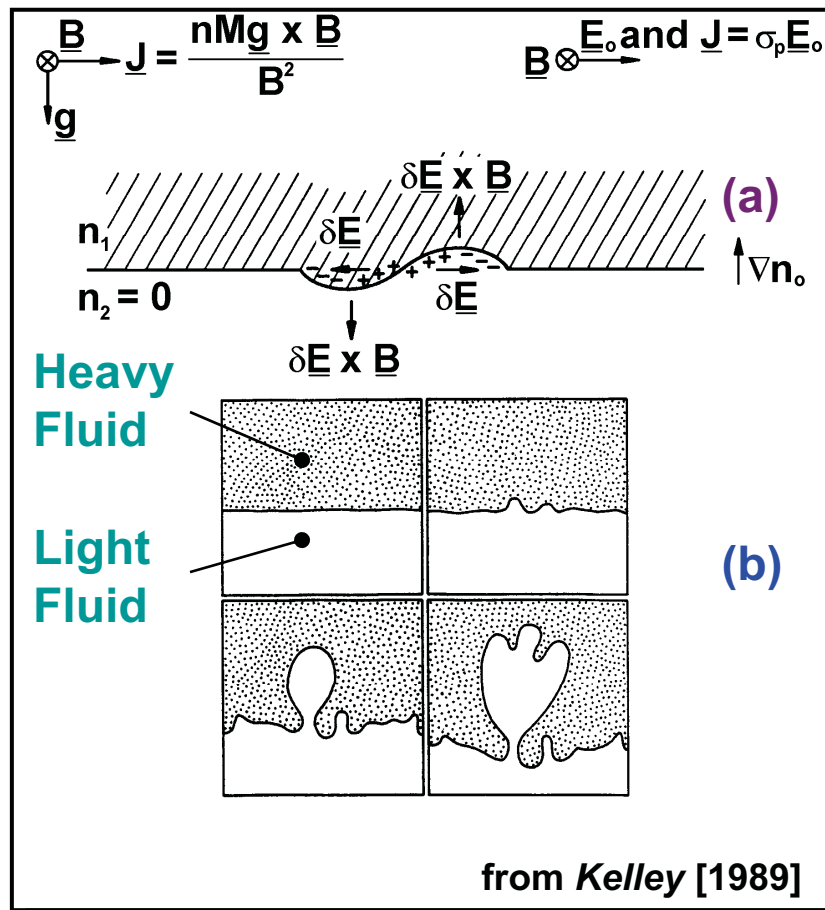


What Is Instability Process?

Basic Plasma Instability



View along bottomside of ionosphere
(E-W section, looking N from equator)



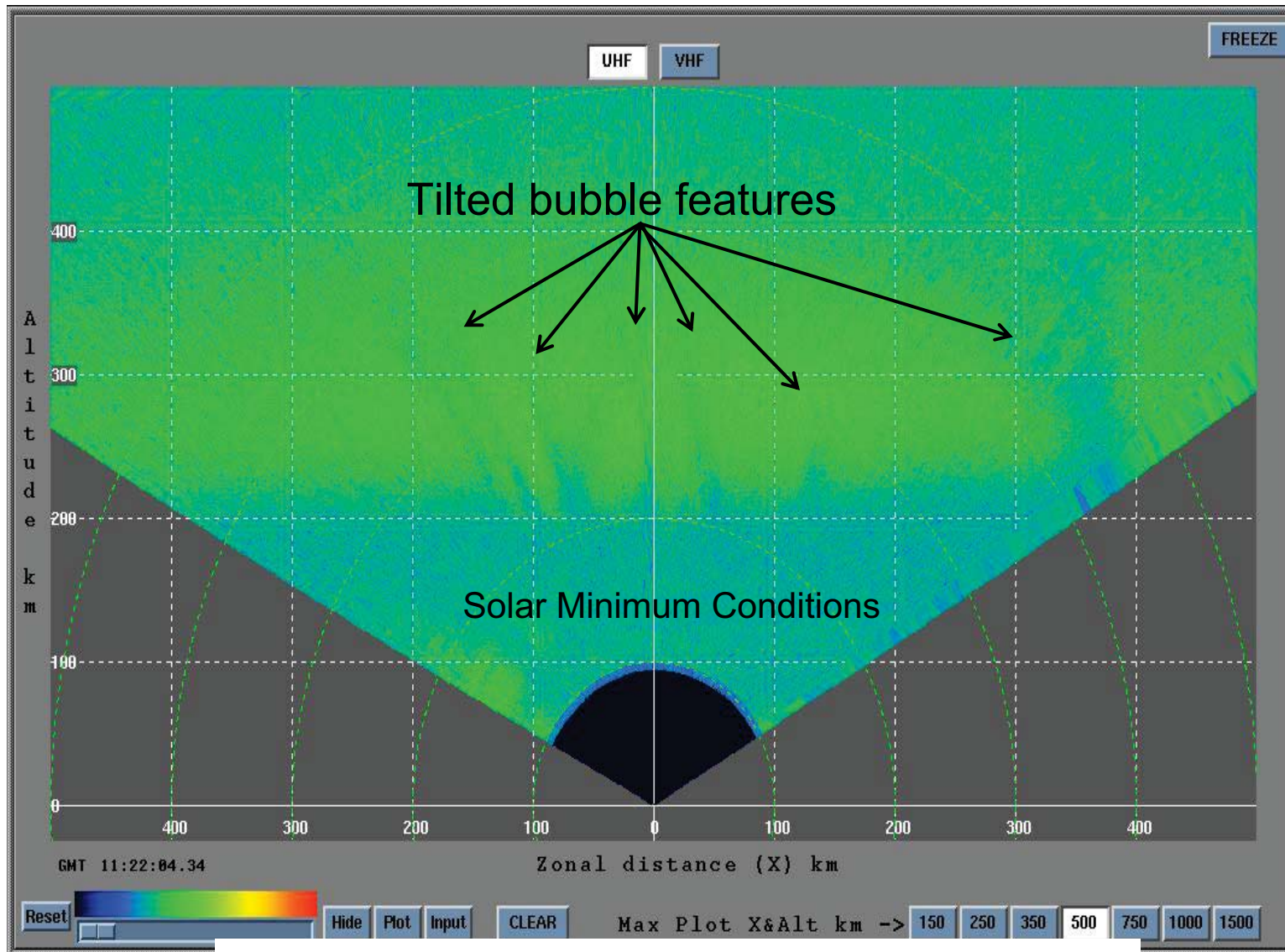
Plasma supported by
horizontal field lines against
gravity is unstable

- (a) Bottomside unstable to perturbations (density gradient against gravity)
- (b) Analogy with fluid Rayleigh-Taylor instability
- Perturbations start at large scales (100s km)
- Cascade to smaller scales (200 km to 30 cm)



ALTAIR Incoherent Scatter Radar Scan

27 Sep 2008 11:22 UT



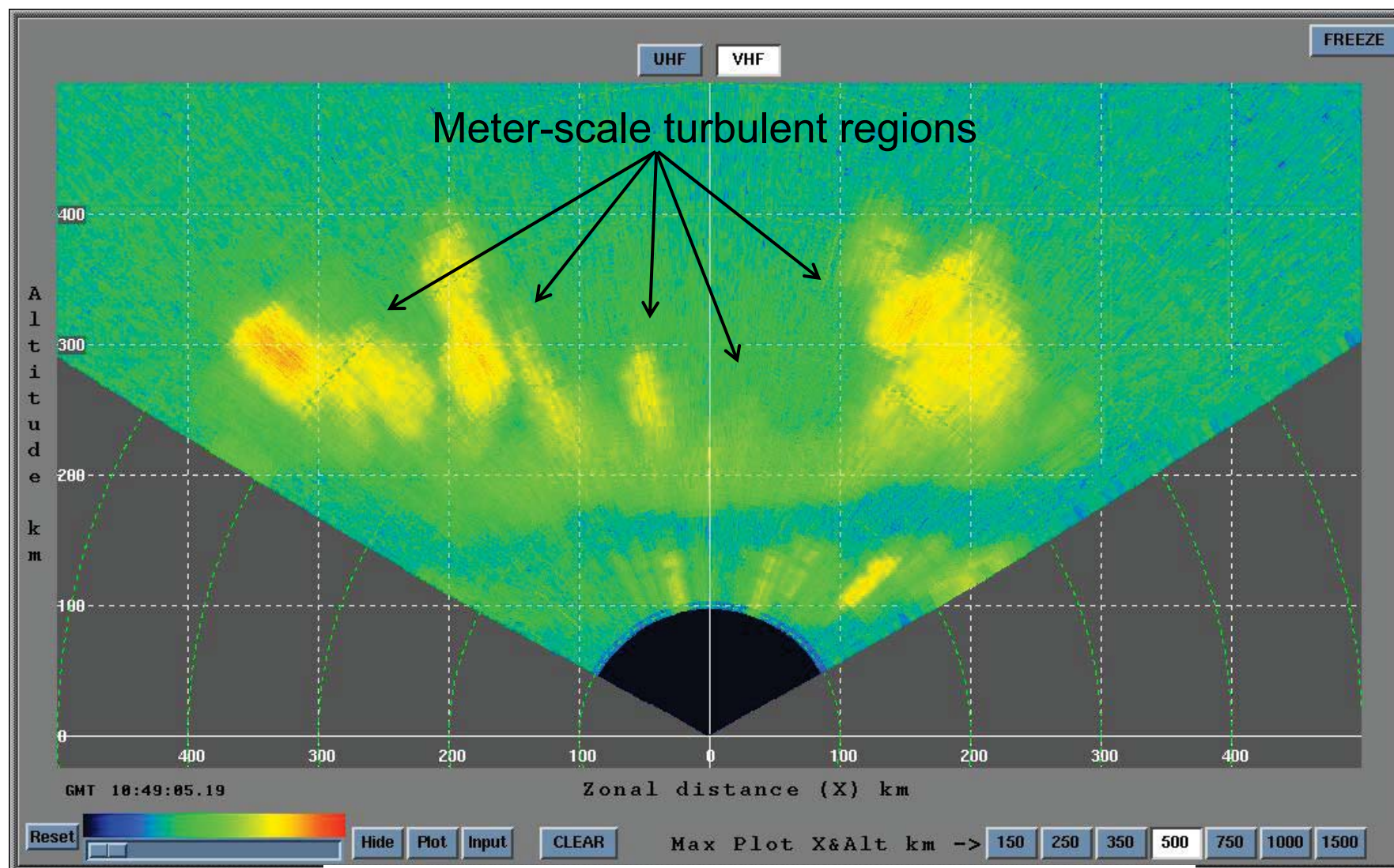
Preliminary result: Real-time display

From J. M. Retterer



ALTAIR Coherent Scatter Radar Scan

27 Sep 2008 10:49 UT

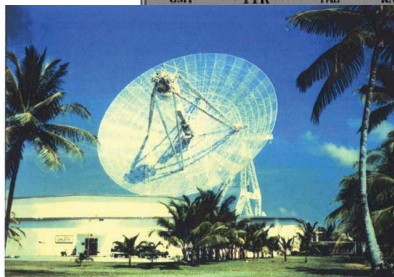
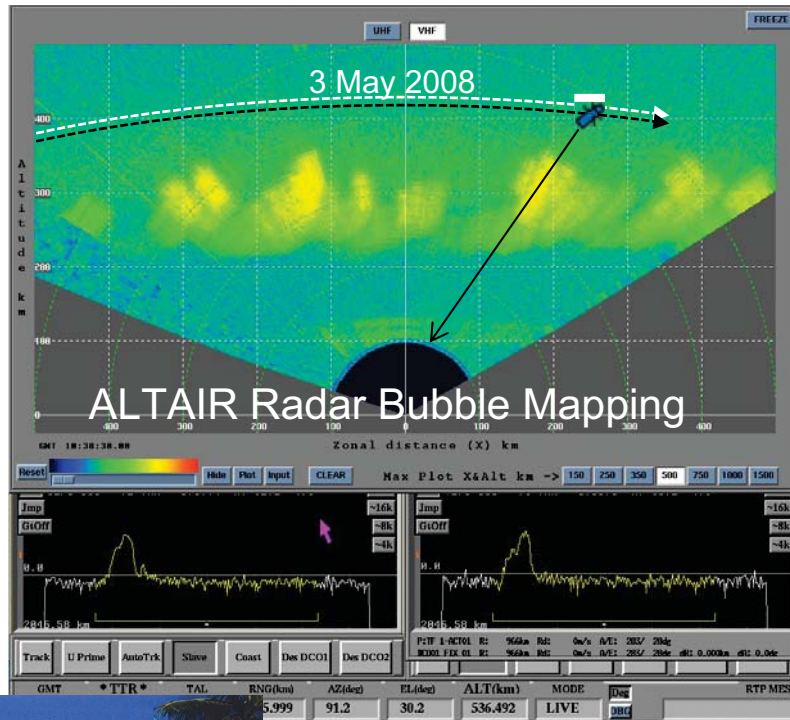


Preliminary result: Real-time display

From J. M. Retterer

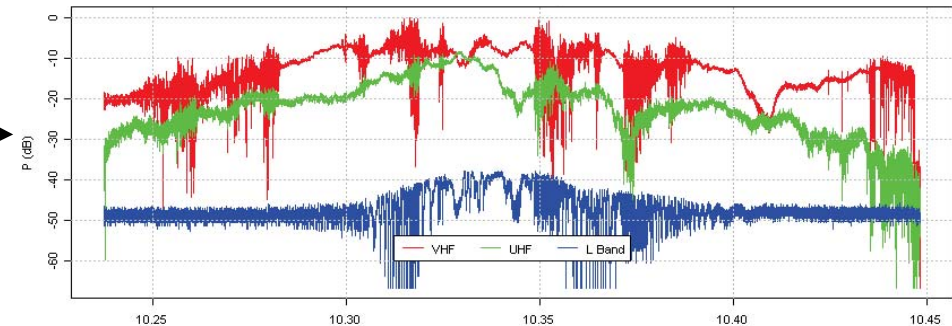


Ground-based Scintillation Nowcast Validation Kwajalein Atoll, M.I. May 2008



ALTAIR VHF/UHF Radar

C/NOFS Tri-band beacon signals



- Direct comparison of ionospheric structure observed with radar and deduced from C/NOFS beacon signal
- C/NOFS radar tracks also performed to validate in situ space-based scintillation nowcasts; analysis in progress
- Physics-based model applied to test forecast capability

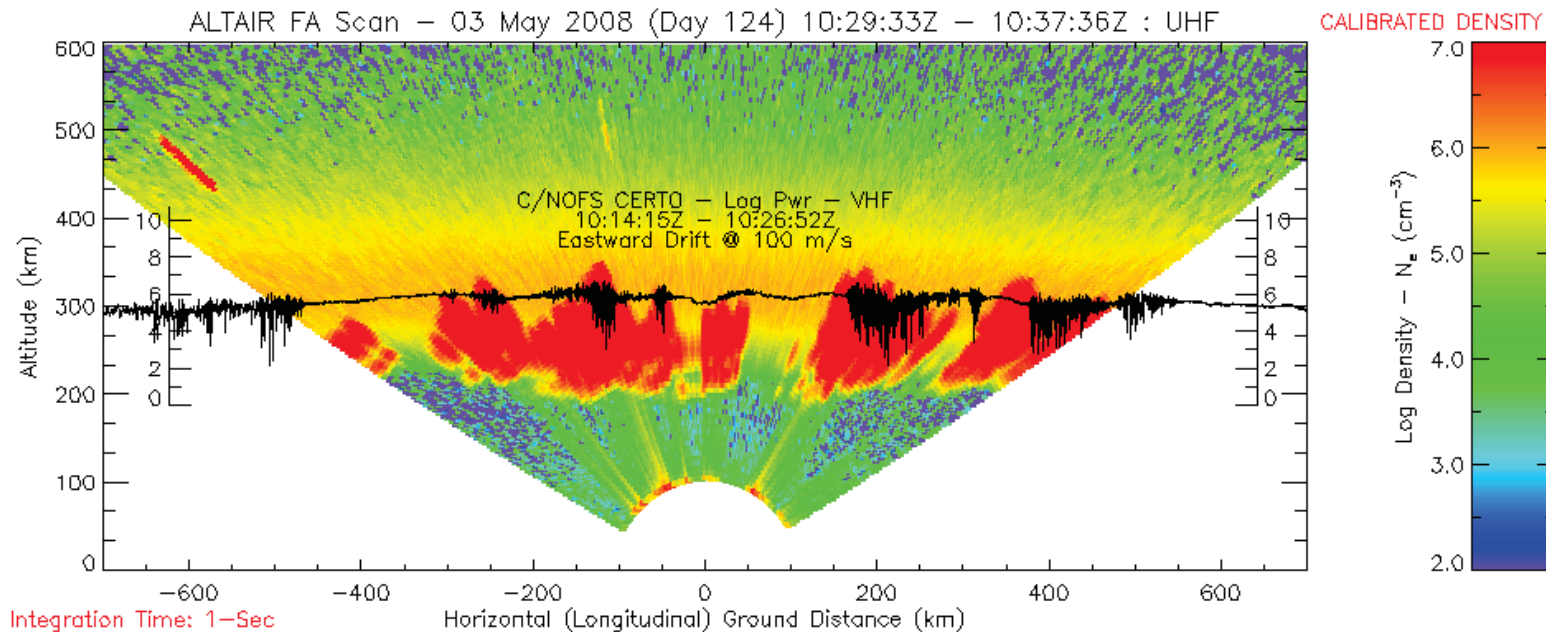
- Fused space- and ground-based scintillation nowcasts provide unprecedented accuracy and resolution



Scintillations and Radar Backscatter



- CERTO beacon on C/NOFS superimposed on ALTAIR Radar Plots: CERTO-VHF, ALTAIR-UHF-10:29Z FA Scan



- Scintillations do not occur until instability interacts with high electron density near F-region peak
- Both intensity and spatial extent of these regions increase during solar maximum

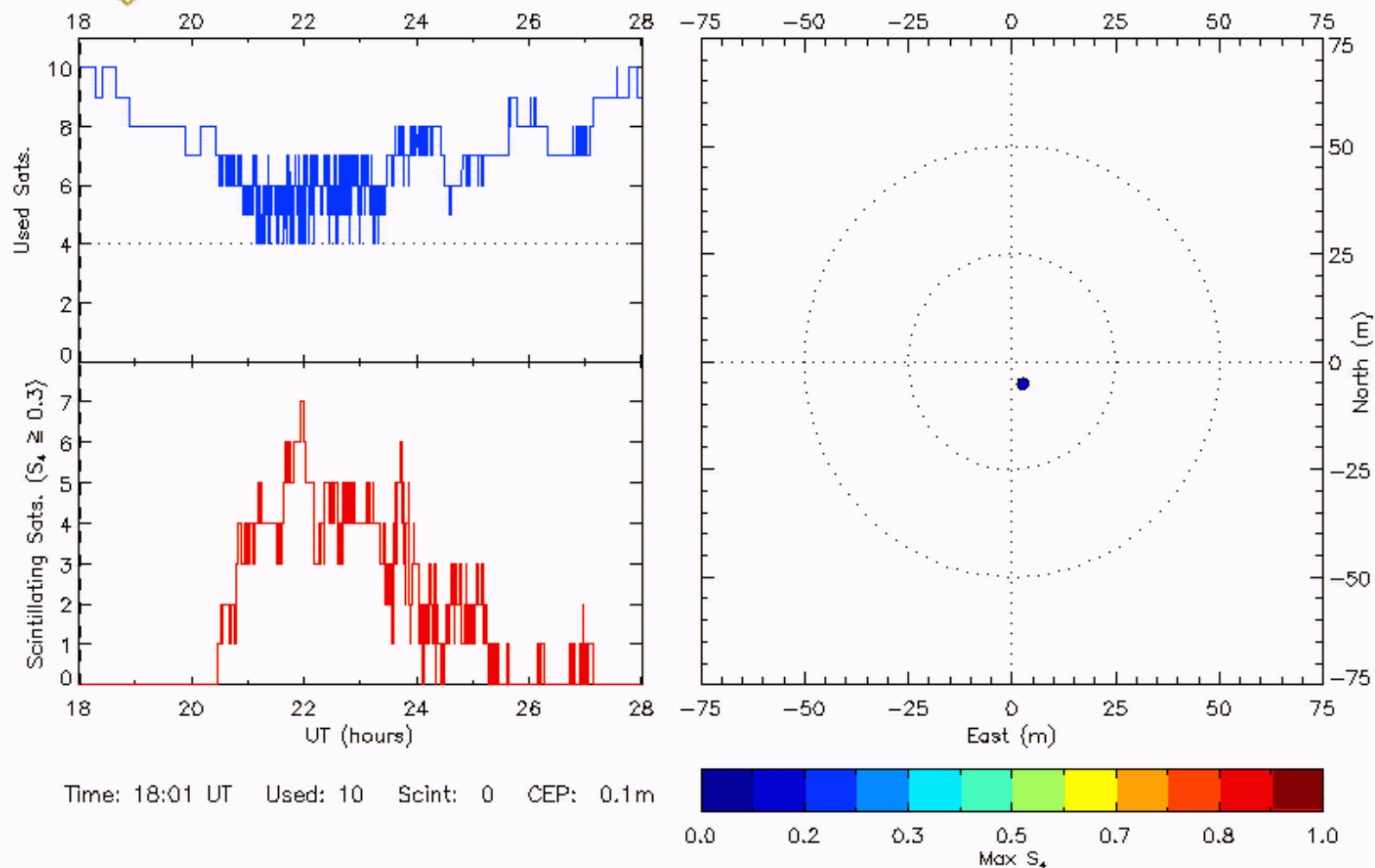


GPS Positioning Errors During Solar Max



GPS Position Error

Ascension Island, 03/16/2002





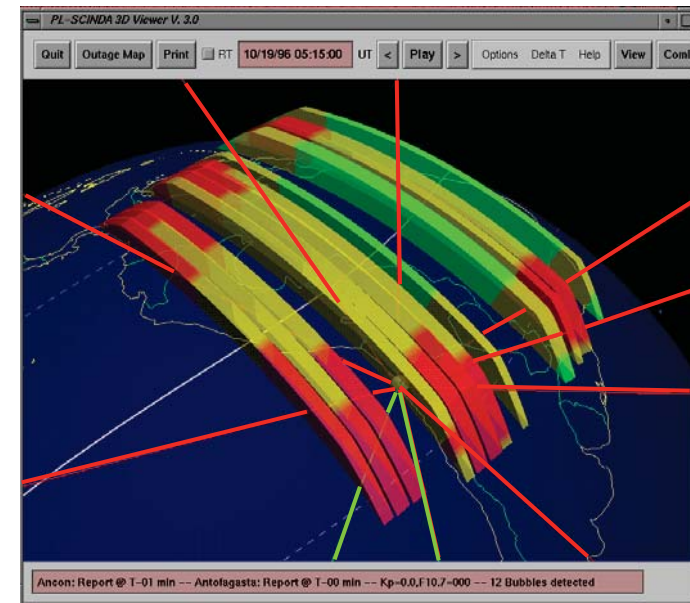
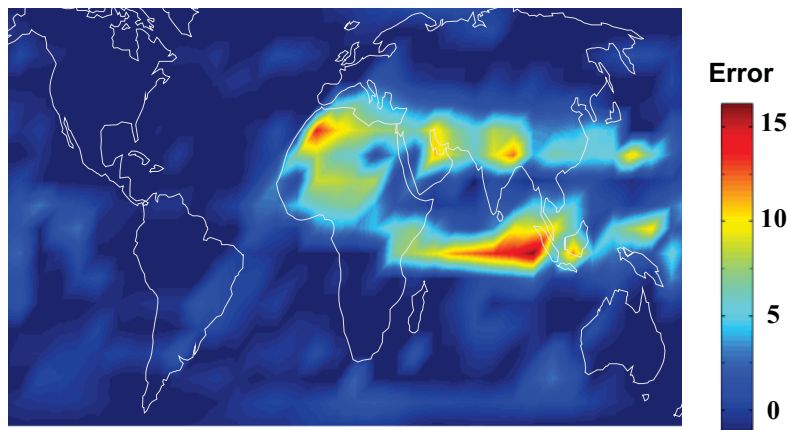
Assessing Impacts on GPS Navigation



L-Band Impacts at Solar Maximum

Multiple GPS-ground links will be affected simultaneously

Objective to produce scintillation-induced GPS position error maps



Actual Ionospheric Disturbance Structures

Equatorial scintillation structures may routinely degrade optimal navigation solution geometry; full extent of impacts under investigation

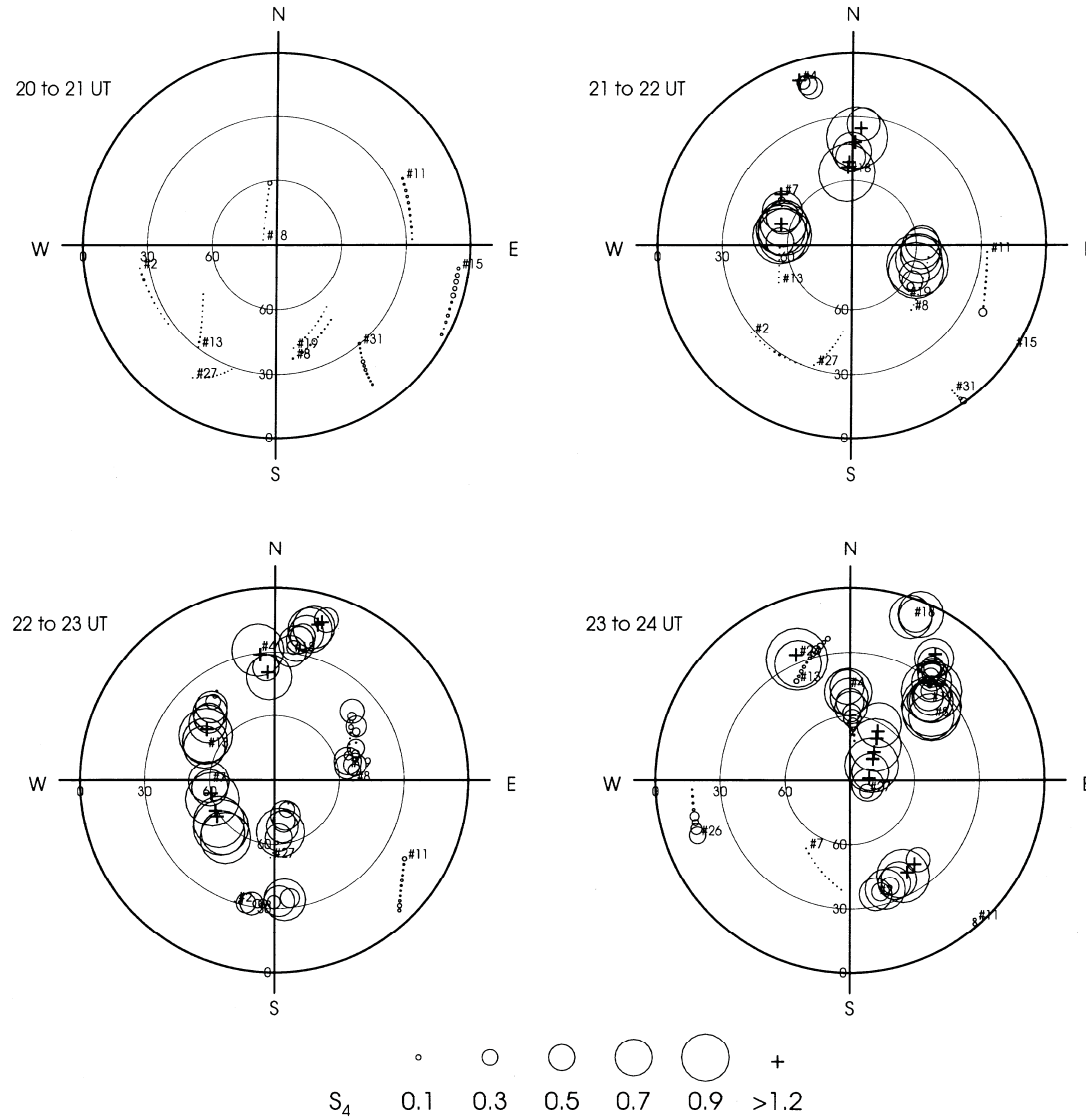
At present, we don't know threshold of pain for most GPS receivers



Scintillation Sky Coverage at Ascension Island



Ascension Island - 27 March 2000 (00087)





6300 Å All-sky Imagery

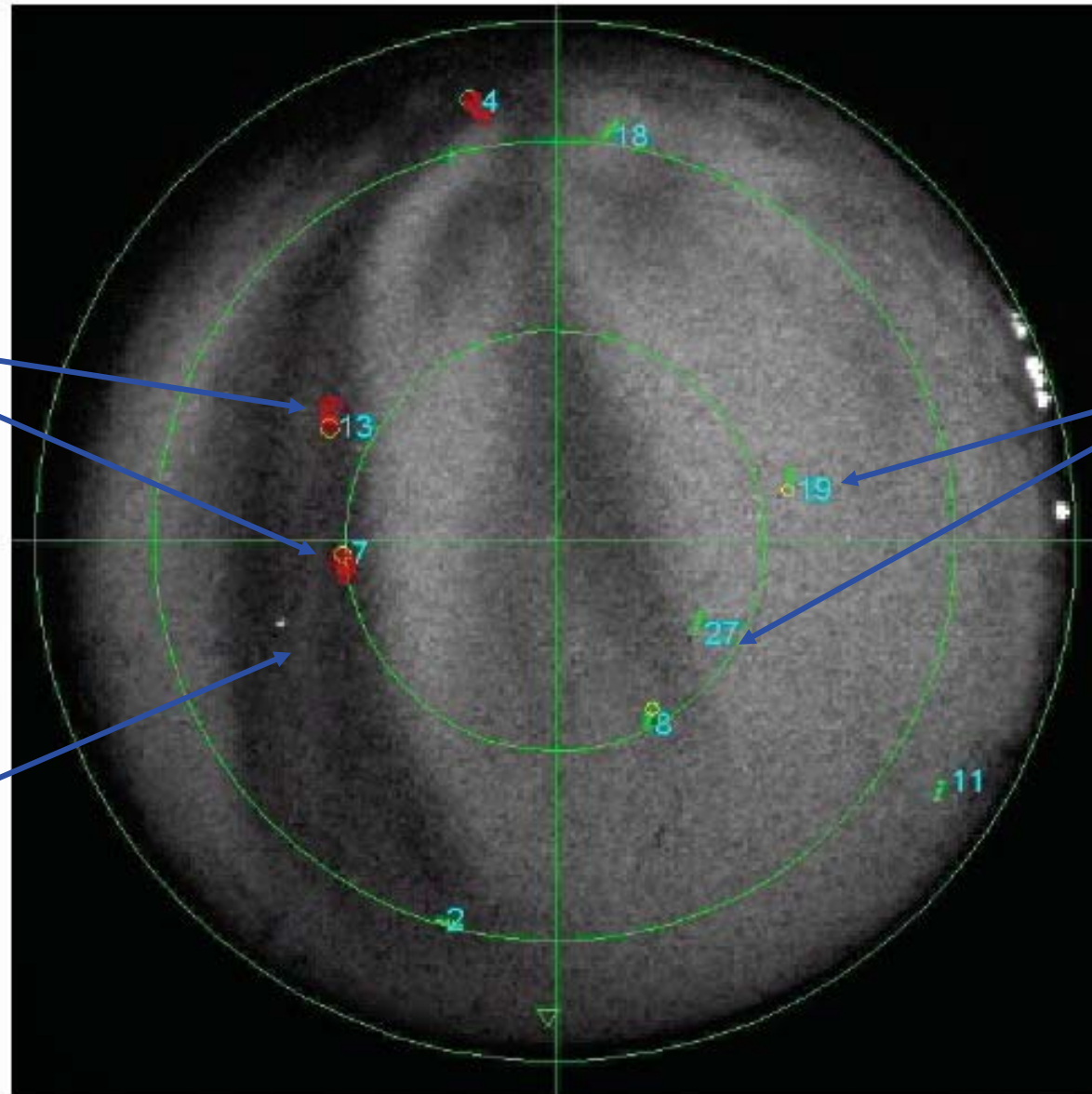


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Scintillating
GPS SATS

GPS SATS

Turbulent
Depletions



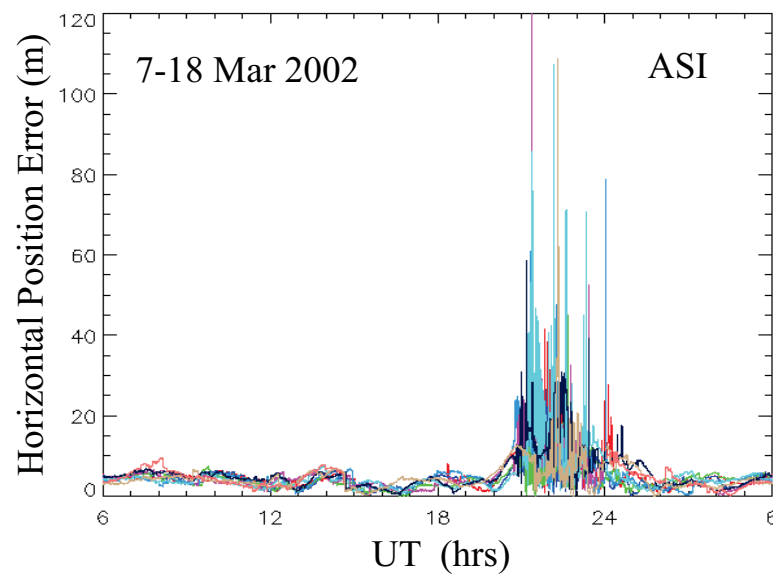


Representative Positioning Errors Near Solar Maximum

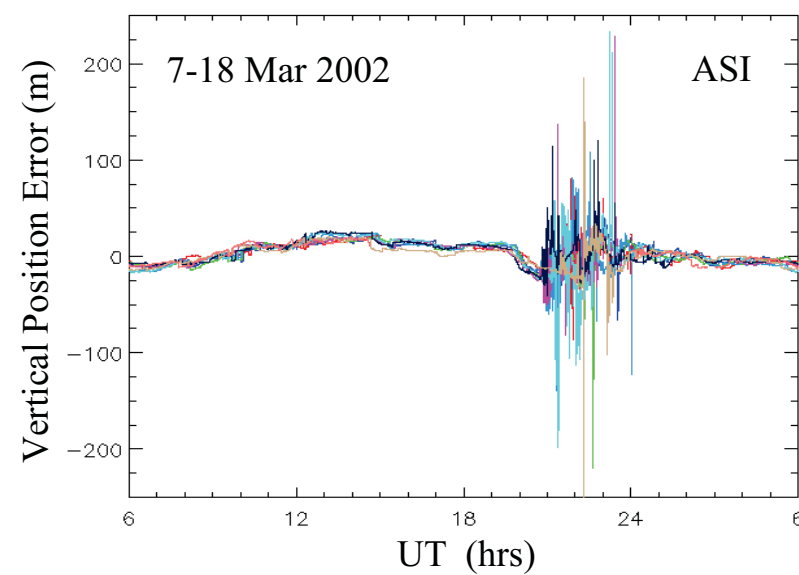


Position from dual
frequency receiver

Active Ionosphere
21:00-23:30 UT



Horizontal Error > 100 m



Vertical Error > +/- 200 m



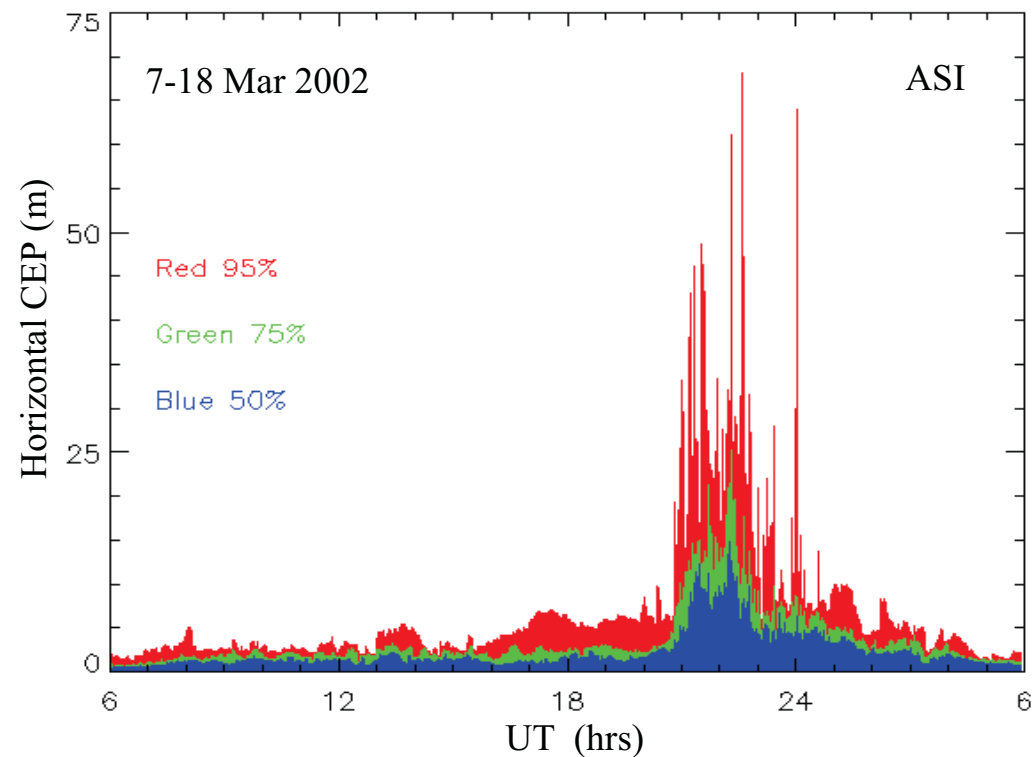
Statistical Analysis of Positioning Errors



Circular Error

Probability: probability that median error will exceed a given level

A possible metric for a position error product



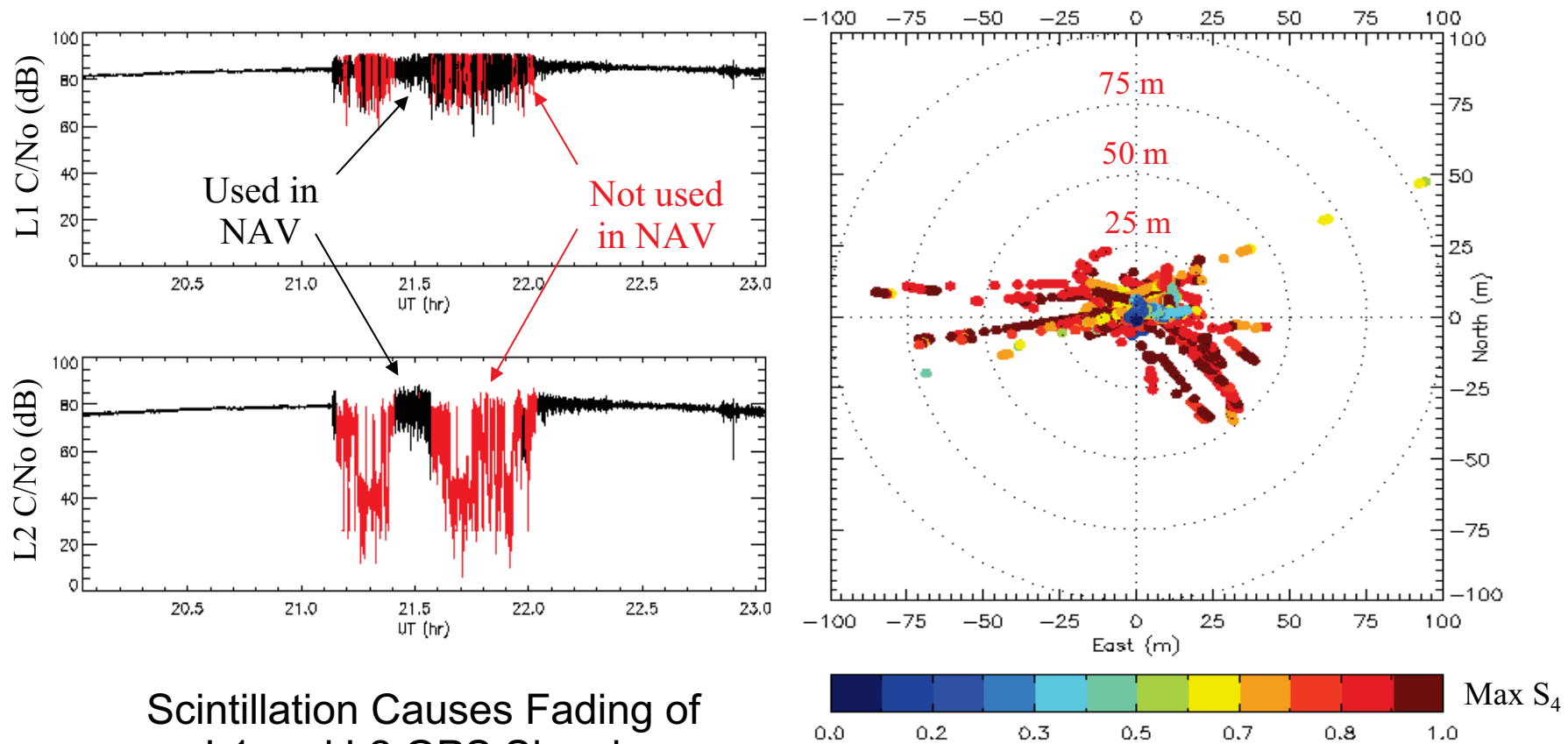
Single point positioning error (2D) better than 10 meters 95% of the time ... except during scintillation



Modeling Effects on Positioning Accuracy



16 Mar 2002, ASI



Scintillation Causes Fading of
L1 and L2 GPS Signals

Resulting Positioning Error



Geometrical Errors and Ranging Errors

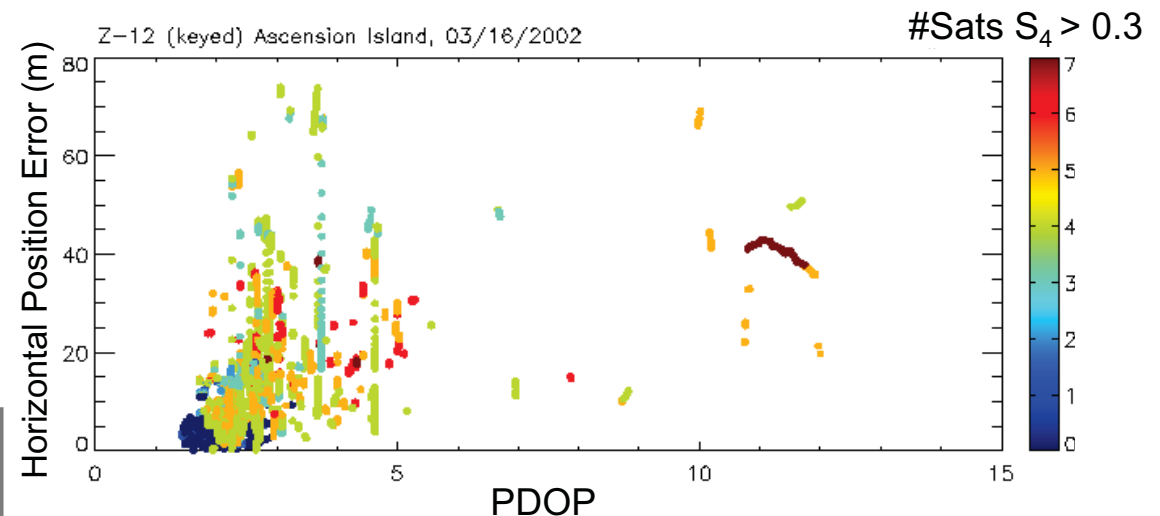
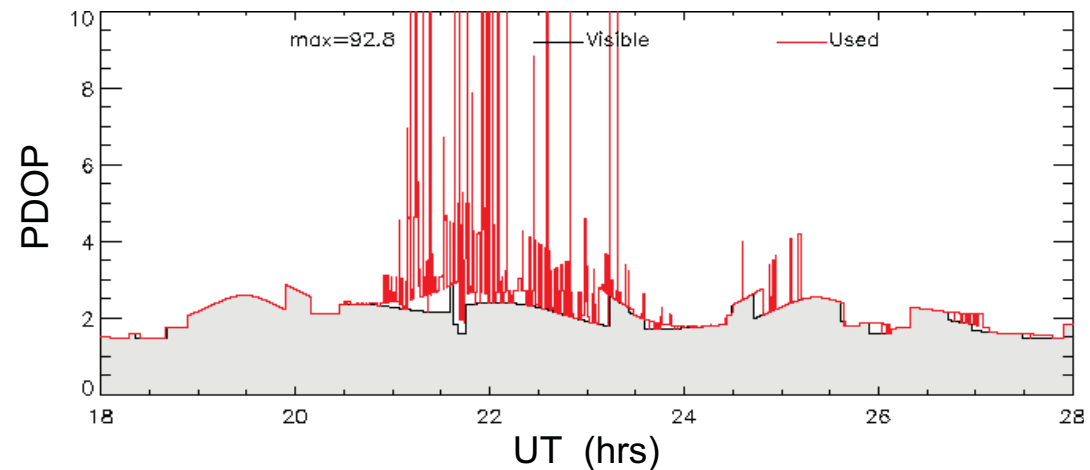


Theoretical and measured Dilution of Precision (DOP)

Spikes occur when a satellite becomes temporarily unavailable (timescale ~ seconds)

Large DOP generally leads to large errors, but ... position error can be large even when DOP is good (>70 m with PDOP of 3)!

Conclusion: scintillation causes ranging errors





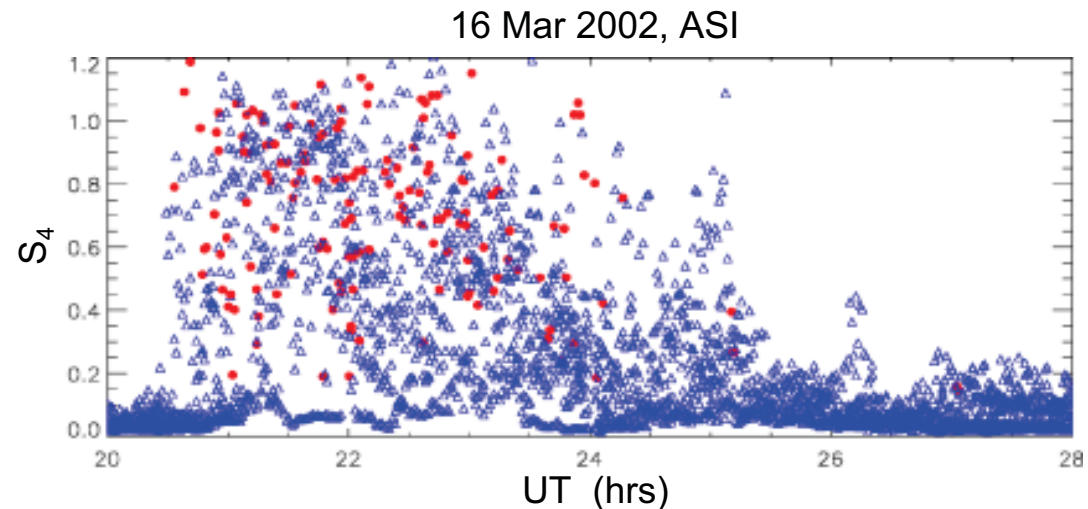
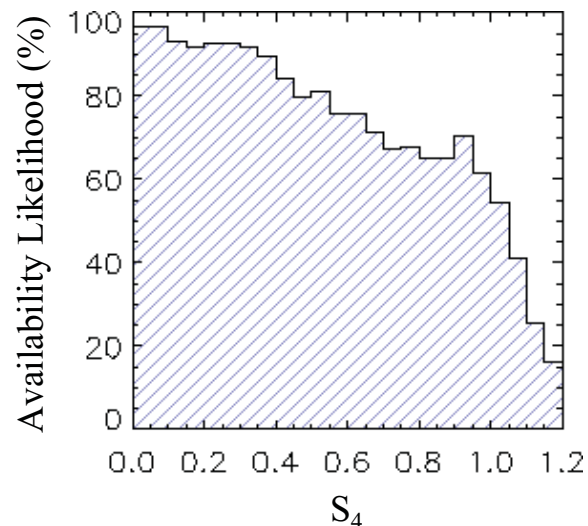
Modeling GPS Satellite Availability During Scintillation

Quality receivers report
which satellites used in
NAV

Example:

blue = used in NAV

red = not available
(corresponds to spike in
DOP)



Likelihood satellite will be available decreases as scintillation intensity increases. Each receiver type will have its own distribution.

Best metric might depend on receiver's "failure mode"

- If fades tend to break delay lock loop (DLL), use S_4 .
- If phase fluctuations tend to break the phase lock loop (PLL), use σ_ϕ
- Other parameters (e.g., decorrelation time) should also be considered



Simulating GPS Position Errors



Once we have modeled which satellites the receiver will track, we model the ranging errors and perform a standard navigation solution for the perturbed receiver position.

GPS range equation for each satellite, k :

$$P_{rs}^k + C_r + E_{rs}^k = \|\mathbf{R}_r - \mathbf{R}_s^k\|, \quad k=1, \dots, n$$

We model the k^{th} pseudorange:

$$\underbrace{P_{rs}^k}_{\text{modeled pseudorange}} = \underbrace{\|\mathbf{R}_r^0 - \mathbf{R}_s^k\|}_{\text{true range (via ephemeris)}} + \underbrace{[\gamma_s \hat{\phi}] S_4^k}_{\text{scintillation induced ranging error}}$$

Linearize the range equations about an initial estimate and solve by iteration:

$$\underbrace{\begin{bmatrix} (X_r - X_s^1)/R_{rs}^1 & (Y_r - Y_s^1)/R_{rs}^1 & (Z_r - Z_s^1)/R_{rs}^1 & (-1) \\ (X_r - X_s^2)/R_{rs}^2 & (Y_r - Y_s^2)/R_{rs}^2 & (Z_r - Z_s^2)/R_{rs}^2 & (-1) \\ \vdots & \vdots & \vdots & (-1) \\ (X_r - X_s^n)/R_{rs}^n & (Y_r - Y_s^n)/R_{rs}^n & (Z_r - Z_s^n)/R_{rs}^n & (-1) \end{bmatrix}}_{\mathbf{A}} \underbrace{\begin{bmatrix} dx \\ dy \\ dz \\ dc \end{bmatrix}}_{\mathbf{D}} = \underbrace{\begin{bmatrix} P_{rs}^1 - R_{rs}^1 \\ P_{rs}^2 - R_{rs}^2 \\ \vdots \\ P_{rs}^n - R_{rs}^n \end{bmatrix}}_{\mathbf{L}} \quad \text{where} \quad R_{rs}^k = \|\mathbf{R}_r - \mathbf{R}_s^k\|$$

Least squares solution to the over-determined system $\mathbf{A}\mathbf{D}=\mathbf{L}$ is $\mathbf{D}=(\mathbf{A}^T \mathbf{A})^{-1} \mathbf{A}^T \mathbf{L}$

Update the receiver position $\mathbf{R}_r \rightarrow \mathbf{R}_r + [D[1], D[2], D[3]]^T$ and repeat until convergence.



Application of the Model: Positioning Errors at Ascension Island

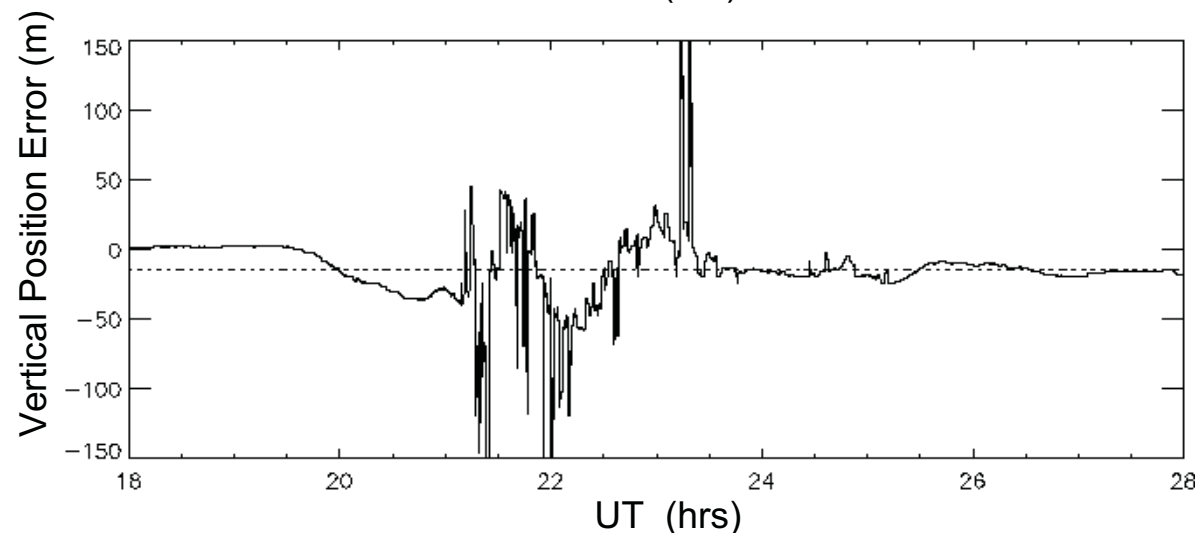
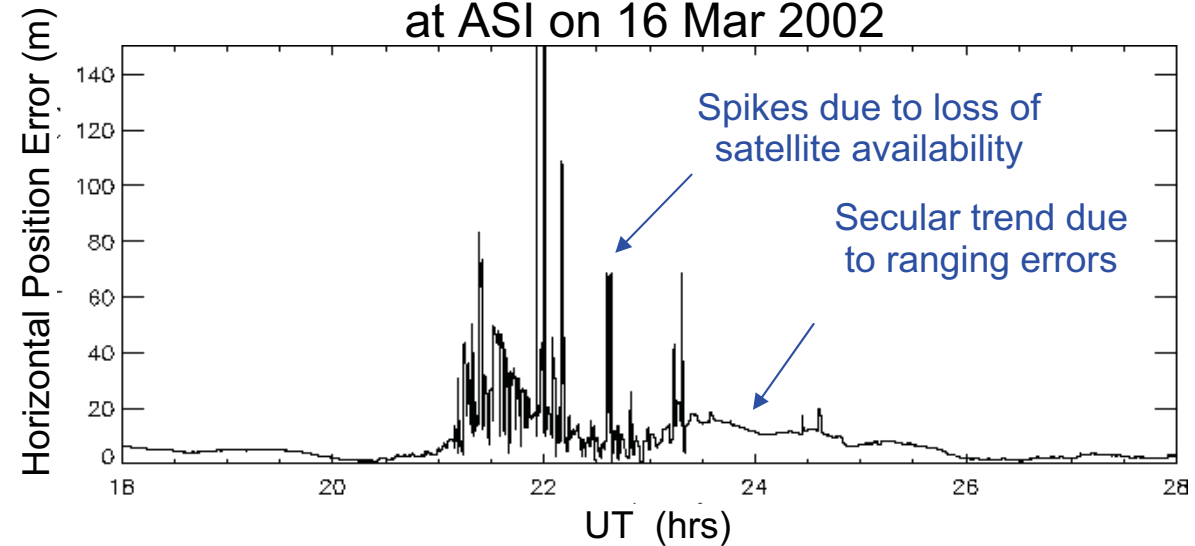


Goal:

- Using only S4 measurements and precise ephemeris, reproduce these position error results.

Only scintillation errors are included, assumes other effects negligible by comparison, including satellite and receiver clock errors, tropospheric errors, etc.

Actual positioning errors
at ASI on 16 Mar 2002





Preliminary Simulation Results

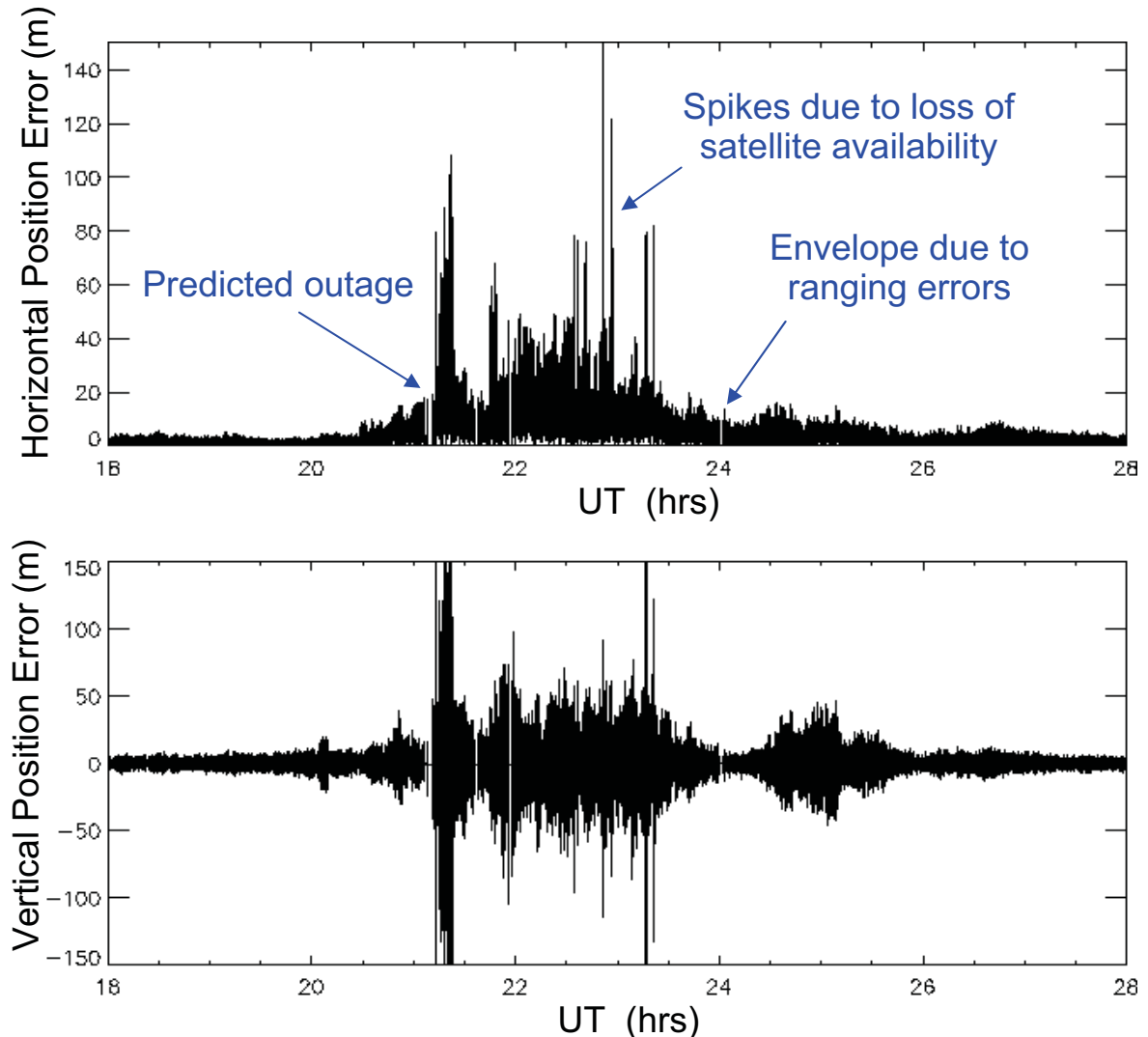


Simulation results using the scaling factor, $\gamma_s = 70$ m

Explanation for rapid fluctuations:

Random range perturbations are not correlated in time, unlike in the real world

Even though we have an S_4 measurement only once per minute, we evaluate the model every second so we can do statistics.

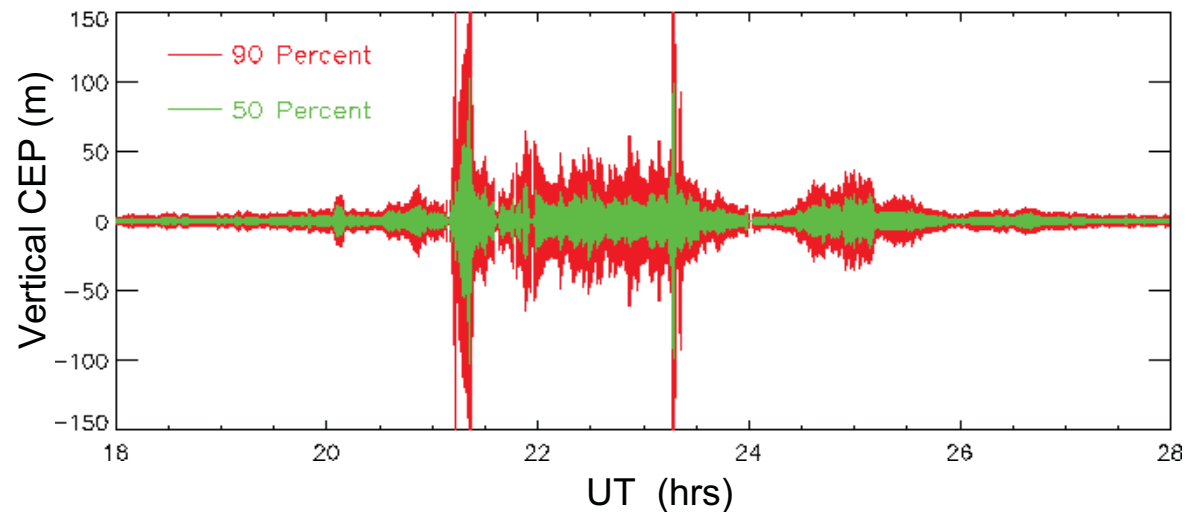
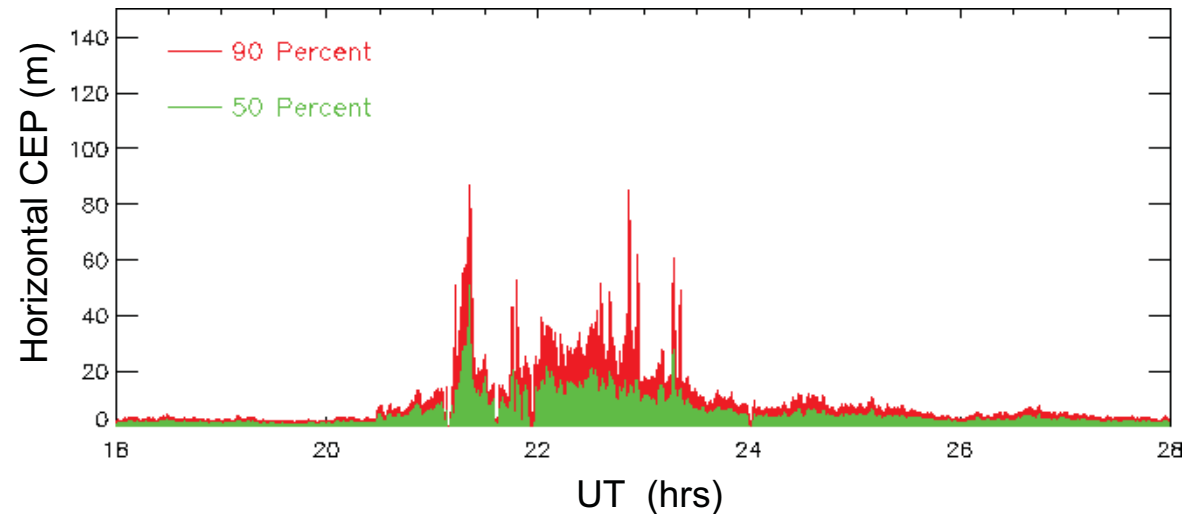




Statistical Analysis of the Simulation Results



- Sixty realizations per minute allow us to estimate CEP
- We can also **invert** these statistics, e.g., for a given accuracy requirement, report the probability that this requirement is met





Summary

- Relatively weak ionospheric interaction with L-band signals produces surprisingly strong propagation effects
- Numerous scintillation-induced GPS performance impacts have been observed and documented
 - Such impacts are generally limited to high periods of solar flux
- The details of how system performance is degraded remains poorly understood, but it has not been extensively studied
 - Opportunity for research in this area
- Additional modeling is needed to fully assess the vulnerability of modern GPS systems to scintillation activity
- Observations in Africa over the next few years can contribute significantly to this topic