



*The Abdus Salam
International Centre for Theoretical Physics*



2053-23

**Advanced Workshop on Evaluating, Monitoring and Communicating
Volcanic and Seismic Hazards in East Africa**

17 - 28 August 2009

Modeling of volcanic and tectonic phenomena

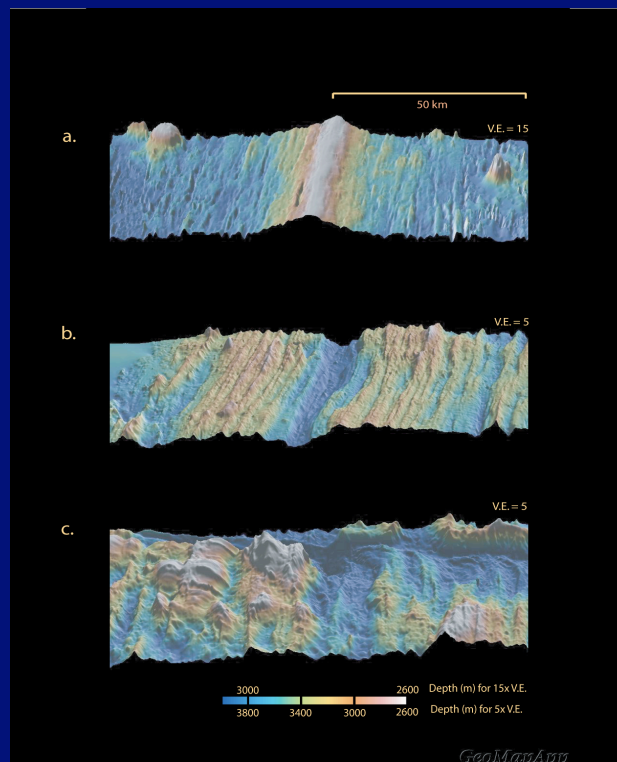
Roger Buck
*Lamont Doherty Earth Observatory
New York
USA*

Simple Models of Dikes and Faults

Roger Buck

Lamont-Doherty Earth Observatory of Columbia University

1. The 1975-1984 dike sequence at Krafla, Iceland



2. Controls on the offset of normal faults

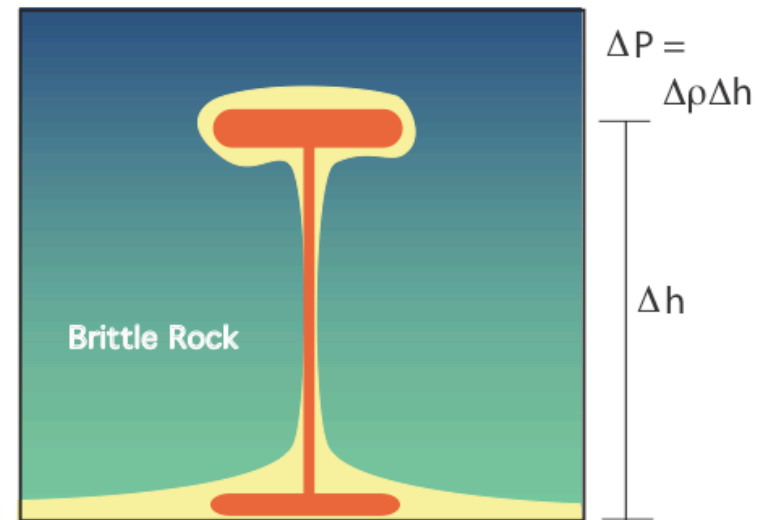
3. **Diking and faulting at spreading centers**

A major difference between volcanoes and rifts/spreading centers may be how magma is forced out of a magma chamber.

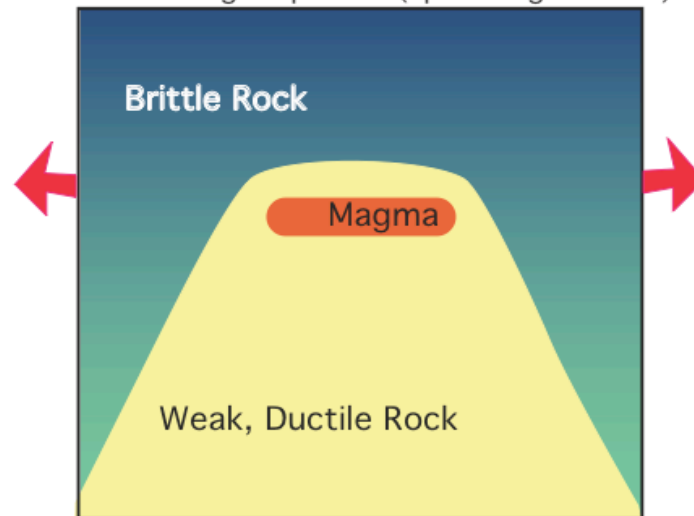
This talk is concerned with how the stresses at a spreading center are relieved by dike intrusions.

The pattern of dikes may reflect the changing stress field.

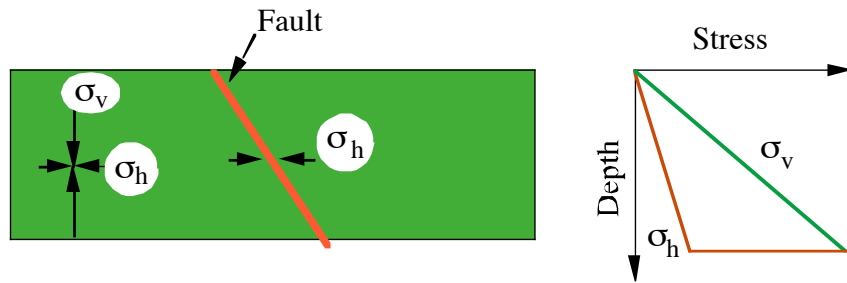
A. Overpressure drives magma breakout (volcanoes)



B. Extension drives magma pullout (spreading centers)



Minimum Stress Difference for Fault Slip

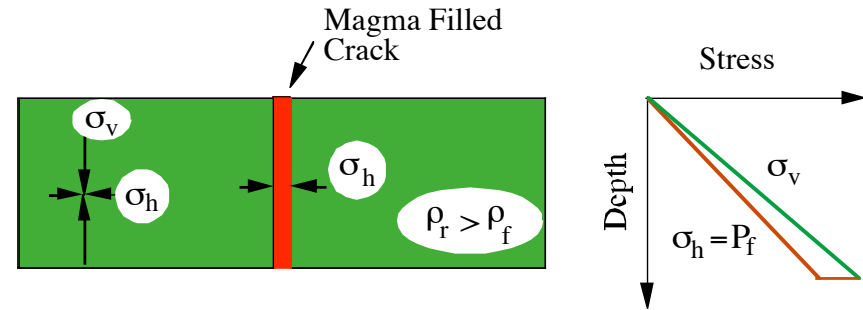


ρ_r = rock density

$$\sigma_v(z) = \rho_r g z$$

$$\sigma_h(z) = \left[\frac{(1+\mu^2)^{1/2} - \mu}{(1+\mu^2)^{1/2} + \mu} \right] \sigma_v(z) \sim [1/4] \sigma_v(z)$$

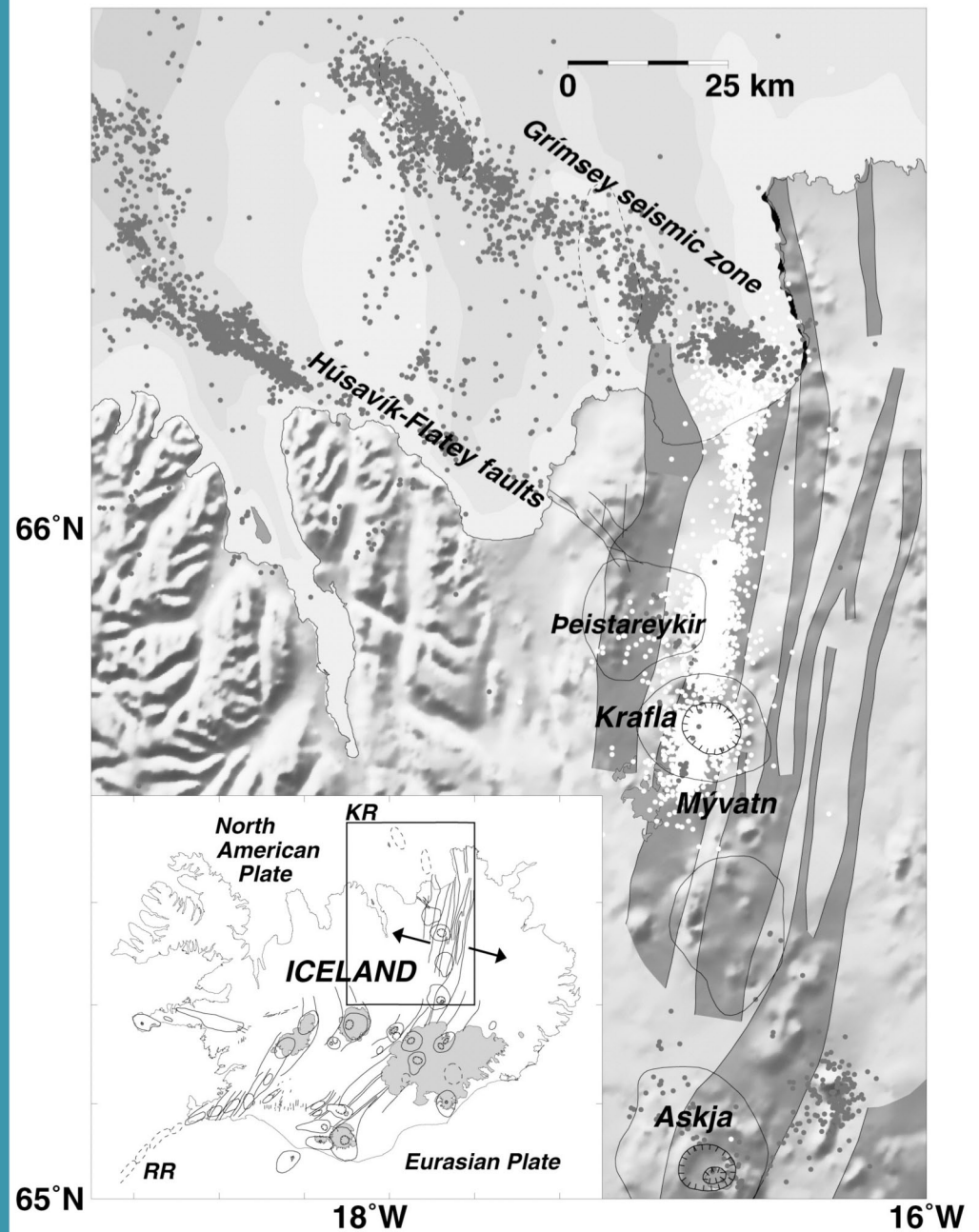
Minimum Stress Difference for Opening Dike

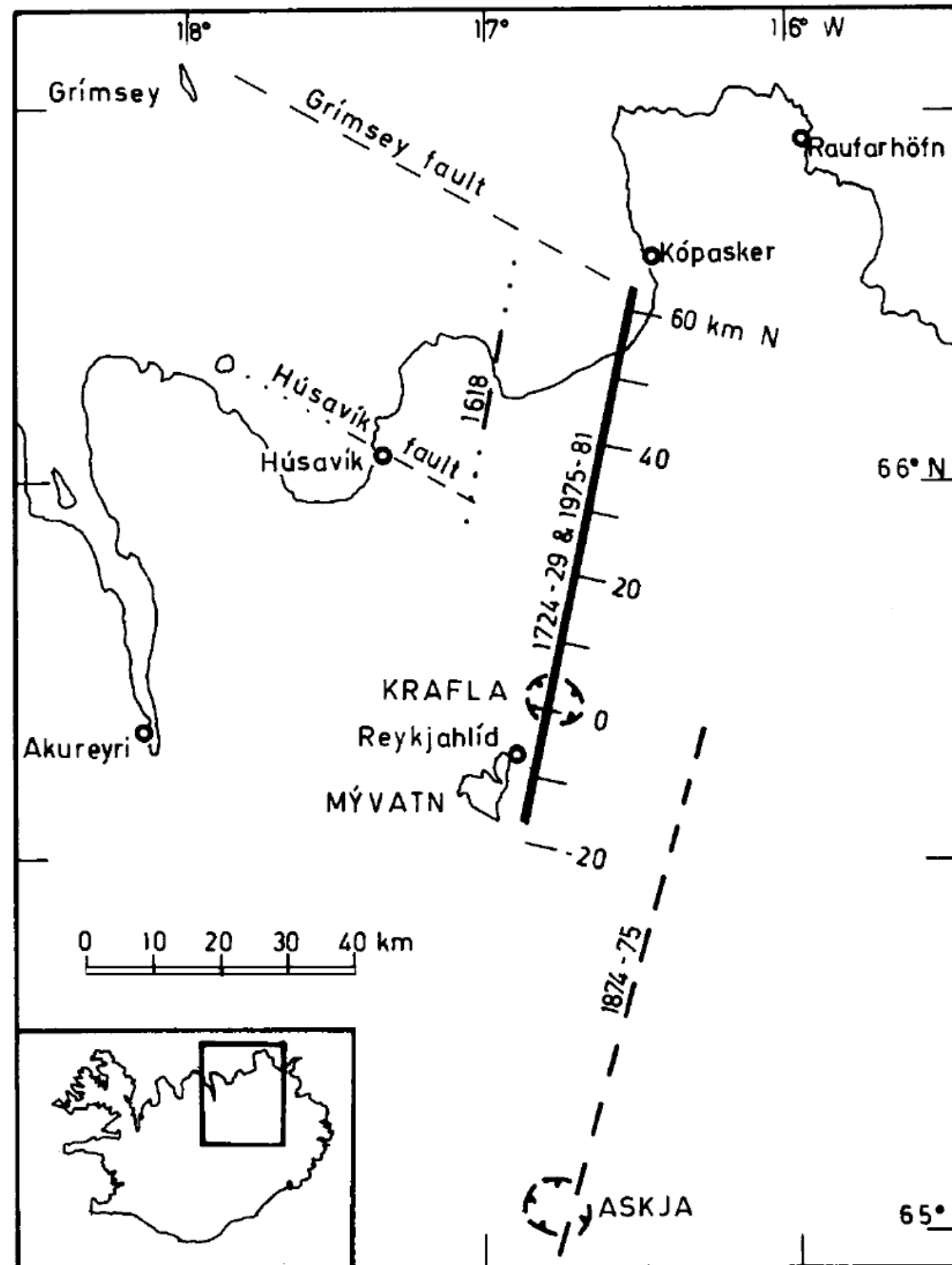


$$\sigma_v(z) = \rho_r g z$$

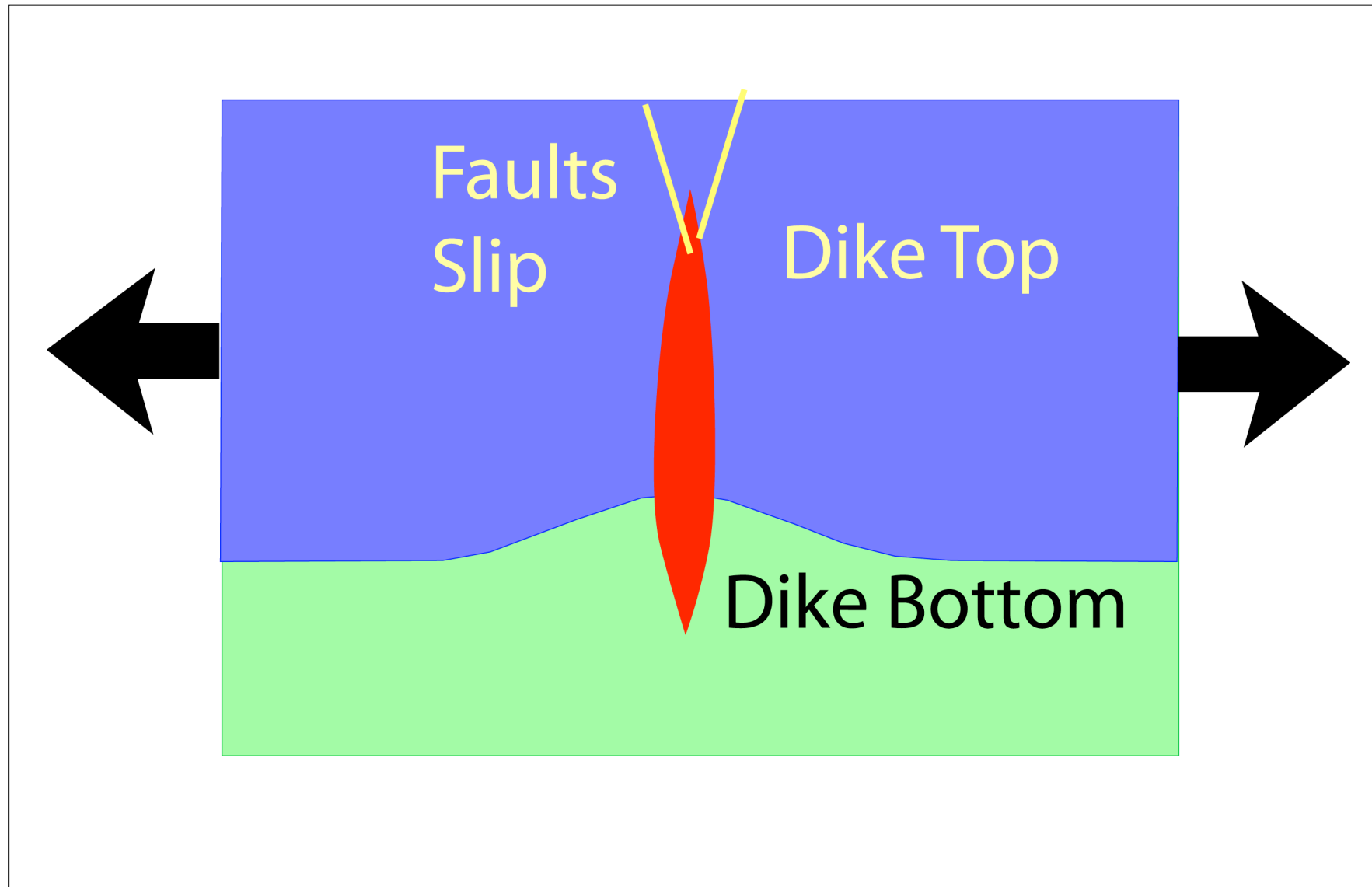
$$\sigma_h(z) = P_f = \rho_f g z$$

Krafla, Iceland Earthquake and Fissure Locations (by Bryndis Brandsdottir)





DIKE OPENING MAKES FAULTS

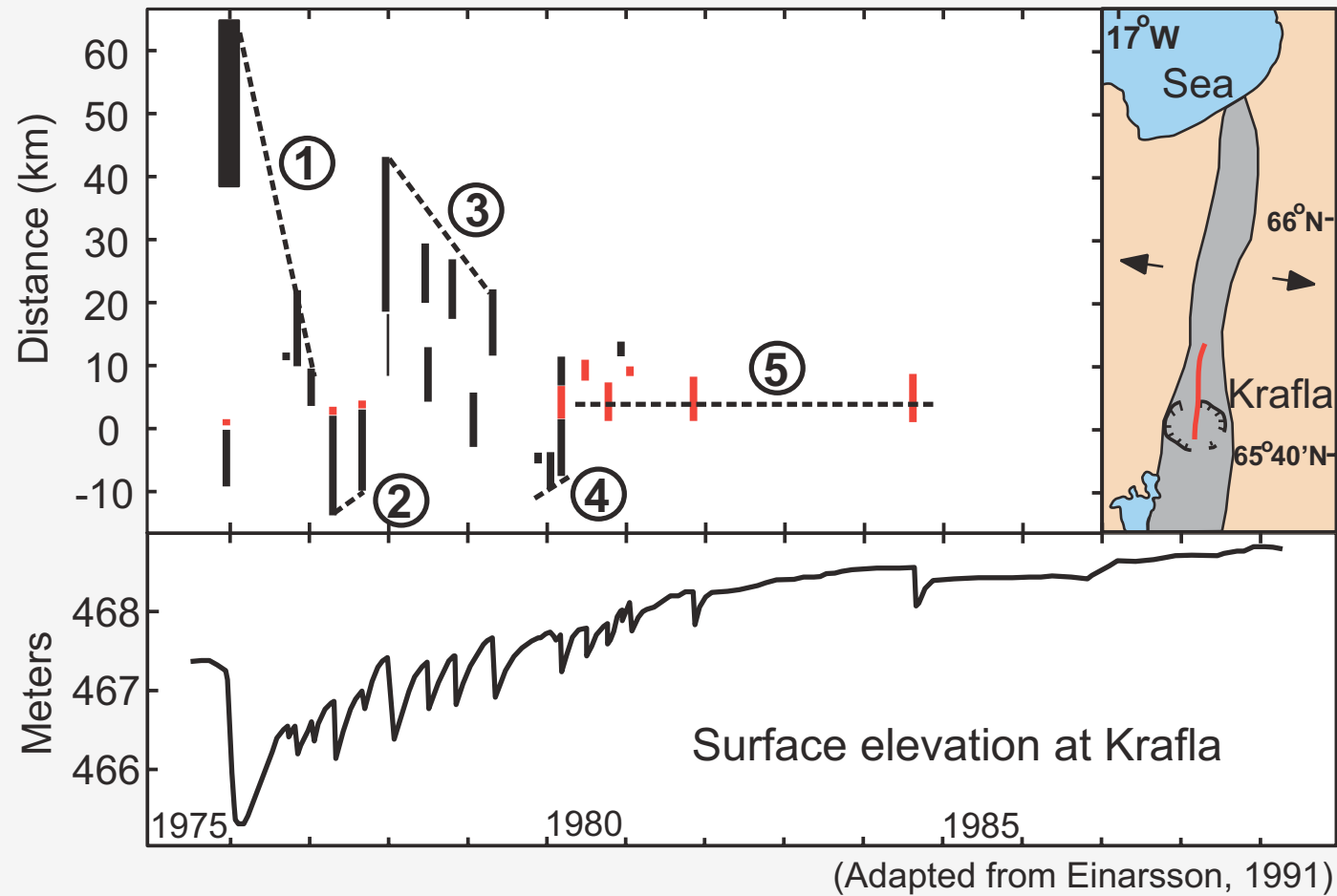


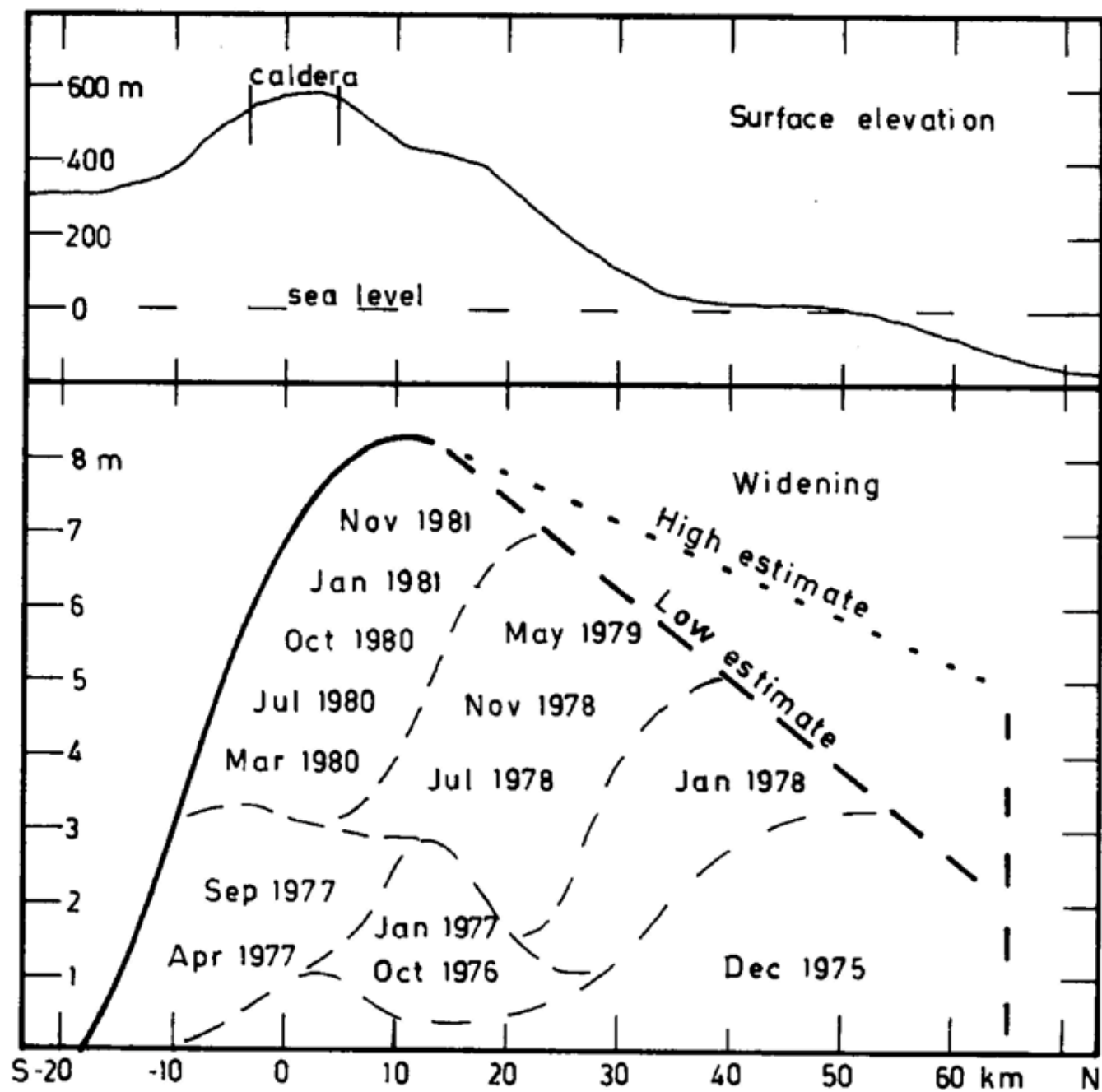


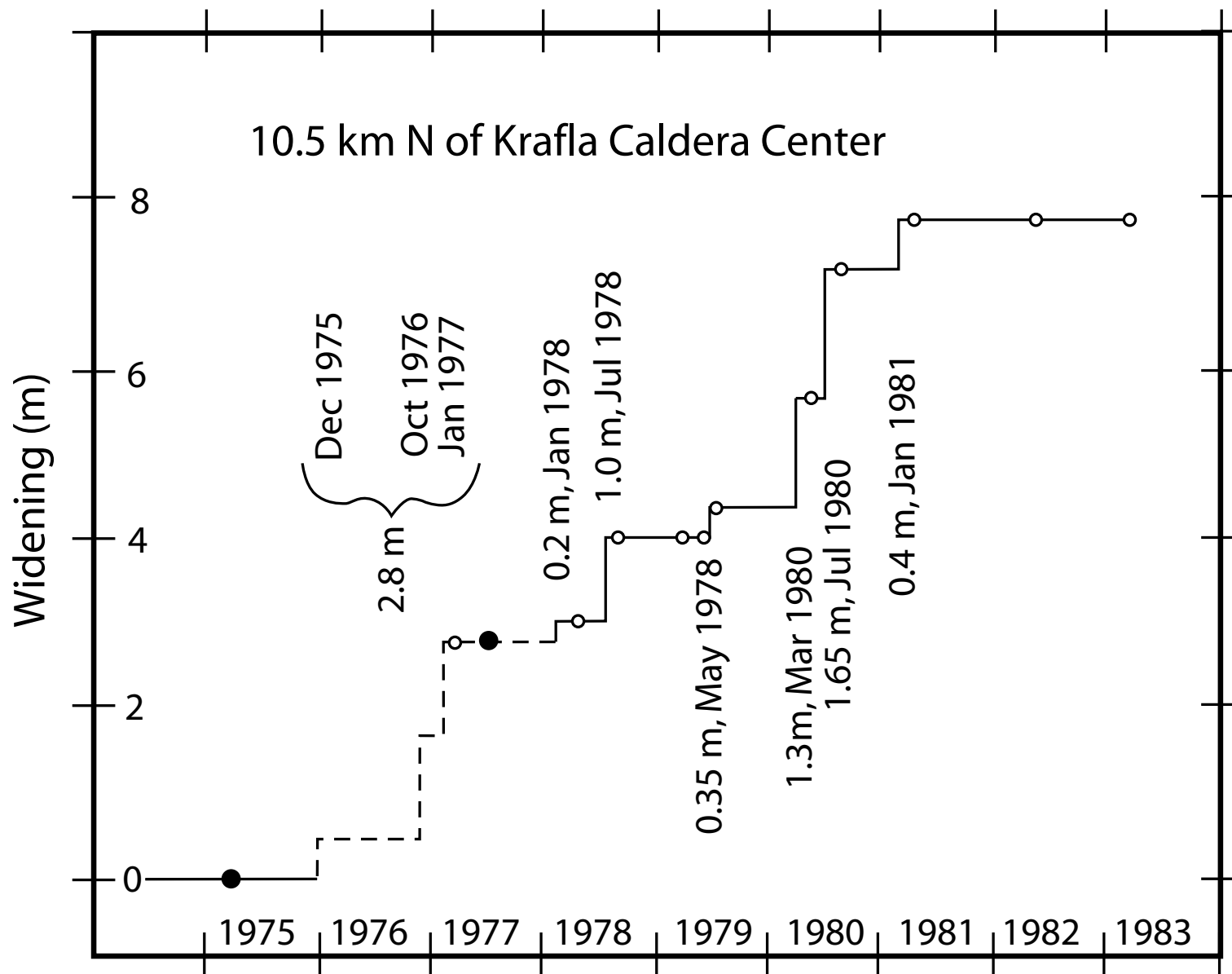
Thorarinsson September 8, 1977

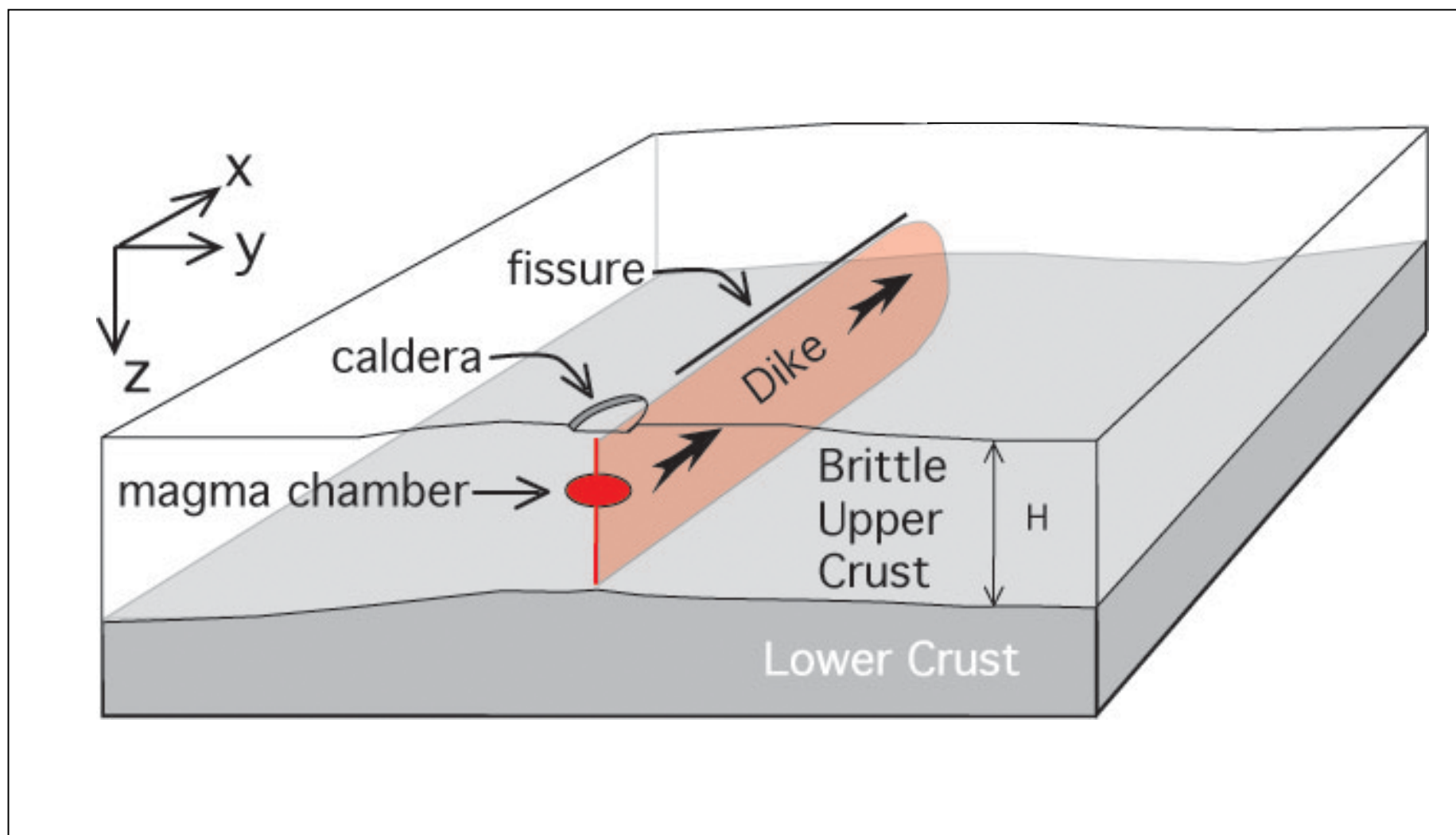


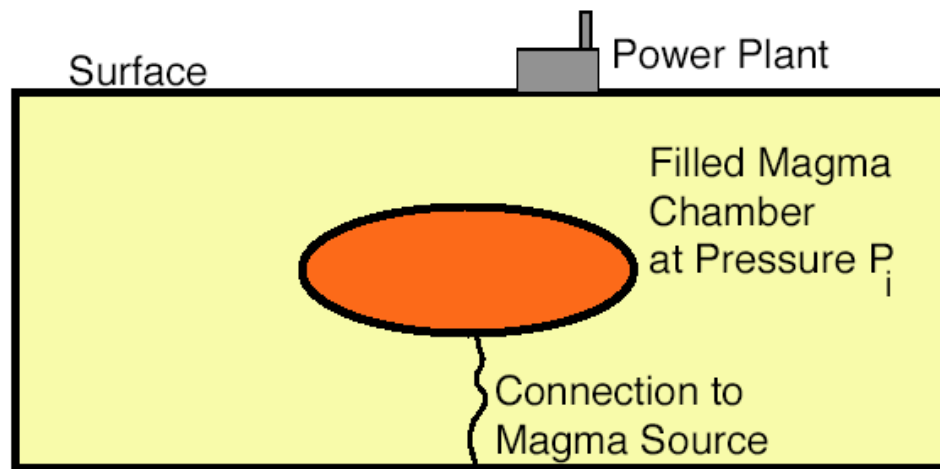
1975-1984 Krafla Rifting Episode



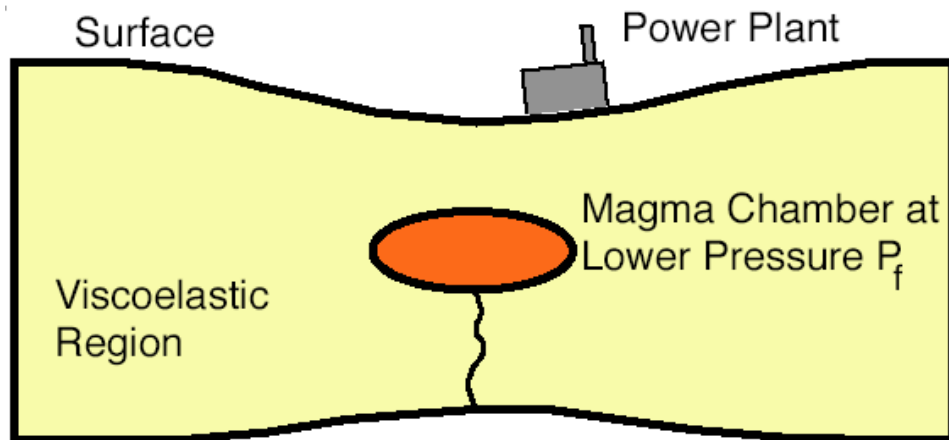
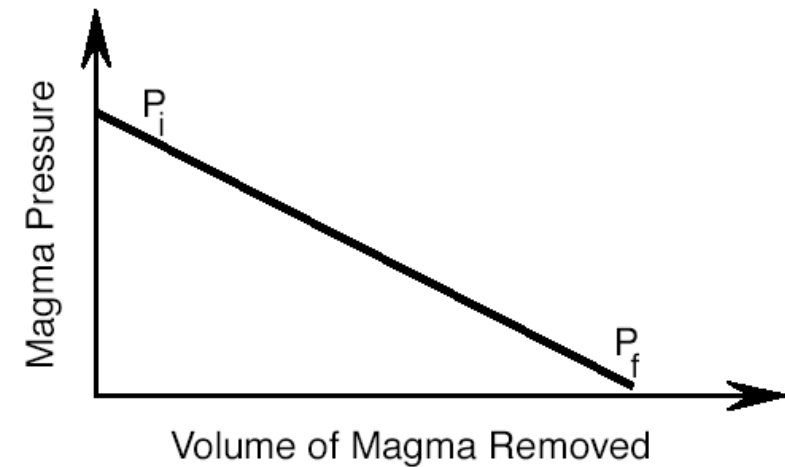




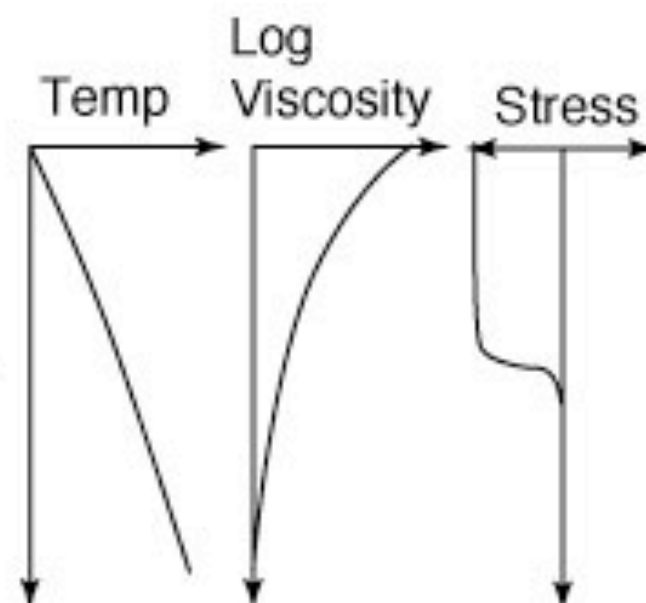
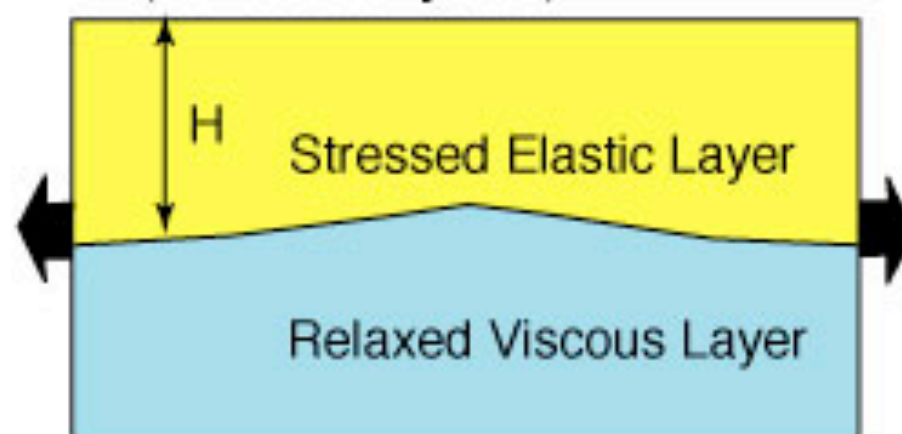




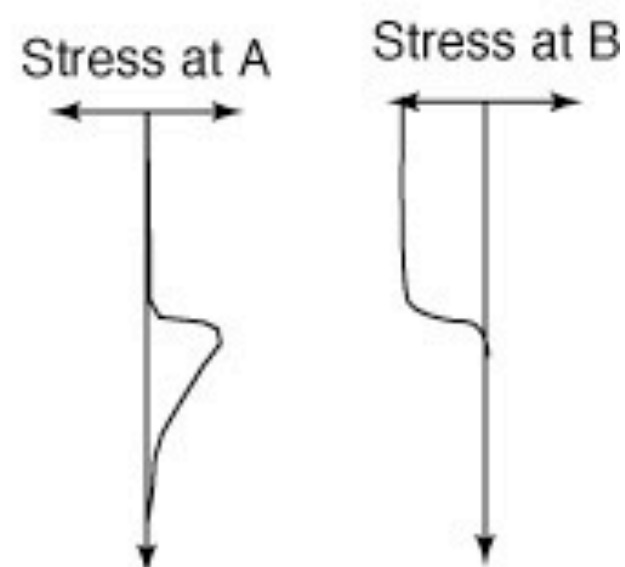
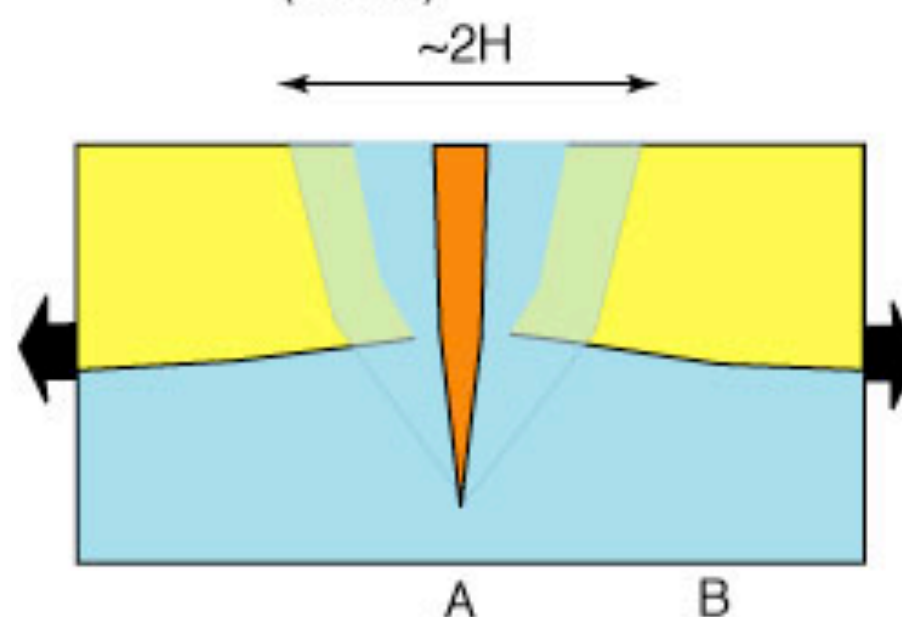
Assumption 1: The system is closed during an event. As magma is pulled from the magma chamber its pressure is reduced.



A. After Finite Loading Time
(10-100's of years)

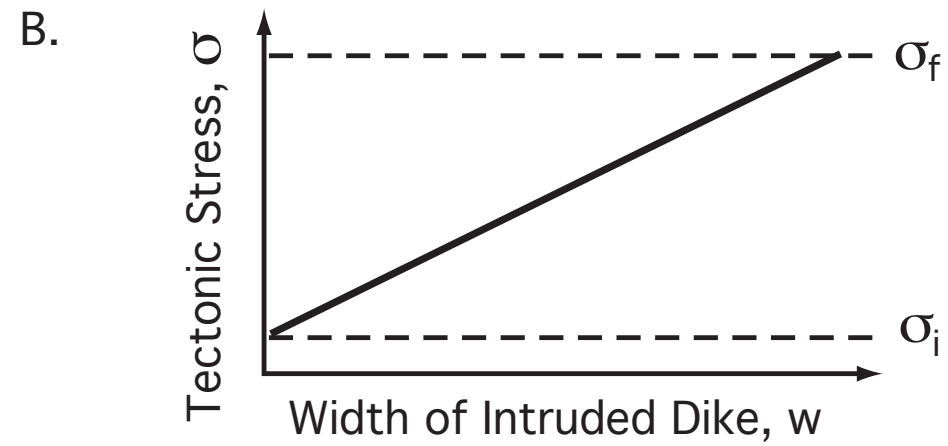
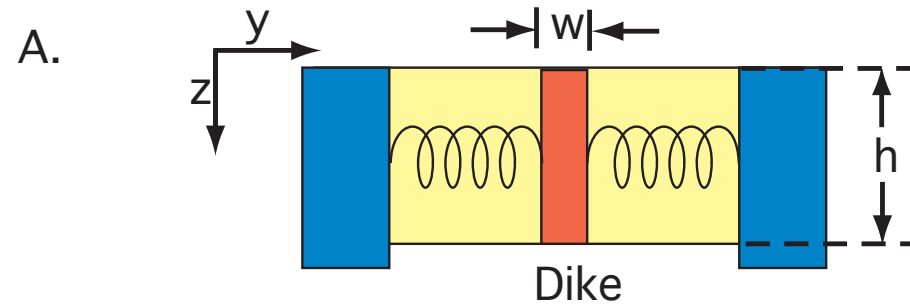


B. After Sudden Dike Intrusion
(hours)



C. After Partial Freezing of Dike

Assumption 2: Dike opening
relieves tectonic stresses
in a finite width region.



Assumption 3: For magma to breakout of a chamber the driving pressure (magma pressure - local tectonic stress) must be larger than ΔP_b

Assumption 4: Dike propagation will stop when the driving pressure drops below ΔP_s .

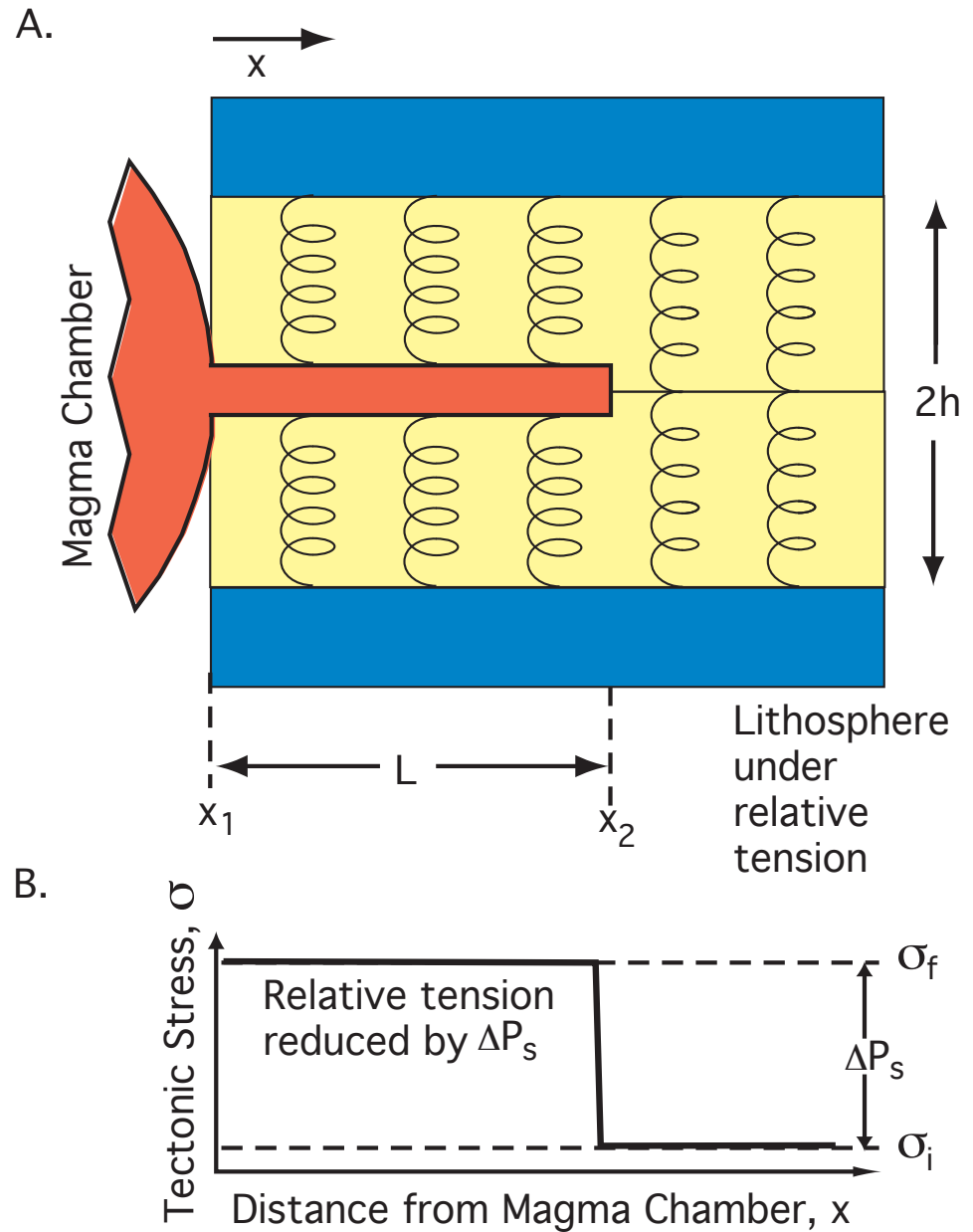
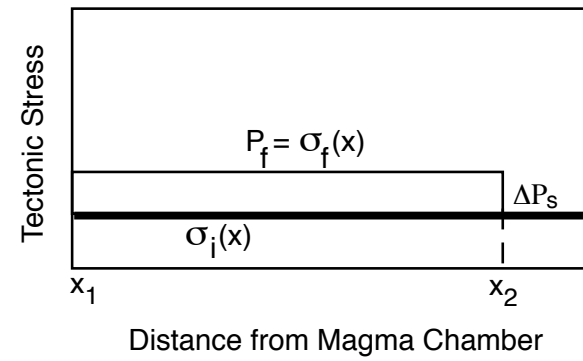
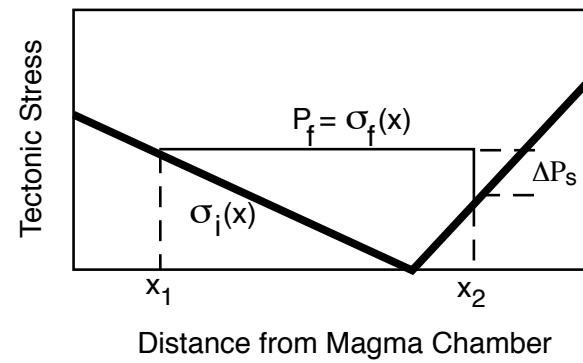


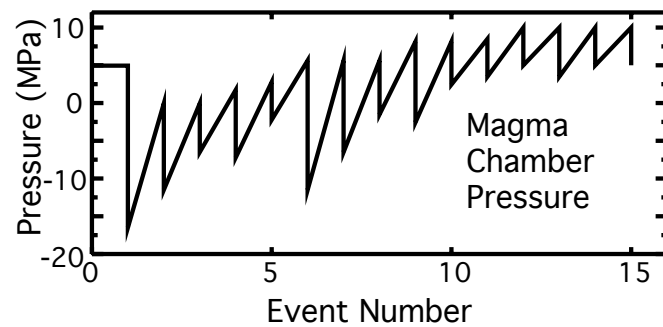
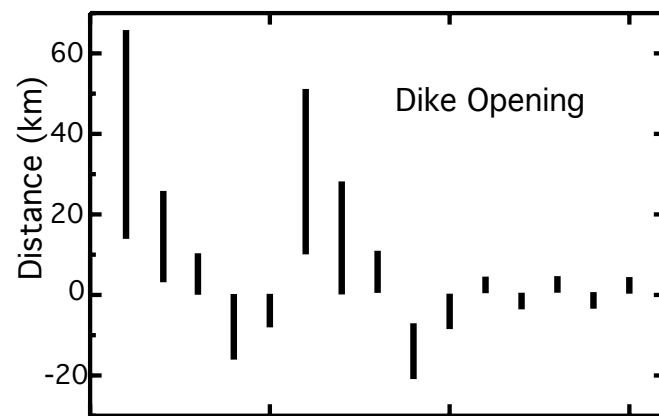
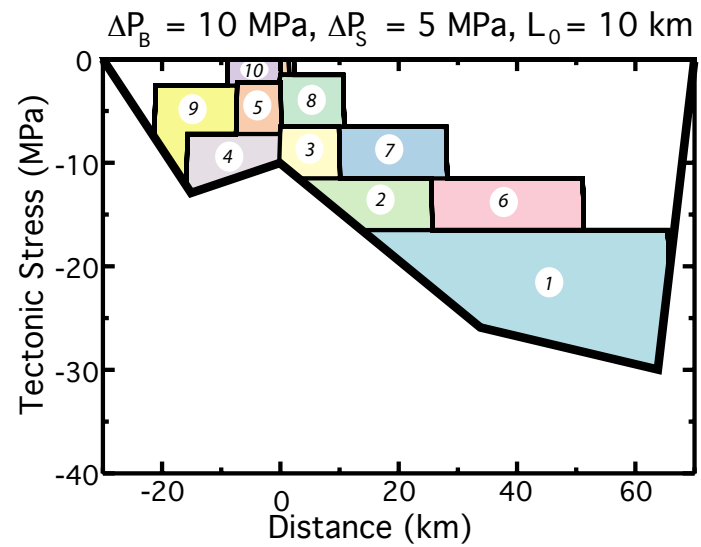
Figure 9.

a. Constant Initial Stress

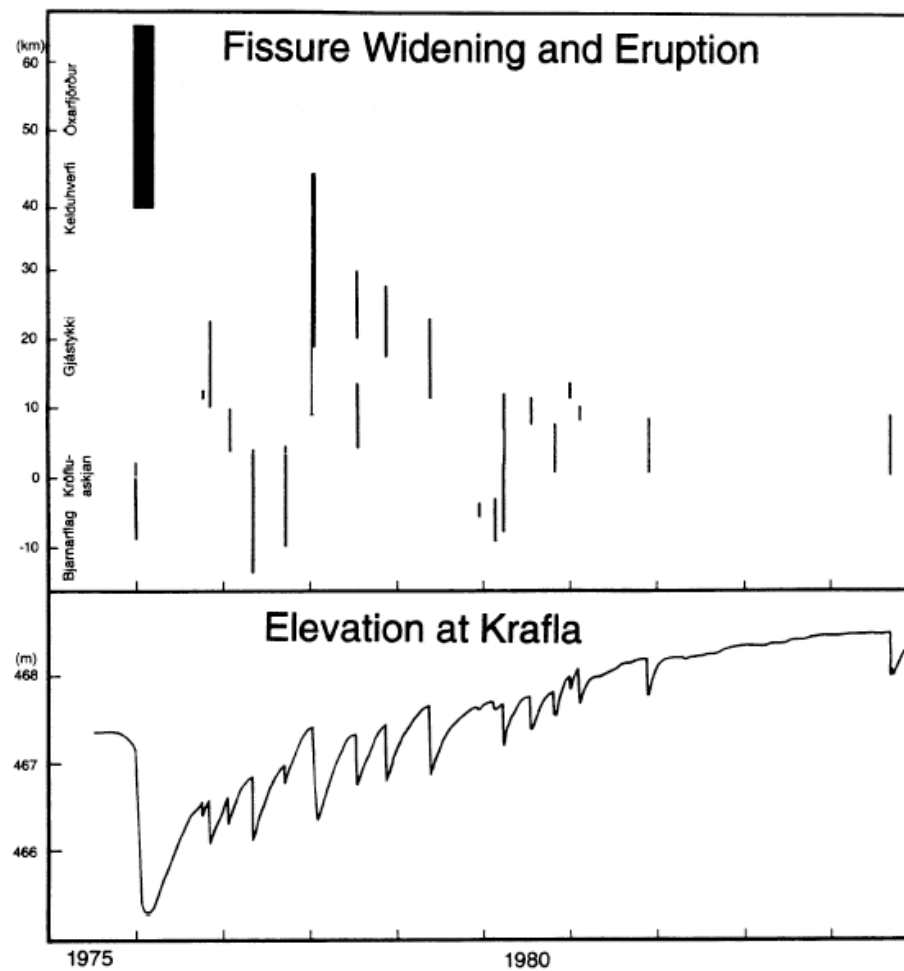
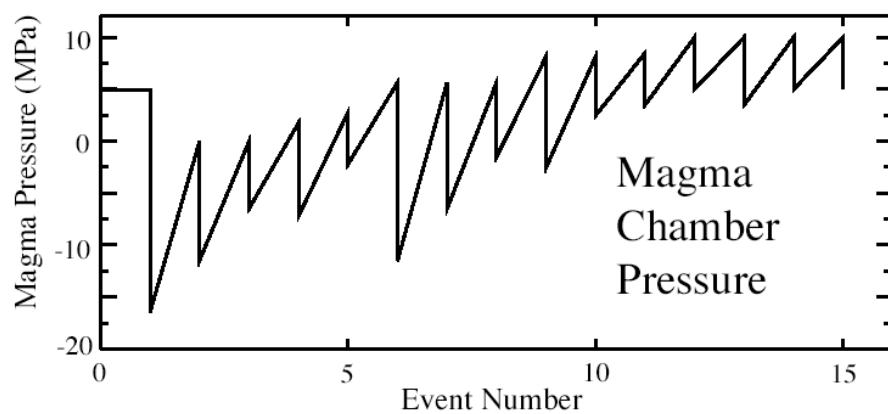
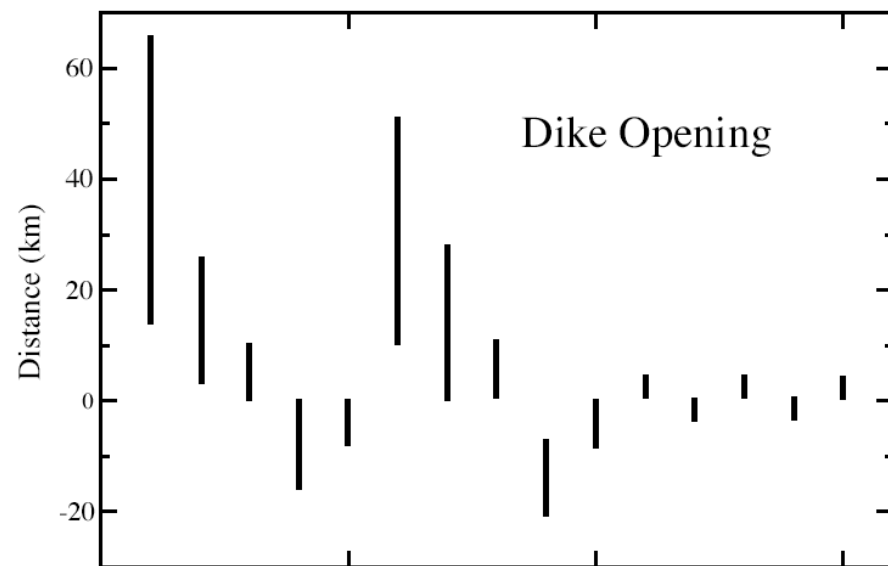


b. Decreasing then Increasing Initial Stress





$T = 5 \text{ MPa}$, $\Delta P = 10 \text{ MPa}$

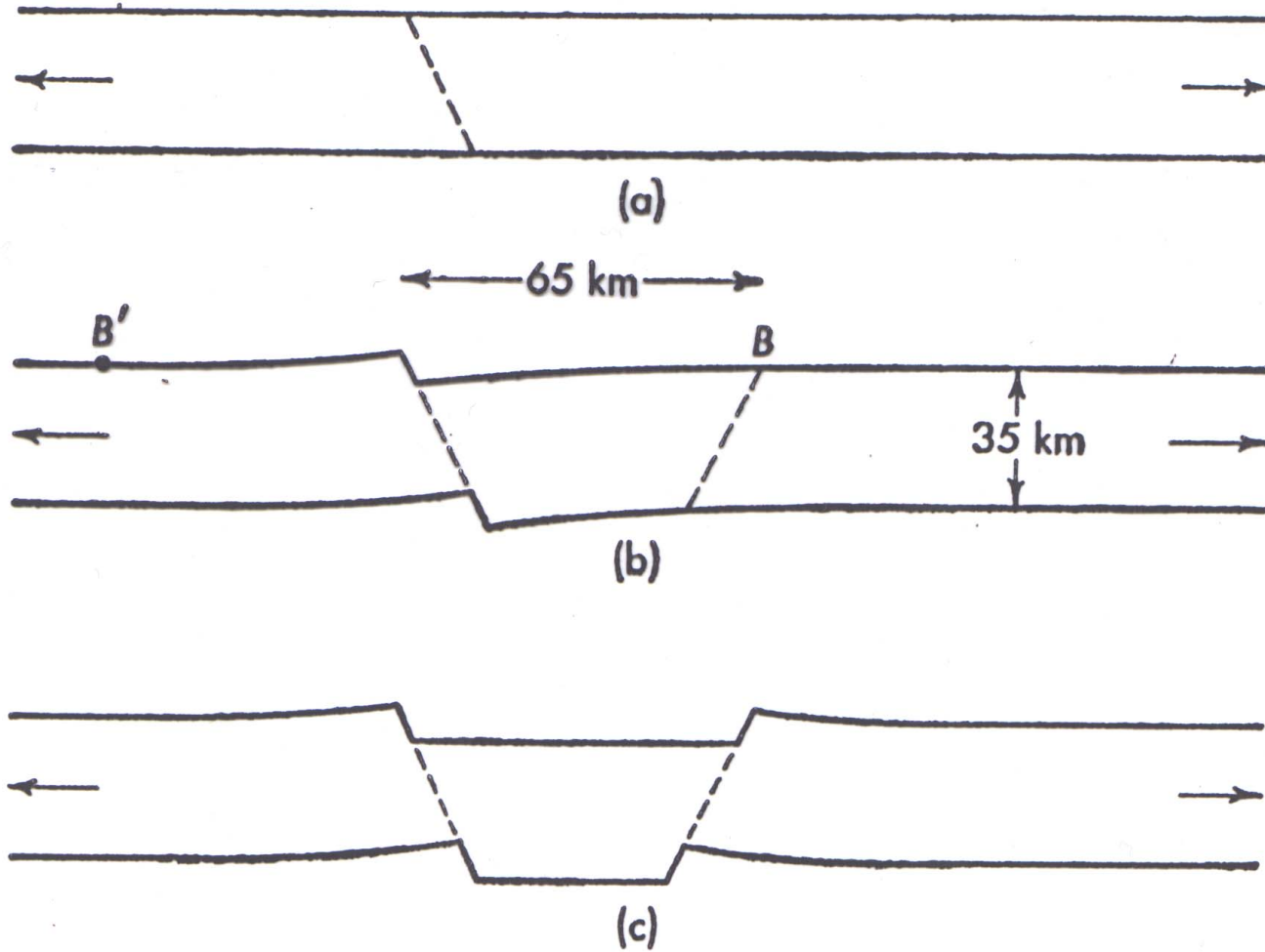


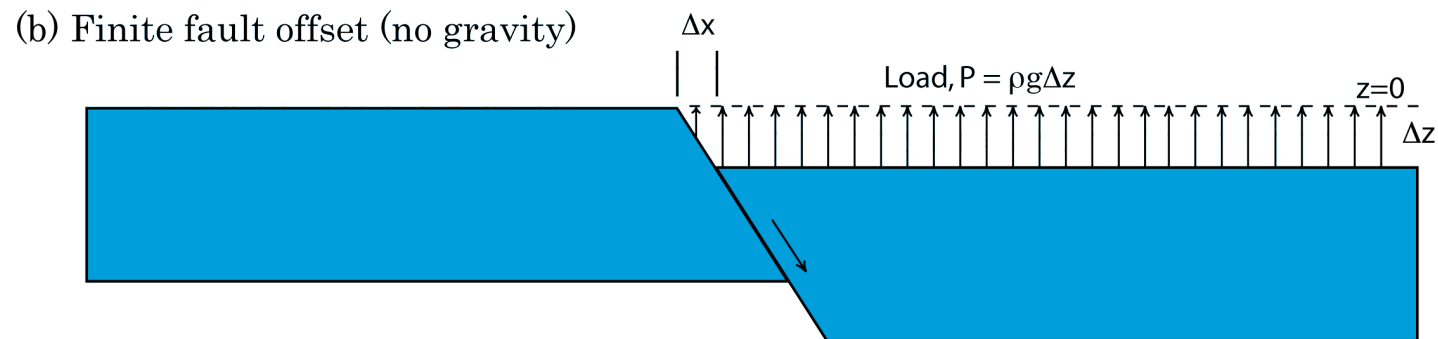
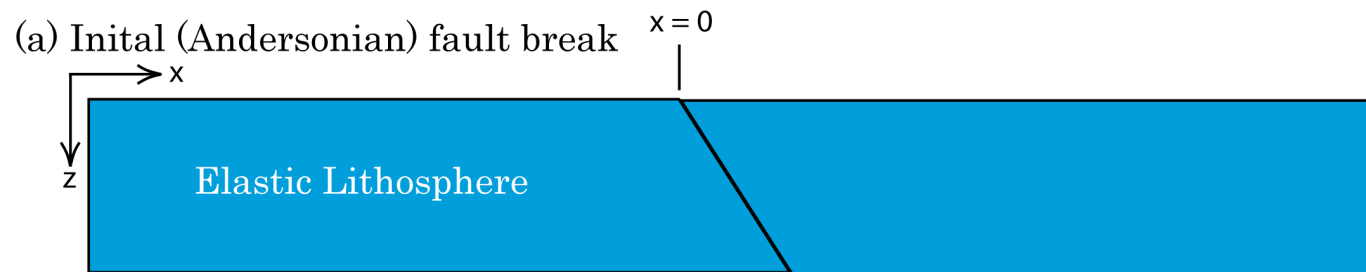
Simple models of Normal Faulting

Big Question: How far can a normal fault slip before another fault takes over.

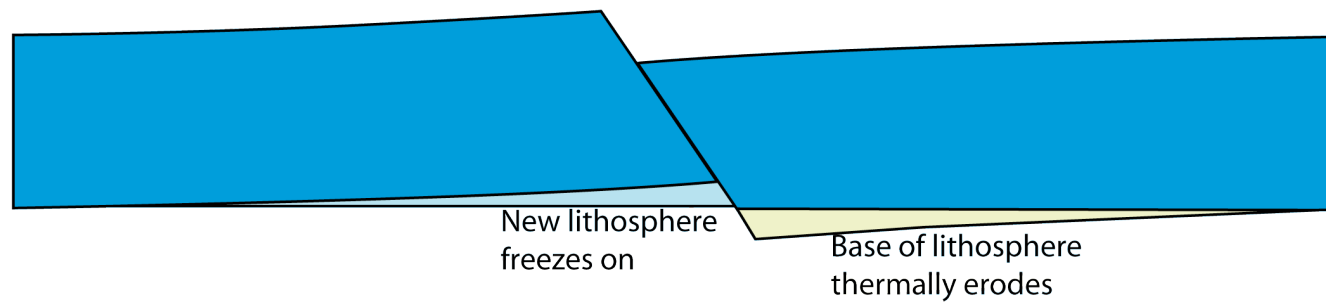
Motivation: A few normal faults slip a huge amount.

Gravitational Stress on a Flexing Layer Scale

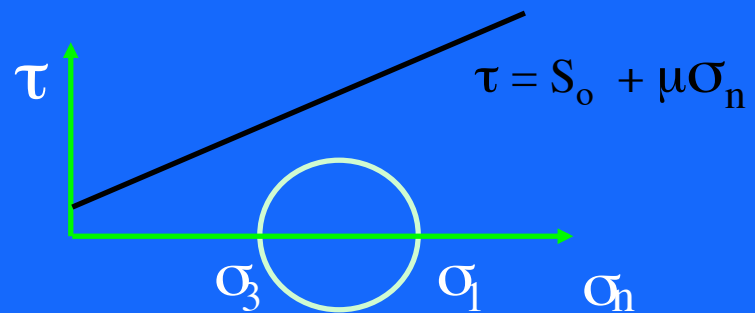
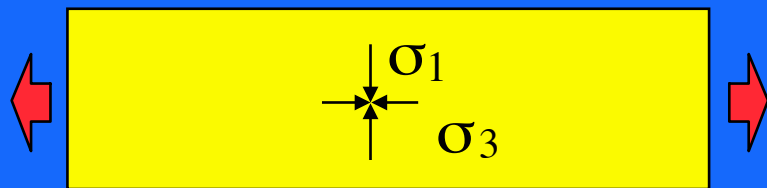




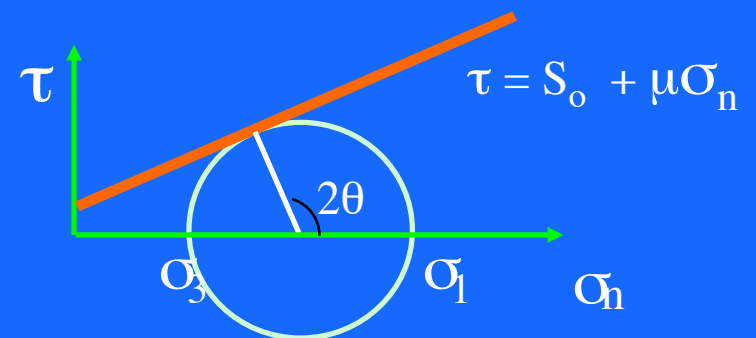
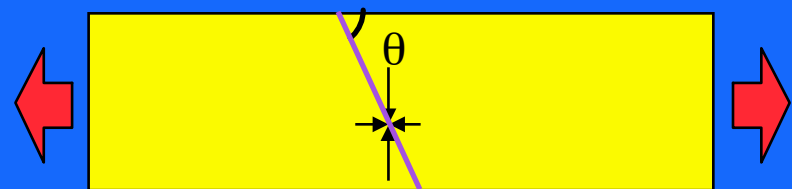
(c) Flexural response when gravity is “turned on”



Andersonian Stress State



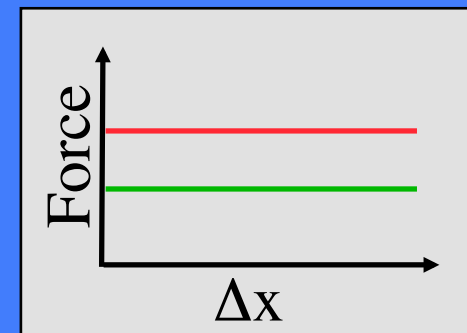
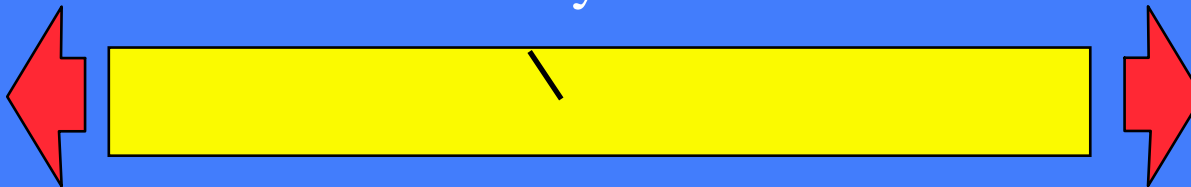
Andersonian Breaking State



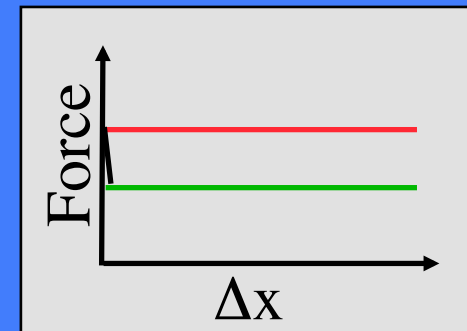
Finite Offset of Elastic Layer

(after Forsyth, Geology, 1992)

Fault Breaks Layer

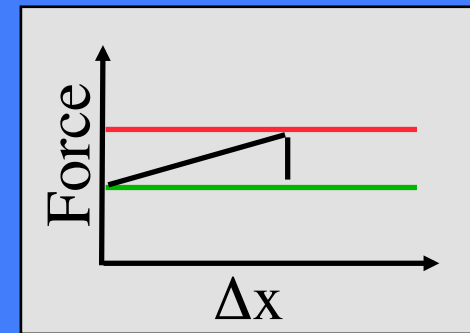
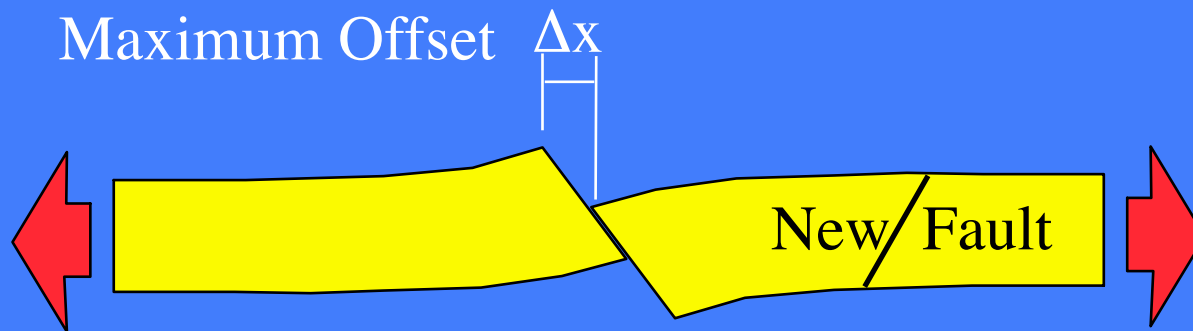
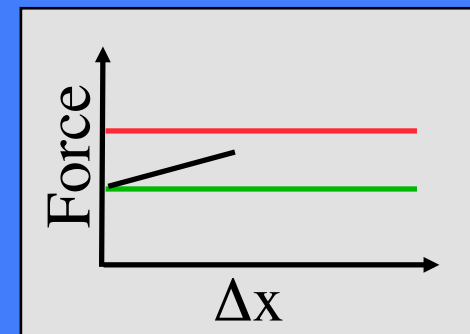
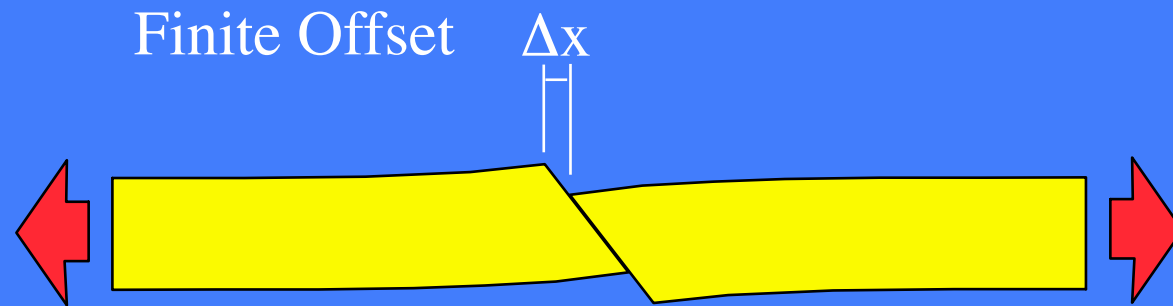


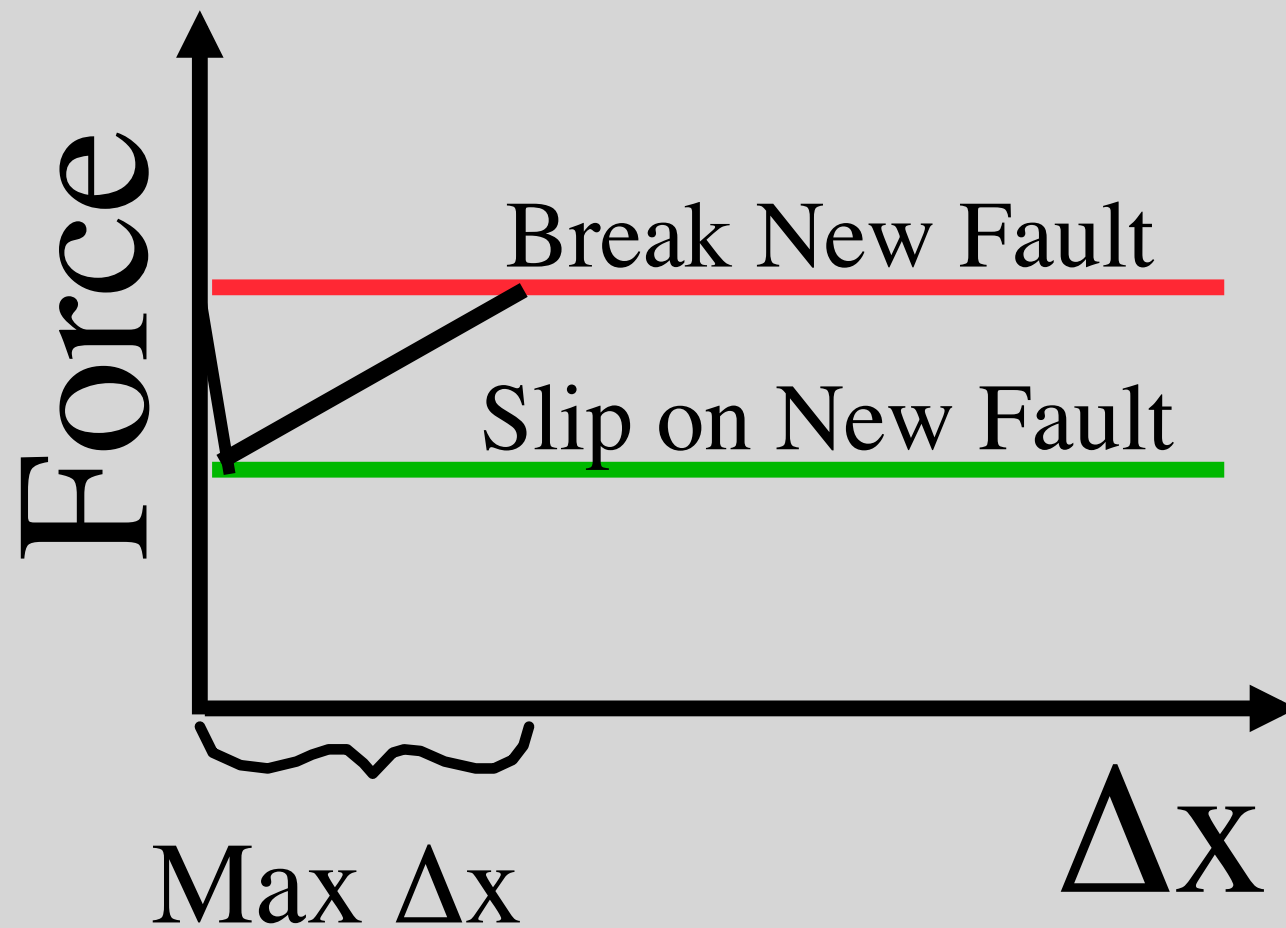
Fault Begins to Slip



Finite Offset of Elastic Layer

(after Forsyth, Geology, 1992)

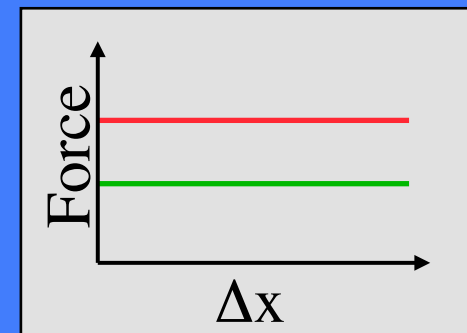
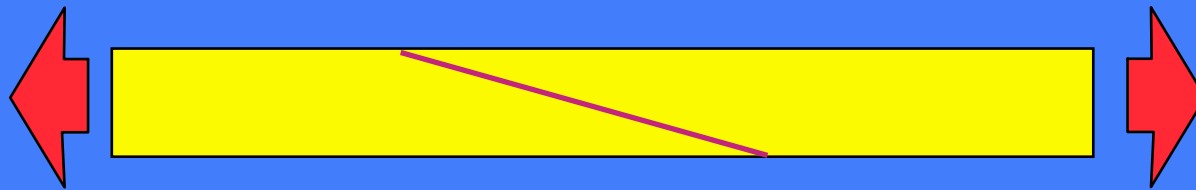




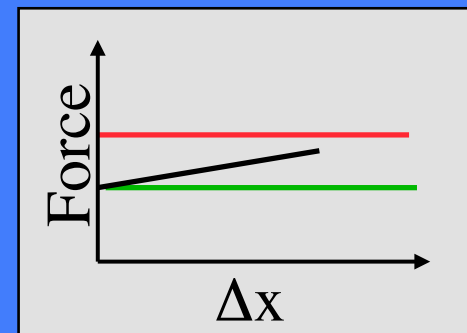
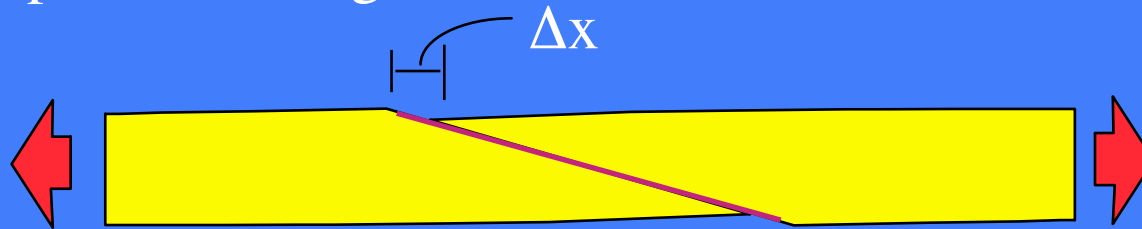
Finite Offset of Elastic Layer

(after Forsyth, Geology, 1992)

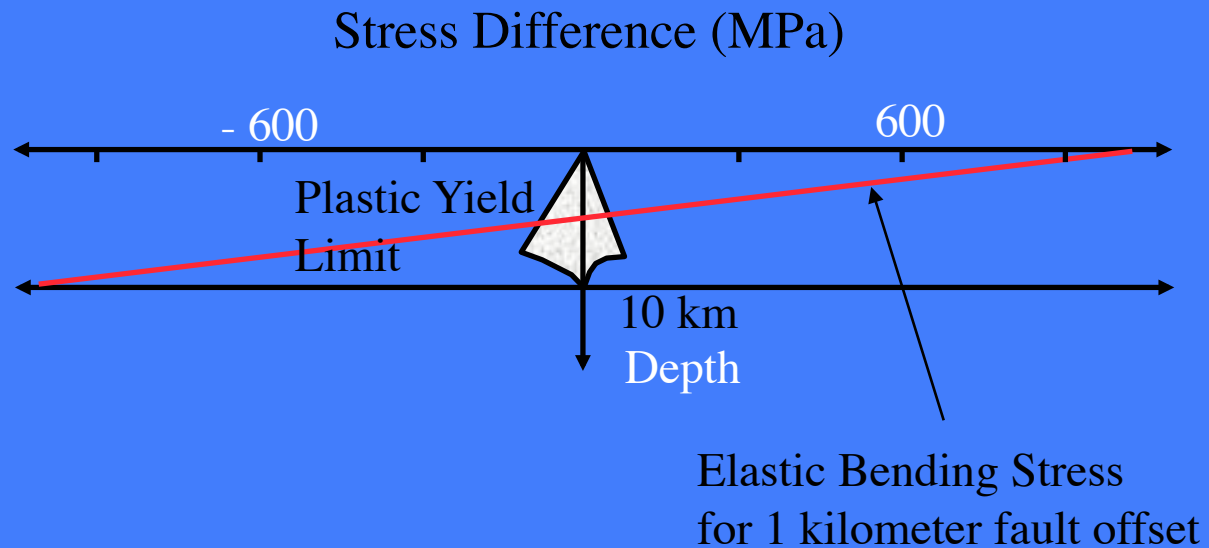
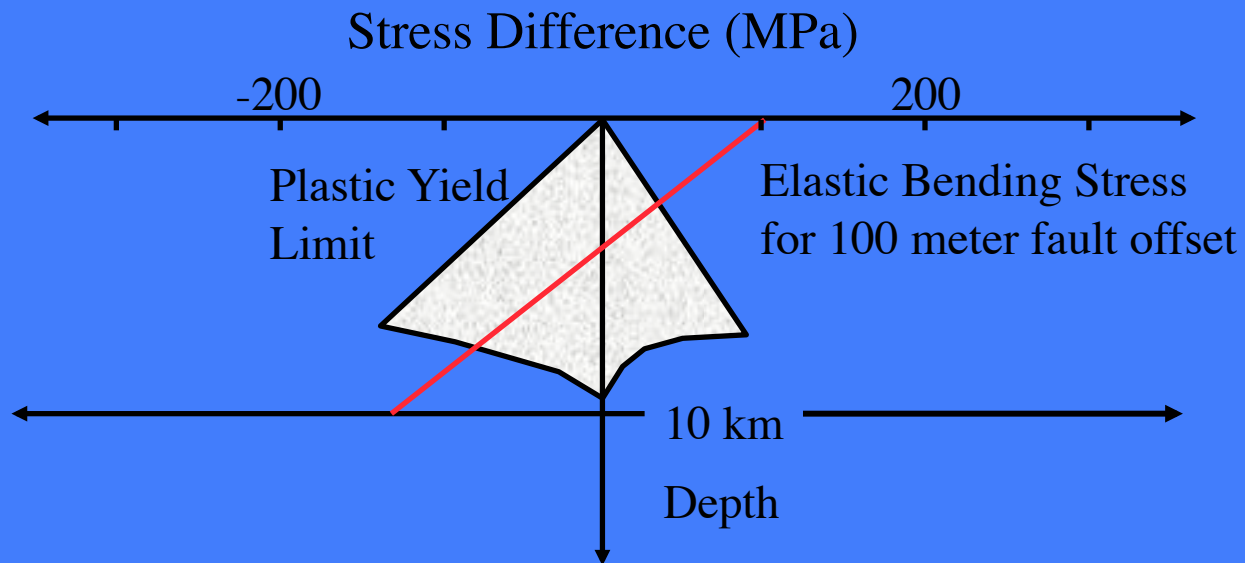
Assume Pre-existing Weak Fault



Slip on Low-angle Weak Fault



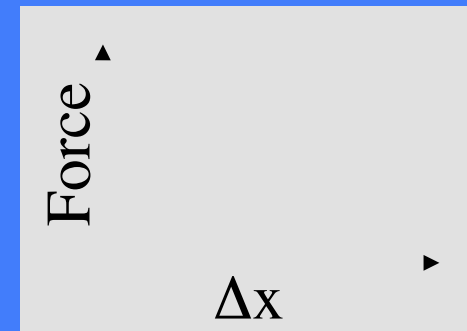
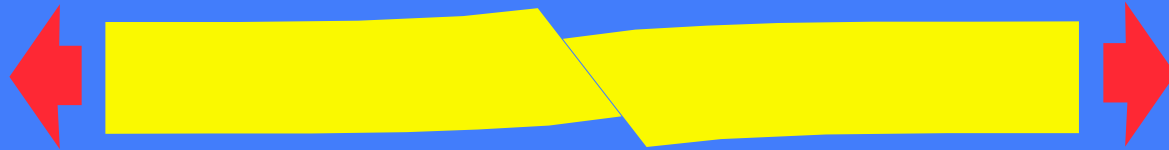
Stresses due to Plate Bending



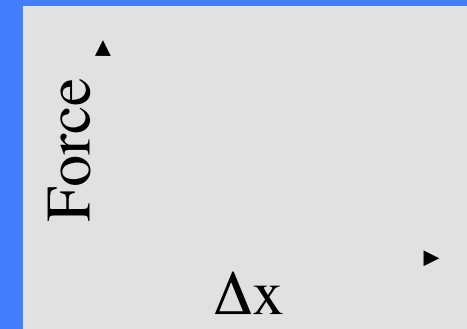
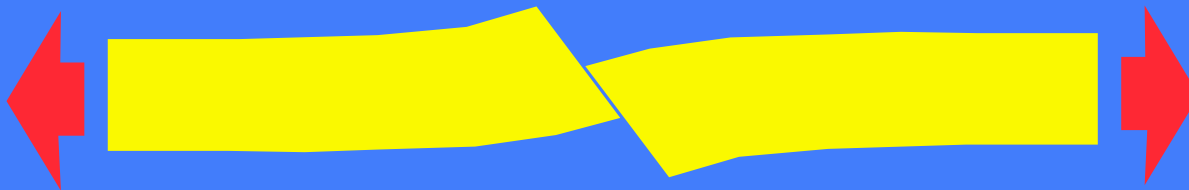
Finite Offset of Elastic-Plastic Layer

(after Buck, Geology, 1993)

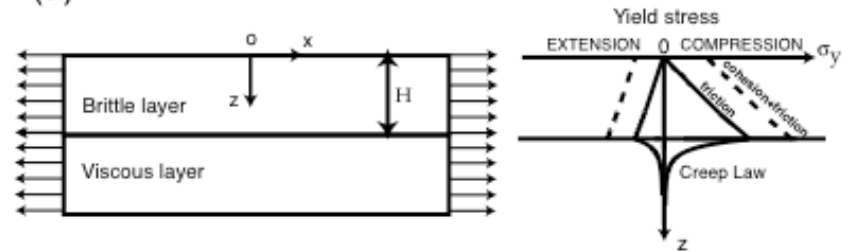
Finite Offset Δx



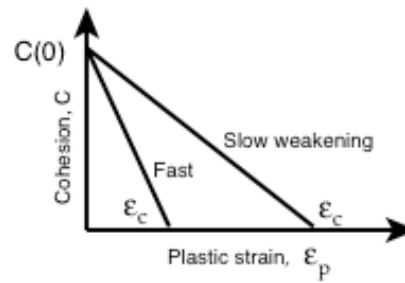
Offset Δx taking Maximum Force



(a)

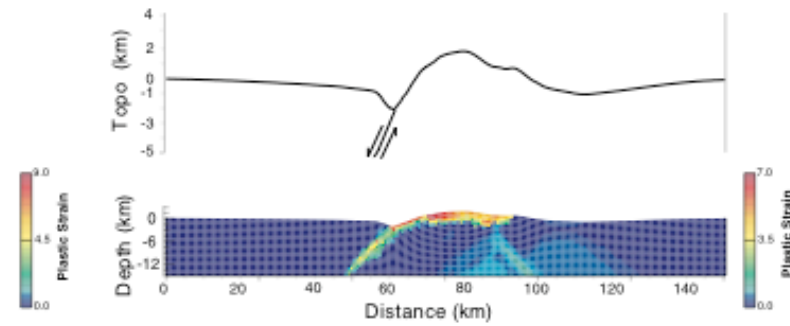


(b)

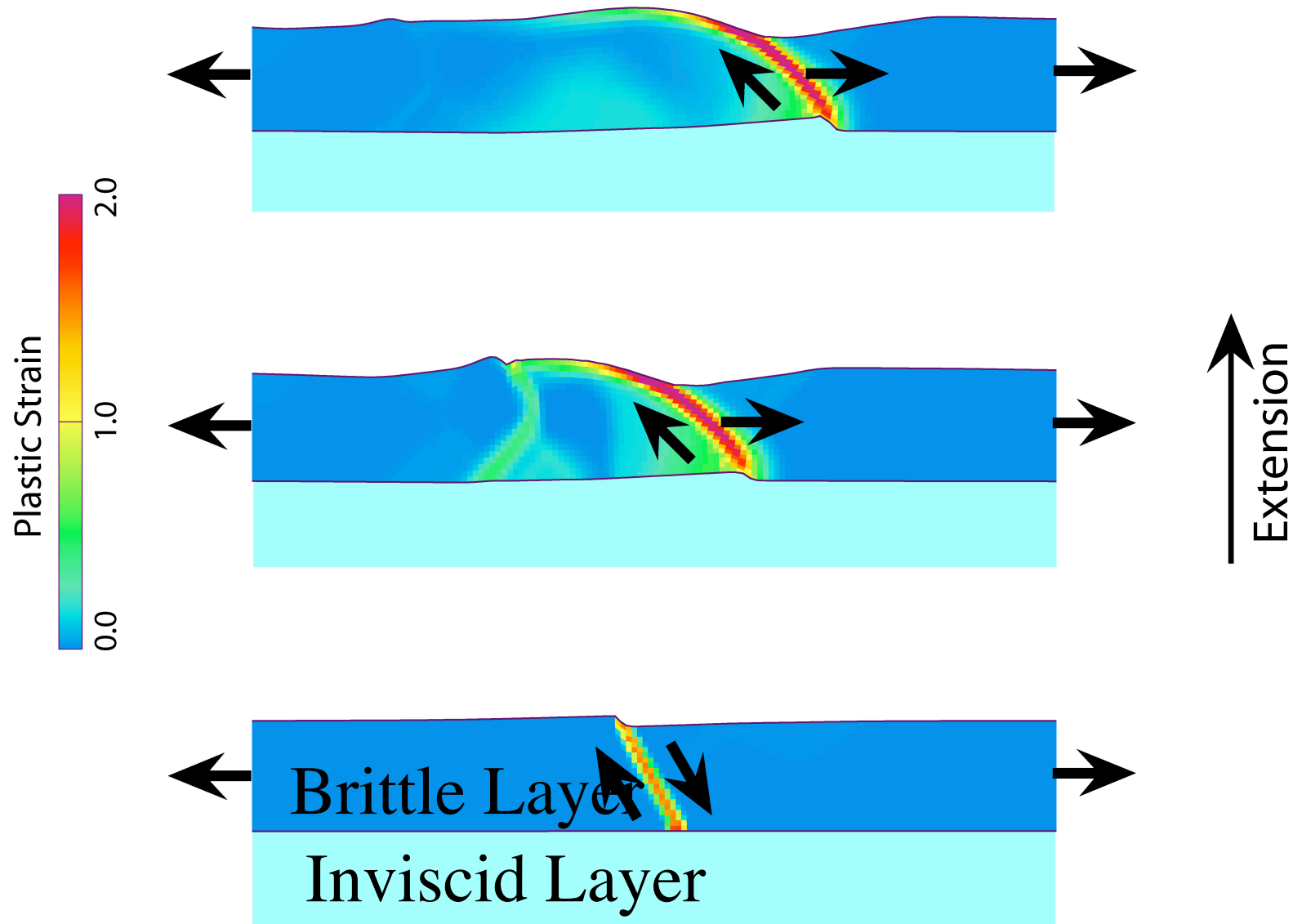


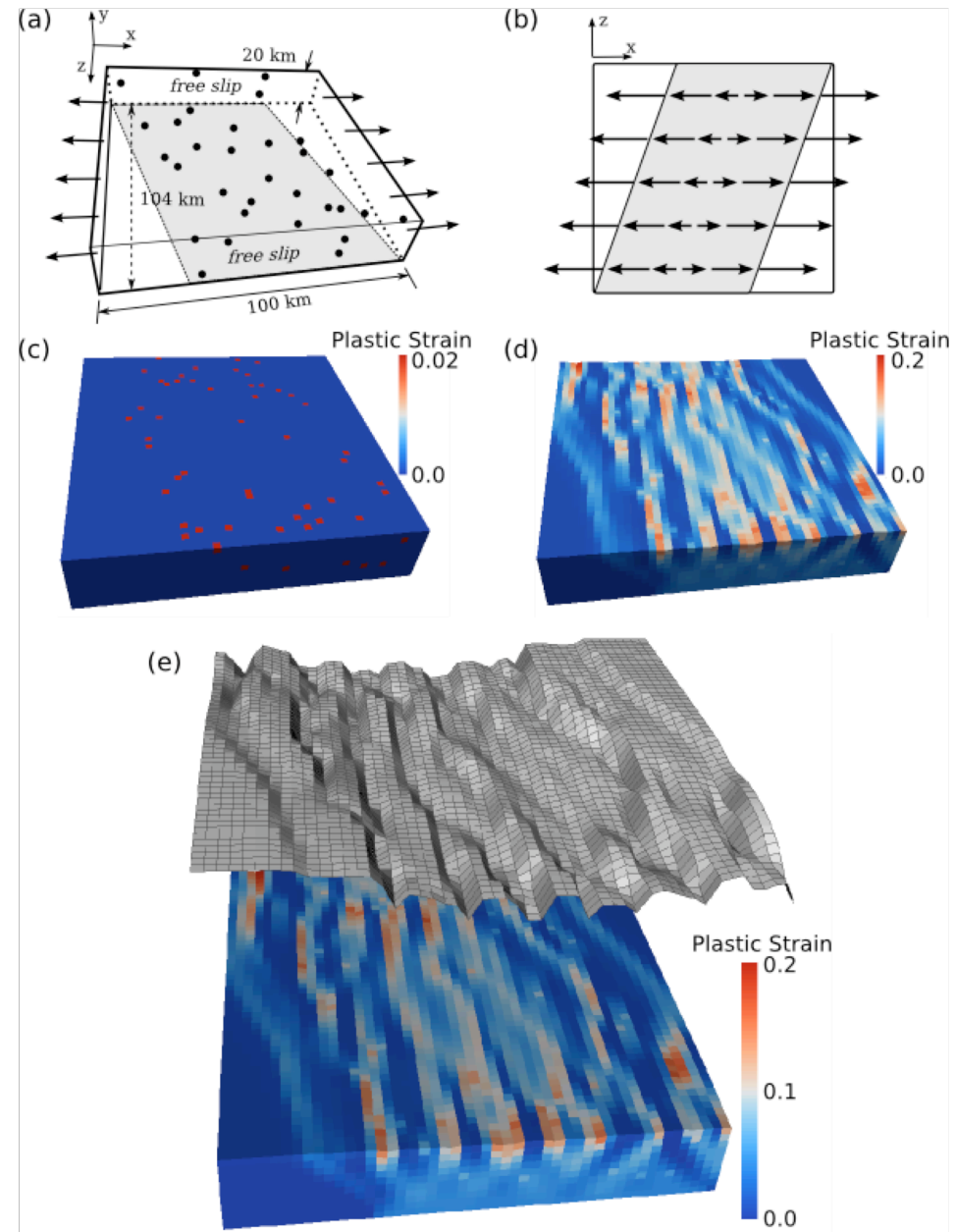
$$C(0) = 44 \text{ MPa}$$

$$H = 15 \text{ km}, \Delta x_c = 1.5 \text{ km}$$

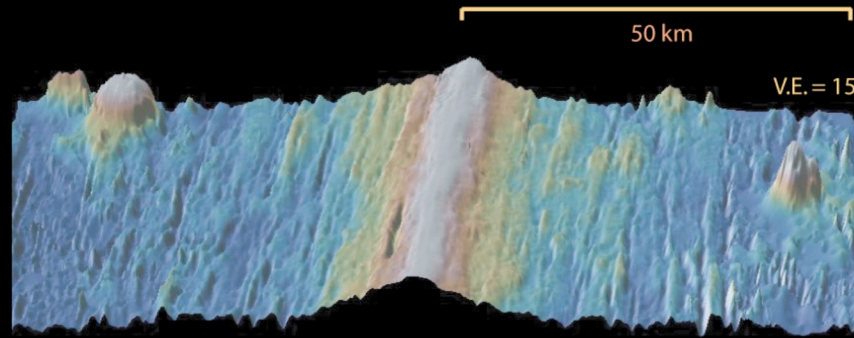


Extension of Floating Brittle Layers:
Single **Fault** Moves with **Upper Plate**

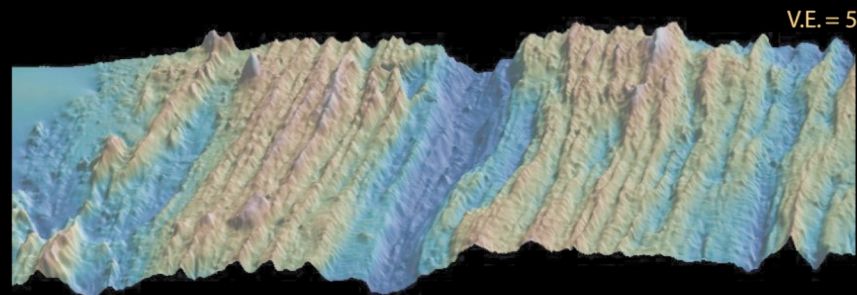




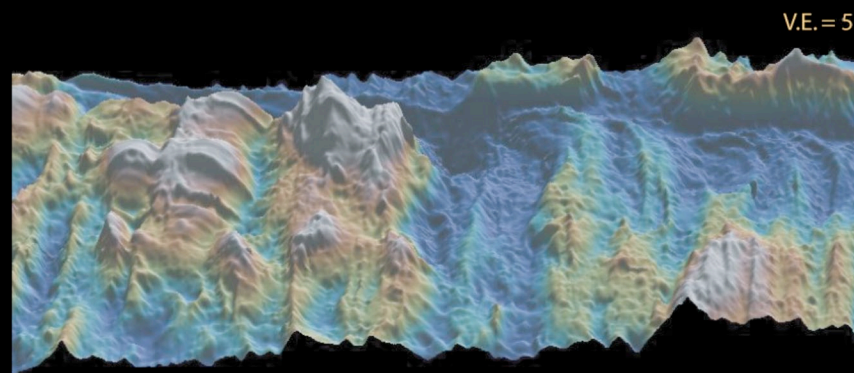
From Eunseo Choi



AXIAL HIGH

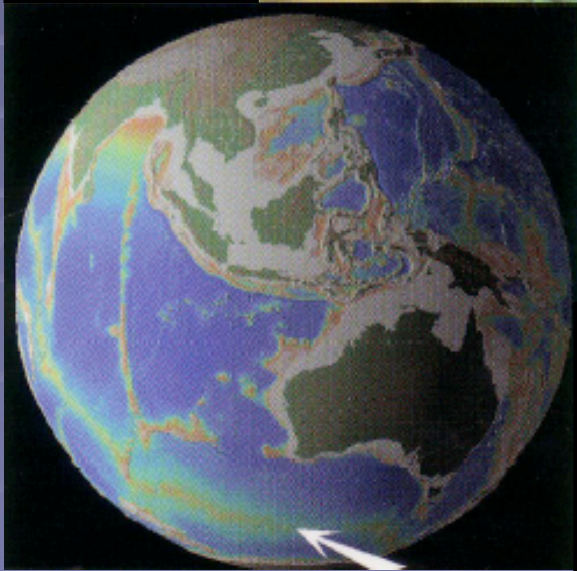
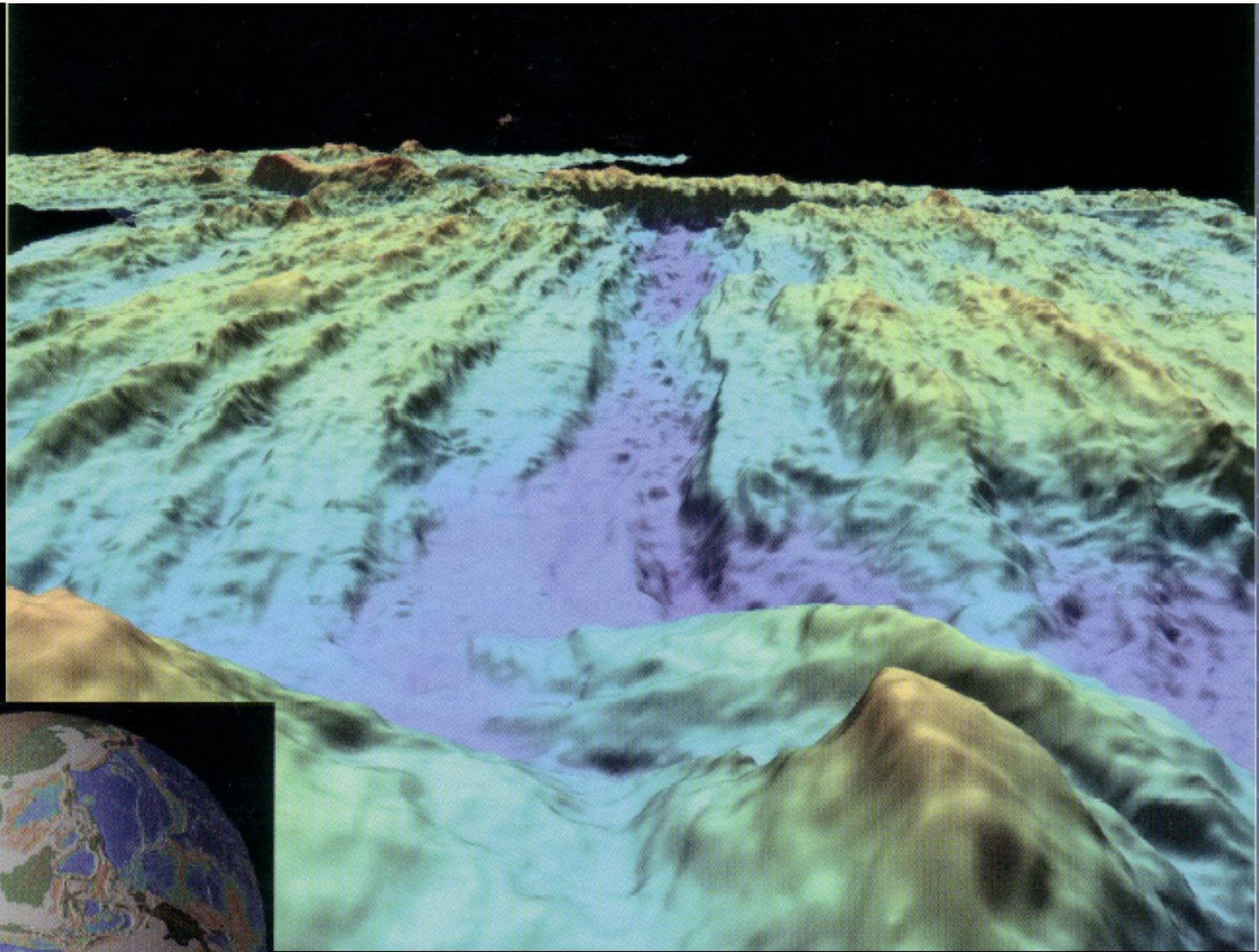


AXIAL VALLEY

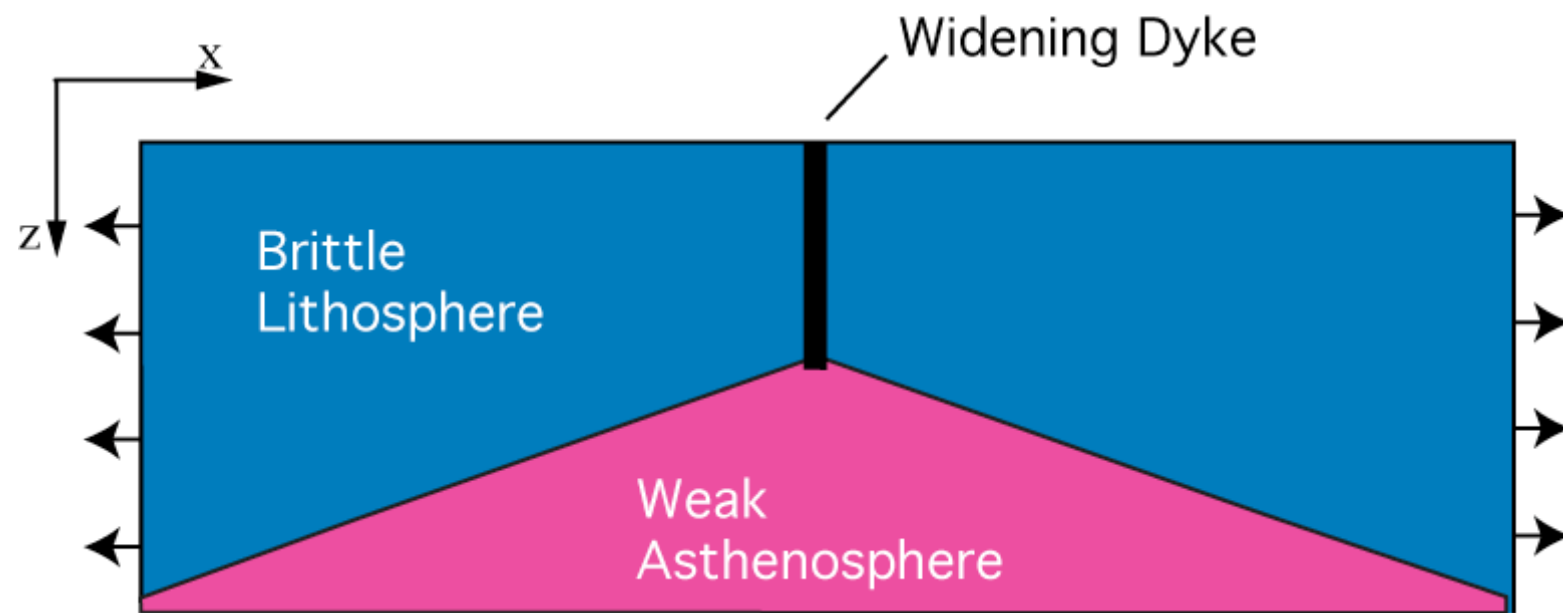


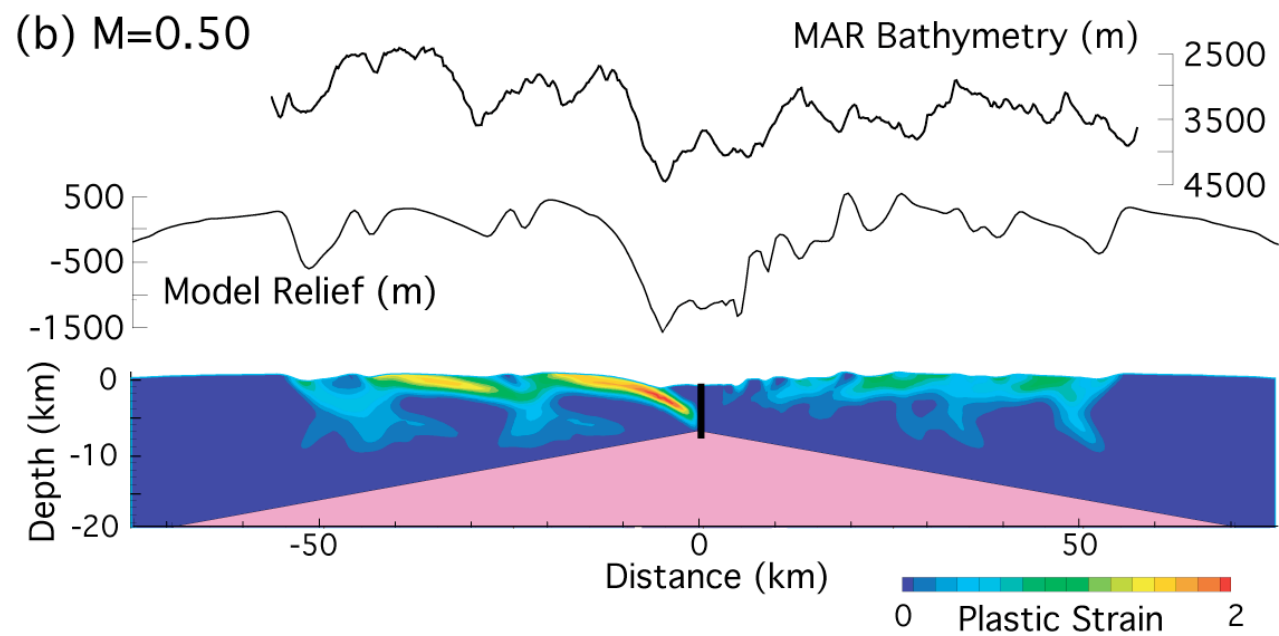
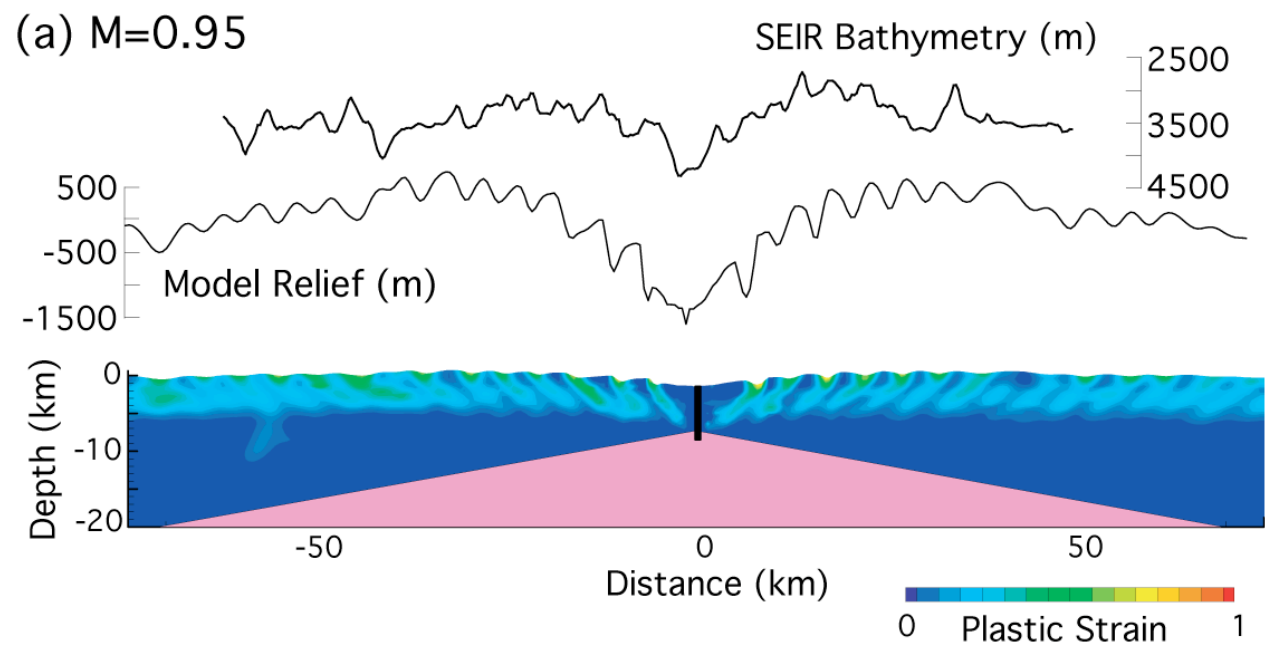
OCEANIC
CORE COMPLEX

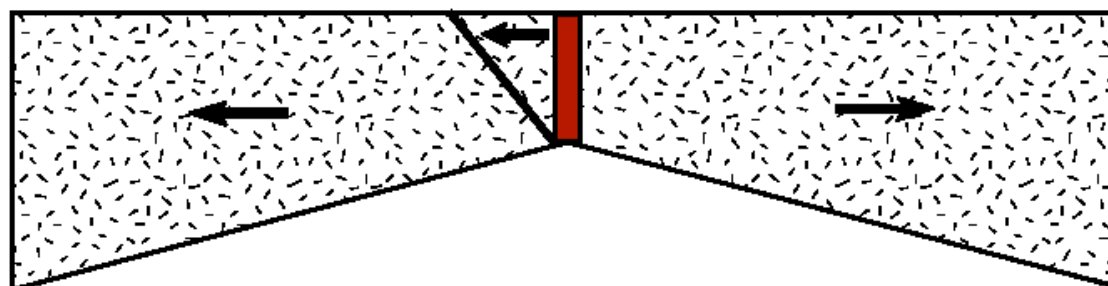
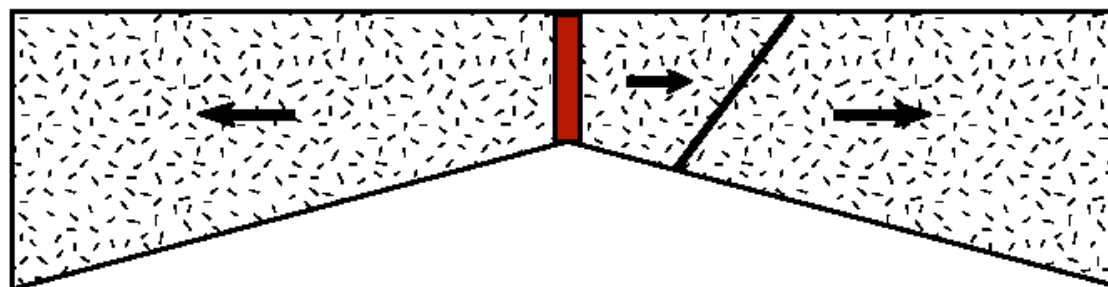
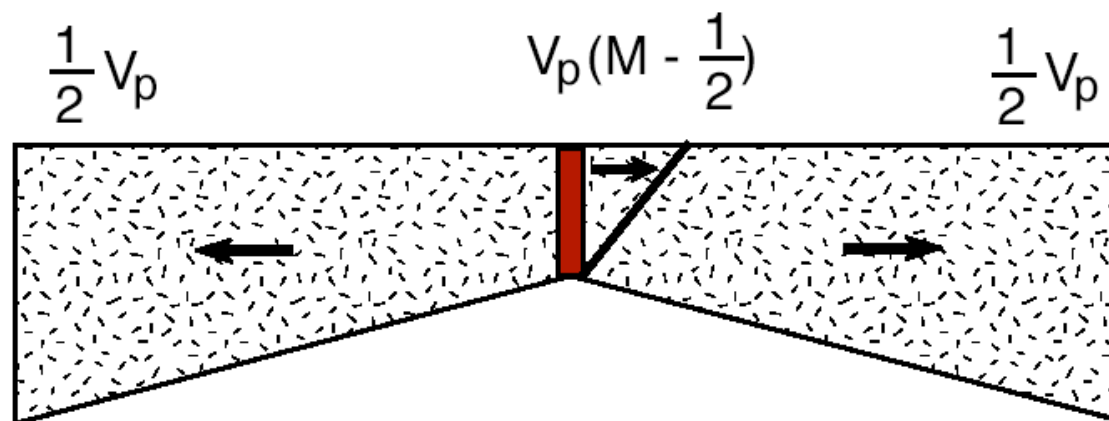


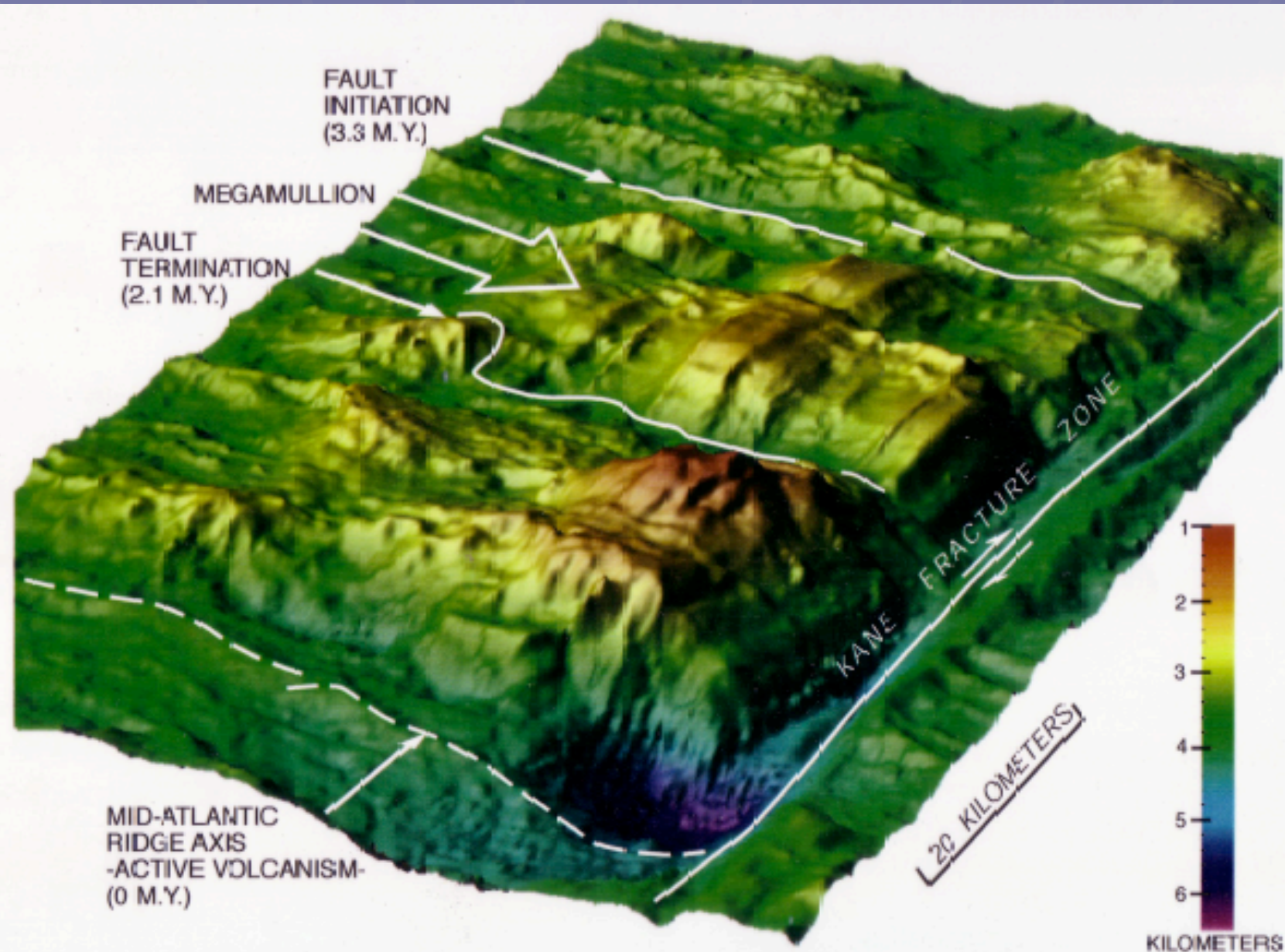


Model Setup



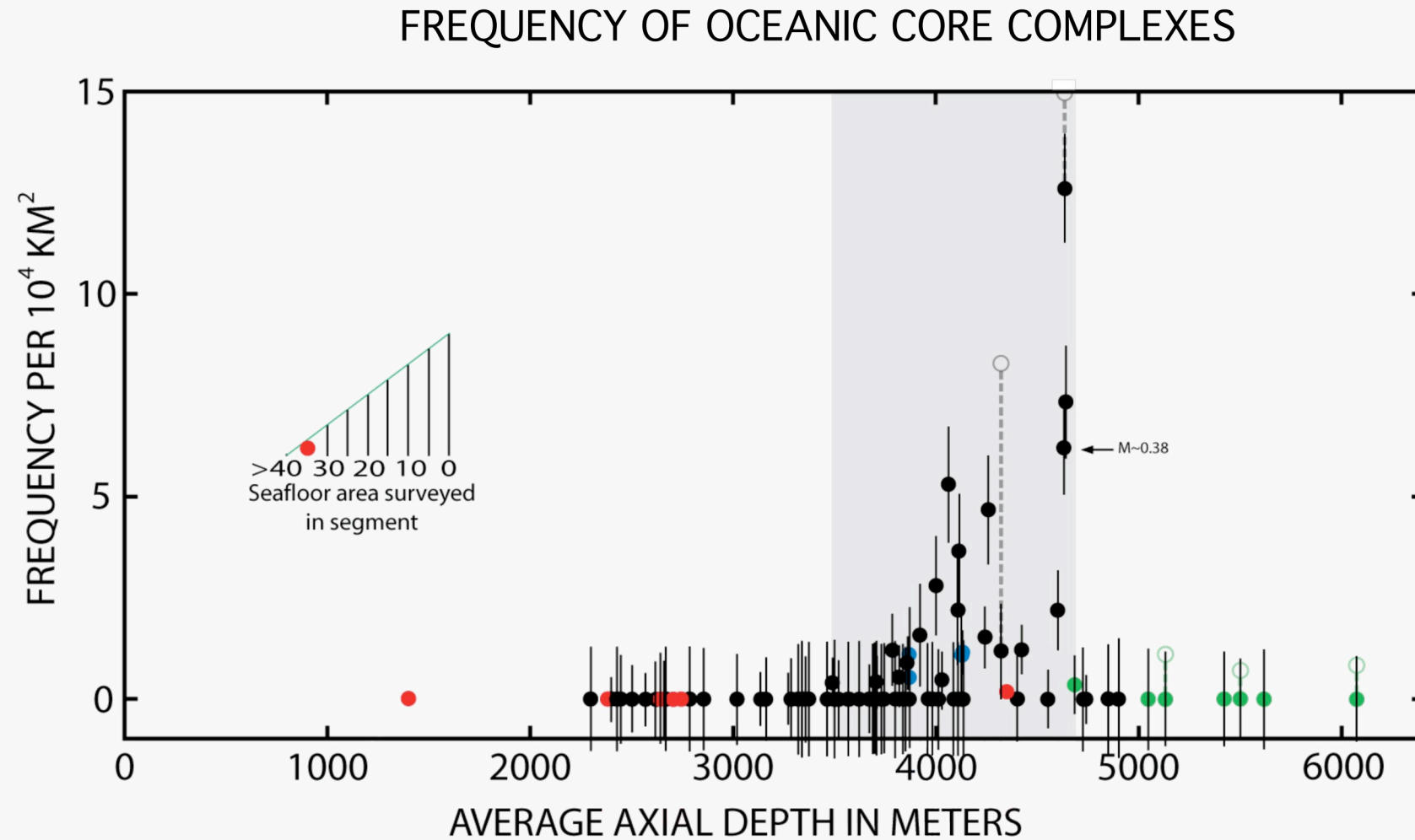




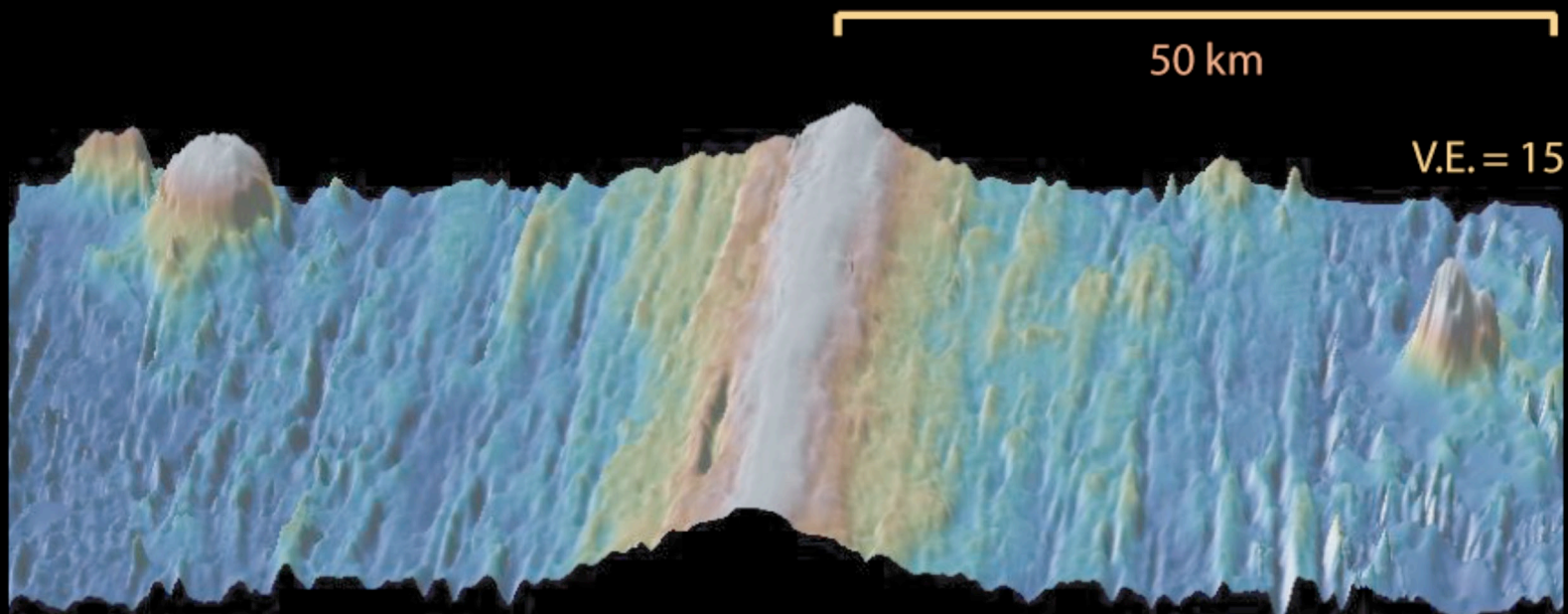


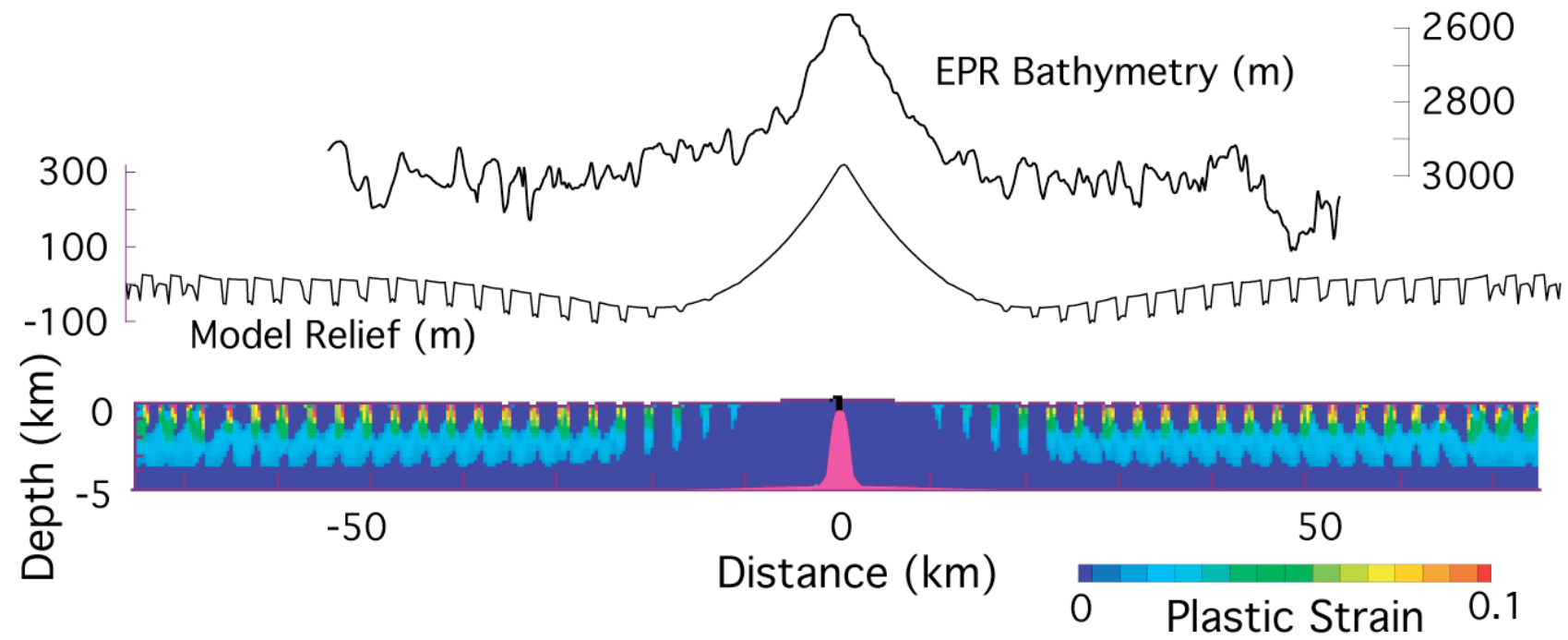
TUCHOLKE (1998)

Data is consistent with the 'Goldilocks Hypothesis'



Tucholke, Behn, Buck and Lin, Geology (2008)





Problem: For fixed M

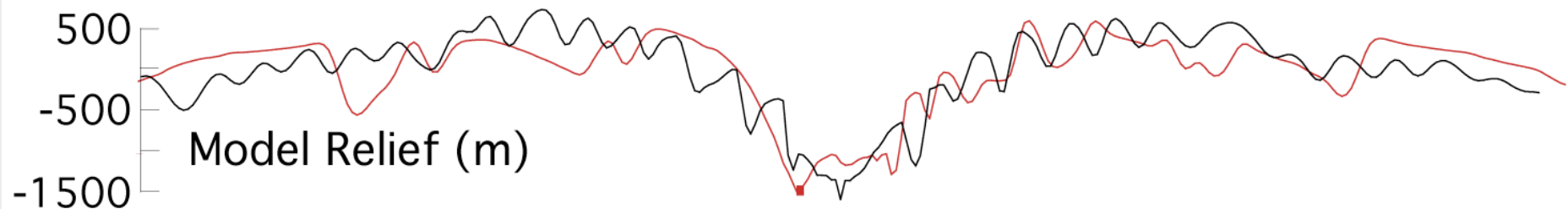
Model gives either a high for $M=1$ or a very deep low for $M<1$

$M=1.0$



$M=0.95$

$M=0.50$

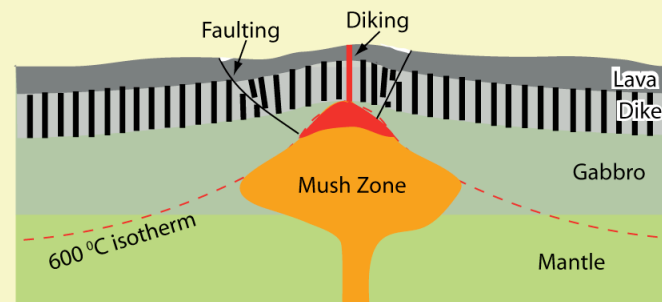


New Model

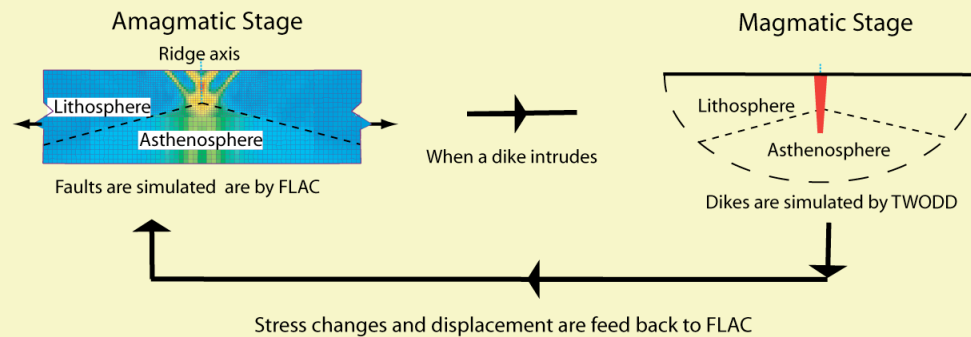
Possible Solution

Magma input, and so M , increases with axial depth.

Rationale: More magma is pulled into a deeper section of ridge axis where pressures are lower.

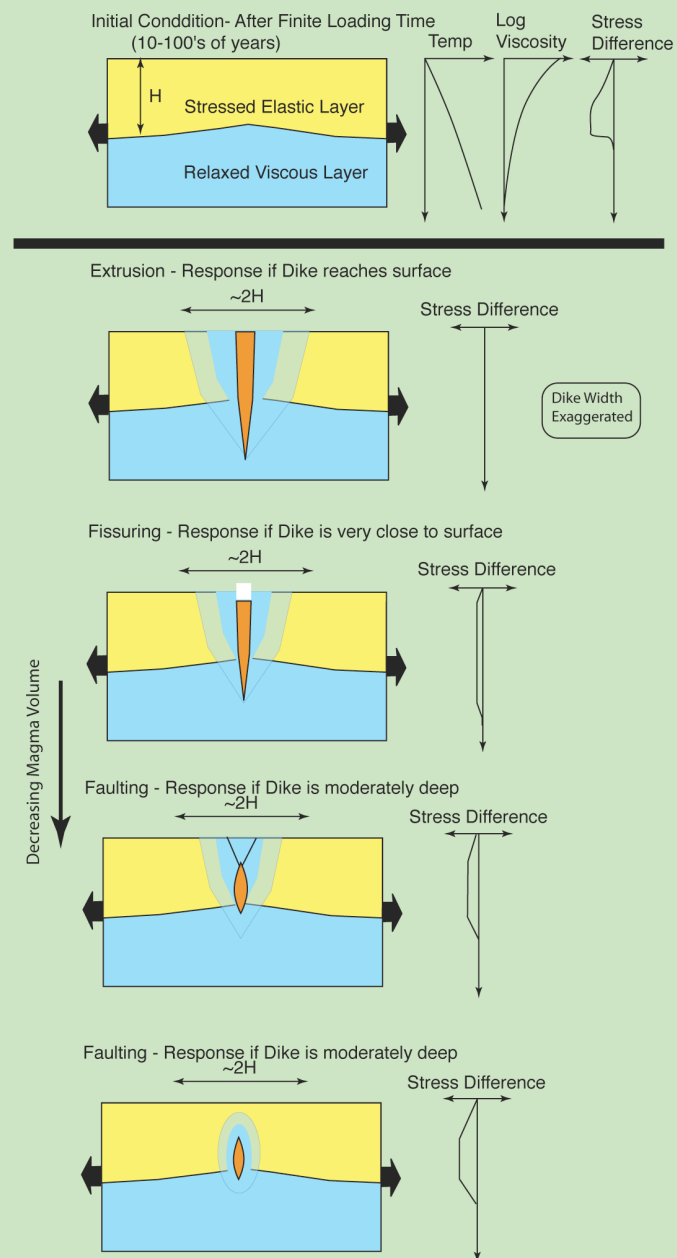


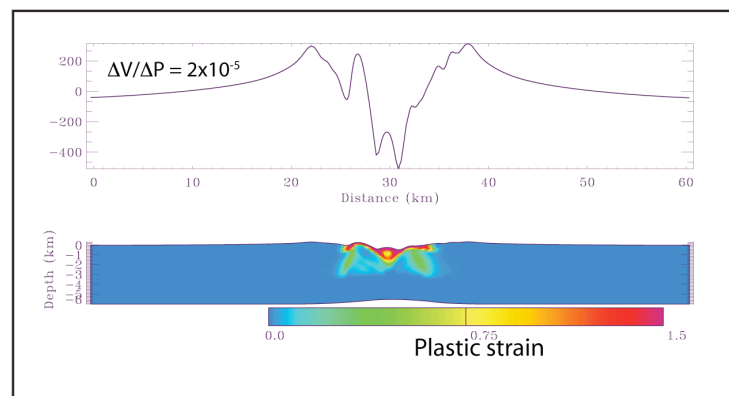
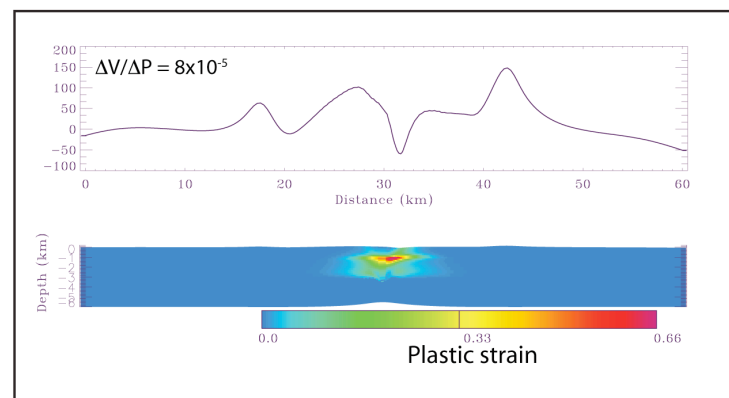
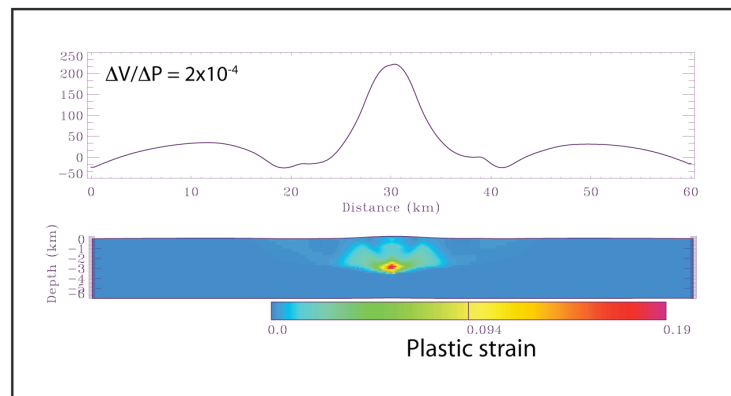
We simulate periodic dike opening and fault offset in response to an evolving stress field produced by plate separation.



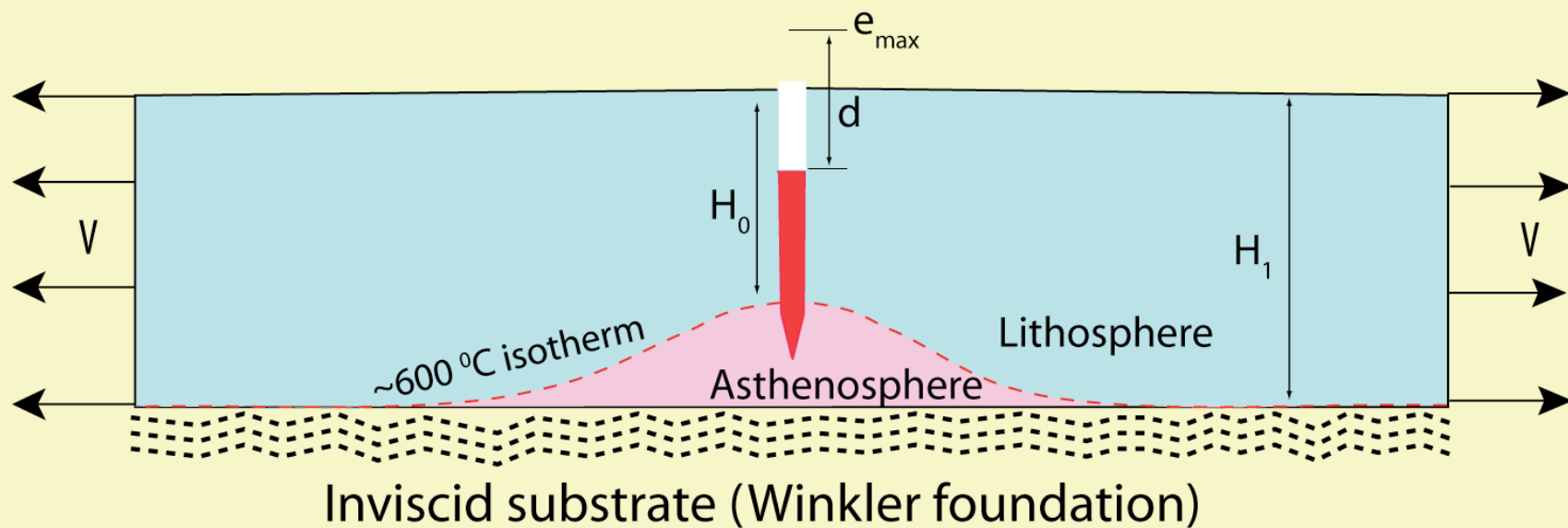
Magma input increases with decreasing axial depth by a set relation between magma volume injected in a dike episode and magma pressure ($\Delta V/\Delta P$). Magma that does not fill a dike is extruded.

Effect of Magma Volume on the Type of Dike Intrusion (cases allowed in the new model)

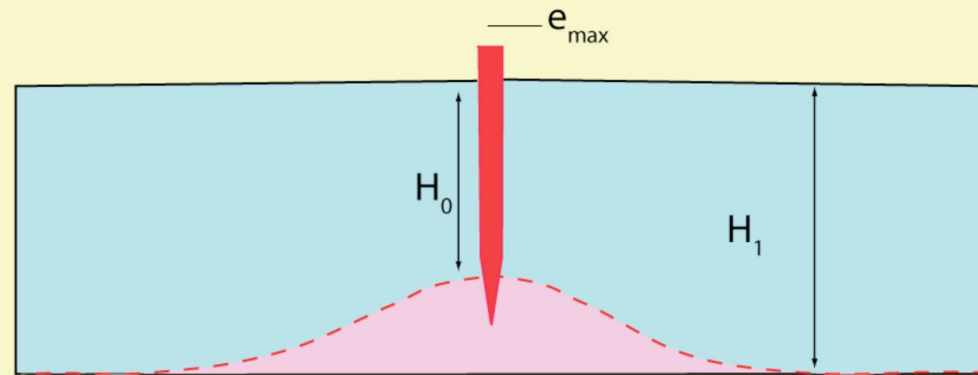




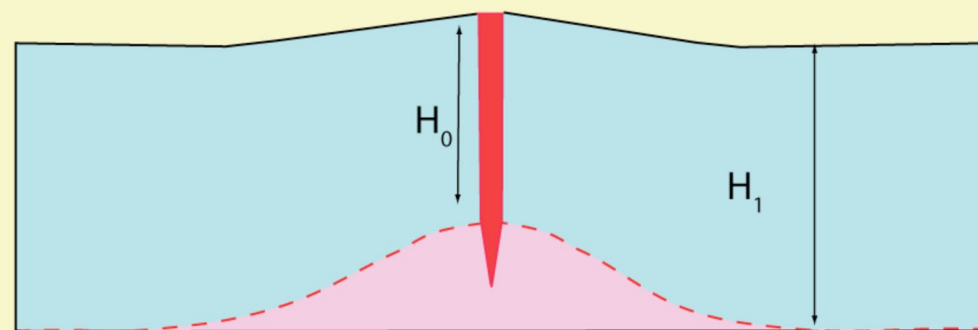
Interpretation of Model Results



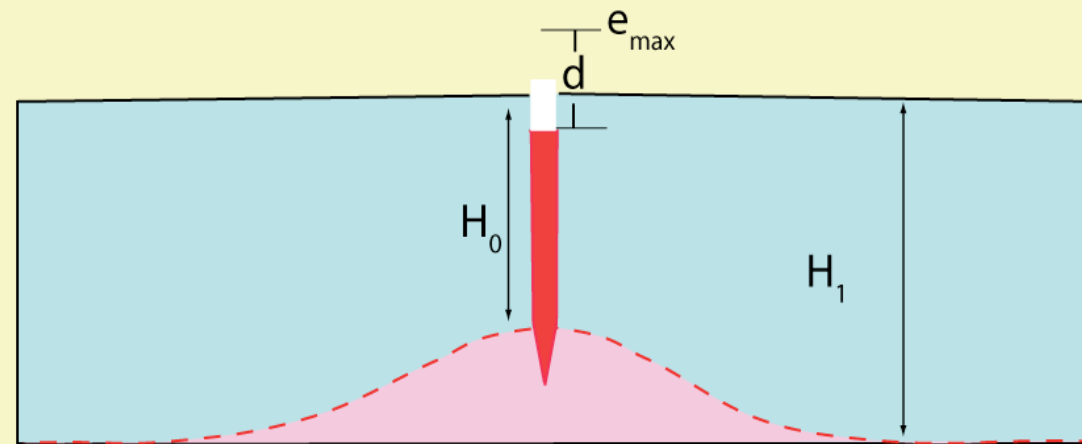
Initial Dike for $d < e_{\max}$



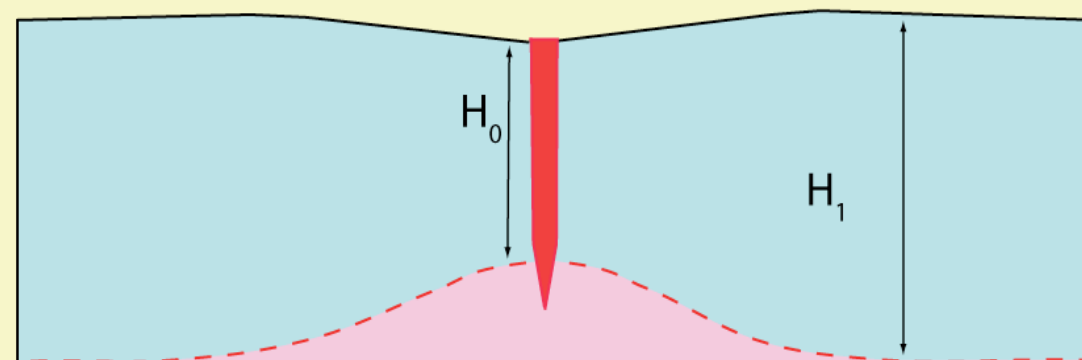
Steady-State for $d < e_{\max}$



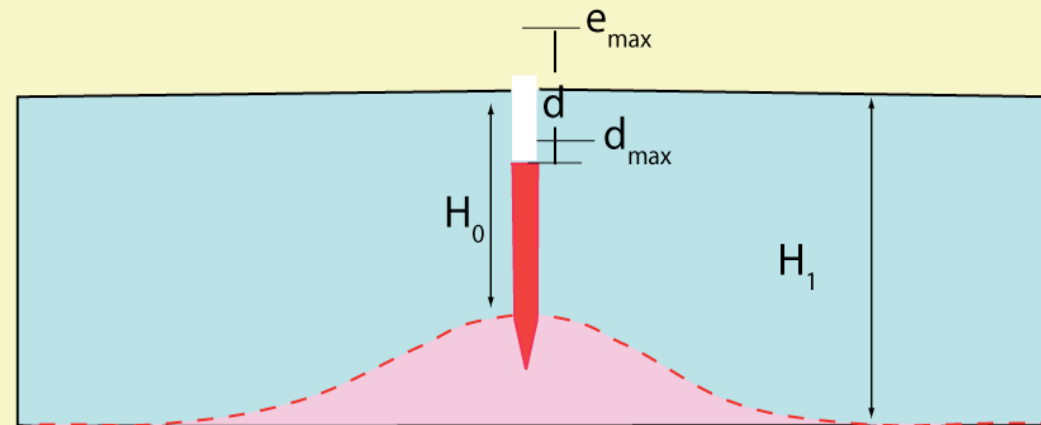
Initial Dike for $e_{\max} < d < d_{\max}$



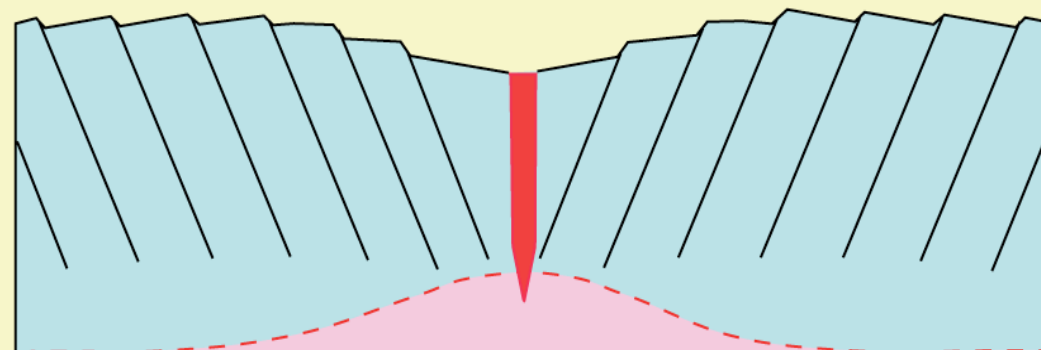
Steady-State for $e_{\max} < d < d_{\max}$



Initial Dike for $d > d_{\max}$



Steady-State for $d > d_{\max}, M < 1$



Conclusions

1. M must be a function of axial depth (d) to get the observed range of axial depths.
2. If the axial depth is less than the maximum tectonic-controlled depth (d_{max}) then $M=1$.
3. For $M=1$ axial valleys the extrusive layer thickness should be proportional to fault stretching.
4. For $M<1$ the axial depth equals d_{max} .
5. For $M\sim 0.5$ the model gives oceanic core complex-like structures on one side of the axis.