



Autonomous Vehicle GNC

- **Introductions**

- **Overview**

- **Autonomous GNC**

- Basic Control
- ION Robotic Mower
- Global Challenge
- Mindstorm Robots

- **Lego® Mindstorms Intro**

- **Lego® Mindstorms Challenge**

- **GNC issues for autonomous vehicles (Mikel - 20 min)**

- **Basic Control**

- **ION Robotic Lawn Mower – (Jade – 40 min)**

- **Miami University’s Approach**

- **A Global Challenge (Carrie and Casey – 1 hour)**

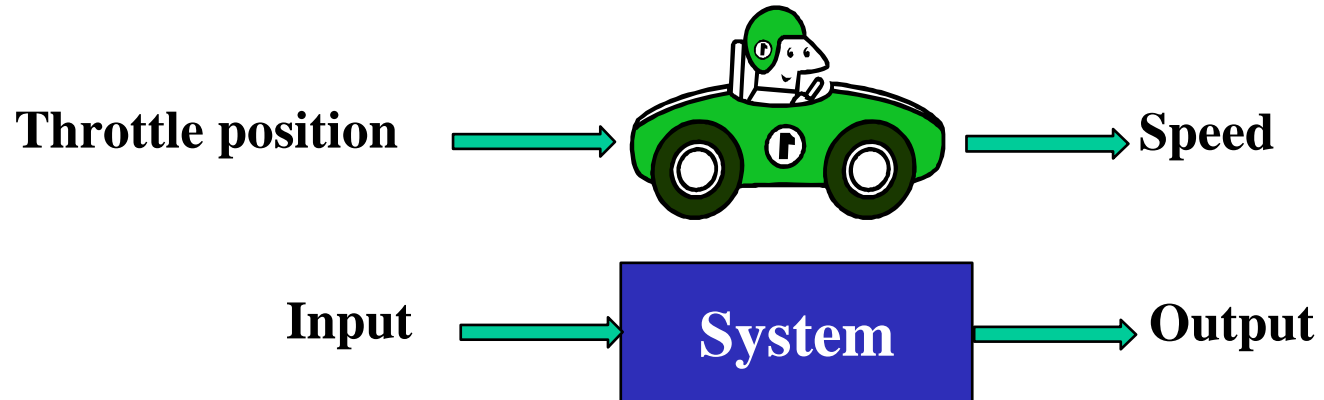
- **Mindstorm Robots at de Universite de Cocody (30 min)**





An Example of Control System: Open-Loop Control

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How much input is needed to get the desired output?



Problems with open loop control:

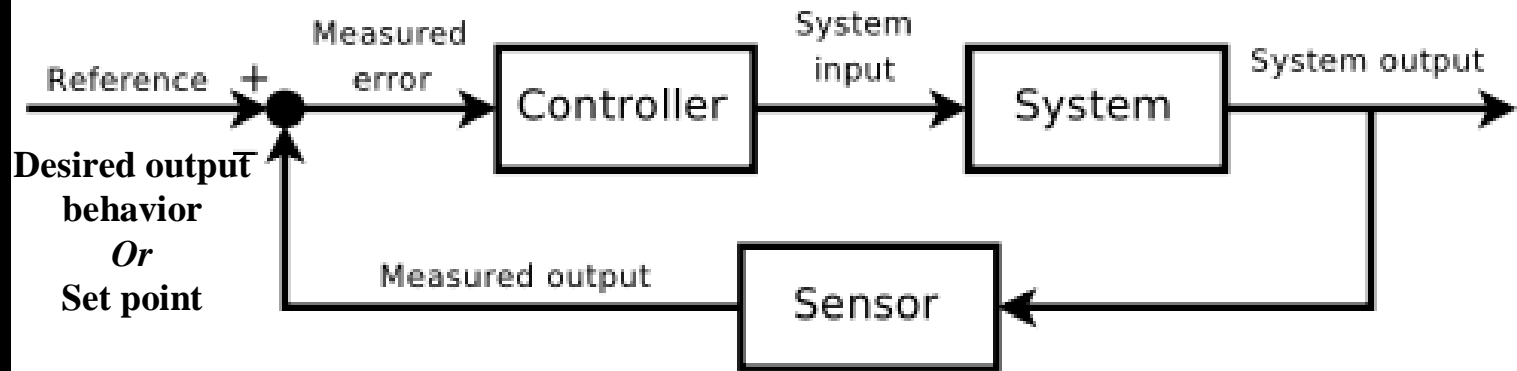
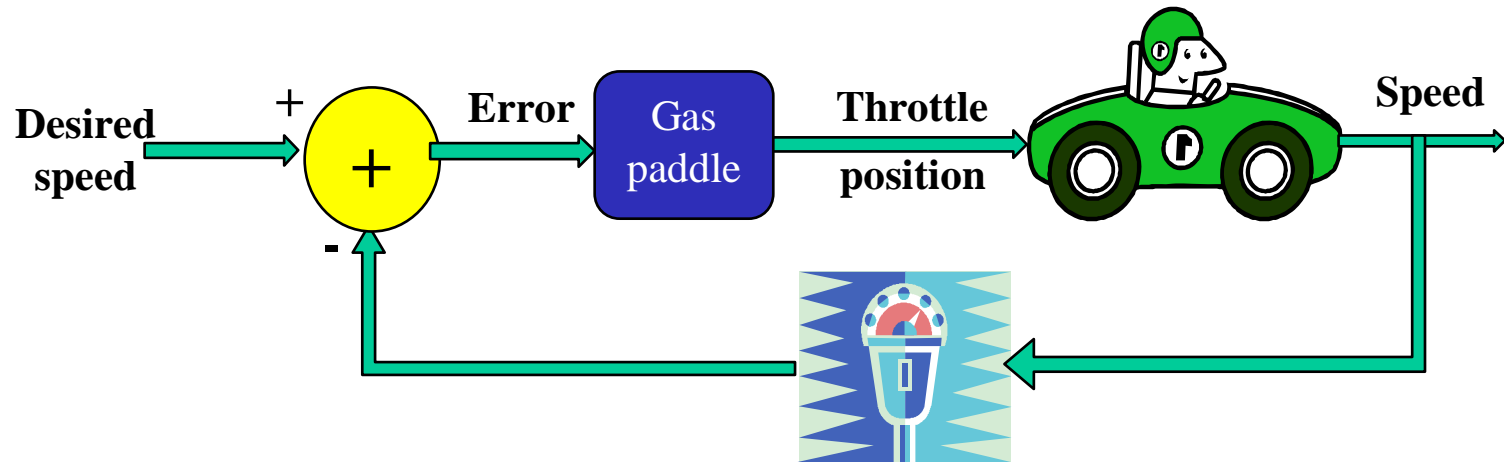
Calibration results are invalid when *environment/system* changes

Slopes, vehicle mass, wind, tire pressure, gas quality, road surface, engine wear, ...



An Example of Control System: Closed Loop

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Can you think of a closed-loop feedback control system in practice?



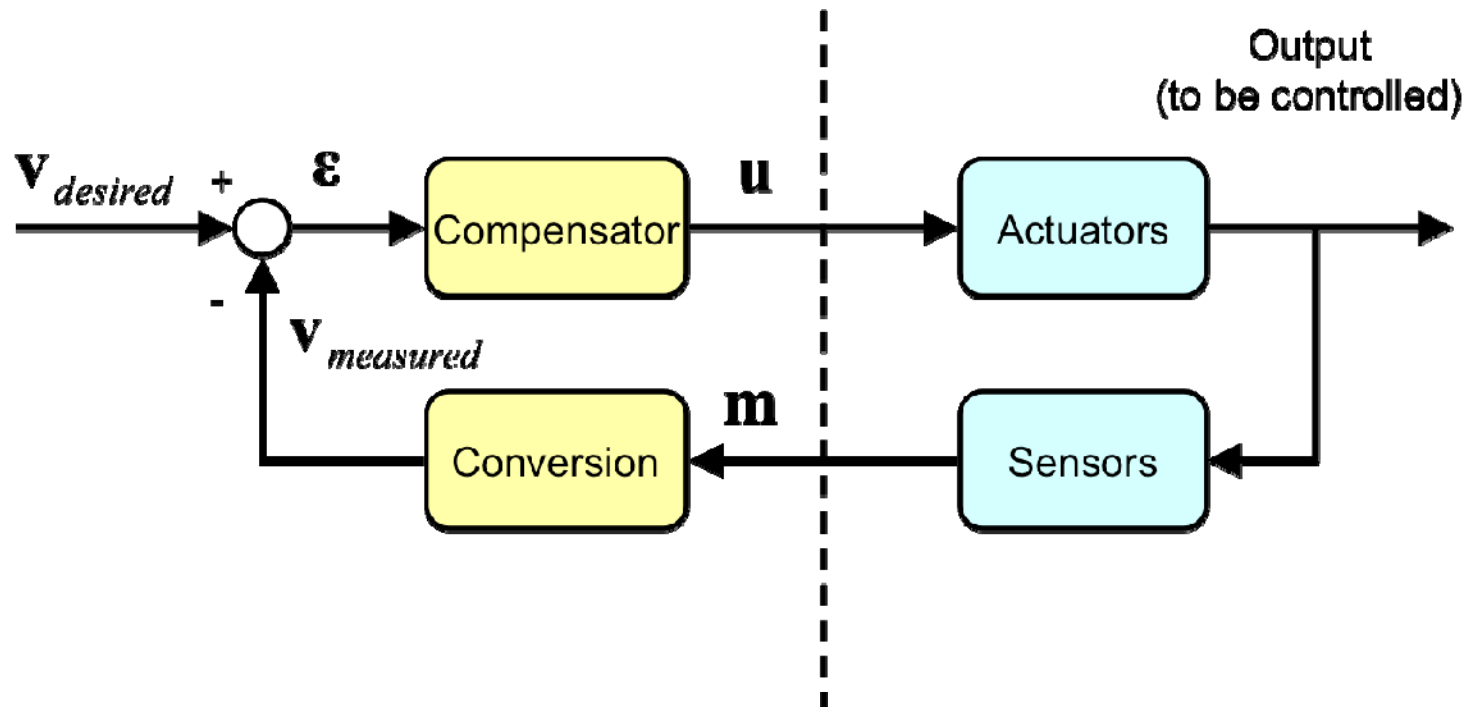


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Basic Feedback Controller

In general



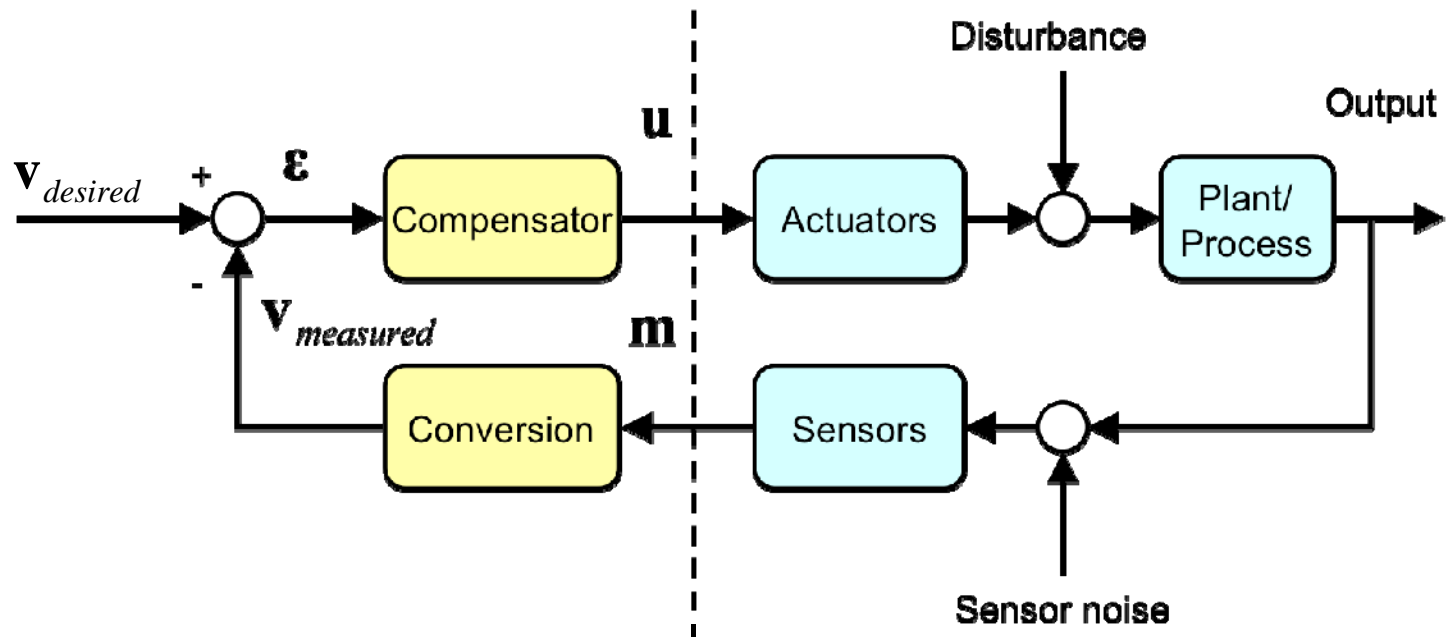


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Basic Feedback Controller

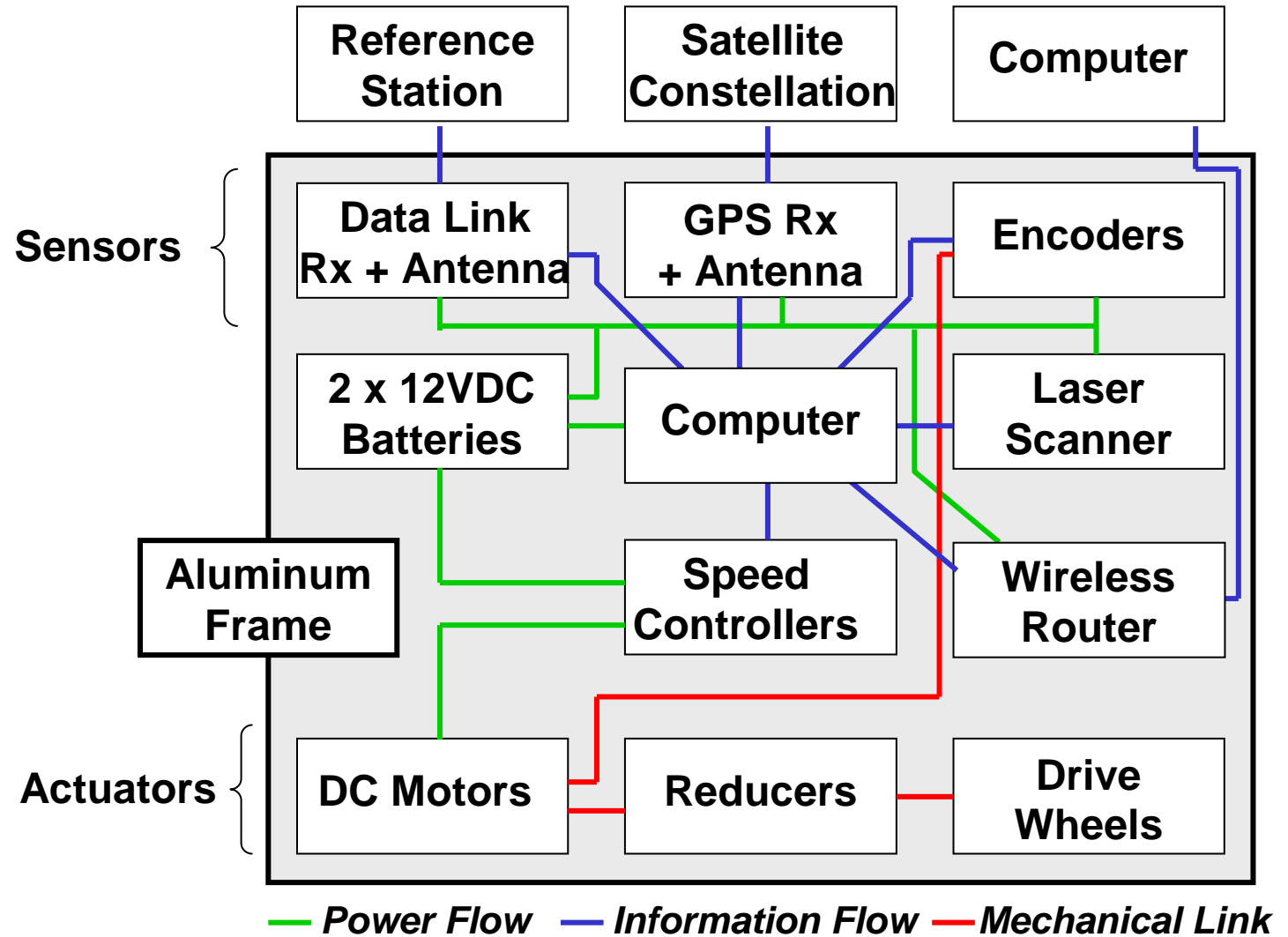
However, in reality





Hardware architecture

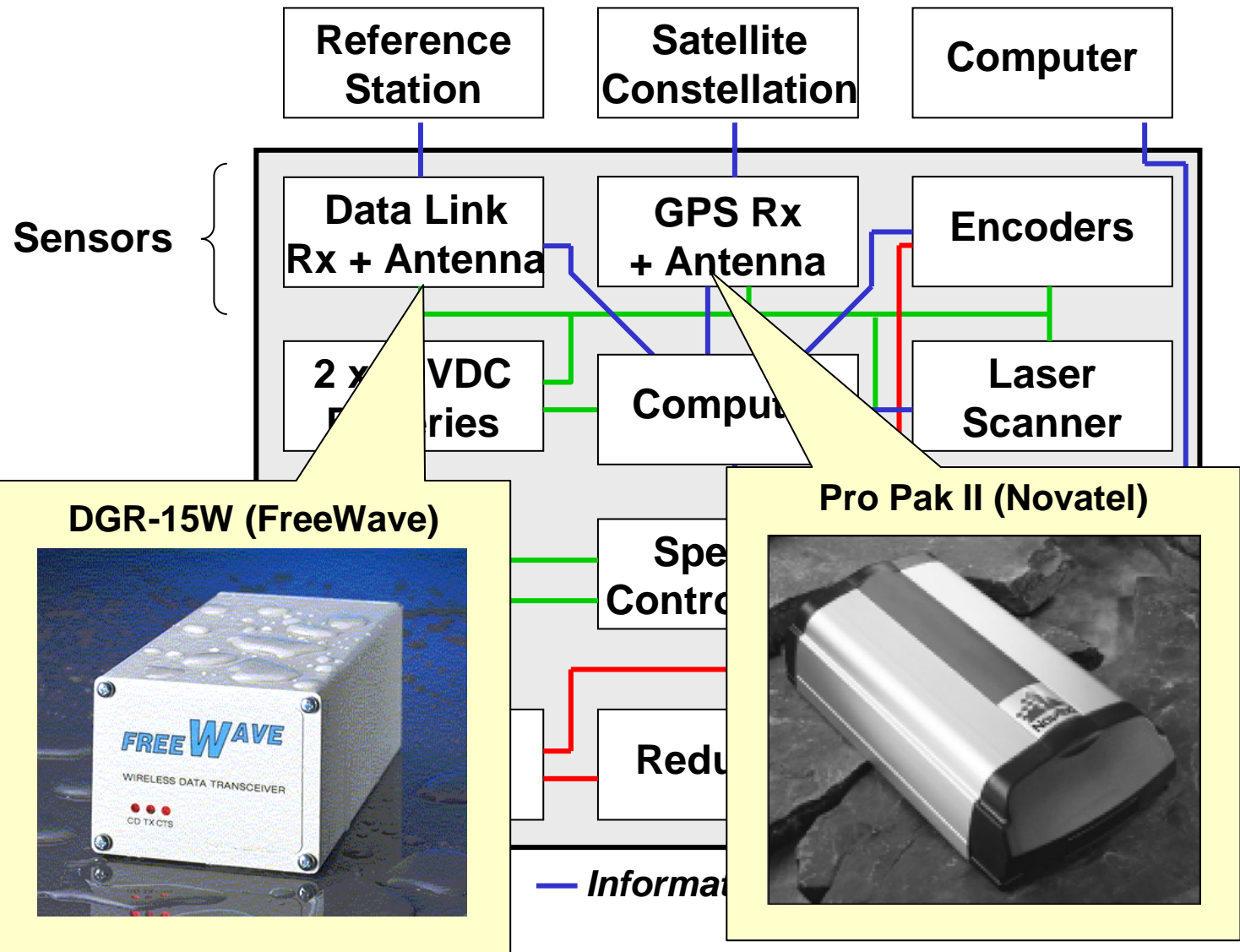
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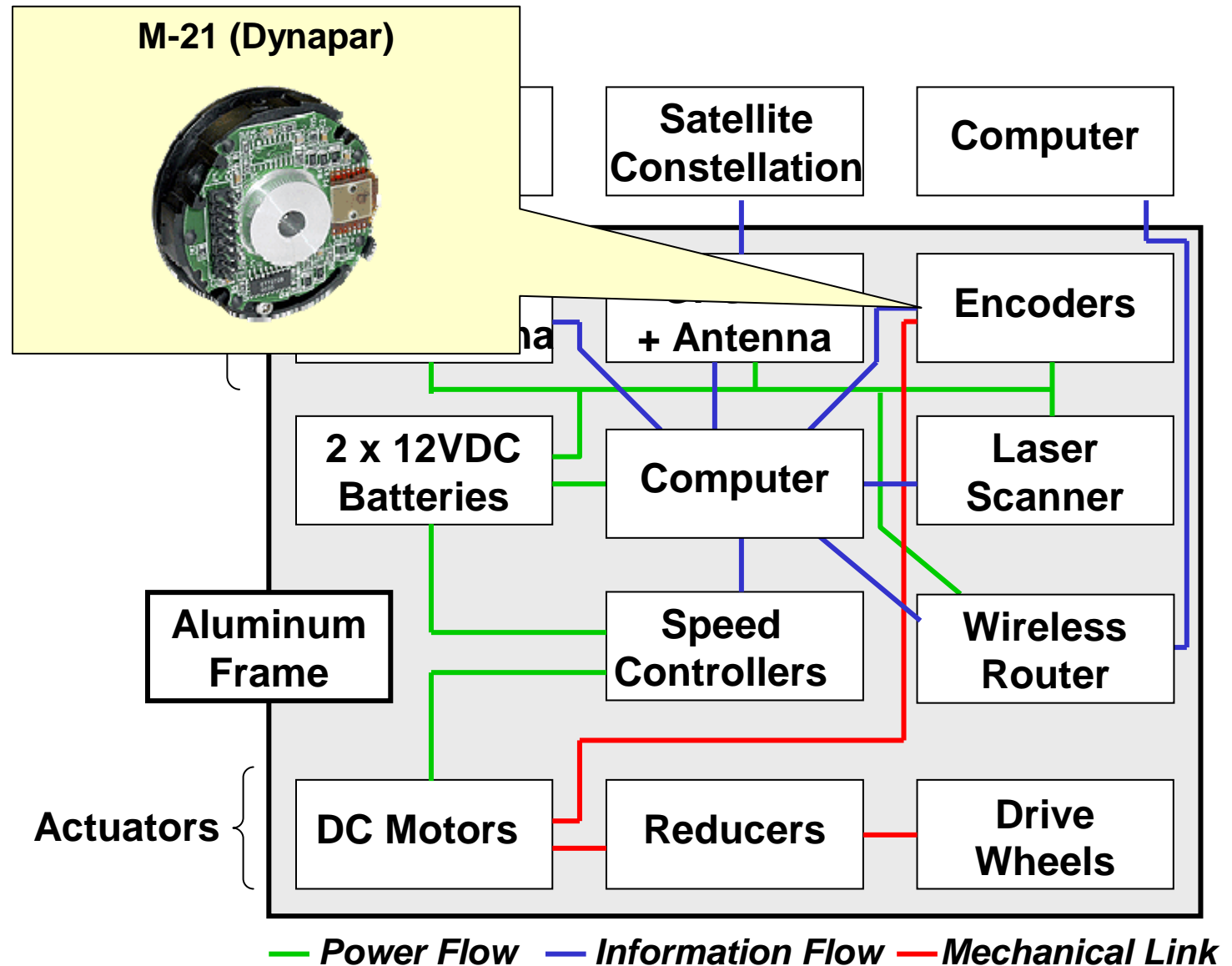




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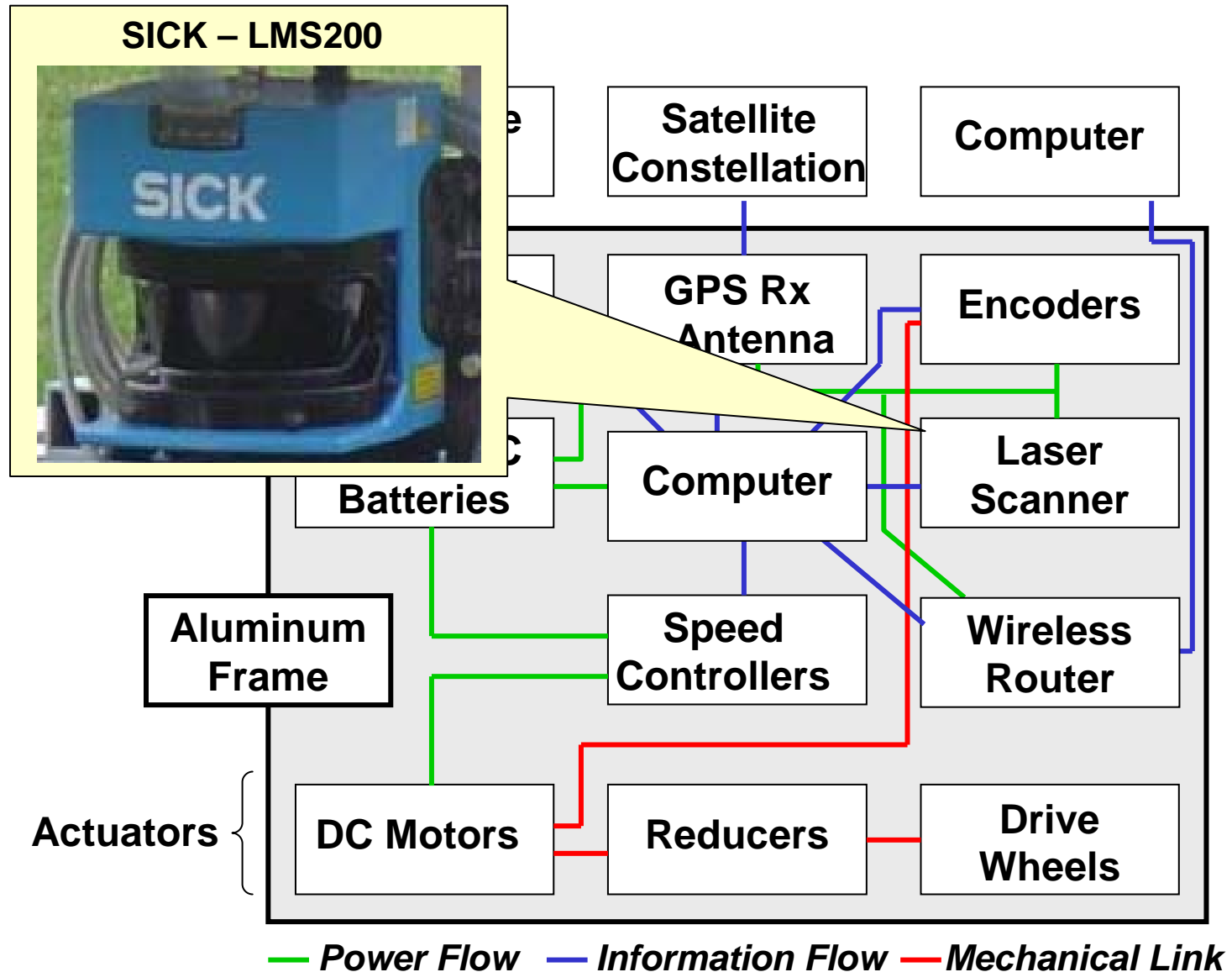
Hardware architecture





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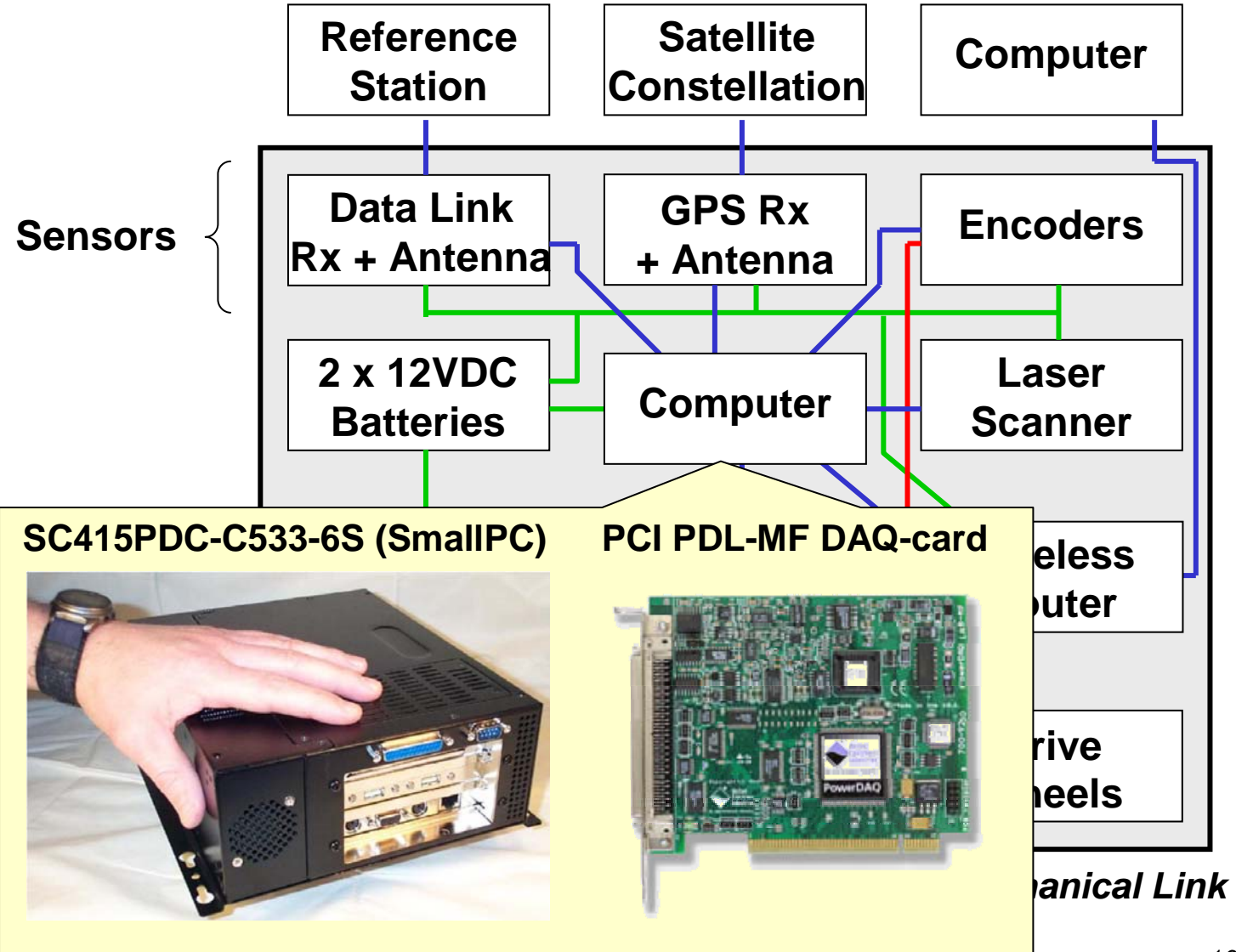
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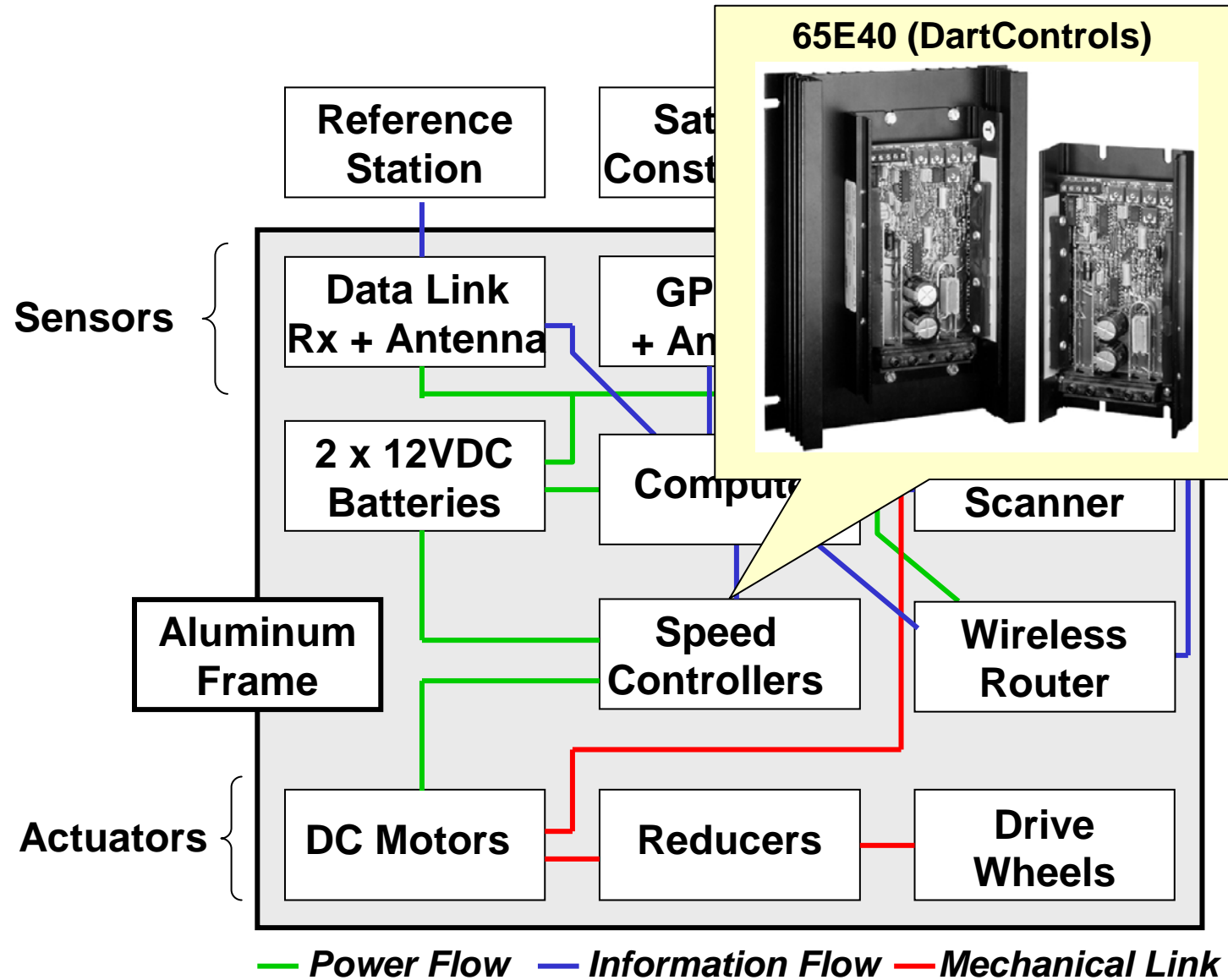
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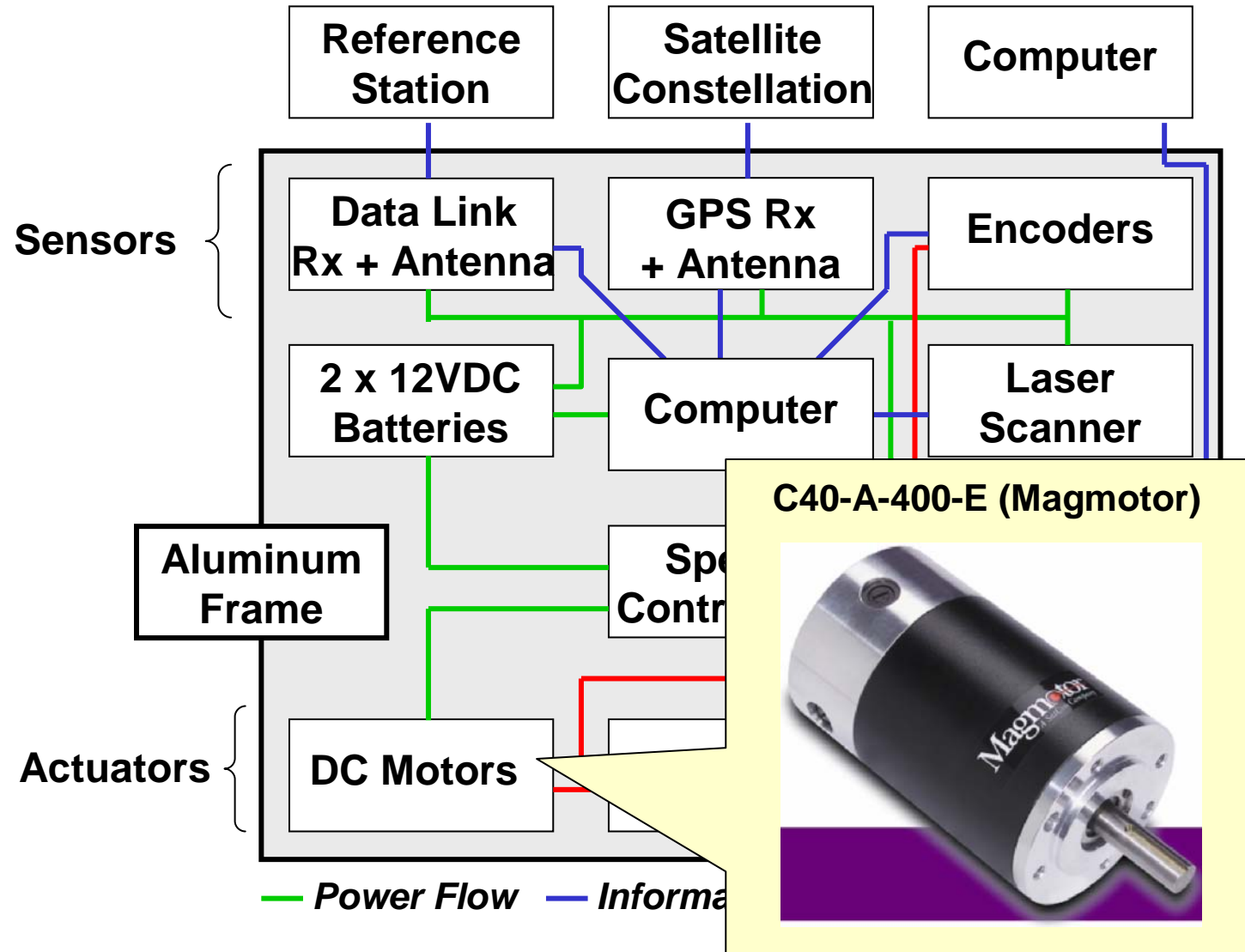
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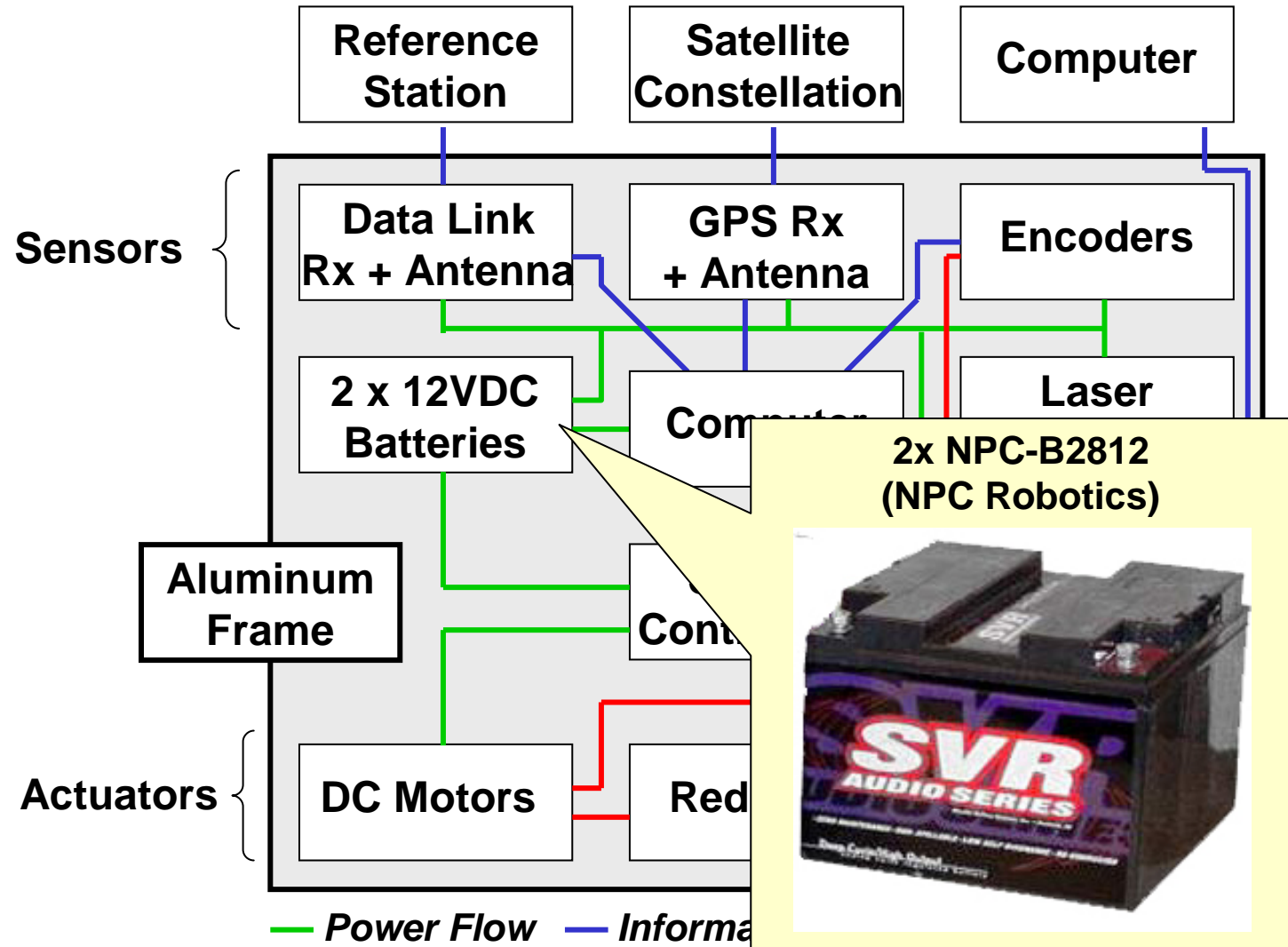
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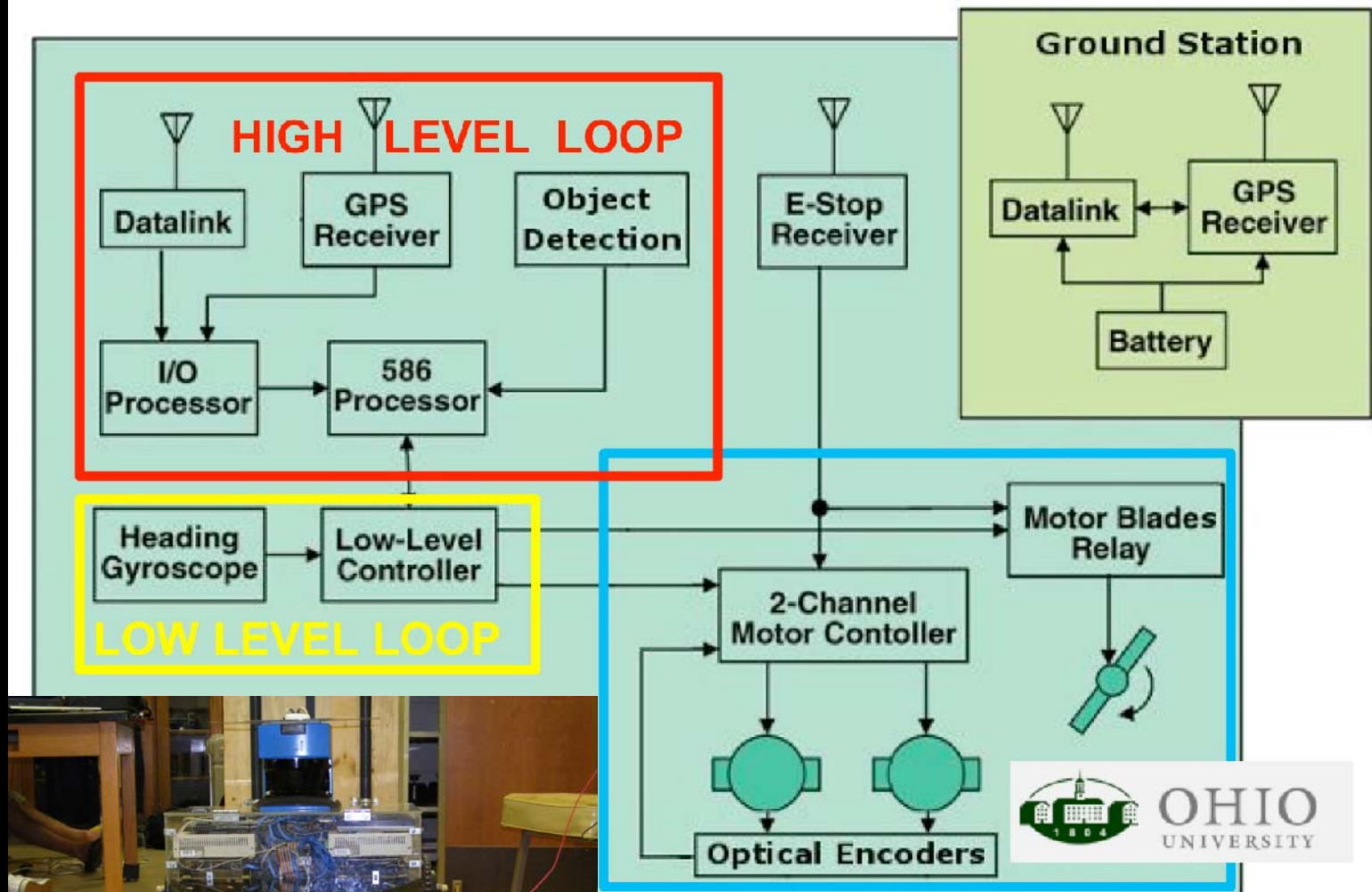
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Ohio University System Design

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INNER LOOP

