



Influence of In-Plane and Out-of-Plane Ultrasonic Oscillations on Sliding Friction

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Trieste**



Outline

Experimental Set-Up

In-Plane Oscillations

- Oscillations in Sliding Direction

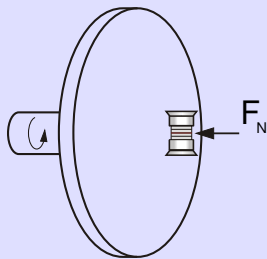
- Oscillations Normal to the Sliding Direction

Out-of-Plane Oscillations

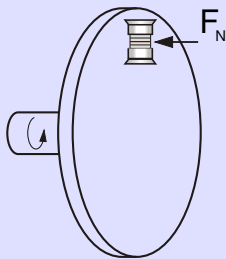
Conclusions



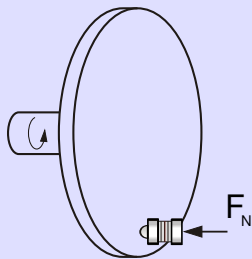
Experimental Set-Up: Oscillation Directions



oscillation
in sliding direction

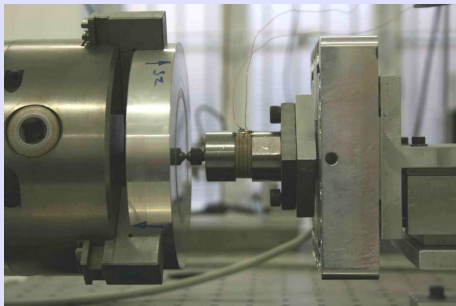


oscillation normal
to the sliding direction



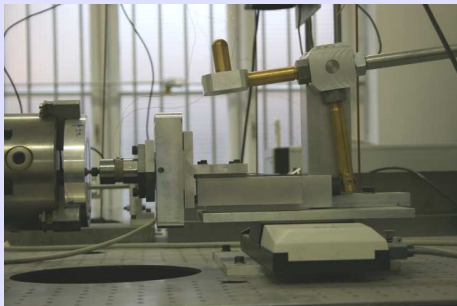
oscillation normal
to the sliding plane

Experimental Set-Up



- ▶ Rotary drive (step motor)
- ▶ Rotational disc (polished, hardened steel)
- ▶ Probe (mostly steel) with build-in piezo ceramic elements
- ▶ Oscillations match the eigenfrequency of the sample
- ▶ Force application via a lever arm and a guiding device

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Oscillations in Sliding Direction

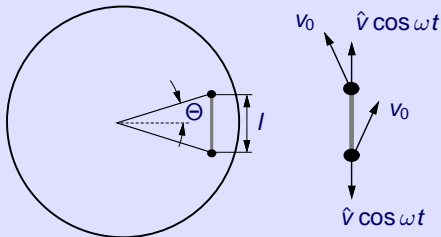


Fig.: Geometrical Set-Up

- ▶ $l = l_0 + \Delta l \sin \omega t \Rightarrow$
 $\frac{dl}{dt} = \Delta l \omega \cos \omega t$
- ▶ Each end of the sample has the oscillation velocity
 $v = \frac{\Delta l}{2} \omega \cos \omega t = \hat{v} \cos \omega t$
- ▶ Θ : Opening angle between plate center and sample end
- ▶ Coulomb's friction law:
 $F = \mu_0 F_N \text{sgn}(v_{rel})$
- ▶ v_0 : Sliding velocity of the disc
- ▶ $v_{rel,1} = v_0 \cos \Theta - \hat{v} \cos \omega t$
 $v_{rel,2} = v_0 \cos \Theta + \hat{v} \cos \omega t$

Oscillations in Sliding Direction

μ : Coefficient of friction averaged over one oscillation period

$$\begin{aligned}\mu &= \frac{1}{2\pi} \int_0^{2\pi} \frac{F}{F_N} d\xi \quad \text{with } \xi = \omega t \\ &= \frac{1}{2\pi} \int_0^{2\pi} \frac{\mu_0}{F_N} \left(\frac{F_N}{2} \frac{v_{rel,1}}{|v_{rel,1}|} + \frac{F_N}{2} \frac{v_{rel,2}}{|v_{rel,2}|} \right) d\xi \\ &= \frac{\mu_0}{2\pi} \int_0^{2\pi} \frac{v_0 \cos \Theta - \hat{v} \cos \xi}{\sqrt{v_0^2 + \hat{v}^2 \cos^2 \xi - 2v_0 \hat{v} \cos \Theta \cos \xi}} d\xi\end{aligned}$$

Note: μ only depends on the ratio $\frac{v_0}{\hat{v}}$

Oscillations in Sliding Direction

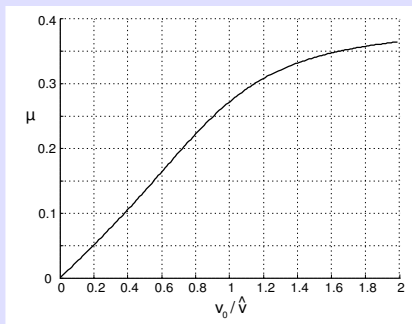


Fig.: Theoretical graph of the coefficient of friction for an amplitude $\Delta l = 0.03 \mu\text{m}$ and the angle $\Theta = 31.5^\circ$

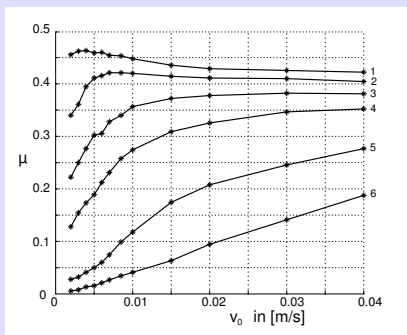


Fig.: Experimental data of the coefficient of friction of a steel-steel-couple, oscillation frequency of 45 kHz and the oscillation amplitudes: (1) $0.023 \mu\text{m}$, (2) $0.056 \mu\text{m}$, (3) $0.095 \mu\text{m}$, (4) $0.131 \mu\text{m}$, (5) $0.211 \mu\text{m}$, (6) $0.319 \mu\text{m}$

Oscillations Normal to the Sliding Direction

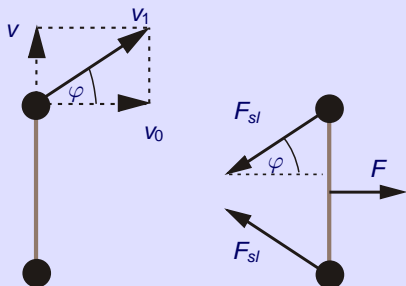


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- ▶ Each end of the sample has the oscillation velocity
 $v = \frac{\Delta l}{2} \omega \cos \omega t = \hat{v} \cos \omega t$
- ▶ v_0 : Sliding velocity of the disc
- ▶ $F_r = 2F_{sl} \cos \varphi = \mu_0 F_N \cos \varphi$
- ▶ $\tan \varphi = \frac{v}{v_0}$

Oscillations Normal to the Sliding Direction

$$\begin{aligned}\mu &= \frac{1}{2\pi} \int_0^{2\pi} \frac{F_r}{F_N} d\xi \quad \text{with } \xi = \omega t \\ &= \frac{\mu_0}{2\pi} \int_0^{2\pi} \cos\left(\arctan \frac{v}{v_0}\right) d\xi \\ &= \frac{\mu_0}{2\pi} \int_0^{2\pi} \frac{1}{1 + \left(\frac{v}{v_0}\right)^2} d\xi \\ &= \frac{\mu_0}{2\pi} \int_0^{2\pi} \frac{1}{1 + \left(\frac{\hat{v}}{v_0} \cos \xi\right)^2} d\xi\end{aligned}$$

Note: μ only depends on the ratio $\frac{v_0}{\hat{v}}$

Oscillations normal to the Sliding Direction

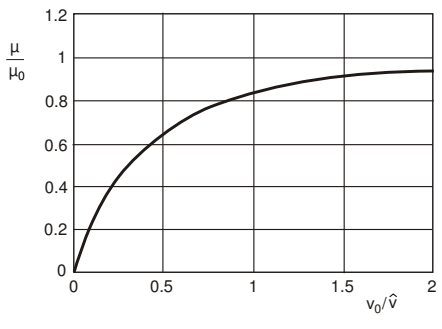


Fig.: Theoretical graph of the coefficient of friction dependent on the sliding velocity. This graph was first introduced in [1]

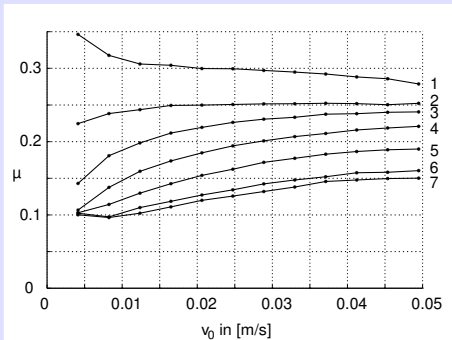


Fig.: Experimental data of the coefficient of friction of a steel-steel-couple, oscillation frequency of 45 kHz and the oscillation amplitudes: (1) 0.0, μm , (2) 0.026 μm , (3) 0.05 μm , (4) 0.076 μm , (5) 0.114 μm , (6) 0.182 μm , (7) 0.244 μm

[1] Littmann, Storck, Wallaschek, *Reibung bei Ultraschallschwingungen*, VDI-Berichte NR. 1736, 2002

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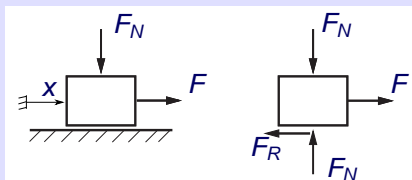
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Out-of-Plane Oscillations

Conclusions



Out-Of-Plane Oscillations



Oscillation due to normal force:

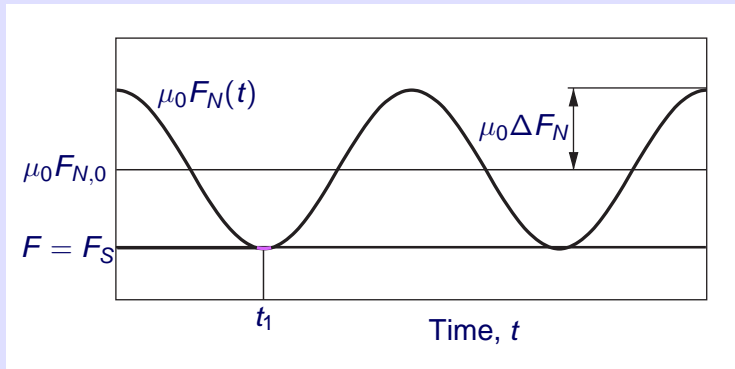
$$F_N = F_{N,0} + \Delta F_N \cos \omega t$$

Equation of motion:

$$m\ddot{x} = F - \mu_0(F_{N,0} + \Delta F_N \cos \omega t)$$

Out-of-Plane Oscillations

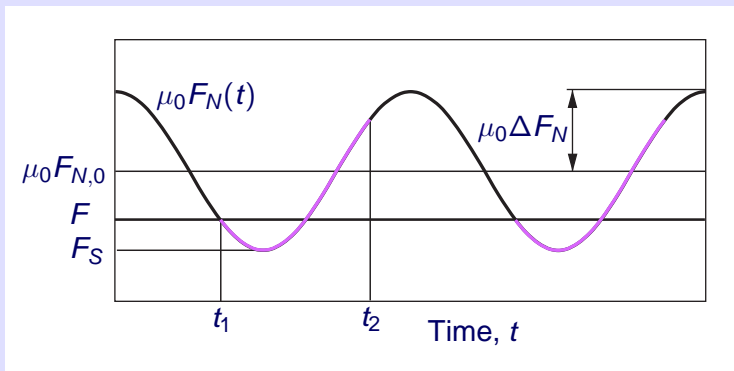
Stick Motion



$$F = F_S = \mu_0(F_{N,0} - \Delta F_N) \Leftrightarrow t_1 = t_2$$

Out-of-Plane Oscillations

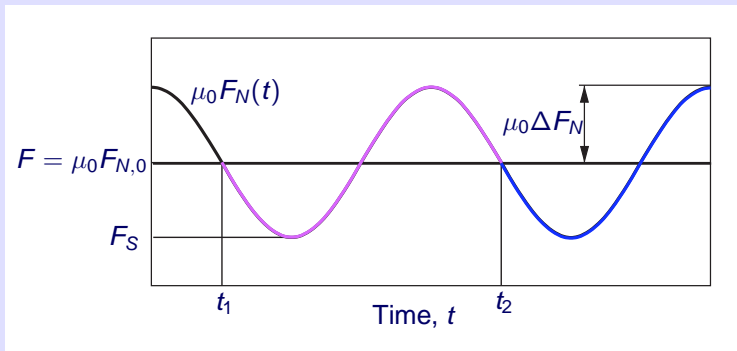
Stick-Slip Motion



$$F > \mu_0(F_{N,0} - \Delta F_N) \Leftrightarrow t_2 > t_1$$

Out-of-Plane Oscillations

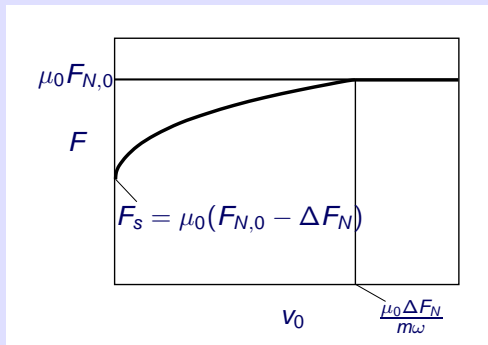
Slip Motion



$$F = \mu_0 F_{N,0} \Leftrightarrow t_2 = t_1 + T$$

Out-of-Plane Oscillations

Analytical/Numerical solution:



Approximative solution:

$$F = \mu_0 (F_{N,0} - \Delta F_N) + \mu_0 \Delta F_N \left[\sqrt{\frac{4\pi}{9} \frac{m\omega}{\mu_0 \Delta F_N} v_0} + \left(1 - \sqrt{\frac{4\pi}{9}}\right) \left(\frac{m\omega}{\mu_0 \Delta F_N} v_0\right)^{1.2} \right]$$

Out-of-Plane Oscillations

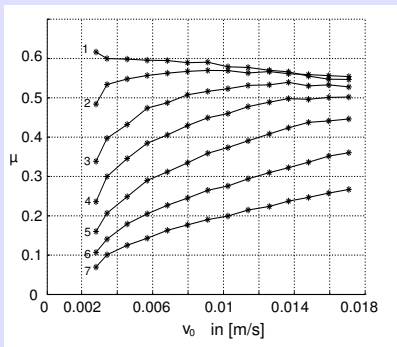
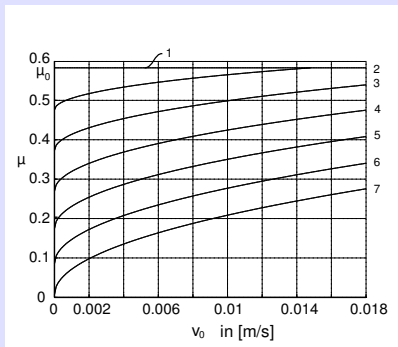


Fig.: Experimental dependence of the coefficient of friction $\mu = F/F_{N,0}$ on the average sliding velocity v_0 for the ratios of $\Delta F_N / F_{N,0}$: (1) 0, (2) 0.18, (3) 0.36, (4) 0.53, (5) 0.70, (6) 0.85, (7) 1.

Conclusions

For dry friction for all three oscillation directions the overall effects are the same!



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- ▶ Without oscillation the coefficient of friction is a monotonically **decreasing** function with respect to the velocity
- ▶ With oscillations the coefficient of friction is a monotonically **increasing** function with respect to the velocity

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 - ⇒ The effect known to cause friction induced instabilities (e.g. braking noise) is reversed!
- ▶ μ is highly reduced
- ▶ Largest effect for small velocities and large oscillation amplitudes
- ▶ We showed that even simple theoretical considerations successfully predict the main features

Thank you for your attention !

