Sliding Over a Phase Transition*









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A phase transition to control friction





Lubrication:

- ✓ Additives
- ✓ Organic molecule
- ✓ Bio molecules





Mechanical Vibrations

Surface modification:

- ✓ Texturing
- \checkmark Functionalization
- ✓ Coating (SEM,DLC,...)

A phase transition to control friction









• The sliding bodies always play a passive role: we never exploit the material physical properties

• Dynamical control of friction: changing friction coefficient during sliding



A phase transition to control friction



Can we exploit the substrate physical properties to dynamically control friction?

We need a substrate with some tunable material property

Such a flexibility cab be provided by the presence of a phase transition



Some experimental evidence

The effect of conductor/superconductor transition on dissipation and friction of...



... QCM adsorbates Highland & Krim PRL (2006)



FFM of TGS (Tc=49.9°C): the domain contrast disappears approaching Tc Bluhm, Schwarz & Wiesendanger (1998) Eng et al. (1999) ...pendulum type AFM Kisiel et al. Nature Mat. (2011)

Friction force microscopy to image ferroelectric domains...

The presence of domains allows us to control the local value of the friction coefficient using temperature, electric fields or stress fields.

Our model experiment

The simplest case of structural phase transition is the *ferrodistortive* one: even if a distortion of the lattice cell take place, no net dipole momet arise and we can neglect all the electrostatic interactions.

Despite its simplicity, a model with an inter-site potential + a multi well on-site potential catch all the qualitative features of a structural phase transition.

We studied a 2D solid with a triangular lattice and an on-site potential with 6 wells in the directions of the nearest neighbors:



Our model experiment

Close to the phase transition molecular dynamics simulations are strongly impaired by the critical slow-down: the fluctuations length-scale and time-scale diverge. However an estimation of the critical temperature can be given:



We have a (quasi) second order phase transition with a critical temperature KT_c = 0.075 (LJ units)

$$C_{V} = \frac{1}{N_{x}N_{z}} \frac{\langle E^{2} \rangle - \langle E \rangle^{2}}{K_{B}T^{2}}$$
$$\chi_{yy} = -\frac{\langle y^{2} \rangle - \langle y \rangle^{2}}{K_{B}T}$$
$$\chi_{xx} = -\frac{\langle x^{2} \rangle - \langle x \rangle^{2}}{K_{B}T}$$

The friction coefficient



• The friction force is non-monotonic, showing a maximum close to T_c .

• Below T_c different polarizations give rise to very different friction force.

• This difference decreases and disappear moving closer to T_c.

• Increasing the vertical load the friction force becomes more sensitive to the different substrate polarizations

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A peak at Tc



because of thermal activation friction is usually expected to decrease with temperature

temperature

but thermal activation works on the substrate atoms too...



Increasing the temperature we open new dissipation channels helping the tip in kicking out the atoms from the well, and thus increasing the friction force.

A peak at Tc



Within the *linear response theory* (Ying et al. 1990-92), the damping coefficient relates to the microscopic properties of

























A model nano-brake





Acting with an external field we can exploit the friction coefficient difference below Tc to increase and decrease sliding friction

Conclusion

The presence of a phase transition provides new degrees of freedom for the substrate physical properties

This degrees of freedom open up new dissipation channels for the slider/tip energy

Below Tc dissipation and friction can be controlled acting on this degrees of freedom with some external field

Model Improvements:

- Include dipole-dipole interaction (ferrodistortive to ferroelectric)
- Include electrostatic tip-substrate interaction and piezoelectric response
- Better tip description

Looking for different kinds of phase transition (ferromagnetic?)

Thanks for your attention!